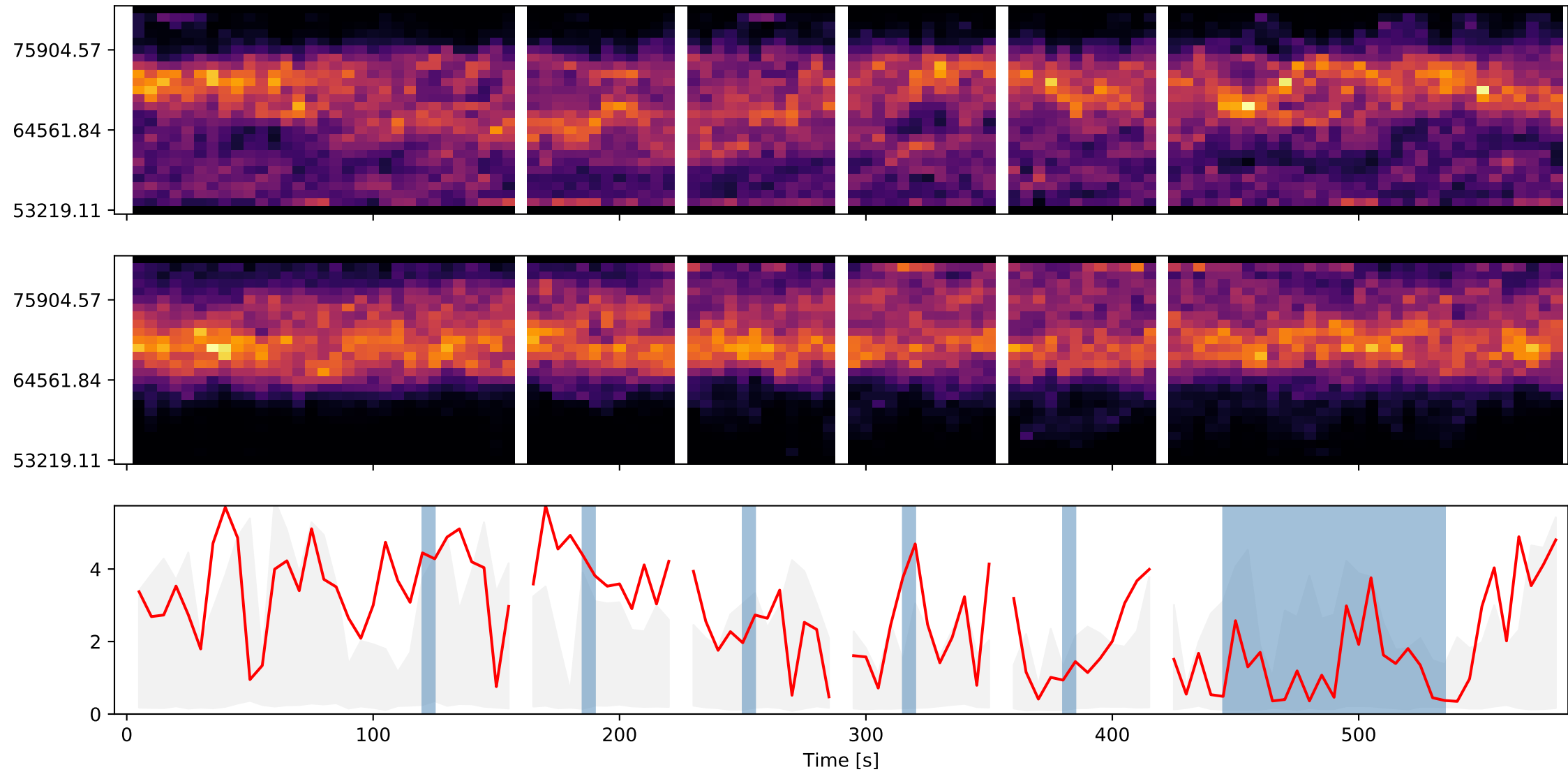
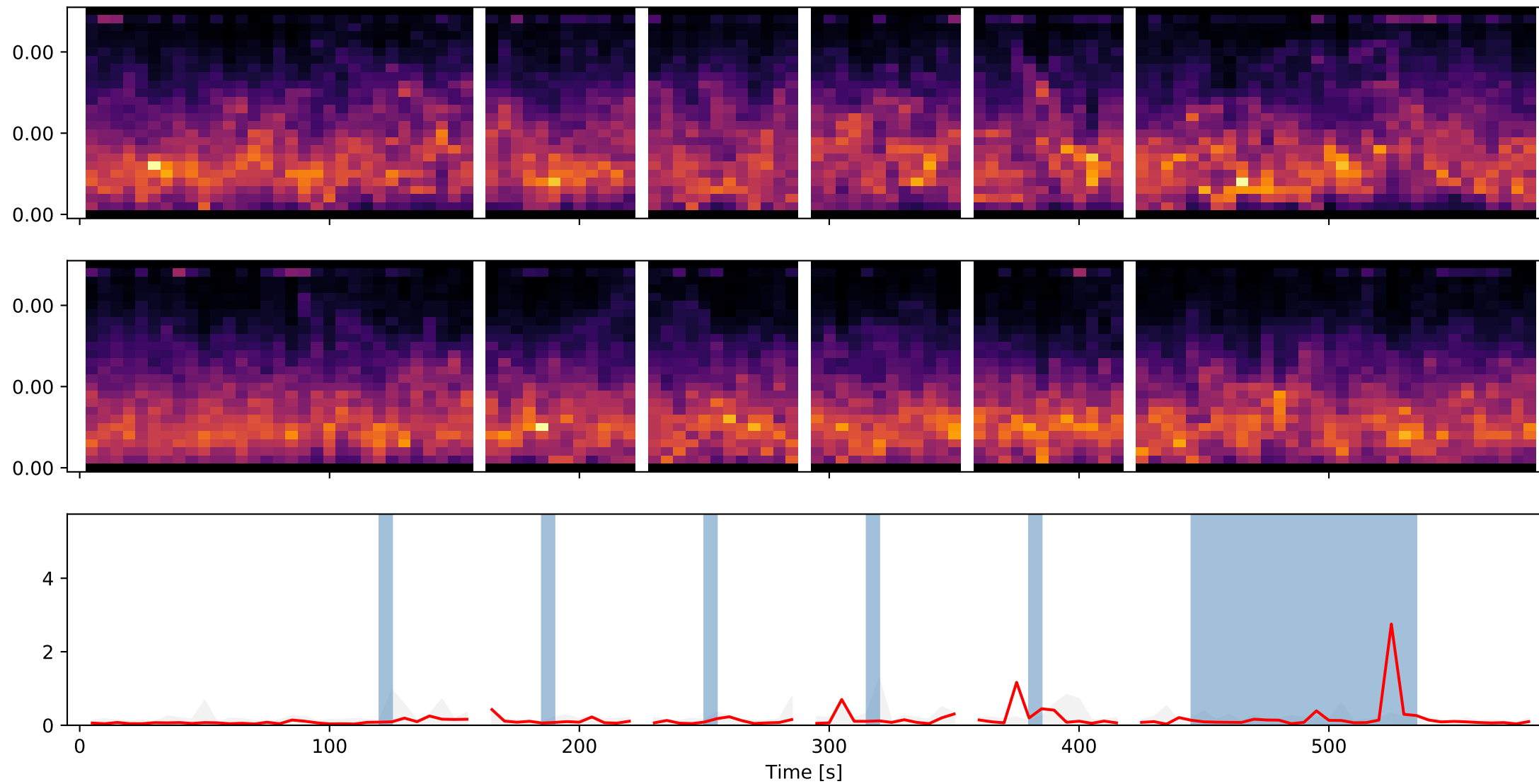


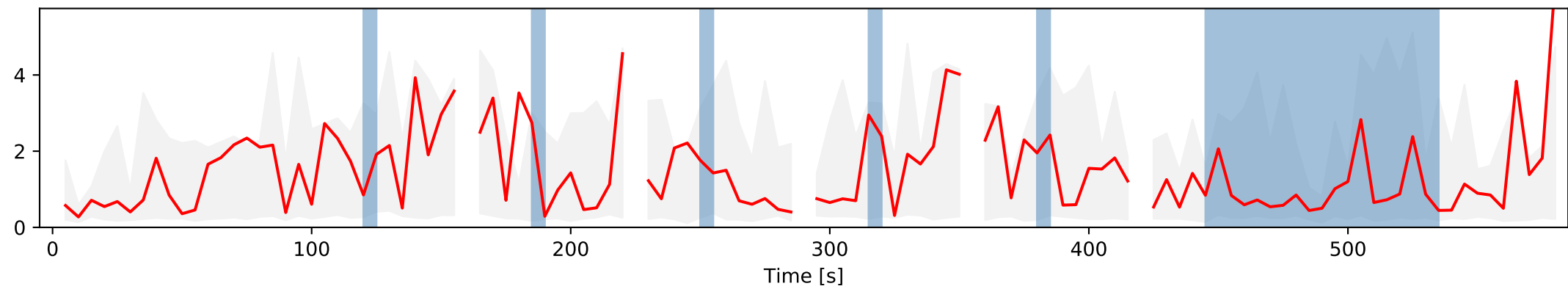
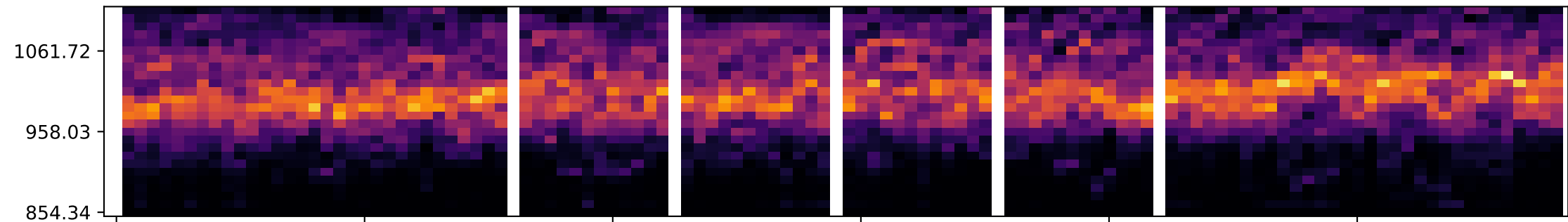
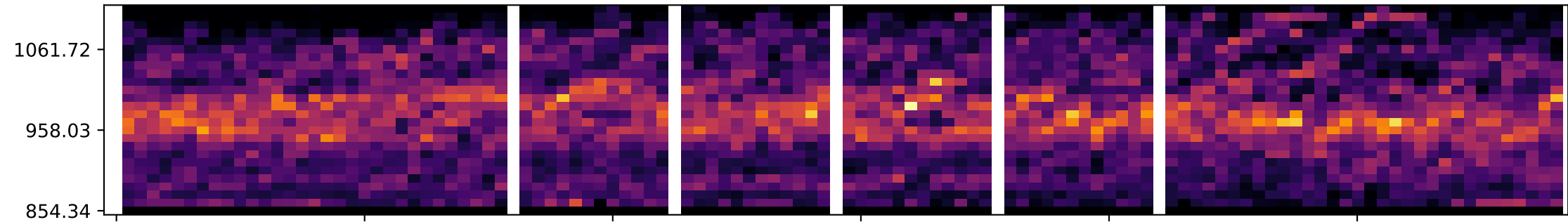
area



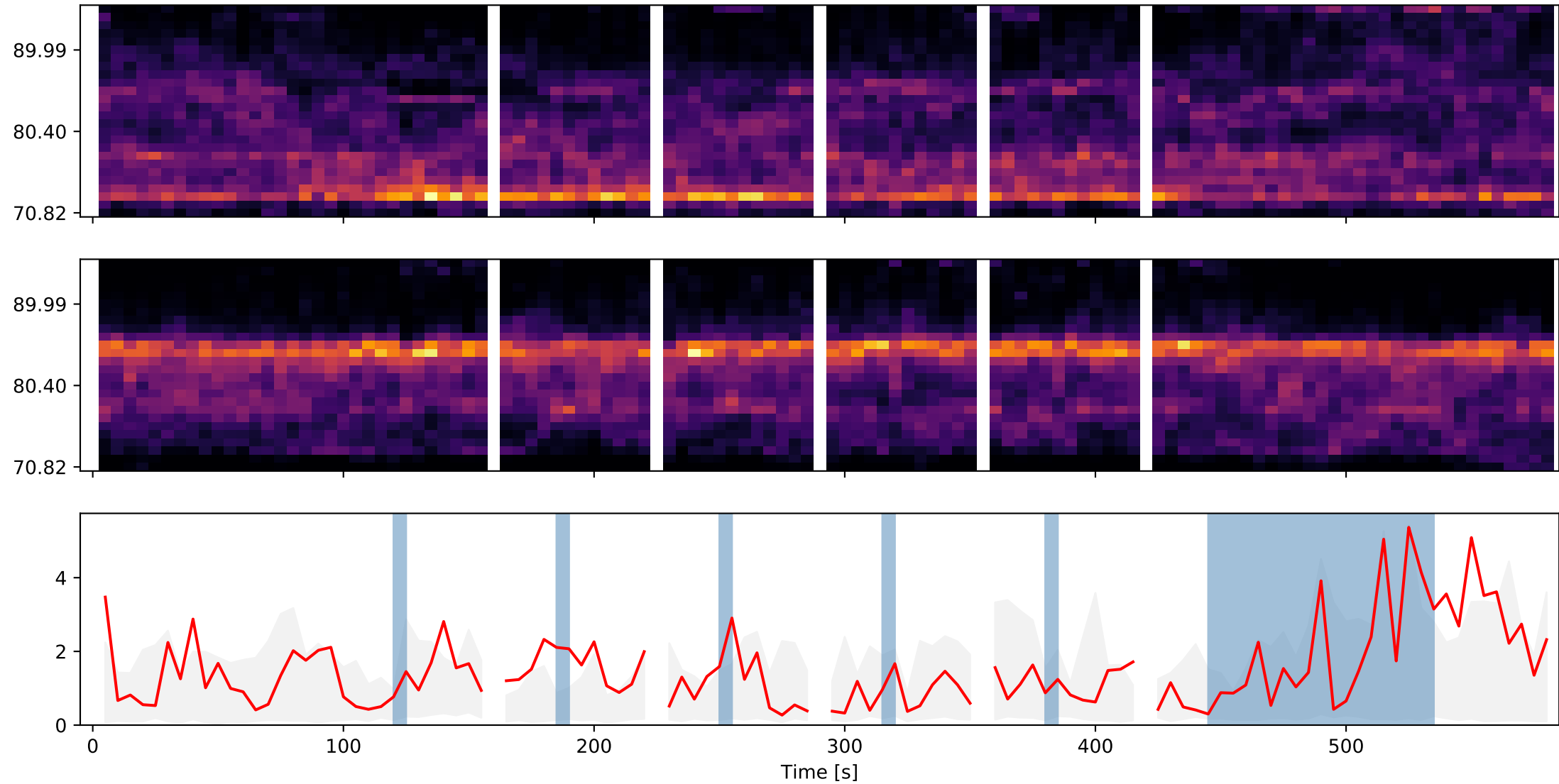
curvature_std_tail



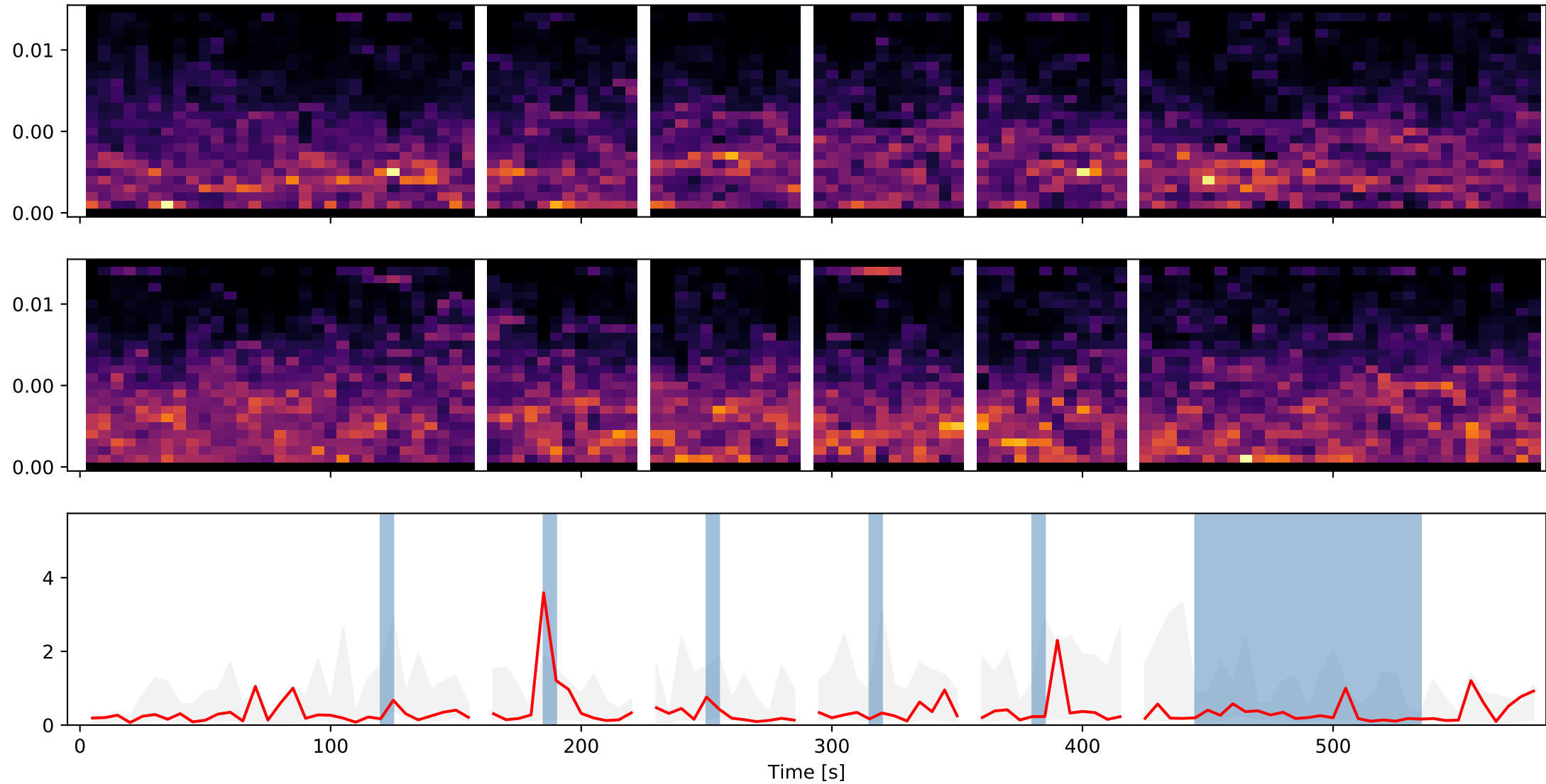
length



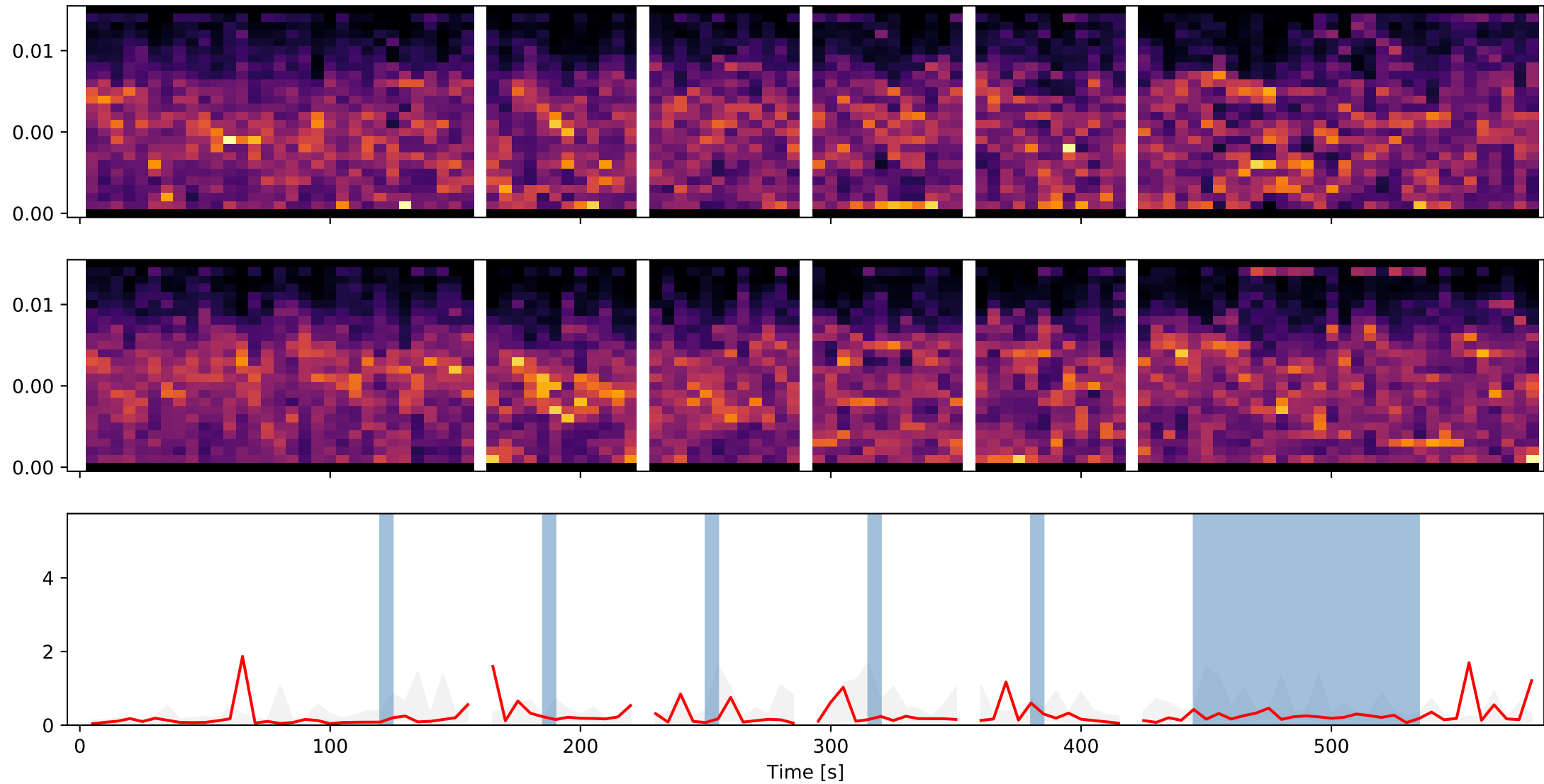
width_midbody



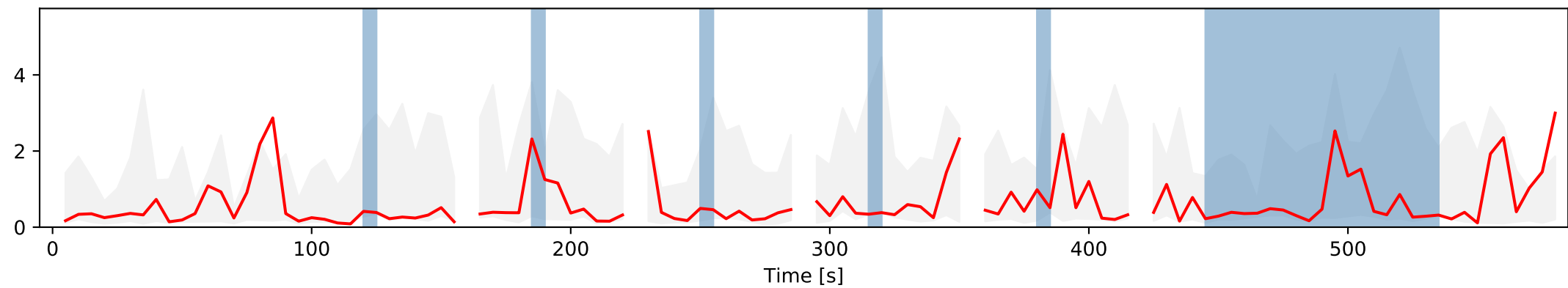
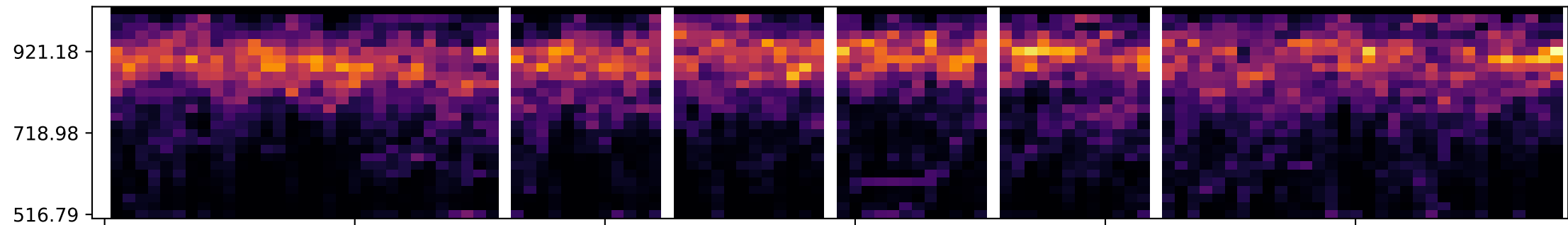
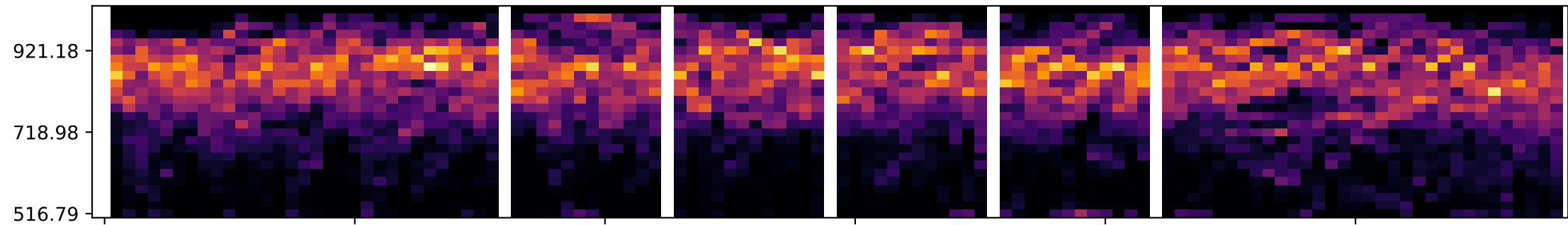
curvature_mean_midbody



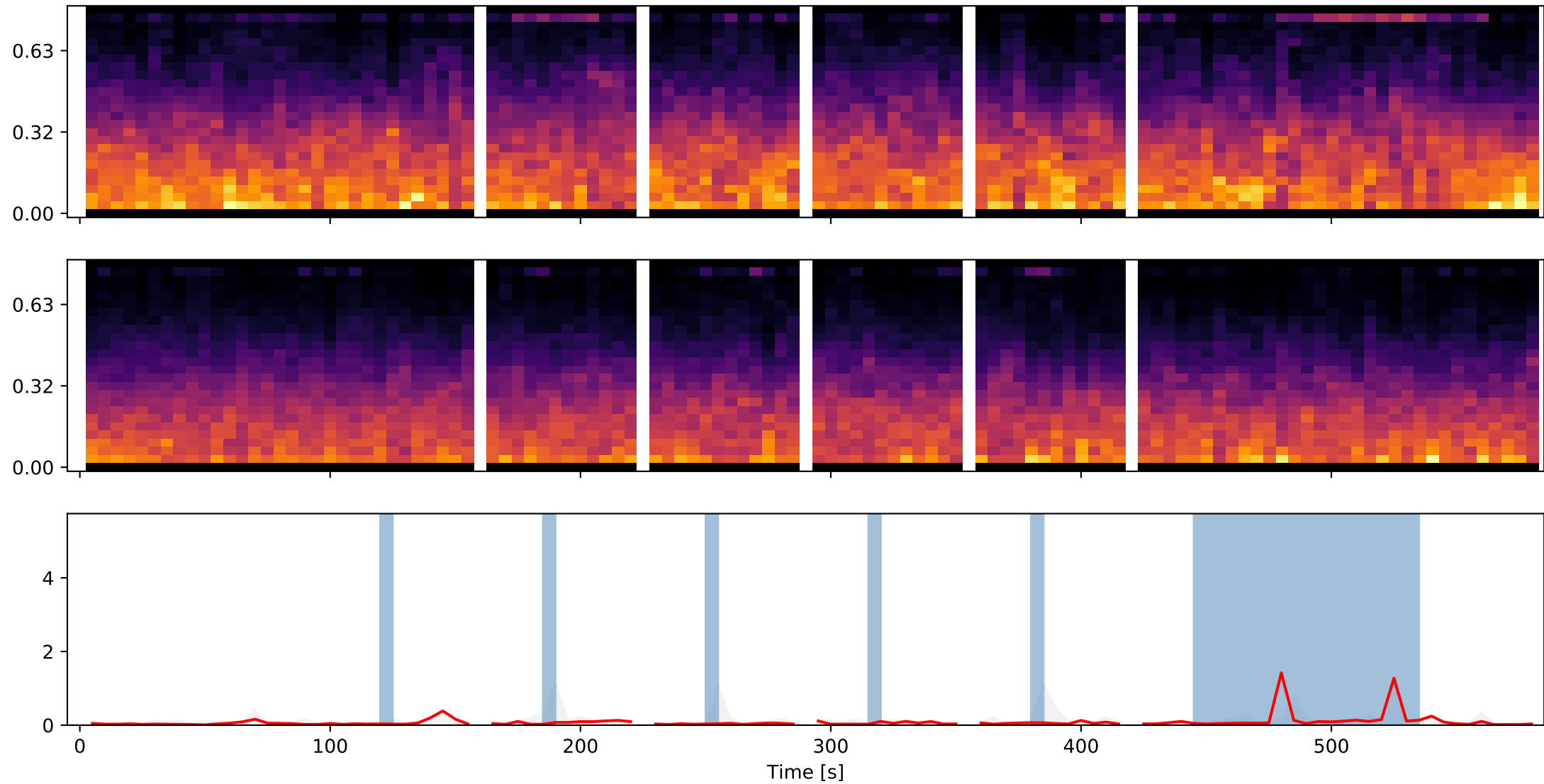
curvature_mean_neck



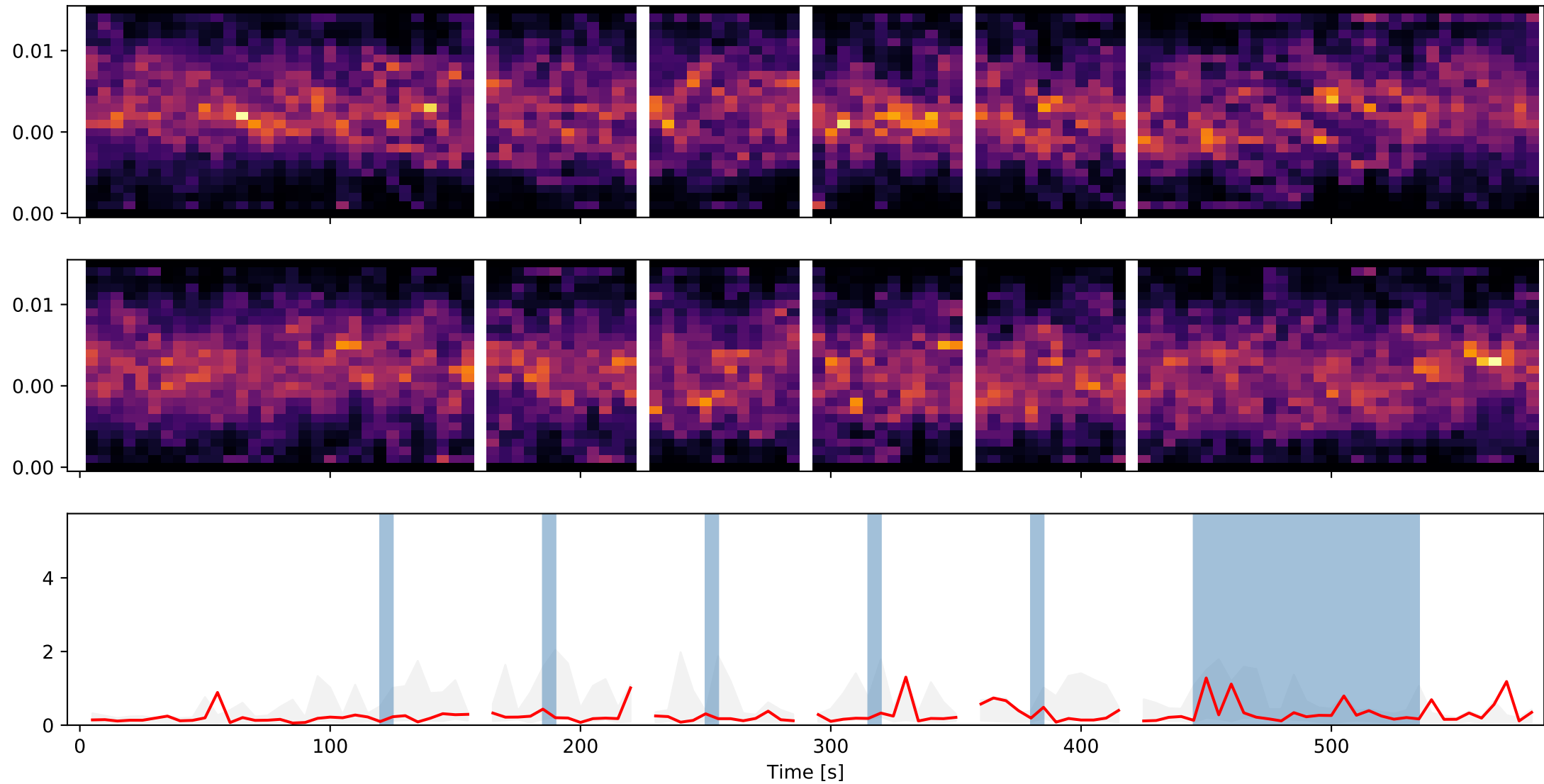
major_axis



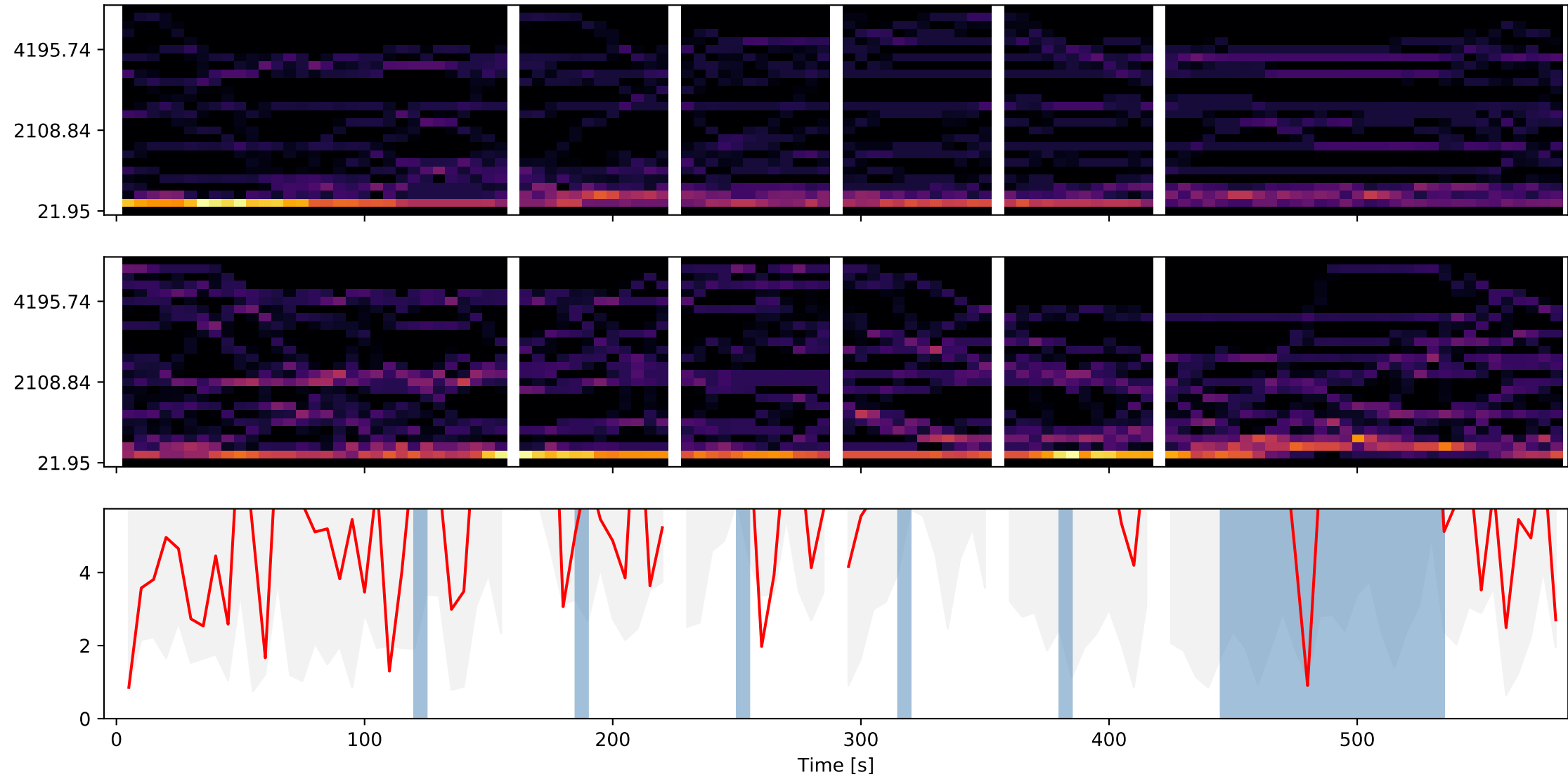
eigen_projection_7



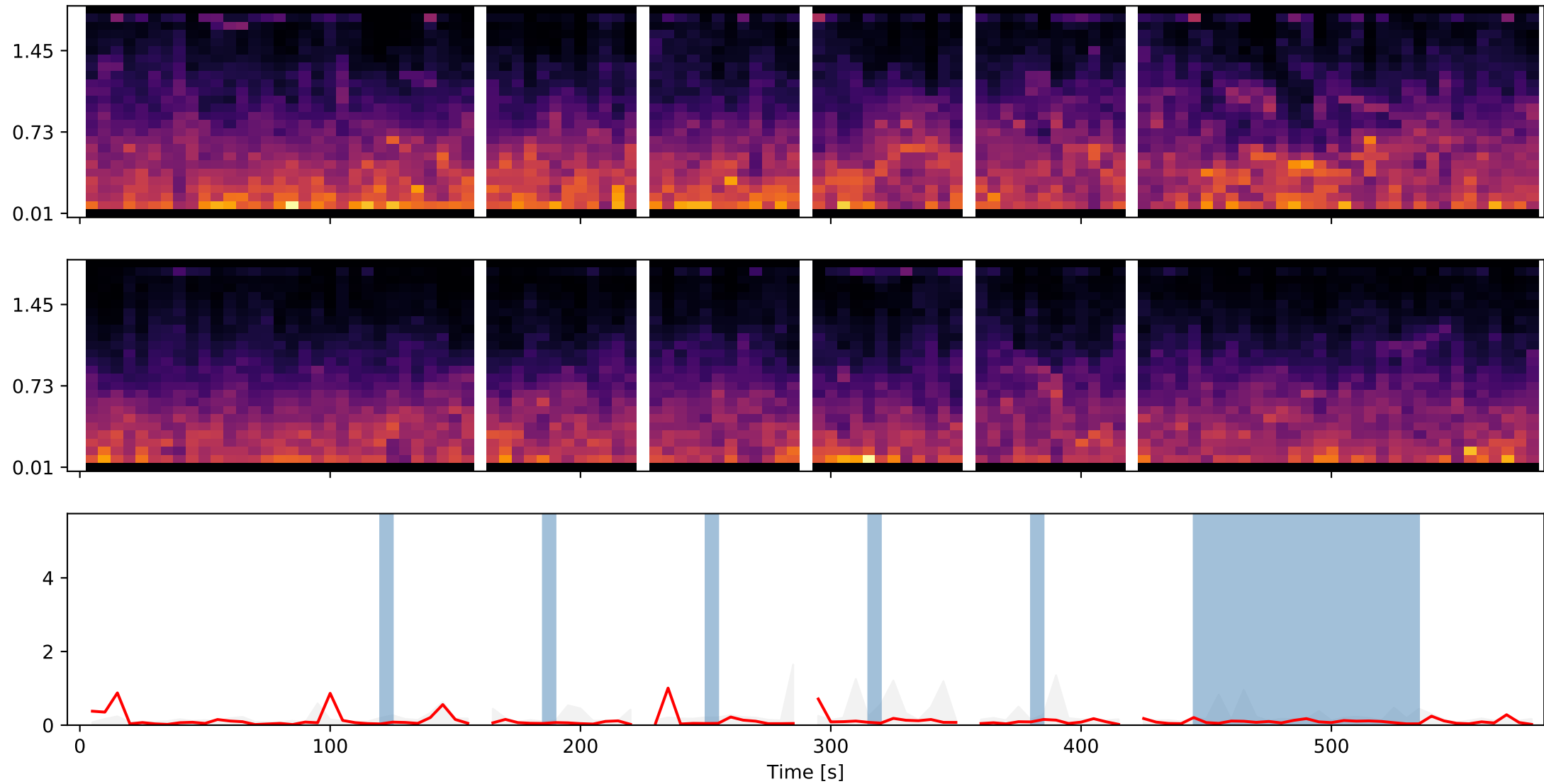
curvature_std_midbody



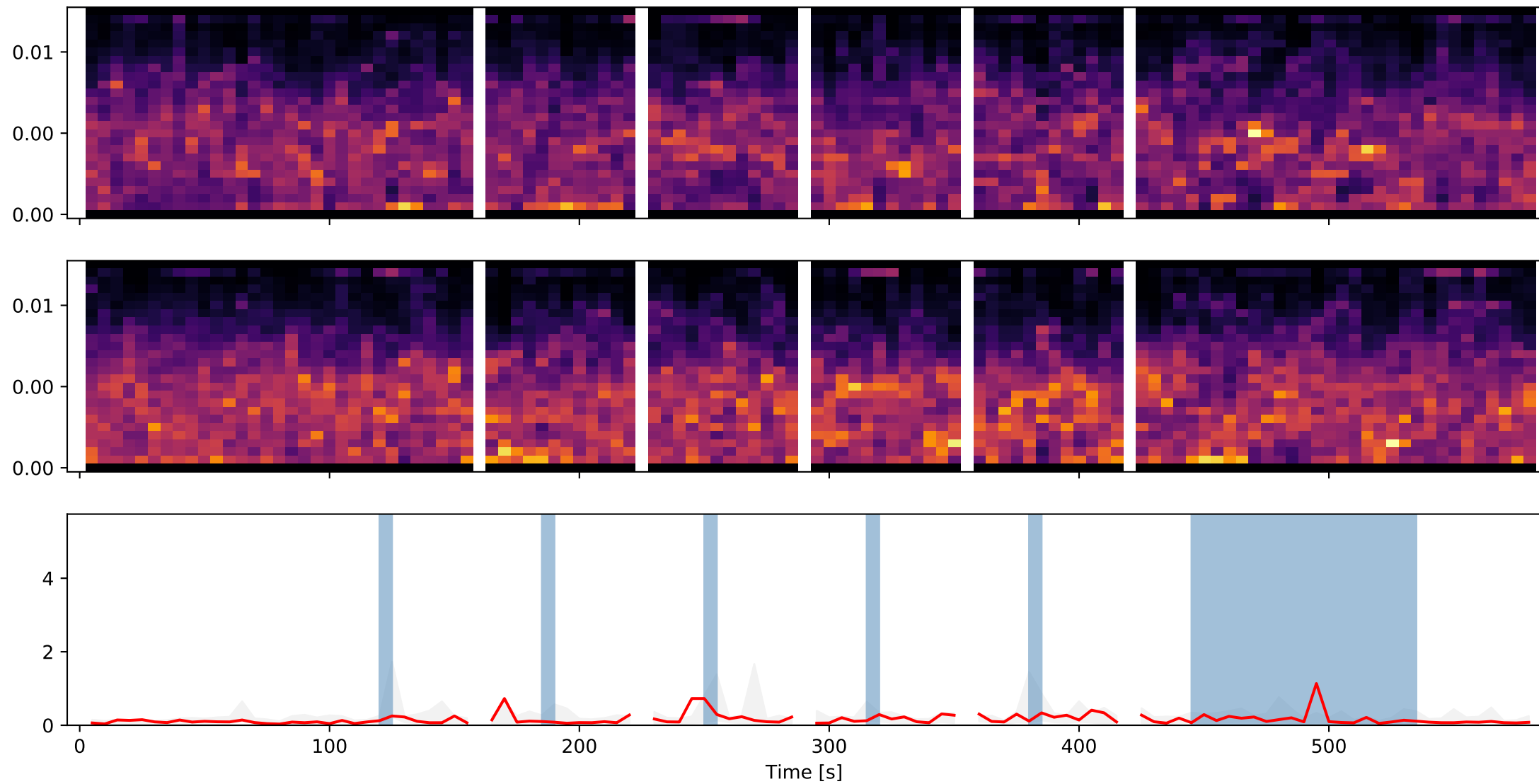
dist_from_food_edge



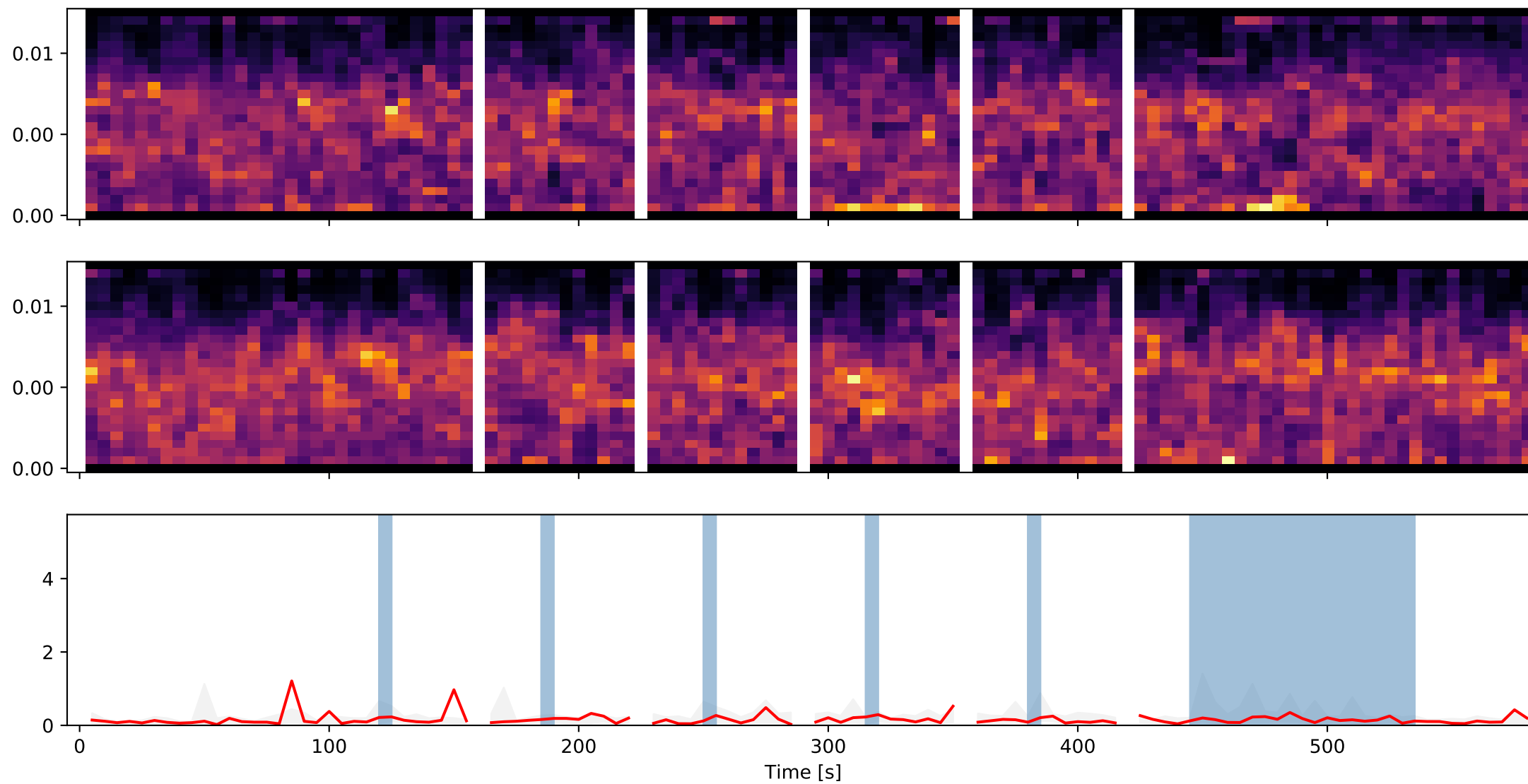
eigen_projection_5



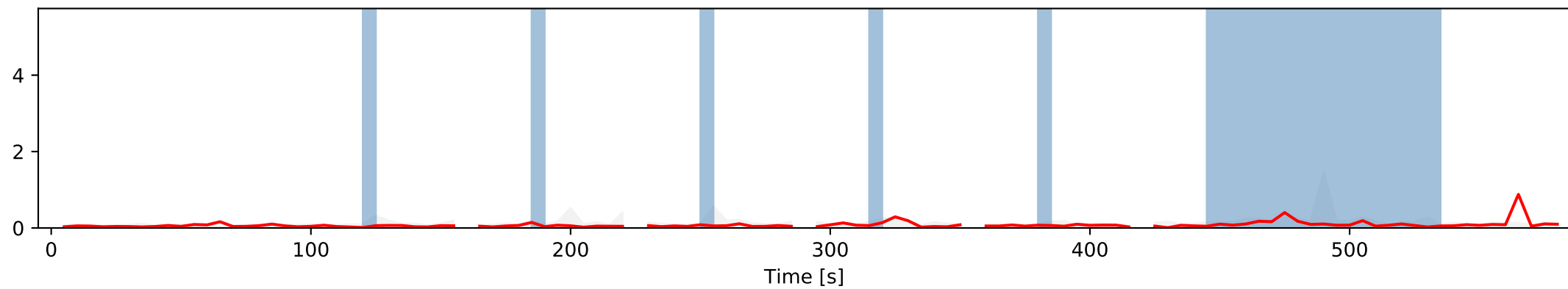
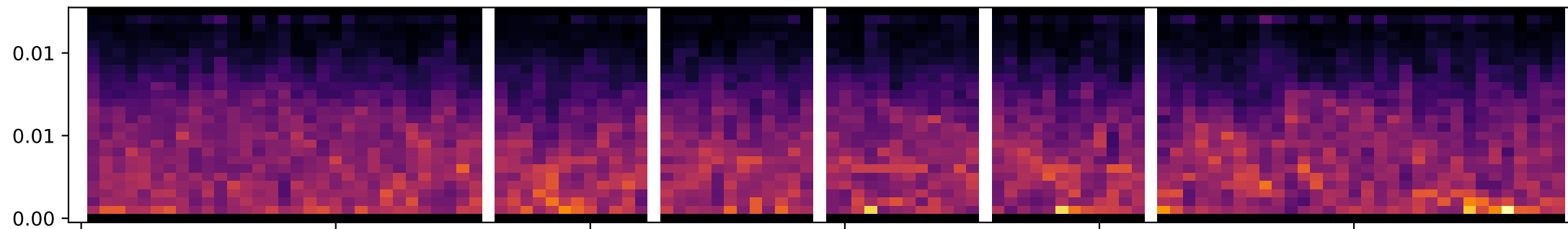
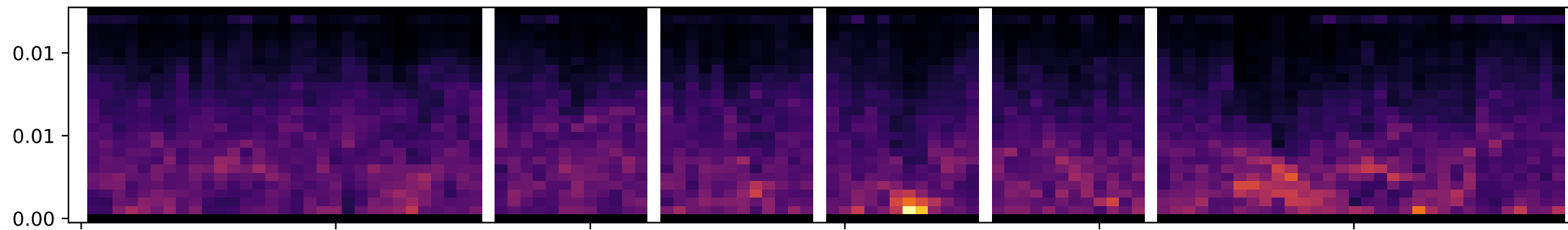
curvature_tail



