

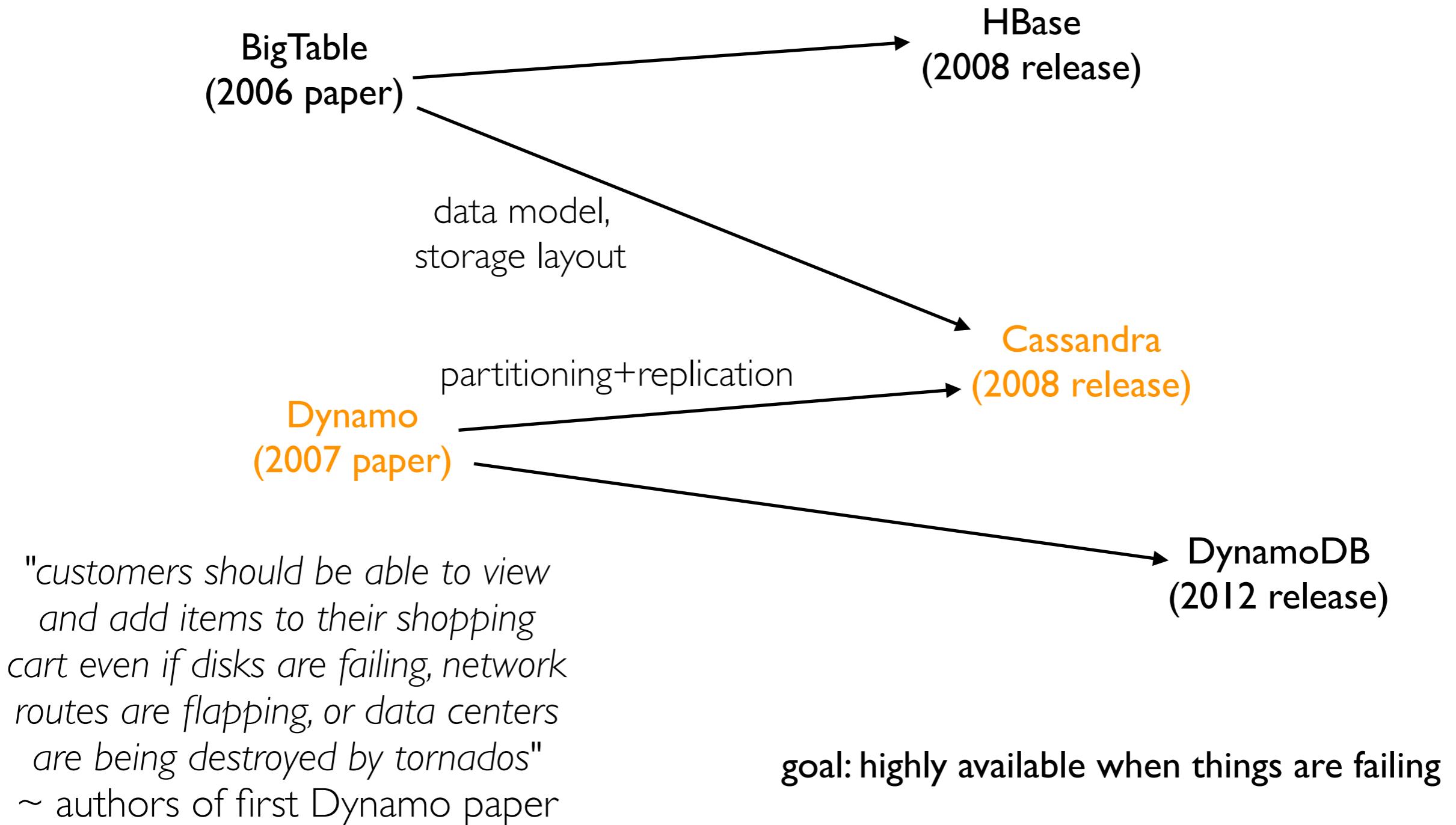
# [544] Cassandra Partitioning

Tyler Caraza-Harter

# Learning Objectives

- identify strengths and weaknesses of different partitioning techniques
- interpret a token ring to assign a row of data to a Cassandra worker (assume single replication for now)
- describe how gossip can be used to replicate data across workers in a cluster, without need for a centralized boss

# Cassandra Influences



# Partitioning Approaches

Given many machines and a partition of data, *how do we decide where it should live?*

