

Precision cosmology with time delay lenses: high resolution imaging requirements

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Abstract. Gravitational time delays are a powerful probe of cosmology, provided that the gravitational potential of the main deflector can be modeled with sufficient precision. Recent work has shown that this can be achieved by detailed modeling of the host galaxies of lensed quasars. The distortion of the images as measured over large number of pixels provides tight constraints on the difference between the gravitational potential between the two quasars, and thus on cosmology in combination with the measured time delay. We carry out a systematic exploration of the high resolution imaging required to exploit the thousands of lensed quasars that will be discovered by current and upcoming surveys with the next decade. Specifically we simulate realistic lens systems as imaged by the Hubble Space Telescope (HST), James Webb Space Telescope (JWST), ground based adaptive optics images taken with Keck or the Thirty Meter Telescope (TMT). We compare the performance of these pointed observations with that of images taken by the Euclid-VIS, Wide-Field Infrared Survey Telescope (WFIRST) and Large Synoptic Survey Telescope (LSST) surveys. Using as our metric the precision with which the slope of the mass density profile for the main deflector can be measured **we find that...**

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1 Introduction

[TT to put introfirst here; introduce ‘informative pixels’ that will be referred to in Sect.s 2 and 3; mention that we’re basically observing how radial magnification changes across the lens, so that we need to understand how that is affected by PSF, pixel-size, and S/N ratio.]

In the past few years, gravitational time delays have emerged as a...

This paper is organized as follows. We first introduce our lens sample in Section 2. Next, we briefly summarize a variety of telescopes properties used in this work and show simulated realistic lens systems as imaged by these telescopes in Section 3. The results from simulation in Section 4. Finally, we discuss and summarize our work in Section 5. Throughout this paper, all magnitudes are given in the AB system. Even though it is not crucial to our findings, we adopt a spatially flat Λ CDM cosmology with $\Omega_m = 0.3$, $\Omega_\Lambda = 0.7$, and the Hubble constant $H_0 = 70 \text{ km s}^{-1} \text{ Mpc}^{-1}$ when calculating distances.

2 Instrument Simulations

The way a lens is observed and modelled, whence the parameter uncertainties, are influenced fundamentally by the instrumental setup itself. First, the signal-to-noise depends on the exposure-time adopted, sky or background noise in a chosen band, and the instrumental readout noise. Second, the pixel-size and PSF properties determine how finely one can map the system being observed, hence how robustly the deflections on either side of the lens can be quantified.

Here we illustrate the main properties of instruments that will be considered in the simulations. For the sake of completeness, they can either be ground-based or space-based telescopes, or even cadenced surveys where the total exposure cannot set arbitrarily. Table 1 and figure 1 display the main properties of the telescopes that are needed when generating images of mock gravitational lenses. Figure [XLM, can you do it?] shows the typical PSF of each instrument.

For TT: A sentence or two on HST and ACS; similarly for JWST (what it’s planned to do and when it’s expected to start); similarly for TMT and IRIS; Keck, both with LGS and NGS and why we must consider both; then Euclid, WFIRST, LSST.

3 The Lens Sample

We have chosen four prototypical systems for this exploration, characterized as *faint* or **bright** and **double** or **quad** depending on the photometry and image configuration. Their structural parameters are listed in Table 2. This set of four main choices covers regimes with different numbers of informative pixels, which depend on the S/N ratio and on the number of images produced by the lens.

To remain as realistic as possible, the mocks are based upon lenses in the SLACS (...) and SL2S (...) samples. When not explicitly known from existing data, mock model parameters are assigned via plausibility arguments as specified below. The source and deflector of the *bright* configurations are built along SLACS J0330-0020 as modelled by Auger et al.(SLACS11). For the *faint* configuration, the deflector has parameters from the Sonnenfeld et al. (????) model of SL2S J135949+553550. Source magnitudes in the *faint* case are arbitrarily set to 25.0 in all bands, whence the source effective radius R_{eff} is assigned along the size-magnitude relation given by Newton et al. (2011?). In all cases, the source positions are assigned so as to map the source in either two or four images. Unknown magnitudes in K band are assigned from H -band ones via $K_{AB} = H_{AB}$.

Question: What are the point-source magnitudes, even if they're not specifically modelled? How were they assigned? (They are in the Table 4. For the fainter systems, they are all 24.0 for all the filters except for TMT. The magnitude of point source is 26.0 for TMT, that's because TMT has an amazing detecting ability. For the brighter systems, they are assigned with magnitude of source galaxy - 0.5 for filter K, VIS, and H; - 1.0 for filter I.) Based on the recipe that Kai and I assembled? Also, magnitudes in the tables are not necessarily the instrument ones, how are they converted? With the XLM's template-based table from AA or something different? (For fainter systems, lens magnitude for I filter is from Ale's paper III, mag for K filter is estimated by TT based on the other colors, mag for VIS filter is evaluated by $mag(r, i, z) = -2.5 * log((10^{-0.4r} + 10^{-0.4i} + 10^{-0.4z})/2)$ (there are r, i, z filters informations in Ale's paper III), $H_{AB} = K_{AB}$. For brighter systems, lens mag for I filter and V filter are from Auger's paper; mag for K band is determined by TT; $H_{AB} = K_{AB}$) (For fainter systems, the source galaxy magnitude for filters are all 25.0 which is determined by TT. For brighter systems, the source galaxy magnitude for I and V filters are from Newton's paper, the source galaxy magnitude for K filter is 22.0 which is determined by TT)

Then: say that source is mapped onto lens plane with formalism illustrated later on, lens light is summed to it, noise added. Refer to one example of puppies, **including TMT with kernel smoothing**.