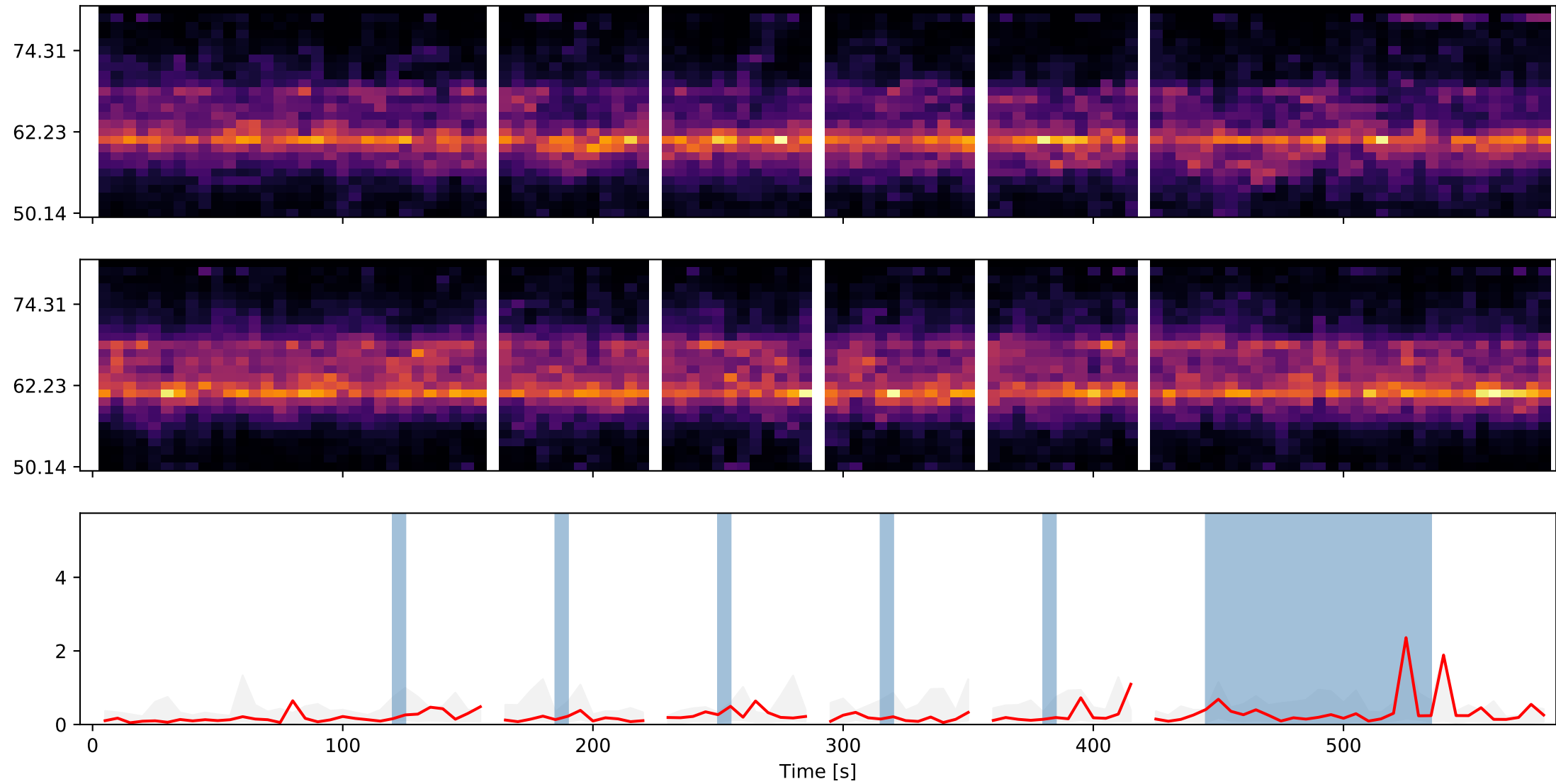
curvature_hips



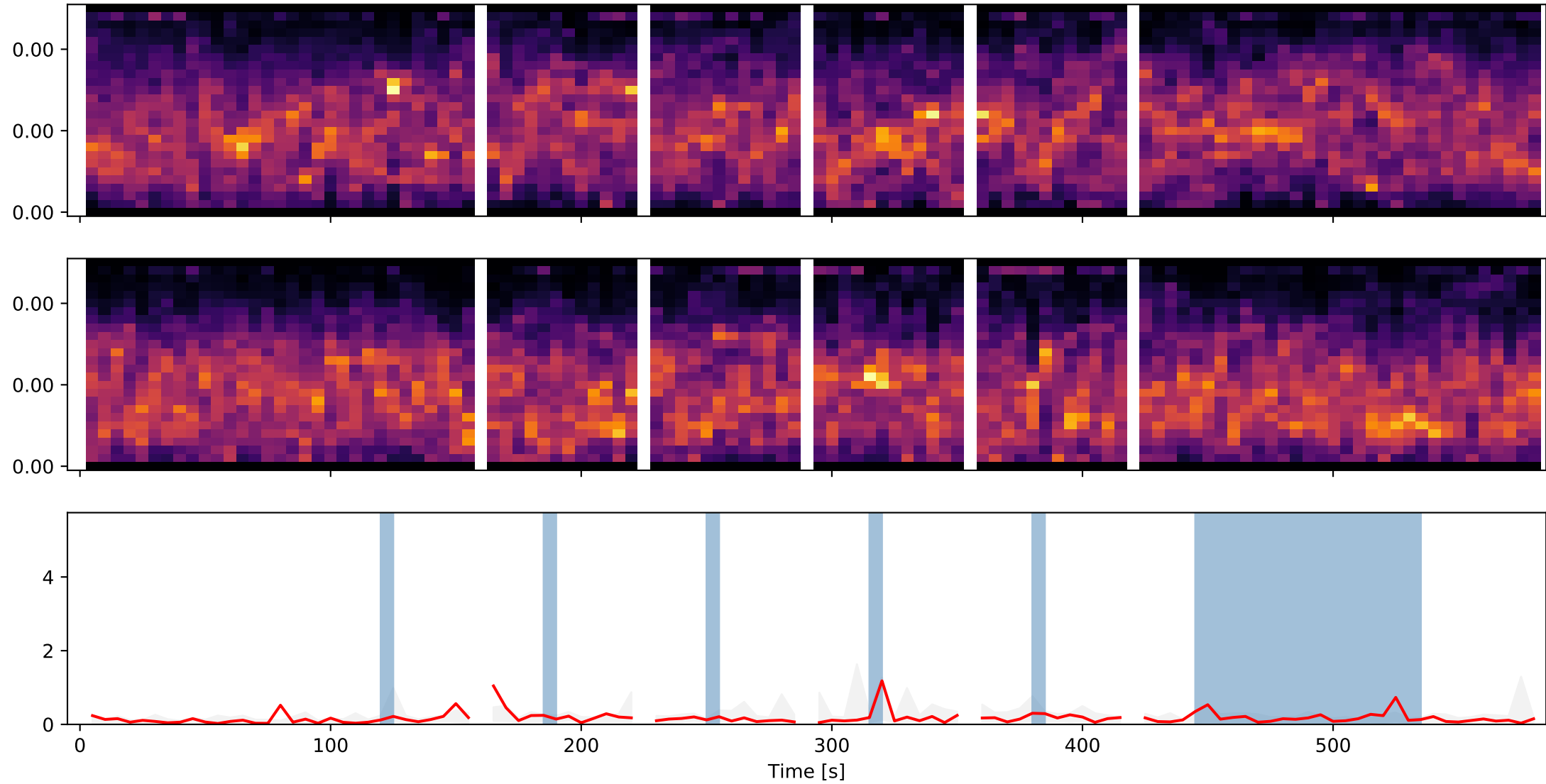
curvature_head



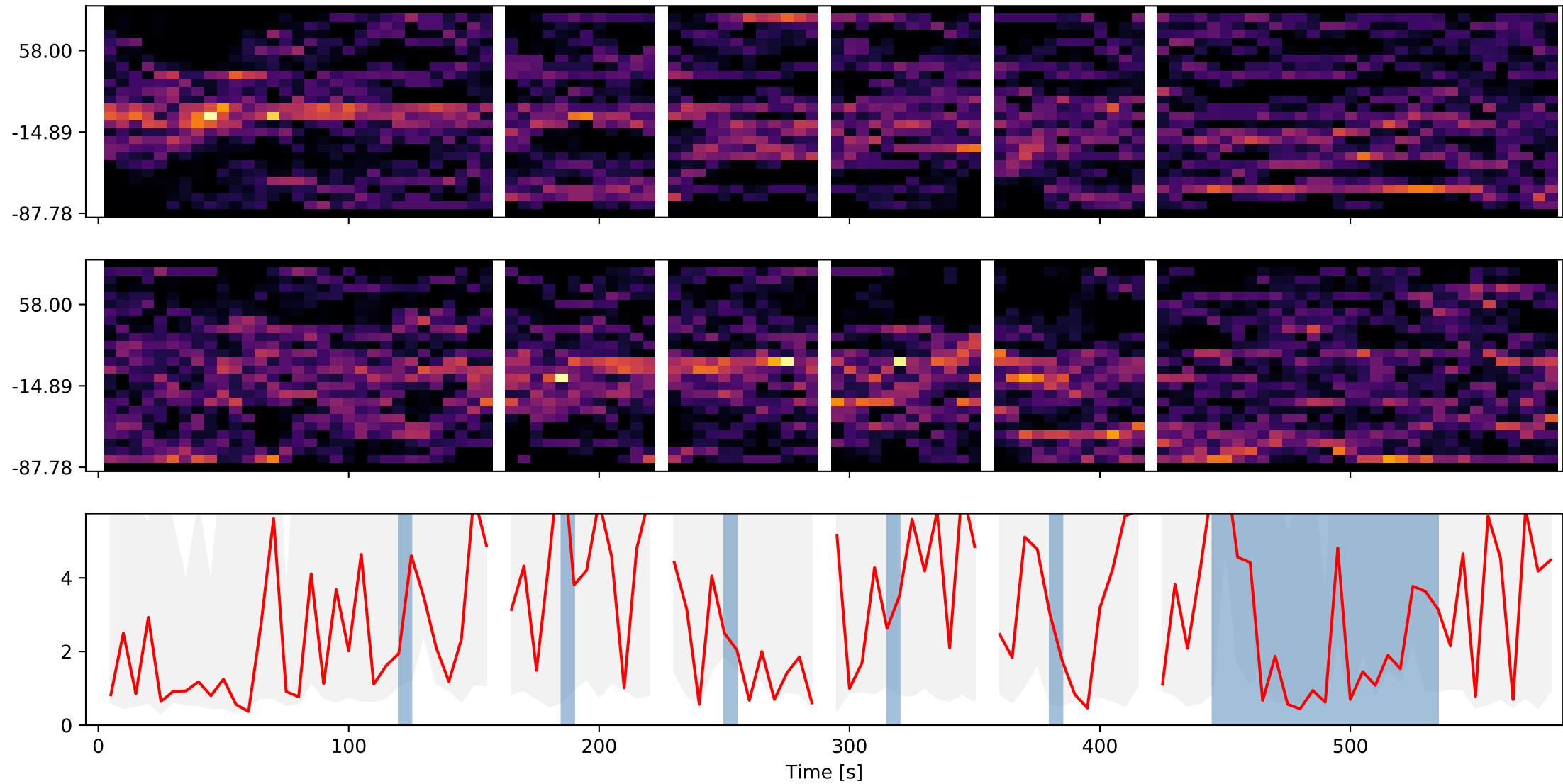
width_tail_base



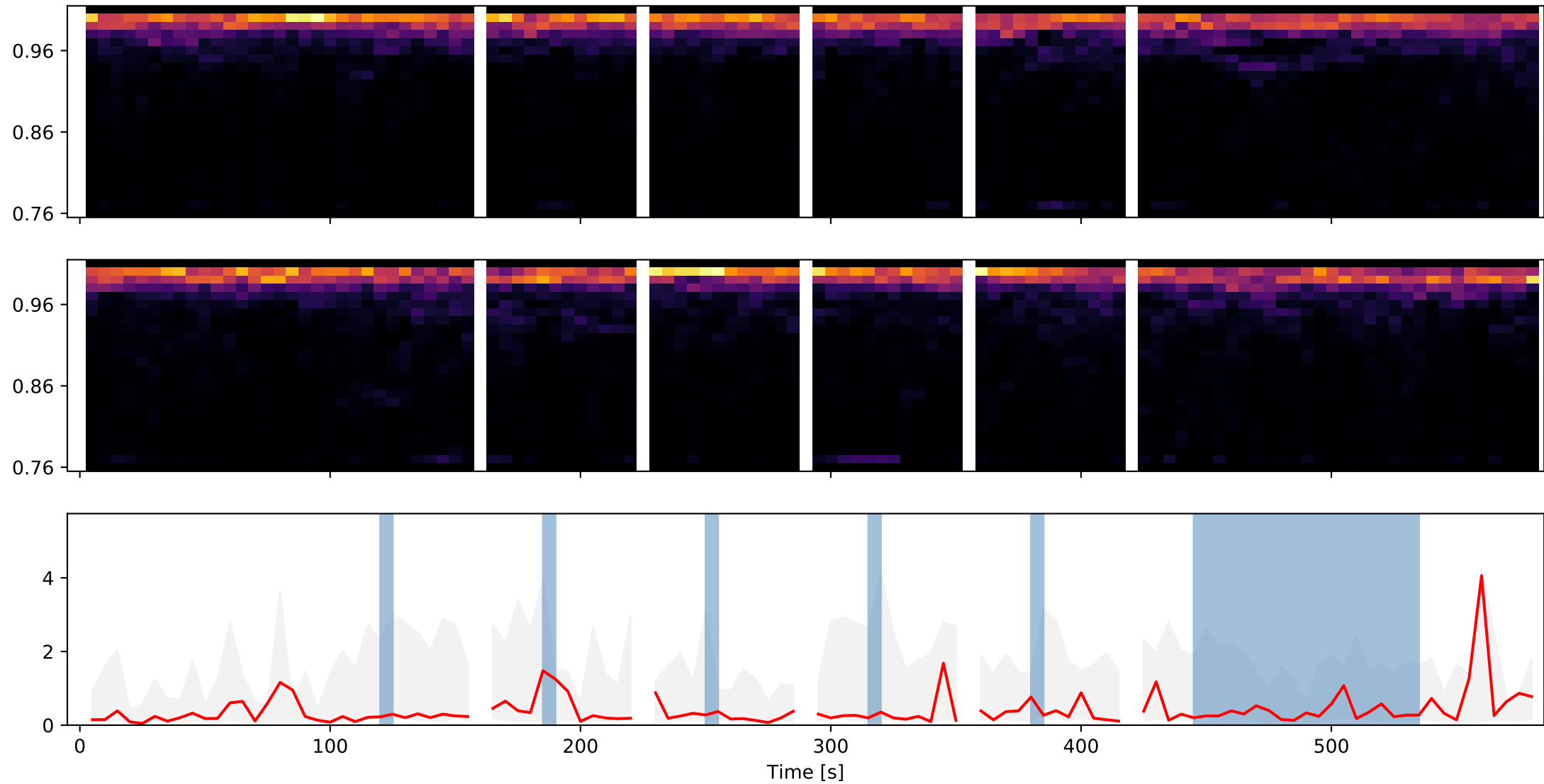
curvature_std_hips



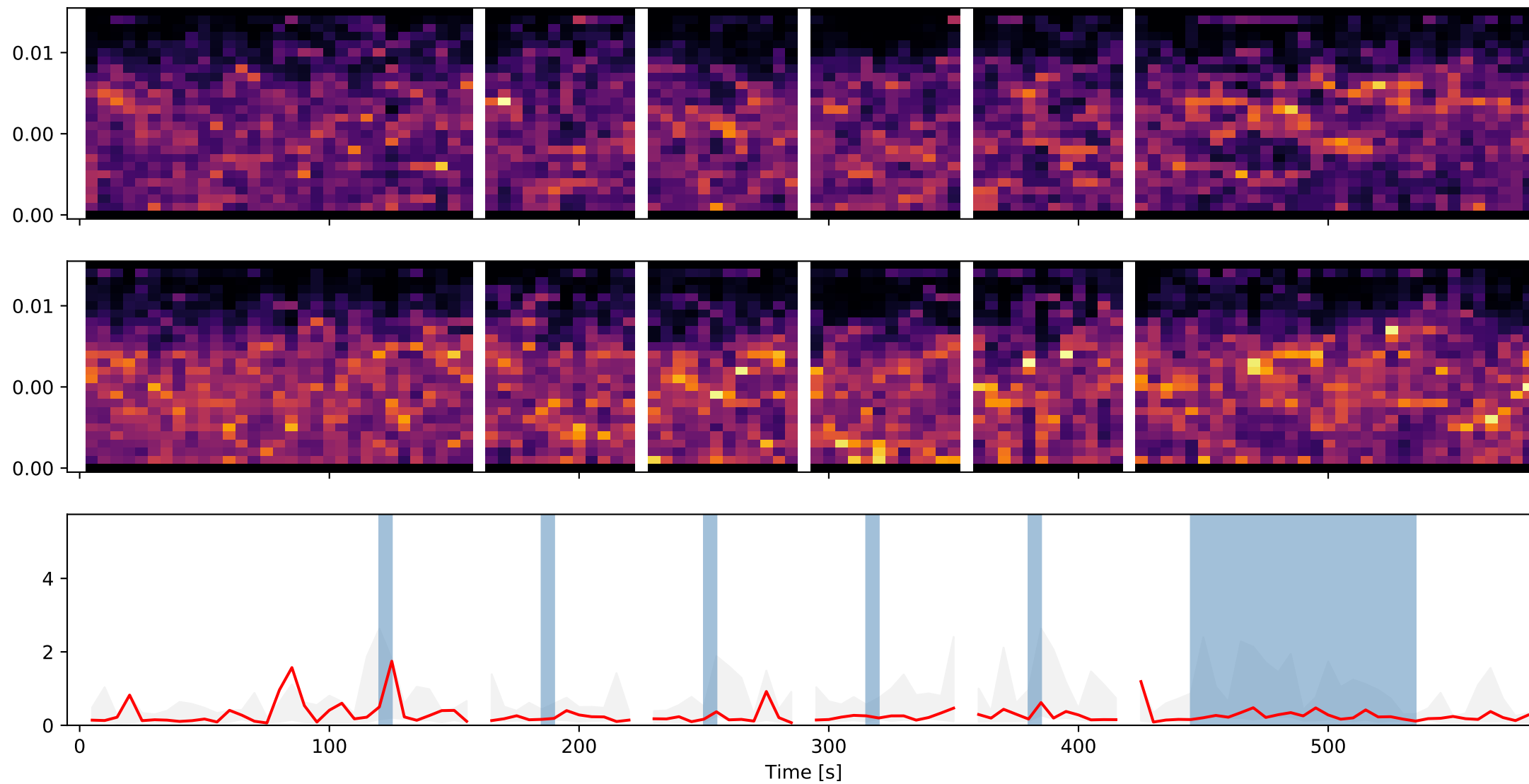
orientation_food_edge



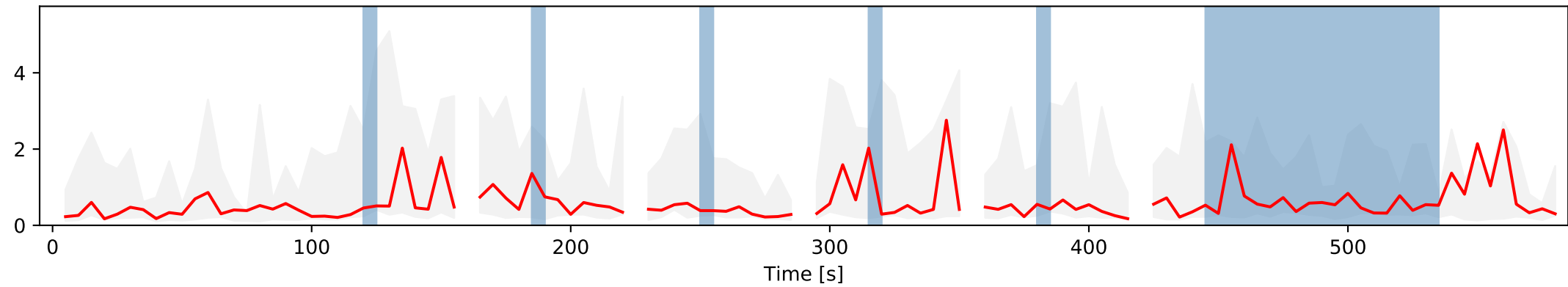
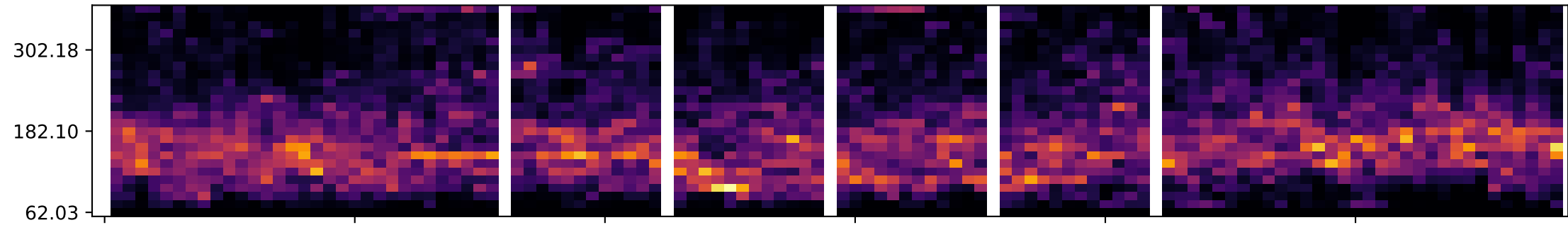
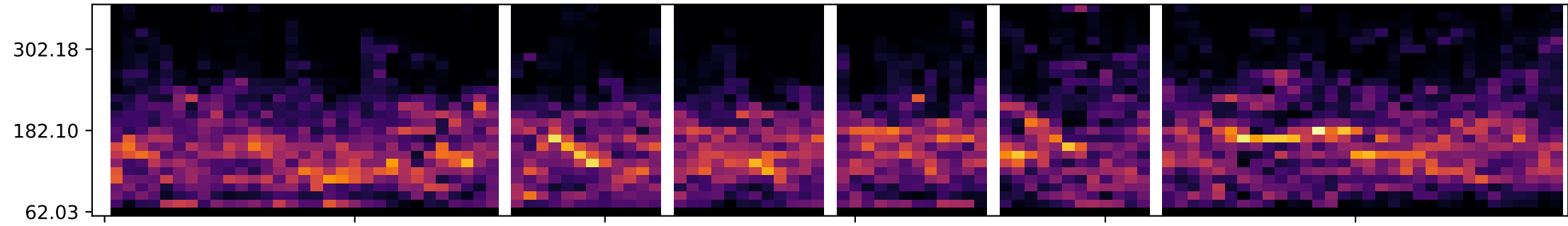
quirkiness



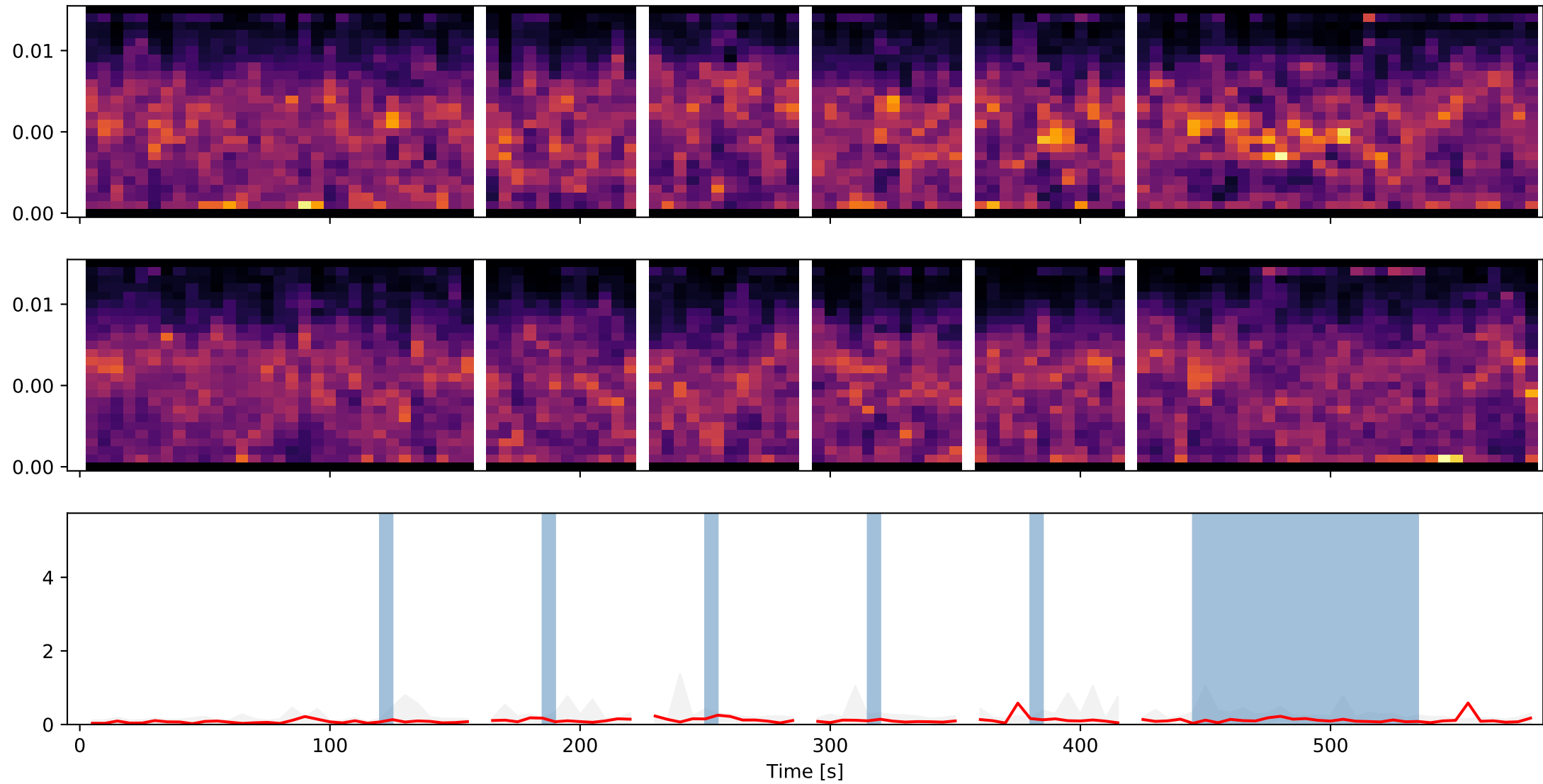
curvature_mean_hips



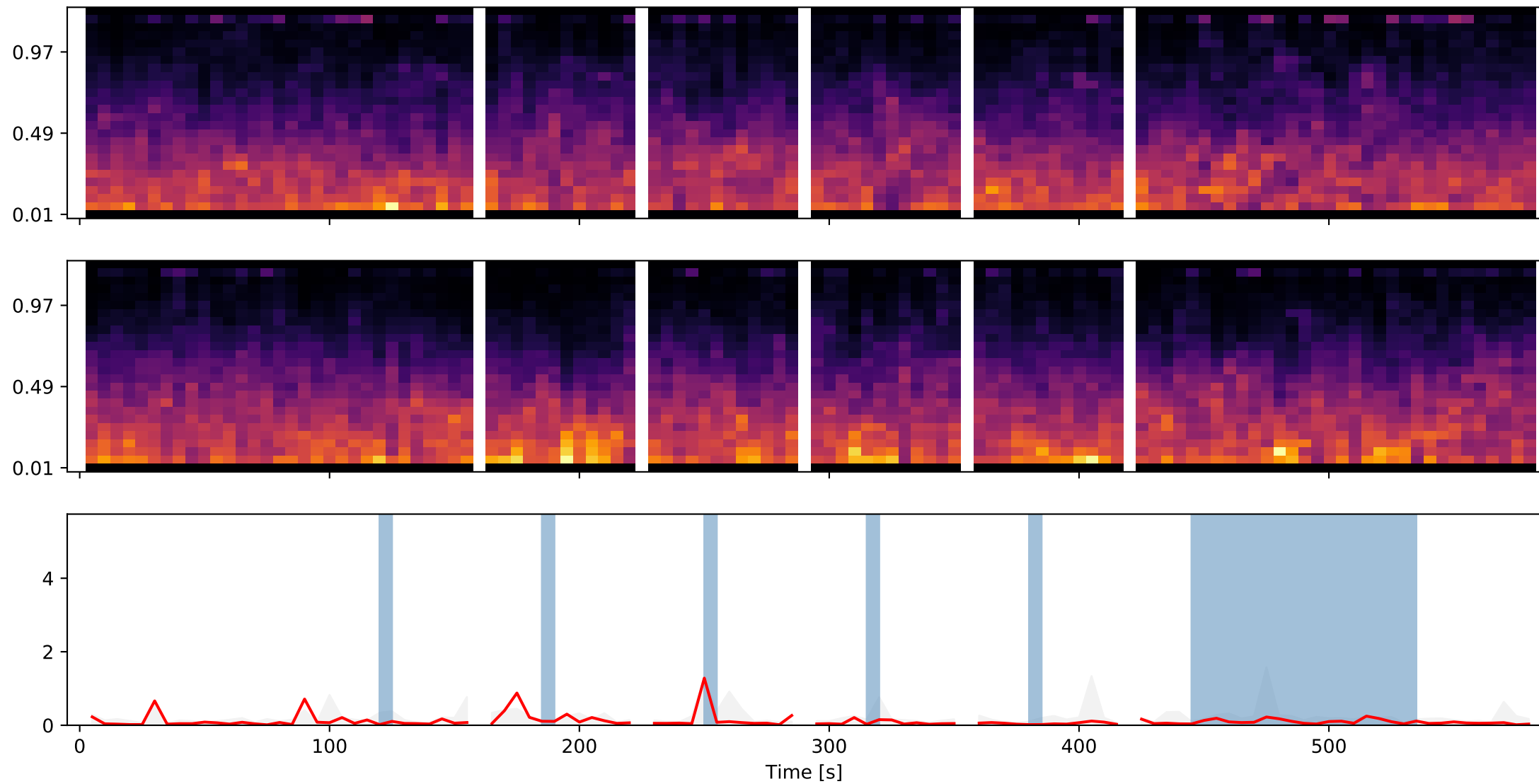
minor_axis



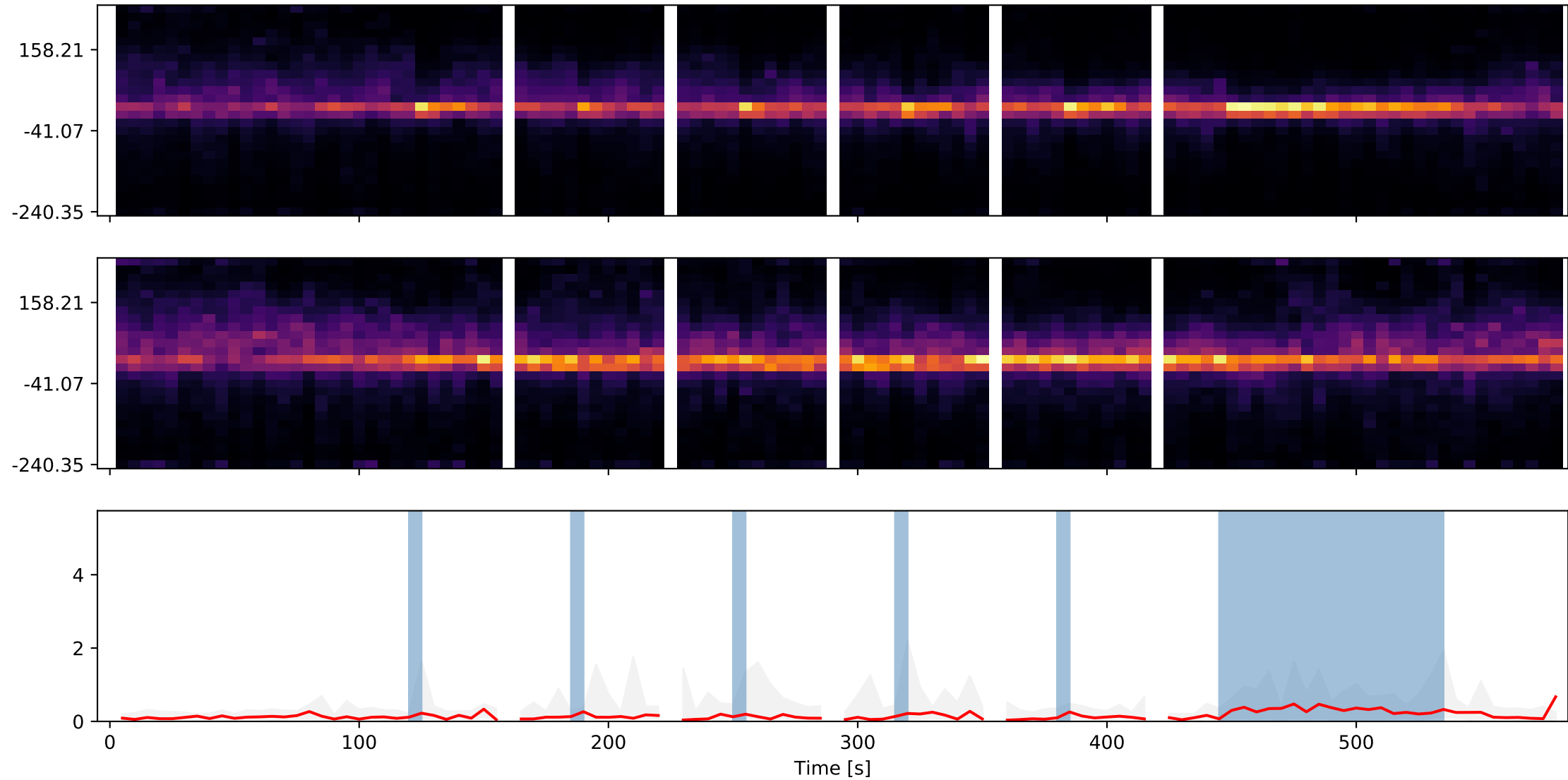
curvature_neck



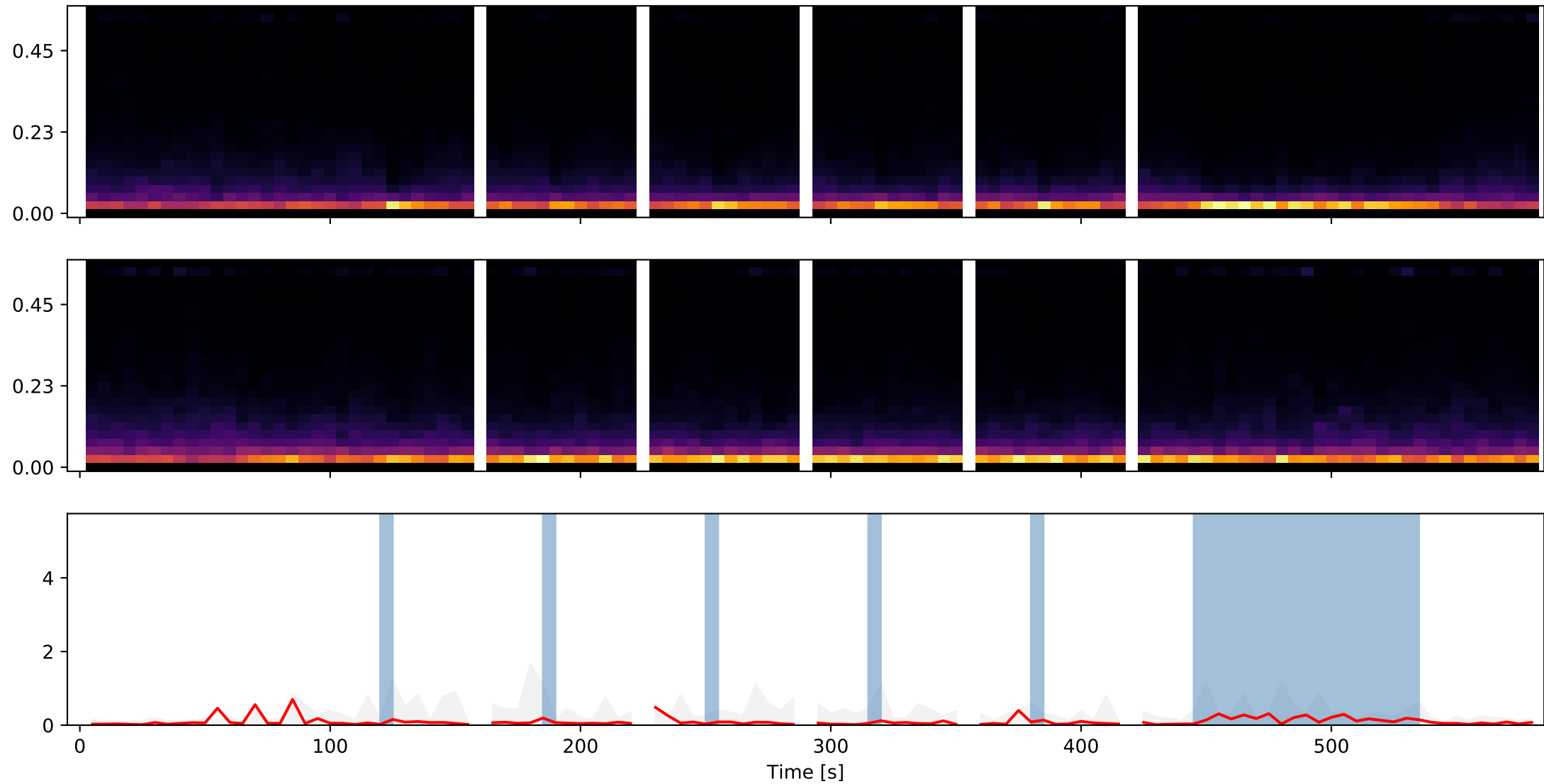
eigen_projection_6



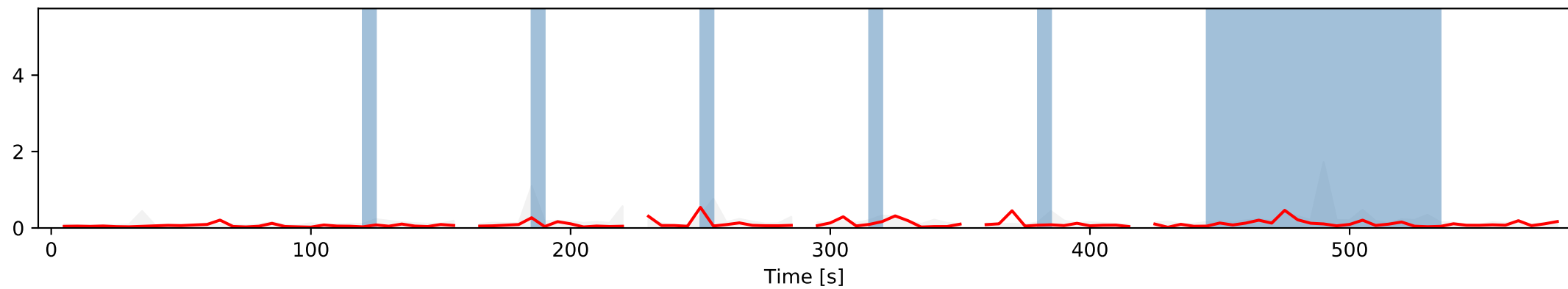
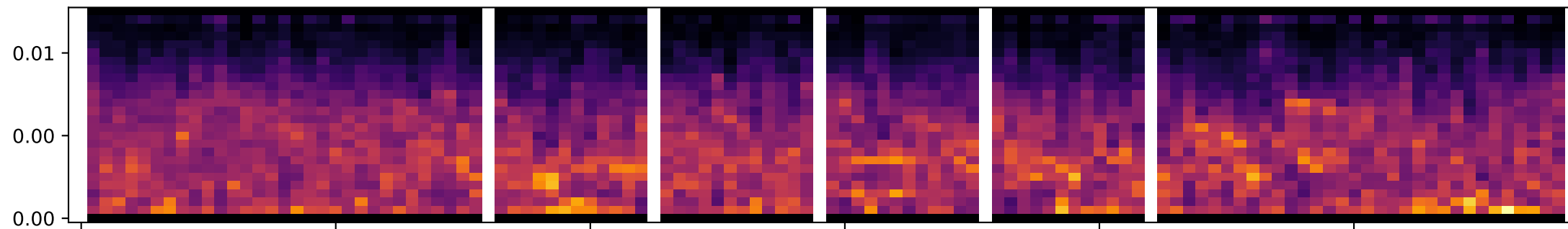
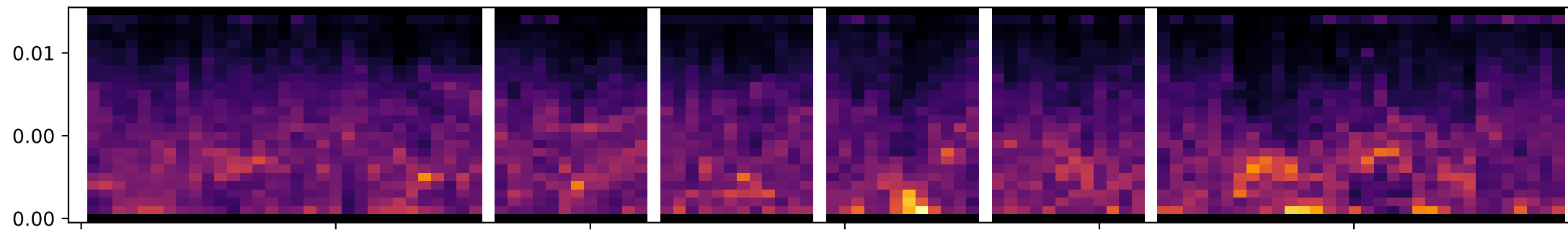
speed_tail_base



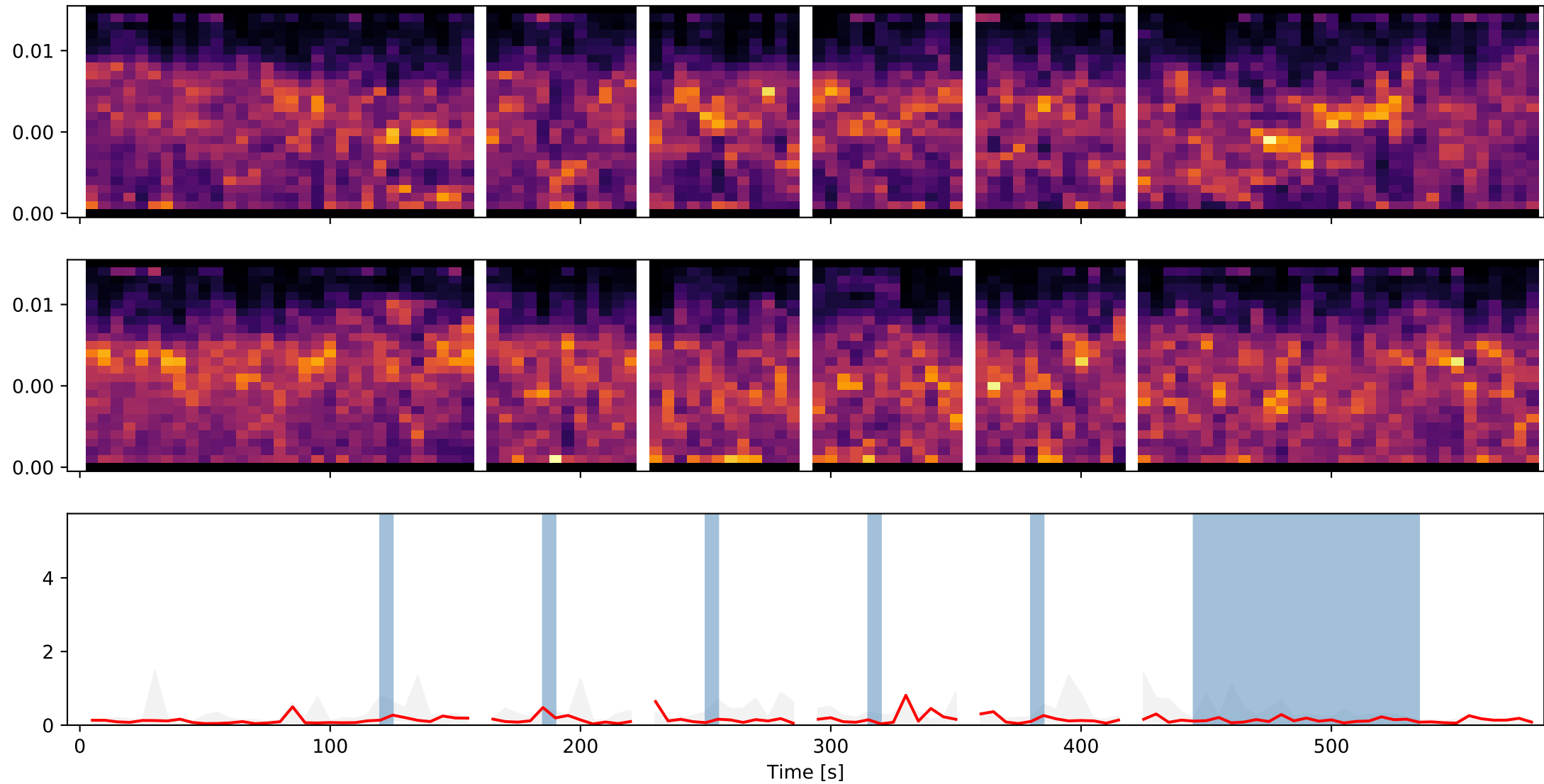
angular_velocity



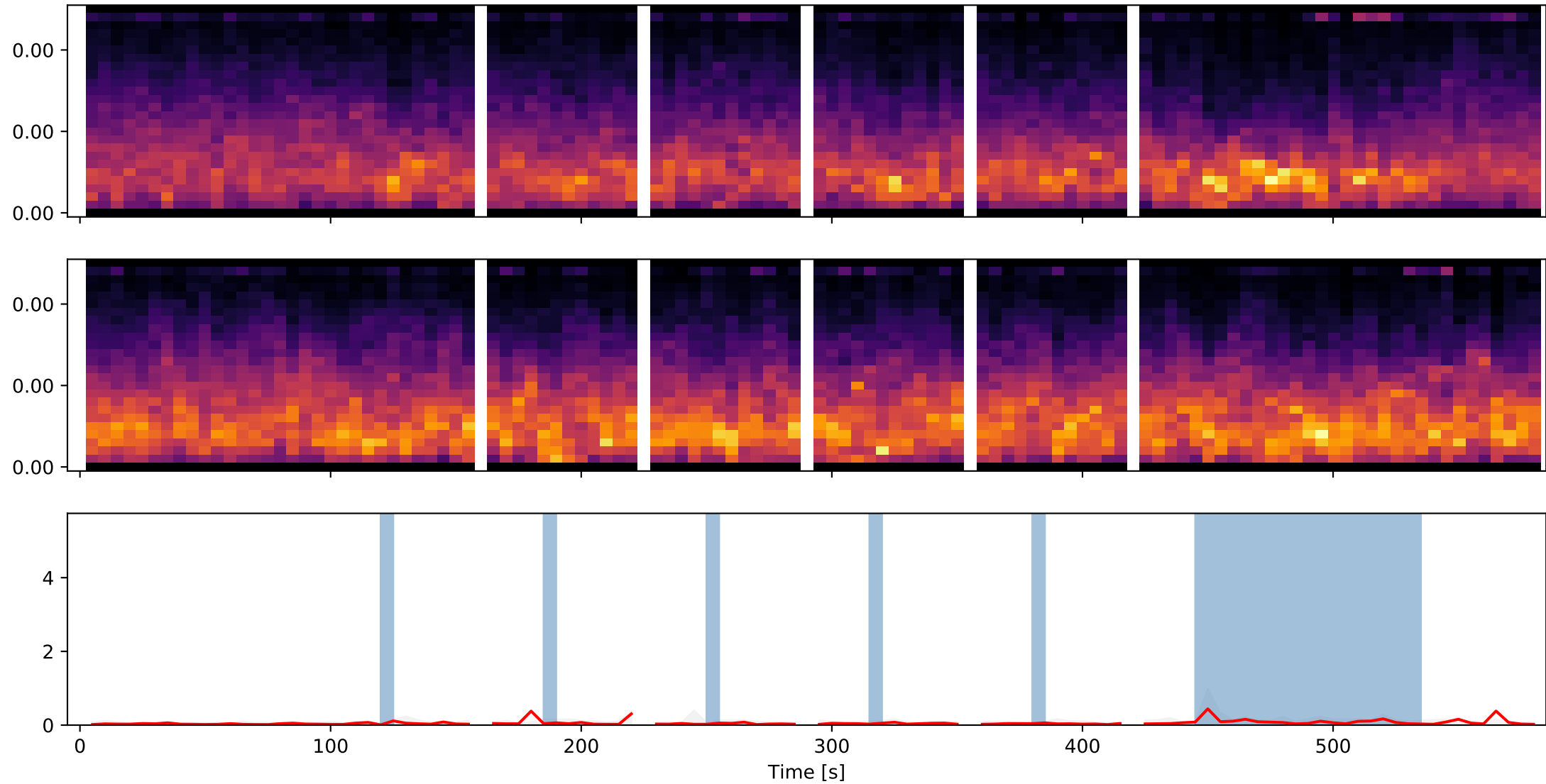
curvature_mean_head



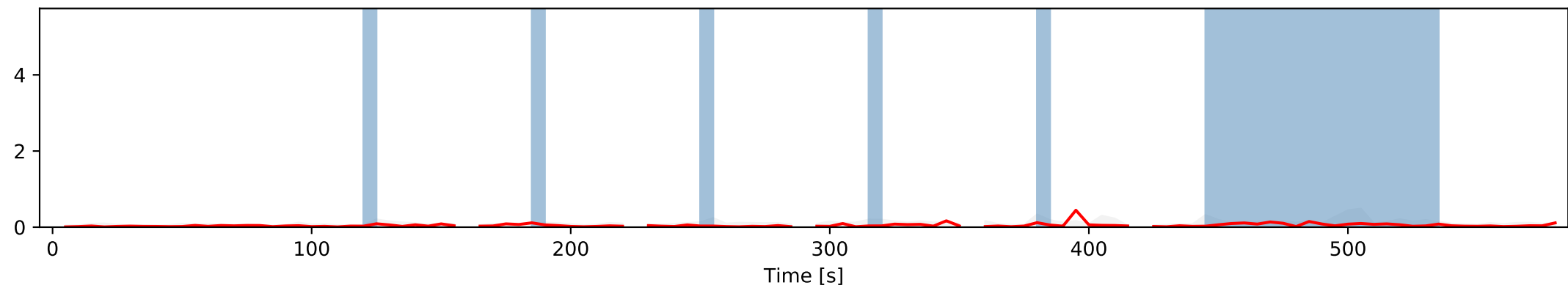
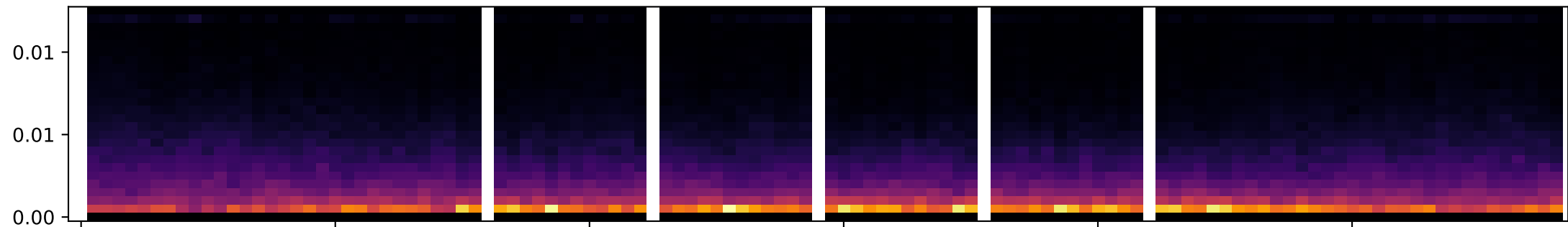
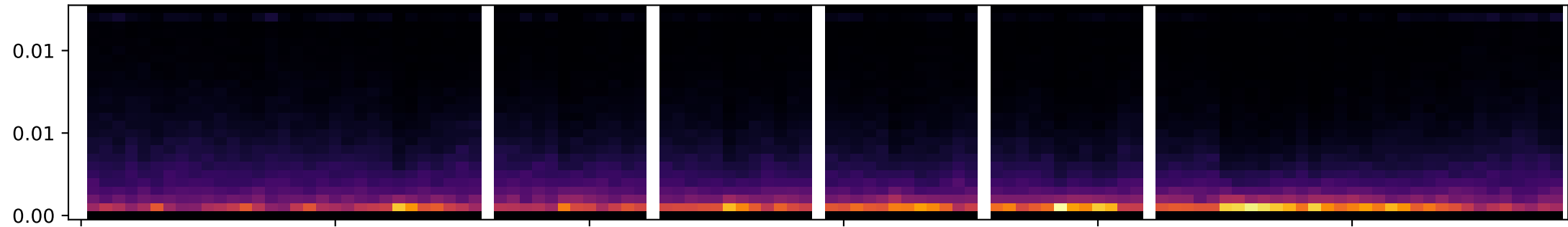
curvature_midbody



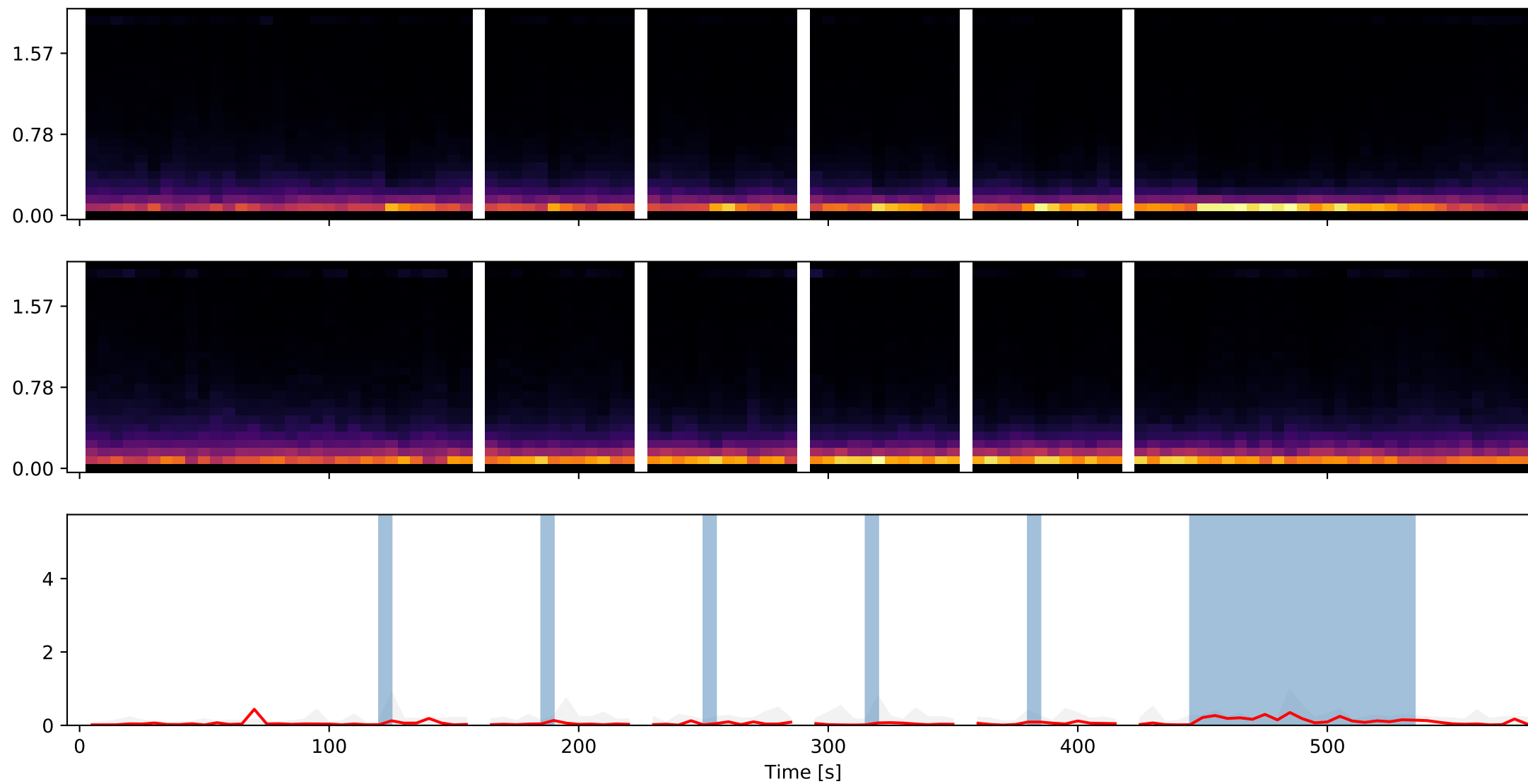
curvature_std_head



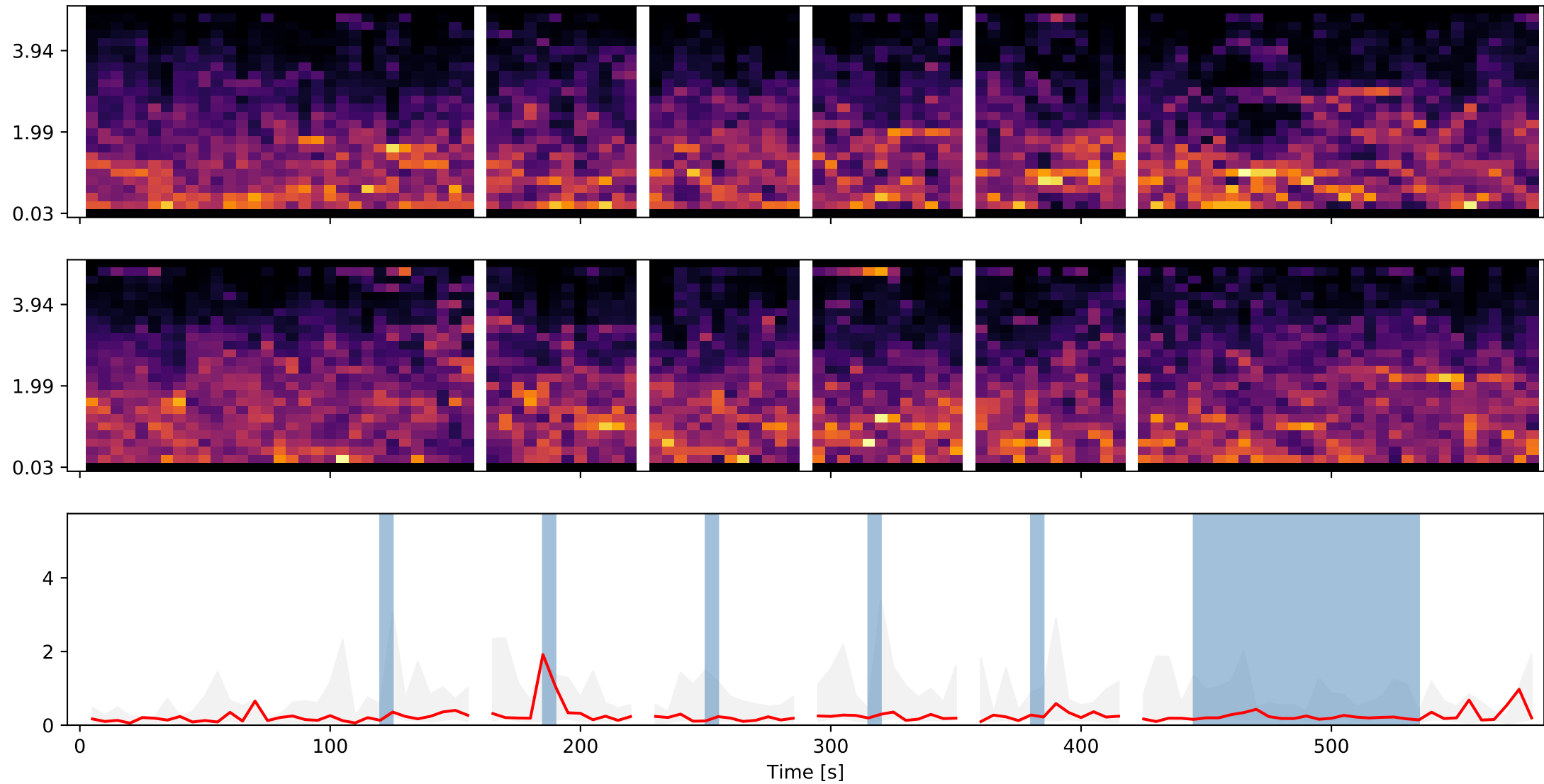
d_curvature_tail



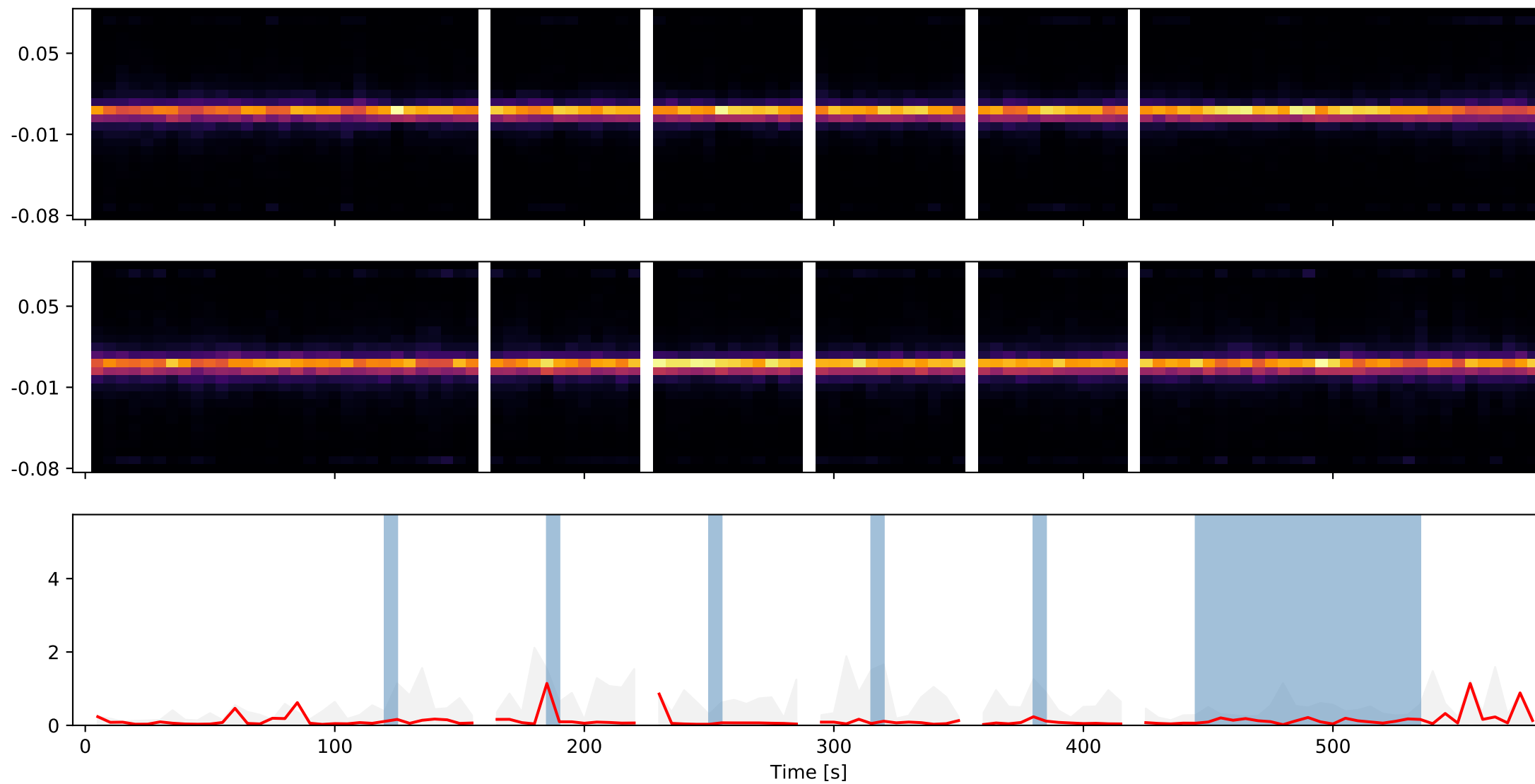
d_relative_to_body_angular_velocity_neck



