

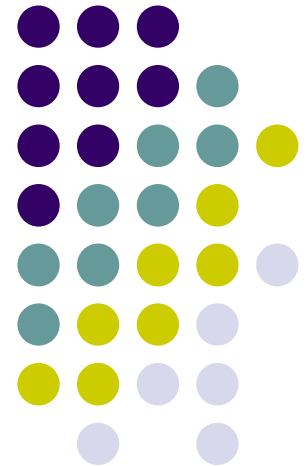
Practical Parallel Computing (実践的並列コンピューティング)

2025 Class No.14
[MPI Part] (3)

Non-Blocking Communication,
Collective Communication

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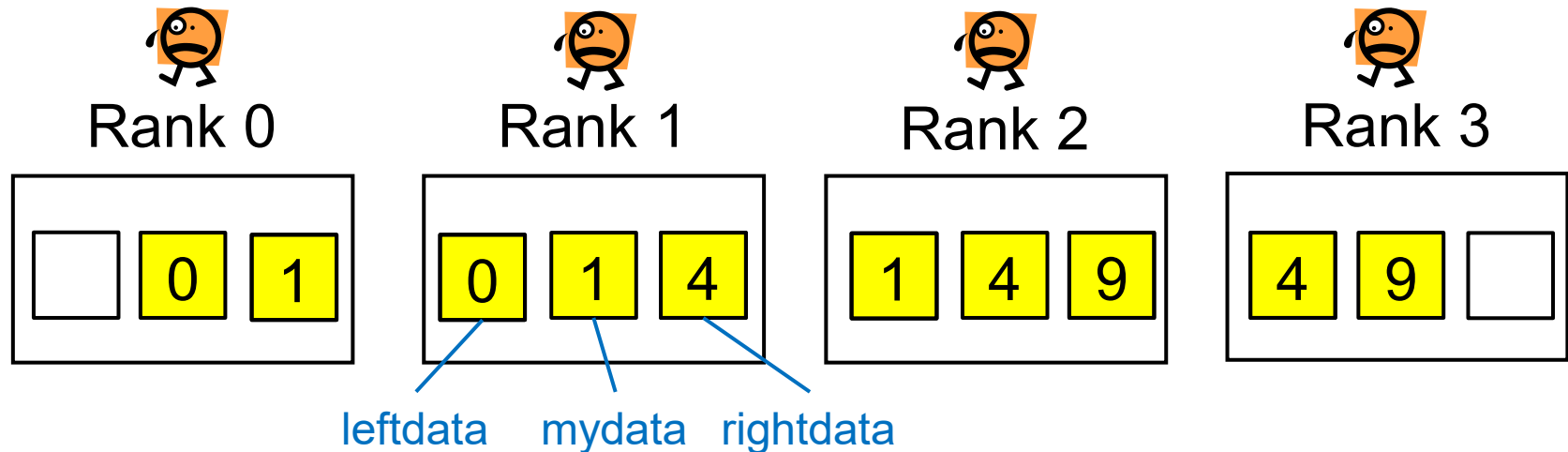
Overview of This Course

- Introduction Part
 - 2 classes
 - OpenMP (OMP) Part
 - 4 classes
 - Report (required)
 - OpenACC (ACC) Part
 - 2 classes
 - Report (required)
 - CUDA Part
 - 3 classes
 - Report (elective)
 - MPI Part
 - 3 classes
 - Report (elective)
- ← We are here (3/3)

Review: Mutual Communication May Cause Deadlock Problem (related to [M1])



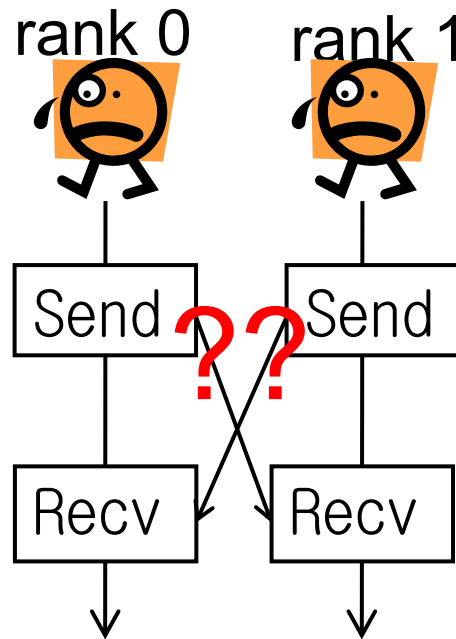
- In neicomm sample, the program does not finish under some conditions → Why?





Deadlock in MPI

- With “`neicomm_unsafe()`”, it “deadlocks” with 2 processes. Why?



One of reasons is usual **MPI_Send** and **MPI_Recv** uses “**blocking communication**”

- a process waits until “some event”



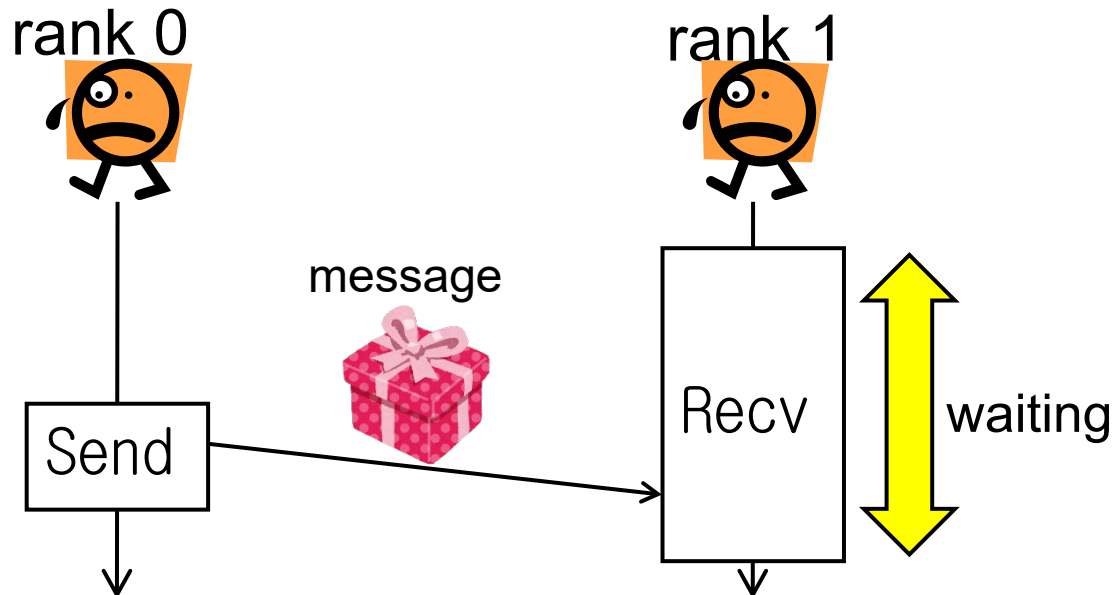
Behavior of MPI_Recv()

Example:

- MPI_Send is called by rank0, and MPI_Recv is called on rank1
 - Processes are running independently

If MPI_Recv is called earlier,

→ MPI_Recv() waits until the message arrives (**blocking**)

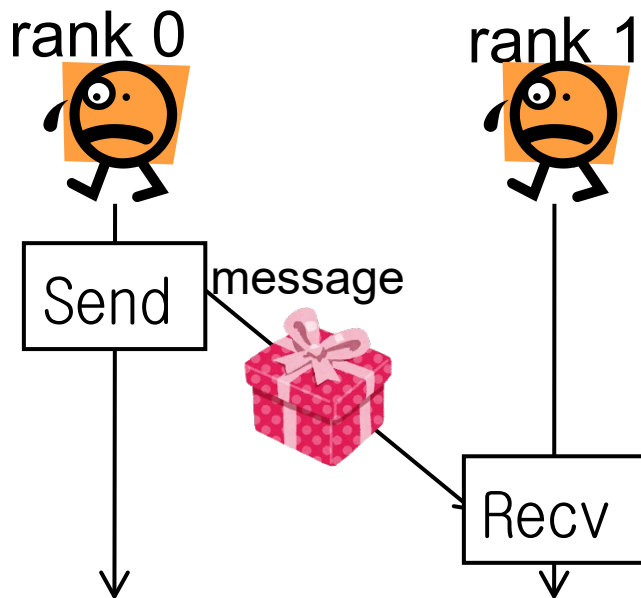




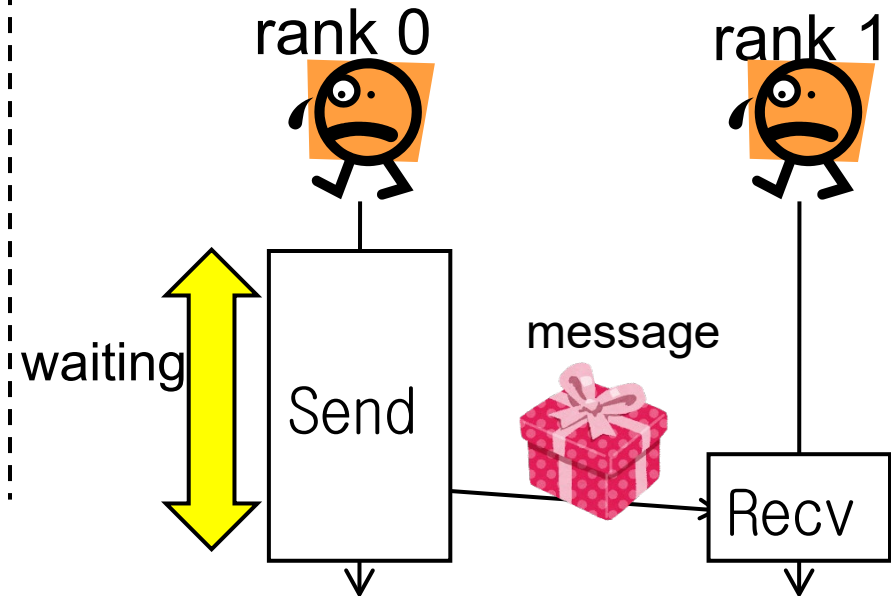
Behavior of MPI_Send()

If MPI_Send is called earlier, there are two possibilities

(case 1) MPI_Send() finishes soon (**non-blocking**)



(case 2) MPI_Send() waits until the message arrives to destination (**blocking**)



Which occurs?

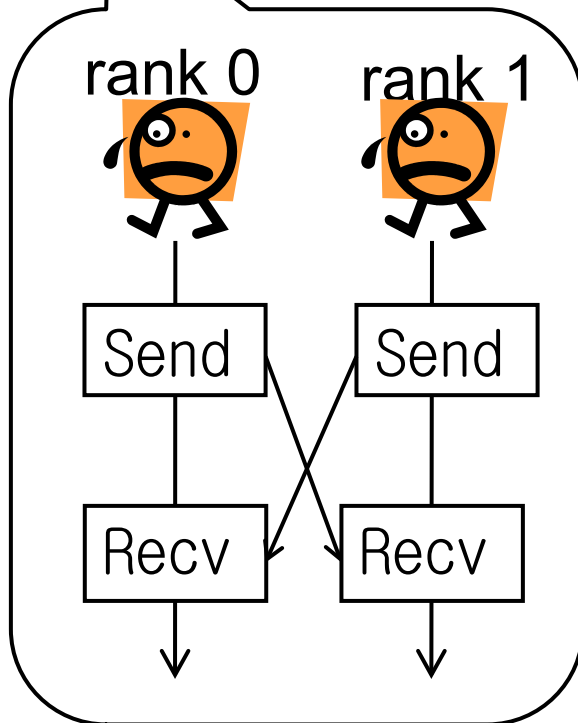
It depends on MPI library, message size, etc. → **Unknown**