4 Lens Reconstruction

Here we describe how the mock lens models are generated, using power-law lenses. The reader familiar with this topic can easily skip to the next Section.

The deflector's mass profile is assigned within a class of power-law models,

$$\Sigma(x, y) = \Sigma_0(qX^2 + q^{-1}Y^2)^{-\gamma'}, \quad (4.1)$$

where the $\{X, Y\}$ axes are rotated by some position angle w.r.to the canonical x (increasing to the West) and y (increasing to the North). This means that the $\{X, Y\}$ deflections scale as ..., where $g(\theta)$ a just function of the relative angle west-of-north. Fast methods to compute deflections from power-law profiles have been given by Barkana (????). Power-law models of elliptical galaxies Evans (1994?) have often been used with success over the years to model gravitational lenses [references!]. In utter generality, the lensing deflections are given by

$$\dots \quad (4.2)$$

where

$$\Sigma_{cr} = \dots \quad (4.3)$$

encompasses the relative positions of source, deflector and observer. Then, in our power-law case the deflections can be rewritten conveniently as

$$\dots \quad (4.4)$$

This introduces the Einstein radius R_E , which is such that in the spherical case ($q = 1$) the mean dimensionless density $\langle \Sigma \rangle / \Sigma_{cr}$ within a circle of radius R_E is exactly 1. This is also the radius of a ring traced by the host of the quasar when this is exactly aligned with the lens galaxy.

Lensed image profiles are obtained by Inverse Ray Shooting: First, each pixel position in the image plane is mapped back to the source plane via the deflections in eq ... Then, we exploit the fact that surface-brightness is preserved by lensing, i.e.

$$\dots \quad (4.5)$$

In general, when dealing with more complex caustics from substructure **Vegetti** (????) or microlensing **Mediavilla** (????), rays are shot through an adaptive, triangular tessellation in the image place. Here, we can simply use a rectangular grid in the image-plane to obtain sufficiently accurate results.

The same code is used to generate the mock models and to fit them. The model fits the following parameters: **which ones?** Goodness of fit is assessed through the image-plane χ^2 , comparing the model and mock data surface brightness profiles. The quasar images are not used in the fit, which is performed just on the lensed host. This is because in reality, even in the absence of substructure lensing, the relative fluxes of the point-like images of the quasar can be appreciably affected by microlensing or dust lanes in the foreground. Uncertainties are obtained via MCMC exploration of the likelihood, which in this case is simply given by $\mathcal{L} \propto \exp[-\chi^2/2]$.

5 Results

6 Summary

Acknowledgments

References

- [1] A. S. Bolton, S. Burles, L. V. E. Koopmans, T. Treu, R. Gavazzi, L. A. Moustakas, R. Wayth, and D. J. Schlegel, *The Sloan Lens ACS Survey. V. The Full ACS Strong-Lens Sample*, *Astrophys. J.* **682** (Aug., 2008) 964–984, [[arXiv:0805.1931](#)].
- [2] M. W. Auger, T. Treu, A. S. Bolton, R. Gavazzi, L. V. E. Koopmans, P. J. Marshall, K. Bundy, and L. A. Moustakas, *The Sloan Lens ACS Survey. IX. Colors, Lensing, and Stellar Masses of Early-Type Galaxies*, *Astrophys. J.* **705** (Nov., 2009) 1099–1115, [[arXiv:0911.2471](#)].

Table 1. Telescope Properties

Telescope	Instrument	Filter	Zero Point	Readout Noise (e ⁻ /pixel)	Background Noise (e ⁻ /pixel/s)	Pixel Size (arcsec)
HST	WFC3	F814W	25.94	4.20	0.11	0.050
JWST	NIRCAM	F200W	27.85	9.00	0.20	0.032
Keck	NIRC2	<i>K'</i>	28.04	5.75	25.94	0.010
NGAO	NGSAO	<i>K'</i>	28.04	5.75	25.94	0.010
TMT	IRIS	<i>K'</i>	31.10	2.00	21.20	0.004
Euclid	VIS	<i>r + i + z</i>	25.58	4.50	0.43	0.100
WFIRST	...	F184	26.18	5.00	0.11	0.110
LSST	—	<i>I</i>	28.35	5.00	68.00	0.200

Observational facilities (telescopes or cadenced surveys) considered in this work. Zero points are given in the ABmag system. The near-IR wavelength coverage of IRIS is $0.85 - 2.5 \mu\text{m}$, the VIS imager of Euclid spans the whole $r + i + z$ wavelength range. Keck 10-m telescope is considered both with current (NIRC2) and next-generation (NGAO) adaptive-optics capabilities.

