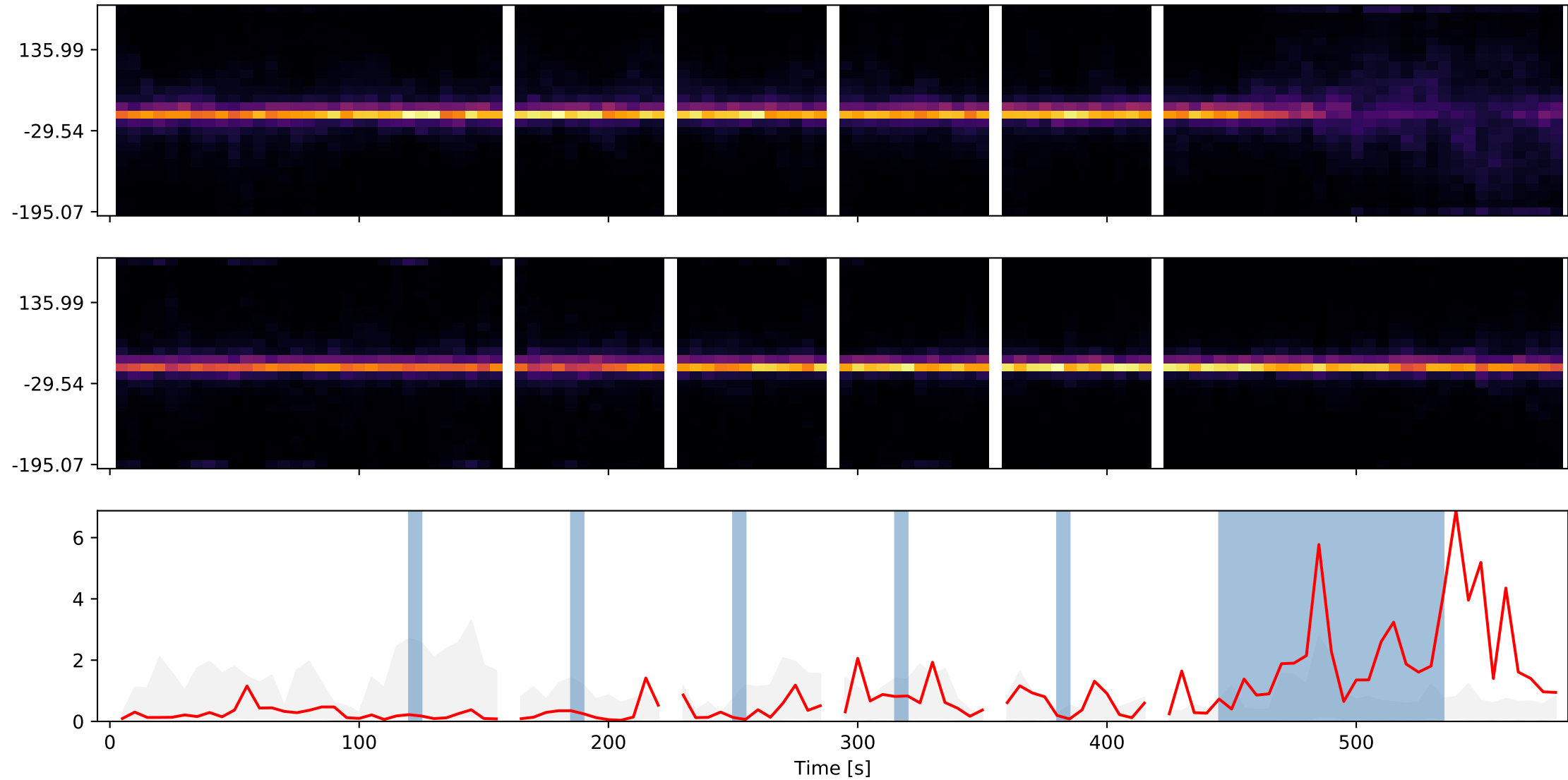
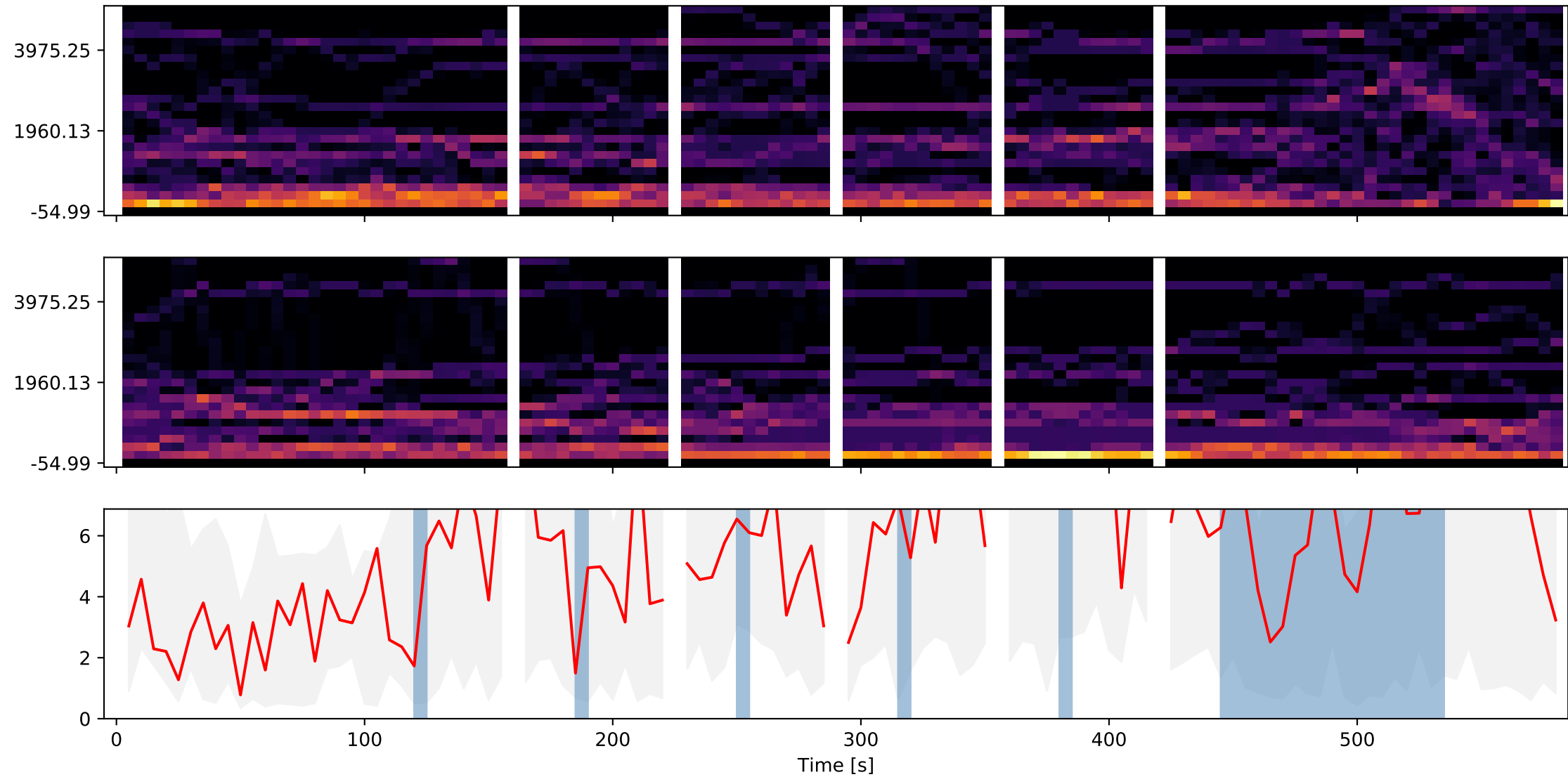


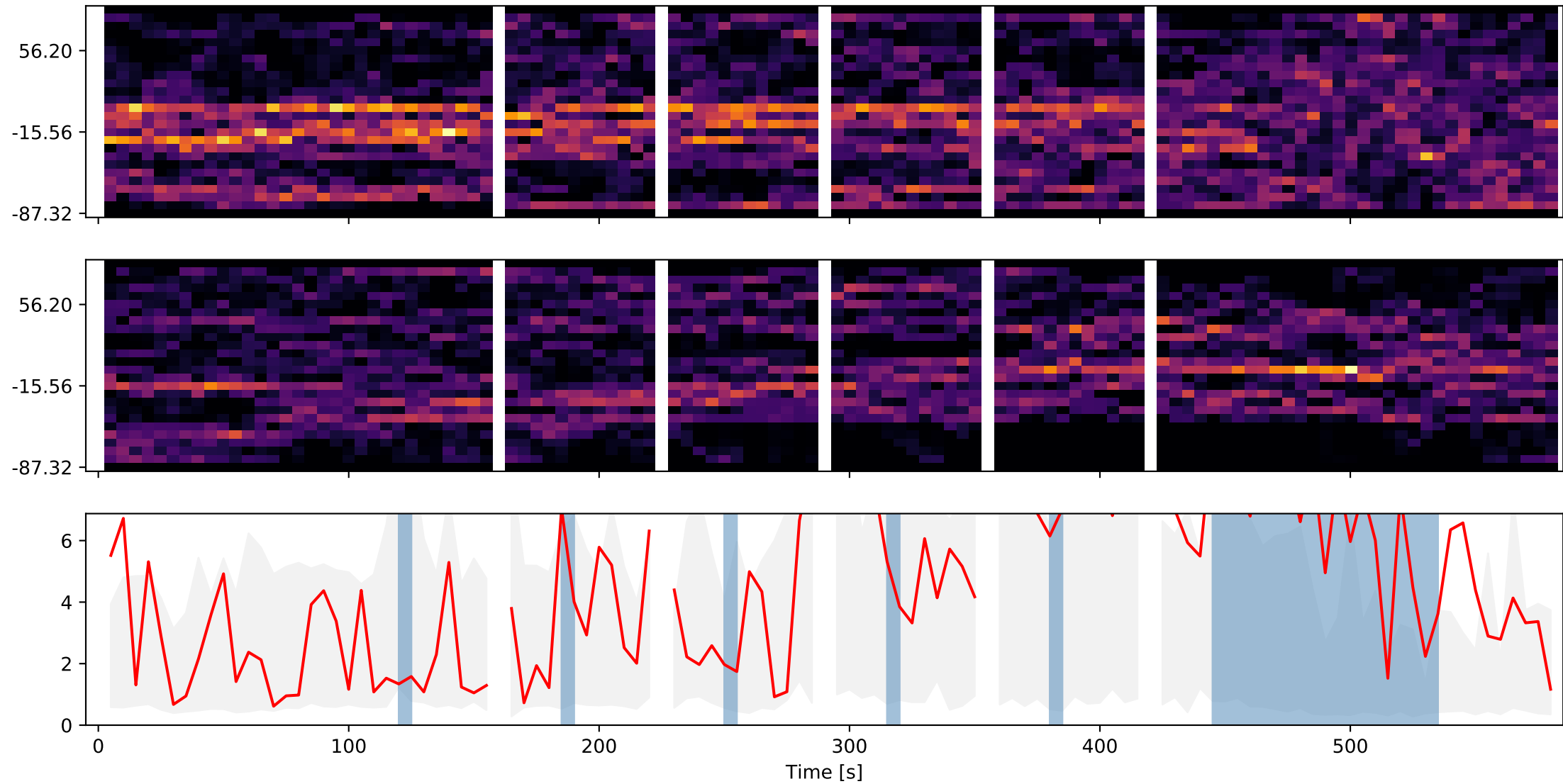
d_dist_from_food_edge



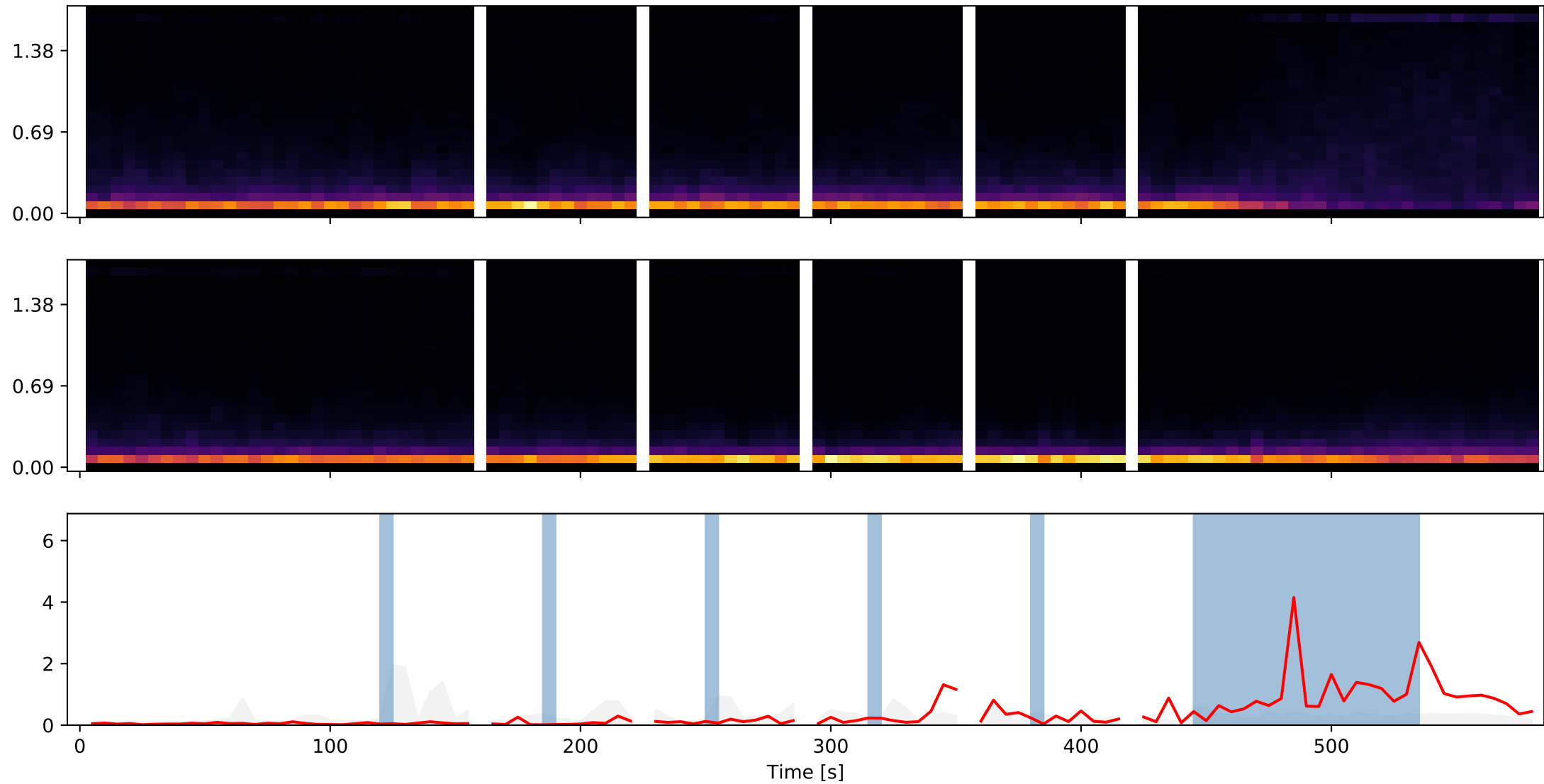
dist_from_food_edge



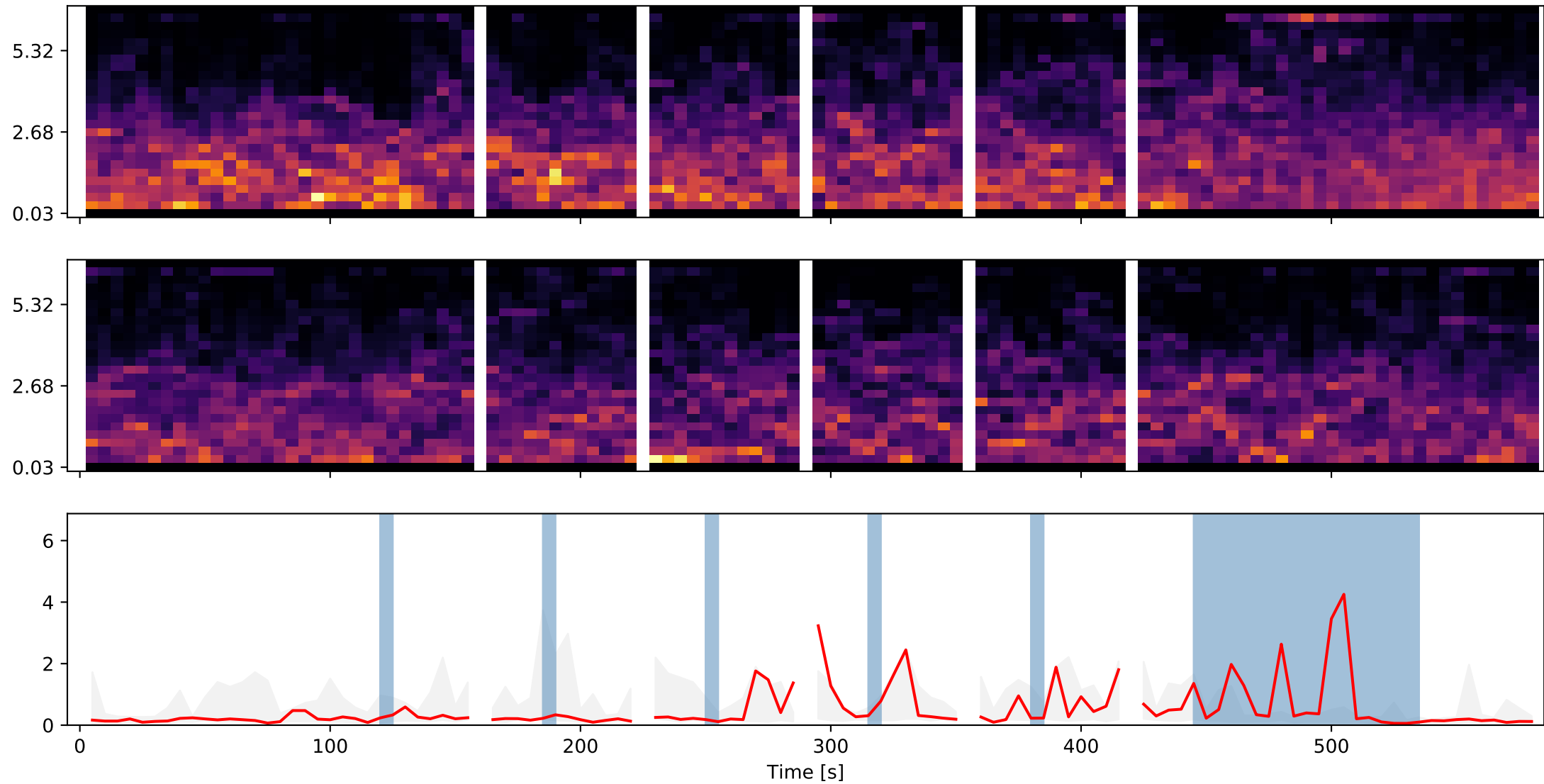
orientation_food_edge



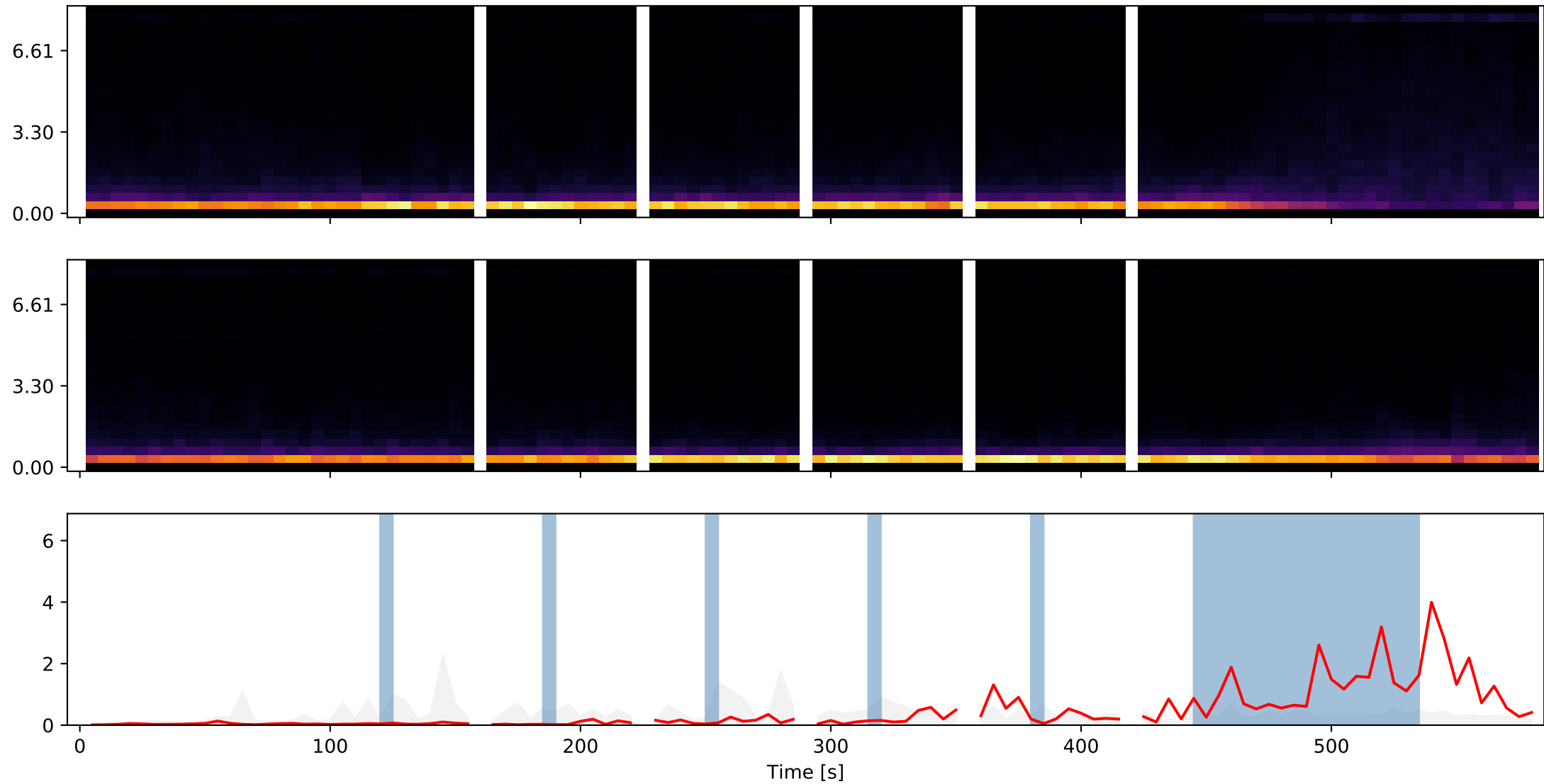
relative_to_hips_angular_velocity_tail_tip



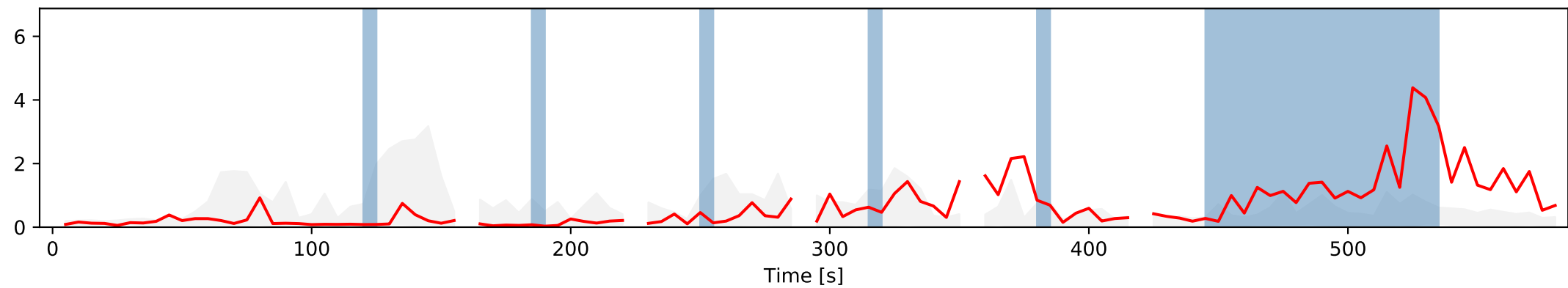
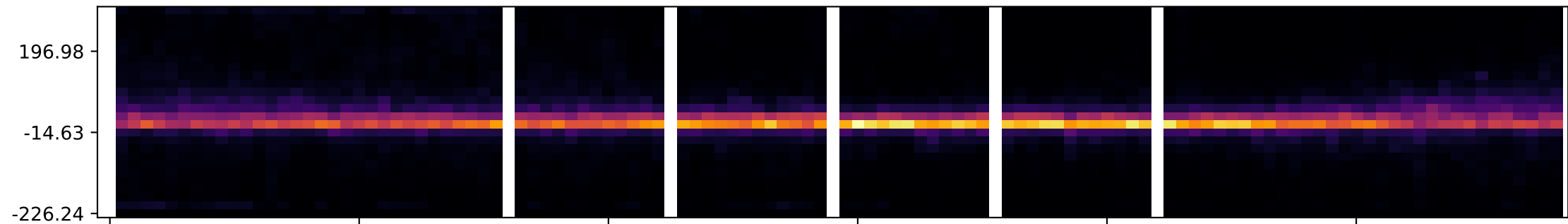
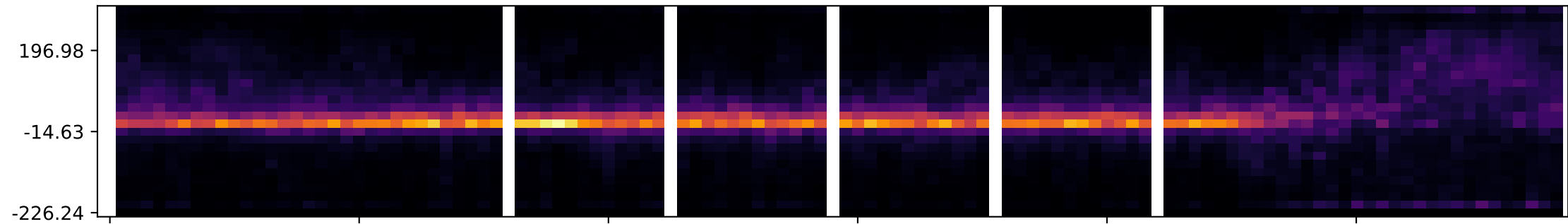
eigen_projection_1



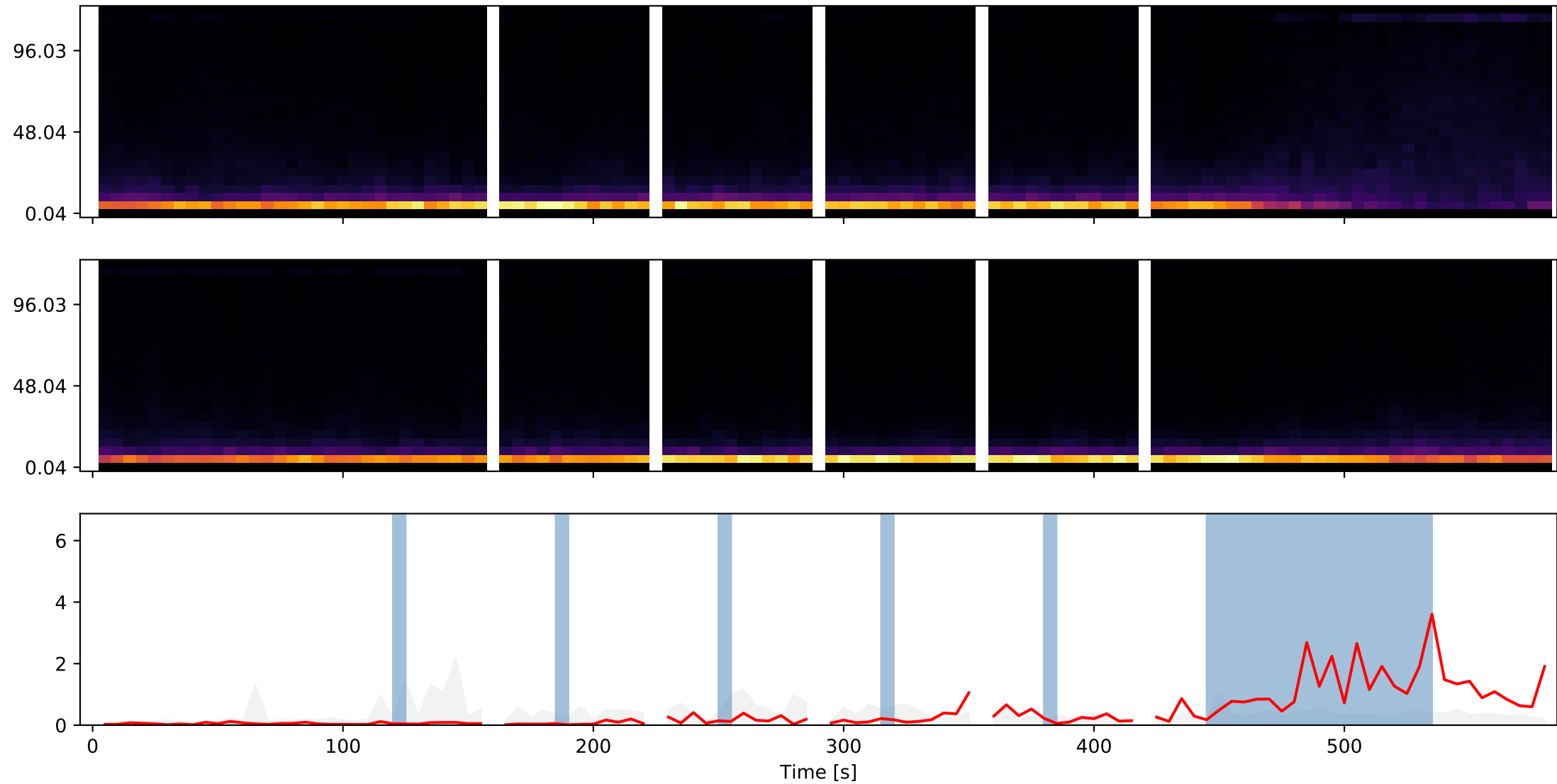
d_eigen_projection_2



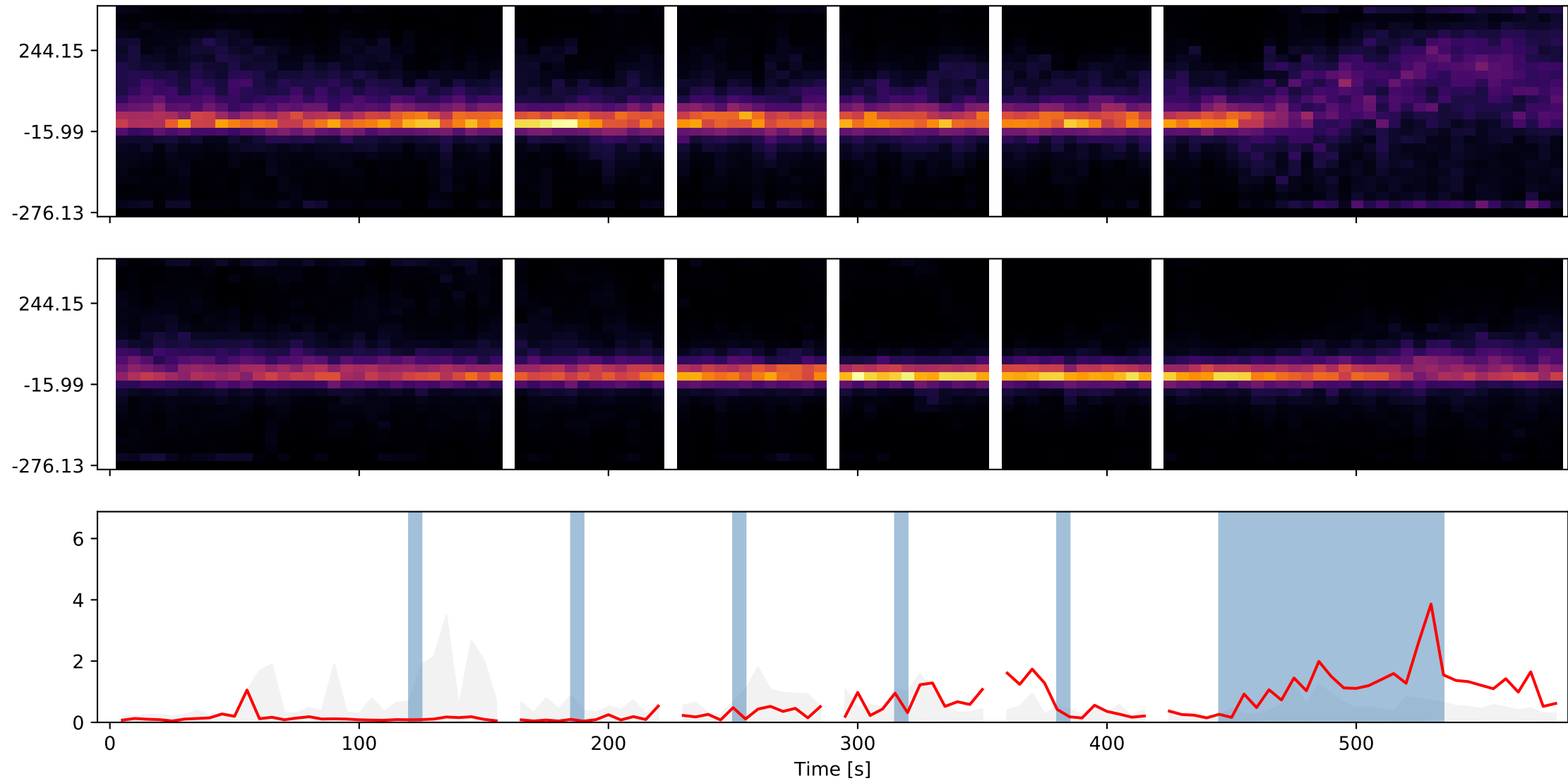
speed



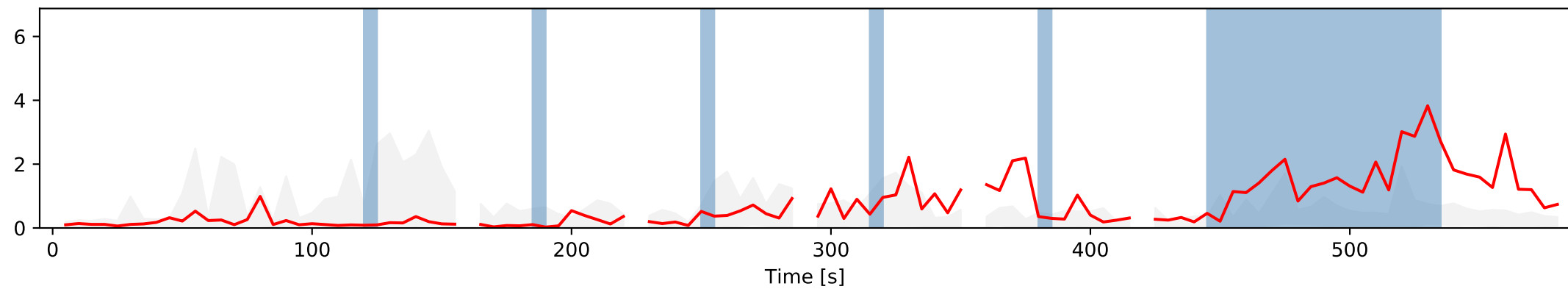
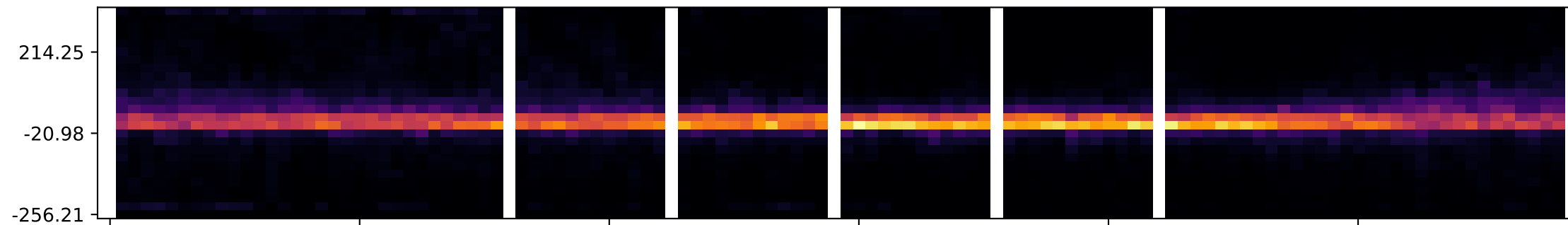
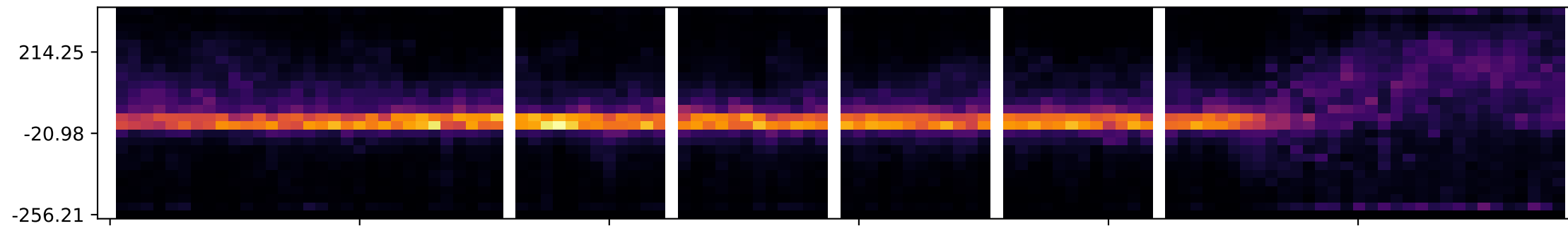
relative_to_body_speed_midbody



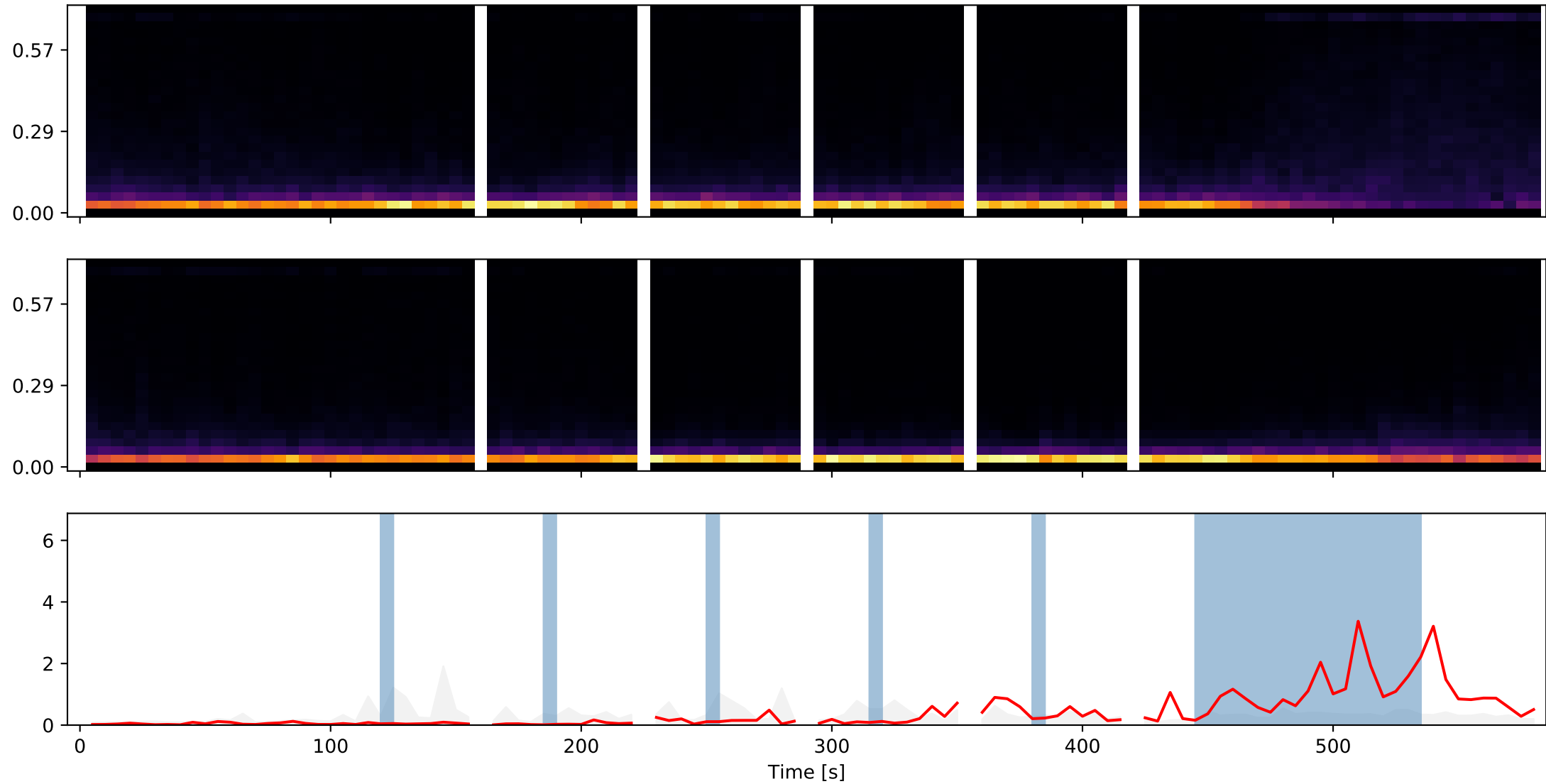
speed_head_base



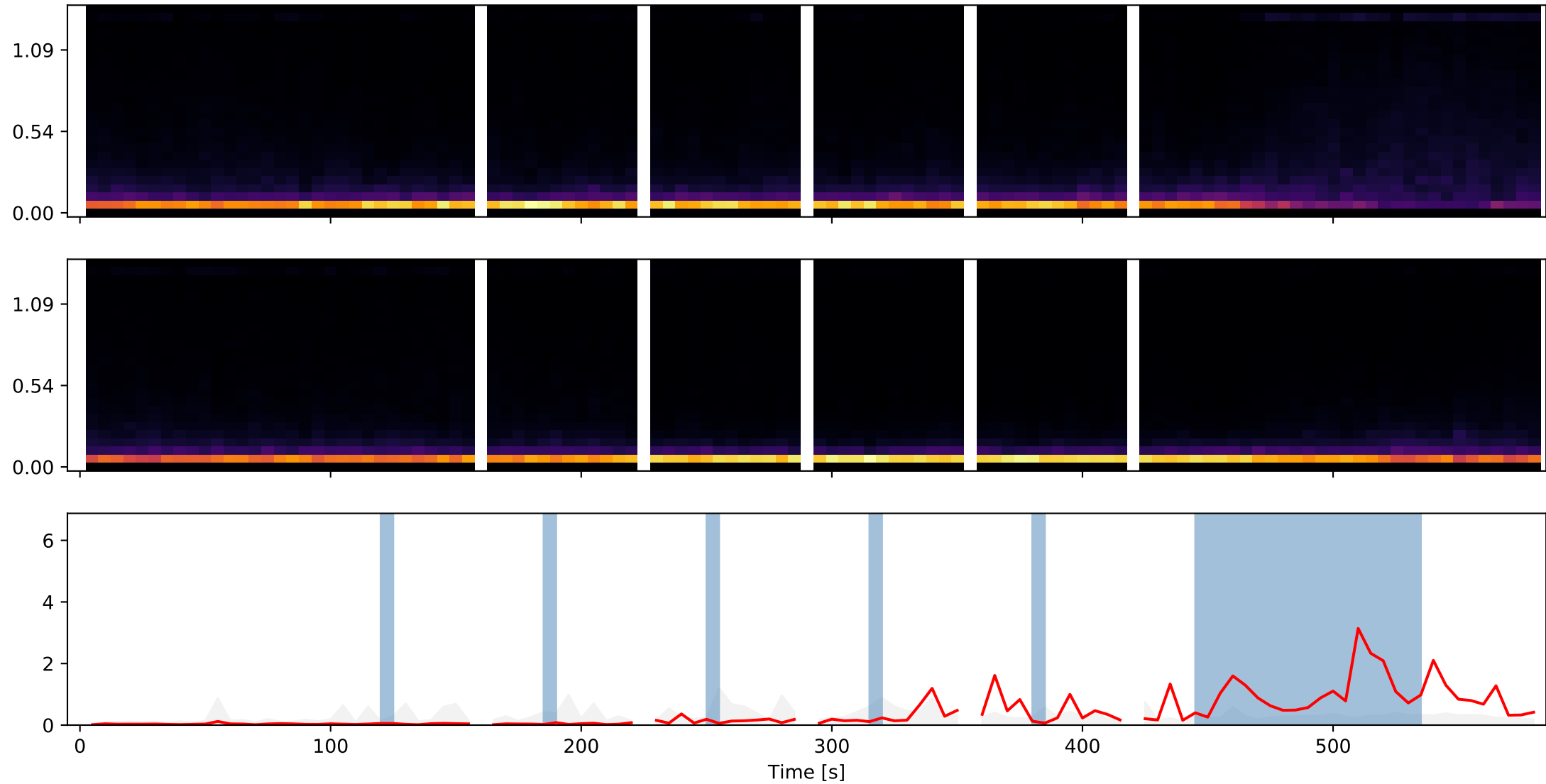
speed_hips



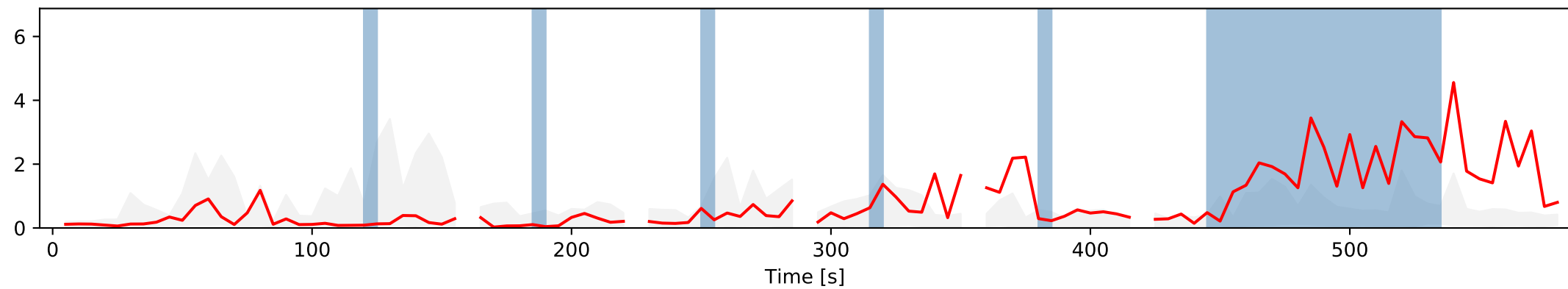
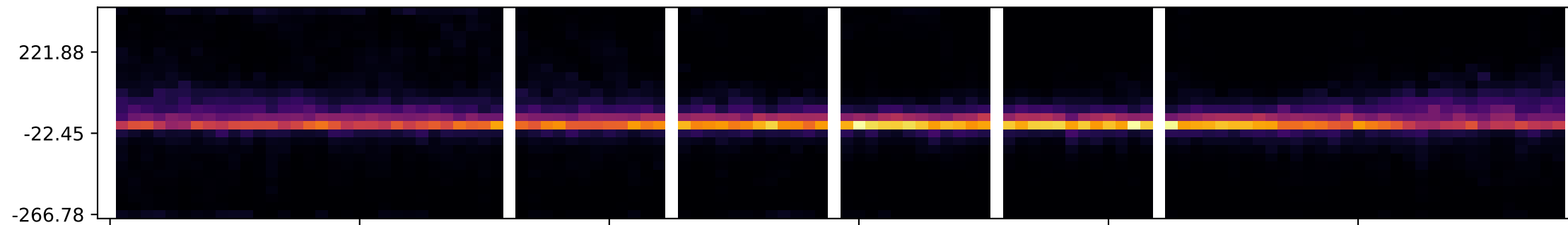
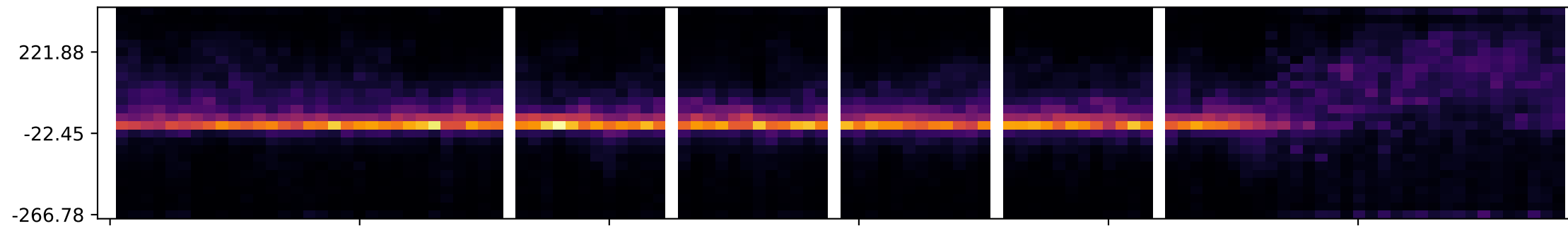
relative_to_body_angular_velocity_neck



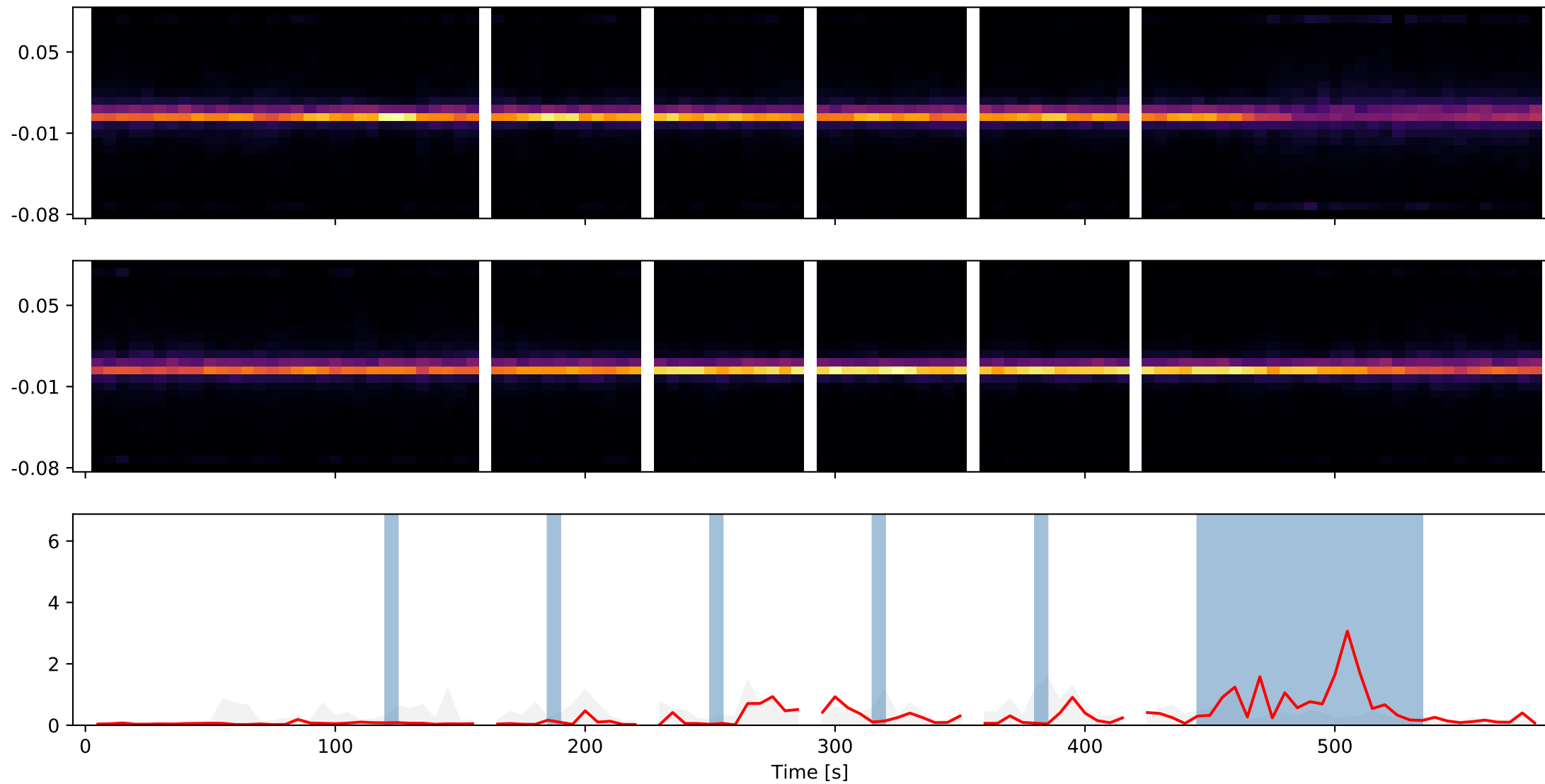
angular_velocity_midbody



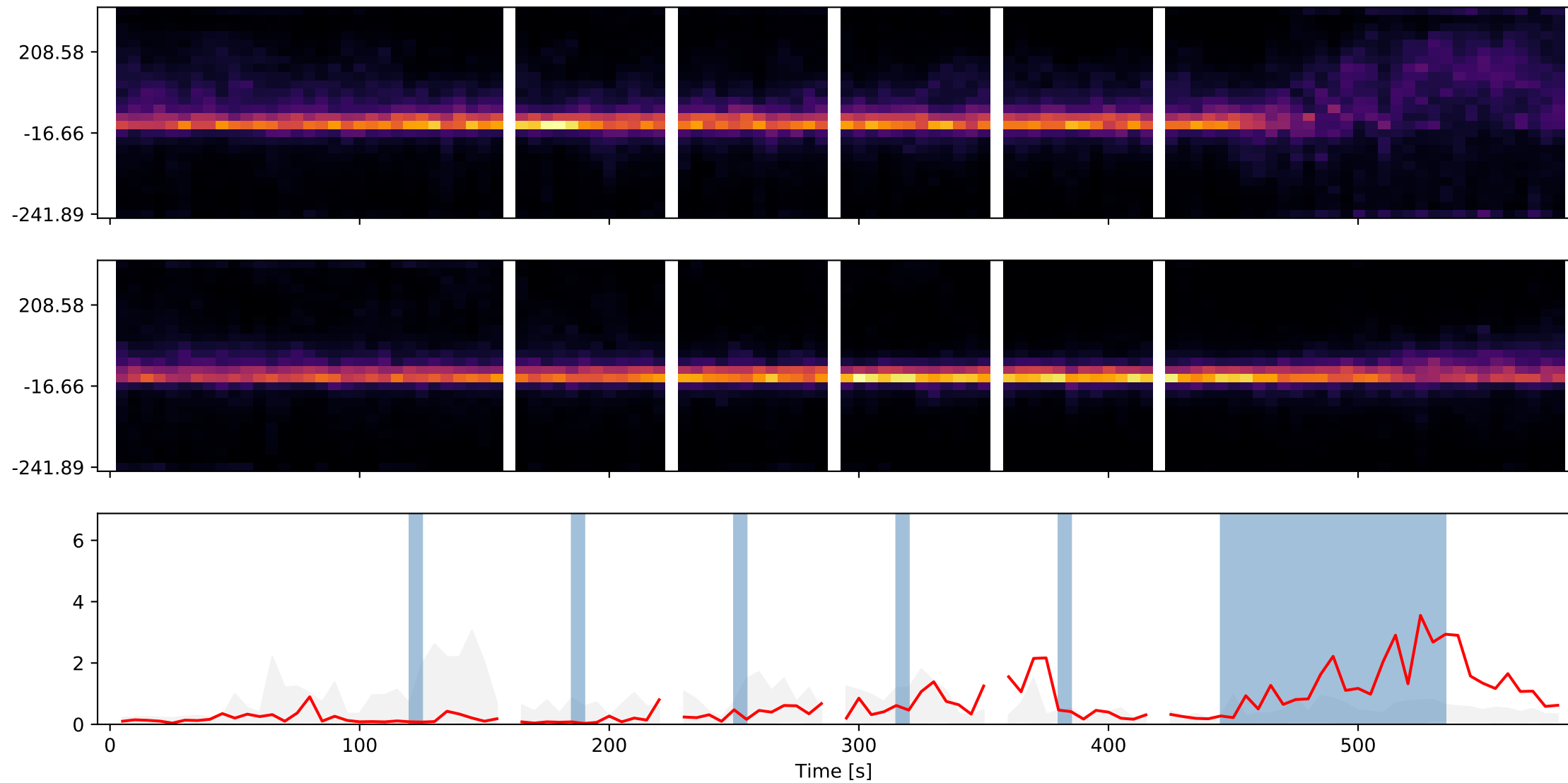
speed_tail_tip



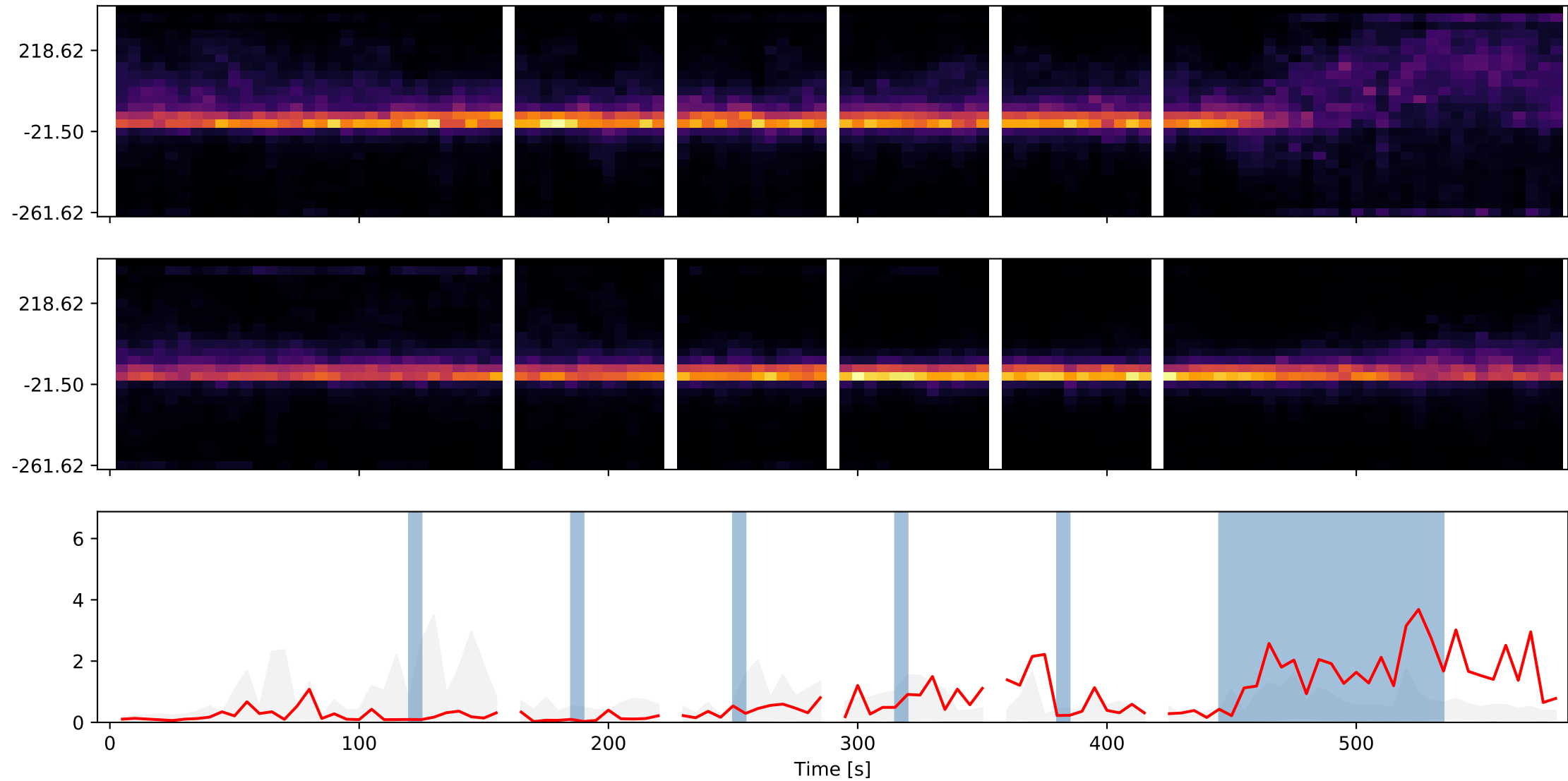
d_quirkiness



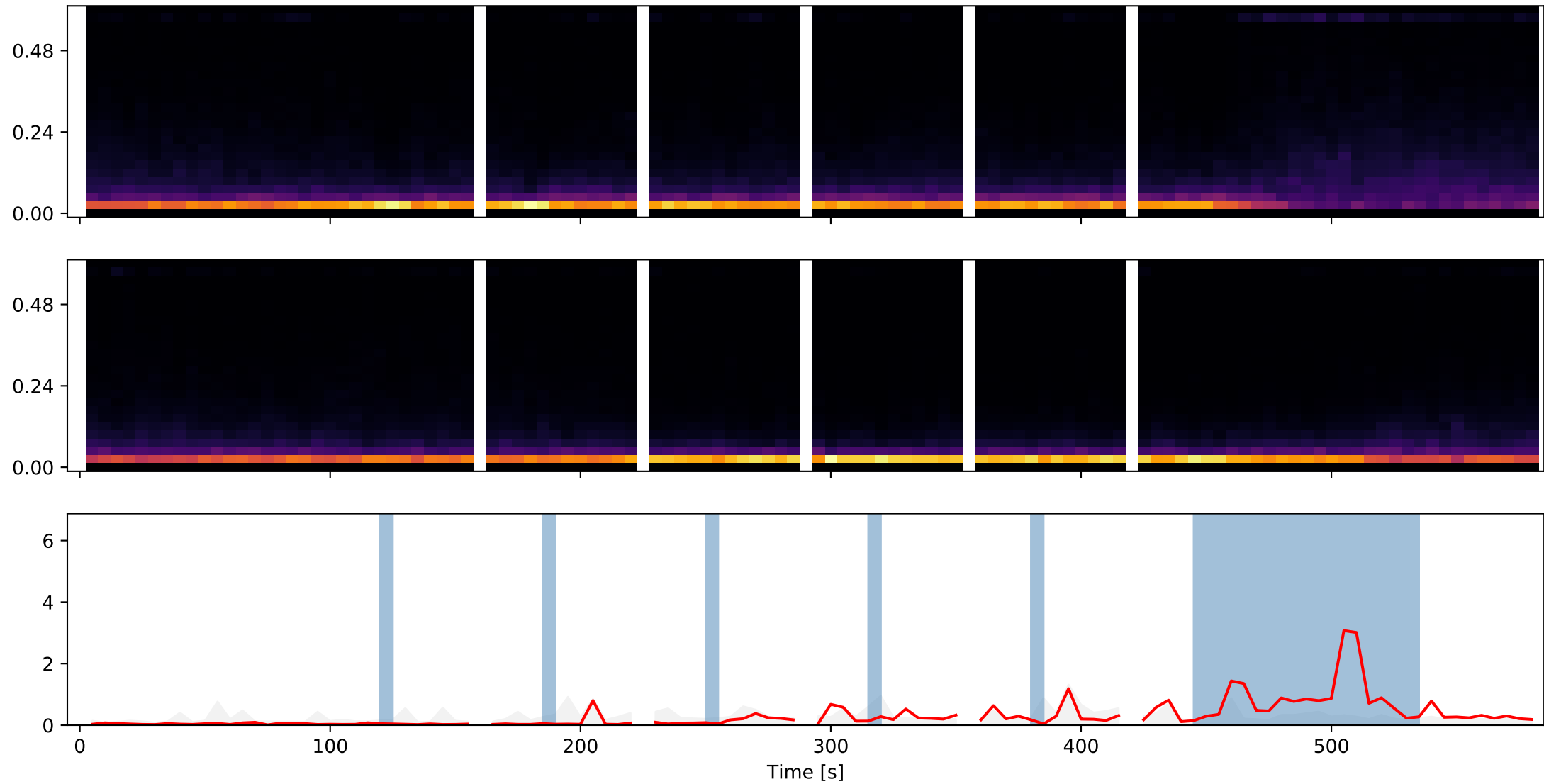
speed_midbody



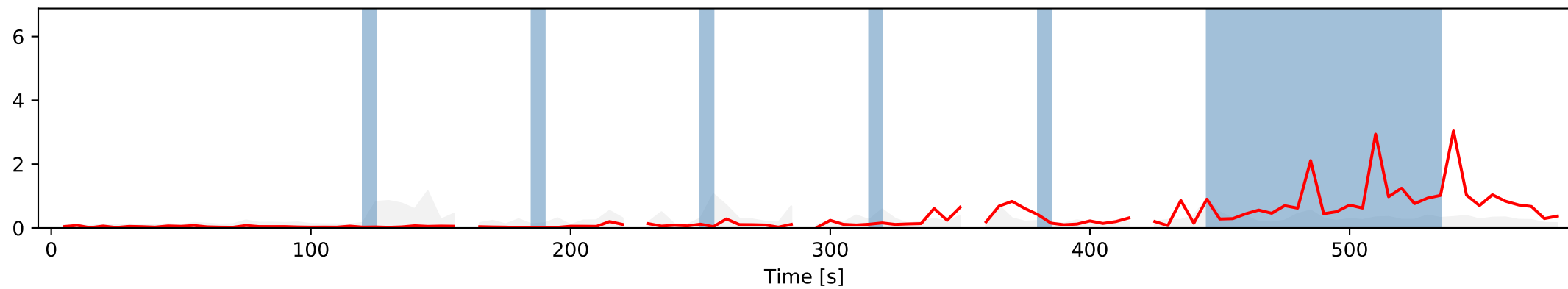
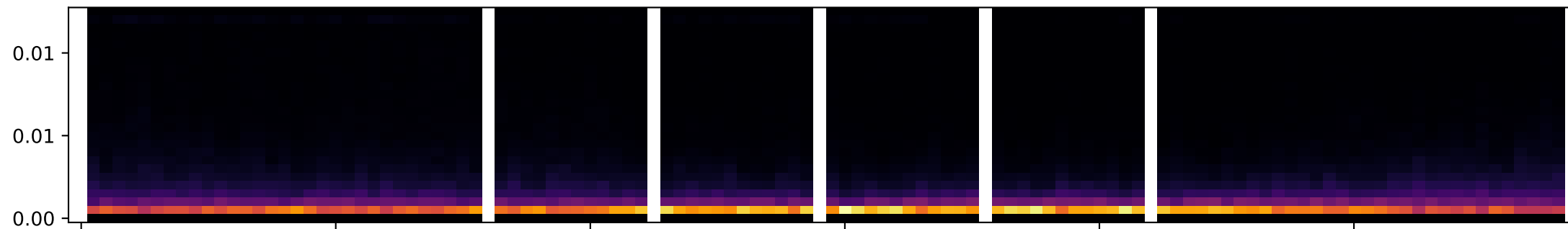
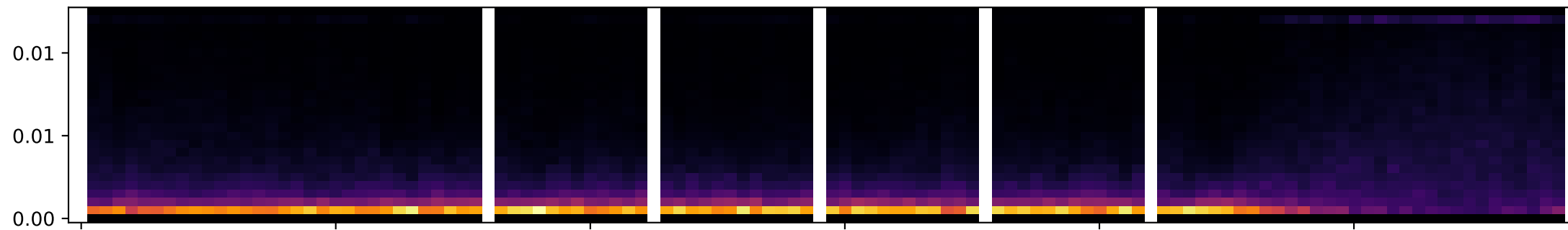
speed_tail_base