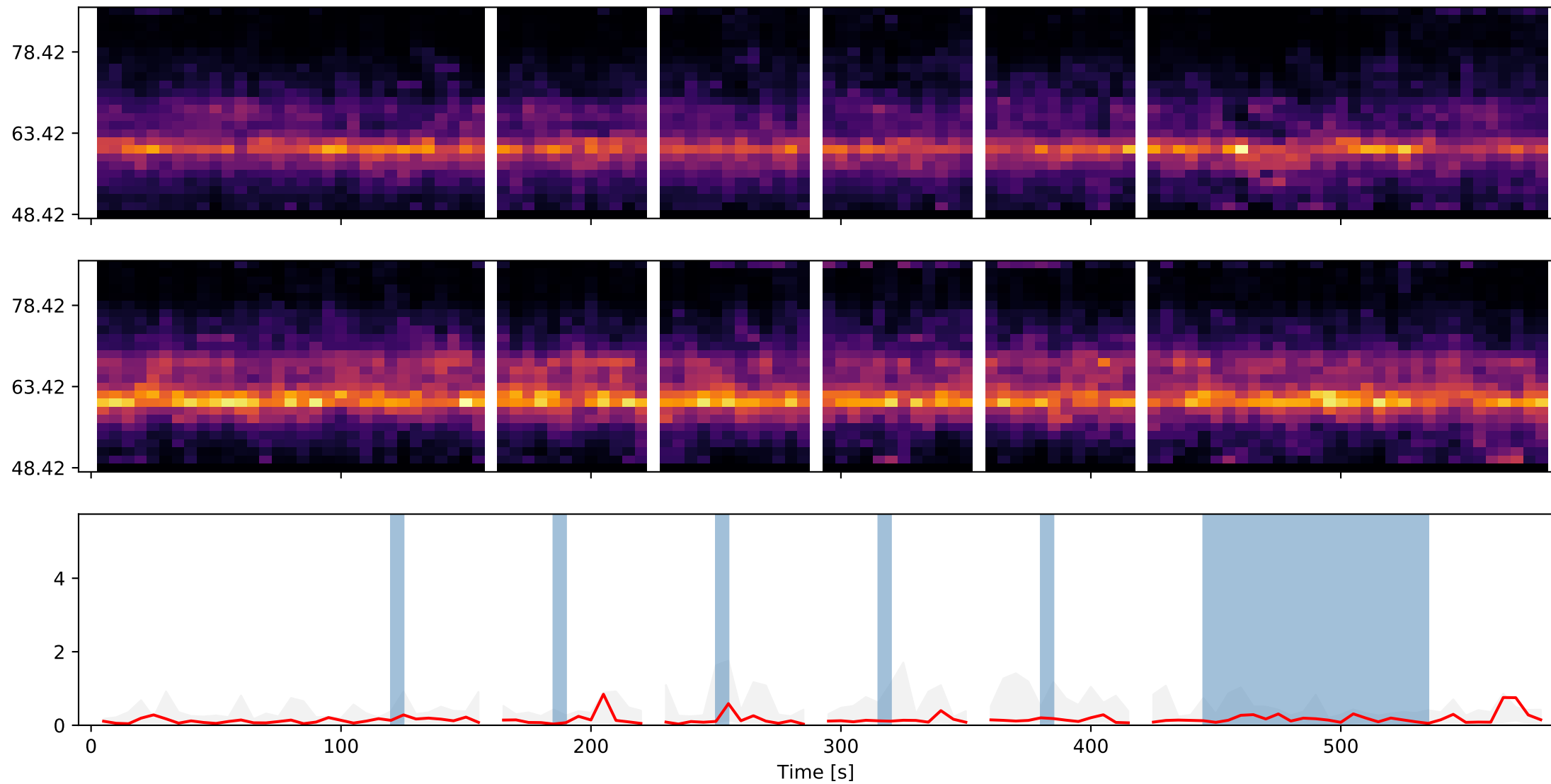
eigen_projection_3



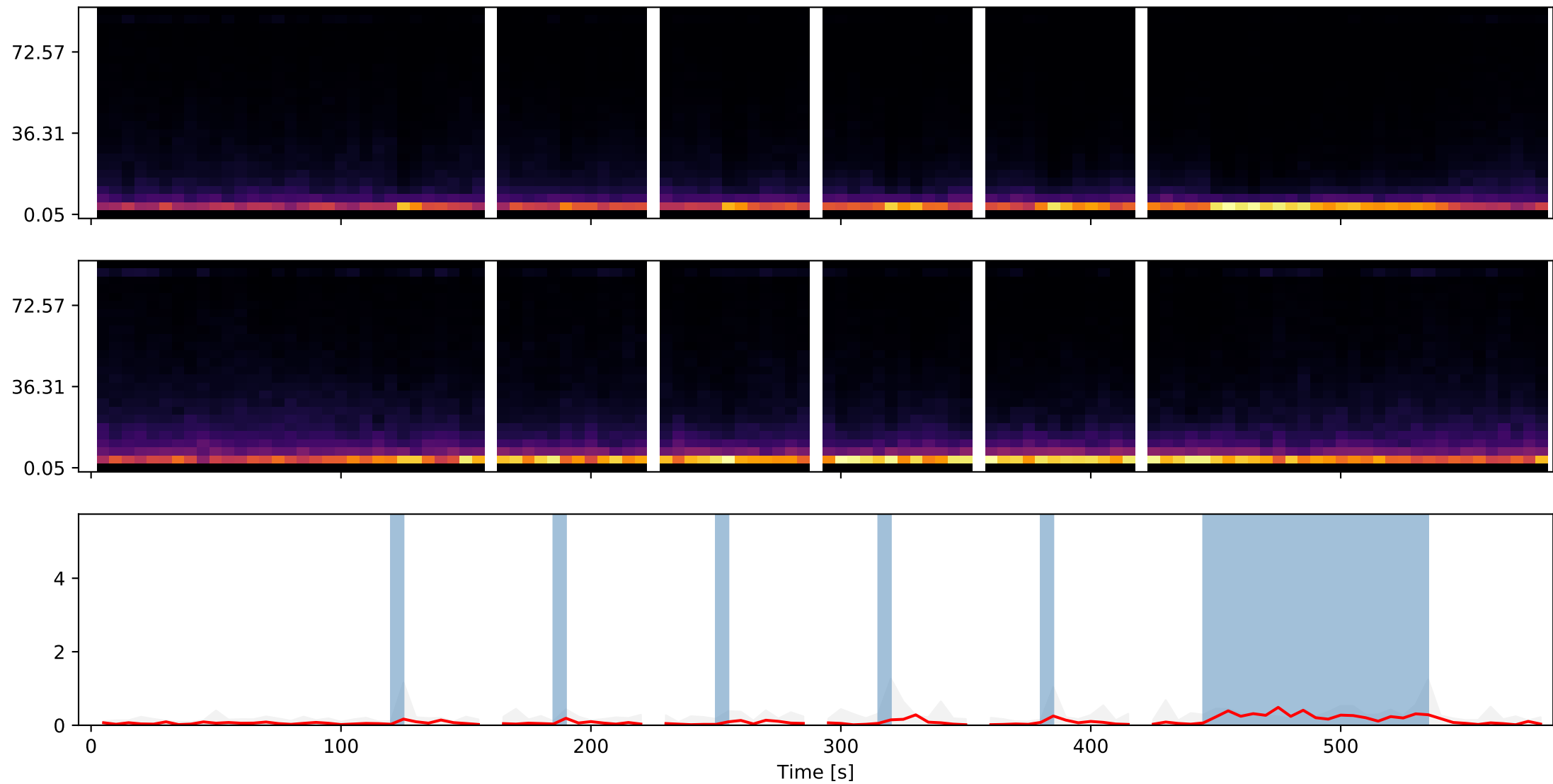
d_quirkiness



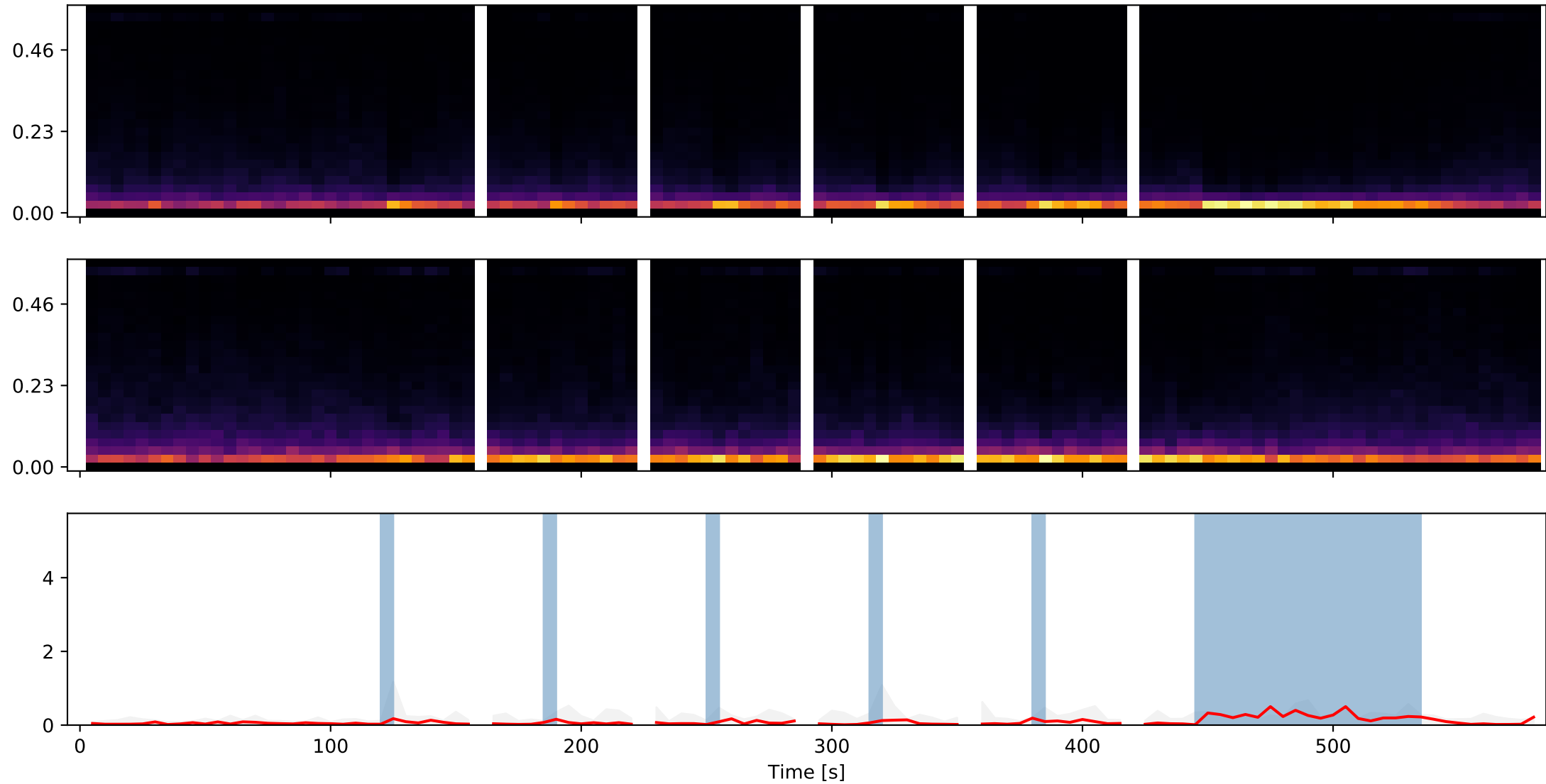
width_head_base



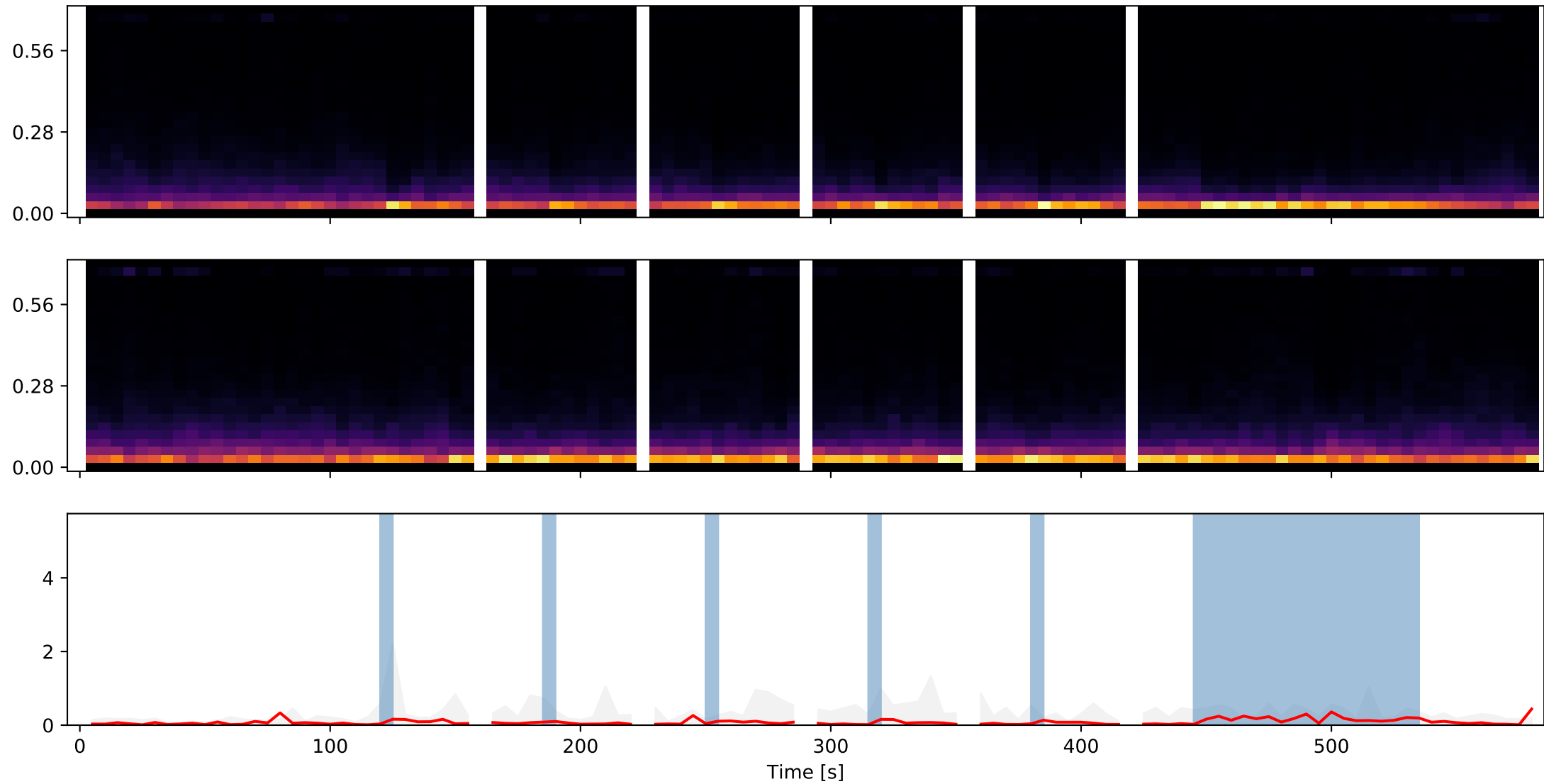
relative_to_body_speed_midbody



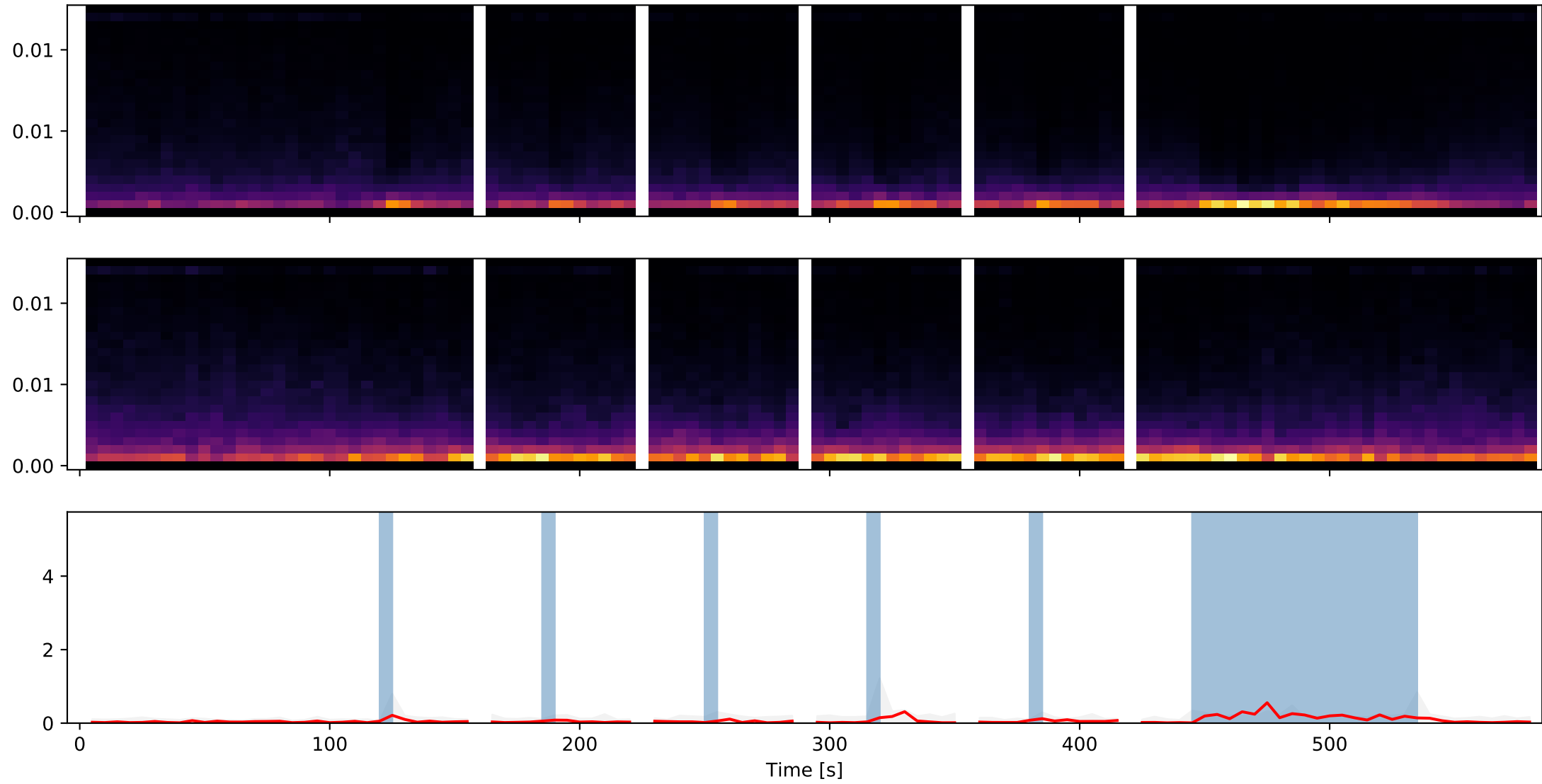
relative_to_body_angular_velocity_neck



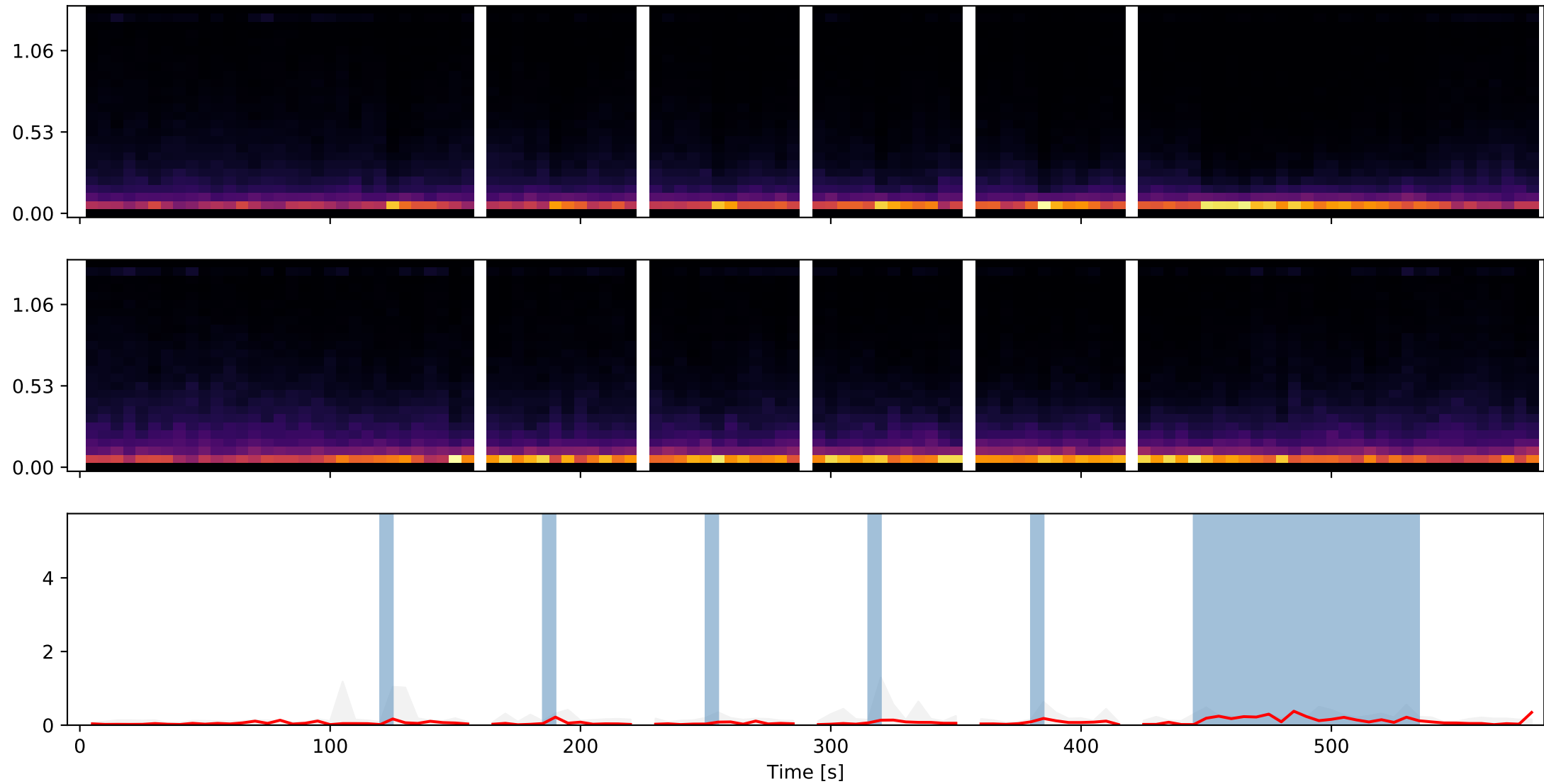
relative_to_body_angular_velocity_tail_tip



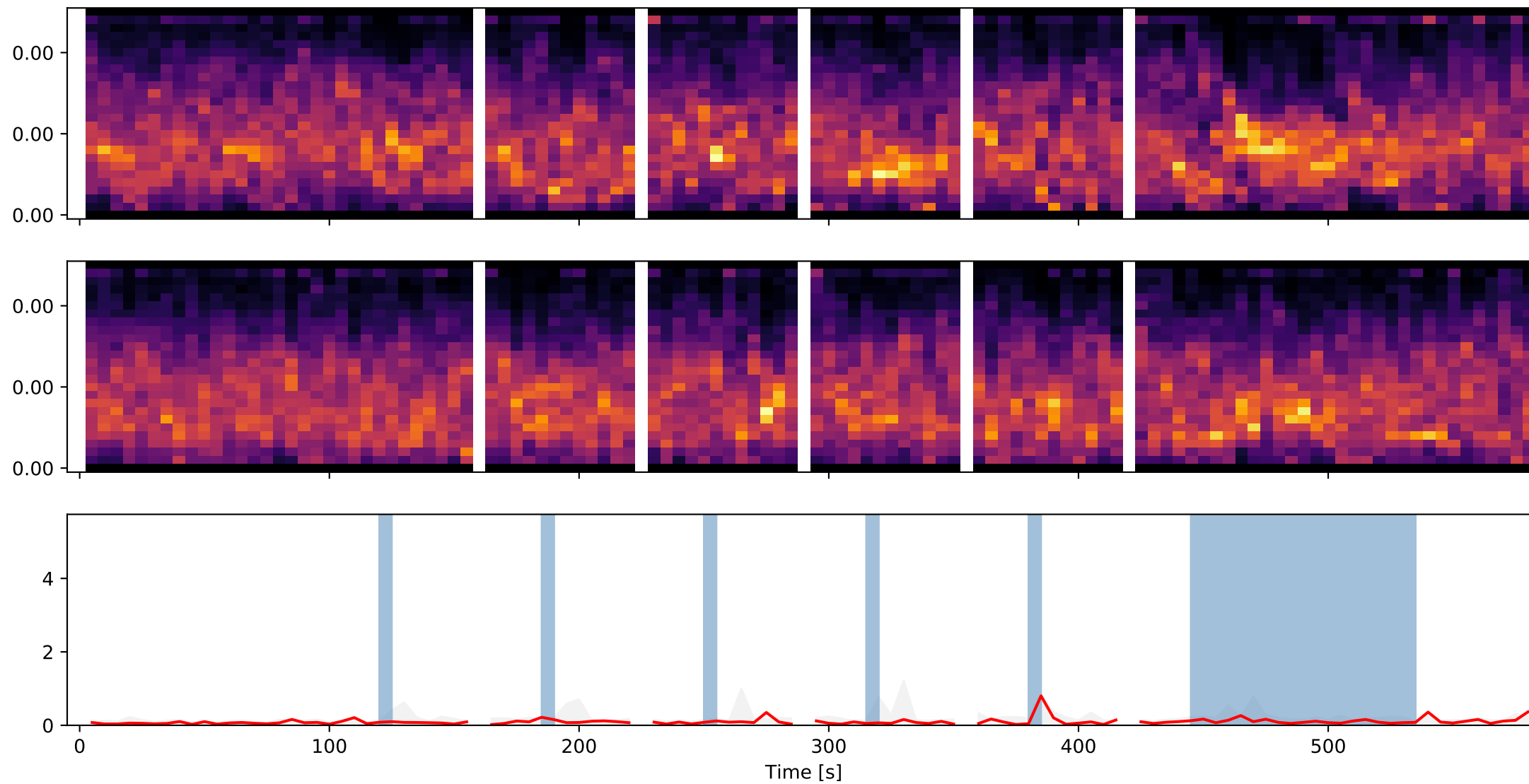
d_curvature_mean_neck



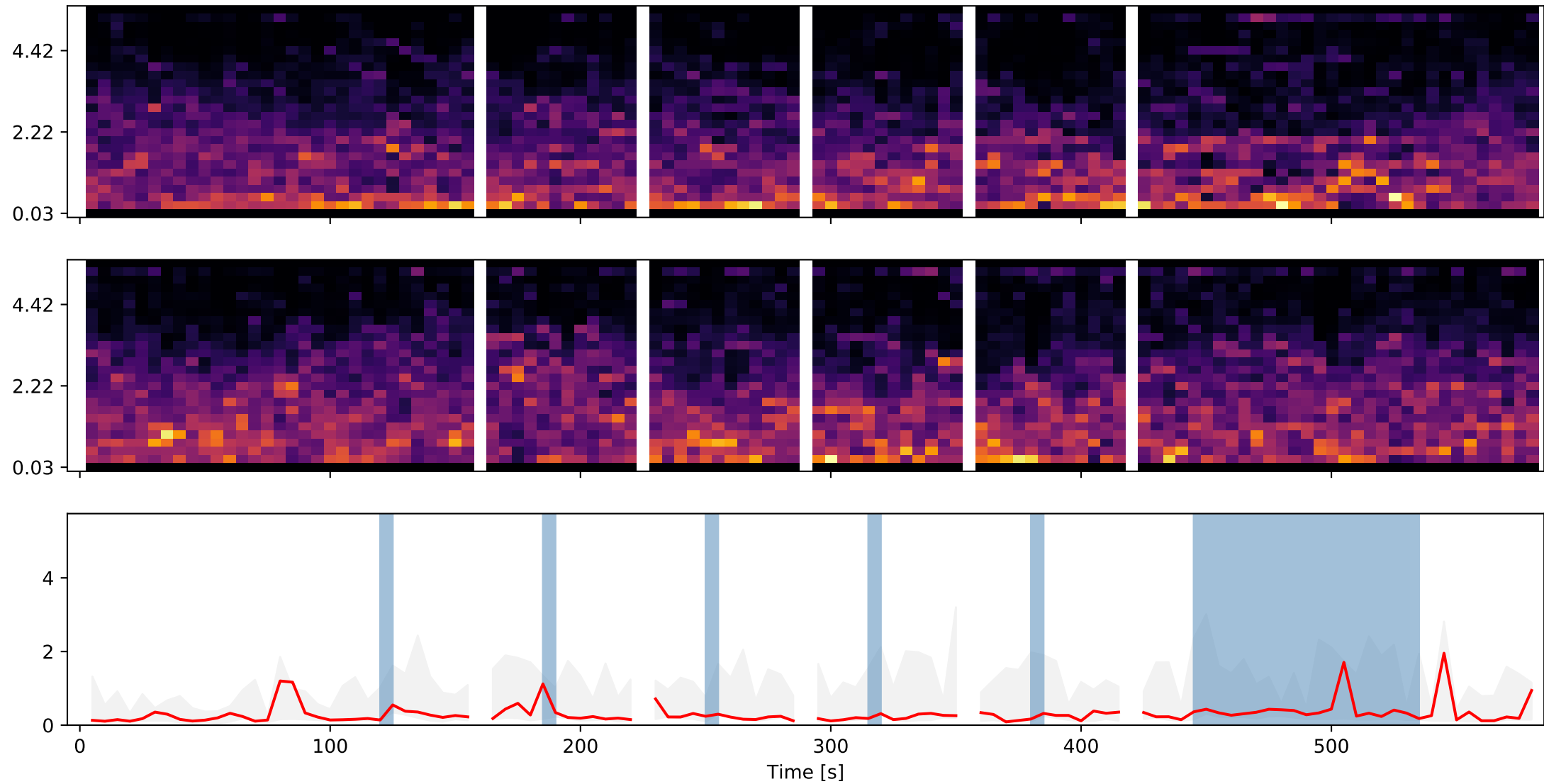
relative_to_hips_angular_velocity_tail_tip



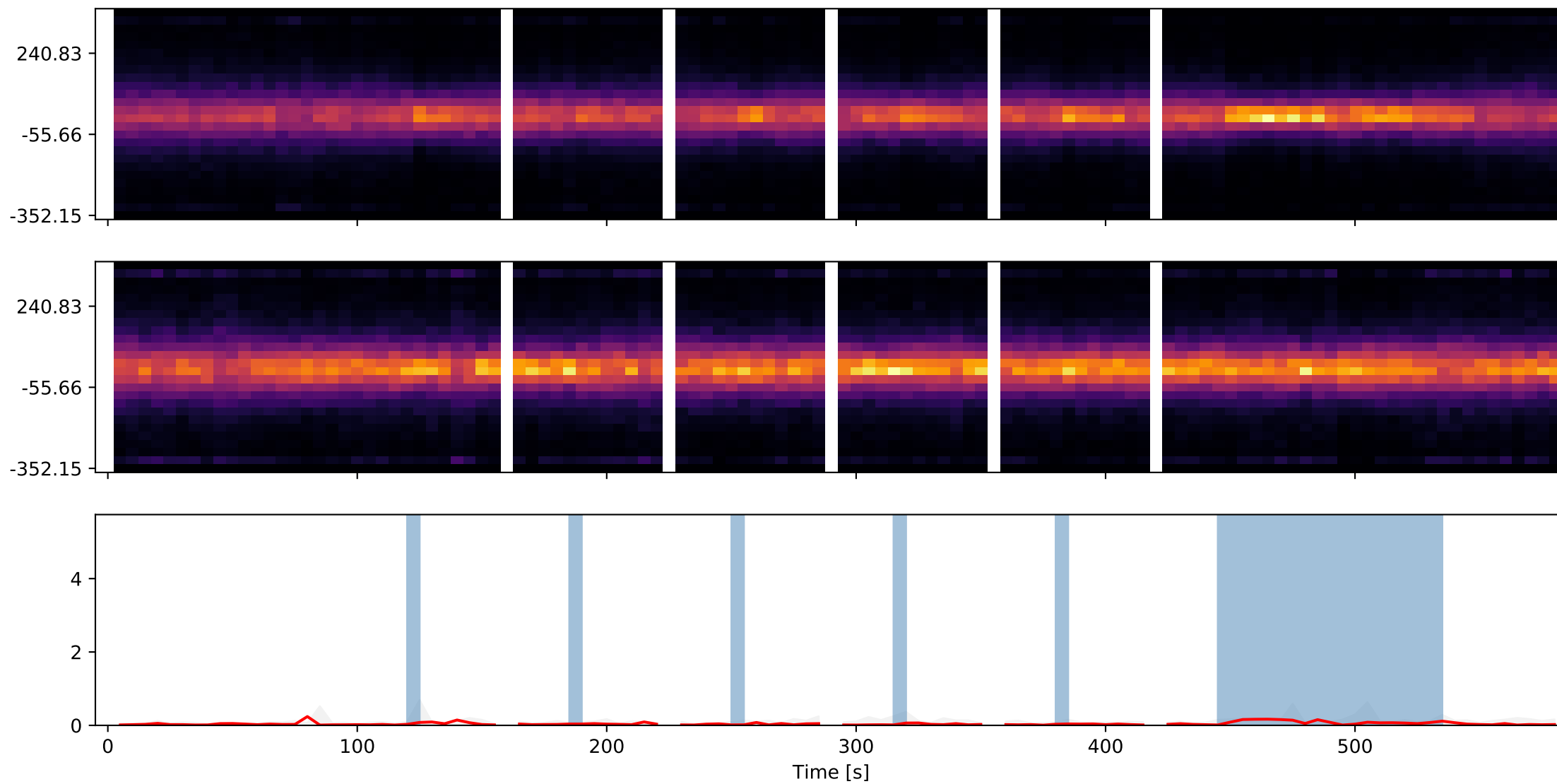
curvature_std_neck



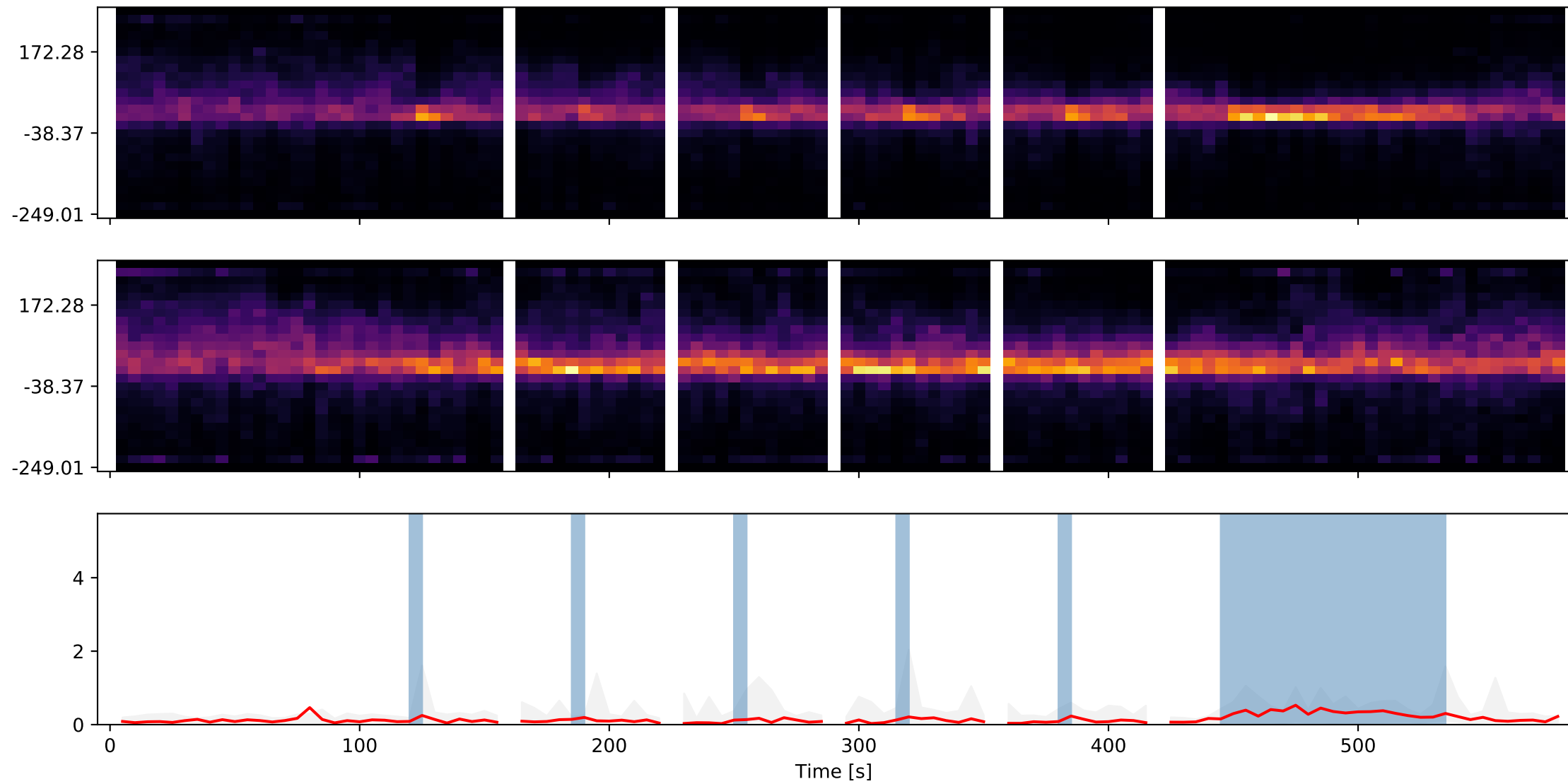
eigen_projection_2



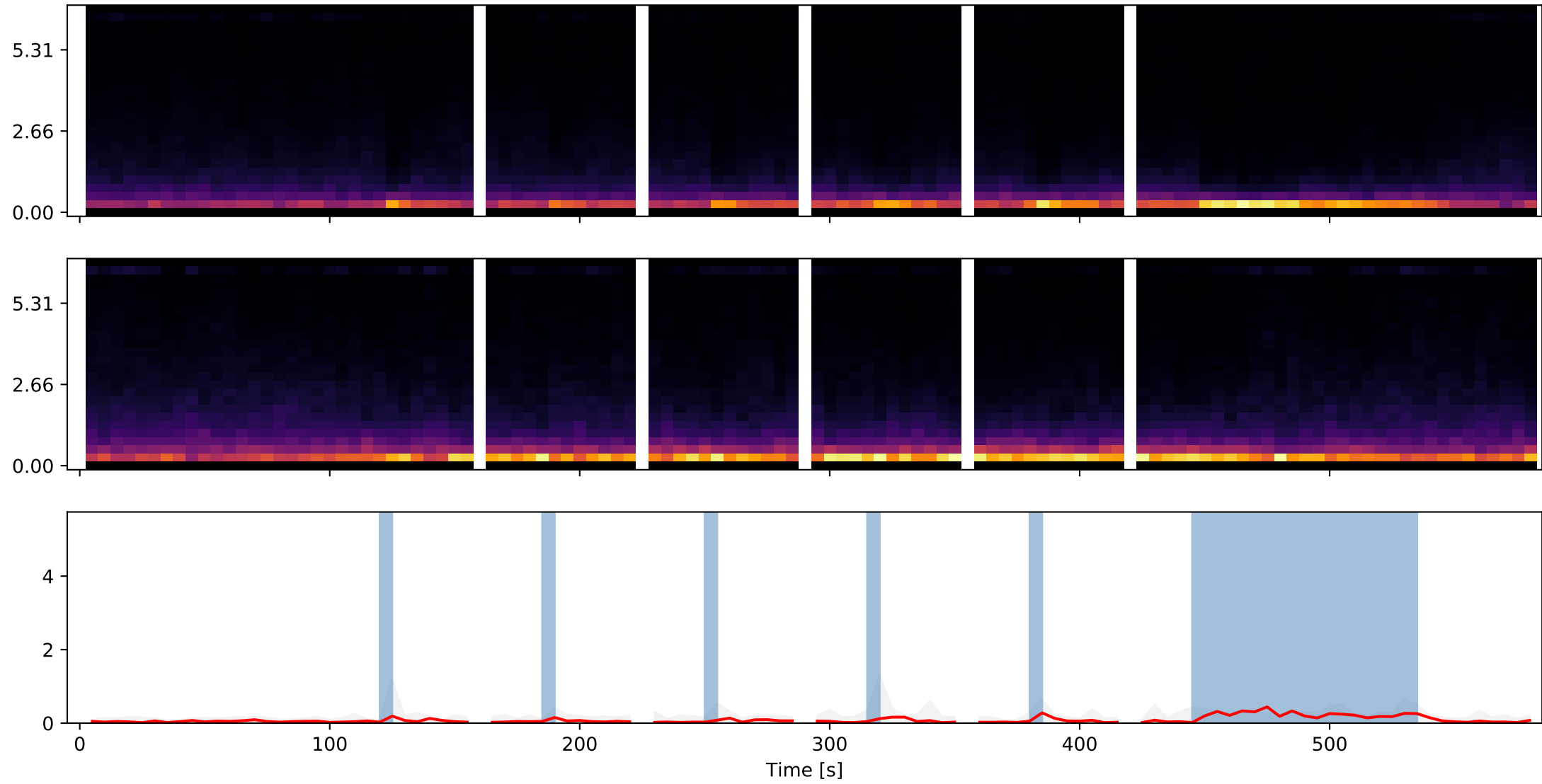
d_relative_to_body_radial_velocity_tail_tip



