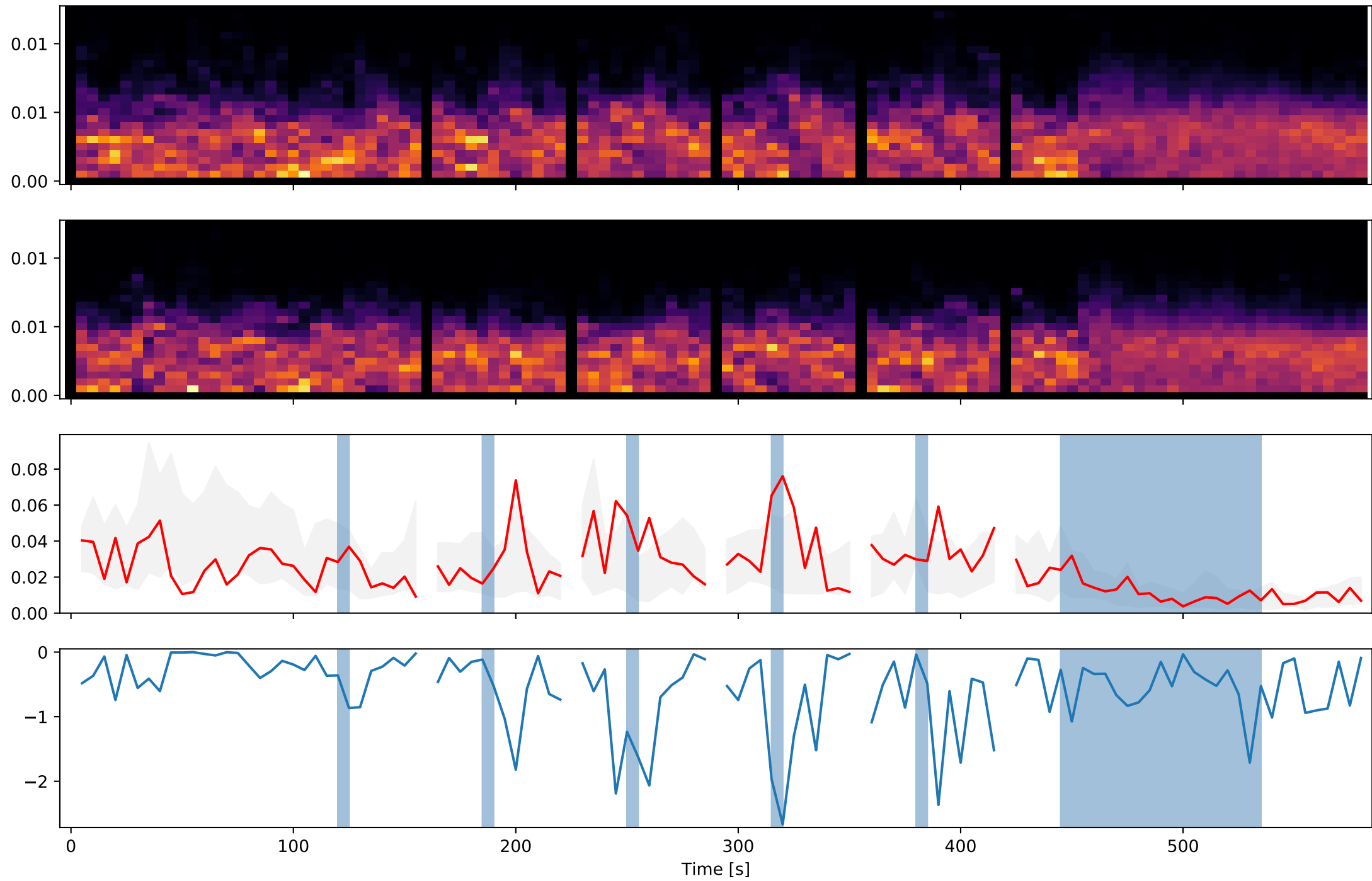
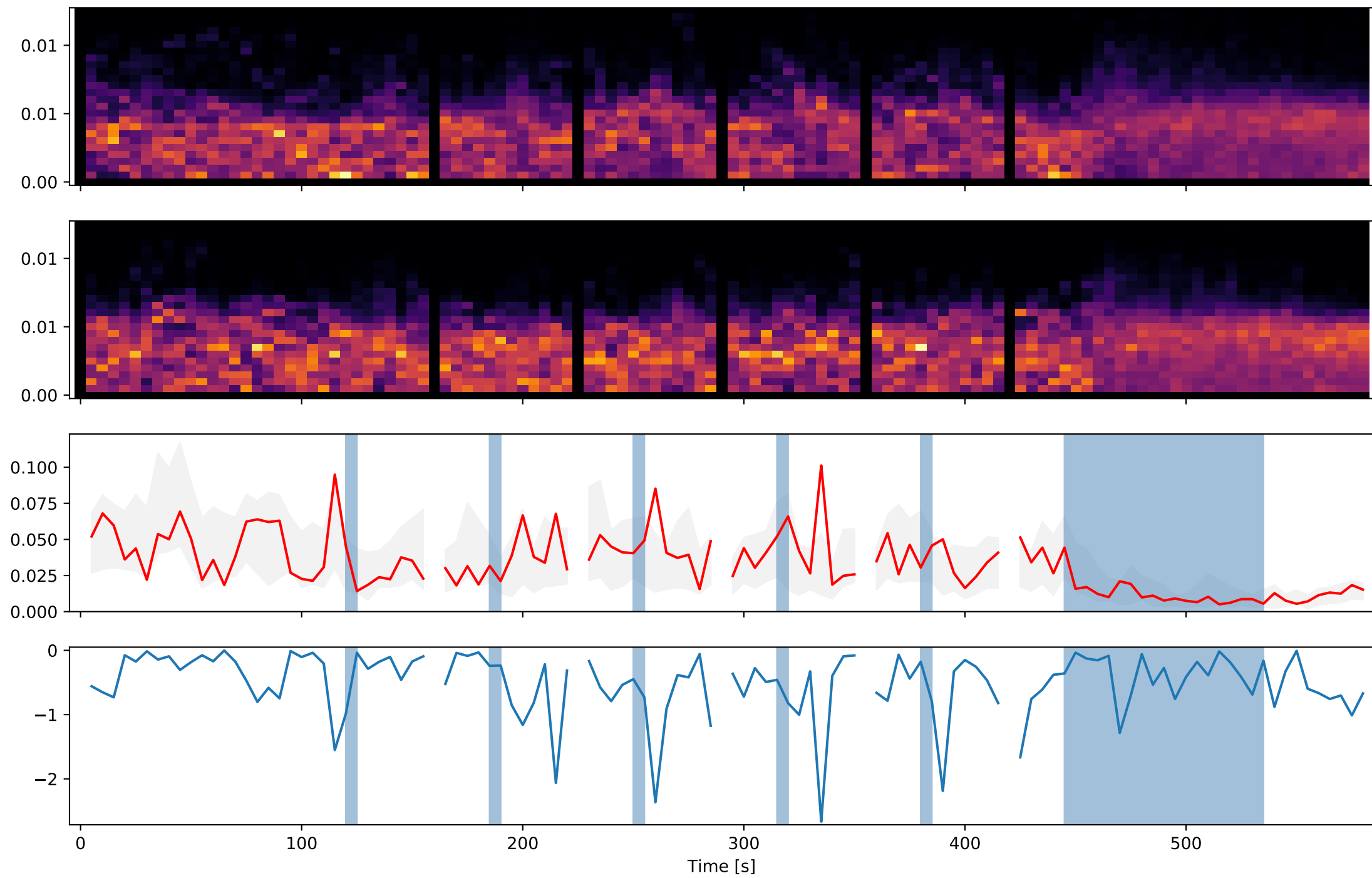


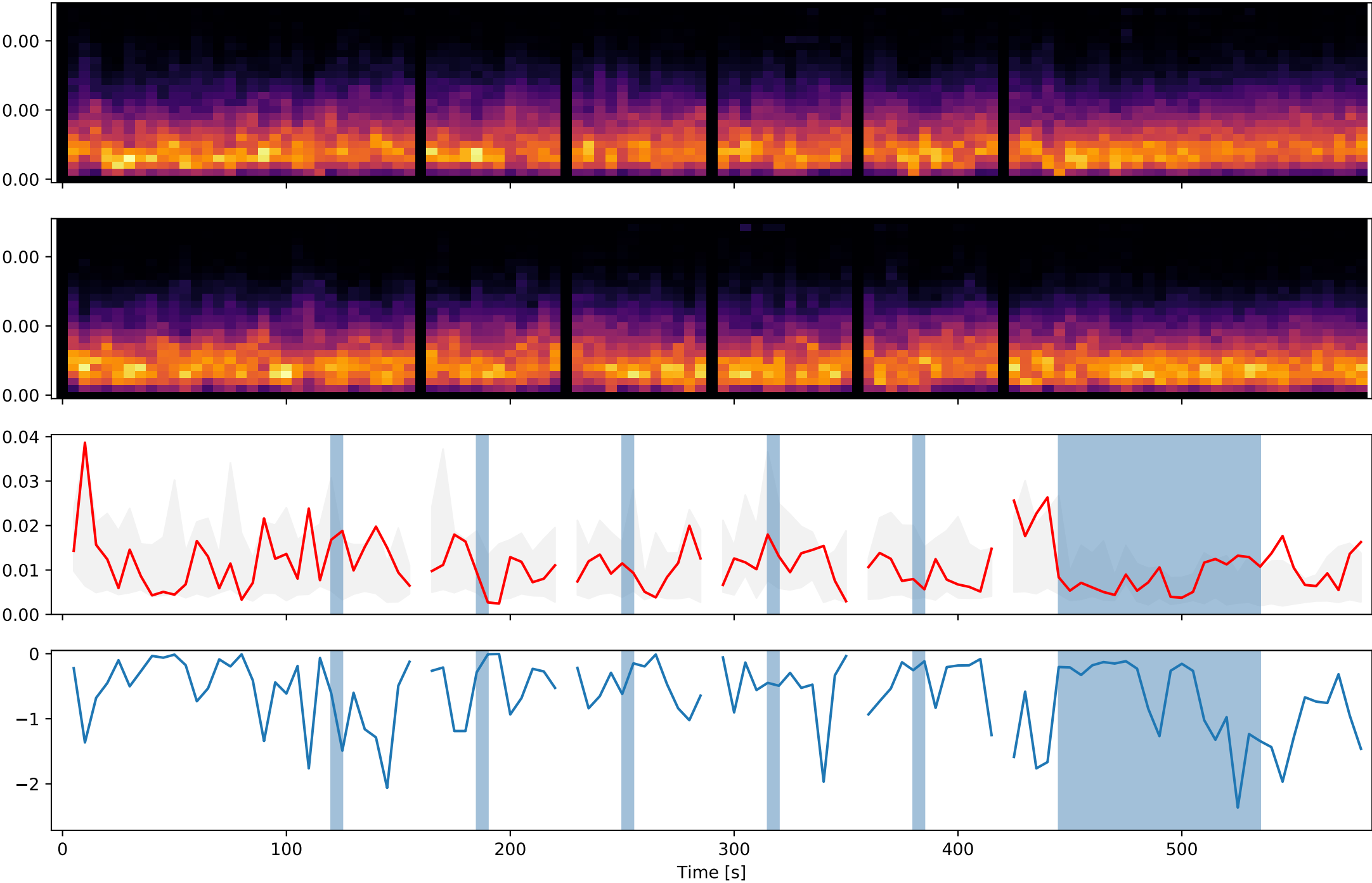
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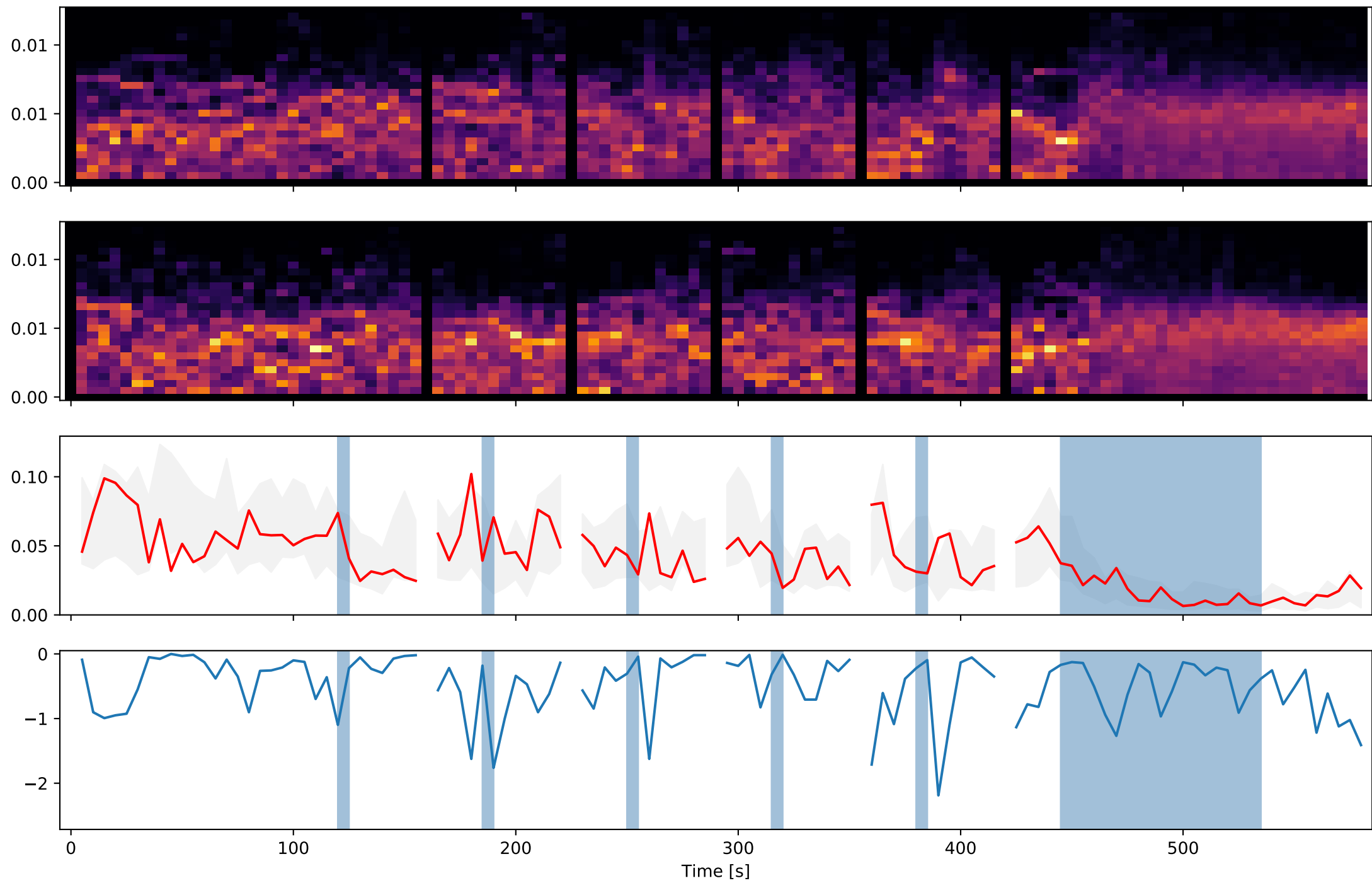
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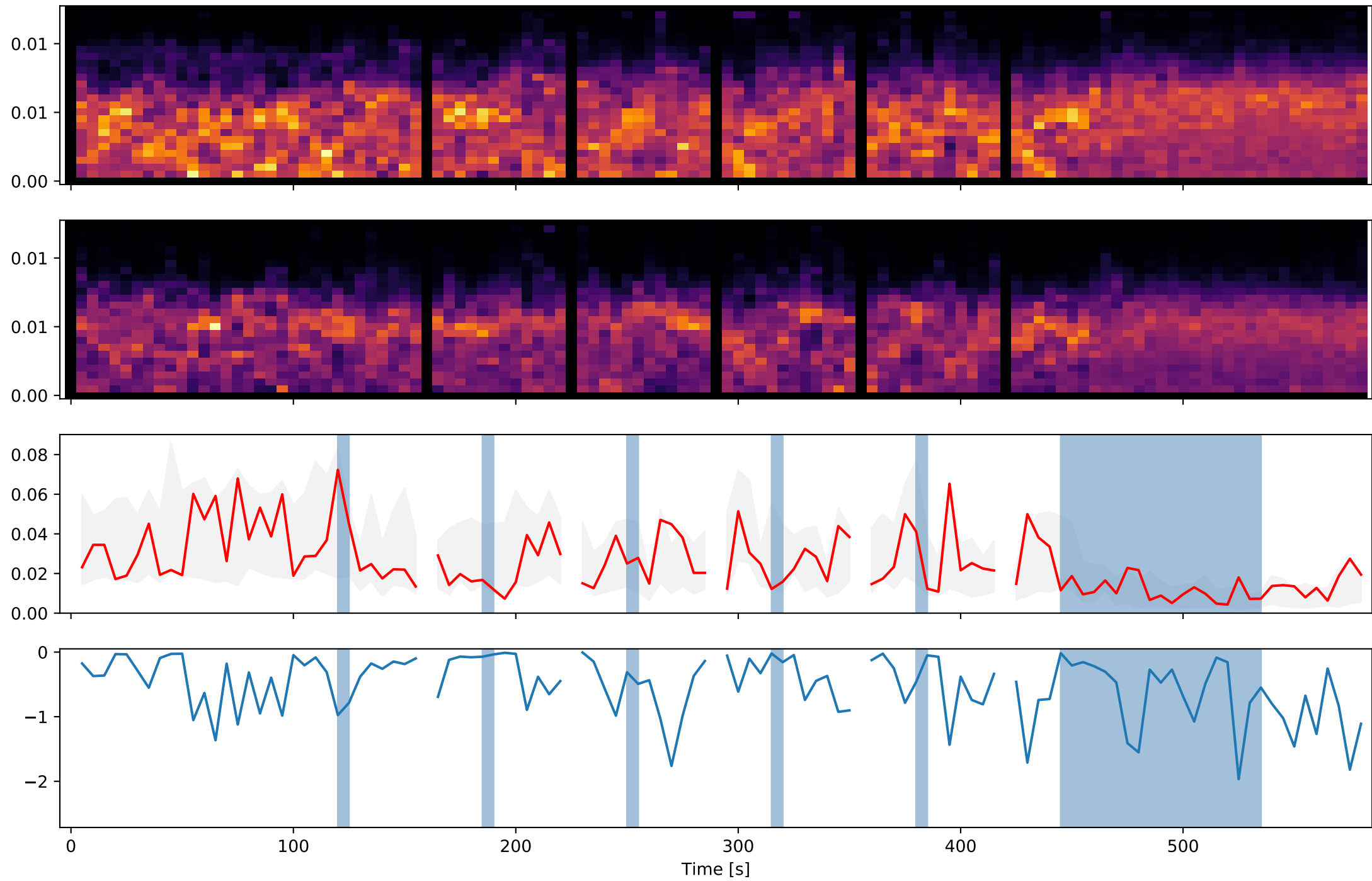
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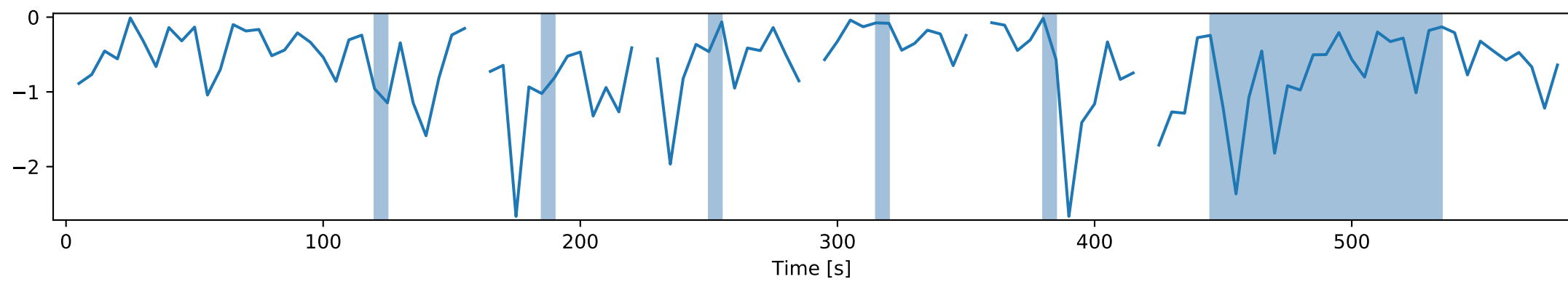
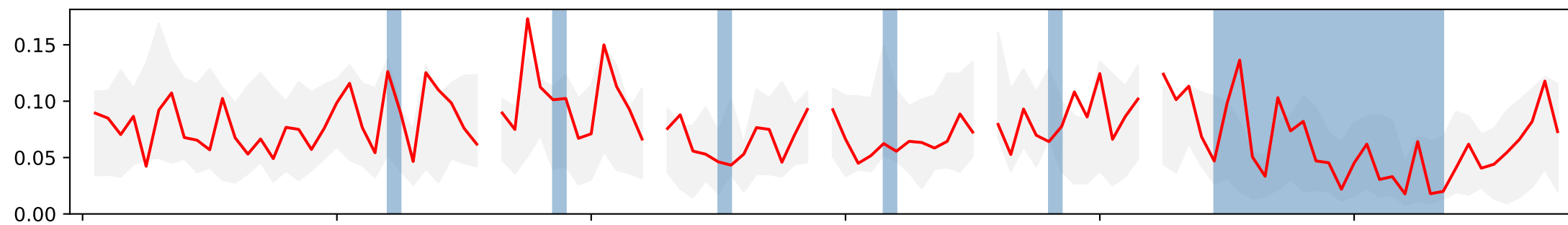
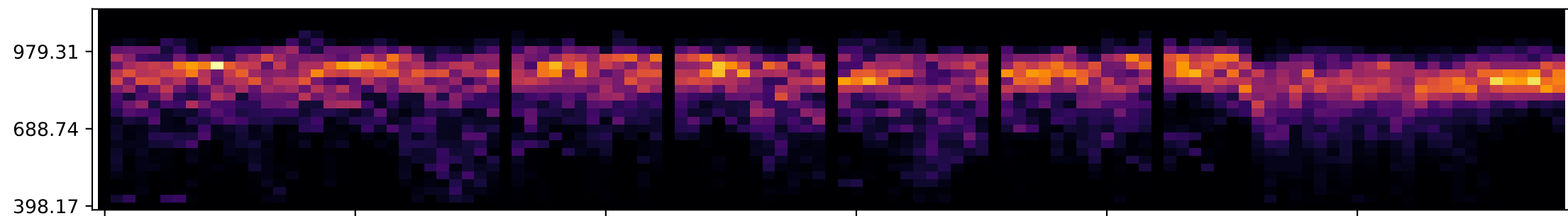
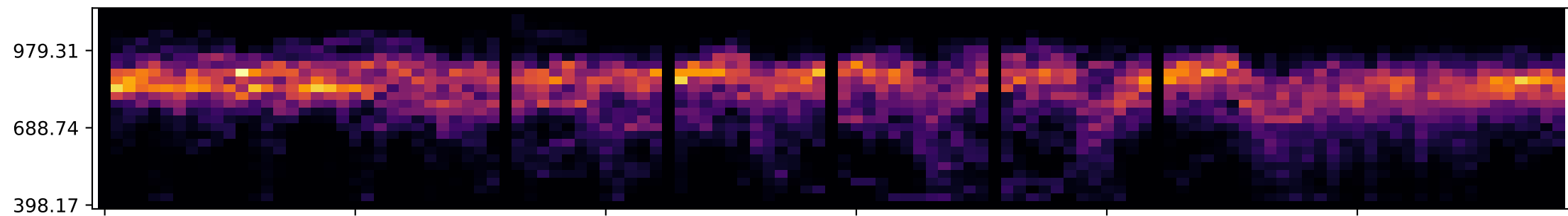
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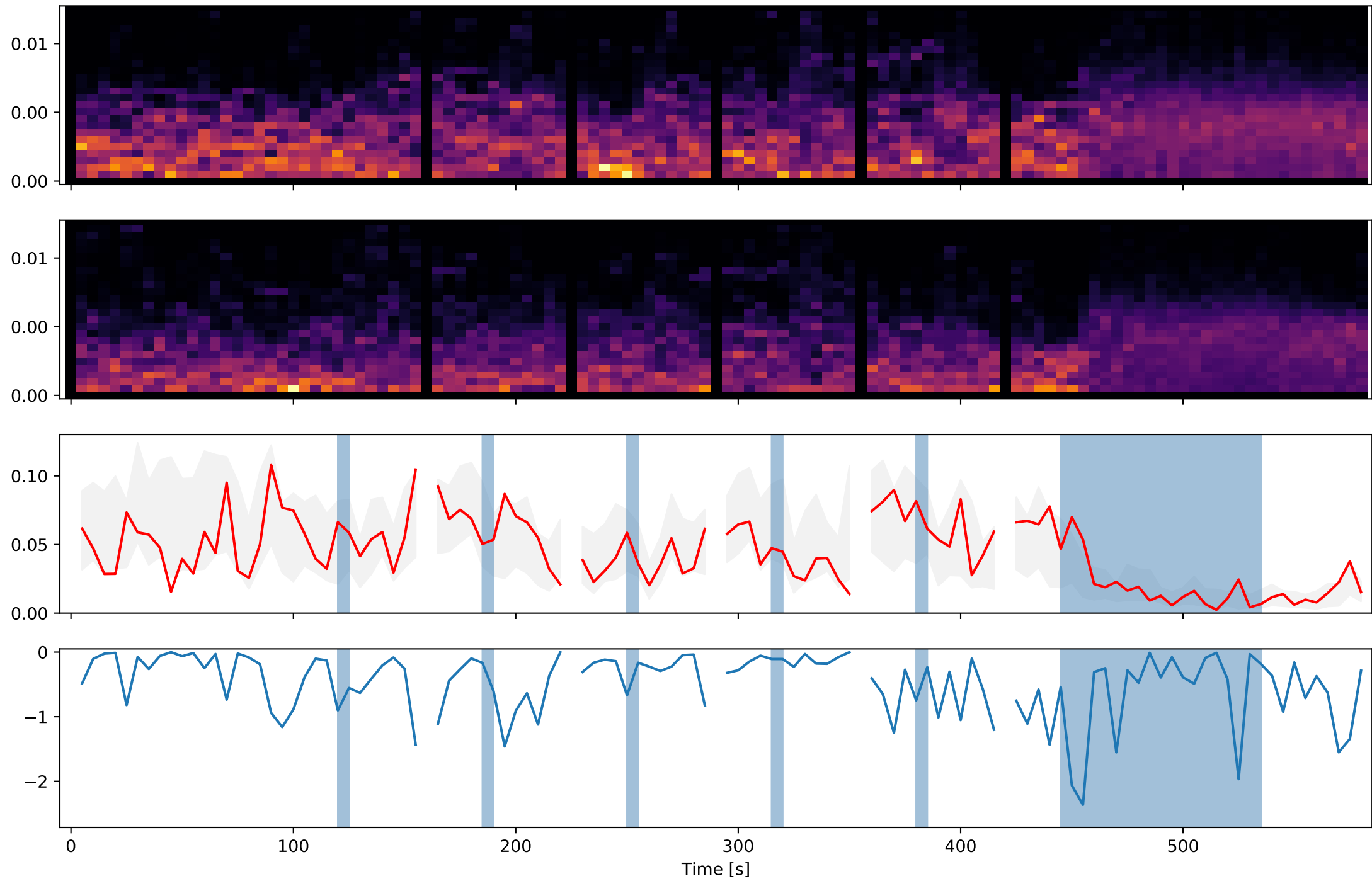
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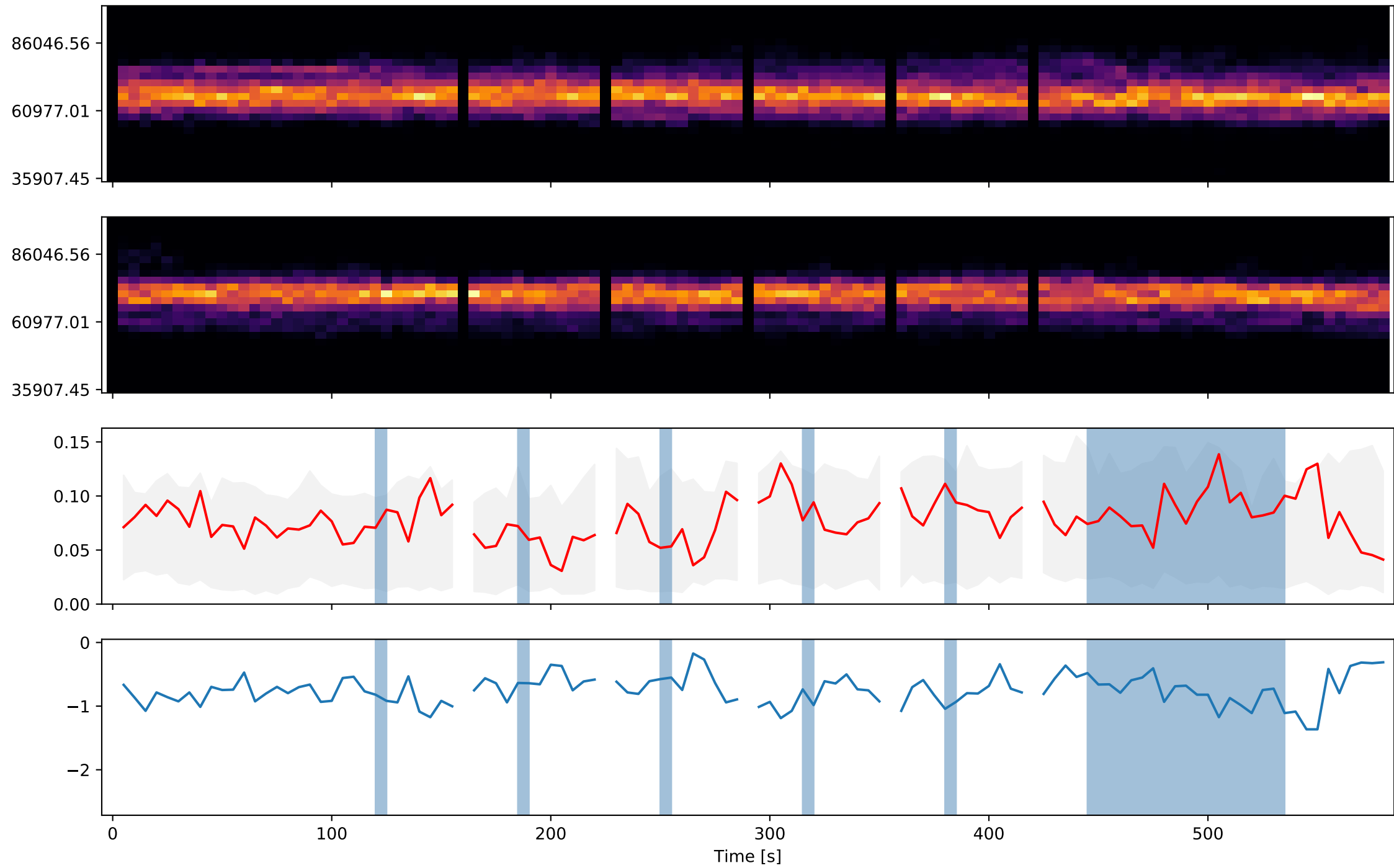
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curvature\_mean\_midbody - pval: 0.13606911447084233

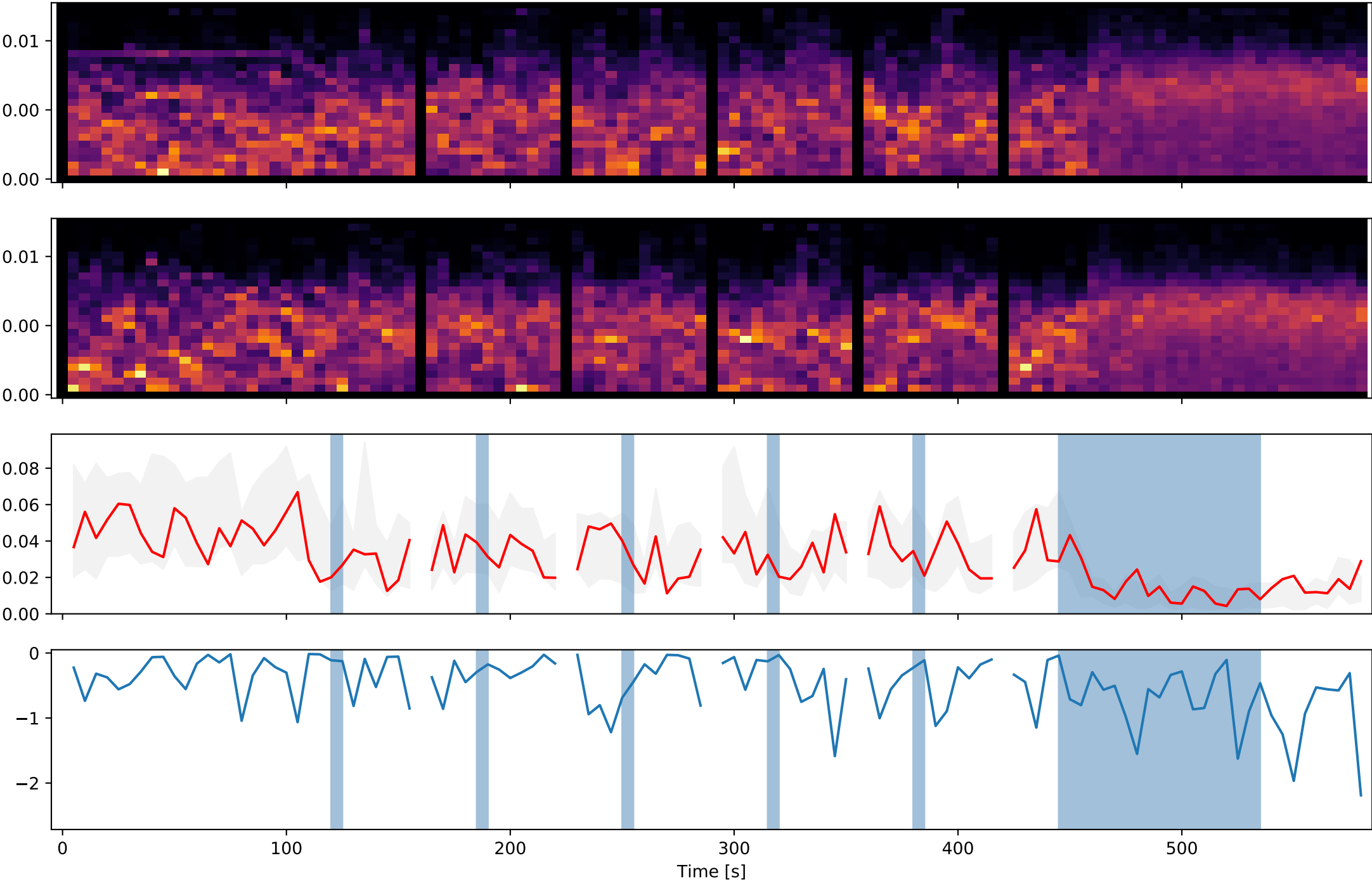


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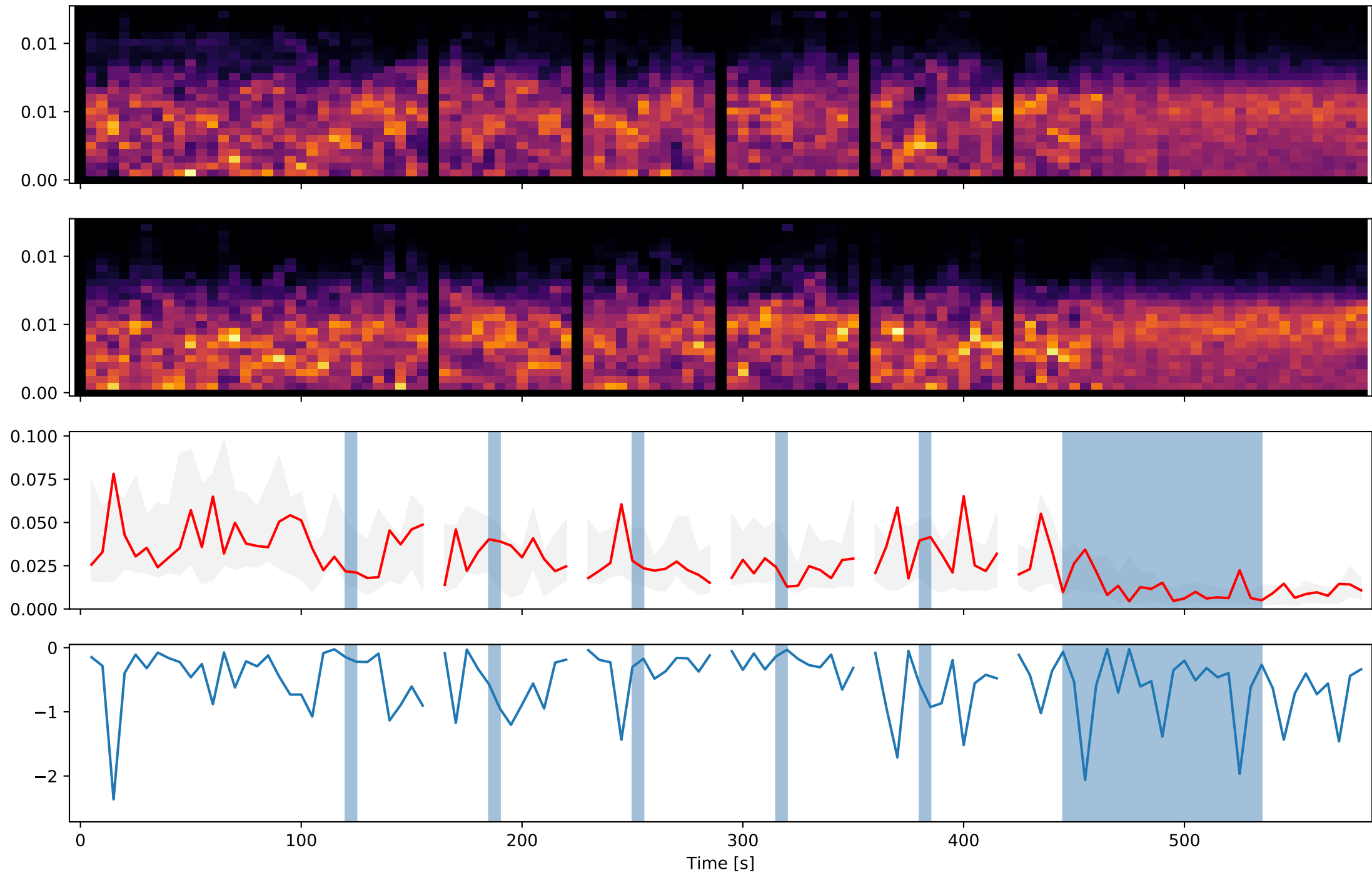




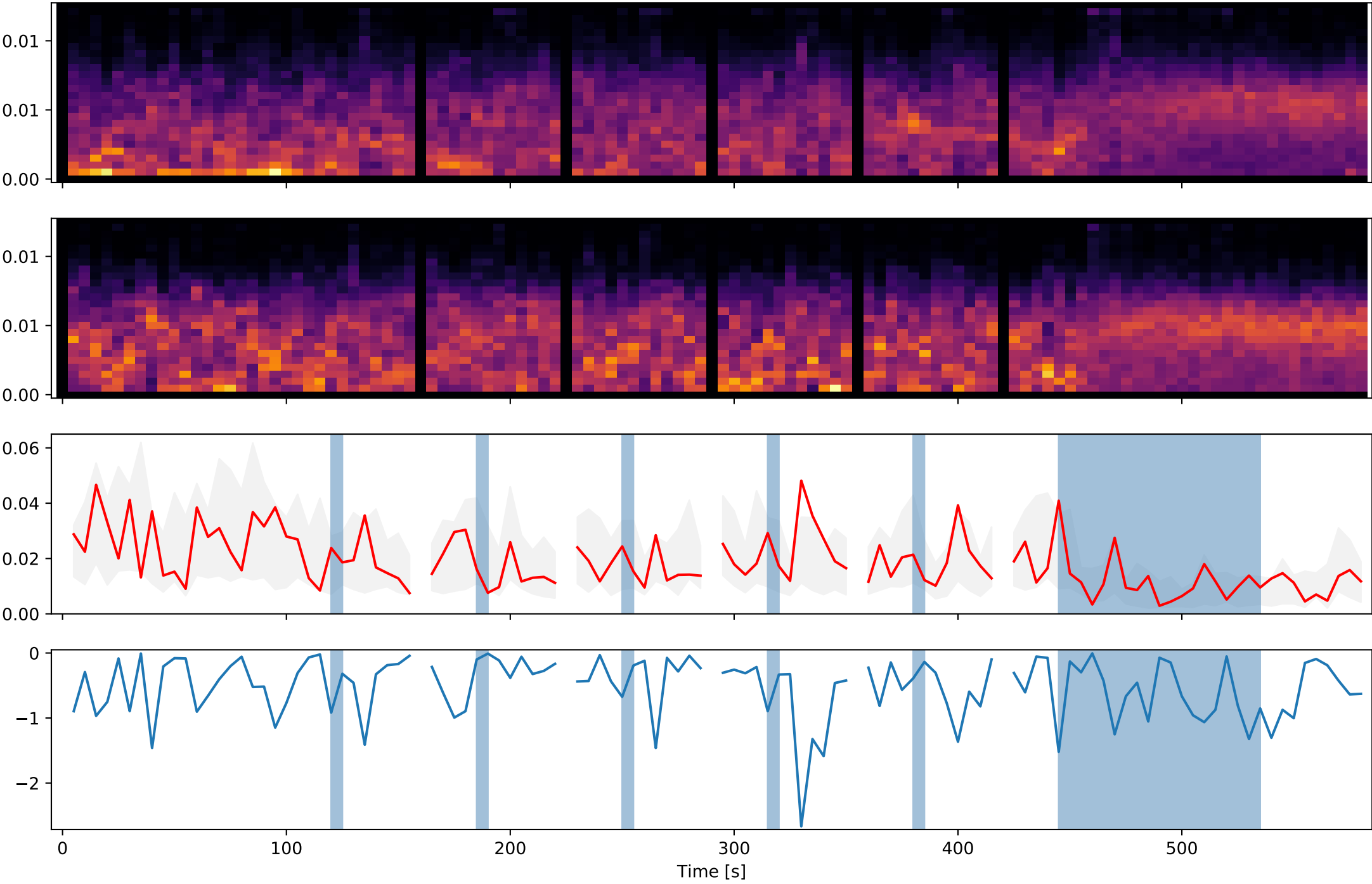
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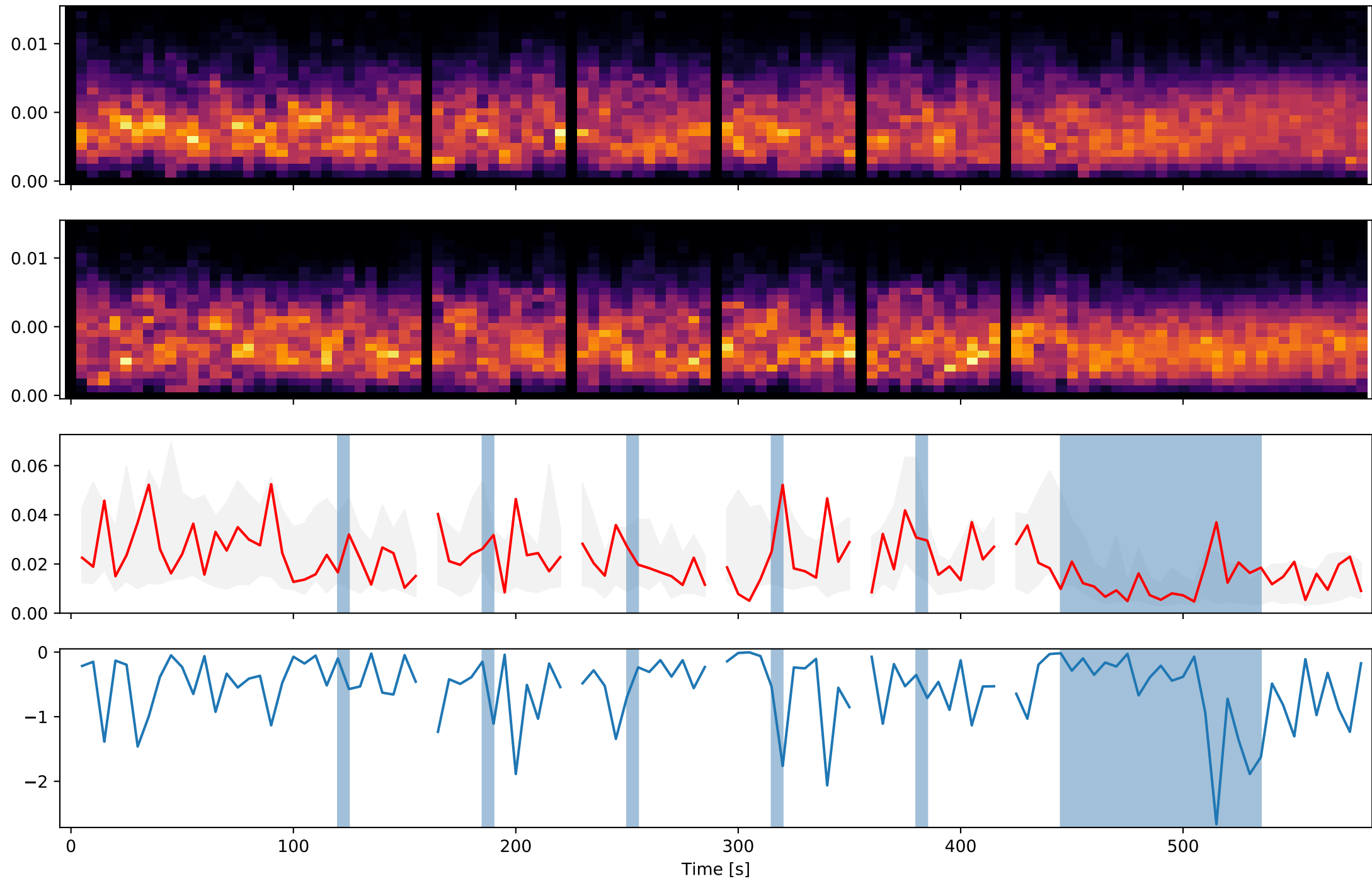
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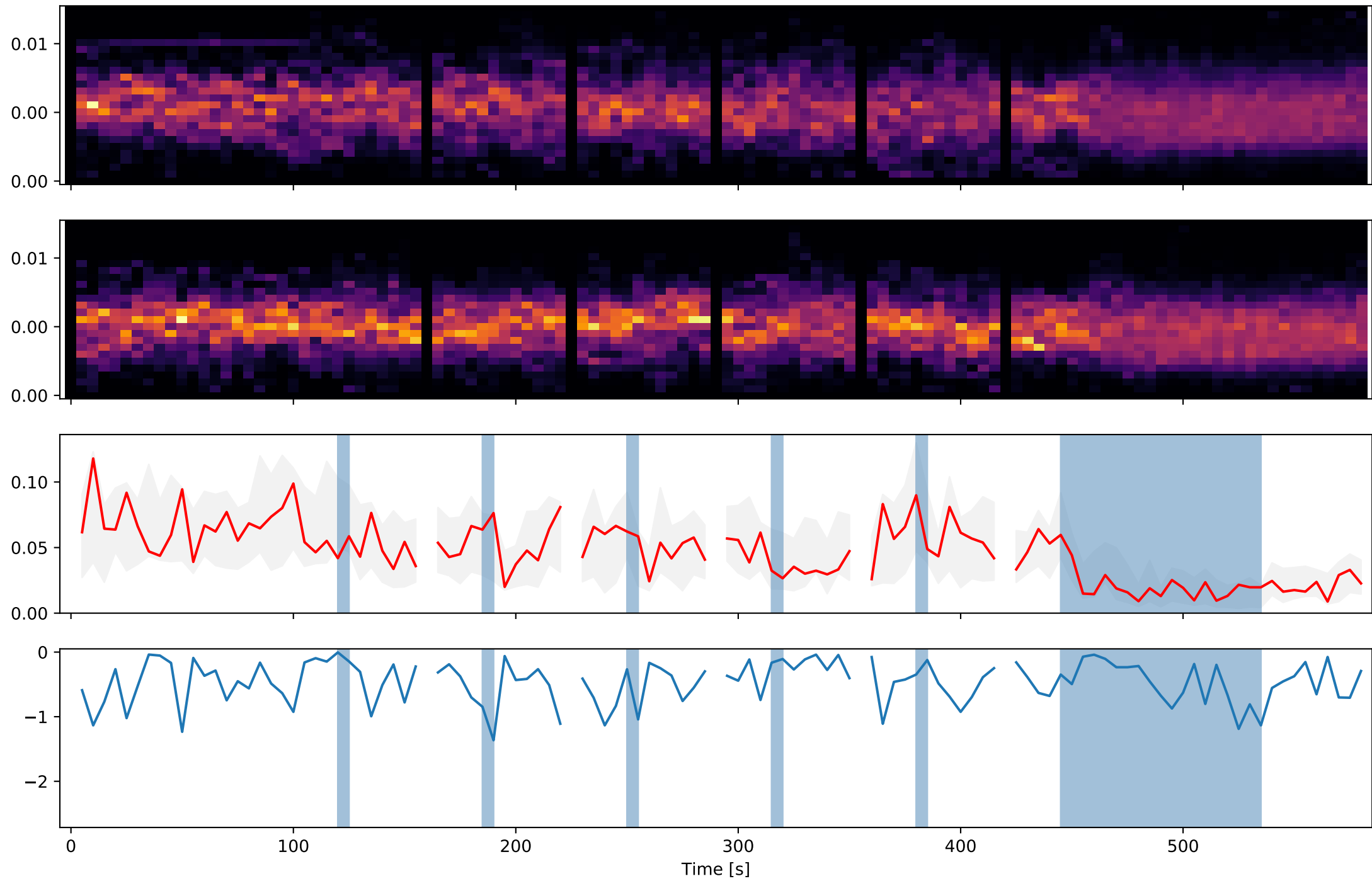
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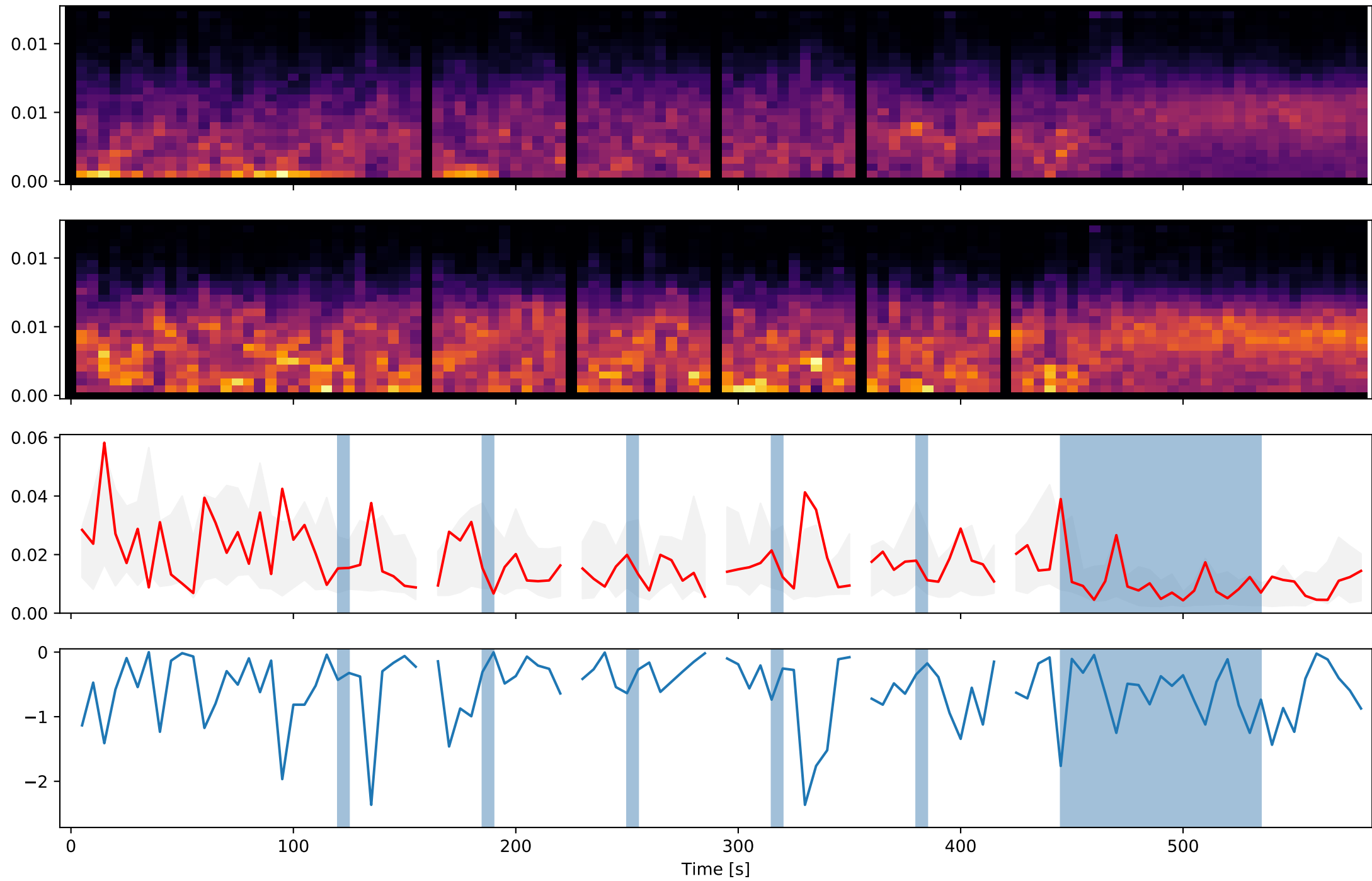
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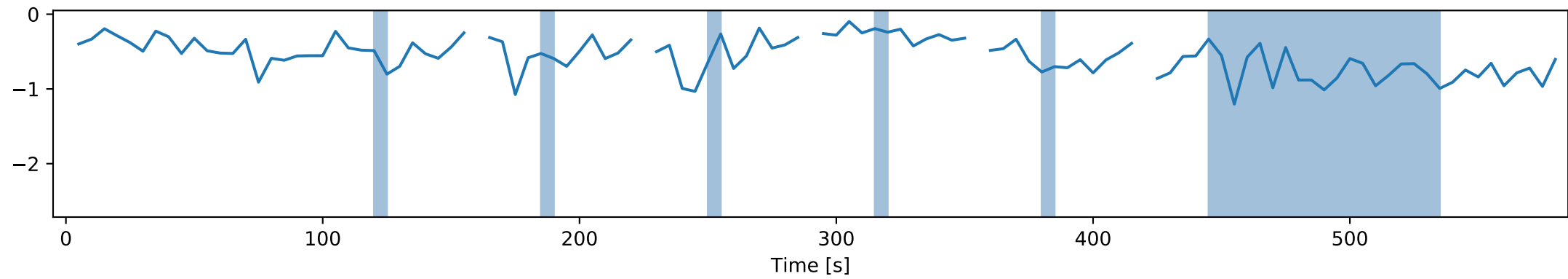
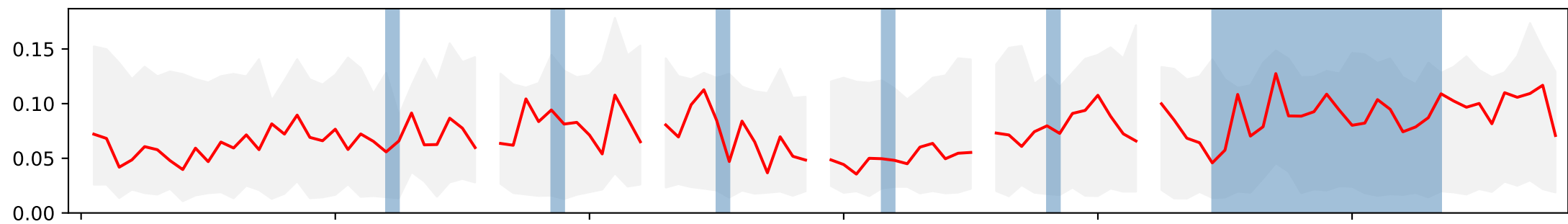
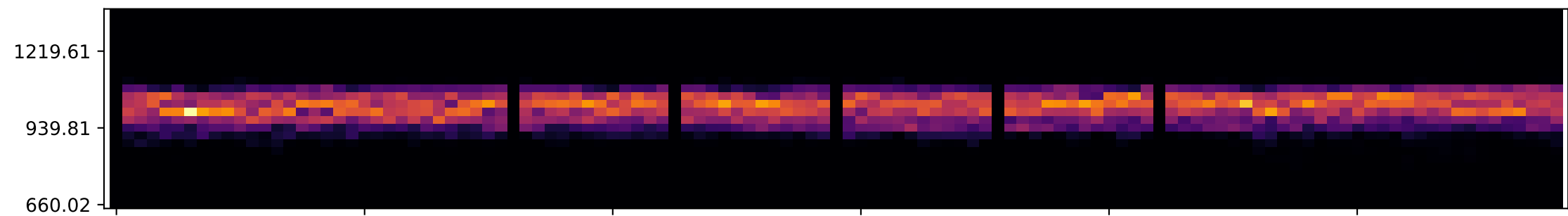
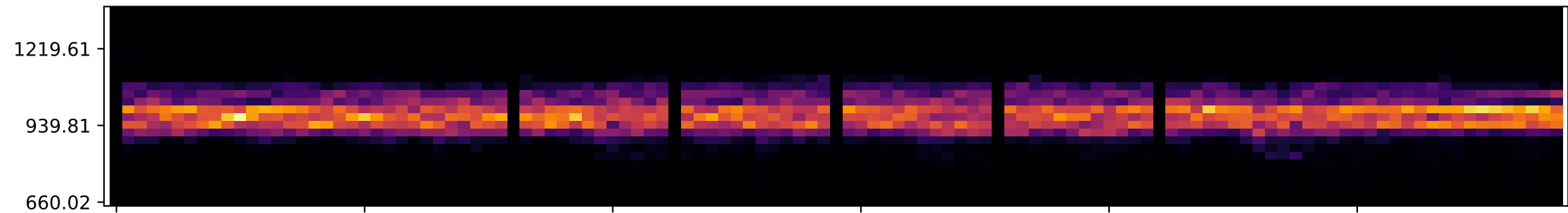
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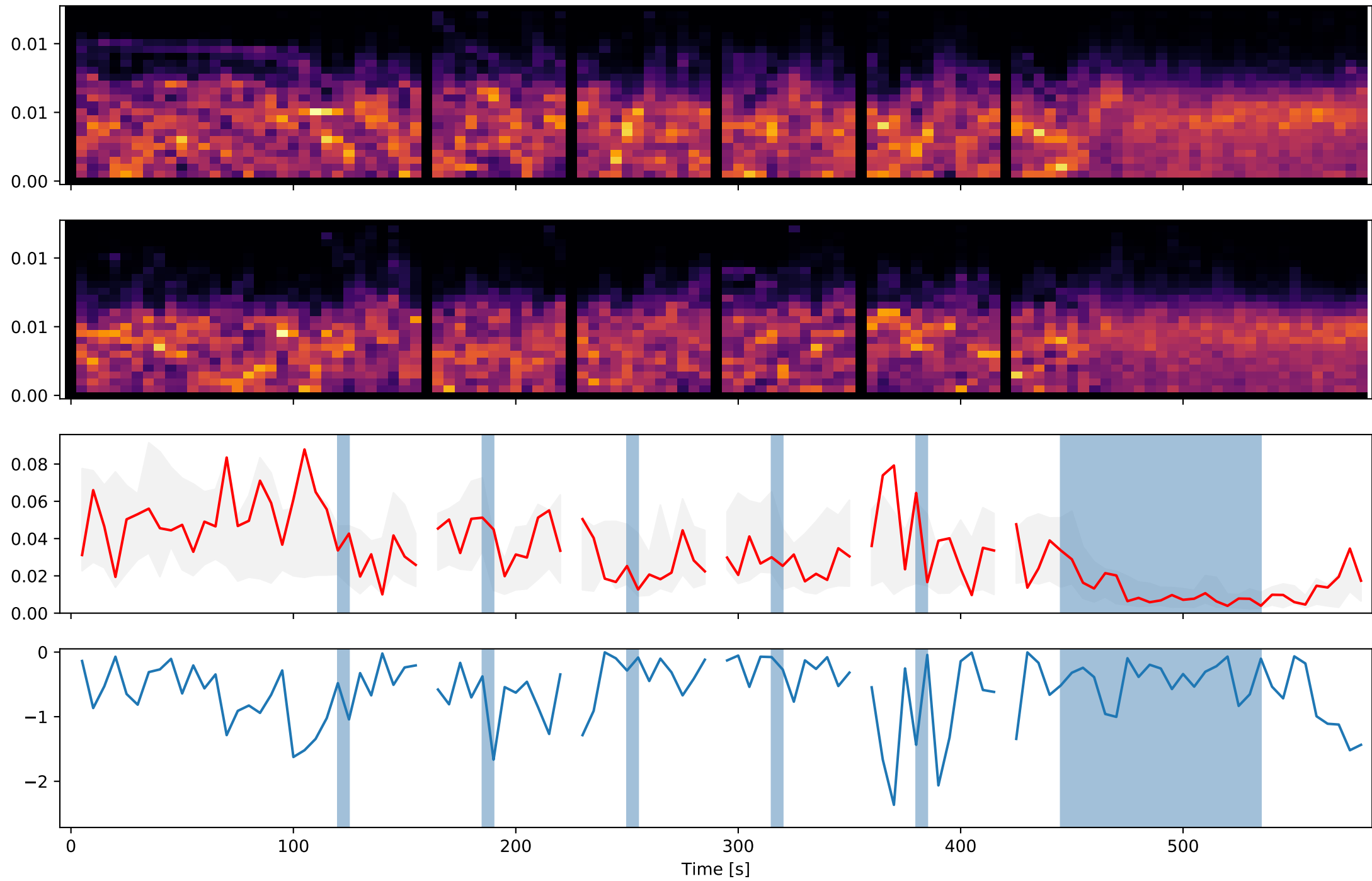
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length - pval: 0.21814254859611232