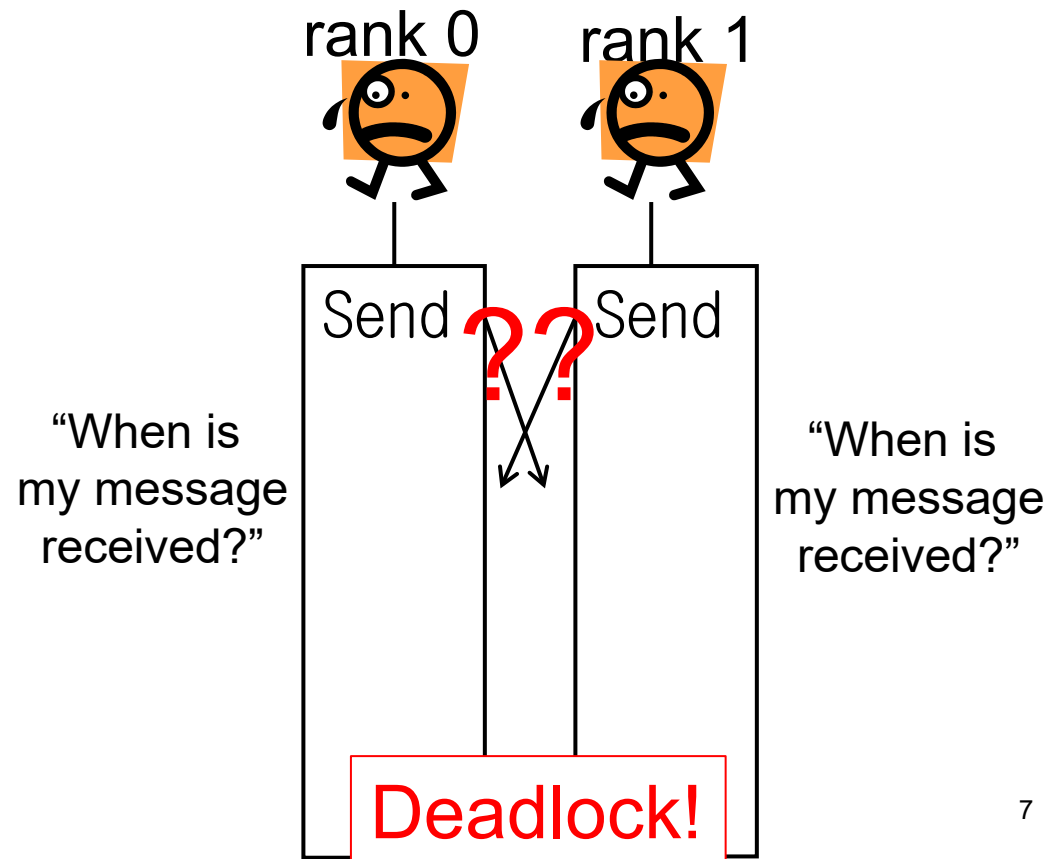
And Deadlock Happens



? Programmer's expectation



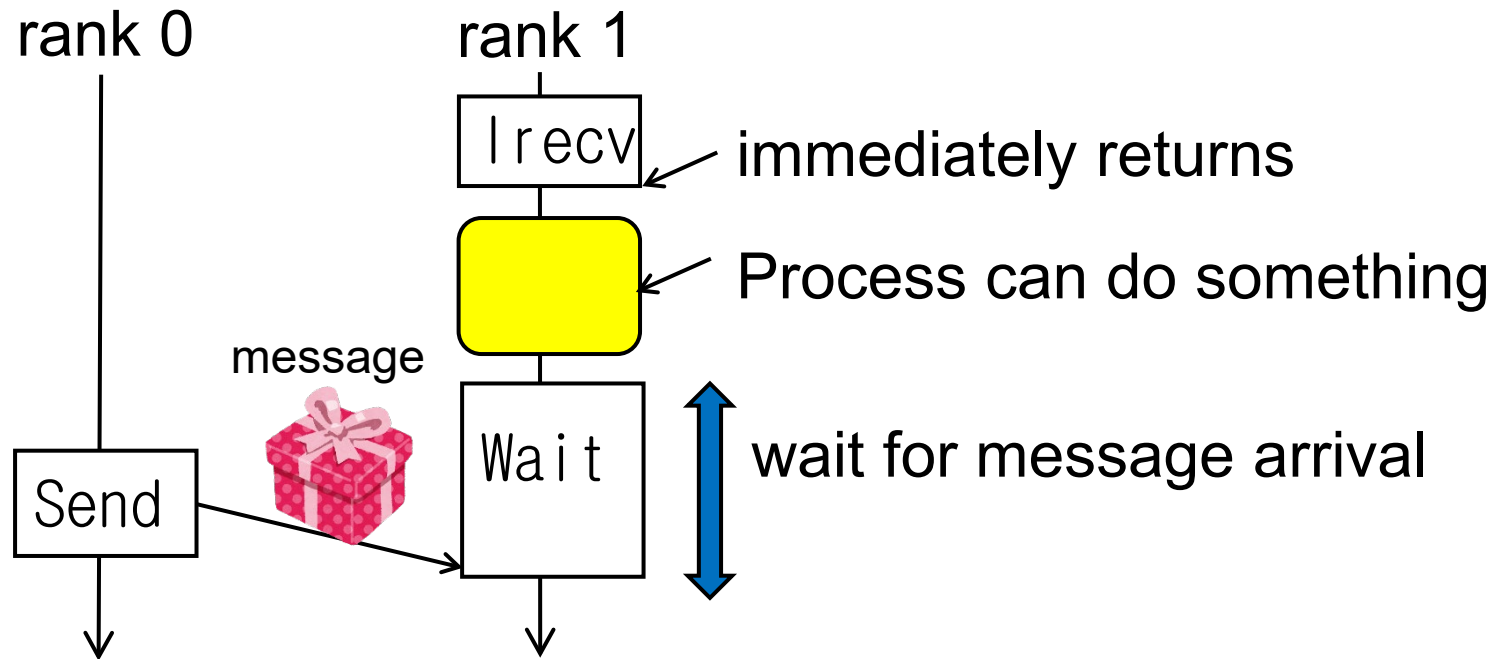
If MPI_Send is blocked until arrival in destination ...



Introduction of Non-Blocking Communication



- **Non-blocking communication**: starts a communication (send or receive), but does **not wait** for its completion
 - MPI_Recv is **blocking communication**, since it waits for message arrival
- Program must wait for its completion later: **MPI_Wait()**





Non-Blocking Receive

```
MPI_Status stat;  
MPI_Recv(buf, n, type, src, tag, comm, &stat);
```



```
MPI_Status stat;  
MPI_Request req;  
MPI_Irecv(buf, n, type, src, tag, comm, &req); ←start recv  
    : (Do something)  
MPI_Wait(&req, &stat); ←wait for completion
```

MPI_Irecv: starts receiving, but it returns **I**mmEDIATELY

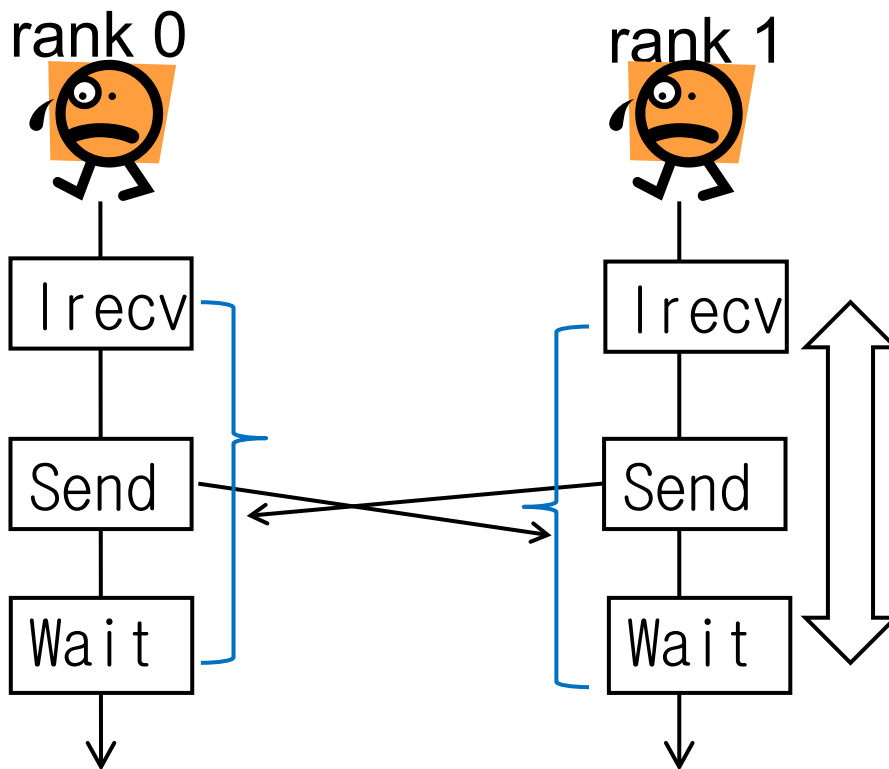
MPI_Wait: wait for message arrival

MPI_Request is like a “ticket” for the communication

Avoiding Deadlock with Non-Blocking Communication



On each process, Recv is divided into Irecv & Wait



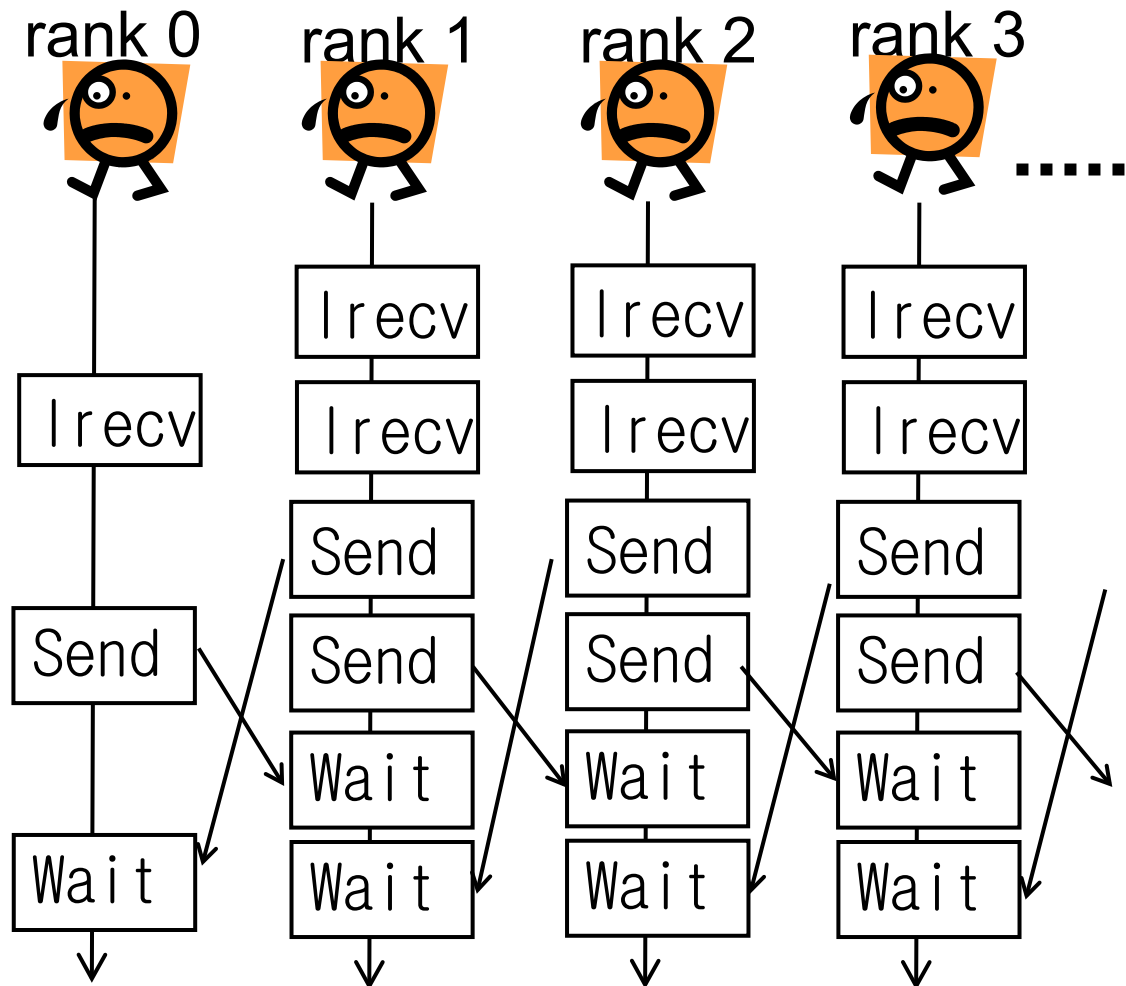
What's difference than before?

A message can be (internally) received during Irecv and Wait
→ MPI_Send can finish in finite time



Cases for Multiple Processes

- See `neicomm_safe()` in `neicomm.c`



Each `Irecv`
has to use
distinct
`MPI_Request`

Functions Related to Non-blocking Communication



- `MPI_Isend(buf, n, type, dest, tag, comm, &req);` ←start send
 - `MPI_Isend` must be followed by `MPI_Wait` (or alternatives)
- `MPI_Wait(&req, &stat);` ←wait for completion of one communication
- `MPI_Test(&req, &flag, &stat);` ←check completion of one communication
- `MPI_Waitall`, `MPI_Waitany`, `MPI_Testall`, `MPI_Testany`...

Avoiding Deadlock with Non-Blocking Communication (2)



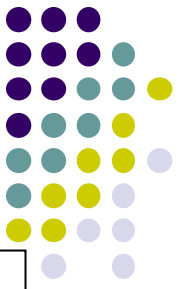
- The following patterns are also Ok
- Each process does
 - Irecv, Irecv, Send, Send, Wait, Wait
 - Use in `neicomm_safe()`
 - Isend, Isend, Recv, Recv, Wait, Wait
 - Isend, Isend, Irecv, Irecv, Wait, Wait, Wait, Wait
 - 4 `MPI_Request` required
 - Irecv, Irecv, Send, Send, Wait, Wait, Wait, Wait
 - 4 `MPI_Request` required

“Send, Send, Irecv, Irecv, Wait, Wait” is NG. Why?

