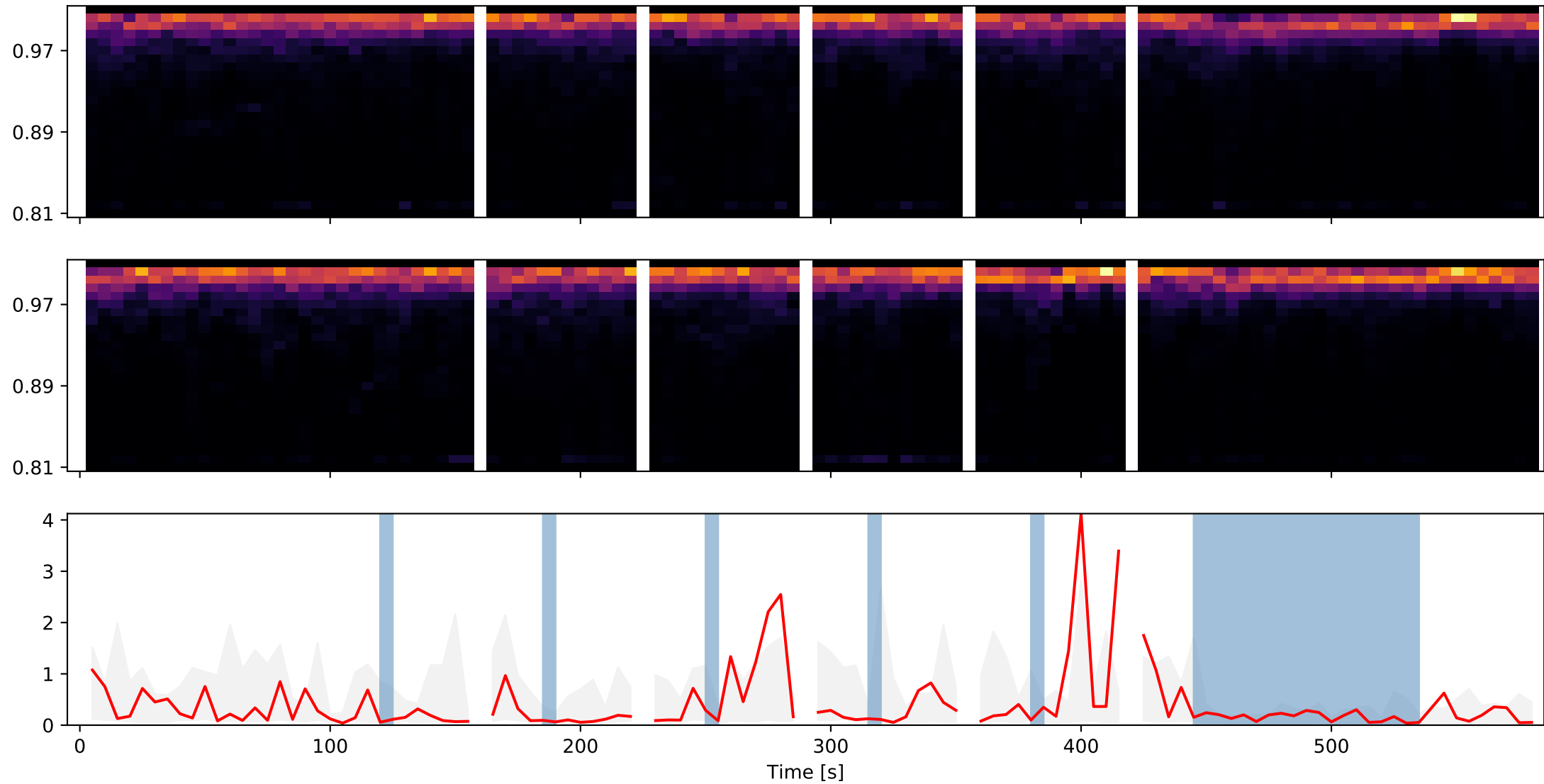
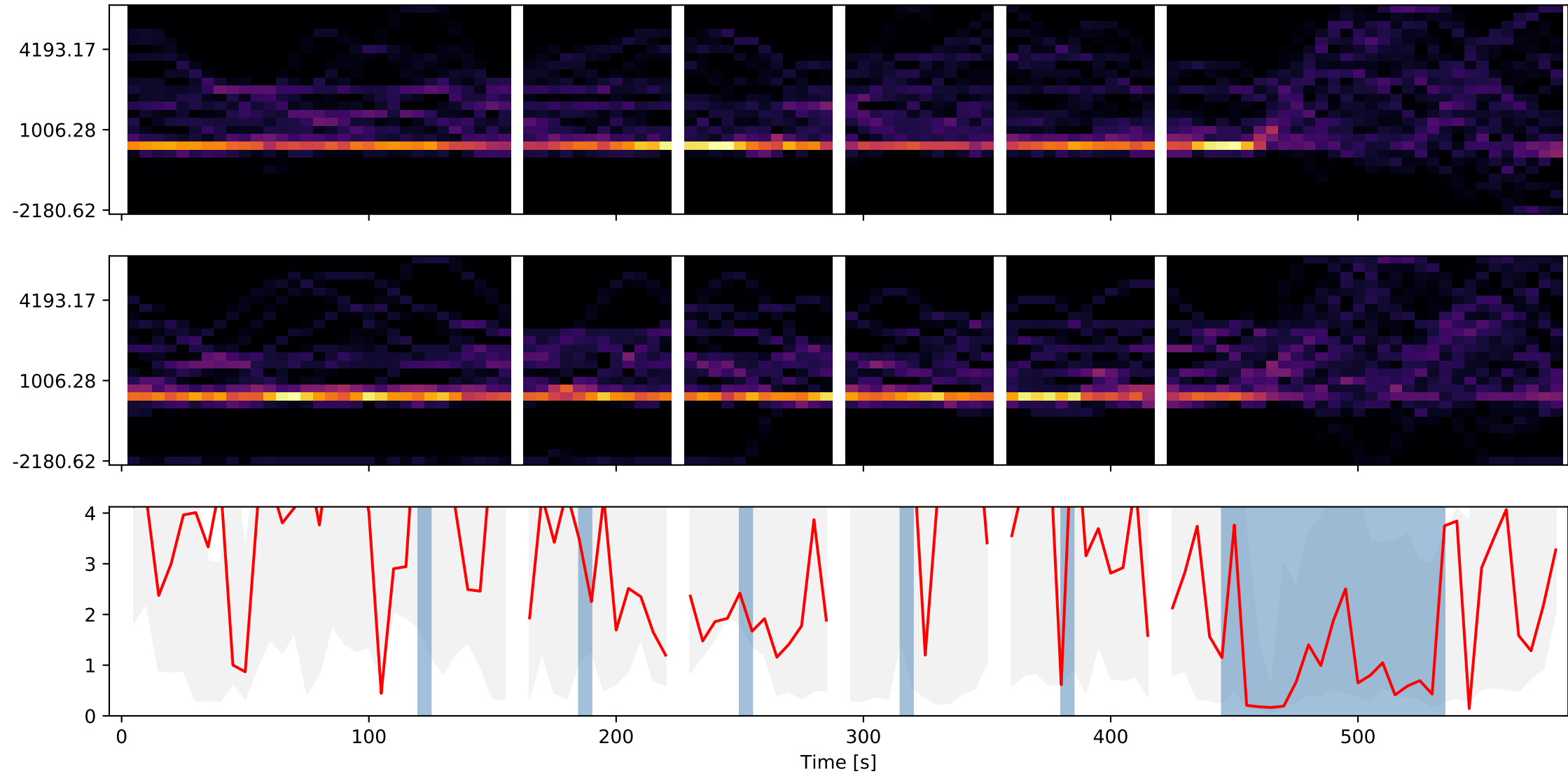


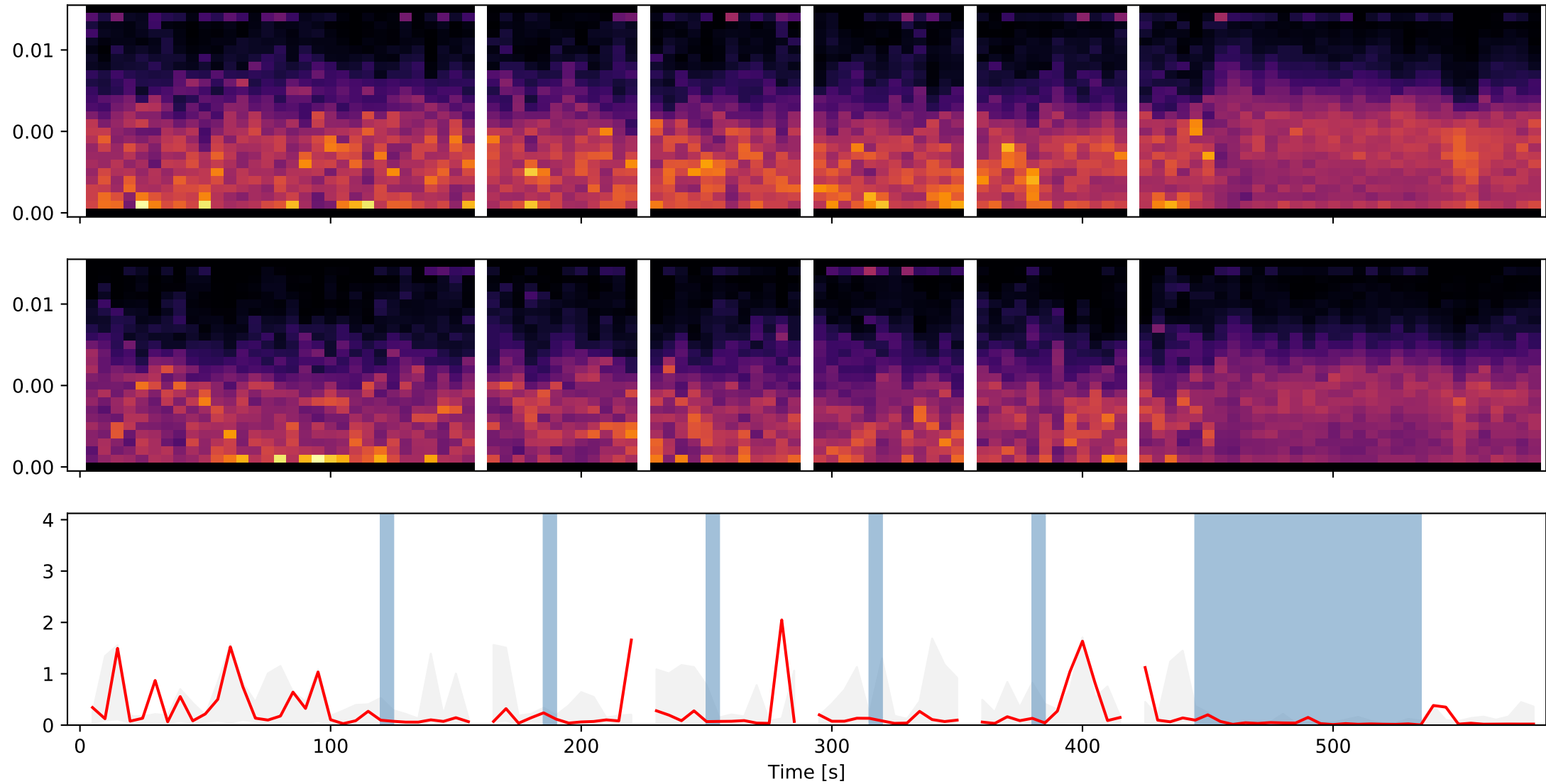
quirkiness



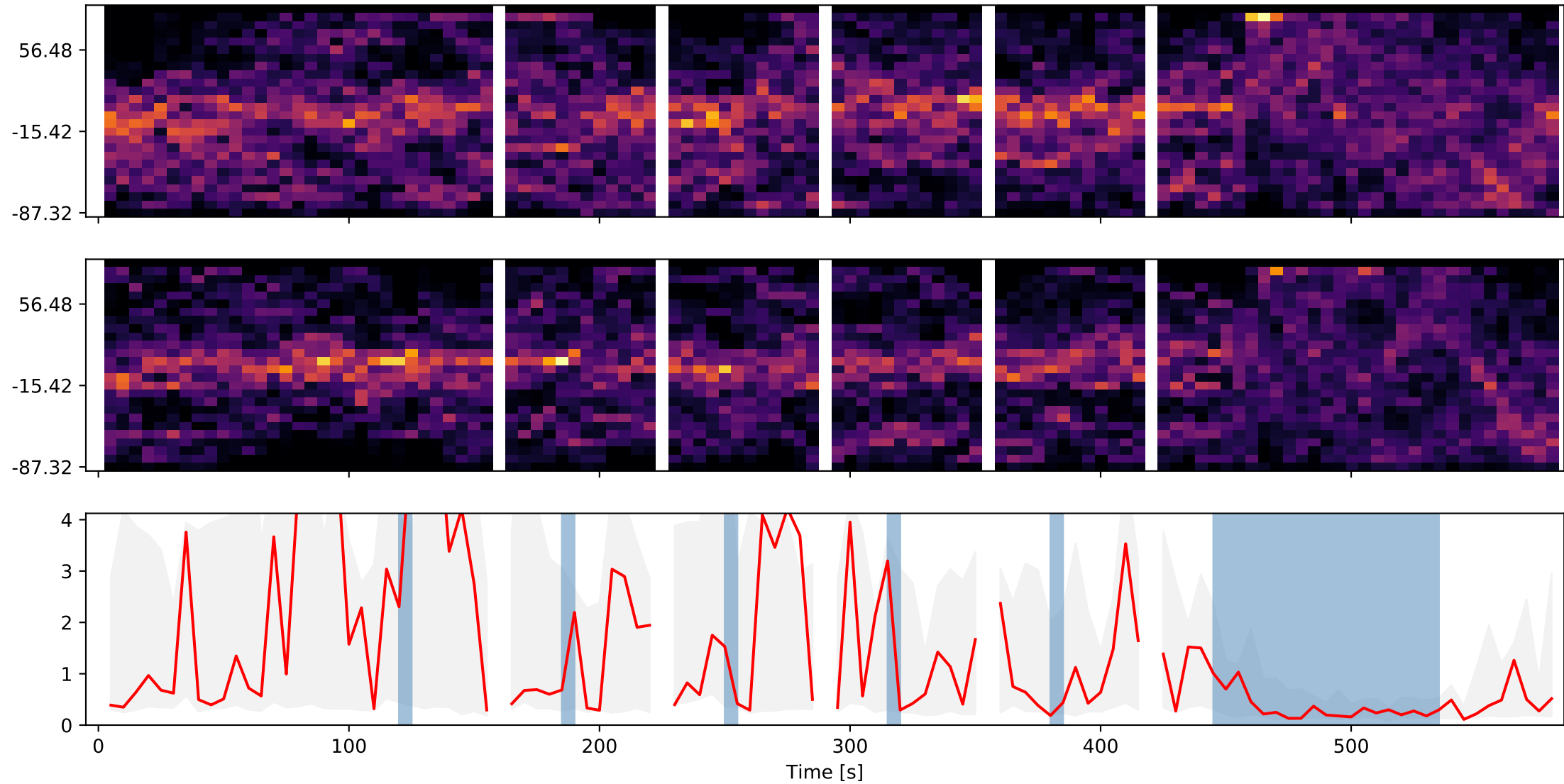
dist_from_food_edge



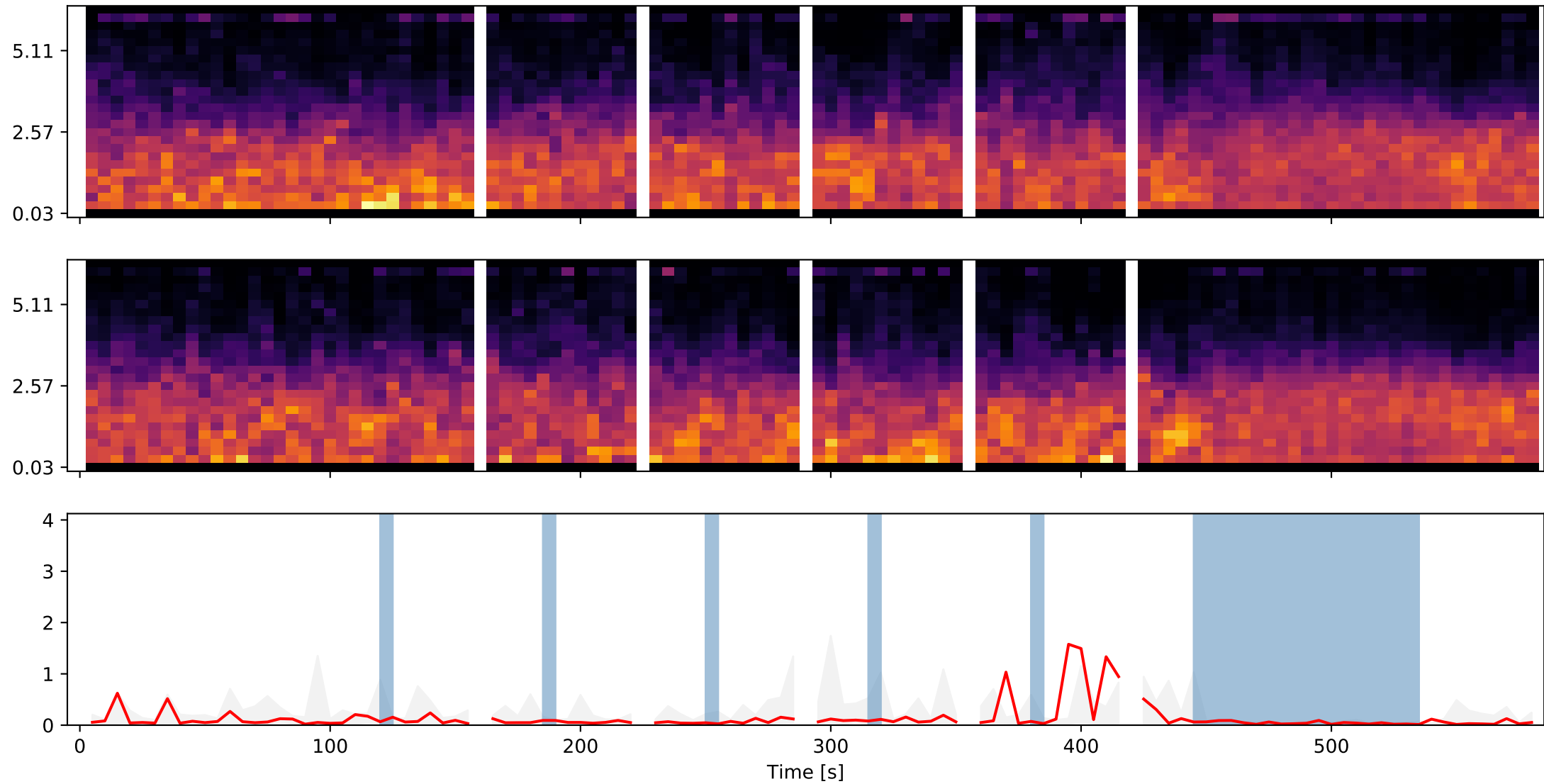
curvature_mean_midbody



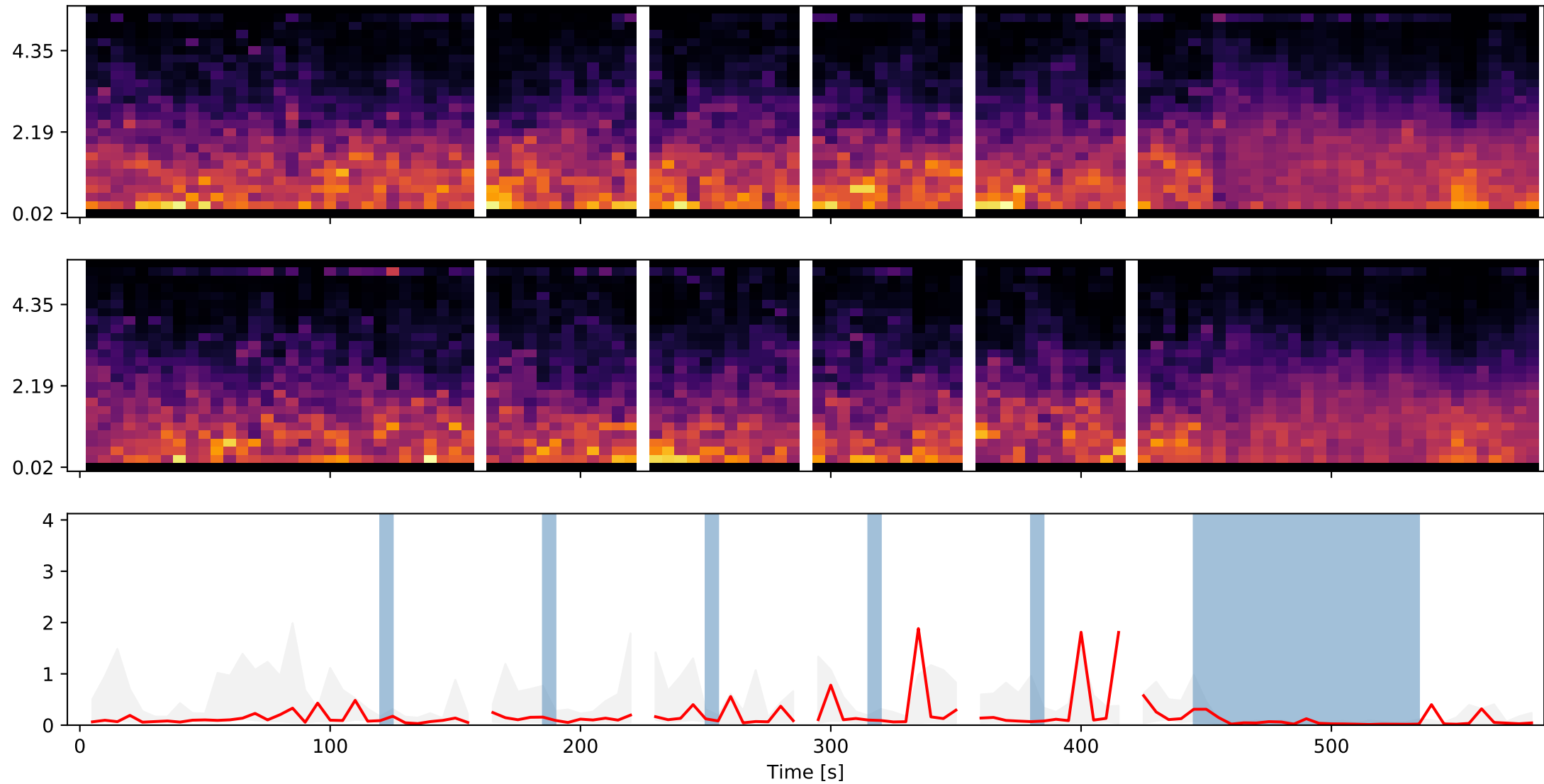
orientation_food_edge



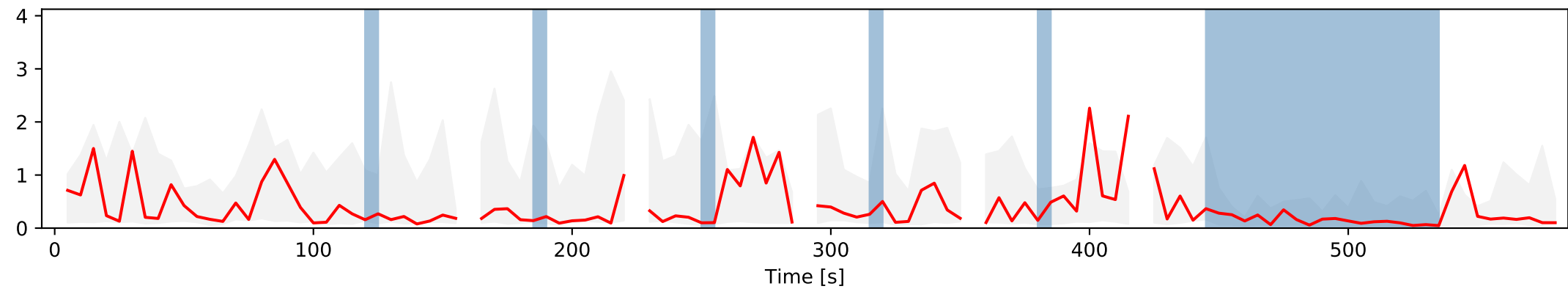
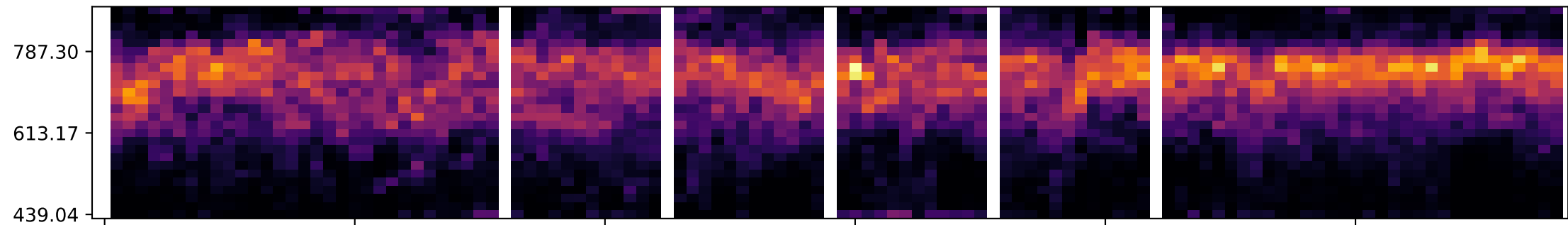
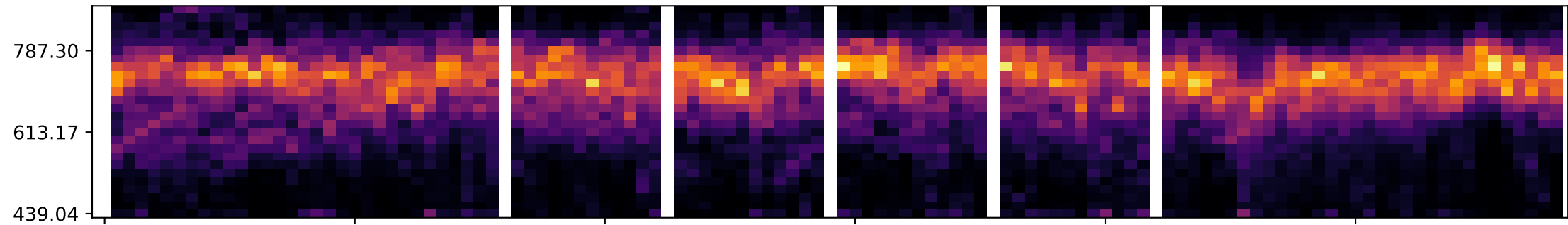
eigen_projection_1



