

12.12 (a) From the identity $\frac{d}{dt}(\hat{\beta} \cdot \vec{S}) = \hat{\beta} \cdot \frac{d\vec{S}}{dt} + \frac{1}{\beta} [\vec{S} - \hat{\beta}(\hat{\beta} \cdot \vec{S})] \cdot \frac{d\hat{\beta}}{dt}$, we can calculate each term separately,

$$\begin{aligned} \hat{\beta} \cdot \frac{d\vec{S}}{dt} &= \frac{e}{mc} \hat{\beta} \cdot \left\{ \vec{S} \times \left[\left(\frac{q}{2} - 1 + \frac{1}{\gamma} \right) \vec{B} - \left(\frac{q}{2} - 1 \right) \frac{\gamma}{\gamma+1} (\vec{\beta} \cdot \vec{B}) \vec{\beta} - \left(\frac{q}{2} - \frac{\gamma}{\gamma+1} \right) \vec{\beta} \times \vec{E} \right] \right\} \\ &= \frac{e}{mc} \left(\frac{q}{2} - 1 + \frac{1}{\gamma} \right) (\hat{\beta} \times \vec{S}) \cdot \vec{B} - \frac{e}{mc} \left(\frac{q}{2} - 1 \right) \frac{\gamma}{\gamma+1} (\vec{\beta} \cdot \vec{B}) \hat{\beta} \cdot (\vec{S} \times \vec{\beta}) \\ &\quad - \frac{e}{mc} \left(\frac{q}{2} - \frac{\gamma}{\gamma+1} \right) (\hat{\beta} \times \vec{S}) \cdot (\vec{\beta} \times \vec{E}) \\ &= \frac{e}{mc} \left(\frac{q}{2} - 1 \right) (\hat{\beta} \times \vec{S}) \cdot \vec{B} + \frac{e}{\gamma mc} (\hat{\beta} \times \vec{S}) \cdot \vec{B} - \frac{e}{mc} \left(\frac{q}{2} - \frac{\gamma}{\gamma+1} \right) (\hat{\beta} \times \vec{S}) \cdot (\vec{\beta} \times \vec{E}) \end{aligned}$$

$$\begin{aligned} \text{and } \frac{1}{\beta} [\vec{S} - \hat{\beta}(\hat{\beta} \cdot \vec{S})] \cdot \frac{d\hat{\beta}}{dt} &= \frac{1}{\beta} [\hat{\beta} \times (\vec{S} \times \hat{\beta})] \cdot \frac{e}{\gamma mc} [\vec{E} + \vec{\beta} \times \vec{B} - \hat{\beta}(\hat{\beta} \cdot \vec{E})] \\ &= \frac{e}{\beta \gamma mc} [\hat{\beta} \times (\vec{S} \times \hat{\beta})] \cdot \vec{E} + \frac{e}{\beta \gamma mc} [\hat{\beta} \times (\vec{S} \times \hat{\beta})] \cdot (\vec{\beta} \times \vec{B}) - \frac{e}{\beta \gamma mc} [\hat{\beta} \times (\vec{S} \times \hat{\beta})] \cdot \hat{\beta}(\hat{\beta} \cdot \vec{E}) \\ &= \frac{e}{\beta \gamma mc} (\vec{S} \times \hat{\beta}) \cdot (\vec{E} \times \hat{\beta}) + \frac{e}{\beta \gamma mc} [(\vec{S} \times \hat{\beta}) \cdot \vec{B} - (\hat{\beta} \cdot \vec{B}) (\vec{S} \times \hat{\beta}) \cdot \hat{\beta}] \\ &= \frac{e}{\beta \gamma mc} (\vec{S} \times \hat{\beta}) \cdot (\vec{E} \times \hat{\beta}) + \frac{e}{\beta \gamma mc} (\vec{S} \times \hat{\beta}) \cdot \vec{B} \end{aligned}$$