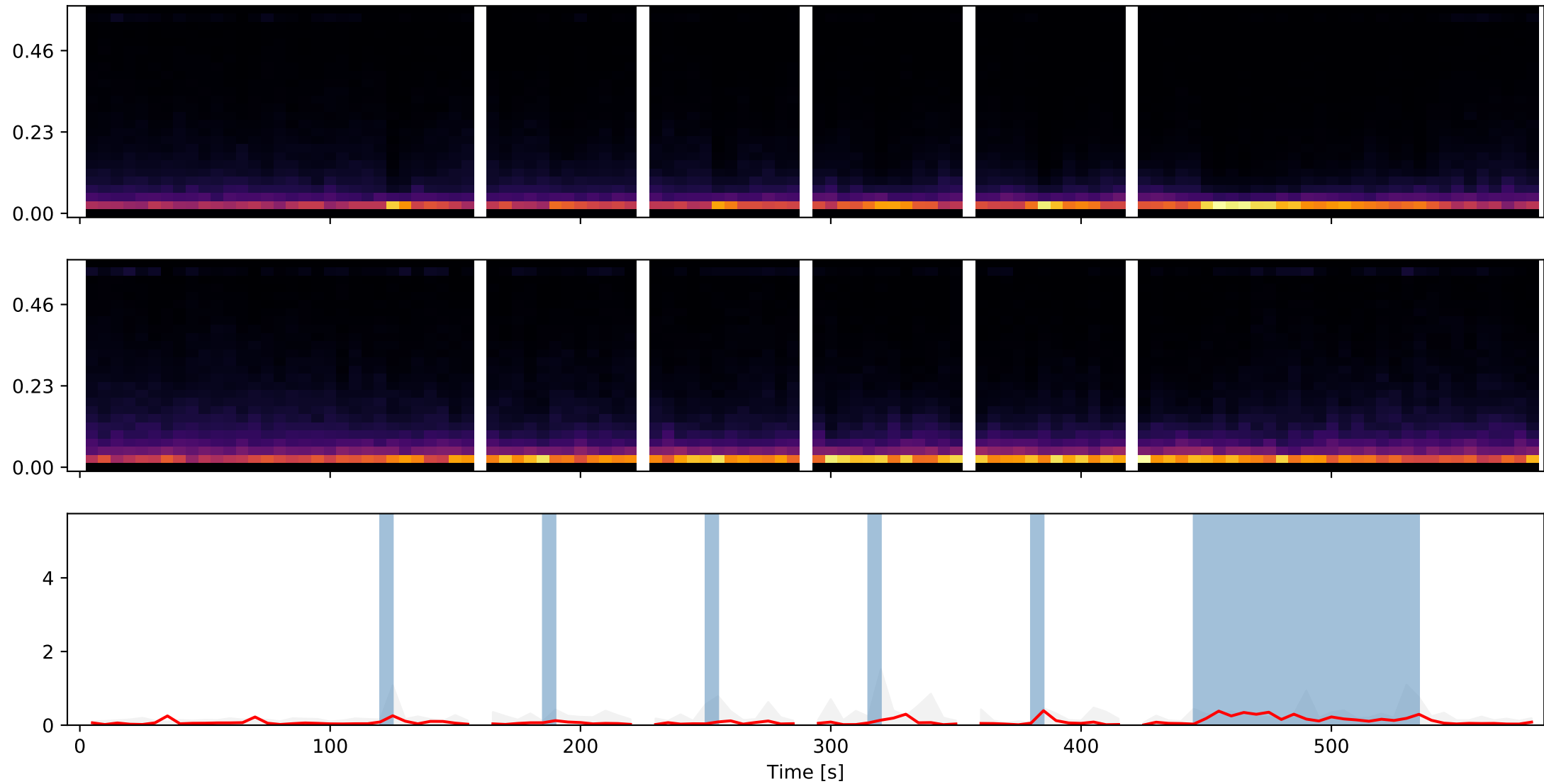
speed_neck



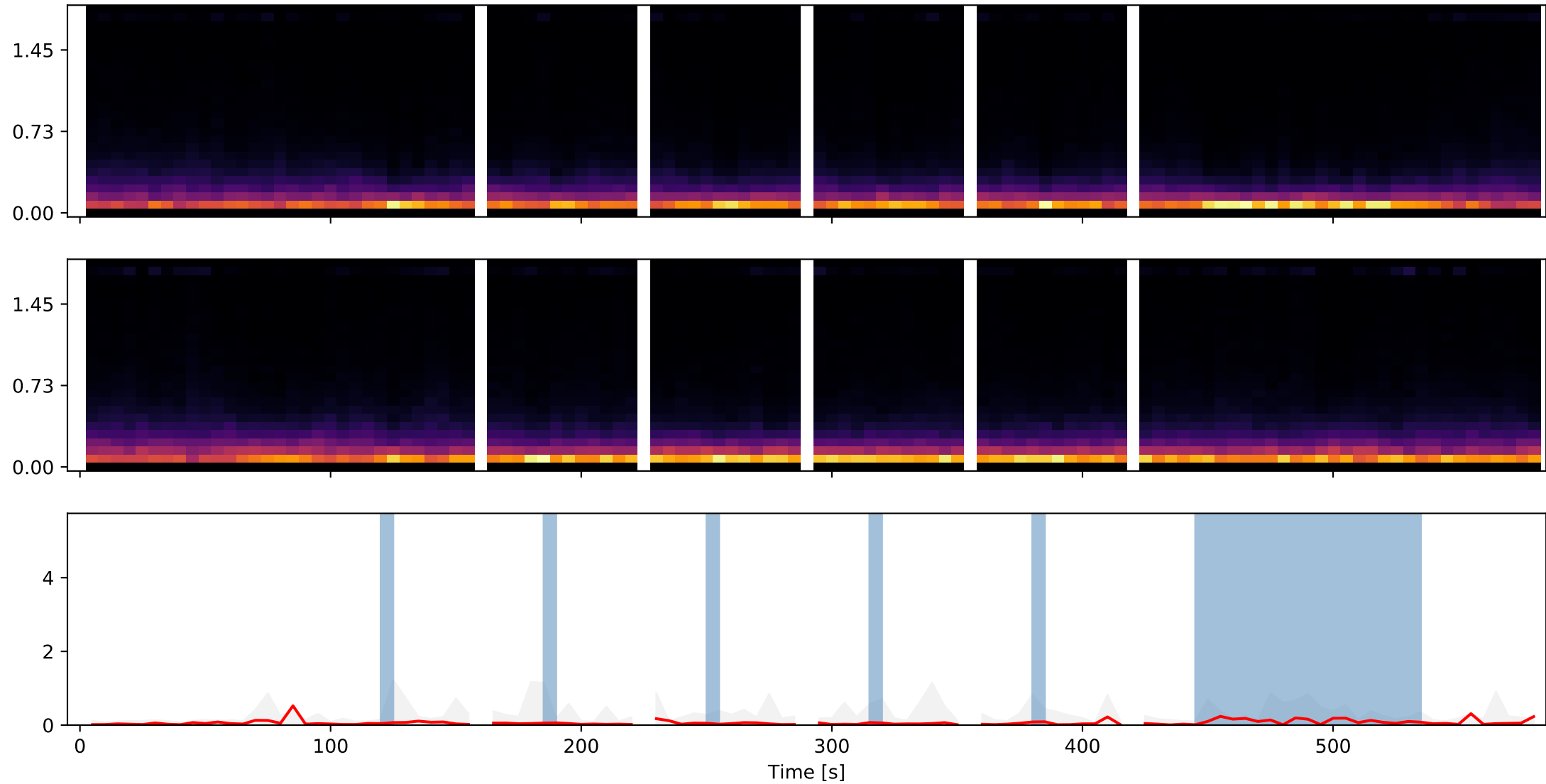
d_eigen_projection_3



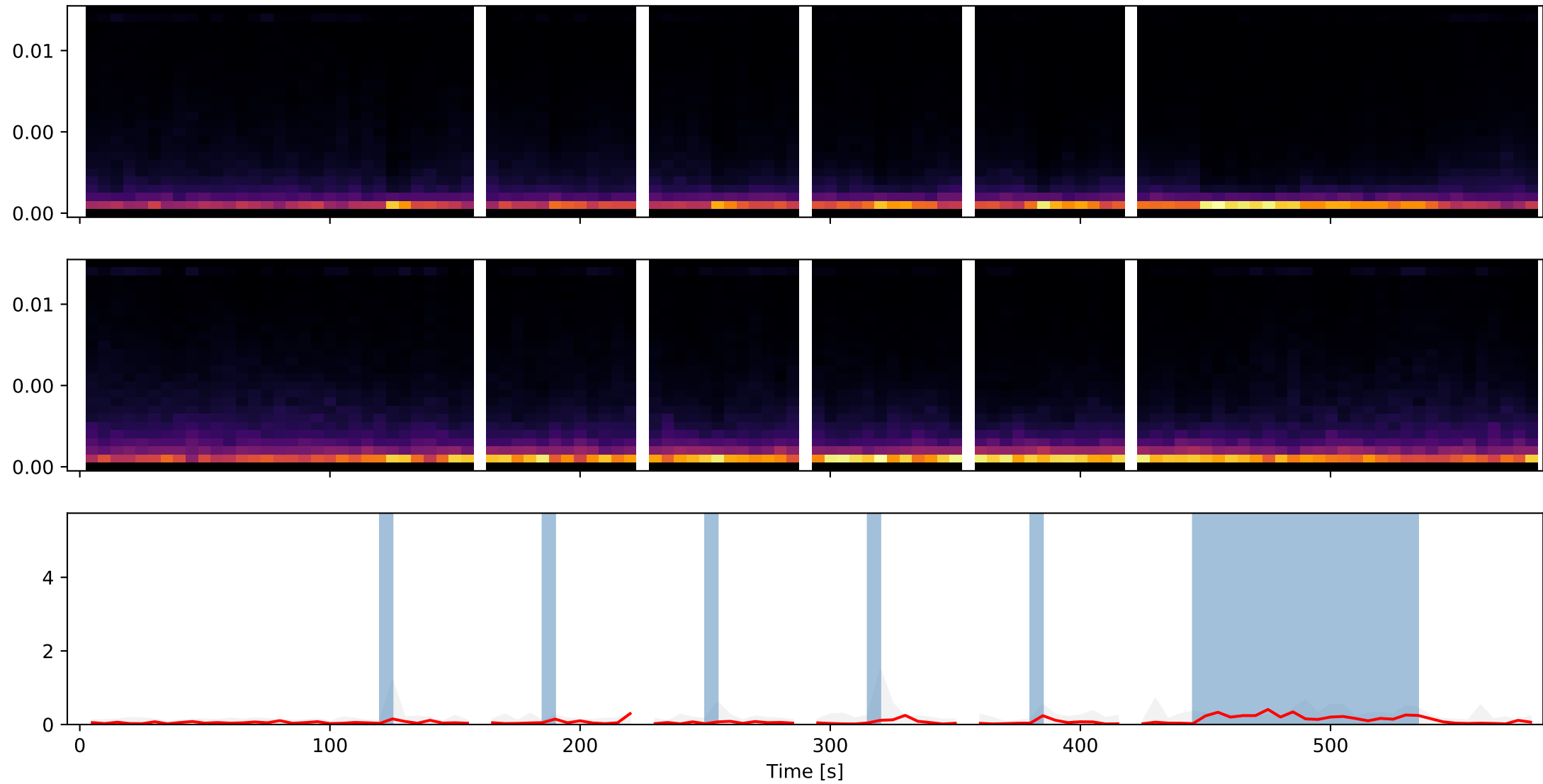
relative_to_body_angular_velocity_hips



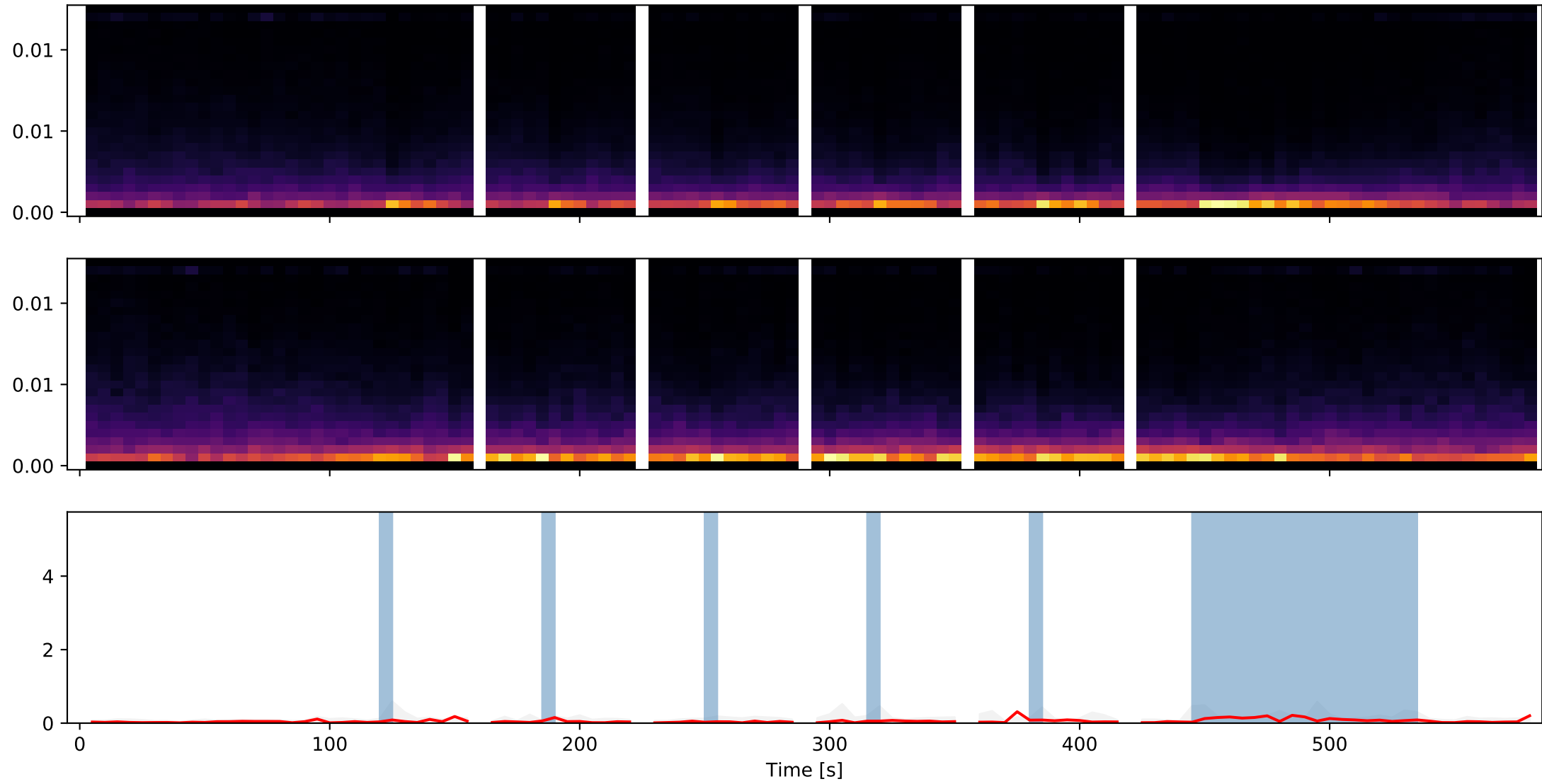
d_angular_velocity



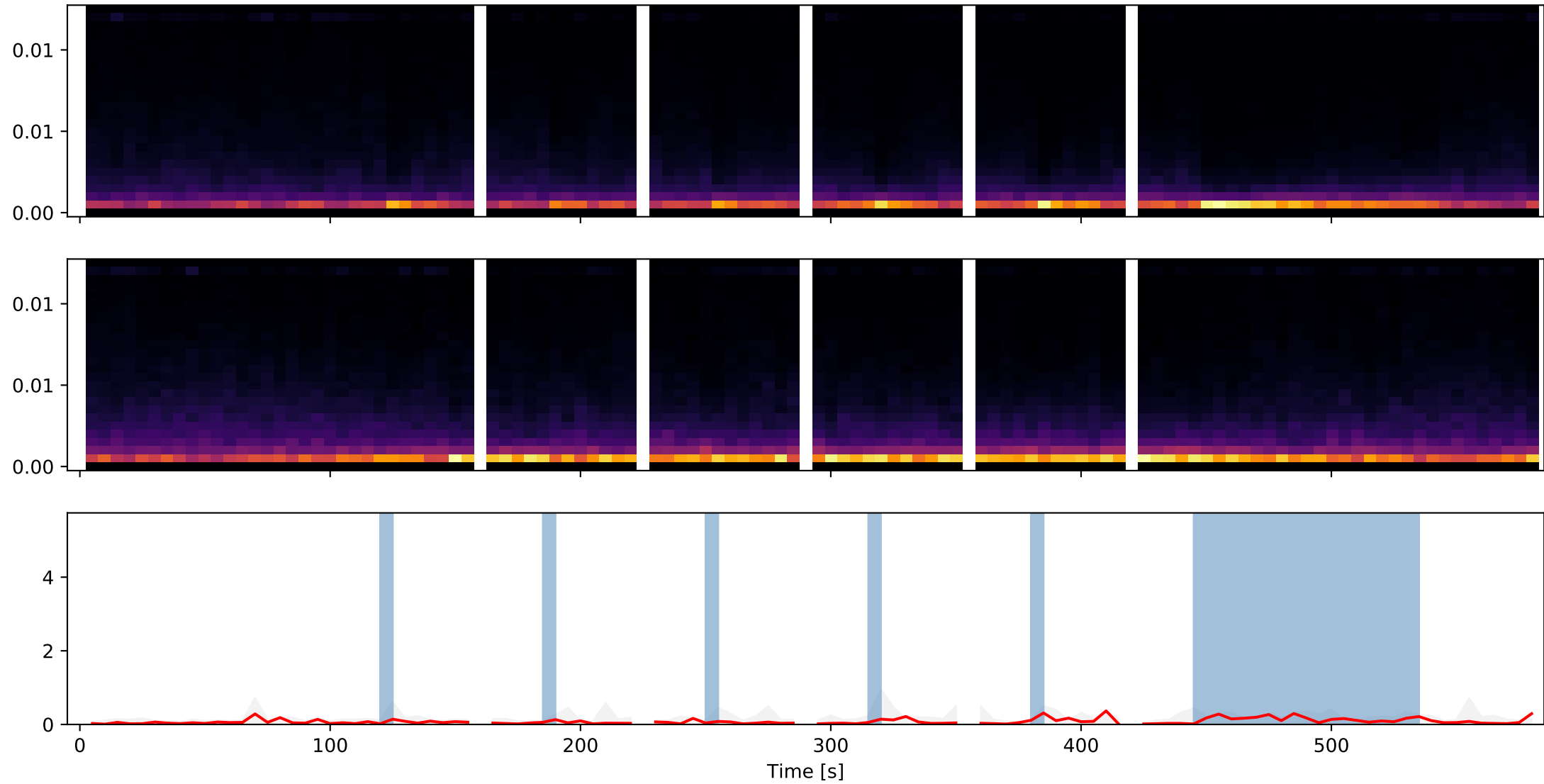
d_curvature_mean_midbody



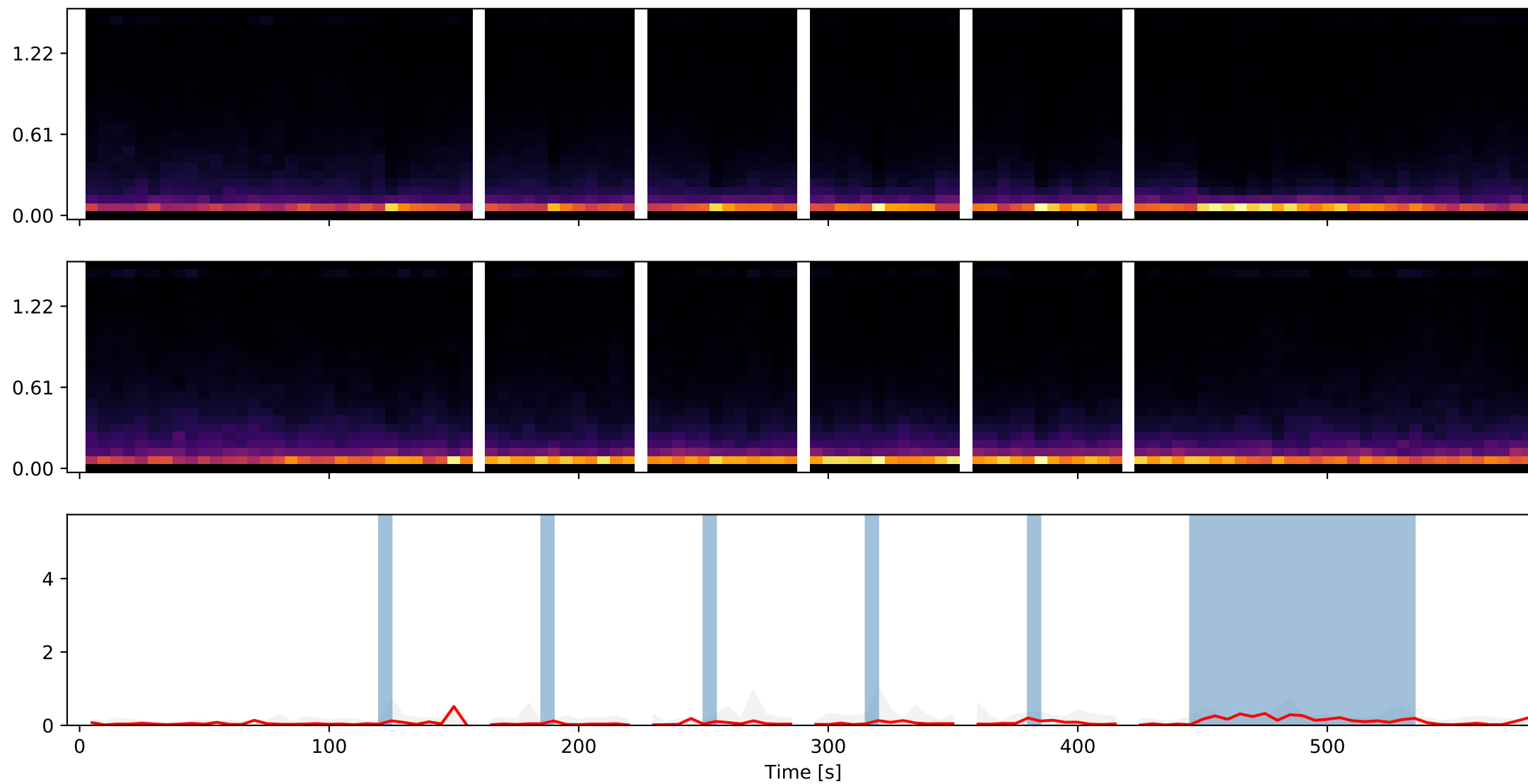
d_curvature_mean_tail



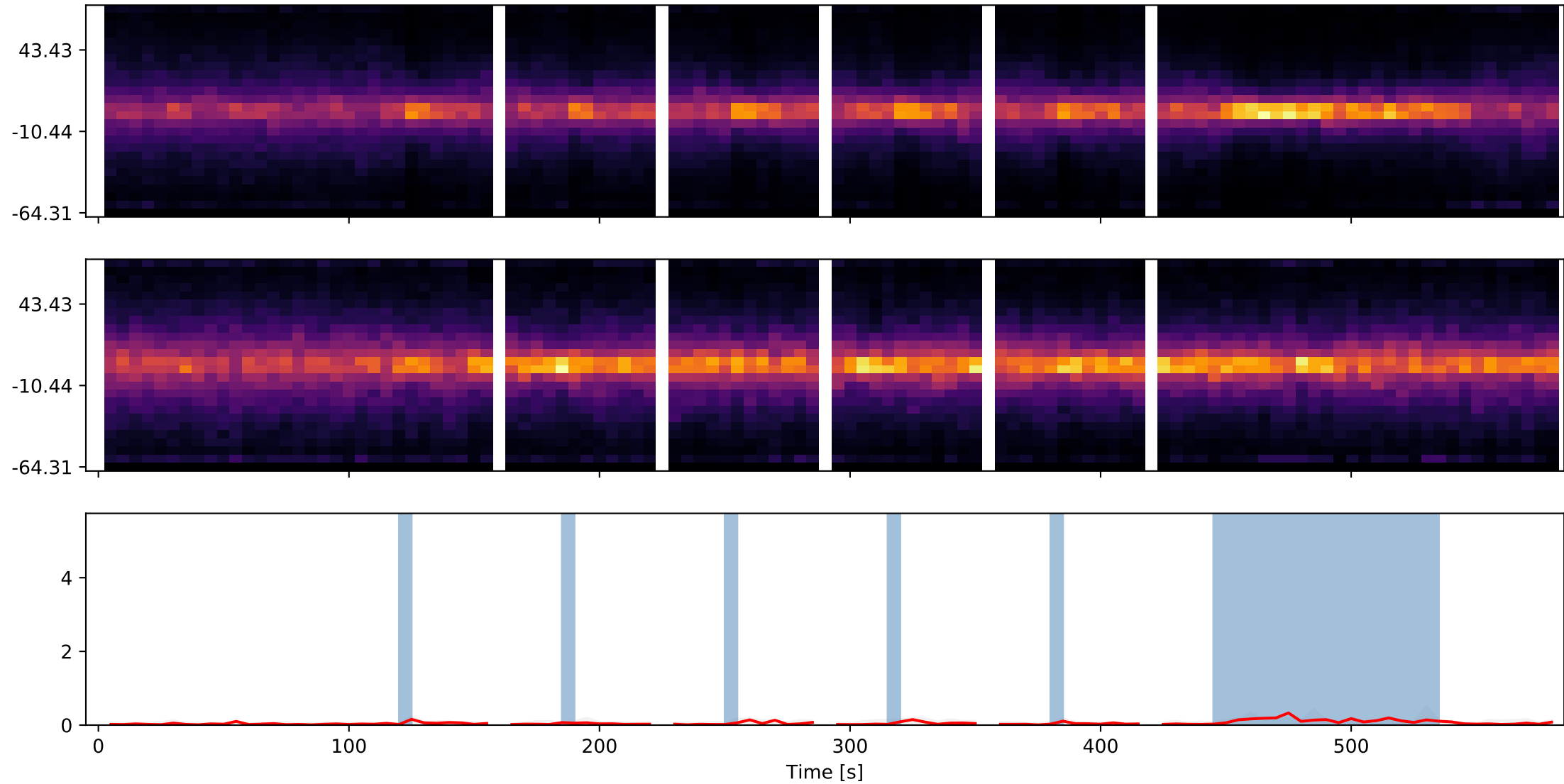
d_curvature_mean_hips



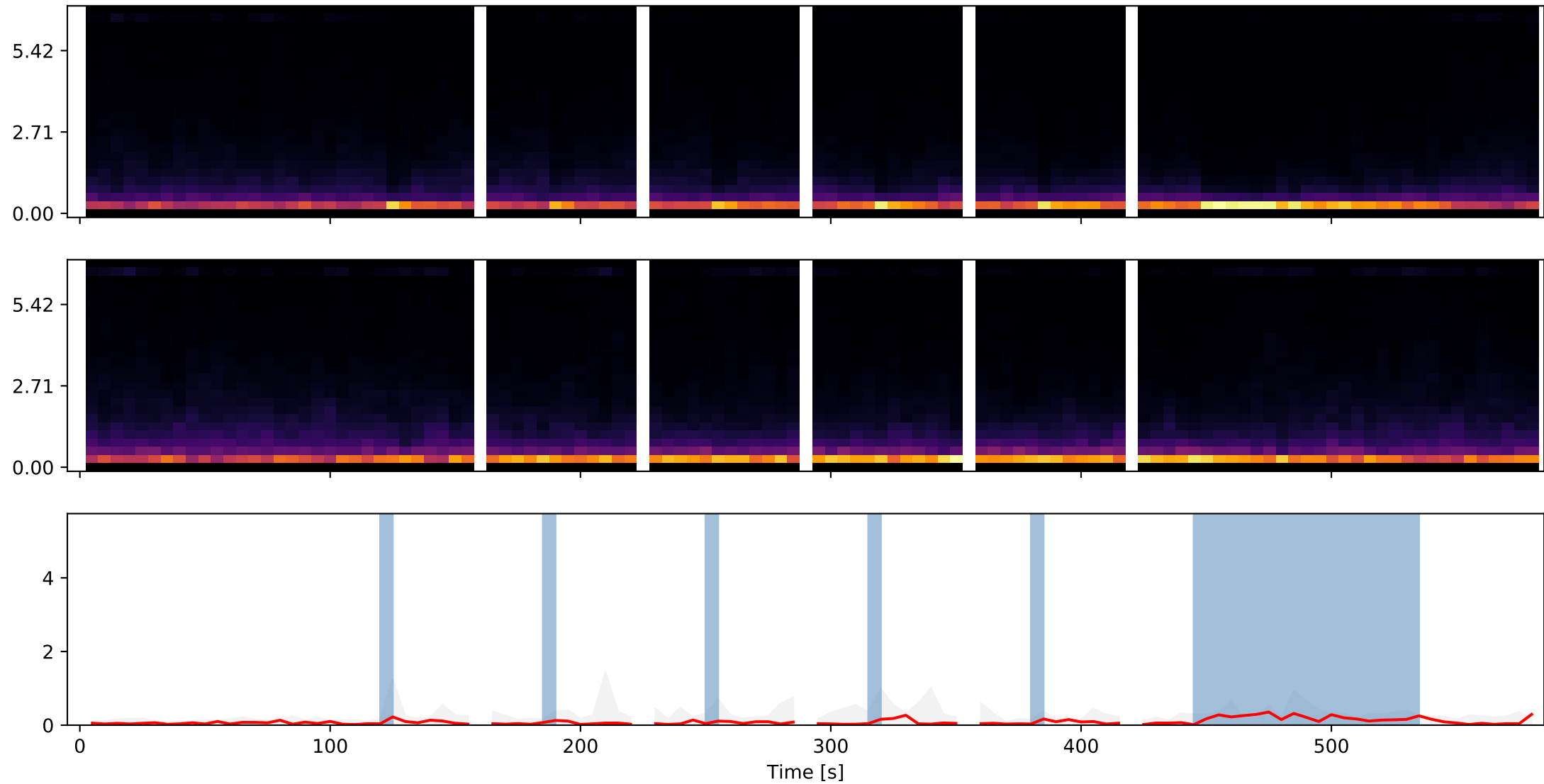
angular_velocity_hips



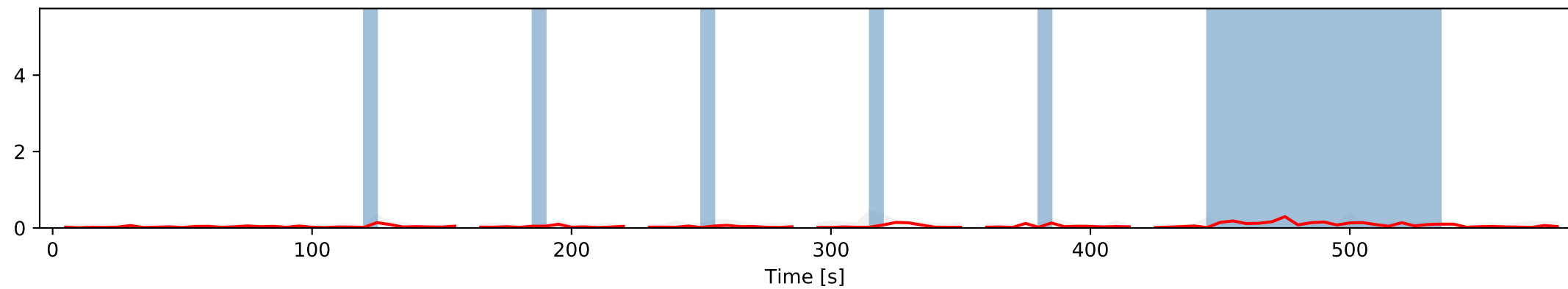
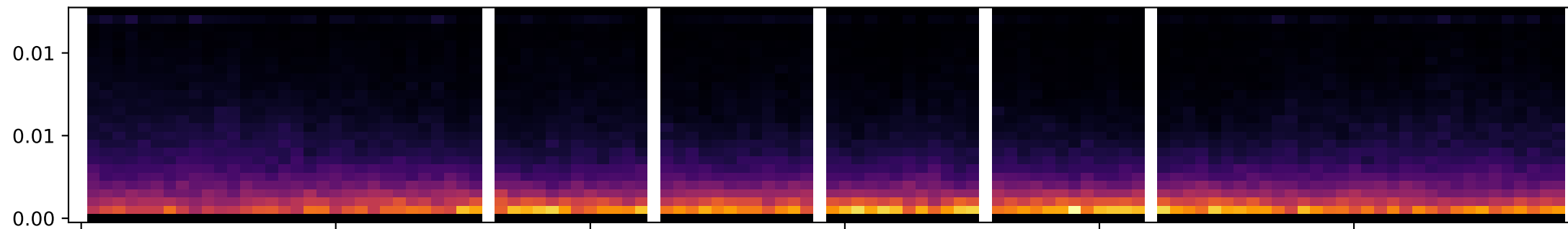
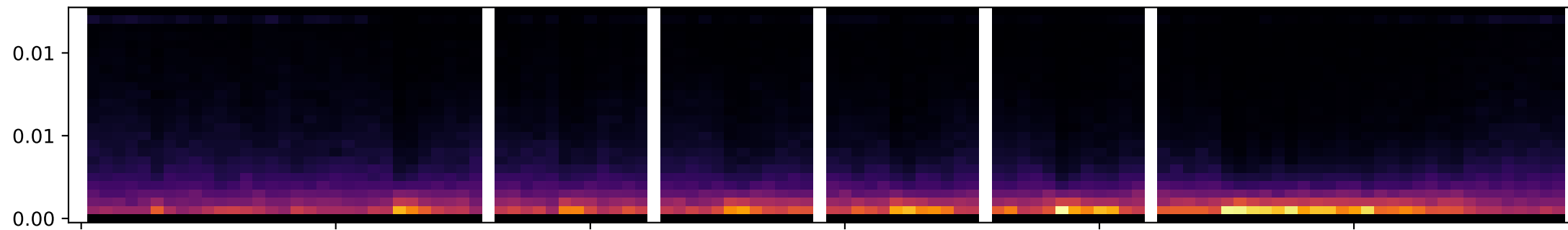
relative_to_neck_radial_velocity_head_tip



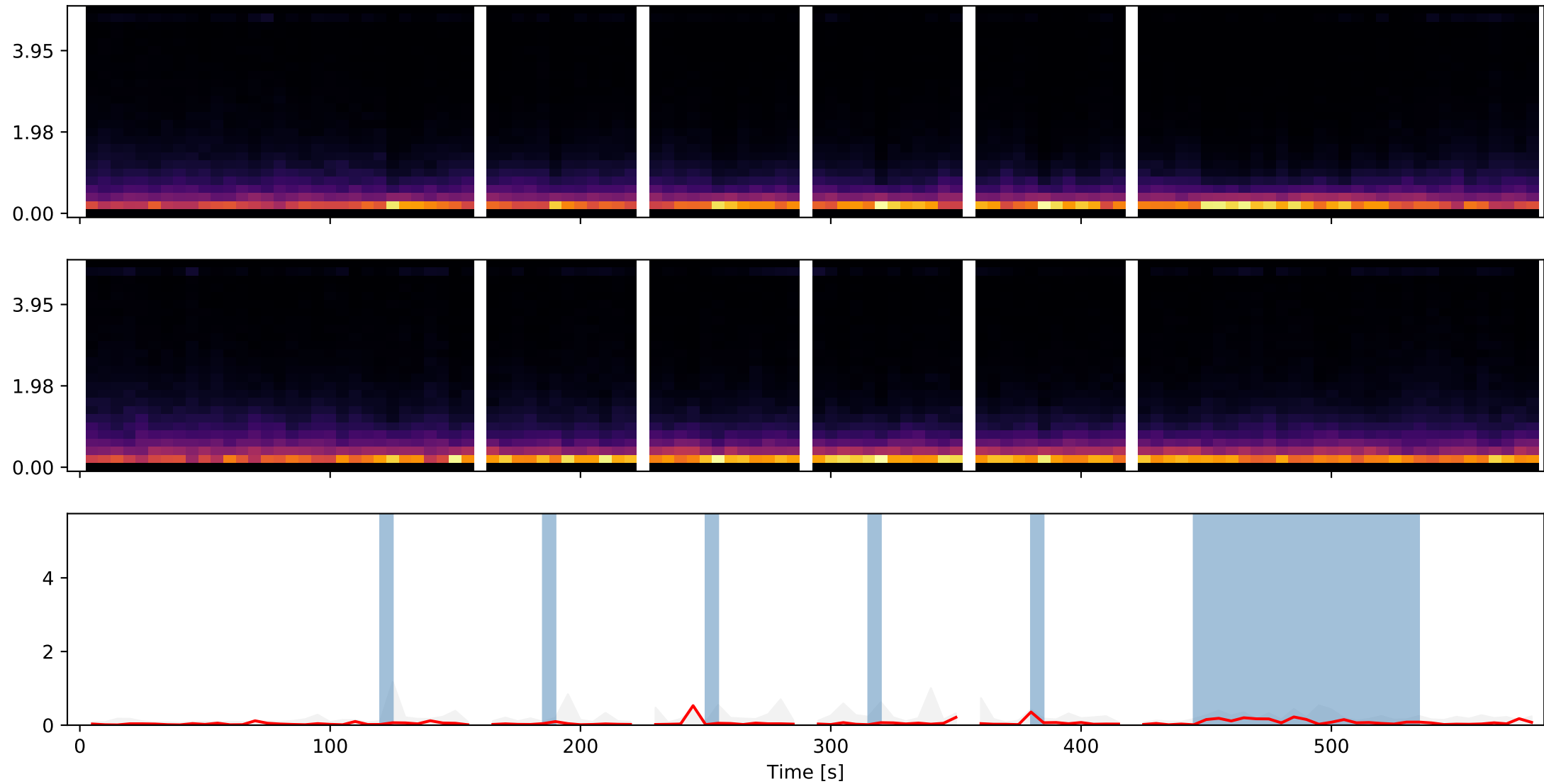
d_eigen_projection_2



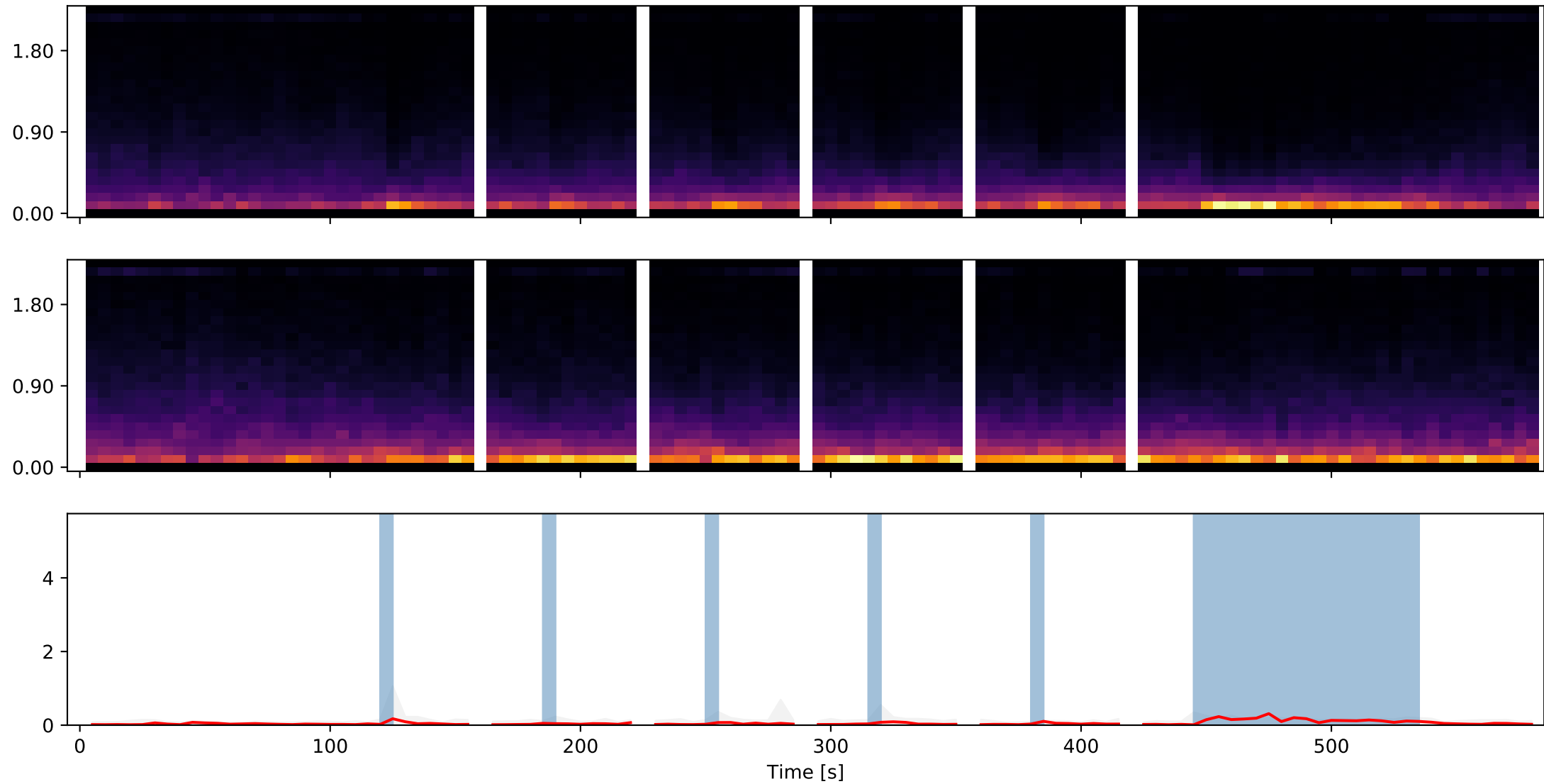
d_curvature_neck



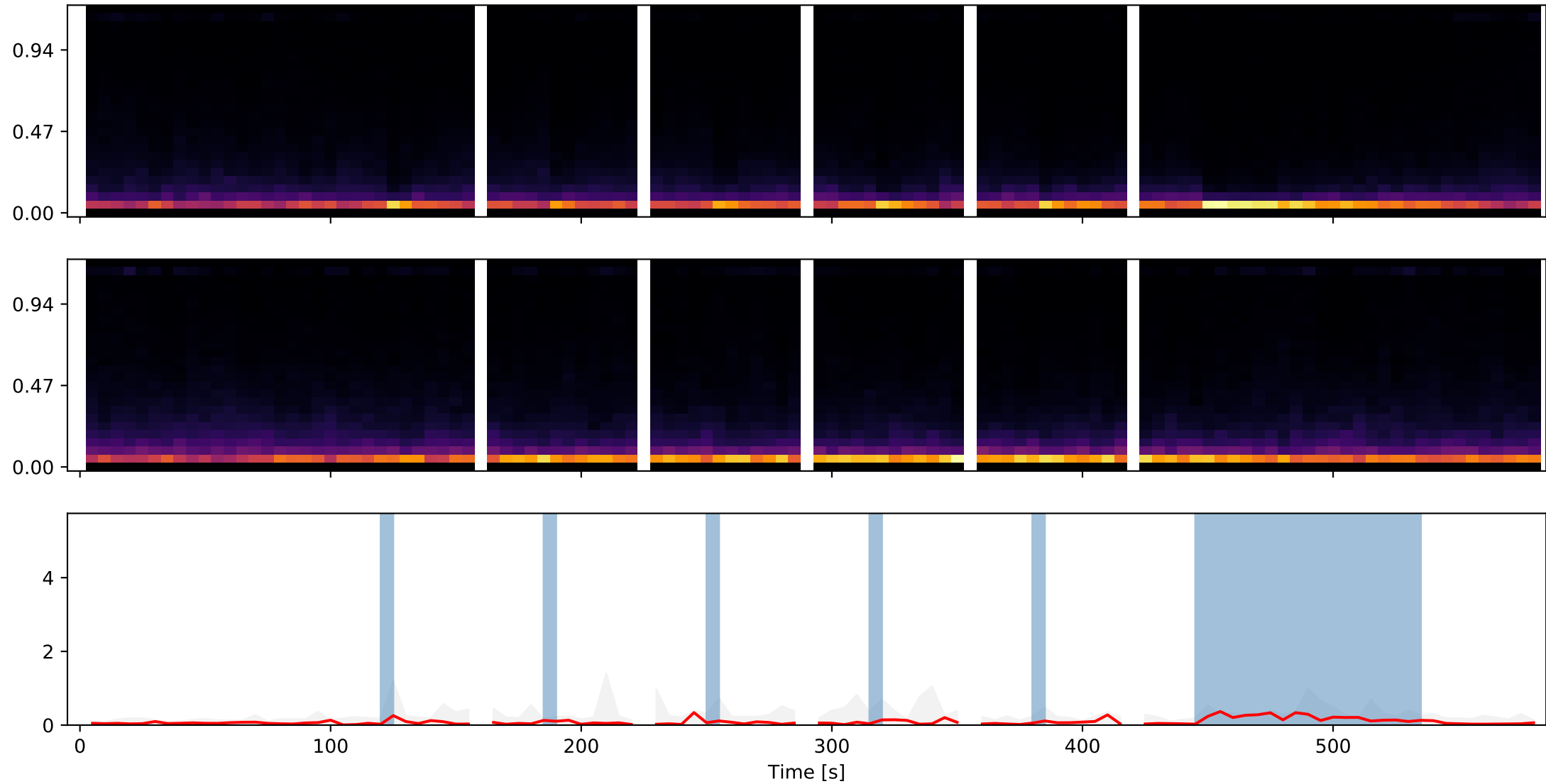
d_angular_velocity_hips



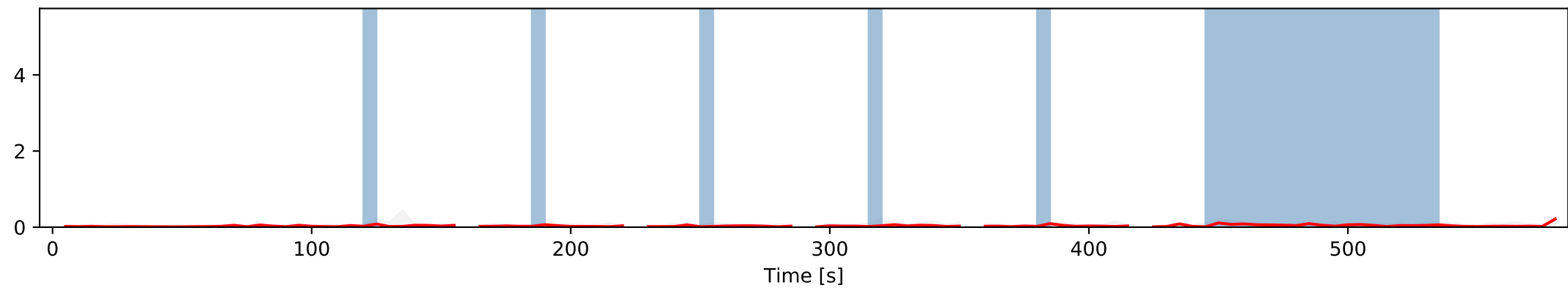
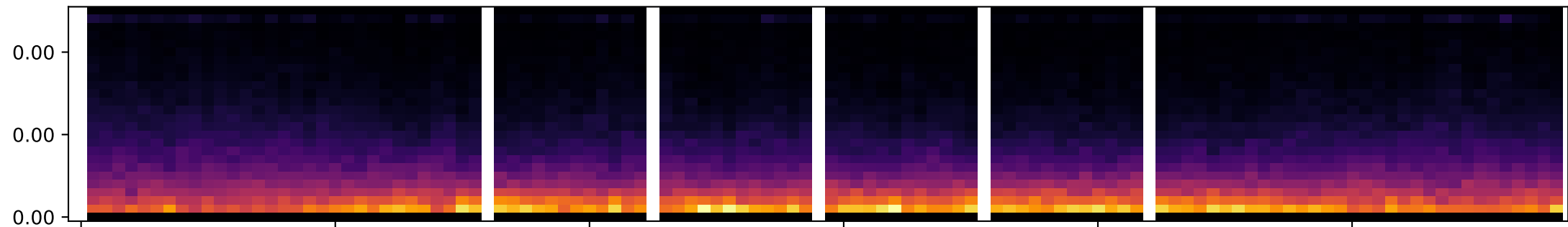
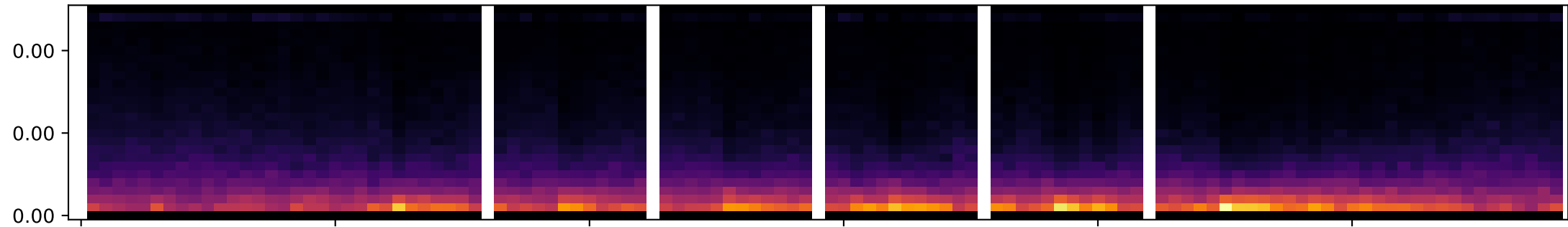
angular_velocity_head_base



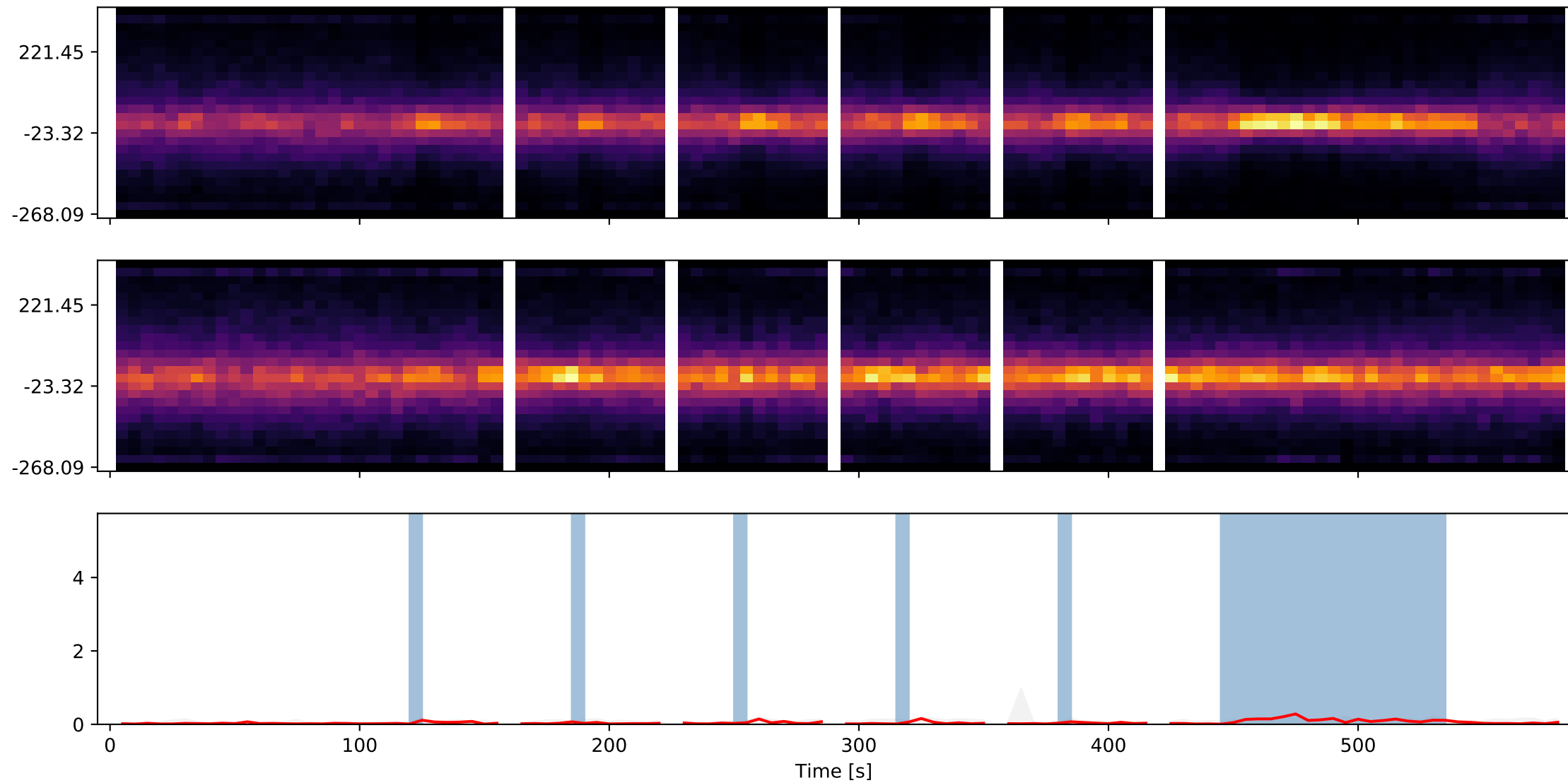
angular_velocity_midbody



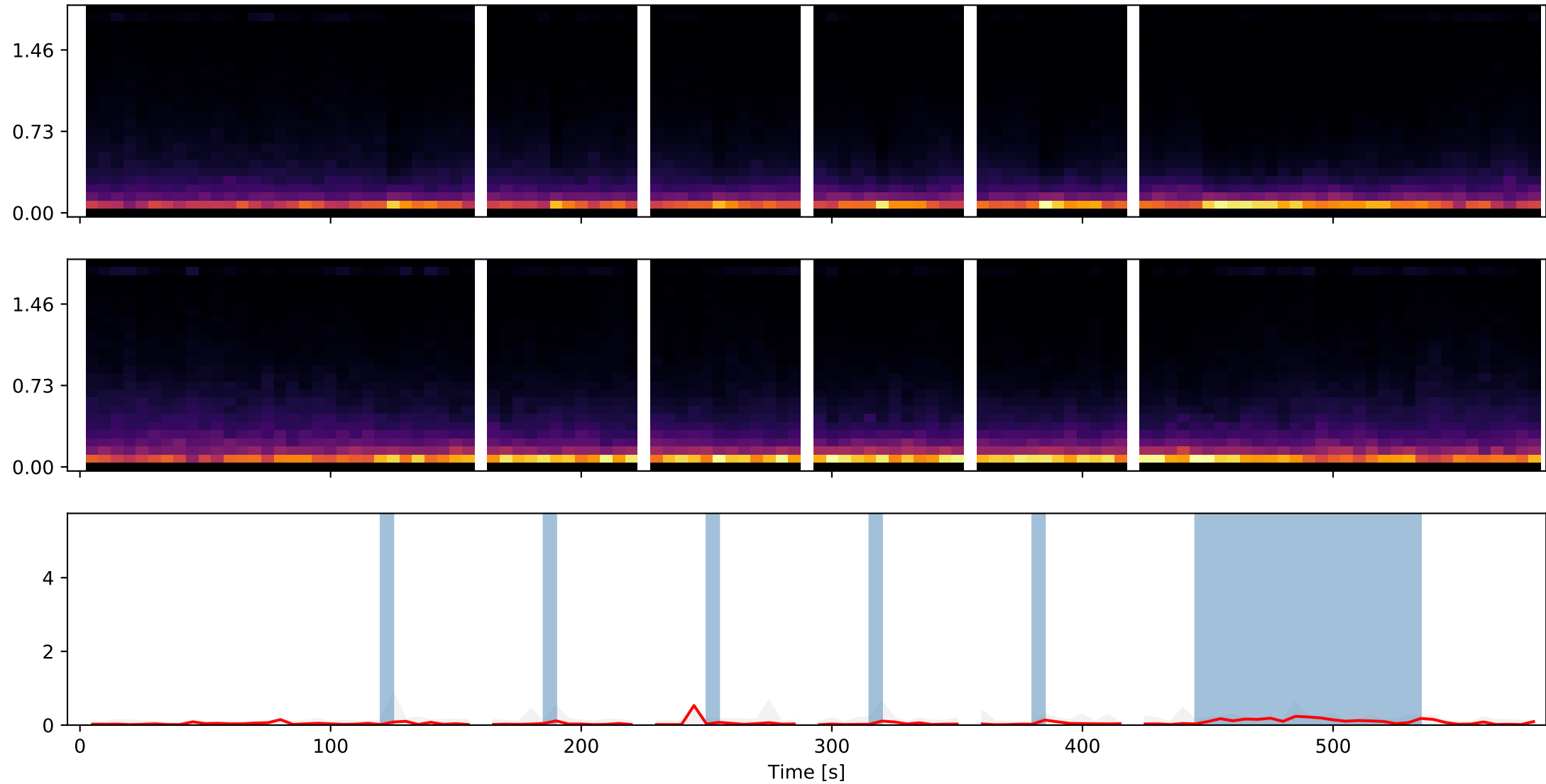
d_curvature_std_hips



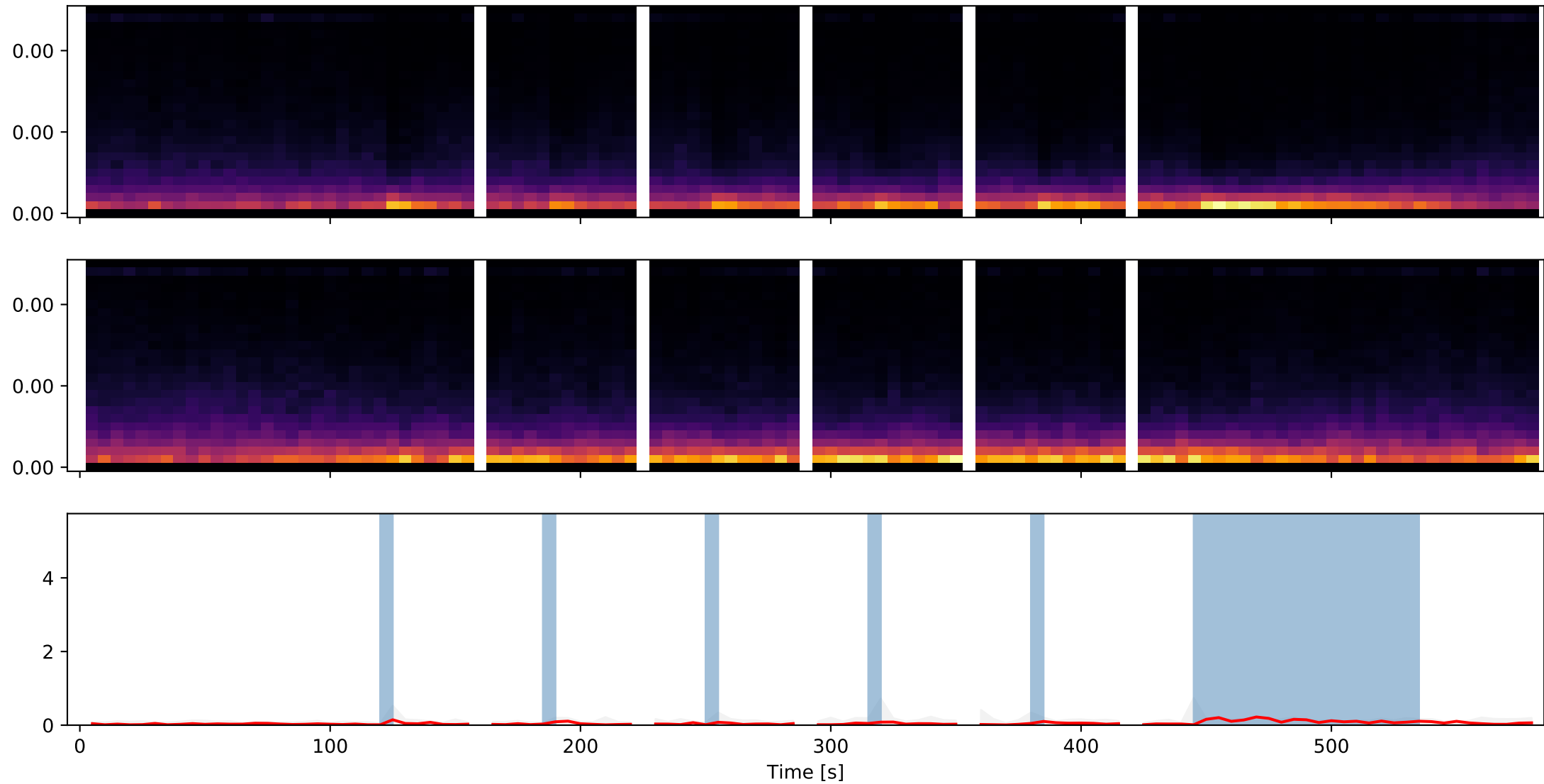
d_relative_to_neck_radial_velocity_head_tip



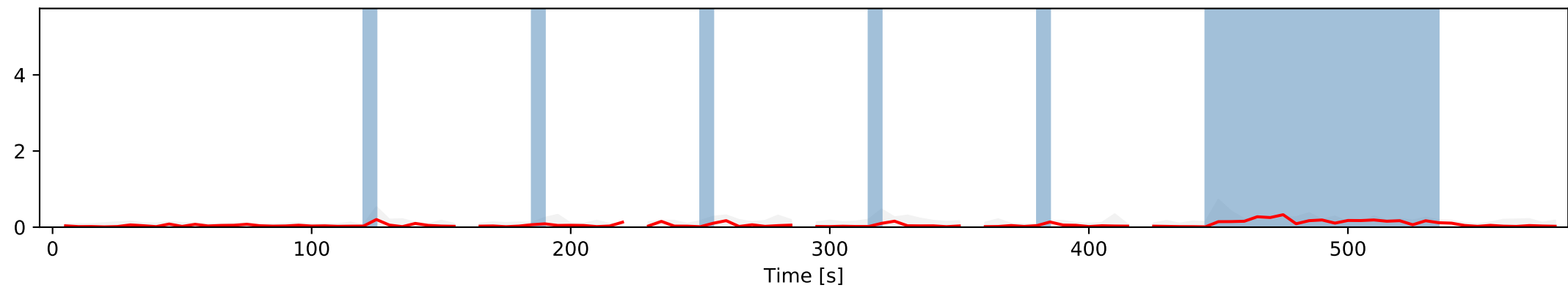
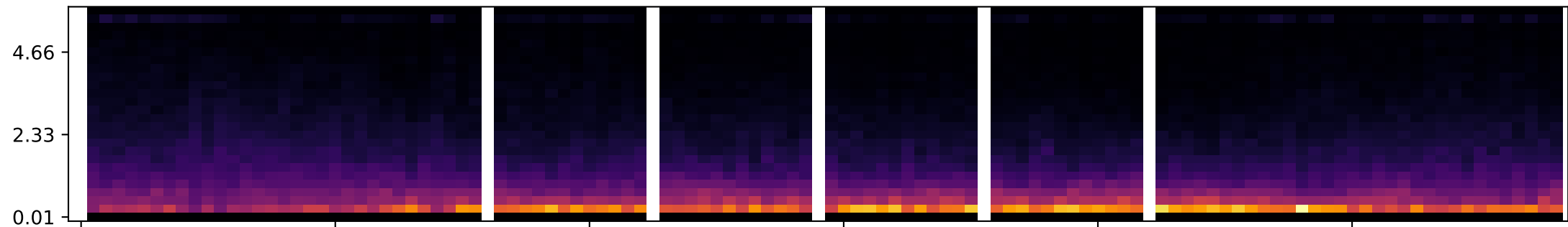
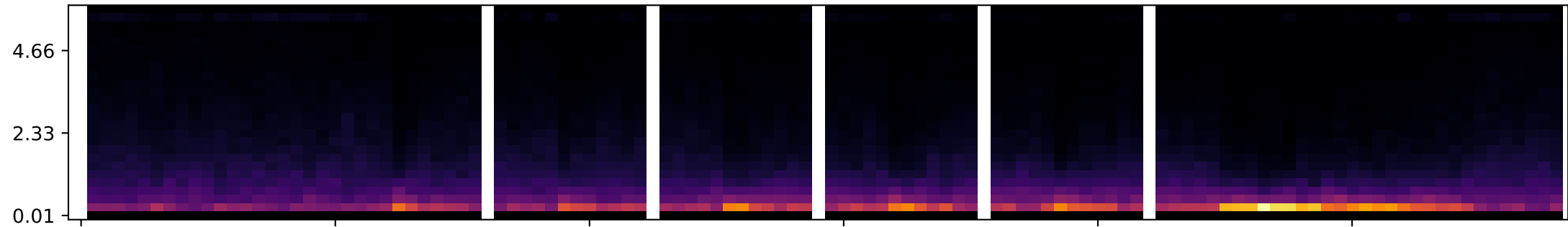
angular_velocity_tail_base



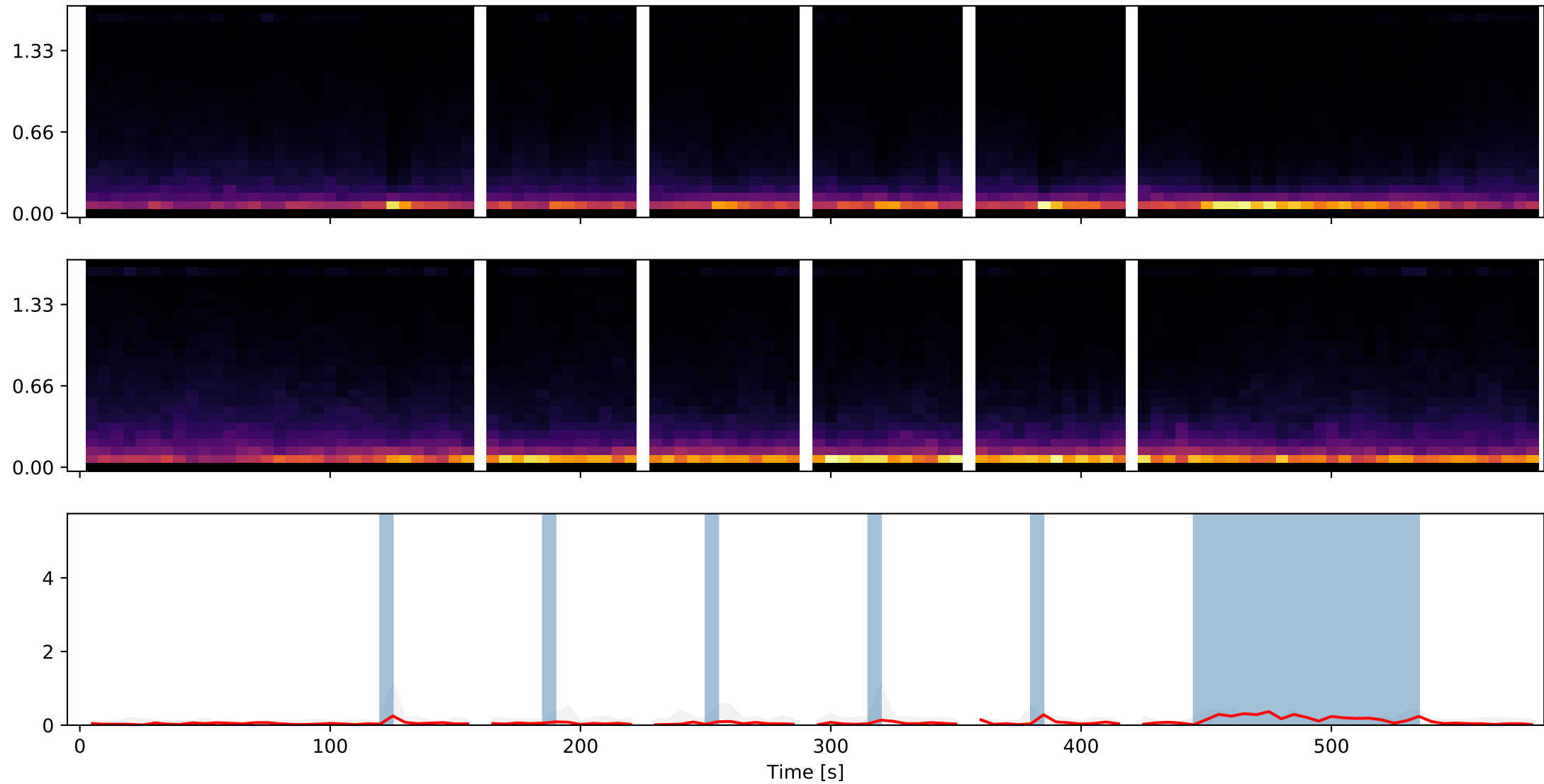
d_curvature_std_midbody



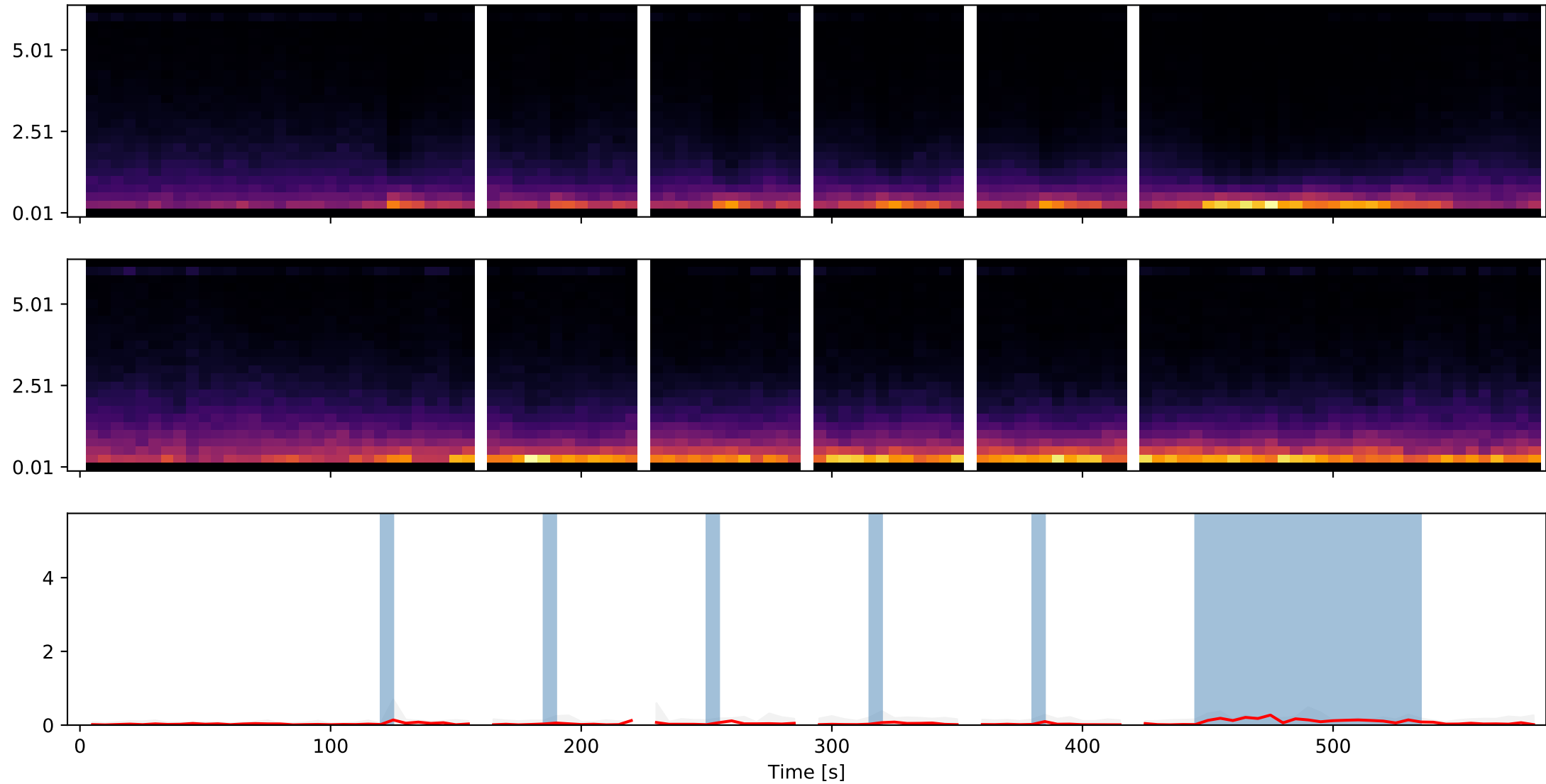
d_eigen_projection_1



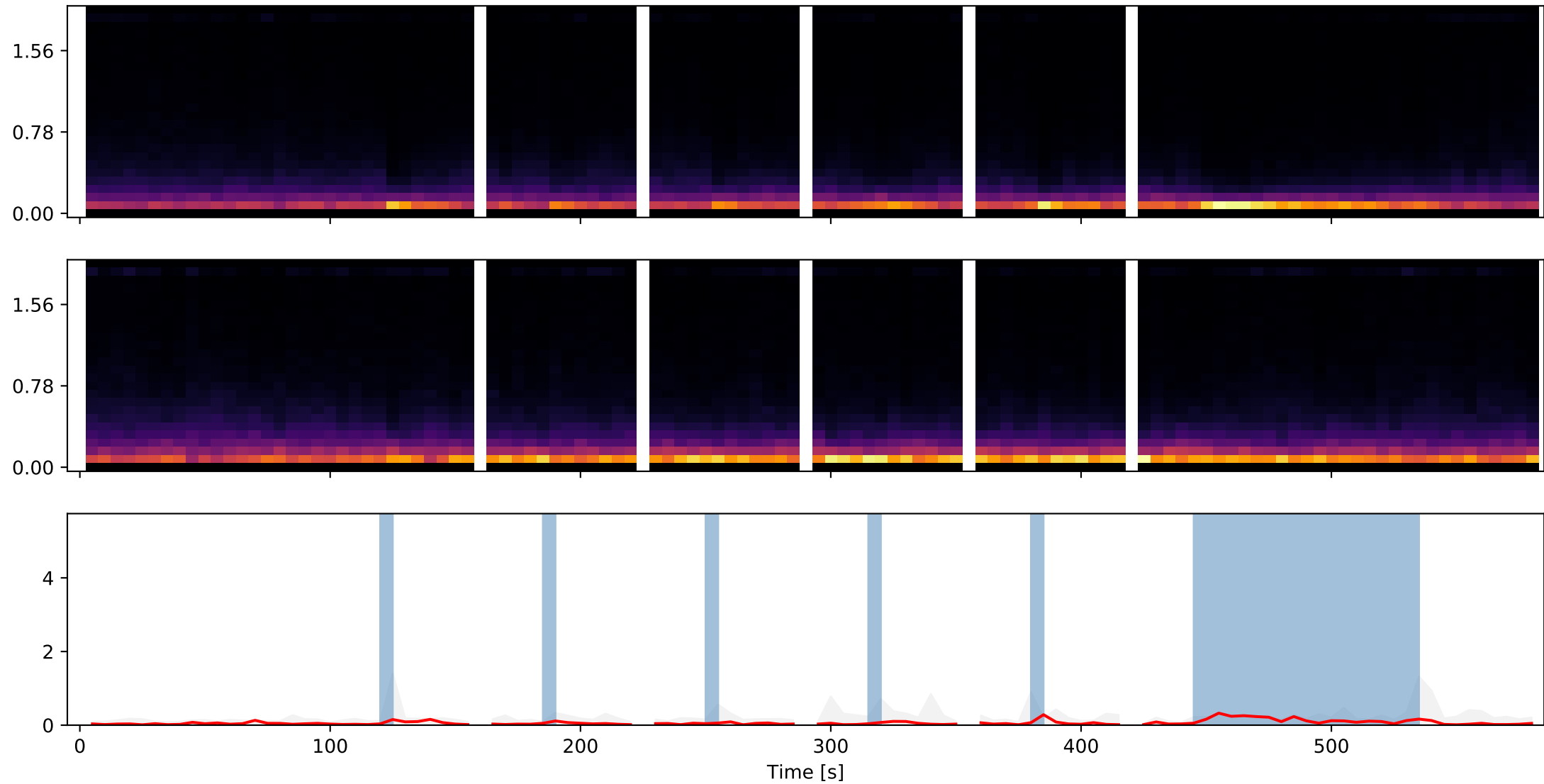
angular_velocity_neck



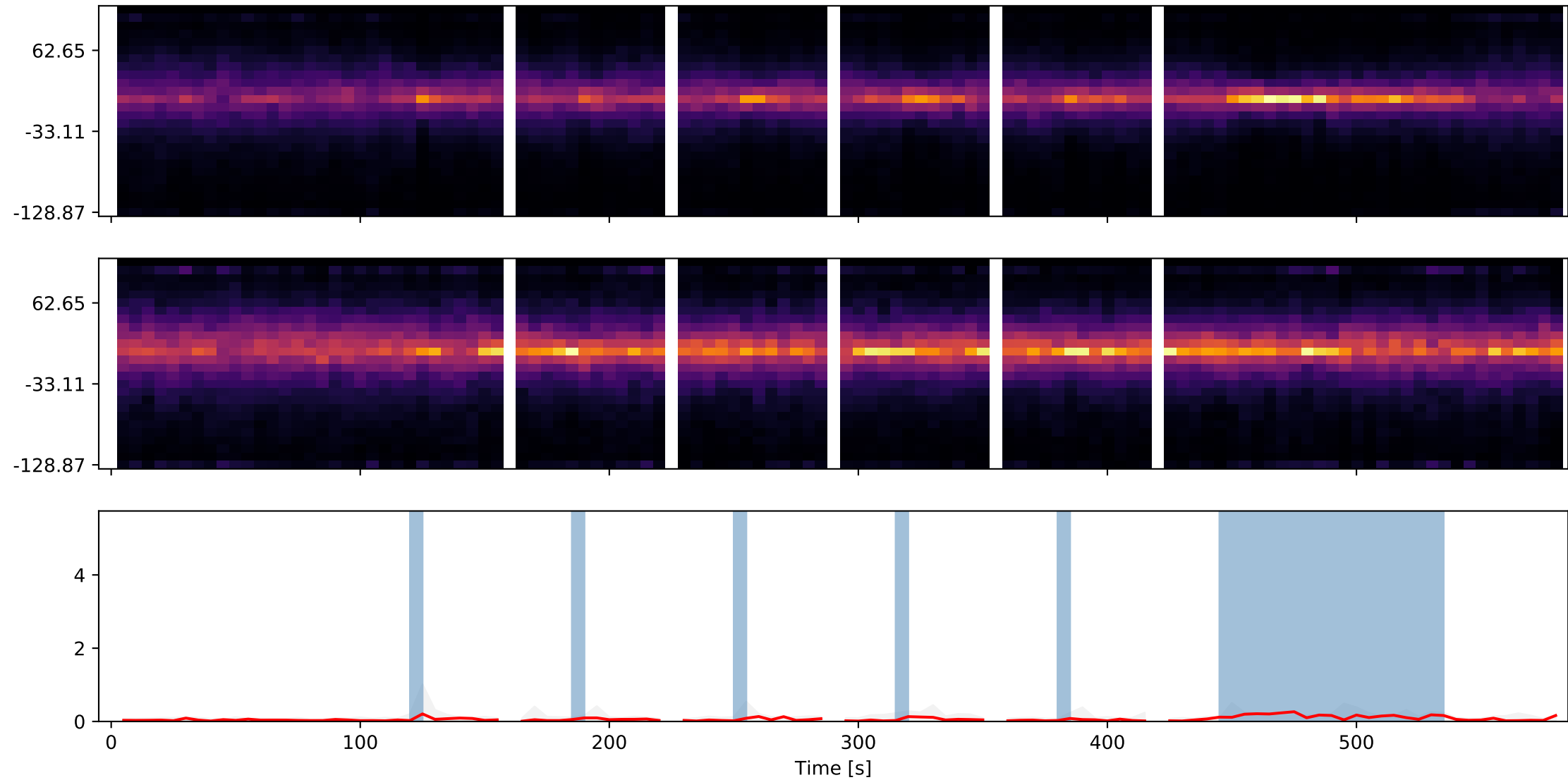
d_relative_to_neck_angular_velocity_head_tip



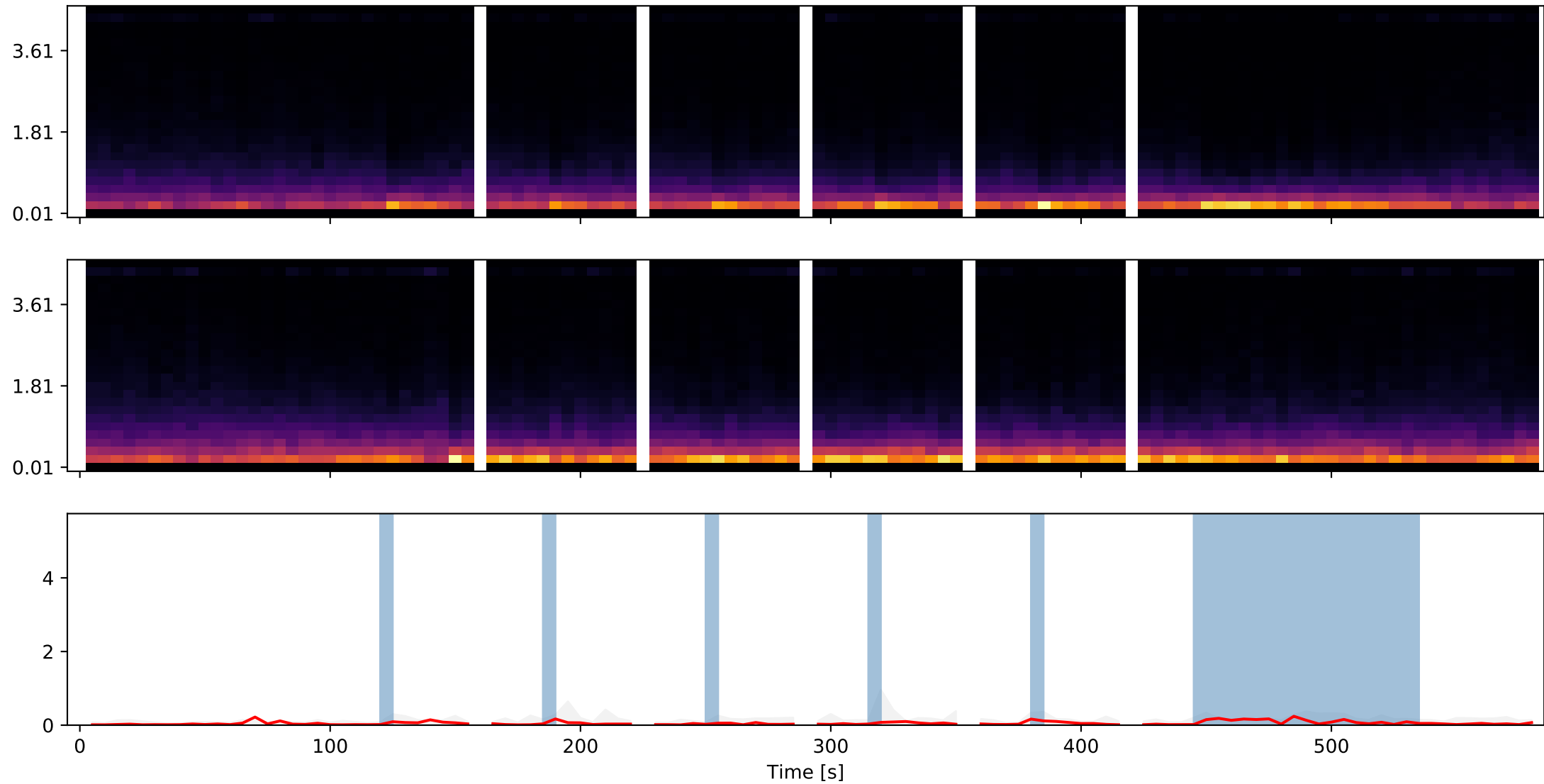
d_relative_to_body_angular_velocity_hips



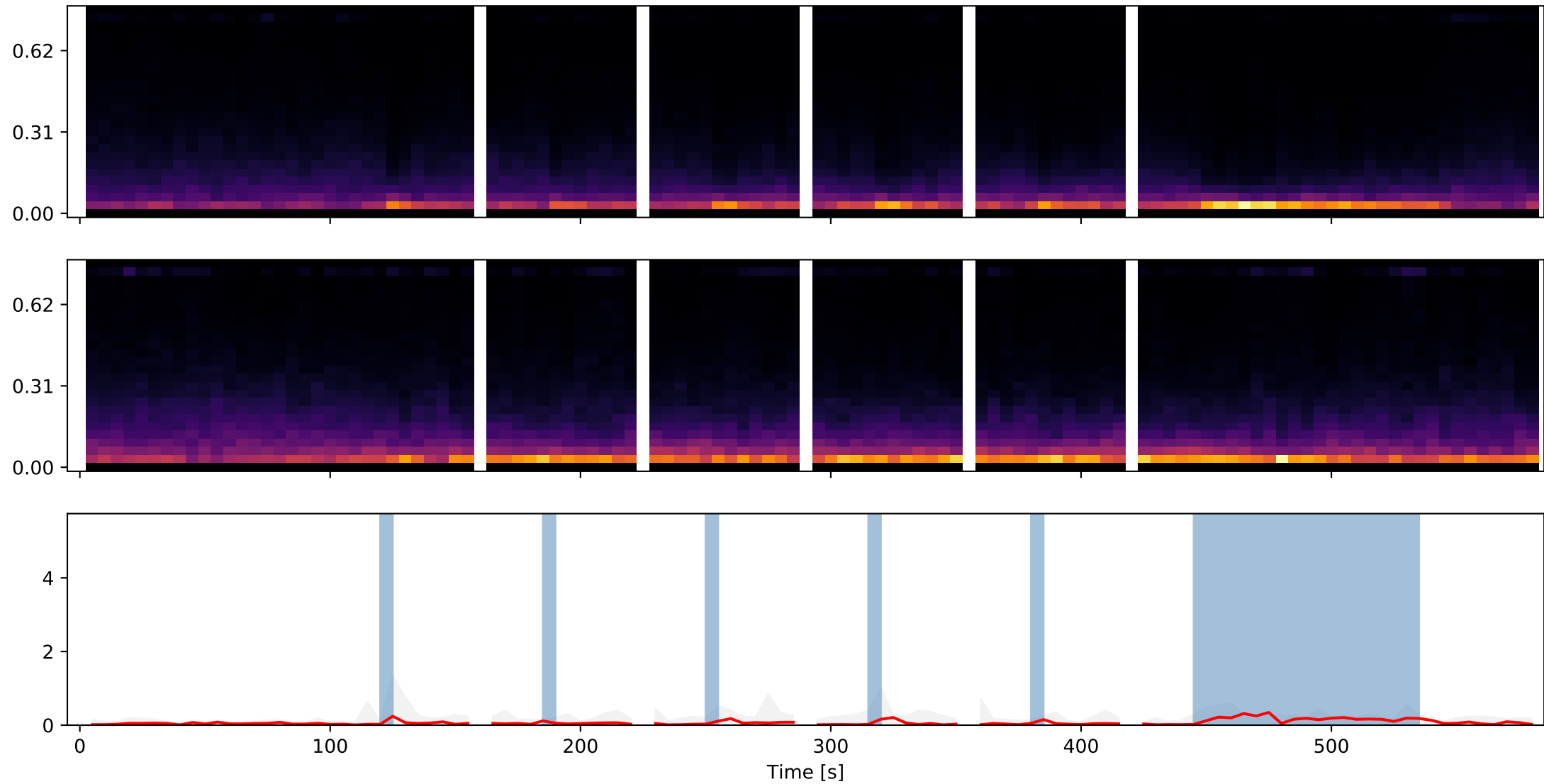
relative_to_body_radial_velocity_head_tip



