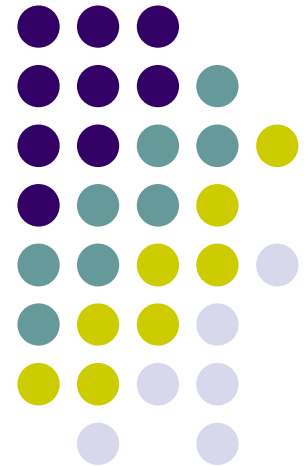


Practical Parallel Computing (実践的並列コンピューティング)

2025 Class No.13
[MPI Part] (2)
Distributed Algorithms with MPI

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Overview of This Course

- Introduction Part
 - 2 classes
 - OpenMP (OMP) Part
 - 4 classes
 - Report (required)
 - OpenACC (ACC) Part
 - 2 classes
 - Report (required)
 - CUDA Part
 - 3 classes
 - Report (elective)
 - MPI Part
 - 3 classes
 - Report (elective)
- ← We are here (2/3)



Today's Contents

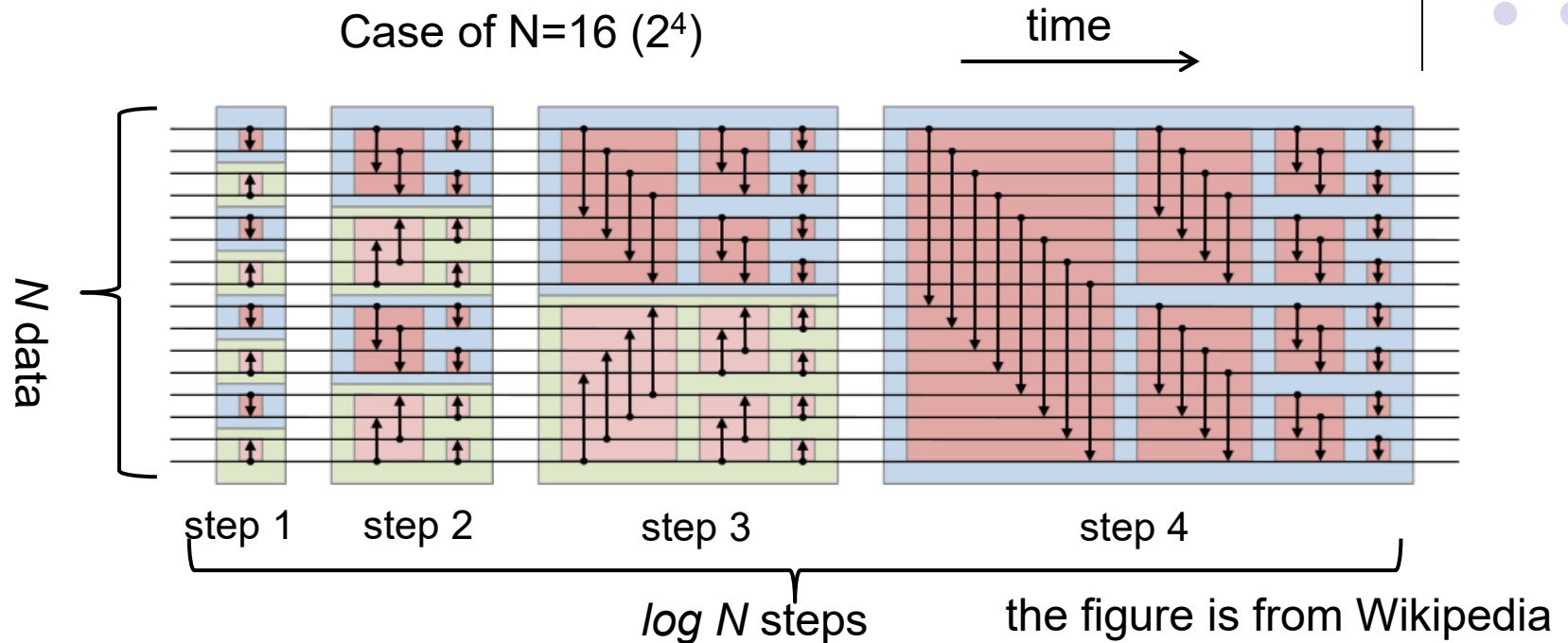
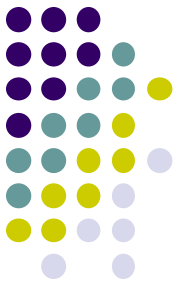
- Discussion on mm-comm sample [\[M3\]](#)
 - We use [ppcomp25-12](#) slides
 - MPI_Send/MPI_Recv are used
- Discussion on bsort sample [\[M2\]](#)
 - MPI_Send/MPI_Recv are used
- Discussion on diffusion sample [\[M1\]](#)
 - Avoiding deadlock is important



- Discussion of mm-comm in ppcomp25-12

“bsort” Sample Program

Target of [M2], details are in ppcomp25-4



Base version: [ppcomp-ex/base/bsort/](https://github.com/ppcomp-ex/base/bsort/)

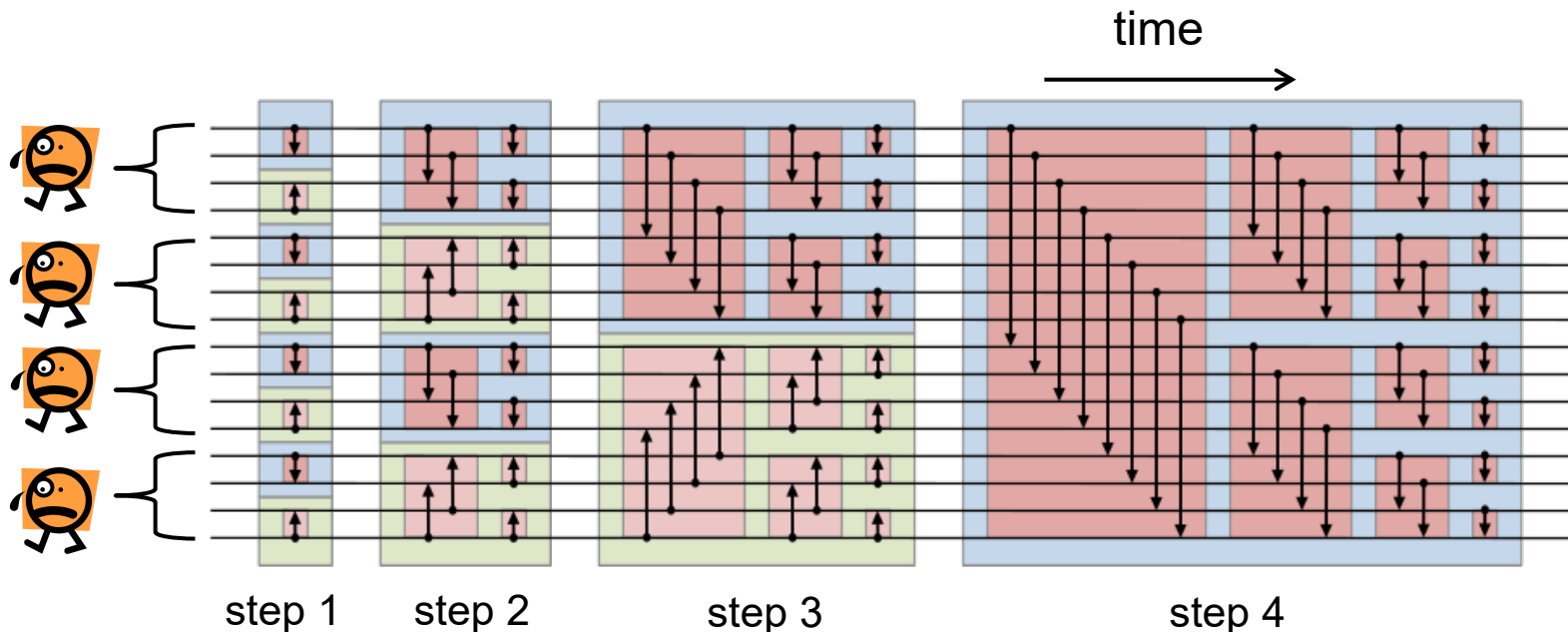
You can use [ppcomp-ex/mmpi/bsort/](https://github.com/ppcomp-ex/mmpi/bsort/) (see notes in p.3)

```
cd ppcomp-ex/mmpi/bsort
module load intel-mpi // if not yet
make
./bsort 1000000 // number of elements to be sorted
```

