

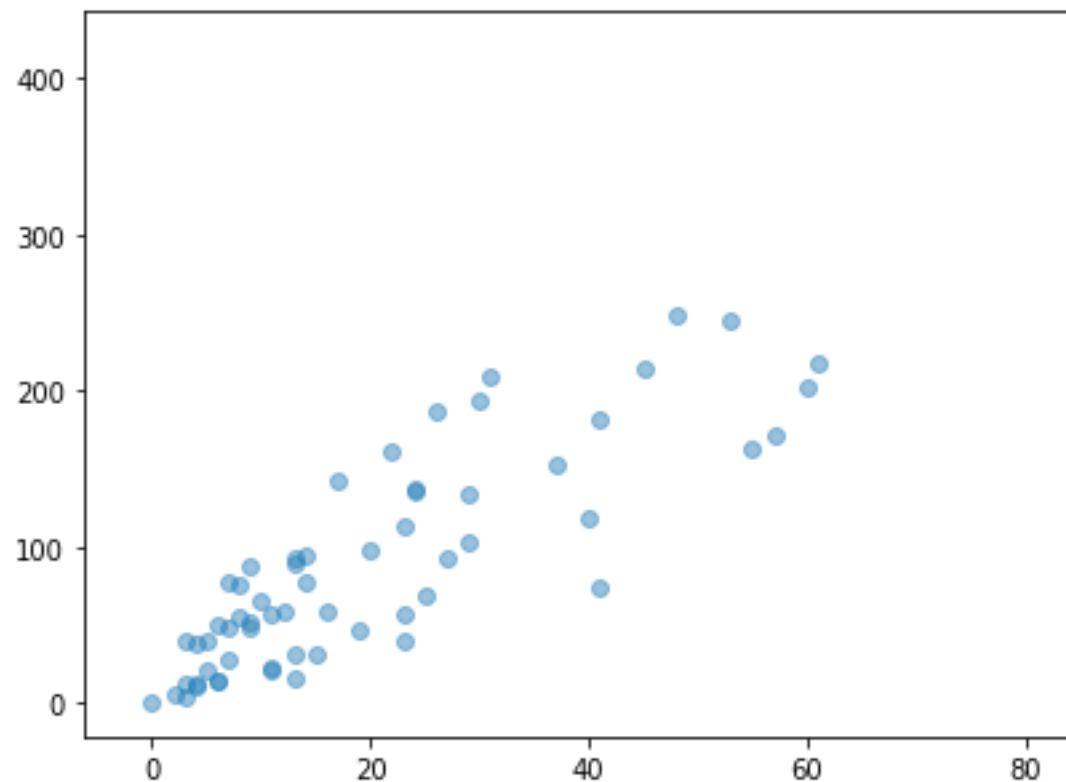
**Implementation**

**Linear Regression**

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# Gradient Descent로 Linear Regression 구해보기



```
df = pd.read_csv("data/slr06.csv")  
df.head()
```

	X	Y
0	108	392.5
1	19	46.2
2	13	15.7
3	124	422.2
4	40	119.4

```
raw_X = df["X"].values.reshape(-1, 1)  
y = df["Y"].values
```

```
plt.figure(figsize=(10,5))  
plt.plot(raw_X,y, 'o', alpha=0.5)
```

```
raw_X[:5], y[:5]
```

```
(array([[108],  
       [ 19],  
       [ 13],  
       [124],  
       [ 40]]), array([ 392.5,   46.2,   15.7,  422.2,  119.4]))
```

```
np.ones((len(raw_X),1))[:5]
```