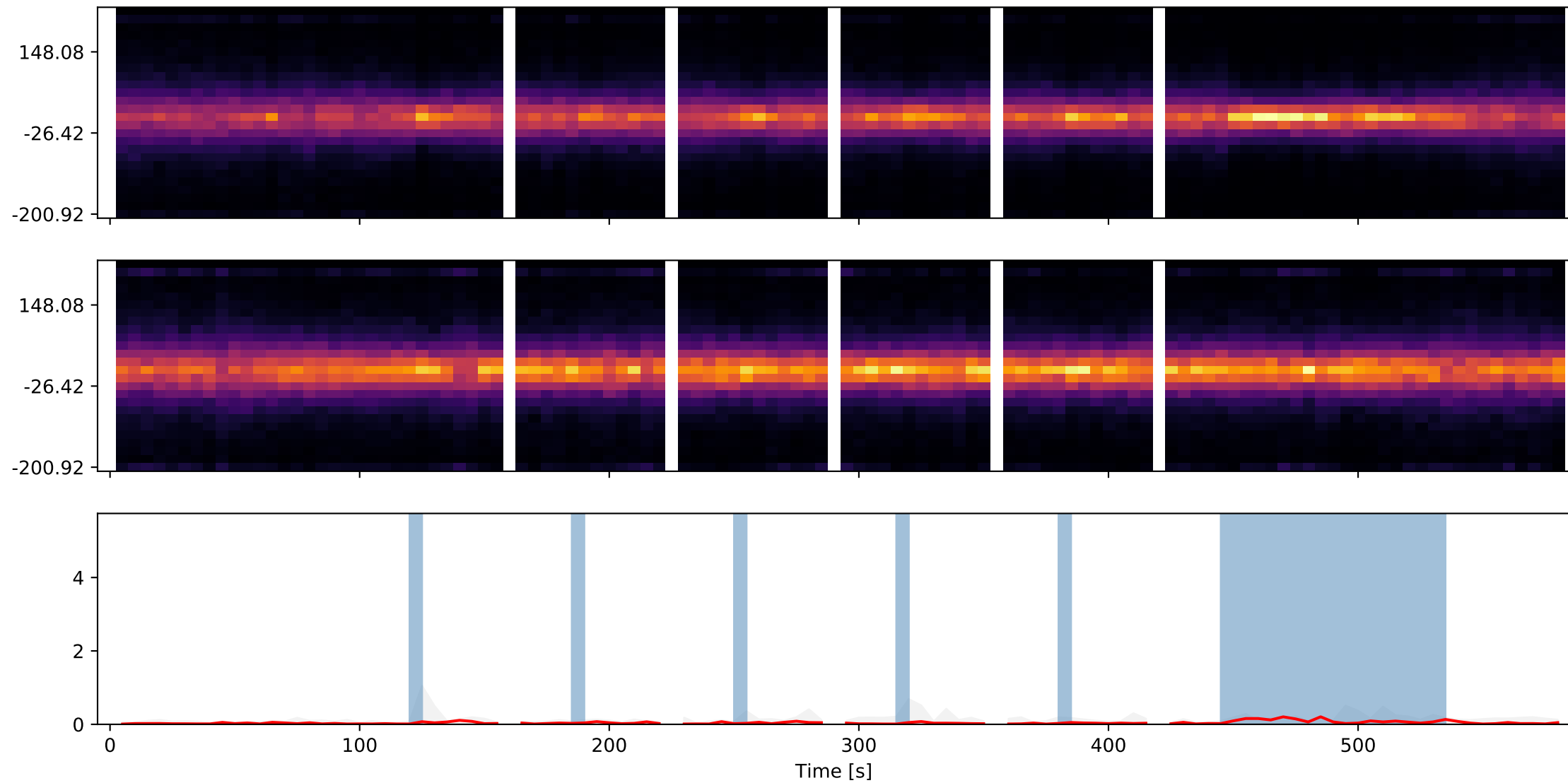
d_relative_to_hips_angular_velocity_tail_tip



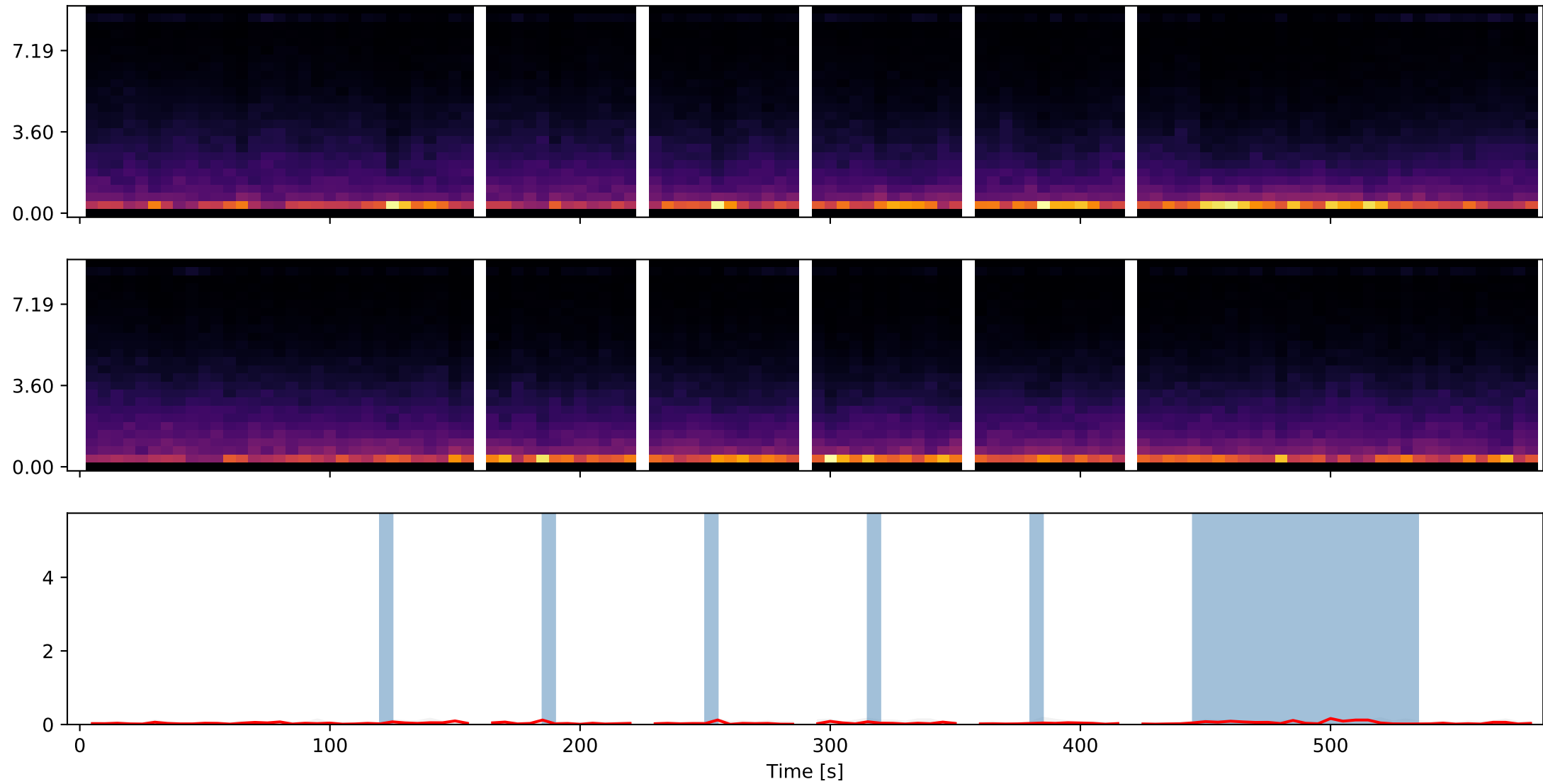
relative_to_body_angular_velocity_head_tip



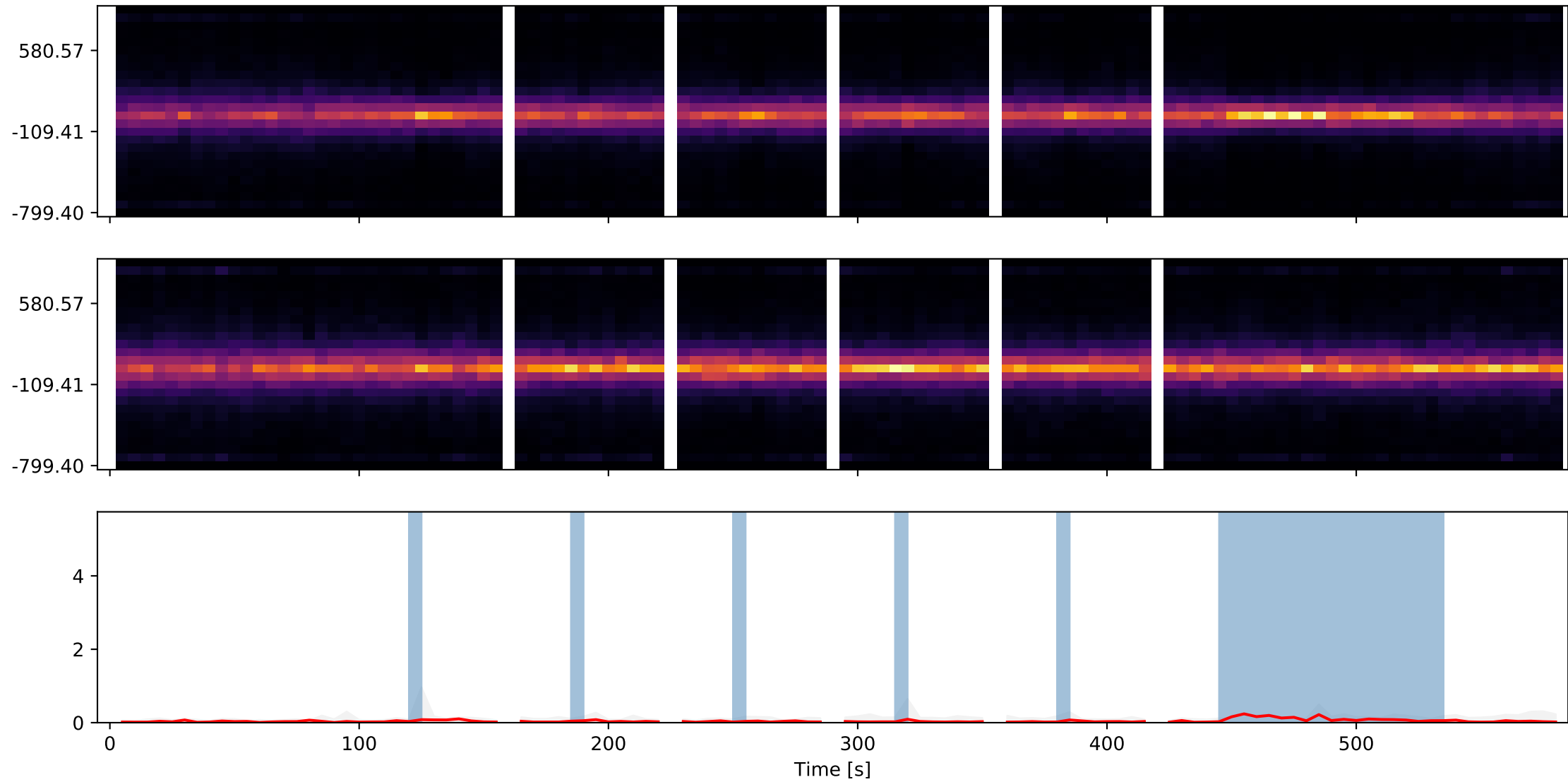
d_relative_to_hips_radial_velocity_tail_tip



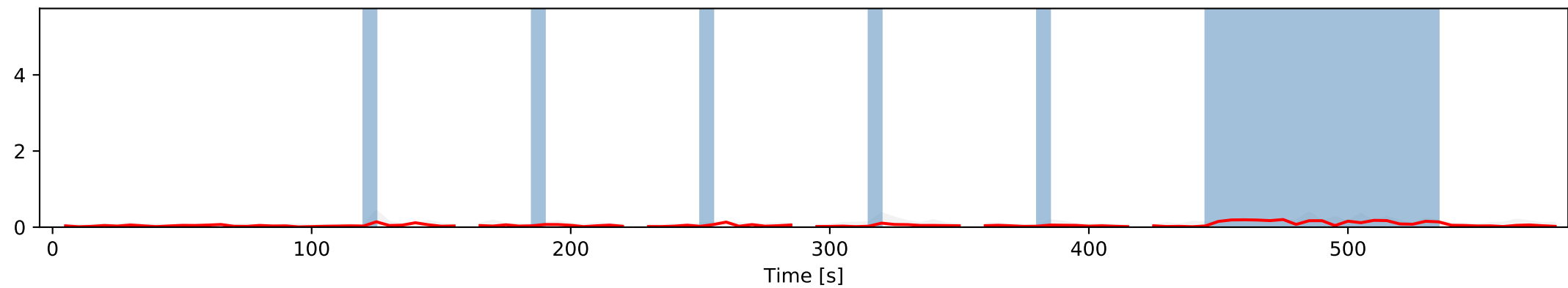
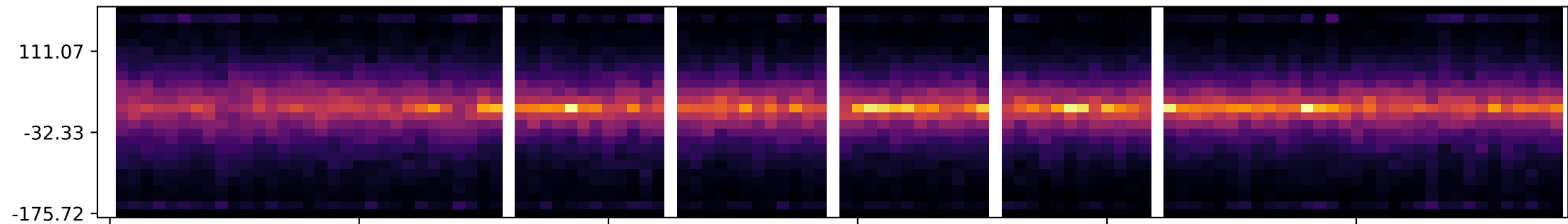
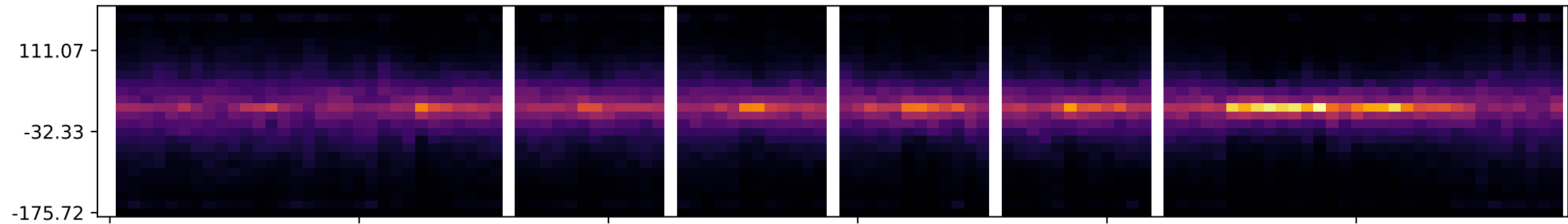
d_angular_velocity_tail_tip



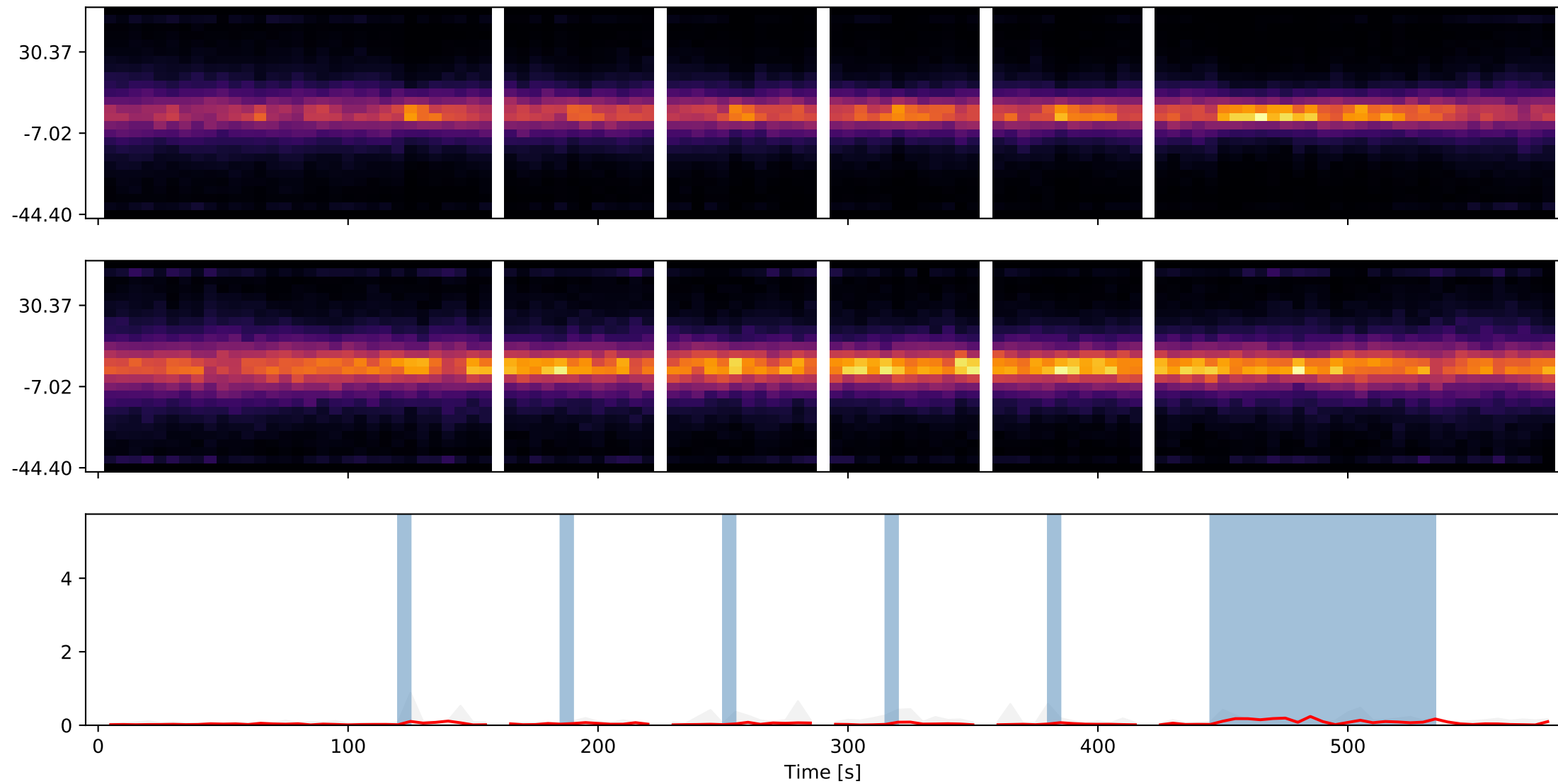
d_speed_neck



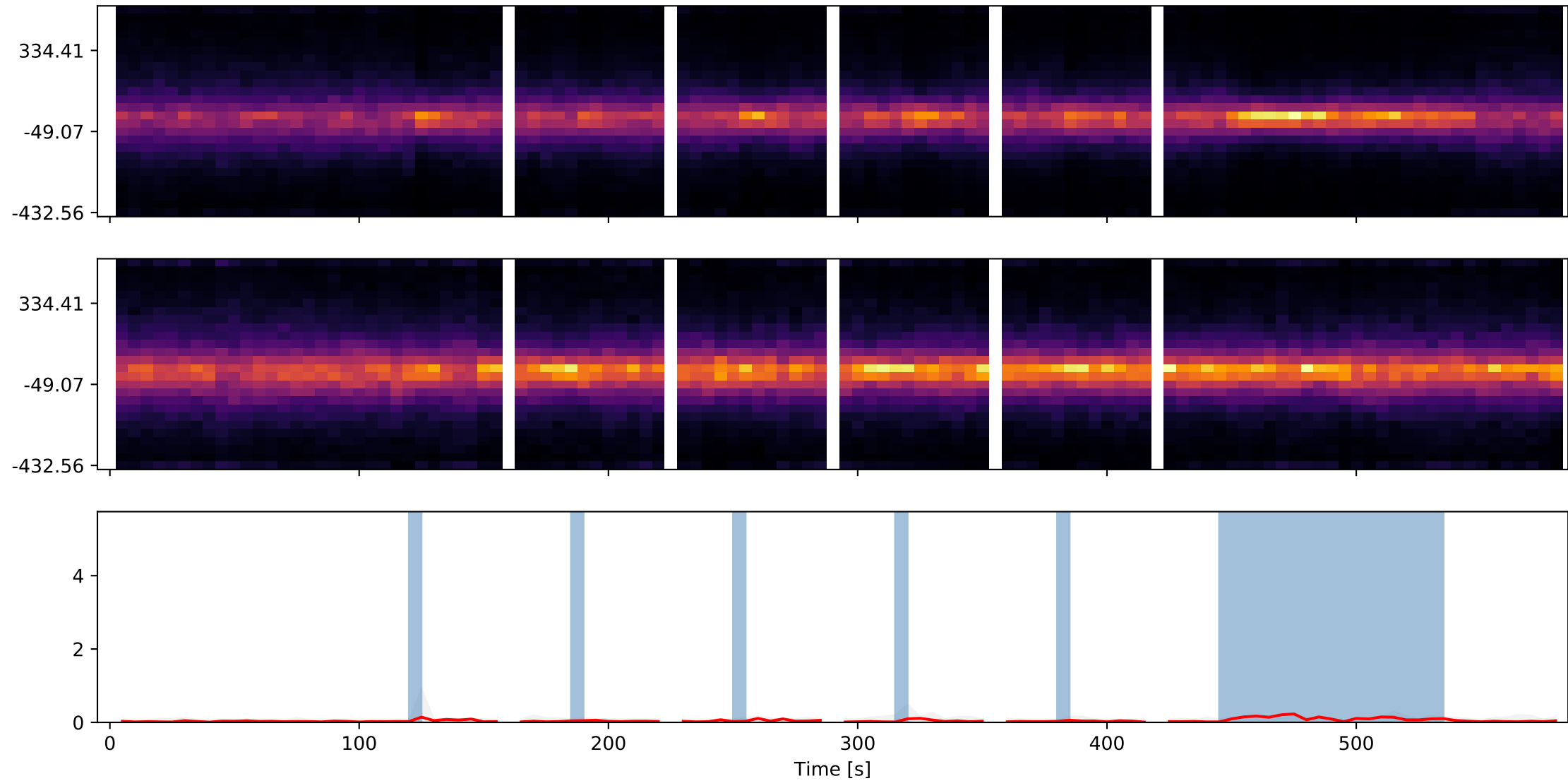
d_major_axis



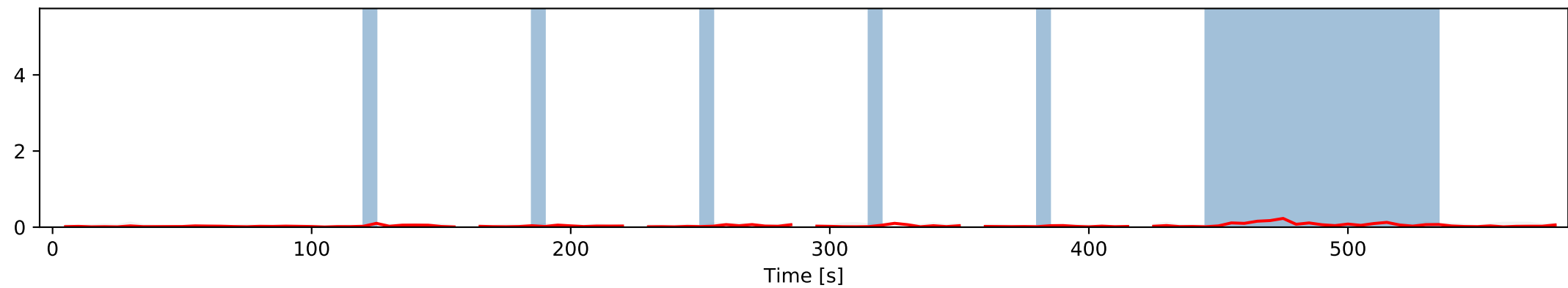
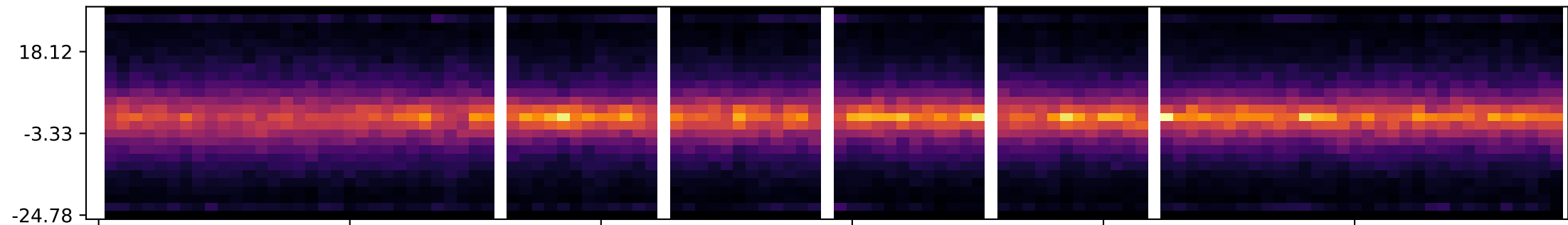
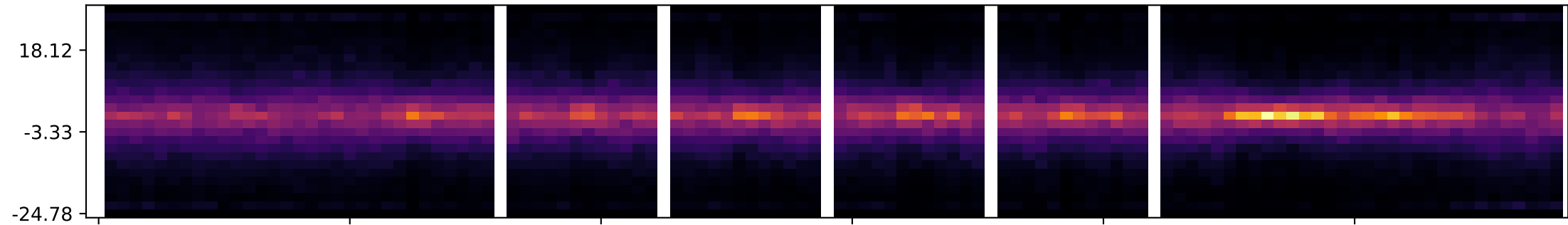
relative_to_hips_radial_velocity_tail_tip



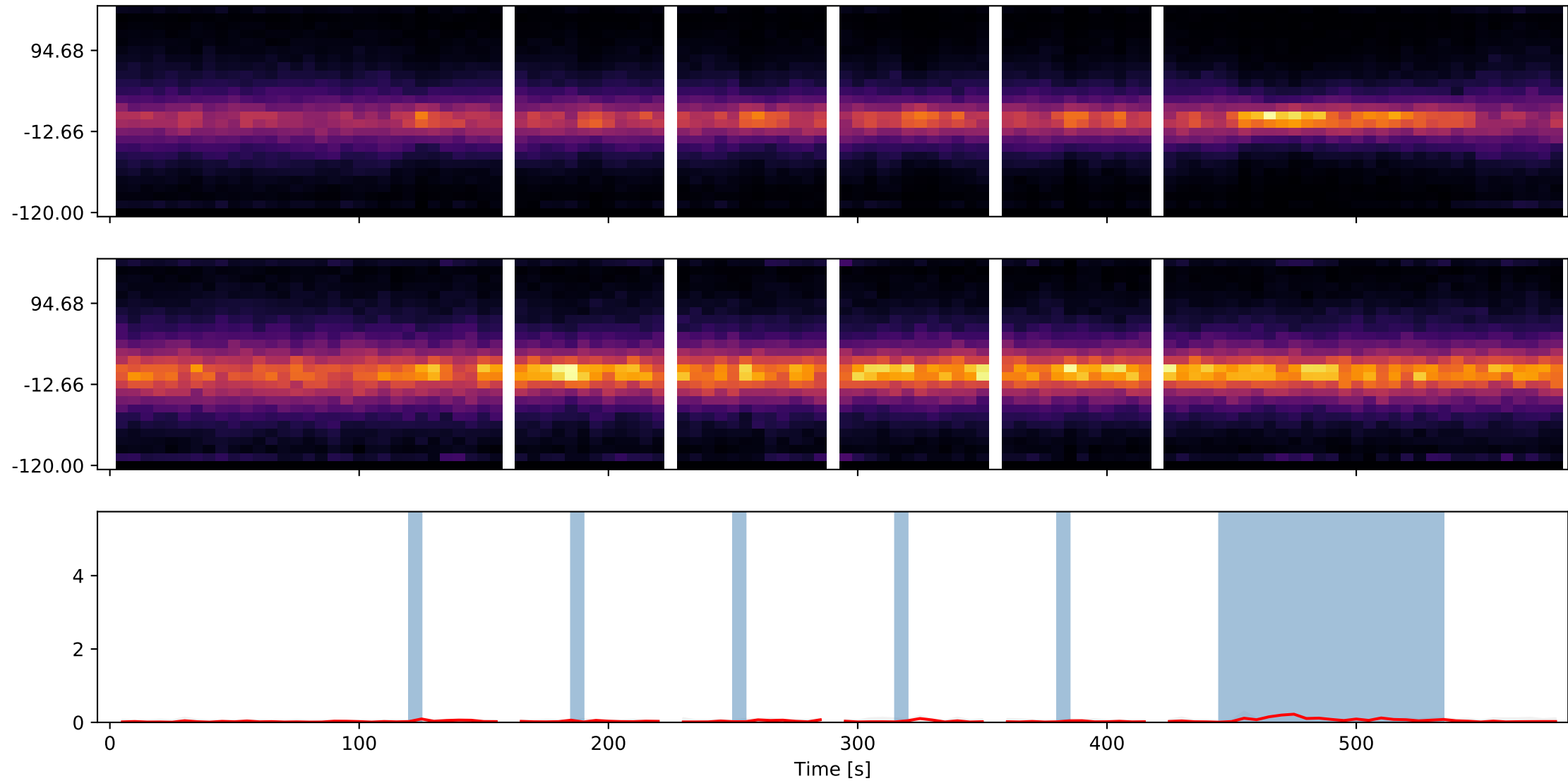
d_relative_to_body_radial_velocity_head_tip



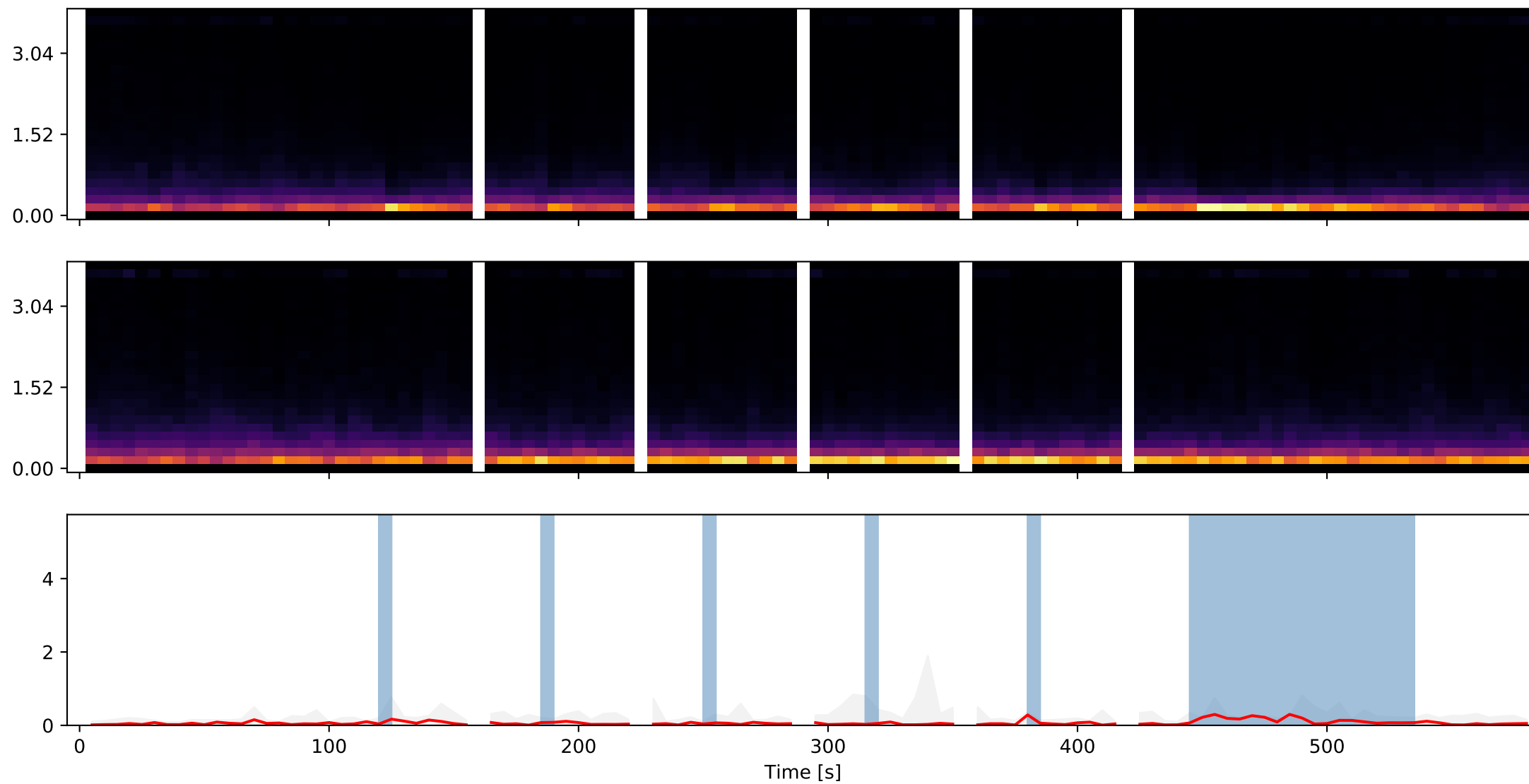
relative_to_head_base_radial_velocity_head_tip



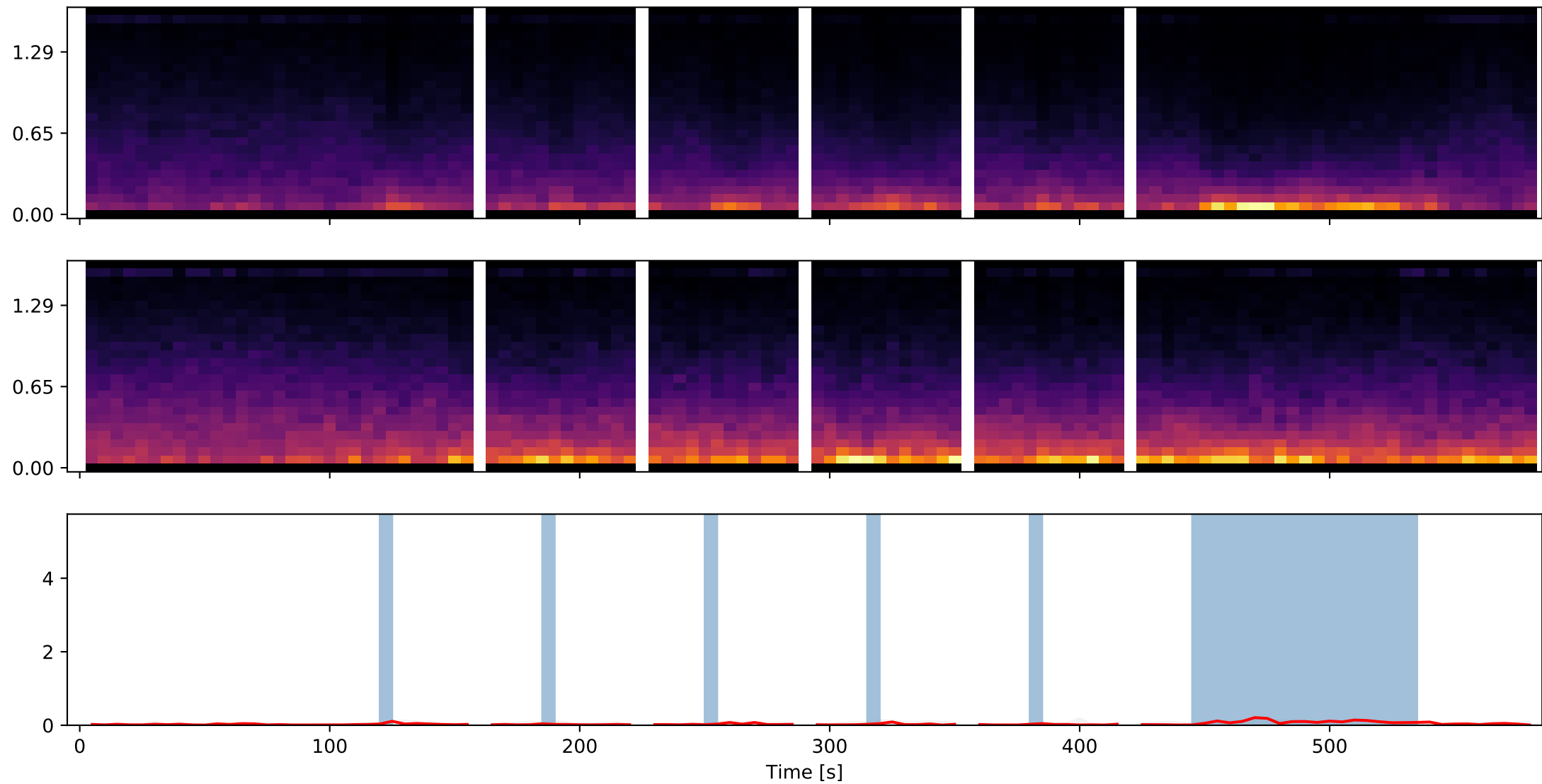
d_relative_to_head_base_radial_velocity_head_tip



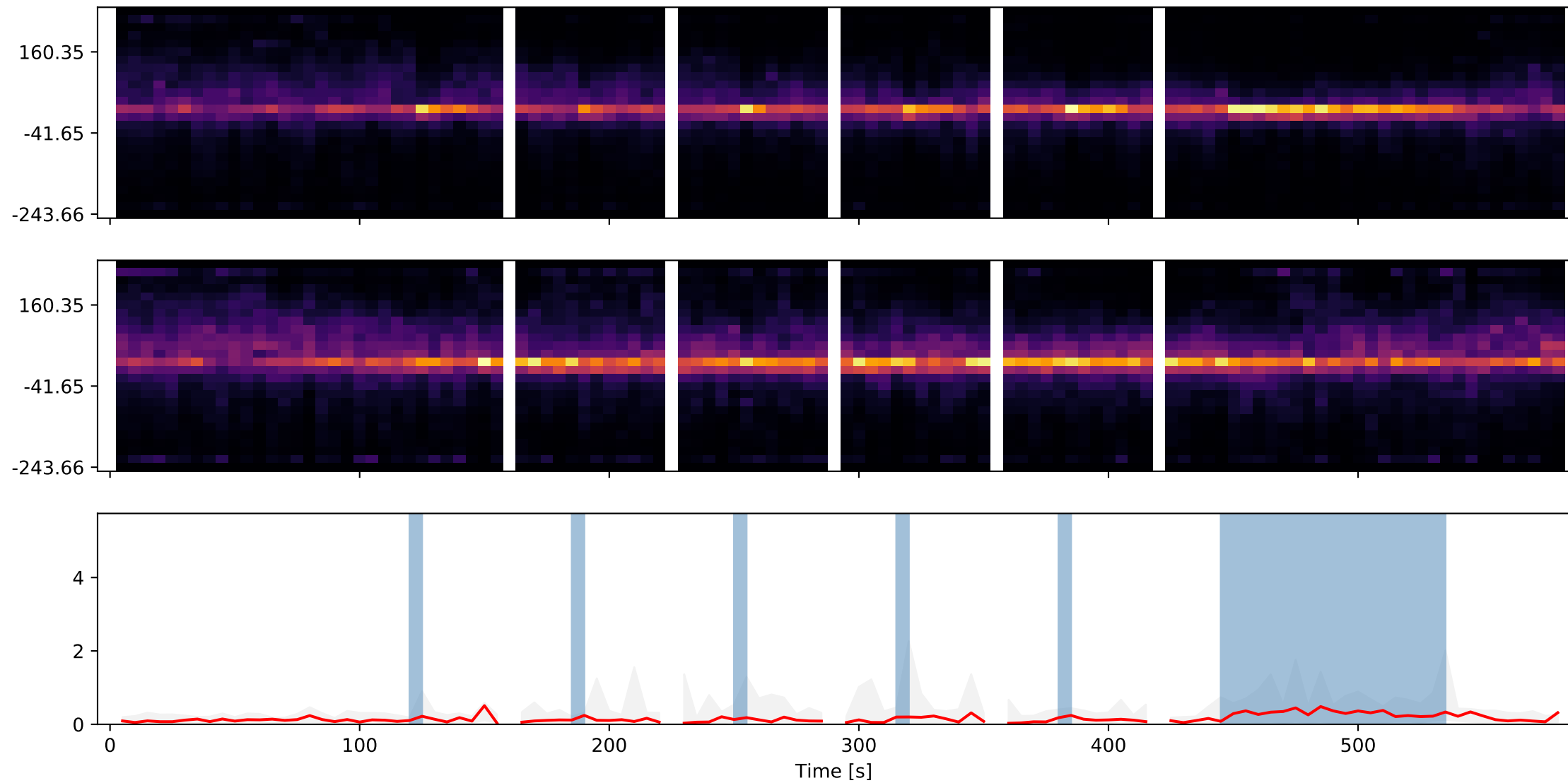
d_angular_velocity_midbody



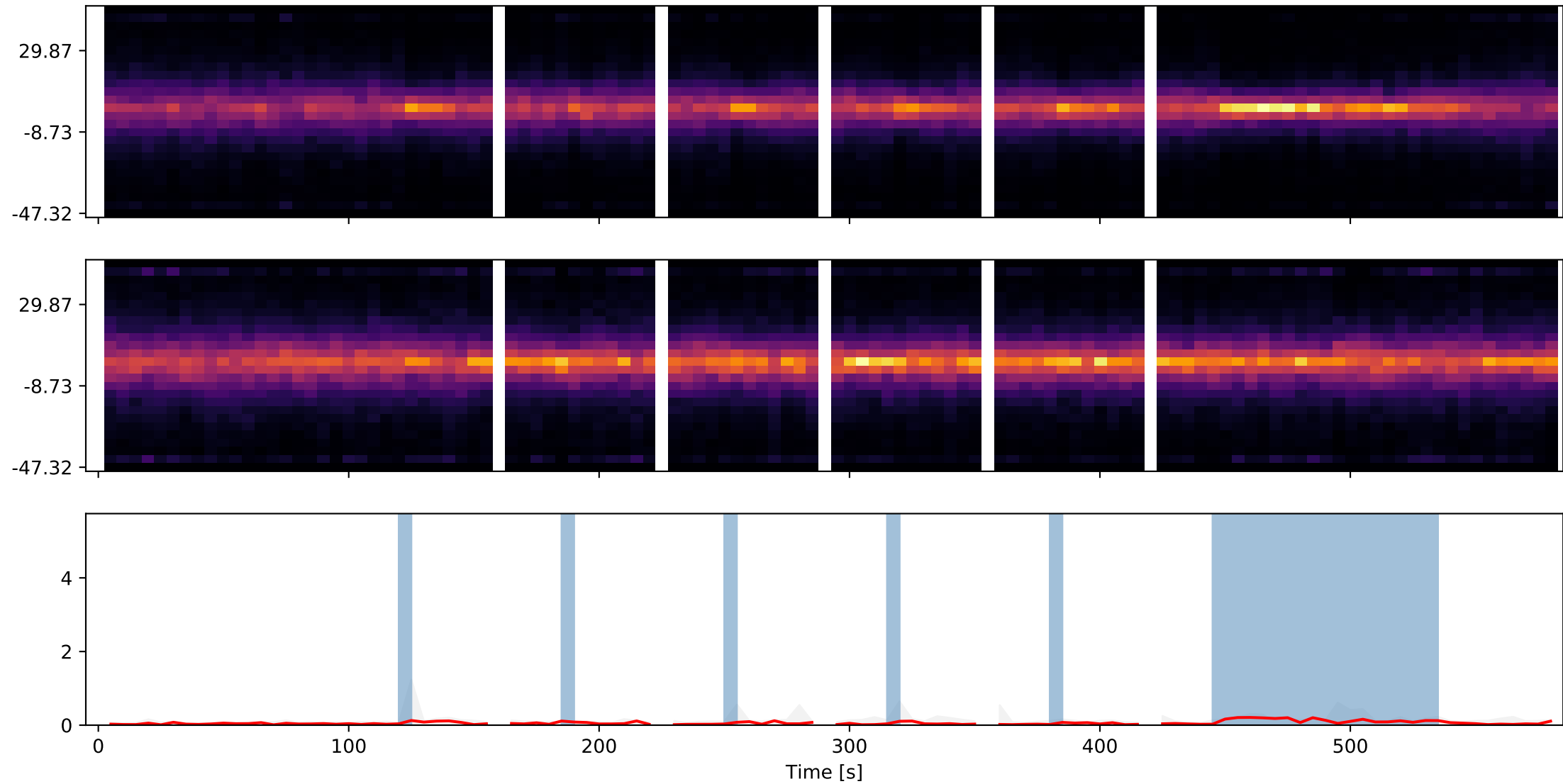
relative_to_head_base_angular_velocity_head_tip



