NEW CONTROL SOFTWARE FOR CERBERUS 3D NANOINDENTATION SYSTEM

by

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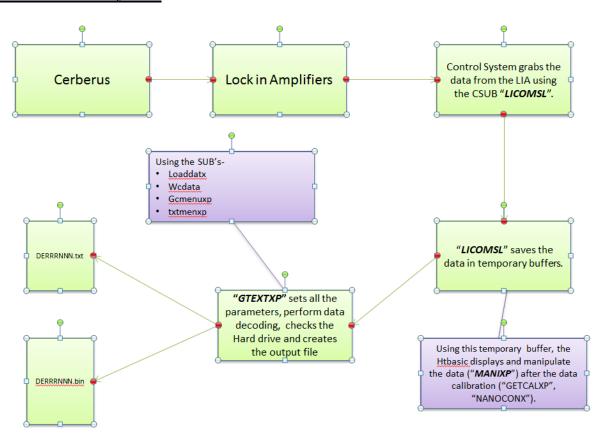
INDIAN INSTITUTE OF INFORMATION TECHNOLOGY DESIGN AND MANUFACTURING JABALPUR

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INTRODUCTION:-

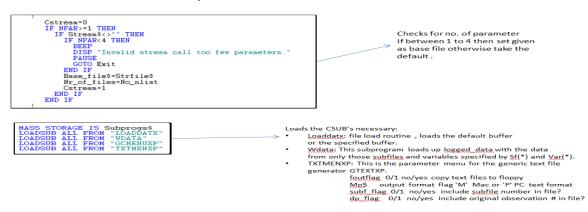
The target of this phase was to dissect the htbasic code and find the data flow in the system. In this phase I also wrote a python script for the text to binary conversion of the data.

Data Flow in the system:



Analysis of HTBASIC code:

Description of Routine "GTEXTXP"



Description of Routine "GTEXTXP" (contd..)

```
Description of Routine "GTE

CREATE Filename$.1

ASSIGN @File TO Filename$;FORMAT ON 
IF Ns<20 THEN Sc(Ns+1)=No+1

BUIfstr5="
FOR I=1 TO Nv-1

OUTPUT Buffstr$ USING "#.K";Buffstr$&Vn$(I)

OUTPUT Buffstr$ USING "A.K";Buffstr$&Vn$(I)

OUTPUT Buffstr$ USING Amask$;Buffstr$

FOR I=1 TO No

IF I=5c(S_f) THEN OUTPUT @File USING Amask$;"

NEXT S_f

Buffstr$="FOR J=1 TO Nv-1

IF R_flag AND (Vn$(J)[1:2]="Di" OR Vn$(J)[1:2]="Lo") THEN

OUTPUT Buffstr$ USING "#.K";Buffstr$&VAL$(PROUND(FNDispl(Logged_data(J,I)).-6))

ELSE

OUTPUT Buffstr$ USING "#.K";Buffstr$&VAL$(PROUND(FNDispl(Logged_data(J,I)).-6))

END IF

END IF
                                                                                                                                                                                                                                                                            Creates an i/o link for filename$
                                                                                                                                                                                                                                                                            Viz. output file
                                                                                                                                                                                                                                                                                                                             This is the part where
             OUTPUT Buffstr$ USING *#.K*; Buffstr$&VAL$(PROUND(FNLoad(Logged_data(J.I)),-6))
END IF
ELSE
                                                                                                                                                                                                                                                                                                                             data is written to the text
                                                                                                                                                                                                                                                                                                                             files.
        ELSE
OUTPUT Buffstrs USING "#,K";Buffstrs&VALs(PROUND(Logged_data(J,I),-12))!4/11/97 bnl
END IF
OUTPUT Buffstrs USING "#,K";Buffstrs&"

IF R, tlag AND (Vns(J)[1;2]="Di" OR Vns(J)[1;2]="Lo") THEN
IF Vns(J)[1;2]="Di" THEN
OUTPUT Buffstrs USING "#,K";Buffstrs&VALs(PROUND(FNDispl(Logged_data(J,I)),-6))
ELSE
OUTPUT Buffstrs USING "#,K";Buffstrs&VALs(PROUND(FNLoad(Logged_data(J,I)),-12))
END IF
        ELSE
OUTPUT Buffstr$ USING "#,K";Buffstr$&VAL$(PROUND(Logged_data(J,I),-12))|4/11/97 bnl
END IF
         END IF
OUTPUT @File USING Amask$; Buffstr$
DISP "Data point ";I
    OUTPOT WRITE USING AMASKS; BUTTSTS
DISP "Data point ";I
NEXT I
NEXT I
PRINTER IS Printer
PRINT "Translated ";Sfile$;" to ";Filename$
OFF ERROR
OFF ERROR
             IGN @File TO *
```

