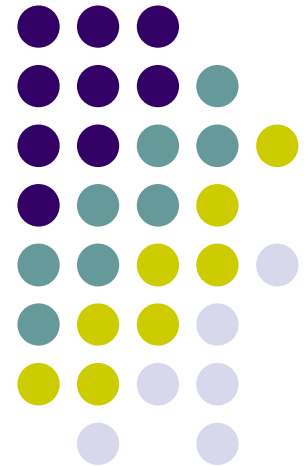


Practical Parallel Computing (実践的並列コンピューティング)

2025 Class No.10
[CUDA Part] (2)
Using Many Threads in CUDA

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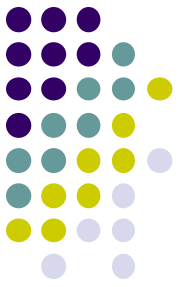


Overview of This Course

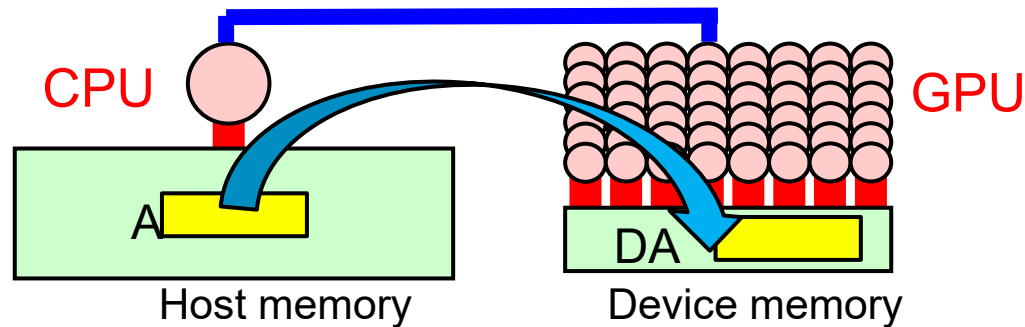
- Introduction Part
 - 2 classes
 - OpenMP (OMP) Part
 - 4 classes
 - Report (required)
 - OpenACC (ACC) Part
 - 2 classes
 - Report (required)
 - CUDA Part
 - 3 classes
 - Report (elective)
 - MPI Part
 - 3 classes
 - Report (elective)
- ← We are here (2/3)

Review:

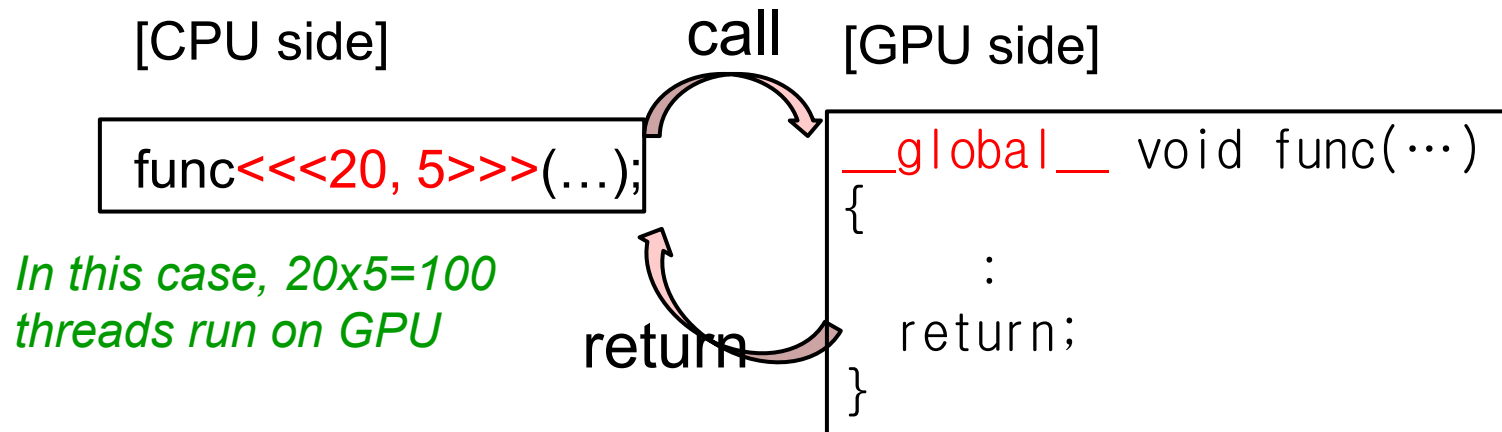
How We Write CUDA Programs



- Data is prepared on GPU device memory
 - `cudaMalloc()`, `cudaMemcpy()`



- CPU function calls GPU kernel functions



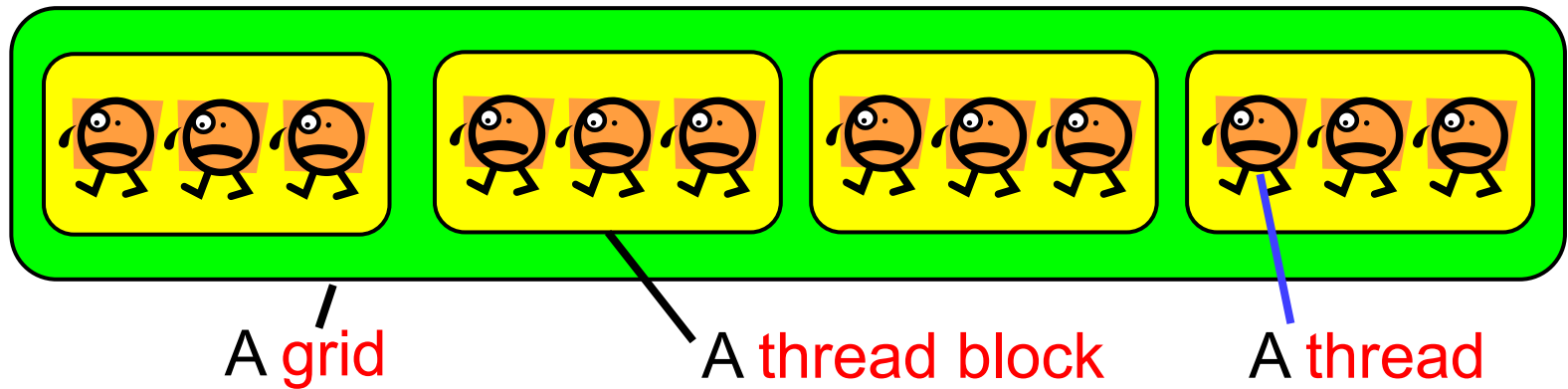
Review:

Grid, Thread Blocks, Threads



A grid has several thread blocks

A thread block has several threads



cf) func <<< 4, 3 >>> (); → 12 threads

Number of thread blocks = gridDim
Number of threads per block = blockDim

Review:

How is Number of Threads Designed?