Taking the sum, we now have

$$\begin{aligned} \frac{d}{dt}(\hat{\beta} \cdot \vec{S}) &= \frac{e}{mc} \left(\frac{q}{2} - 1 \right) (\hat{\beta} \times \vec{S}) \cdot \vec{B} - \frac{e}{mc} \left(\frac{q}{2} - \frac{\gamma}{\gamma+1} \right) (\hat{\beta} \times \vec{S}) \cdot (\vec{\beta} \times \vec{E}) + \frac{e}{\beta \gamma mc} (\vec{S} \times \hat{\beta}) \cdot (\vec{E} \times \hat{\beta}) \\ &= \frac{e}{mc} \left(\frac{q}{2} - 1 \right) \vec{S} \cdot (\vec{B} \times \hat{\beta}) + \frac{e}{mc} \left[\frac{1}{\beta \gamma} - \frac{q\beta}{2} + \frac{\beta \gamma}{\gamma+1} \right] (\hat{\beta} \times \vec{S}) \cdot (\vec{\beta} \times \vec{E}) \\ &= - \frac{e}{mc} \left(\frac{q}{2} - 1 \right) \vec{S} \cdot (\hat{\beta} \times \vec{B}) - \frac{e}{mc} \left(\frac{q\beta}{2} - \frac{1}{\beta} \right) [(\hat{\beta} \times \vec{S}) \times \hat{\beta}] \cdot \vec{E}, \end{aligned}$$

where we have used the fact that

$$\frac{1}{\beta \gamma} + \frac{\beta \gamma}{\gamma+1} = \frac{\gamma+1 + \gamma^2 \beta^2}{\beta \gamma (\gamma+1)} = \frac{\gamma+1 + \frac{\beta^2}{1-\beta^2}}{\beta \gamma (\gamma+1)} = \frac{\gamma + \frac{1}{1-\beta^2}}{\beta \gamma (\gamma+1)} = \frac{\gamma + \gamma^2}{\beta \gamma (\gamma+1)} = \frac{1}{\beta}$$

Finally, notice that $(\hat{\beta} \times \vec{S}) \times \hat{\beta} = \vec{S} - \hat{\beta}(\hat{\beta} \cdot \vec{S}) = \vec{S} - \vec{S}_{\parallel} = \vec{S}_{\perp}$, where \vec{S}_{\parallel} and \vec{S}_{\perp} are the components of \vec{S} parallel and perpendicular to $\hat{\beta}$, and also that only \vec{S}_{\perp} contribute to $\vec{S} \cdot (\hat{\beta} \times \vec{B})$, we can write

$$\text{the result as: } \frac{d}{dt}(\hat{\beta} \cdot \vec{S}) = - \frac{e}{mc} \vec{S}_{\perp} \cdot \left[\left(\frac{q}{2} - 1 \right) \hat{\beta} \times \vec{B} + \left(\frac{q\beta}{2} - \frac{1}{\beta} \right) \vec{E} \right].$$

(b) In the configuration, $\hat{\beta} \cdot \vec{S} = S \cos \theta$ and $\vec{S}_\perp = S \sin \theta \hat{n}$. Then,

$$\frac{d}{dt}(\vec{\beta} \cdot \vec{S}) = -S \sin \theta \frac{d\theta}{dt} = -\frac{e}{mc} S \sin \theta \hat{n} \cdot \left[\left(\frac{g}{2} - 1 \right) \hat{\beta} \times \vec{B} + \left(\frac{g\beta}{2} - \frac{1}{\beta} \right) \vec{E} \right],$$

or
$$\frac{d\theta}{dt} = \frac{e}{mc} \left[\left(\frac{g}{2} - 1 \right) \hat{n} \cdot (\hat{\beta} \times \vec{B}) + \left(\frac{g\beta}{2} - \frac{1}{\beta} \right) \hat{n} \cdot \vec{E} \right]$$