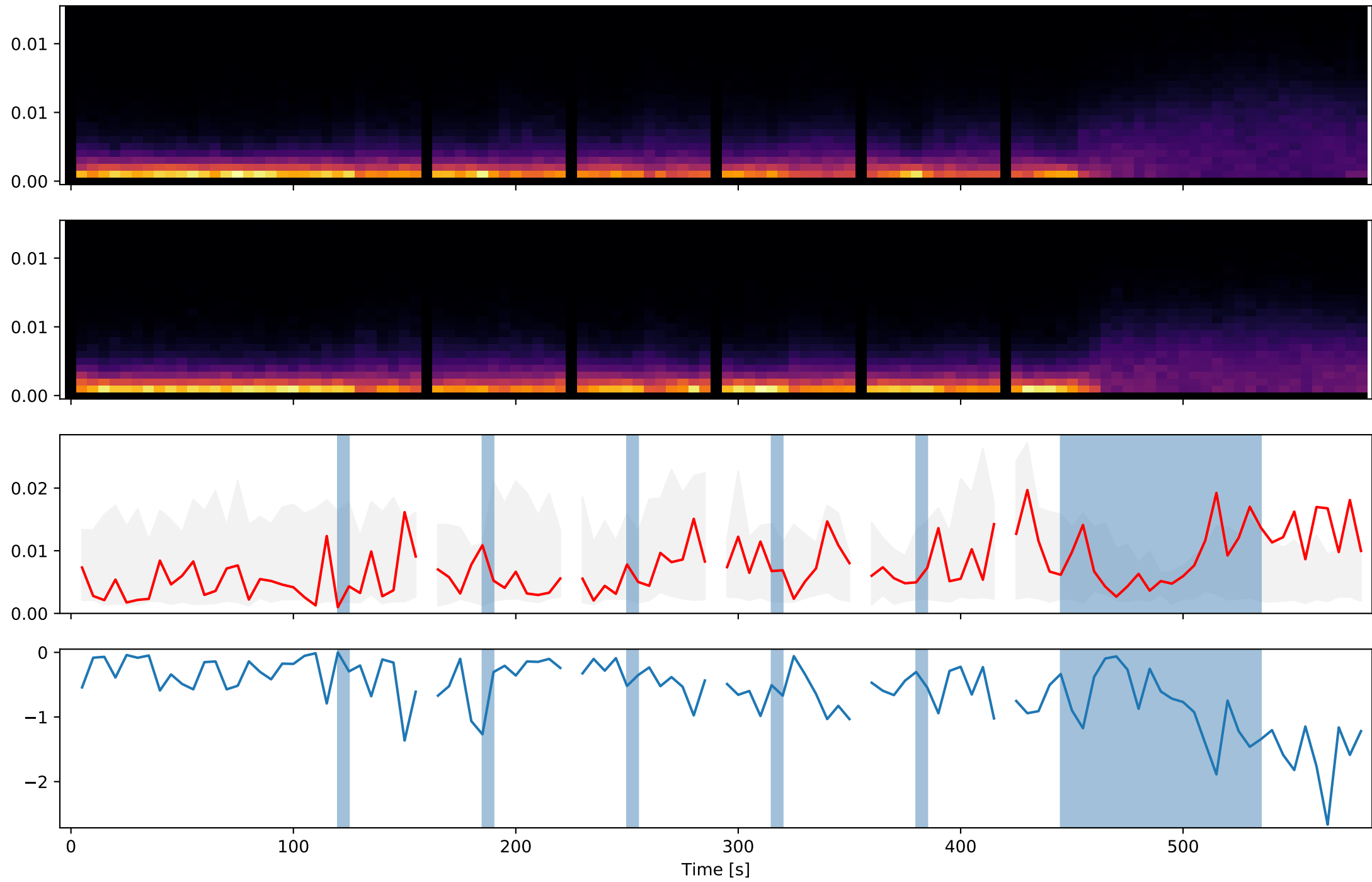


curvature\_hips - pval: 0.2267818574514039

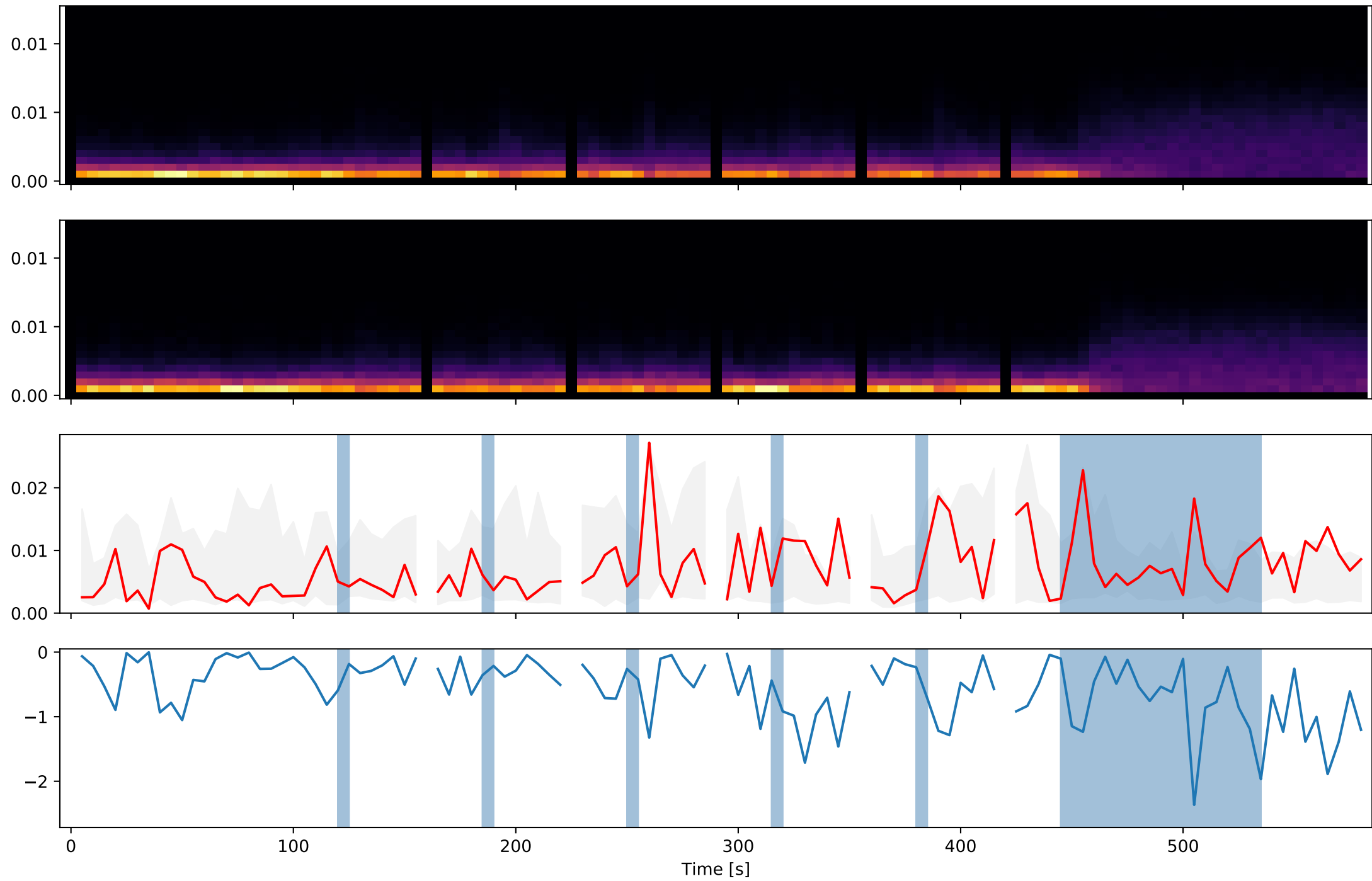




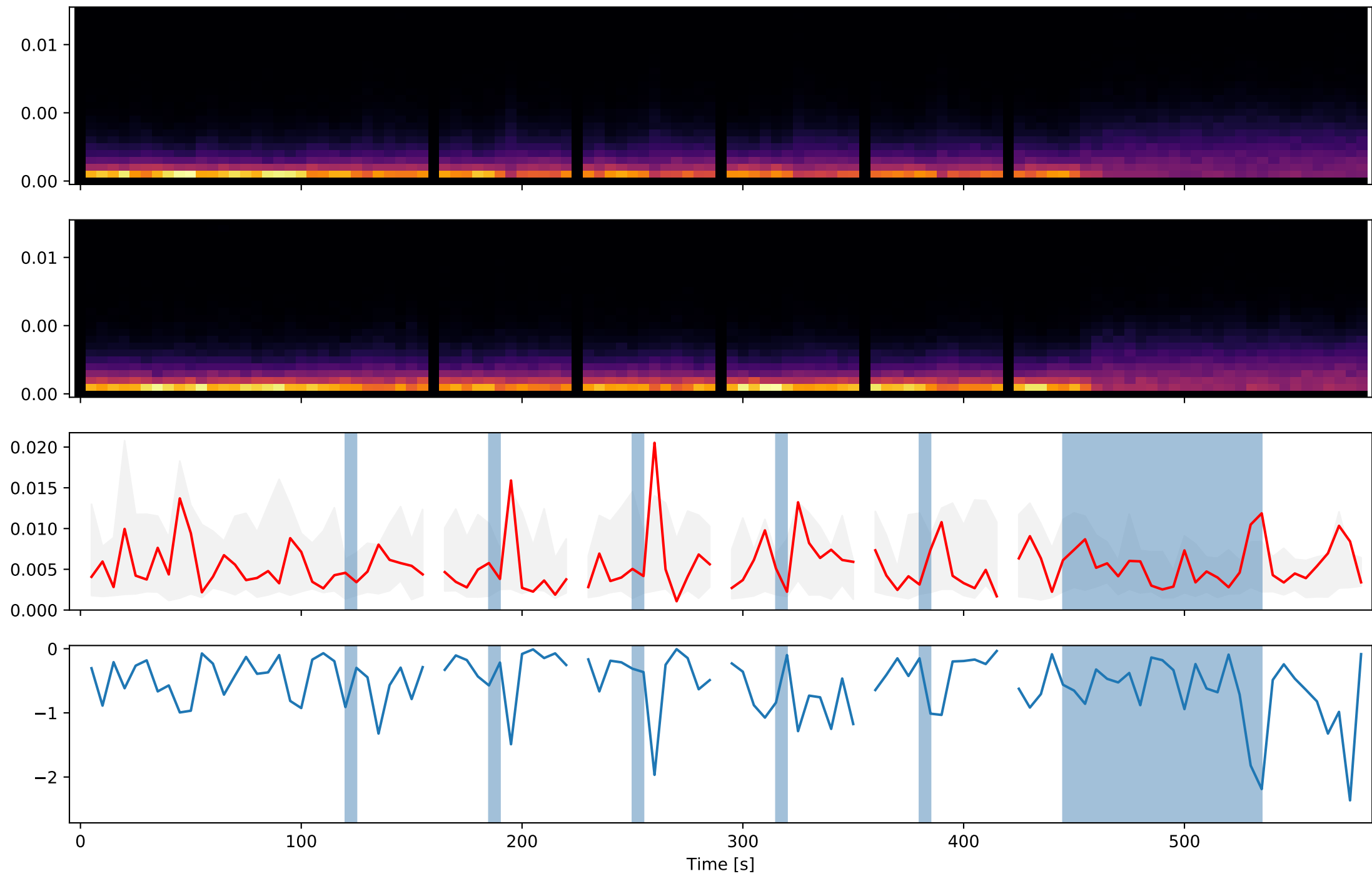
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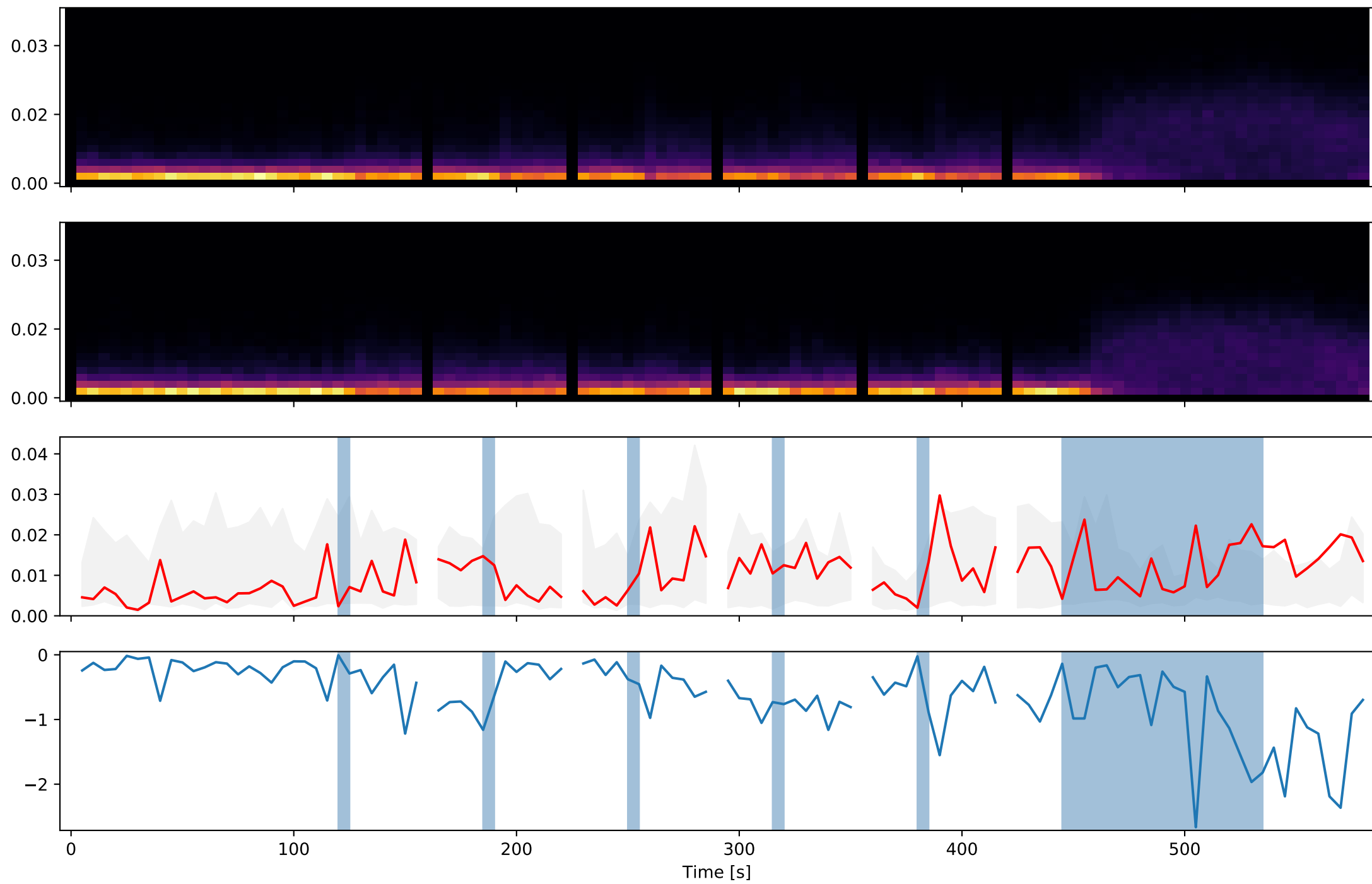
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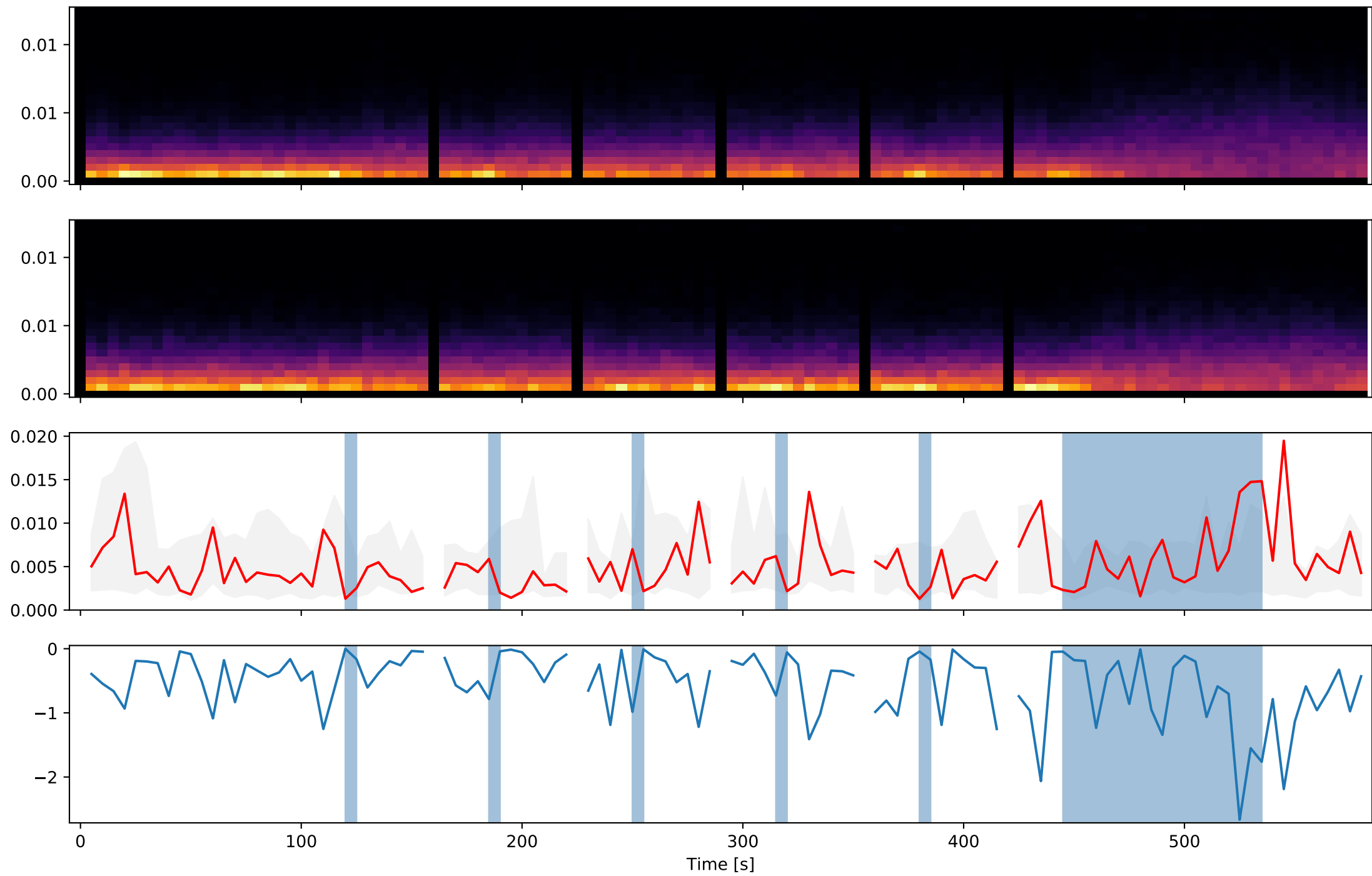
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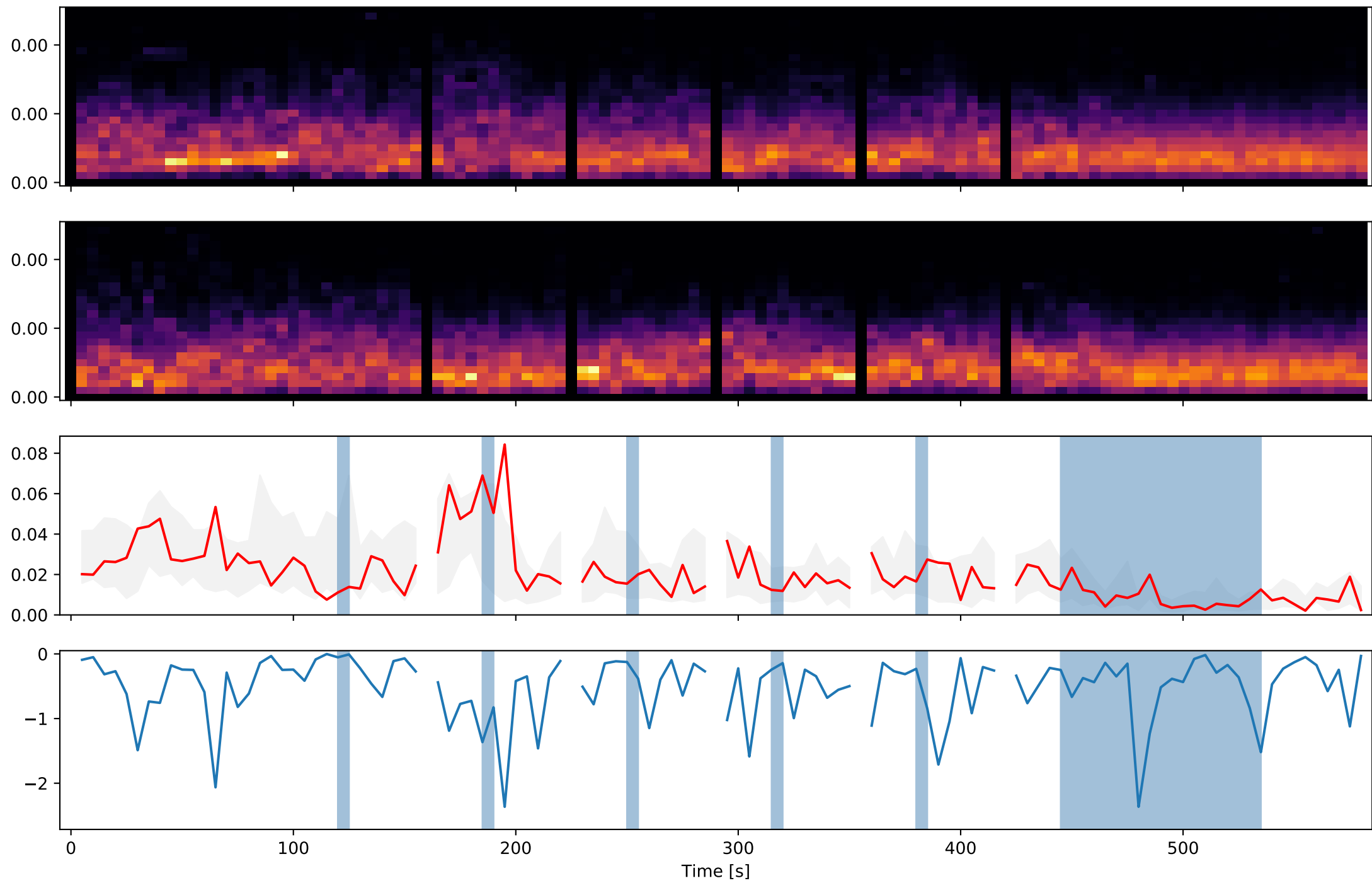
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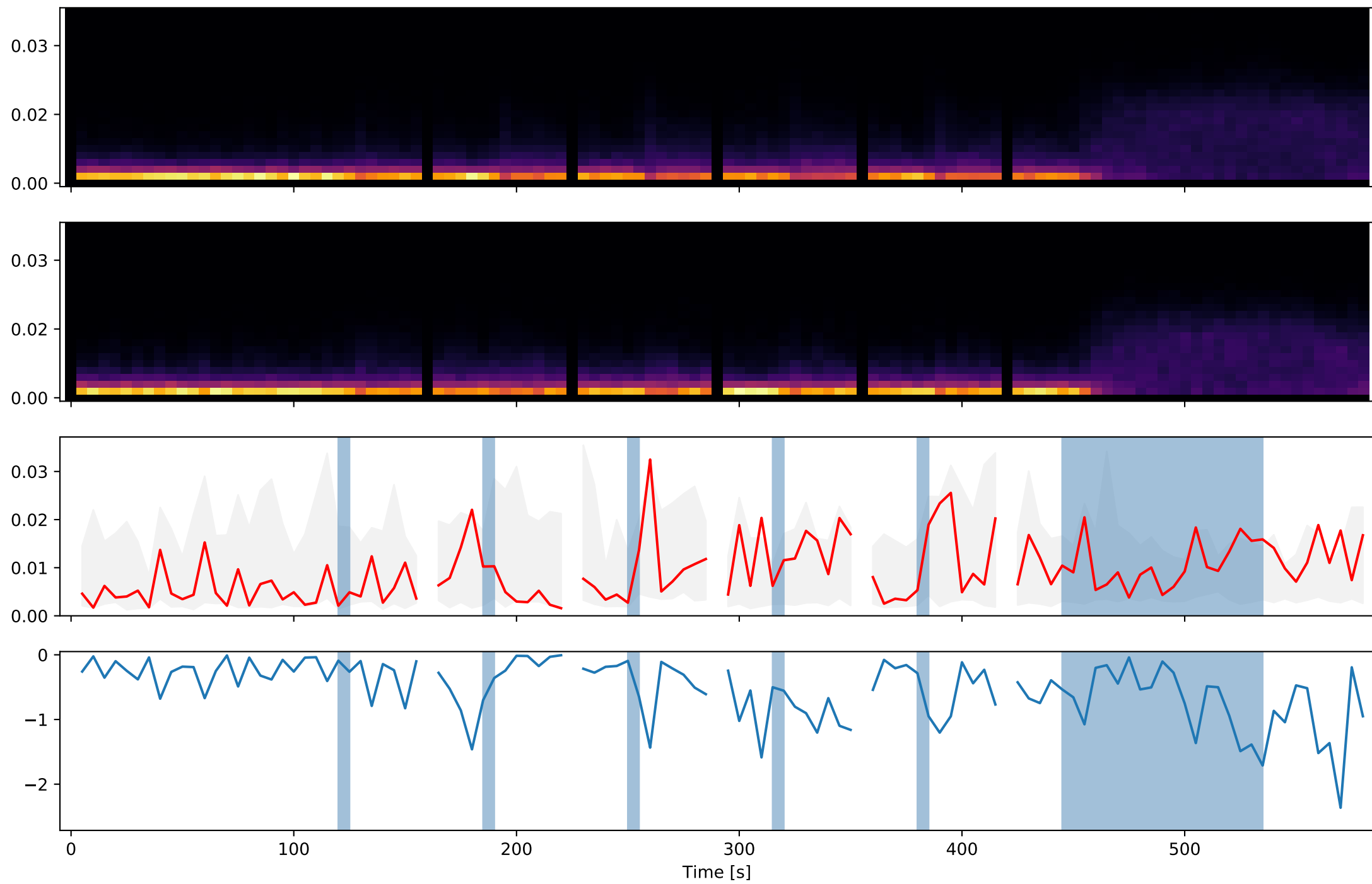
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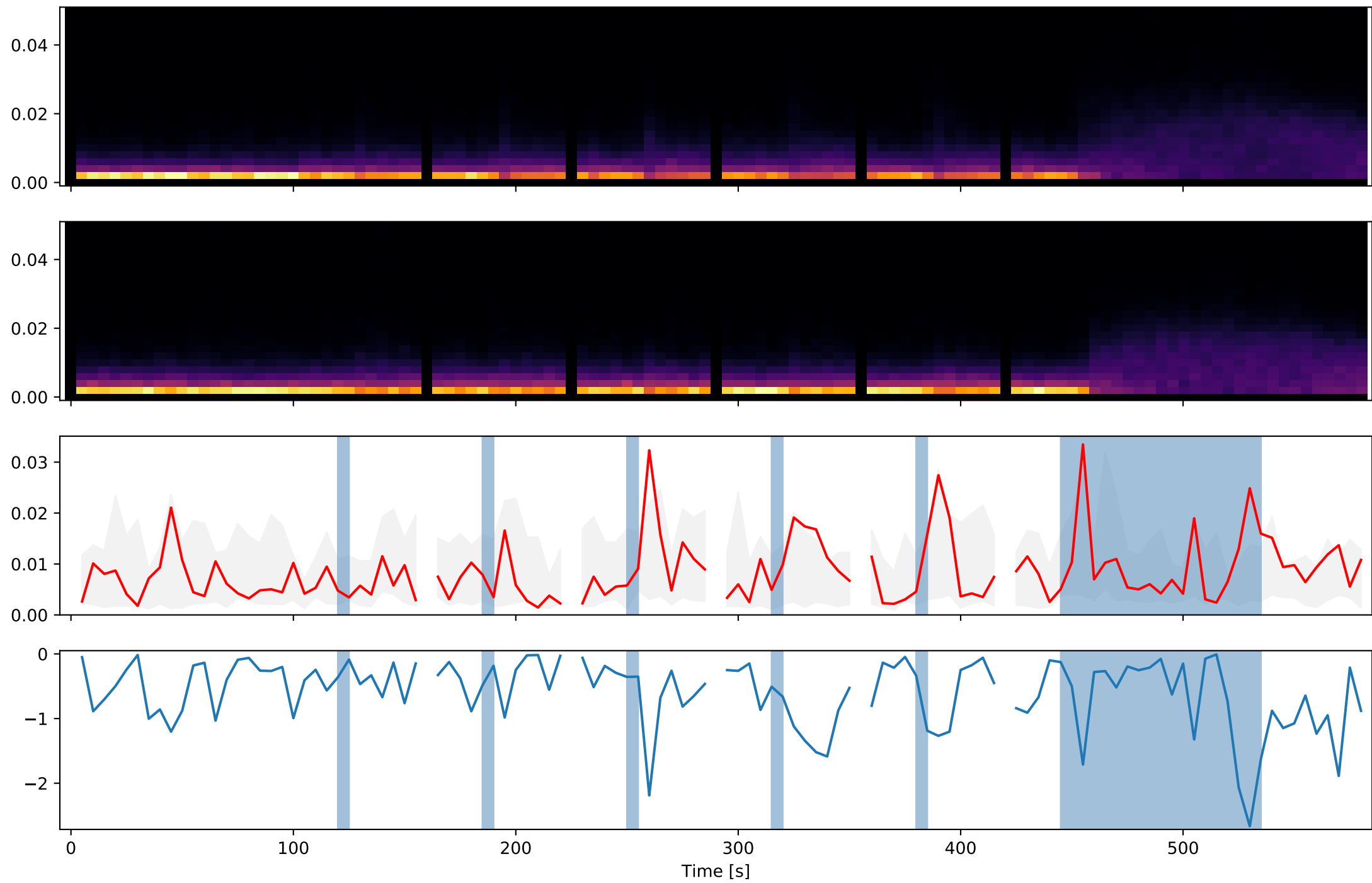
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d\_curvature\_midbody - pval: 0.28077753779697623

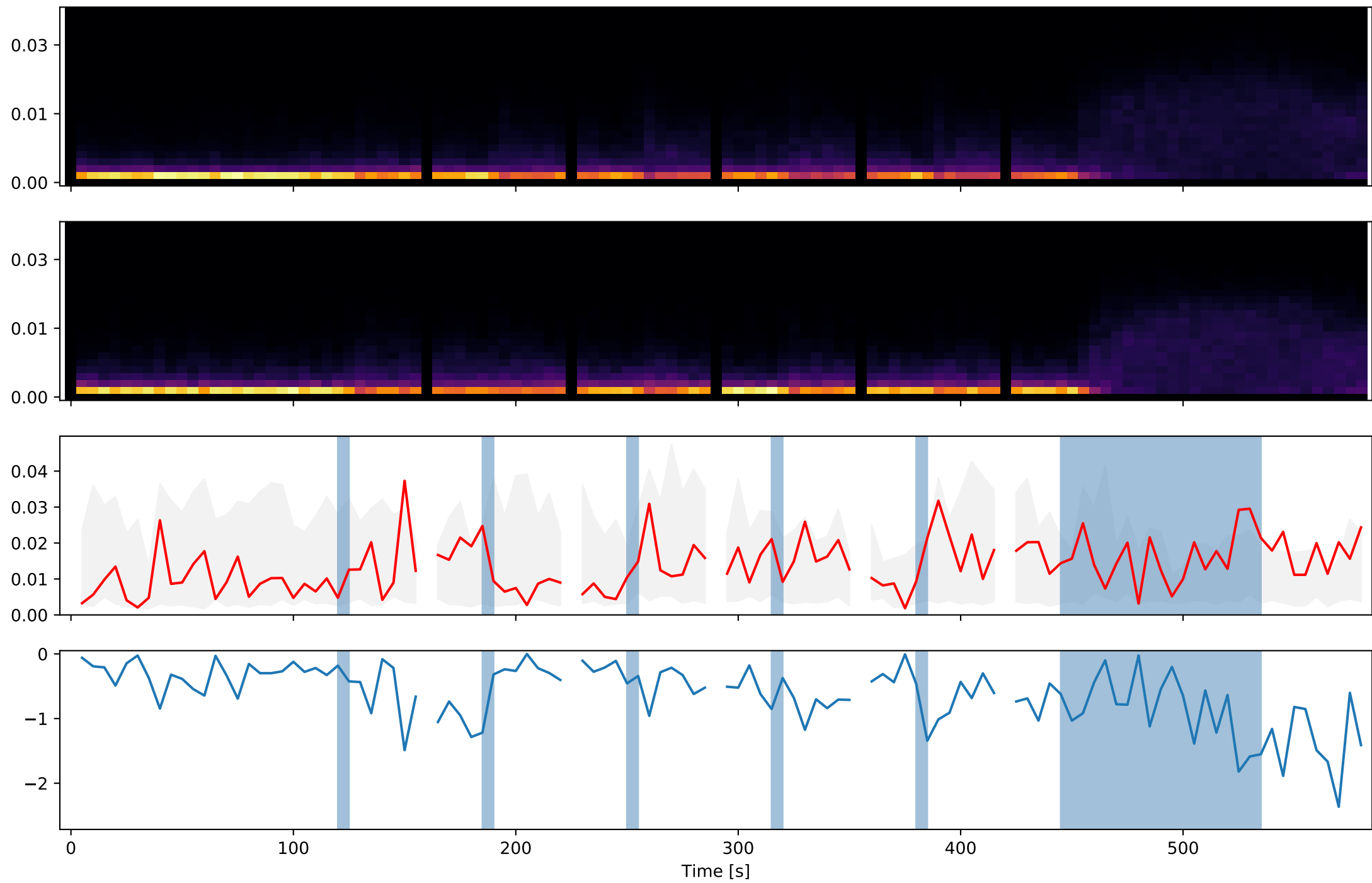


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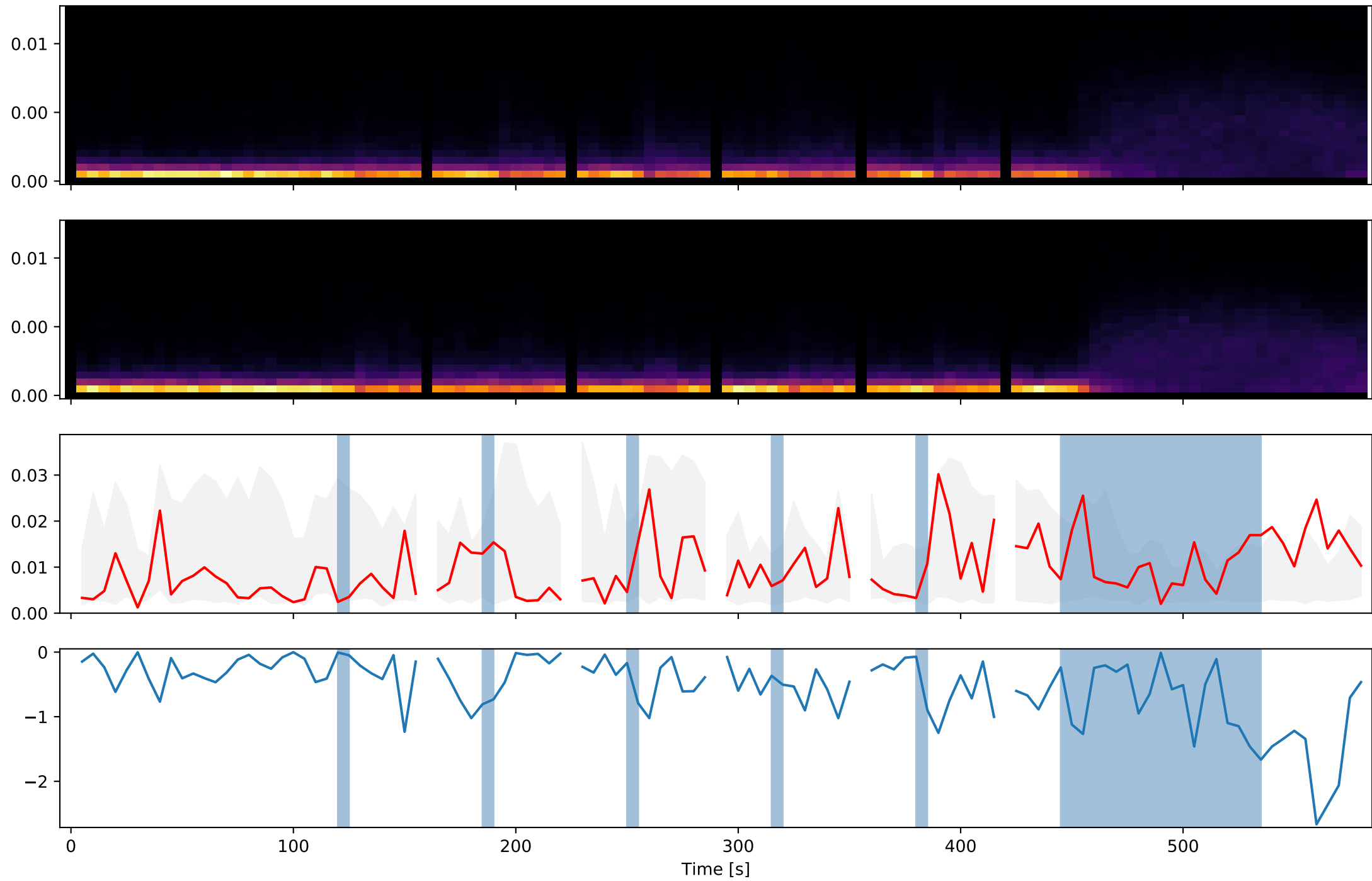




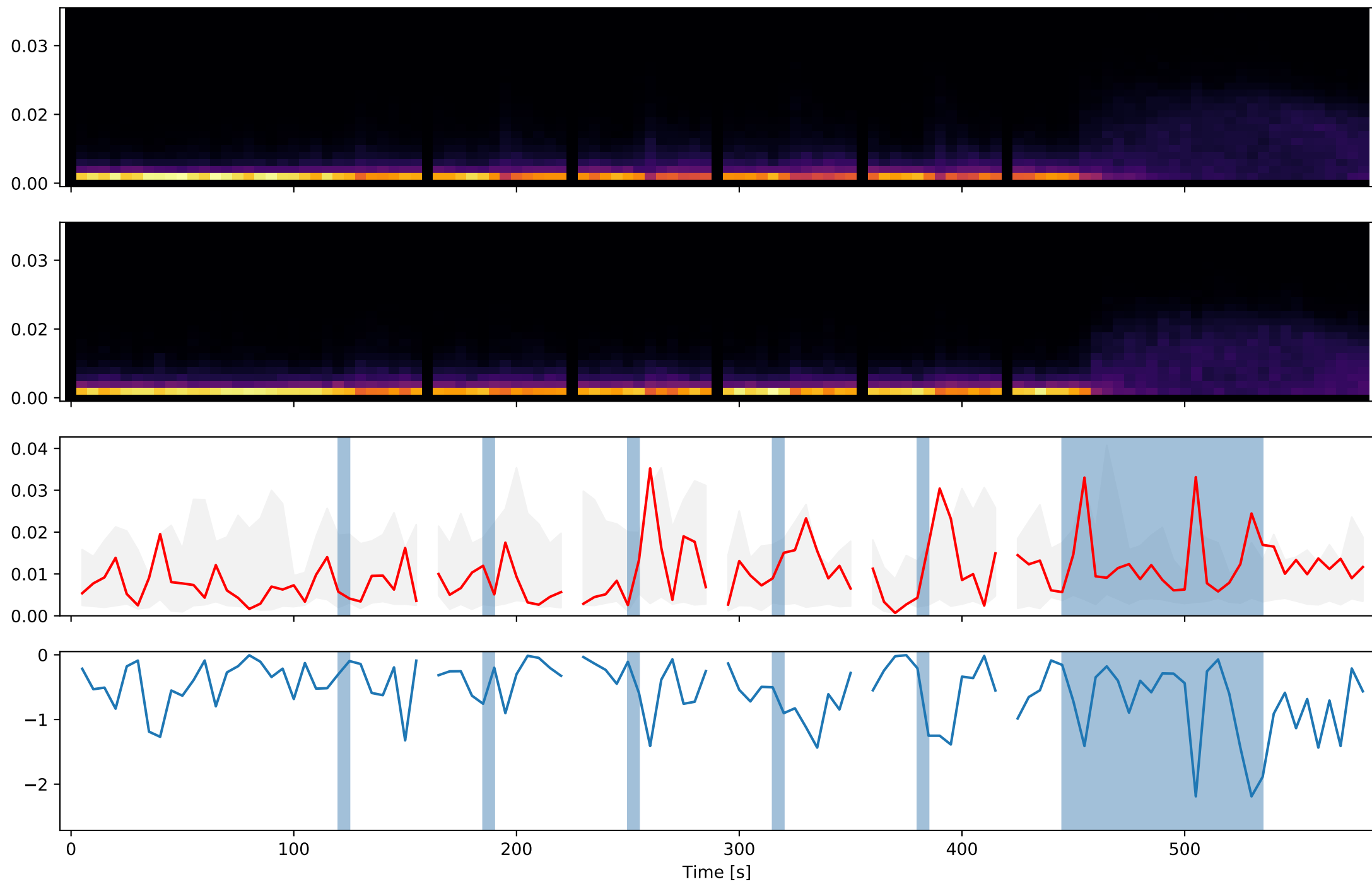
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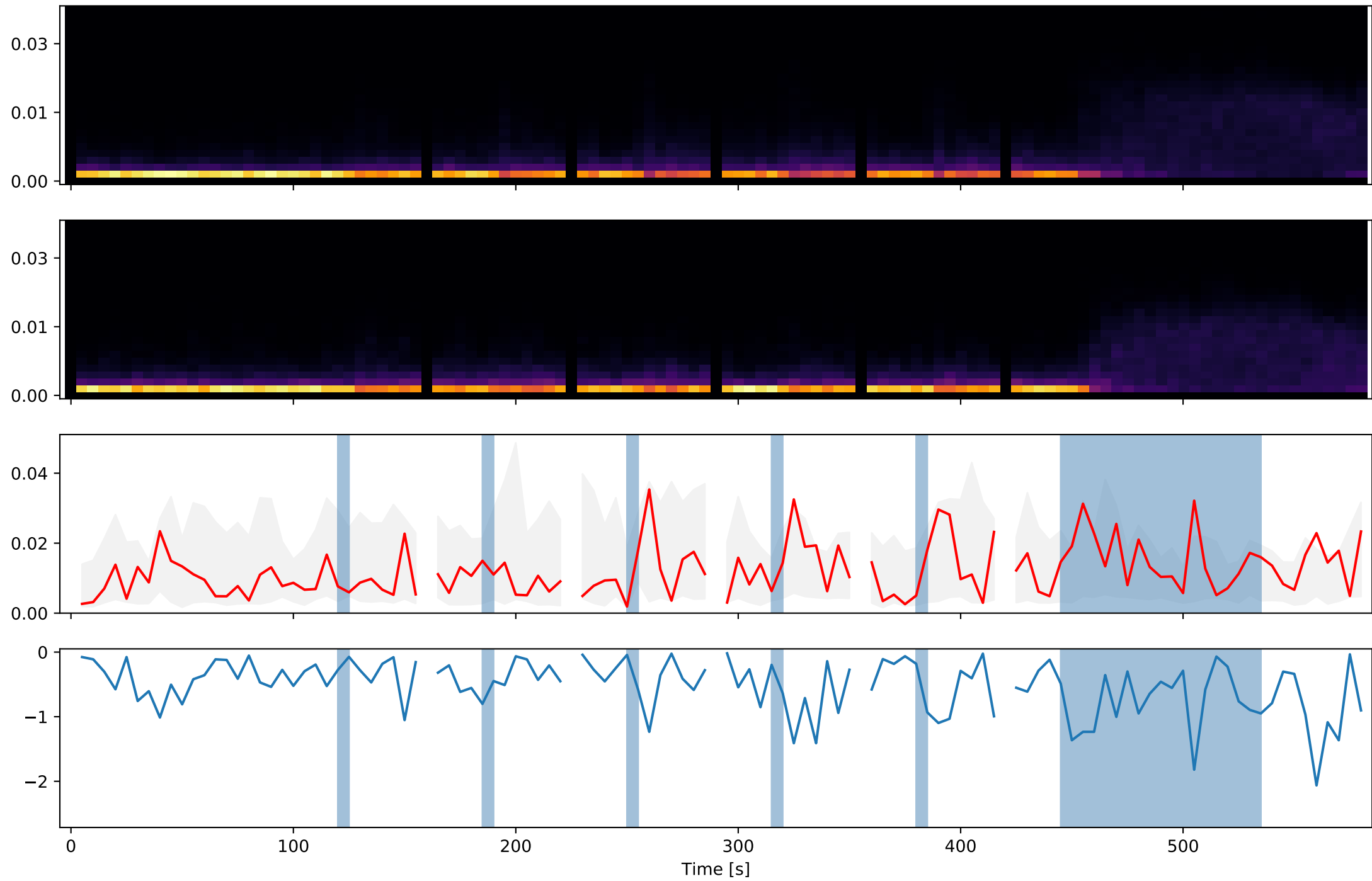
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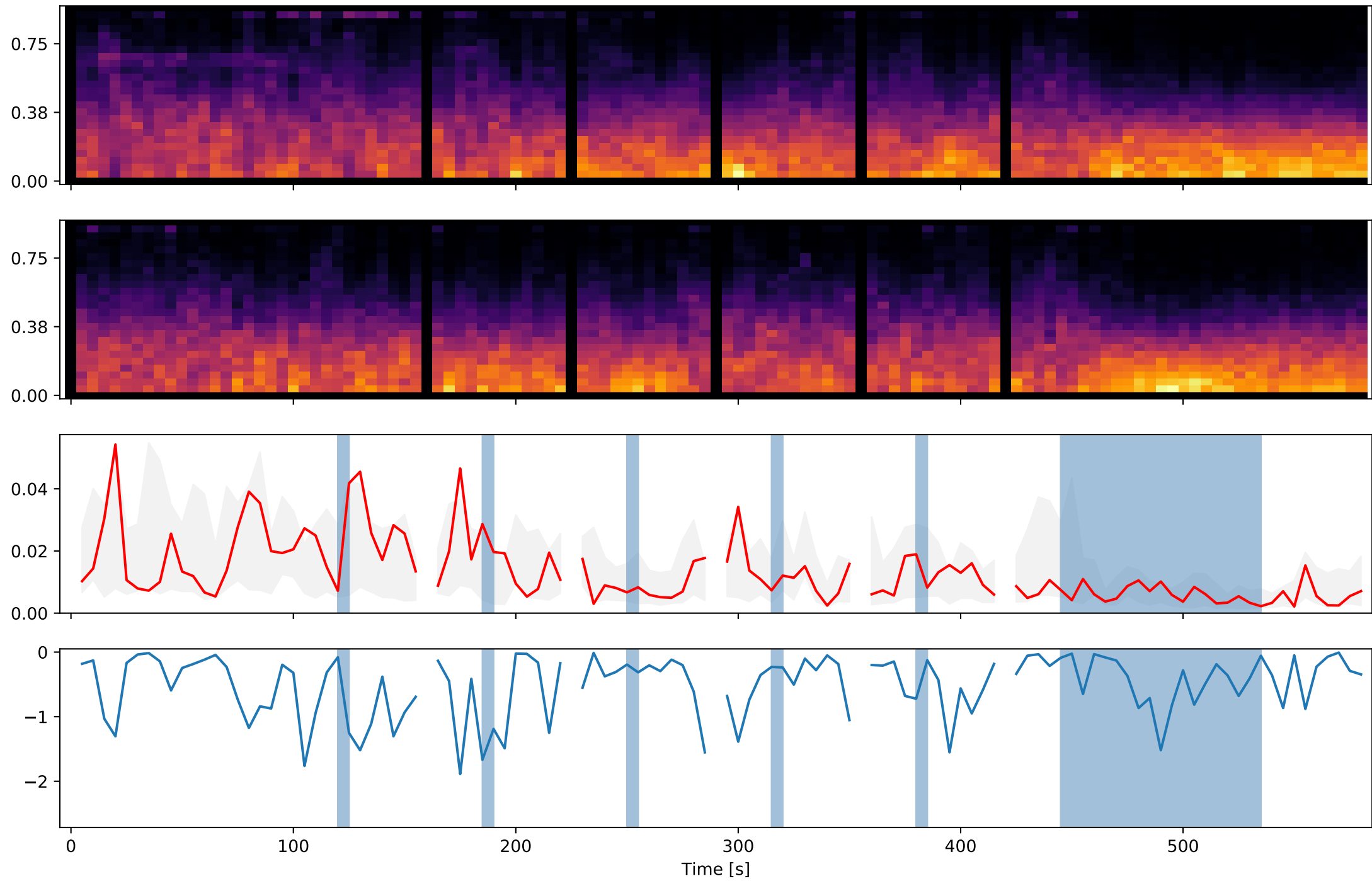
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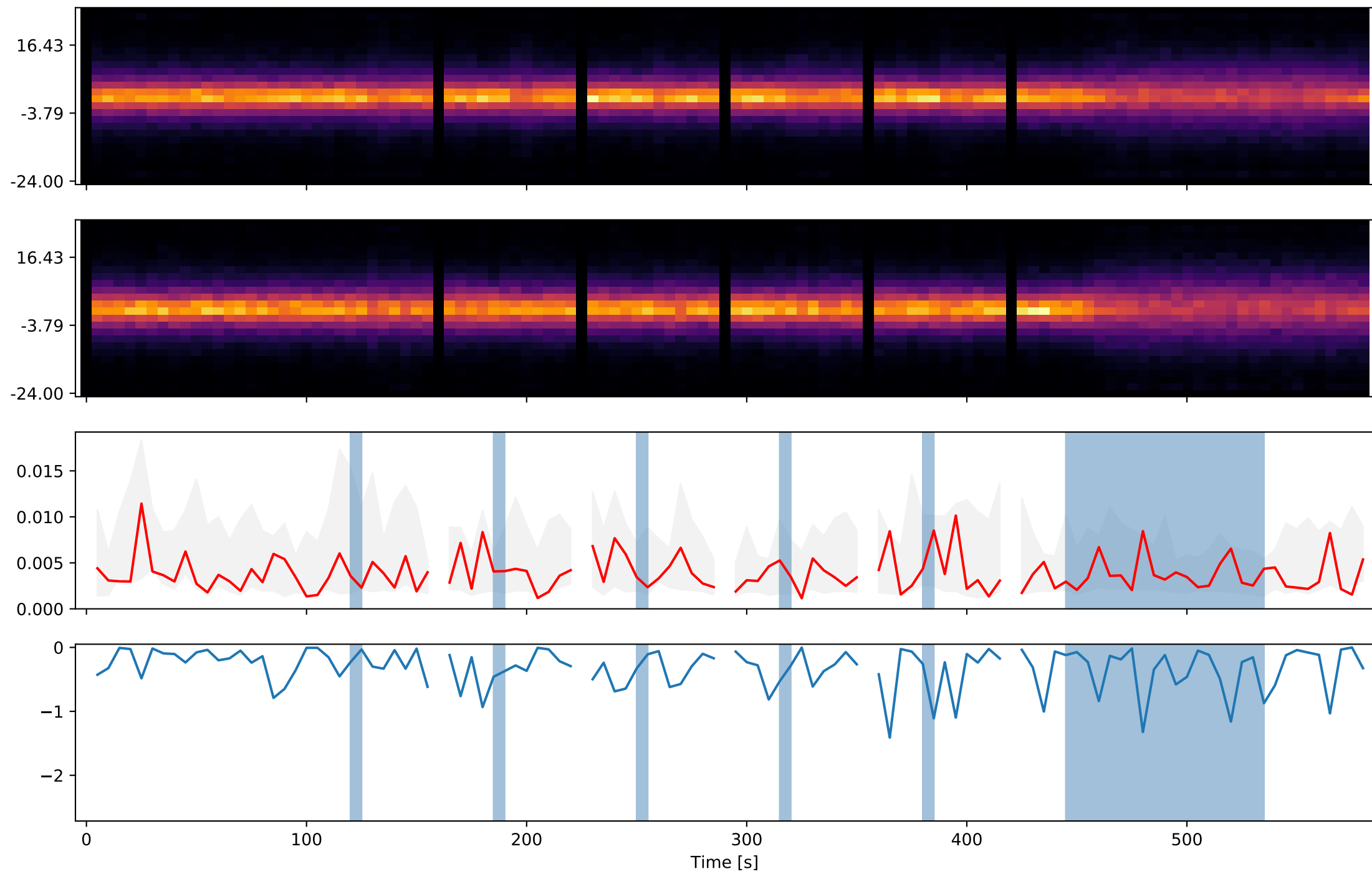
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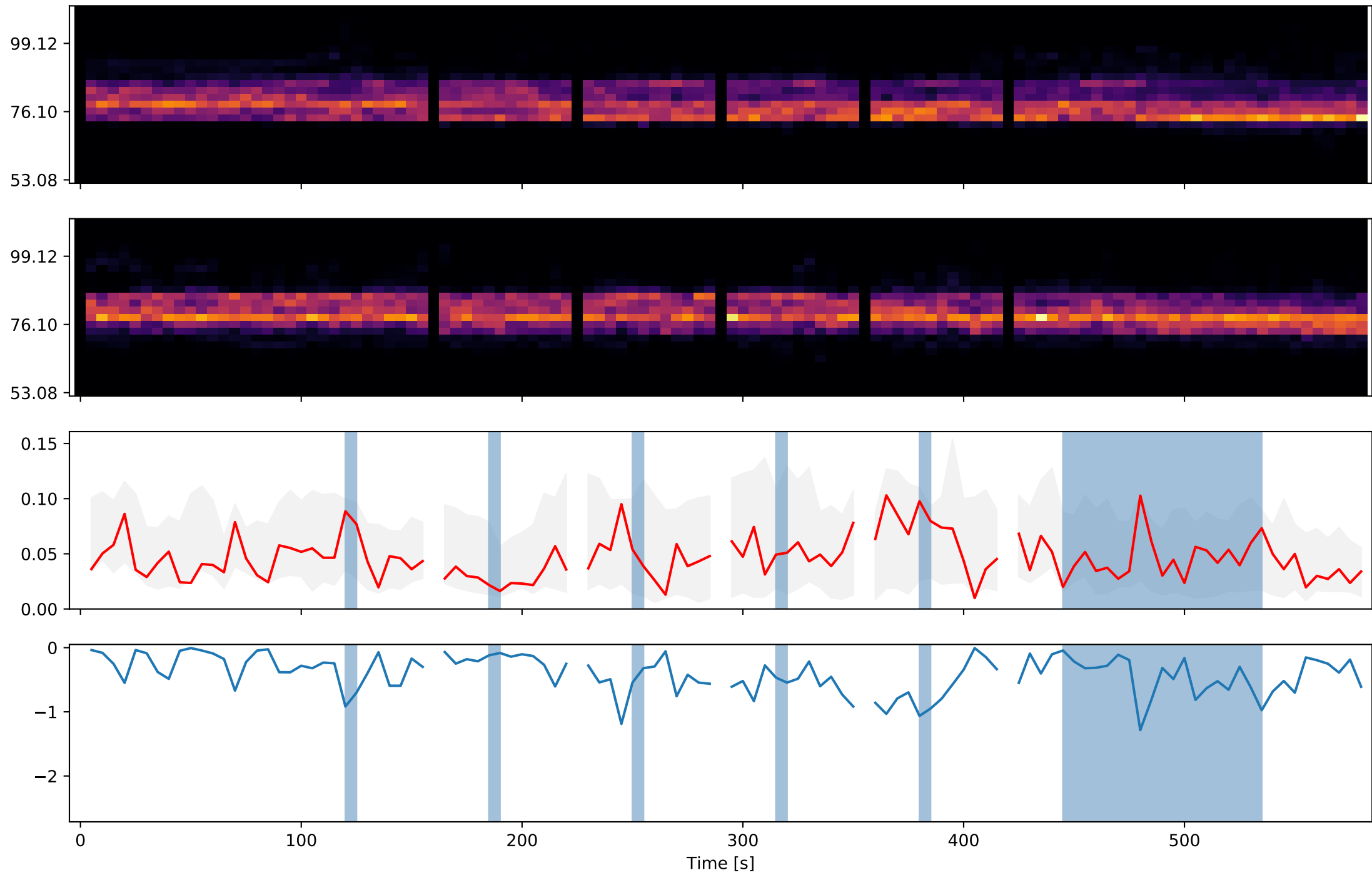
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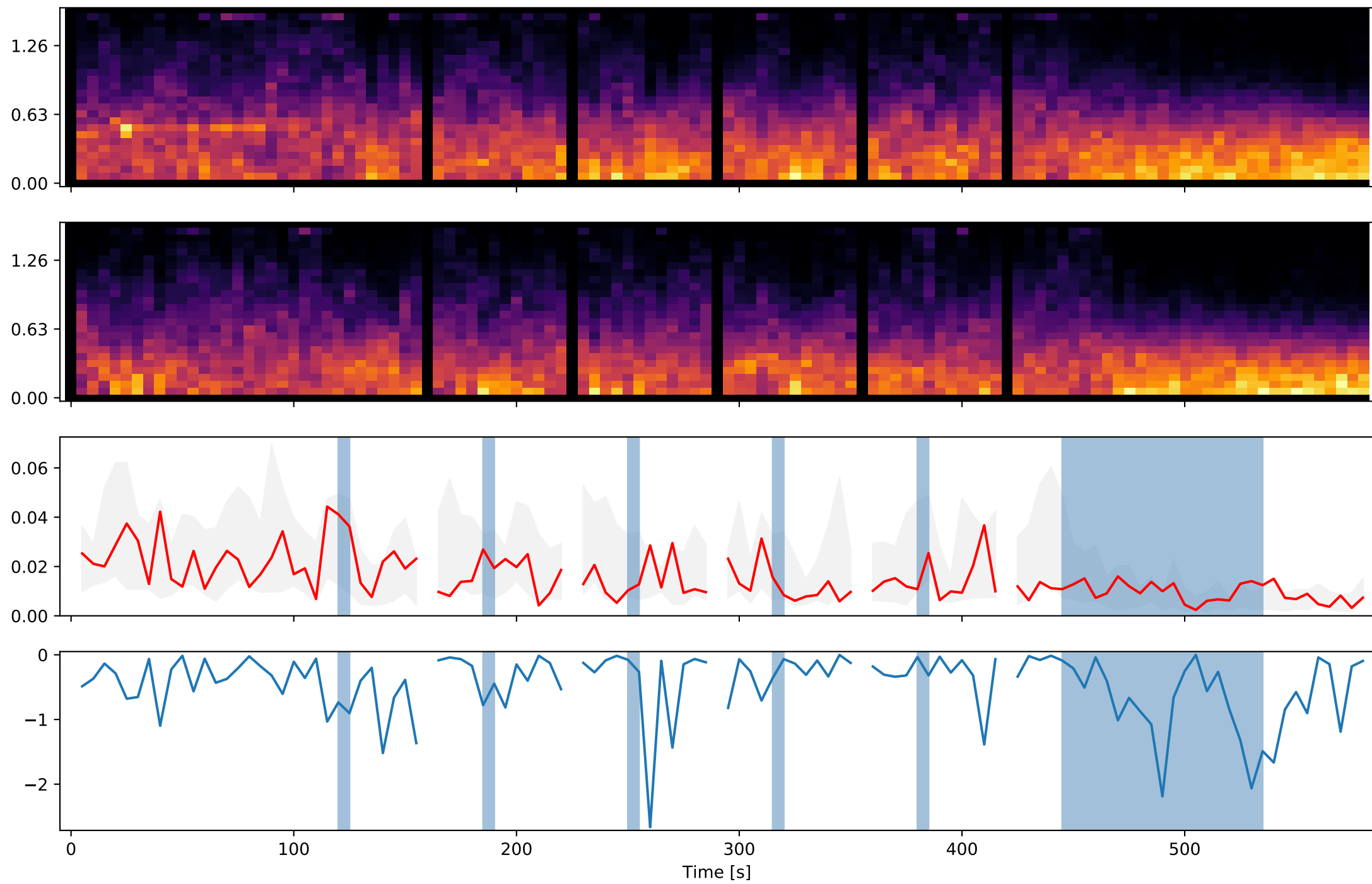
d\_width\_midbody - pval: 0.35205183585313177



width\_midbody - pval: 0.3693304535637149

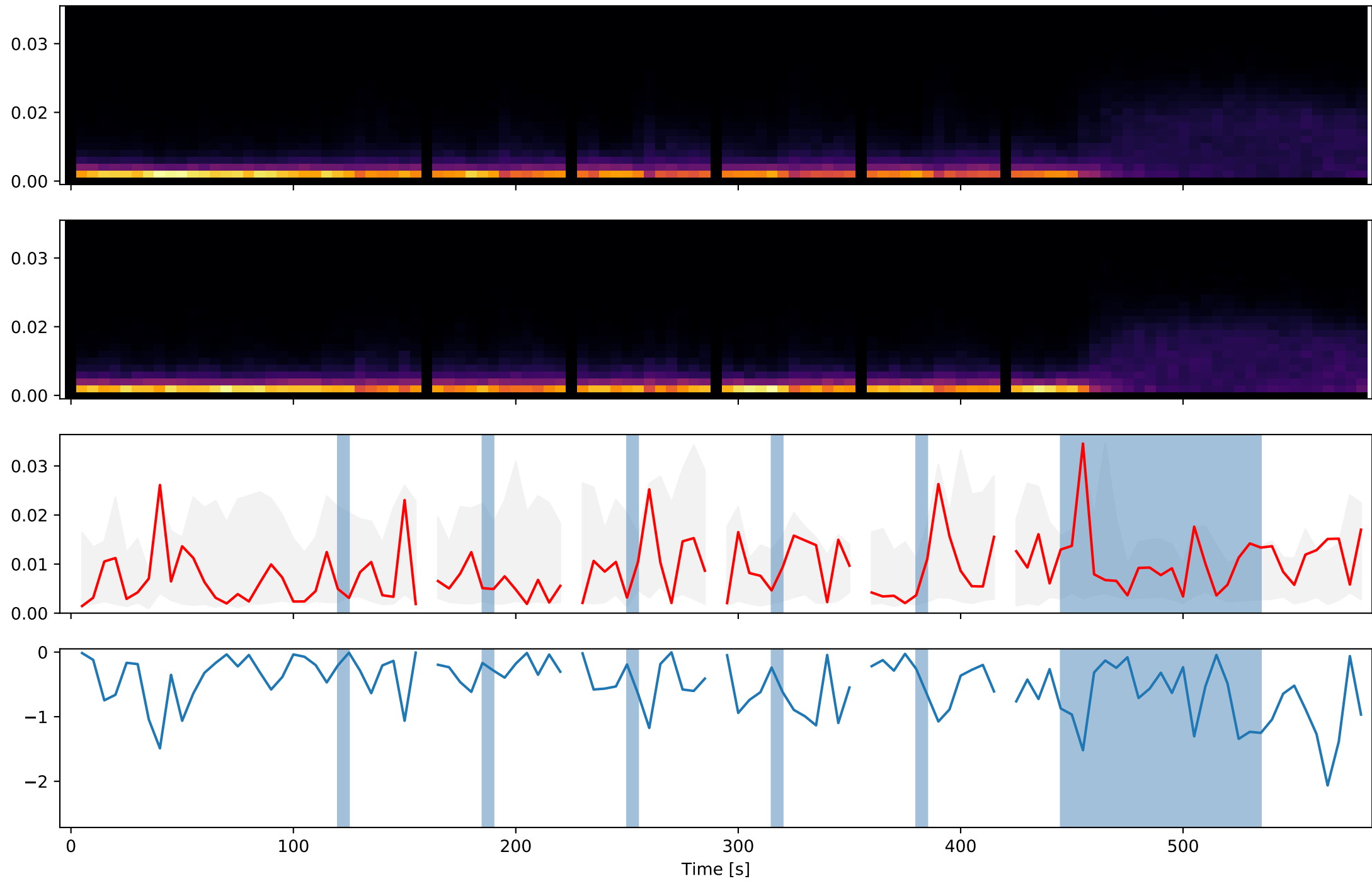


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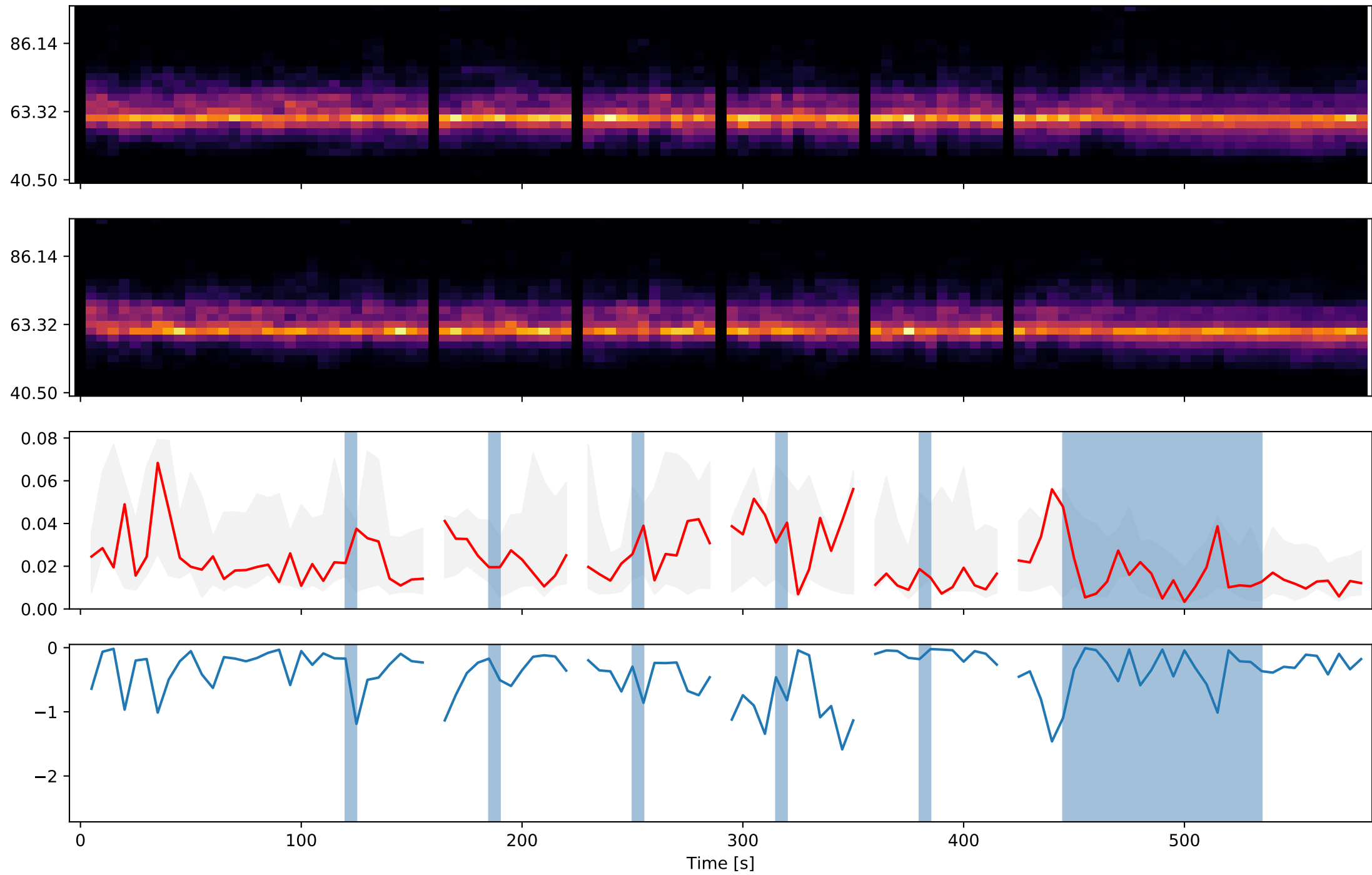




