

$$a) X(t) = A + B \cos(\omega_0 t + \Theta)$$

$$E(A) = 0; E(B) = 0; \text{Var}(A) = E(A^2) = 3; \text{Var}(B) = E(B^2) = 4$$

A ve B bağımsız

$$E(A \cdot B) = E(A) \cdot E(B) = 0$$

$$f(\Theta) = \begin{cases} \frac{1}{\pi} & 0 < \Theta < \pi \\ 0 & \text{diğer} \end{cases}$$

$$E[X(t)] = E[A + B \cos(\omega_0 t + \Theta)] = E(A) + E(B) \cdot E(\cos(\omega_0 t + \Theta)) = 0$$

$$\begin{aligned} R_{XX}(t, t+\tau) &= E[(A + B \cos(\omega_0 t + \Theta))(A + B \cos(\omega_0 t + \omega_0 \tau + \Theta))] \\ &= E(A^2) + E[A \cdot B \cos(\omega_0 t + \omega_0 \tau + \Theta)] + E[B A \cos(\omega_0 t + \Theta)] \\ &\quad + E[B^2 \cos(\omega_0 t + \Theta) \cos(\omega_0 t + \omega_0 \tau + \Theta)] \\ &= 3 + 4 E[\underbrace{\cos(\omega_0 t + \Theta)}_{\pi} \underbrace{\cos(\omega_0 t + \omega_0 \tau + \Theta)}_{\theta}] \end{aligned}$$

$$= 3 + \frac{4}{2} E[\cos(\omega_0 t + \Theta - \omega_0 t - \omega_0 \tau - \Theta) + \cos(\omega_0 t + \Theta + \omega_0 t + \omega_0 \tau + \Theta)]$$

$$= 3 + \frac{4}{2} \{ E[\cos(-\omega_0 \tau)] + E[\cos(2\omega_0 t + \omega_0 \tau + 2\Theta)] \}$$

$$= 3 + 2 \cos(\omega_0 \tau) + 2 \int_0^\pi \cos(2\omega_0 t + \omega_0 \tau + 2\Theta) \frac{1}{\pi} d\Theta$$

$$= 3 + 2 \cos(\omega_0 \tau) + \frac{4}{\pi} \left[ \sin(2\omega_0 t + \omega_0 \tau + 2\Theta) \Big|_0^\pi \right]$$

$$= 3 + 2 \cos(\omega_0 \tau) = R_{XX}(\tau)$$

$X(t)$  sürekli geniş anlamda durağan süreçtir.

$$b) Y(t) = \sin(\omega_0 t + \Theta)$$

$$R_{XY}(t, t+\tau) = E[\{A + B \cos(\omega_0 t + \Theta)\} \{\sin(\omega_0 t + \omega_0 \tau + \Theta)\}]$$

$$= E[A] E[\sin(\omega_0 t + \omega_0 \tau + \Theta)] + E[B \cos(\omega_0 t + \Theta) \sin(\omega_0 t + \omega_0 \tau + \Theta)] = 0$$