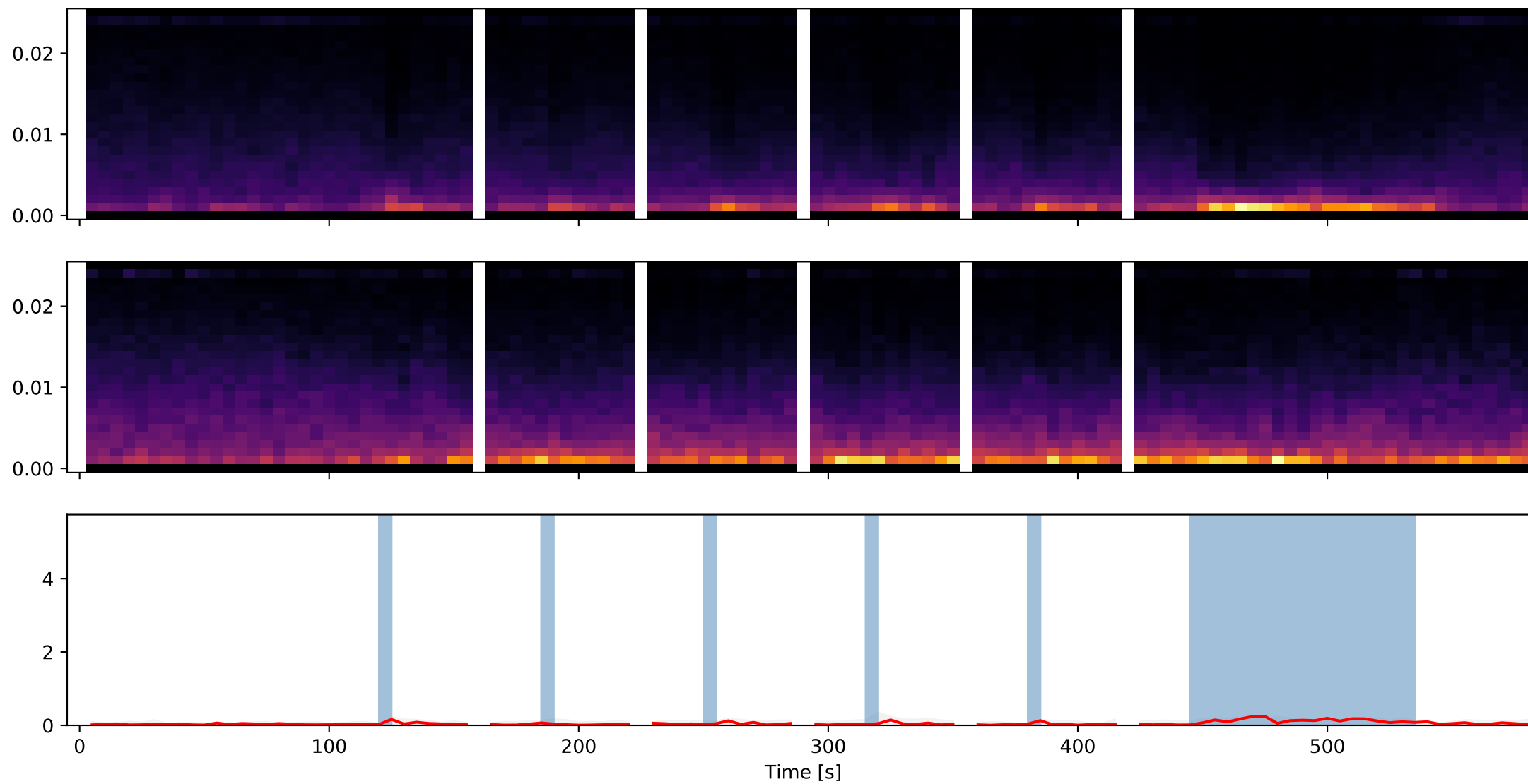
speed_tail_tip



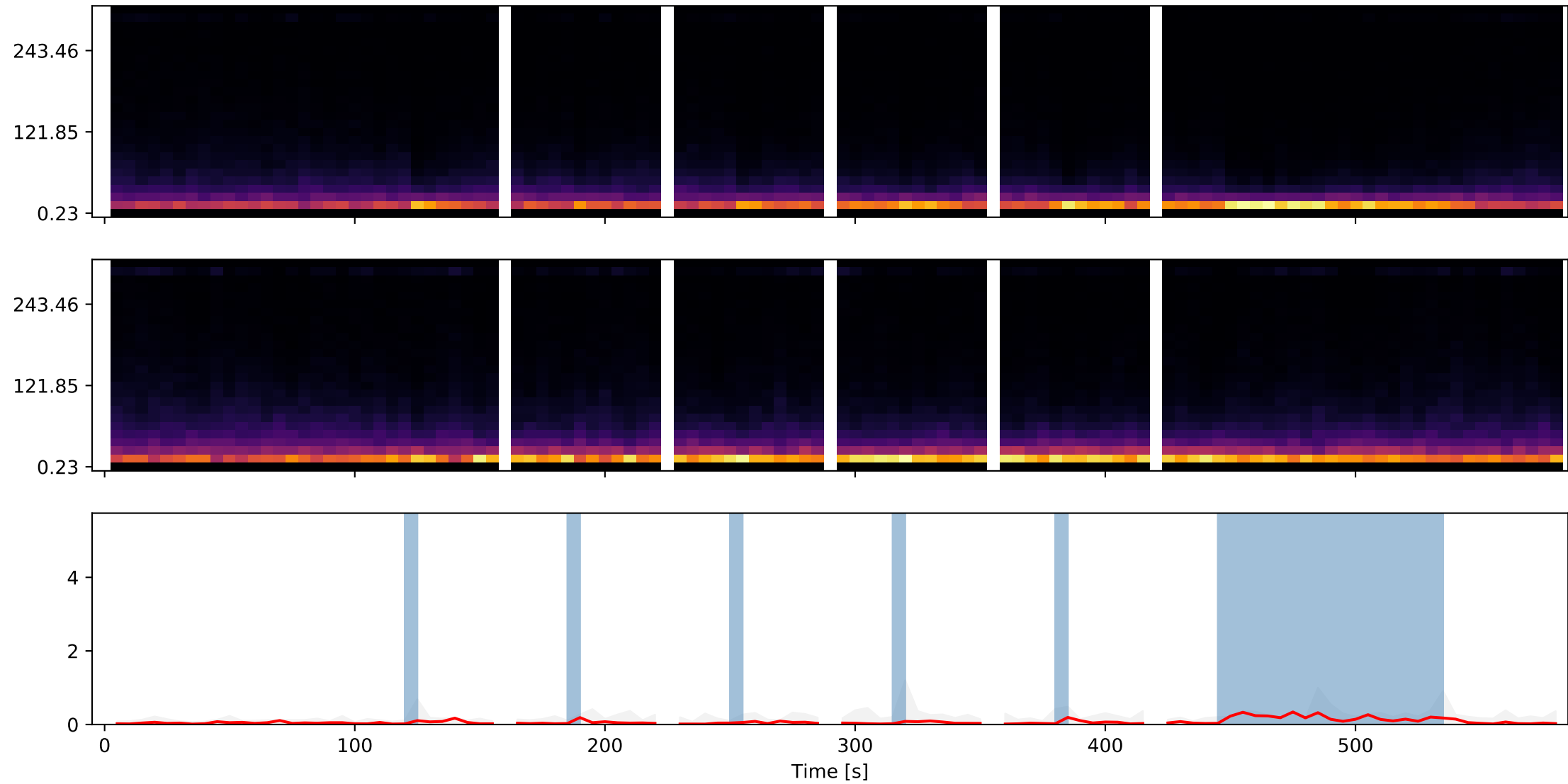
relative_to_body_radial_velocity_neck



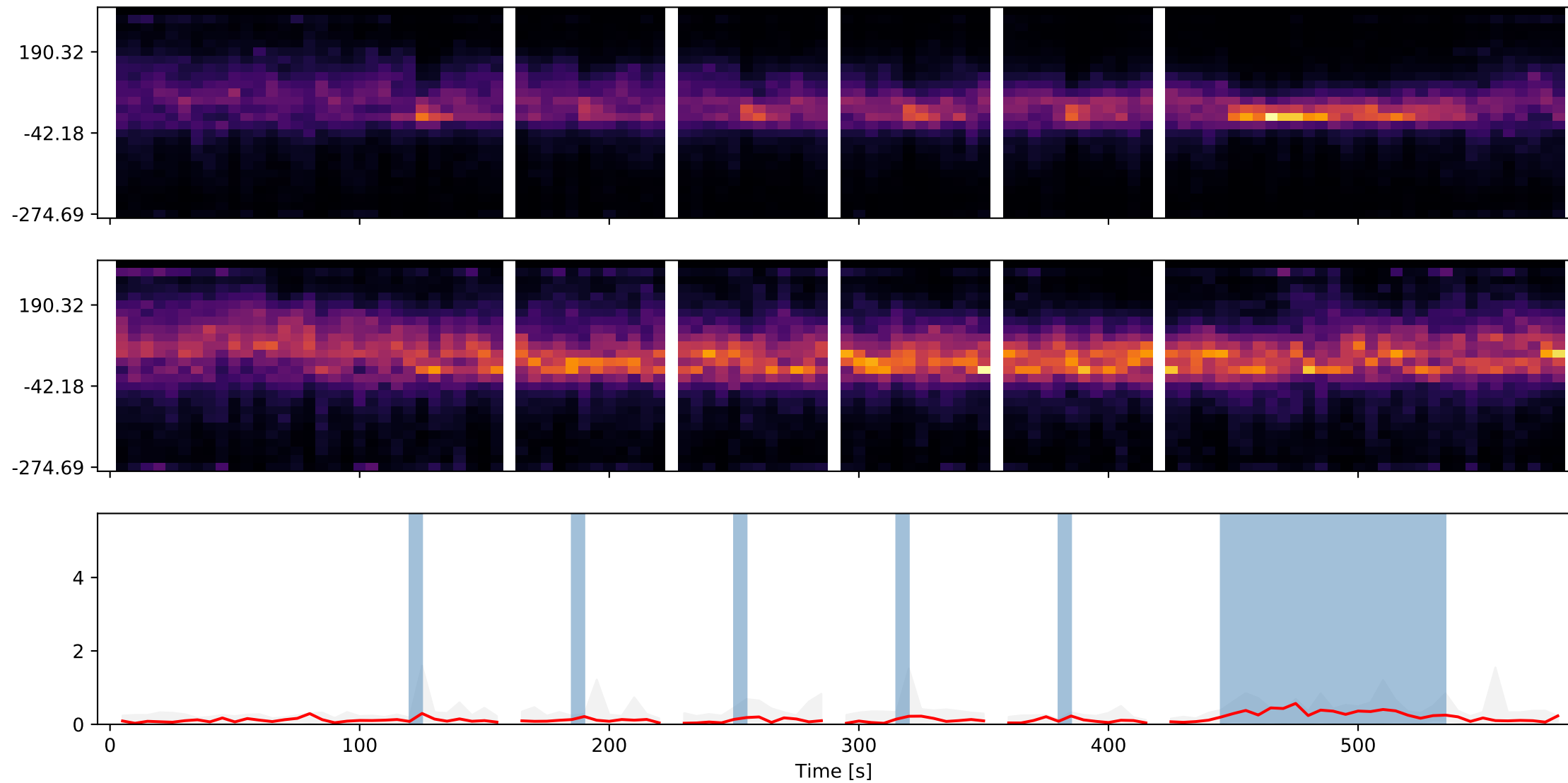
d_curvature_mean_head



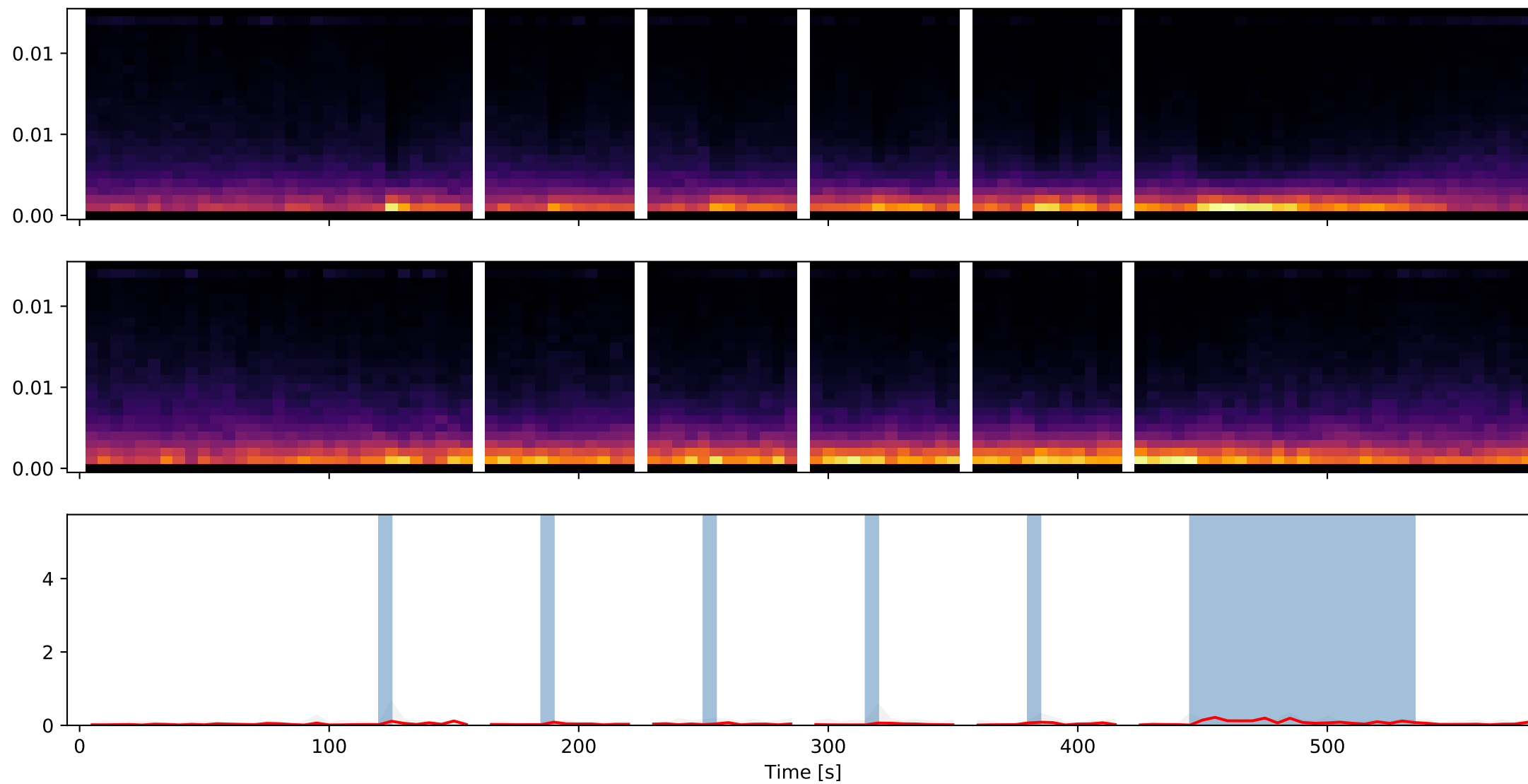
d_relative_to_body_speed_midbody



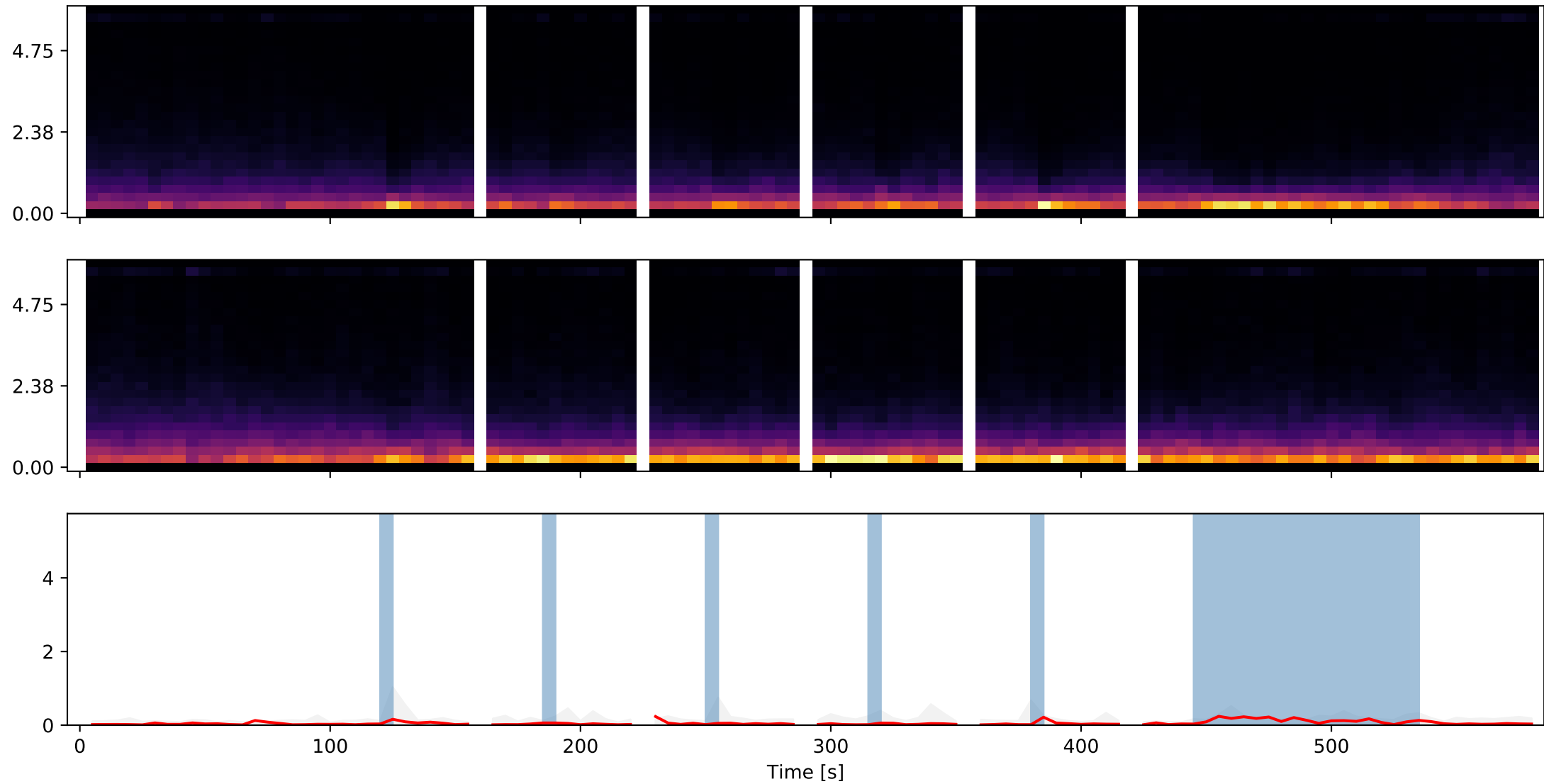
speed_head_tip



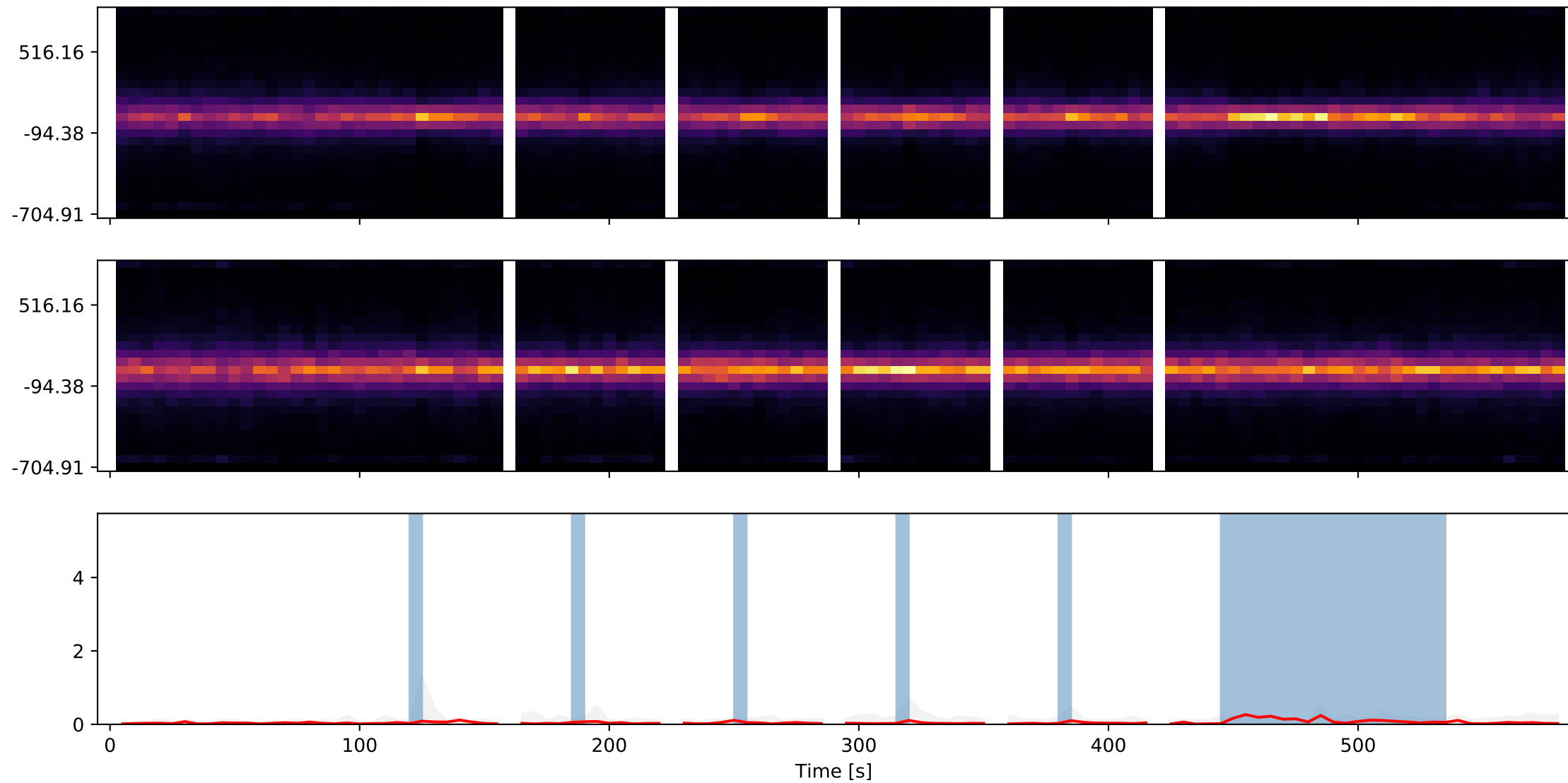
d_curvature_midbody



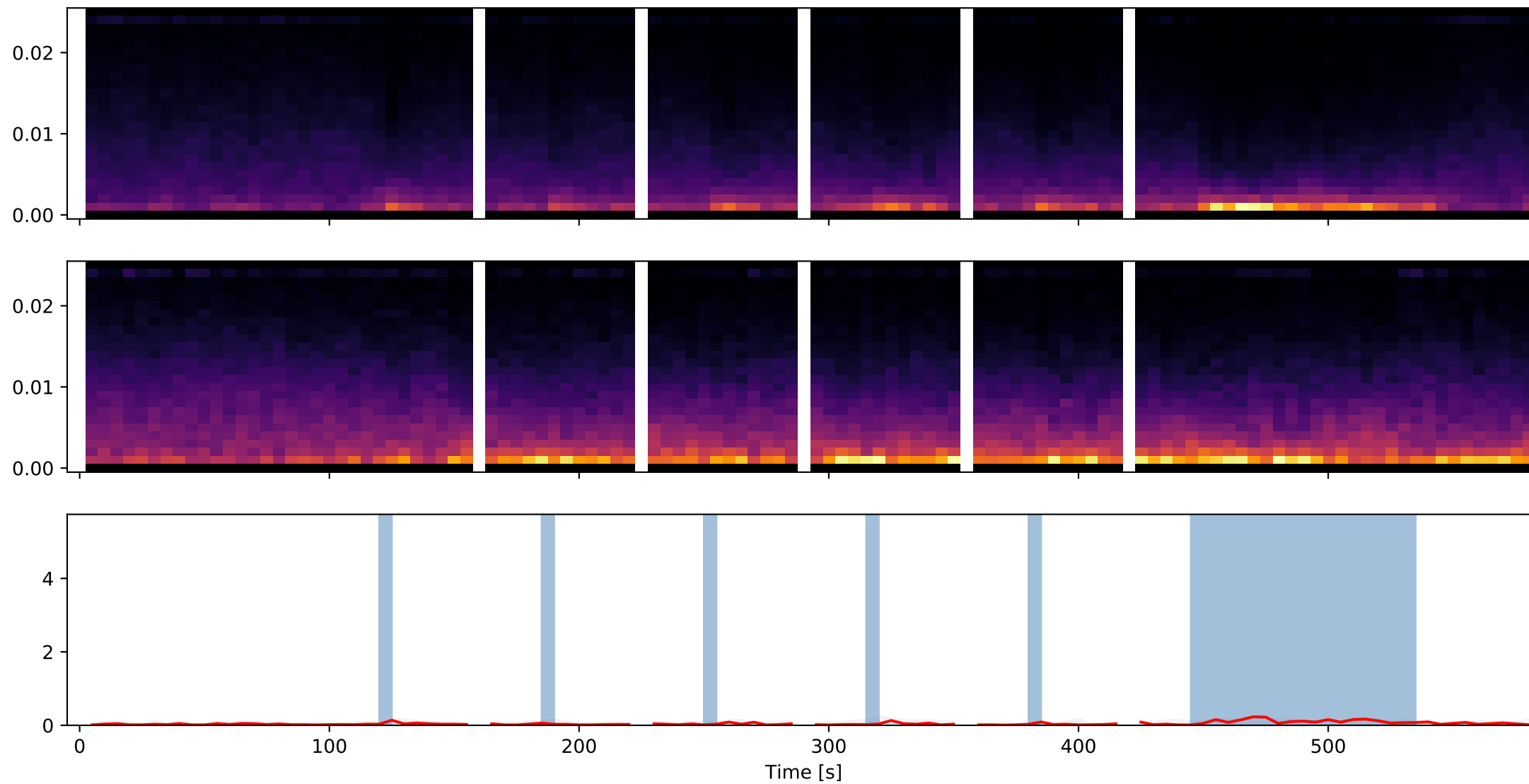
d_angular_velocity_neck



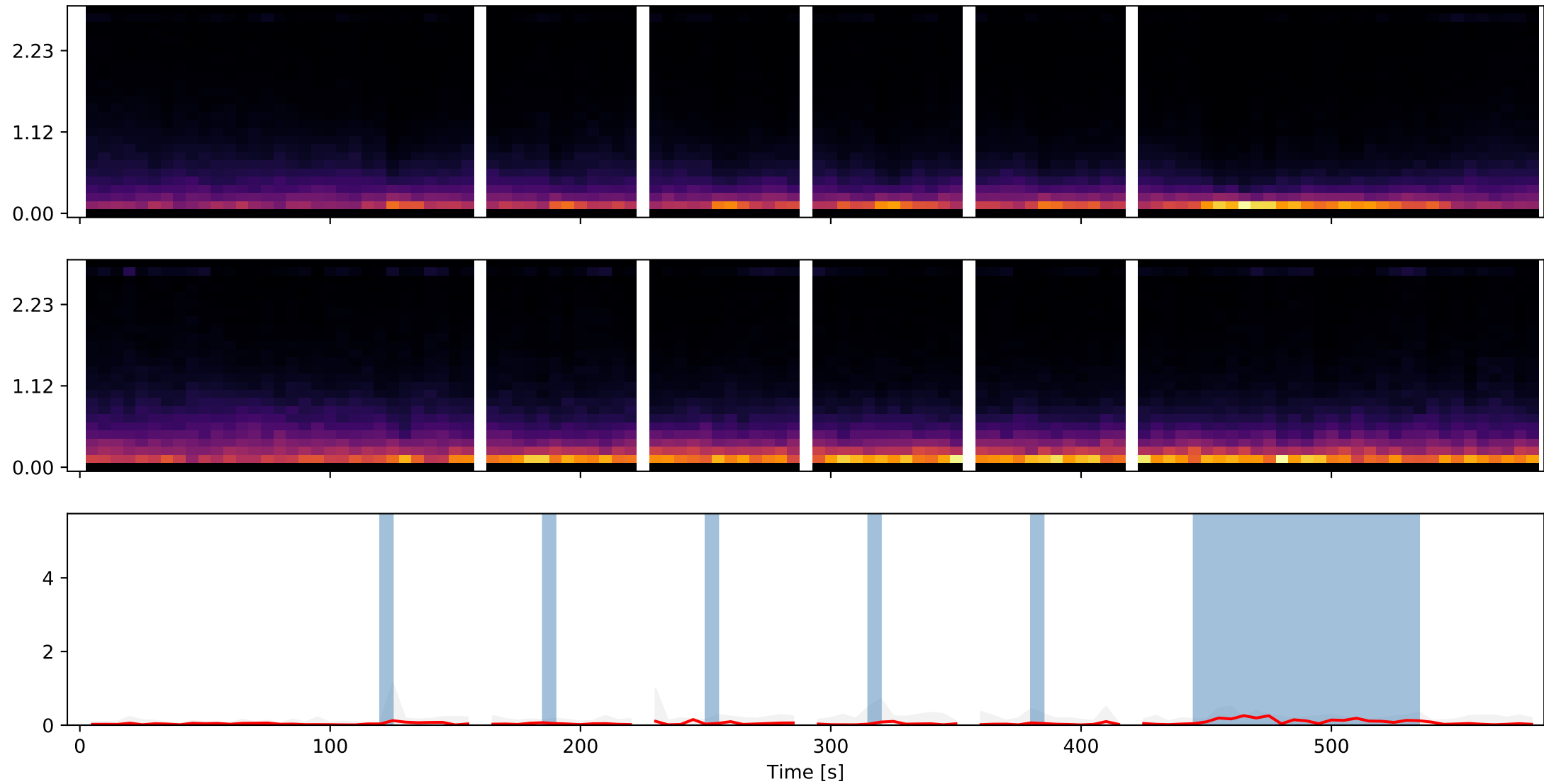
d_speed_midbody



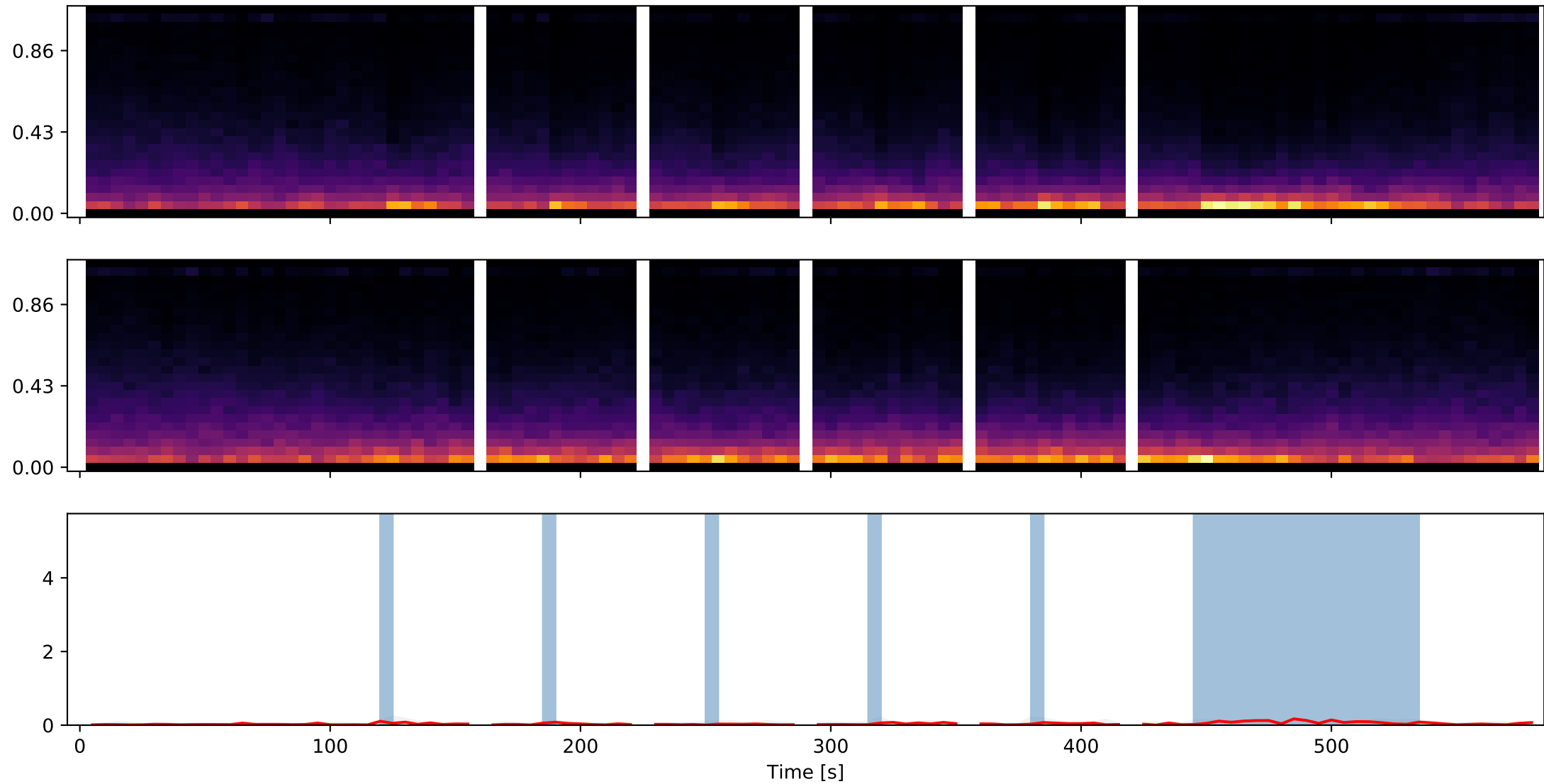
d_curvature_head



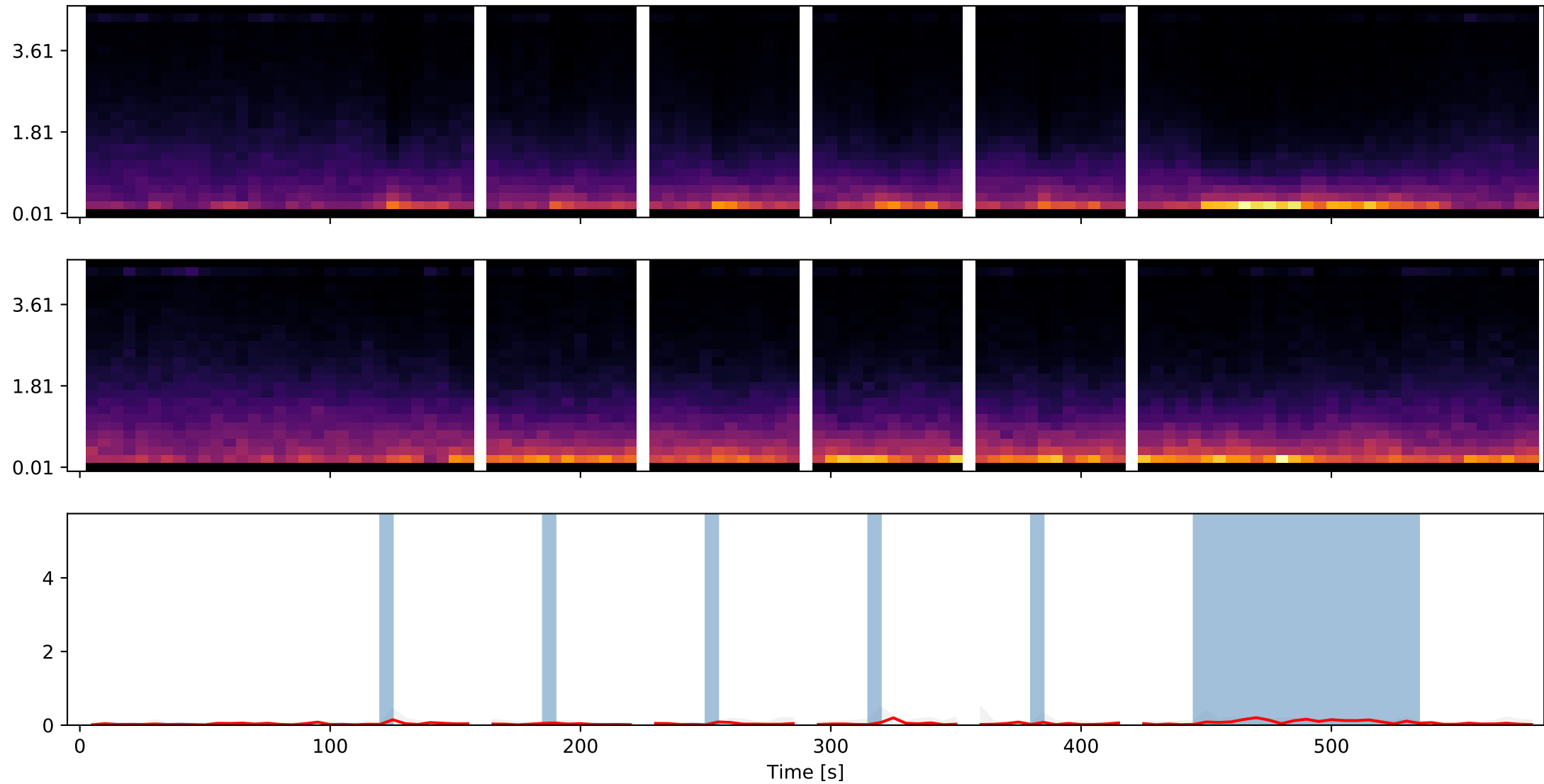
d_relative_to_body_angular_velocity_head_tip



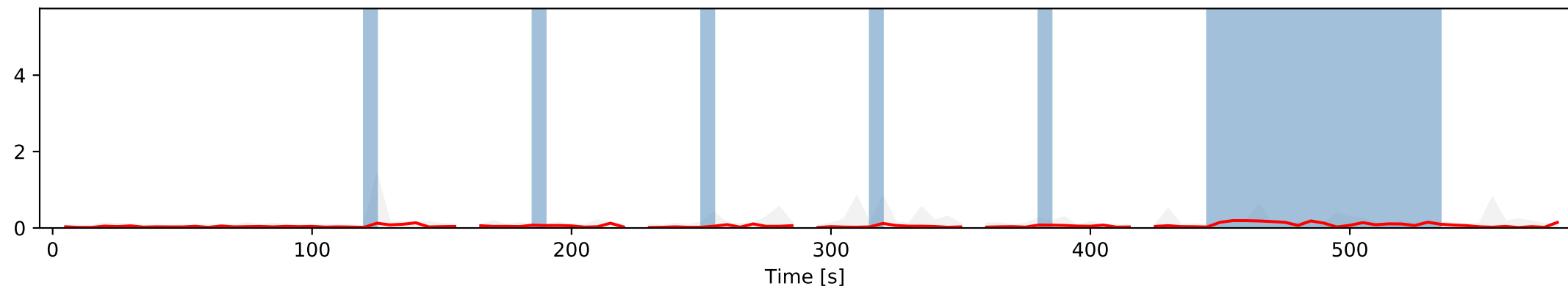
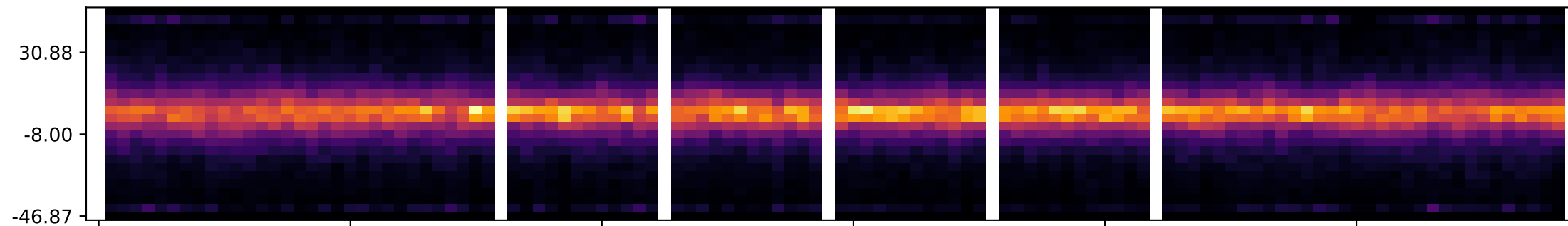
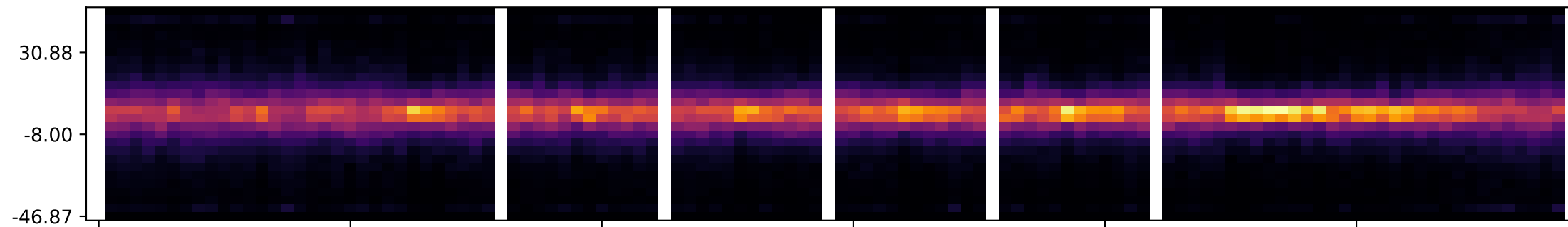
relative_to_tail_base_angular_velocity_tail_tip



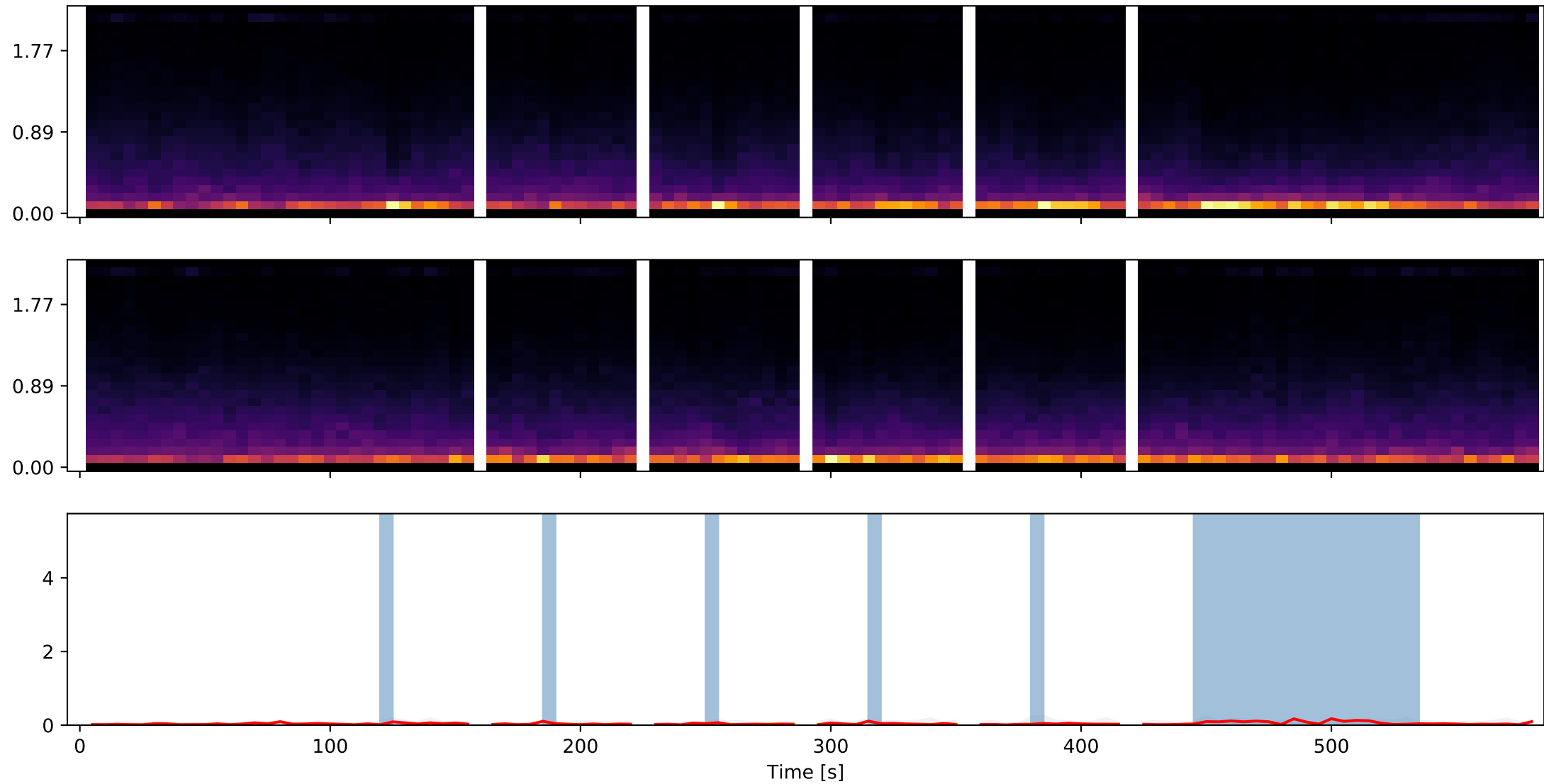
d_eigen_projection_4



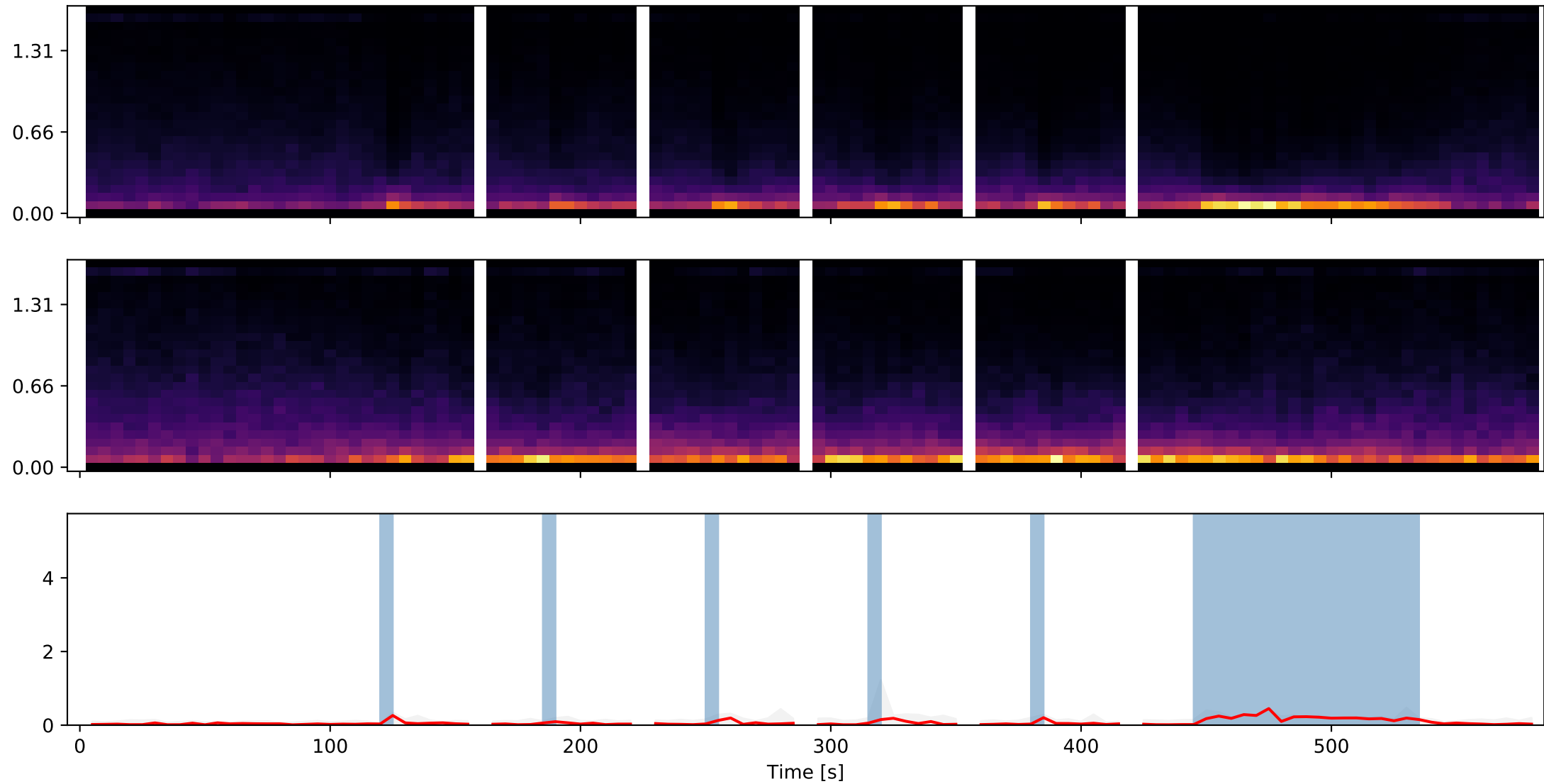
relative_to_body_radial_velocity_hips



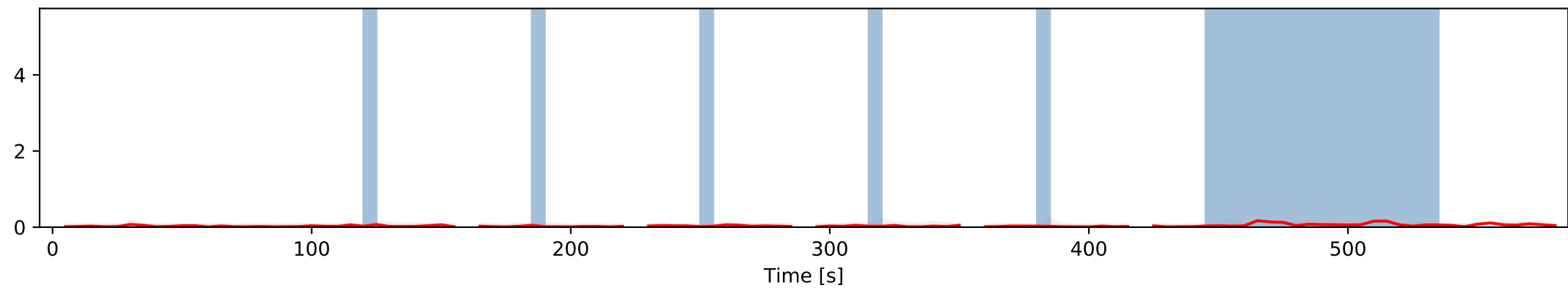
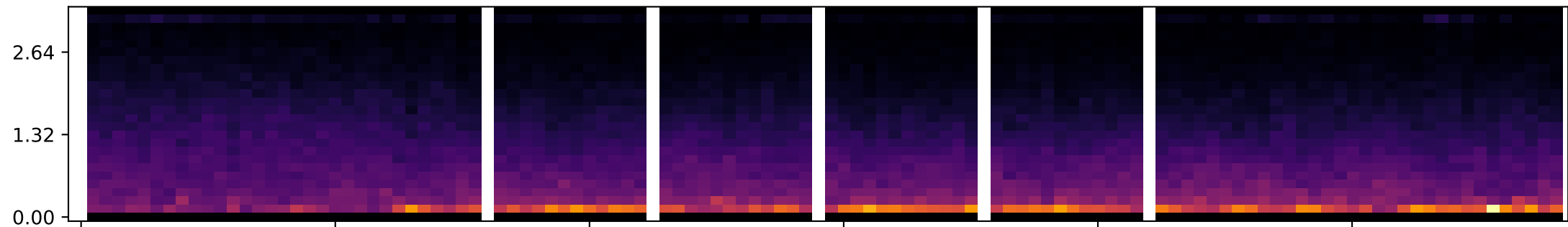
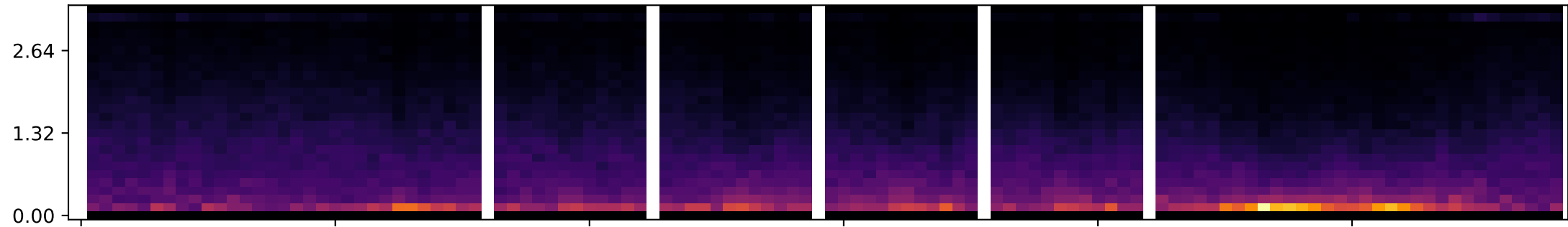
angular_velocity_tail_tip



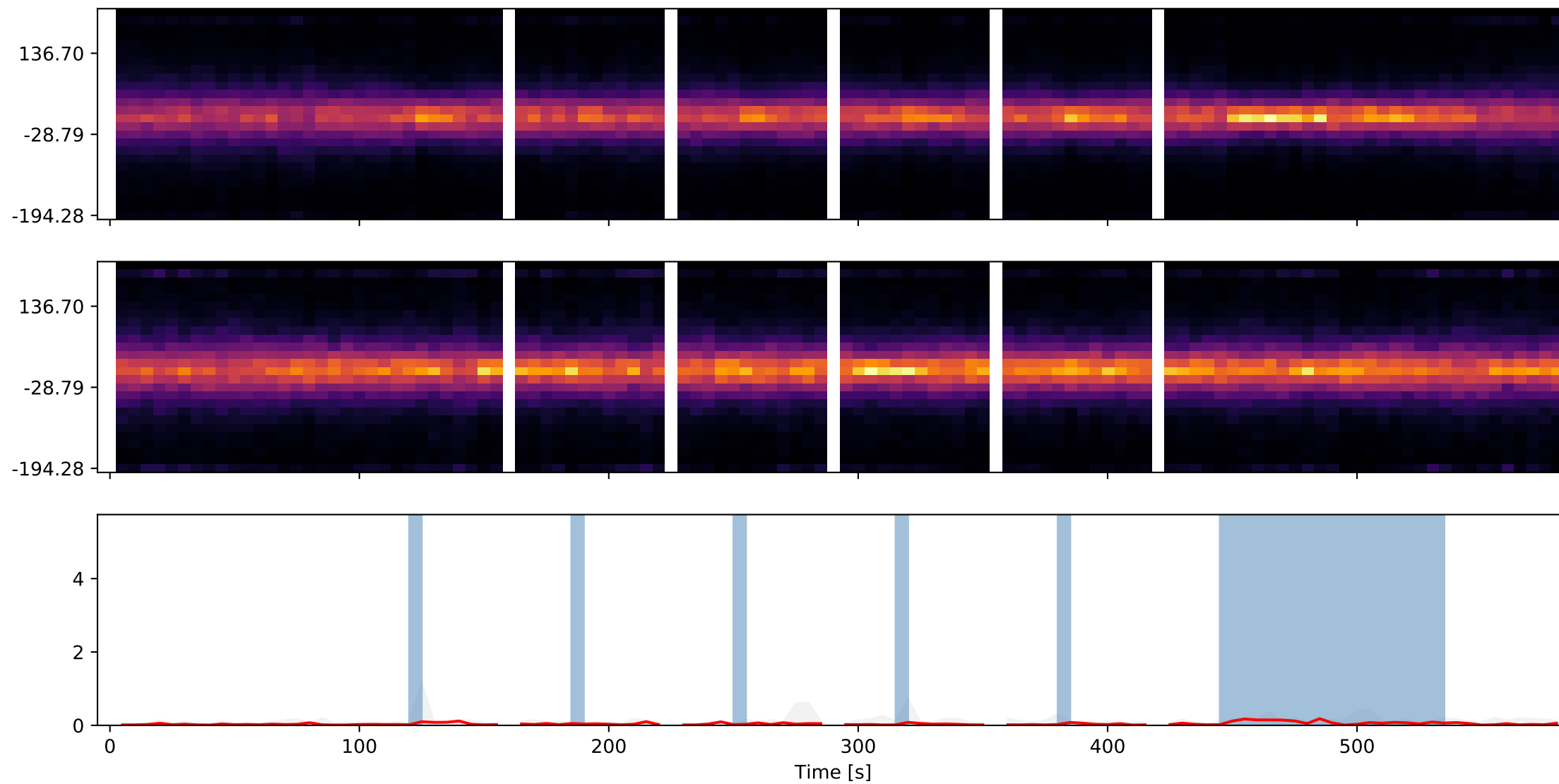
relative_to_neck_angular_velocity_head_tip



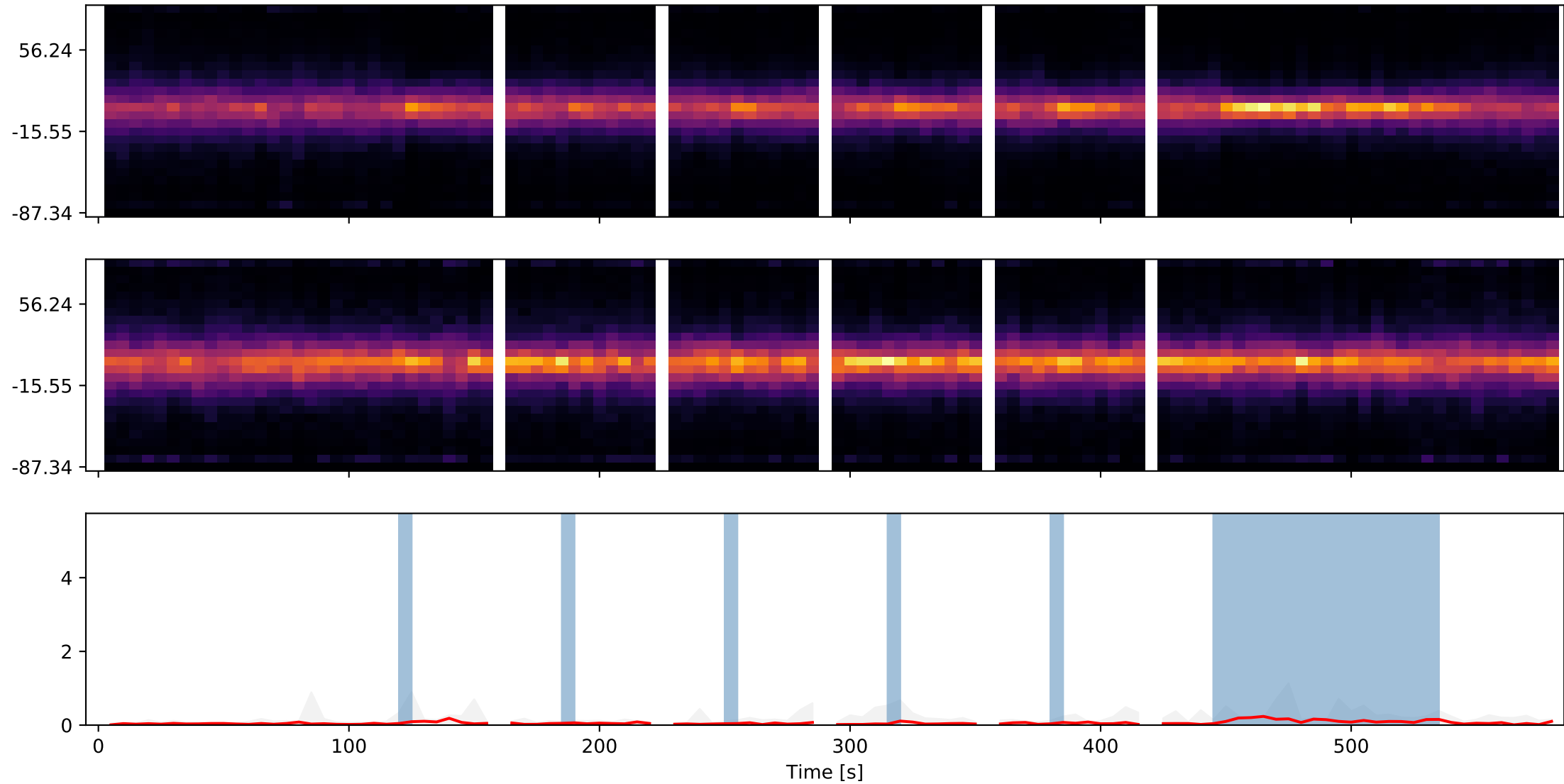
angular_velocity_head_tip



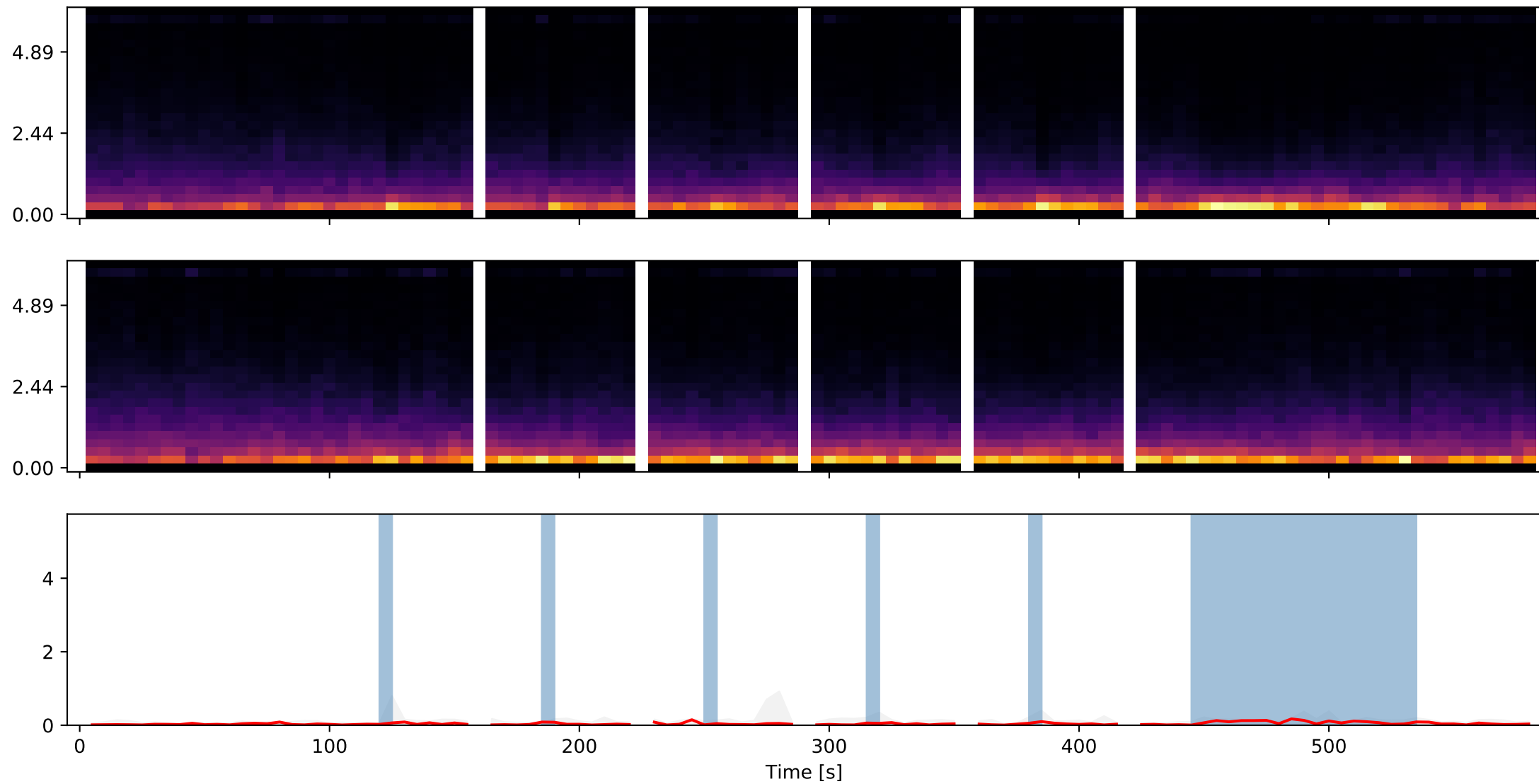
d_relative_to_body_radial_velocity_hips



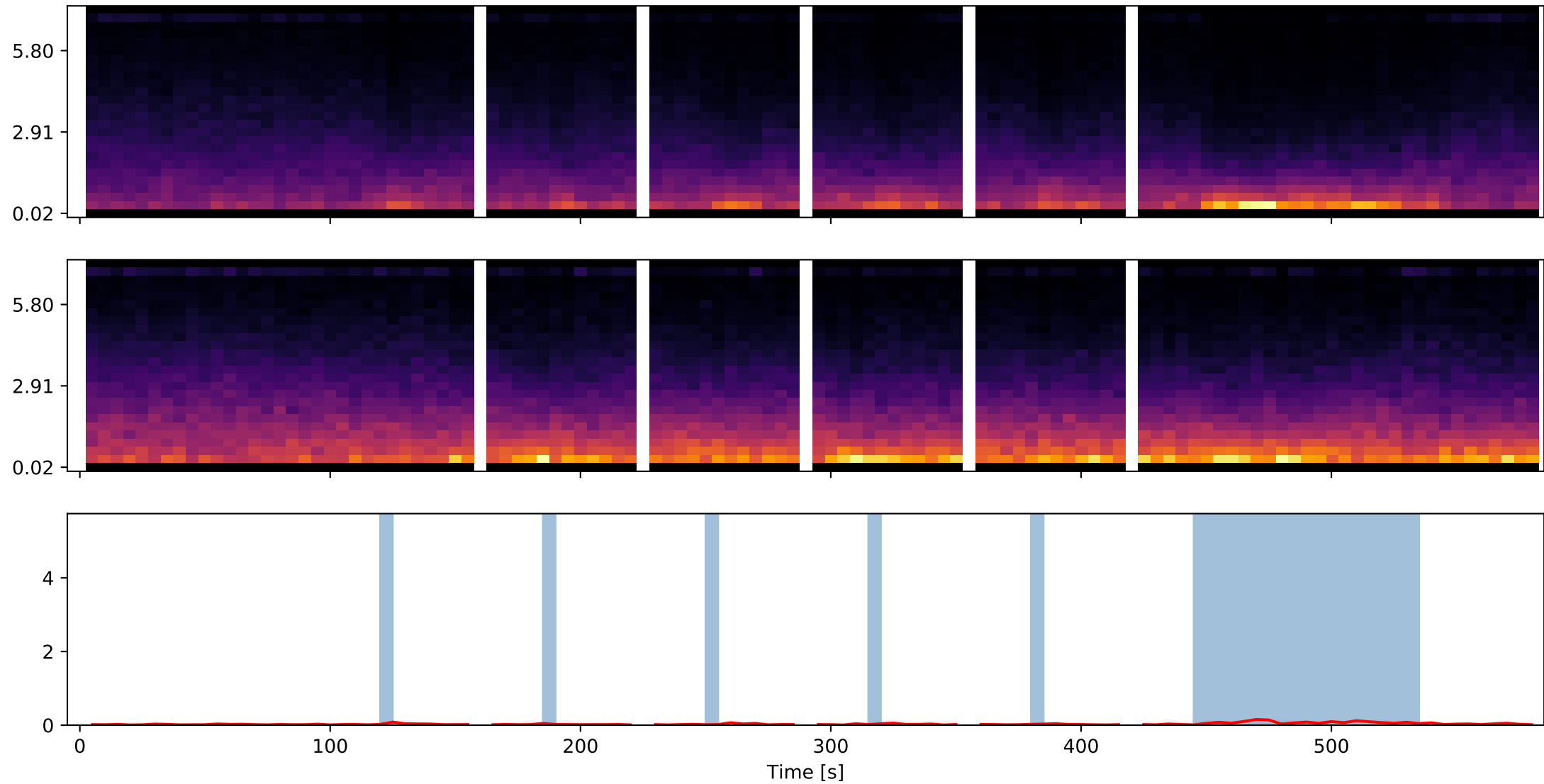
relative_to_body_radial_velocity_tail_tip



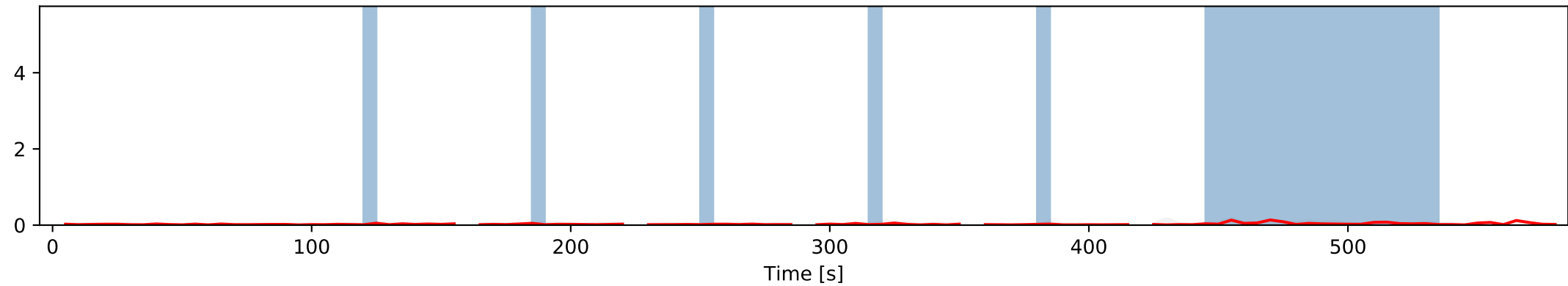
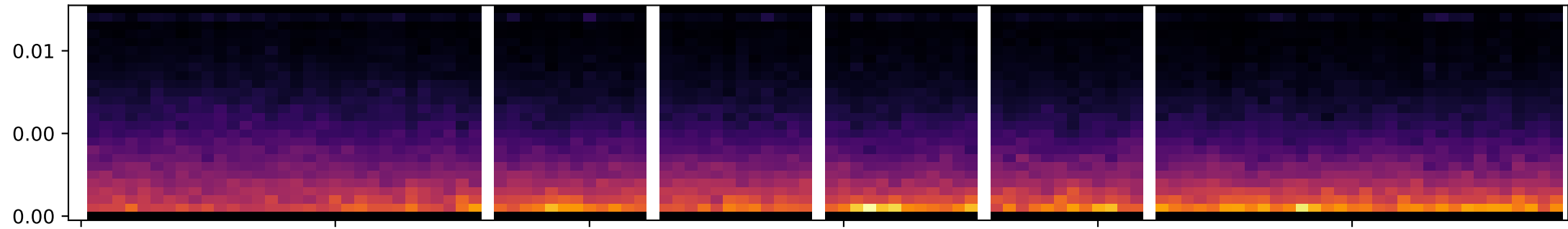
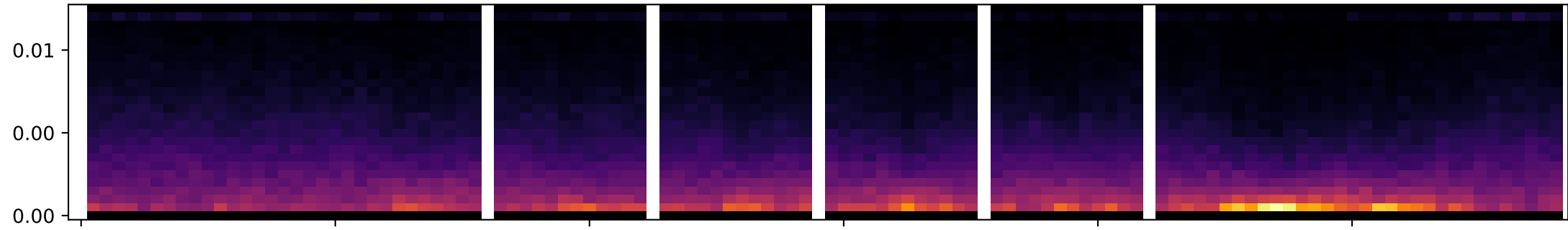
d_angular_velocity_tail_base



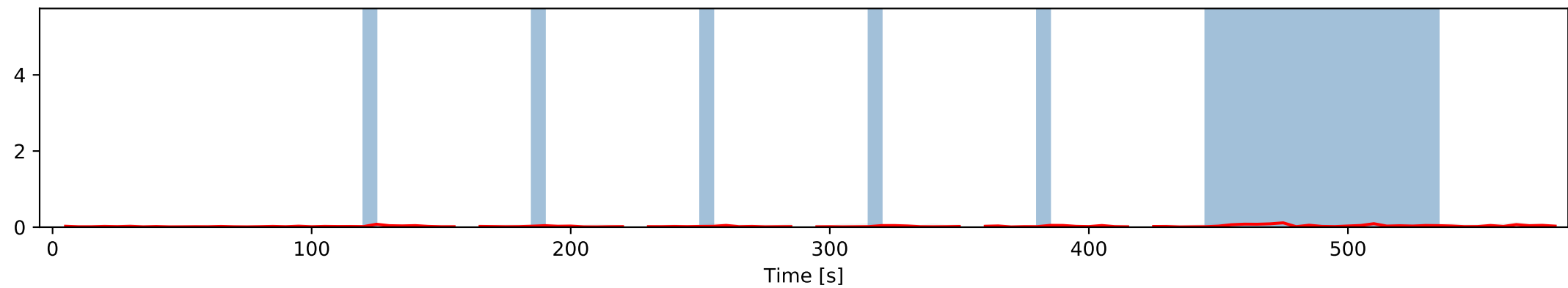
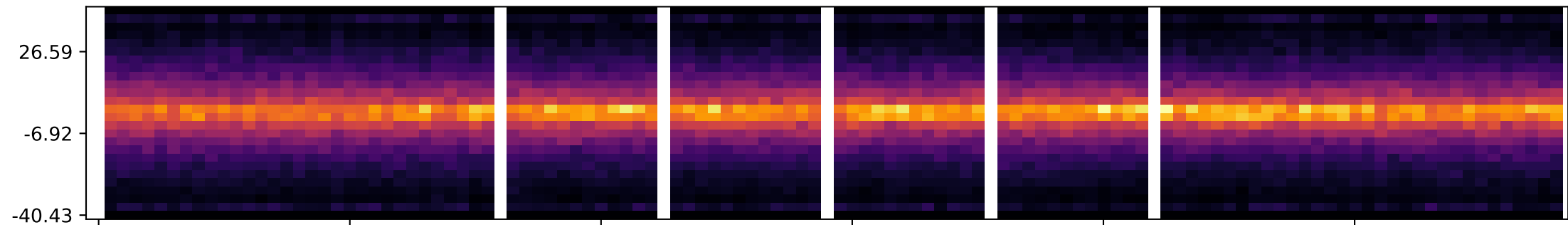
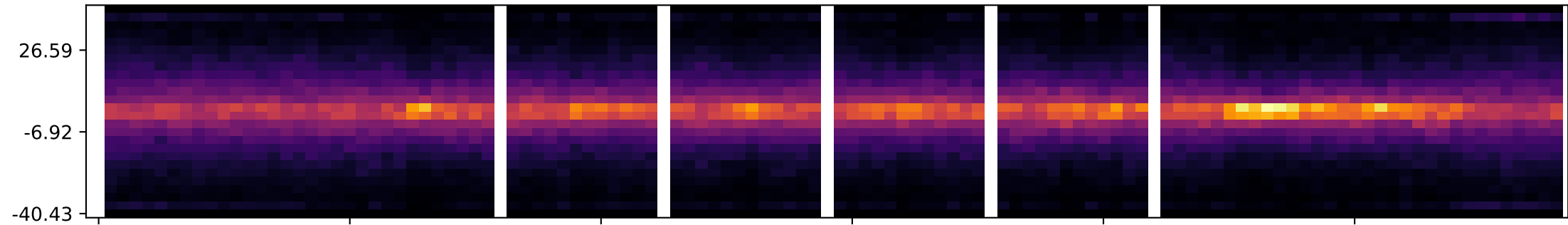
d_relative_to_head_base_angular_velocity_head_tip



