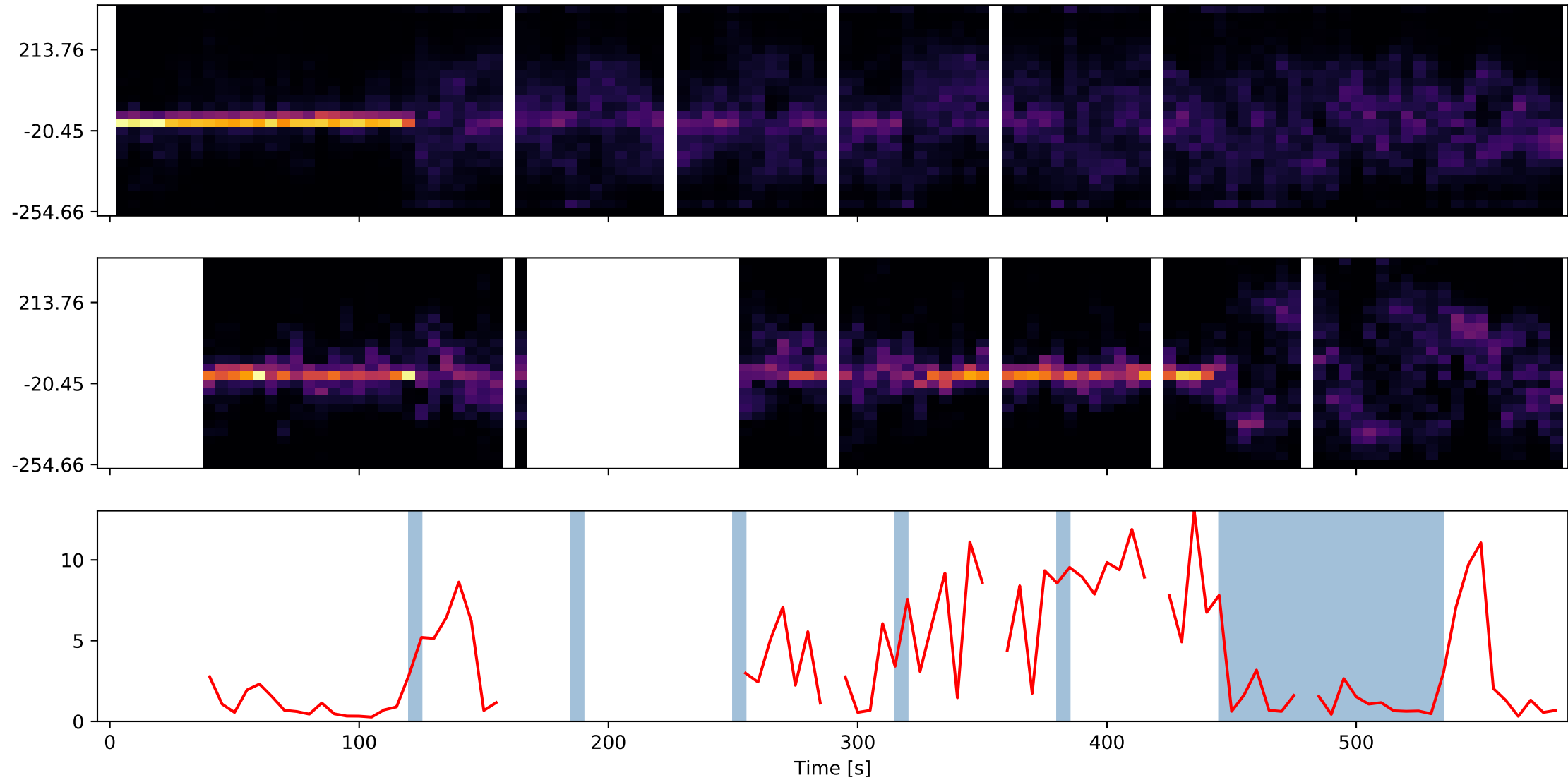
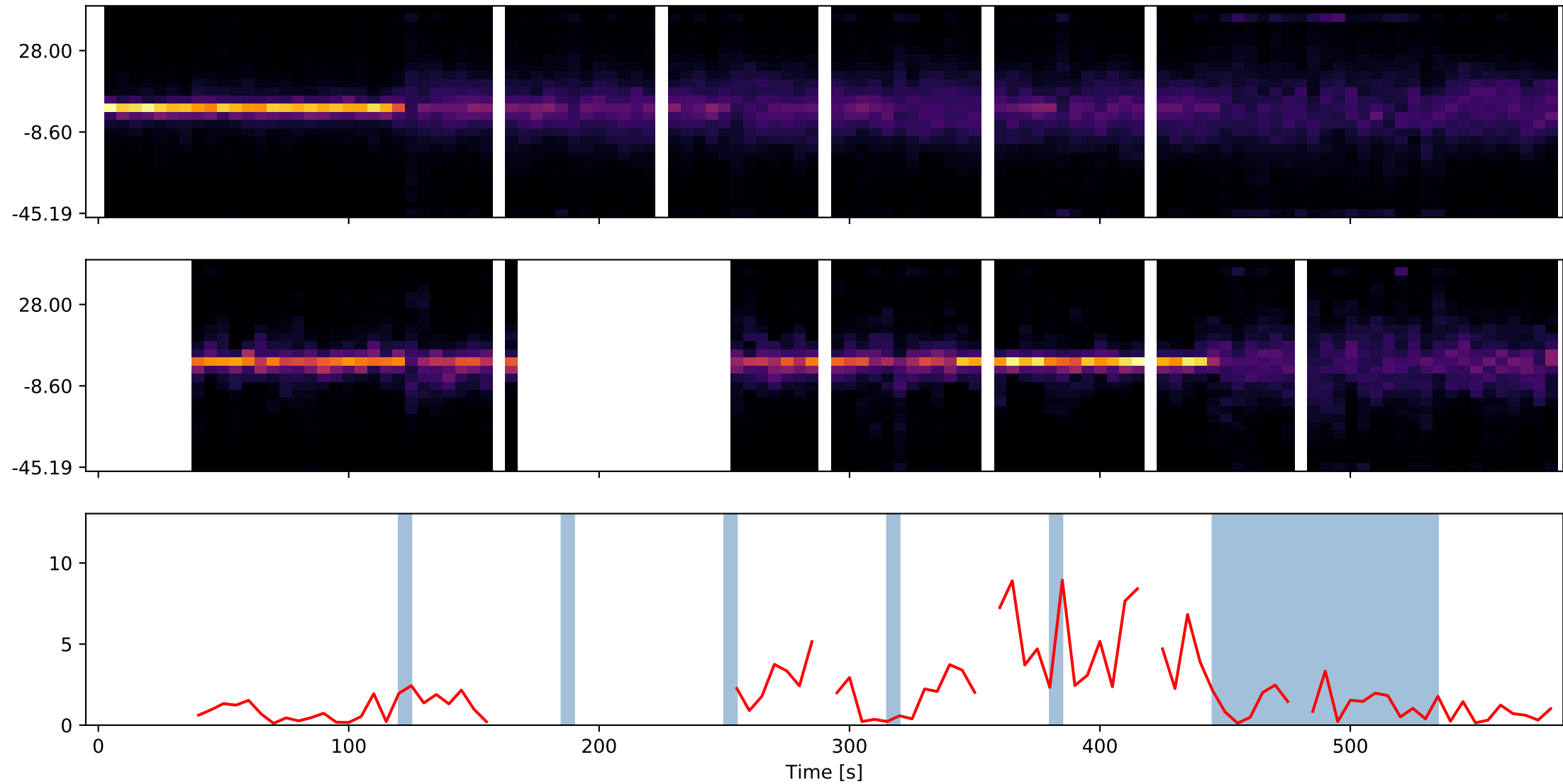


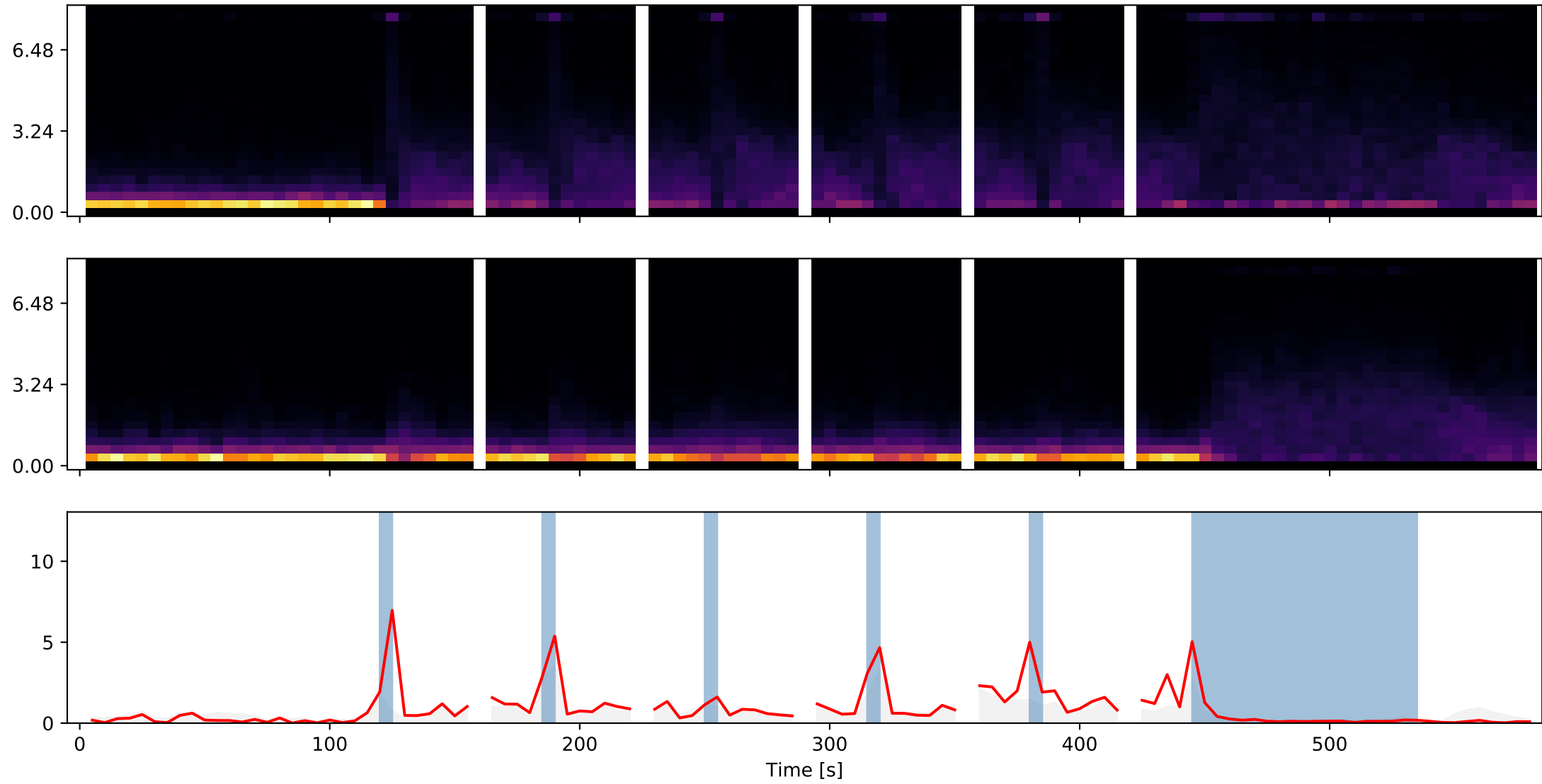
d\_dist\_from\_food\_edge



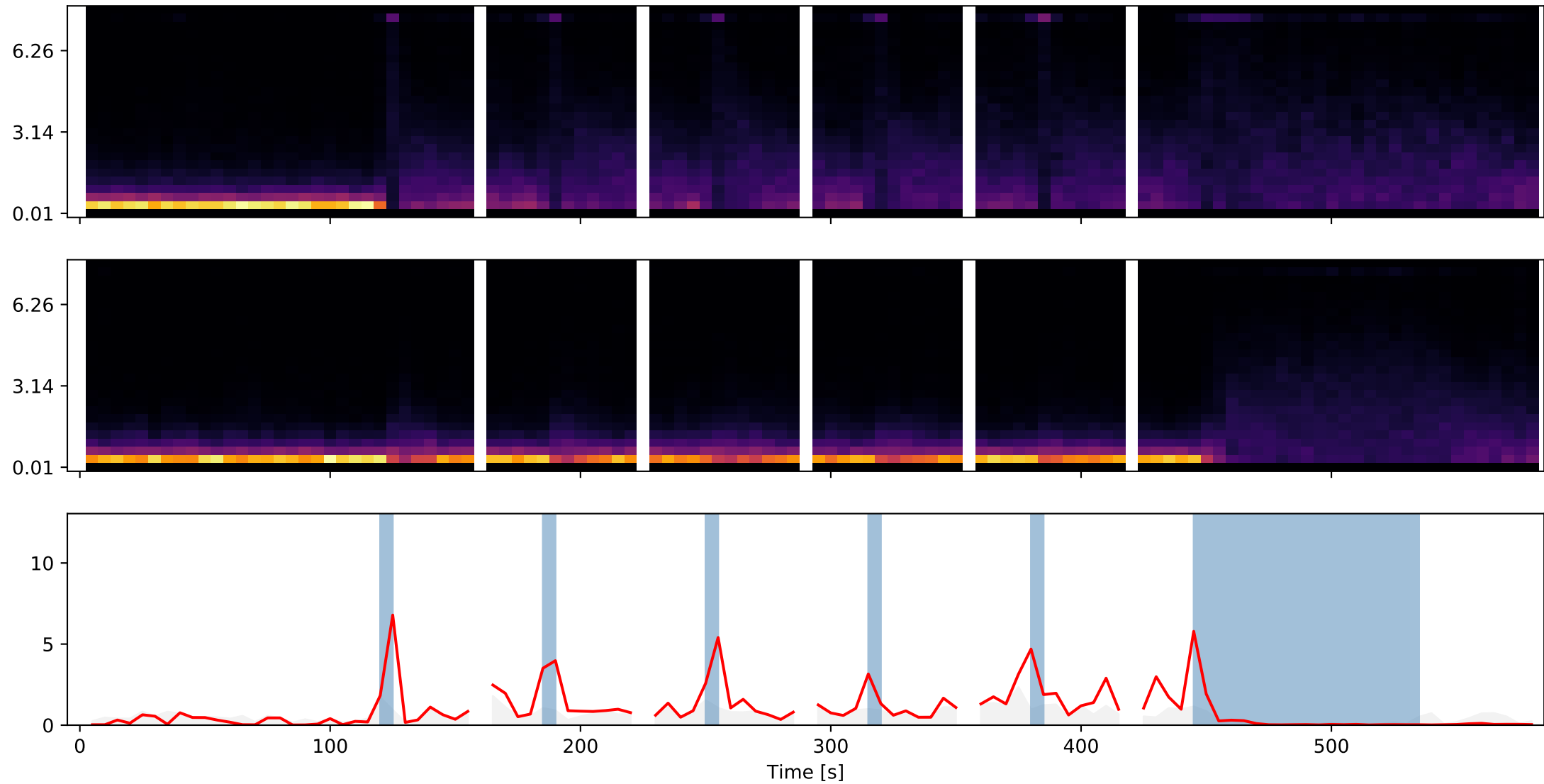
d\_orientation\_food\_edge



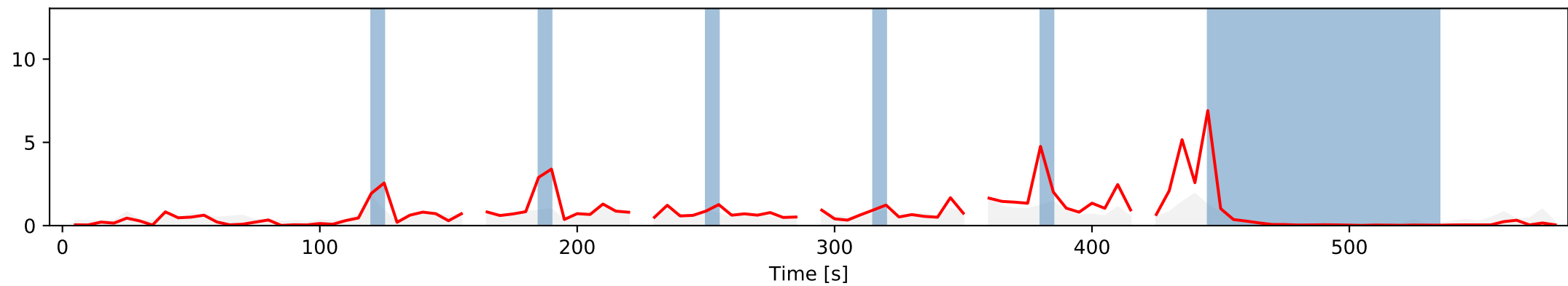
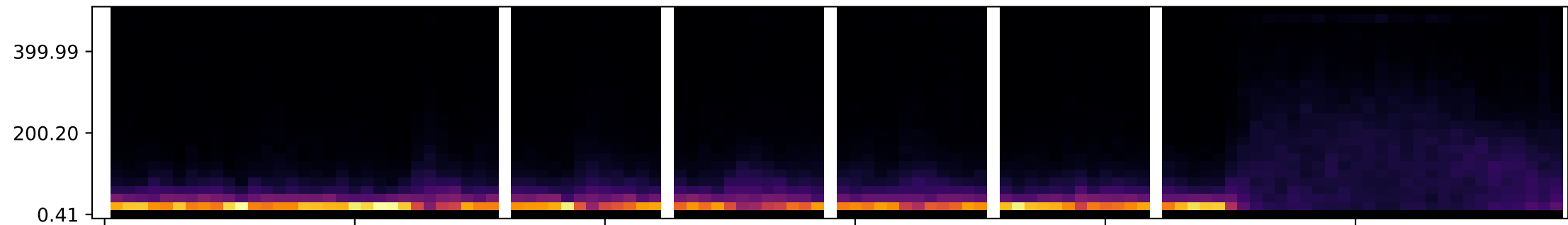
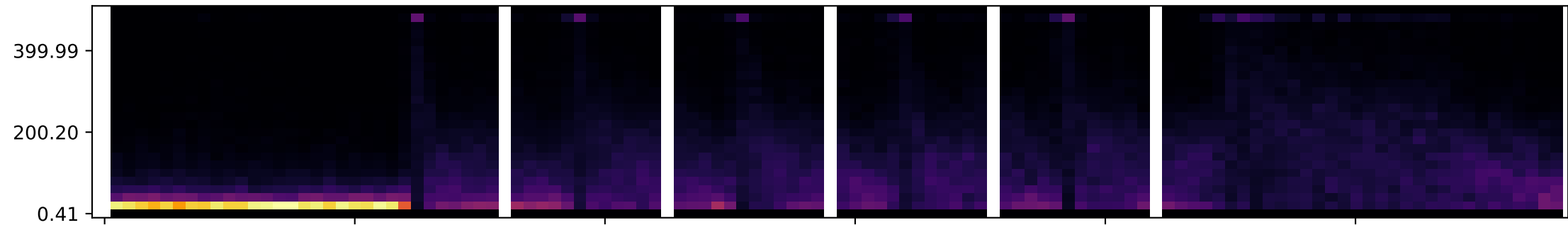
d\_angular\_velocity\_hips



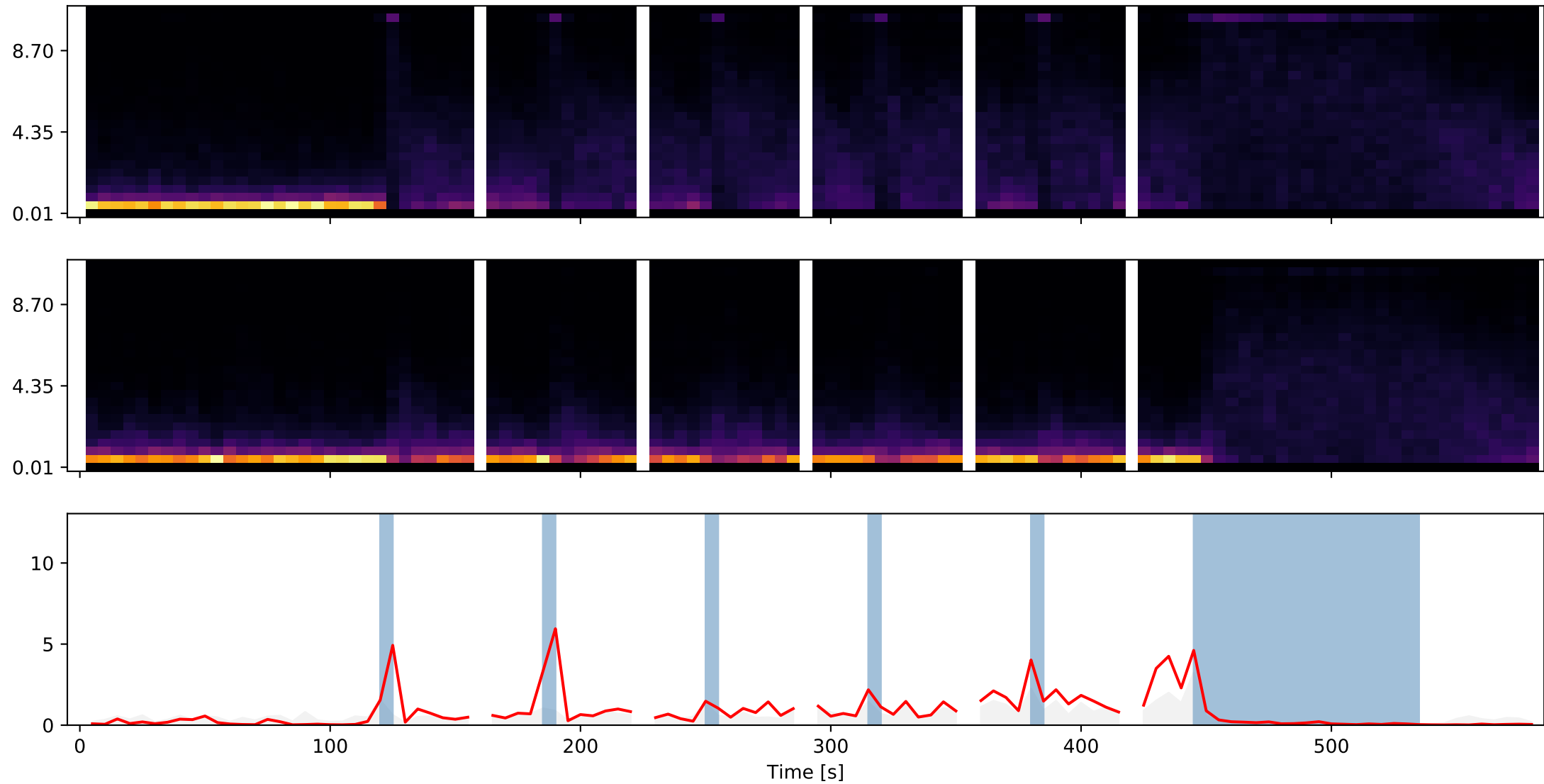
d\_relative\_to\_hips\_angular\_velocity\_tail\_tip



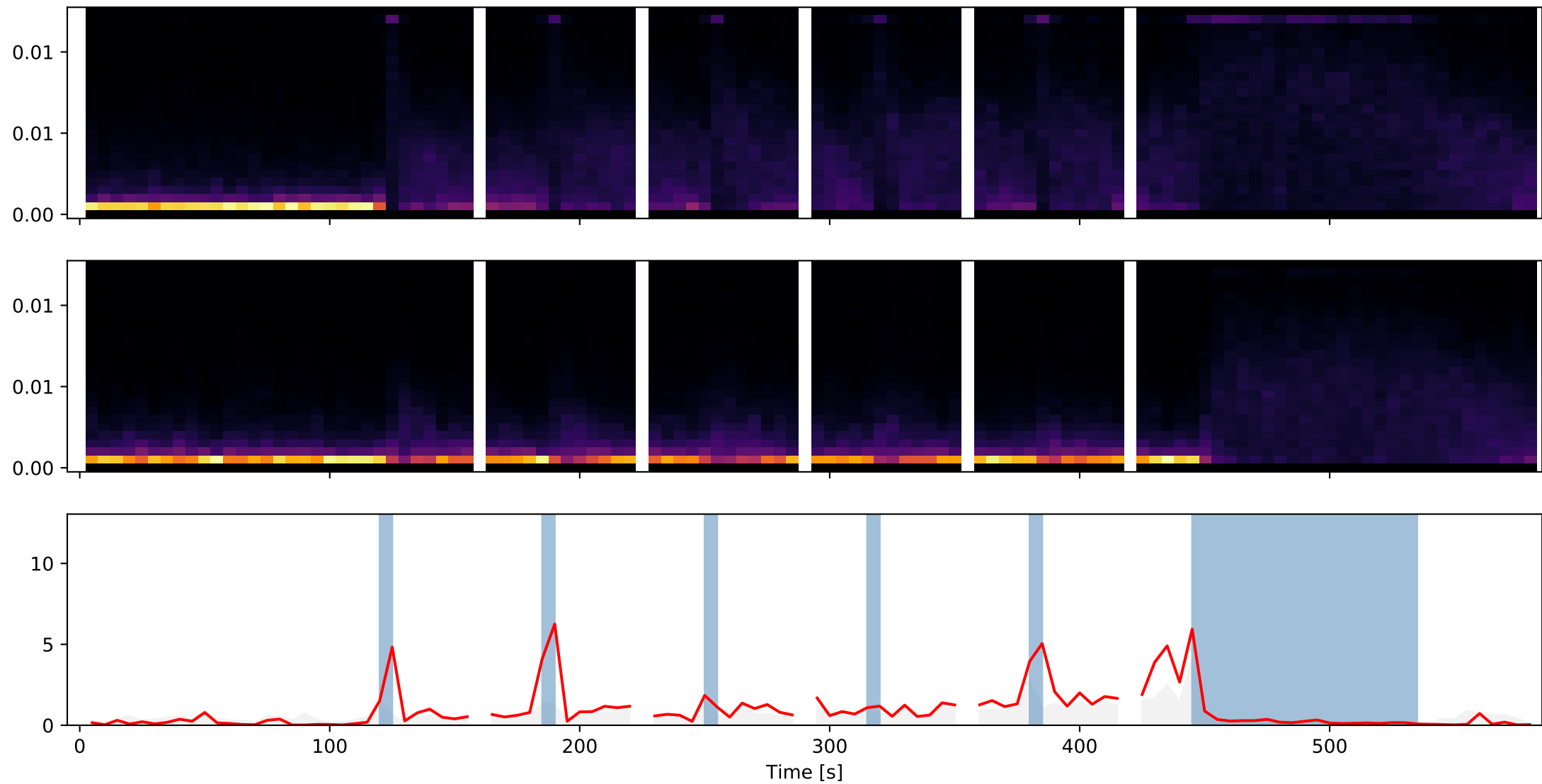
d\_relative\_to\_body\_speed\_midbody



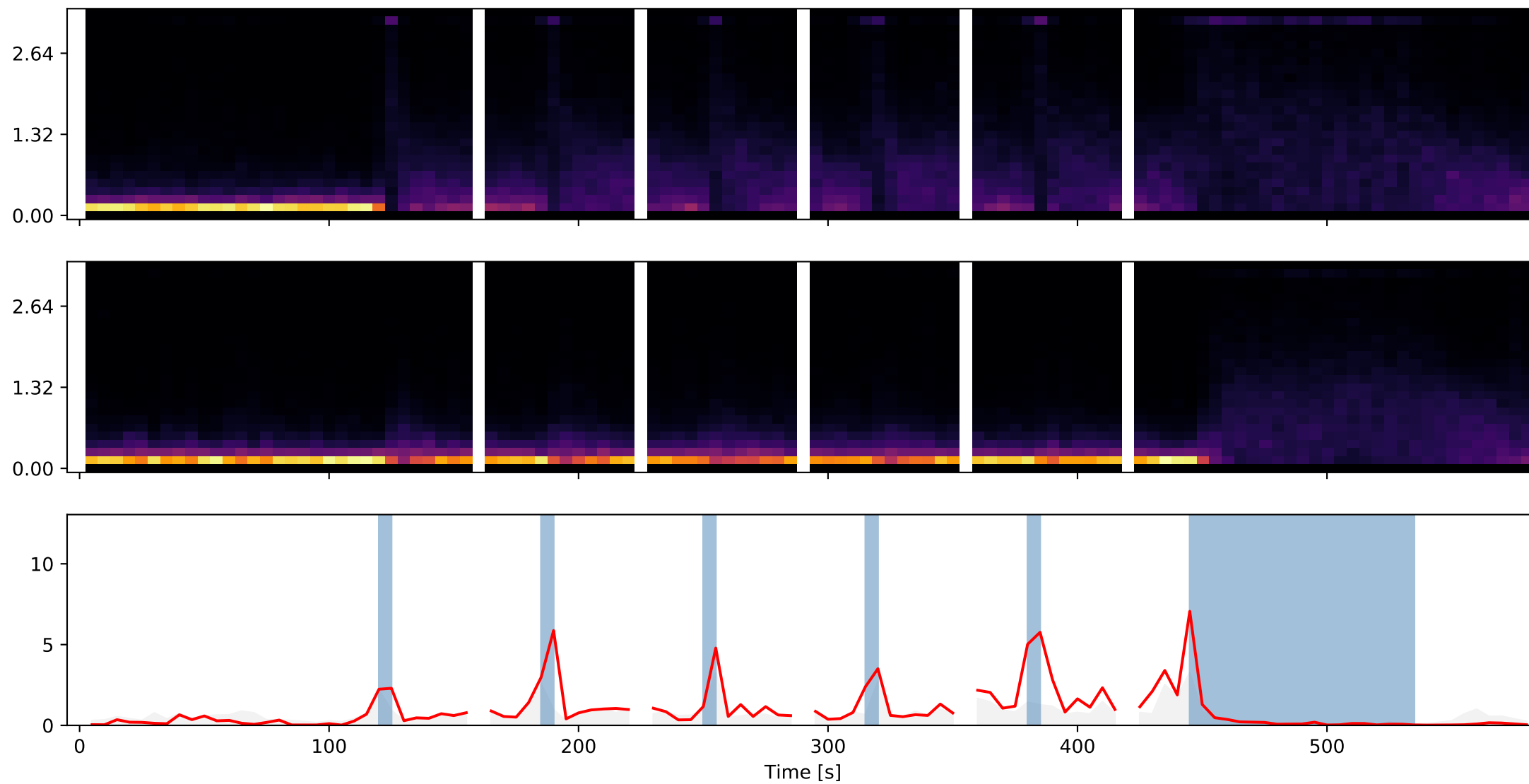
d\_eigen\_projection\_3



d\_curvature\_mean\_midbody

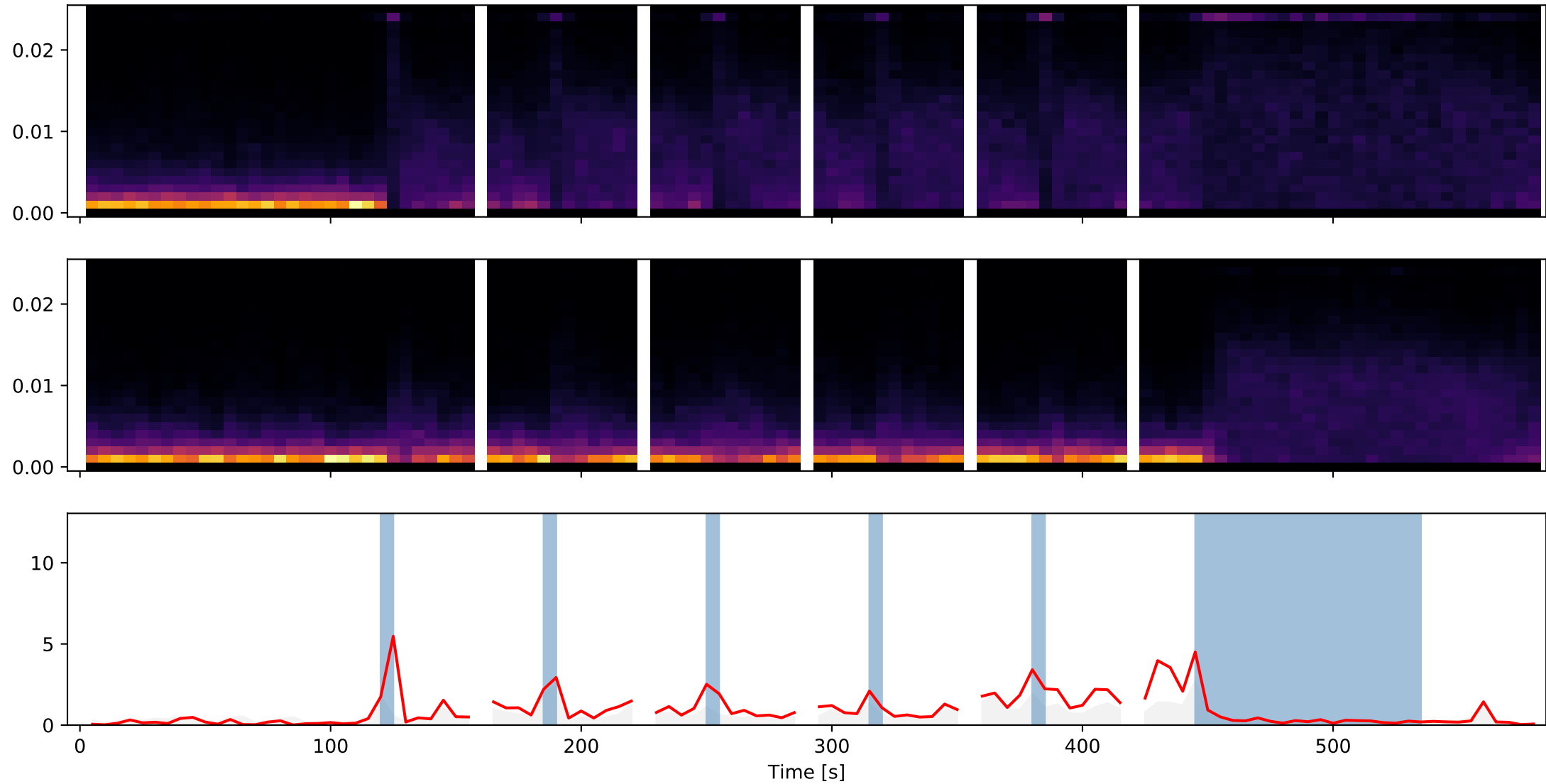


d\_relative\_to\_body\_angular\_velocity\_neck

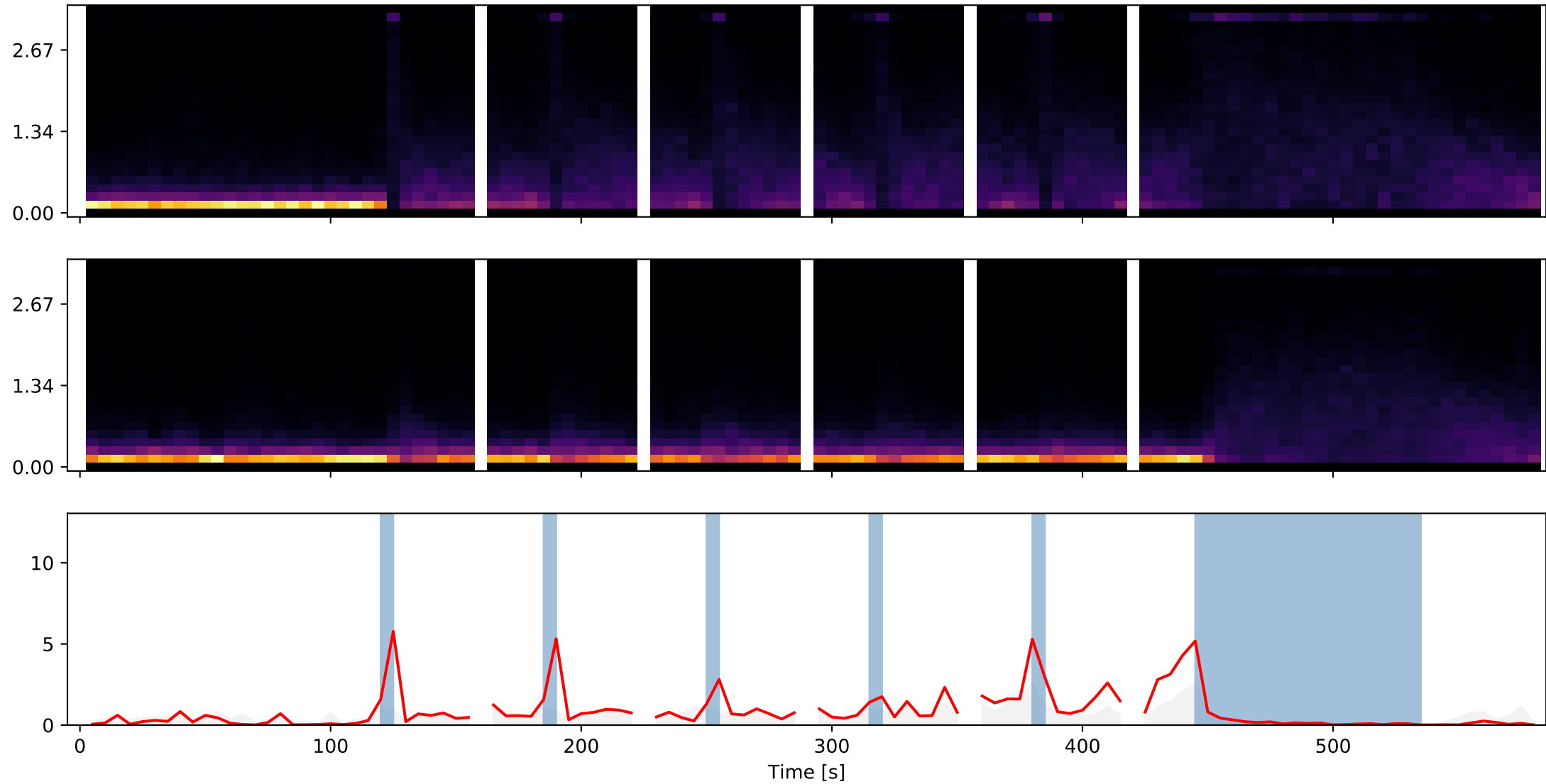




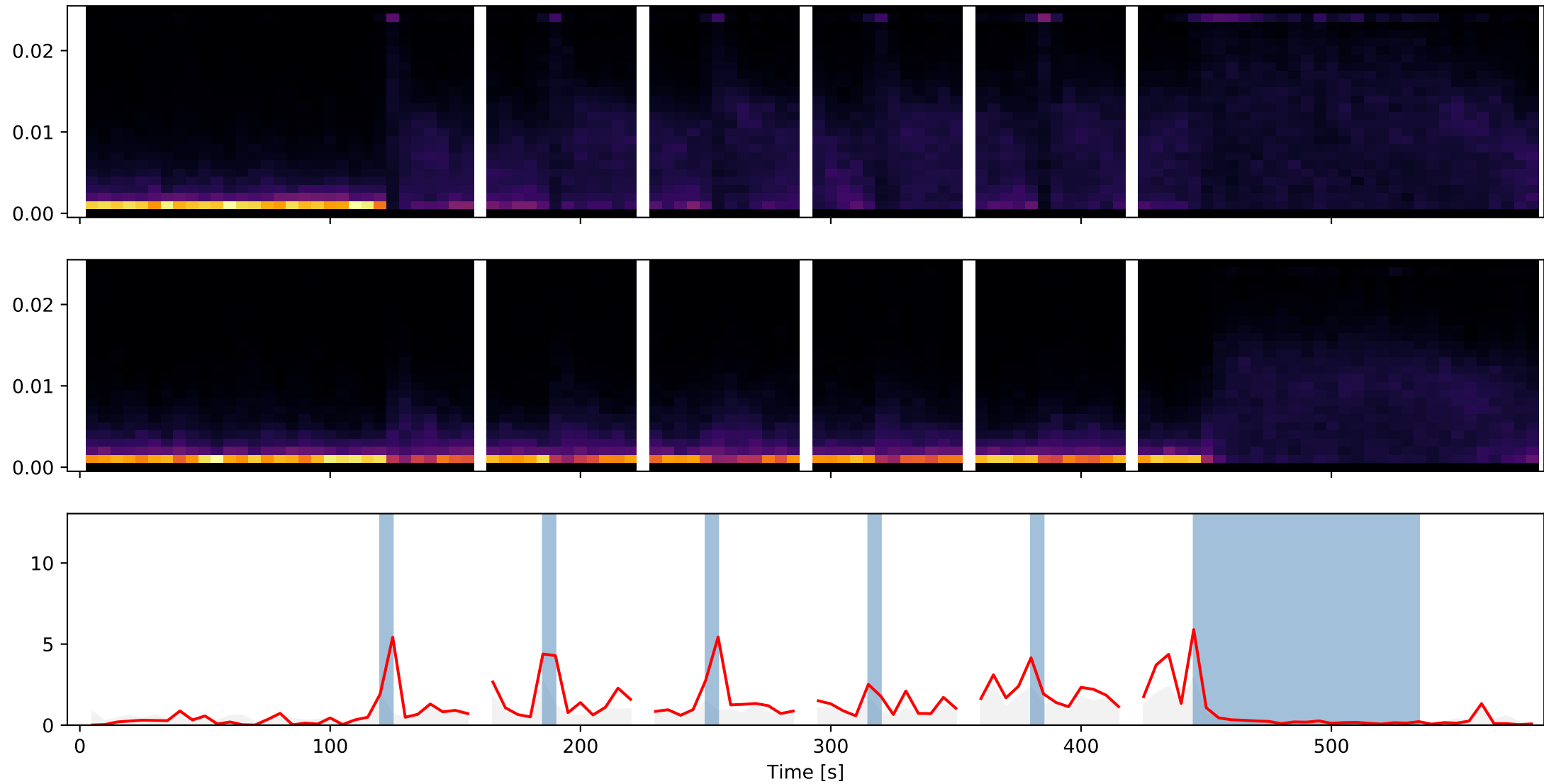
d\_curvature\_hips



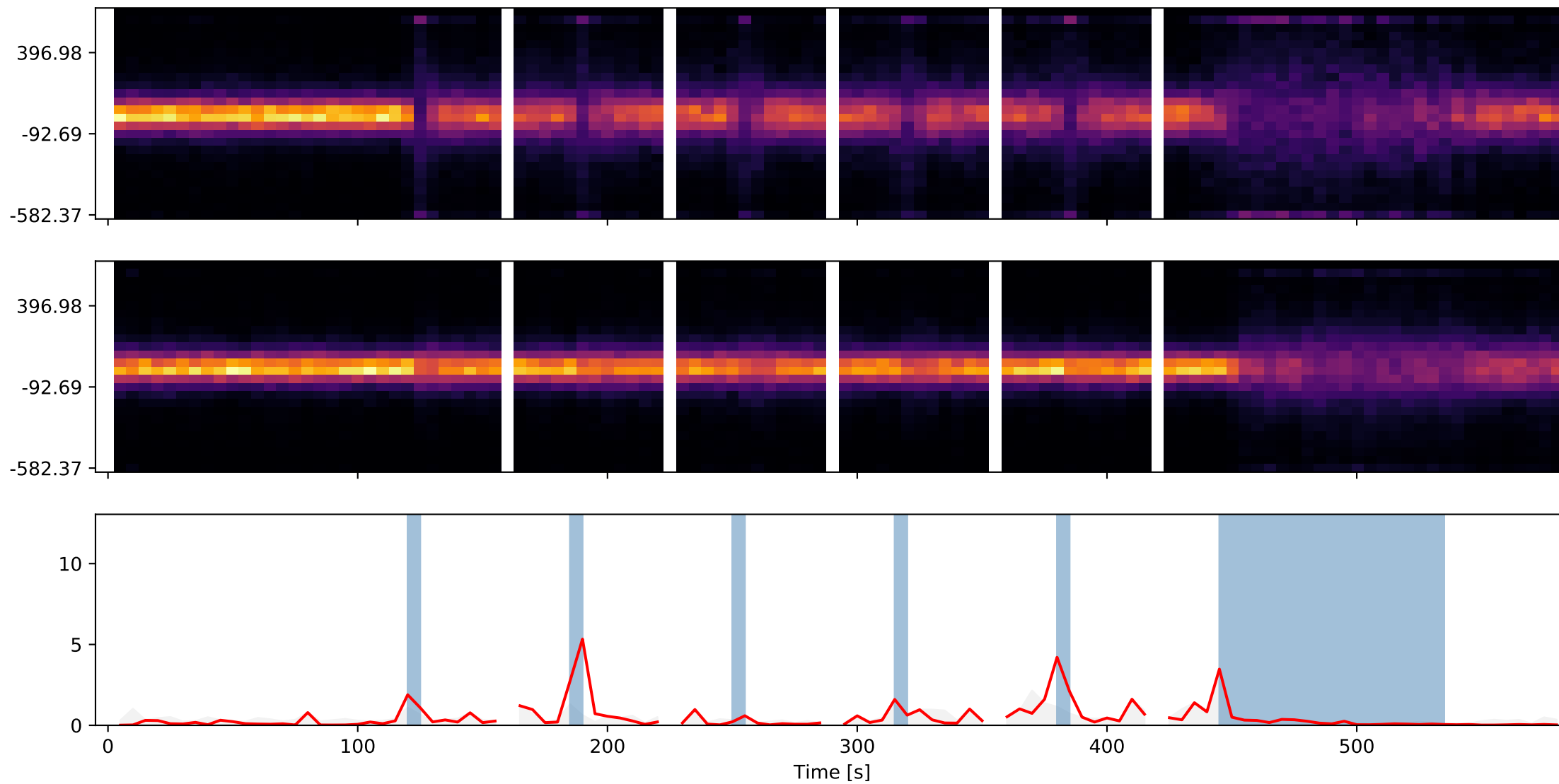
d\_relative\_to\_body\_angular\_velocity\_hips



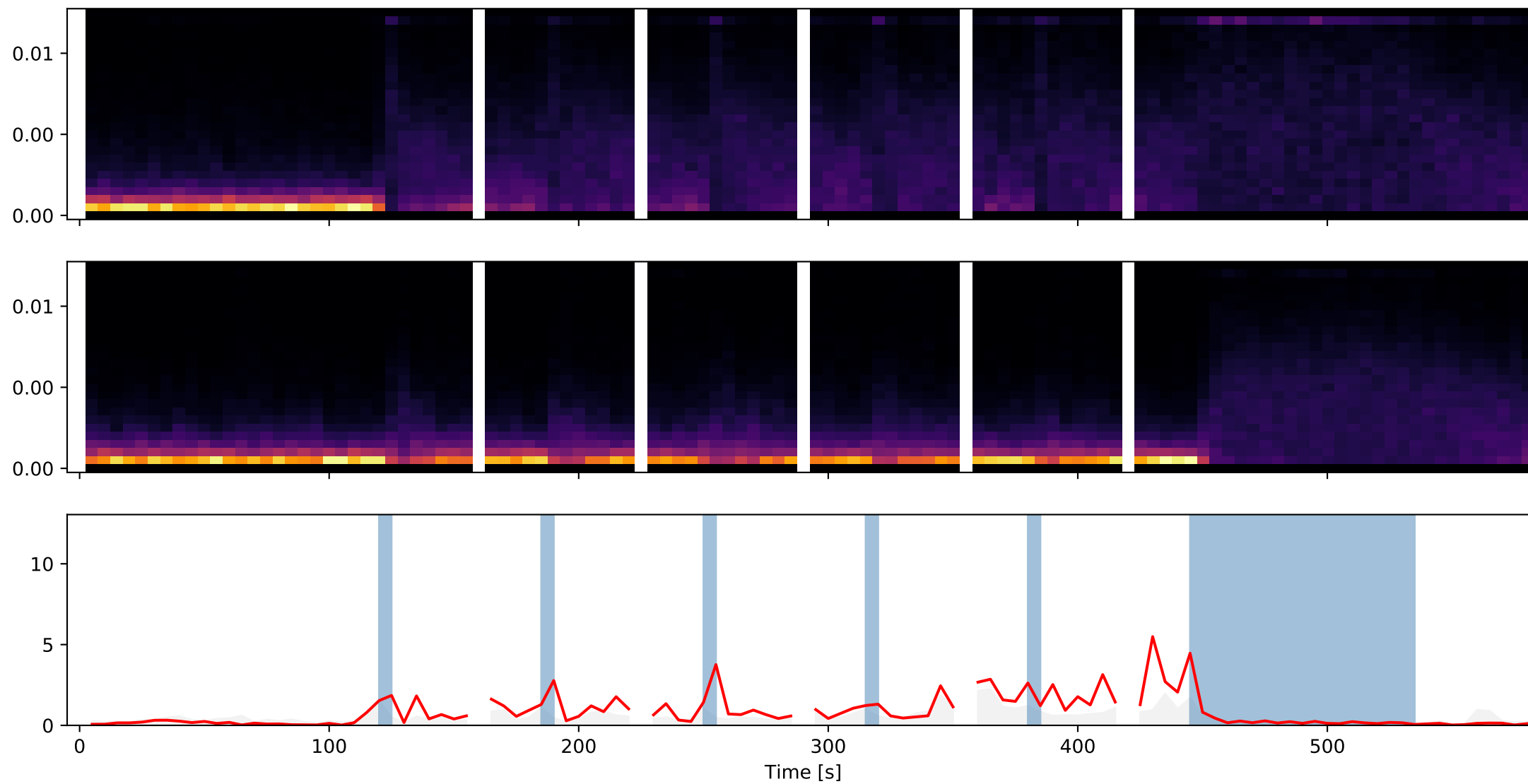
d\_curvature\_mean\_hips



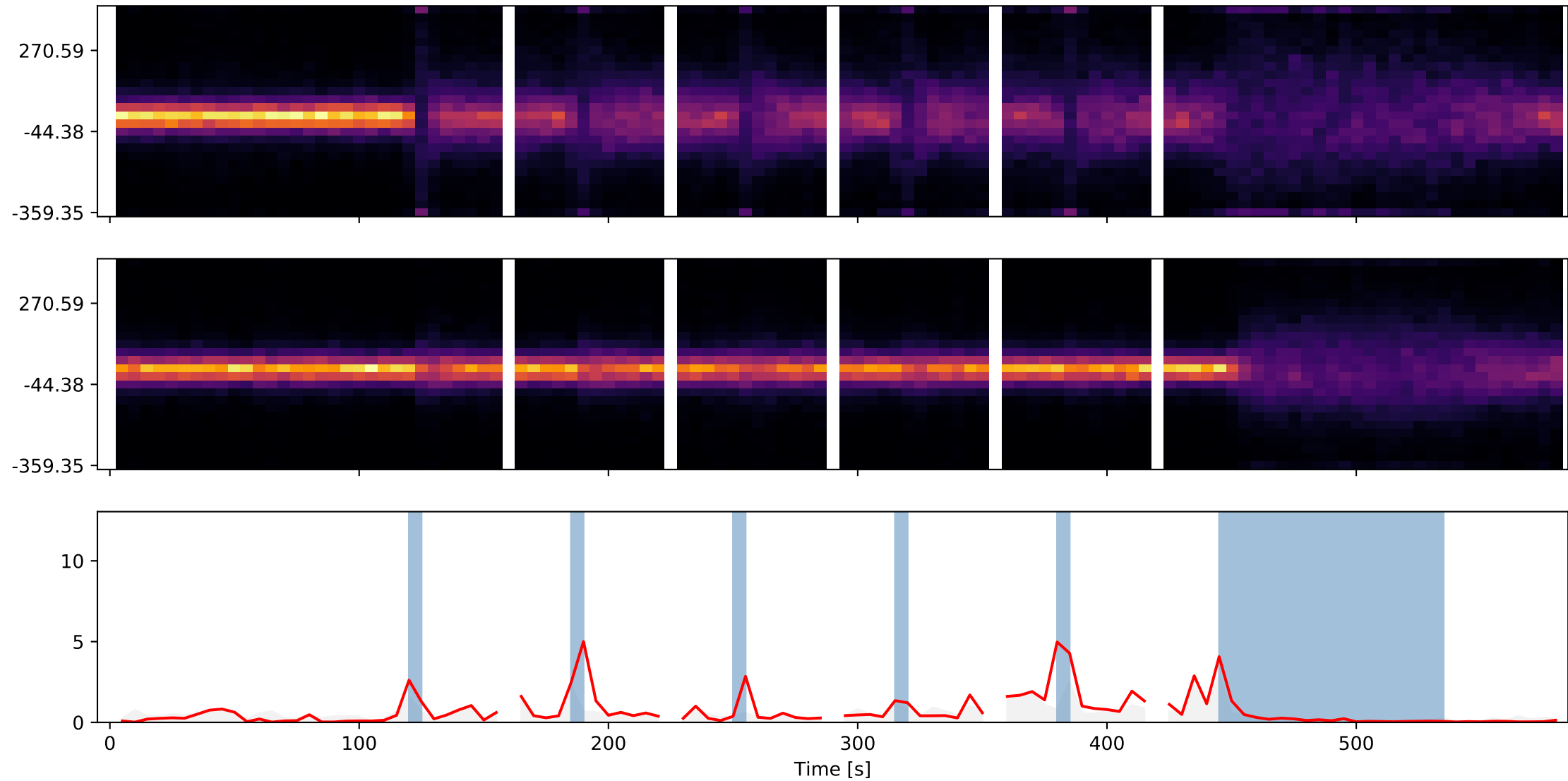
d\_relative\_to\_body\_radial\_velocity\_tail\_tip



