

v> Box Plot:-

$X = \{x_1, \dots, x_n\} \rightarrow \text{data}$ .

Step 1 :-

Compute  $x_{(1)}$  [minimum one] &  $x_{(n)}$  [maximum one].

Step 2 :-

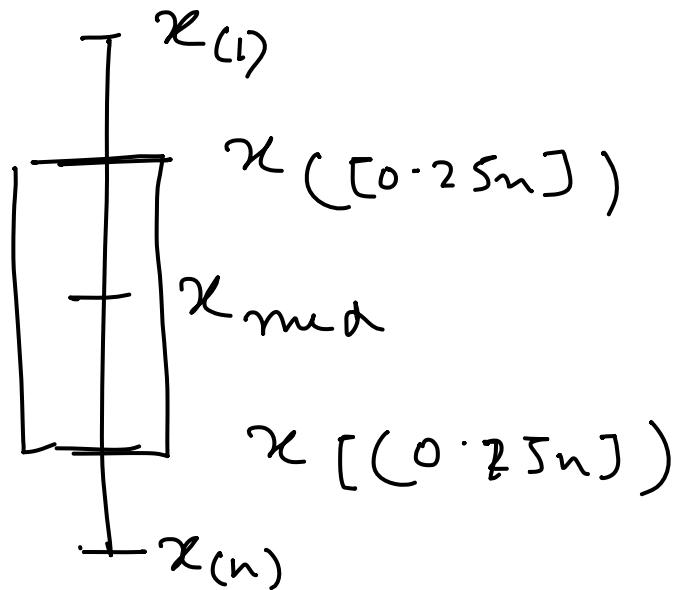
Compute interquartile range [i.e.,  
 $x_{([0.25n])}$  &  $x_{([0.75n])}$ ]

Step 3 :-

Compute median as well.

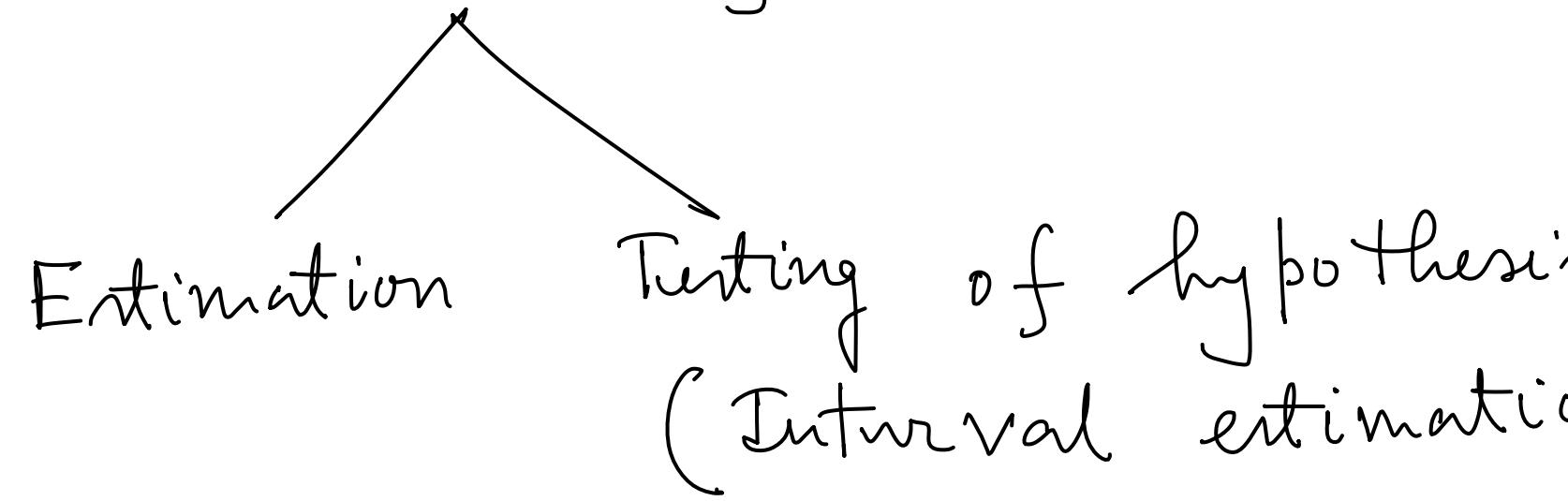
n: Sample size.