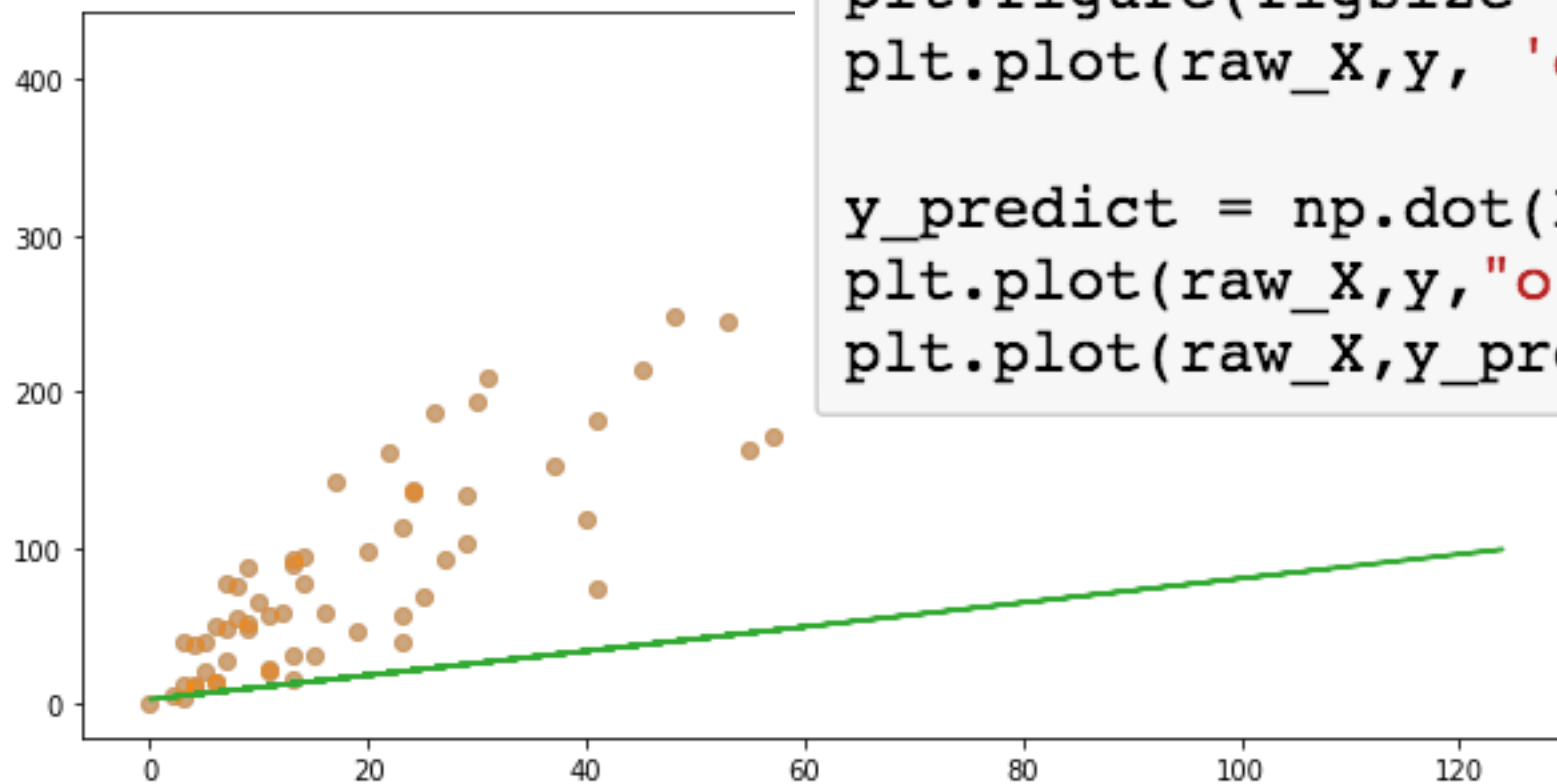
```
array([[ 1.],  
       [ 1.],  
       [ 1.],  
       [ 1.],  
       [ 1.]])
```

```
X = np.concatenate( (np.ones((len(raw_X),1)), raw_X ), axis=1)  
X[:5]
```

```
array([[ 1., 108.],  
       [ 1.,  19.],  
       [ 1.,  13.],  
       [ 1., 124.],  
       [ 1.,  40.]])
```

```
w = np.random.normal((2,1))  
# w = np.array([5,3])  
w
```

```
array([ 3.19571562,  0.77429904])
```



```
plt.figure(figsize=(10,5))  
plt.plot(raw_X,y, 'o', alpha=0.5)  
  
y_predict = np.dot(X, w)  $\hat{y} = Xw$   
plt.plot(raw_X,y, "o", alpha=0.5)  
plt.plot(raw_X,y_predict)
```

```
def hypothesis_function(X, theta):  
    return X.dot(theta)
```