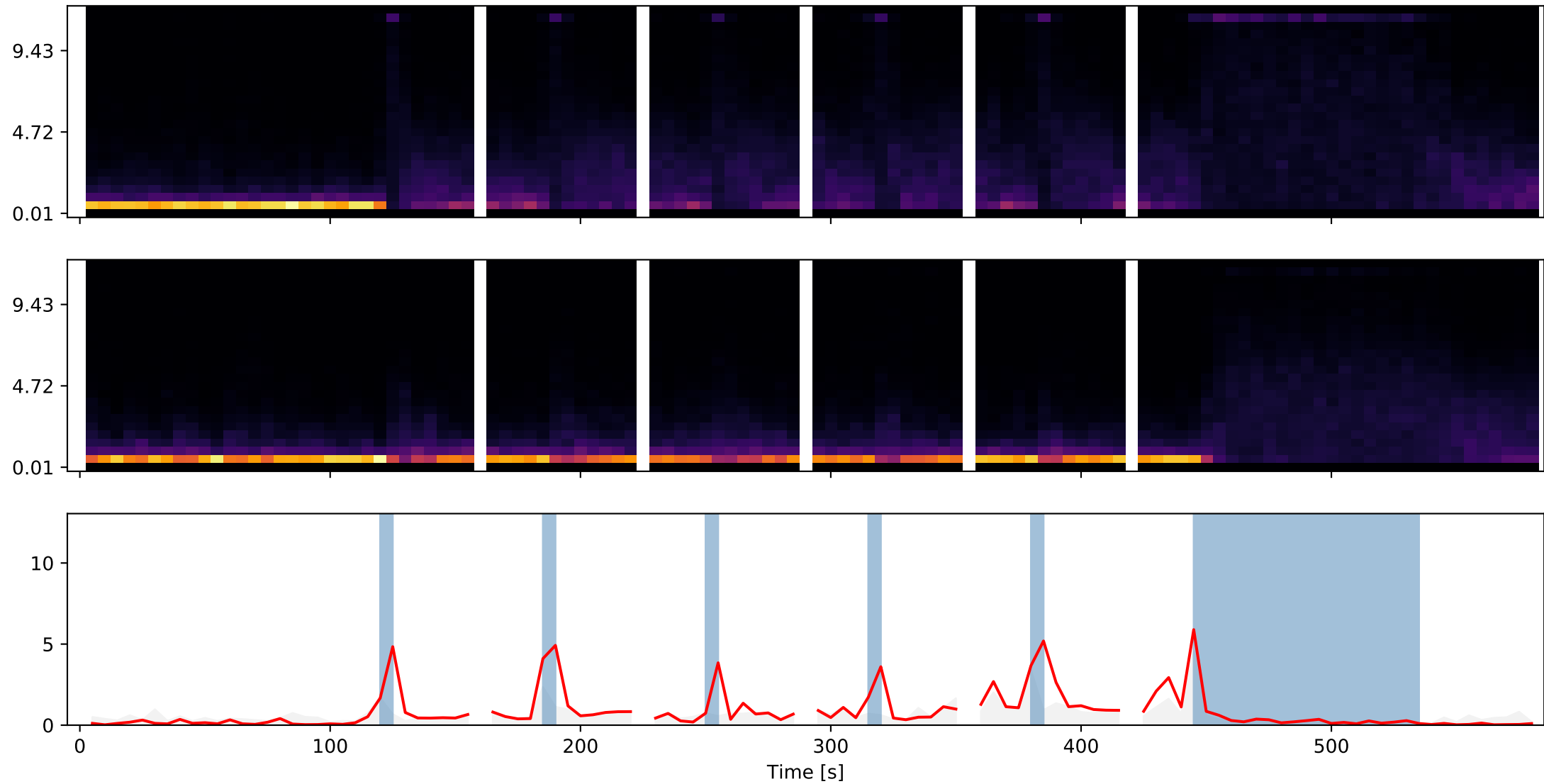
d\_curvature\_std\_midbody



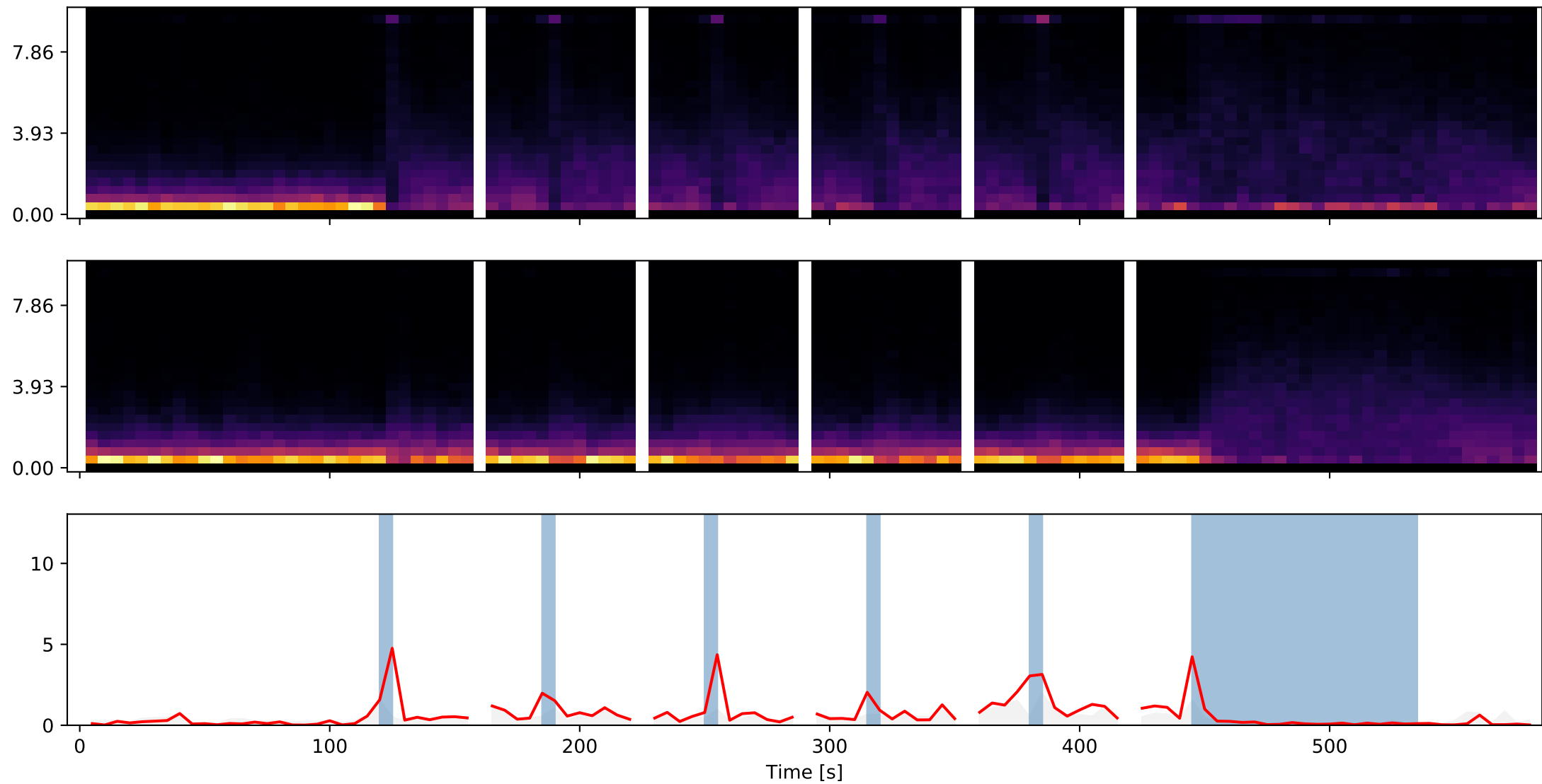
d\_relative\_to\_hips\_radial\_velocity\_tail\_tip



d\_eigen\_projection\_2

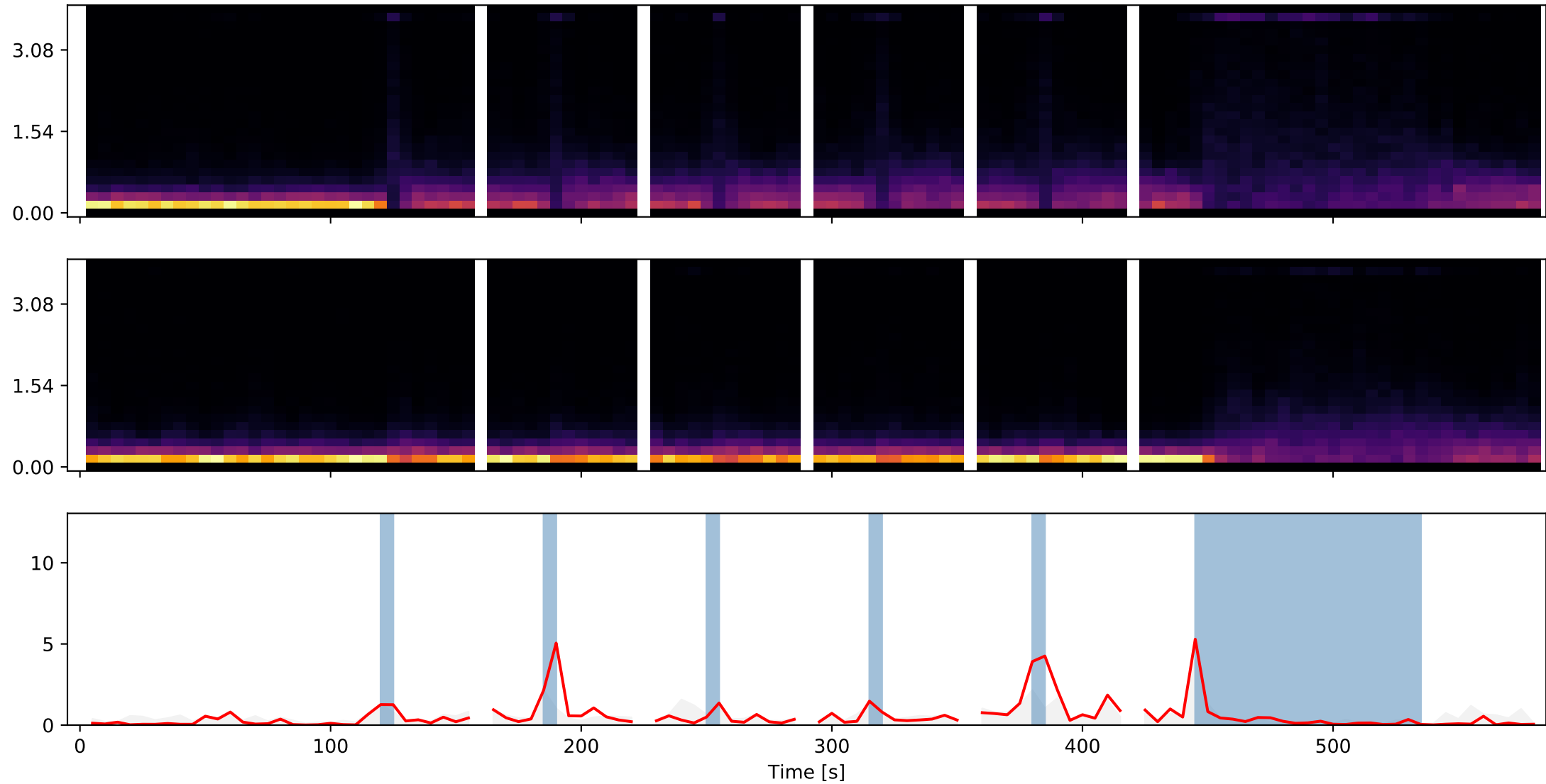


d\_angular\_velocity\_tail\_base

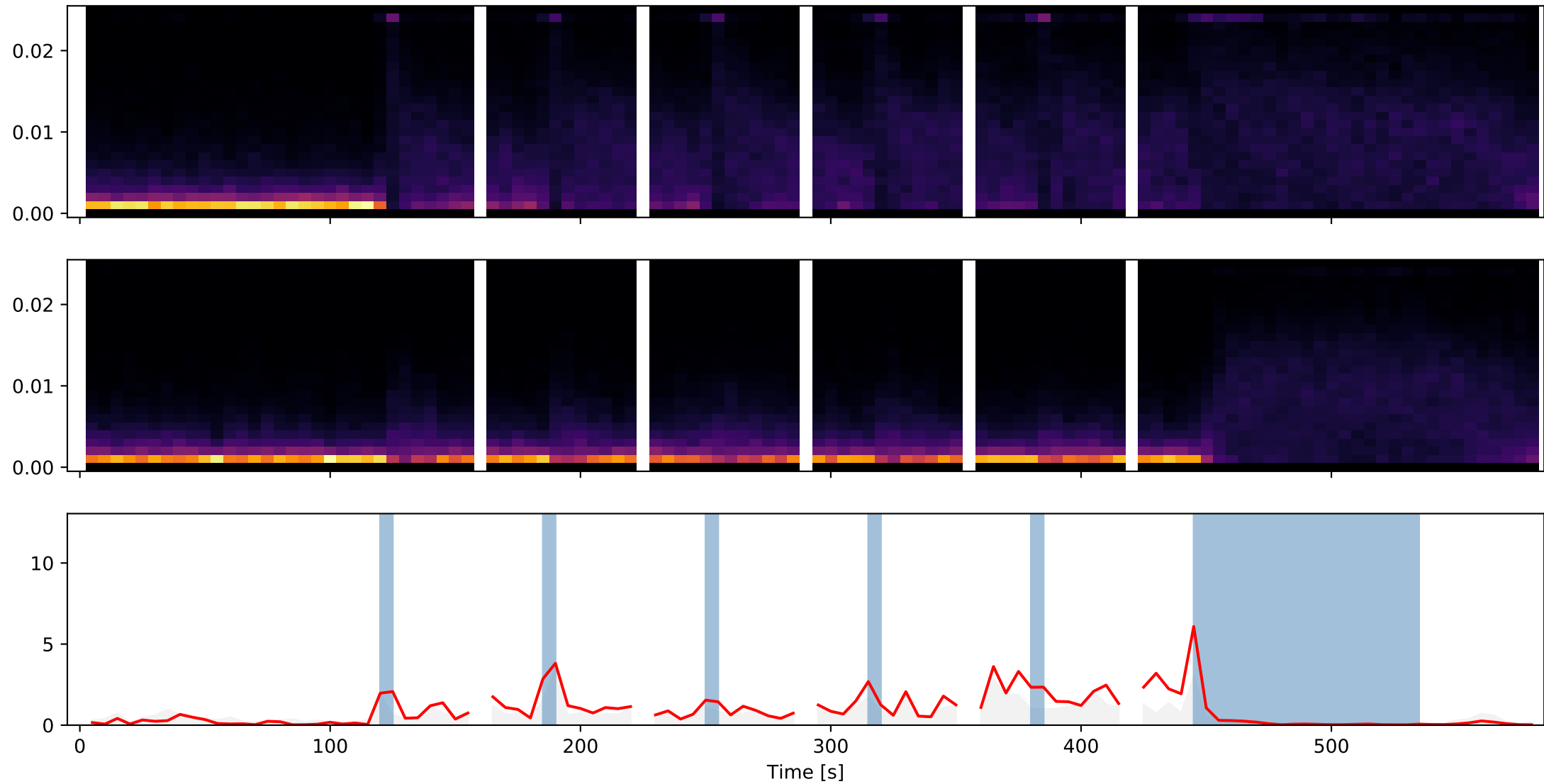




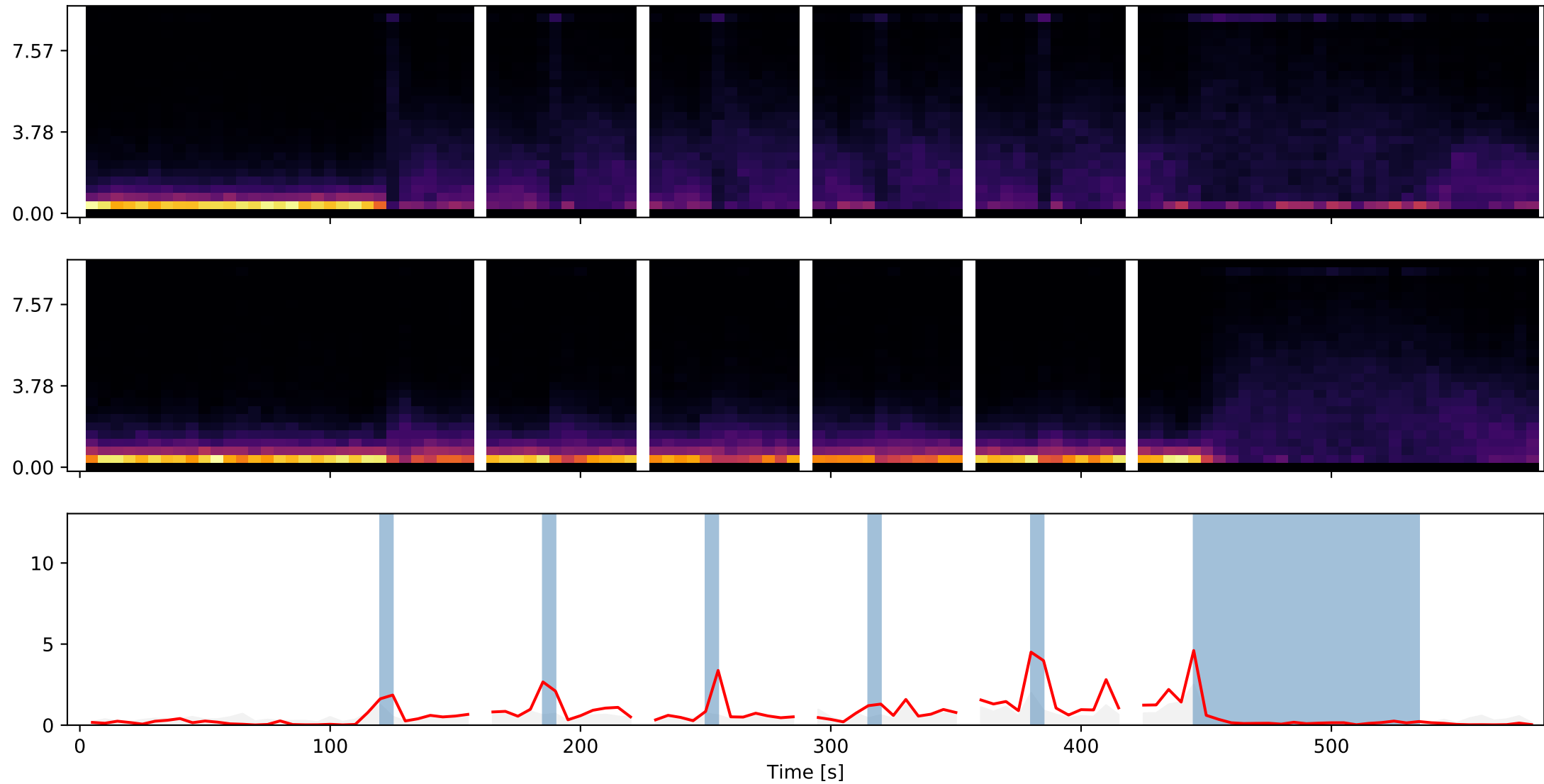
d\_relative\_to\_body\_angular\_velocity\_tail\_tip



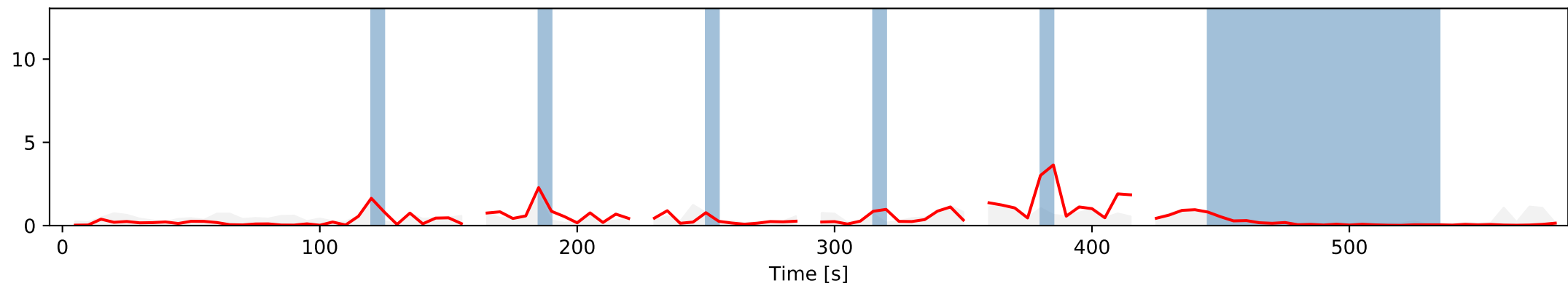
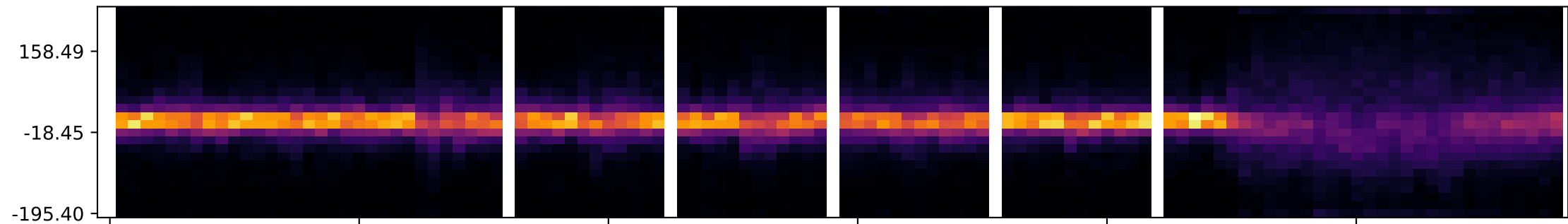
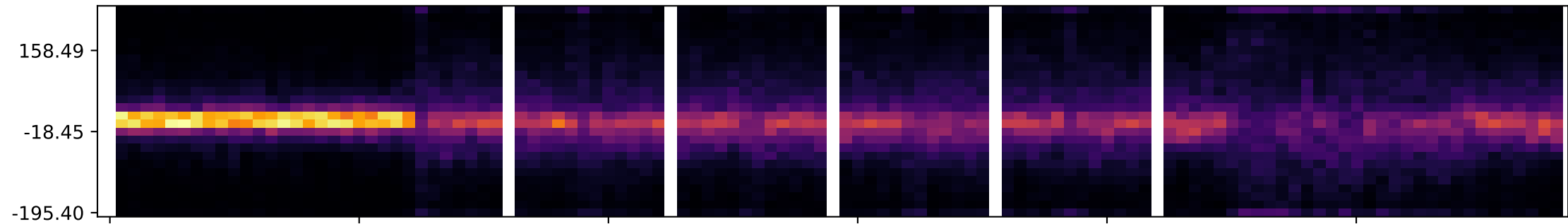
d\_curvature\_mean\_tail



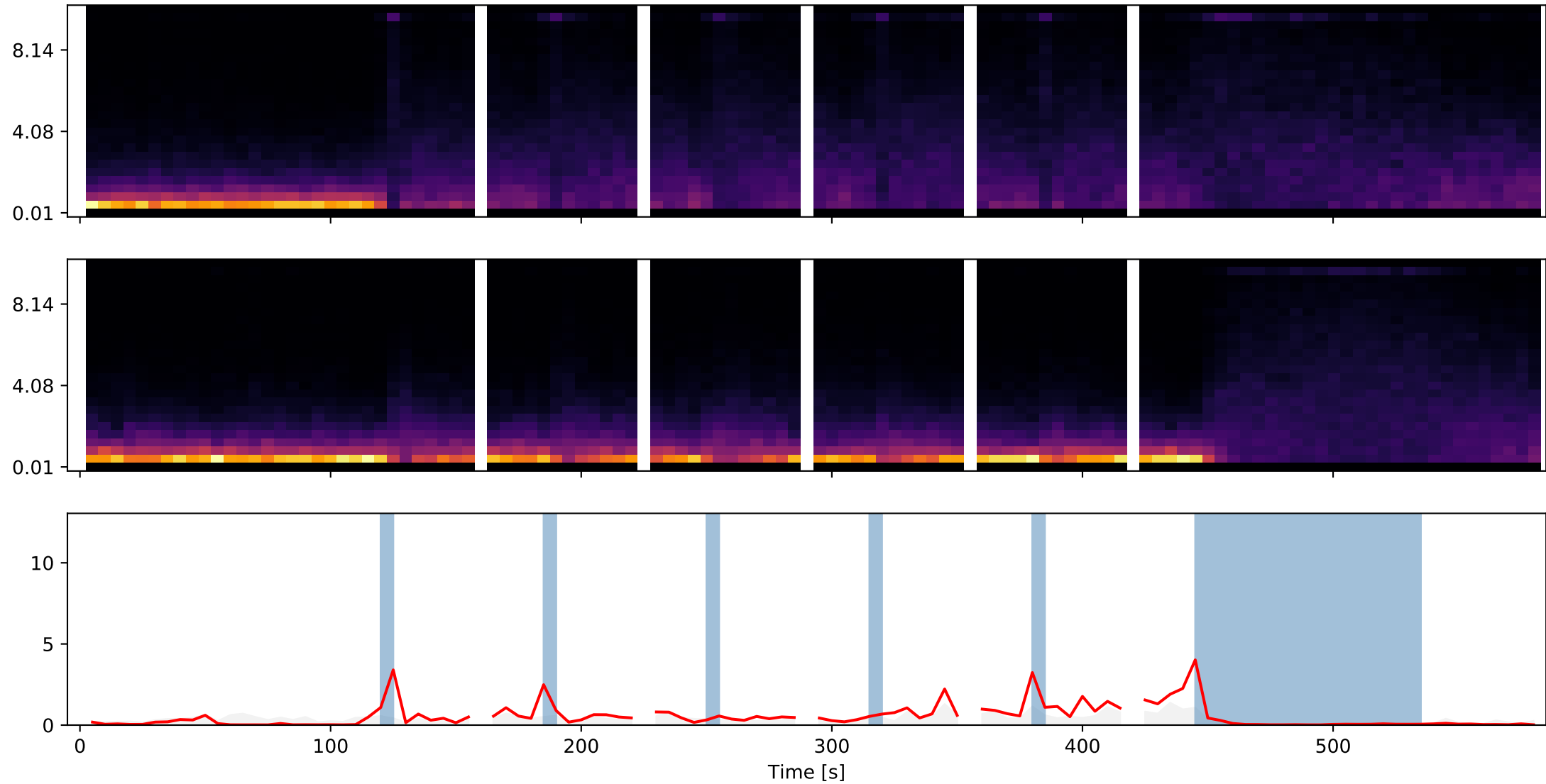
d\_angular\_velocity\_neck



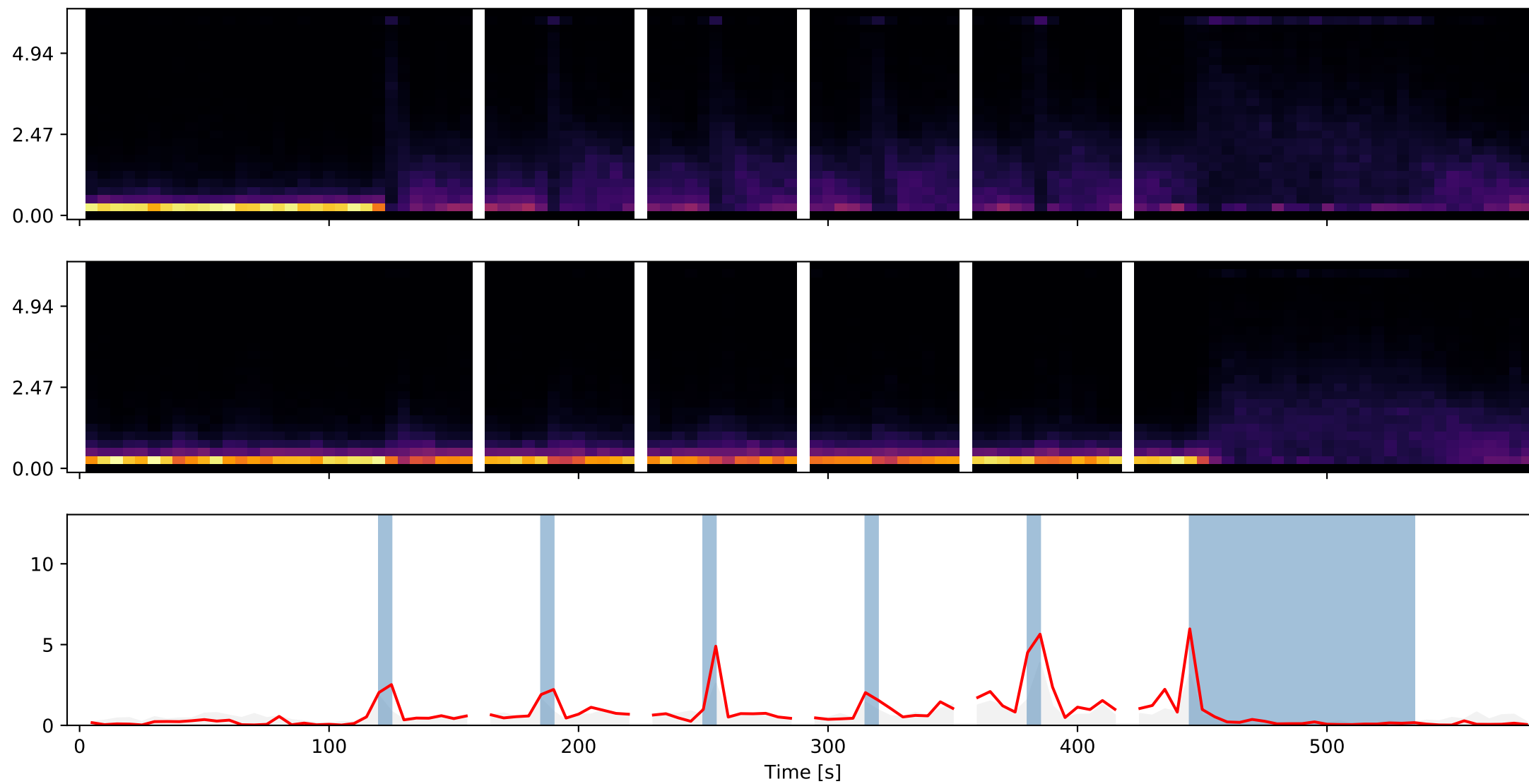
d\_minor\_axis



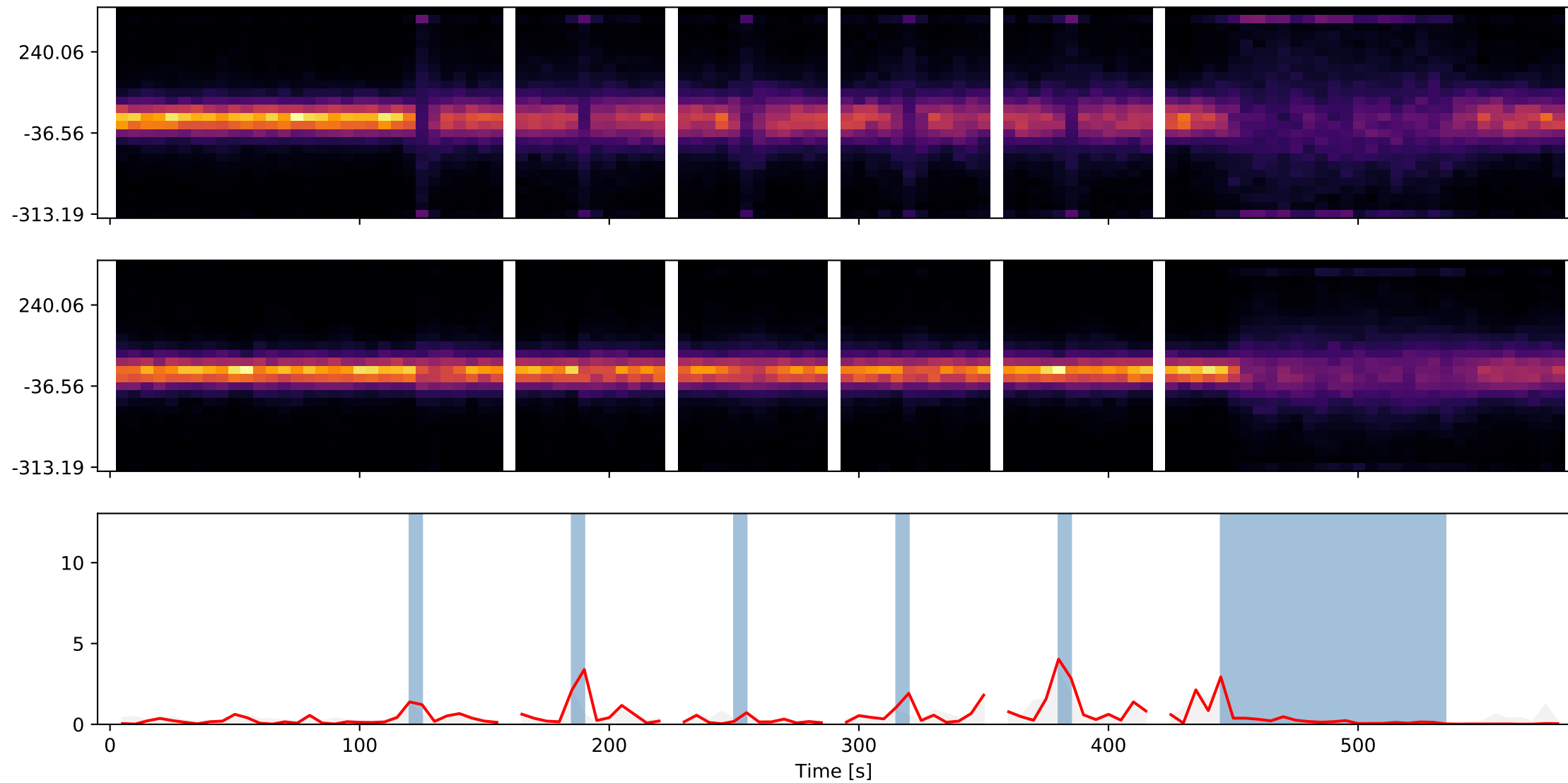
d\_relative\_to\_neck\_angular\_velocity\_head\_tip



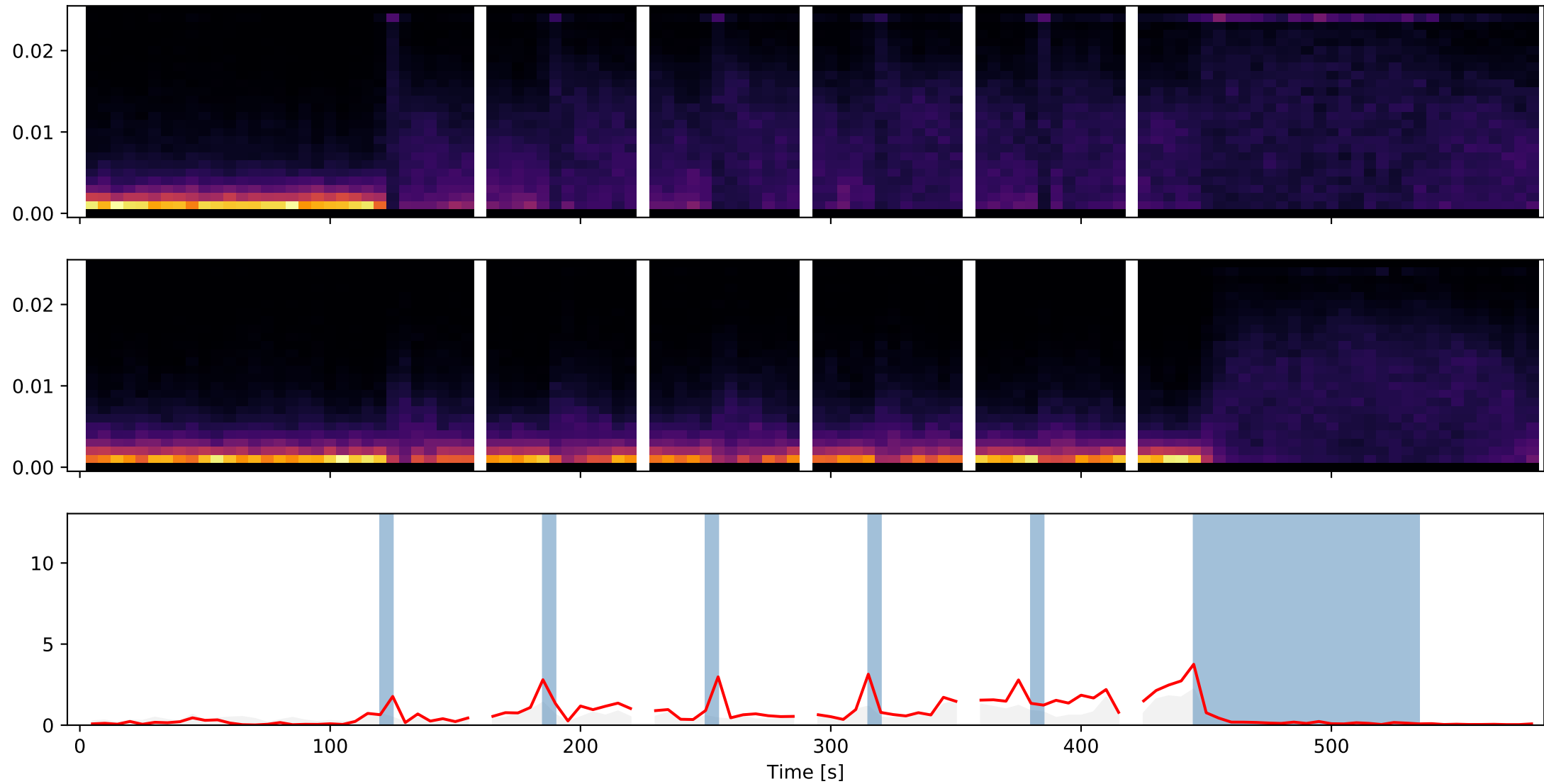
d\_angular\_velocity\_midbody



d\_relative\_to\_body\_radial\_velocity\_hips

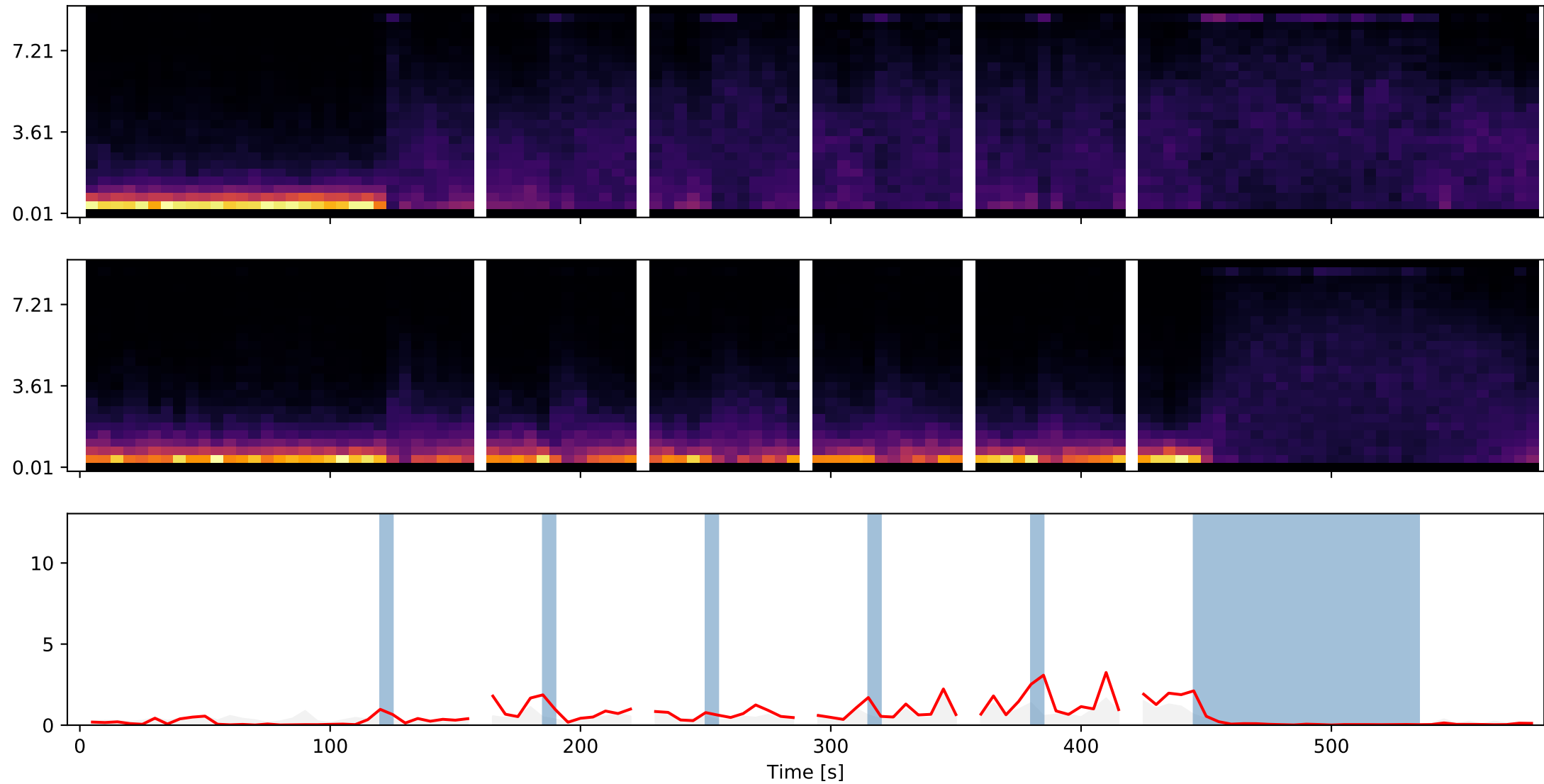


d\_curvature\_neck

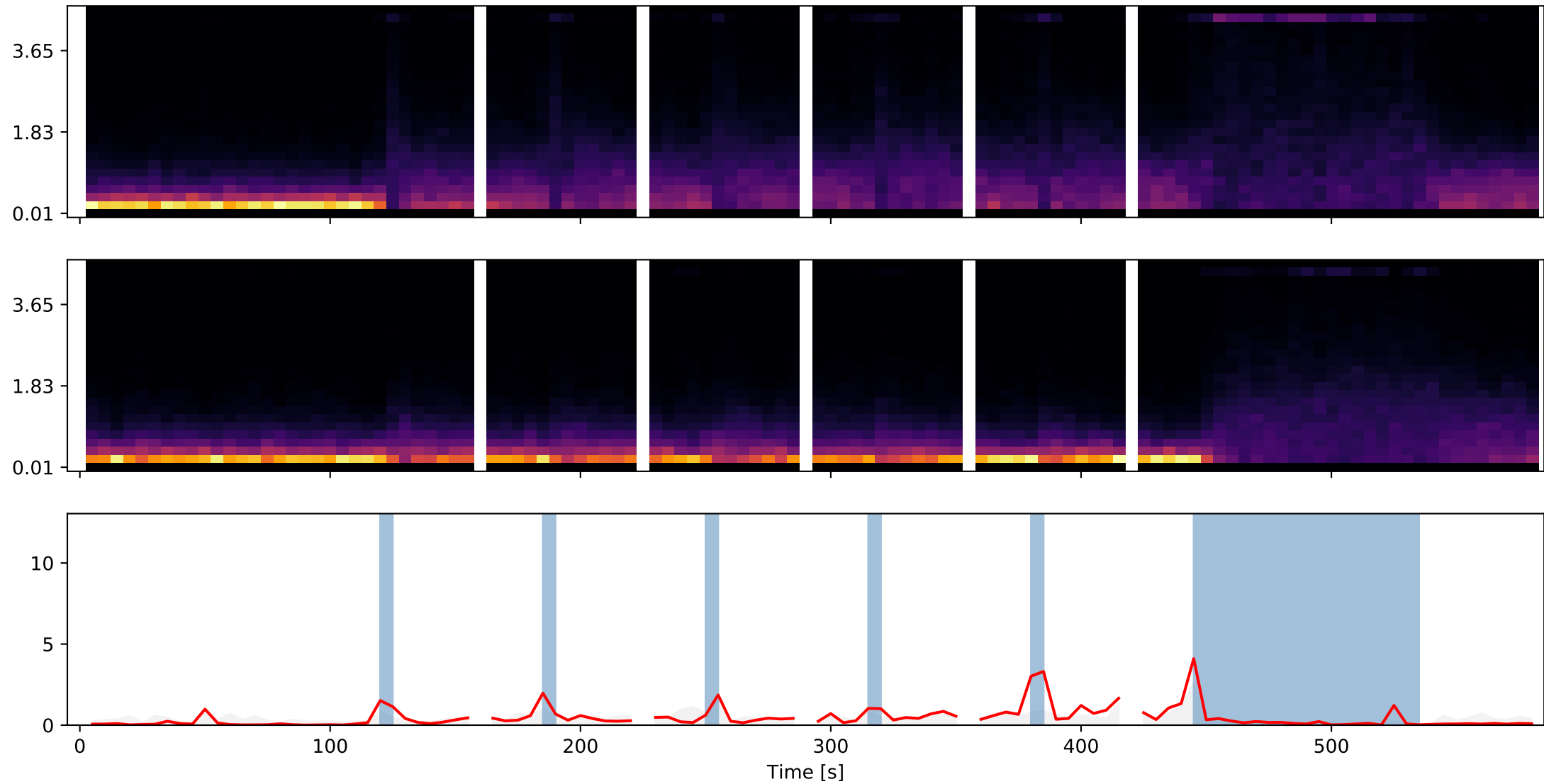




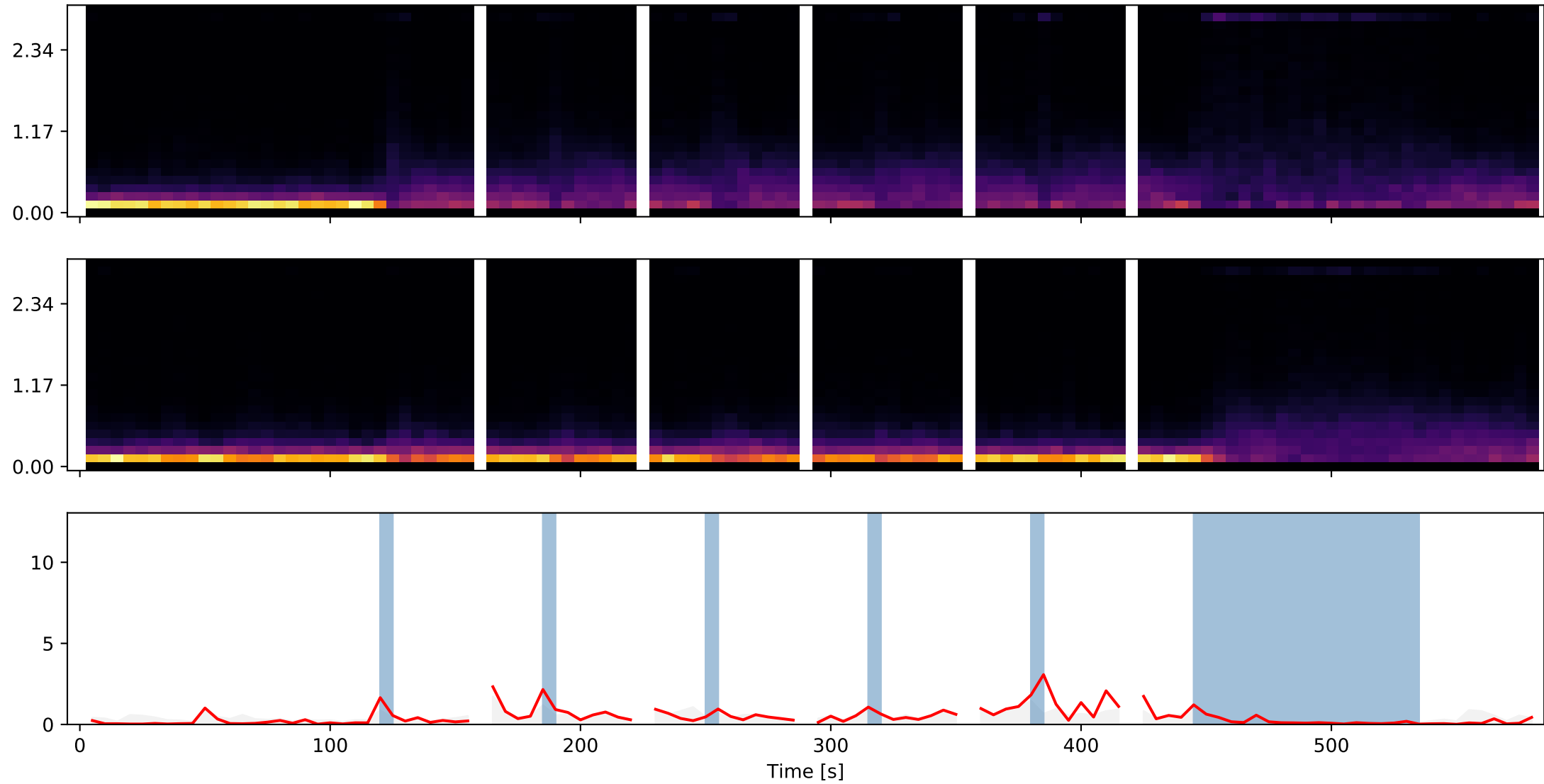
d\_eigen\_projection\_1



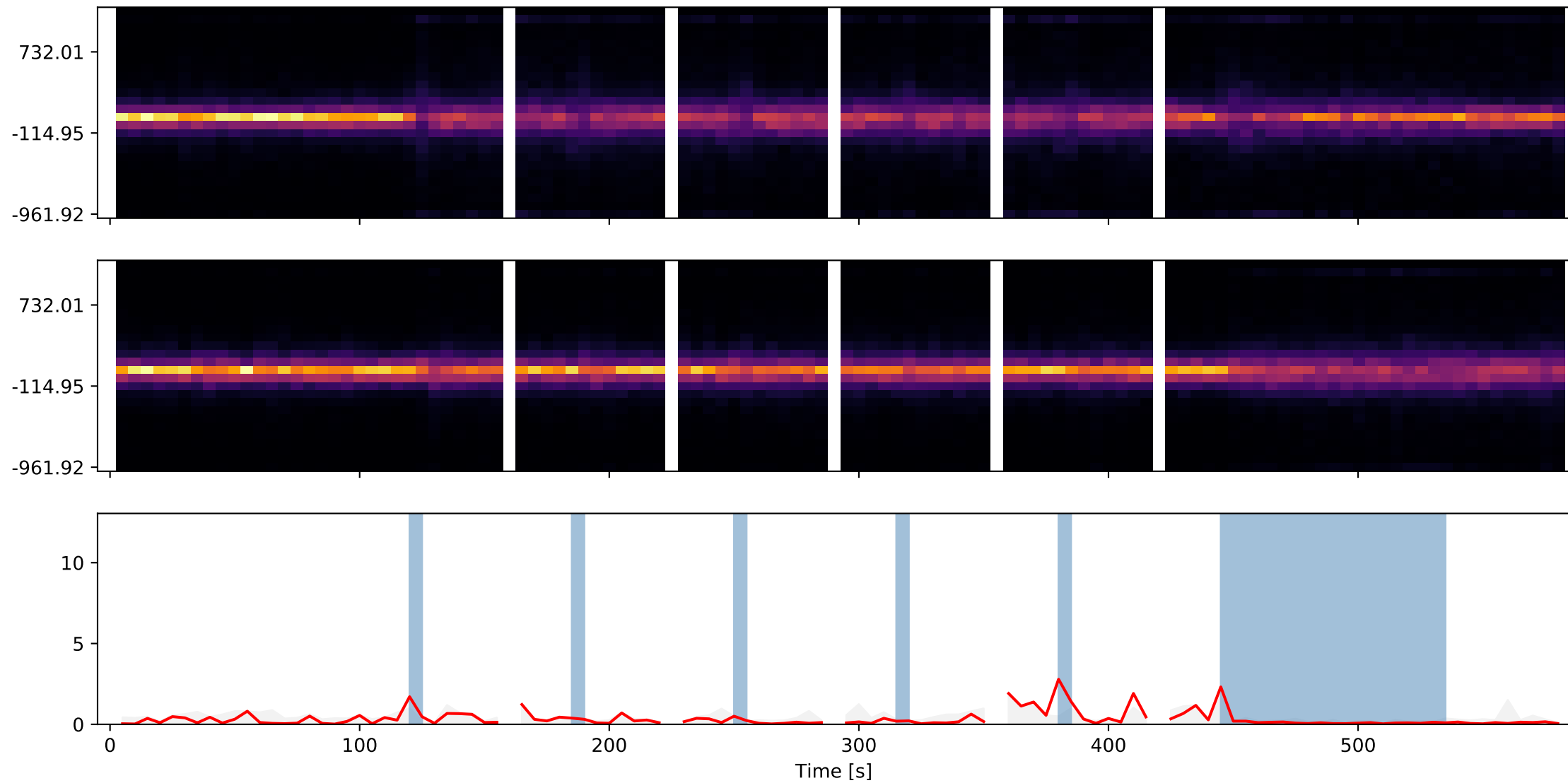
d\_relative\_to\_body\_angular\_velocity\_head\_tip



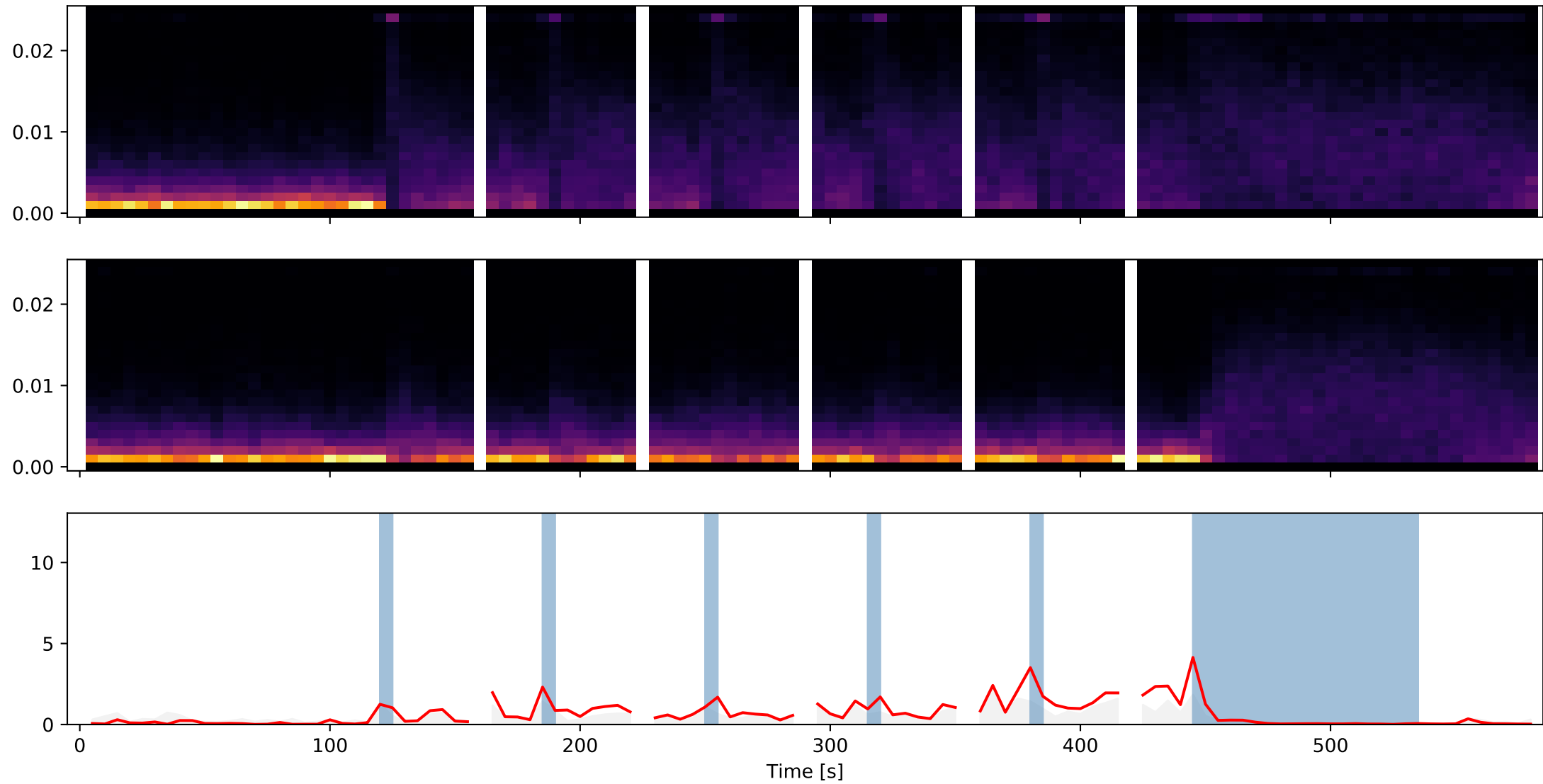
d\_angular\_velocity



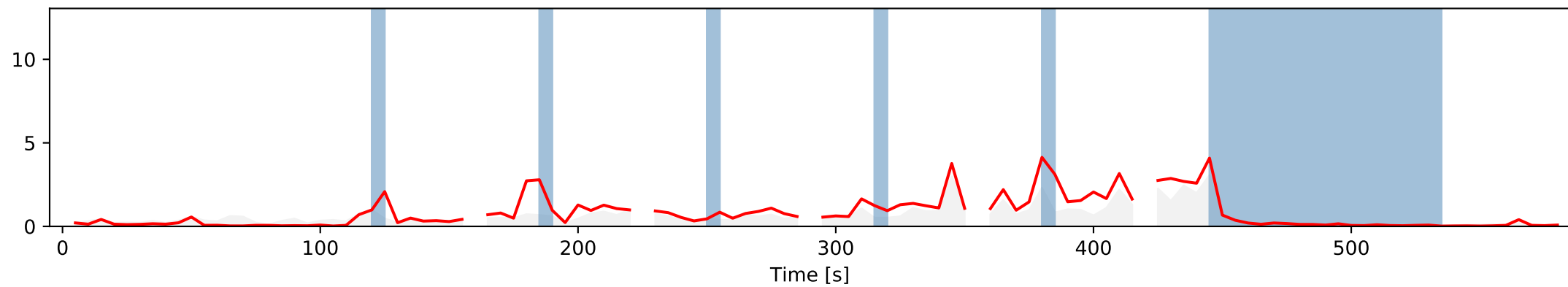
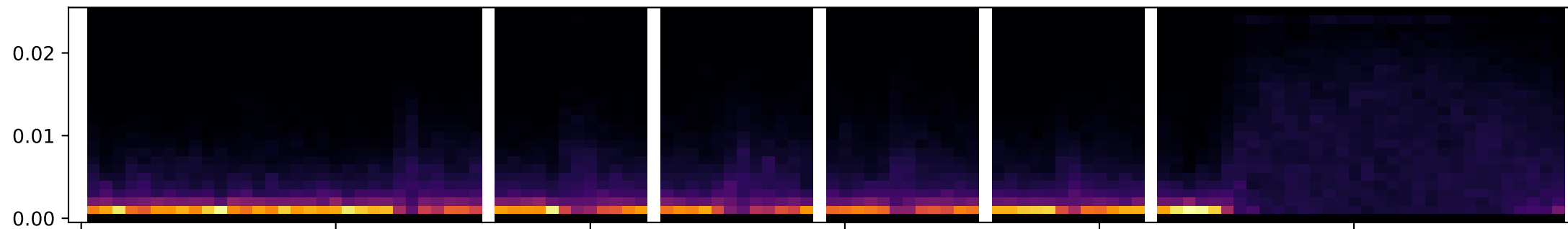
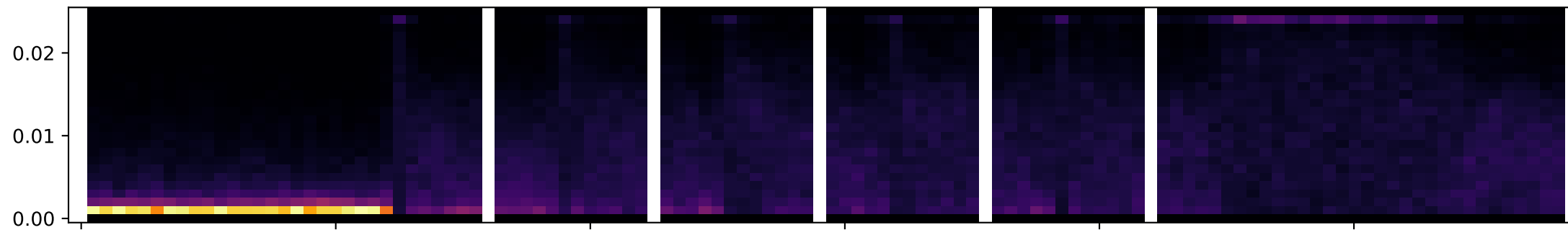
d\_speed\_hips



