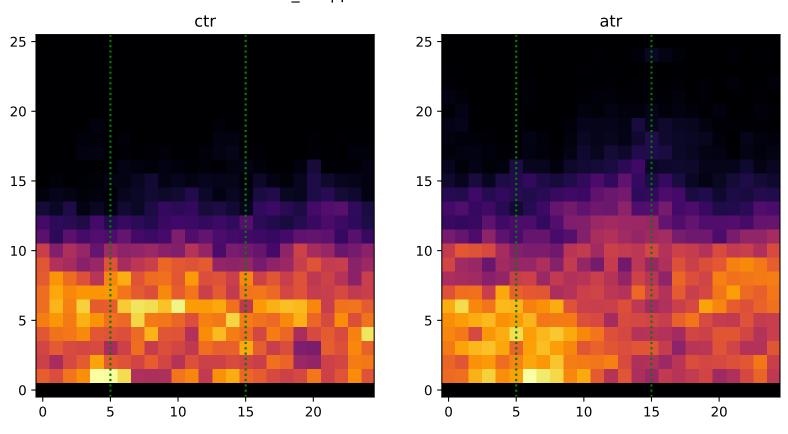
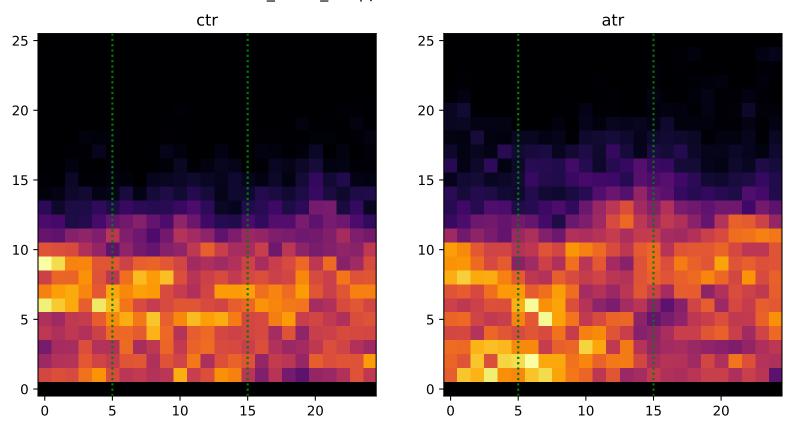
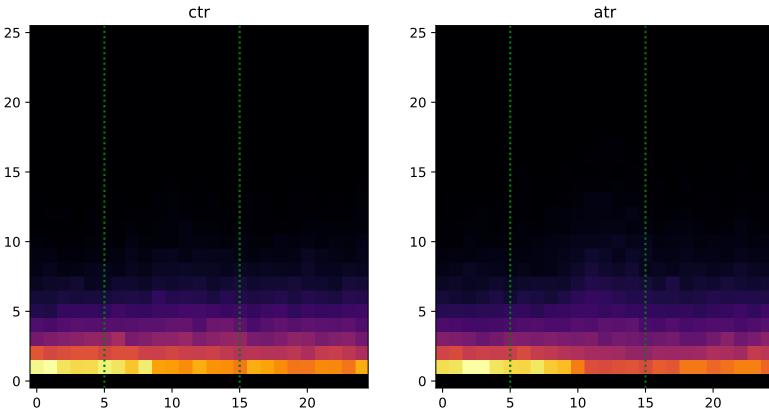
## curvature\_tail | pval:0.004319654427645789



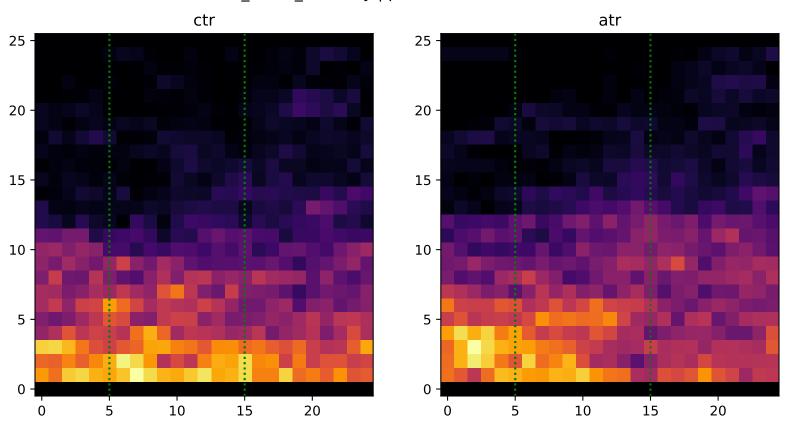
## curvature\_mean\_tail | pval:0.012958963282937365



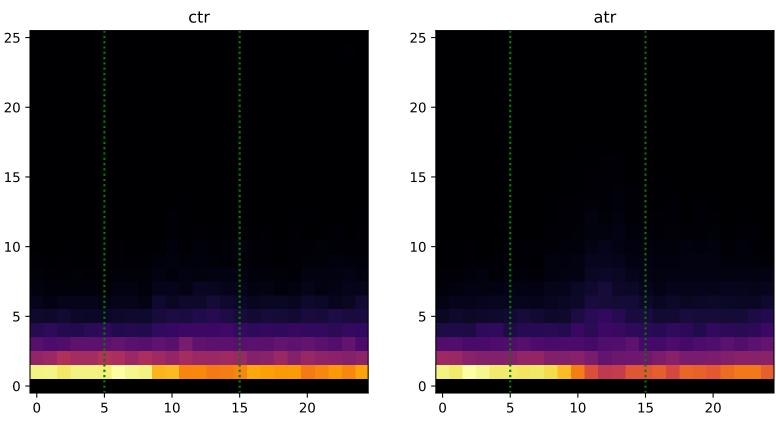
d\_curvature\_std\_tail | pval:0.019438444924406047



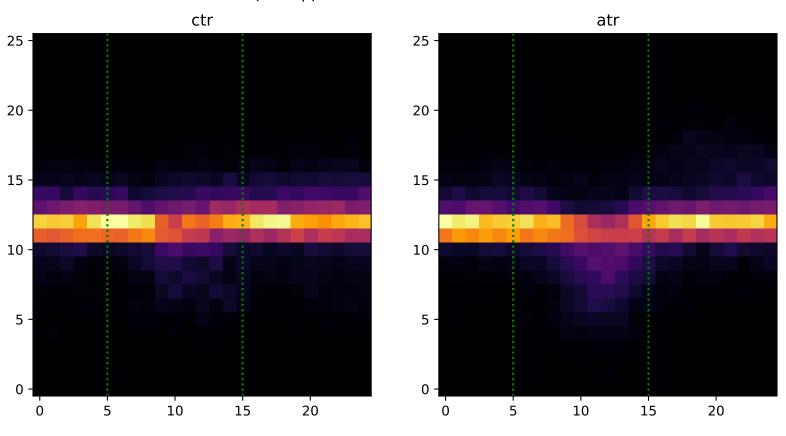
## curvature\_mean\_midbody | pval:0.038876889848812095



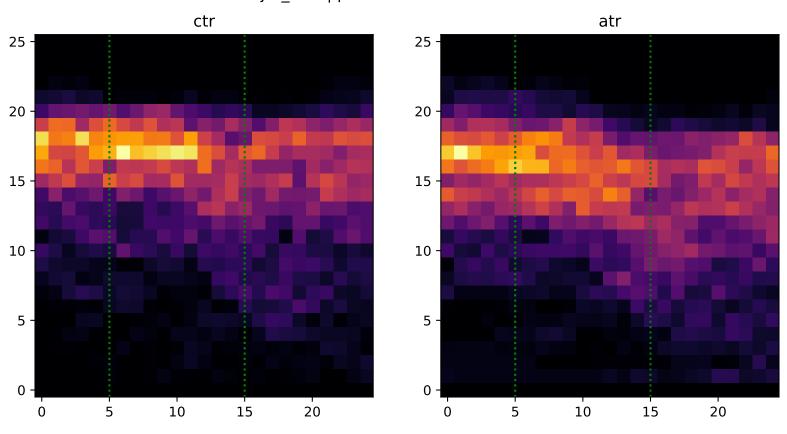
d\_curvature\_tail | pval:0.04103671706263499



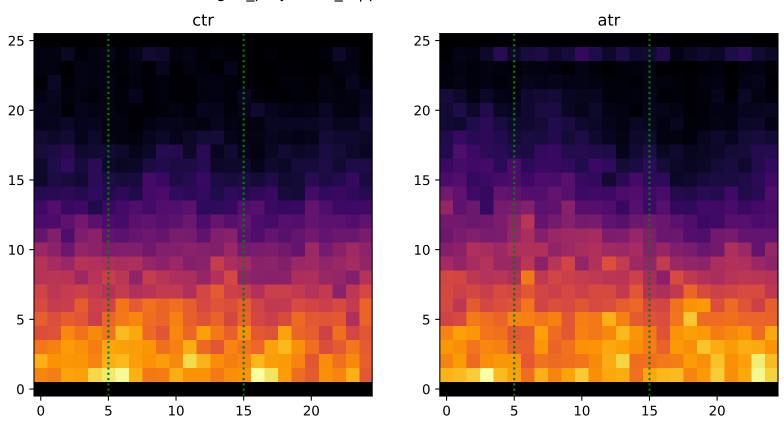
## speed | pval:0.06911447084233262



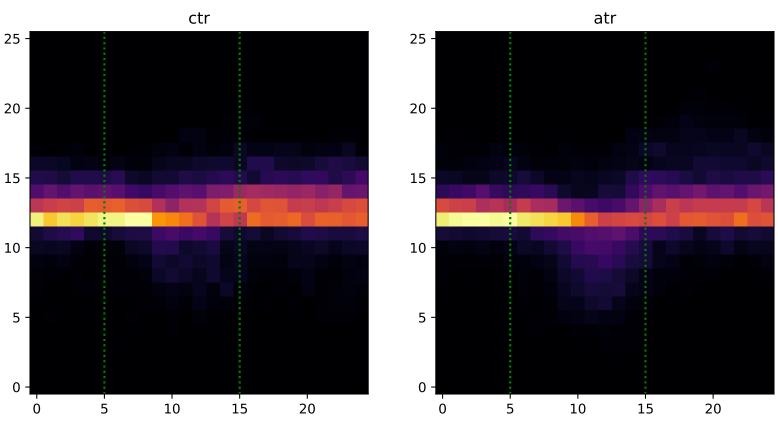
major\_axis | pval:0.0734341252699784



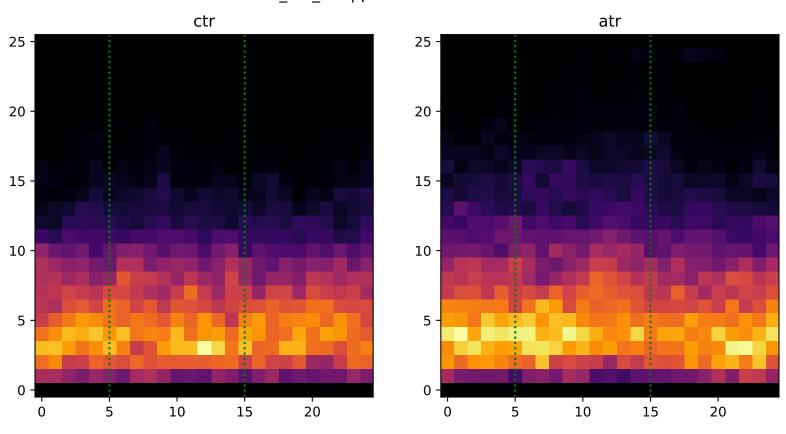
eigen\_projection\_7 | pval:0.0755939524838013



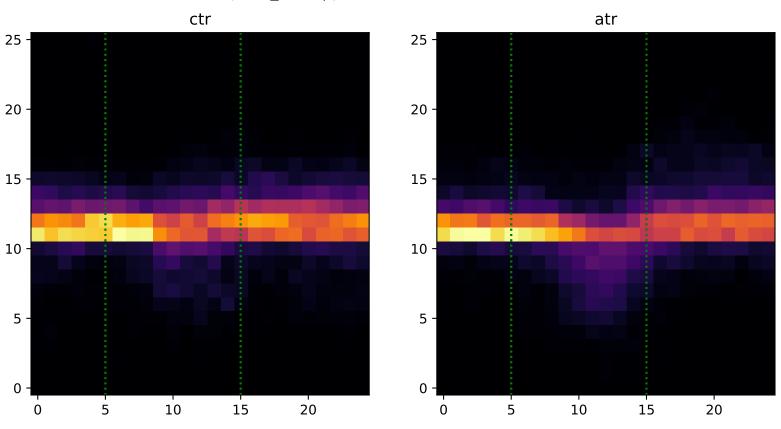
speed\_hips | pval:0.07775377969762419



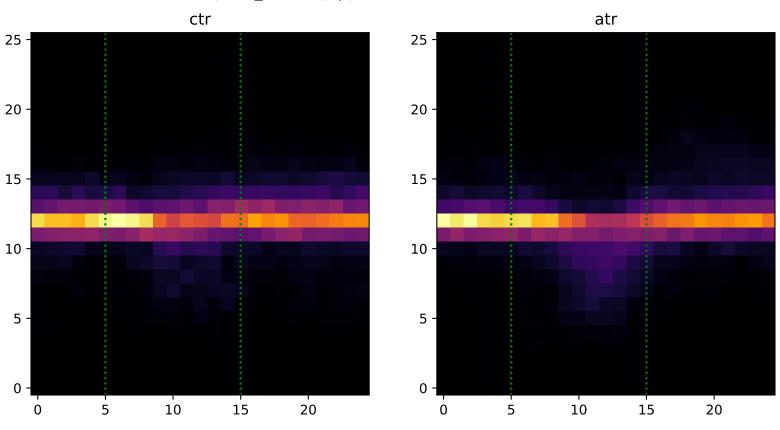
## curvature\_std\_tail | pval:0.07991360691144708



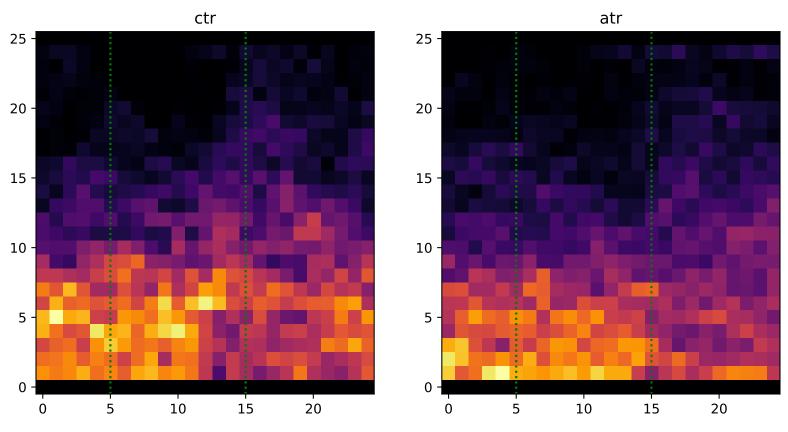
speed\_neck | pval:0.08207343412526998



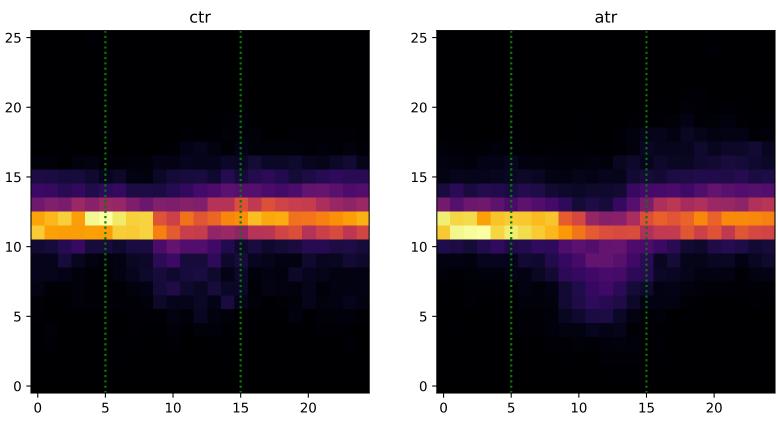
#### speed\_midbody | pval:0.08855291576673865



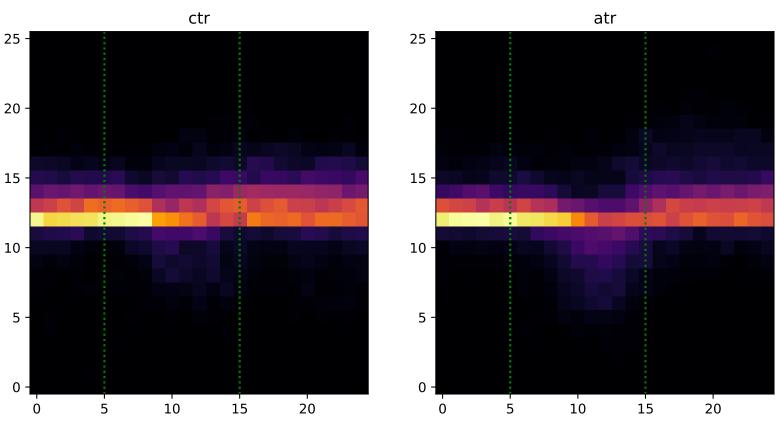
eigen\_projection\_1 | pval:0.09287257019438445



