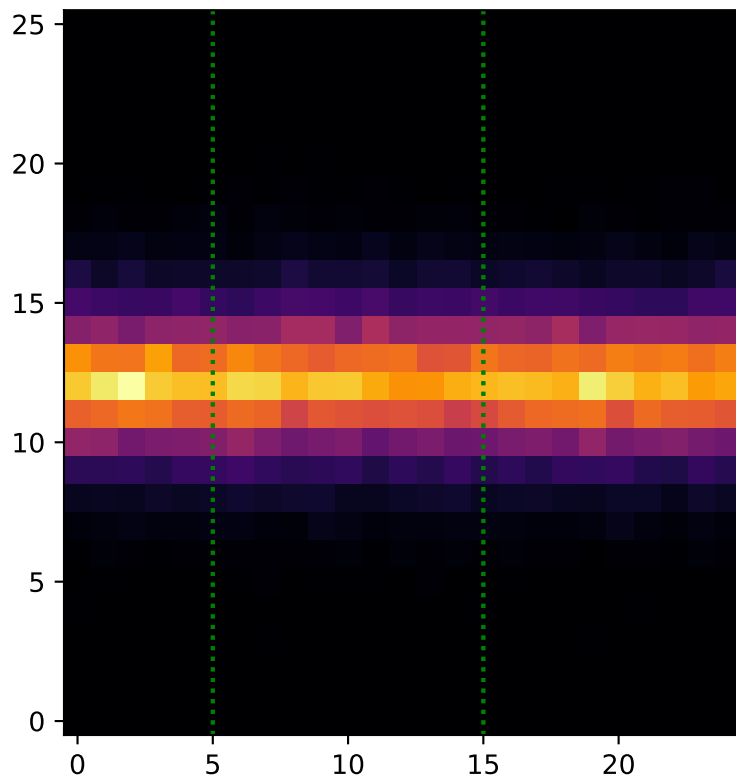
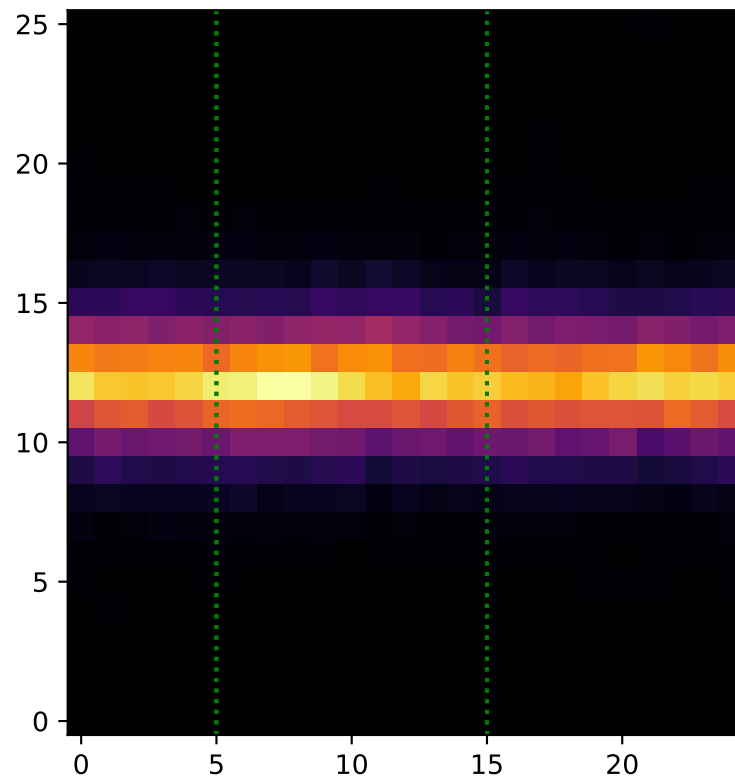


d_area | pval:0.03135135135135135

ctr

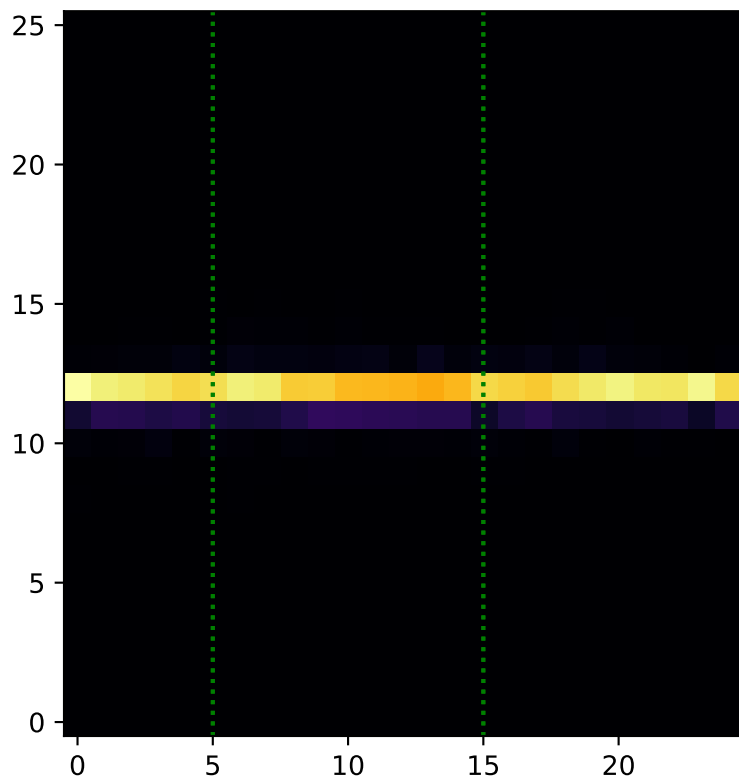


atr

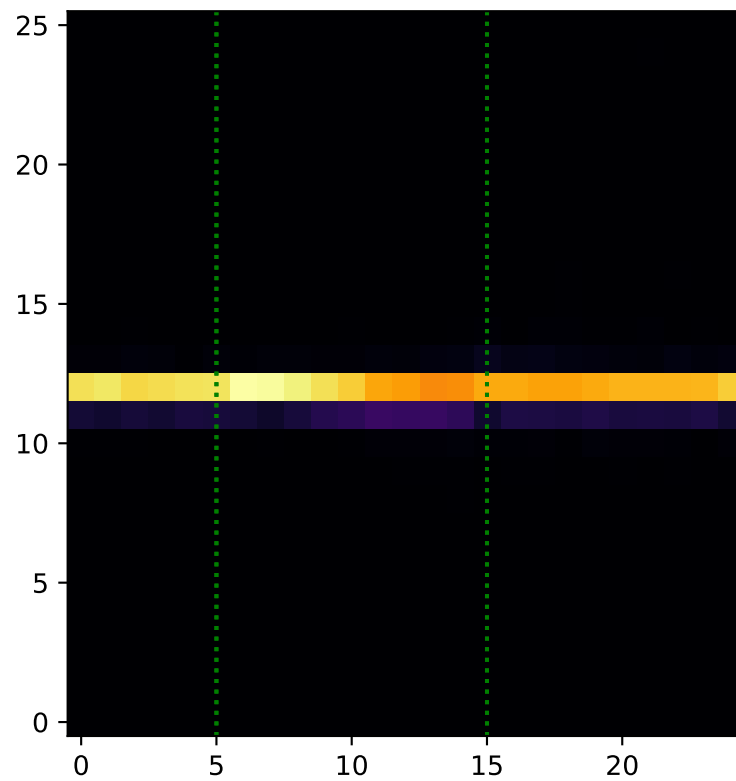


d_quirkiness | pval:0.03783783783783784

ctr

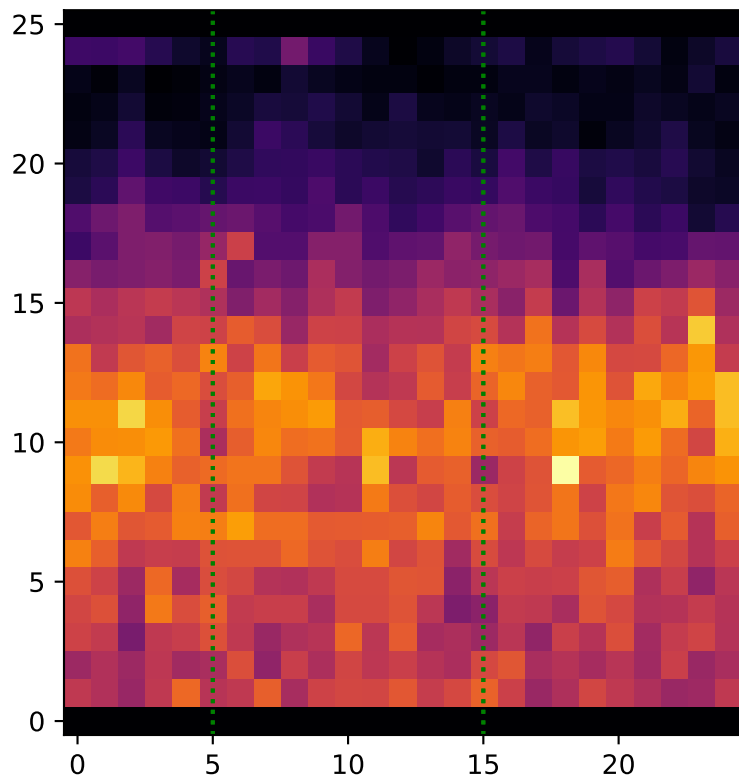


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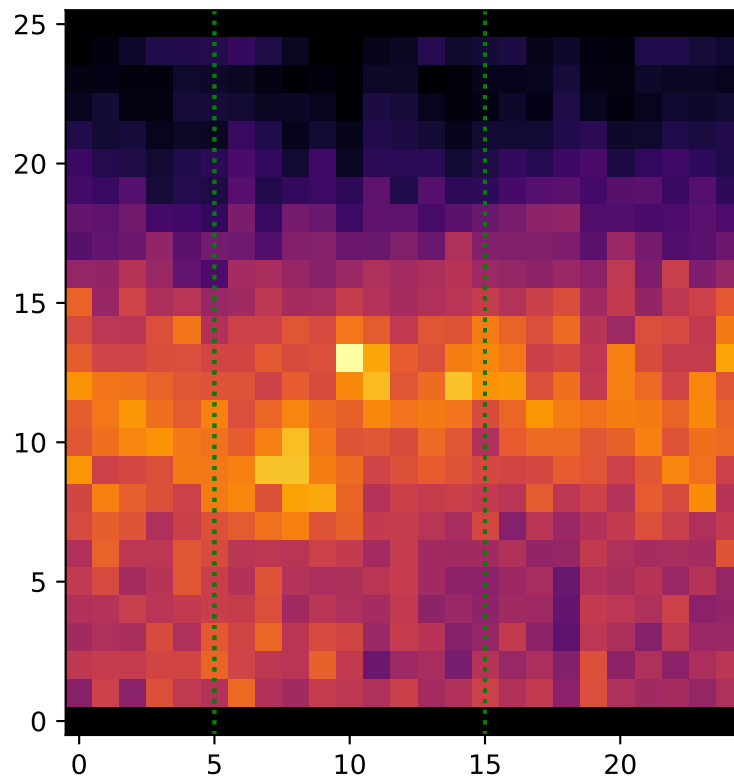


curvature_hips | pval:0.04216216216216216

ctr

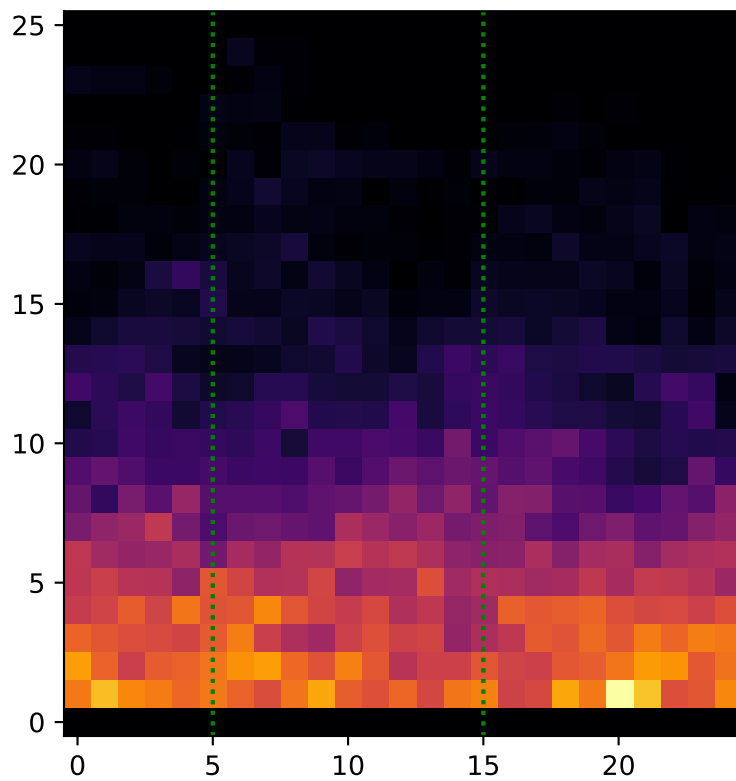


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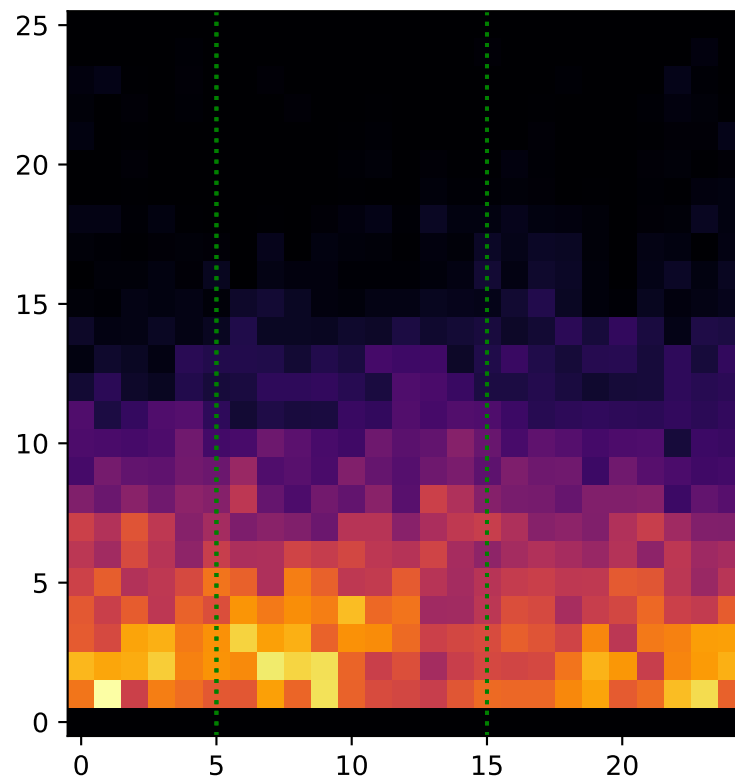


eigen_projection_2 | pval:0.04432432432432432

ctr

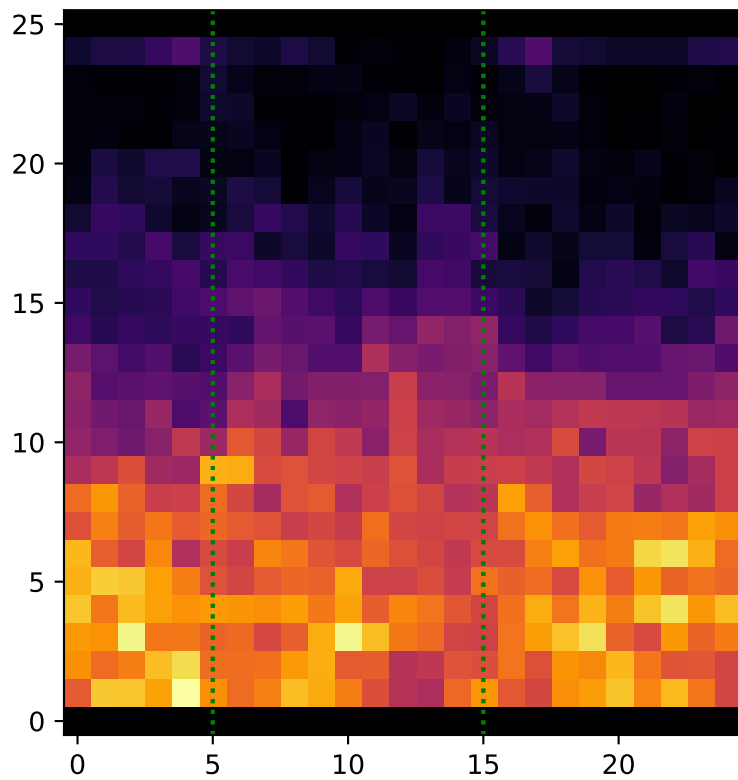


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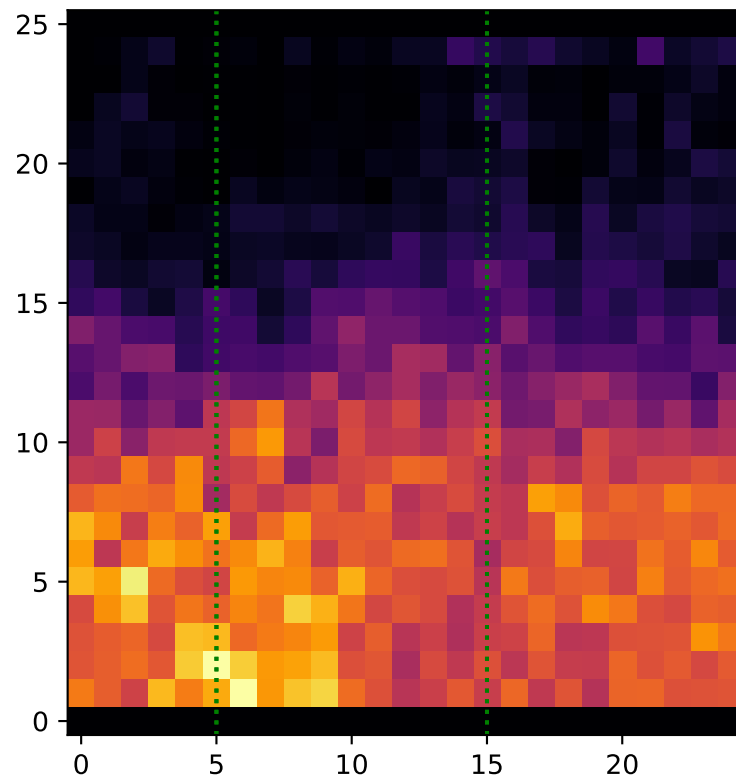


curvature_mean_midbody | pval:0.07243243243243243

ctr

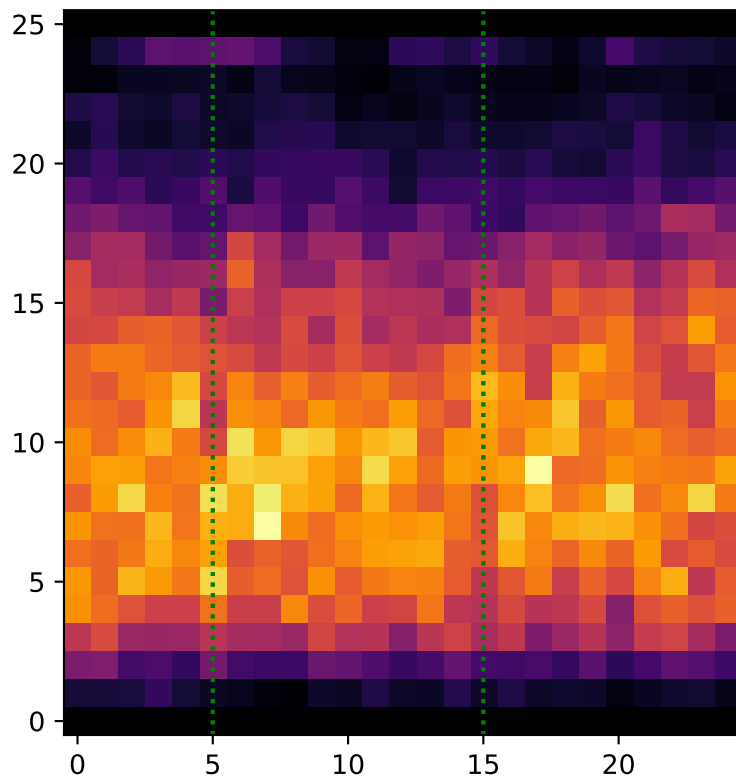


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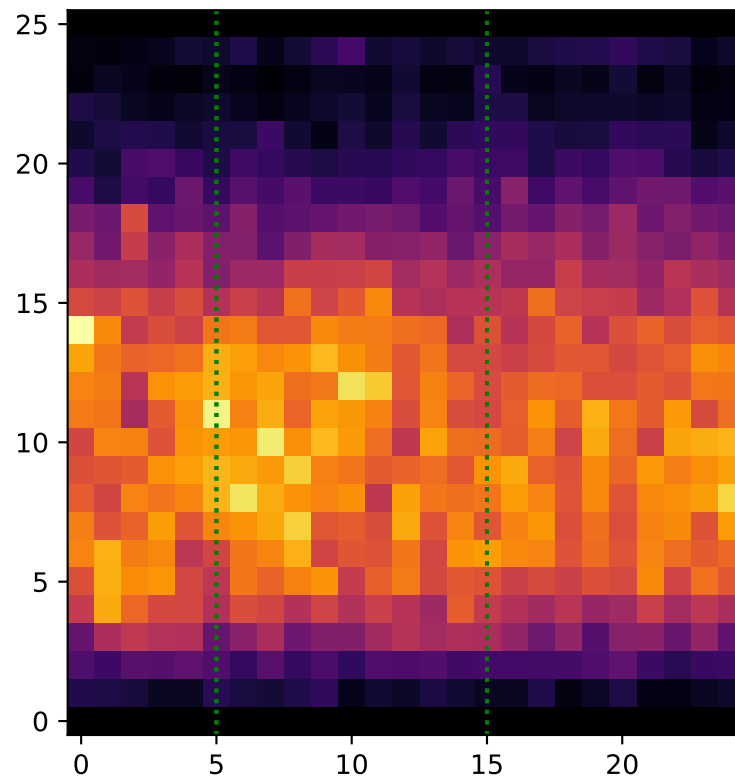


curvature_std_hips | pval:0.08540540540540541

ctr

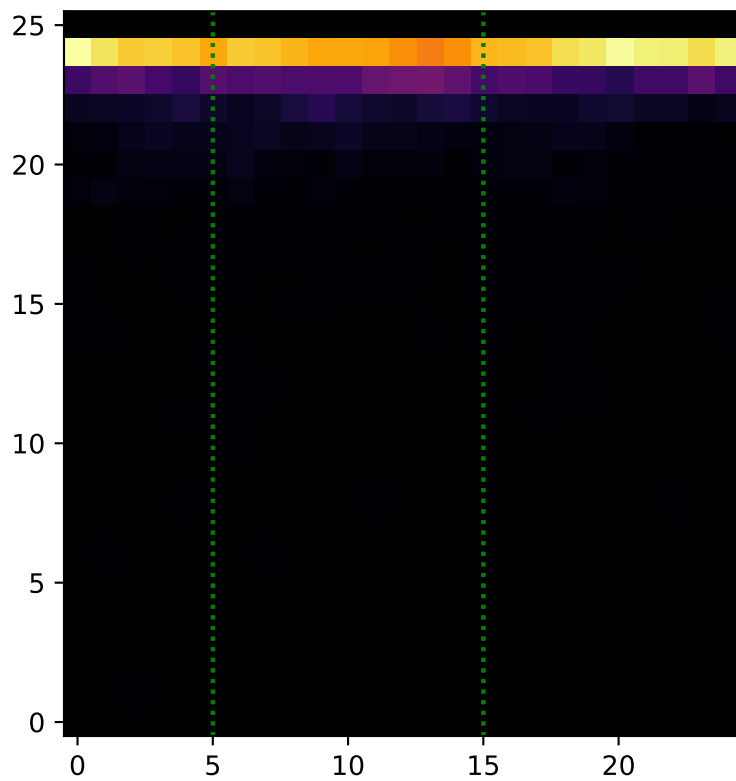


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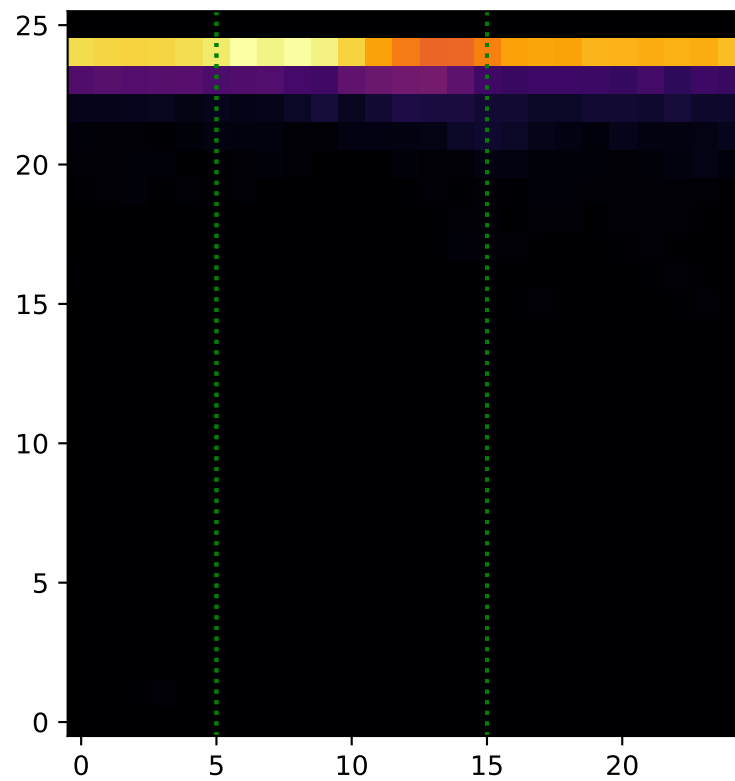


quirkiness | pval:0.09405405405405405

ctr

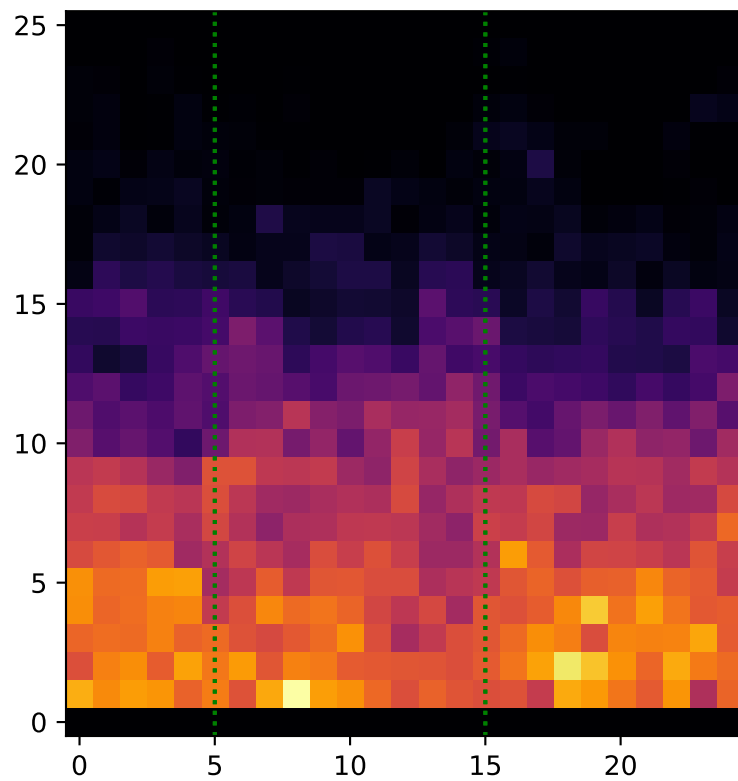


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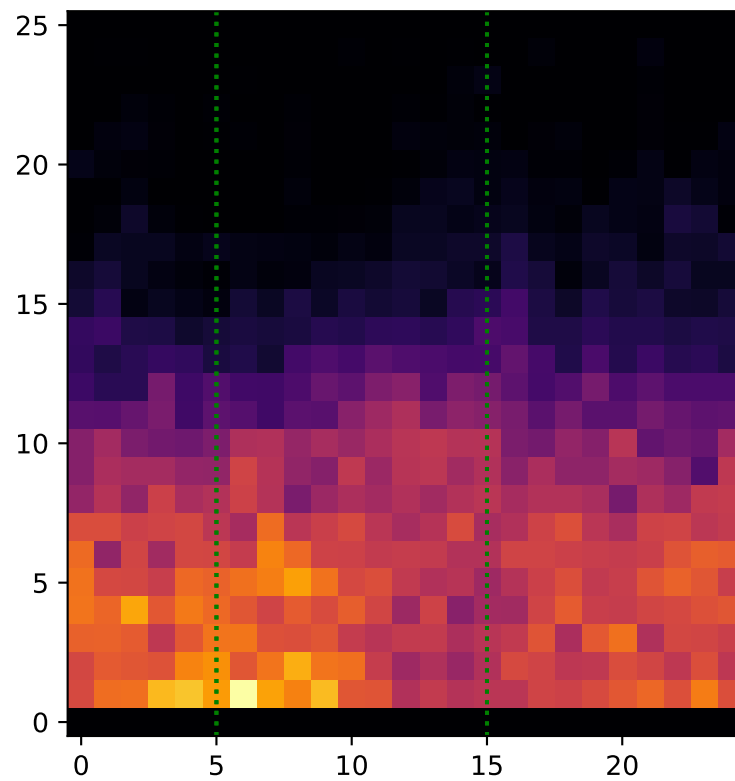


eigen_projection_3 | pval:0.10702702702702703

ctr

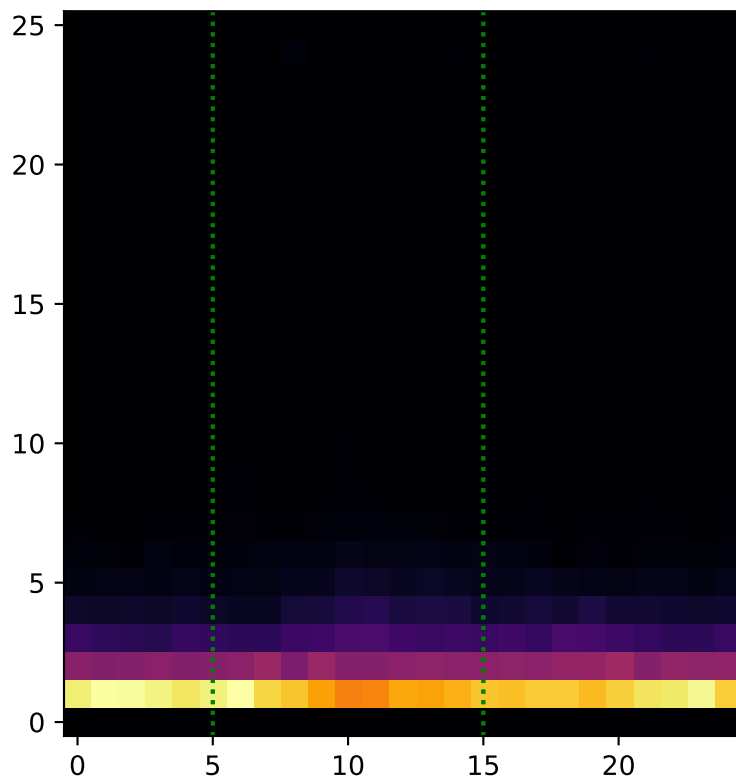


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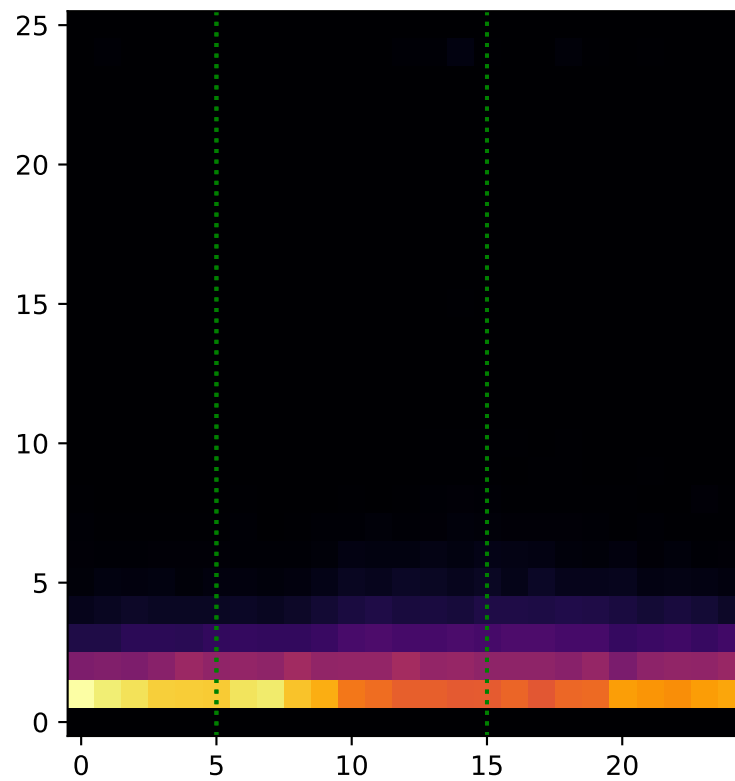


d_angular_velocity | pval:0.19567567567567568

ctr

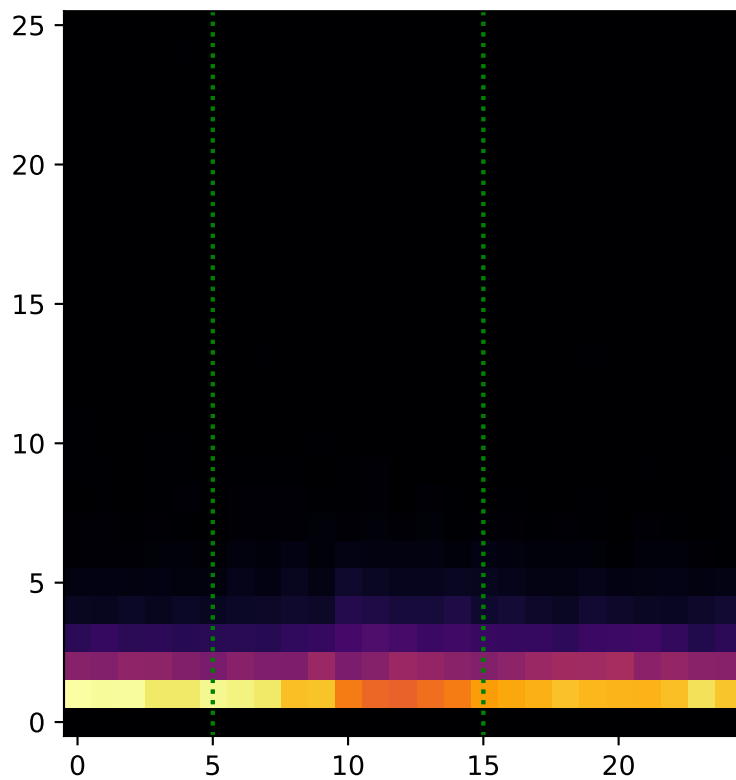


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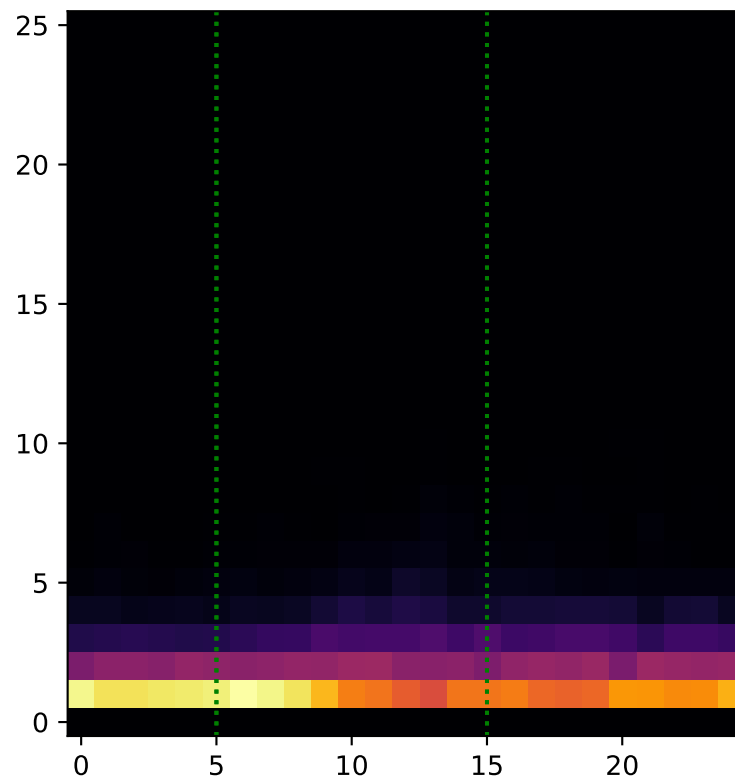


d_relative_to_body_angular_velocity_tail_tip | pval:0.2064864864864865

ctr

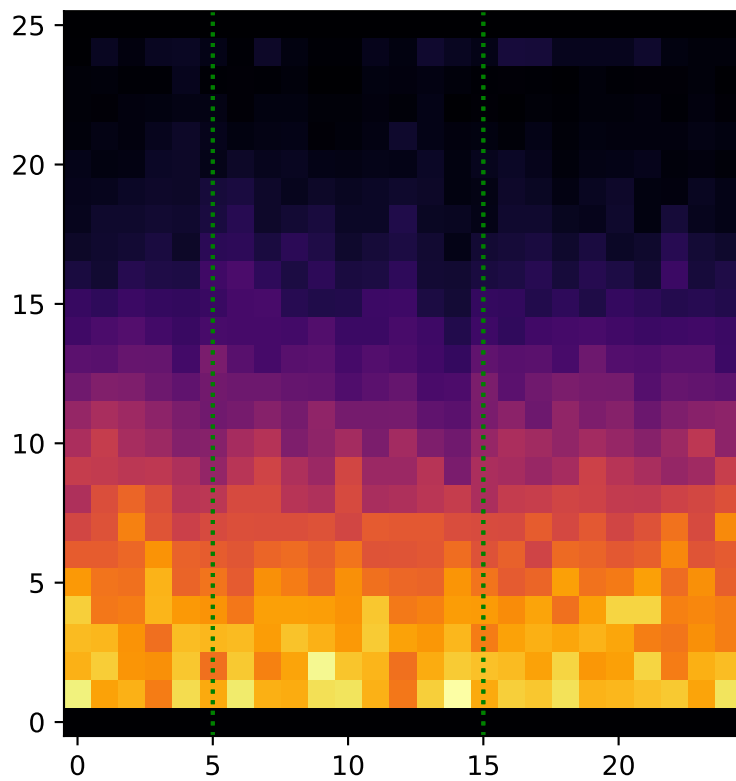


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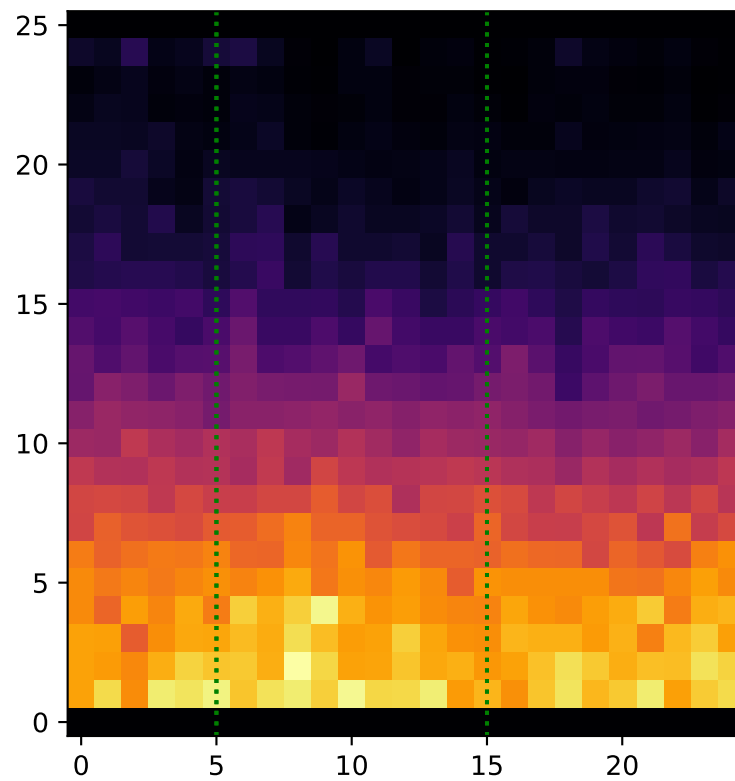


eigen_projection_7 | pval:0.21297297297297296

ctr

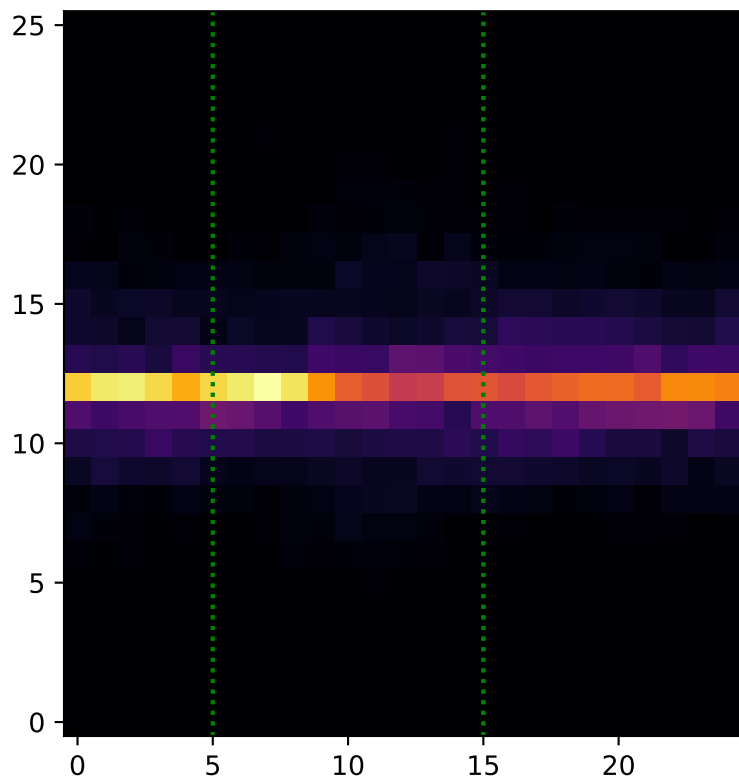


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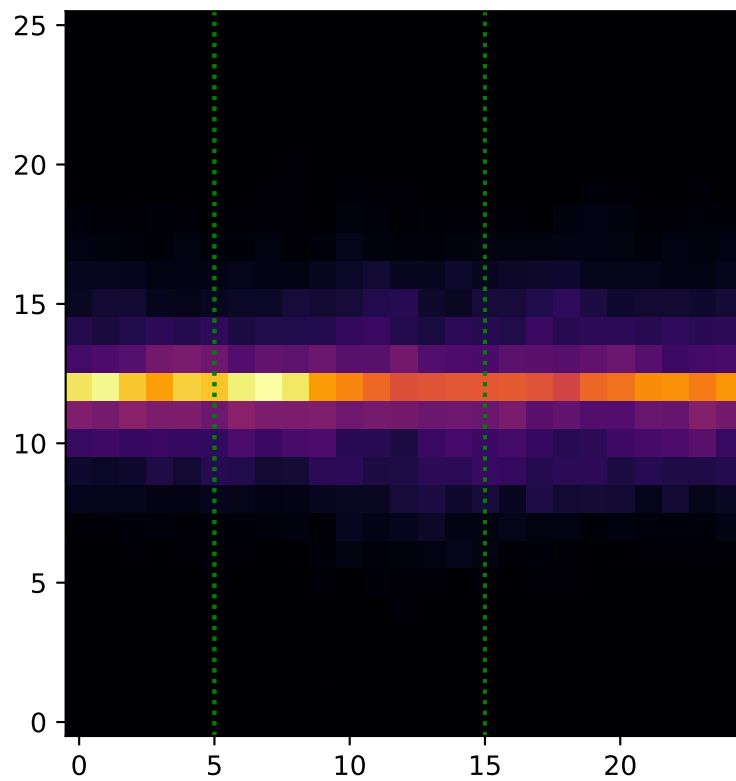


d_dist_from_food_edge | pval:0.22378378378378377

ctr

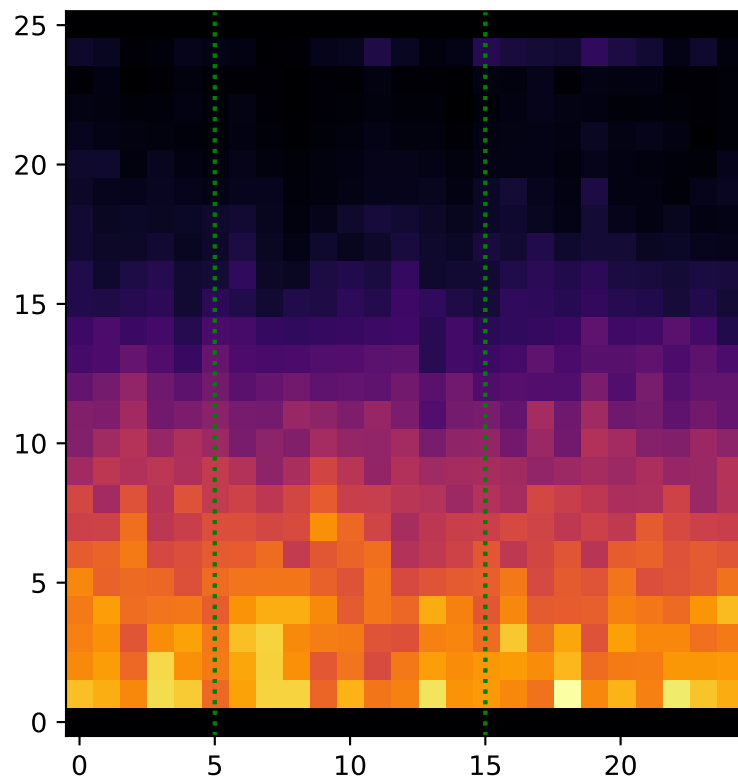


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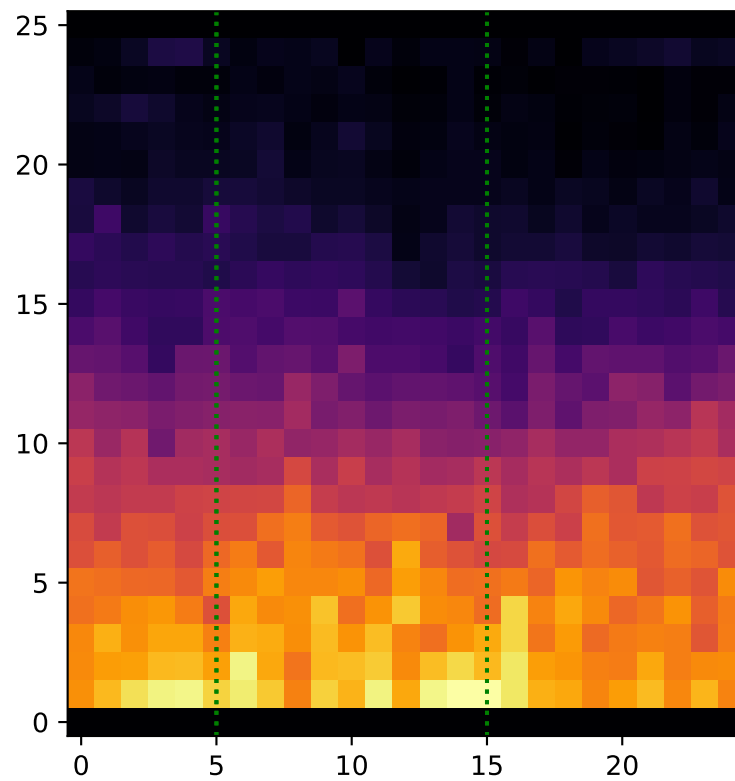


eigen_projection_6 | pval:0.23027027027027028

ctr

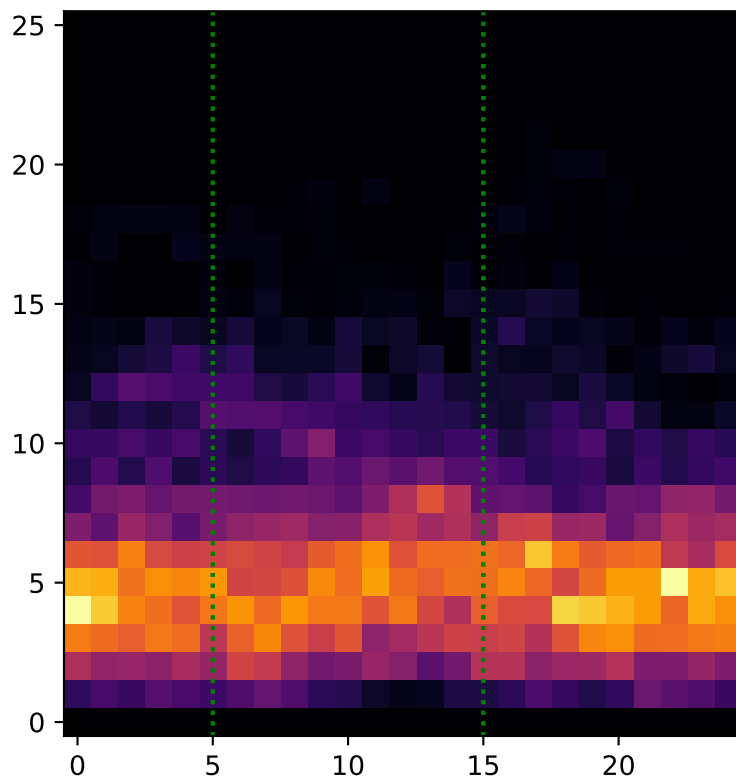


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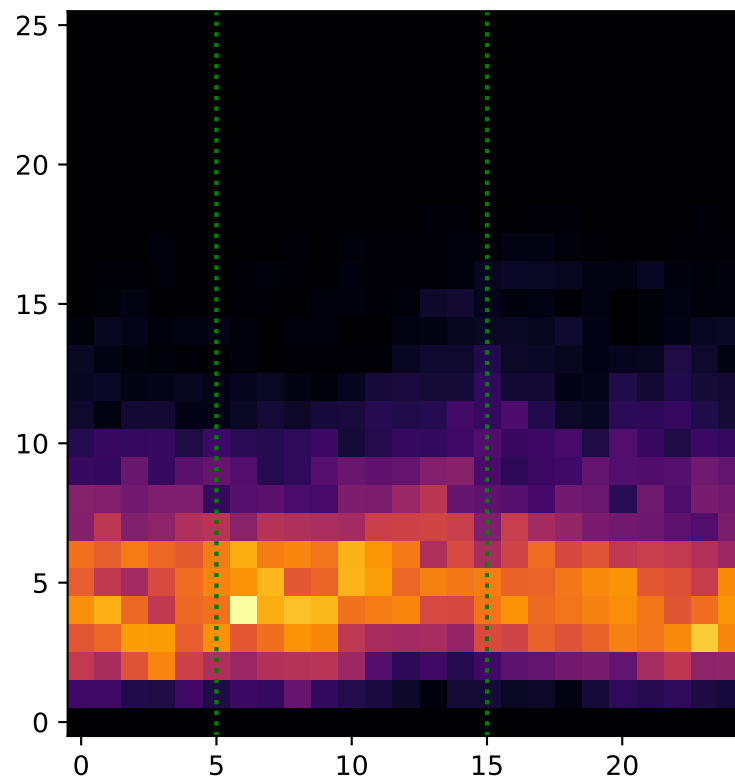


minor_axis | pval:0.23243243243243245

ctr

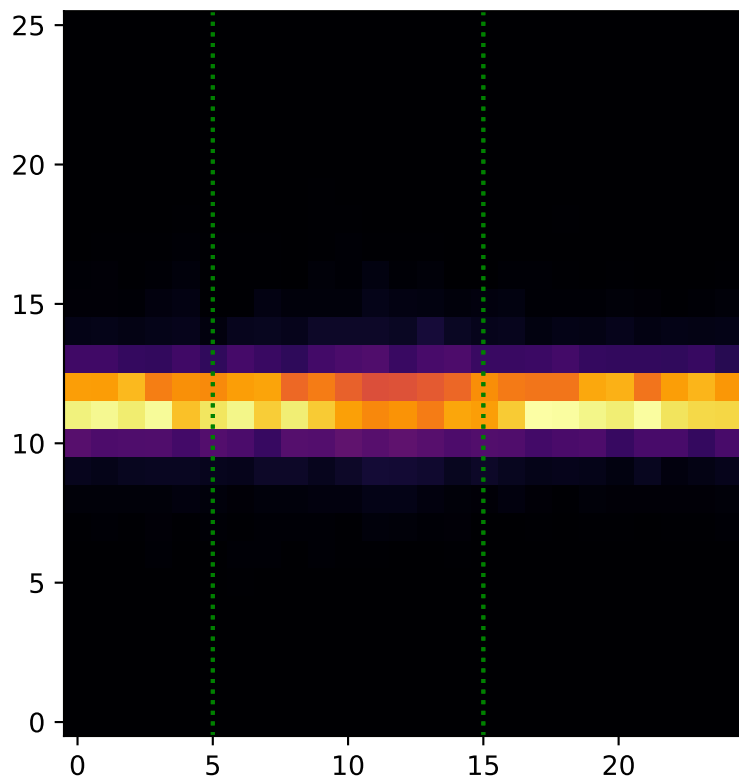


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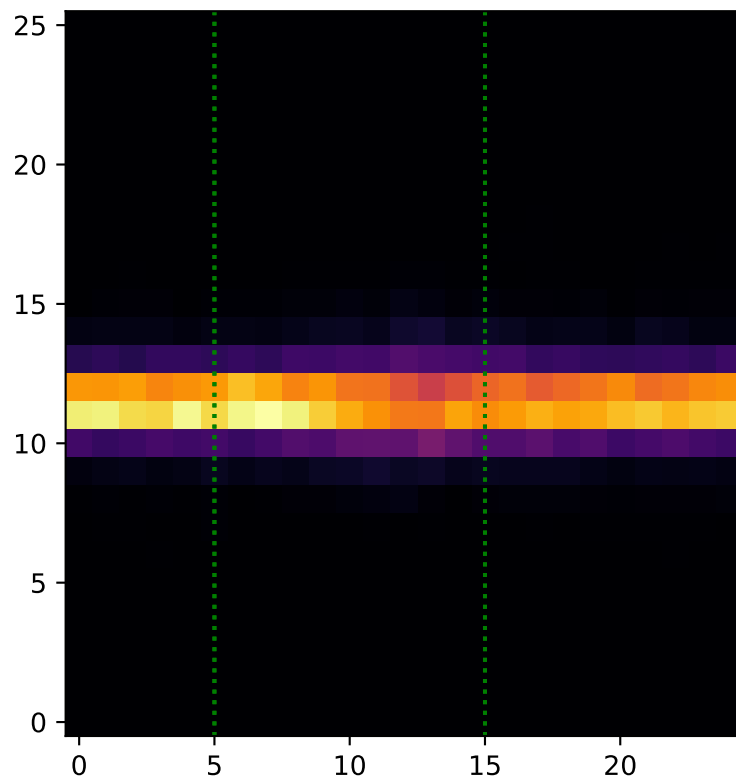


d_relative_to_body_radial_velocity_neck | pval:0.23243243243243245

ctr

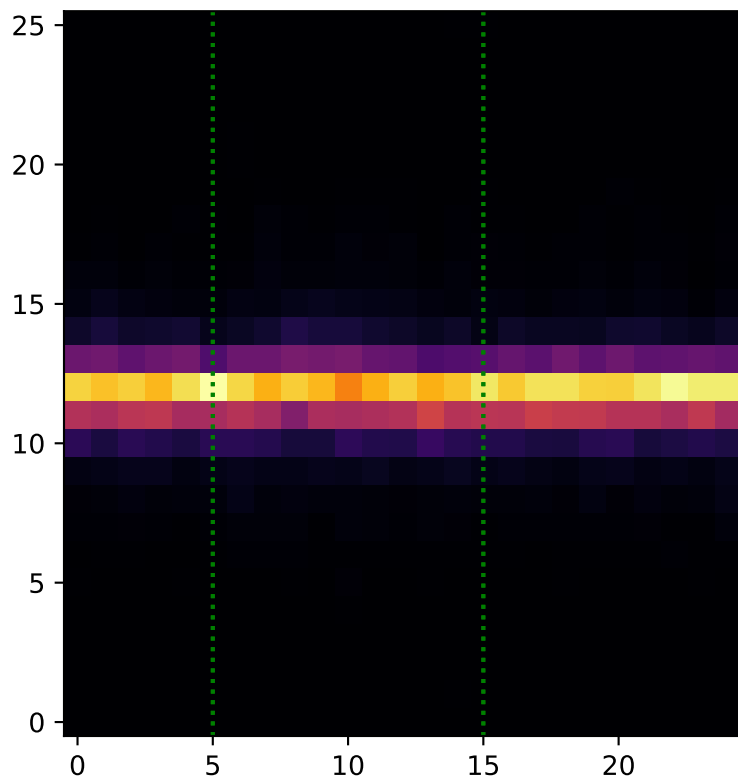


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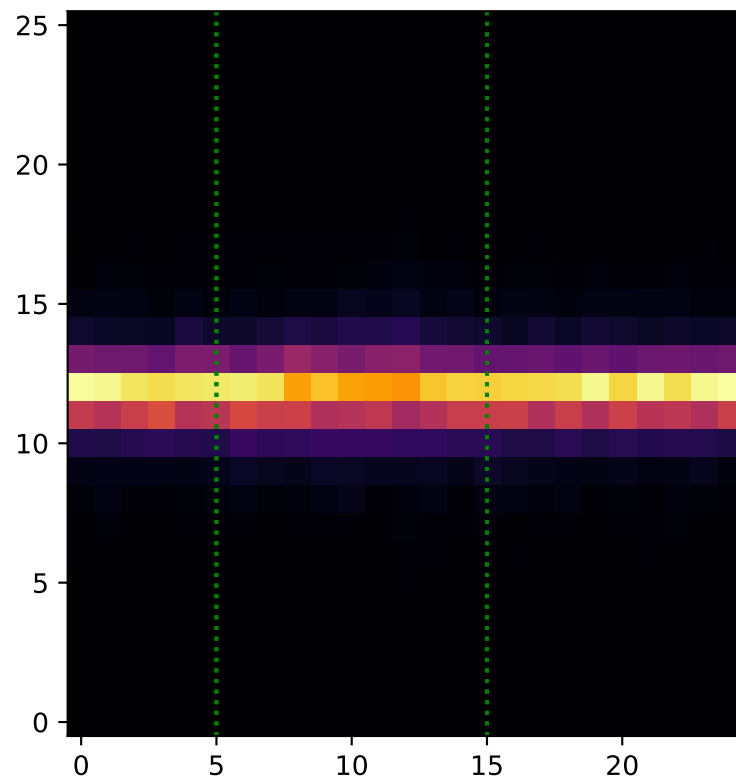