## Mapping Data Structure

- locations = {"fileA-block0": [datanode1, ...], ...}
- HDFS NameNode uses this

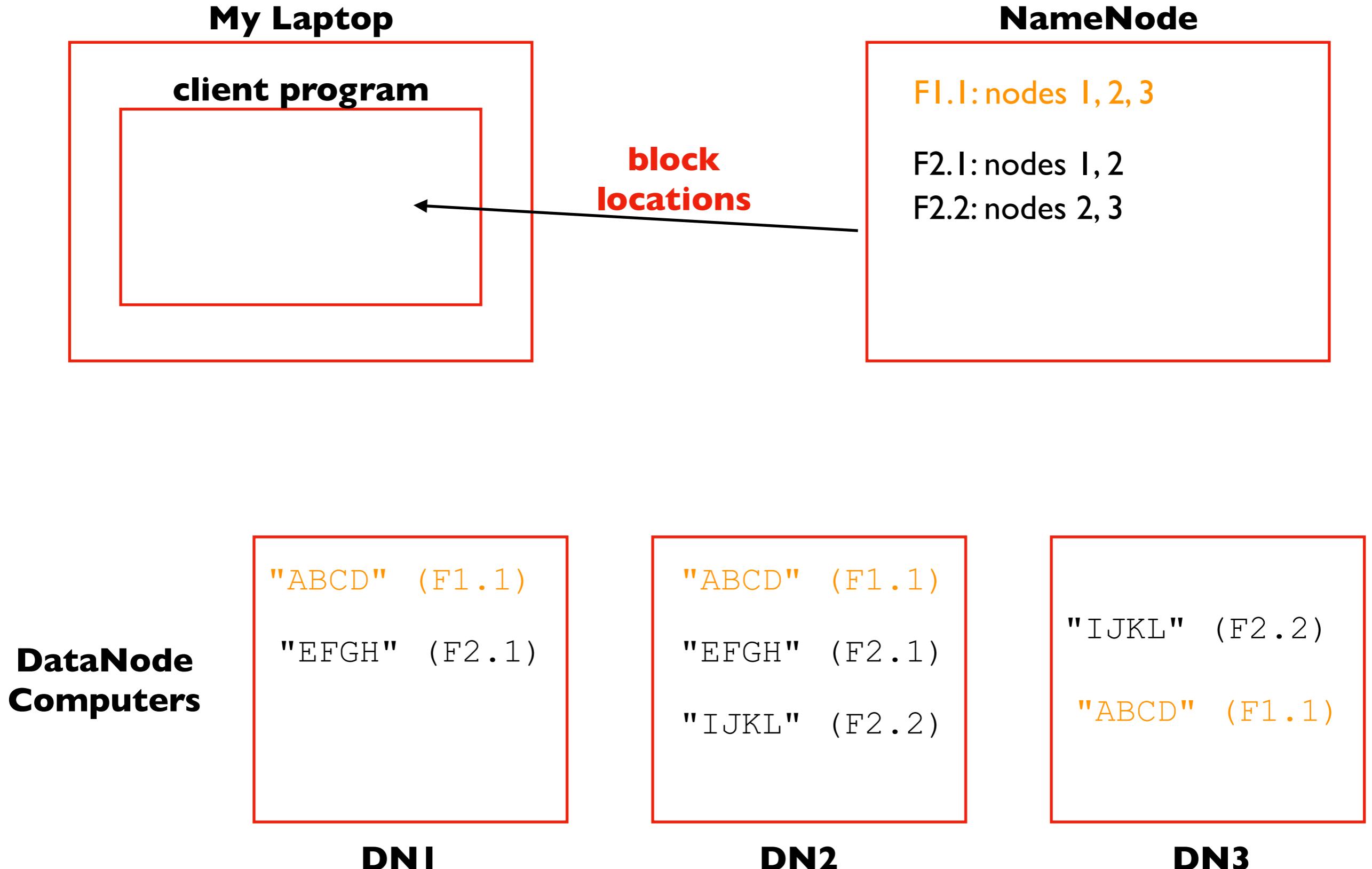
## Hash Partitioning

- partition = hash(key) % partition\_count
- Spark shuffle uses this (for grouping, joining, etc); data structures associate partitions with worker machines

## Consistent Hashing

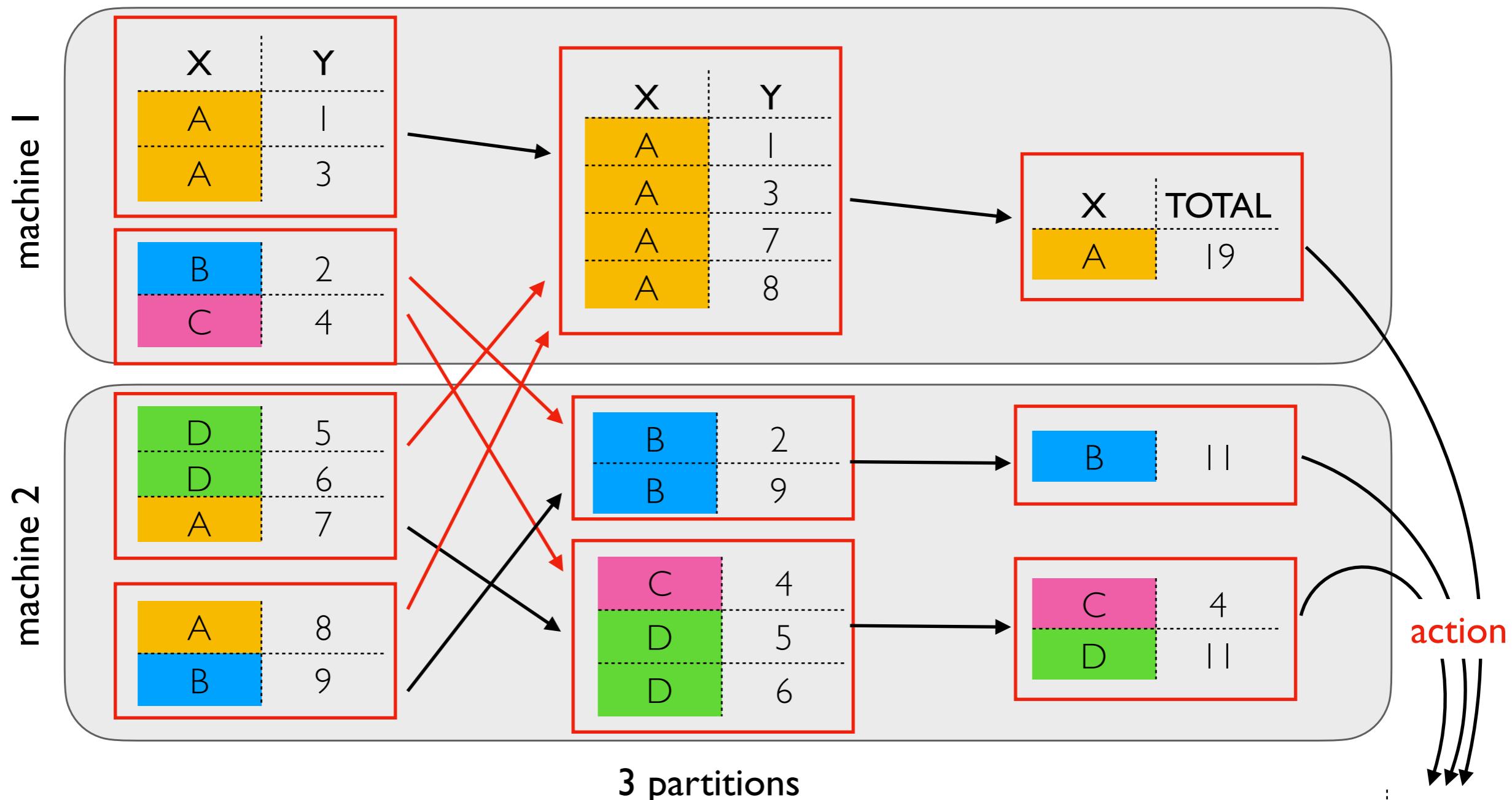
- Dynamo and Cassandra use this

# Review: HDFS Partitioning



# Review: Spark Hash Partitioning

  partition



row = Row(X=D, Y=5)

partition = **hash(row.X) % 3** # *partition=2*

file or  
Pandas DF

X	TOTAL
A	19
B	11
C	4
D	11

# Discuss Scalability: HDFS and Spark

**Scalability:** we can make efficient use of many machines for big data

Some ways we can have big data:

- few **large** objects (files/tables)
- **lots** of small objects (files/tables)

Will HDFS struggle with either kind of big data? Spark?

# Elasticity: Easily Growing/Shrinking Clusters

**Incremental Scalability:** can we efficiently add more machines to an already large cluster?

What happens when we **add a new DataNode** to an HDFS cluster?

What would need to happen if we able to **add an RDD partition** in the middle of a Spark hash-partitioned shuffle?