Table 2. Surface Brightness Profile Models

Lens Name	R_{eff} (arcsec)	q	P.A. (deg)	n	Δx (arcsec)	Δy (arcsec)	m_I	m_K	m_{VIS}	m_H
Parameters for the Source										
fainter system ^a	0.23	0.92	54.0	4.0	0.0662	-0.167	25.0	25.0	25.0	25.0
fainter system ^b	0.23	0.92	54.0	4.0	0.008	0.298	25.0	25.0	25.0	25.0
brighter system ^b	0.12	0.77	120.0	1.33	-0.195	0.34	22.73	22.0	23.46	22.0
brighter system ^a	0.12	0.77	120.0	1.33	0.01	-0.005	22.73	22.0	23.46	22.0
Parameters for the lens										
fainter system	1.76	0.61	-9.6	4.0	—	—	20.69	19.7	21.13	19.7
brighter system	0.91	0.81	113.2	4.0	—	—	17.99	16.5	18.84	16.5

The effective radius R_{eff} is the radius at which the major axis contains half of the total flux. q denotes the axis ratio. P.A. is with respect to the x-axis. The Sérsic index n controls the degree of curvature of the galaxy light profile. Magnitudes m are given in the ABmag system. The only difference among sources of different brightness is in the source-position, which is set to produce either two or four images.

^a 4 QSO images exist in the lens plane.

^b 2 QSO images exist in the lens plane.

Table 3. Lens Model Parameters

Lens Name	z	R_{Ein} (arcsec)	q	P.A. (deg)	γ'
fainter system	0.783	1.14	0.6	14.7	2.0
brighter system	0.351	1.1	0.81	113.2	2.0

Rephrase[R_{Ein} is the radius of a ring which is taken from a lensing phenomenon if a point source is located on the viewing direction extending from the observer]. q denotes the axis ratio. P.A. is anti-clockwise from the x-axis. The underlying deflector is a Singular Isothermal Ellipsoid ($\gamma' = 2$), which will be fit using power-law models.

^a 4 QSO images exist in the lens plane.

^b 2 QSO images exist in the lens plane.

Table 4. Point Source Parameters

Lens Name	magnitude (I)	magnitude (K)	magnitude (VIS)	magnitude (H)	magnification (I)	magnification (II)	magnification (III)	magnification (IV)
fainter system ^a	24.0	24.0	24.0	24.0	2.84	3.75	6.59	2.78
fainter system ^b	24.0	24.0	24.0	24.0	2.78	2.48	—	—
brighter system ^b	21.7	21.5	22.9	21.5	1.22	6.10	—	—
brighter system ^a	21.7	21.5	22.9	21.5	6.09	8.22	6.86	7.53

Magnitude m is given in the ABmag system.

^a 4 QSO images exist in the lens plane.

^b 2 QSO images exist in the lens plane.

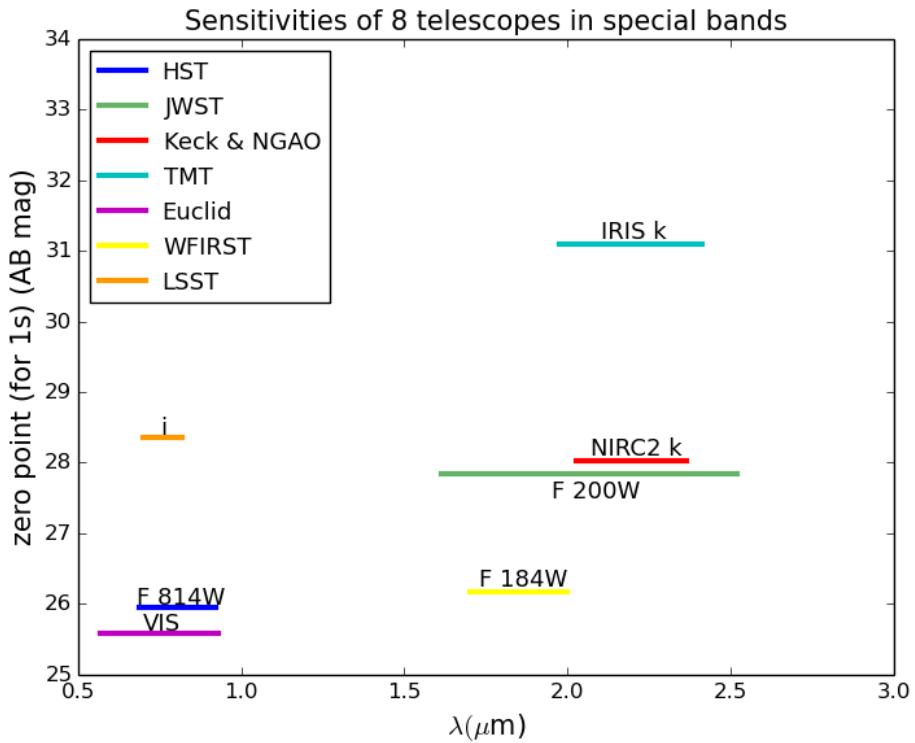


Figure 1. Zero Points in AB magnitudes of HST (blue), JWST (green), Keck & NGAO (red), TMT (cyan), Euclid (magenta), WFIRST (yellow) and LSST (orange) in units of per second. Different color bars indicate the wavelength range of each telescope used in this work.