d_speed_tail_tip | pval:0.23243243243243245

ctr

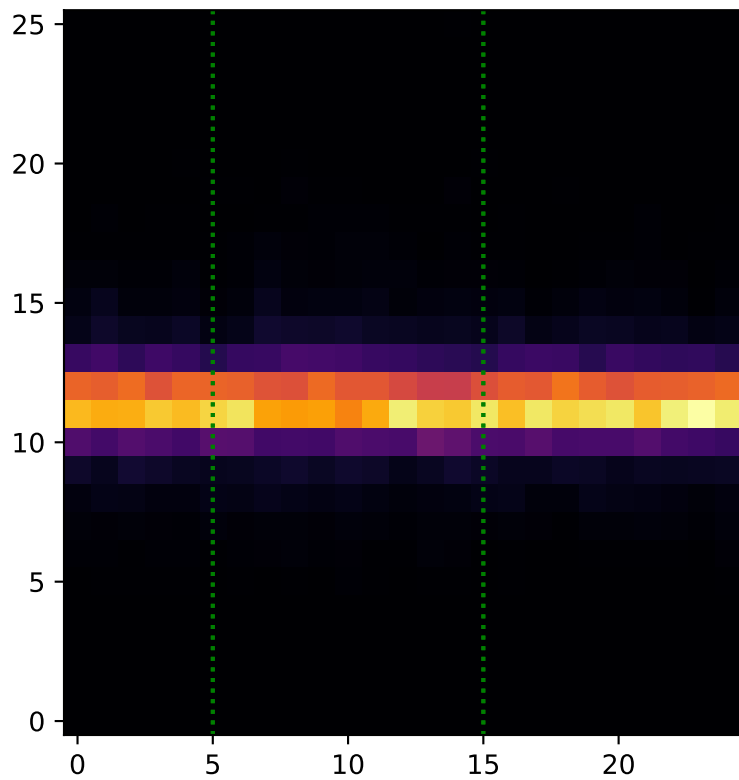


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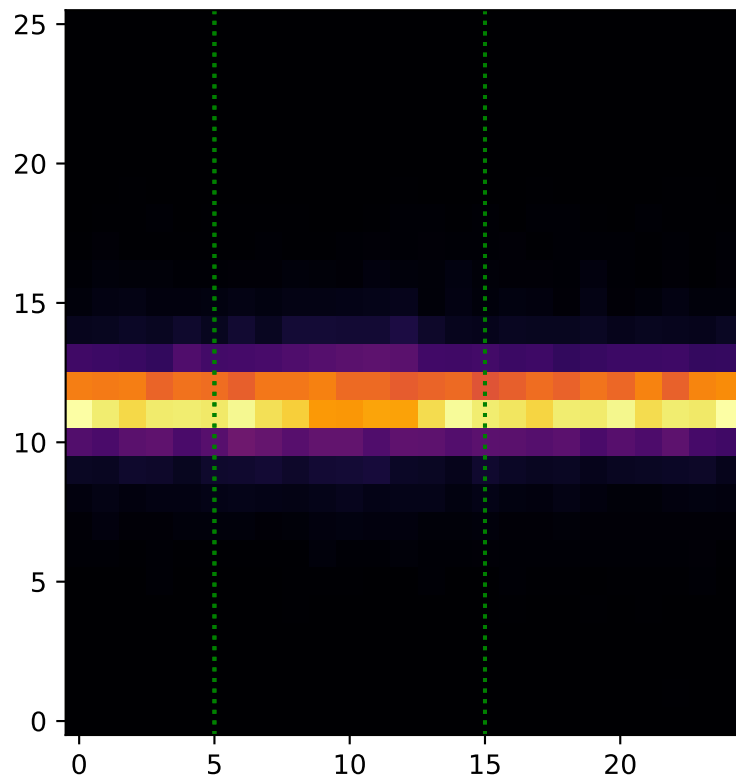


d_speed_neck | pval:0.28

ctr

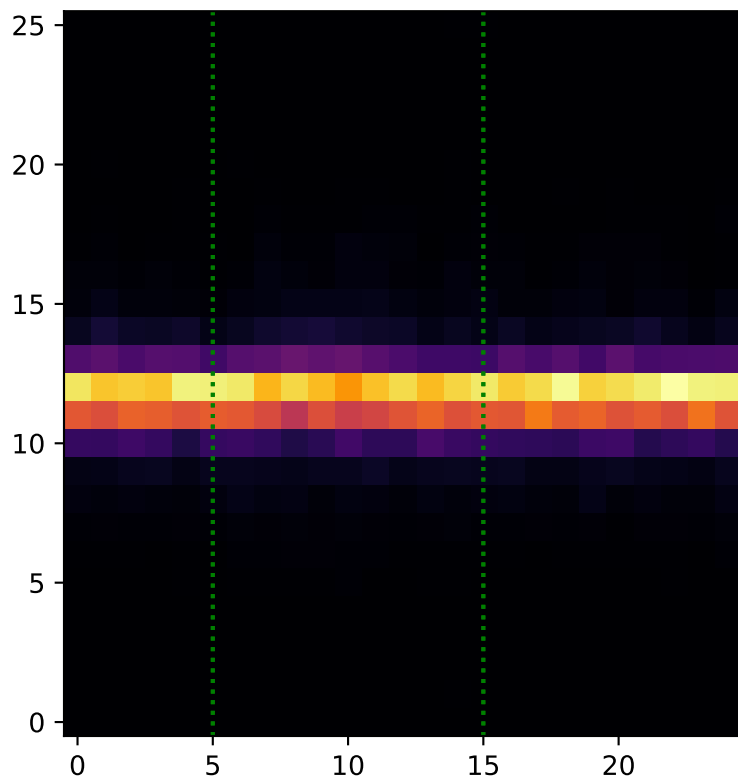


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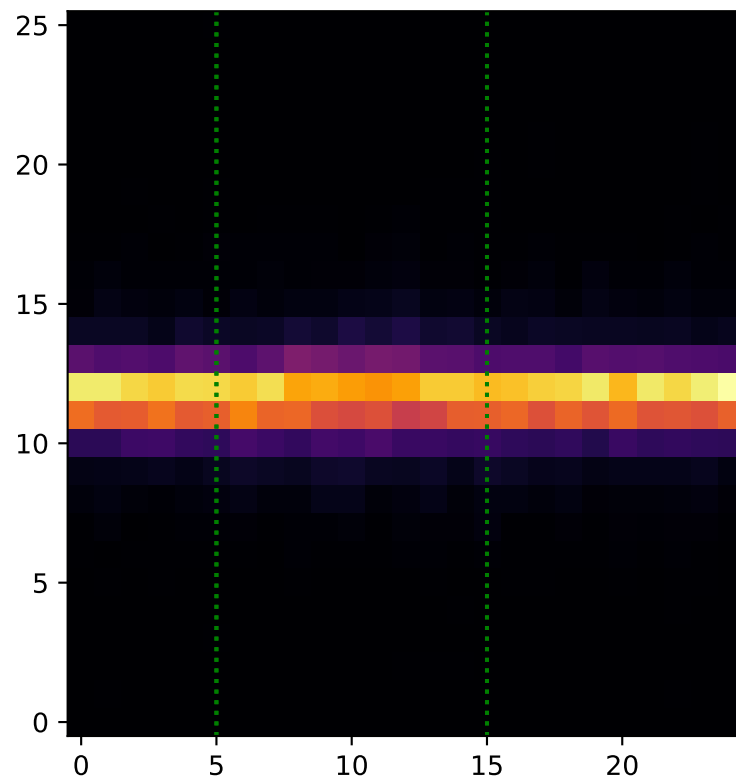


d_speed_tail_base | pval:0.2843243243243243

ctr

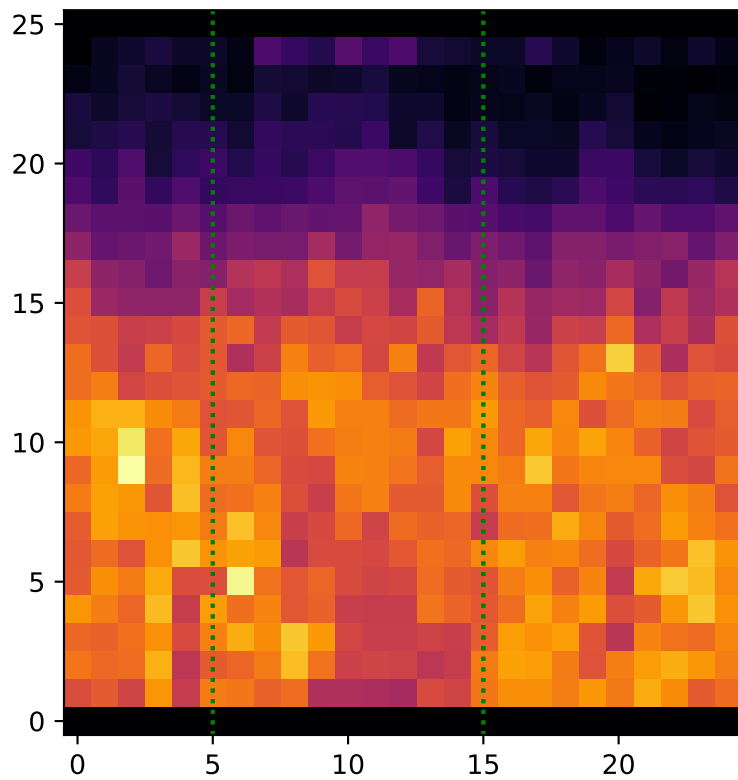


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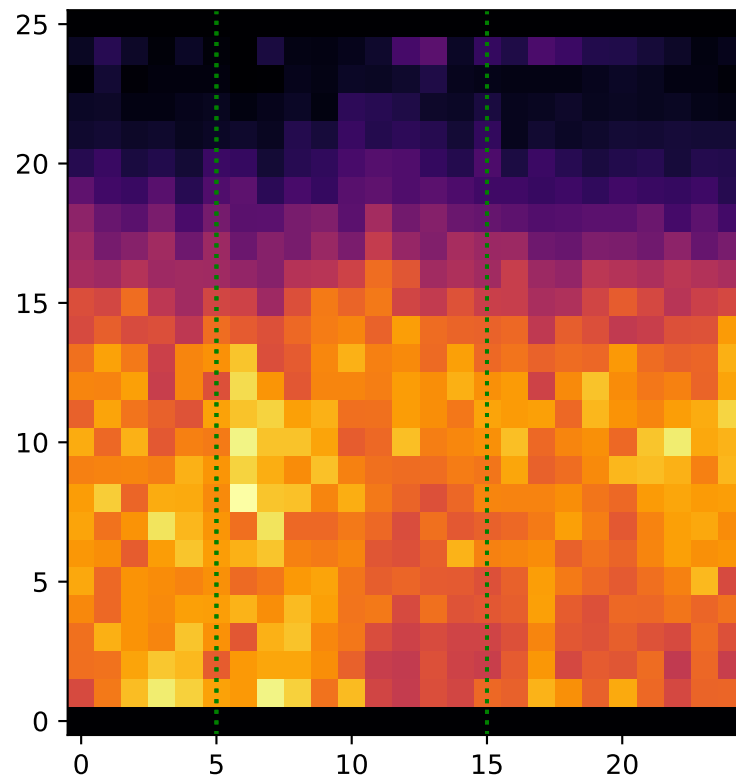


curvature_mean_head | pval:0.28864864864864864

ctr

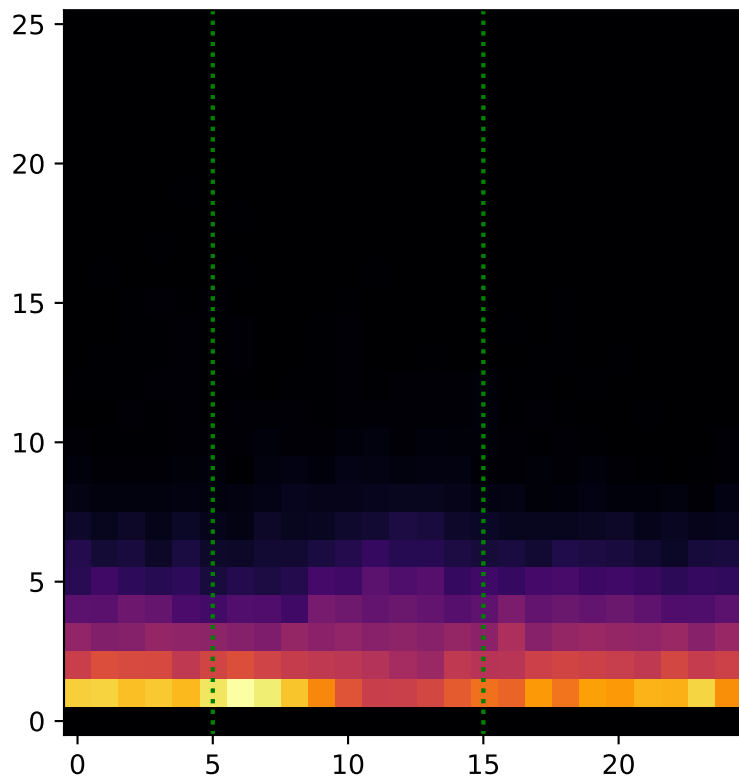


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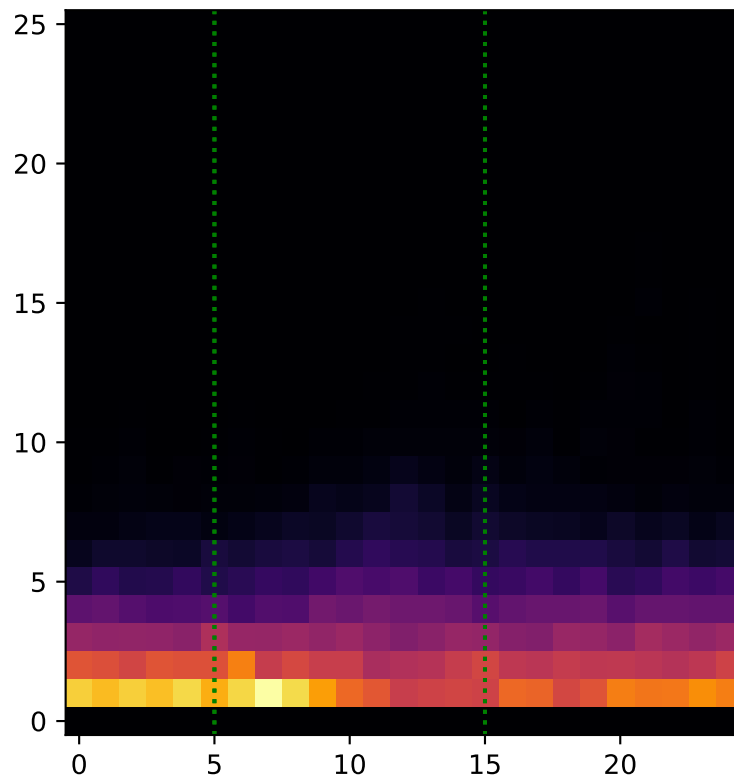


relative_to_body_angular_velocity_head_tip | pval:0.3081081081081081

ctr

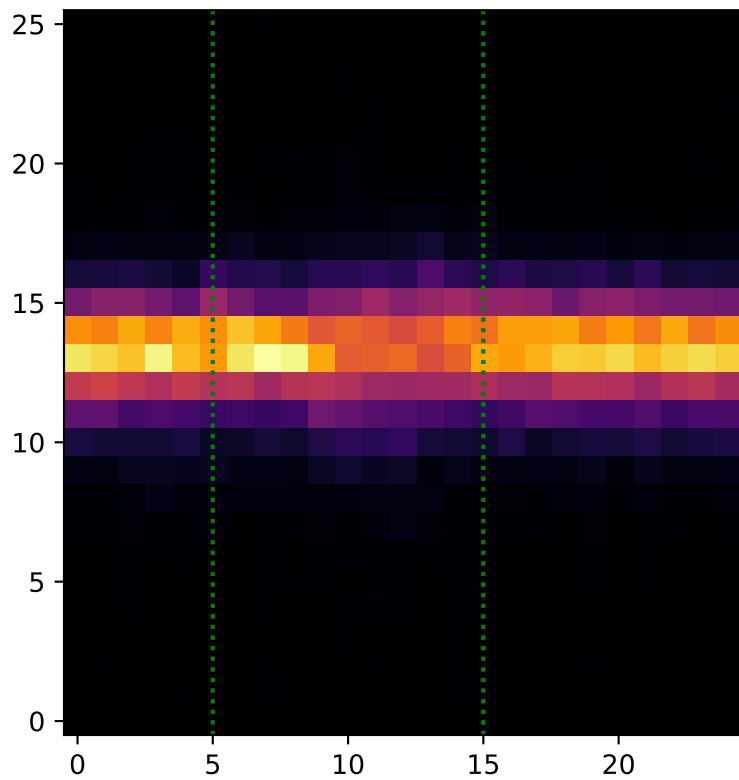


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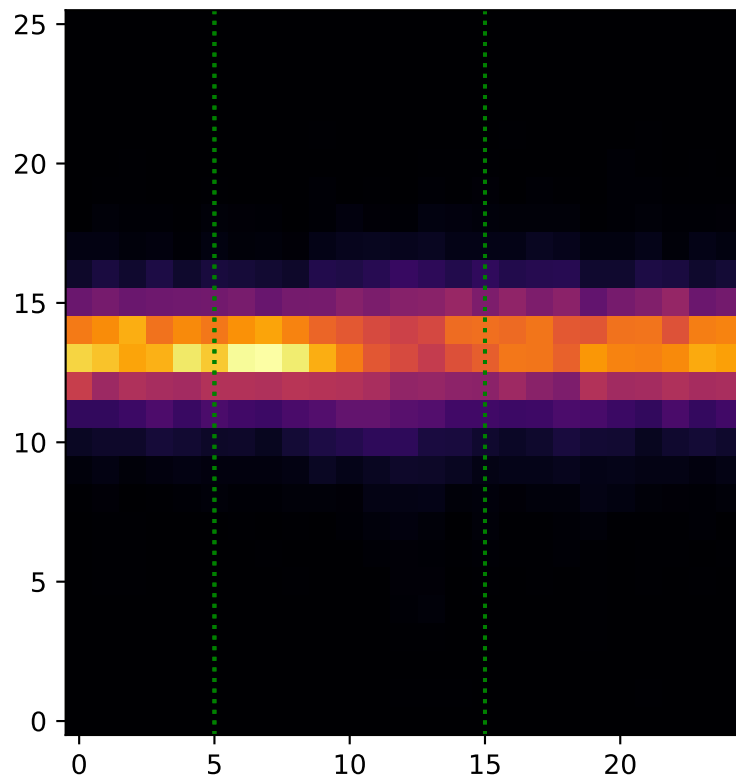


relative_to_body_radial_velocity_head_tip | pval:0.3124324324324324

ctr

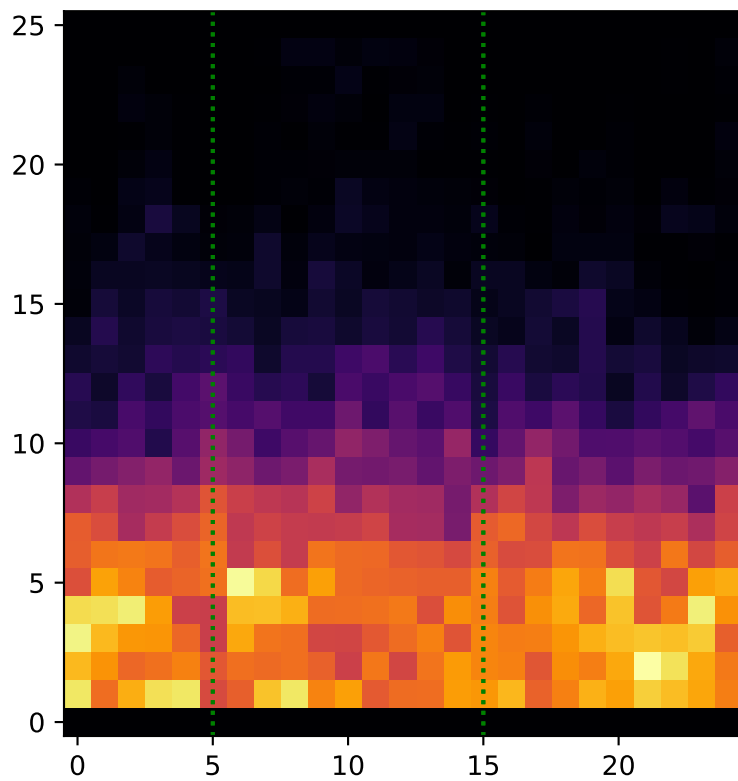


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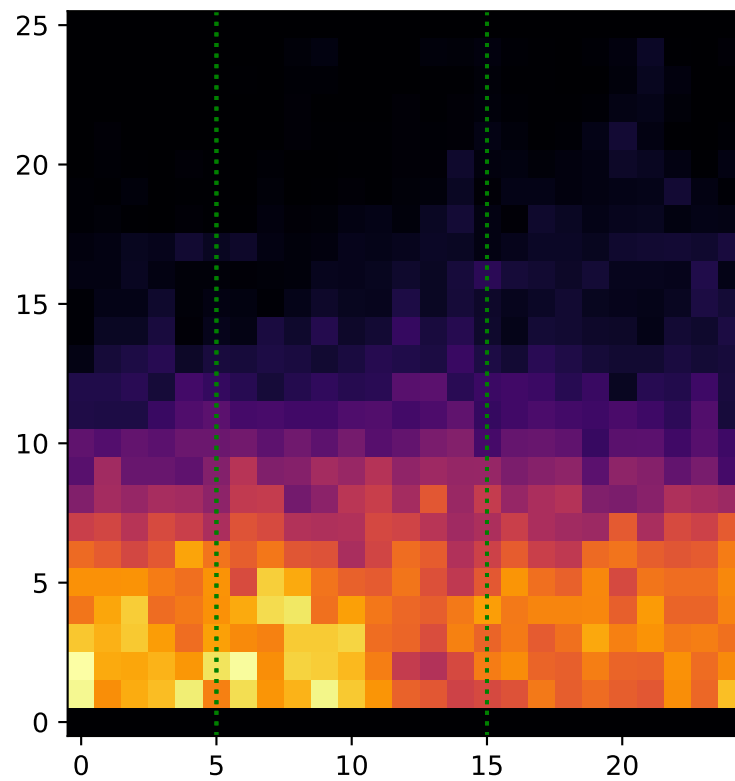


eigen_projection_1 | pval:0.3210810810810811

ctr

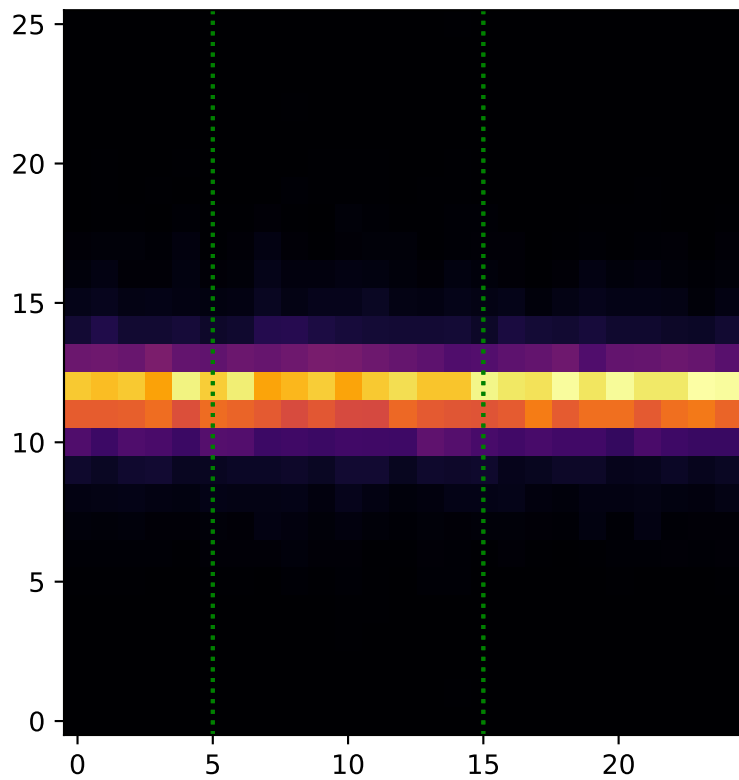


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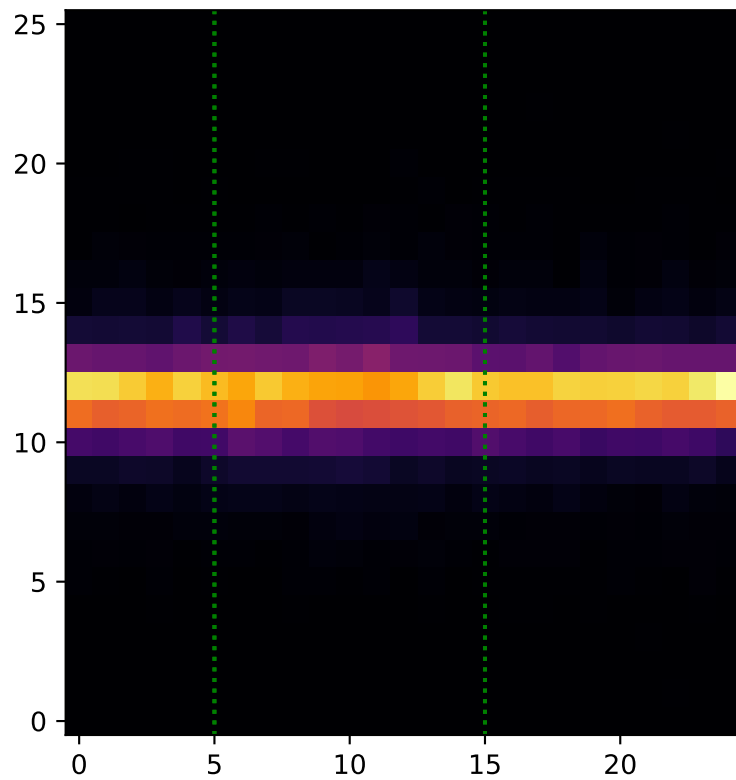


d_speed_head_base | pval:0.33405405405405403

ctr

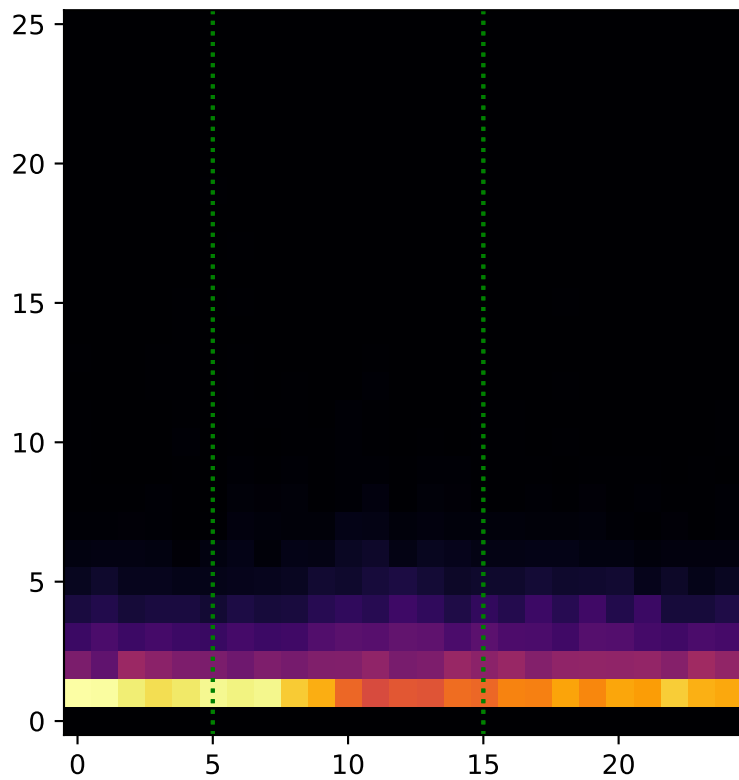


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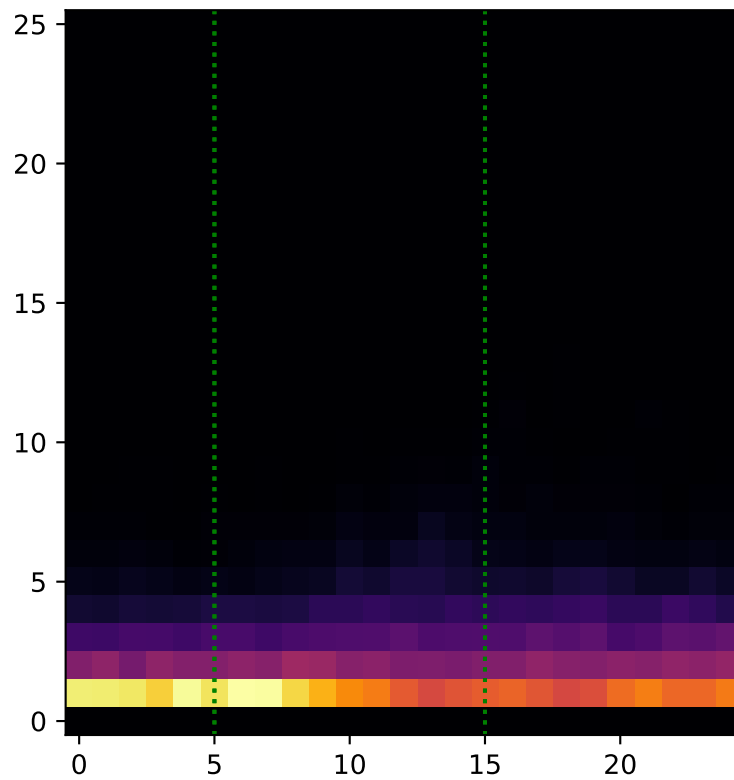


relative_to_body_angular_velocity_tail_tip | pval:0.34054054054054056

ctr

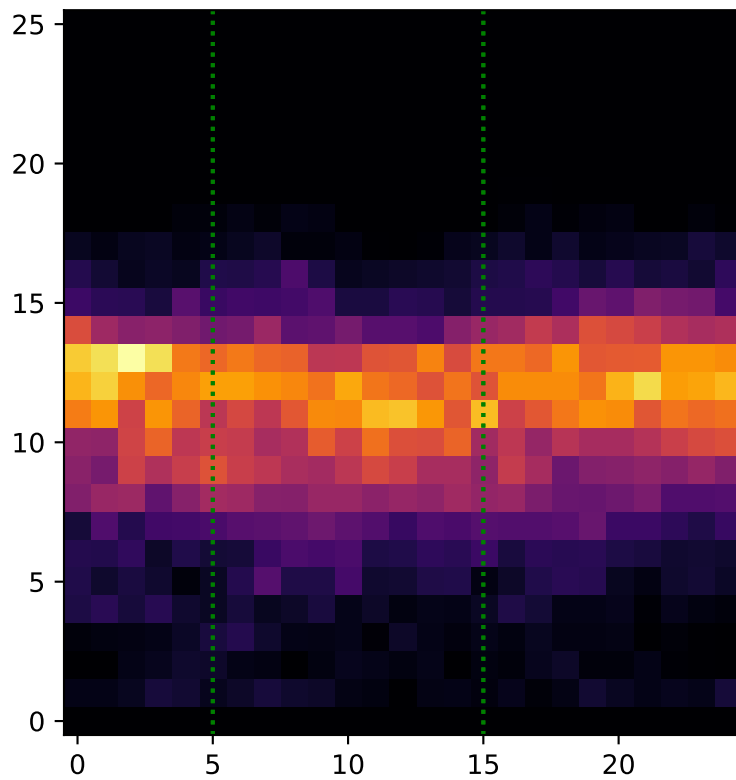


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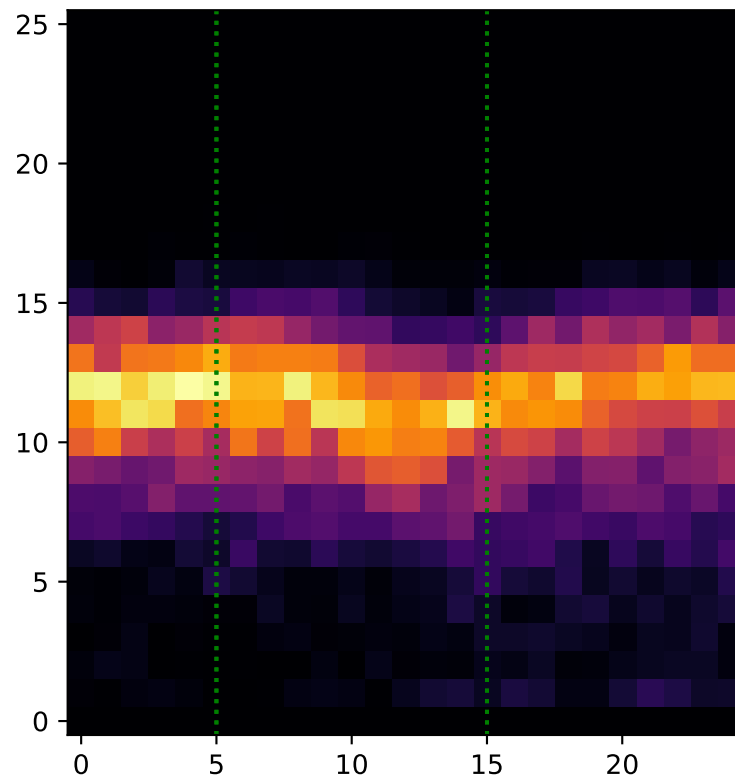


major_axis | pval:0.34486486486486484

ctr

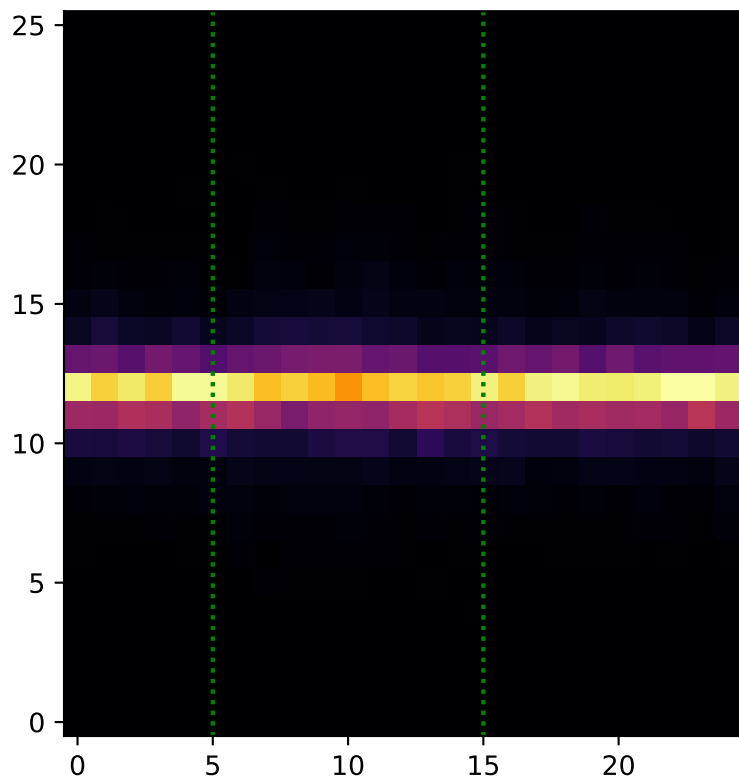


atr

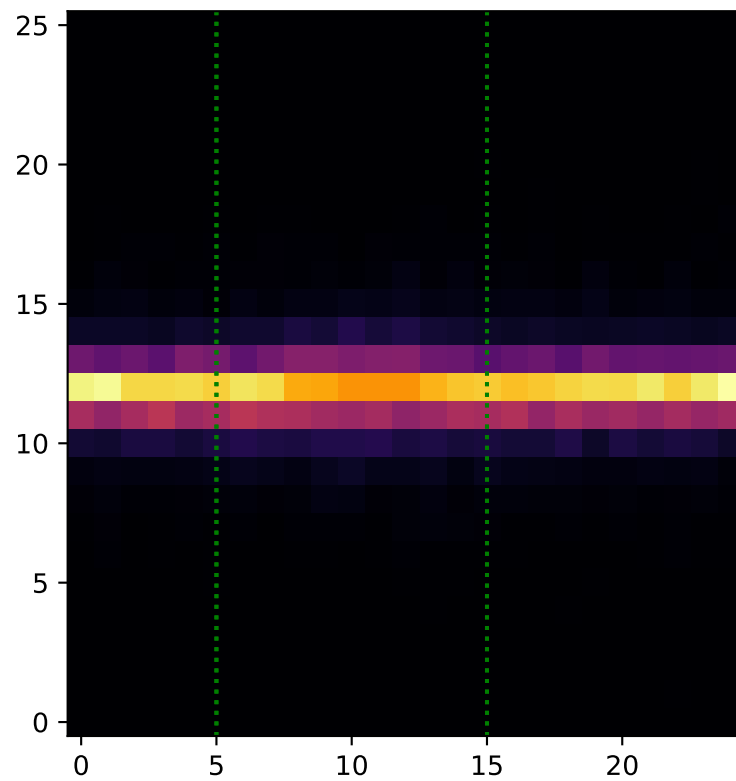


d_speed_hips | pval:0.3491891891891892

ctr

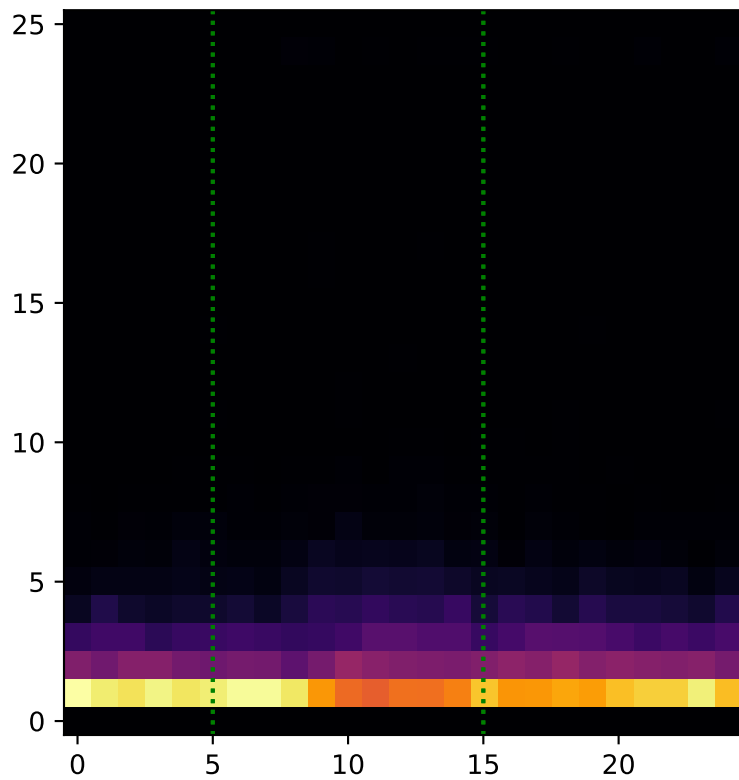


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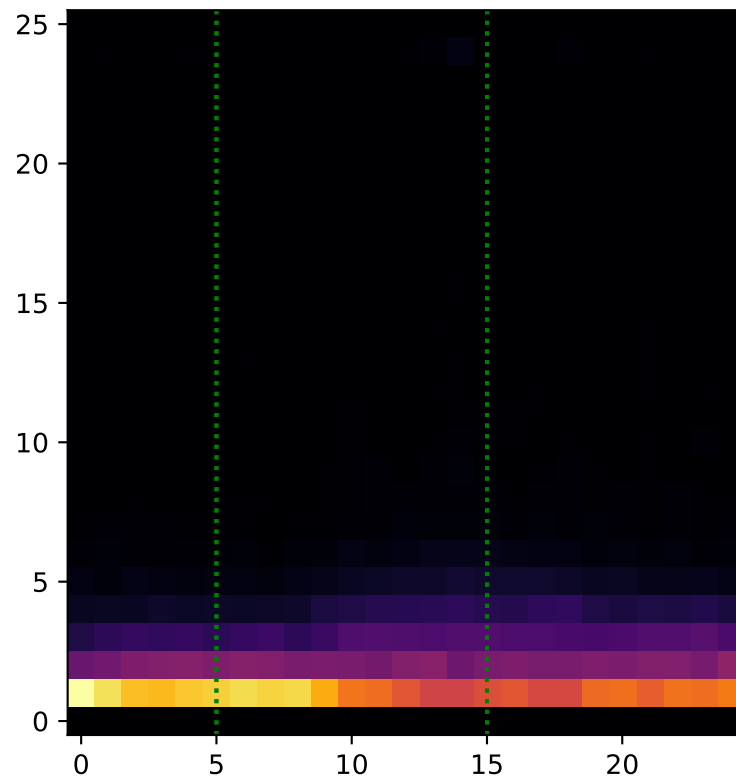


angular_velocity | pval:0.372972972972973

ctr

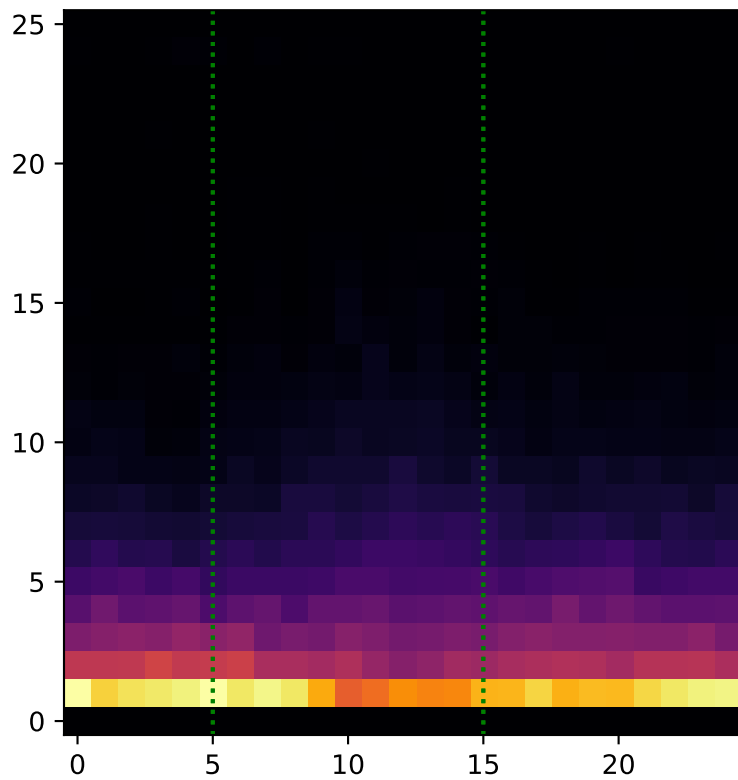


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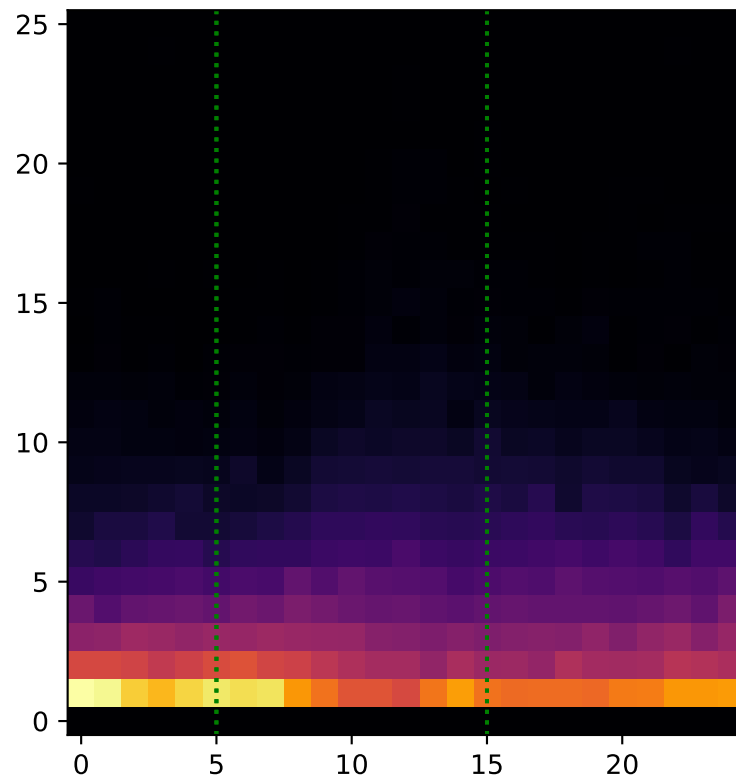


d_angular_velocity_tail_base | pval:0.3772972972972973

ctr

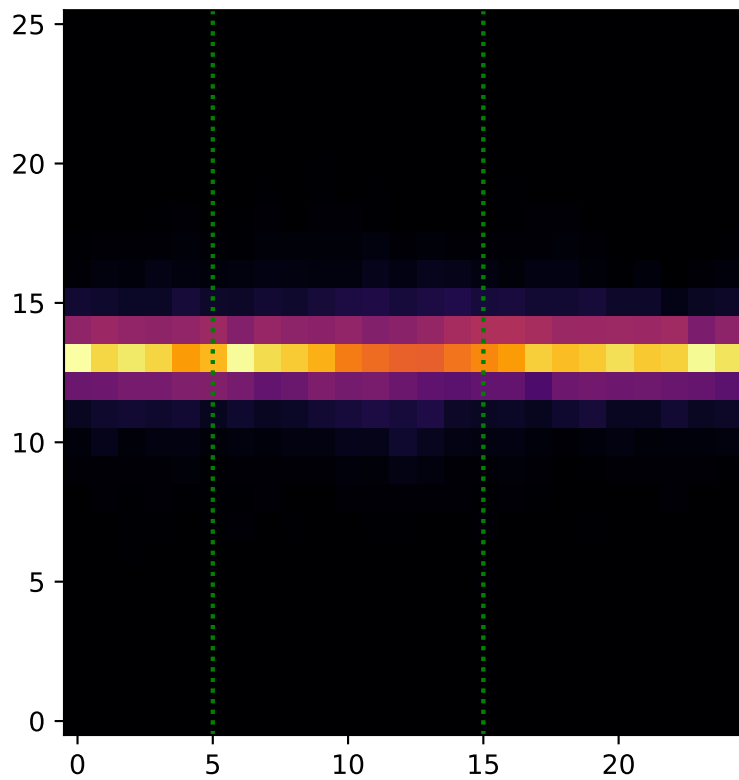


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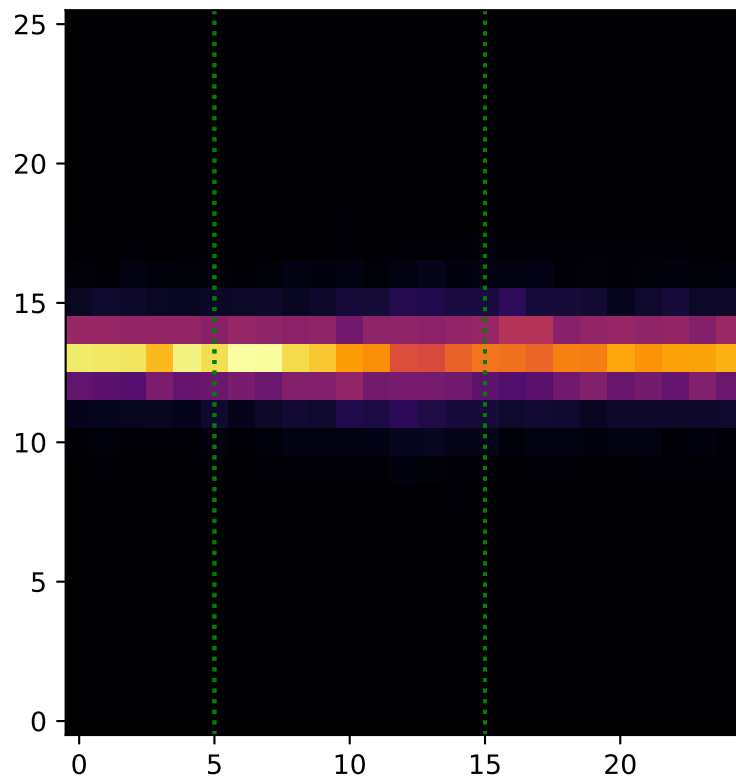


relative_to_body_radial_velocity_neck | pval:0.37945945945945947

ctr

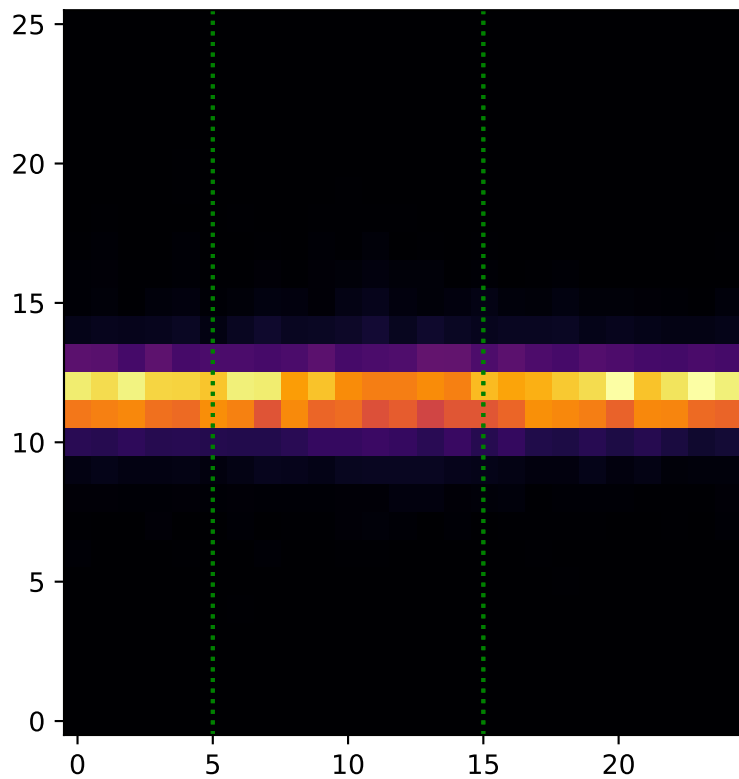


atr

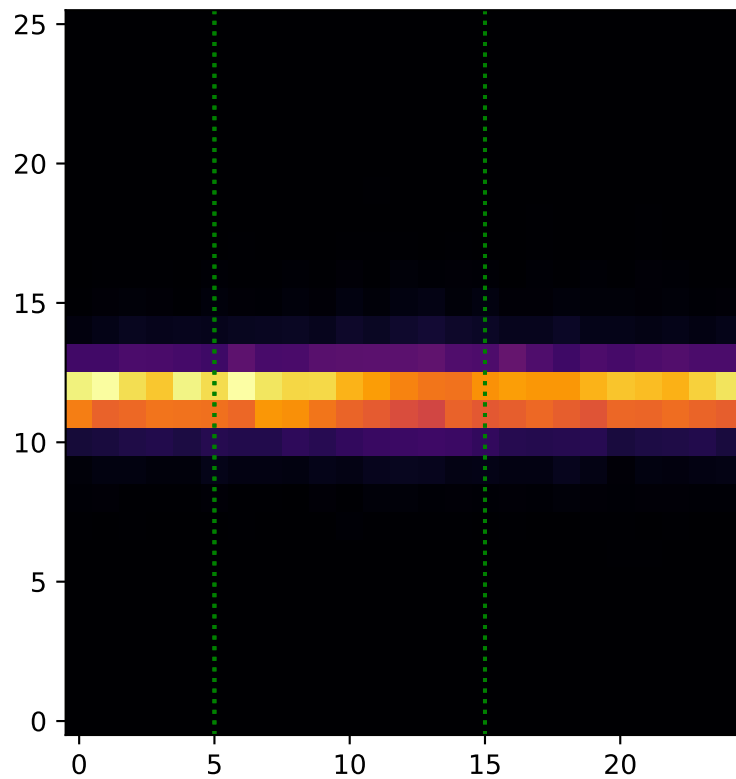


d_relative_to_body_radial_velocity_hips | pval:0.3816216216216216

ctr

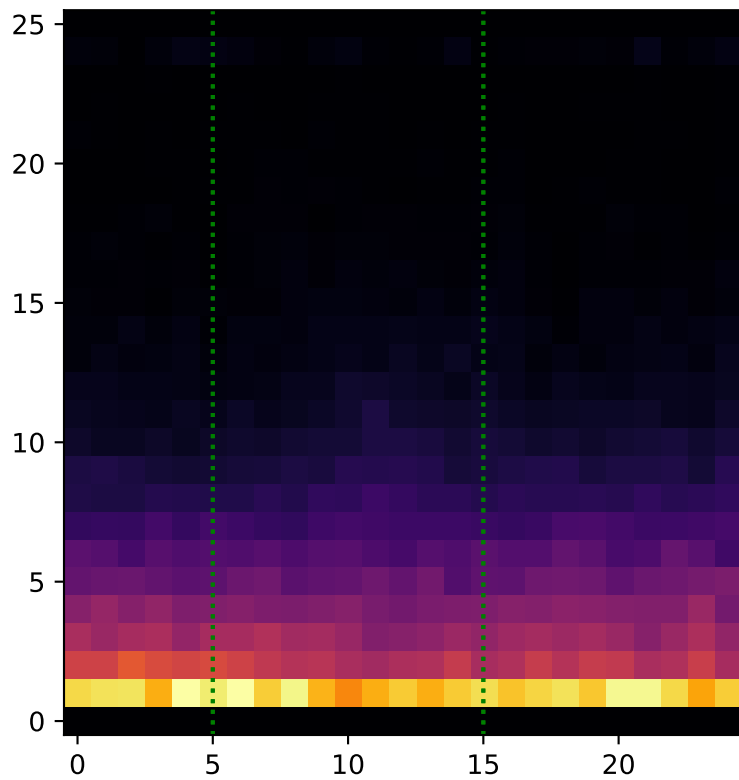


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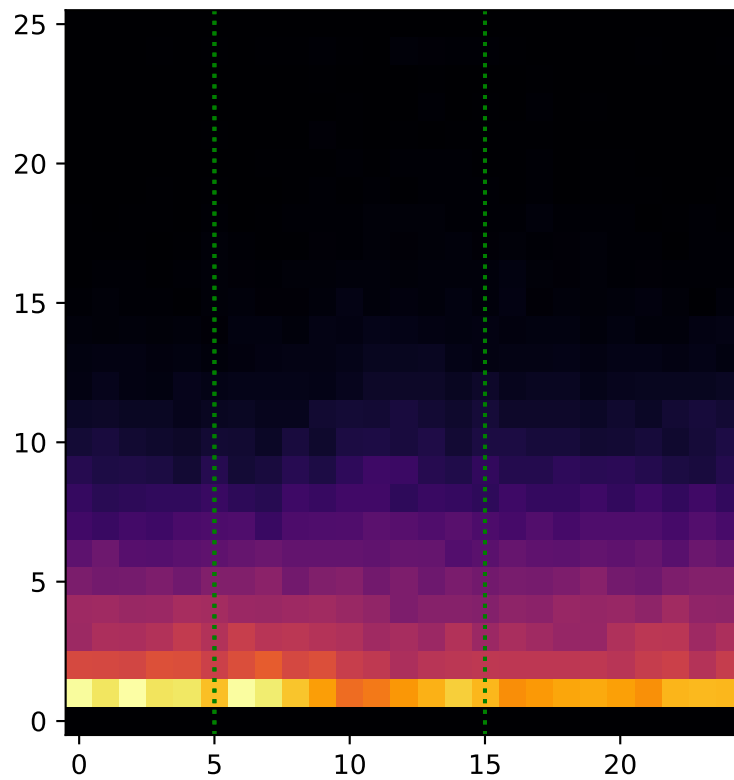


d_angular_velocity_tail_tip | pval:0.40756756756756757

ctr

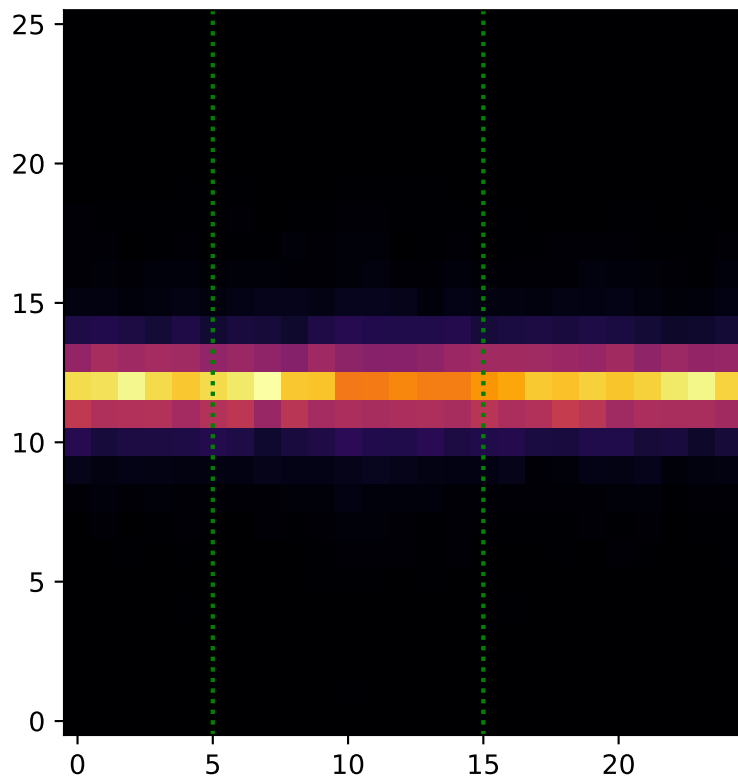


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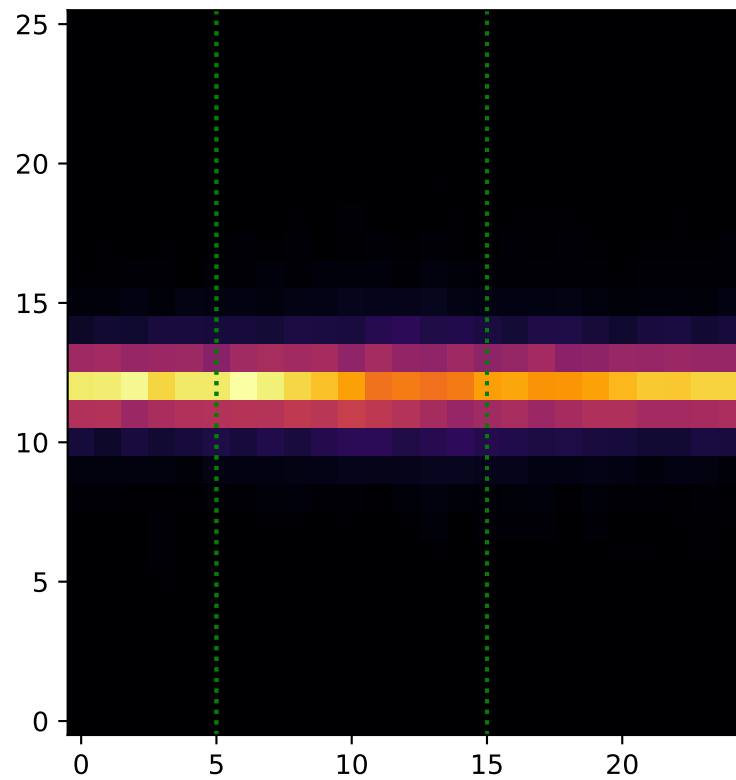