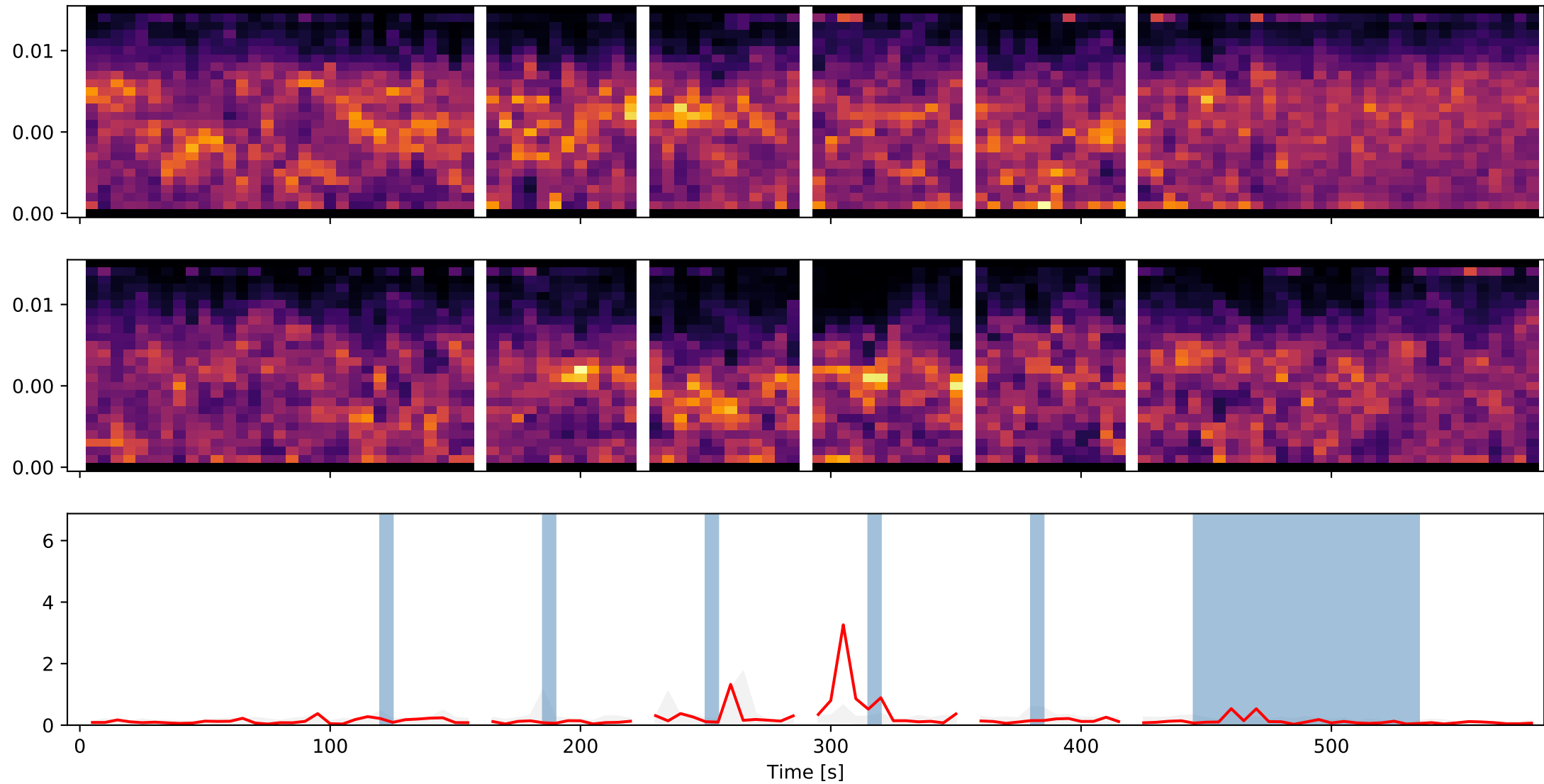
angular_velocity



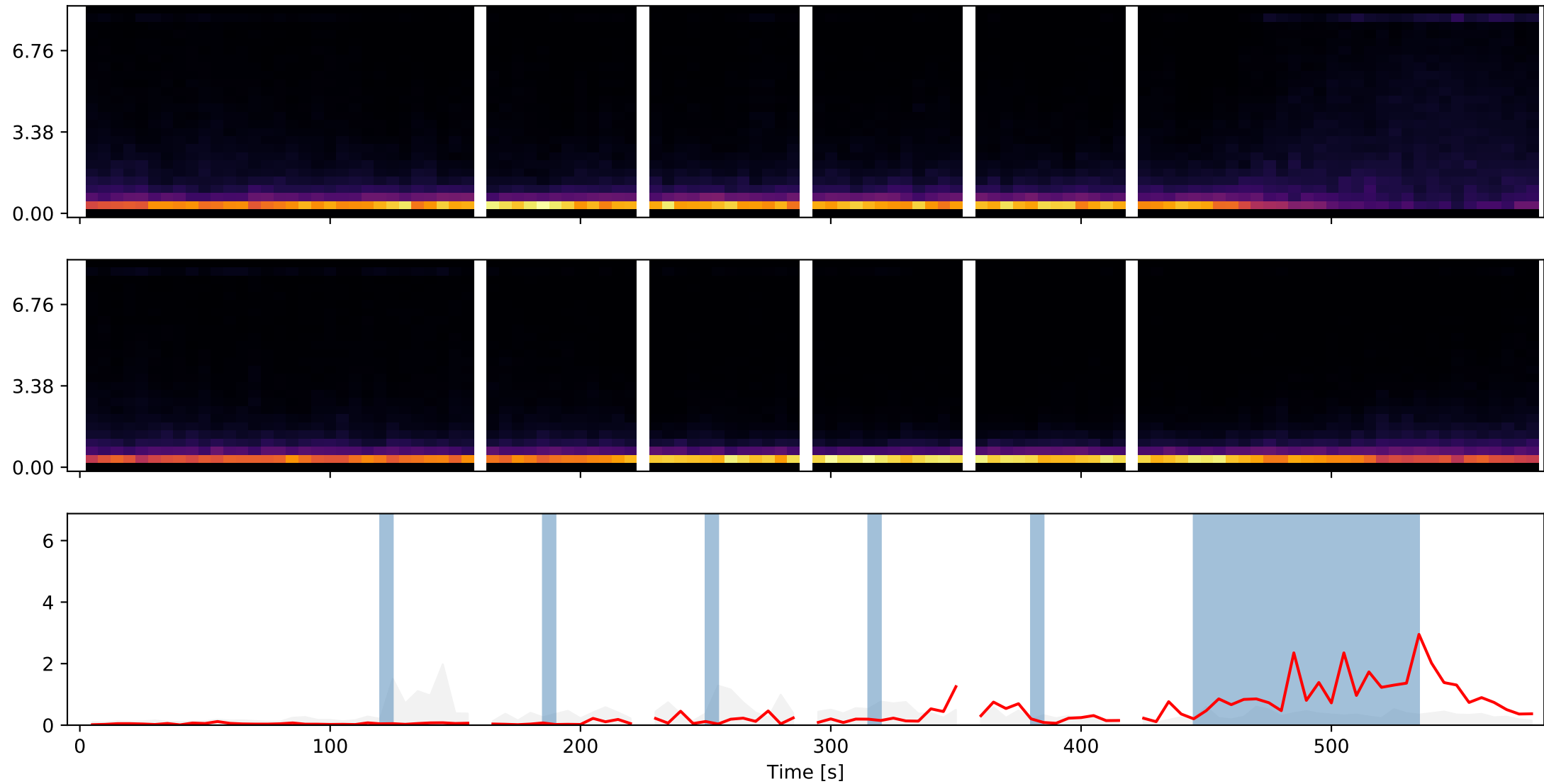
d_curvature_mean_tail



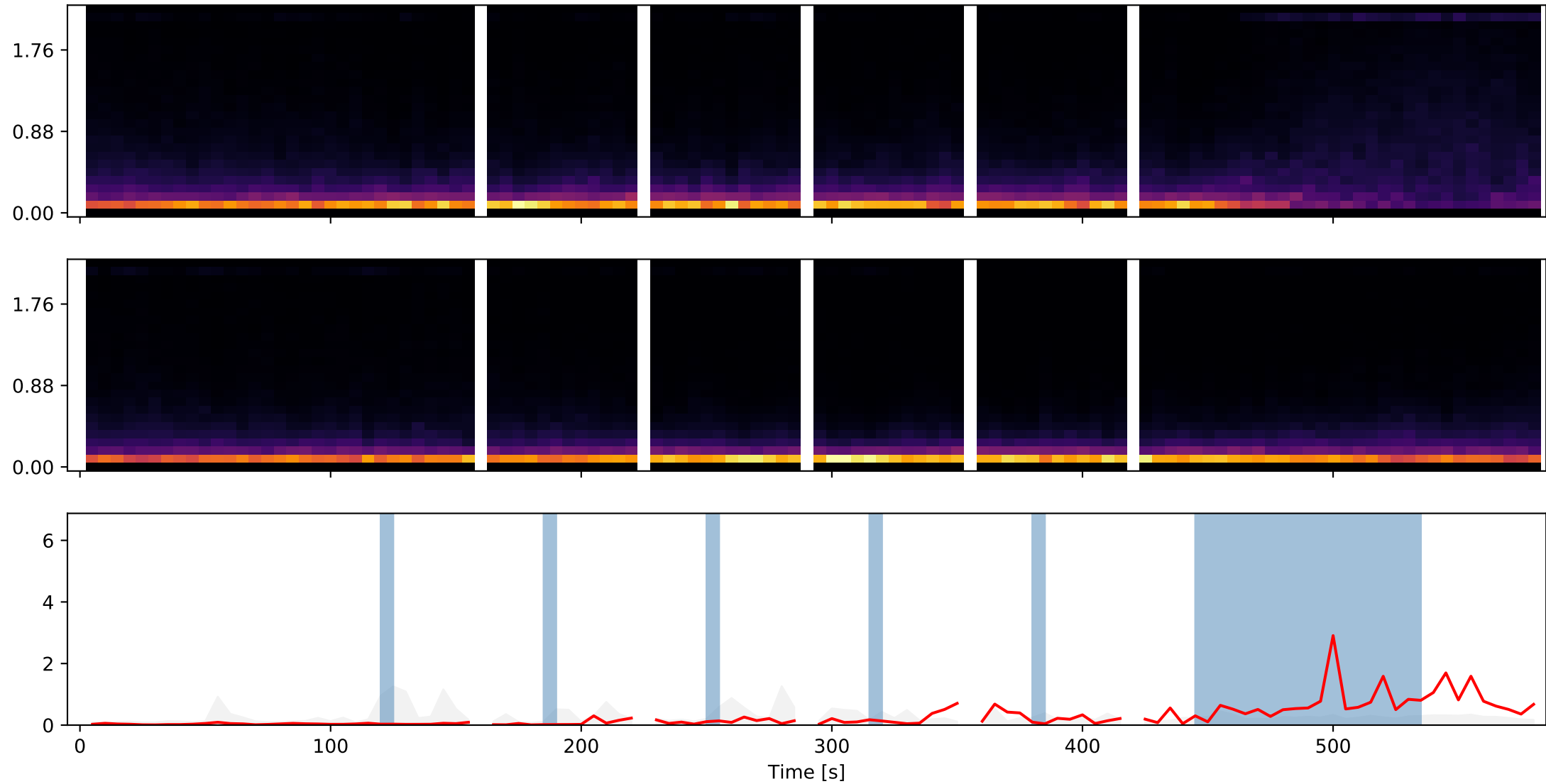
curvature_neck



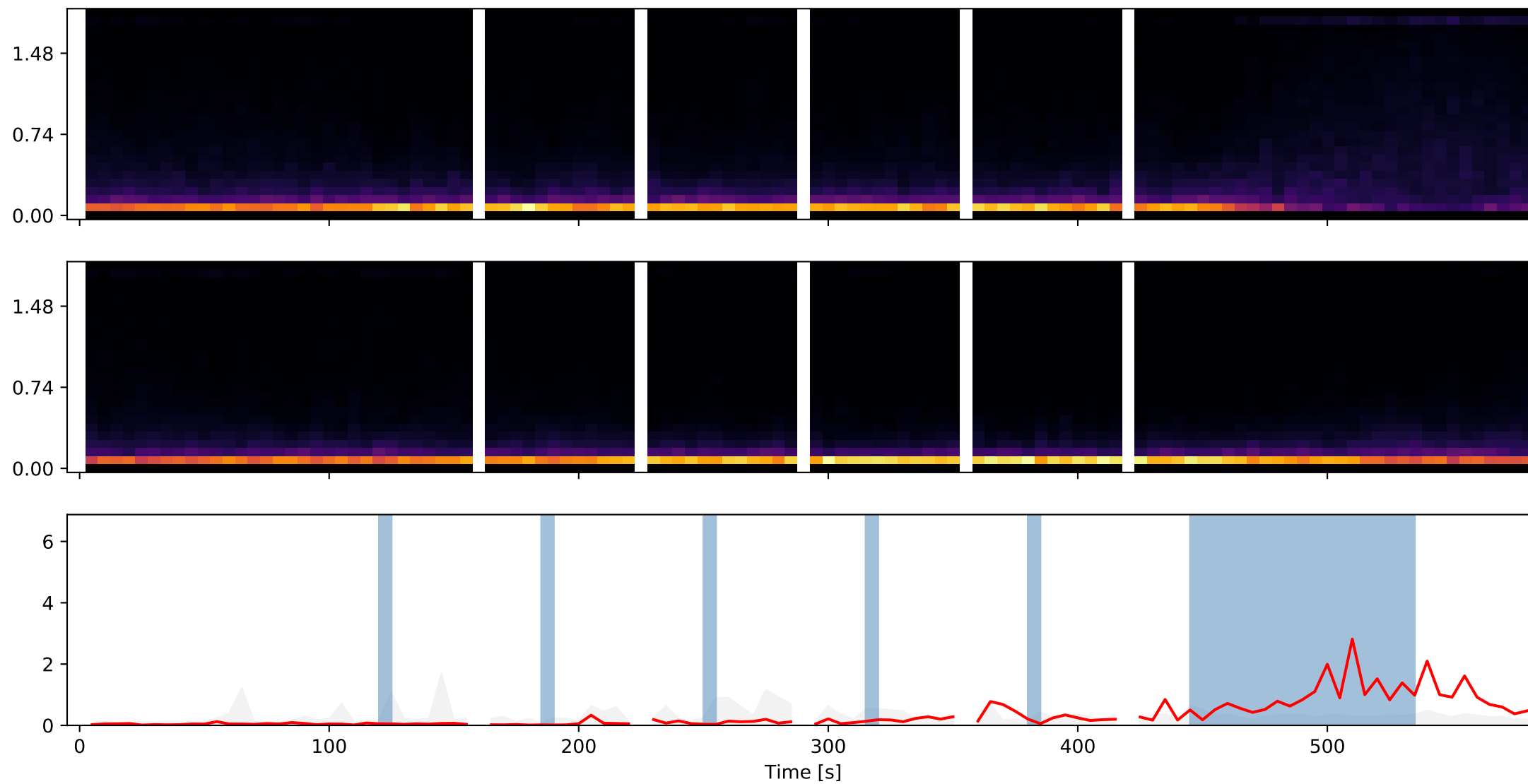
d_eigen_projection_3



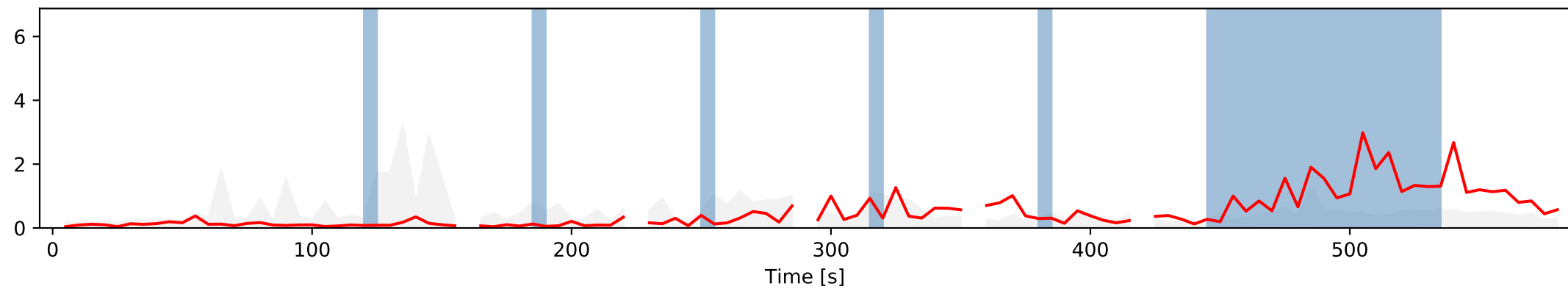
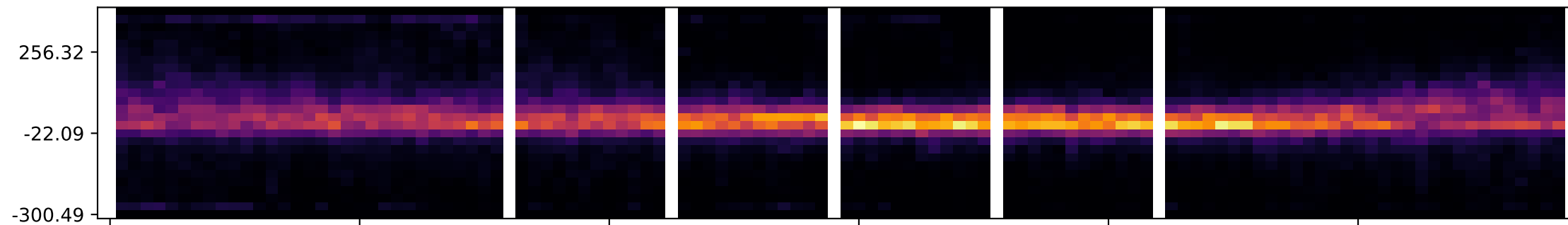
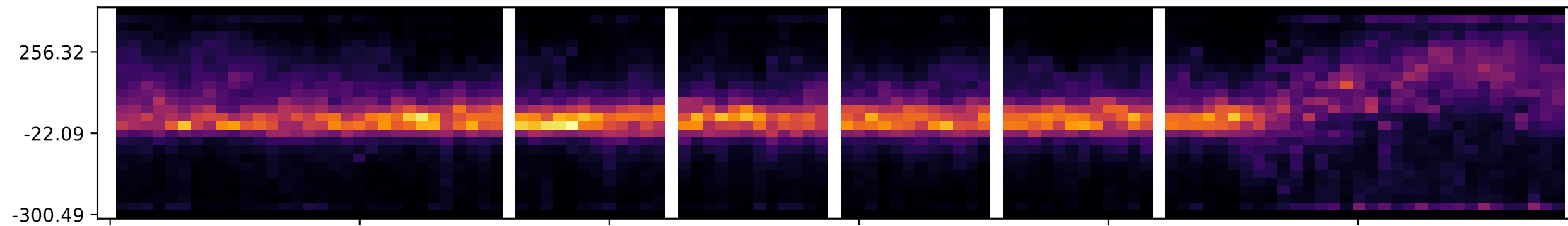
angular_velocity_tail_base



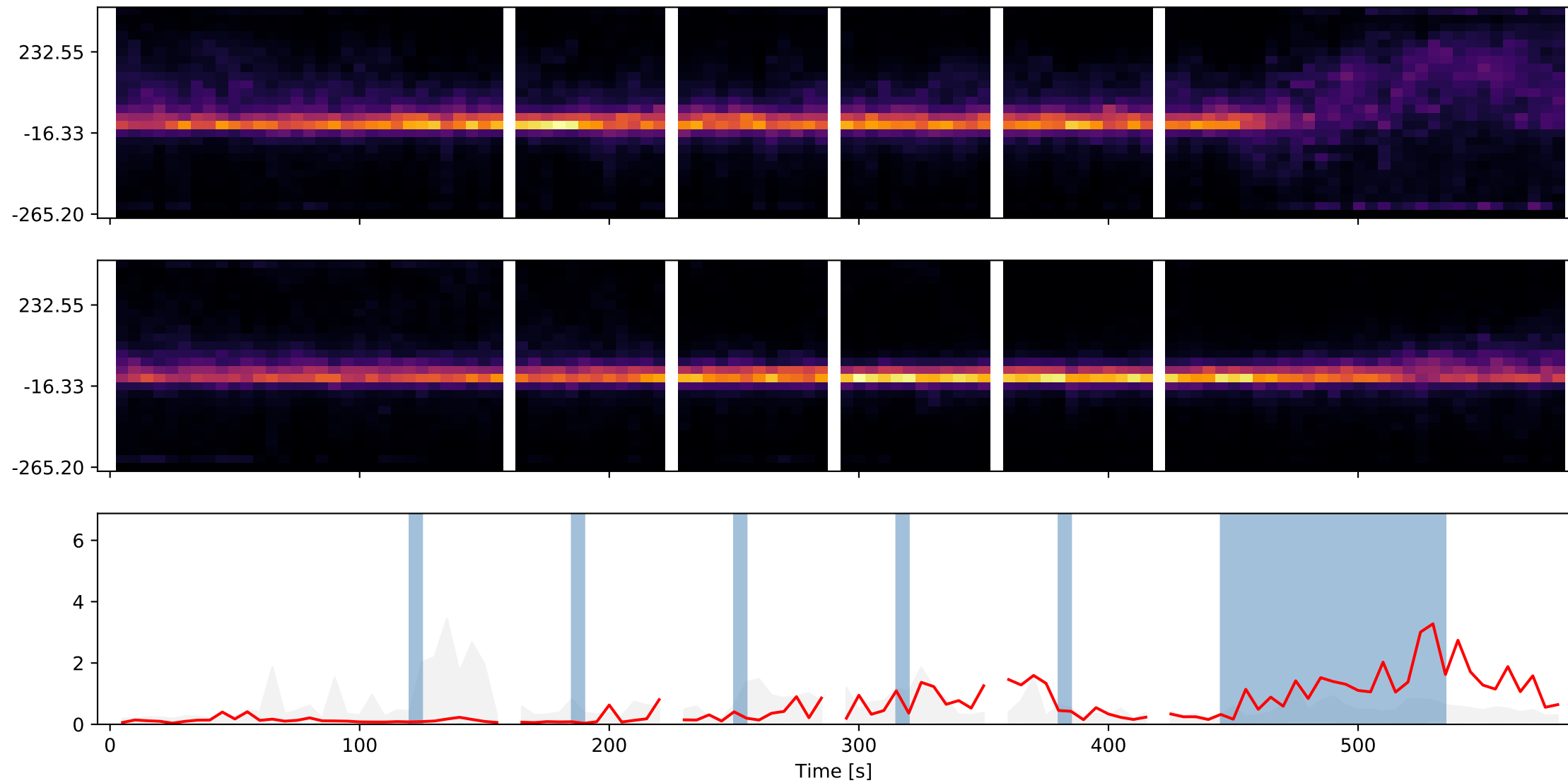
angular_velocity_hips



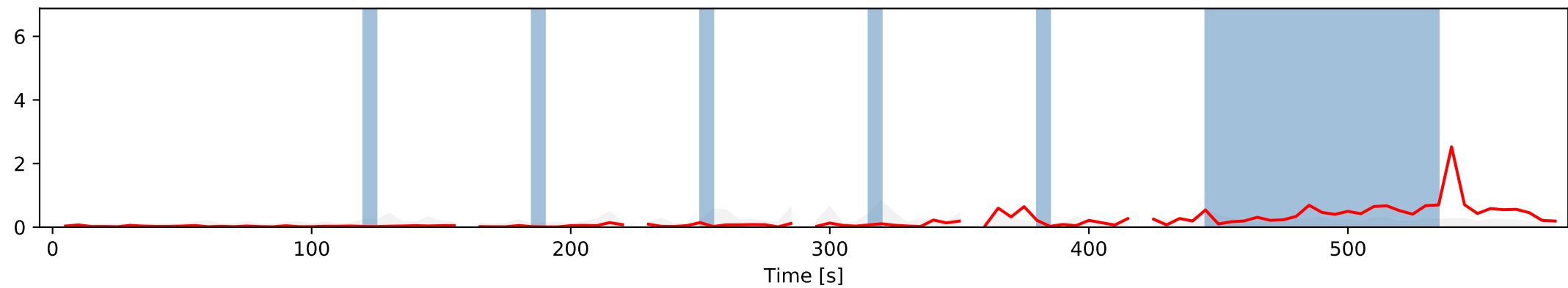
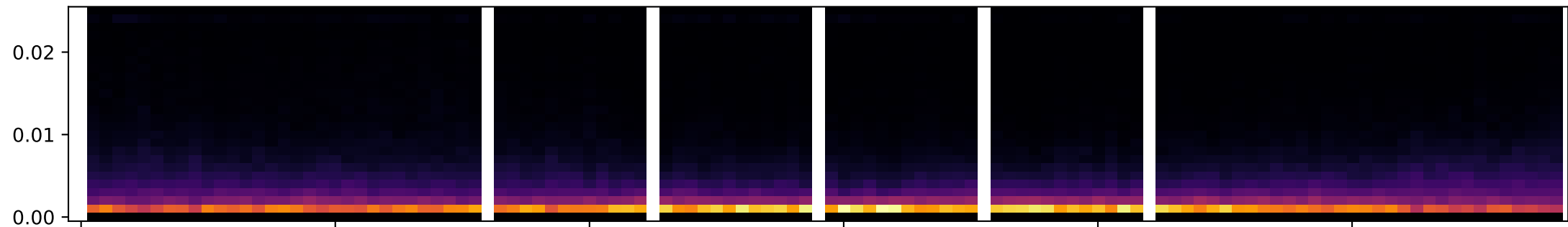
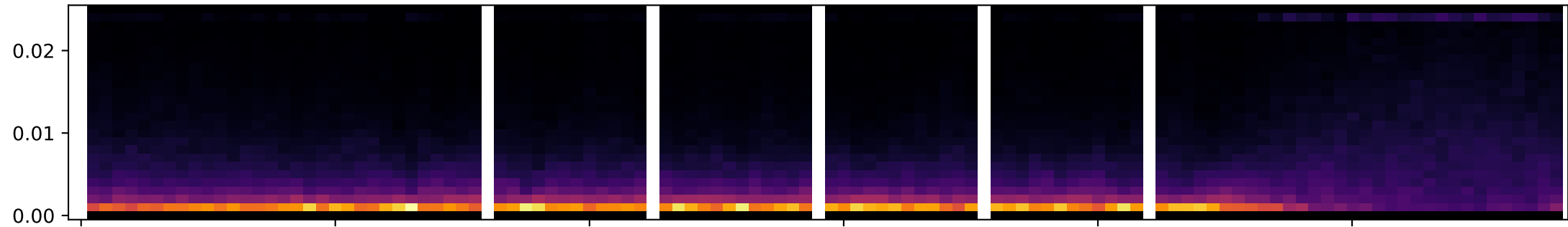
speed_head_tip



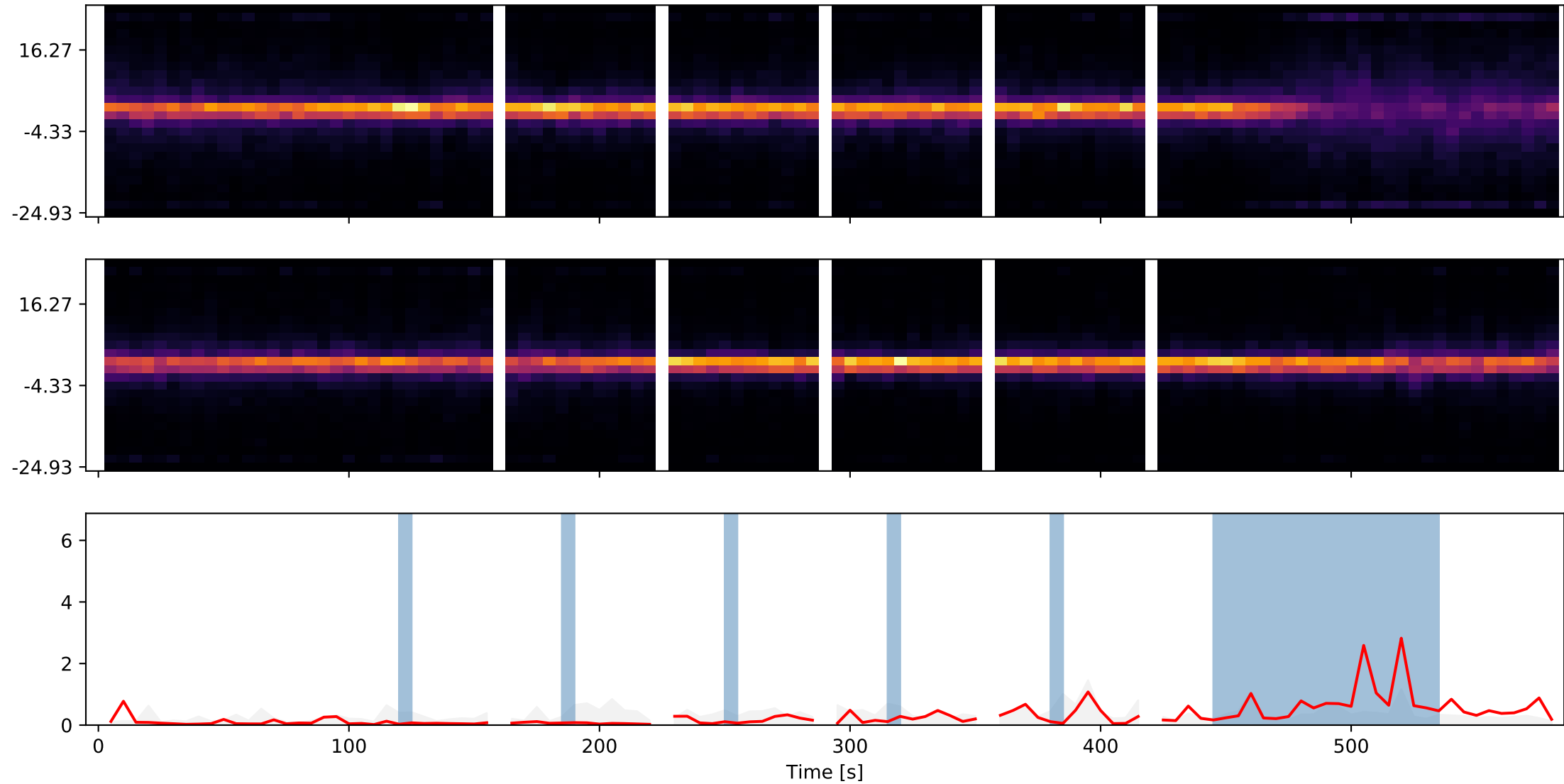
speed_neck



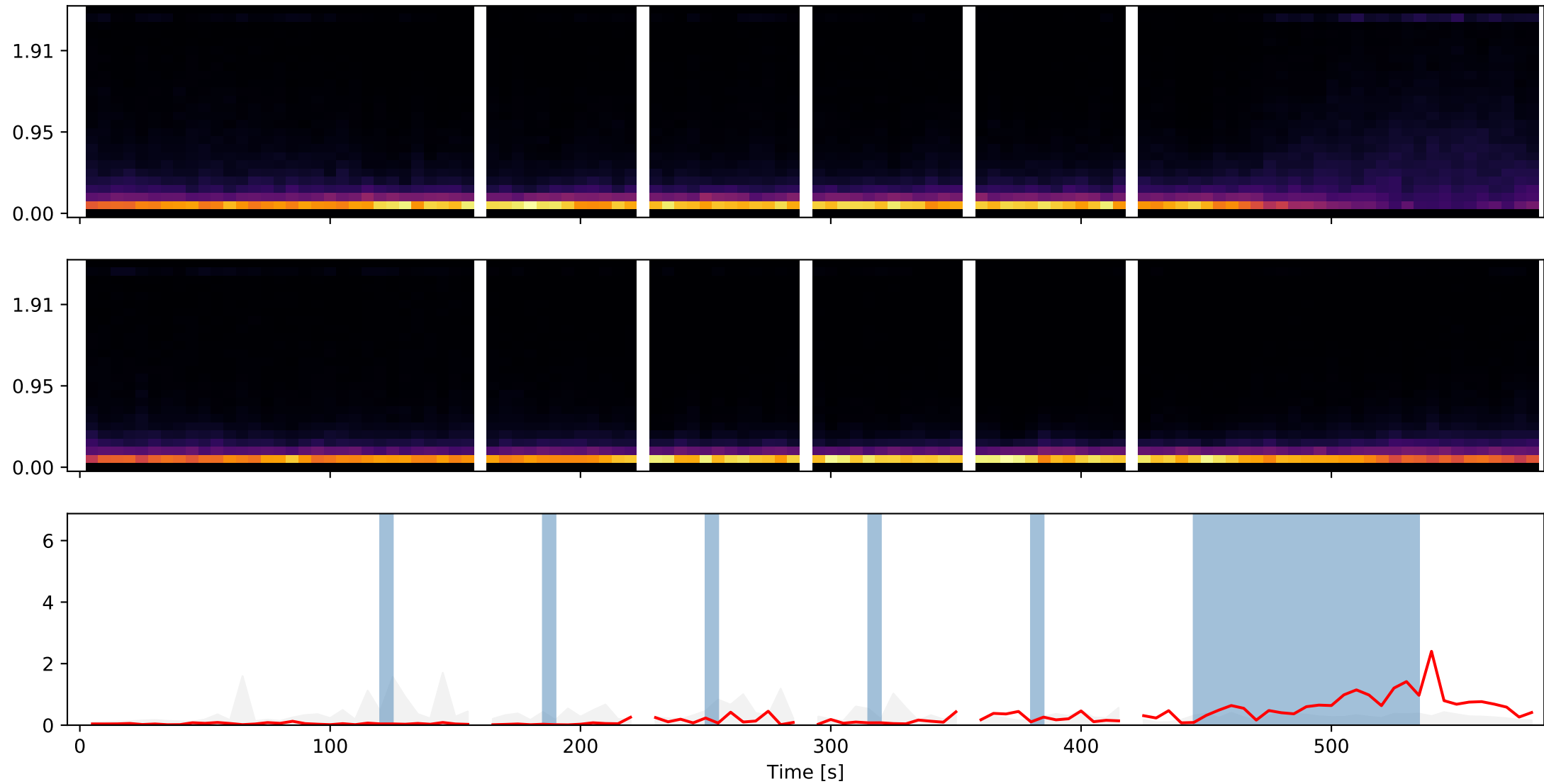
d_curvature_tail



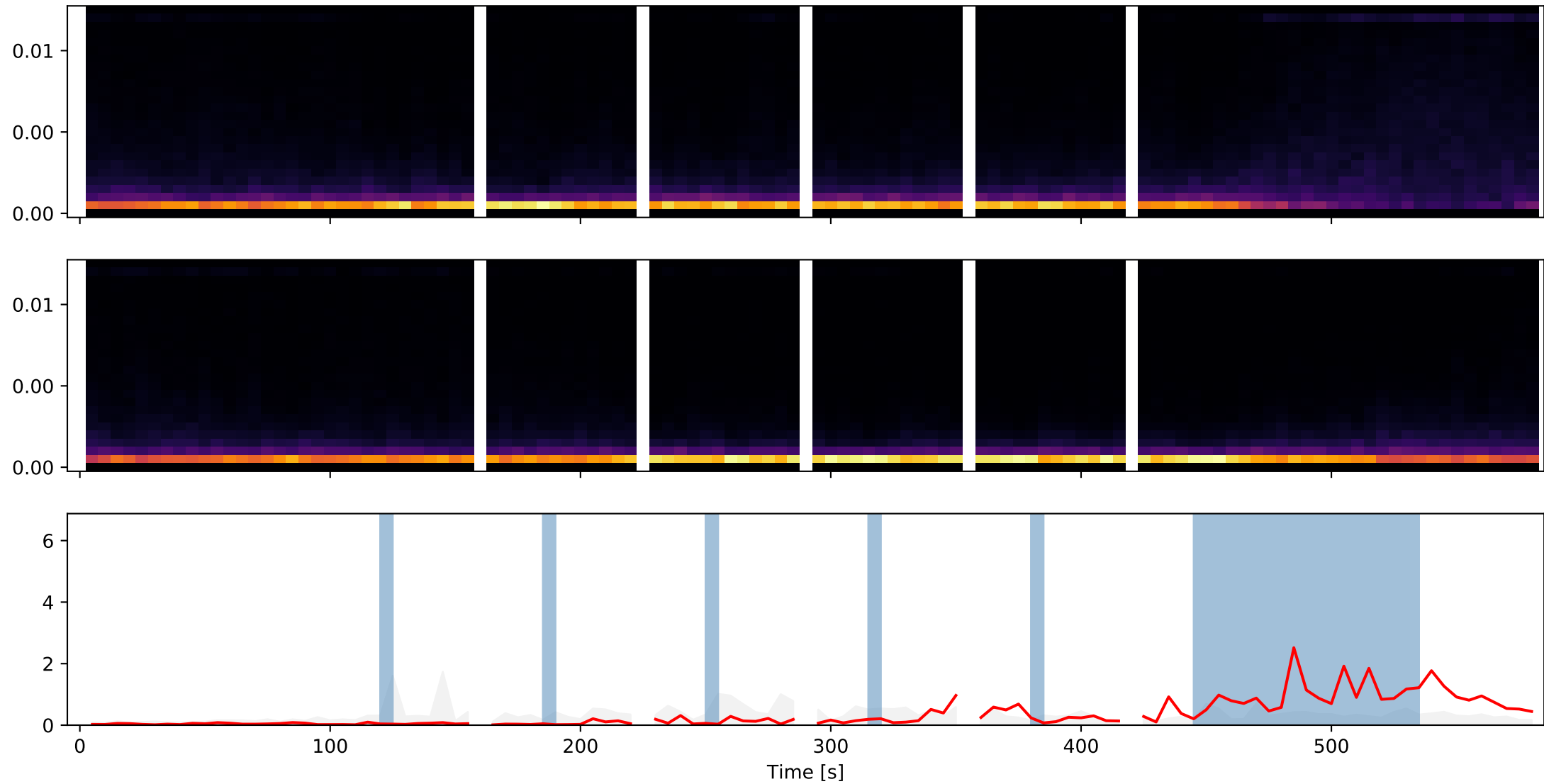
d_orientation_food_edge



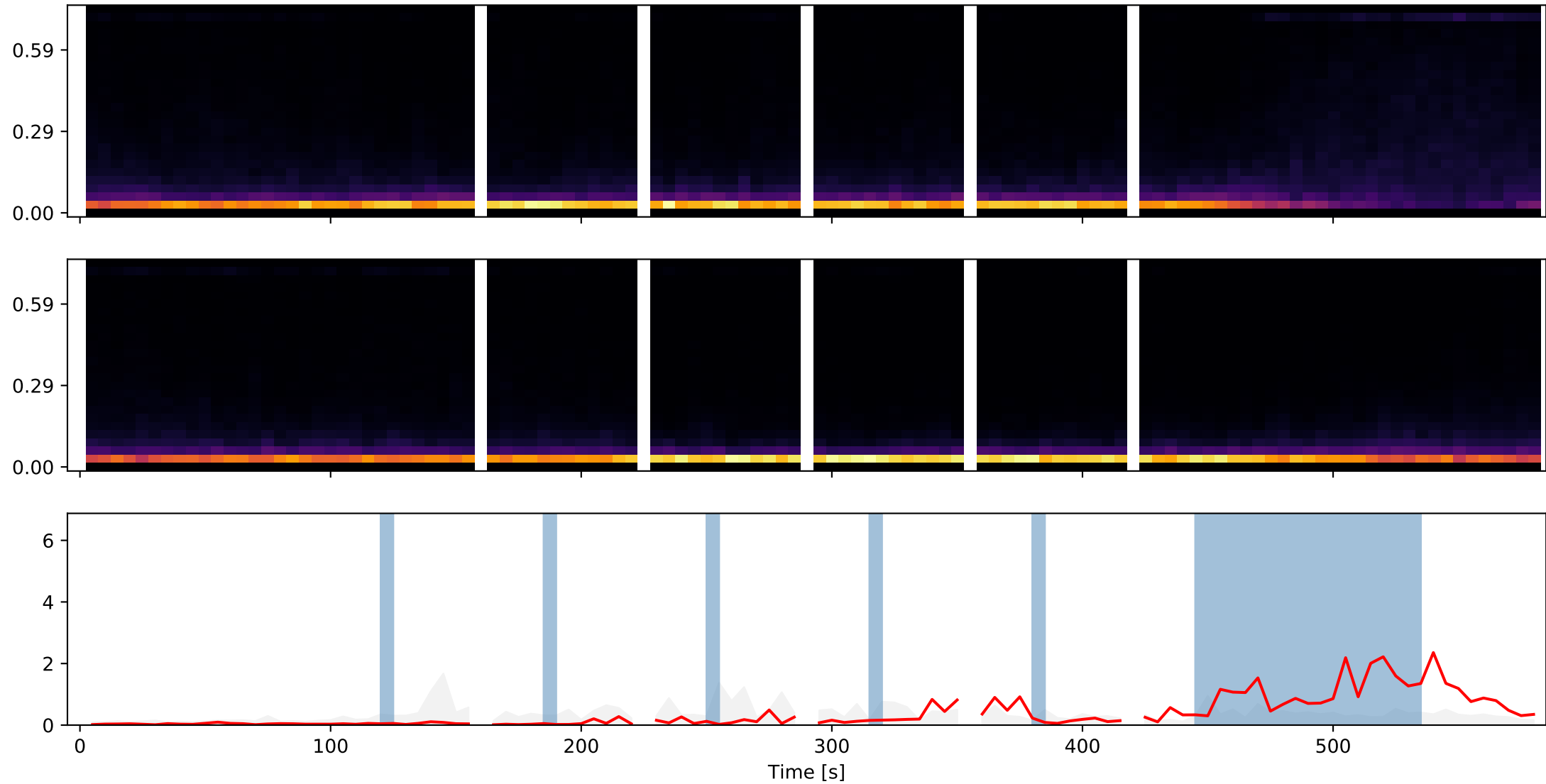
d_relative_to_body_angular_velocity_neck



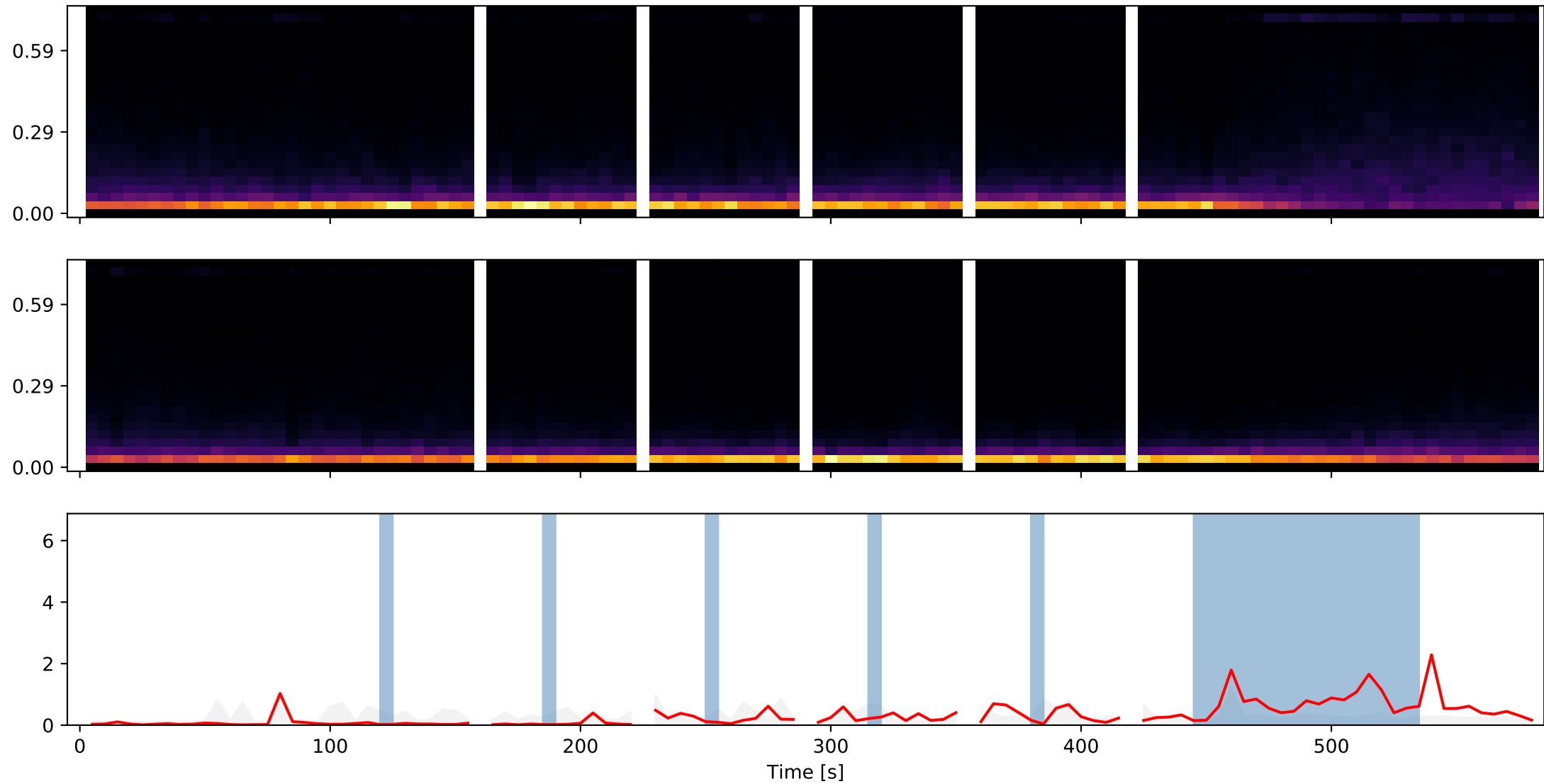
d_curvature_mean_midbody



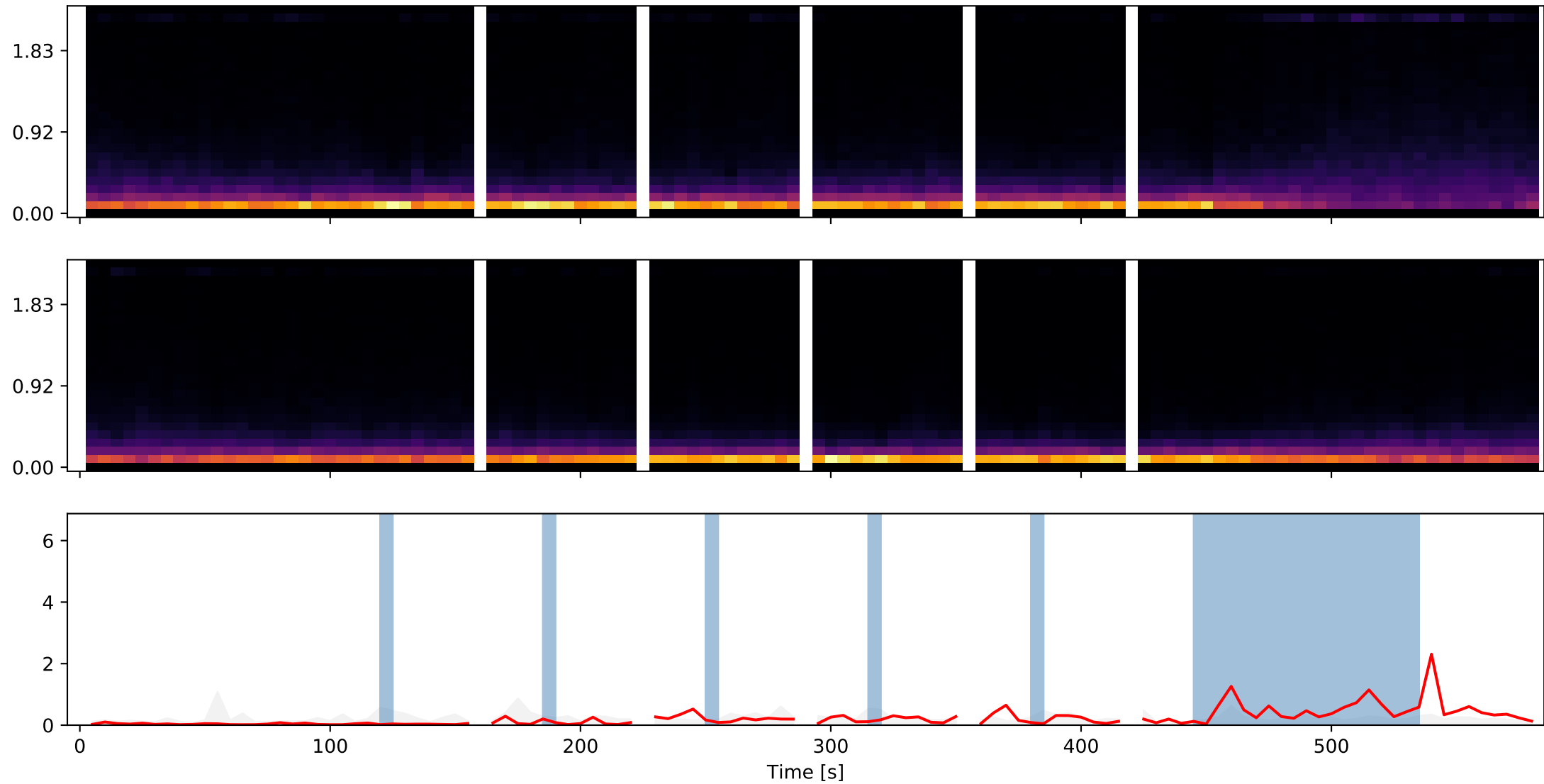
relative_to_body_angular_velocity_hips



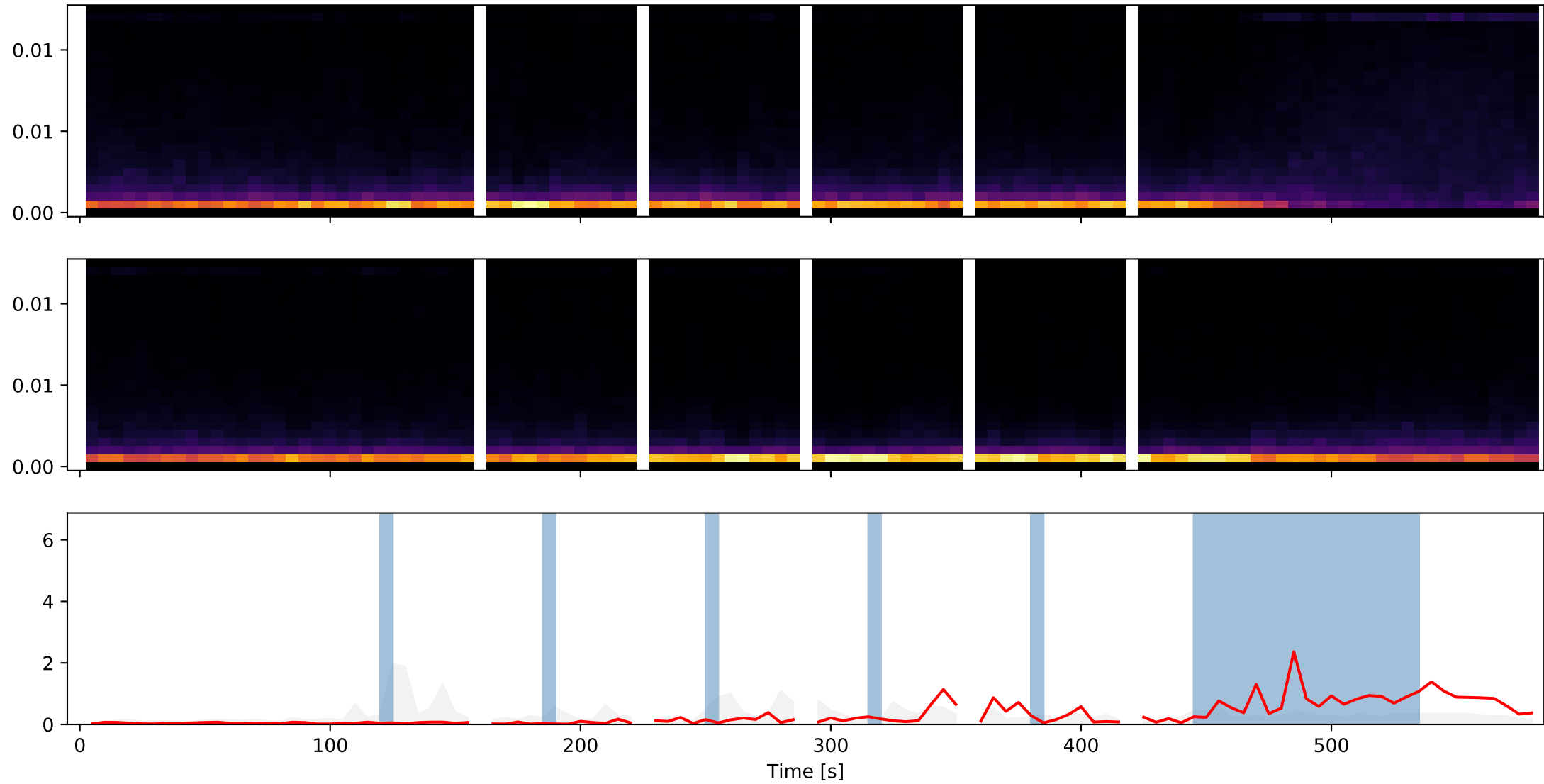
relative_to_body_angular_velocity_tail_tip