How We Parallelize bsort? (1)



- In this case, we should assume “the number of process $P = \text{power of } 2$ ” (1, 2, 4, 8...)
- Data array is divided among processes
 - Each process has N/P data ($N/2$ in bsort.c)
 - If array is initialized in rank 0, communication is needed before and after the algorithm





For Loops in bsort

```
for (i = 1; (1<<i) <= N2; i++) { // step loop
    for (j = i-1; j >= 0; j--) { // sub-step loop
        :
        for (k = 0; k < N2; k++) {
            // compare 2 data and swap if appropriate
        }
    }
}
```

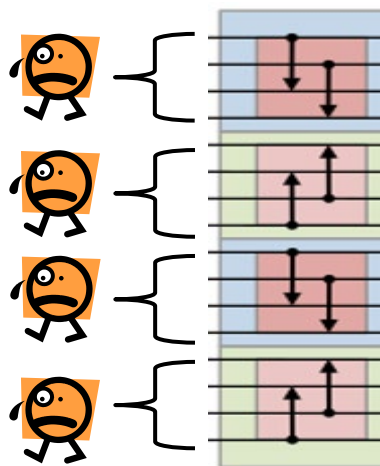
- All processes executes steps and sub-steps
 - i, j loop are not changed
- Algorithm of each sub-step should be discussed



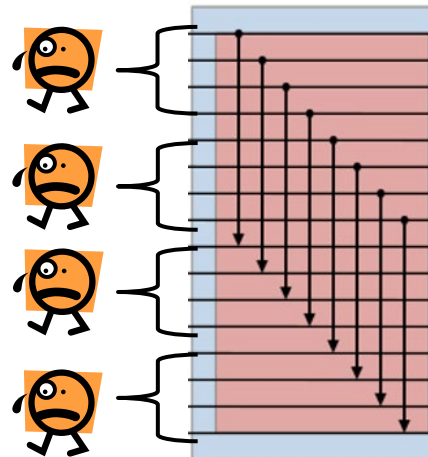
Algorithm of a Sub-step

- In a sub-step, $\text{data}[k]$ and $\text{data}[k+\text{dist}]$ are compared and may be swapped
 - $\text{dist} = 1 \ll j$;

If $\text{dist} < N/P$,
a sub-step can be done
within each process



If $\text{dist} \geq N/P$,
We need communication!



