EEM412 CourseIntroduction to IC Design – II

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- Very High Speed Integrated Circuit Hardware Description Language
 - Product of the VHSIC program funded by DOD in the 1970s and 1980s.
 - The language was intended to be a standard means to document complex circuits so that a designer would understand an other designer's work easily.
 - Also, to be used as a modeling language that could be processed by software for simulation purposes.
 - Became a standard, IEEE 1076, in 1987. Updated and additional VHDL standard, IEEE 1164, was adopted. In 1996, IEEE 1076.3 became a VHDL synthesis standard.
 - Today, VHDL is an industry standard for description, modeling, and synthesis
 of digital circuits and systems. Only a subset of VHDL can be used to write
 codes which can be synthesized.

- VHDL provides the capabilities of;
 - Power and Flexibility
 - Multiple levels of design description for controlling design implementation.
 - Supports design libraries and creation of reusable components.
 - Provides design hierarchies to create modular designs.
 - A single language for both design and simulation.
 - Device-Independent Design
 - Permits to create a design prior to device determination for implementation.
 - Permits multiple styles (behavioral, structural) of design description.
 - A design description may be implemented in many device architectures.
 - Allows the designer to concentrate on the design, instead of a device architecture for optimization of performance and utilization.

- ... VHDL provides the capabilities of;
 - Portability
 - A design description can be taken from one simulator/synthesizer/platform to an other.
 - VHDL design descriptions can be used in multiple projects.
 - Benchmarking
 - Device-independent design and portability allows to benchmark a design using different device architectures, and different synthesis tools. So that, one can evaluate the results and chooses the device that best fits the design requirements, or chooses the synthesis tool that gives the best quality.
 - Quick Time-to-Market and Low Cost
 - VHDL and programmable logic pair facilitate a speedy design process.
 - Designs are described quickly in VHDL and PLD eliminates NRE costs and facilitates quick design iterations by VHDL synthesis.

- ... VHDL provides the capabilities of;
 - ASIC Migration
 - ASIC vendor takes the design description in VHDL.
- Shortcomings
 - The logic implementations created by synthesis tools may be inefficient.
 - The quality of synthesis varies from tool to tool.

- A digital system is modeled and designed in VHDL by the topdown design approach.
- A VHDL design consists of separate design units each of which is compiled and saved in library. The basic two design source units are
 - Entity
 - Describes the design's interface signals and represents the most basic building block in a design.
 - Architecture
 - Describes the design's behavior.

Entity

 Defines a component name, inputs/outputs connections and related declarations.

```
entity abc4 is
    port ( a, b : in bit;
        c : out bit );
end abc4;
```

Architecture

 Describes the behavior, interconnections, and components of a design entity. Includes <u>concurrent</u> statements and structure.

```
architecture arch2 of abc4 is
begin
  c <= (a xor b) and a;
end arch2;</pre>
```

- Entity Port Modes
 - In: Data flows only into the entity.
 - Out: Data flows only from its source to the output port of the entity.
 - **Buffer**: Similar to mode "out" port, except that it allows internal feedback.
 - Inout: Used for bi-directional signals, which allows data to flow into or out of entity. It also allows internal feedback.

Example: 4-bit Equality Comparator -- eqcomp4 is a four bit equality comparator library ieee; use ieee.std logic 1164.all; entity eqcomp4 is port (a, b : in std_logic_vector(3 downto 0); equals: out std logic); -- equals is active "high" end eqcomp4; architecture dataflow of eqcomp4 is begin equals <= '1' **when** (a=b) **else** '0'; end architecture dataflow;

• Same Example (architecture part):

```
architecture behavioral of eqcomp4 is
begin
process (a,b)
begin
    if a = b then equals <= '1';
        else equals <= '0';
    end if;
end process;
end architecture;</pre>
```

• Same Example (architecture part):

```
architecture behavioral of eqcomp4 is
begin
label: process (a,b)
begin
    equals <= '0';
    if a = b then equals <= '1';
    end if;
end process label;
end architecture;</pre>
```

• Same Example (architecture part):

```
architecture boolean_dataflow of eqcomp4 is
begin

equals <= not(a(0) xor b(0))
    and not(a(1) xor b(1))
    and not(a(2) xor b(2))
    and not(a(3) xor b(3));
end architecture boolean_dataflow;</pre>
```

• Same Example (including components):

```
component xnor2 port (a,b : in std logic; z : out std logic); end component;
component and 4 port (a,b,c,d : in std logic; z : out std logic); end component;
architecture structural of eqcomp4 is
signal x : std logic vector(3 downto 0);
begin
u0: xnor2 port map (a(0), b(0), x(0));
u1: xnor2 port map (a(1), b(1), x(1));
u2: xnor2 port map (a(2), b(2), x(2));
u3: xnor2 port map (a(3), b(3), x(3));
u4: and4 port map (x(0), x(1), x(2), x(3), equals);
end architecture boolean dataflow;
```