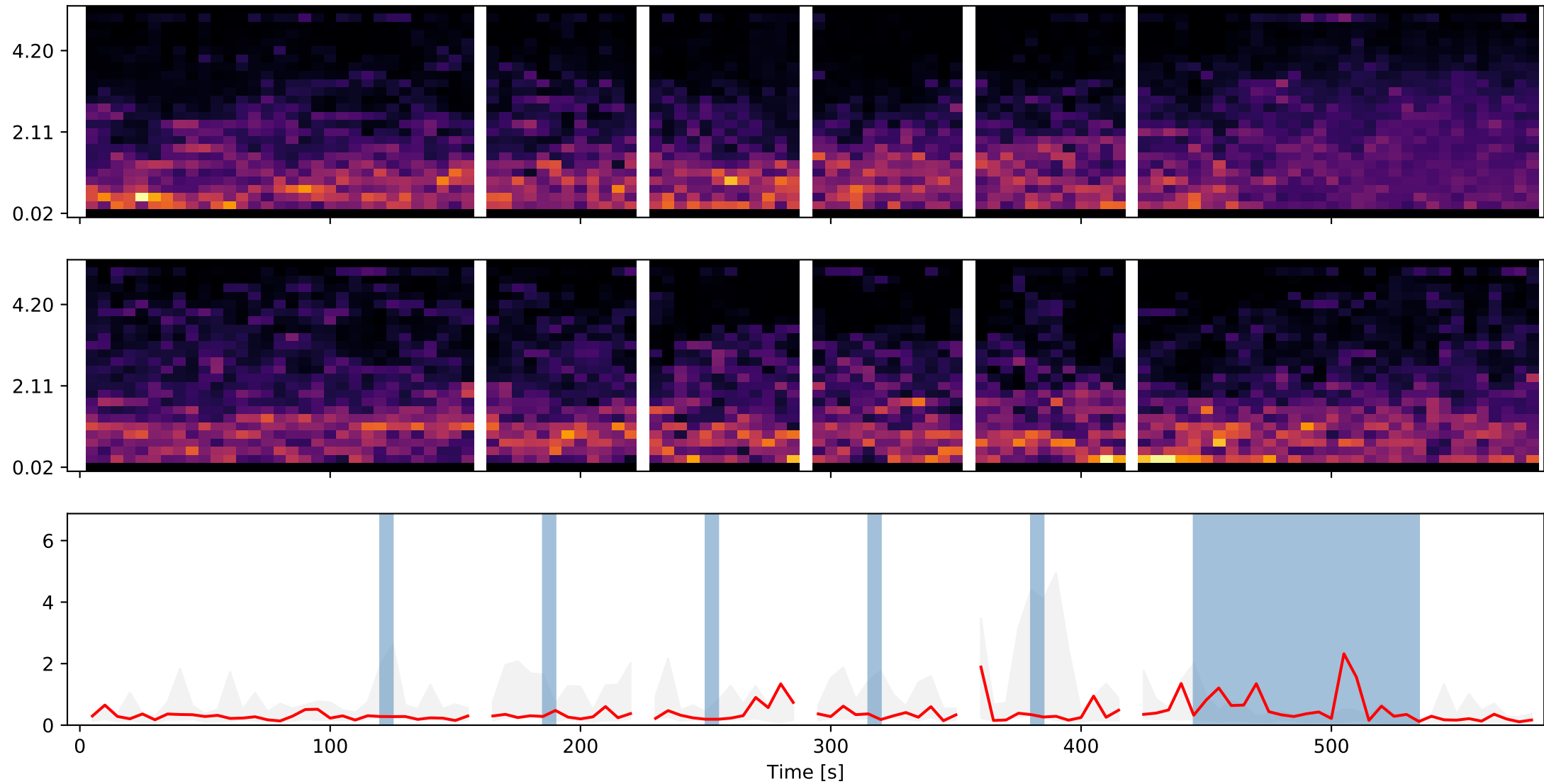
d_relative_to_body_angular_velocity_tail_tip



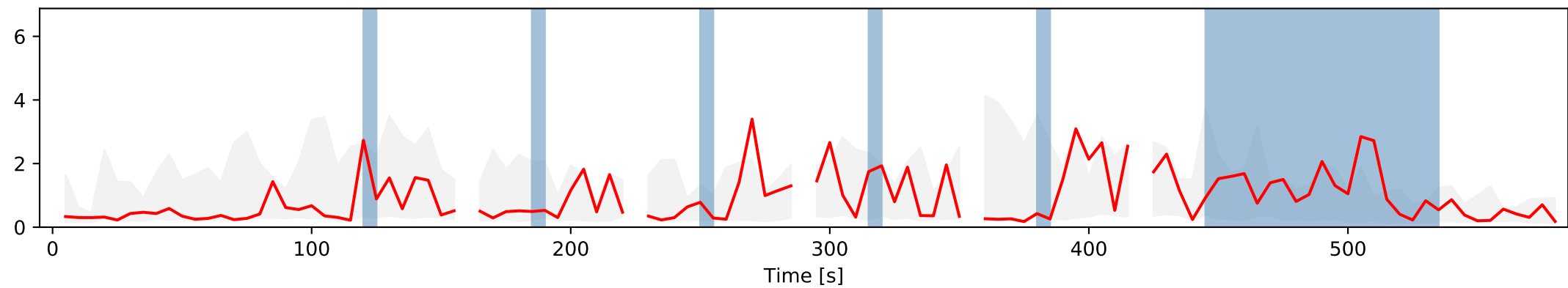
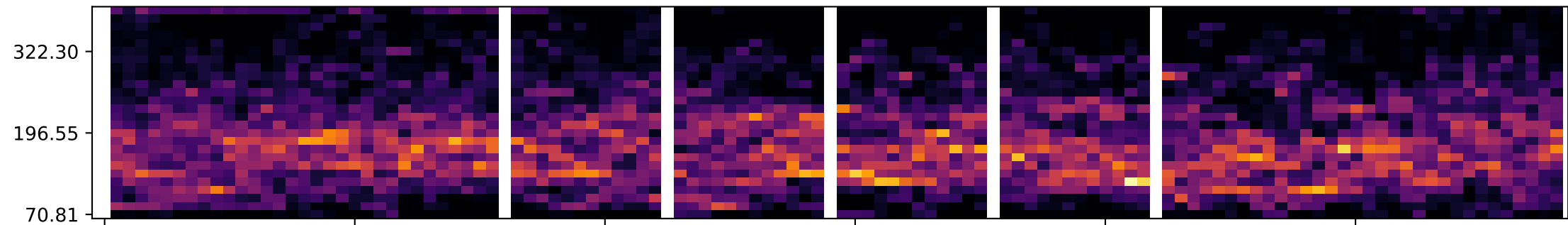
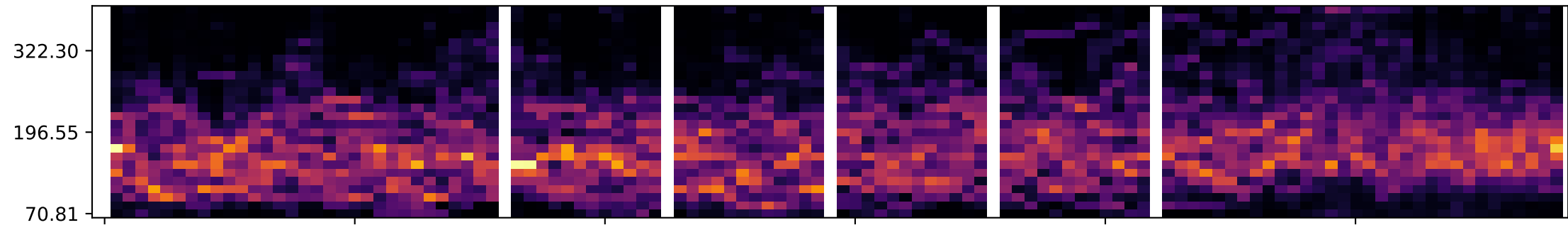
d_curvature_mean_hips



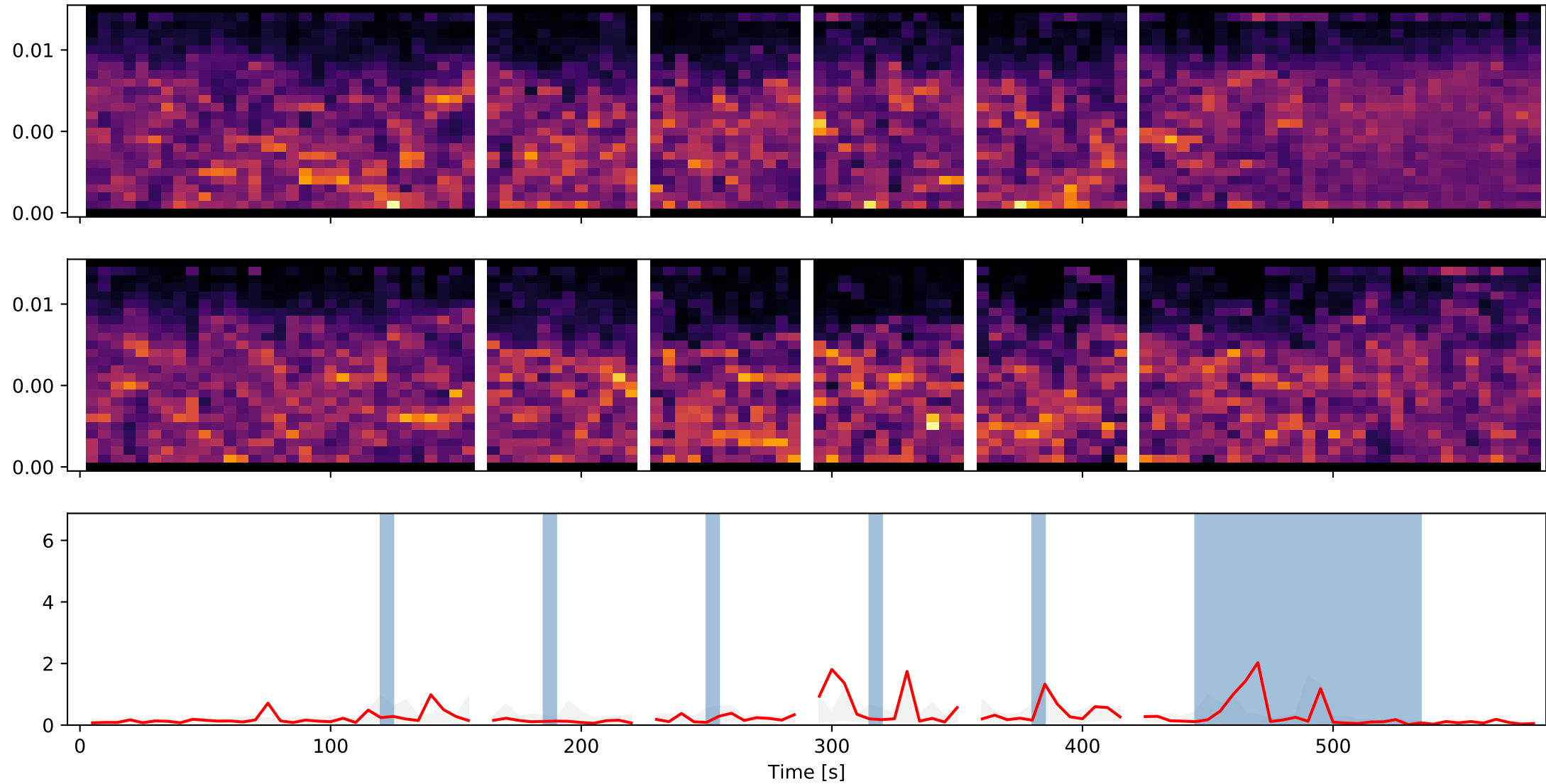
eigen_projection_2



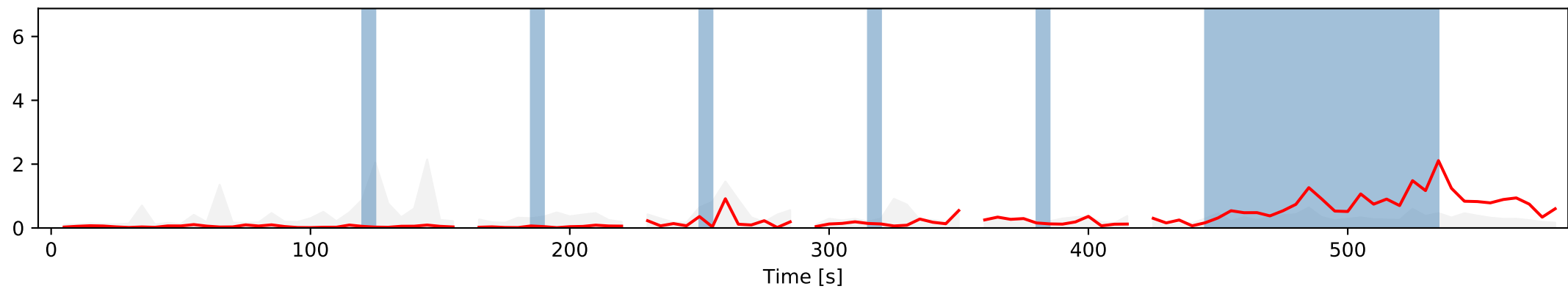
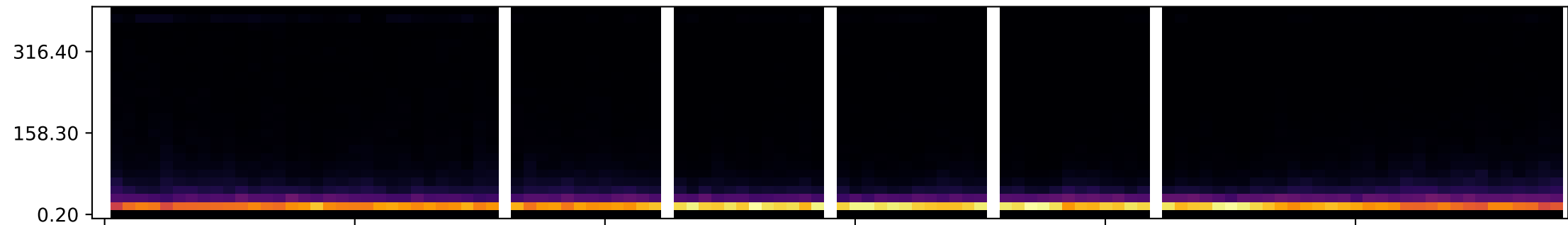
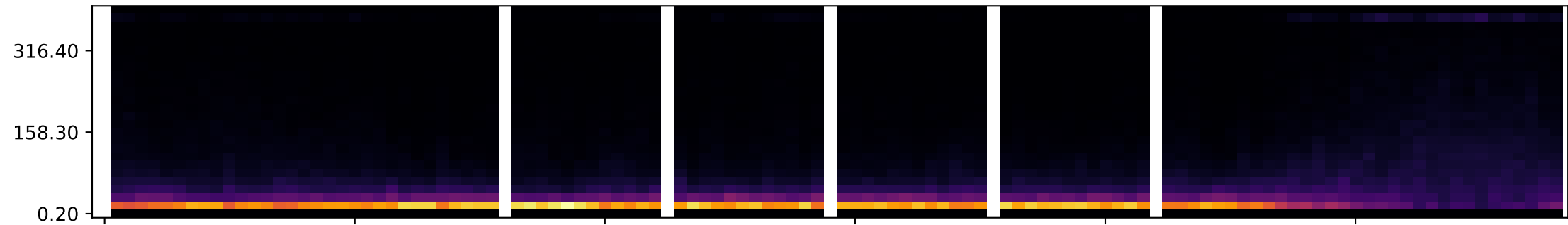
minor_axis



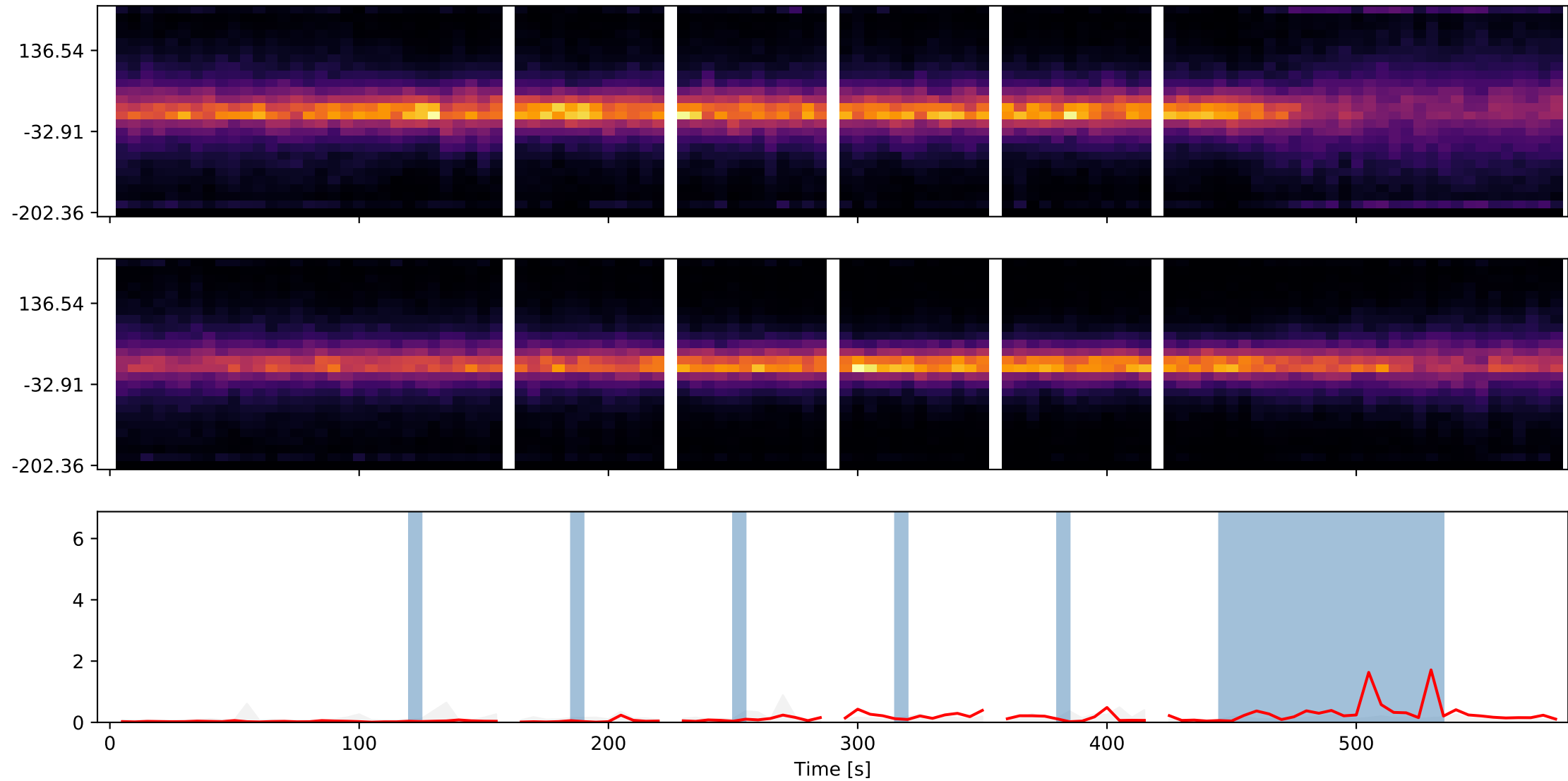
curvature_mean_neck



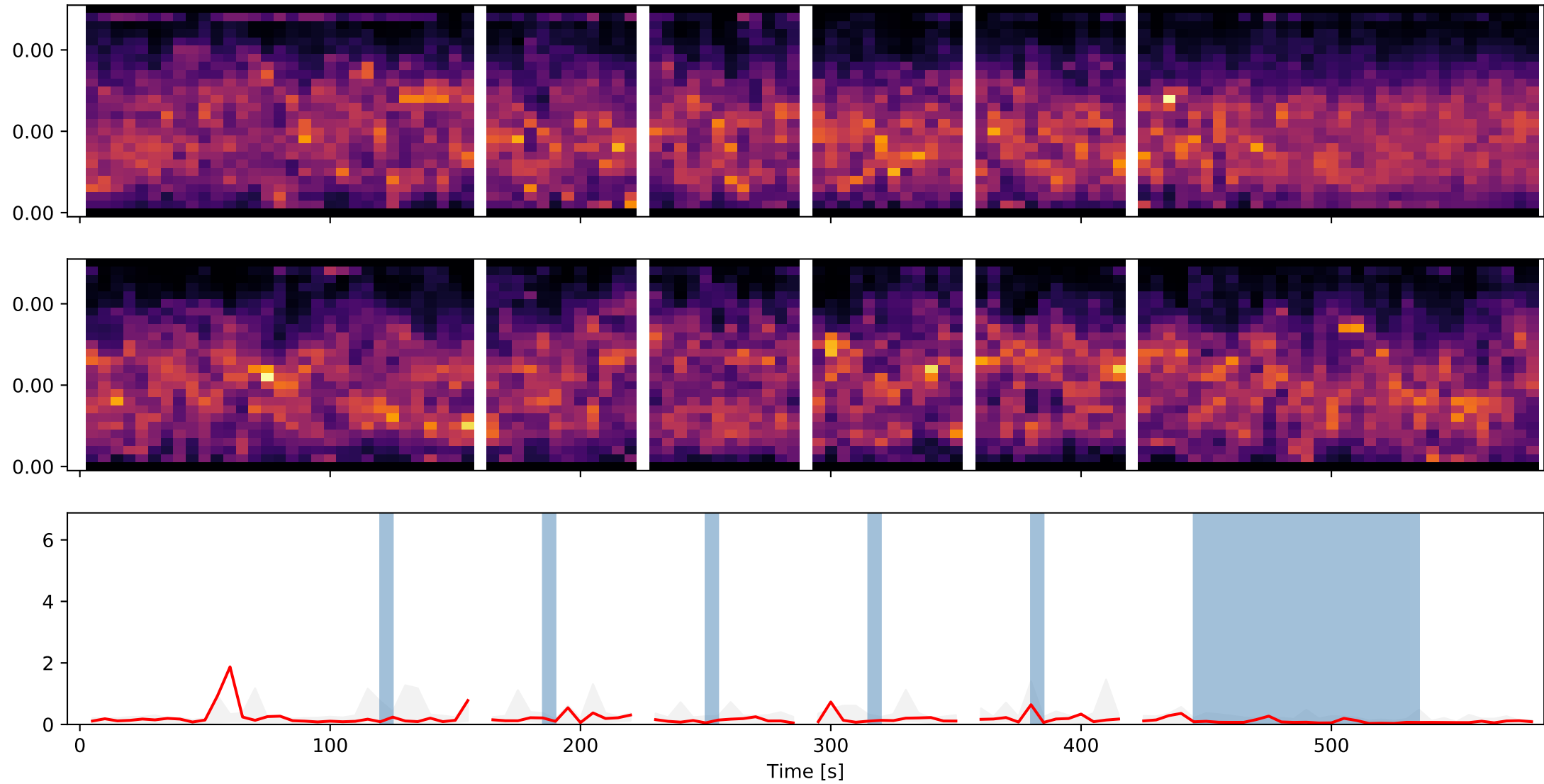
d_relative_to_body_speed_midbody



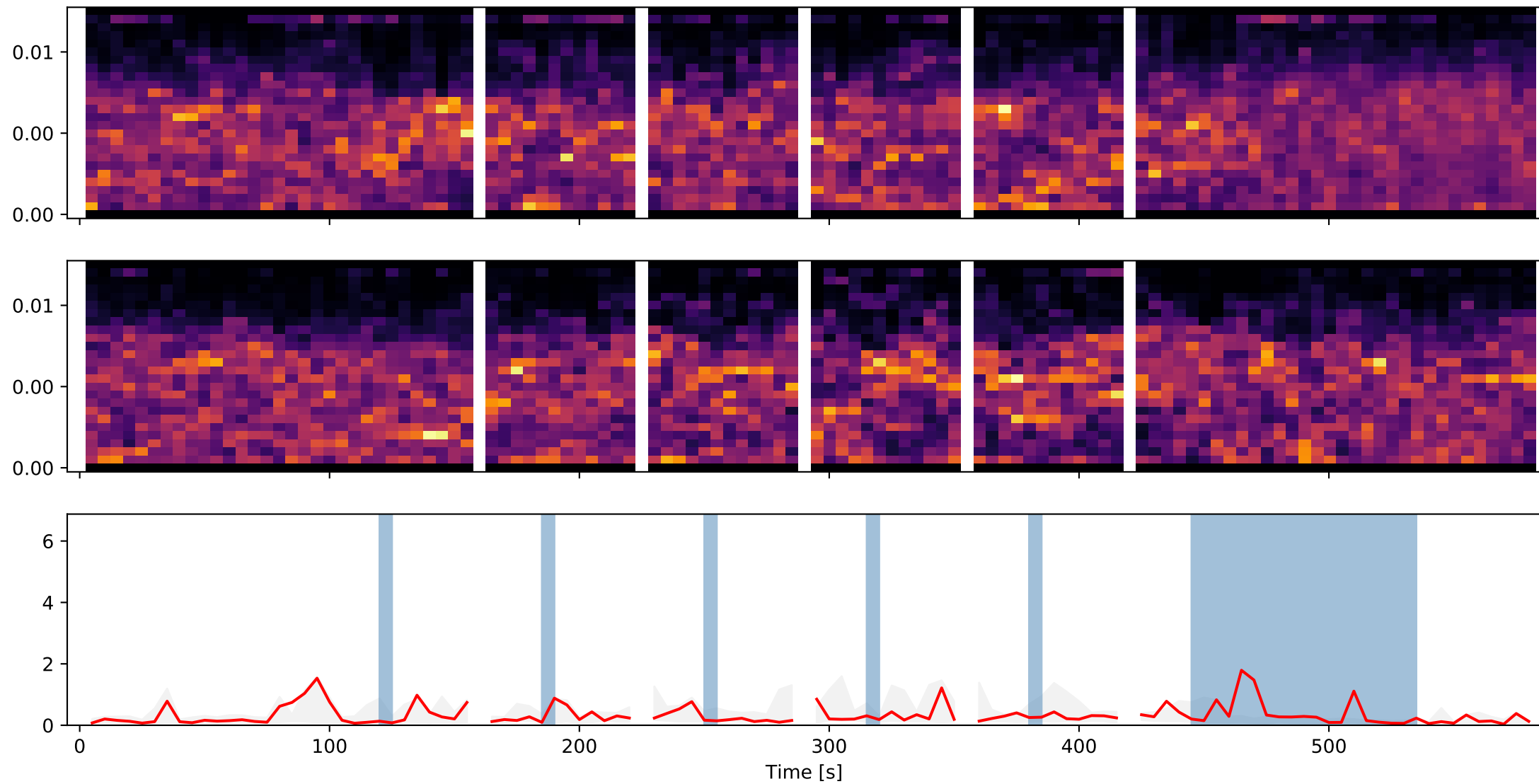
d_major_axis



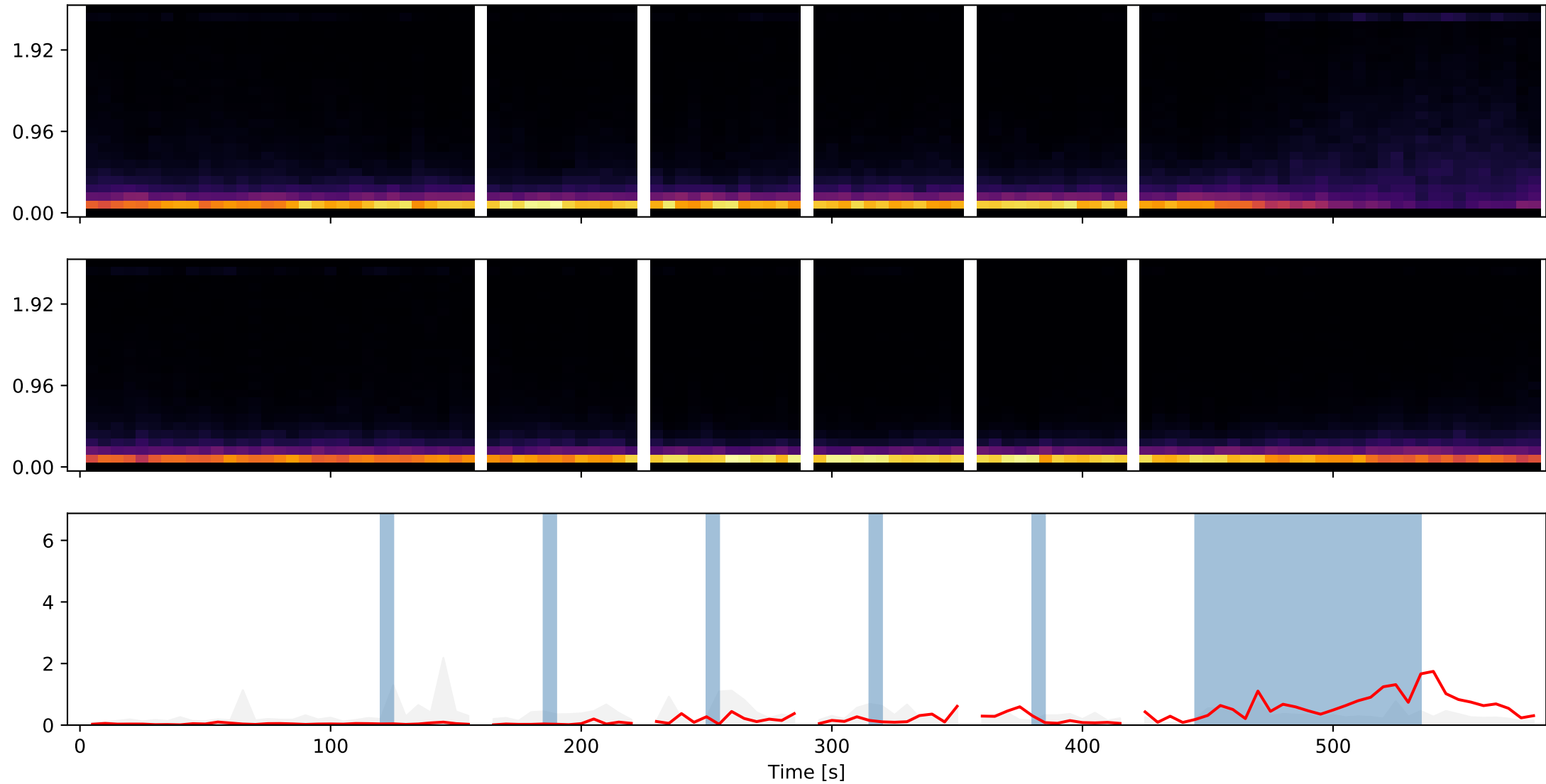
curvature_std_hips



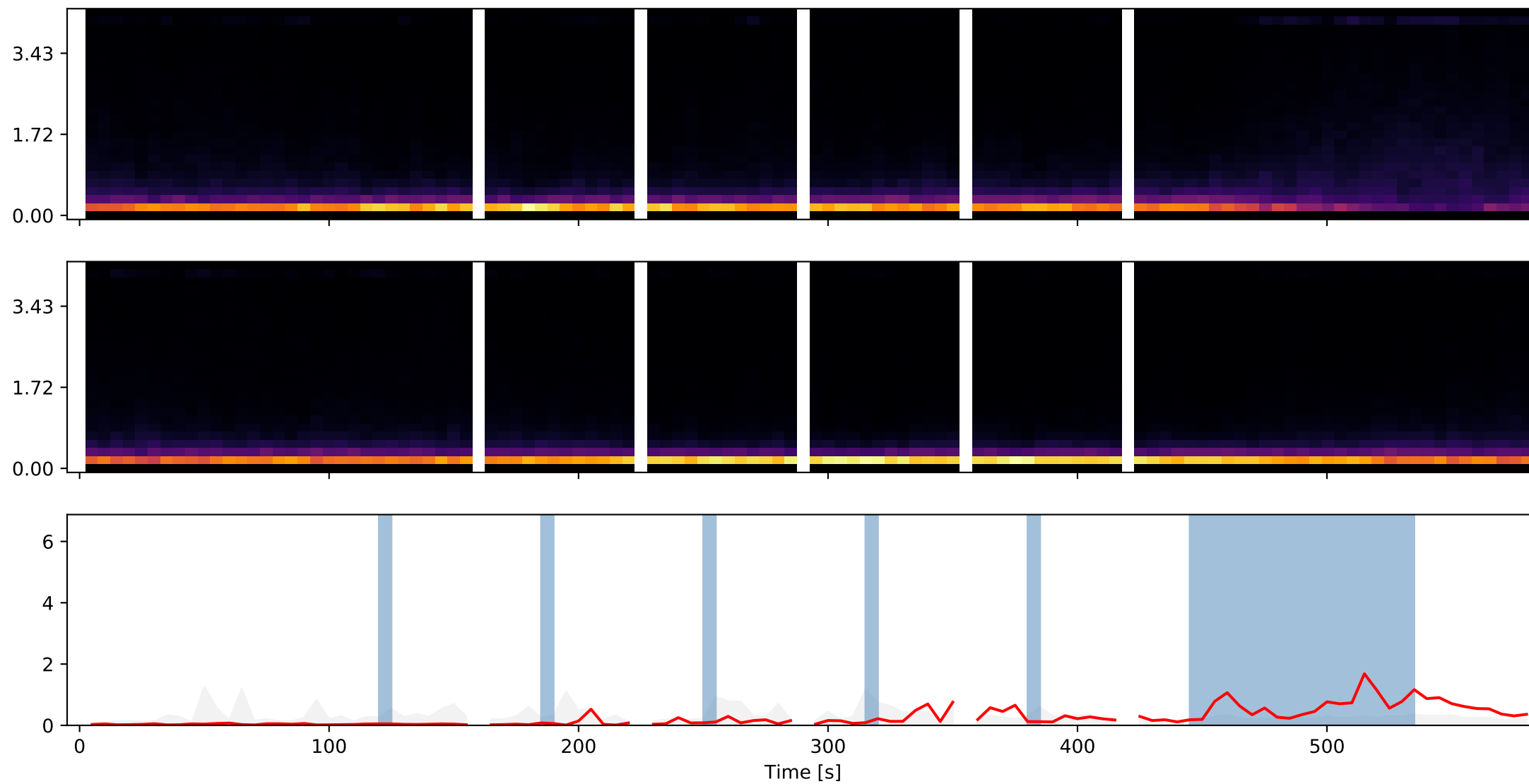
curvature_mean_tail



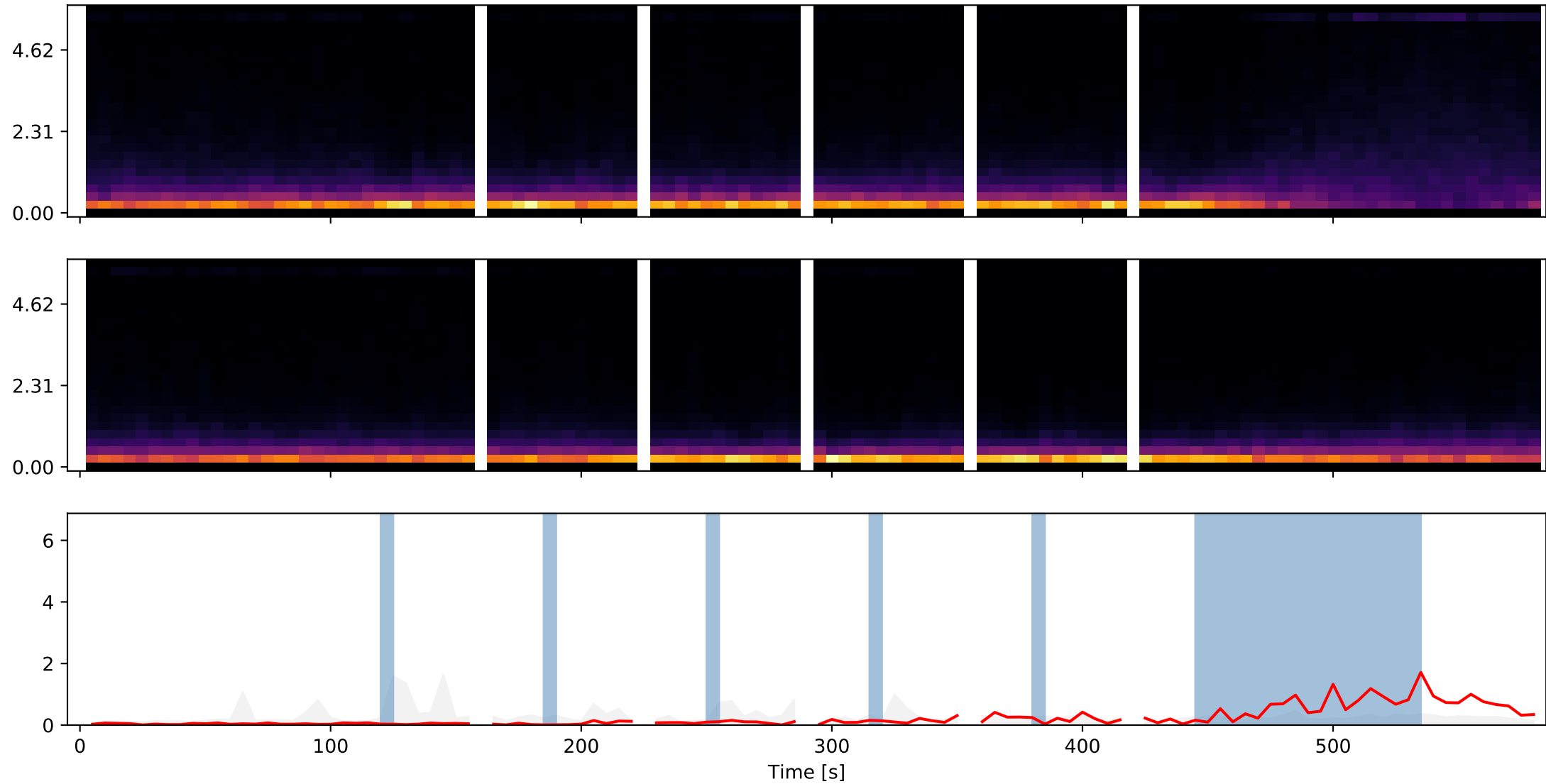
d_relative_to_body_angular_velocity_hips



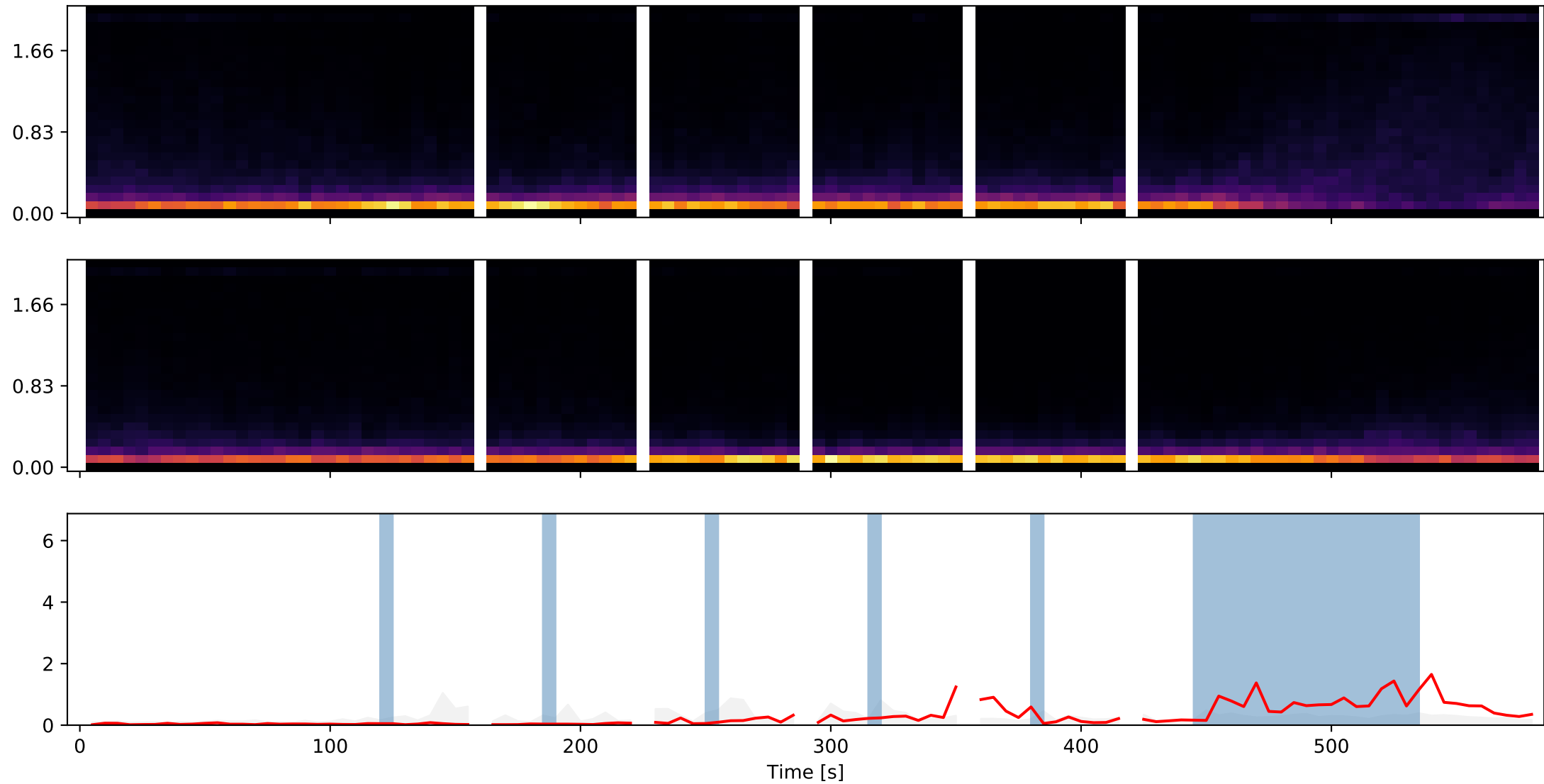
d_angular_velocity_midbody



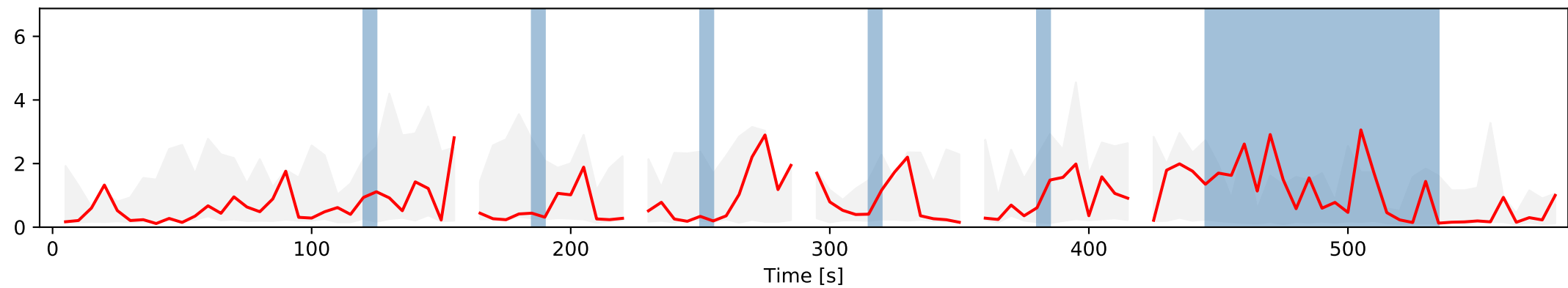
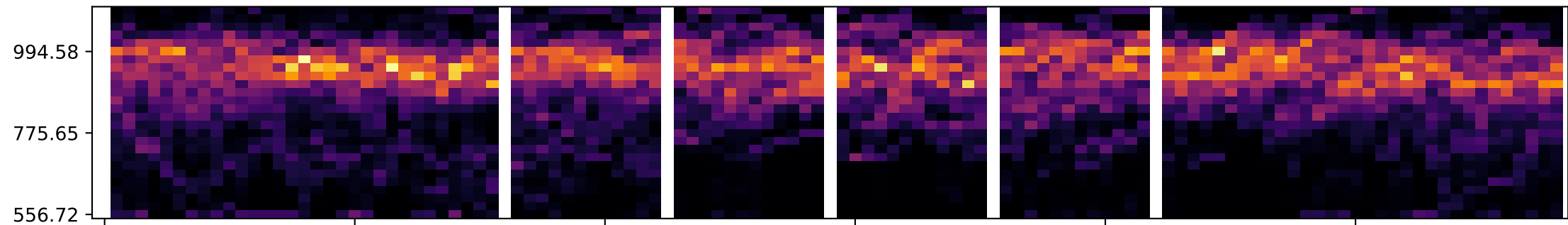
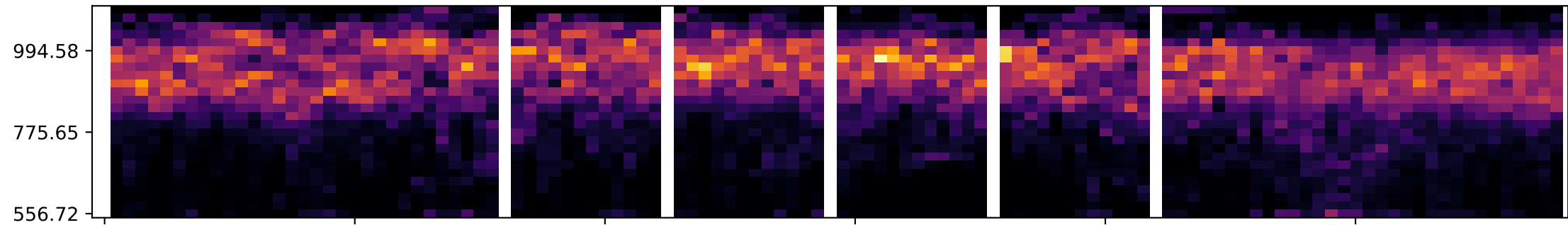
d_relative_to_hips_angular_velocity_tail_tip



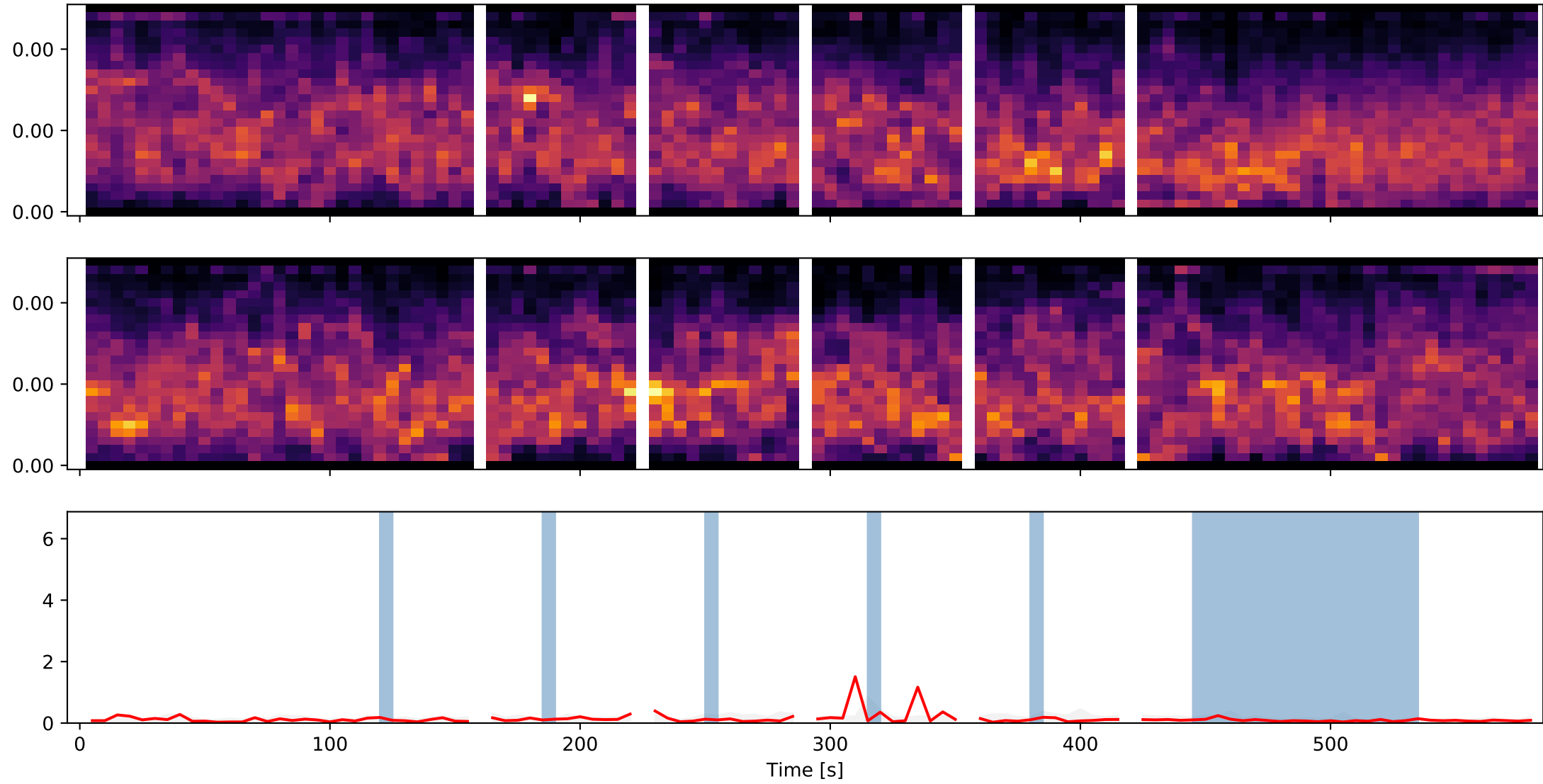
angular_velocity_neck



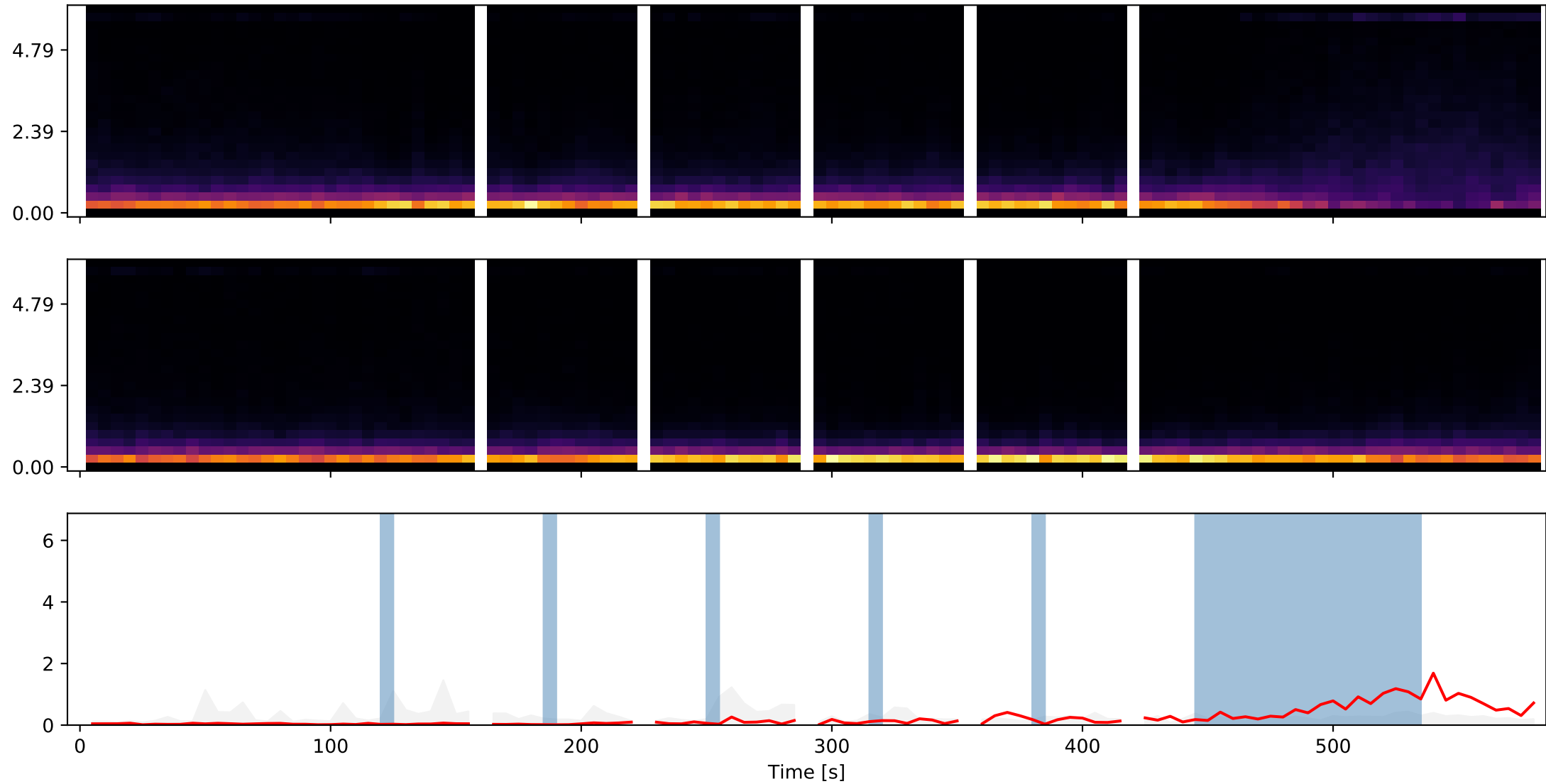
major_axis



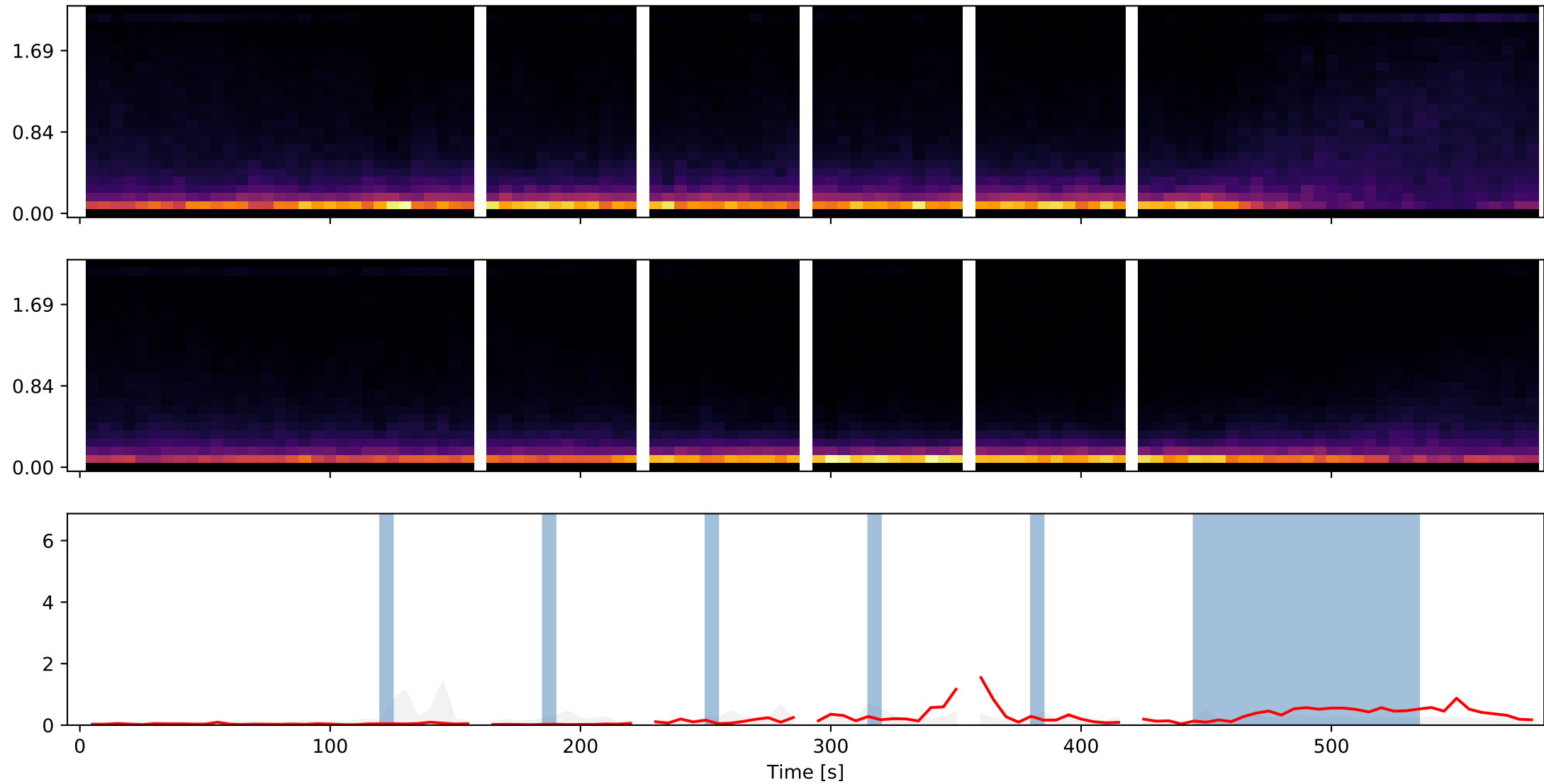
curvature_std_neck



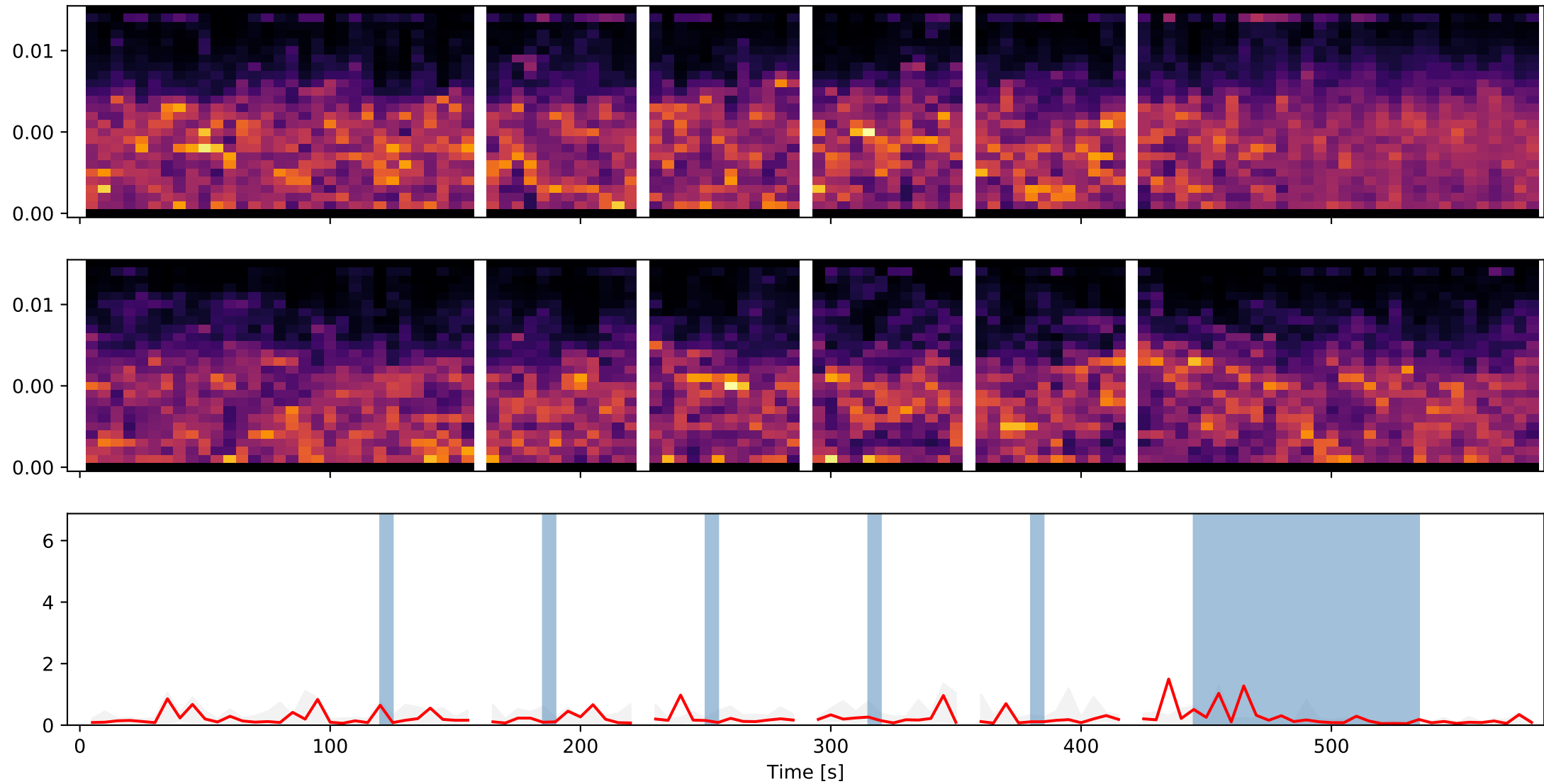
d_angular_velocity_hips



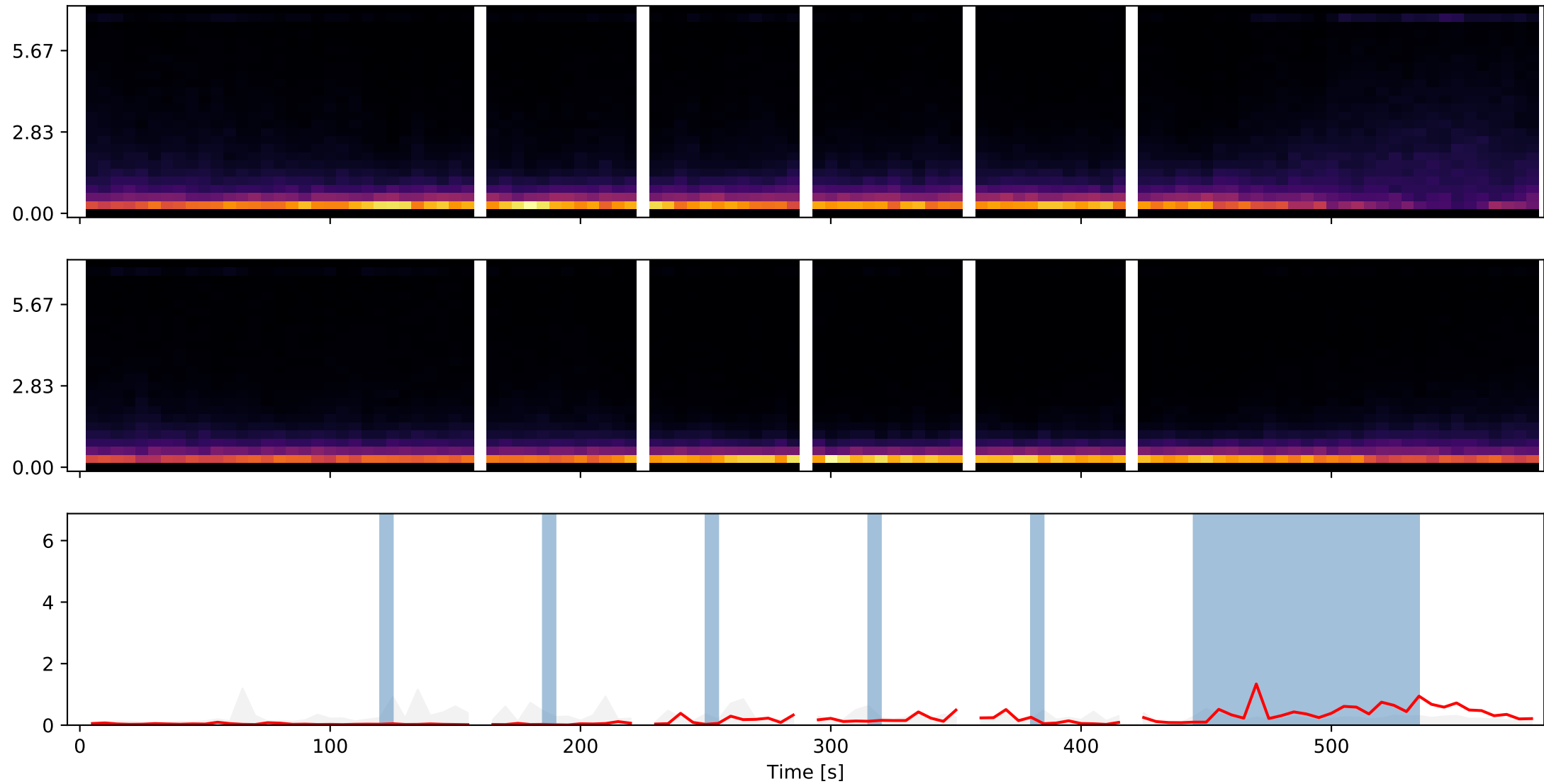
relative_to_neck_angular_velocity_head_tip