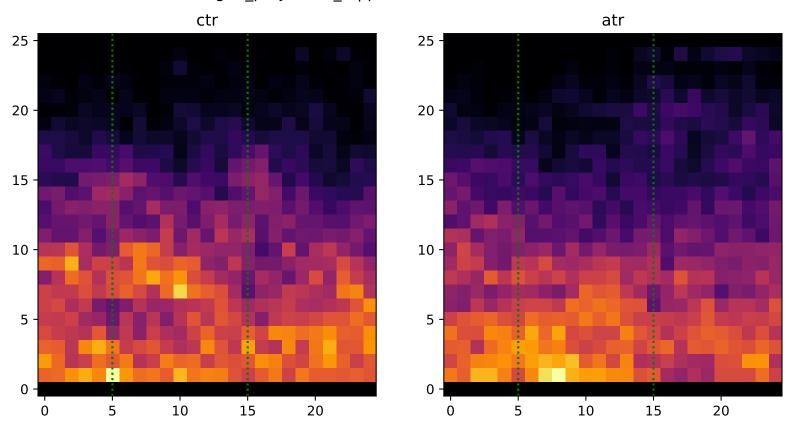
speed\_head\_base | pval:0.09503239740820735



speed\_tail\_base | pval:0.09935205183585313



eigen\_projection\_4 | pval:0.10151187904967603



d\_curvature\_std\_hips | pval:0.10583153347732181 ctr atr 25 -25 -20 -20 -15 -15 -10 -10 -5 -5 -0 -0 -20

10

5

0

15

10

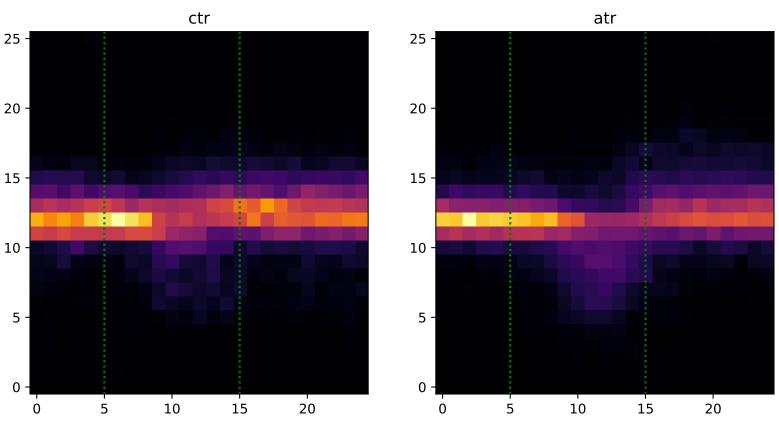
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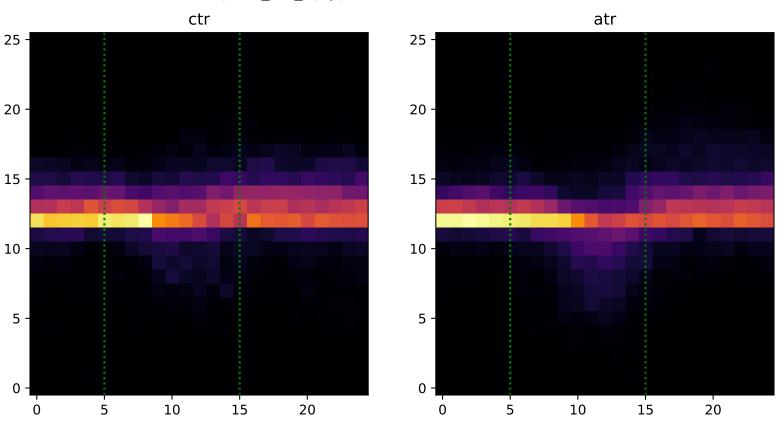
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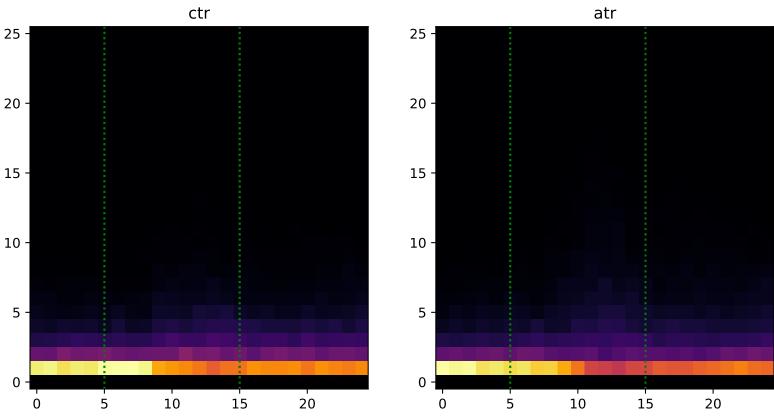
speed\_head\_tip | pval:0.11663066954643629



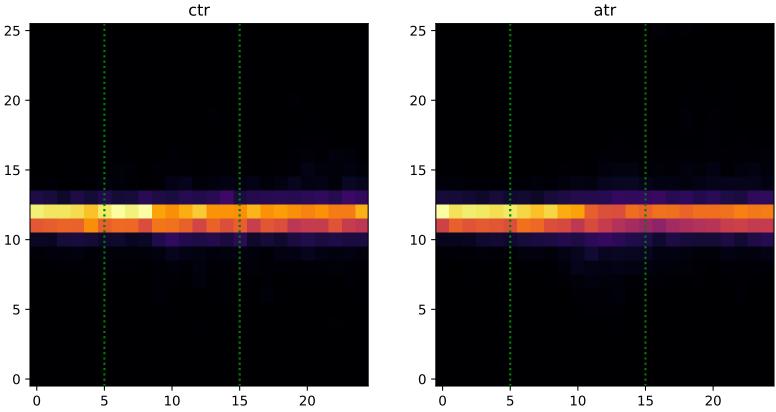
speed\_tail\_tip | pval:0.11879049676025918



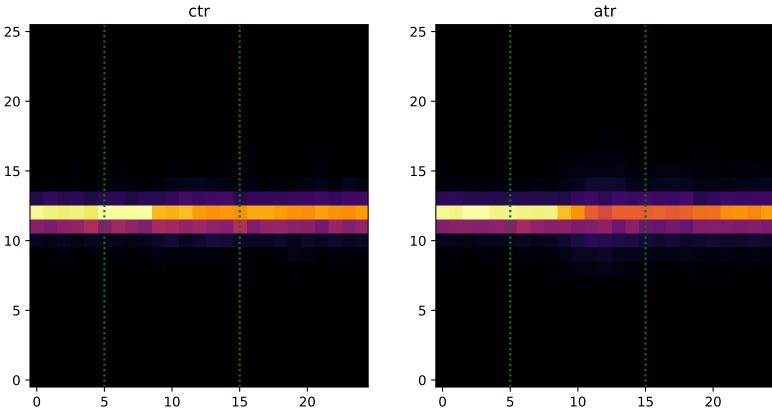
d\_curvature\_mean\_tail | pval:0.12095032397408208



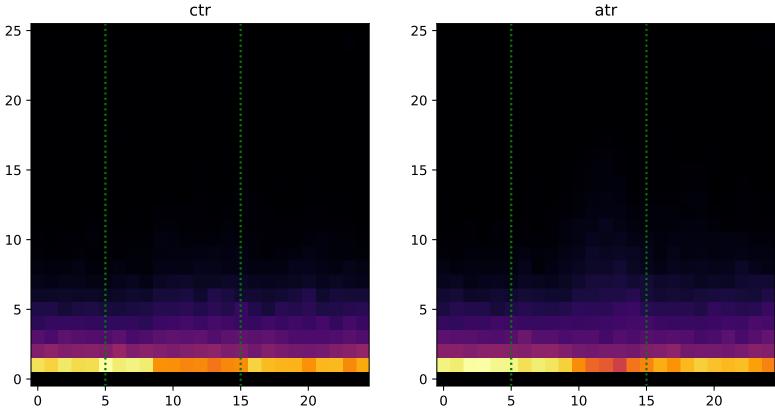
relative\_to\_body\_radial\_velocity\_tail\_tip | pval:0.12311015118790497



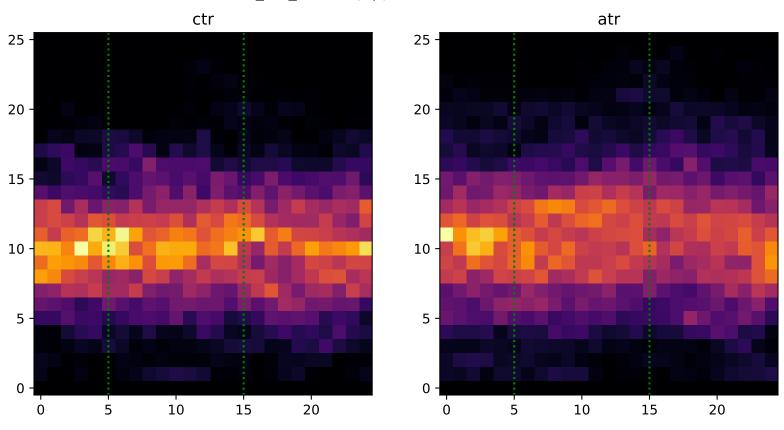
relative\_to\_hips\_radial\_velocity\_tail\_tip | pval:0.12526997840172785



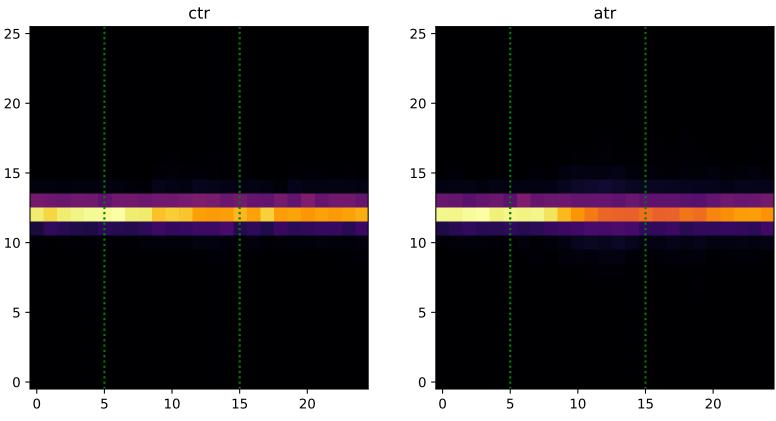
angular\_velocity\_tail\_tip | pval:0.13390928725701945



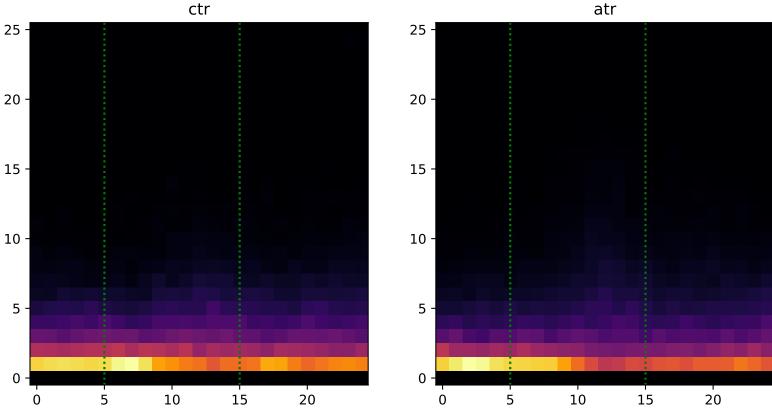
## curvature\_std\_midbody | pval:0.13390928725701945



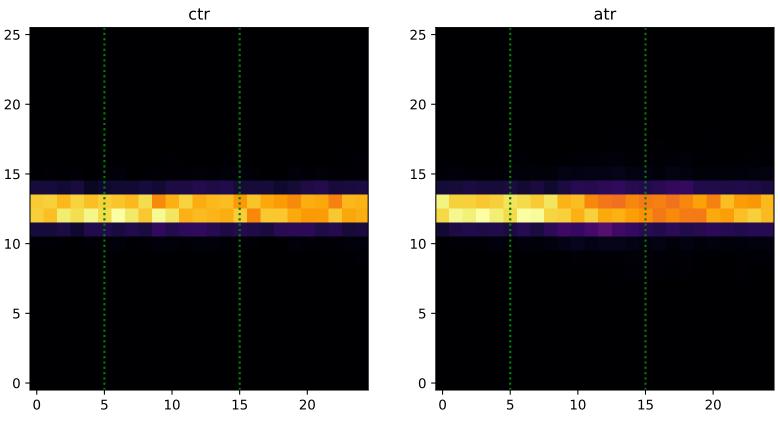
d\_relative\_to\_hips\_radial\_velocity\_tail\_tip | pval:0.13390928725701945



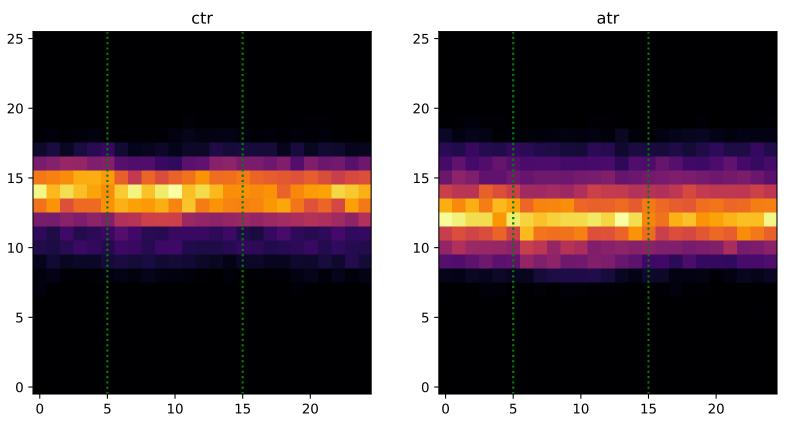
relative\_to\_tail\_base\_angular\_velocity\_tail\_tip | pval:0.13822894168466524



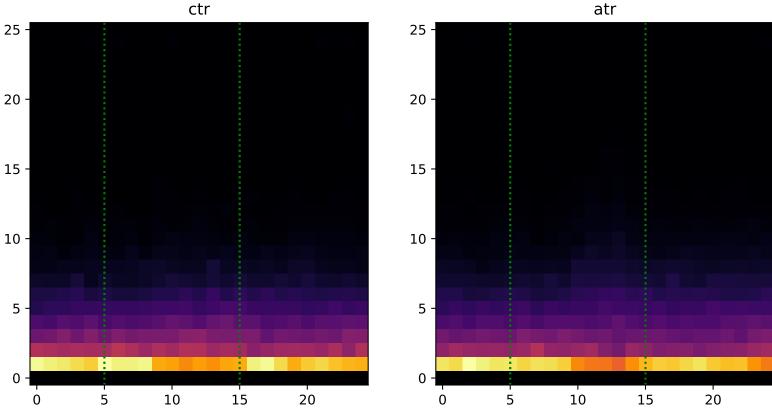
relative\_to\_tail\_base\_radial\_velocity\_tail\_tip | pval:0.14038876889848811