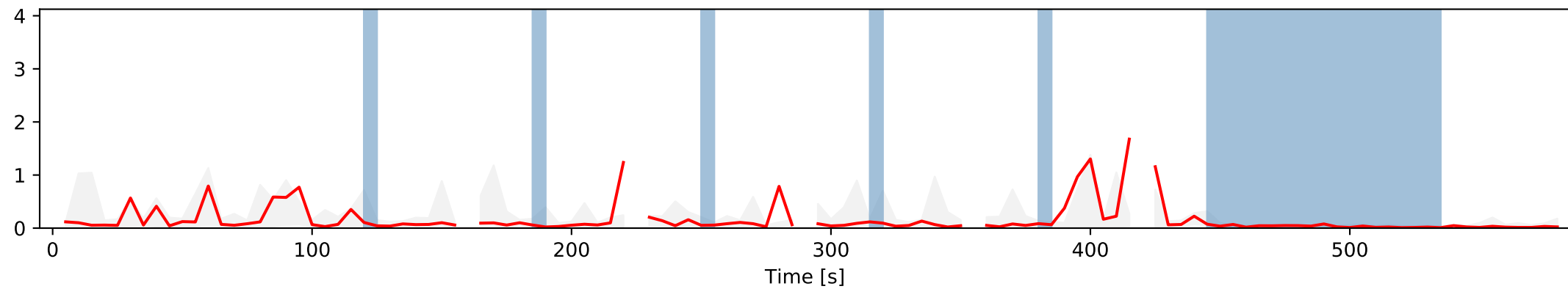
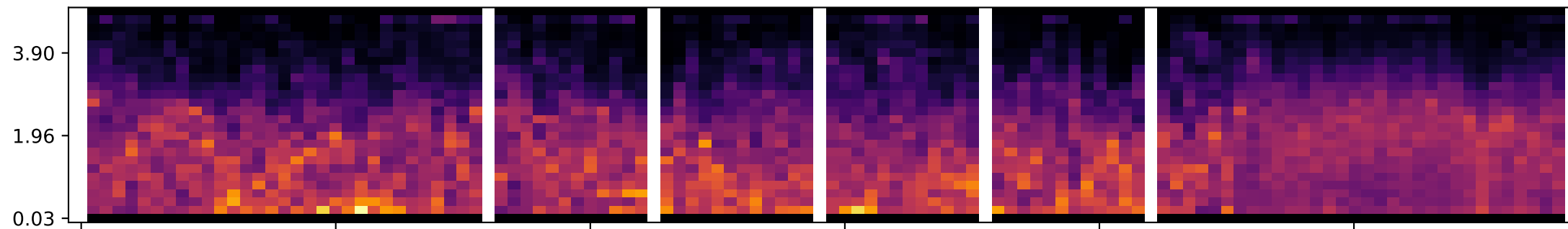
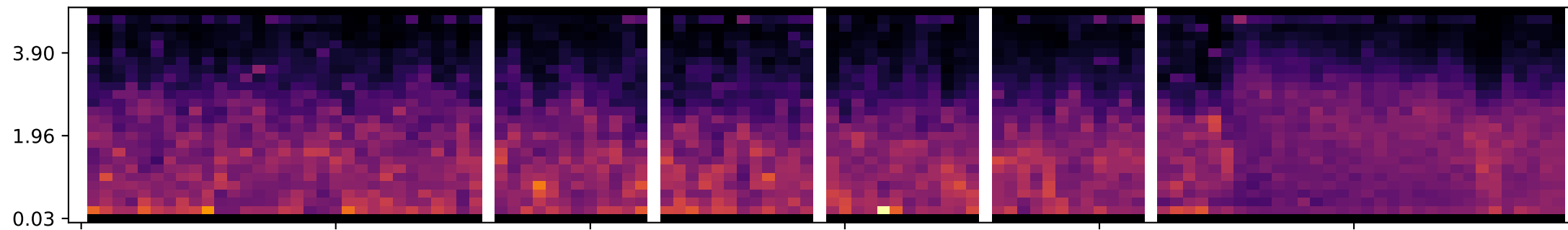
eigen_projection_2



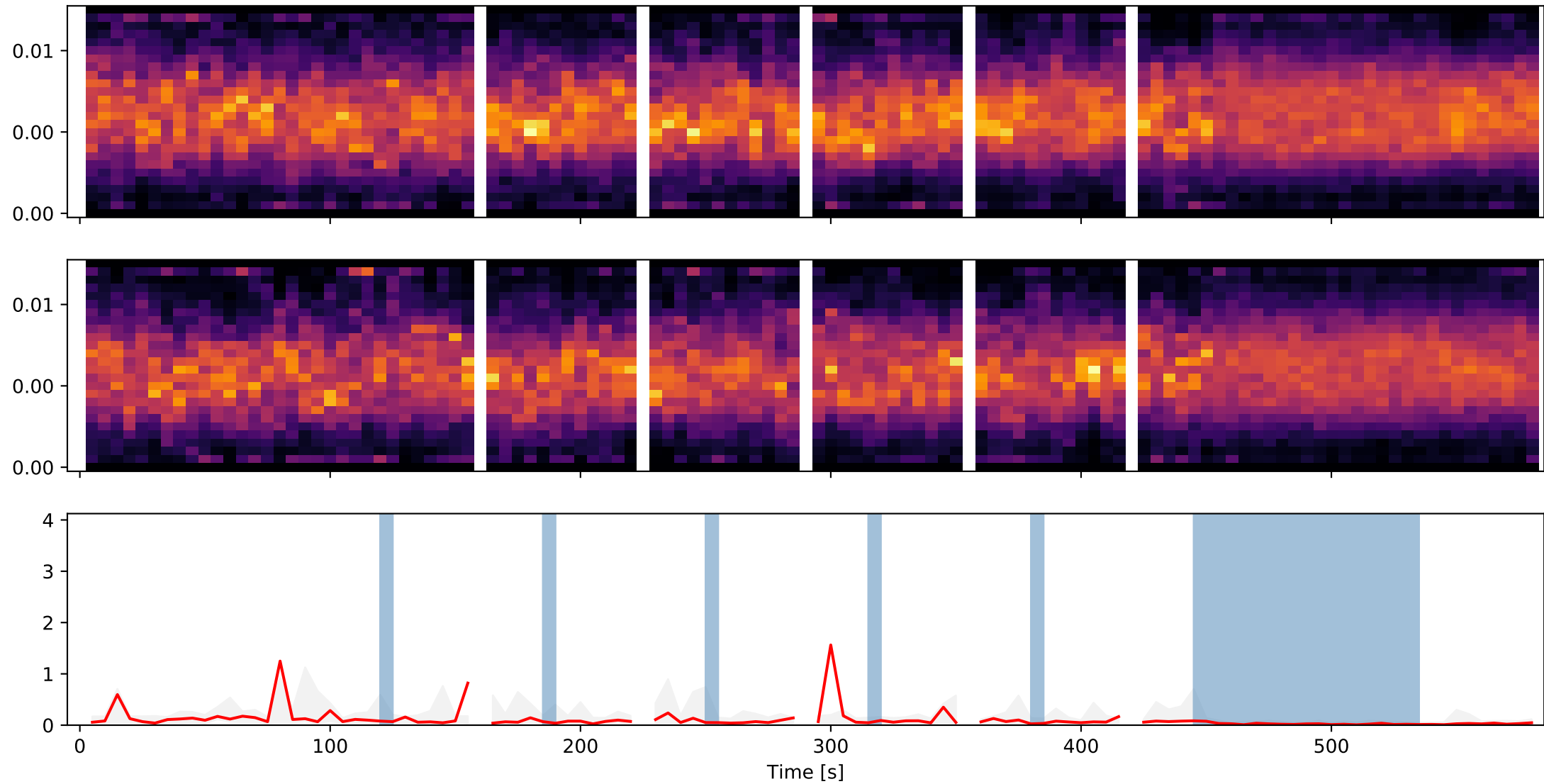
major_axis



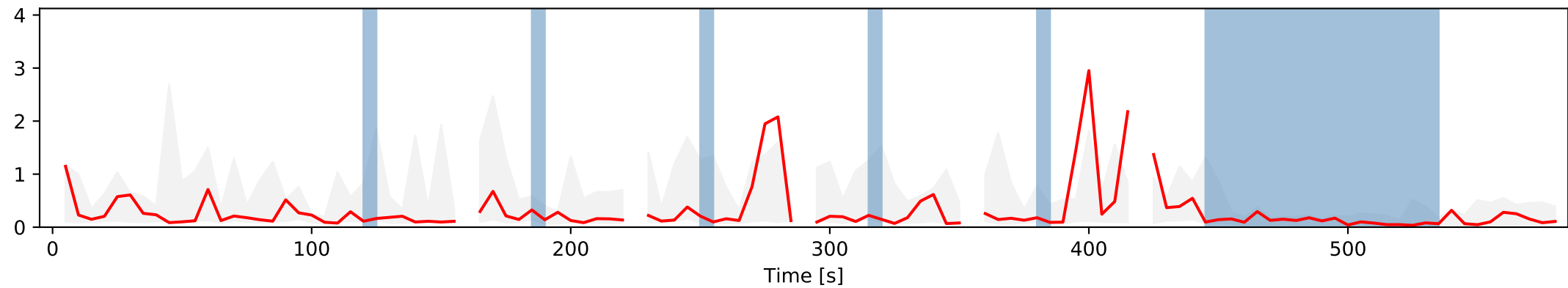
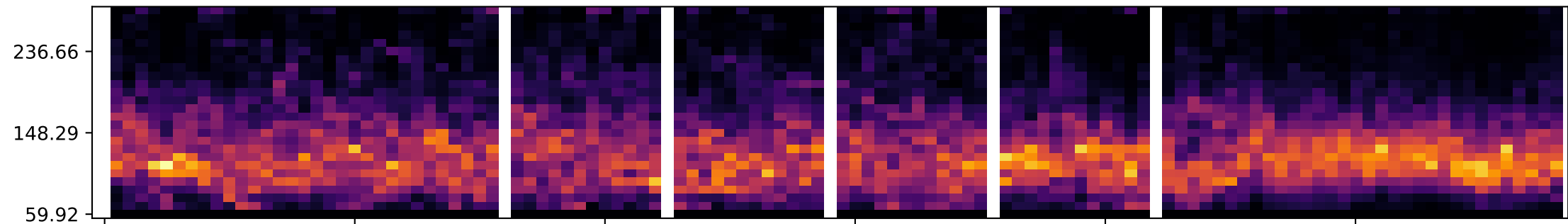
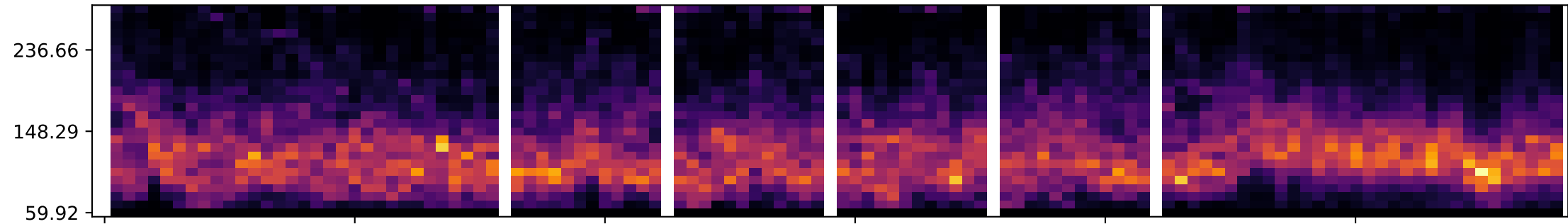
eigen_projection_3



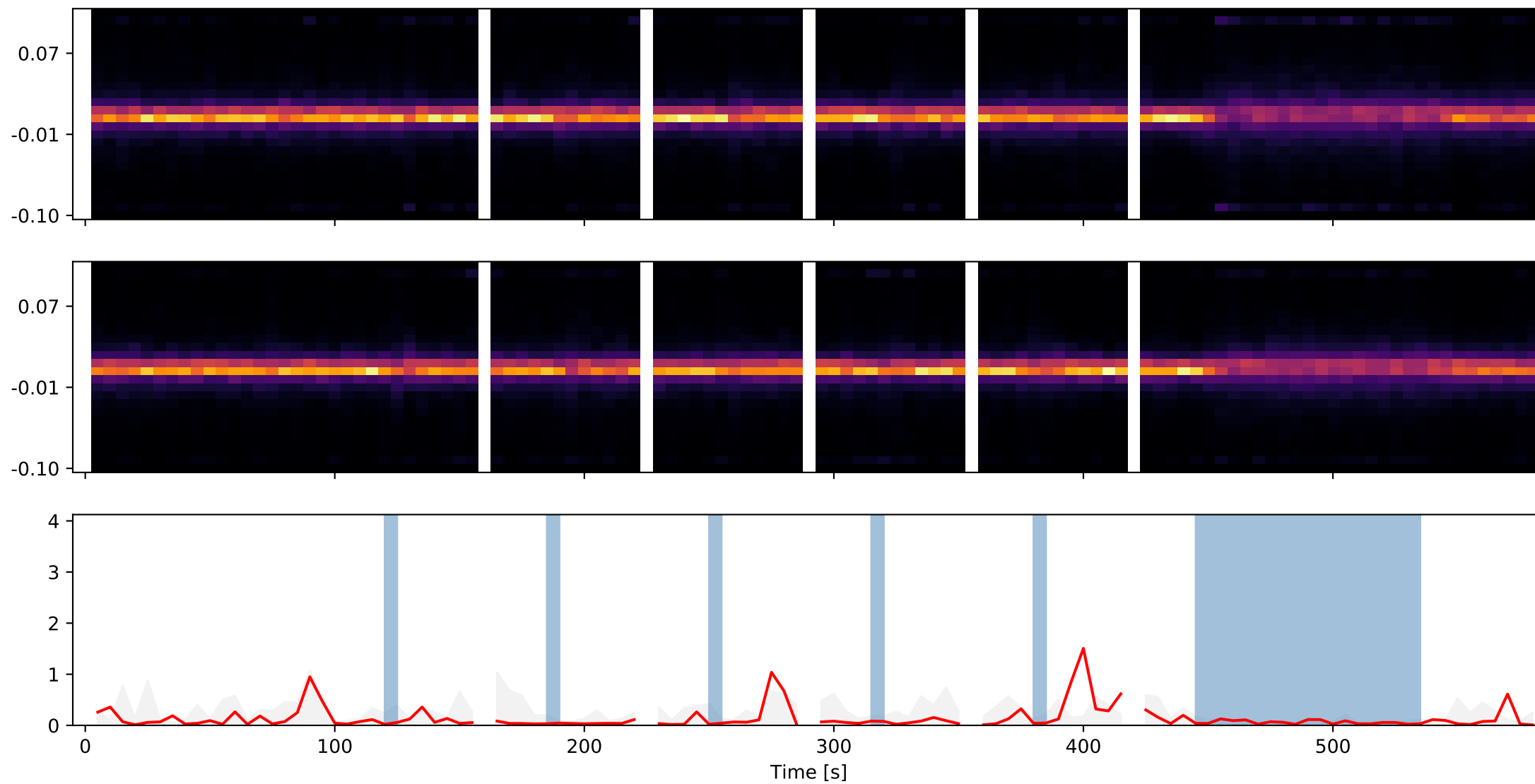
curvature_std_midbody



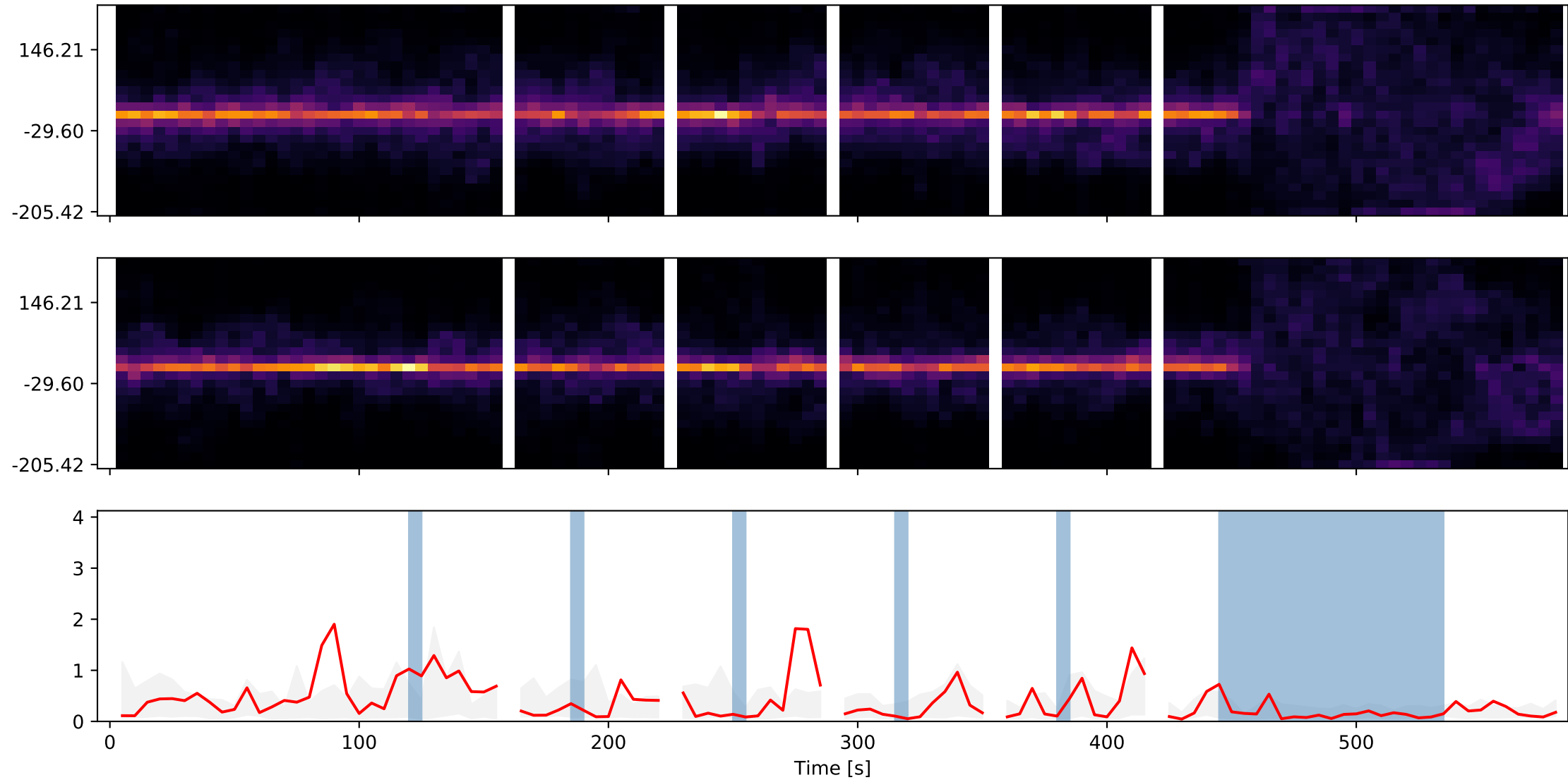
minor_axis



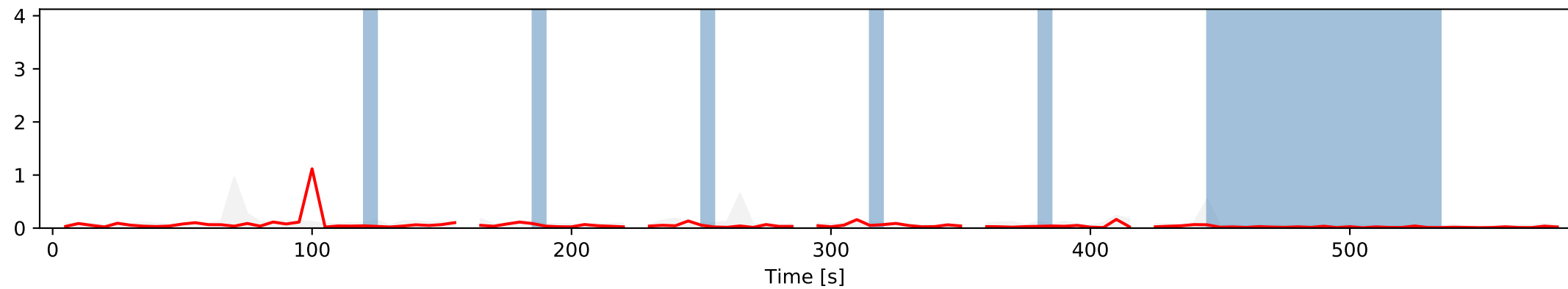
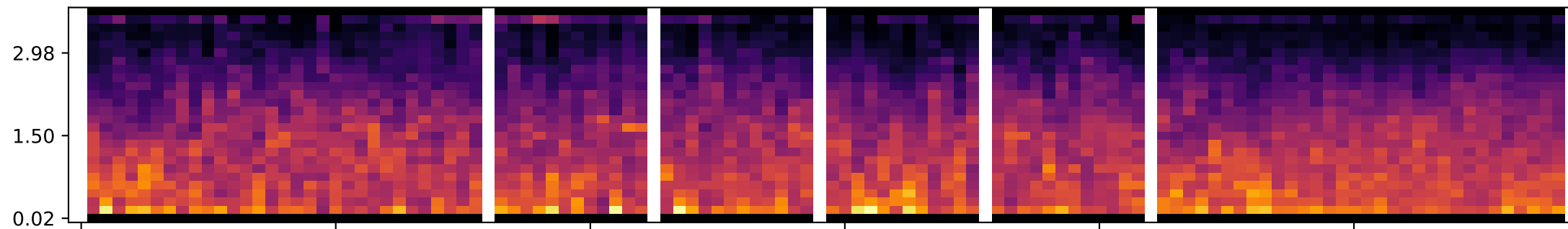
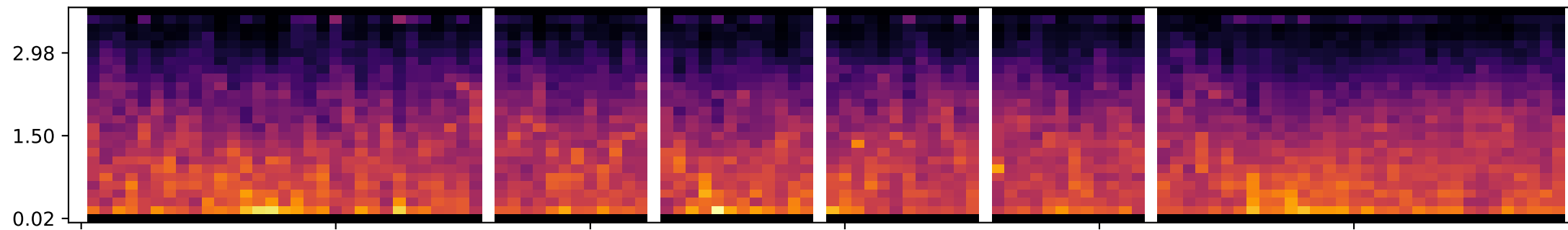
d_quirkiness