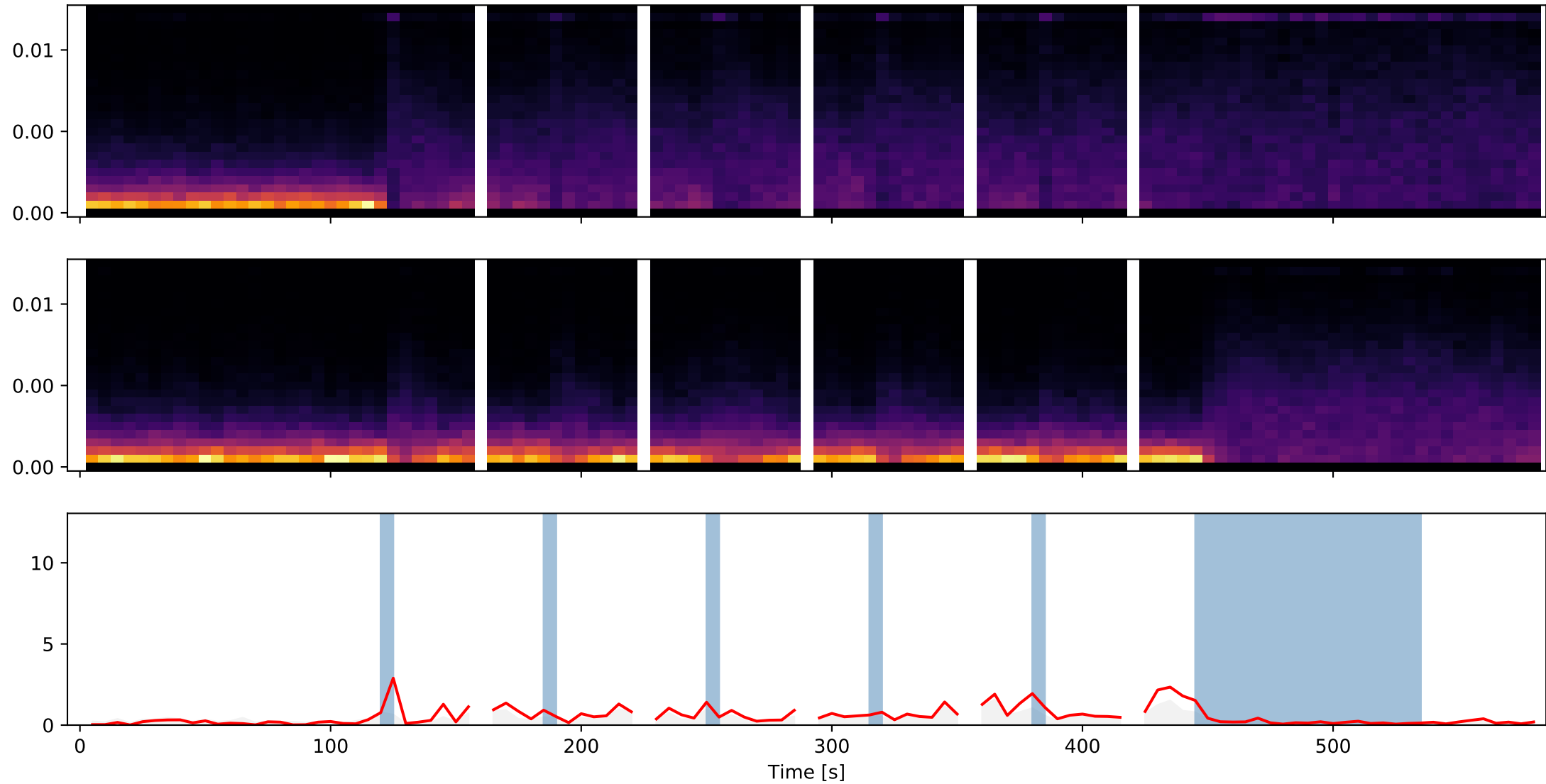
d\_curvature\_tail



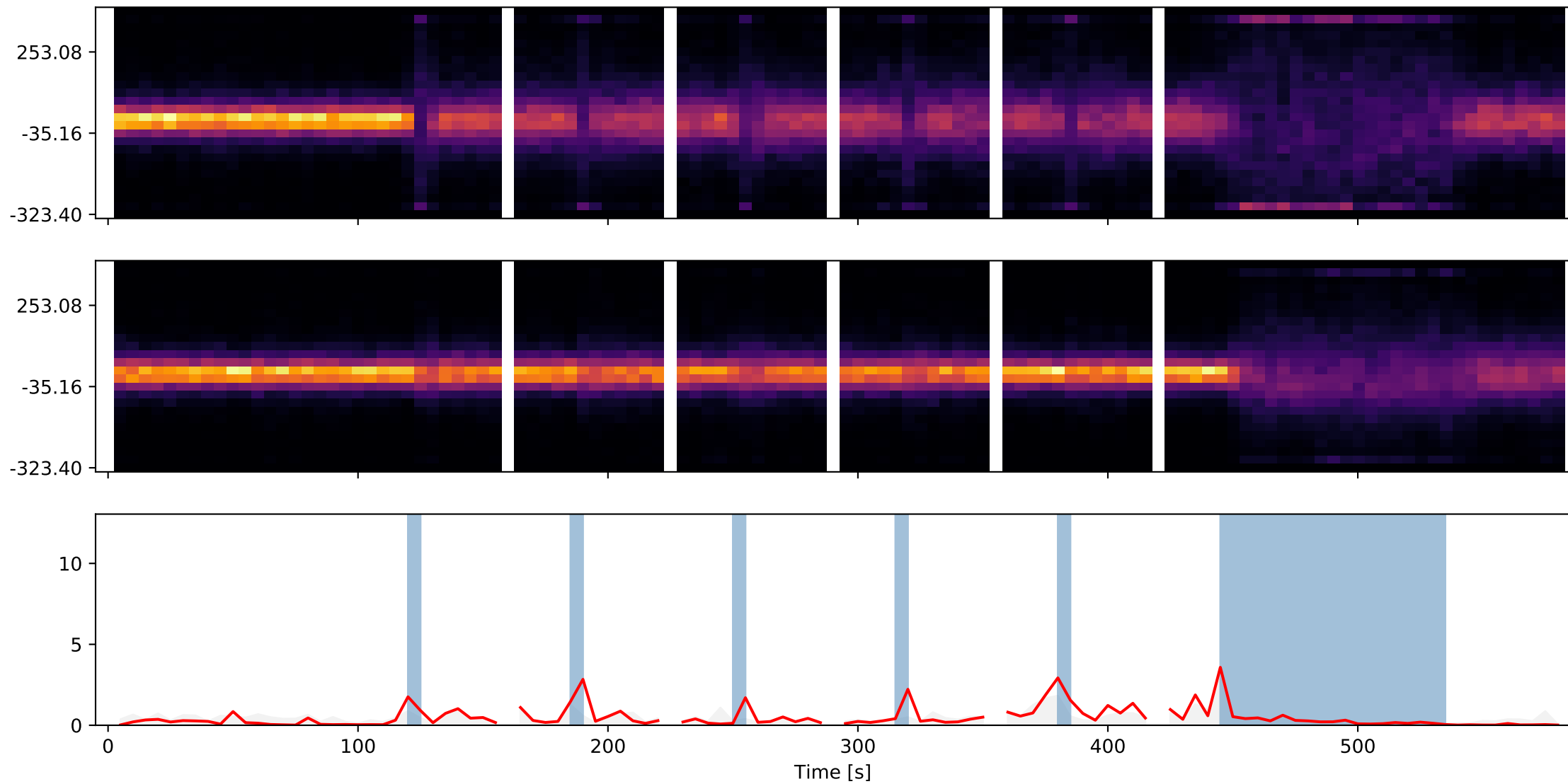
d\_curvature\_mean\_neck



d\_curvature\_std\_hips

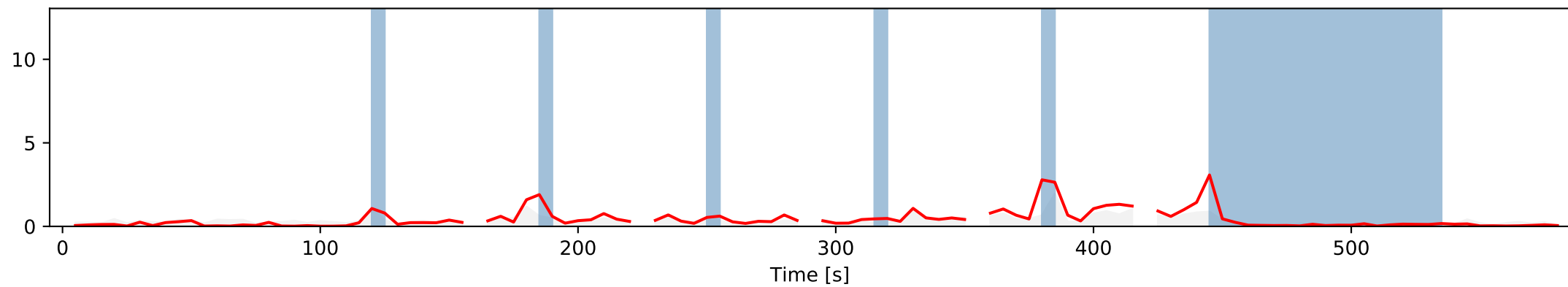
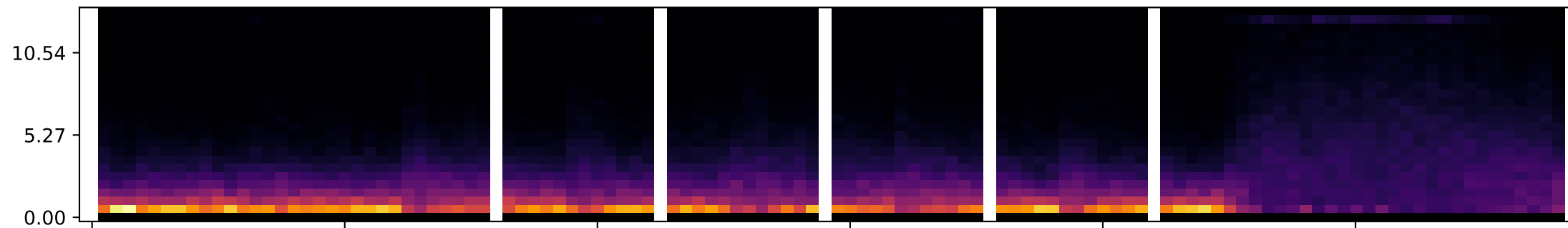
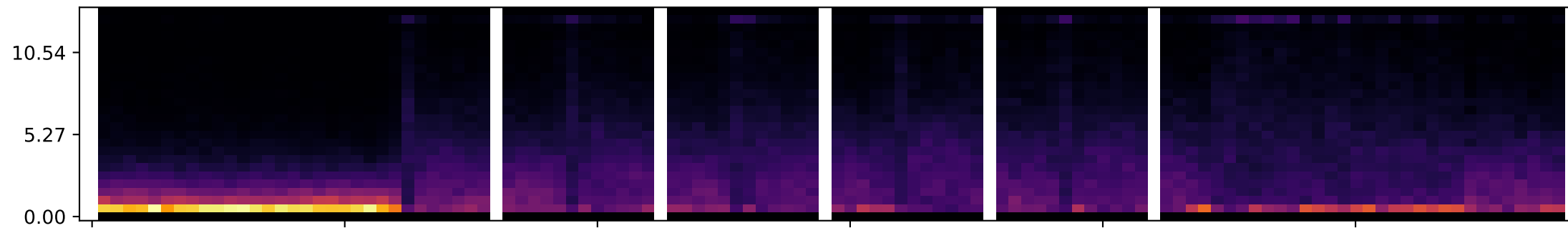


d\_relative\_to\_body\_radial\_velocity\_neck

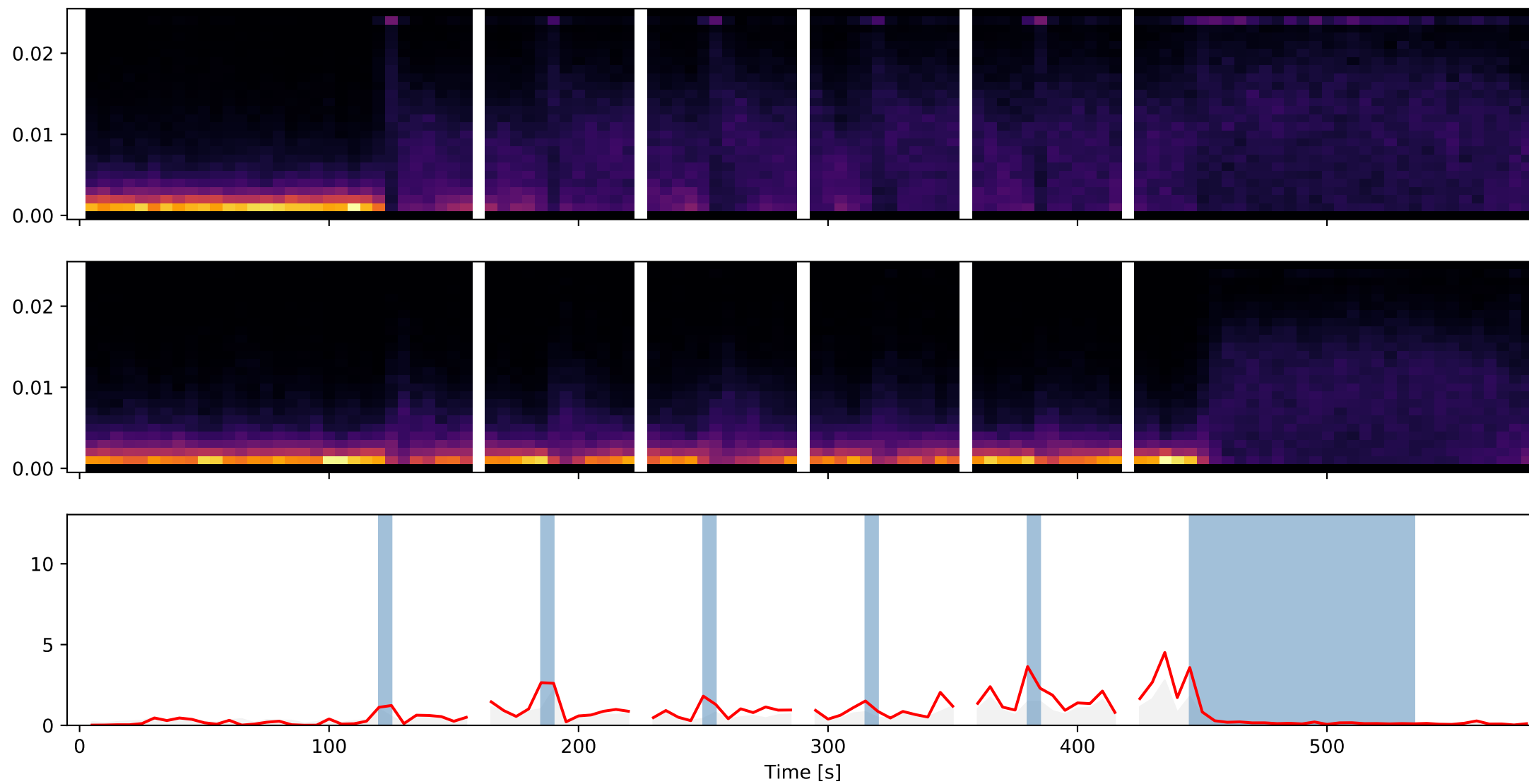




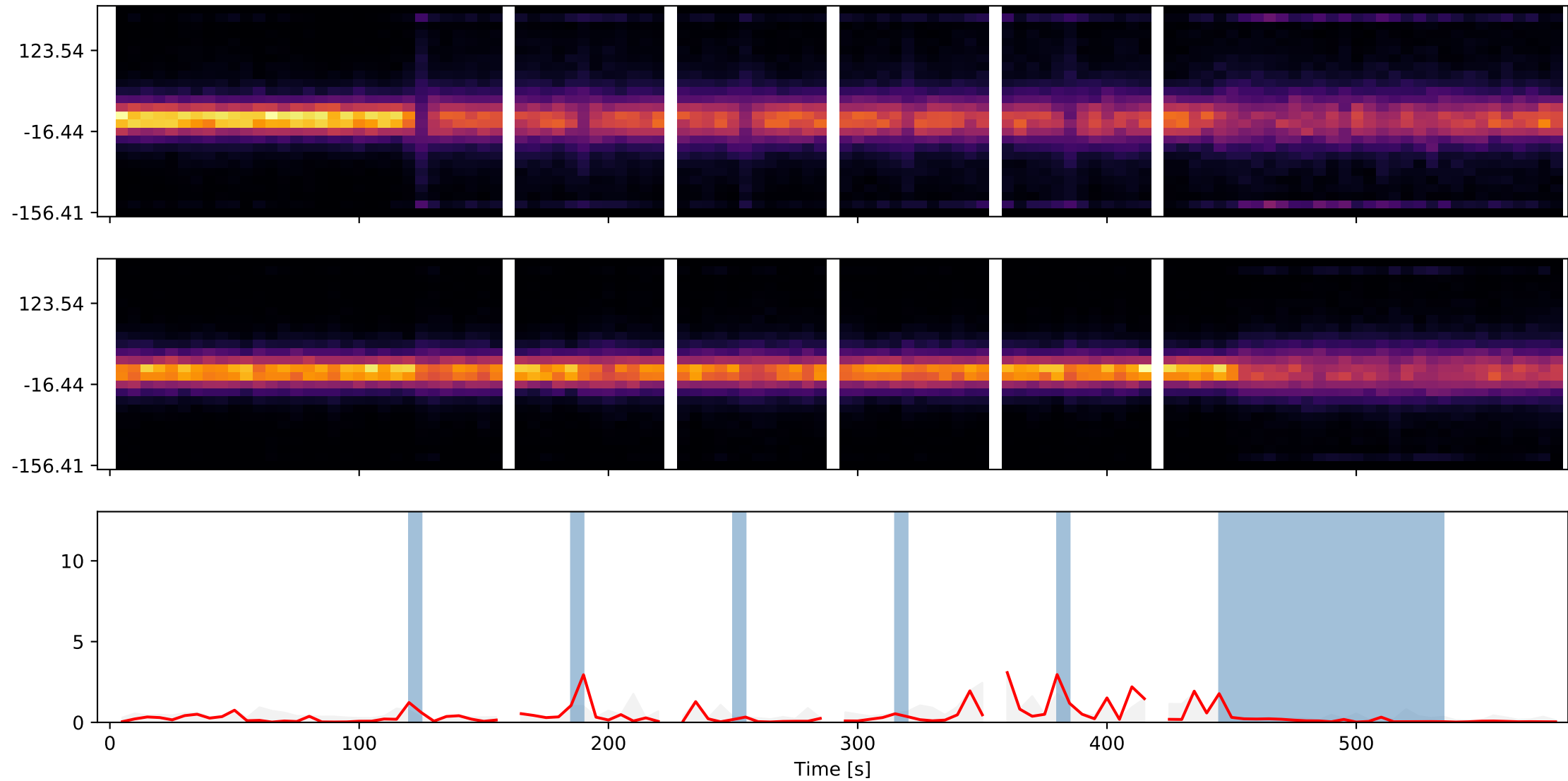
d\_angular\_velocity\_head\_base



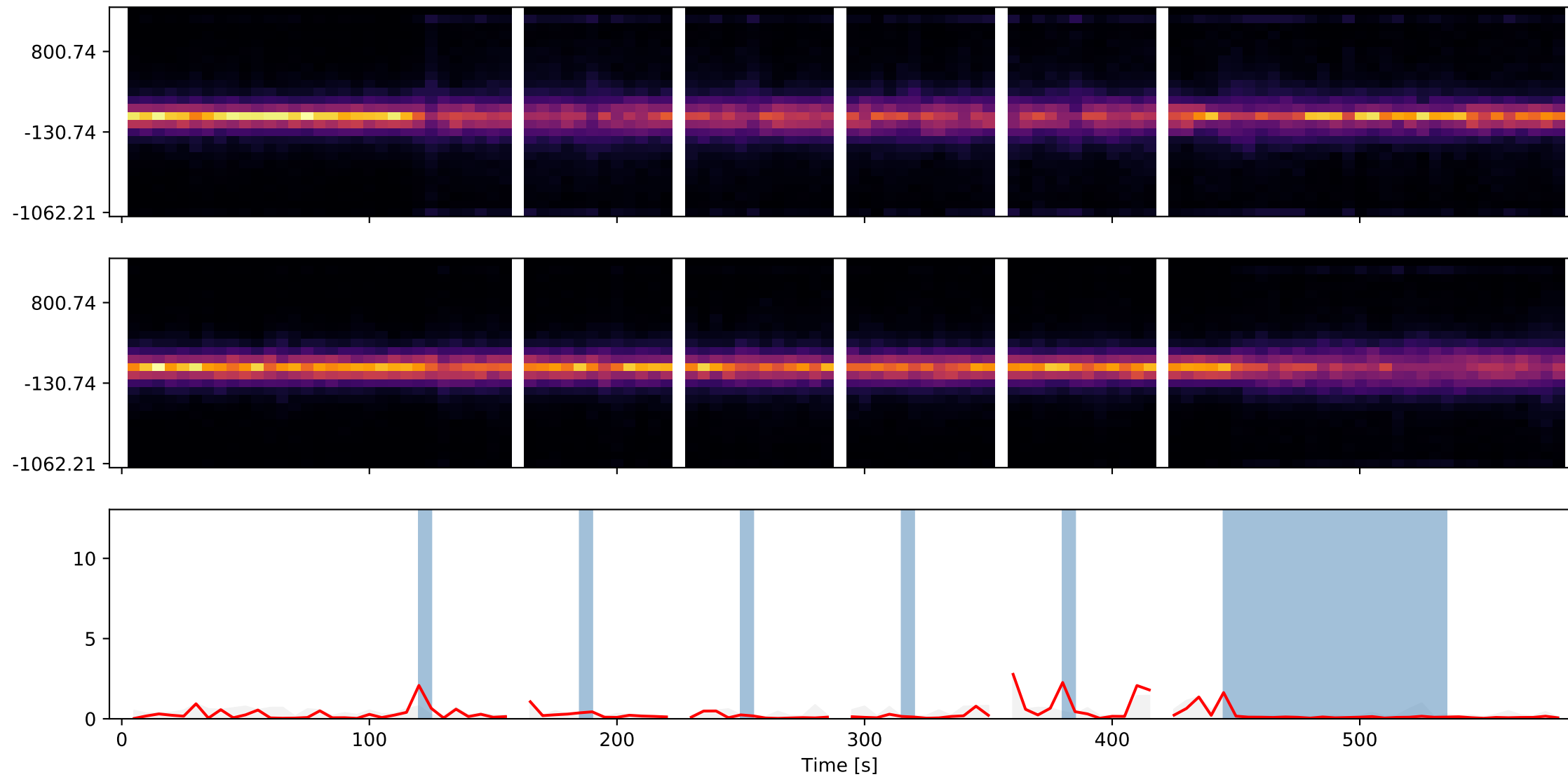
d\_curvature\_midbody



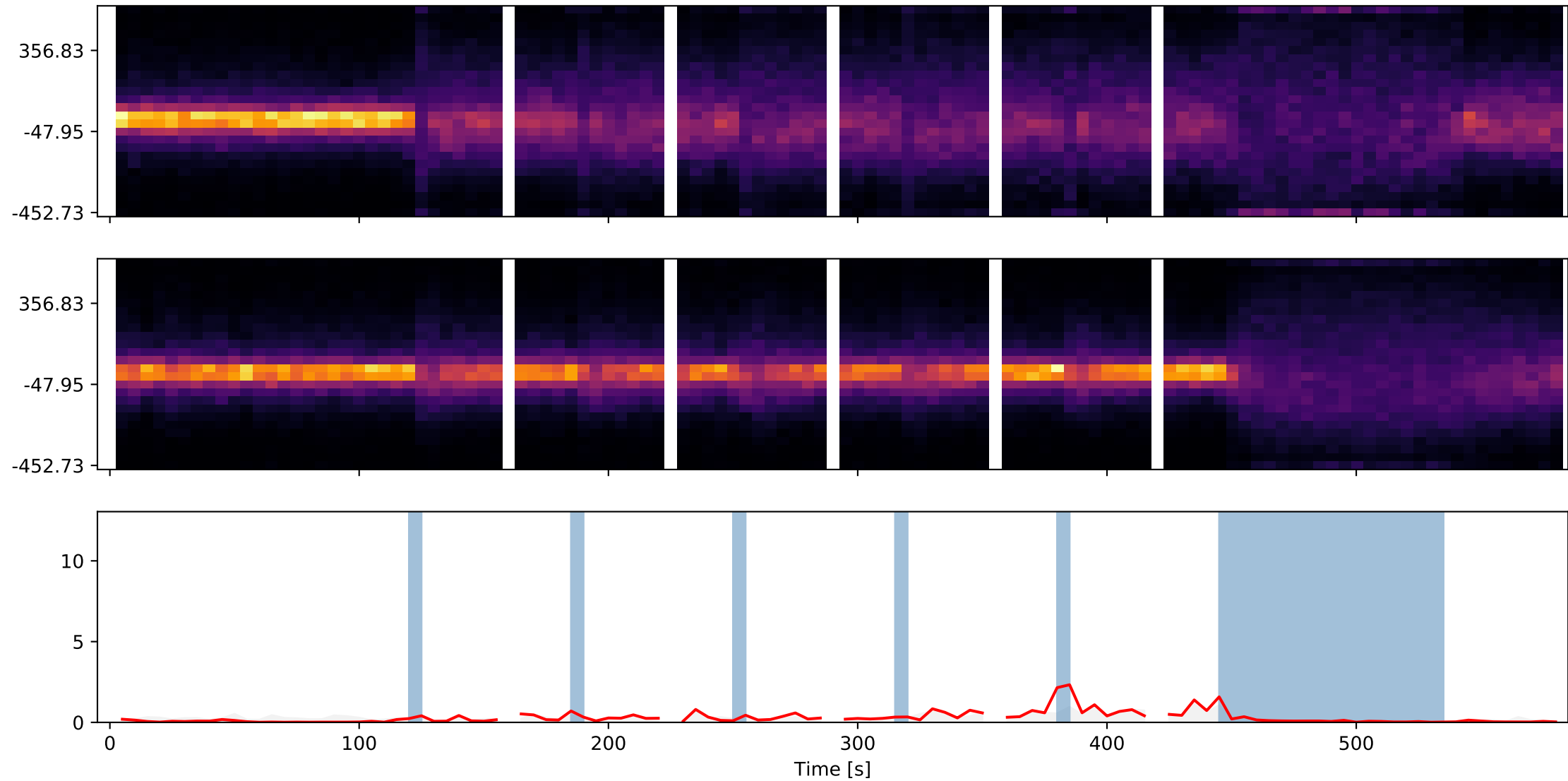
d\_relative\_to\_tail\_base\_radial\_velocity\_tail\_tip



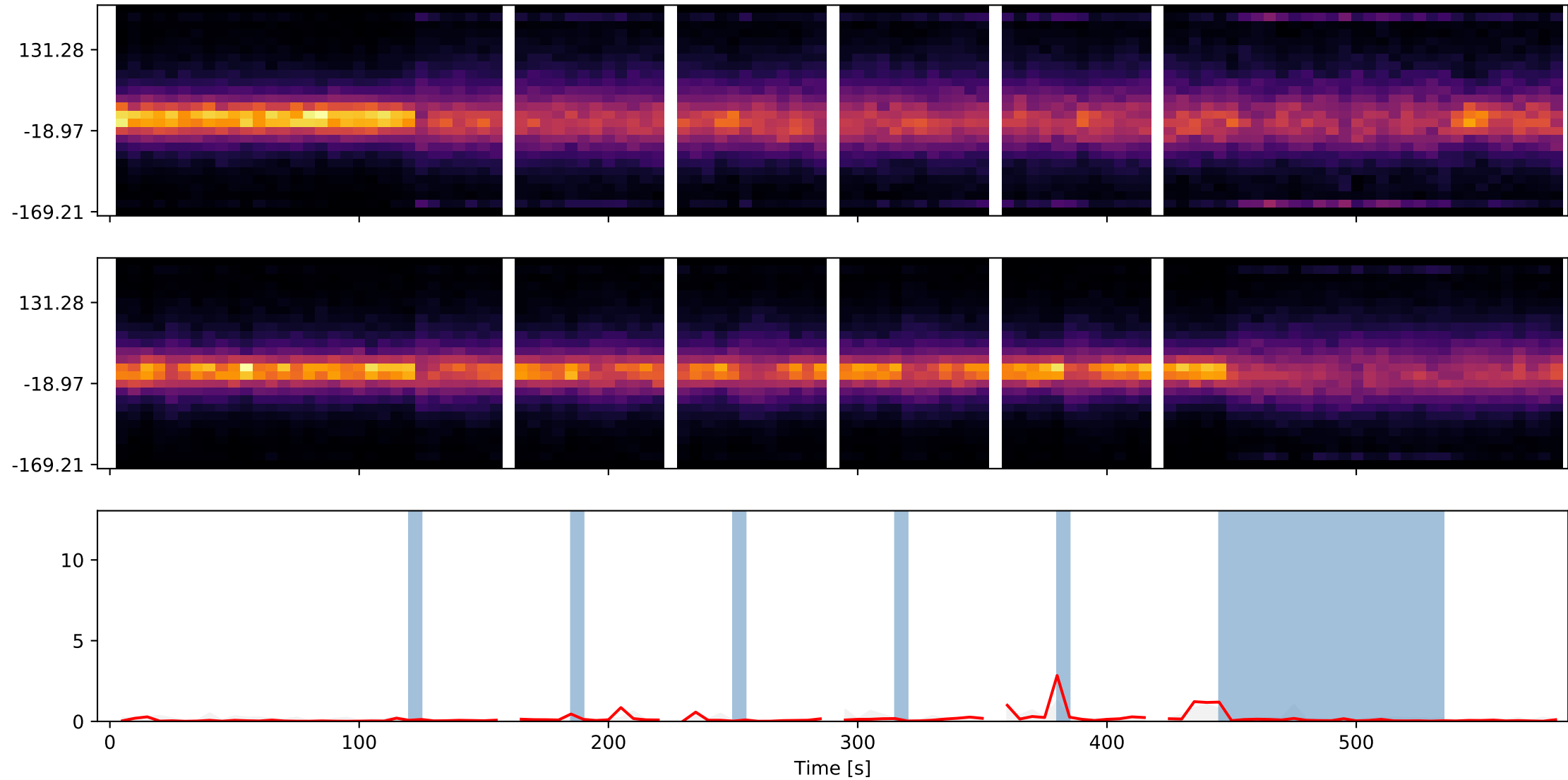
d\_speed\_neck



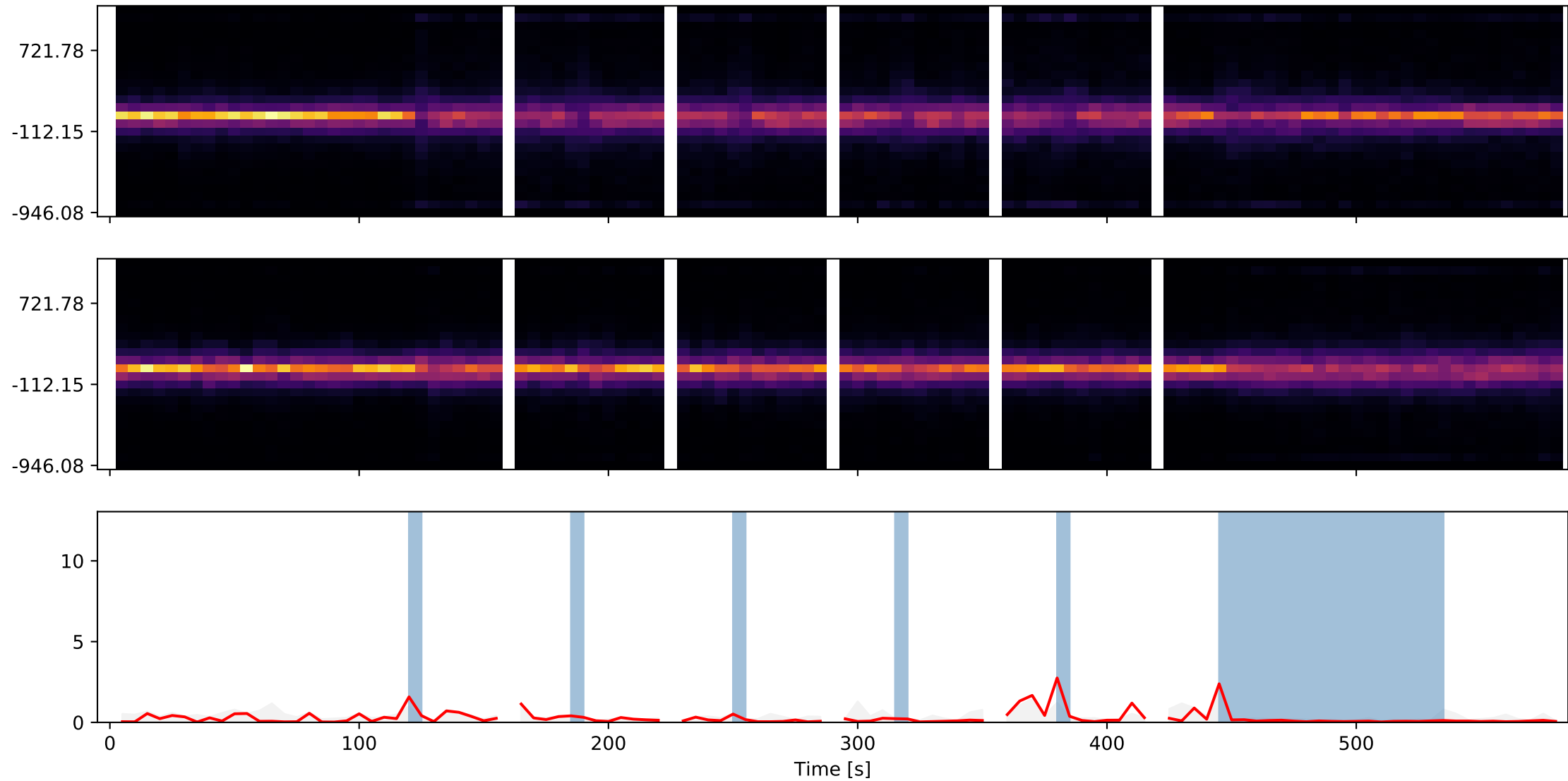
d\_relative\_to\_neck\_radial\_velocity\_head\_tip



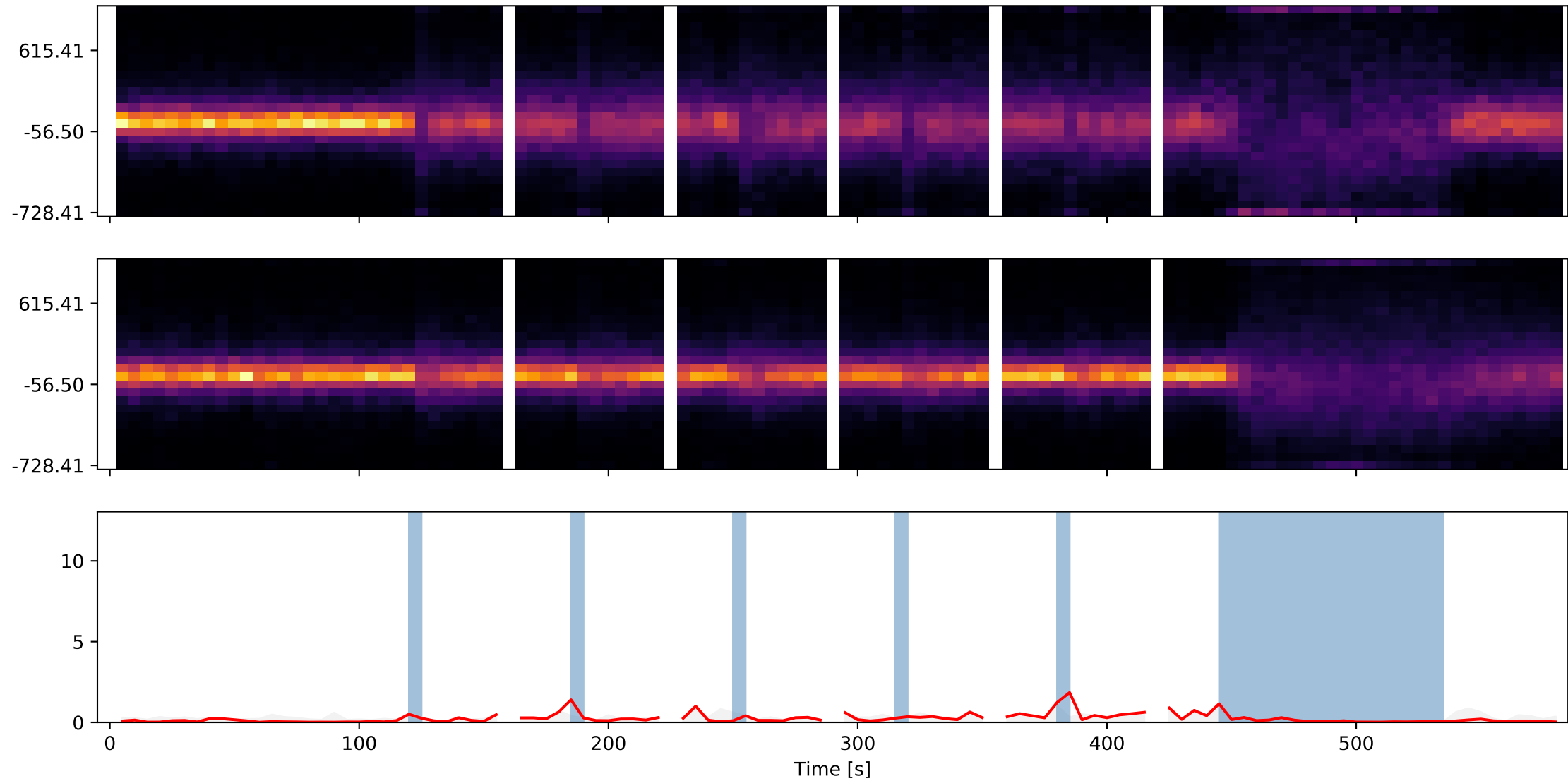
d\_relative\_to\_head\_base\_radial\_velocity\_head\_tip