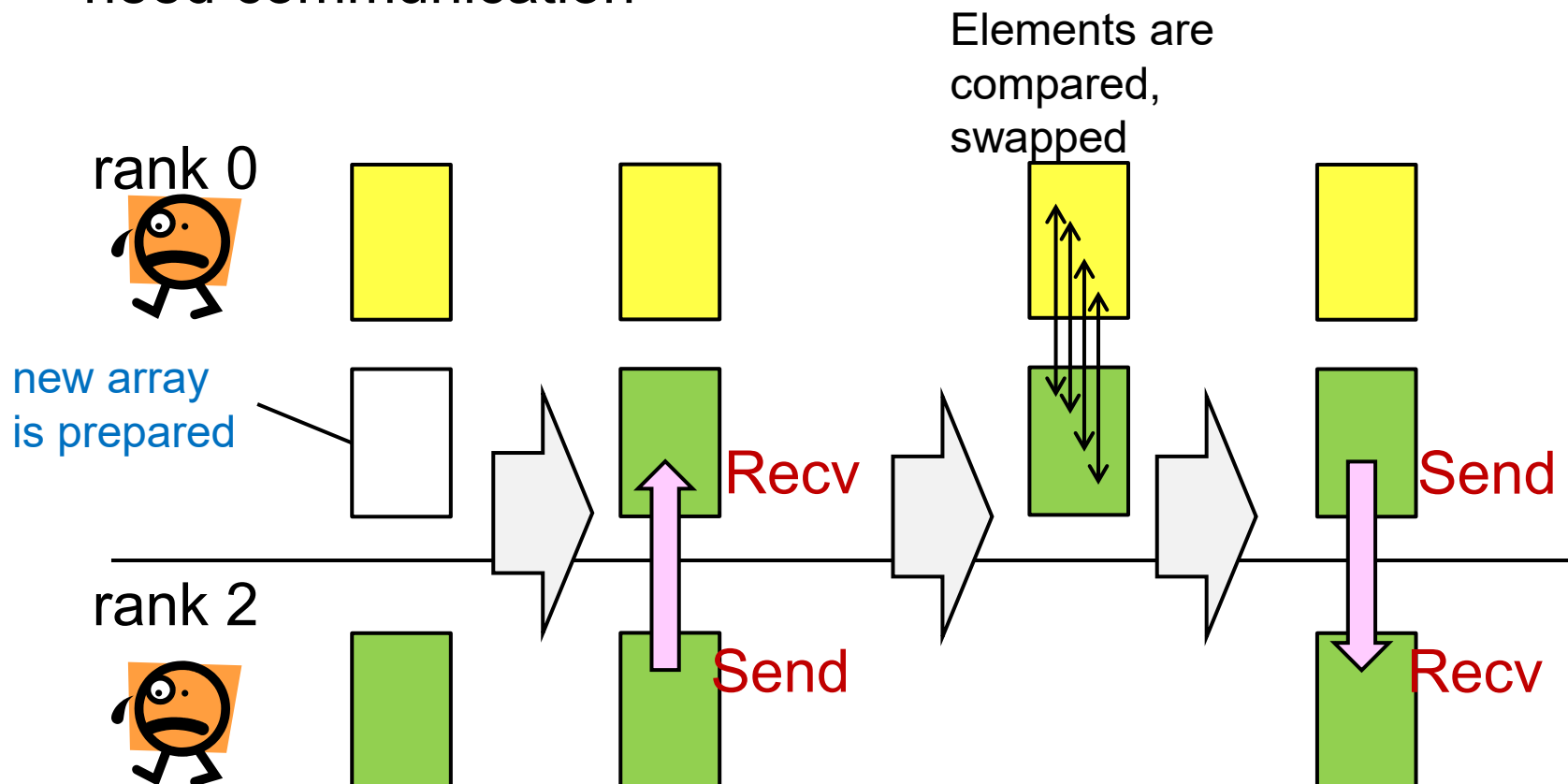
In this case,

- rank 0 and 2 need communication
- rank 1 and 3 need communication

Example of Communication in bsort



- Let us consider a sub-step, where rank 0 and rank 2 need communication





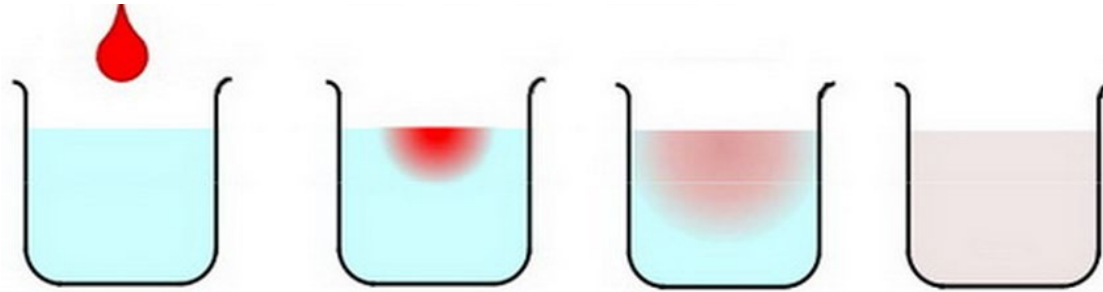
Overview of MPI bsort

```
for (i = 1; (1<<i) <= N2; i++) { // step loop
    for (j = i-1; j >= 0; j--) { // sub-step loop
        int dist = 1 << j;
        if (dist < N2/P) {
            // local computation
        }
        else {
            int rdist = dist/(N2/P);
            if (rank & rdist == 0) {
                // my buddy is (rank+rdist)
                // recv, computation, send
            }
            else {
                // my buddy is (rank-rdist)
                // send, recv
            }
        }
    }
}
```

Case of “diffusion” Sample related to [M1]



An example of diffusion phenomena:

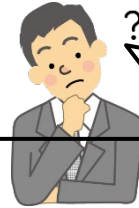


The ink spreads gradually, and finally the density becomes uniform (Figure by Prof. T. Aoki)

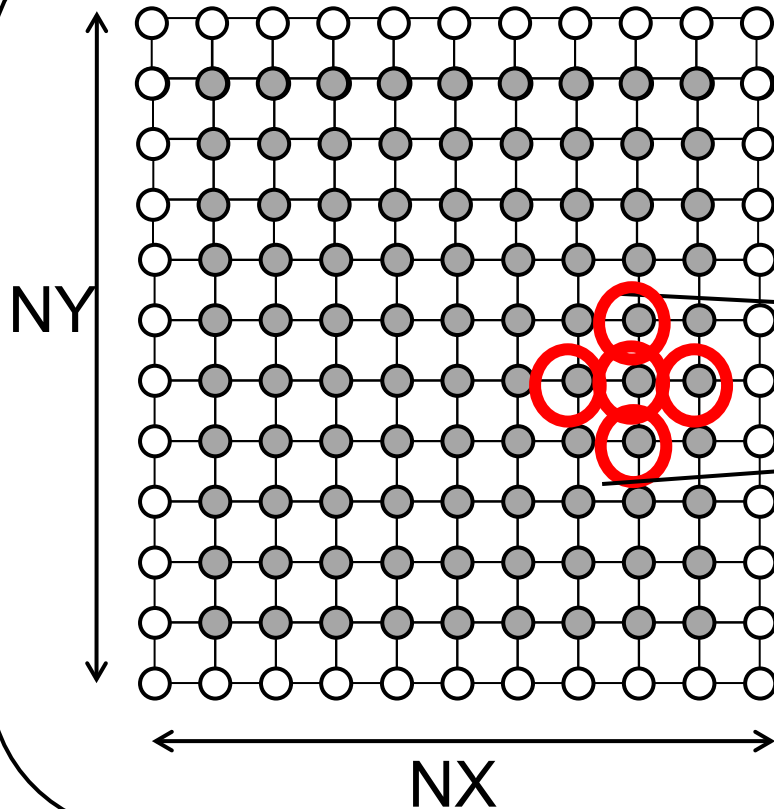
- Execution: `./diffusion [nt]`
 - nt: Number of time steps

You can use [ppcomp-ex/mpi/diffusion](https://ppcomp-ex.mpi/diffusion) as a base.
Makefile uses mpicc

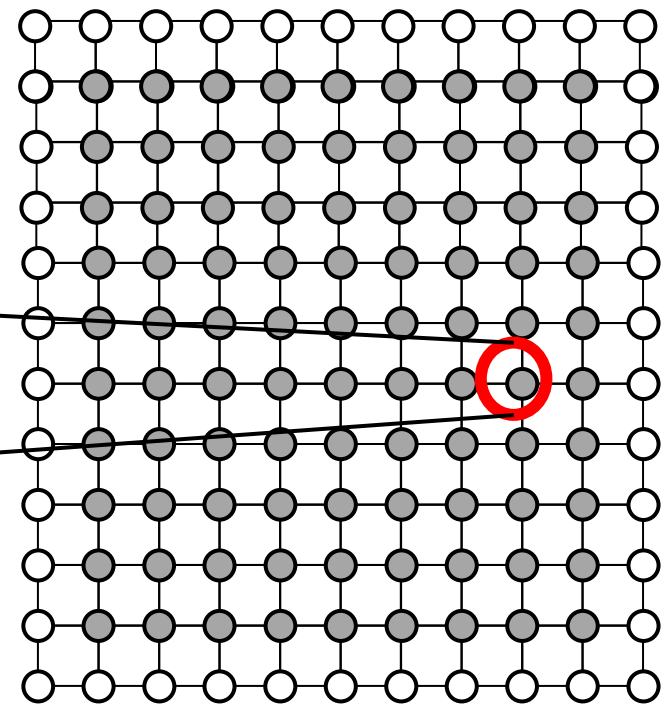
Data Structure in Original “diffusion”



An Array for “even” steps



An Array for “odd” steps



How should we distribute data?