Next topic:

“mm” sample again (related to [M3])

[ppcomp-ex/mpi/mm](#), [ppcomp-ex/mpi/mm-comm](#)

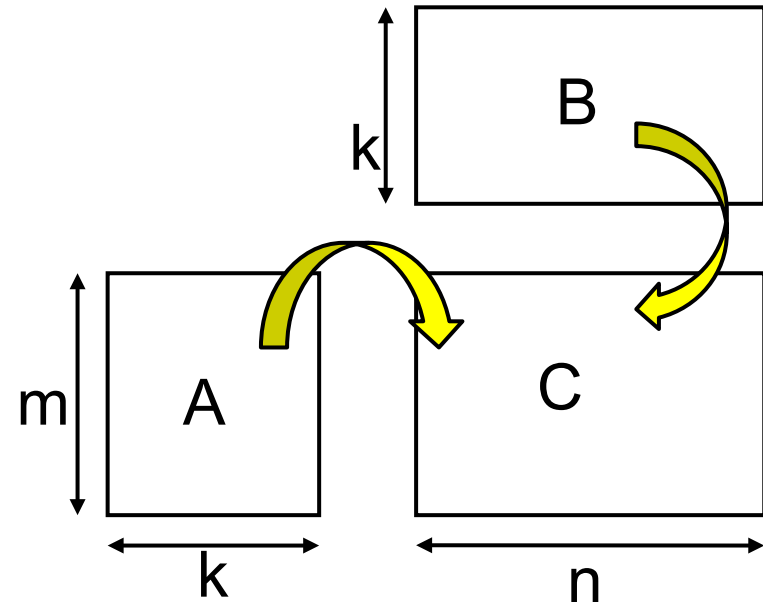


A: a $(m \times k)$ matrix, B: a $(k \times n)$ matrix

C: a $(m \times n)$ matrix

$$C \leftarrow A \times B$$

- Algorithm with a triple for loop
- Supports variable matrix size.
 - Each matrix is expressed as a 1D array by *column-major* format

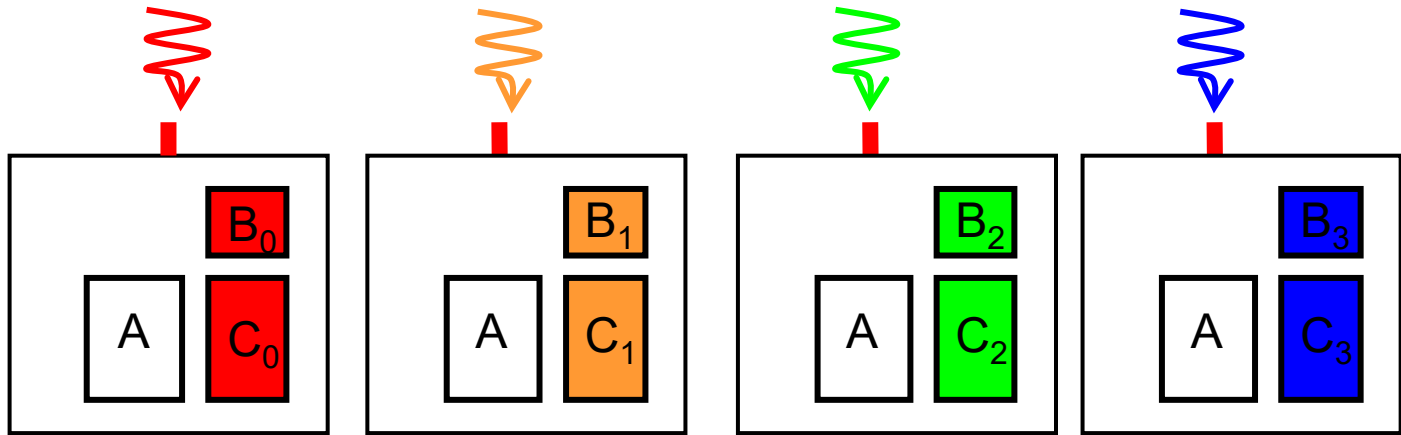


Execution: `mpiexec -n [#proc] ./mm [m] [n] [k]`

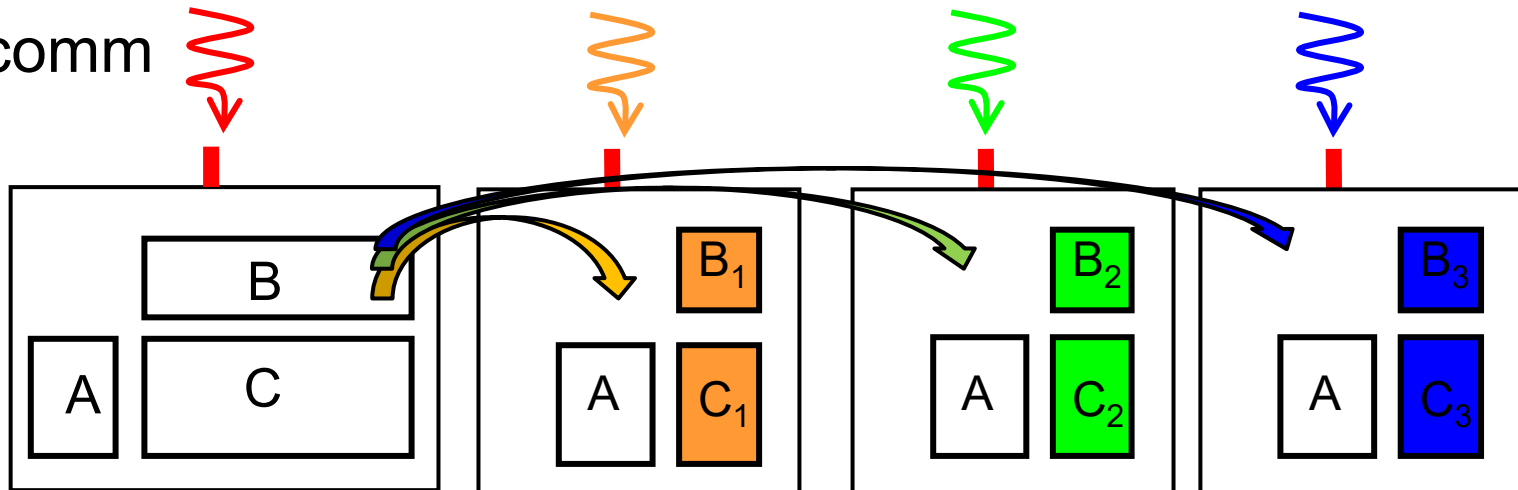


Data Distribution in mm, mm-comm

mm



mm-comm



Introduction of Group Communication

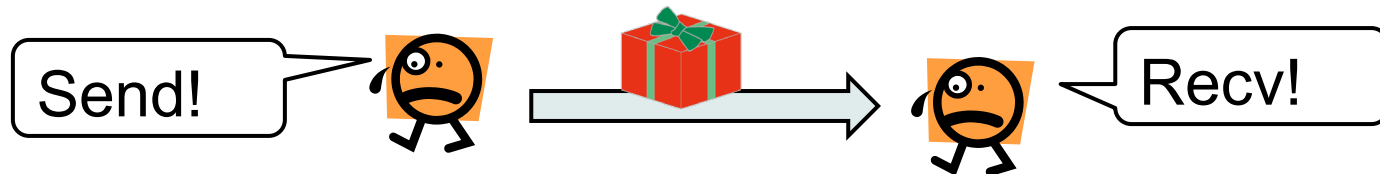


- mm-comm does communication:
 - Matrix A is sent from rank 0 to others
 - Matrix B/C are split and sent from rank 0 to others
 - Partial Cs are sent from other processes to rank 0
 - In mm-comm, all are written by combination of MPI_Send/MPI_Recv
 - MPI have specialized functions for above purposes
- ➔ **Collective communication functions**

Peer-to-peer Communications vs Collective Communications



- Communications we have learned are called **peer-to-peer communications**
- A process sends a message. A process receives it



※ `MPI_Irecv`, `MPI_Isend` are also peer-to-peer communications

	Blocking	Non-Blocking
Peer-to-Peer	<code>MPI_Send</code> , <code>MPI_Recv...</code>	<code>MPI_Isend</code> , <code>MPI_Irecv...</code>
Collective	<code>MPI_Bcast</code> , <code>MPI_Reduce...</code>	(<code>MPI_Ibcast</code> , <code>MPI_Ireduce...</code>)

Collective Communications (Group Communications)



- **Collective communications** involves many processes
 - MPI provides several collective communication patterns
 - Bcast, Reduce, Gather, Scatter, Barrier...
 - All processes must call the same communication function



→ Something happens for all of them

Several communication patterns:

- `MPI_Bcast`, `MPI_Scatter`, `MPI_Gather`,
`MPI_Reduce`, `MPI_Barrier`...

One of Collective Communications: Broadcast by MPI_Bcast

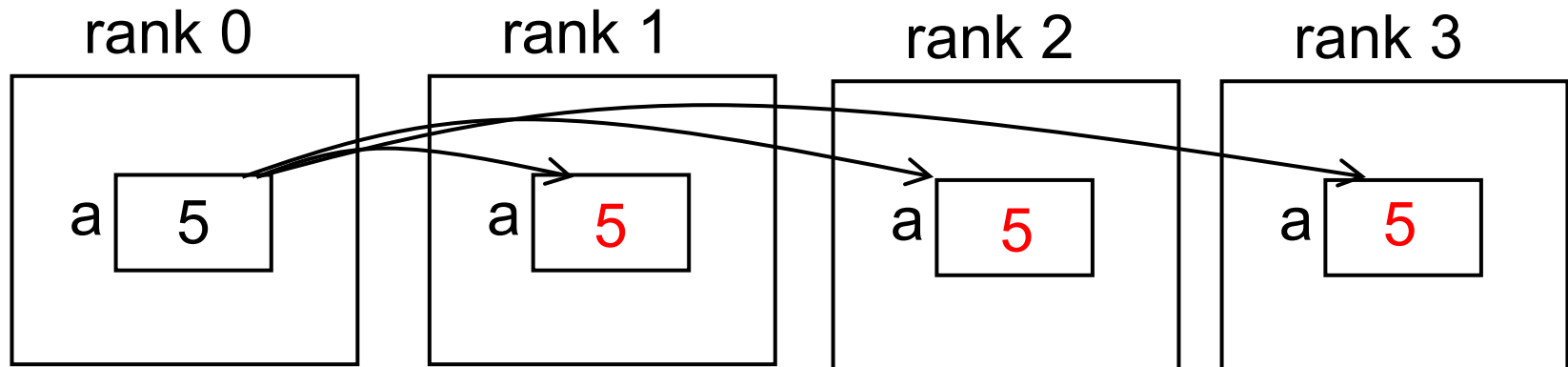


cf) rank 0 has “int a” (called **root process**). We want to send it to all other processes

```
MPI_Bcast(&a, 1, MPI_INT, 0, MPI_COMM_WORLD);
```

- All processes (in the communicator) must call MPI_Bcast(), including rank 0

→ All other process will receive the value on memory region **a**

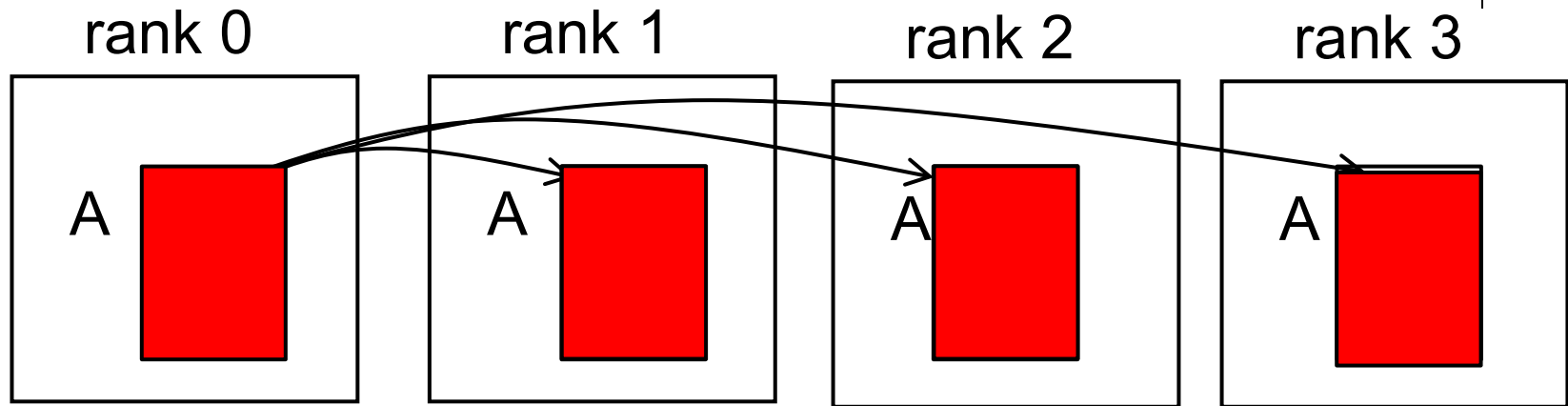


✂ What is the role of 1st argument?

it is “input” on the root process, and “output” on other processes



MPI_Bcast Can Be Used in “Communication of A” in mm-comm [M3]



- Rank 0 has contents of A
 - All other processes require *all* contents of A
- This is “broadcast” pattern. **We can use MPI_Bcast instead!**
Root 0 becomes rank

Communication of A in comm1() in mm_comm can be modified

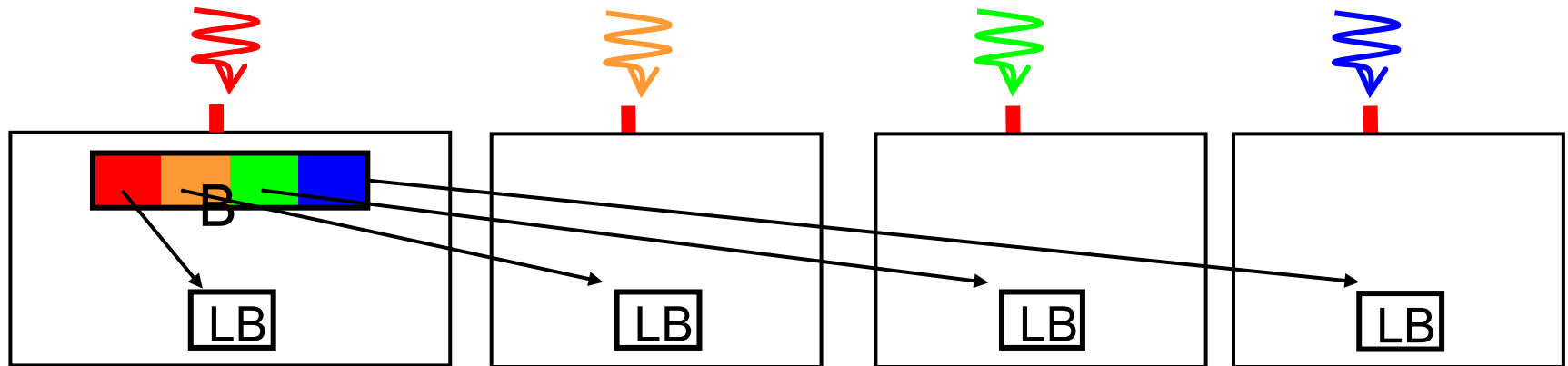
```
MPI_Bcast(A, m*k, MPI_DOUBLE, 0, MPI_COMM_WORLD);
```

root



Another Pattern: MPI_Scatter

- In mm-comm, we do not want to broadcast B/C
- Instead, we want to distribute partial B/Cs → **MPI_Scatter**