d\_speed\_tail\_tip

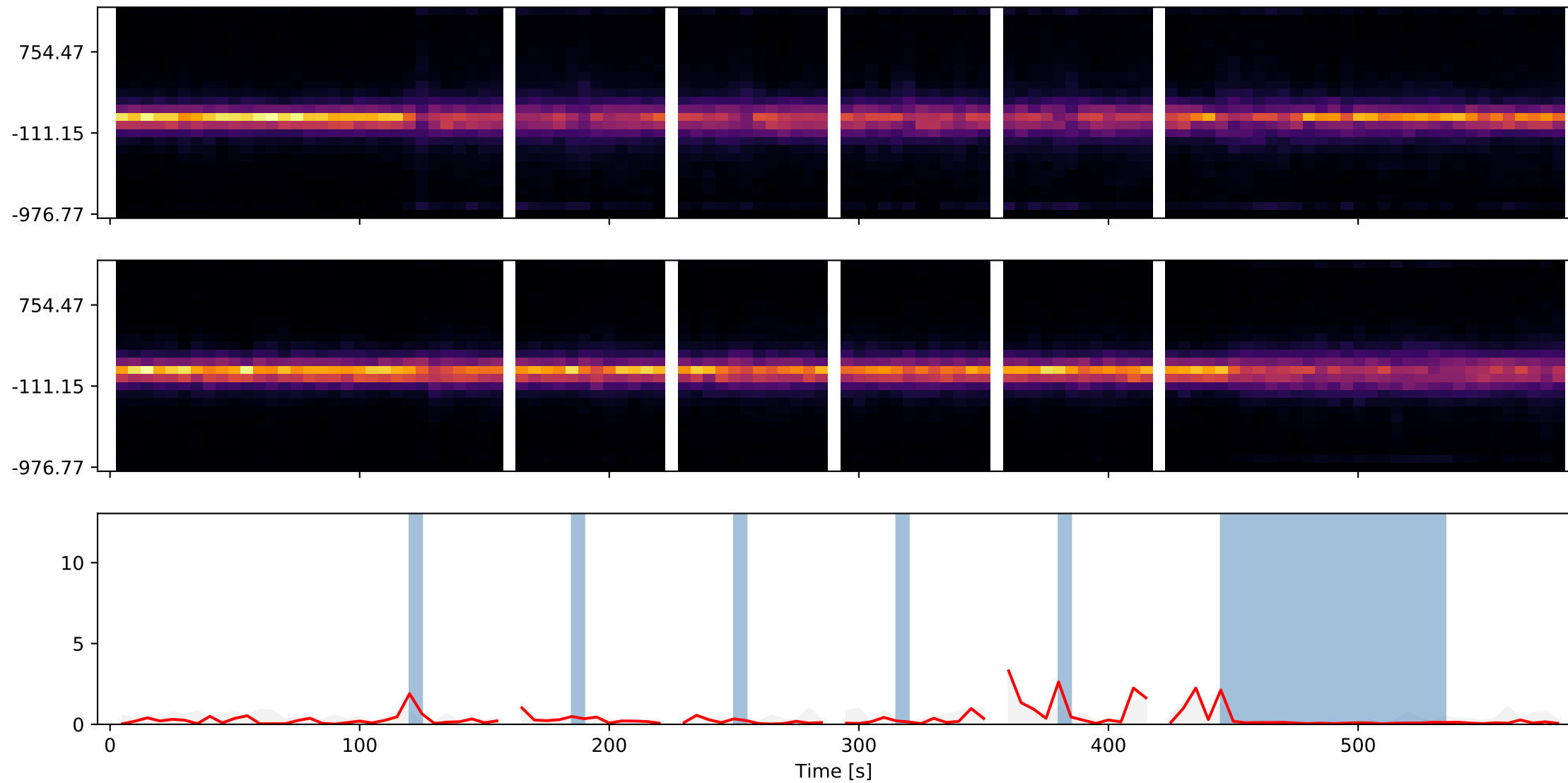


d\_relative\_to\_body\_radial\_velocity\_head\_tip

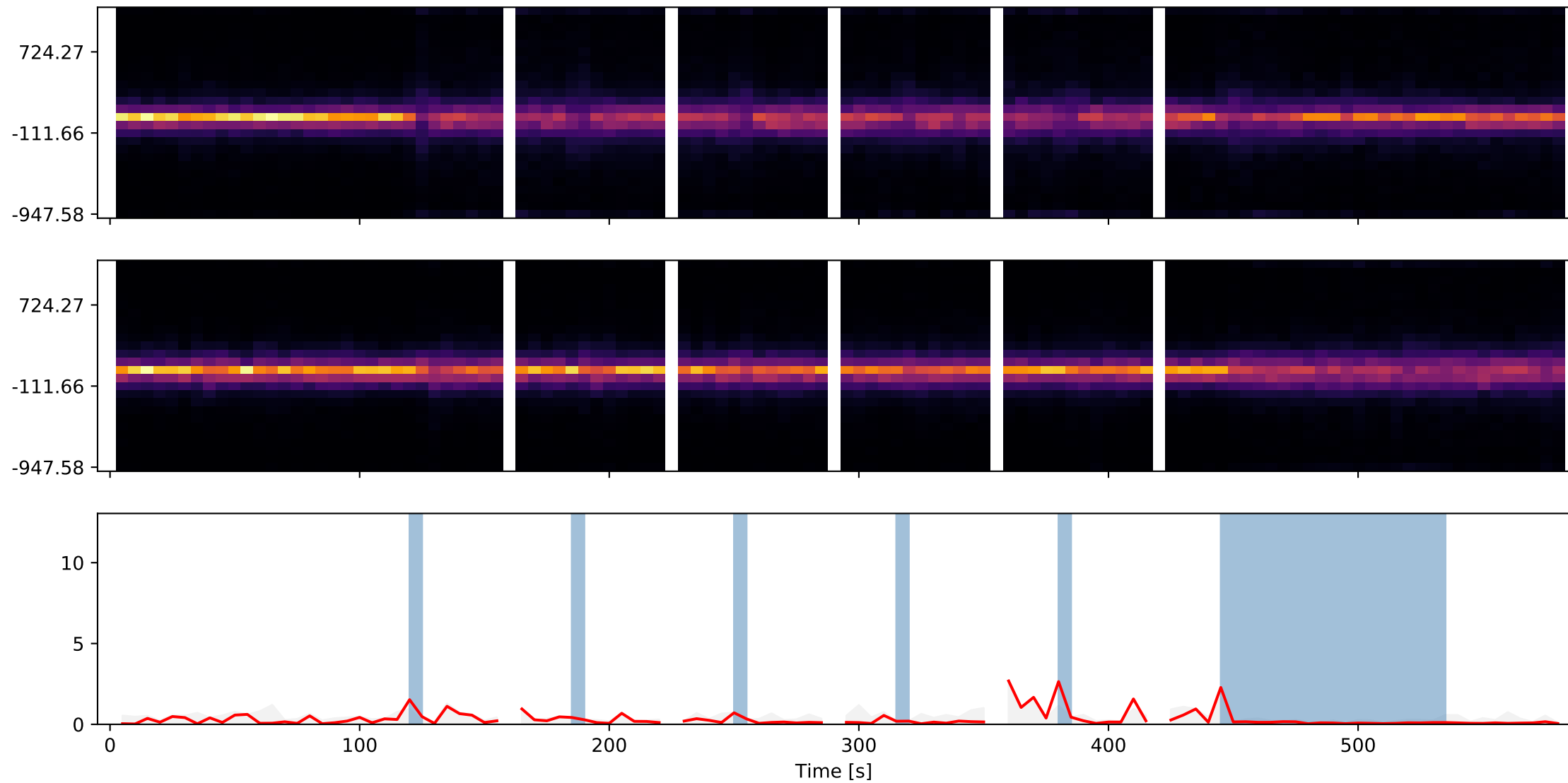




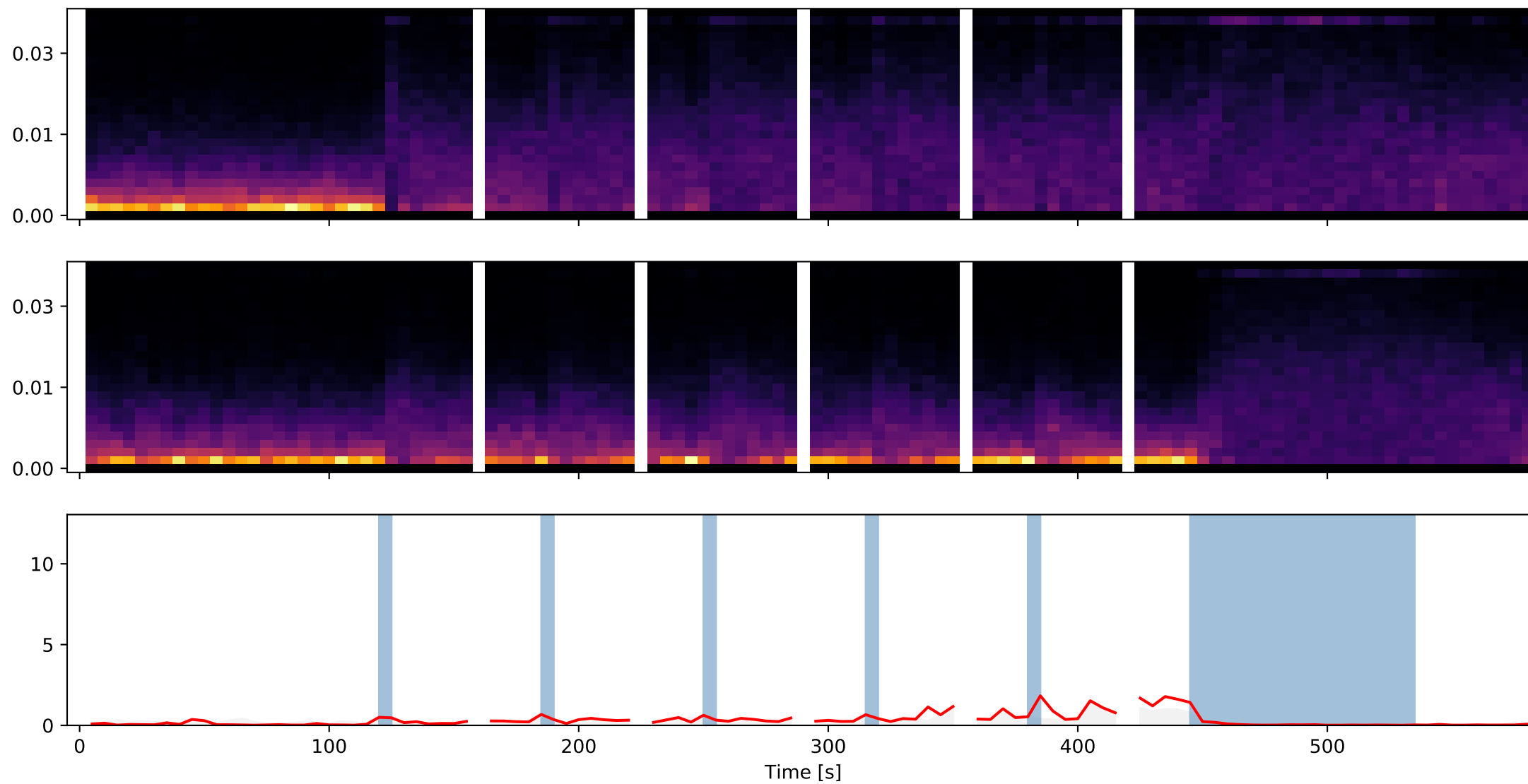
d\_speed\_midbody



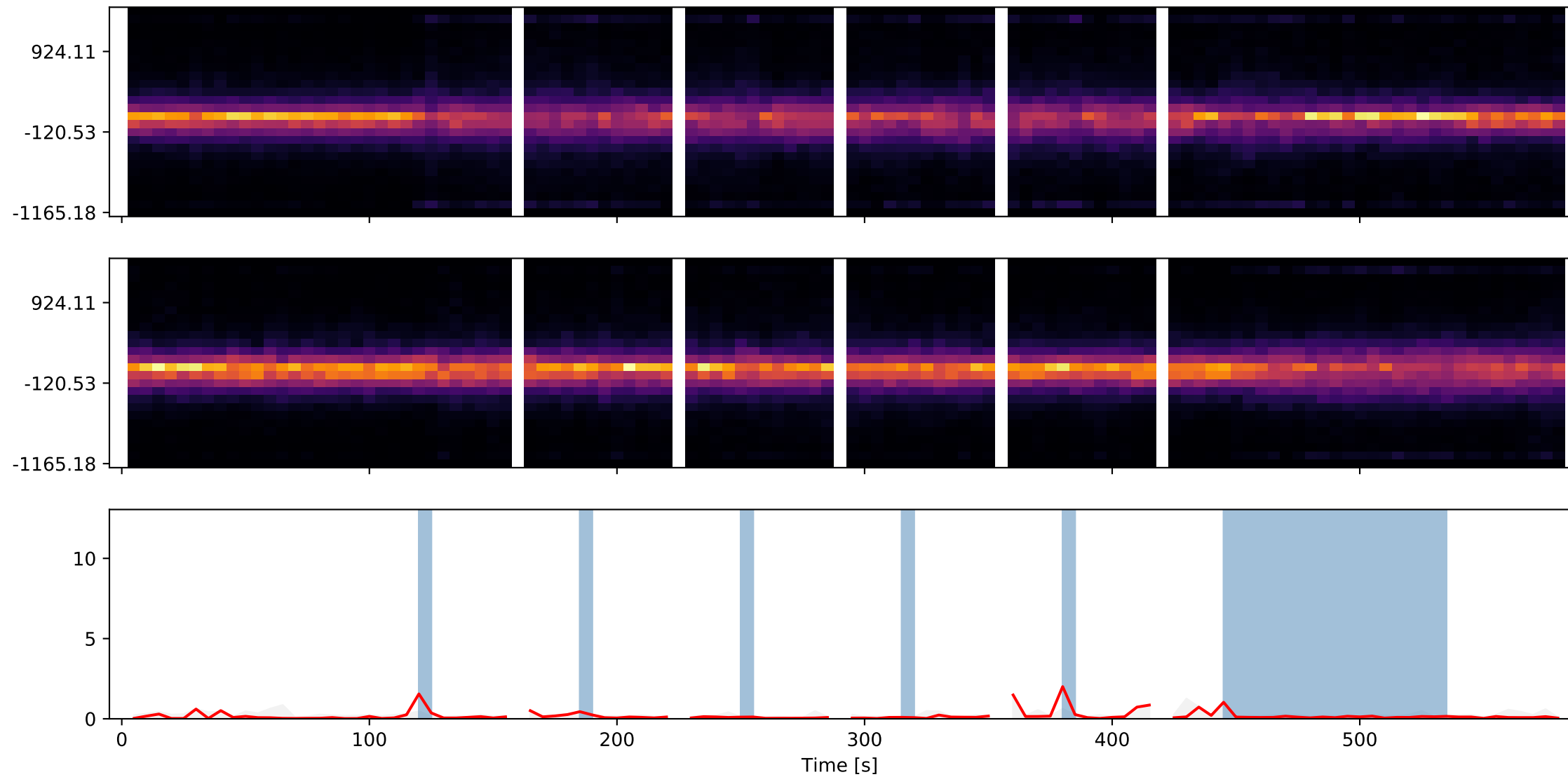
d\_speed\_tail\_base



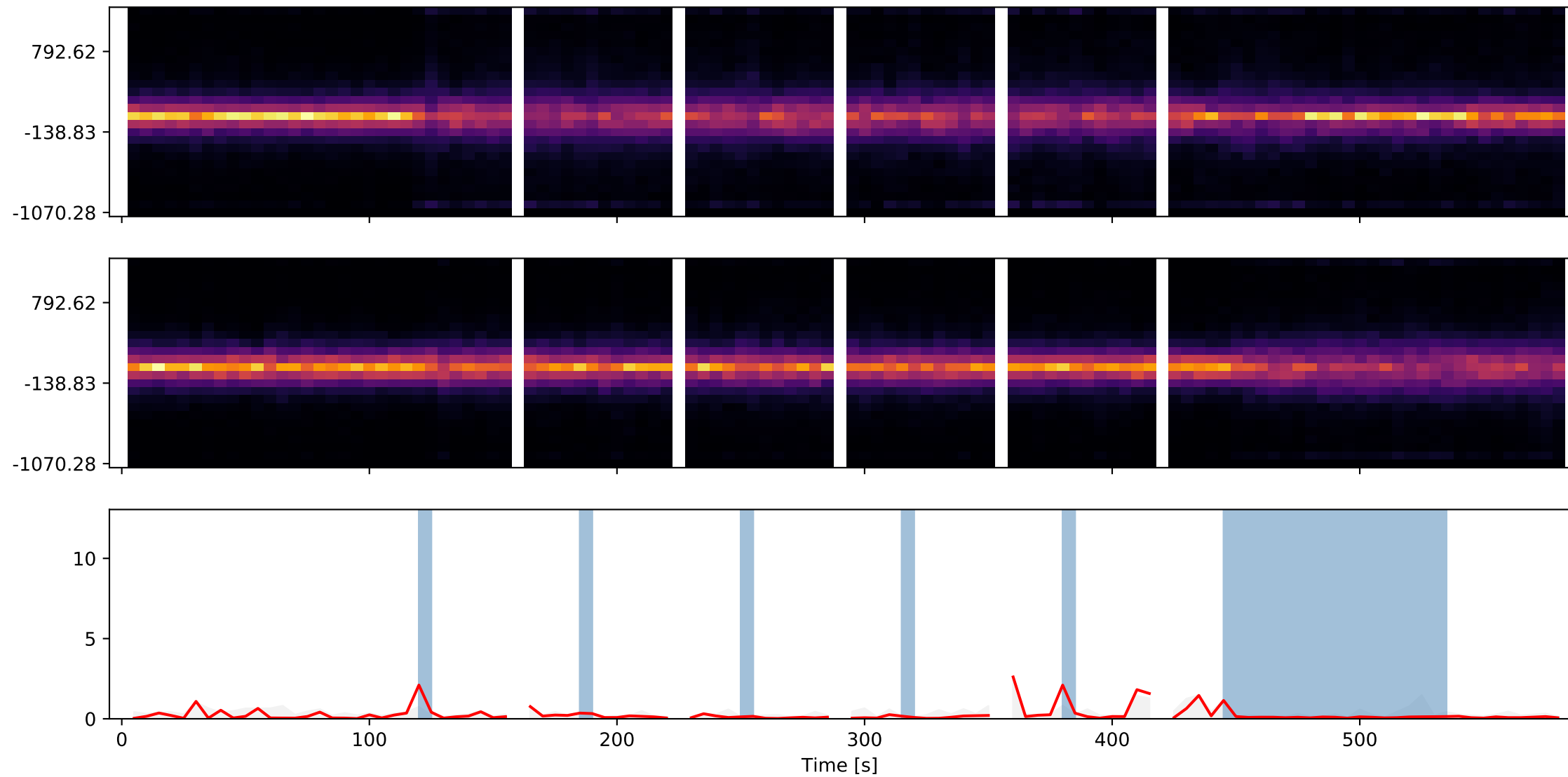
d\_curvature\_mean\_head



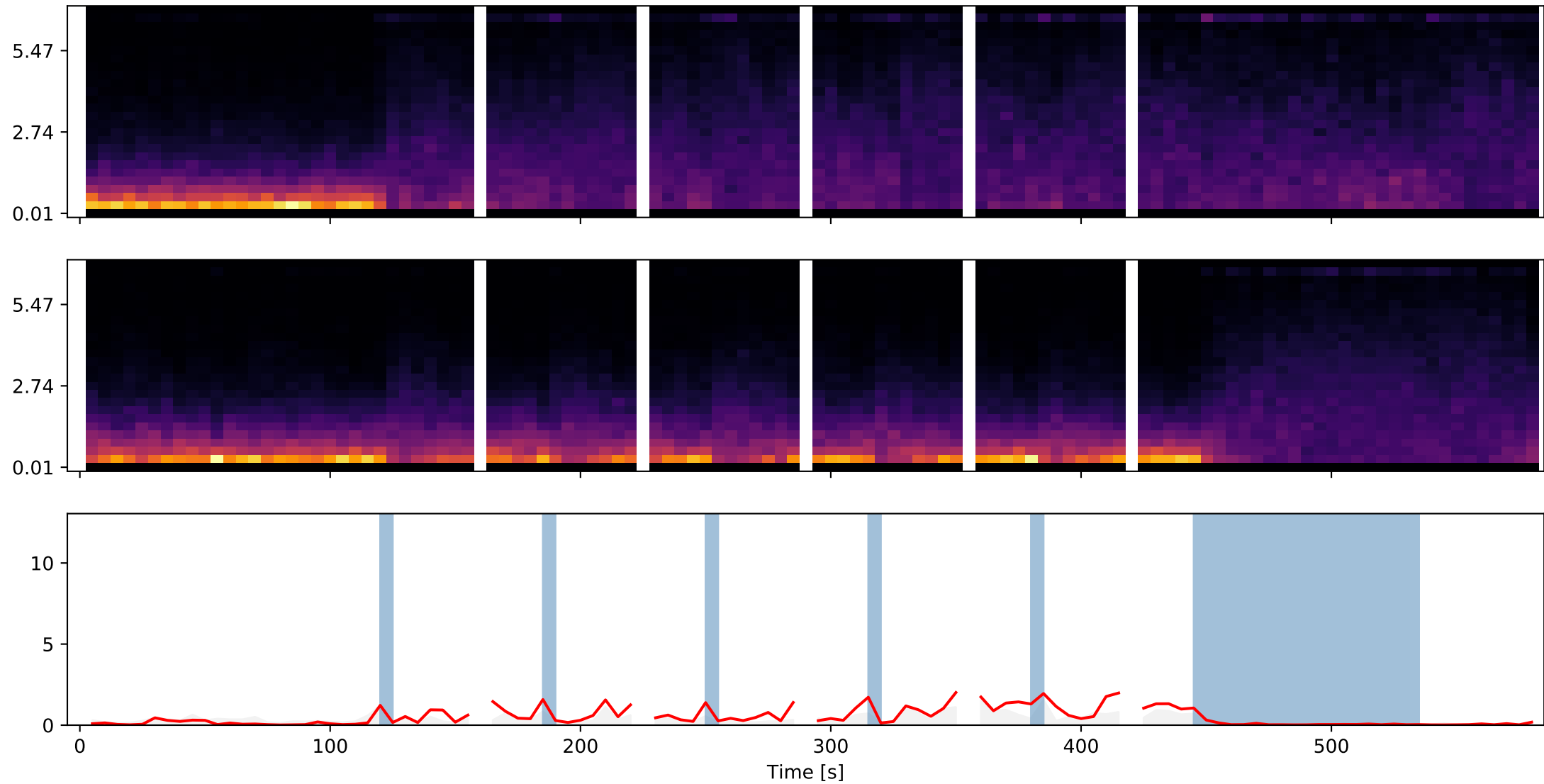
d\_speed\_head\_tip



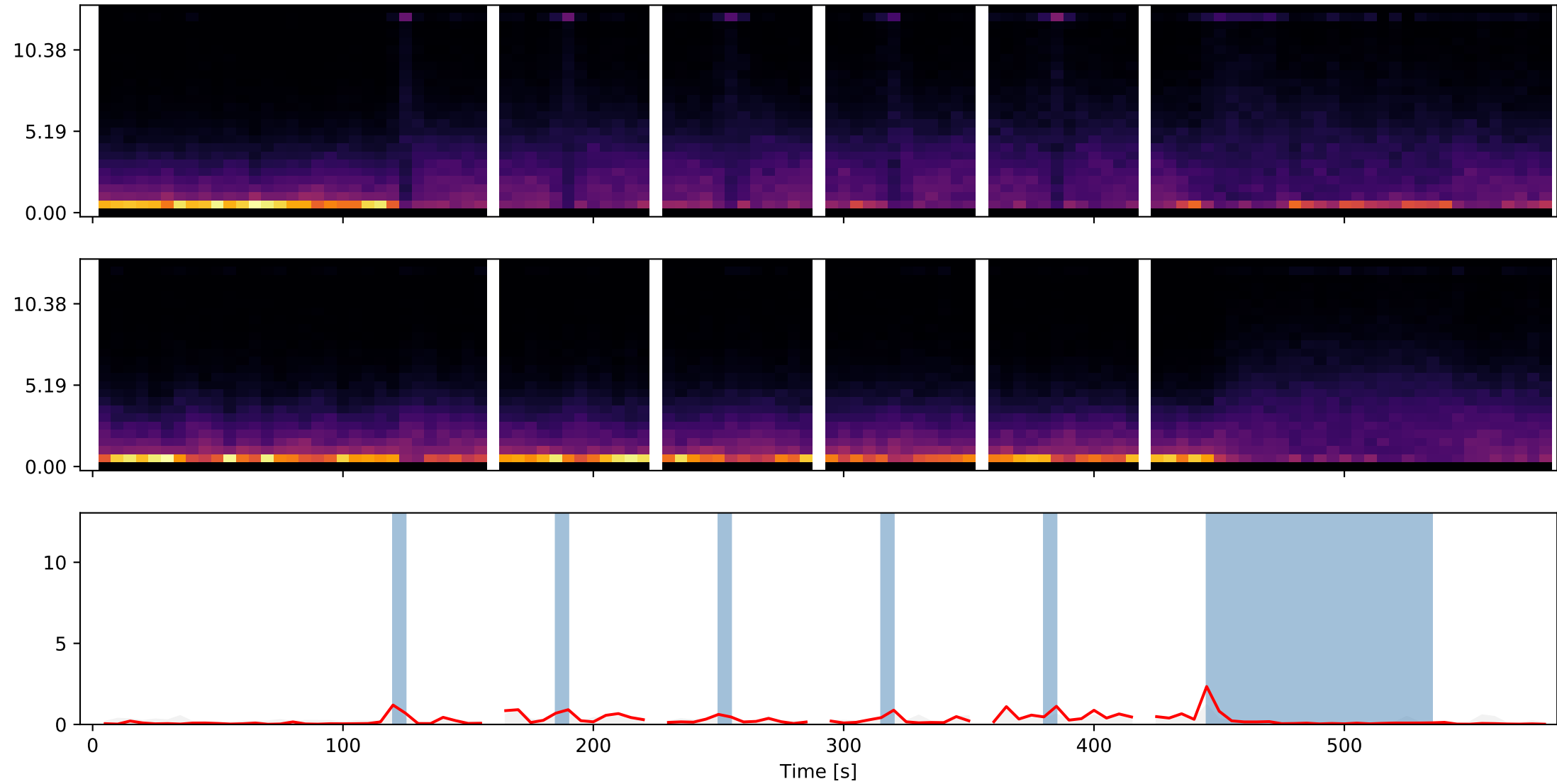
d\_speed\_head\_base



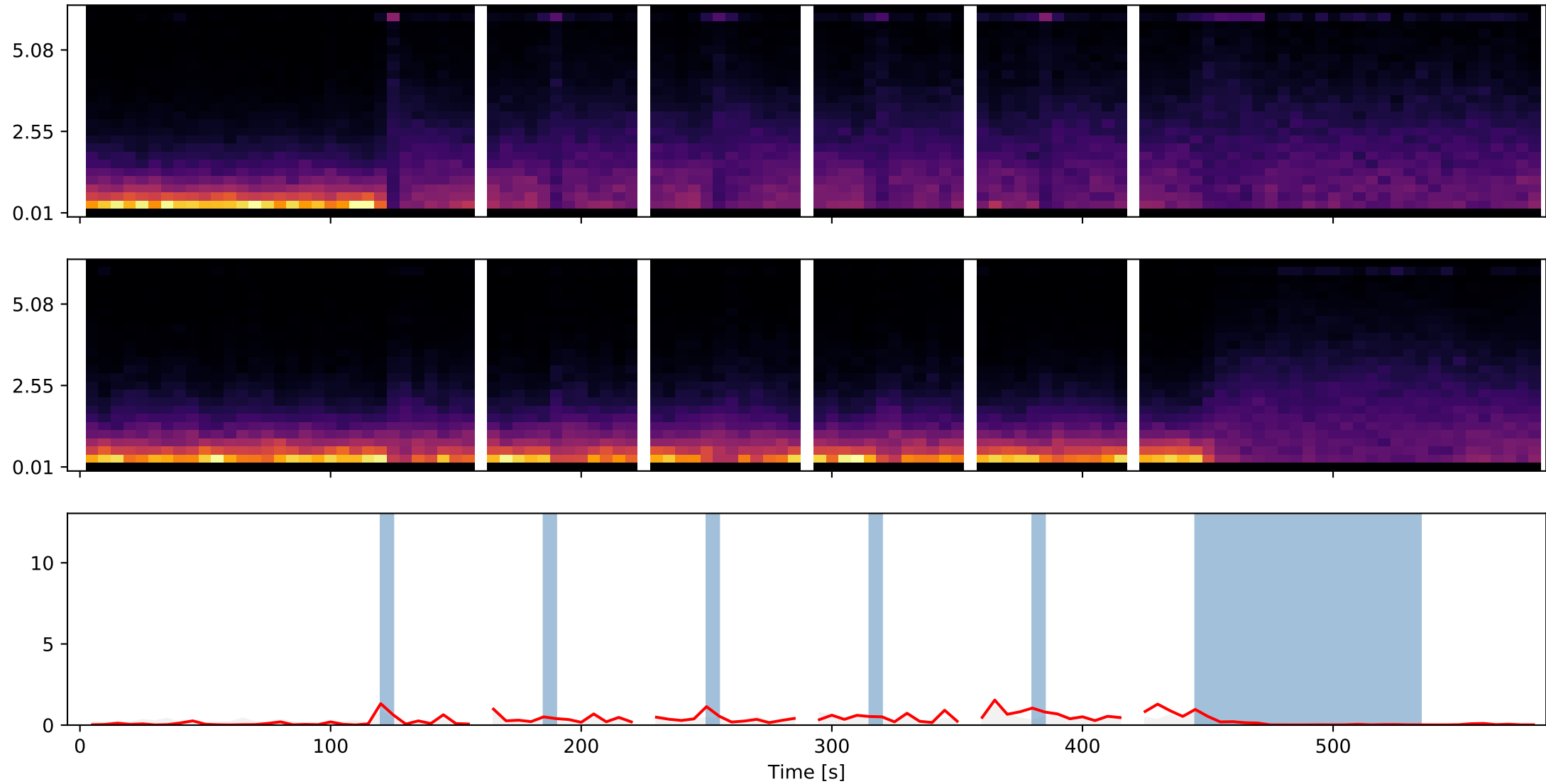
d\_eigen\_projection\_4



d\_angular\_velocity\_tail\_tip

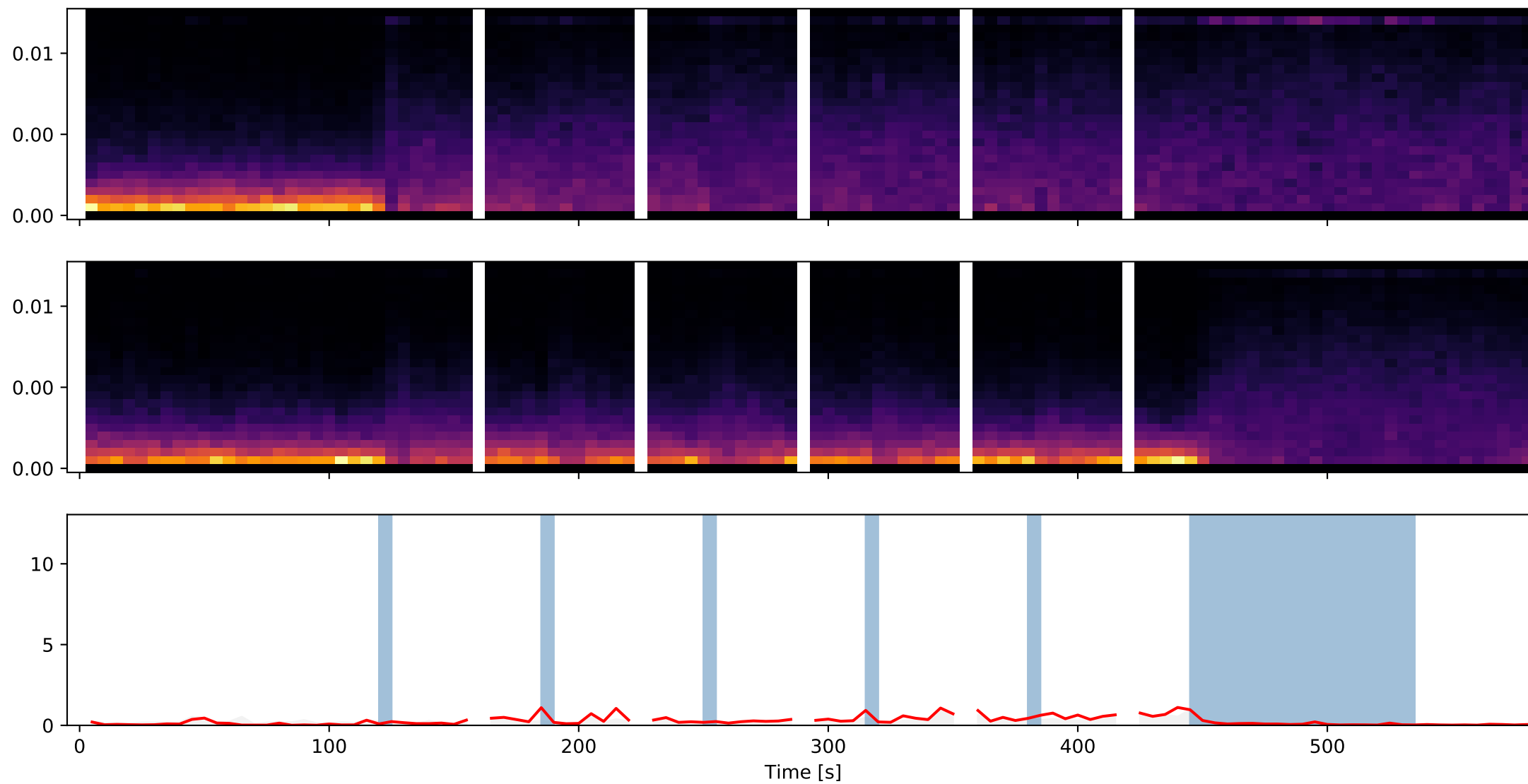


d\_relative\_to\_tail\_base\_angular\_velocity\_tail\_tip

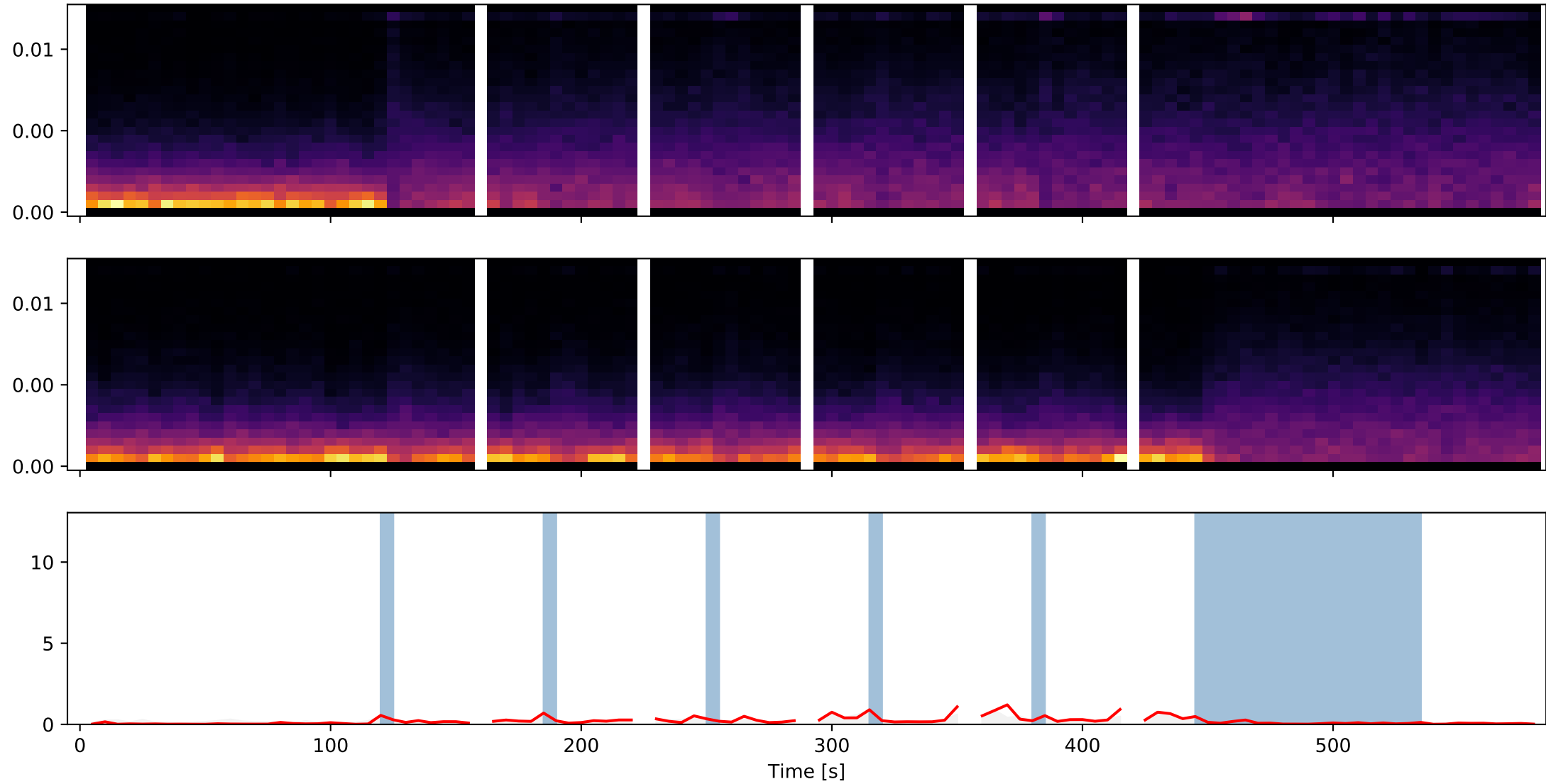




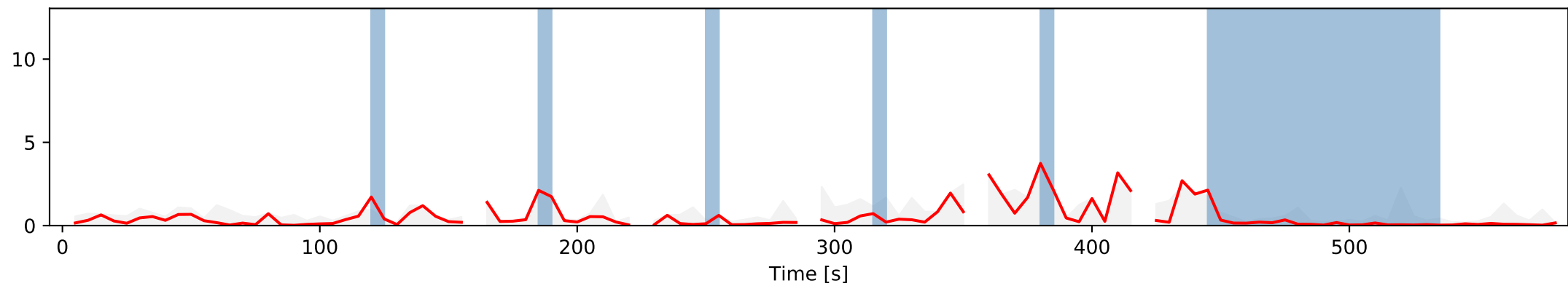
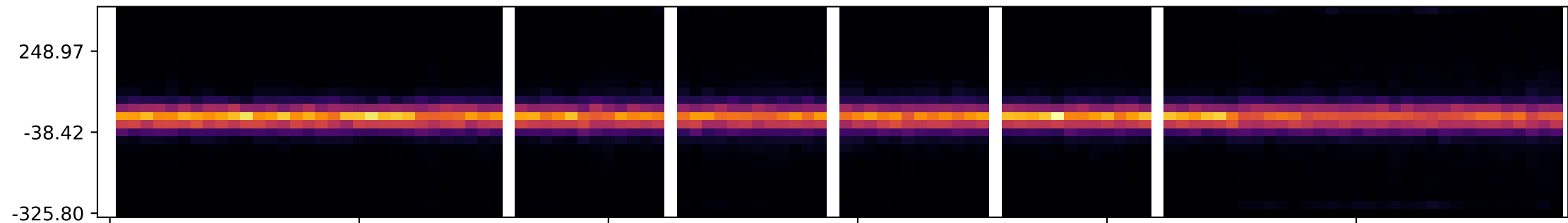
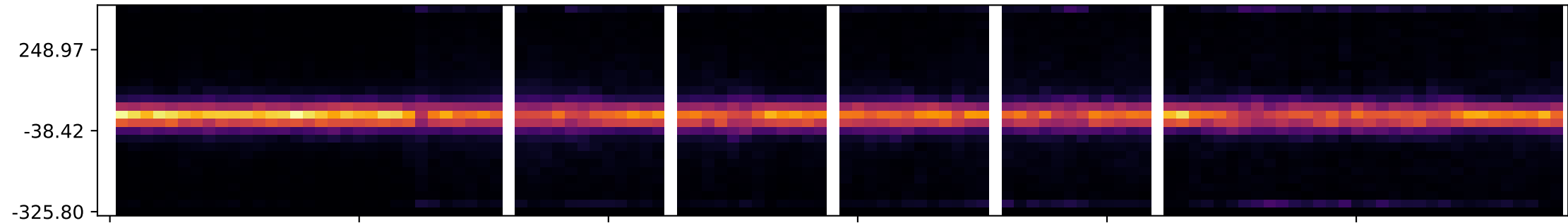
d\_curvature\_std\_neck



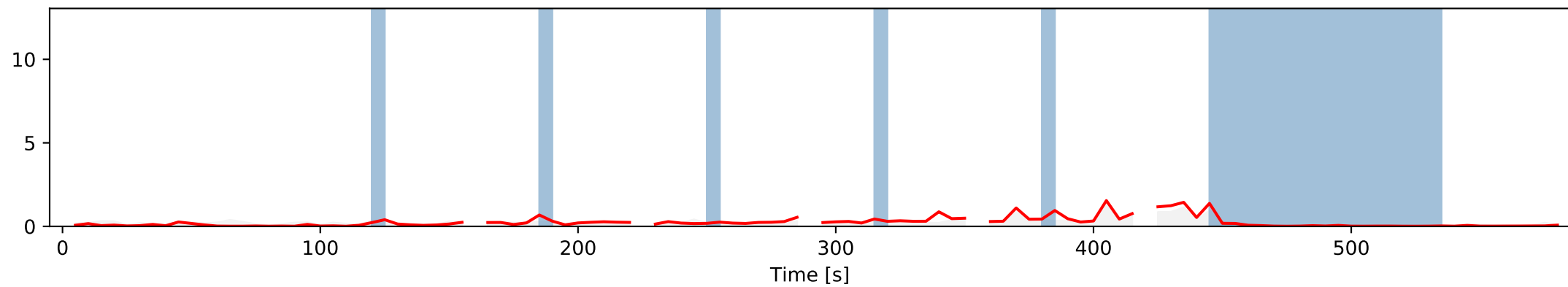
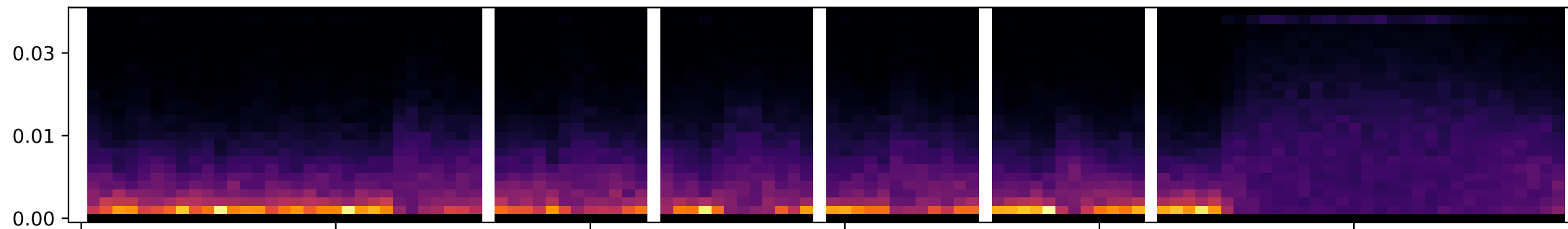
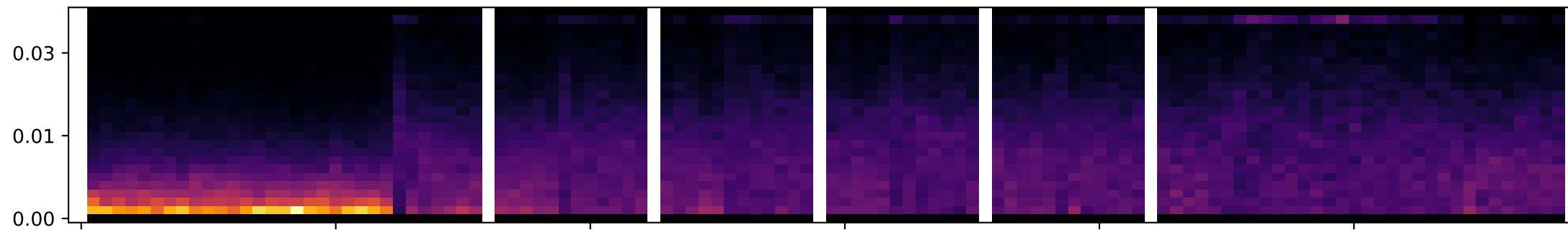
d\_curvature\_std\_tail



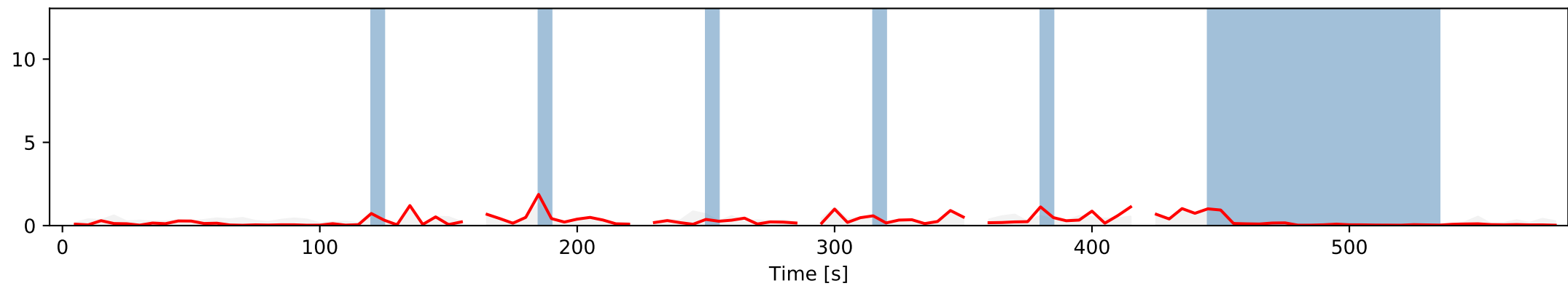
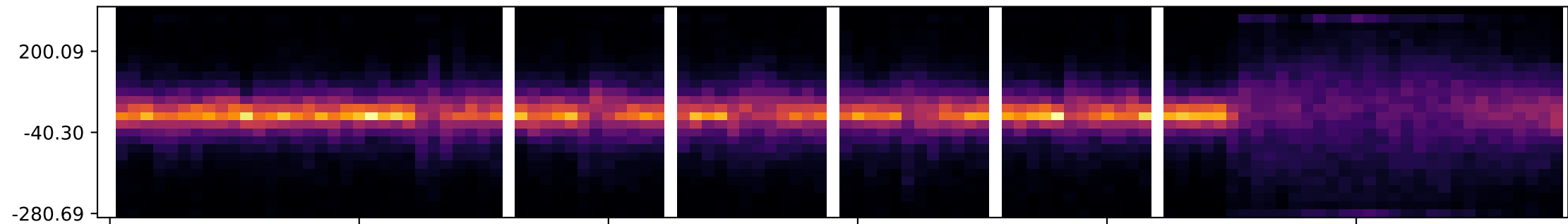
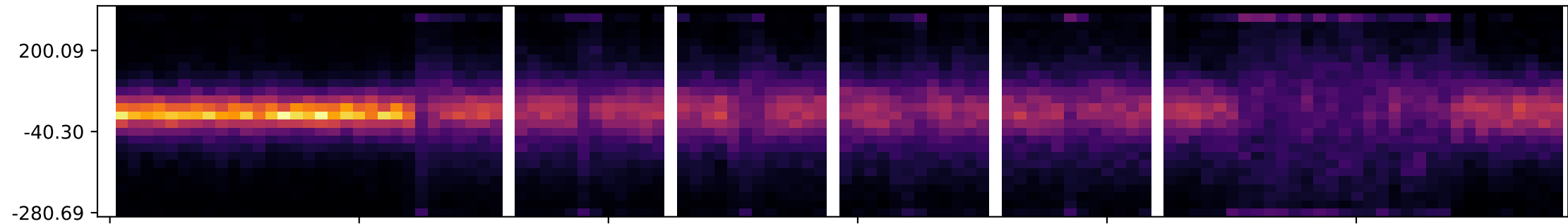
d\_length



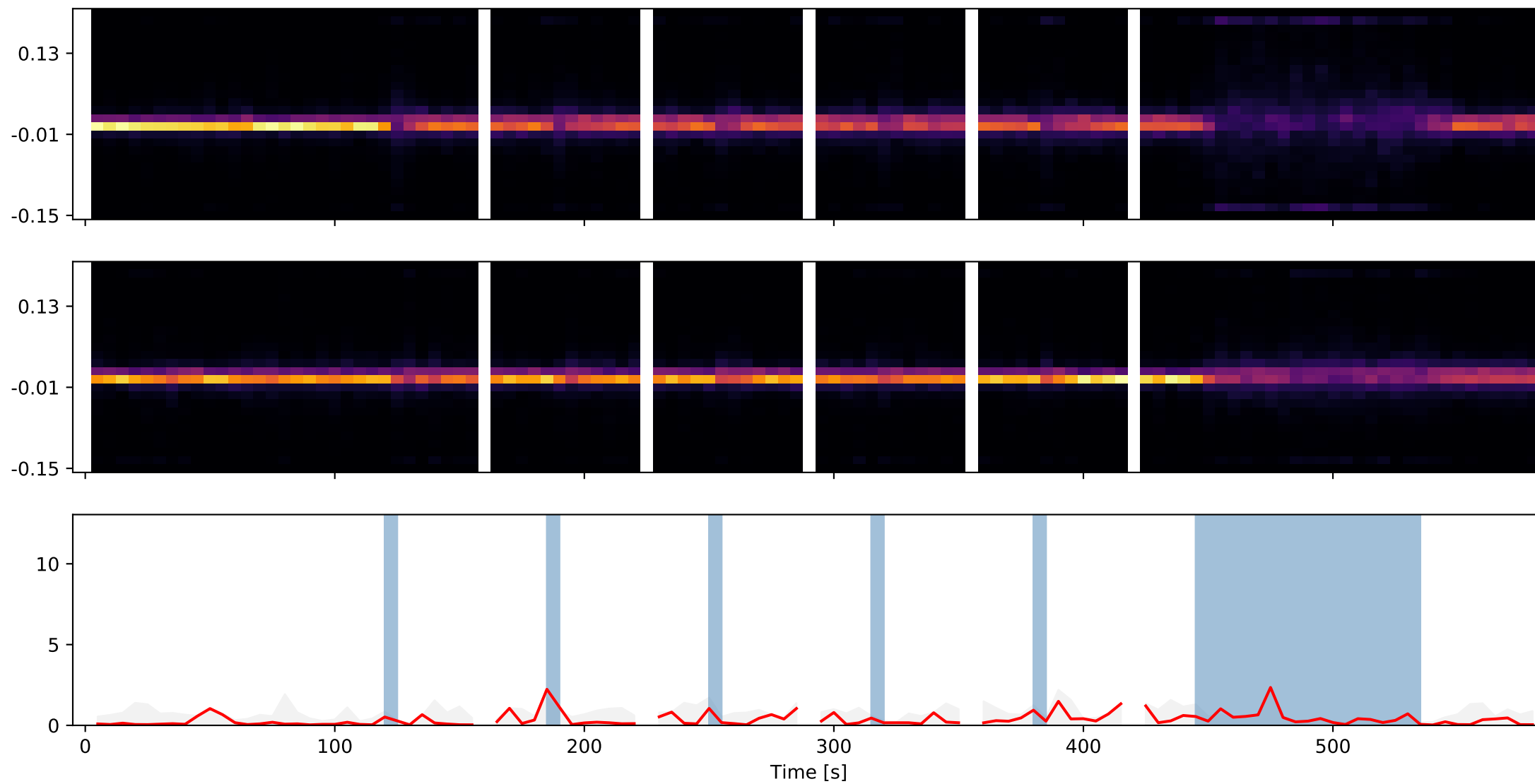
d\_curvature\_head



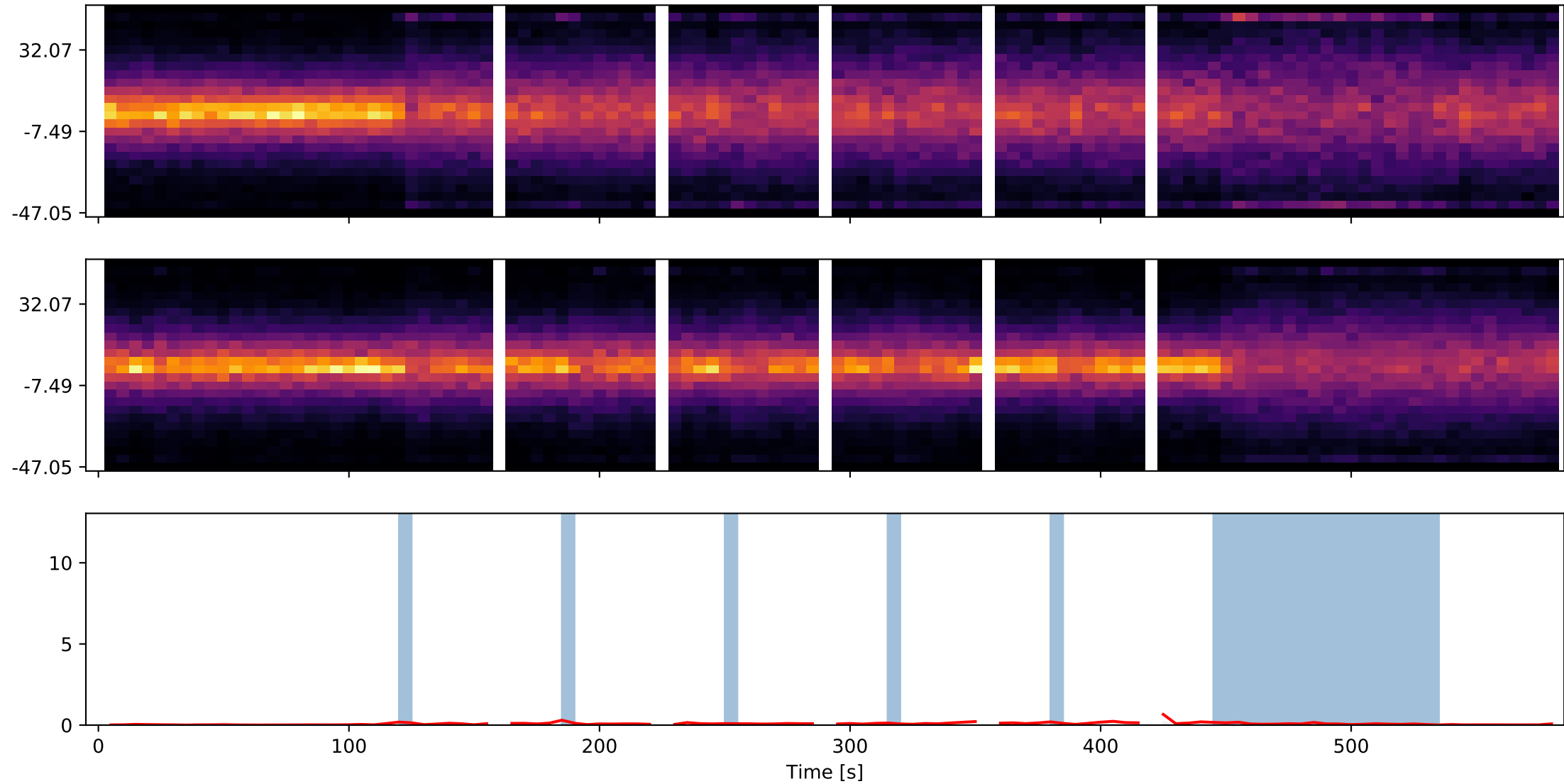
d\_major\_axis



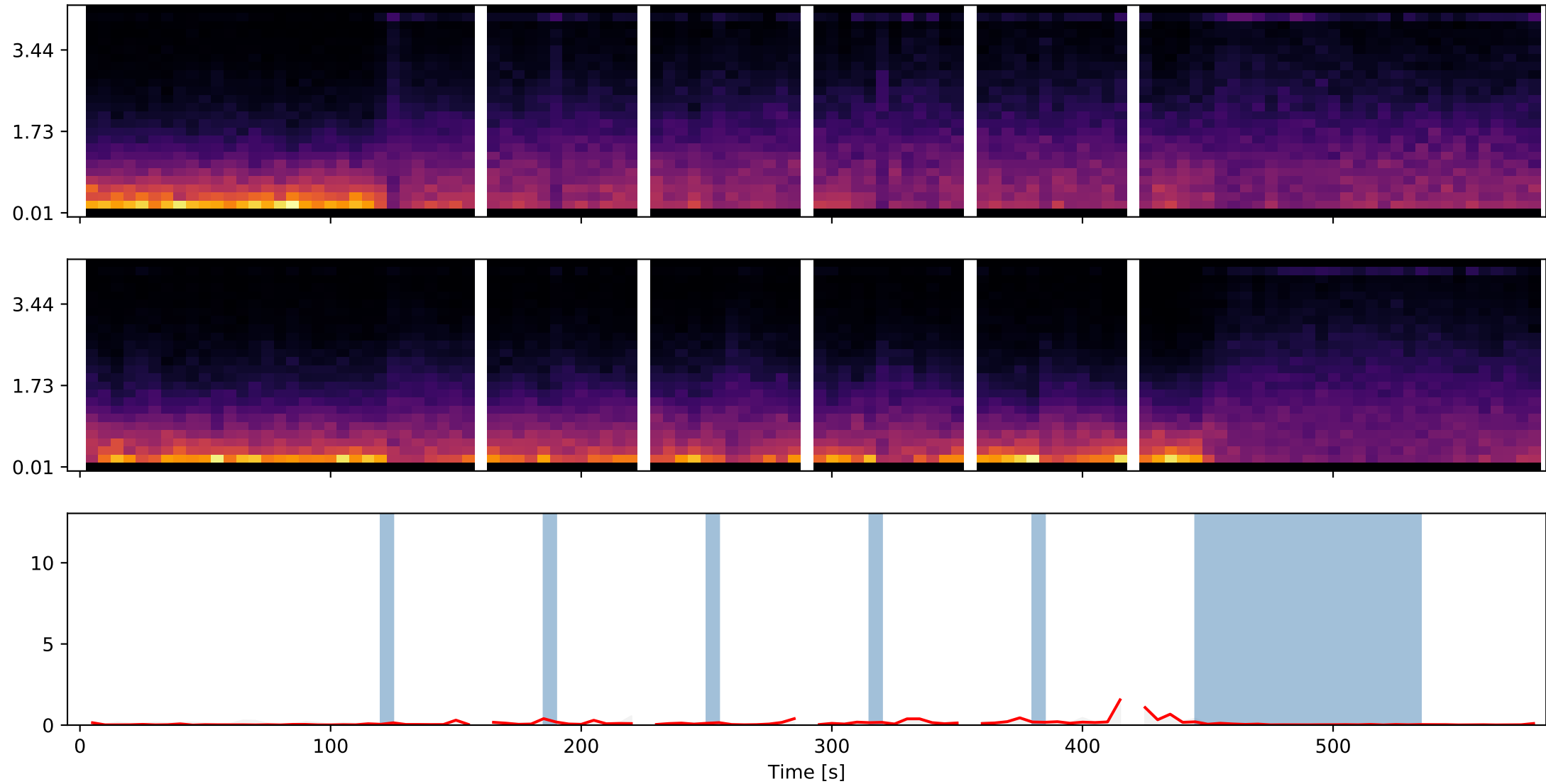
d\_quirkiness



d\_width\_head\_base

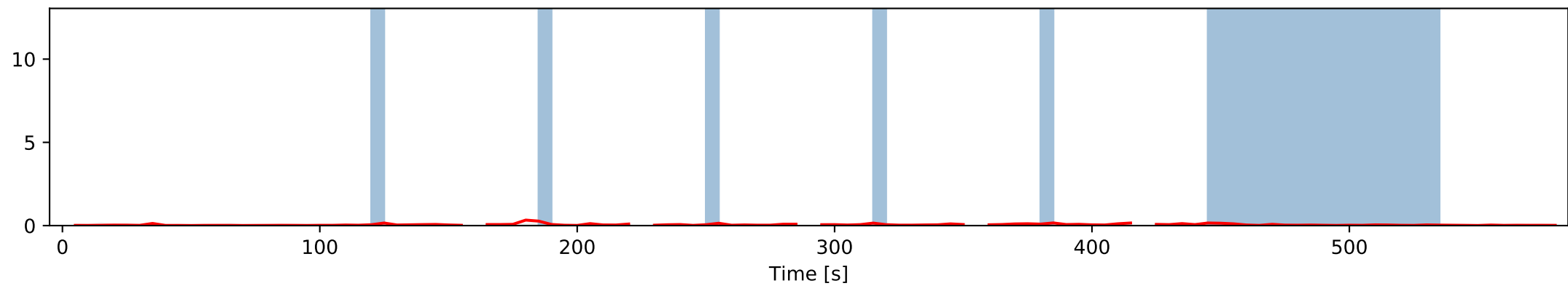
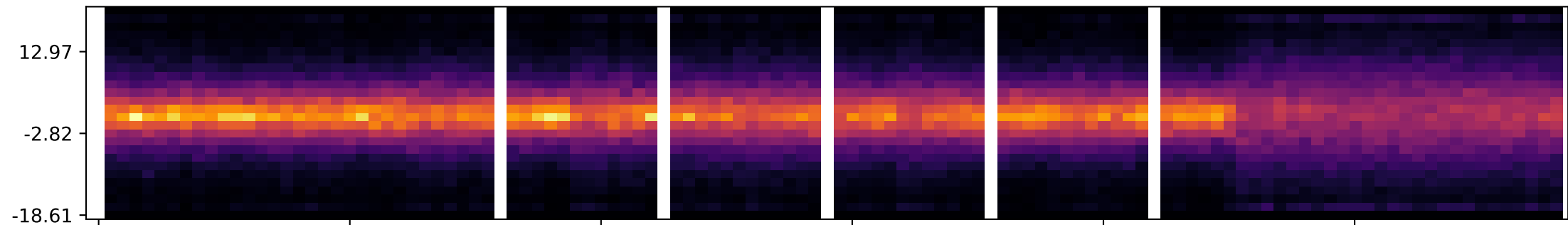
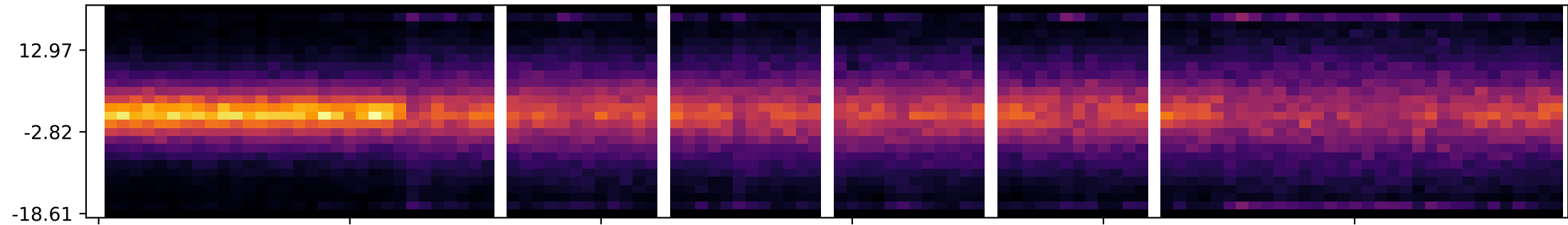


d\_eigen\_projection\_5

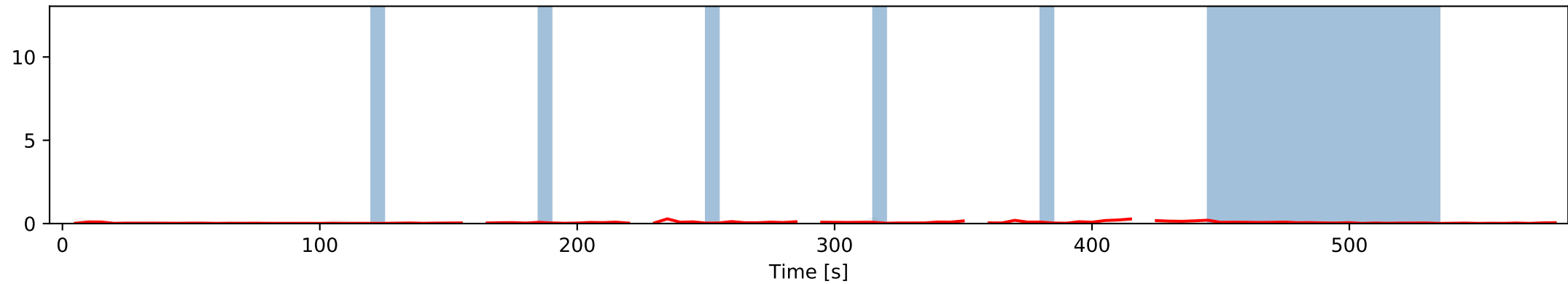
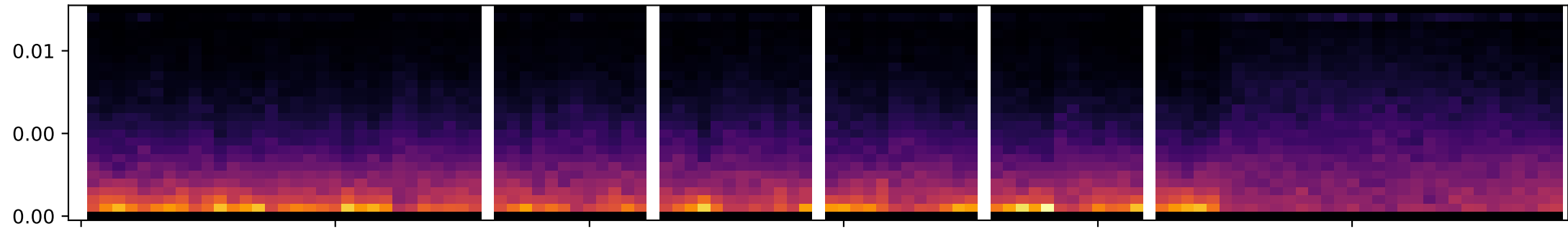
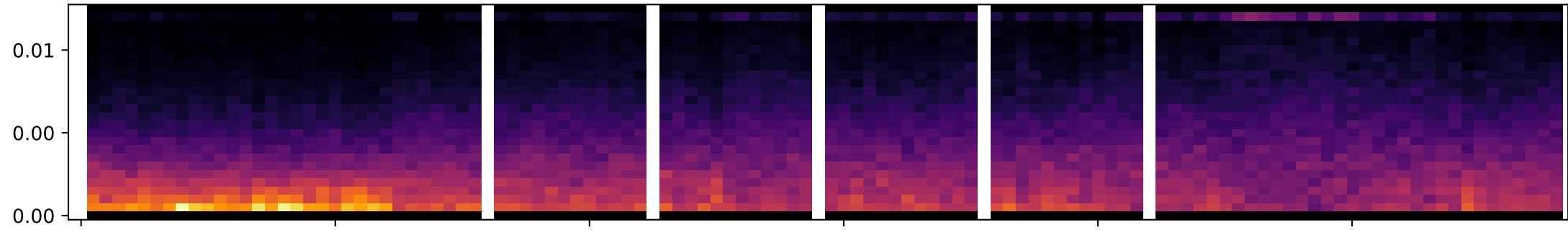




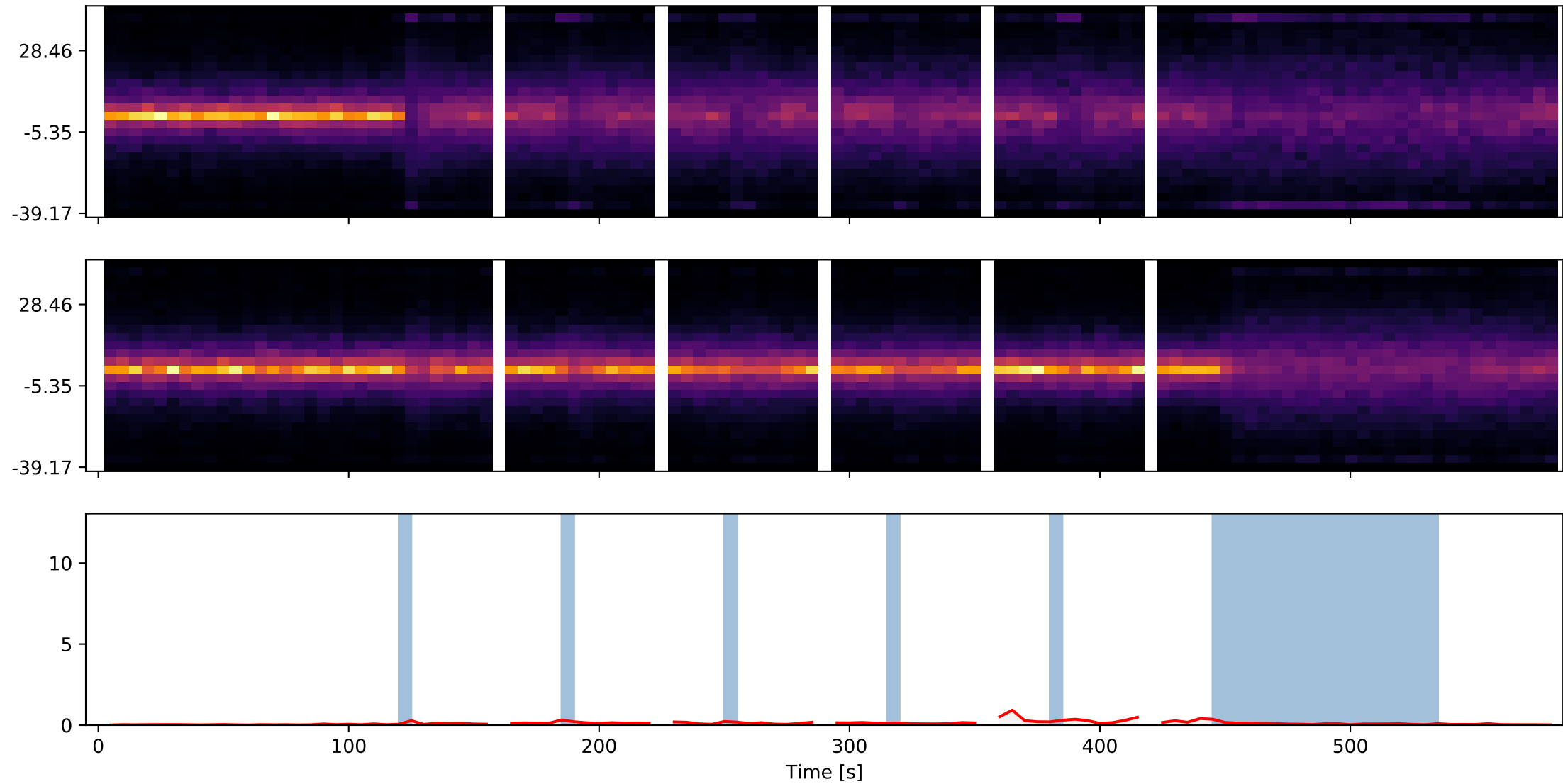
d\_width\_midbody



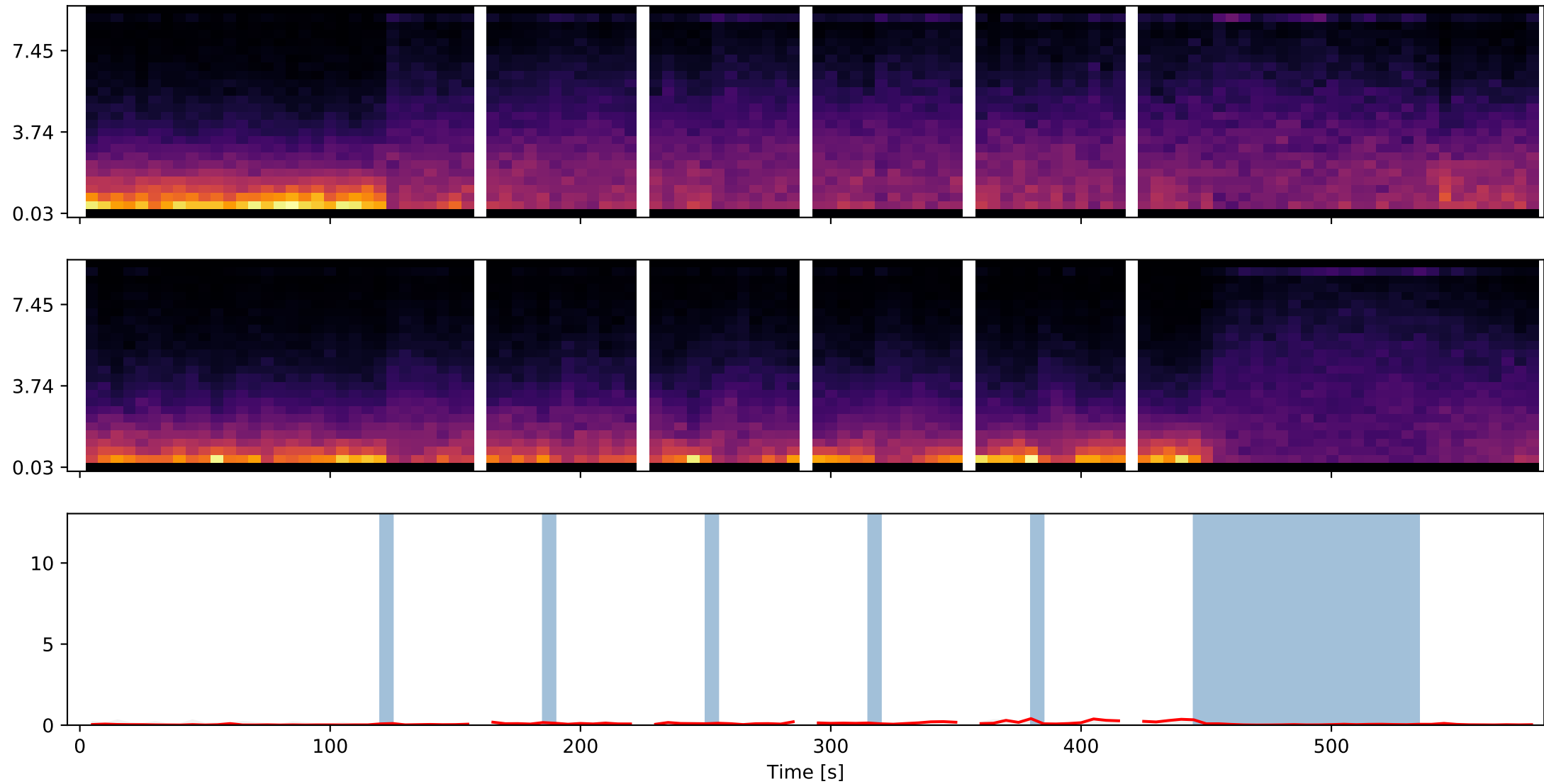
d\_curvature\_std\_head



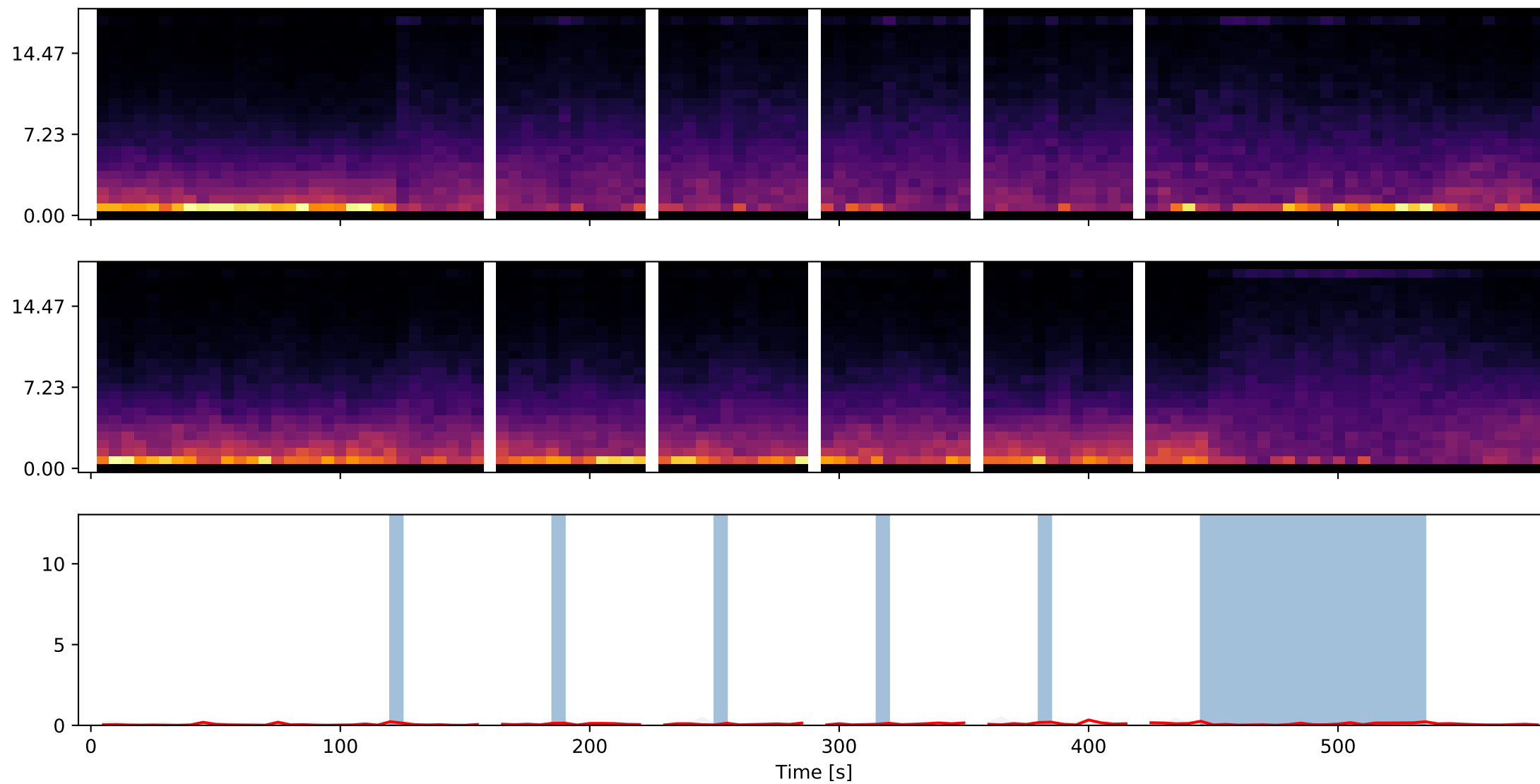
d\_width\_tail\_base



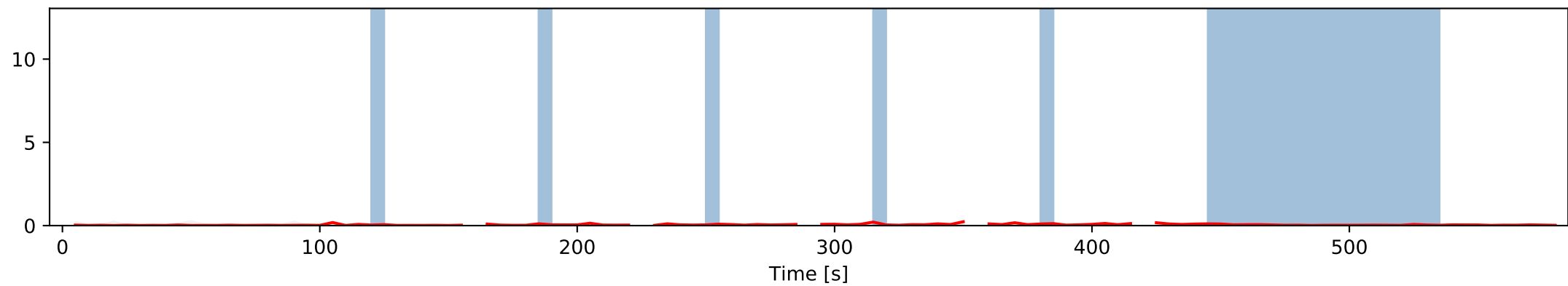
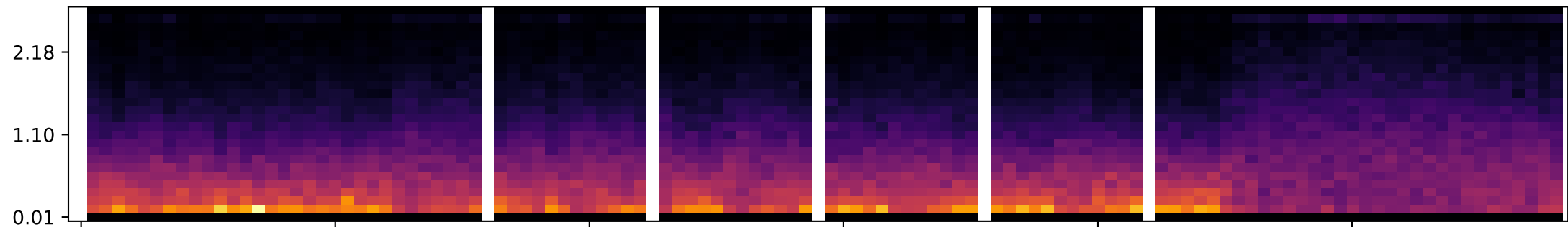
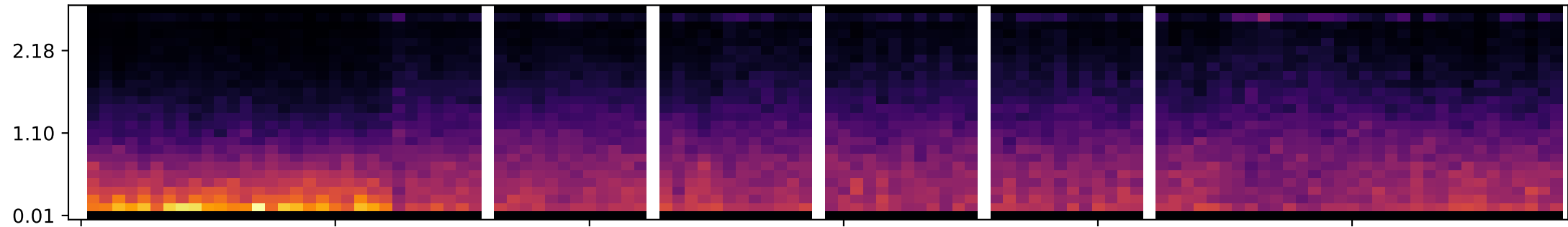
d\_relative\_to\_head\_base\_angular\_velocity\_head\_tip



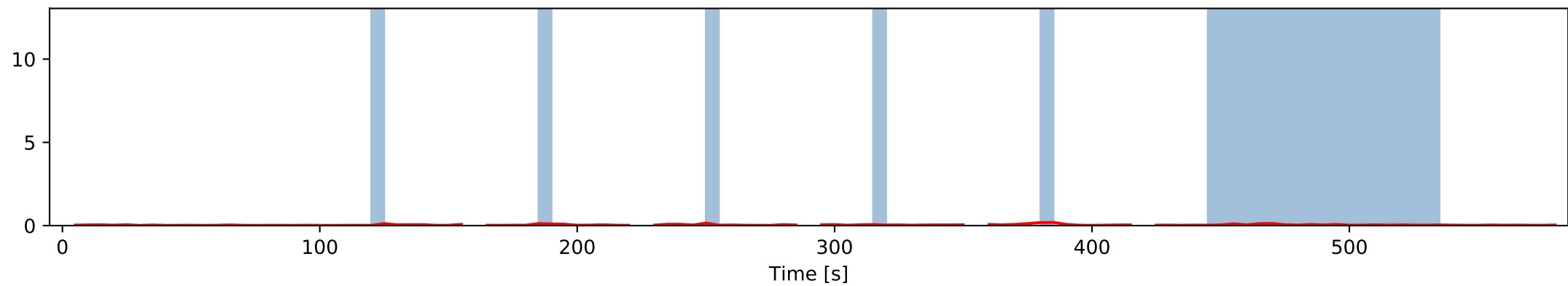
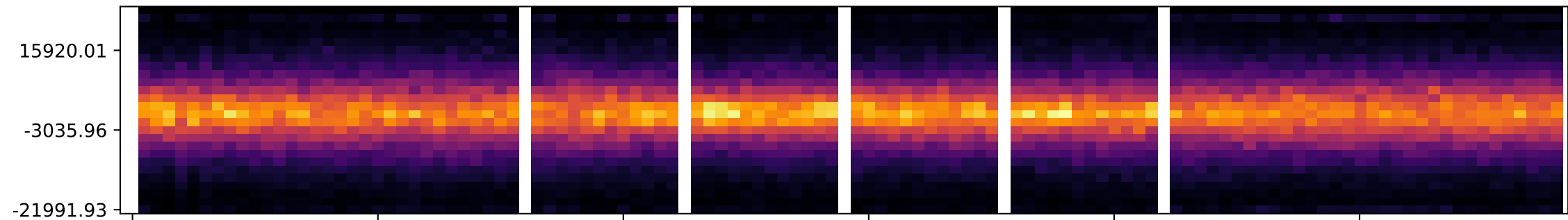
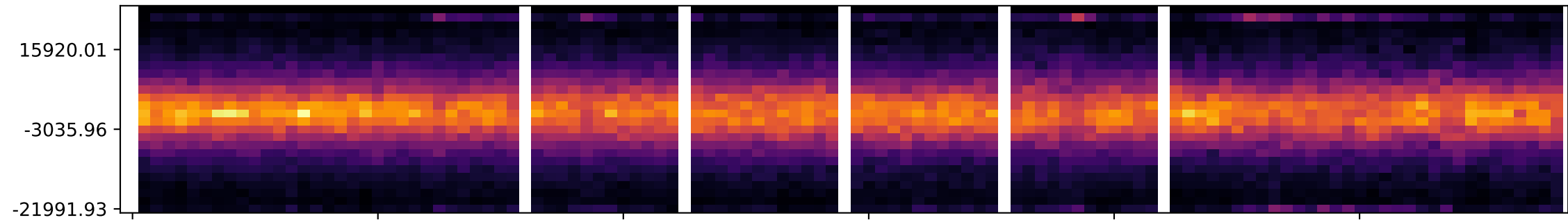
d\_angular\_velocity\_head\_tip



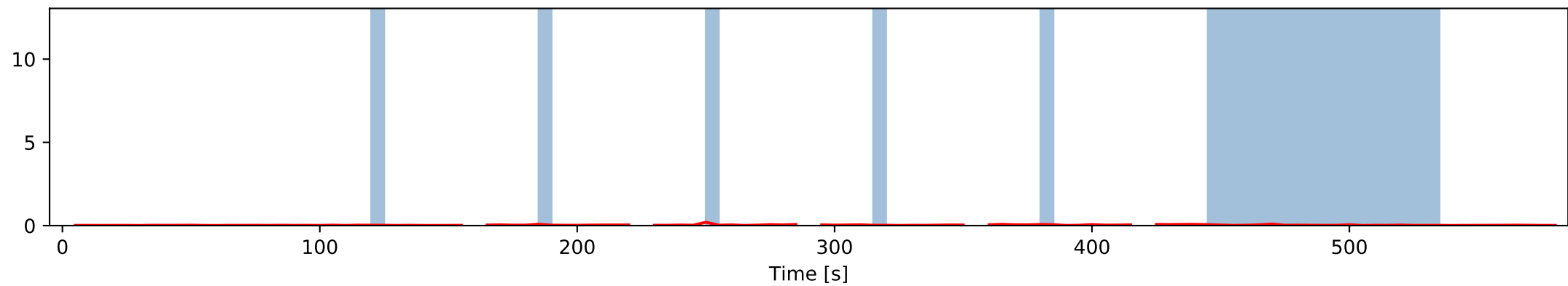
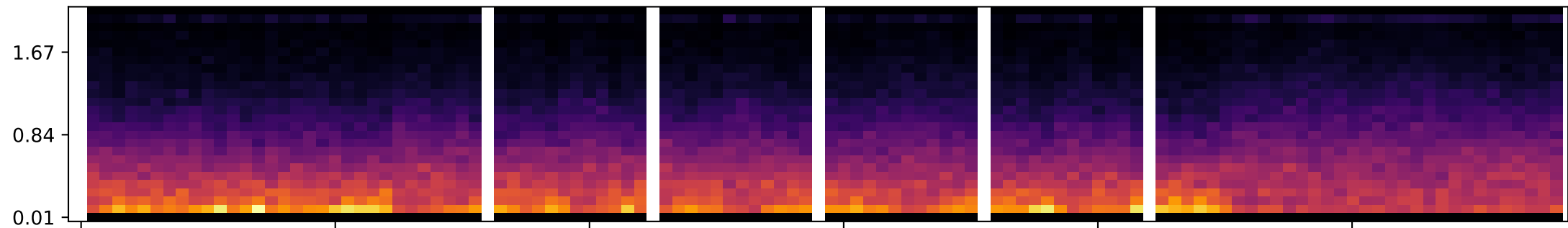
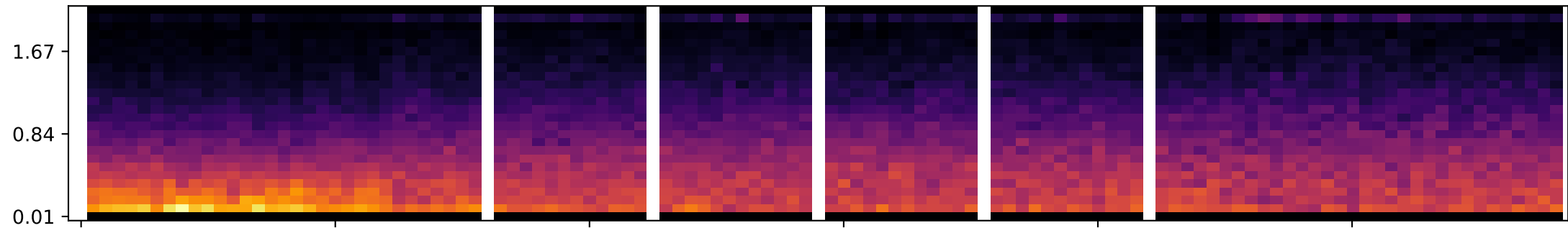
d\_eigen\_projection\_6



d\_area

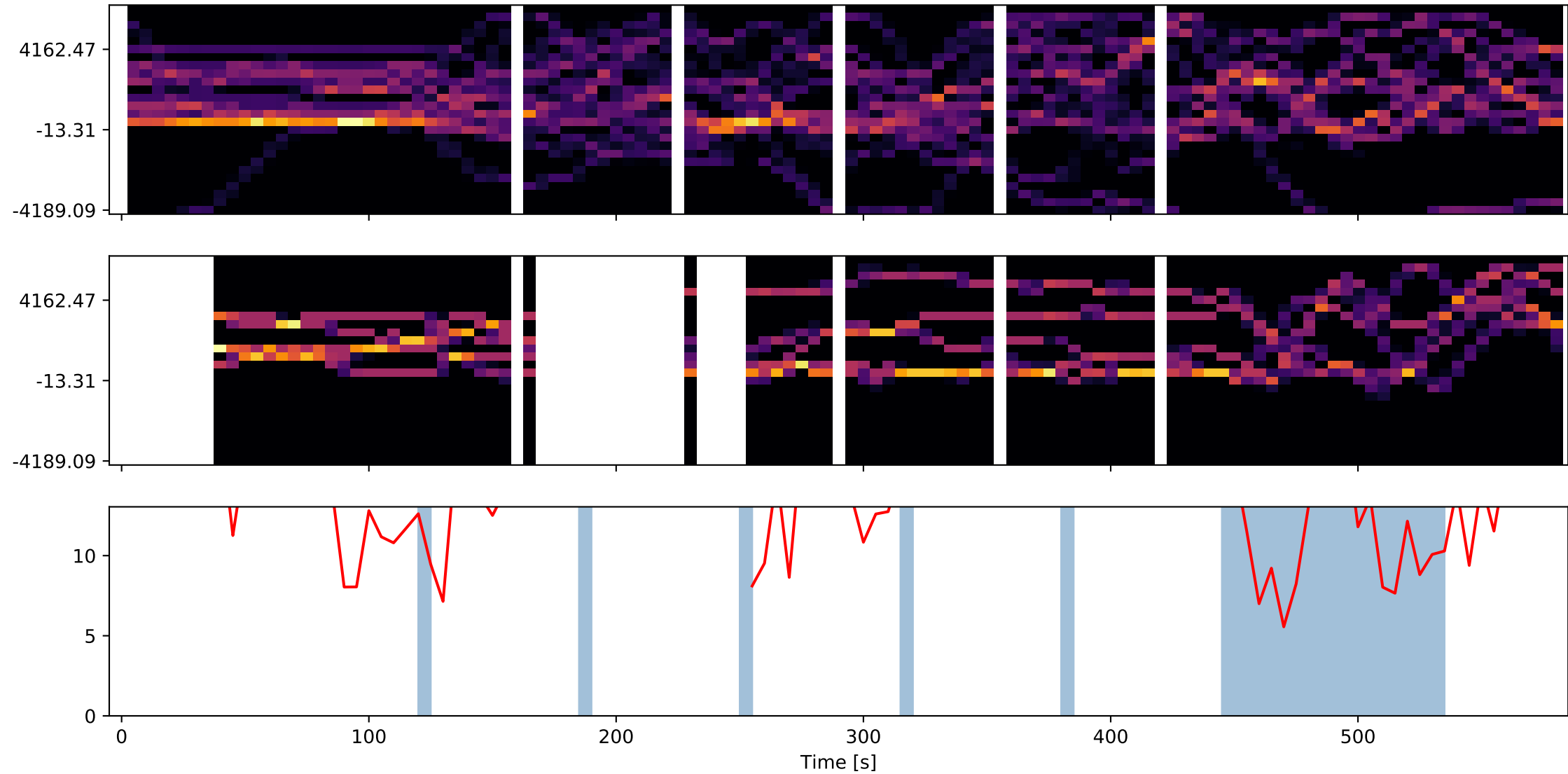


d\_eigen\_projection\_7

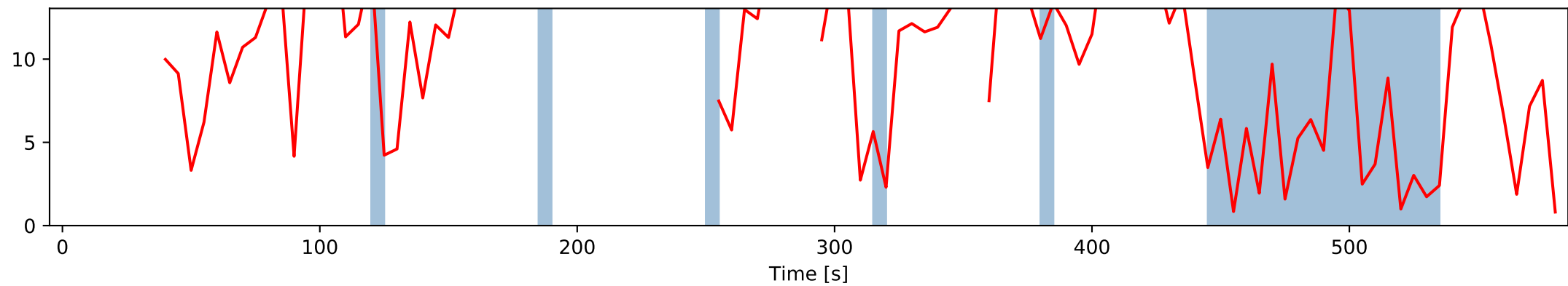
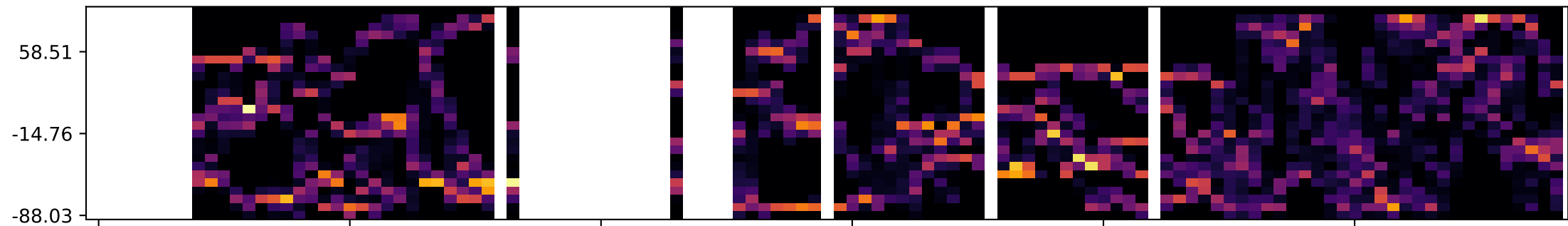
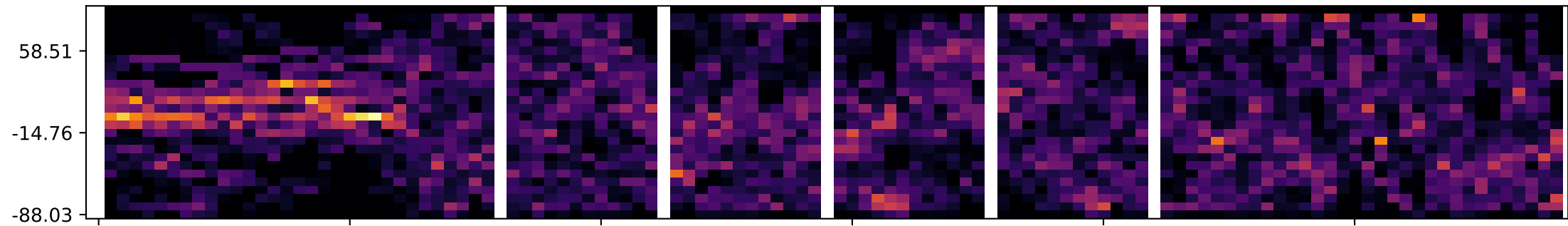