# Elasticity: Easily Growing/Shrinking Clusters

**Incremental Scalability:** can we efficiently add more machines to an already large cluster?

What happens when we **add a new DataNode** to an HDFS cluster?

What would need to happen if we able to **add an RDD partition** in the middle of a Spark hash-partitioned shuffle?

**Demo:** hash partition 26 letters over 4 "machines".  
Add a 5th machine. How many letters must move?

# Partitioning Approaches

Given many machines and a partition of data, *how do we decide where it should live?*

## Mapping Data Structure

- locations = `{"fileA-block0": [datanode1, ...], ...}`
- HDFS NameNode uses this

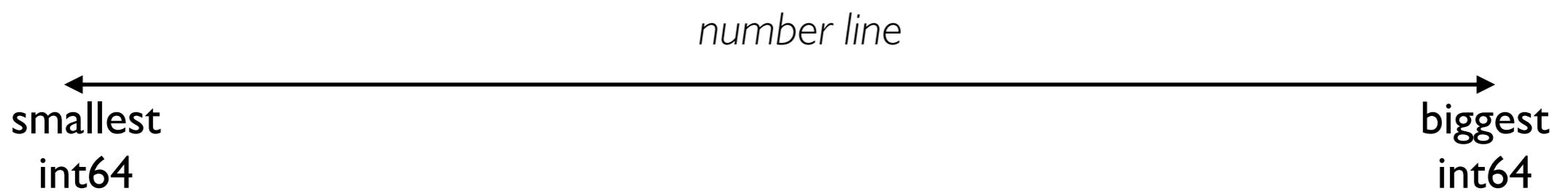
## Hash Partitioning

- partition = `hash(key) % partition_count`
- Spark shuffle uses this (for grouping, joining, etc); data structures associate partitions with worker machines

## Consistent Hashing

- Dynamo and Cassandra use this
- token = `hash(key)` # every token is in a range, indicating the worker
- locations = `{range(0,10): "worker1", range(10,20): "worker2", ...}`

# Consistent Hashing



# Consistent Hashing

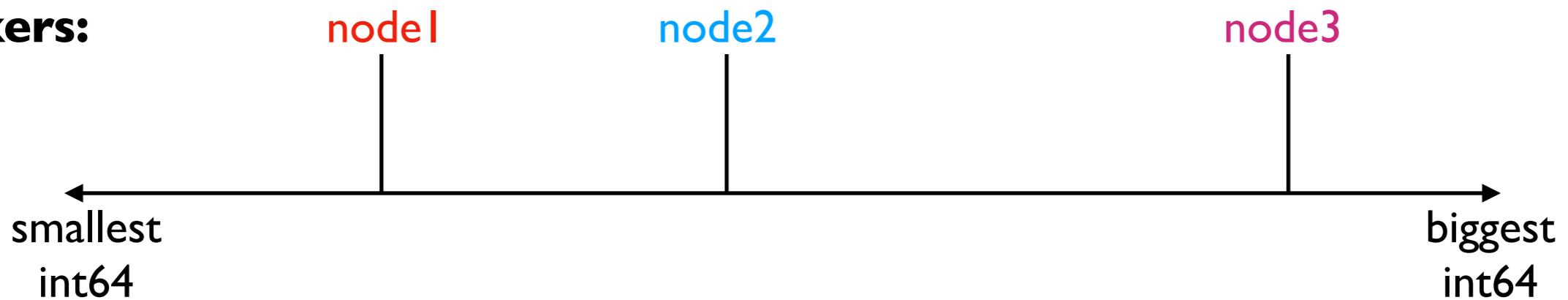
## **Token Map:**

**token(node1) = pick something**

**token(node2) = pick something**

**token(node3) = pick something**

## **workers:**



assign every **worker** a point on the number line.

Could be random (though newer approaches are more clever).

# No hashing needed, yet!

# Consistent Hashing

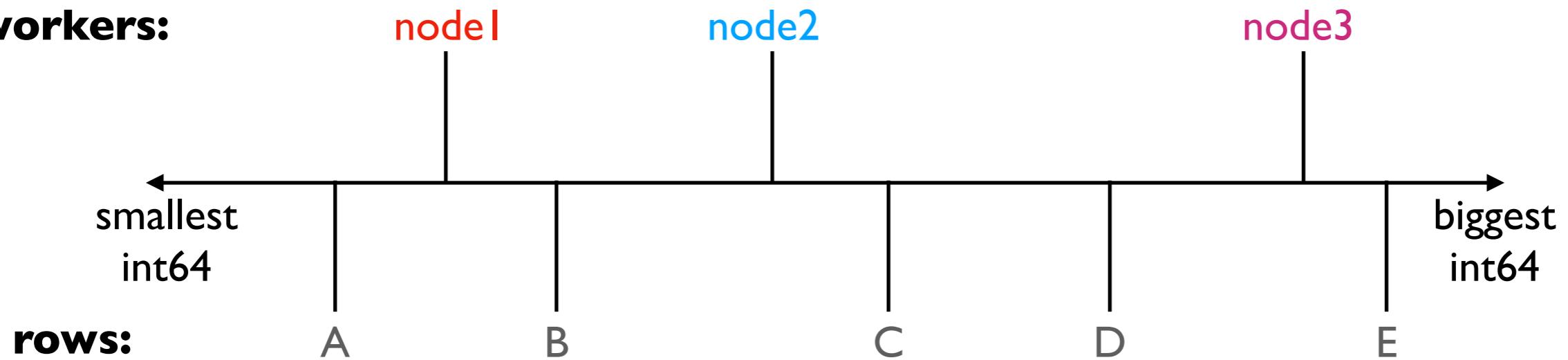
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assign every **row** a point on the number line.

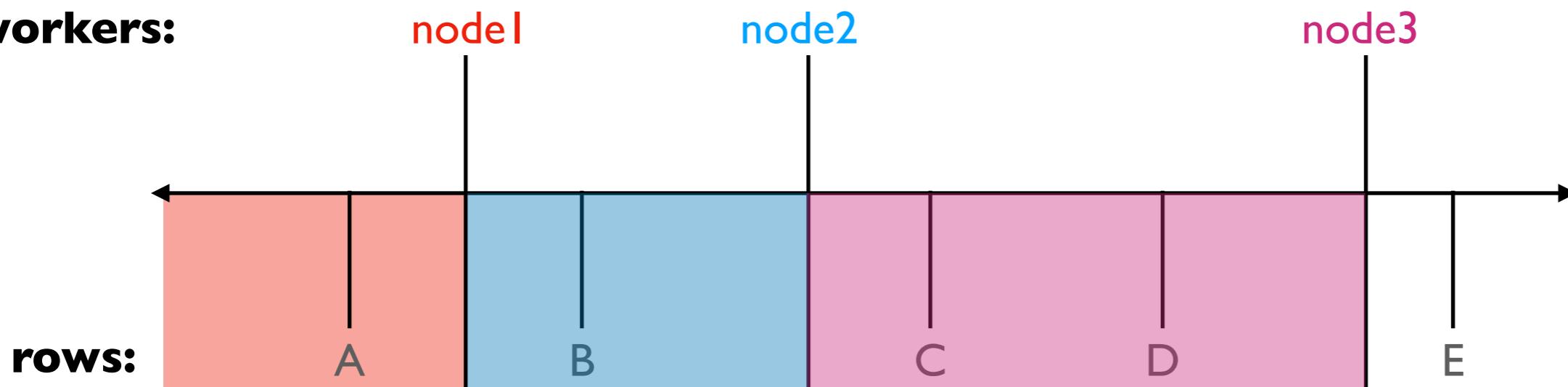
`token(row) = hash(row's partition key)`