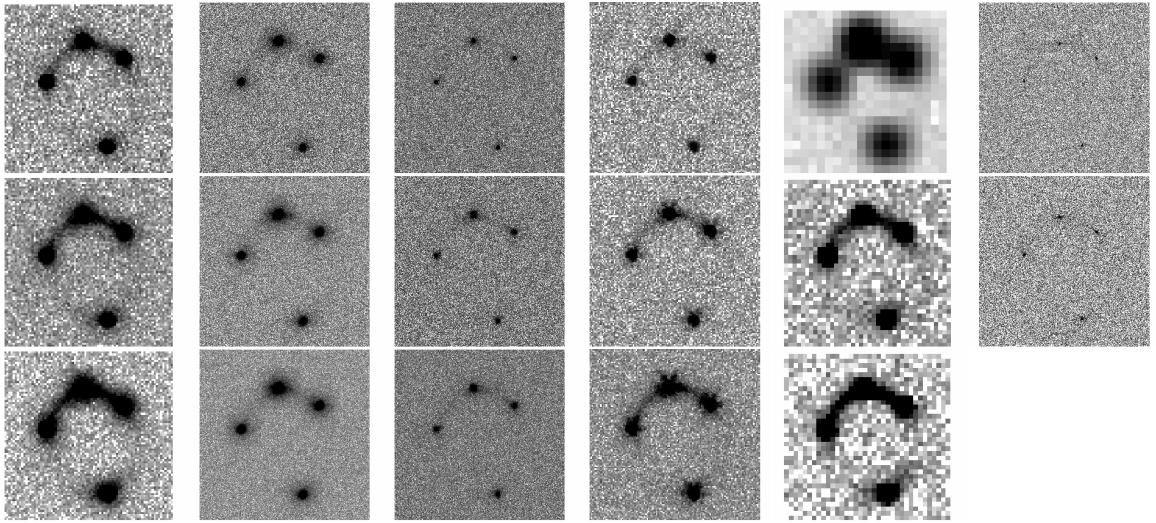


Figure 2. Simulated lens system results showing the fainter lens system (4 QSO images in the lens plane). The simulated image pixel scales are all $4'' \times 4''$. The first 4 columns, from left to right, represent HST, Keck, NGAO, and JWST; from top to bottom, correspond to $1/3 \times$ good exposure time, good exposure time, and $3 \times$ good exposure time (See the definition of “good exposure time” in Section *.*). The fifth column include 3 survey detections by 3 different telescopes, from top to bottom, for LSST, Euclid, and WFIRST respectively. The last column is for TMT with 2 fixed exposure time: 360 seconds and 1080 seconds.

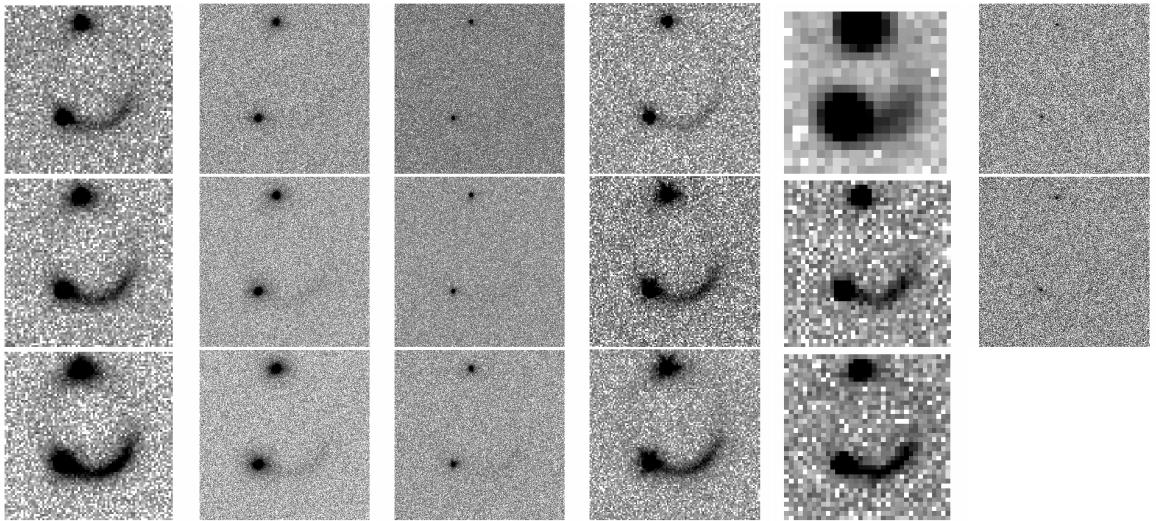


Figure 3. Same as Fig. 2, except that the simulated lens system results showing the fainter lens system (2 QSO images in the lens plane).