d_relative_to_body_radial_velocity_tail_tip | pval:0.41405405405405404

ctr

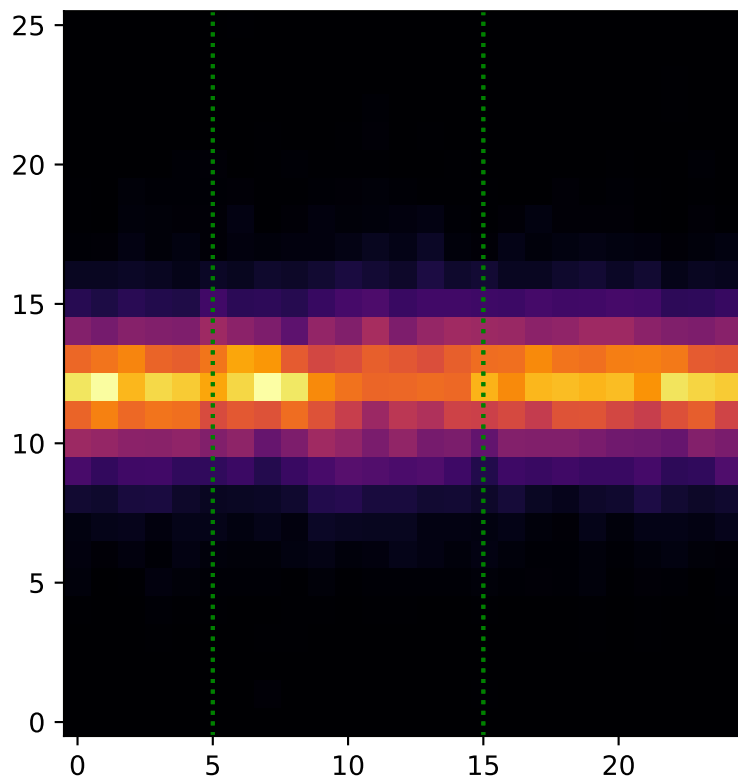


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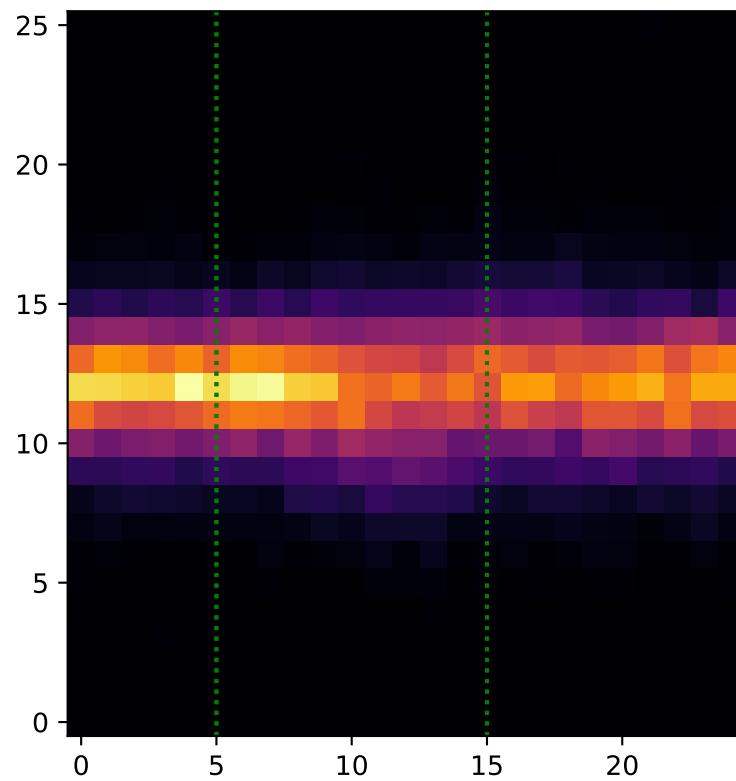


d_major_axis | pval:0.41405405405405404

ctr

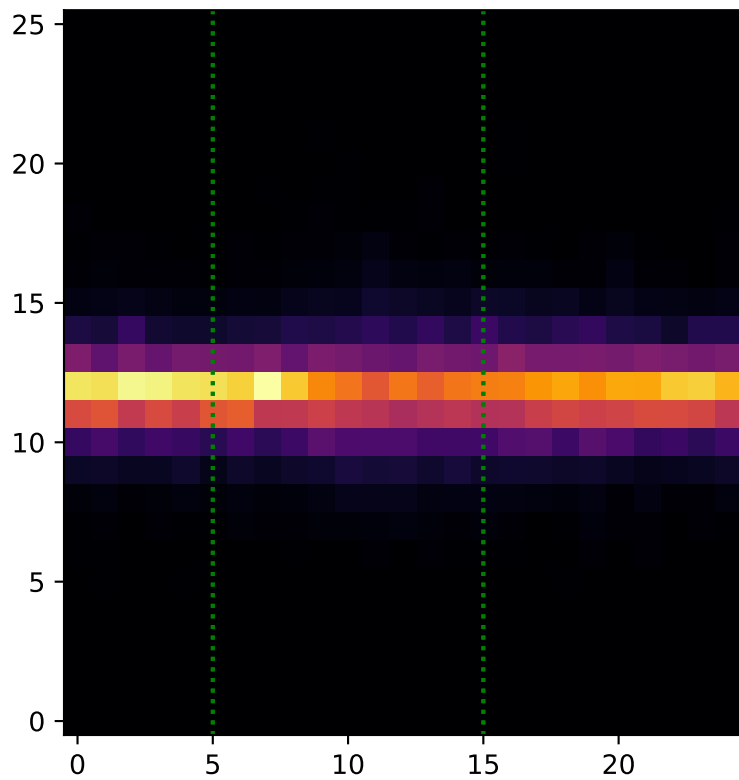


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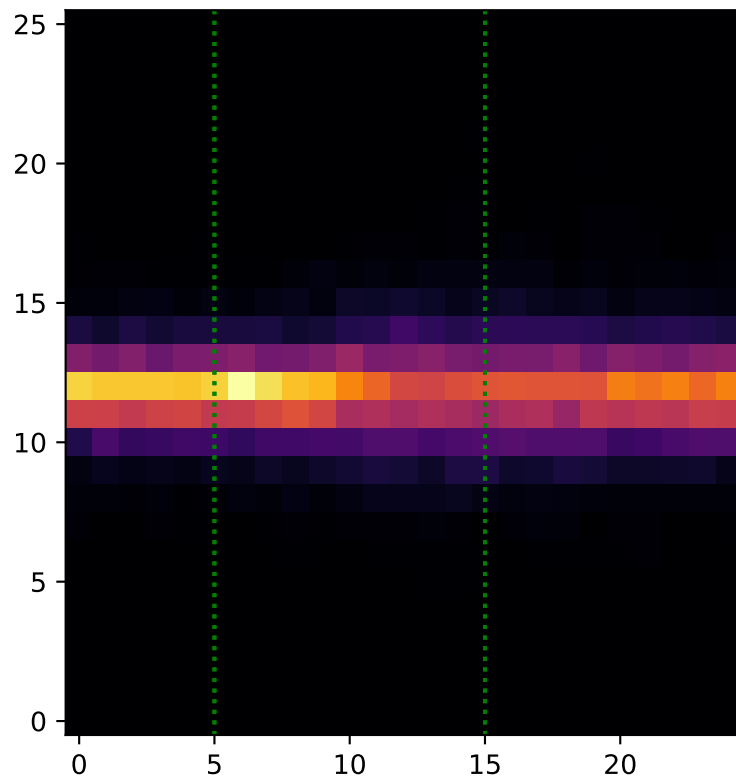


relative_to_hips_radial_velocity_tail_tip | pval:0.4227027027027027

ctr

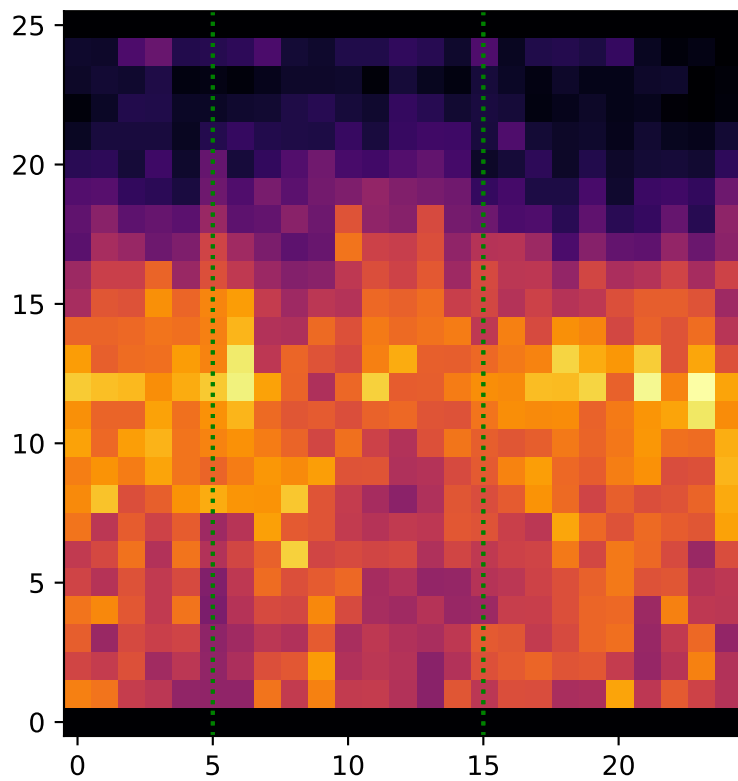


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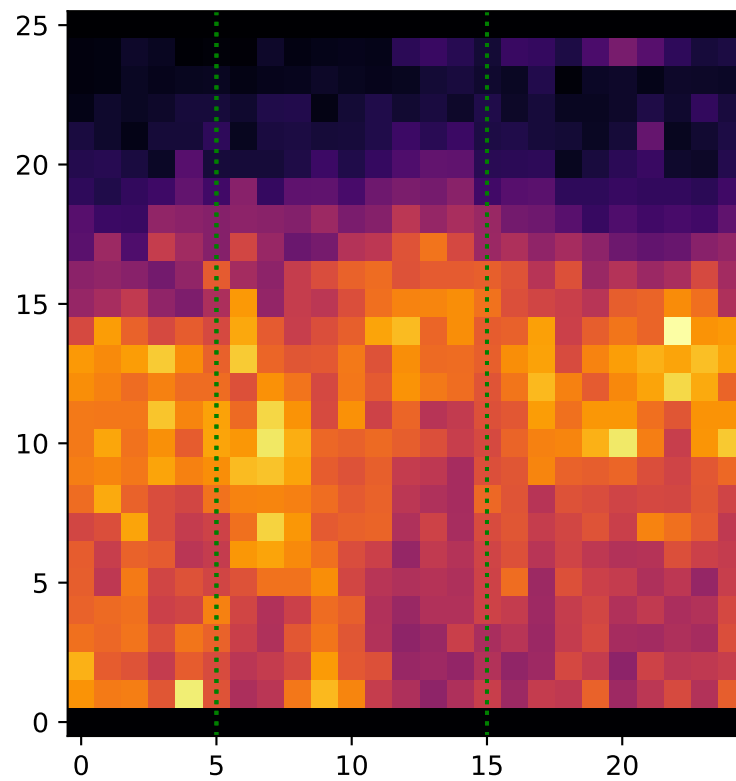


curvature_mean_neck | pval:0.4572972972972973

ctr

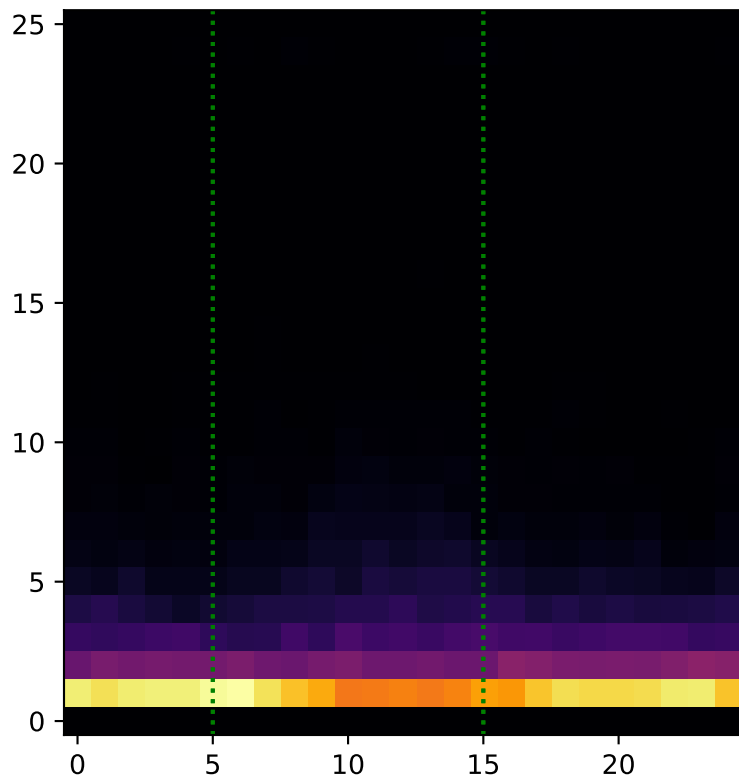


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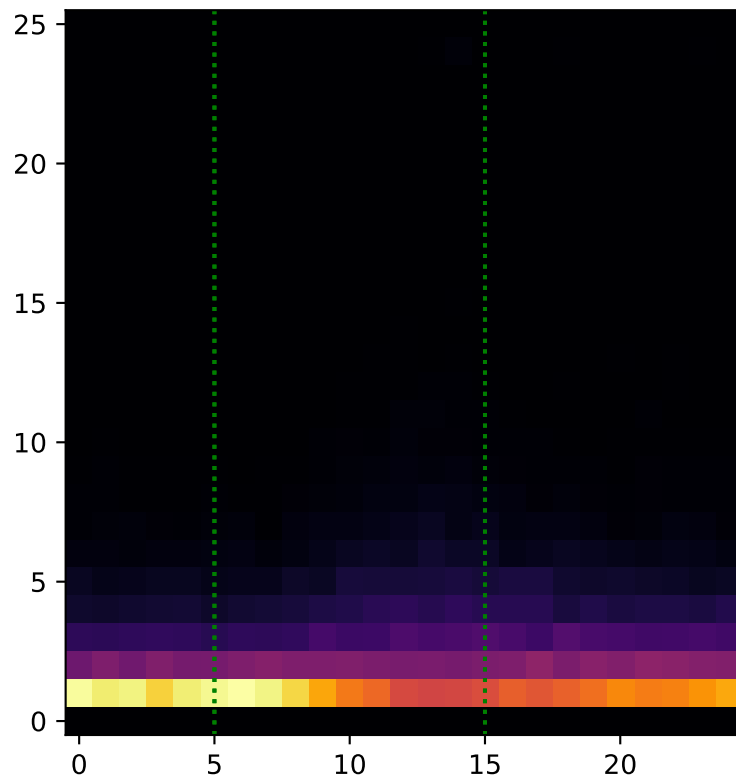


d_angular_velocity_midbody | pval:0.4594594594594595

ctr

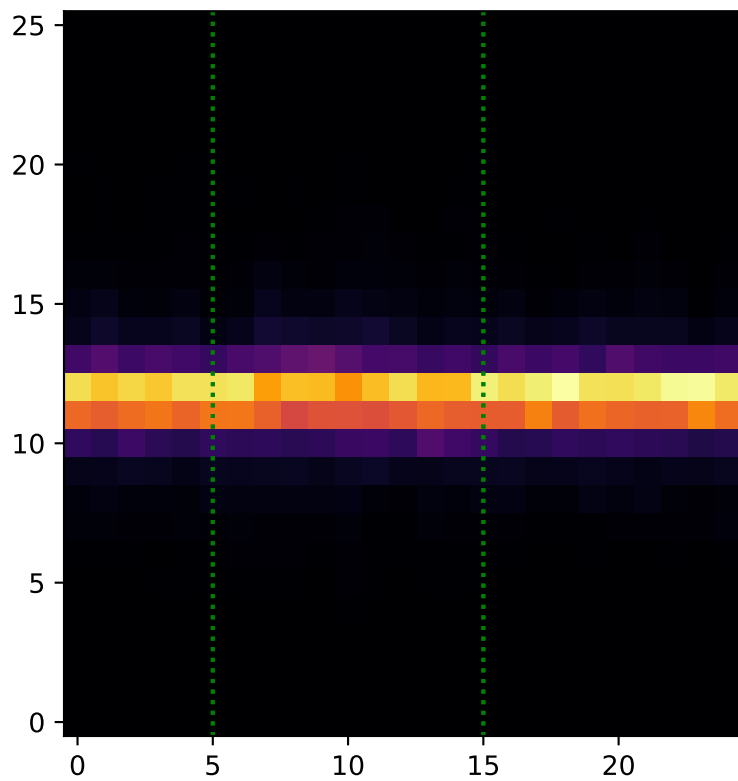


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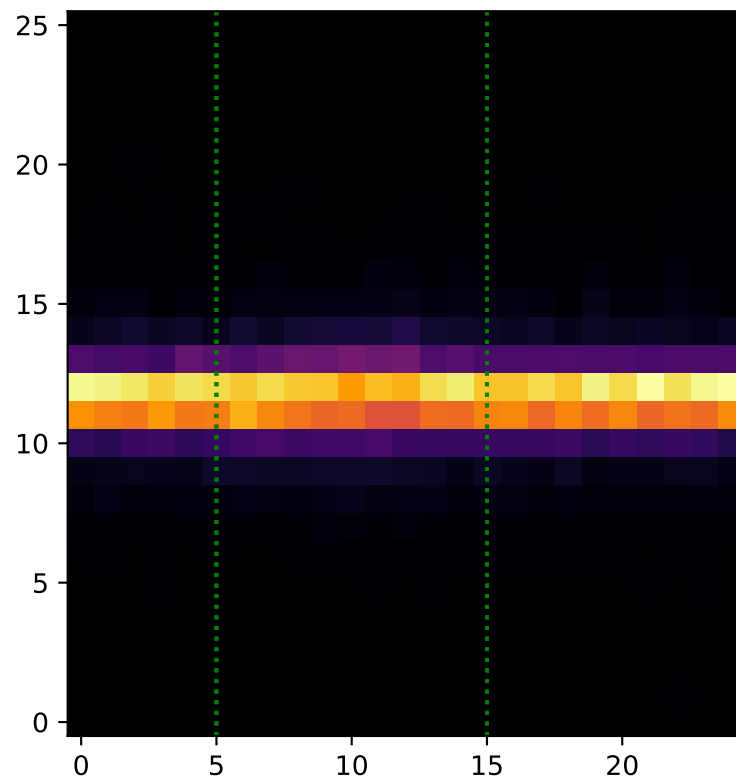


d_speed_midbody | pval:0.4616216216216216

ctr

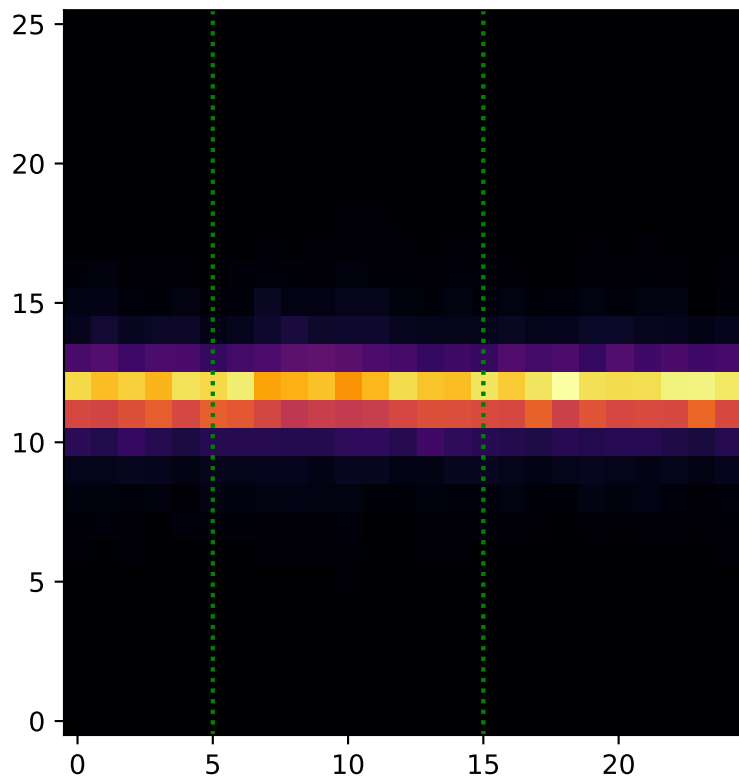


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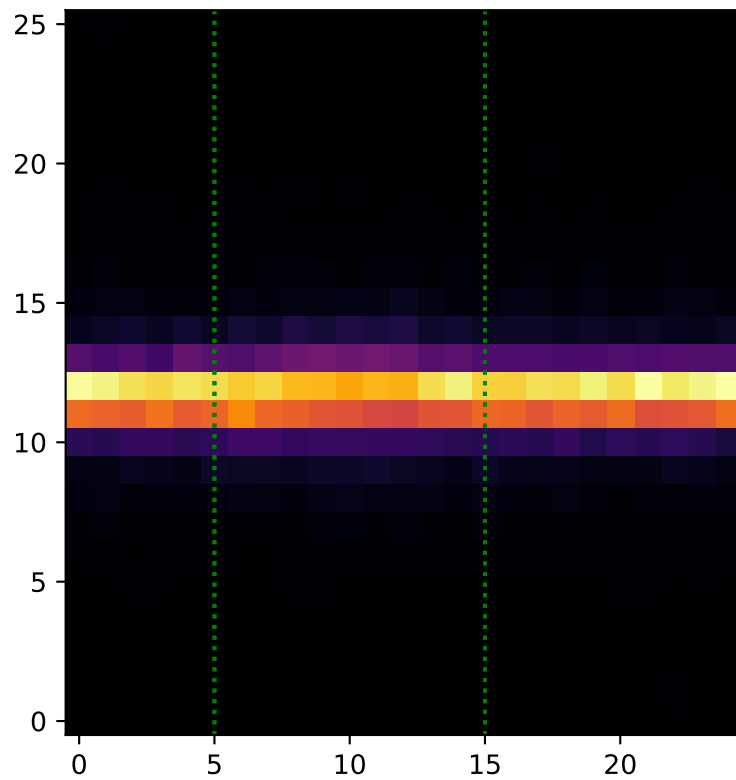


d_speed | pval:0.46378378378378377

ctr

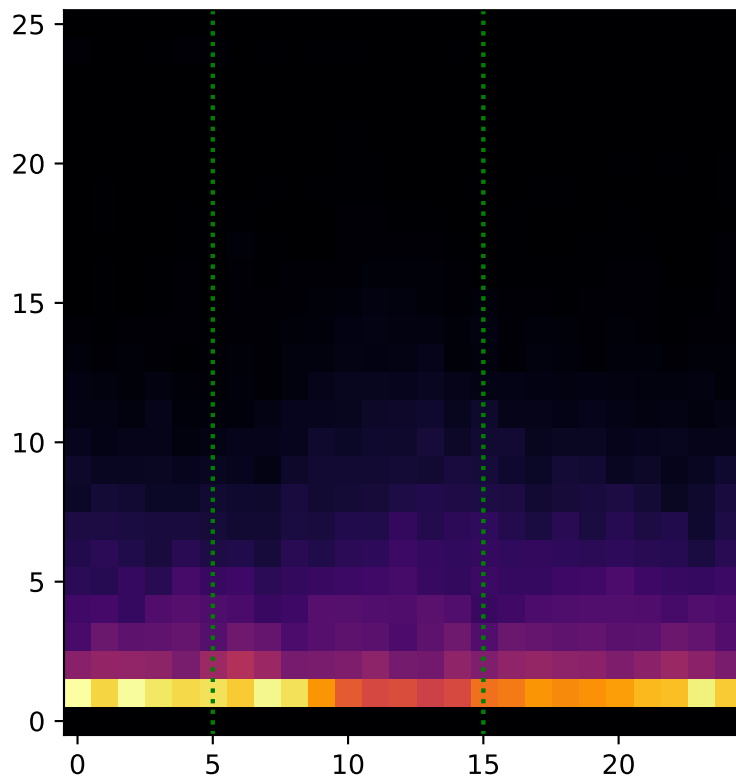


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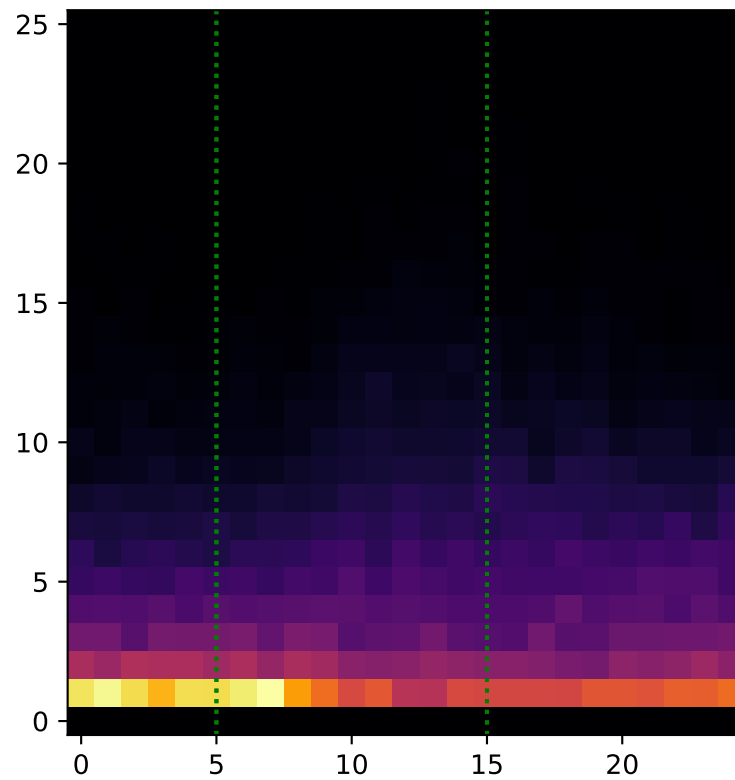


angular_velocity_tail_base | pval:0.4681081081081081

ctr

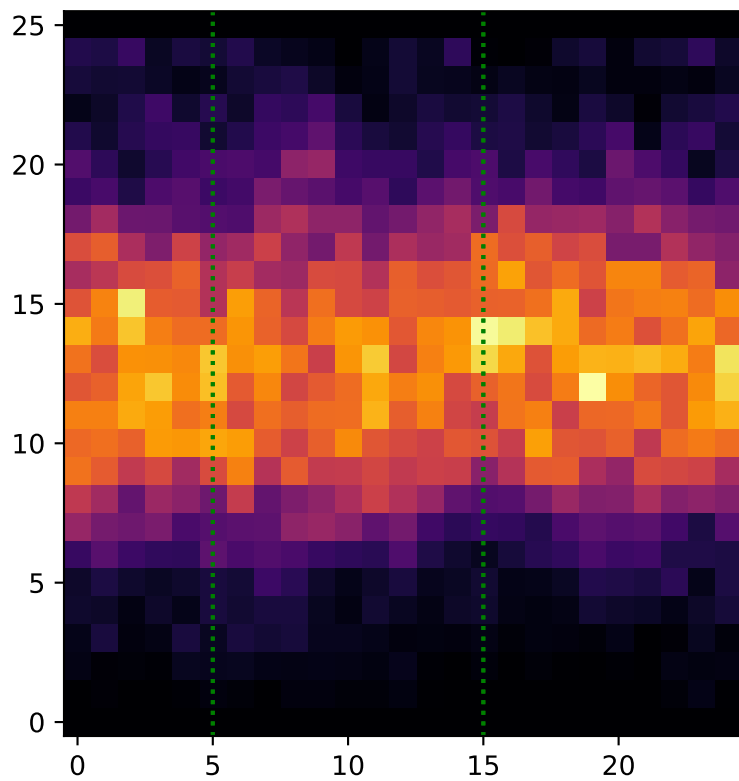


atr

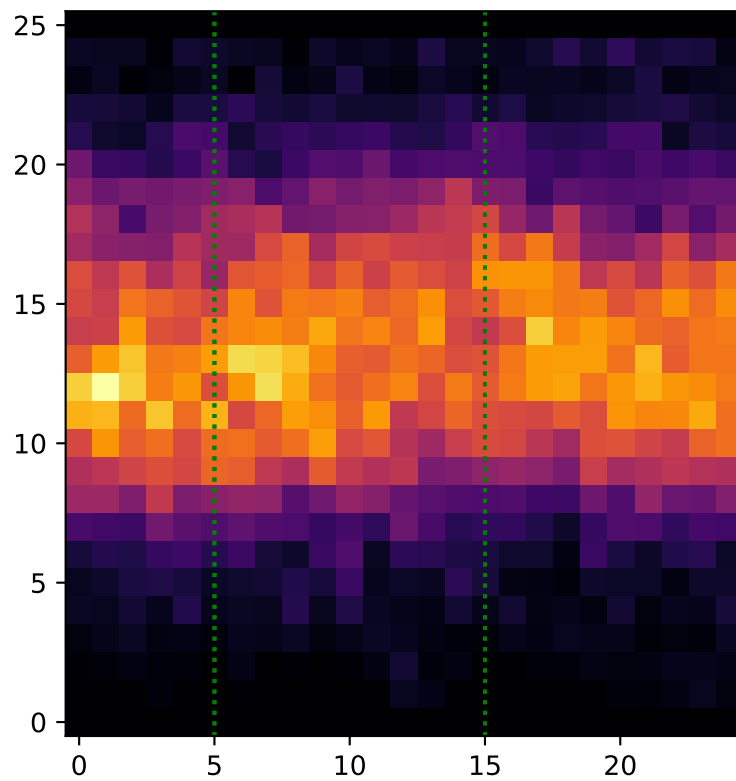


curvature_std_midbody | pval:0.4745945945945946

ctr

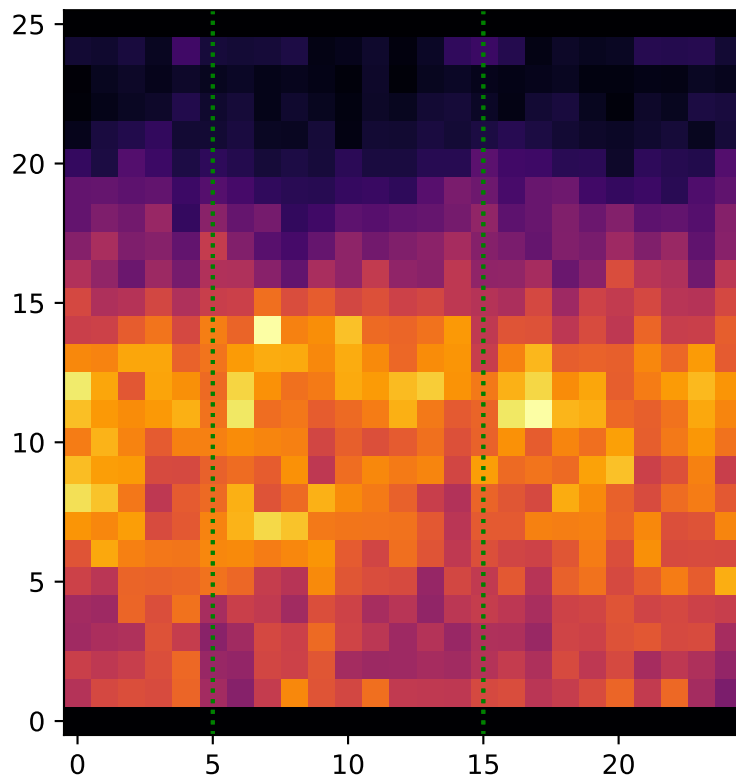


atr

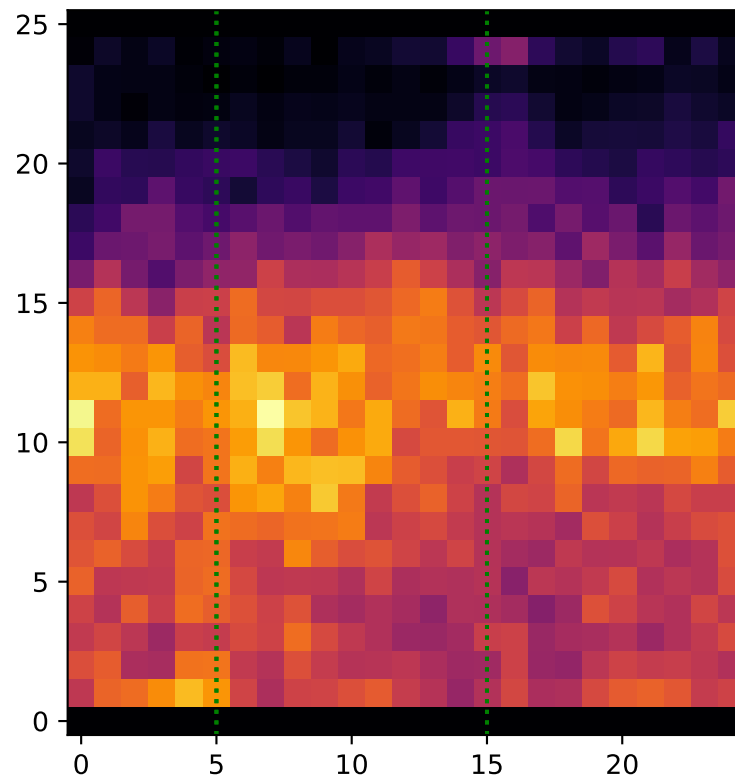


curvature_midbody | pval:0.48324324324324325

ctr

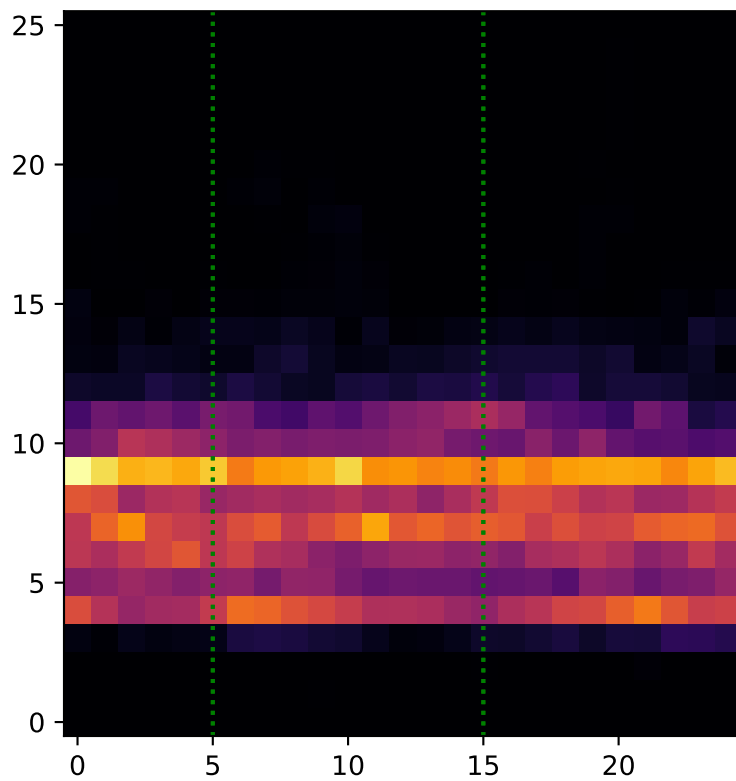


atr

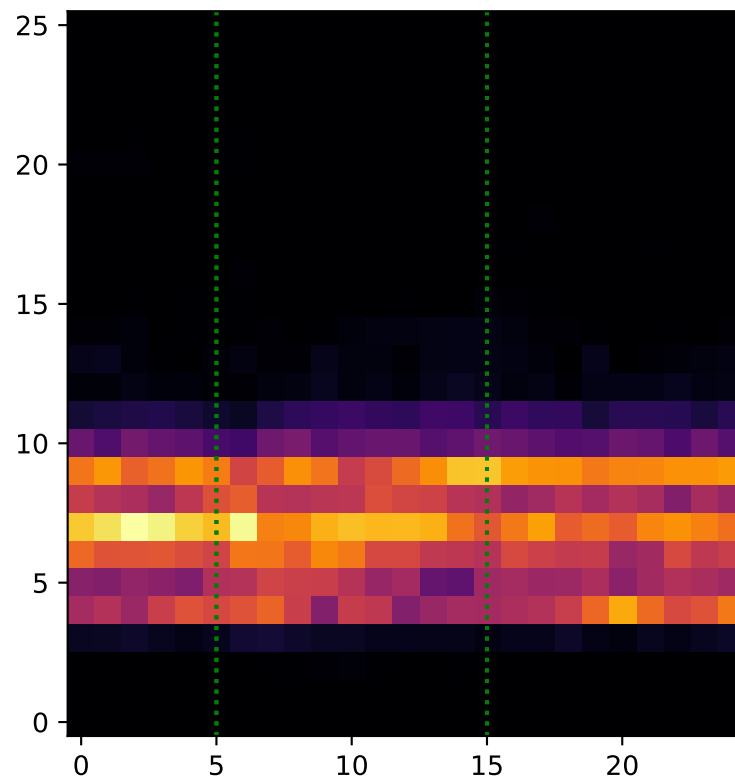


width_midbody | pval:0.4854054054054054

ctr

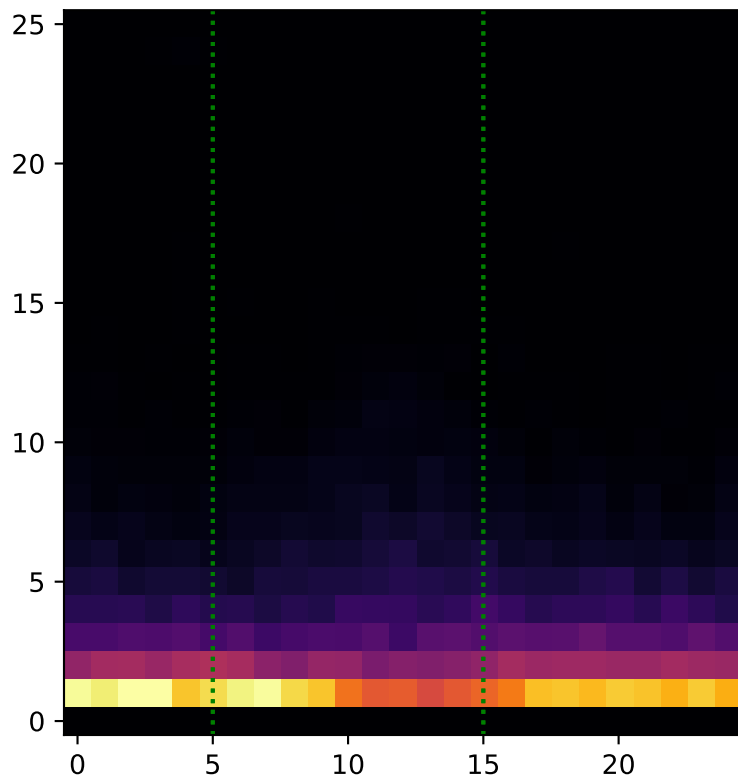


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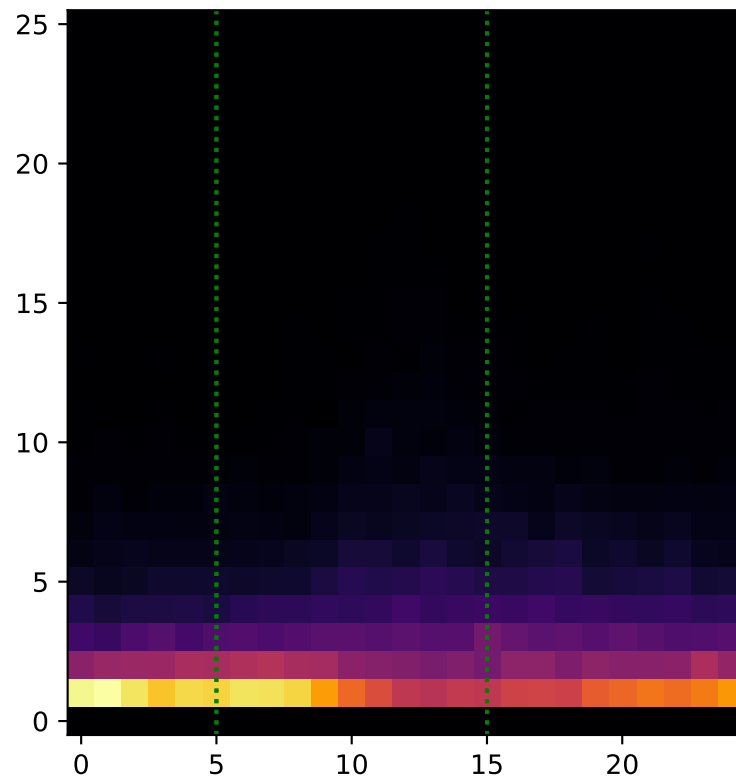


d_relative_to_body_angular_velocity_hips | pval:0.4854054054054054

ctr

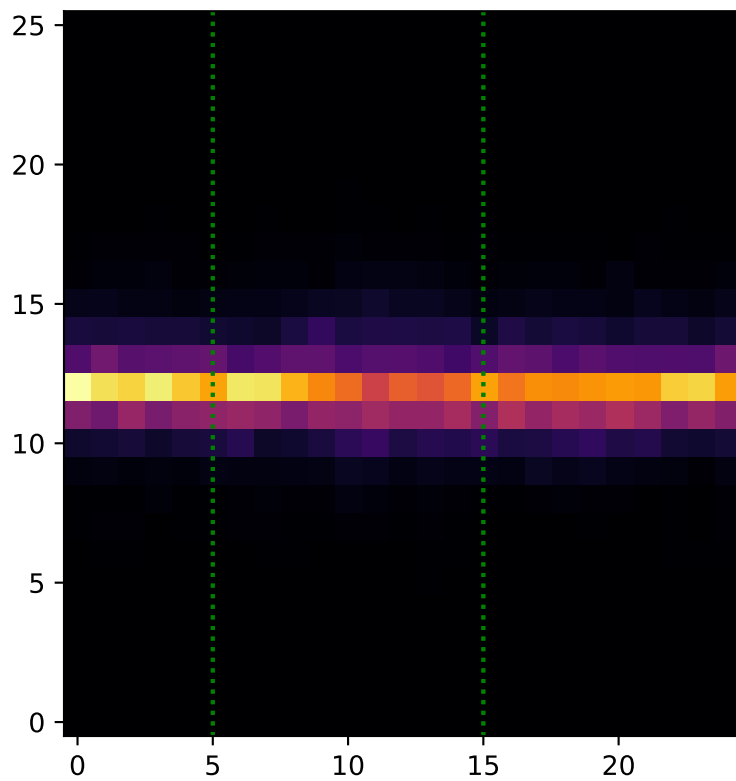


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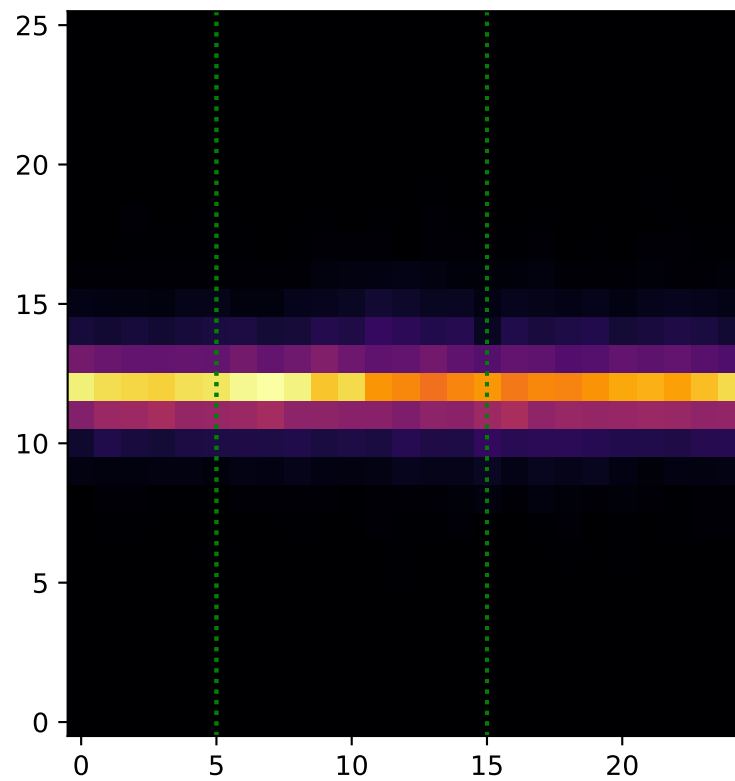


d_minor_axis | pval:0.49405405405405406

ctr

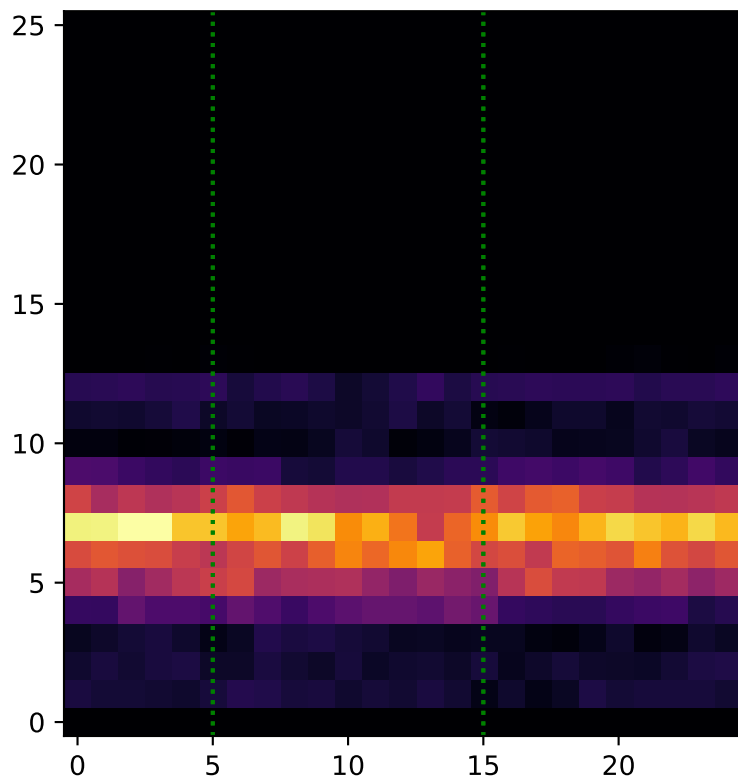


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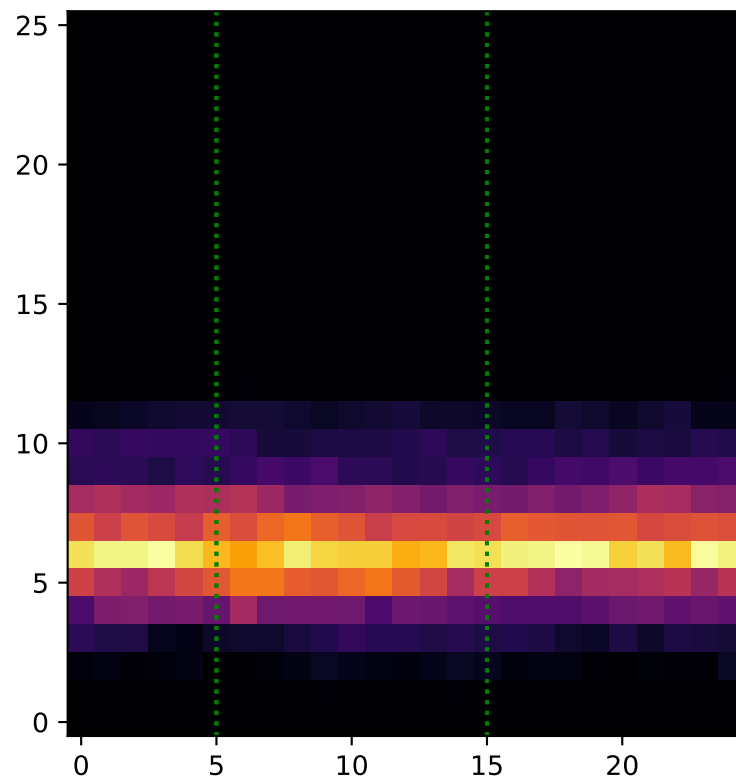


length | pval:0.4962162162162162

ctr

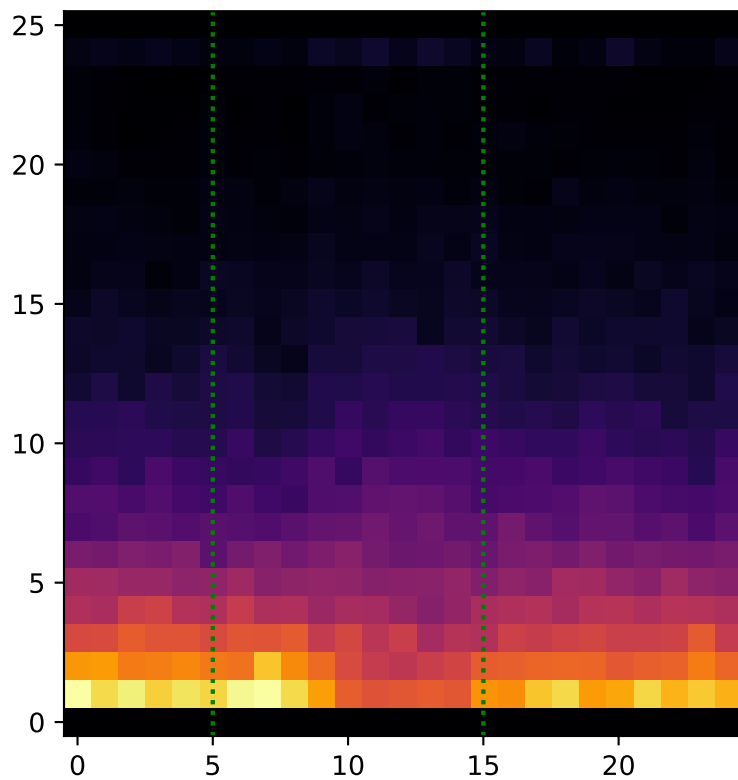


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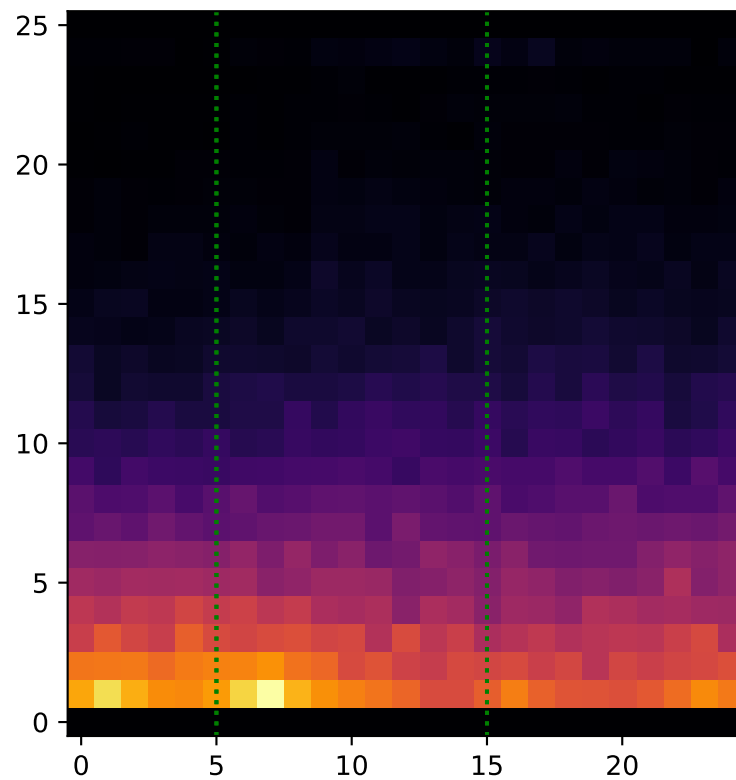


d_curvature_std_tail | pval:0.4962162162162162

ctr

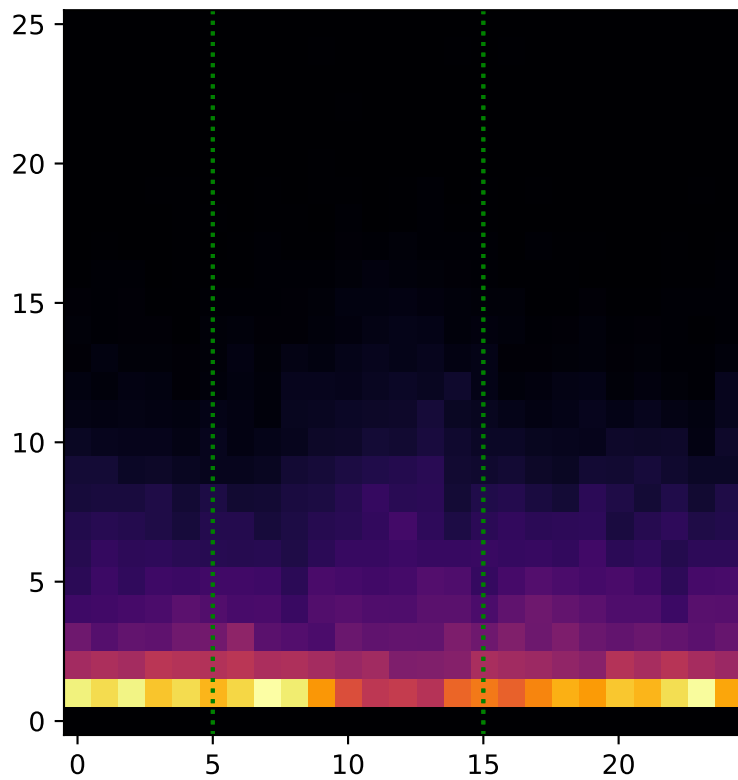


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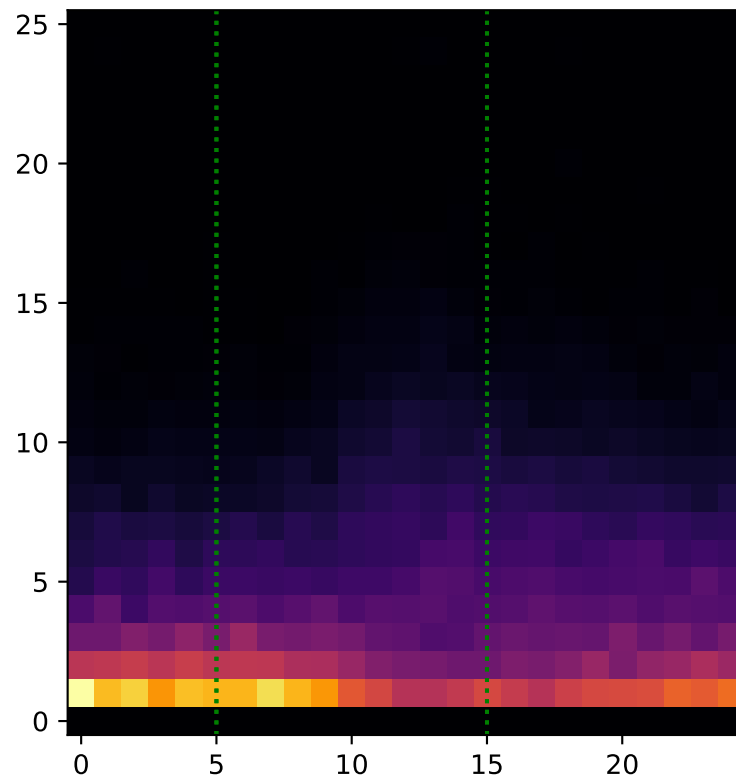


angular_velocity_neck | pval:0.5005405405405405

ctr

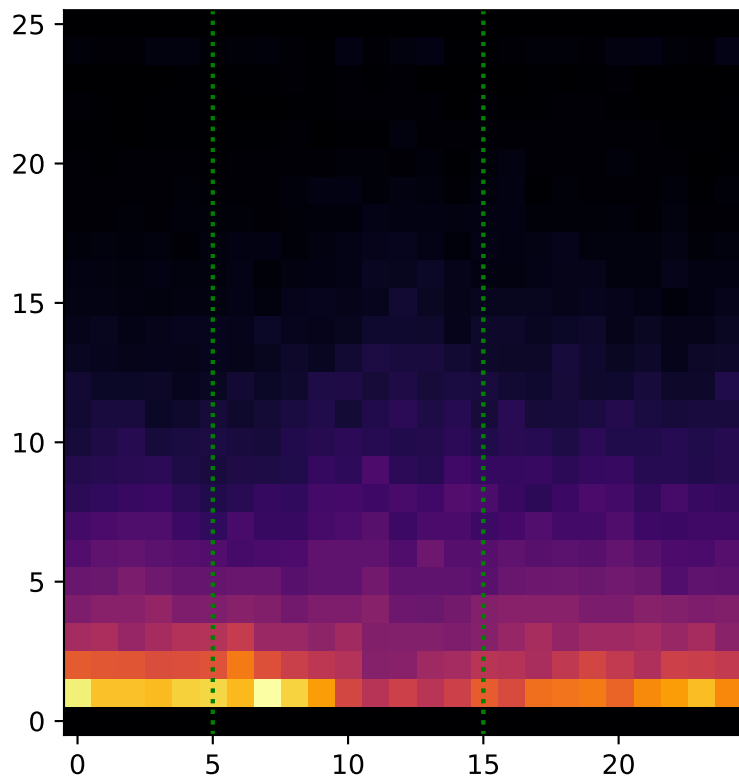


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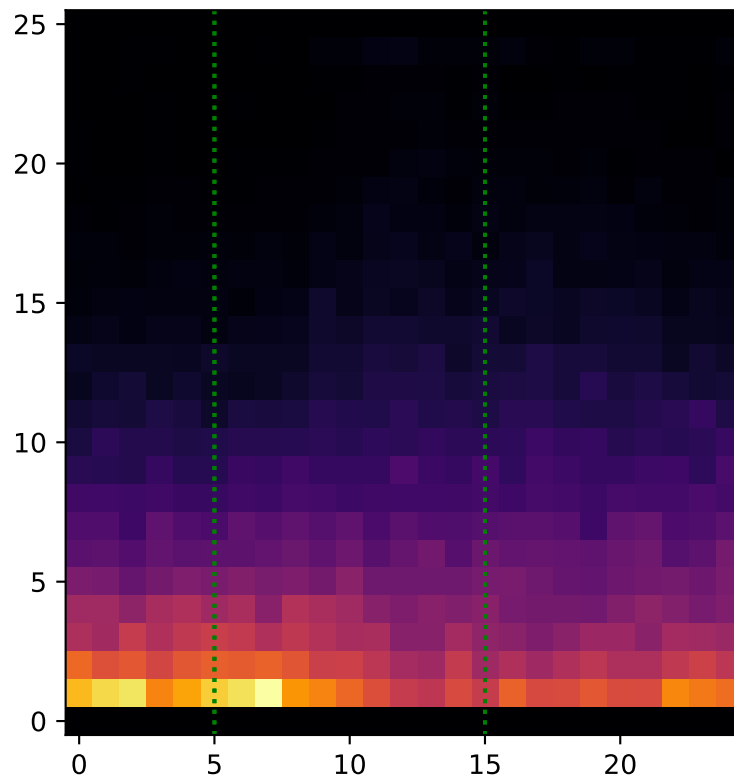


relative_to_tail_base_angular_velocity_tail_tip | pval:0.5027027027027027

ctr

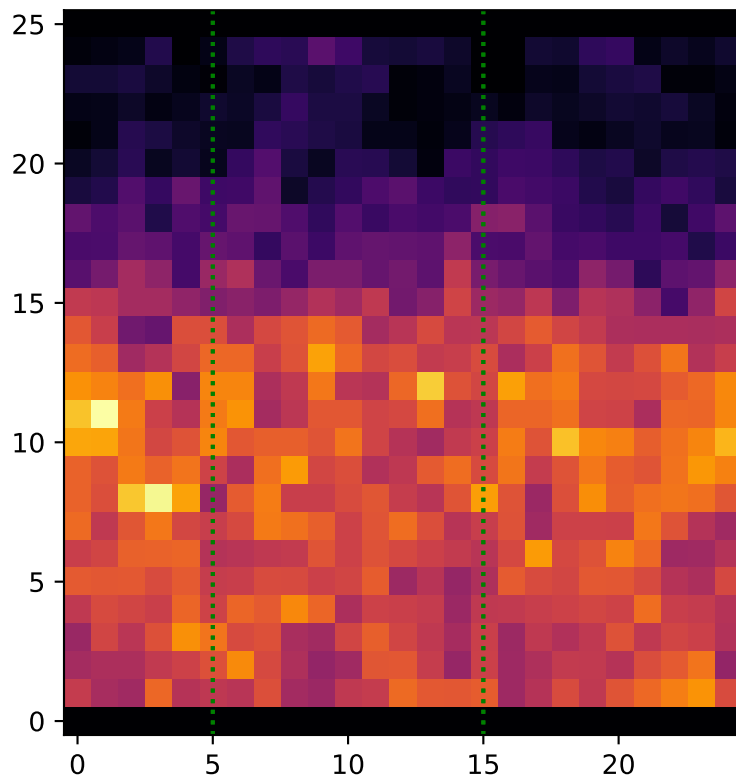


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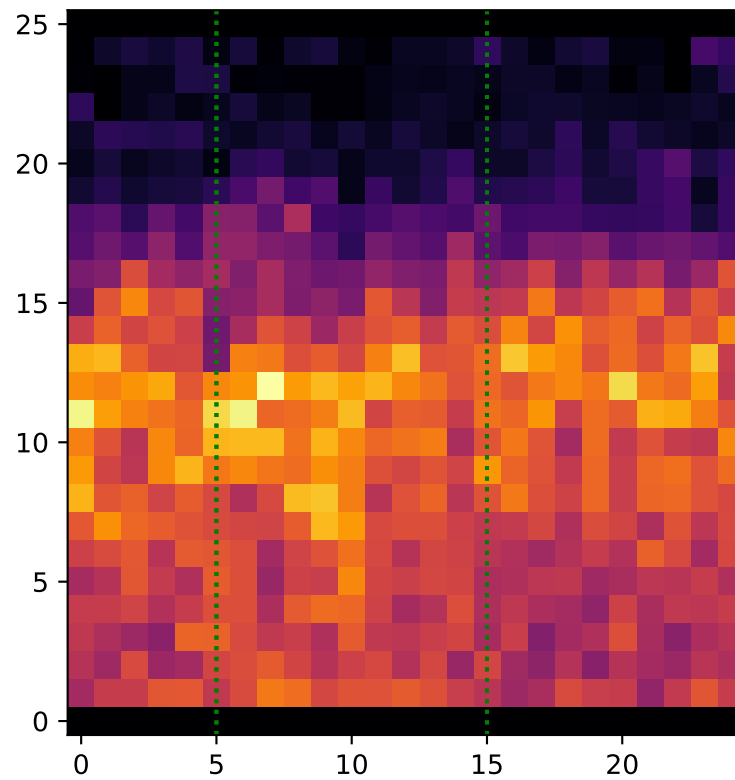