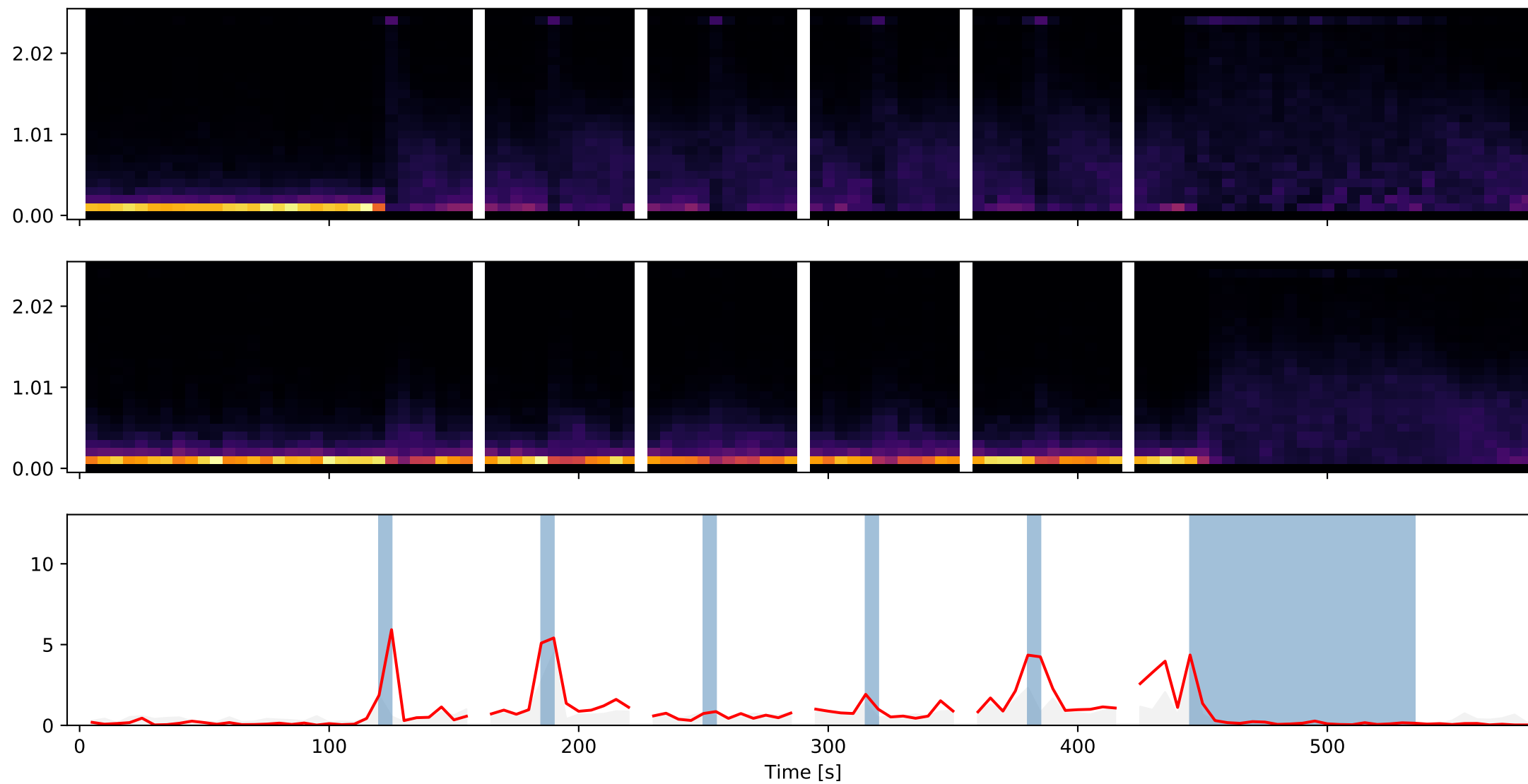
dist\_from\_food\_edge



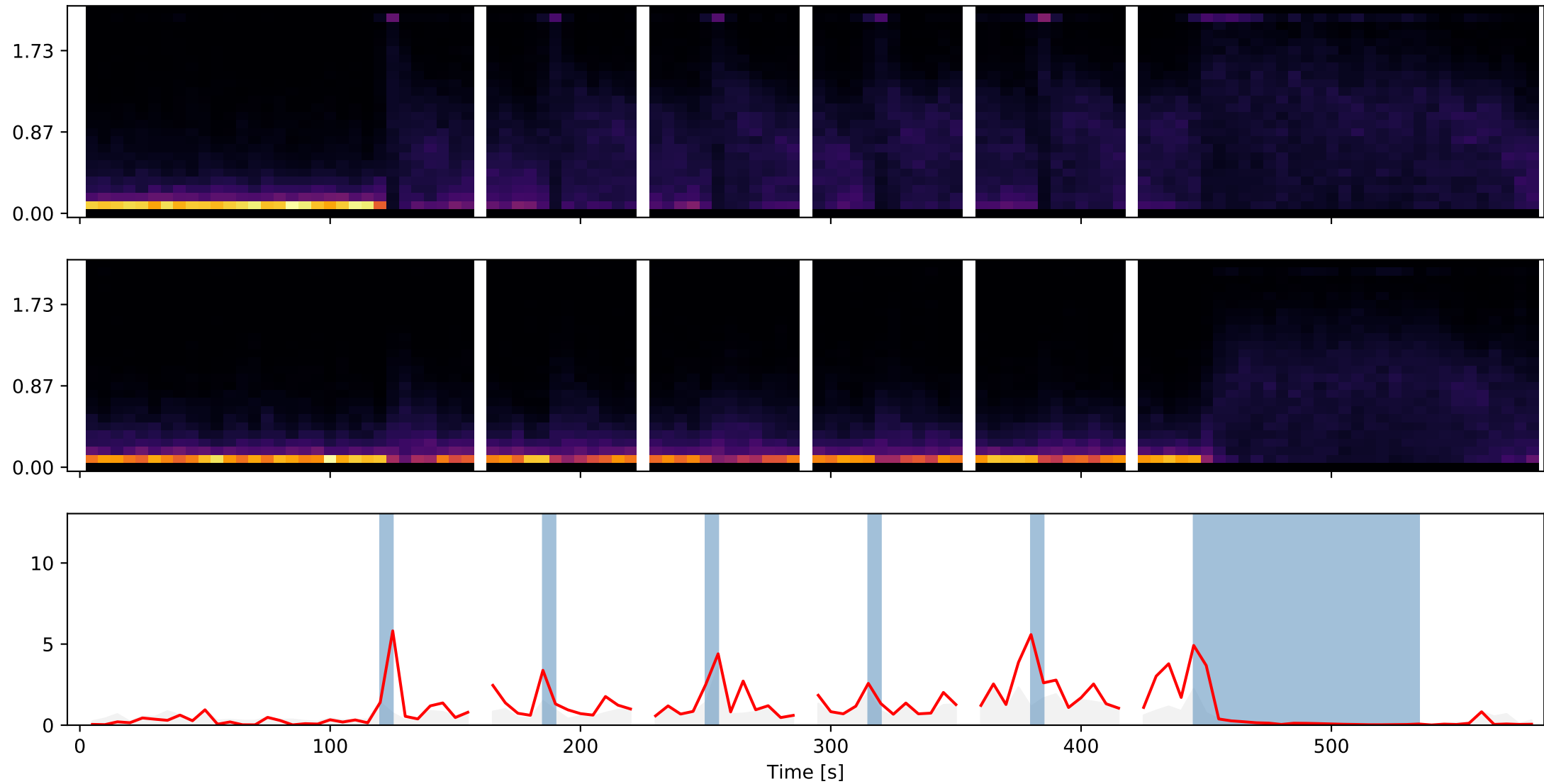
orientation\_food\_edge



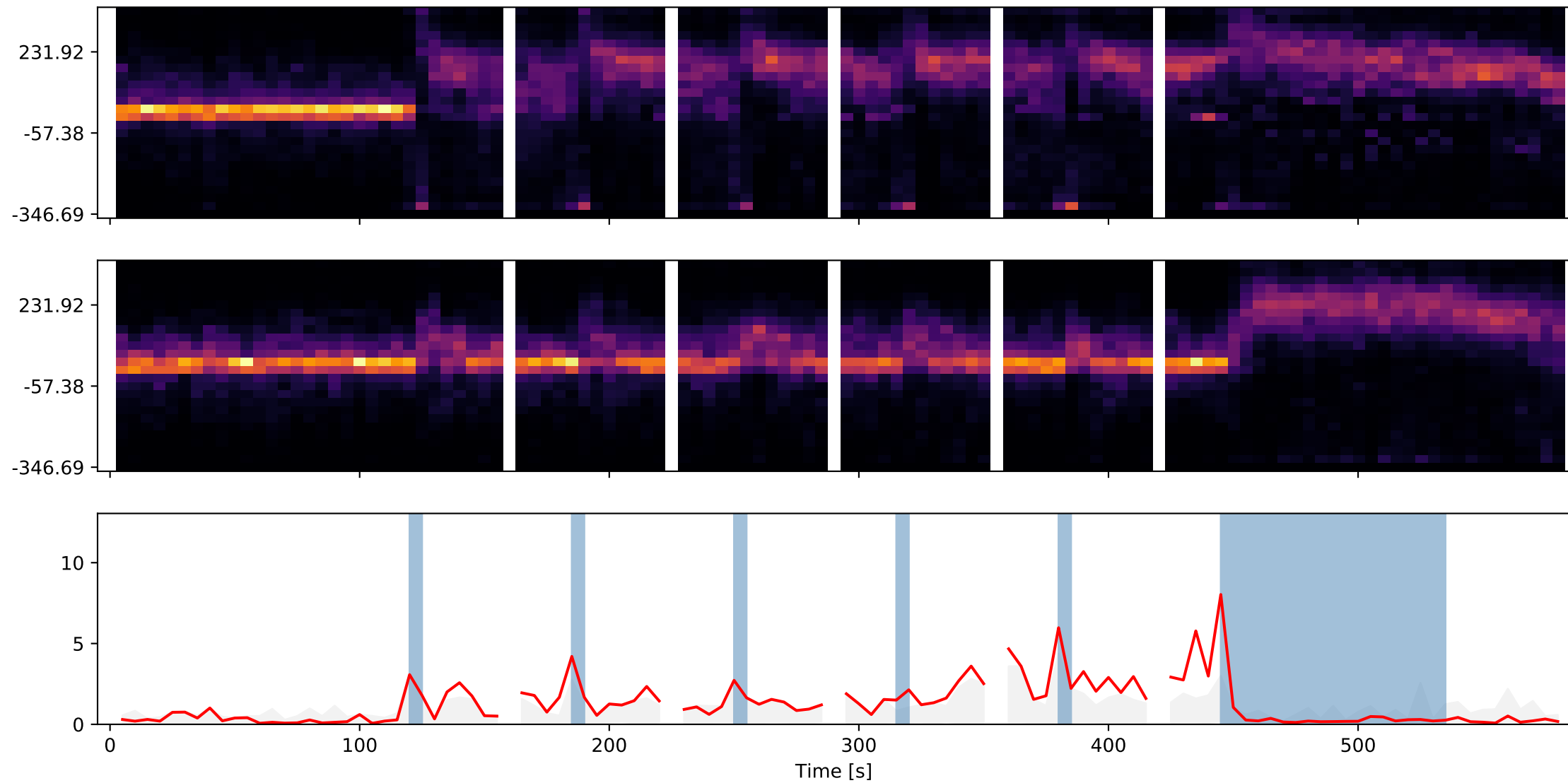
angular\_velocity\_hips



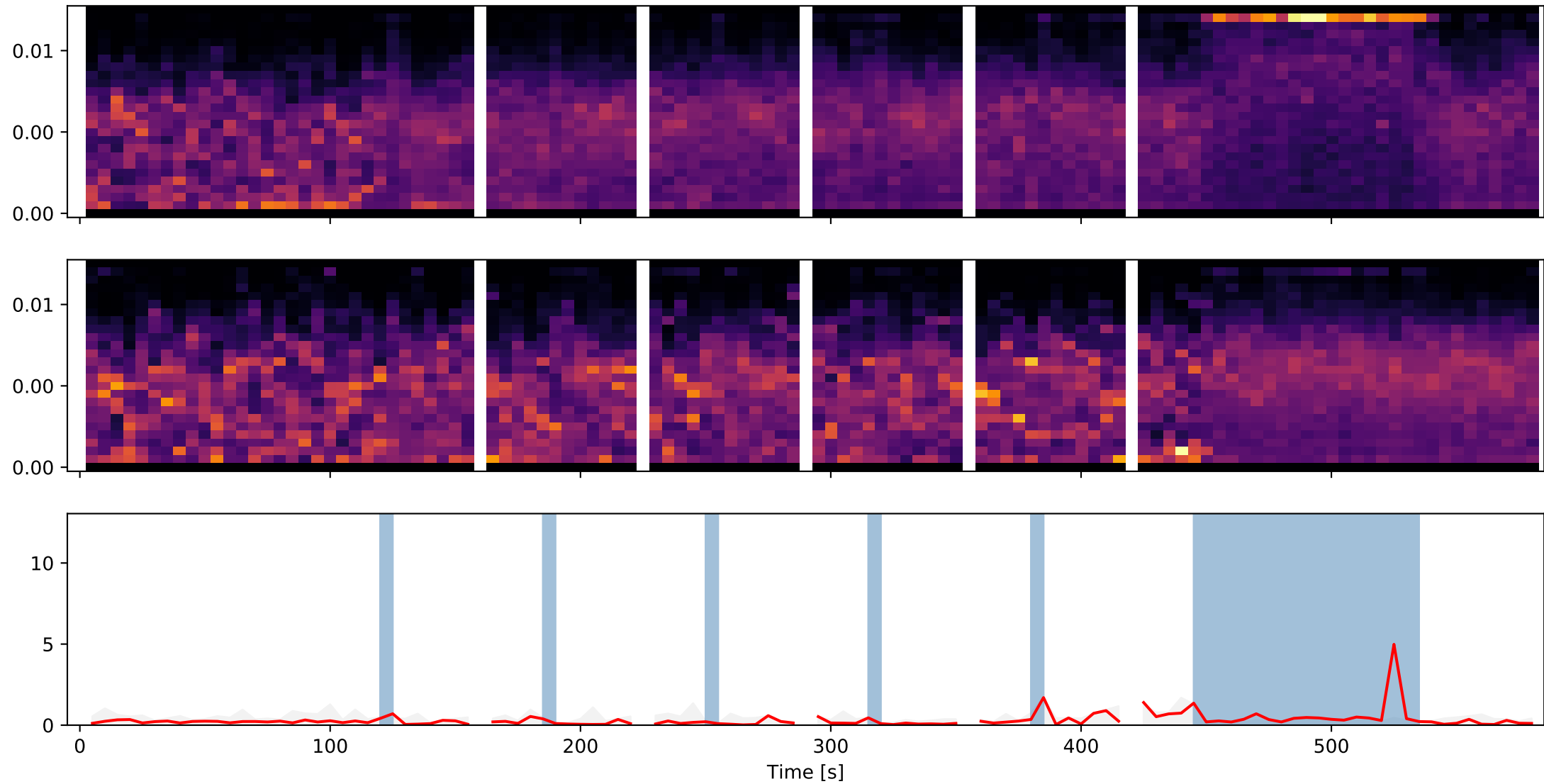
relative\_to\_hips\_angular\_velocity\_tail\_tip



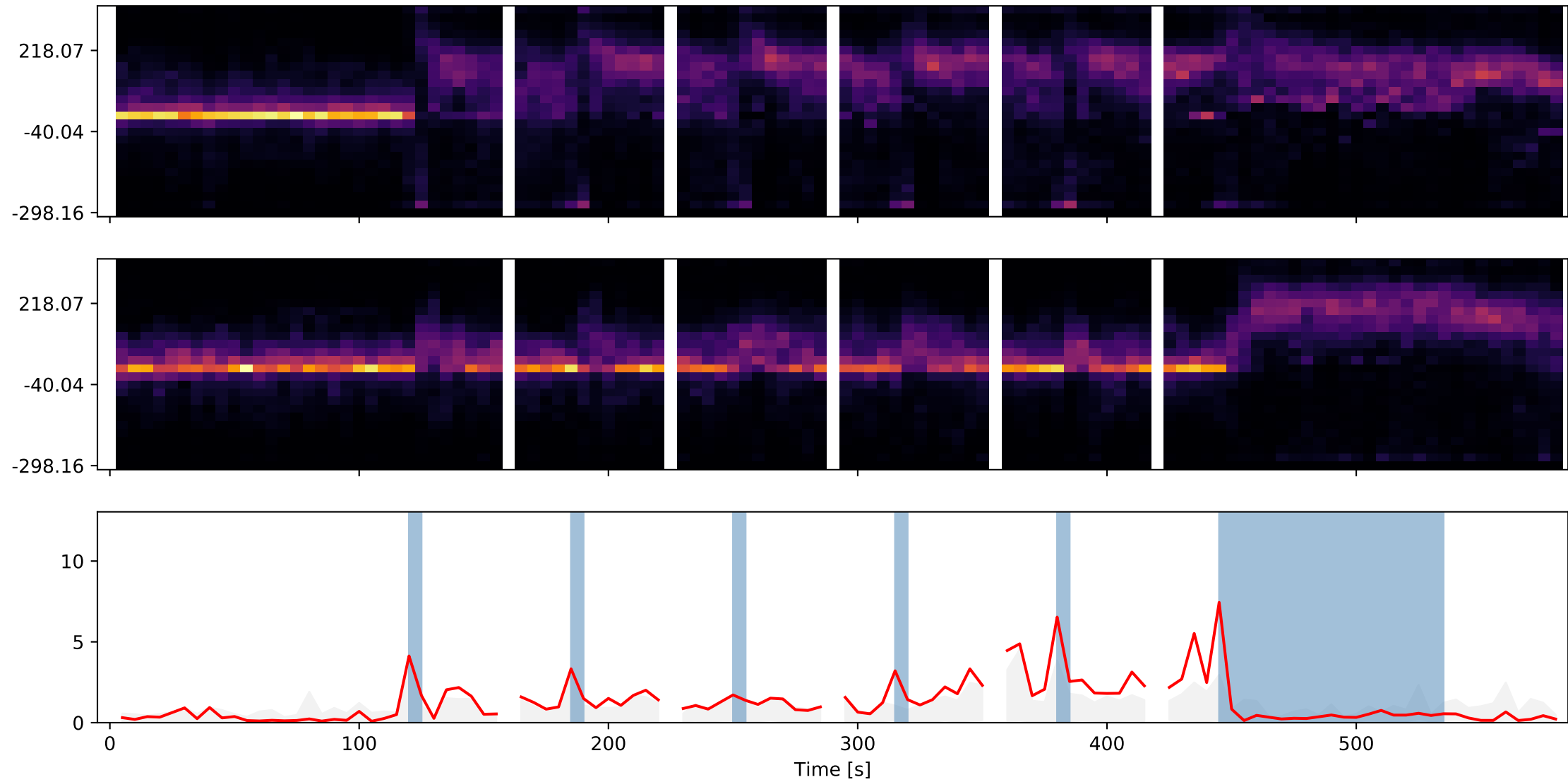
speed\_hips



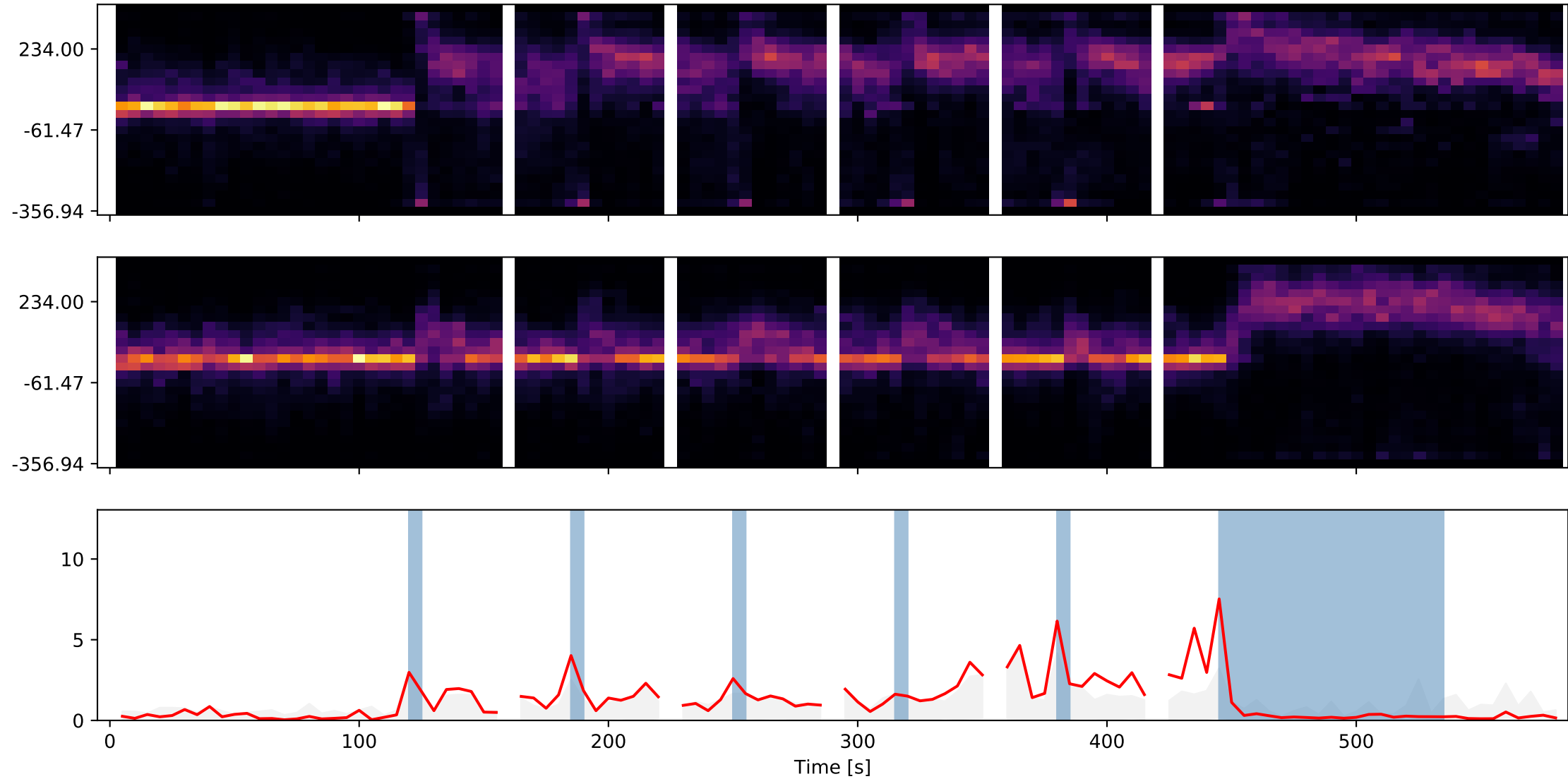
curvature\_mean\_neck



speed

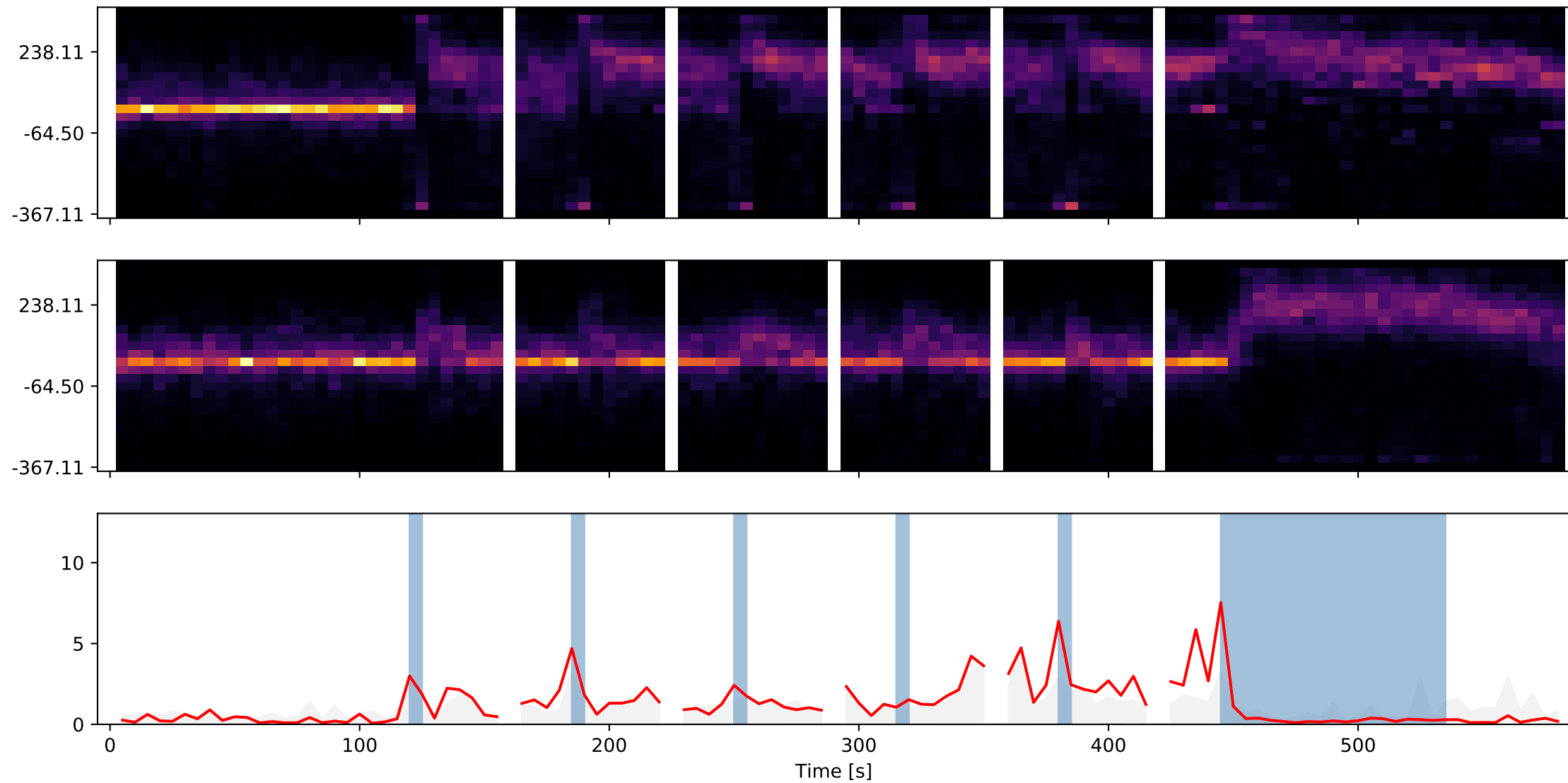


speed\_tail\_base

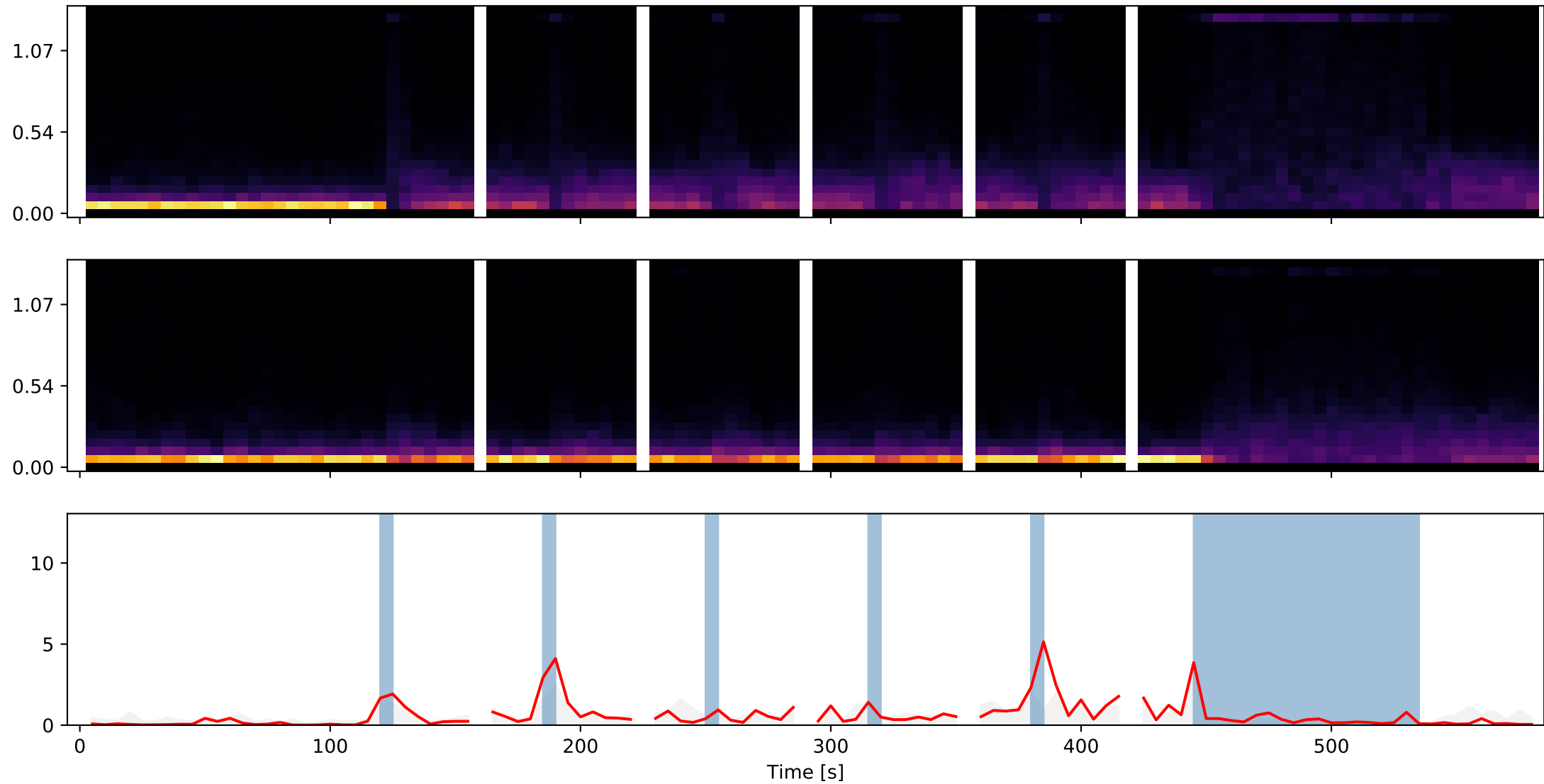




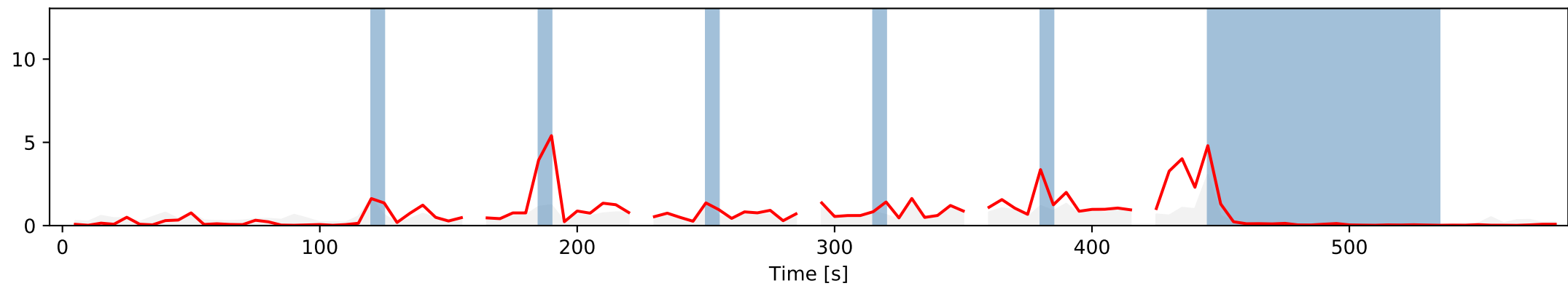
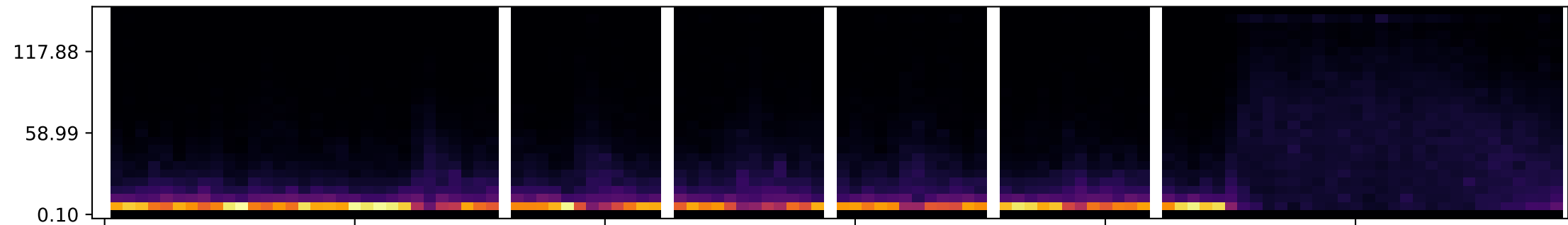
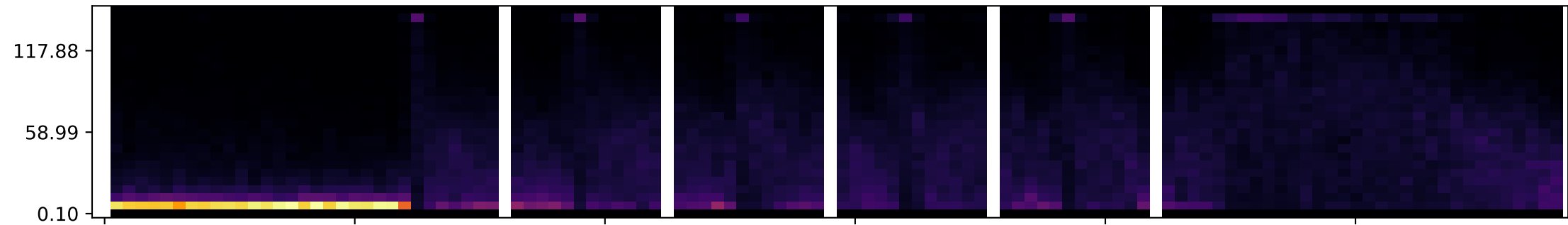
speed\_tail\_tip



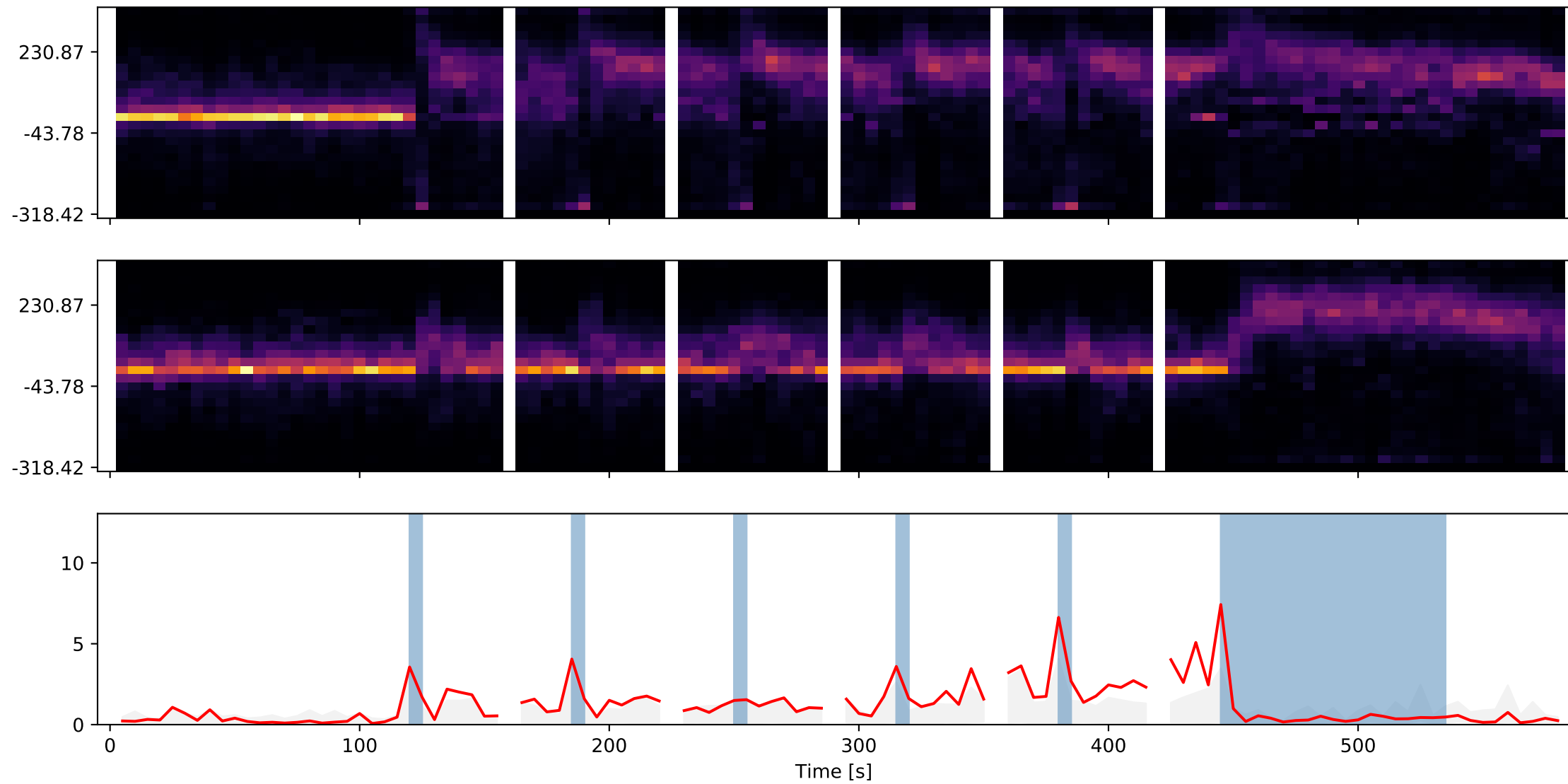
relative\_to\_body\_angular\_velocity\_tail\_tip



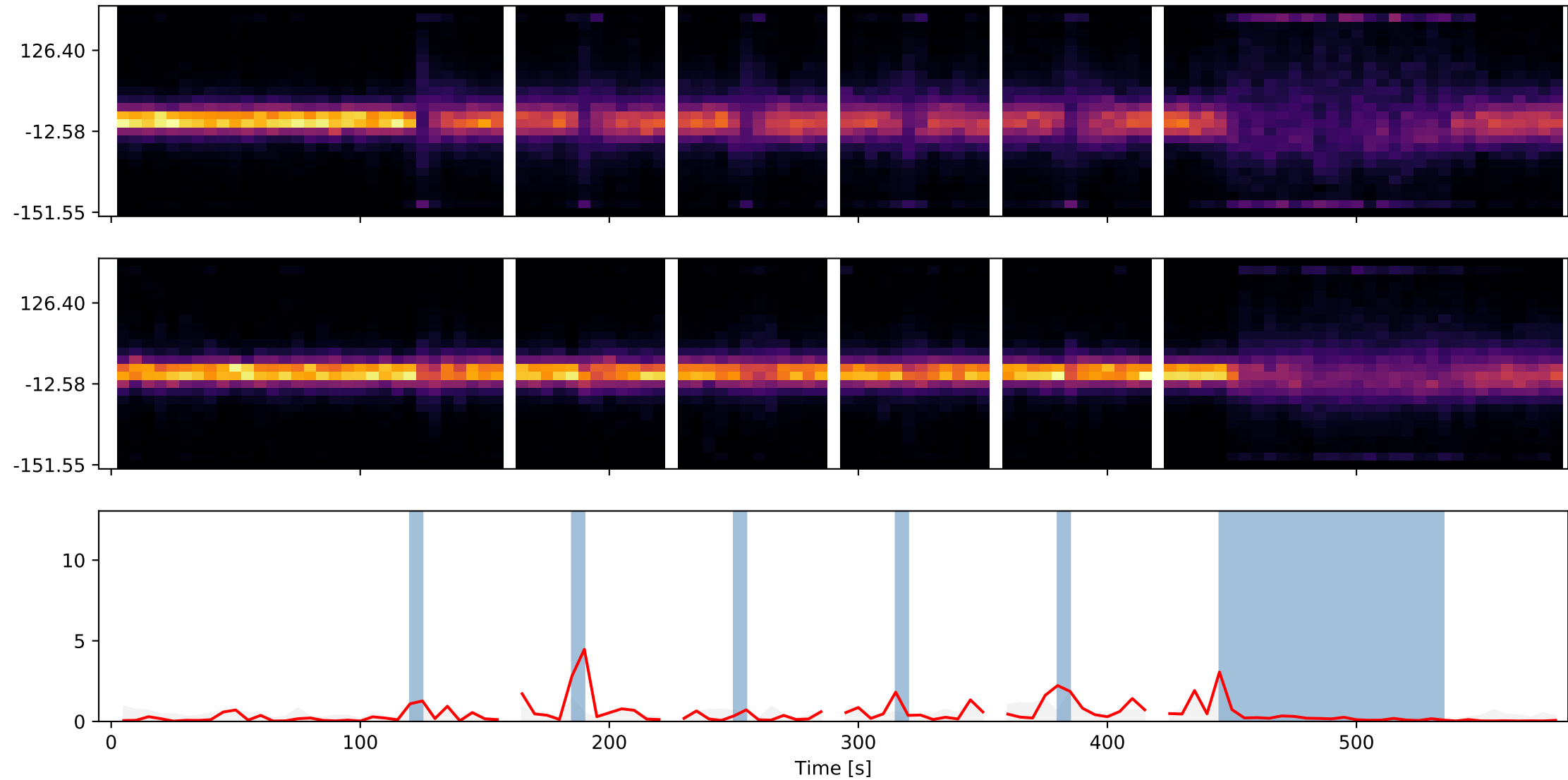
relative\_to\_body\_speed\_midbody



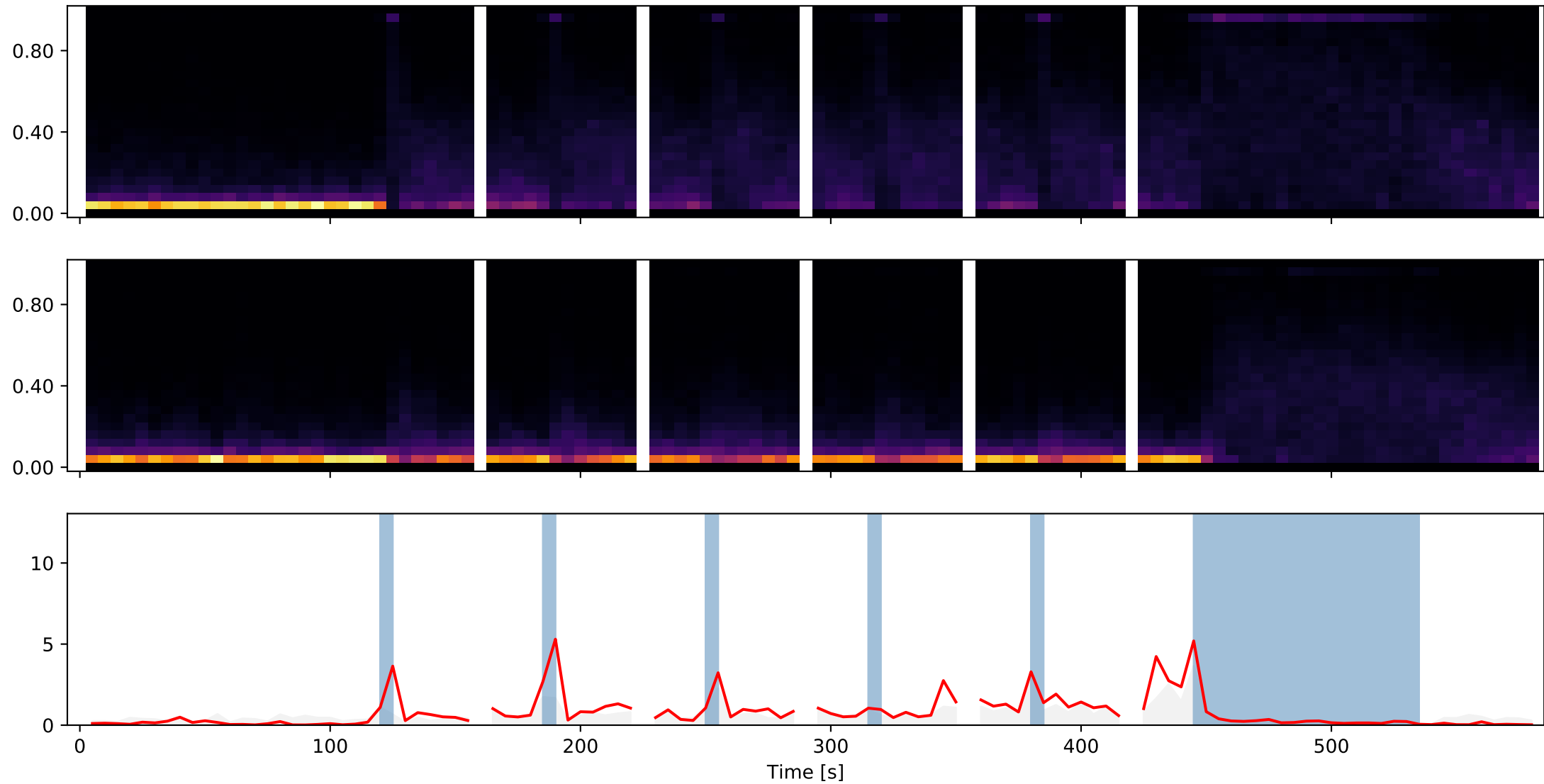
speed\_midbody



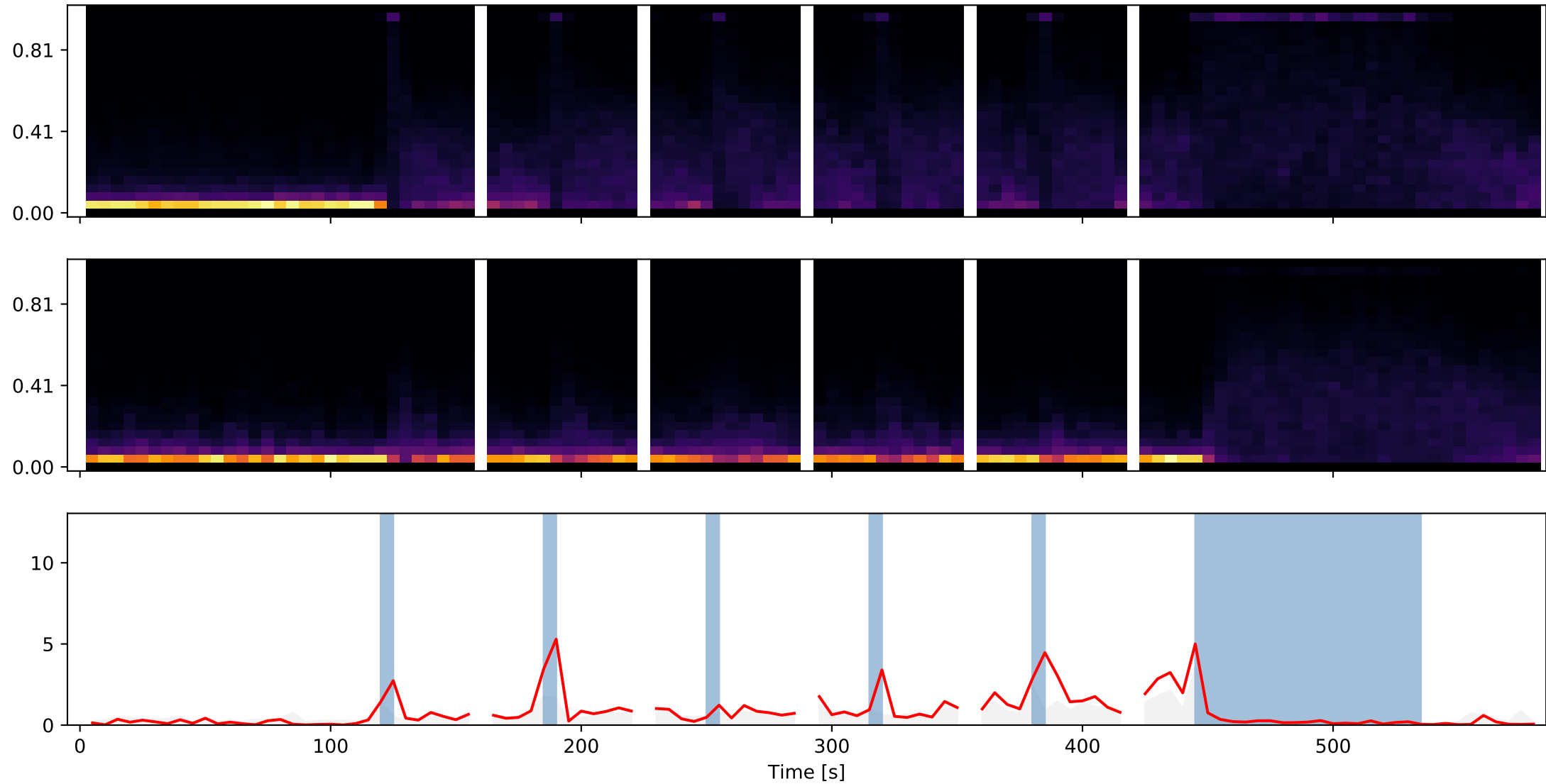
relative\_to\_body\_radial\_velocity\_tail\_tip