# Consistent Hashing

## Token Map:

token(node1) = pick something  
token(node2) = pick something  
token(node3) = pick something

**workers:**



**rows:**

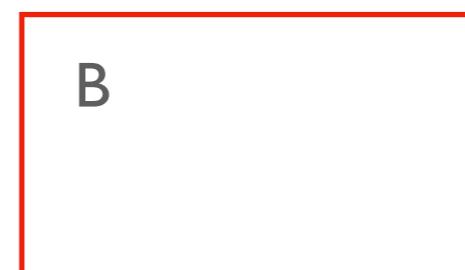
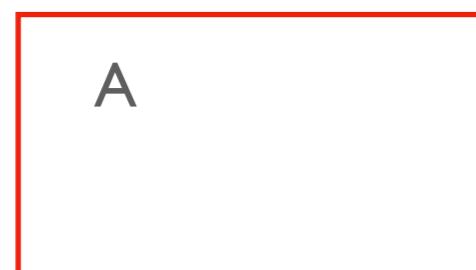
belongs to node2

**cluster:**

node1

node2

node3



each node's token is the **inclusive end** of a range.  
A row is mapped to a node based on the range it is in.

# Consistent Hashing

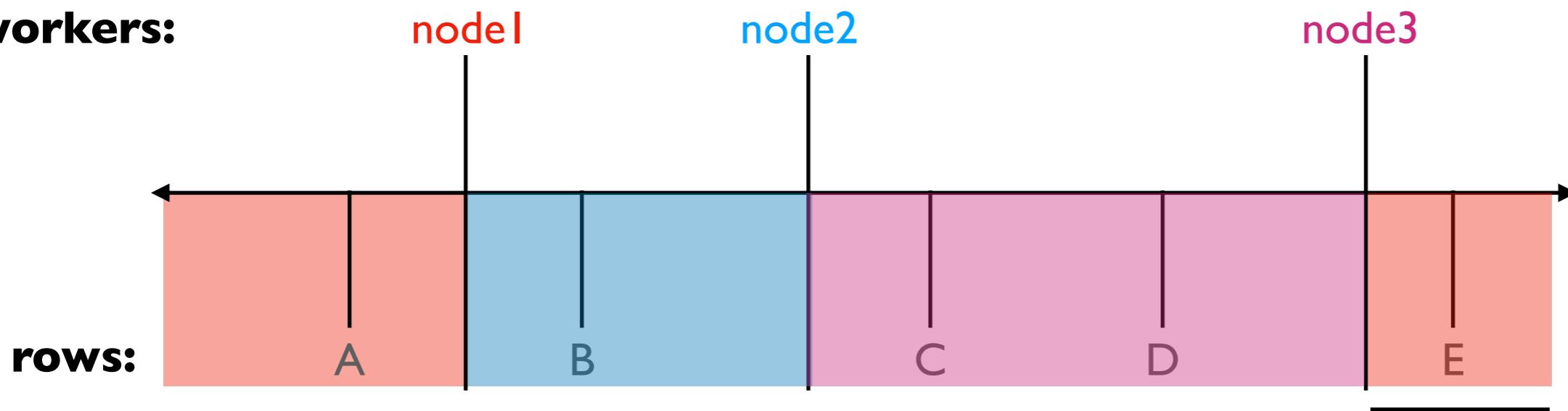
## Token Map:

token(node1) = pick something

token(node2) = pick something

token(node3) = pick something

**workers:**



**rows:**

tokens > biggest node token are in the *wrapping range*. Rows in this region go to the node with the smallest token.