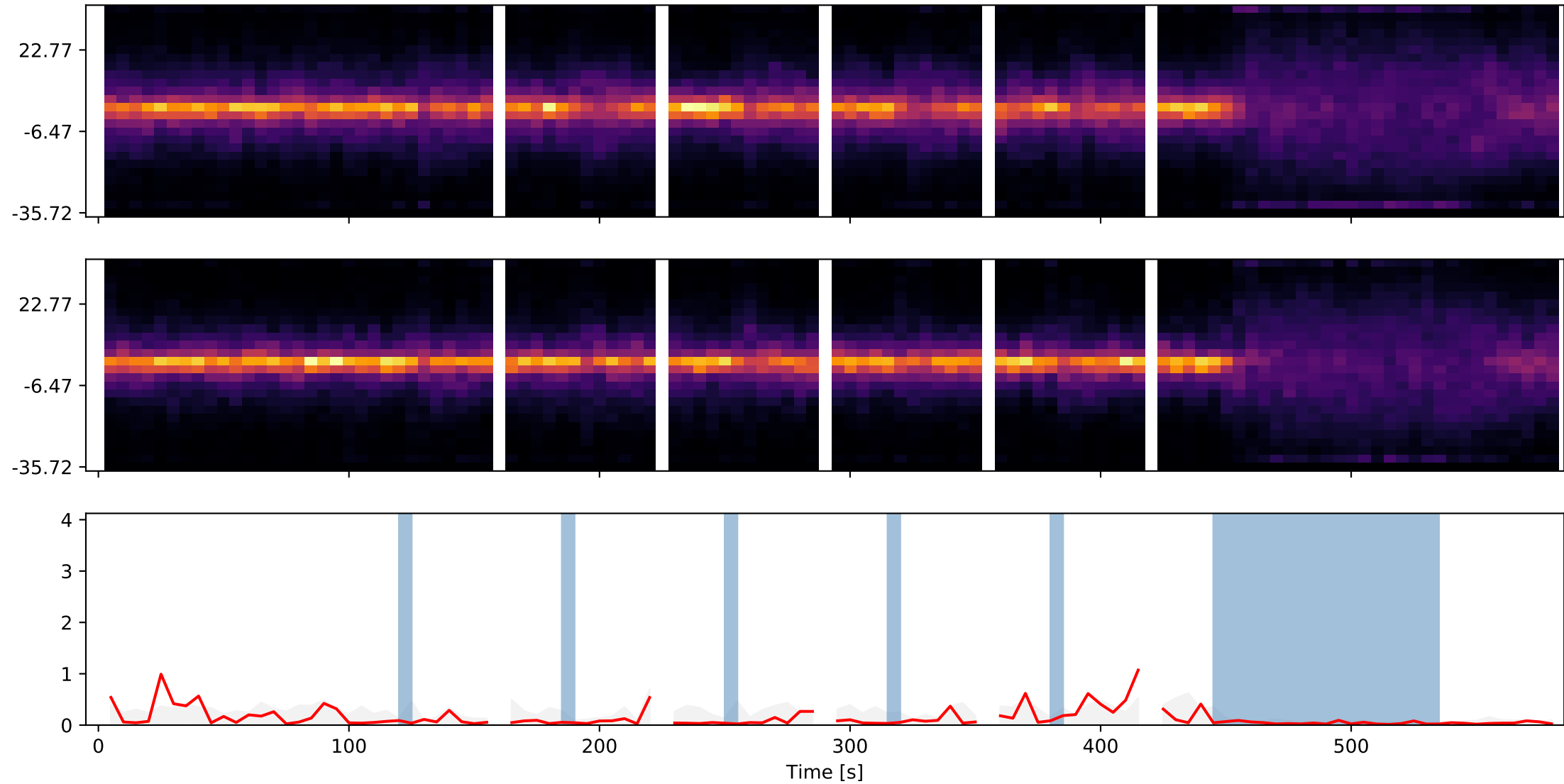
d_dist_from_food_edge



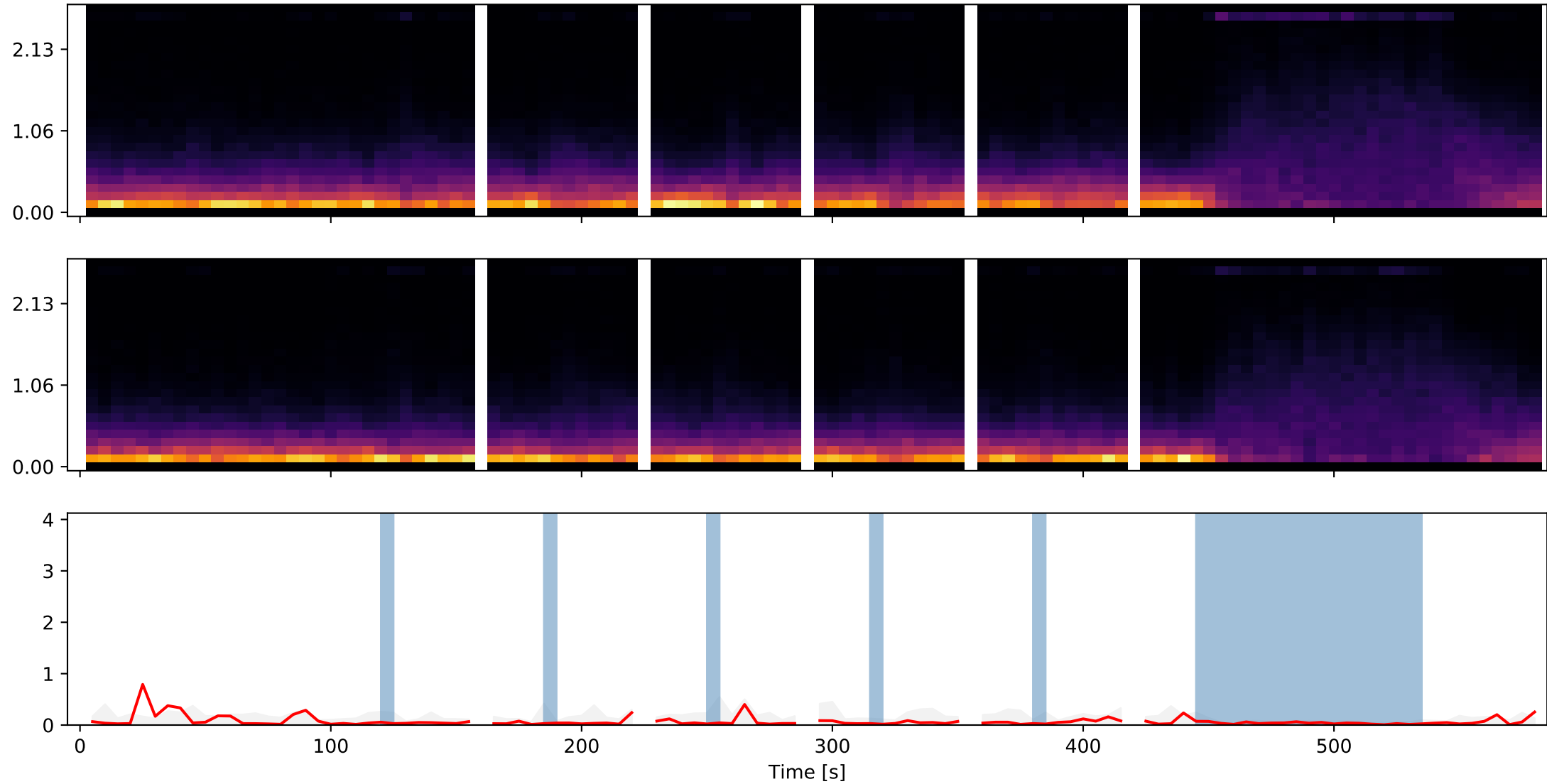
eigen_projection_4



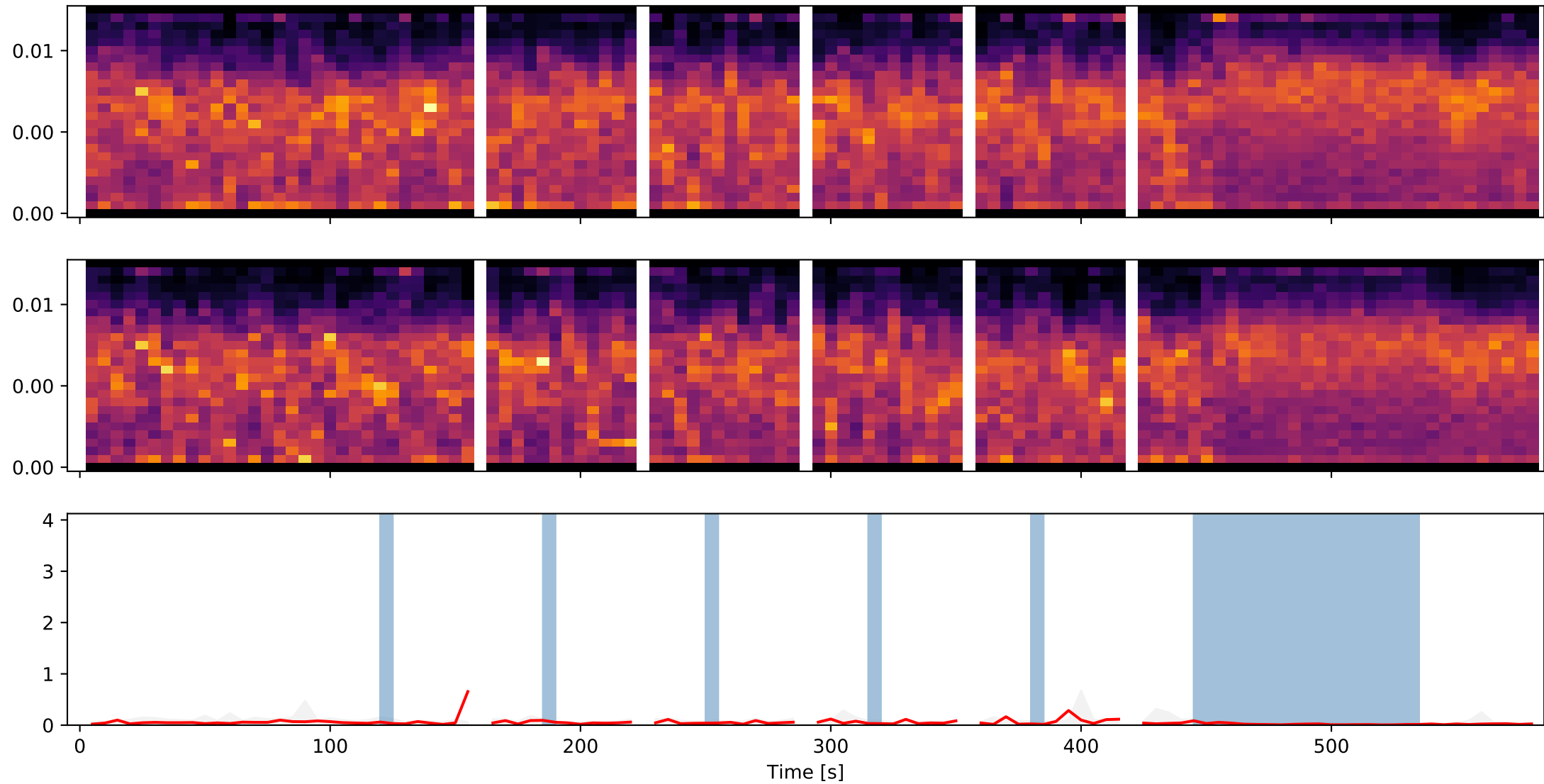
d_orientation_food_edge



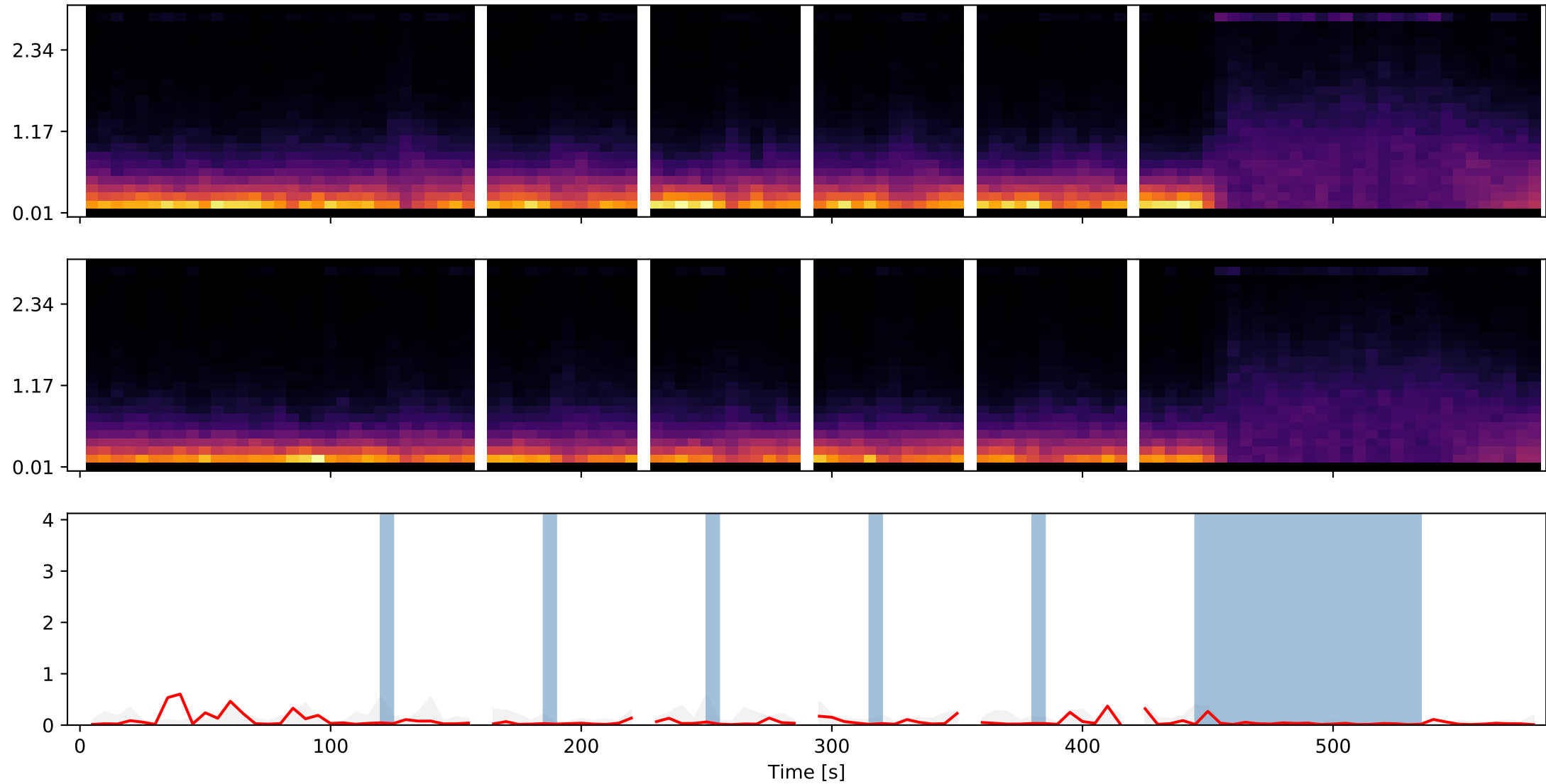
d_angular_velocity



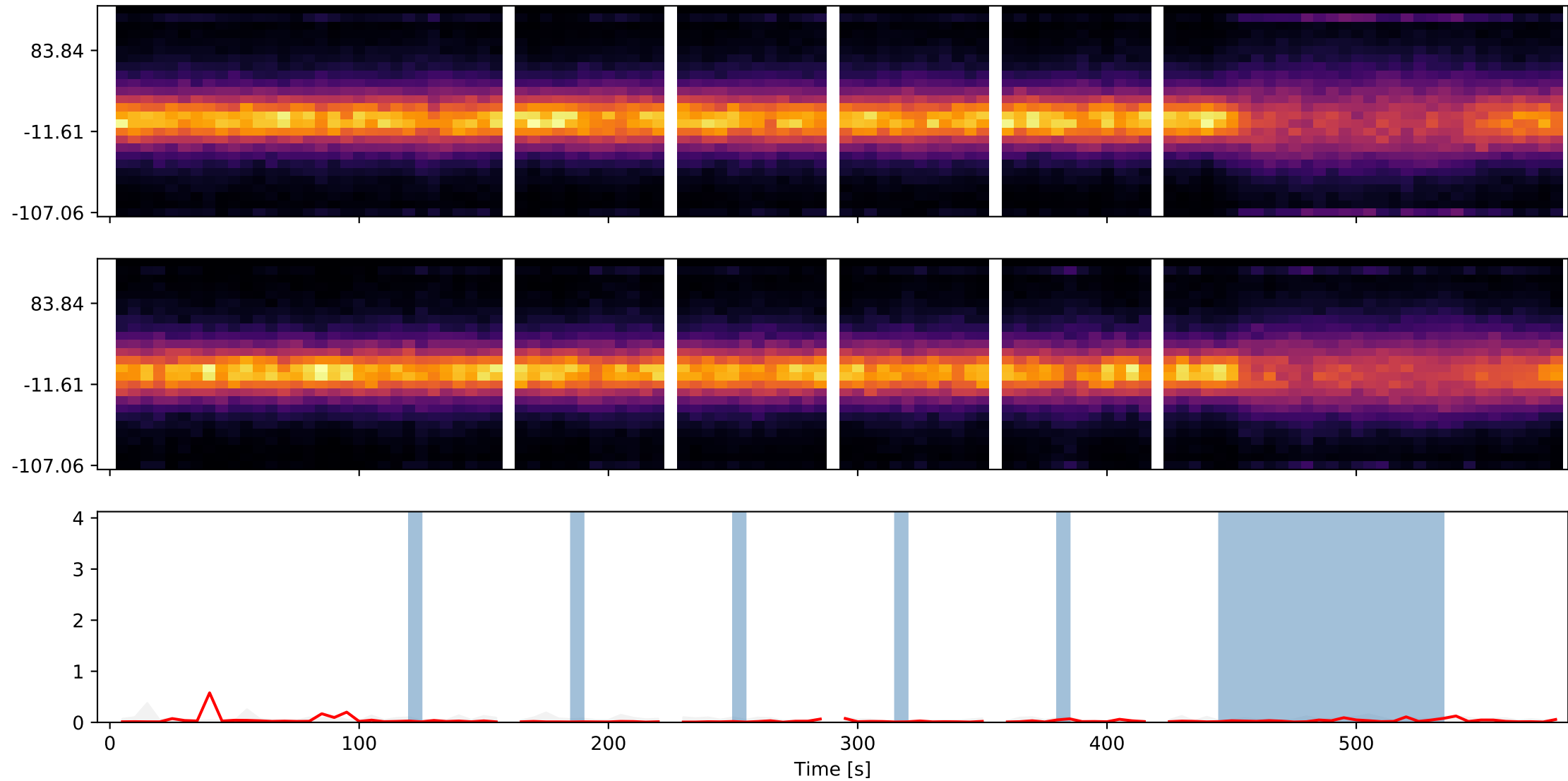
curvature_mean_neck



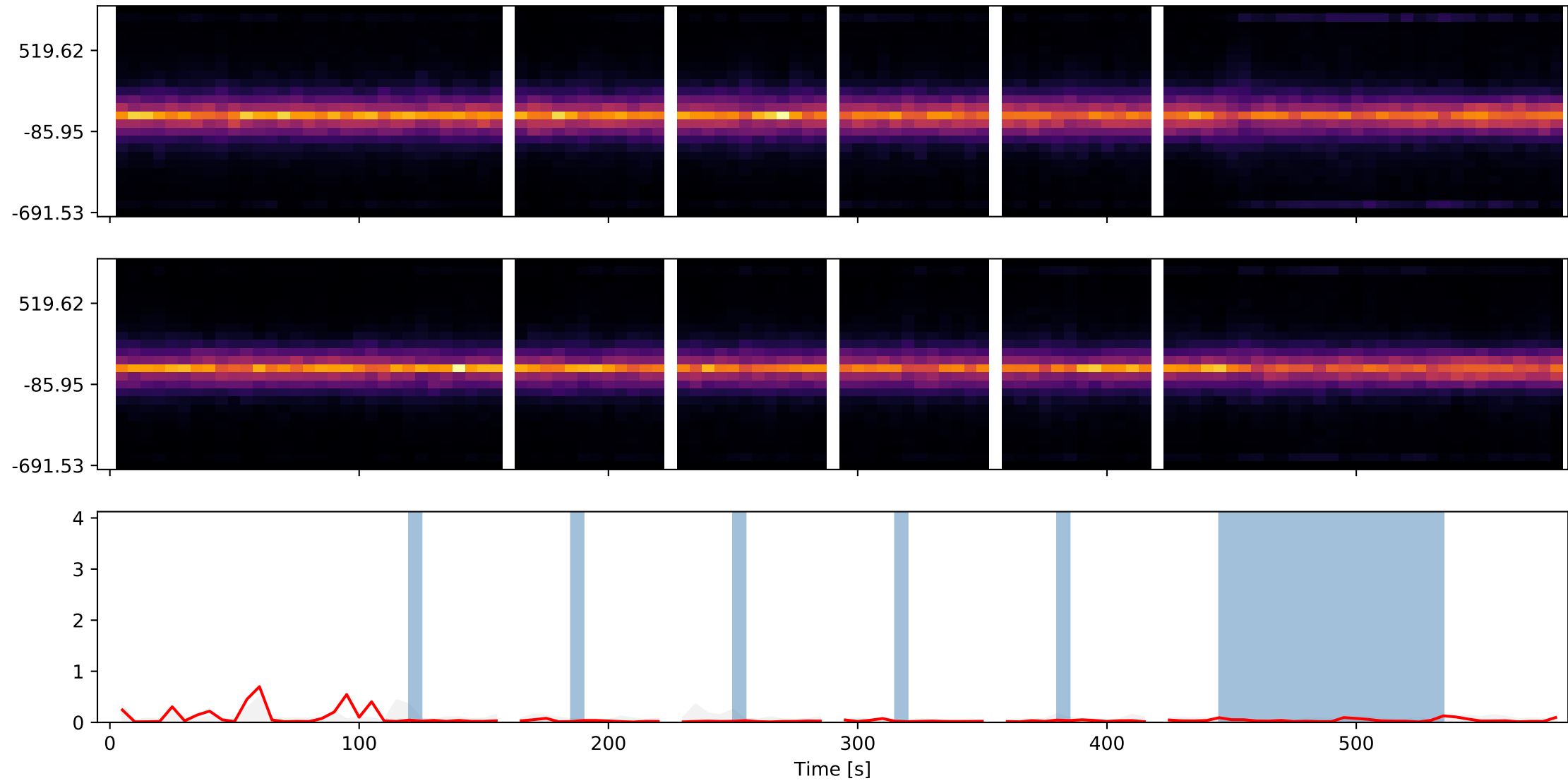
d_relative_to_body_angular_velocity_tail_tip