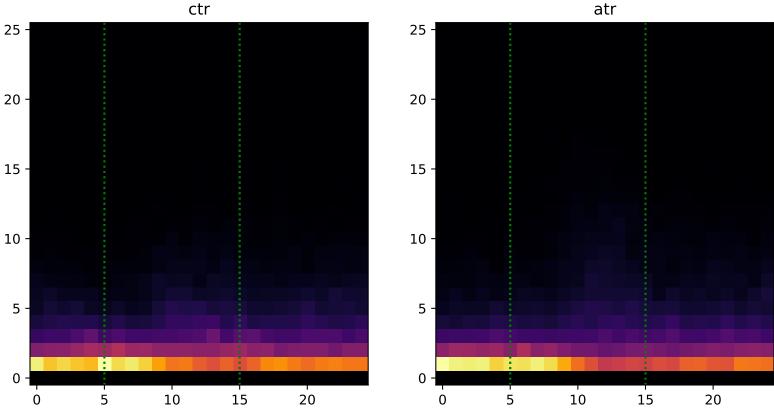
area | pval:0.14254859611231102



d\_angular\_velocity\_tail\_tip | pval:0.1511879049676026

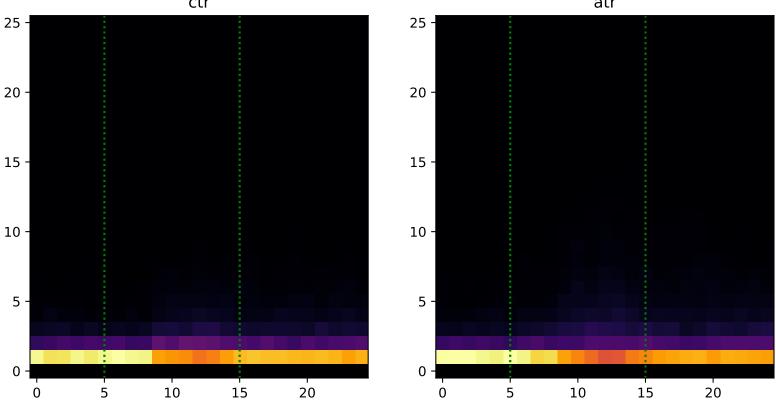


d\_curvature\_midbody | pval:0.15550755939524838

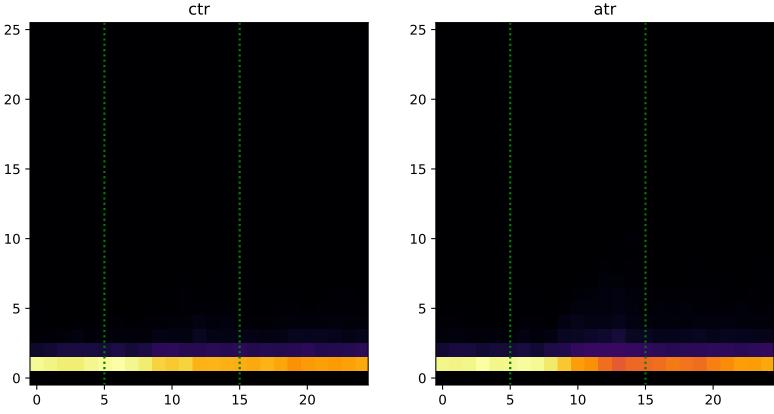


d\_angular\_velocity\_hips | pval:0.16198704103671707

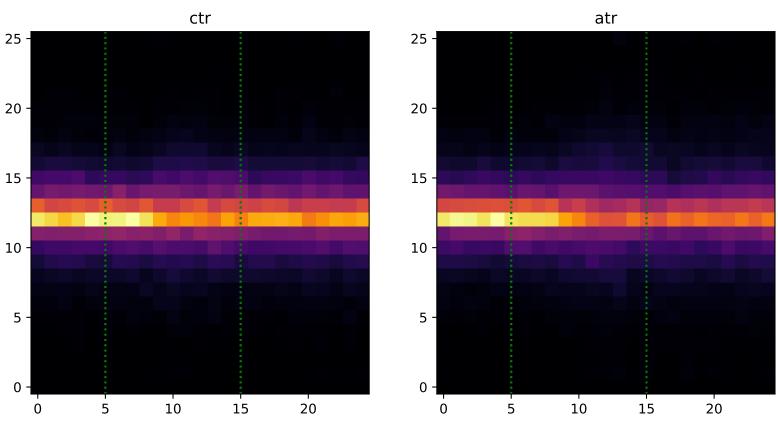
ctr atr



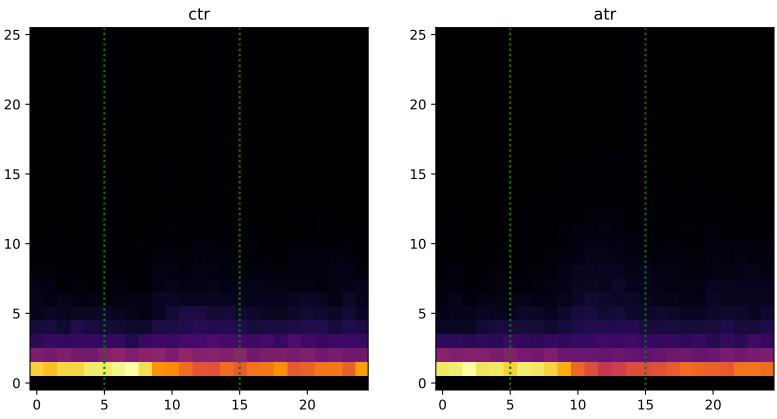
d\_relative\_to\_body\_angular\_velocity\_tail\_tip | pval:0.16846652267818574



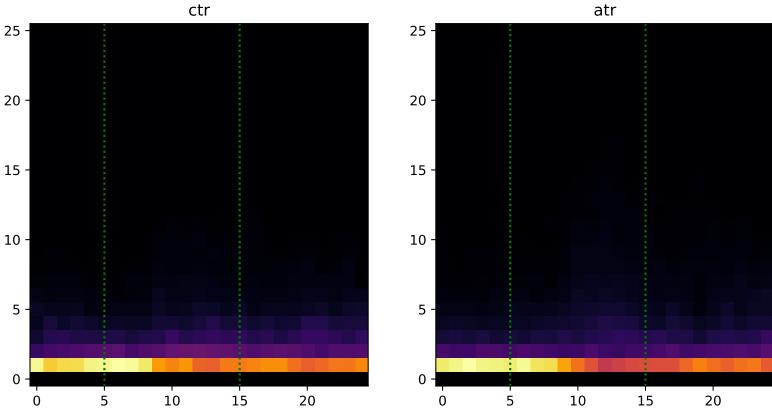
d\_width\_tail\_base | pval:0.17062634989200864



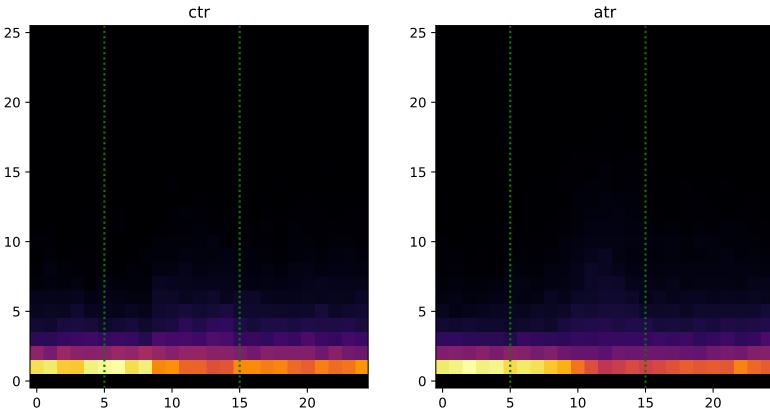
d\_curvature\_hips | pval:0.17494600431965443



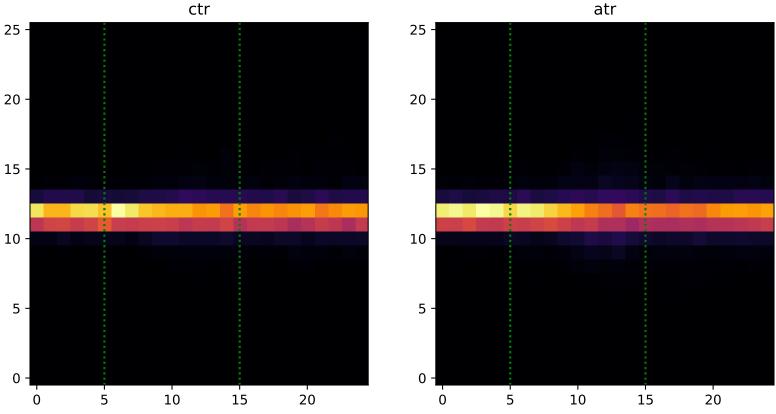
d\_curvature\_mean\_hips | pval:0.17494600431965443



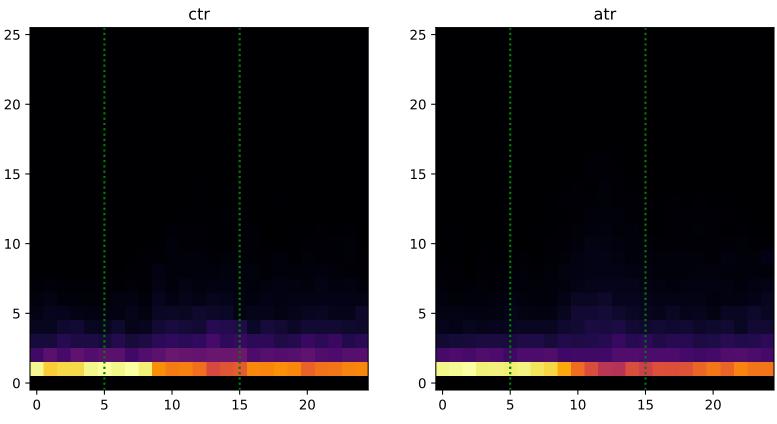
# d\_curvature\_std\_midbody | pval:0.17926565874730022



d\_relative\_to\_body\_radial\_velocity\_hips | pval:0.18142548596112312

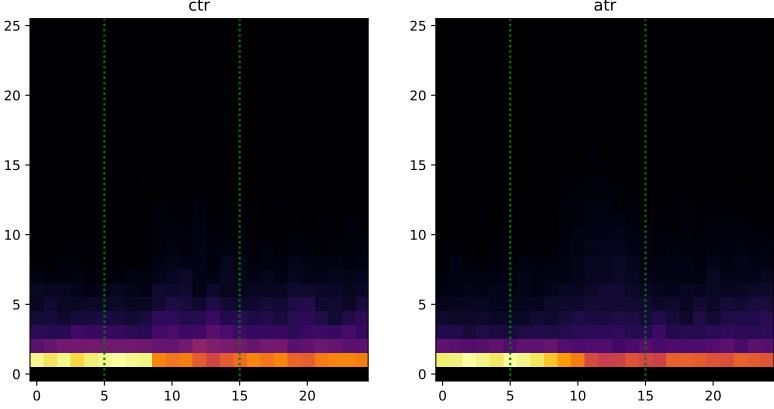


relative\_to\_hips\_angular\_velocity\_tail\_tip | pval:0.19438444924406048

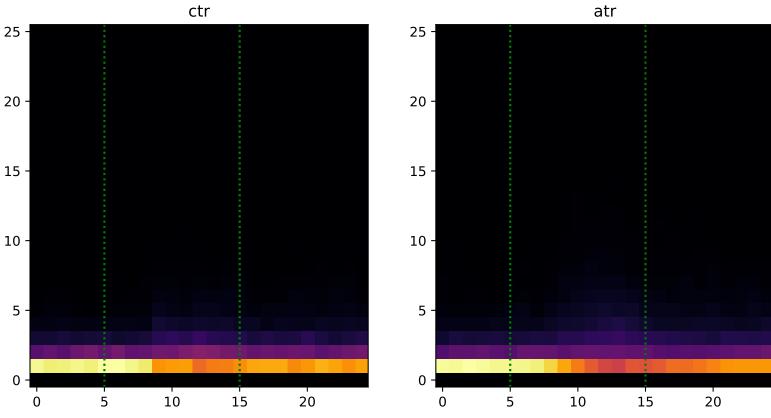


d\_curvature\_mean\_neck | pval:0.19438444924406048

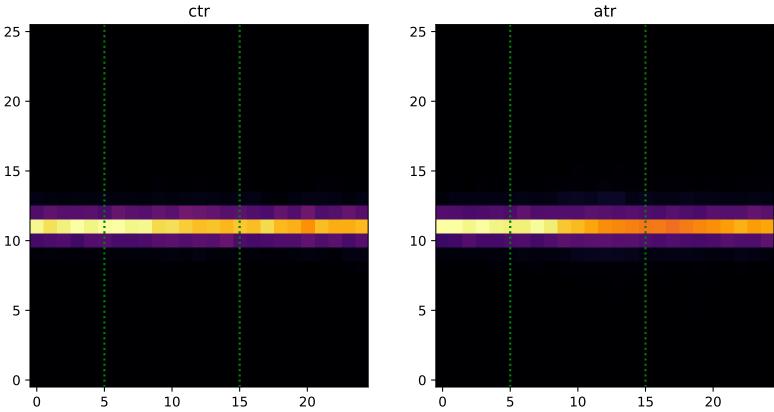
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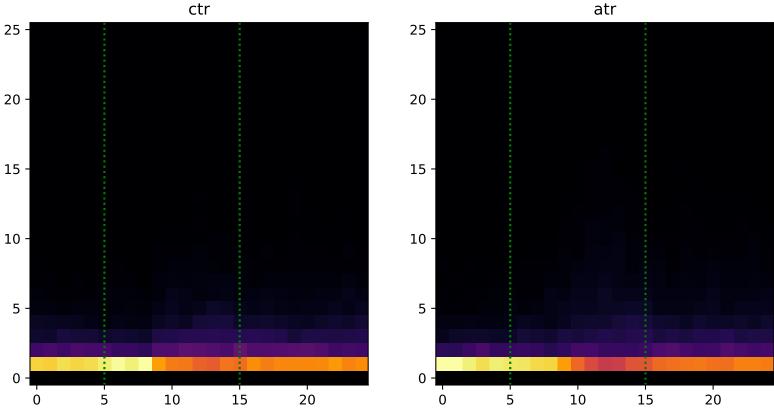
d\_relative\_to\_hips\_angular\_velocity\_tail\_tip | pval:0.19654427645788336



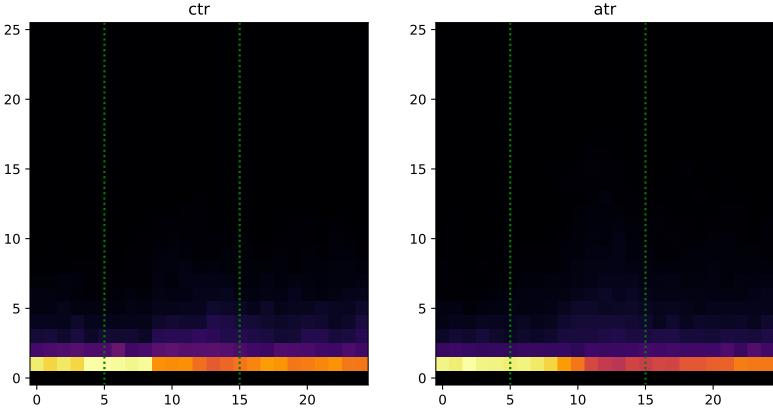
d\_relative\_to\_tail\_base\_radial\_velocity\_tail\_tip | pval:0.19654427645788336



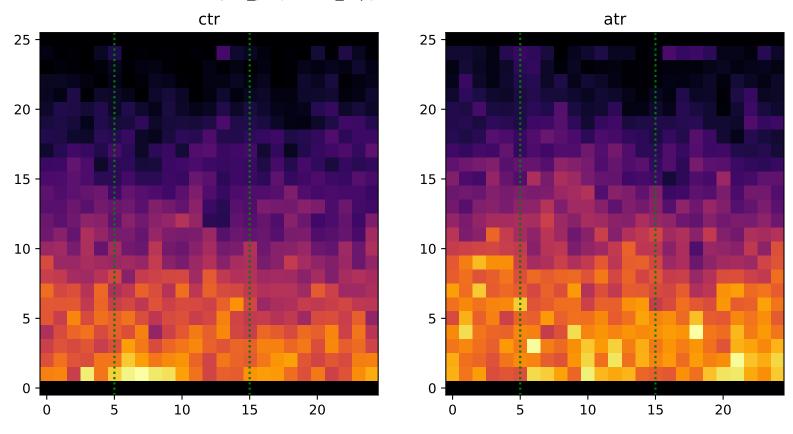
### angular\_velocity\_hips | pval:0.20086393088552915



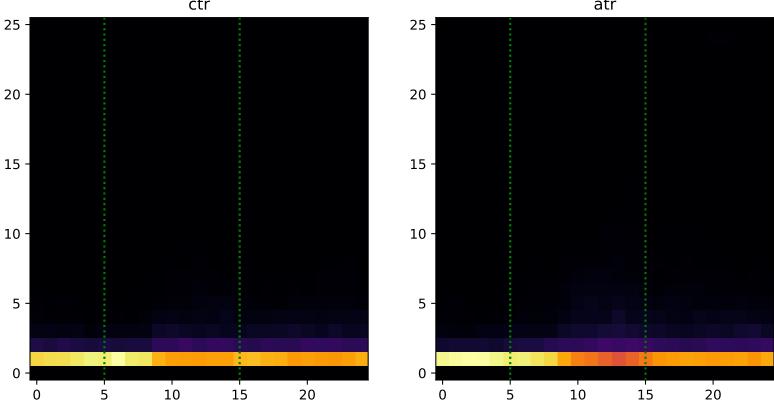
d\_curvature\_mean\_midbody | pval:0.20302375809935205



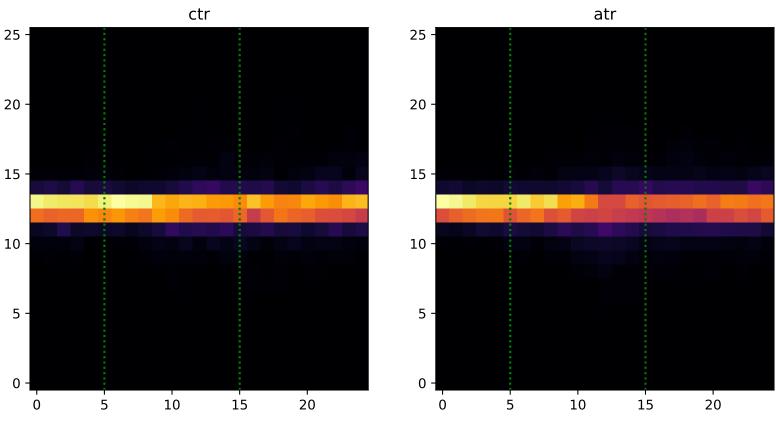
eigen\_projection\_5 | pval:0.21382289416846653



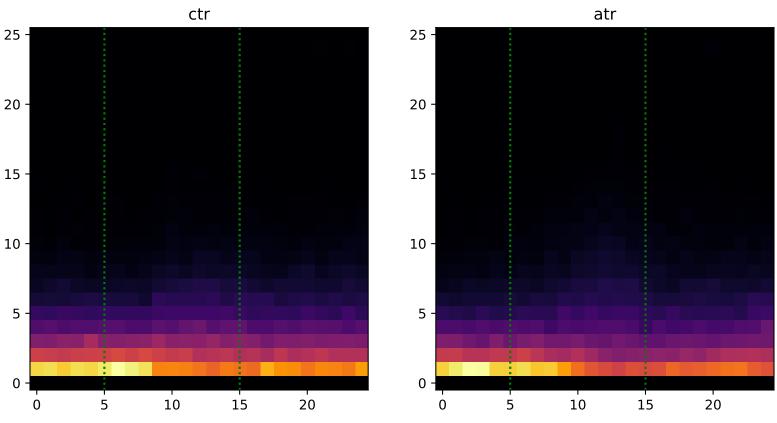
d\_angular\_velocity\_midbody | pval:0.2159827213822894 ctr atr