send data send count, # of data per process

```
MPI_Scatter(B, k*n/nprocs, MPI_DOUBLE, LB, k*n/nprocs, MPI_DOUBLE, 0, MPI_COMM_WORLD);
```

recv data

sender (root) information.
valid only in root

receiver information

root



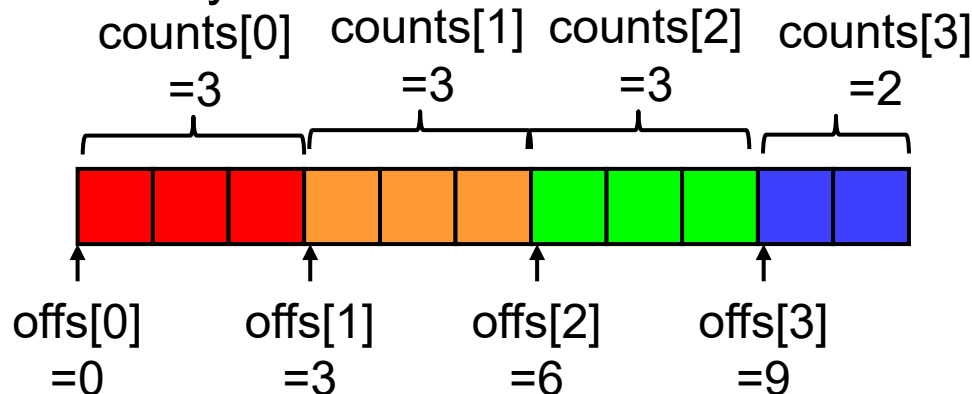
Non-uniform Scatter

- MPI_Scatter only supports uniform division
- If n (width of B) is indivisible by nprocs, each process may take non-uniform counts of data
- MPI_Scatterv would be useful

```
MPI_Scatterv(B, counts, offs, MPI_DOUBLE,  
             LB, (e-s), MPI_DOUBLE,  
             0, MPI_COMM_WORLD);
```

counts: arrays that have data counts for each process

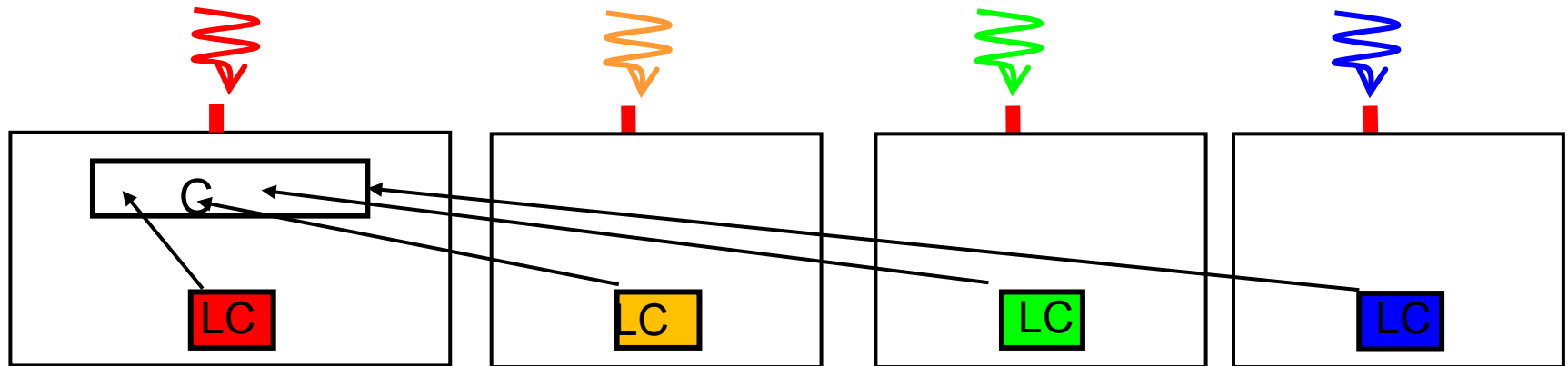
offs: arrays that have start offset





Next Pattern: MPI_Gather

- After computation, we want to gather partial Cs on process 0
- MPI_Gather/MPI_Gatherv may be used



send data send count, # of data per process

```
MPI_Gather(LC, k*n/nprocs, MPI_DOUBLE, C, k*n/nprocs, MPI_DOUBLE, 0, MPI_COMM_WORLD);
```

recv data

sender information

receiver (root) information
valid only in root

root



Non-uniform Gather

- MPI_Gather gathers data from each process uniformly
- MPI_Gatherv can gather data of uniform sizes

```
MPI_Gatherv(LC, (e-s), MPI_DOUBLE,  
            C, counts, offs, MPI_DOUBLE,  
            0, MPI_COMM_WORLD);
```

} sender information

} receiver (root) information
valid only in root

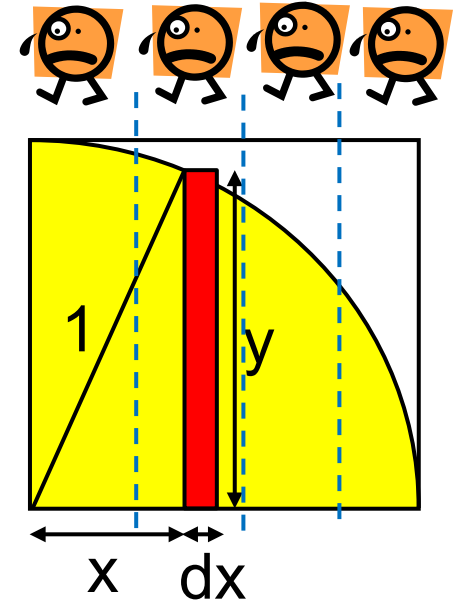
Meanings of **counts** and **offs** arrays are similar to MPI_scatterv

Next Pattern: MPI_Reduce with “mpi/pi” Sample



ppcomp-ex/mpi/pi/

- Execution: `mpiexec -n [#procs] ./pi [n]`
 - n: Number of division
 - Cf) `./pi 100000000`
- We divide n tasks among processes and calculate total yellow area
 1. Each process calculates local sum
 2. Rank 0 obtains the final sum by **MPI_Reduce**



$$dx = 1/n$$
$$y = \sqrt{1-x^2}$$



Using pi-mpi sample

- `ppcomp-ex/mpi/pi`

[make sure that you are at a interactive node (r7i7nX)]

`module load intel-mpi` *[Do once after login]*

[please go to your ppcomp-ex directory]


`cd mpi/pi`

`make`

[An executable file “pi” is created]

`mpiexec -n 4 ./pi 1000000000`

Number of division





Reduction Operation by MPI_Reduce

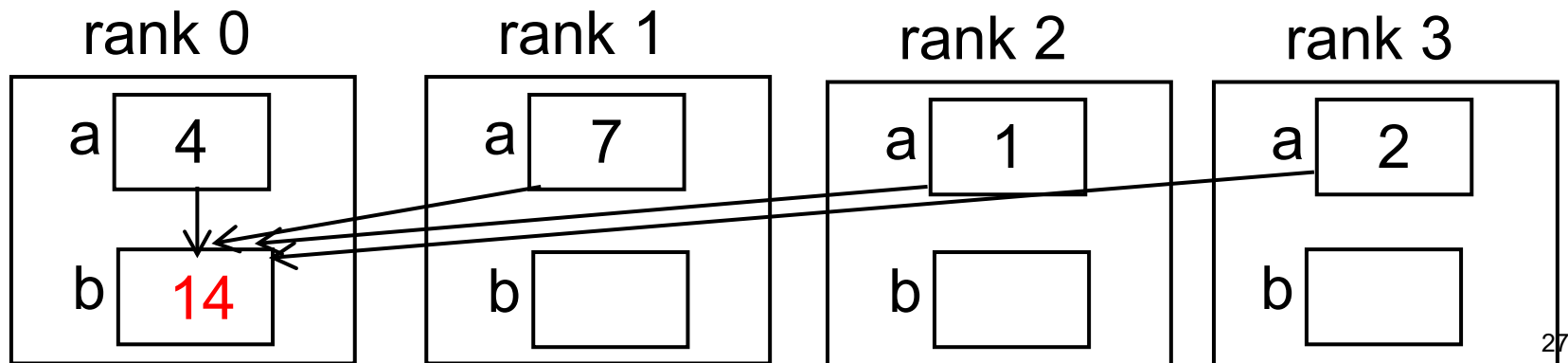
cf) Every process has “int a”. We want the sum of them

```
MPI_Reduce(&a, &b, 1, MPI_INT, MPI_SUM, 0,  
           MPI_COMM_WORLD);
```

operation

root process

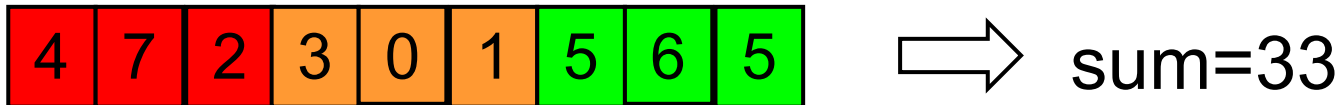
- Every process must call MPI_Reduce()
→ The sum is put on **b** on root process (rank 0 now)
- Operation is one of MPI_SUM, MPI_PROD(product), MPI_MAX, MPI_MIN, MPI_LAND (logical and), etc.



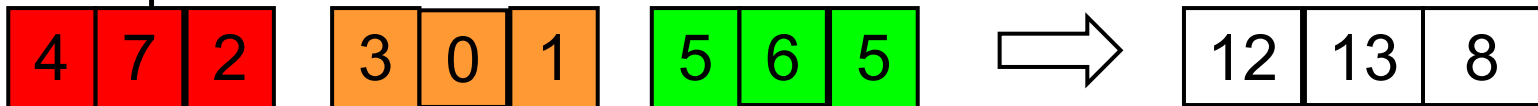
Note: Differences with “omp for reduction” in OpenMP



- Syntaxes are completely different
- Computations are also different
 - `#pragma omp for reduction(...)` in OpenMP
 - Do “`sum += a[i]`” in parallel for loop with `reduction(+:sum)`



- `MPI_Reduce(...)` in MPI
 - If each input is an array, output is also an array
 - Operations are done for each index



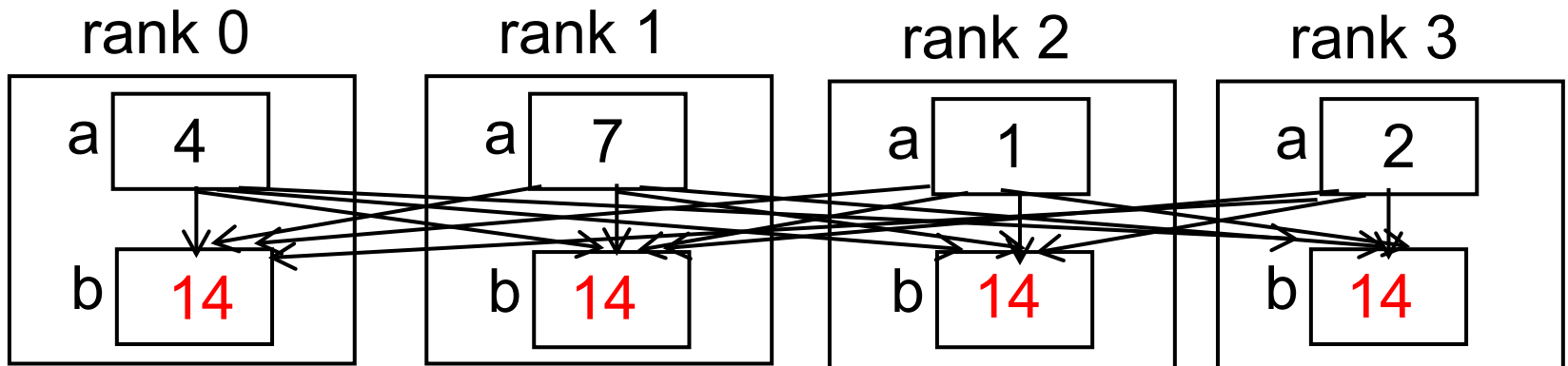


MPI_Allreduce

- Allreduce = Reduction + Bcast

```
MPI_Allreduce(&a, &b, 1, MPI_INT, MPI_SUM,  
              MPI_COMM_WORLD);
```

- The sum is put on **b** on all processes



Important communication pattern for distributed deep learning → Try Google “allreduce deep learning”



MPI_Barrier

- **Barrier synchronization:** processes are stopped until all processes reach the point
`MPI_Barrier(MPI_COMM_WORLD);`
 - Used in sample programs, to measure execution time more precisely

Other Collective Communications

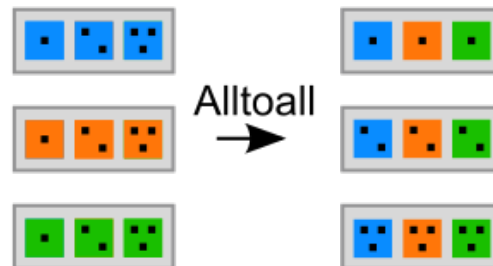


- MPI_Allgather, MPI_Allgatherv
 - Similar to MPI_Gather. Gathered data are put on all processes



from Wikipedia

- MPI_Alltoall, MPI_Alltoallv
 - Each process has data. Each of them are scattered