**cluster:**

node1                    node2                    node3

A    E

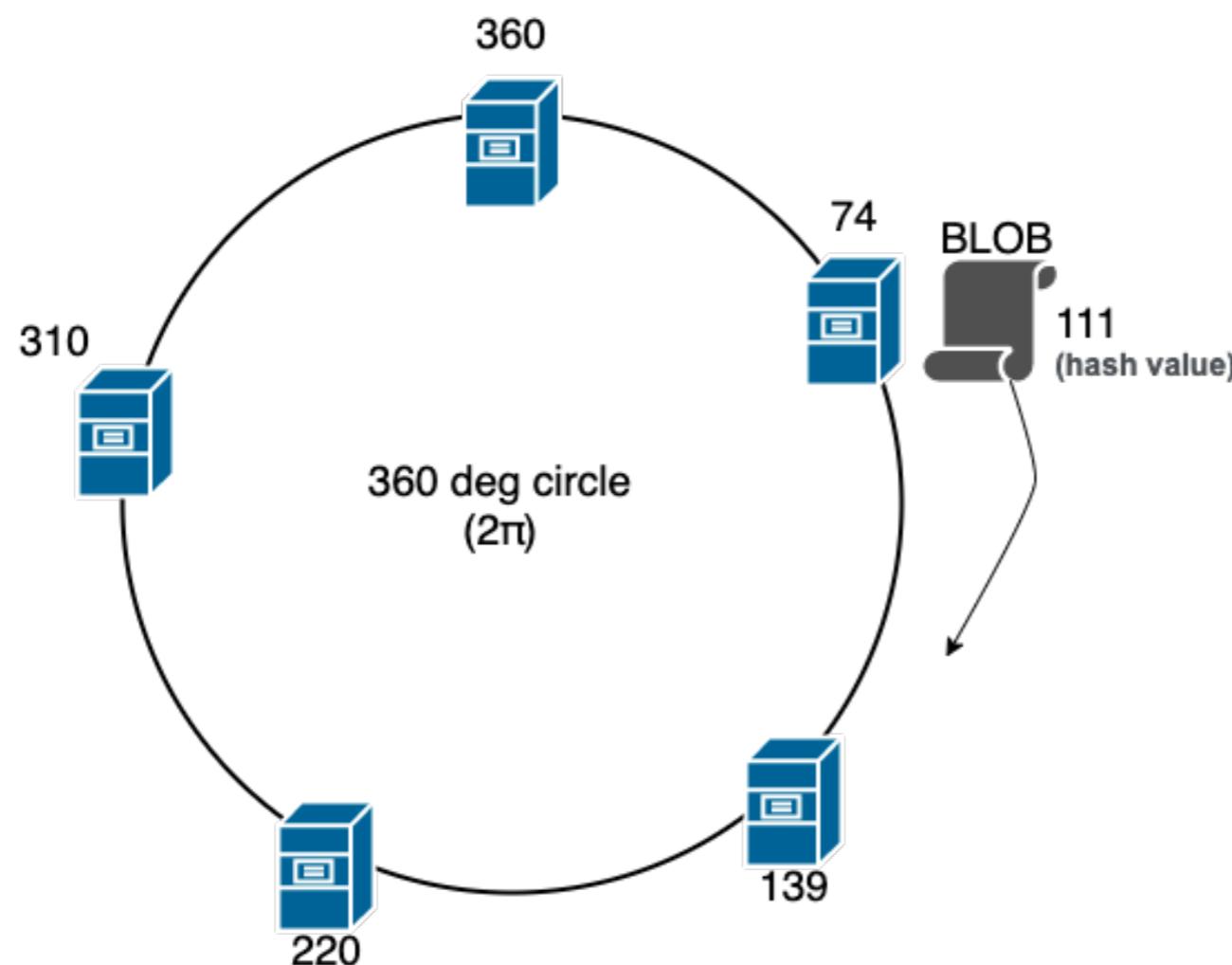
B

C    D

# Alternate Visualization

Given the wrapping, clusters using consistent hashing are called "token rings"

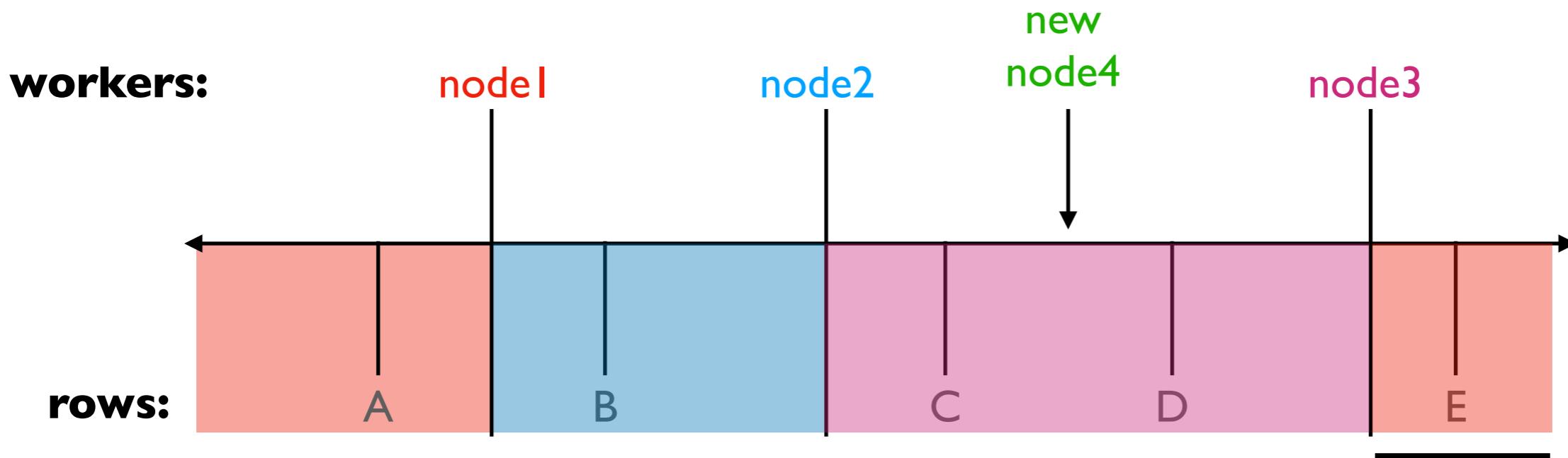
Common visualization (e.g., from Wikipedia)



# Adding a Node

## Token Map:

token(node1) = pick something  
token(node2) = pick something  
token(node3) = pick something  
token(node4) = pick something



which rows will have to move?  
which nodes will be involved?