$$f(x) = h_{\theta}(x)$$

```
hypothesis_function(X,w)[:5]
```

```
array([ 86.82001149,  17.9073973 ,  13.26160309,  99.20879607,  34.16767706])
```

```
def cost_function(h, y):  
    return (1/(2*len(y))) * np.sum((h-y)**2)
```

```
h = hypothesis_function(X,w)  
cost_function(h, y)
```

$$J(w_0, w_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

```
5479.1213778520041
```

```
def gradient_descent(X, y, w, alpha, iterations):
```

```
    theta = w
```

```
    m = len(y)
```

```
    theta_list = [theta.tolist()]
```

$$f(x) = h_{\theta}(x) \quad J(w_0, w_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

```
    cost = cost_function(hypothesis_function(X, theta), y)
```

$$\frac{\partial J}{\partial w_0} = \frac{1}{m} \sum_{i=1}^m (w_1 x^{(i)} + w_0 - y^{(i)})$$

```
    cost_list = [cost]
```

```
    for i in range(iterations):
```

```
        t0 = theta[0] - (alpha / m) * np.sum(np.dot(X, theta) - y)
```

```
        t1 = theta[1] - (alpha / m) * np.sum((np.dot(X, theta) - y) * X[:,1])
```

```
        theta = np.array([t0, t1])
```

$$\frac{\partial J}{\partial w_1} = \frac{1}{m} \sum_{i=1}^m (w_1 x^{(i)} + w_0 - y^{(i)}) x^{(i)}$$

```
        if i % 10 == 0:
```

```
            theta_list.append(theta.tolist())
```

```
            cost = cost_function(hypothesis_function(X, theta), y)
```

```
            cost_list.append(cost)
```

```
    return theta, theta_list, cost_list
```

```
def gradient_descent(X, y, w, alpha, iterations):
```

```
    theta = w
```

```
    m = len(y)
```

```
    theta_list = [theta.tolist()]
```

```
    cost = cost_function(hypothesis_function(X, theta), y)
```

```
    cost_list = [cost]
```

```
    for i in range(iterations):
```

```
        t0 = theta[0] - (alpha / m) * np.sum(np.dot(X, theta) - y)
```

```
        t1 = theta[1] - (alpha / m) * np.sum((np.dot(X, theta) - y) * X[:,1])
```

```
        theta = np.array([t0, t1])
```

loop until convergence{

do  $\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1)$

}

```
        theta_list.append(theta.tolist())
```

```
    cost_list.append(cost_function(hypothesis_function(X, theta), y))
```

```
    return theta, theta_list, cost_list
```

$$f(x) = h_{\theta}(x) \quad J(w_0, w_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

$$\frac{\partial J}{\partial w_0} = \frac{1}{m} \sum_{i=1}^m (w_1 x^{(i)} + w_0 - y^{(i)})$$

$$\frac{\partial J}{\partial w_1} = \frac{1}{m} \sum_{i=1}^m (w_1 x^{(i)} + w_0 - y^{(i)}) x^{(i)}$$



```
def gradient_descent(X, y, w, alpha, iterations):
```

```
    theta = w
```

```
    m = len(y)
```

```
    theta_list = [theta.tolist()]
```

$$f(x) = h_{\theta}(x) \quad J(w_0, w_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

```
    cost = cost_function(hypothesis_function(X, theta), y)
```

$$\frac{\partial J}{\partial w_0} = \frac{1}{m} \sum_{i=1}^m (w_1 x^{(i)} + w_0 - y^{(i)})$$

```
    cost_list = [cost]
```

```
    for i in range(iterations):
```

```
        t0 = theta[0] - (alpha / m) * np.sum(np.dot(X, theta) - y)
```

```
        t1 = theta[1] - (alpha / m) * np.sum((np.dot(X, theta) - y) * X[:,1])
```

```
        theta = np.array([t0, t1])
```