How Do We Parallelize “diffusion” Sample?



On OpenMP:

[Algorithm] Parallelize spatial (Y or X) for-loop

- Each thread computes its part in the space
- Time (T) loop cannot be parallelized, due to dependency

[Data] Data structure is same as original:

- 2 x 2D arrays → `float data[2][NY][NX];`

On MPI:

[Algorithm] Same as above

- Each process computes its part in the space

[Data] 2 x 2D arrays are divided among processes

- Each process has its own part of arrays

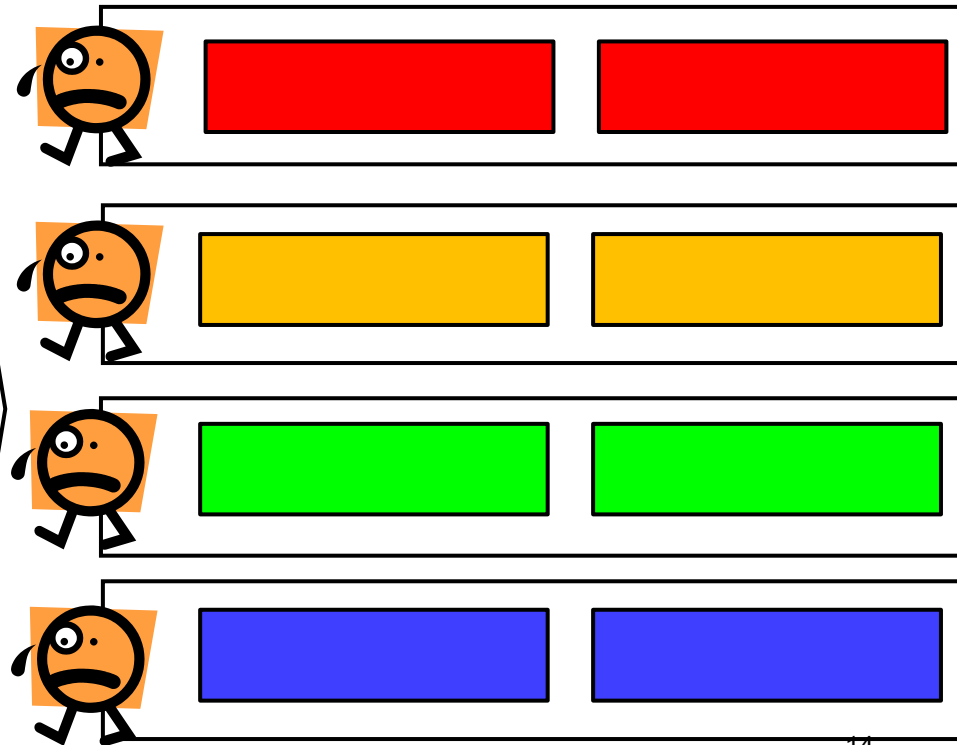
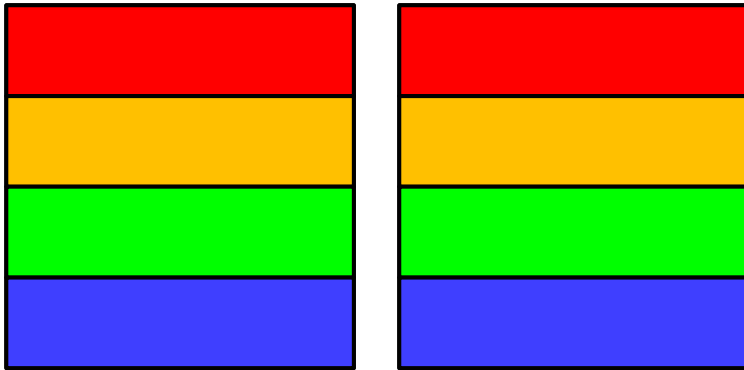


Considering Data Distribution (1)

2 x 2D arrays are divided among
P processes (in this case, horizontally)



✖ A color = a process



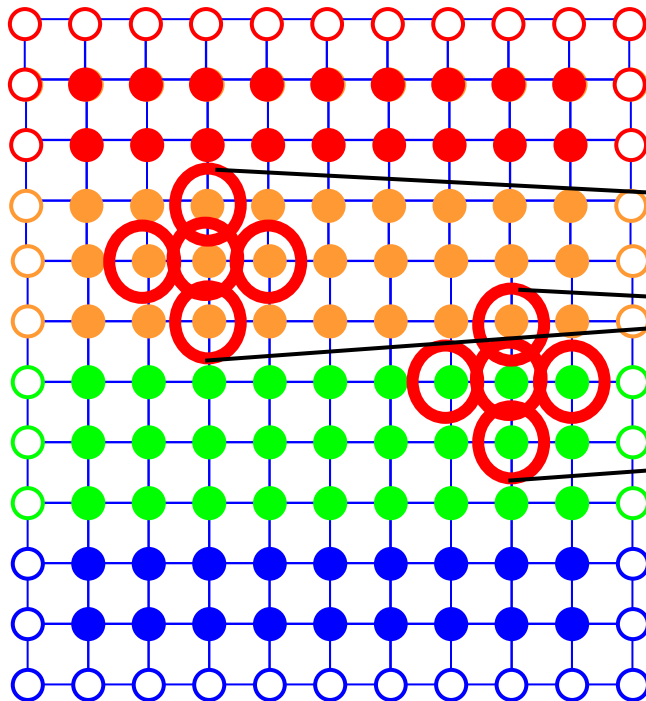
This looks ok, but will be
improved next

Each array size is (roughly)
 $NX \times (NY/P)$

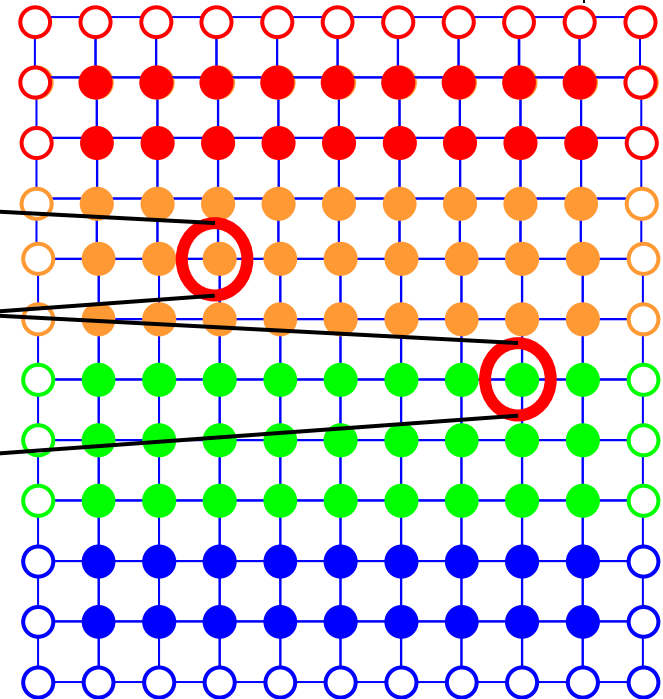
Improving Data Distribution (1)



