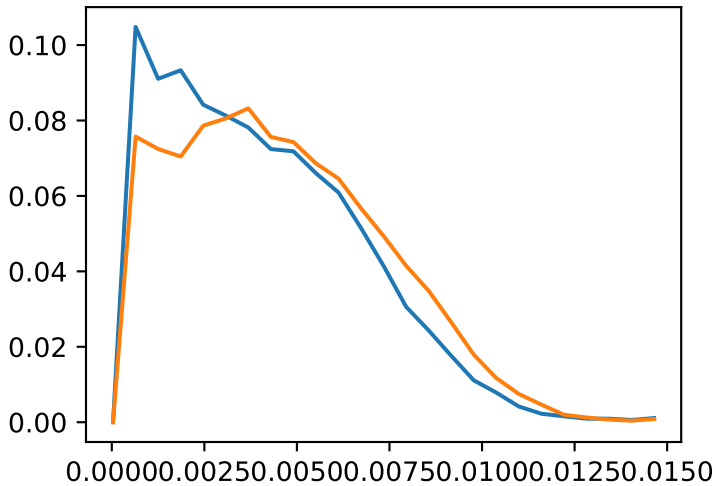
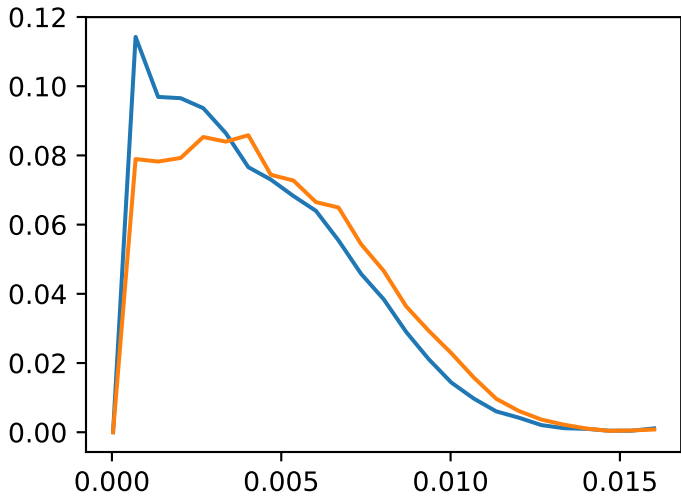


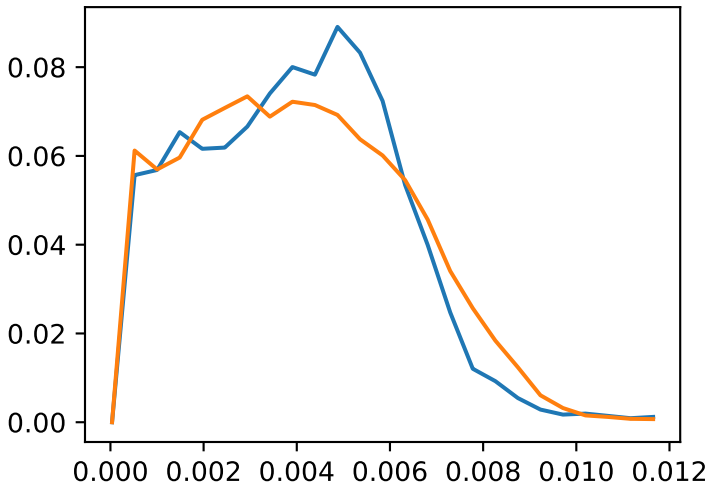
curvature\_mean\_head | pval:0.008639



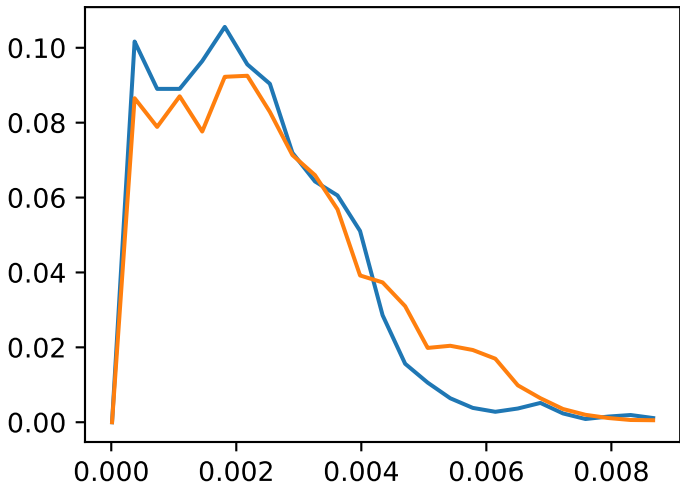
curvature\_head | pval:0.0108



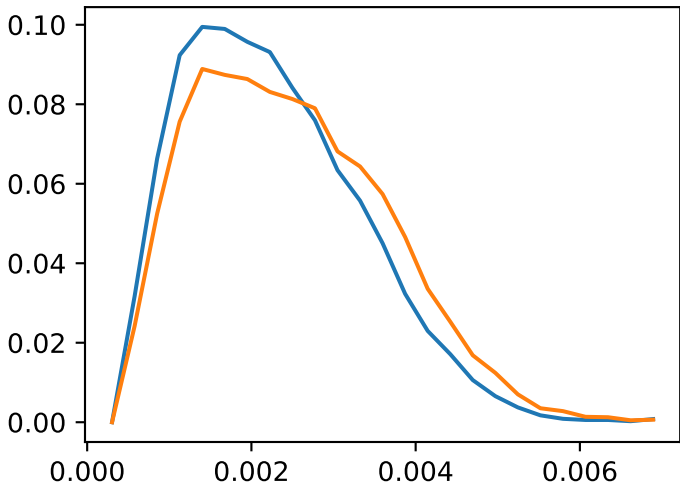
curvature\_mean\_neck | pval:0.02808



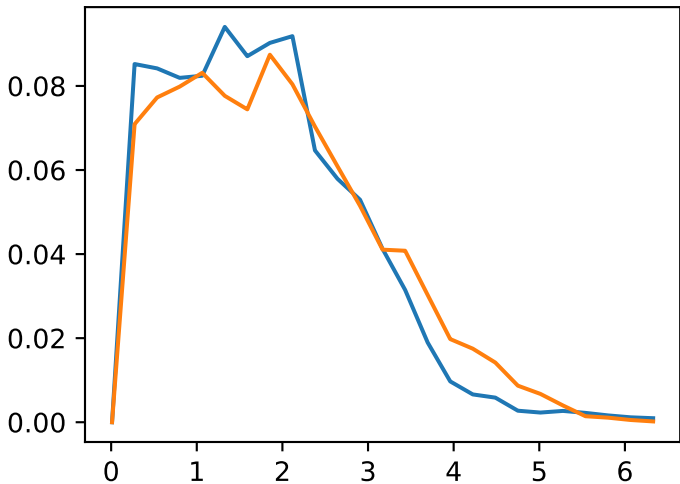
curvature\_mean\_midbody | pval:0.0324



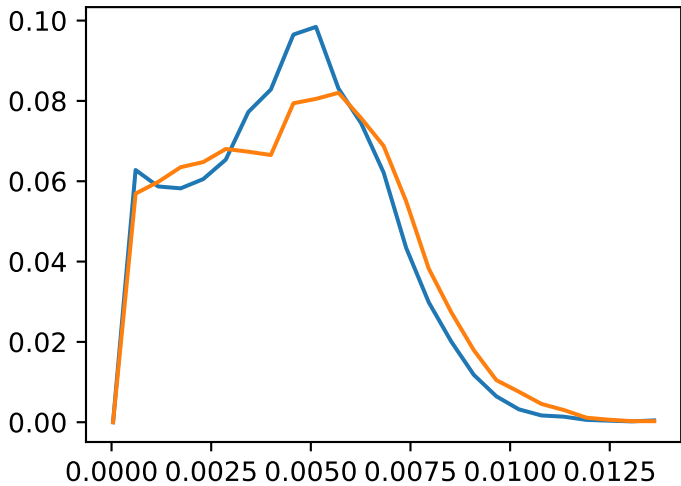
curvature\_std\_neck | pval:0.0432



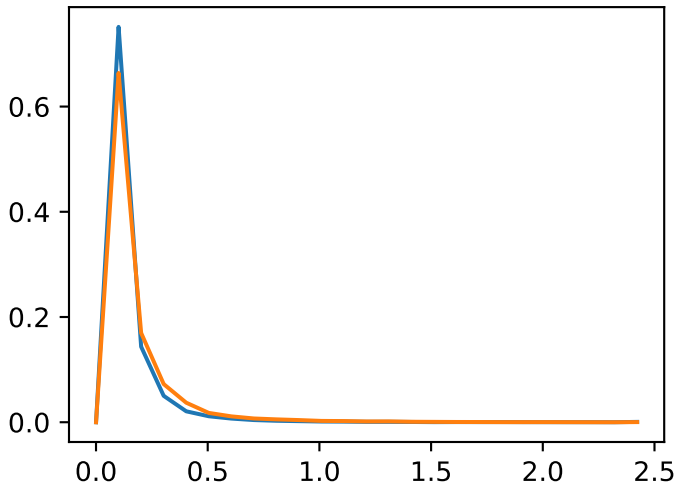
eigen\_projection\_3 | pval:0.06048



curvature\_neck | pval:0.06048

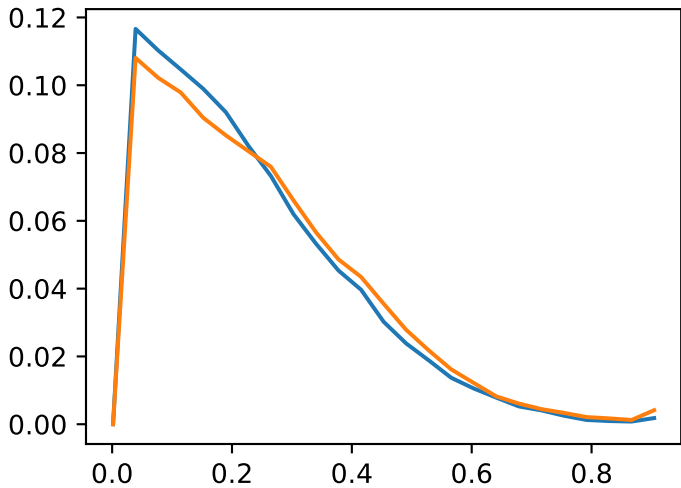


relative\_to\_body\_angular\_velocity\_tail\_tip | pval:0.1058

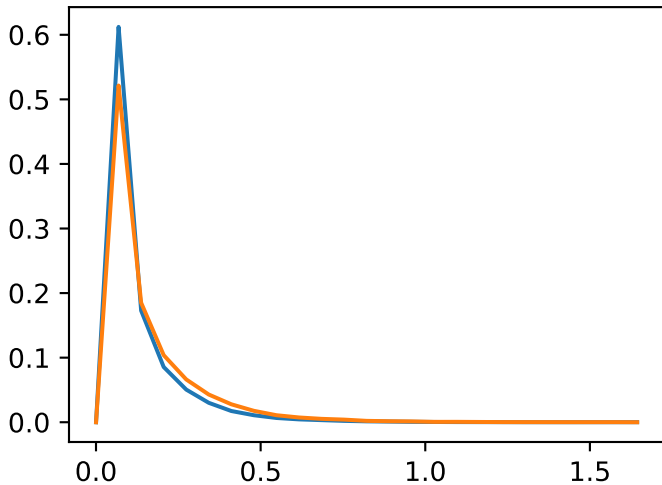




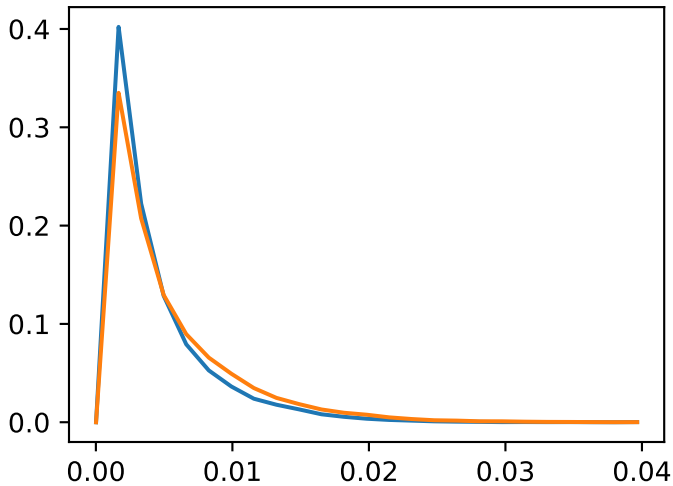
eigen\_projection\_7 | pval:0.1123



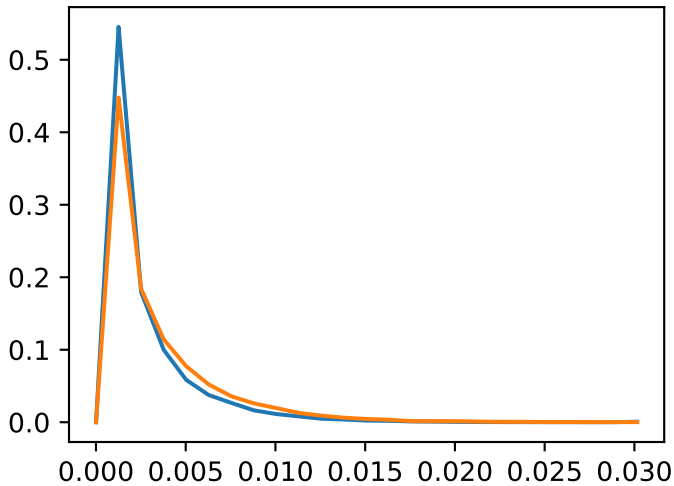
relative\_to\_body\_angular\_velocity\_hips | pval:0.1188