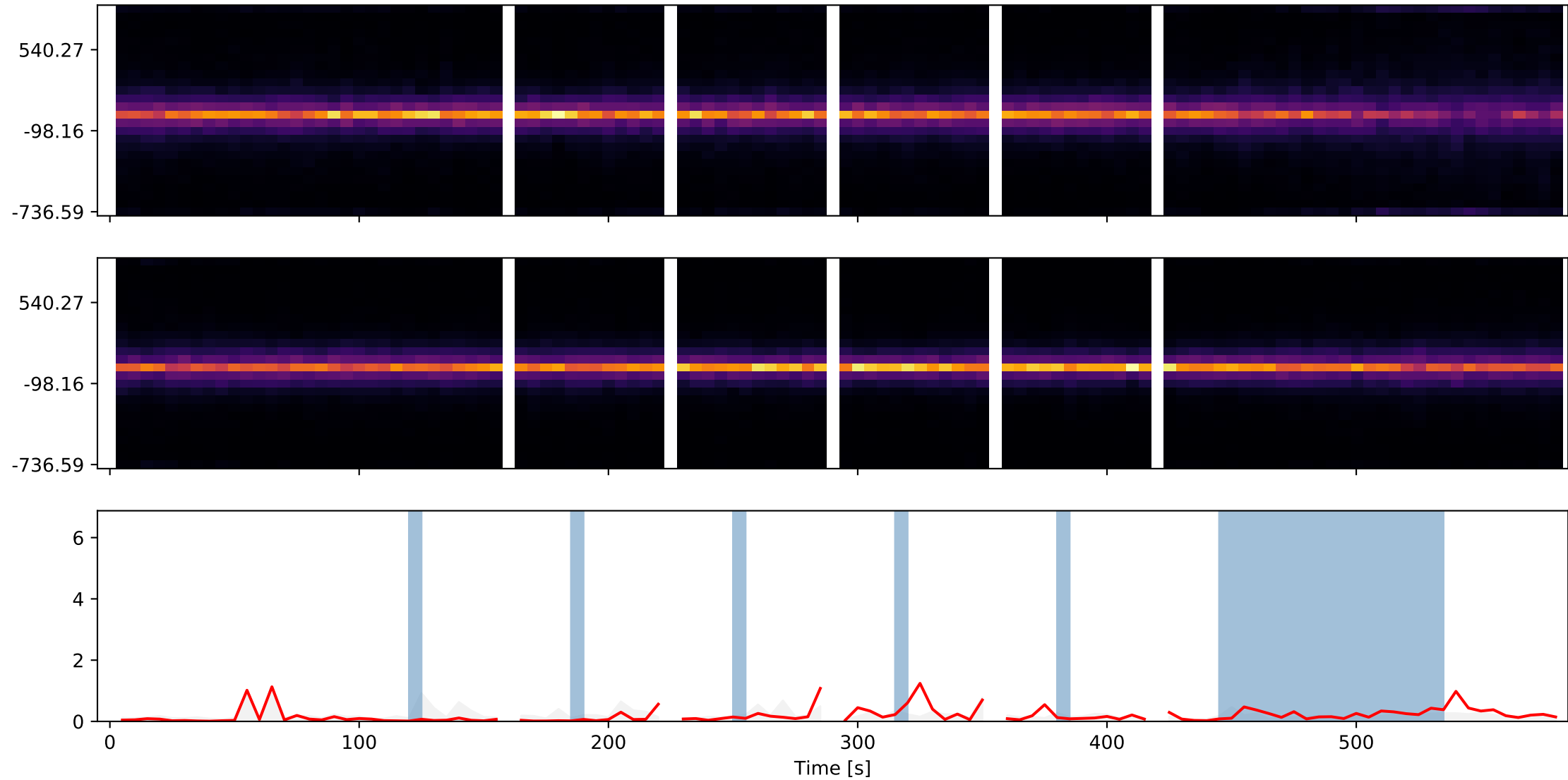
curvature_tail



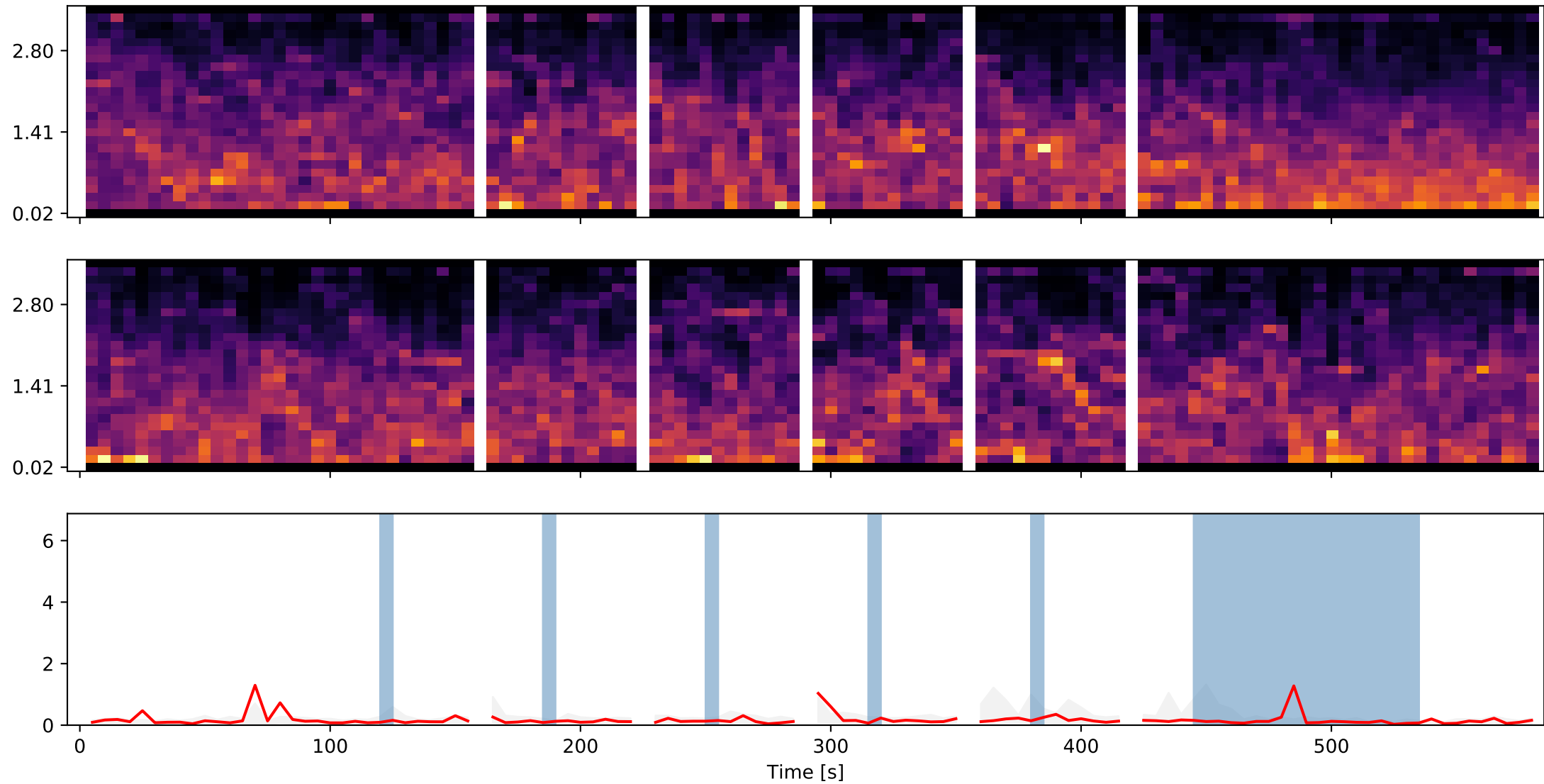
d_angular_velocity_neck



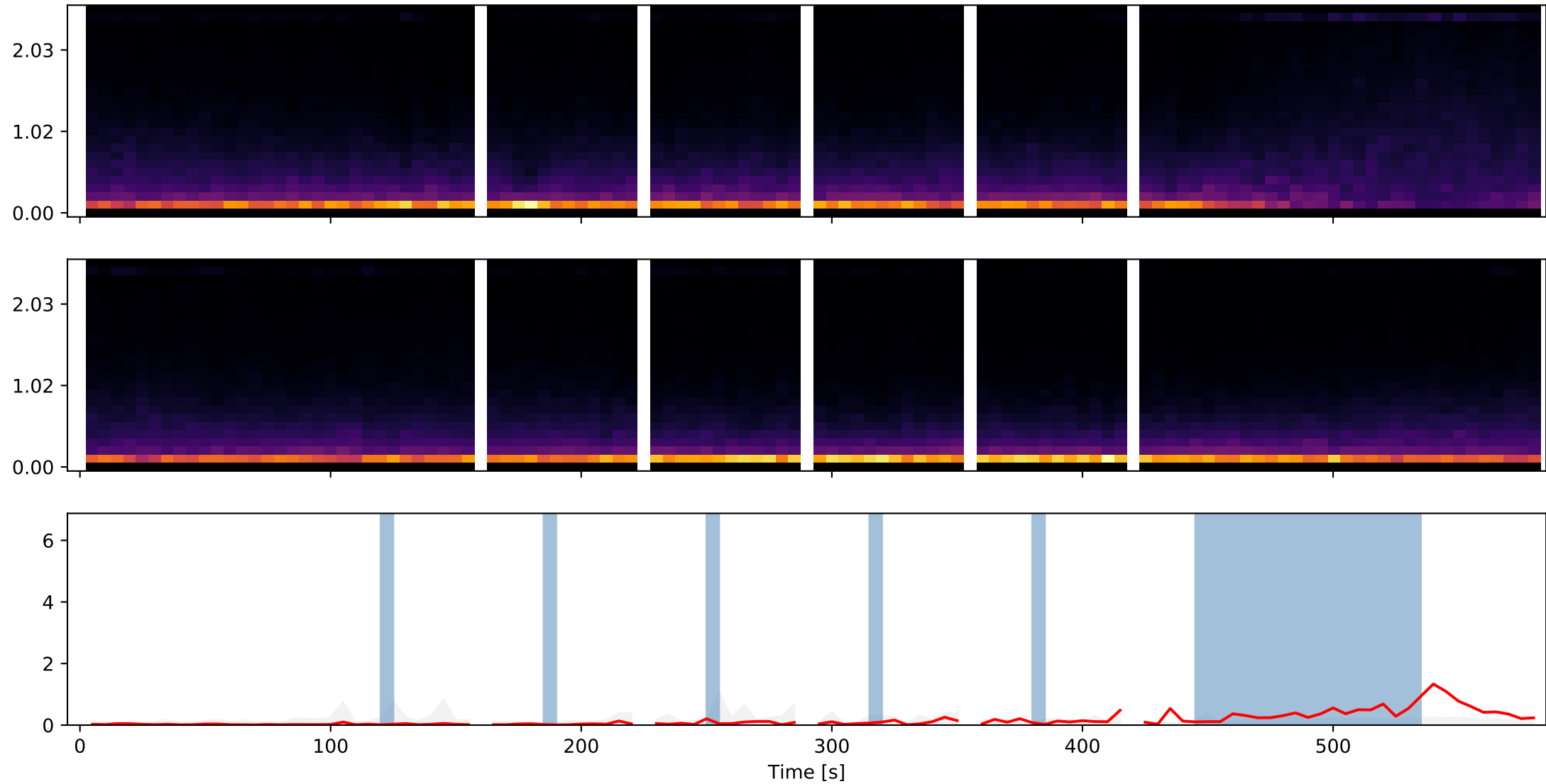
d_speed_tail_tip



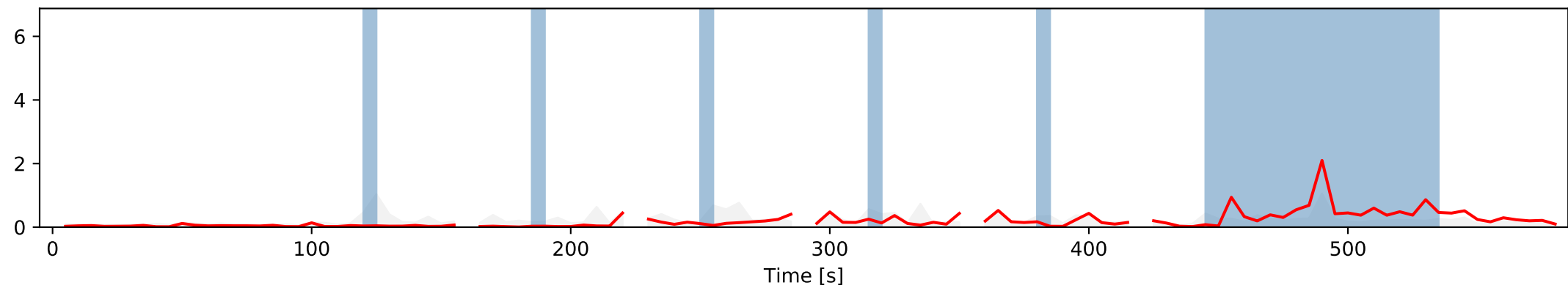
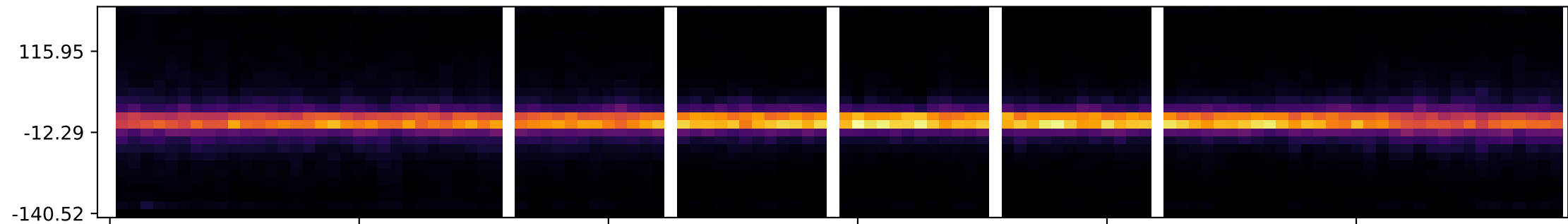
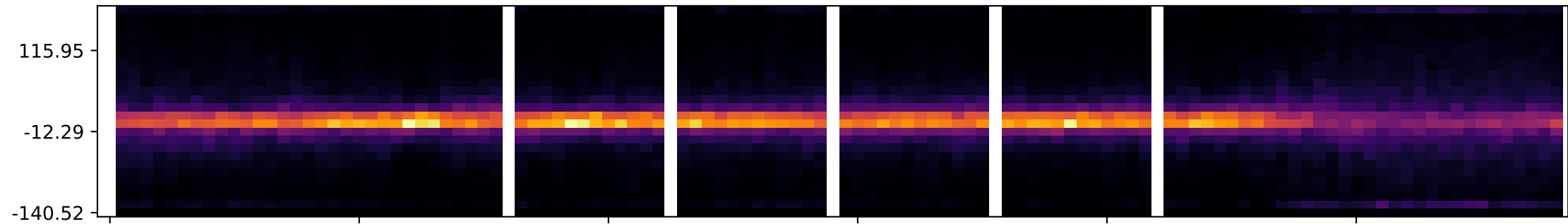
eigen_projection_4



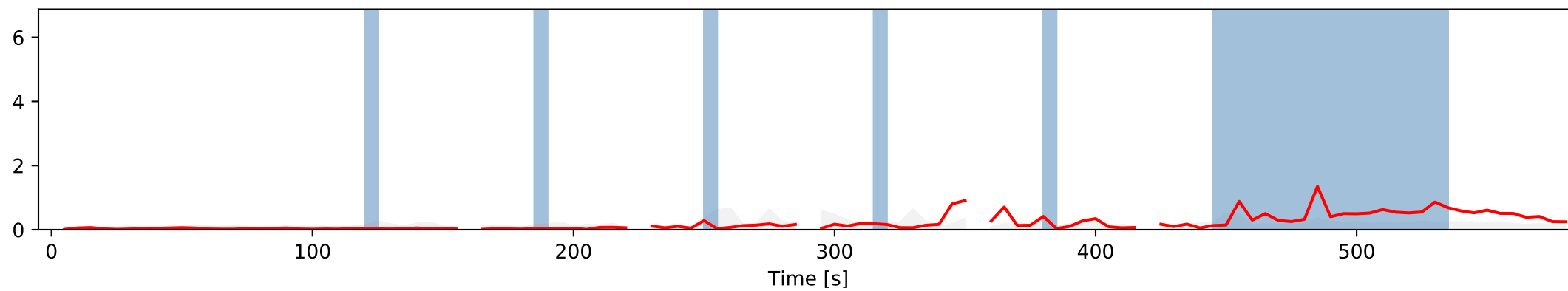
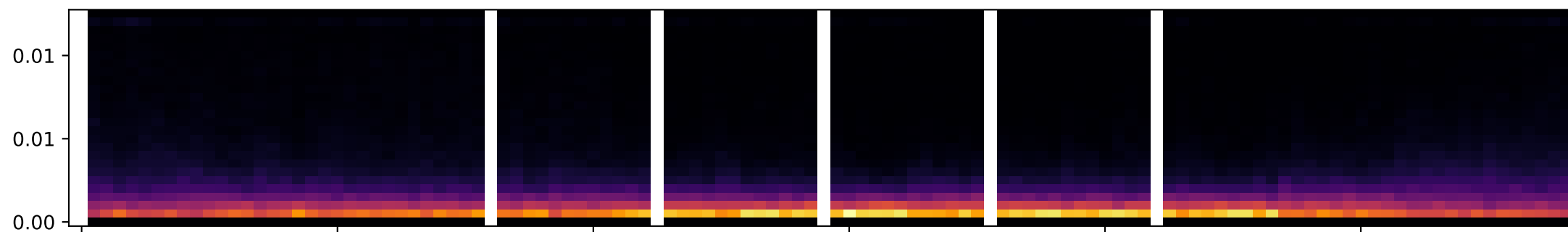
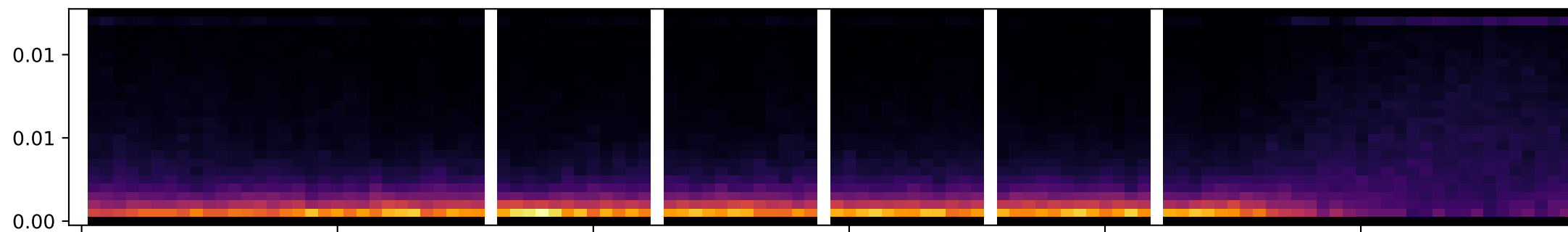
angular_velocity_tail_tip



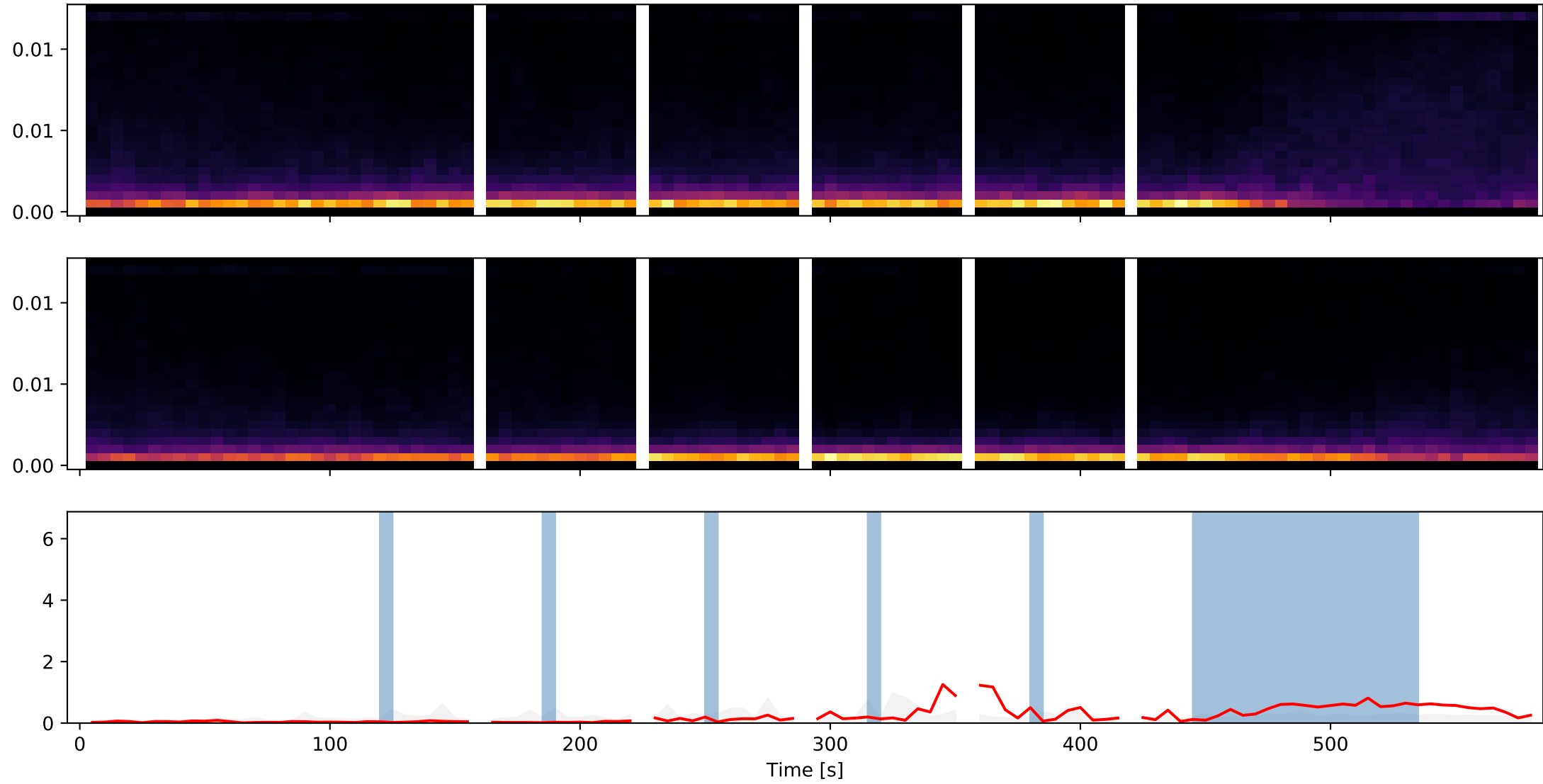
d_minor_axis



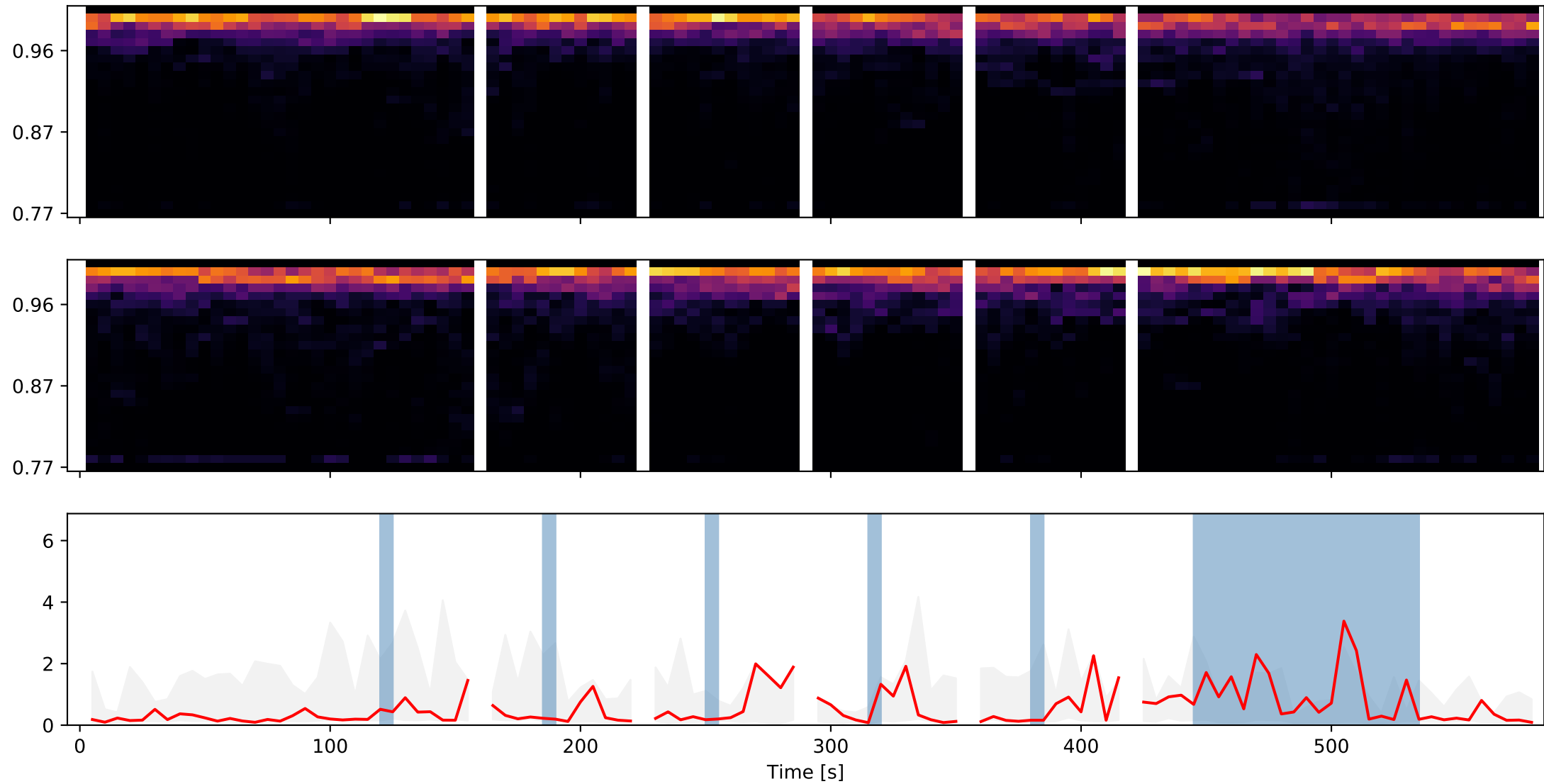
d_curvature_midbody



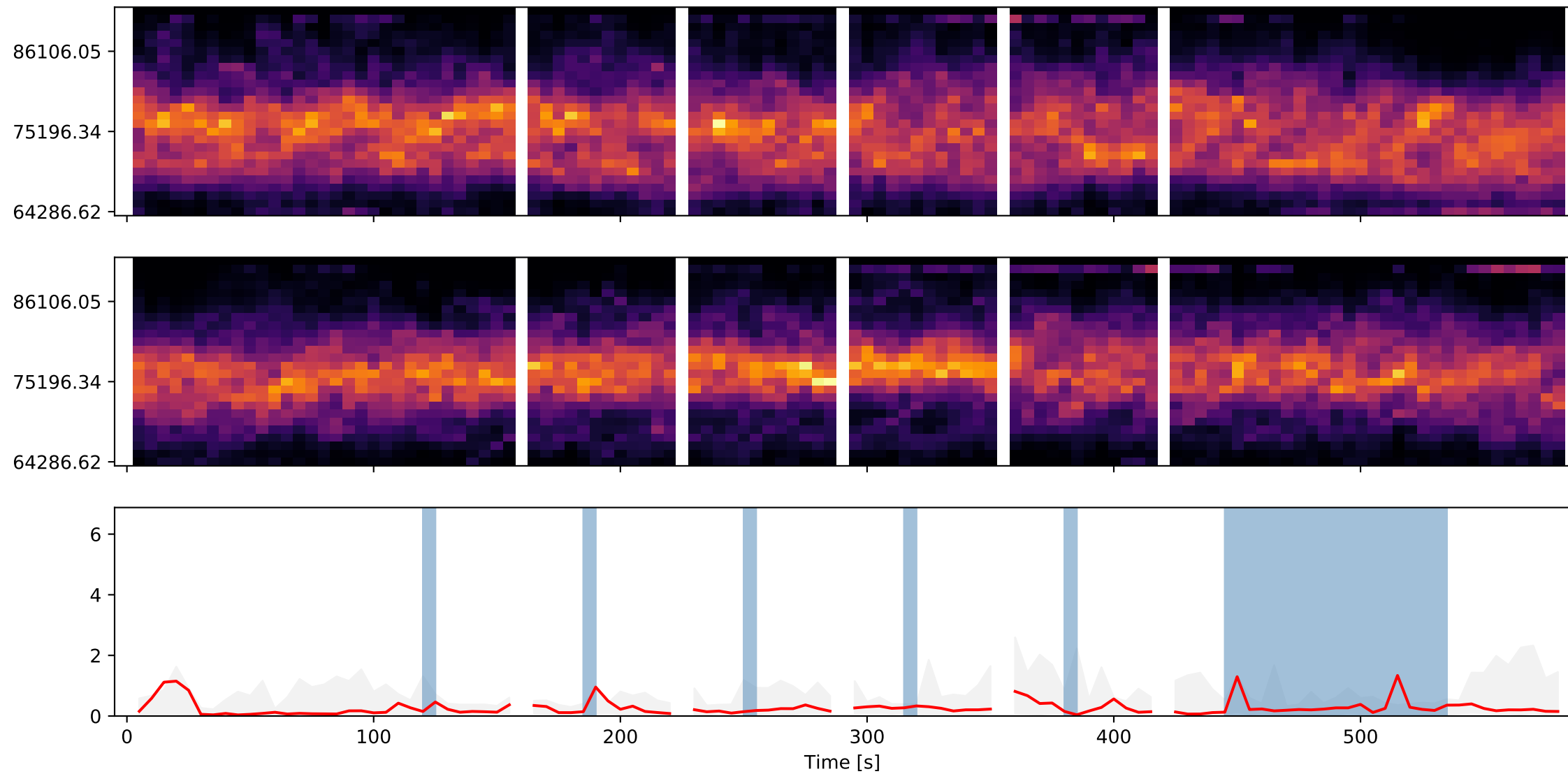
d_curvature_mean_neck



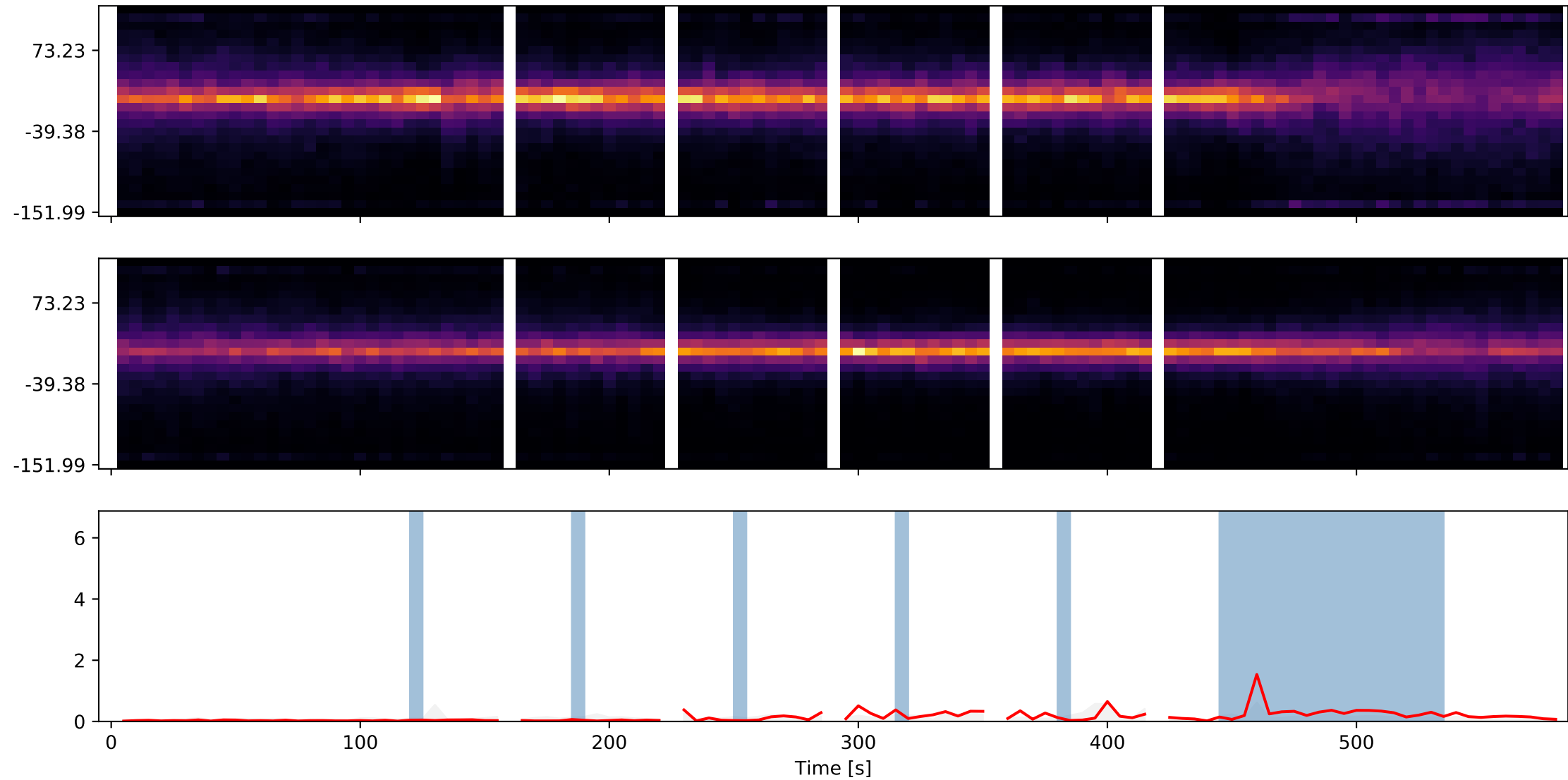
quirkiness



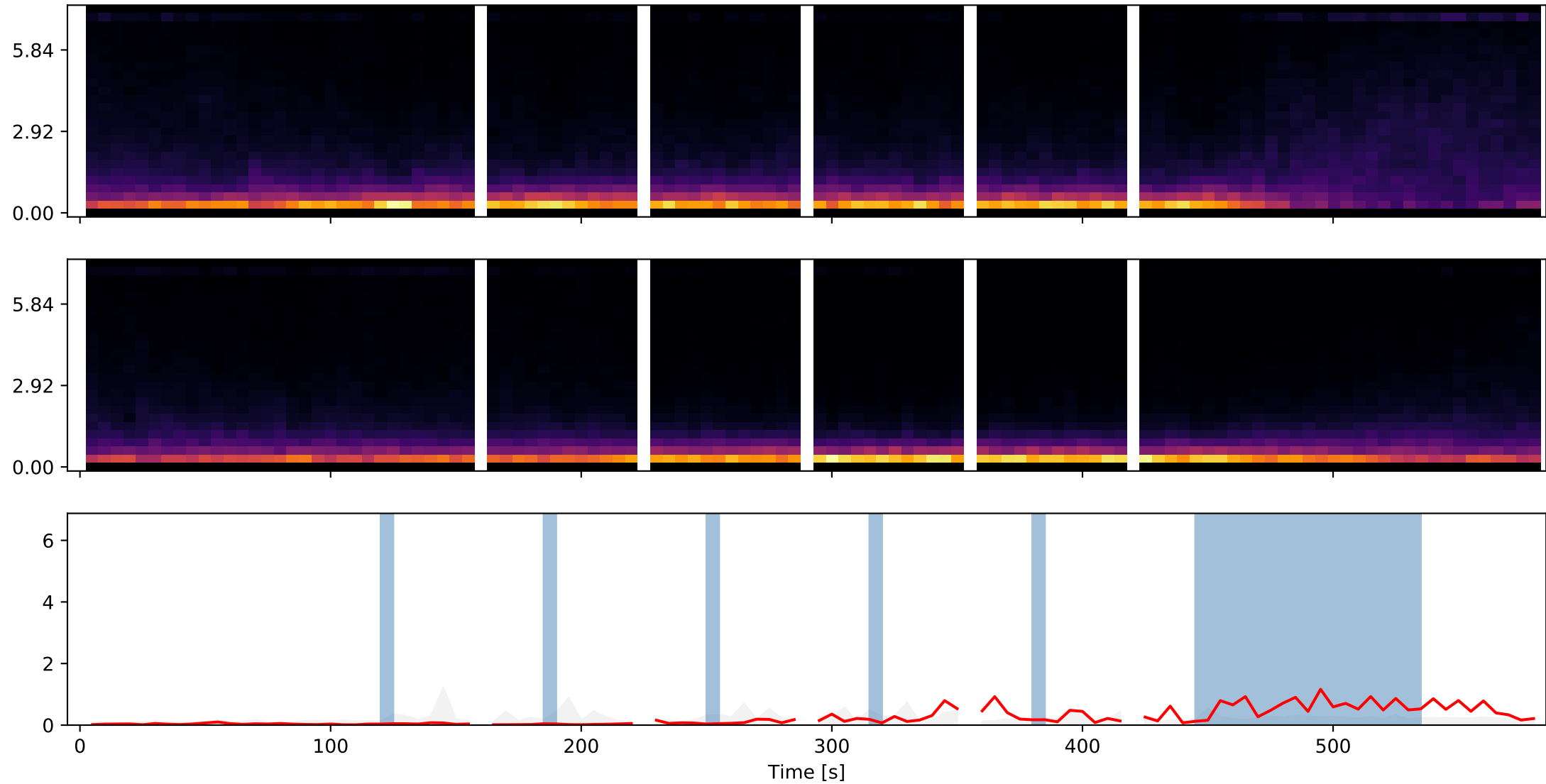
area



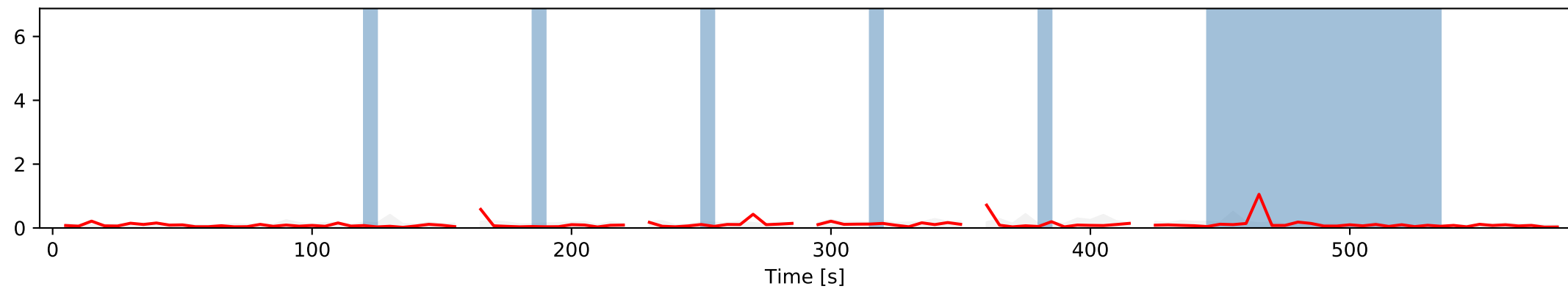
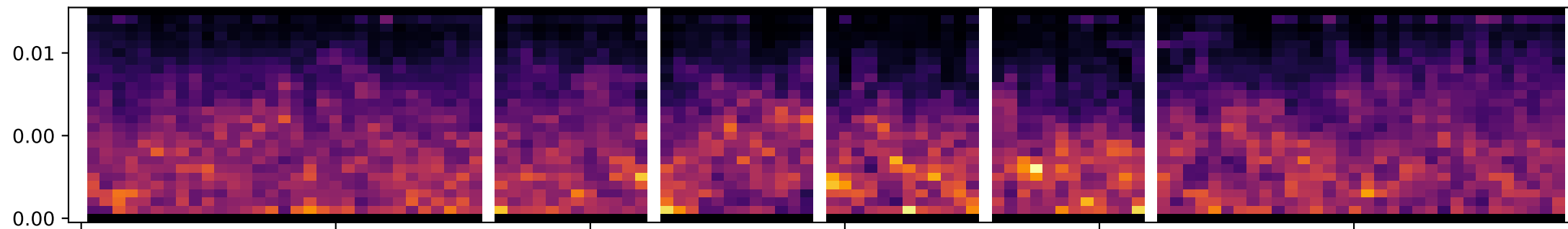
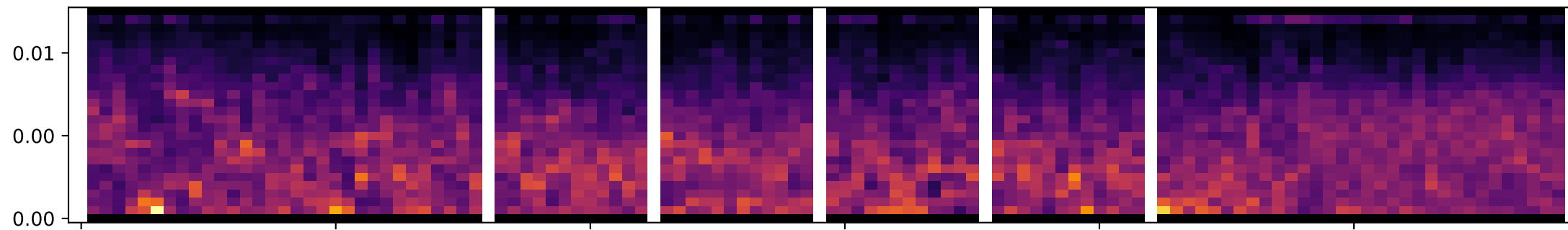
relative_to_body_radial_velocity_head_tip



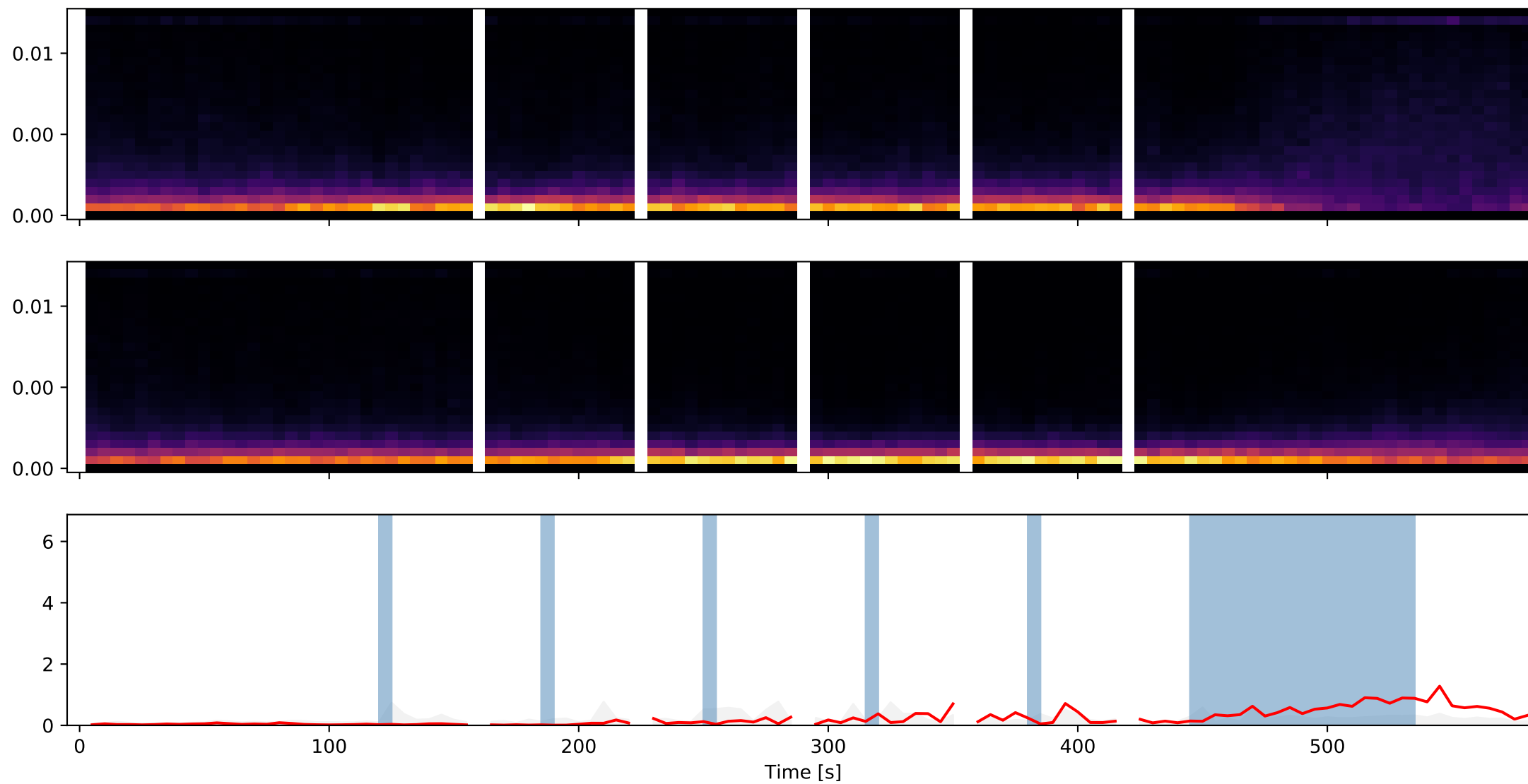
d_eigen_projection_1



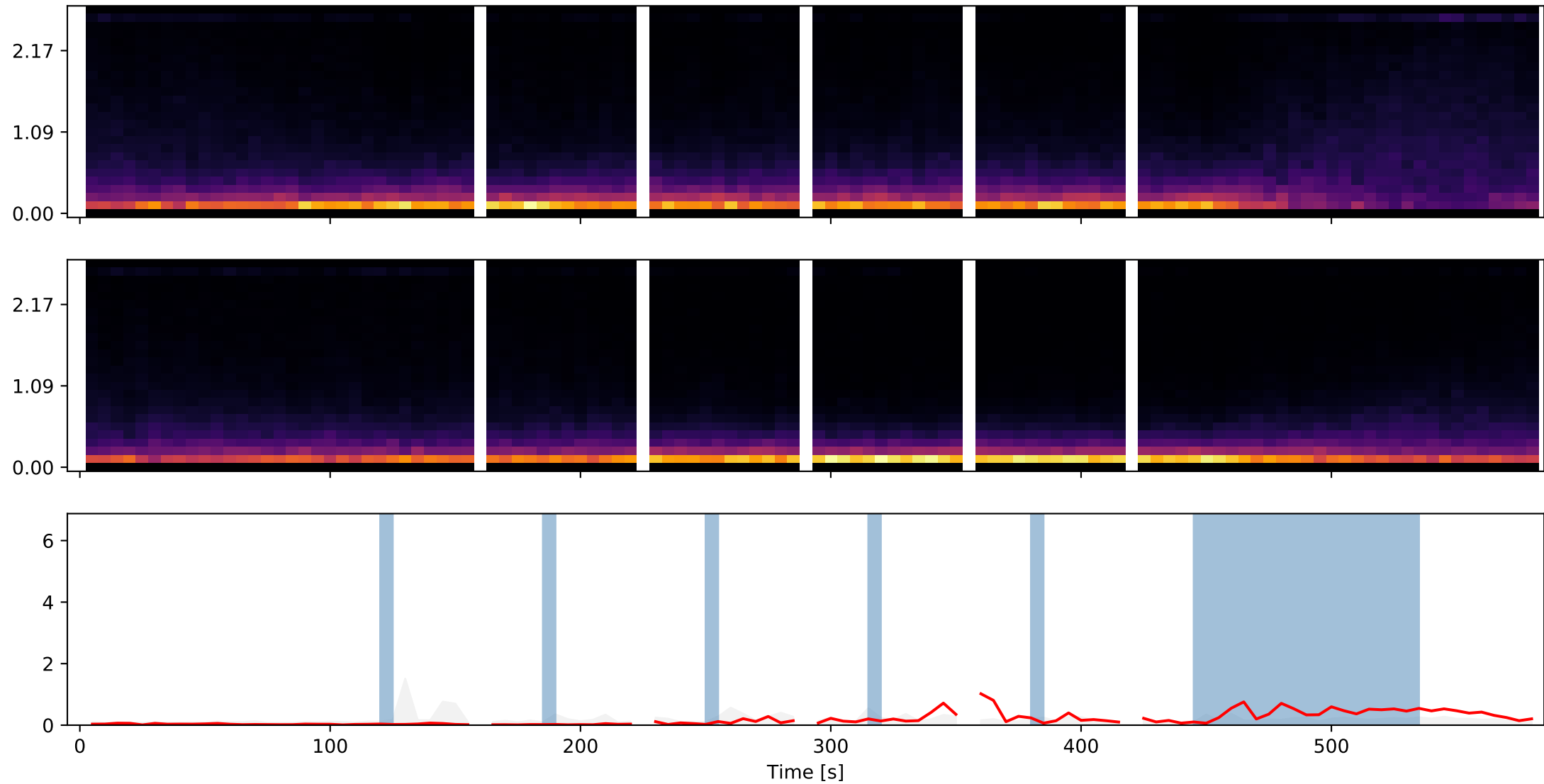
curvature_mean_head



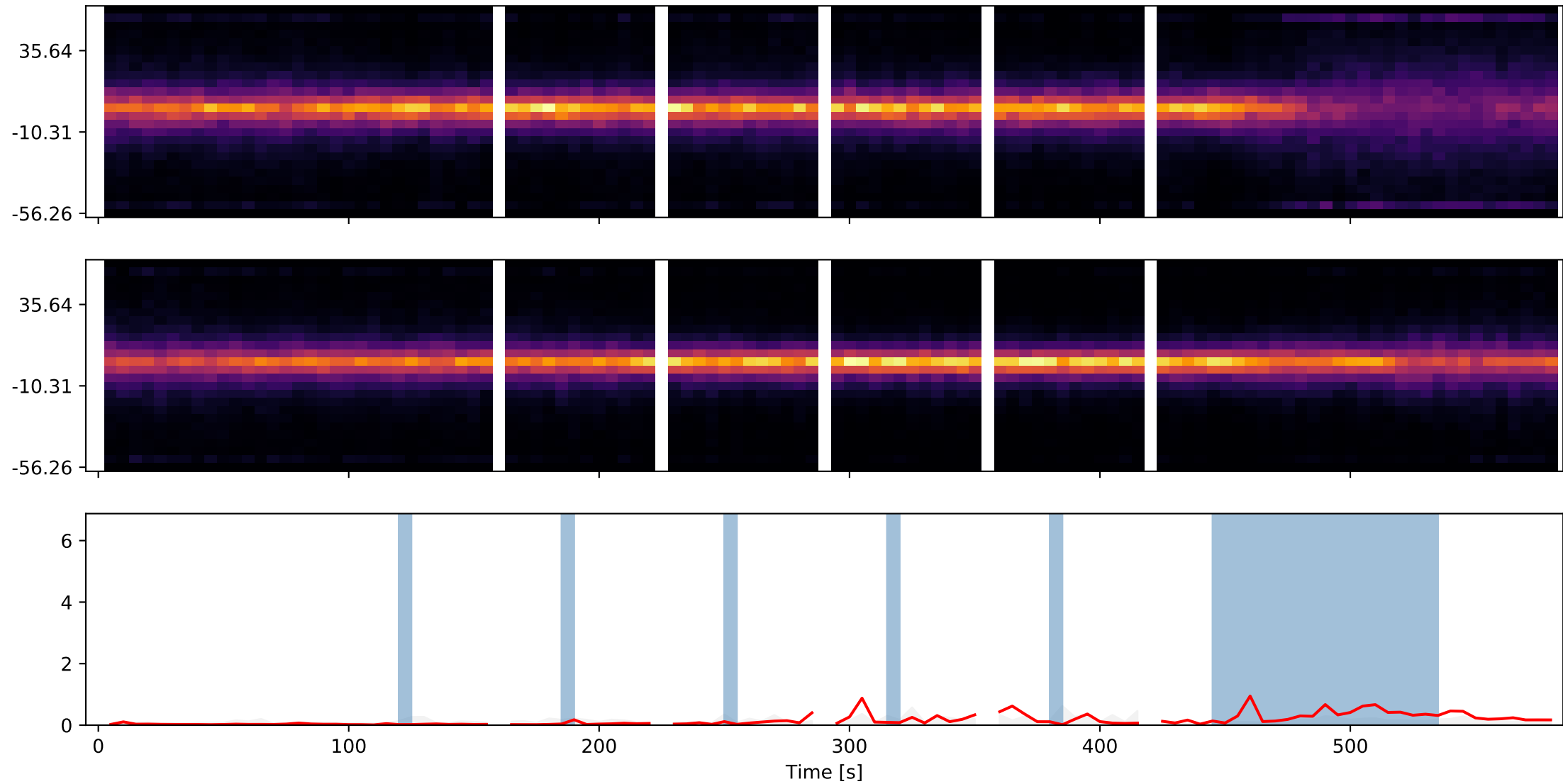
d_curvature_std_midbody



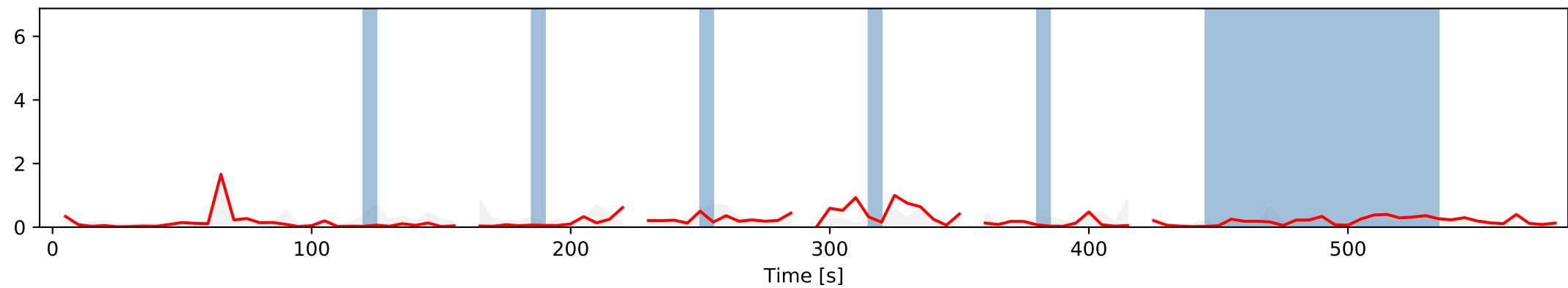
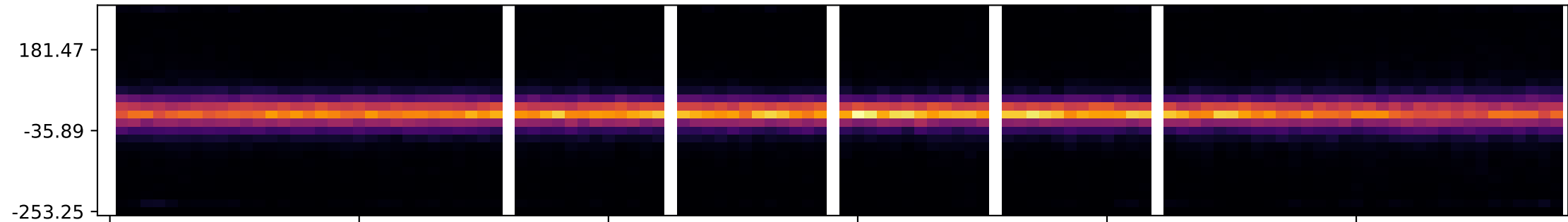
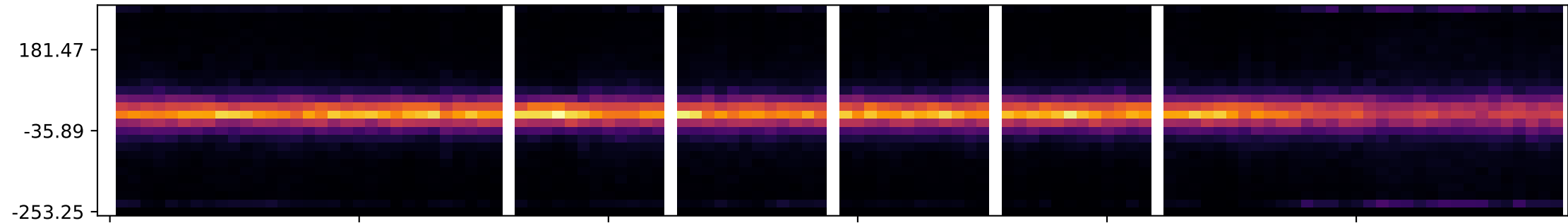
angular_velocity_head_base