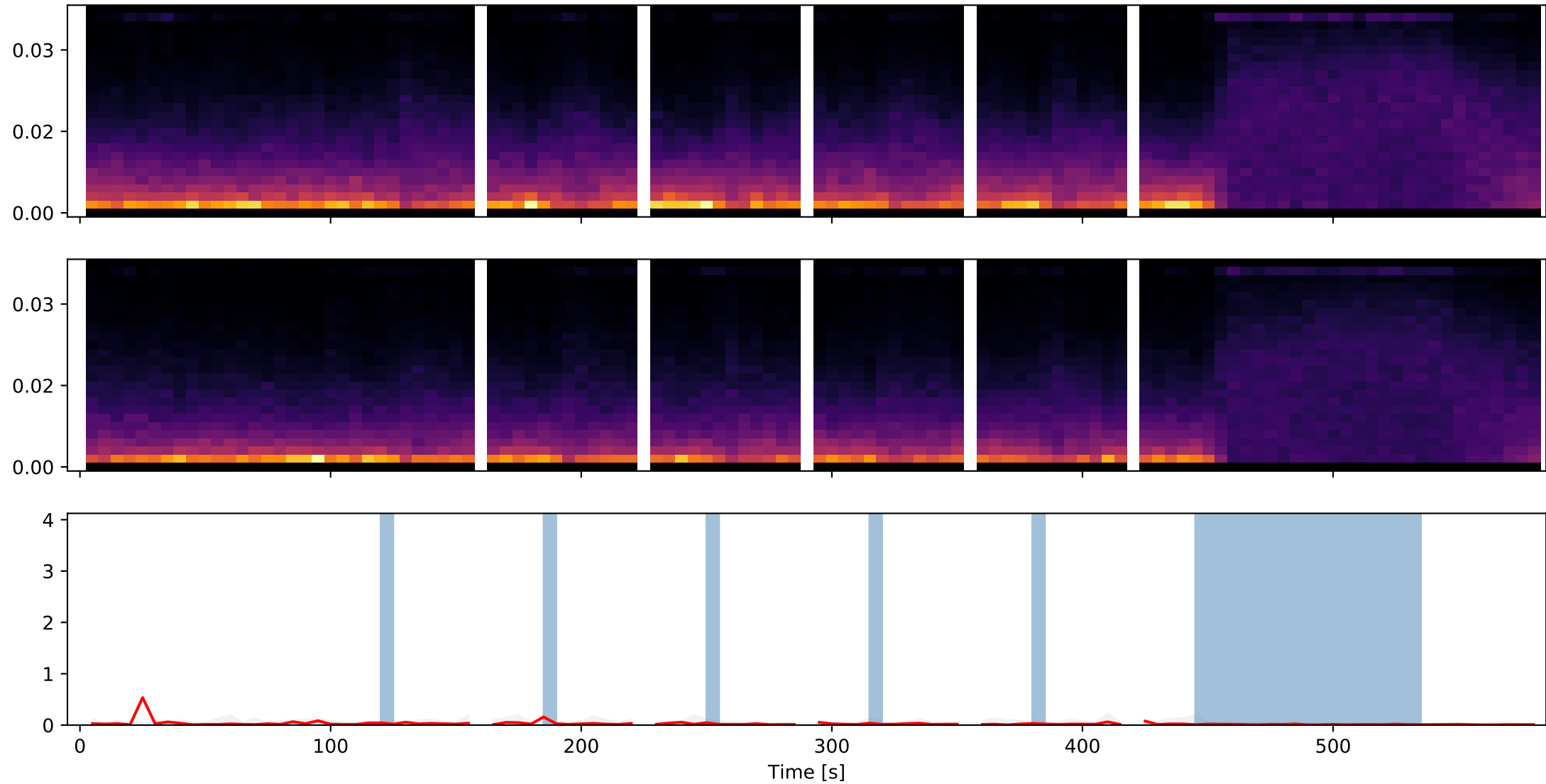
d_relative_to_tail_base_radial_velocity_tail_tip



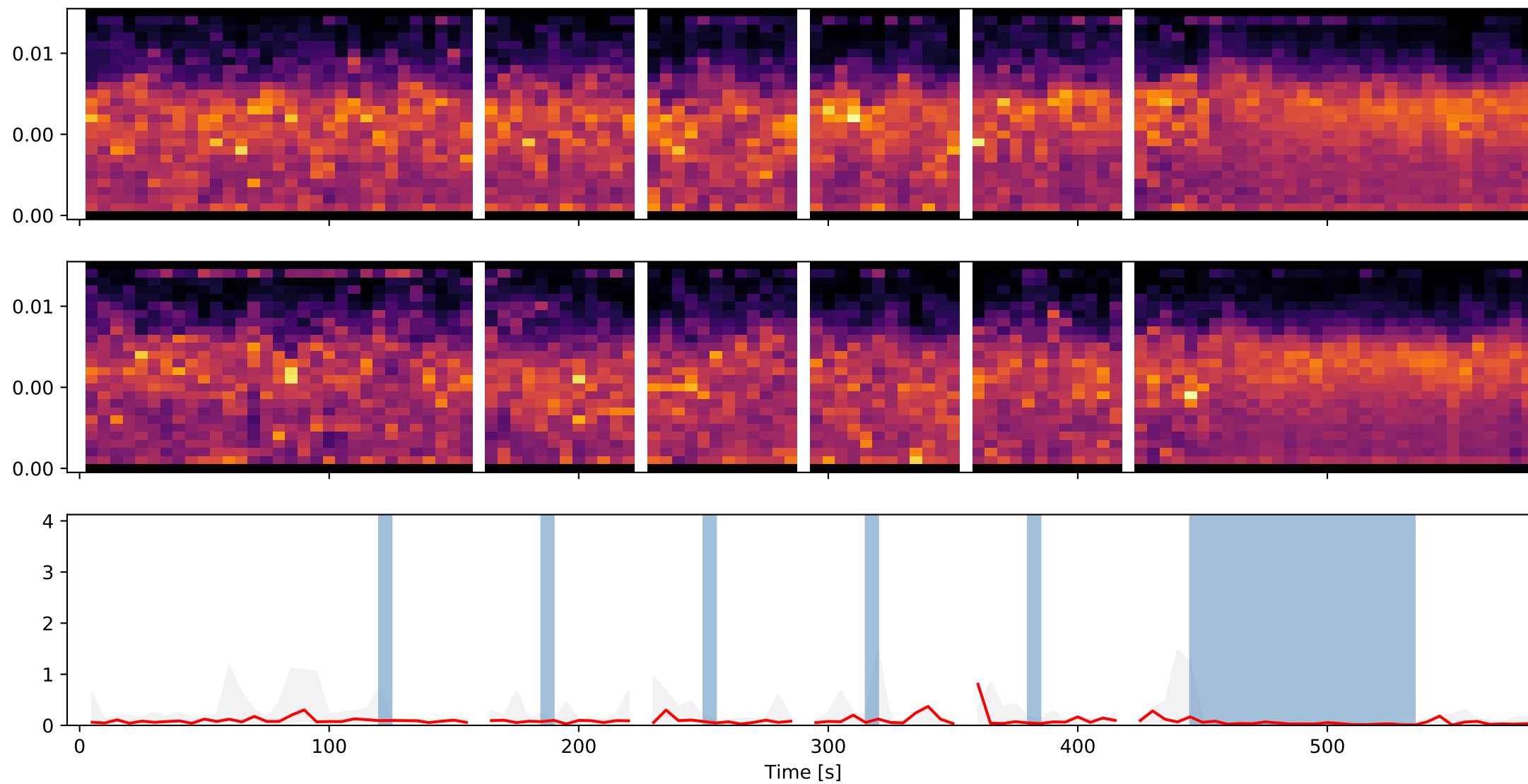
d_speed_tail_tip



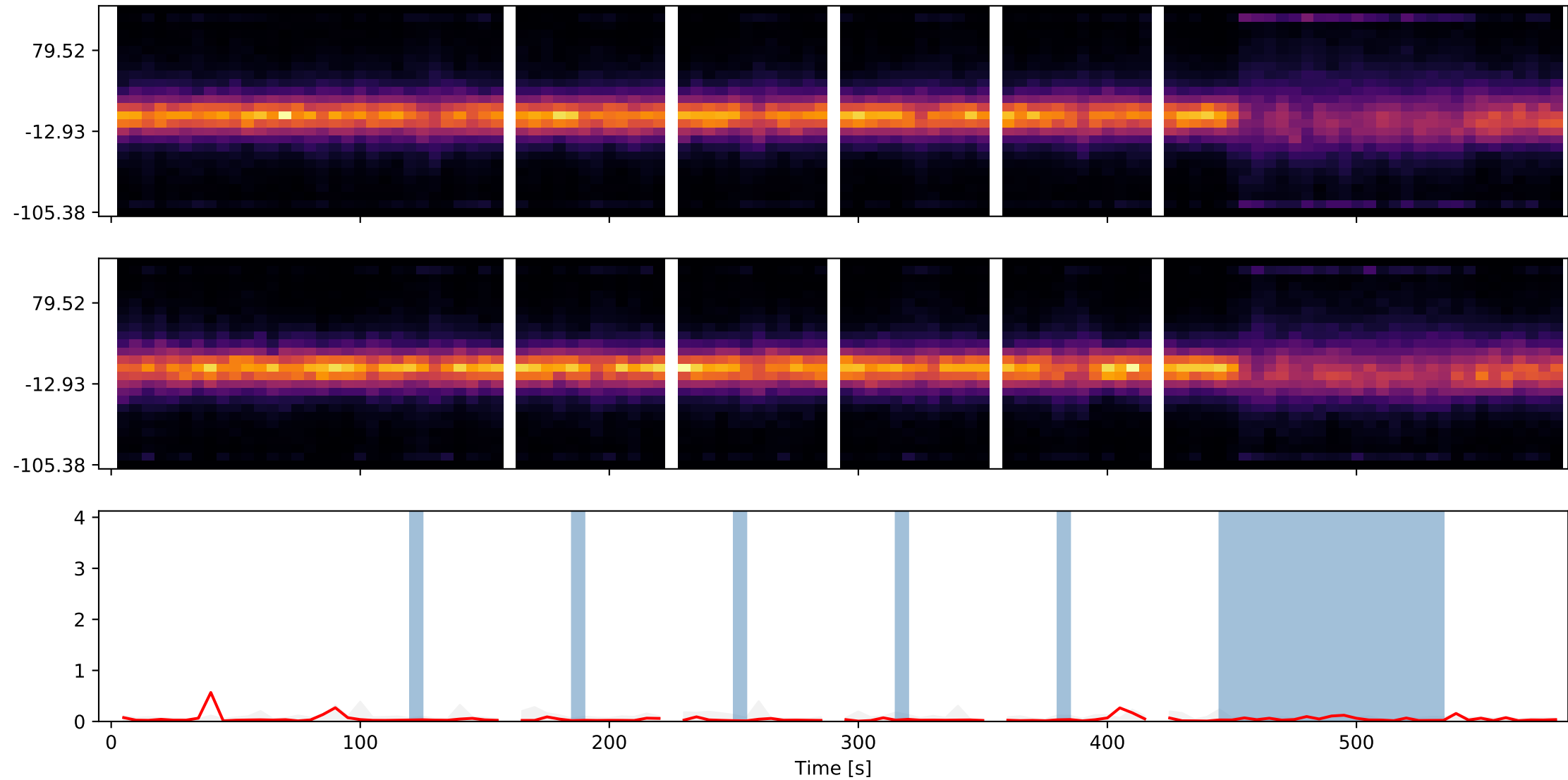
d_curvature_tail



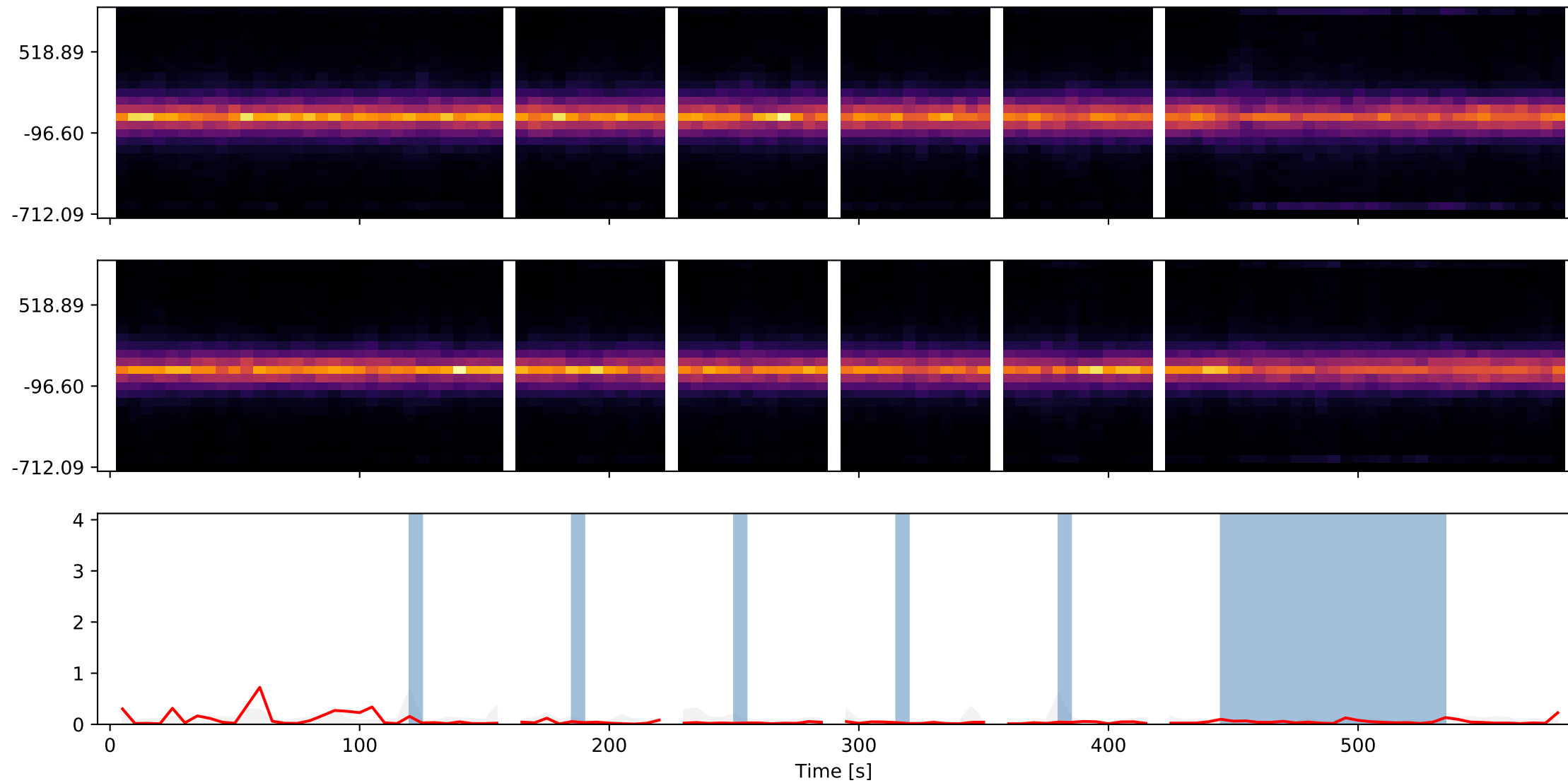
curvature_mean_hips



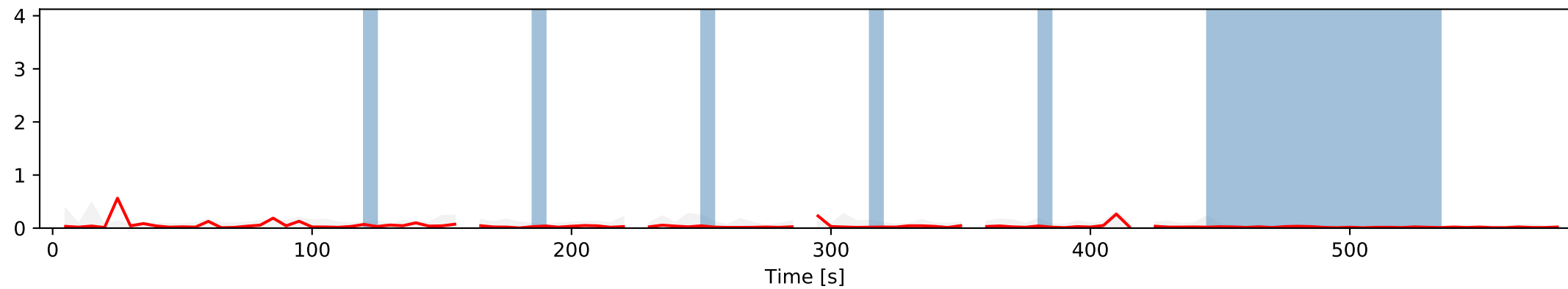
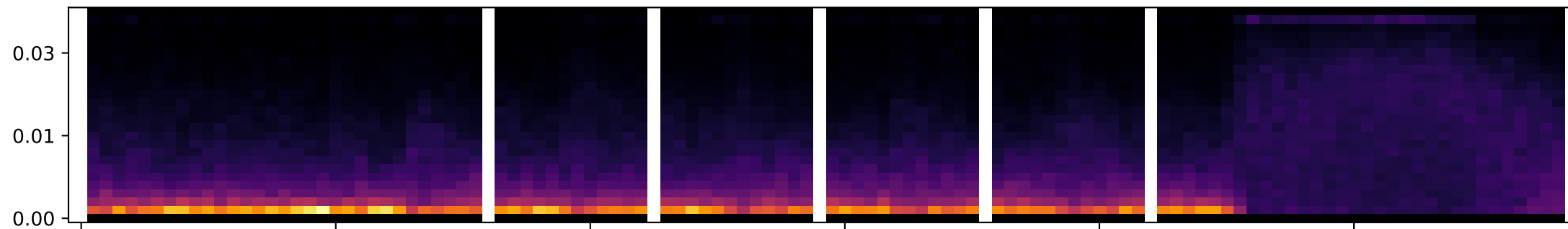
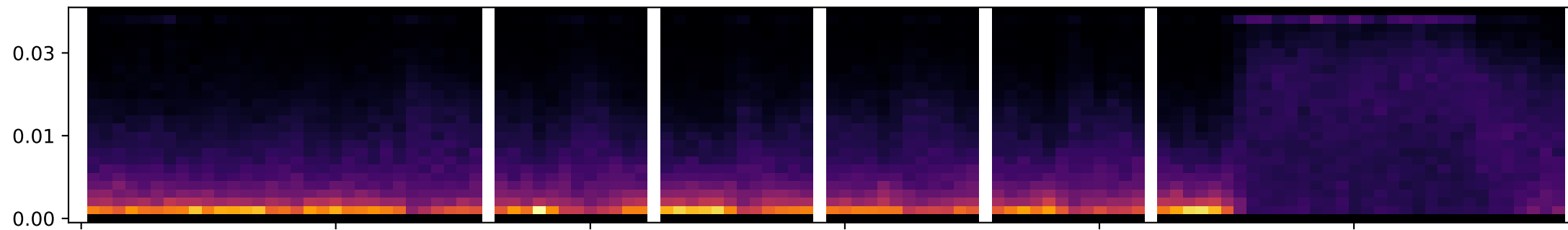
relative_to_body_radial_velocity_tail_tip



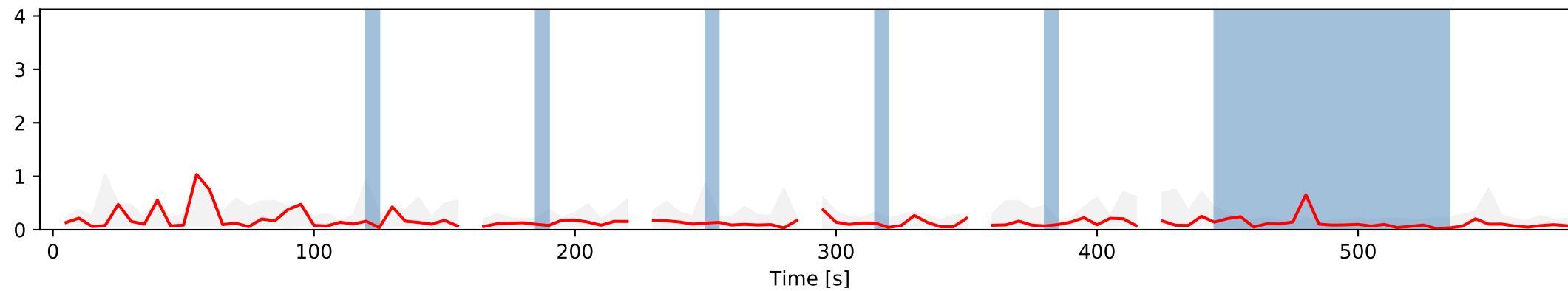
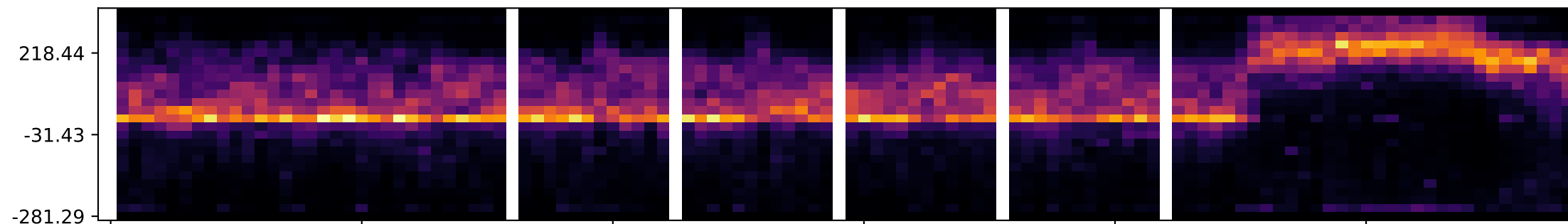
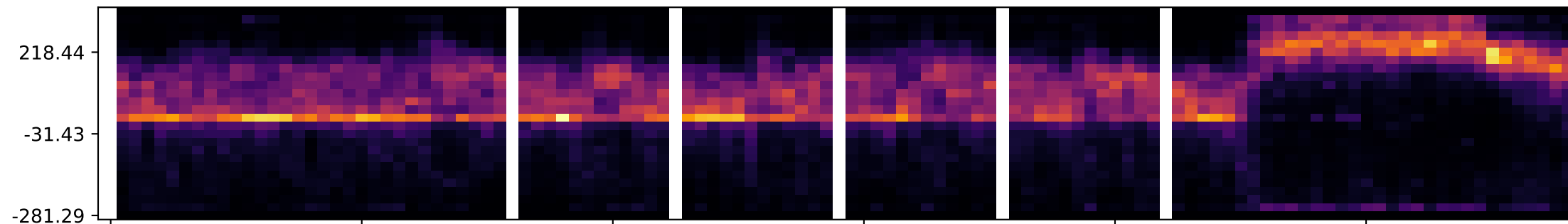
d_speed_hips