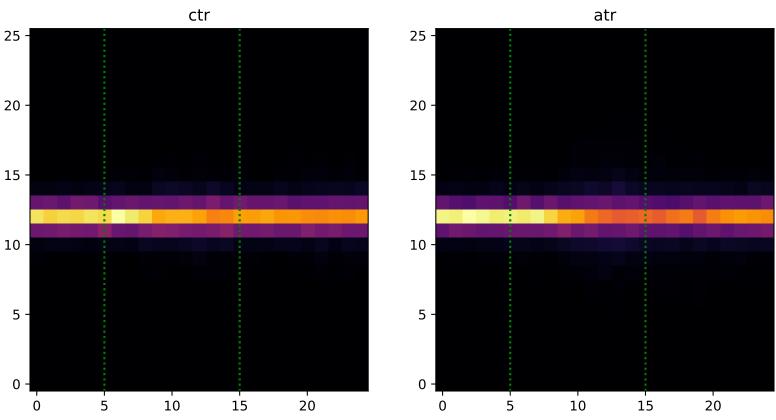
relative\_to\_body\_radial\_velocity\_hips | pval:0.2203023758099352



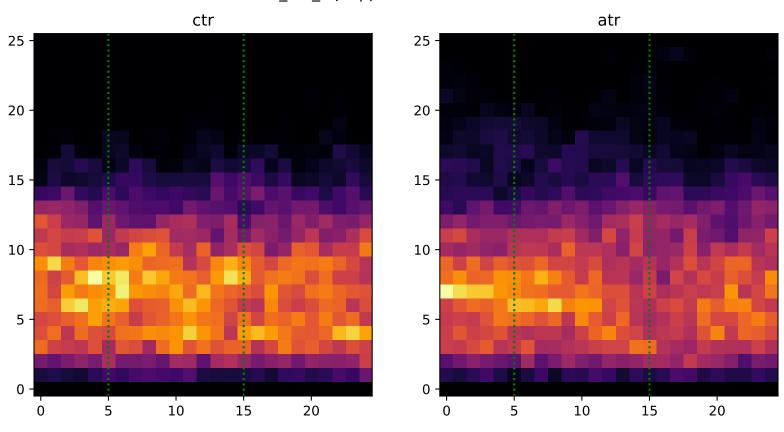
#### d\_relative\_to\_tail\_base\_angular\_velocity\_tail\_tip | pval:0.2203023758099352



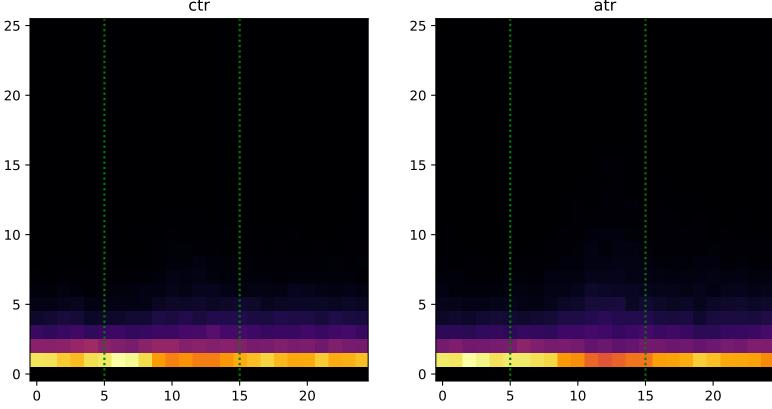
d\_relative\_to\_body\_radial\_velocity\_tail\_tip | pval:0.22462203023758098



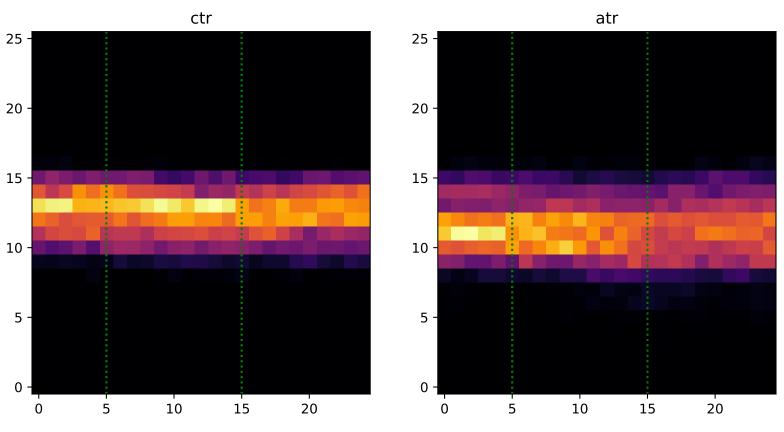
curvature\_std\_hips | pval:0.2267818574514039



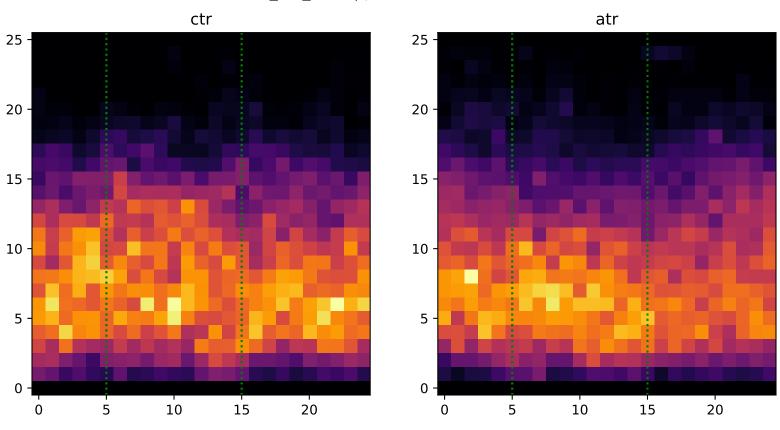
d\_angular\_velocity\_tail\_base | pval:0.23758099352051837 ctr atr



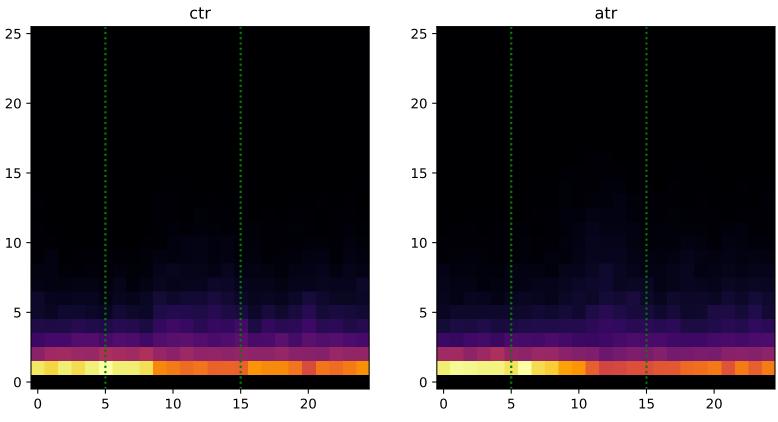
#### length | pval:0.24190064794816415



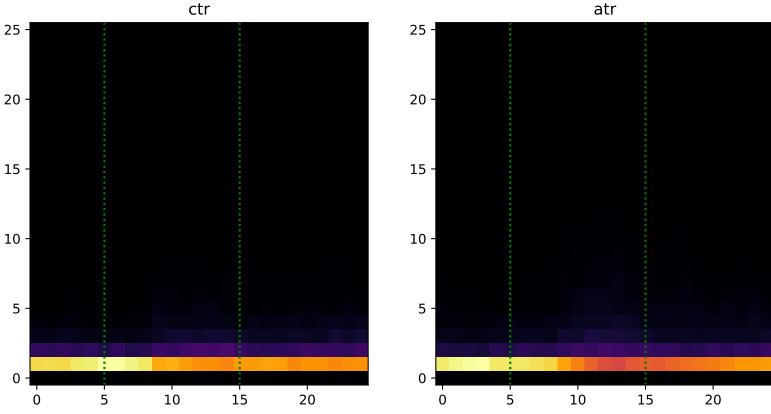
curvature\_std\_neck | pval:0.24190064794816415



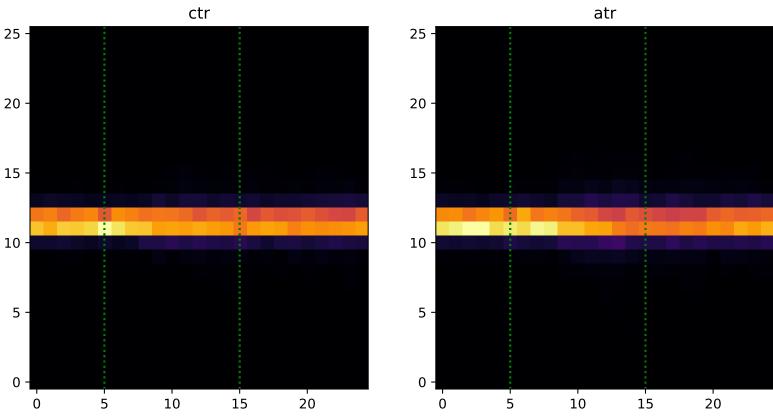
d\_curvature\_neck | pval:0.24622030237580994



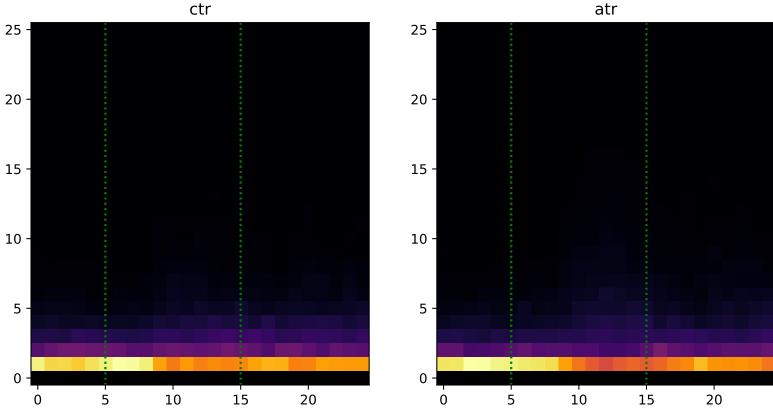
d\_relative\_to\_body\_angular\_velocity\_hips | pval:0.2505399568034557



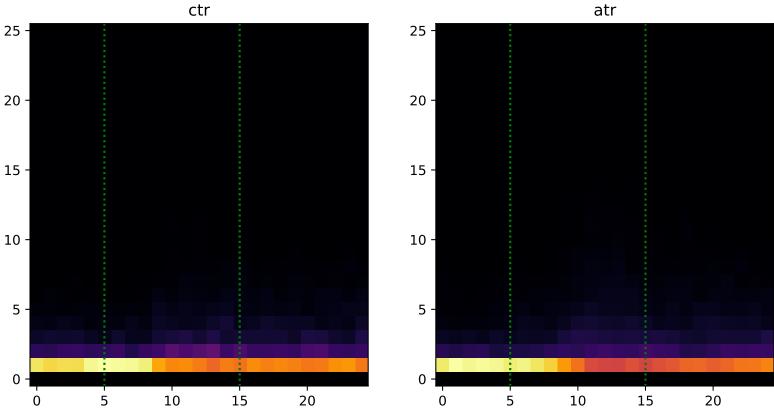
### d\_relative\_to\_body\_radial\_velocity\_neck | pval:0.2526997840172786



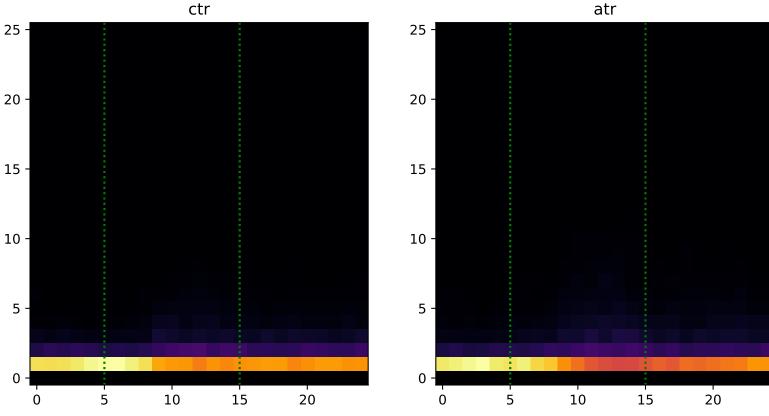
# angular\_velocity\_tail\_base | pval:0.2548596112311015



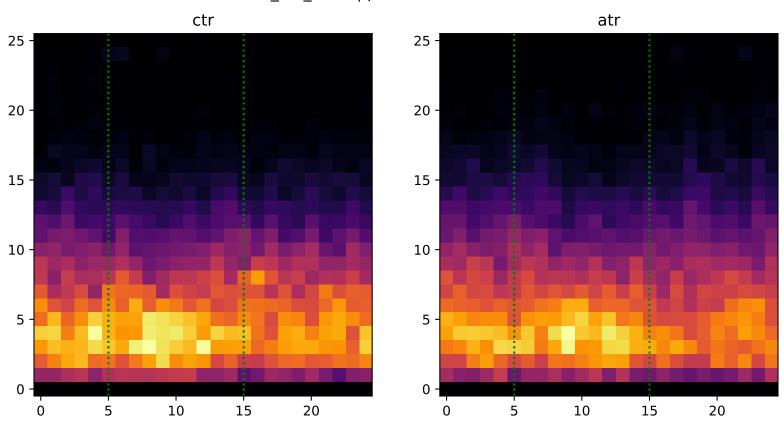
relative\_to\_body\_angular\_velocity\_neck | pval:0.2613390928725702



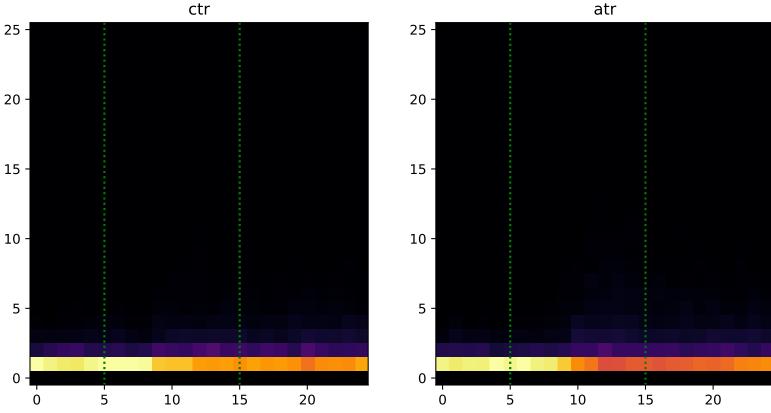
## d\_relative\_to\_body\_angular\_velocity\_neck | pval:0.2634989200863931



curvature\_std\_head | pval:0.28077753779697623



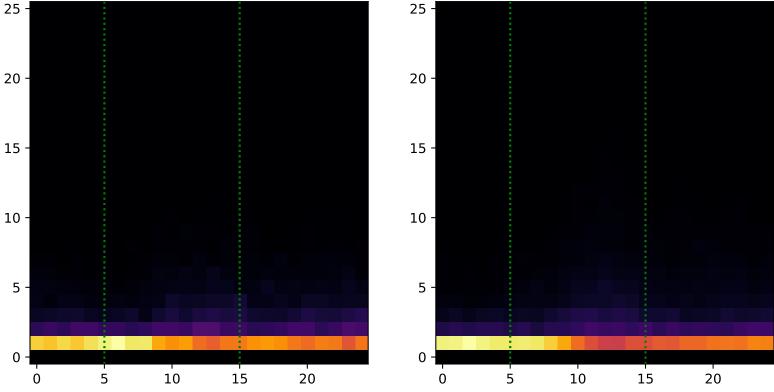
relative\_to\_body\_angular\_velocity\_tail\_tip | pval:0.28293736501079914



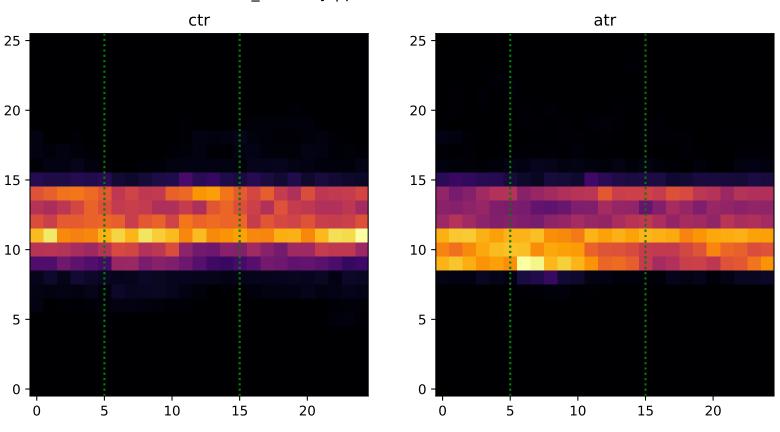
d\_eigen\_projection\_2 | pval:0.28509719222462204 ctr atr 25 -25 -20 -20 -15 -15 -10 -10 -5 -5 -0 -0 -20 10 15 5 10 15 20 0 5 0

d\_eigen\_projection\_3 | pval:0.30885529157667385 ctr atr 25 -25 -20 -20 -15 -15 -10 -10 -5 -5 -0 -0 -20 10 15 10 20 5 5 15 0 0