curvature_mean_hips | pval:0.5070270270270271

ctr

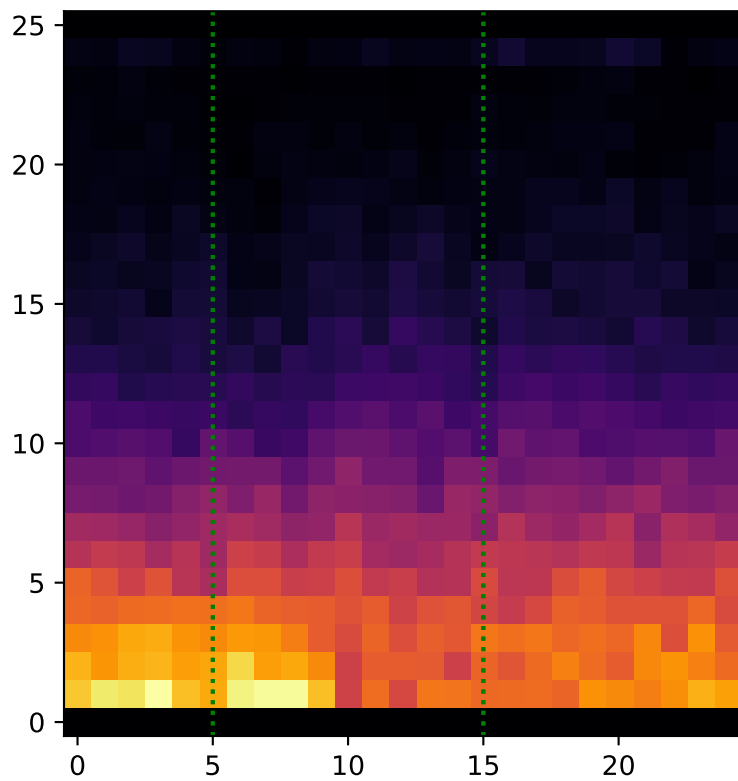


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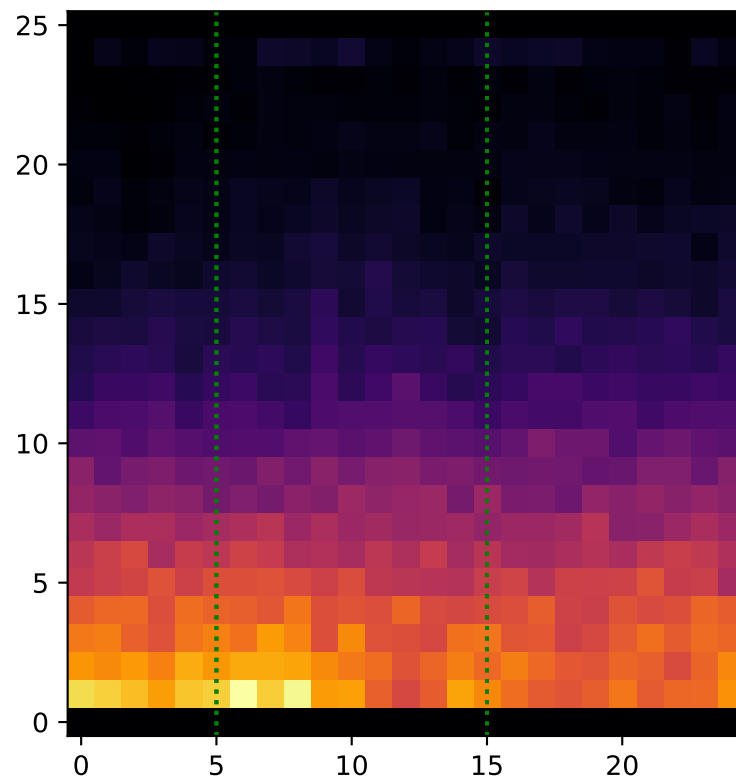


d_eigen_projection_5 | pval:0.5091891891891892

ctr

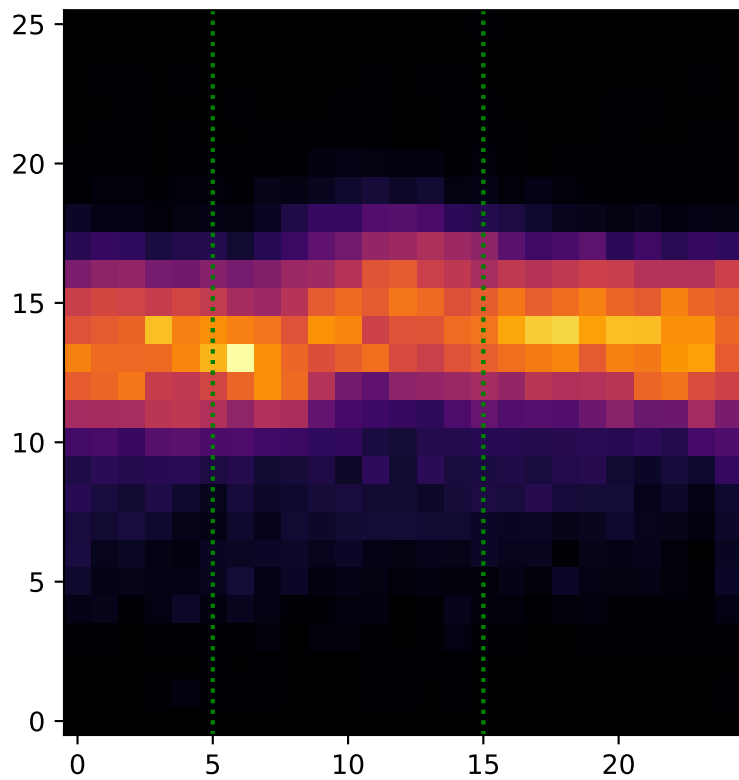


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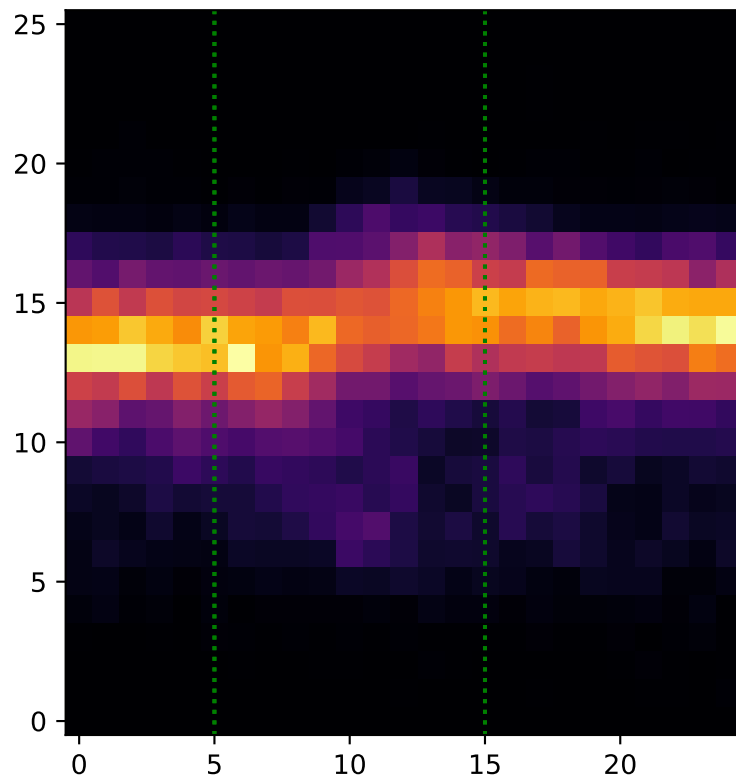


speed_head_tip | pval:0.5286486486486487

ctr

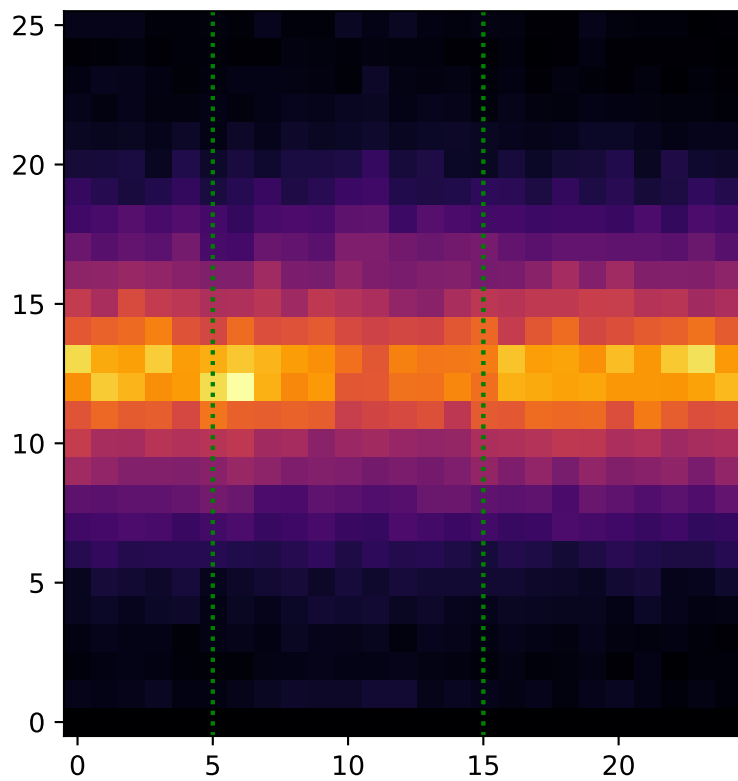


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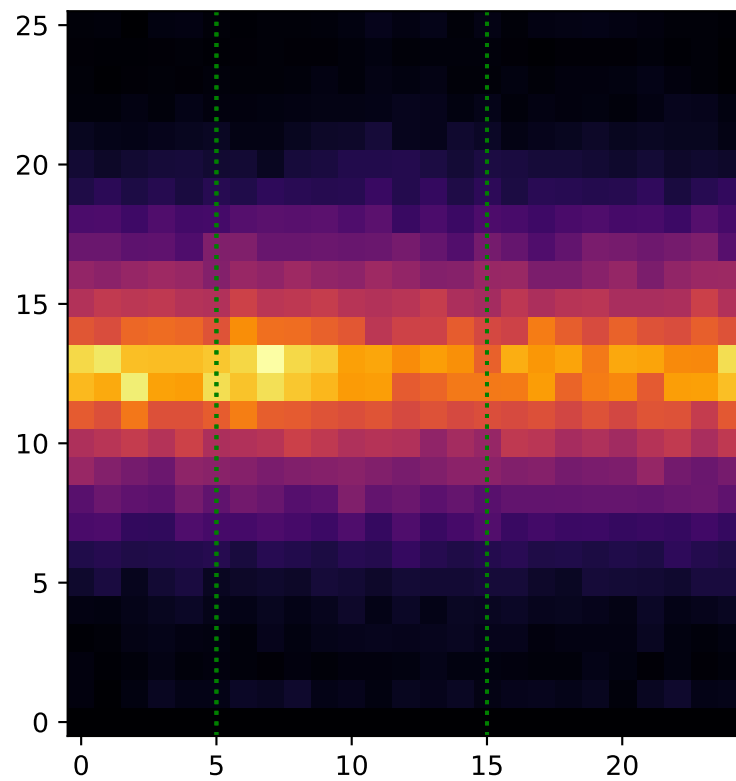


d_width_head_base | pval:0.5286486486486487

ctr

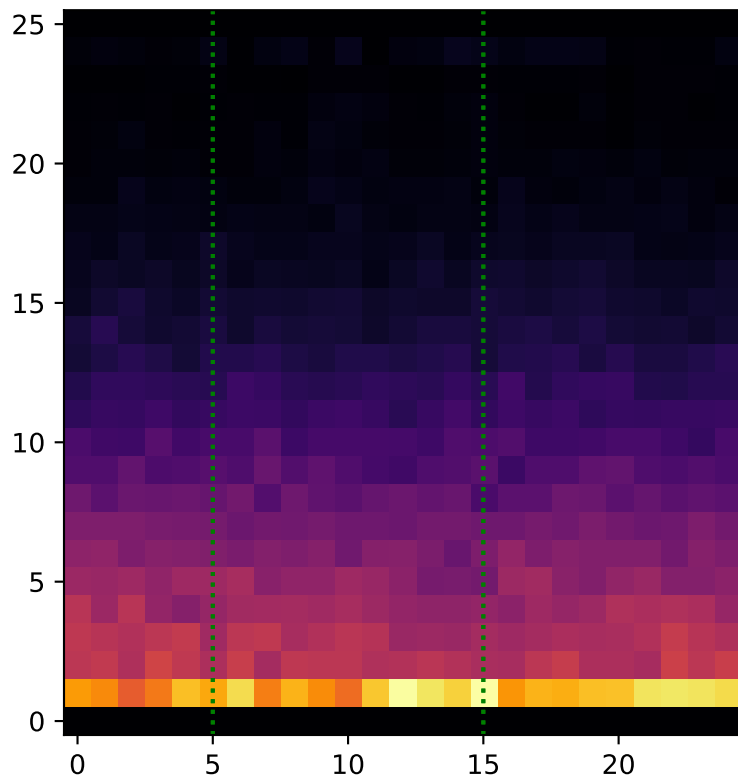


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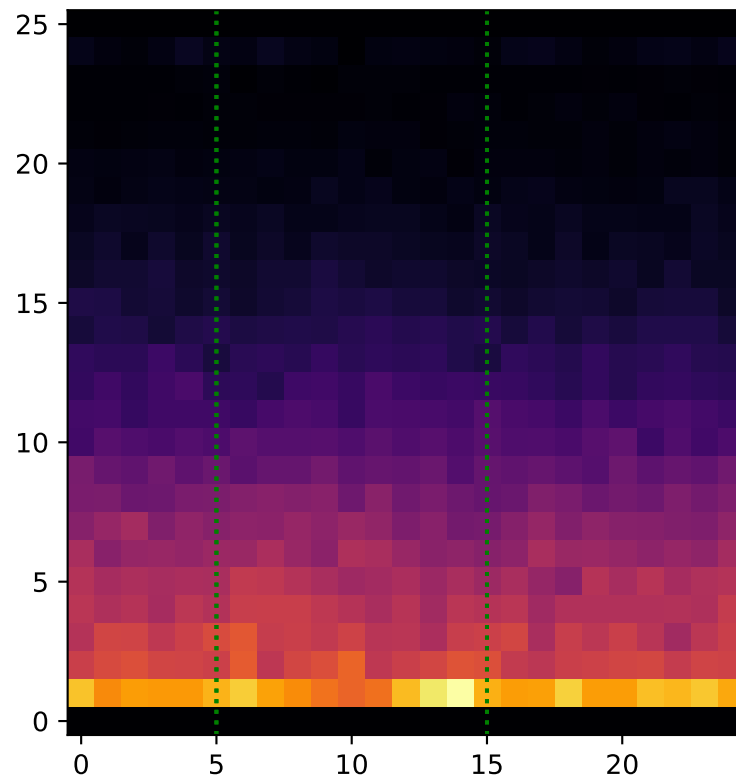


d_angular_velocity_head_tip | pval:0.5308108108108108

ctr

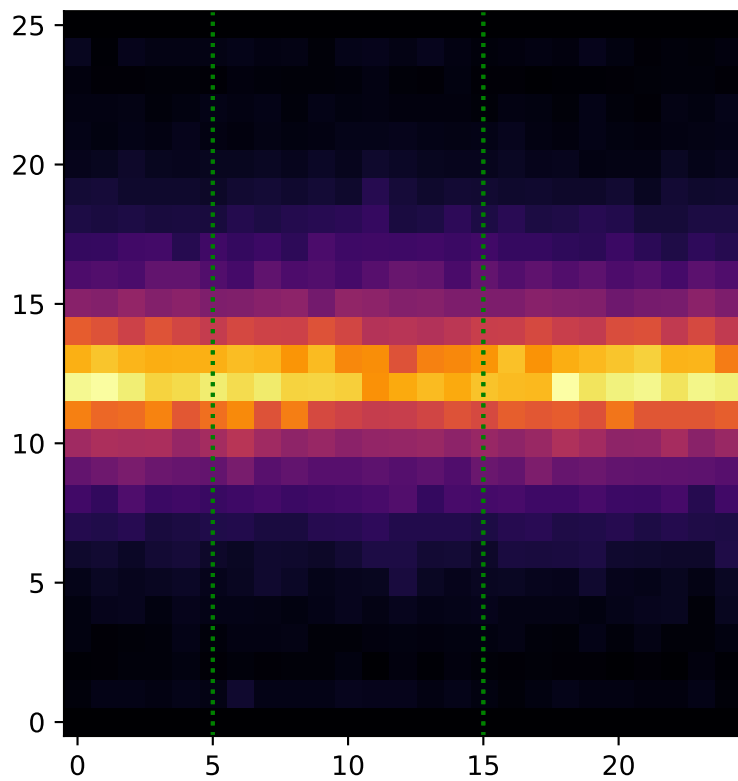


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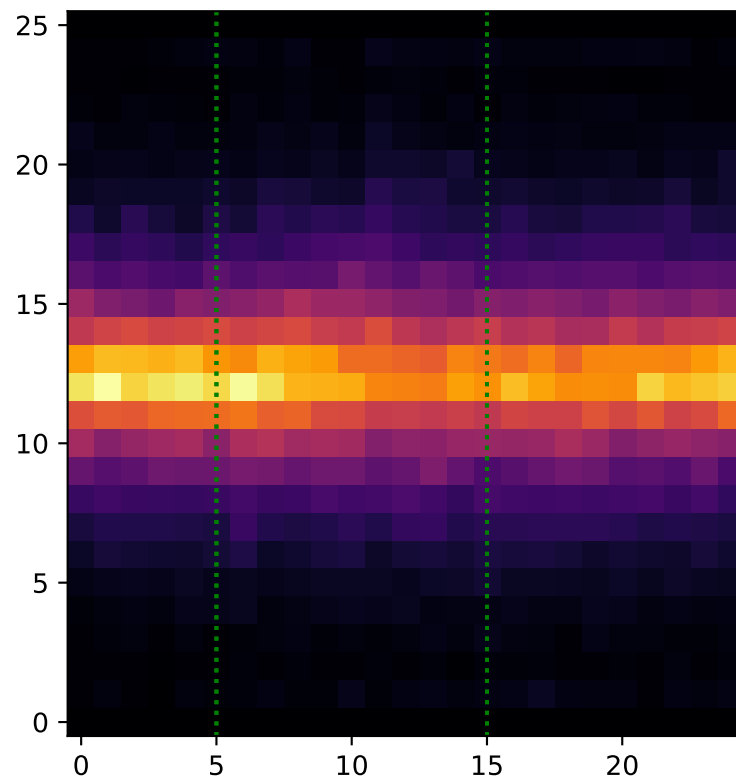


d_width_midbody | pval:0.532972972972973

ctr

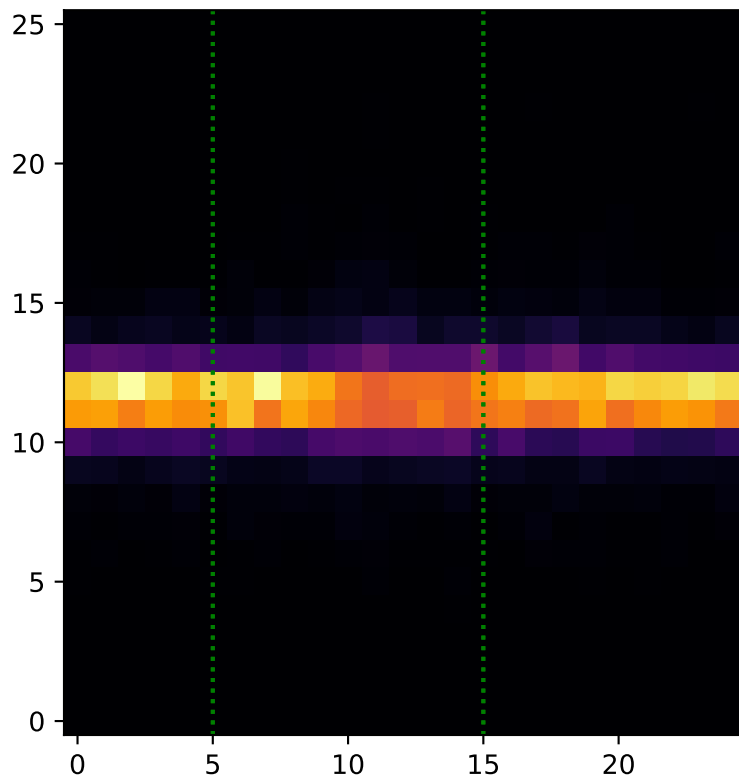


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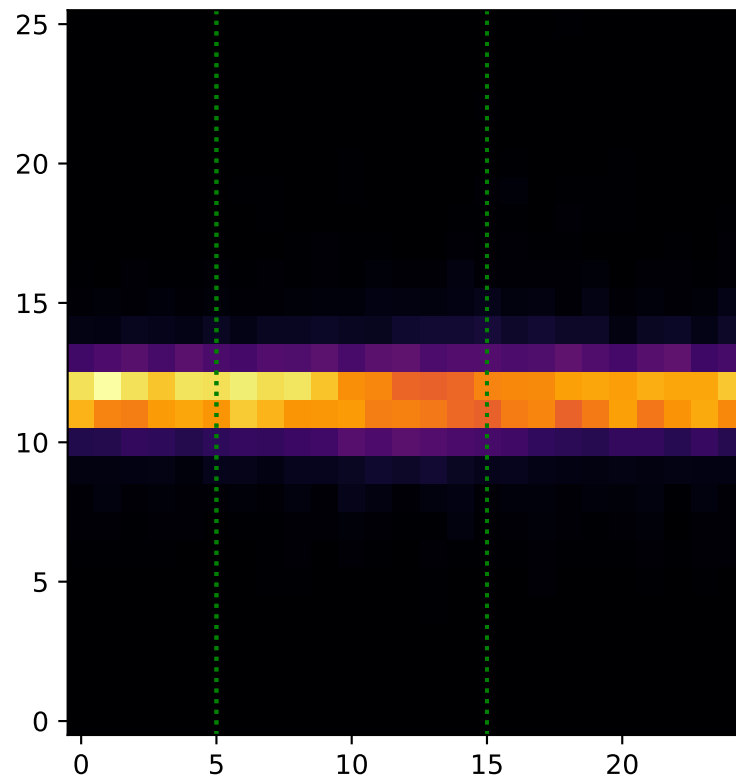


relative_to_body_radial_velocity_tail_tip | pval:0.5351351351351351

ctr

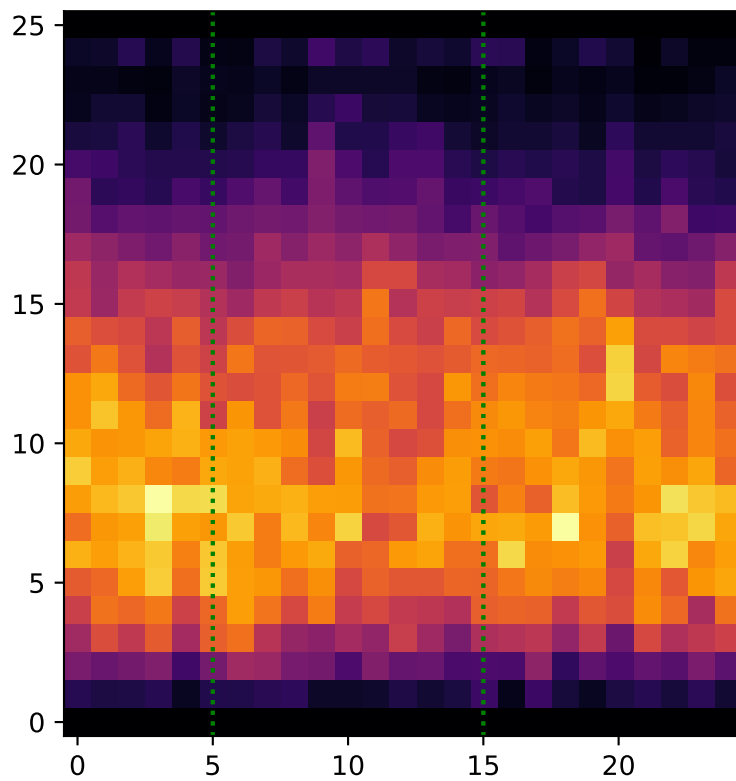


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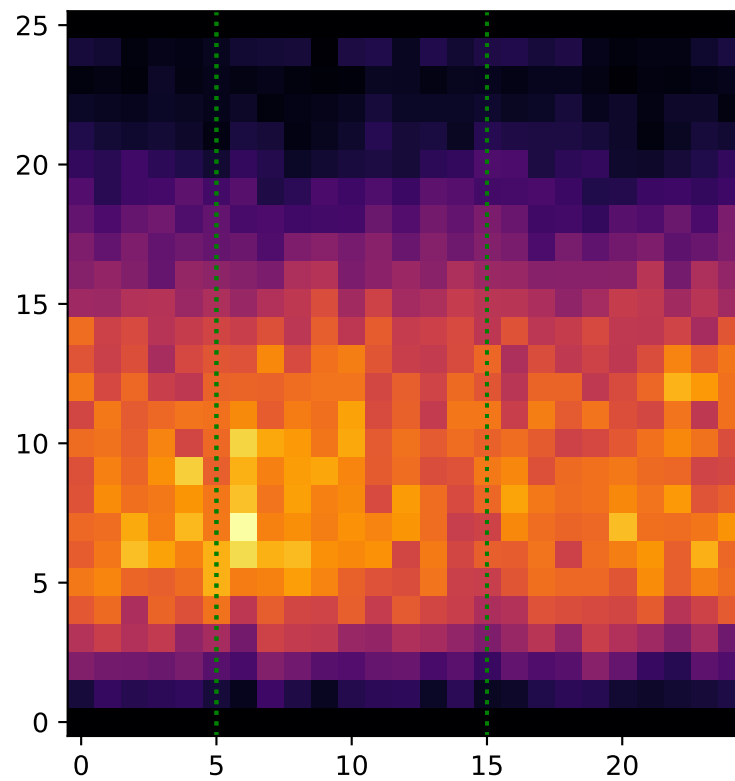


curvature_std_neck | pval:0.5394594594594595

ctr

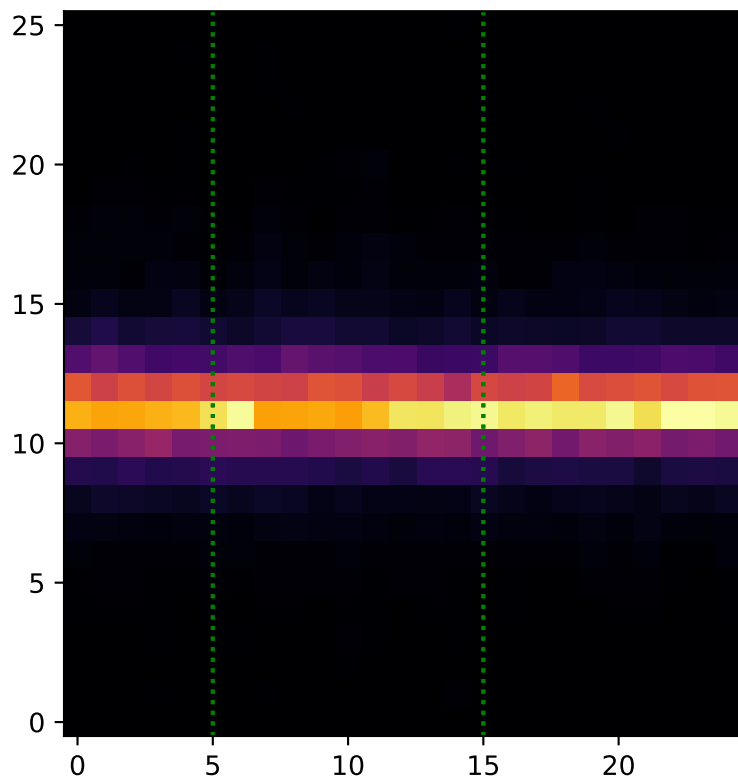


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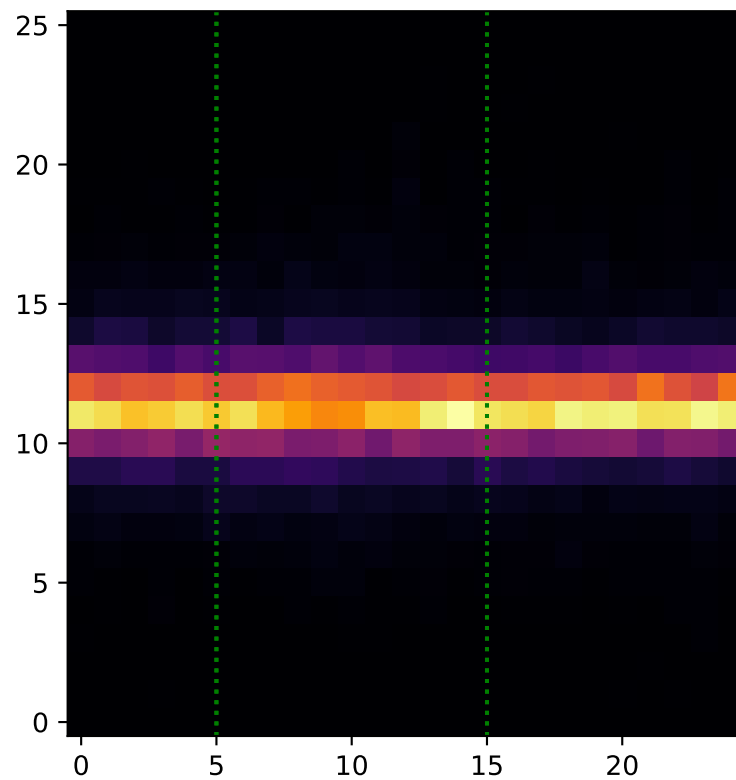


d_speed_head_tip | pval:0.5481081081081081

ctr

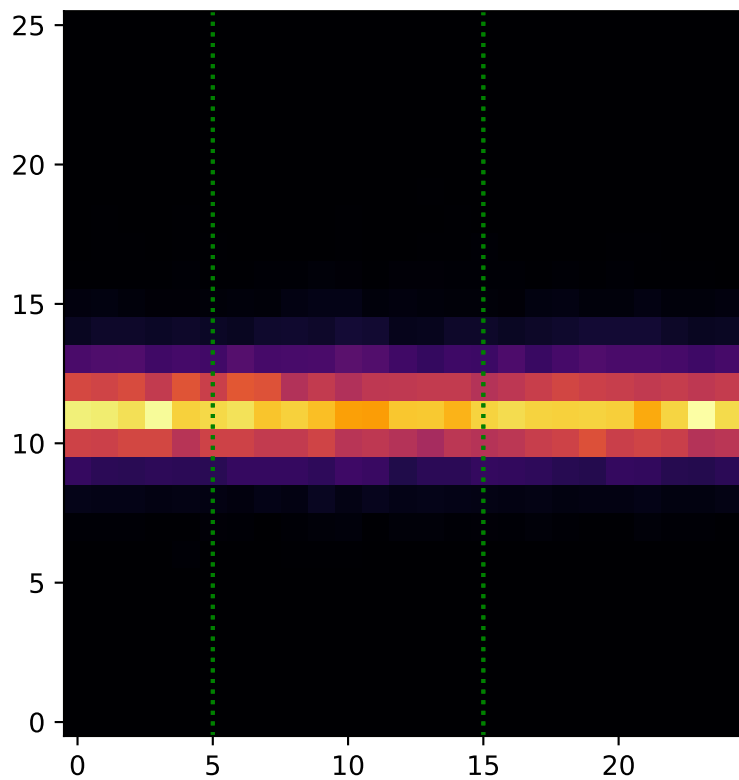


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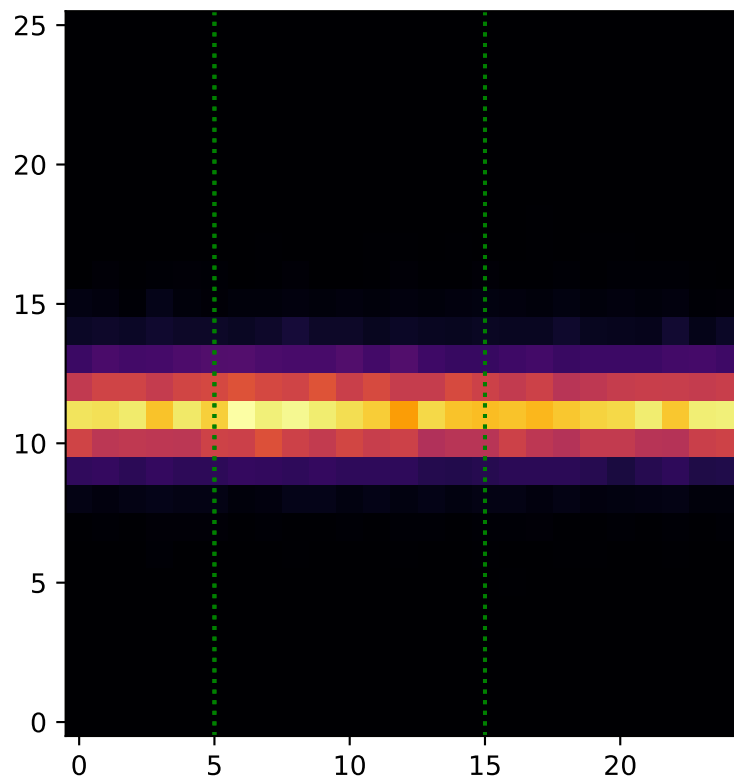


d_relative_to_head_base_radial_velocity_head_tip | pval:0.5610810810810811

ctr

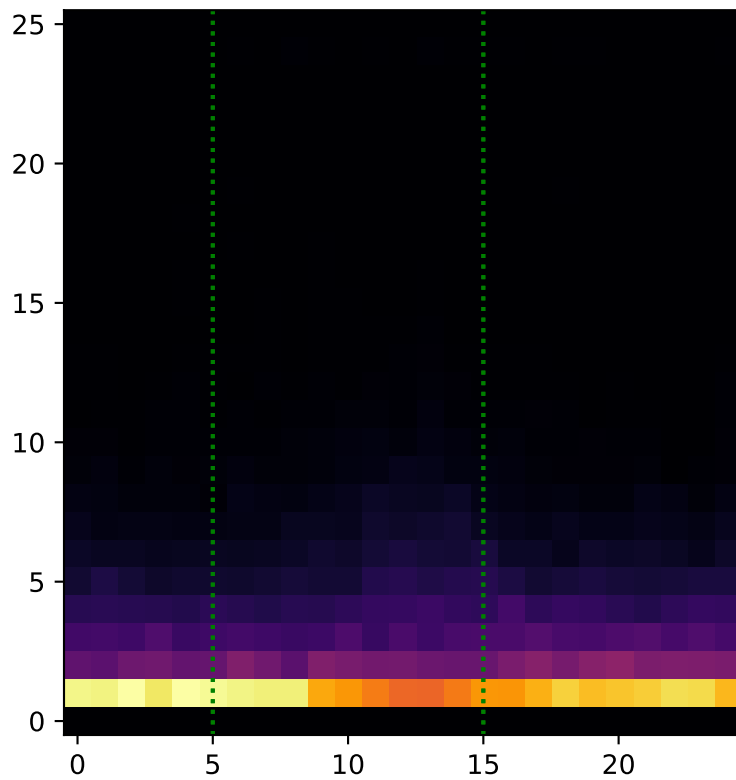


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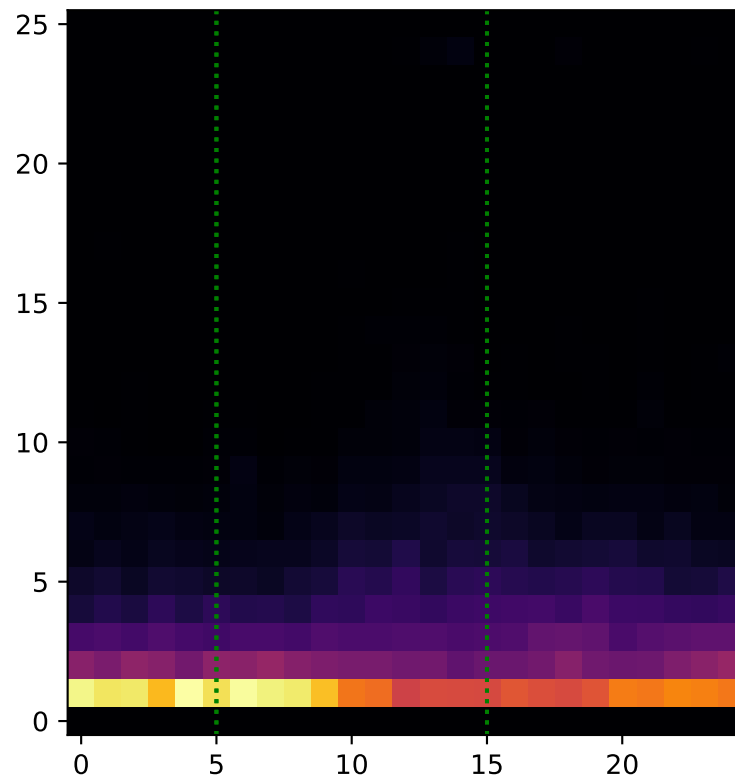


angular_velocity_midbody | pval:0.5654054054054054

ctr

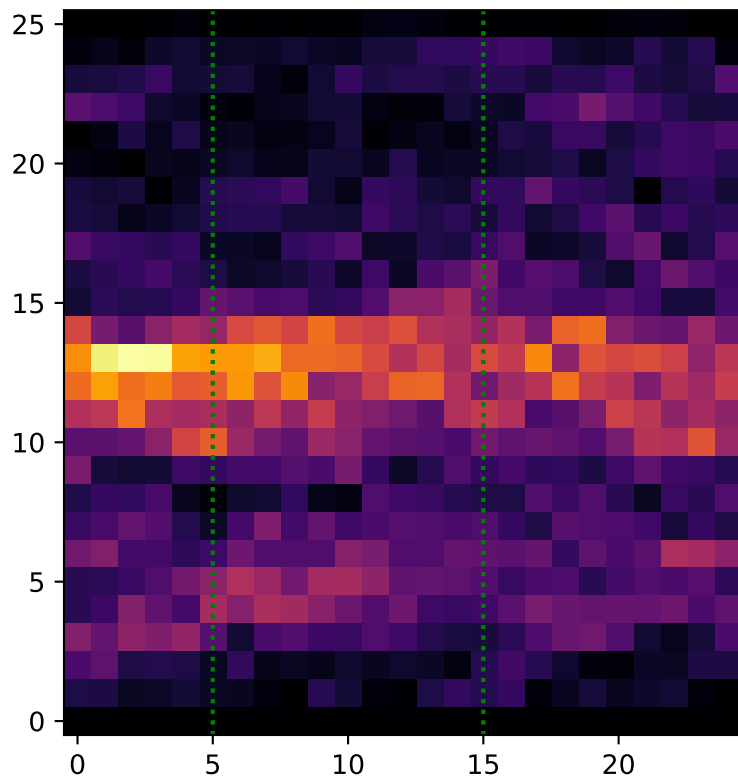


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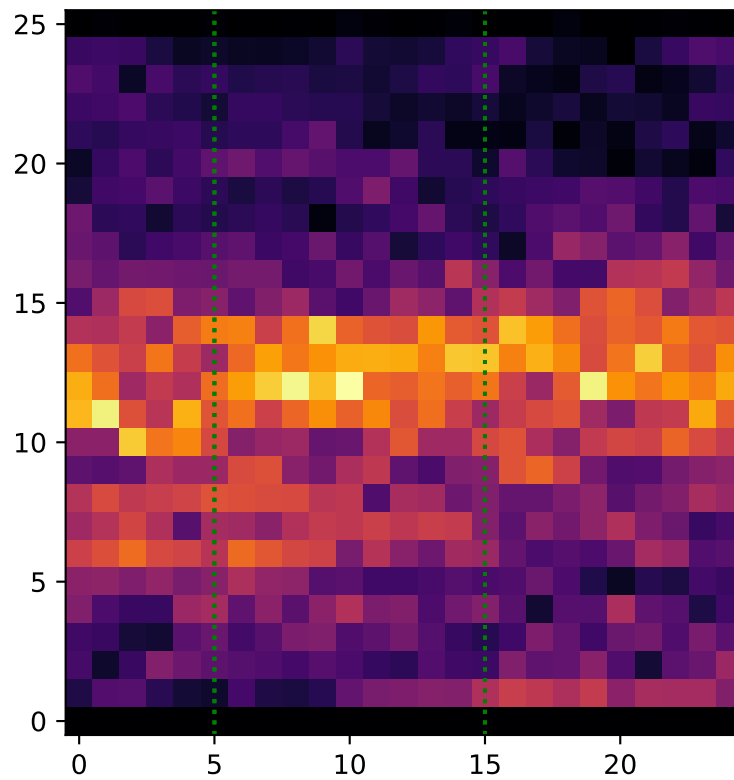


orientation_food_edge | pval:0.5718918918918919

ctr

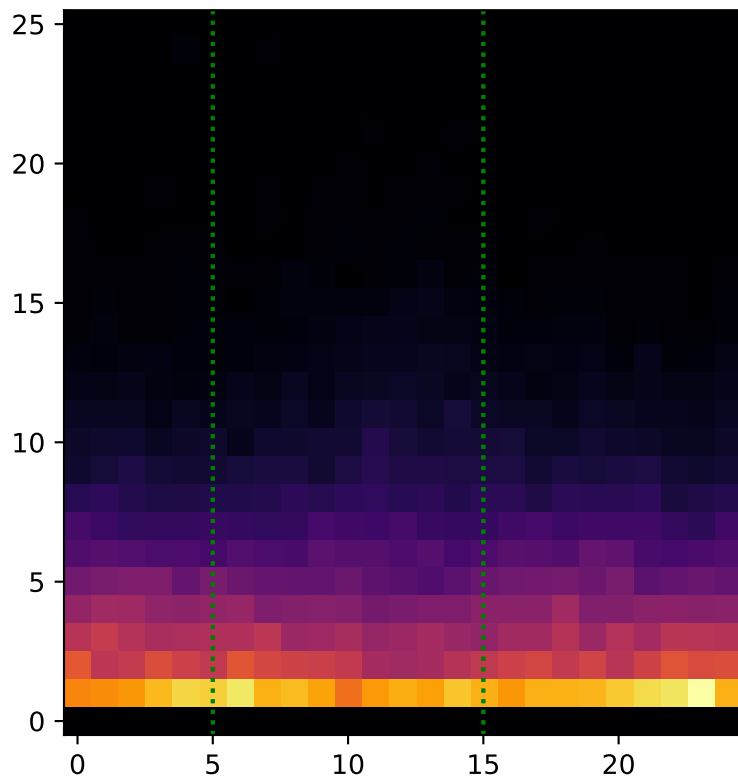


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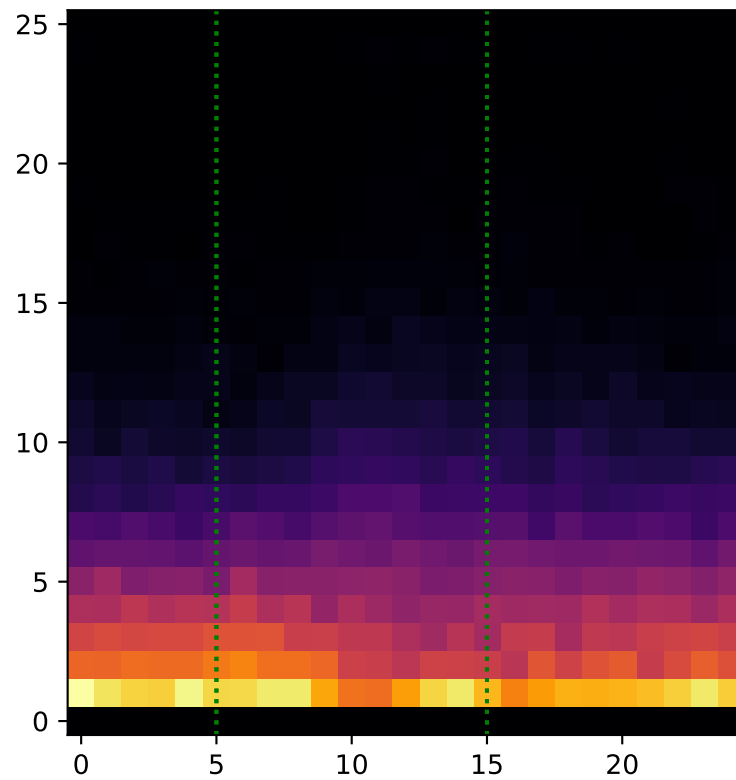


d_angular_velocity_head_base | pval:0.5718918918918919

ctr

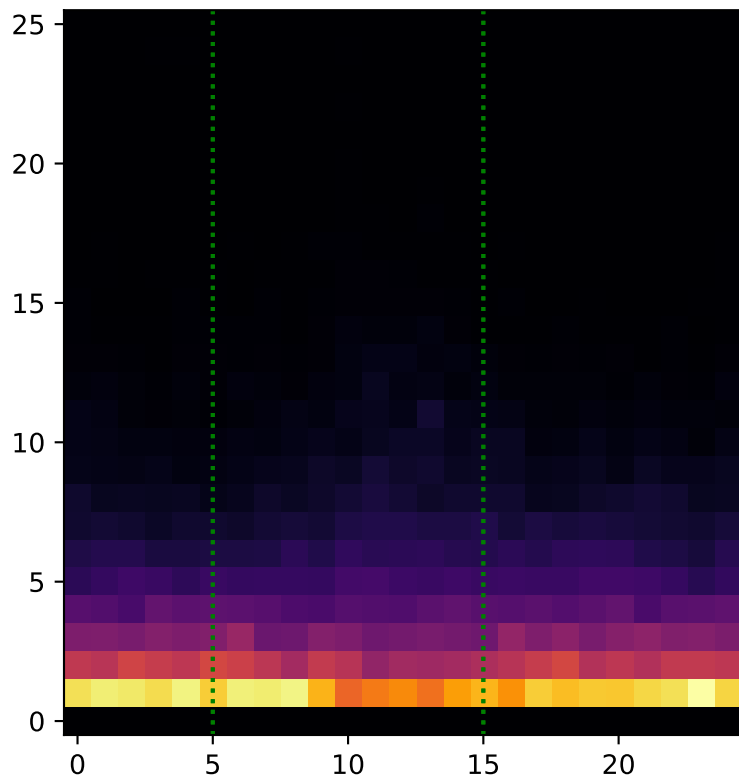


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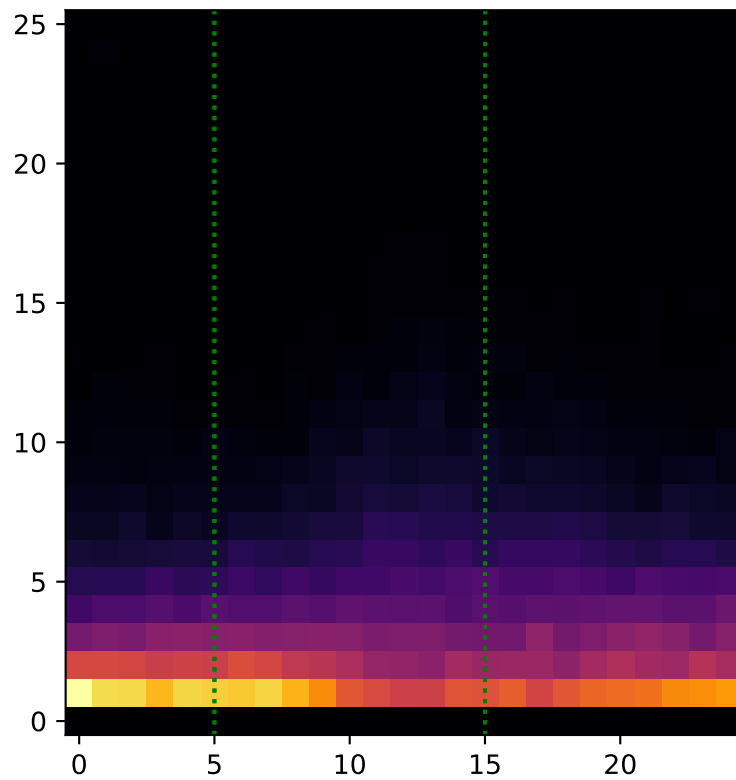


d_angular_velocity_neck | pval:0.5740540540540541

ctr

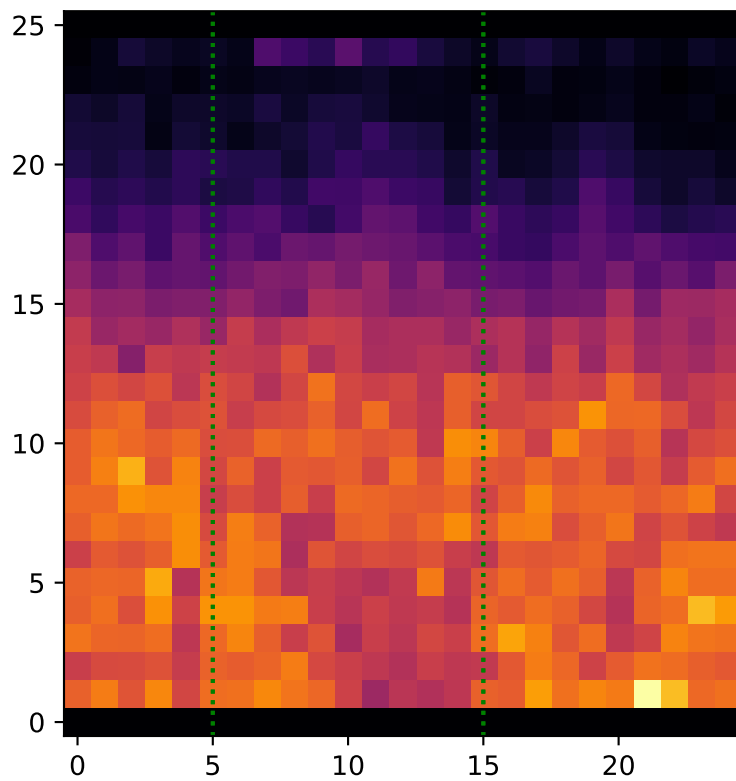


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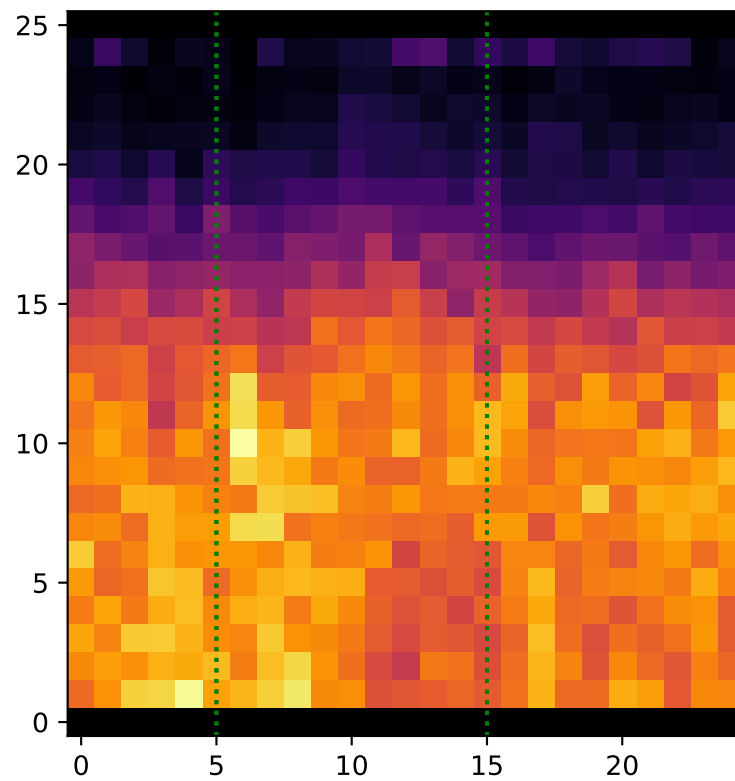


curvature_head | pval:0.587027027027027

ctr

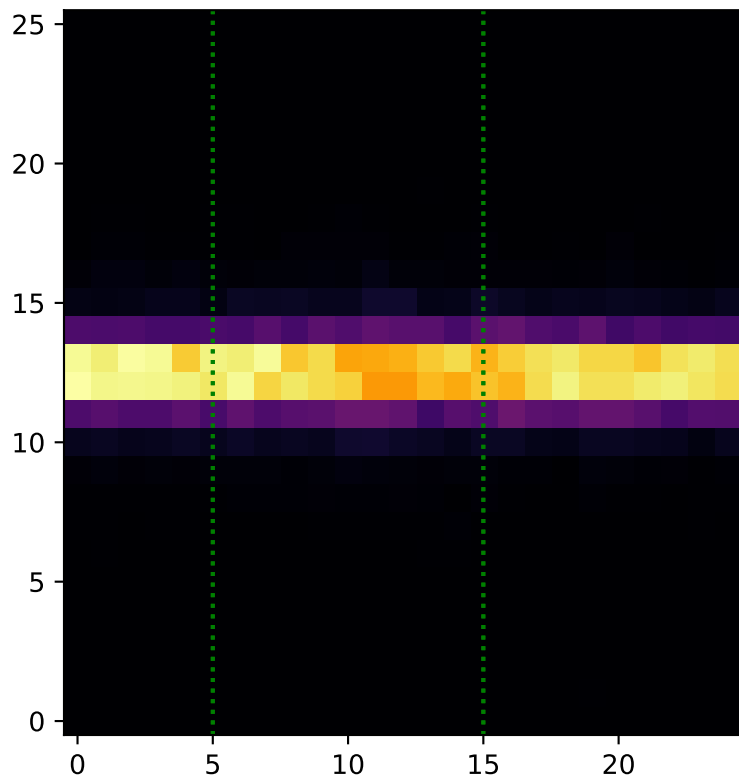


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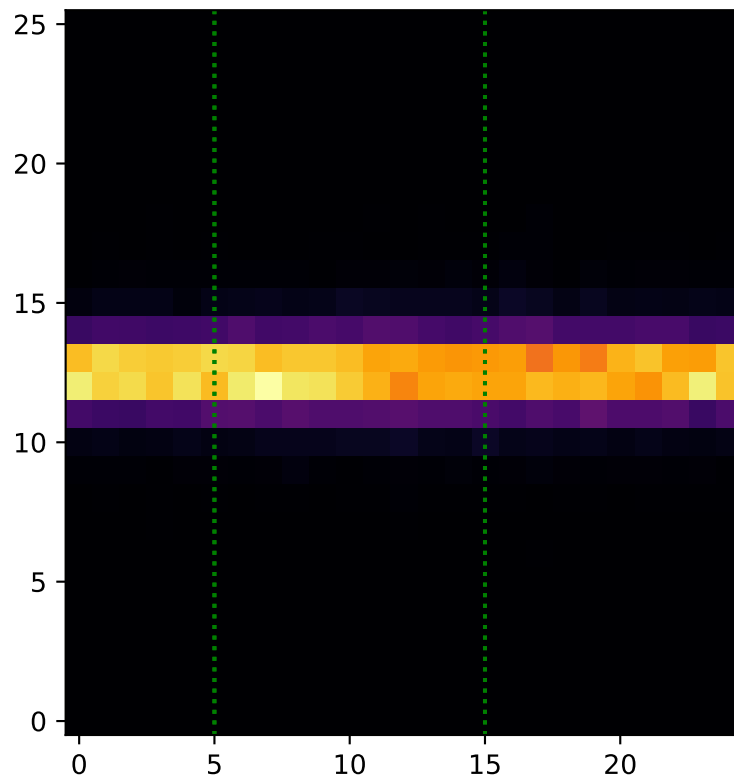


relative_to_tail_base_radial_velocity_tail_tip | pval:0.5956756756756757

ctr

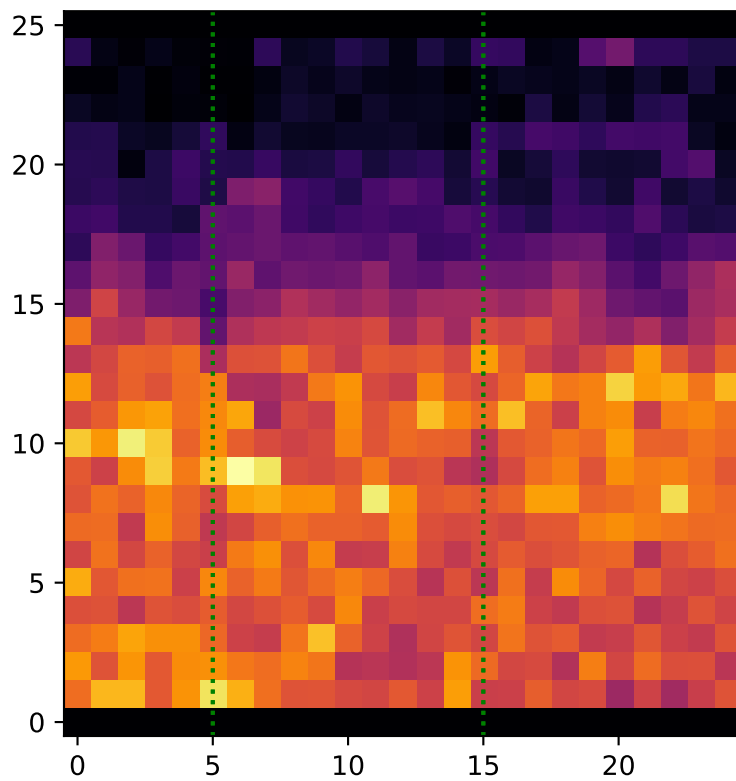


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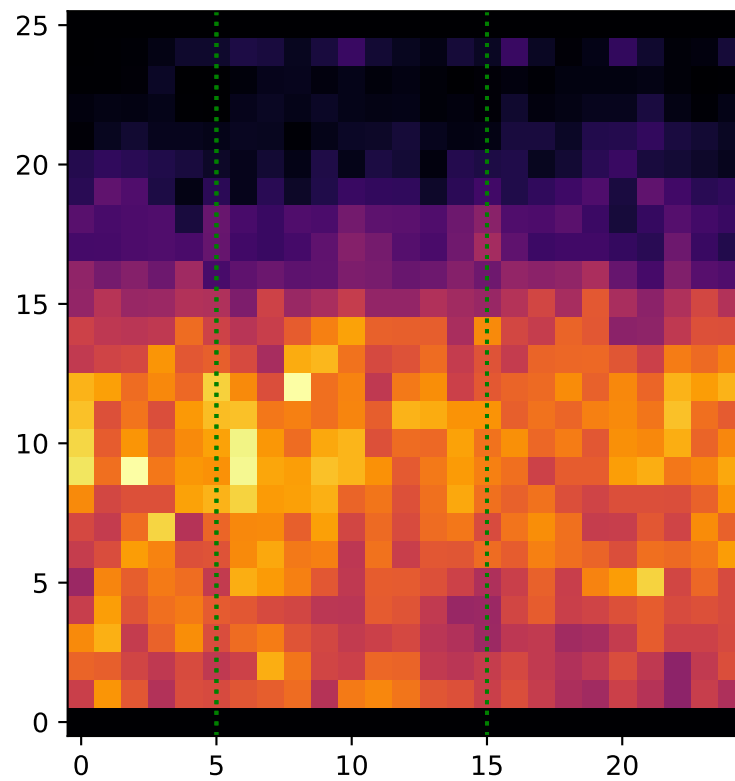