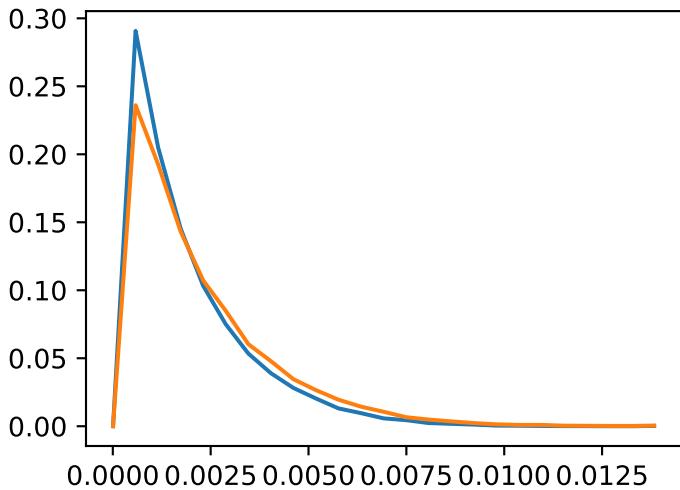
d\_curvature\_neck | pval:0.121



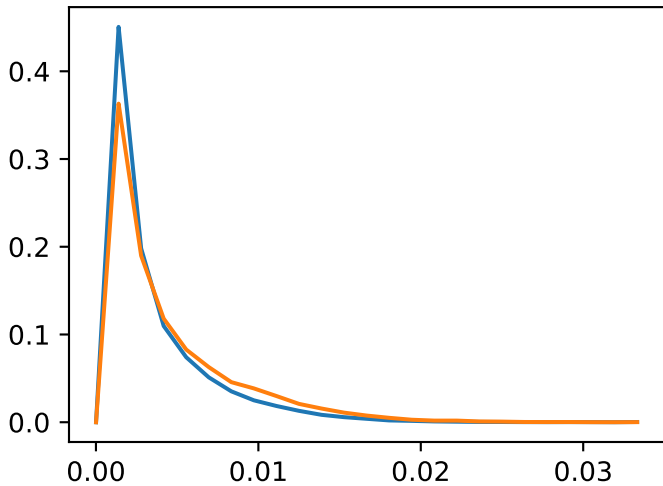
d\_curvature\_mean\_hips | pval:0.1274



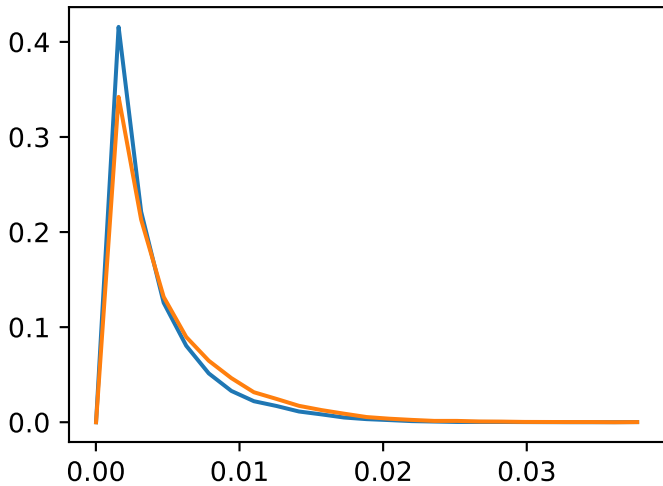
d\_curvature\_std\_neck | pval:0.1296



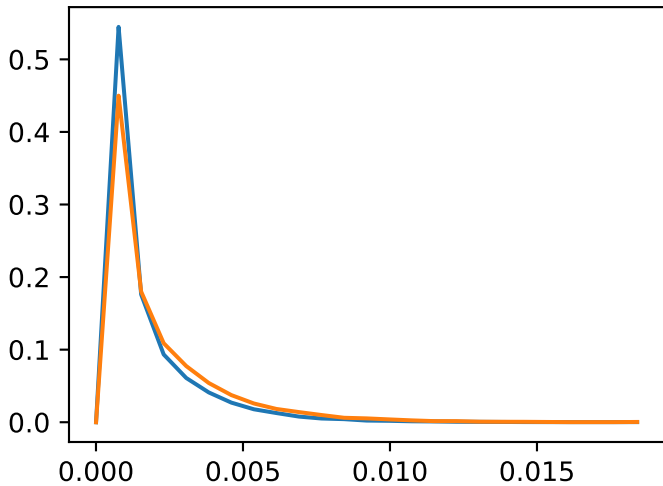
d\_curvature\_mean\_neck | pval:0.1317



d\_curvature\_midbody | pval:0.1339

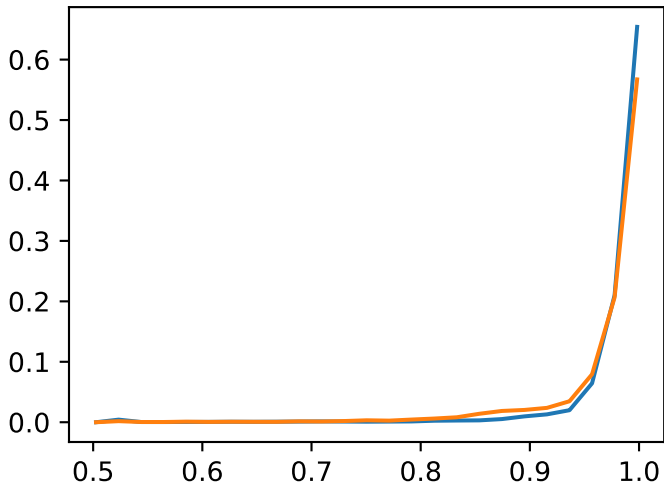


d\_curvature\_mean\_midbody | pval:0.1361

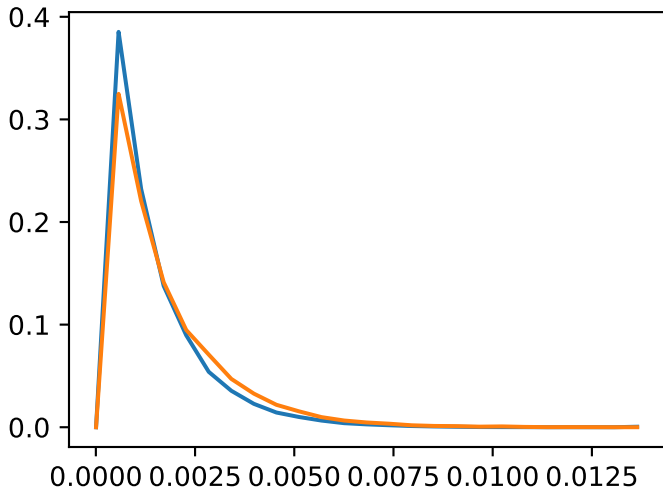




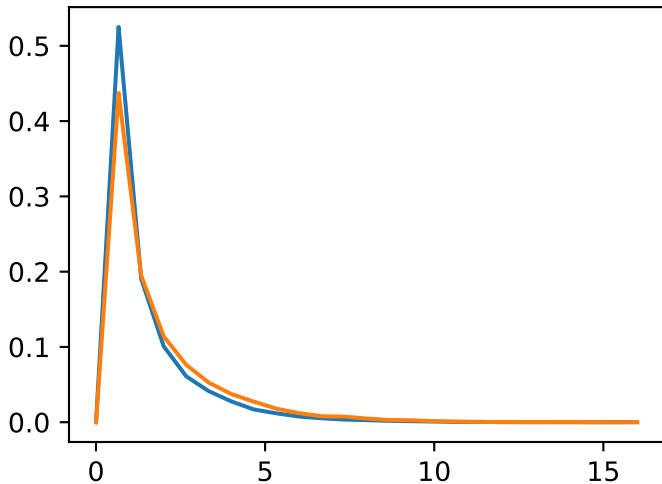
quirkiness | pval:0.1404



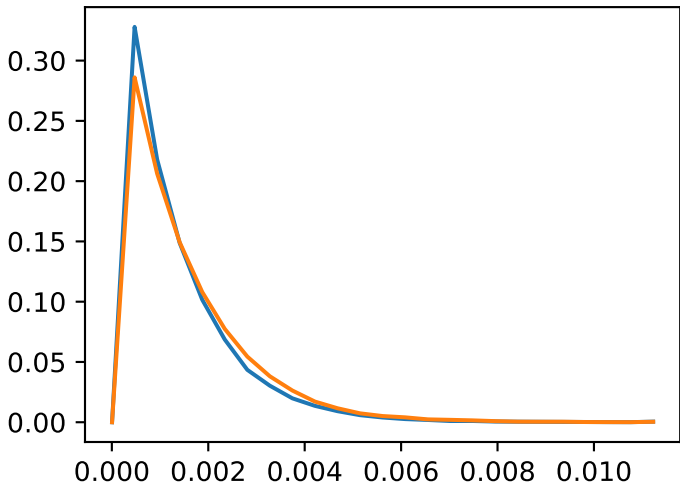
d\_curvature\_std\_hips | pval:0.1404



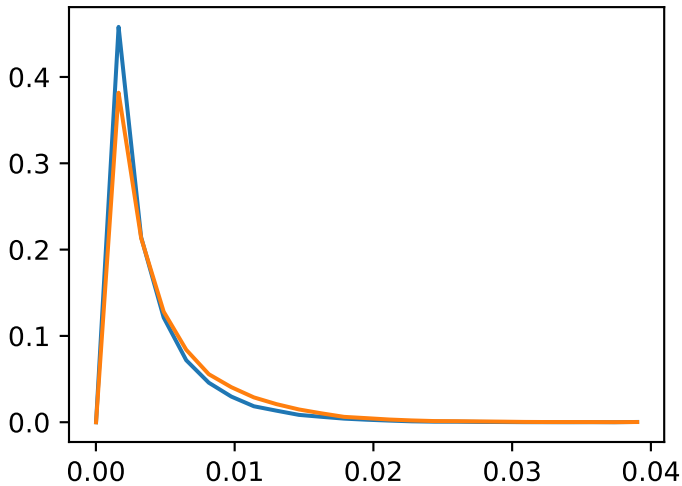
d\_eigen\_projection\_3 | pval:0.1447



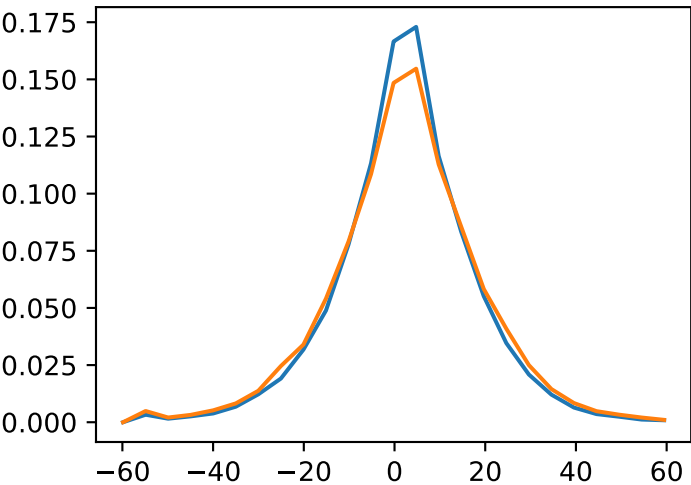
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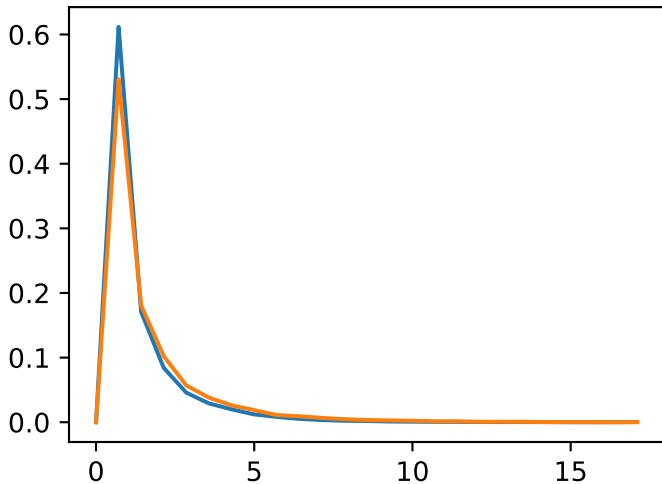
d\_curvature\_hips | pval:0.1533



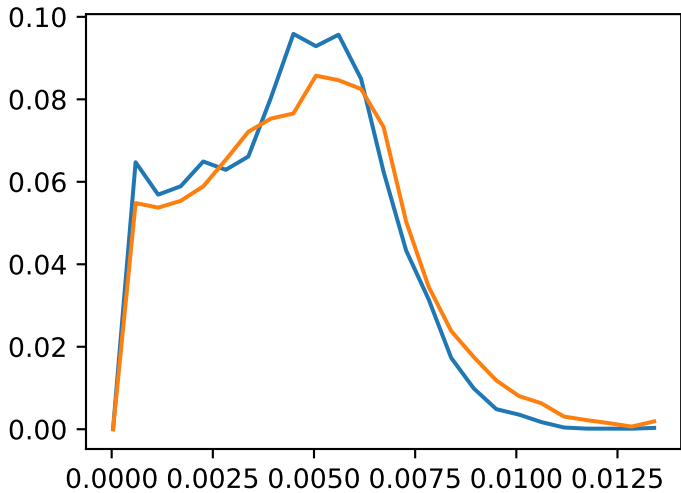
d\_width\_head\_base | pval:0.1555



d\_eigen\_projection\_2 | pval:0.1577

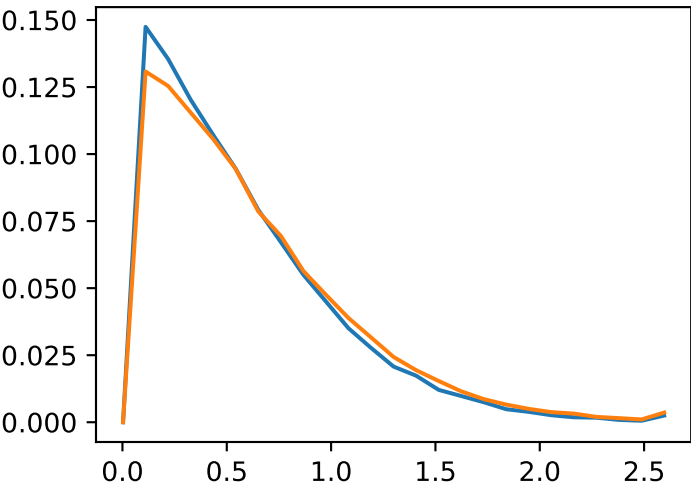


curvature\_midbody | pval:0.162

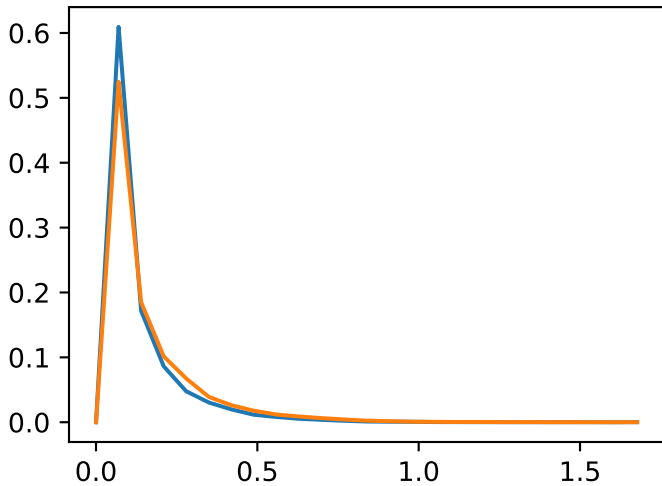




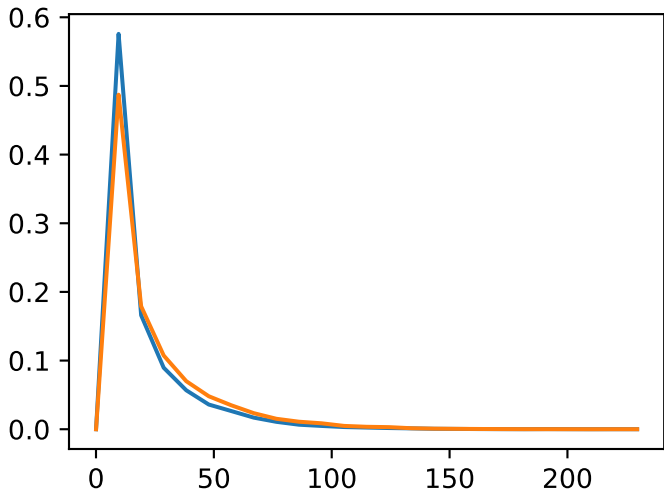
d\_eigen\_projection\_7 | pval:0.1641



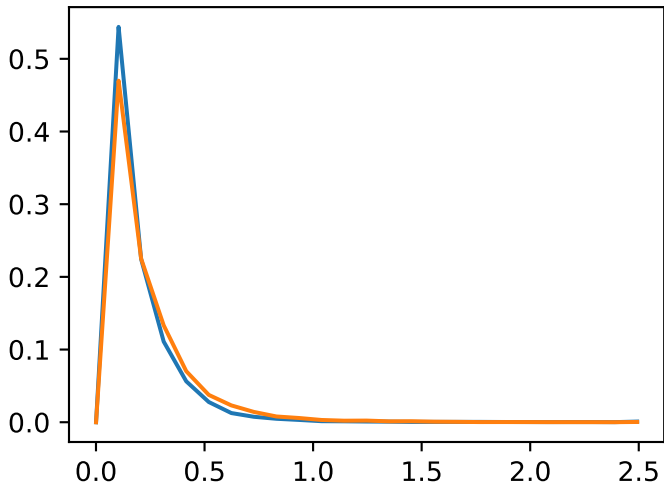
relative\_to\_body\_angular\_velocity\_neck | pval:0.1706



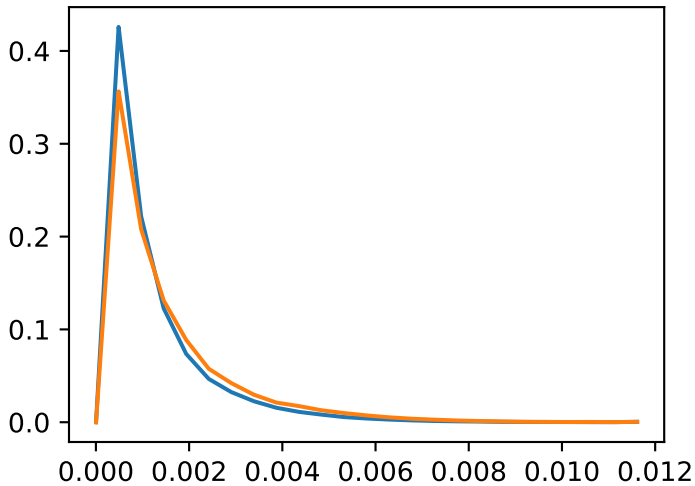
relative\_to\_body\_speed\_midbody | pval:0.1728



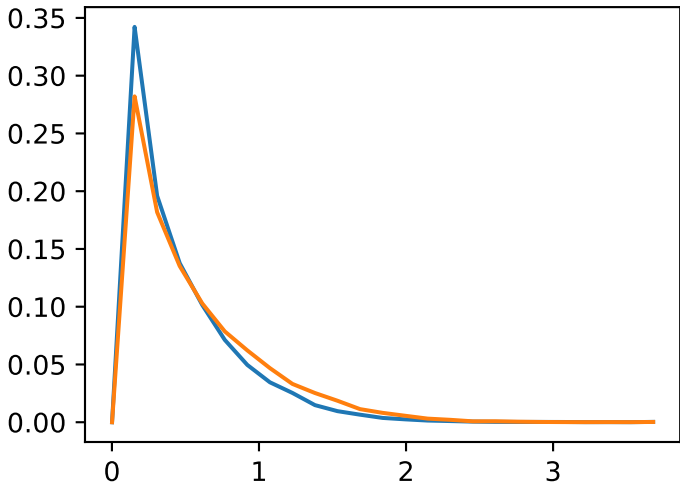
relative\_to\_body\_angular\_velocity\_head\_tip | pval:0.1771



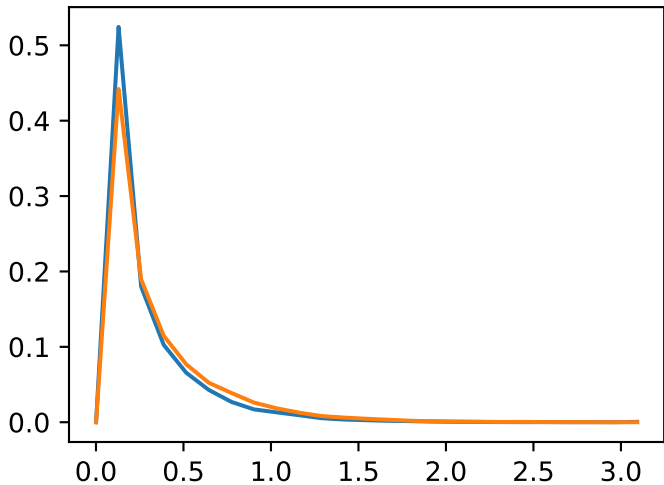
d\_curvature\_std\_midbody | pval:0.1771