We have to decide 2 numbers
<<<block number, block size>>>

A better way would be

- (1) We decide **total** number of threads P
 - P should be very large, such as $>1,000,000$
- (2) We tune each block size BS
 - Good candidate are 16, 32, 64, ... 1024
- (3) Then block number is P/BS
 - It is better to consider indivisible cases





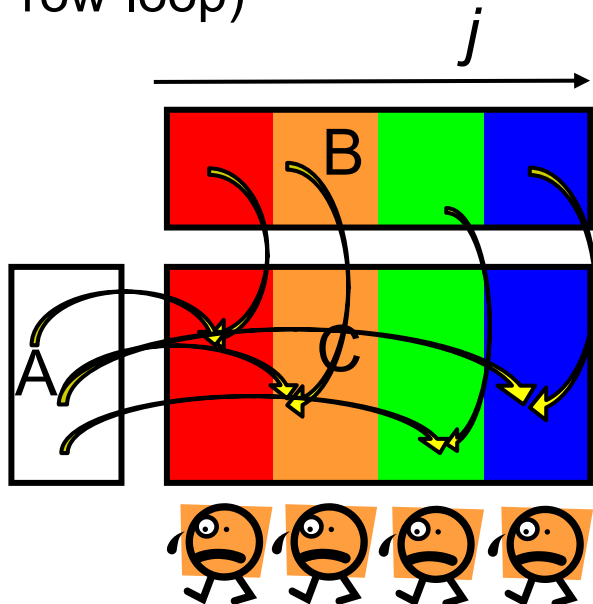
Review: mm-1dpar Sample is Slow

Related to [C3]

- CUDA versions of mm samples are at
- [ppcomp-ex/cuda/mm-1dpar/](https://github.com/ppcomp-ex/cuda/mm-1dpar/) (slow)
 - [ppcomp-ex/cuda/mm/](https://github.com/ppcomp-ex/cuda/mm/) (faster)

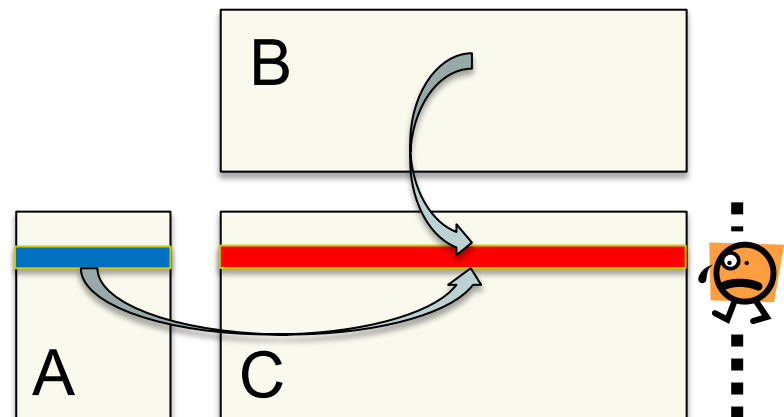
OpenMP

- Parallelize column-loop
(or row-loop)



CUDA (mm-1dpar)

- We can create many threads
- 1 thread computes 1 row
 - We use m threads



m threads are too few for GPU



In Case of mm-acc (OpenACC)

- mm-use “acc loop independent” twice

- j loop (size n) and i loop (size m)

```
#pragma acc data copyin(A[0:m*k],B[0:k*n]),copy(C[0:m*n])
#pragma acc kernels
#pragma acc loop independent // j loop is parallelized
    for (j = 0; j < n; j++) {
#pragma acc loop seq
        for (l = 0; l < k; l++) {
#pragma acc loop independent // i loop is parallelized
            for (i = 0; i < m; i++) {
                Ci,j += Ai,l * Bl,j;
            } } }
    }
```

- This program creates m * n threads internally
- Also we want to create m * n threads on CUDA

Improvement of mm:

How to Use More Threads

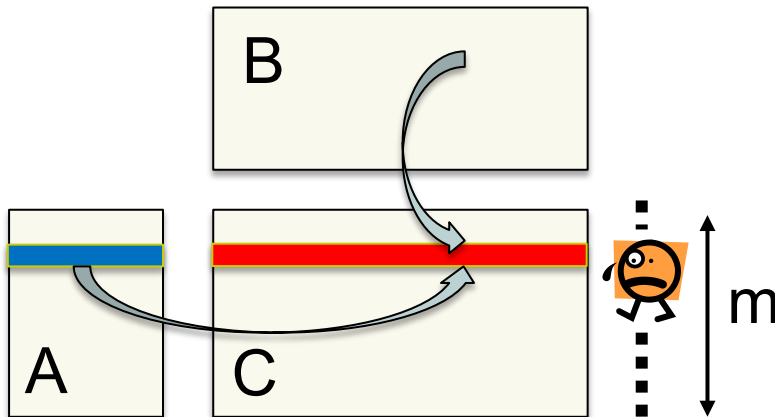


In mm, computation of **each C element** is independent with each other

cuda/mm-1dpar

- 1 thread computes 1 row

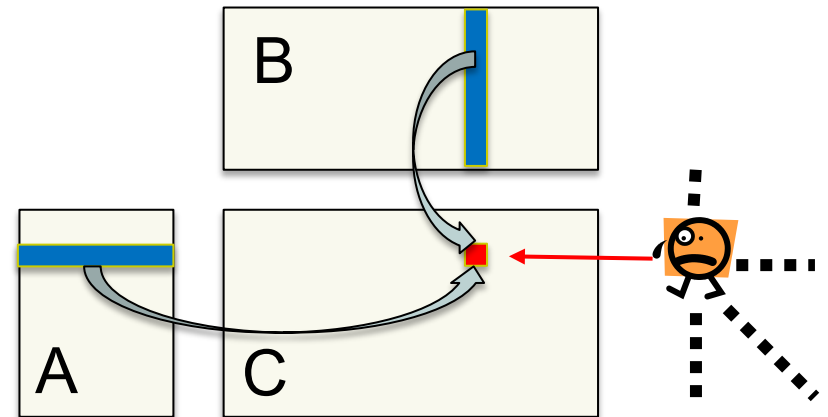
→ We use **m** threads



cuda/mm

- 1 thread computes 1 element

→ We use **m × n** threads !!