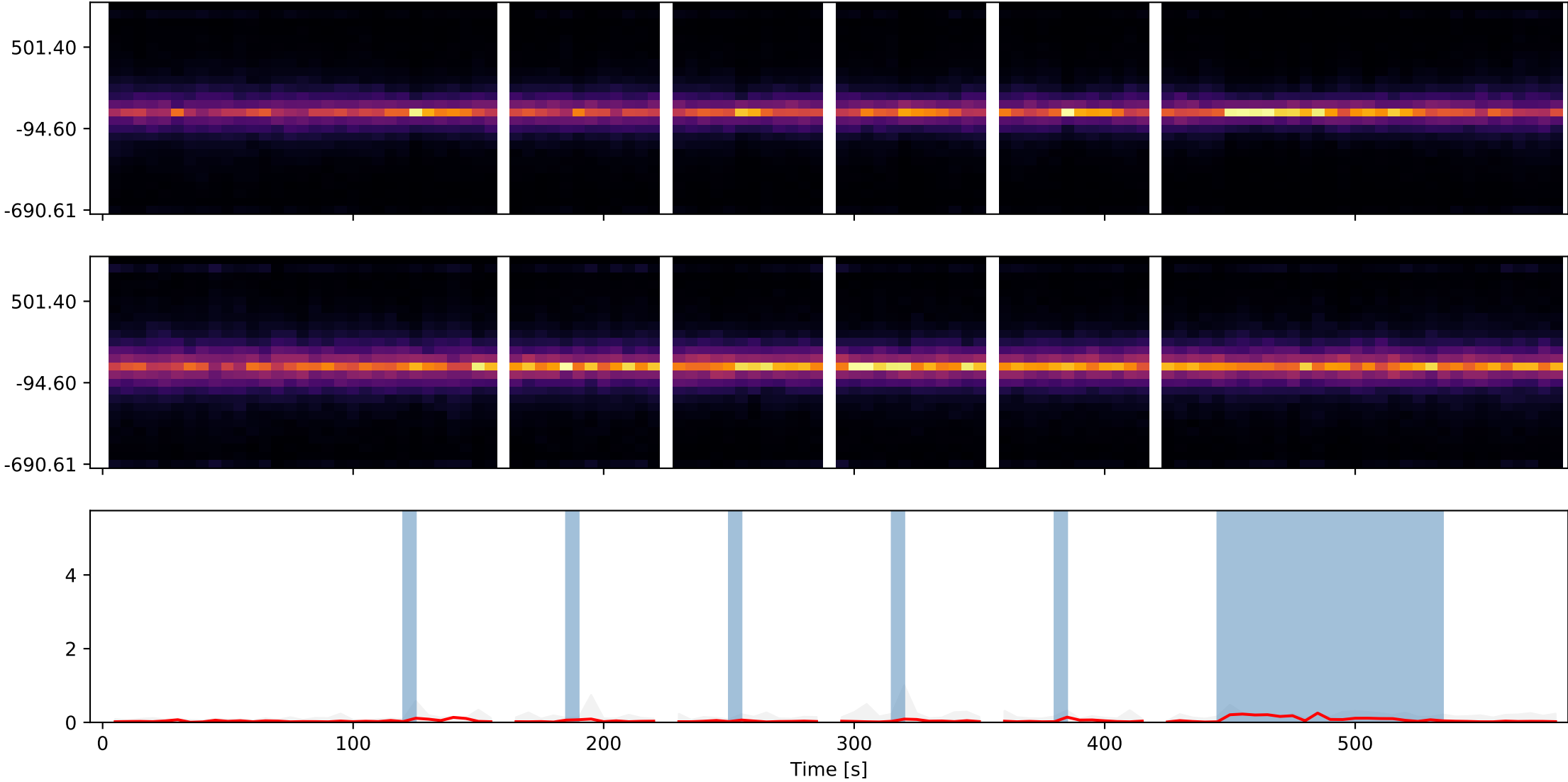
d_curvature_std_head



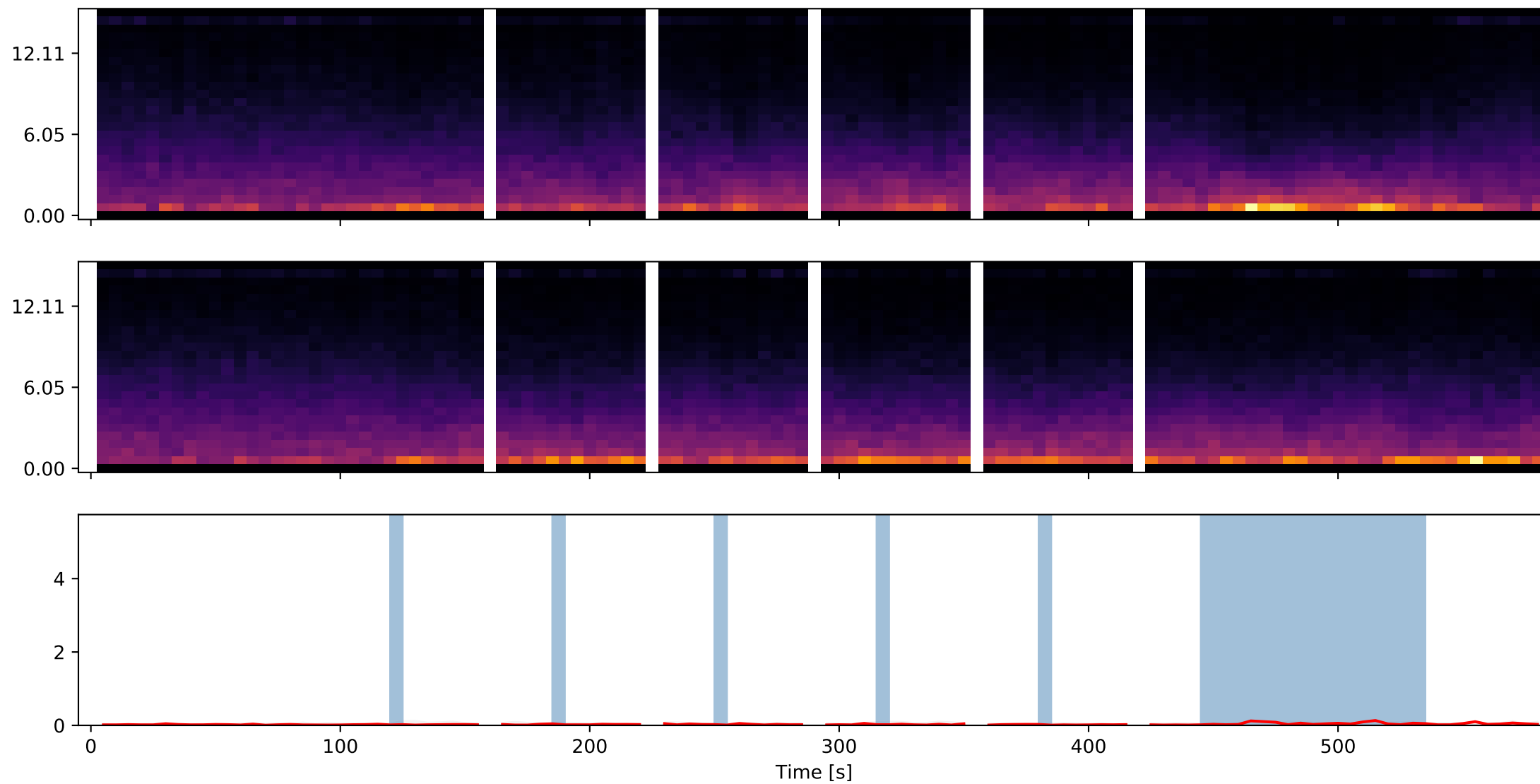
d_width_head_base



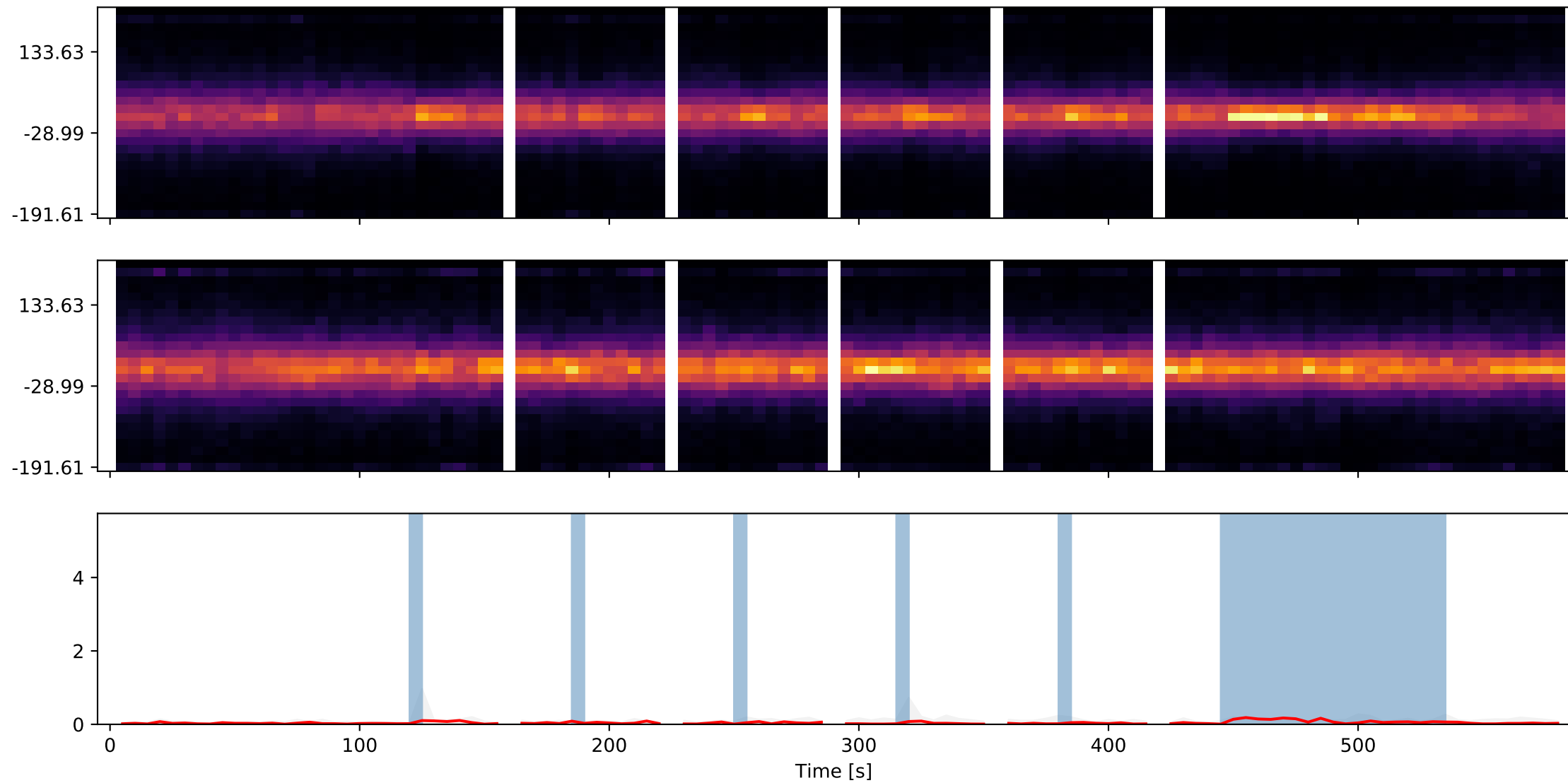
d_speed_tail_base



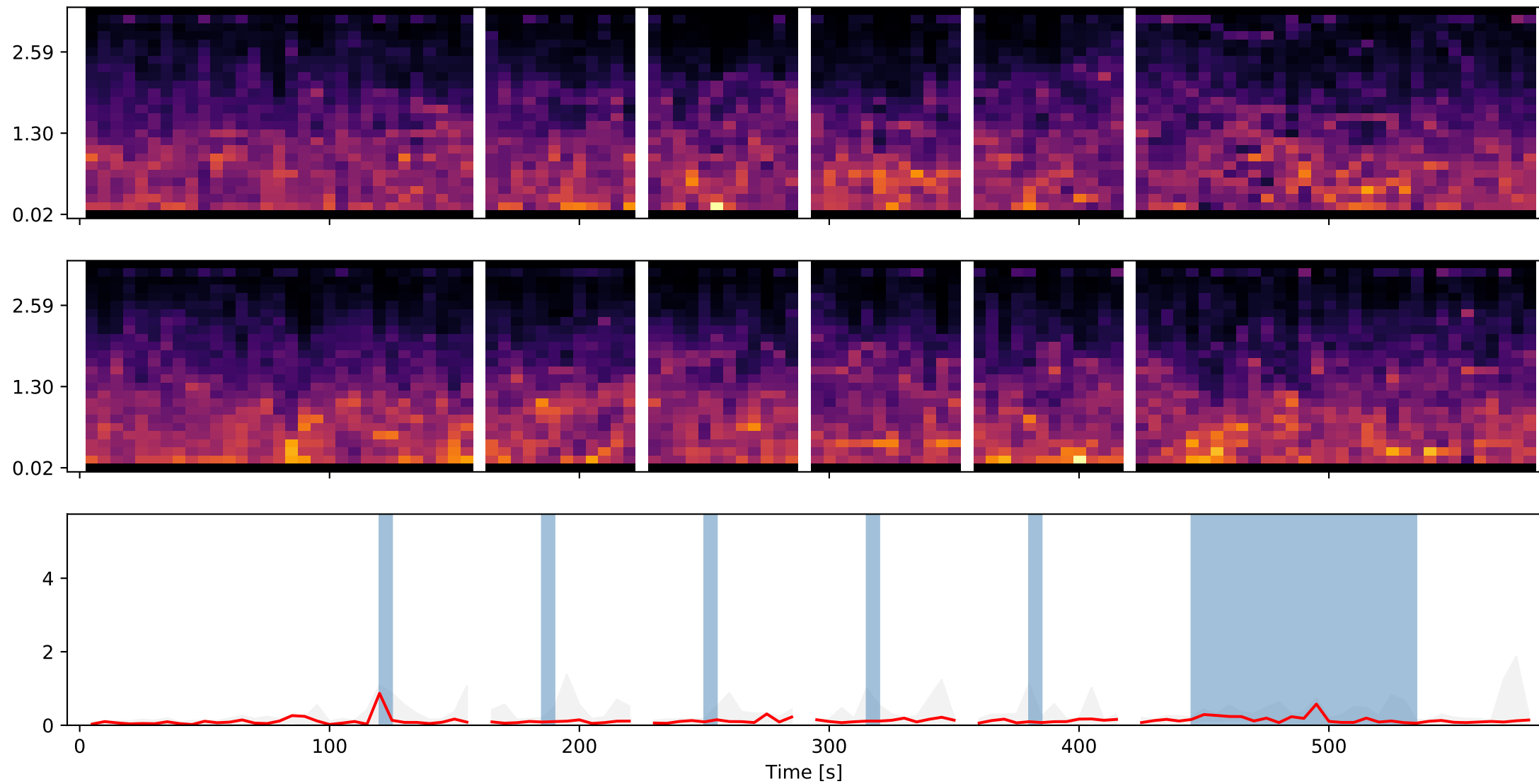
d_angular_velocity_head_tip



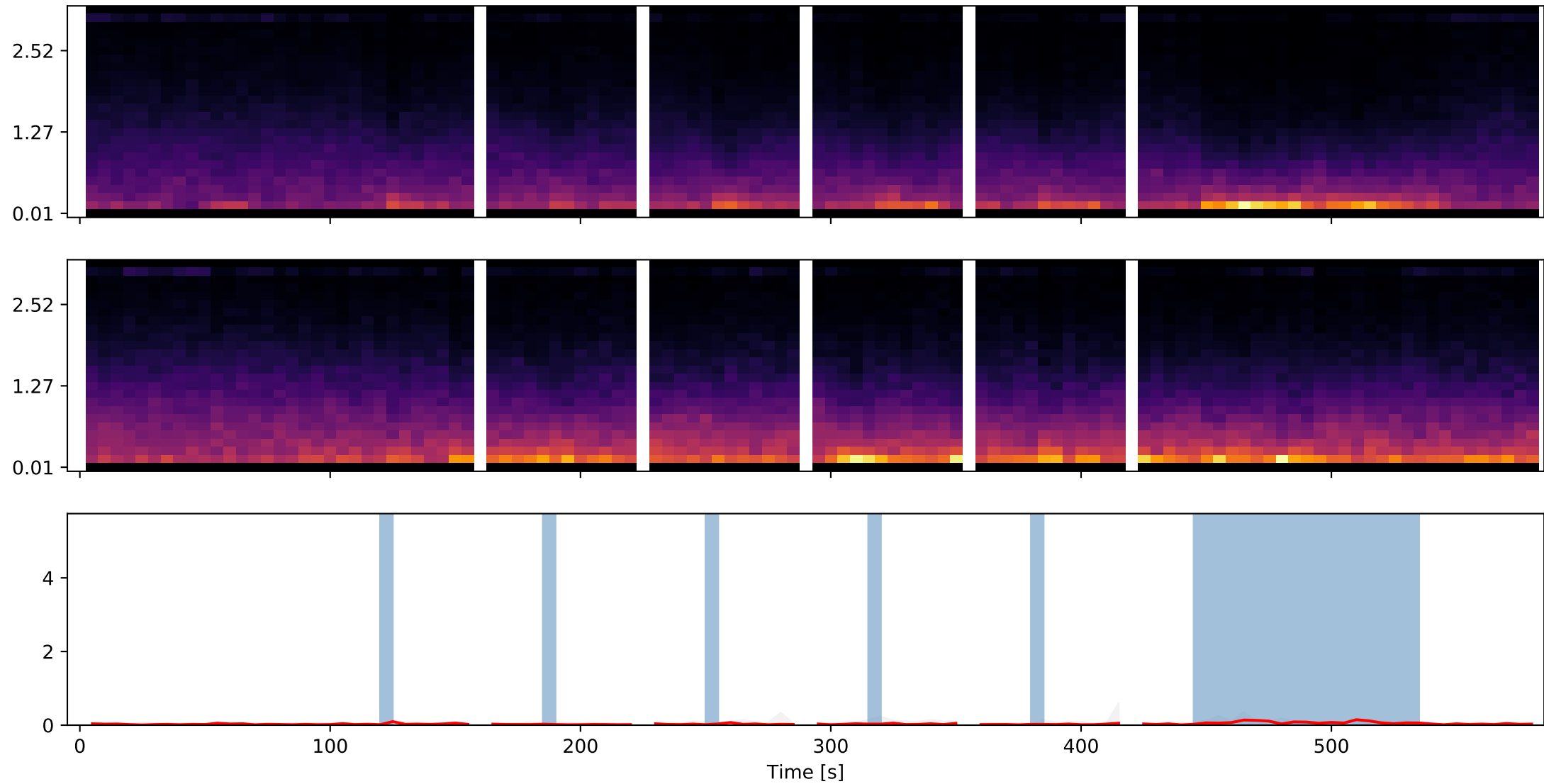
d_relative_to_body_radial_velocity_neck



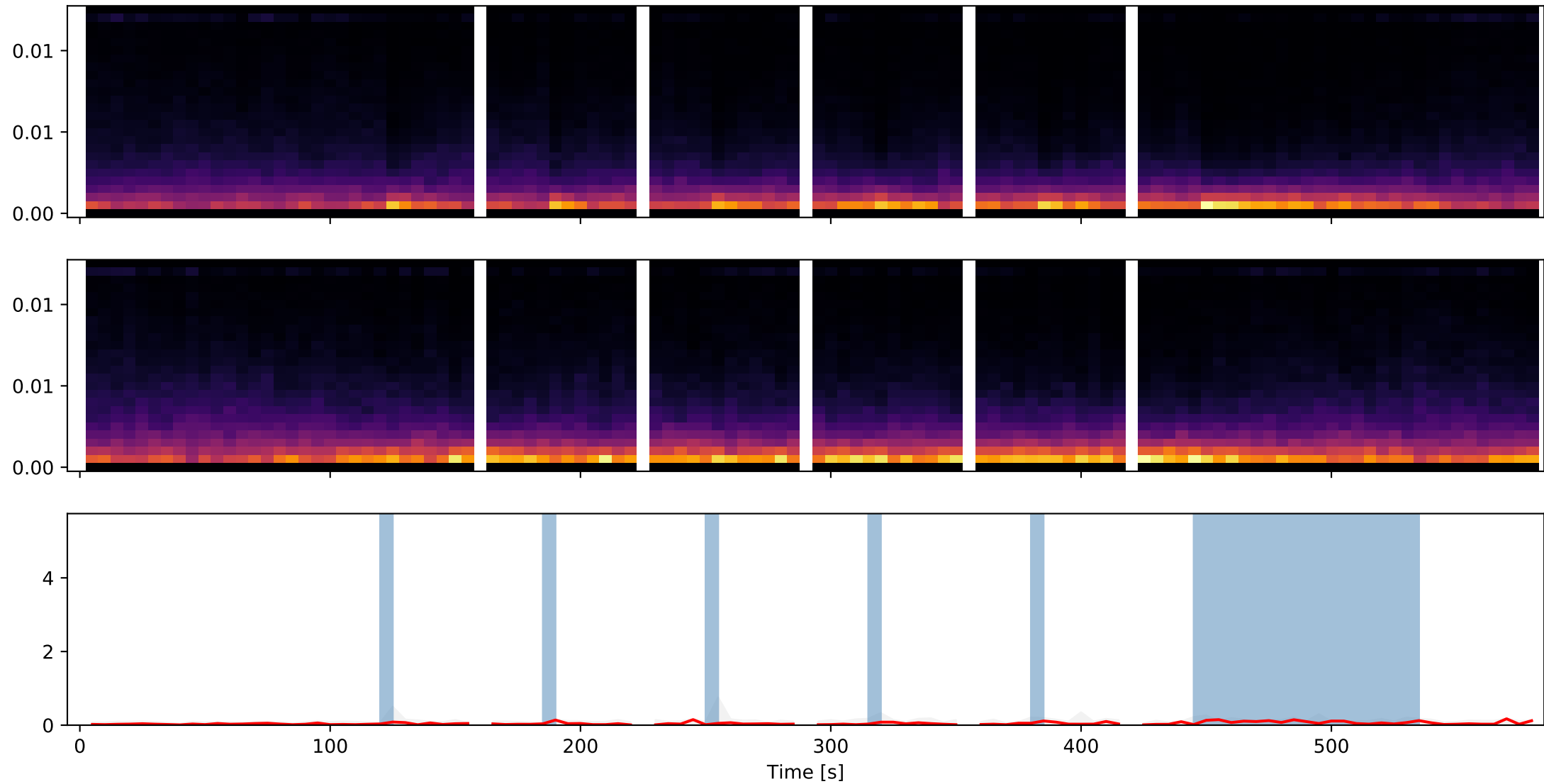
eigen_projection_4



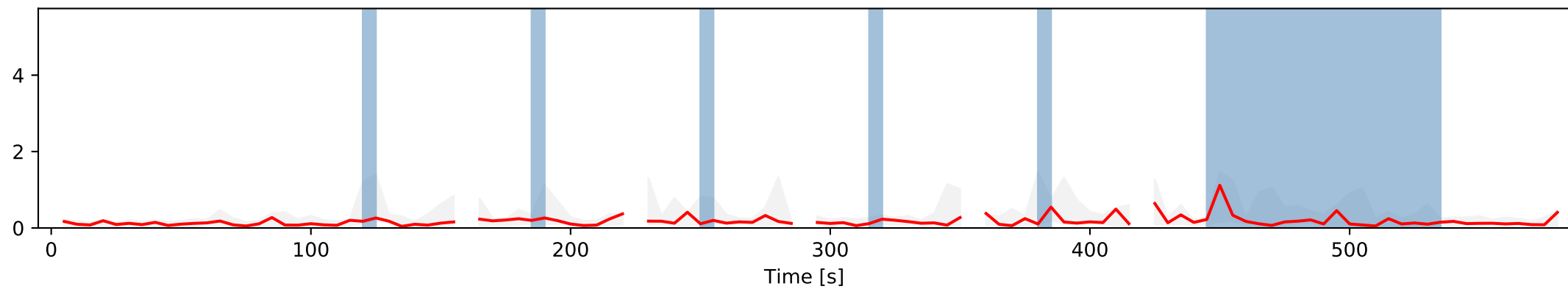
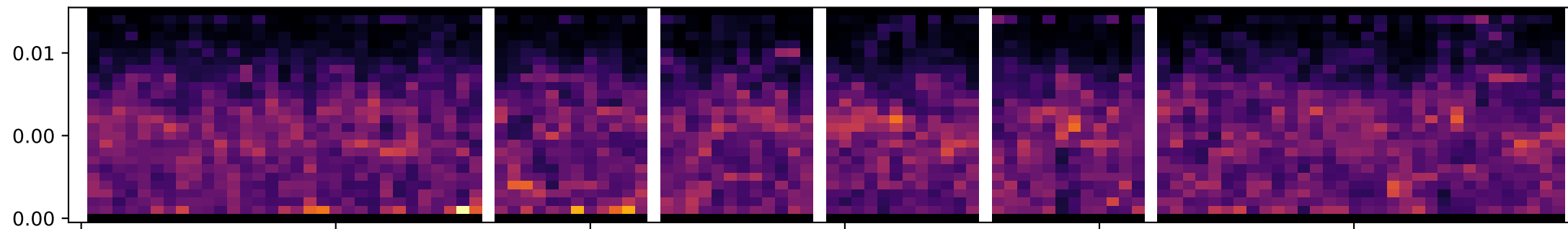
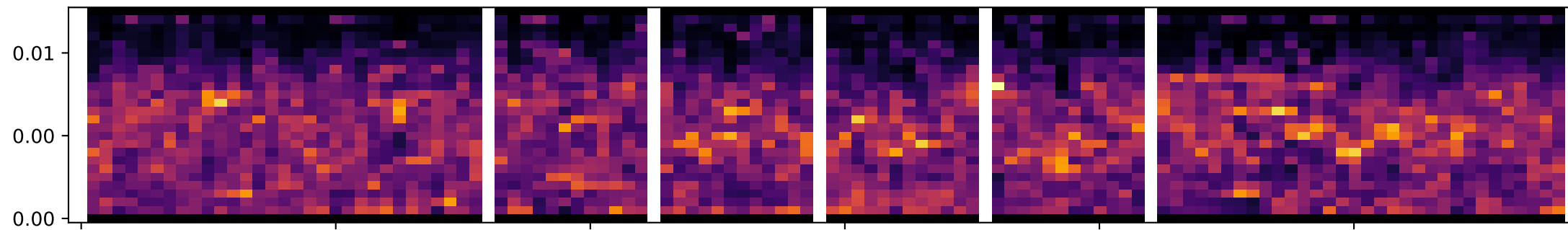
d_eigen_projection_5



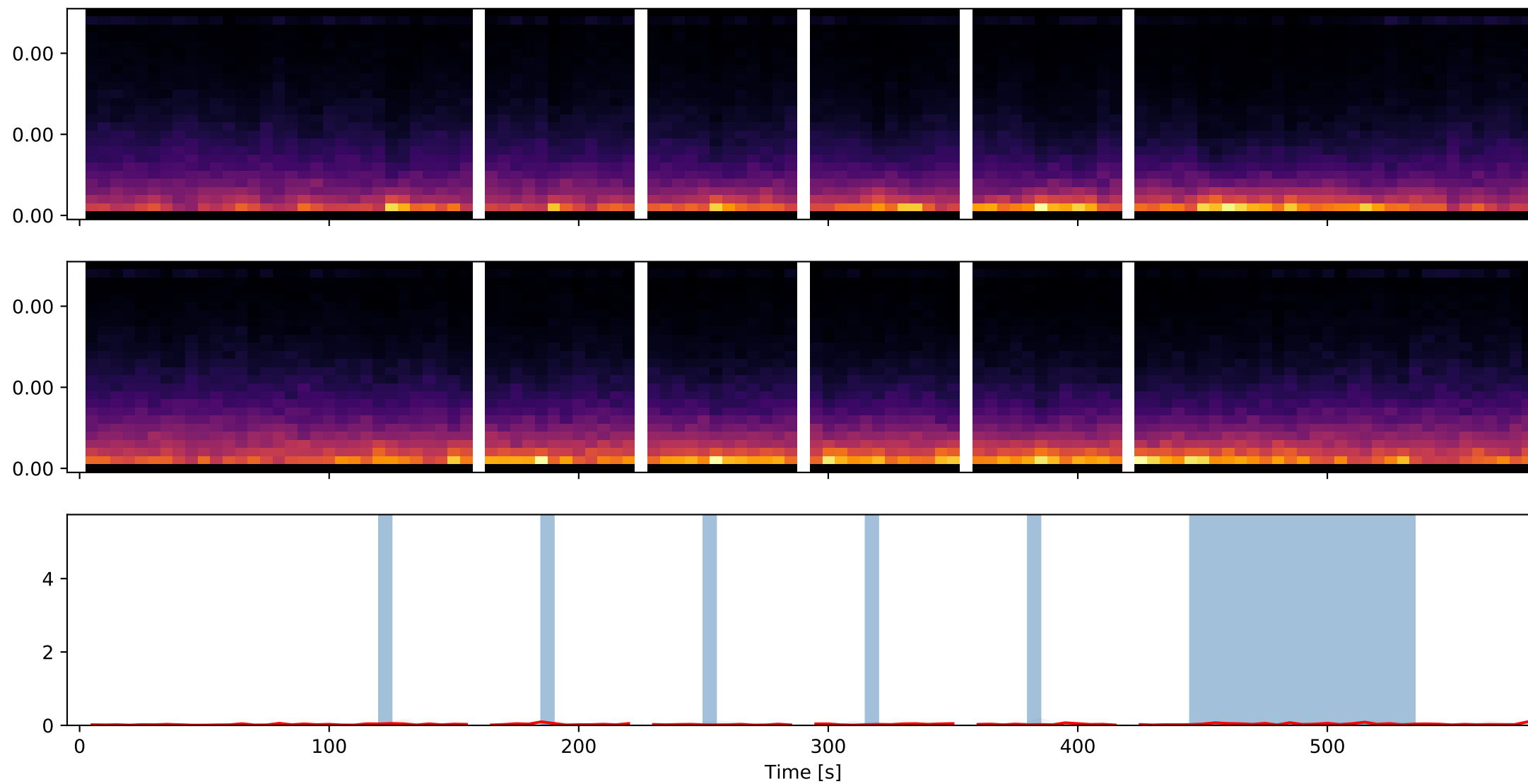
d_curvature_hips



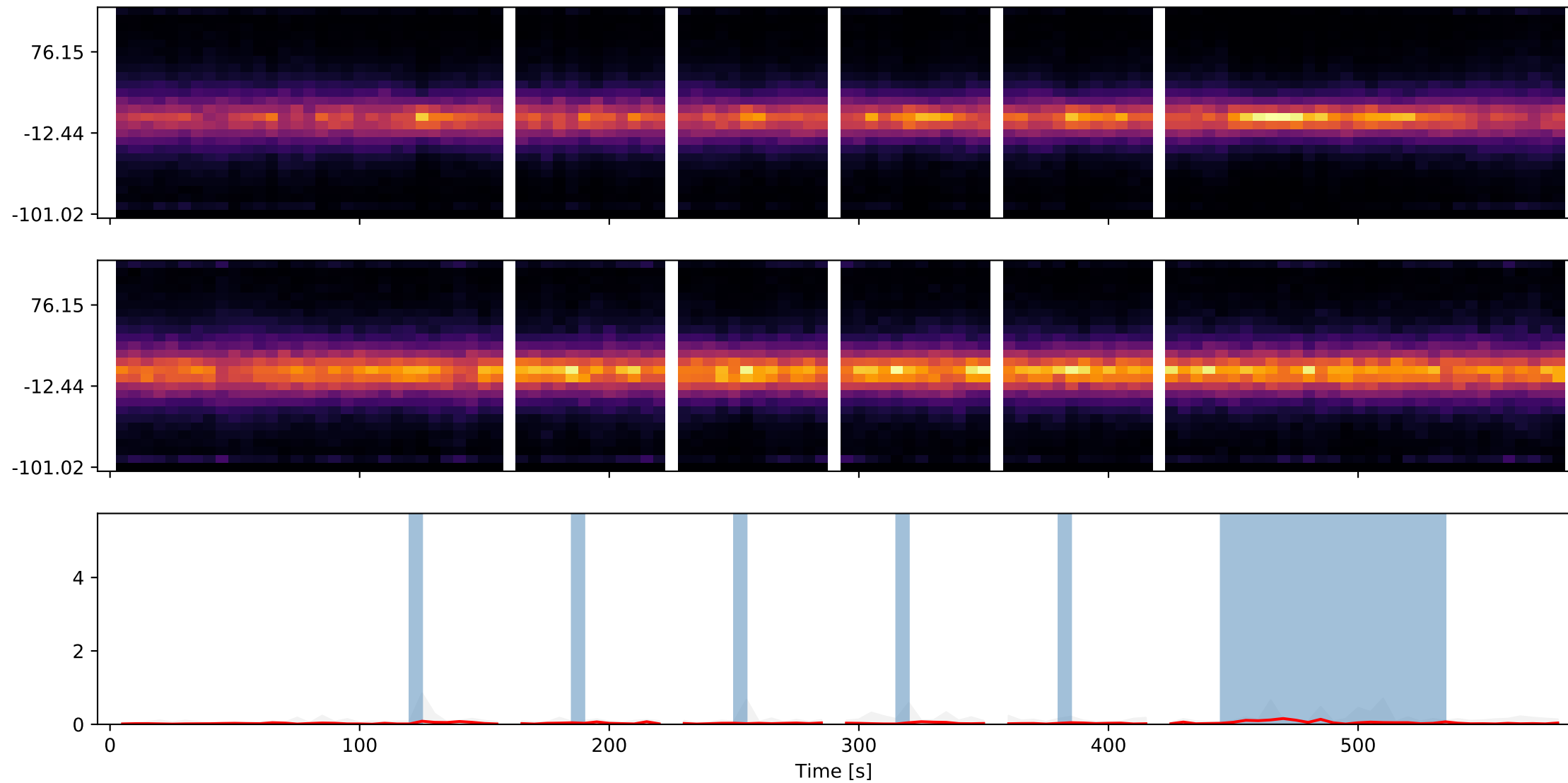
curvature_mean_tail



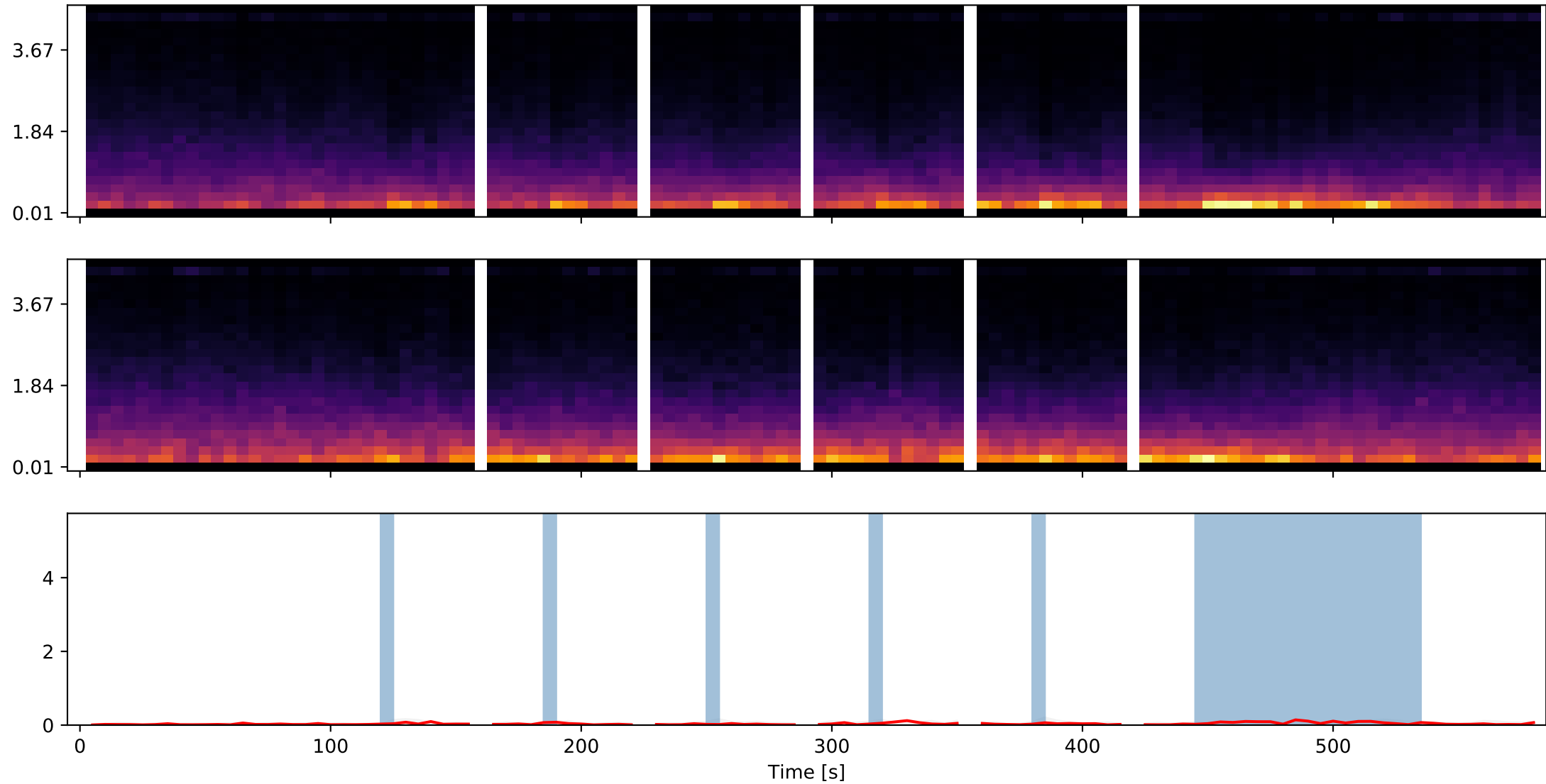
d_curvature_std_tail



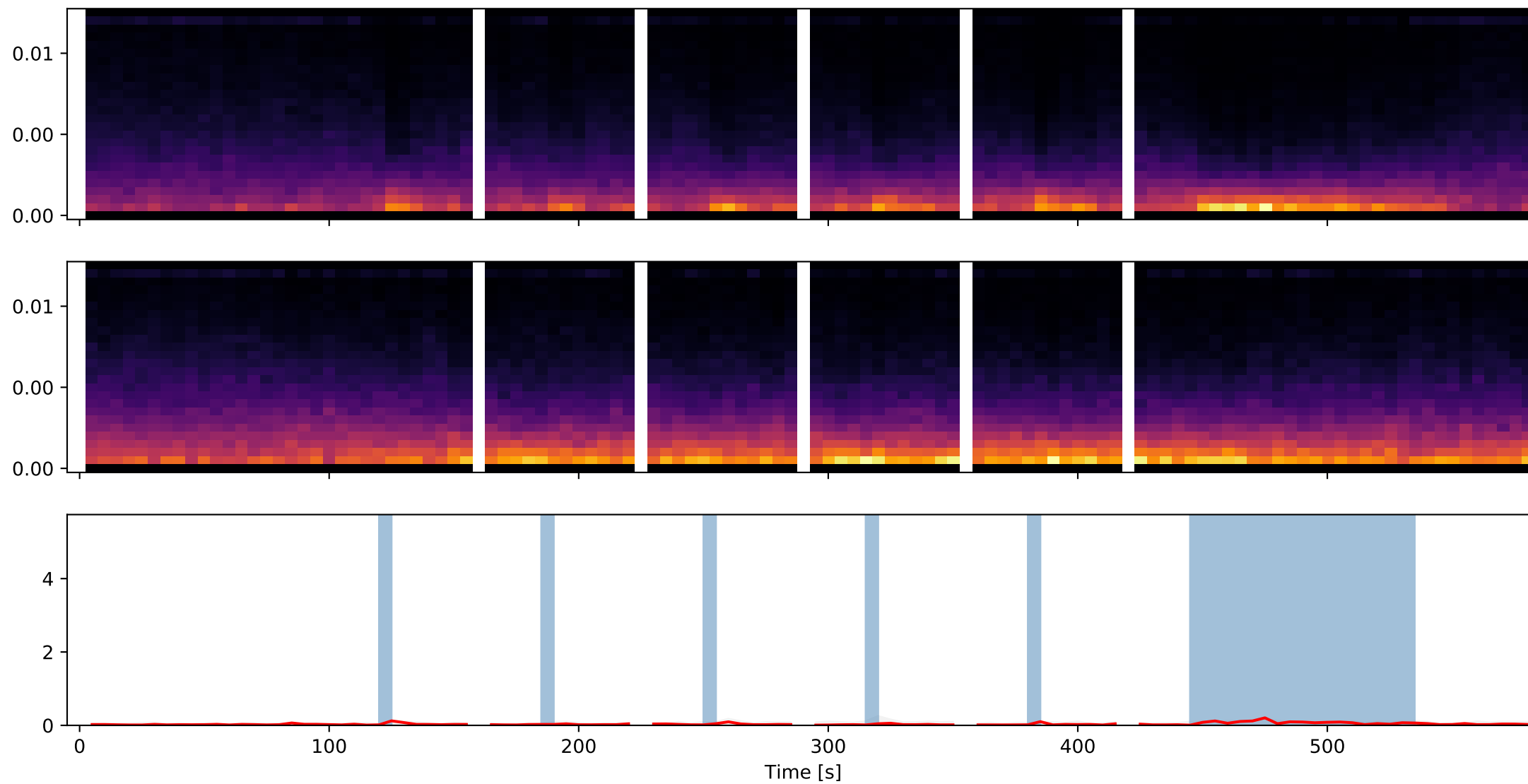
d_relative_to_tail_base_radial_velocity_tail_tip



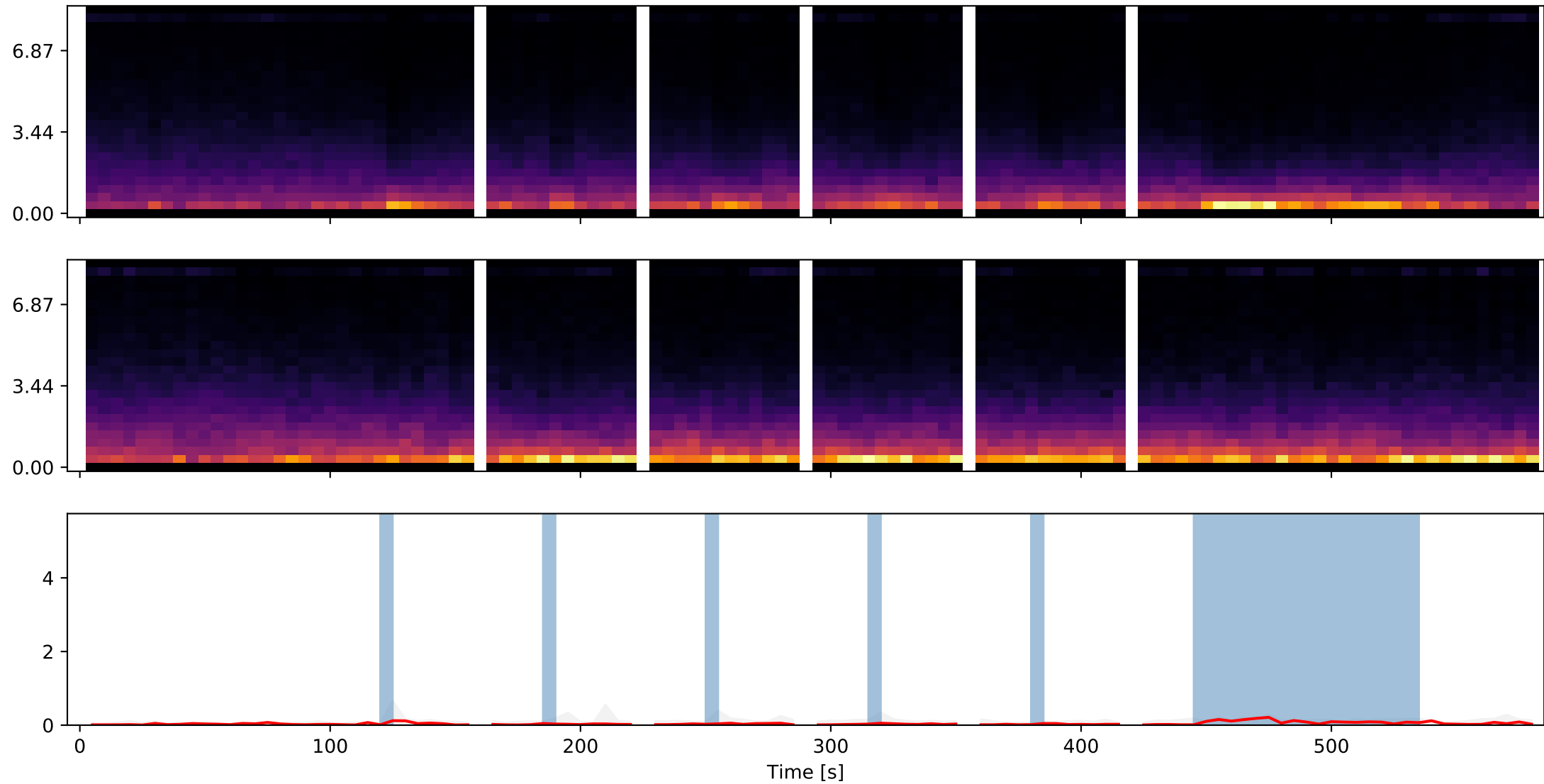
d_relative_to_tail_base_angular_velocity_tail_tip



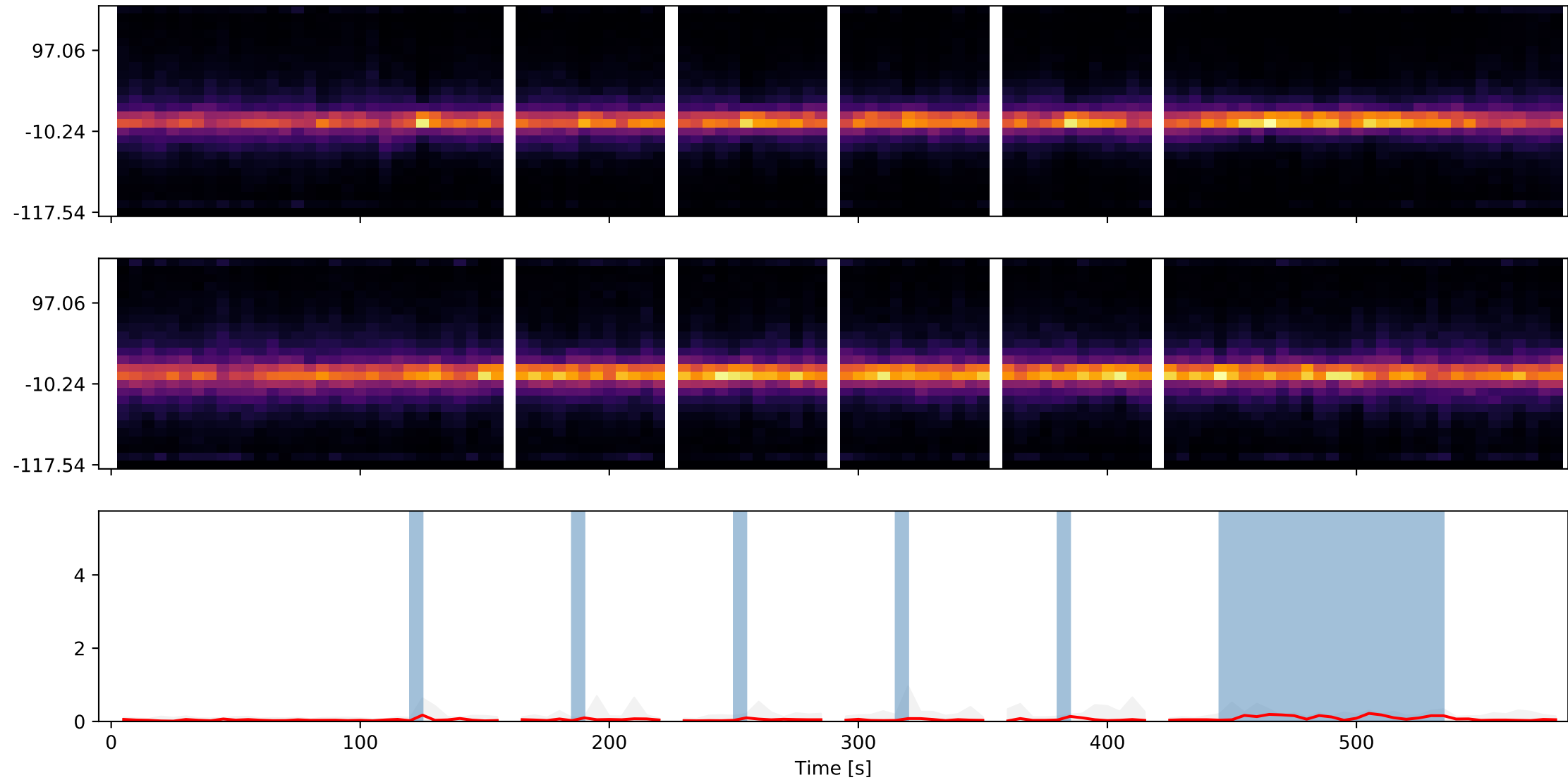
d_curvature_std_neck



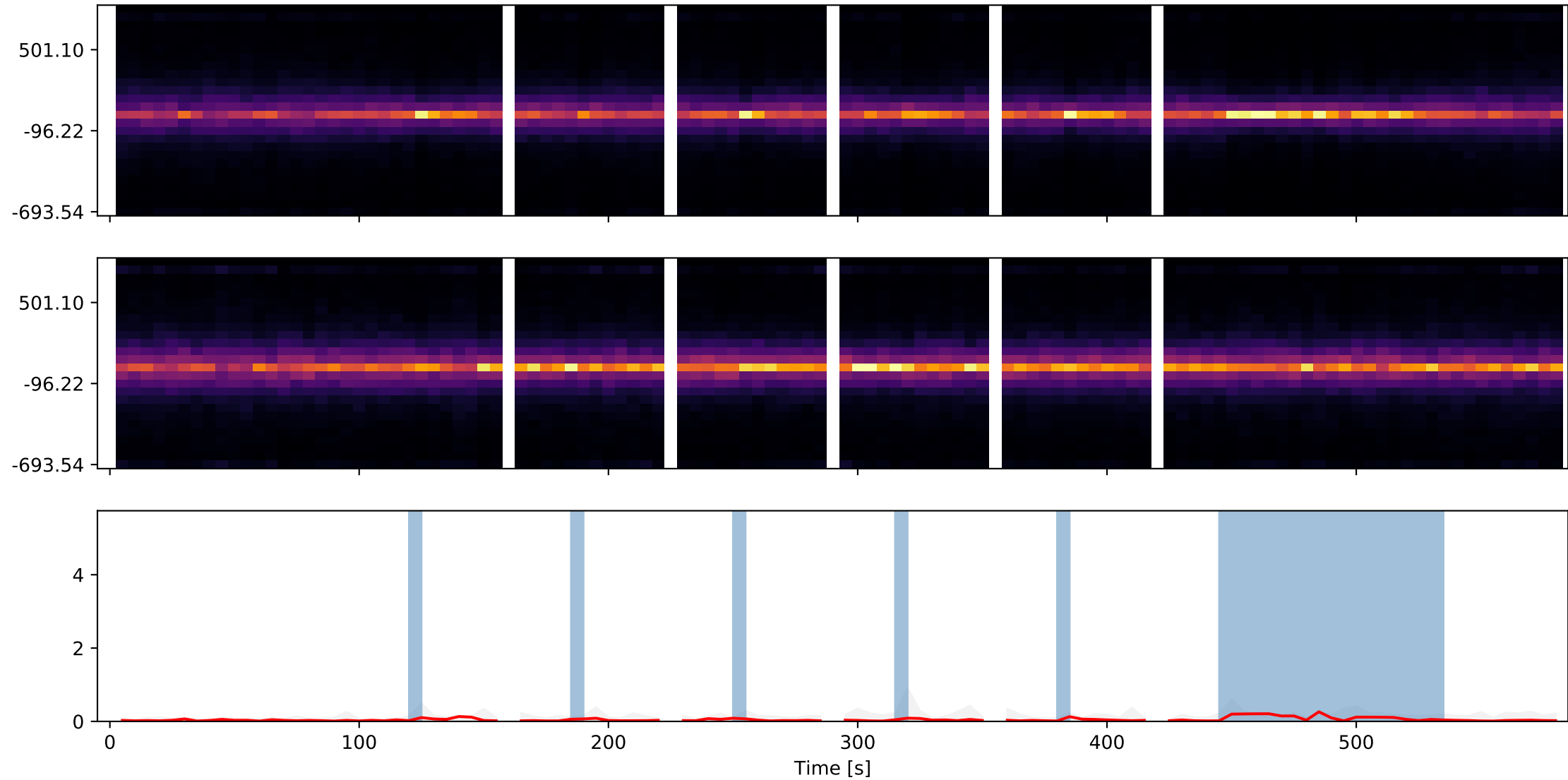
d_angular_velocity_head_base



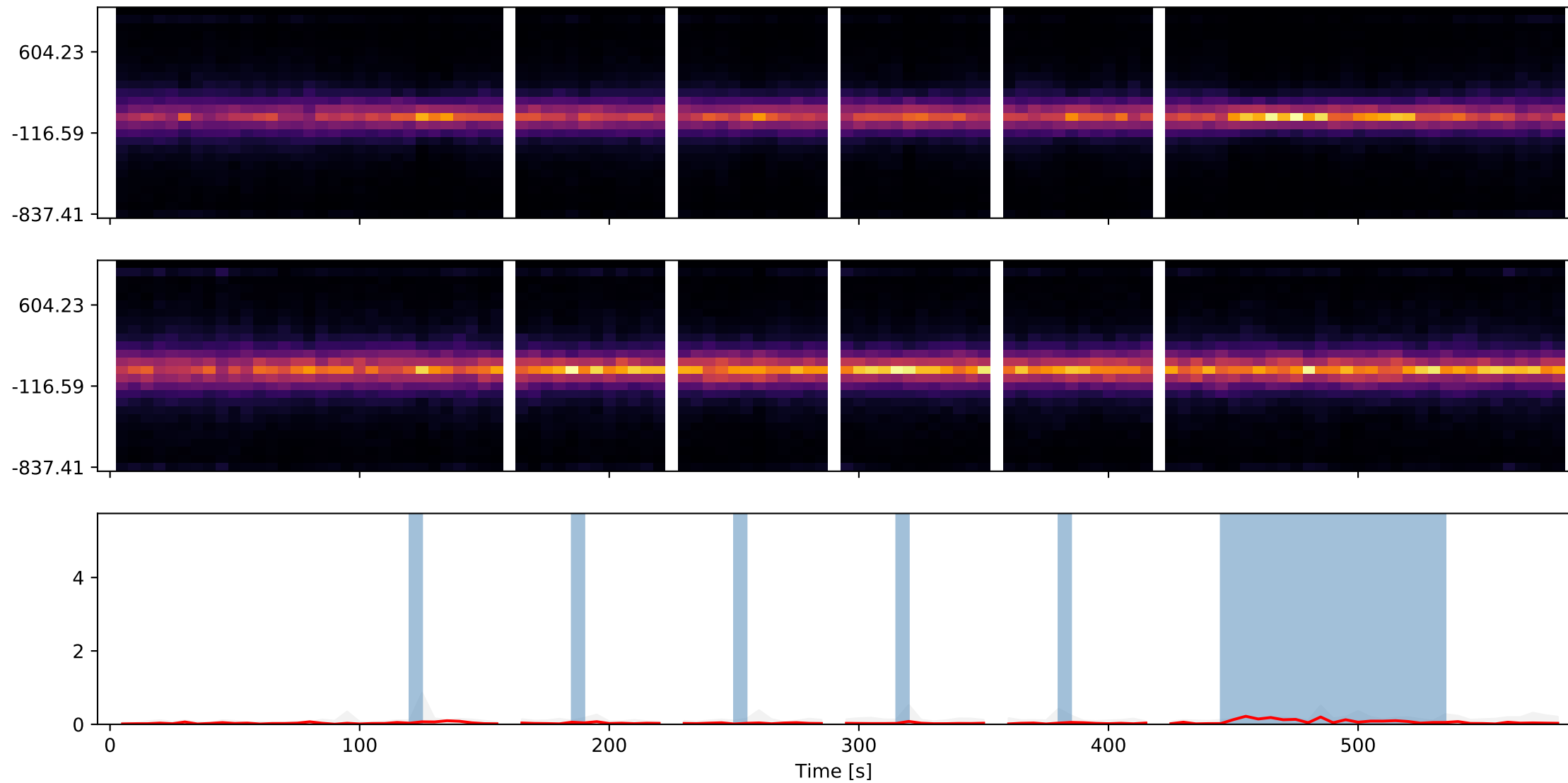
d_minor_axis



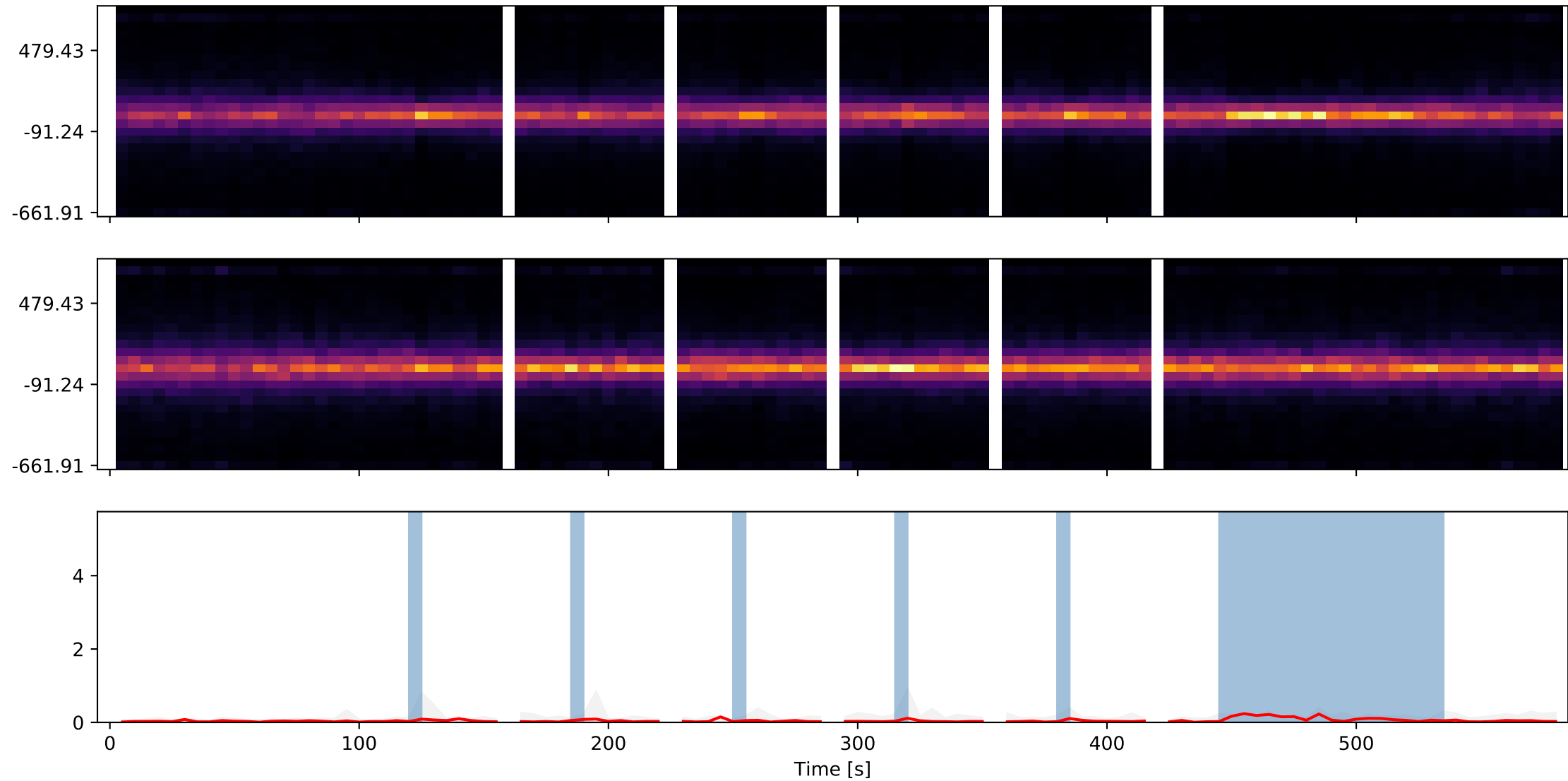
d_speed_tail_tip



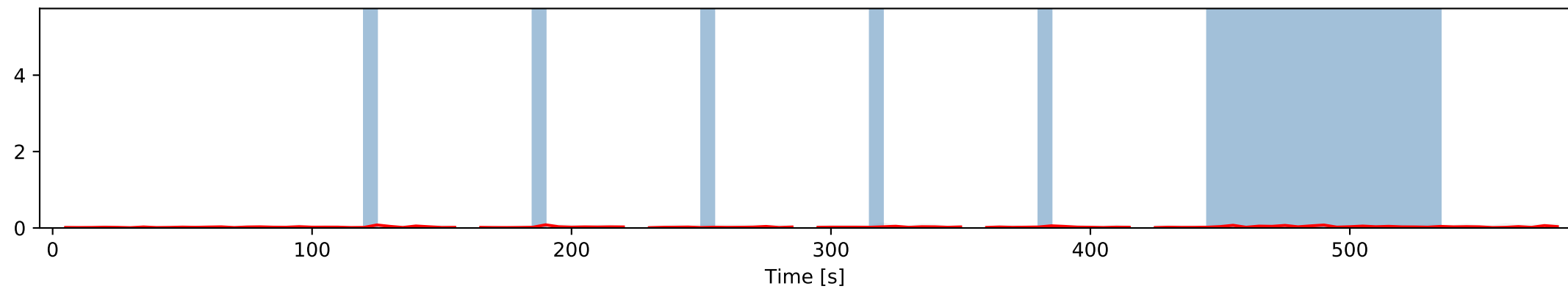
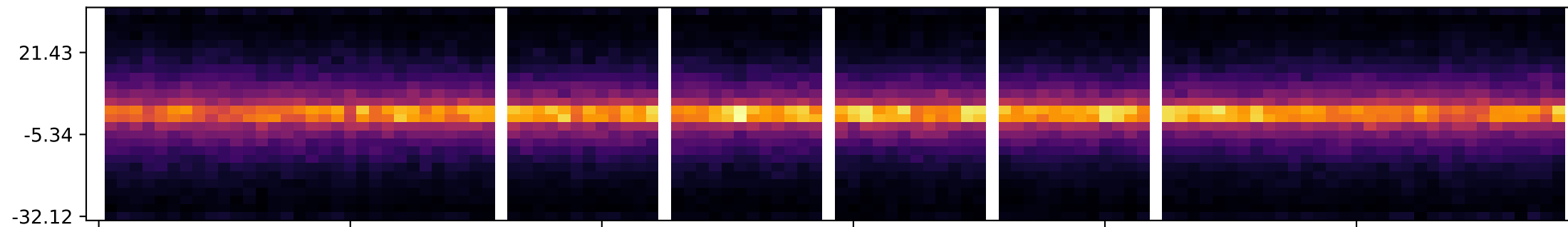
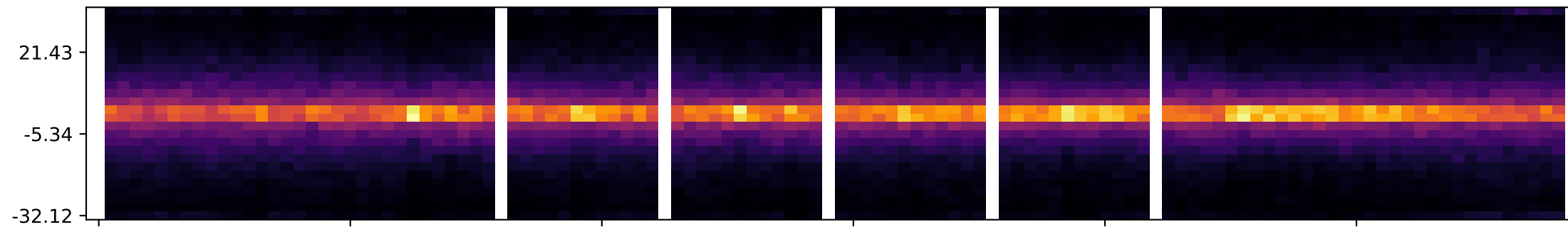
d_speed_head_base