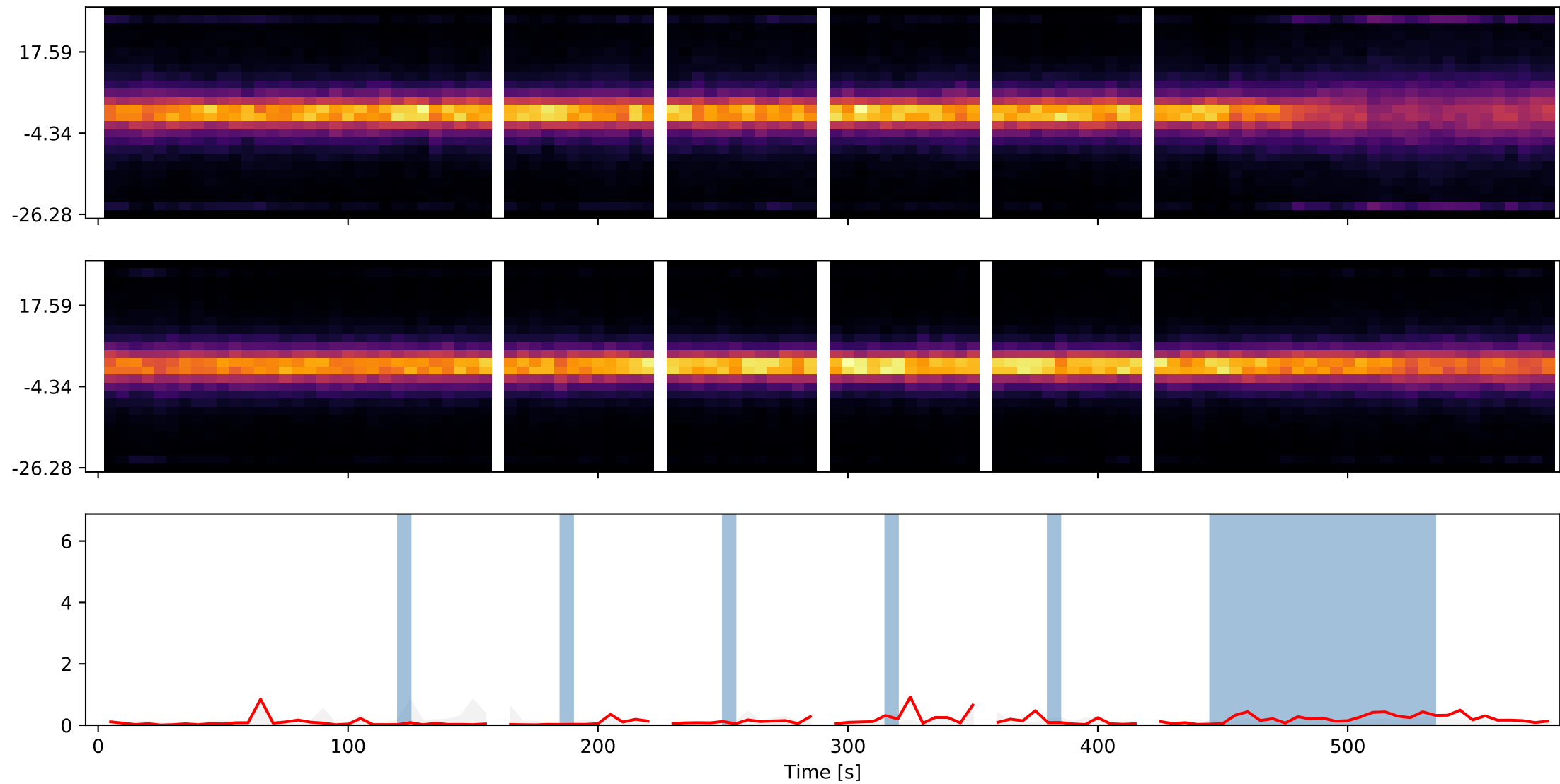
relative_to_body_radial_velocity_neck



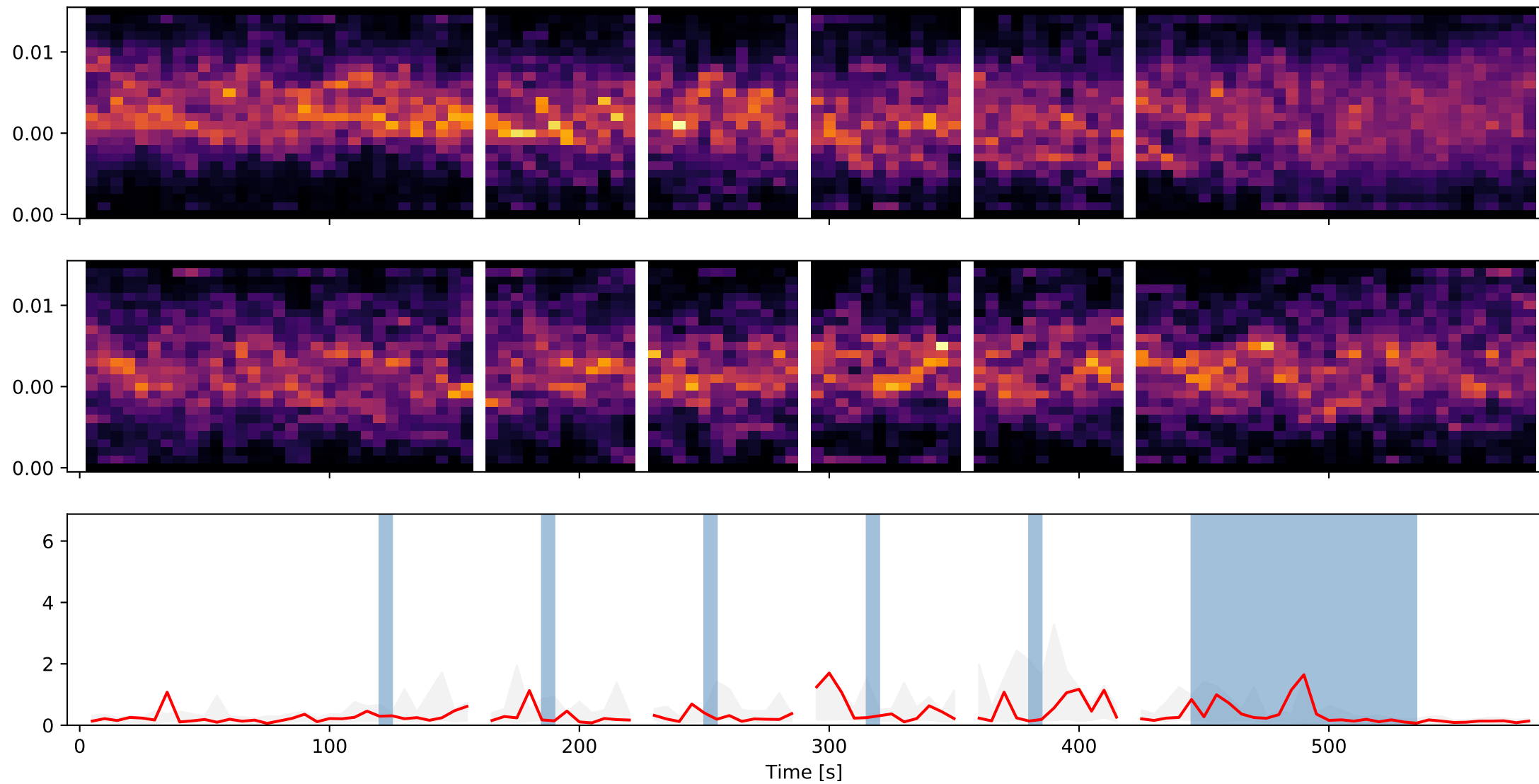
d_length



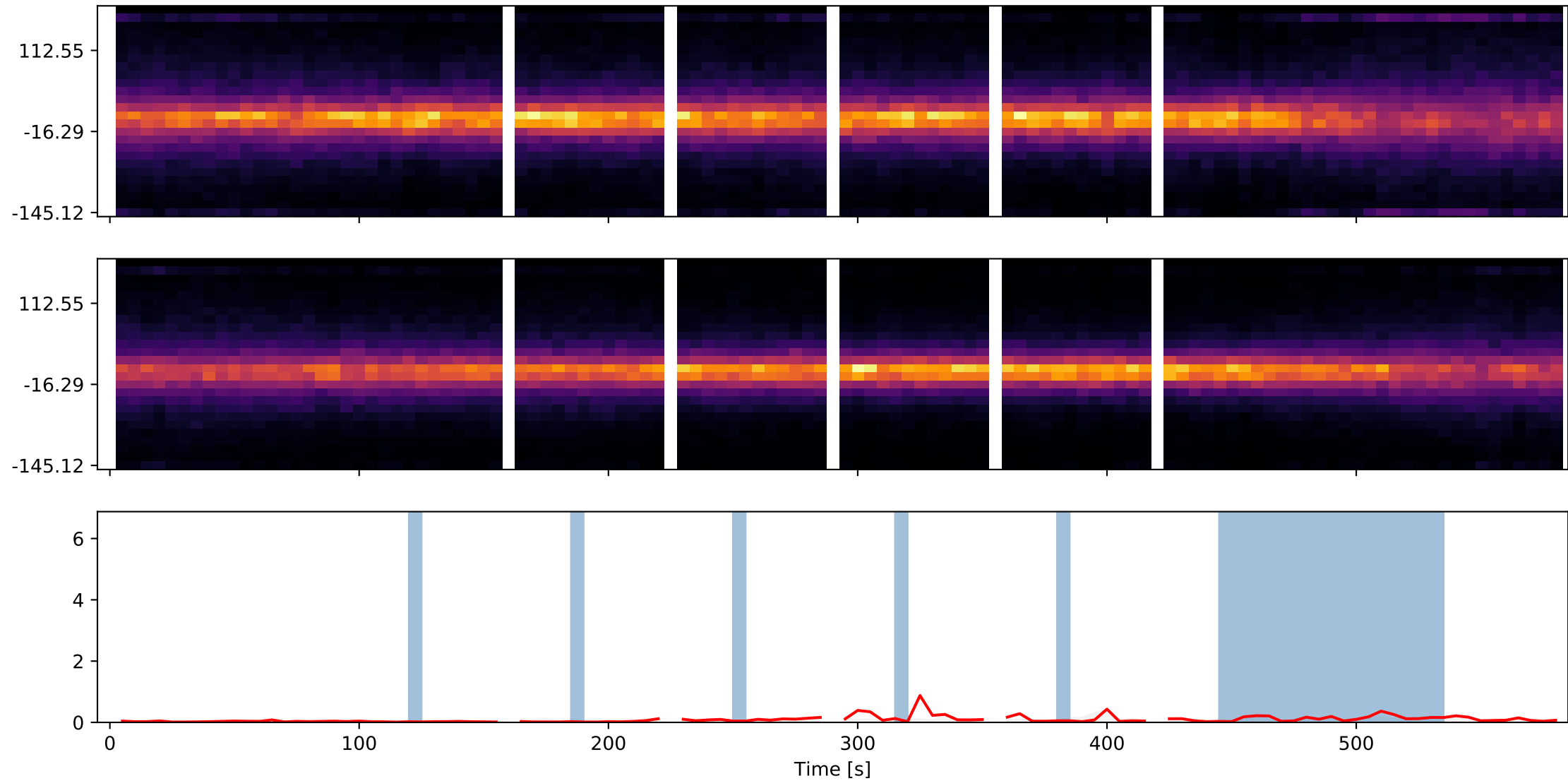
relative_to_tail_base_radial_velocity_tail_tip



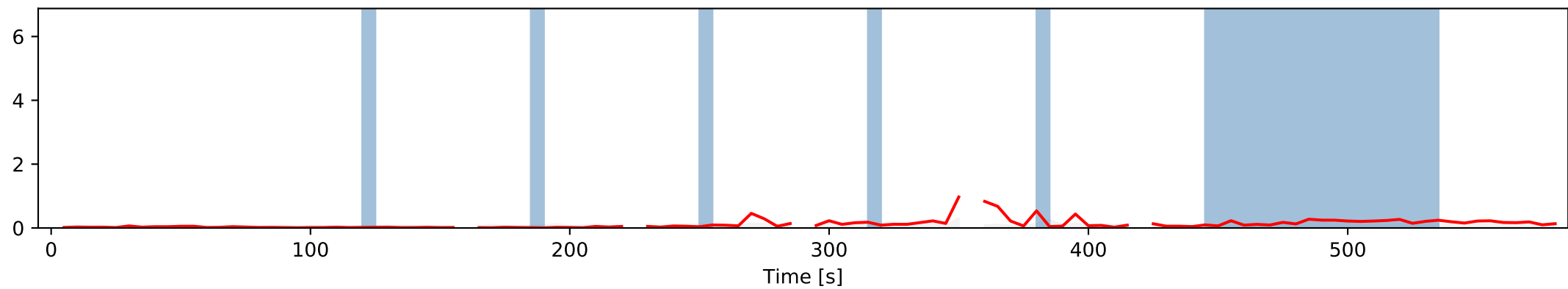
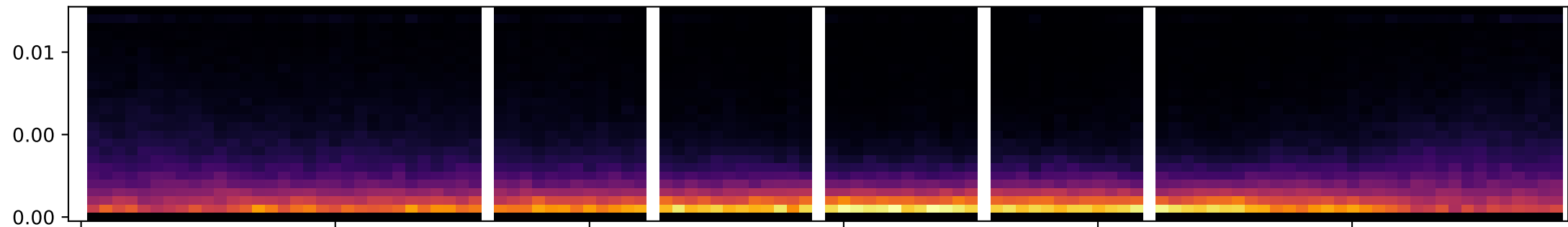
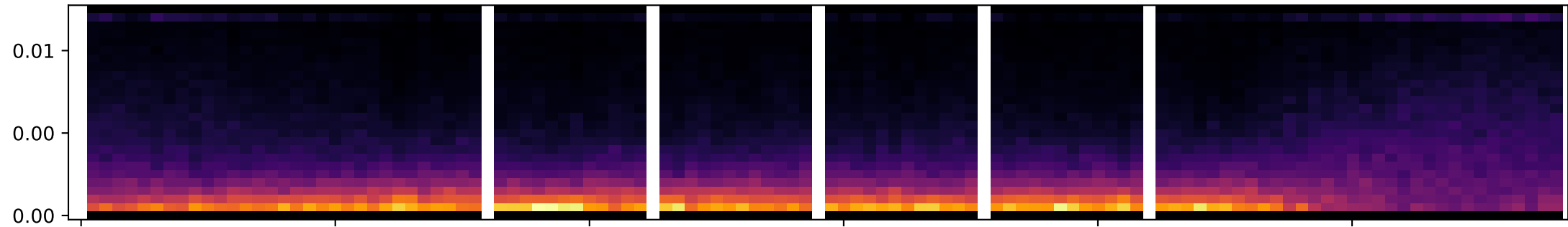
curvature_std_midbody



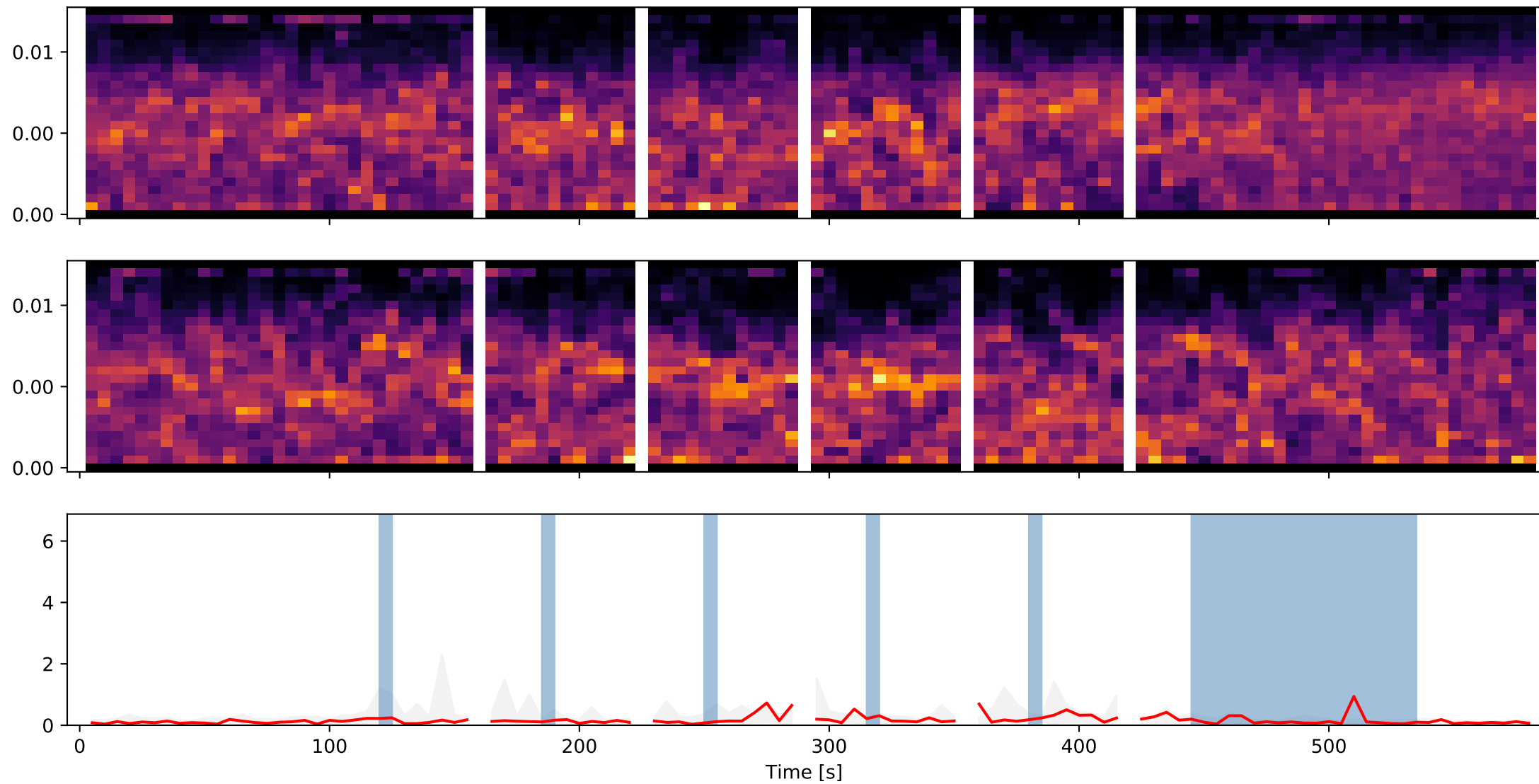
d_relative_to_head_base_radial_velocity_head_tip



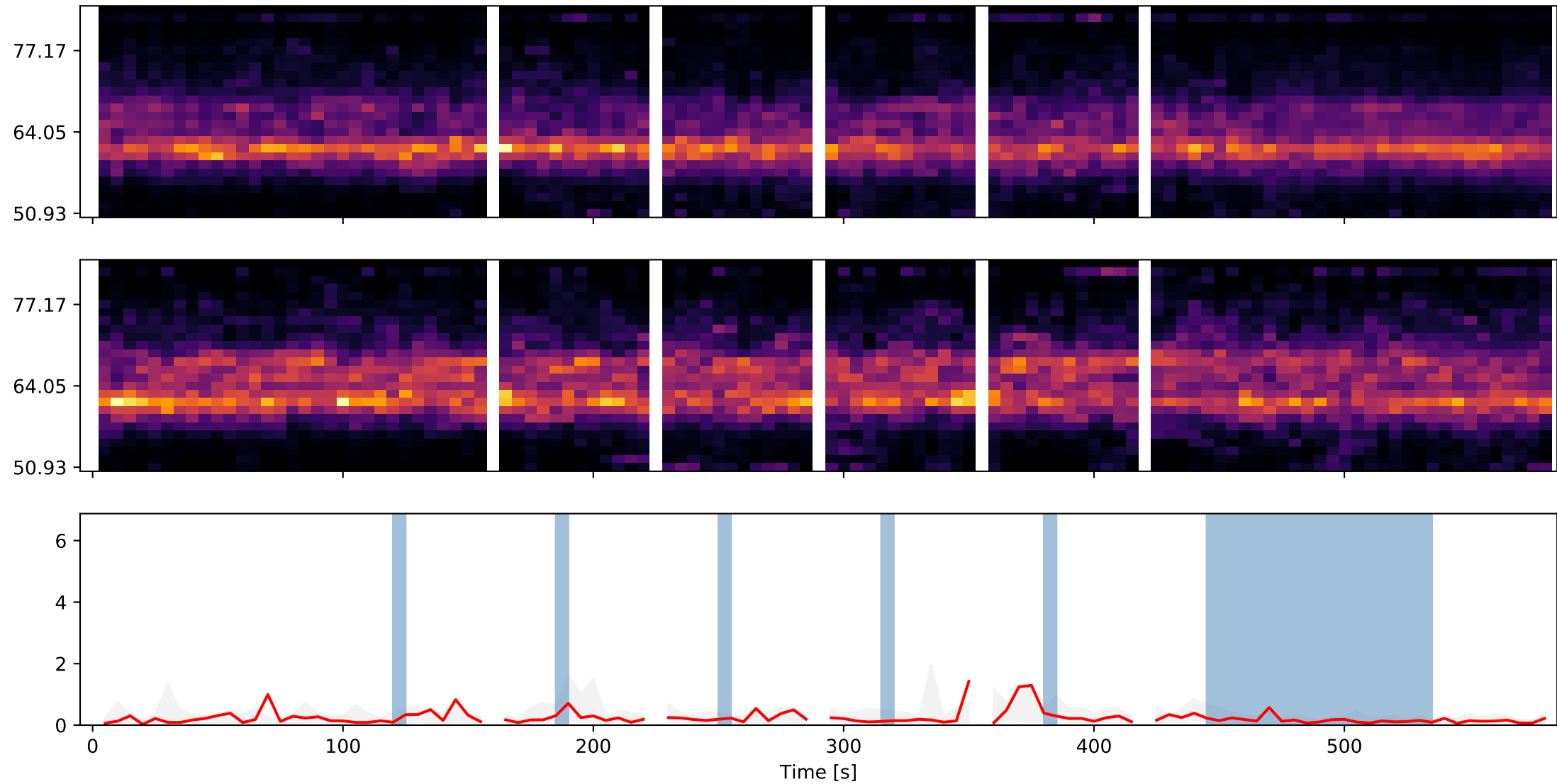
d_curvature_std_neck



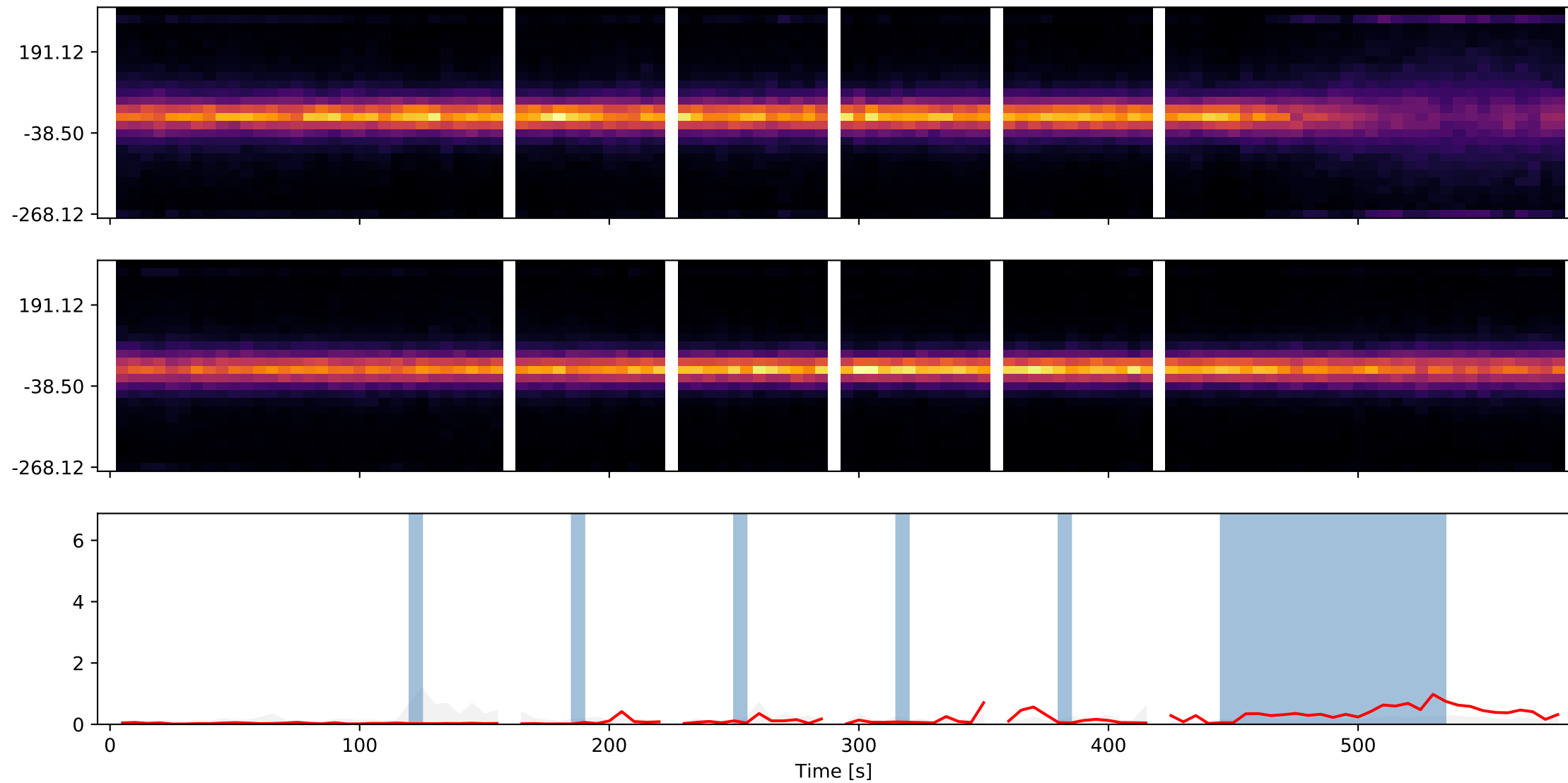
curvature_midbody



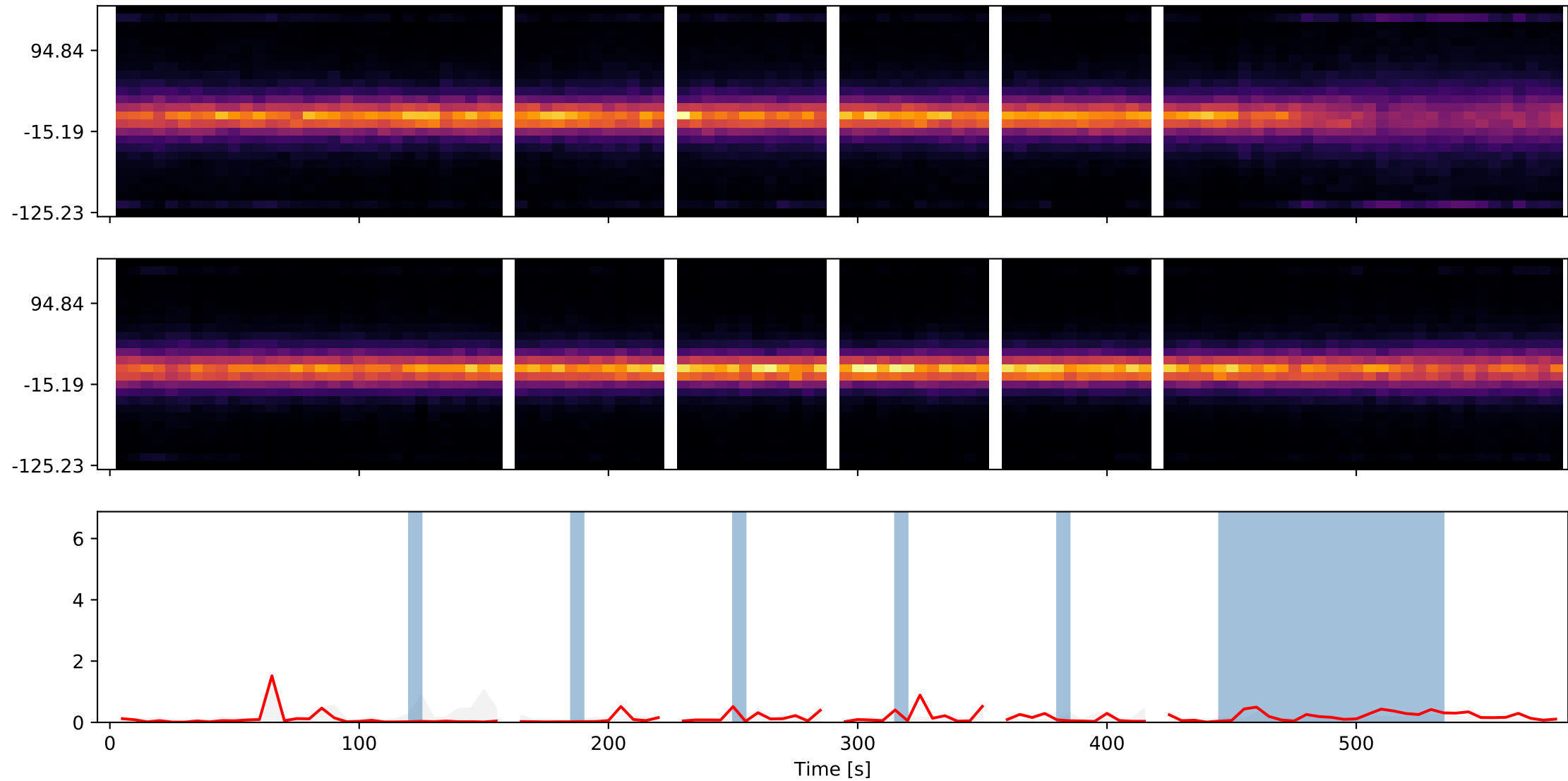
width_tail_base



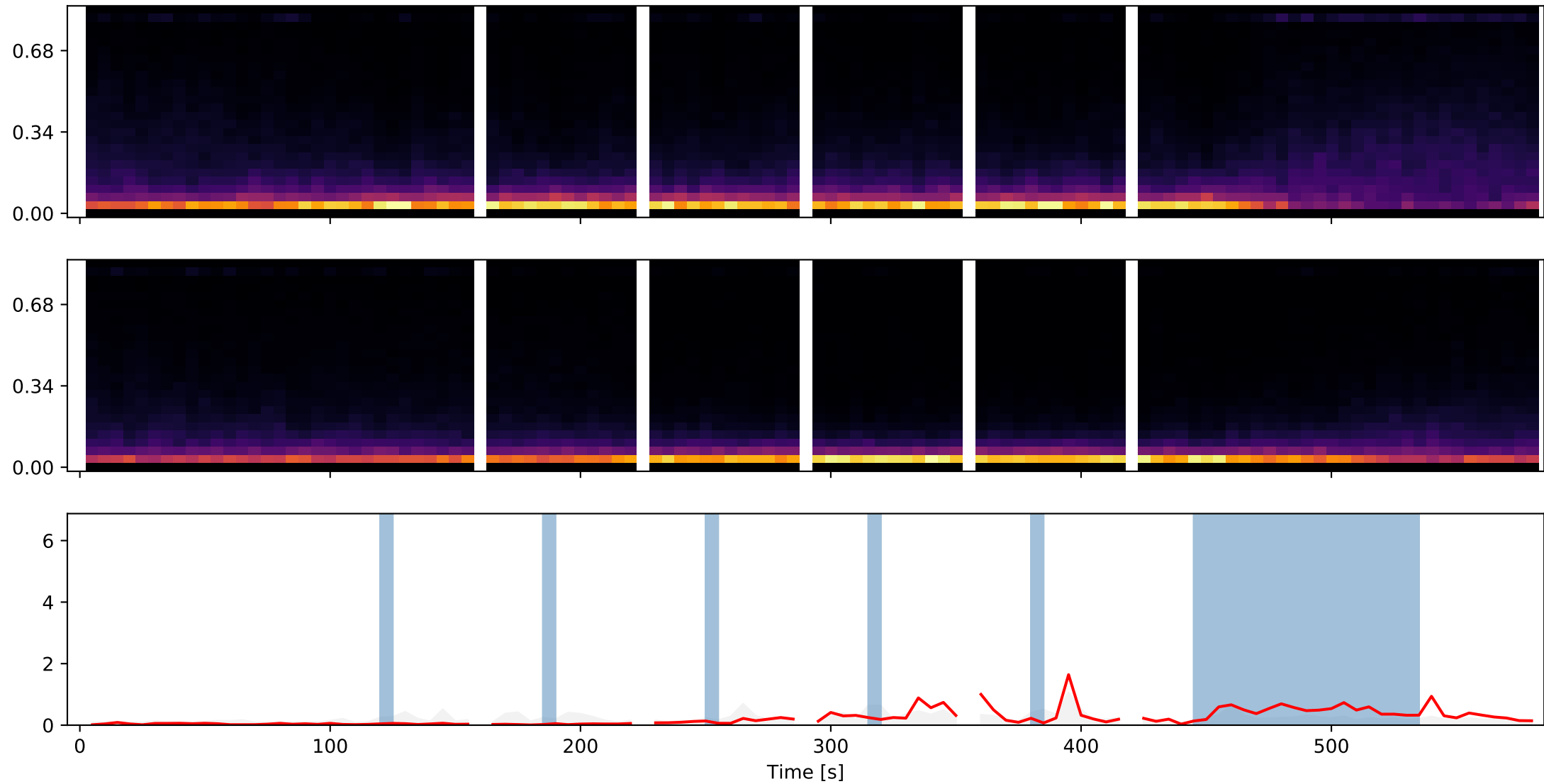
d_relative_to_hips_radial_velocity_tail_tip



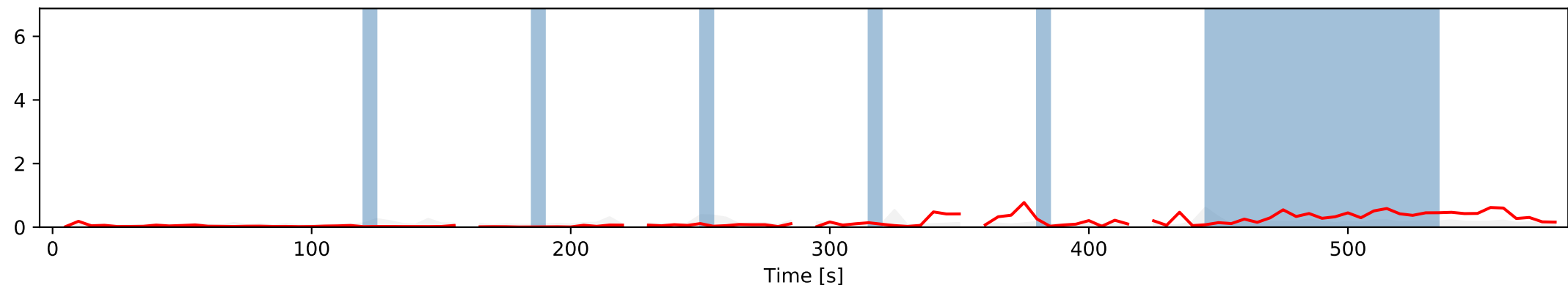
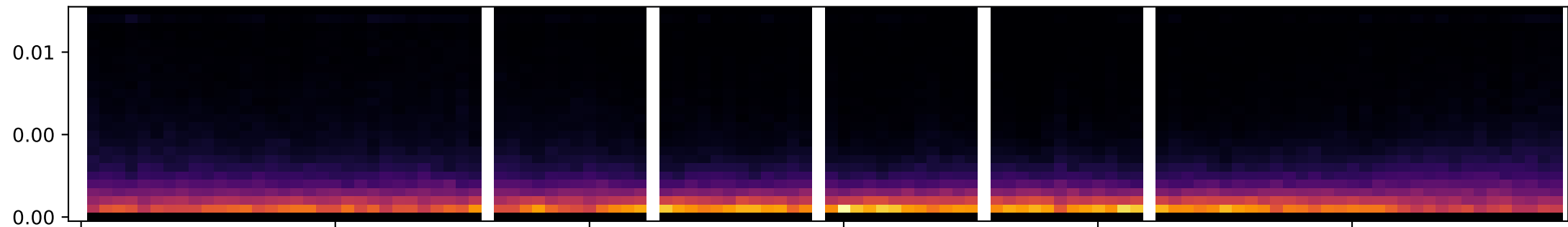
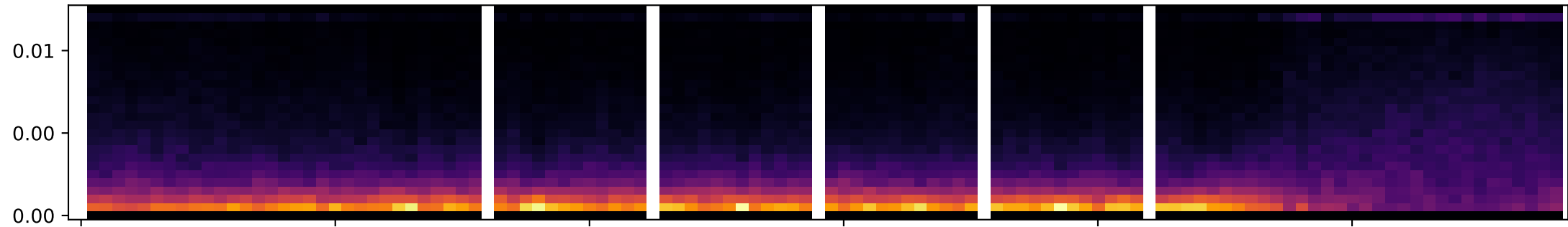
d_relative_to_tail_base_radial_velocity_tail_tip



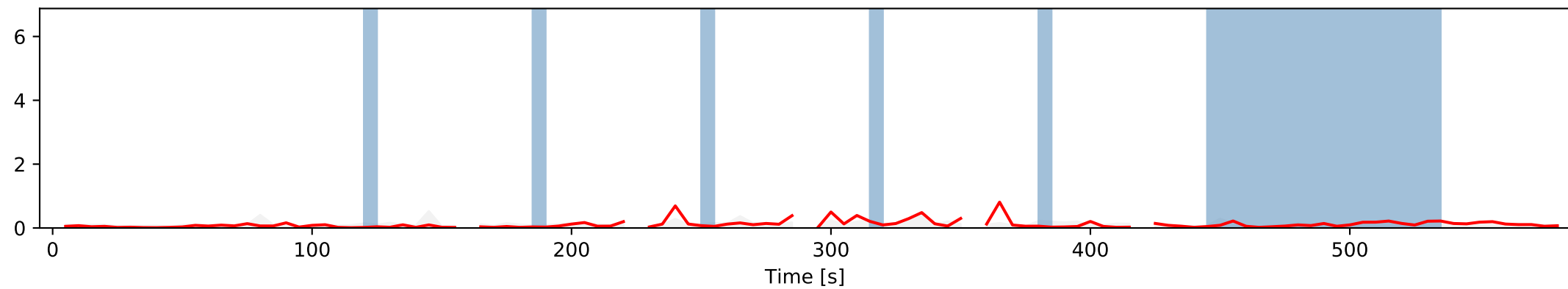
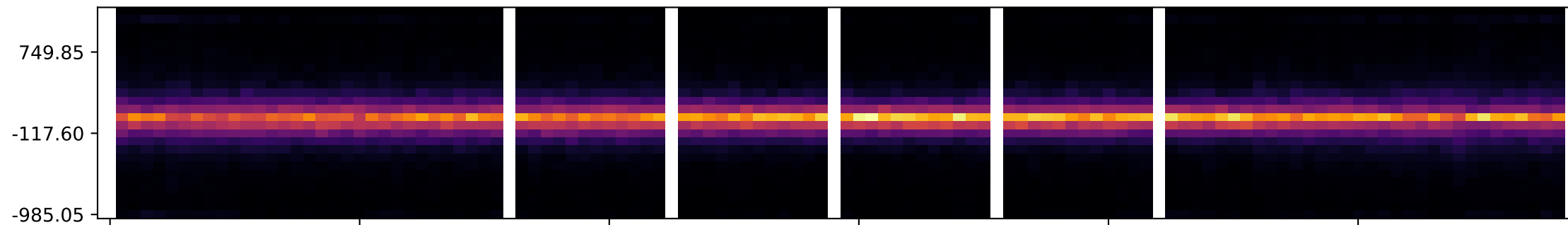
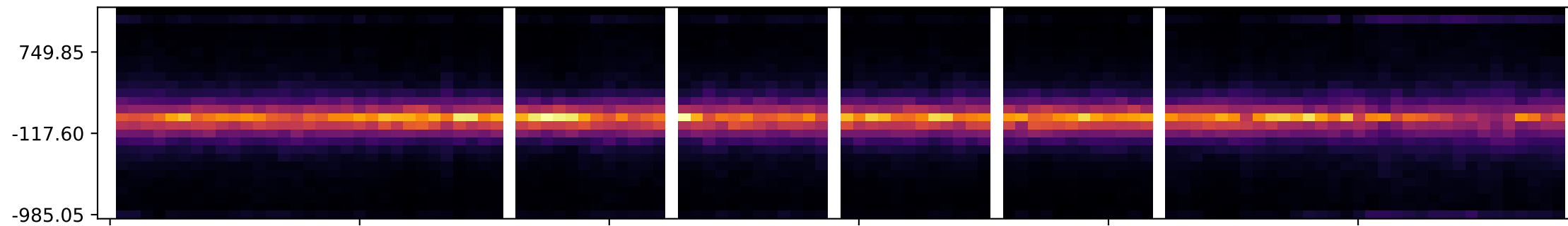
relative_to_body_angular_velocity_head_tip



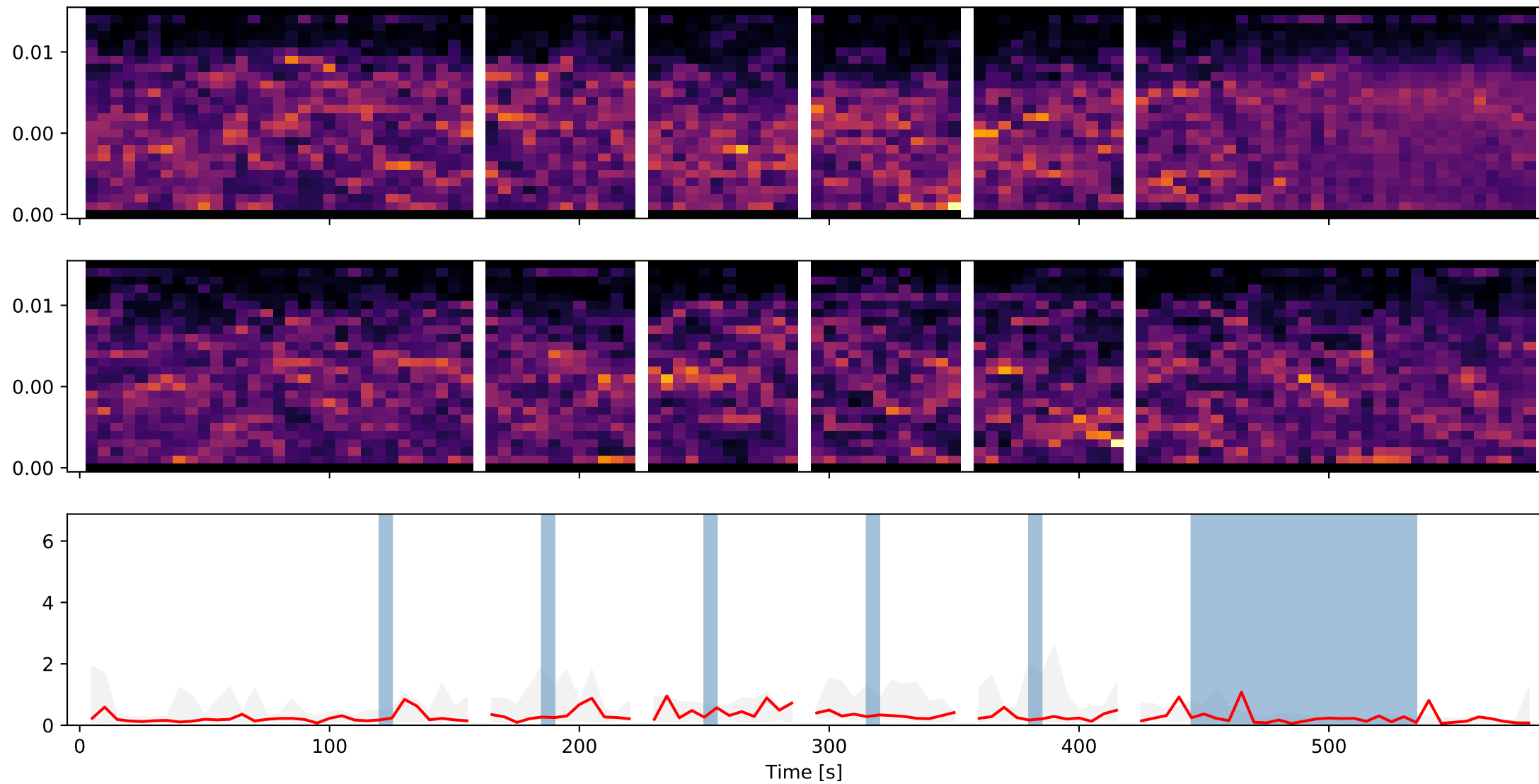
d_curvature_std_hips



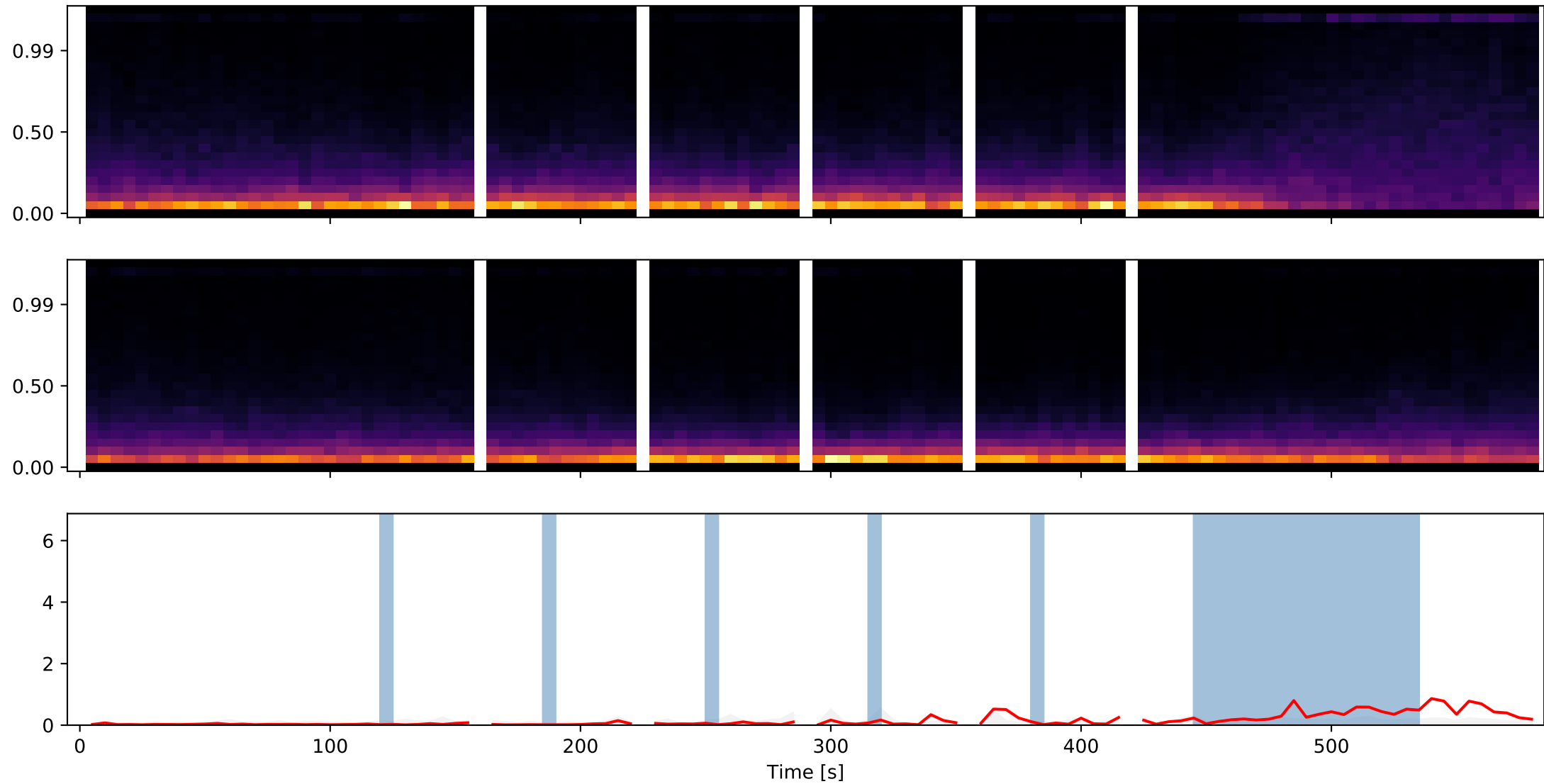
d_speed_head_tip



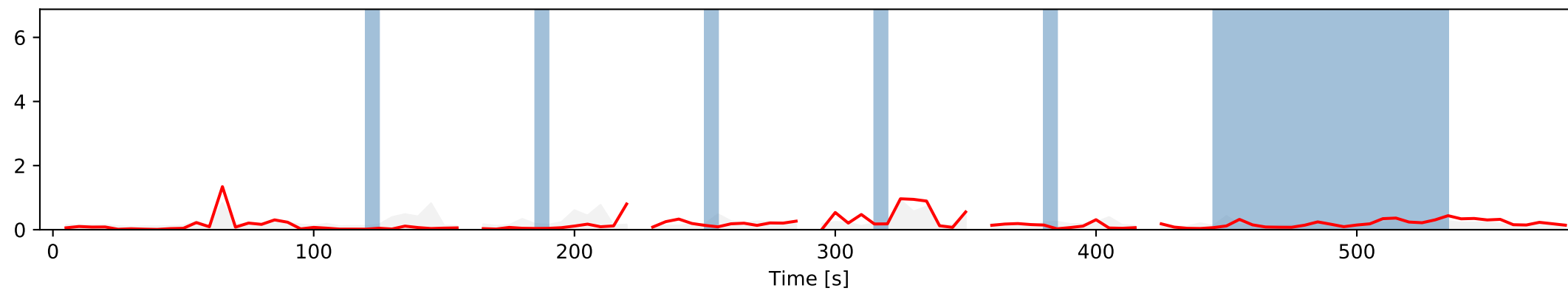
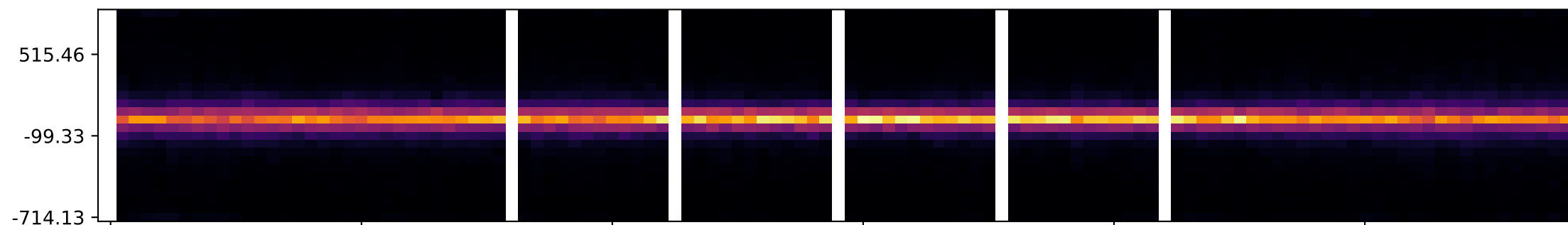
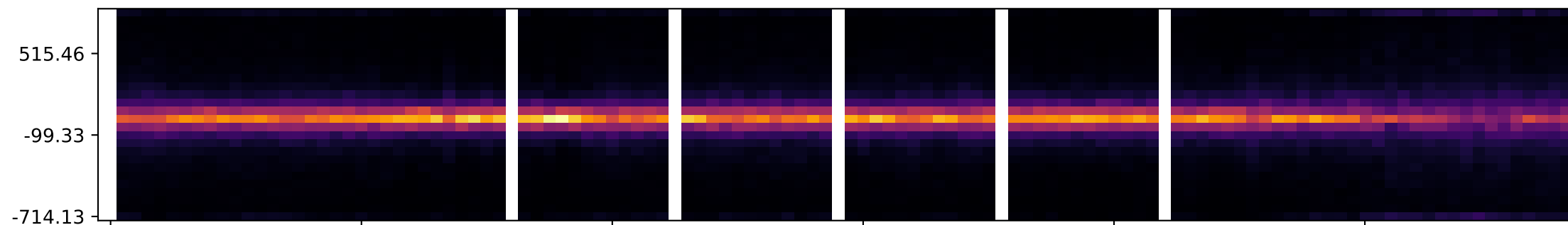
curvature_mean_hips



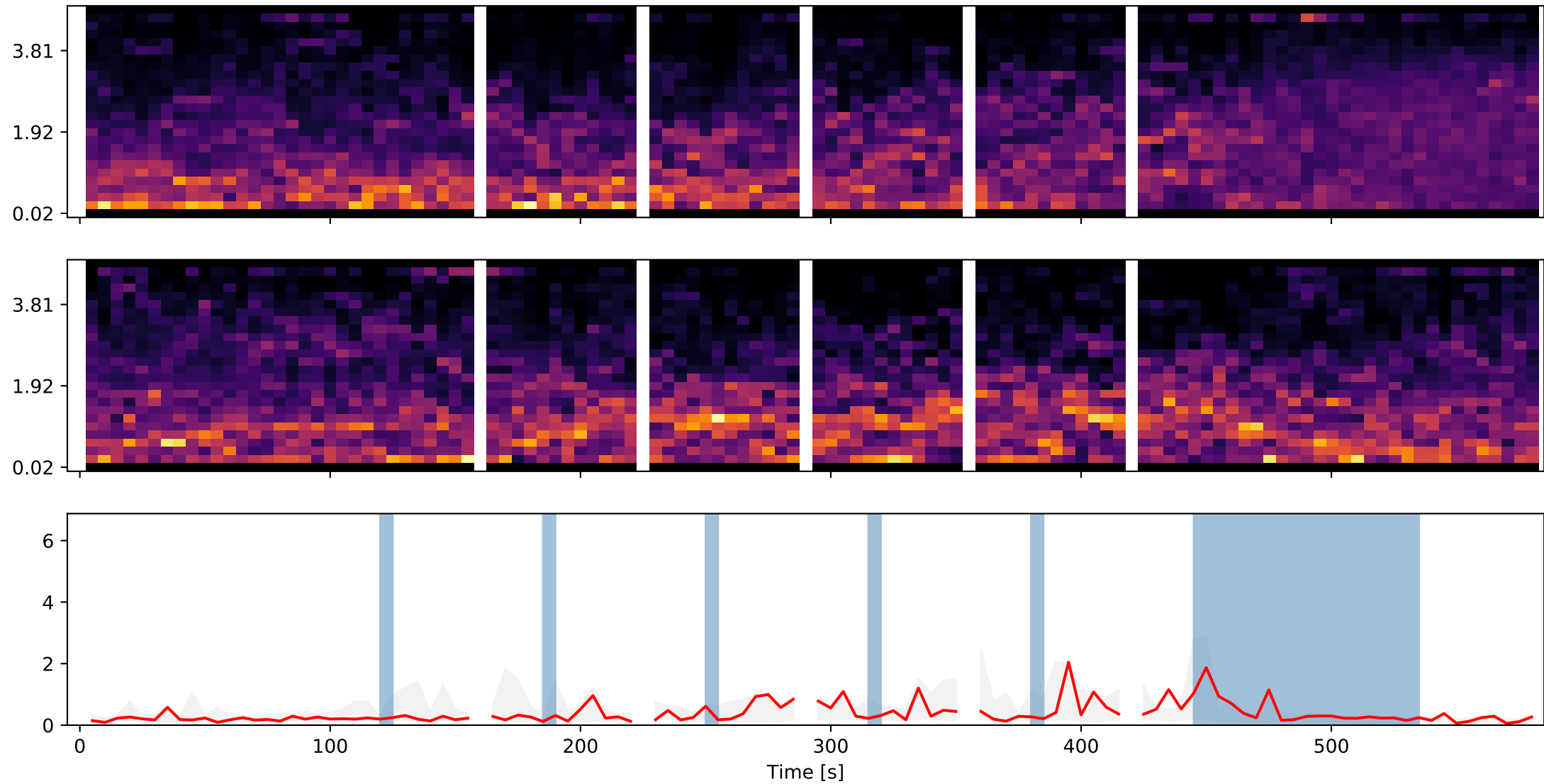
relative_to_tail_base_angular_velocity_tail_tip



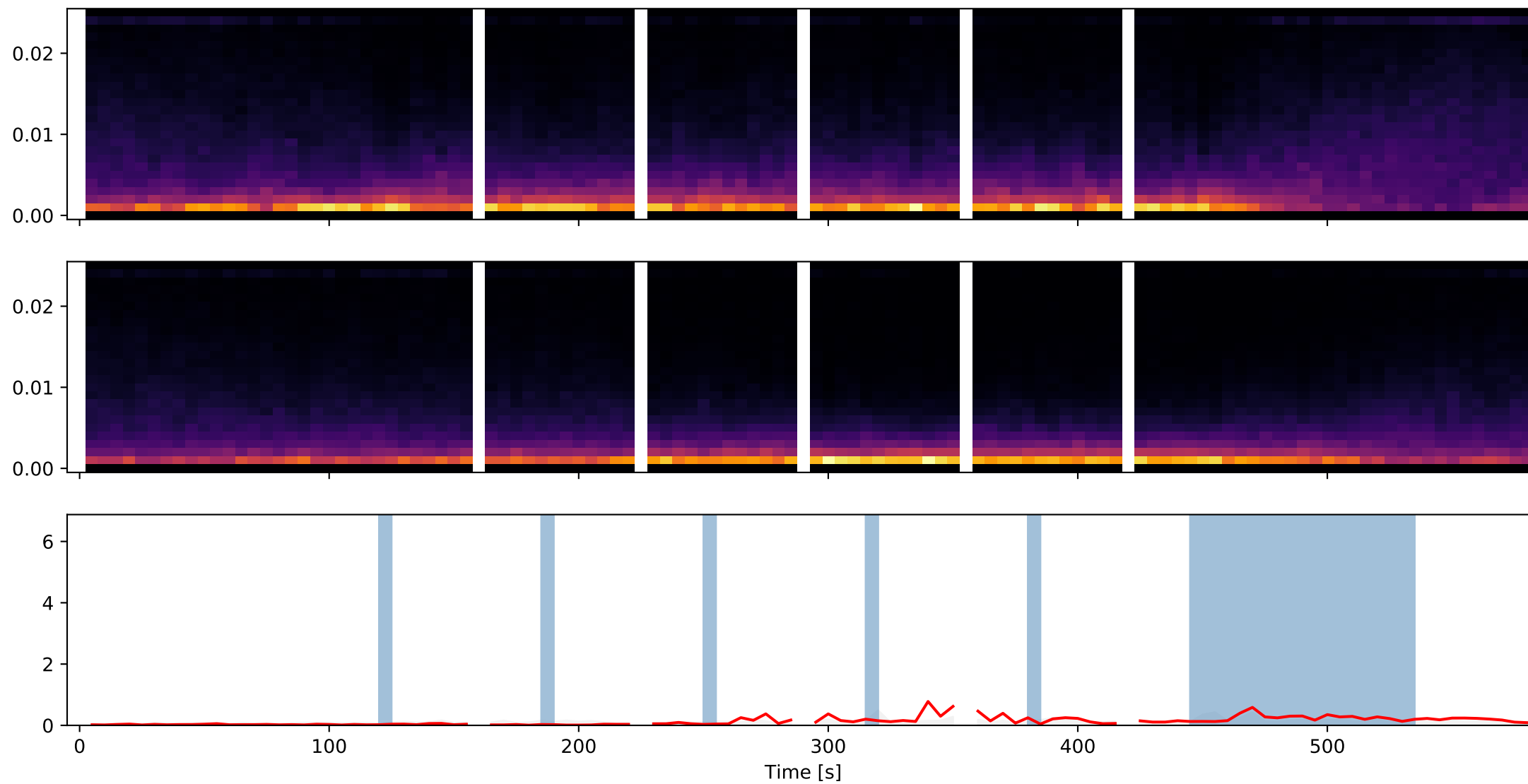
d_speed



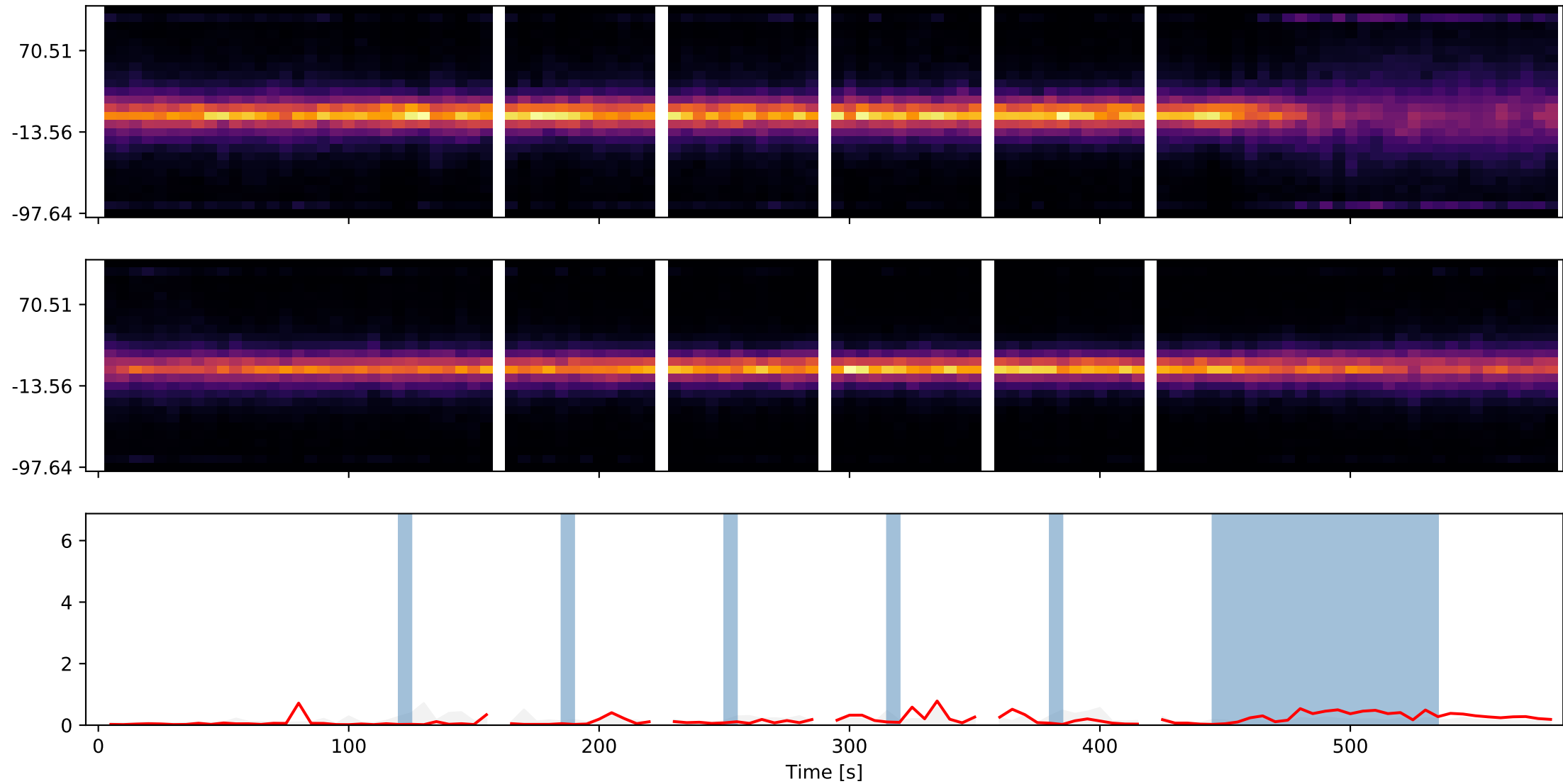
eigen_projection_3



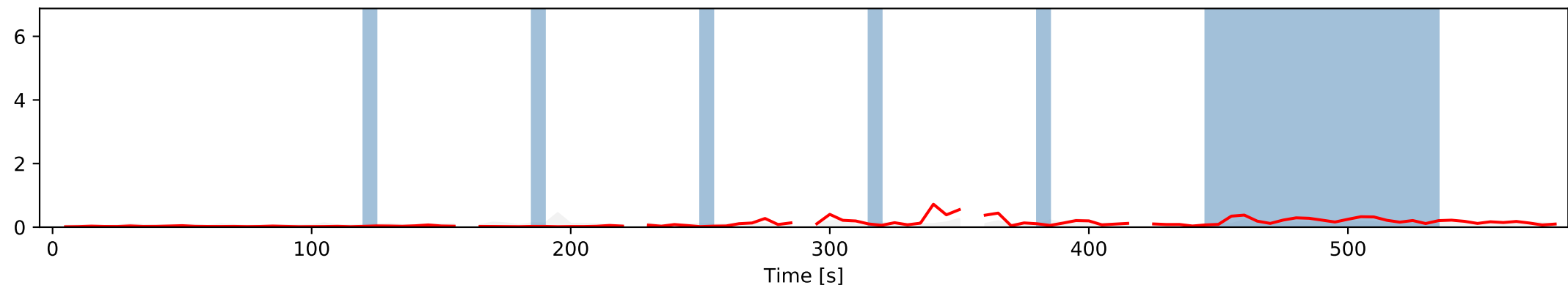
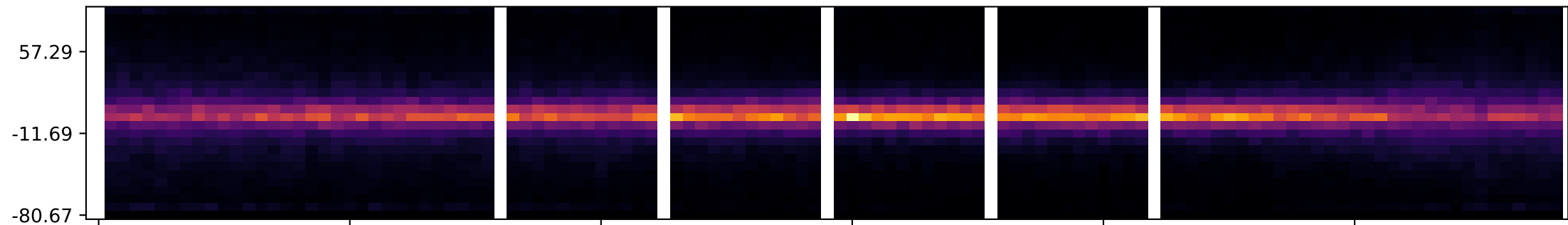
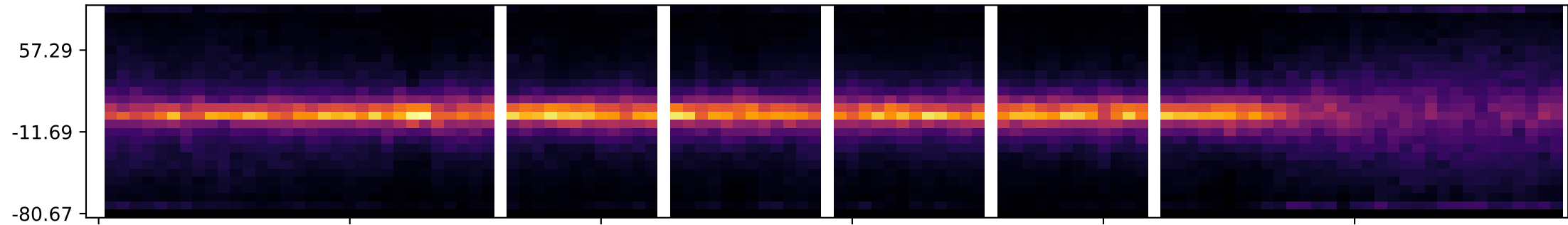
d_curvature_mean_head