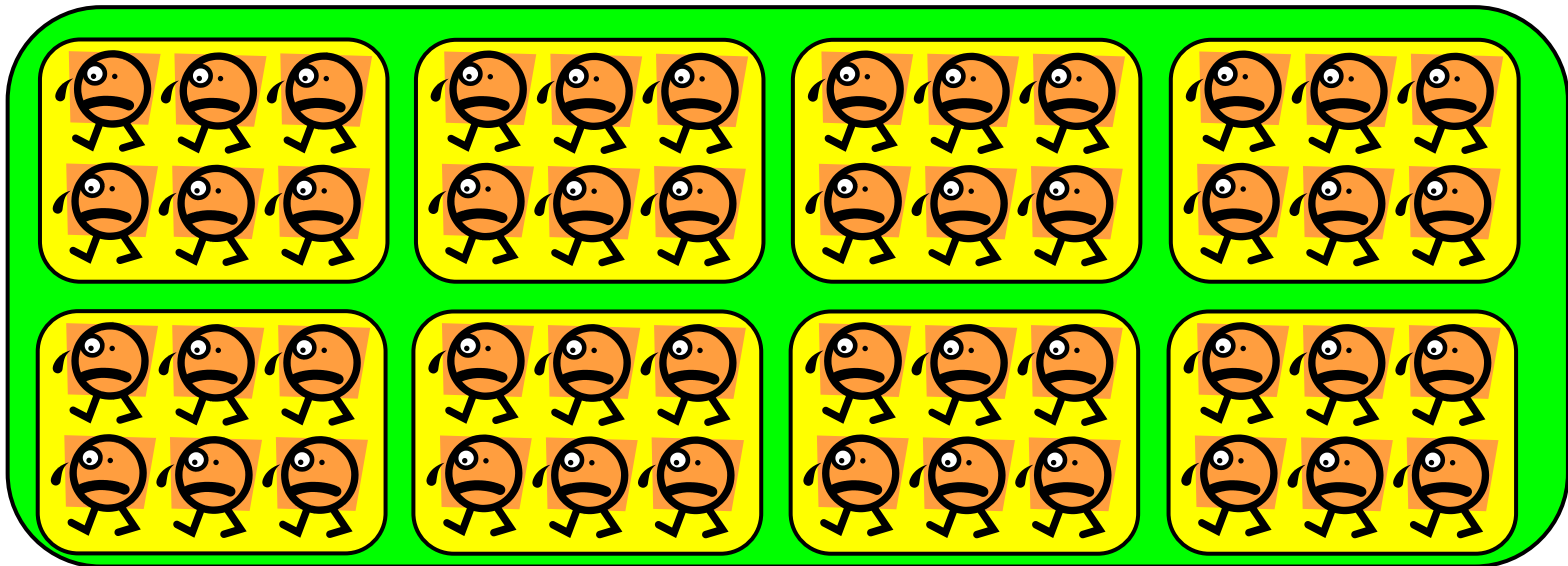


Creating Threads with 2D/3D IDs



- Now we want to make $m*n$ (may be $>1,000,000$) threads
 - `<<<(m*n)/BS, BS>>>` is ok, but coding is bothersome
- On CUDA, thread blocks and thread can have **3D IDs**
 - `gridDim` and `blockDim` may have “**dim3**” type, 3D vector structure with x, y, z fields

cf) func `<<< dim3(4,2,1), dim3(3,2,1) >>> ();` → 48 threads

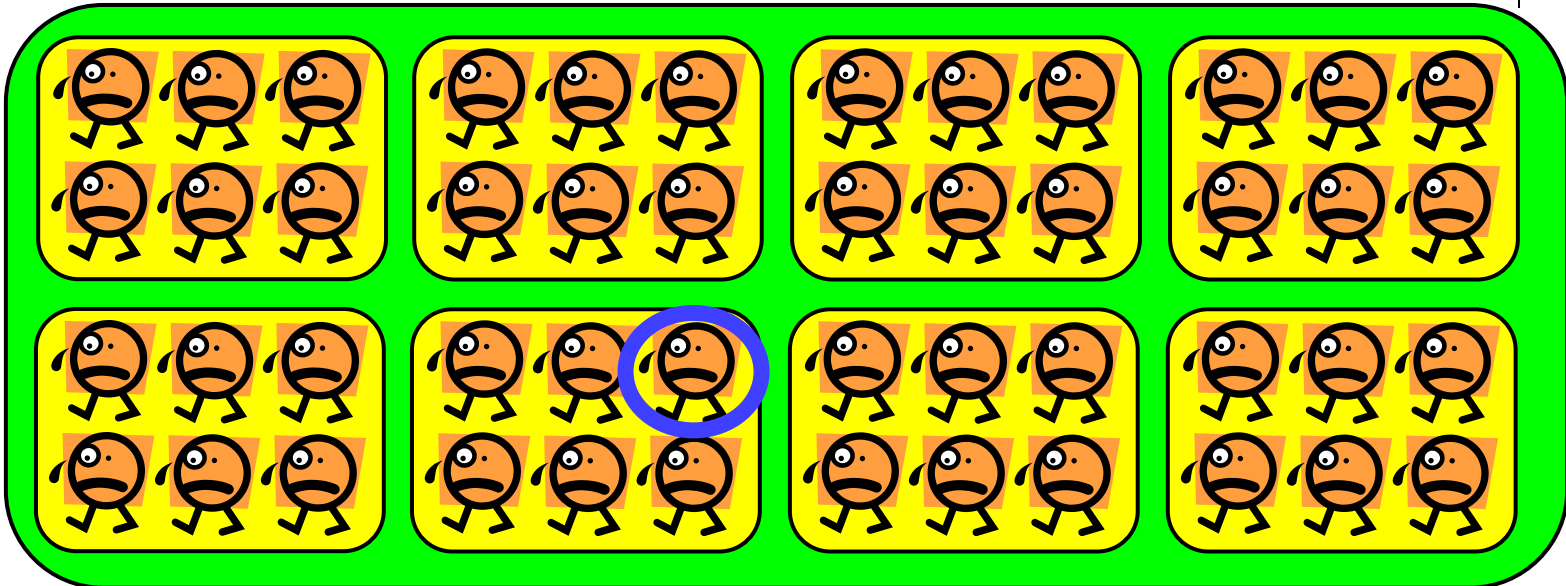


✂ This example is the case of 2D (Z dimensions are 1)

Thread IDs in multi-dimensional cases



In the case of func `<<< dim3(4,2,1), dim3(3,2,1) >>> ();`



- For every thread,
gridDim.x=4, gridDim.y=2, gridDim.z=1
blockDim.x=3, blockDim.y=2, blockDim.z=1
- For the thread with blue mark,
blockIdx.x=1, blockIdx.y=1, blockIdx.z=0
threadIdx.x=2, threadIdx.y=0, threadIdx.z=0



Notes on 1D Specification

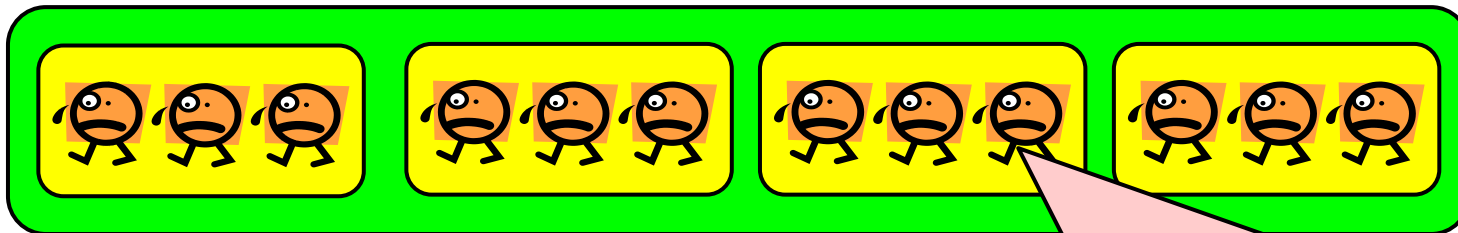
- So far we used 1D gridDim, 1D blockDim
- They are special cases of 3D IDs