curvature_mean_tail | pval:0.5956756756756757

ctr

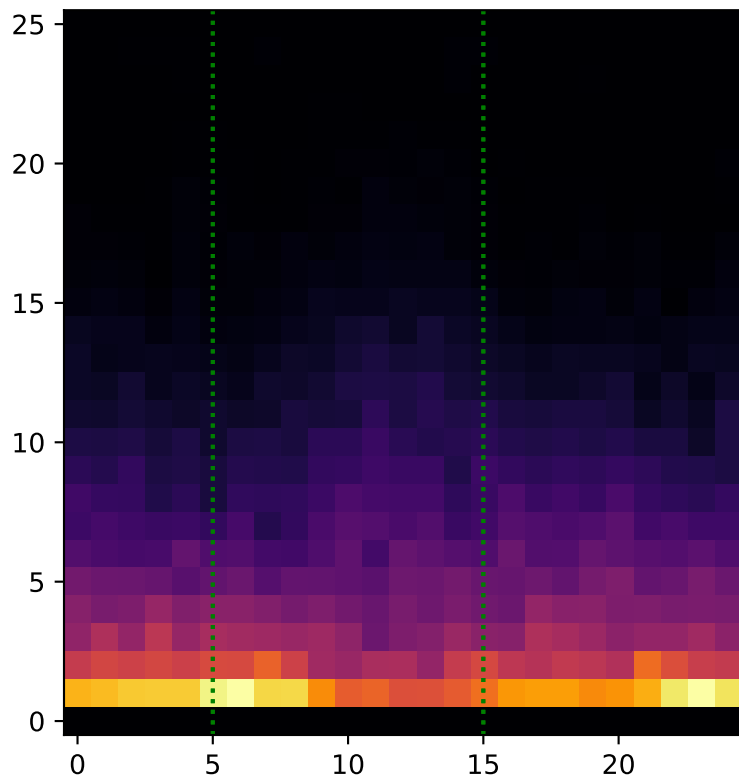


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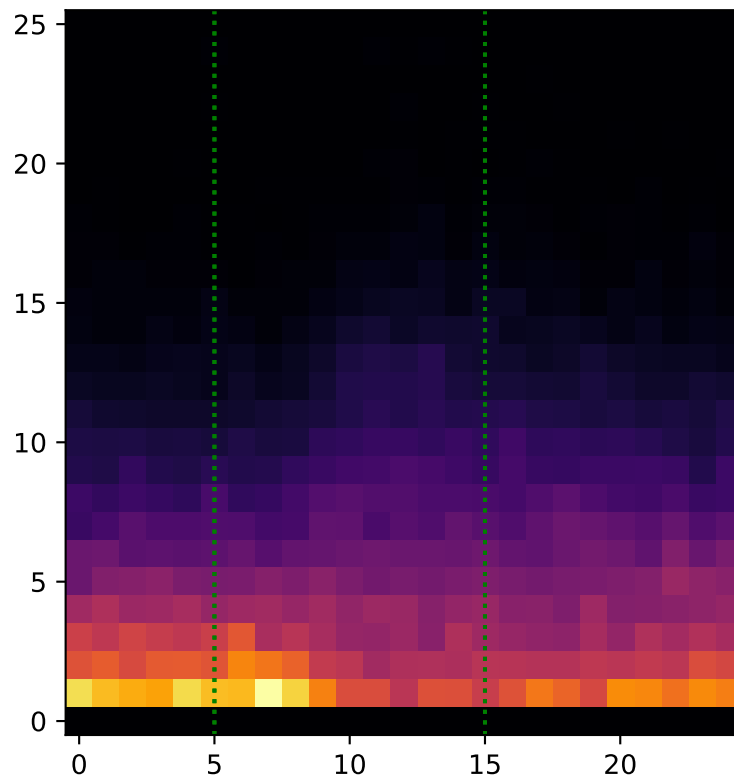


angular_velocity_head_base | pval:0.6

ctr

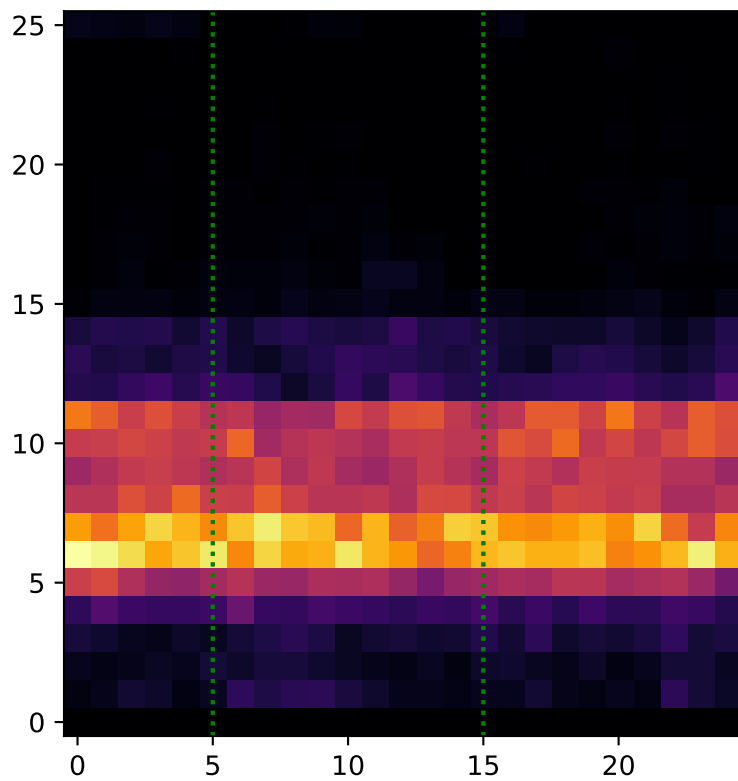


atr

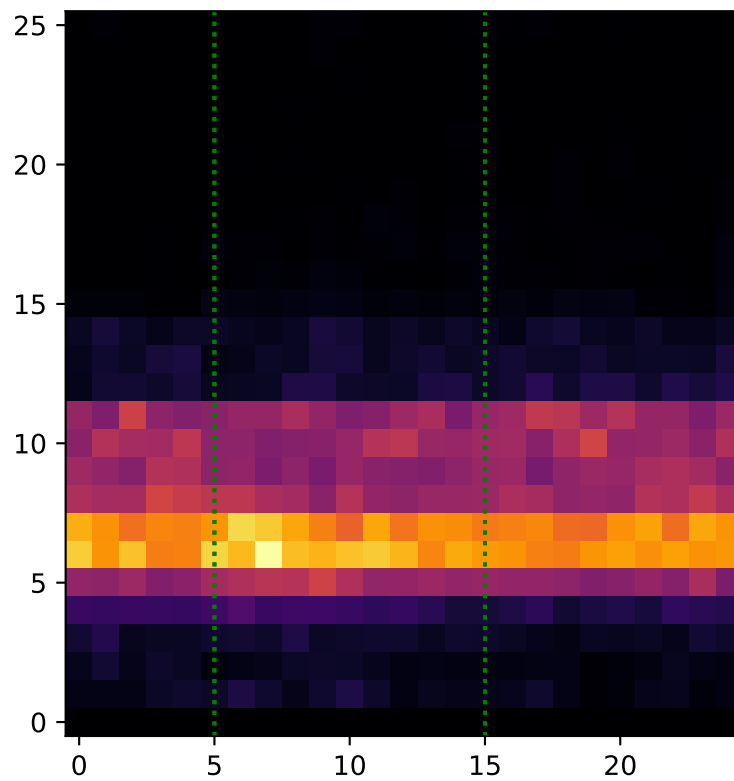


width_tail_base | pval:0.6021621621621621

ctr

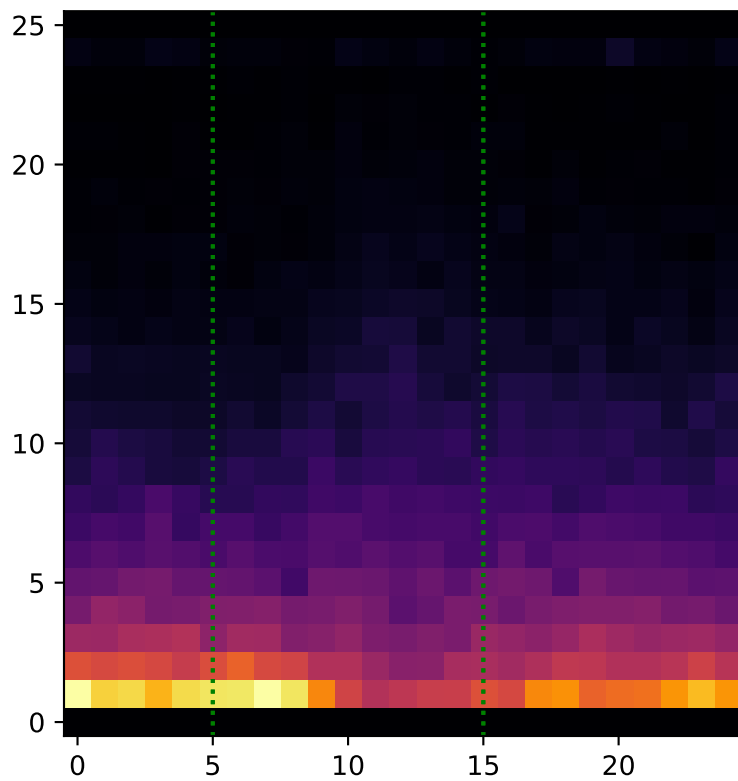


atr

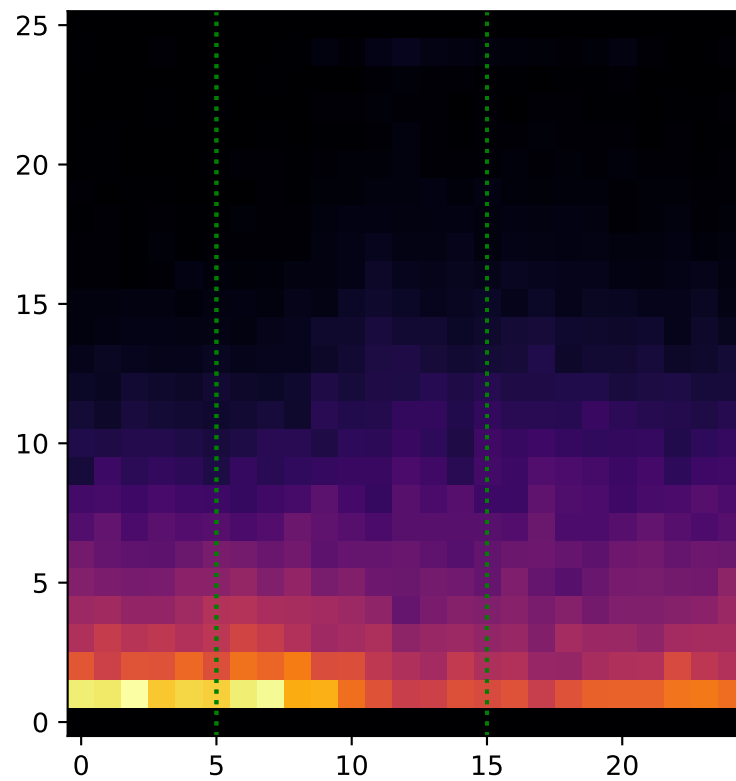


d_curvature_tail | pval:0.6021621621621621

ctr

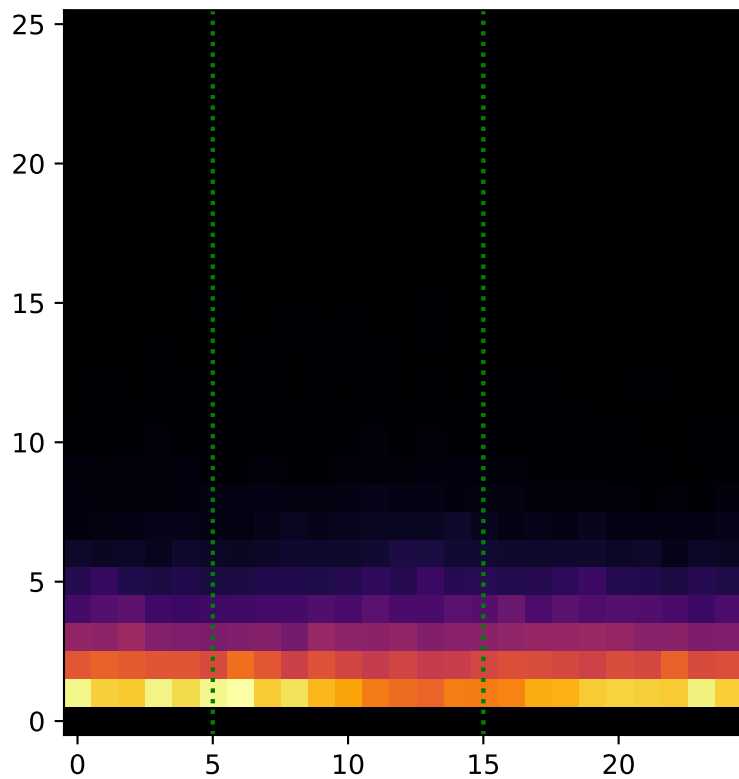


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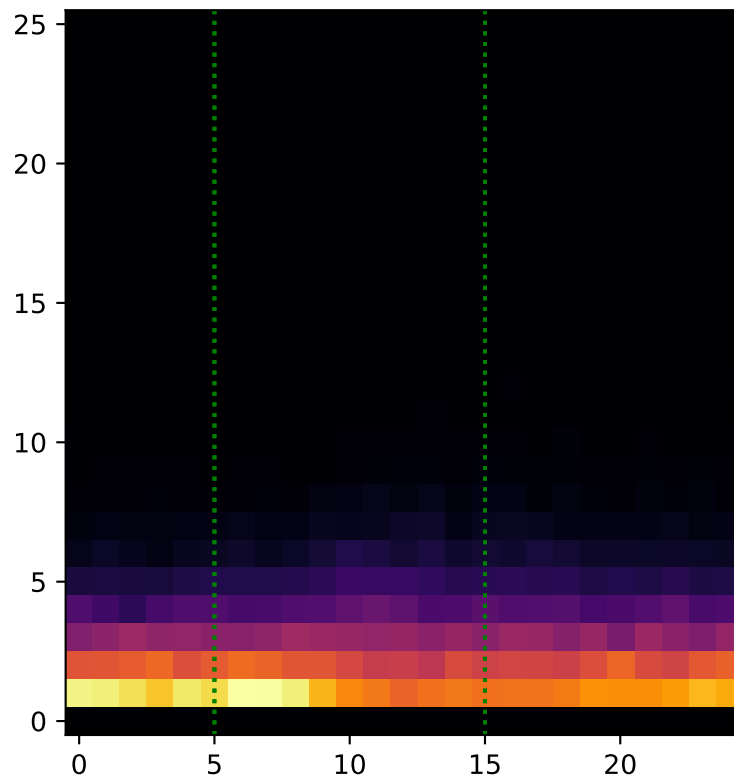


d_relative_to_body_angular_velocity_head_tip | pval:0.6108108108108108

ctr

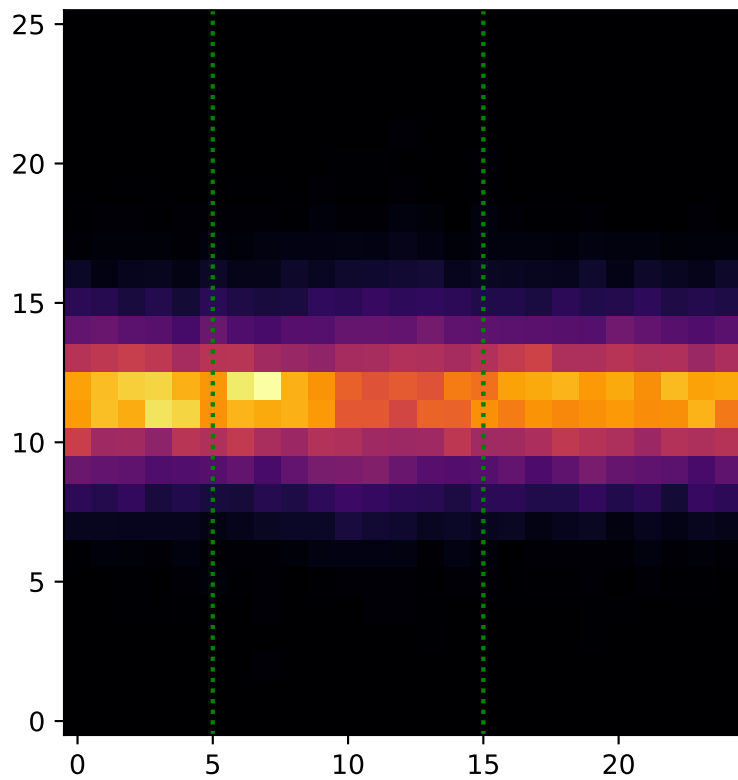


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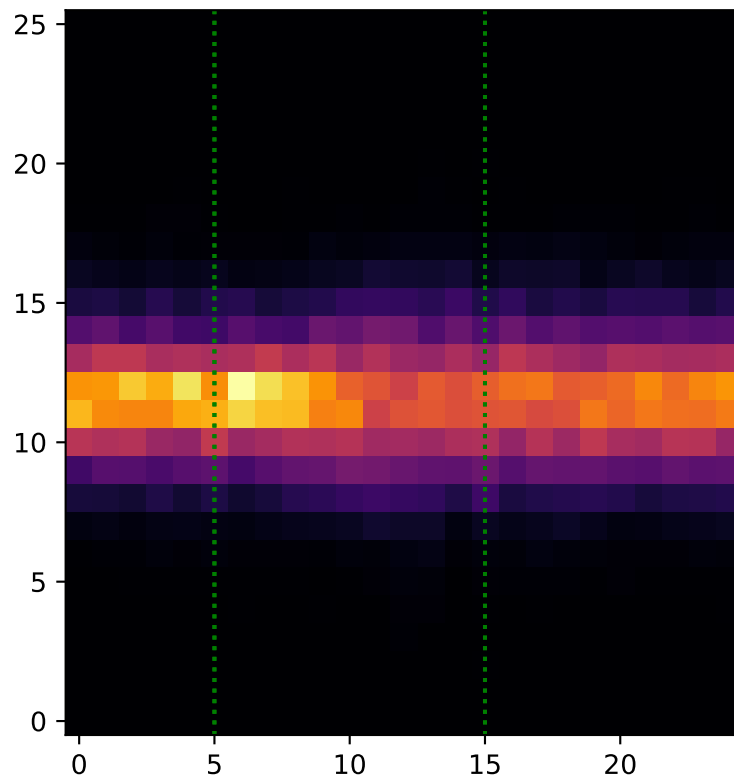


relative_to_neck_radial_velocity_head_tip | pval:0.6194594594594595

ctr

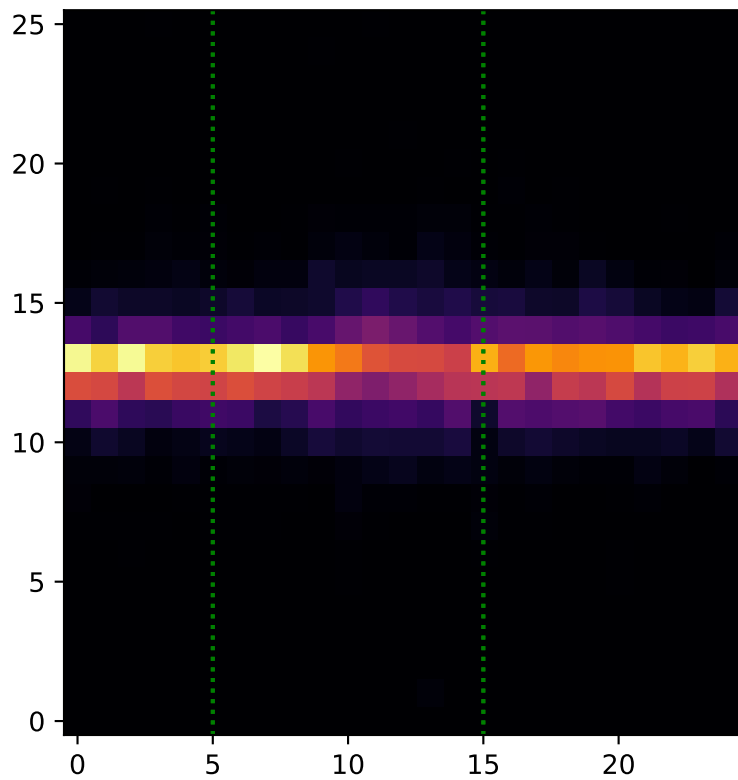


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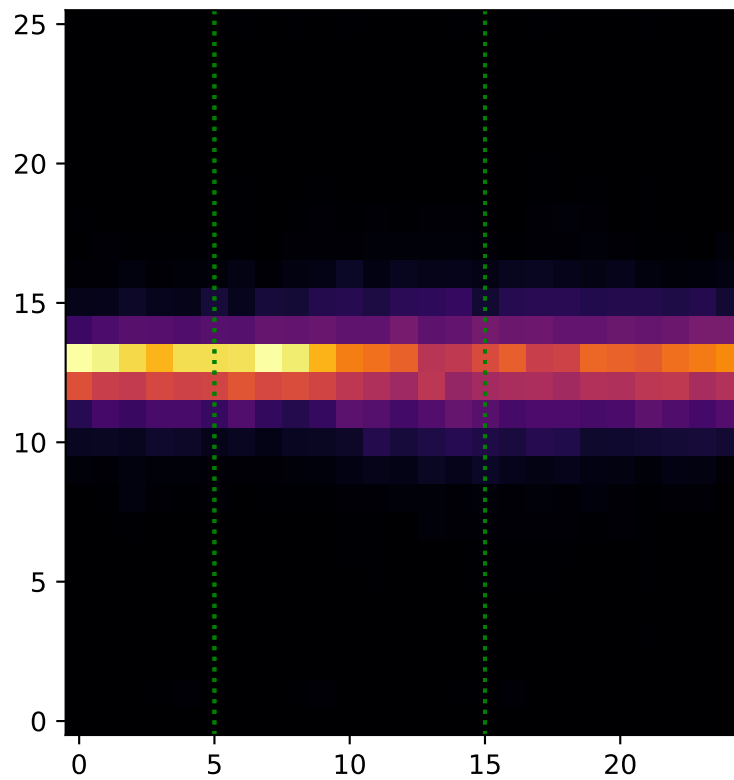


d_orientation_food_edge | pval:0.6237837837837837

ctr

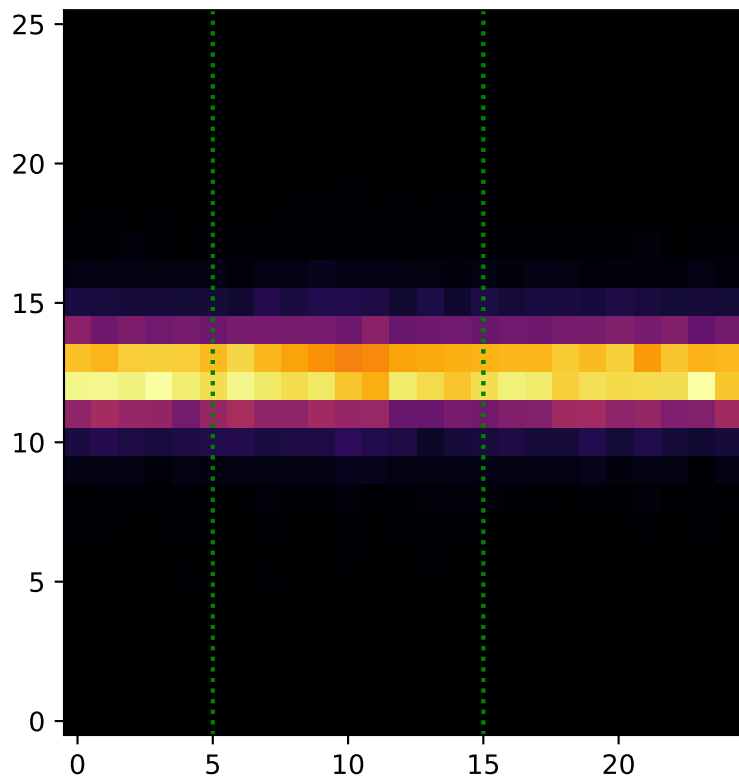


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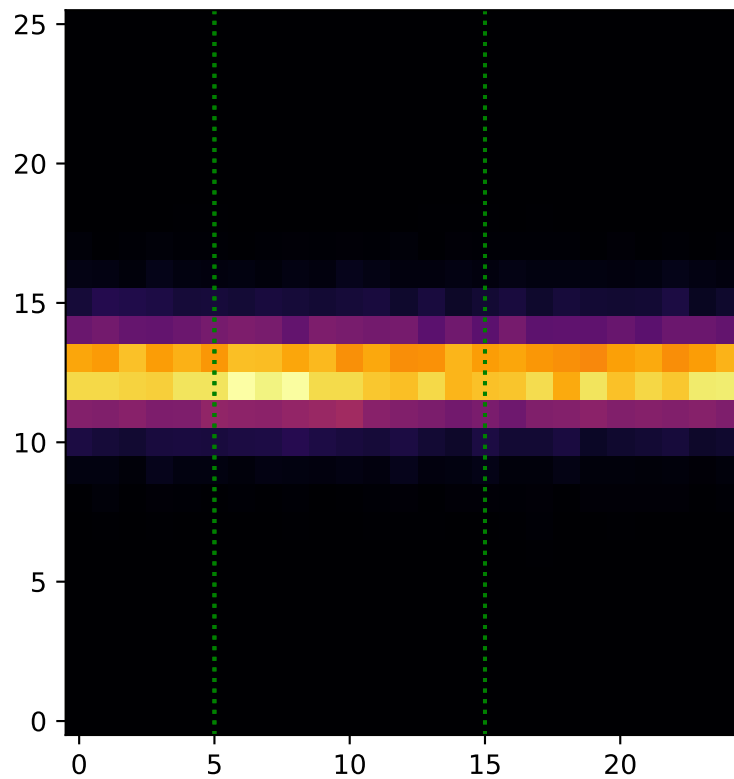


relative_to_head_base_radial_velocity_head_tip | pval:0.6410810810810811

ctr

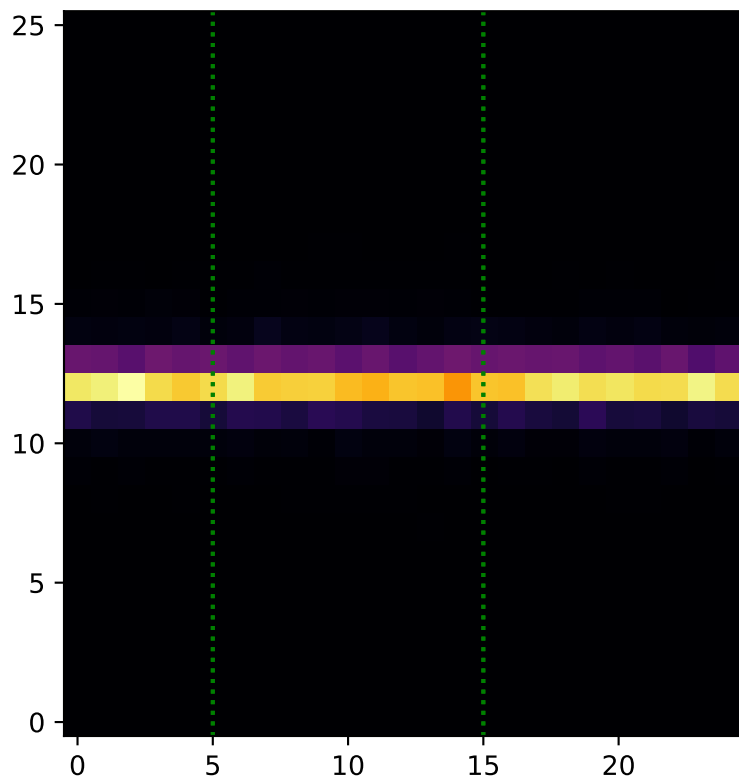


atr

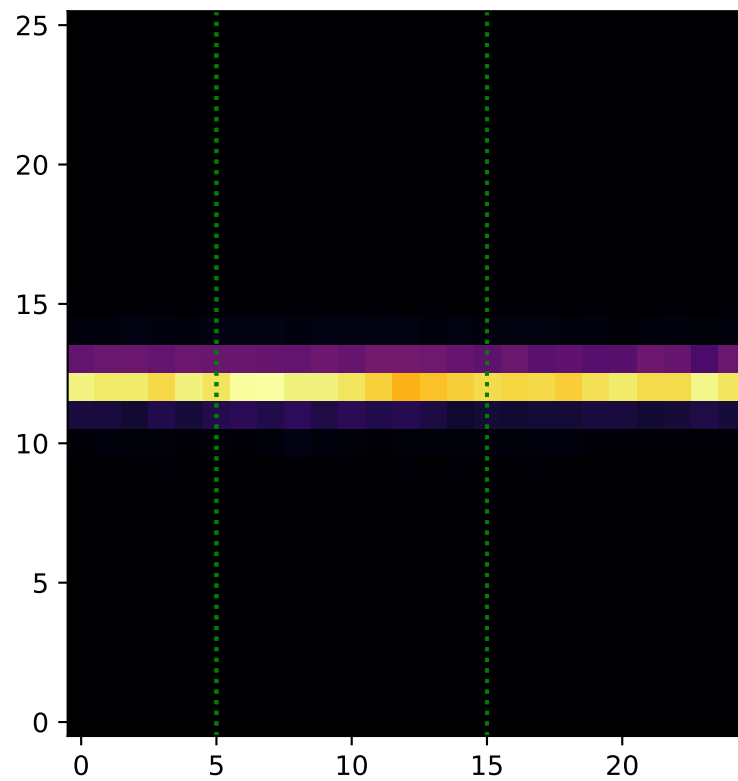


d_length | pval:0.6432432432432432

ctr

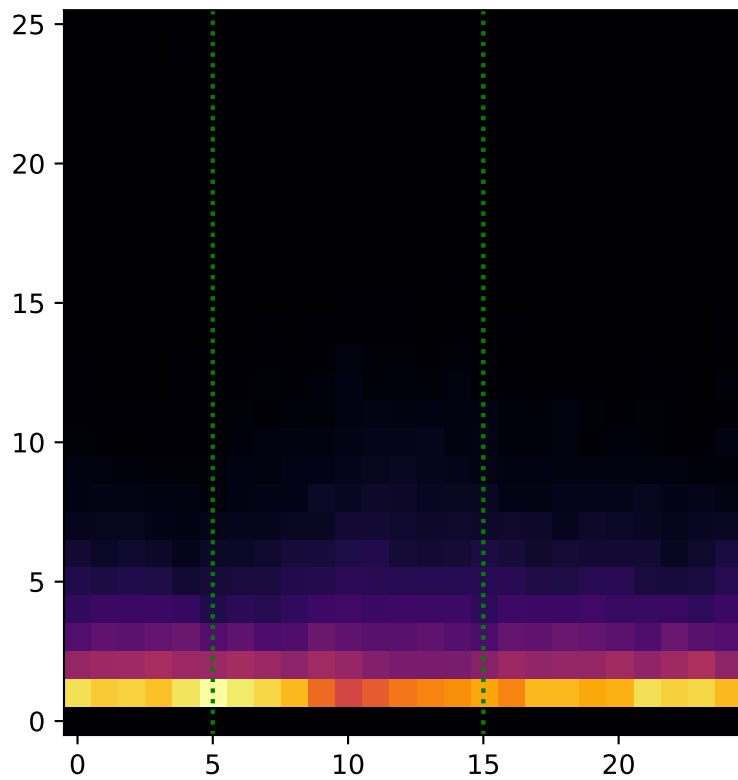


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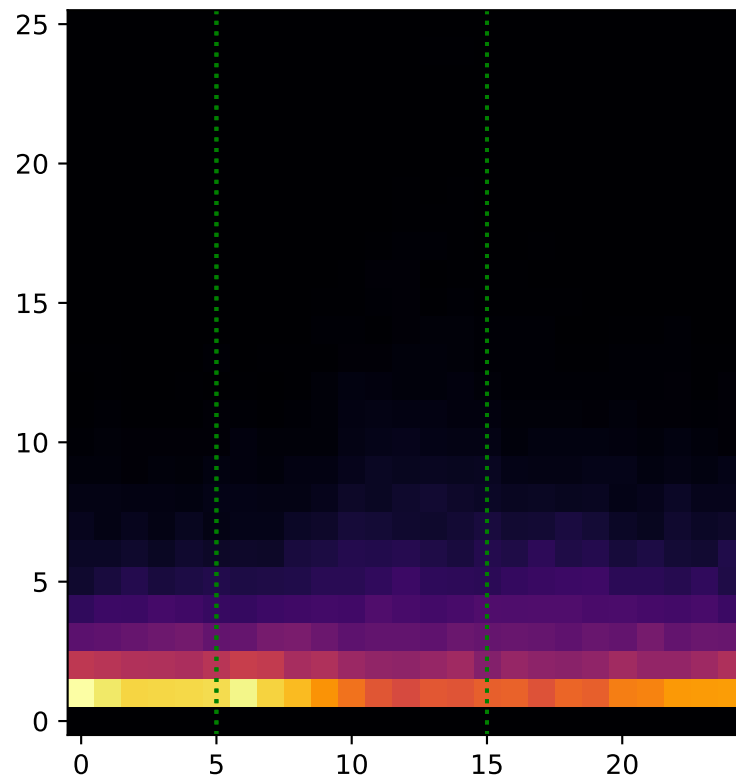


d_angular_velocity_hips | pval:0.6454054054054054

ctr

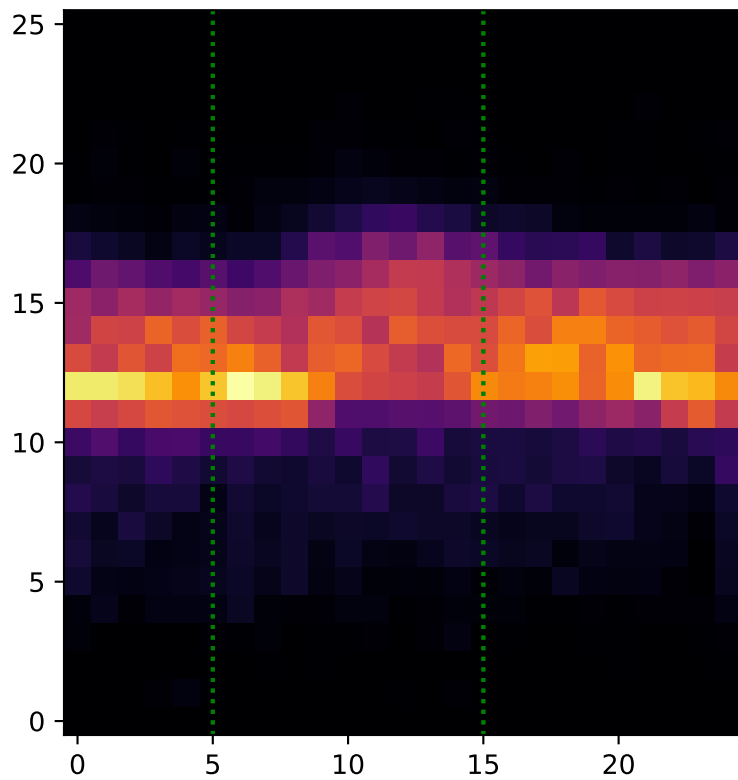


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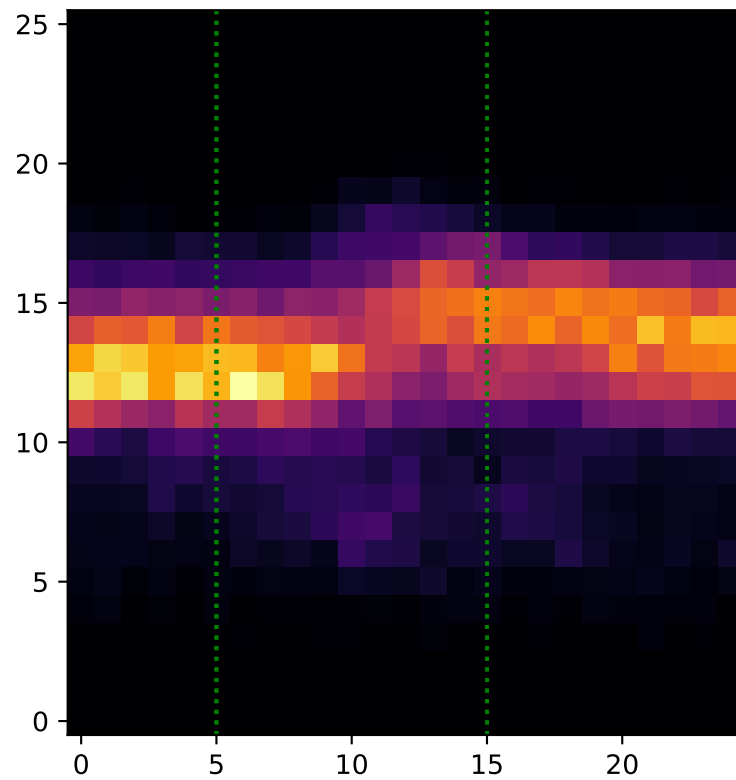


speed_head_base | pval:0.6475675675675676

ctr

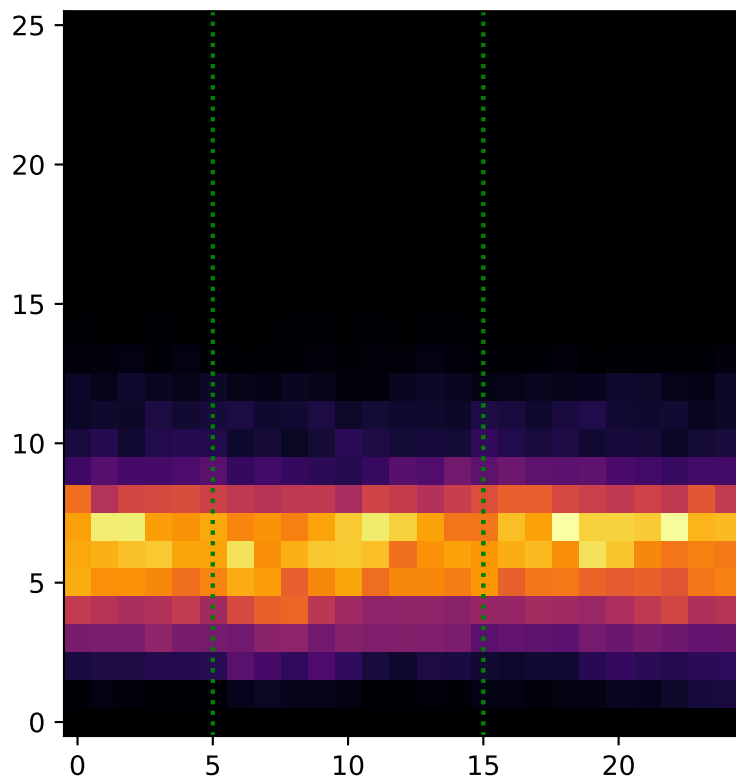


atr

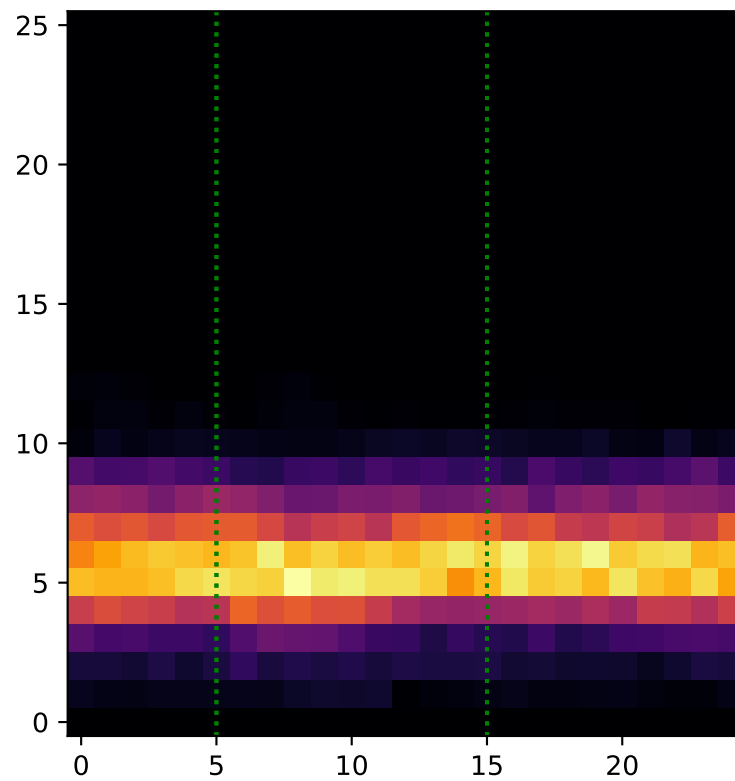


area | pval:0.667027027027027

ctr

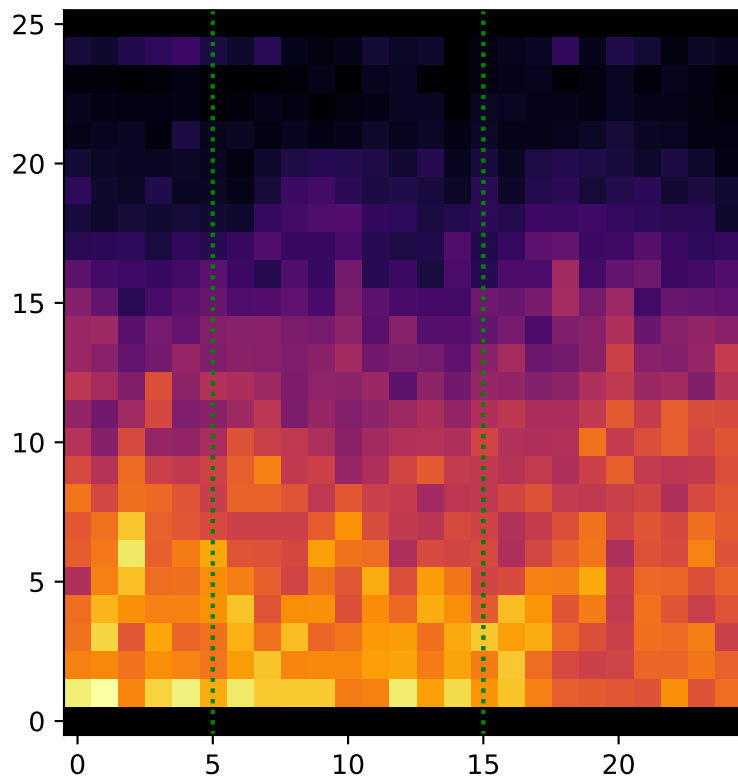


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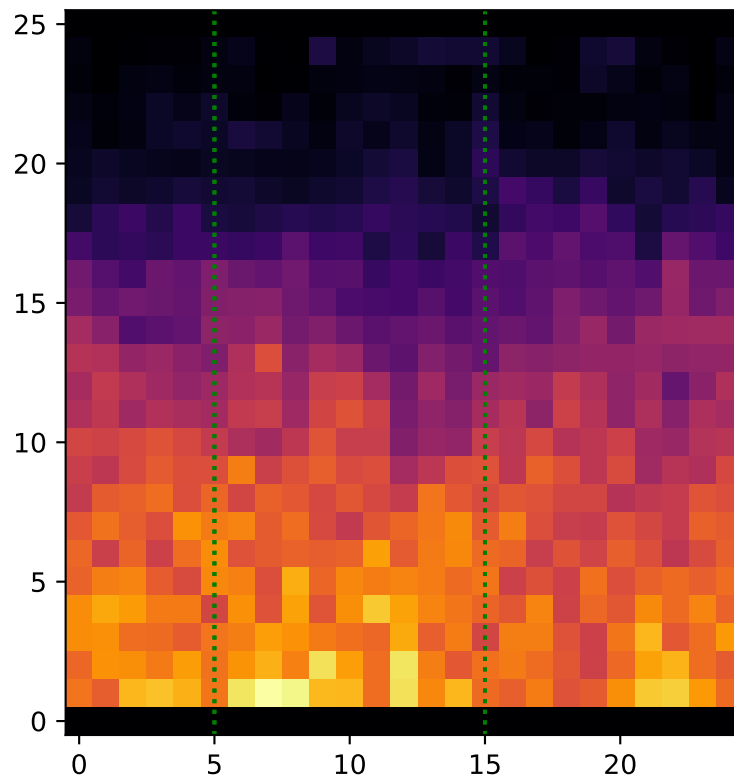


eigen_projection_4 | pval:0.667027027027027

ctr

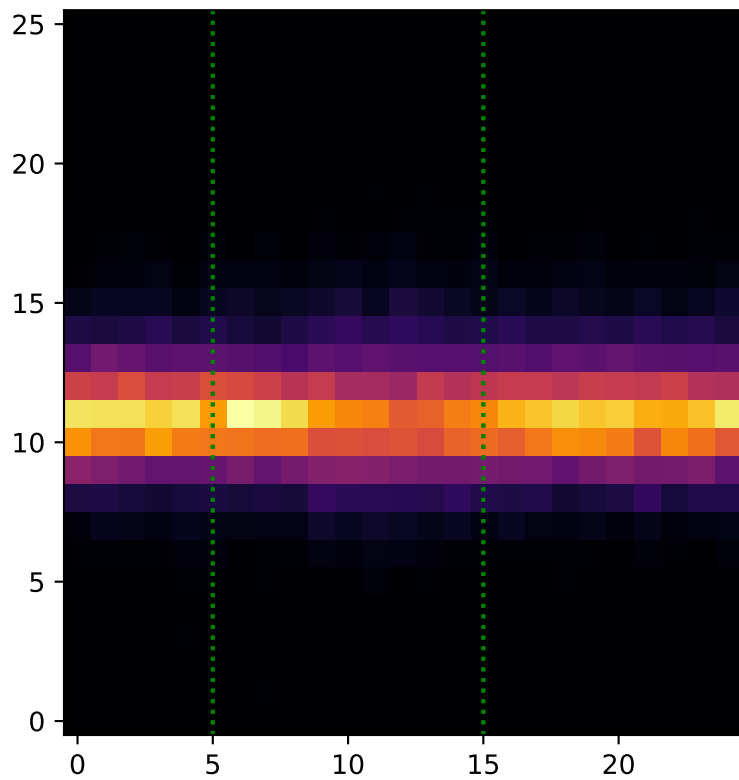


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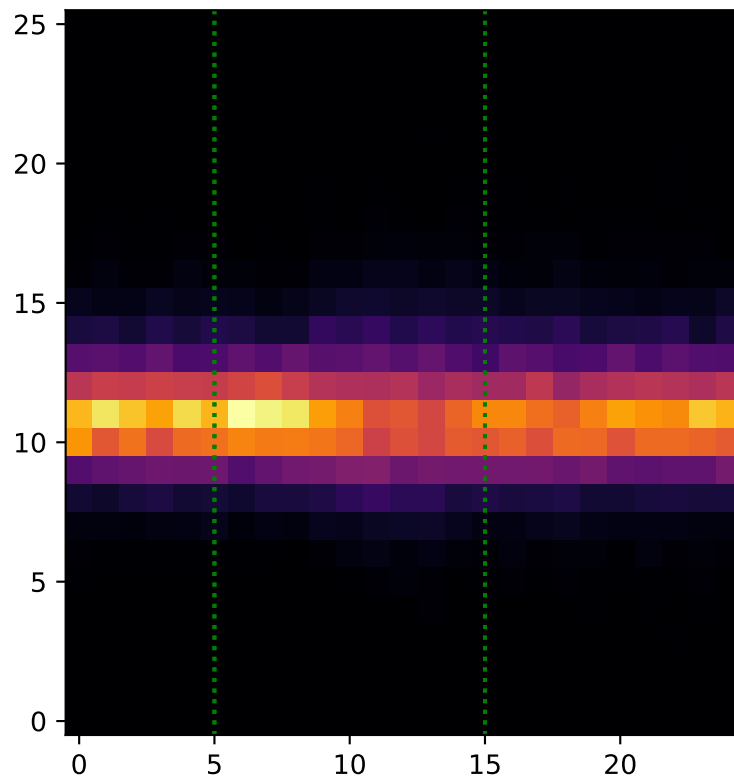


d_relative_to_body_radial_velocity_head_tip | pval:0.667027027027027

ctr

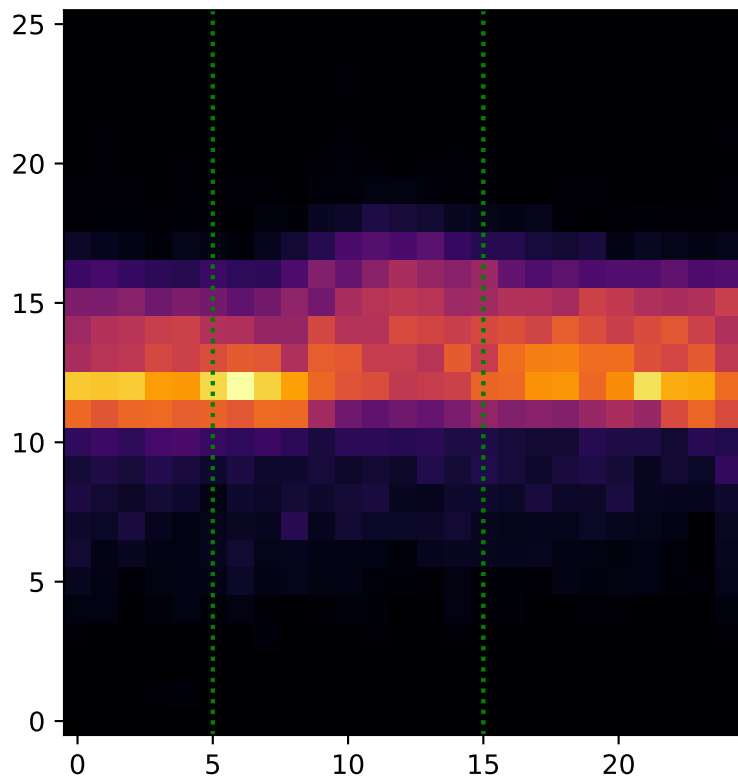


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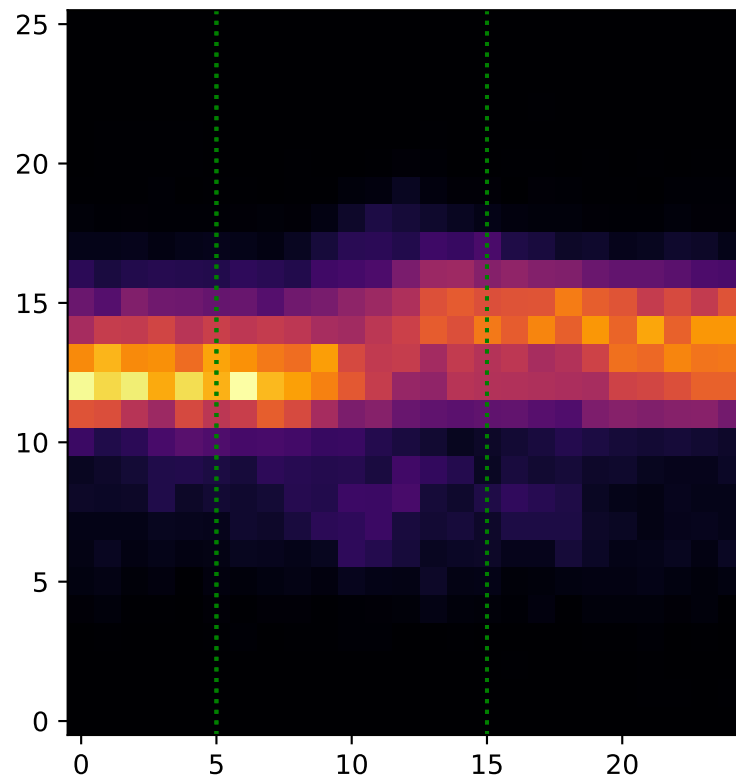


speed_neck | pval:0.6691891891891892

ctr

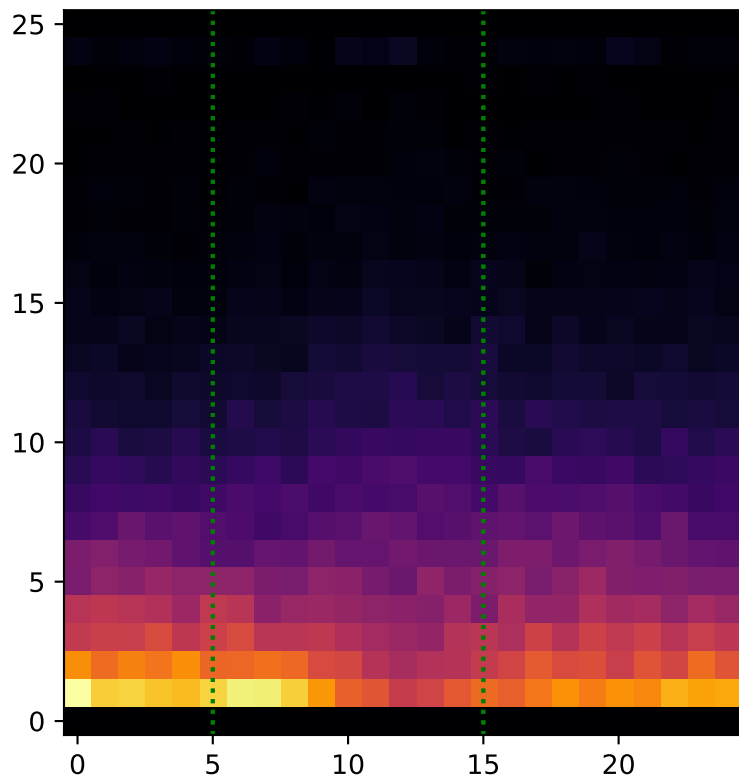


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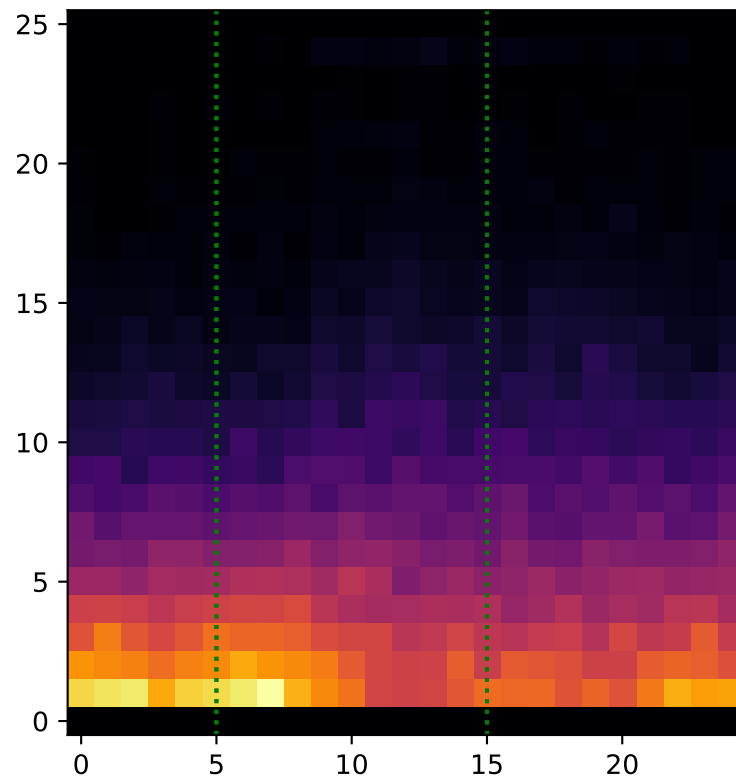


d_relative_to_tail_base_angular_velocity_tail_tip | pval:0.6821621621621622

ctr

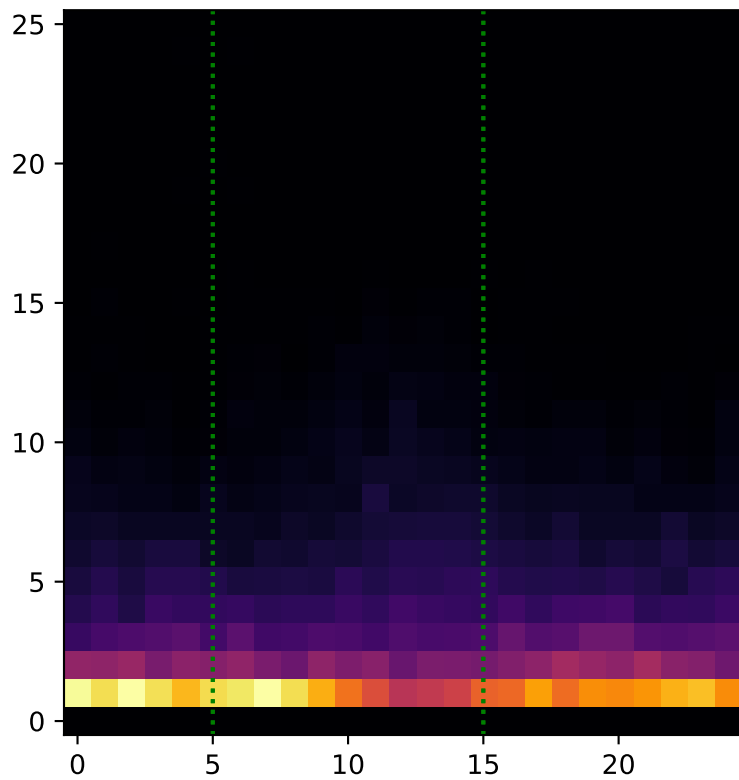


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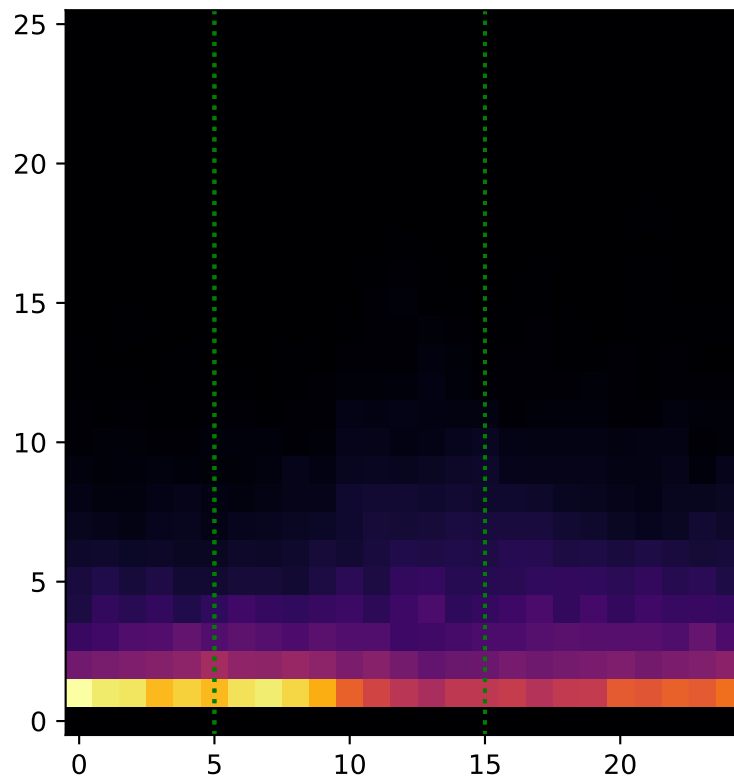