$$\frac{\partial J}{\partial w_1} = \frac{1}{m} \sum_{i=1}^m (w_1 x^{(i)} + w_0 - y^{(i)}) x^{(i)}$$

```
        if i % 10 == 0:
```

```
            theta_list.append(theta.tolist())
```

```
            cost = cost_function(hypothesis_function(X, theta), y)
```

```
            cost_list.append(cost)
```

```
    return theta, theta_list, cost_list
```

```
iterations = 10000
alpha = 0.001

theta, theta_list, cost_list = gradient_descent(X, y, w, alpha, iterations)
cost = cost_function(hypothesis_function(X, theta), y)

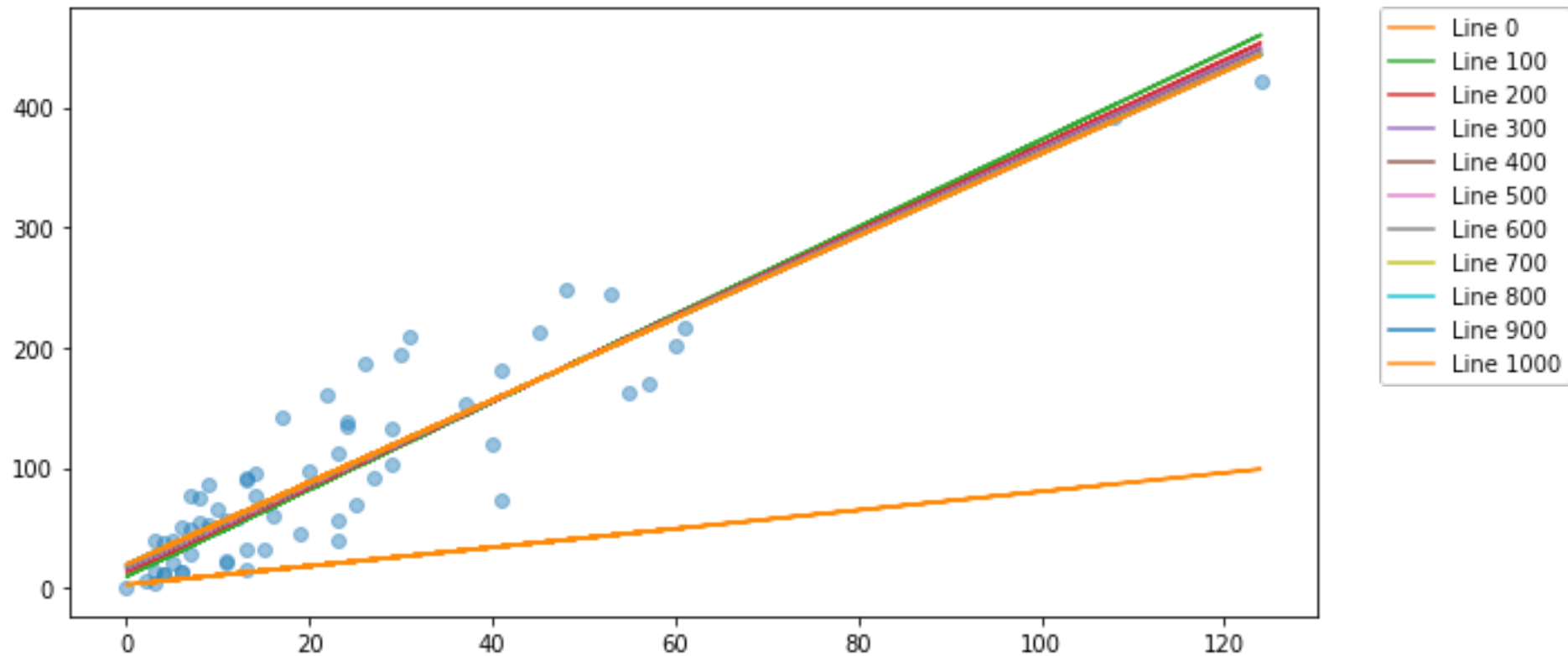
print("theta:", theta)
print('cost:', cost_function(hypothesis_function(X, theta), y))
```