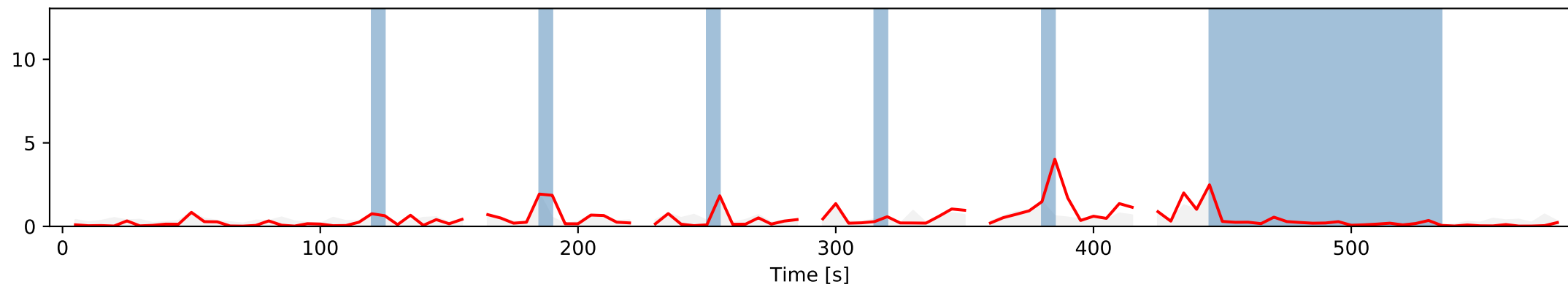
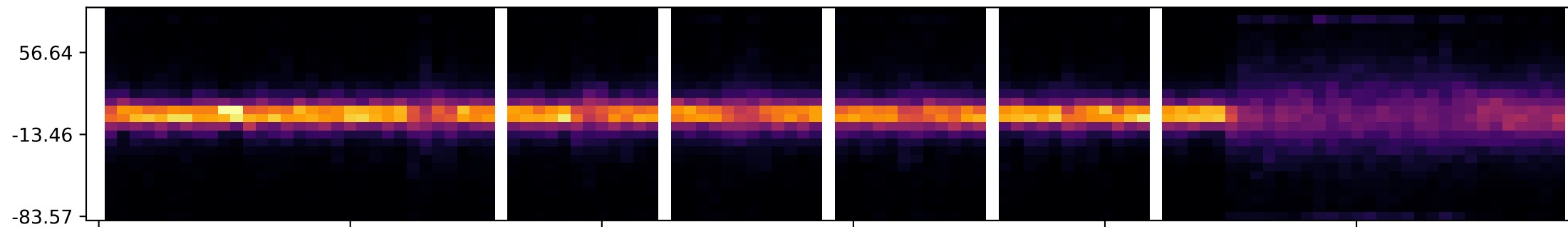
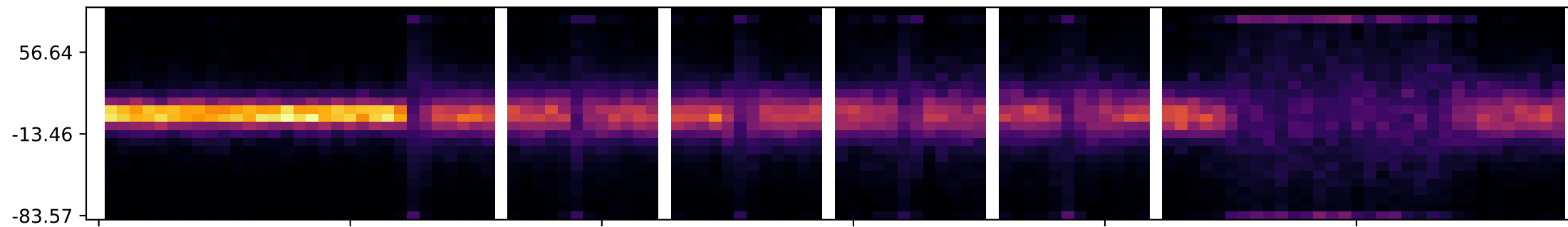
relative\_to\_body\_angular\_velocity\_hips



relative\_to\_body\_angular\_velocity\_neck

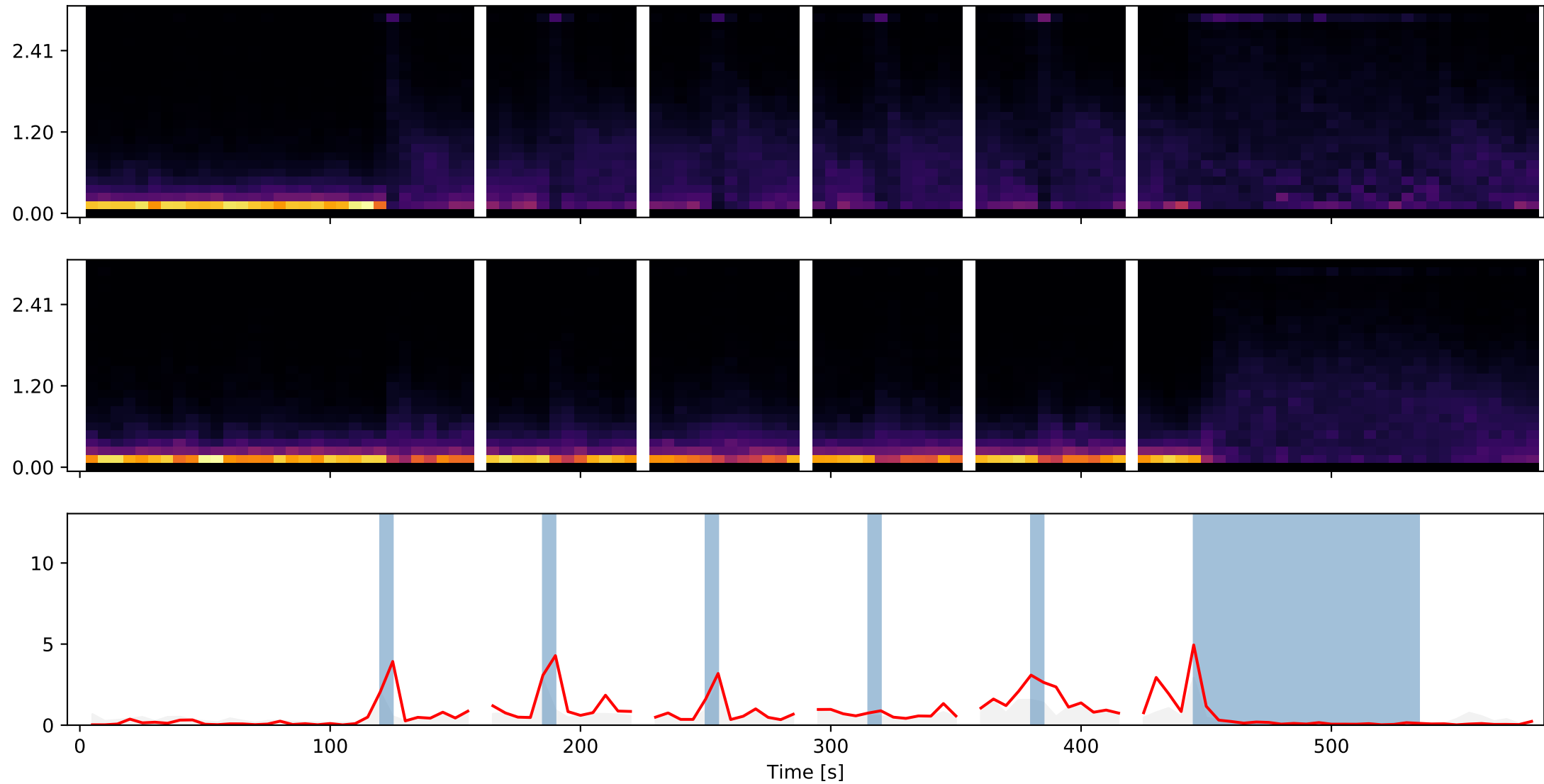


relative\_to\_body\_radial\_velocity\_hips

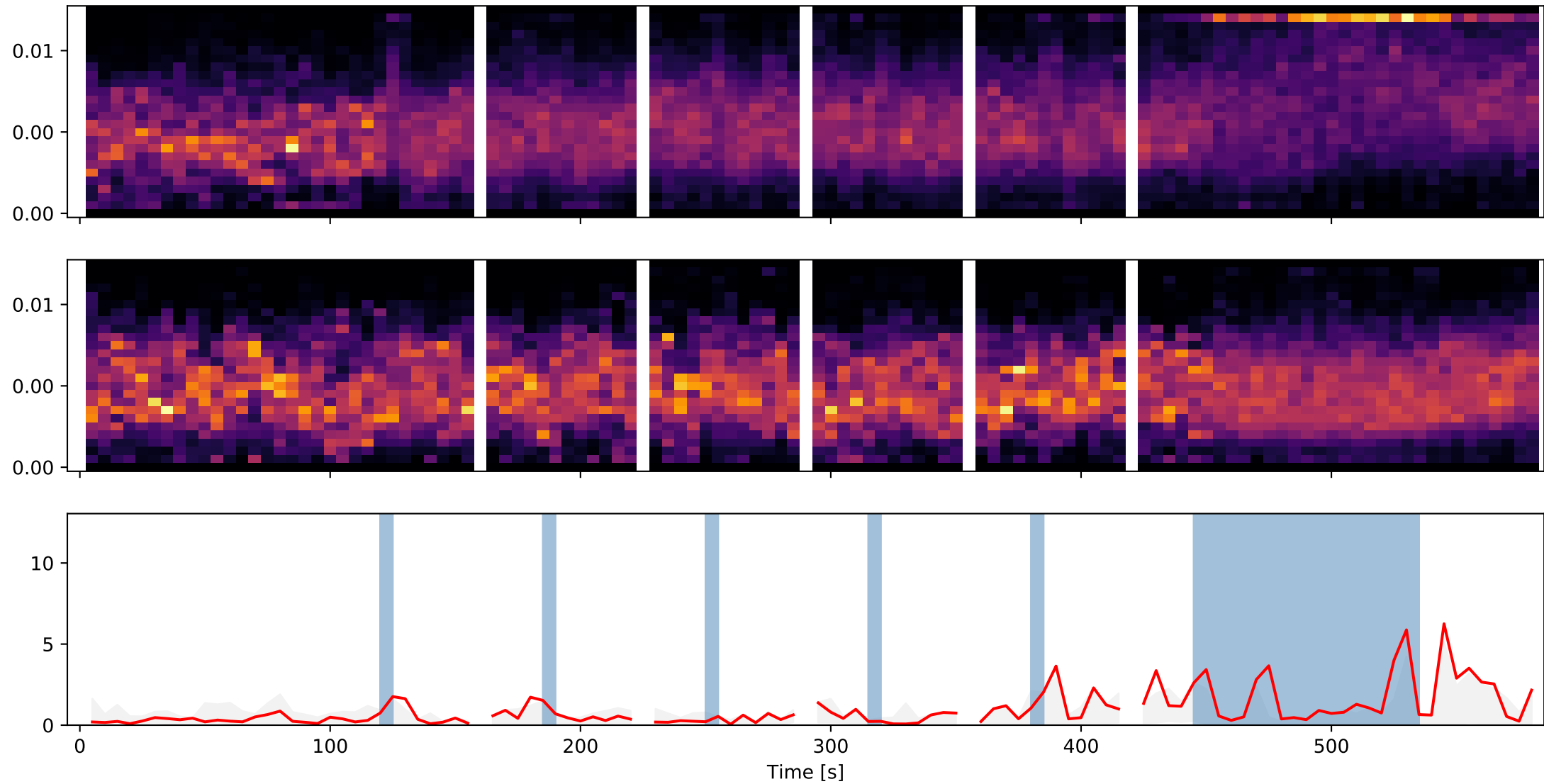




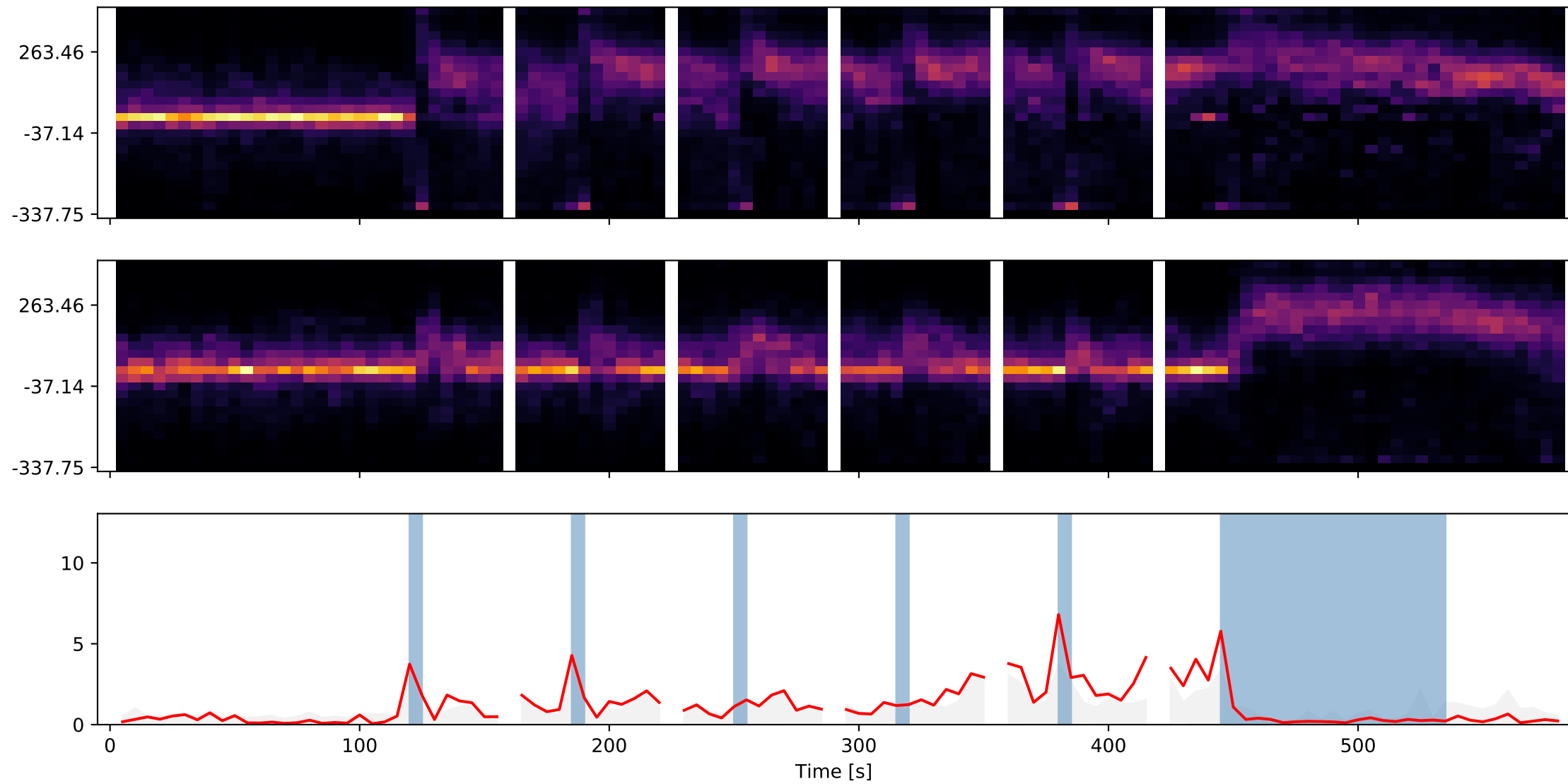
angular\_velocity\_tail\_base



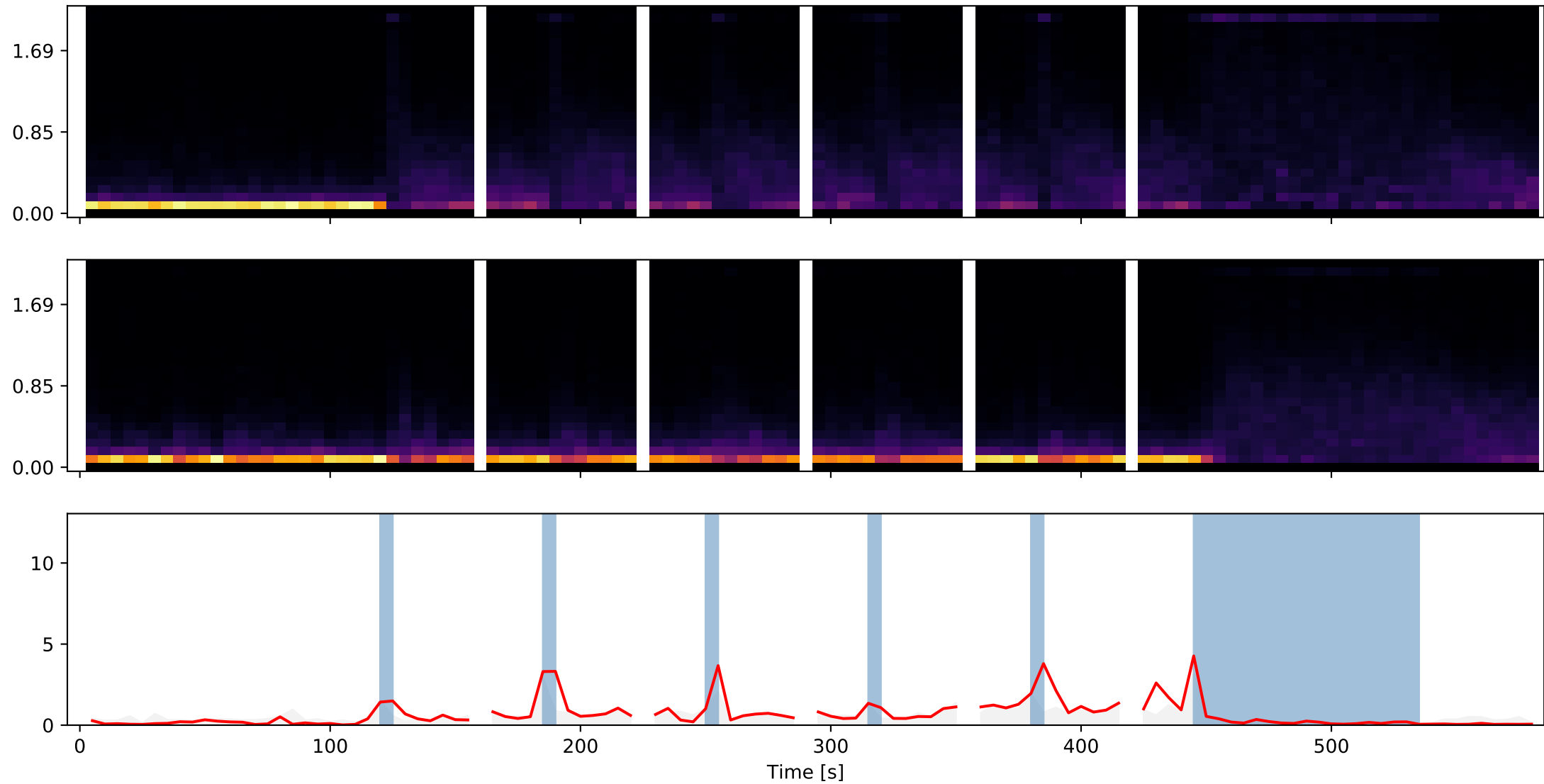
curvature\_std\_midbody



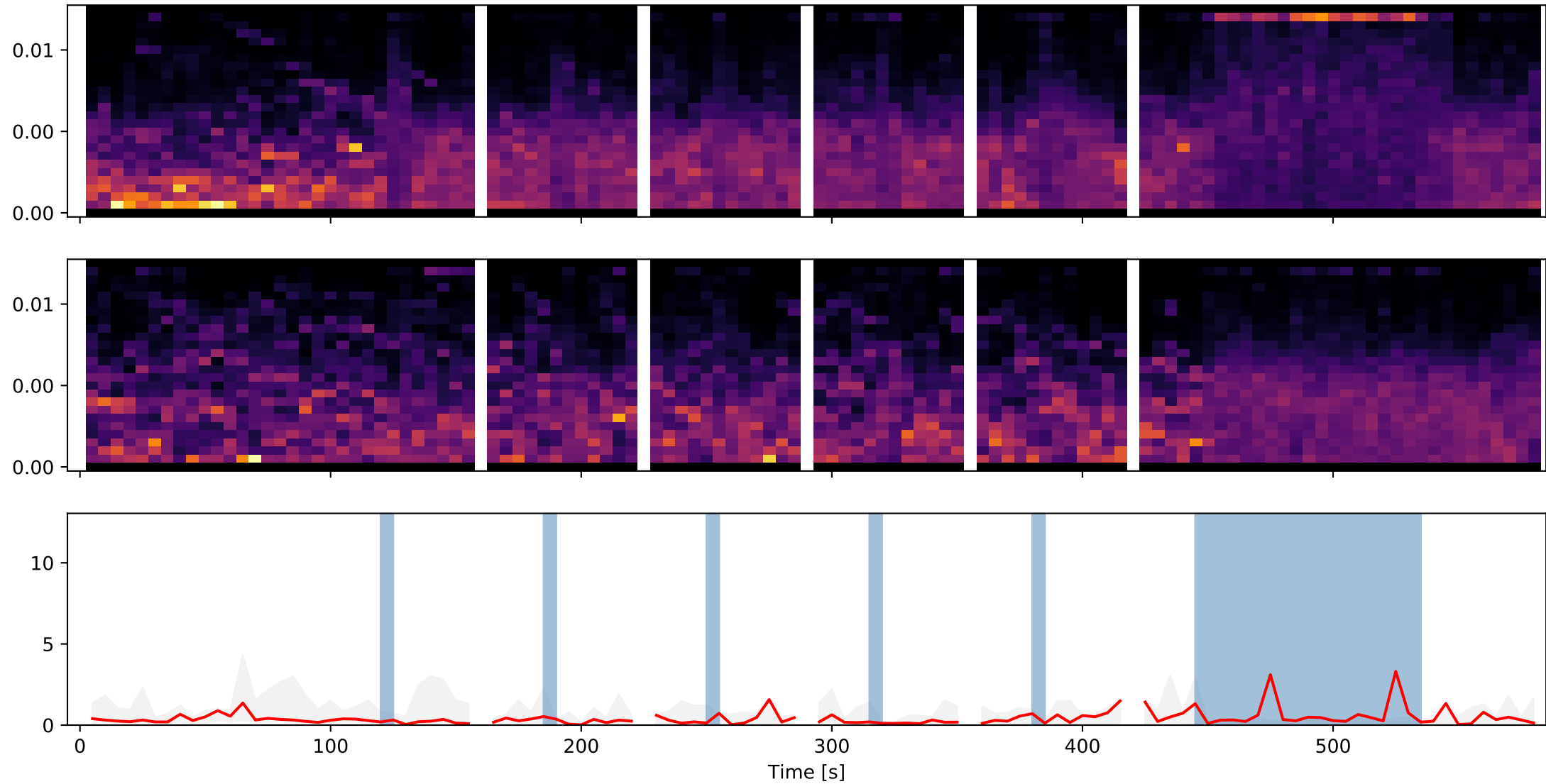
speed\_neck



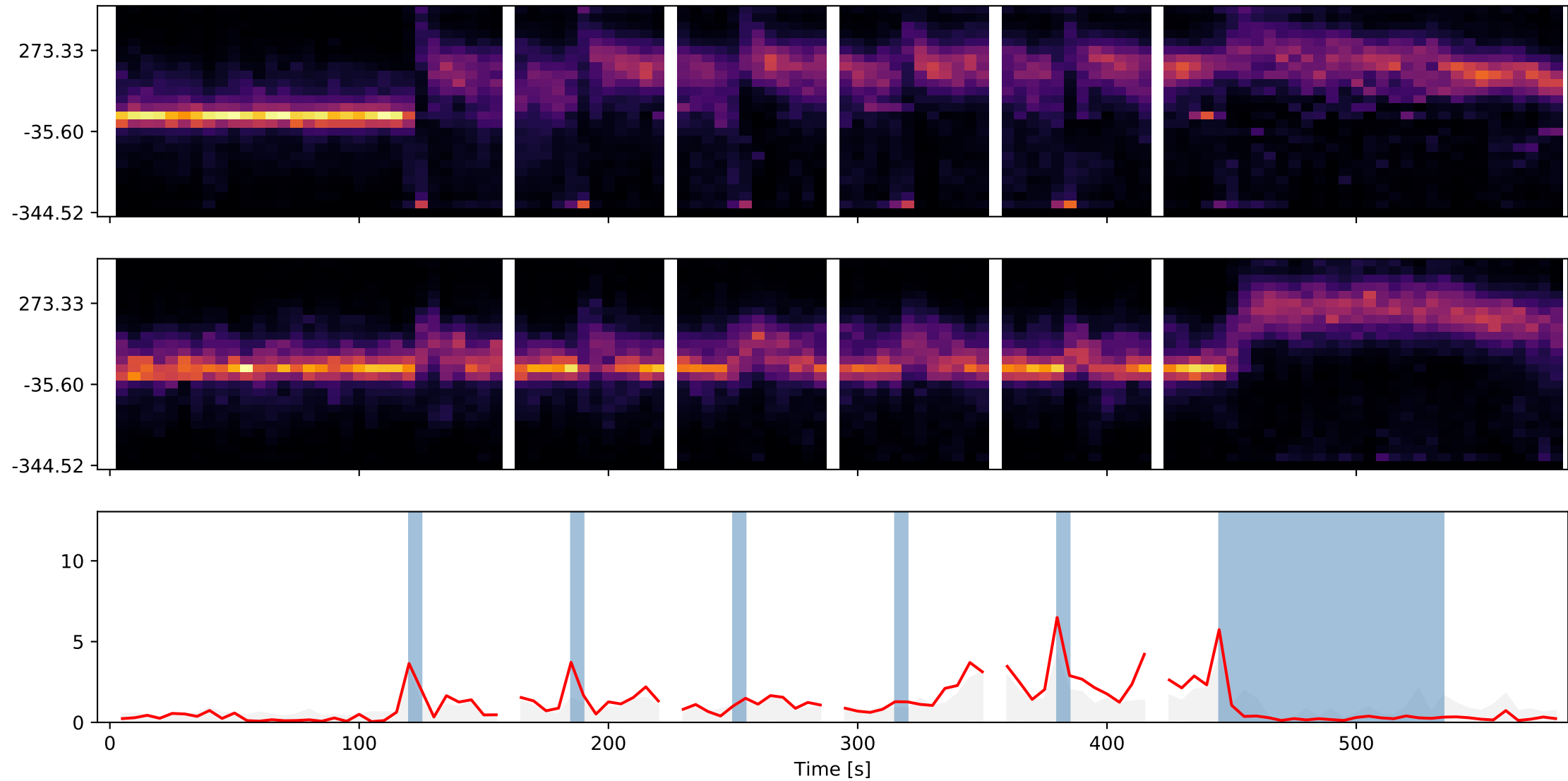
angular\_velocity\_midbody



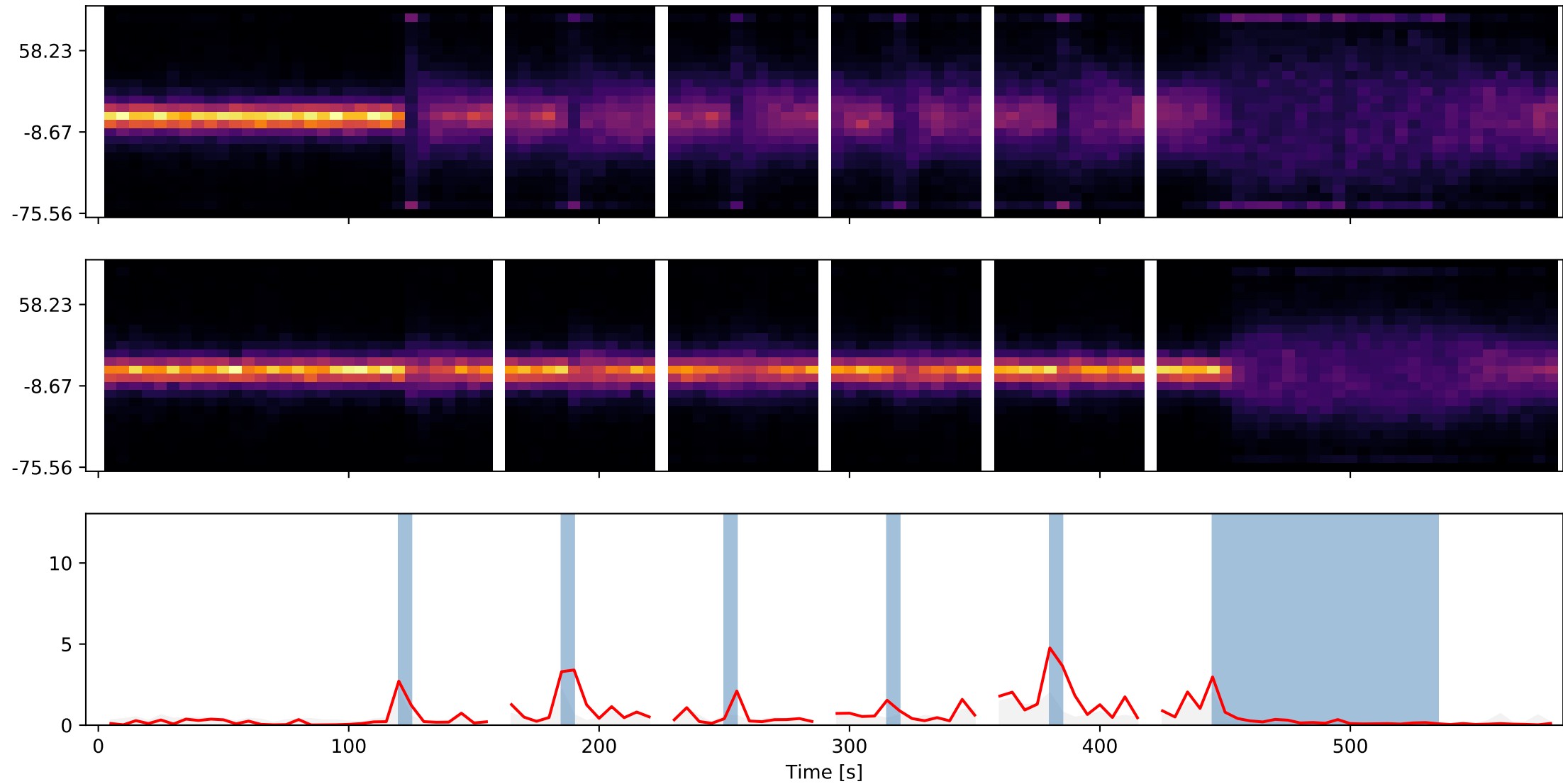
curvature\_mean\_midbody



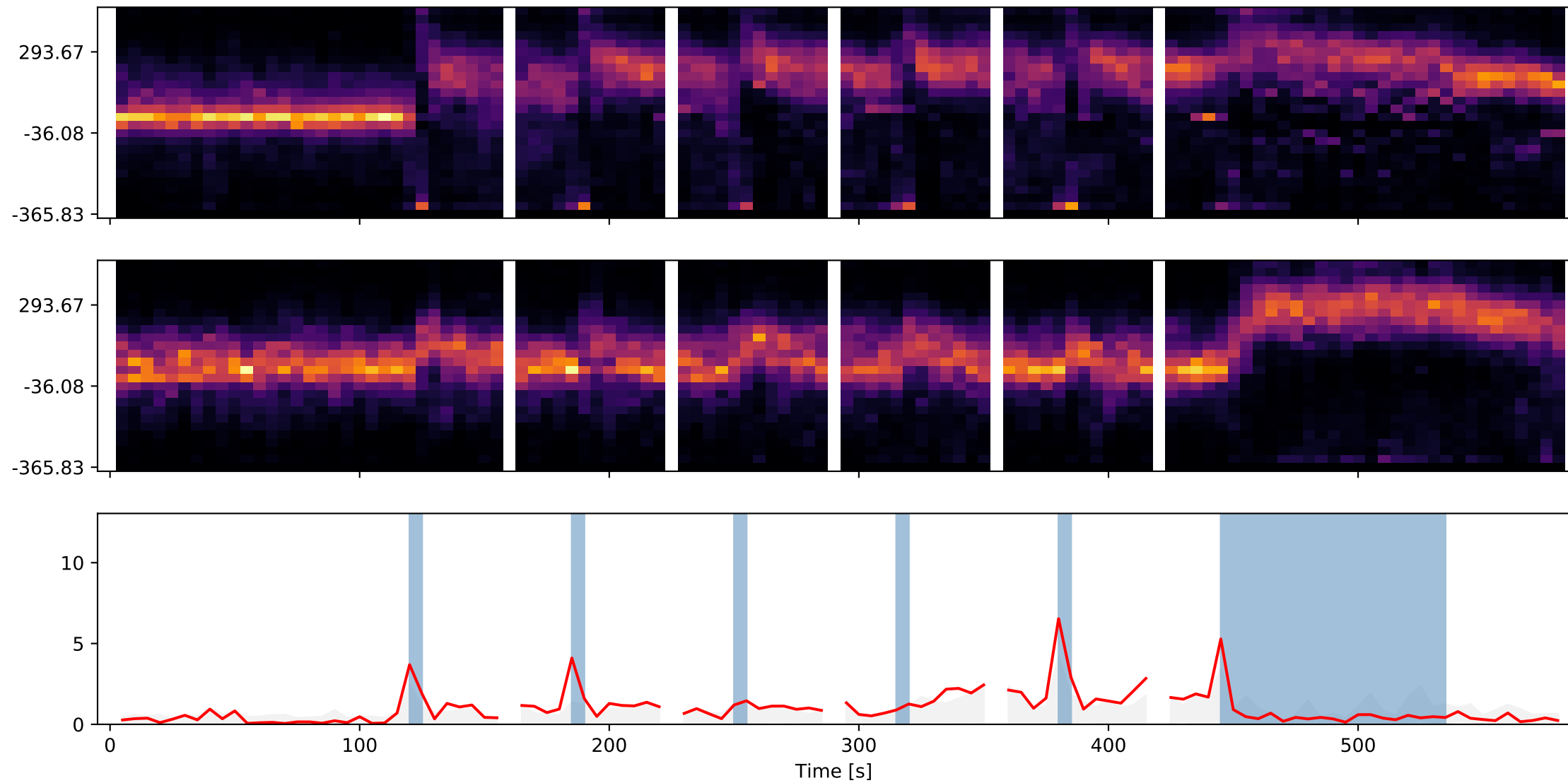
speed\_head\_base



relative\_to\_hips\_radial\_velocity\_tail\_tip

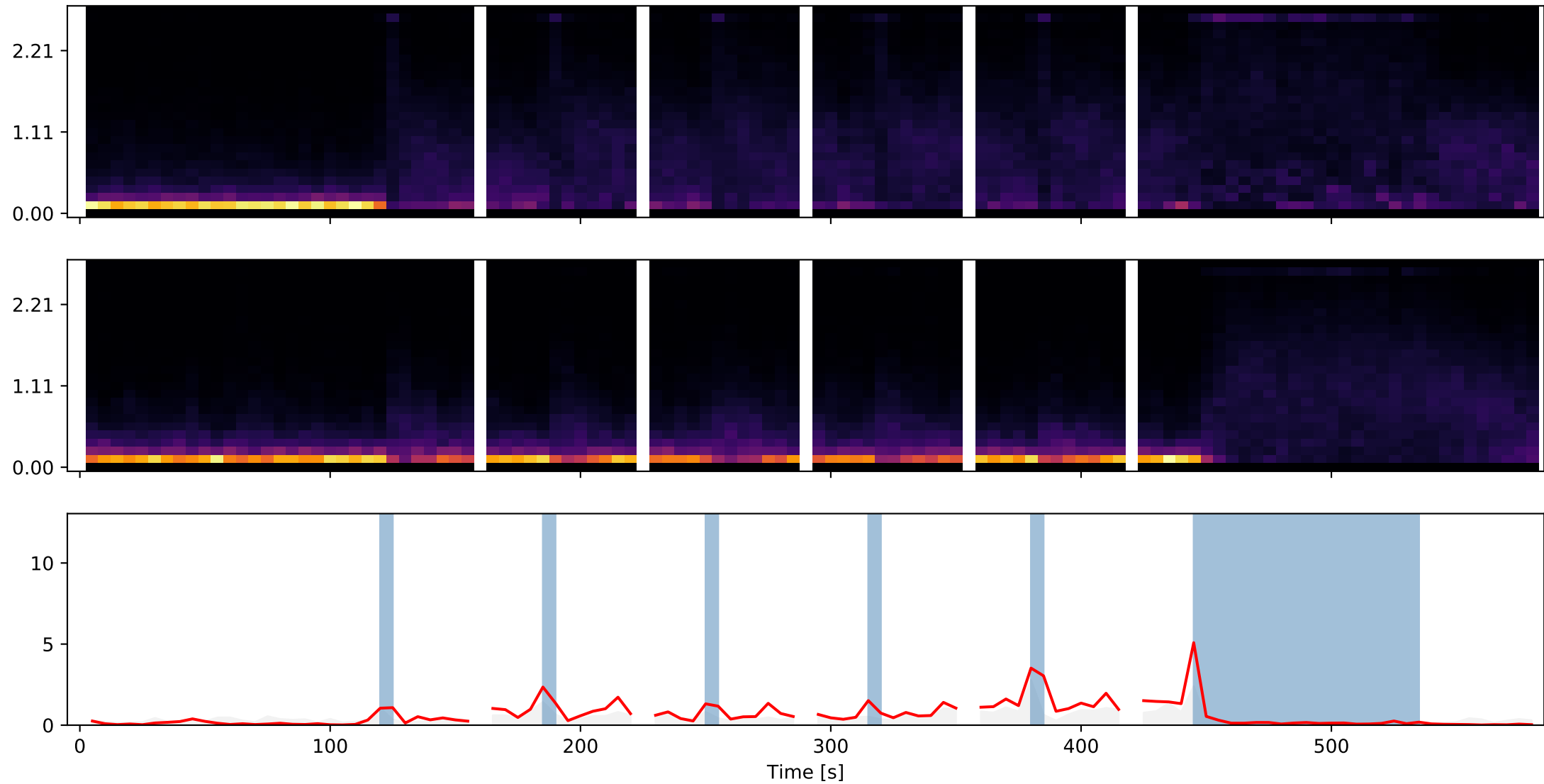


speed\_head\_tip

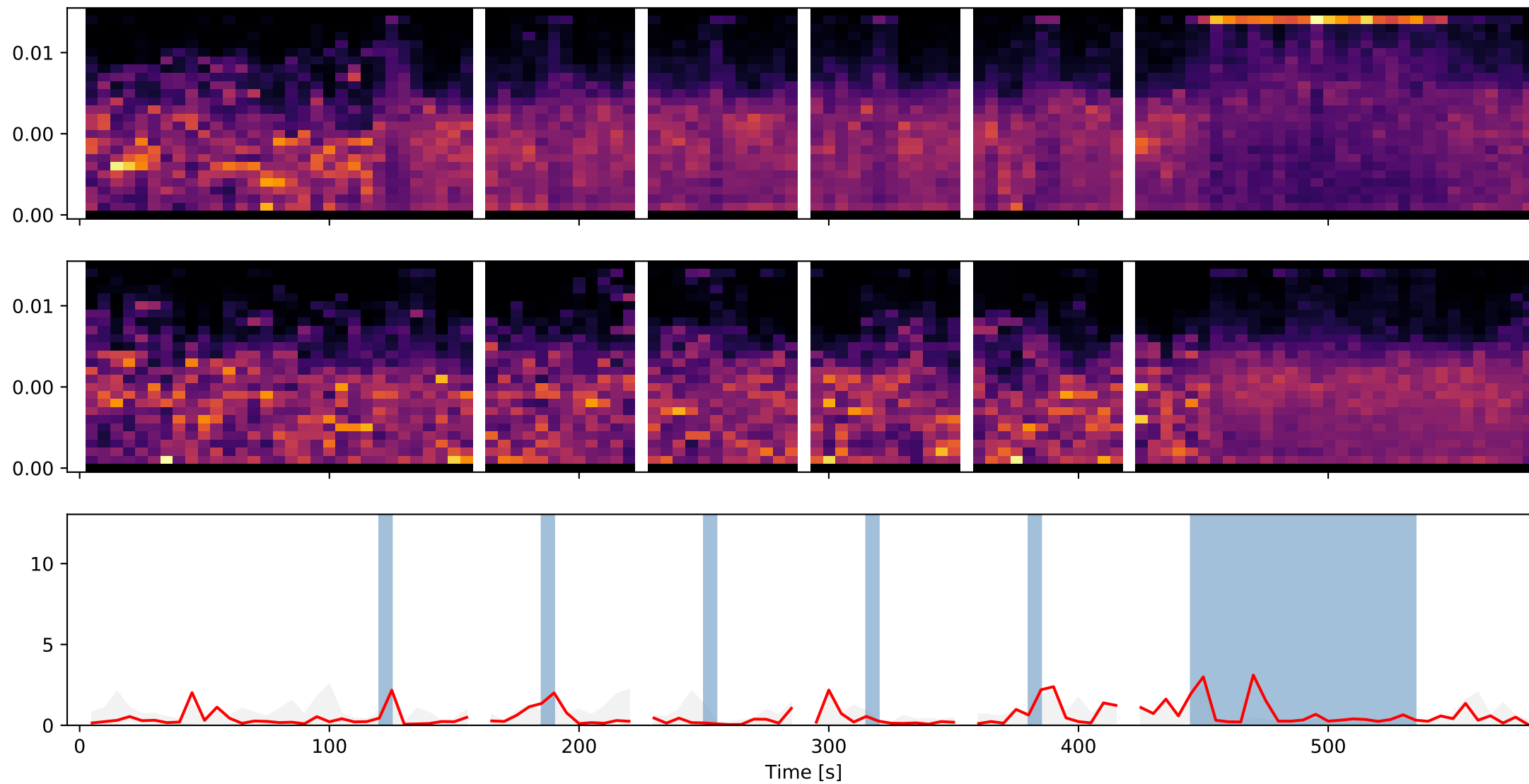




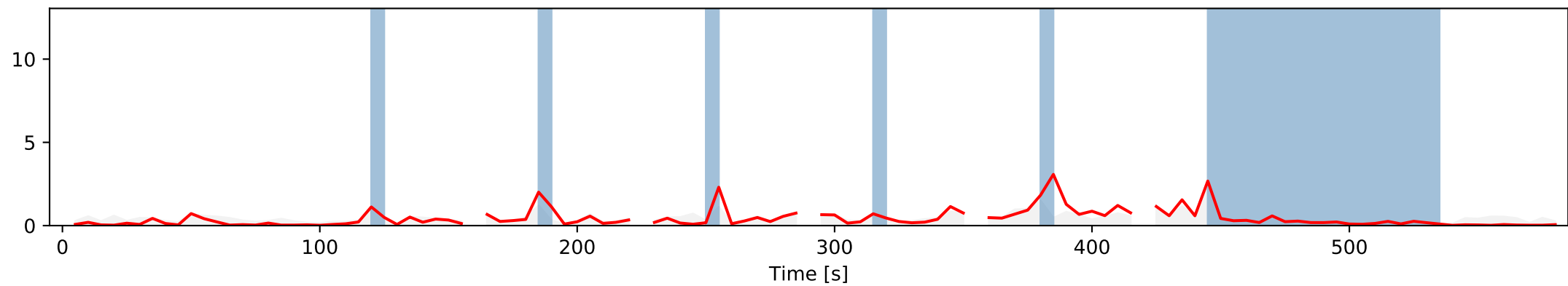
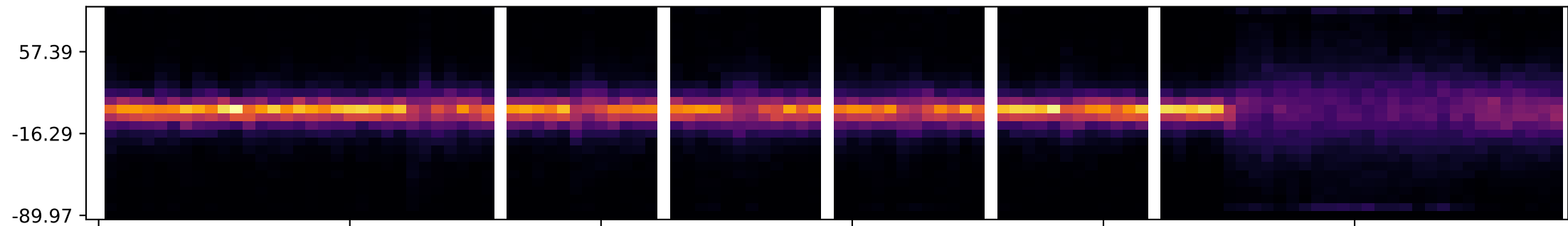
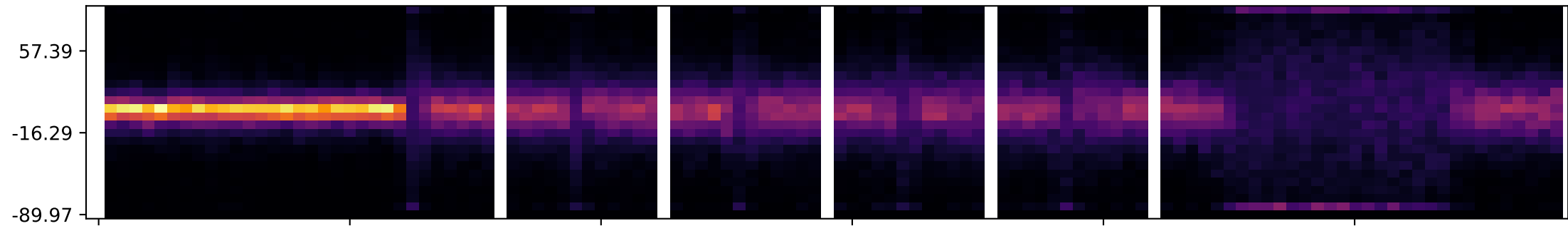
angular\_velocity\_neck



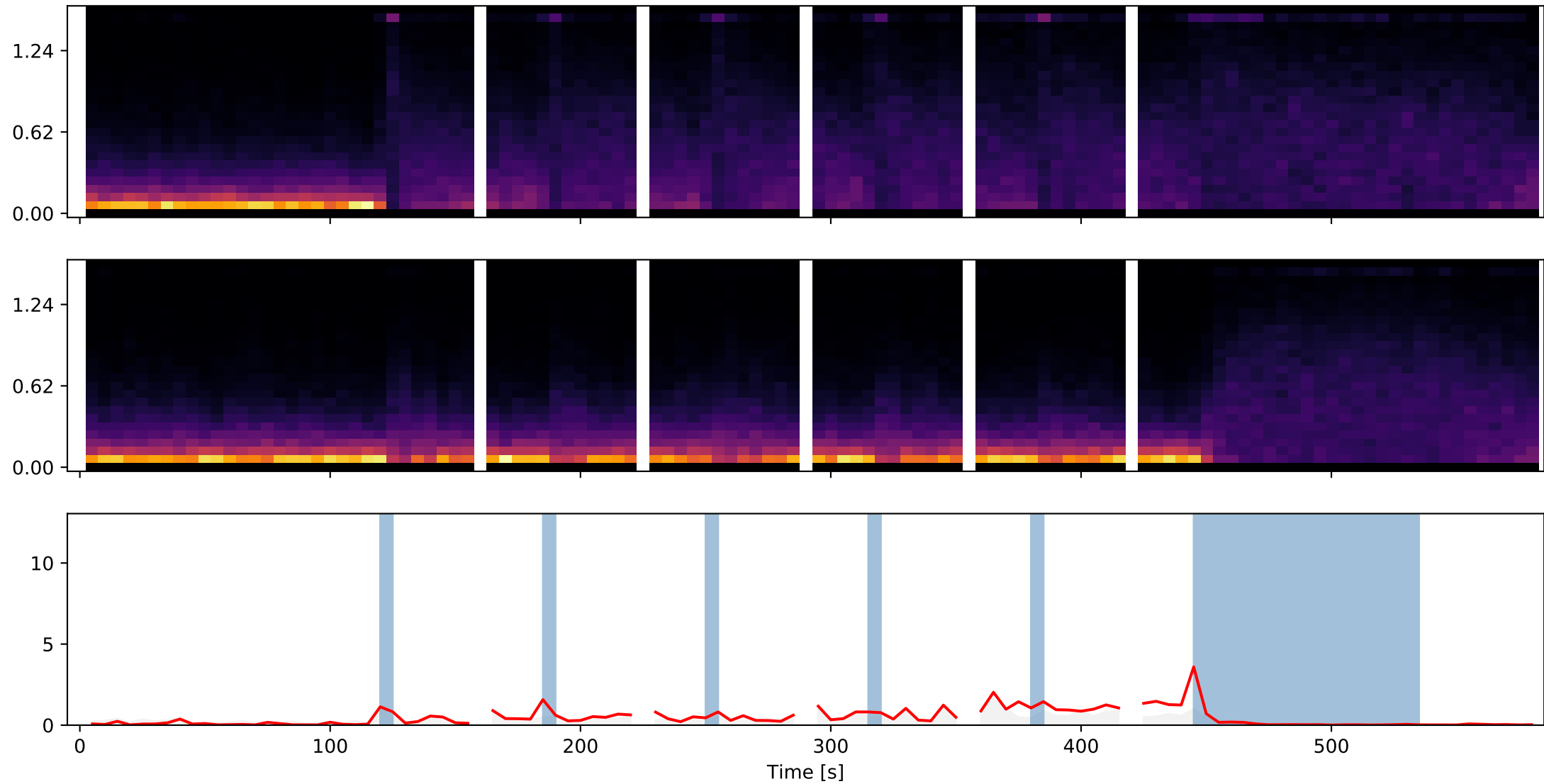
curvature\_mean\_hips



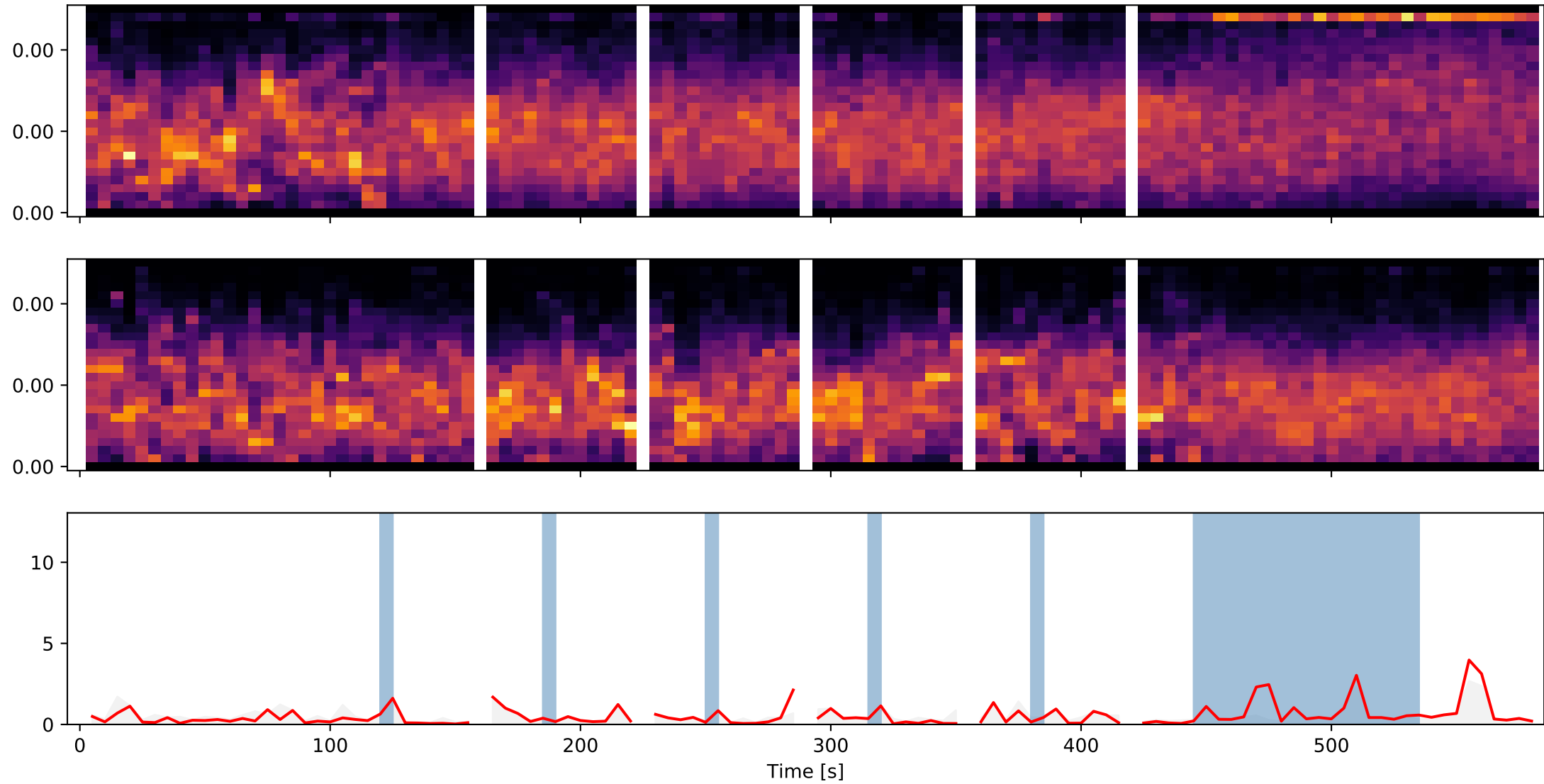
relative\_to\_body\_radial\_velocity\_neck



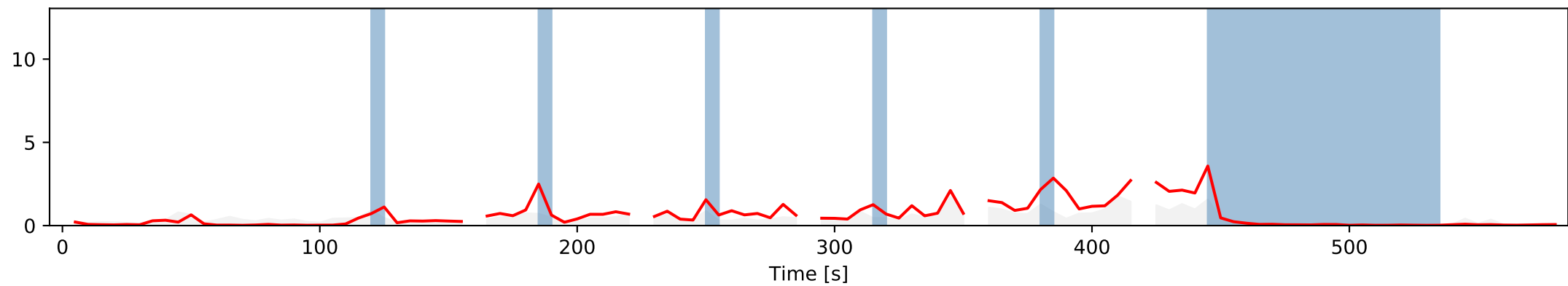
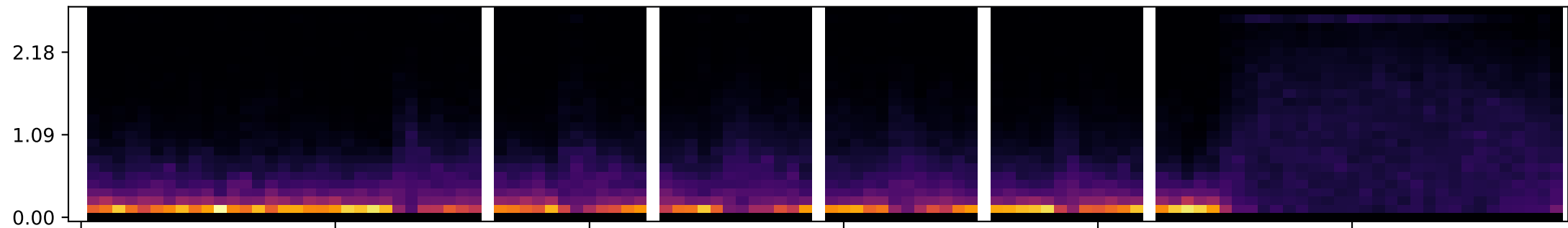
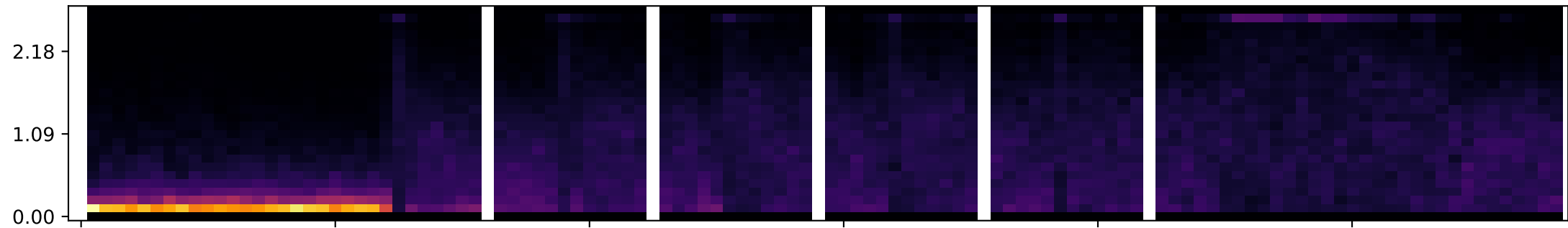
relative\_to\_tail\_base\_angular\_velocity\_tail\_tip



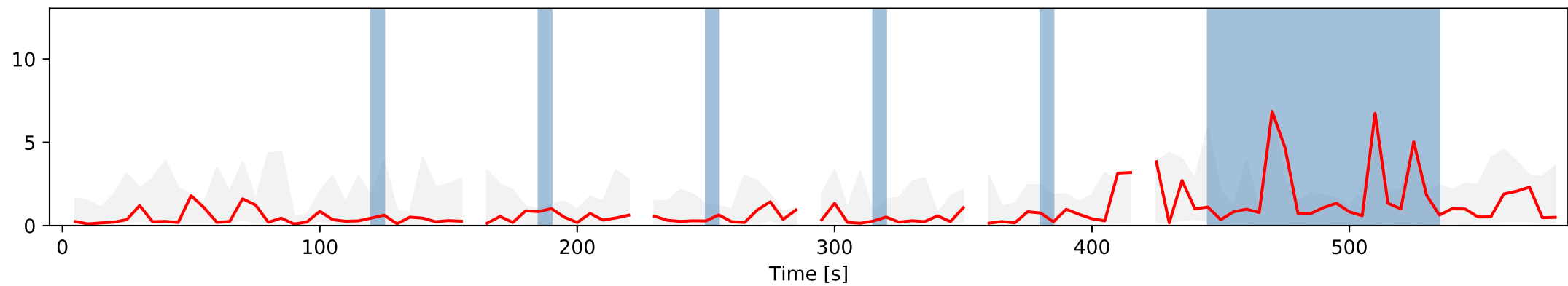
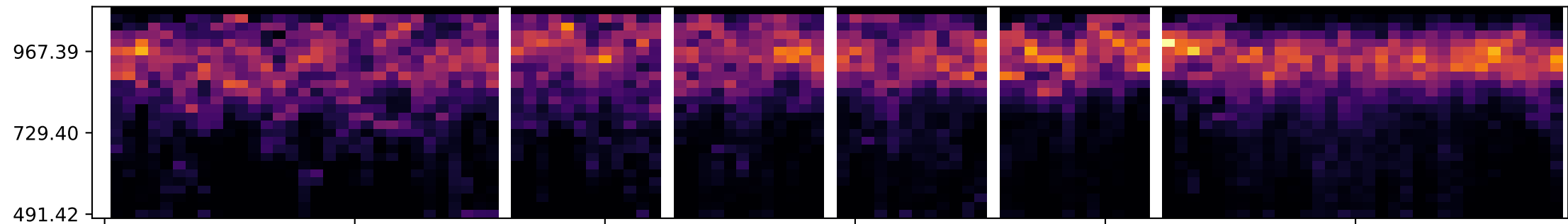
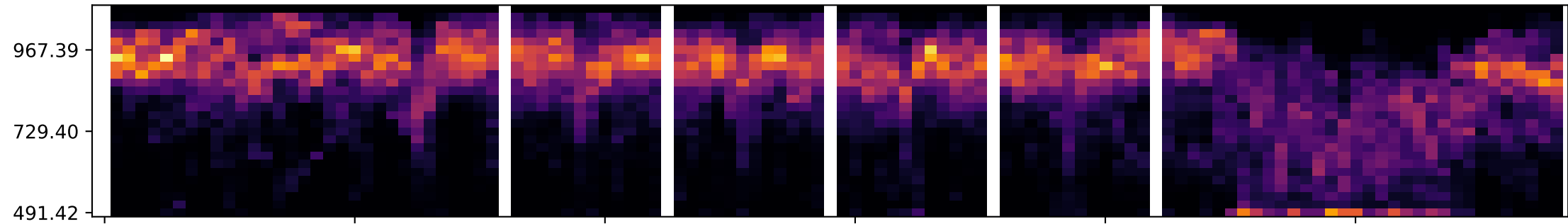
curvature\_std\_hips



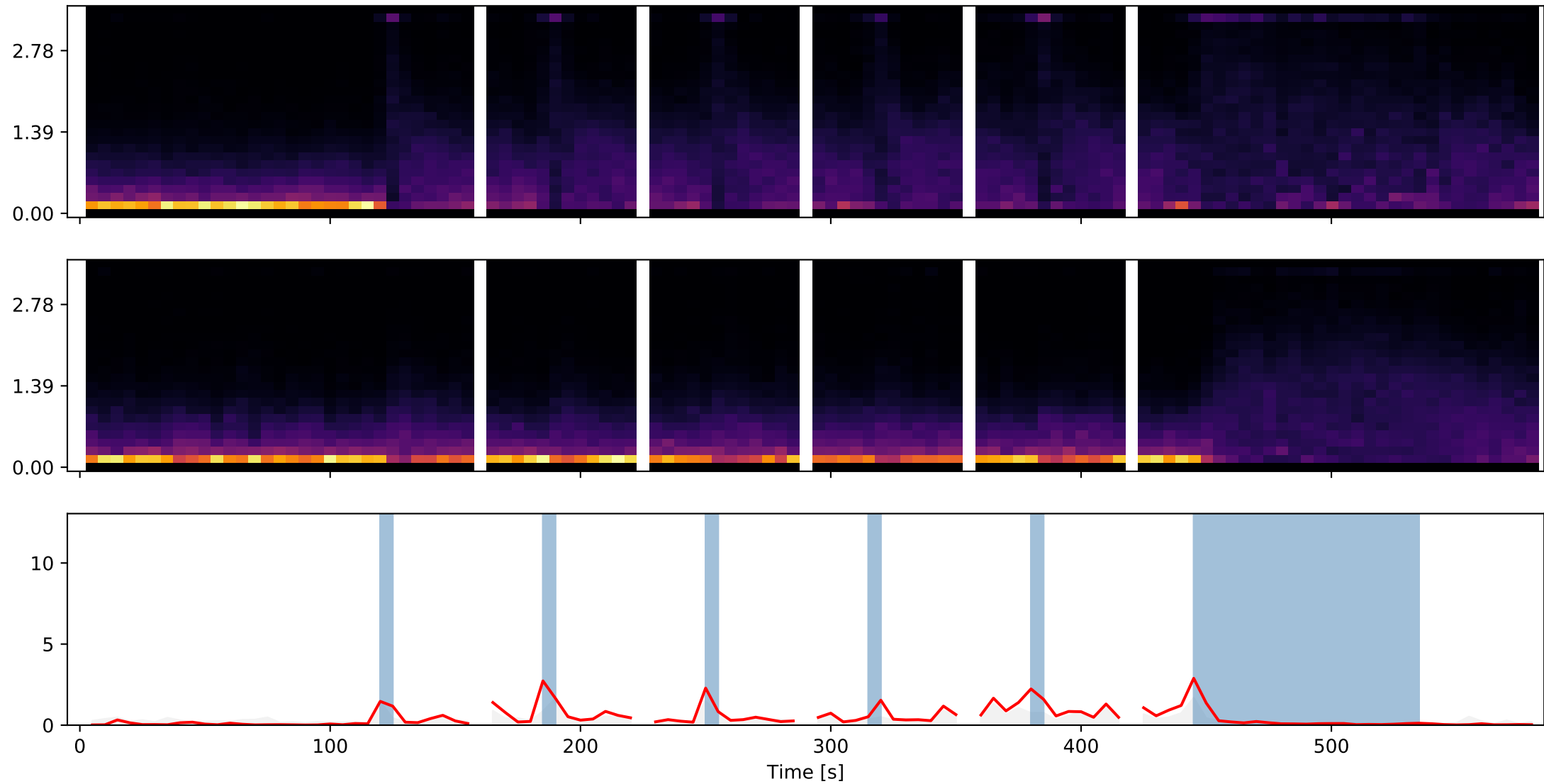
relative\_to\_neck\_angular\_velocity\_head\_tip



major\_axis

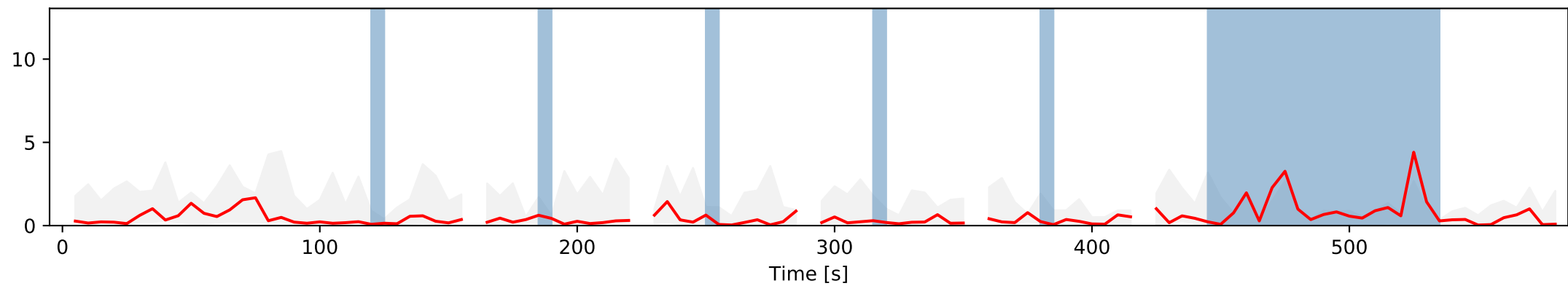
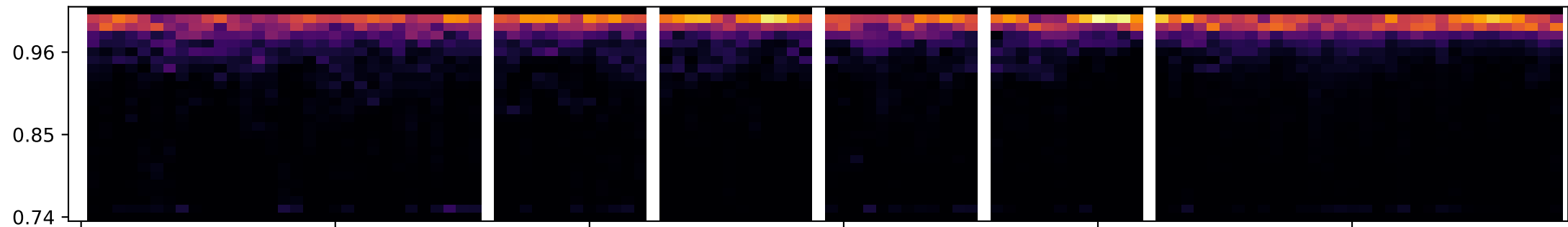
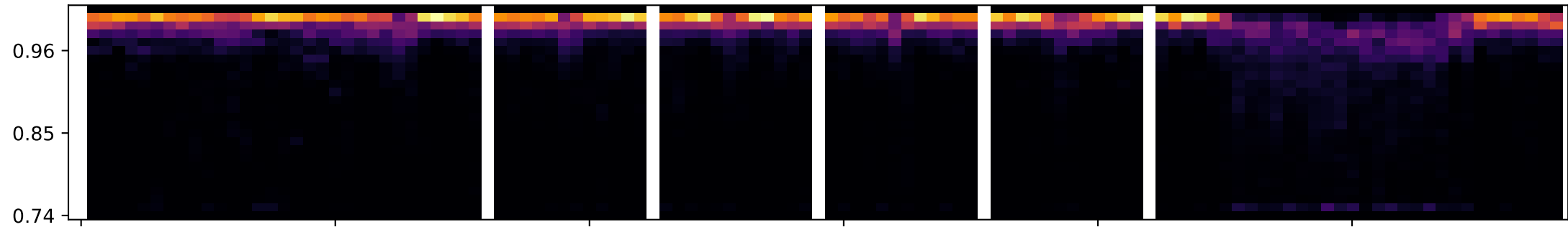


angular\_velocity\_tail\_tip

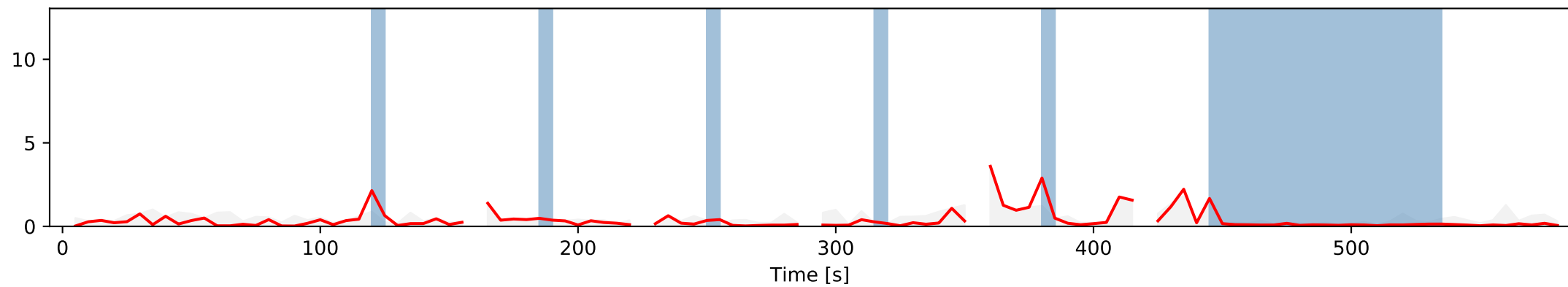
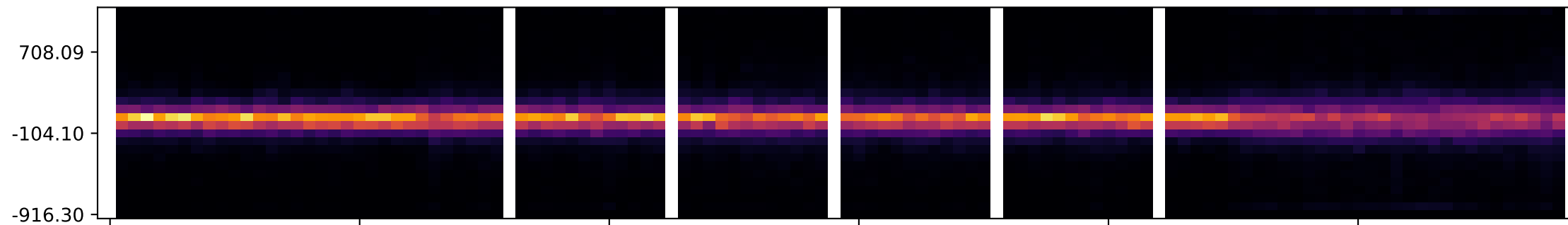
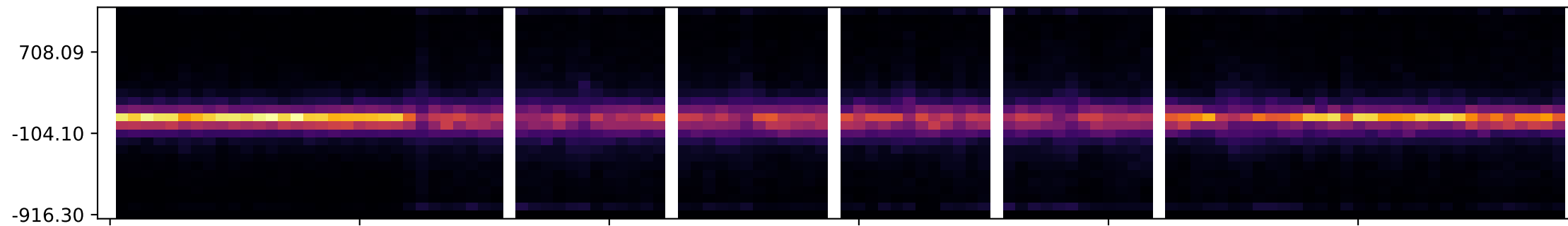