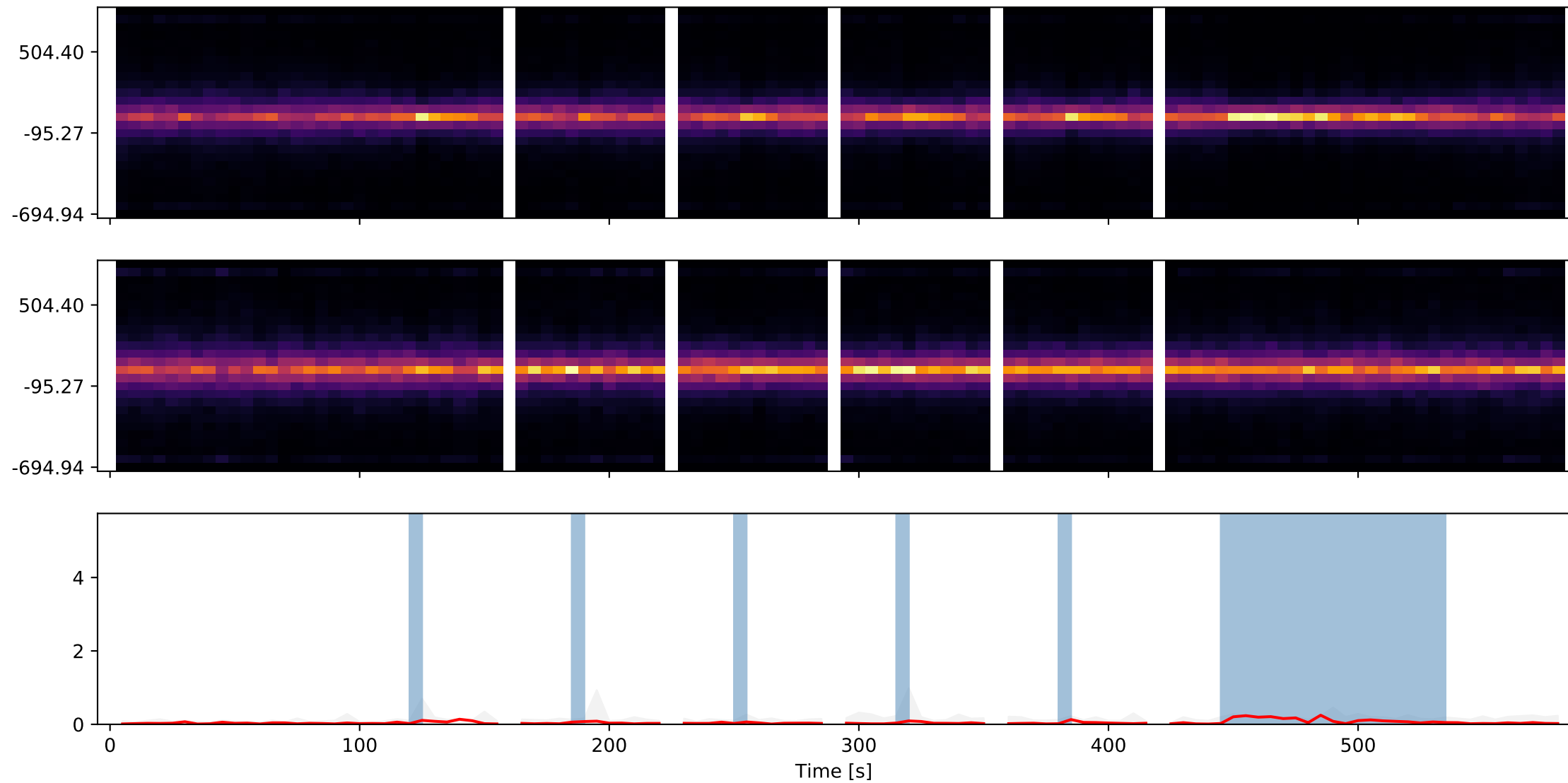
d_speed



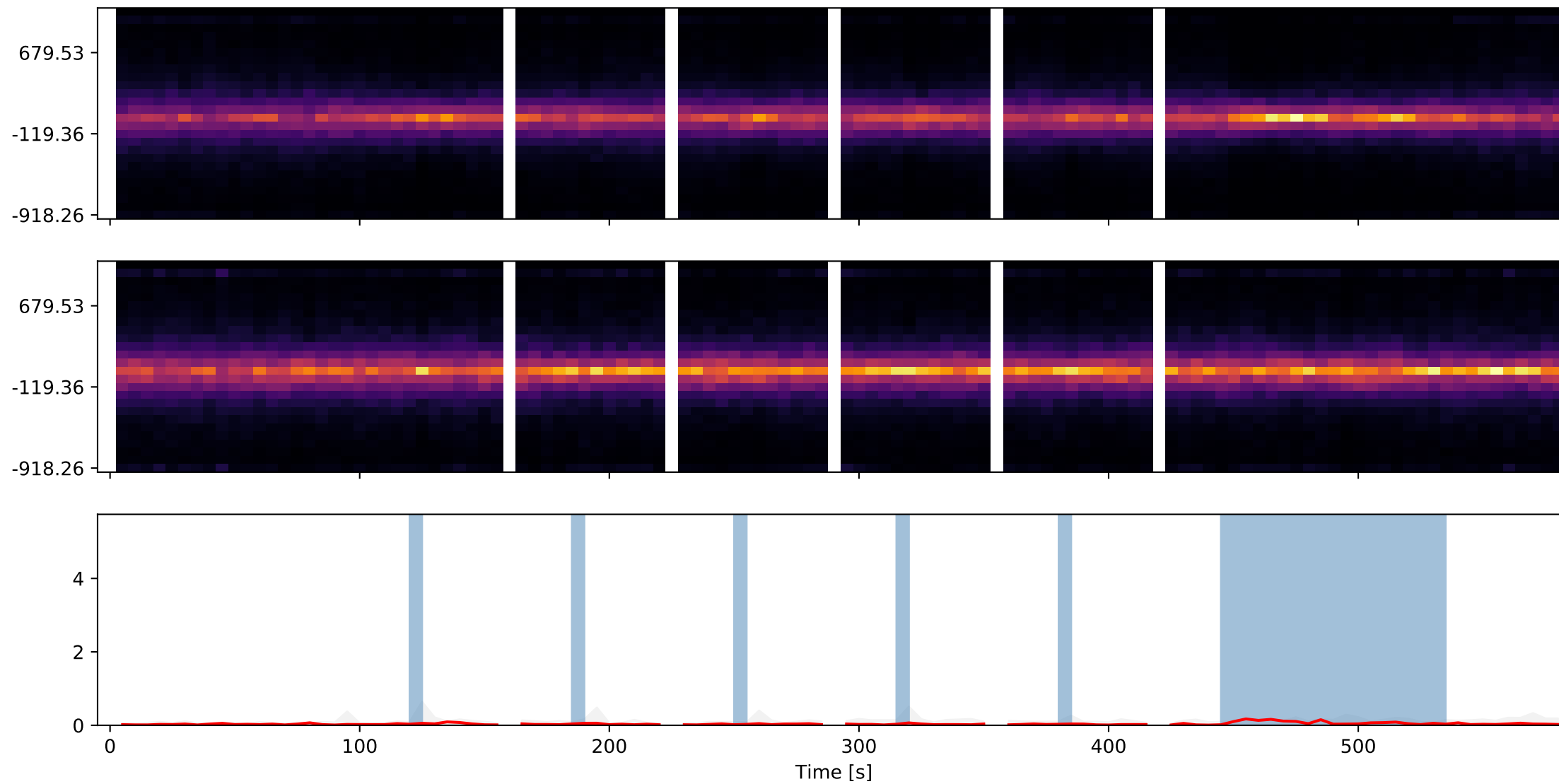
d_width_tail_base



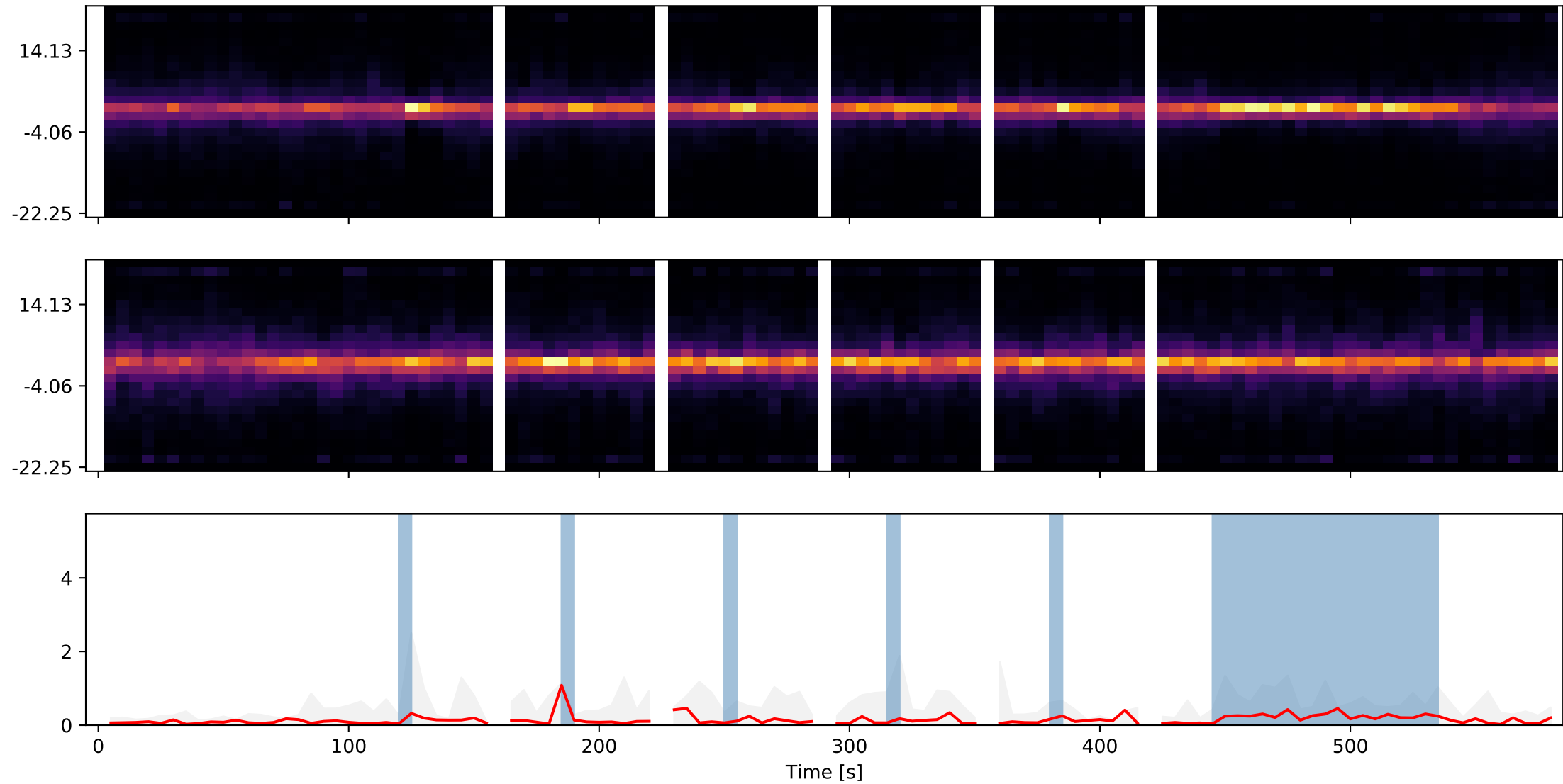
d_speed_hips



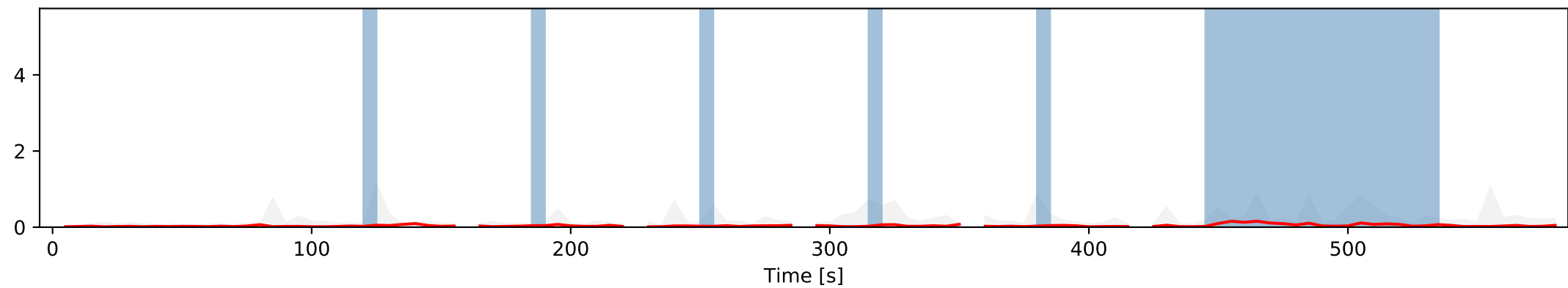
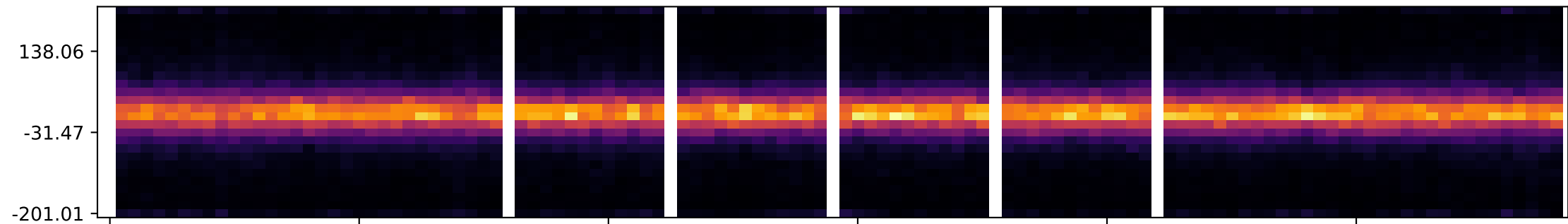
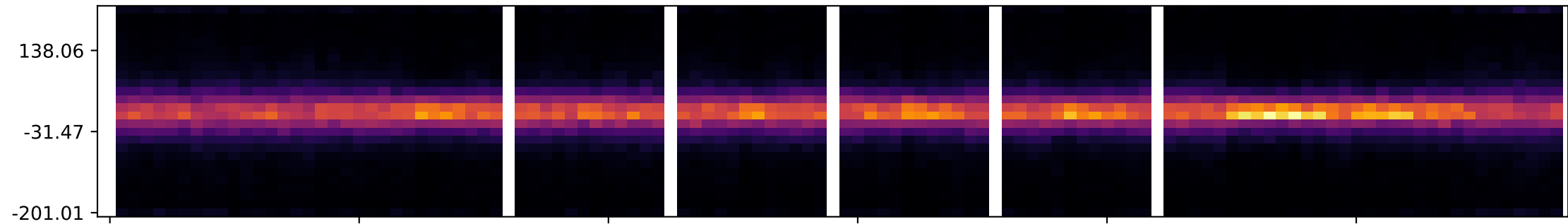
d_speed_head_tip



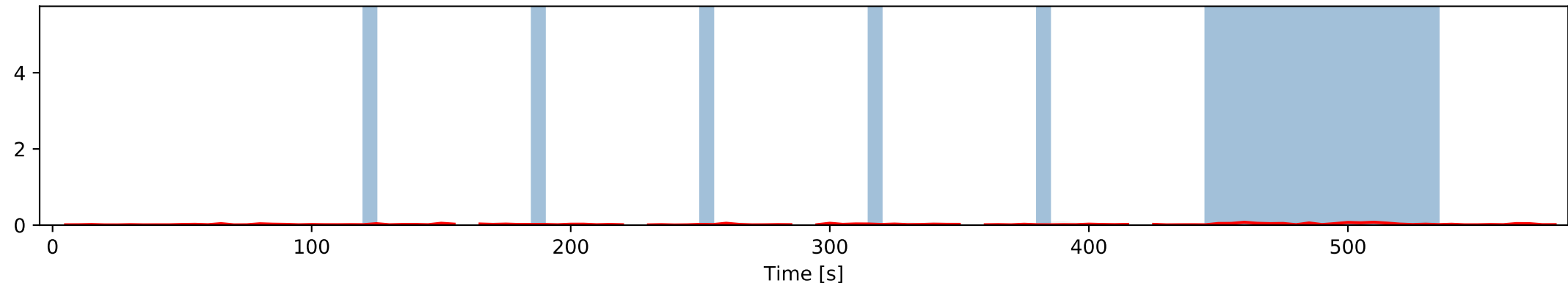
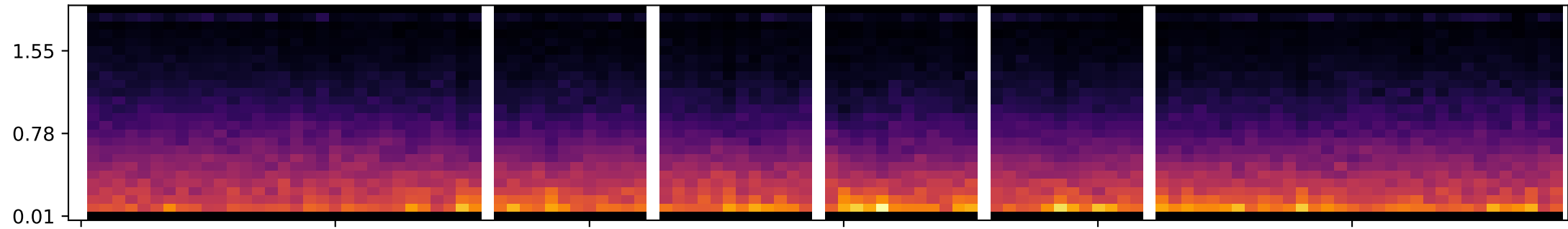
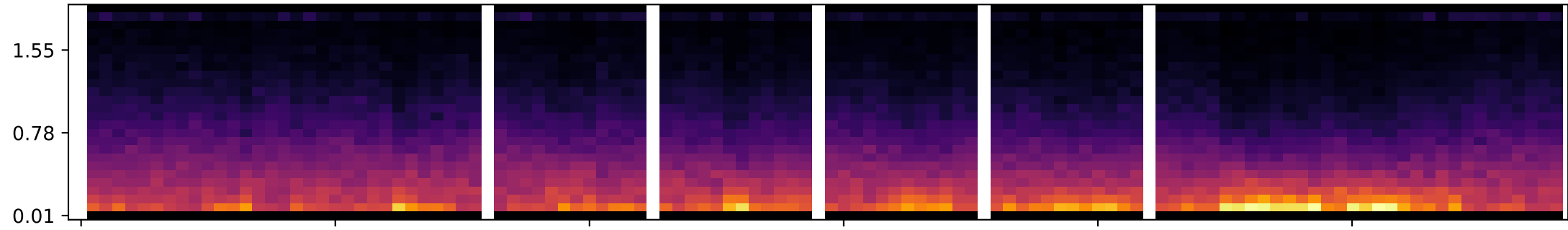
d_orientation_food_edge



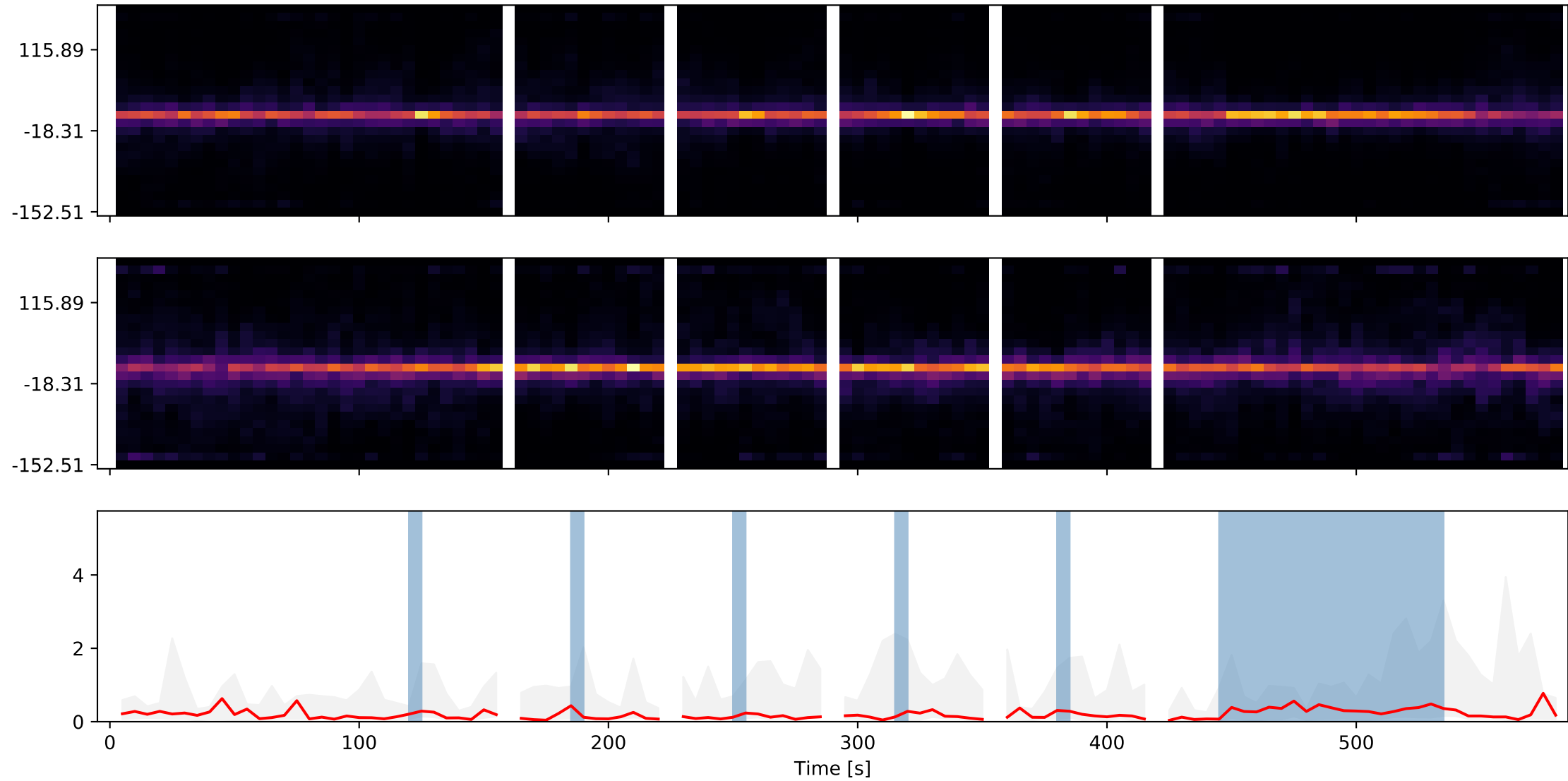
d_length



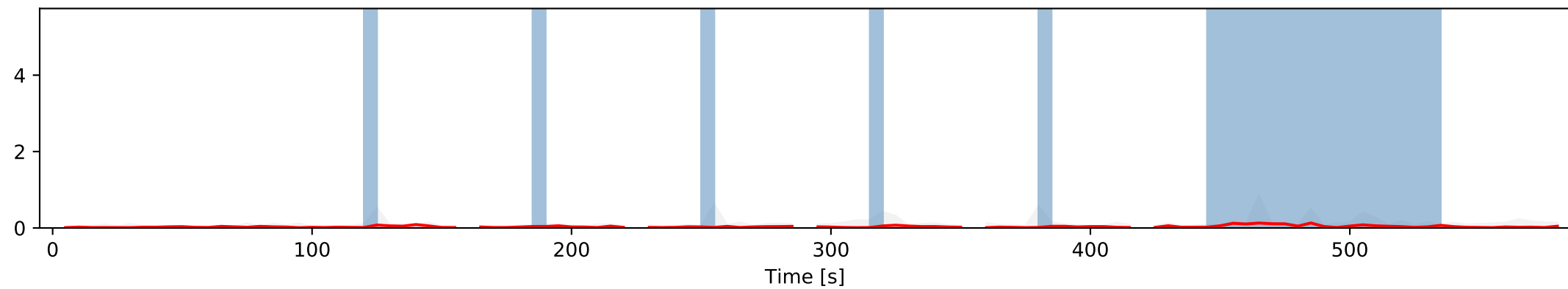
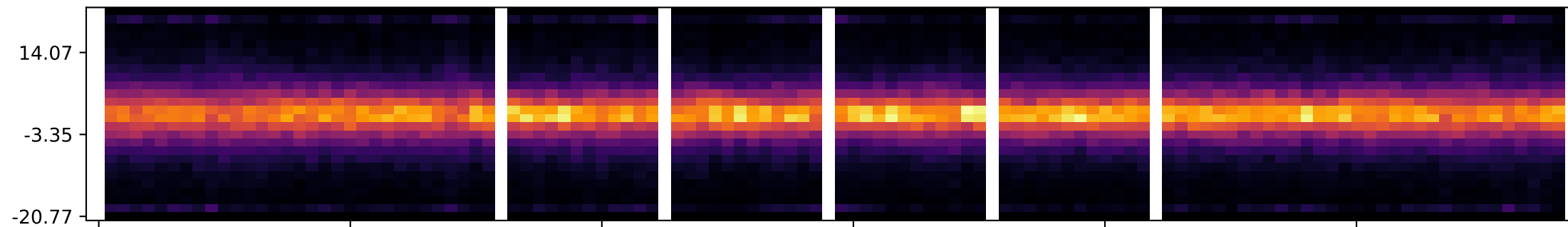
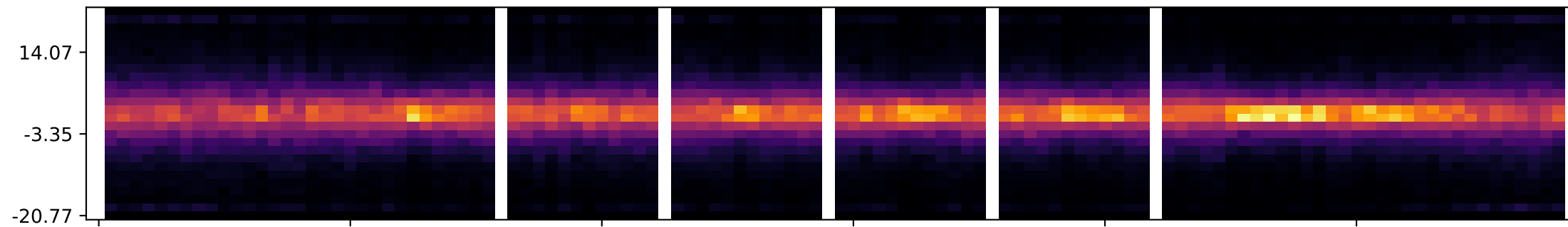
d_eigen_projection_7



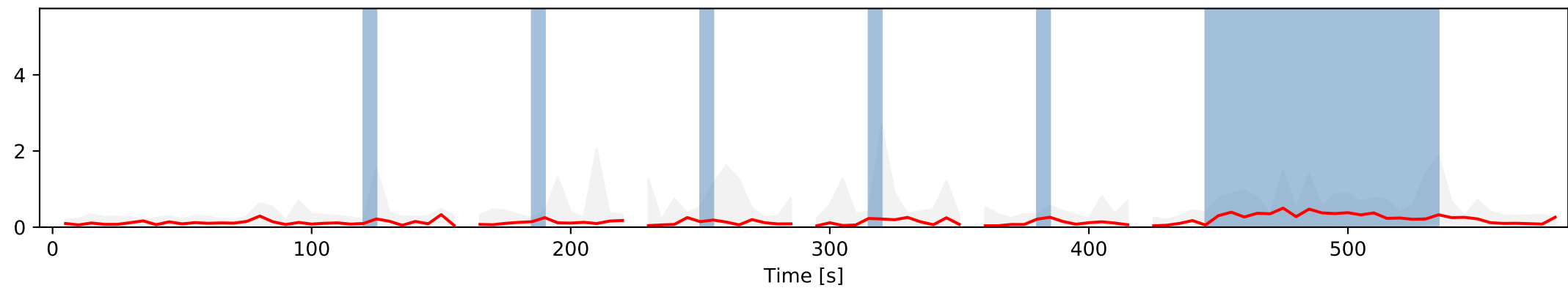
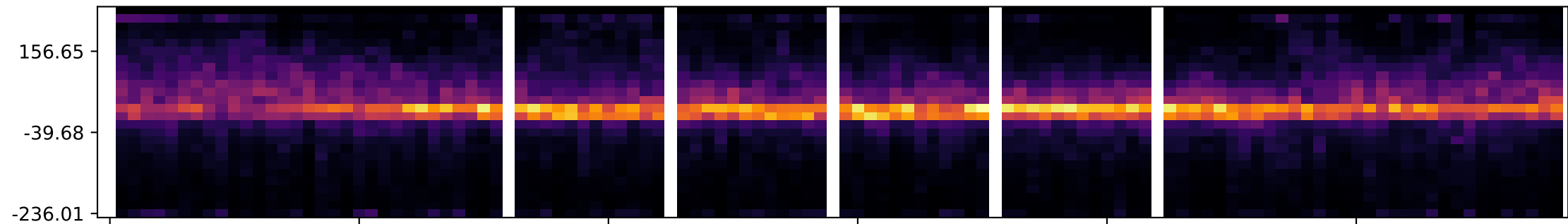
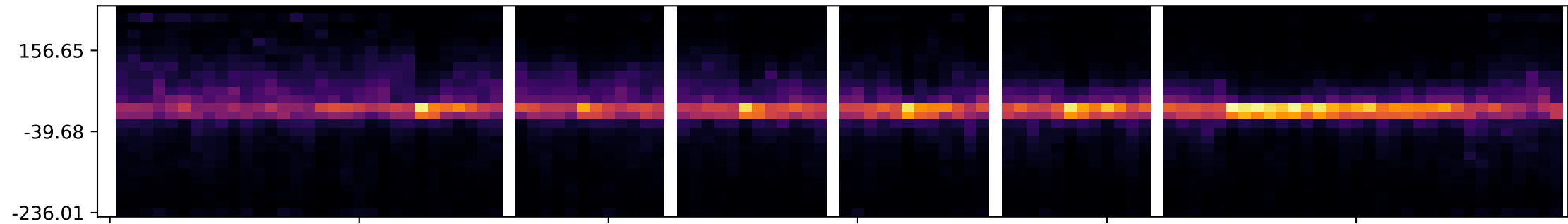
d_dist_from_food_edge



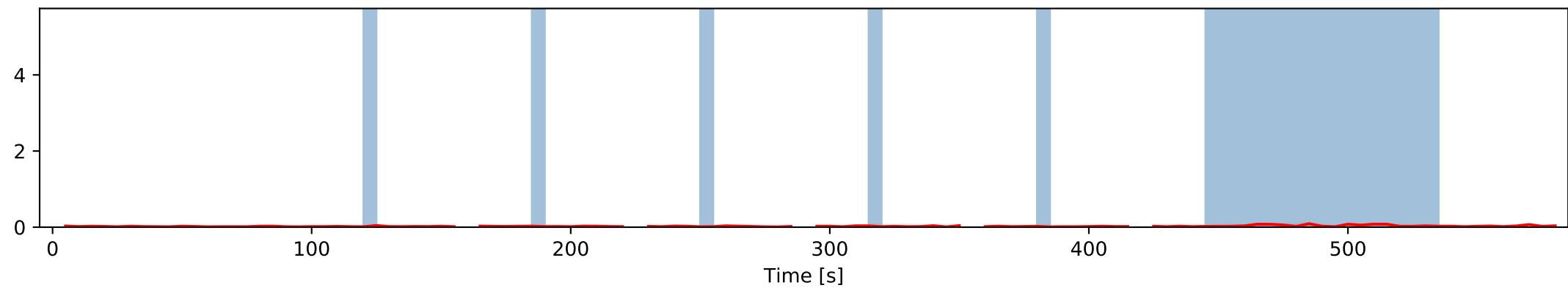
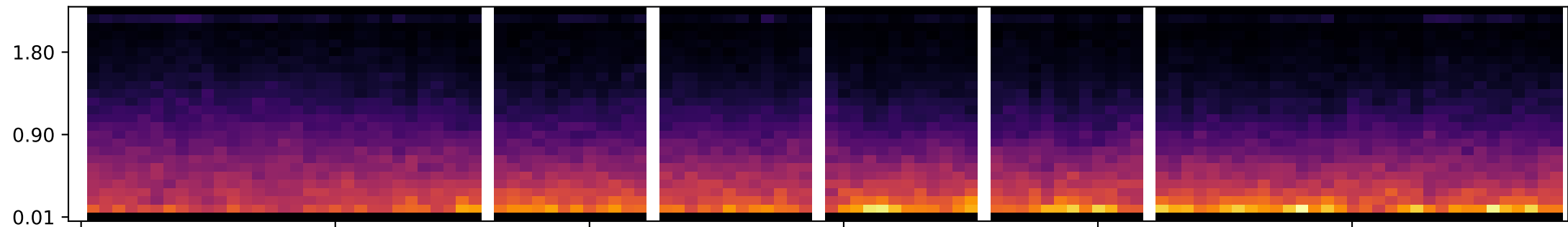
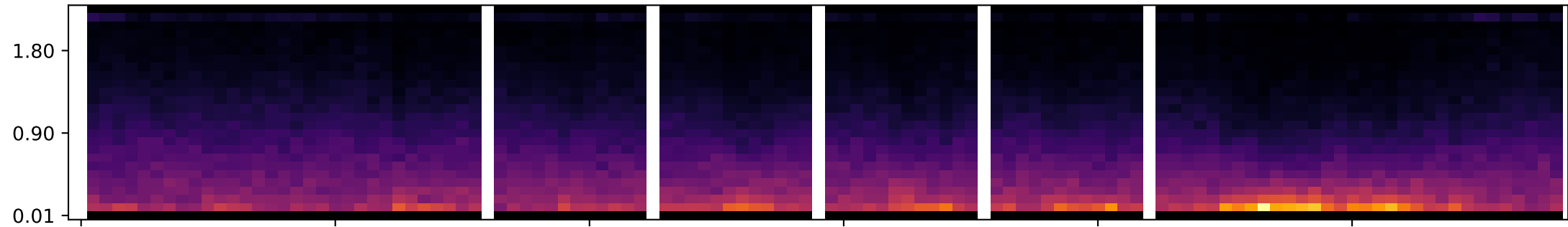
relative_to_tail_base_radial_velocity_tail_tip



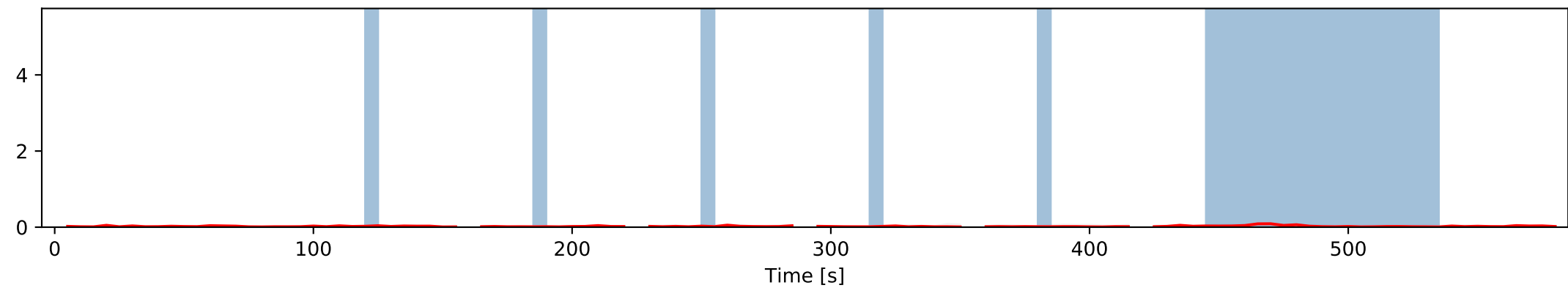
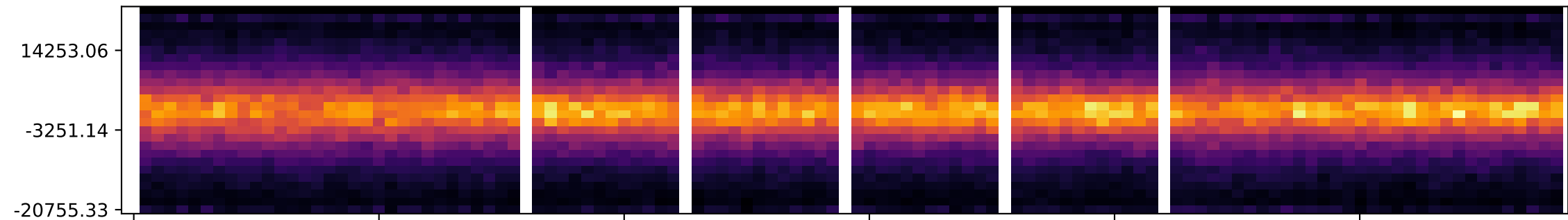
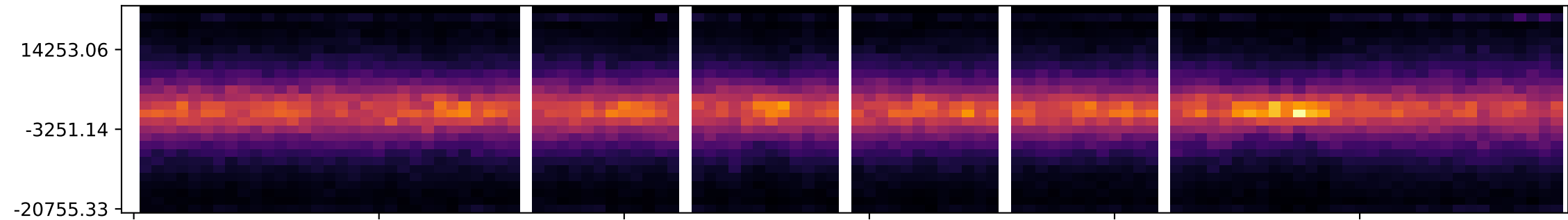
speed_hips



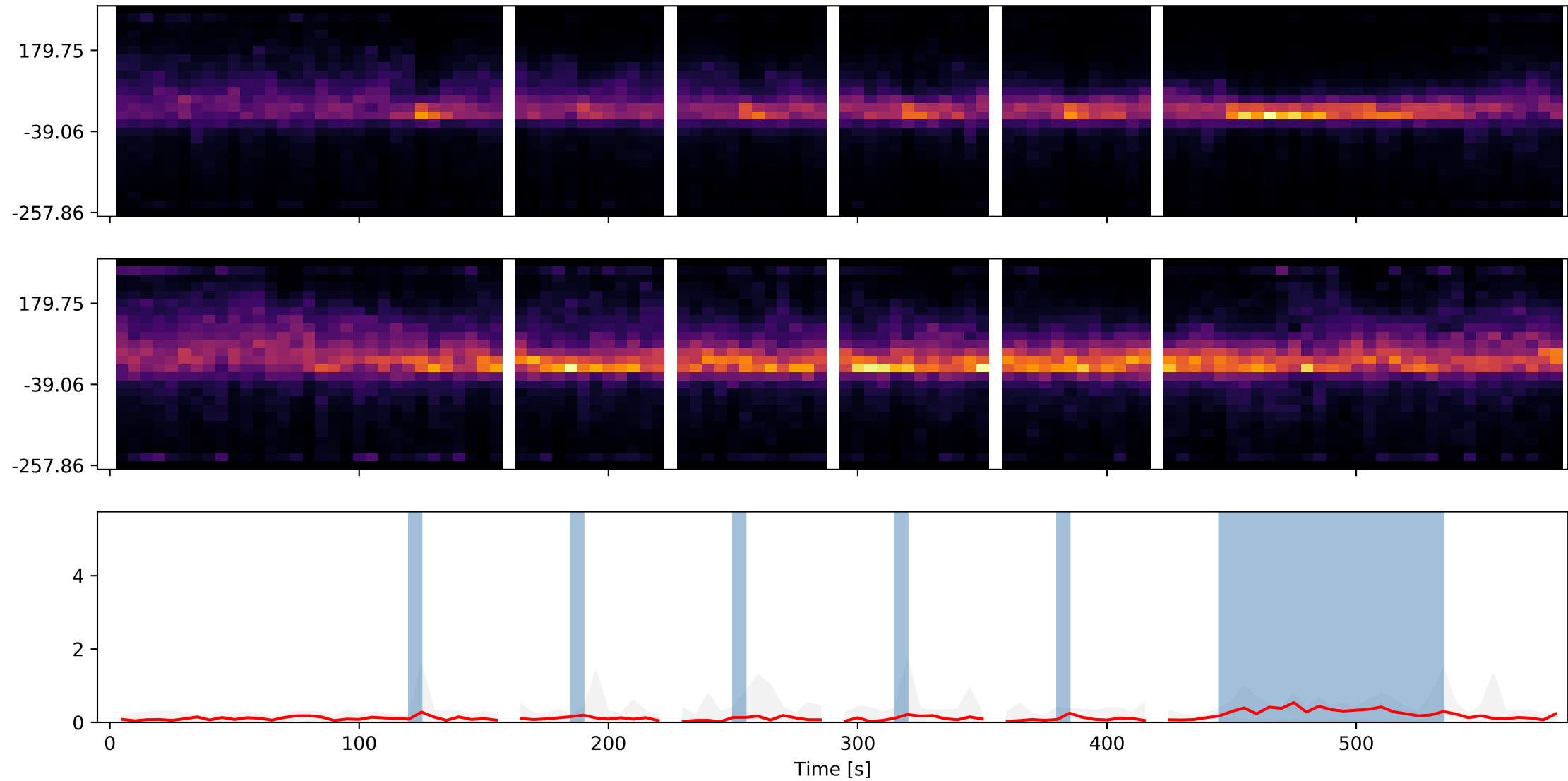
d_eigen_projection_6



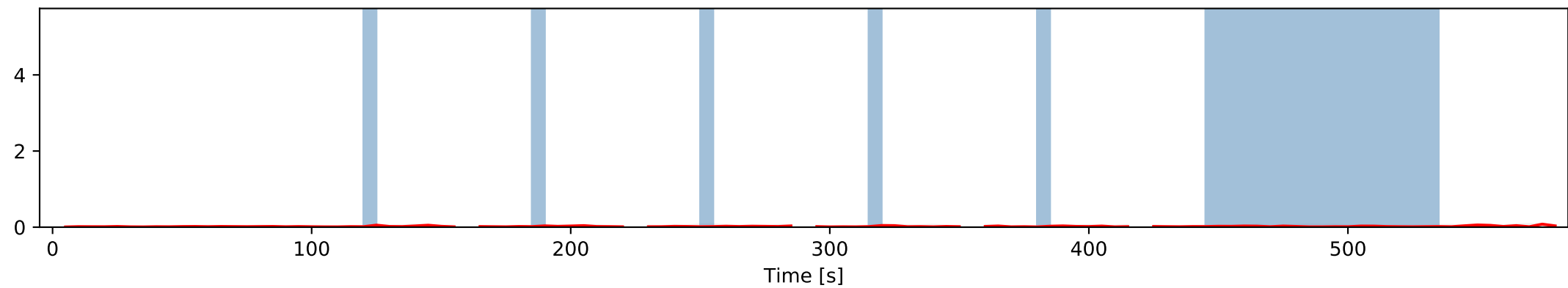
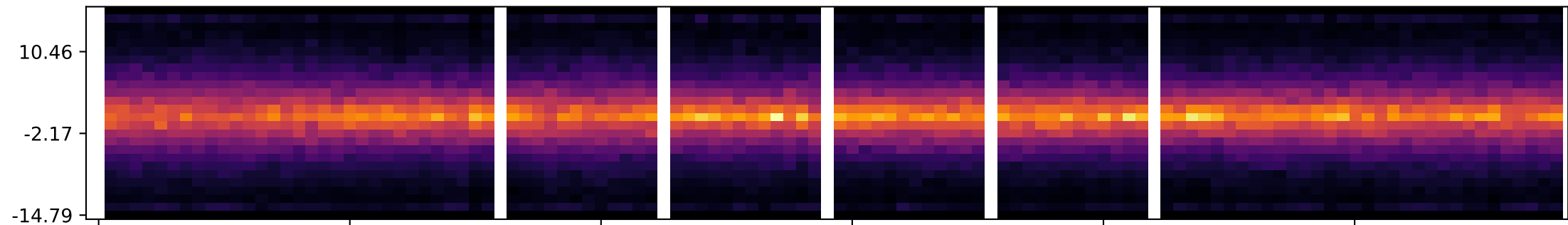
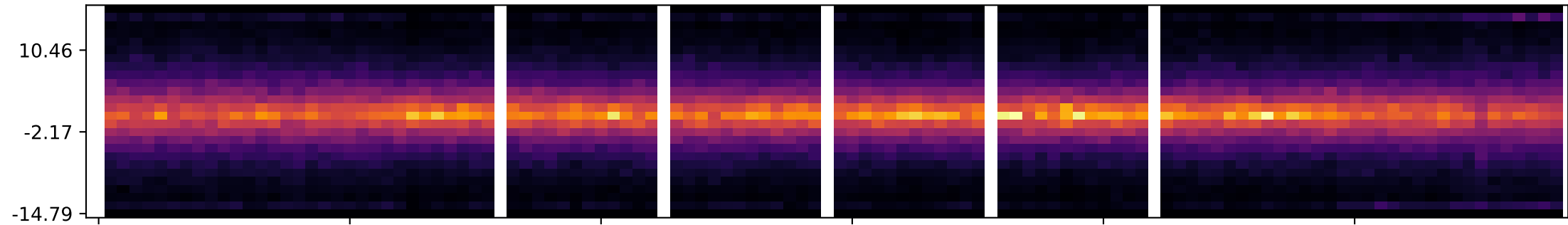
d_area



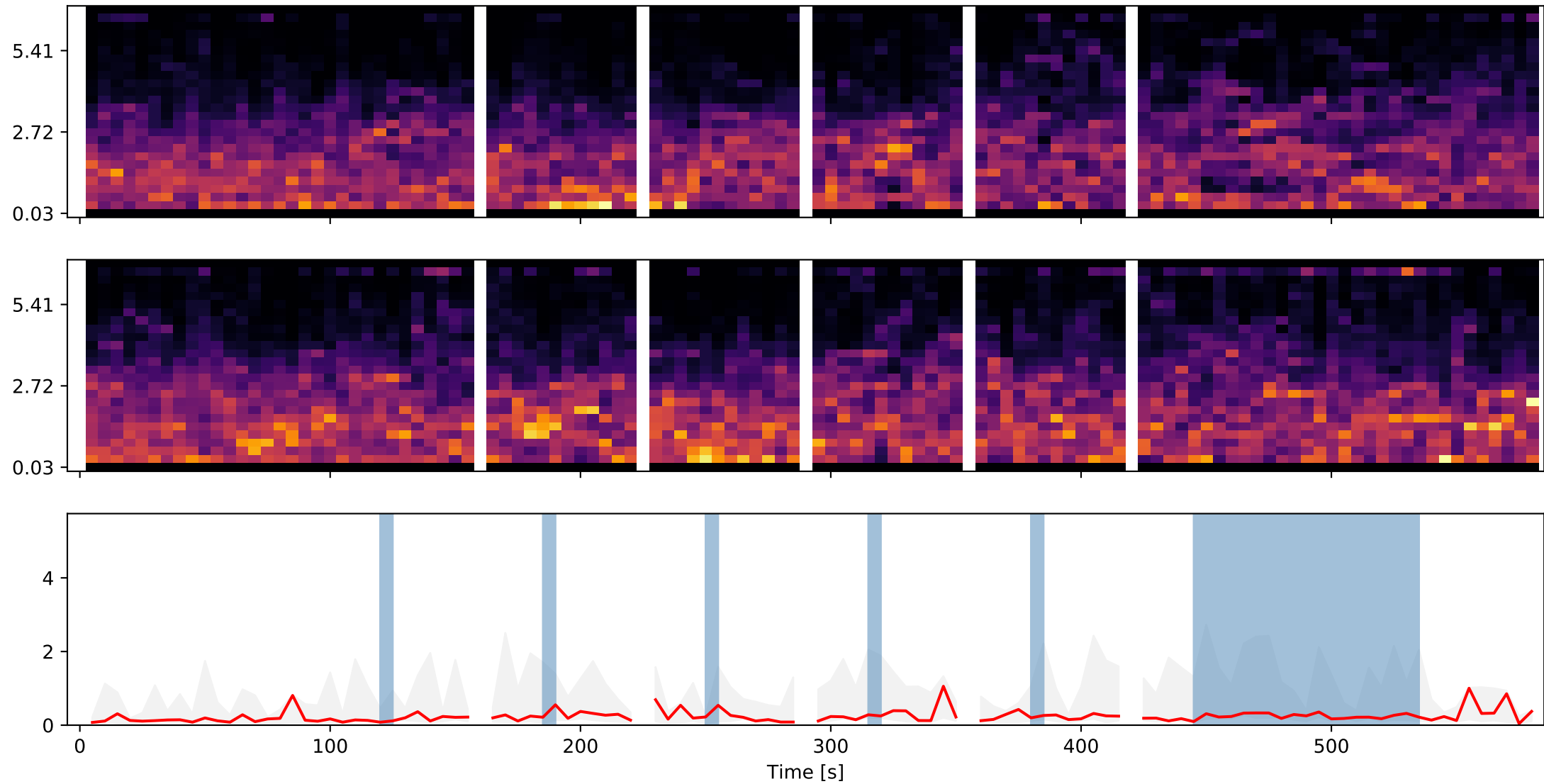
speed_head_base



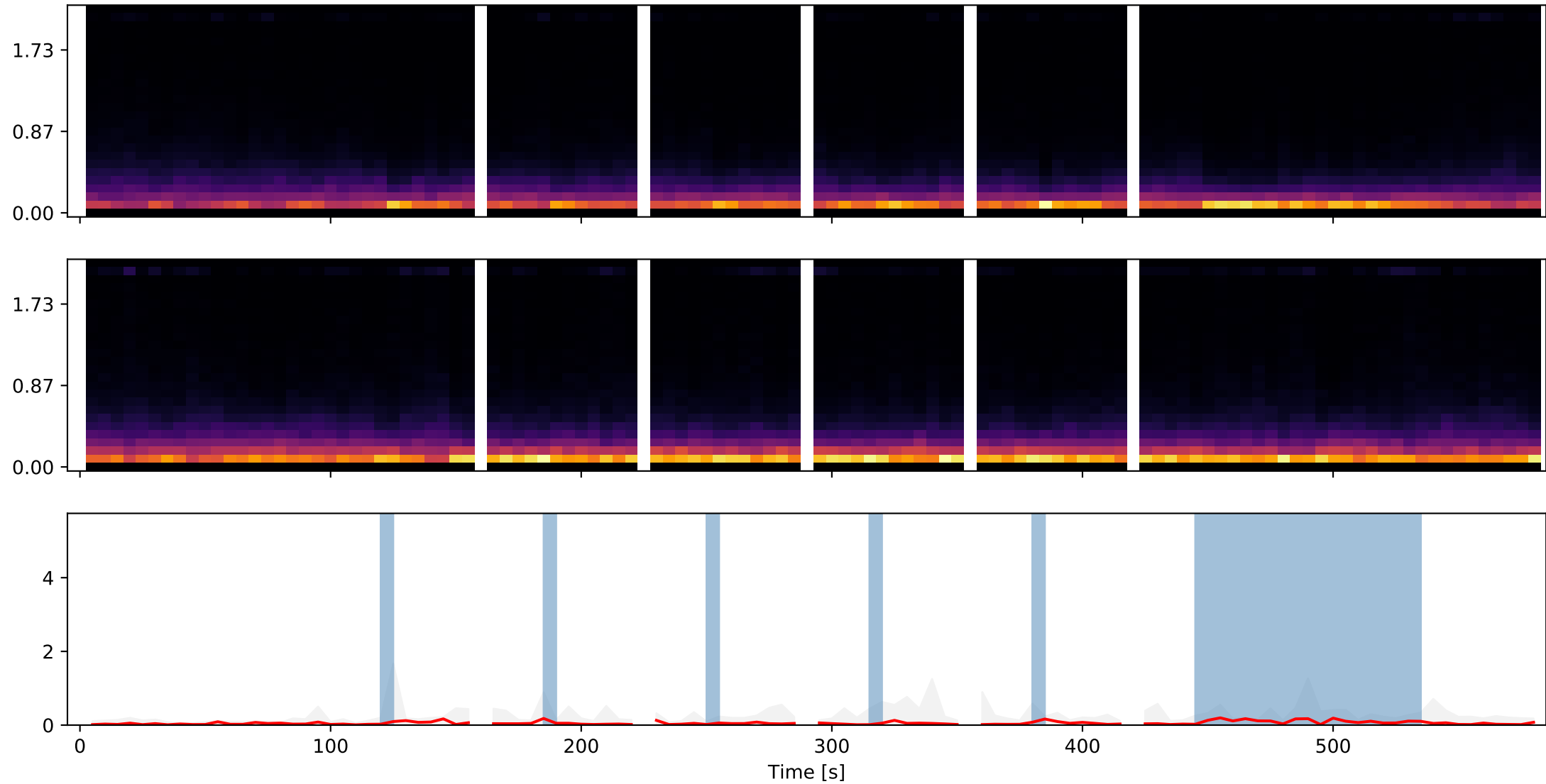
d_width_midbody



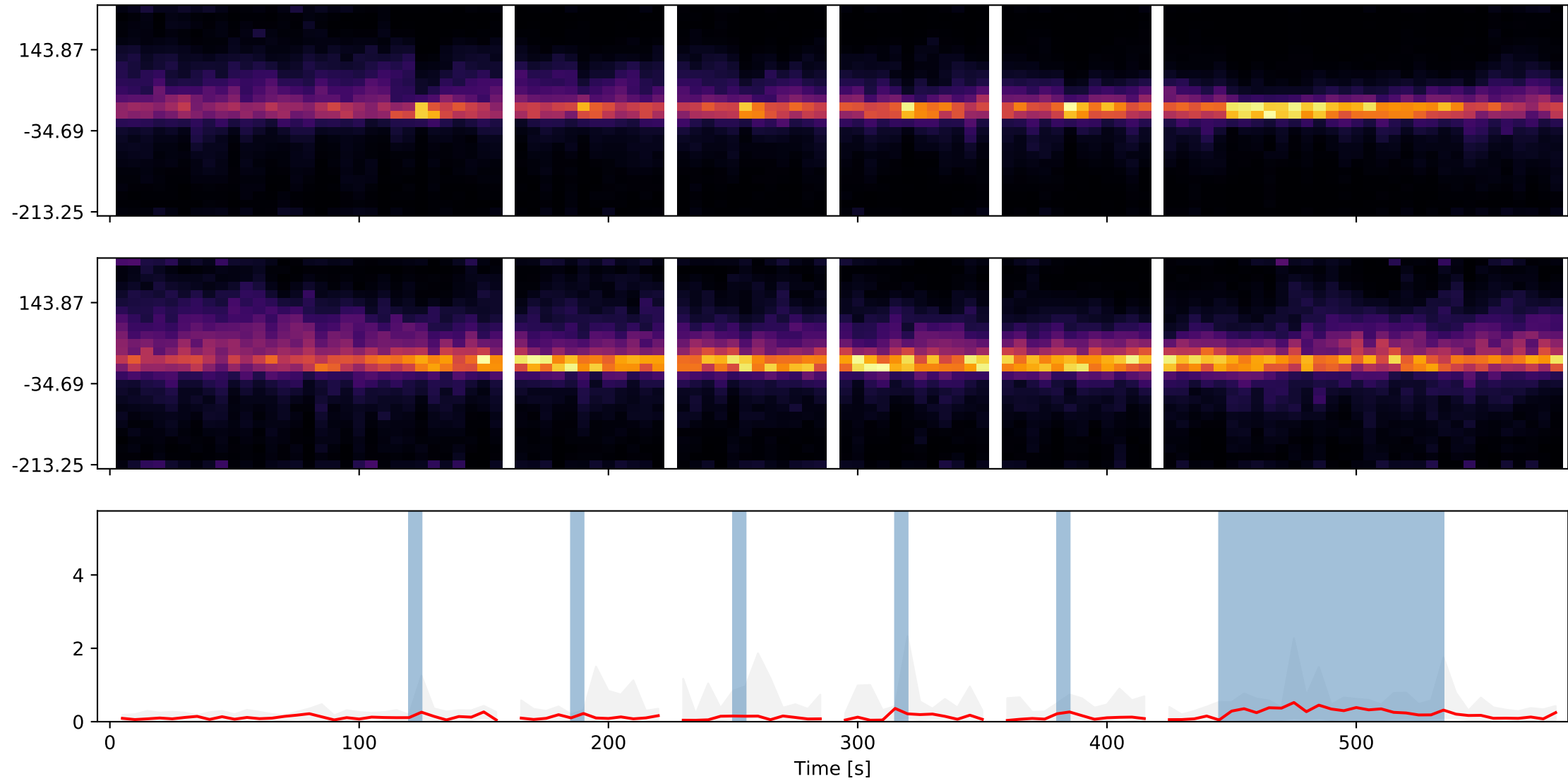
eigen_projection_1



d_relative_to_body_angular_velocity_tail_tip



speed



speed_midbody