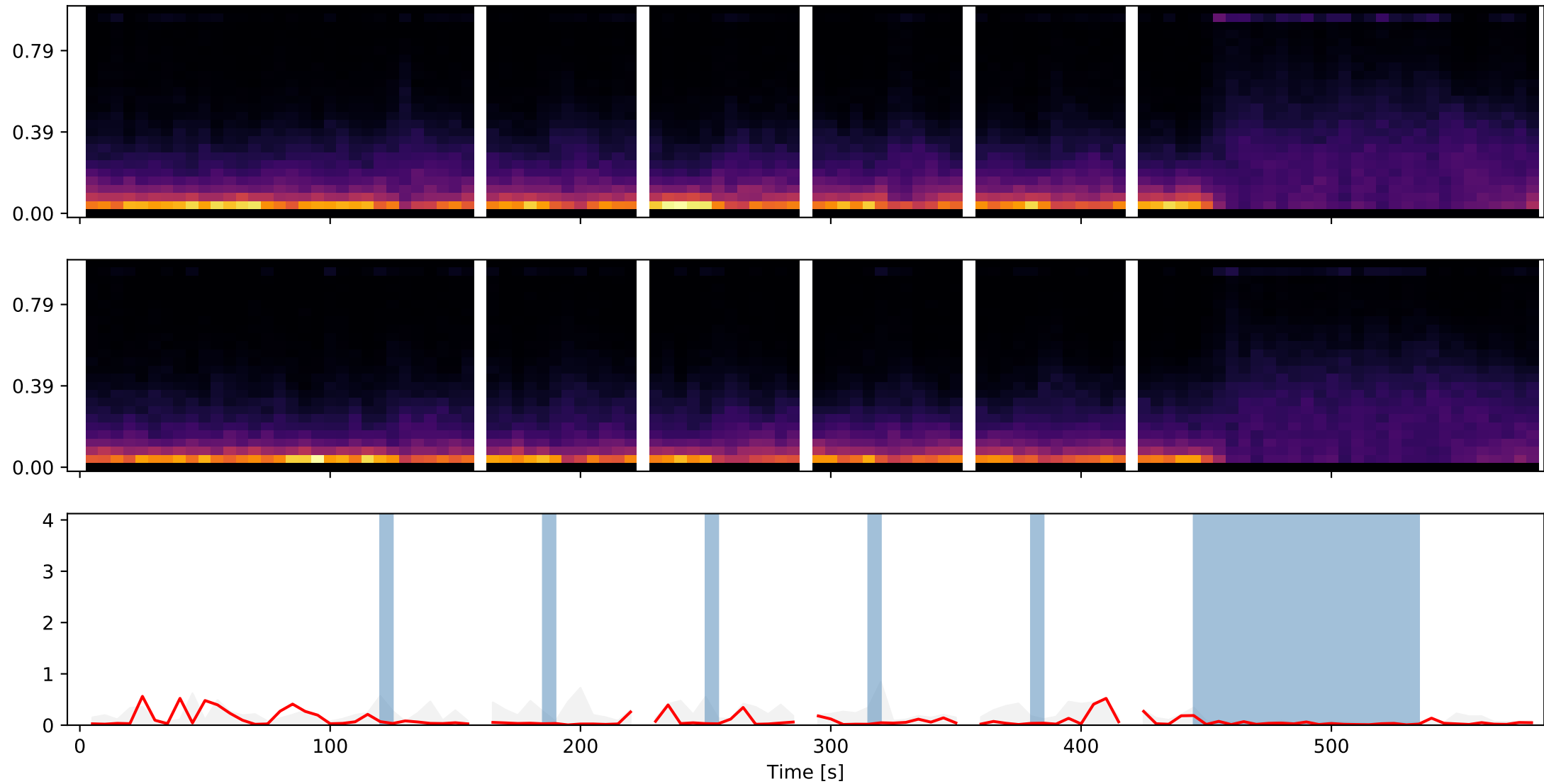
d_curvature_mean_tail



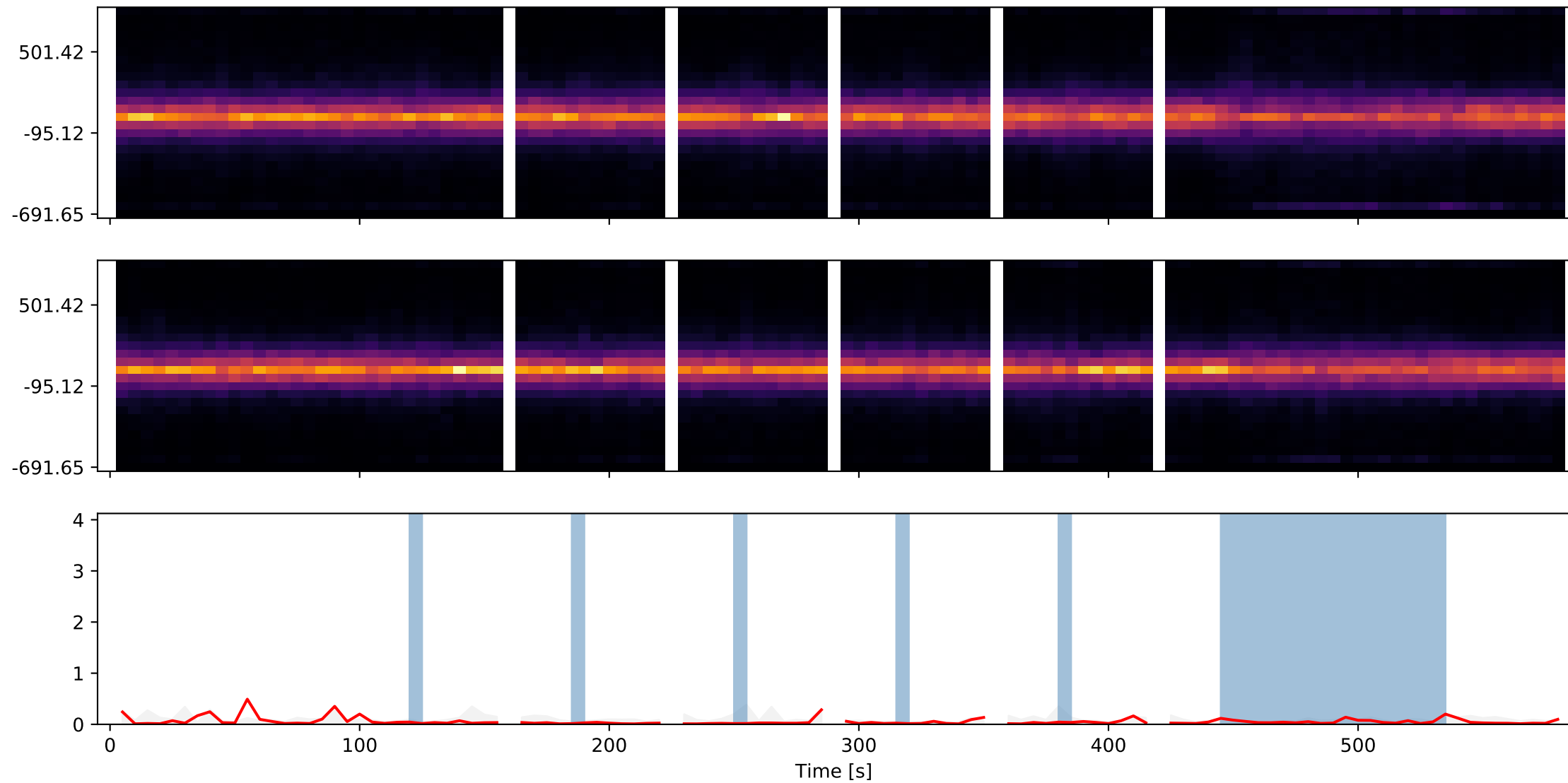
speed_tail_tip



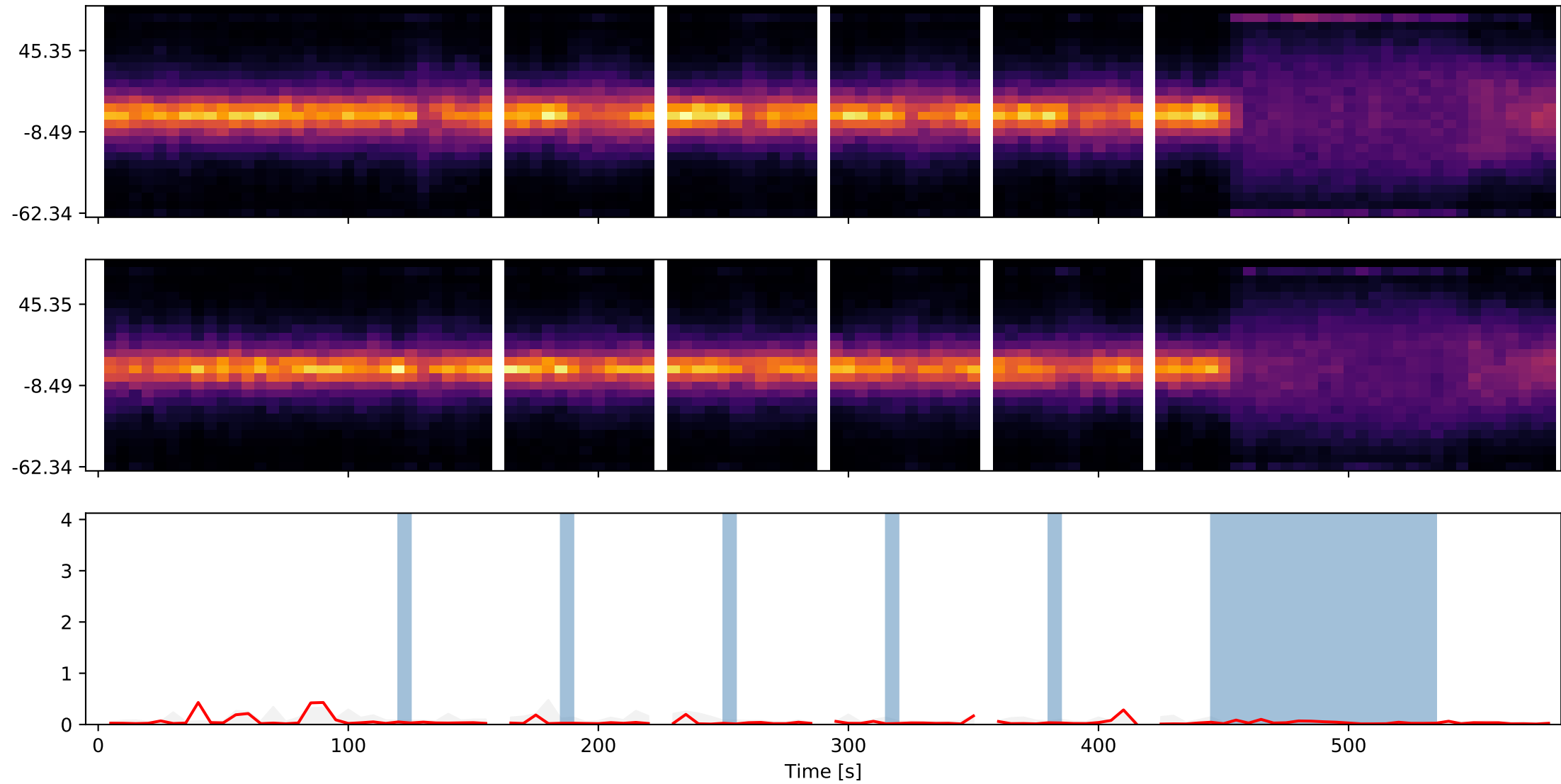
relative_to_body_angular_velocity_tail_tip



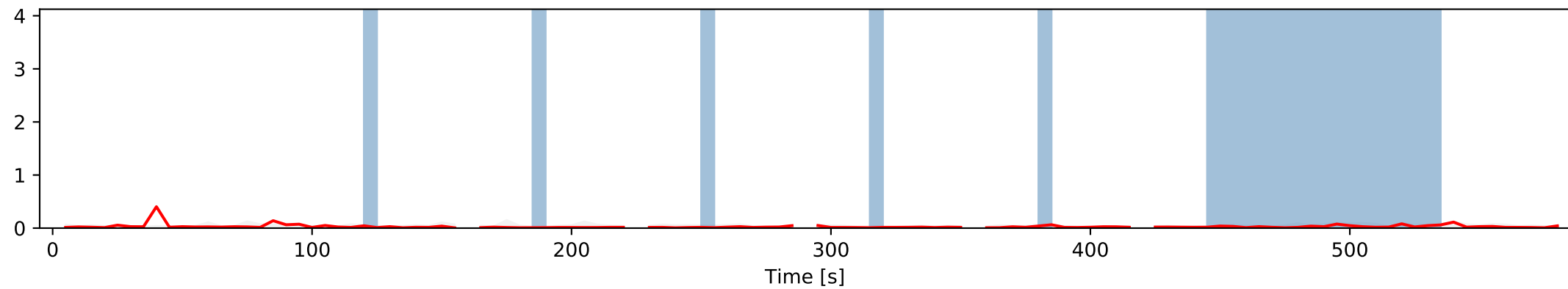
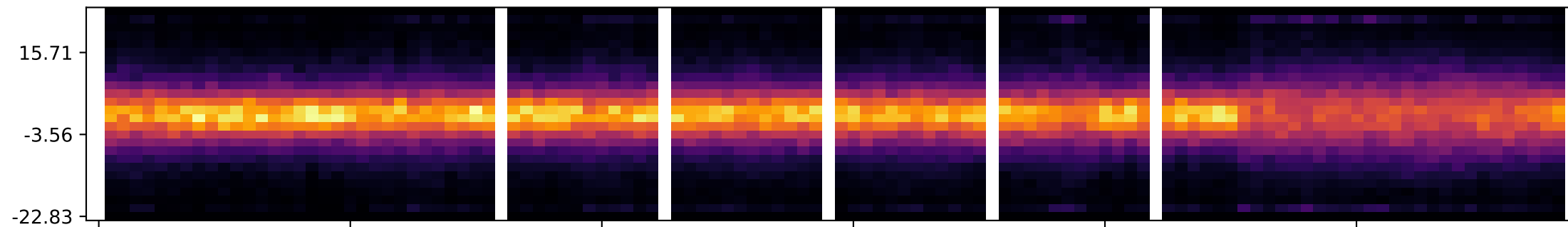
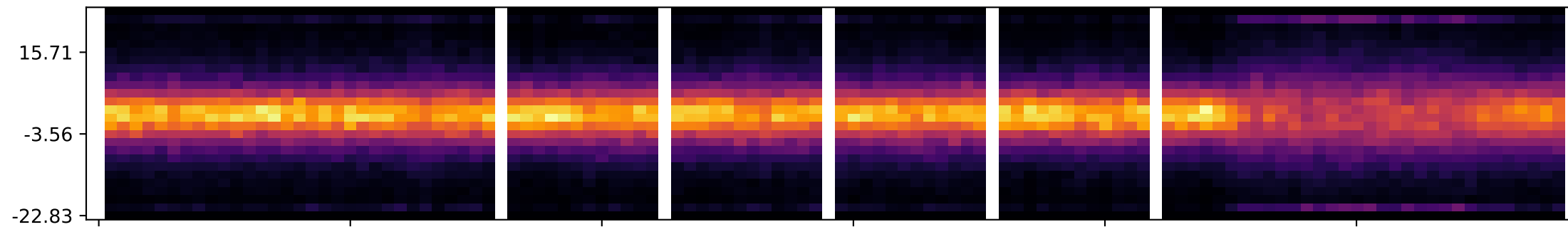
d_speed_midbody



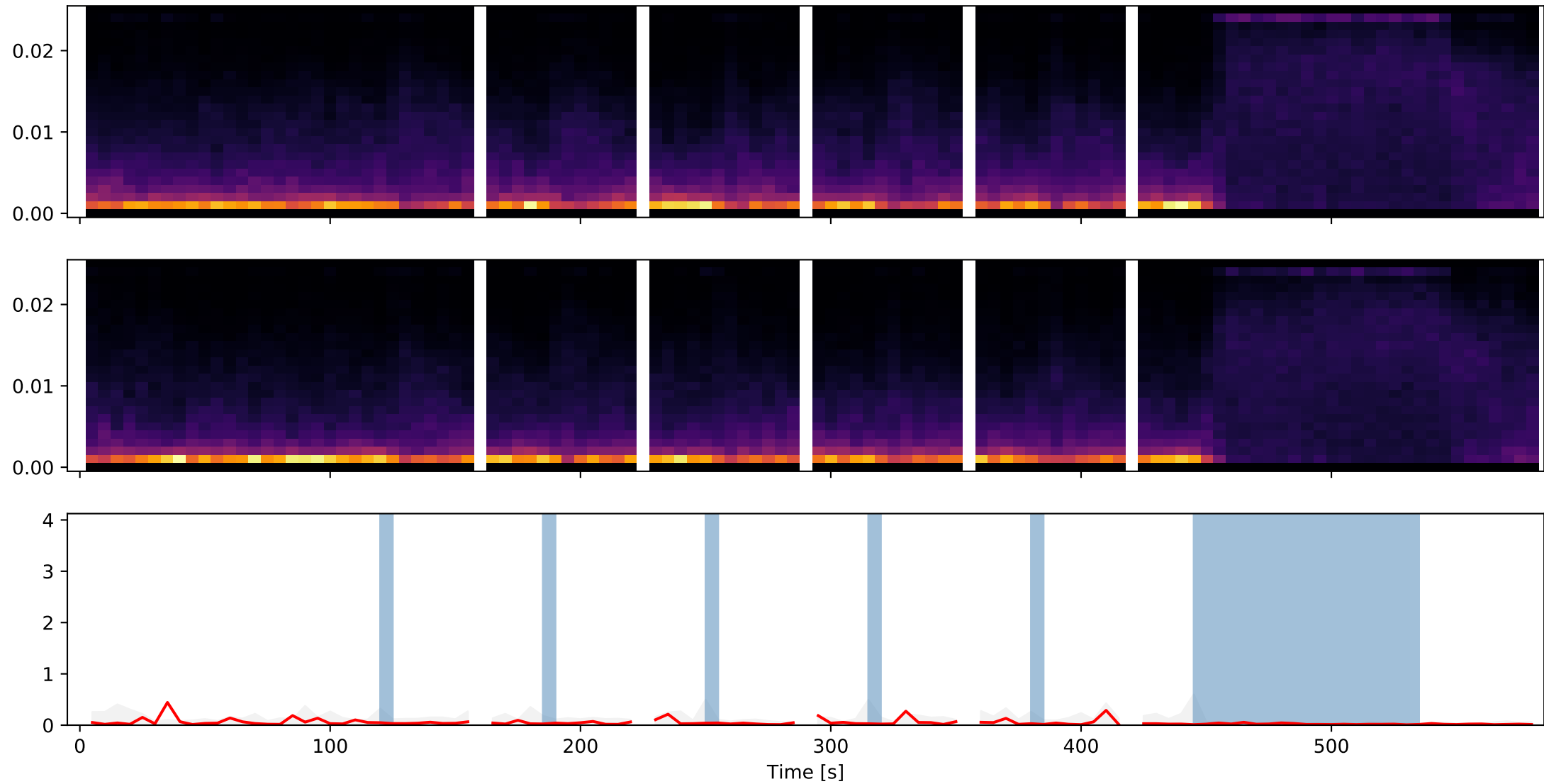
relative_to_hips_radial_velocity_tail_tip



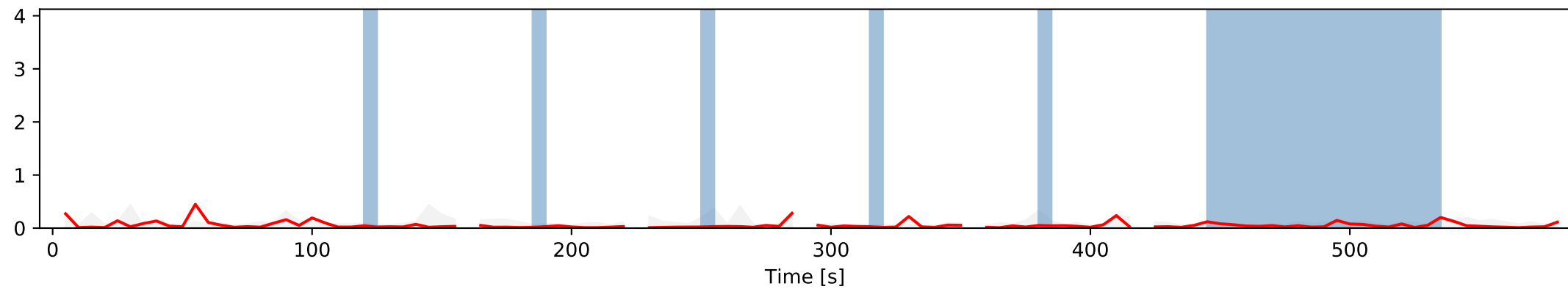
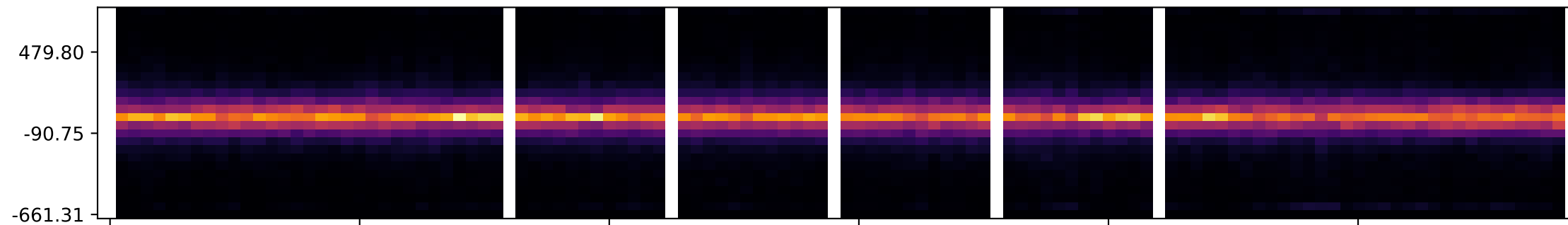
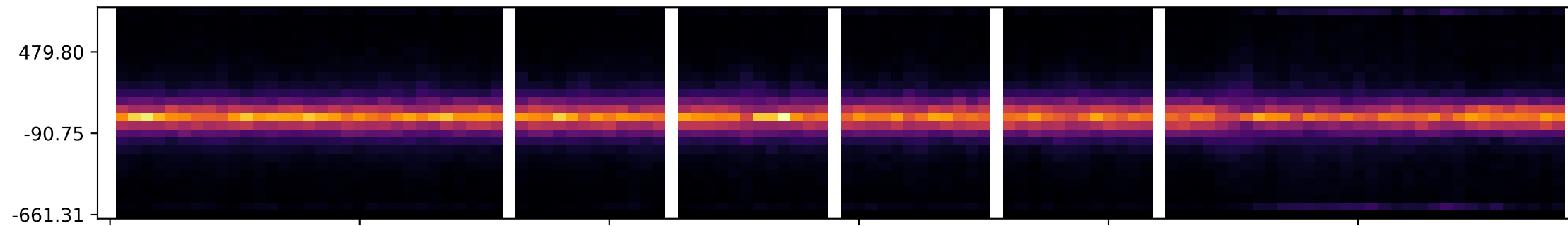
relative_to_tail_base_radial_velocity_tail_tip



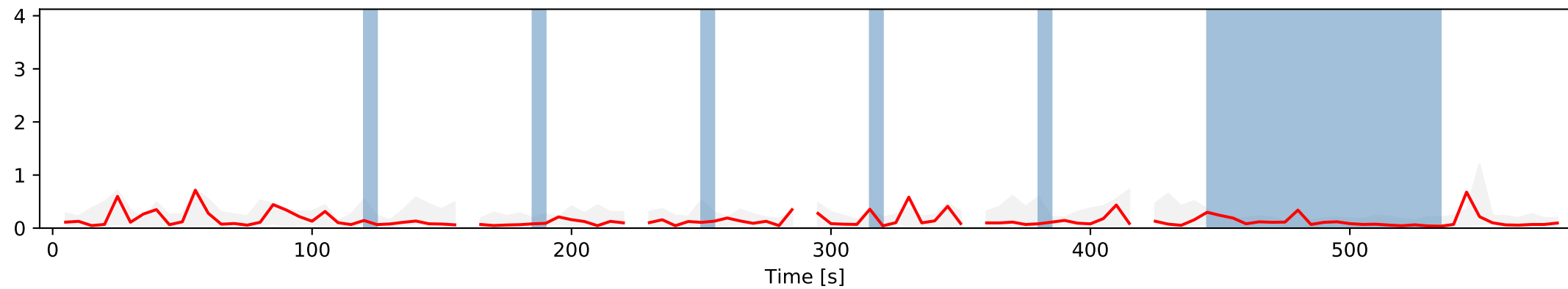
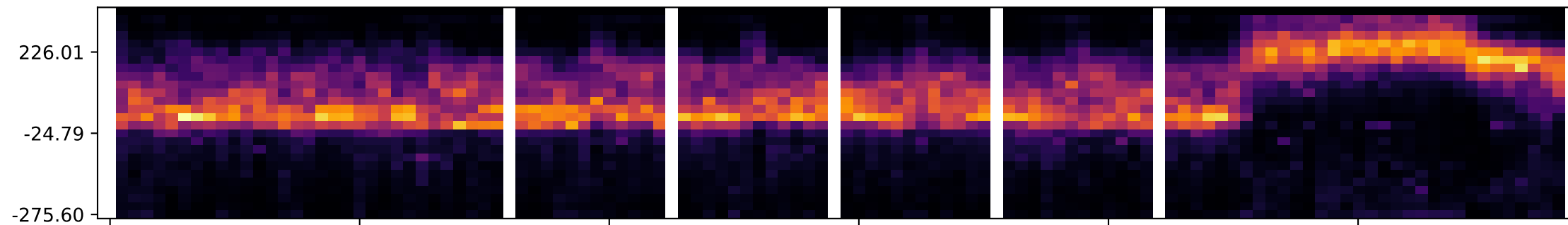
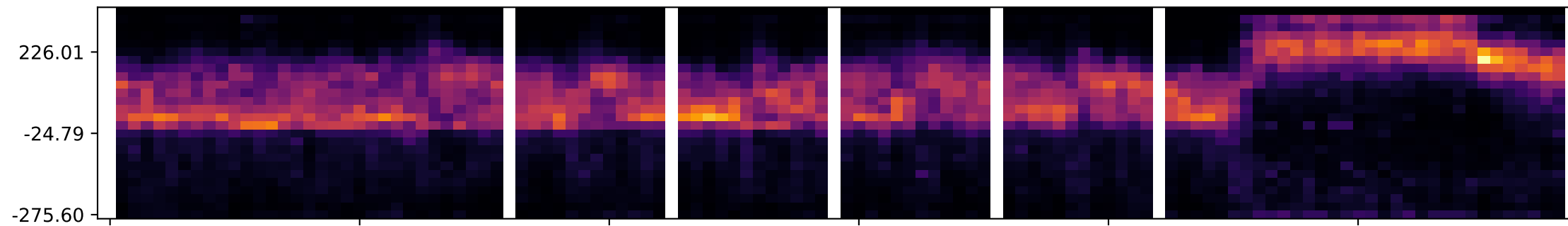
d_curvature_mean_hips