relative_to_body_angular_velocity_hips | pval:0.6843243243243243

ctr

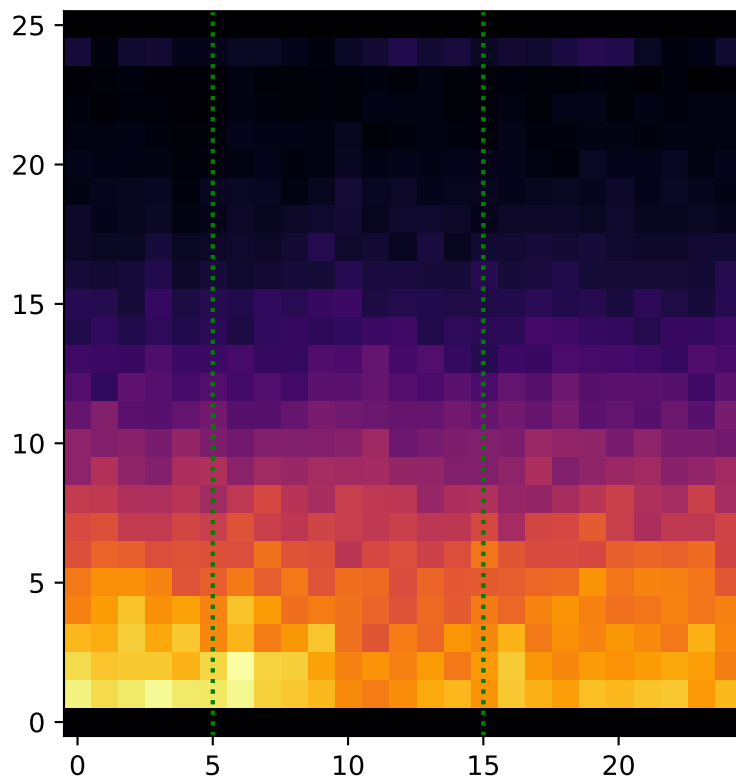


atr

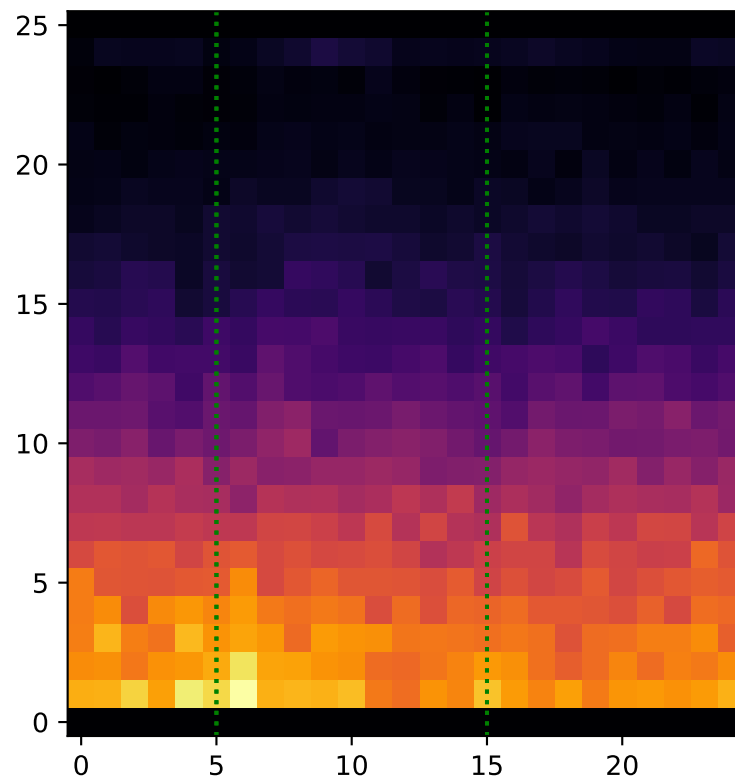


d_eigen_projection_6 | pval:0.692972972972973

ctr

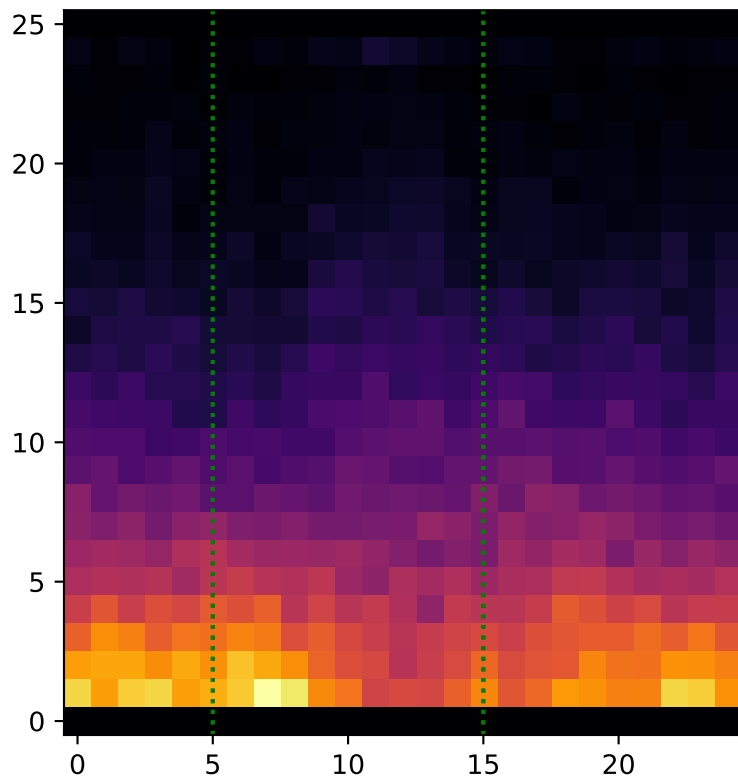


atr

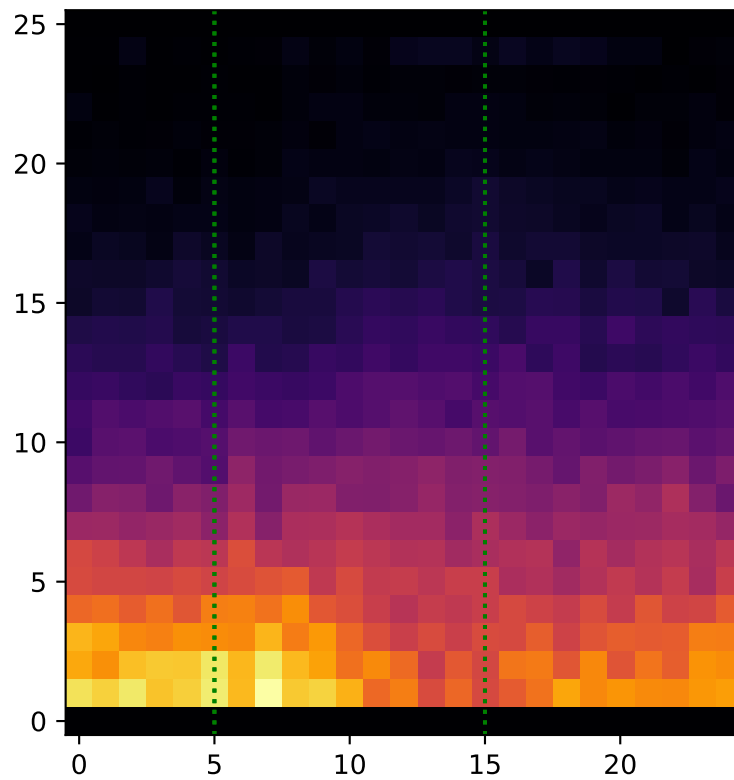


d_curvature_std_neck | pval:0.692972972972973

ctr

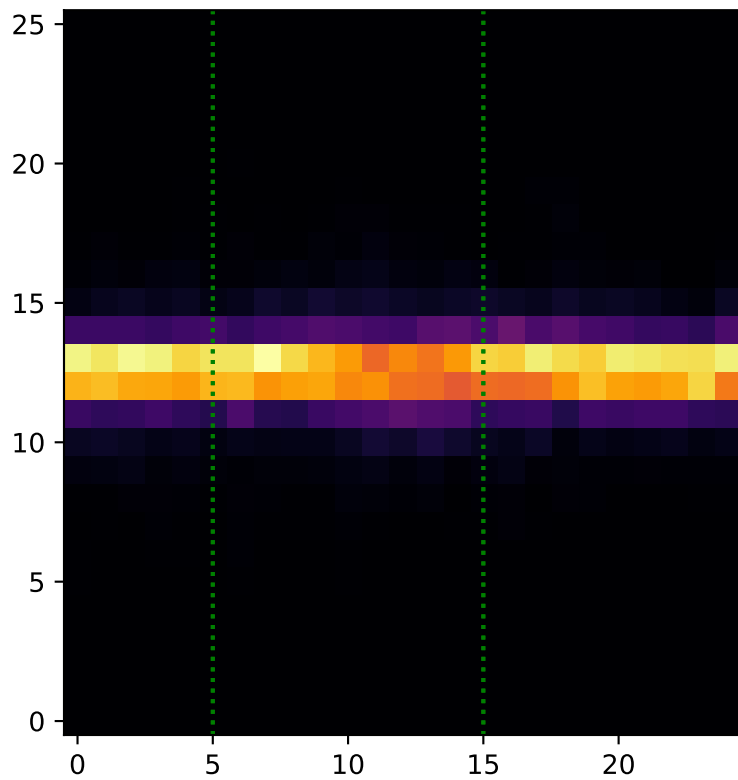


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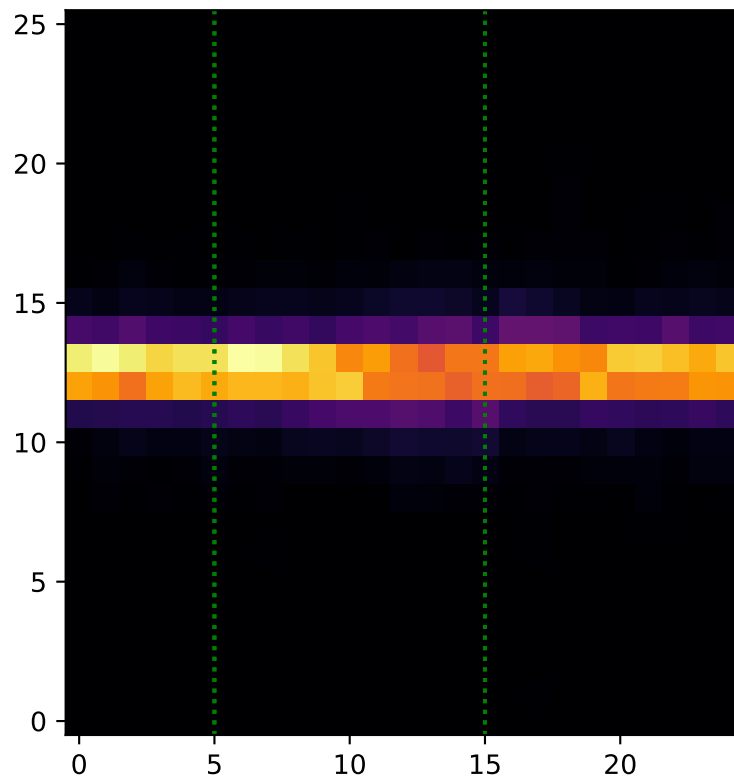


relative_to_body_radial_velocity_hips | pval:0.6972972972972973

ctr

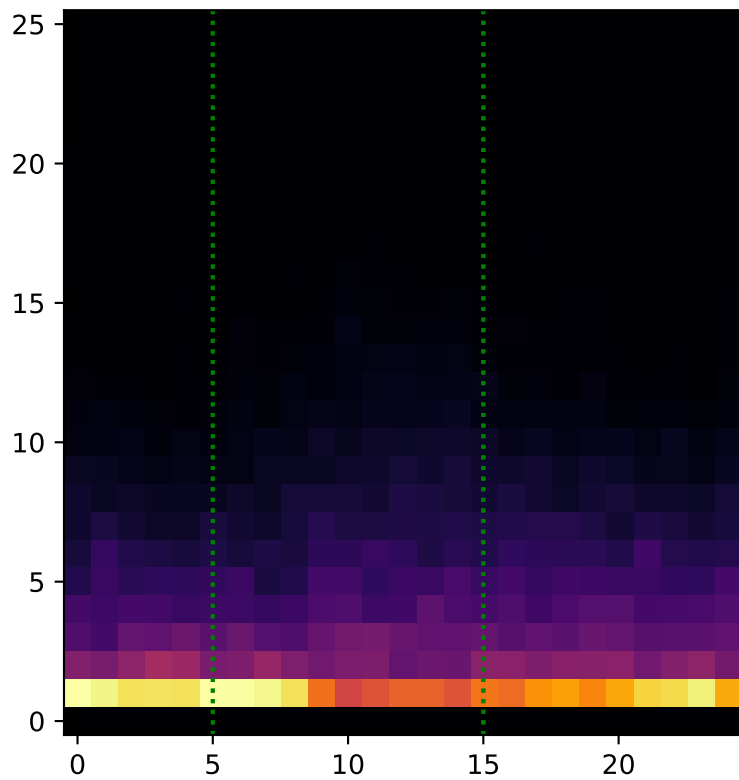


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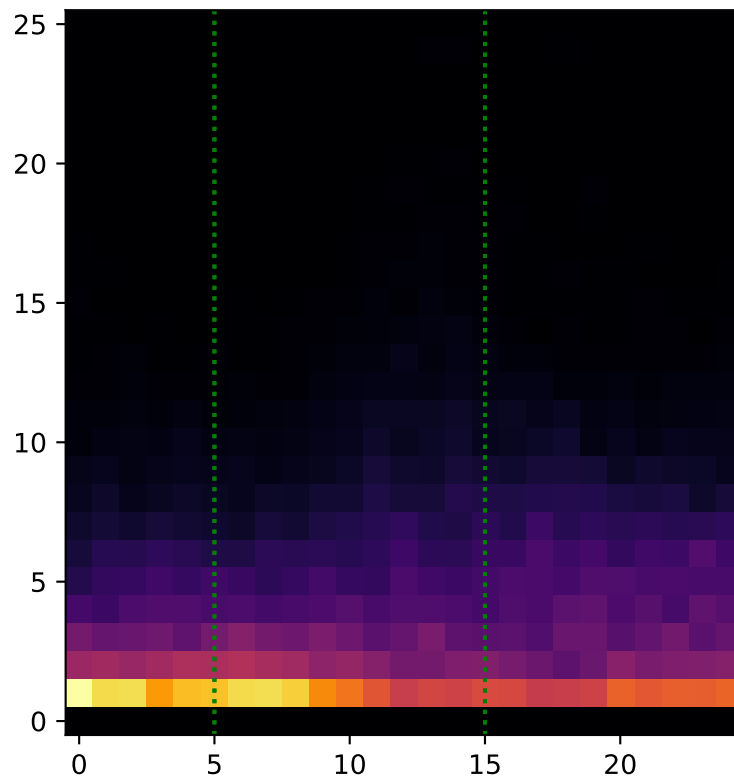


angular_velocity_hips | pval:0.6994594594594594

ctr

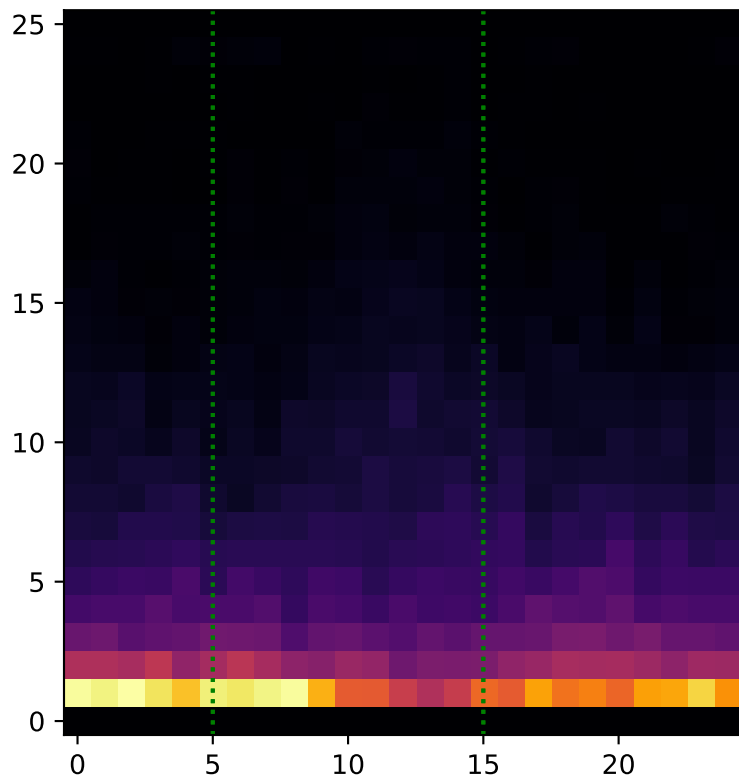


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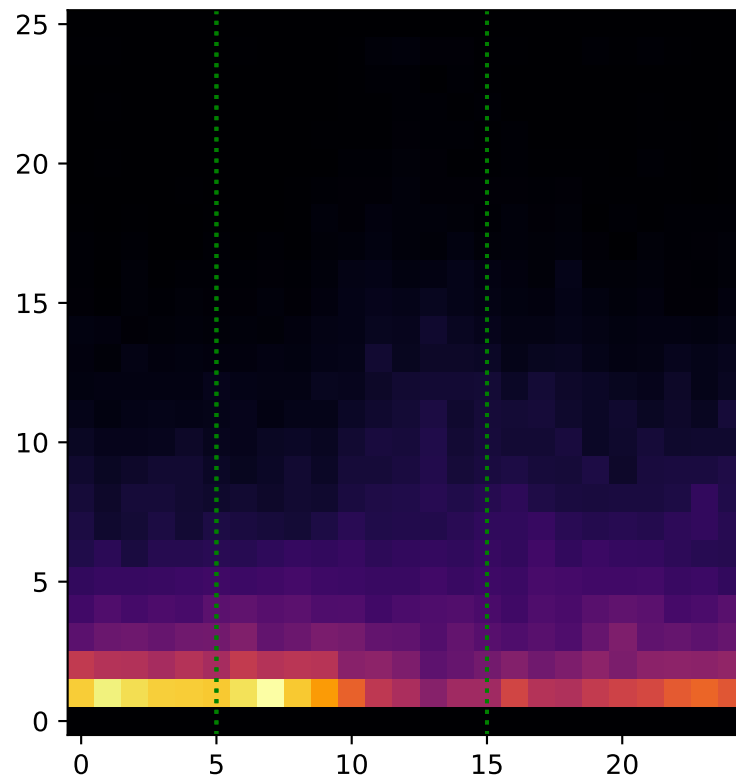


d_curvature_mean_midbody | pval:0.7016216216216217

ctr

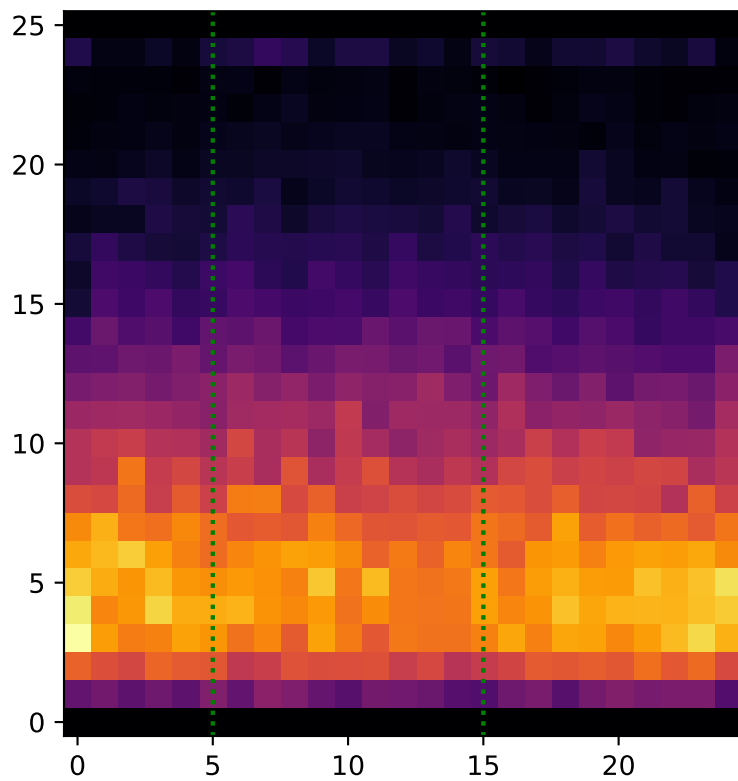


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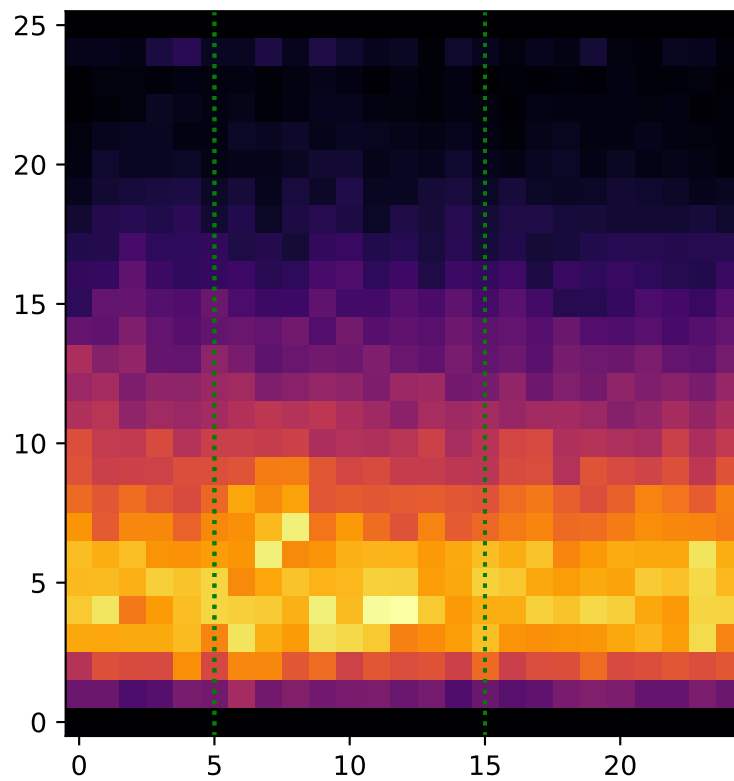


curvature_std_head | pval:0.7037837837837838

ctr

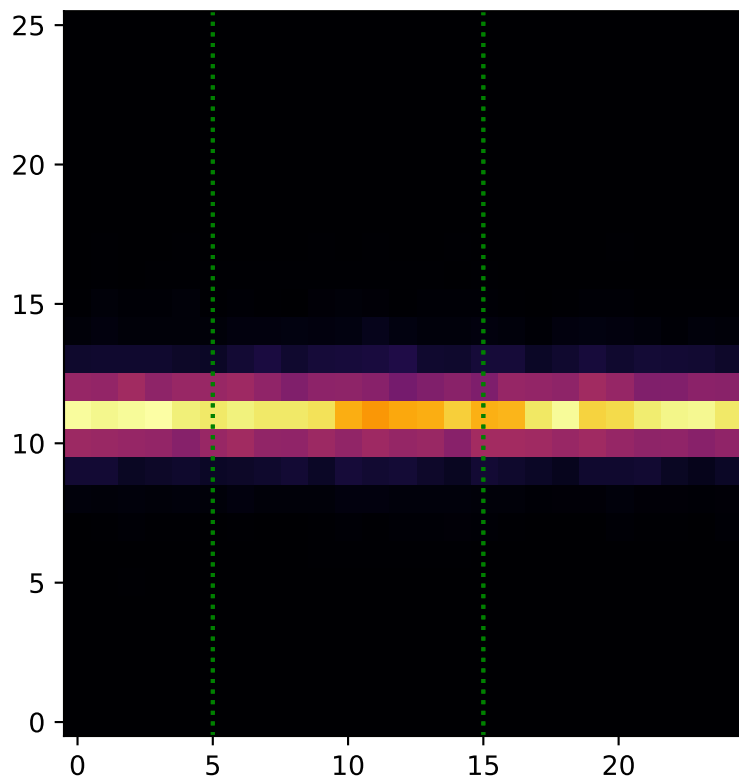


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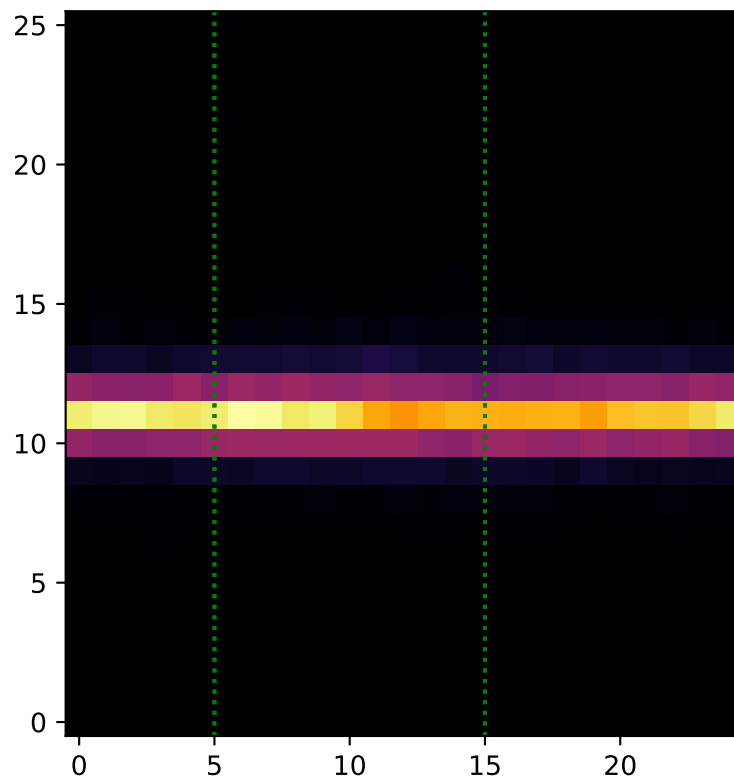


d_relative_to_tail_base_radial_velocity_tail_tip | pval:0.7081081081081081

ctr

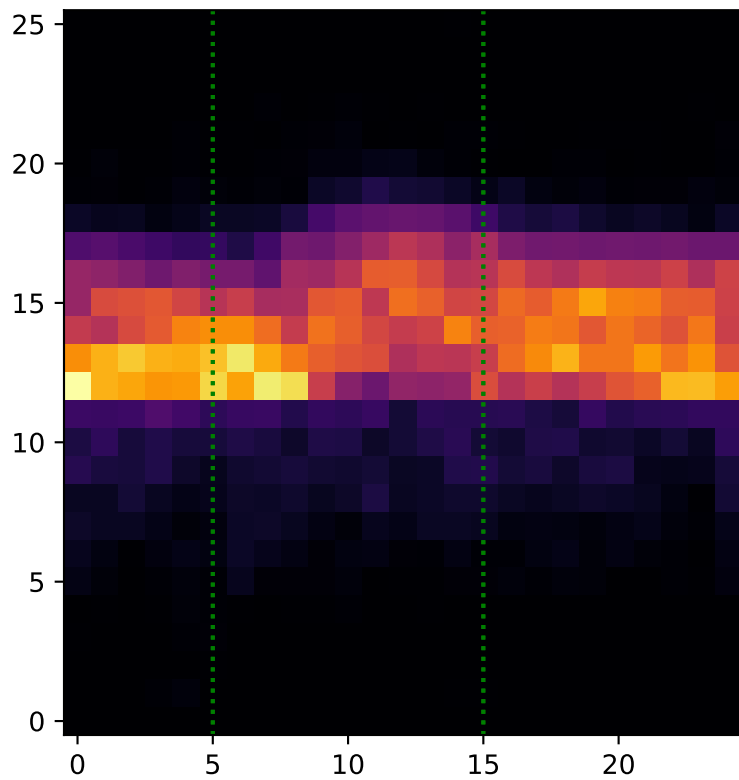


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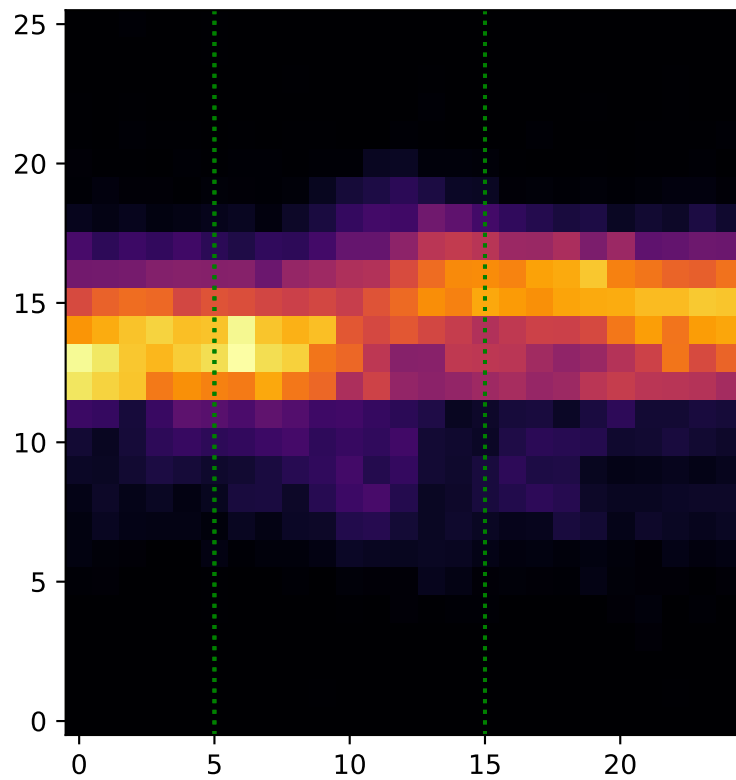


speed_tail_tip | pval:0.7124324324324325

ctr

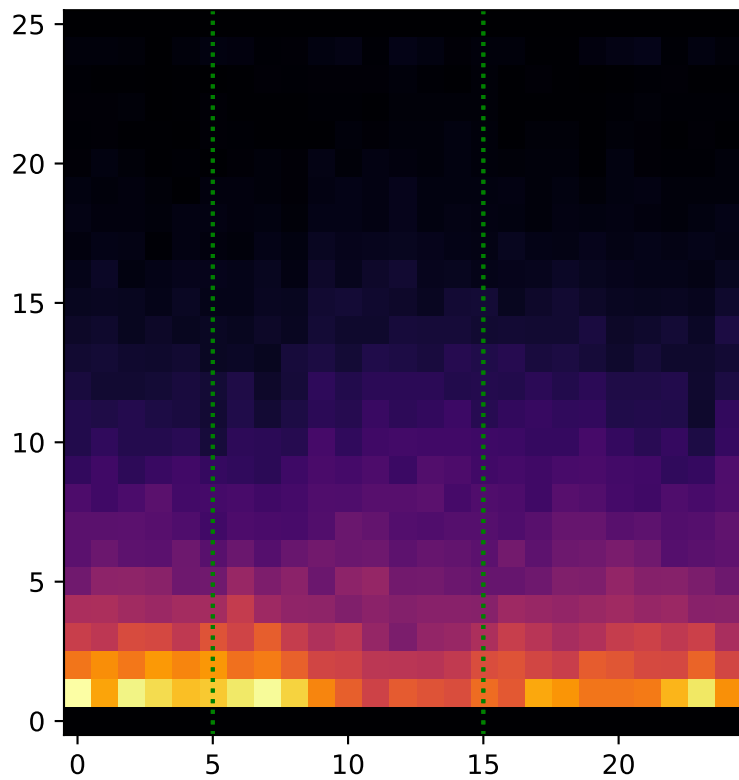


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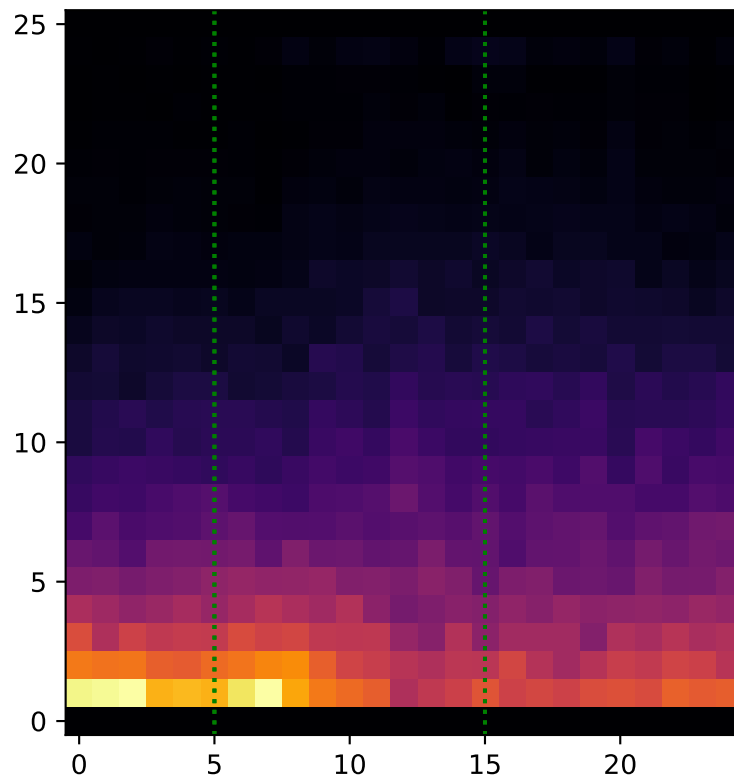


d_curvature_std_hips | pval:0.7167567567567568

ctr

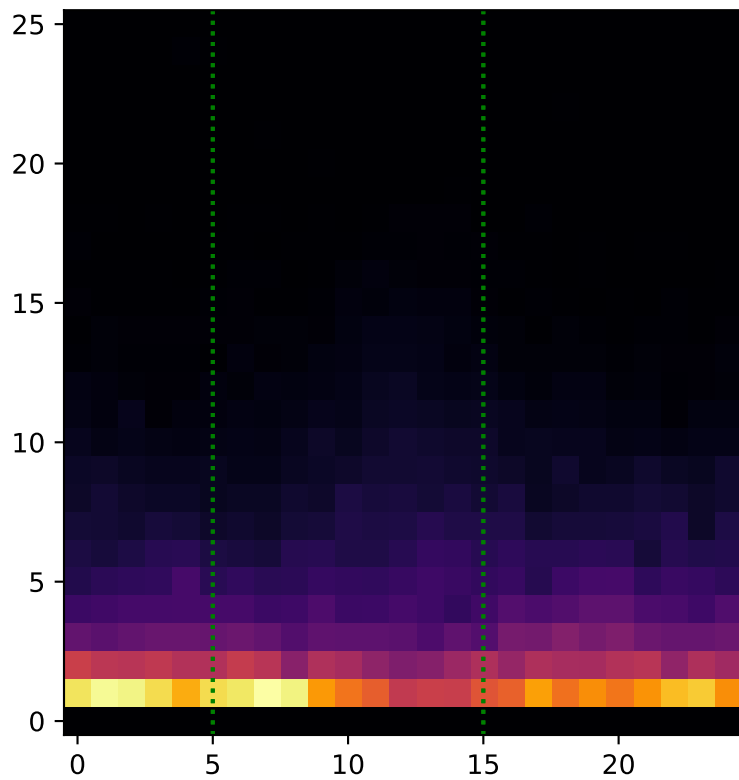


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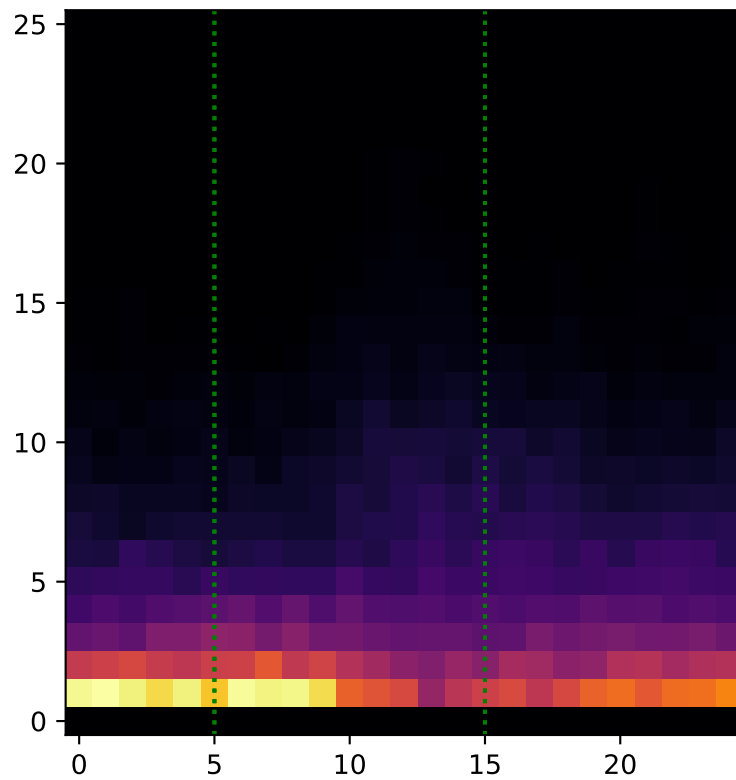


d_eigen_projection_3 | pval:0.7297297297297297

ctr

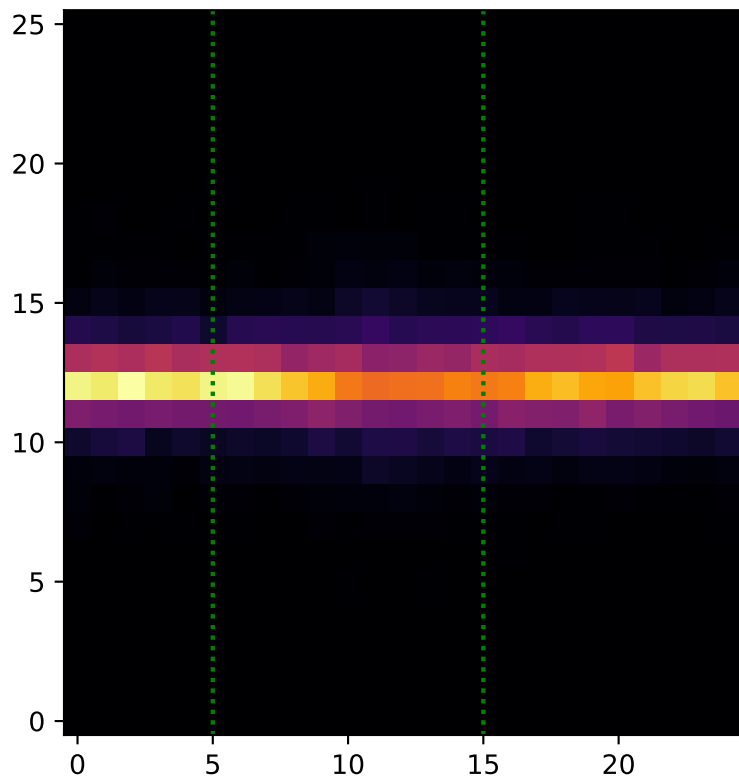


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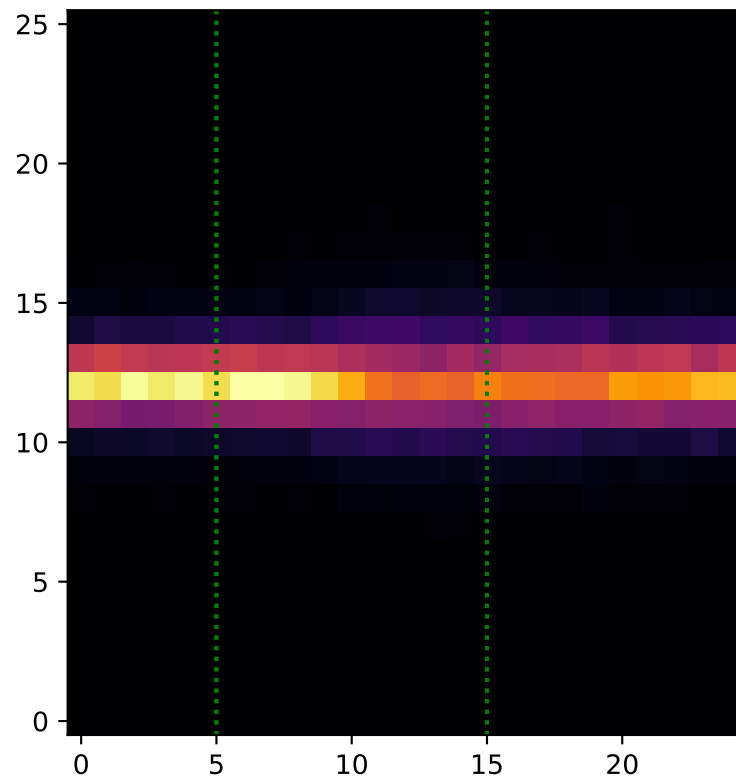


d_relative_to_hips_radial_velocity_tail_tip | pval:0.7340540540540541

ctr

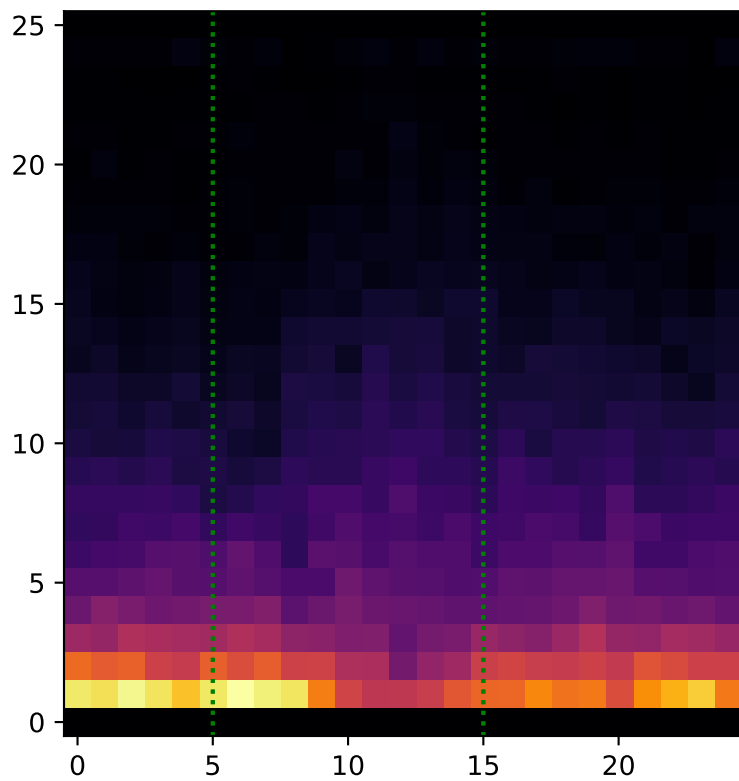


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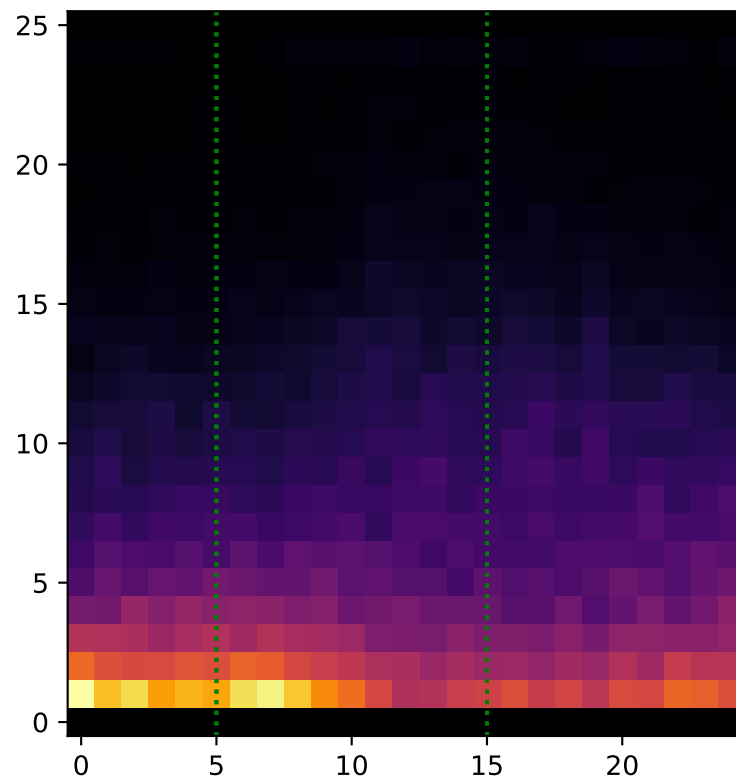


d_curvature_hips | pval:0.7340540540540541

ctr

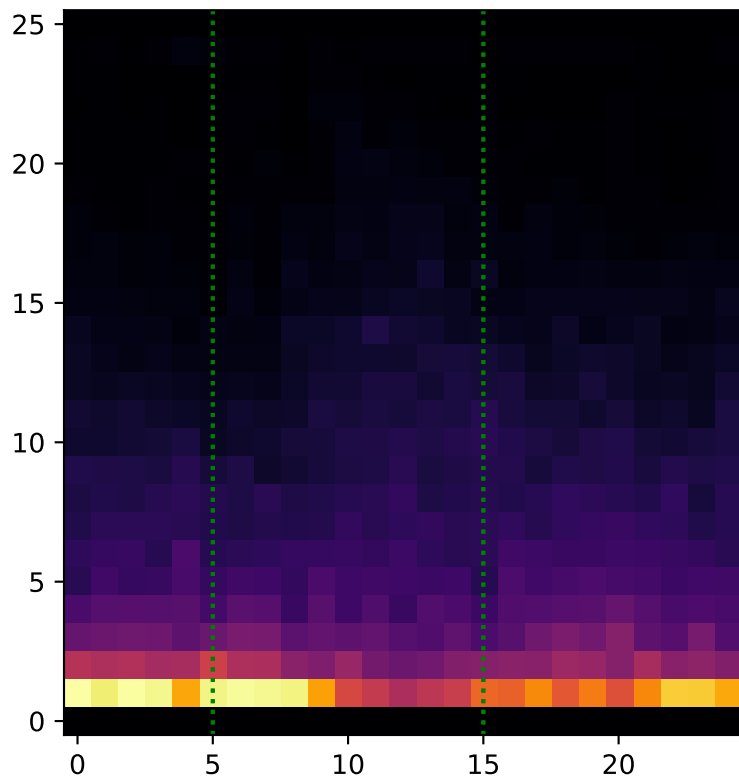


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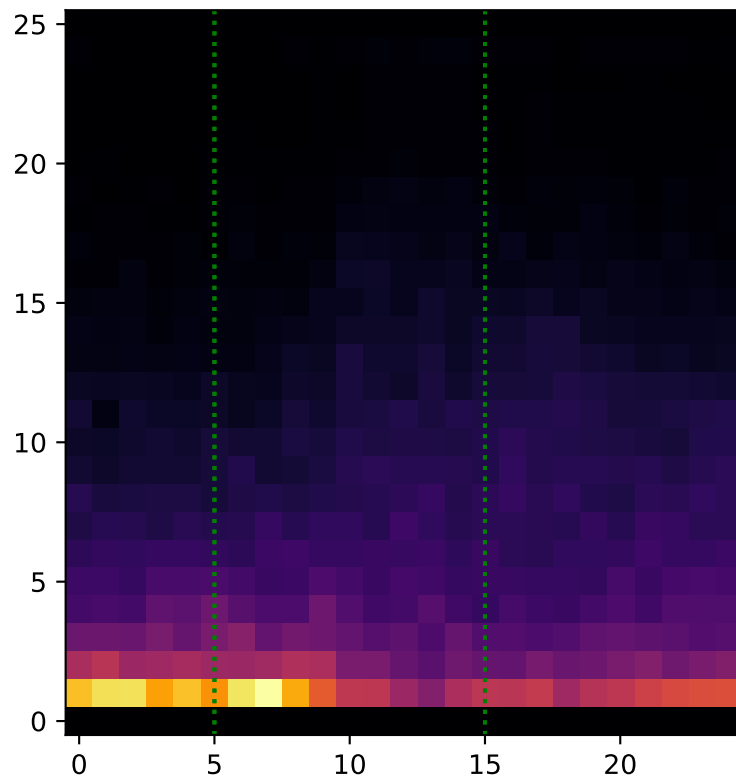


d_curvature_mean_hips | pval:0.7340540540540541

ctr

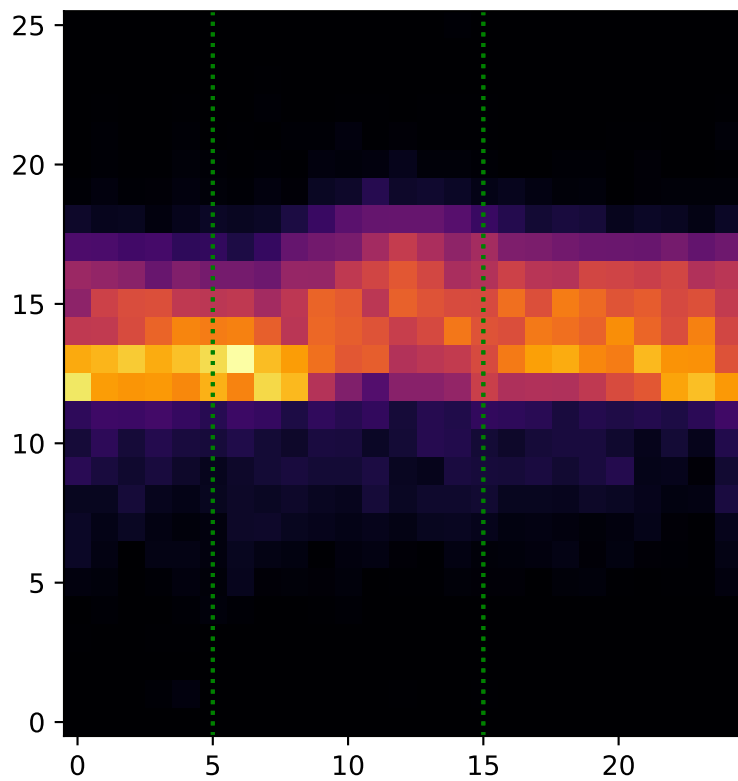


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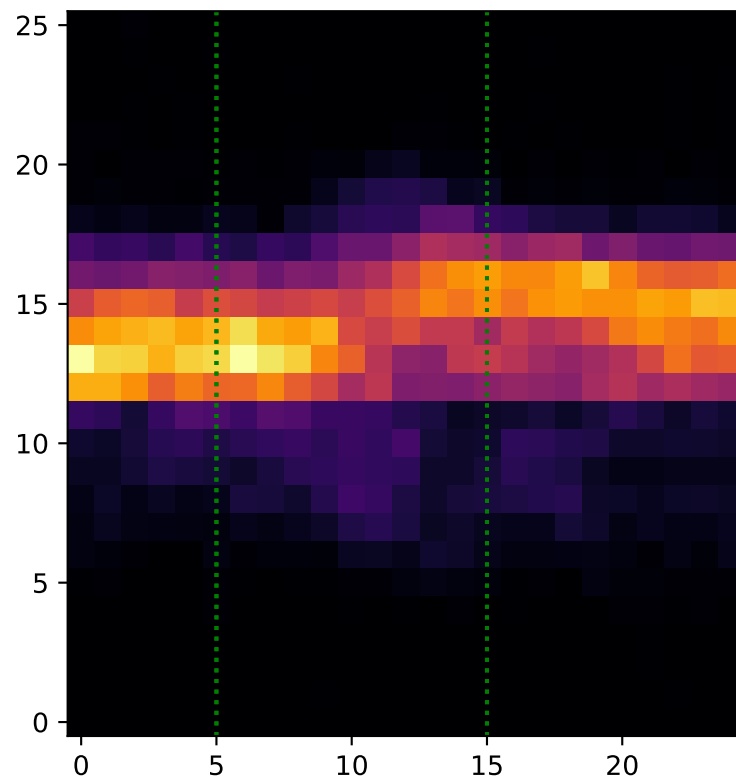


speed_tail_base | pval:0.7383783783783784

ctr

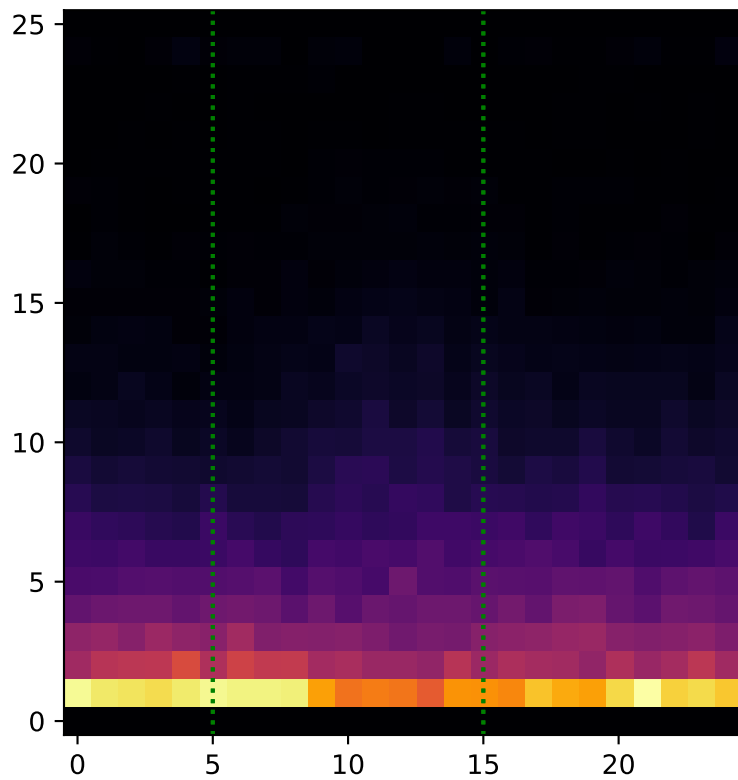


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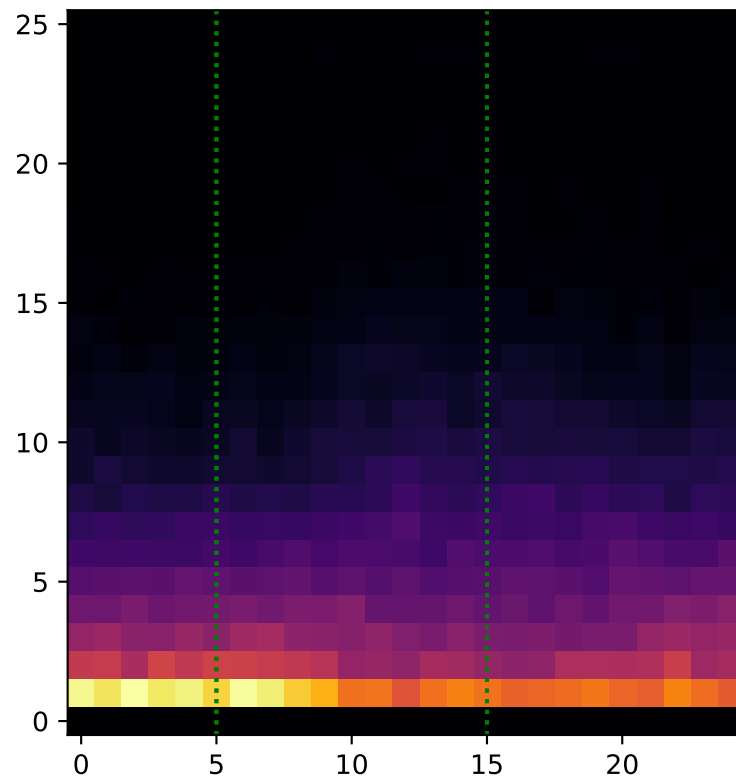


angular_velocity_tail_tip | pval:0.7448648648648649

ctr

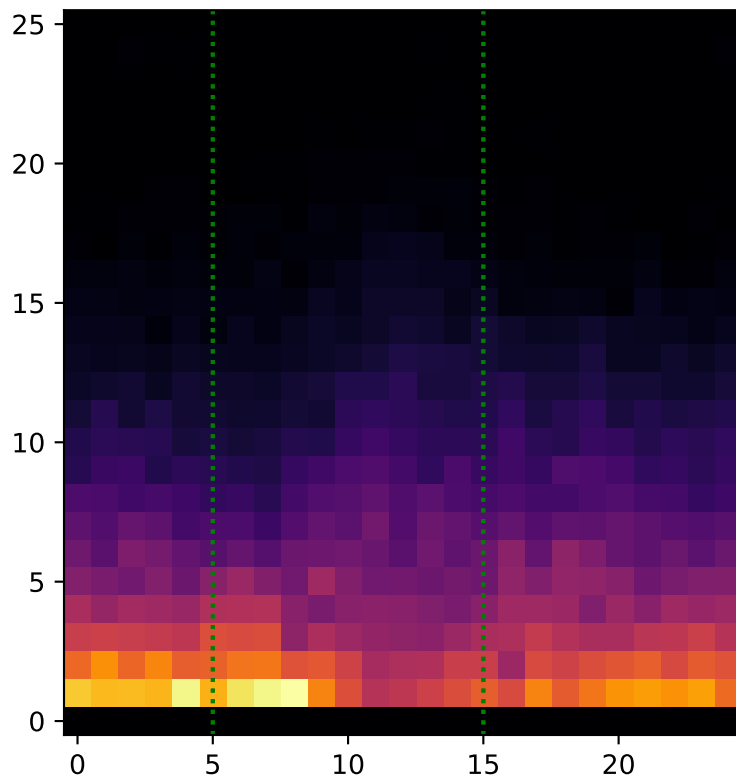


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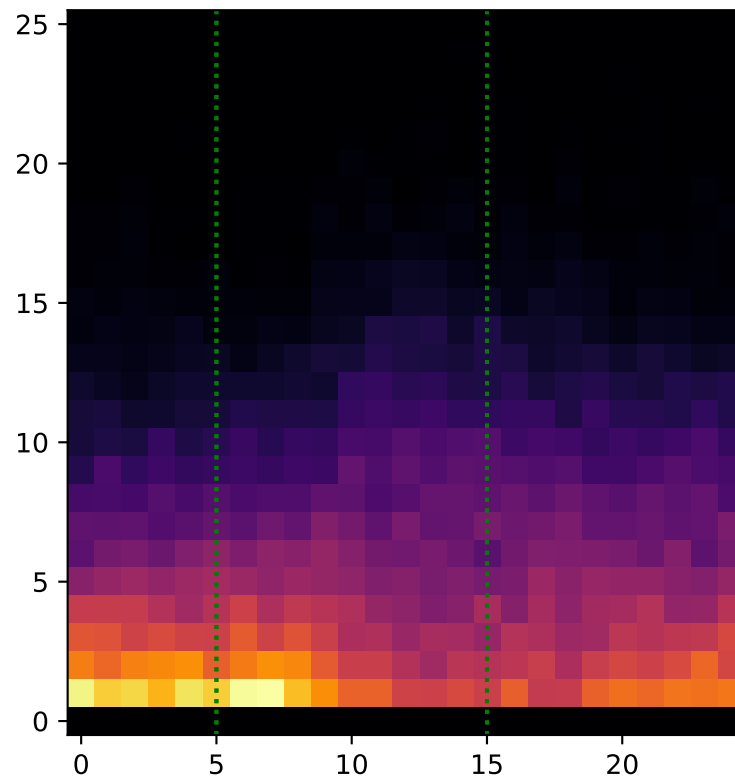