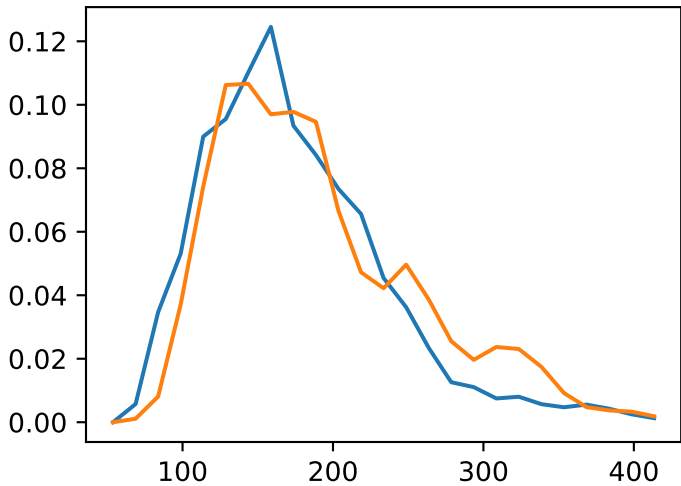
relative\_to\_neck\_angular\_velocity\_head\_tip | pval:0.1836



relative\_to\_hips\_angular\_velocity\_tail\_tip | pval:0.1857

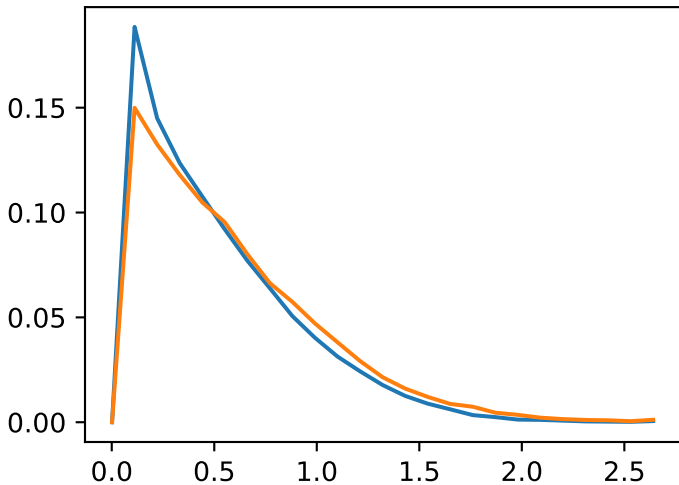


minor\_axis | pval:0.1901

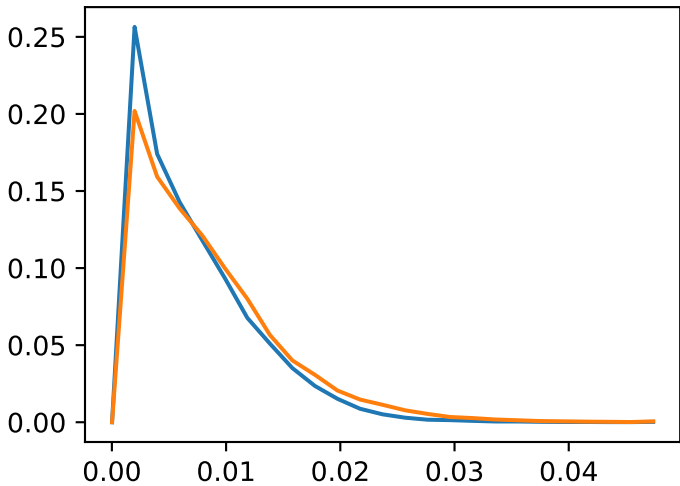




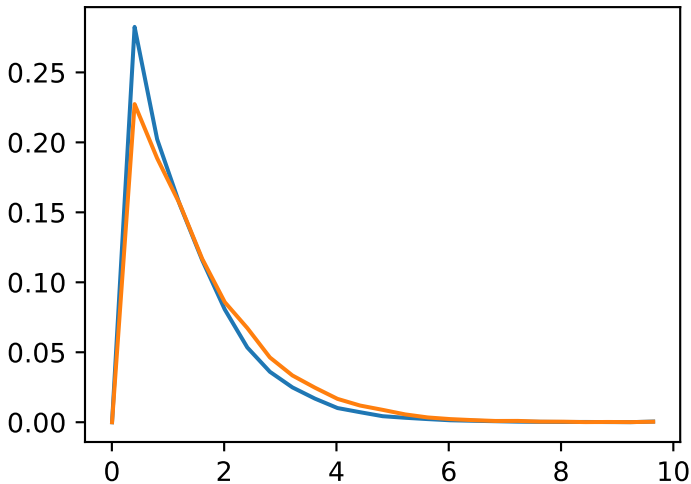
relative\_to\_head\_base\_angular\_velocity\_head\_tip | pval:0.1965



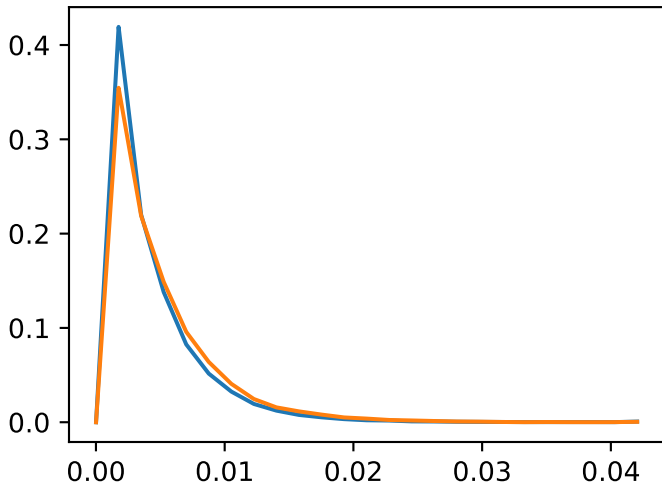
d\_curvature\_mean\_head | pval:0.1987



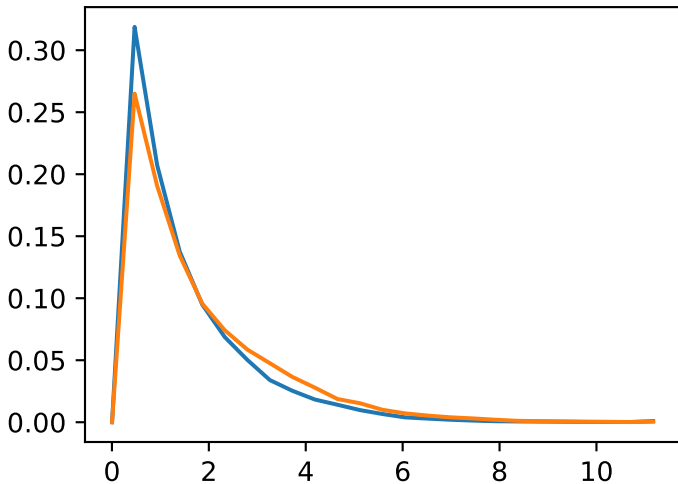
d\_eigen\_projection\_4 | pval:0.2009



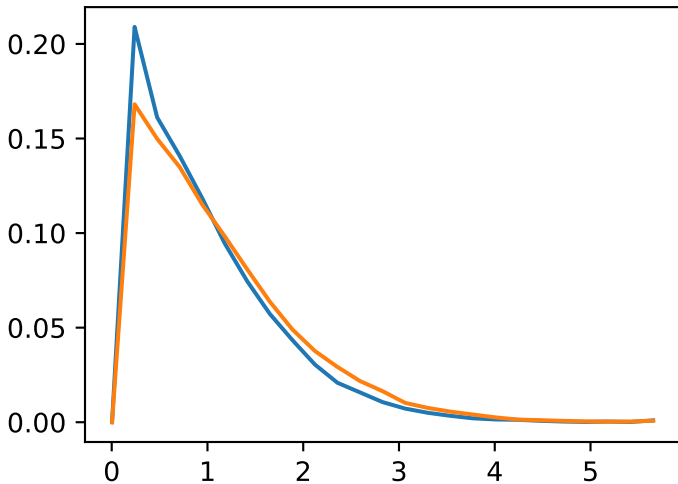
d\_curvature\_tail | pval:0.2073



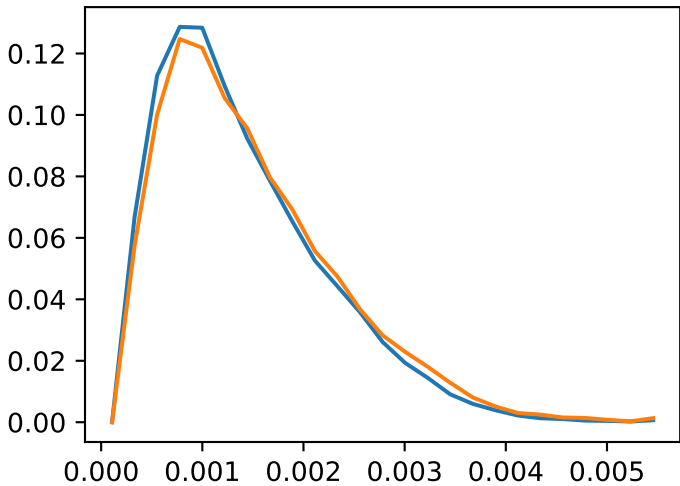
d\_eigen\_projection\_1 | pval:0.2138



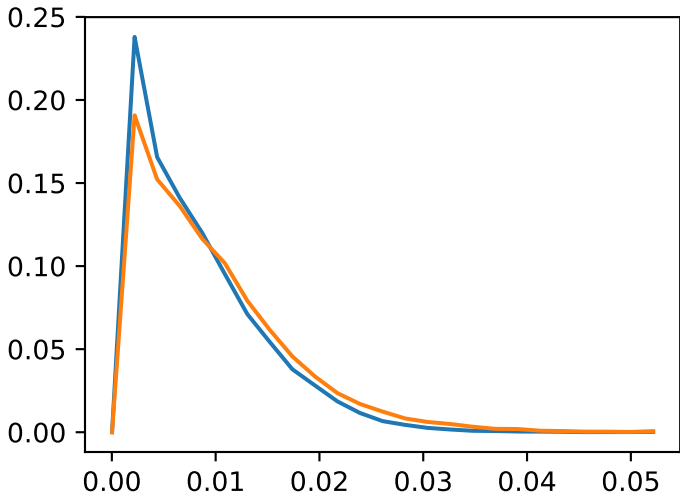
d\_eigen\_projection\_5 | pval:0.2181



curvature\_std\_head | pval:0.2225

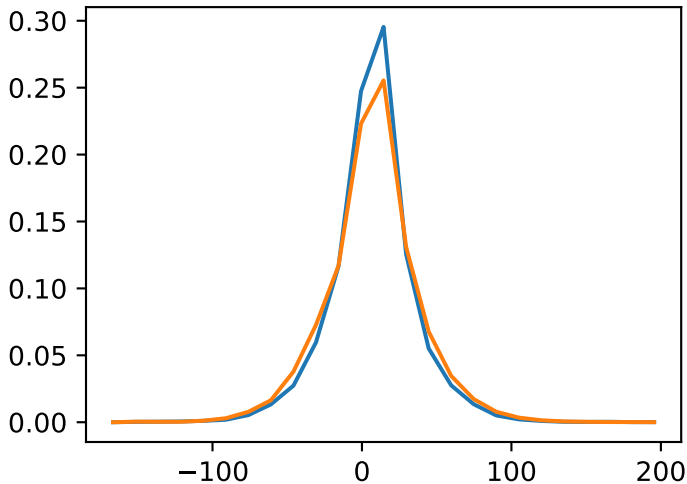


d\_curvature\_head | pval:0.2246

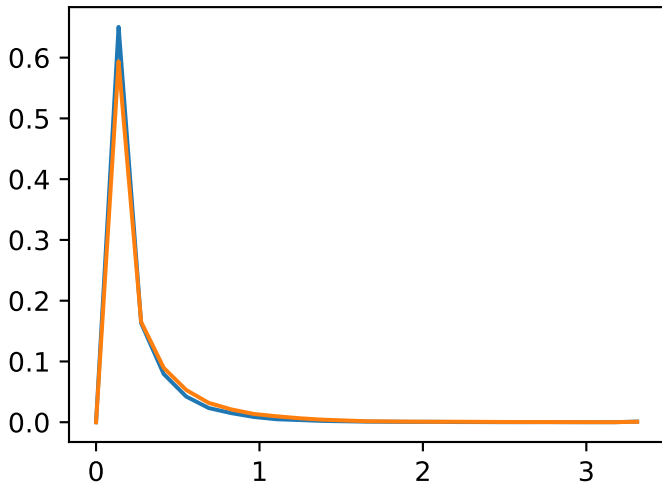




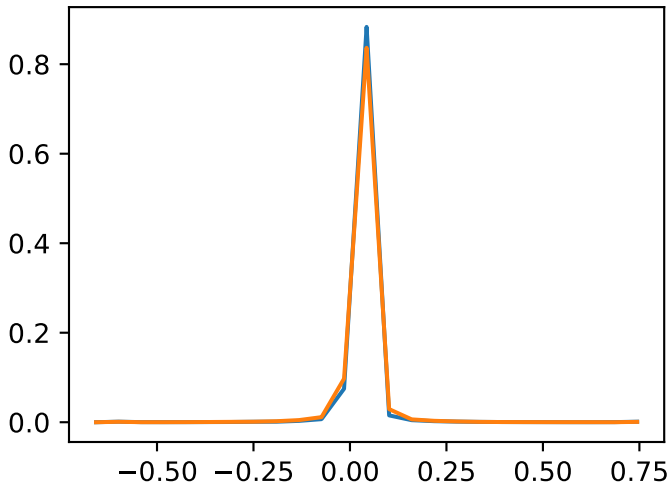
relative\_to\_neck\_radial\_velocity\_head\_tip | pval:0.2268



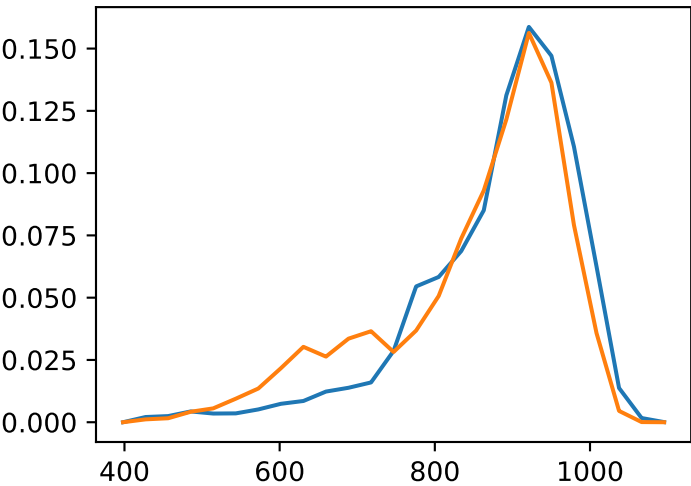
angular\_velocity\_midbody | pval:0.2289



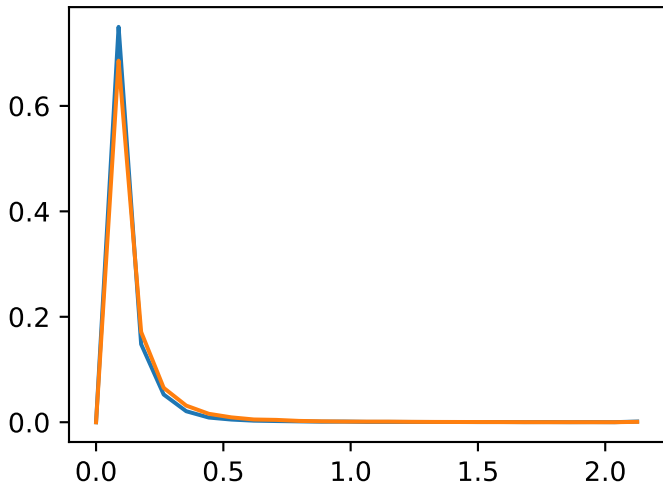
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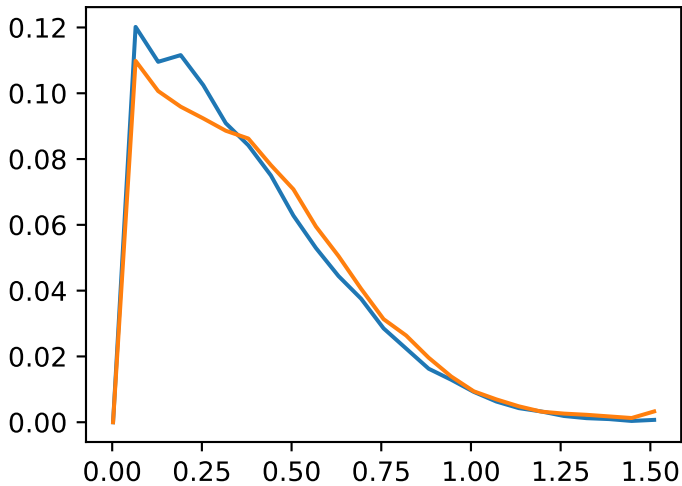
major\_axis | pval:0.2419