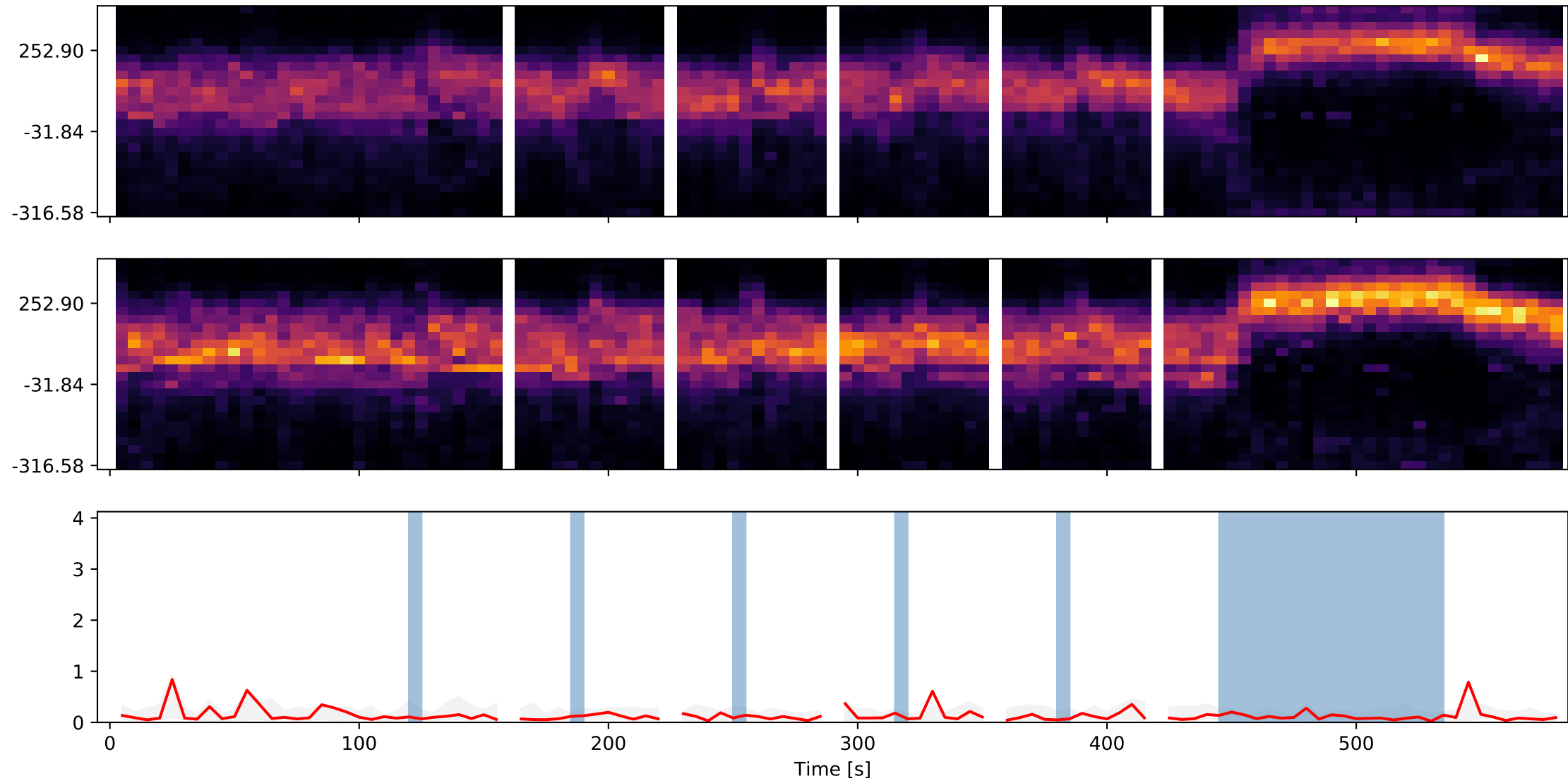
d_speed



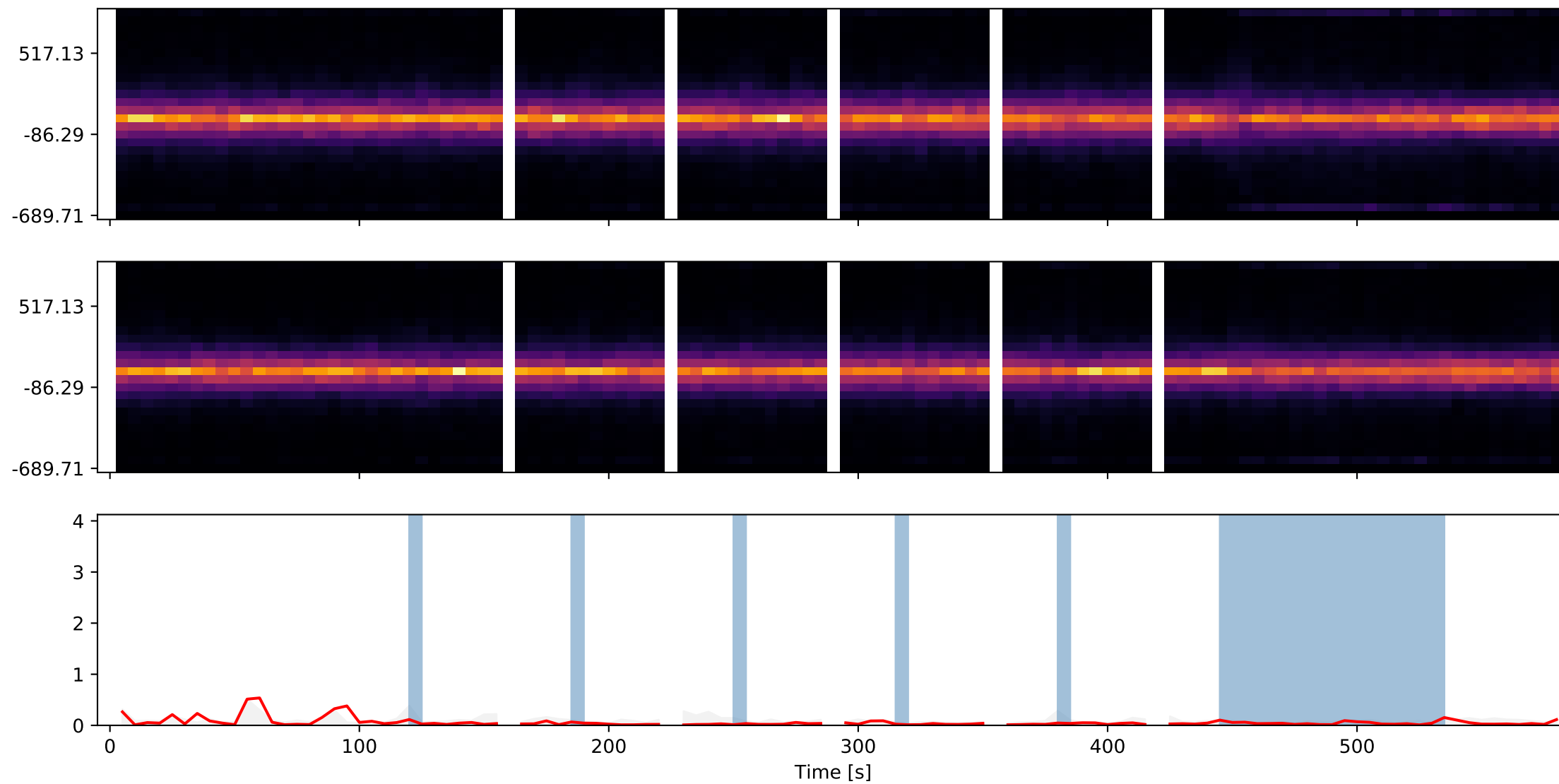
speed_neck



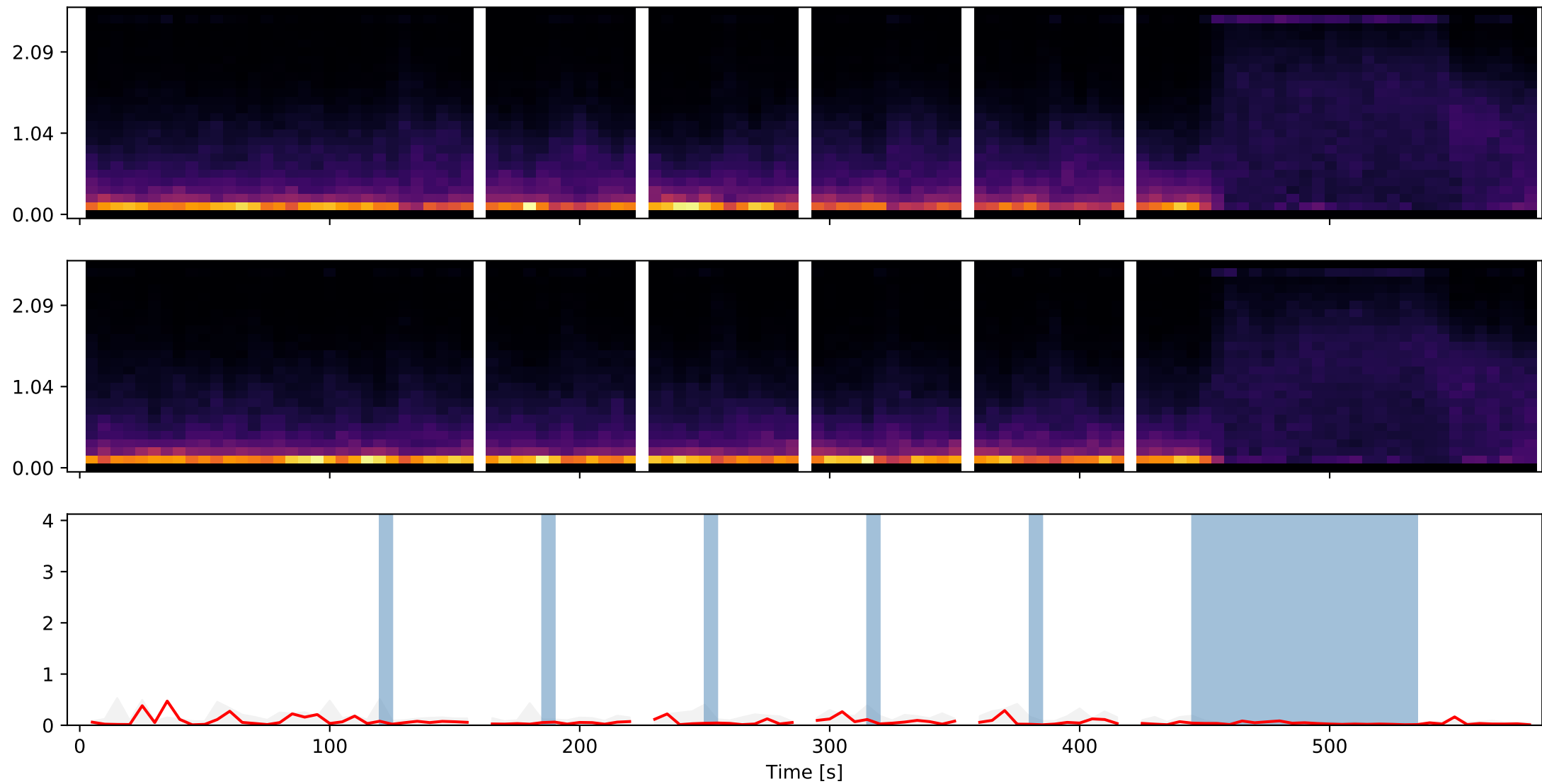
speed_head_tip



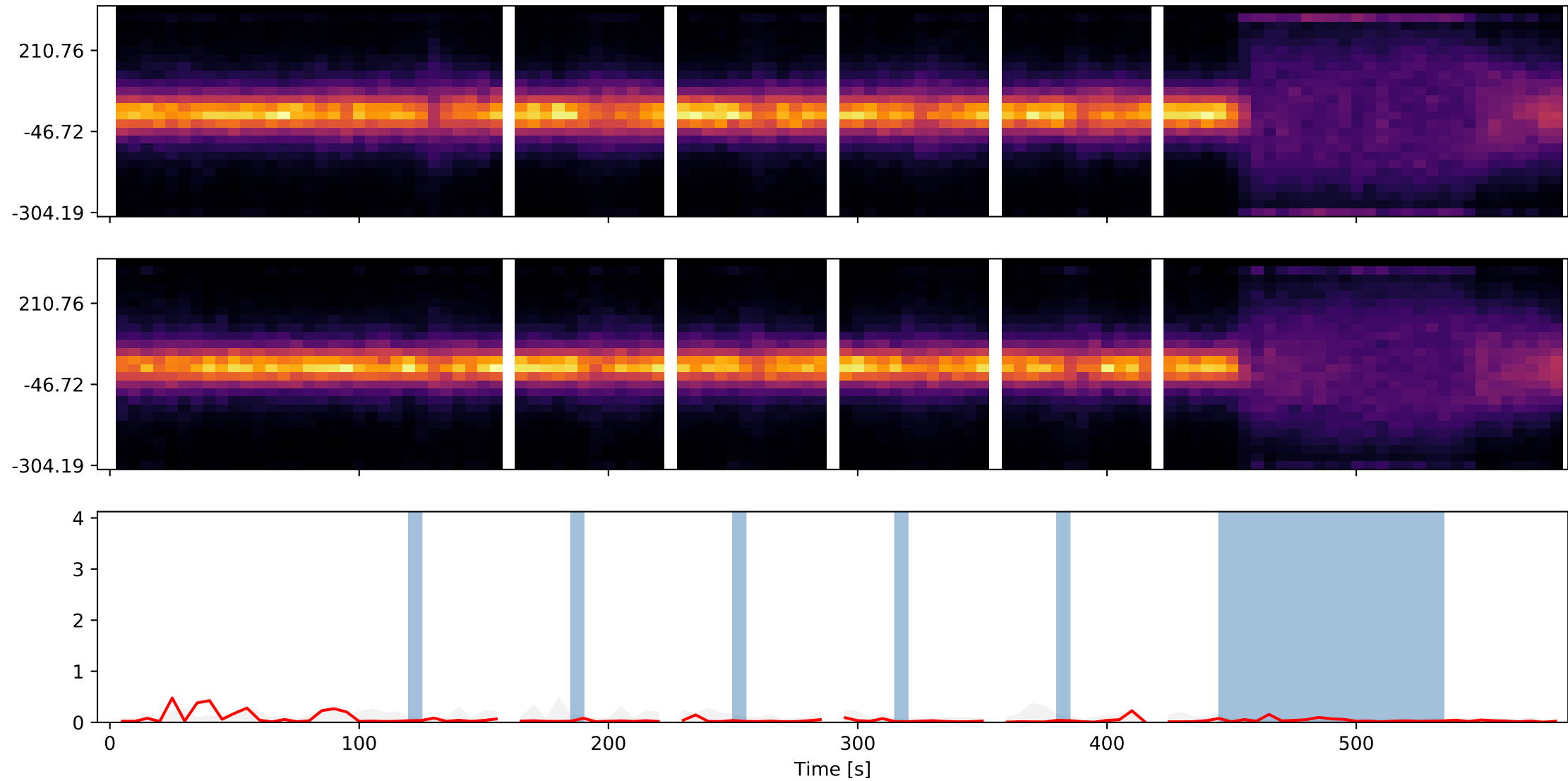
d_speed_tail_base



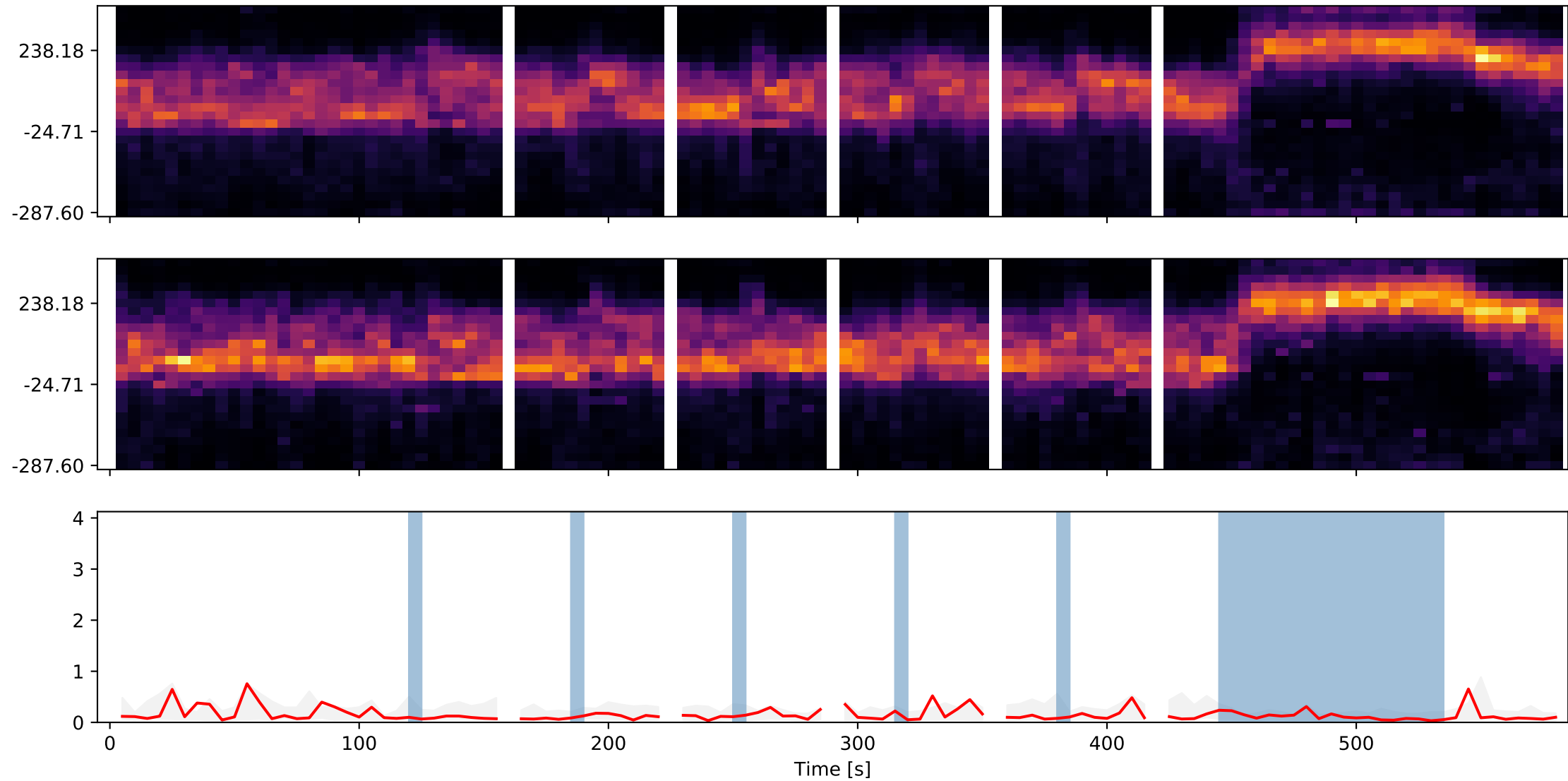
angular_velocity_hips



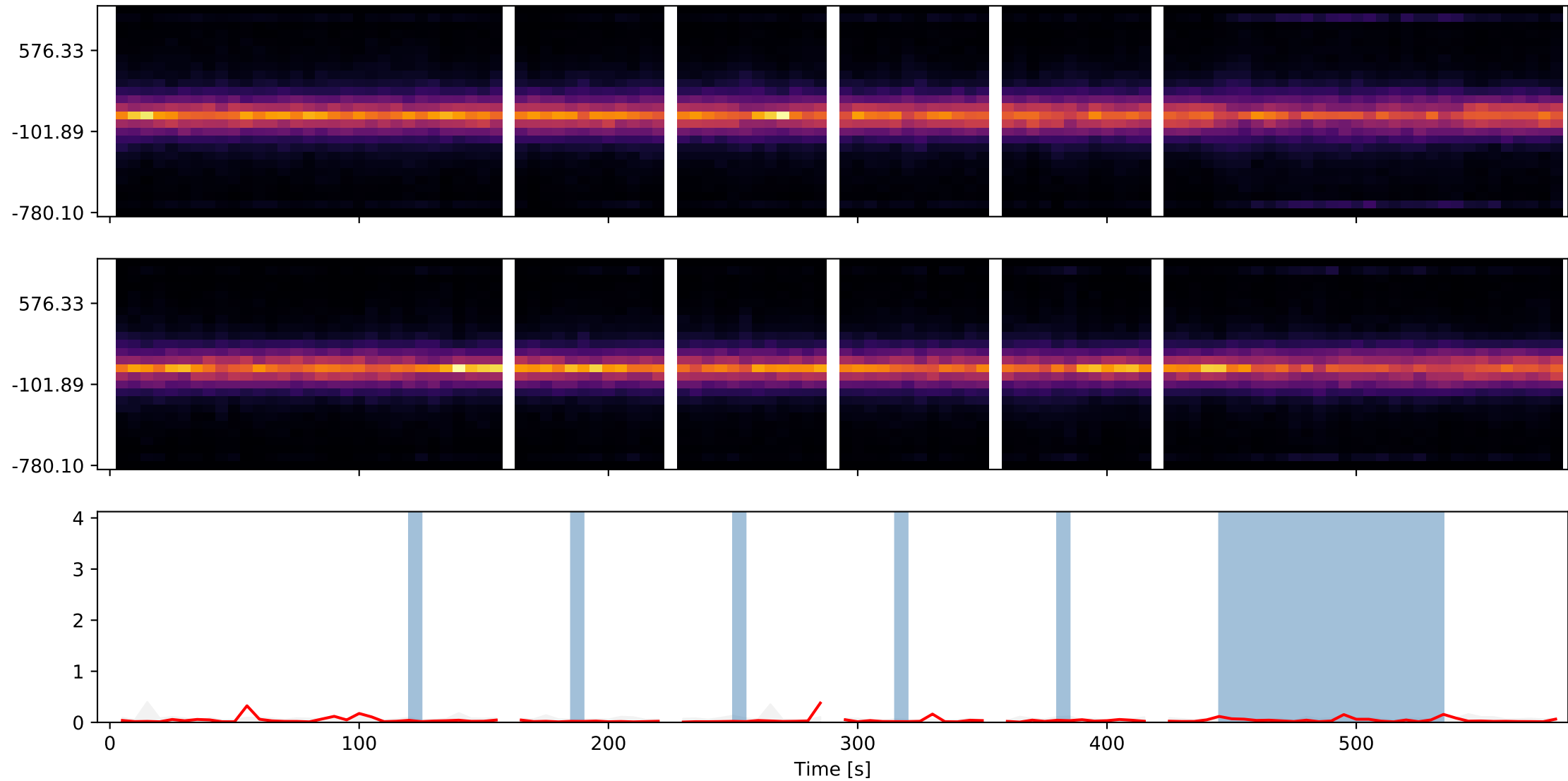
d_relative_to_hips_radial_velocity_tail_tip