An Array for “even” steps



An Array for “odd” steps

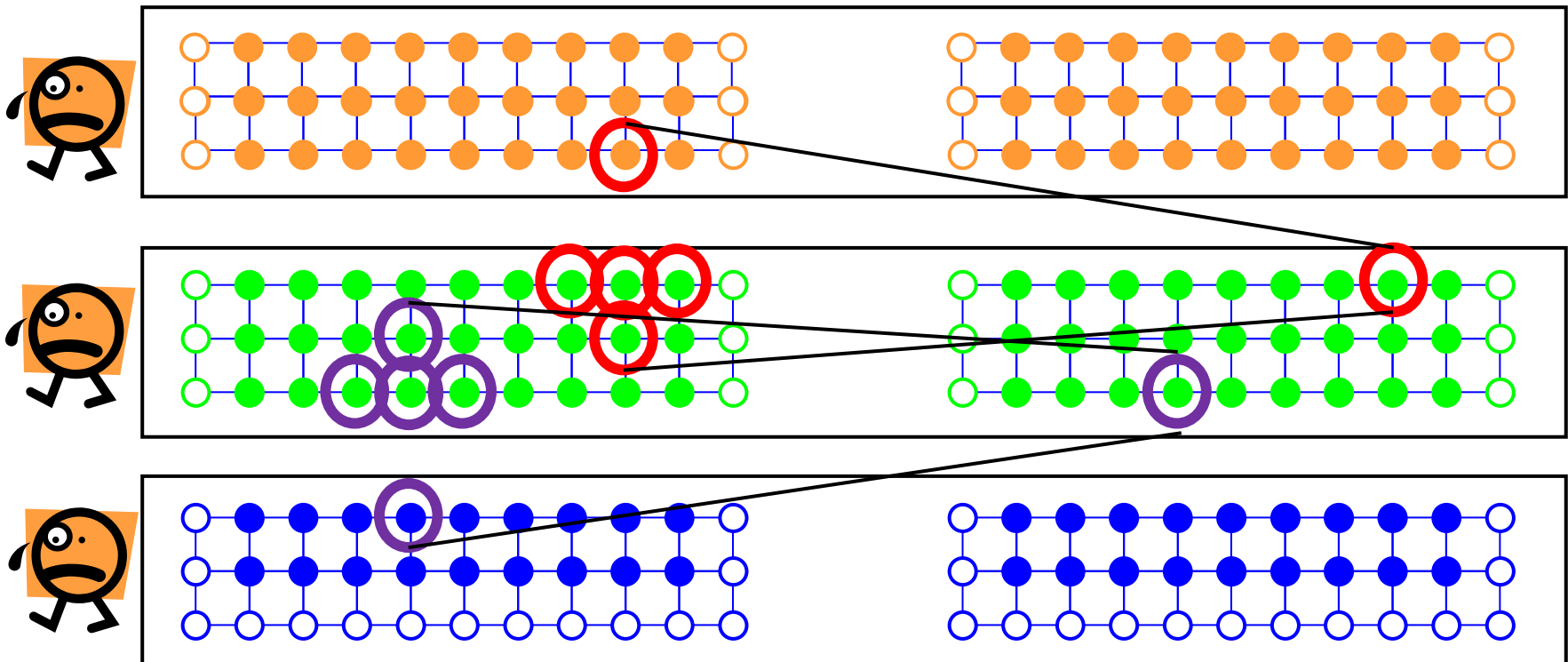


- Let's remember computation of each point
→ 5 points are read and 1 point is written



Improving Data Distribution (2)

- What's wrong with the simple distribution?



Computation requires data in other processes

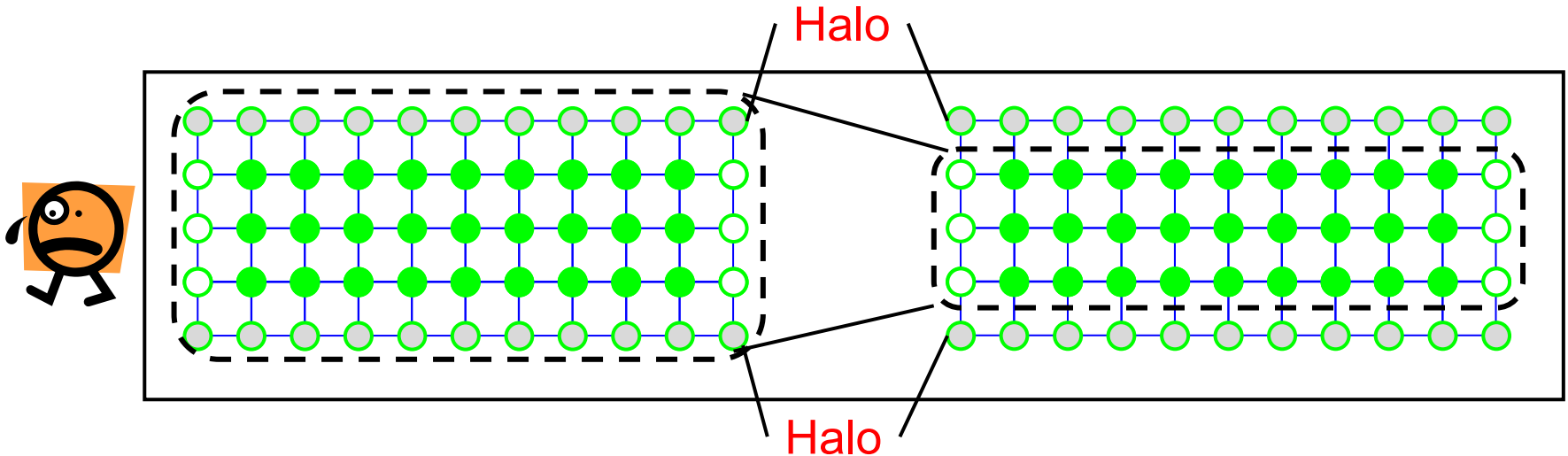
→ **Message passing is required**

We need memory region for received data!