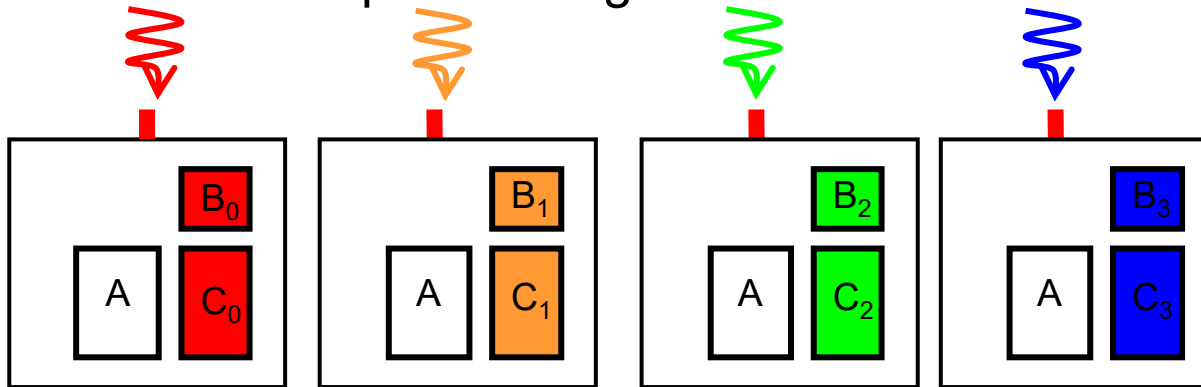


[Advanced Topic]

Re-considering Data Distribution of mm (Option of [M3])



- Consider memory consumption cost:
 - In **mm**, every process has whole matrix A → memory consumption is larger ☹



Memory amount
of each process:
 $O(\textcolor{red}{mk} + km/\textcolor{blue}{p} + mn/\textcolor{blue}{p})$

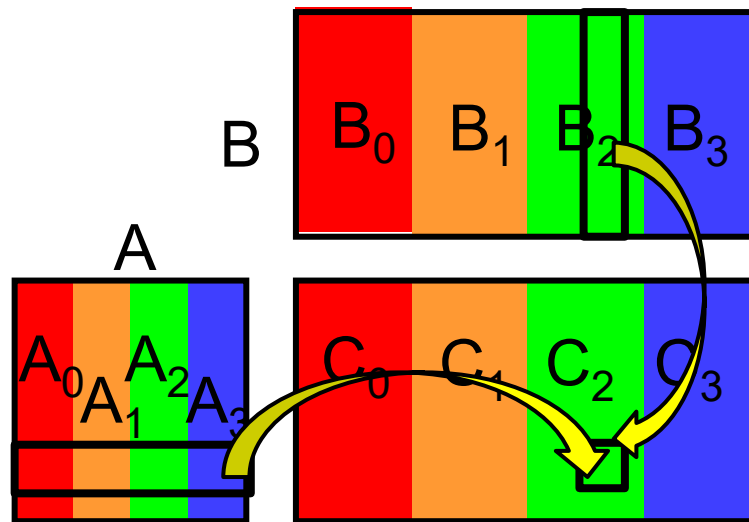
Each process has
whole A

- Even **mm-comm** has the same problem
- Can we reduce memory consumption?
 - The ideal case would be $O(mk/\textcolor{blue}{p} + km/\textcolor{blue}{p} + mn/\textcolor{blue}{p})$



Data Distribution of Memory Reduced “mm”

- Not only B and C, but A is divided among all processes
(In this example, column-wise)



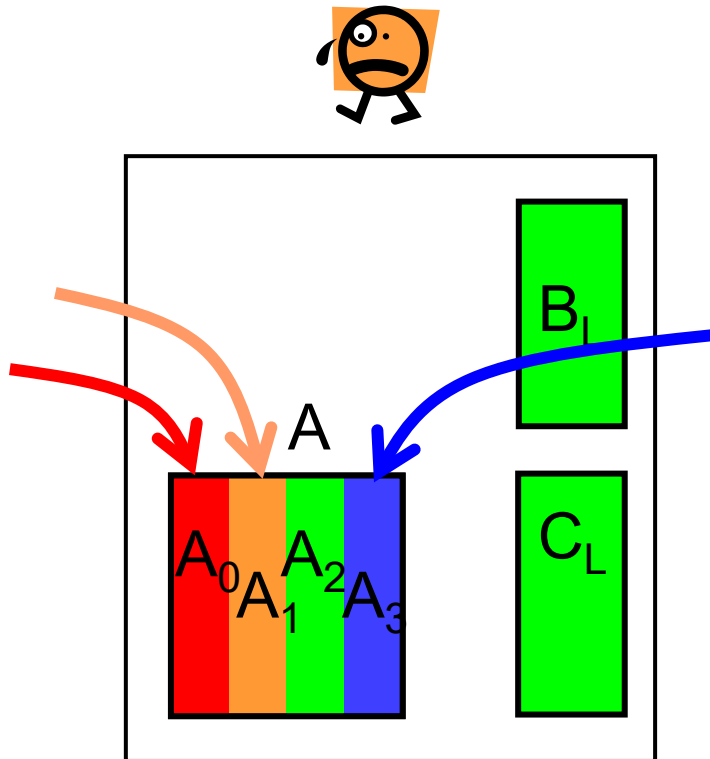
Memory consumption is smallest

- But computing each C element requires data on other processes → We need **communication** !

How We Proceed Computation with Others' Data



- The following algorithm is not good for memory consumption

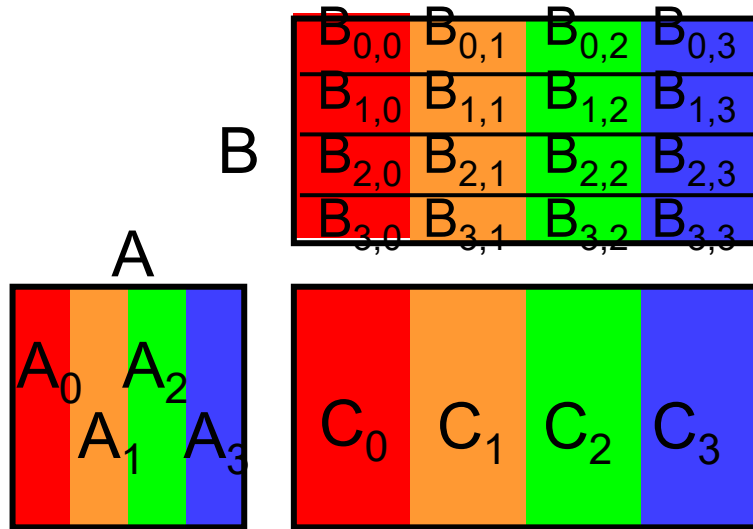


1. Collect entire A from other processes by communication
 2. Compute $C_L = A \times B_L$
- Each process has (entire) A , B_L , C_L → Same as mm ☹️

We should avoid computation of $C_L = A \times B_L$ at once



Algorithm of Memory Reduced “mm”



If we have A only partially,
we can only do $C_L = A \times B_L$
partially

Algorithm

Step 0:

P_0 sends A_0 to all other processes
Every process P_r computes

$$C_r += A_0 \times B_{0,r}$$

Step 1:

P_1 sends A_1 to all other processes
Every process P_r computes

$$C_r += A_1 \times B_{1,r}$$

:

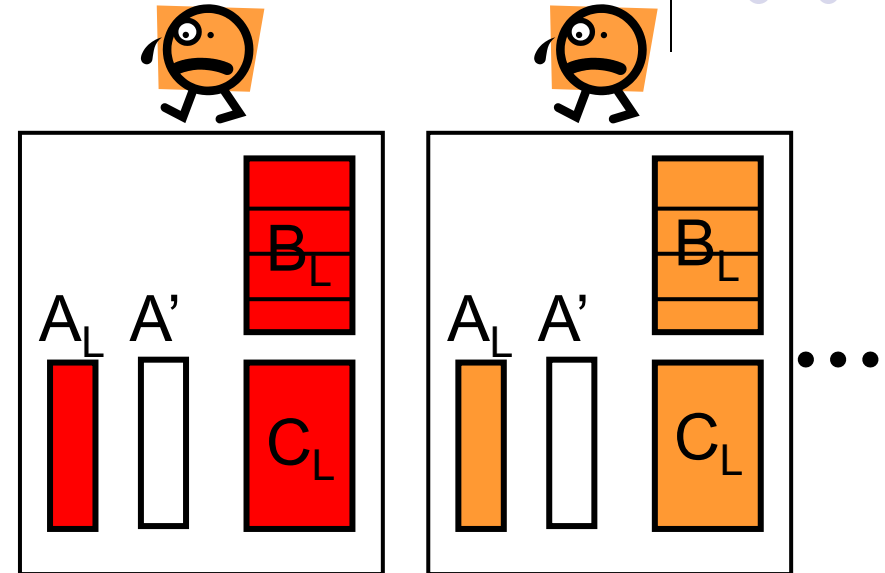
Repeat until Step (p-1)

Actual Data Distribution



Every process has partial A, B, C

- A_L on process $r \Leftrightarrow A_r$
- B_L on process $r \Leftrightarrow B_r$
- C_L on process $r \Leftrightarrow C_r$



- Additionally, every process should prepare a receive buffer $\rightarrow A'$ in the figure
 - A' (instead of A_L) is used for arguments of `MPI_Recv()`
 - On receivers, A' is used for computation

[Q] What if a process uses A_L for `MPI_Recv()`'s target ?

Programming

Memory Reduced mm (1)



On every **process** r :

for ($s = 0$; $s < p$; $s++$) { // s : step no, p : number of processes

if ($r == s$) {

for ($dest = 0$; $dest < p$; $dest++$)

if ($dest != r$) MPI_Send(A_L , ..., $dest$, ...);

} else

MPI_Recv(A' , ..., s , ...);

P_s sends its A_L to all other processes

Receives data (P_s 's A_L) and stores it to A'

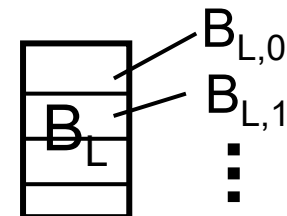
if ($r == s$)

Compute $C_L += A_L \times B_{L,s}$

else

Compute $C_L += A' \times B_{L,s}$

}





Using Collective Communication

- Communication part of the previous code is same as MPI_Bcast pattern!

Note:

1. The different “roots” are used for different steps
2. Sent data is A_L , while received data is A'

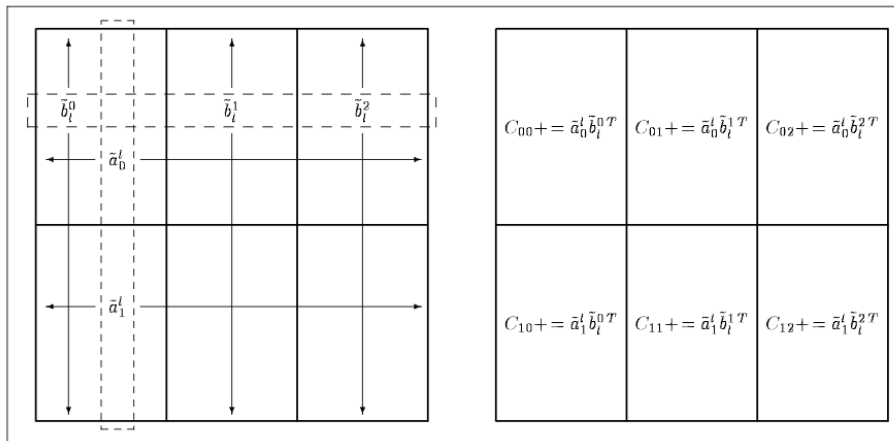
One of solutions:

```
if (r == s) {  
    // on root  
    MPI_Bcast( $A_L$ , ..., s, MPI_COMM_WORLD);  
} else {  
    // on non-root  
    MPI_Bcast( $A'$ , ..., s, MPI_COMM_WORLD);  
}
```

[More Advanced] Improvements of Memory Reduced Version



- To use SUMMA: scalable universal matrix multiplication algorithm
 - See <http://www.netlib.org/lapack/lawnspdf/lawn96.pdf>
 - Replica is eliminated, and matrices are divided in 2D





Performance of Collective Communication



“Do I Really Need to Learn New Functions?”

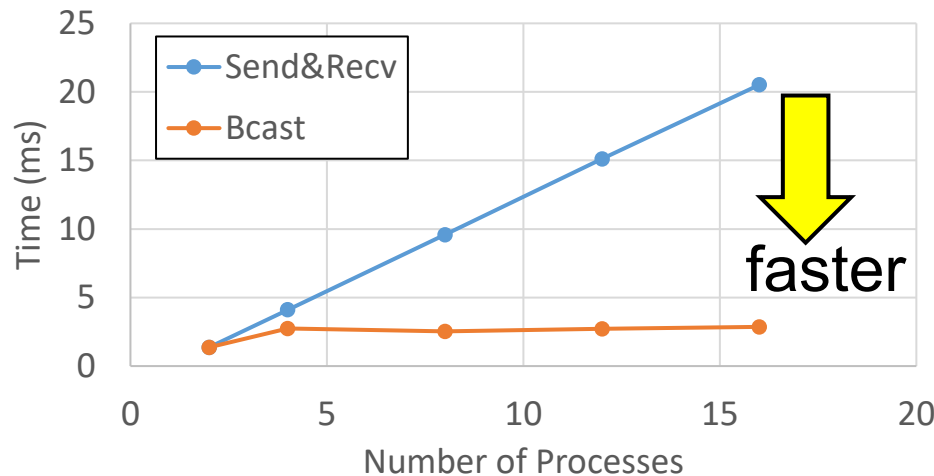


- You can still use MPI_Send/MPI_Recv multiple times, but **collective functions are often faster**