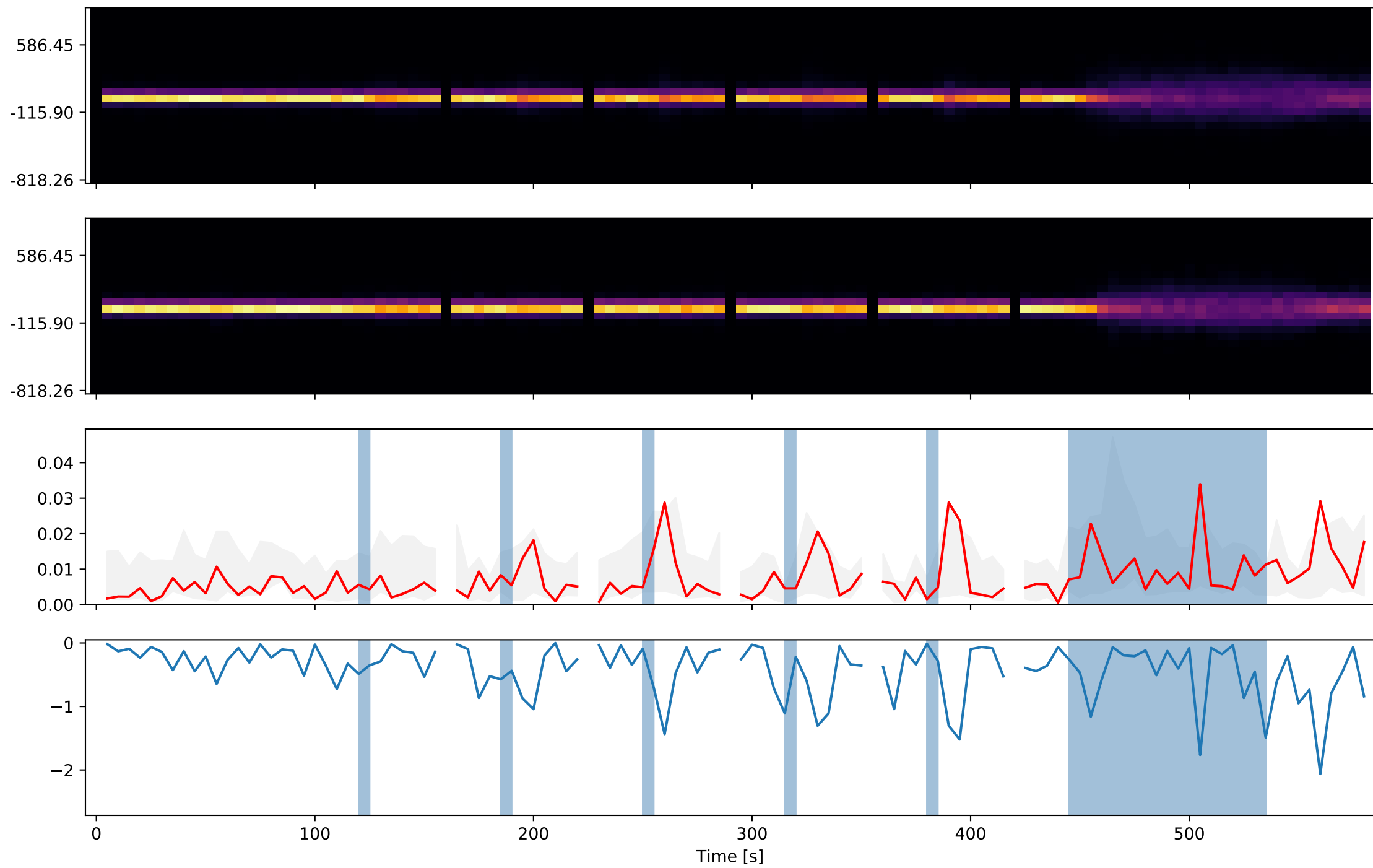
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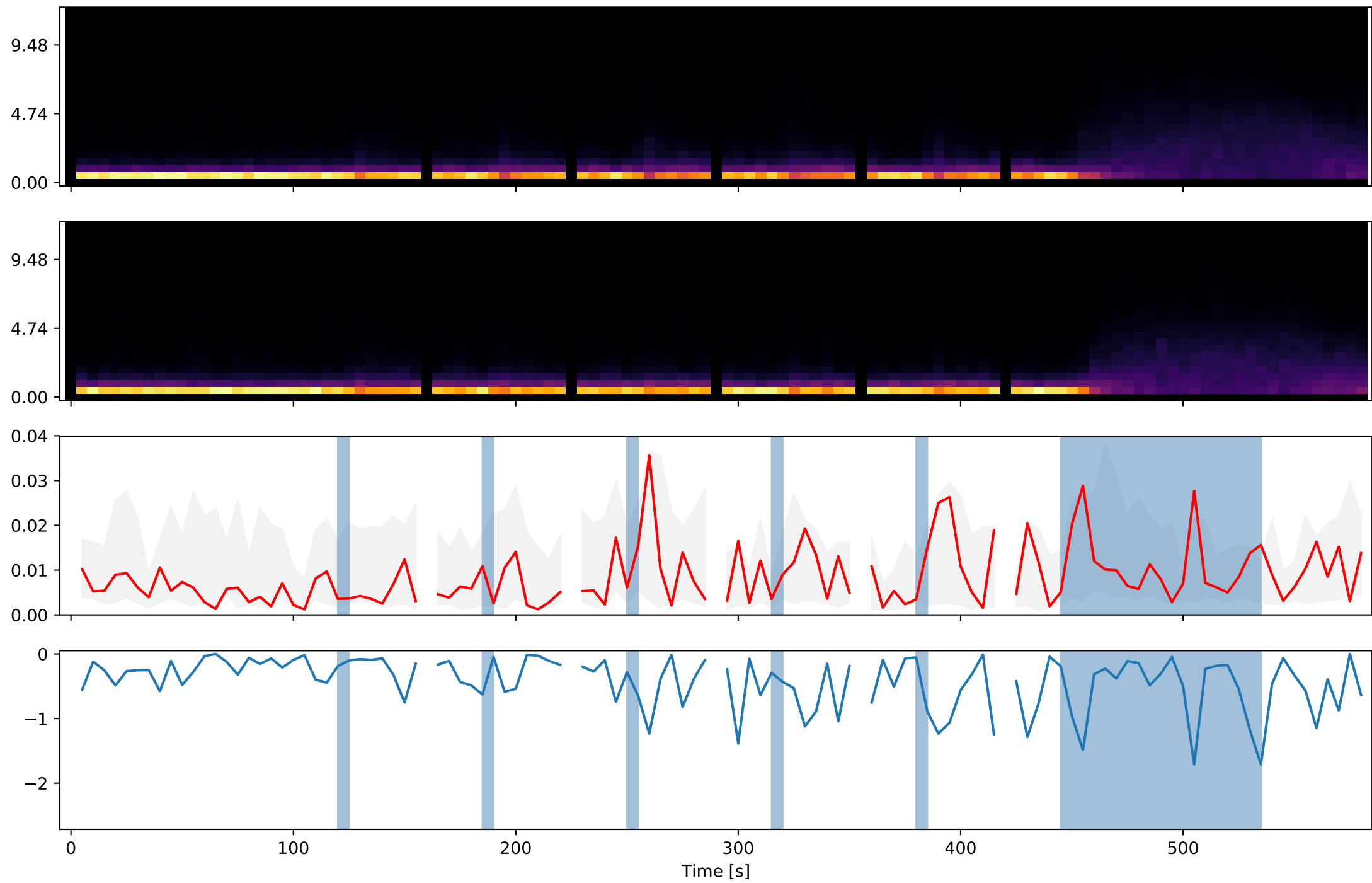
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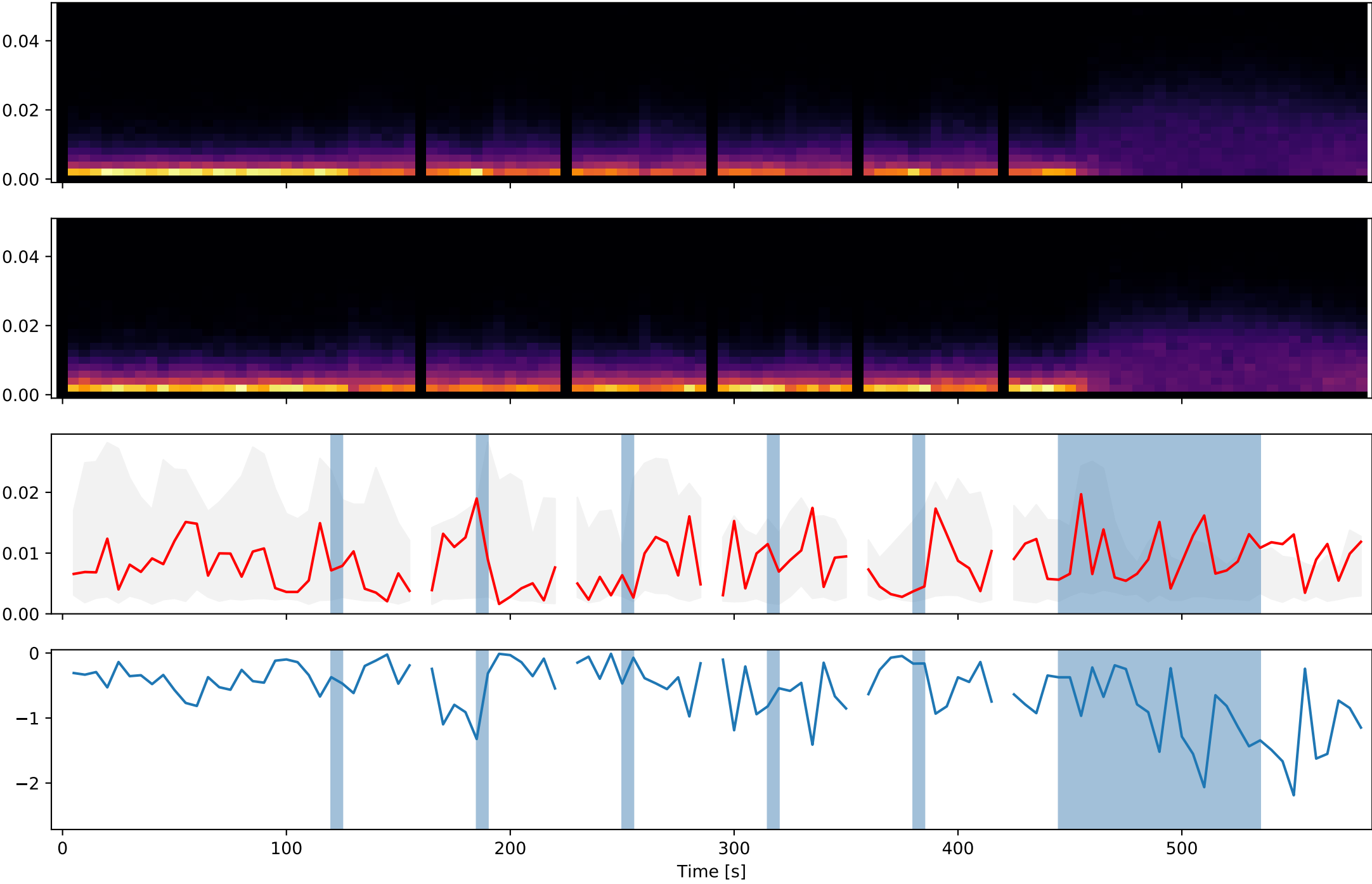
d\_relative\_to\_hips\_radial\_velocity\_tail\_tip - pval: 0.38444924406047515



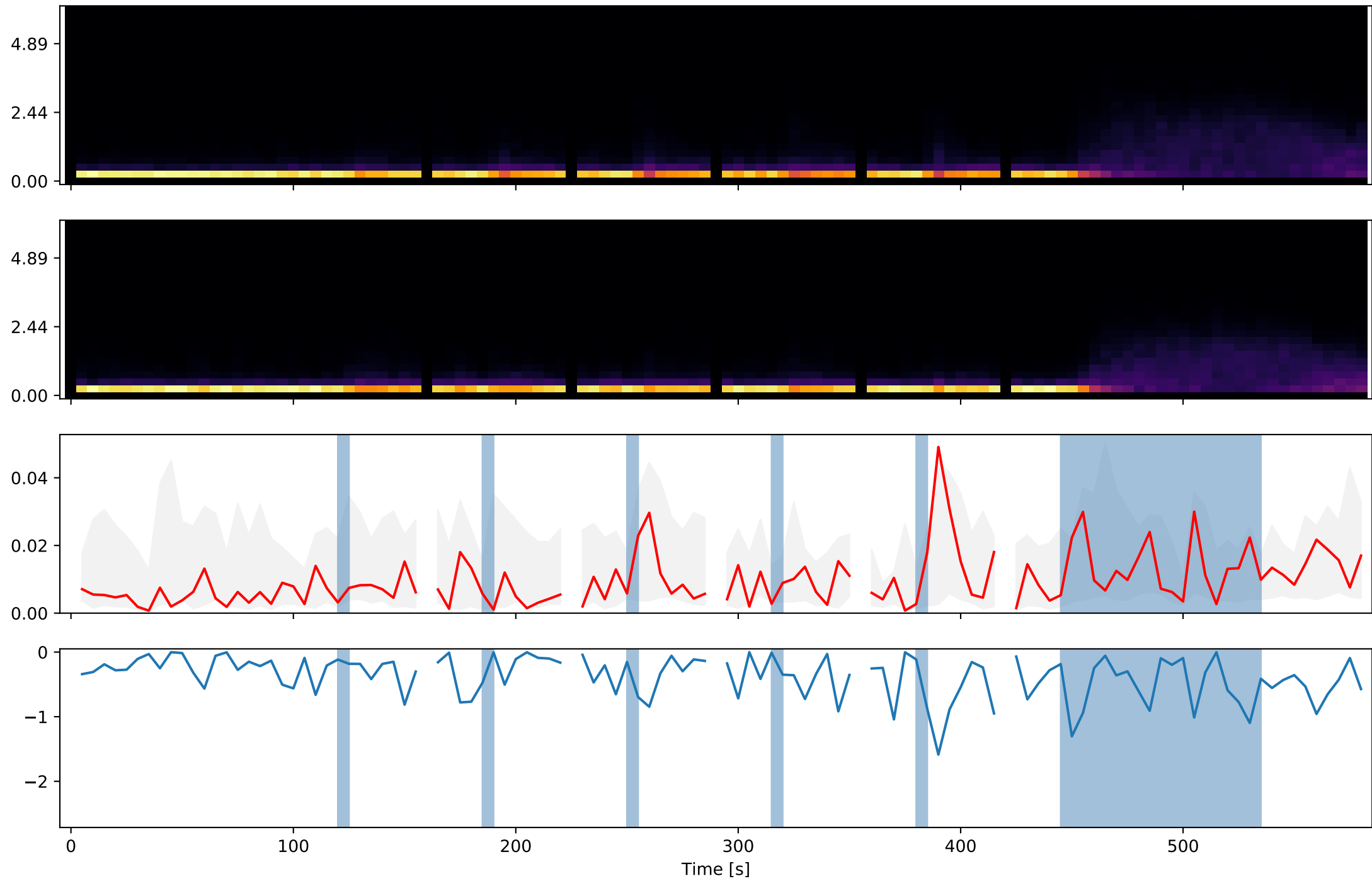
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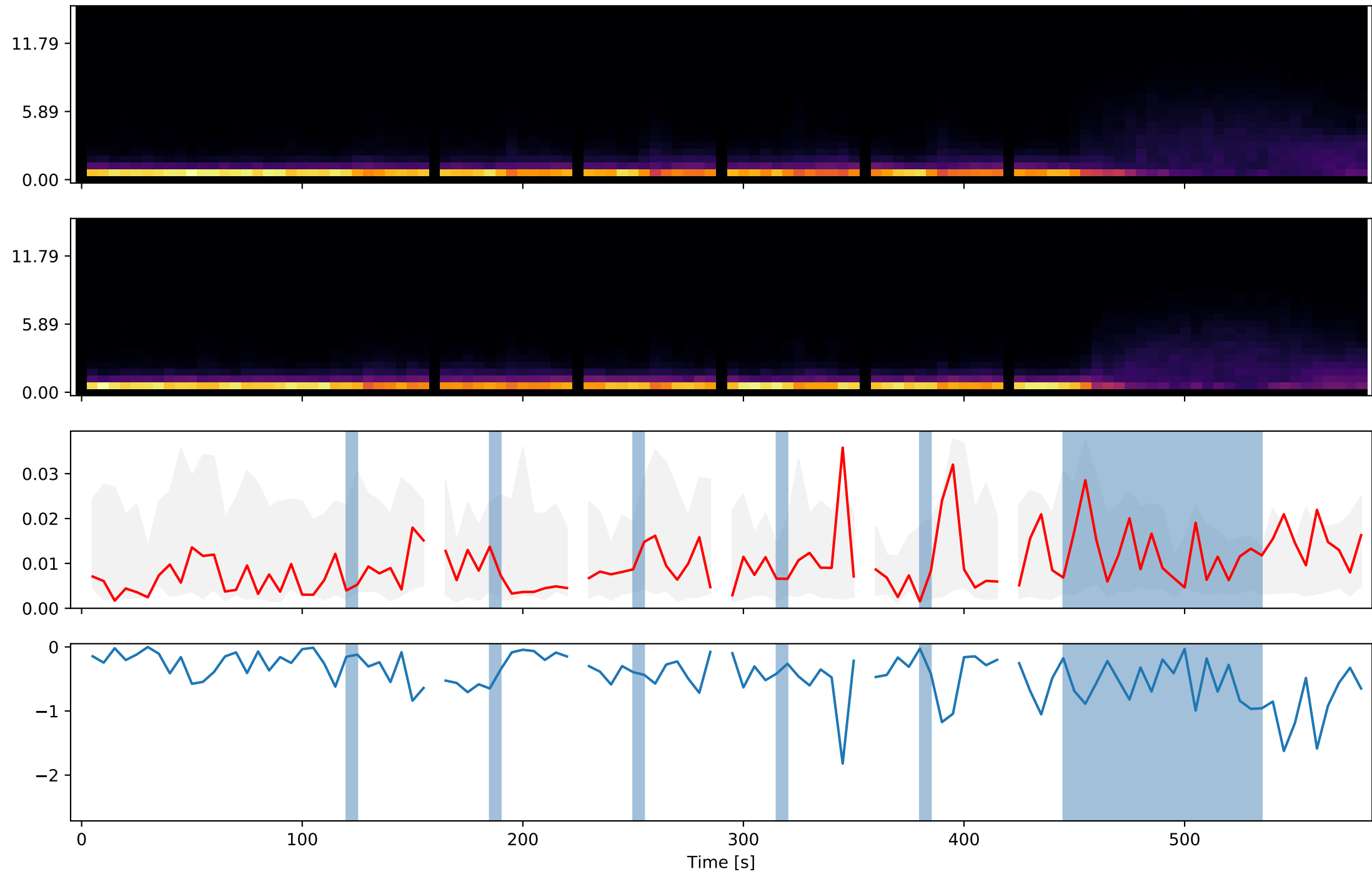
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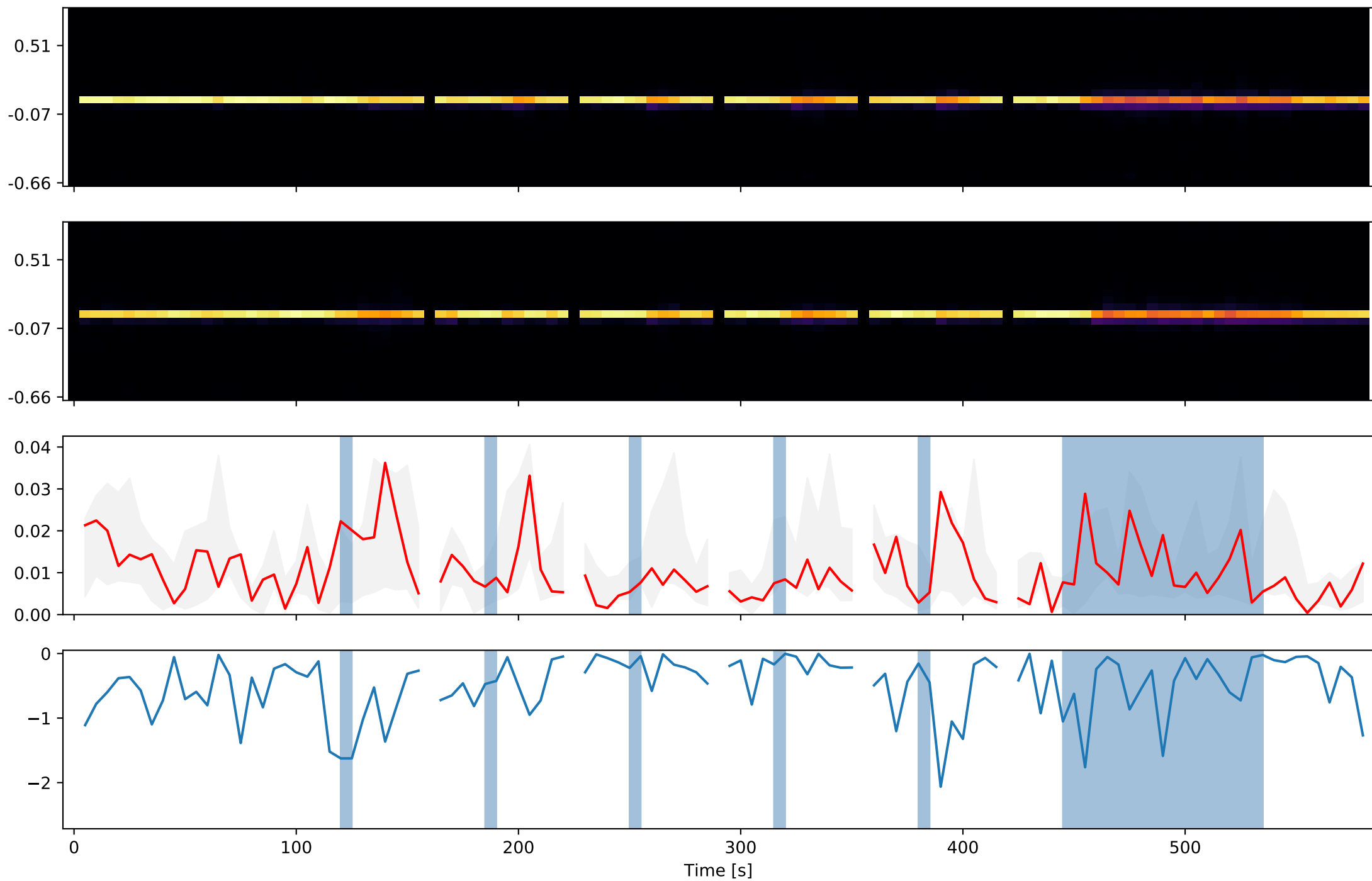
d\_relative\_to\_body\_angular\_velocity\_neck - pval: 0.42548596112311016



d\_angular\_velocity\_neck - pval: 0.4406047516198704

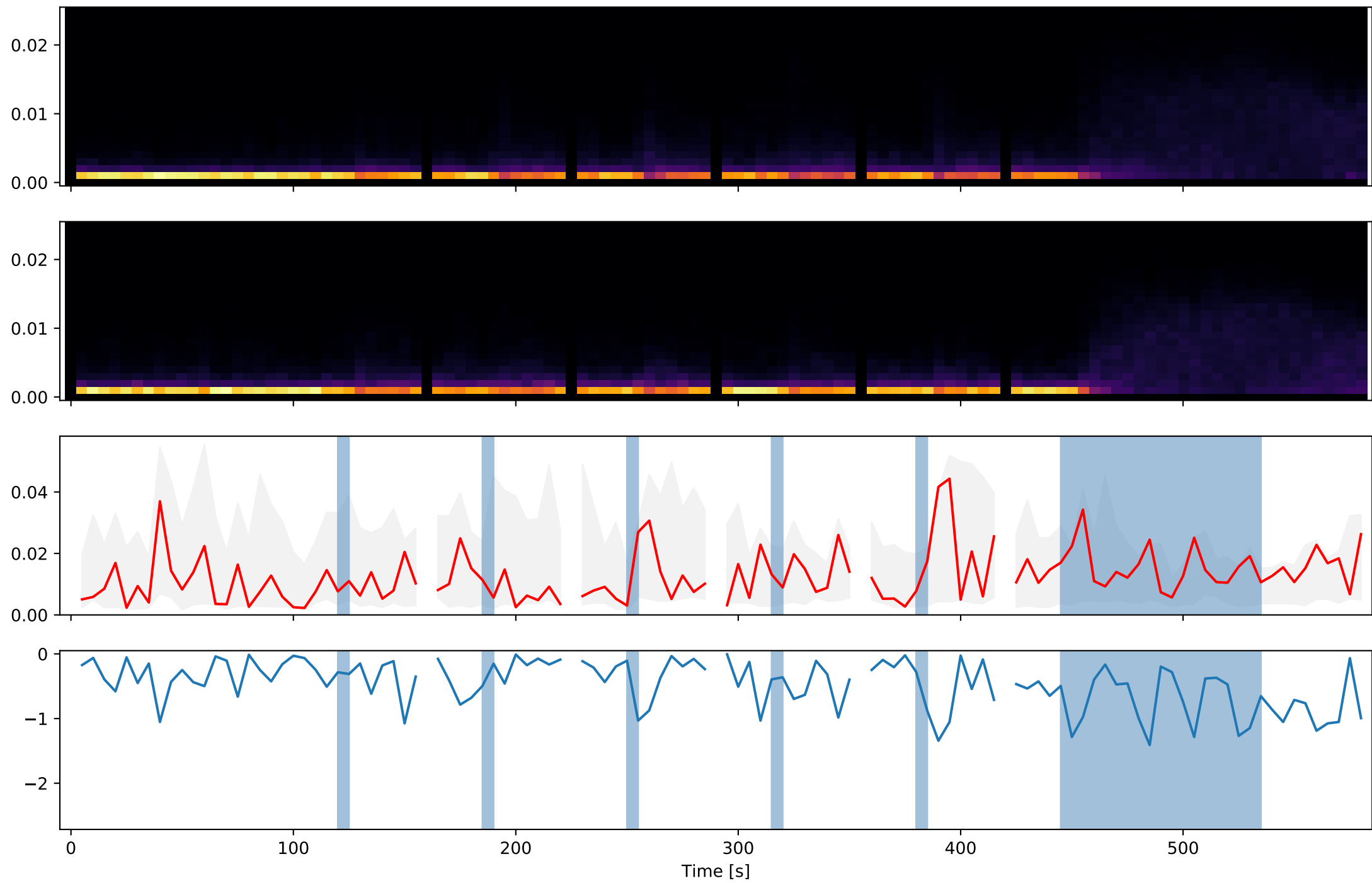


d\_quirkiness - pval: 0.4406047516198704

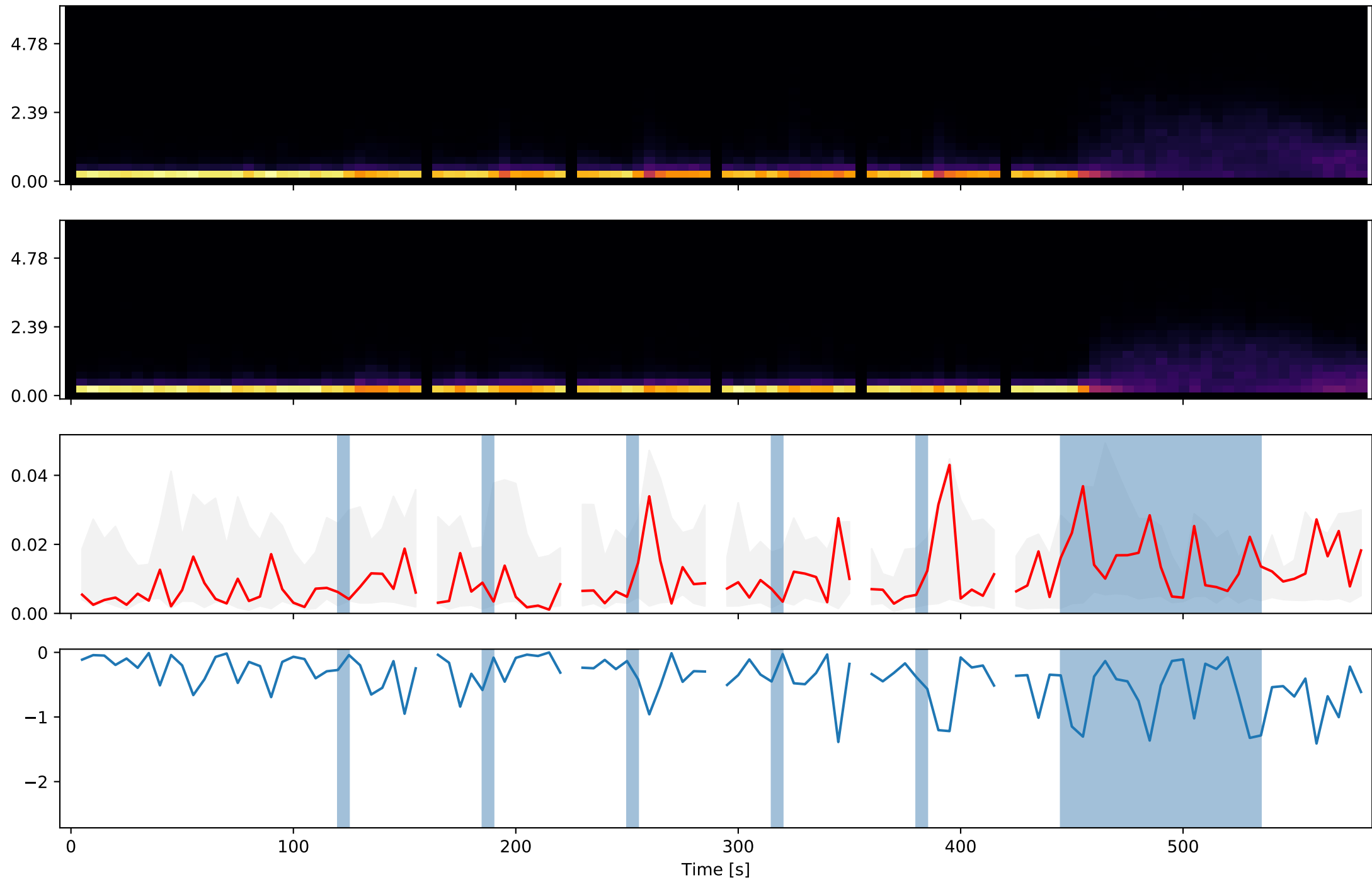




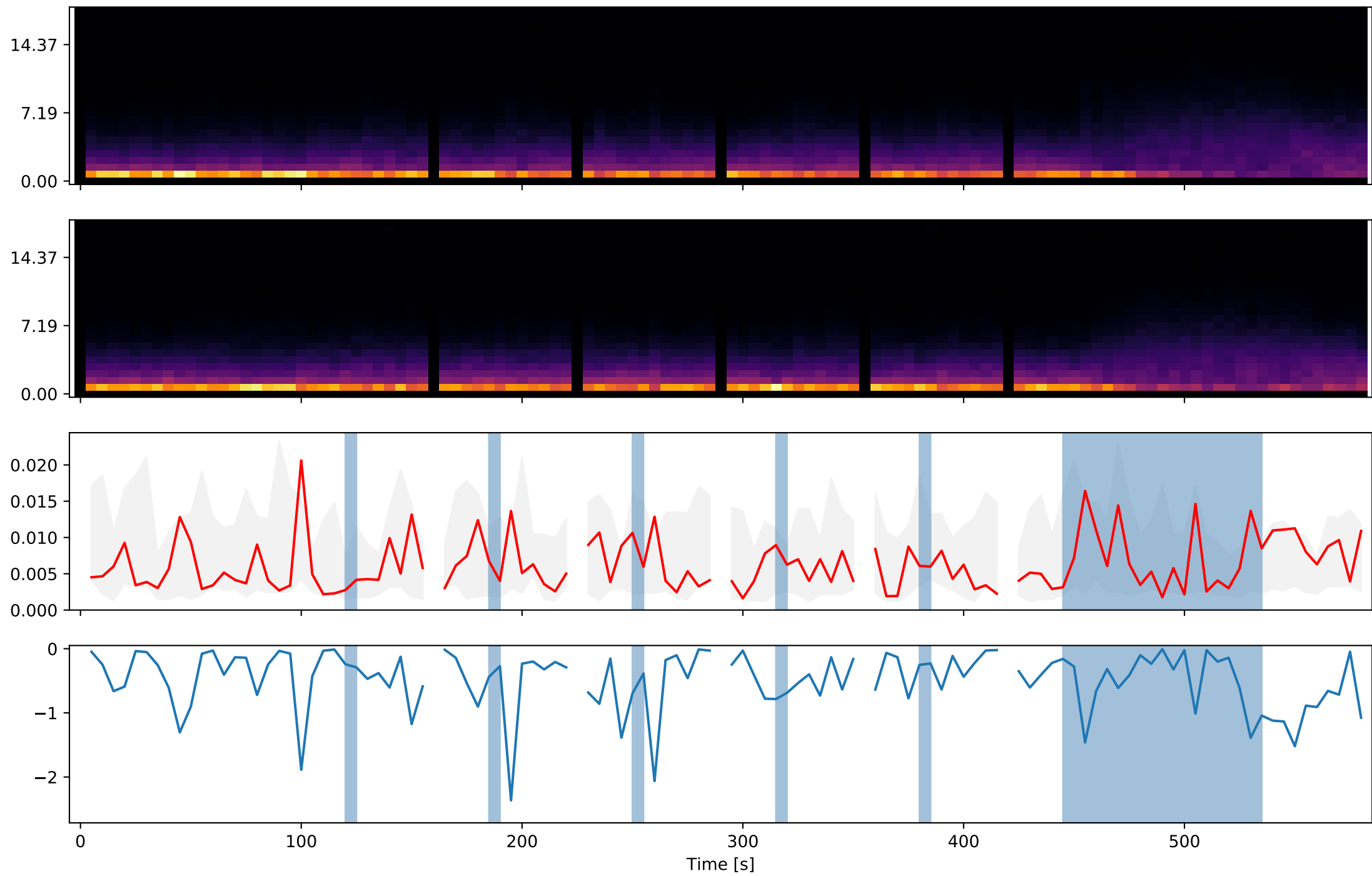
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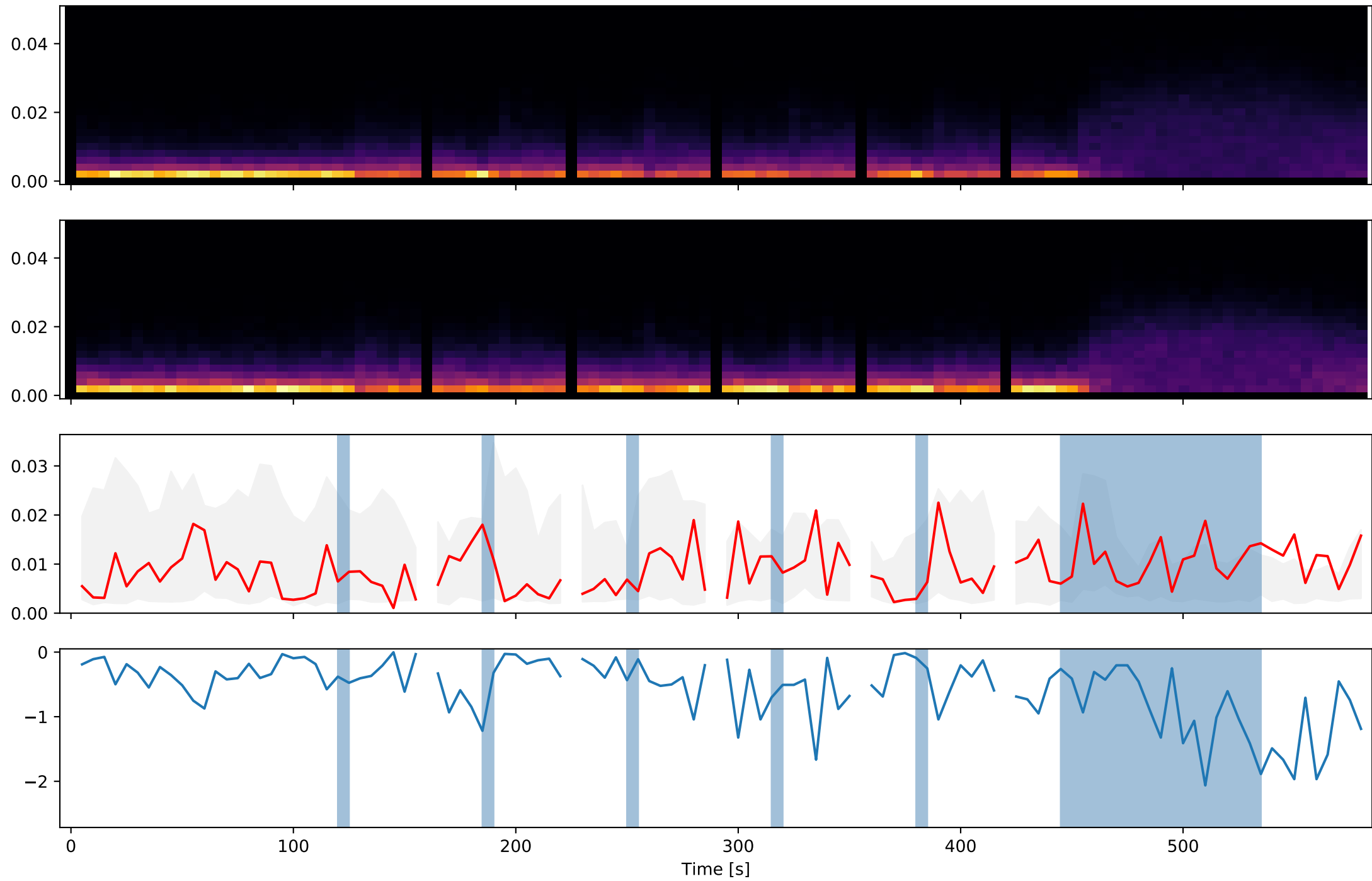
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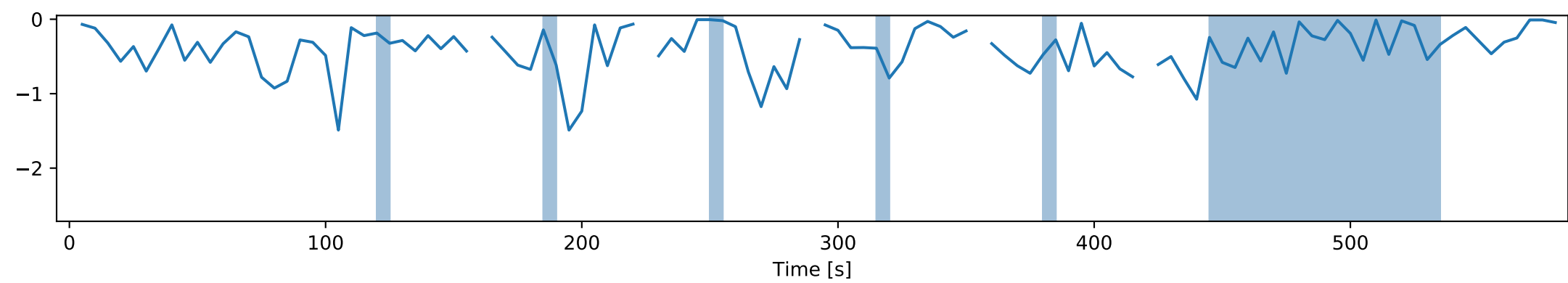
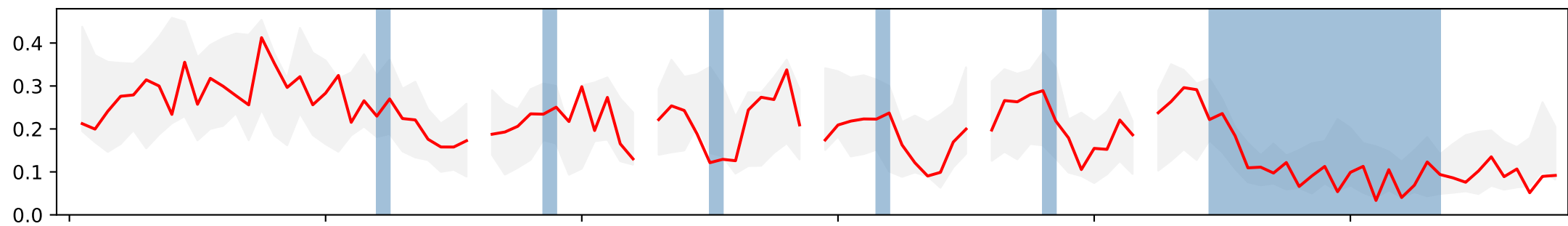
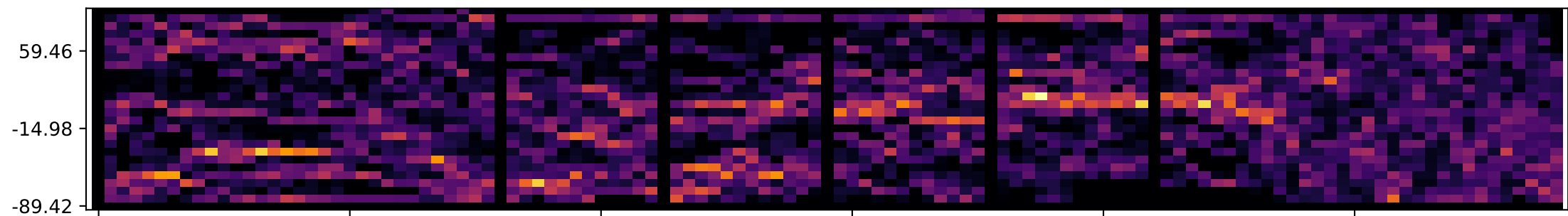
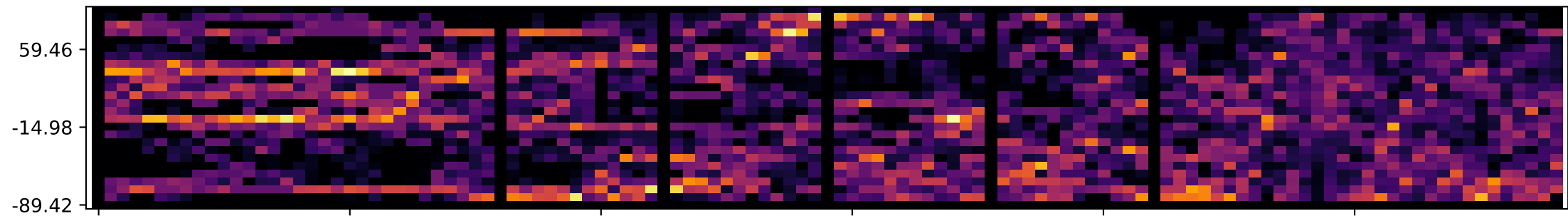
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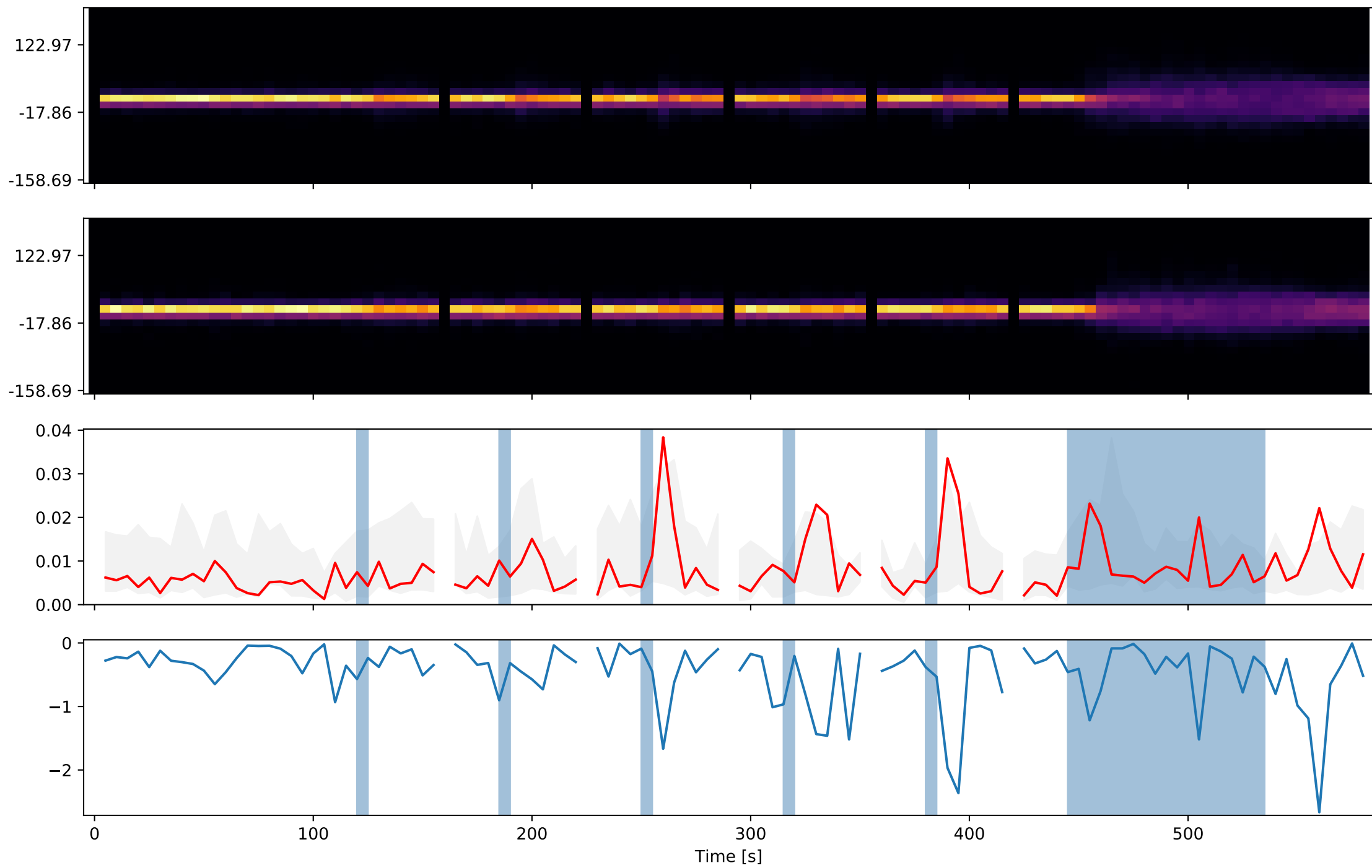
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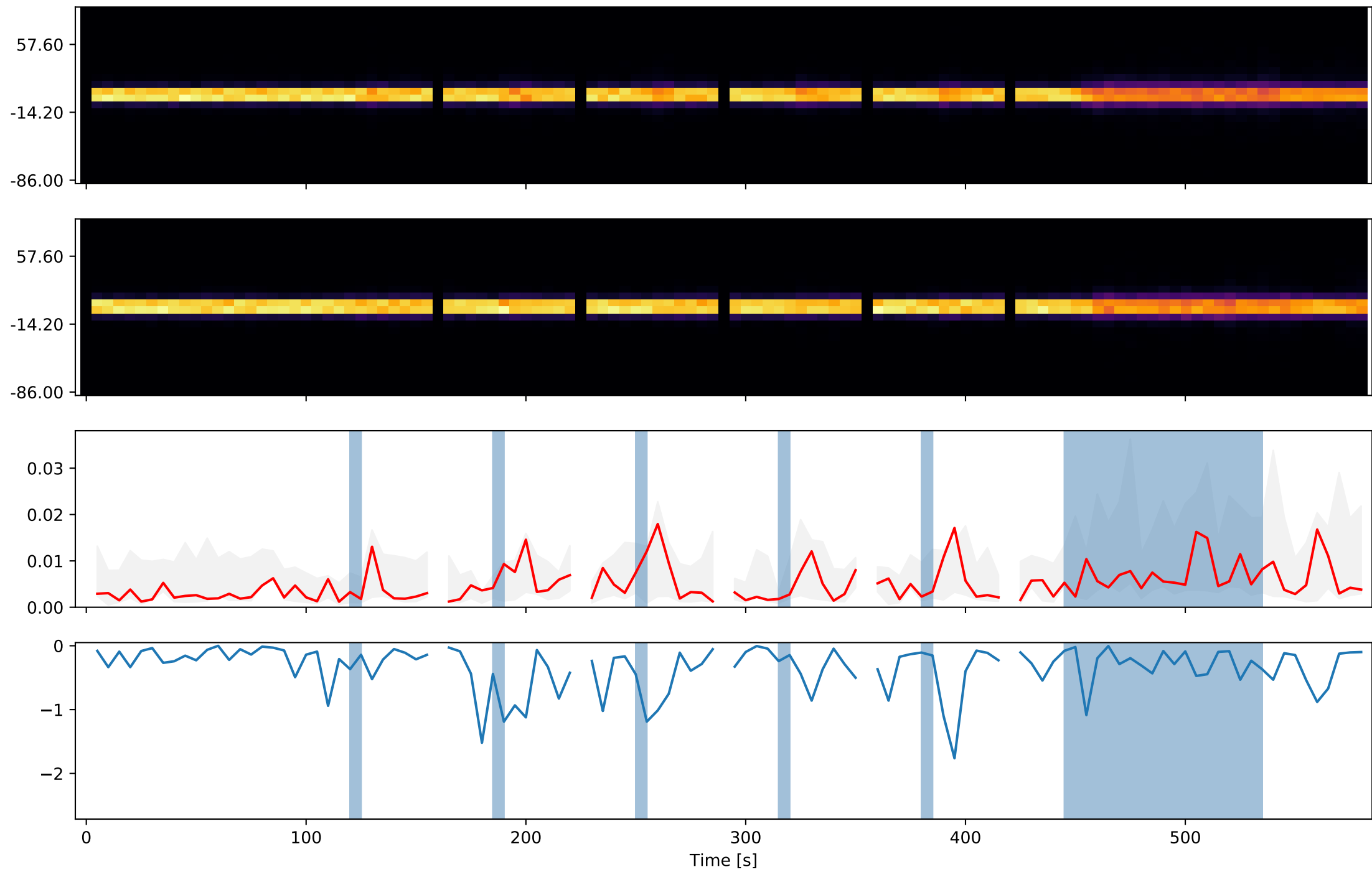
orientation\_food\_edge - pval: 0.4535637149028078