A Technique in Stencil: Introducing “Halo” Region



- In stencil computation, it is a good idea to make additional rows to arrays
→ called “Halo” region



Each array size is (roughly) $NX \times (NY/P + 2)$

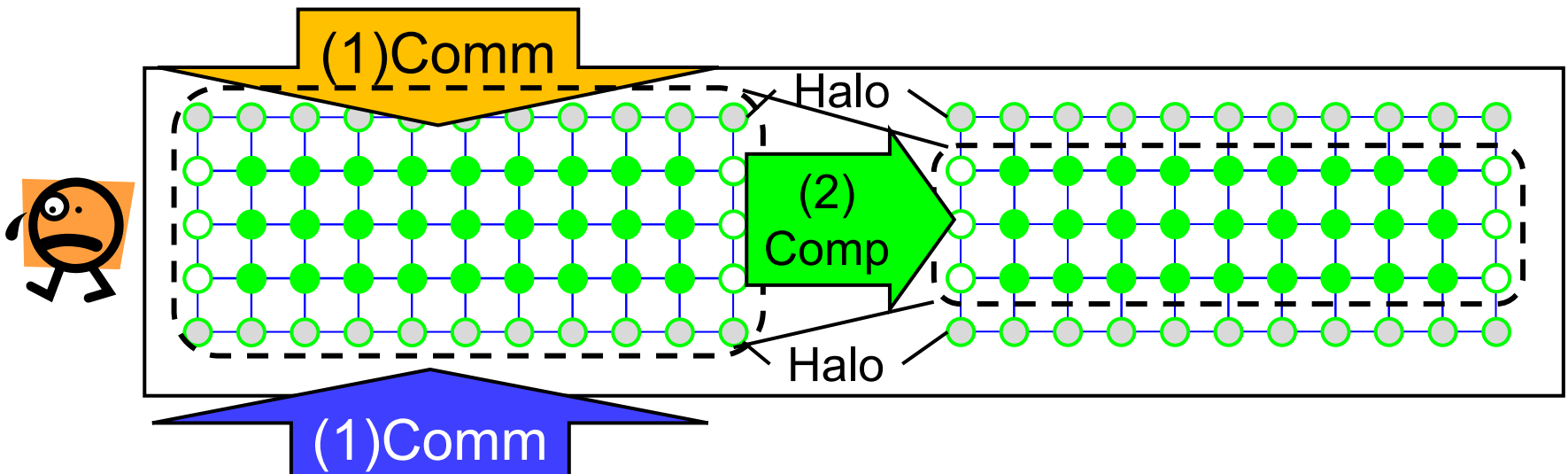
Halo regions are used to **receive** outside border data
from neighbor processes



Using “Halo” Region

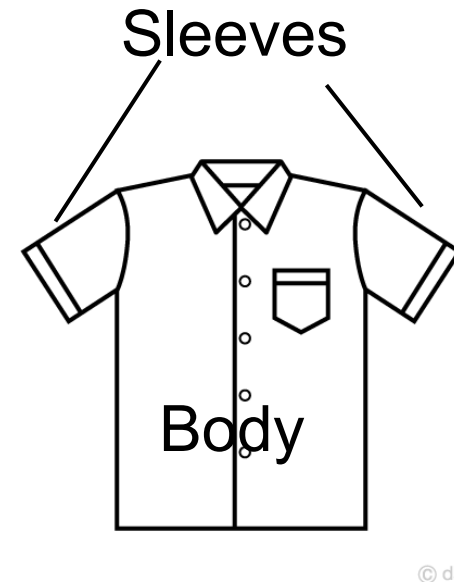
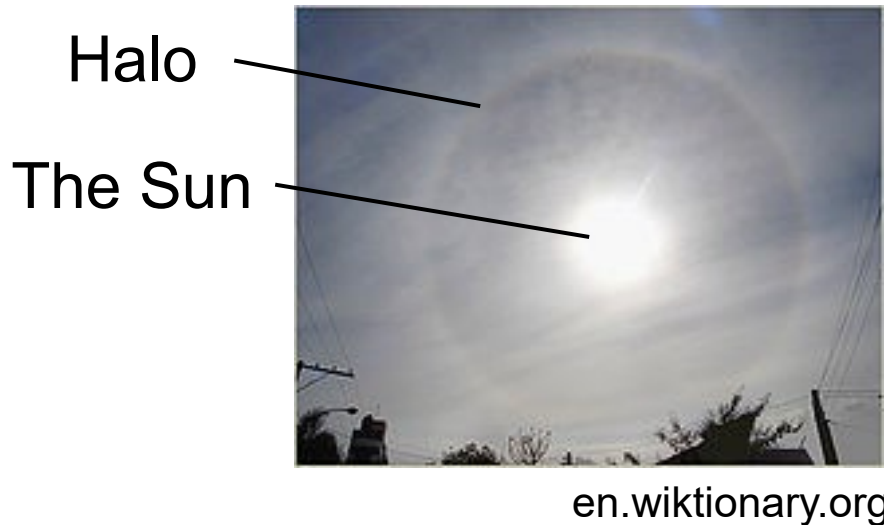
Each time step consists of:

- (1) **Communication**: Recv data and store into “halo” region
 - Also neighbor processes need “my” data
- (2) **Computation**: Old data at time t (including “halo”)
→ New data at time $t+1$



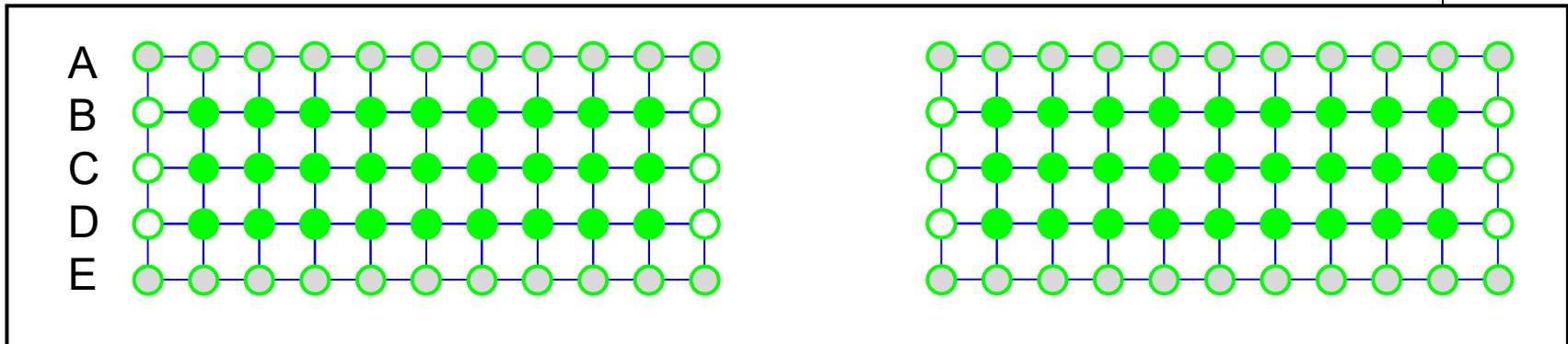
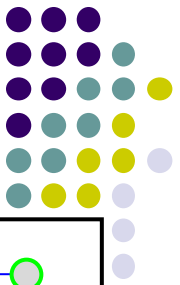