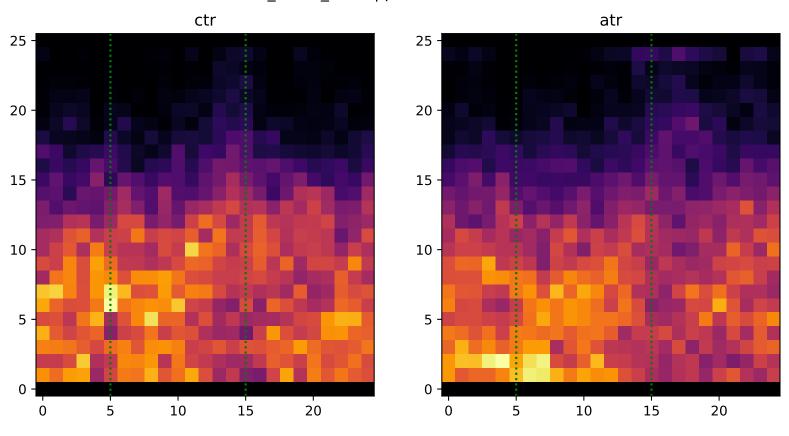
relative\_to\_body\_angular\_velocity\_hips | pval:0.32181425485961124 ctr atr 25 -20 -15 -



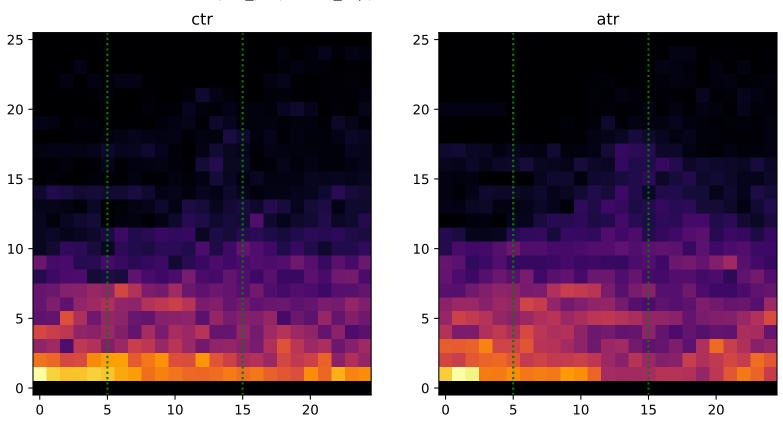
width\_midbody | pval:0.32397408207343414



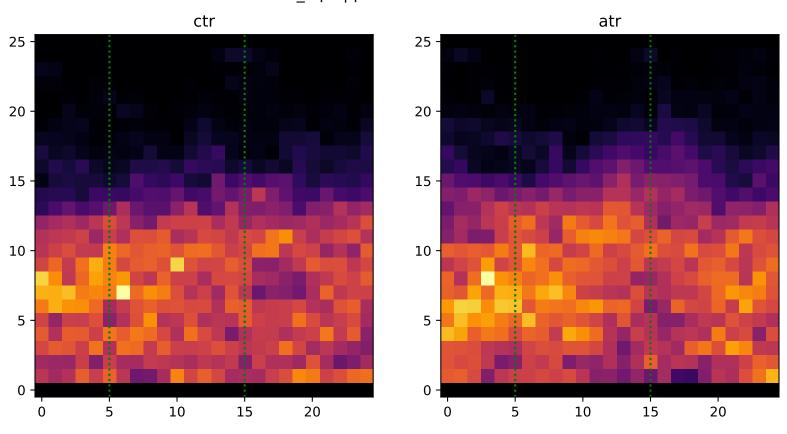
### curvature\_mean\_head | pval:0.3326133909287257



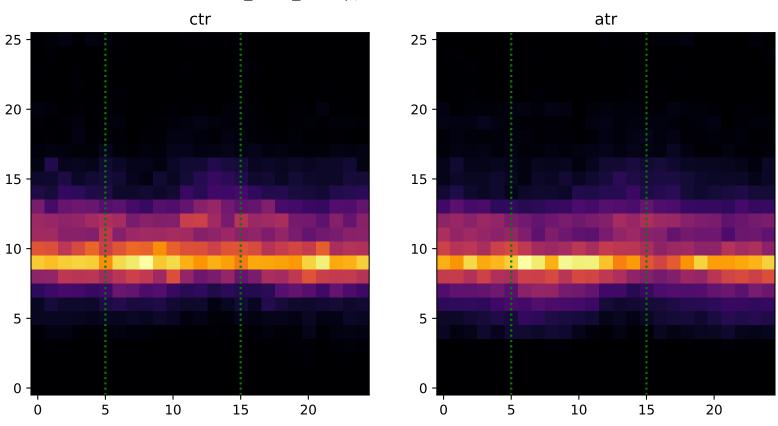
eigen\_projection\_2 | pval:0.3347732181425486



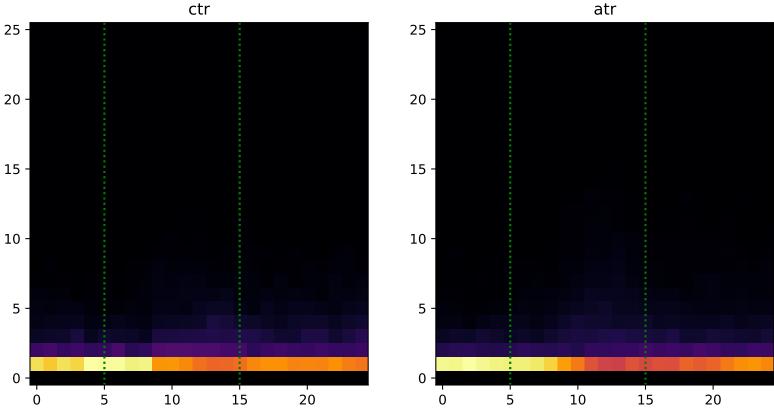
#### curvature\_hips | pval:0.3347732181425486



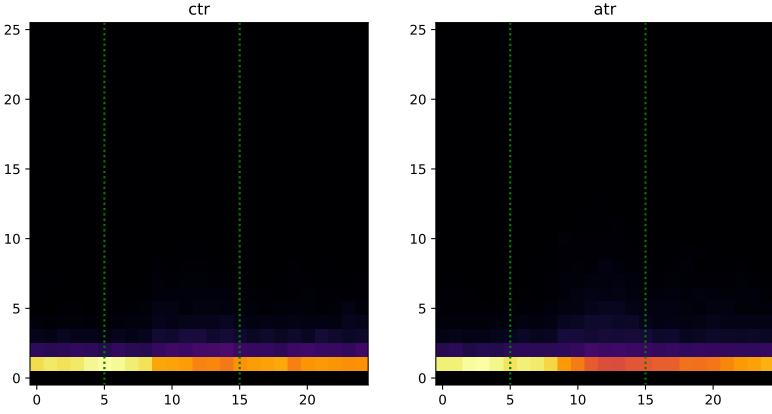
width\_head\_base | pval:0.35205183585313177



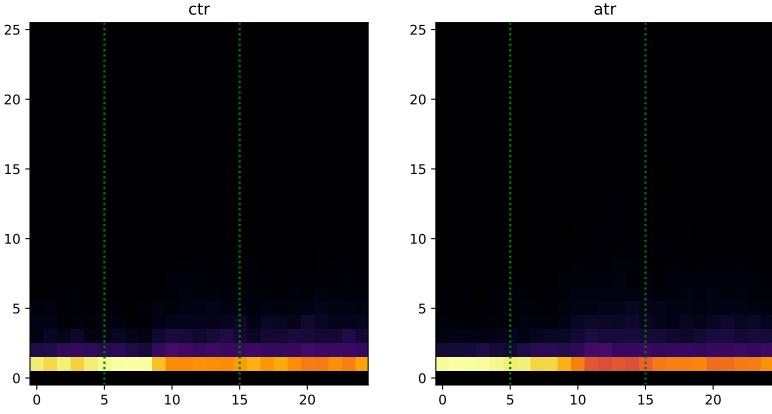
relative\_to\_body\_speed\_midbody | pval:0.35853131749460043

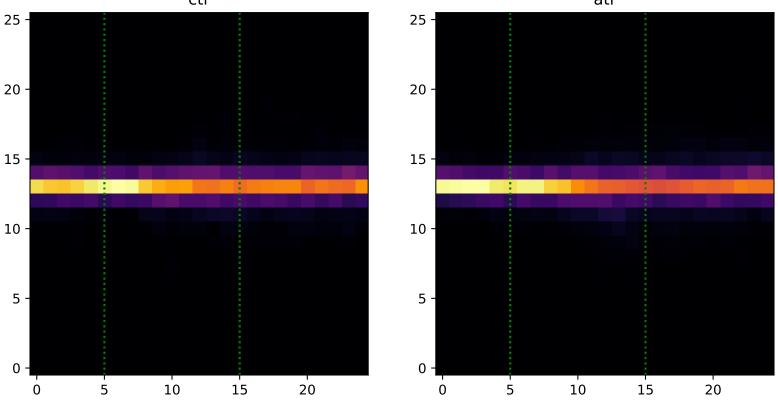


d\_relative\_to\_body\_speed\_midbody | pval:0.36069114470842334

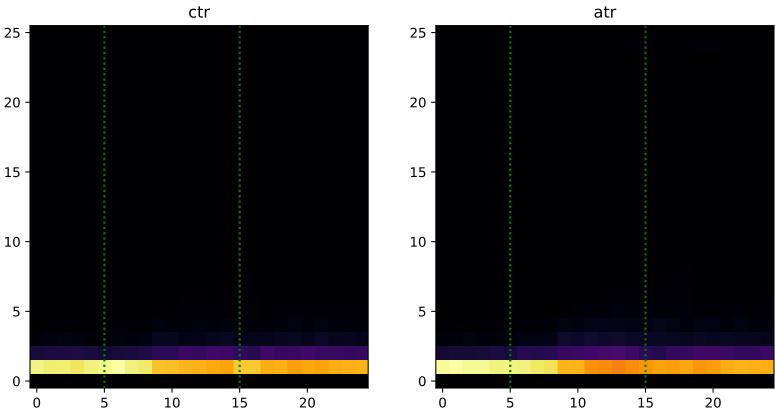


## angular\_velocity\_midbody | pval:0.36285097192224625

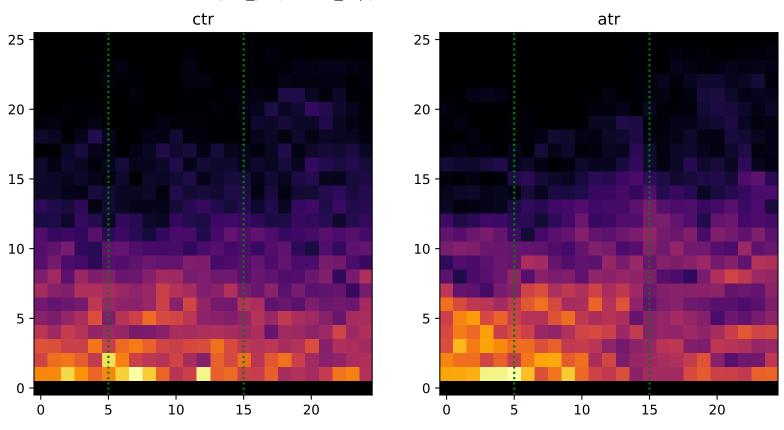




d\_angular\_velocity | pval:0.3758099352051836

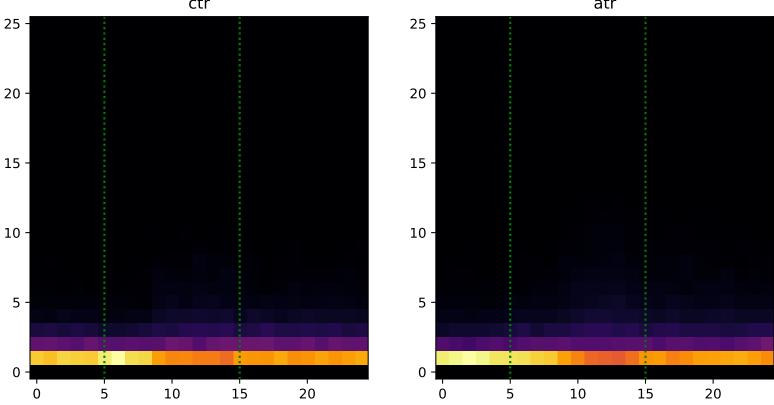


eigen\_projection\_3 | pval:0.3930885529157667

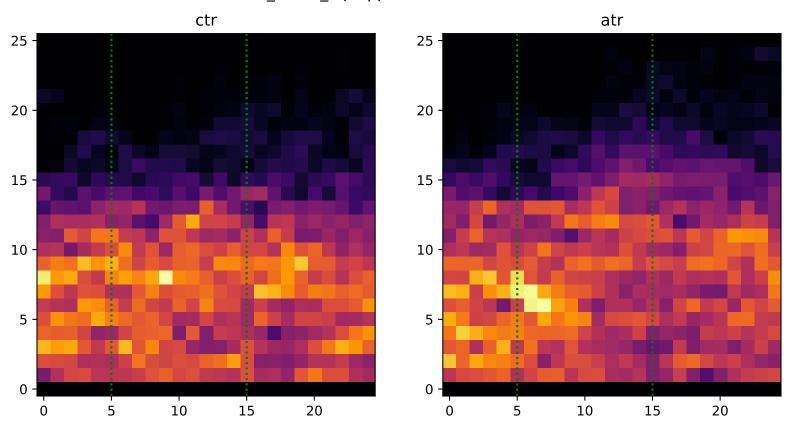


d\_eigen\_projection\_5 | pval:0.3952483801295896 ctr atr 25 -25 -20 -20 -15 -15 -10 -10 -5 -5 -0 -0 -20 10 10 20 5 15 5 15 0 0

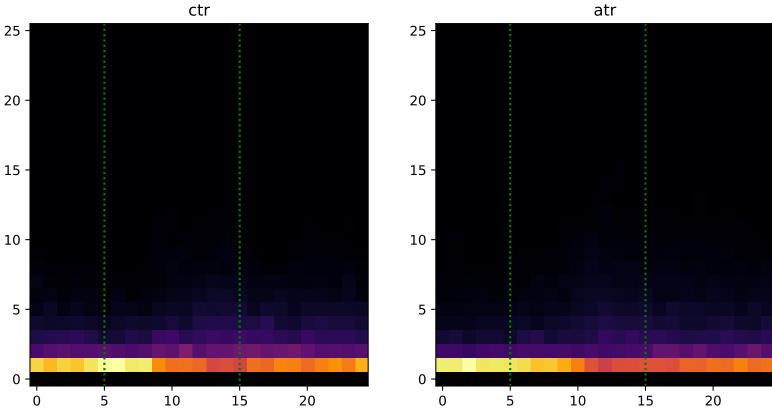
d\_angular\_velocity\_neck | pval:0.4060475161987041 ctr atr



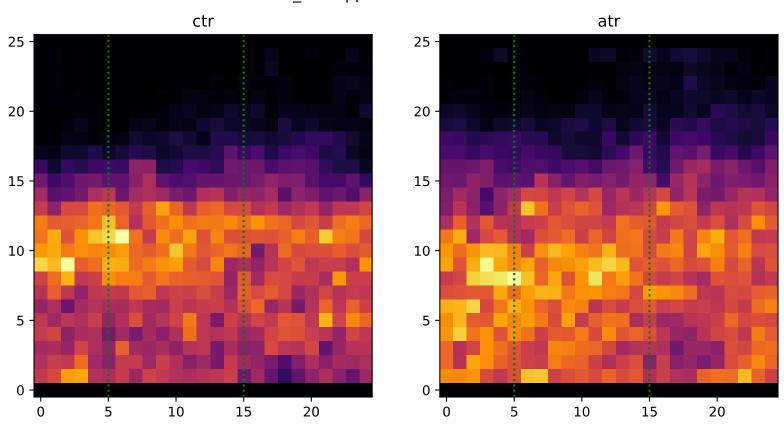
# curvature\_mean\_hips | pval:0.41252699784017277



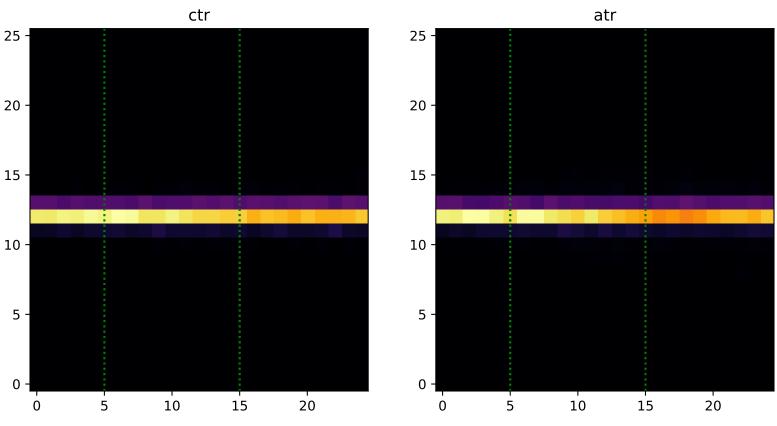
angular\_velocity\_neck | pval:0.4535637149028078