The followings are same meanings

```
func <<<4, 3>>> ();
```

```
func <<<dim3(4,1,1), dim3(3,1,1)>>> ();
```

```
dim3 grid = dim3(4,1,1);  
dim3 block = dim3(3,1,1);  
func <<<grid, block>>> ();
```

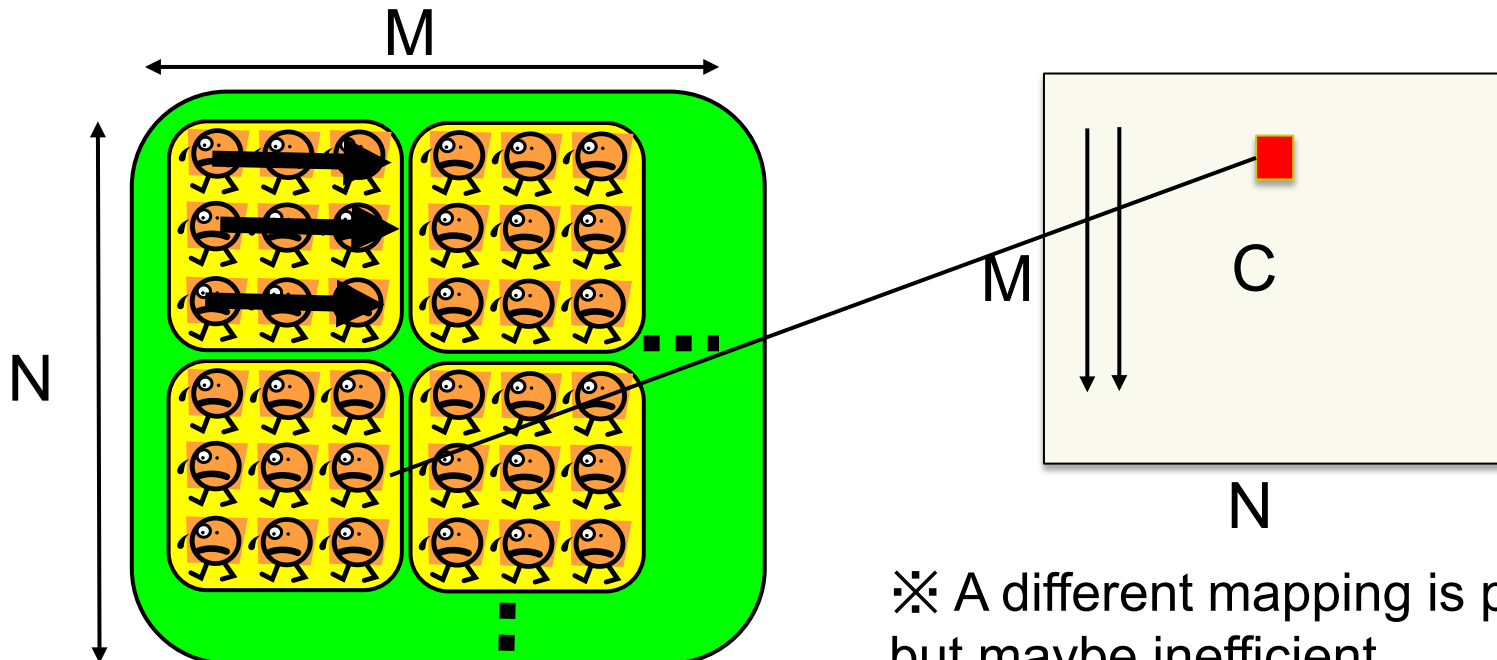


blockIdx.x = 2, blockIdx.y = 0, blockIdx.z = 0
threadIdx.x = 2, threadIdx.y = 0, threadIdx.z = 0

Using More Threads in cuda/mm Sample



- The total number of threads should be $m \times n$
- How do we determine gridDim, blockDim?
 - `<<<m, n>>>` does not work for CUDA constraints
- Here, we determine blockDim as $x=16, y=16 \rightarrow 256$ threads per block
 - Then gridDim is computed from M, N
- x is mapped to row index, y is mapped to column index (※)



※ A different mapping is possible, but maybe inefficient

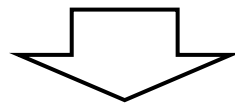


CPU Side Code in cuda/mm

gridDim blockDim

matmul_kernel<<<dim3(m / BS, n / BS, 1), dim3(BS, BS, 1)>>>
(DA, DB, DC, m, n, k);

BS=16 in this sample



Using rounding up for
indivisible cases...

```
dim3 grid = dim3((m+BS-1)/BS, ((n+BS-1)/BS), 1);  
dim3 block = dim3(BS, BS, 1);  
matmul_kernel<<<grid, block>>>(DA, DB, DC, m, n, k);
```

GPU Side Code in cuda/mm



```
__global__ void matmul_kernel(double *DA, double *DB, double *DC, int m, int n, int k)
{
    int i, j, l;
    j = blockIdx.y * blockDim.y + threadIdx.y;
    i = blockIdx.x * blockDim.x + threadIdx.x;
    if (i >= m || j >= n) return; // do nothing

    double cij = DC[i+j*ldc];
    for (l = 0; l < k; l++) {
        cij += DA[i+l*m] * DB[l+j*n];
    }
    DC[i+j*ldc] = cij;
}
```

A thread gets
entire thread IDs (x,y)
j \leftarrow y dimension, i \leftarrow x dimension

Avoid too many threads

A thread computes C_{ij}
 \rightarrow Only 1 loop (dot prod)



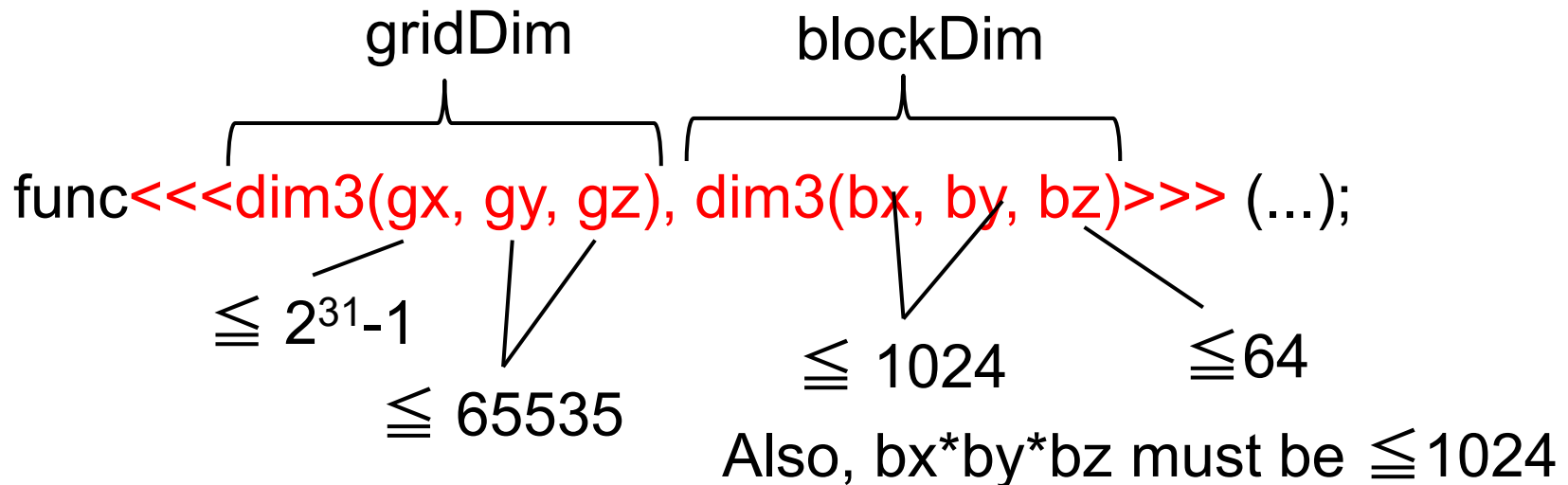
Notes about Report [C3]