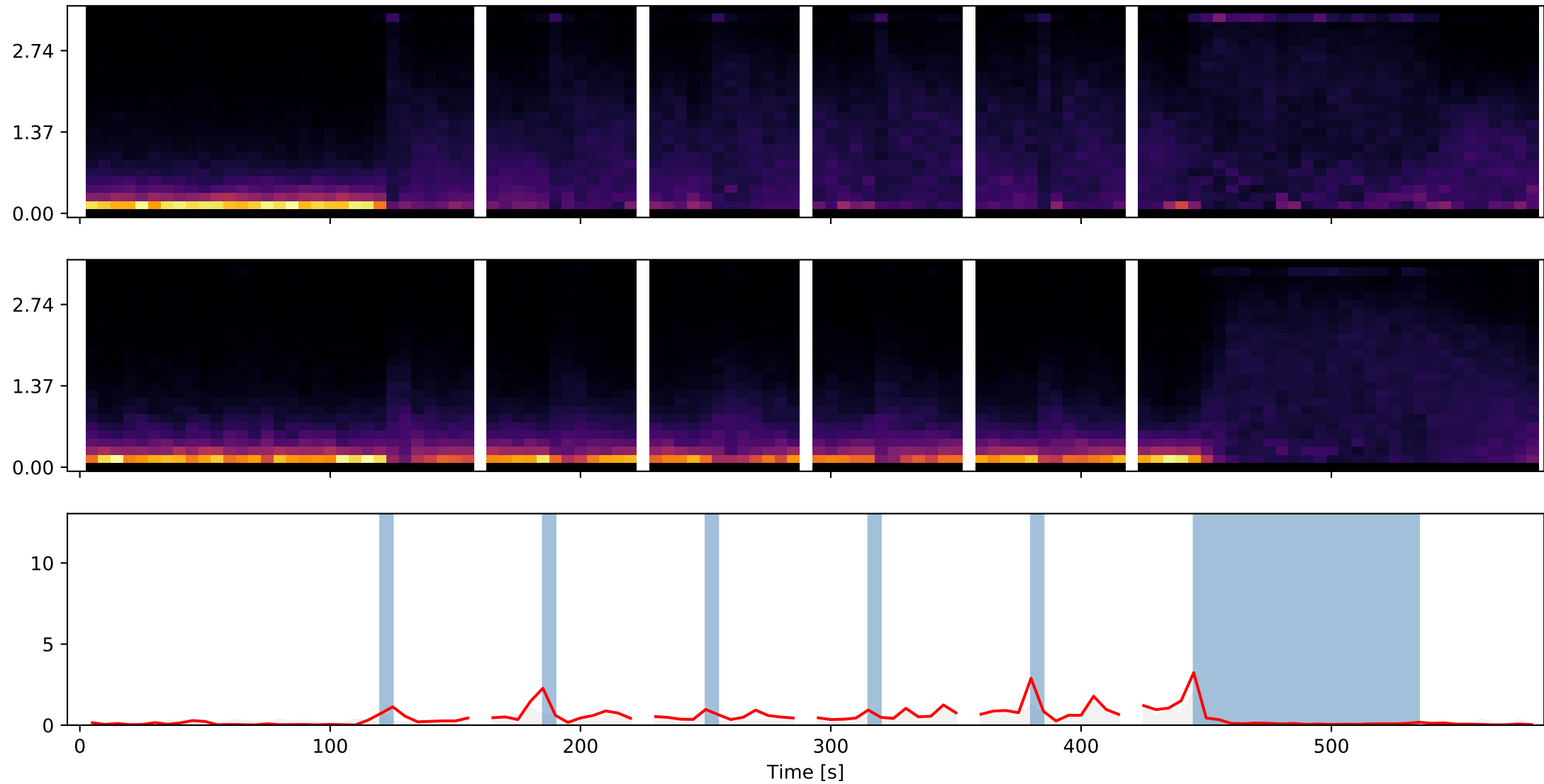
# quirkiness



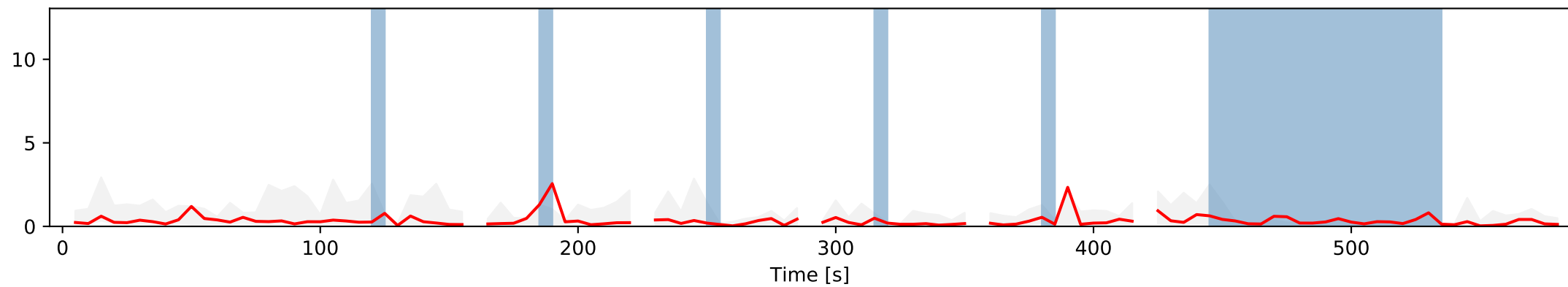
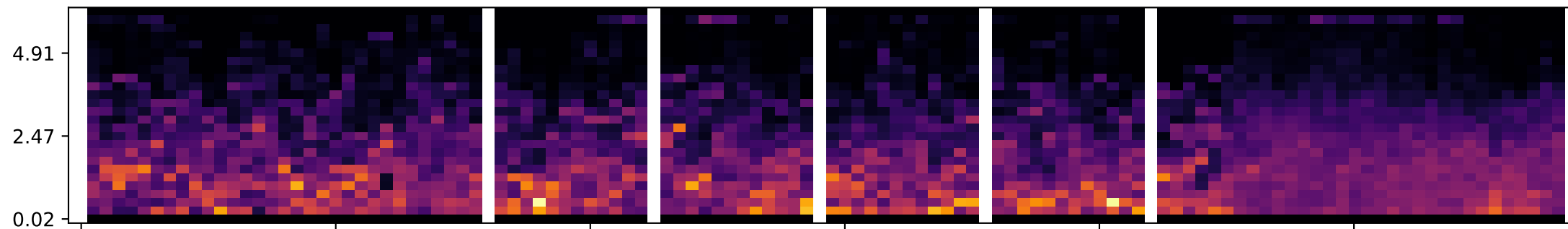
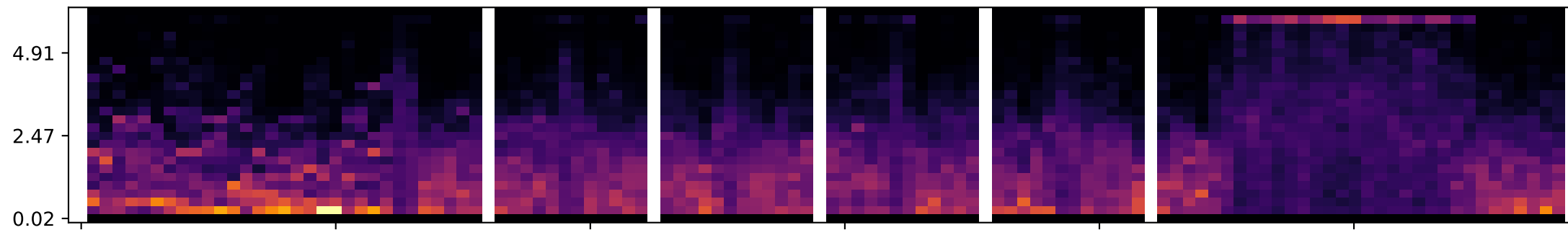
d\_speed



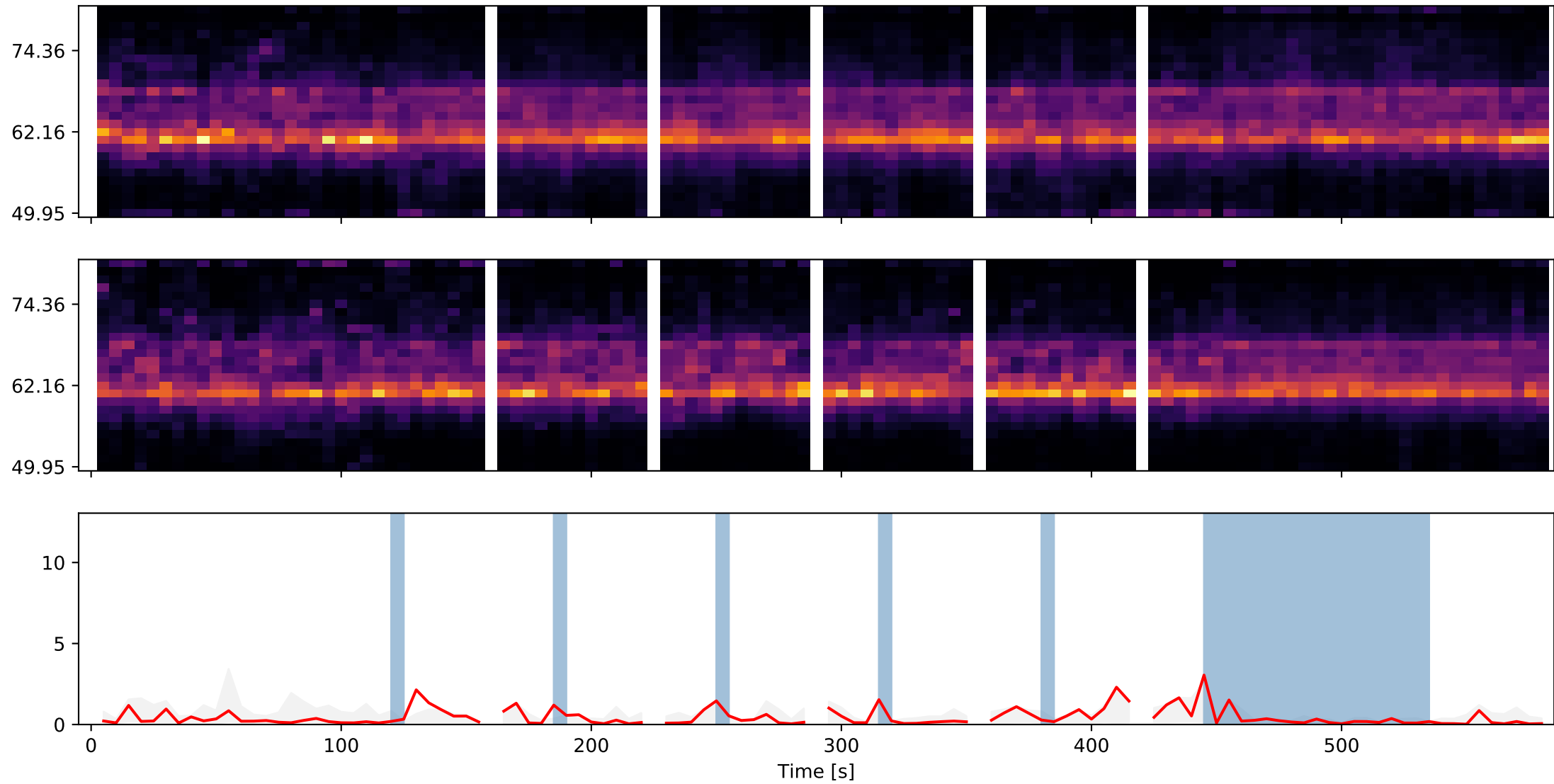
angular\_velocity\_head\_base



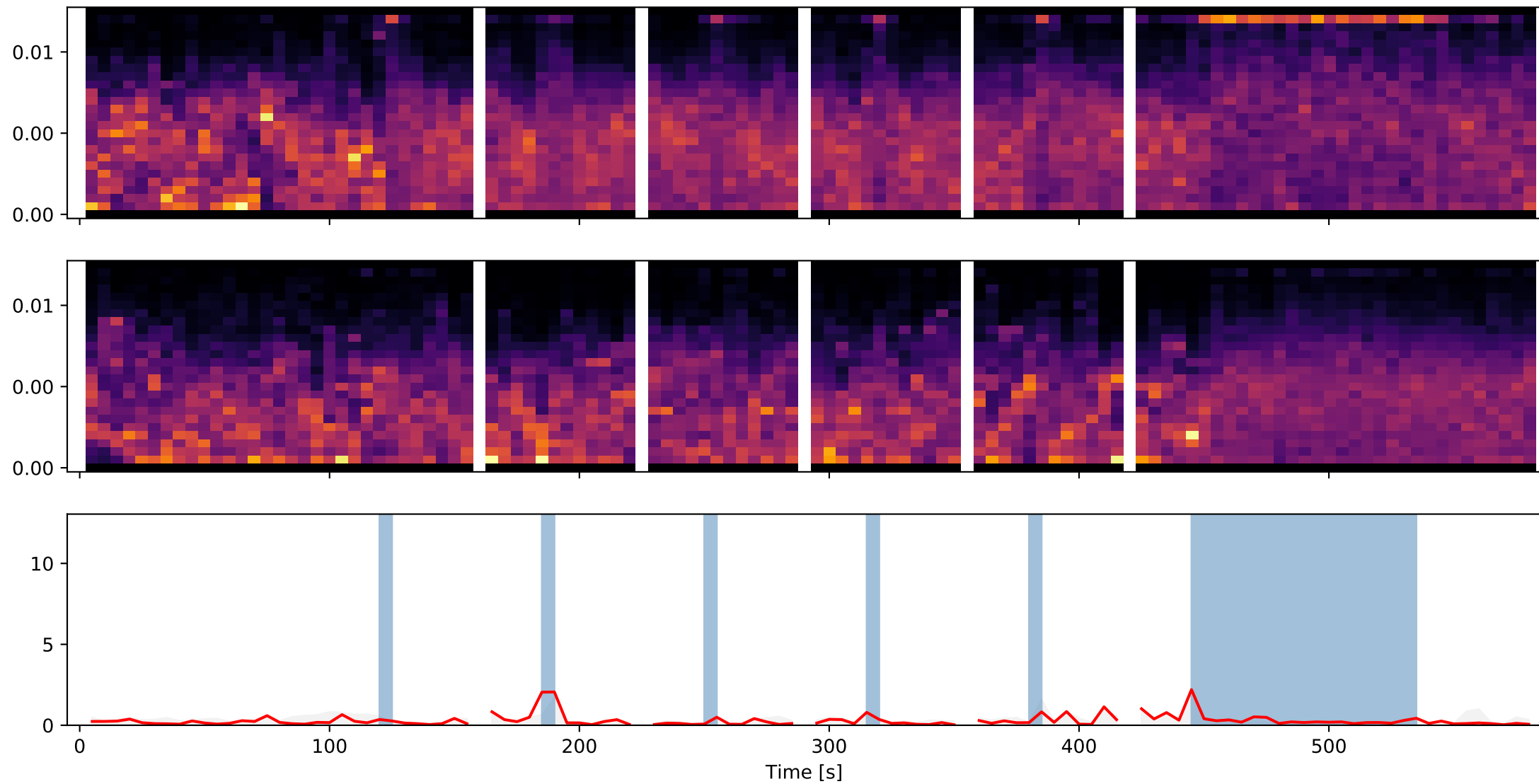
eigen\_projection\_2



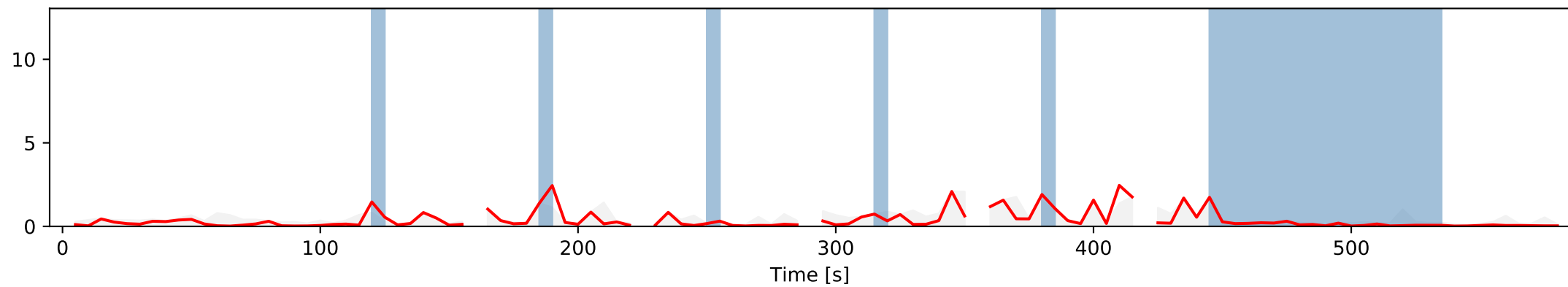
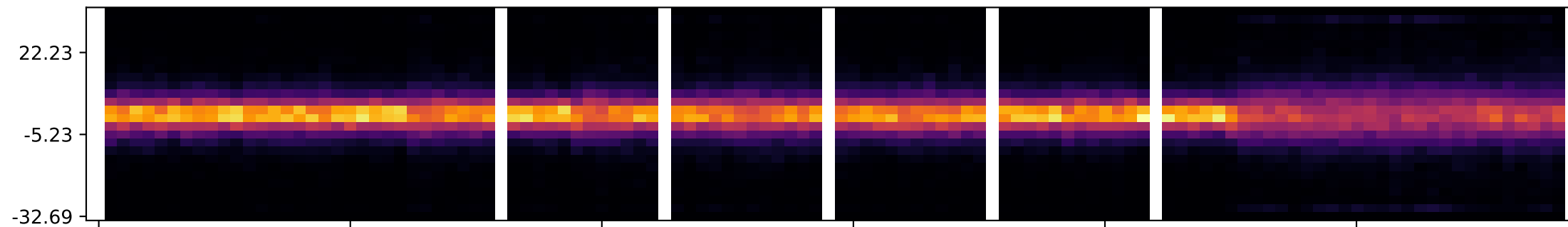
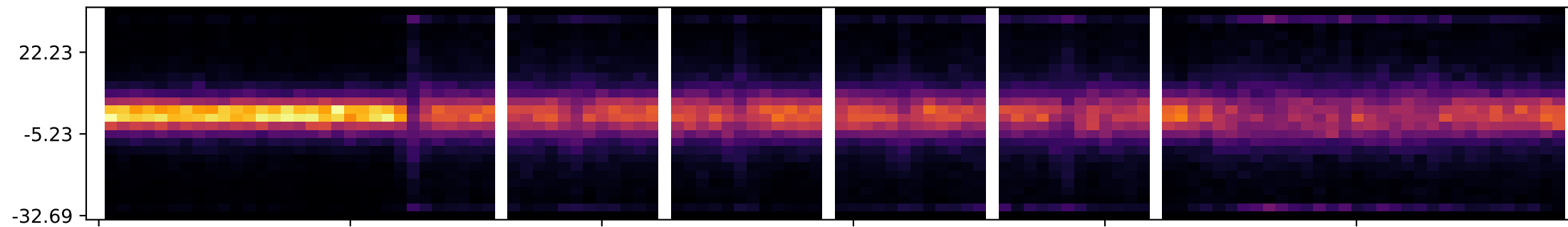
width\_tail\_base



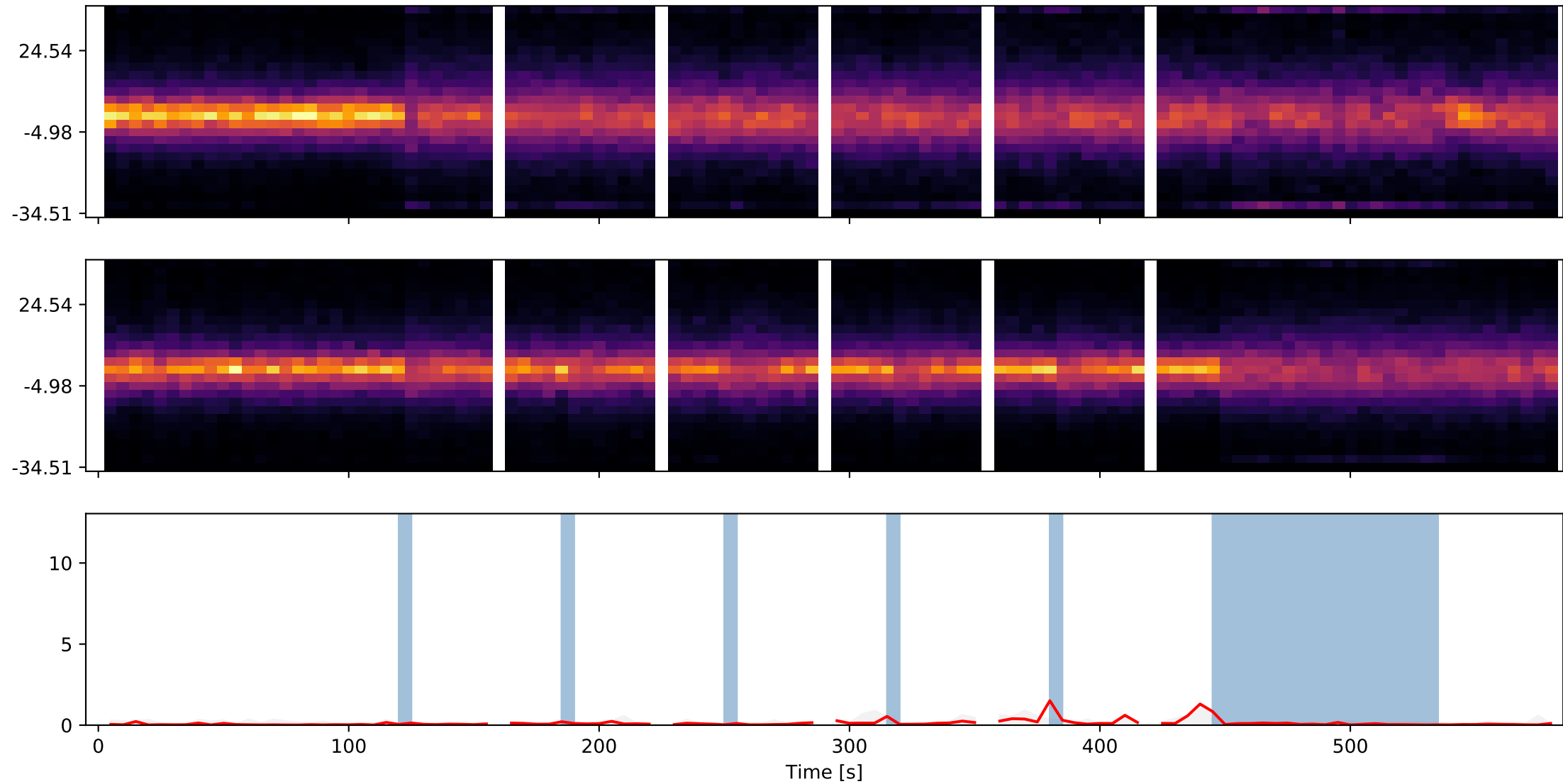
curvature\_tail



relative\_to\_tail\_base\_radial\_velocity\_tail\_tip

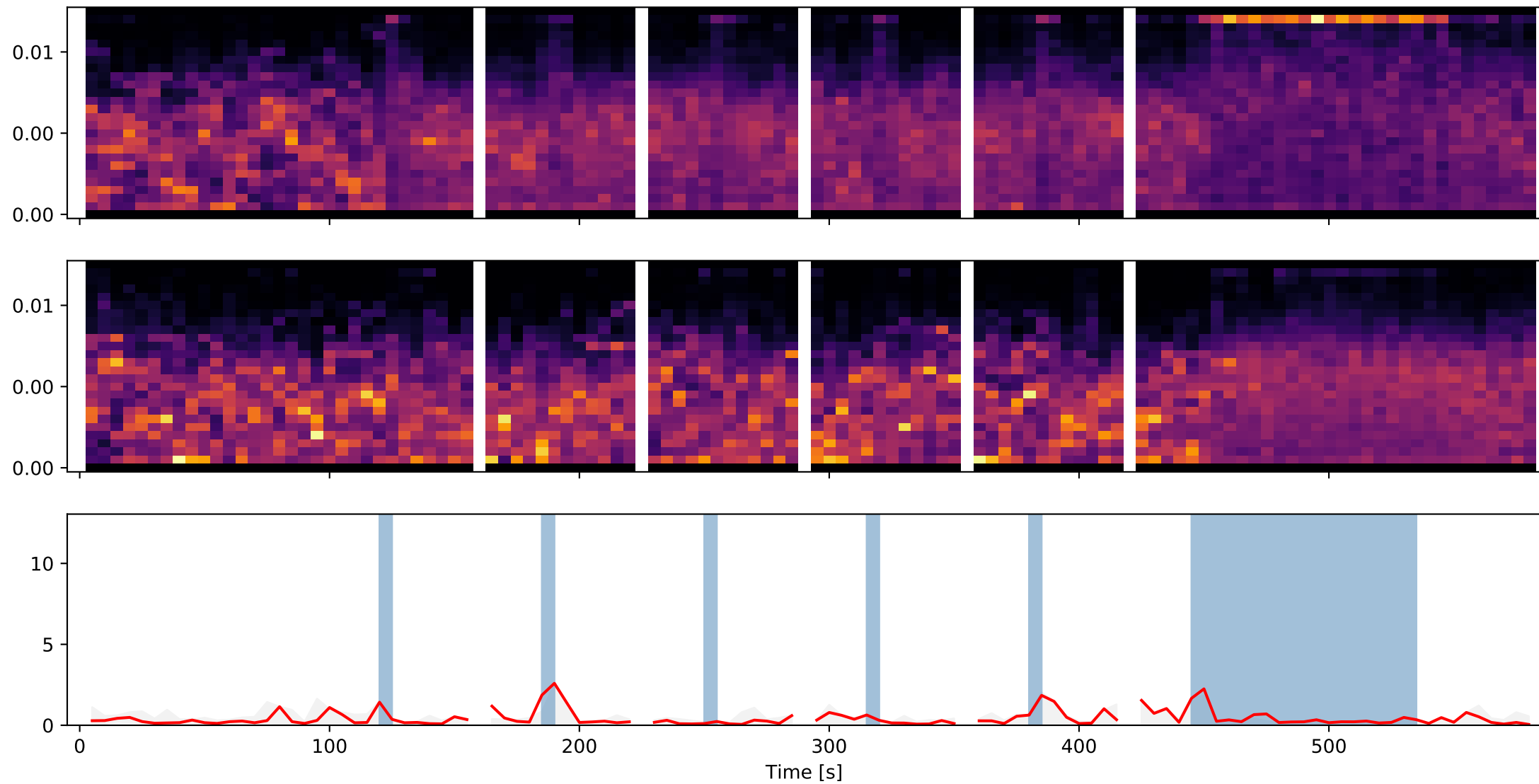


relative\_to\_head\_base\_radial\_velocity\_head\_tip

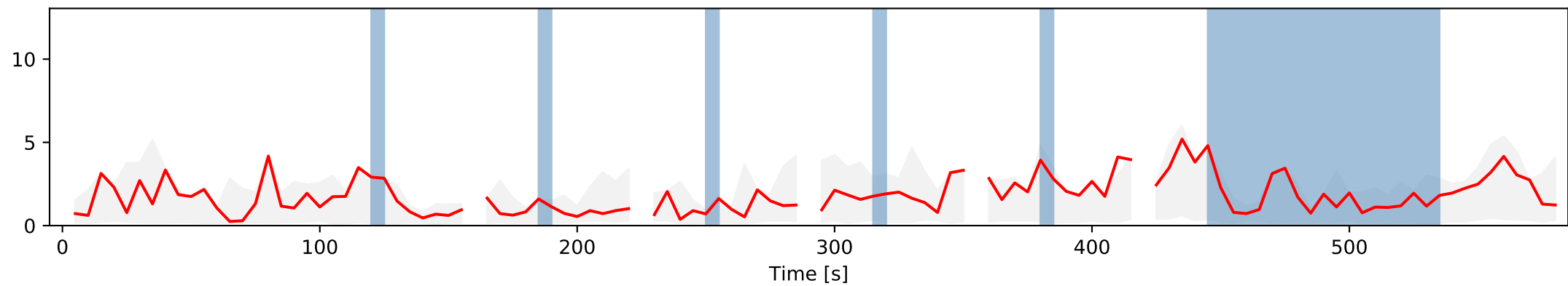
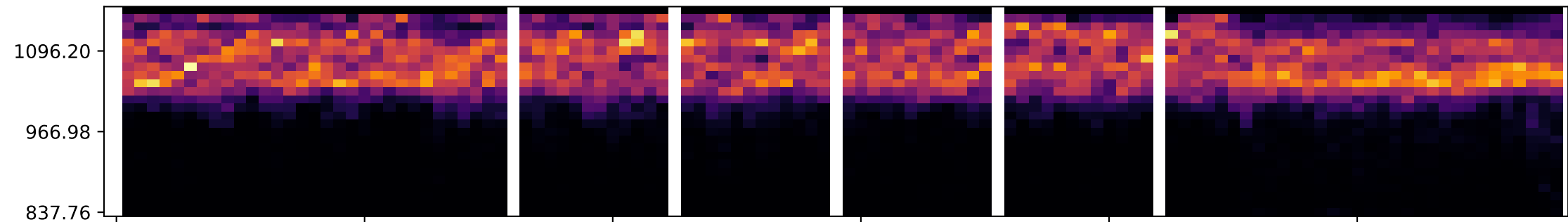
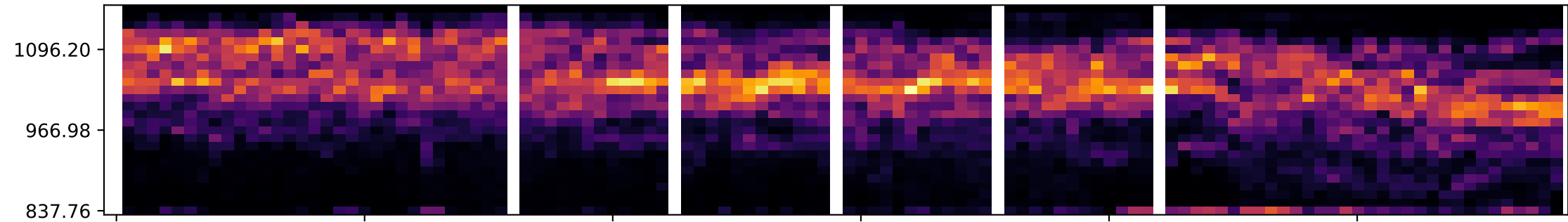




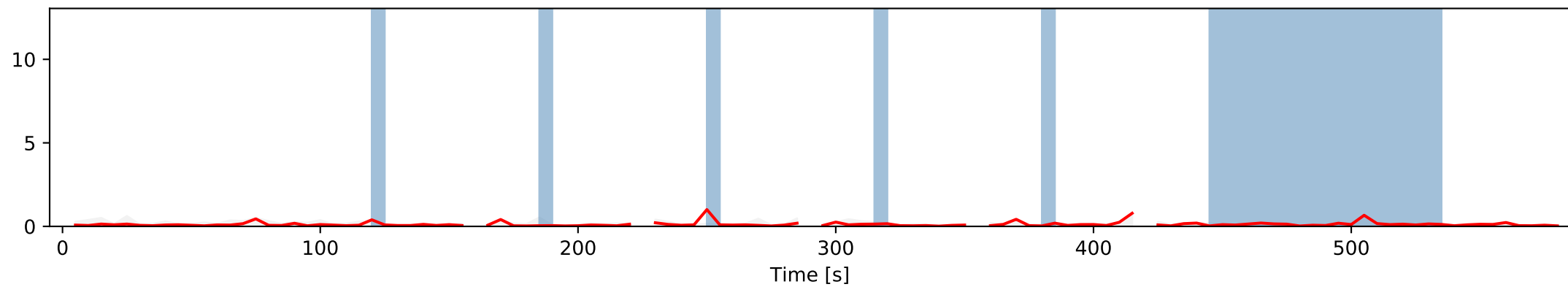
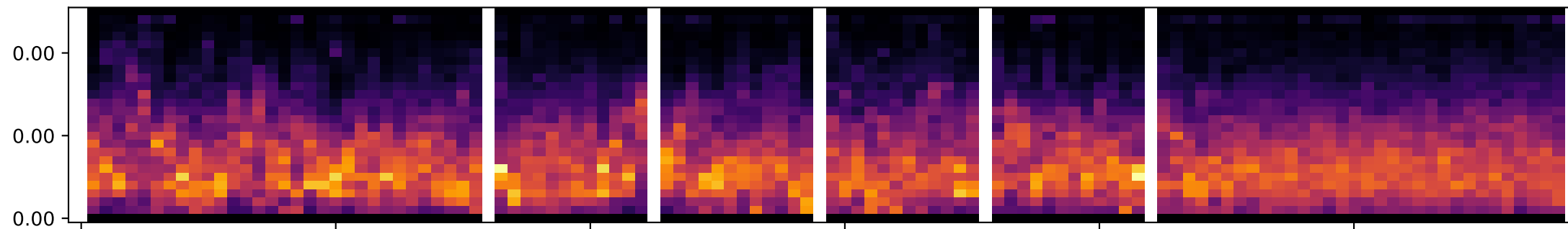
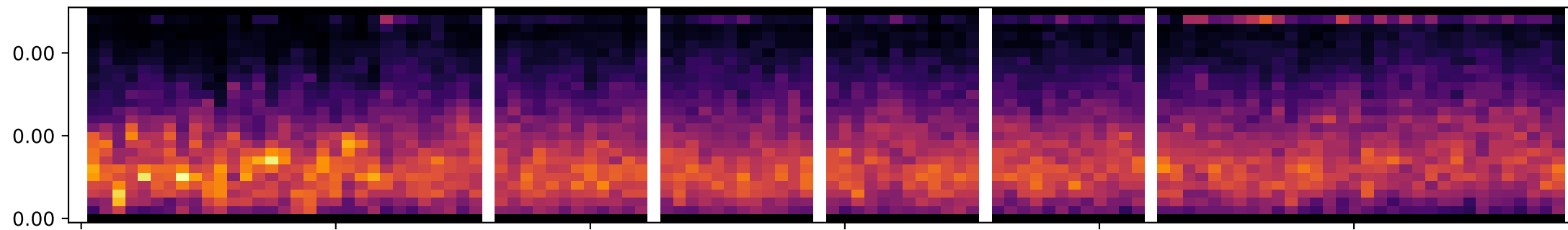
curvature\_mean\_tail



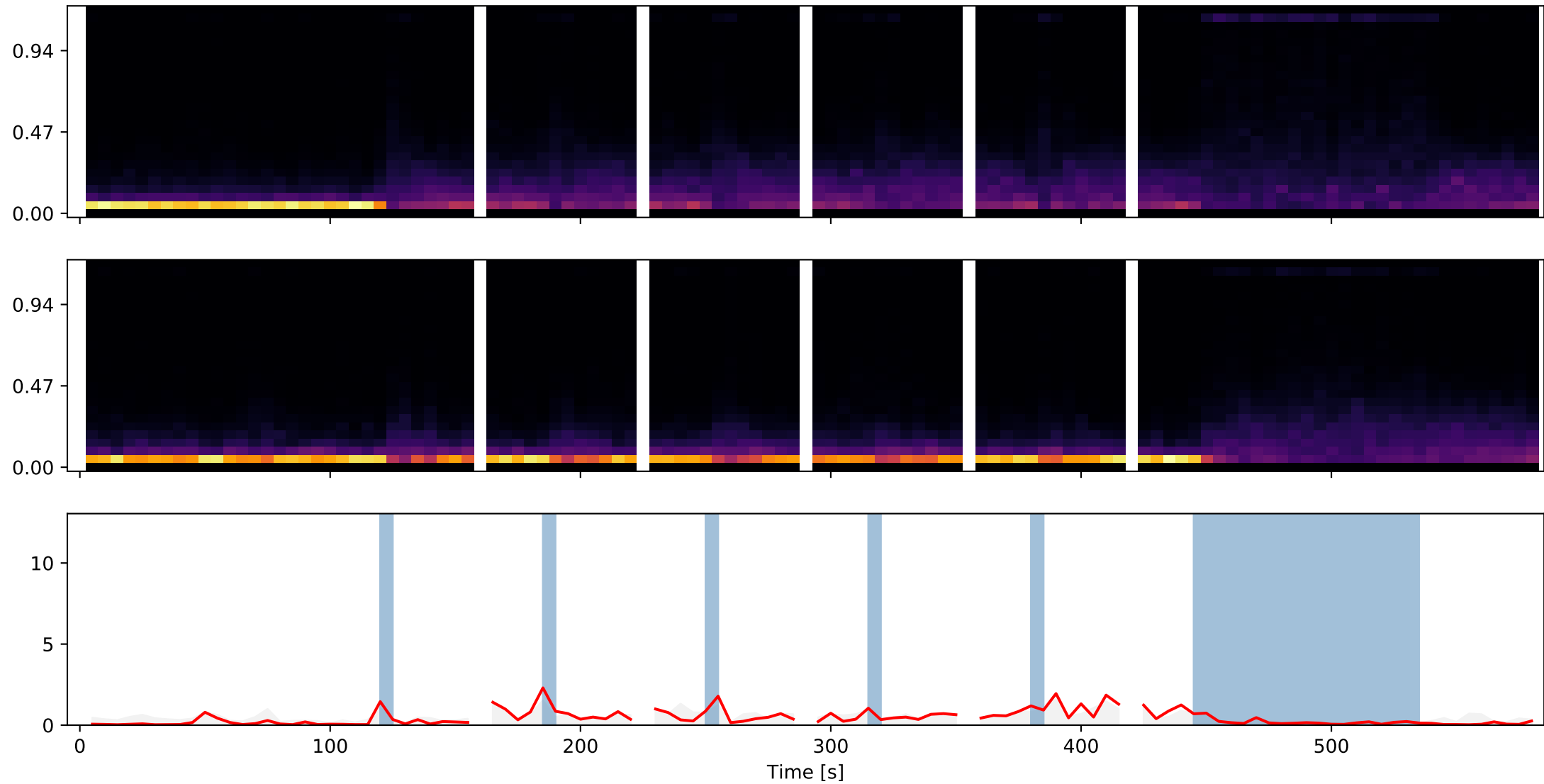
length



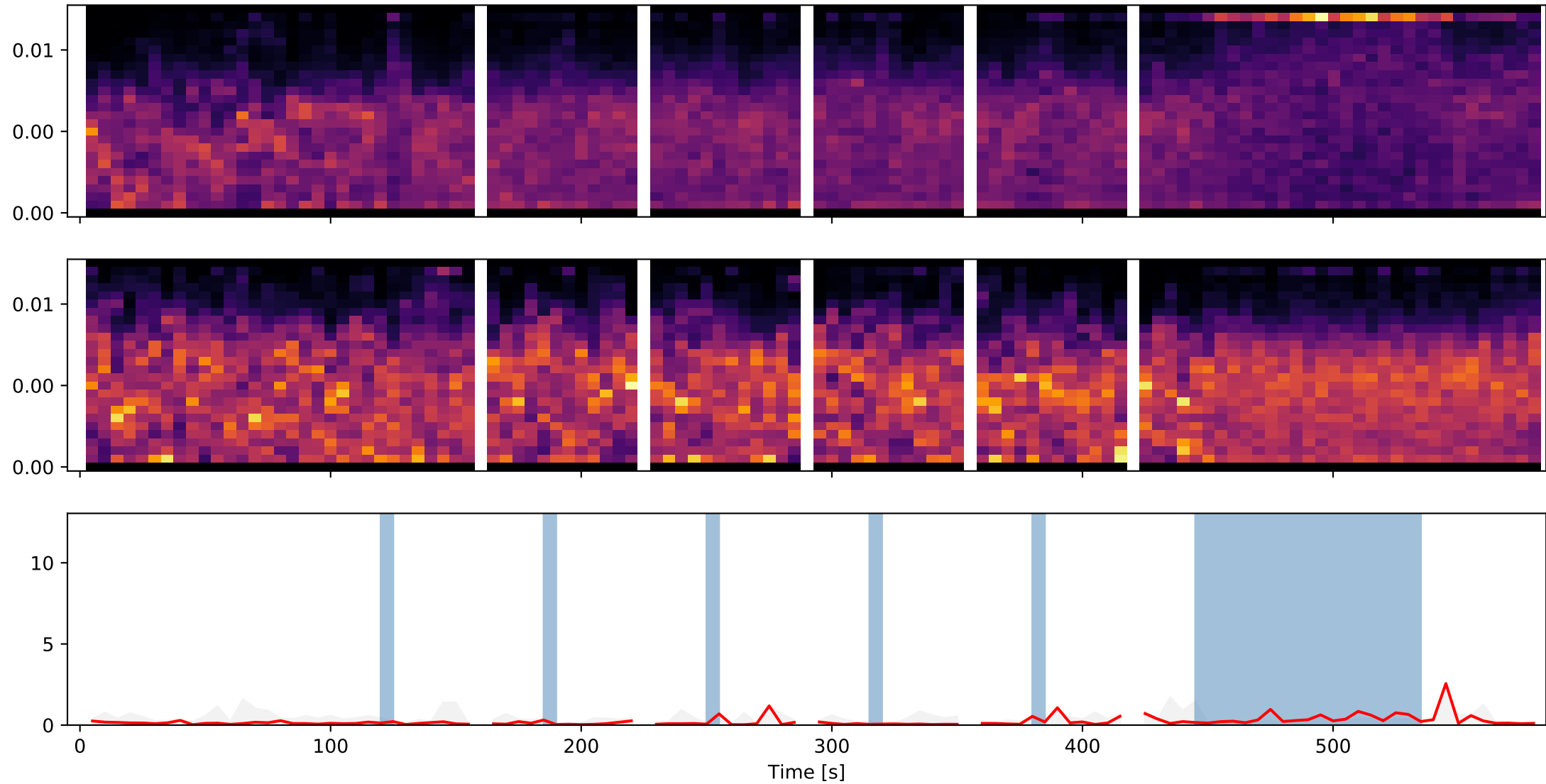
curvature\_std\_tail



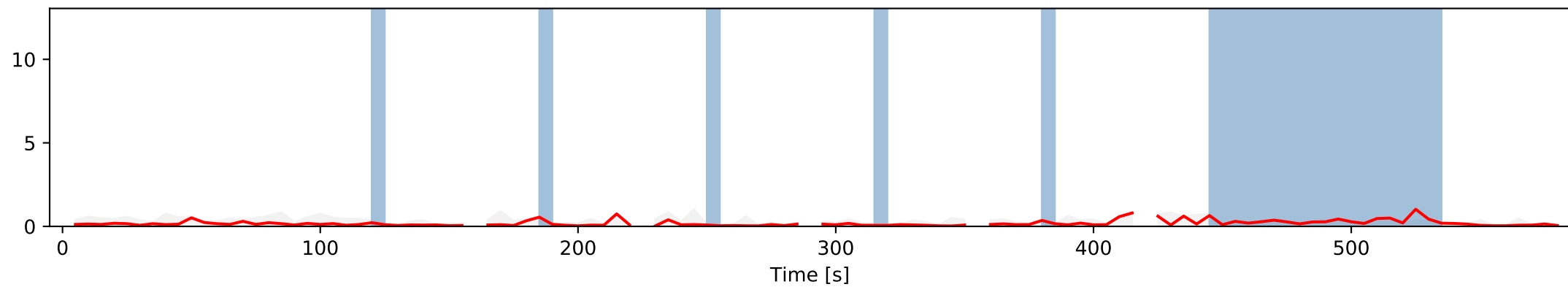
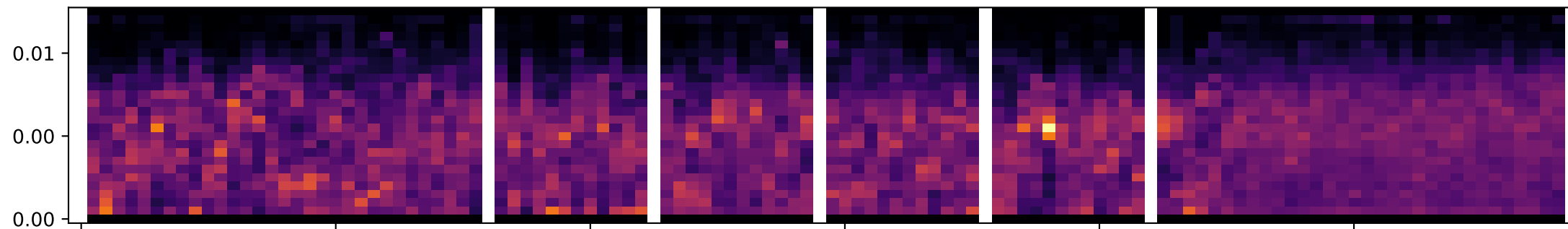
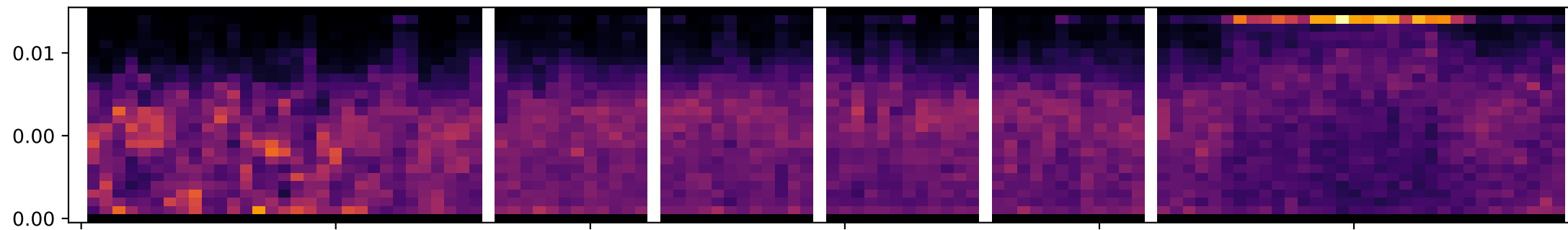
angular\_velocity



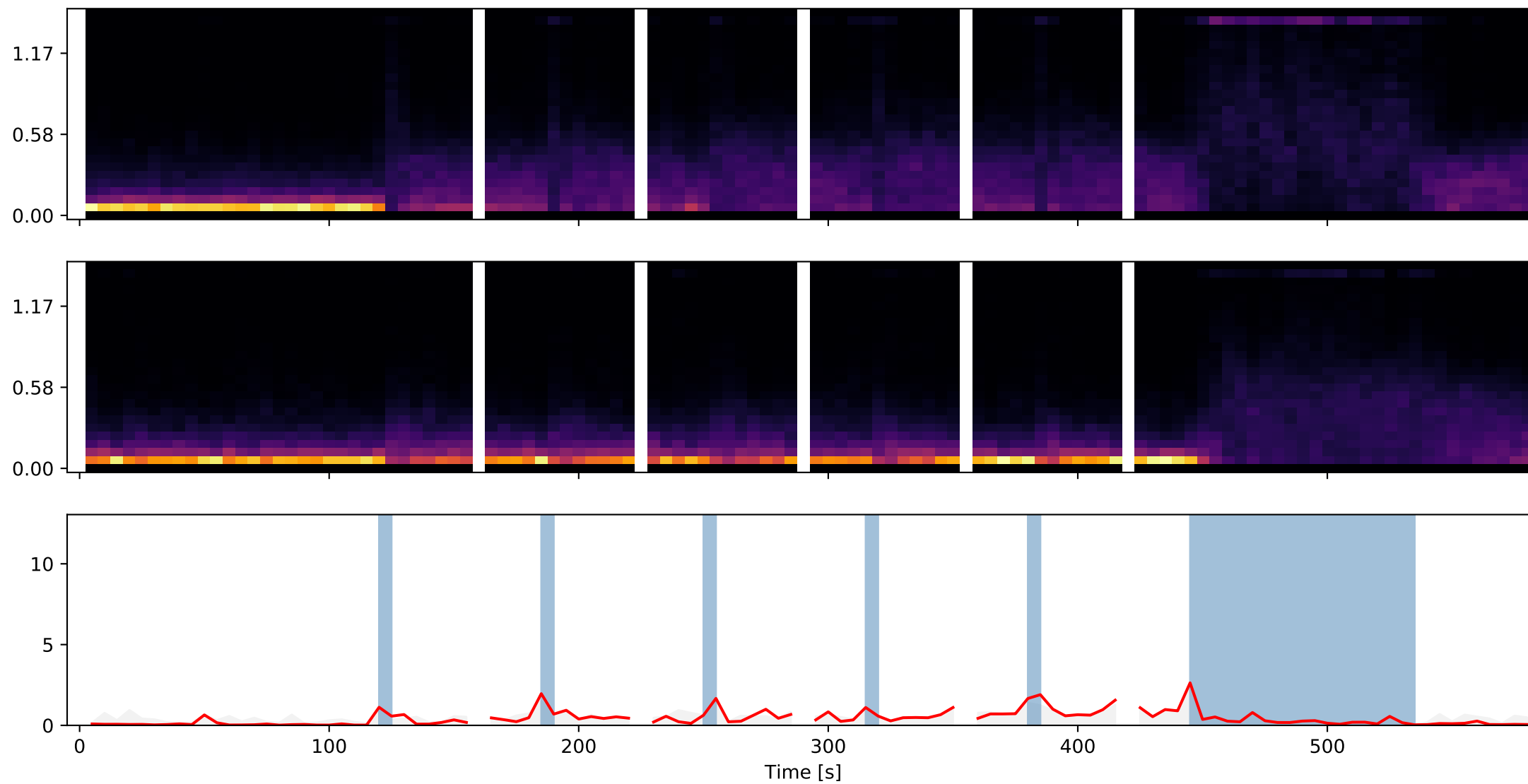
curvature\_midbody



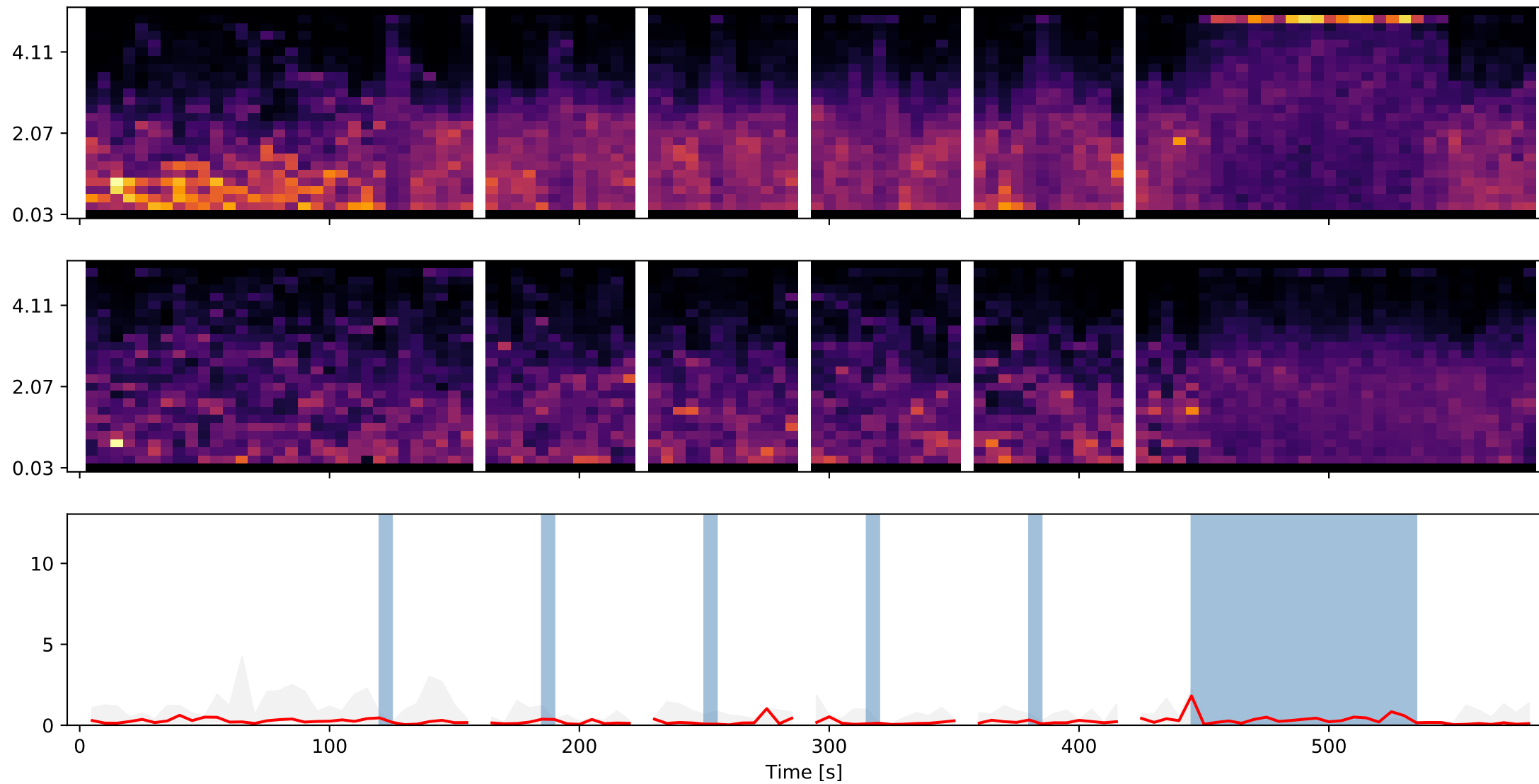
curvature\_neck



relative\_to\_body\_angular\_velocity\_head\_tip

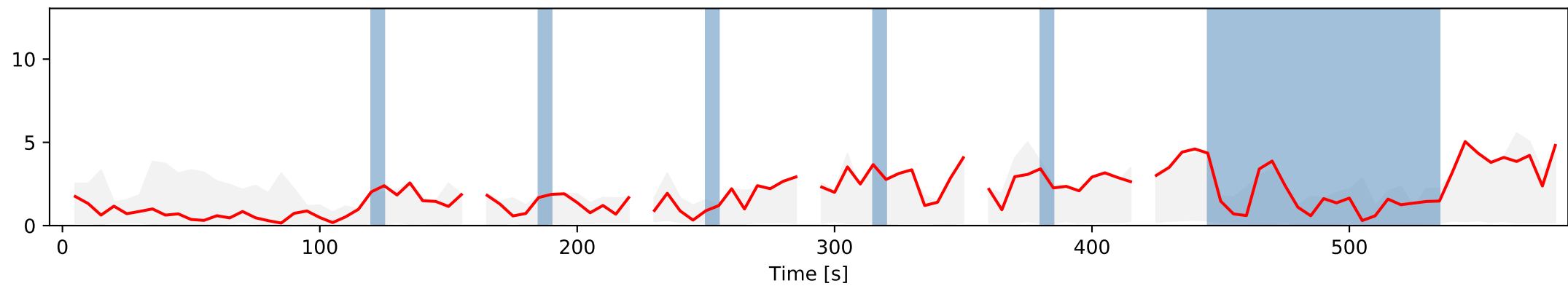
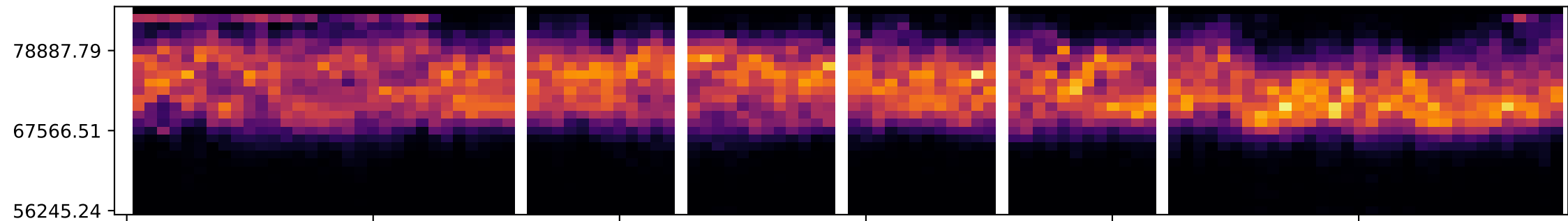
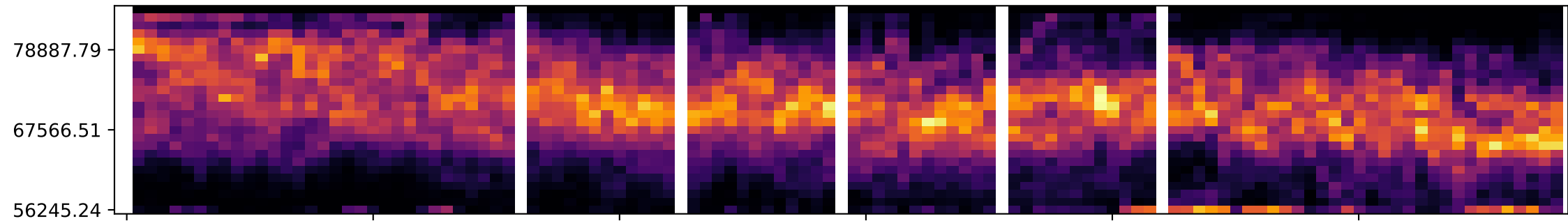