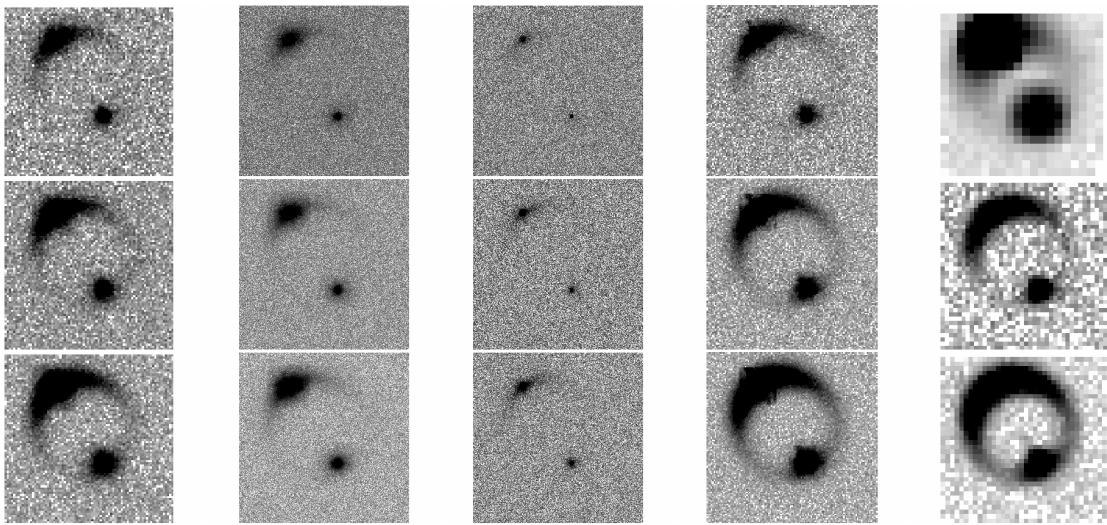


Figure 4. Simulated lens system results showing the brighter lens system (2 QSO images in the lens plane). The simulated image pixel scales are all $4'' \times 4''$. The first 3 columns, from left to right, present HST, Keck, and NGAO; from top to bottom, correspond to $1/3 \times$ good exposure time, good exposure time, and $3 \times$ good exposure time. The fourth column shows JWST with 3 fixed exposure time: 60 seconds, 180 seconds, and 540 seconds. The last column include 3 survey detections by 3 different telescopes, from top to bottom, for LSST, Euclid, and WFIRST respectively.

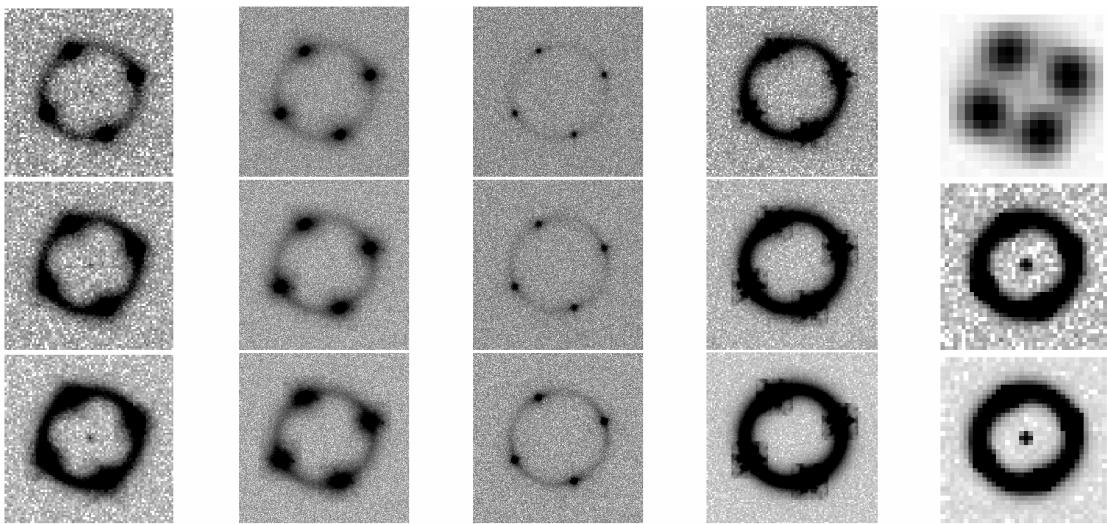


Figure 5. Same as Fig. 4, except that the simulated lens system results showing the brighter lens system (4 QSO images in the lens plane). The black spots in the center of the simulated images using HST, Euclid and WFIRST are from the efforts of strong signal pixels, so it's a “ghost” image which can be ignored.