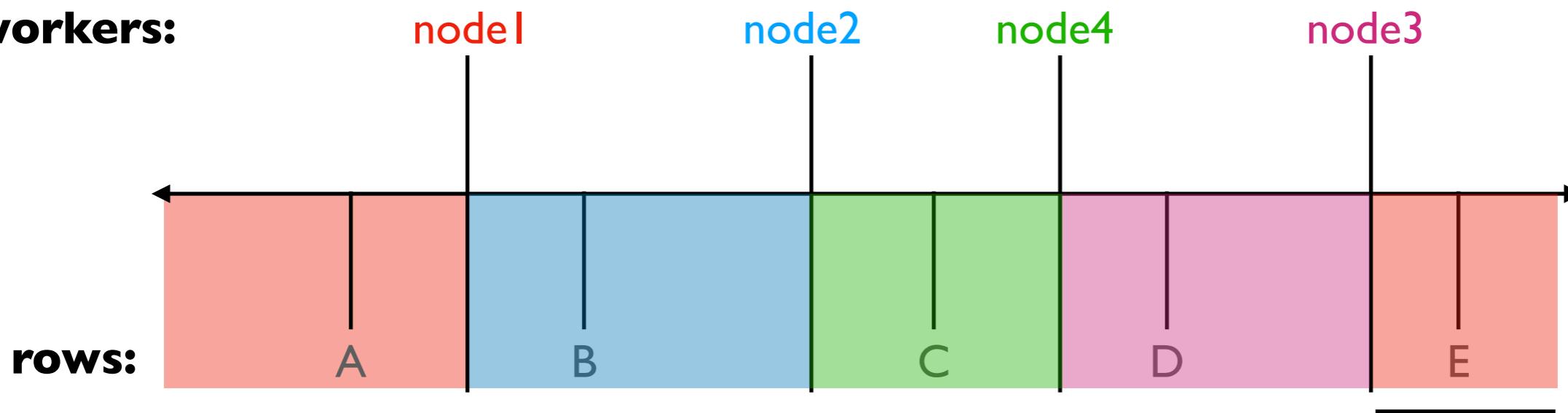


# Adding a Node

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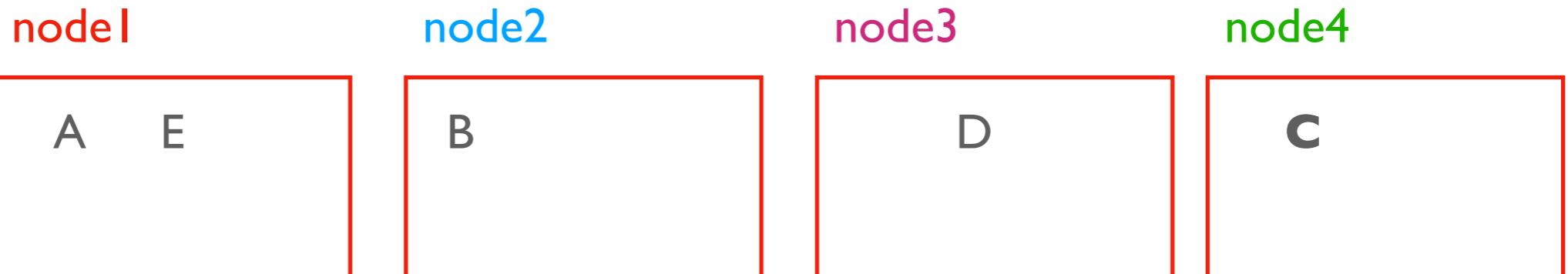
**workers:**



which rows will have to move? Only C

which nodes will be involved? Only node3 and node4

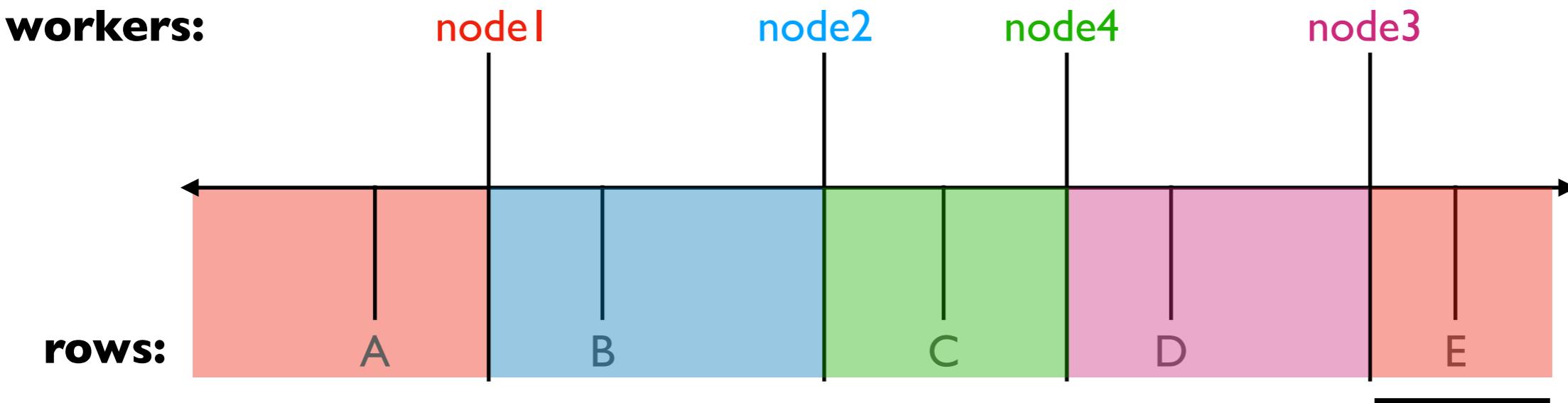
**cluster:**



# Adding a Node

## Token Map:

token(node1) = pick something  
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token(node4) = pick something



*Typically, what fraction of the data must move when we scale from  $N-1$  to  $N$ ?*

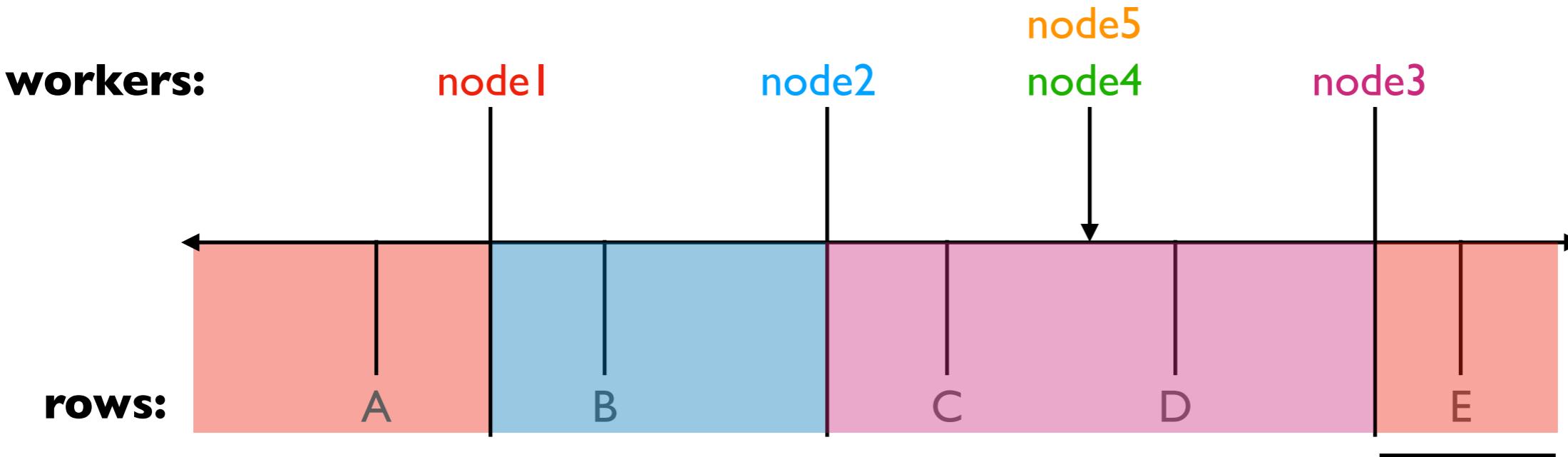
**Hash partitioning:** about  $(N-1)/N$  of the data

**Consistent hashing:** about  $(\text{size of new range})/(\text{size of ring})$  of the data must move.

# Collisions

## Token Map:

token(node1) = pick something  
token(node2) = pick something  
token(node3) = pick something  
token(node4) = pick something