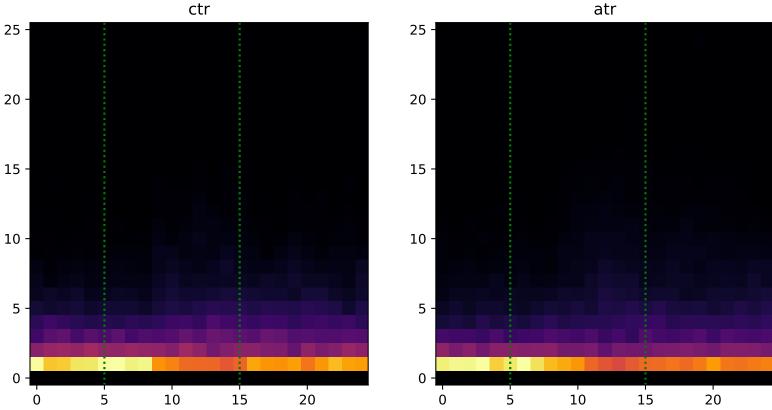
# curvature\_neck | pval:0.4557235421166307



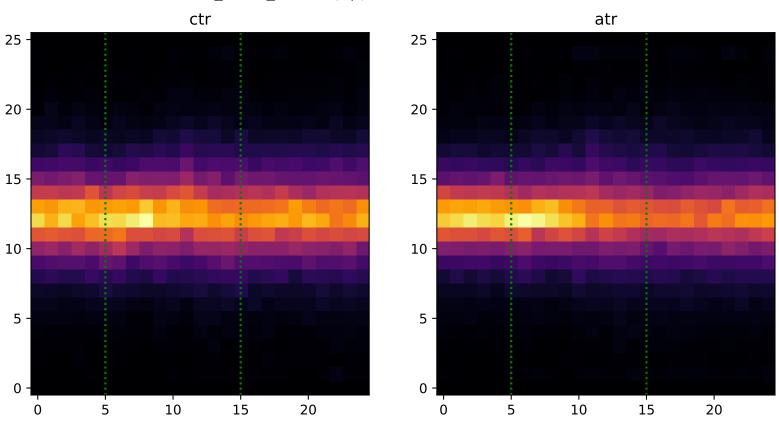
d\_length | pval:0.4838012958963283



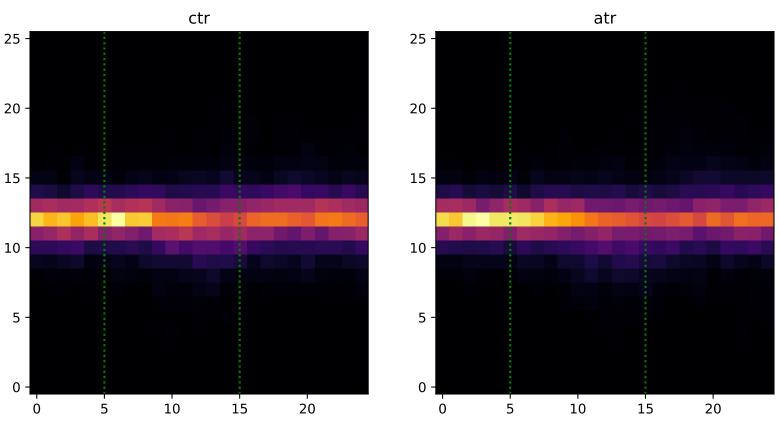
angular\_velocity\_head\_base | pval:0.4924406047516199



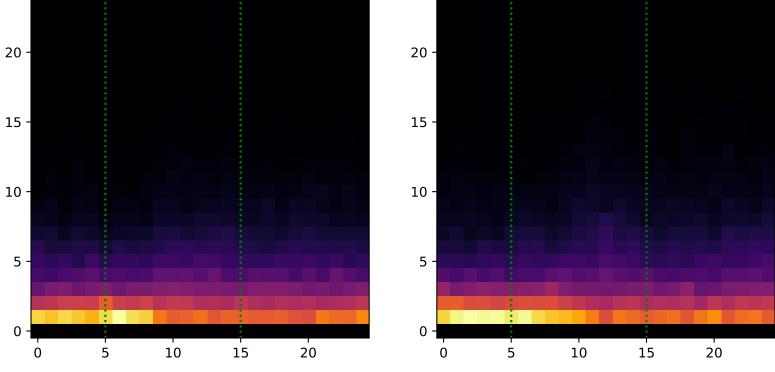
d\_width\_midbody | pval:0.5010799136069114



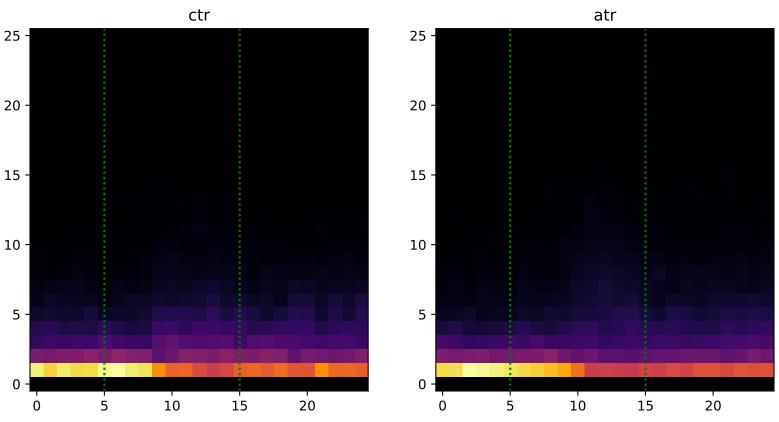
d\_major\_axis | pval:0.5032397408207343



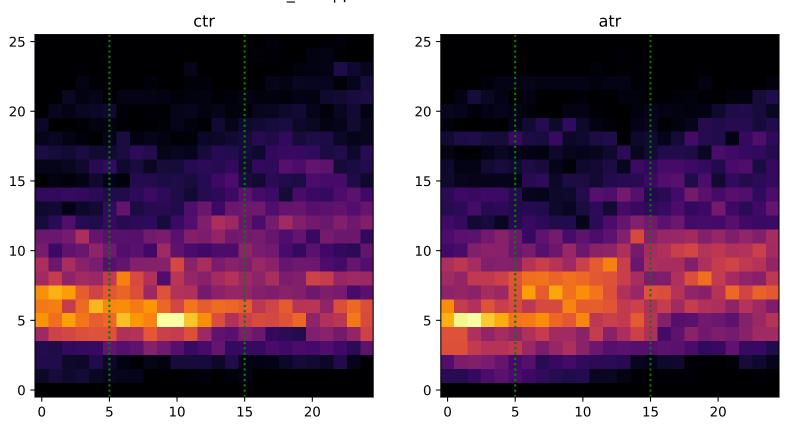
d\_curvature\_std\_neck | pval:0.5032397408207343 ctr atr 25 -25 -20 -15 -10 -



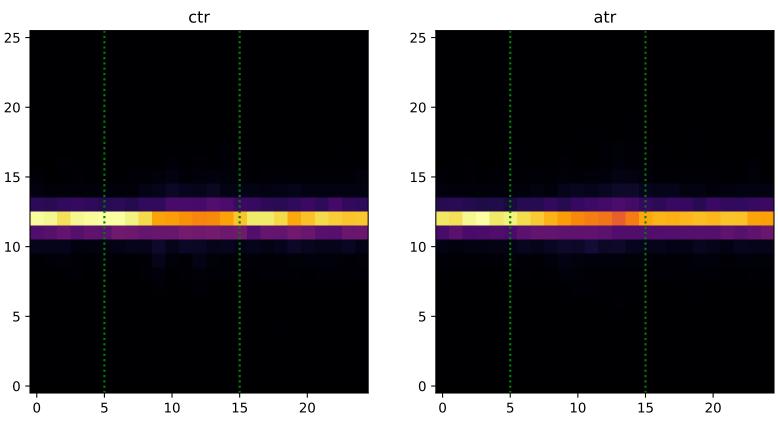
relative\_to\_neck\_angular\_velocity\_head\_tip | pval:0.5075593952483801



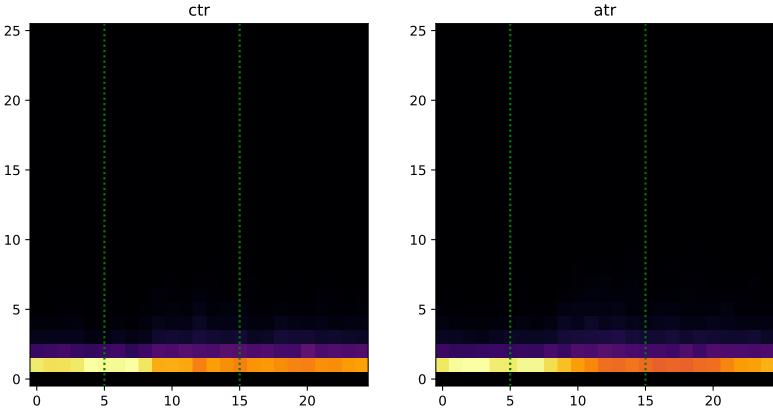
# minor\_axis | pval:0.509719222462203



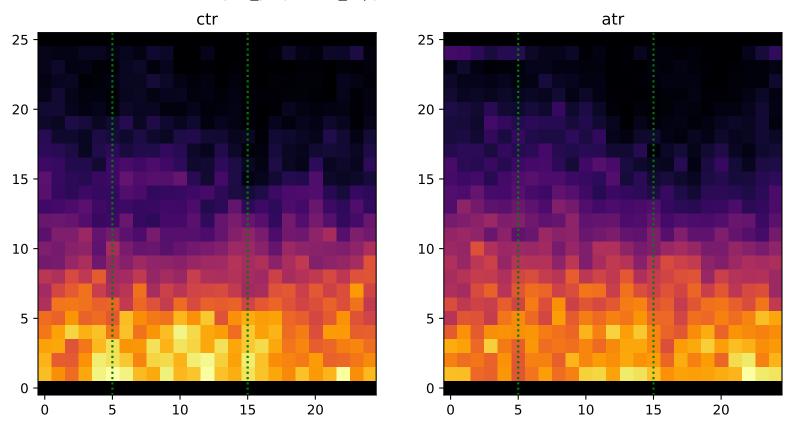
d\_speed\_hips | pval:0.509719222462203



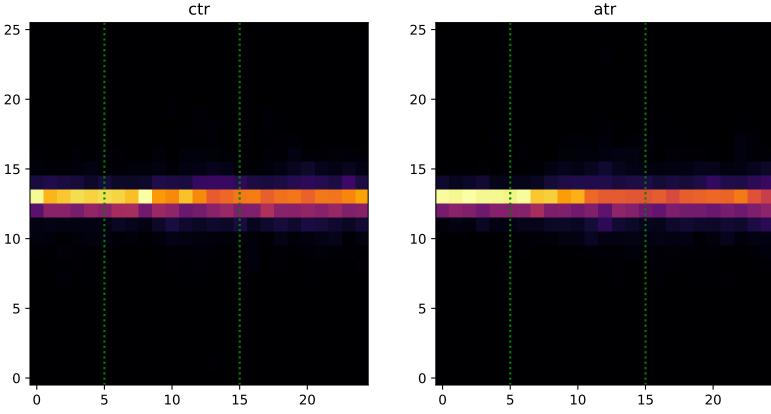
d\_relative\_to\_body\_angular\_velocity\_head\_tip | pval:0.5226781857451404



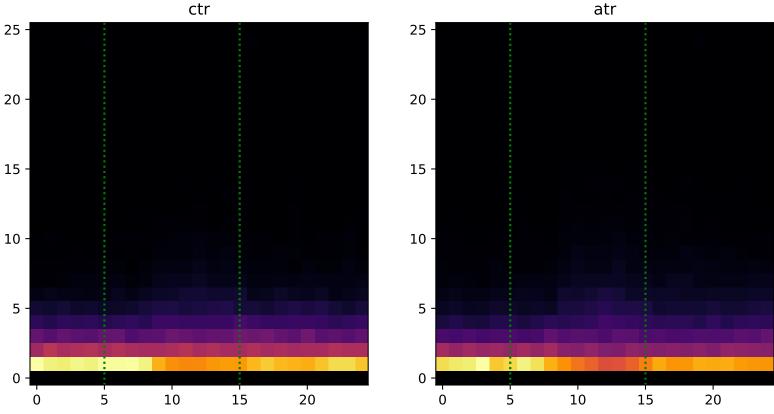
eigen\_projection\_6 | pval:0.5485961123110151



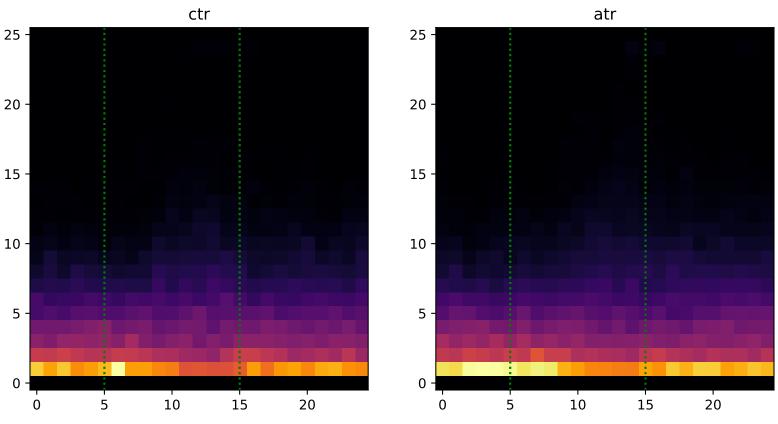
d\_orientation\_food\_edge | pval:0.550755939524838



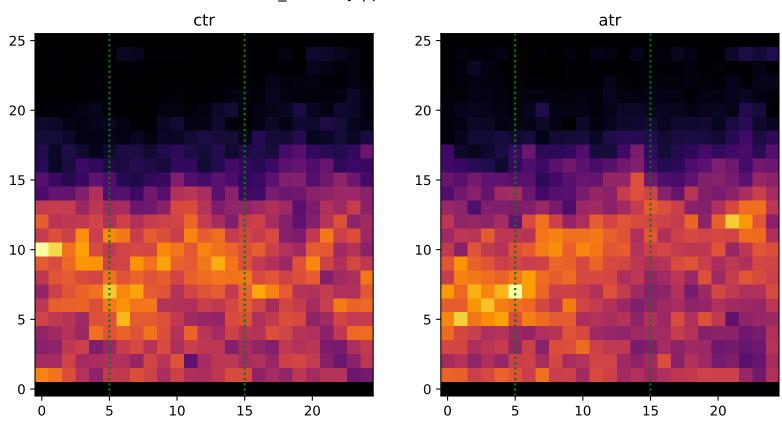
d\_angular\_velocity\_head\_base | pval:0.5529157667386609



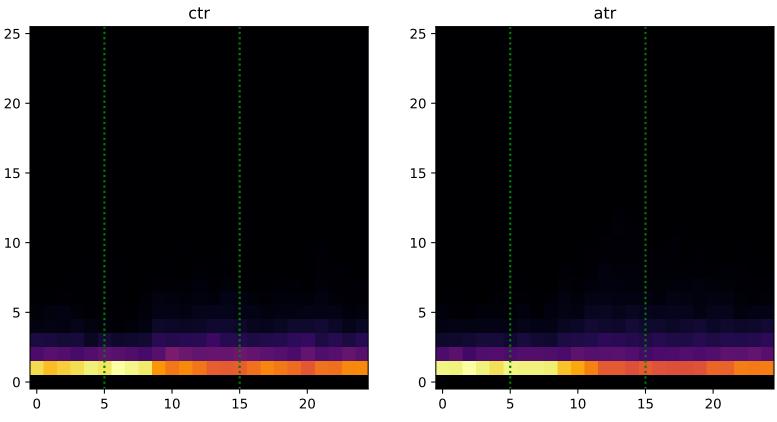
angular\_velocity\_head\_tip | pval:0.5550755939524838



curvature\_midbody | pval:0.5615550755939525



relative\_to\_body\_angular\_velocity\_head\_tip | pval:0.5637149028077754



d\_dist\_from\_food\_edge | pval:0.5637149028077754 ctr atr 25 -25 -20 -20 -15 -15 -10 -10 5 -5 -0 -0 -