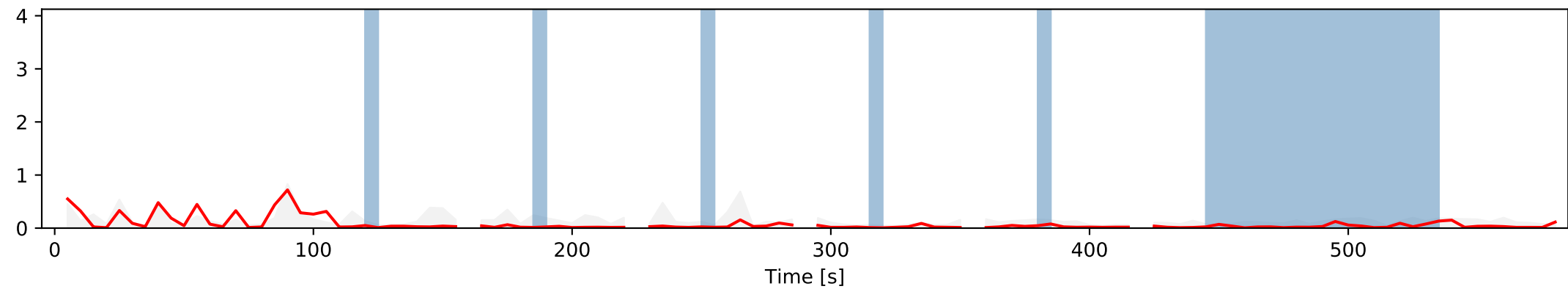
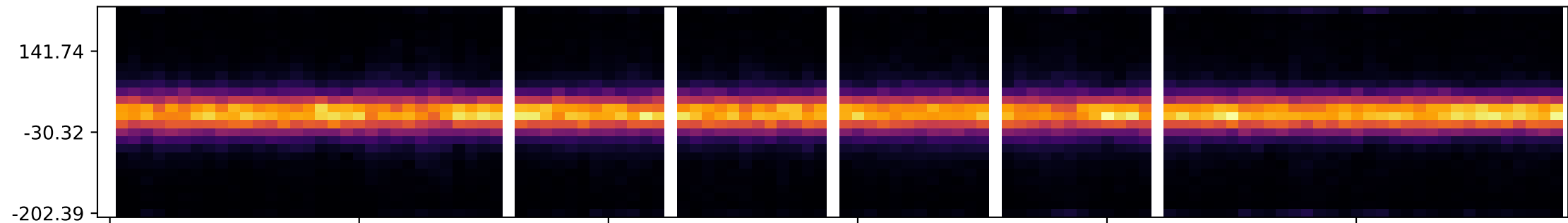
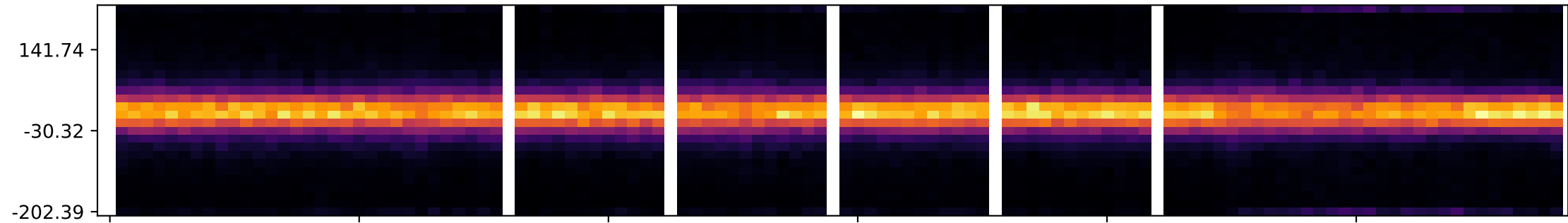
speed_head_base



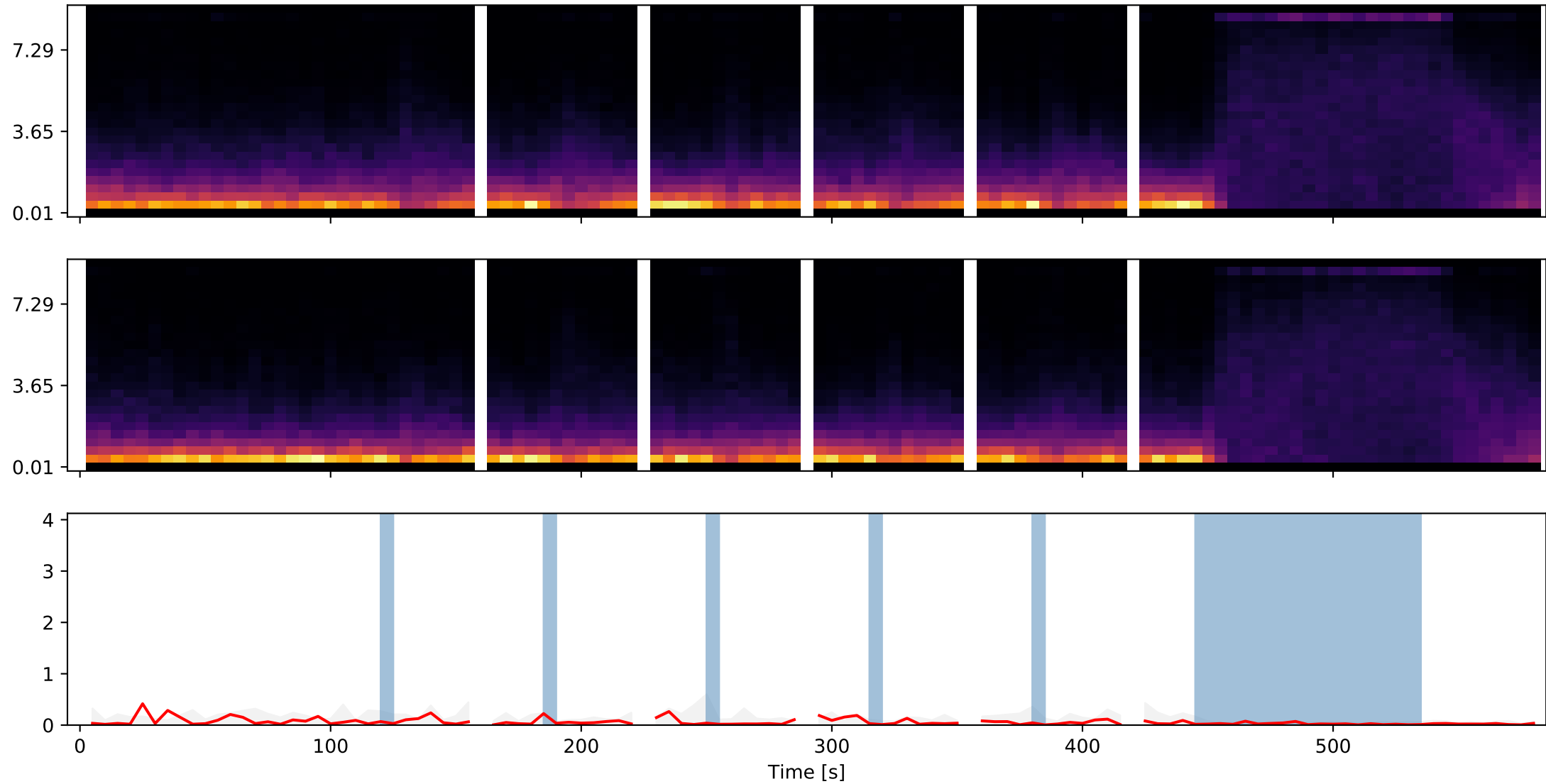
d_speed_neck



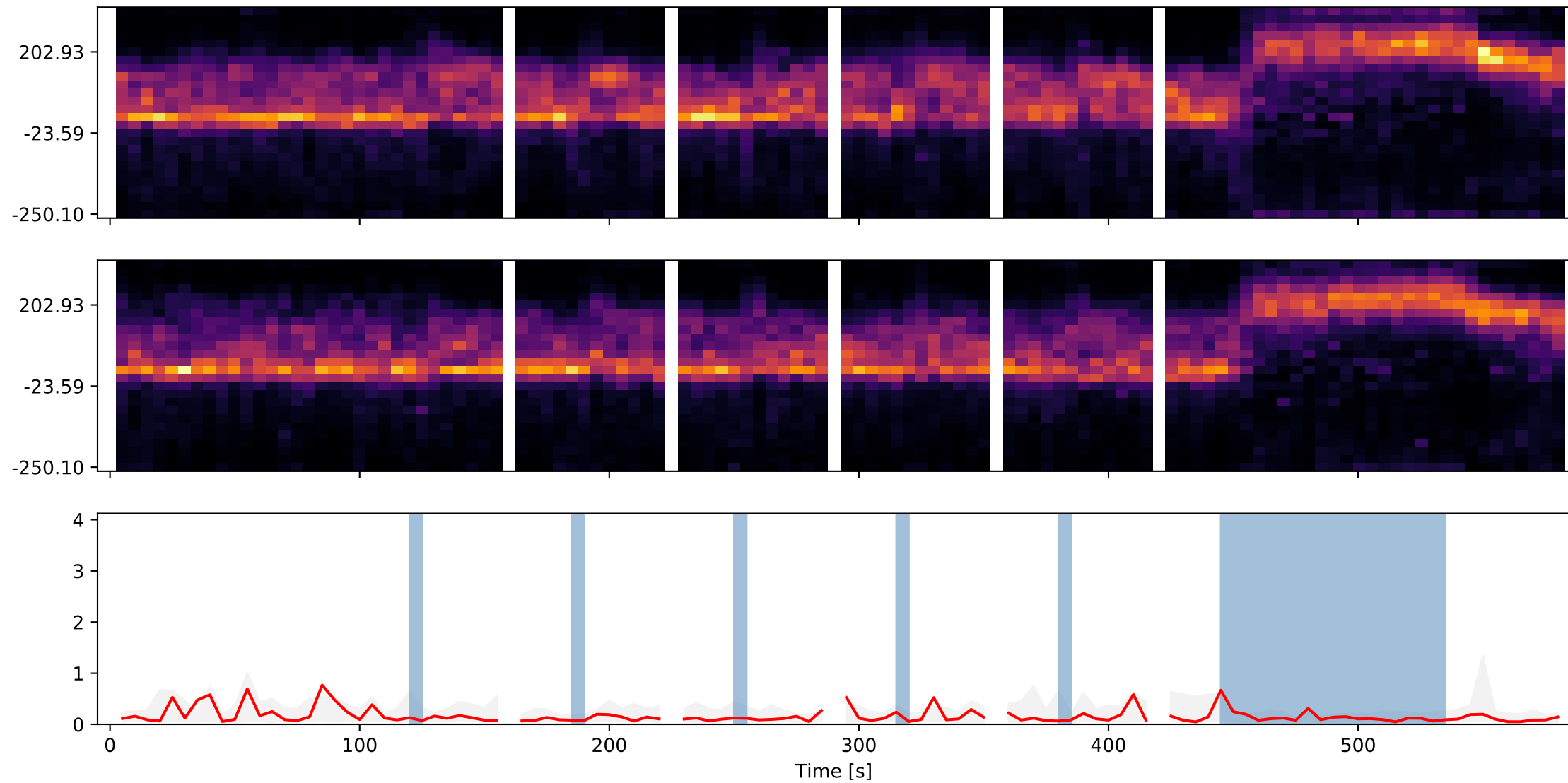
d_length



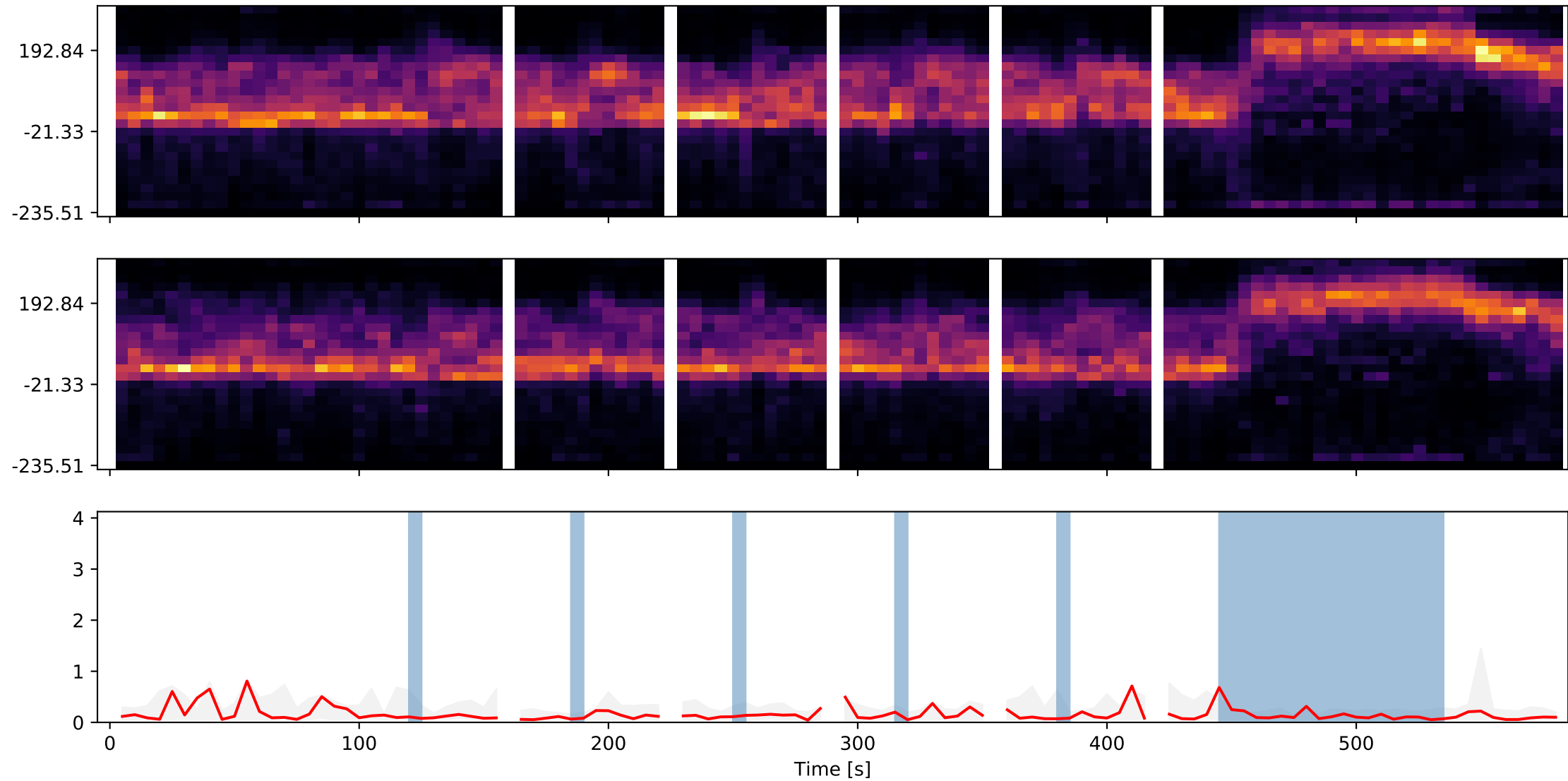
d_relative_to_hips_angular_velocity_tail_tip



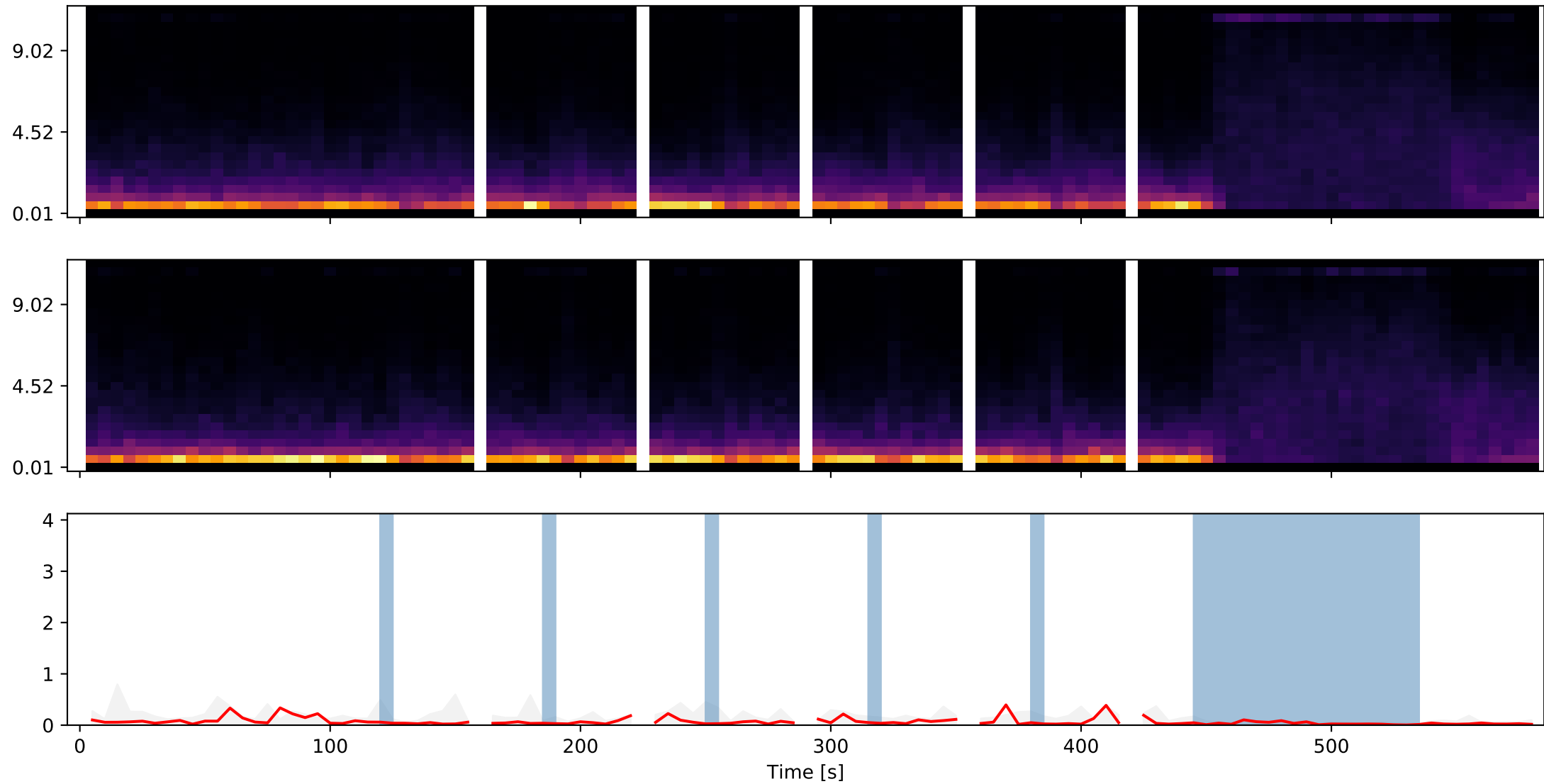
speed_midbody



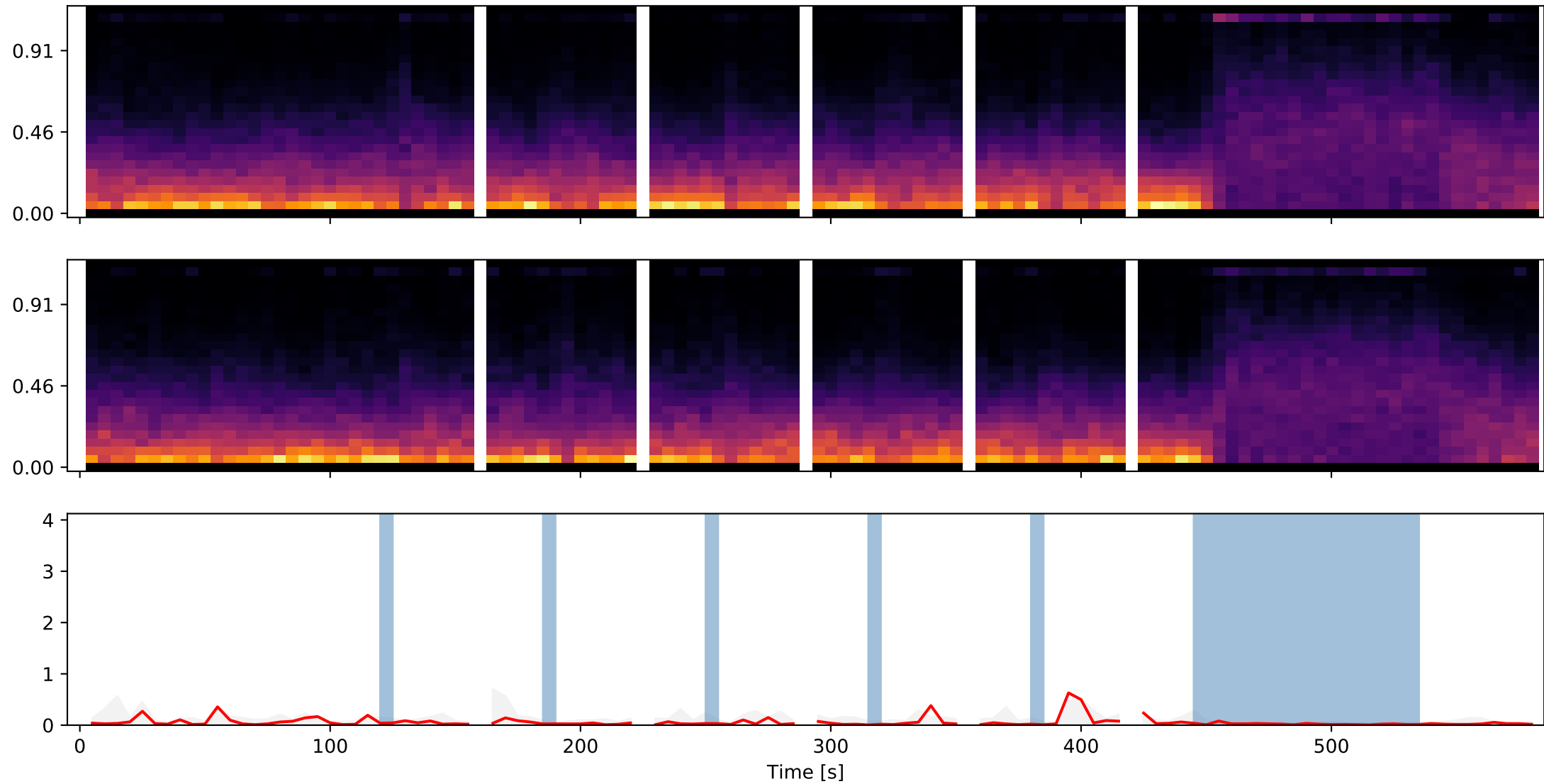
speed



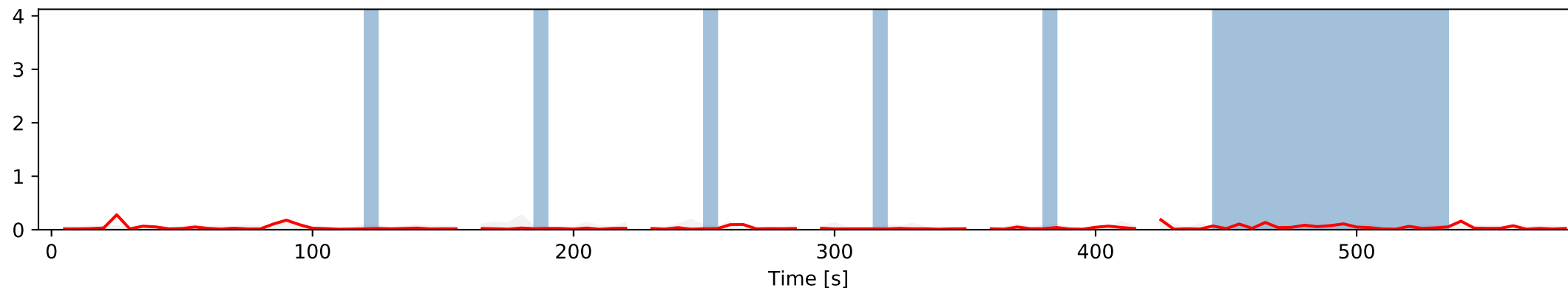
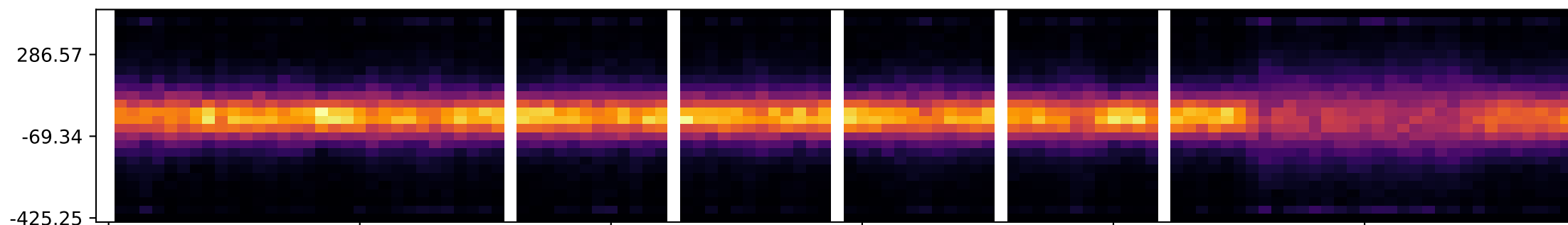
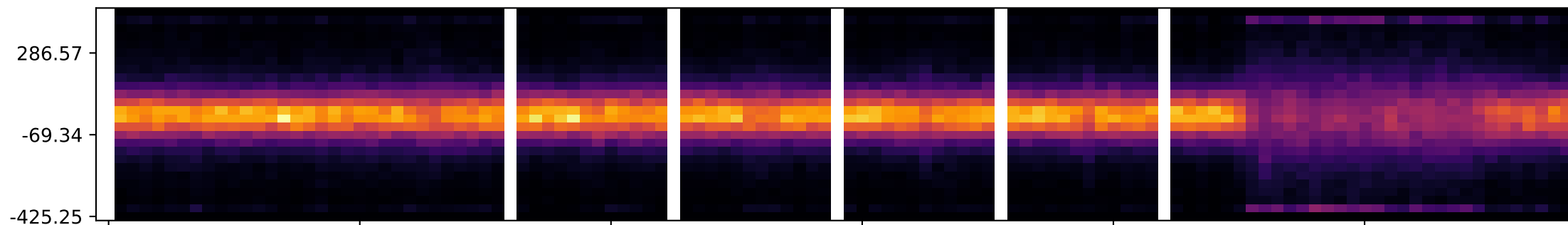
d_eigen_projection_2