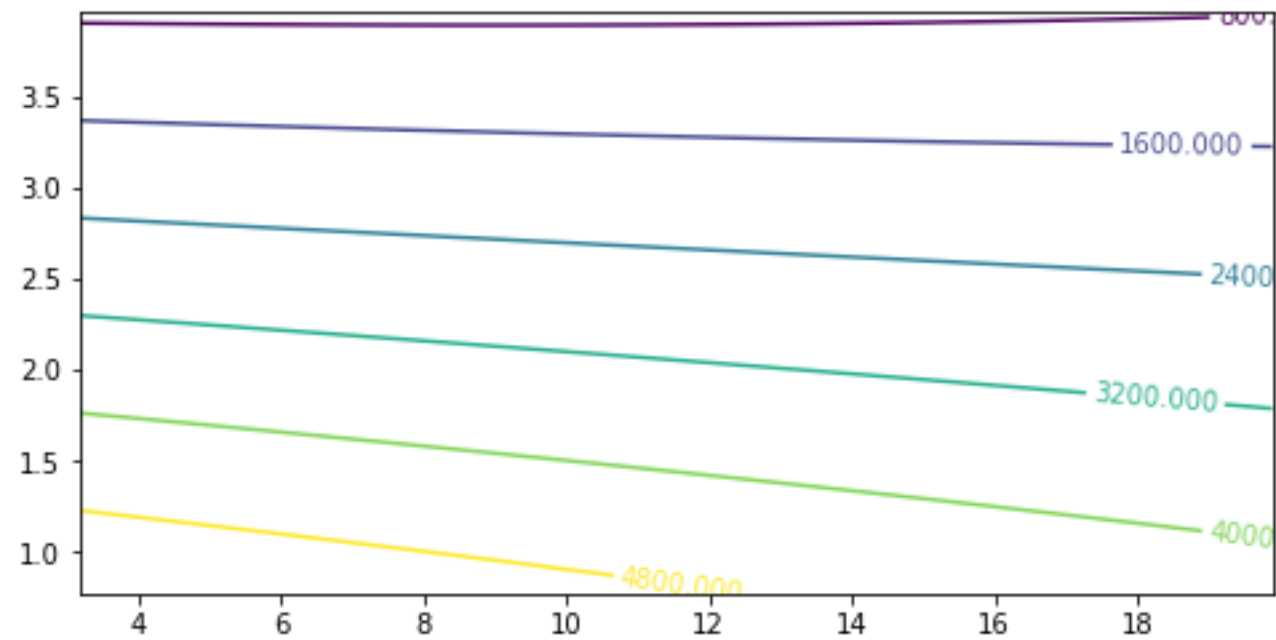
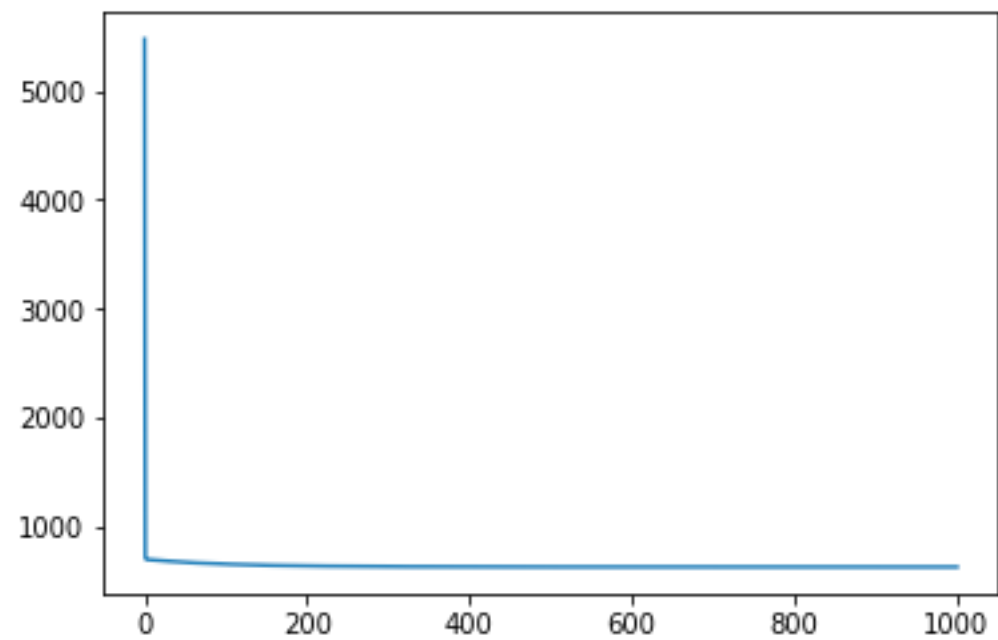
```
theta: [ 19.8878307    3.4161265]
cost: 625.373840751
```