- Compare speeds of
 - cuda/mm-1dpar: m threads
 - cuda/mm: $m \cdot n$ threads
 - Please use various matrices sizes (m , n , k)
- Evaluate effect of data transfer cost
 - The sample prints measured time in detail
 - Discussions are similar to OpenACC version (ppcomp25-8 slides)
 - Computation complexity: $O(mnk)$
 - Data transfer complexity: $O(mk + kn + mn)$

CUDA Rules on Number of Threads



`func<<<A, B>>> (...);` (*A, B are integers*) is same as
`func<<<dim3(A,1,1), dim3(B,1,1)>>> (...);`

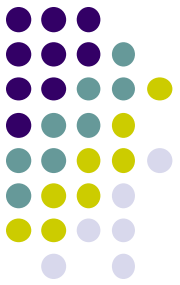


Size of blockDim has severe limitation ☹

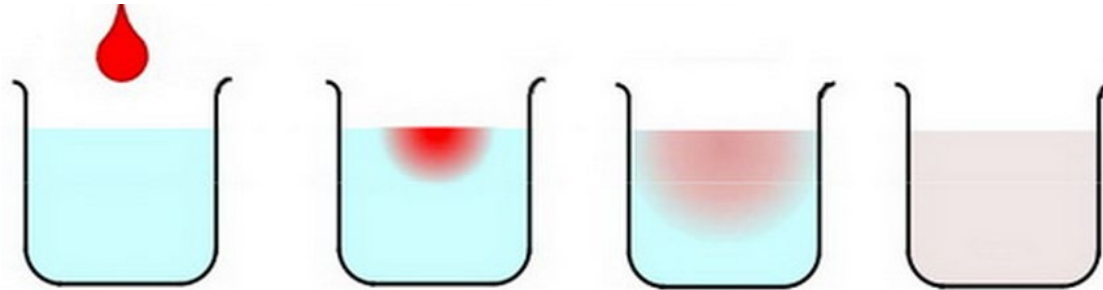
Cf) `<<<m, n>>>` causes an error if $n > 1024$ ☹

“diffusion” Sample Program

Target of [C1] , details are in ppcomp25-4



An example of diffusion phenomena:



The ink spreads gradually, and finally the density becomes uniform (Figure by Prof. T. Aoki)

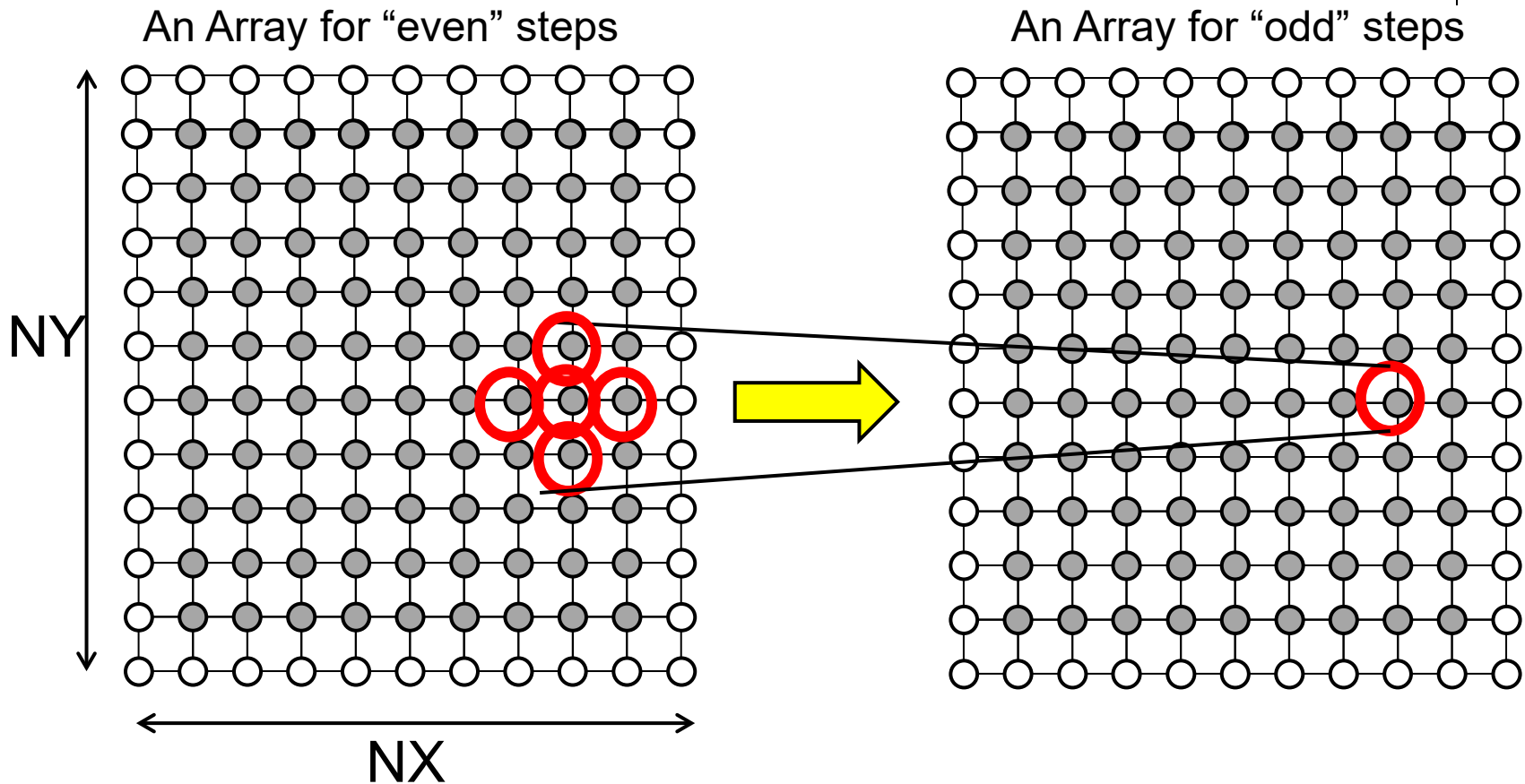
Base version: [ppcomp-ex/base/diffusion/](https://github.com/ppcomp-ex/base/diffusion/)