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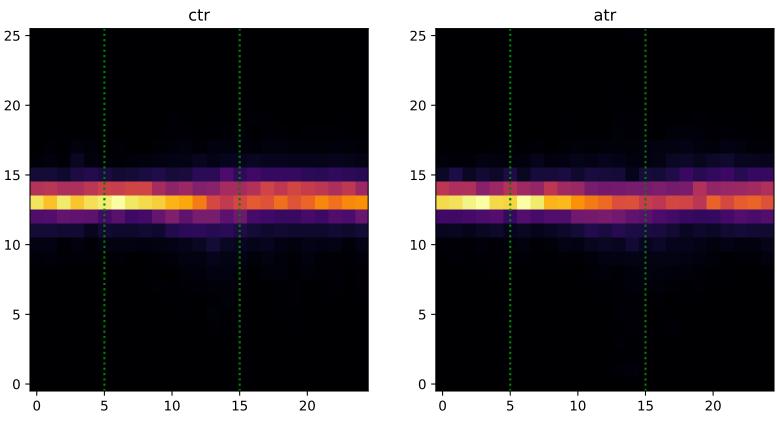
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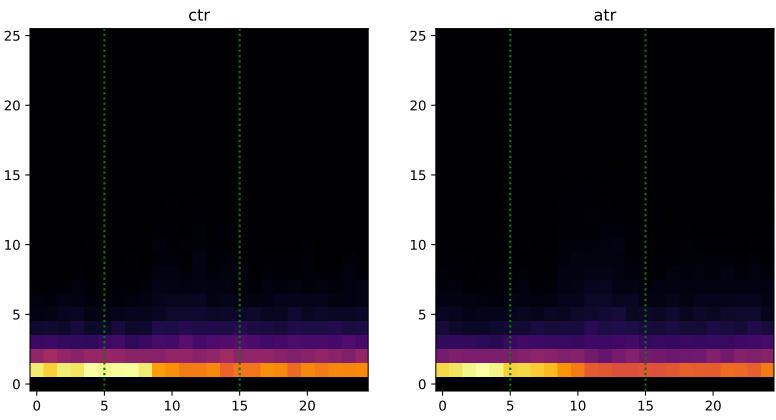
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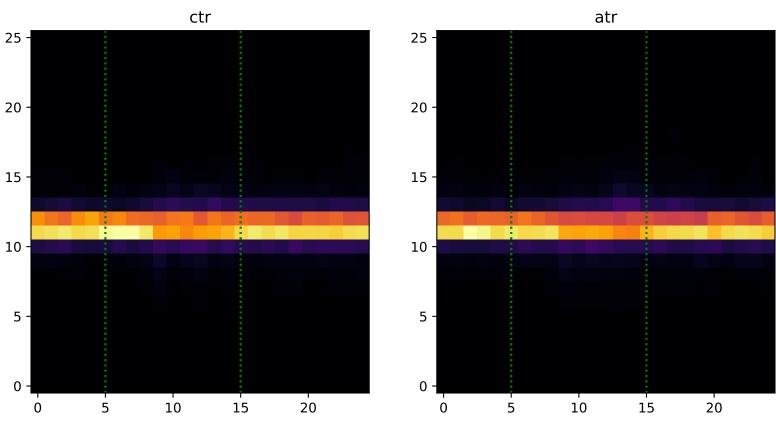
relative\_to\_body\_radial\_velocity\_head\_tip | pval:0.5658747300215983

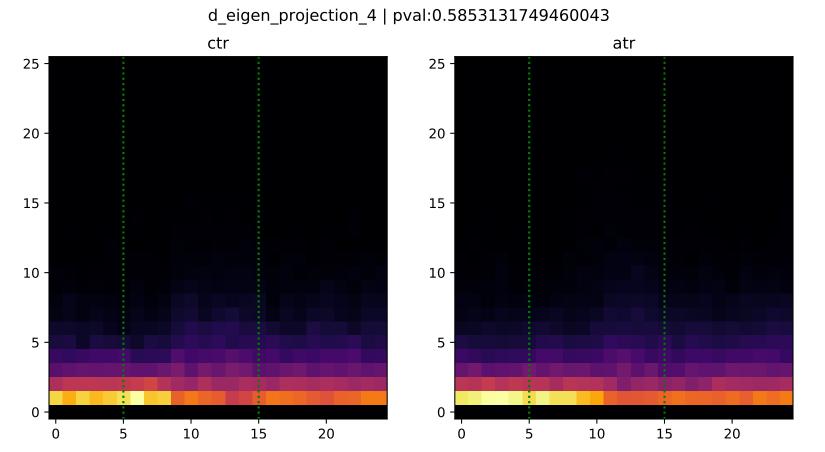


d\_relative\_to\_neck\_angular\_velocity\_head\_tip | pval:0.5745140388768899

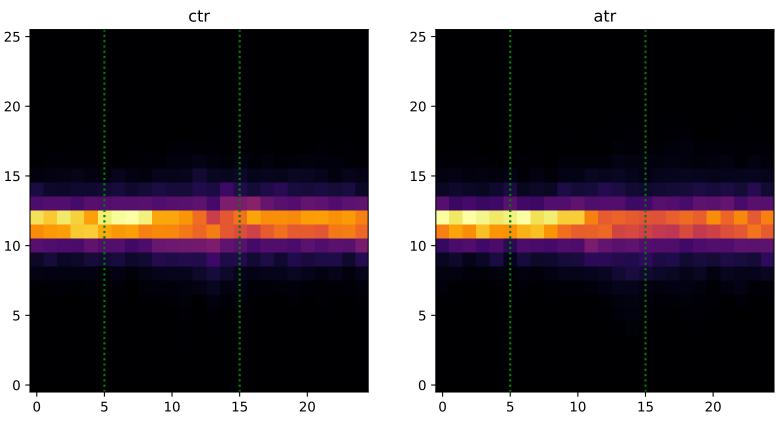


d\_speed\_neck | pval:0.5809935205183585

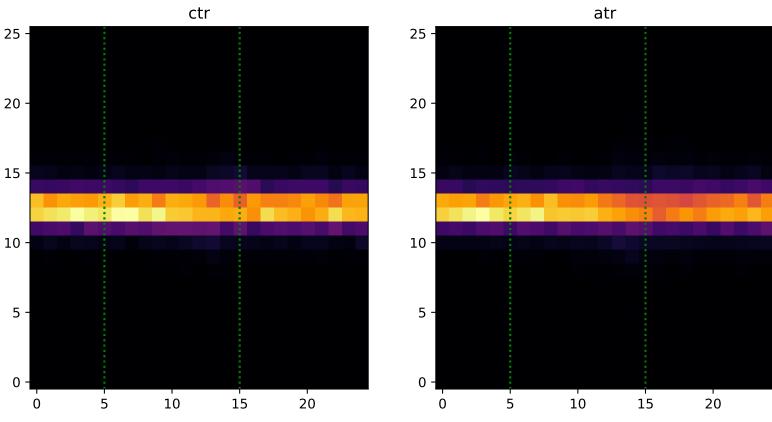




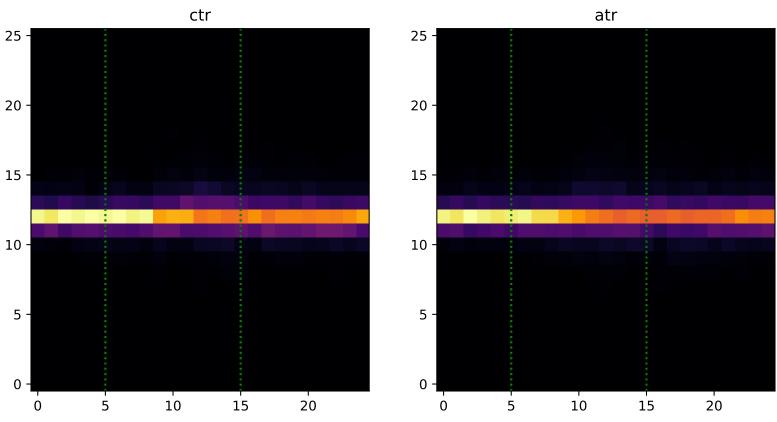
relative\_to\_neck\_radial\_velocity\_head\_tip | pval:0.593952483801296



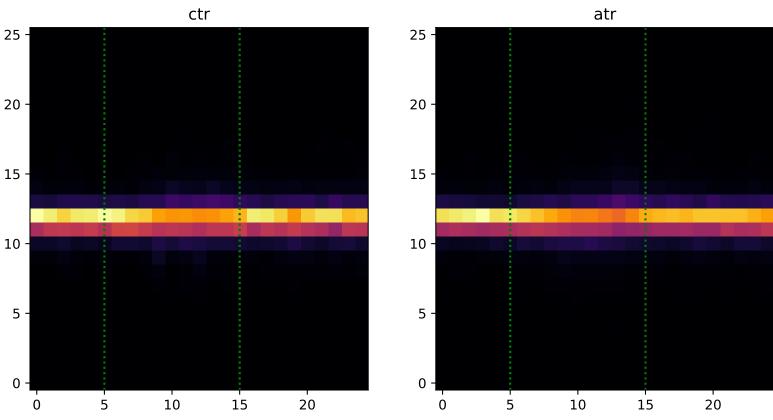
relative\_to\_head\_base\_radial\_velocity\_head\_tip | pval:0.6004319654427646



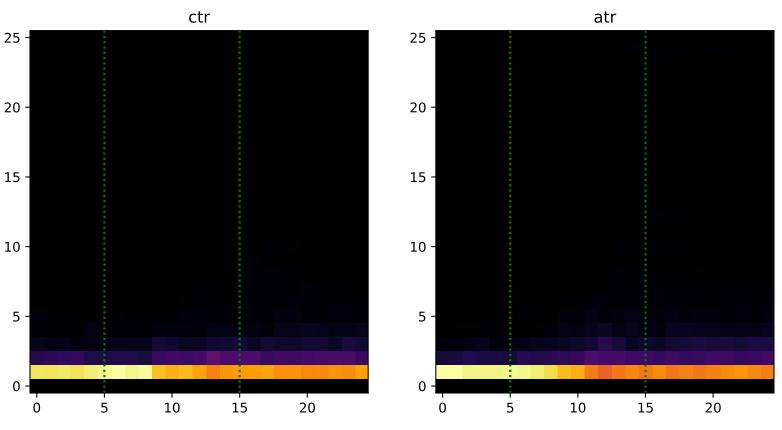
d\_minor\_axis | pval:0.6025917926565875



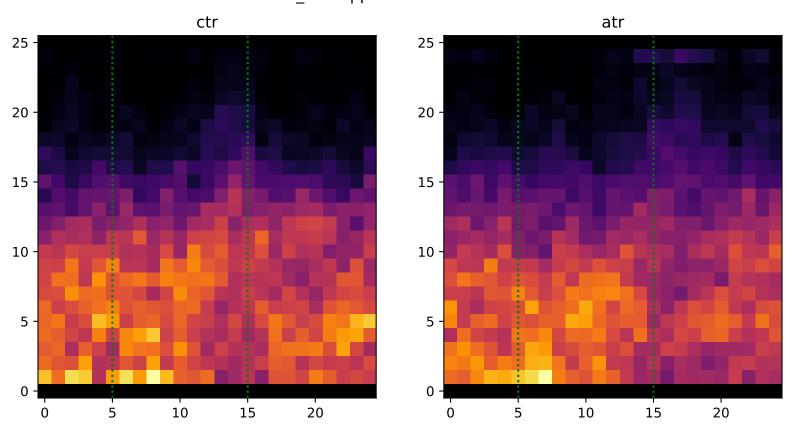
d\_speed\_tail\_base | pval:0.6069114470842333



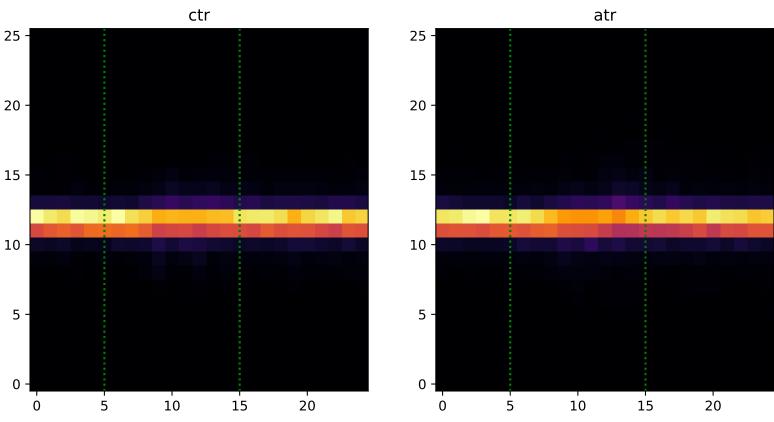
# angular\_velocity | pval:0.6133909287257019



# curvature\_head | pval:0.6241900647948164

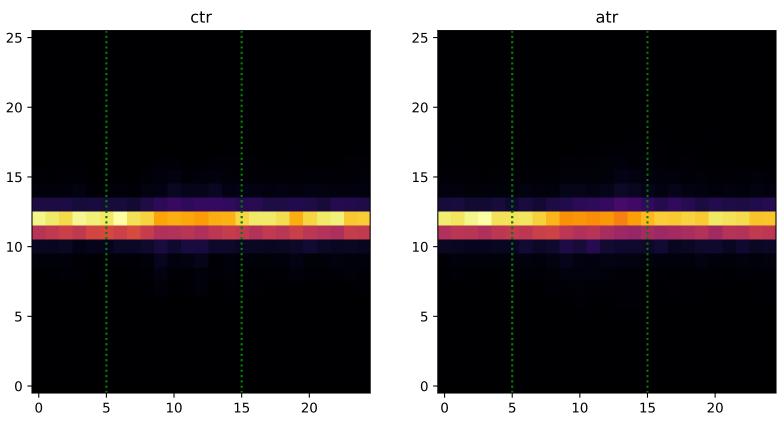


d\_speed\_midbody | pval:0.6630669546436285

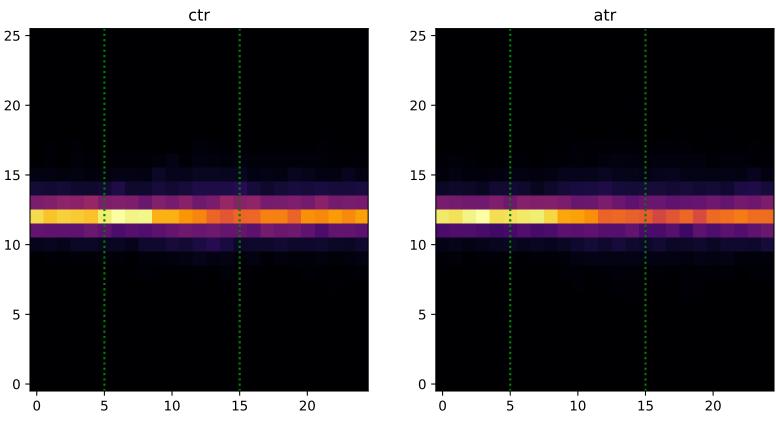


d\_eigen\_projection\_6 | pval:0.6673866090712743 ctr atr 25 -25 -20 -20 -15 -15 -10 -10 5 -5 -0 -0 -20 10 10 20 15 5 15 5

d\_speed | pval:0.673866090712743

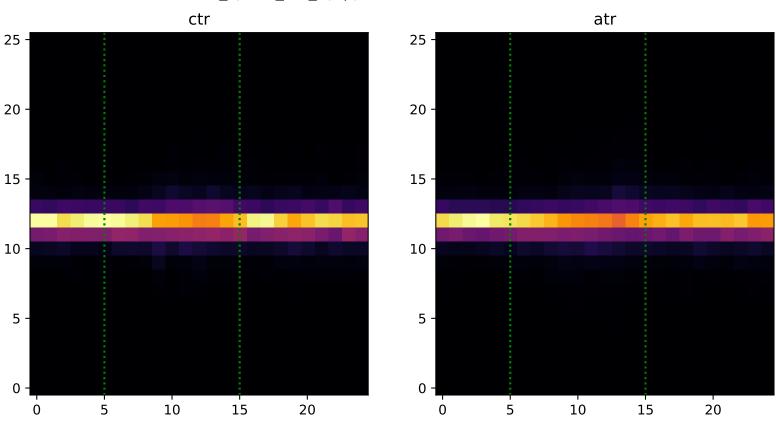


d\_relative\_to\_neck\_radial\_velocity\_head\_tip | pval:0.673866090712743

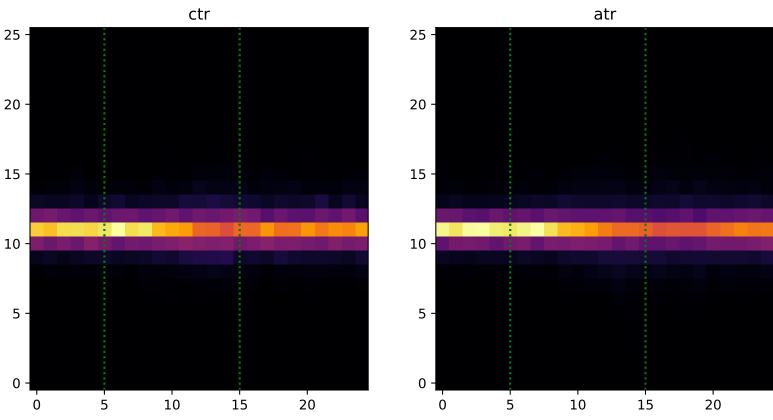


d\_eigen\_projection\_7 | pval:0.6954643628509719 ctr atr 25 -25 -20 -20 -15 -15 -10 -10 5 -5 -0 -0 20 10 10 20 5 15 5 15