relative_to_neck_angular_velocity_head_tip | pval:0.7470270270270271

ctr

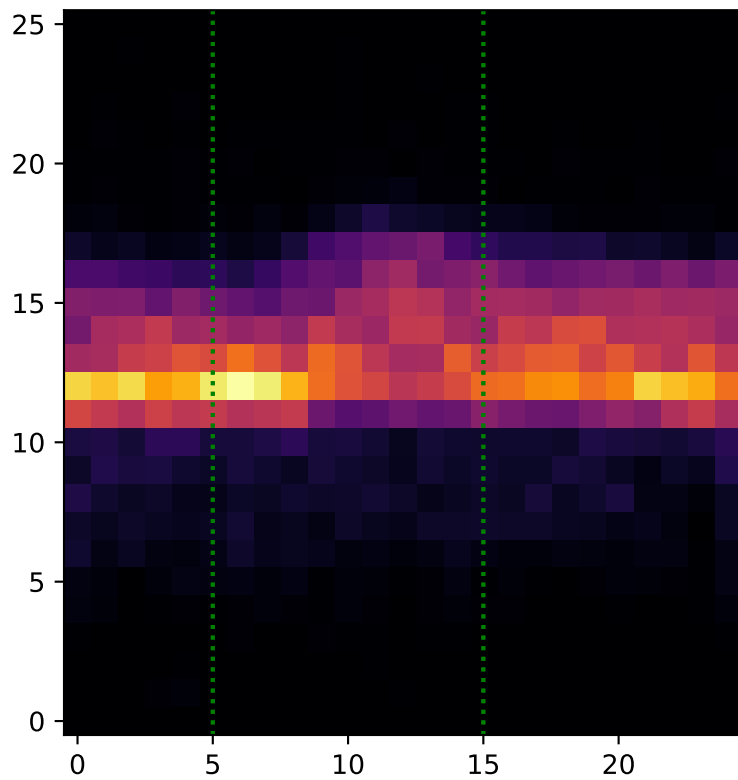


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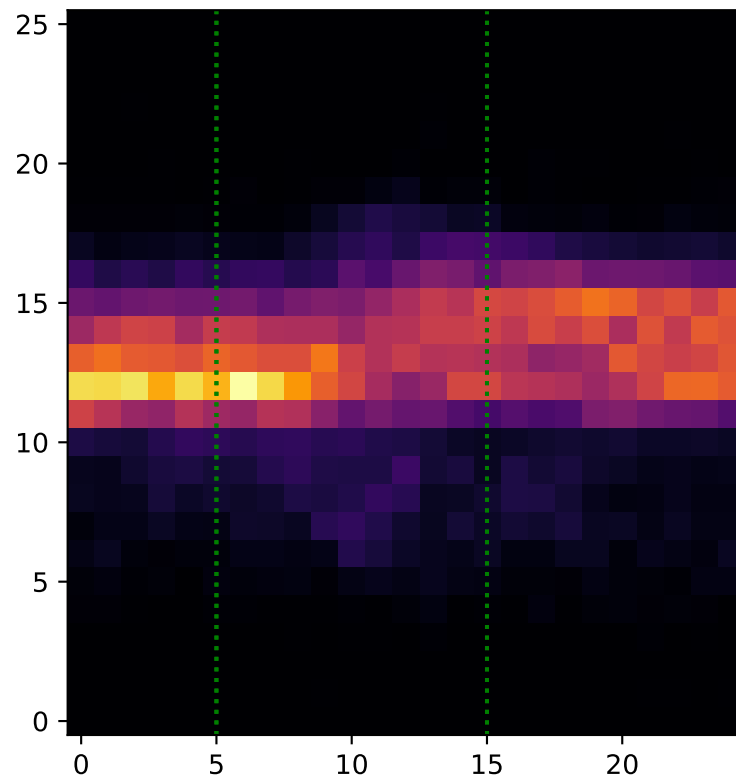


speed | pval:0.7578378378378379

ctr

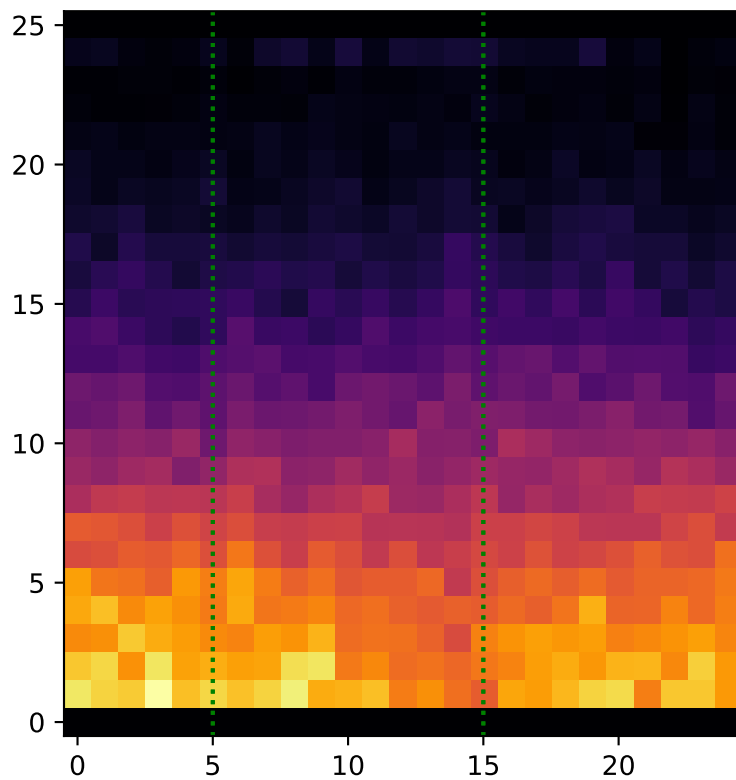


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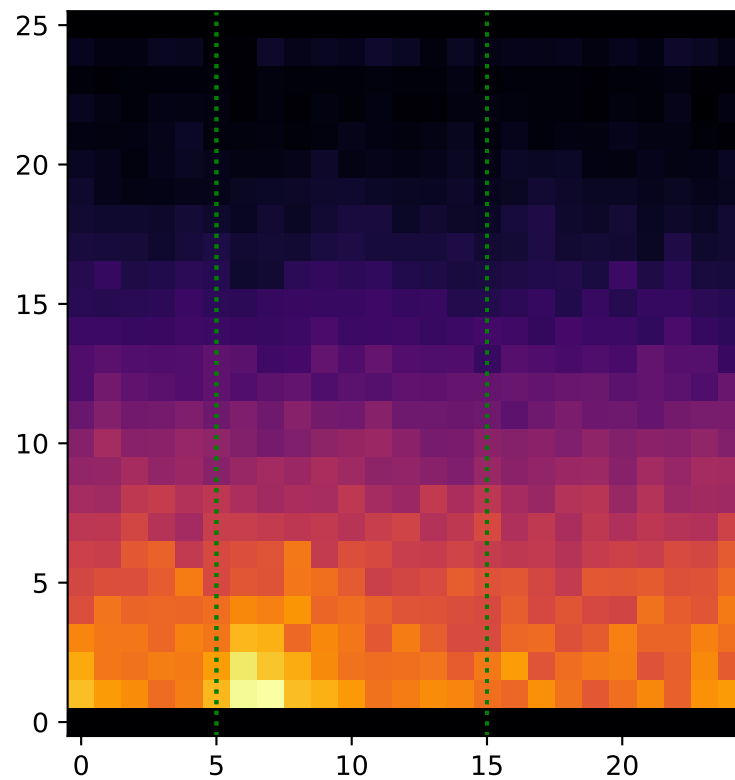


d_relative_to_head_base_angular_velocity_head_tip | pval:0.7621621621621621

ctr

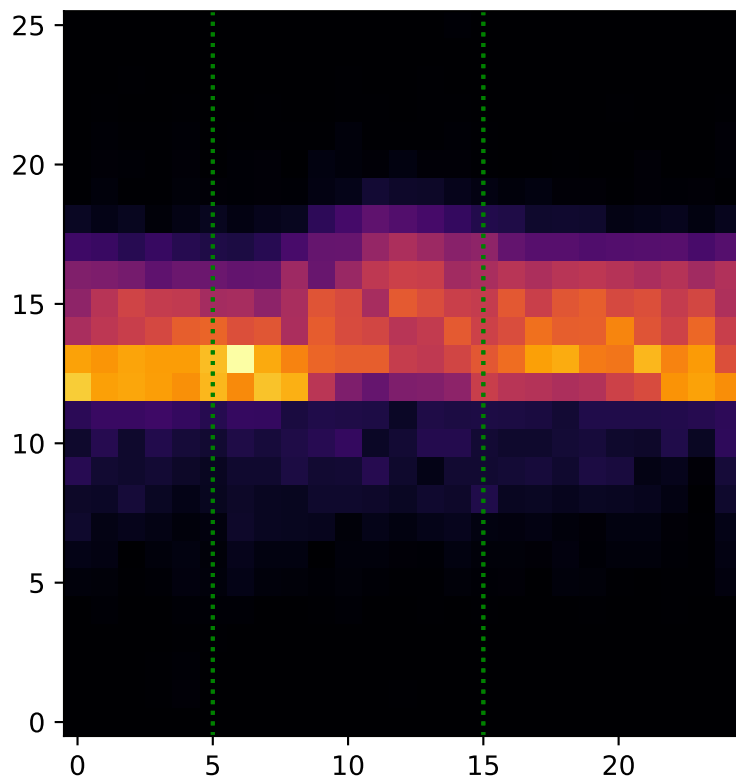


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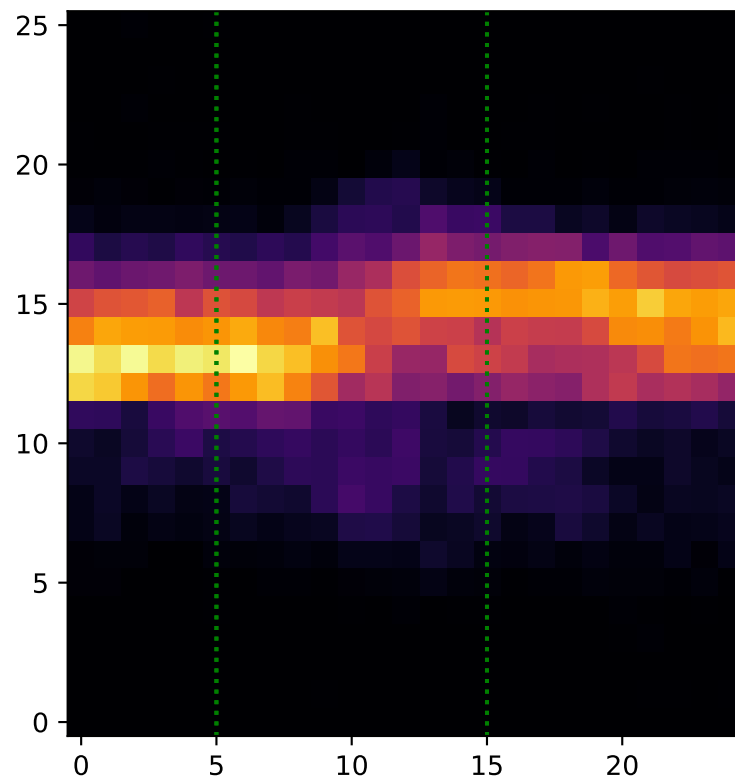


speed_hips | pval:0.7708108108108108

ctr

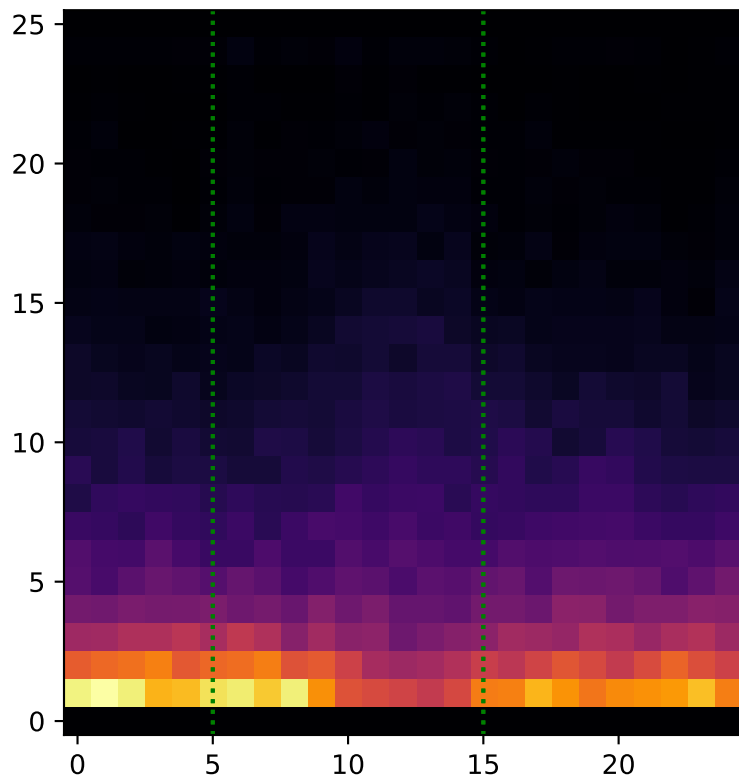


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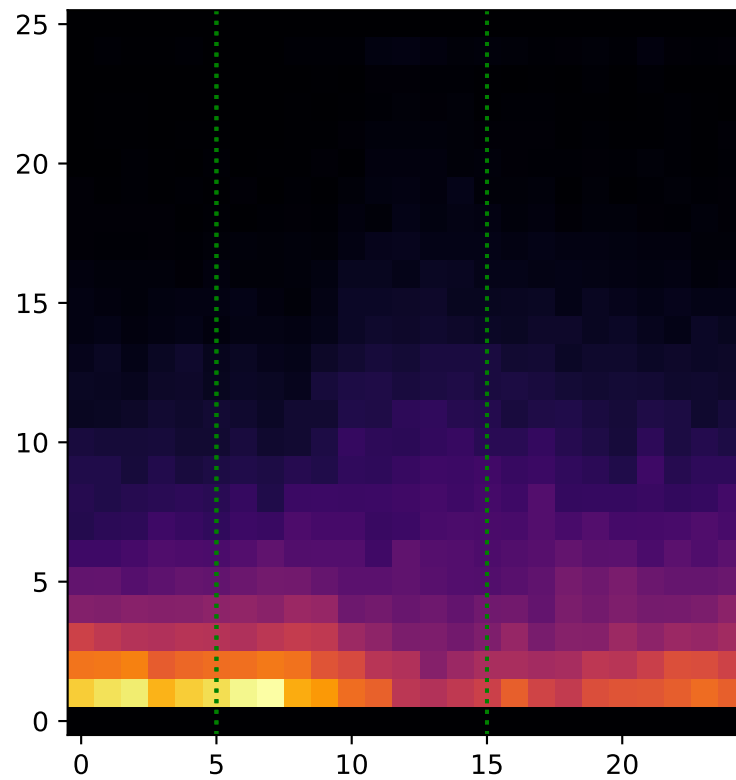


d_curvature_std_midbody | pval:0.7708108108108108

ctr

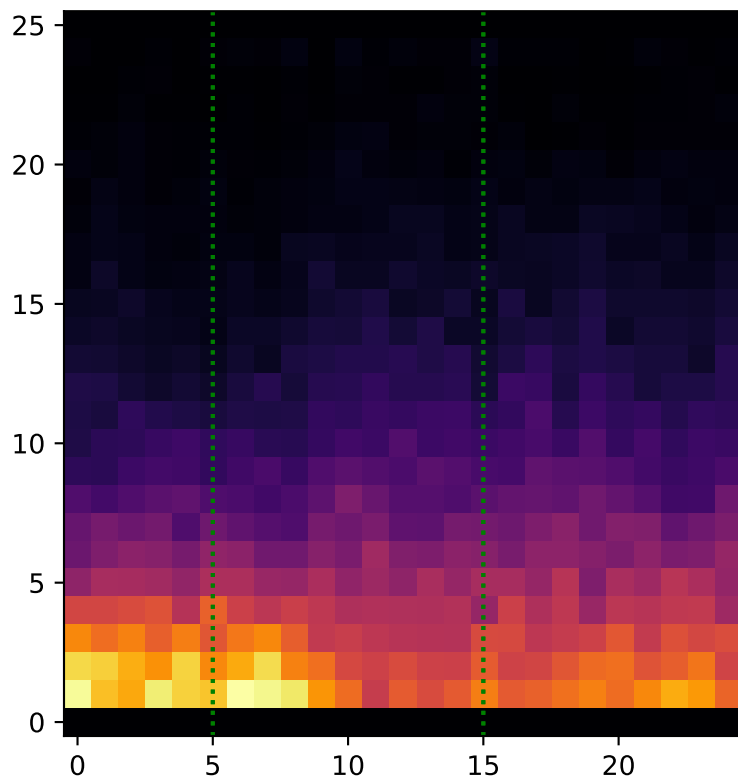


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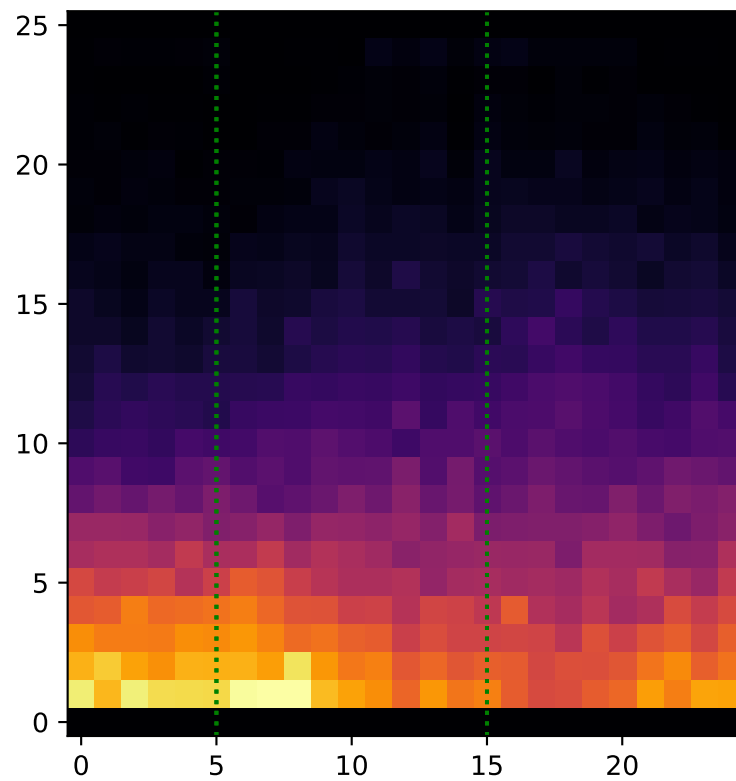


d_eigen_projection_4 | pval:0.772972972973

ctr

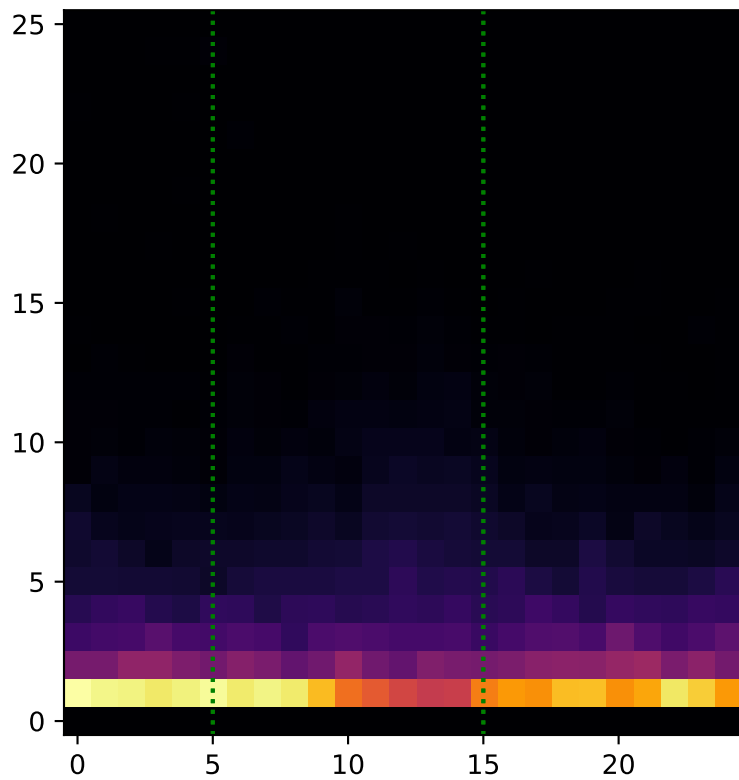


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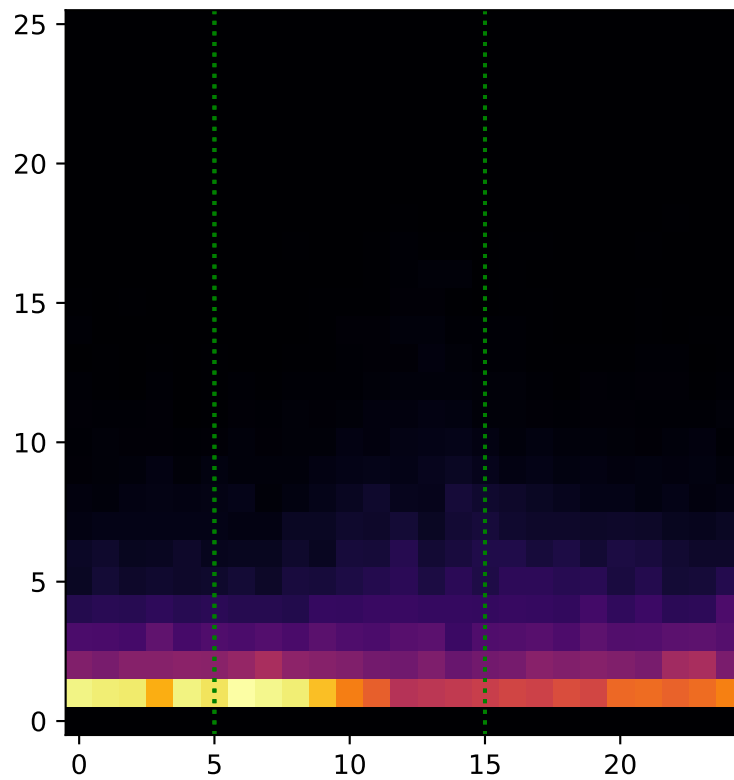


d_eigen_projection_2 | pval:0.7772972972972974

ctr

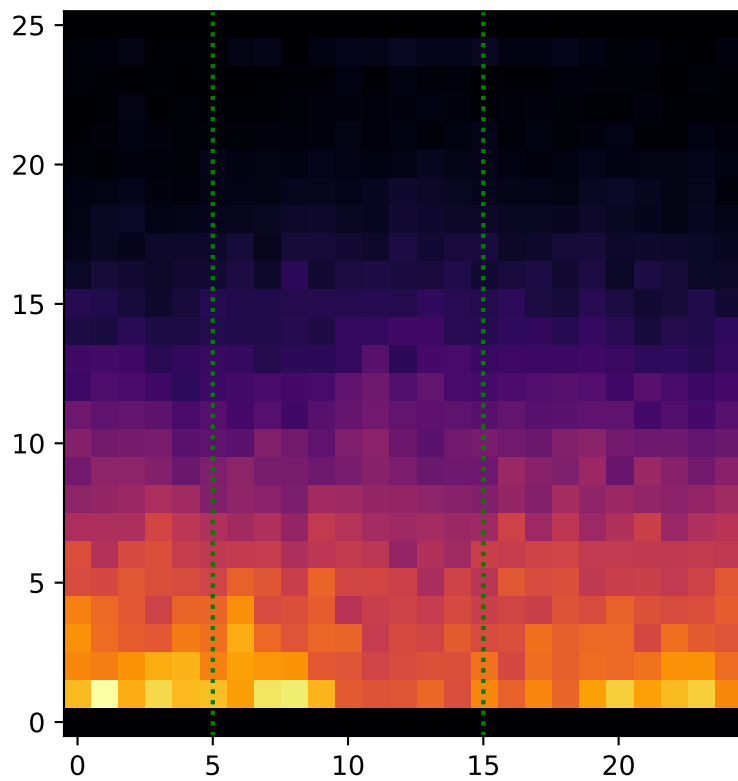


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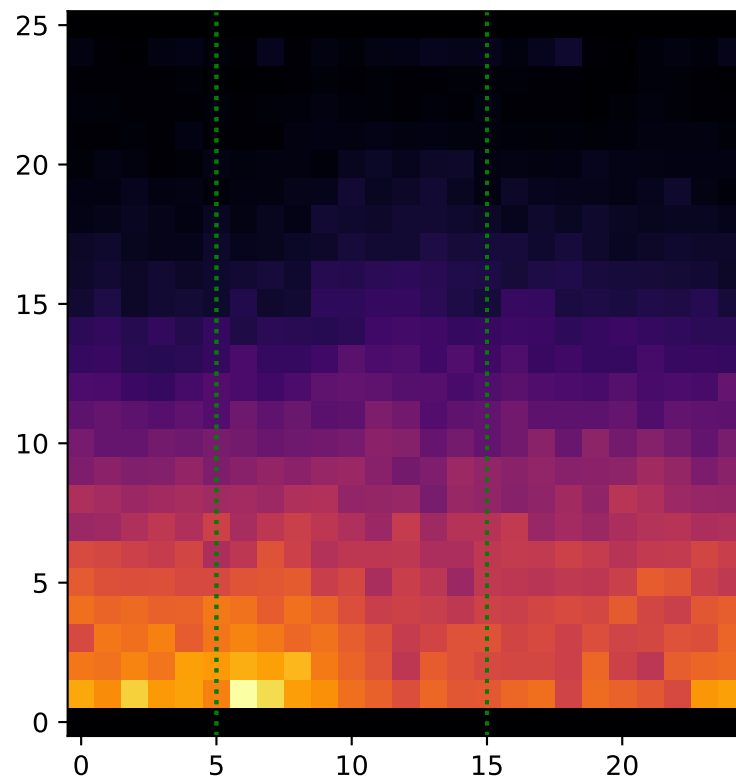


d_curvature_head | pval:0.7881081081081082

ctr

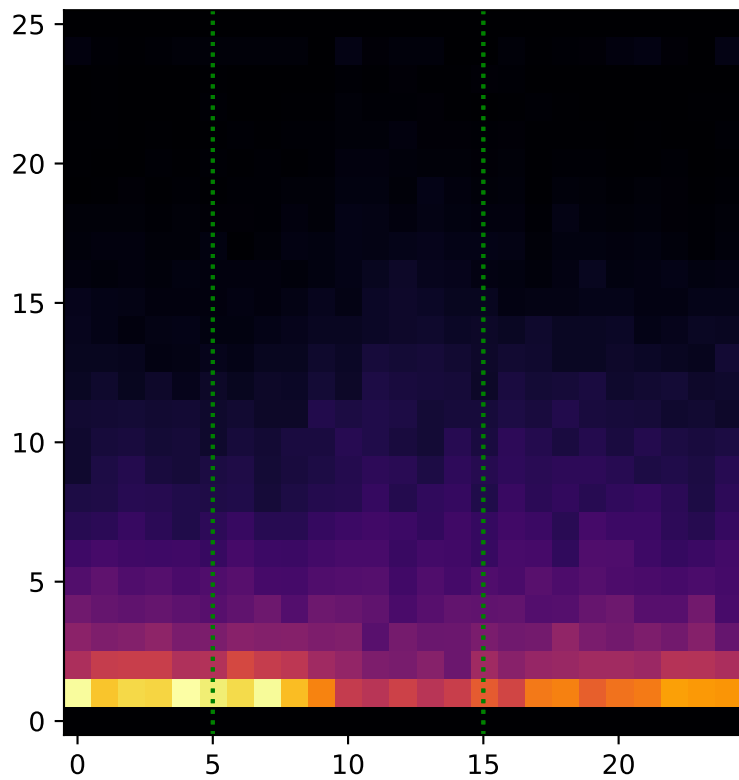


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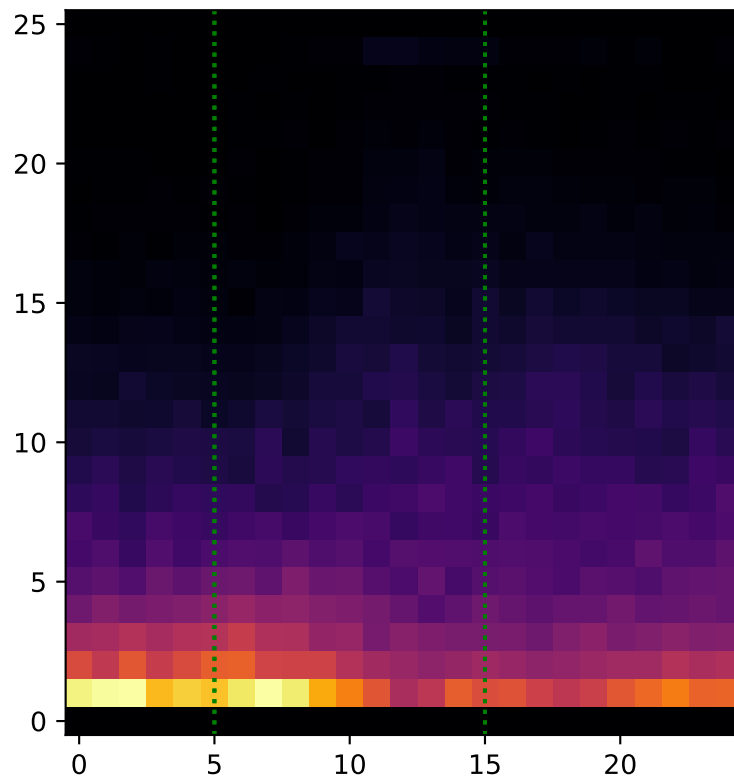


d_curvature_mean_tail | pval:0.7881081081081082

ctr

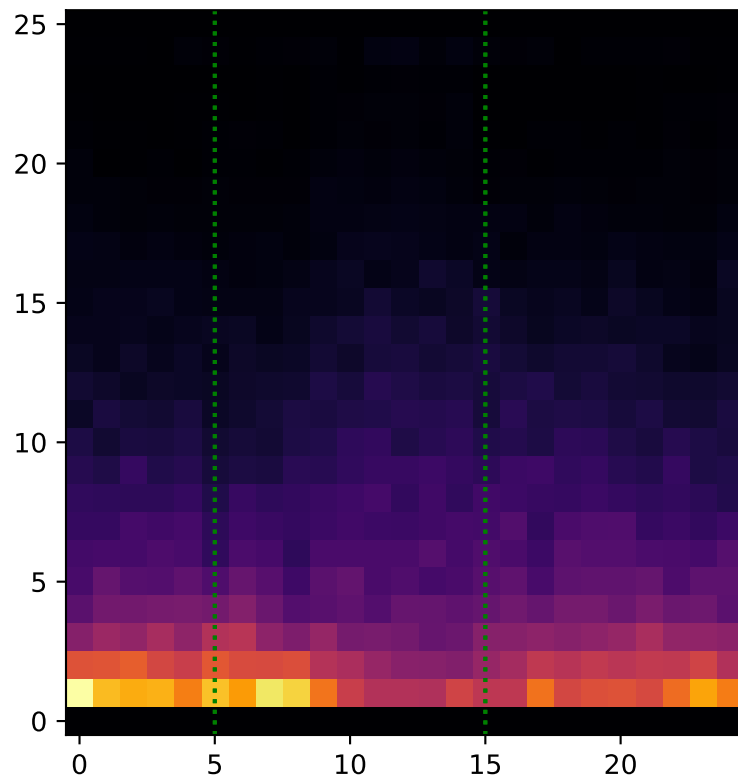


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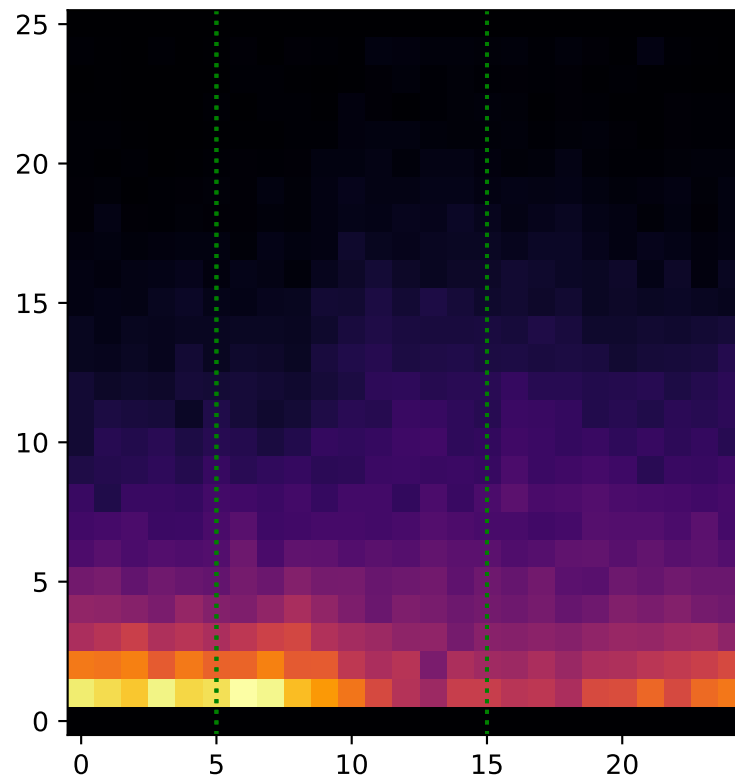


d_curvature_midbody | pval:0.7924324324324324

ctr

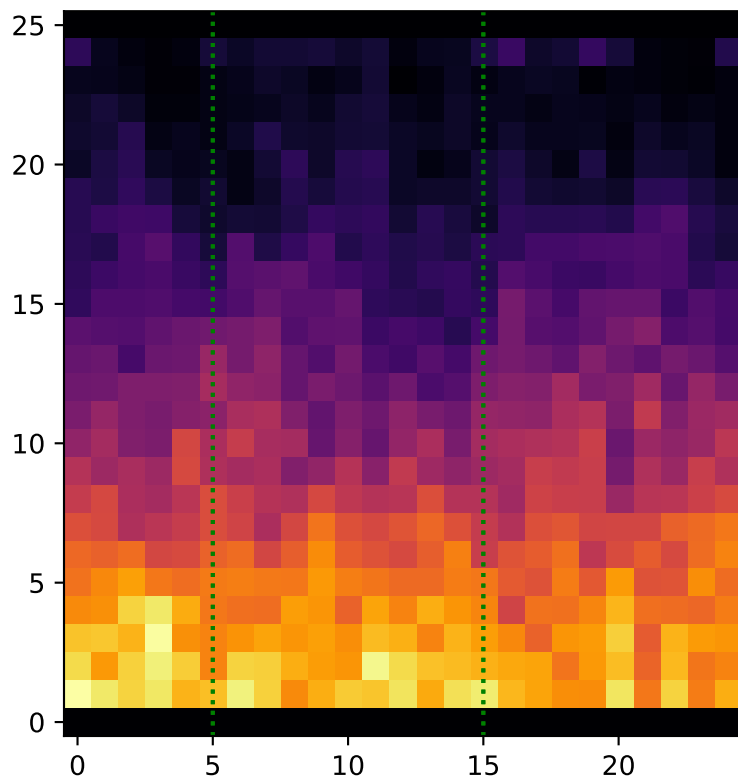


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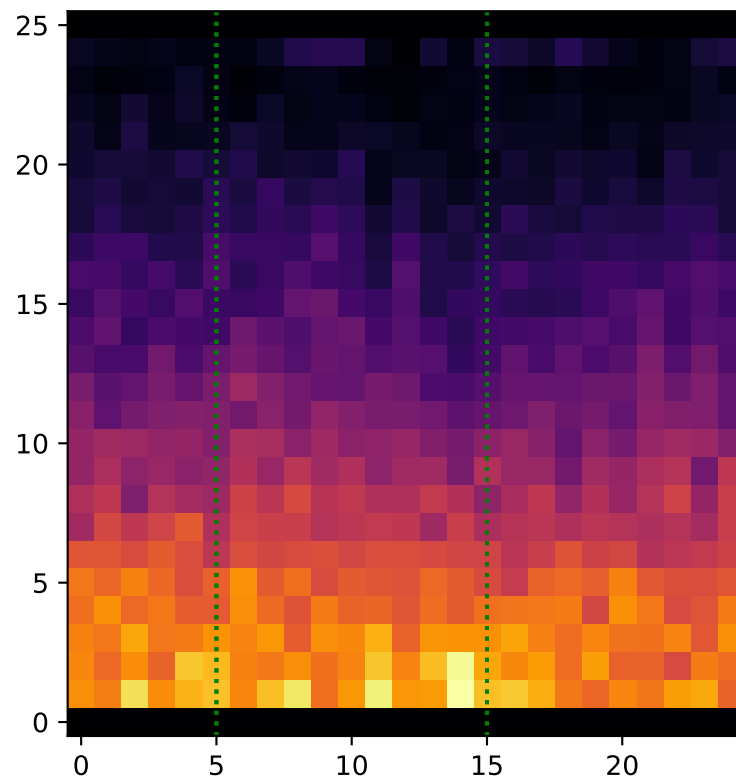


eigen_projection_5 | pval:0.7967567567567567

ctr

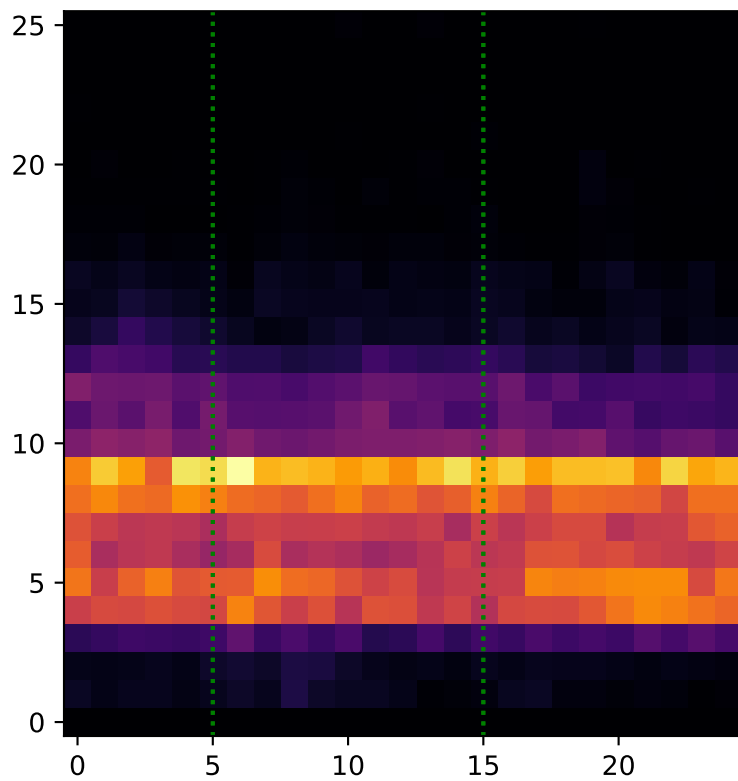


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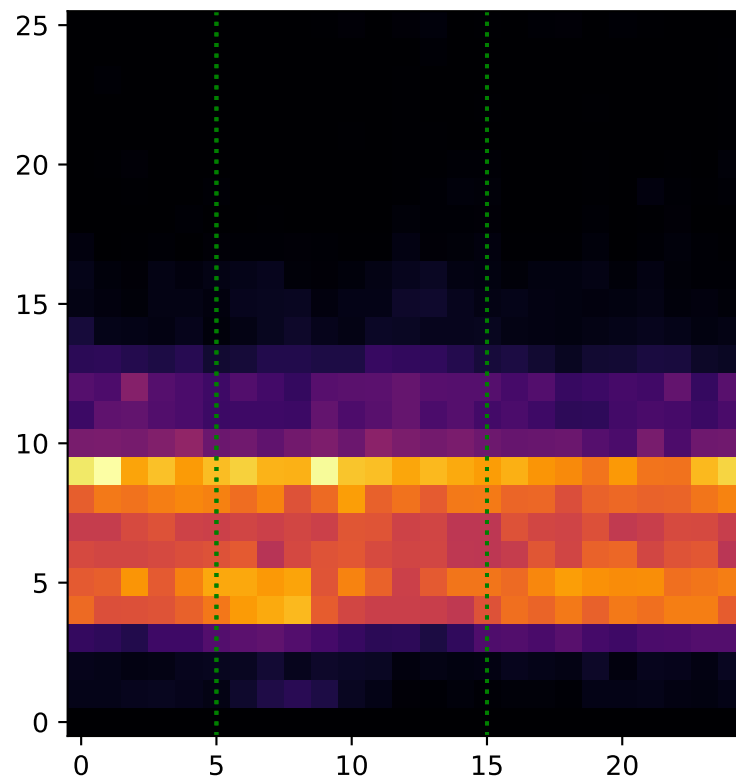


width_head_base | pval:0.798918918918919

ctr

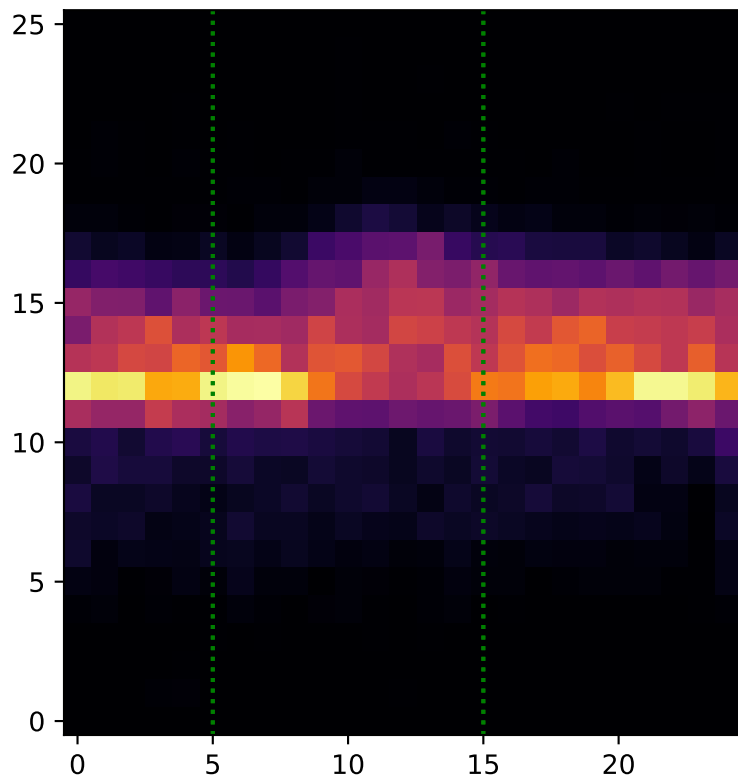


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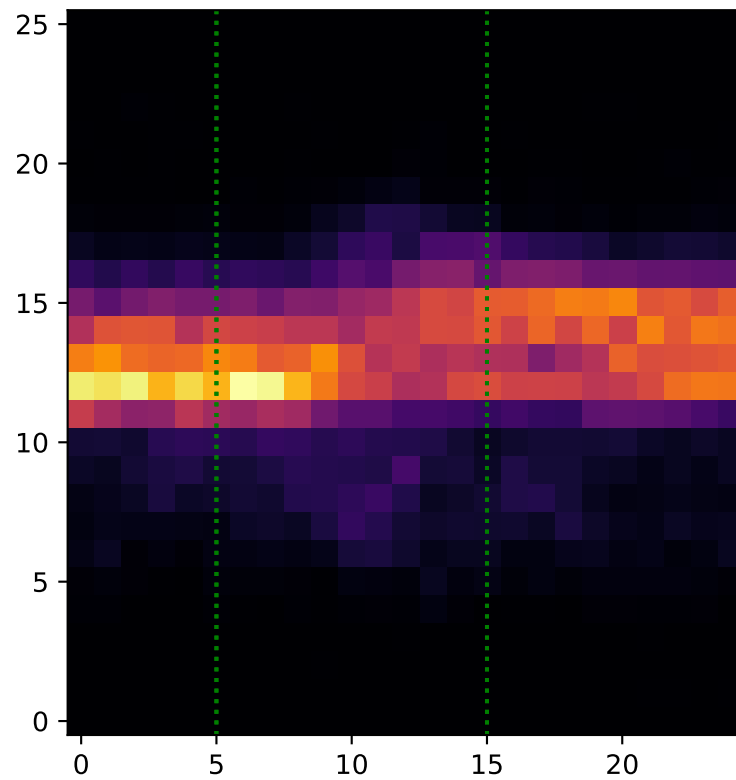


speed_midbody | pval:0.8054054054054054

ctr

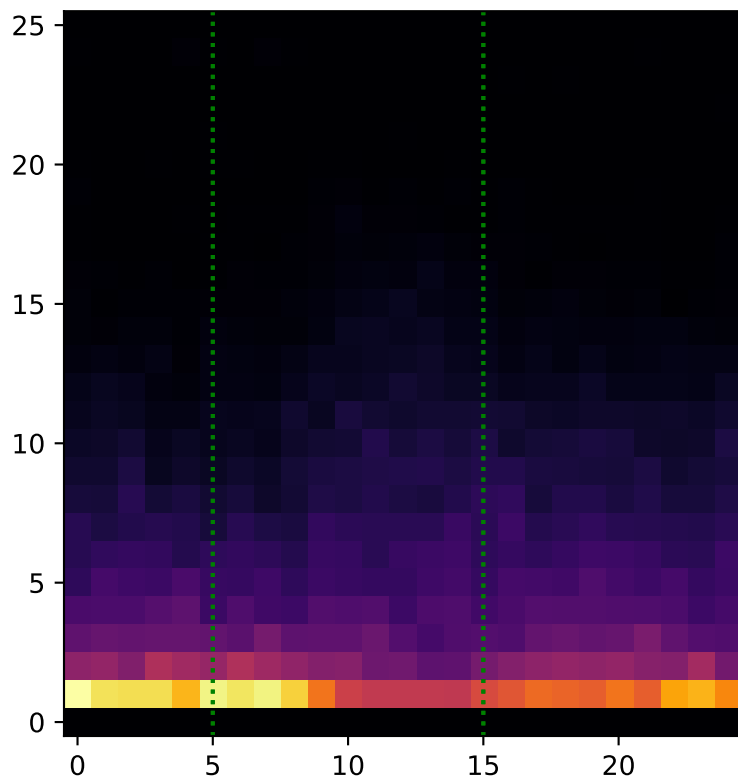


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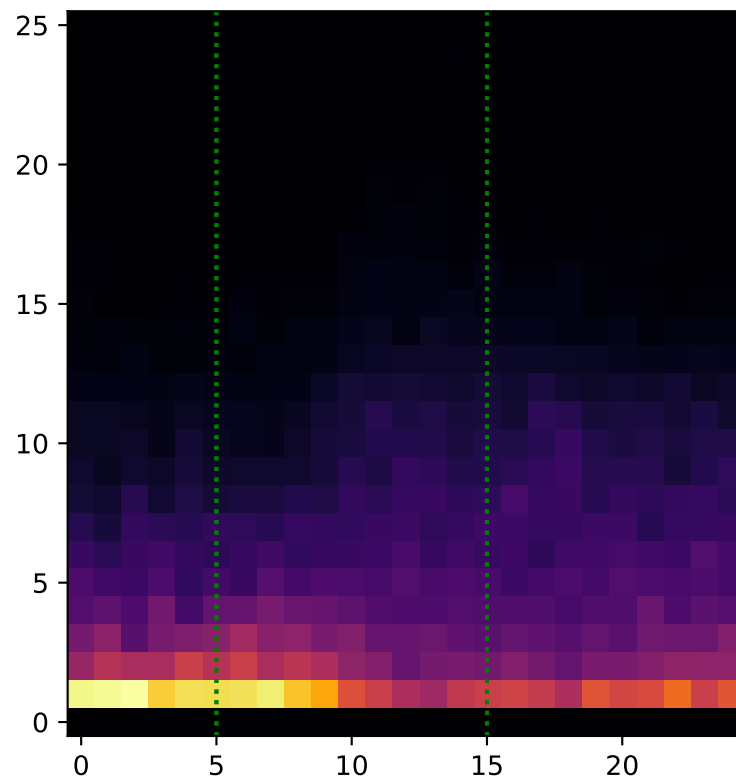


relative_to_hips_angular_velocity_tail_tip | pval:0.8140540540540541

ctr

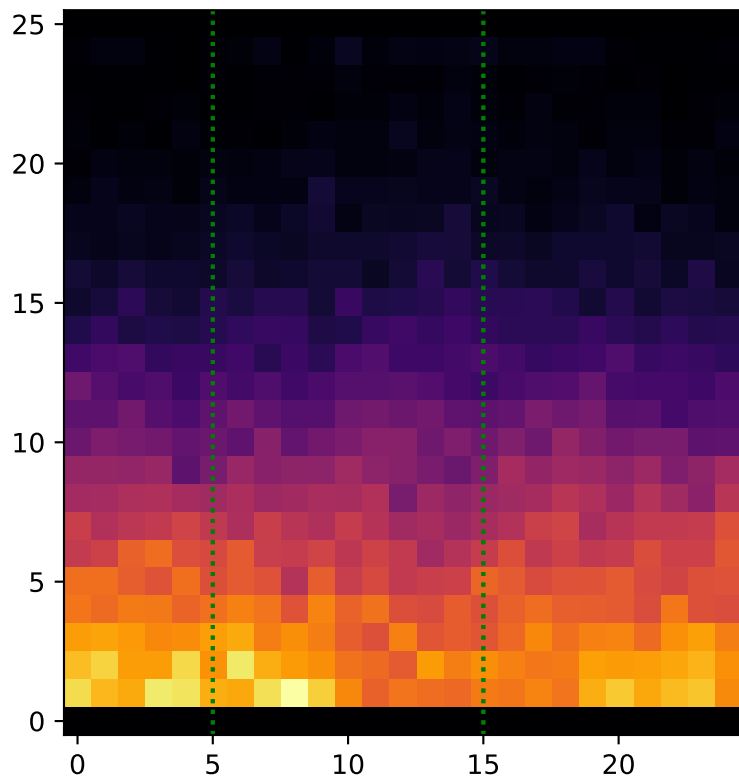


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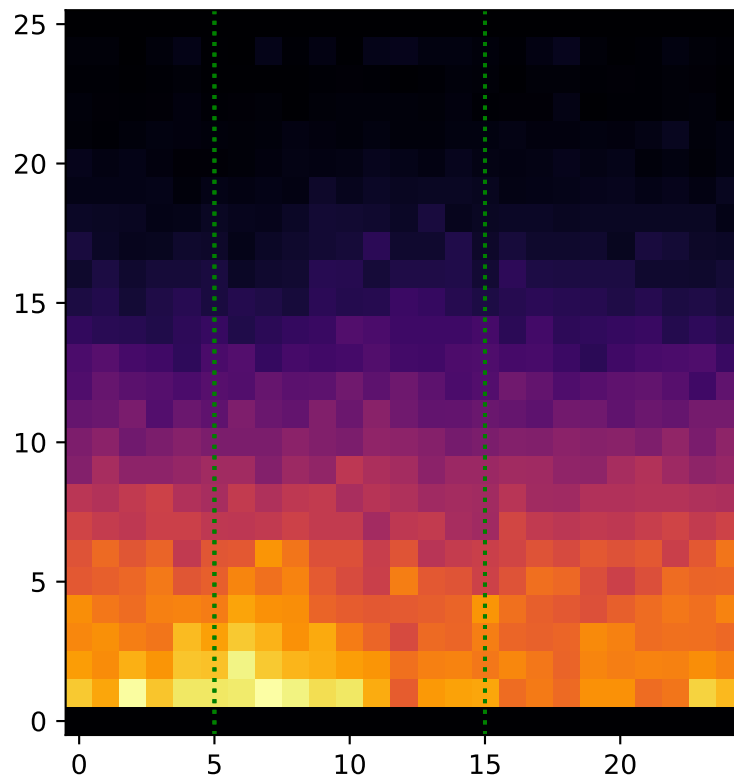


relative_to_head_base_angular_velocity_head_tip | pval:0.8162162162162162

ctr

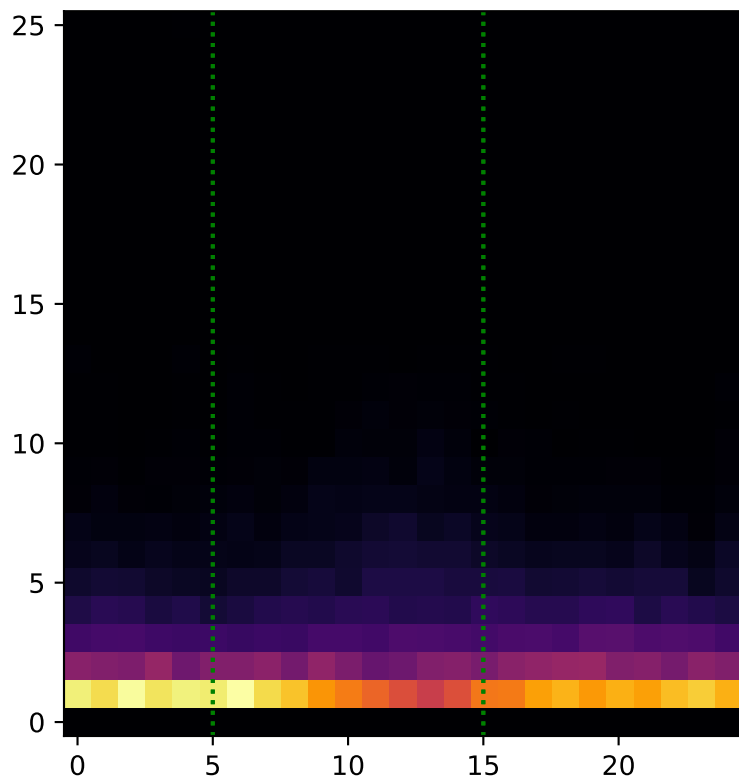


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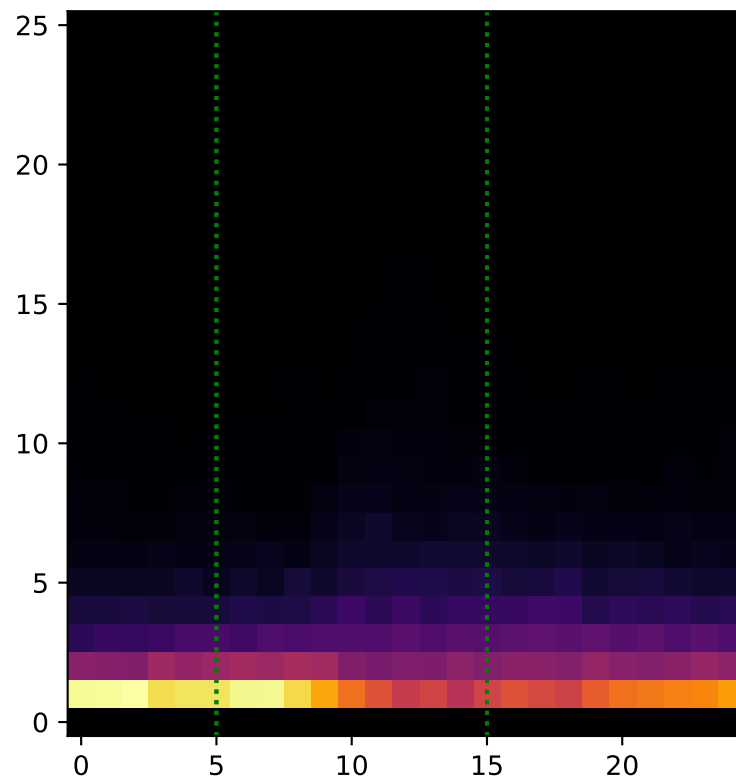


d_relative_to_body_speed_midbody | pval:0.8162162162162162

ctr

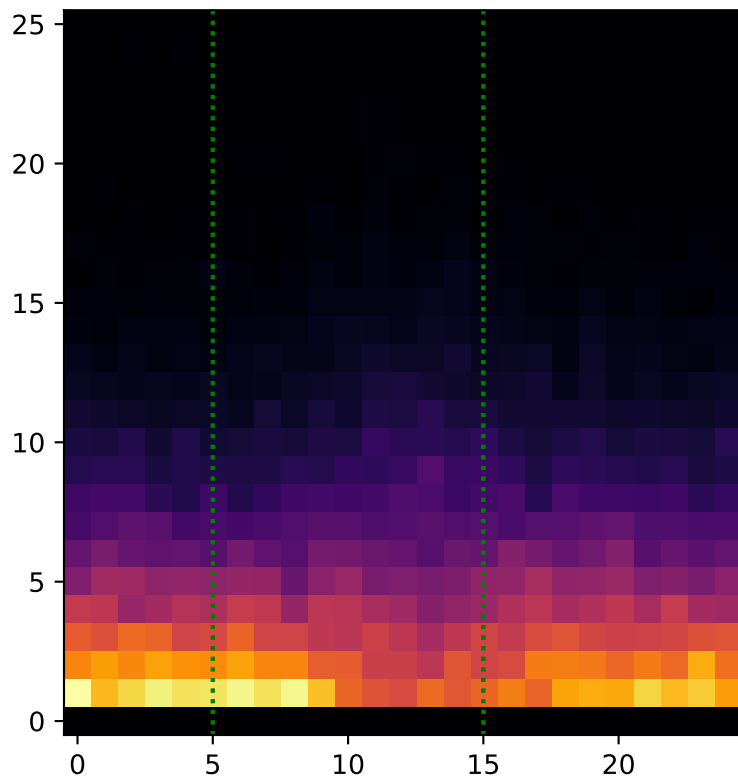


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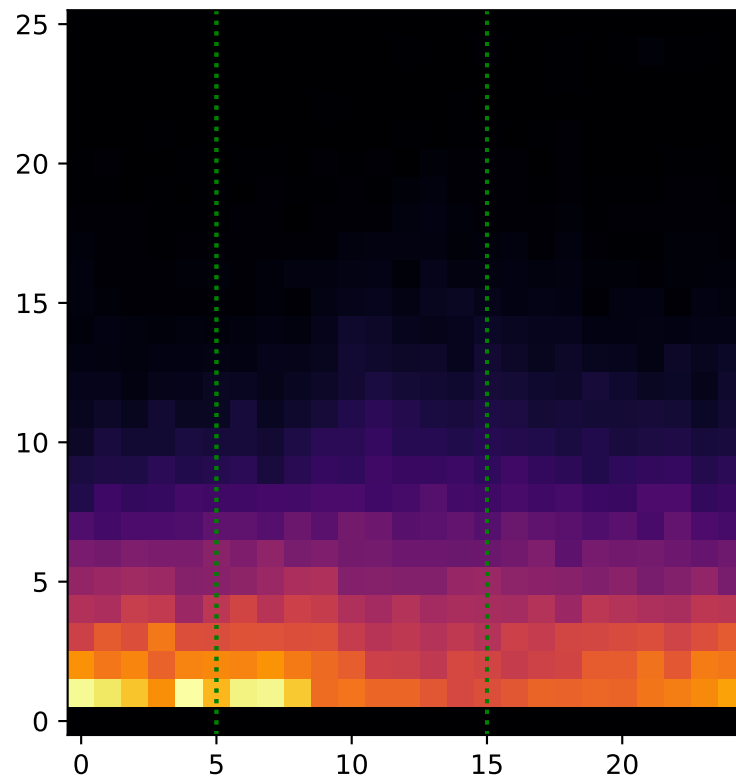