Plot



Section 9(Estimation) :-

## Statistical Inference

*included.*  
Estimation

↑

Parametric estimation      Non-parametric estimation (Not included)  
 (The form of the dist<sup>n</sup> is known but the parameters involved in the dist<sup>n</sup> are unknown. We have to estimate the underlying dist<sup>n</sup>/density).

Some basic:-

$x$  : Random variable.

$f(x) = P[x = x]$  → p.m.f. of  $x$  at  $x$ .

$f_x(x)$  : P.d.f. of  $x$  at  $x$ .

$$P[a < x < b] = \int_a^b f_x(x) dx.$$

Parametric estimation:-

Suppose, the population is a member

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of family of p.d.f-s.  $\{f(x; \theta) : \theta \in \mathbb{H}\}$

Here  $\theta$ : parameter (unknown);  $\mathbb{H}$ : Parameter space.

Example:- 1) Normal family :  $\{N(\mu, \sigma^2) : \mu \in \mathbb{R}, \sigma \in \mathbb{R}^+\}$ .

Here  $\theta = (\mu, \sigma^2)$ ,  $\mathbb{H} = \mathbb{R} \times \mathbb{R}^+$

2) Poisson family :  $\left\{ \frac{e^{-\lambda} \lambda^x}{x!} : \lambda > 0 \right\}$ .

Here  $\theta = \lambda$  &  $\mathbb{H} = \mathbb{R}^+$ .

In parametric estimation time we want to estimate the unknown parameter  $\theta$  or any  $f^n$  of  $\theta$  (suppose  $\pi(\theta)$ ); when the <sup>data</sup>  $x_1, x_2, \dots, x_n$  is known to us.

## Our objective :-

To find a "good estimator" of  $\pi(\theta)$  based on the random sample  $(x_1, \dots, x_n)$  obtained from the data dist<sup>n</sup>.

## A few fundamental questions:-

- 1: What is an estimator ?? What is an estimate ??
2. How to find an estimator ??
3. What does it mean by "good" estimator. ??

Answer of 1: Estimator :-  $T_n(x_1, \dots, x_n)$ , which is a f<sup>n</sup>. of  $(x_1, \dots, x_n)$ ,  
is an estimator. When  $x_1 = x_1, \dots, x_n = x_n$  (i.e.  $X = \{x_1, \dots, x_n\}$ ),  
the estimate of  $T_n(x_1, \dots, x_n)$  will be  $T_n(x_1, \dots, x_n)$ .

Example:

Let  $x_1, \dots, x_n \sim N(\mu, 1)$ .

i)  $T_n^{(1)}(x_1, \dots, x_n) = \frac{1}{n} \sum_{i=1}^n x_i$  is an estimator of  $\mu$ .

ii)  $T_n^{(2)}(x_1, \dots, x_n) = \frac{x_1 + x_7}{2}$  is an estimator of  $\mu$ .

iii)  $T_n^{(3)}(x_1, \dots, x_n) = \frac{x_{(3)} + x_{(109)}}{2}$  is an estimator of  $\mu$ .

iv)  $T_n^{(4)}(x_1, \dots, x_n) = 0$  is an estimator of  $\mu$ .

For  $i = 1, \dots, 4$ ,  $T_n^{(i)}(x_1, \dots, x_n)$  is an estimator of  $\mu$ .

Suppose,  $x_1 = 0.37$ ,  $x_2 = 1.12$ ,  $x_3 = 3.79$ ,  $\dots$ ,  $x_{300} = 7.52$ ,

we can estimate  $\mu$  based on each  $T_n^{(i)}(x_1, \dots, x_n)$ .