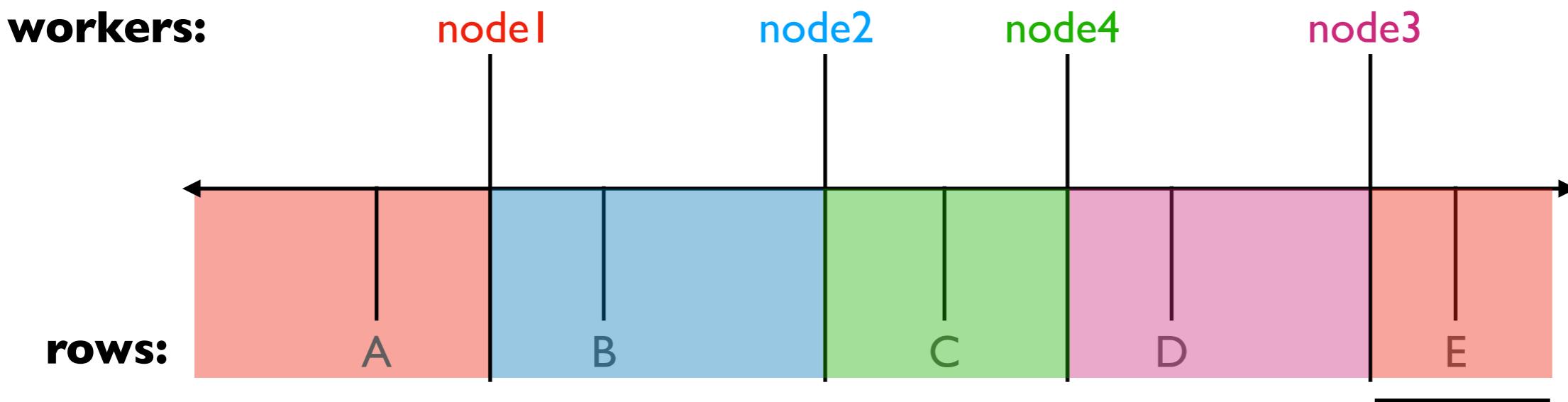
**Problem:** latest Cassandra versions by default try to choose new node tokens to split big ranges for better balance (instead of randomly picking). Adding multiple nodes simultaneously can lead to collisions, preventing nodes from joining.

**Solution:** add one at a time (after initial "seed" nodes)

# Sharing the Work

## Token Map:

token(node1) = pick something  
token(node2) = pick something  
token(node3) = pick something  
token(node4) = pick something



## Other problems with adding node 4

- **long term:** only load of node 3 is alleviated
- **short term:** node 3 bears all the burden of transferring data to node 4

Solution: "vnodes"

# Virtual Nodes (vnodes)

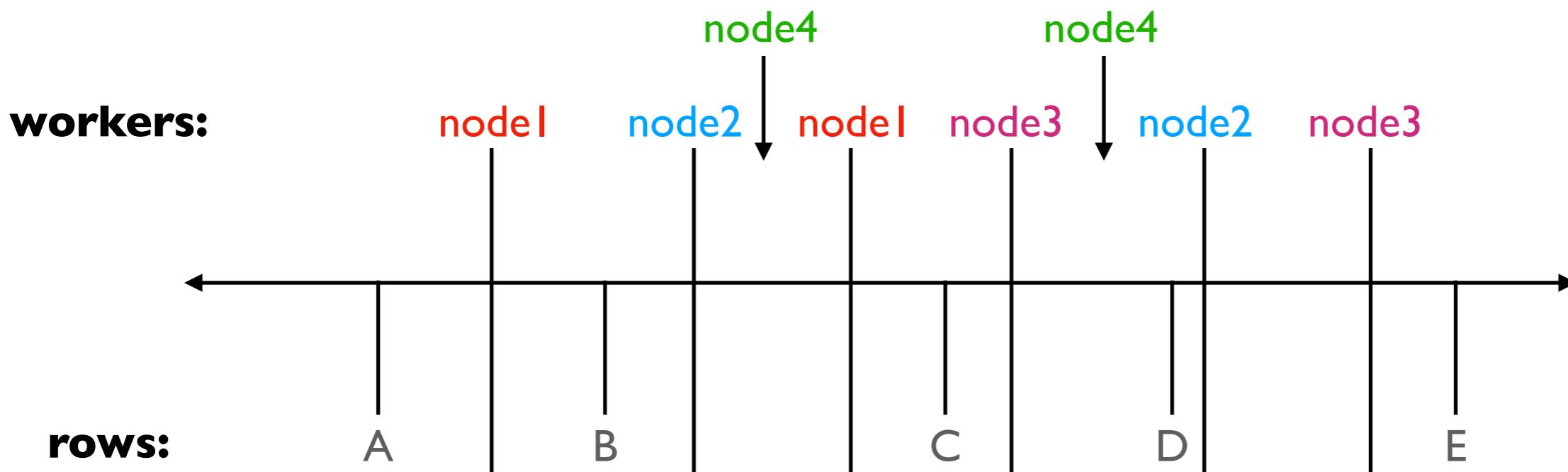
## Token Map:

$\text{token}(\text{node1}) = \{t1, t2\}$

$\text{token}(\text{node2}) = \{t3, t4\}$

$\text{token}(\text{node3}) = \{t5, t6\}$

$\text{token}(\text{node4}) = \{t7, t8\}$



Each node is responsible for multiple ranges

- how many is configurable
- node 4 will take some load off nodes 1 and 2  
(those to the right of its vnodes)

# Heterogeneity

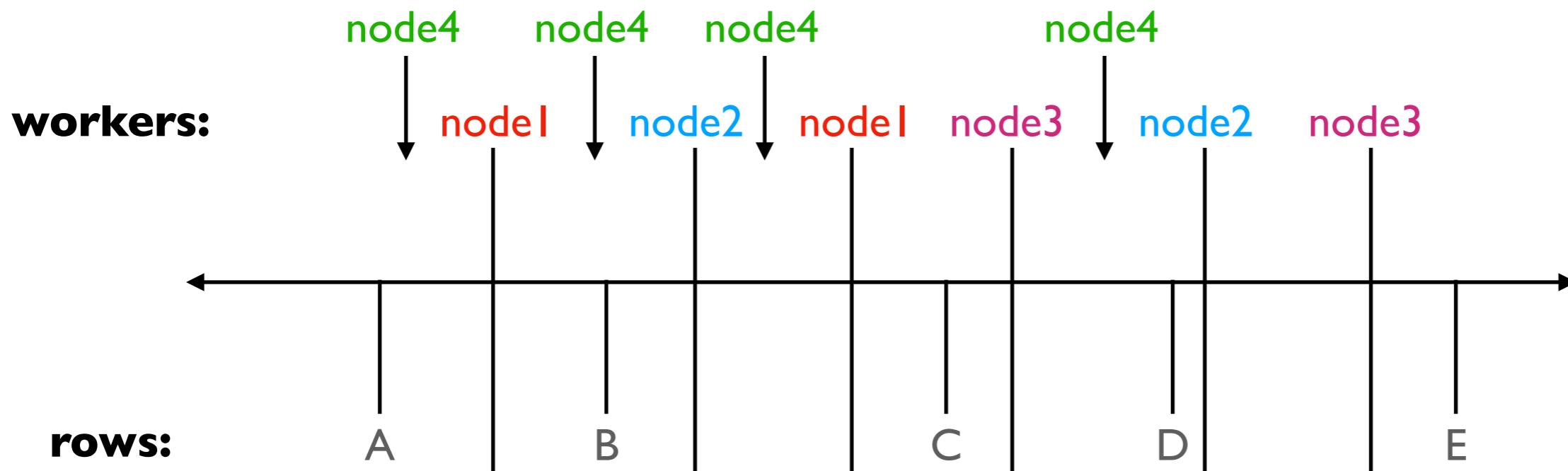
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$\text{token}(\text{node3}) = \{t5, t6\}$