eigen\_projection\_3

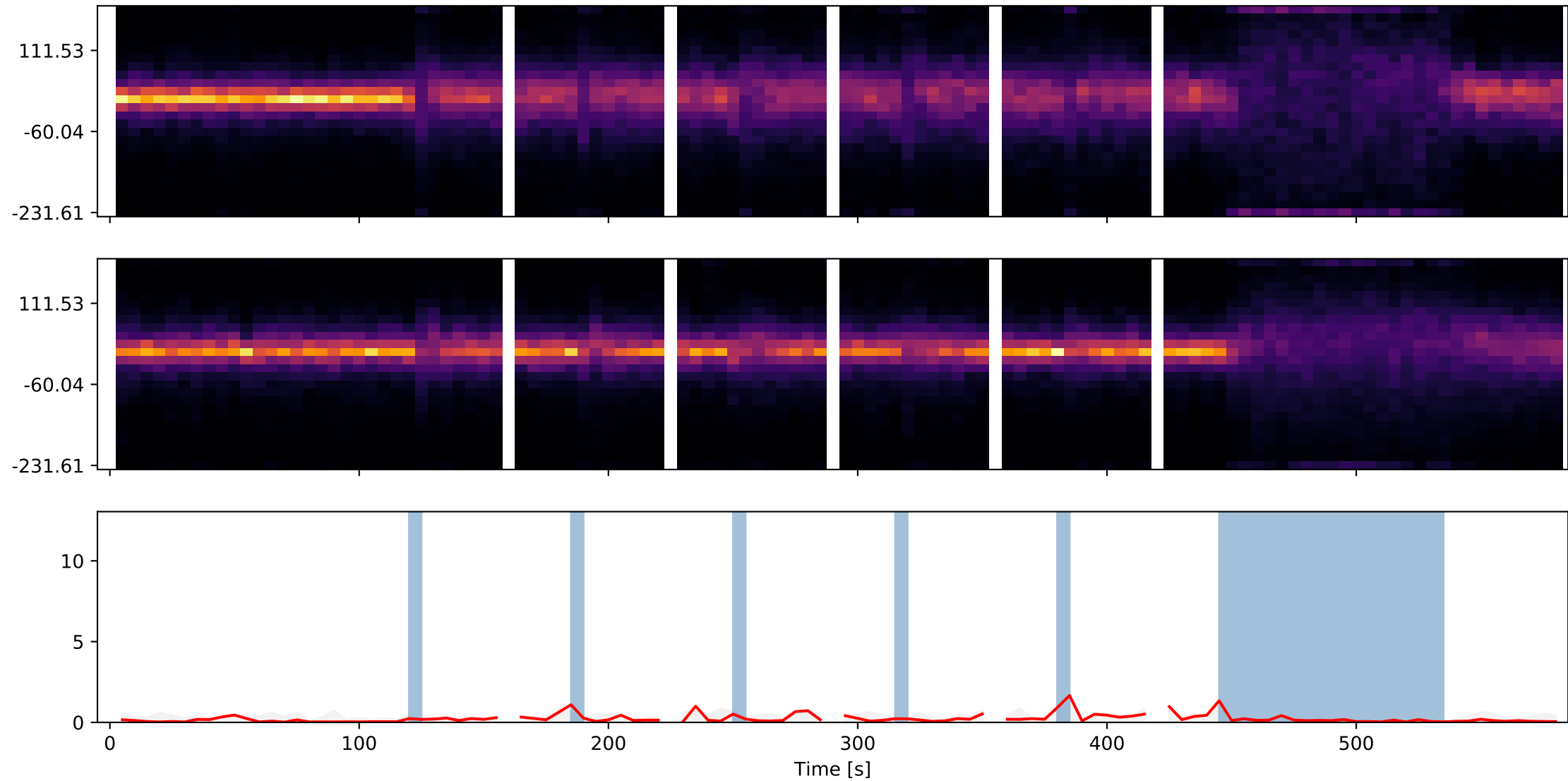




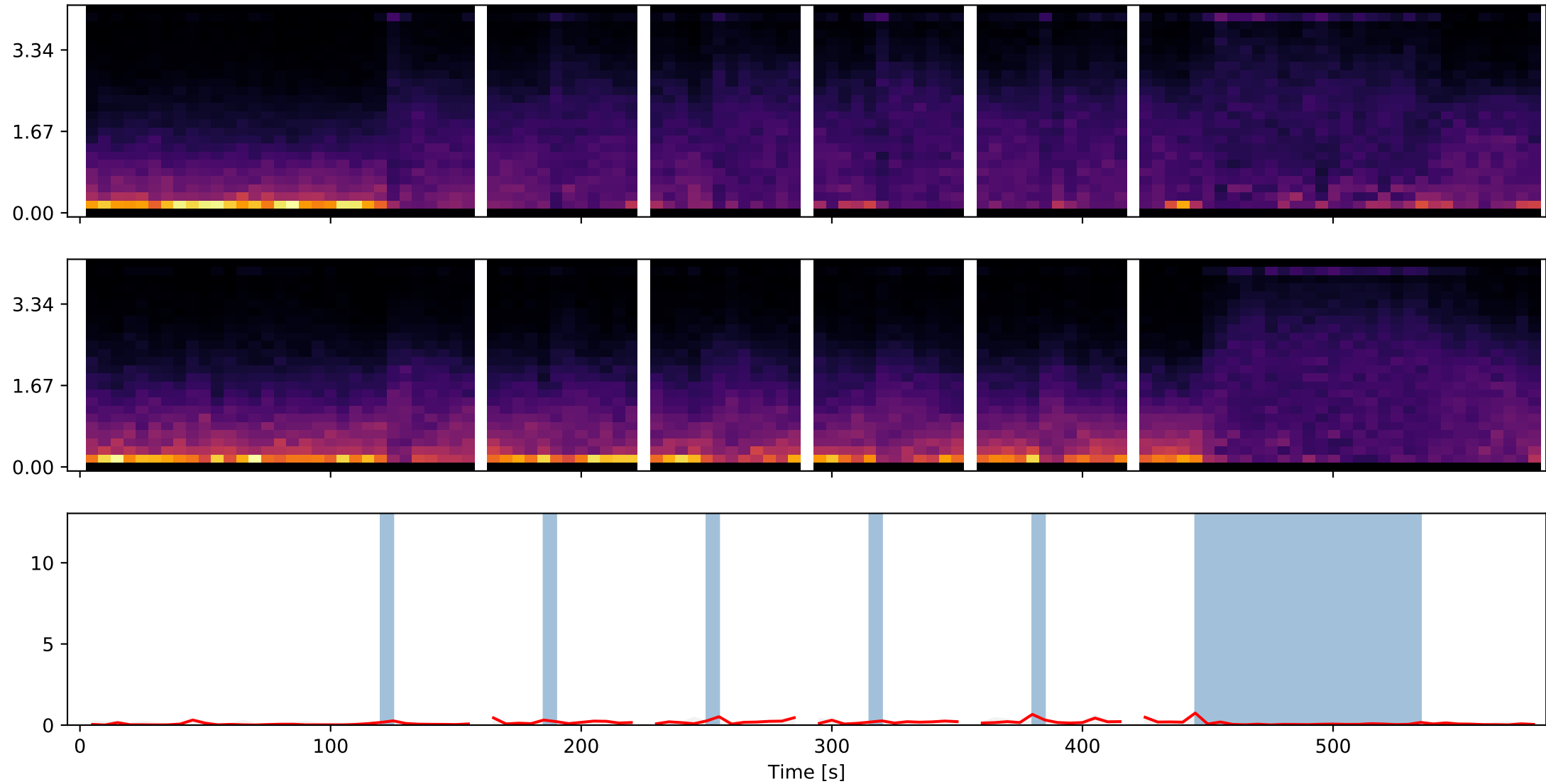
area



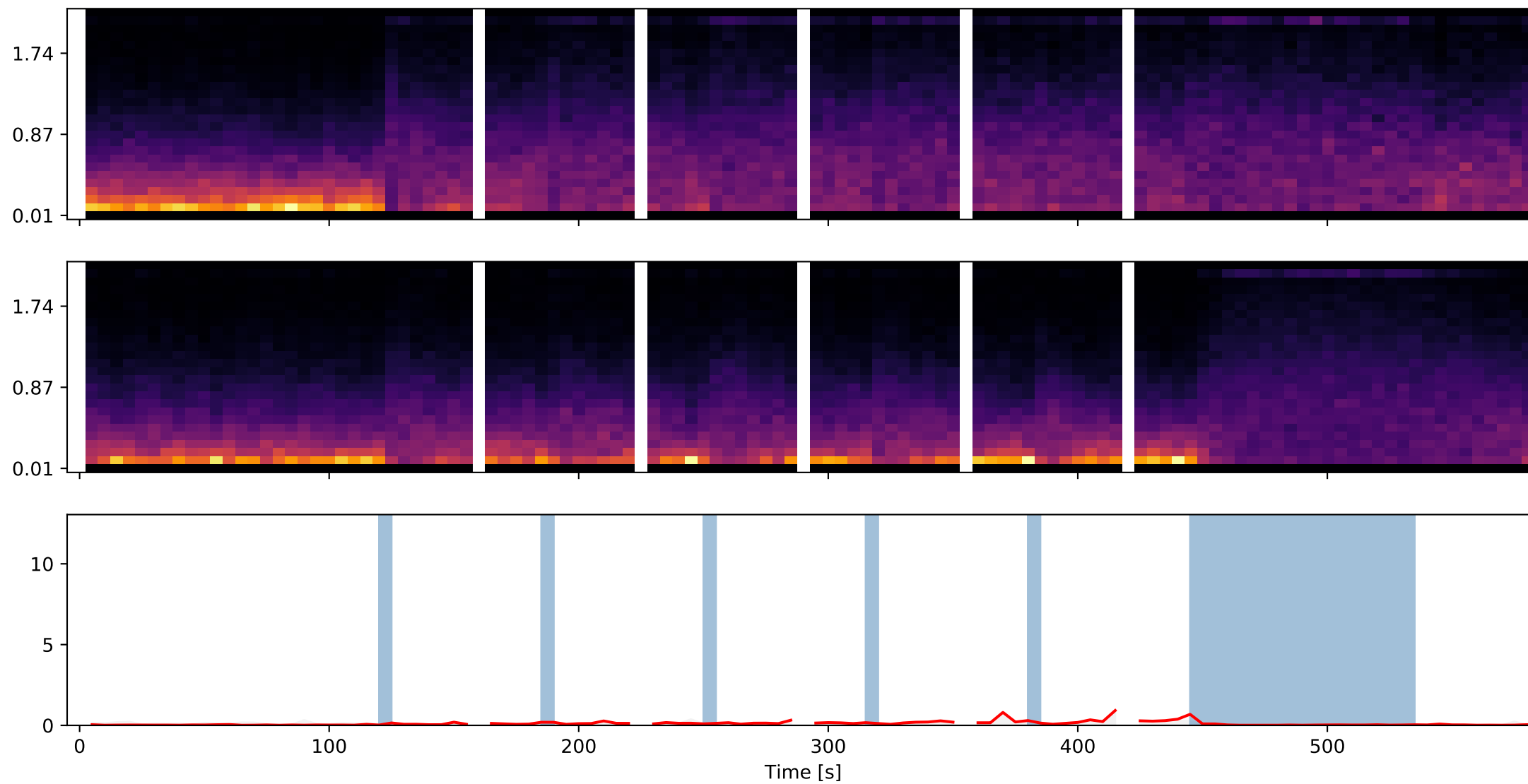
relative\_to\_body\_radial\_velocity\_head\_tip



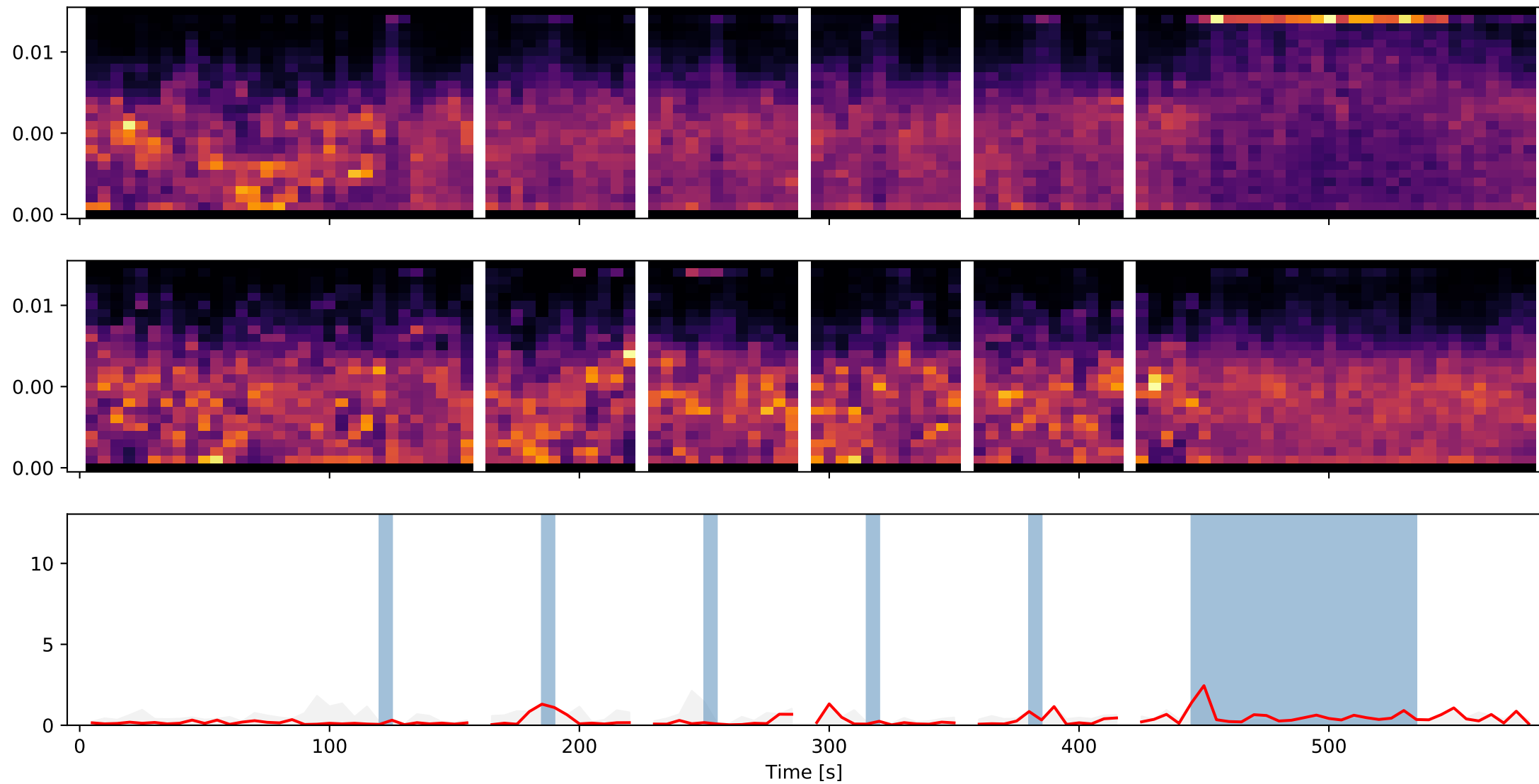
angular\_velocity\_head\_tip



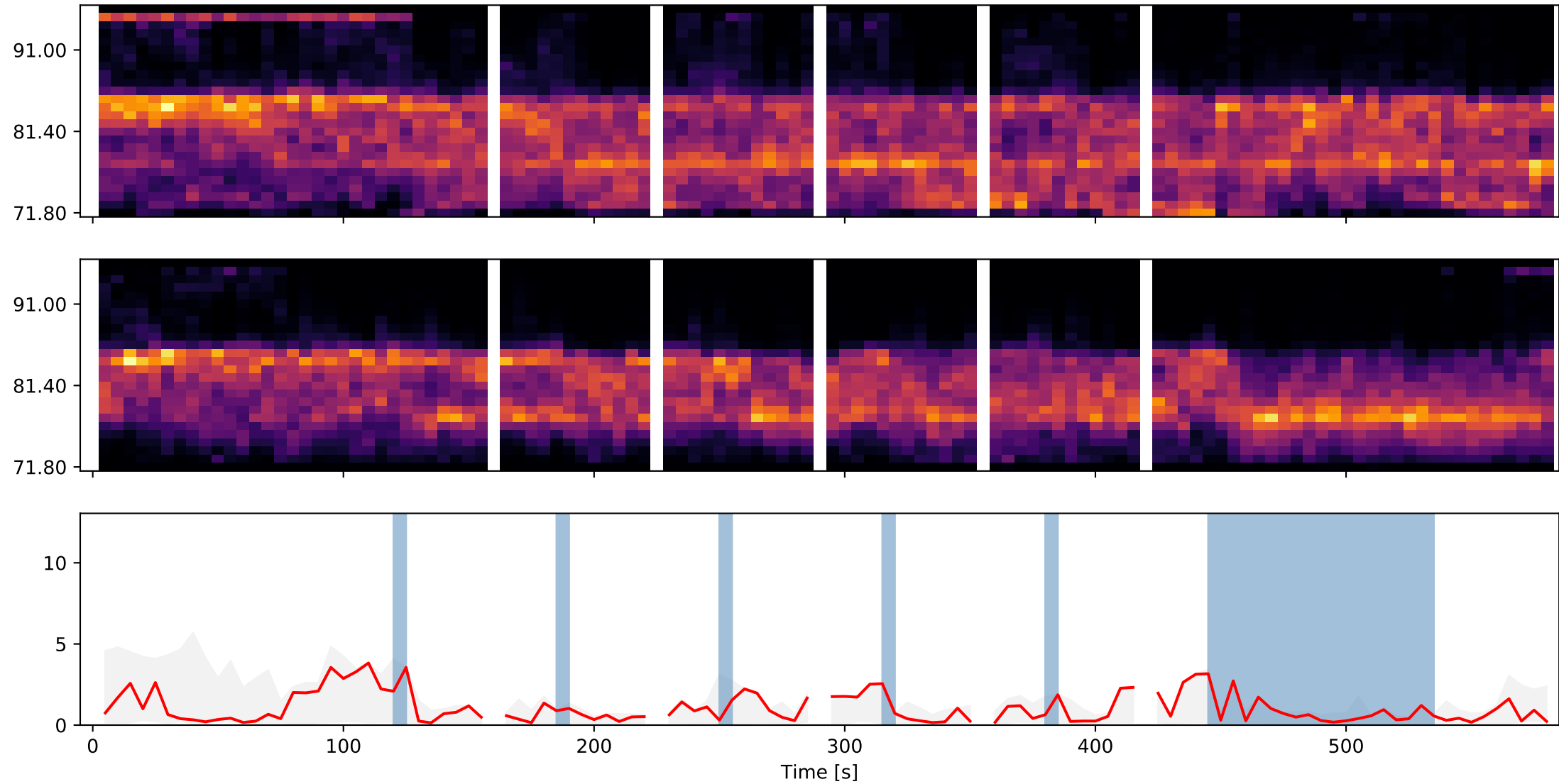
relative\_to\_head\_base\_angular\_velocity\_head\_tip



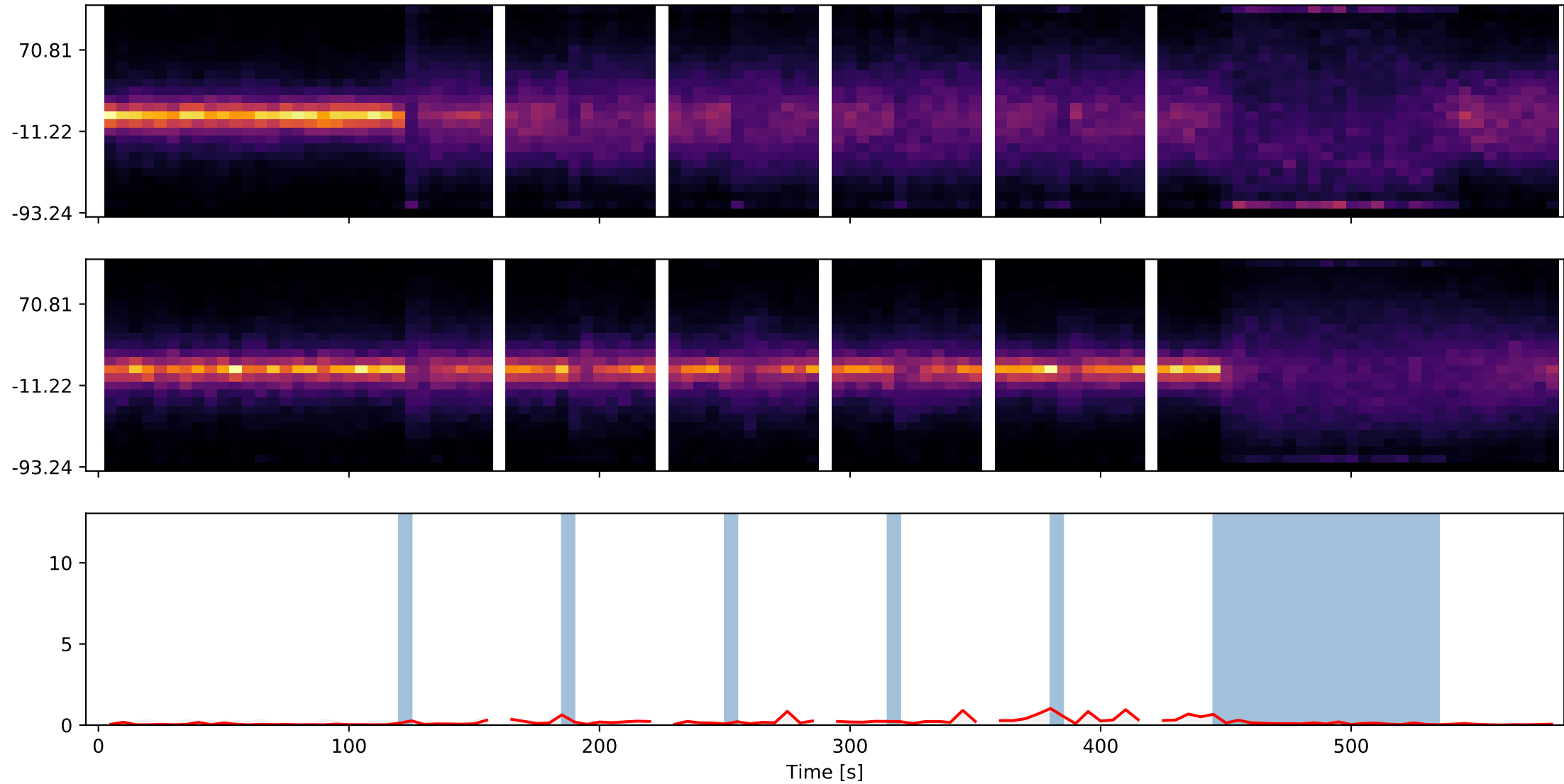
curvature\_hips



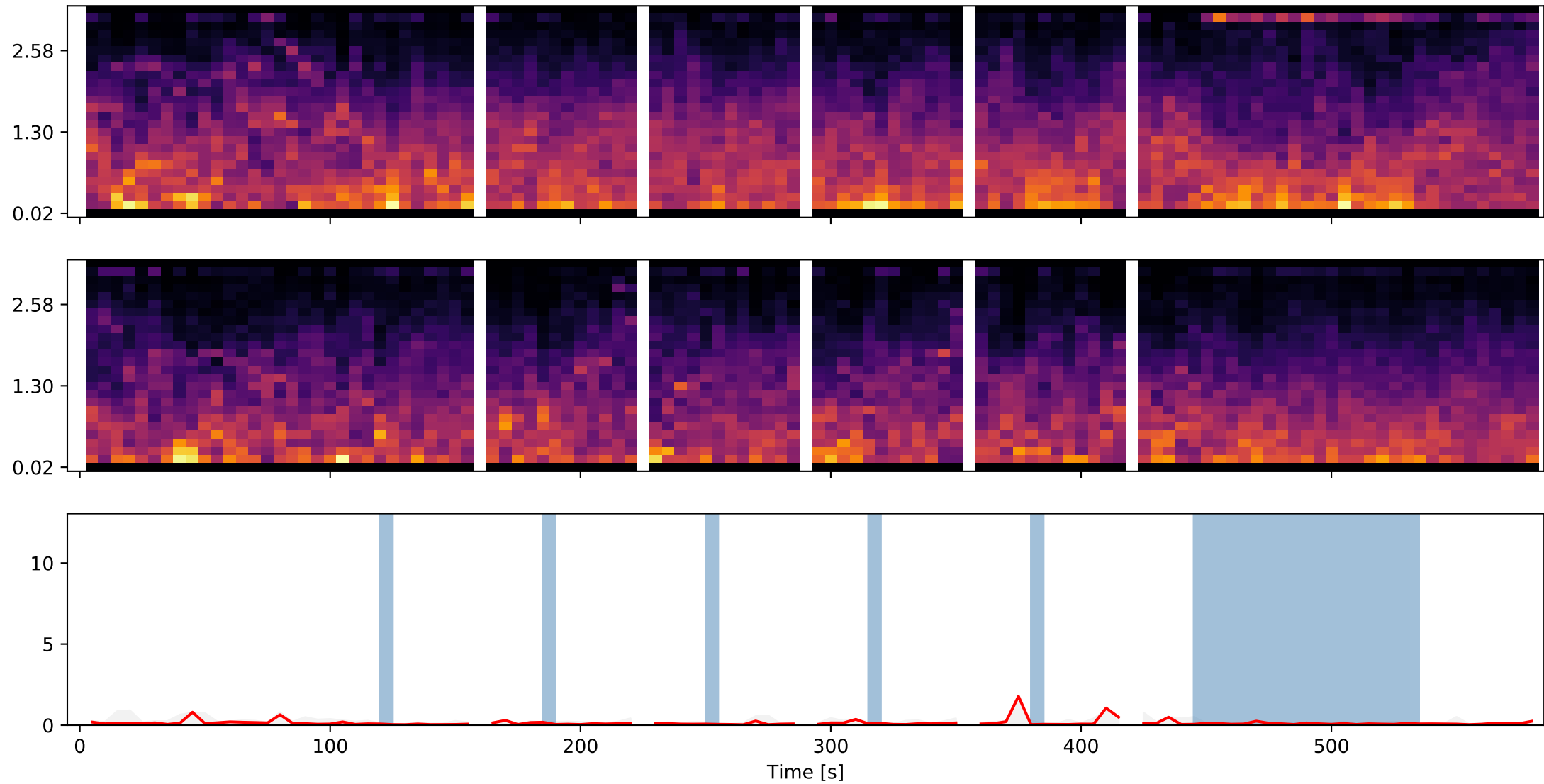
width\_midbody



relative\_to\_neck\_radial\_velocity\_head\_tip

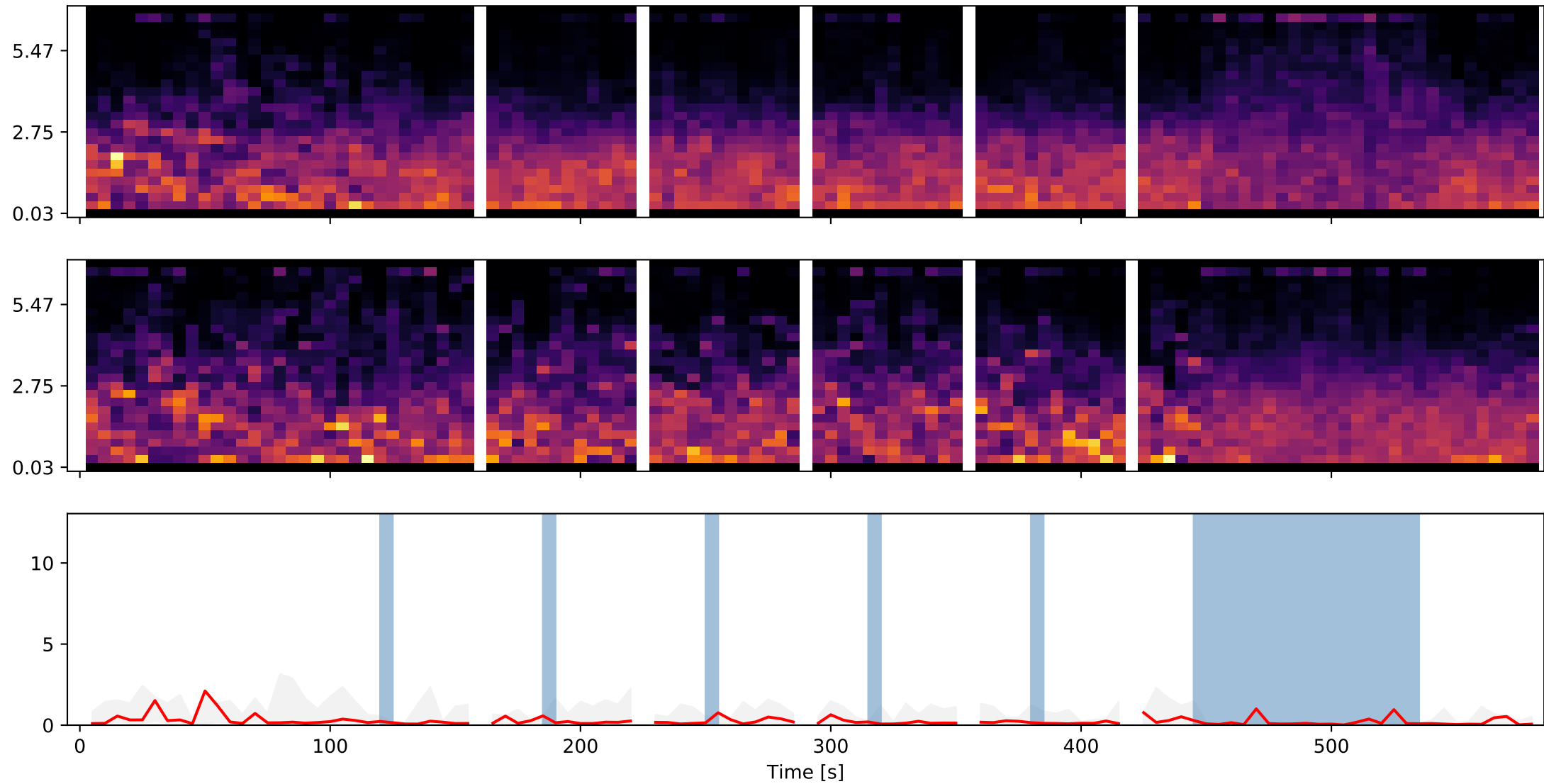


eigen\_projection\_4

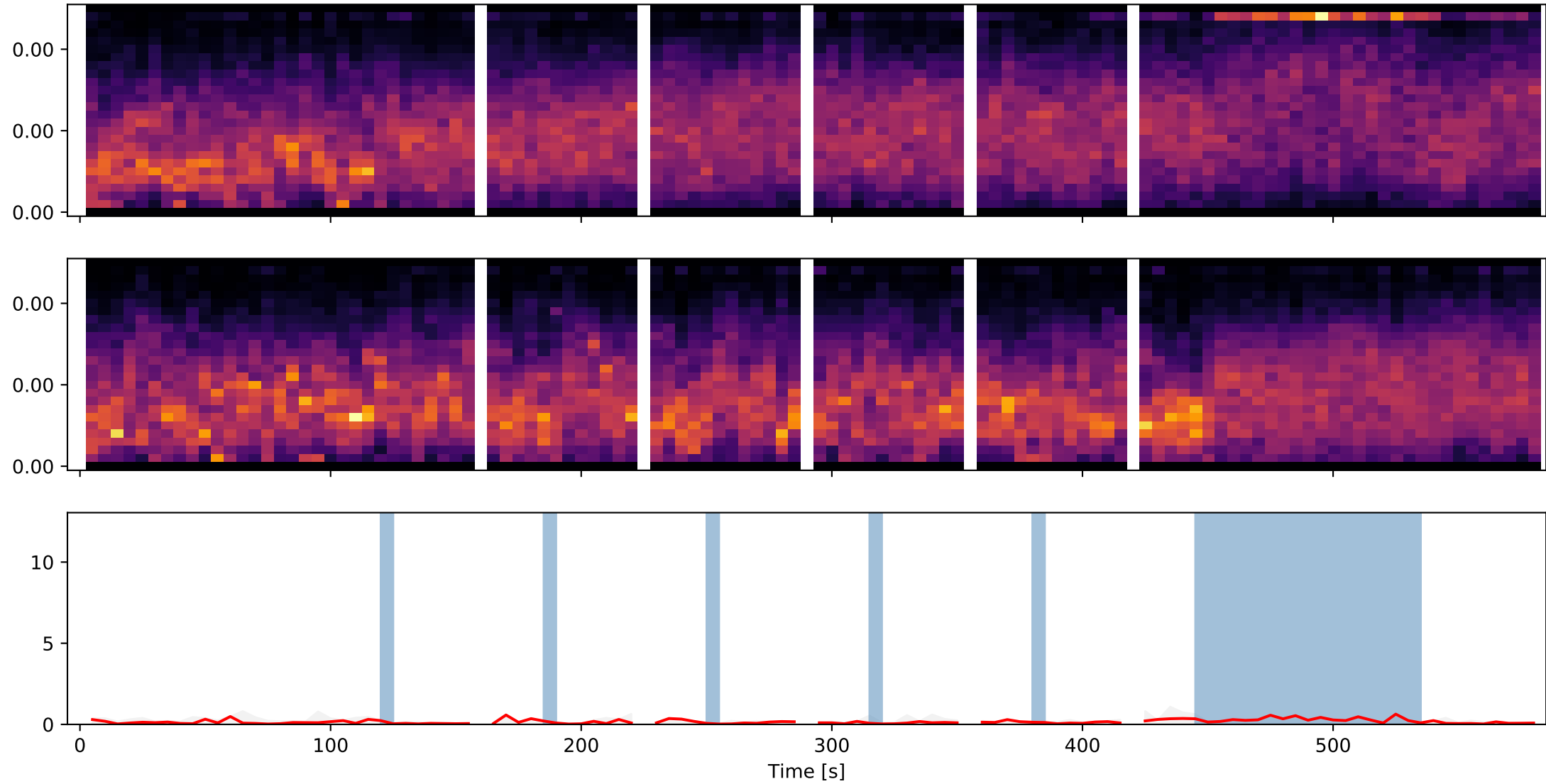




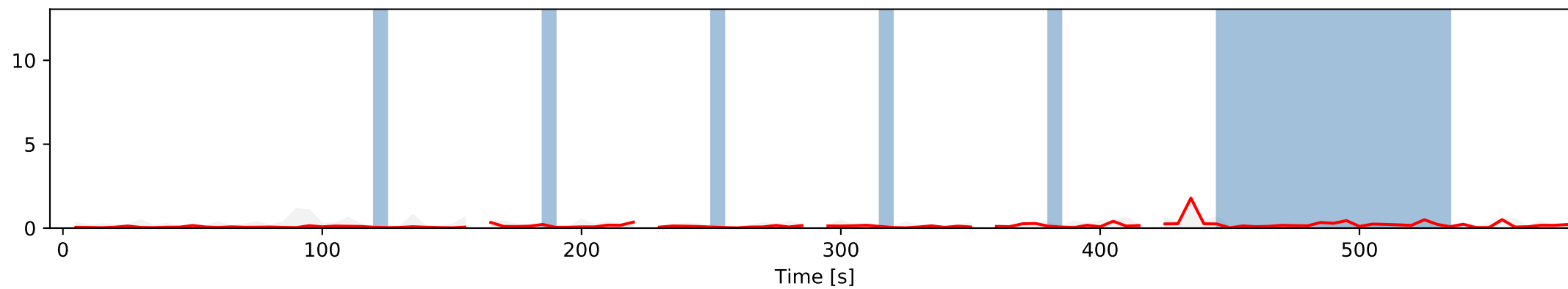
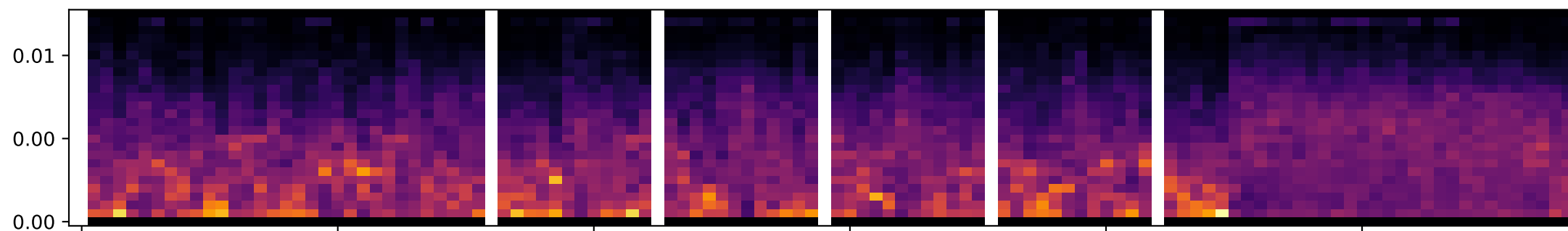
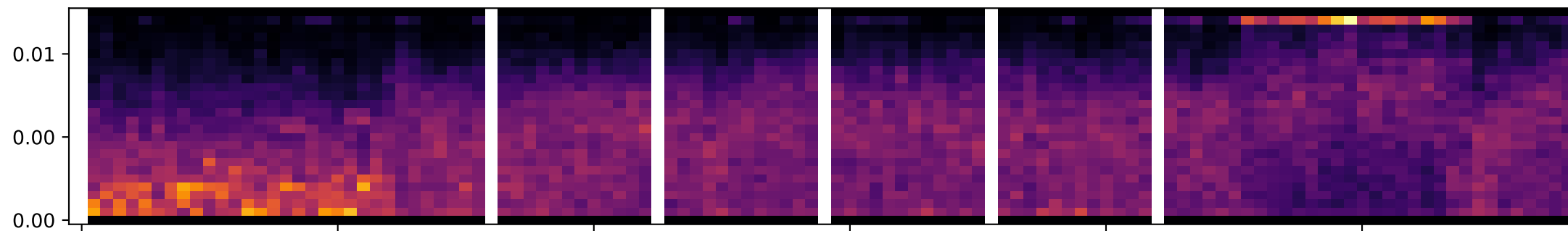
eigen\_projection\_1



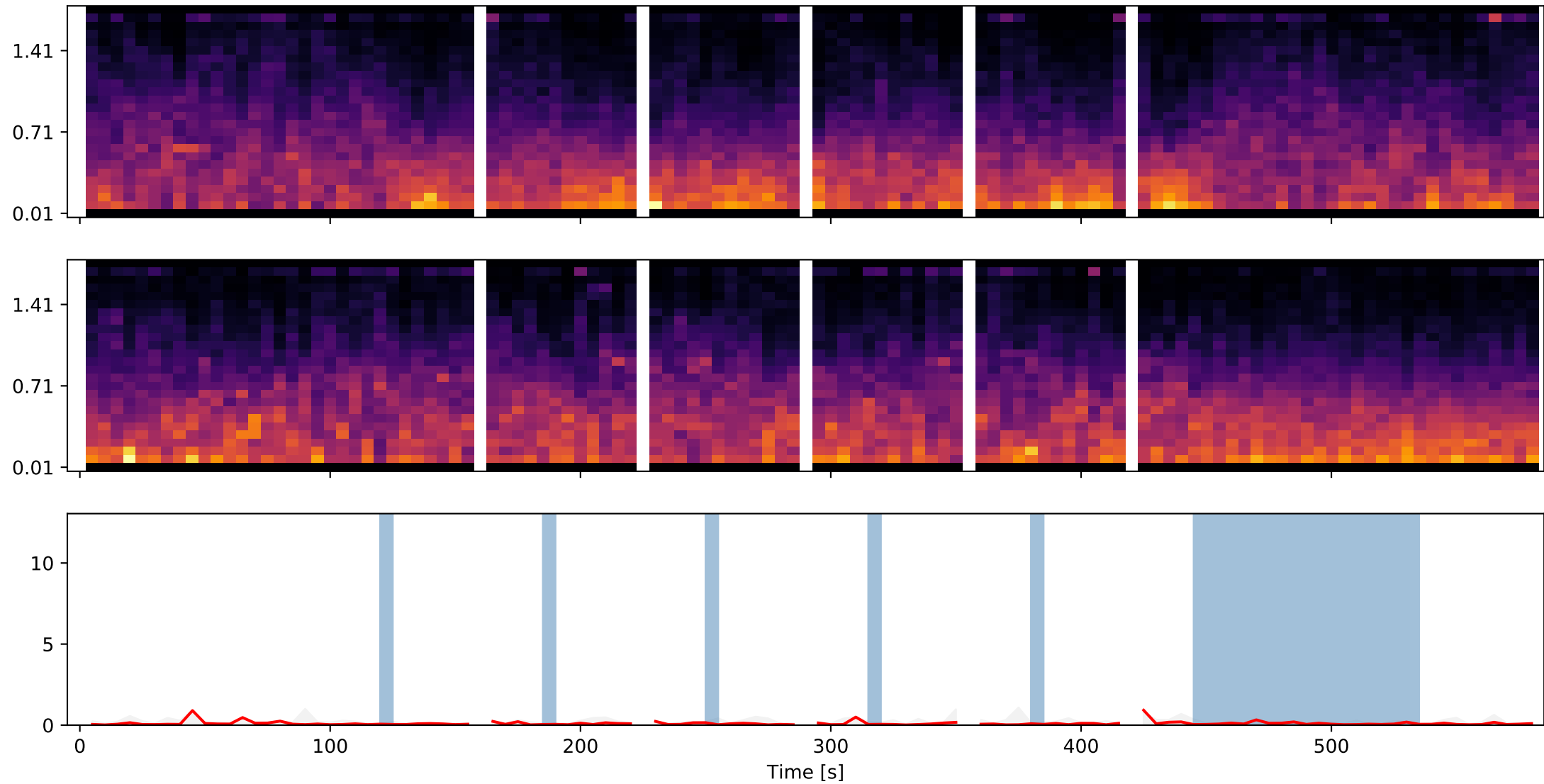
curvature\_std\_neck



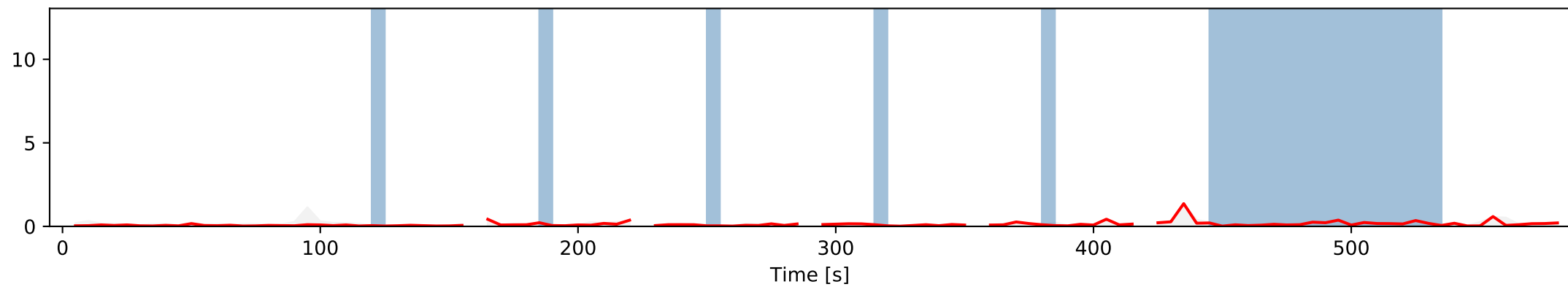
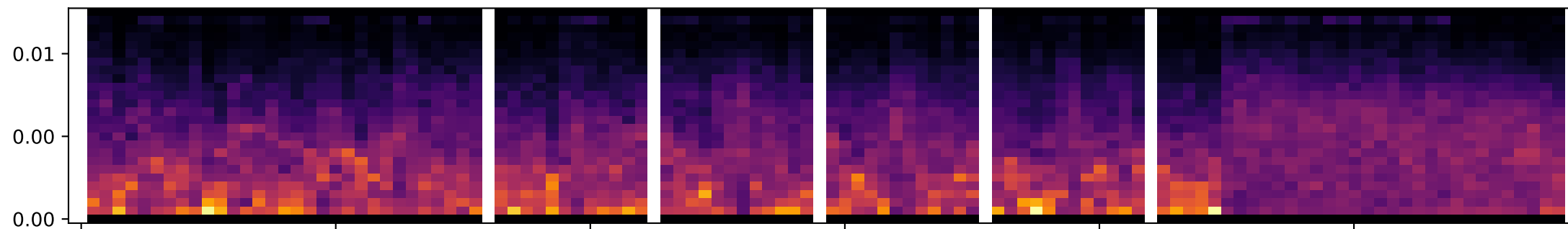
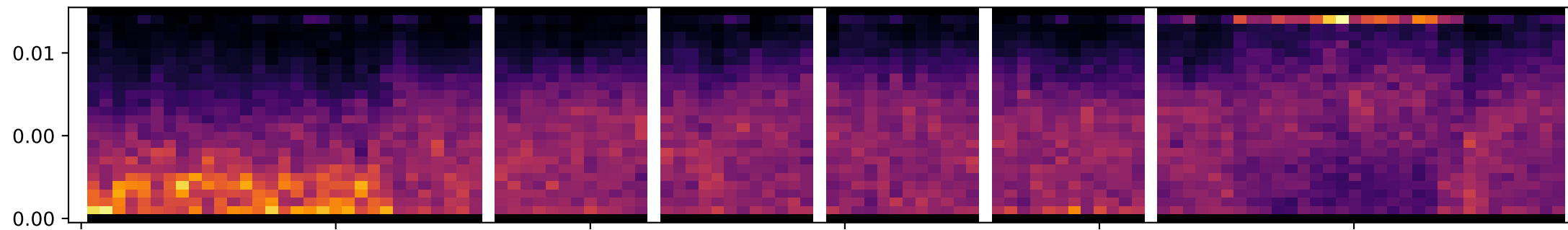
curvature\_mean\_head



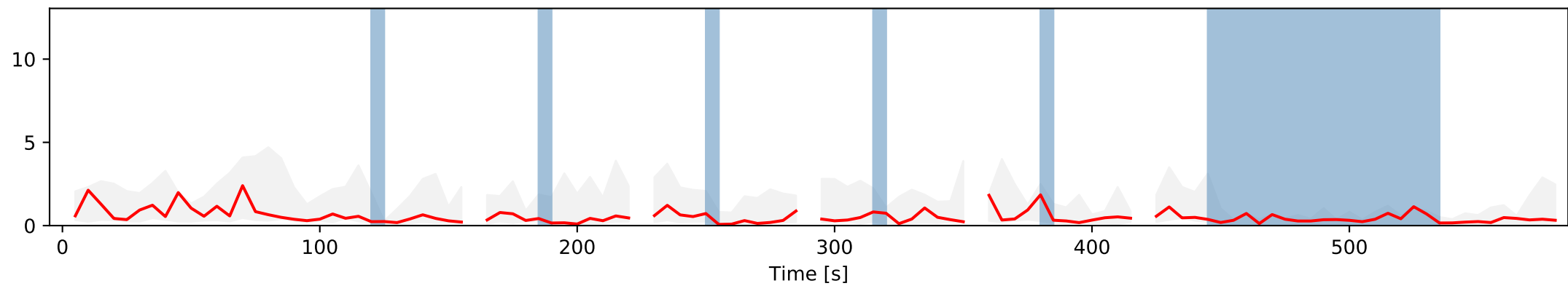
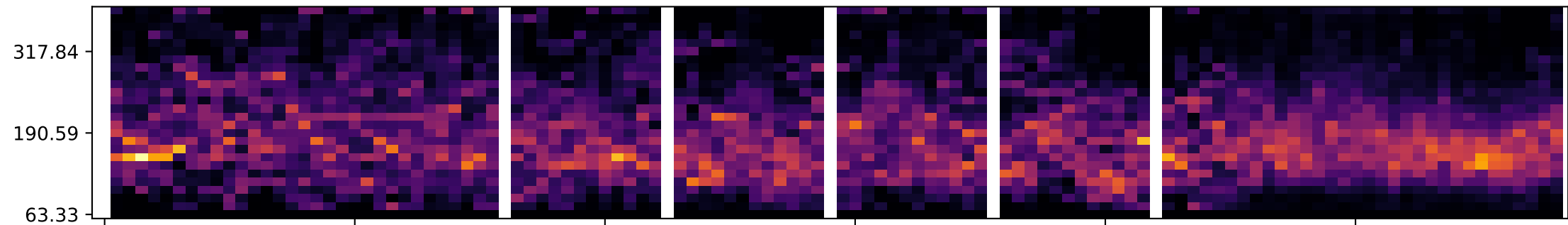
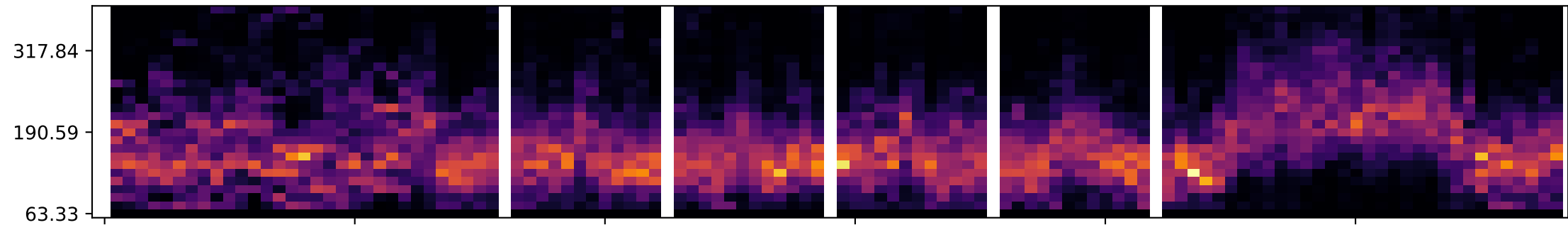
eigen\_projection\_5



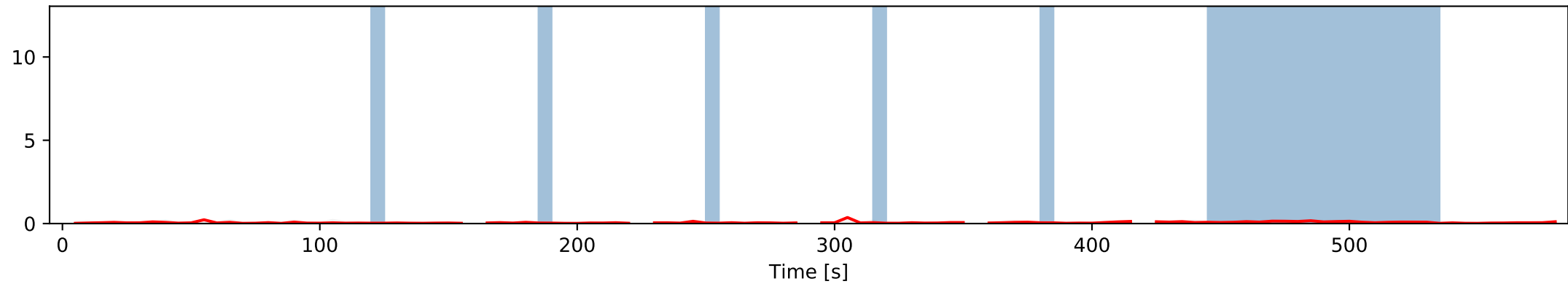
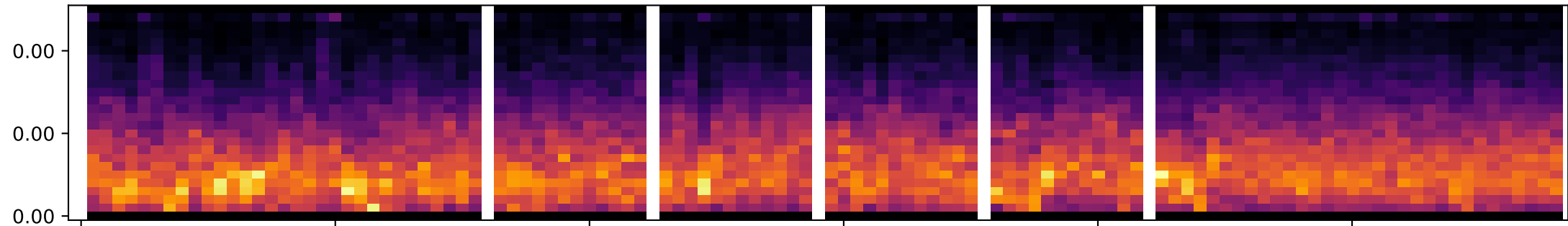
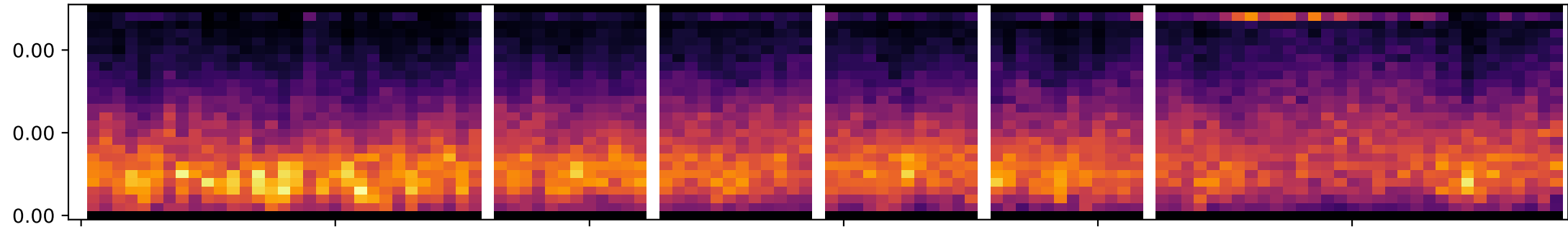
curvature\_head



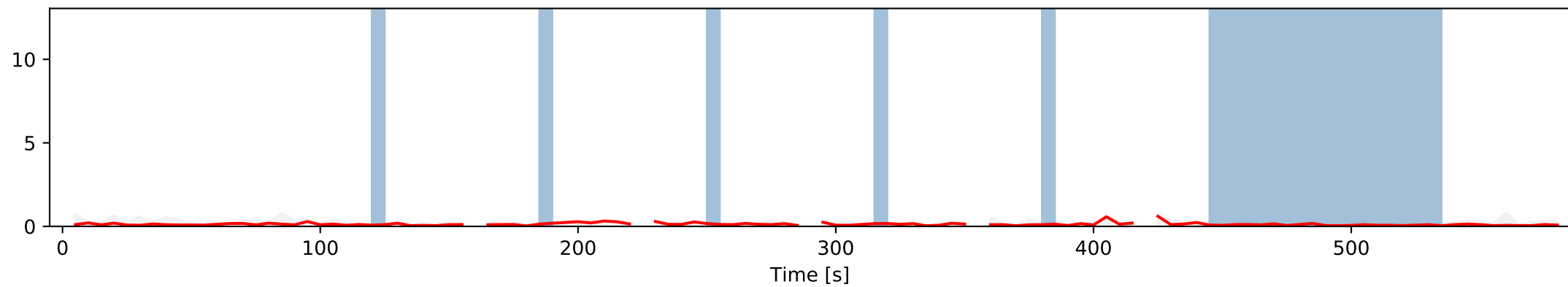
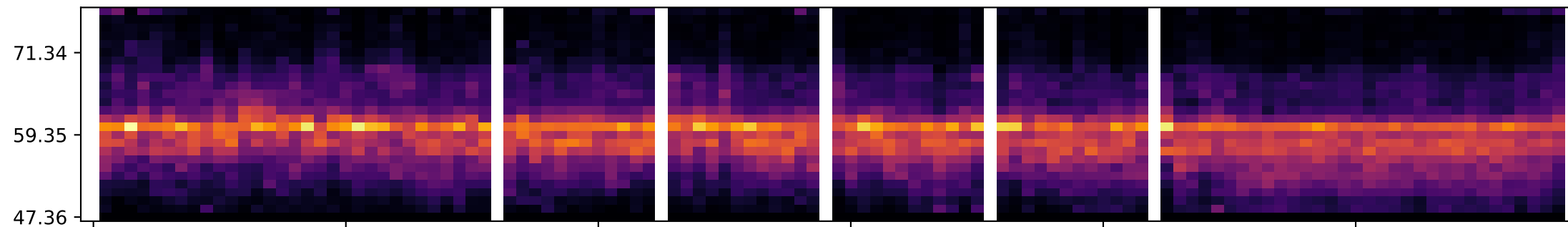
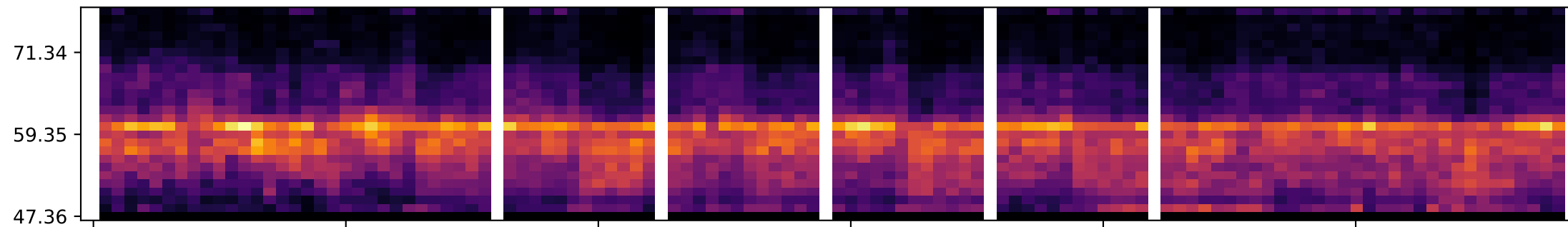
minor\_axis



curvature\_std\_head

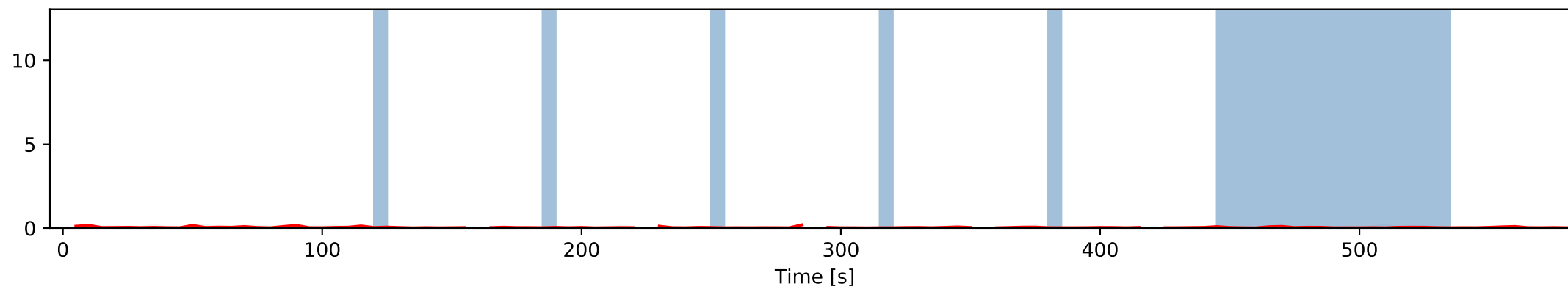
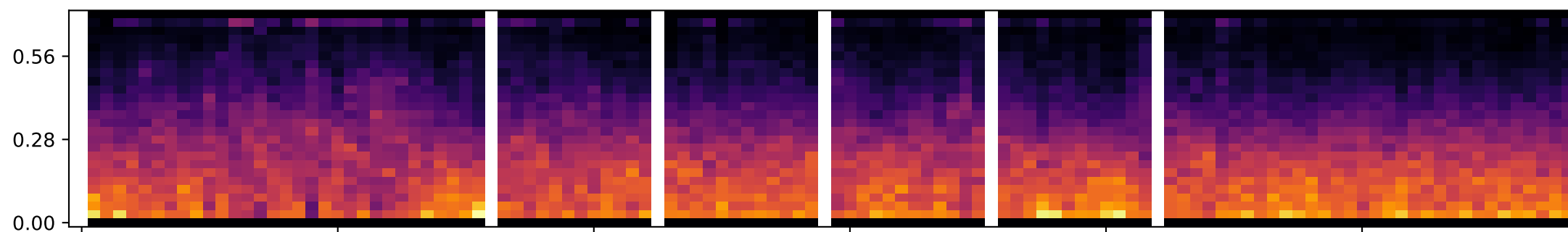
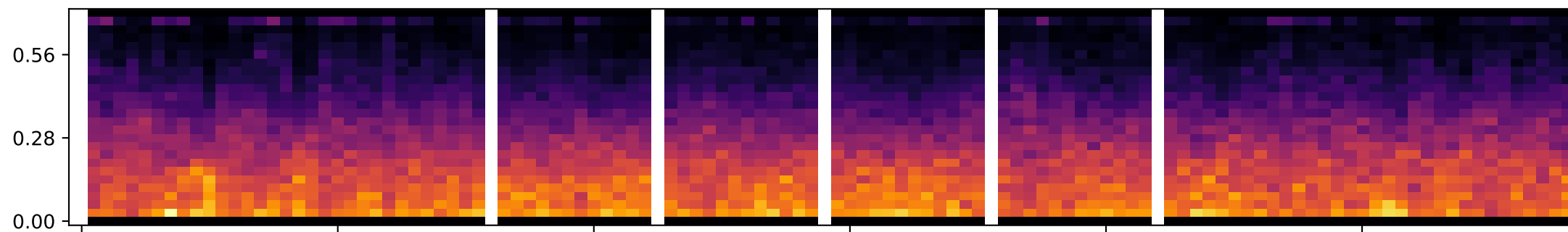


width\_head\_base





eigen\_projection\_7



eigen\_projection\_6