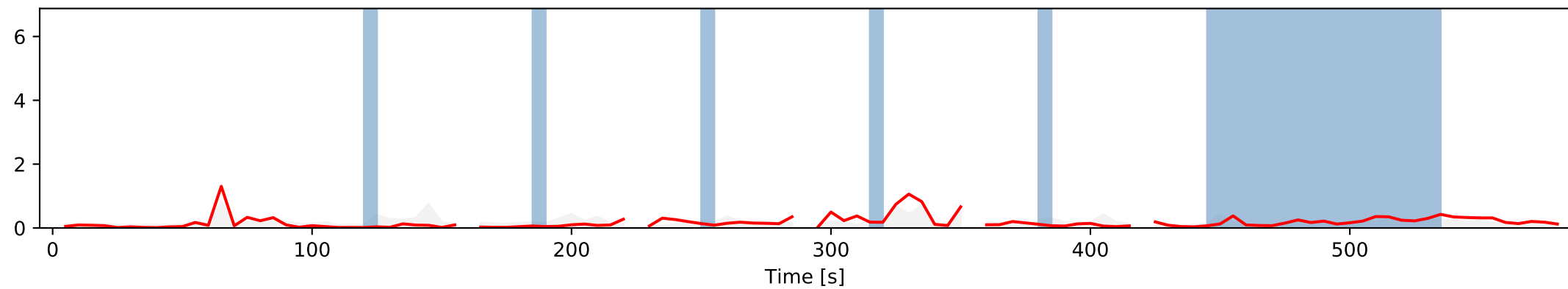
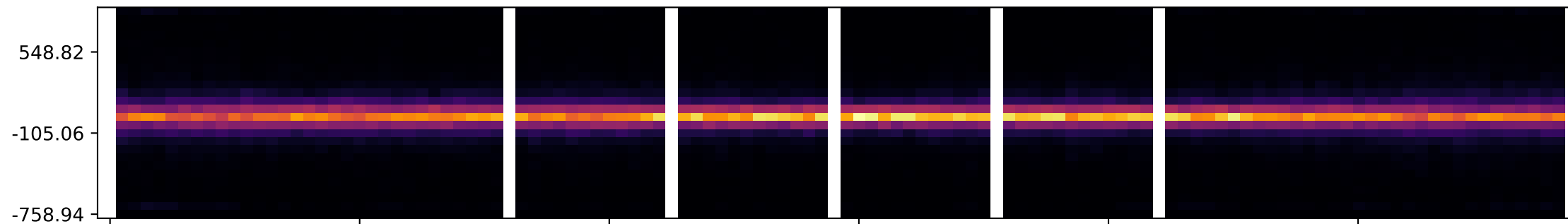
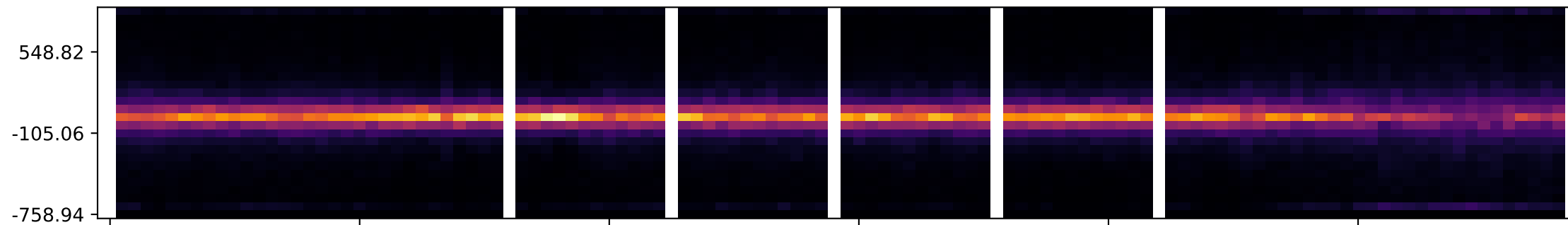
relative_to_body_radial_velocity_tail_tip



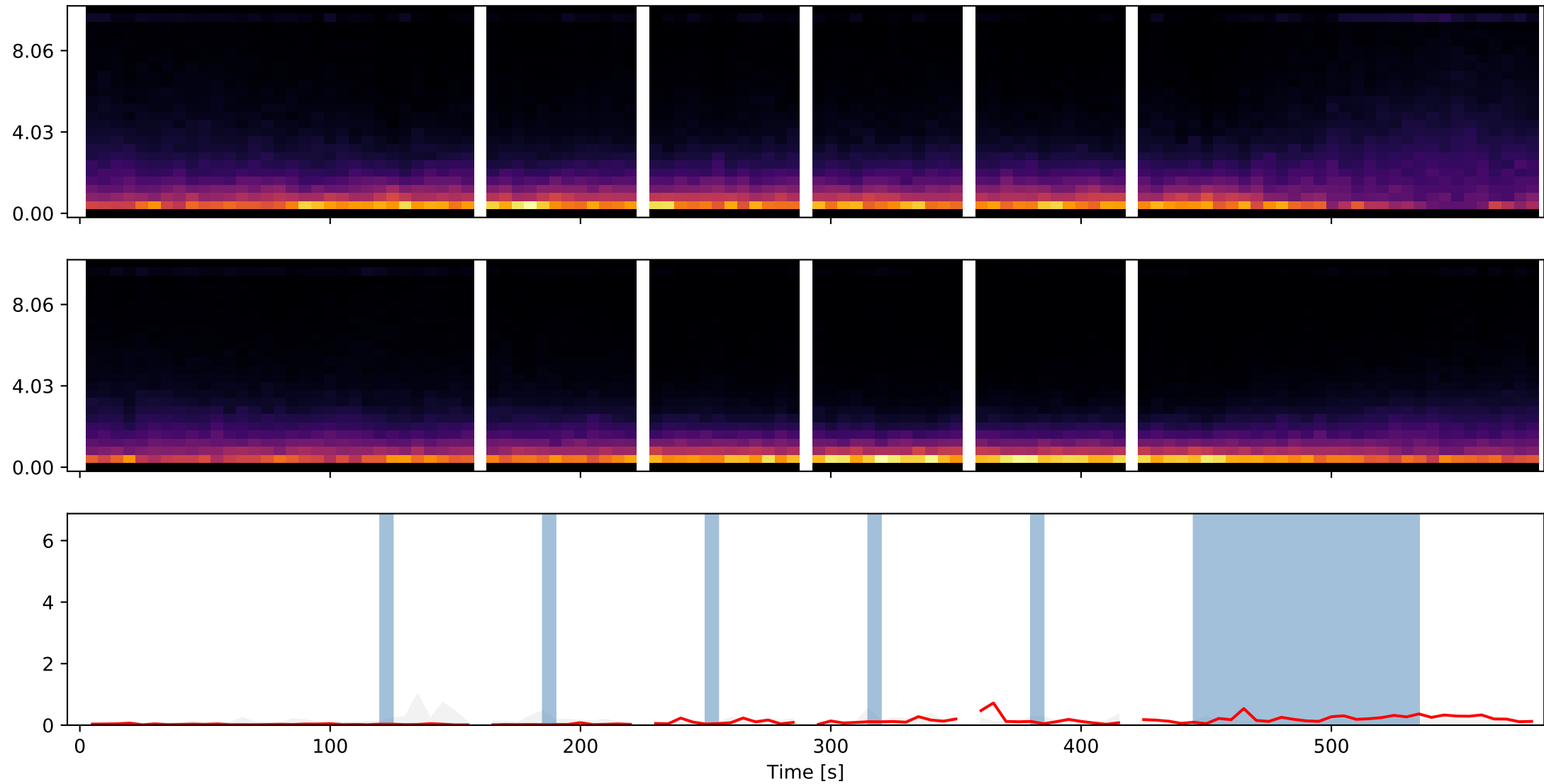
relative_to_neck_radial_velocity_head_tip



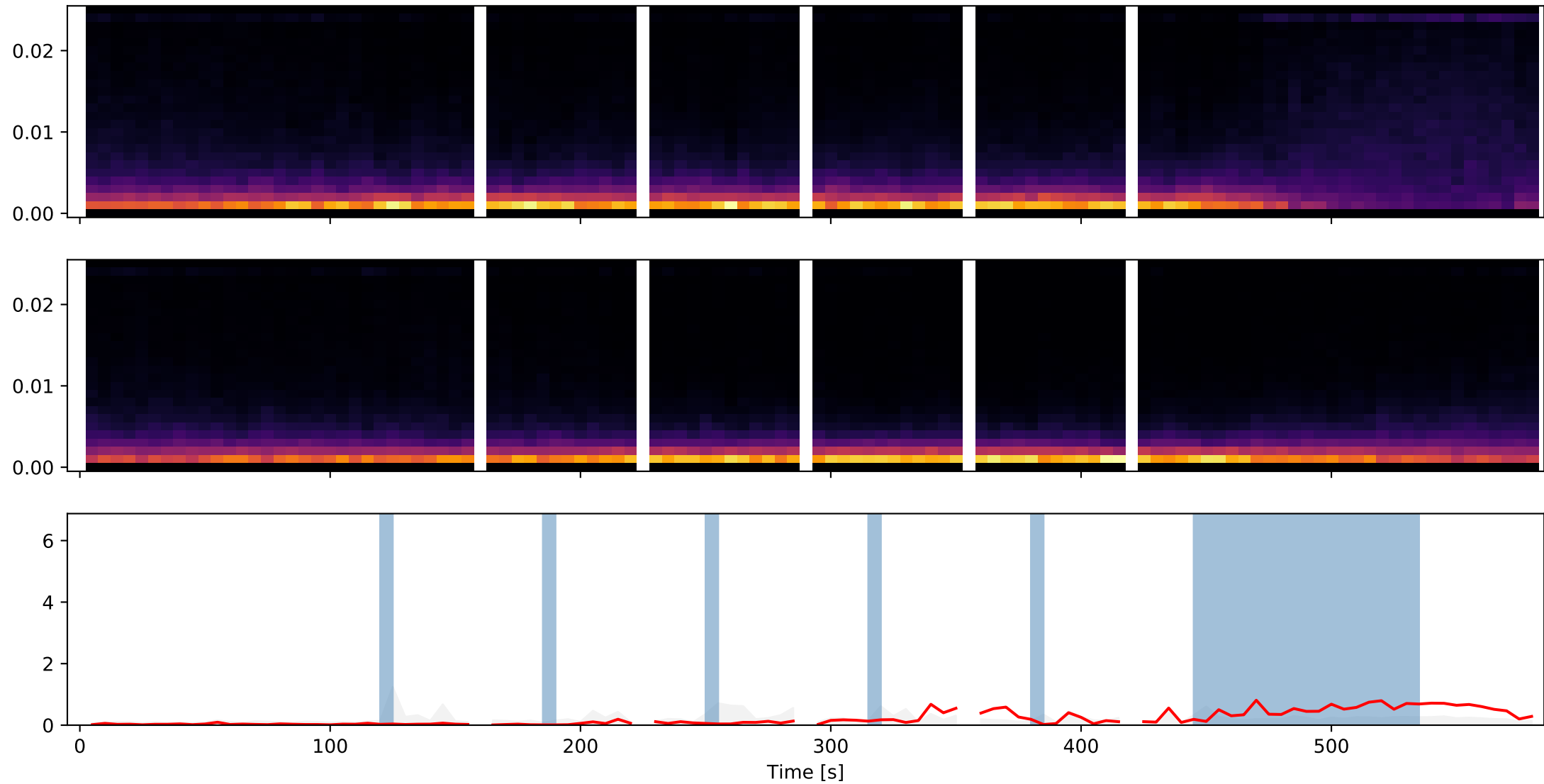
d_speed_midbody



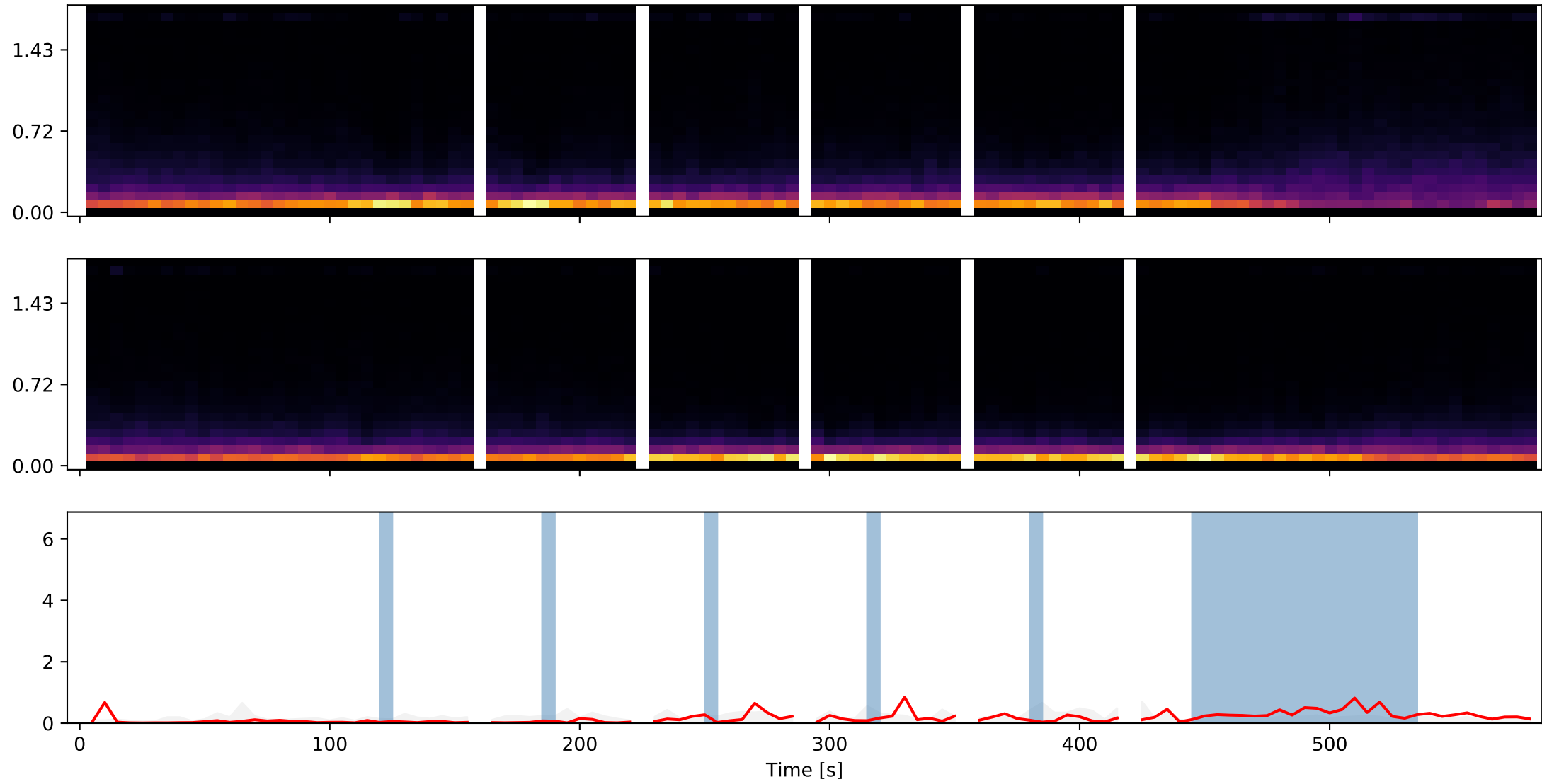
d_angular_velocity_head_base



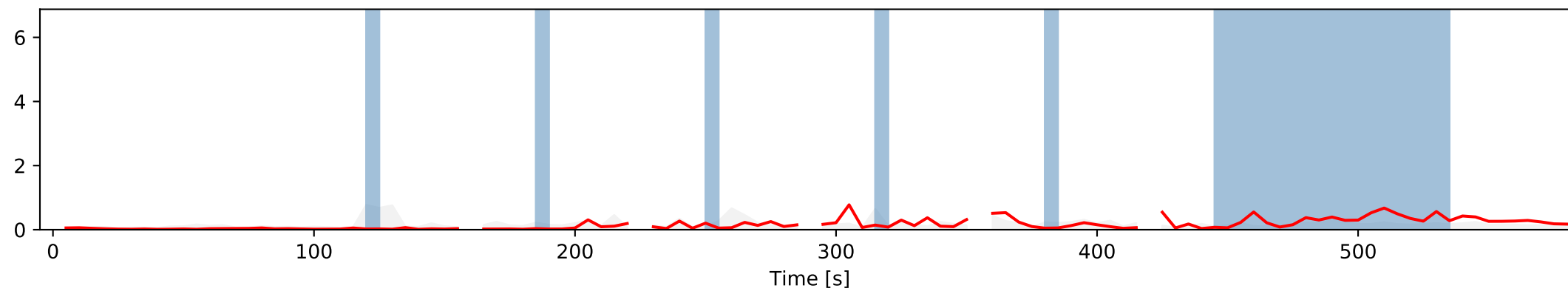
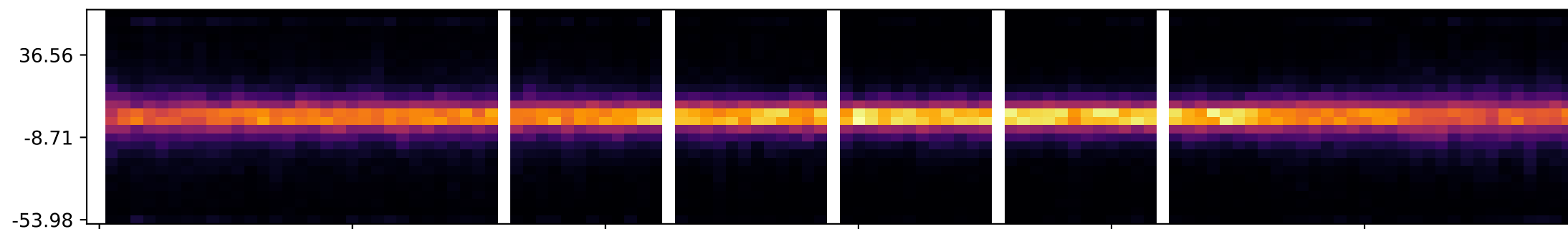
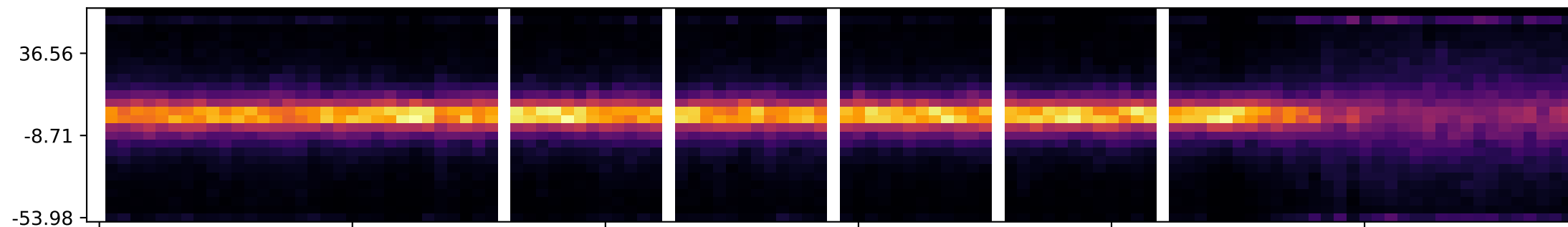
d_curvature_hips



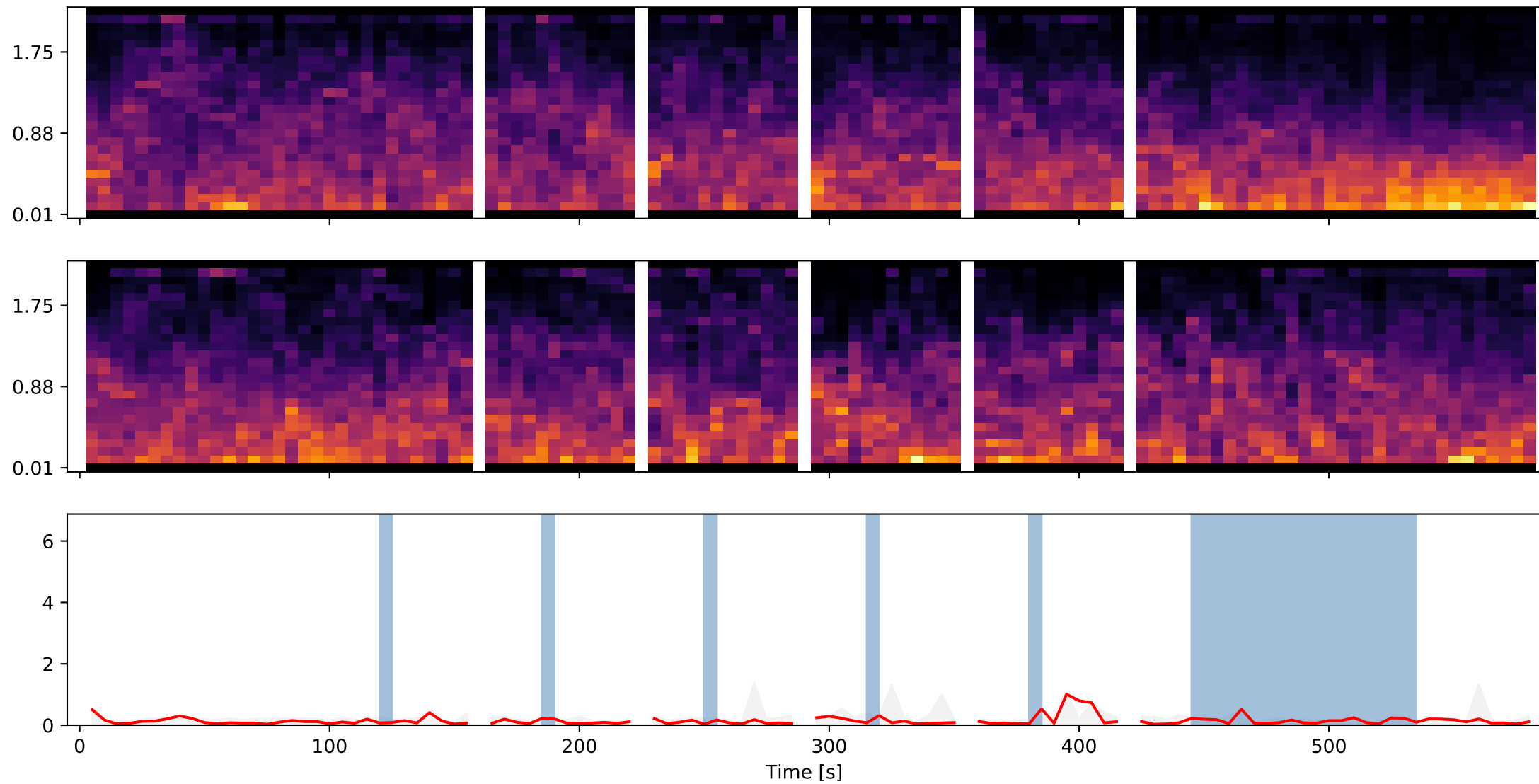
d_angular_velocity



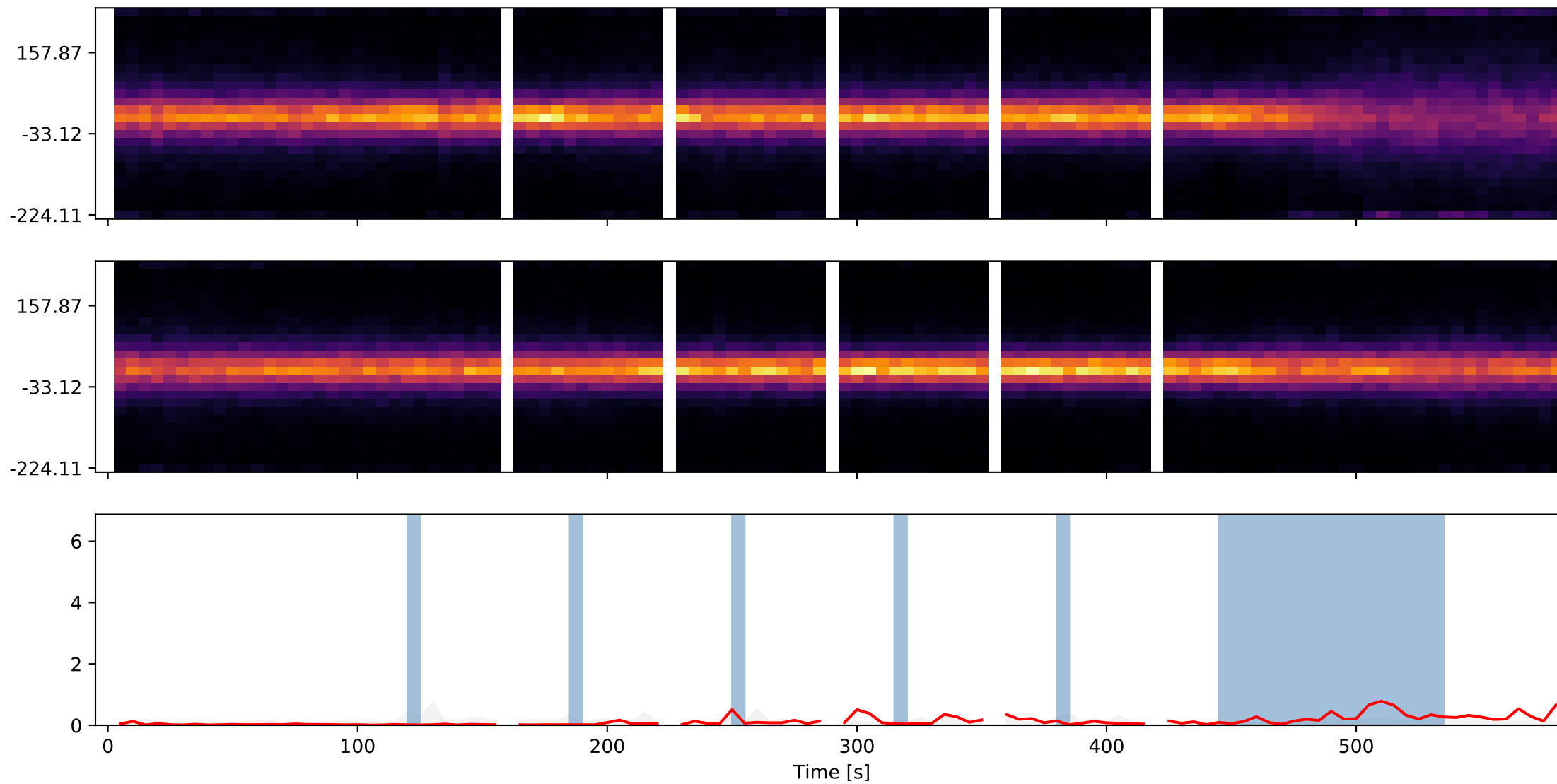
relative_to_body_radial_velocity_hips



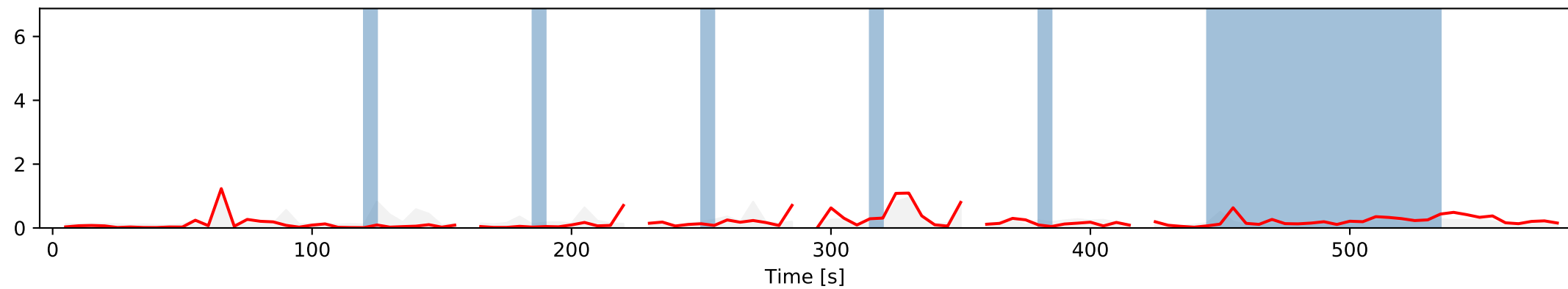
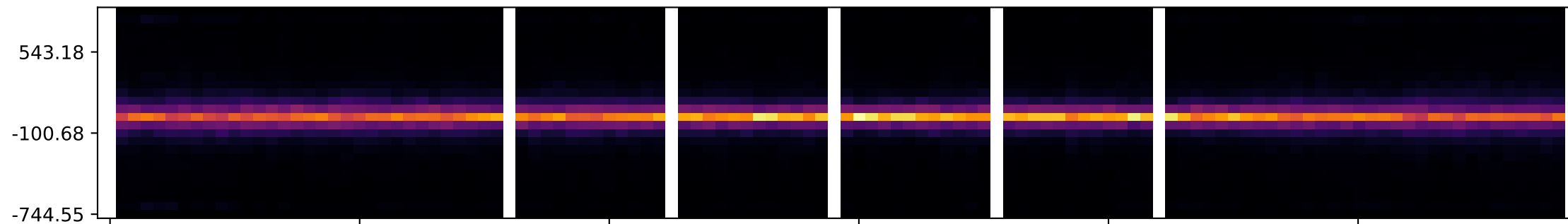
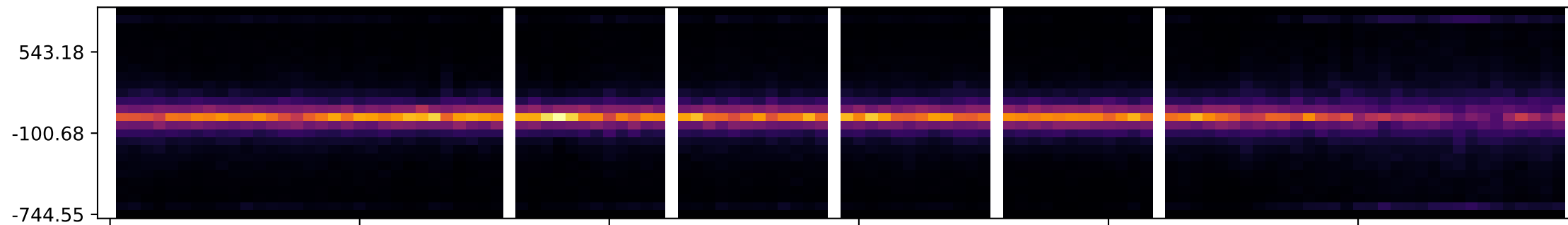
eigen_projection_5



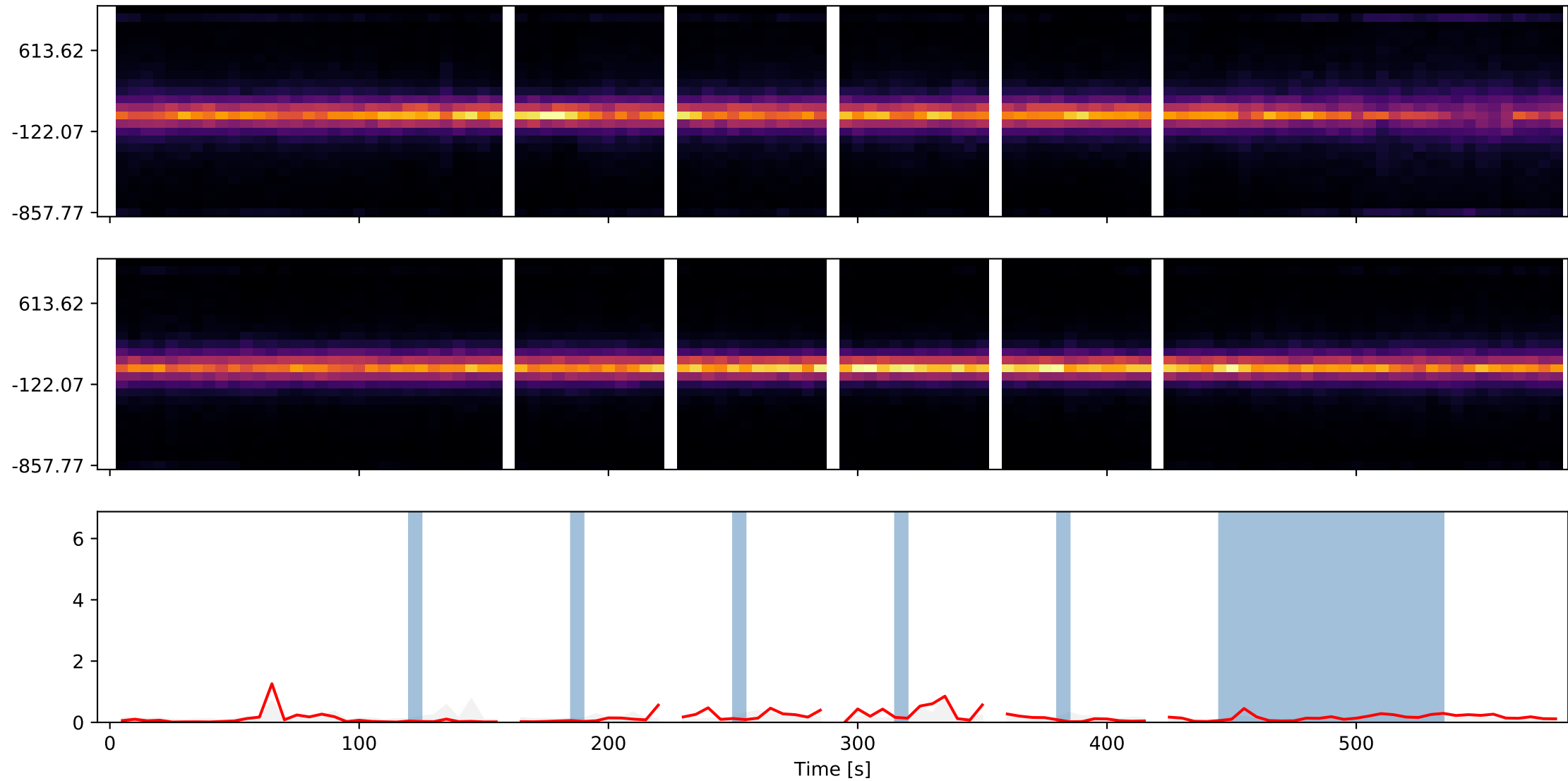
d_relative_to_body_radial_velocity_neck



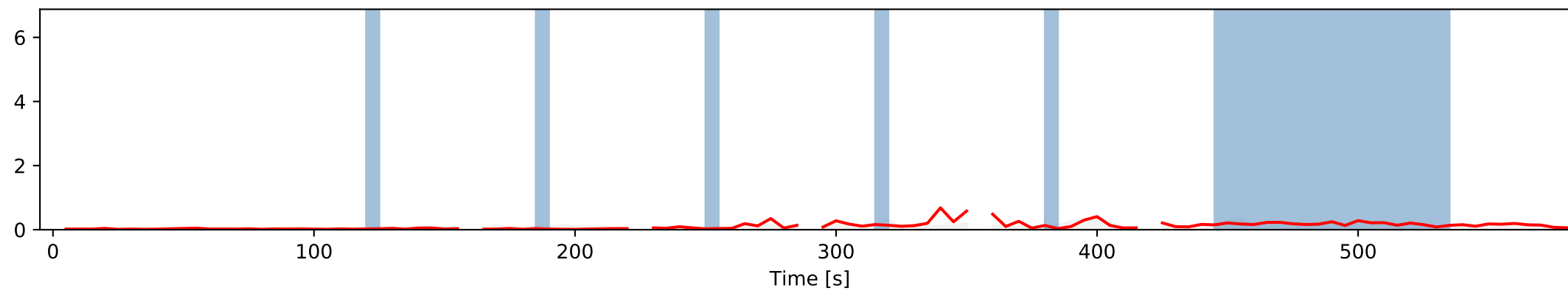
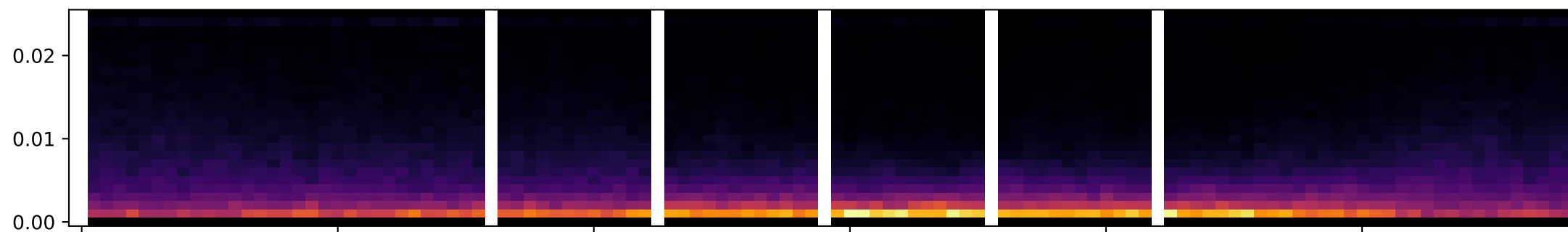
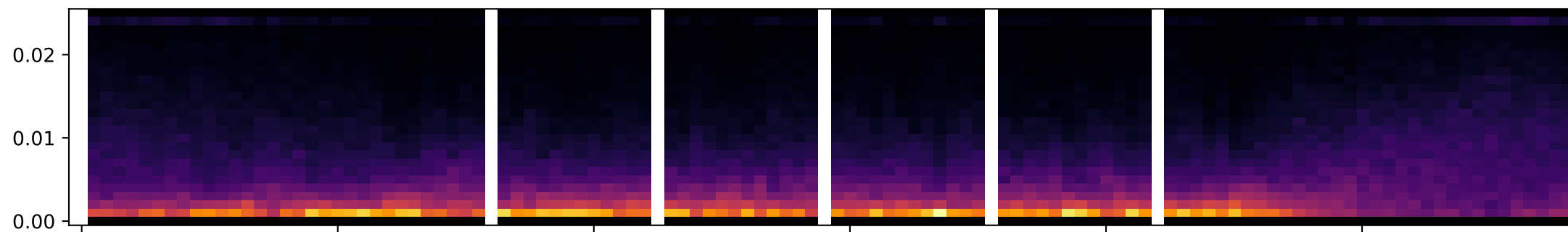
d_speed_hips



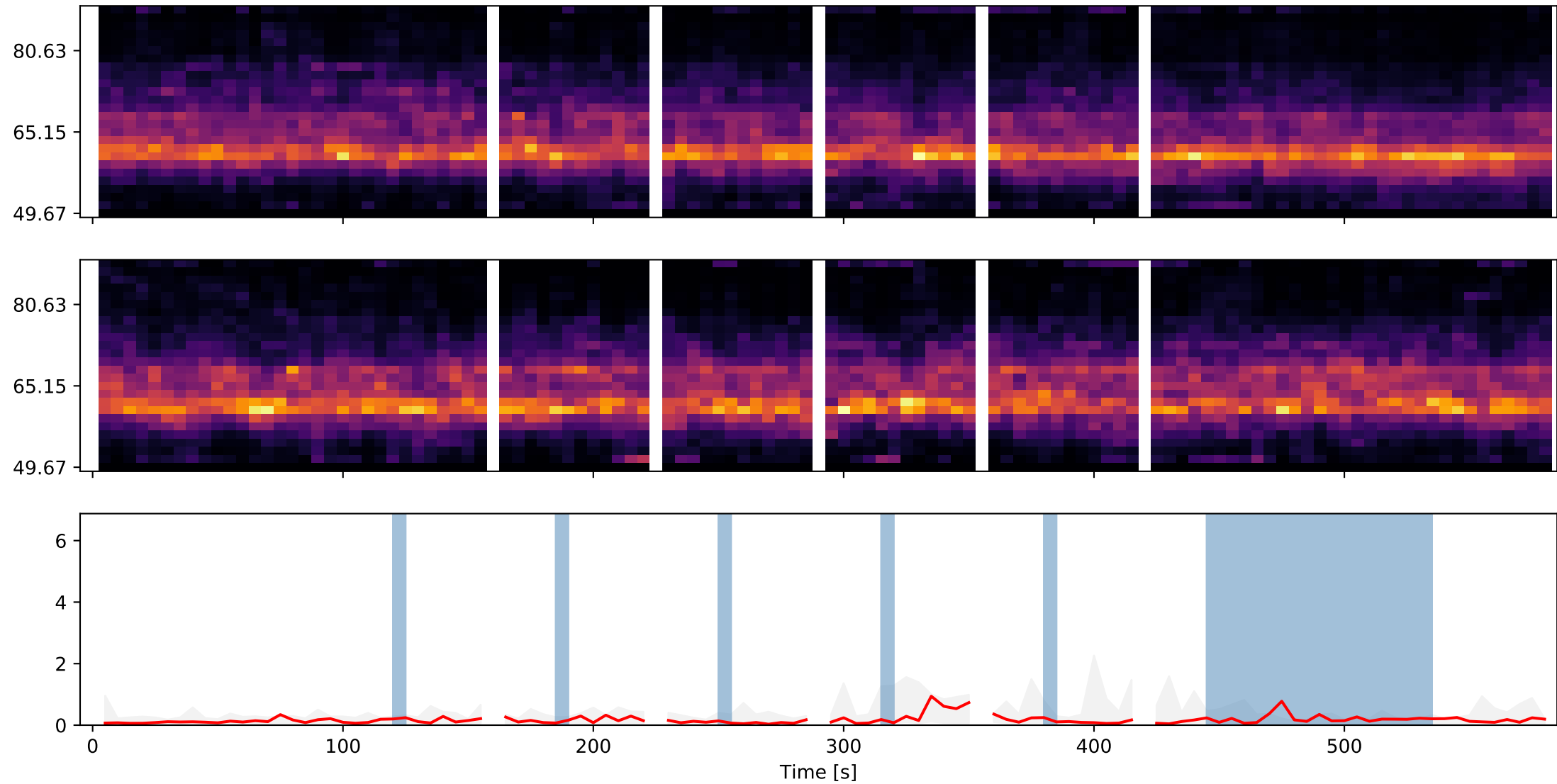
d_speed_neck



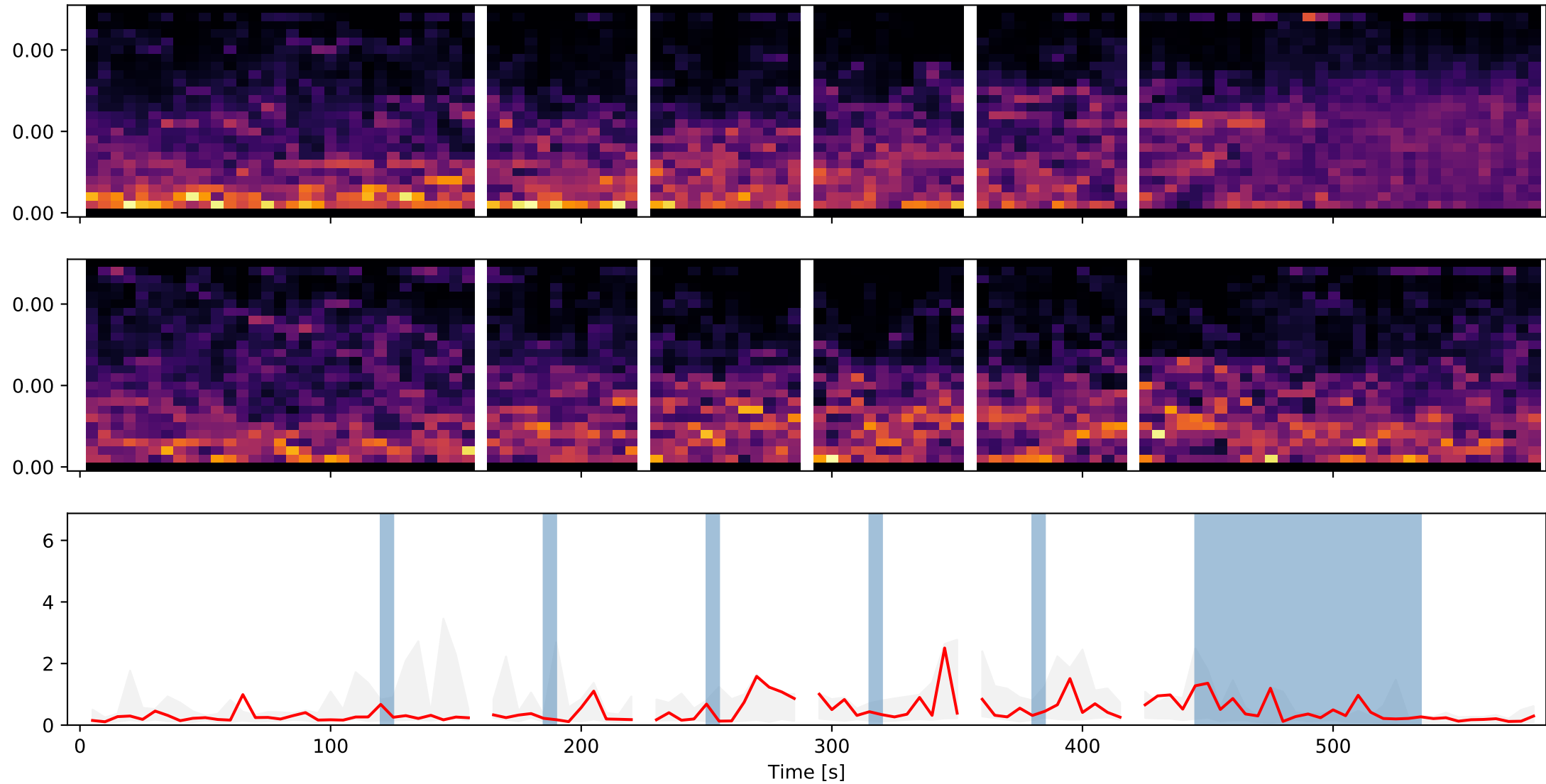
d_curvature_head



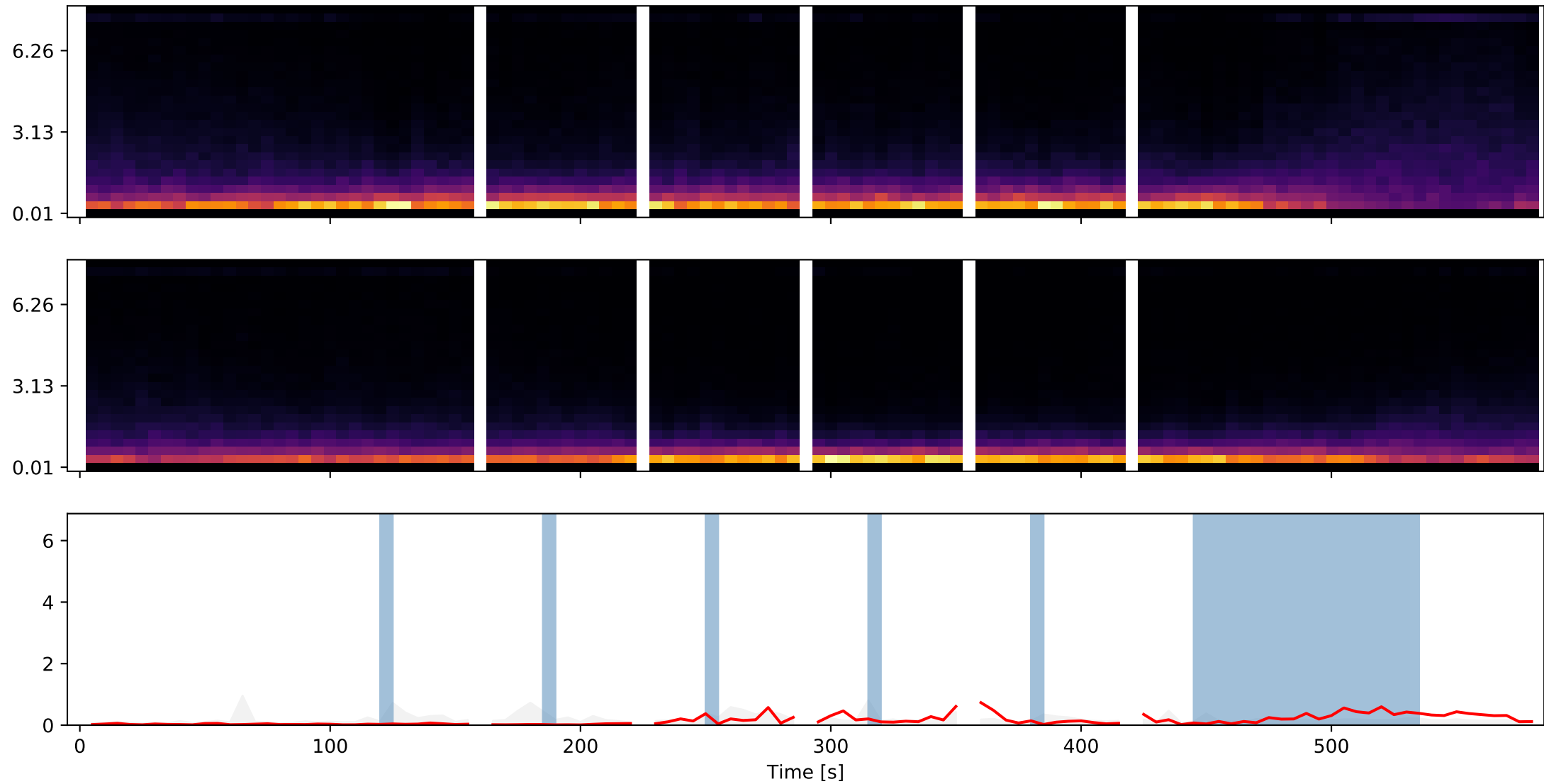
width_head_base



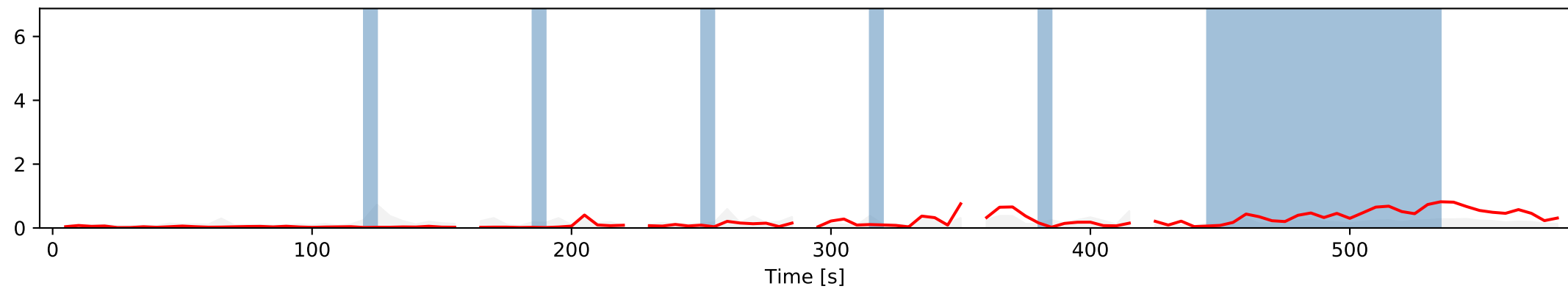
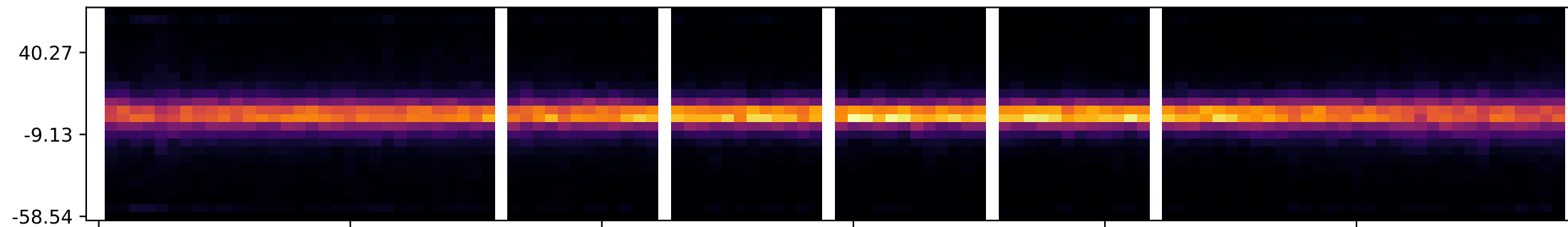
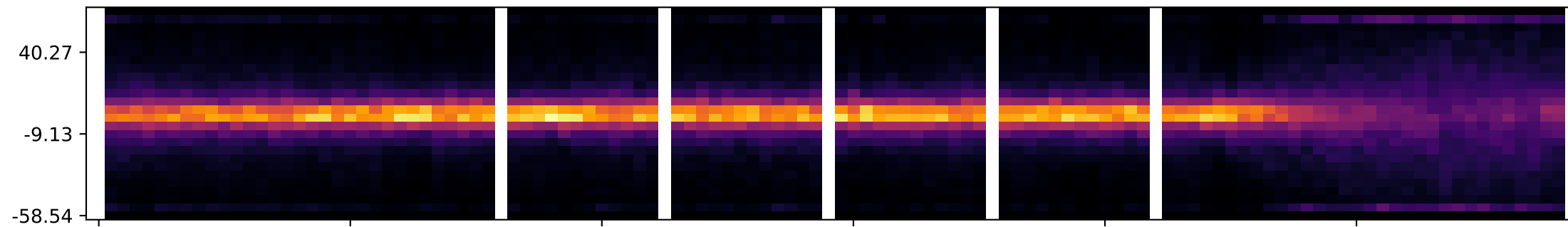
curvature_mean_midbody



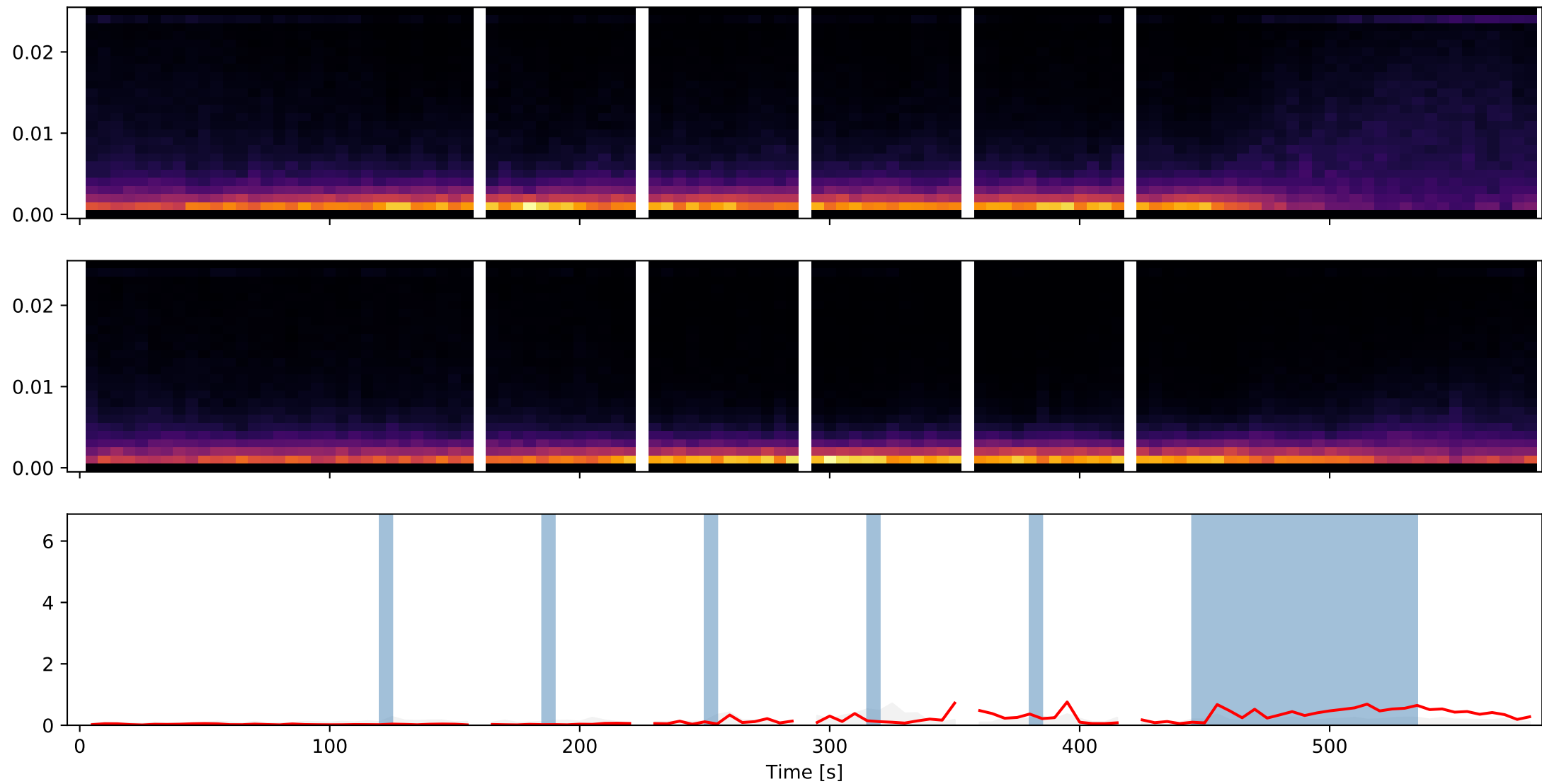
d_relative_to_neck_angular_velocity_head_tip