d_relative_to_neck_angular_velocity_head_tip | pval:0.8227027027027027

ctr

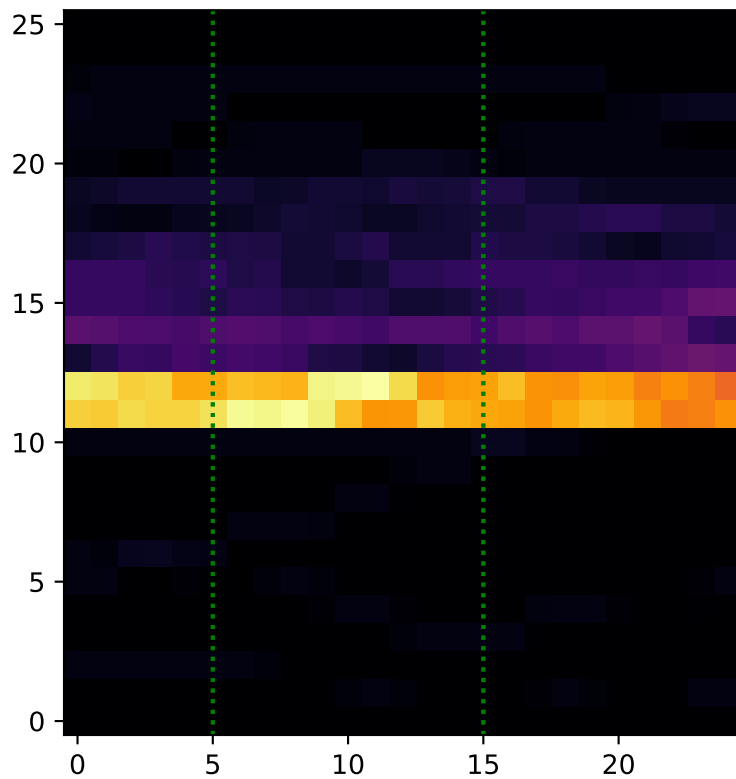


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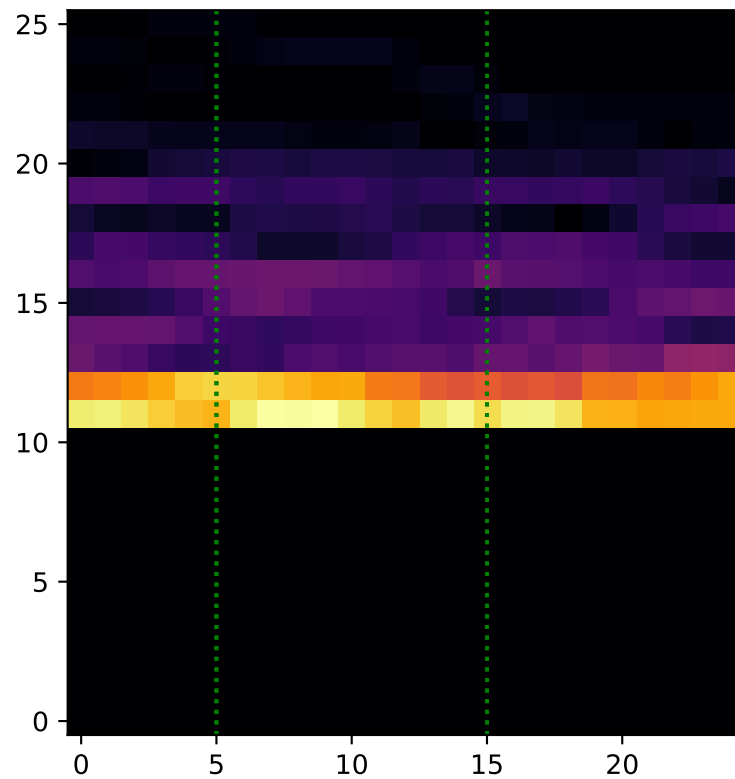


dist_from_food_edge | pval:0.8356756756756757

ctr

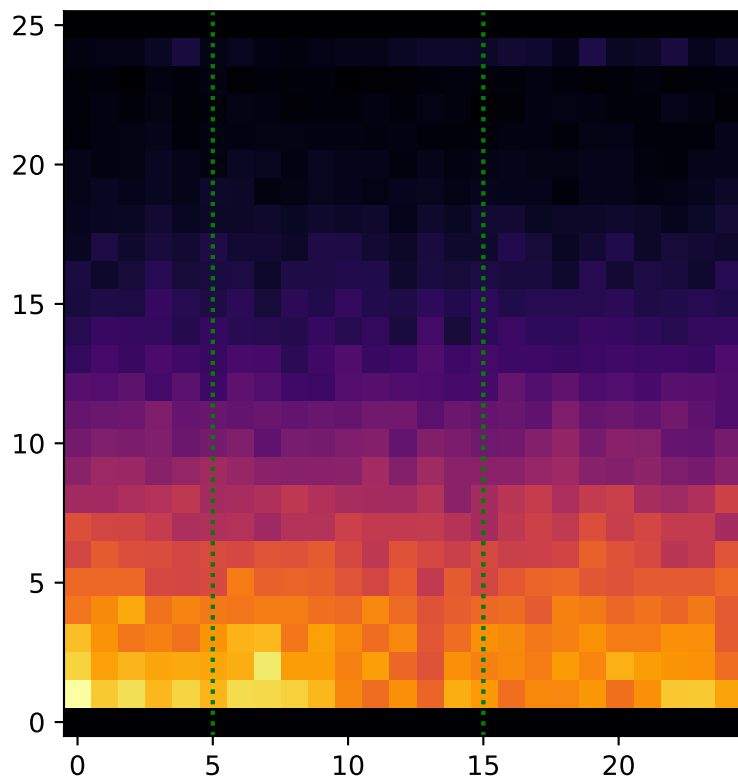


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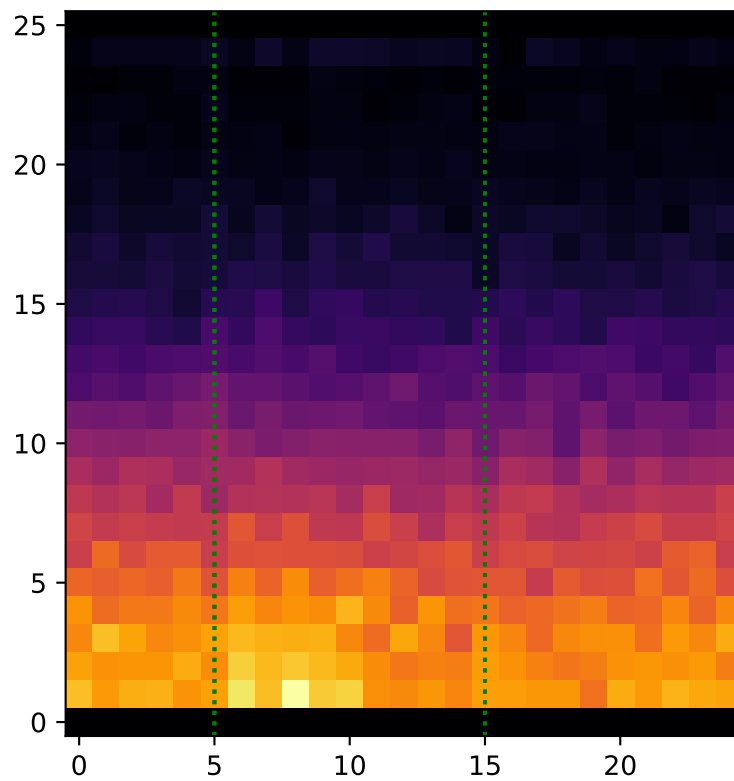


d_eigen_projection_7 | pval:0.8421621621621621

ctr

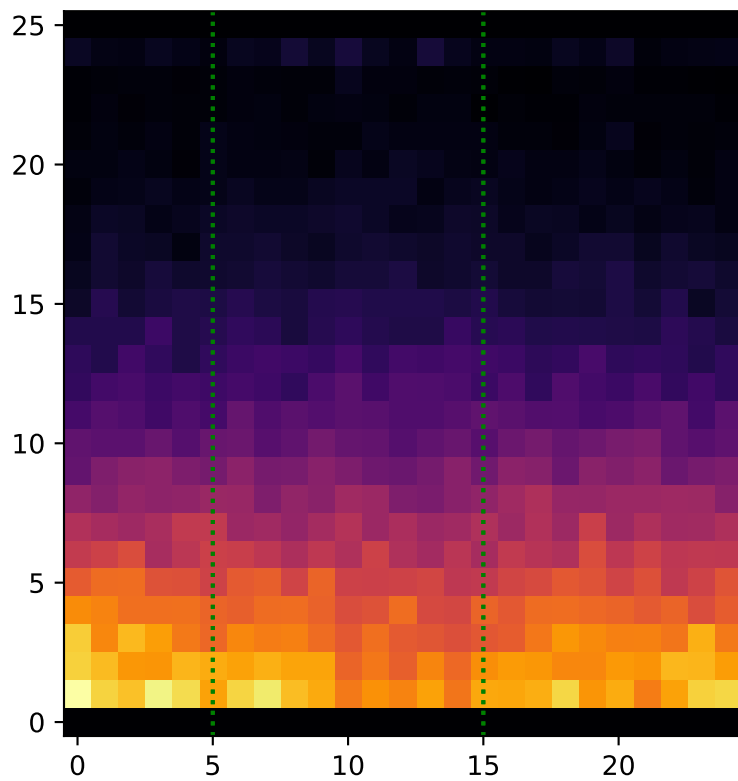


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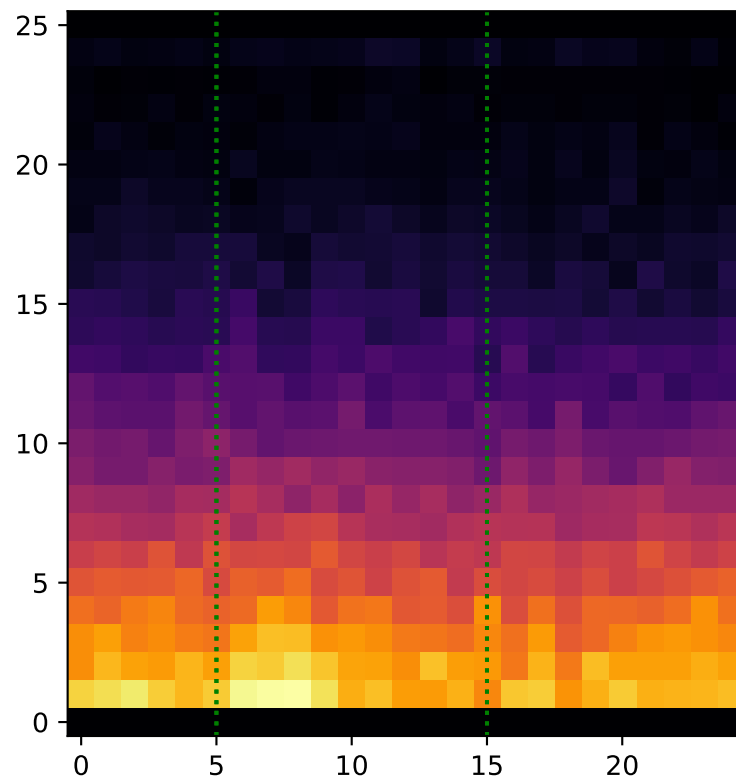


d_curvature_std_head | pval:0.8508108108108108

ctr

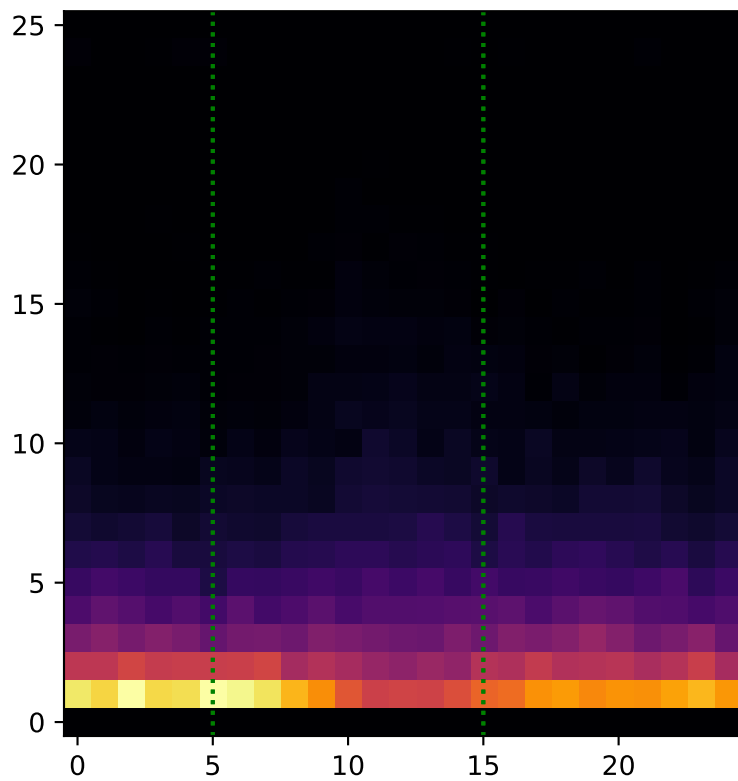


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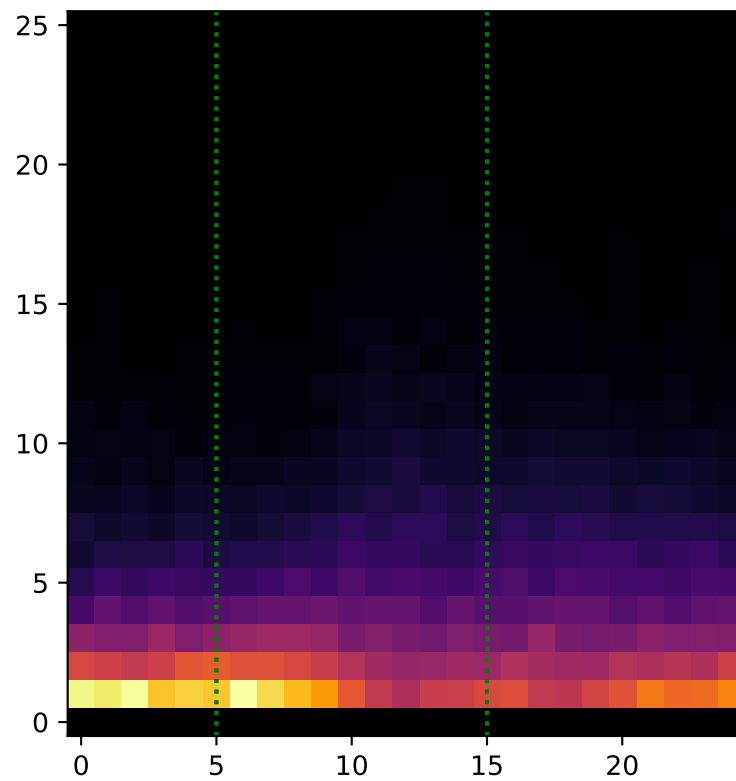


d_relative_to_hips_angular_velocity_tail_tip | pval:0.8702702702702703

ctr

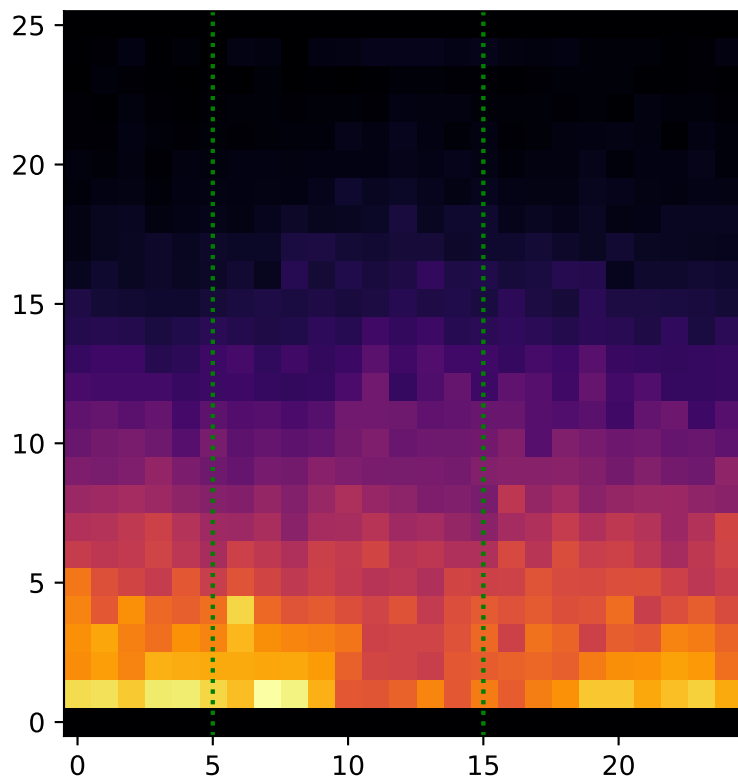


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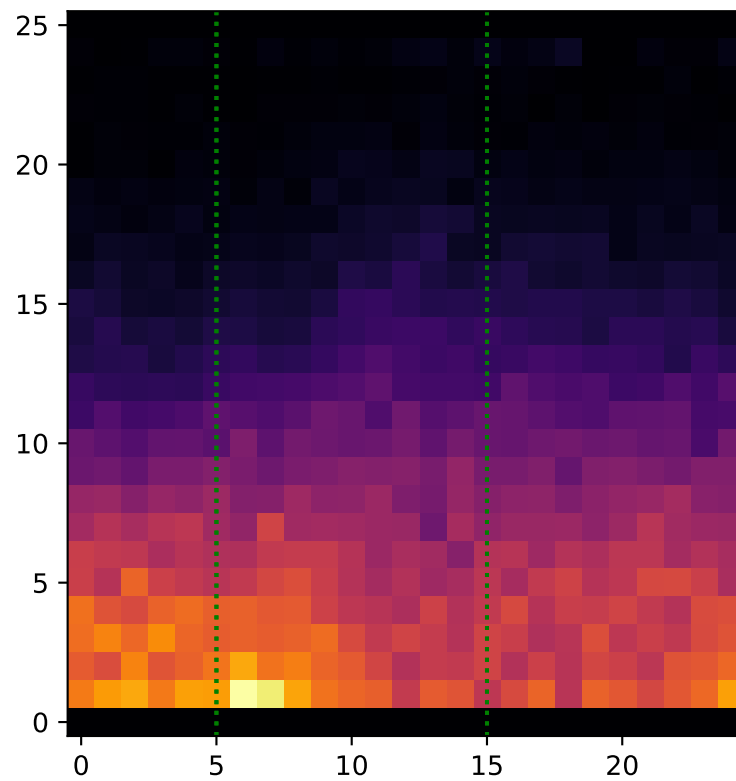


d_curvature_mean_head | pval:0.8724324324324324

ctr

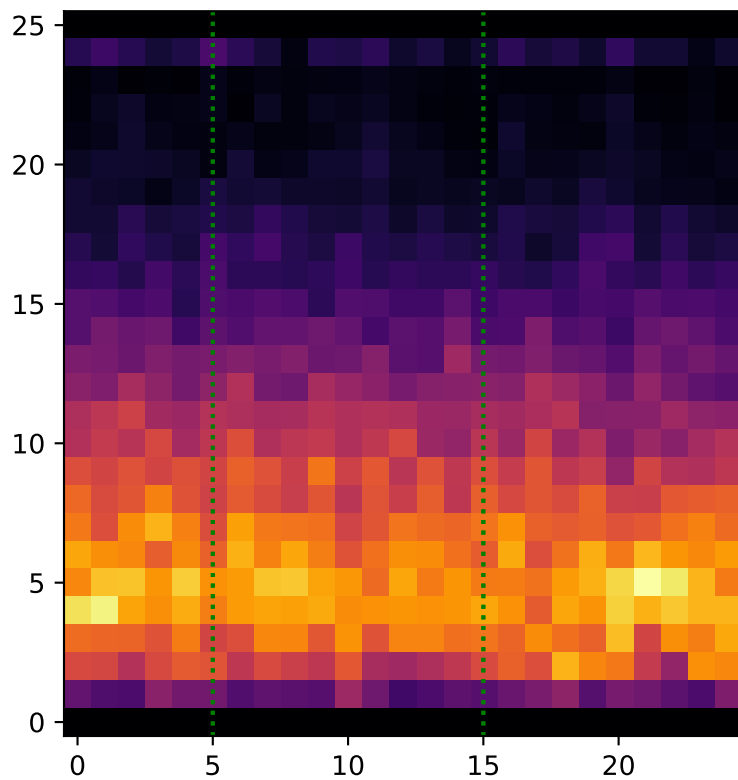


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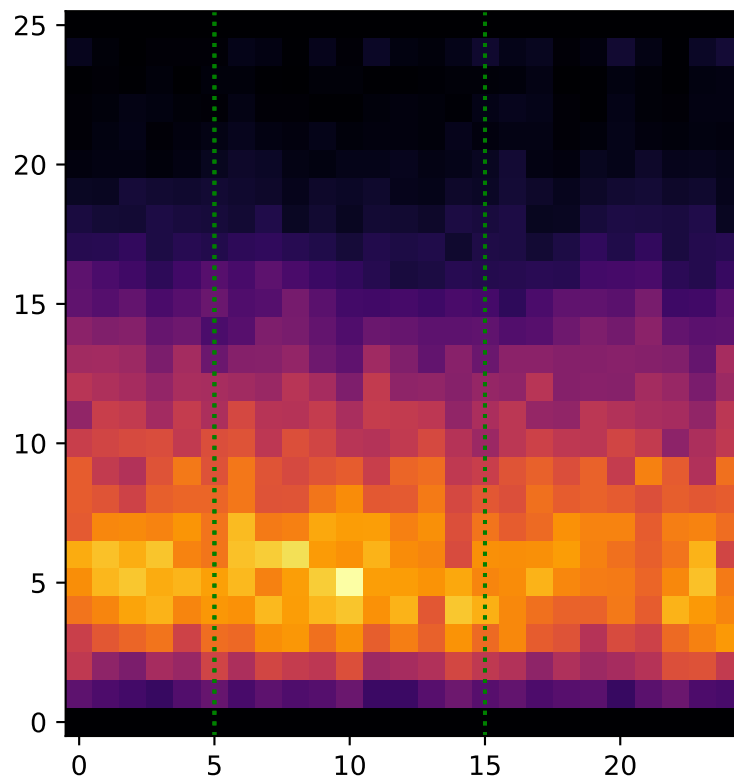


curvature_std_tail | pval:0.8832432432432432

ctr

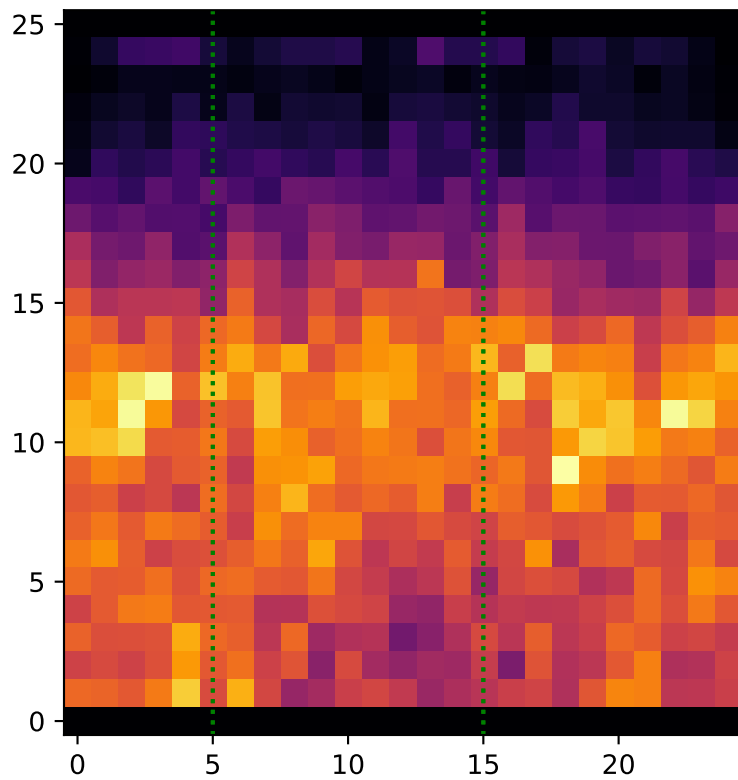


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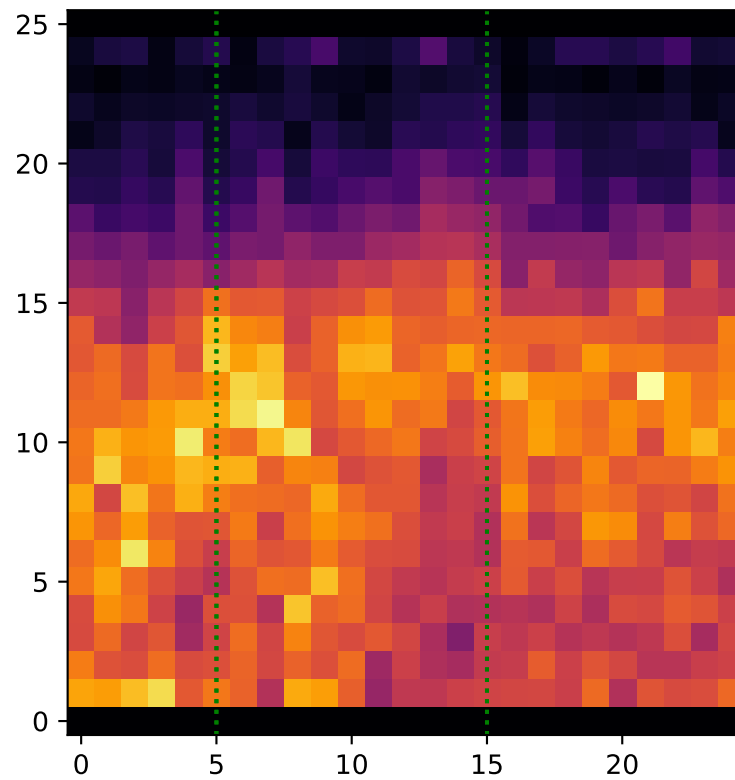


curvature_neck | pval:0.8918918918918919

ctr

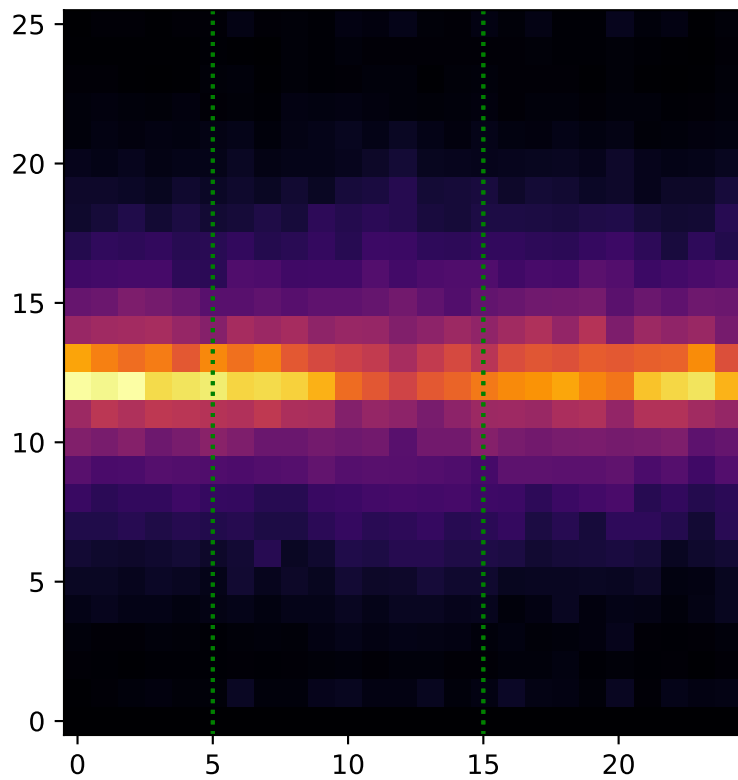


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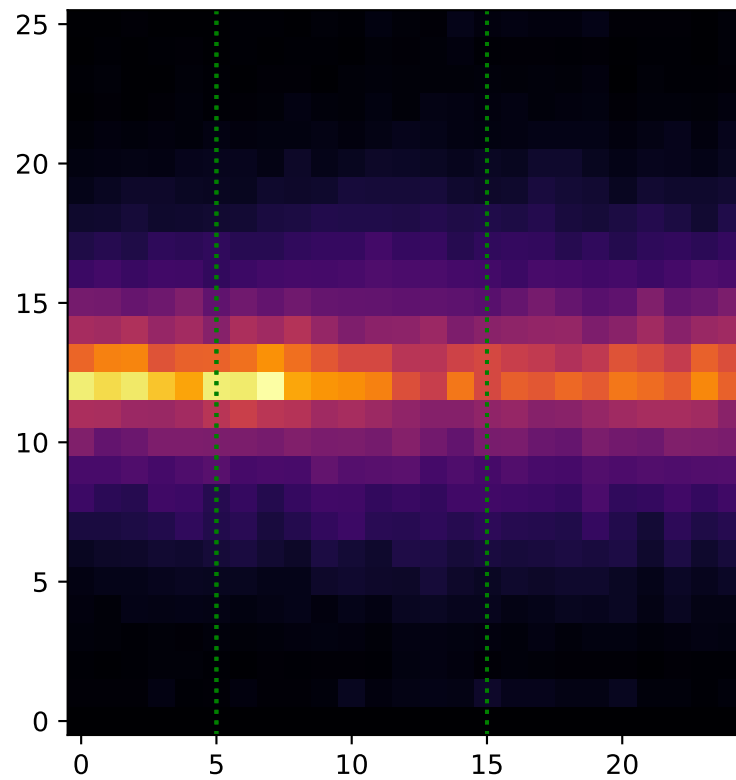


d_width_tail_base | pval:0.8962162162162162

ctr

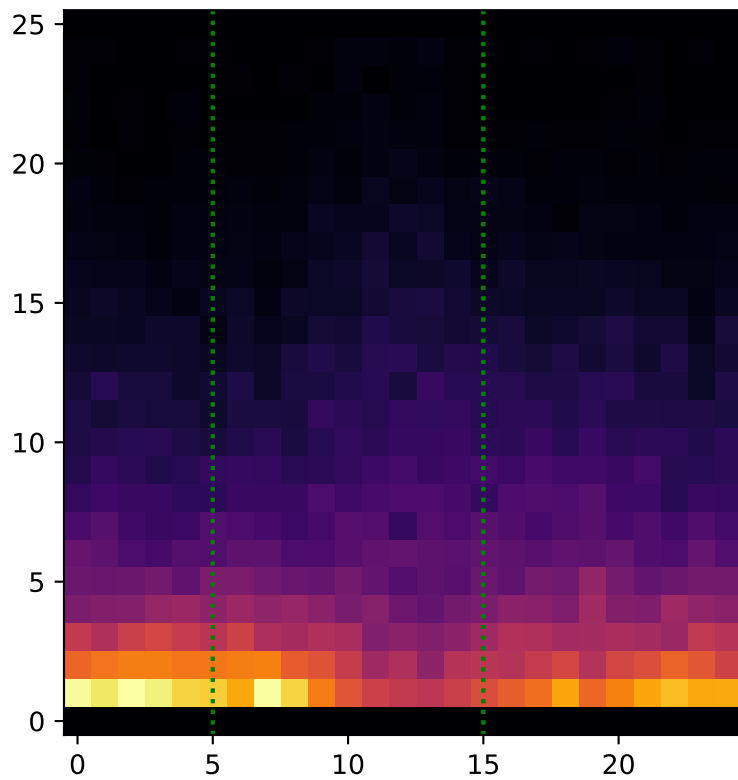


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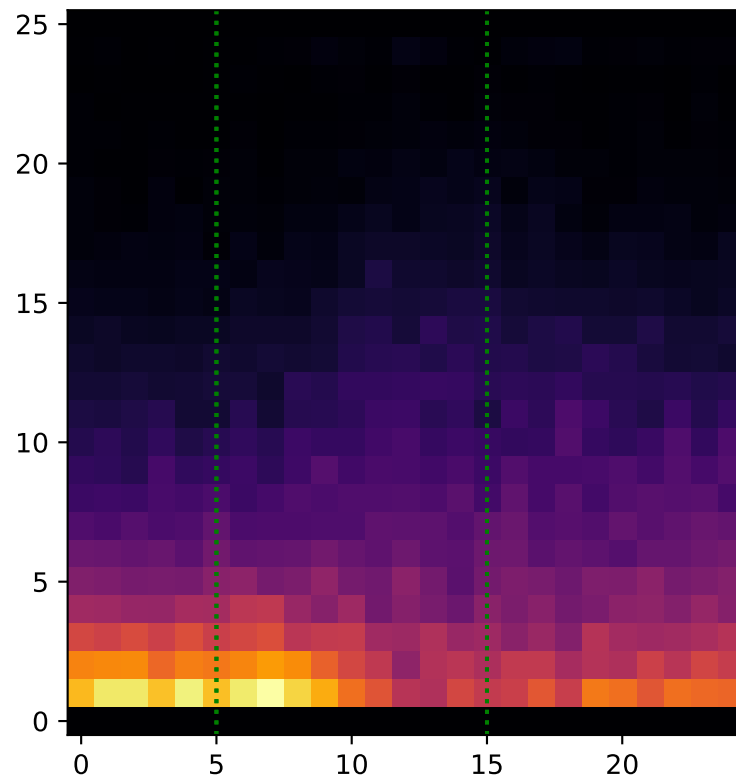


d_curvature_neck | pval:0.9243243243243243

ctr

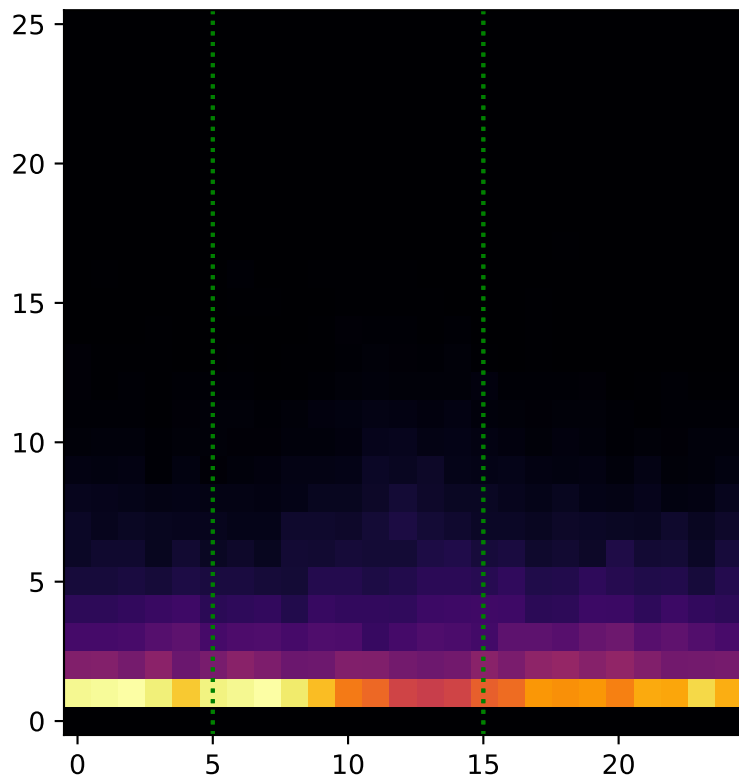


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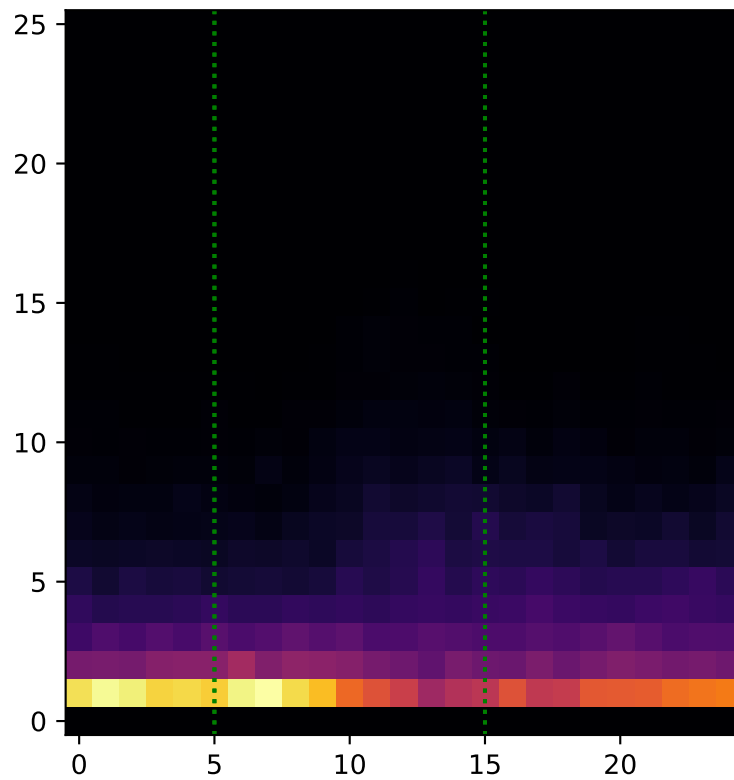


relative_to_body_speed_midbody | pval:0.9286486486486486

ctr

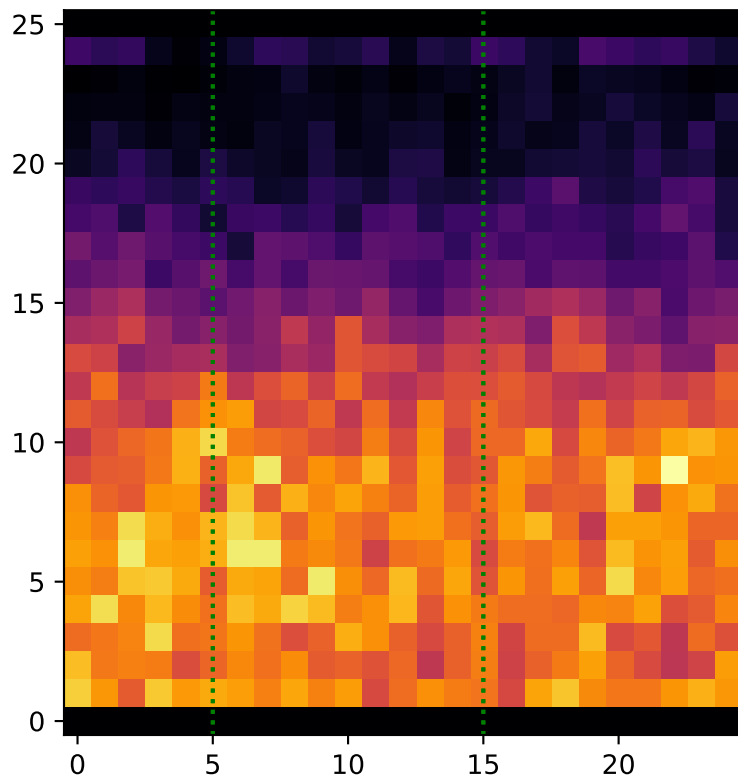


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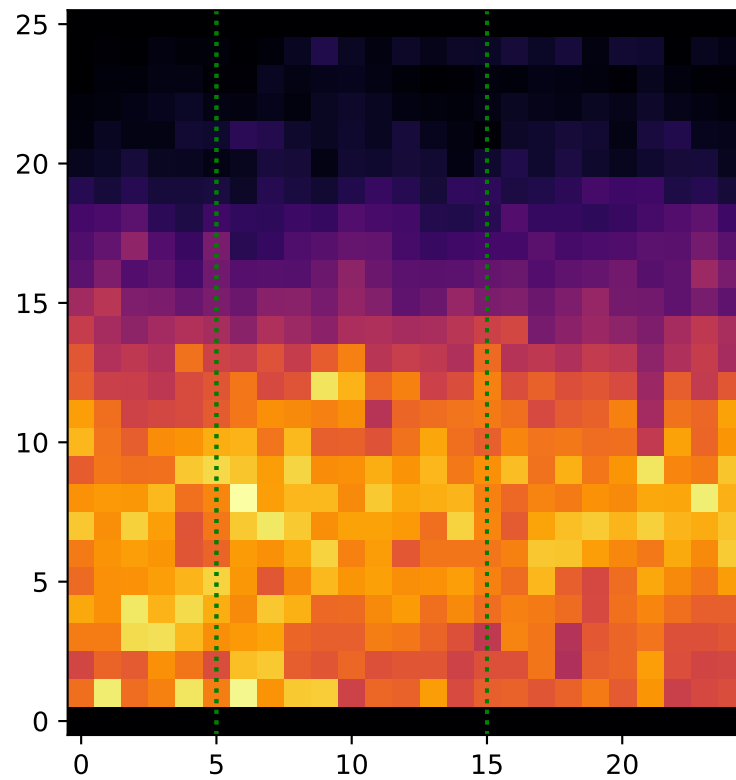


curvature_tail | pval:0.9308108108108109

ctr

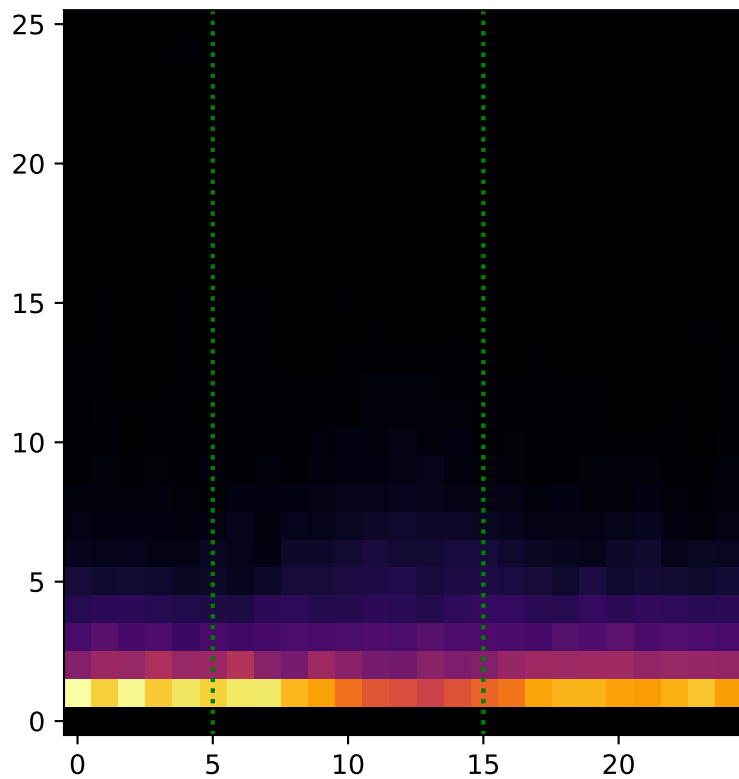


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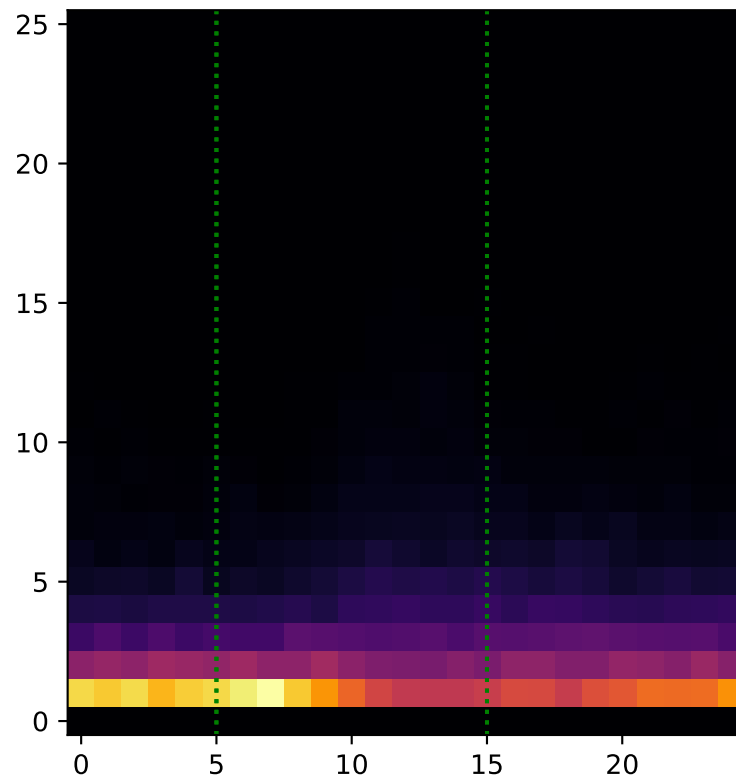


d_relative_to_body_angular_velocity_neck | pval:0.9481081081081081

ctr

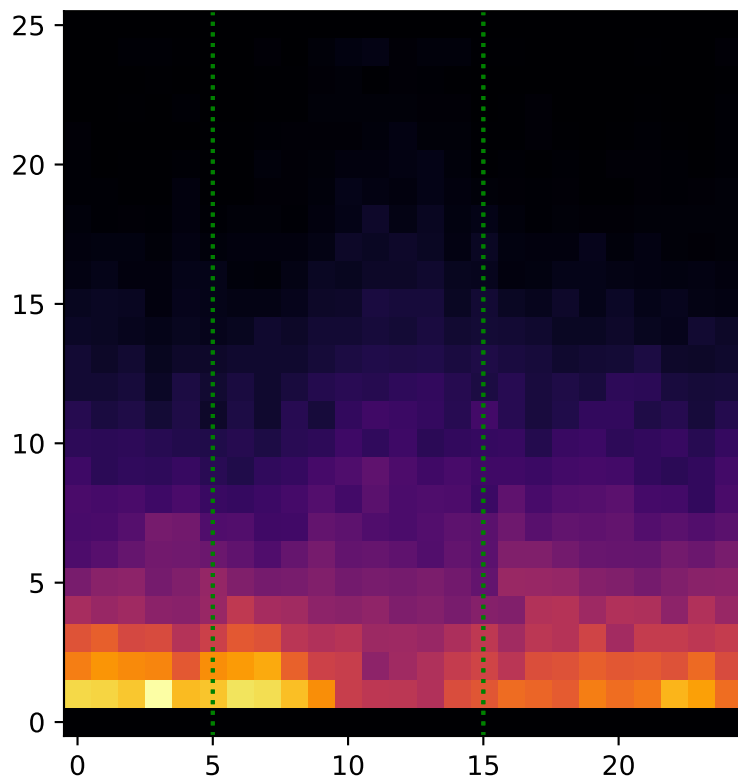


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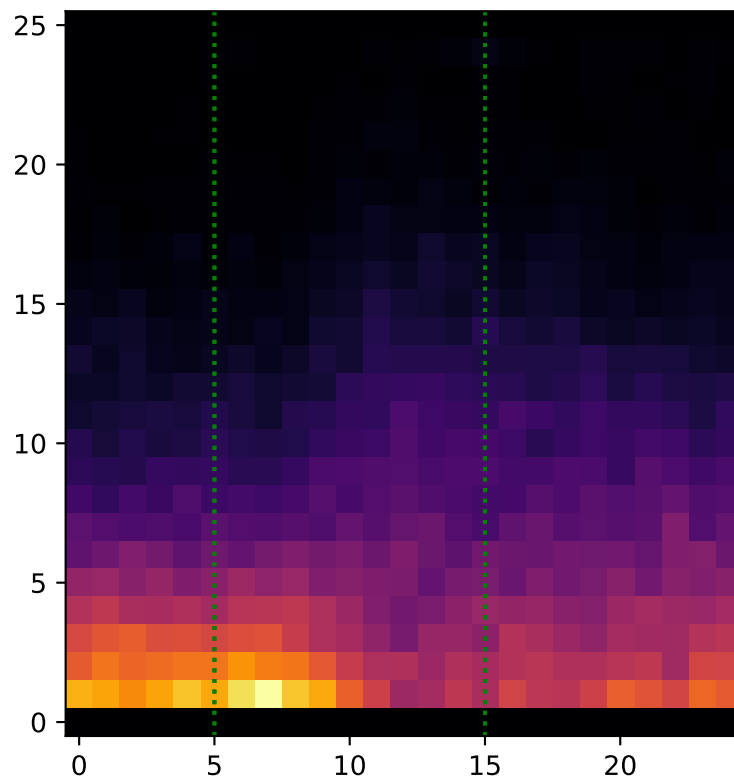


d_eigen_projection_1 | pval:0.9545945945945946

ctr

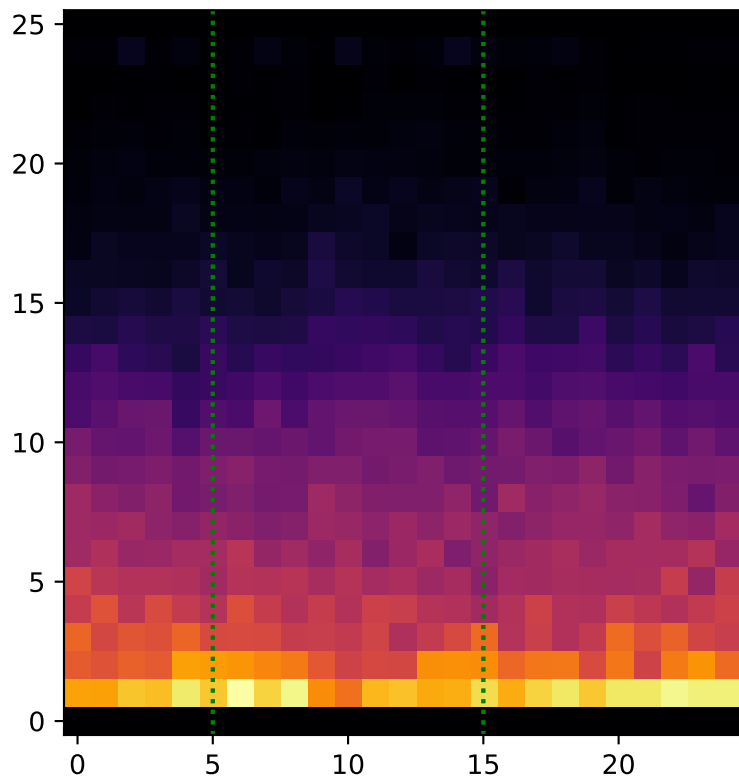


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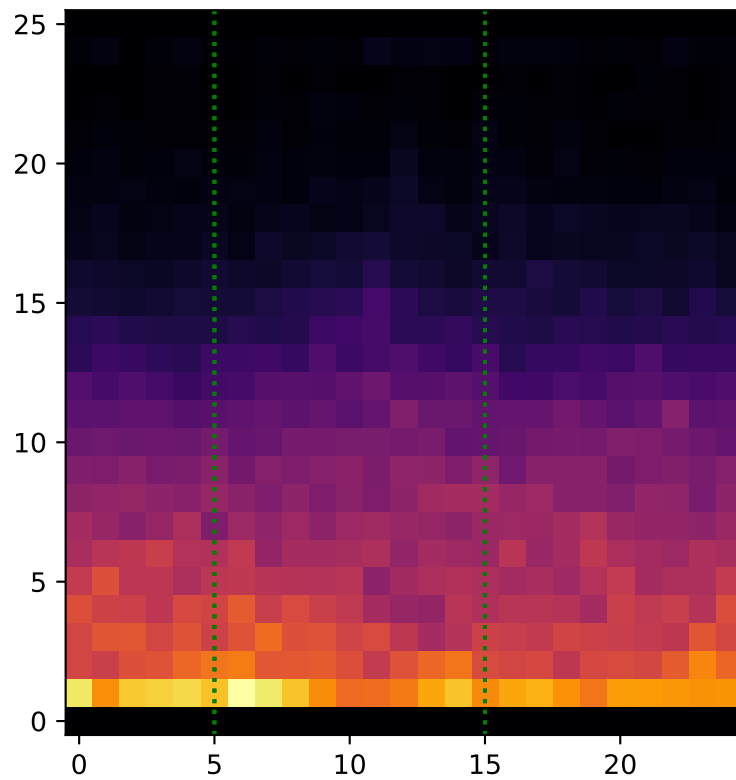


angular_velocity_head_tip | pval:0.9589189189189189

ctr

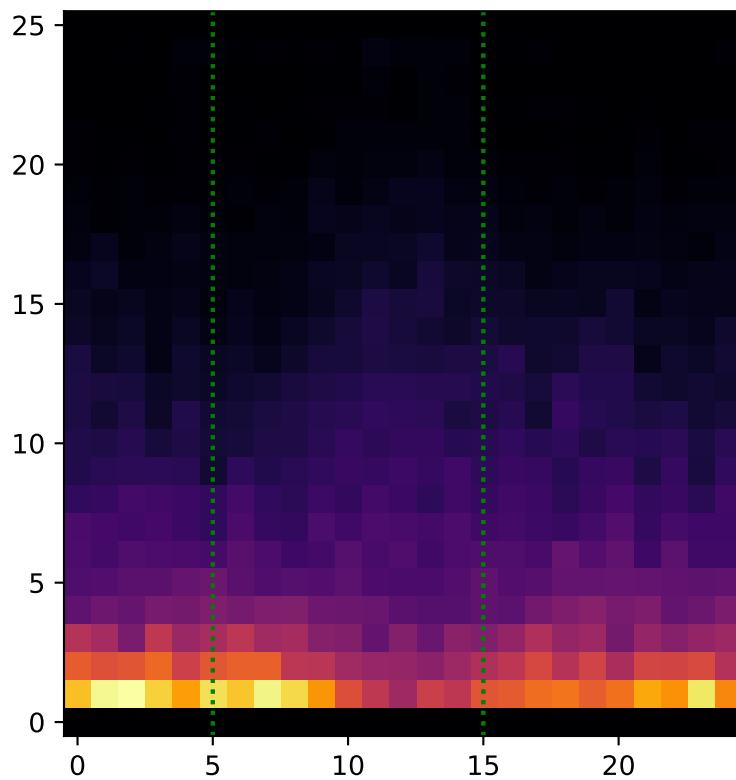


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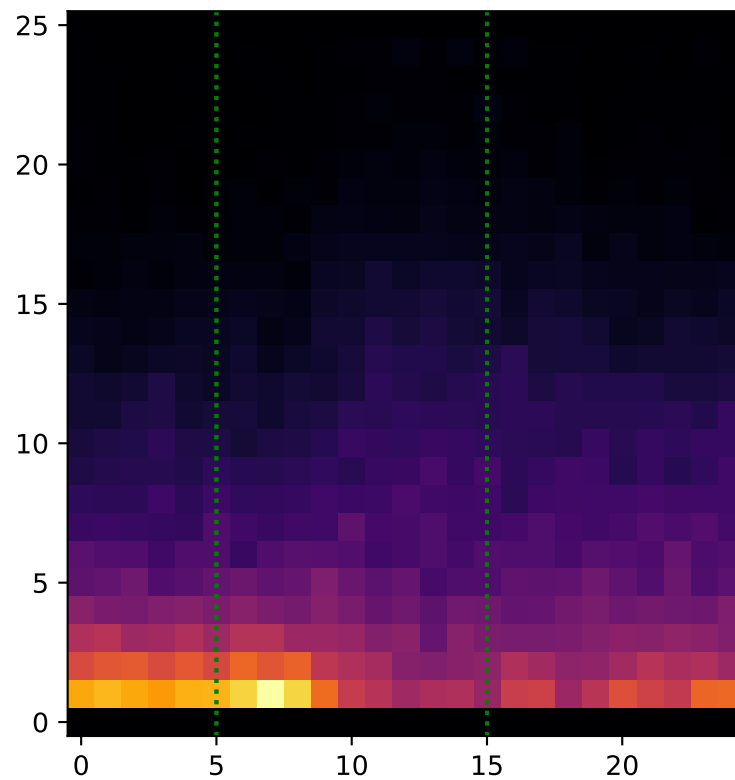


d_curvature_mean_neck | pval:0.9783783783783784

ctr

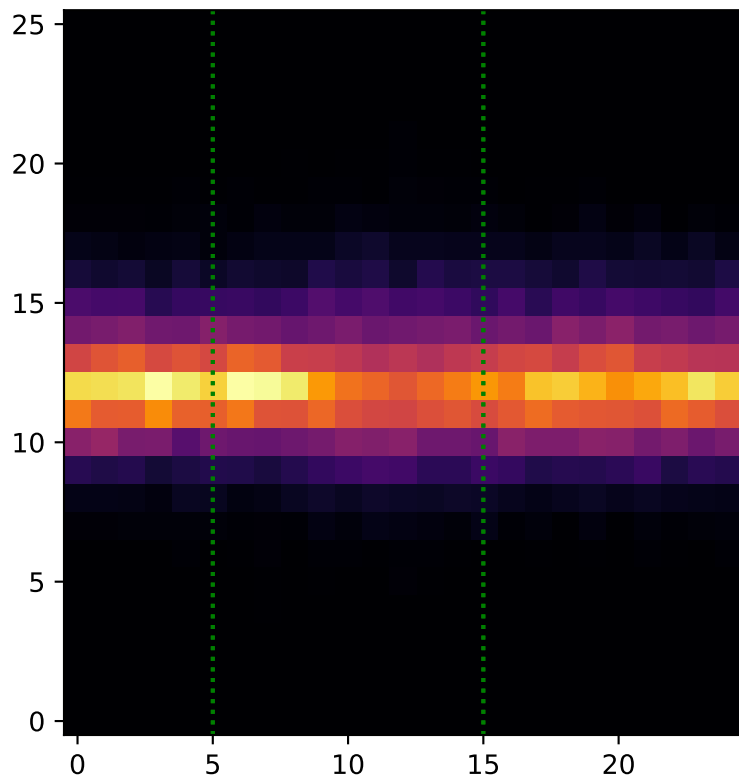


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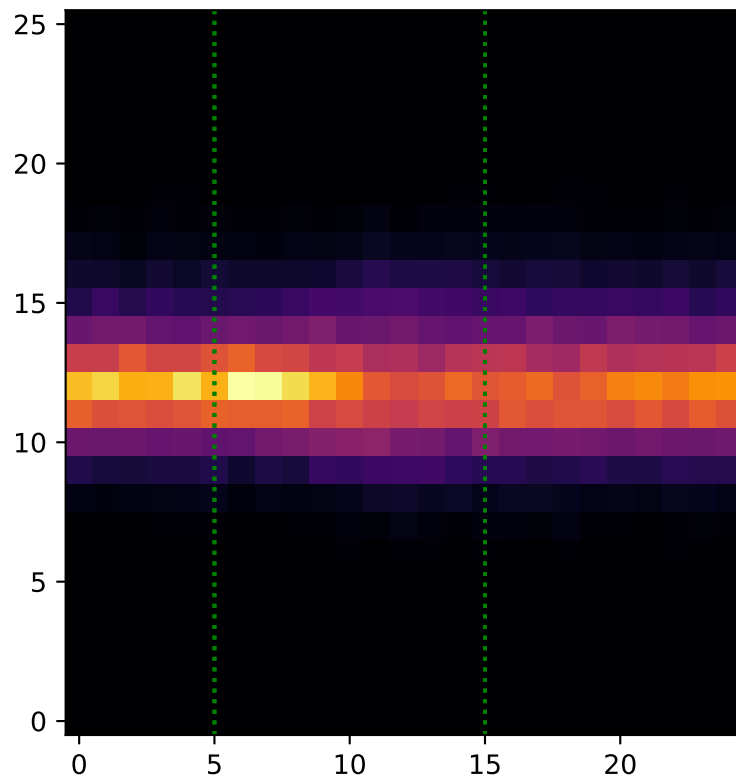


d_relative_to_neck_radial_velocity_head_tip | pval:0.987027027027027

ctr

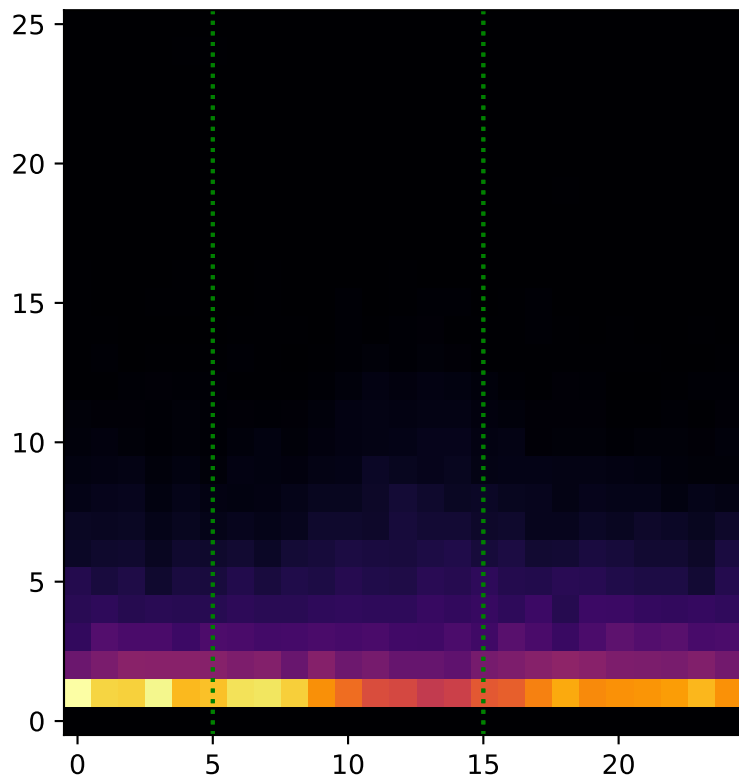


atr



relative_to_body_angular_velocity_neck | pval:0.9935135135135135

ctr



atr