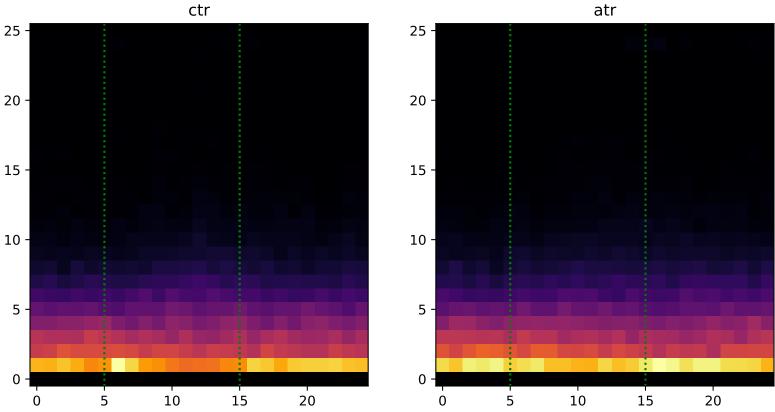
d\_speed\_tail\_tip | pval:0.7192224622030238



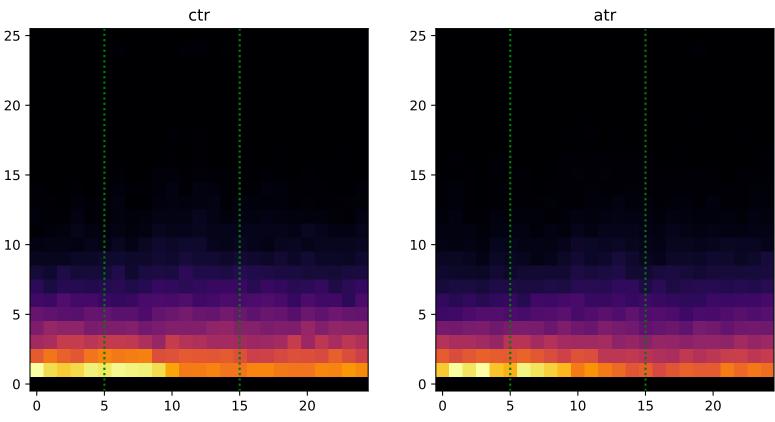
d\_relative\_to\_body\_radial\_velocity\_head\_tip | pval:0.7300215982721382



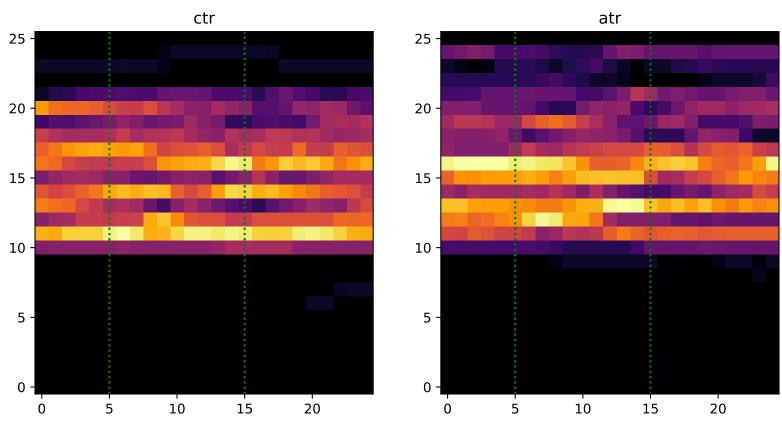
d\_angular\_velocity\_head\_tip | pval:0.7321814254859611



d\_relative\_to\_head\_base\_angular\_velocity\_head\_tip | pval:0.7365010799136069

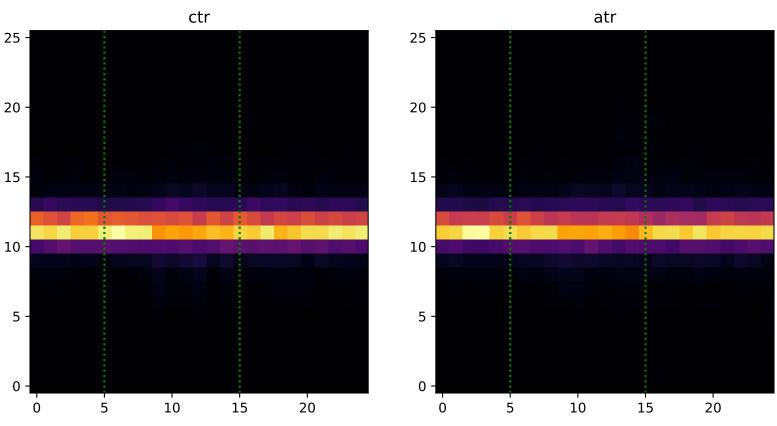


dist\_from\_food\_edge | pval:0.7429805615550756

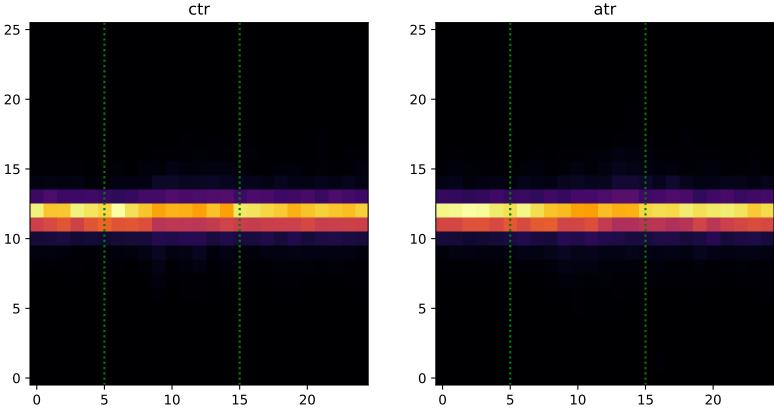


d\_eigen\_projection\_1 | pval:0.7580993520518359 ctr atr 25 -25 -20 -20 -15 -15 -10 -10 -5 -5 -0 -0 -20 10 10 20 5 15 5 15 0 0

d\_speed\_head\_tip | pval:0.7818574514038877



d\_speed\_head\_base | pval:0.7948164146868251 ctr



d\_curvature\_std\_head | pval:0.8185745140388769 ctr atr 25 -25 -20 -20 -15 -15 -10 -10 -5 -5 -

0 -

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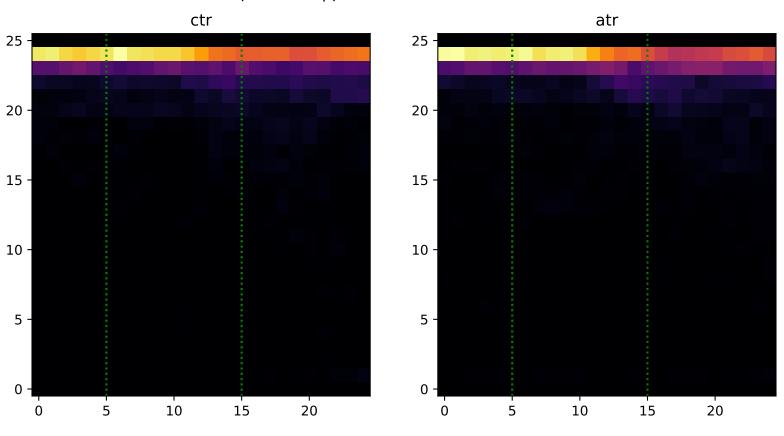
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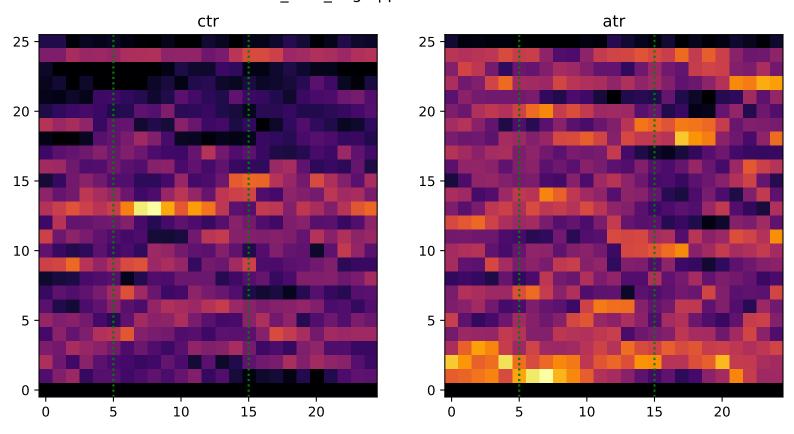
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0

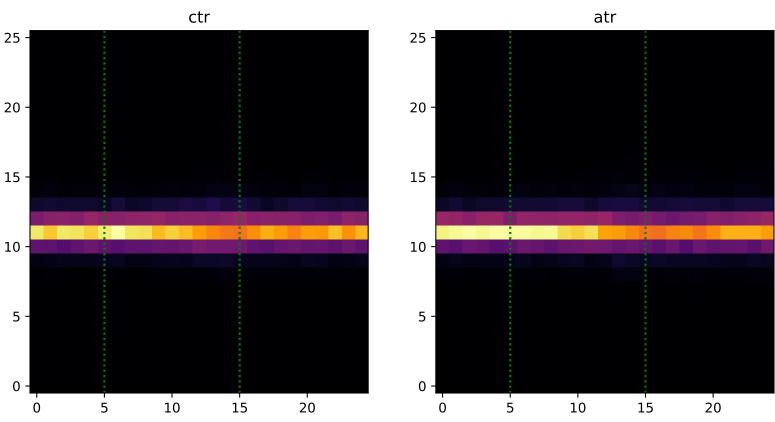
quirkiness | pval:0.8272138228941684



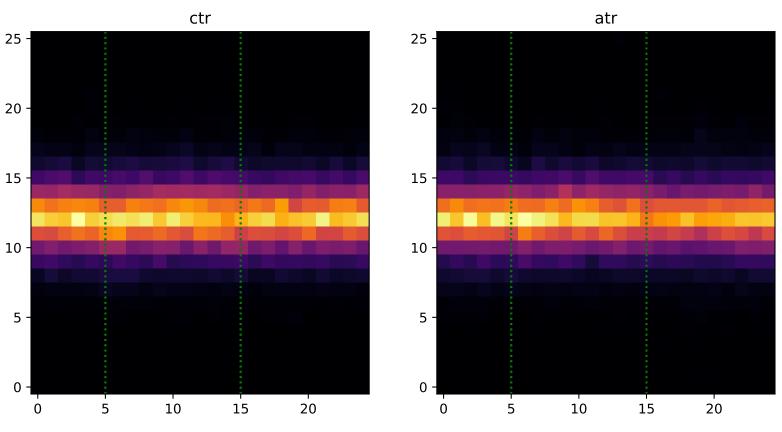
## orientation\_food\_edge | pval:0.8358531317494601



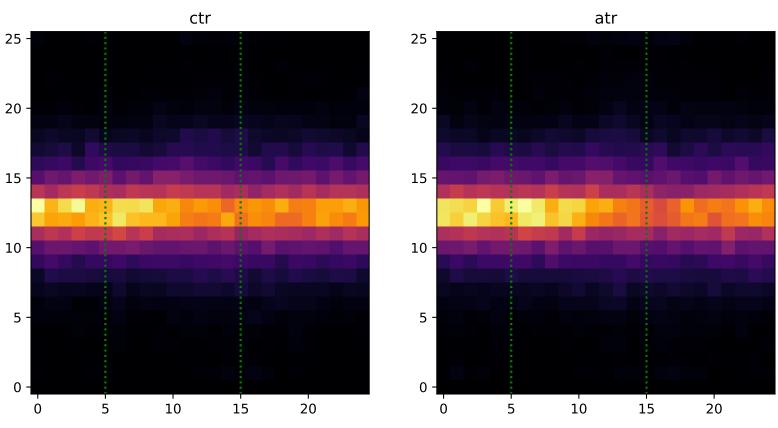
d\_relative\_to\_head\_base\_radial\_velocity\_head\_tip | pval:0.8596112311015118



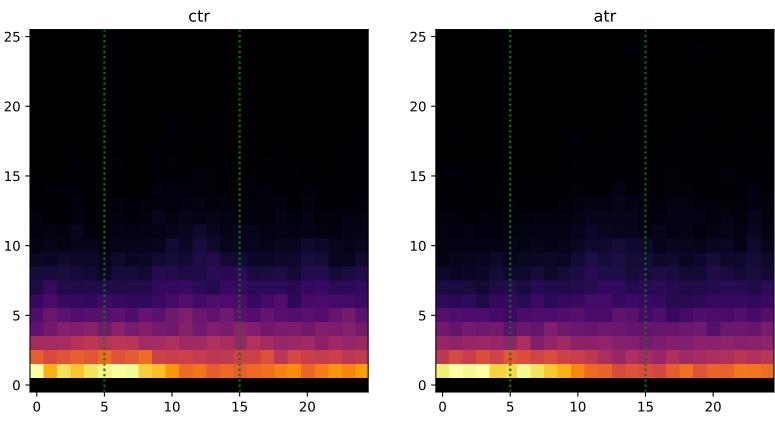
d\_area | pval:0.8876889848812095



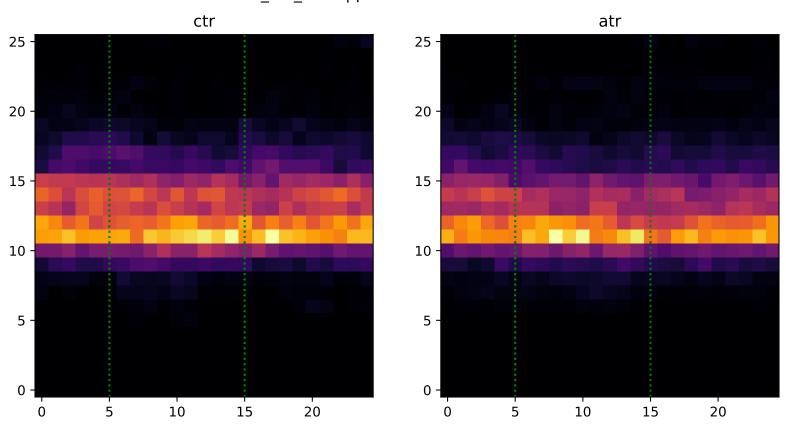
d\_width\_head\_base | pval:0.8876889848812095



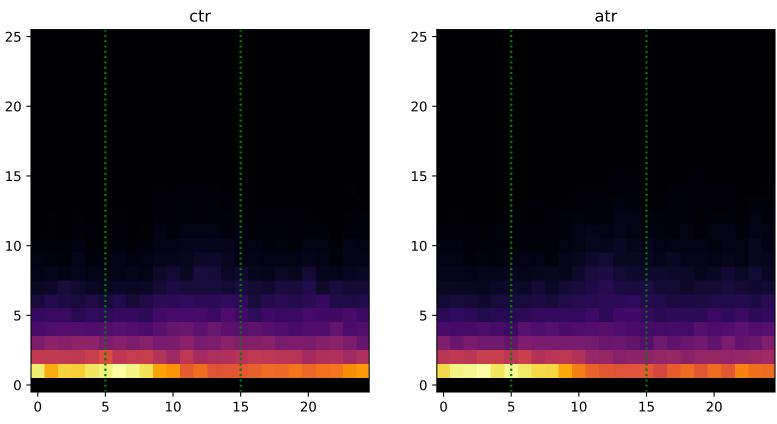
relative\_to\_head\_base\_angular\_velocity\_head\_tip | pval:0.9114470842332614



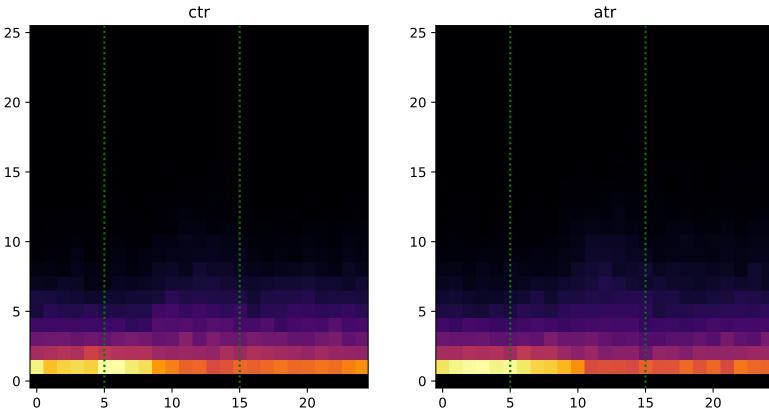
## width\_tail\_base | pval:0.9287257019438445



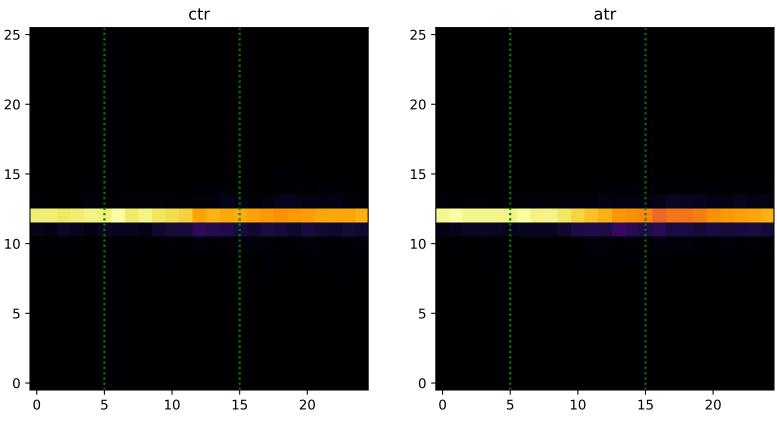
d\_curvature\_head | pval:0.9308855291576674



d\_curvature\_mean\_head | pval:0.9438444924406048



d\_quirkiness | pval:0.9481641468682506



curvature\_mean\_neck | pval:0.9654427645788337