(c) For this configuration, $\vec{E} = -\beta B \hat{n}$, which can be easily verified. Therefore,

$$\begin{aligned} \frac{d\theta}{dt} &= \frac{e}{mc} \left[\left(\frac{g}{2} - 1 \right) (\hat{n} \times \hat{\beta}) \cdot \vec{B} - \left(\frac{g\beta}{2} - \frac{1}{\beta} \right) \beta B \right] = \frac{eB}{mc} \left[\frac{g}{2} - 1 - \frac{g\beta^2}{2} + 1 \right] = \frac{geB}{2mc} (1 - \beta^2) \\ &= \frac{geB}{2\gamma mc} = \frac{g}{2\gamma} \omega_B. \end{aligned}$$

(d) The equation can be verified by matrix multiplication. Notice that

$$F^{\mu\nu} = \begin{pmatrix} 0 & -\vec{E} \\ \vec{E} & -\epsilon_{ijk} B_k \end{pmatrix}, \quad \text{we can write } L_\alpha F^{\mu\nu} N_\beta \text{ as}$$

$$L_\alpha F^{\mu\nu} N_\beta = (\gamma\beta, -\gamma\vec{\beta}) \begin{pmatrix} 0 & -\vec{E} \\ \vec{E} & -\epsilon_{ijk} B_k \end{pmatrix} \begin{pmatrix} 0 \\ -\hat{n} \end{pmatrix} = \gamma\beta \hat{n} \cdot \vec{E} - \gamma\vec{\beta} \cdot (\hat{n} \times \vec{B}) = \gamma\beta \hat{n} \cdot \vec{E} + \gamma\hat{n} \cdot (\vec{\beta} \times \vec{B}).$$

$$\text{Similarly, } U_\alpha F^{\mu\nu} N_\beta = (\gamma c, -\gamma c \vec{\beta}) \begin{pmatrix} 0 & -\vec{E} \\ \vec{E} & -\epsilon_{ijk} B_k \end{pmatrix} \begin{pmatrix} 0 \\ -\hat{n} \end{pmatrix} = \gamma c (\hat{n} \cdot \vec{E}) + \gamma c \hat{n} \cdot (\vec{\beta} \times \vec{B}).$$

$$\text{Then, } \left(\frac{g}{2} L_\alpha - \frac{1}{v} U_\alpha \right) F^{\mu\nu} N_\beta = \frac{g}{2} (\gamma\beta \hat{n} \cdot \vec{E} + \gamma\hat{n} \cdot (\vec{\beta} \times \vec{B})) - \frac{\gamma c}{v} (\hat{n} \cdot \vec{E} + \hat{n} \cdot (\vec{\beta} \times \vec{B}))$$

$$= \gamma \left[\left(\frac{g}{2} - \frac{c\beta}{v} \right) \hat{n} \cdot (\vec{\beta} \times \vec{B}) + \left(\frac{g\beta}{2} - \frac{1}{\beta} \right) \hat{n} \cdot \vec{E} \right]$$

$$= \gamma \left[\left(\frac{g}{2} - 1 \right) \hat{n} \cdot (\hat{\beta} \times \vec{B}) + \left(\frac{g\beta}{2} - \frac{1}{\beta} \right) \hat{n} \cdot \vec{E} \right]$$

Notice that $dt/d\tau = \gamma$, we have

$$\frac{d\theta}{d\tau} = \frac{d\theta}{dt} \frac{dt}{d\tau} = \gamma \cdot \frac{e}{mc} \left[\left(\frac{g}{2} - 1 \right) \hat{n} \cdot (\hat{\beta} \times \vec{B}) + \left(\frac{g\beta}{2} - \frac{1}{\beta} \right) \hat{n} \cdot \vec{E} \right]$$

$$= \frac{e}{mc} \left[\frac{g}{2} L_\alpha - \frac{1}{v} U_\alpha \right] F^{\mu\nu} N_\beta.$$