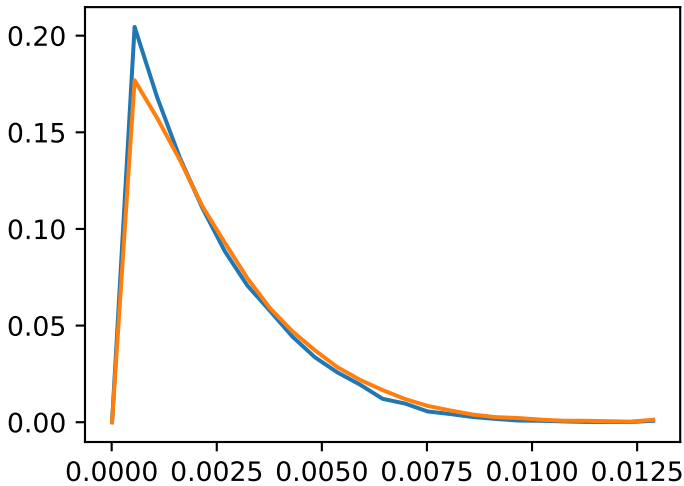
angular\_velocity | pval:0.2441



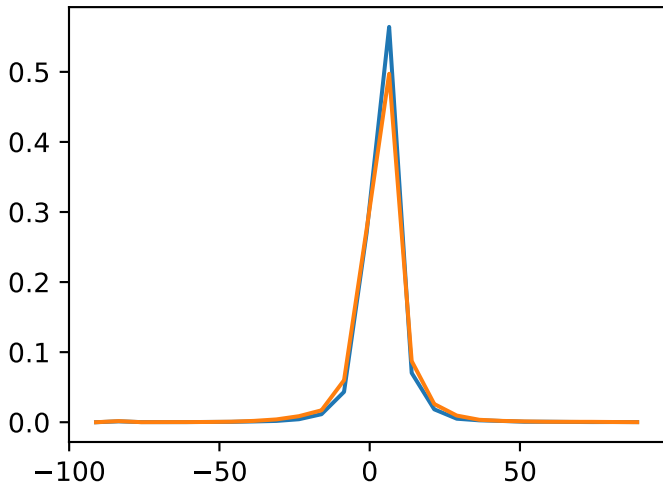
eigen\_projection\_6 | pval:0.2505



d\_curvature\_std\_head | pval:0.257

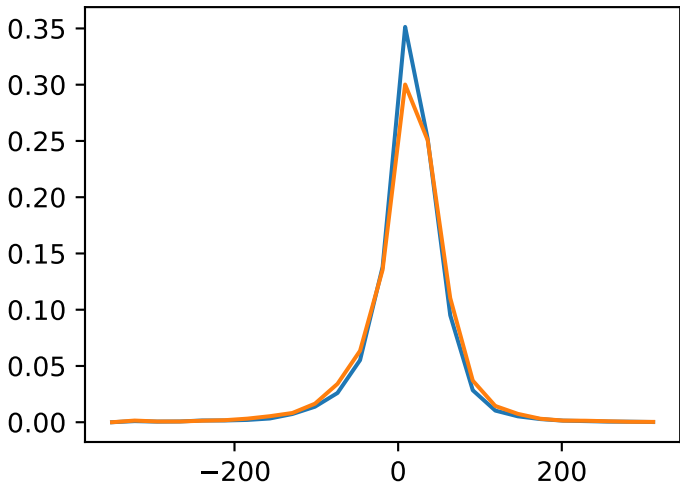


d\_orientation\_food\_edge | pval:0.257

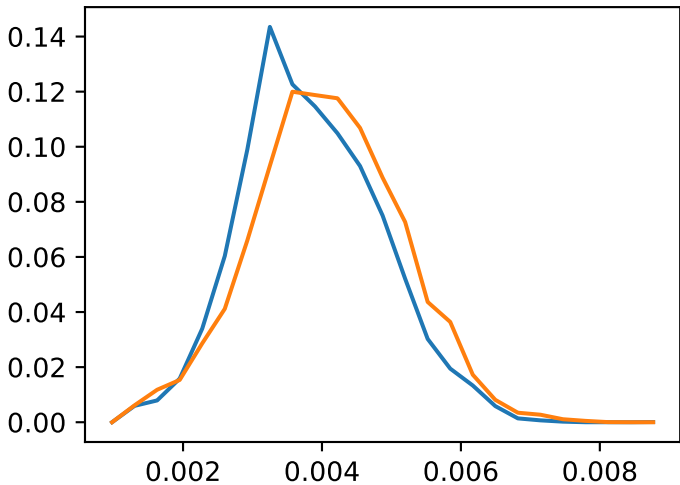




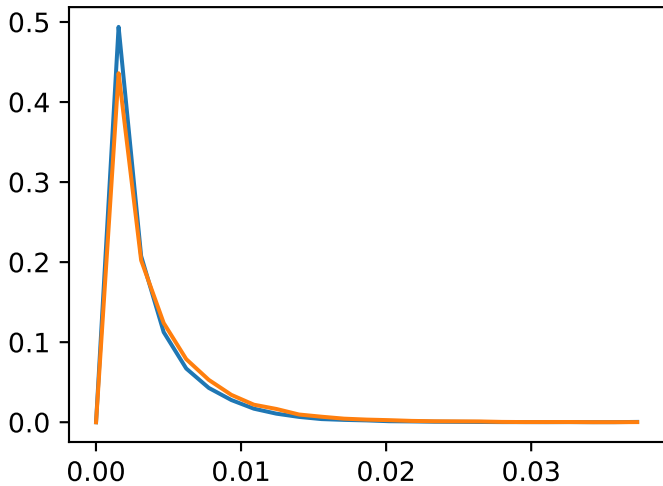
relative\_to\_body\_radial\_velocity\_head\_tip | pval:0.2613



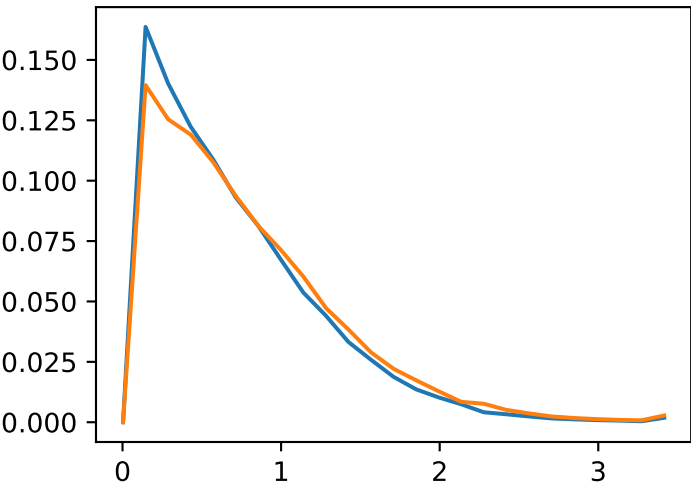
curvature\_std\_midbody | pval:0.27



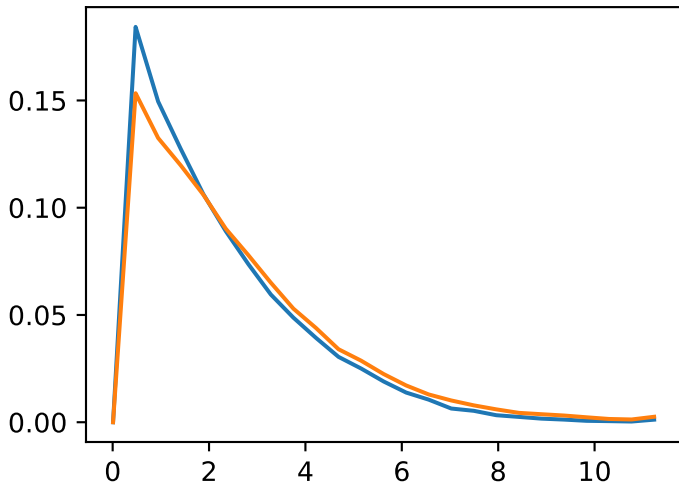
d\_curvature\_mean\_tail | pval:0.2894



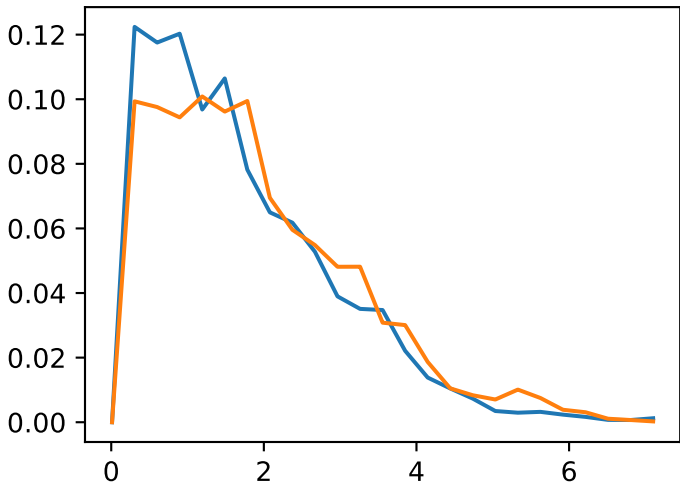
d\_eigen\_projection\_6 | pval:0.3089



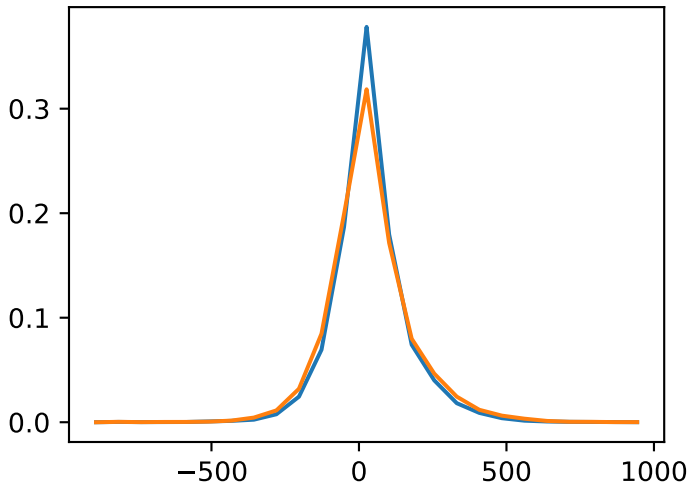
d\_relative\_to\_head\_base\_angular\_velocity\_head\_tip | pval:0.3132



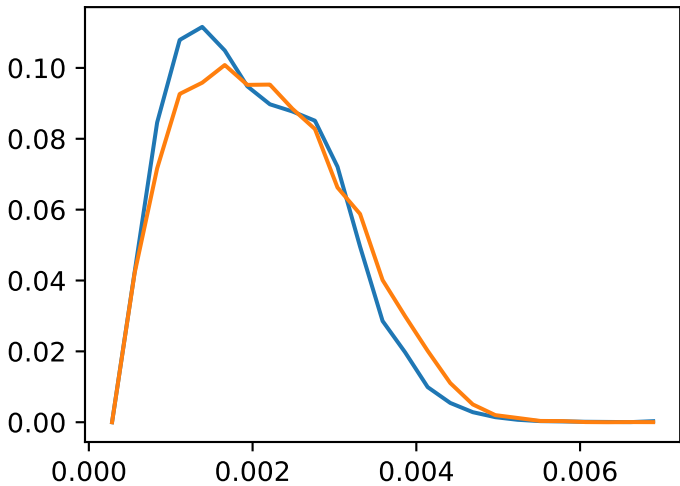
eigen\_projection\_2 | pval:0.3153



d\_relative\_to\_neck\_radial\_velocity\_head\_tip | pval:0.3261

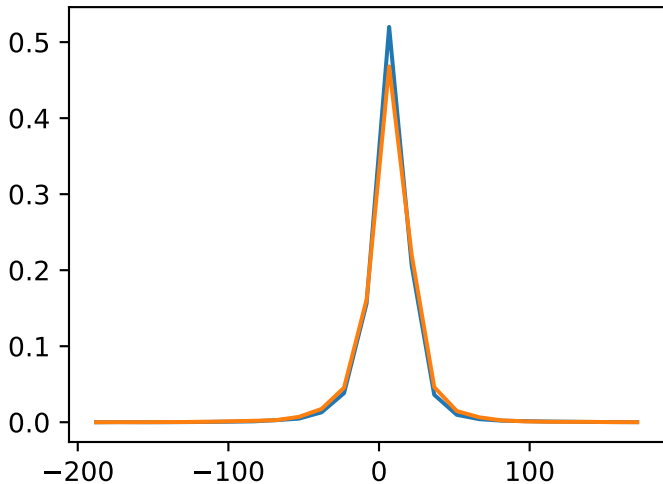


curvature\_std\_hips | pval:0.3391

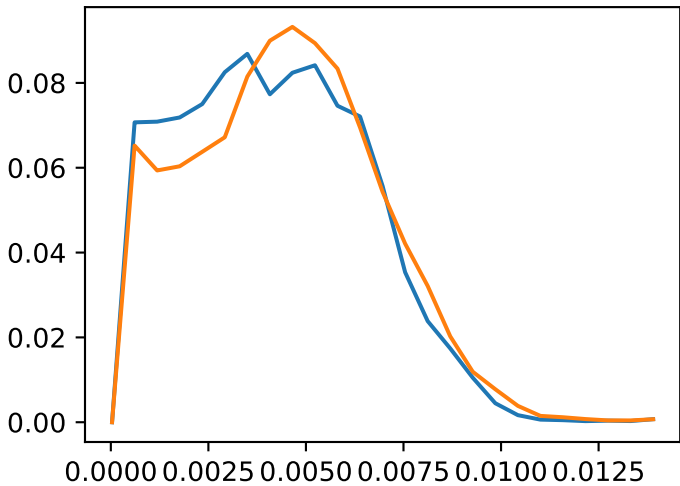




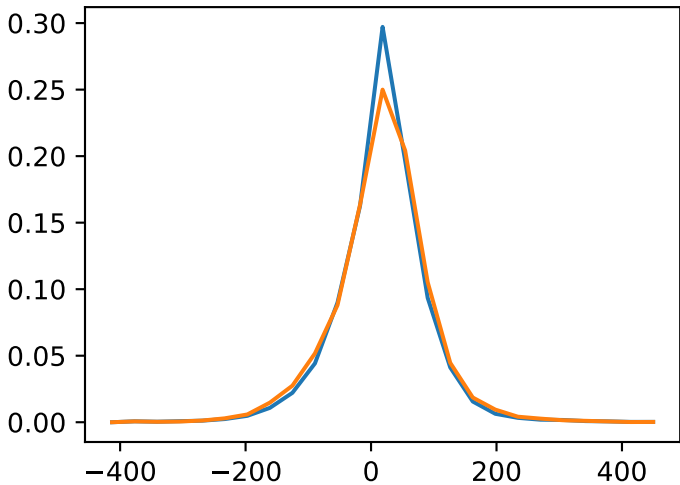
relative\_to\_body\_radial\_velocity\_neck | pval:0.3477



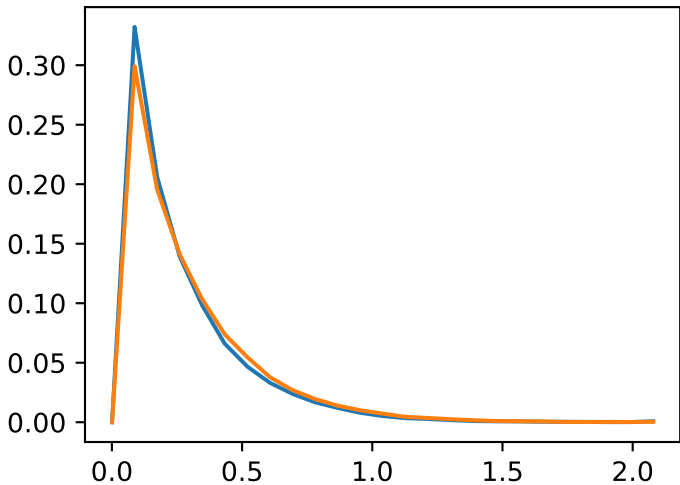
curvature\_hips | pval:0.365



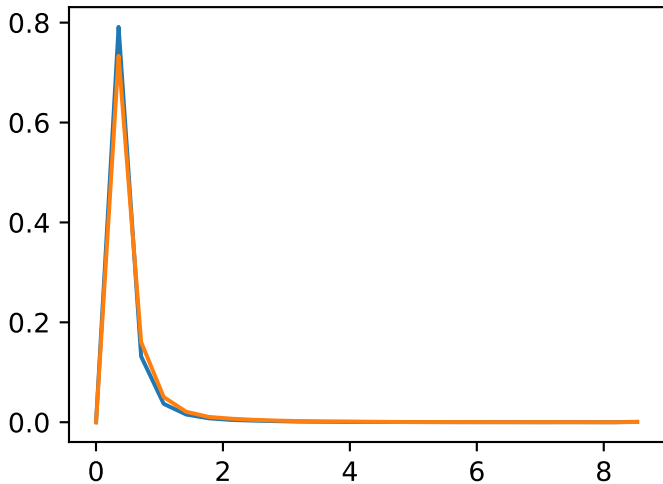
d\_major\_axis | pval:0.3672



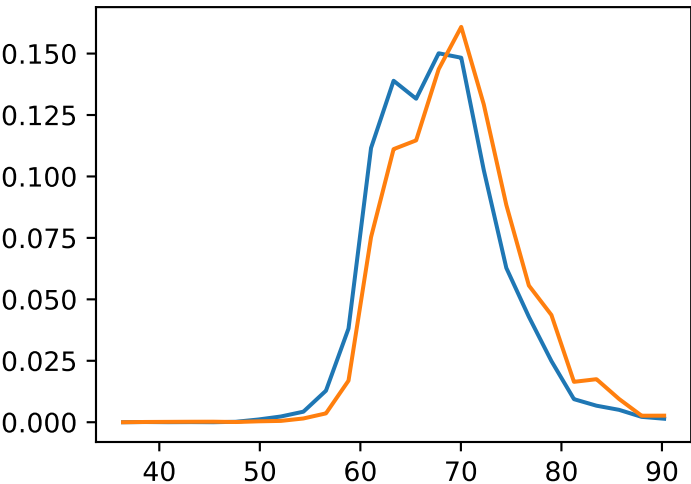
relative\_to\_tail\_base\_angular\_velocity\_tail\_tip | pval:0.3758



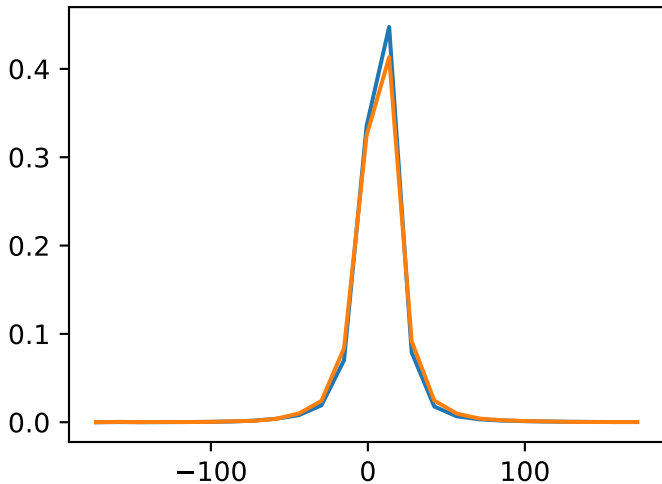
d\_relative\_to\_body\_angular\_velocity\_tail\_tip | pval:0.3758