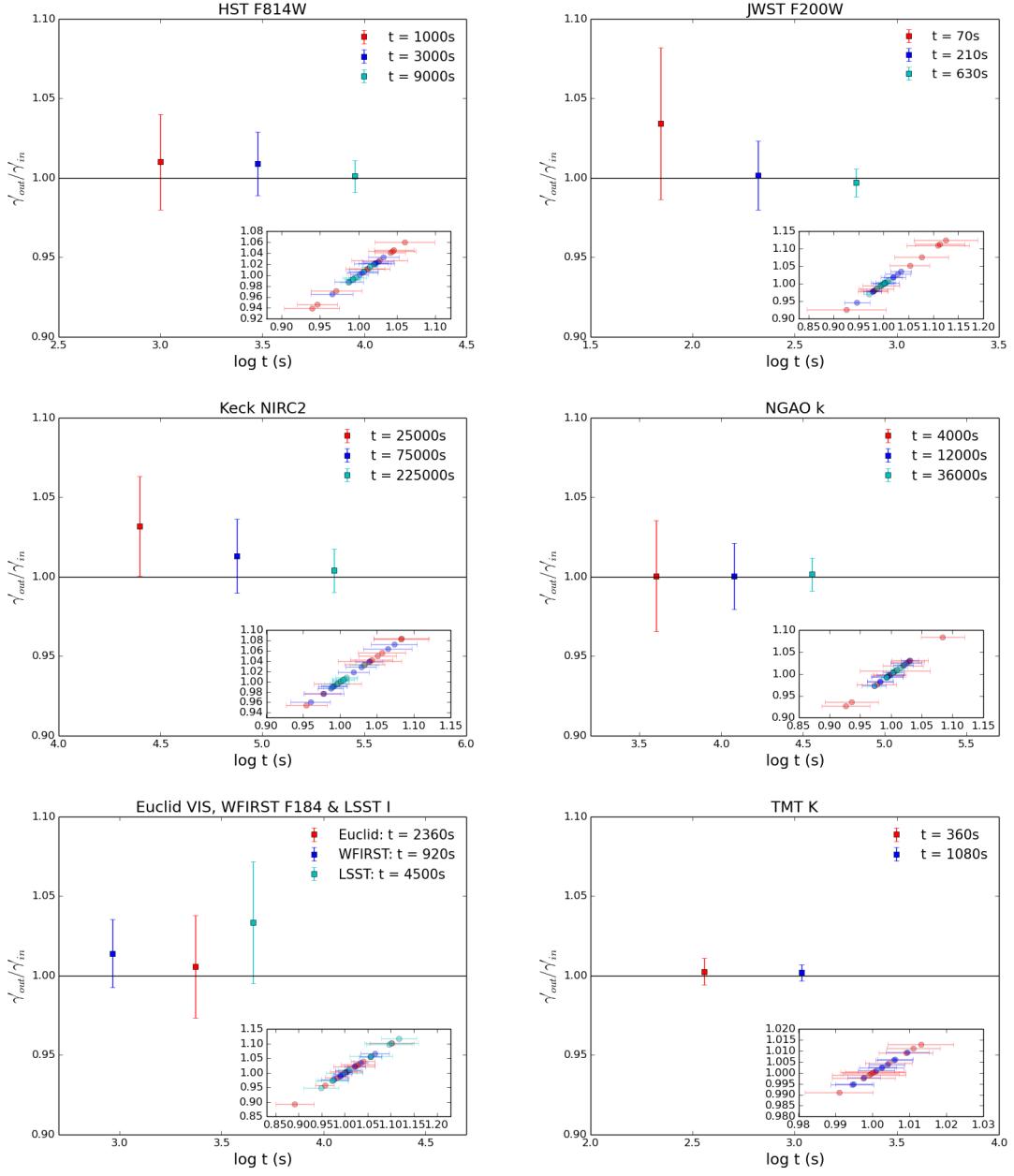


Figure 6. The ability of recovering mass slope with respect to different exposure time for a variety of telescopes. This figure shows the fainter lens system with 4 QSO images in the lens plane. γ'_{in} is the input SIE mass slope. γ'_{out} is drawn from MCMC sampling based on the simulated images given γ'_{in} . The error bar represents 1σ confidence range. The insert in each panel shows all 10 simulation results for each exposure time with the same color coding. Note that both axes represent $\gamma'_{out}/\gamma'_{in}$ whereas error bars are only shown on the x-axis for clarity.