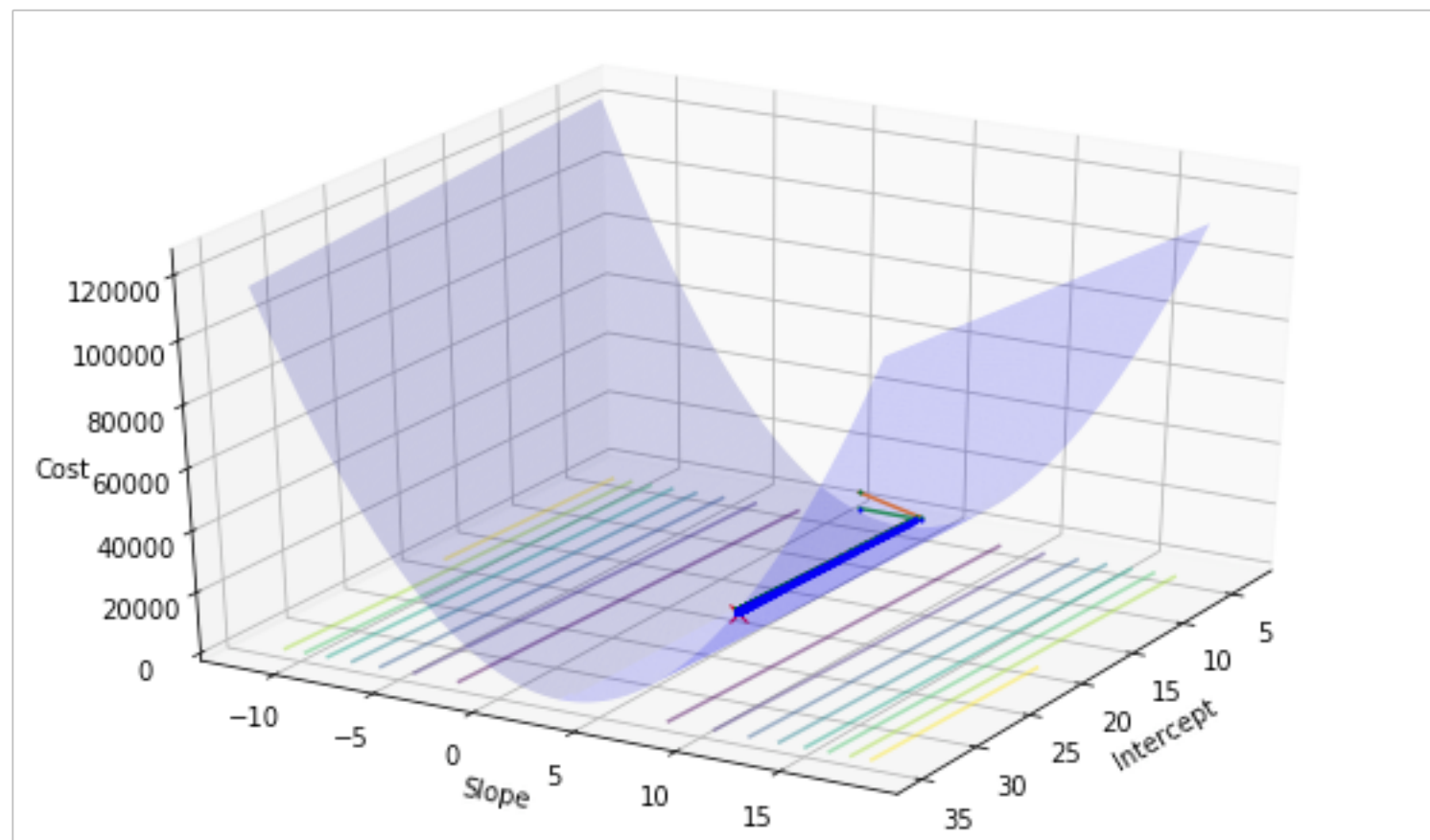
```
plt.figure(figsize=(10,5))

y_predict_step= np.dot(X, theta_list.transpose())
plt.plot(raw_X,y,"o", alpha=0.5)
for i in range (0,len(cost_list),100):
    plt.plot(raw_X,y_predict_step[:,i], label='Line %d'%i)

plt.legend(bbox_to_anchor=(1.05, 1), loc=2, borderaxespad=0.)
plt.show()
```









**Human knowledge belongs to the world.**