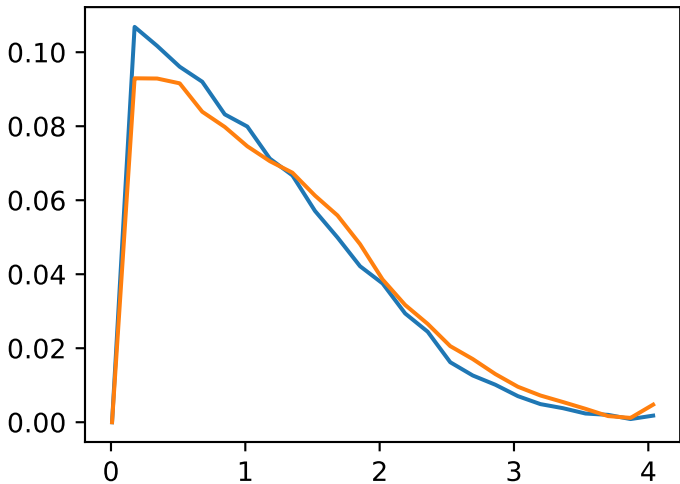
width\_tail\_base | pval:0.378



relative\_to\_body\_radial\_velocity\_hips | pval:0.3801

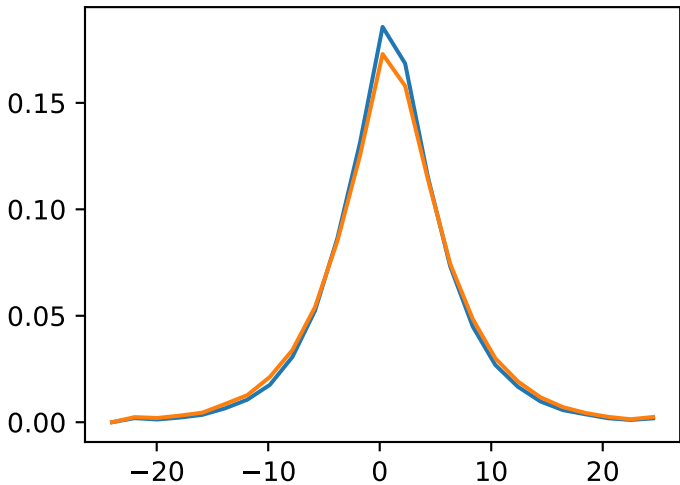


eigen\_projection\_4 | pval:0.4082

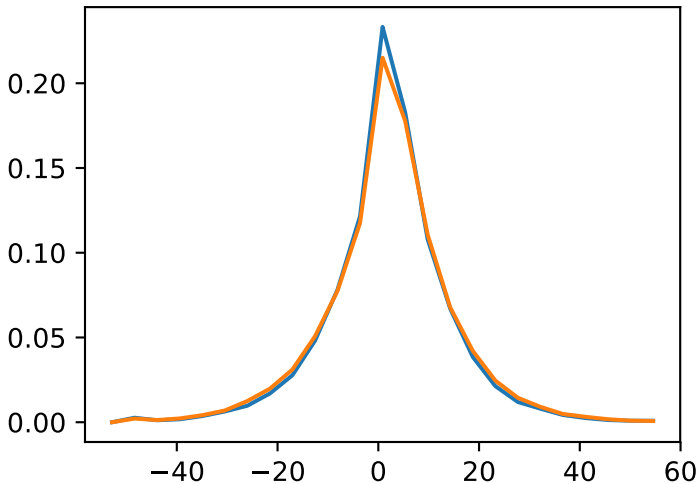




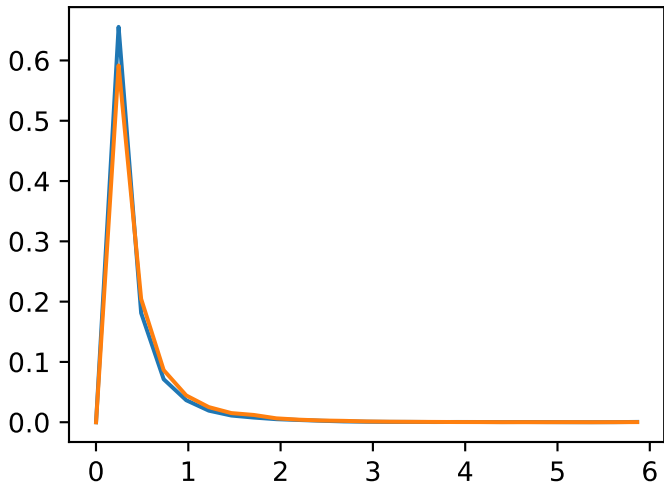
d\_width\_midbody | pval:0.4104



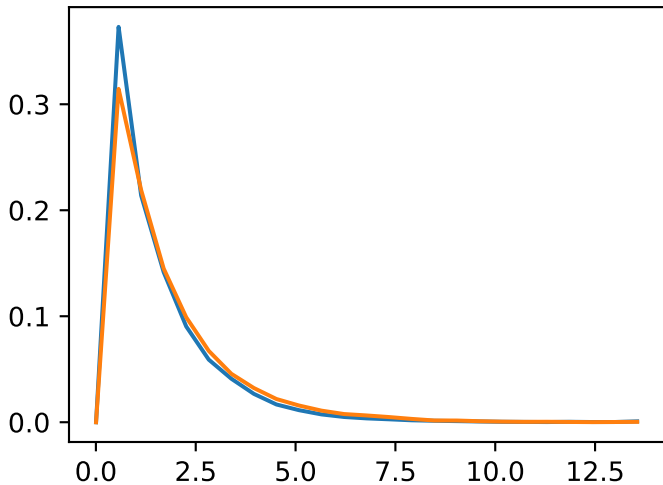
d\_width\_tail\_base | pval:0.419



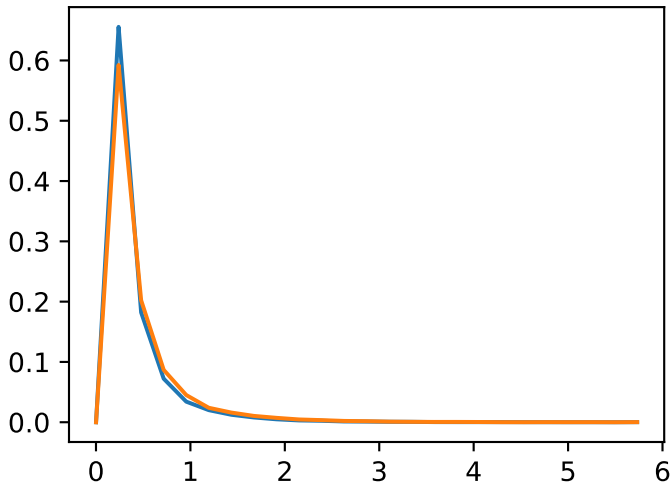
d\_relative\_to\_body\_angular\_velocity\_neck | pval:0.4233



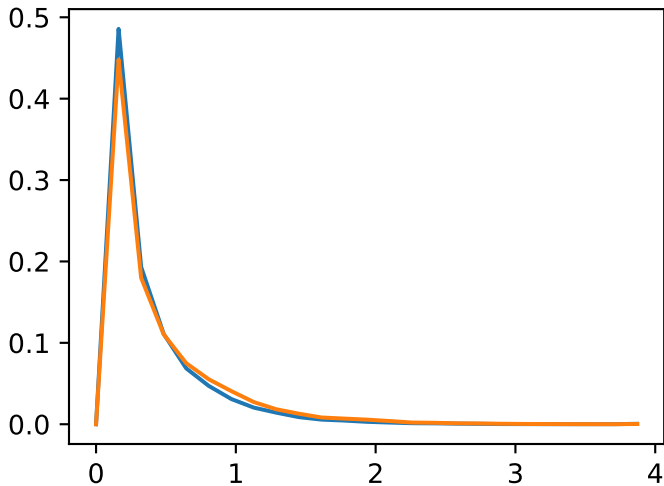
d\_relative\_to\_neck\_angular\_velocity\_head\_tip | pval:0.4233



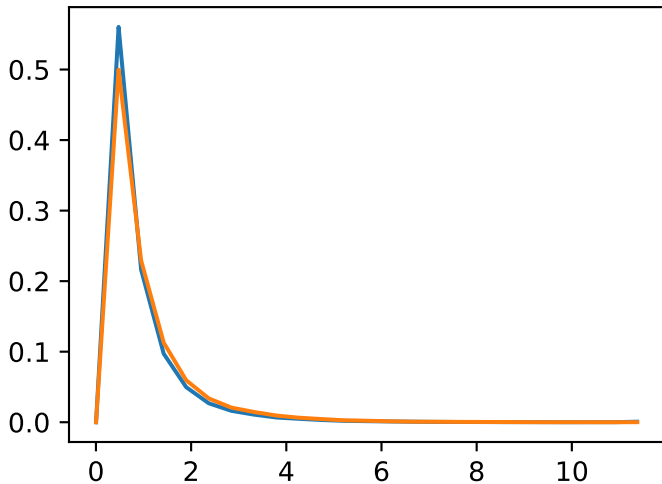
d\_relative\_to\_body\_angular\_velocity\_hips | pval:0.4255



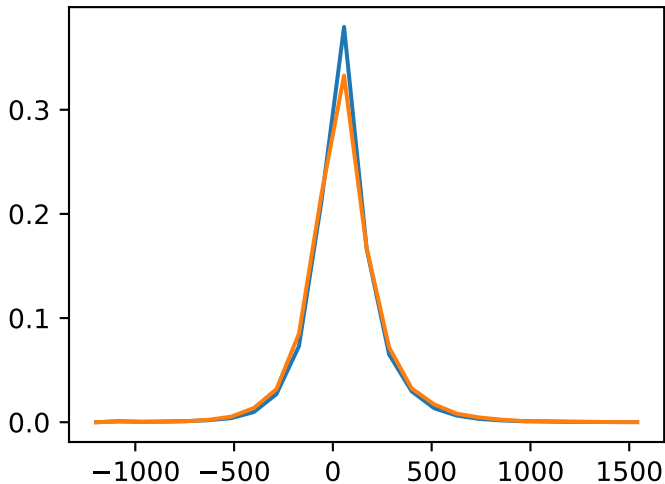
angular\_velocity\_neck | pval:0.4341



d\_relative\_to\_hips\_angular\_velocity\_tail\_tip | pval:0.4492

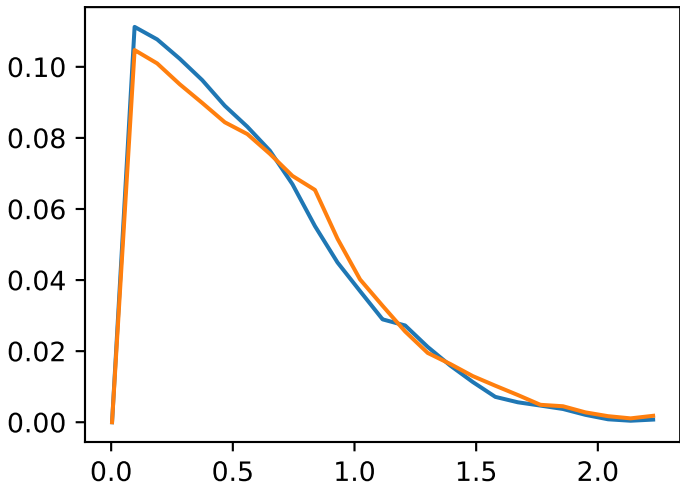


d\_relative\_to\_body\_radial\_velocity\_head\_tip | pval:0.4514

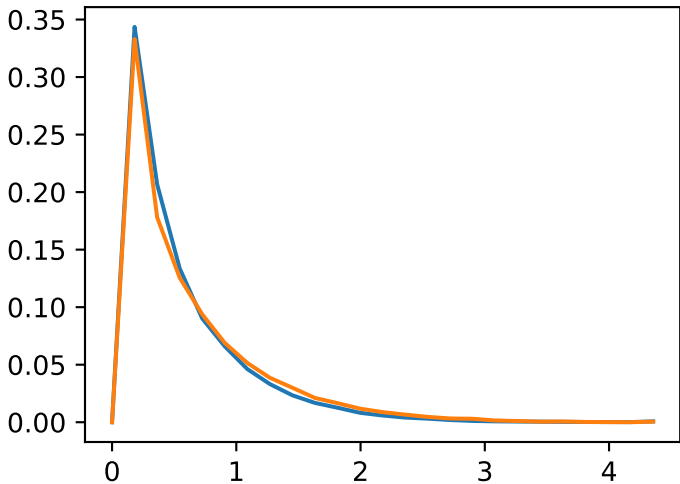




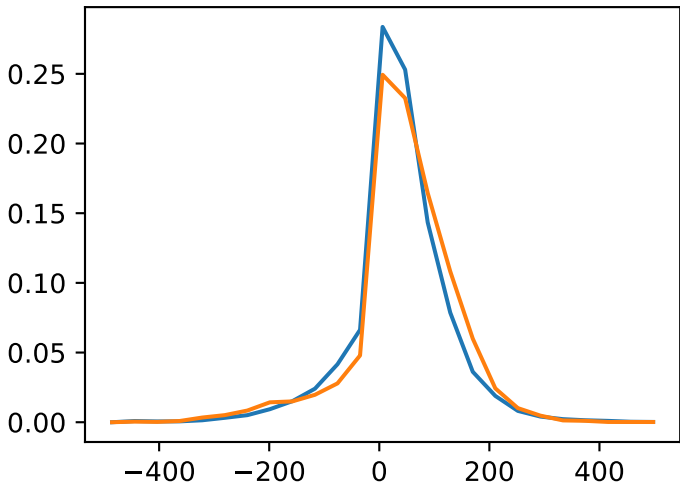
eigen\_projection\_5 | pval:0.4536



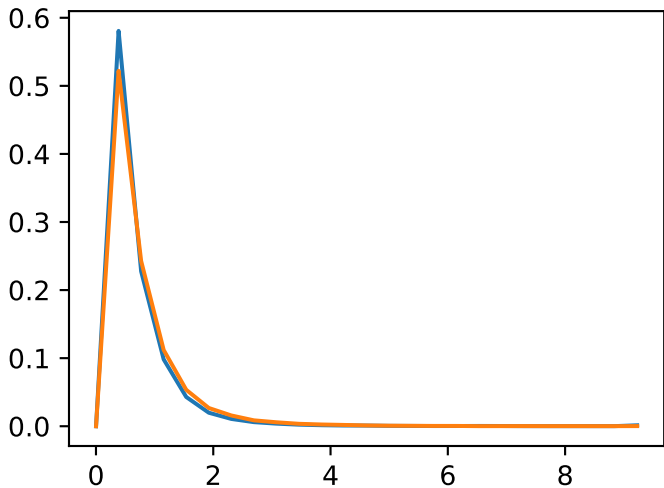
angular\_velocity\_head\_base | pval:0.4557



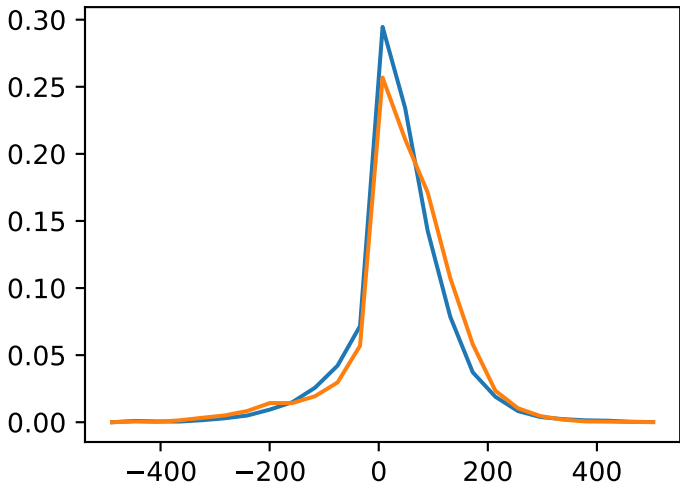
speed\_tail\_base | pval:0.4622



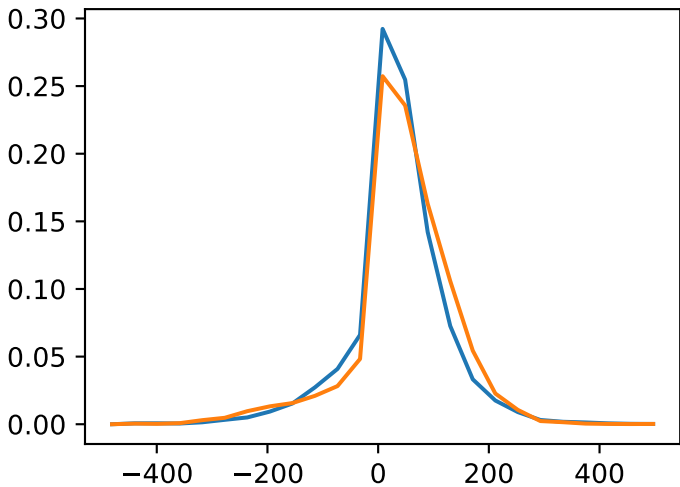
d\_relative\_to\_body\_angular\_velocity\_head\_tip | pval:0.4816



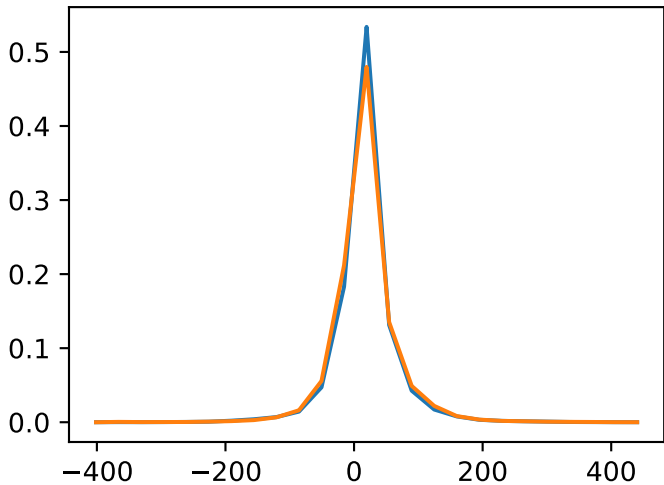
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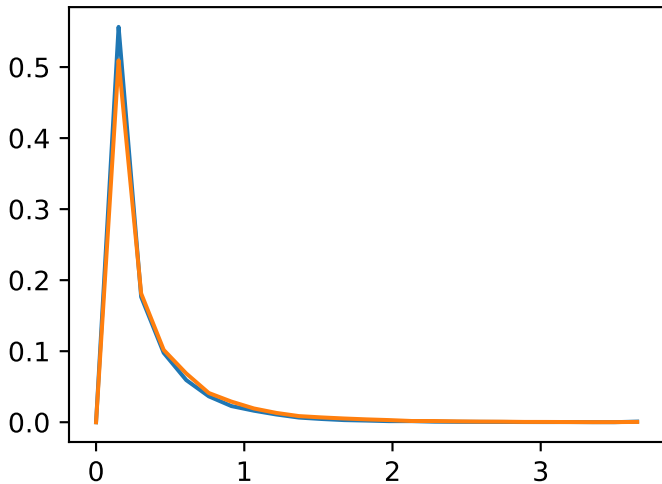
speed\_hips | pval:0.4903



d\_minor\_axis | pval:0.4924

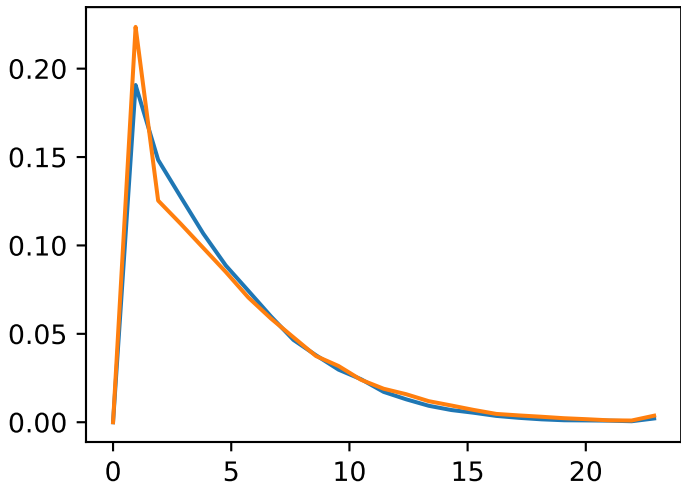


angular\_velocity\_hips | pval:0.4968

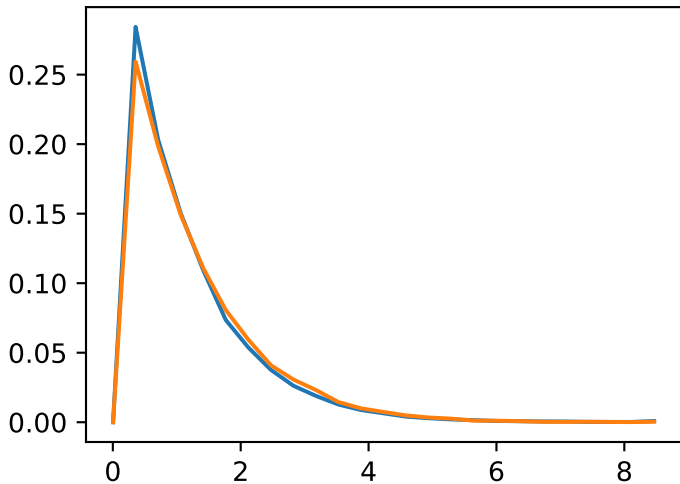




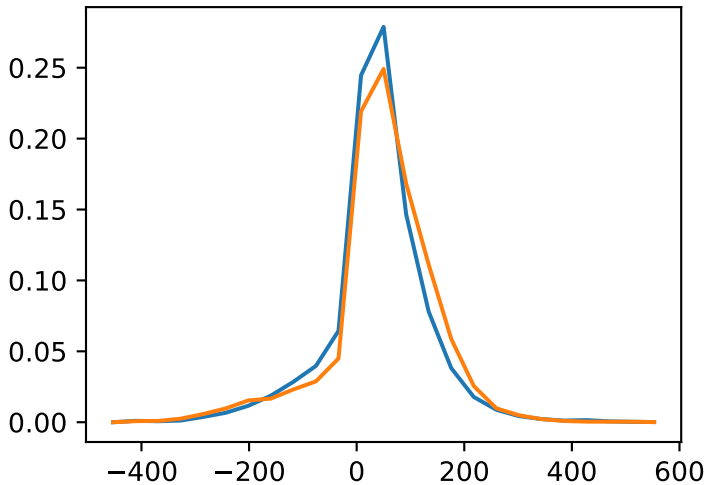
d\_angular\_velocity\_head\_tip | pval:0.5032