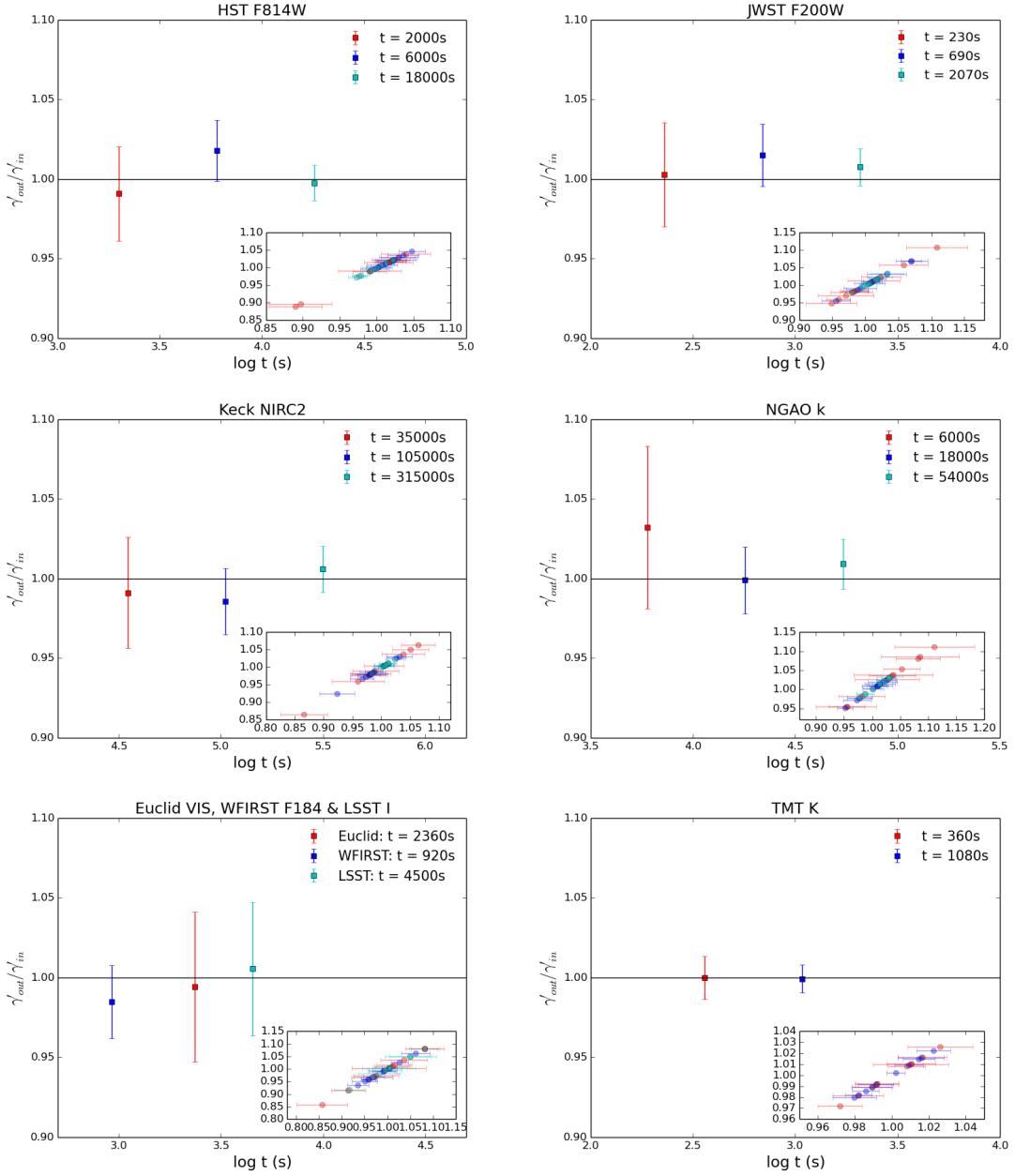


Figure 7. Same as Fig. 6, except that this figure is shown for the fainter lens system with 2 QSO images in the lens plane.