The name of “Halo” Region



“Halo regions” are sometimes called “sleeve regions” or “overlap regions”

Overview of MPI “diffusion” (?)



```
for (t = 0; t < nt; t++) {  
    if (rank > 0) Send B to rank-1  
    if (rank < size-1) Send D to rank+1  
    if (rank > 0) Recv A from rank-1  
    if (rank < size-1) Recv E from rank+1  
    Computes points in rows B-D  
    Switch old and new arrays  
}
```

(1) Communication
in “old” array

(2) Computation
“old” array \Rightarrow “new” array

This version is still unsafe, for possibility of **deadlock**
→ Explained next

A Sample with Neighbor Communication (1)

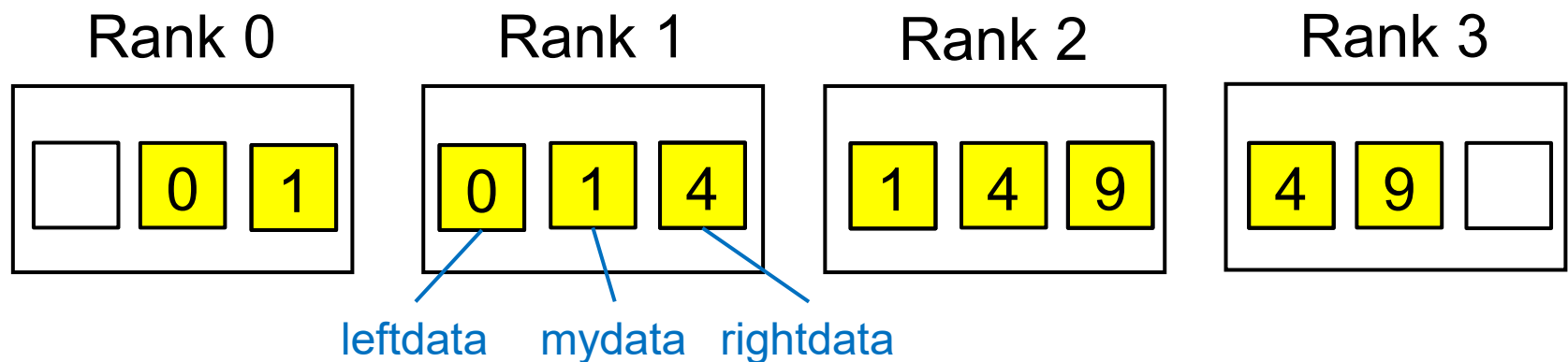


When considering neighbor communication, we have to avoid deadlock (a serious bug)!

A sample is available at ppcomp-ex/mpi/neicomm/

Execution: `mpiexec -n [P] ./neicomm`

- (1) Each process prepares its local data
- (2) Each process receives data from its neighbors, rank-1 and rank+1



(actually each of them is an array)

A Sample with Neighbor Communication (2)



- [ppcomp-ex/mpi/neicomm/](#)
- The behavior is different with different MPI libraries.
We use “[openmpi](#)” here, different from usual ([intel-mpi](#))

[make sure that you are at a interactive node (rXn11)]

module purge *[Clear loaded modules]*

module load openmpi *[Do once after login]*

[please go to your ppcomp-ex directory]

cd mpi/neicomm

make

[An executable file “neicomm” is created]

mpiexec -n 4 ./neicomm



Changing “neicomm” sample

- If neicomm.c is changed, the behavior is changed

```
    :
    #define N 65536
    :
    int main(...) {
    :
    #if 1
        printf("Calling neicomm_safe¥n");
        neicomm_safe(..., N, DOUBLE);
    #else
        printf("Calling neicomm_unsafe¥n");
        neicomm_unsafe(..., N, DOUBLE);
    #endif
    :
```

Size of arrays
to be transferred

Usually `neicomm_safe()`
is called.
When changed to “`#if 1`”,
`neicomm_unsafe()` is called.



Behavior of “neicomm” Sample

	neicomm_unsafe()	neicomm_safe()
module load intel-mpi	Deadlock!	Ok
module load openmpi	If N is small, Ok (?) If N is large, Deadlock!	Ok

✘ In case of “deadlock”,
the sample does not finish.
To abort it, press Ctrl+C

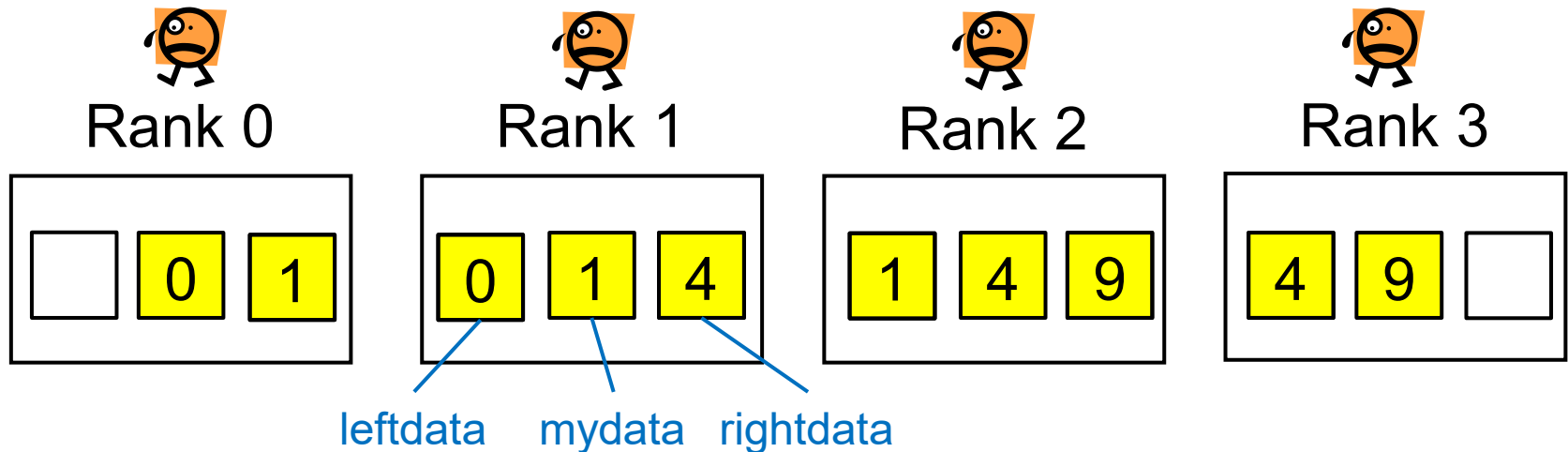
The problem of deadlock should be avoided (with any condition)

➔ “neicomm_safe()” is good



neicomm_safe() in neicomm Sample (1)

