TRAVIS DRIVER

(972) 310-0047

travisdriver.github.io

travisdriver@gatech.edu

EDUCATION

Georgia Institute of Technology

2019 - 2024 (Expected)

Doctor of Philosophy, Aerospace Engineering

Advisor: Professor Panagiotis Tsiotras

The University of Texas at Austin

2015 - 2019

Bachelor of Science, Computational Engineering, High Honors

Cumulative GPA: 3.93

RESEARCH EXPERIENCE

Autonomous GNC Lab

September 2018 - May 2019

Austin, TX

Undergraduate Research Assistant

- $\cdot \ \ Designed \ and \ implemented \ computer \ vision \ algorithms \ for \ autonomous \ navigation \ of \ robotic \ rover \ platform$
- · Implemented feature detection algorithms using OpenCV to resolve relative pose of target object
- · Demonstrated successful autonomous rendezvous operation of robotic platform with target object
- \cdot Constructed a model of the International Docking Adapter for use in spacecraft rendezvous simulations

Texas Spacecraft Lab

June 2017 - January 2018

Algorithms Team Lead (Sept. 2017 - Jan. 2018), Systems Engineer (June 2017 - Sept. 2017)

Austin, TX

- · Led team of 5+ engineers to implement machine learning and computer vision algorithms to detect target space-craft
- · Created a Python-based GUI to track and display spacecraft electrical power systems data
- · Conducted workshops to teach 20+ new members basic concepts in Python and Git

Institute for Computational Engineering and Sciences

May 2017 - August 2017

Austin, TX

Undergraduate Research Assistant

- · Implemented and evaluated novel clustering methods for an optimization and integration software library
- · Constructed programs to evaluate an advanced uncertainty quantification software library (QUESO) in C++
- · Improved variable assignment and subroutine methods to increase script efficiency of test programs

INDUSTRY EXPERIENCE

Sandia National Laboratories

June 2019 - Present

Albuquerque, NM

Software R & D Intern

- · Training and optimizing CNNs to efficiently identify objects in x-ray images
- · Implementing Simultaneous Localization And Mapping (SLAM) algorithms for application in autonomous drone navigation

Northrop Grumman

January 2018 - August 2018

Guidance, Navigation & Control Engineer Intern

Wallops Island, VA

- · Implemented novel Inertial Navigation System (INS) calibration methods improving performance by 43%
- · Designed a software interface to configure the on-board Flash memory of the Attitude Control System
- · Created an automated testing module to collect data and analyze the performance of the developmental INS
- · Conducted post-flight analysis of the reported angular rates and attitude of the INS to evaluate performance

Travis Driver August 1, 2019

TEACHING EXPERIENCE

COE 301: Introduction to Computer Programming

August 2017 - December 2017 Austin, TX

Teaching Assistant, The University of Texas at Austin

- · Aided in teaching core programming concepts in MATLAB, C++, and Fortran to a class of 100+ engineering students
- · Taught students course material one-on-one through 2 one-hour sessions of office hours per week
- · Assisted in creating course material and homework assignments focused on key programming concepts

HONORS & AWARDS

President's Fellowship, Georgia Institute of Technology (2019) University Honors, The University of Texas at Austin (2015 - 2019)

SKILLS

Programming: C, C++, C#, Python, MATLAB, Embedded, Fortran, Bash, Java

Software: ROS, OpenCV, TensorFlow, SolidWorks

Certifications: Technician Class Operator Radio License, NASA GSFC Electrostatic Discharge Operator

Travis Driver August 1, 2019