$\text{token}(\text{node4}) = \{t7, t8, t9, t10\}$



**Heterogeneity:** some machines (e.g., newer ones) have more resources

- more powerful nodes can have more vnodes
- probabilistically, they'll do more work and store more data

# Token Map Storage

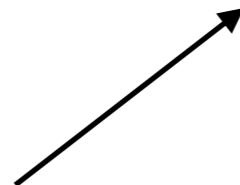
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$\text{token}(\text{node1}) = \{\text{t1}, \text{t2}\}$

$\text{token}(\text{node2}) = \{\text{t3}, \text{t4}\}$

$\text{token}(\text{node3}) = \{\text{t5}, \text{t6}\}$

where should this live?



we don't want a single point of failure  
(like an HDFS NameNode)

# Token Map Storage

node1

## table rows

...lots of data...

## Token Map:

token(node1) = {t1, t2}  
token(node2) = {t3, t4}  
token(node3) = {t5, t6}

node2

## table rows

...lots of data...

## Token Map:

token(node1) = {t1, t2}  
token(node2) = {t3, t4}  
token(node3) = {t5, t6}

node3

## table rows

...lots of data...

## Token Map:

token(node1) = {t1, t2}  
token(node2) = {t3, t4}  
token(node3) = {t5, t6}

every node has a copy of the token map

they should all get updated when new nodes join

# Adding Nodes: Bad Approach

*uh oh, node 3 won't know about  
node 4 when it comes back*

node1

## table rows

...lots of data...

## Token Map:

token(node1) = {t1, t2}  
token(node2) = {t3, t4}  
token(node3) = {t5, t6}  
**token(node4) = {t7, t8}**

node2

## table rows

...lots of data...

## Token Map:

token(node1) = {t1, t2}  
token(node2) = {t3, t4}  
token(node3) = {t5, t6}  
**token(node4) = {t7, t8}**

node3

## table rows

...lots of data...

rebooting...

## Token Map:

token(node1) = {t1, t2}  
token(node2) = {t3, t4}  
token(node3) = {t5, t6}

node4

## table rows

...lots of data...

## Token Map:

token(node1) = {t1, t2}  
token(node2) = {t3, t4}  
token(node3) = {t5, t6}  
**token(node4) = {t7, t8}**

# Better Approach: Gossip

just inform one or a few nodes about the new one

node1

## table rows

...lots of data...

## Token Map:

token(node1) = {t1, t2}  
token(node2) = {t3, t4}  
token(node3) = {t5, t6}

node2

## table rows

...lots of data...

## Token Map:

token(node1) = {t1, t2}  
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**token(node4) = {t7, t8}**

node3

## table rows

...lots of data...

rebooting...

## Token Map:

token(node1) = {t1, t2}  
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token(node3) = {t5, t6}

node4

## table rows

...lots of data...

## Token Map:

token(node1) = {t1, t2}  
token(node2) = {t3, t4}  
token(node3) = {t5, t6}  
**token(node4) = {t7, t8}**

# Better Approach: Gossip

once per second:  
choose a random friend  
gossip about new nodes

node1

## table rows

...lots of data...

## Token Map:

token(node1) = {t1, t2}  
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token(node3) = {t5, t6}  
token(node4) = {t7, t8}

node2

## table rows

...lots of data...

## Token Map:

token(node1) = {t1, t2}  
token(node2) = {t3, t4}  
token(node3) = {t5, t6}  
token(node4) = {t7, t8}

"have you heard  
about node 4?"



node3

## table rows

...lots of data...

rebooting...

## Token Map:

token(node1) = {t1, t2}  
token(node2) = {t3, t4}  
token(node3) = {t5, t6}

node4

## table rows

...lots of data...

## Token Map:

token(node1) = {t1, t2}  
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# Better Approach: Gossip

eventually, every node should find out

node1

## table rows

...lots of data...

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token(node3) = {t5, t6}  
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node2

## table rows

...lots of data...

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node3

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node4

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# Better Approach: Gossip

when a client wants to write a row, they can contact any node -- it should know where the data should live and coordinate the operation

node1

## table rows

...lots of data...

## Token Map:

```
token(node1) = {t1, t2}  
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token(node3) = {t5, t6}  
token(node4) = {t7, t8}
```

node2

## table rows

...lots of data...

## Token Map:

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token(node1) = {t1, t2}  
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```

node3

## table rows

...lots of data...

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token(node4) = {t7, t8}
```

node4 (coordinator)

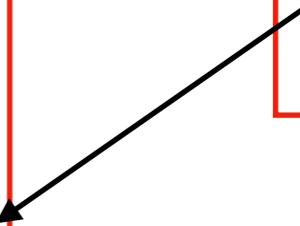
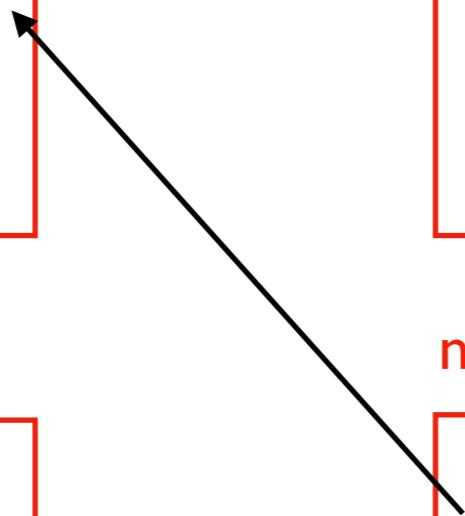
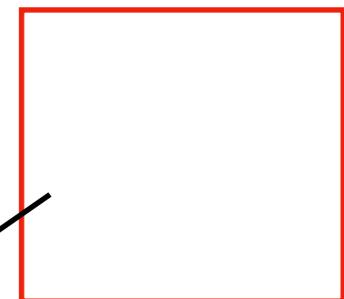
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```

client



**TopHat, Worksheet**