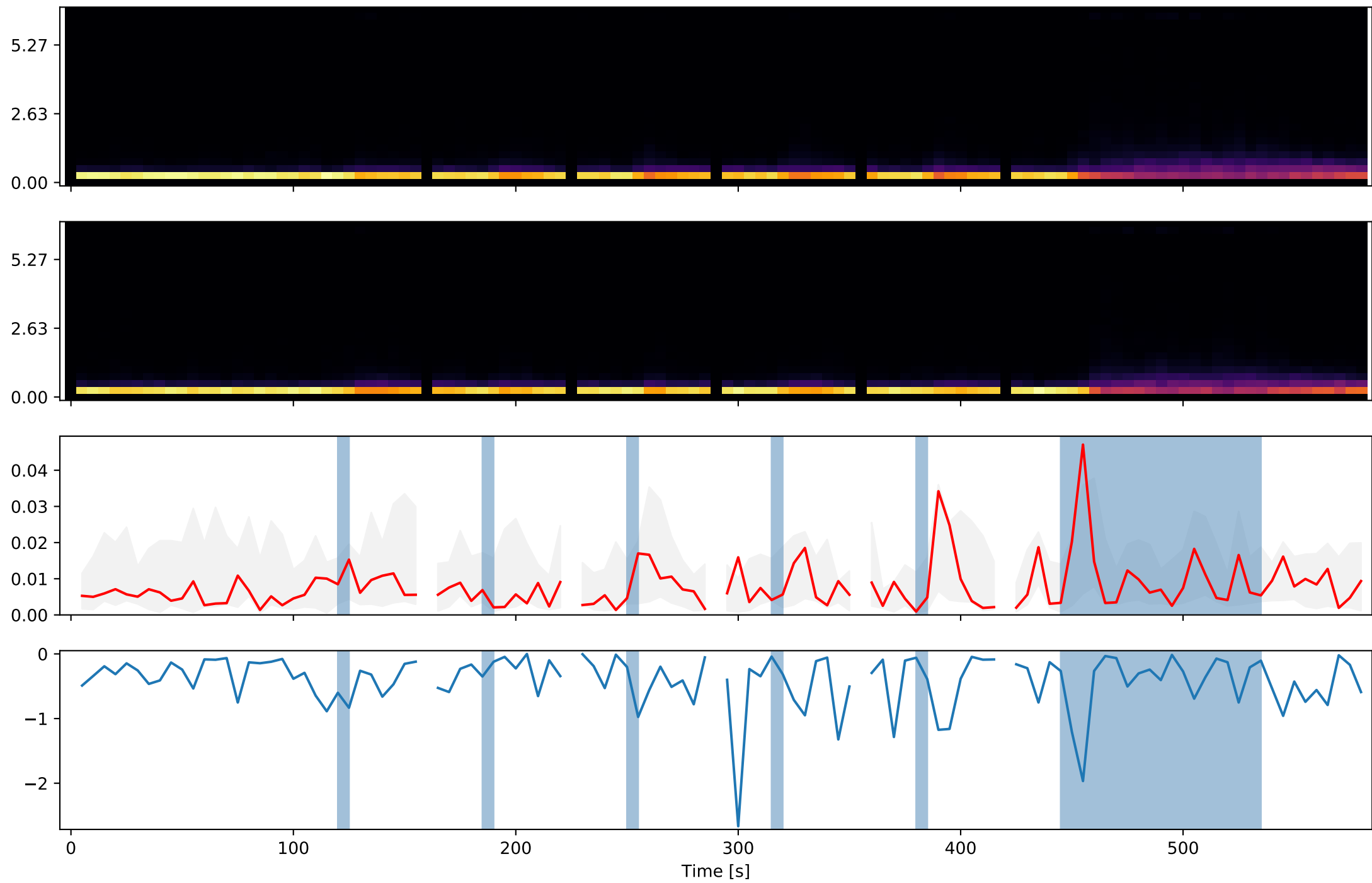
relative\_to\_hips\_radial\_velocity\_tail\_tip - pval: 0.4557235421166307



relative\_to\_tail\_base\_radial\_velocity\_tail\_tip - pval: 0.4557235421166307

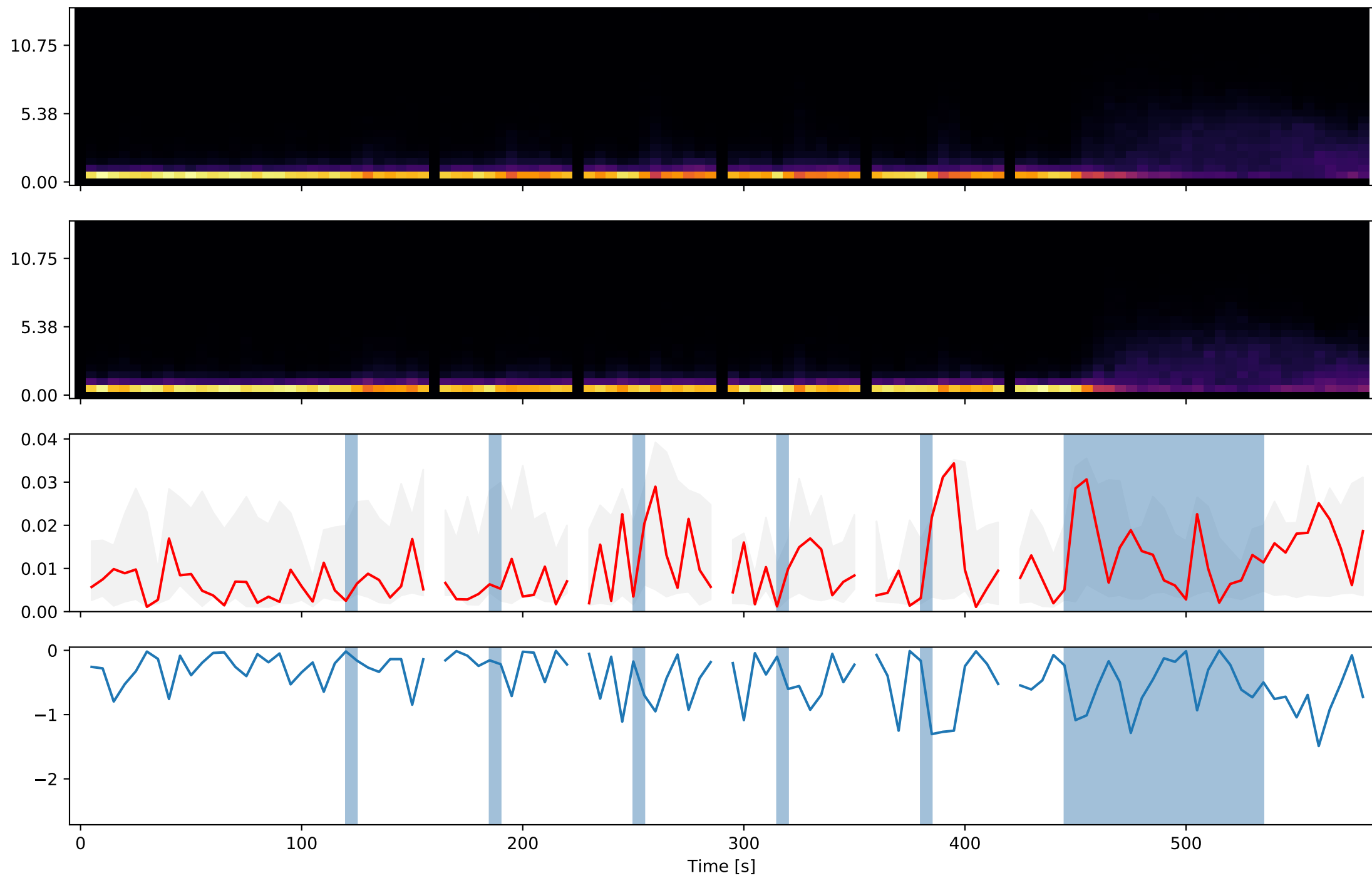


d\_angular\_velocity - pval: 0.4557235421166307

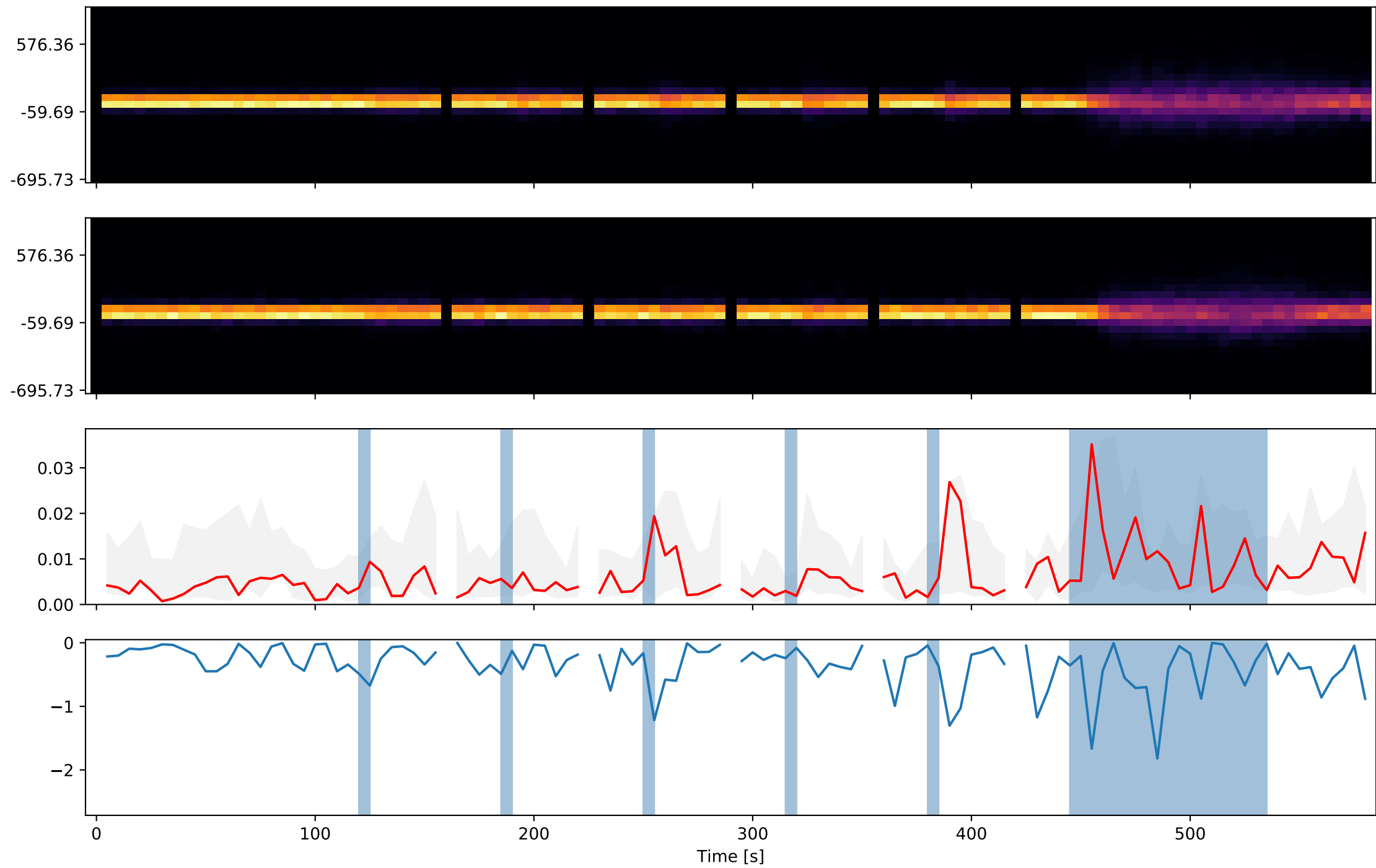




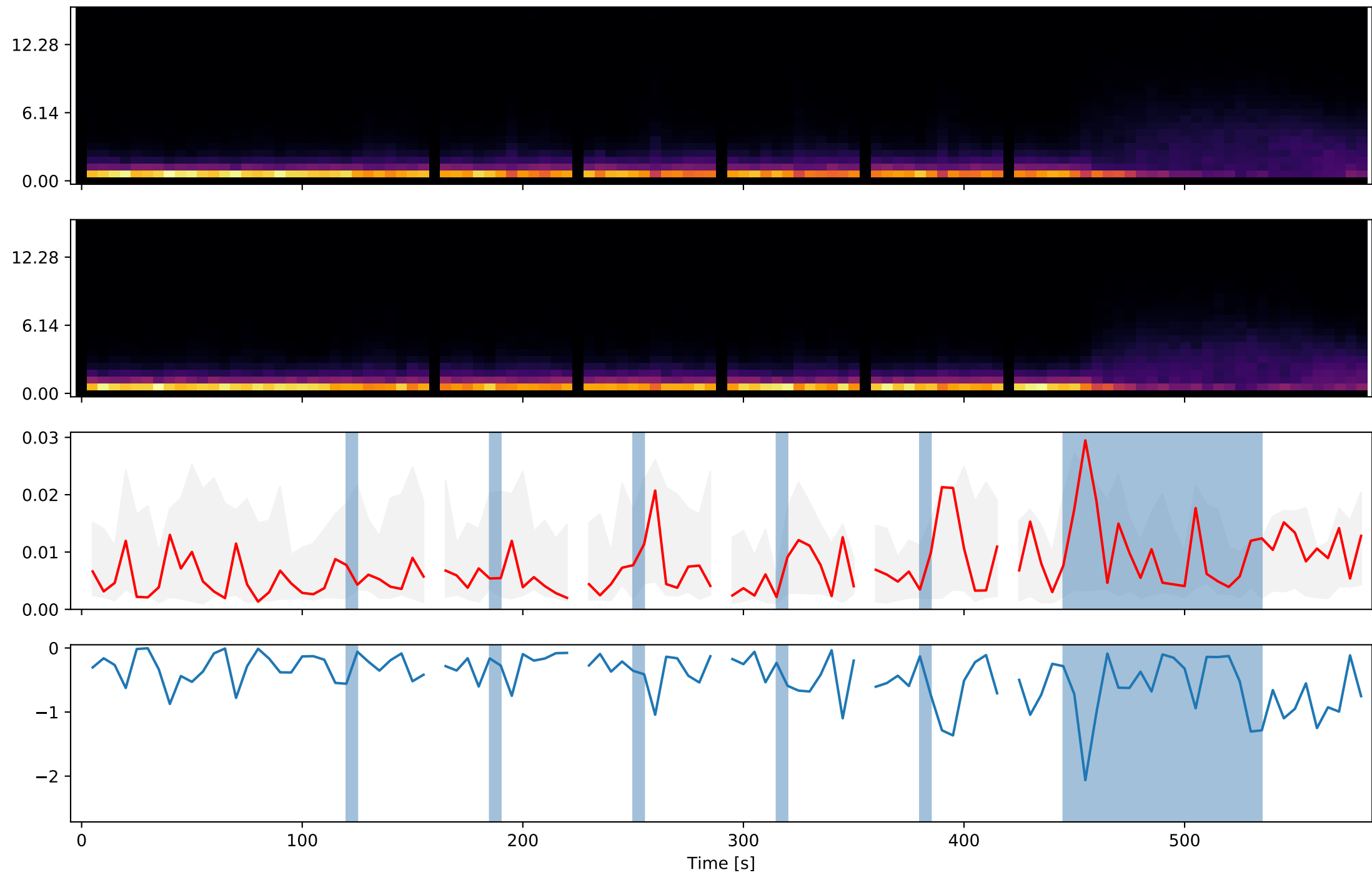
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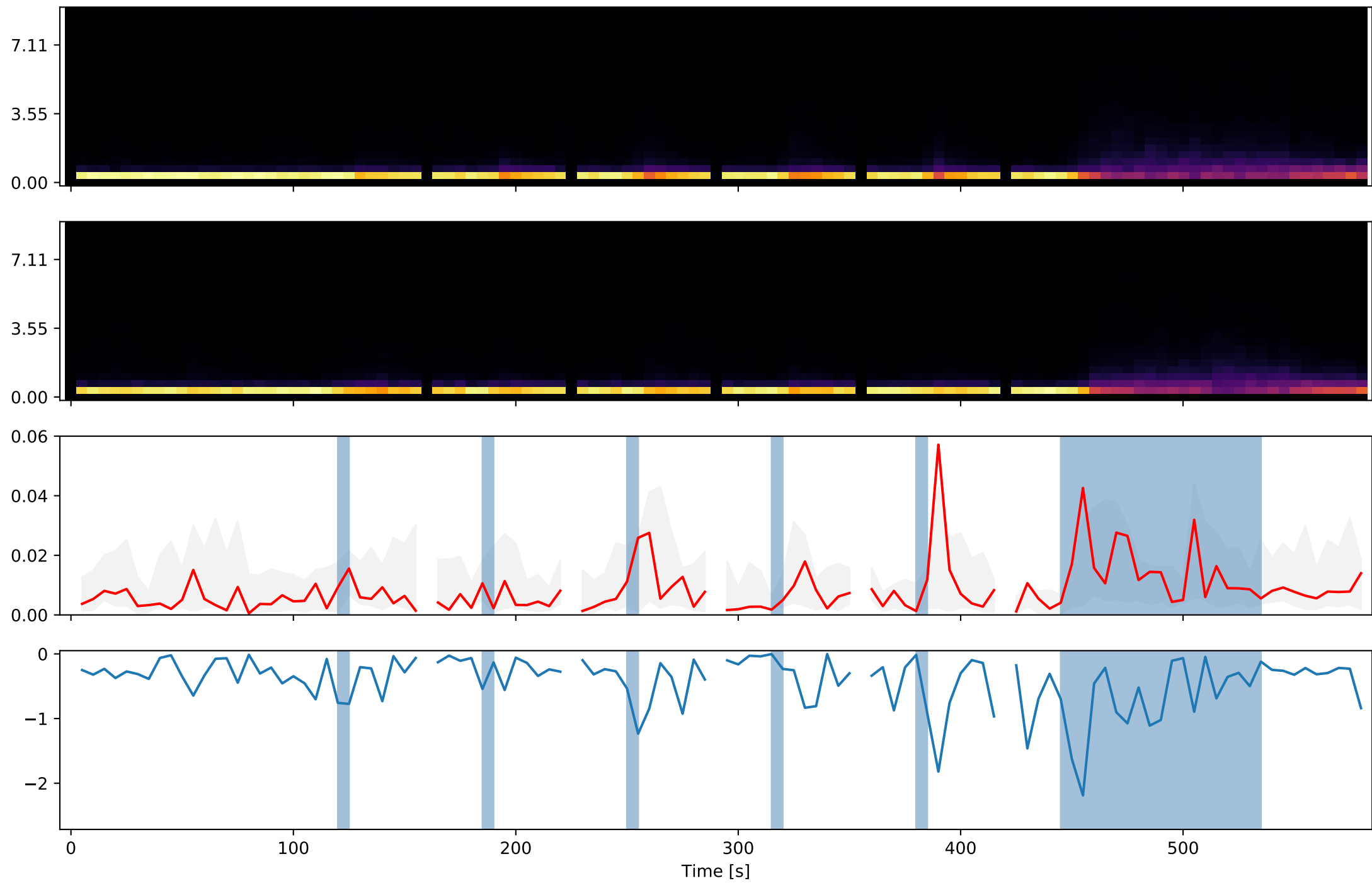
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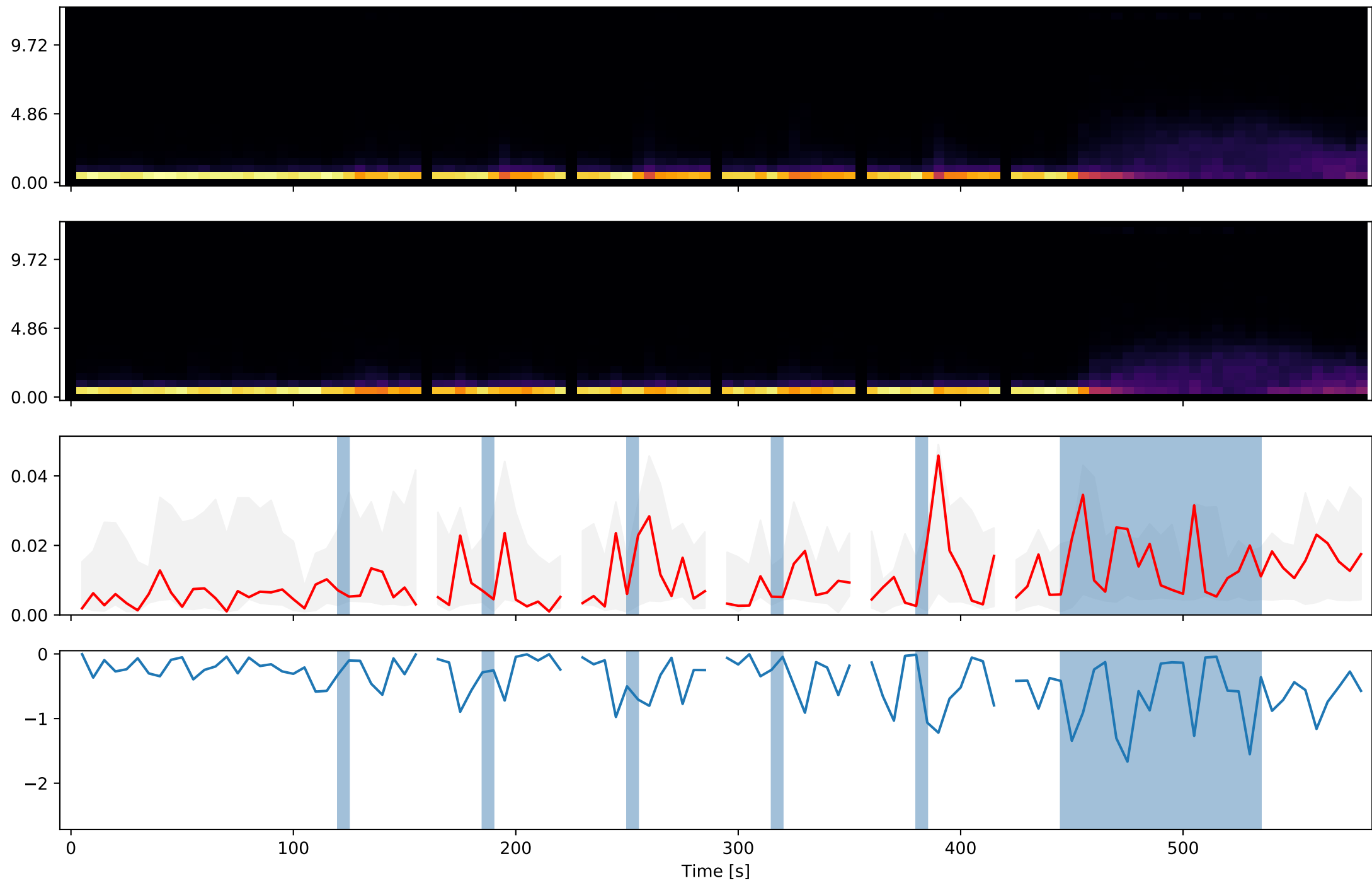
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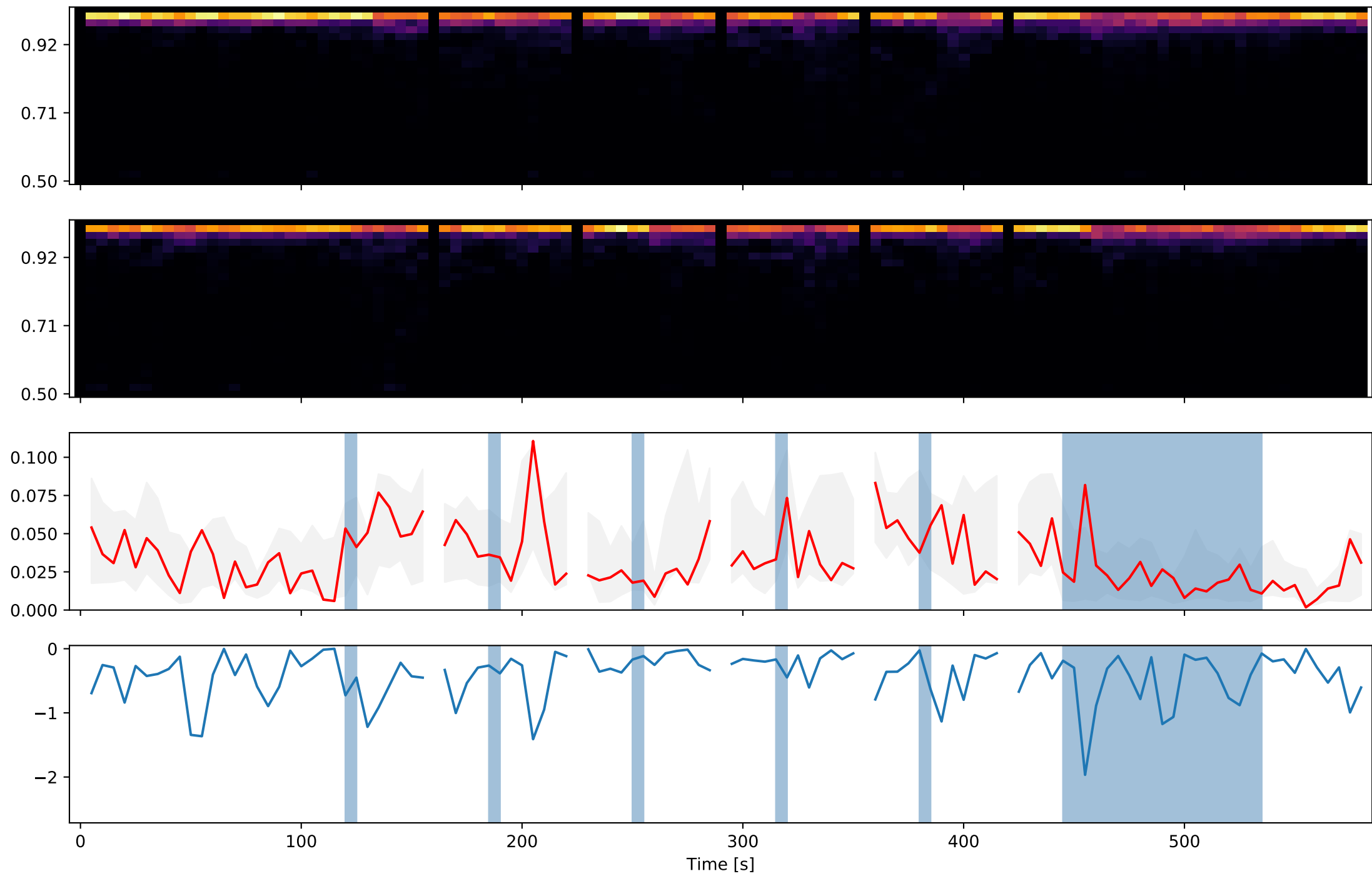
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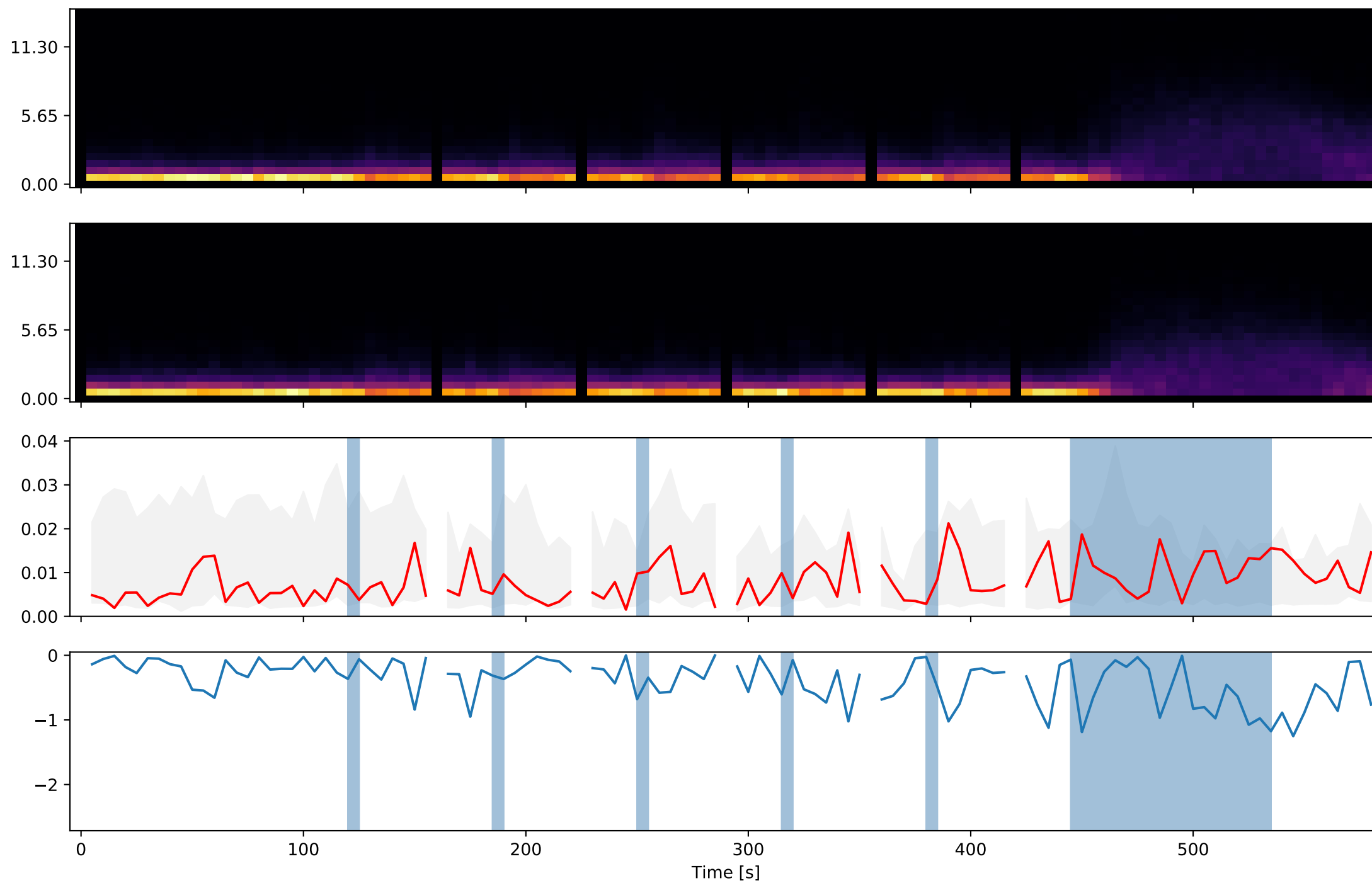
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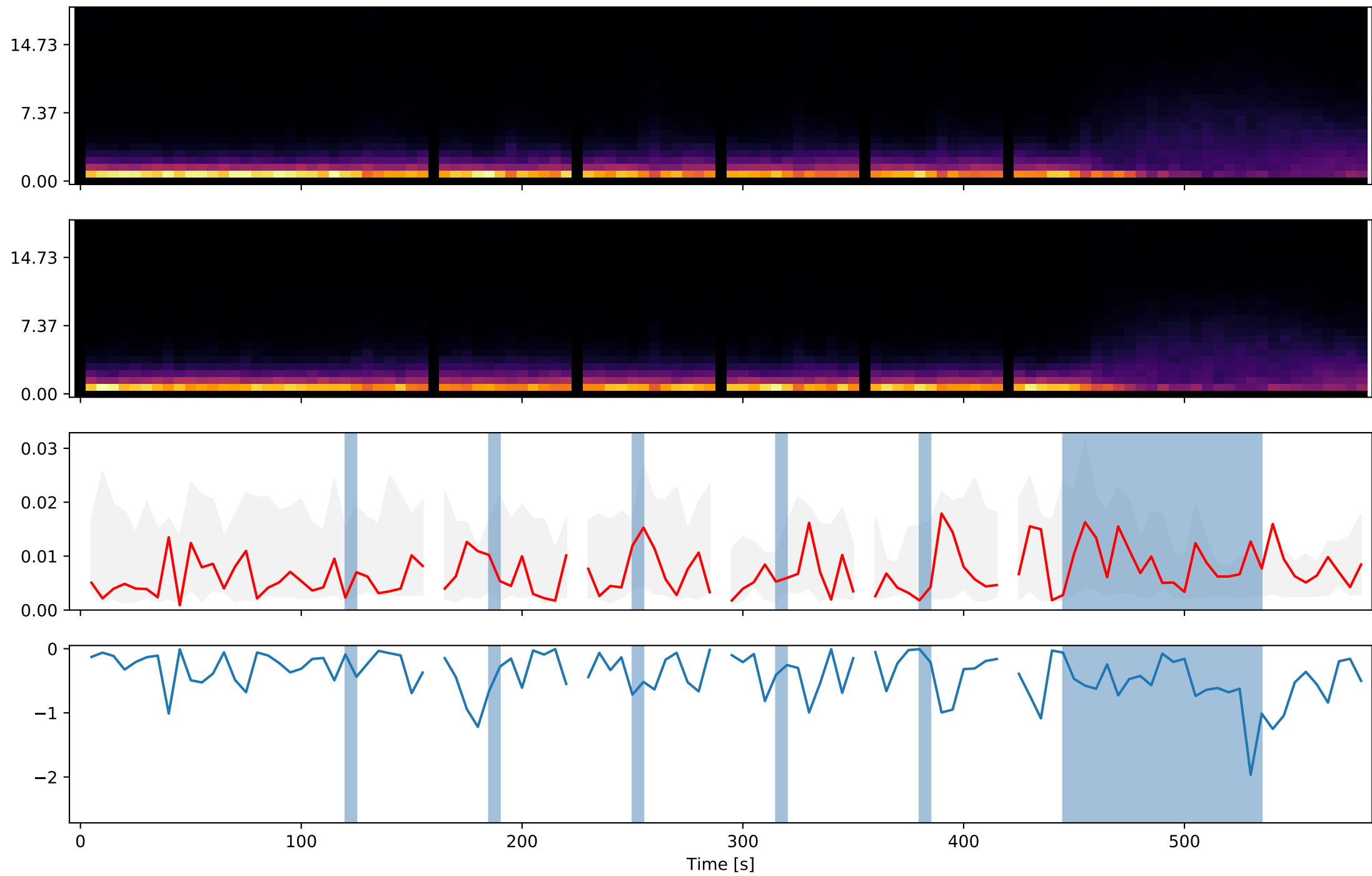
quirkiness - pval: 0.5032397408207343



d\_relative\_to\_neck\_angular\_velocity\_head\_tip - pval: 0.5032397408207343

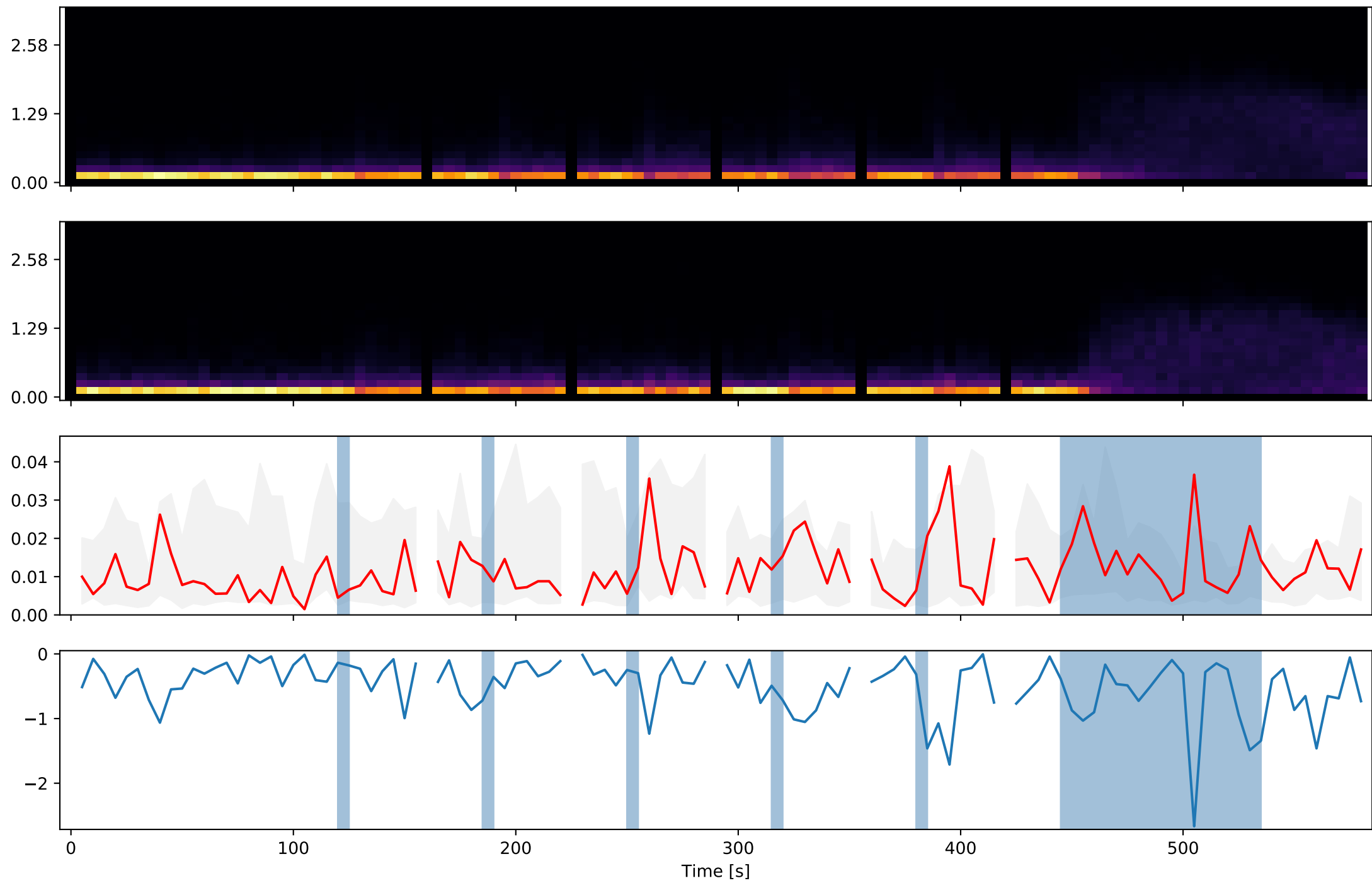


d\_angular\_velocity\_head\_base - pval: 0.5053995680345572

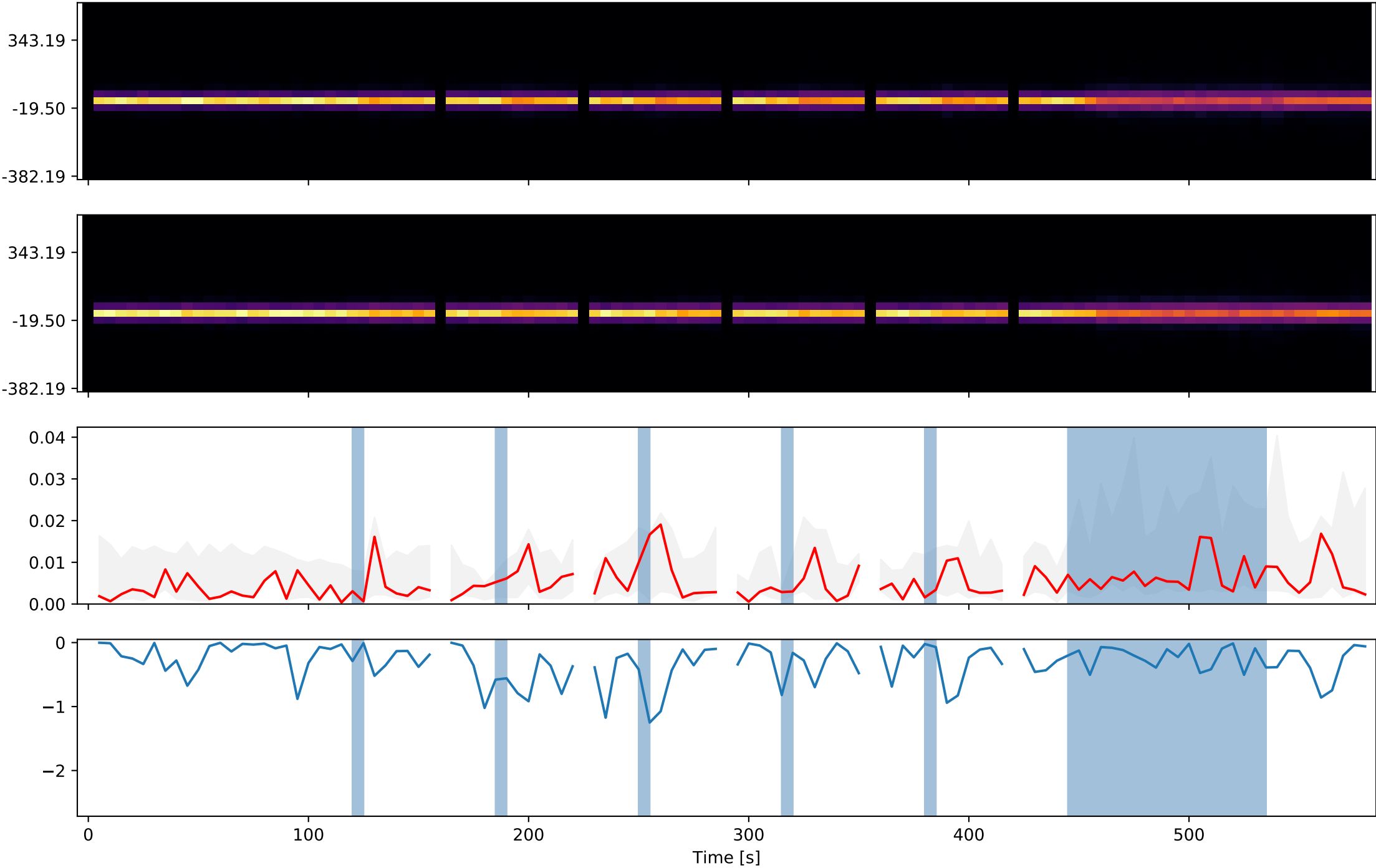




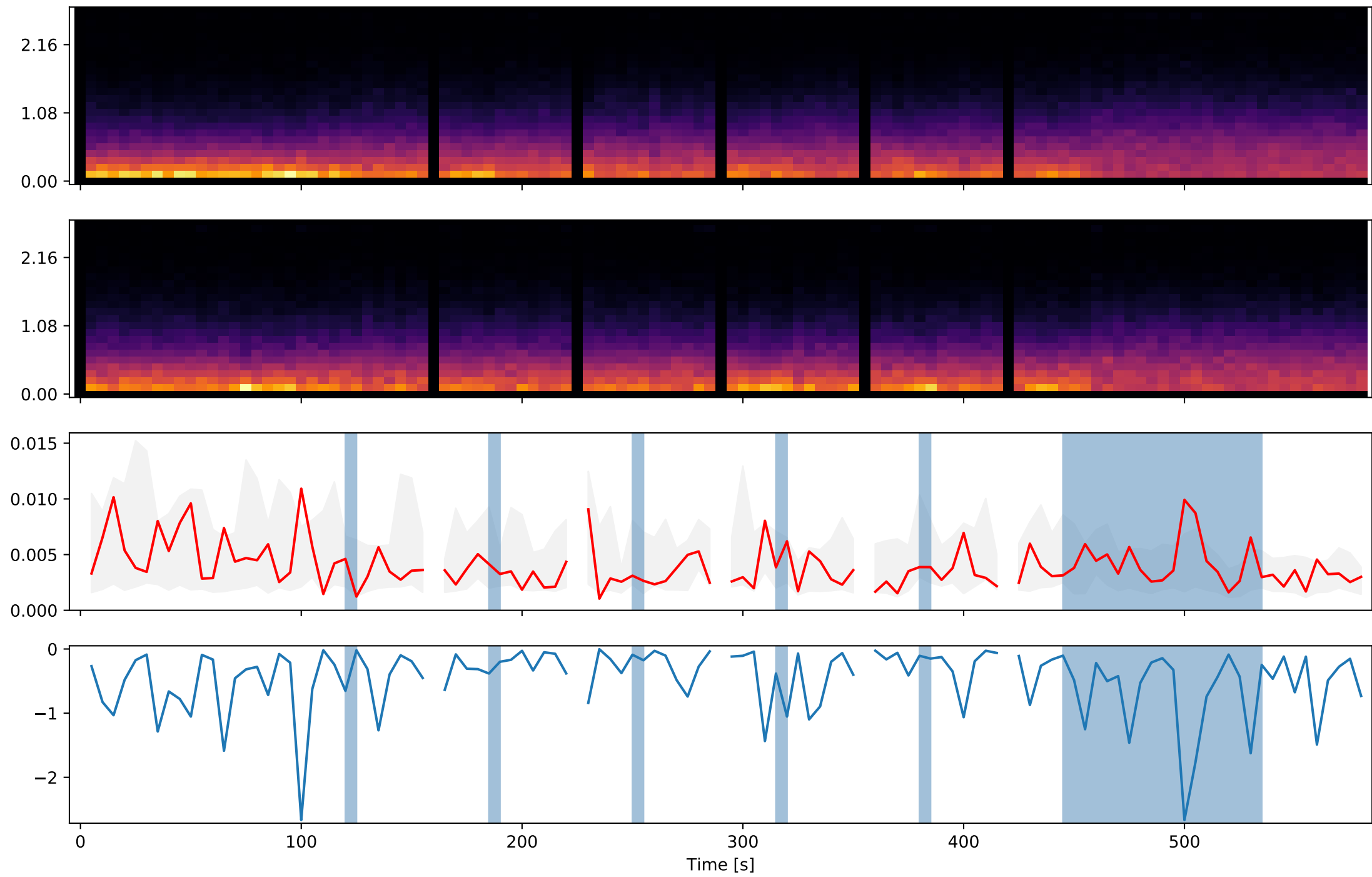
relative\_to\_hips\_angular\_velocity\_tail\_tip - pval: 0.5183585313174947



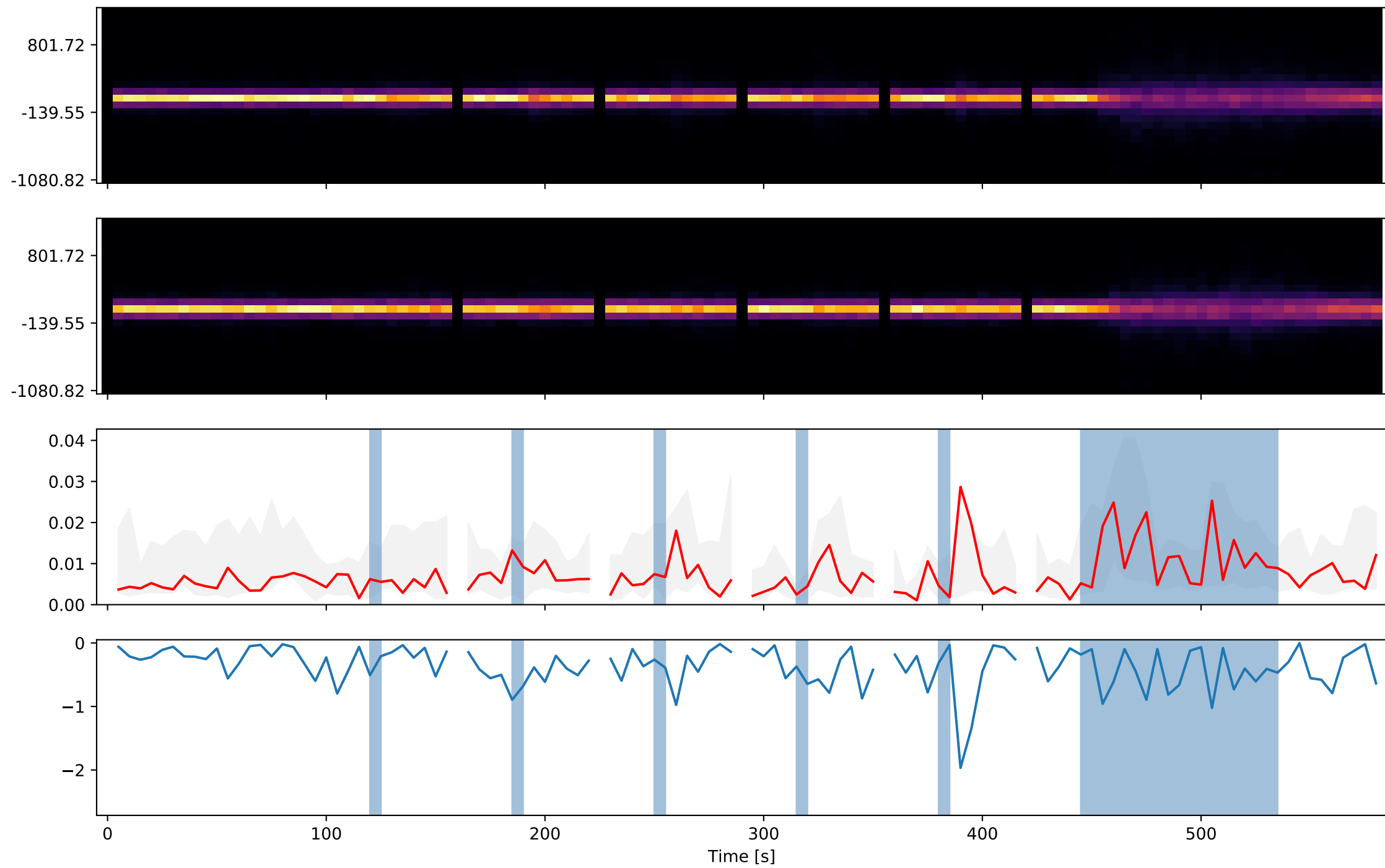
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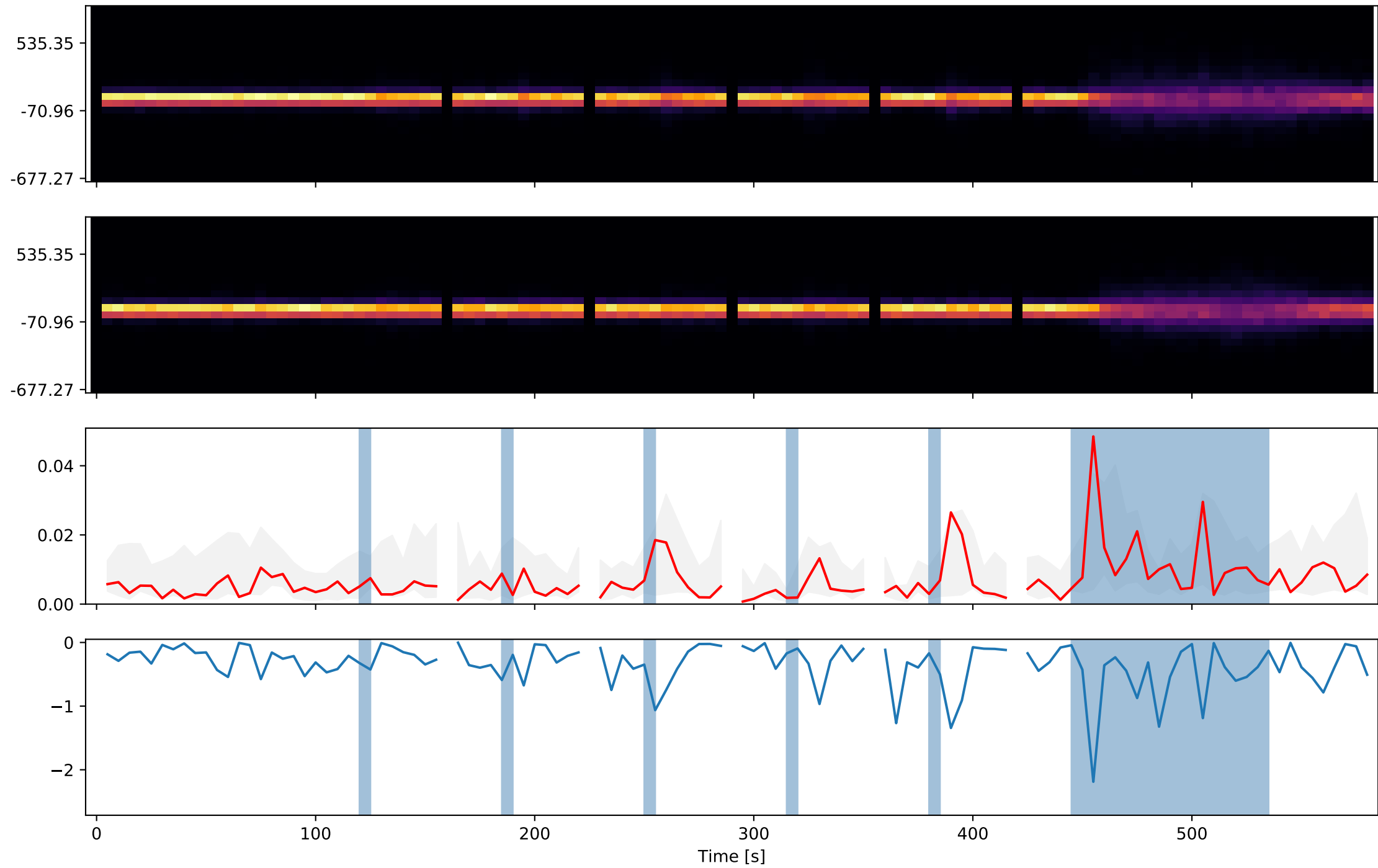
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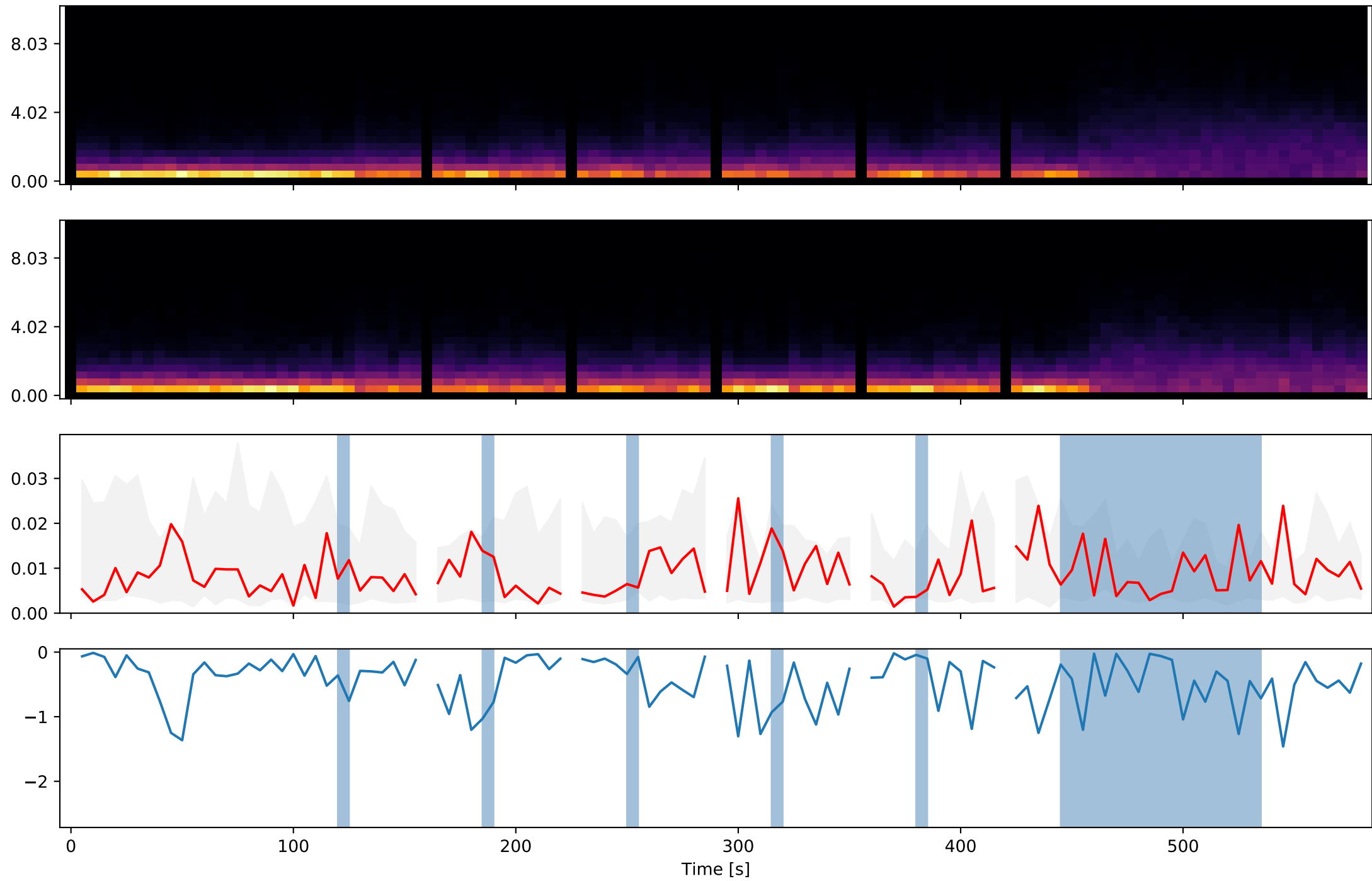
d\_relative\_to\_body\_radial\_velocity\_tail\_tip - pval: 0.5550755939524838



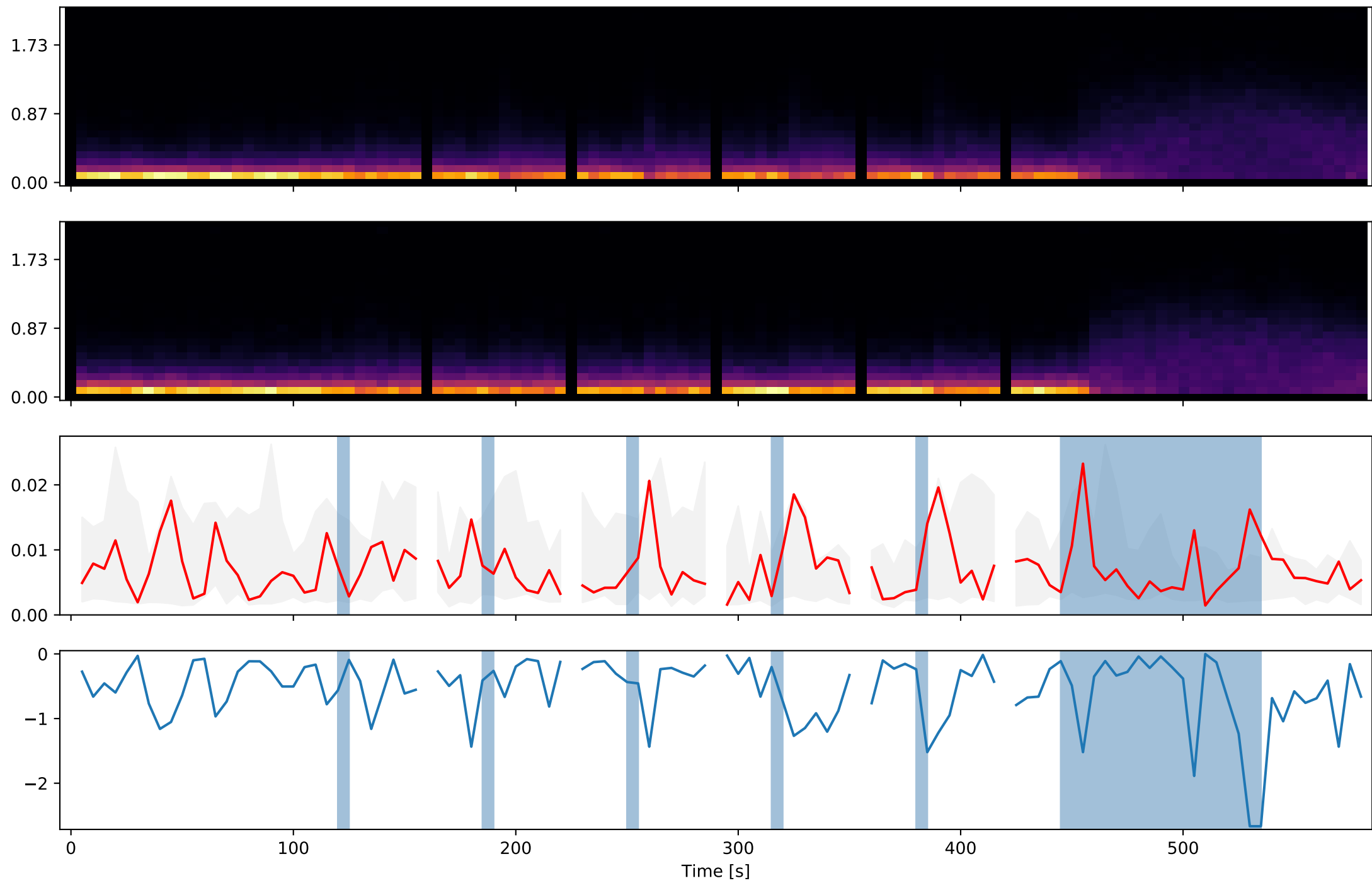
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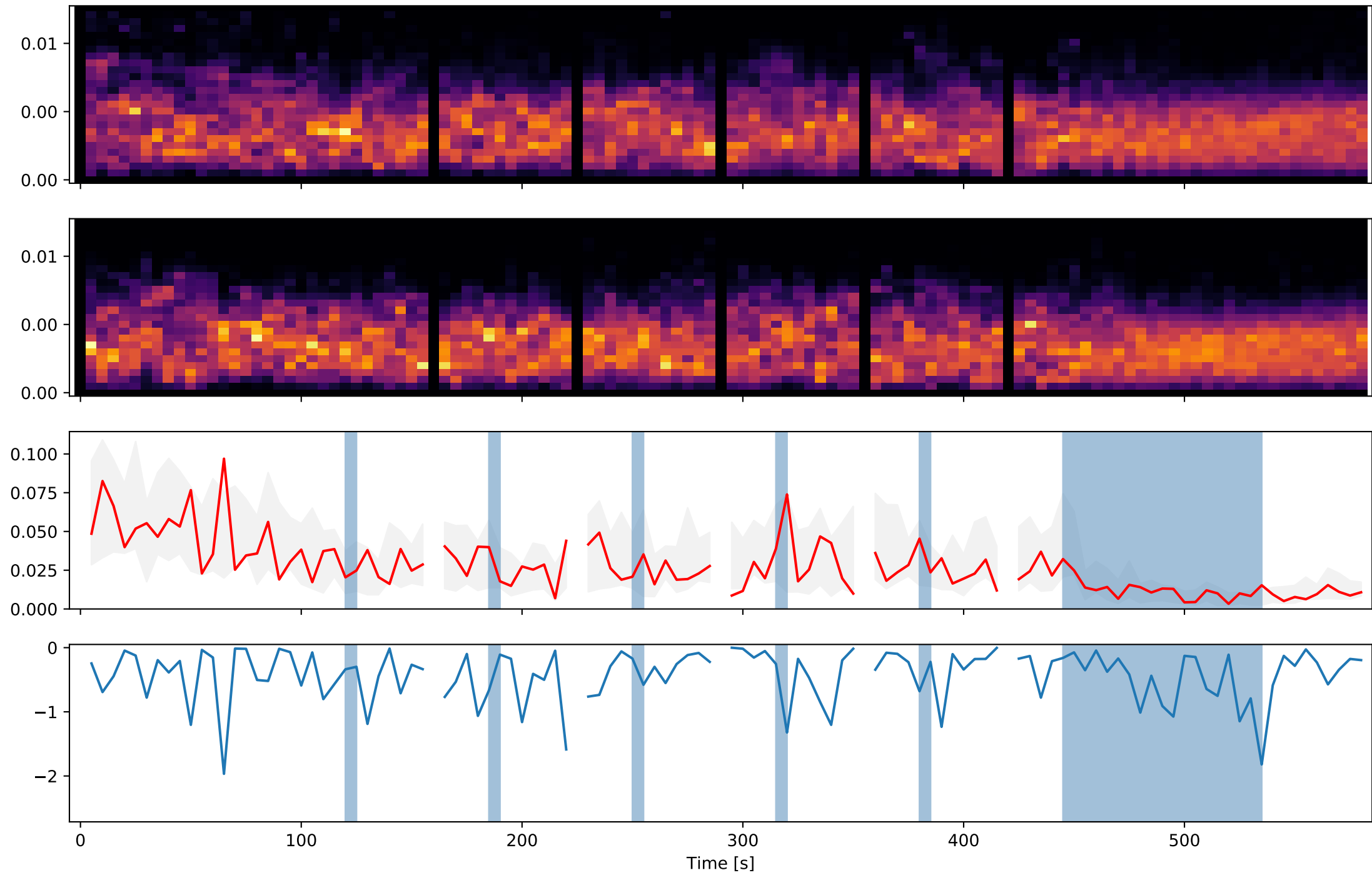
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relative\_to\_tail\_base\_angular\_velocity\_tail\_tip - pval: 0.5680345572354212