You can use [ppcomp-ex/cuda/diffusion/](https://github.com/ppcomp-ex/cuda/diffusion/)

```
cd ppcomp-ex/cuda/diffusion
module load nvhpc
make
./diffusion 20    // number of time steps
```



Discussion on diffusion sample



Both arrays have to be on GPU device memory when computations are done



Consideration of Parallelizing Diffusion

- x, y loops can be parallelized
- t loop cannot be parallelized

[Data transfer from CPU to GPU]

```
for (t = 0; t < nt; t++) {
```

```
    for (y = 1; y < NY-1; y++) {  
        for (x = 1; x < NX-1; x++) {  
            :  
        }  
    }
```

```
}
```

[Data transfer from GPU to CPU]

GPU computation must be a distinct function (GPU kernel function)

It's better to transfer data *out of* t-loop



Preparing GPU Kernel Function

- Unlike OpenACC/OpenMP, region on GPU must be a separated function. Code needs large change!

```
__global__ void calc_gpu(...) {  
    :    // behavior of each thread  
}
```

```
int calc(int nt) {  
    :  
    for (t = 0; t < nt; t++) {  
        :  
        calc_gpu<<<...>>>(...)  
        :  
    }  
}
```

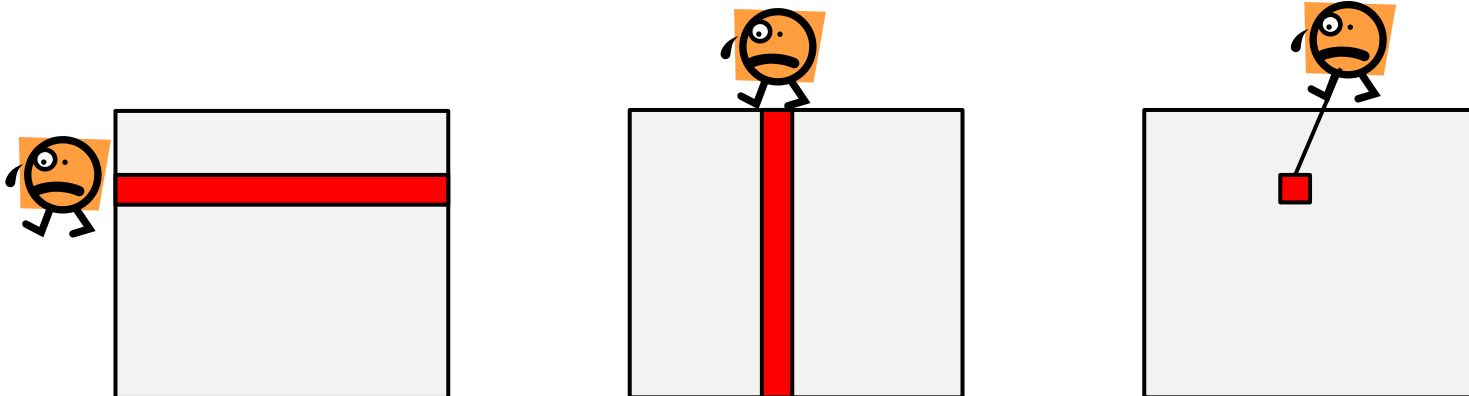


Calling a kernel
function



Considering CUDA Threads

- How do we design threads on CUDA?
- There are several choices
 - 1thread = 1row
 - We use NY threads in total → only x-loop in kernel function
 - 1thread = 1column
 - We use NX threads in total → only y-loop in kernel function
 - 1thread = 1element (Recommended)
 - We use NX x NY threads in total → No loop in kernel function!
 - This will be fast since the number of threads is very large

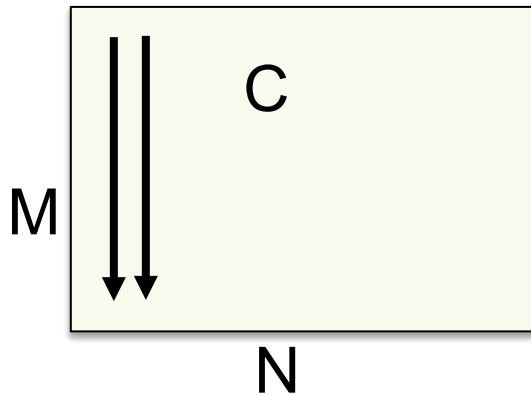


Mapping between Threads and Data

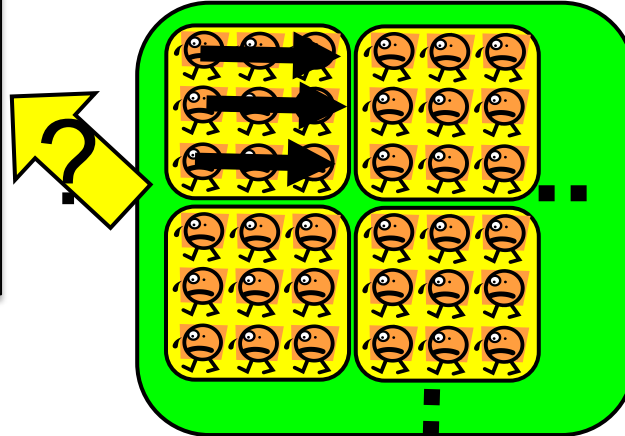


mm:

Matrices has
column-major format

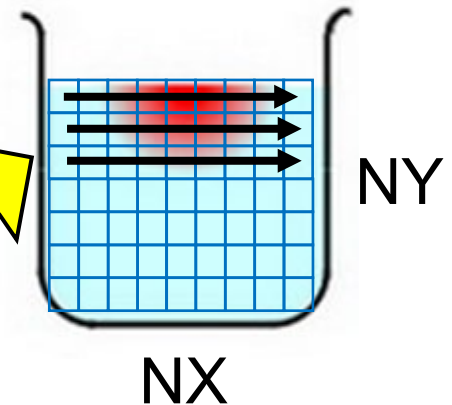


CUDA threads



diffusion:

2D array has
row-major format



```
j = blockIdx.y * blockDim.y +  
threadIdx.y;  
i = blockIdx.x * blockDim.x +  
threadIdx.x;  
: This thread computes Cij
```

```
y = blockIdx.y * blockDim.y +  
threadIdx.y;  
x = blockIdx.x * blockDim.x +  
threadIdx.x;  
: This thread computes [y][x]
```

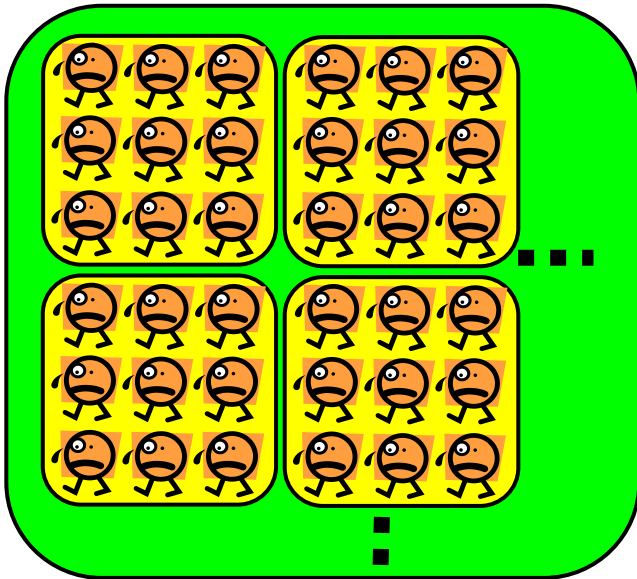
[Q] What if the dimensions are exchanged?