- VHDL architectures are generally categorized in styles of;
 - Behavioral:
 - State machines
 - Sequential descriptions
 - Test benches
 - High level specifications
 - Data flow: implies a structure and behavior
 - Arithmetic operations
 - Concurrent signal assignment
 - Register transfers
 - Structural: defines interconnections of components
 - Physical information
 - Hierarchy of gates
 - Boolean equations

Behavioral style architecture

```
architecture my_arch of andgate is
begin
    process (a,b)
    begin
        if a = '1' and b = '1' then c <= '1' after 1ns;
              else c <= '0' after 1ns;
        end if;
    end process;
end my_arch;</pre>
```

Dataflow style architecture

```
architecture my_dataflow of xor2 is
begin
    c <= a xor b after m;
-- m is a parameter of delay defined in the entity of xor2
-- as generic ( m : time := 1.0ns);
end my_dataflow;</pre>
```

• Structural style architecture

```
entity comparator is
  port (a, b: in bit;
          c: out bit);
end comparator;
architecture my structure of comparator is
signal i : bit; -- defines internal signal named as i.
component xor2 port (x, y : in bit; z : out bit); end component;
component inv port (x : in bit; z : out bit); end component;
begin
  c1 : xor2 port map (a, b, i); -- instance name is c1.
  c2: inv port map (i, c);
end my structure;
```

Data Objects

- They hold values of specified types. They belong to four classes;
 Constants, Signals, Variables, Files
- Constant
 - Holds a value that can not be changed within a design description.
 - **constant** width: integer := 8;
- Signals
 - Represent wires and also state of memory elements.
 - The symbol "<=" is used to indicate signal assignment.
 - signal count : bit_vector (3 downto 0);
- Variables
 - Used only in processes and sub-programs.
 - Used for computational purposes during synthesis.
 - The symbol ":=" is used for variable assignment.
- variable result : std_logic := '0';
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- Alias
 - Not a data object.
 - An alternate identifier for an existing object.
 - alias top_addr : std_logic_vector (3 downto 0) is addr (31 downto 28);
- Data Types
 - Enumeration type is a list of values that an object of that type may have.
 - type states is (idle, preamble, data, jam, error);
 signal current_state : states;
 - type boolean is (FALSE, TRUE); -- already defined by IEEE 1076.
 - **type** bit **is** ('0', '1'); -- already defined by IEEE 1076.

- ... Data Types
 - ... Enumeration type

```
type std_ulogic is ('U', -- uninitialized
'X', -- forcing unknown
'0', -- forcing 0
'1', -- forcing 1
'Z', -- high impedance
'W', -- weak unknown
'L', -- weak 0
'H', -- weak 1
```

-- this type is already defined in IEEE 1164.

'-'); -- don't care

• To use these already defined types, place the following before an entity declaration; **library** ieee;

use ieee.std logic 1164.all

- ... Data Types
 - Integer type is supported in the range $-(2^{31} 1)$ to $(2^{31} 1)$. variable a : integer range -255 to 255;
 - Array type
 type word is array (15 downto 0) of bit;
 signal my bus: word;

```
type table_8x4 is array ( 0 to 2, 0 to 3 ) of bit;

constant ex_or : table_8x4 := ("0000", "0011", 1001");
```

- ... Data Types
 - Record type has multiple elements of different types.

```
type iocell is record

buffer_inp : bit_vector ( 7 downto 0 );
enable : bit;
buffer_out : bit_vector ( 7 downto 0);
end record;
signal busa, busb, busc : iocell;
signal vec : bit_vector( 7 downto 0 );
busa.buffer_inp <= vec;
busb.enable <= '1';
busc <= busb;</pre>
```

Sequential Statements

- They are found in a process, function, or procedure.
- The collection of statements that make up a process constitutes a concurrent statement.
- Electronic systems are concurrent and so are processes. If a design has
 multiple processes then these processes are concurrent with respect to one
 another and to other concurrent statements within the architecture.
- Inside a process, signal assignment is sequential from a simulation standpoint. The order in which signal assignments are listed does affect how logic is synthesized.

```
... Sequential Statements
                                                     ... Sequential Statements
     – example
                                                       – example
          signal step: std logic;
                                                               a name: process (addr)
          signal addr: std logic vector(7 downto 0);
                                                               begin
                                                               if addr > X"0F" then step \leq '1';
          a name : process (addr)
                                                                               else step <= '0';
             begin
                                                               end if;
                     step <= '0';
                                                               end process;
                     if addr > X"0F" then step <= '1'; - example
                     end if;
                                                               a name : process (addr)
             end process;
                                                               begin
                                                               if addr > X"0F" then step <= '1';
                                                               end if;
                                                            -- else step retains its value.
                                                            -- This is referred to as implicit
                                                               memory.
                                                               end process;
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```

```
... Sequential Statements
 – example
 process (addr)
 begin
    case addr is
      when "001" => decode <= X"11";
      when "111" => decode <= X"42";
      when "101" => decode <= X"88";
      when others => decode <= X"00";
    end case;
 end process;
```

```
Synchronous Logic
 example: D-FF
 library ieee,
 use ieee.std logic 1164.all
 entity dff is port (d, clk : in std logic,
                    q : out std_logic);
 end dff;
 architecture example of dff is
 begin
    process(clk)
    begin
      if clk'event and clk ='1' then q <= d;
      -- implicit memory for q.
      end if;
    end process;
 end example;
```

\mathbf{VHDL}