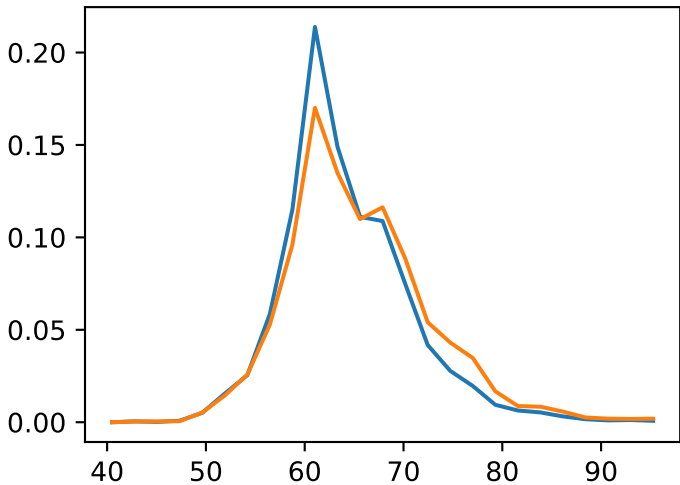
d\_relative\_to\_tail\_base\_angular\_velocity\_tail\_tip | pval:0.5248



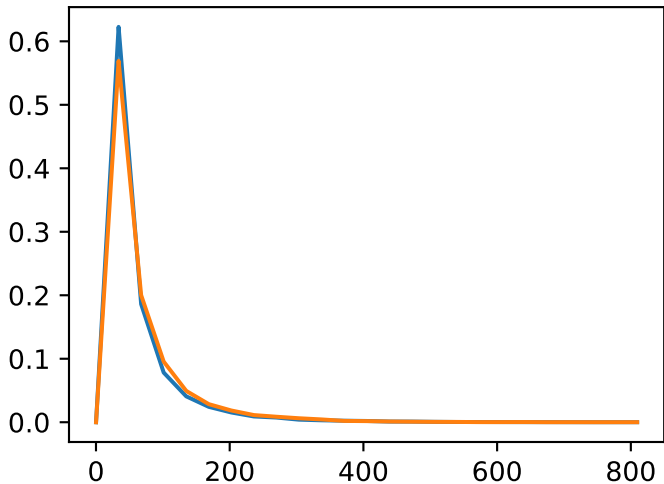
speed\_neck | pval:0.5421



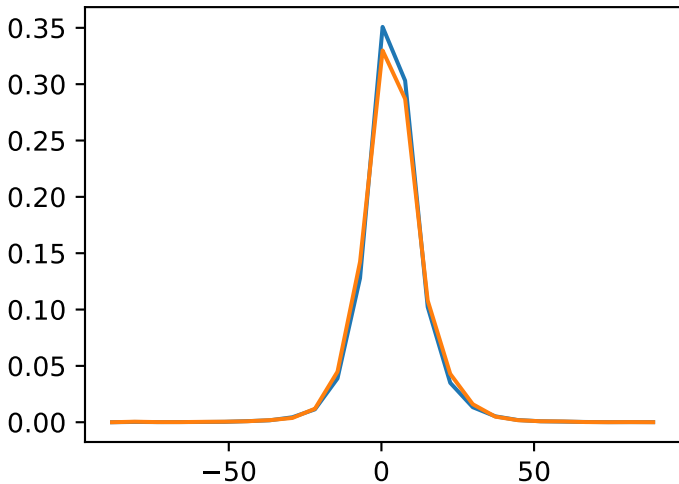
width\_head\_base | pval:0.5529



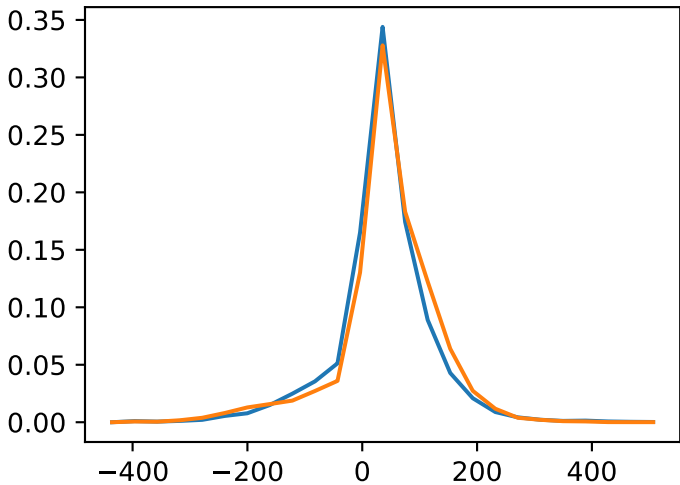
d\_relative\_to\_body\_speed\_midbody | pval:0.5594



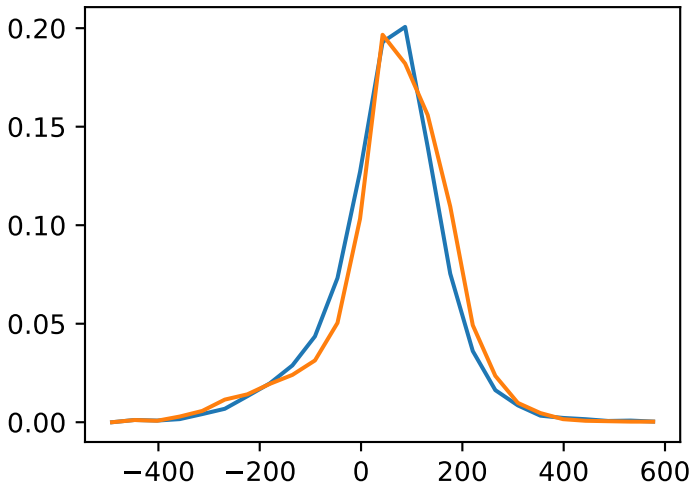
relative\_to\_head\_base\_radial\_velocity\_head\_tip | pval:0.5616



speed\_midbody | pval:0.5637

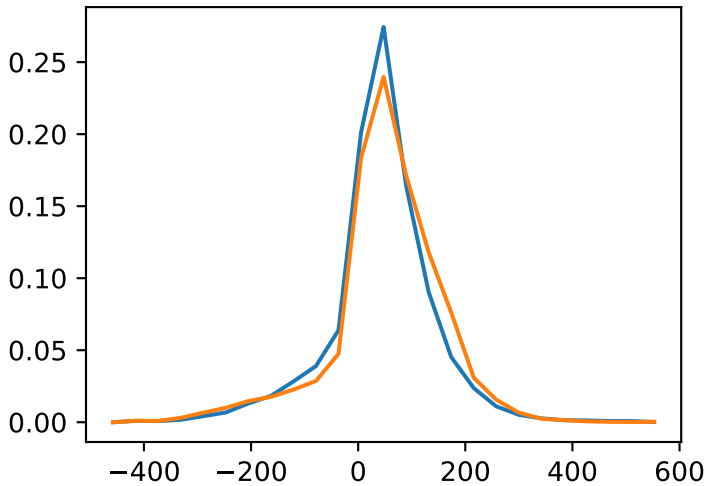


speed\_head\_tip | pval:0.5767

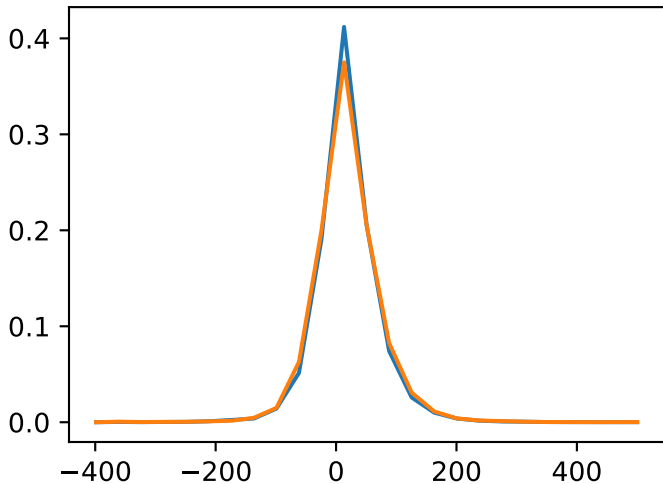




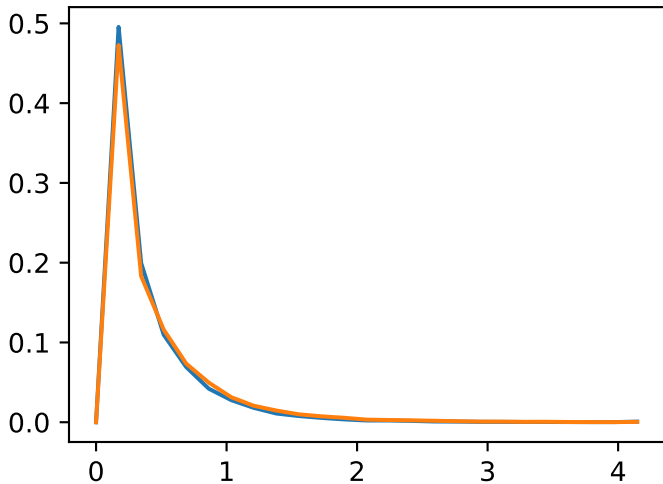
speed\_head\_base | pval:0.5918



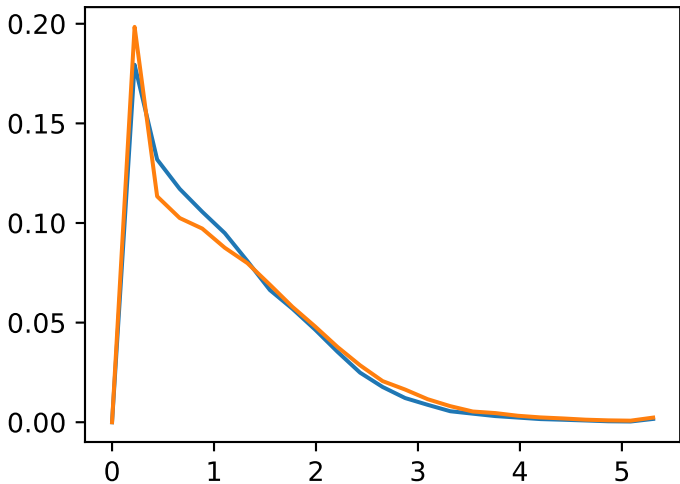
d\_relative\_to\_head\_base\_radial\_velocity\_head\_tip | pval:0.5918



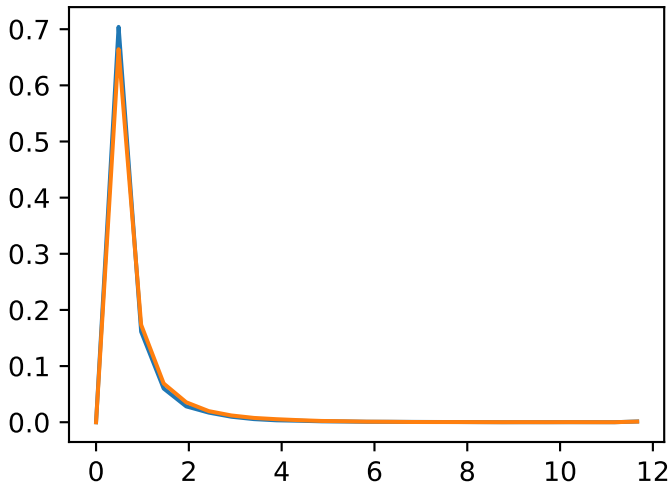
angular\_velocity\_tail\_base | pval:0.6026



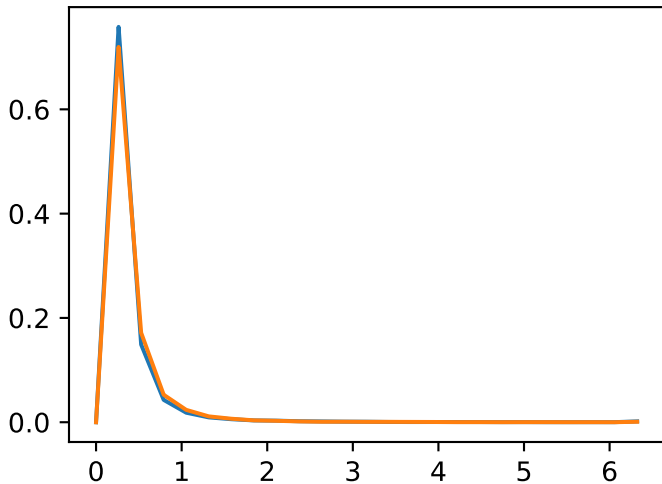
angular\_velocity\_head\_tip | pval:0.6091



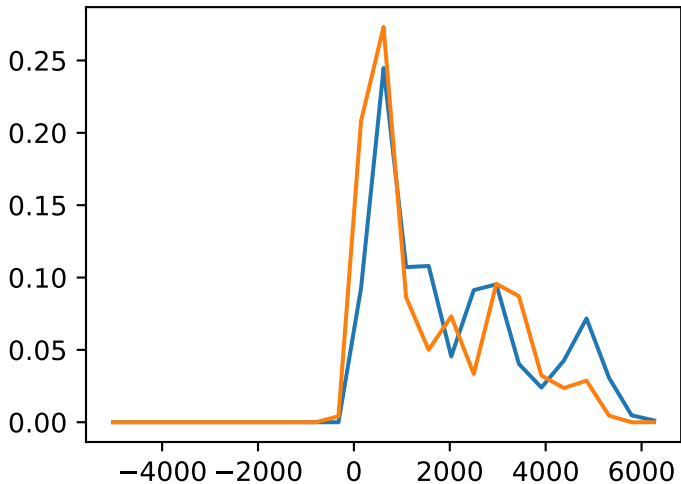
d\_angular\_velocity\_midbody | pval:0.6091