Shows the message

New python code:

```
fromfile:
    init__(self, fileaddress):
    self.fileaddress = fileaddress
ZDisp=[]
ZLoad=[]
Time =[]
ZPha =[]
ZPha =[]
XDisp =[]
XLoad =[]
YLoad =[]
YAmp=[]
XPha=[]
XExc=[]
YAmp=[]
YPha=[]
YPha=[]
Yexc=[]
Channel =[]
def getval(self,line):
   val = []
   char = ''
   for i in range(0, len(line)):
       if line[i] == ',' or line[i] == '\n':
            val.append(char)
            char=''
in range(0, len(line)):
line[i] == ',' or line[i] == '\n':
val.append(float(char))
char=''
```

```
self.YDisp.append(dataset[8])
      self.YLoad.append(dataset[9])
       self.XAmp.append(dataset[10])
       self.XPha.append(dataset[11])
      self.XExc.append(dataset[12])
      self.YAmp.append(dataset[13])
       self.YPha.append(dataset[14])
       self.YExc.append(dataset[15])
def grabdata(self):
       f = file(self.fileaddress)
       header = f.readline()
       self.channel = self.getval(header)
       dataset = []
      while True:
              data = f.readline()
              if len(data) == 0:
                     data = f.readline()
                      if len(data) == 0:
                            break:
                            dataset = self.getvalfloat(data)
                             self.setdata(dataset)
              else:
                     dataset = self.getvalfloat(data)
                      self.setdata(dataset)
def printdata(self):
      print '%10s\t\t%10s\t\t%10s\t\t%10s\t\t%10s\t\t%10s\t\t%10s\t\t\t%10s\t\t
                 %(self.channel[0],self.channel[1],self.channel[2],self.channel[3],self.channel[4],self.channel[5],self.channel[6],self.channel[7])
      print '
       for i in range(0,16):
             \label{lem:condition} $$ (self.2Disp[i],self.2Load[i],self.Time[i],self.2Amp[i],self.2Pha[i],self.ZExcite[i],self.XDisp[i],self.XLoad[7]) $$ (self.2Disp[i],self.2Disp[i],self.XDisp[i],self.XLoad[7]) $$ (self.2Disp[i],self.2Disp[i],self.XDisp[i],self.XLoad[7]) $$ (self.2Disp[i],self.XDisp[i],self.XLoad[7]) $$ (self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XLoad[7]) $$ (self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XLoad[7]) $$ (self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],self.XDisp[i],s
       % (self.channel[8], self.channel[9], self.channel[10], self.channel[11], self.channel[12], self.channel[13], self.channel[14], self.channel[14]
       for i in range(0,16):
              print \ '\$10s\t\t\$10s\t\t\$10s\t\t\$10s\t\t\$10s\t\t\$10s\t\t\t\$10s\t\t\t
                         %(self.YDisp[i],self.YLoad[i],self.XAmp[i],self.XPha[i],self.XExc[i],self.YAmp[i],self.YPha[i],self.YExc[i])
```

RESULT & DISCUSSION:-

- 1. After deep evaluation of the available options due to its slight advantage over Matlab and increasing use in the scientific community, Pythonxy is selected as the final environment.
- 2. Following points about the "XPMASTER" code were identified:
 - a. We must check whether it is "rerun" of the "XPMASTER" to do calibration.
 - b. Identify the printer status initially, and make it available throughout the program.
 - c. Select the appropriate drivers for the printer; in this case it is "HP-PC".
 - d. Perform the appropriate test to ensure that appropriate displacement card, load card and motor card are present.

NEXT OBJECTIVE:-

The objectives of the next phase in the project are as follows-

To fully explore the htbasic code and create the interaction model between different subroutines.

To study the raw binary data from the Cerberus system and write a python code to convert it into the desired txt format.