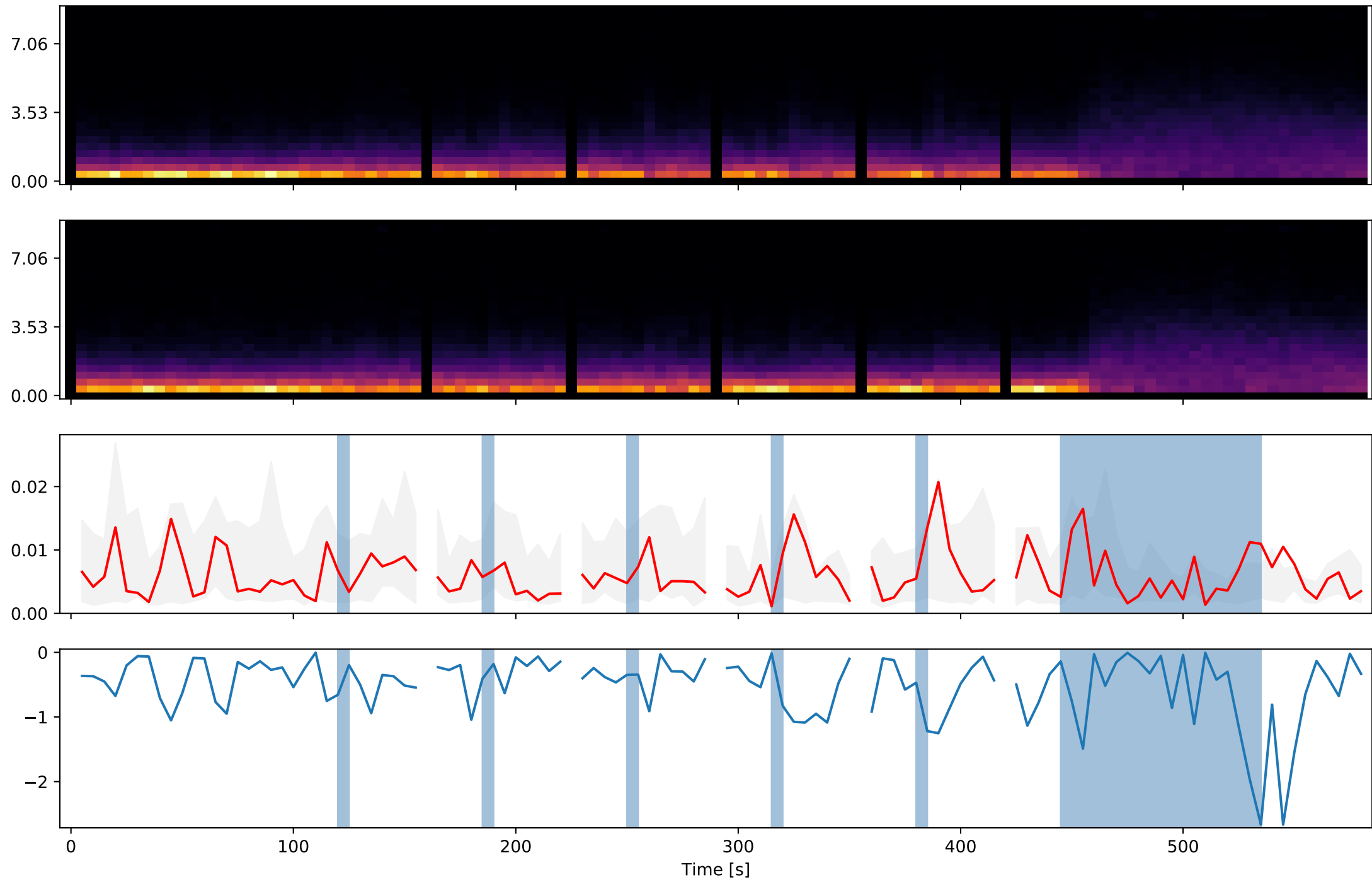


curvature\_std\_hips - pval: 0.572354211663067

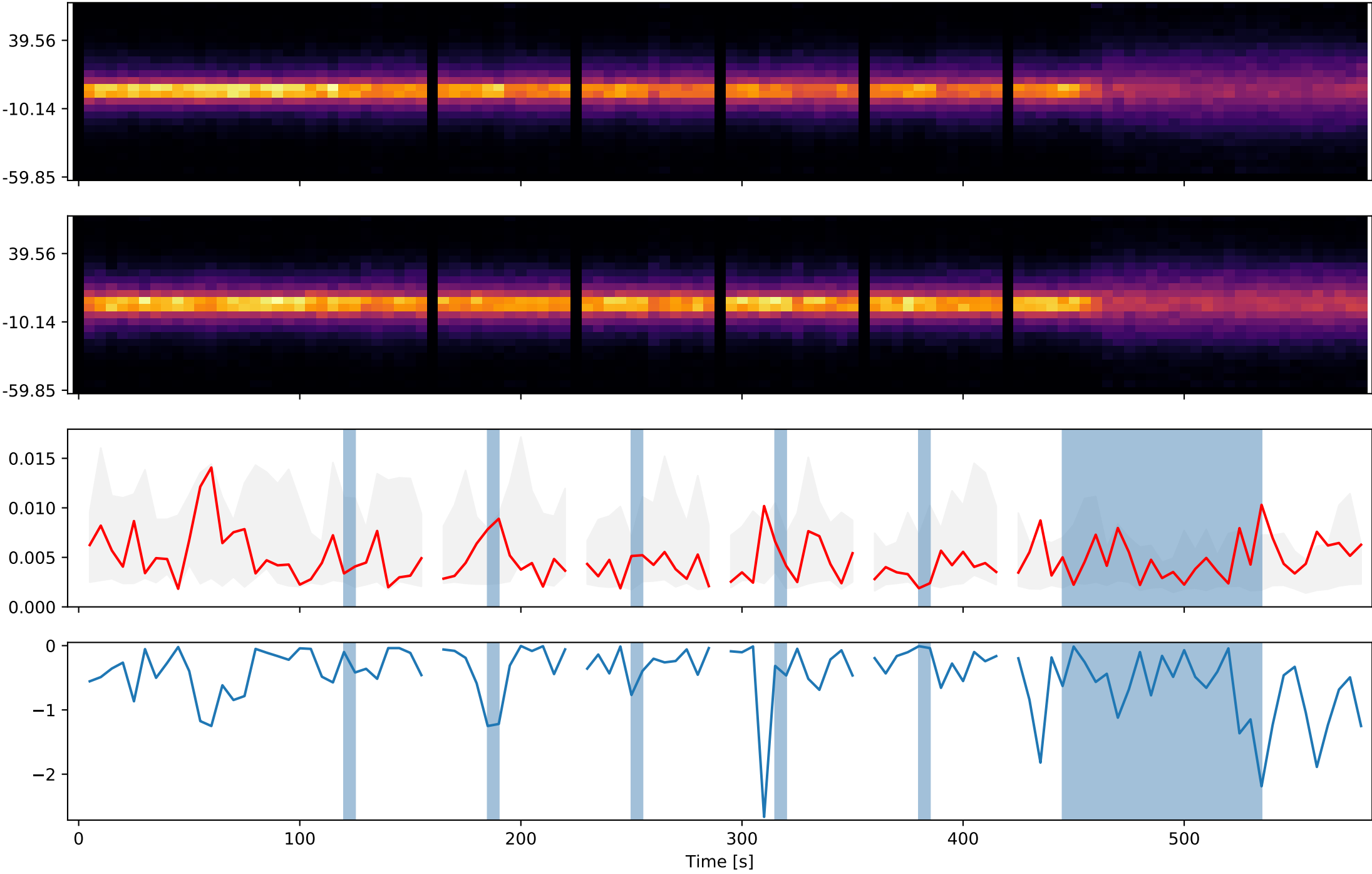




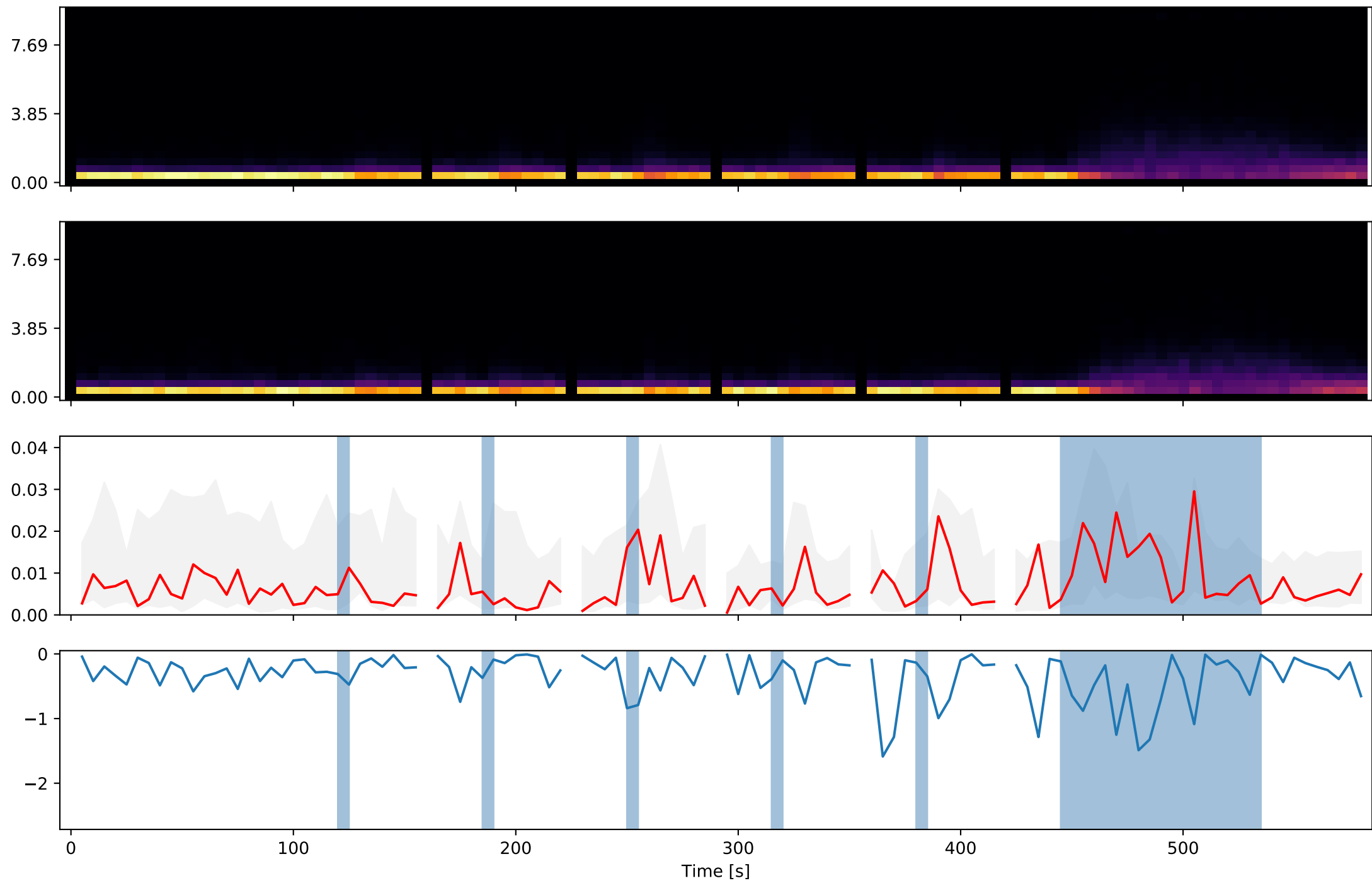
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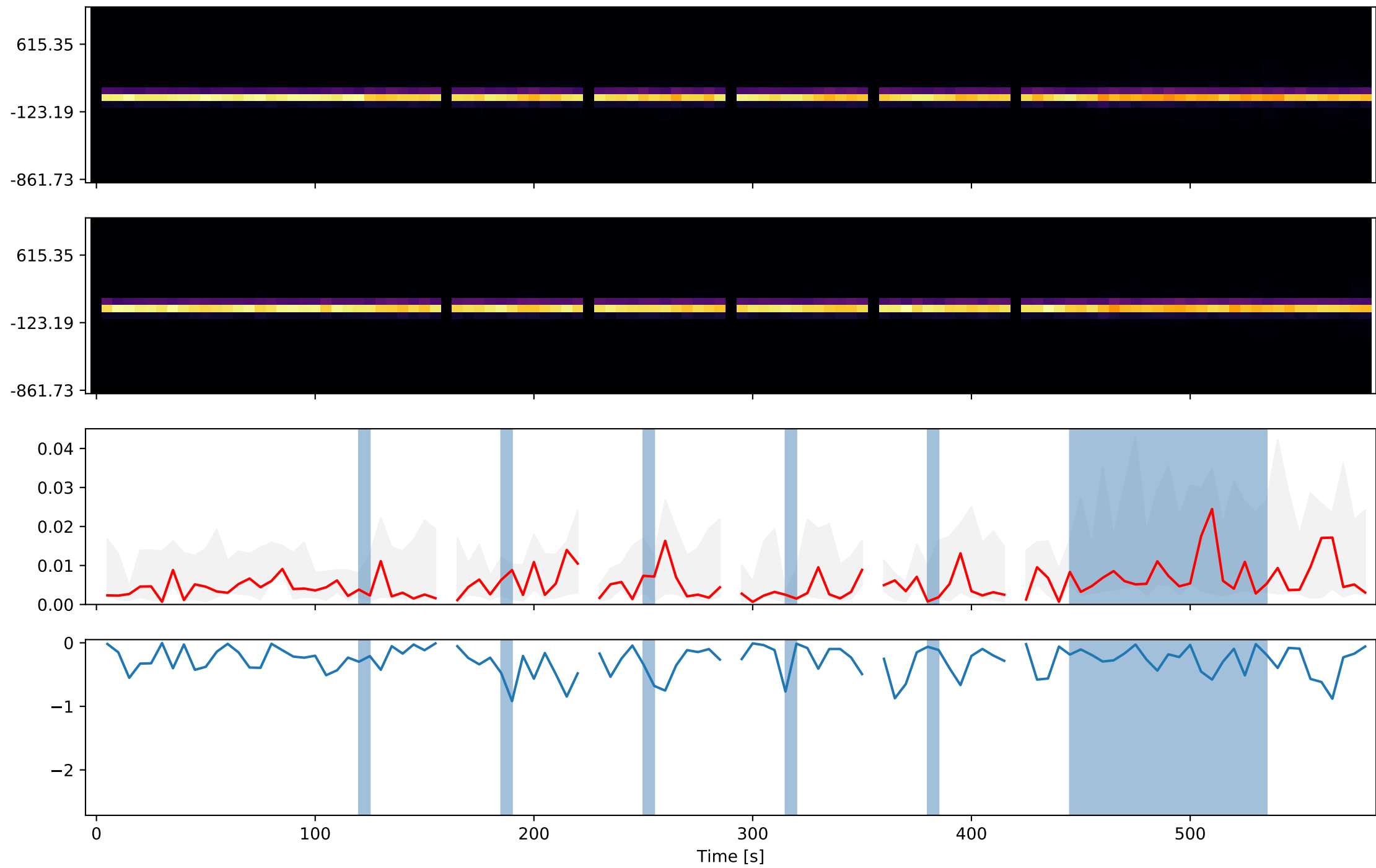
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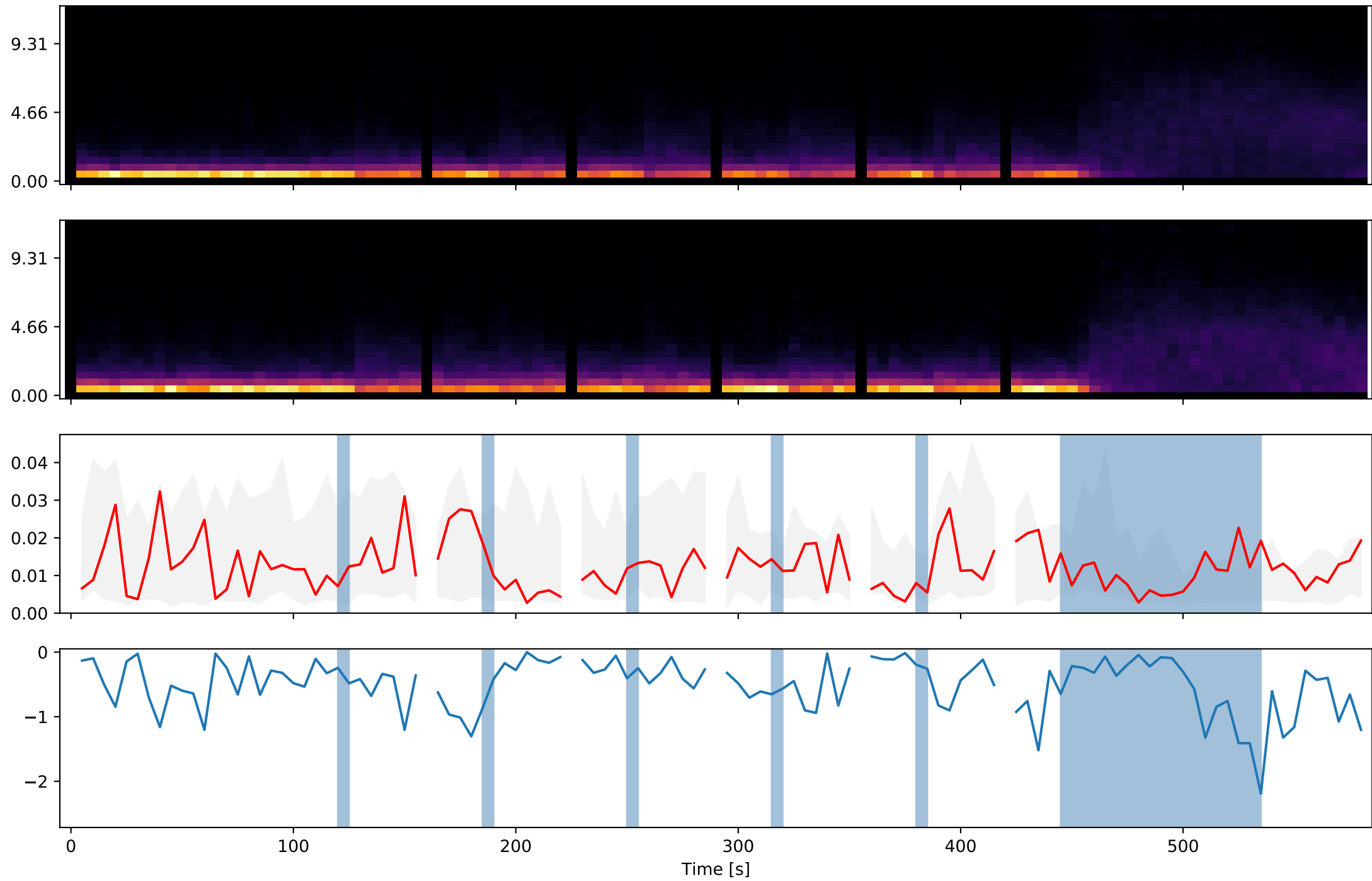
d\_relative\_to\_body\_angular\_velocity\_head\_tip - pval: 0.591792656587473



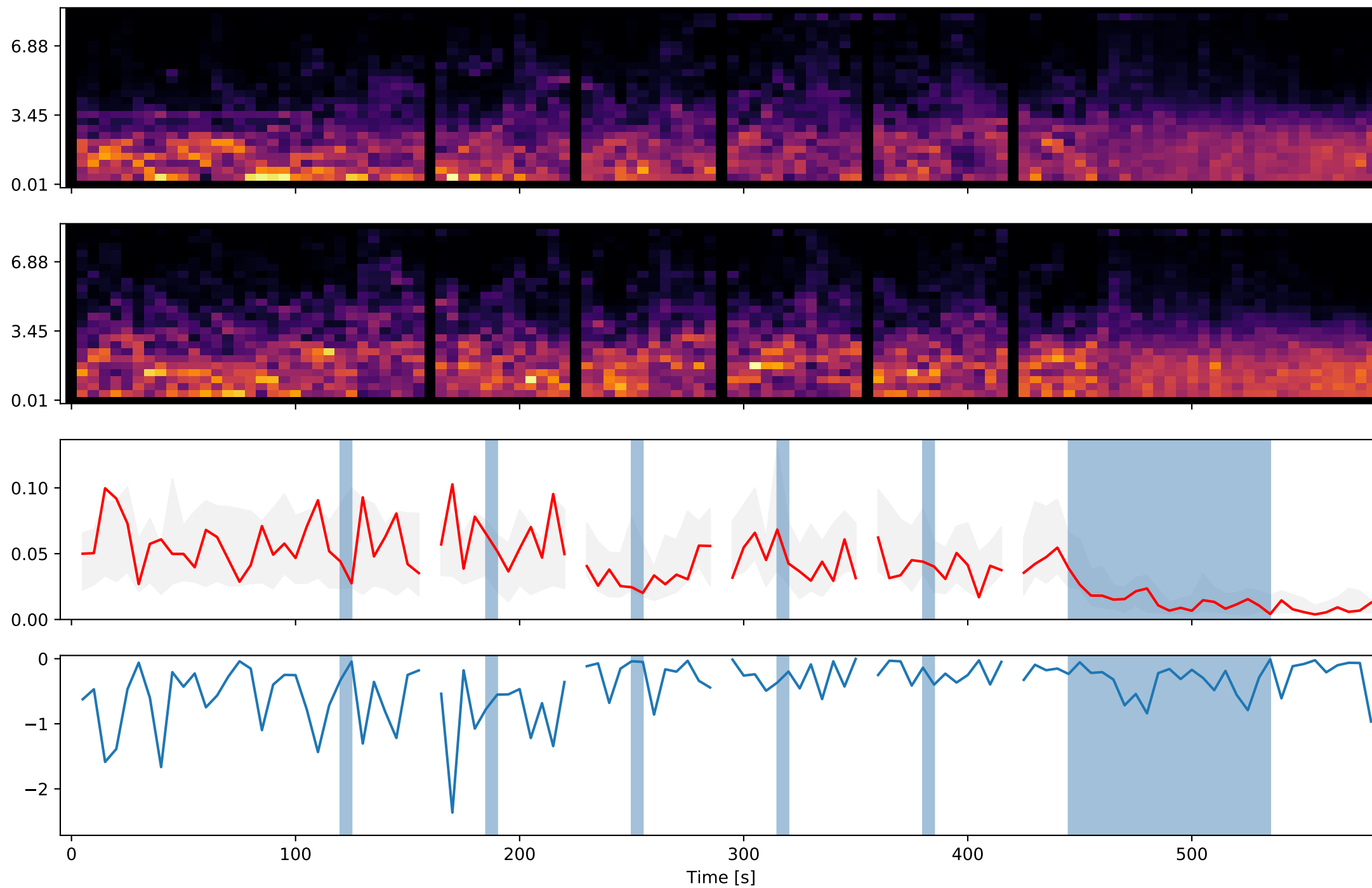
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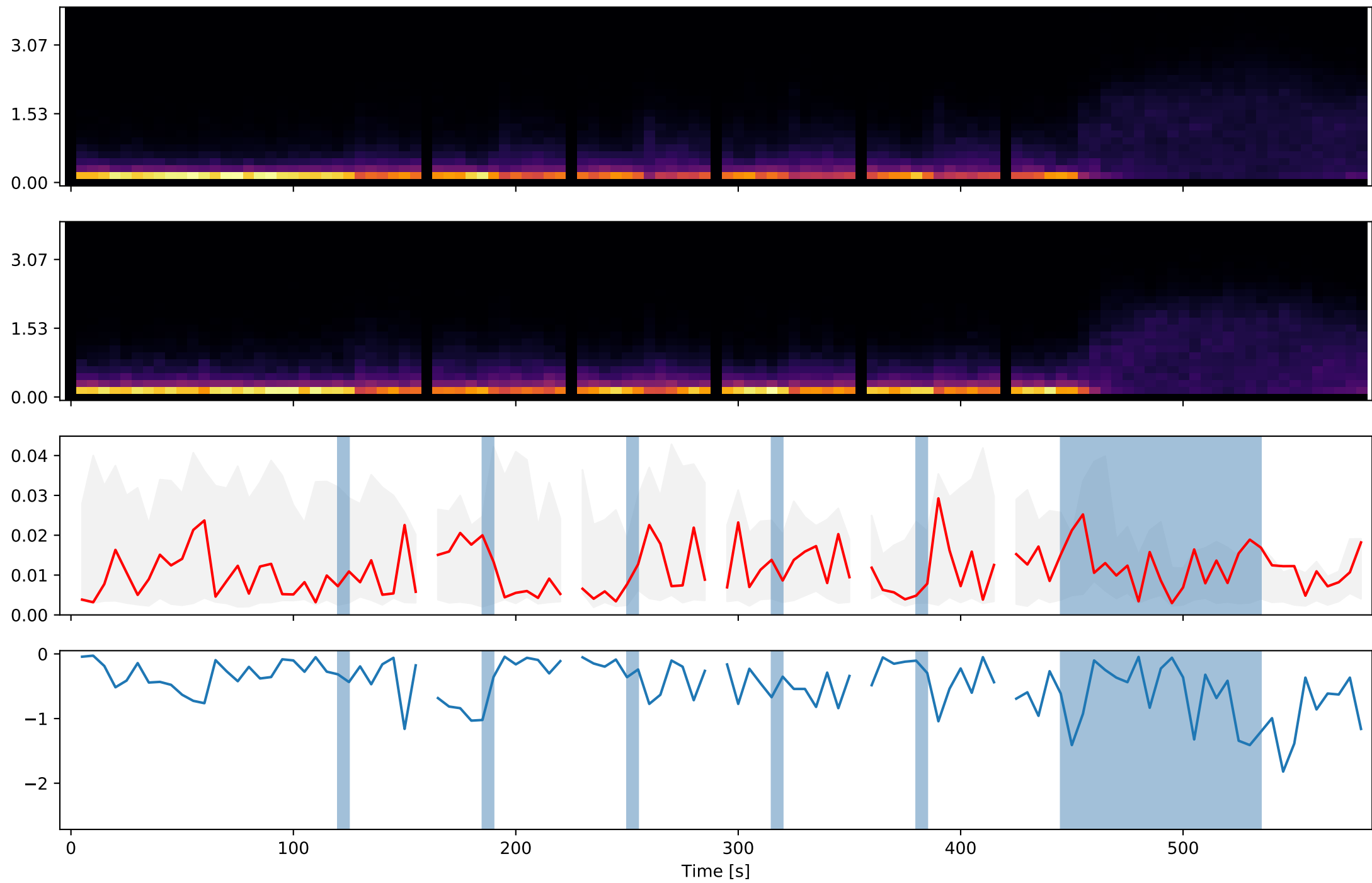
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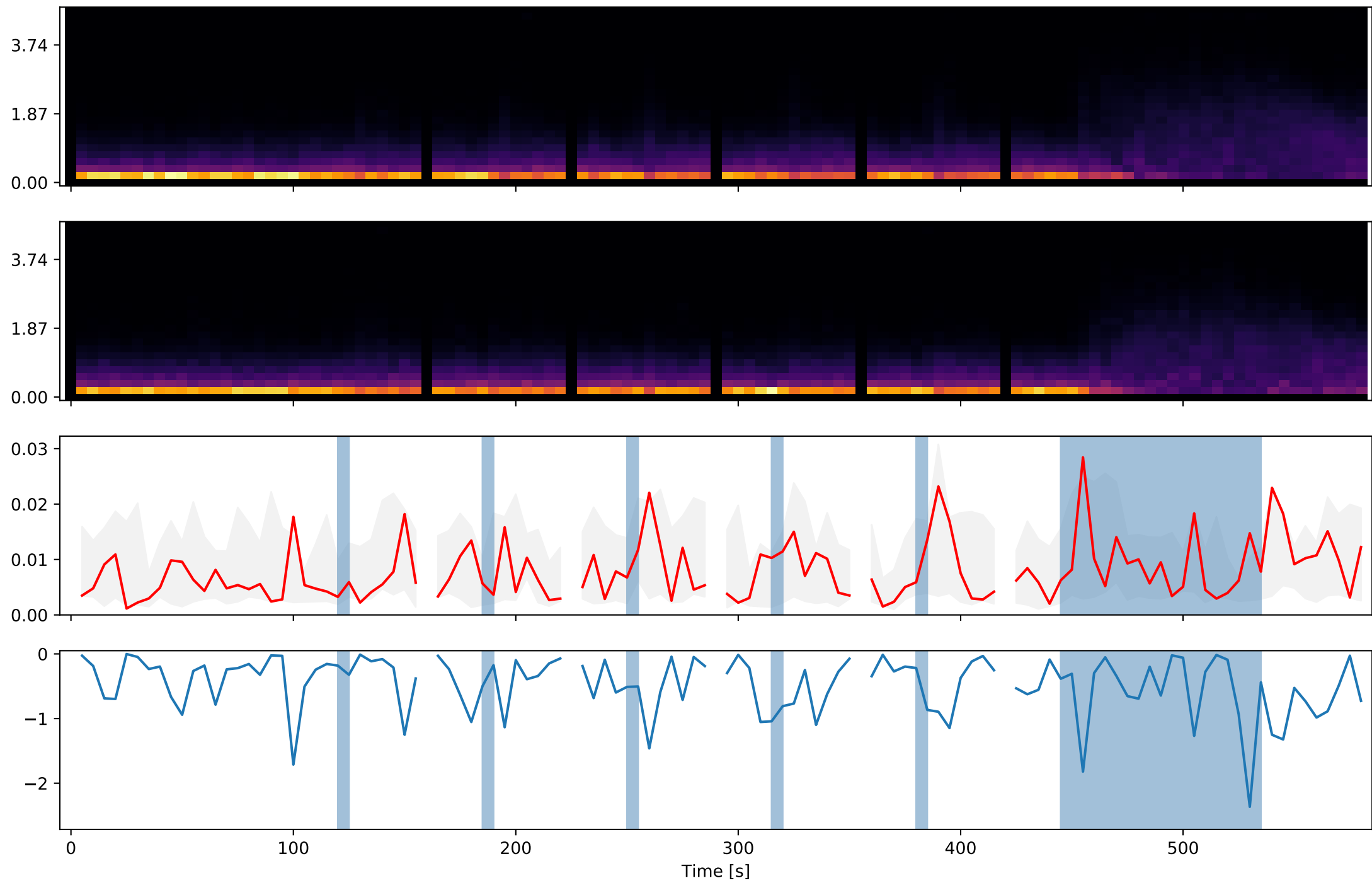
eigen\_projection\_1 - pval: 0.6004319654427646



relative\_to\_neck\_angular\_velocity\_head\_tip - pval: 0.6025917926565875

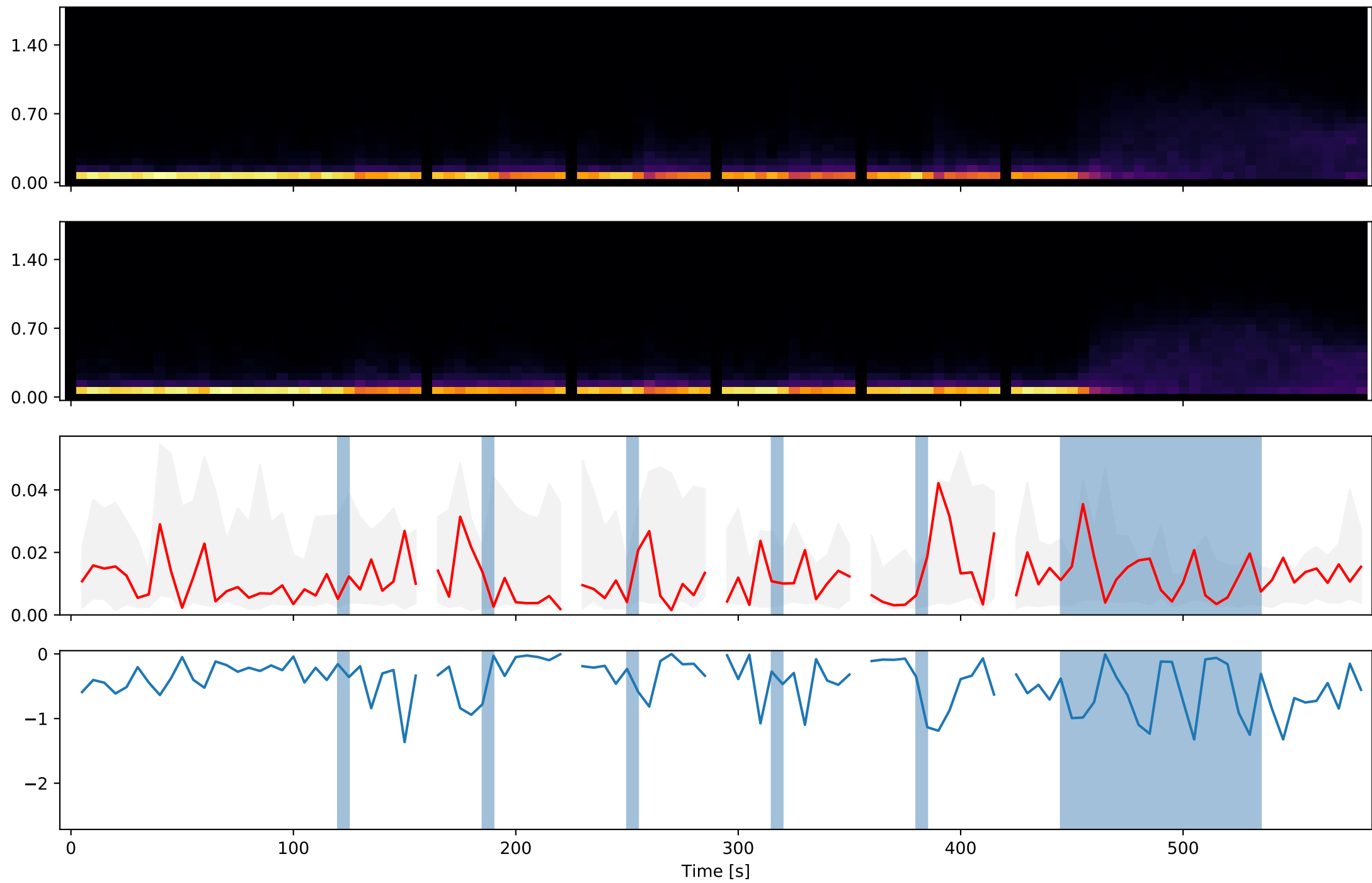


angular\_velocity\_tail\_tip - pval: 0.6047516198704104

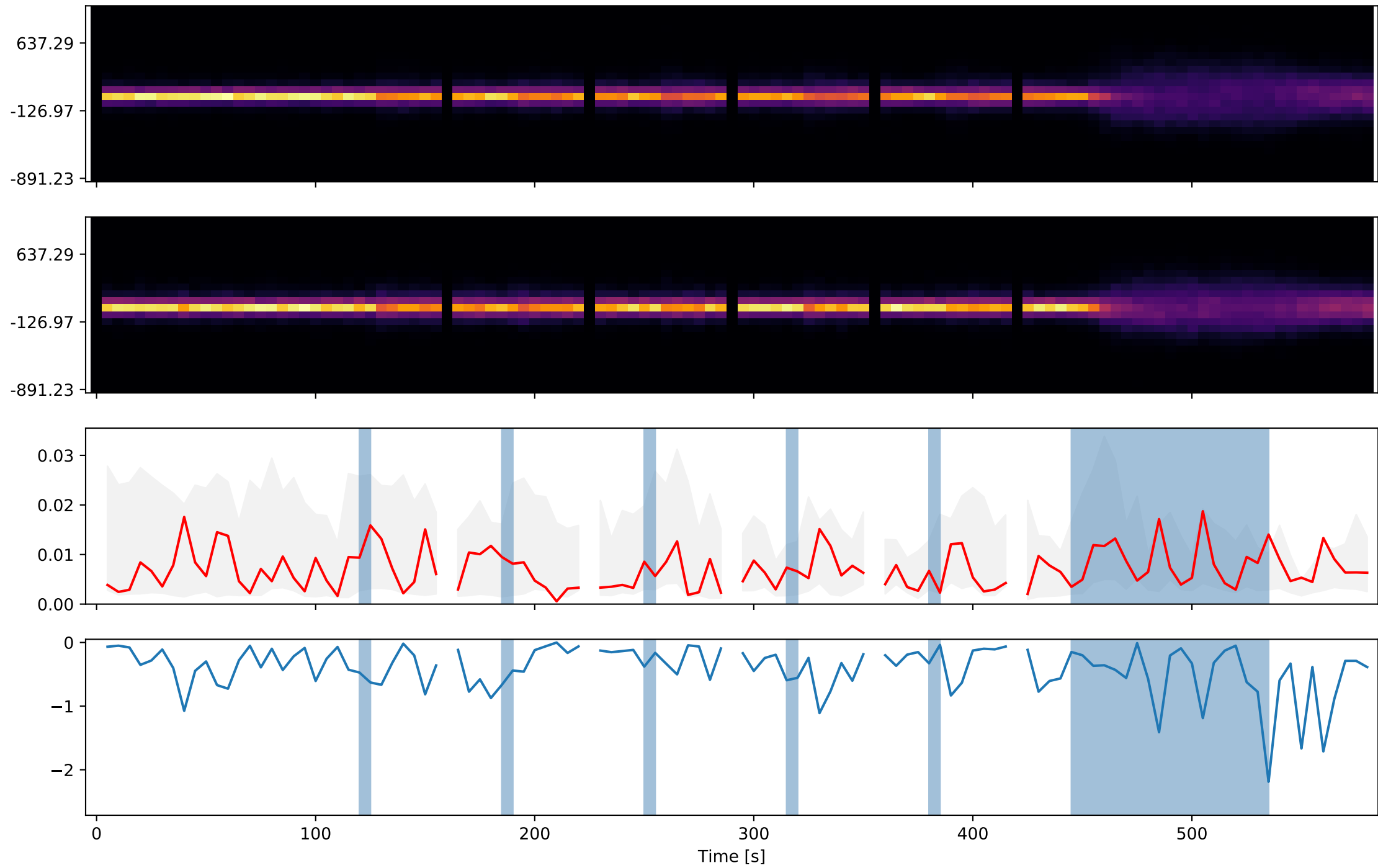




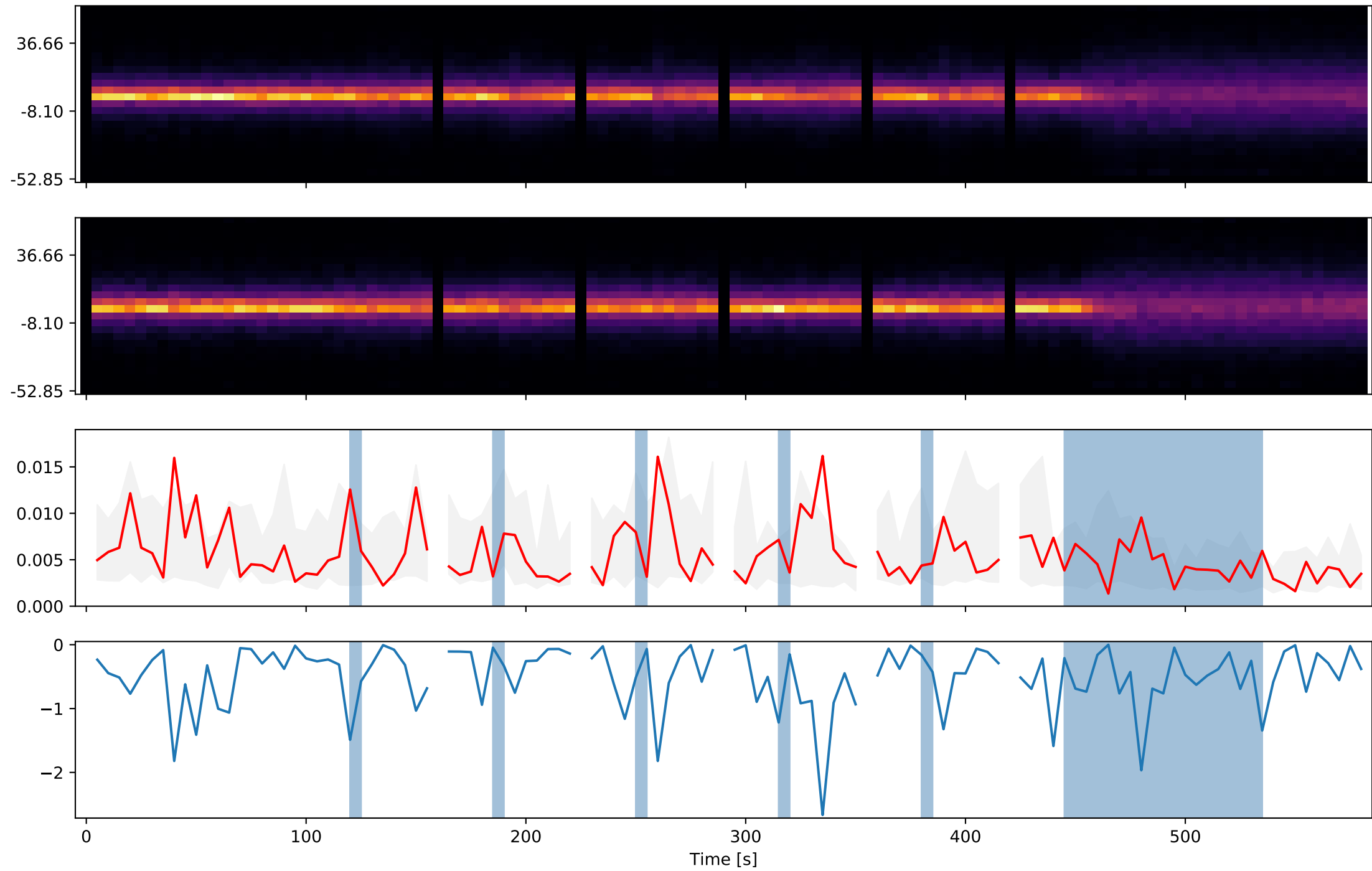
relative\_to\_body\_angular\_velocity\_neck - pval: 0.6198704103671706



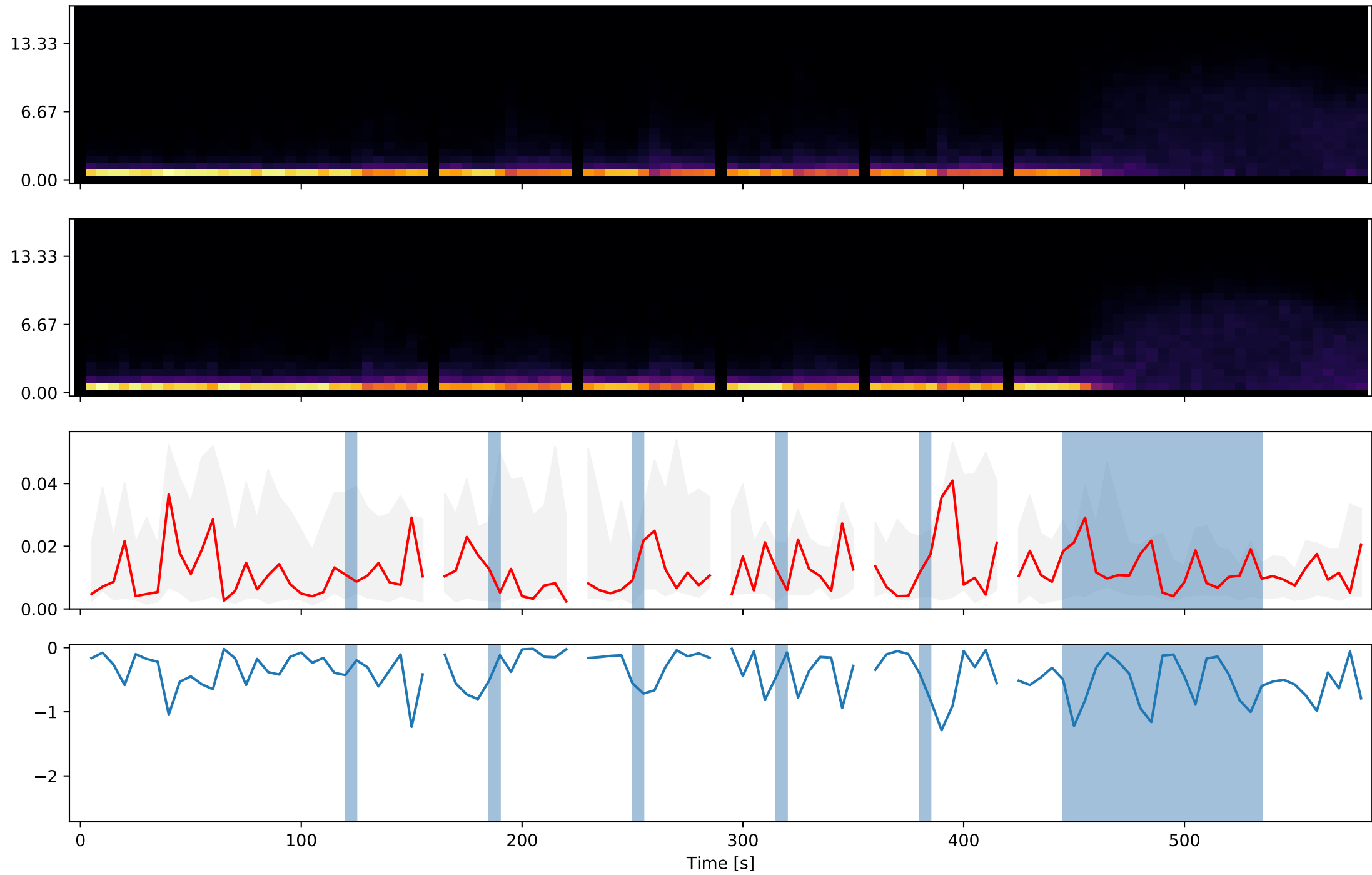
d\_relative\_to\_neck\_radial\_velocity\_head\_tip - pval: 0.6220302375809935



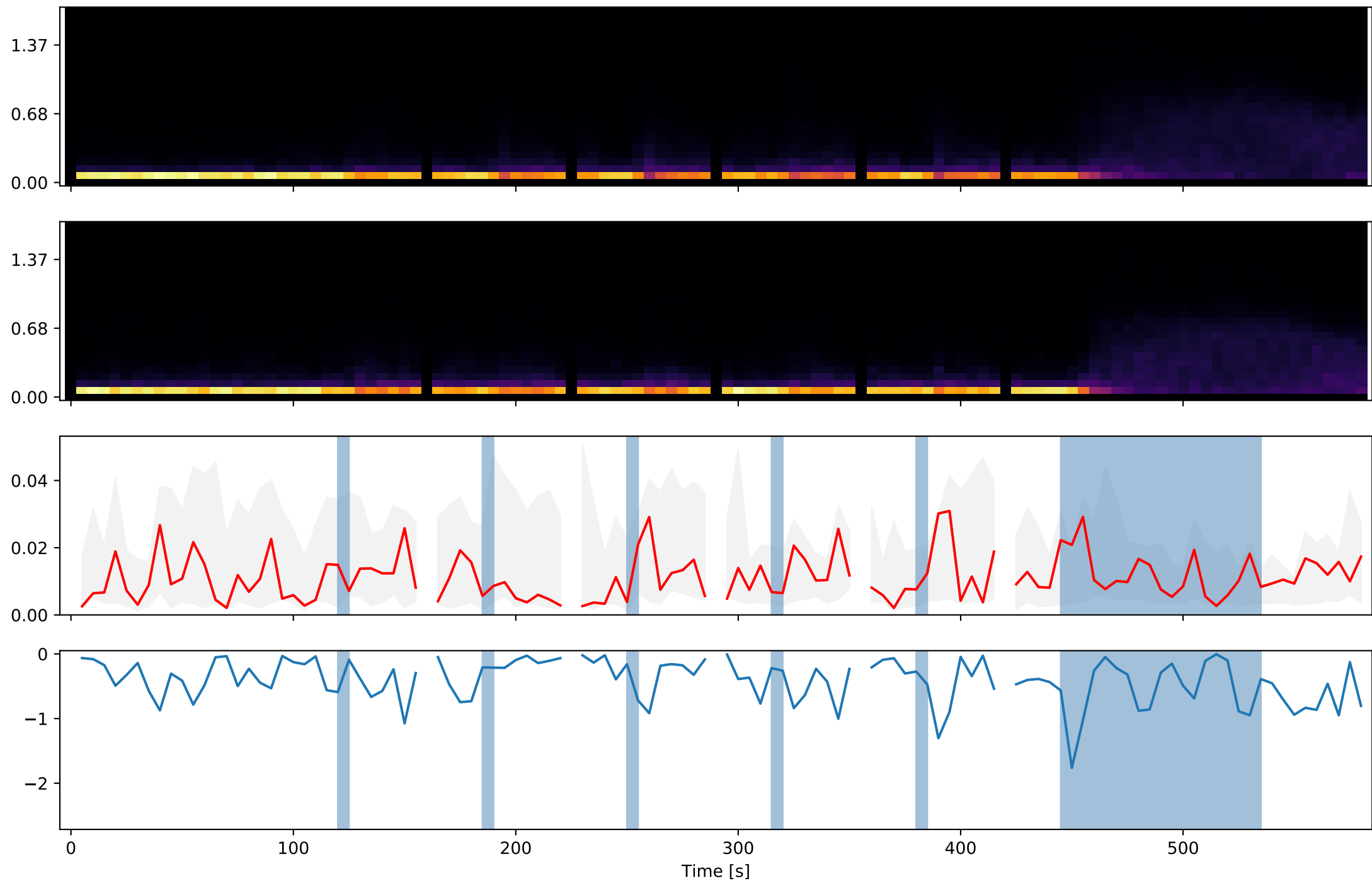
d\_width\_tail\_base - pval: 0.6220302375809935



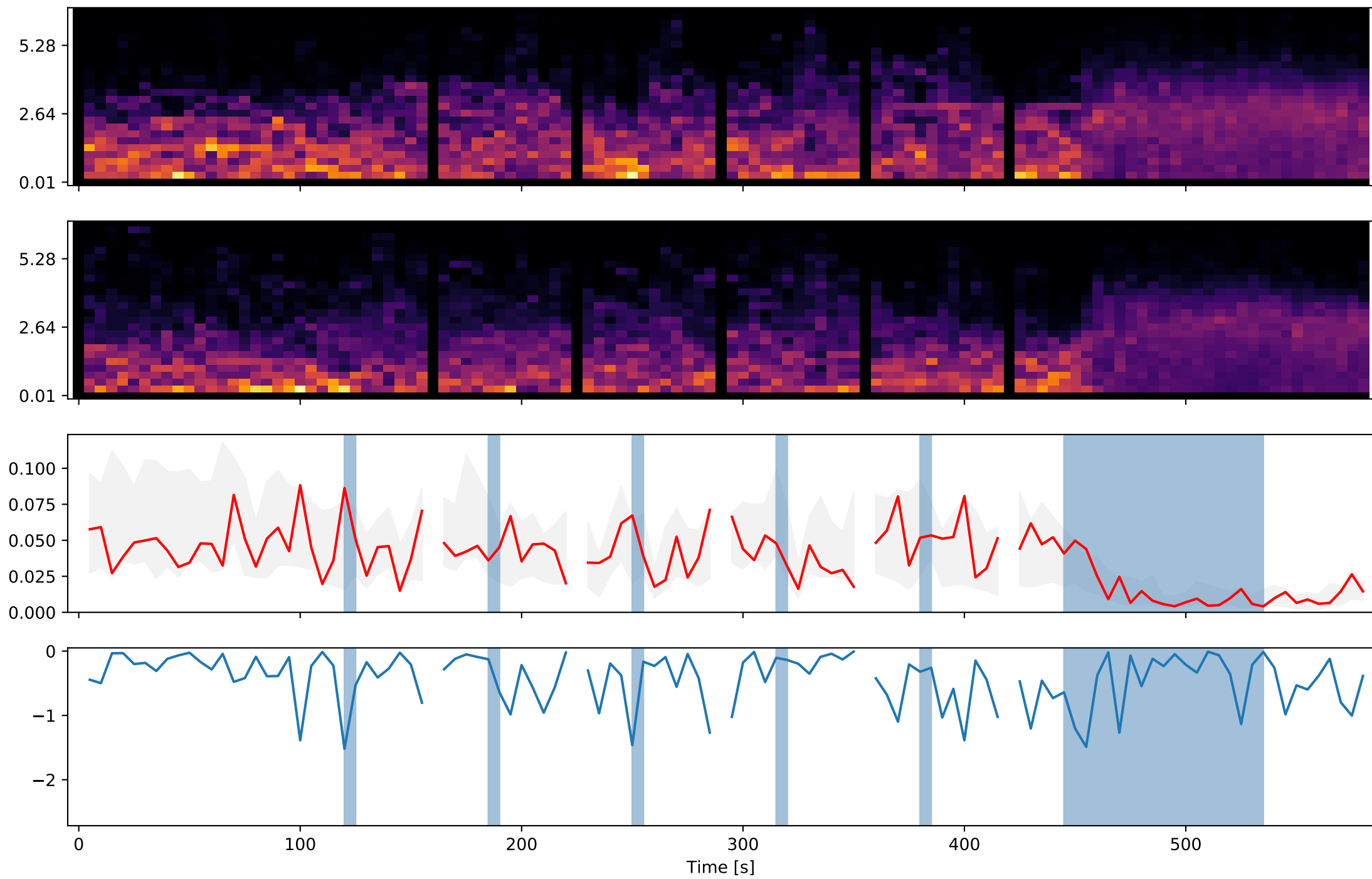
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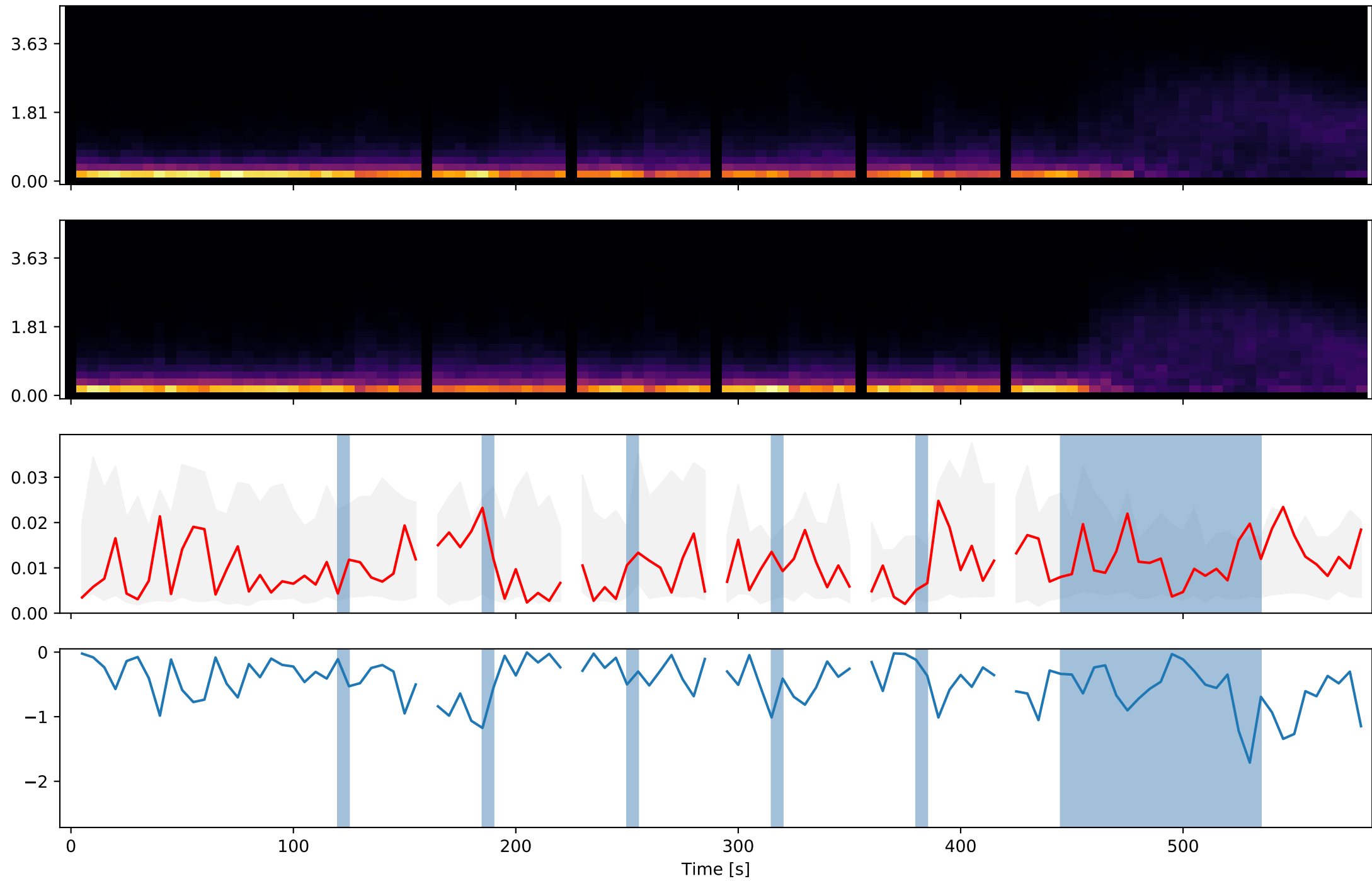
relative\_to\_body\_angular\_velocity\_hips - pval: 0.6241900647948164



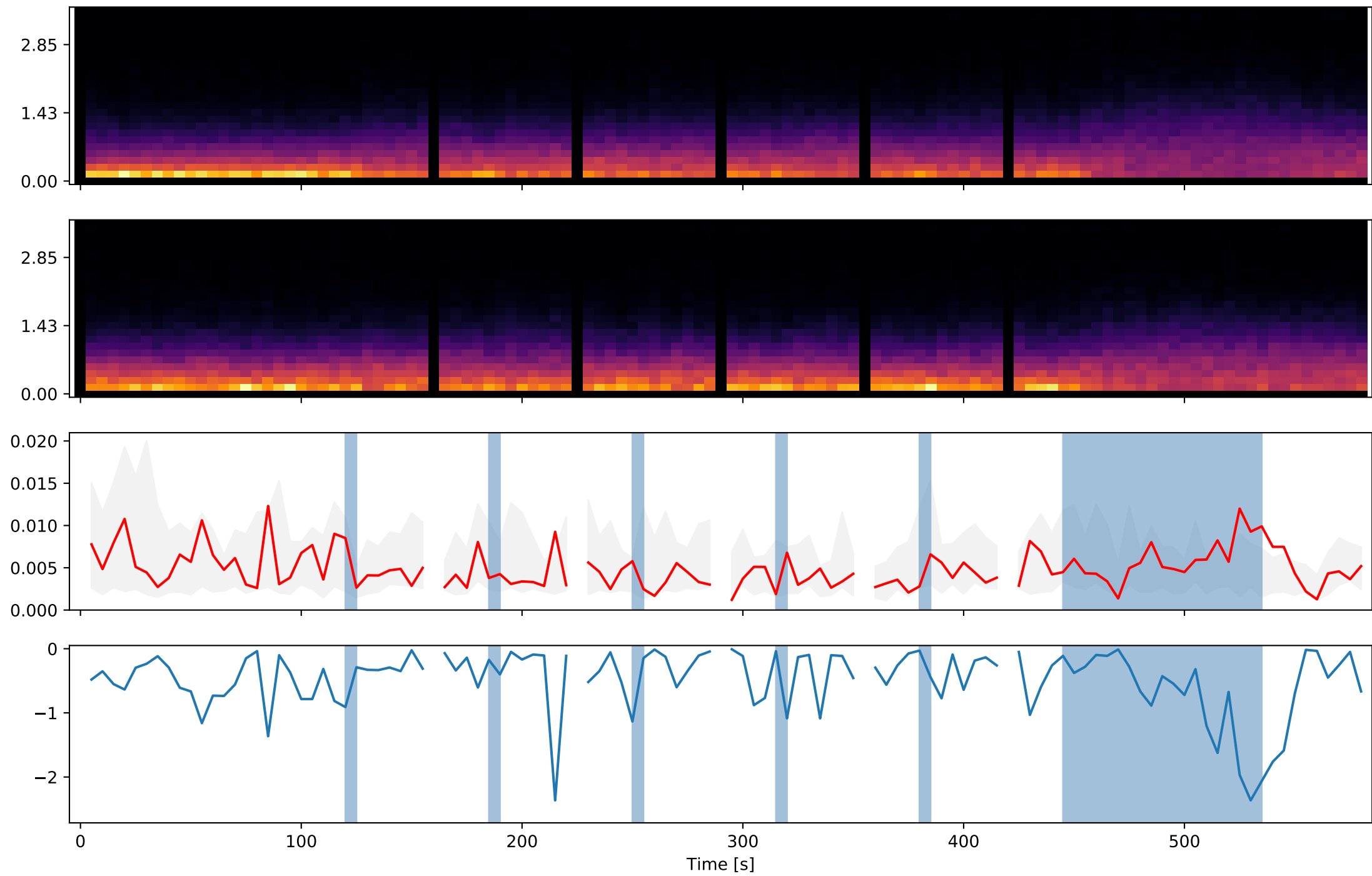
eigen\_projection\_3 - pval: 0.6285097192224622



angular\_velocity\_head\_base - pval: 0.6306695464362851

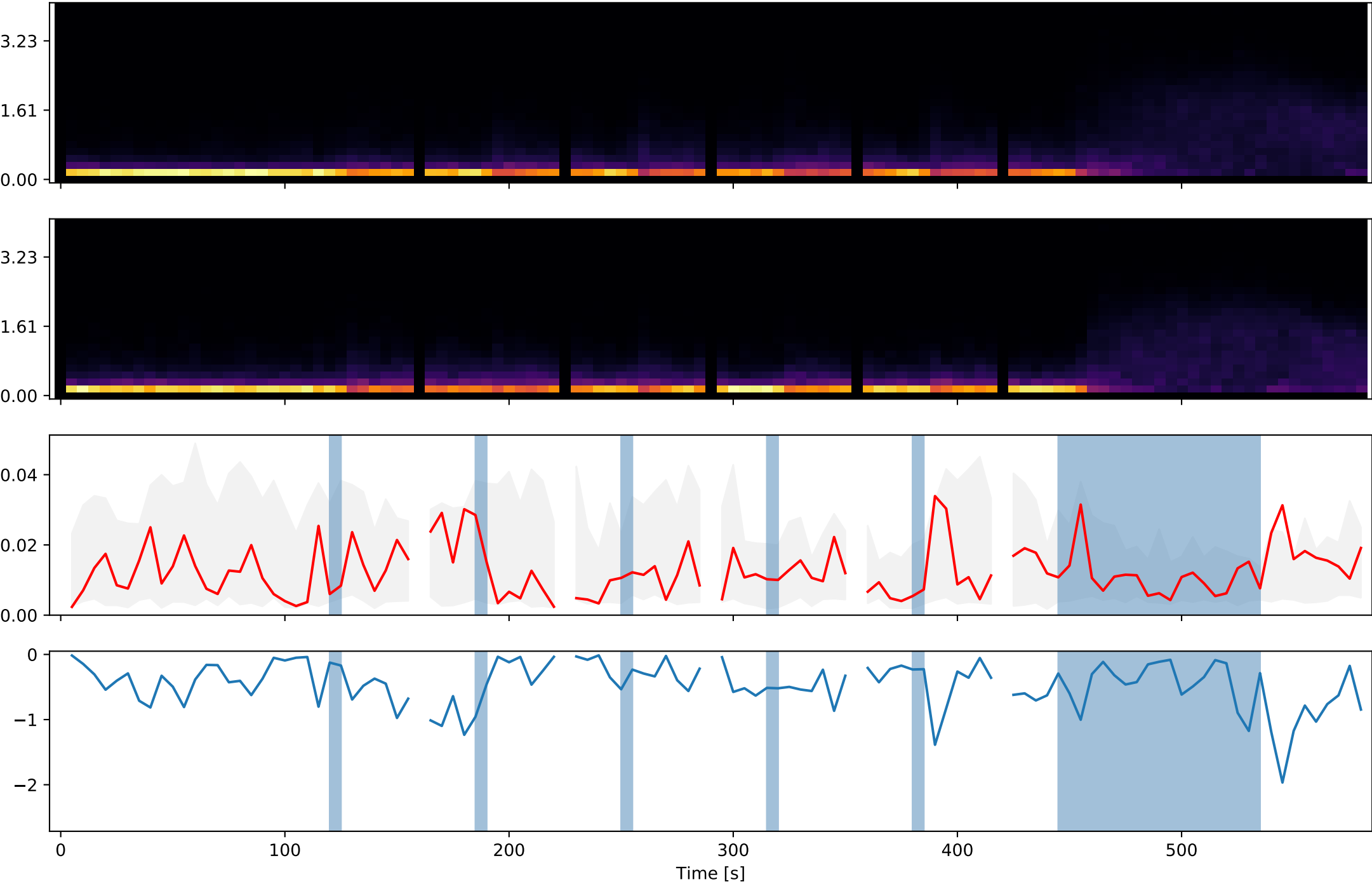


d\_eigen\_projection\_6 - pval: 0.6349892008639308

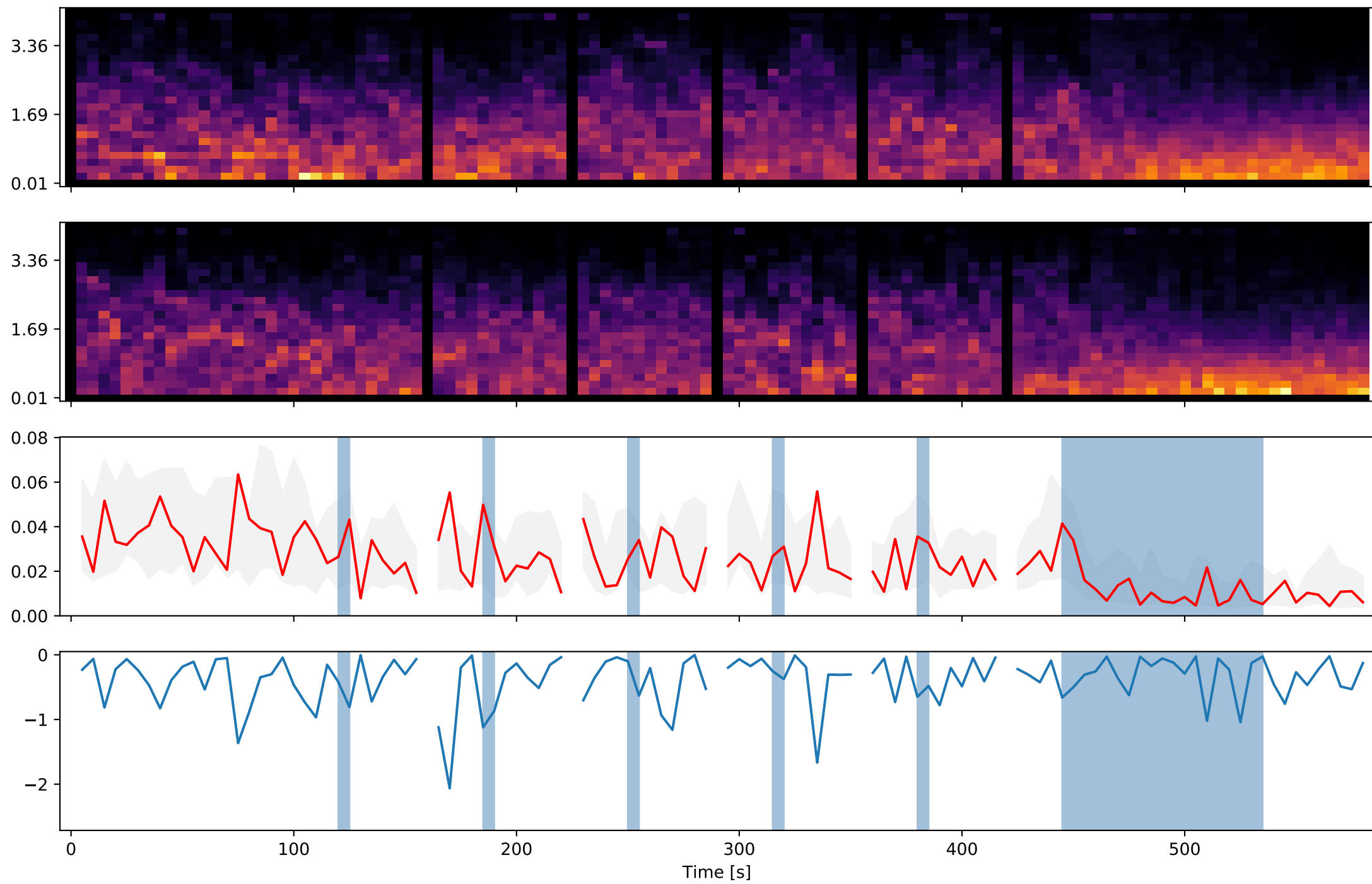




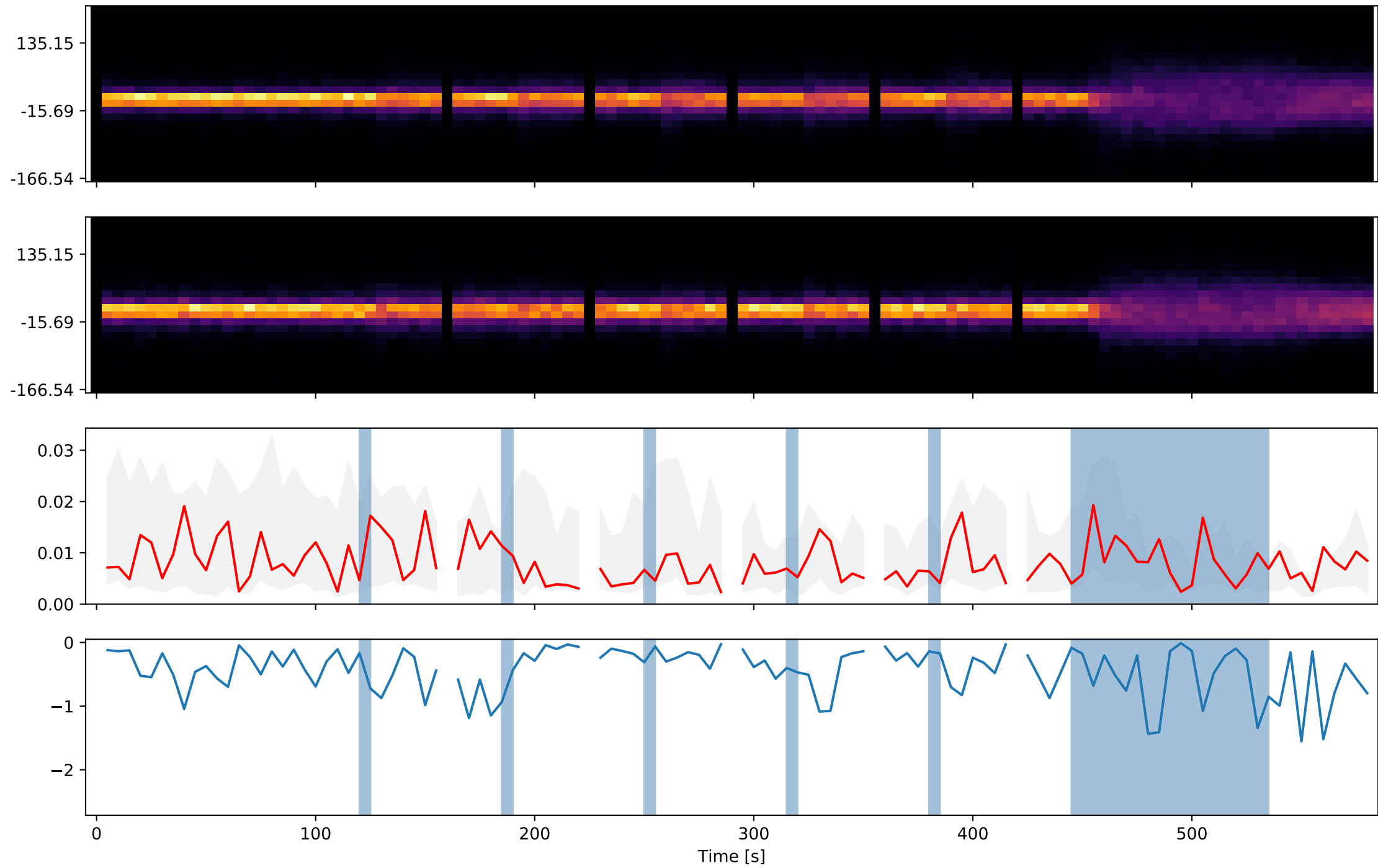
angular\_velocity\_neck - pval: 0.6371490280777538



