ECE 3724 Test #1 – Spring 2005/Reese Solution

Last 128 locations of bank 15 are the special function registers.

Part I: (20 pts)

- a. The PIC18 has something called the ACCESS bank. These locations are:
 - 1. The locations in bank 0 and the locations of bank 15.
 - 2. The last 128 locations of bank 0, and last 128 locations of bank 15.
 - 3. The first 128 locations of bank 0, and the first 128 locations of bank 15.
 - 4. The first 128 locations of bank0, and the last 128 locations of bank 15.
 - 5. The last 128 locations of bank0, and the first 128 locations of bank 15.
 - 6. Only the locations of bank 0.
- b. Give the machine code in **HEX** for the instruction:

movff 0x150, 0x2A3

Requires two instruction words: 0xC150 0xF2A3

c. The machine code 0x9745 represents instruction? (use 'w' or 'f' for the destination, and 'ACCESS' or BANKED to represent the value of the a bit)

 $0x9745 \rightarrow 1001\ 0111\ 0100$ 0101, first FOUR bits indicate the bcf instruction bcf 1001 bbba ffff ffff, \rightarrow bcf 0x45,3, BANKED (a =1)

d. For a 25 MHz clock, how long does it take to execute the following instructions? (give the answer in microseconds)

movf 0x013,w addwf 0x020,f

The movf and addwf each require 1 instruction cycle, so: clocks = 2 instruction cycles * 4 clocks per instruction cycle = 8 clocks.

1/25MHz = 1/(25e6) = 0.04 e -6 = 0.04 us (microseconds). 0.04 us * 8 clocks = 0.32 us (microseconds)

- e. Circle the true statement (non-volatile means contents are retained when power is removed; volatile means contents are lost when power is removed).
 - 1. On the PIC18, program memory is volatile and data memory(file registers) is volatile.
 - 2. On the PIC18, program memory is non-volatile and data memory (file registers) is volatile
 - 3. On the PIC1 program memory is volatile and data memory(file registers) is non-volatile.
- 4. On the PIC18, program memory is non-volatile and data memory(file registers) is non-volatile.

data registers are where temporary values are stored so volatile, program memory is non-volatile so that when power is removed, the program memory contents will be retained. When the PIC powers up, it needs something to execute, the program instructions are retained by the non-volatile program memory.

1/3/1/4/A 1/3/41'	register has the value 0xE3 in it, and that 'C, Z are both '0'.
Part II. (35 pts) Assume the above memory co at the START of each instruction.	ntents, W register value, initial C,Z values
a. bcf 0x04A, 3	Circle one: W dest. Reg. file dest.
$7654 \ 3210$ $[0x4A] = 0x4F = 0100 \ 1111 \ (clear bit 3)$ new value $[0x4A] = 0100 \ 0111 = 0x47$,	New value (hex) 0x47 C_flag :_0 , Z flag:0_
b. iorlw 0x48 literal 0x48 = 0100 1000 OR operation W = 0xE3 = 1110 0011 new W = 1110 1011 = 0xEB, c. rlcf 0x04B, f	Circle one: W dest. Reg. file dest. New value (hex) _0xEB_ C_flag :_0_ , Z flag:_0_ Circle one: W dest. Reg. file dest.
$[0x4B] = 0x1D= 0001 1101 (\leftarrow left shift)$ new $[0x4B] = 0011 1010 = 0x3A$, MSB goes into C-flag, so C=0	New value (hex) _0x3A C_flag:_0_ , Z flag:_0_
d. addwf 0x04B,f	Circle one: W dest. Reg. file dest. New value (hex) _0x00_ C_flag :_1_ , Z flag:_1_
[0x4B] = $0x1D$ (1 st digit is 13+3=16, so 0). W = + $0xE3$ (2 nd digit is 14+1+1(carry)=16,0 new W = $0x00$ C = 1 because of carry out of 2 nd digit, Z=1 because 8-bit value is $0x00$.	se
e. subwf 0x049, f	Circle one: W dest. Reg. file dest.

New value (hex) $_0x1D$ __ C_flag :_0__ , Z flag:_0_

[0x49]

new [0x49]

= 0x00= - 0xE3

0x1D C = 0 because of borrow out of MSB

=

(45 pts) PART III. Convert the following C code fragments to PIC18 assembly.

Variable locations are: i is data location 0x000, j is data location 0x001, k is data location 002. Assume the BSR has a 0x0 value in it initially.

unsigned char i,j,k;

```
a. (6 \text{ pts})
 k = (i >> 1) + 50;
```

```
; one solution
bcf STATUS,C ;C_flag=0
rrcf i,w ; w = i>>1
addlw 0x32 ;w = w+50
movwf k ;k = w
```

```
b. (10 pts)
    if ((i == 0) & (j != 0) {
      k--; j++;
                 ; one solution
                 movf i,f
                                 ;test i
                       end if
                                 ;skip if i is non-zero
                 bnz
                               test j;
                       j,£
                 movf
                       end_if
                                skip if j is zero;
                 bz
                 ;; only get here is i is zero and j is nonzero
                 decf k,f
                                 ;k--
                 incf
                       j,£
                                 ;j++
               end if
                ....rest of code....
```

```
c. (7 \text{ pts})
k = i - j - 1;
; one solution
movf \quad j,w \quad ; \quad w = j
subwf \quad i,w \quad ; \quad w = i - j
movwf \quad k \quad ; \quad k = w
decf \quad k,f \quad ; \quad k = k - 1
```

```
; a common error

movf j,w ; w = j

subwf i,w ; w = i-j

sublw 1

movwf k ; k = w

Some students used this thinking
```

Some students used this thinking this does w - 1. It does NOT; instead, it computes 1 - w. So the computation implemented above is actually k = 1 - (i-j)

```
; an incorrect solution

decf j,w ; w = j - 1
subwf i,w ; w = i - w
movwf k ; k = w

This is incorrect.
i-j-1 = i-(j+1)
i-j-1 is NOT equal to i-(j-1)
A correct solution using the above approach is:
   ;correct solution
   incf j,w ; w = j + 1
   subwf i,w ; w = i - w
   movwf k ; k = w
```

```
d. (10 \text{ pts})
while (i < k) \{
k = k << 2;
\}
```

the comparison (i < k) is actually (k > i), so do i - k as test. The TRUE case is C = 0 (borrow as we subtract a larger number from smaller number); the FALSE case is C = 1 (no borrow).

Use the FALSE case for the branch as we want to skip around the loop body

```
loop top
 movf
        k,w
  subwf i,w
                  ; i - k
        loop end ; skip if C=1,k > i is FALSE
 bc
 bcf
        STATUS, C
 rlcf
        k,f
 bcf
        STATUS, C
 rlcf
        k,f
        loop top ; this is a LOOP, jump back to top
 bra
loop end
  ....rest of code....
```

e. (5 pts) Write a sequence of assembly code instructions that will clear the MSb (most significant bit) and LSb (least significant bit) of variable k.

```
; one solution
bcf k,0 ; clear LSB
bcf k,7 ; clear MSB
```

```
;another solution
movlw 0x7E ; clear LSB
andwf k,f k = k & 0x7E, clears LSb, MSb
```

f. (7 pts) Write a PIC18 instruction sequence that does

$$k = (i | j) & 0xA0$$

```
; one solution
movf i,w ; w = i
iorwf j,w ; w = w | j
andlw 0xA0 ; w = w & 0xA0
movwf k ; k = w
```

```
; another solution
movff i,k ; k = i
movf j,w
iorwf k,f ; k = k | j
movlw 0xA0 ; w = 0xA0
andwf k,f ; k = k & w
```