Considering gridDim/blockDim (1)

```
func <<< dim3 ( ?, ?, ? ), dim3 ( ?, ?, ? ) >>> (...);
```

gridDim blockDim



(1) We decide total number of threads

→ (NX, NY, 1) threads

- See notes on the next page

(2) We tune each block size (blockDim)

→ Good candidates are (4, 4, 1), (8, 8, 1), (16, 16, 1), (32, 32, 1)

- The number must be ≤ 1024
- How about non-square blocks?

(3) Then block number (gridDim) is determined

We should consider indivisible cases

Considering gridDim/blockDim (2)



- In diffusion, Points $[1, NX-1) \times [1, NY-1)$, excluded boundary, should be computed

There are choices:

(A) Create $NX \times NY$ threads

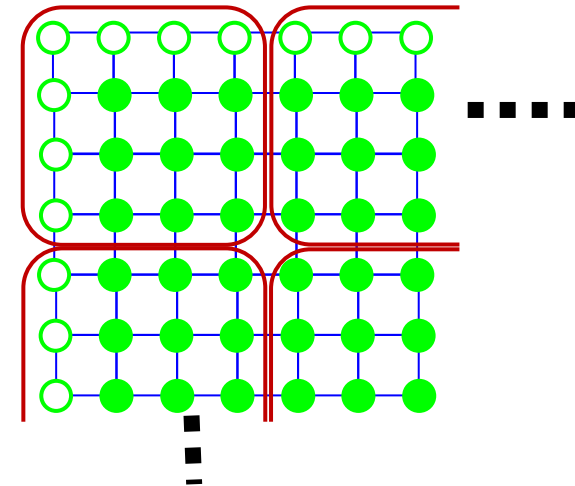
- Thread (x,y) computes (x,y)
- Threads with below IDs do nothing
 - $x == 0$ or $y == 0$ or $x \geq NX-1$ or $y \geq NY-1$

(B) Create $(NX-2) \times (NY-2)$ threads

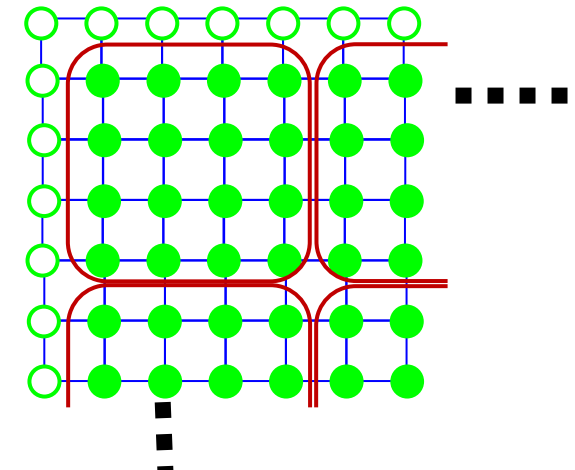
- Thread (x,y) computes $(x+1,y+1)$
- Threads with below IDs do nothing
 - $x \geq NX-2$ or $y \geq NY-2$

Either is ok 😊

(A)



(B)



Discussion on Data Transfer of Diffusion



Both codes will work, but how about speeds?

[Data transfer from CPU to GPU]

```
for (t = 0; t < nt; t++) {  
    :
```

```
    for (y = 1; y < NY-1; y++) {  
        for (x = 1; x < NX-1; x++) {  
            :  
        }  
    }  
}
```

```
}
```

[Data transfer from GPU to CPU]

Computation: $O(NX NY nt)$
Transfer: $O(NX NY)$

```
for (t = 0; t < nt; t++) {  
    :
```

[Data transfer from CPU to GPU]

```
for (y = 1; y < NY-1; y++) {  
    for (x = 1; x < NX-1; x++) {  
        :  
    }  
}
```

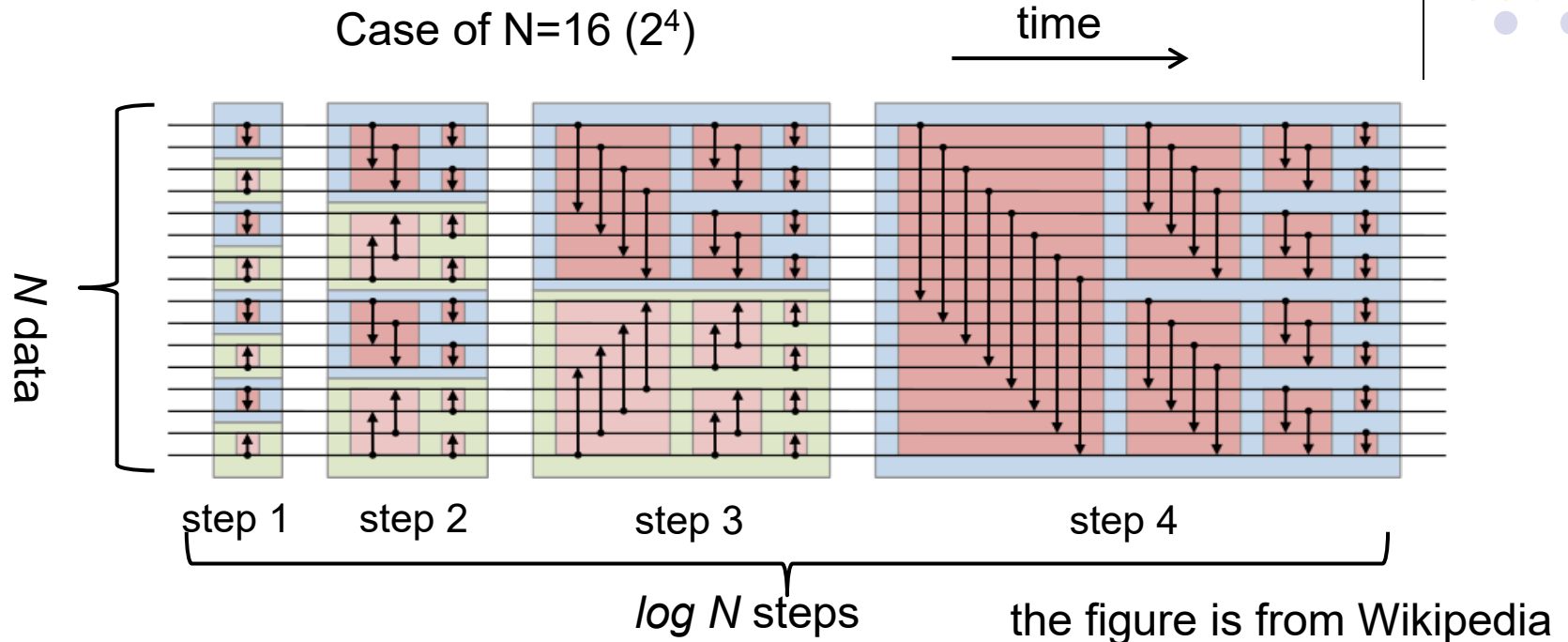
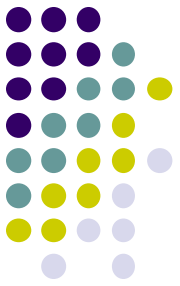
```
}
```