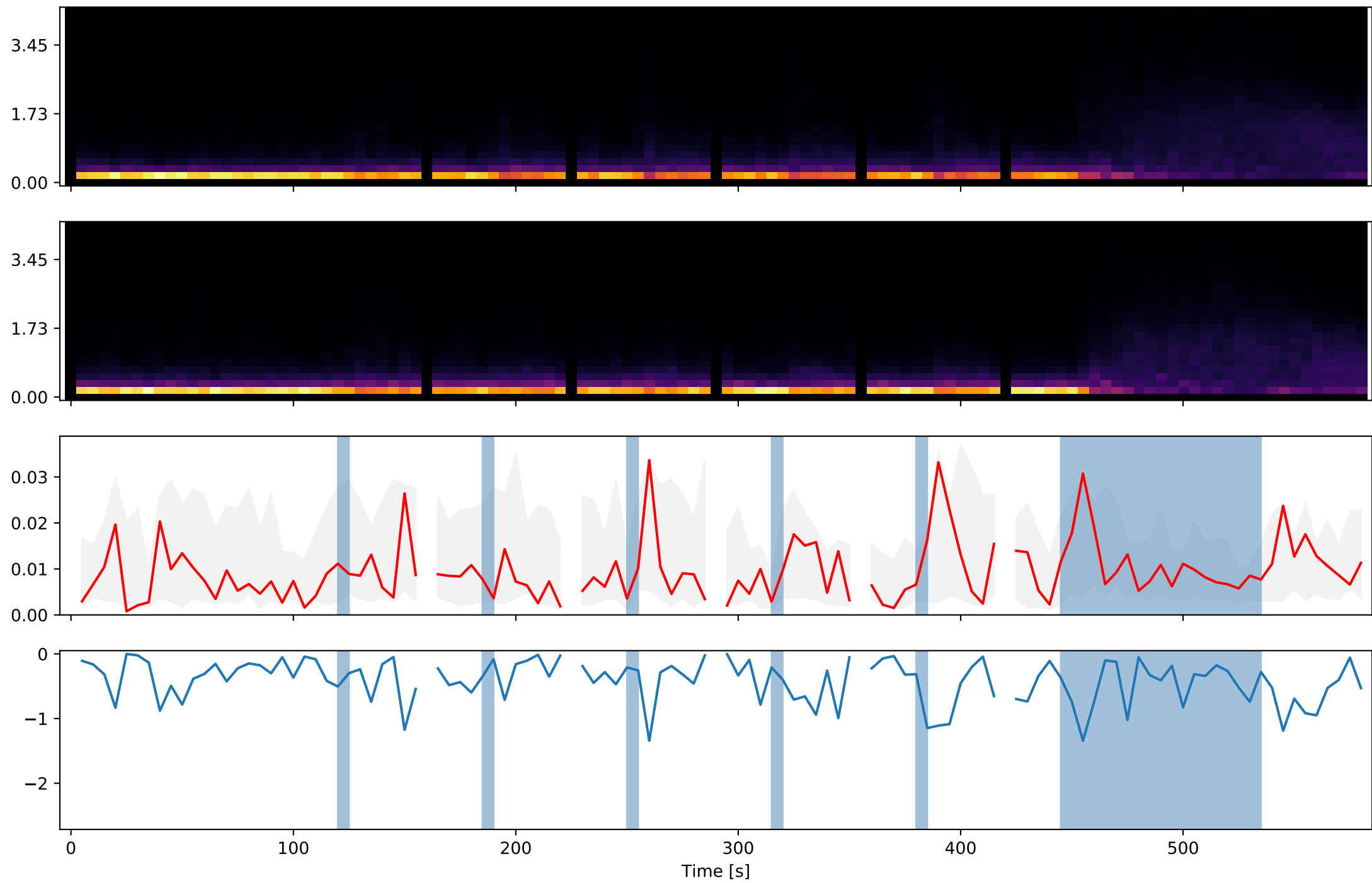
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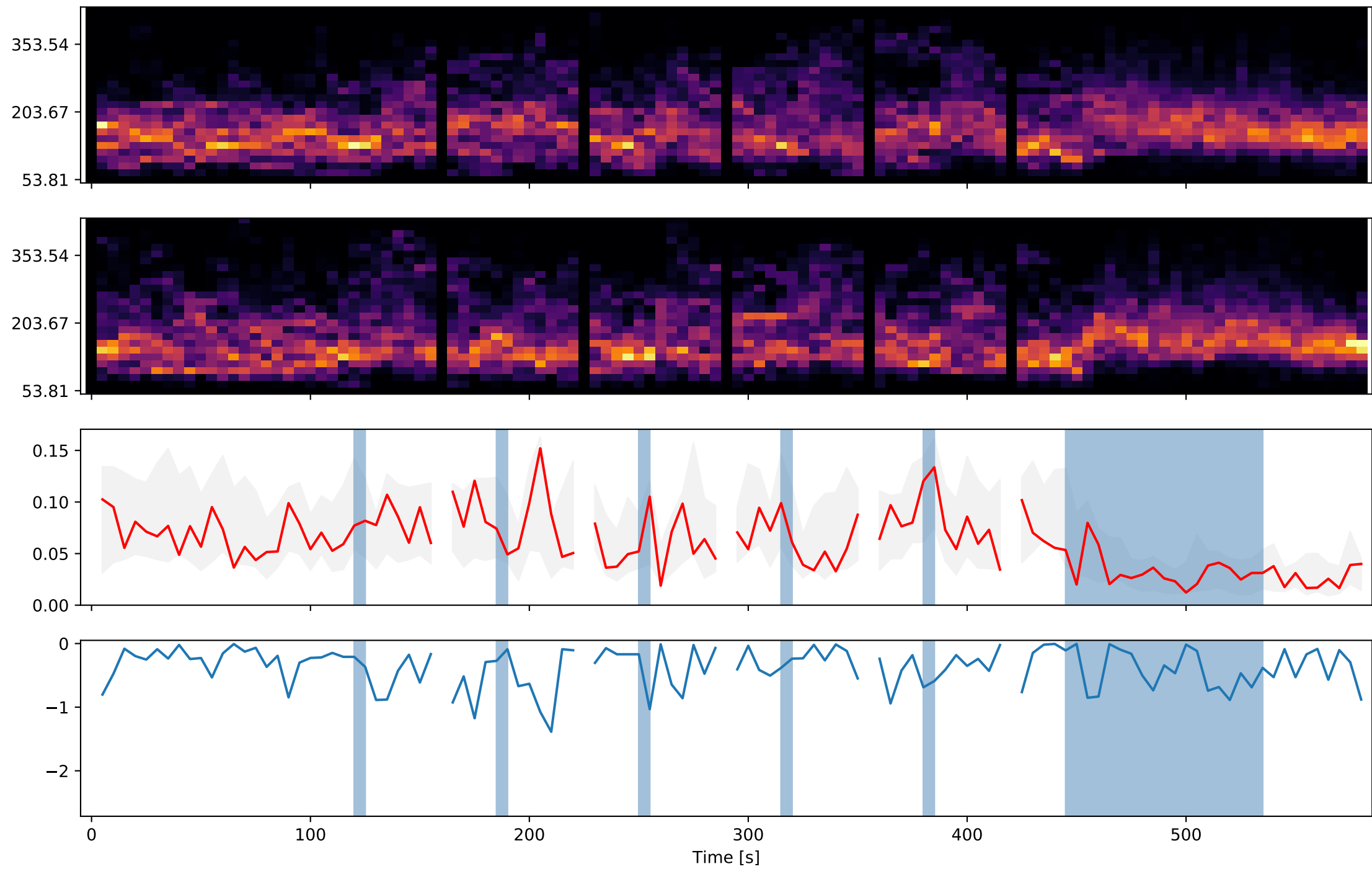
relative\_to\_neck\_radial\_velocity\_head\_tip - pval: 0.6673866090712743



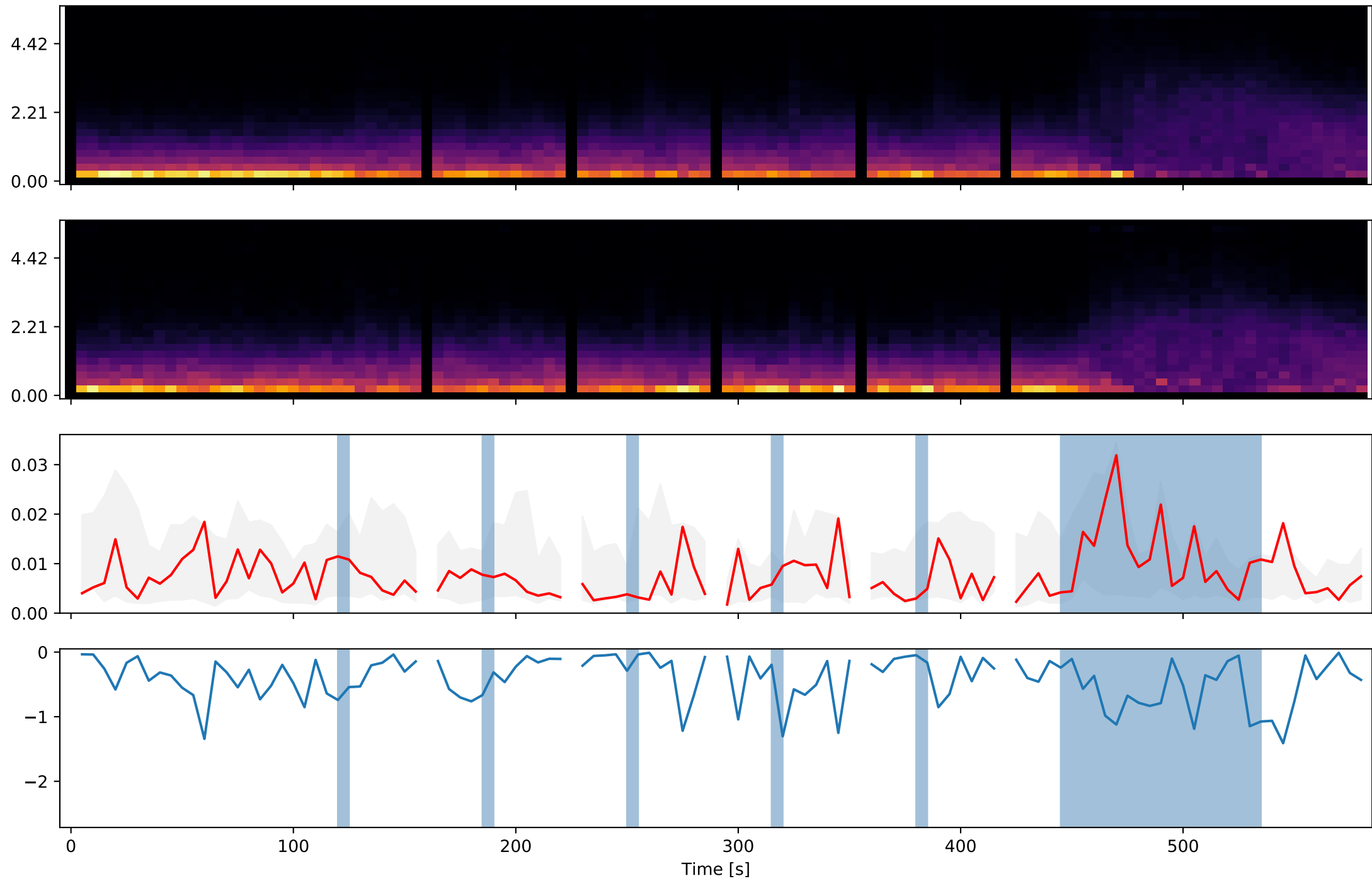
angular\_velocity\_tail\_base - pval: 0.6673866090712743



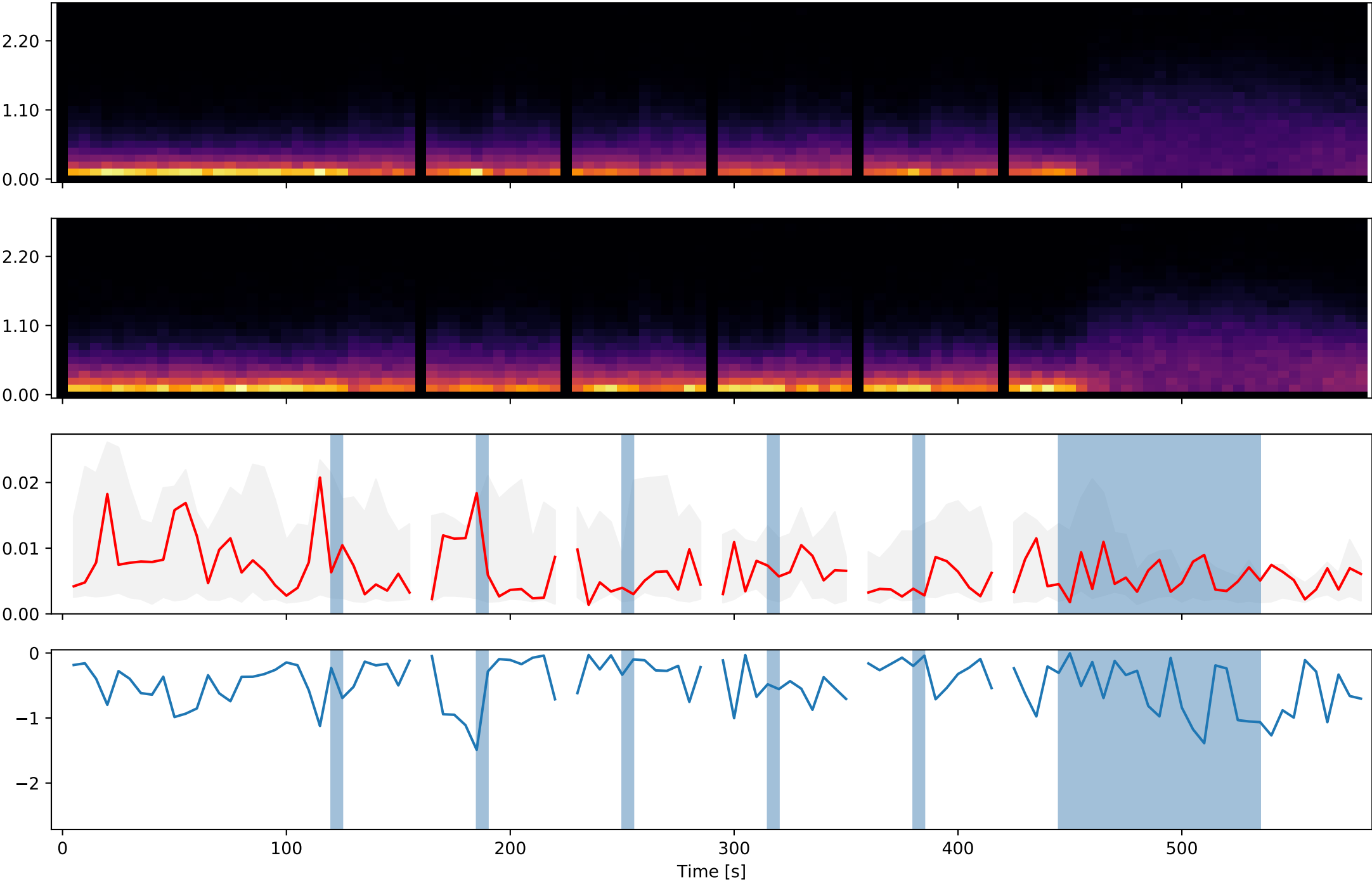
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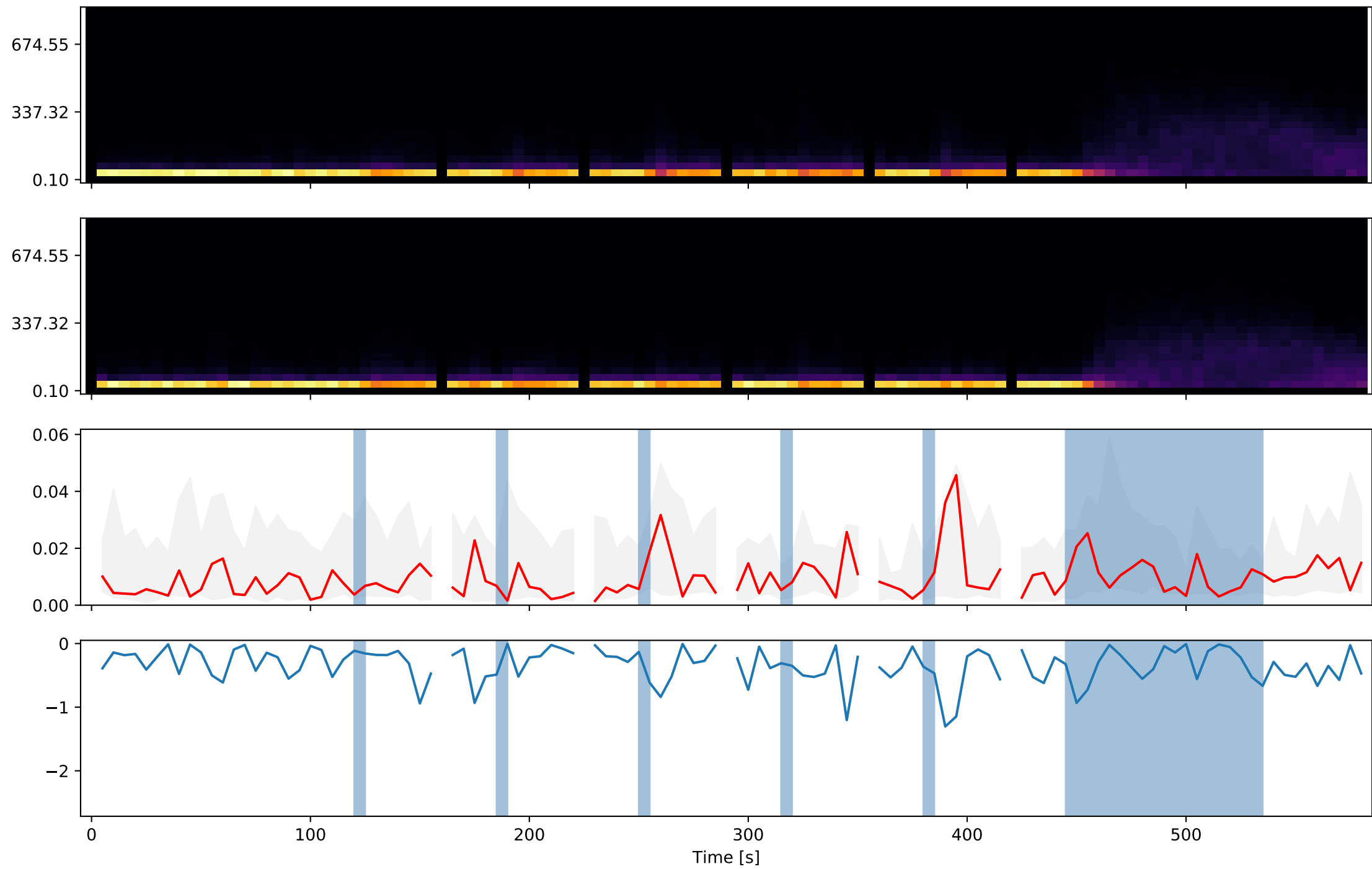
angular\_velocity\_head\_tip - pval: 0.673866090712743



relative\_to\_head\_base\_angular\_velocity\_head\_tip - pval: 0.6781857451403888

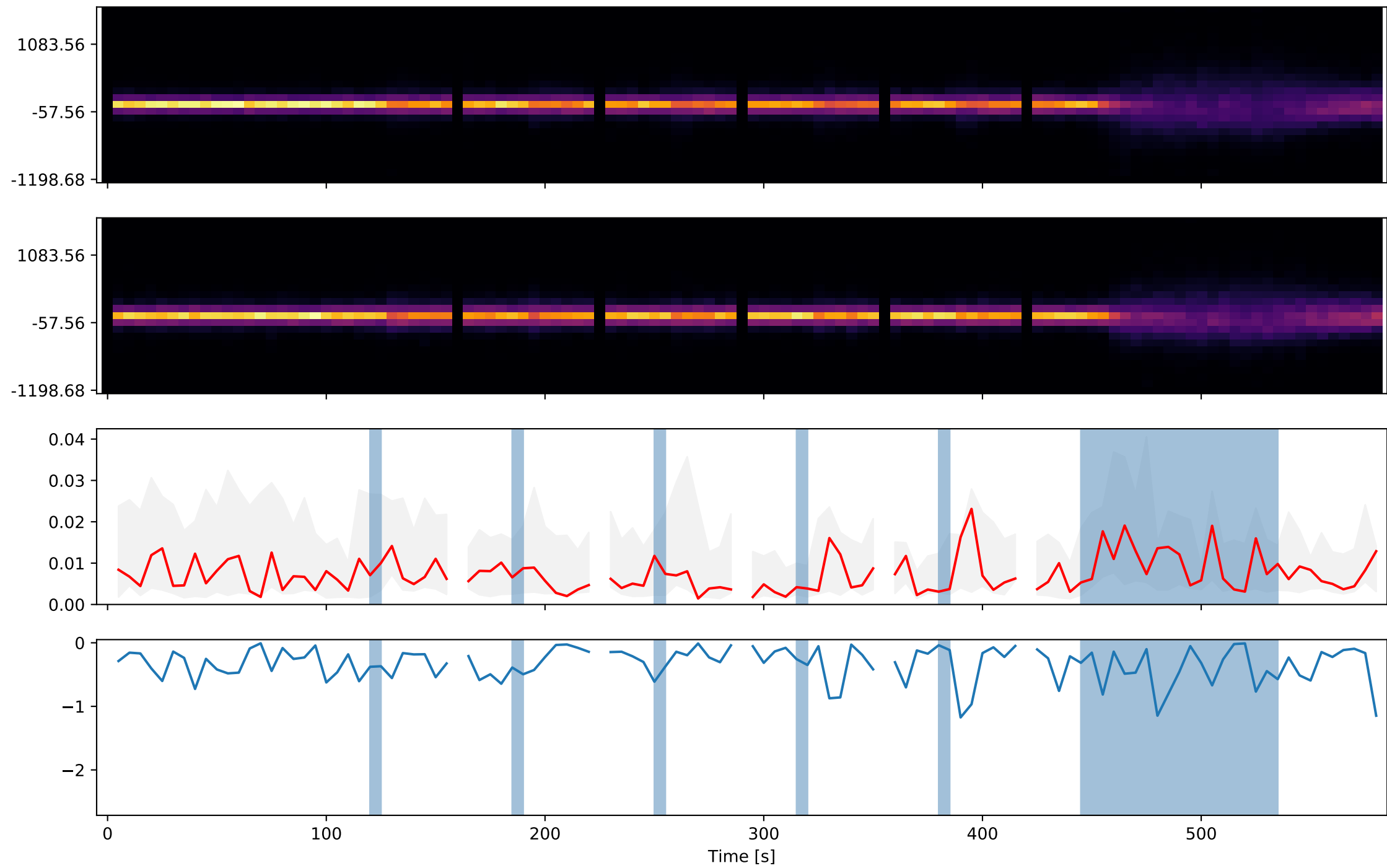


d\_relative\_to\_body\_speed\_midbody - pval: 0.6781857451403888

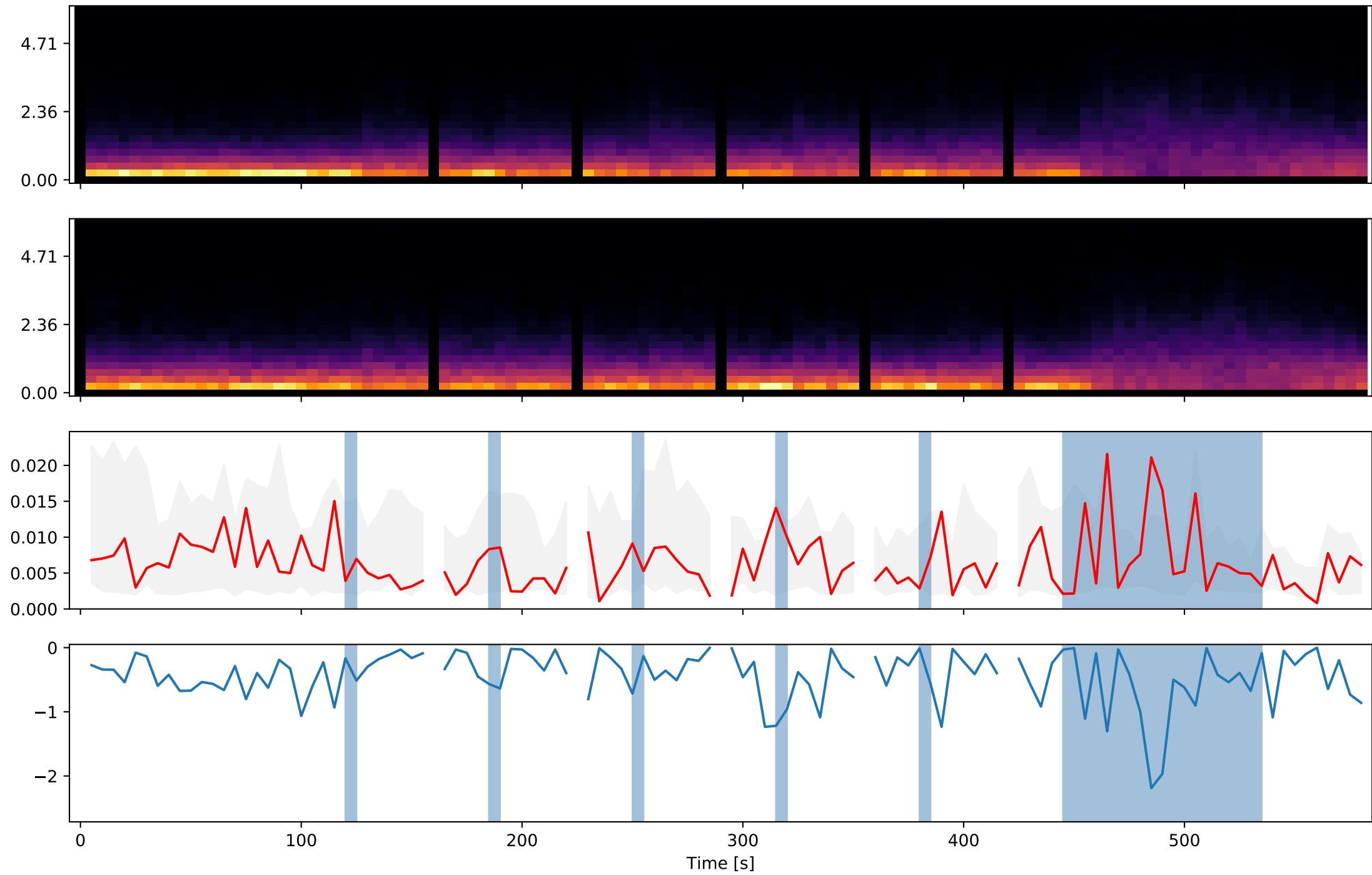




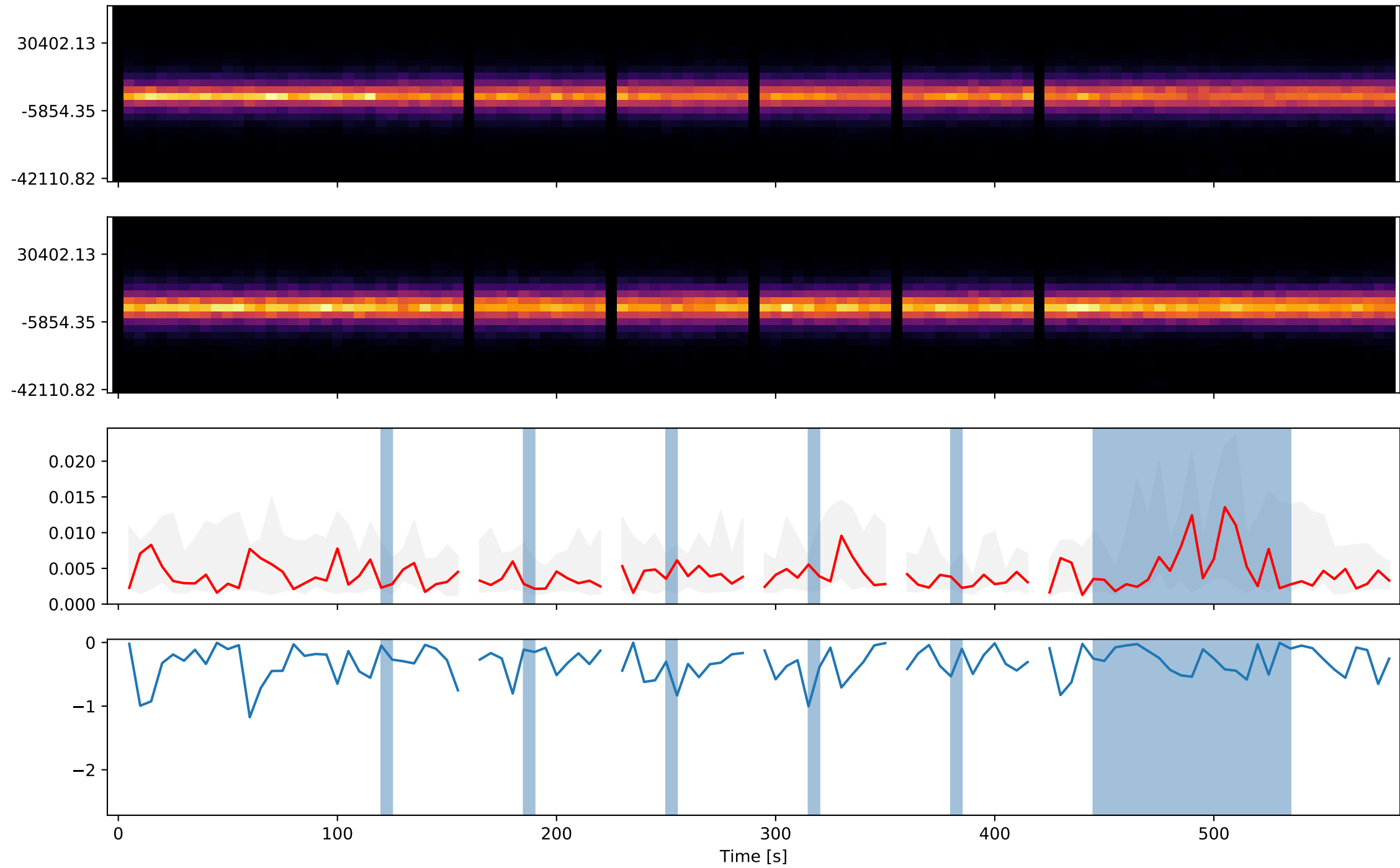
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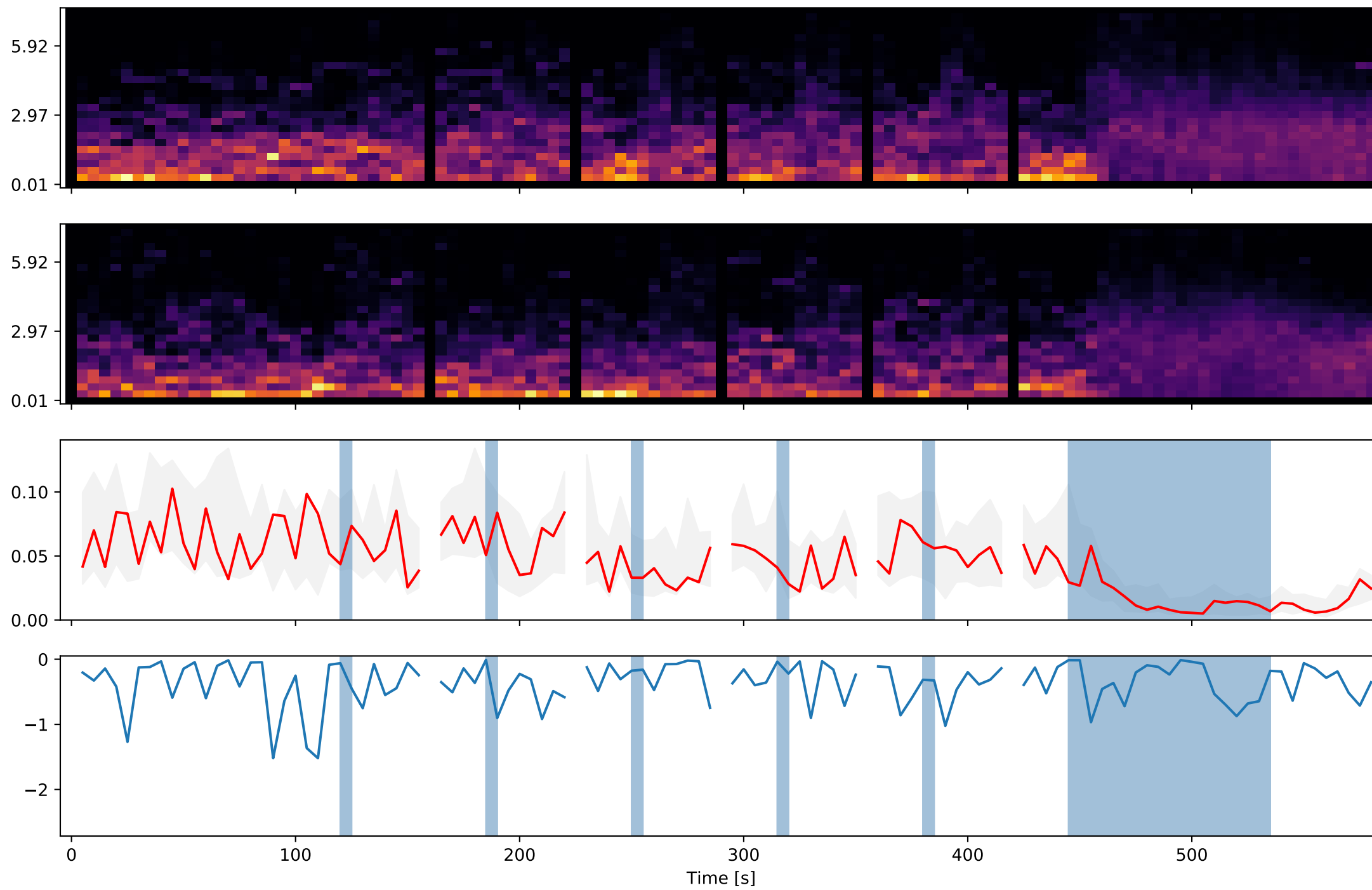
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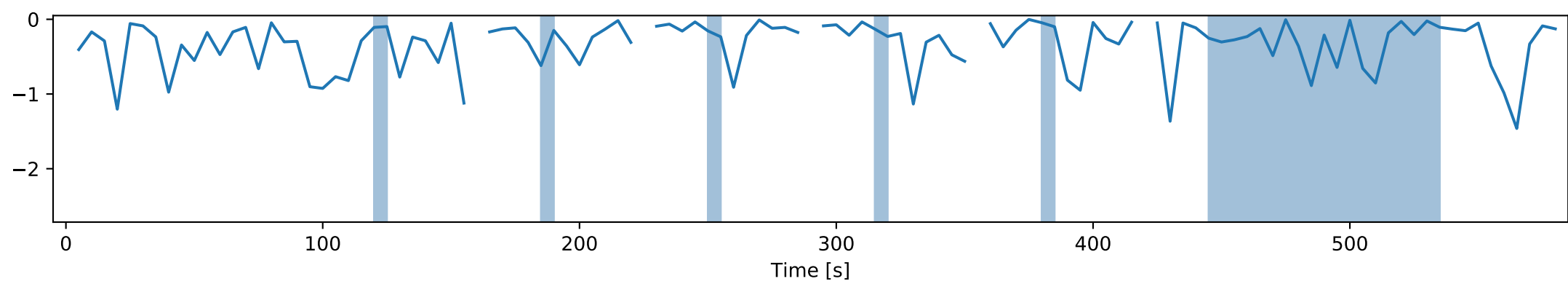
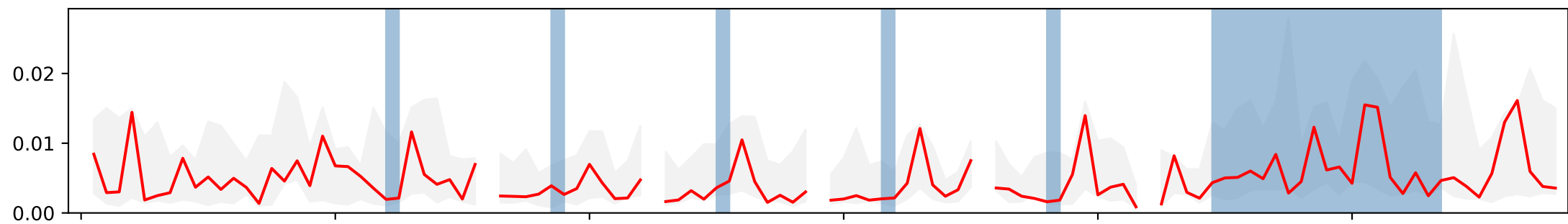
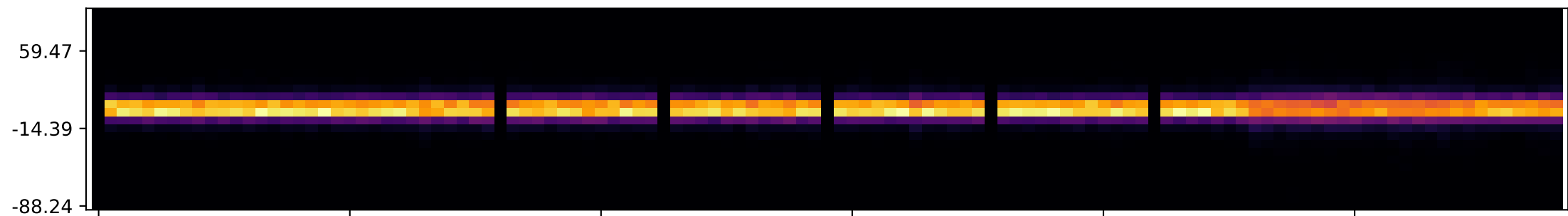
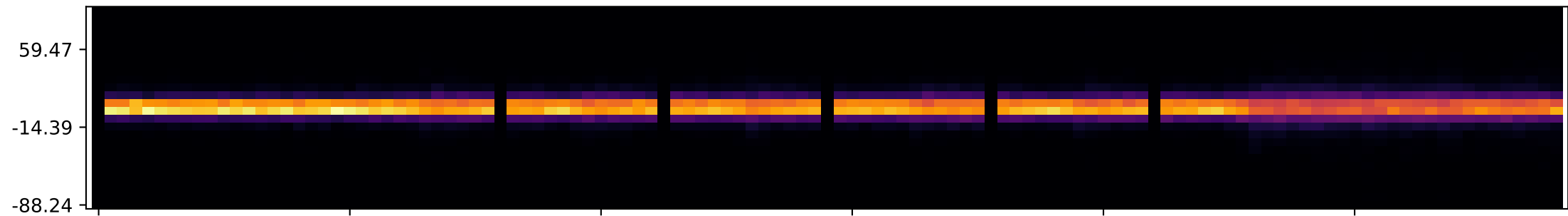
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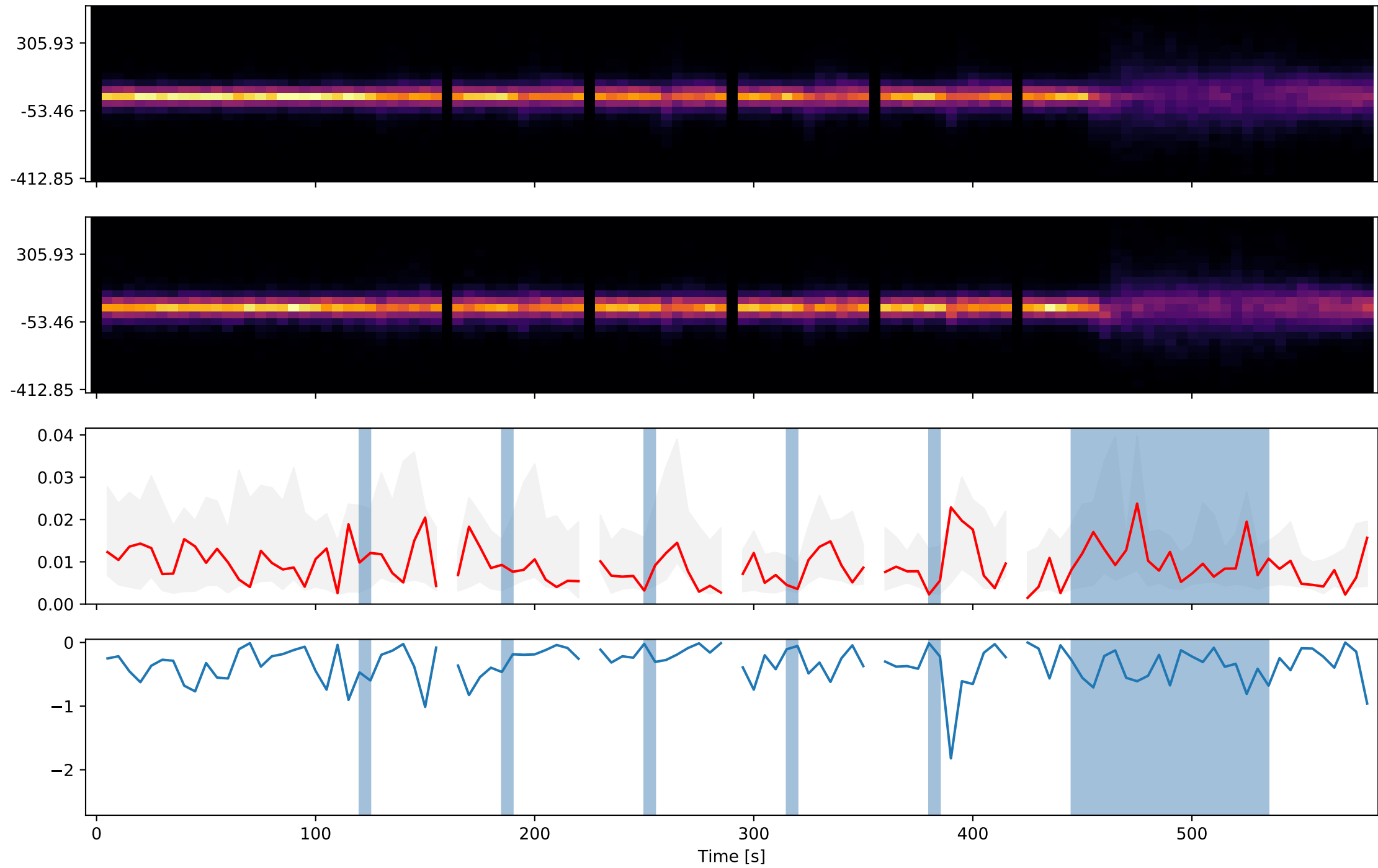
eigen\_projection\_2 - pval: 0.7062634989200864



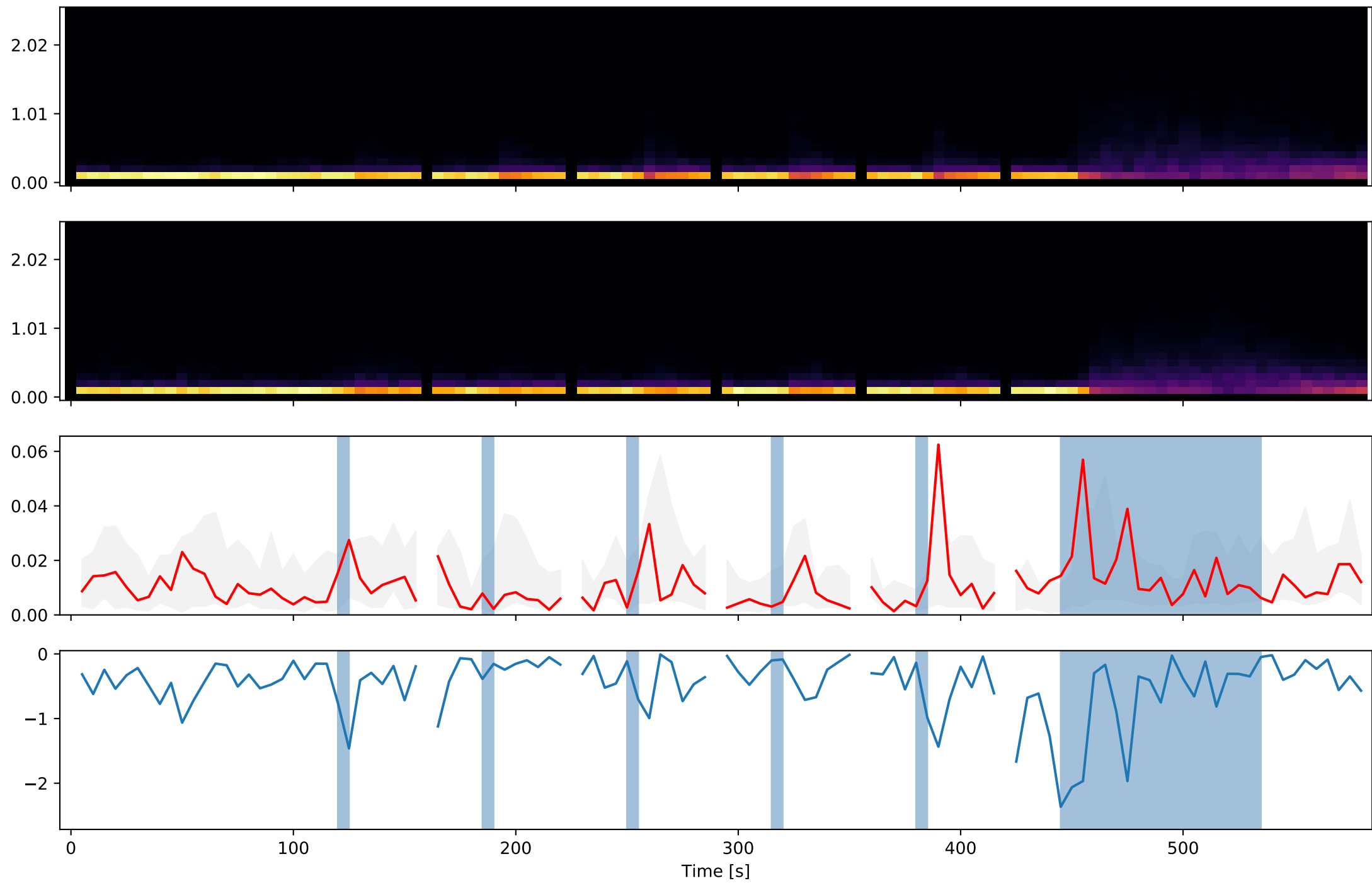
relative\_to\_head\_base\_radial\_velocity\_head\_tip - pval: 0.712742980561555



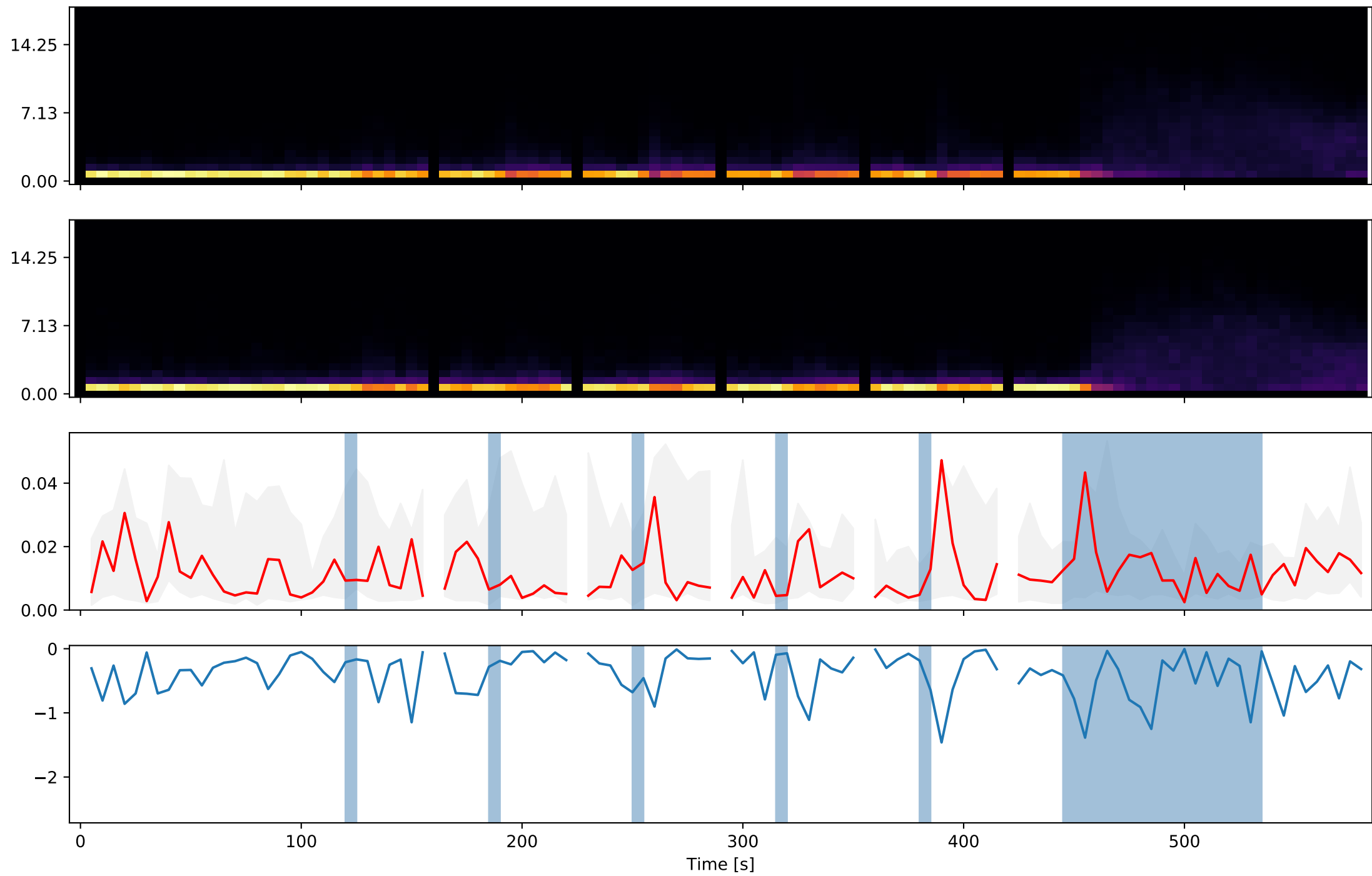
d\_major\_axis - pval: 0.7321814254859611



relative\_to\_body\_angular\_velocity\_tail\_tip - pval: 0.734341252699784

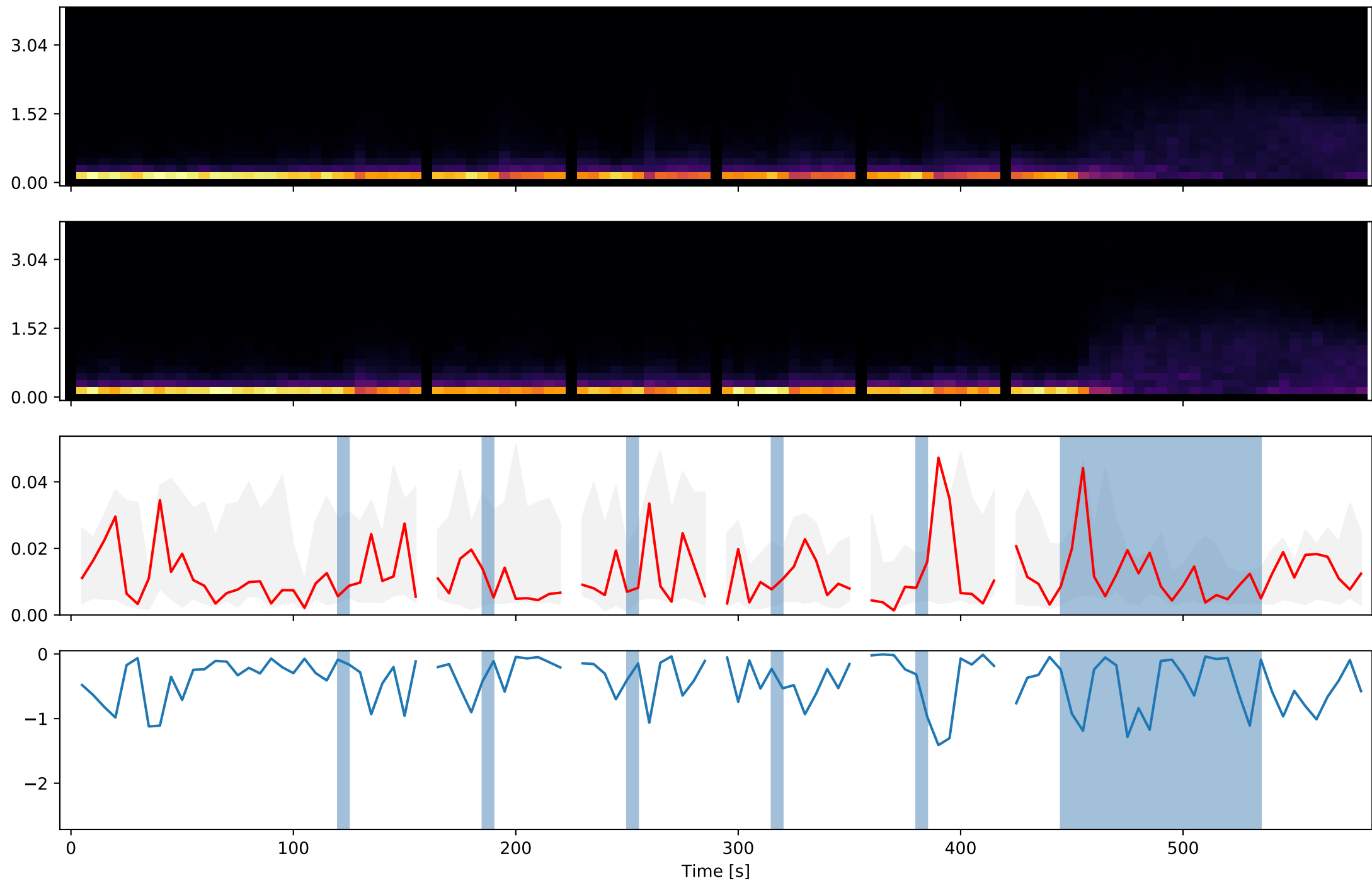


d\_eigen\_projection\_2 - pval: 0.7429805615550756

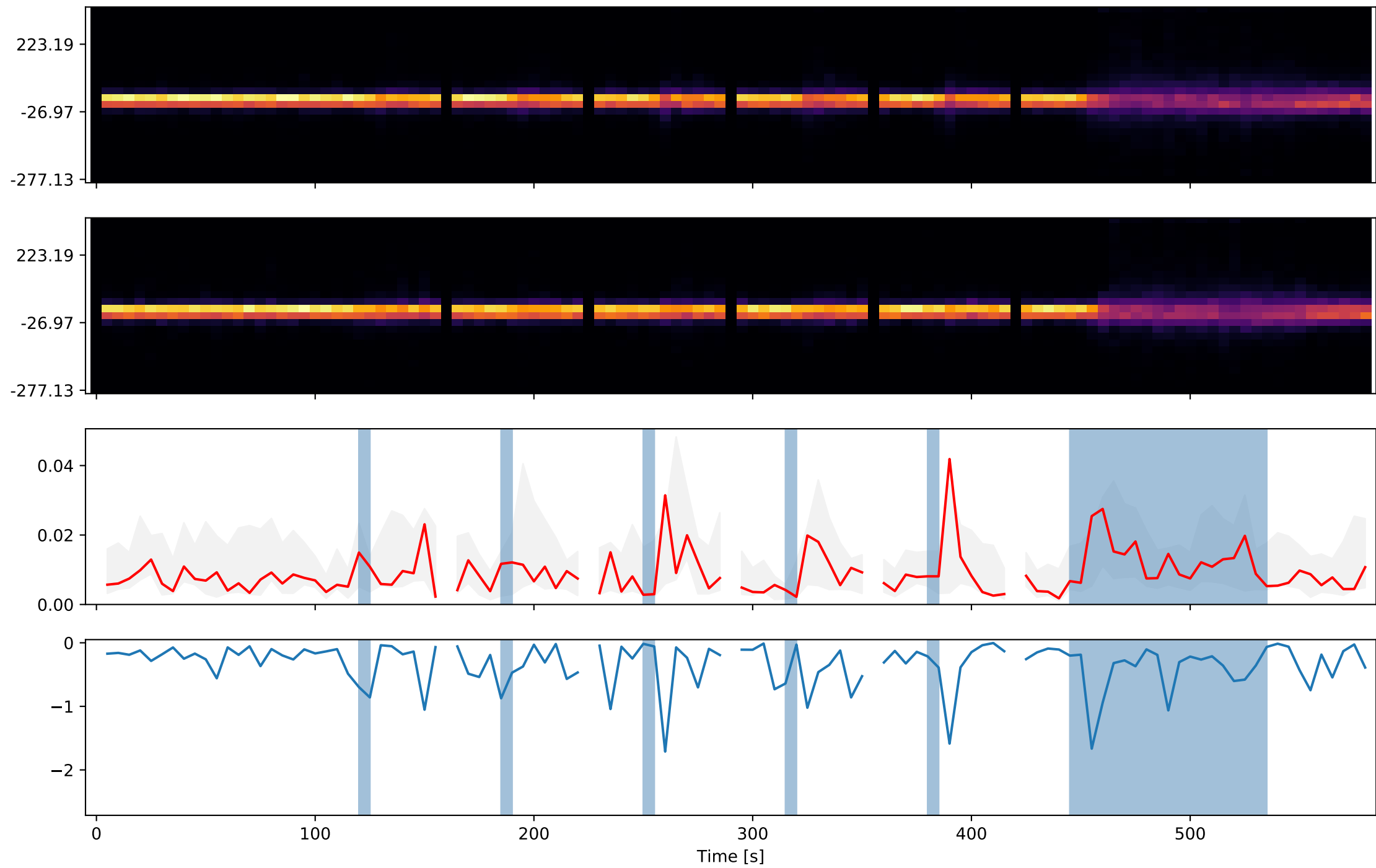




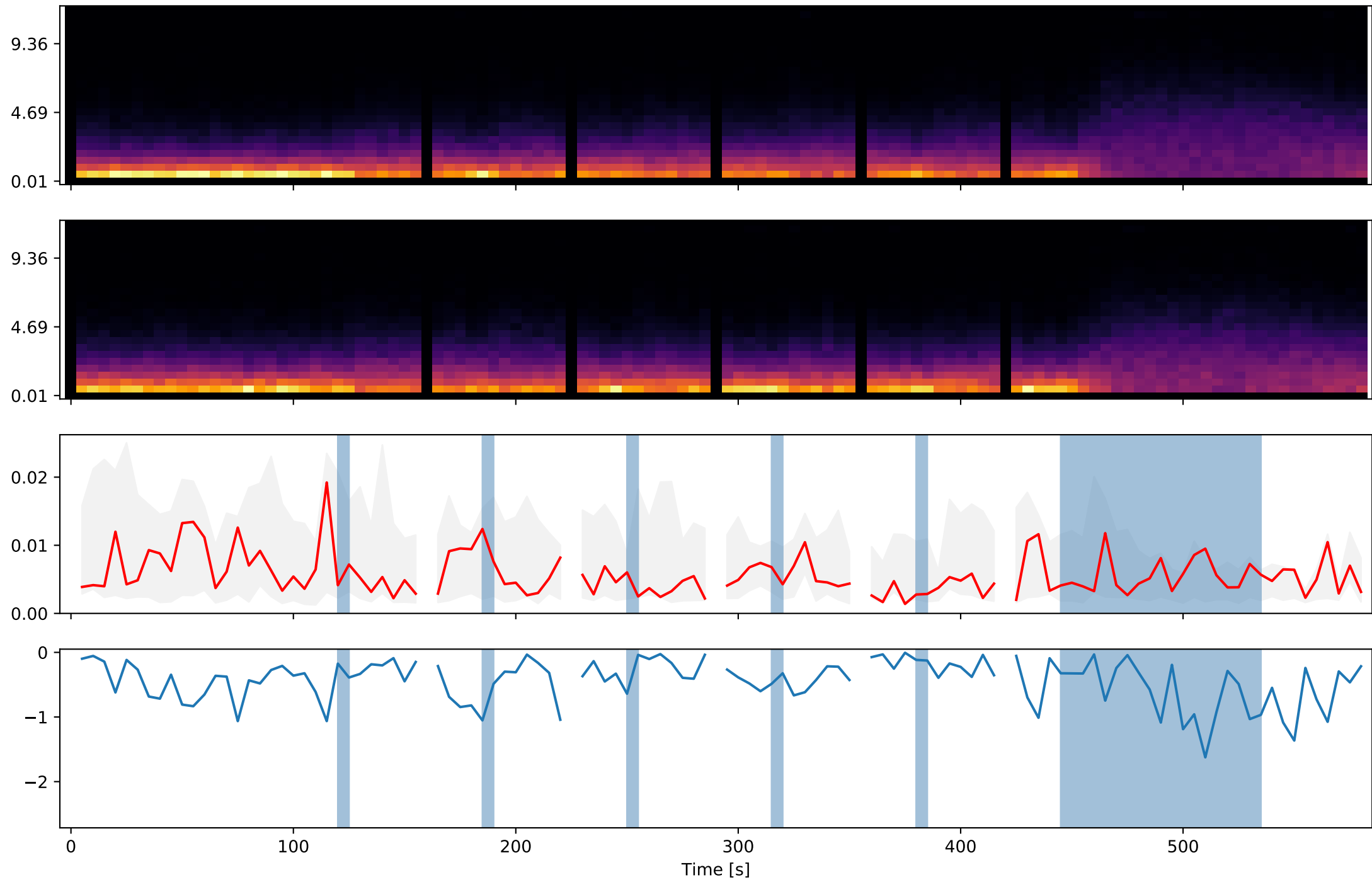
angular\_velocity\_hips - pval: 0.7473002159827213