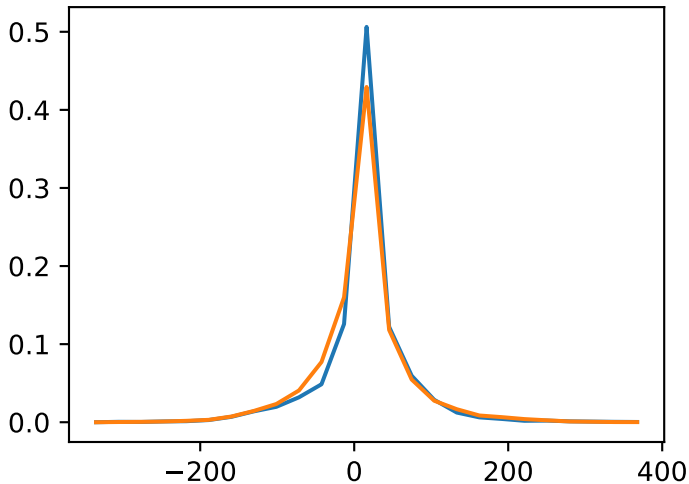
d\_angular\_velocity | pval:0.6263



dist\_from\_food\_edge | pval:0.6285

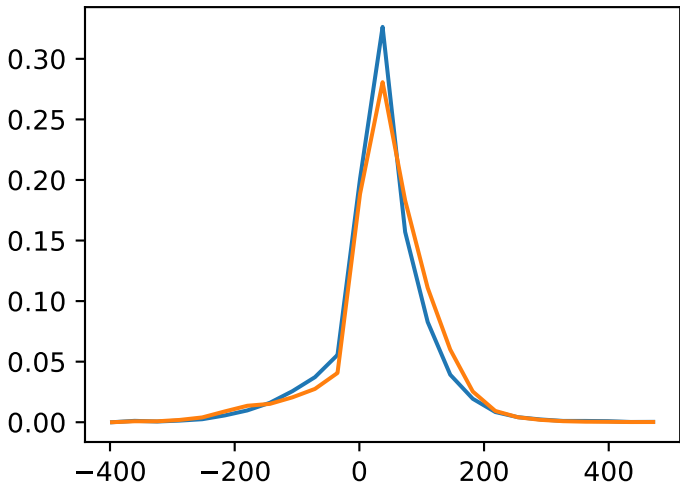


d\_dist\_from\_food\_edge | pval:0.6458

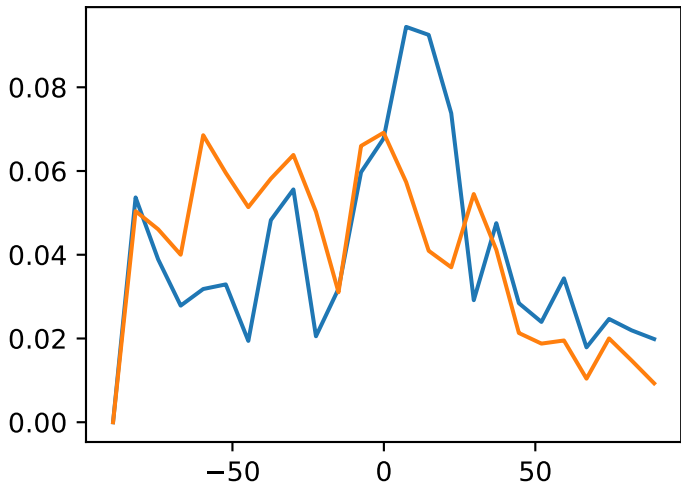




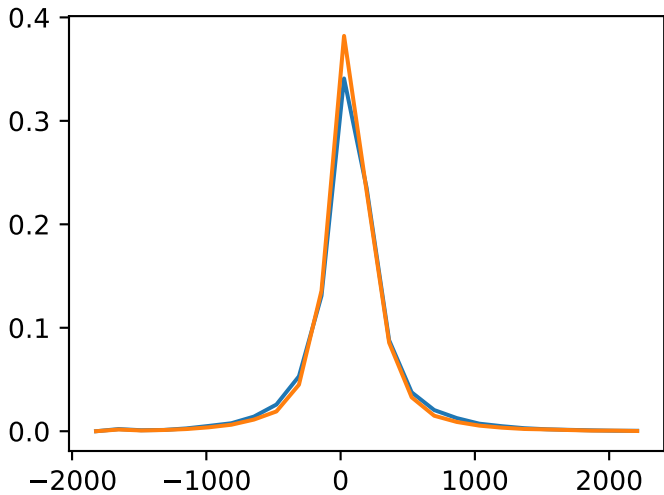
speed | pval:0.6566



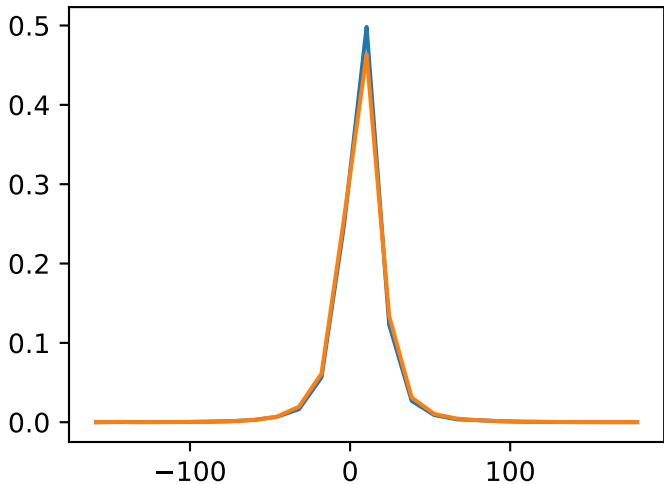
orientation\_food\_edge | pval:0.6587



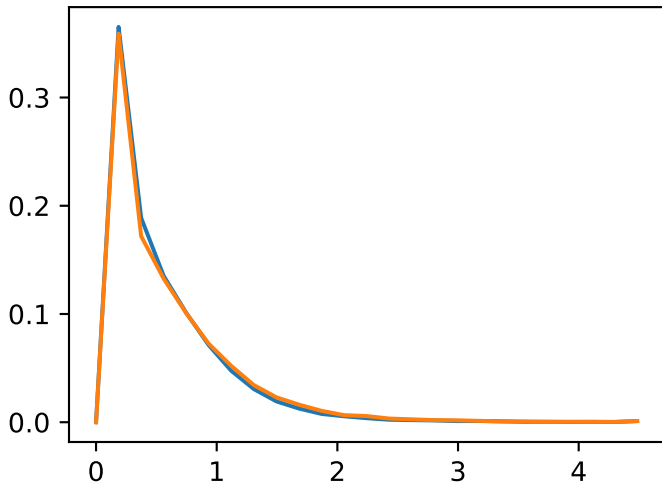
d\_speed\_head\_tip | pval:0.6587



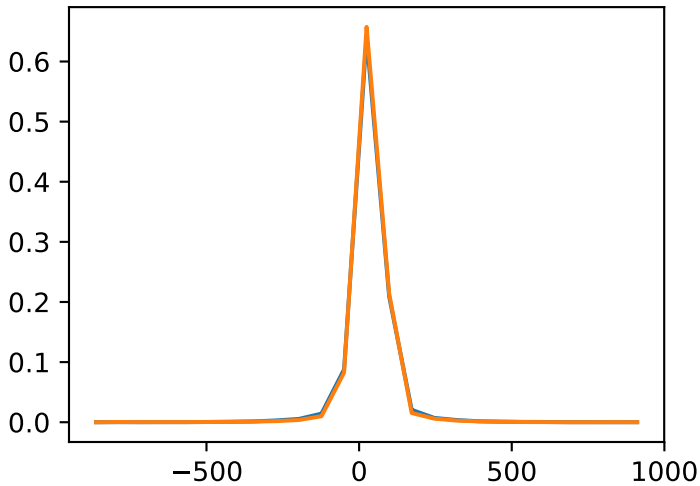
relative\_to\_hips\_radial\_velocity\_tail\_tip | pval:0.6609



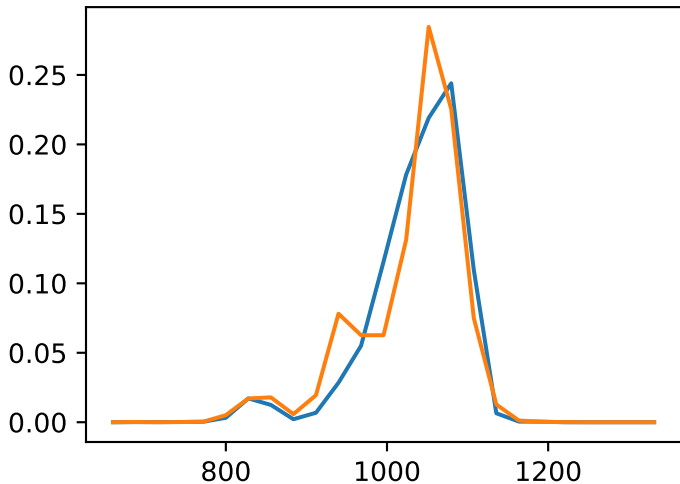
angular\_velocity\_tail\_tip | pval:0.6631



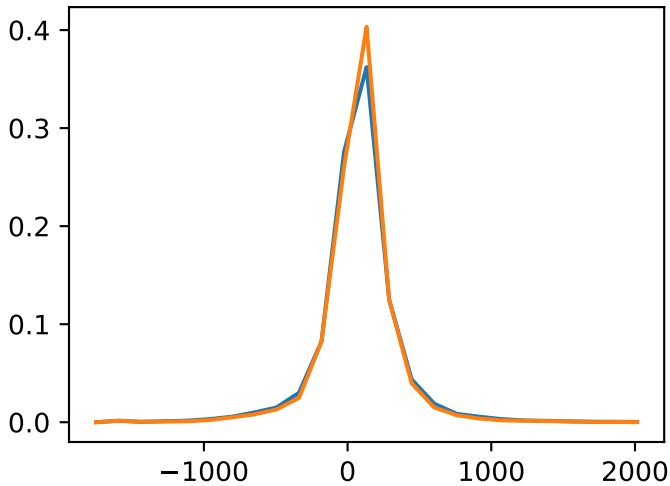
d\_length | pval:0.6955



length | pval:0.7106

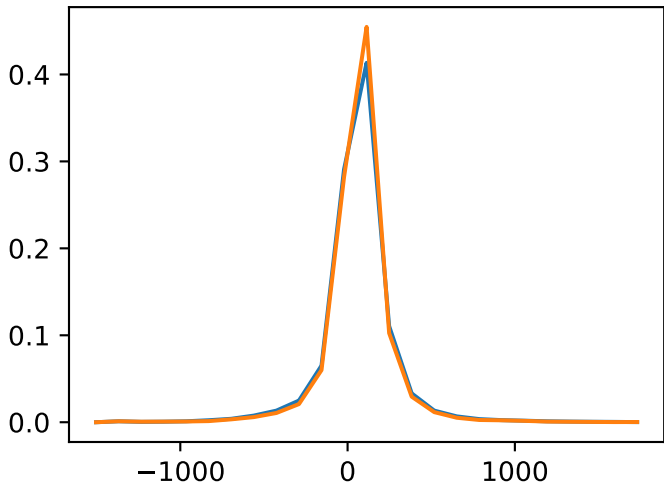


d\_speed\_head\_base | pval:0.7149

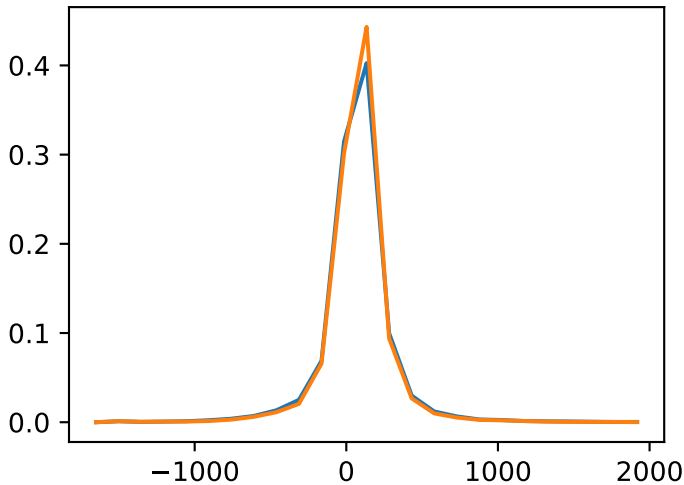




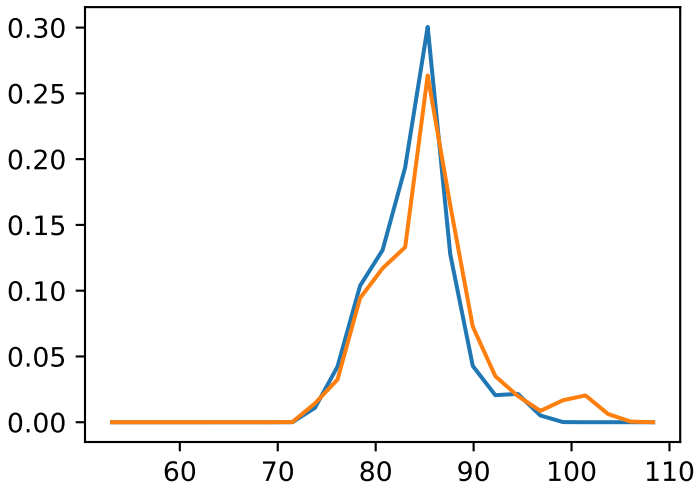
d\_speed | pval:0.7171



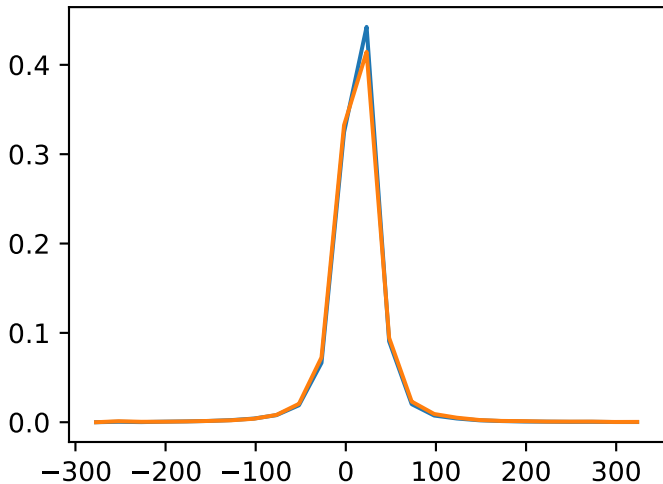
d\_speed\_midbody | pval:0.7257



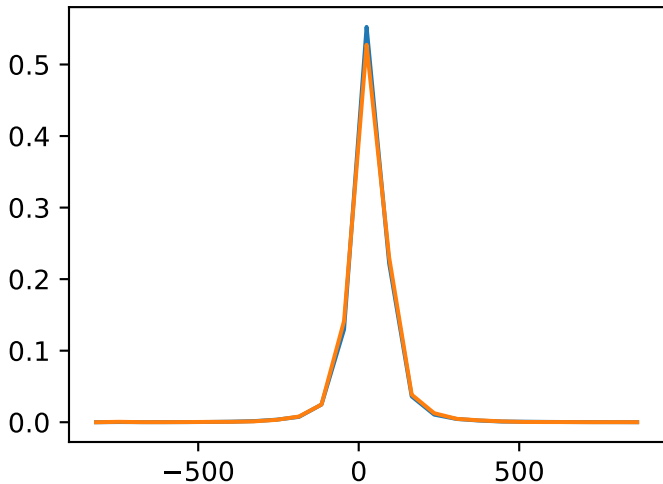
width\_midbody | pval:0.7343



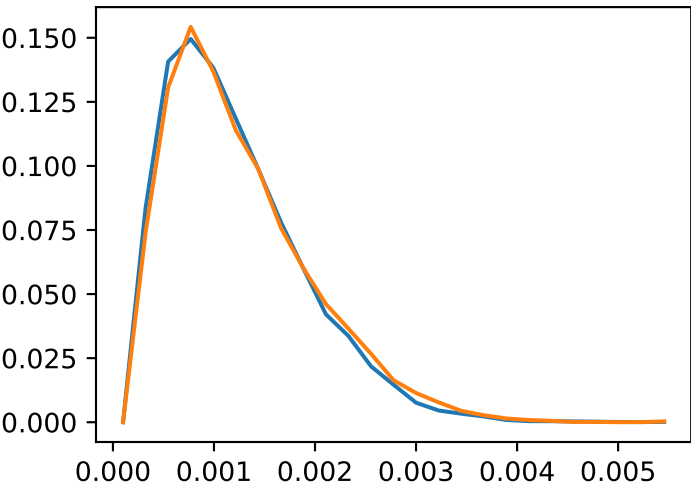
relative\_to\_body\_radial\_velocity\_tail\_tip | pval:0.7473



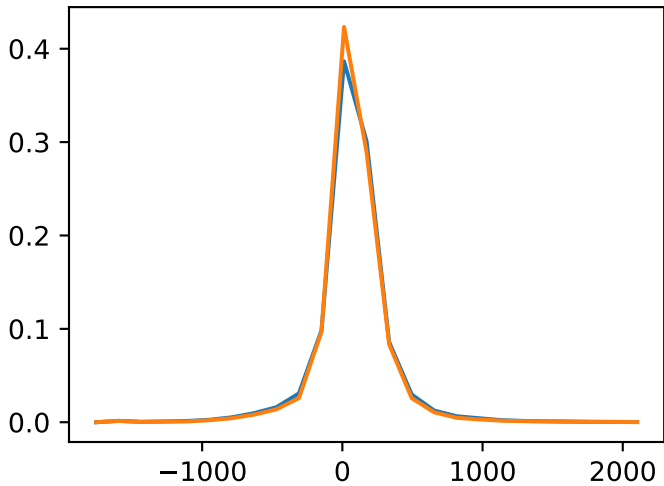
d\_relative\_to\_hips\_radial\_velocity\_tail\_tip | pval:0.7495



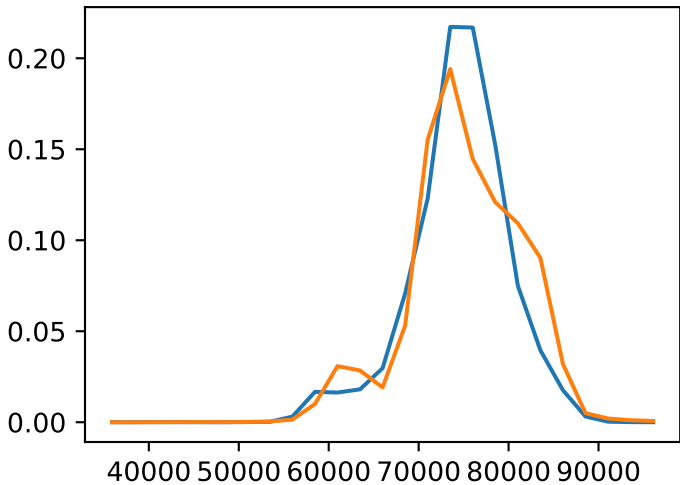
curvature\_std\_tail | pval:0.7538



d\_speed\_neck | pval:0.7689

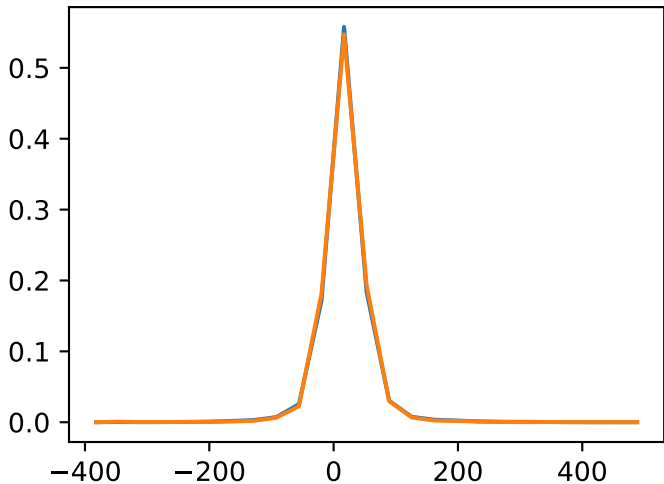


area | pval:0.7775

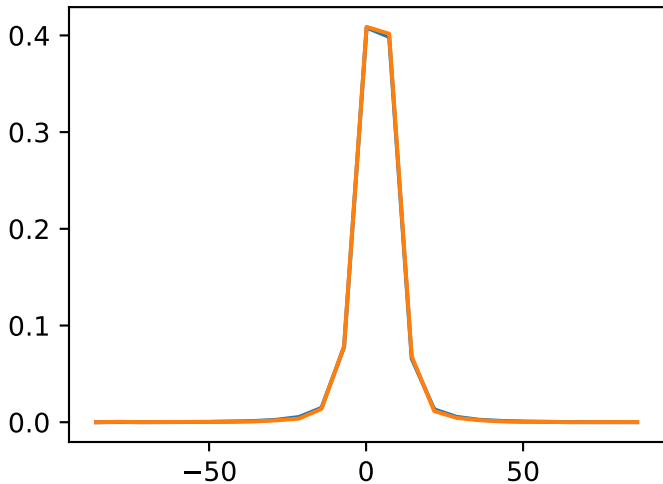




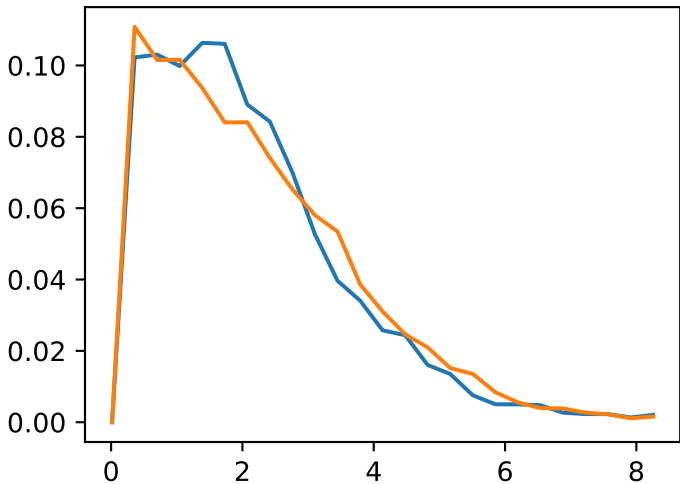
d\_relative\_to\_tail\_base\_radial\_velocity\_tail\_tip | pval:0.7797