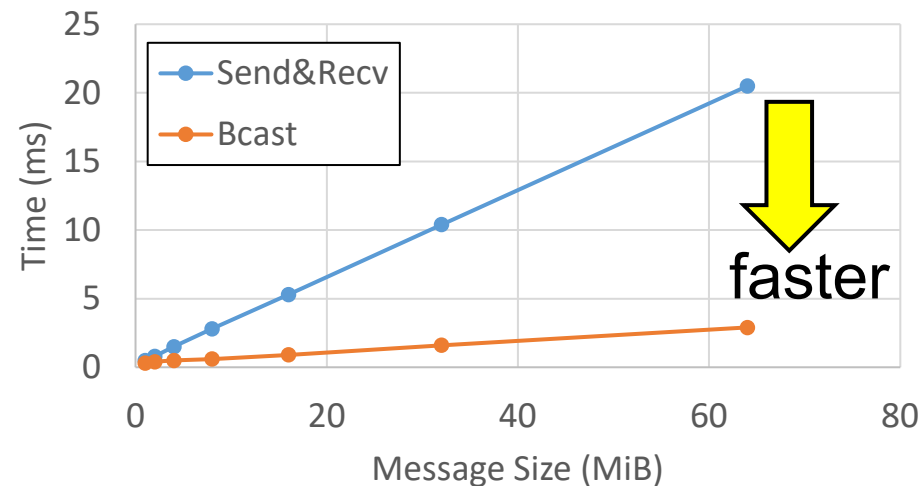
On TSUBAME4
1 proc / node

In the graph, rank 0 called MPI_Send for p-1 times to other processes

64MB message



16 Processes



- MPI_Bcast are faster, especially when p is larger !
- The reason is MPI uses “scalable” communication algorithms:
cf) <http://www.mcs.anl.gov/~thakur/papers/mpi-coll.pdf>



FYI: Measurement Method

- Measurement in the previous page was done with [ppcomp-ex/mpi/mpibcast/](#)
- intel-mpi is used
- NOTE: job*.sh in this directory need to consume TSUBAME points
 - job*.sh use > 2nodes

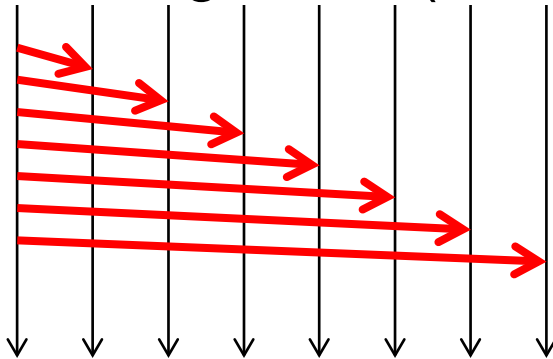
Why are Collective Communications Fast?



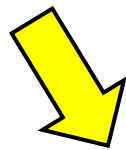
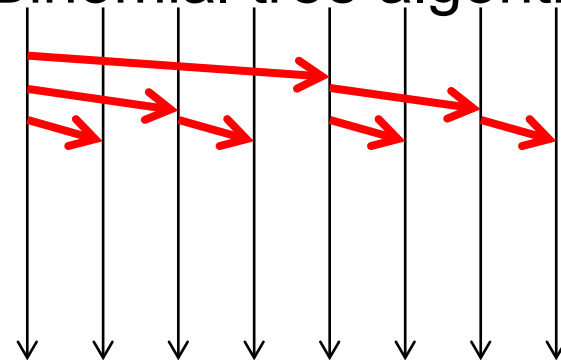
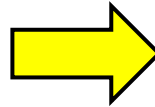
- Since MPI library uses *scalable* communication algorithms

- Case of **broadcast**:

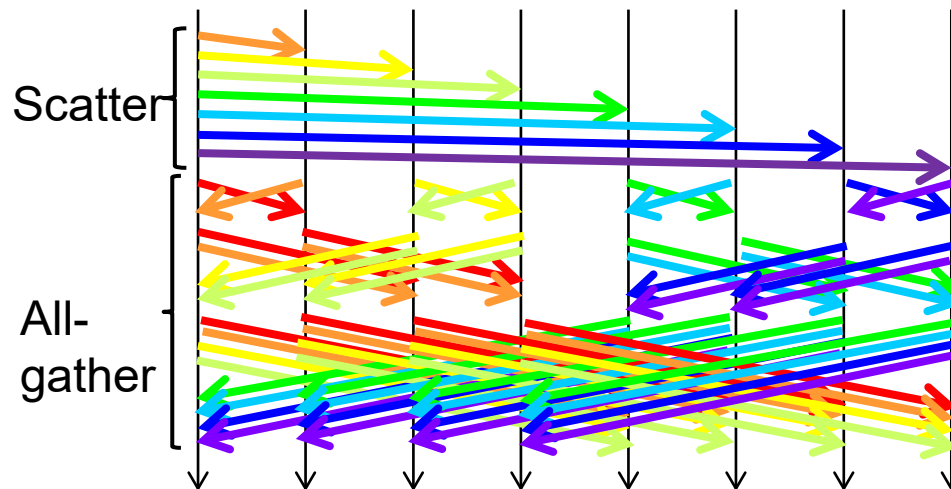
Flat tree algorithm (slow)



Binomial tree algorithm



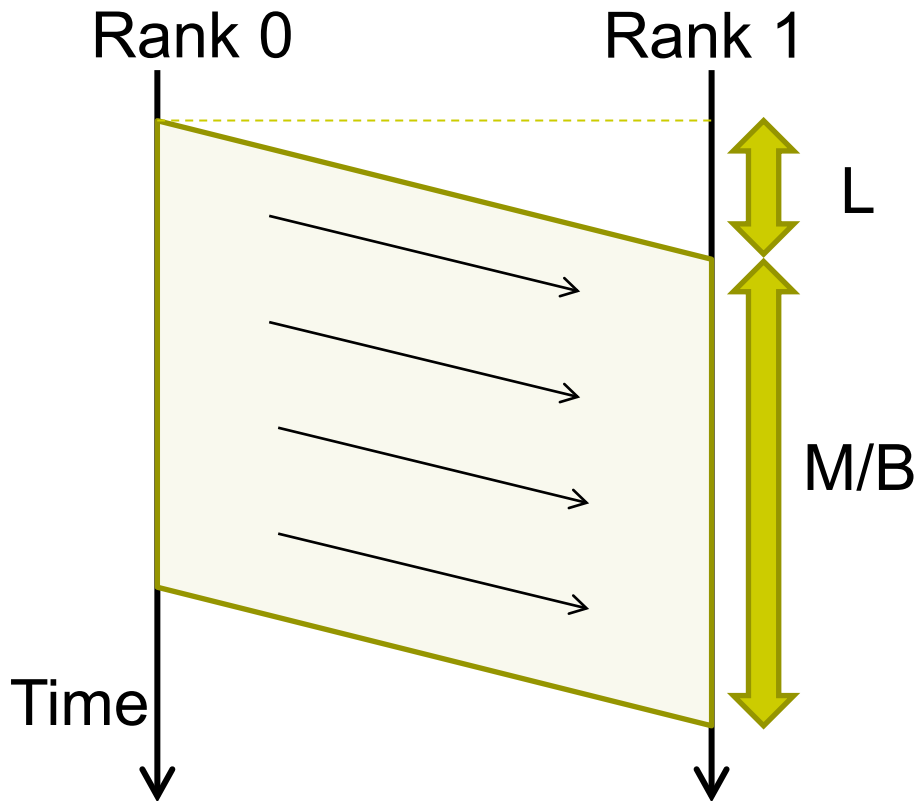
Scatter&Allgather
algorithm



Model of Communication Time



Illustration of peer-to-peer communication of data size M



$$T = M / B + L$$

T : Communication time

M : Data size

B : Bandwidth

L : Network latency

※ Be aware of difference between “Byte” and “bit”: 1Byte=8bit

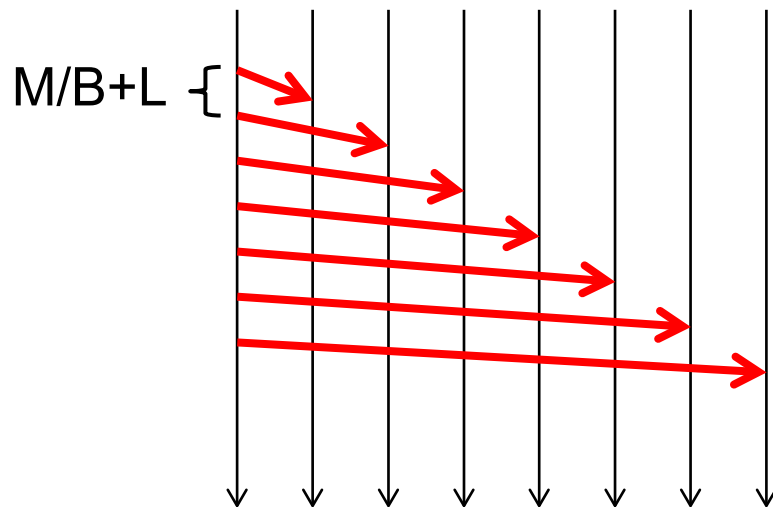
※ Actually it is more complex for process's place, effects of network topology, congestion, packet size...

Cost Model of Broadcast Algorithms



- Case of “broadcast” of size M data
 - p : number of processes, B : network bandwidth, L : network latency

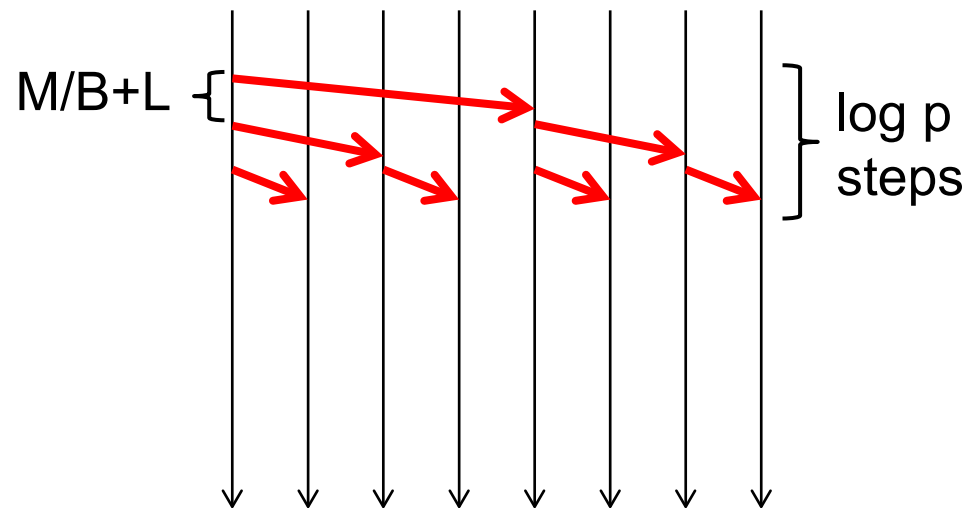
Flat tree algorithm



$$p(M/B+L)$$

→ *Slow*

Binomial tree algorithm



$$(\log p)(M/B+L)$$

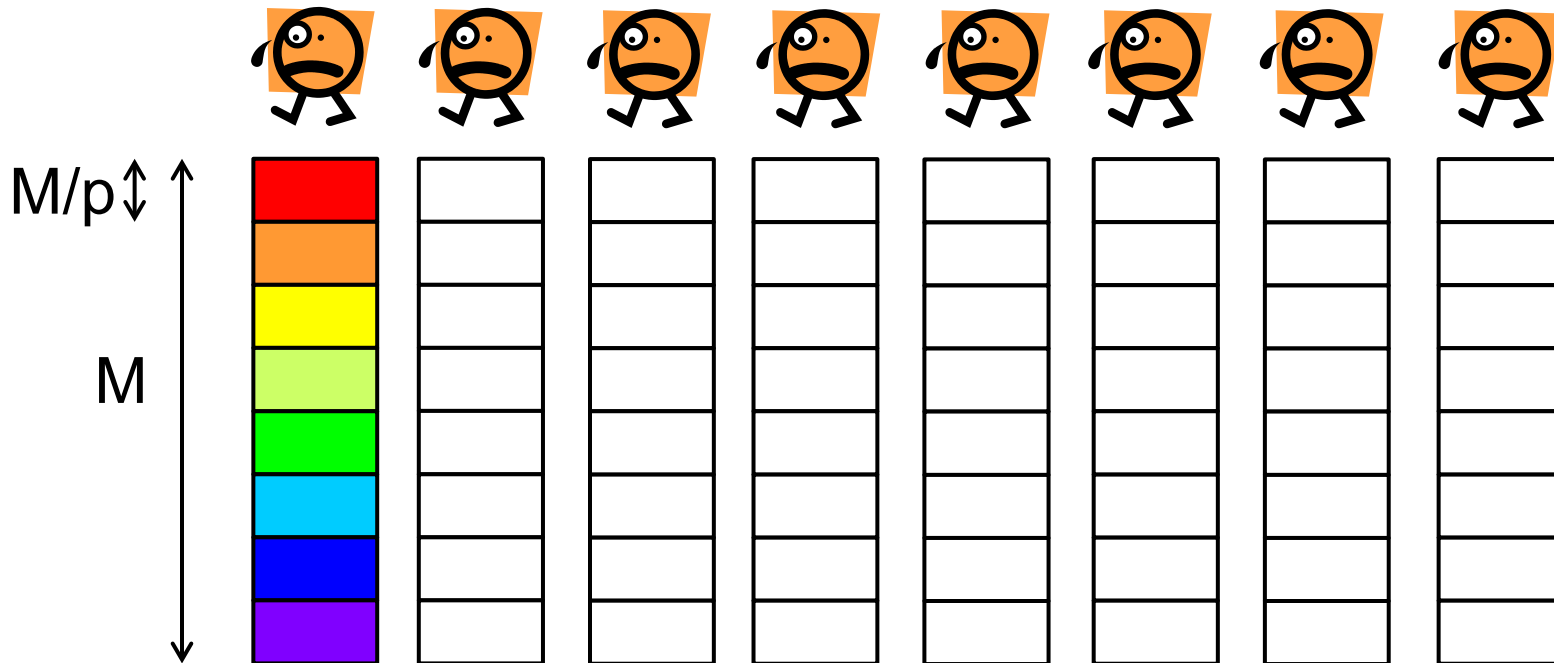
※ difference between $p-1$ and p is ignored

Broadcast by Scatter&Allgather Algorithm (1)