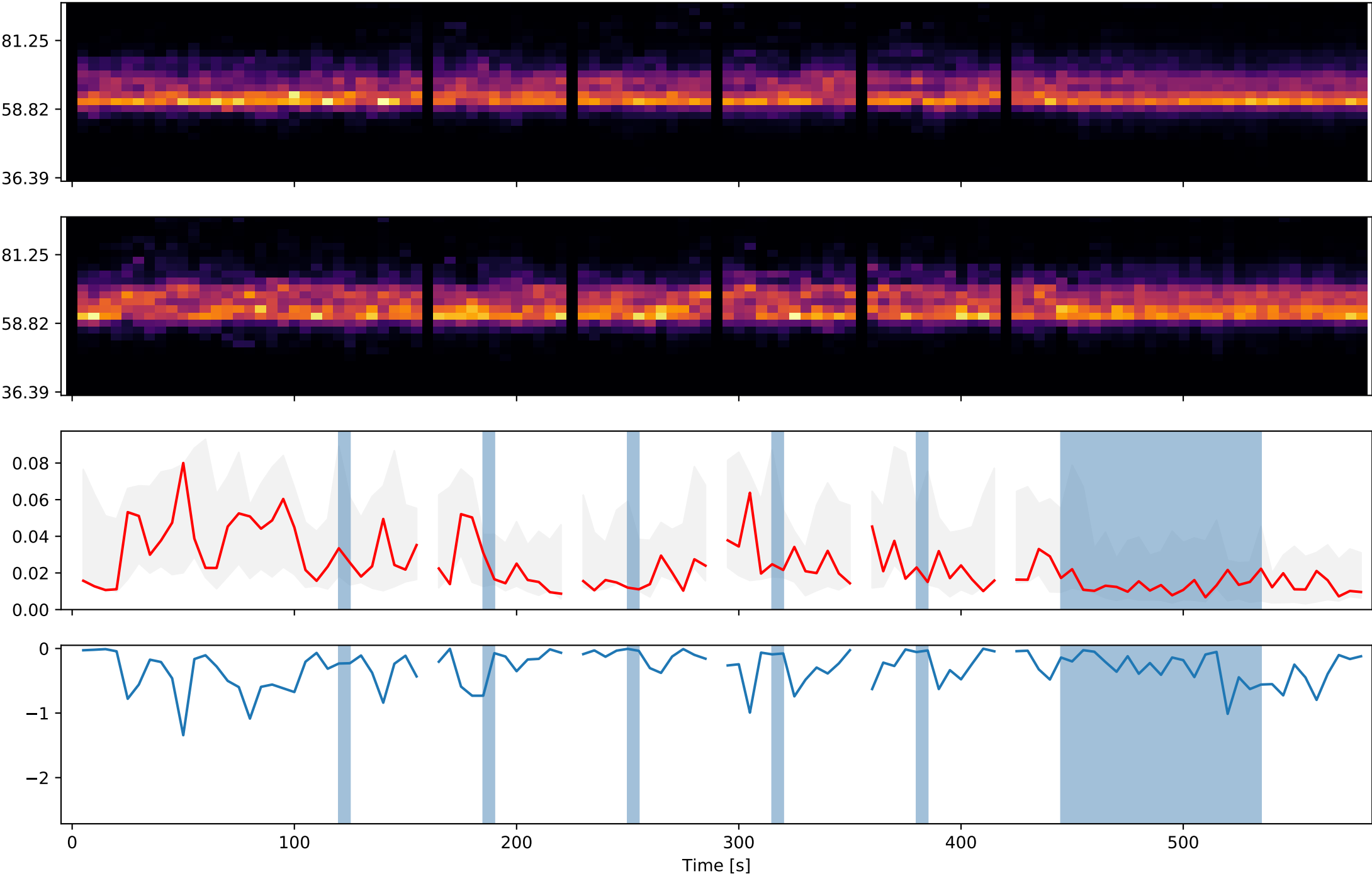
relative\_to\_body\_radial\_velocity\_tail\_tip - pval: 0.7537796976241901



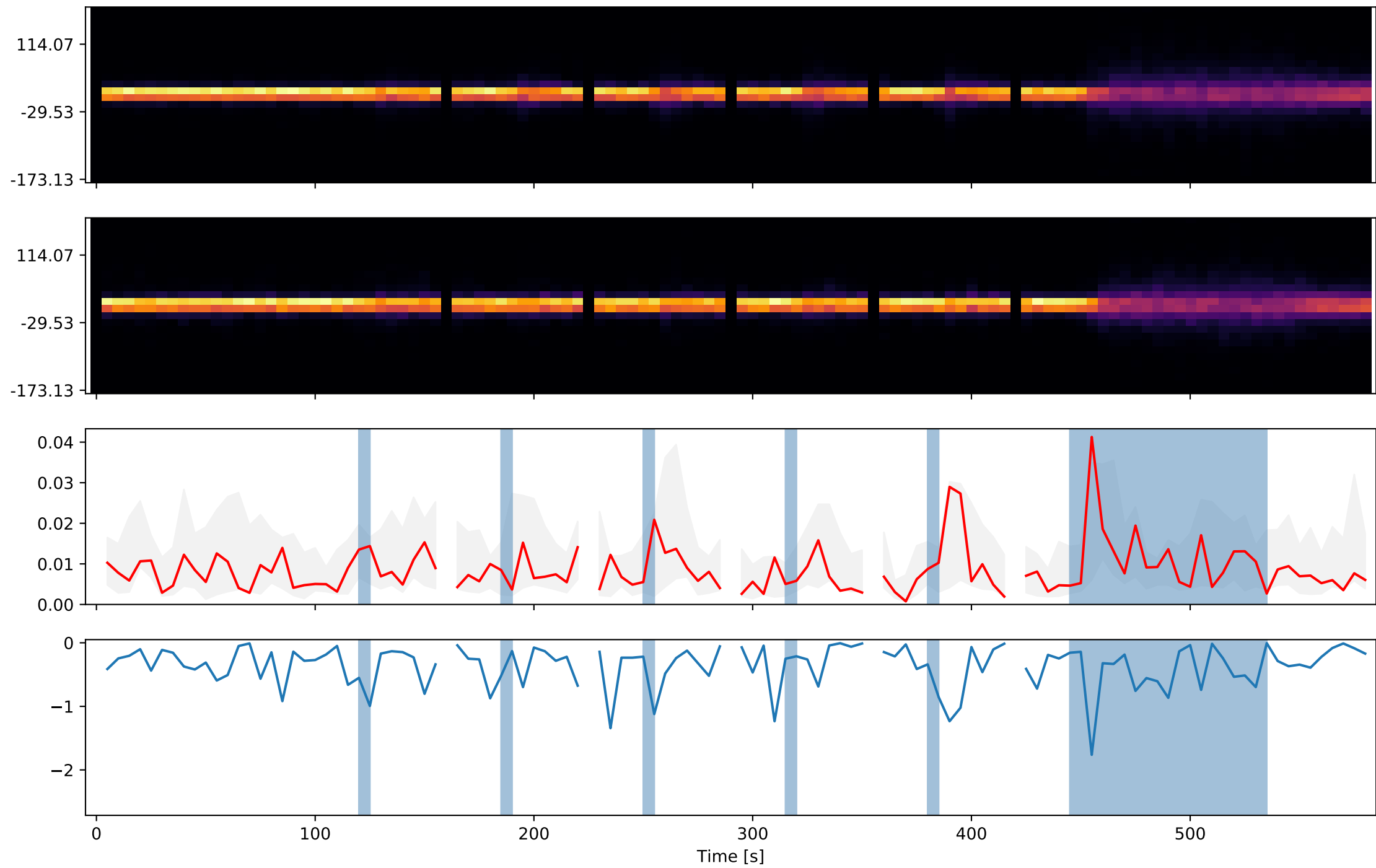
d\_relative\_to\_head\_base\_angular\_velocity\_head\_tip - pval: 0.7537796976241901



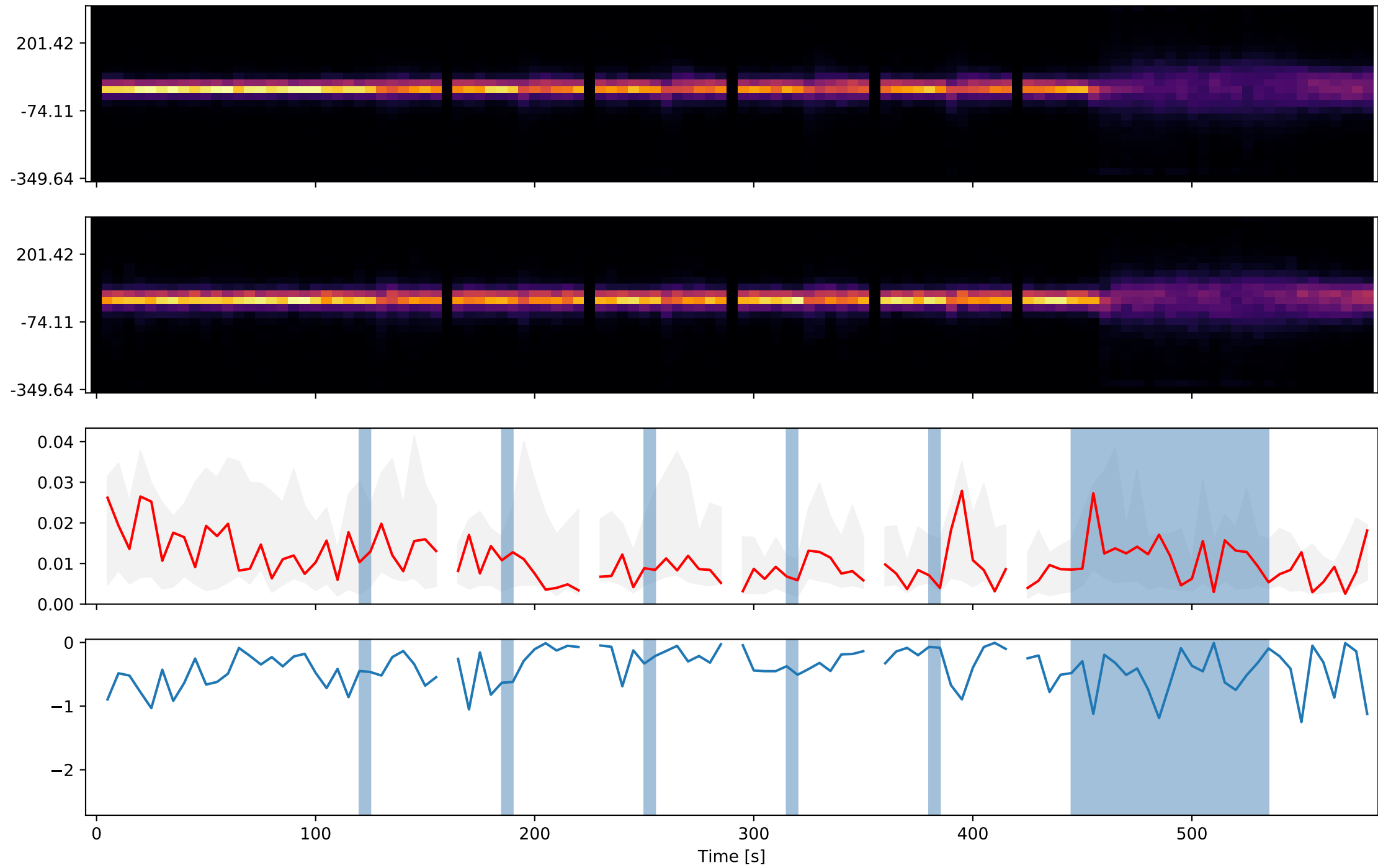
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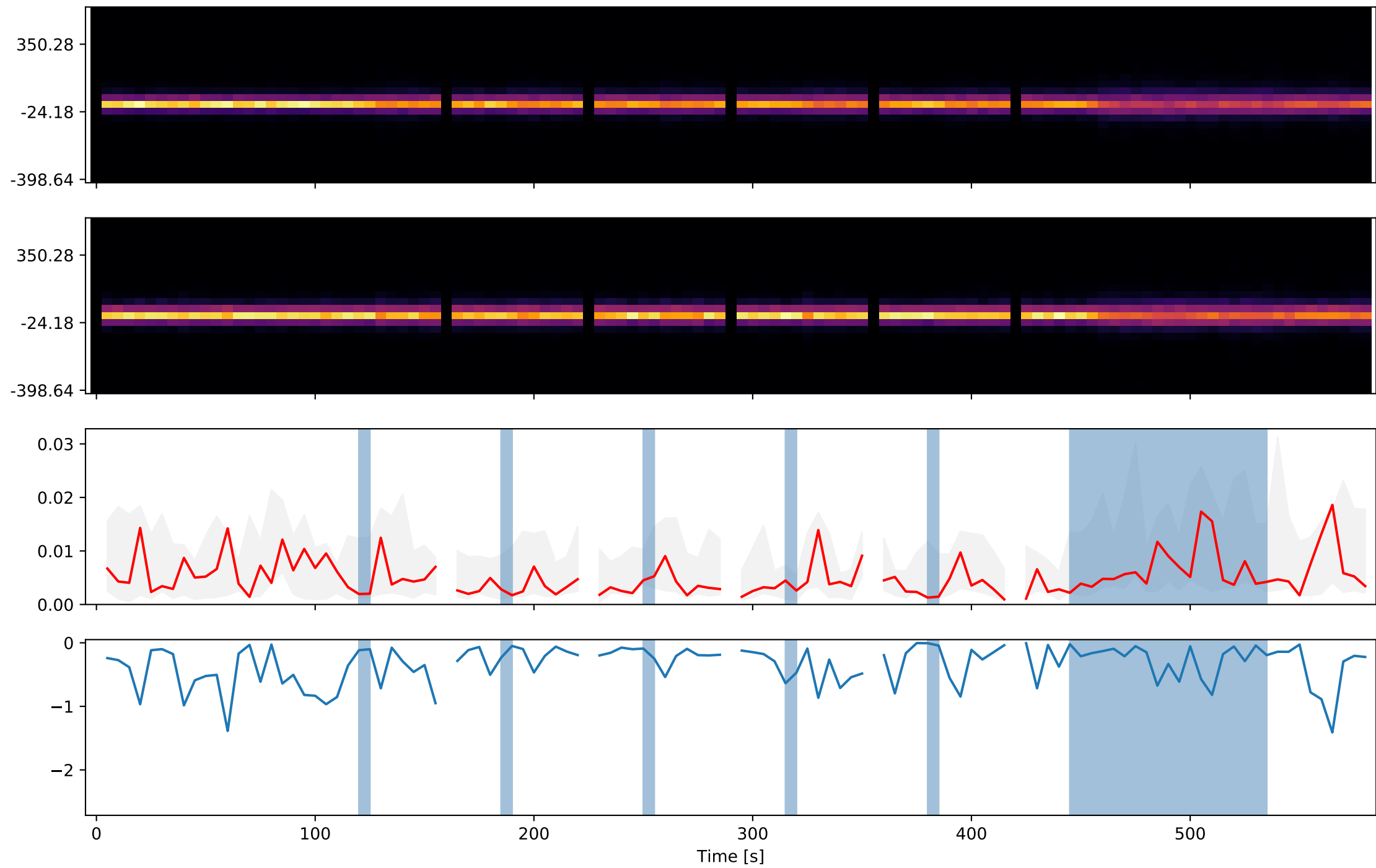
relative\_to\_body\_radial\_velocity\_hips - pval: 0.7688984881209503



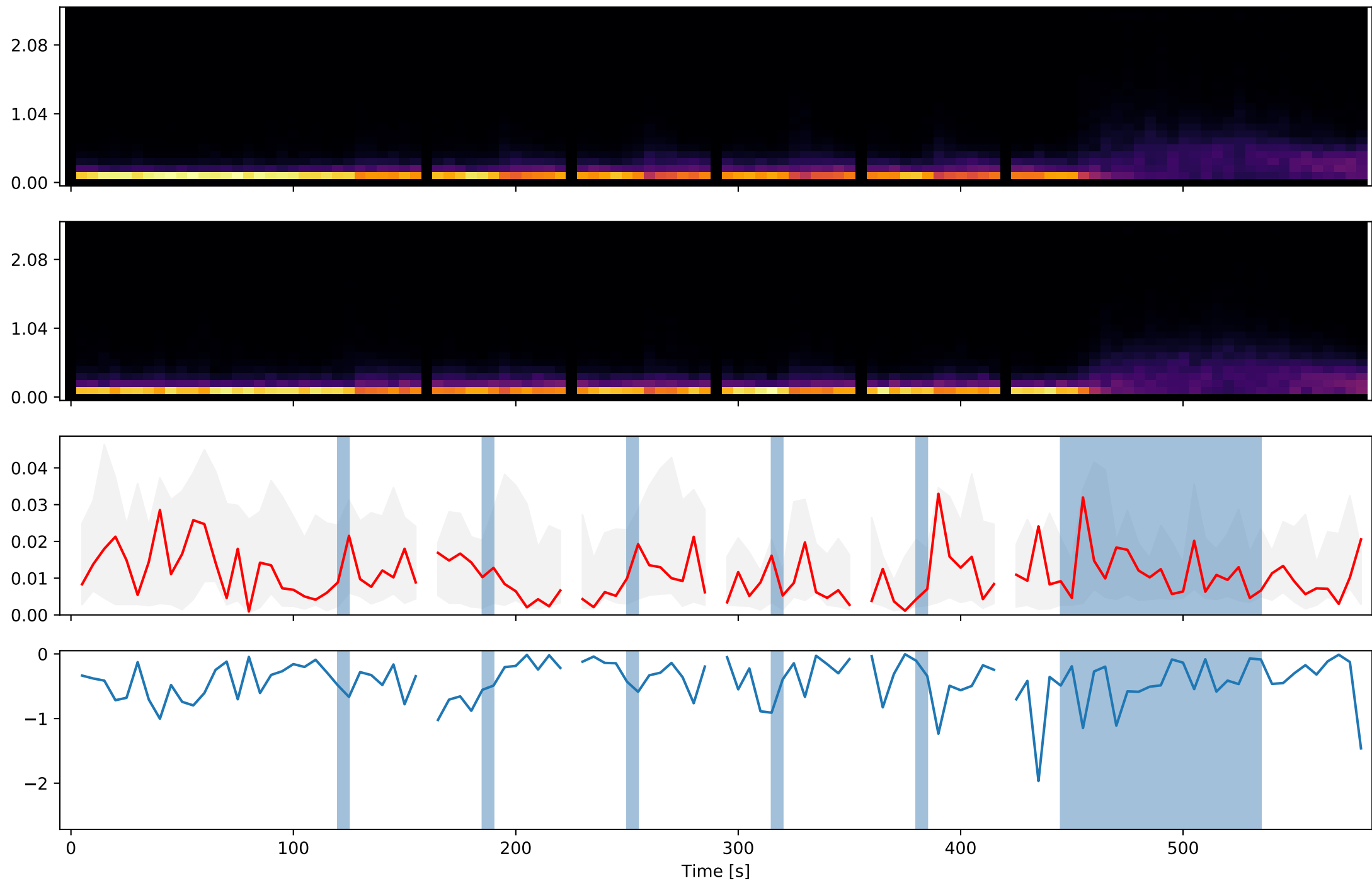
relative\_to\_body\_radial\_velocity\_head\_tip - pval: 0.7732181425485961



d\_relative\_to\_head\_base\_radial\_velocity\_head\_tip - pval: 0.7775377969762419

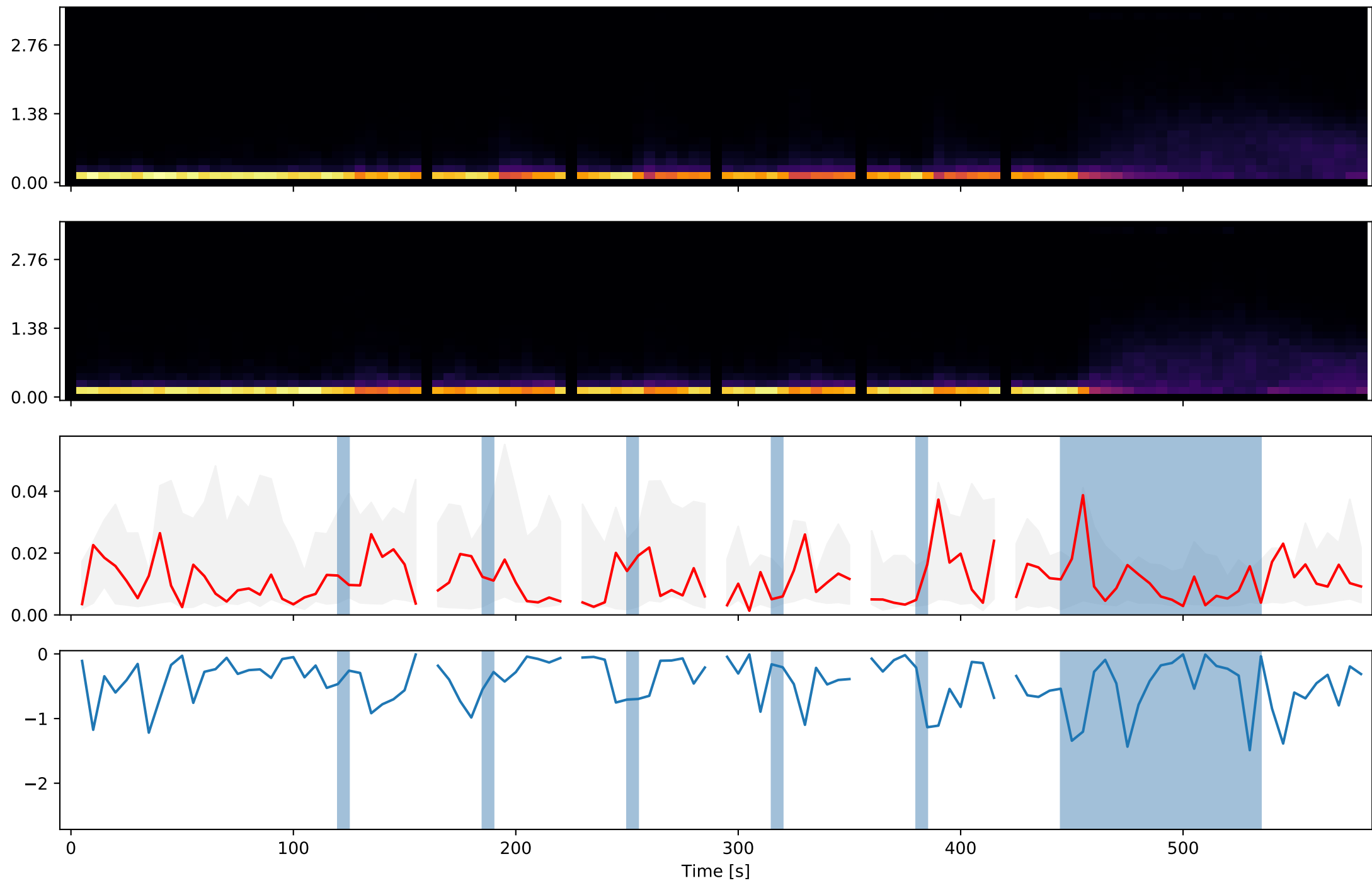


relative\_to\_body\_angular\_velocity\_head\_tip - pval: 0.7883369330453563

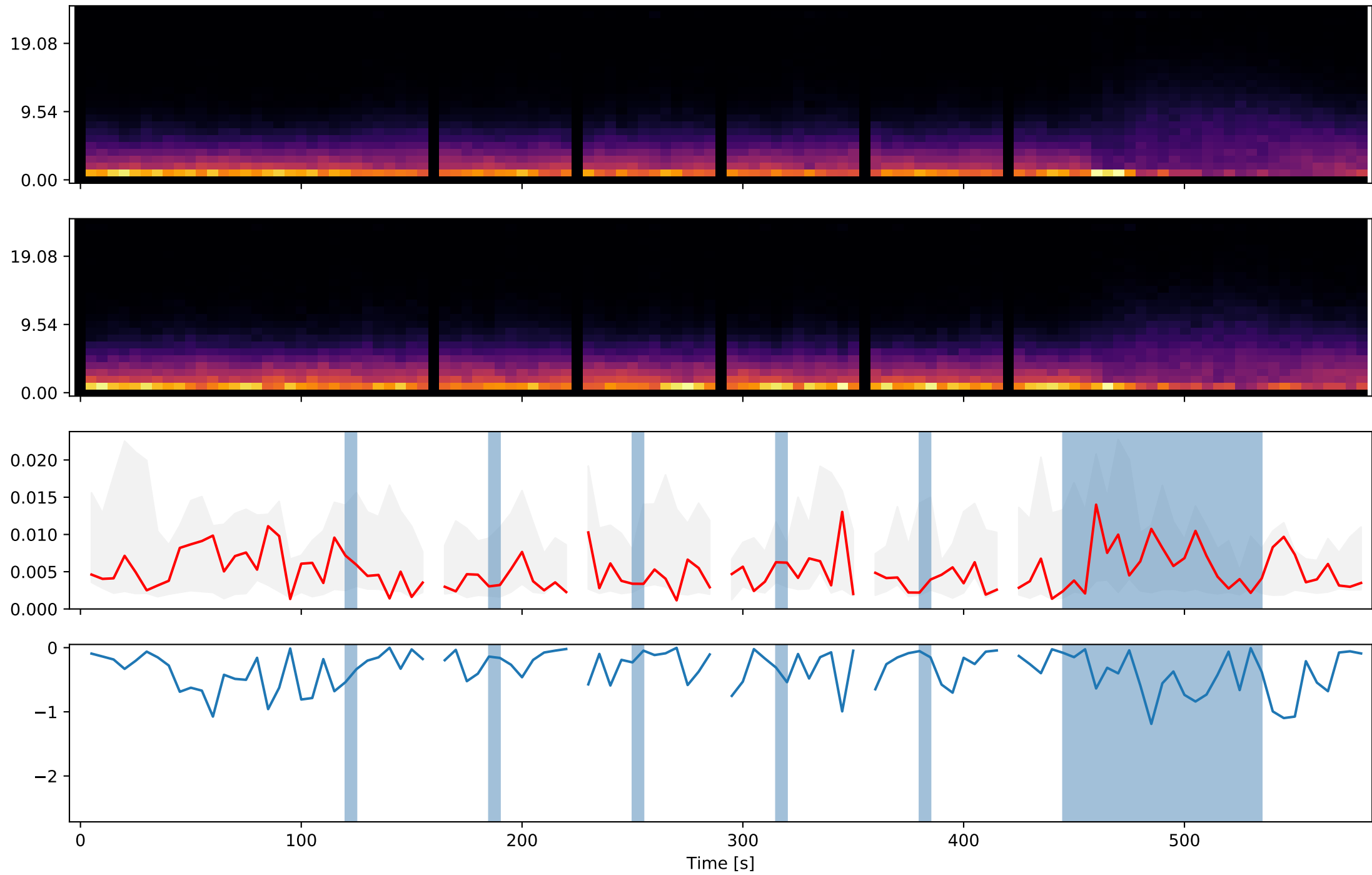




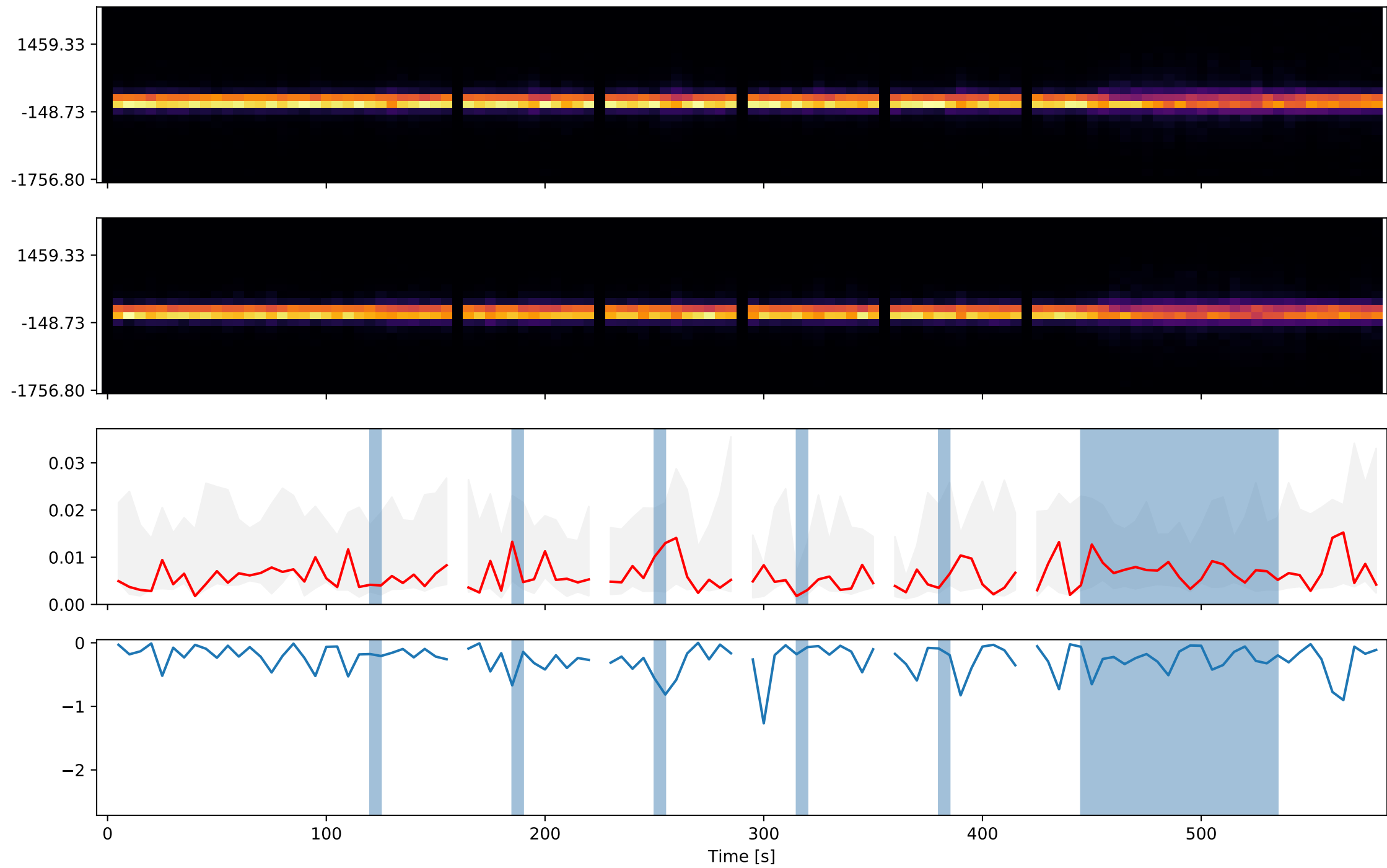
angular\_velocity\_midbody - pval: 0.7883369330453563



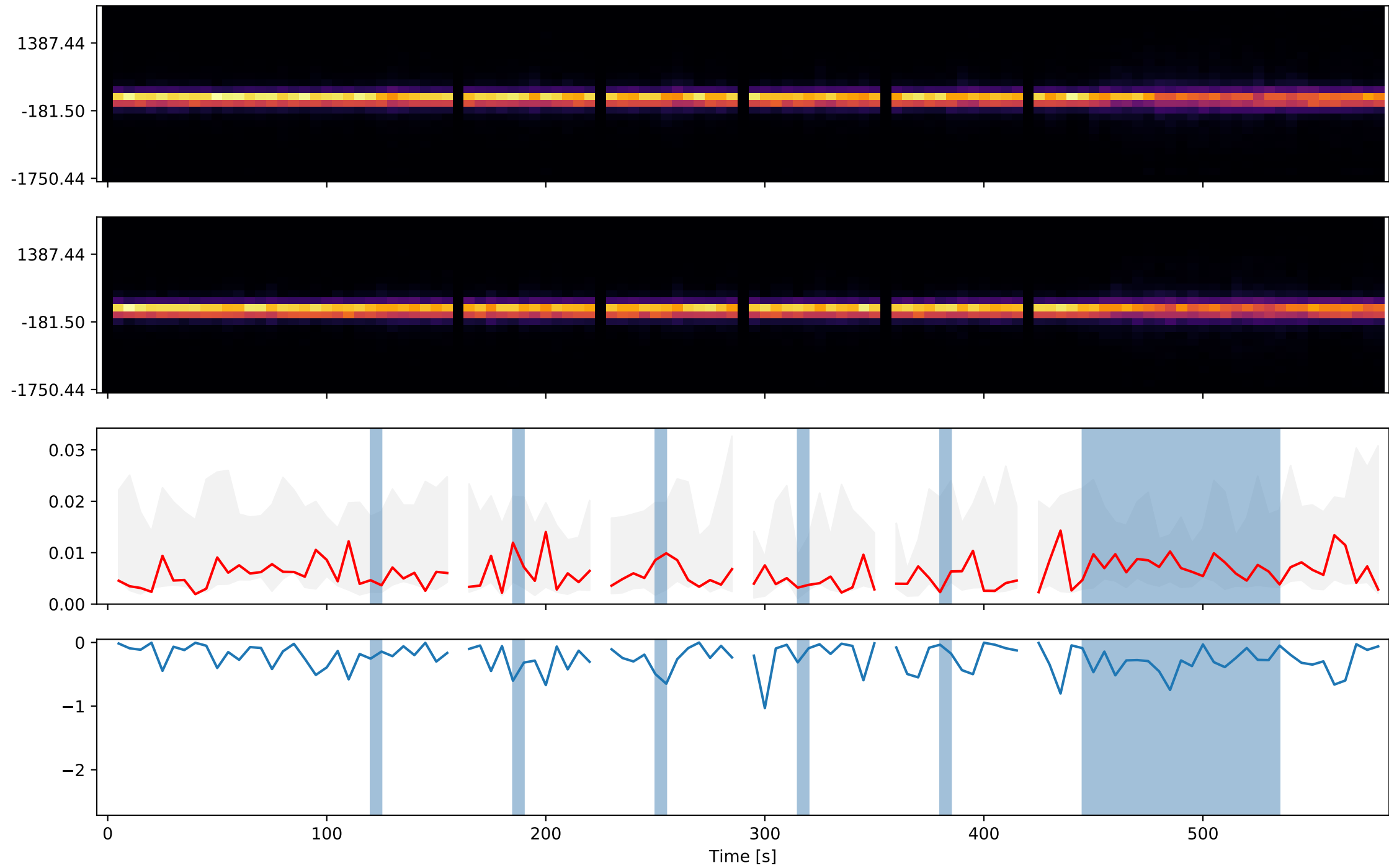
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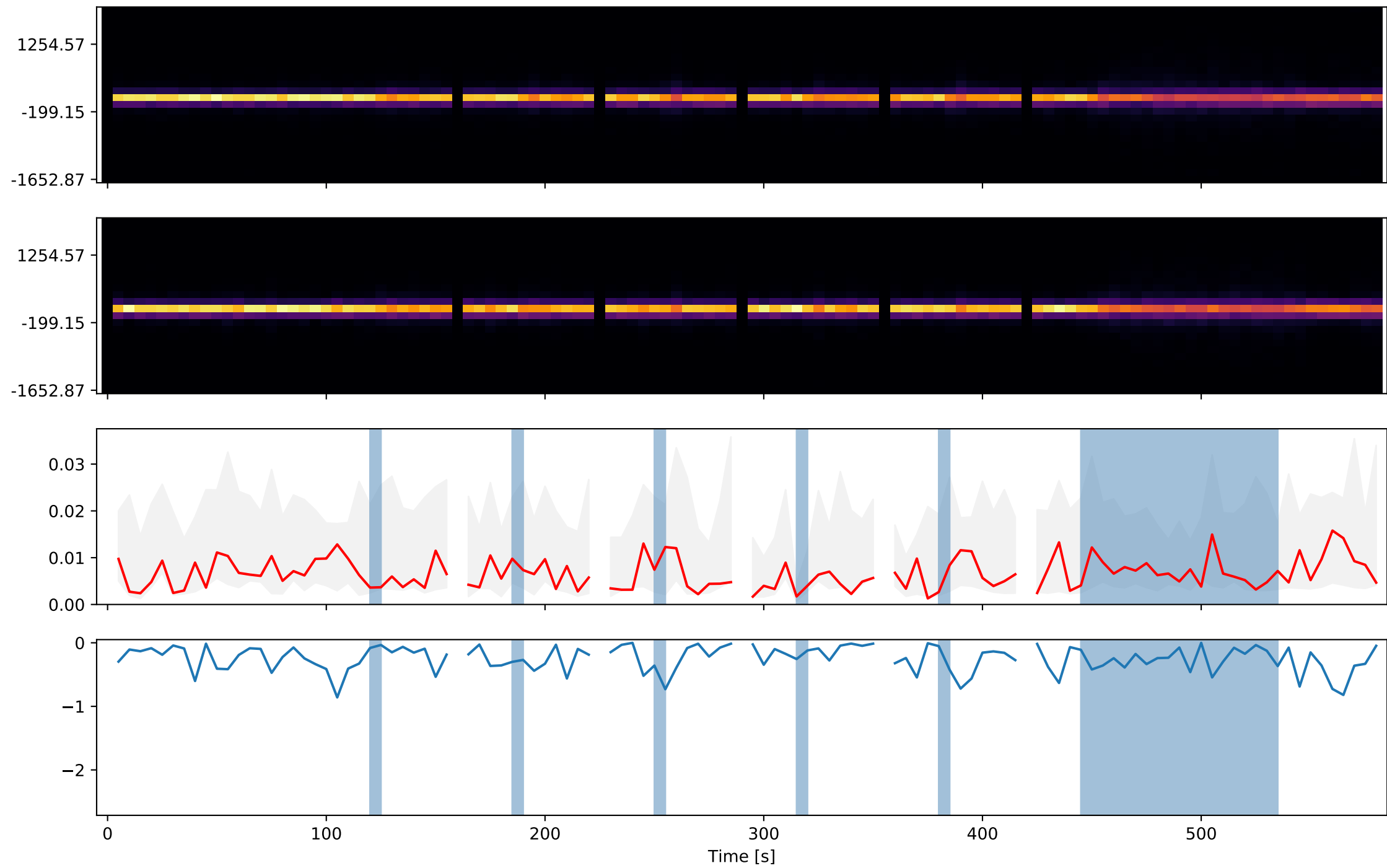
d\_speed\_neck - pval: 0.8250539956803455



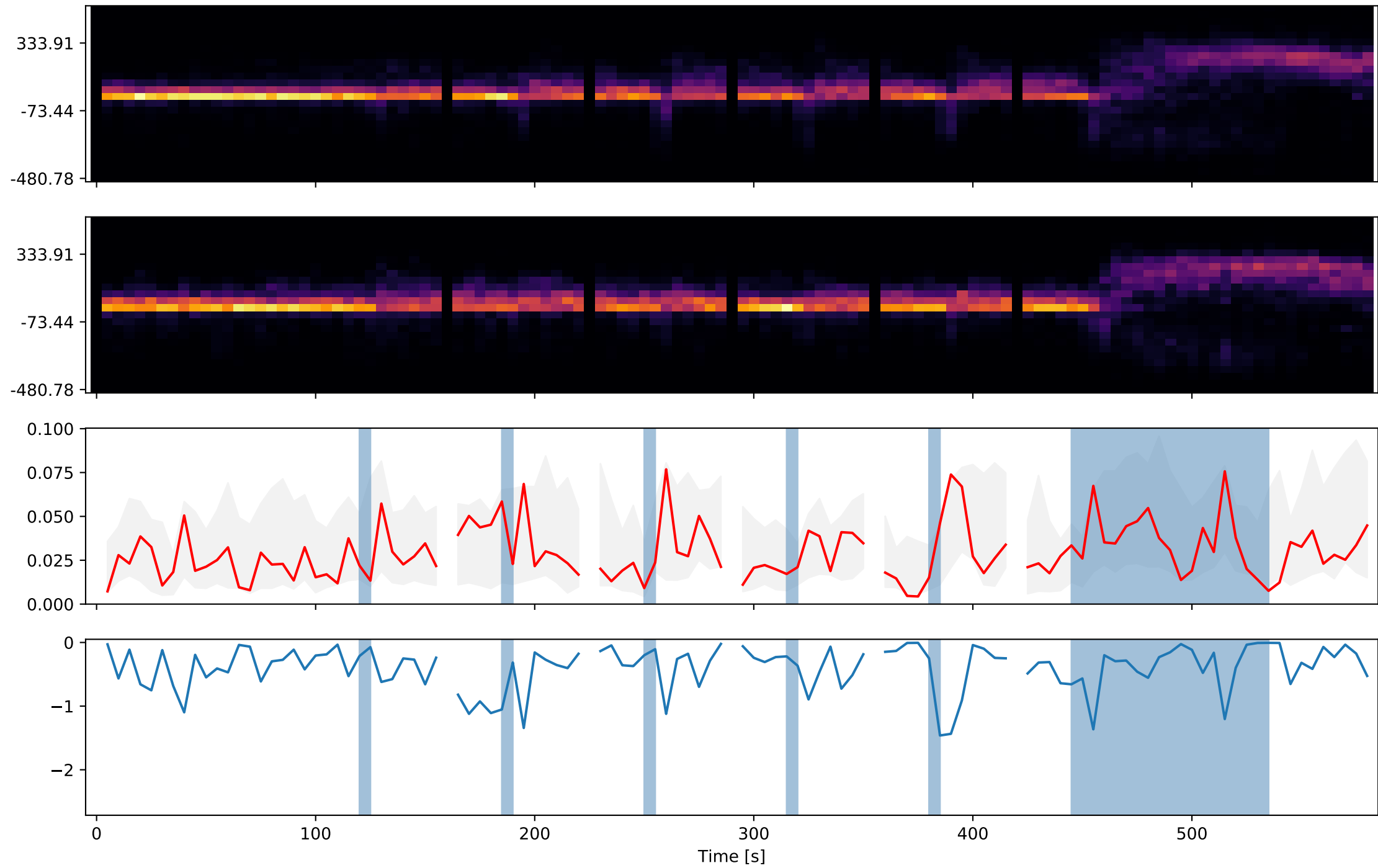
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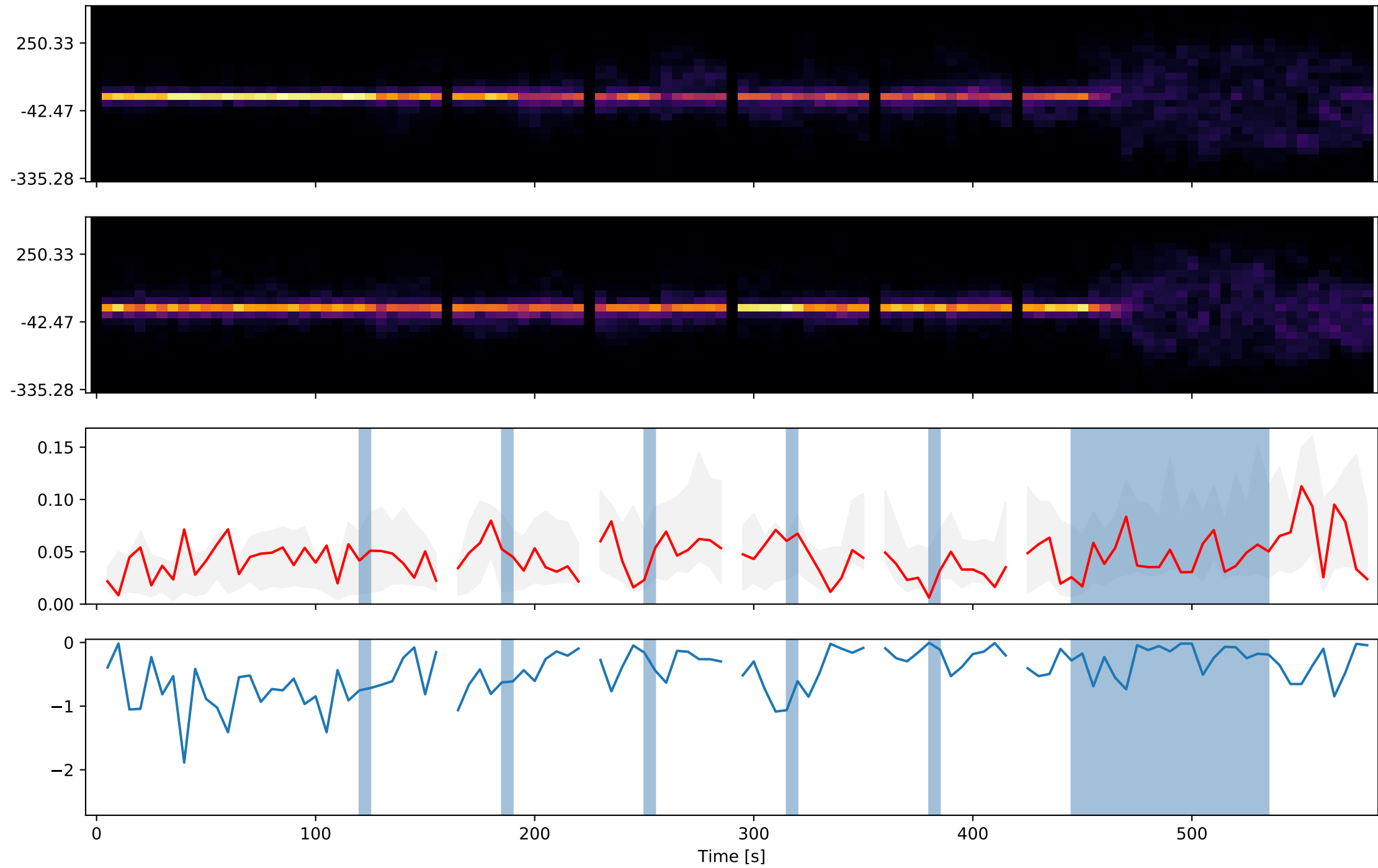
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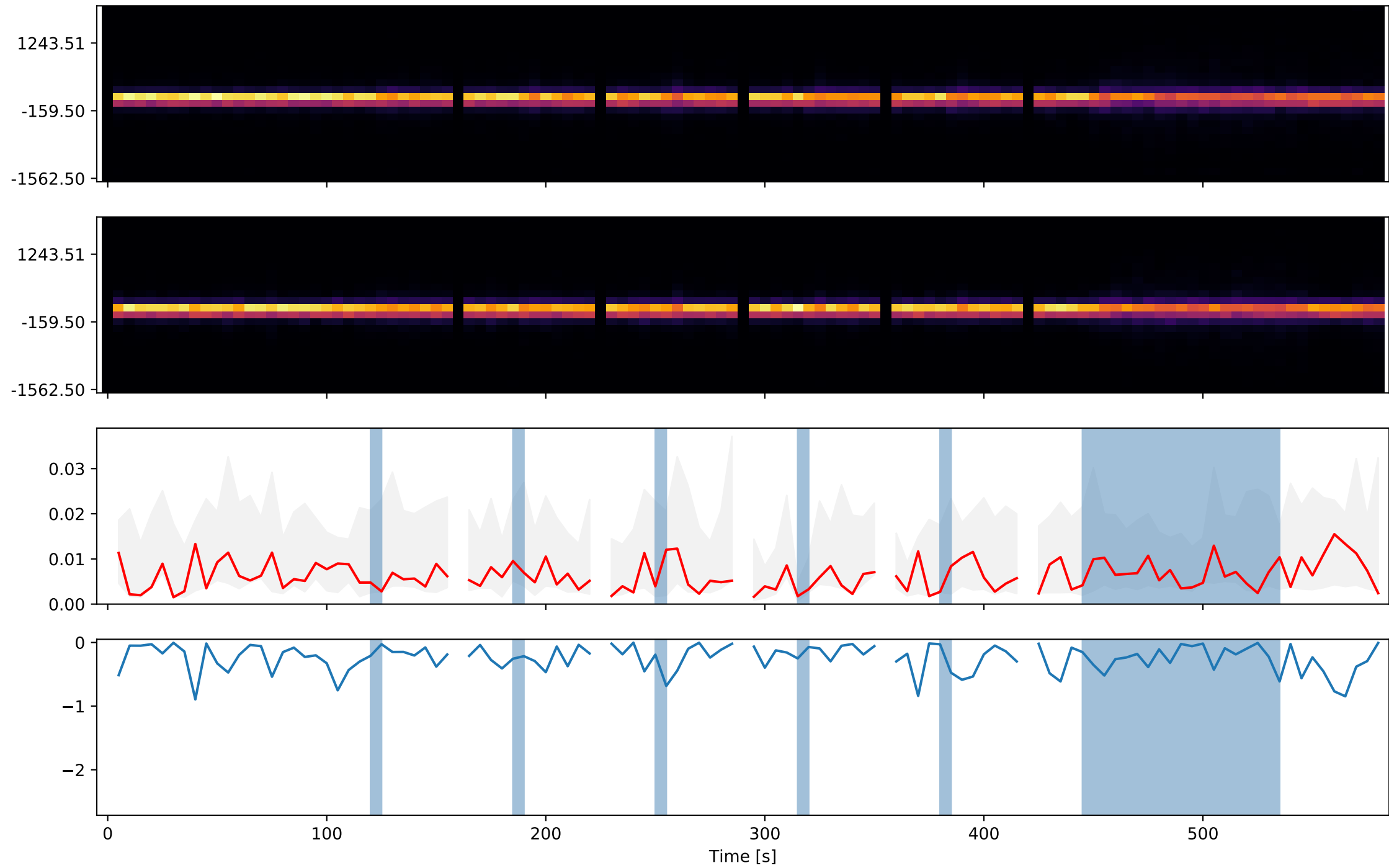
speed\_hips - pval: 0.8336933045356372



d\_dist\_from\_food\_edge - pval: 0.838012958963283

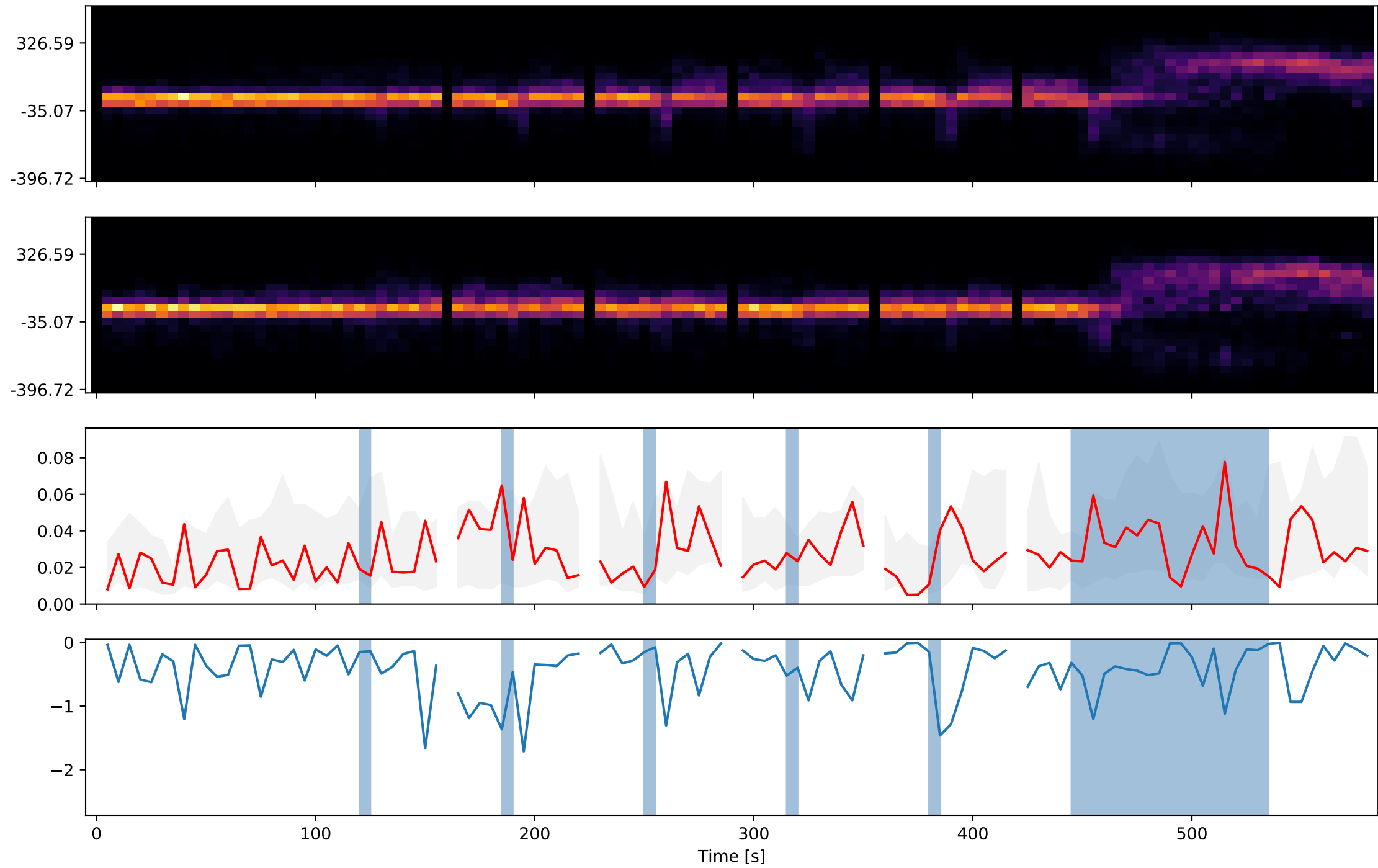


d\_speed\_tail\_base - pval: 0.8423326133909287

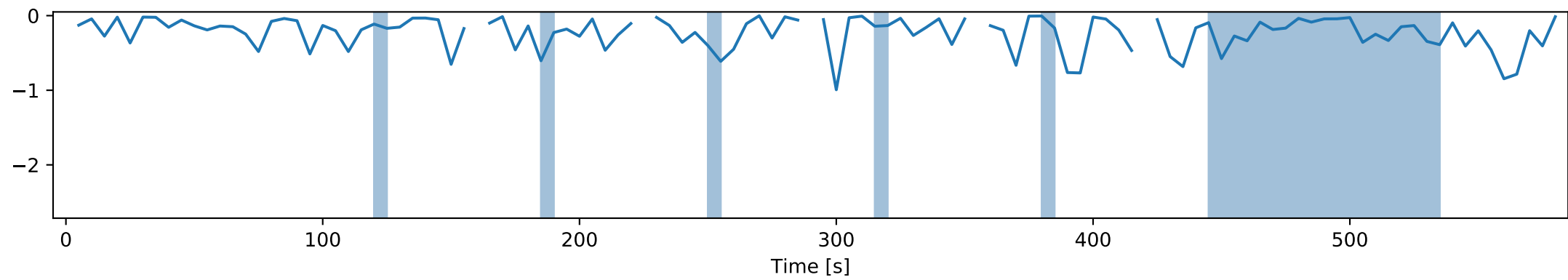
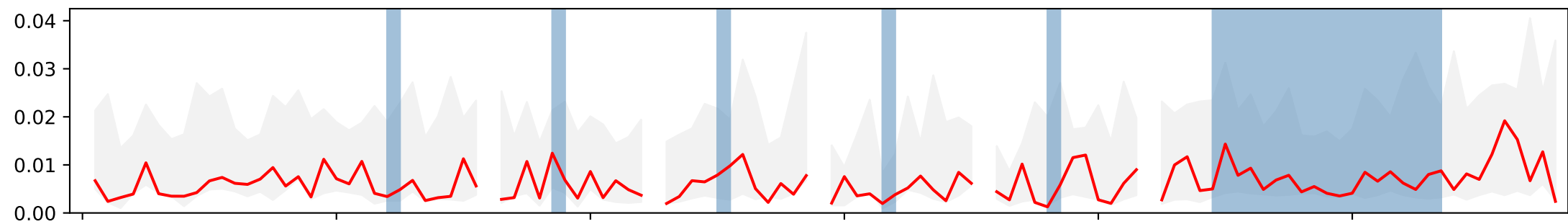
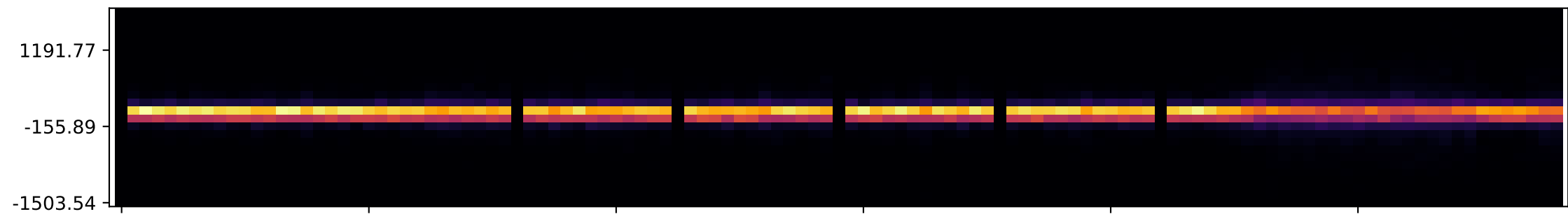
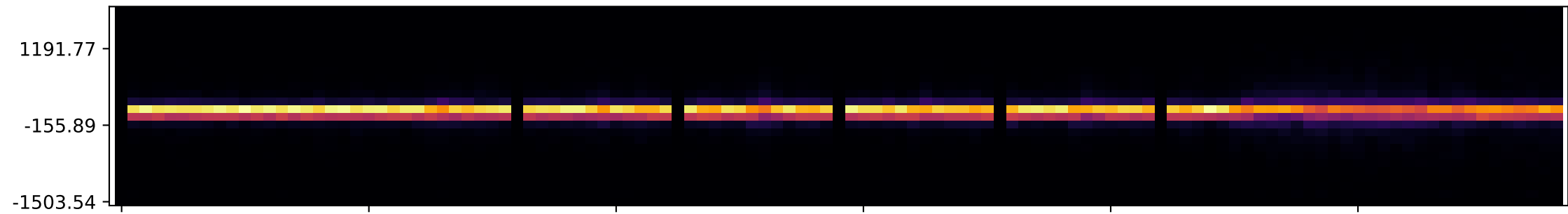