[Data transfer from GPU to CPU]

Computation: $O(NX NY nt)$
Transfer: $O(\underline{NX NY nt})$

“bsort” Sample Program

Target of [C2], details are in ppcomp25-4



Base version: [ppcomp-ex/base/bsort/](https://github.com/ppcomp-ex/base/bsort/)

You can use [ppcomp-ex/cuda/bsort/](https://github.com/ppcomp-ex/cuda/bsort/)

```
cd ppcomp-ex/cuda/bsort
module load nvhpc // if not yet
make
./bsort 1000000 // number of elements to be sorted
```



How Can We Parallelize bsort?

- k loops can be parallelized
- i, j loops cannot be parallelized

```
for (i = 1; (1<<i) <= N2; i++) { // step loop
    for (j = i-1; j >= 0; j--) { // sub-step loop
        :
        for (k = 0; k < N2; k++) {
            // compare 2 data and swap
        }
    }
}
```

GPU computation must be
a distinct function
(GPU kernel function)

Next, where should the `cudaMemcpy` be?

- Please consider reducing data copy cost

Preparing GPU Kernel Function for bsort

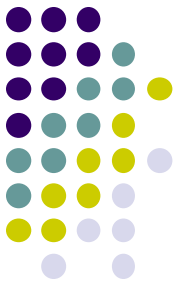


```
__global__ void sort_kernel (...) {  
    int k = blockIdx.x * blockDim.x  
        + threadIdx.x;  
    :  
    // behavior of each thread  
}
```

```
int sort(...) {  
    :  
    for (i = 1 ...) {  
        for (j = i-1 ...) {  
            :  
            sort_kernel<<<....>>>(...)  
            :  
        } ...  
    }
```

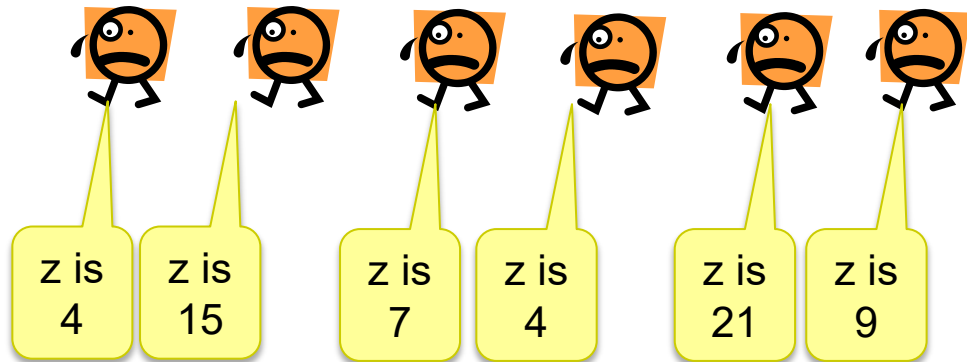


Calling a kernel
function
The total number of
threads should be N^2



Rules for Memory/Variables

- Variables declared in GPU kernel functions are “**thread private**”



- Device memory is **shared** by all CUDA threads
 - Be careful to avoid race condition problem (multiple threads write same address)
 - Reading same address is ok
- Do not forget host memory and device memory are separated



Two Types of GPU Kernel Functions

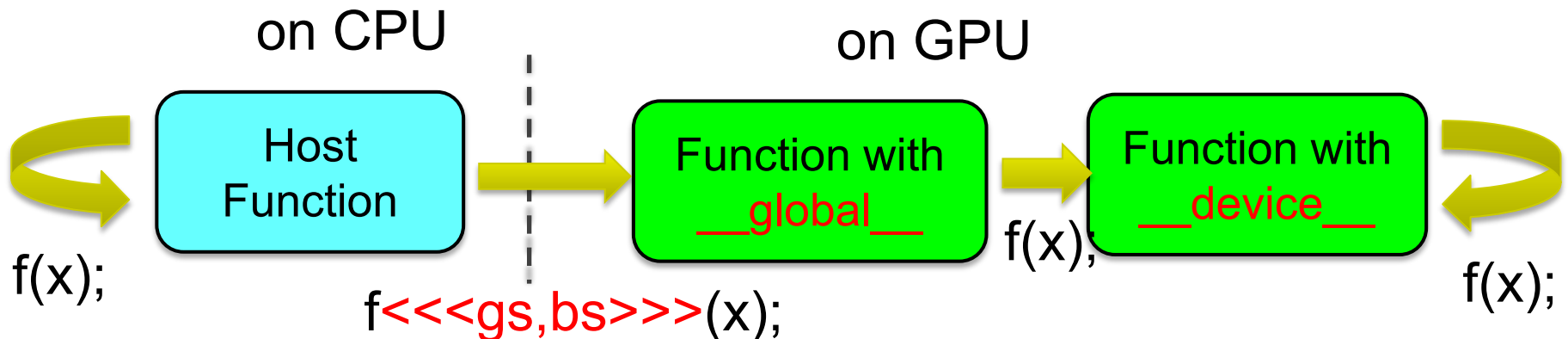
1) Functions with `__global__` keyword

- “Gateway” from CPU
- Return value type must be “void”

2) Function with `__device__` keyword

- Callable only from GPU
- Can have return values
- Recursive call is OK

→ In OpenACC, `#pragma acc routine`



What Can be Done in GPU Functions?



- Basic computations (+, -, *, /, %, &&, ||...) are OK
- if, for, while, return are OK
- Device memory access is OK
- Host memory access is NG
- Calling host functions is NG
- Calling most of functions in libc or other libraries for CPUs are NG
 - Several mathematical functions, sin(), sqrt()... are OK
 - printf() is OK
 - Calling malloc()/free() on GPU is OK, if the size must be small
 - Usually, use cudaMalloc() on CPU



Assignments in CUDA Part

Choose one of [C1]—[C4], and submit a report

Due date: May 26 (Monday)

[C1] Parallelize “diffusion” sample program by CUDA

[C2] Parallelize “bsort” sample program by CUDA

[C3] Evaluate speed of “acc/mm” sample in detail

[C4] (Freestyle) Parallelize *any* program by CUDA

For more details, please see [ppcomp25-9](#) slides



Plan of CUDA Part

- Class #9
 - Introduction to CUDA, kernel functions
- Class #10 (Today)
 - Characteristics of grid, thread blocks, threads
- Class #11
 - Performance improvement on GPU

NOTICE:

- Due date for OpenACC report is changed from May 12 to May 15
 - Machine trouble on TSUBAME interactive nodes happens