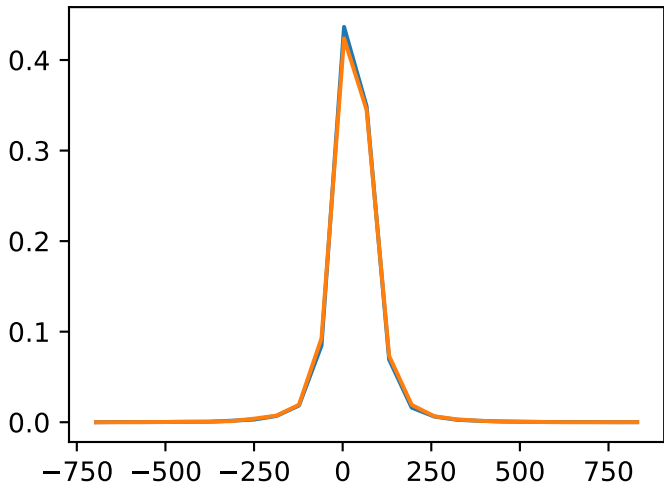
relative\_to\_tail\_base\_radial\_velocity\_tail\_tip | pval:0.7862



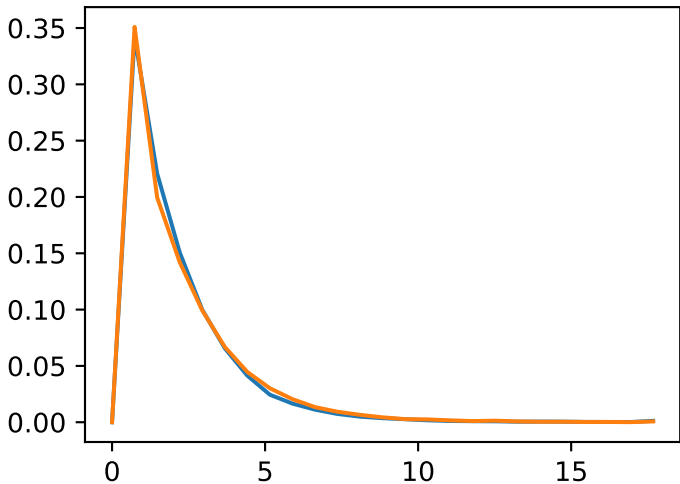
eigen\_projection\_1 | pval:0.7883



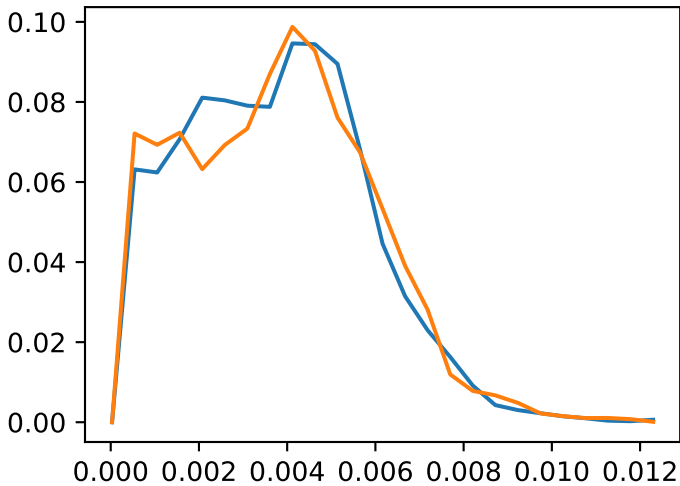
d\_relative\_to\_body\_radial\_velocity\_neck | pval:0.7883



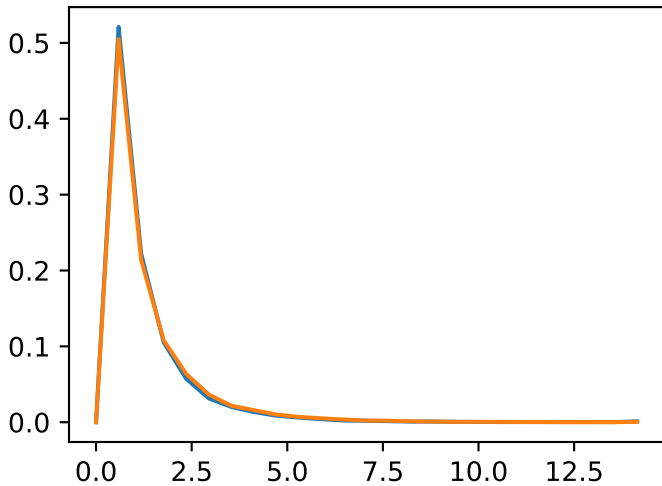
d\_angular\_velocity\_head\_base | pval:0.8035



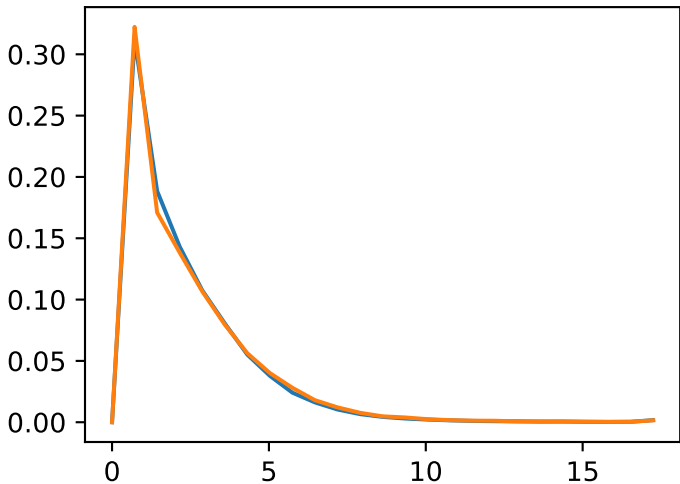
curvature\_mean\_hips | pval:0.8056



d\_angular\_velocity\_neck | pval:0.8229

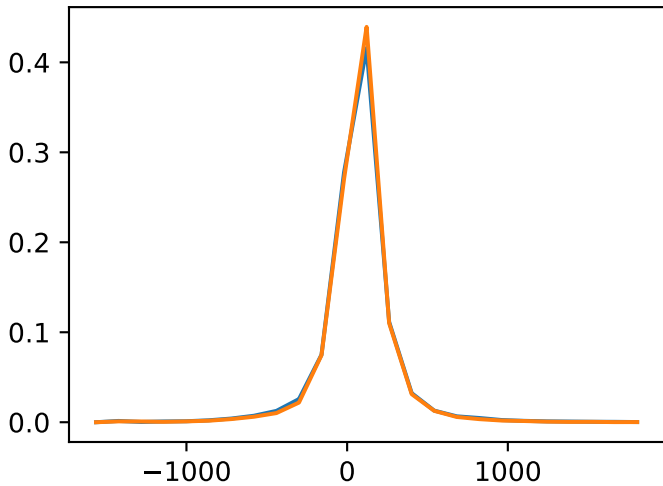


d\_angular\_velocity\_tail\_tip | pval:0.8575

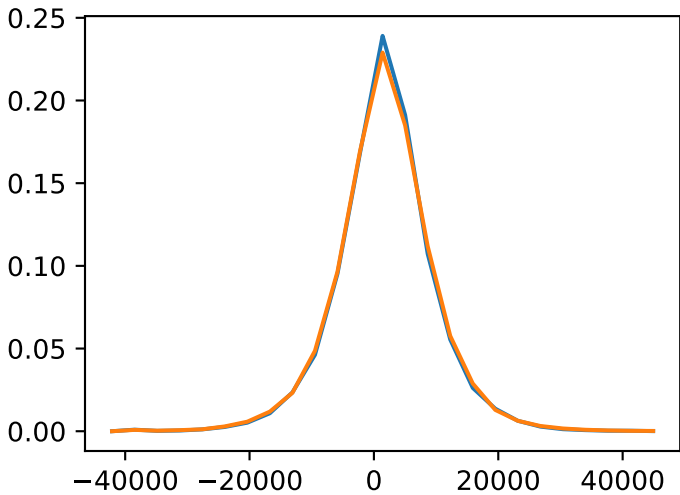




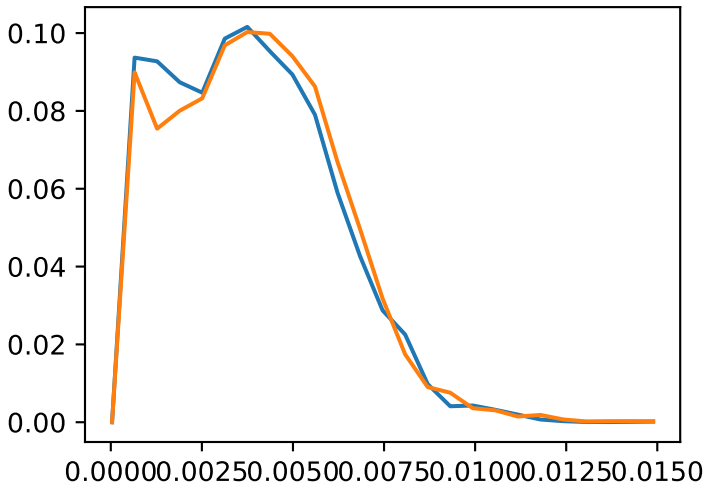
d\_speed\_tail\_base | pval:0.8596



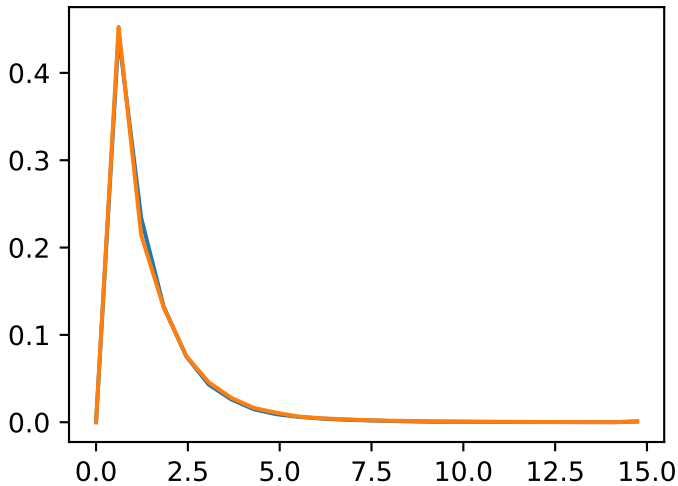
d\_area | pval:0.8726



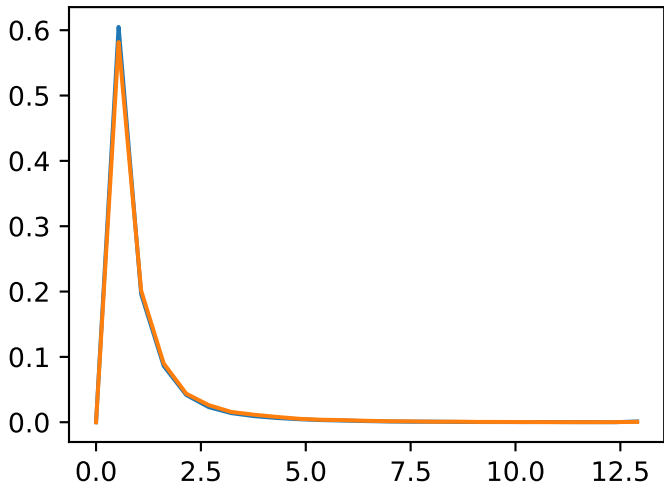
curvature\_mean\_tail | pval:0.8834



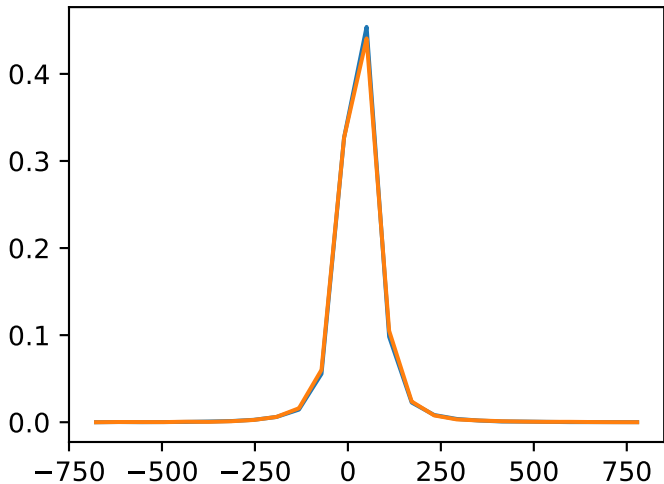
d\_angular\_velocity\_tail\_base | pval:0.8834



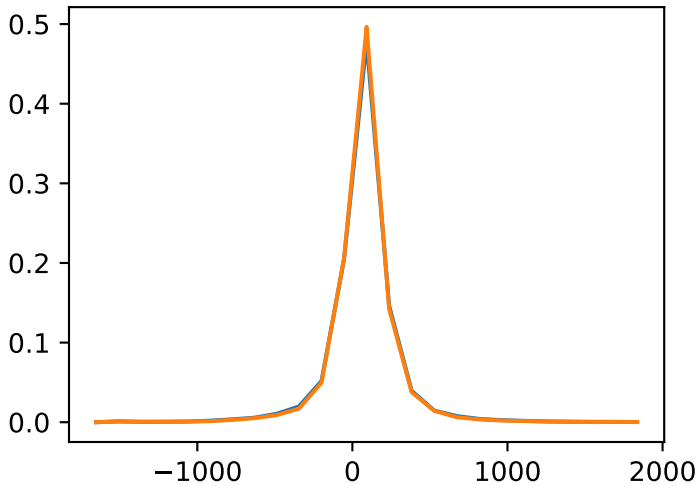
d\_angular\_velocity\_hips | pval:0.8942



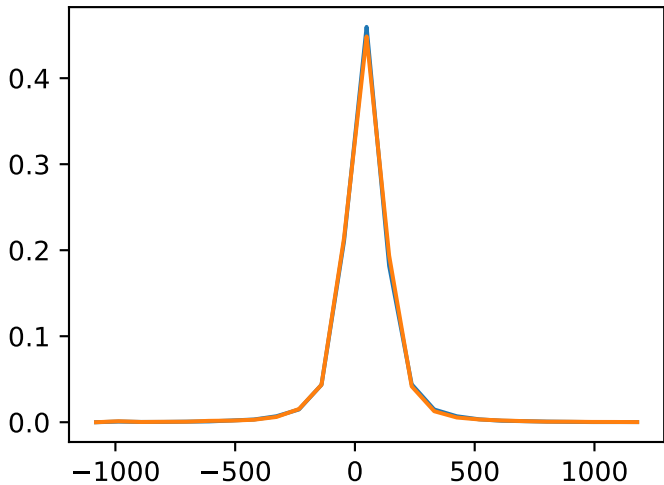
d\_relative\_to\_body\_radial\_velocity\_hips | pval:0.8963



d\_speed\_hips | pval:0.9028

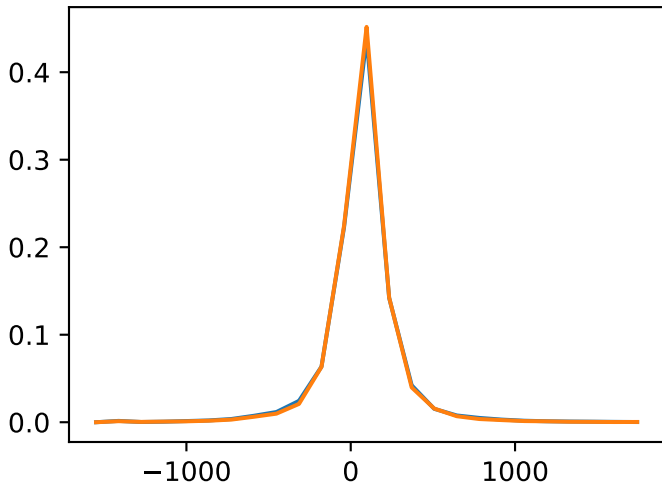


d\_relative\_to\_body\_radial\_velocity\_tail\_tip | pval:0.9158





d\_speed\_tail\_tip | pval:0.9222



curvature\_tail | pval:0.9546