2) There are a few well-known methods to find an estimator!

Answe  
2<sup>nd</sup> question

- a) Method of Moment.
- b) Maximum likelihood estimation.
- c) Least square estimation.
- d) Least absolute deviation estimation.

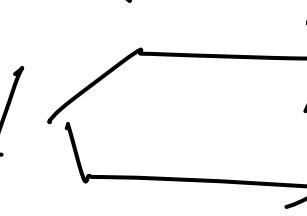
Point estimation:-

$T_n(x_1, \dots, x_n)$  is estimator  $\hat{\theta}$  for

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a given data  $x = \{x_1, \dots, x_n\}$  (of the realization of  $(x_1, \dots, x_n)$ )

estimate the unknown parameter  $\theta$  pointwise.

Point estimation / estimator 

Unbiased estimator  
Consistent estimator -

Remark :-

Unbiased estimation is a finite sample

property of an estimator whereas consistent estimation is (consistency)  
a large sample property of an estimator.

Unbiased estimator :-

$T_n = T_n(x_1, \dots, x_n)$  is said to be an unbiased estimator of  $\theta$  if

$$E(T_n) = \theta \text{ for all } \theta \in \Theta.$$

Set up :-  $x_1, \dots, x_n \sim f(x|\theta)$

$f(x|\theta)$  p.m.f. unknown parameter  
 $f(x)$  p.d.f.  $\theta \in \Theta$  parameter space.

Example:-

Let  $x_1, \dots, x_n \sim N(\mu, 1)$ .

$$T_n^{(1)} = x_1, \quad T_n^{(2)} = \frac{x_1 + x_2}{2}, \quad T_n^{(3)} = \frac{1}{n} \sum_{i=1}^n x_i,$$

$$T_n^{(4)} = 0.7 \times T_n^{(1)} + 0.17 \times T_n^{(2)} + 0.13 \times T_n^{(3)}$$

$$T_n^{(5)} = \frac{1}{n} \sum_{i=1}^n x_i + \frac{5}{n}.$$

Study:- i)  $E[T_n^{(1)}] = E(x_1) = \mu.$

ii)  $E(T_n^{(2)}) = E\left(\frac{x_1 + x_2}{2}\right) = \frac{1}{2} [E x_1 + E x_2] = \frac{1}{2} [\mu + \mu] = \mu.$

iii)  $E(T_n^{(3)}) = \frac{1}{n} \sum_{i=1}^n E(x_i) = \frac{1}{n} \sum_{i=1}^n \mu = \mu.$

iv)  $E(T_n^{(4)}) = 0.7 E(T_n^{(1)}) + 0.17 E(T_n^{(2)}) + 0.13 E(T_n^{(3)}) = 0.7 \times \mu + 0.17 \mu + 0.13 \mu = \mu.$

$$\text{v) } E(T_n^{(s)}) = \mathbb{E} \left[ \frac{1}{n} \sum_{i=1}^n E(x_i) \right] \neq E\left(\frac{5}{n}\right)$$

$$= \frac{1}{n} \sum_{i=1}^n \mu + \frac{5}{n} = \mu + \frac{5}{n}.$$

Remark :-  $T_n^{(s)}$  is NOT an unbiased estimator but  
 as  $n \rightarrow \infty$ ,  $E(T_n^{(s)}) = \mu$ , and hence,  $T_n^{(s)}$  is an asymptotically unbiased estimator.

The construction of  
Remark :-  $\uparrow T_n^{(u)}$  indicates that the u.e. is ~~not~~  
 may NOT be unique. (if  $E(T_n^{(1)}) = \theta$   
 $\Sigma E(T_n^{(2)}) = \theta$ , then

$$E(a_1 T_n^{(1)} + a_2 T_n^{(2)}) = \theta \text{ as long as } a_1 + a_2 = 1.$$