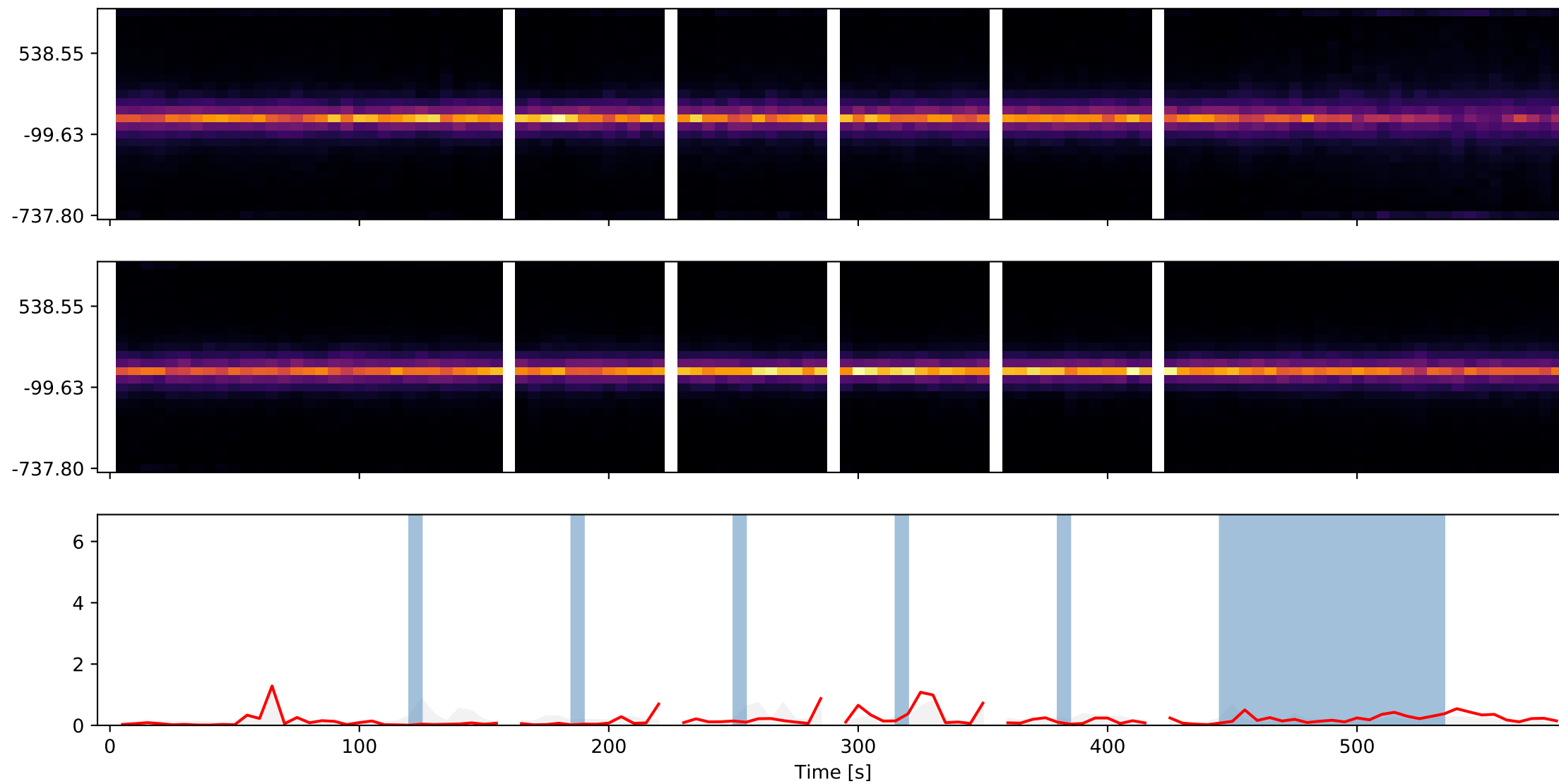
relative_to_hips_radial_velocity_tail_tip



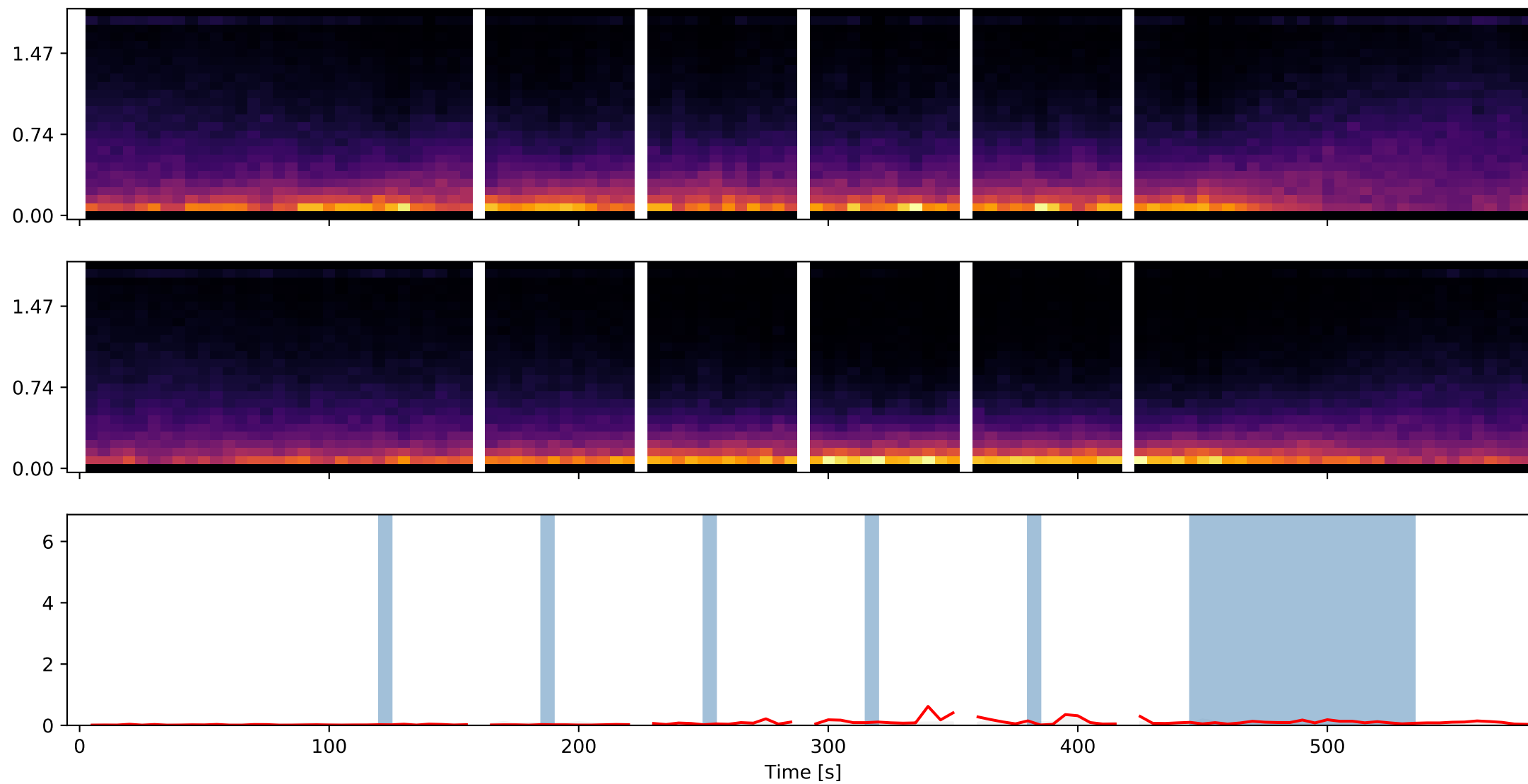
d_curvature_neck



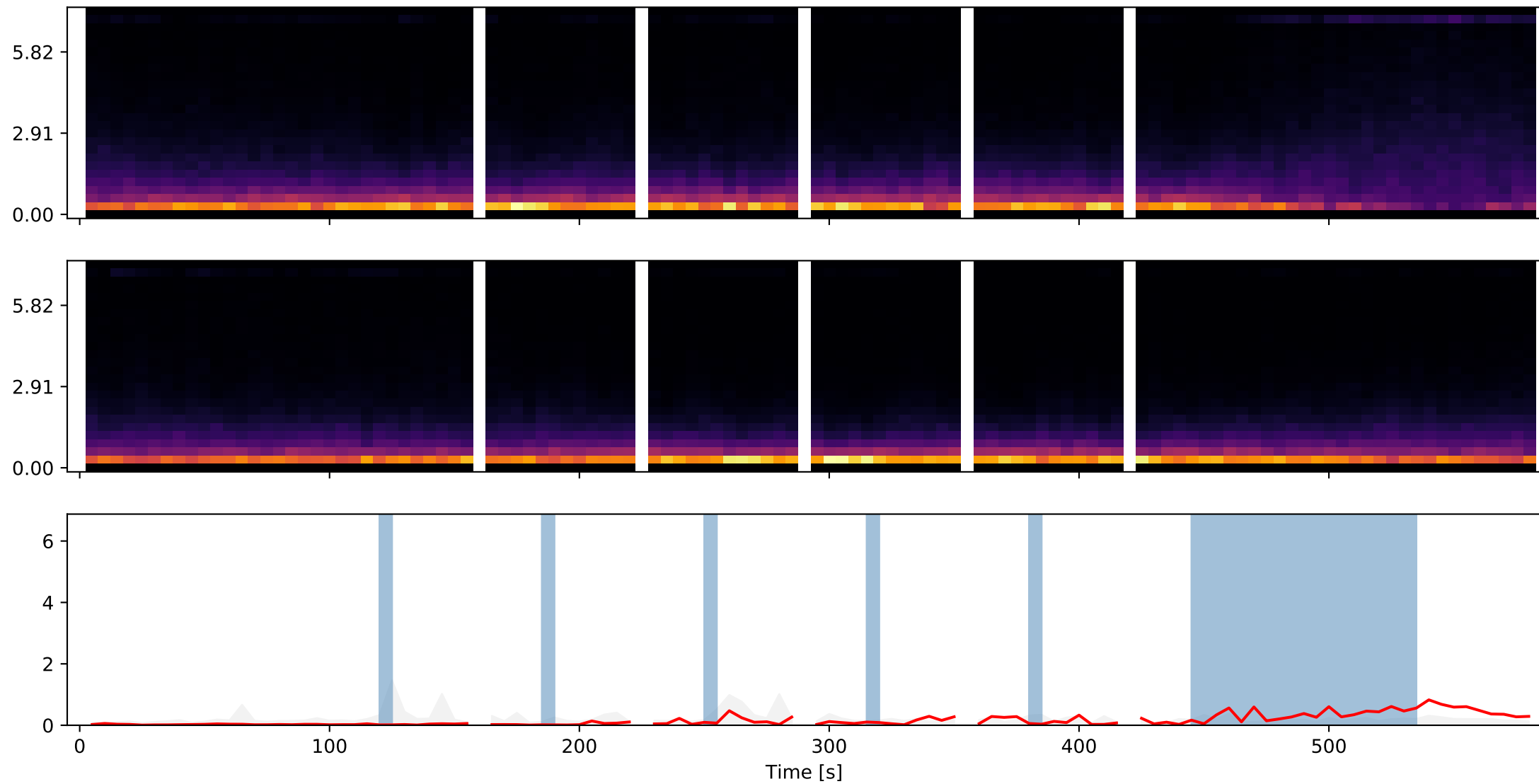
d_speed_tail_base



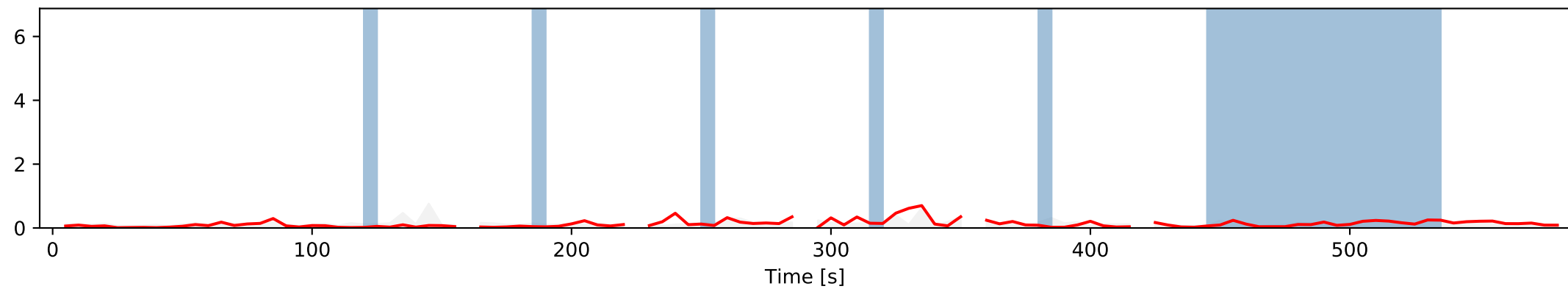
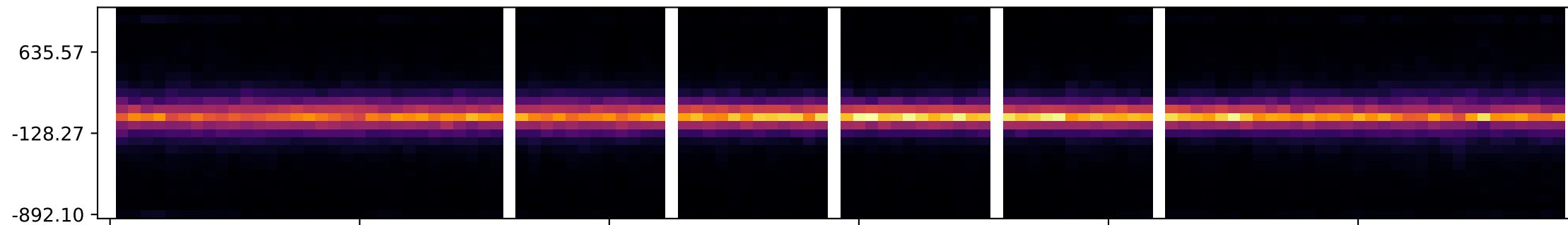
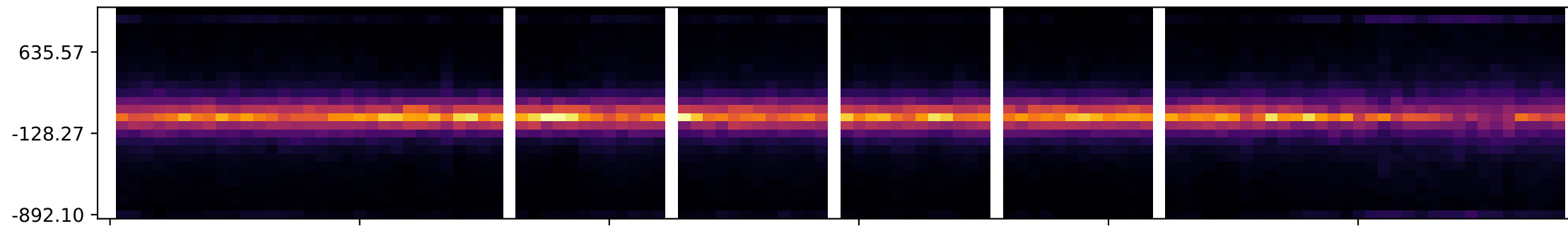
relative_to_head_base_angular_velocity_head_tip



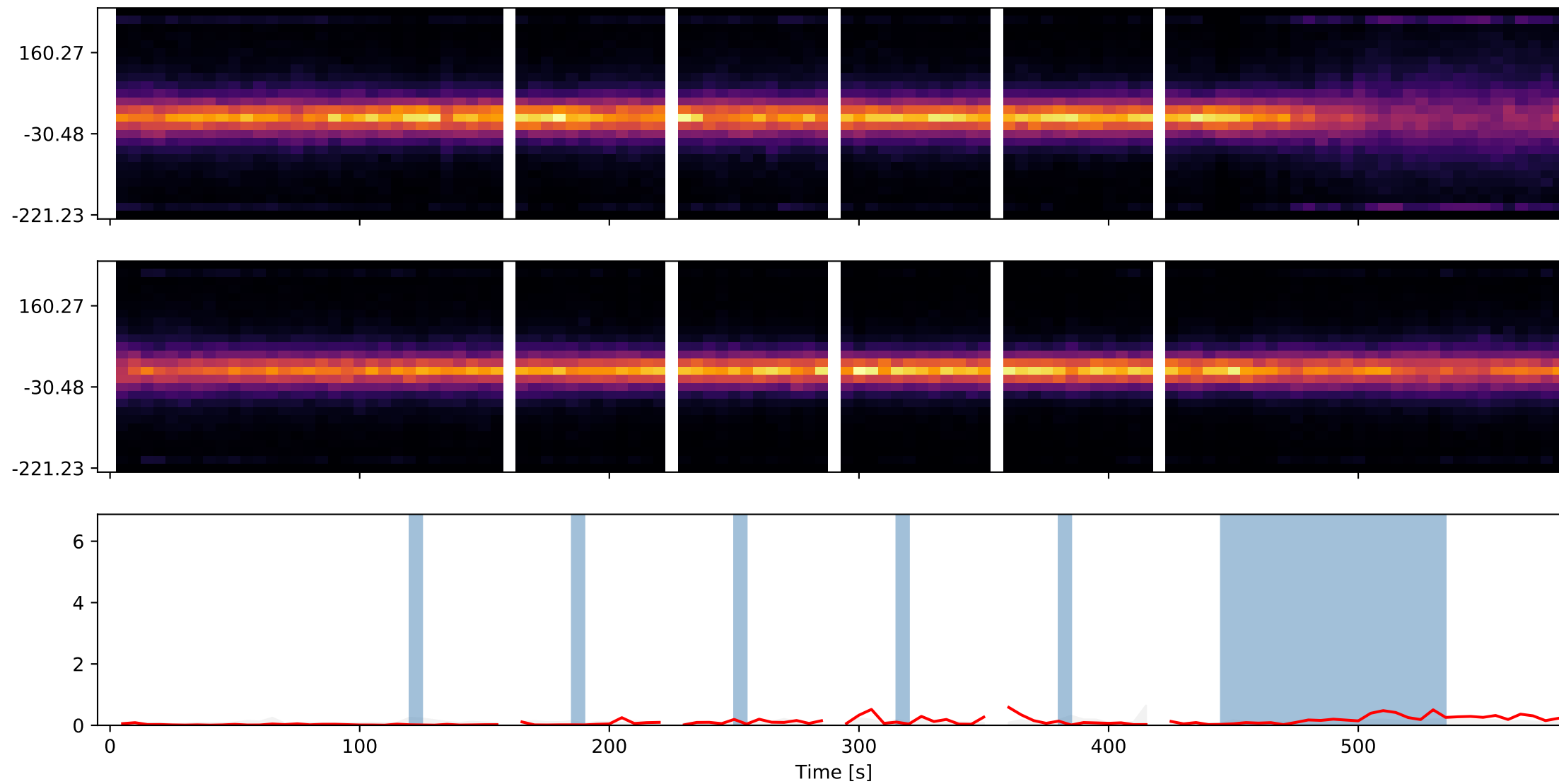
d_angular_velocity_tail_base



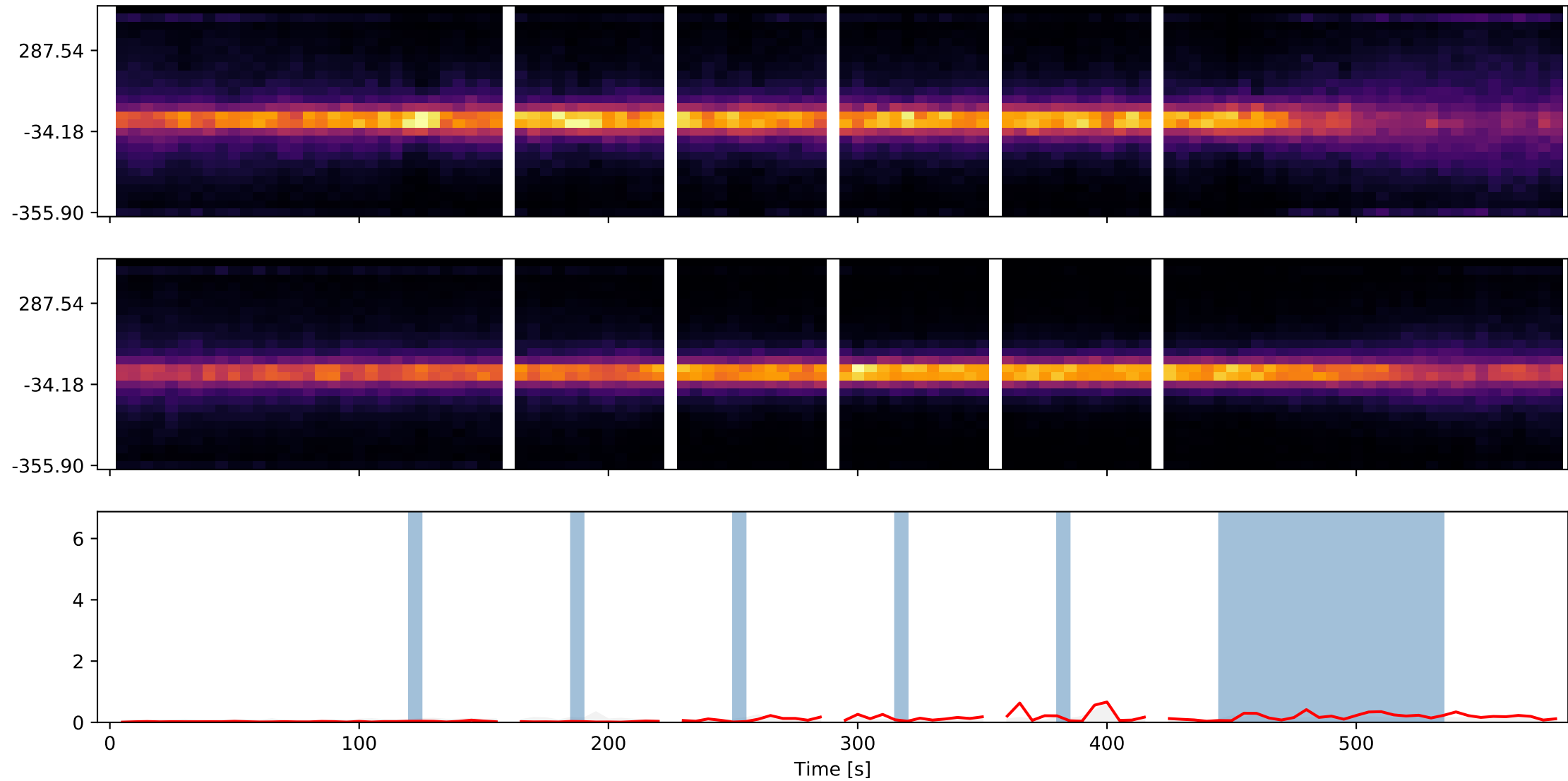
d_speed_head_base



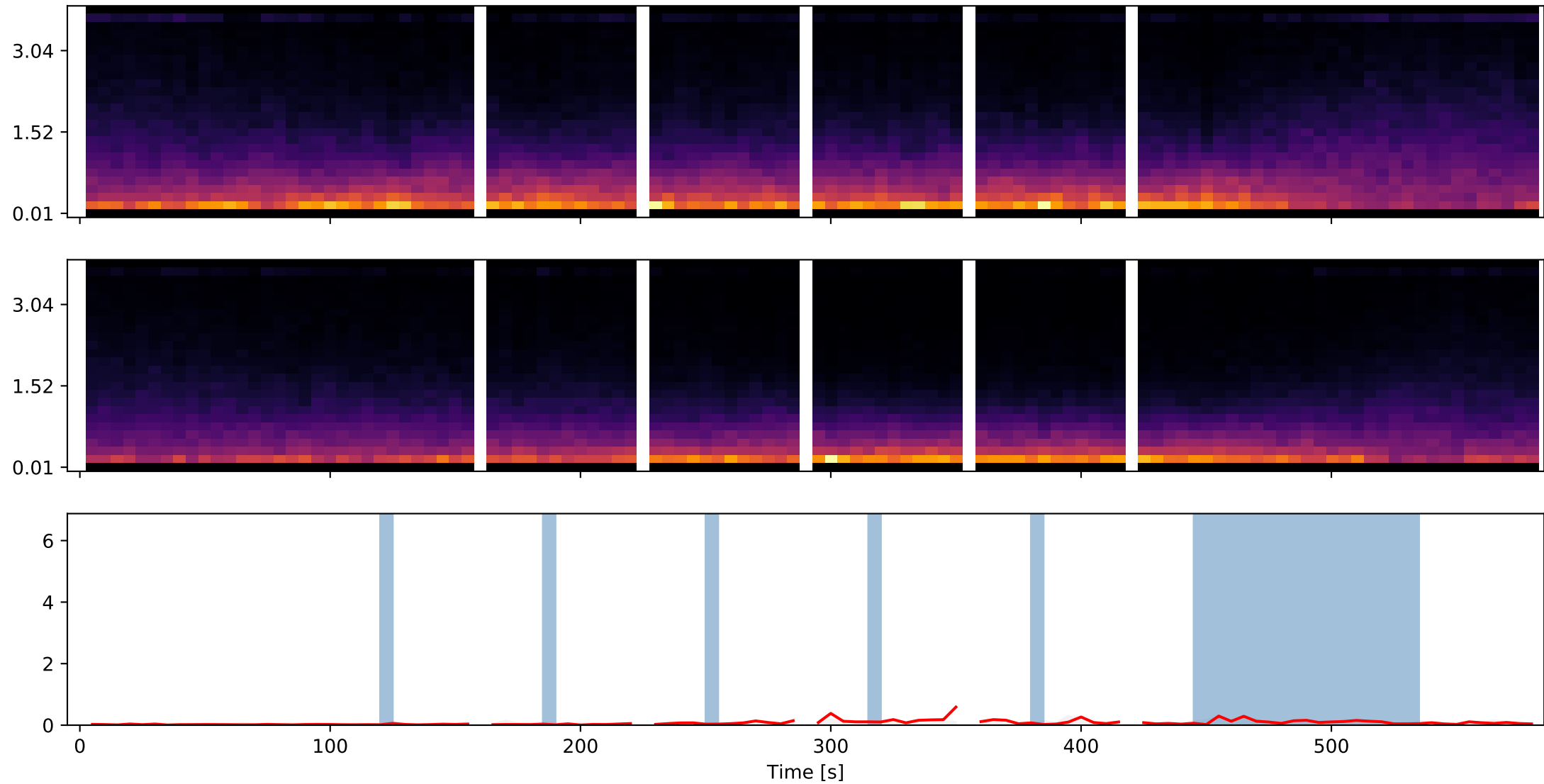
d_relative_to_body_radial_velocity_hips



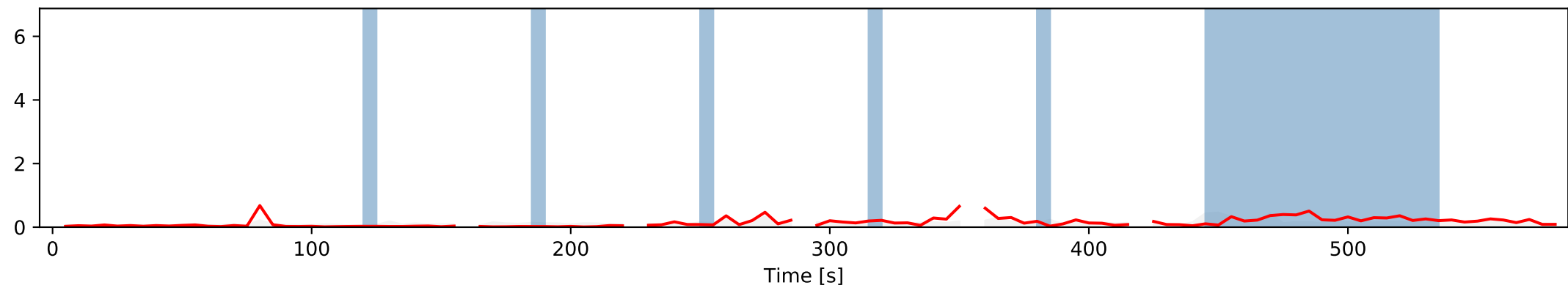
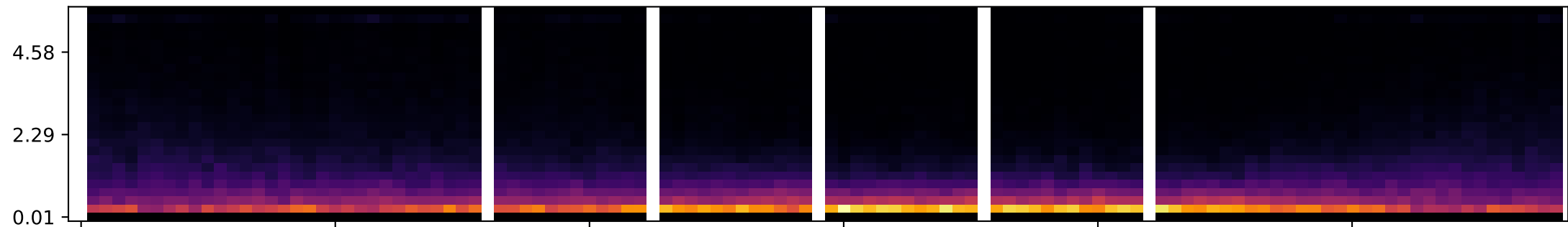
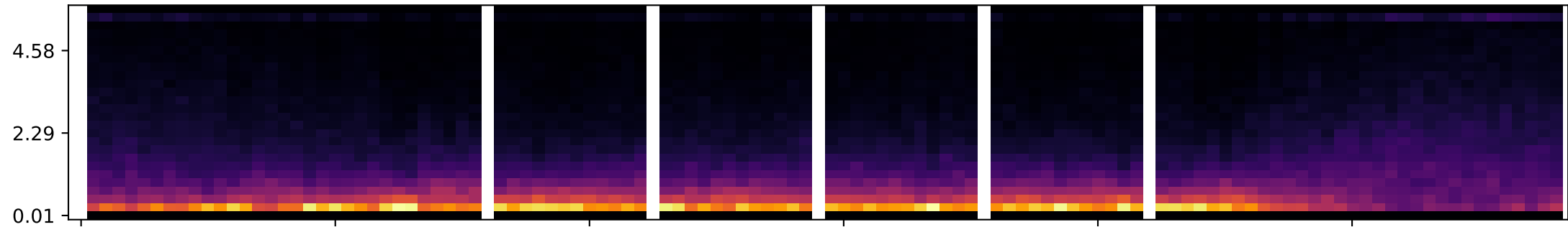
d_relative_to_neck_radial_velocity_head_tip



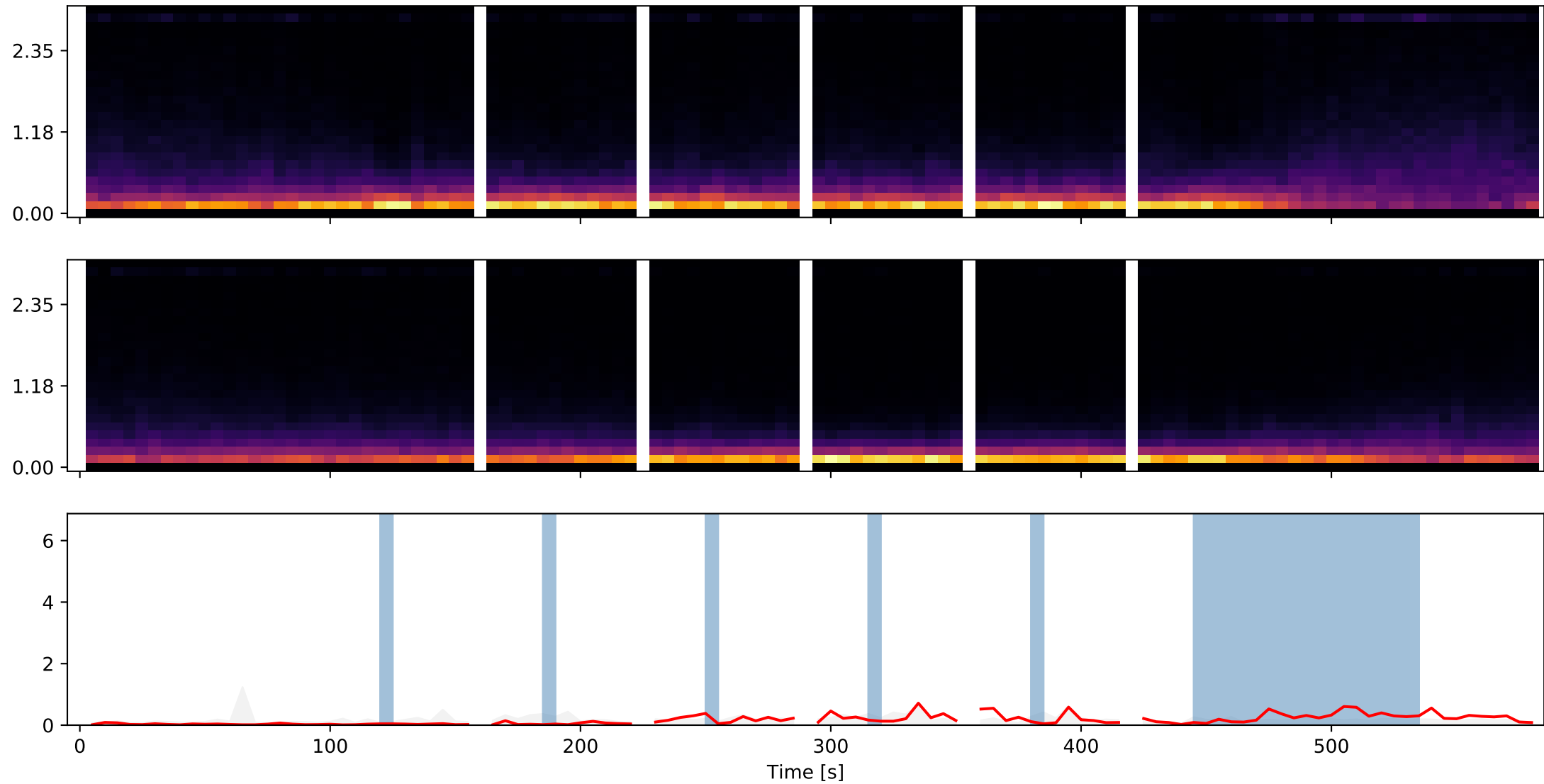
d_eigen_projection_5



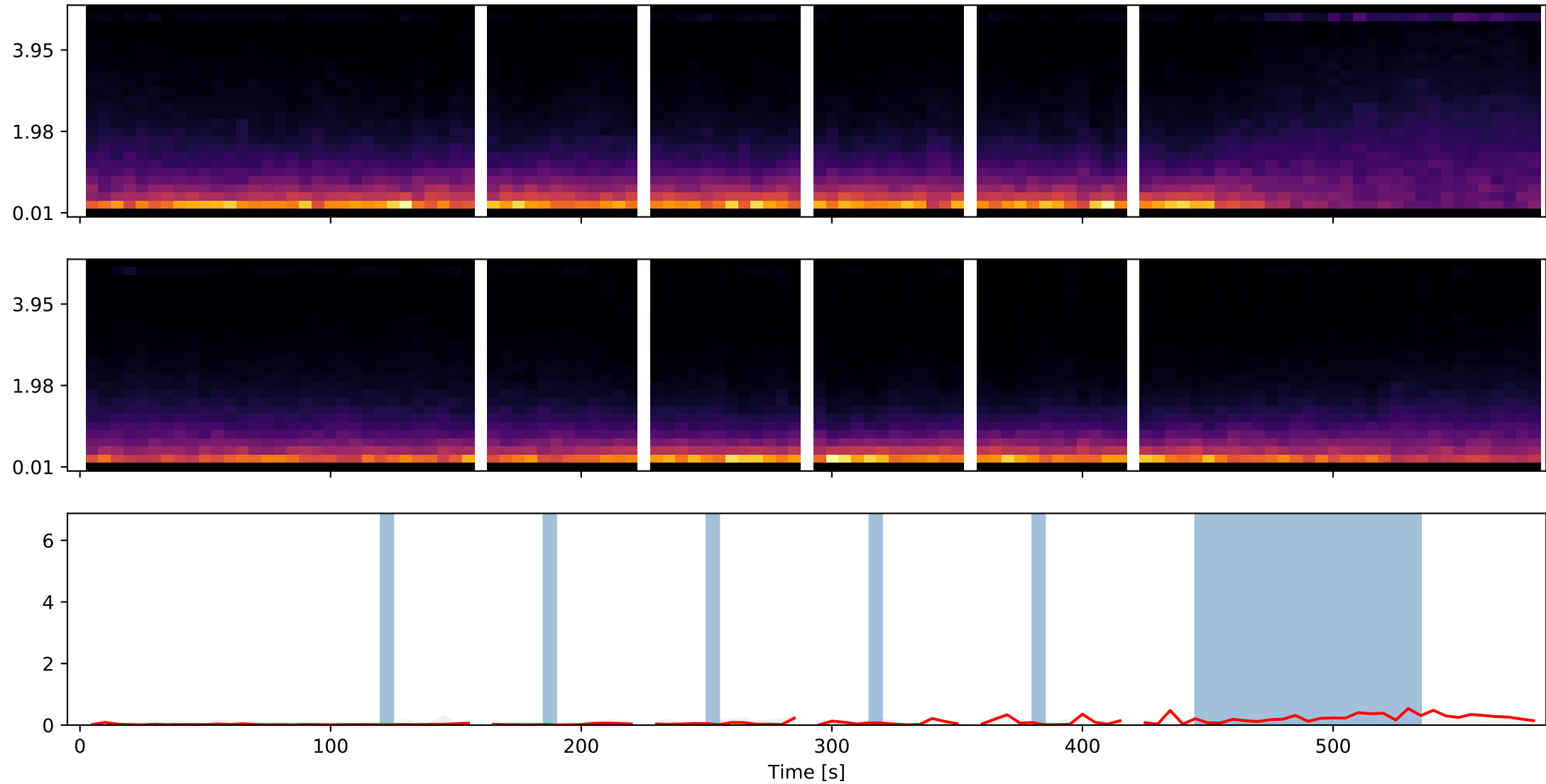
d_eigen_projection_4



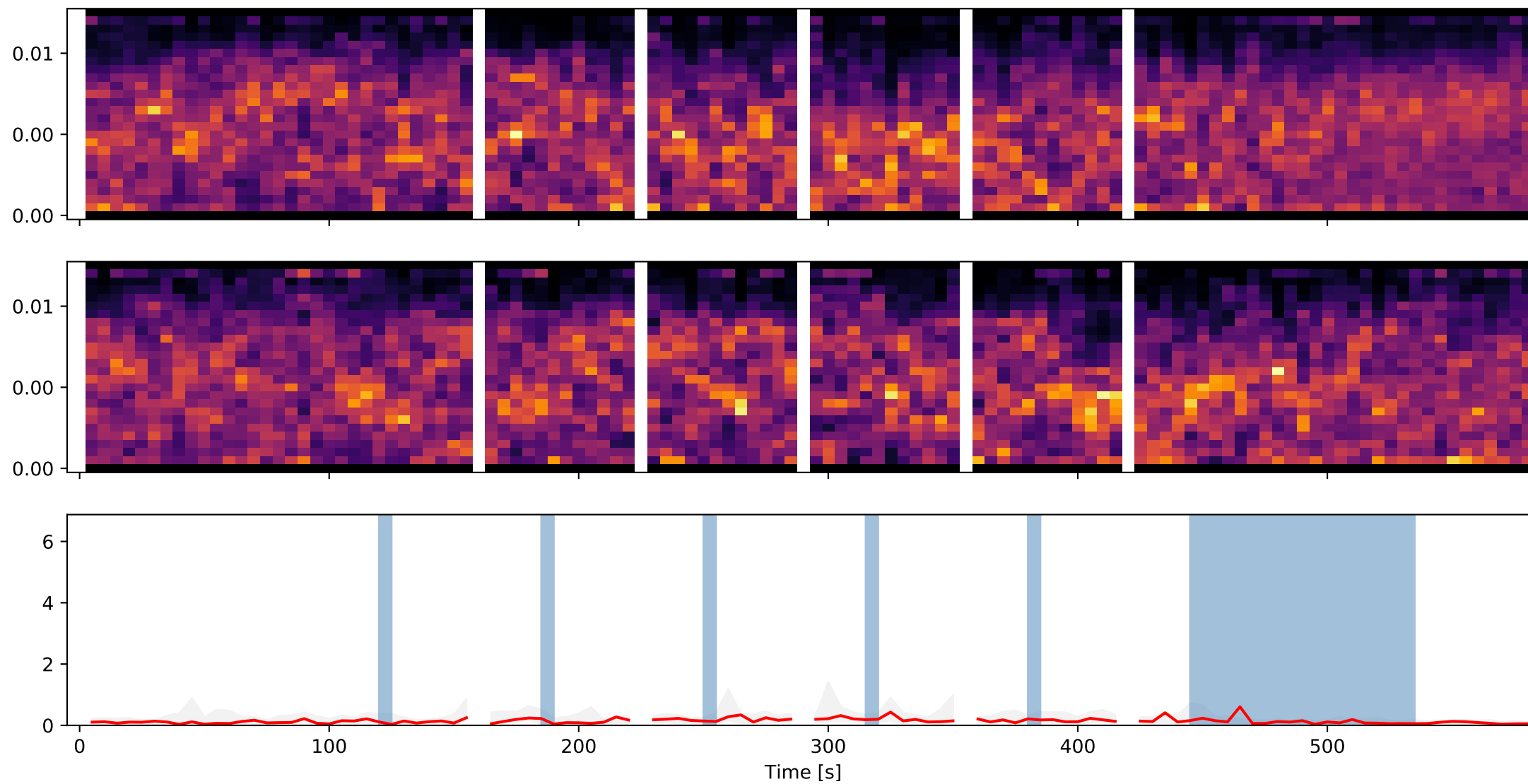
d_relative_to_body_angular_velocity_head_tip



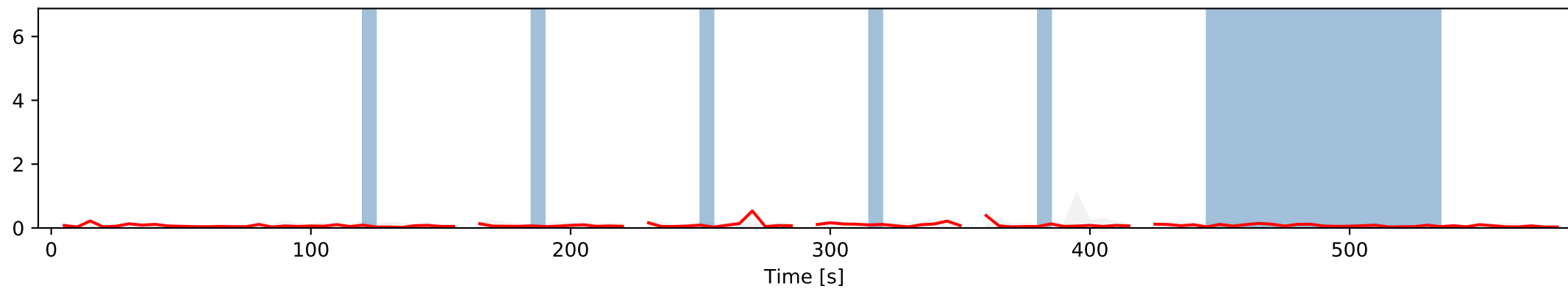
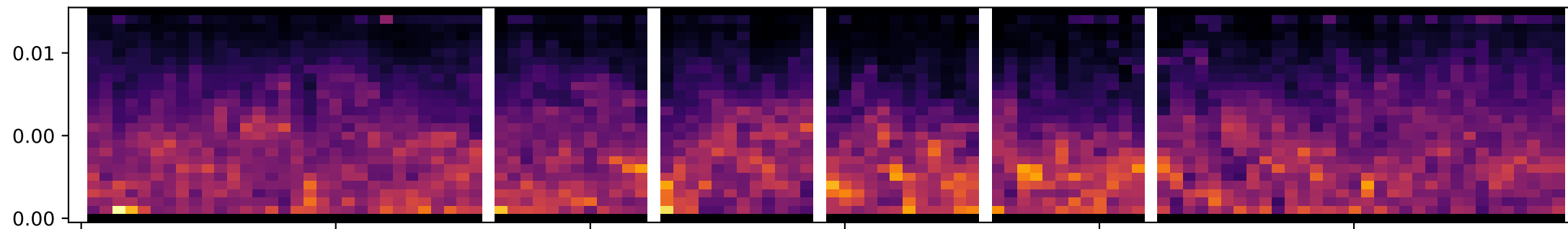
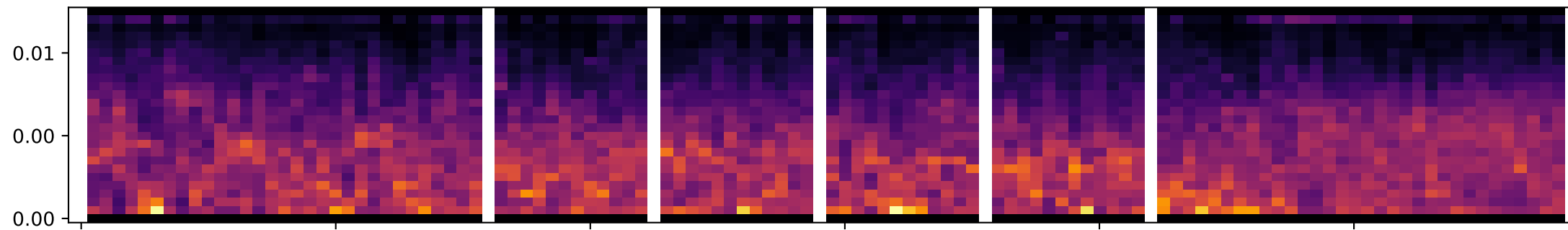
d_relative_to_tail_base_angular_velocity_tail_tip



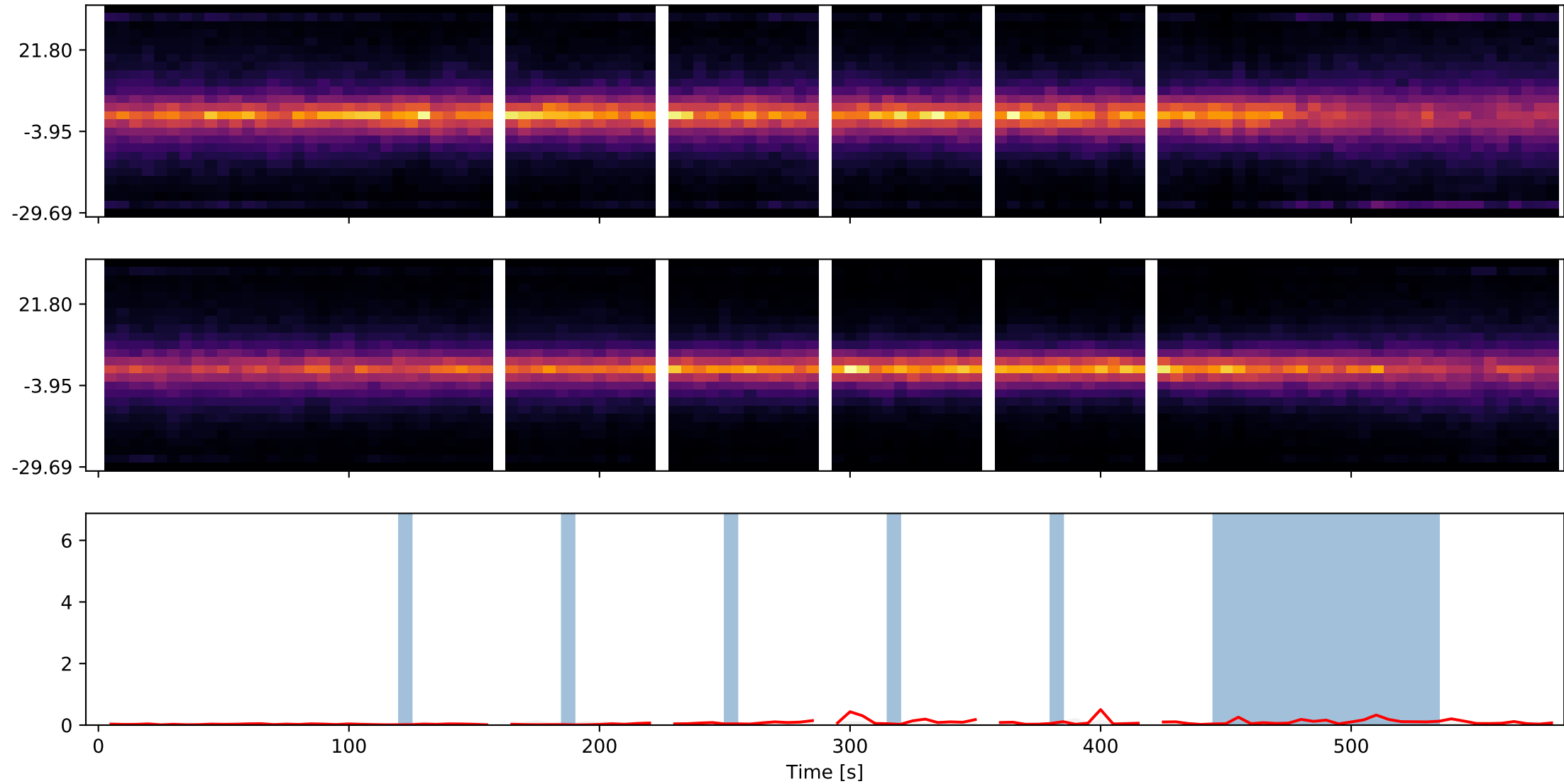
curvature_hips



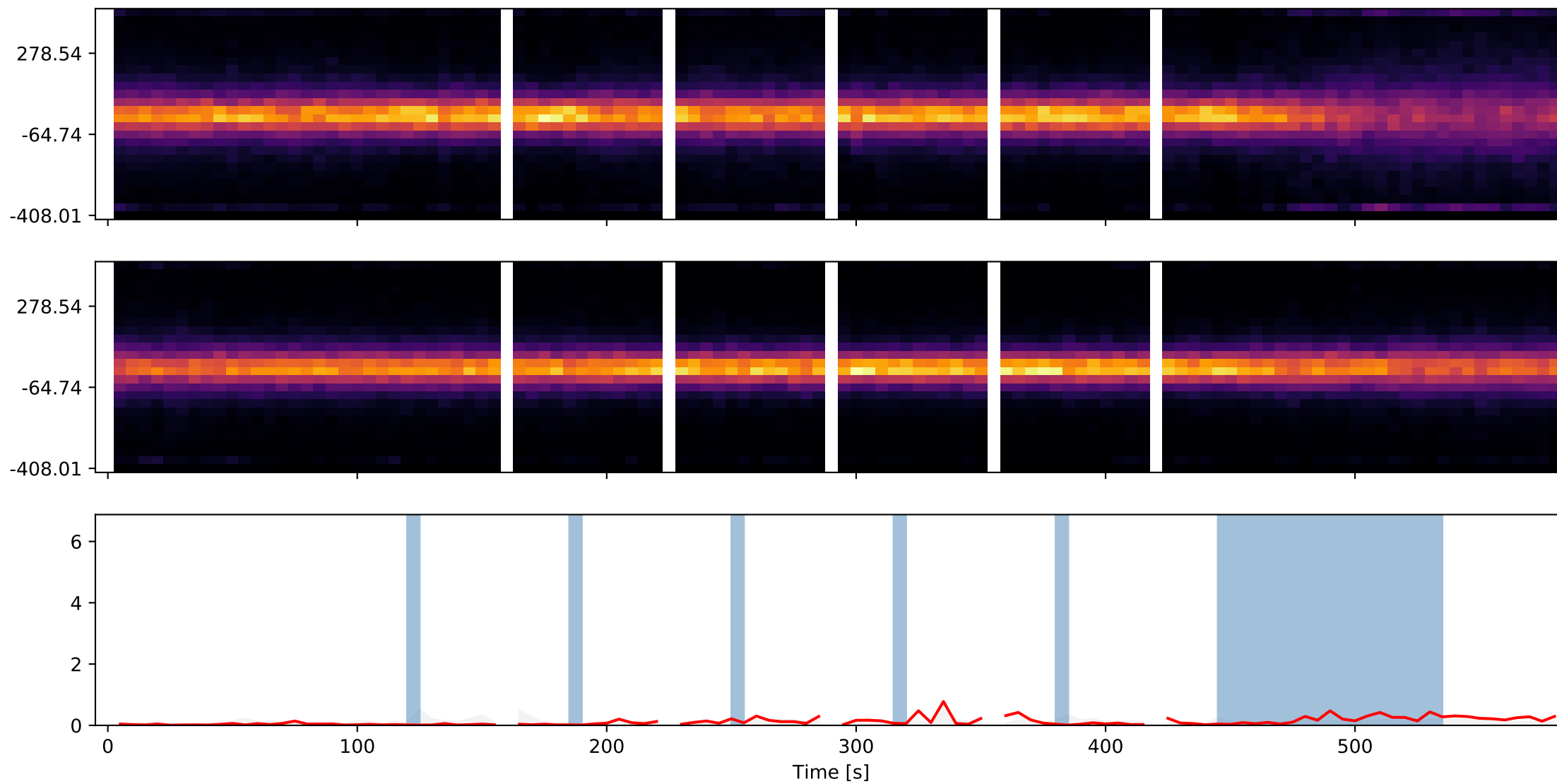
curvature_head



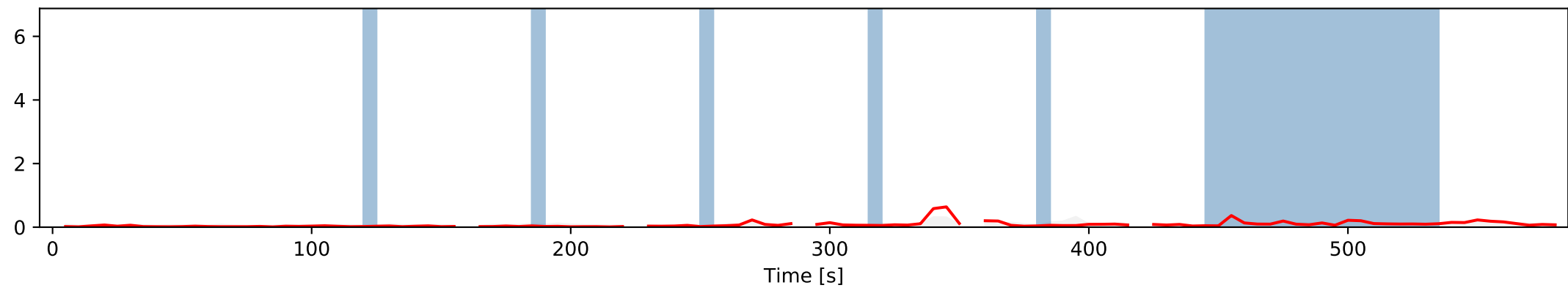
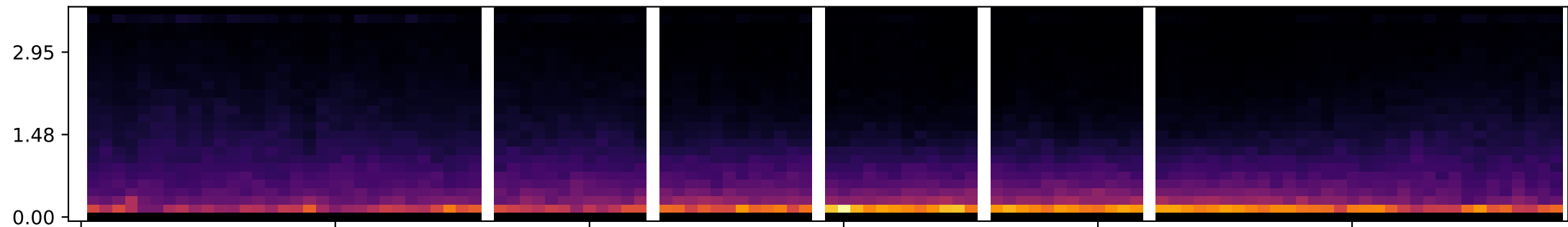
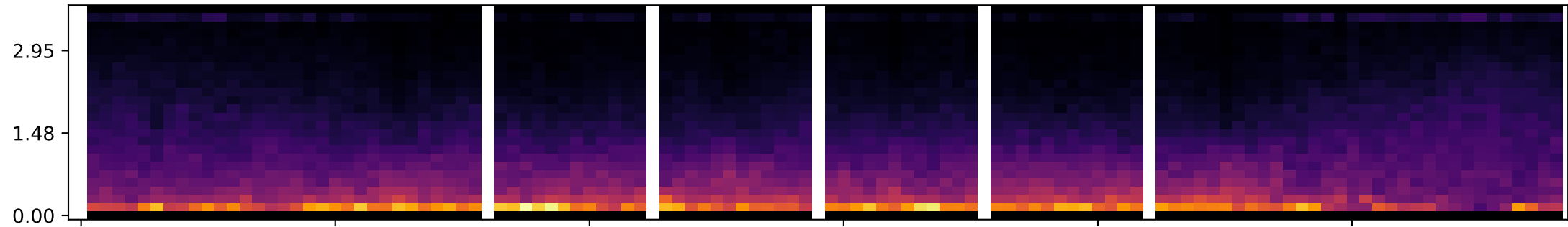
relative_to_head_base_radial_velocity_head_tip



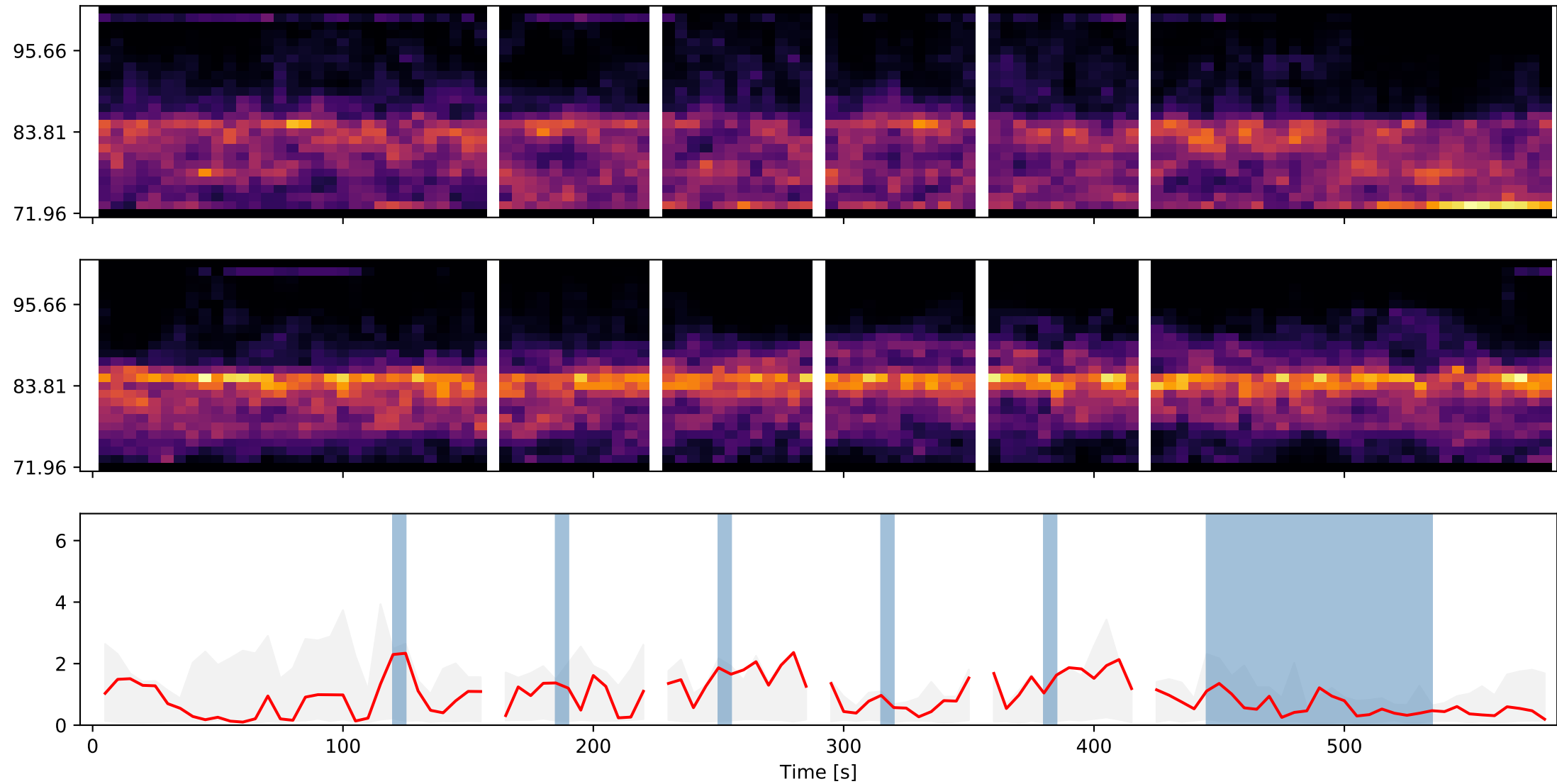
d_relative_to_body_radial_velocity_tail_tip