- neicomm_safe() does neighbor communication
 - It should be called from all processes



neicomm_safe

(rank, size,

(void *)mydata, (void *)mydata,

(void *)leftdata, (void *)rightdata,

N, MPI_DOUBLE);

my rank (ID), # processes

data sent to rank-1 & rank+1

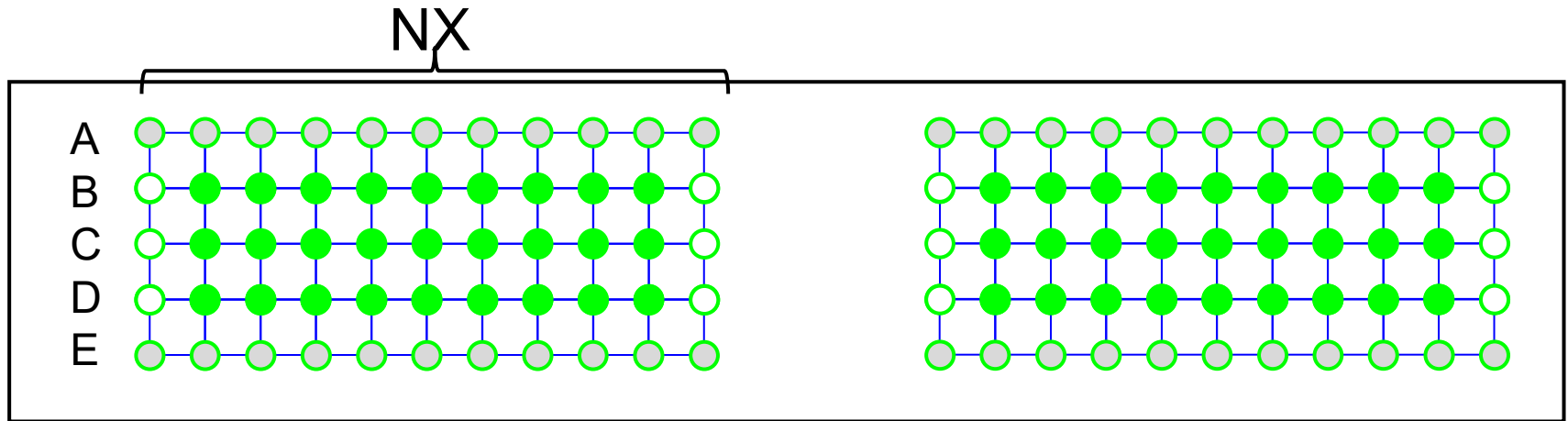
address received from rank-1&rank+1

data size, data type



neicomm_safe() in neicomm Sample (2)

- In [M1], you may use neicomm_safe() for halo communication



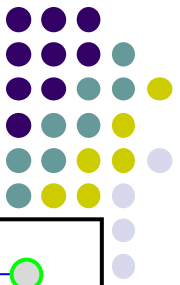
```
neicomm_safe (rank, size,  
              B, D, A, E, NX, MPI_FLOAT);
```

send to
rank-1

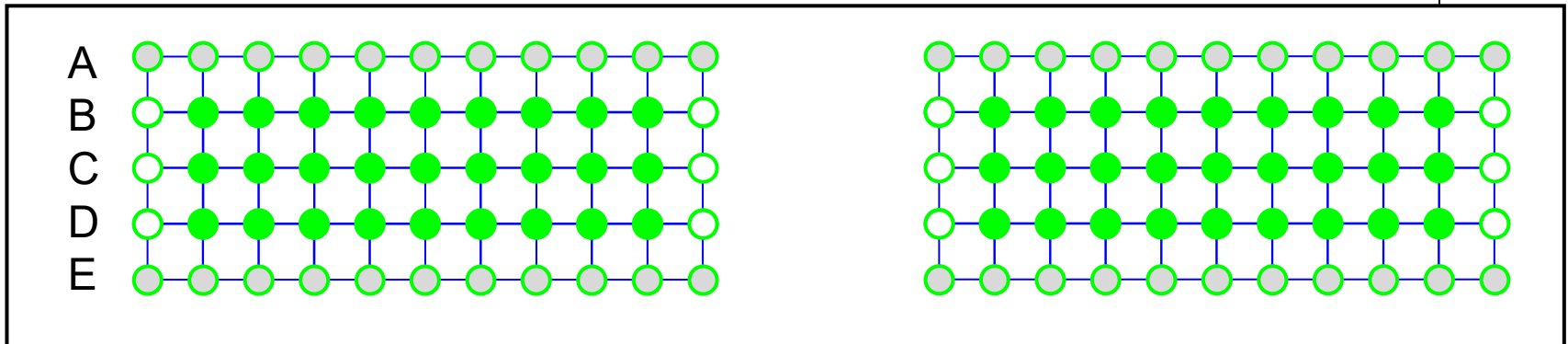
send to
rank+1

recv from
rank-1

recv from
rank+1



Overview of MPI “diffusion” (Final)



```
for (t = 0; t < nt; t++) {
```

```
if (rank > 0) Send B to rank-1
if (rank < size-1) Send D to rank+1
if (rank > 0) Recv A from rank-1
if (rank < size-1) Recv E from rank+1
```

(1) Communication
in “old” array

→ Replaced to
`neicomm_safe()`

Computes points in rows B–D

Switch old and new arrays

(2) Computation

“old” array ⇒ “new” array

```
}
```

What are Differences between Unsafe Version and Safe Version?

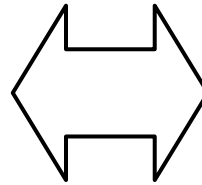


Unsafe version ☹️

Safe version 😊

Inside `neicomm_unsafe()`

```
Send to rank-1
Send to rank+1
Recv from rank-1
Recv from rank+1
```



Inside `neicomm_safe()`

```
Start to recv from rank-1
Start to recv from rank+1
Sent to rank-1
Sent to rank+1
Finish to recv from rank-1
Finish to recv from rank+1
```

This look ok, but may cause
deadlock !! ☹️

New type of communication,
Non-blocking Communication
appears

➔ **Next Class**



Assignments in MPI Part

Choose one of [M1]—[M4], and submit a report

Due date: June 9 (Monday)

[M1] Parallelize “diffusion” sample program by MPI

[M2] Parallelize “bsort” sample program by MPI

[M3] Evaluate speed of “mpi/mm” sample in detail

[M4] (Freestyle) Parallelize *any* program by MPI

For more details, please see [ppcomp25-12](#) slides



Plan of MPI Part

- Class #12
 - Introduction to MPI, message passing
- Class #13
 - Distributed Algorithms with MPI
- Class #14
 - Non-blocking communication
 - Group communication
 - Performance improvement
- Class #15 (May 29, Optional)
 - TSUBAME supercomputer tour