- (1) The root process divide the message into p parts
- (2) Scatter
- (3) Allgather

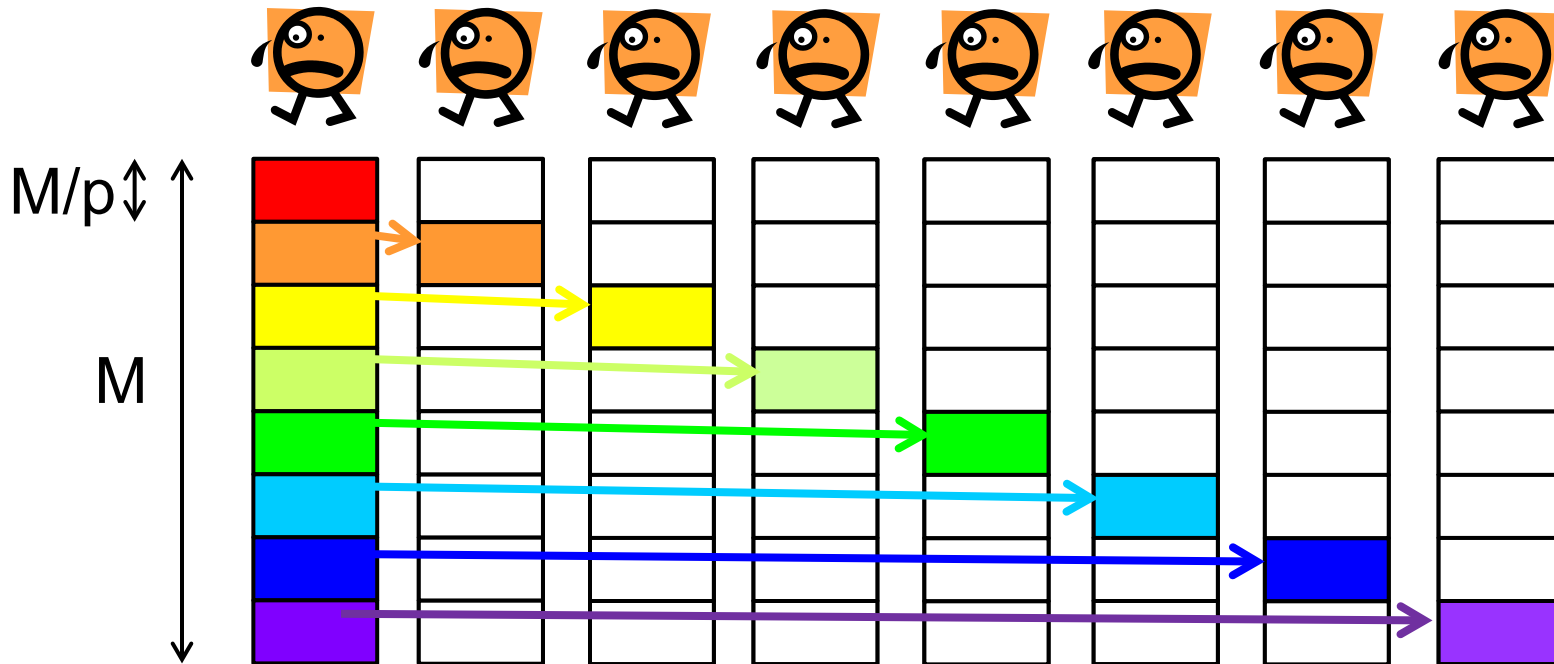
R. Thakur and W. Gropp. Improving the performance of collective operations in mpich. EuroPVM/MPI conference, 2003.



Scatter&Allgather Algorithm (2)



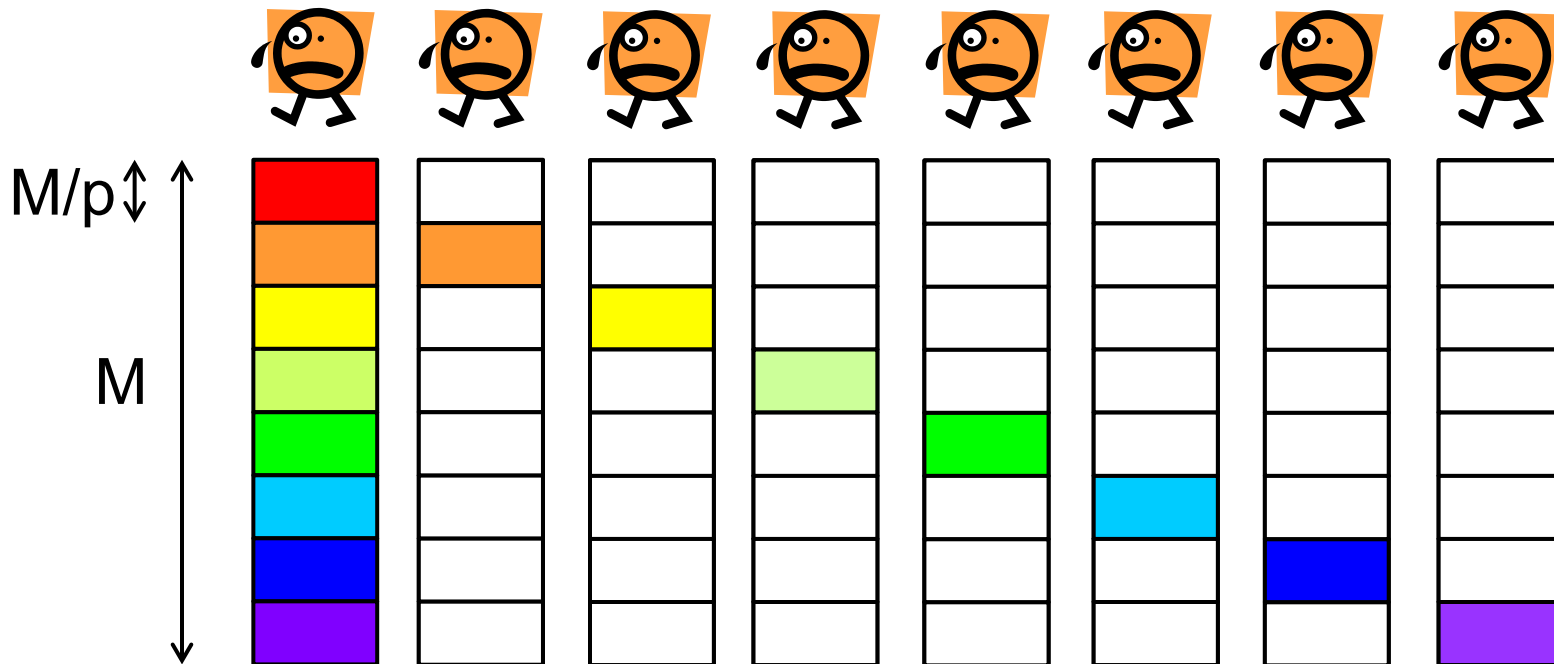
- (1) The root process divide the message into p parts
- (2) Scatter: i -th part goes to process i
- (3) Allgather



Scatter&Allgather Algorithm (3)



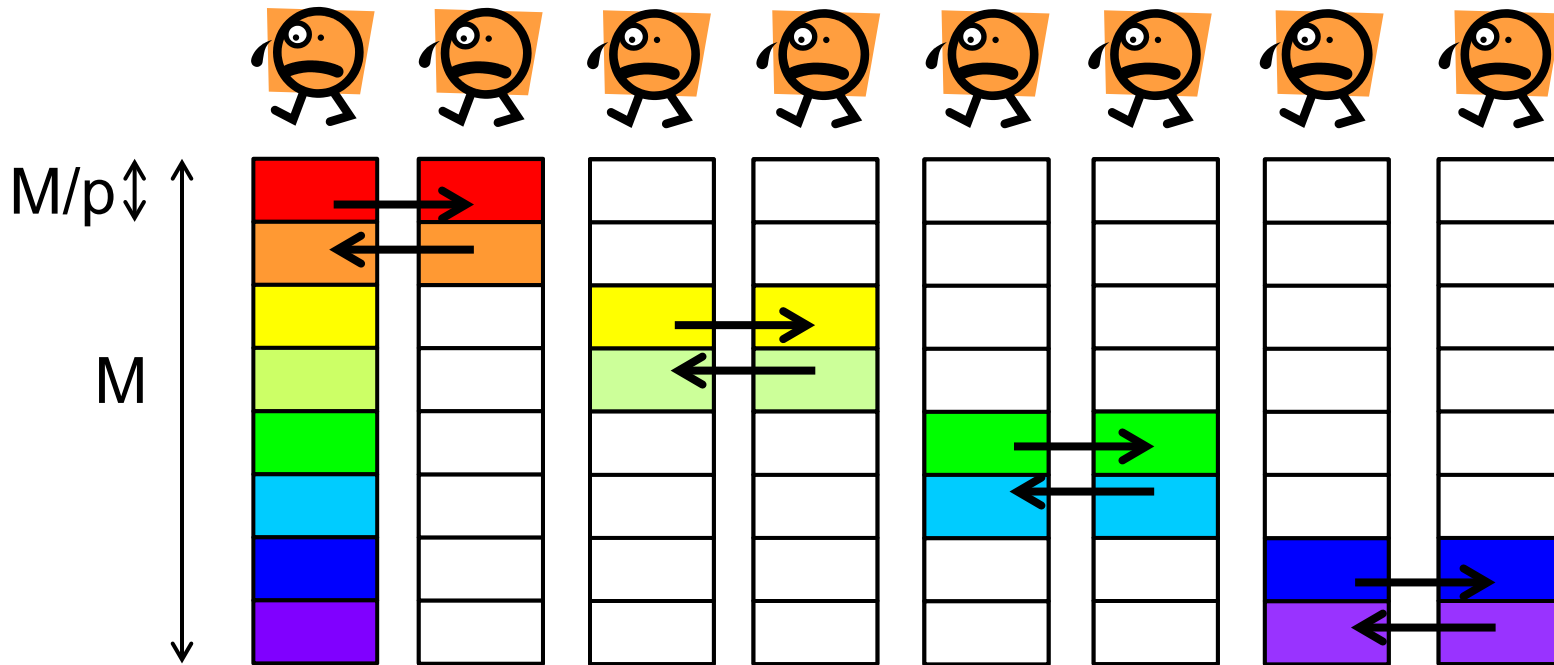
- (1) The root process divide the message into p parts
- (2) Scatter
- (3) Allgather in $\log p$ steps
 - If $p=8$, we use 3 steps



Scatter&Allgather Algorithm (3)



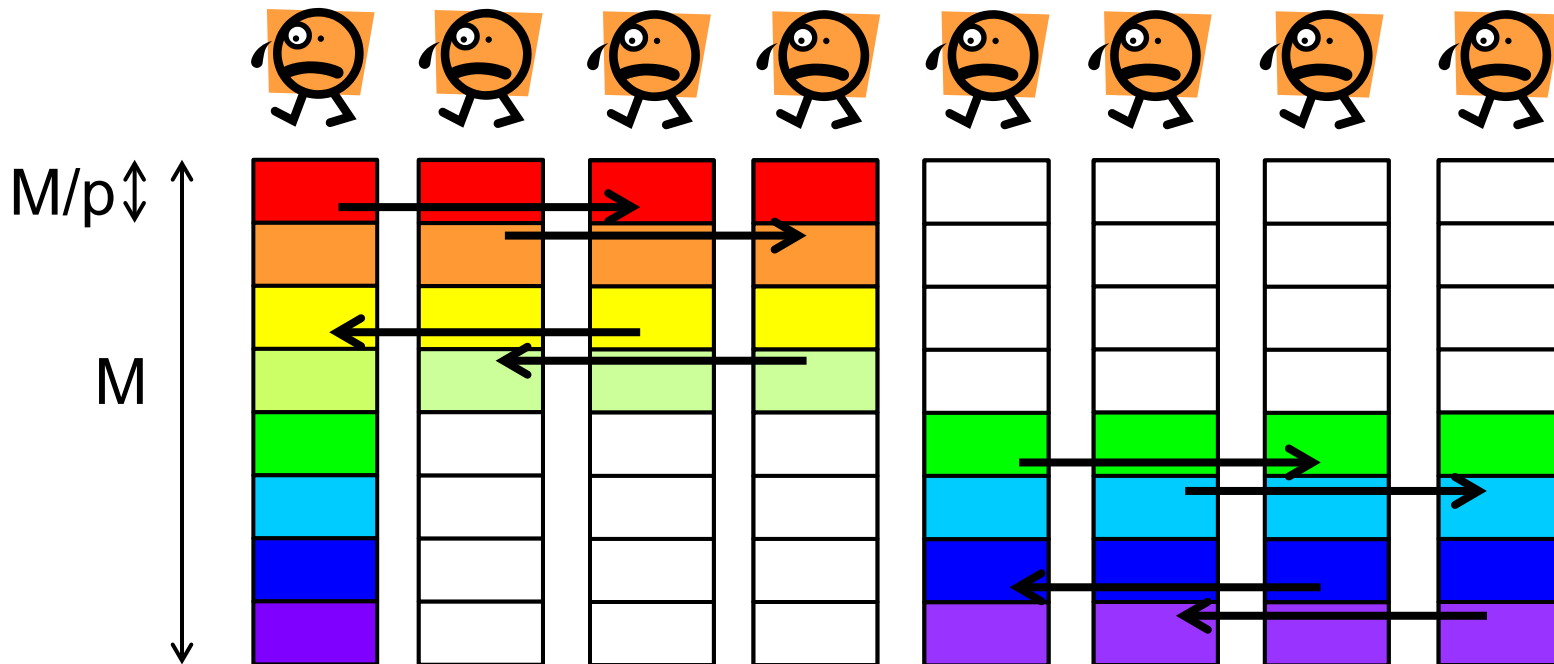
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- (3) Allgather in $\log p$ steps
 - If $p=8$, we use 3 steps