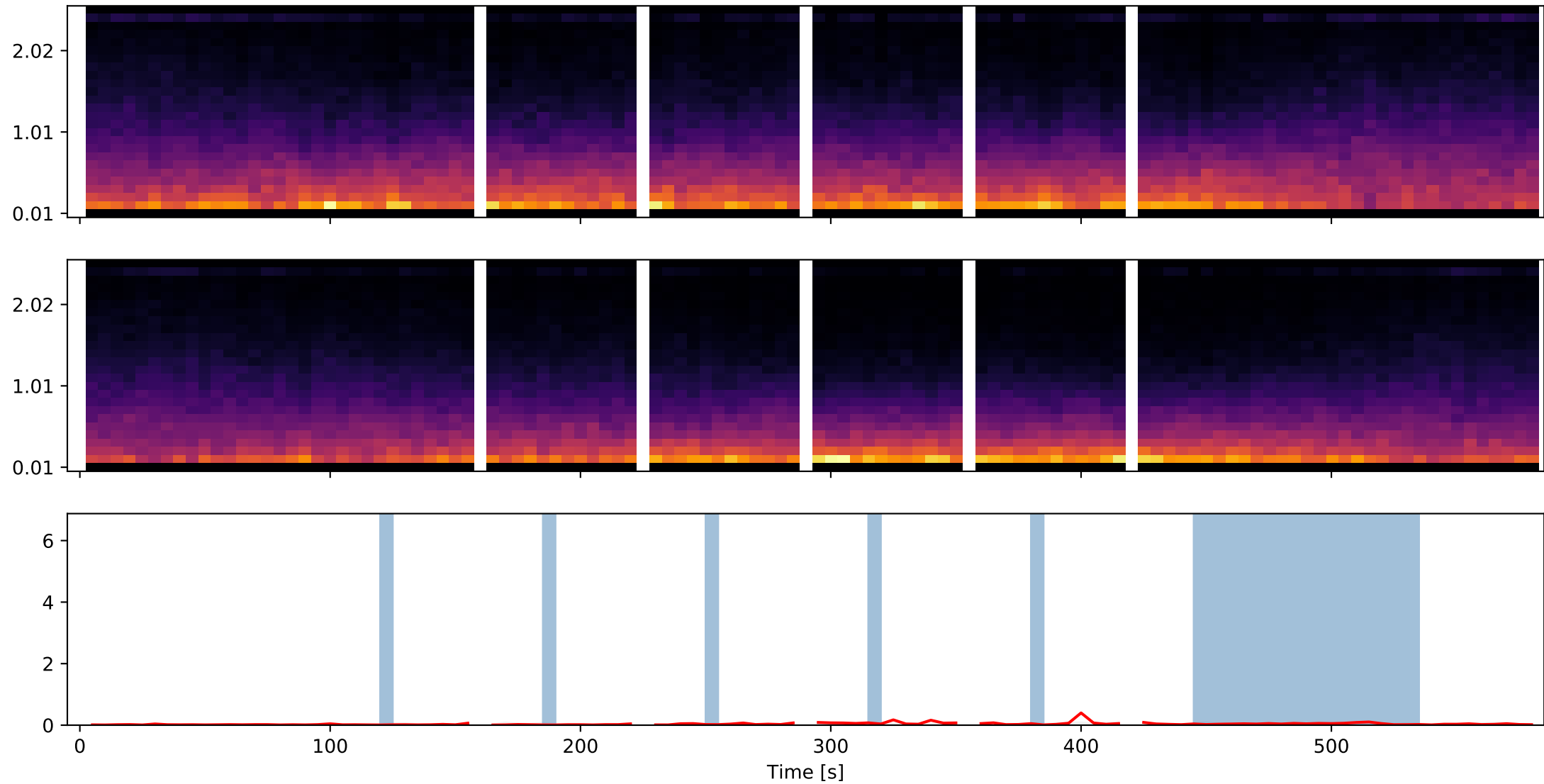
angular_velocity_head_tip



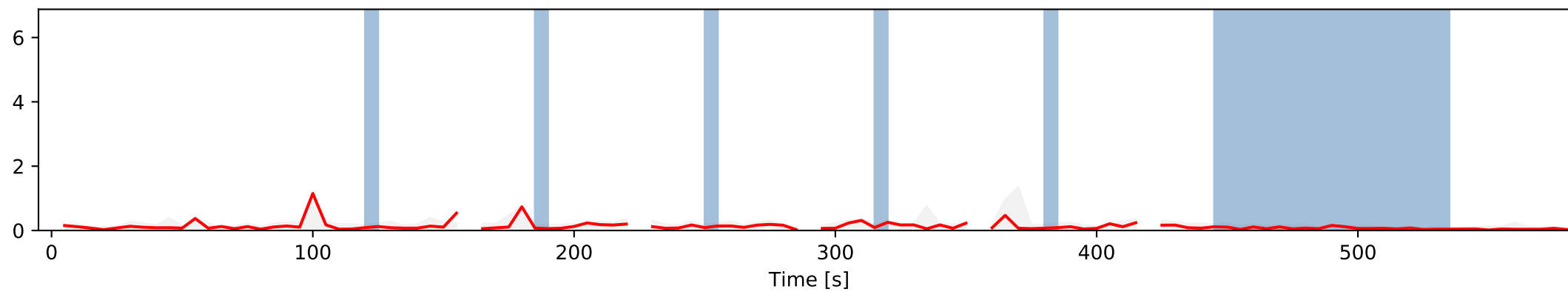
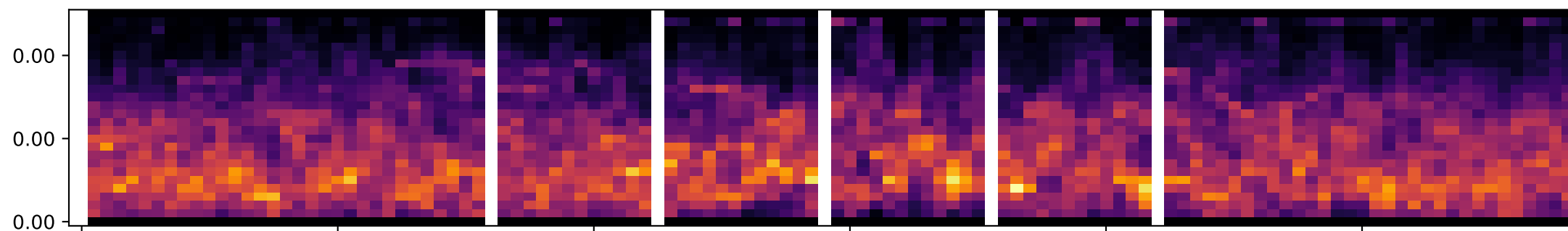
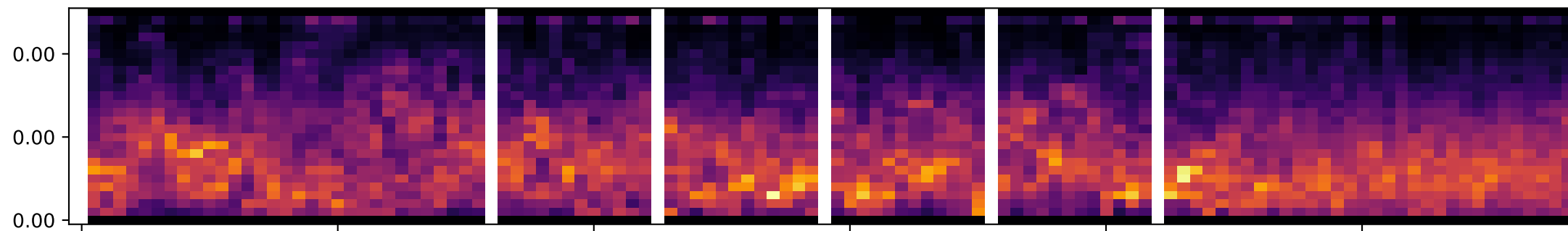
width_midbody



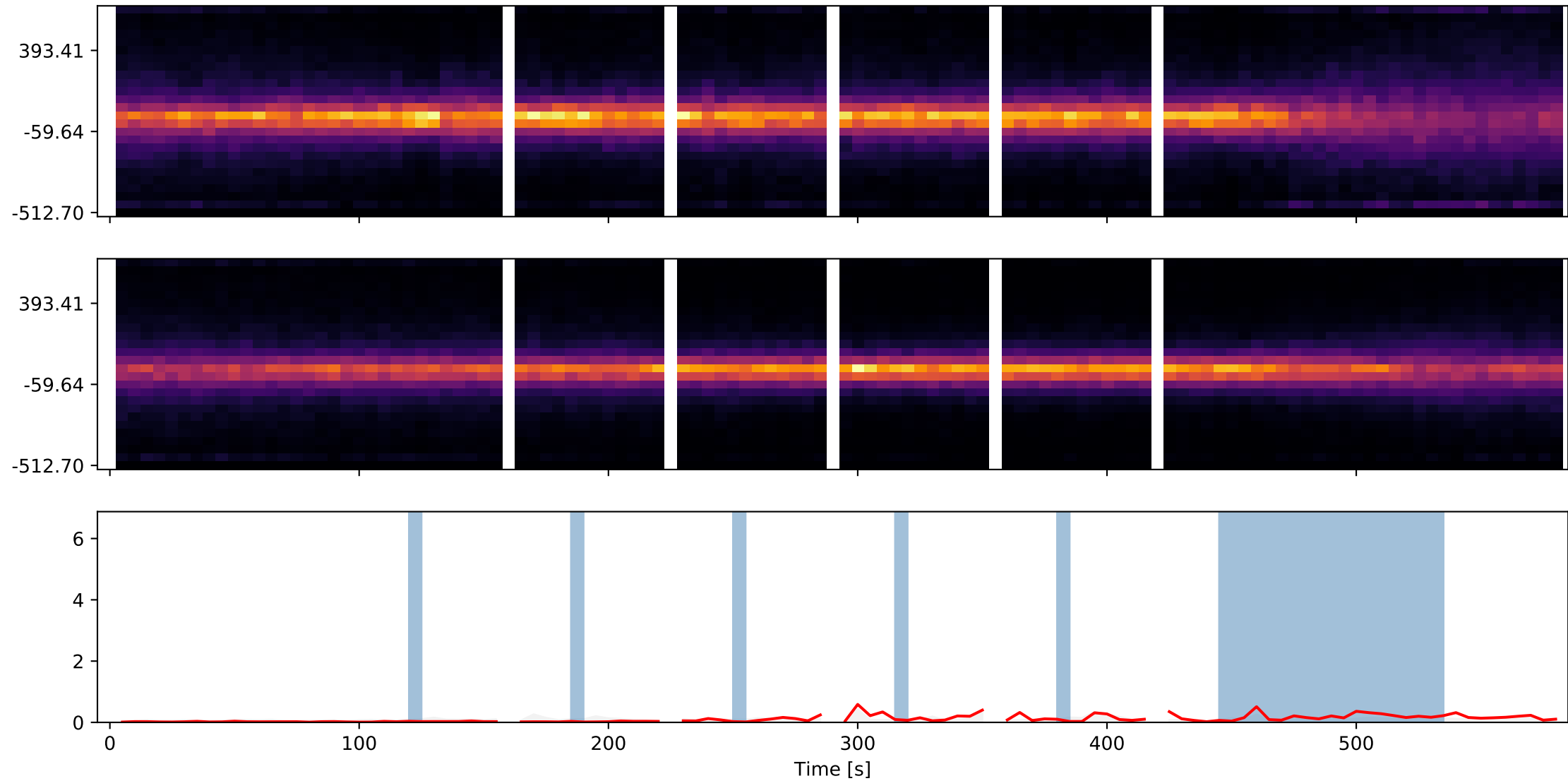
d_eigen_projection_6



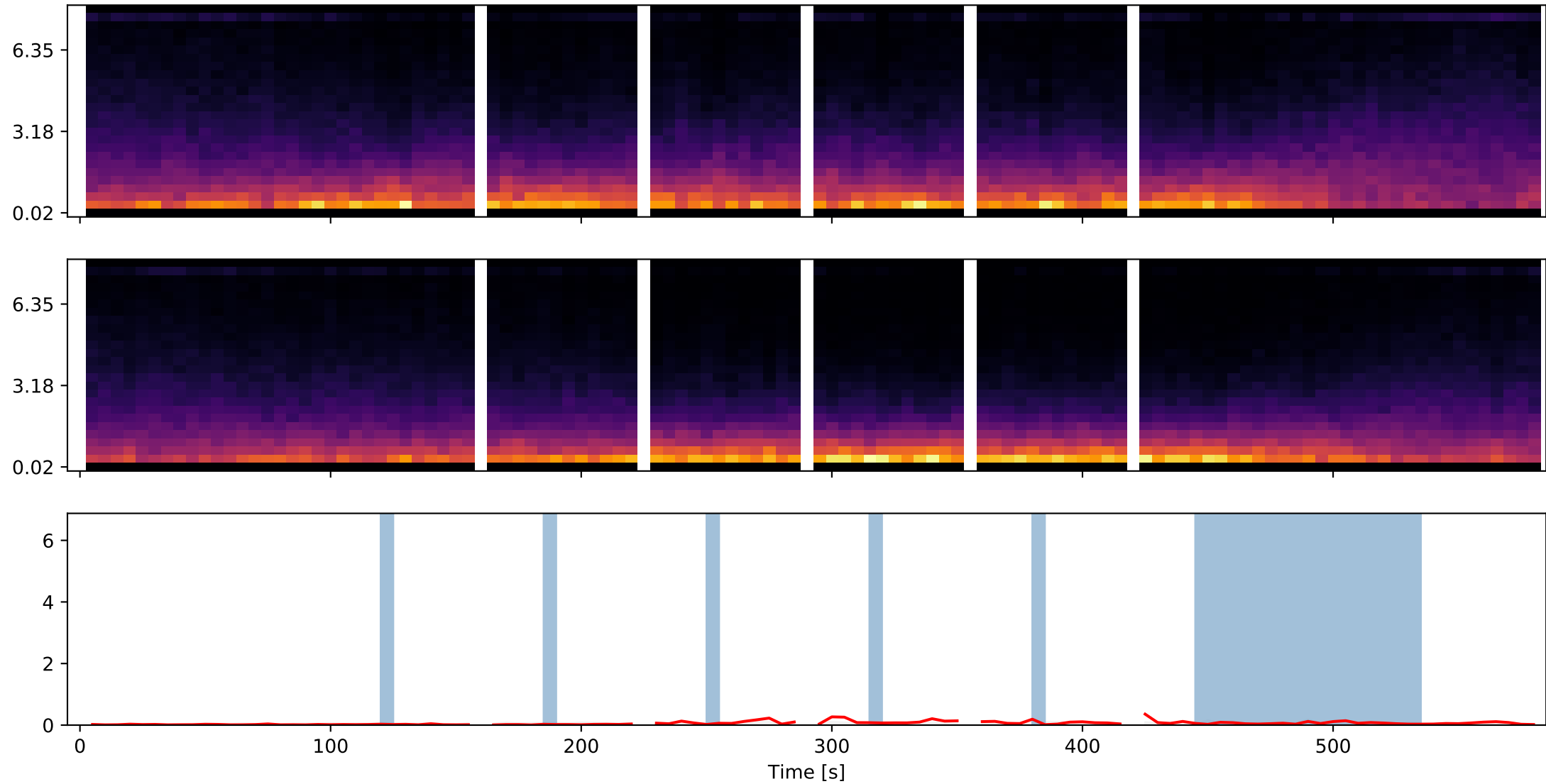
curvature_std_tail



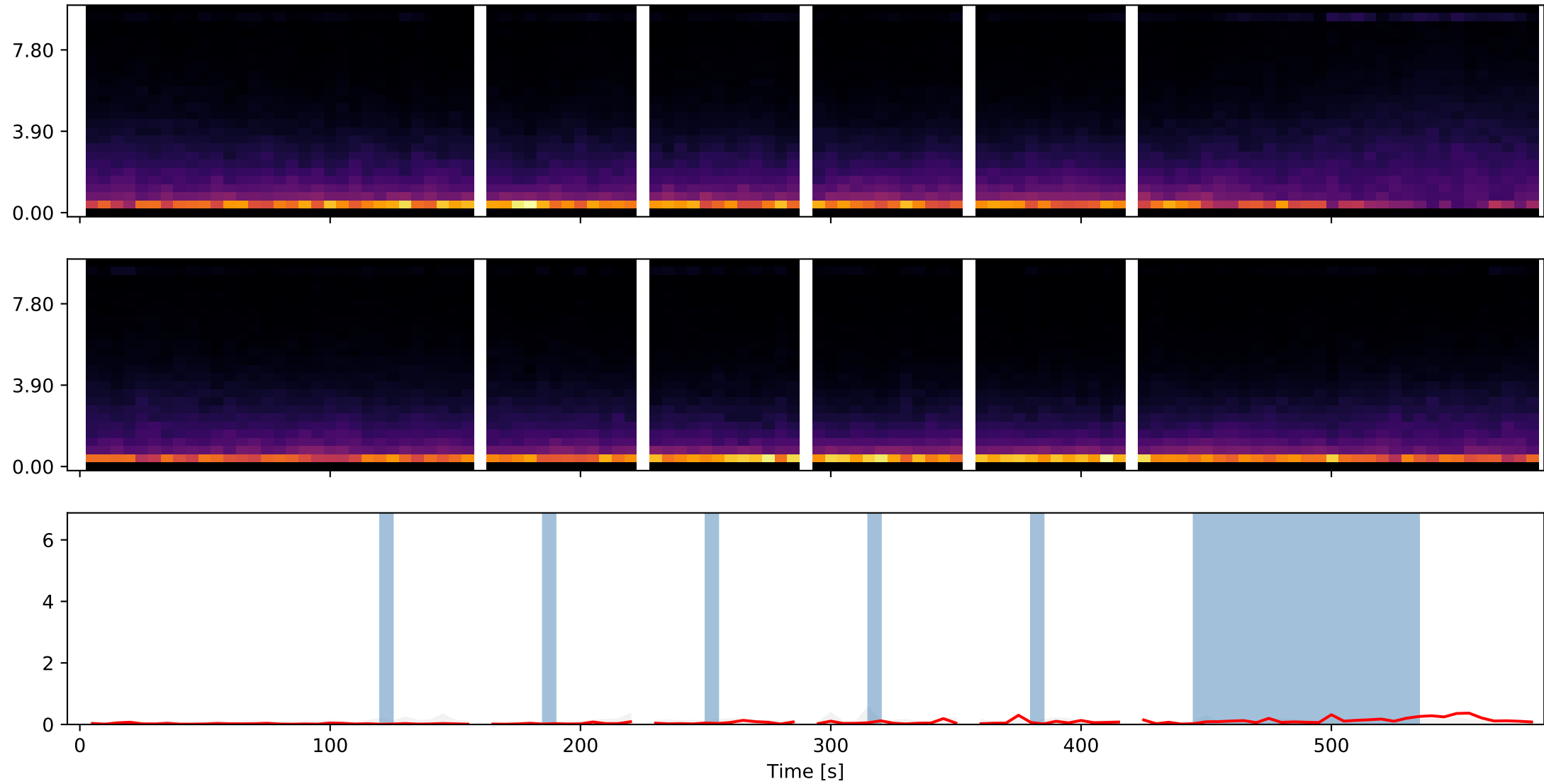
d_relative_to_body_radial_velocity_head_tip



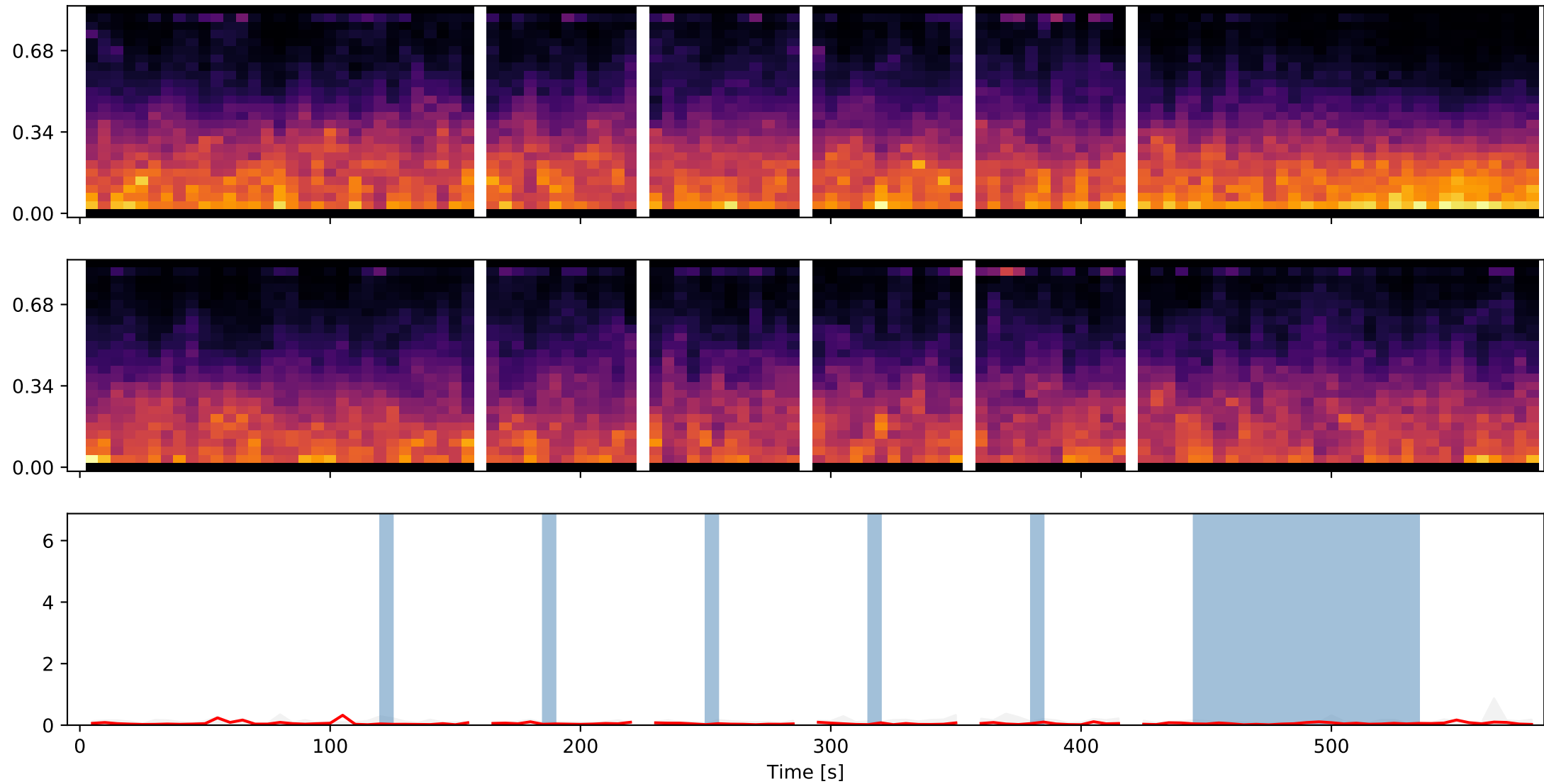
d_relative_to_head_base_angular_velocity_head_tip



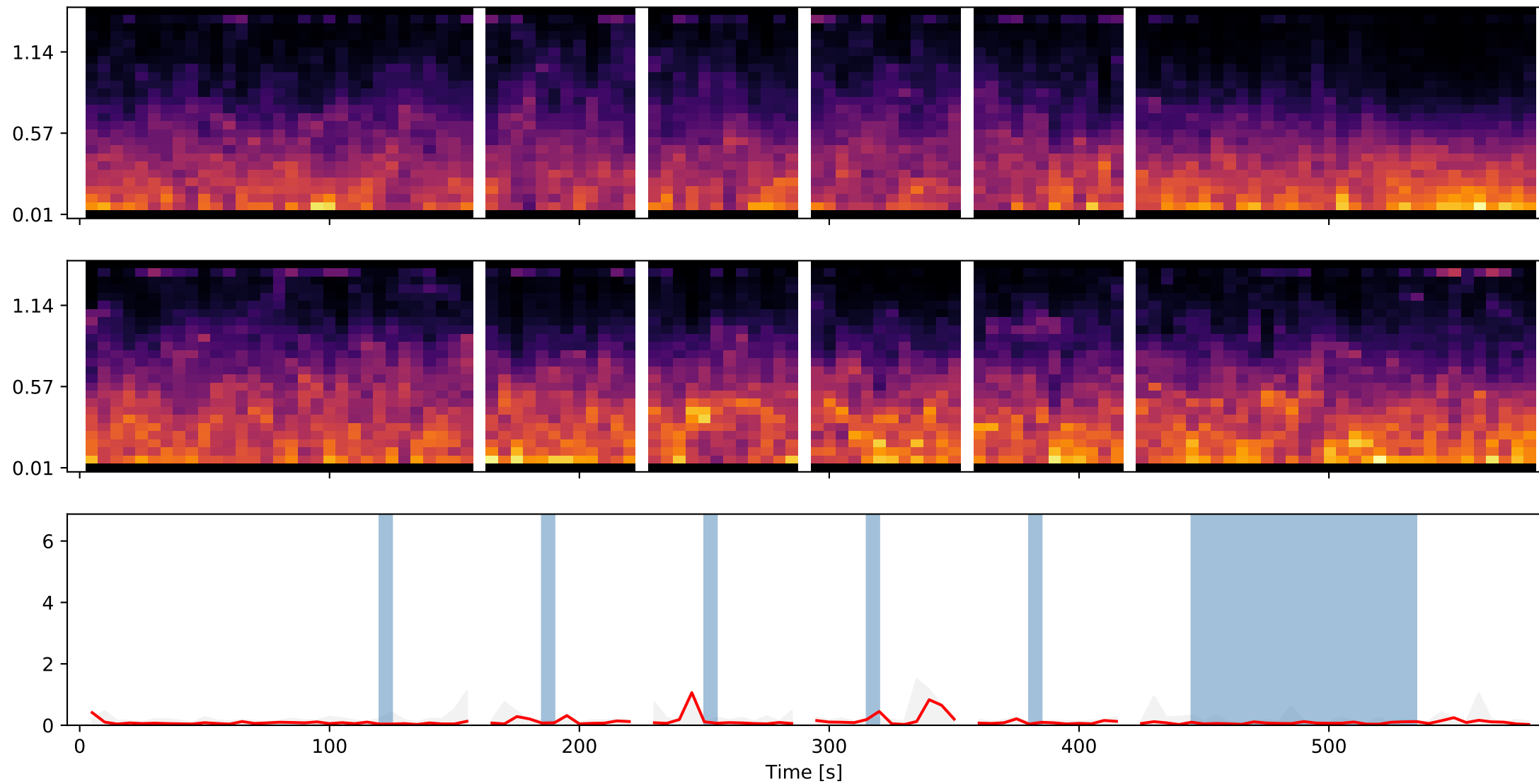
d_angular_velocity_tail_tip



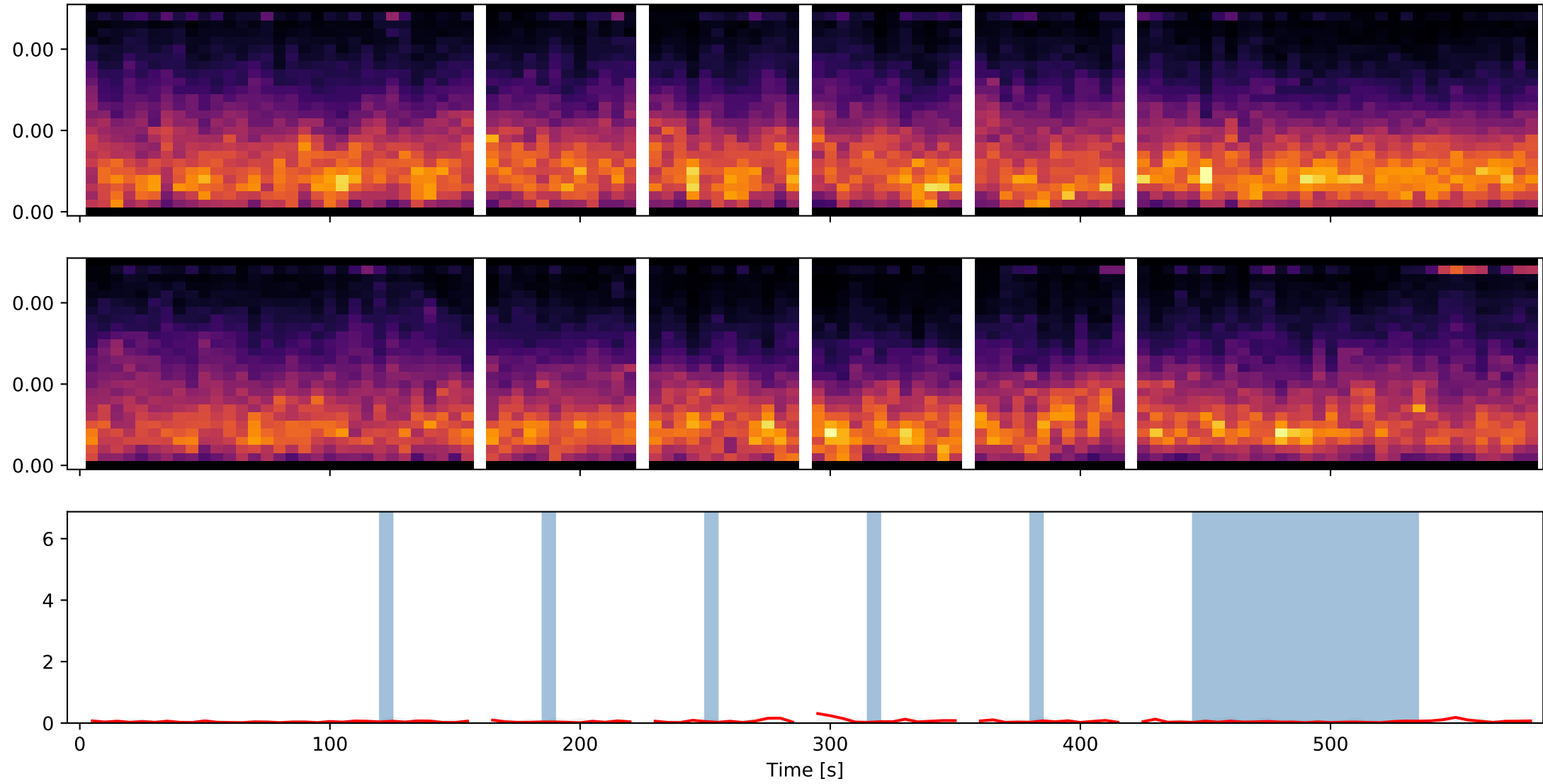
eigen_projection_7



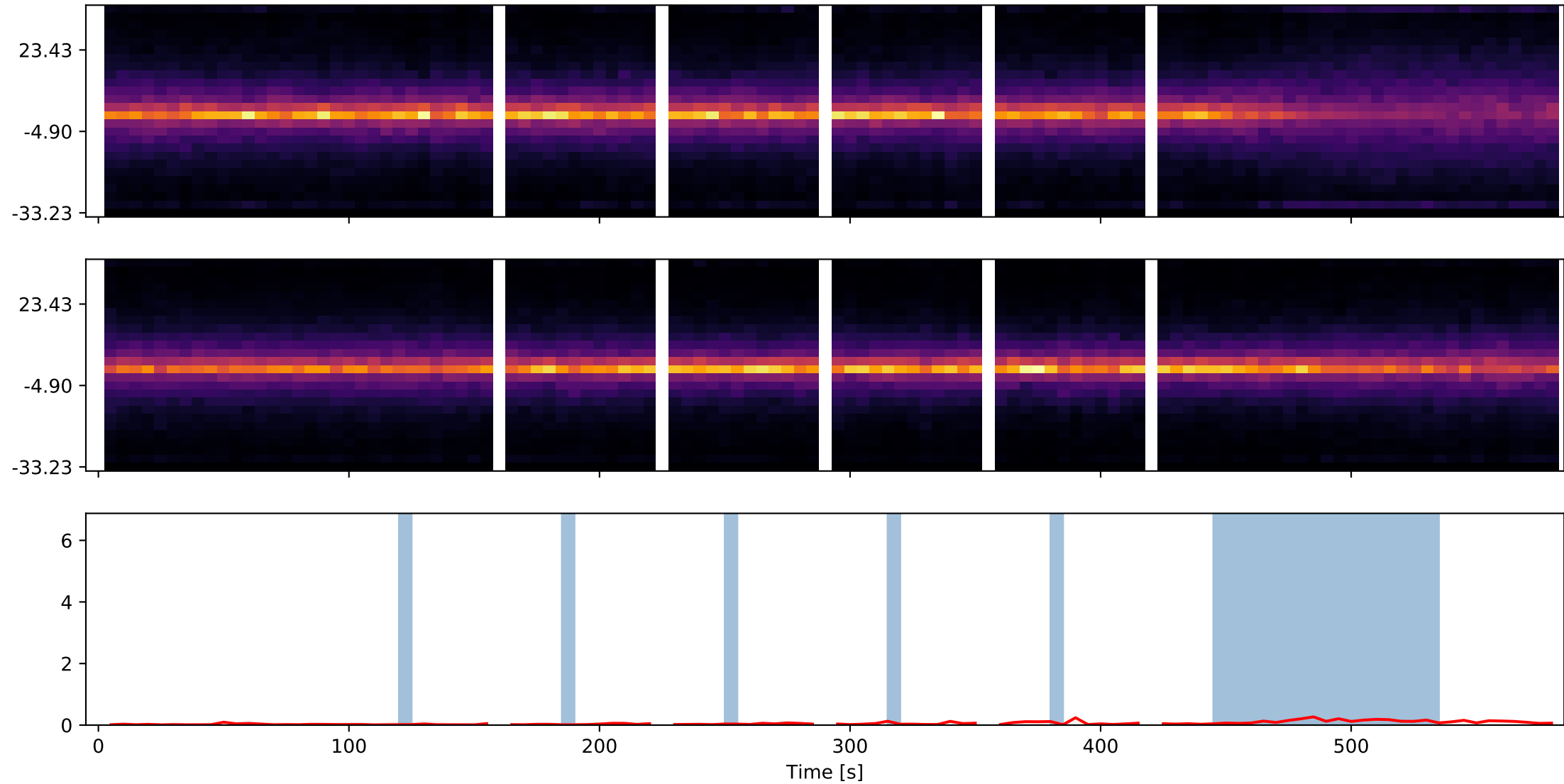
eigen_projection_6



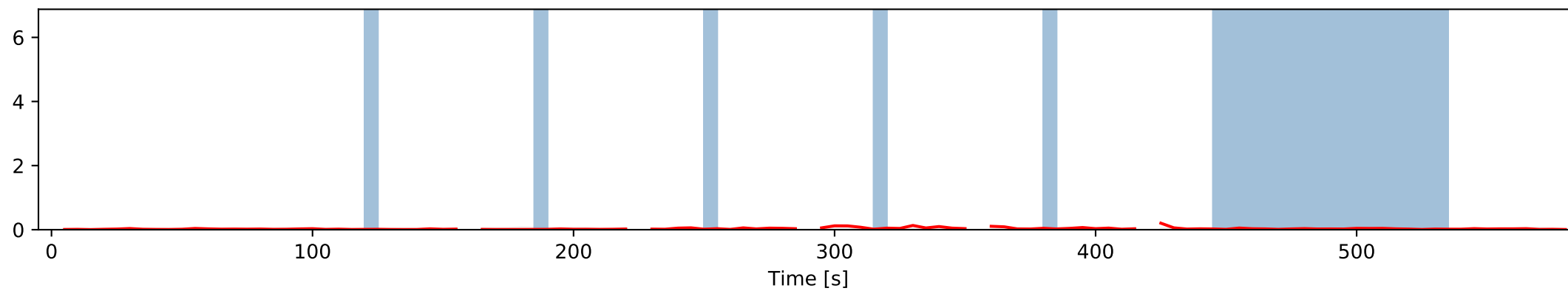
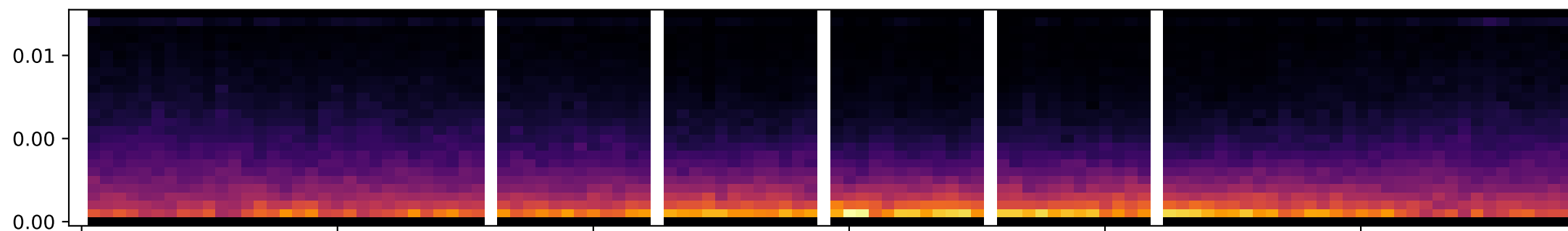
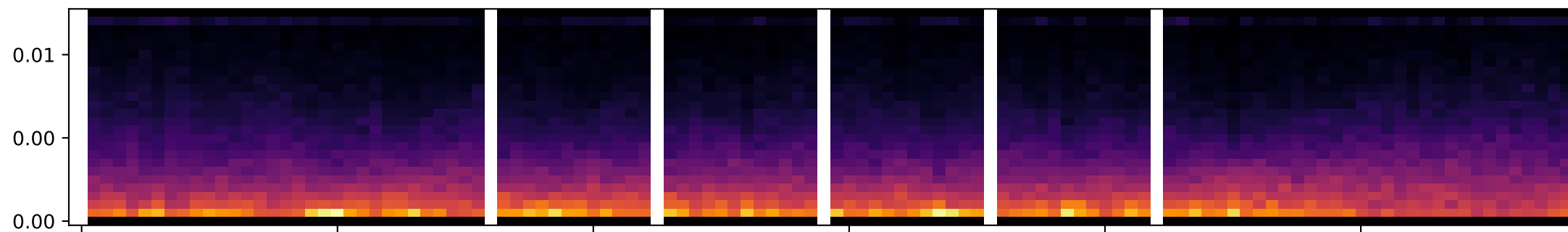
curvature_std_head



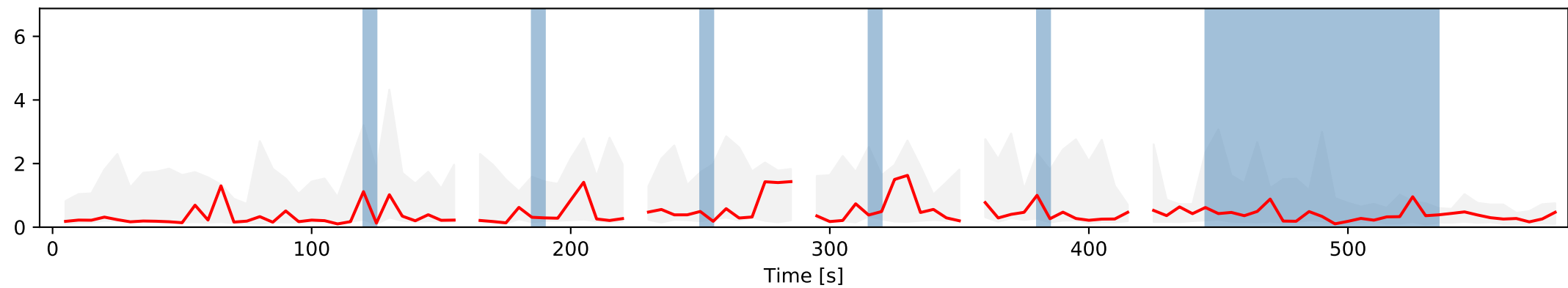
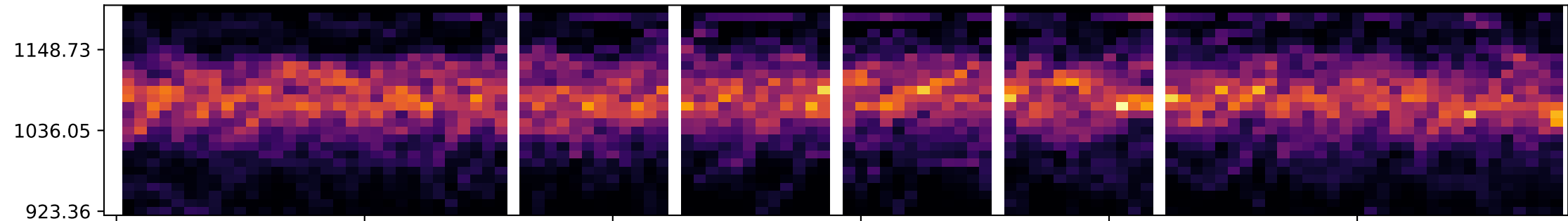
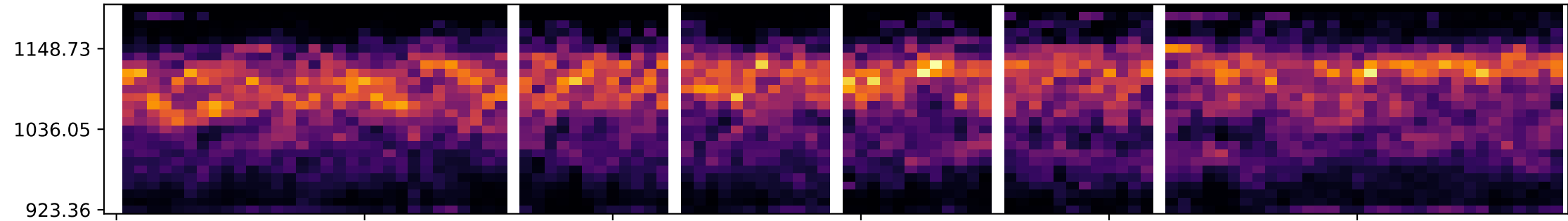
d_width_tail_base



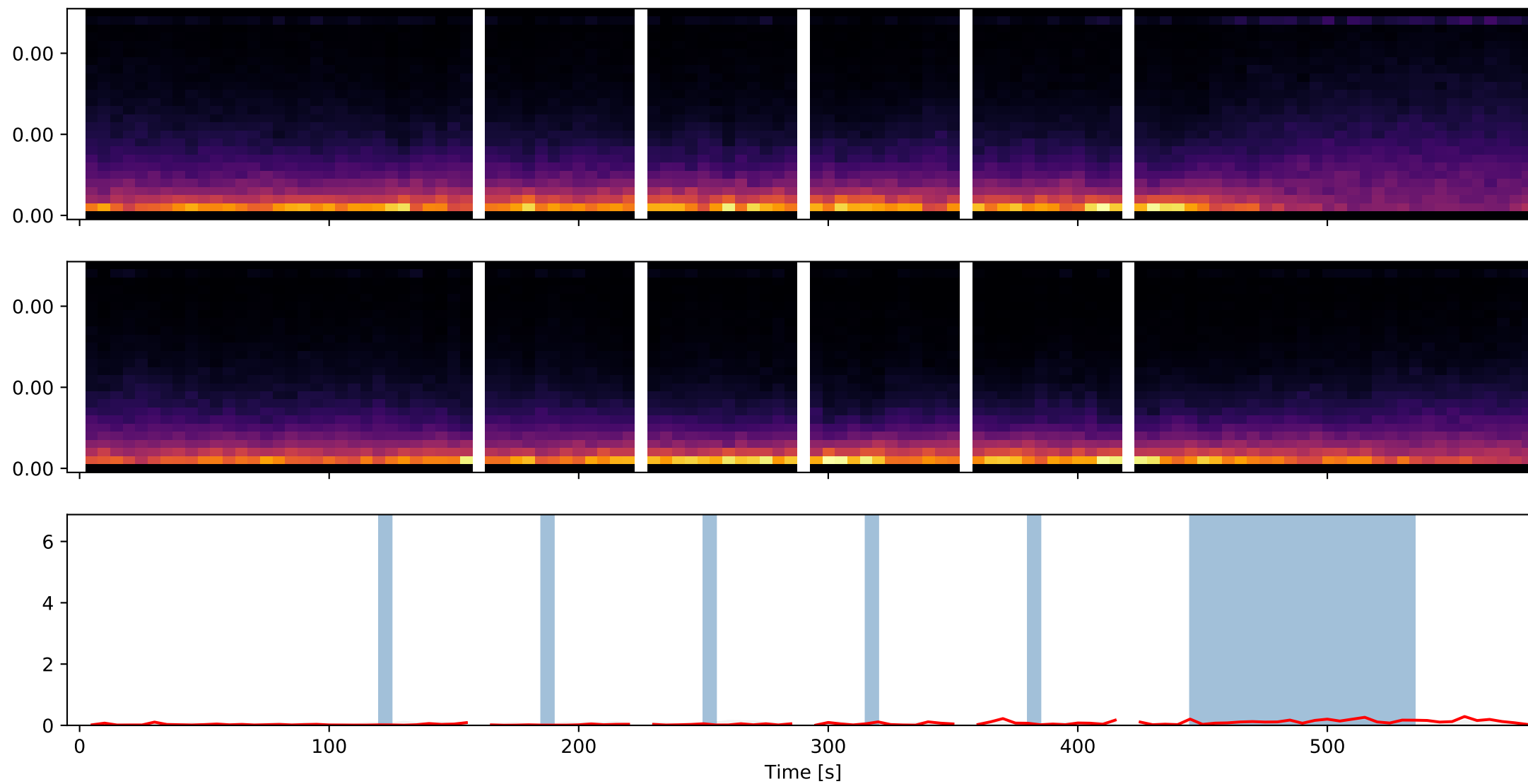
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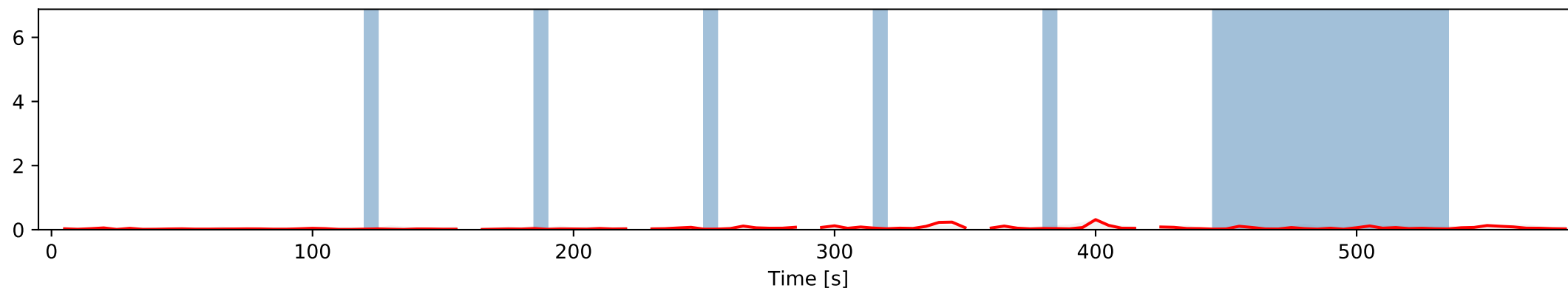
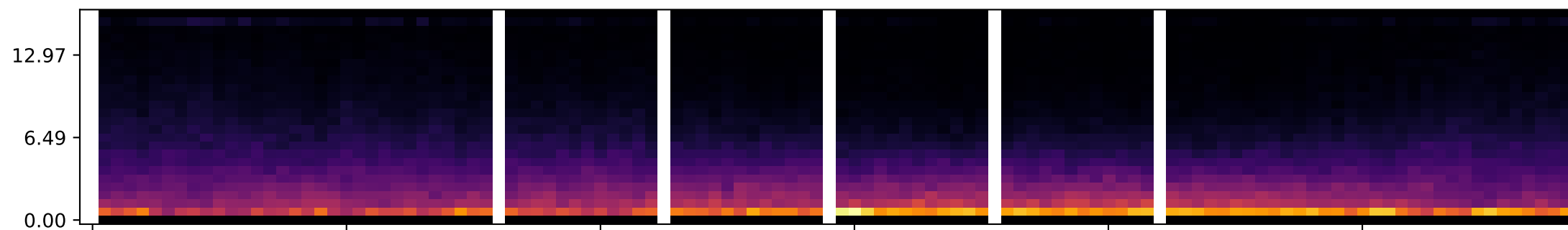
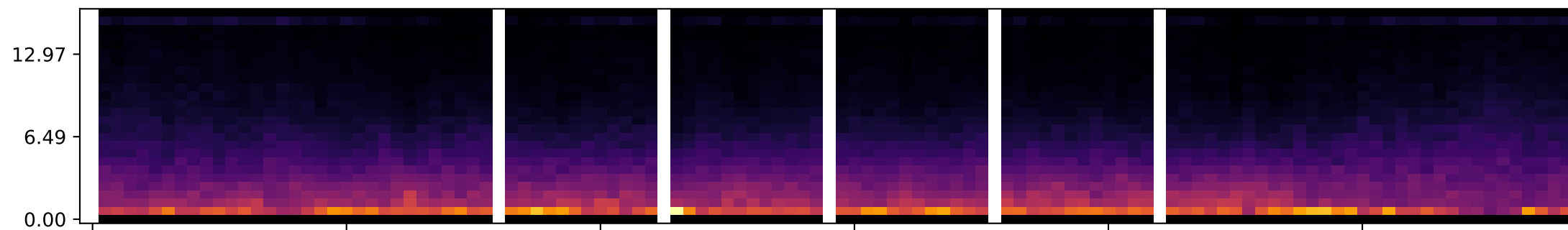
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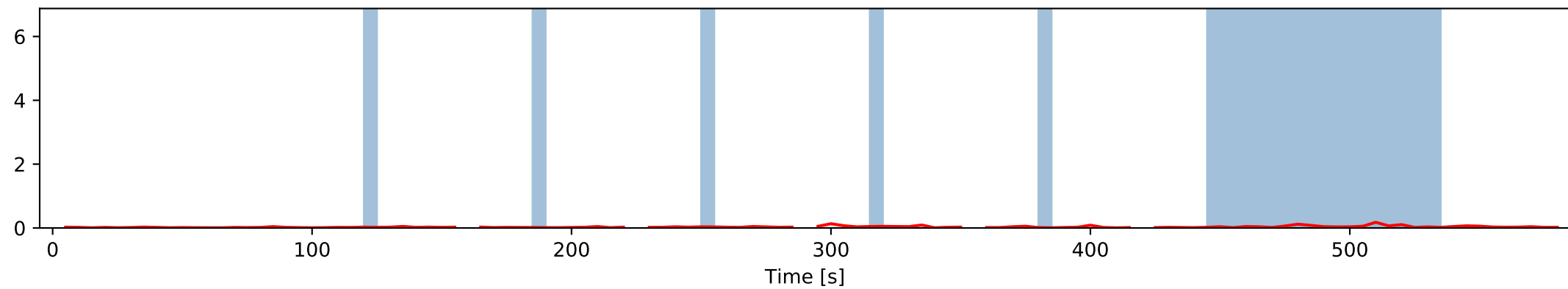
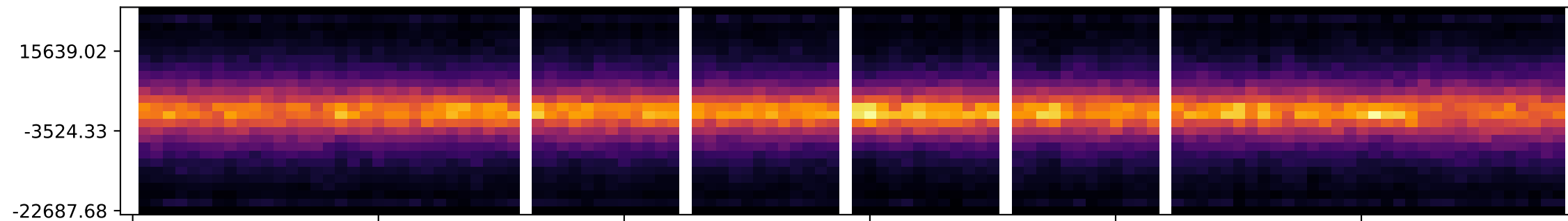
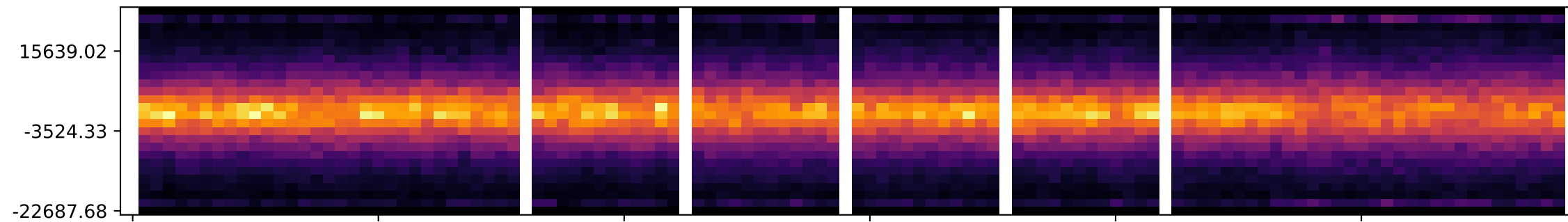
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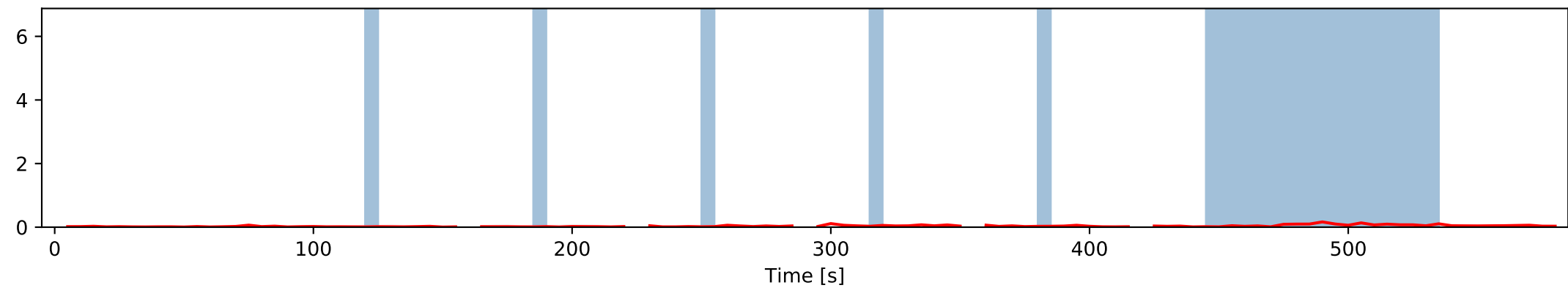
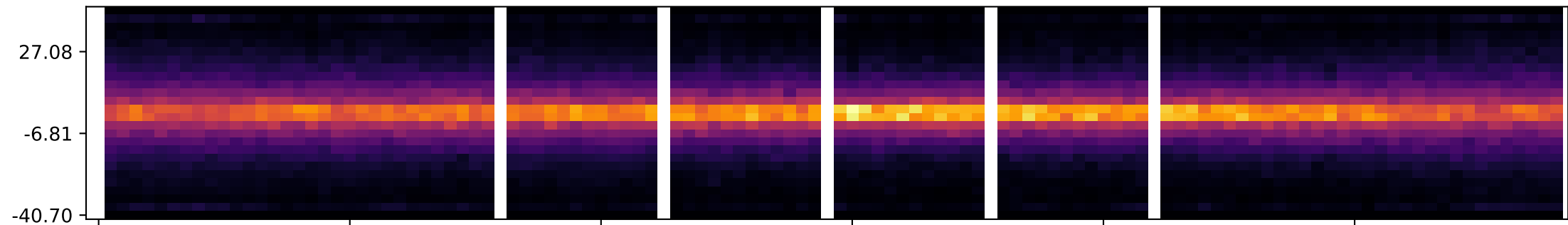
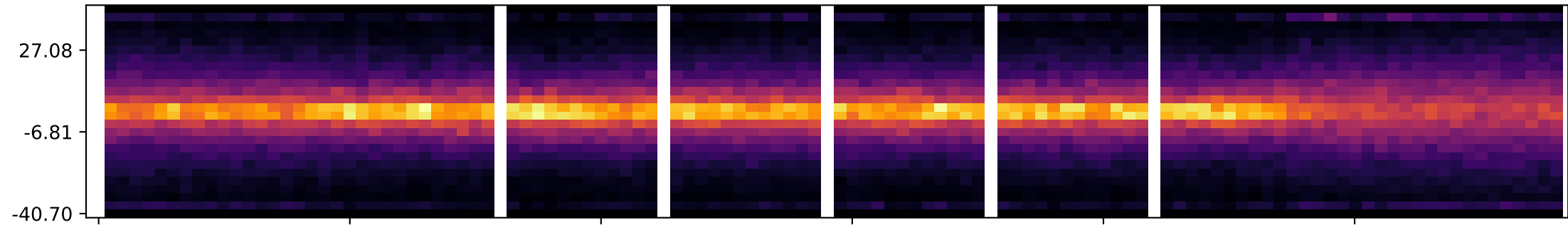
d_angular_velocity_head_tip



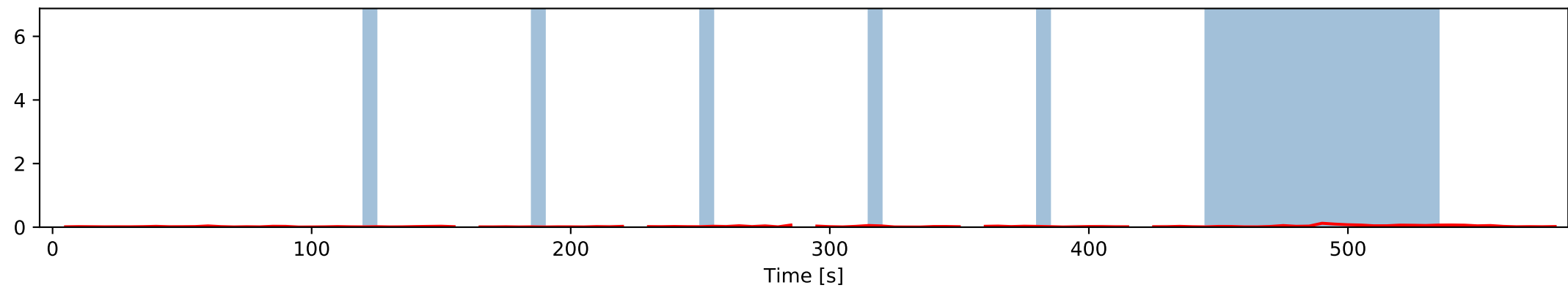
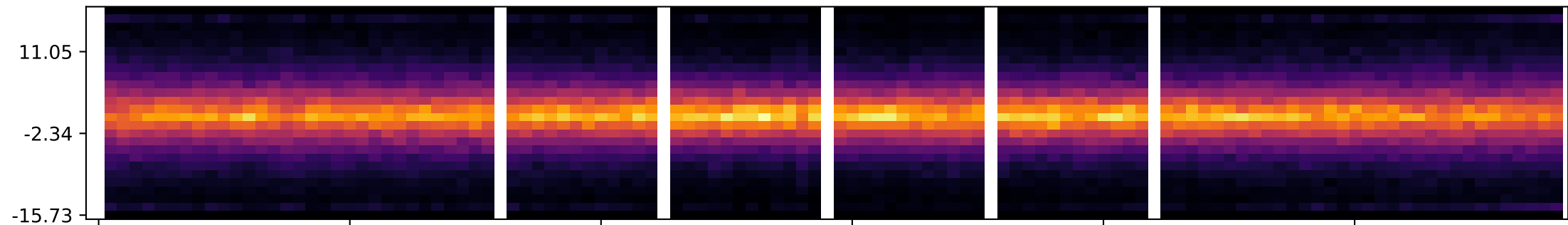
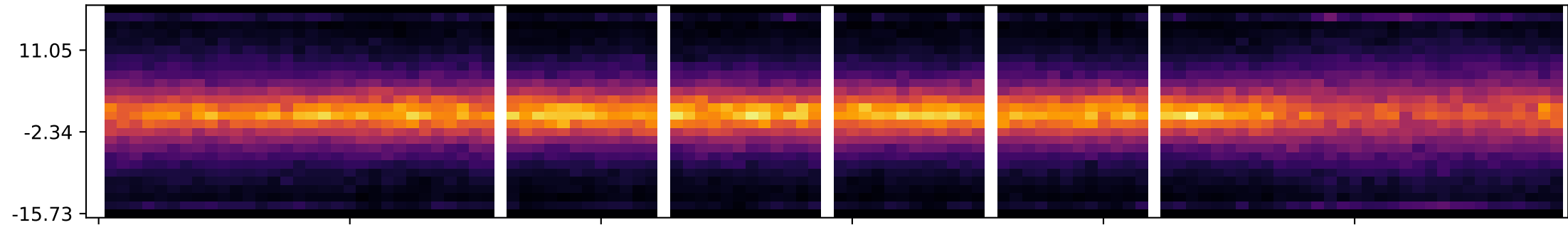
d_area



d_width_head_base



d_width_midbody



d_eigen_projection_7