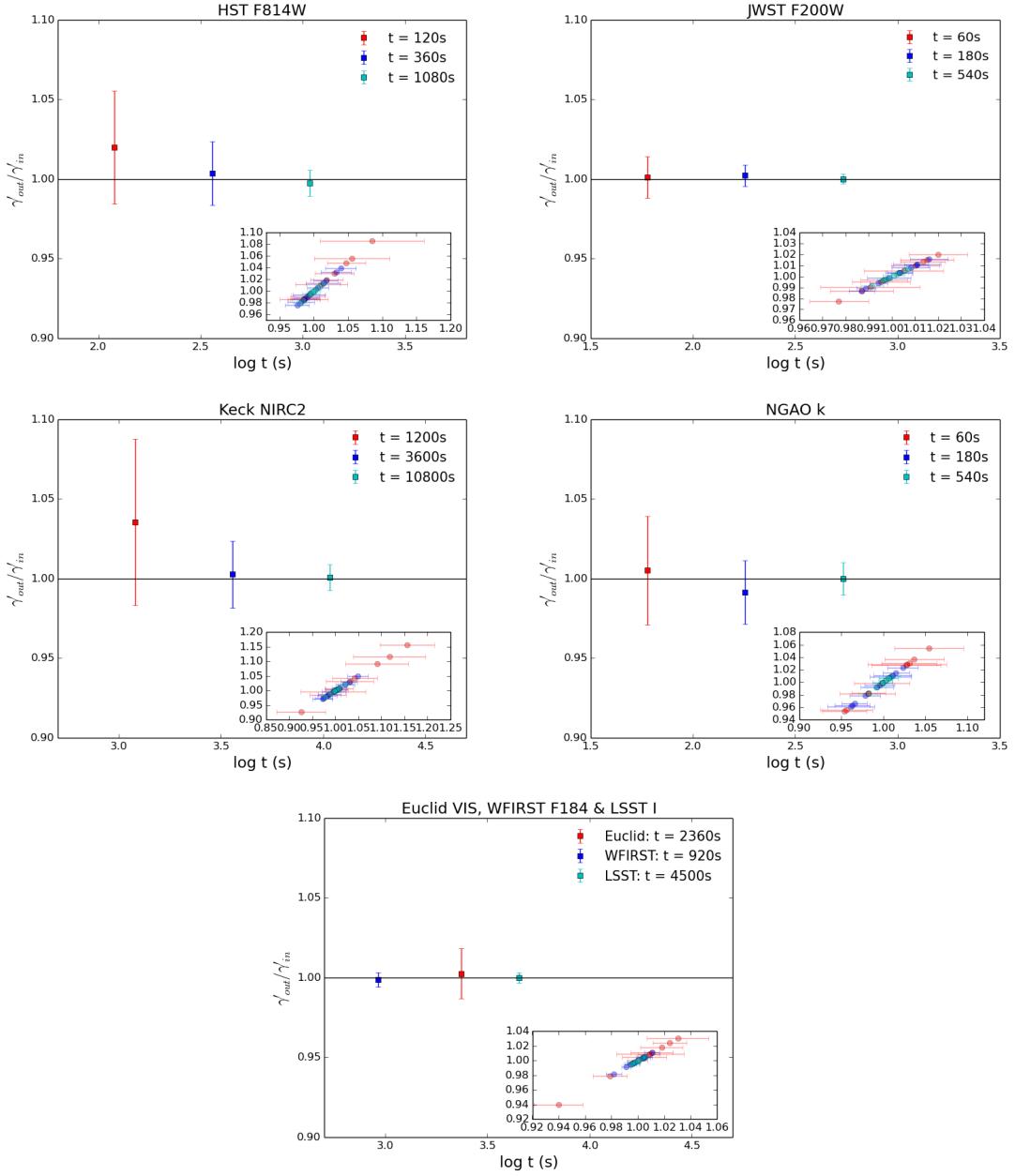


Figure 8. Same as Fig. 6, except that this figure is shown for the brighter lens system with 2 QSO images in the lens plane.

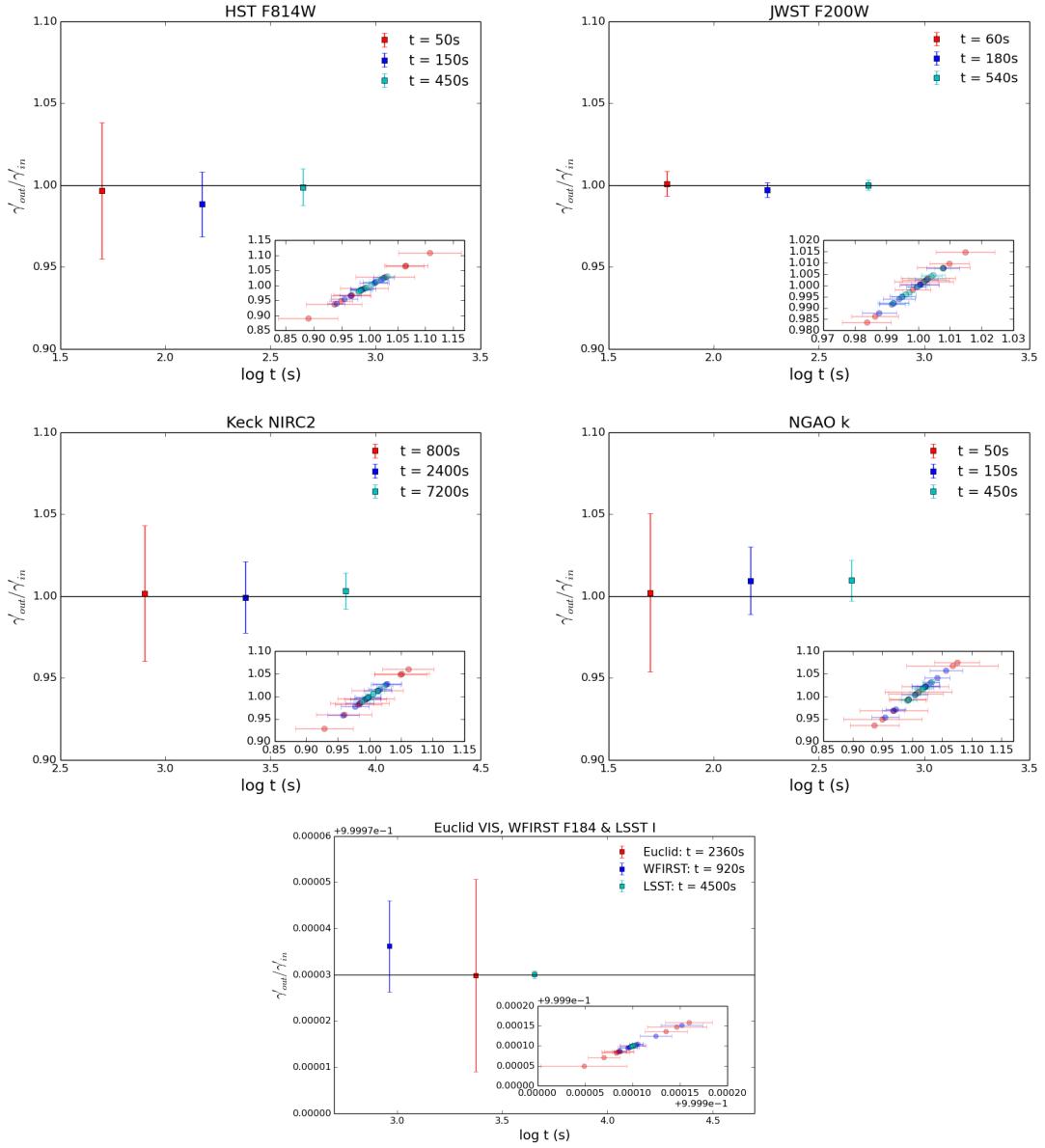


Figure 9. Same as Fig. 6, except that this figure is shown for the brighter lens system with 4 QSO images in the lens plane.