Scatter&Allgather Algorithm (3)



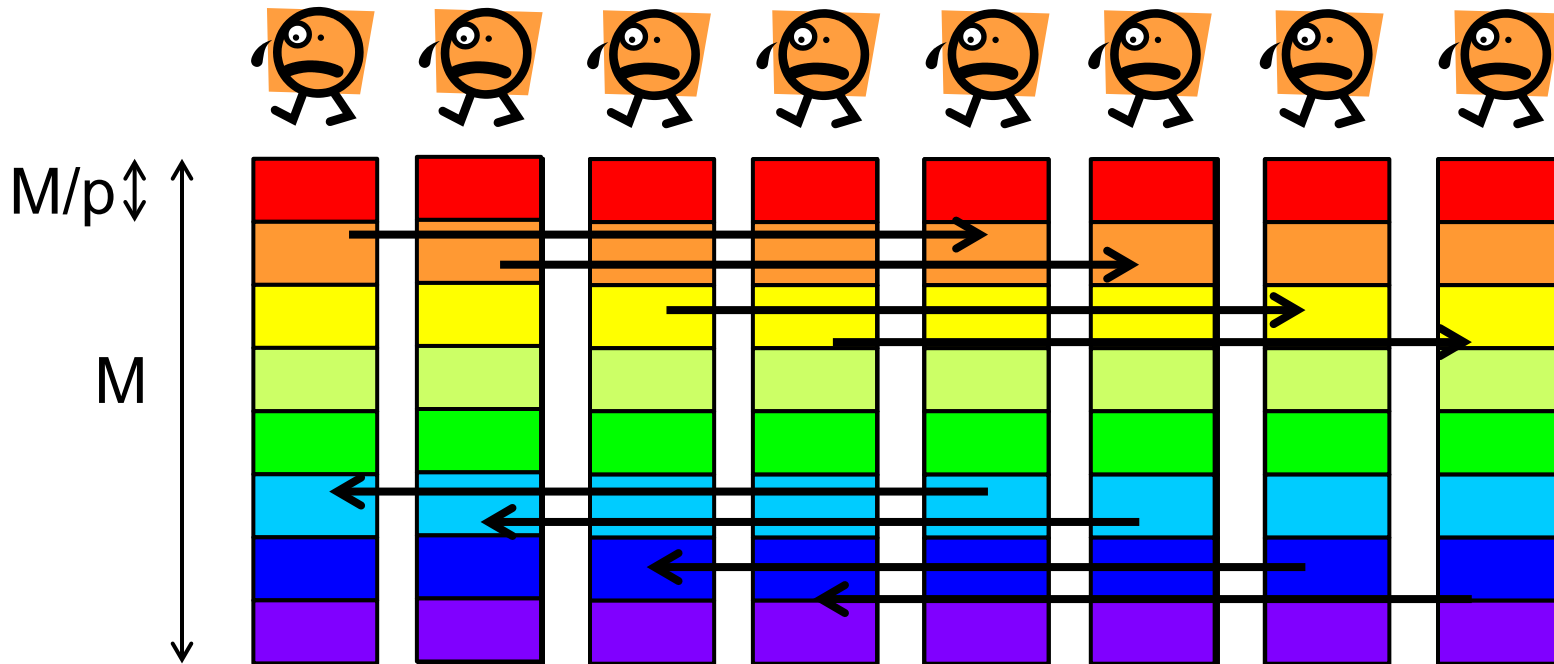
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Scatter&Allgather Algorithm (3)



- (1) The root process divide the message into p parts
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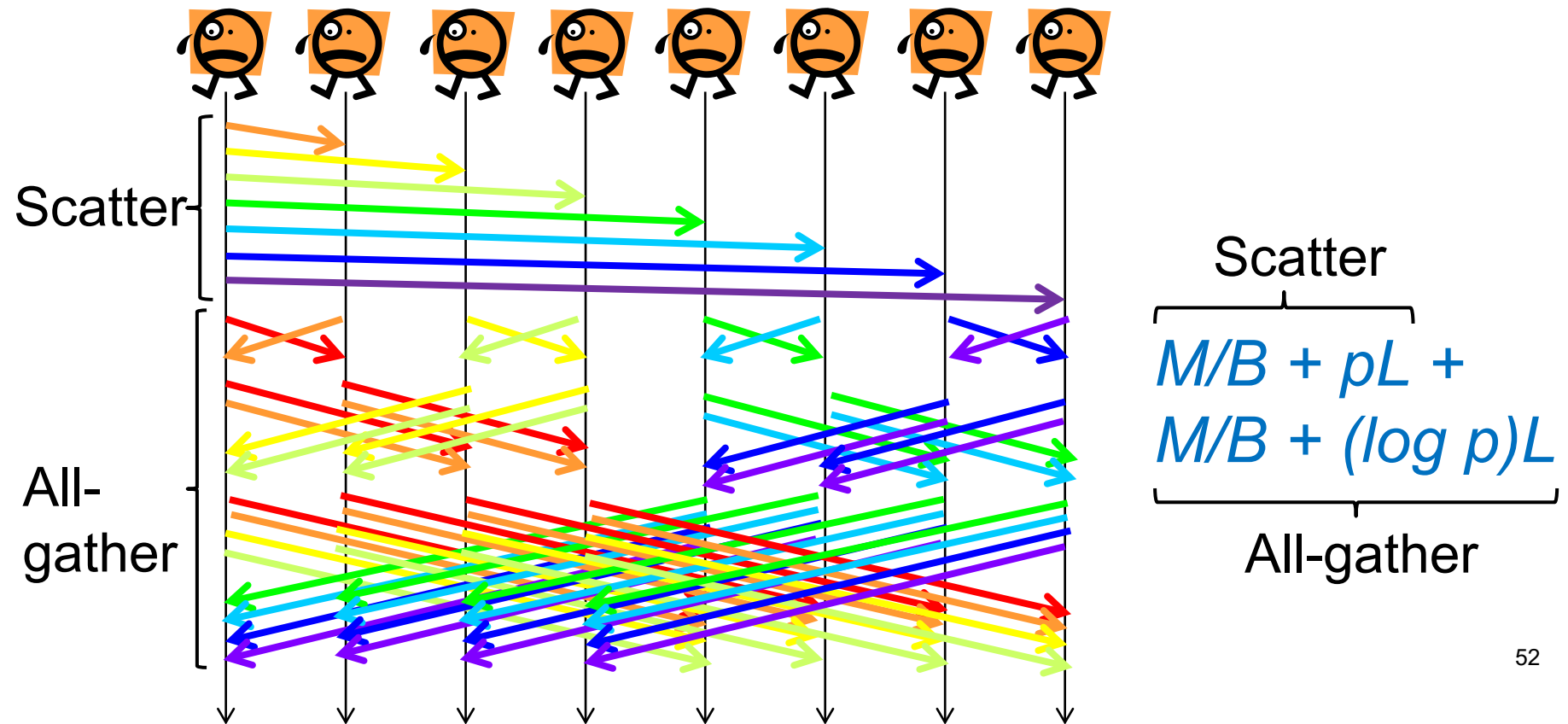


Cost of Scatter&Allgather Algorithm



- Scatter&Allgather algorithm

- (1) The root process divide the message into p parts
- (2) Scatter
- (3) Allgather



Comparison of Broadcast Algorithms



- Consider two extreme cases
 - If M is sufficiently large: $M/B+L \rightarrow M/B$
 - If M is close to zero: $M/B+L \rightarrow L$

	Flat Tree	Binomial Tree	Scatter&Allgather
General Cost	$p(M/B+L)$	$(\log p) (M/B+L)$	$2M/B + (p + \log p)L$
Cost with very large M (L is ignored)	$p M/B$	$(\log p) M/B$	$2 M/B$ \rightarrow Fastest
Cost with very small M (M is ignored)	$p L$	$(\log p) L$ \rightarrow Fastest	$(p + \log p) L$

Many MPI libraries implement multiple algorithms

They switch them automatically according to message size M 😊



Assignments in MPI Part

Choose one of [M1]—[M4], and submit a report

Due date: June 9 (Monday)

[M1] Parallelize “diffusion” sample program by MPI

[M2] Parallelize “bsort” sample program by MPI

[M3] Evaluate speed of “mpi/mm” sample in detail

[M4] (Freestyle) Parallelize *any* program by MPI

For more details, please see [ppcomp25-12](#) slides

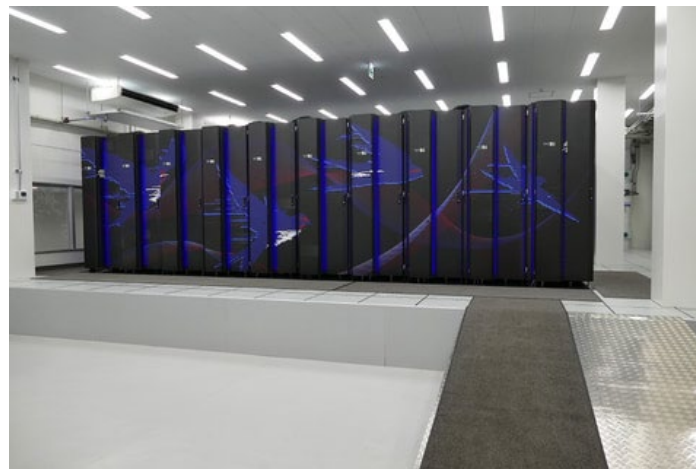


Next Optional Class

- May 29: (Short) class + TSUBAME4 tour
 - Shorter explanation in Classroom + zoom, as usual
 - If you come to the class room at 10:45, you can see TSUBAME4
 - Room 202, 2F, G2 building, Suzukake-dai campus

G2 bulding: No 31 in Campus map

<https://www.titech.ac.jp/english/0/maps/suzukakedai>



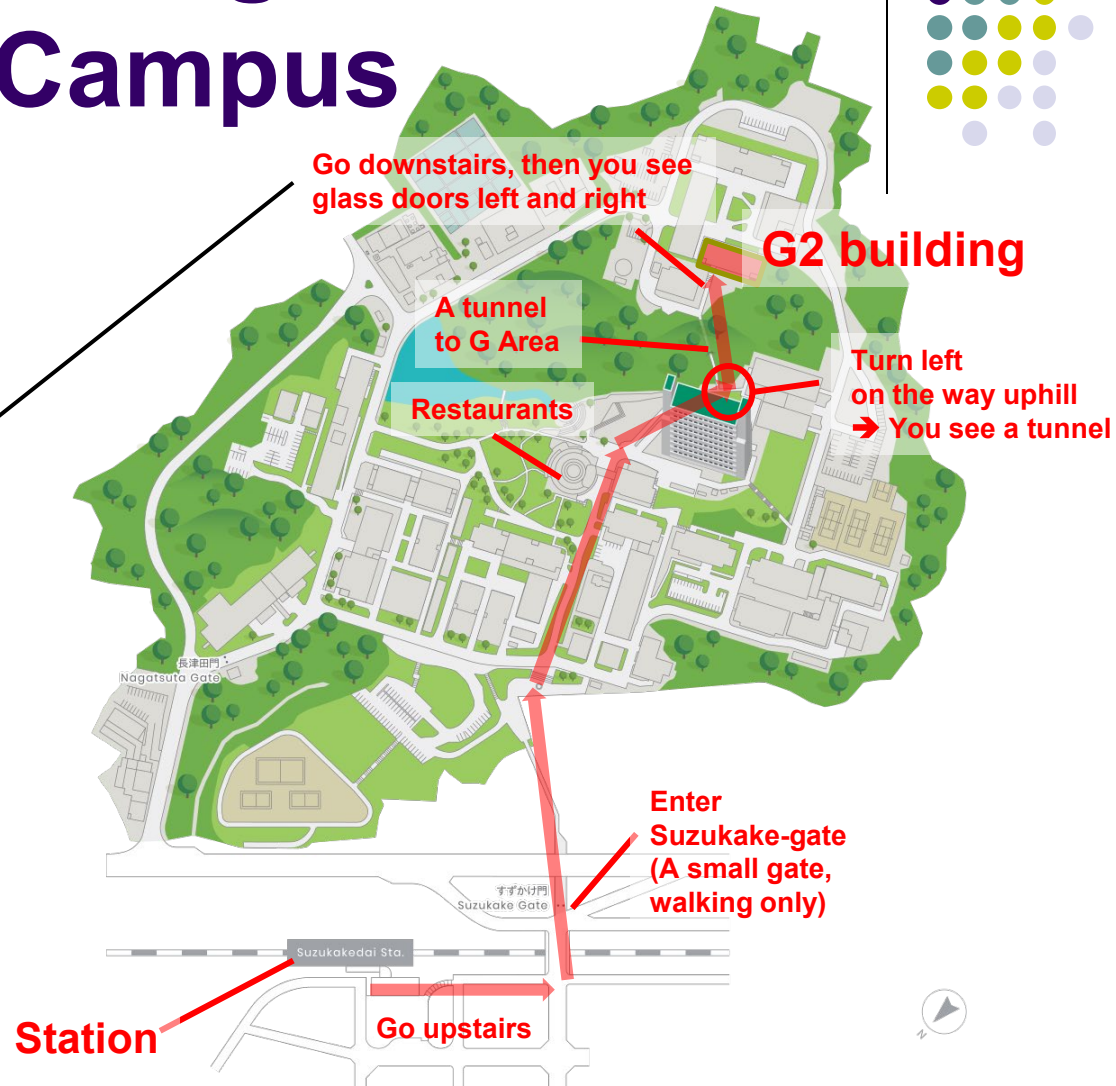
Way to G2 Building at Suzukakedai Campus



Suzukakedai Campus:

10 minutes walk from
Suzukakedai Station,
Denentoshi Line

Enter the right door and
go up to the 2nd floor
→ Room 202



すずかけ台G2棟 への道

すずかけ台キャンパス：

田園都市線すずかけ台駅から
約徒歩10分

202講義室：
右のドアに入り二階に上る