```
Three-State Buffers and
Bi-directional Signals
 - example:
 entity ali is port
 (count : buffer std logic vector(7 downto 0));
 end ali;
 -- one of the processes in the architecture is
 my buffer: process(oe,count)
    begin
      if oe='0' then count \leq= (others => 'Z');
       else count <= counter;</pre>
 -- counter is the output of a counter somewhere
 -- in the architecture.
       end if;
    end process;
```

```
... Three-State Buffers and
Bi-directional Signals
 – example:
 entity my port is port
 (count io : inout std logic vector(7 downto 0));
 end my port;
 counting: process (clk) begin
 if clk'event and clk='0' then
    if load='1' then count <= count io;
    elsif enable='1' then count <= count + 1;
    end if;
 end process;
 outputting: process (oe, count) begin
    if oe='0' then count io \leq= (others => 'Z');
    else count io <= count;
    end if;
 end process;
```

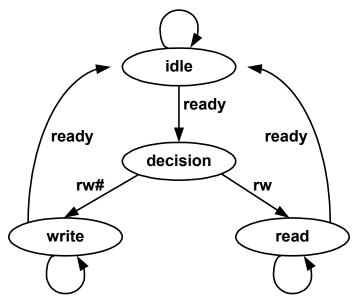
```
Loops
 They are used to implement repetitive
    operations; consist of either "for"
    loops or "while" loops.

    example: Resetting a FIFO using

    "while" loop.
 reg array: process(rst, clk)
 variable j: integer := 0;
 begin
    if rst='1' then
      while j < 7 loop
         fifo(j) \le (others = >'0');
         j := j + 1;
      end loop;
    else . . . . .
```

```
... Loops
 example: Resetting a FIFO using "for"
    loop.
 reg array: process(rst, clk)
 begin
    if rst='1' then
       for j in 7 downto 0 loop
         if j = 4 then next; -- don't reset fifo(4)
         else fifo(j) \leq (others =>'0');
         end if:
       end loop;
    else . . . . .
```

- State-Machine Design
 - Example

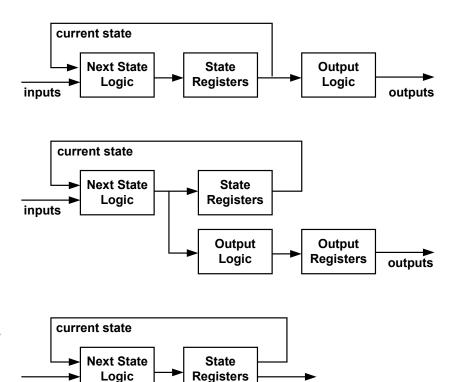


<u>state</u>	<u>outputs</u>	
	<u>oe</u>	we
idle	0	0
decision	0	0
write	0	1
read	1	0

```
... State-Machine Design
architecture state_machine of example is
type statetype is (idle,decision,read,write);
signal present_state, next_state : state_type;
begin
my machine : process(present state,rw,ready)
begin
    case present state is
    when idle =>
           oe<='0';
           we<='0';
           if ready='1' then next_state<= decision;</pre>
                       else next state<= idle;
           end if;
```

```
... State-Machine Design
                                                  ... State-Machine Design
when decision =>
                                                  when write => oe<='0'; we<='1';
       oe<='0':
                                                         if ready ='1' then next state<= idle;
       we<='0';
                                                                     else next state<= write;</pre>
       if rw = '1' then next state<= read;
                                                         end if;
                                                  when others => oe<='0'; we<='0';
                 else next state<= write;
       end if;
                                                                  next state <= idle;
when read =>
                                                  end case;
       oe<='1':
                                              end process;
       we<='0';
                                              state clock : process(clk)
       if ready ='1' then next state<= idle;
                                              begin
                                                  if clk'event and clk ='1' then
                   else next state<= read;
       end if:
                                                         present state <= next state;
                                                  end if:
                                              end process;
                                              end state machine;
```

- ... State-Machine Design
 - Outputs are decoded from state bits combinatorially
 - Clock to output delay is high.
 - Outputs are decoded in parallel output registers
 - Clock to output delay is minimum
 - Operating frequency is reduced.
 - Outputs are encoded within state bits
 - Clock to output delay is minimum
 - Operating frequency is maximum
 - Less macro-cells
 - Time and effort are needed for encoding
 - Debugging is harder



outputs

inputs

- ... State-Machine Design
 - One-Hot Encoding
 - Technique that uses n flip-flops to represent a state-machine with n states.
 - Each state has its own flip-flop.
 - Only one flip-flop is "hot" (holds a '1') at any given time.
 - Depending on the target device architecture, it may require less macro-cells.
 - More flip-flops are required.
 - Simple and faster output decoding logic.
 - Example: One-Hot encoding

<u>state</u>	sequential encoded	One-Hot encoded
a b c	000 001 010	$\begin{array}{c} 00000001 \\ 00000010 \\ 00000100 \end{array}$

...