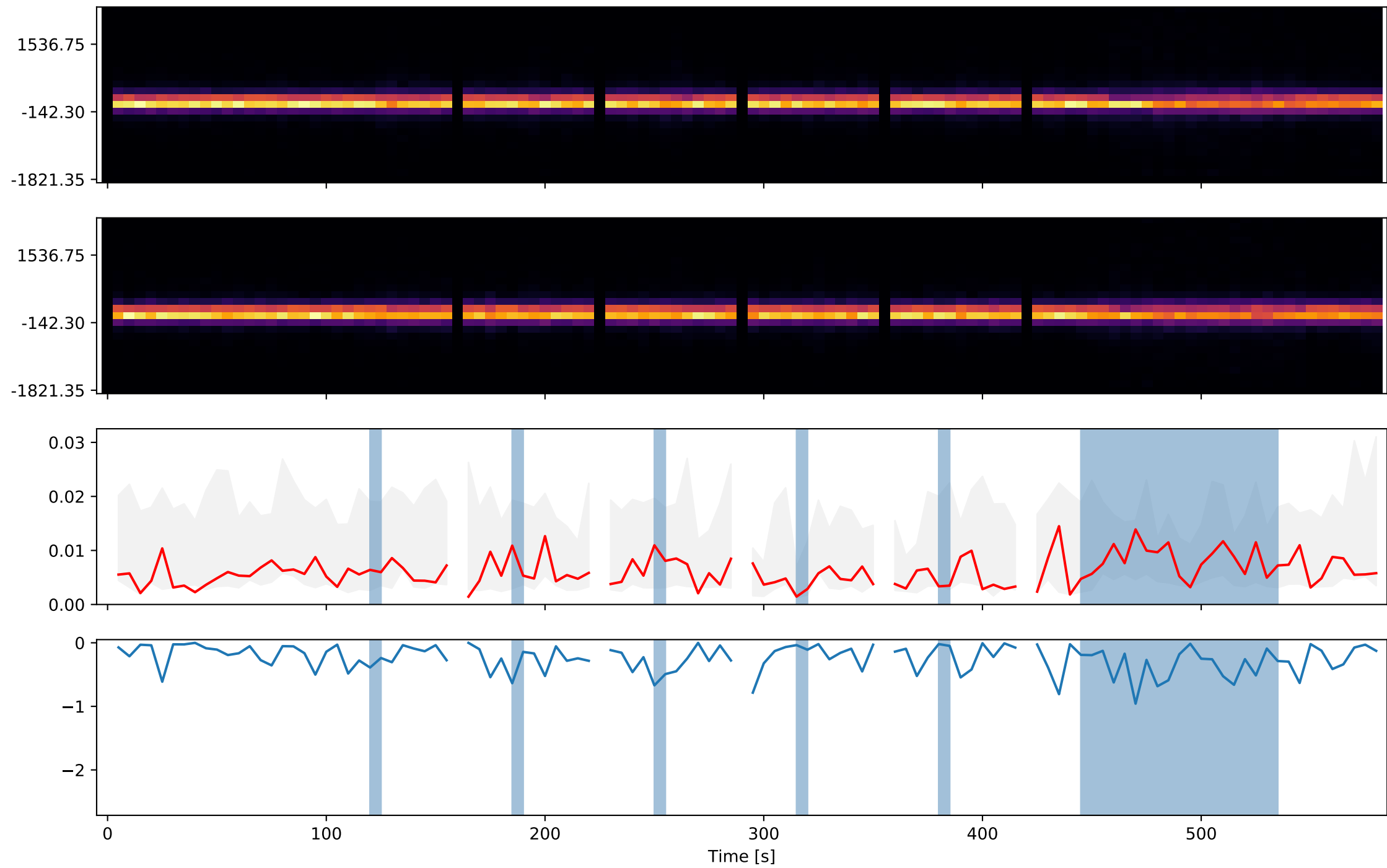
speed - pval: 0.8466522678185745



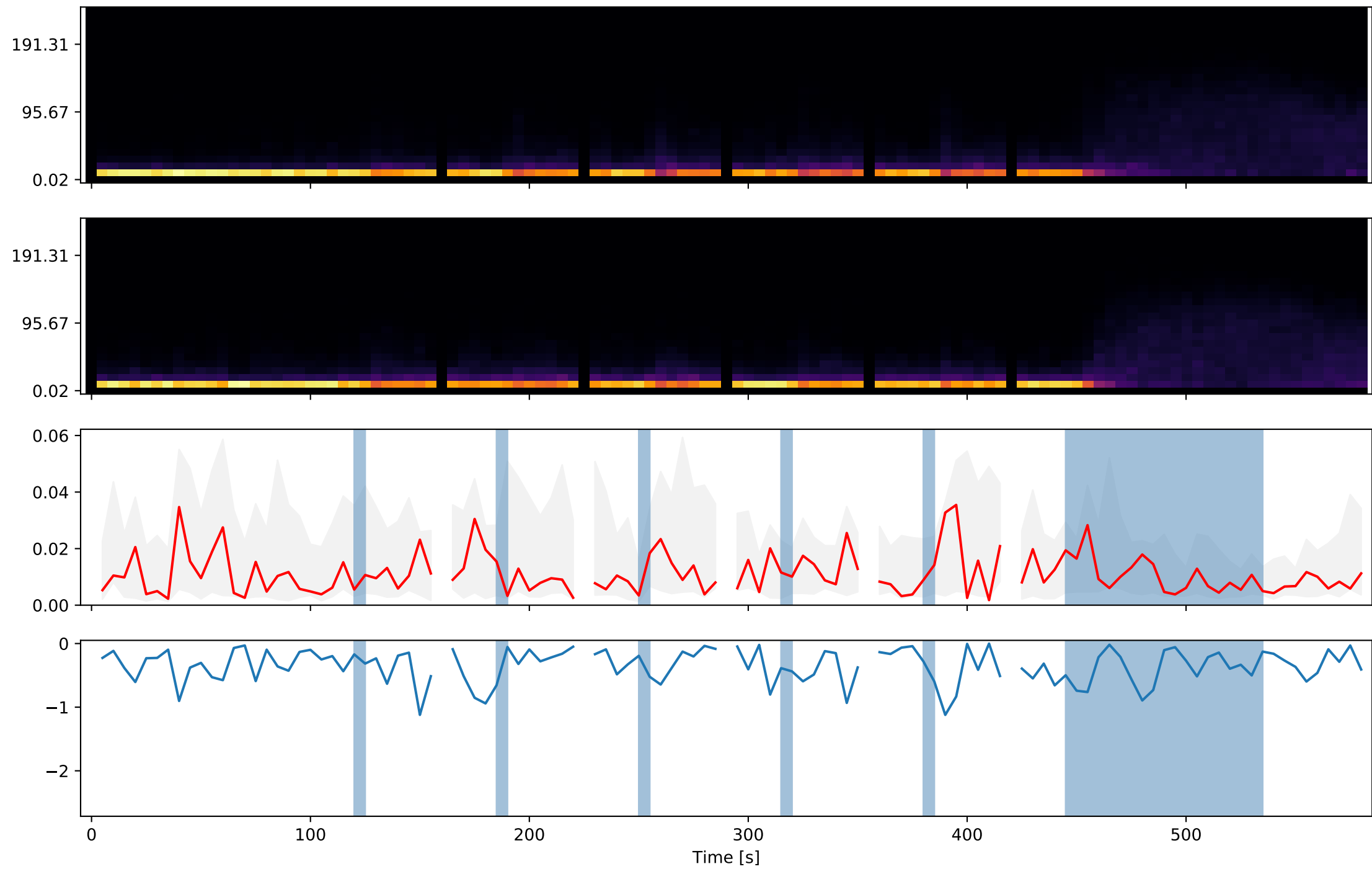
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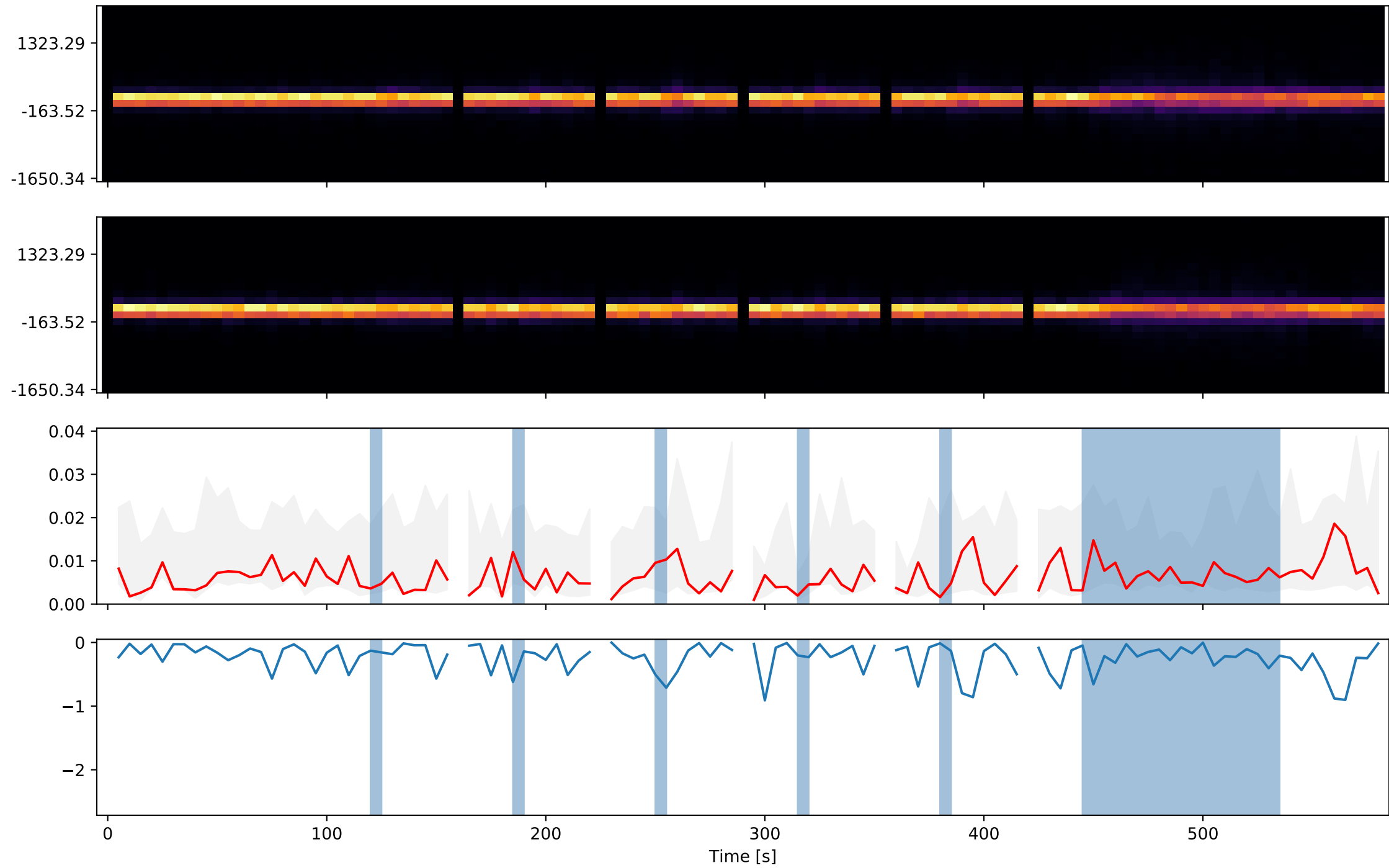
d\_speed\_head\_tip - pval: 0.8466522678185745



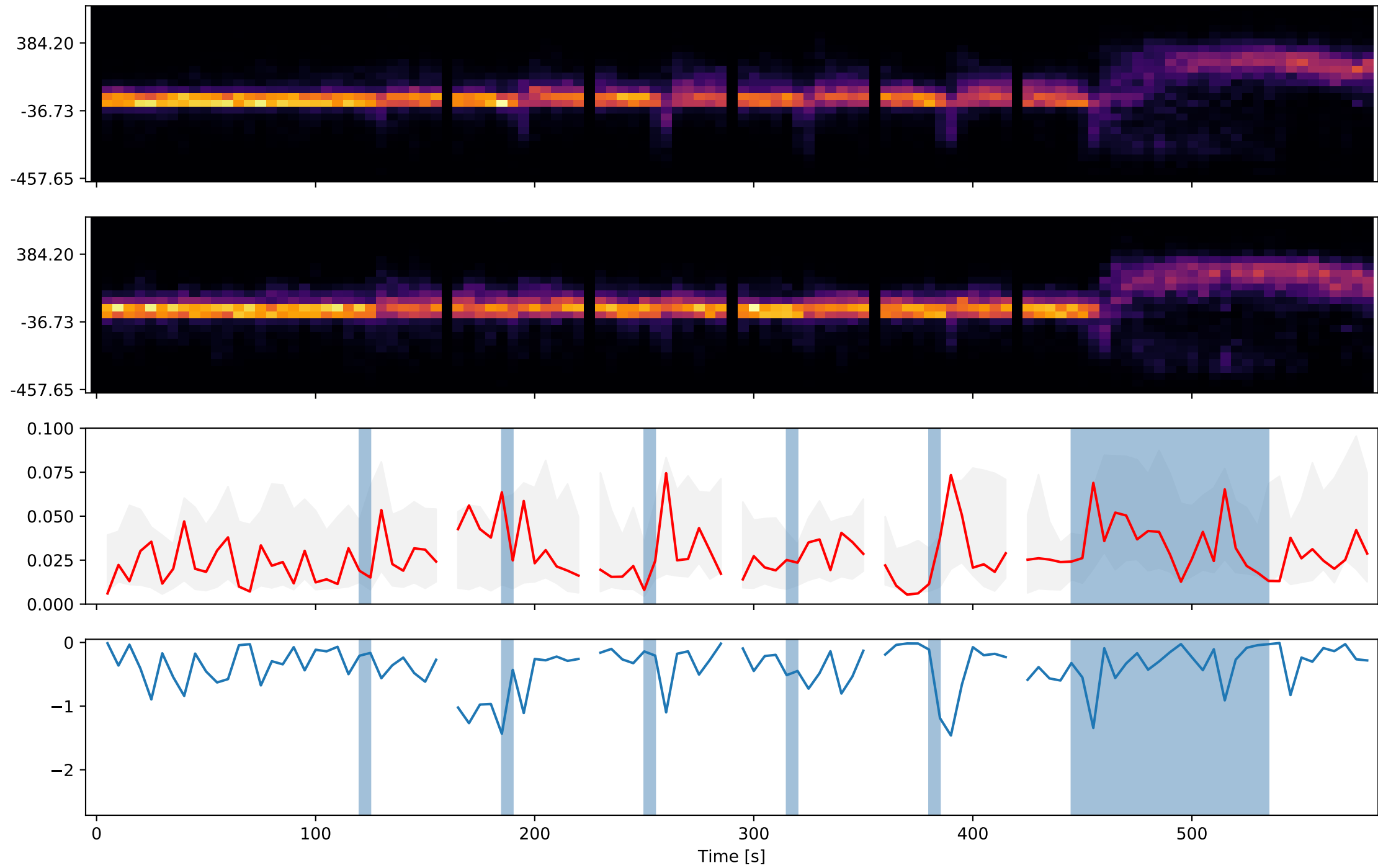
relative\_to\_body\_speed\_midbody - pval: 0.8488120950323974



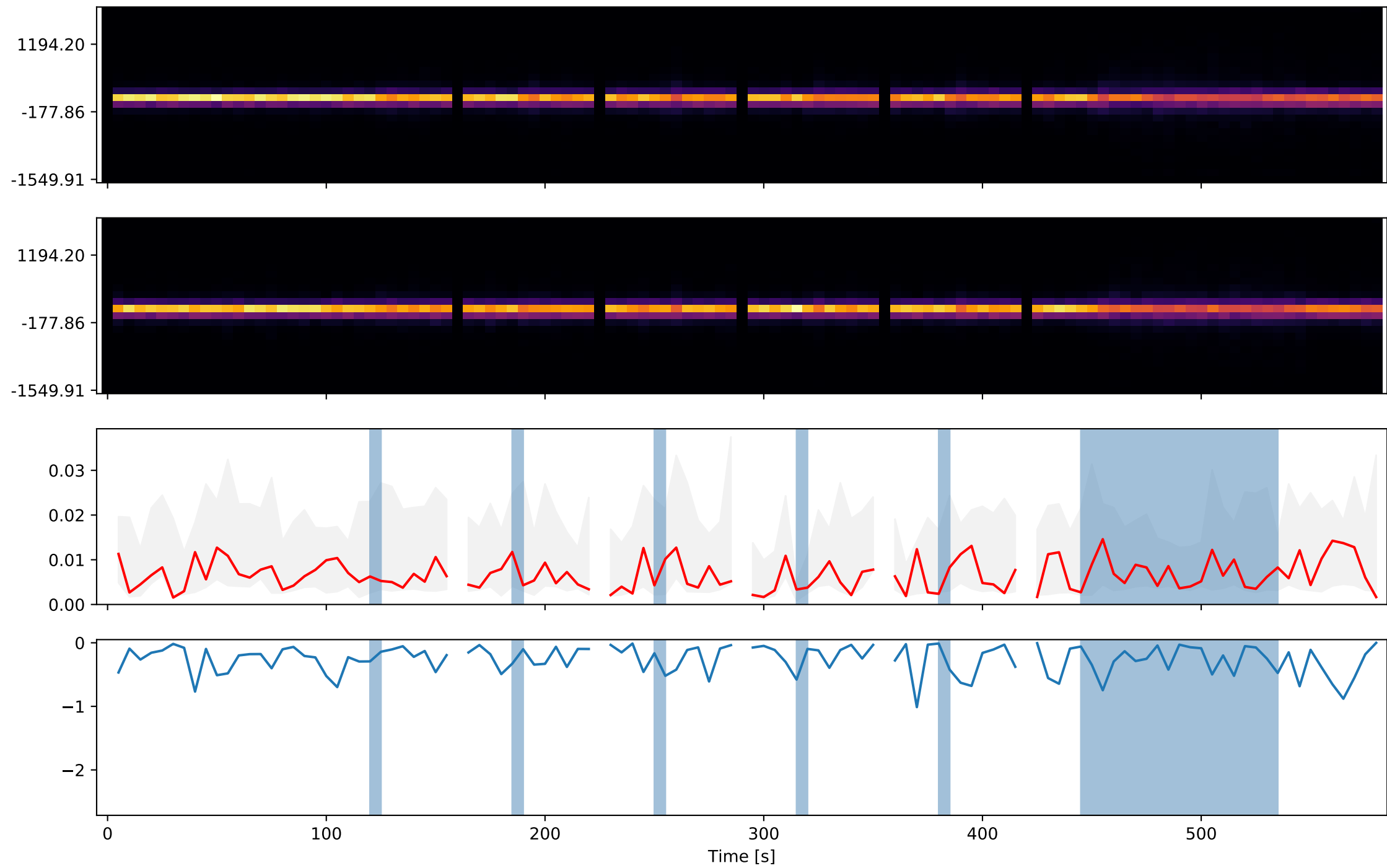
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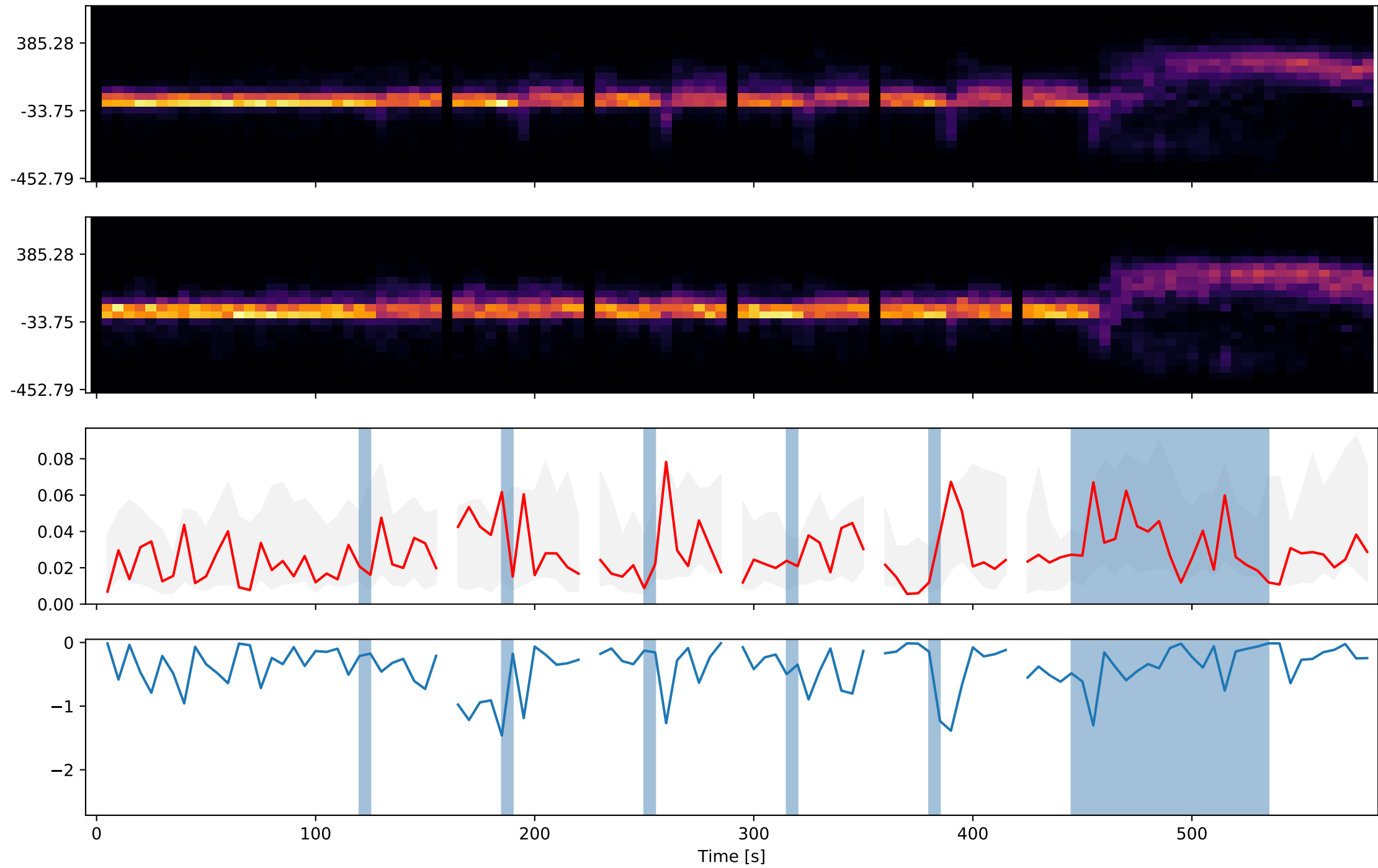
speed\_head\_base - pval: 0.8596112311015118



d\_speed\_tail\_tip - pval: 0.8617710583153347

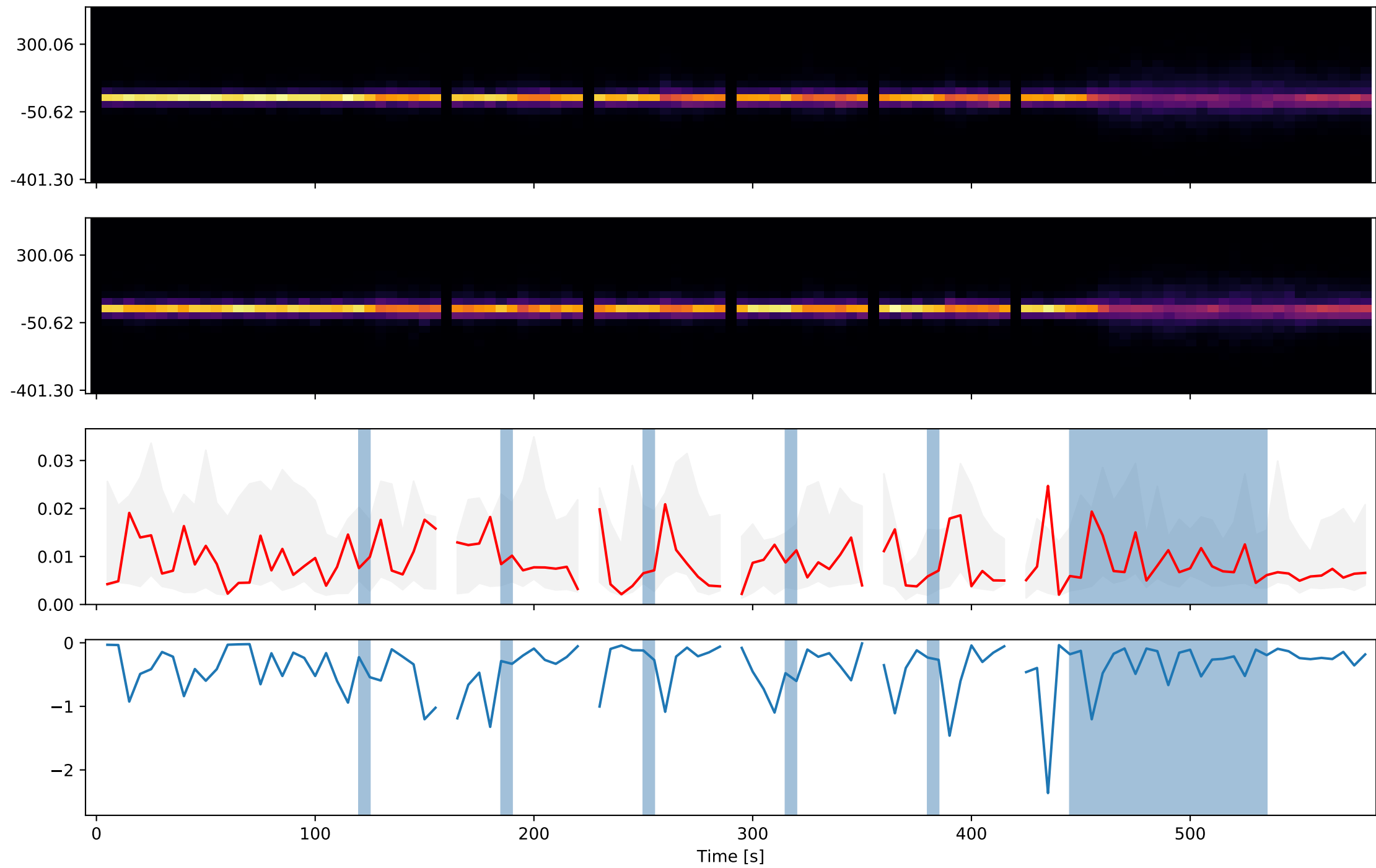


speed\_neck - pval: 0.8682505399568035

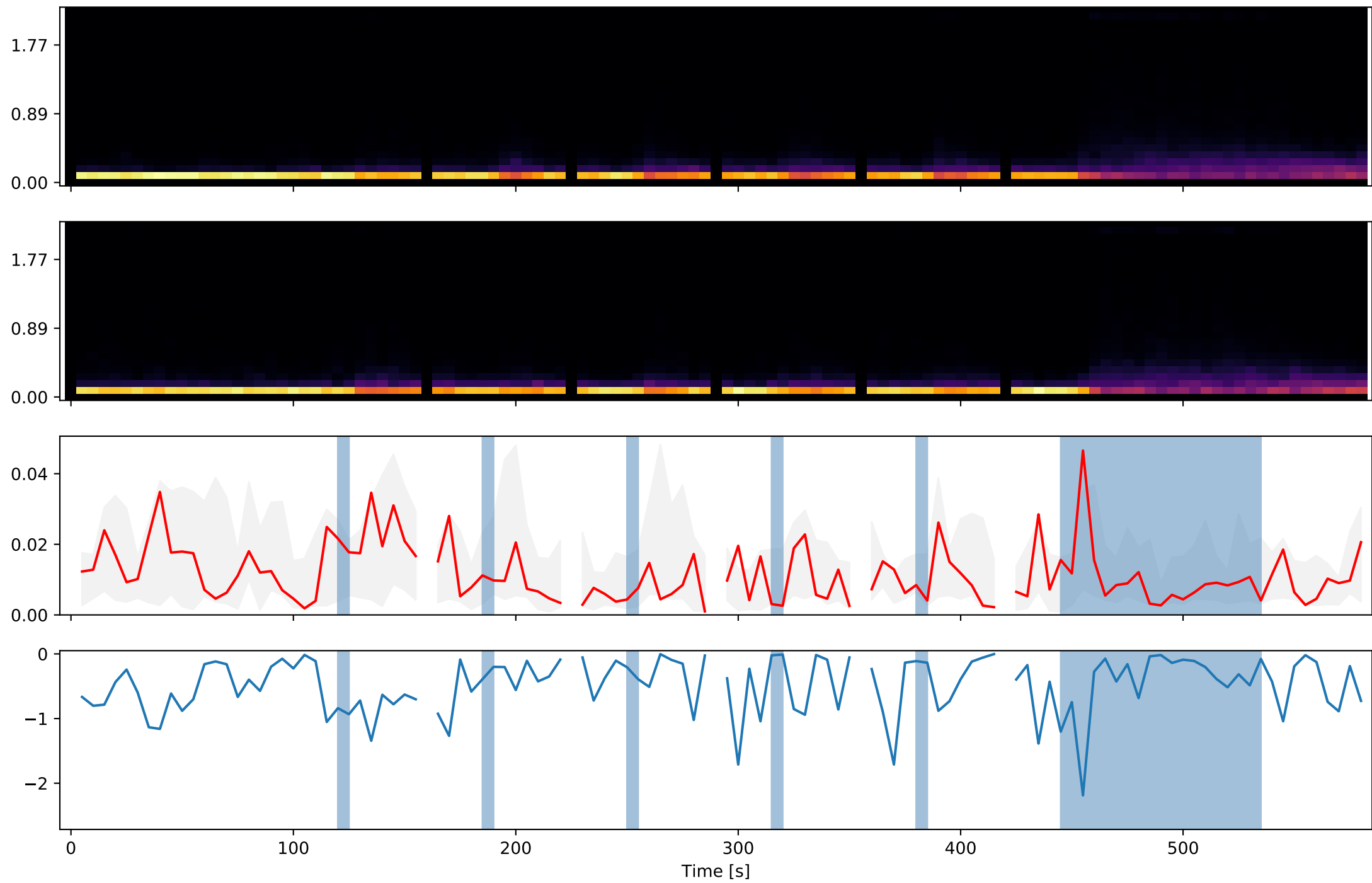




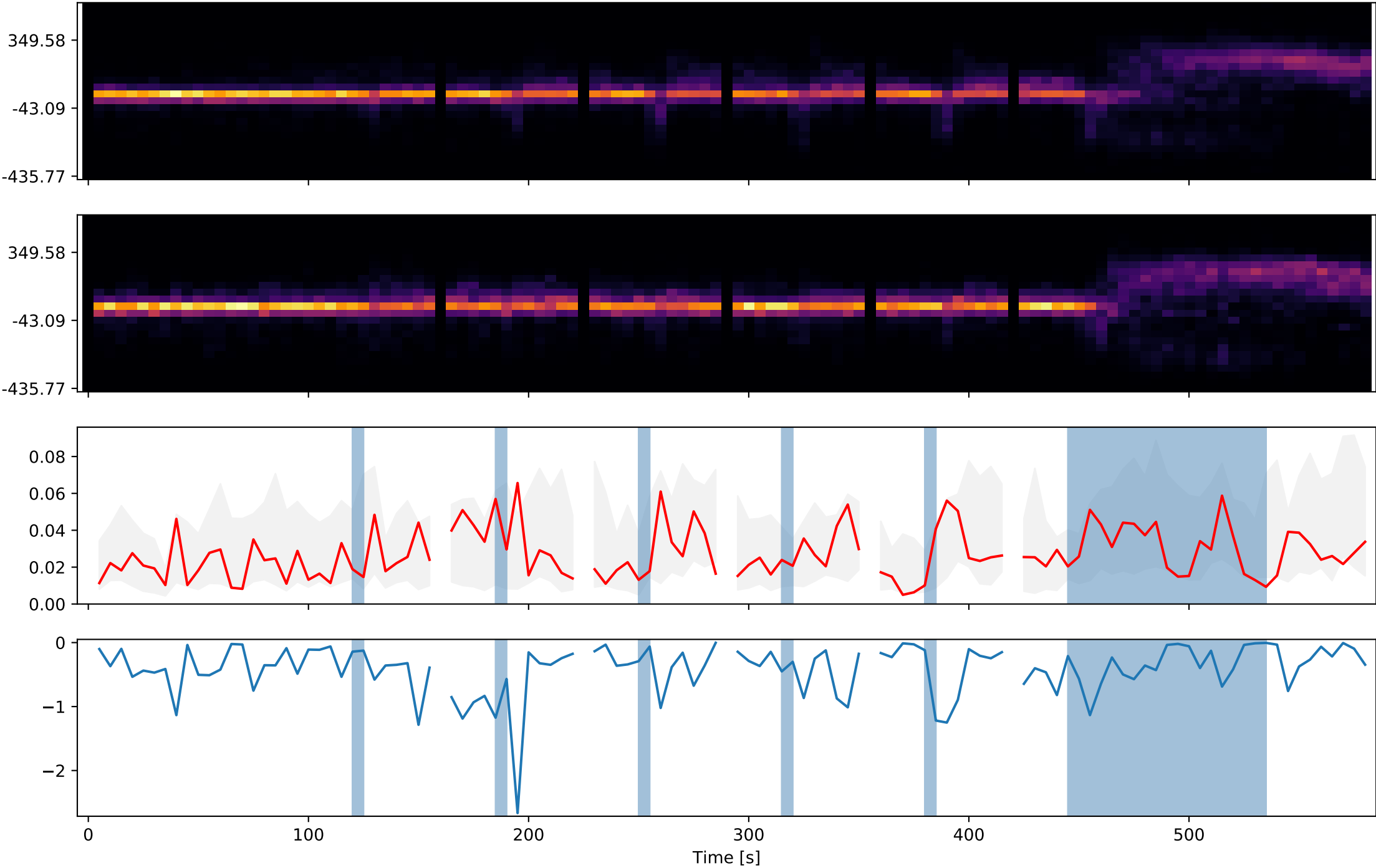
d\_minor\_axis - pval: 0.8682505399568035



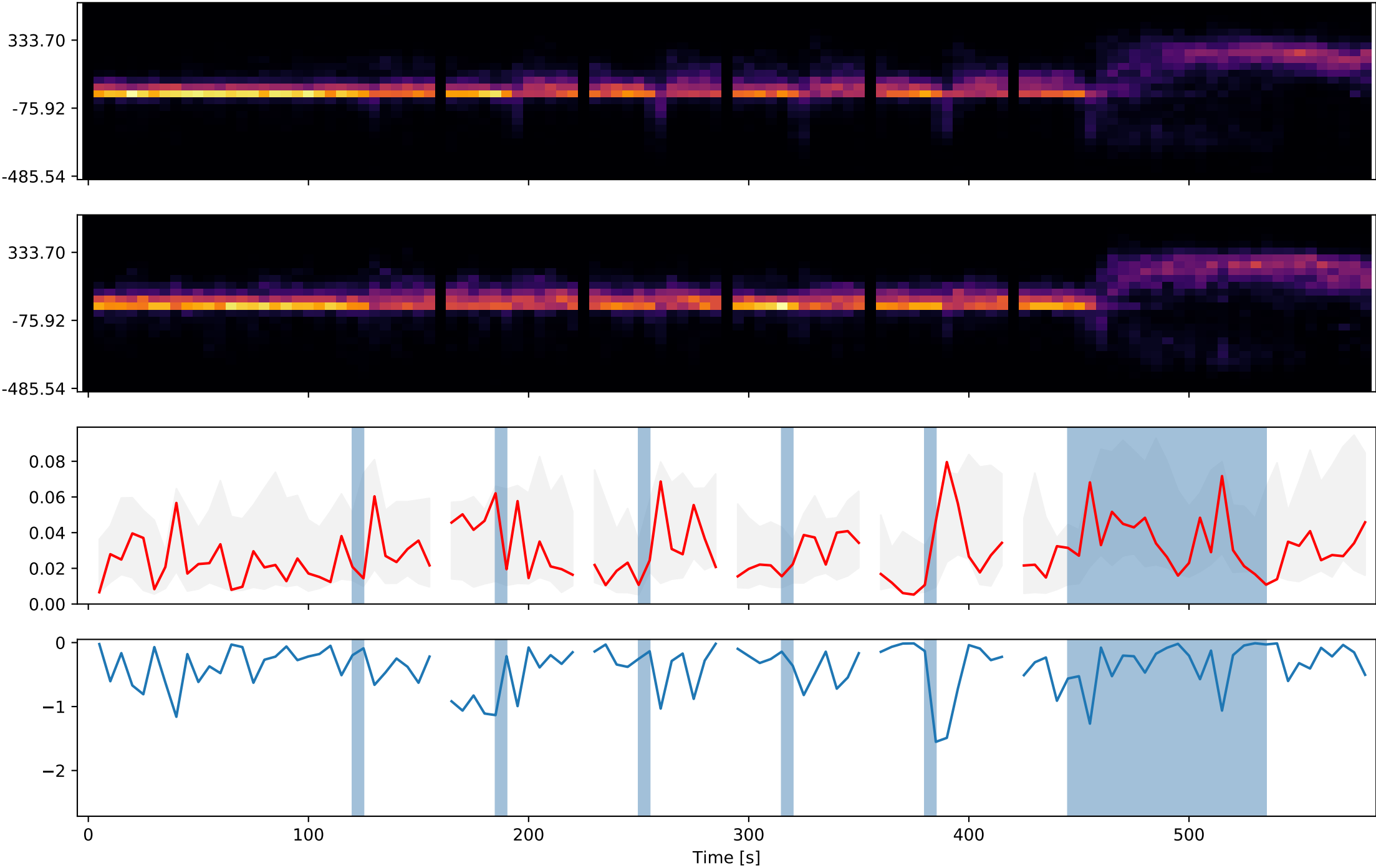
angular\_velocity - pval: 0.8855291576673866



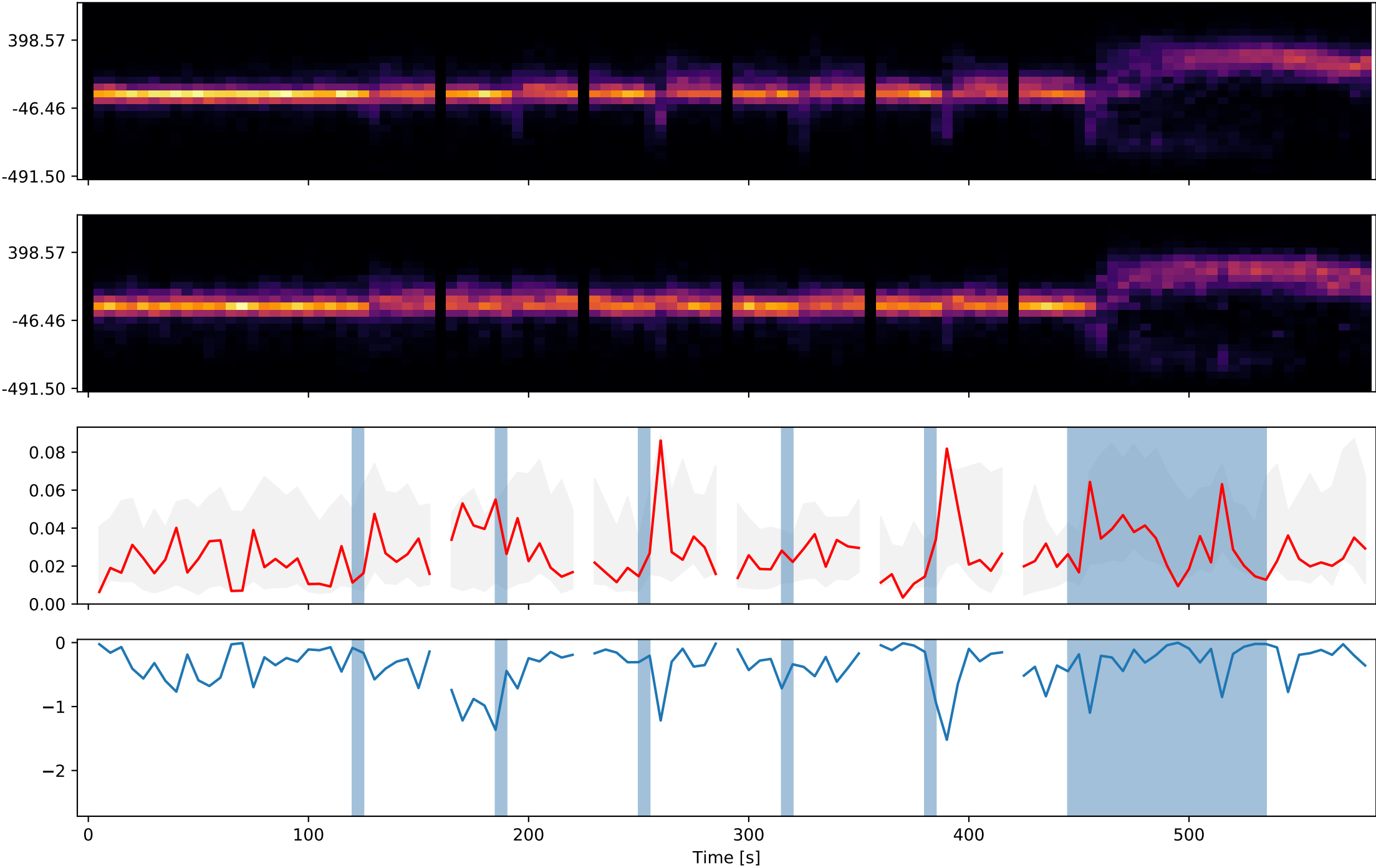
speed\_midbody - pval: 0.8855291576673866



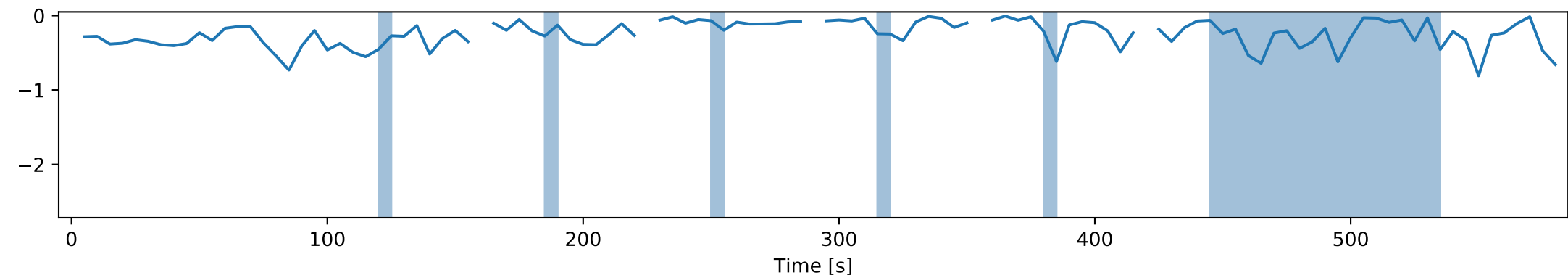
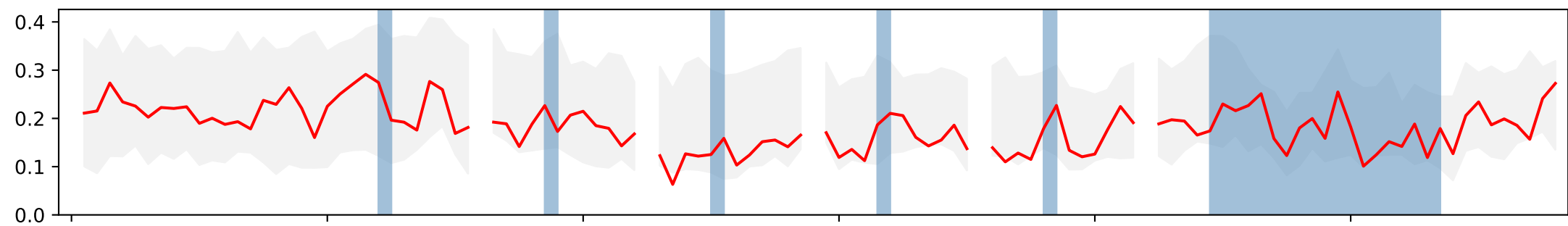
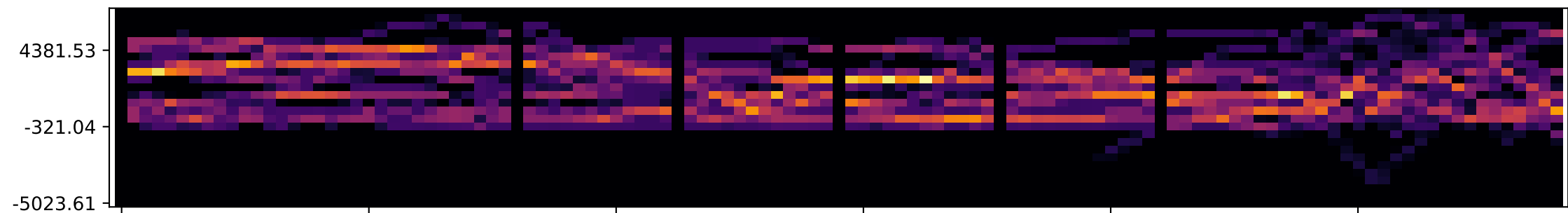
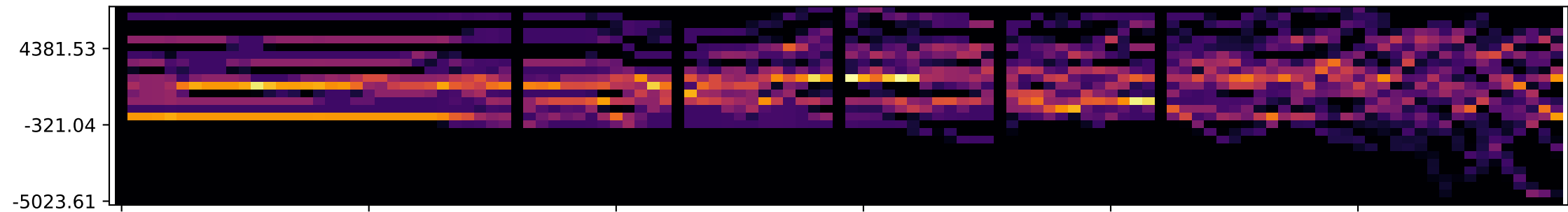
speed\_tail\_base - pval: 0.8920086393088553



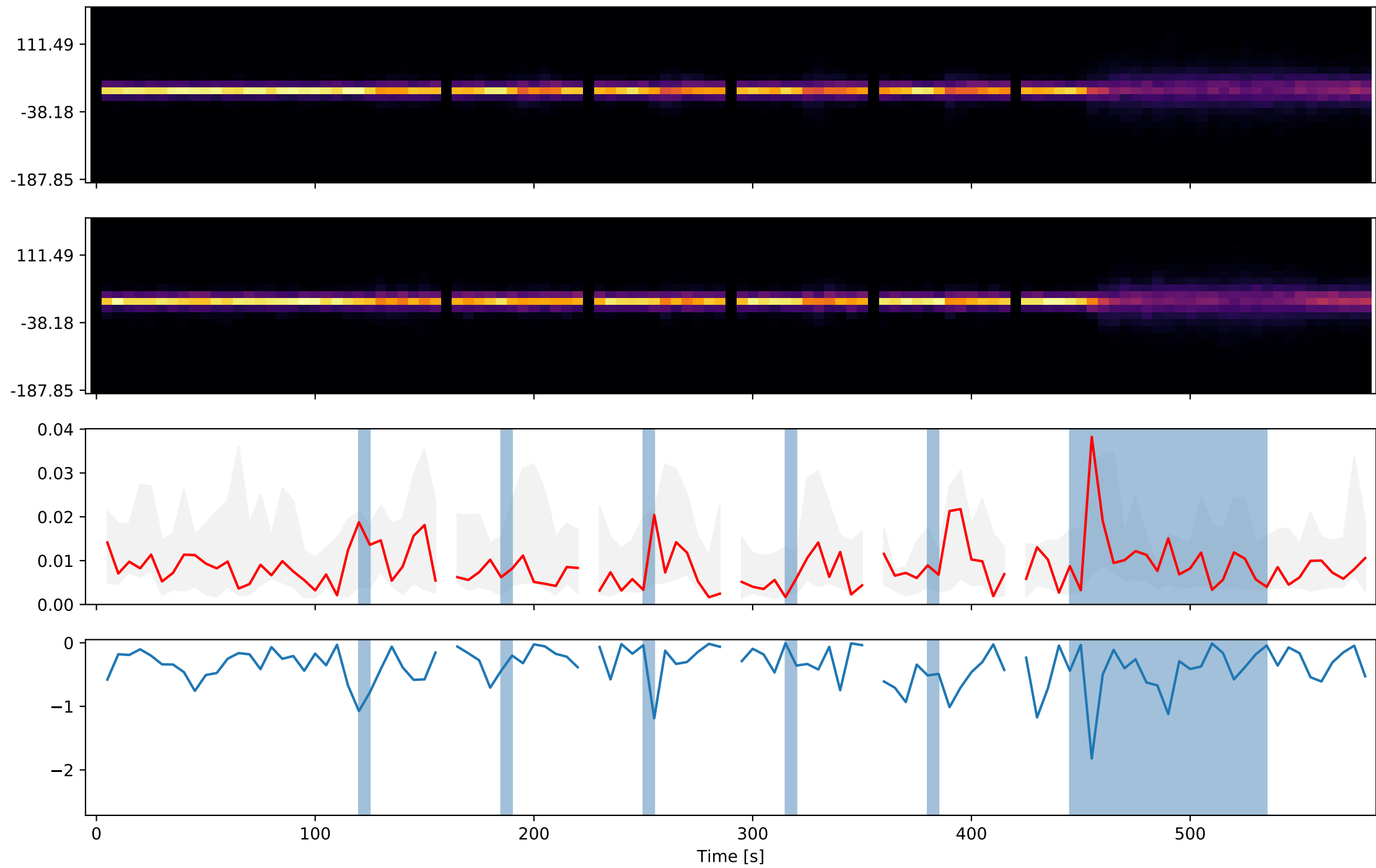
speed\_head\_tip - pval: 0.8984881209503239



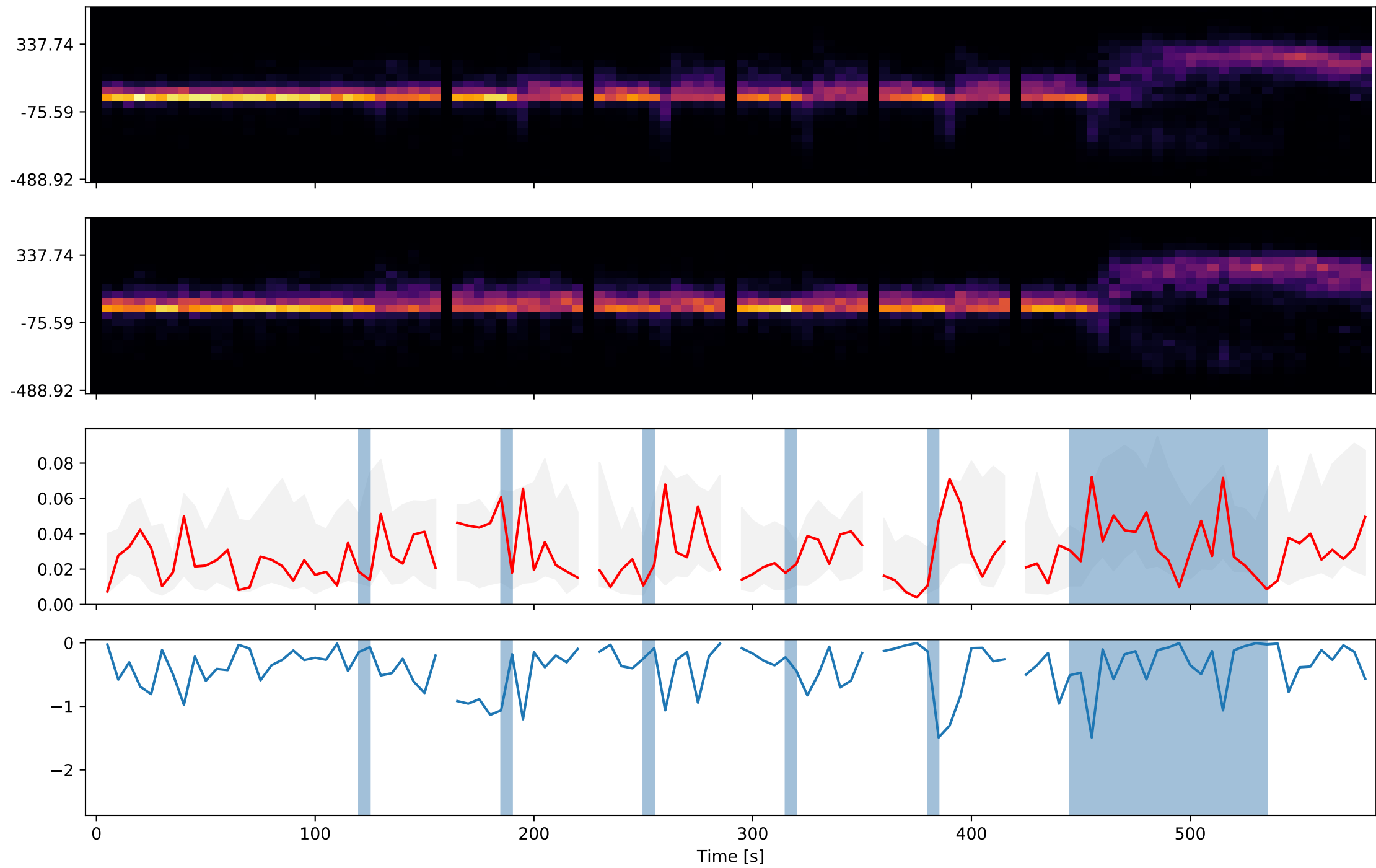
dist\_from\_food\_edge - pval: 0.9006479481641468



relative\_to\_body\_radial\_velocity\_neck - pval: 0.9071274298056156

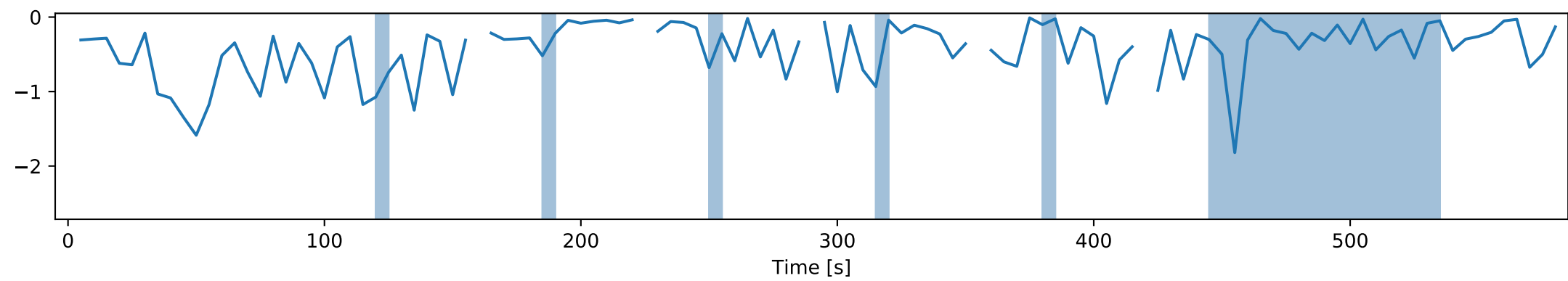
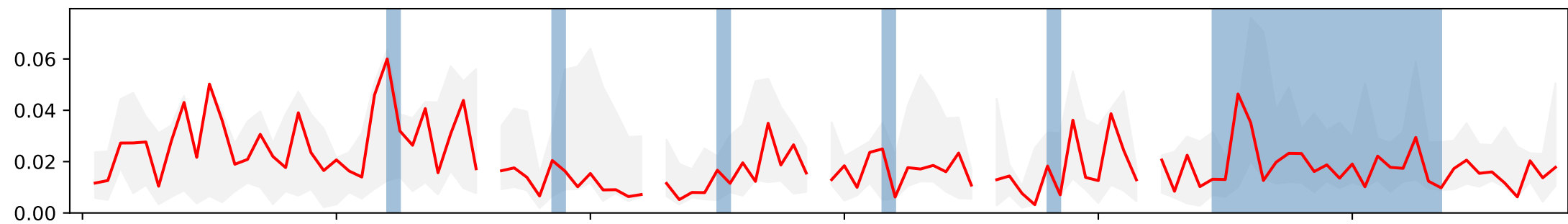
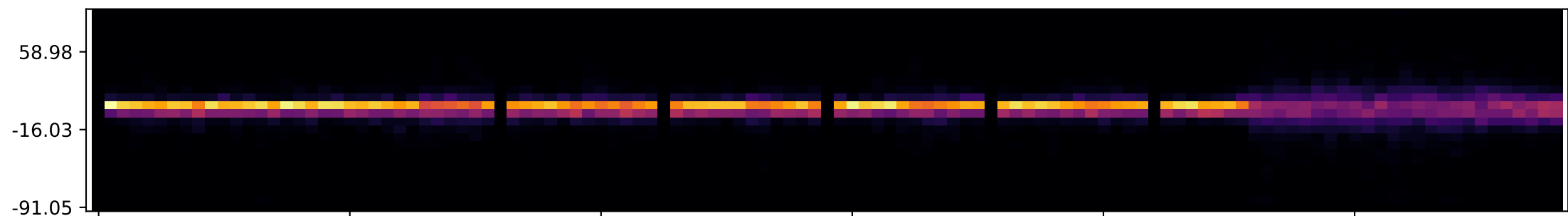
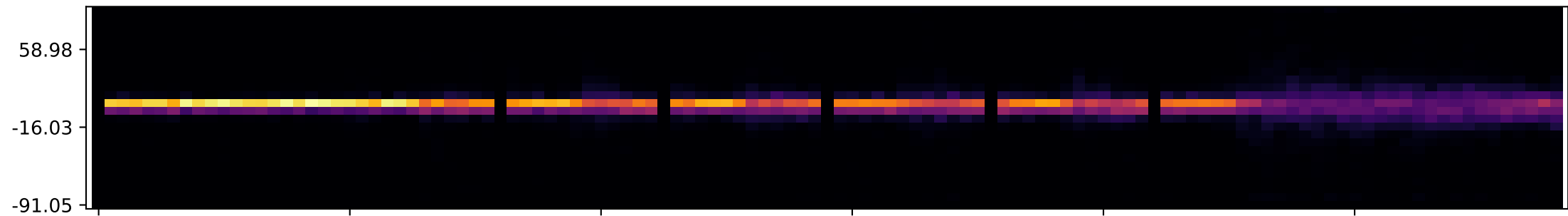


speed\_tail\_tip - pval: 0.9330453563714903





d\_orientation\_food\_edge - pval: 0.9395248380129589



eigen\_projection\_5 - pval: 1.0