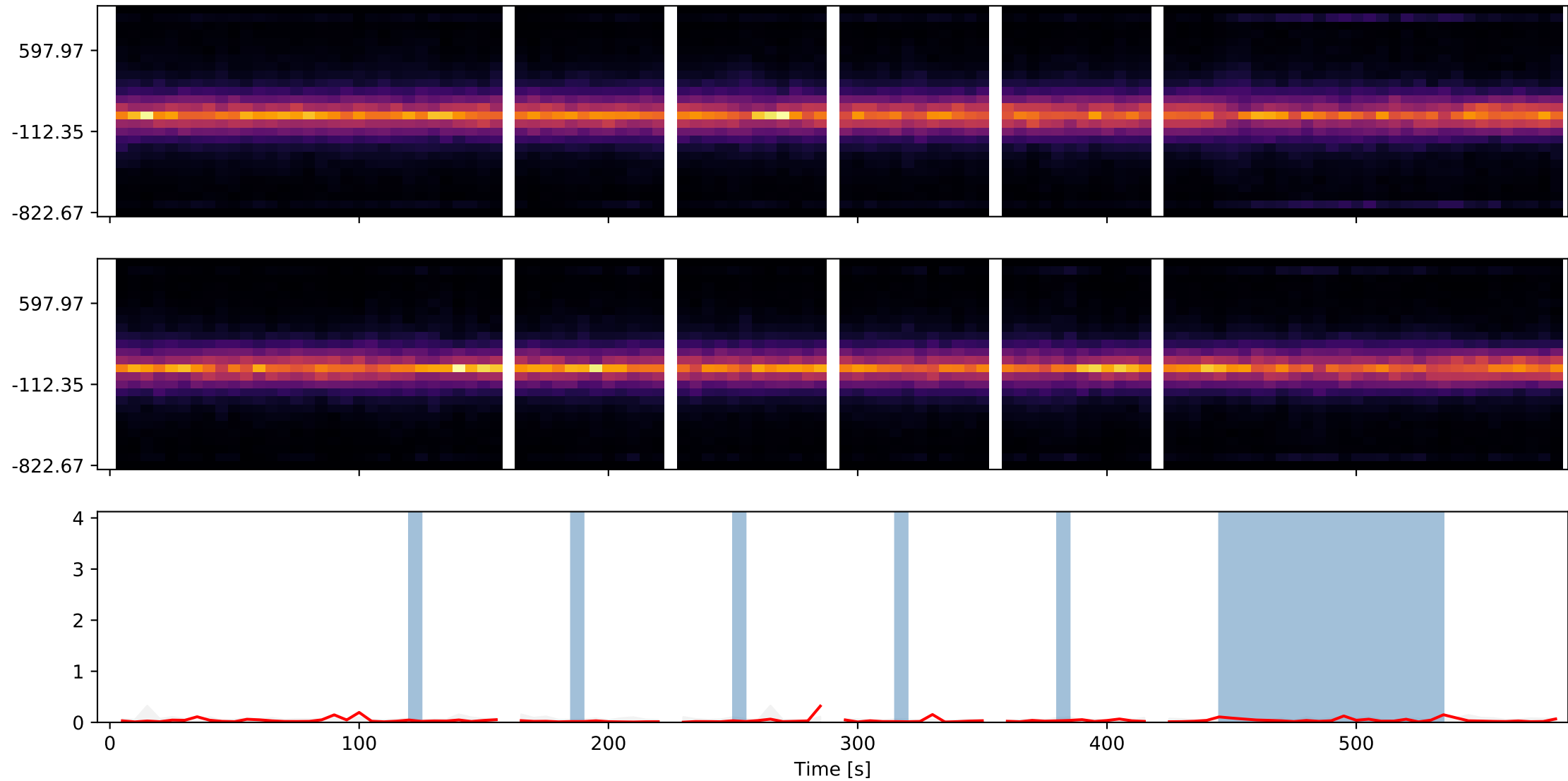
relative_to_body_angular_velocity_head_tip



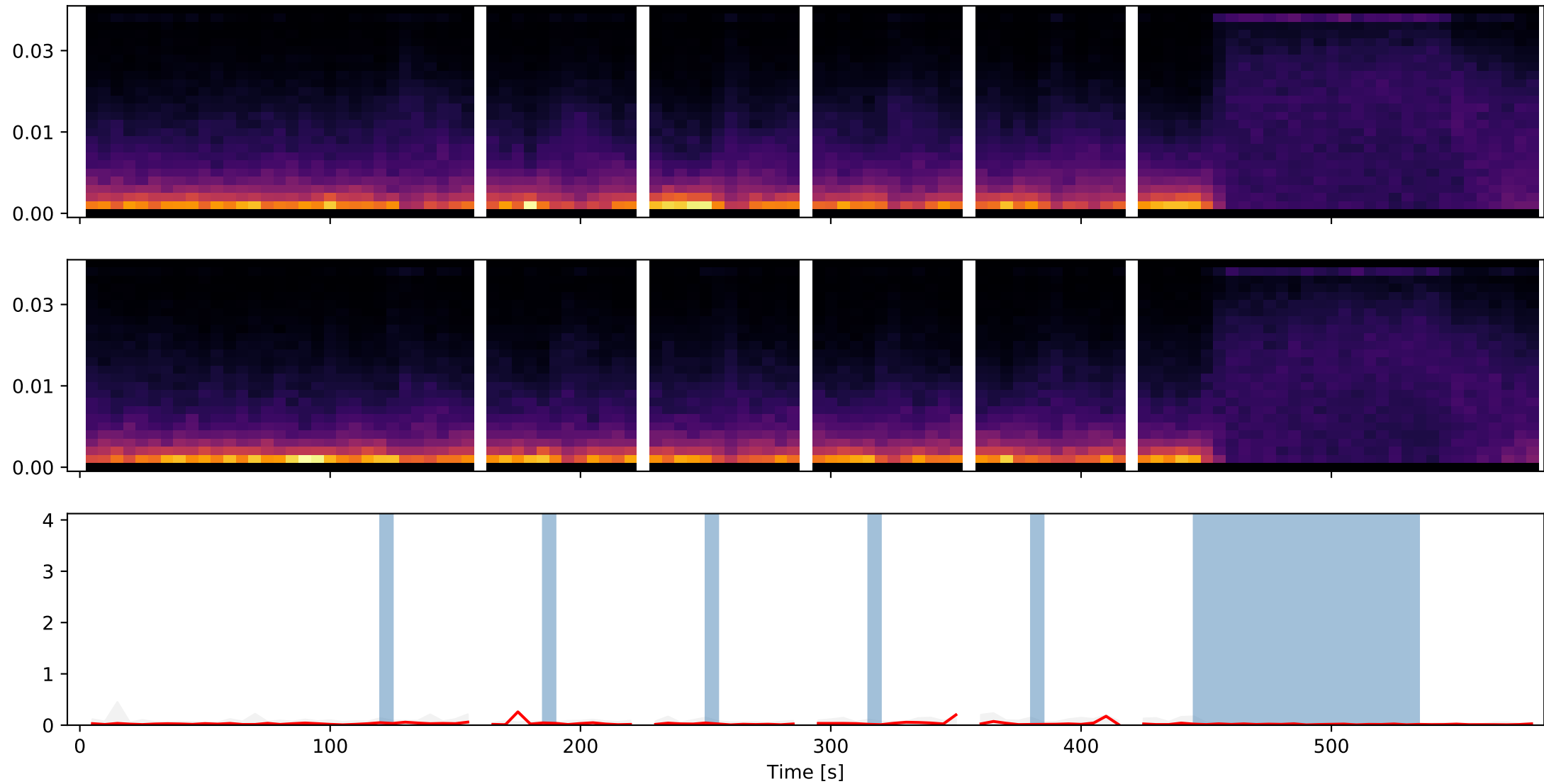
d_relative_to_body_radial_velocity_tail_tip



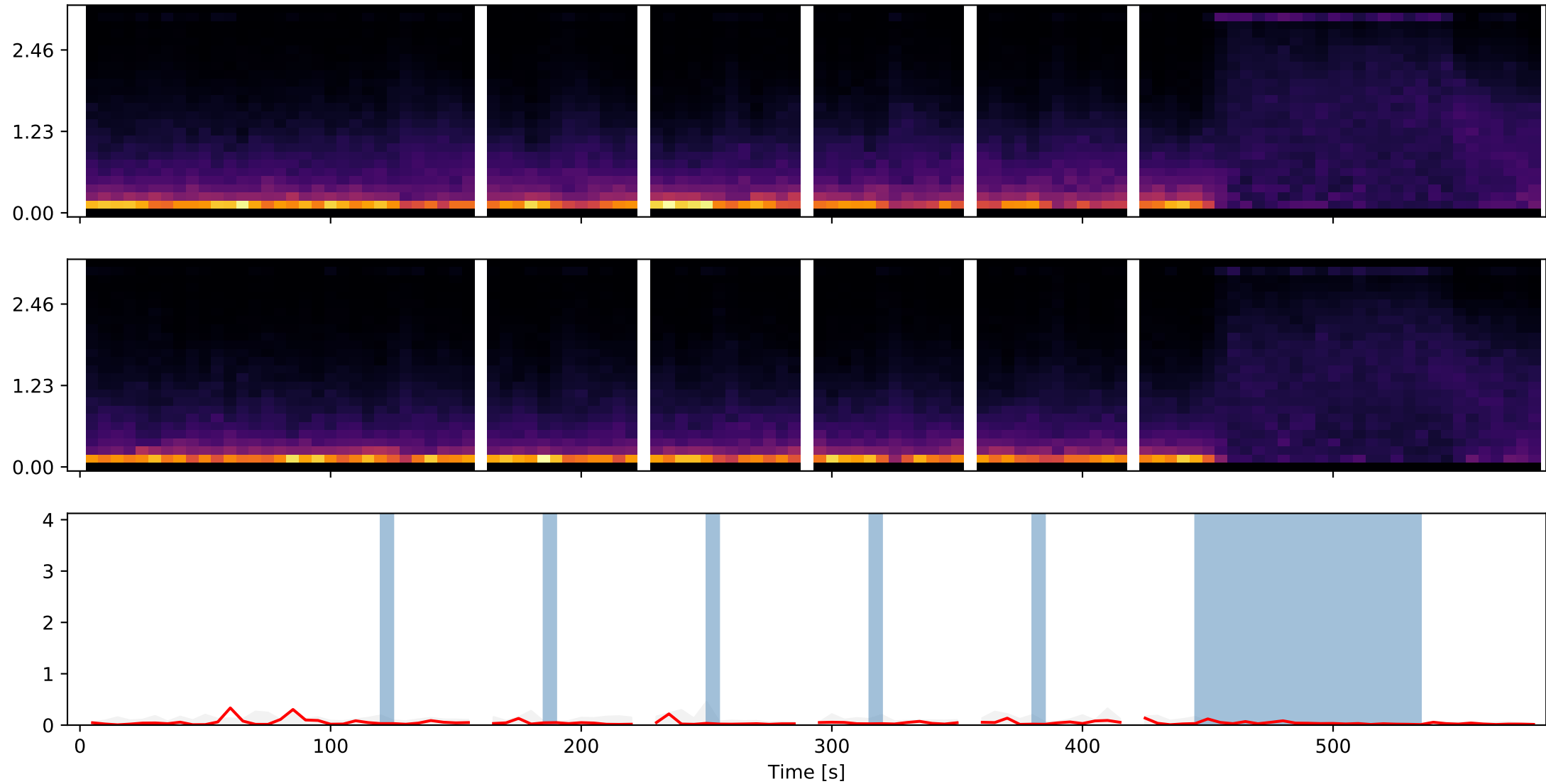
d_speed_head_base



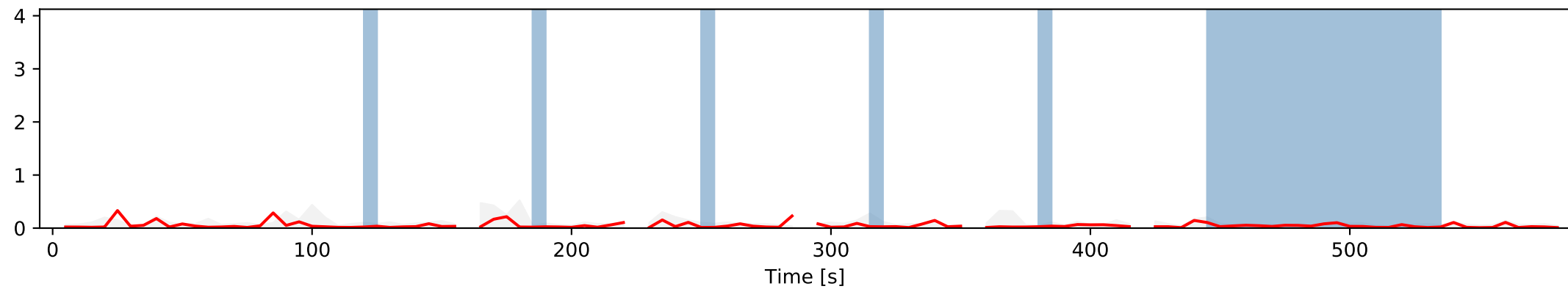
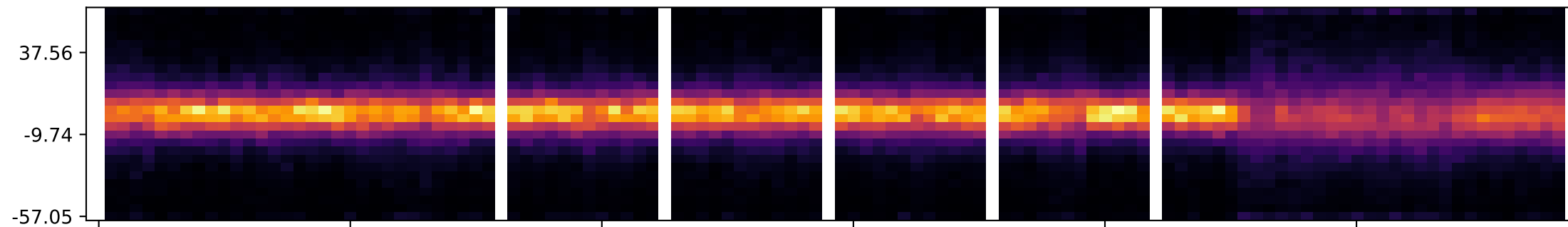
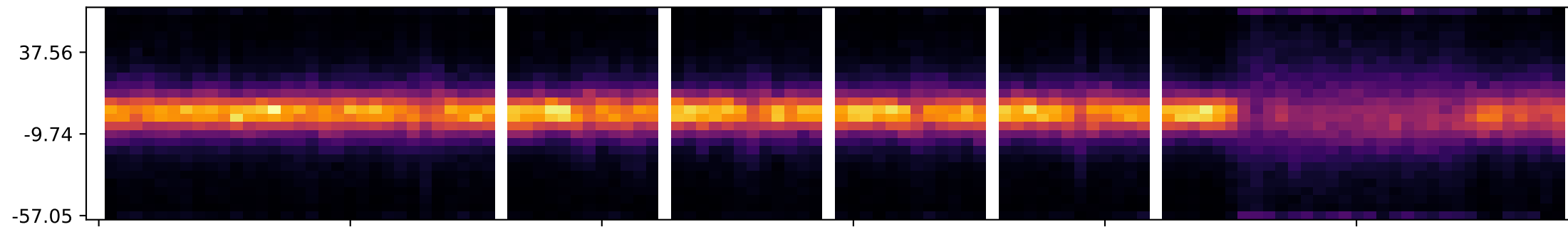
d_curvature_hips



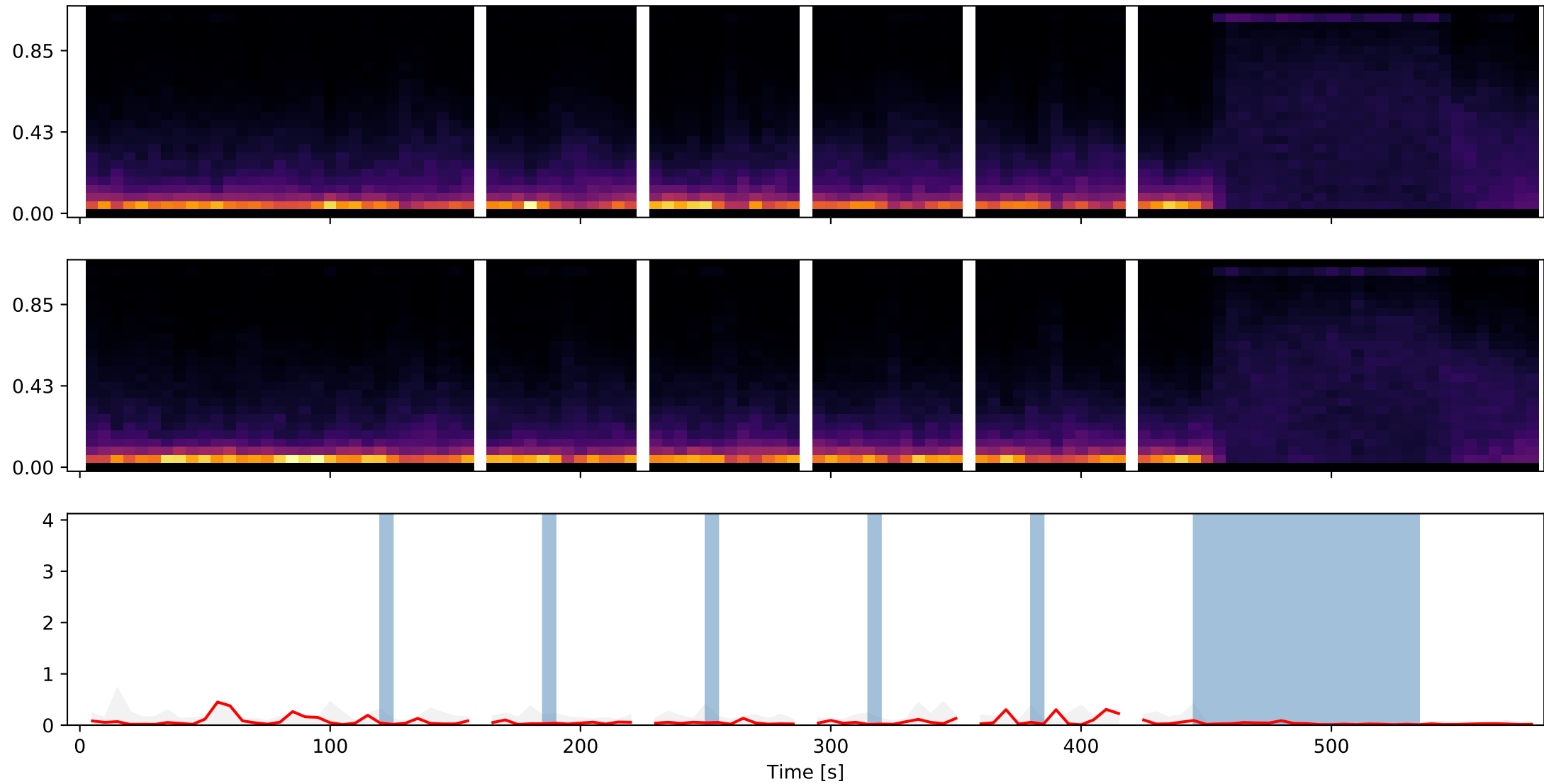
angular_velocity_tail_base



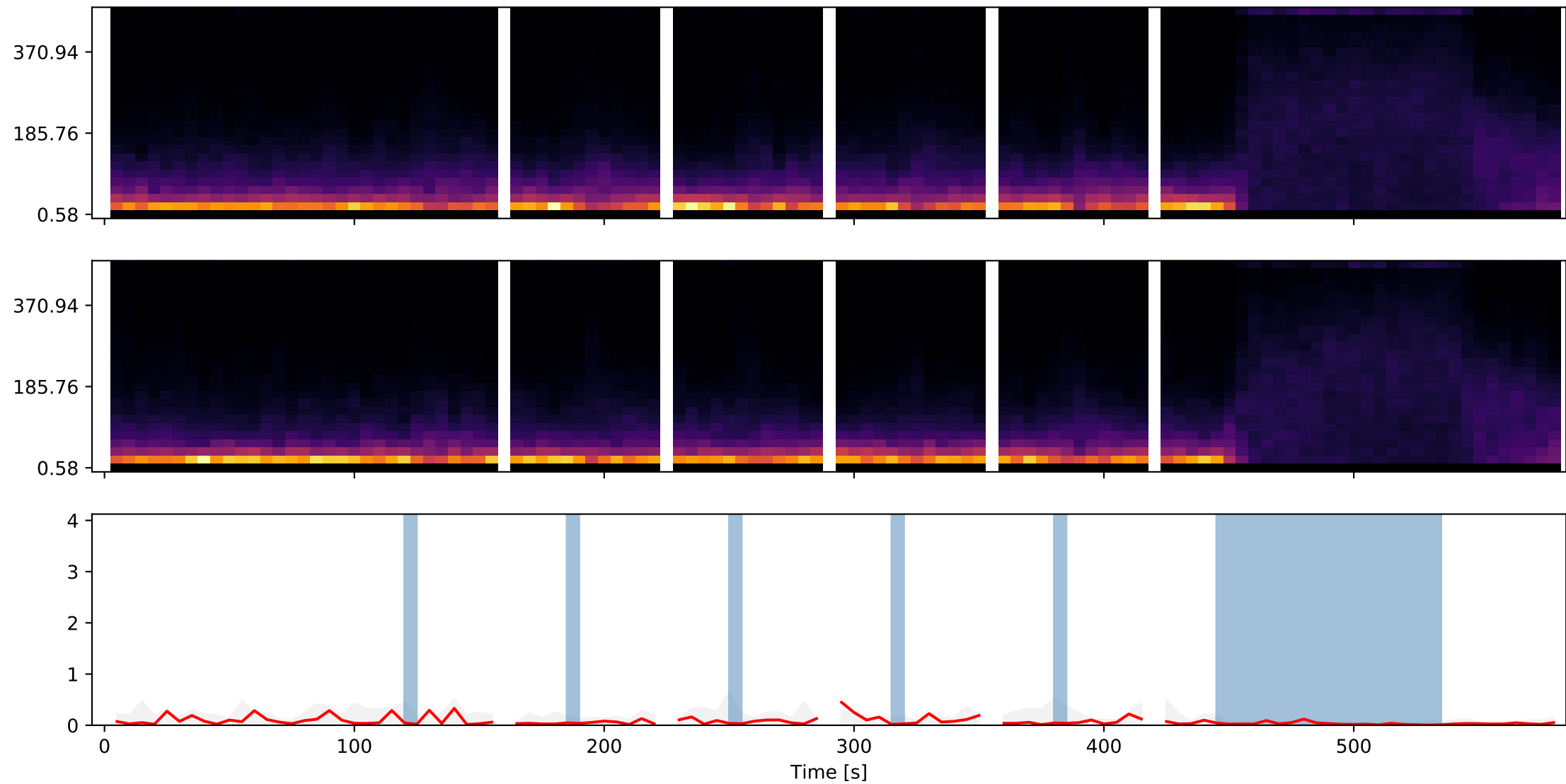
relative_to_body_radial_velocity_hips



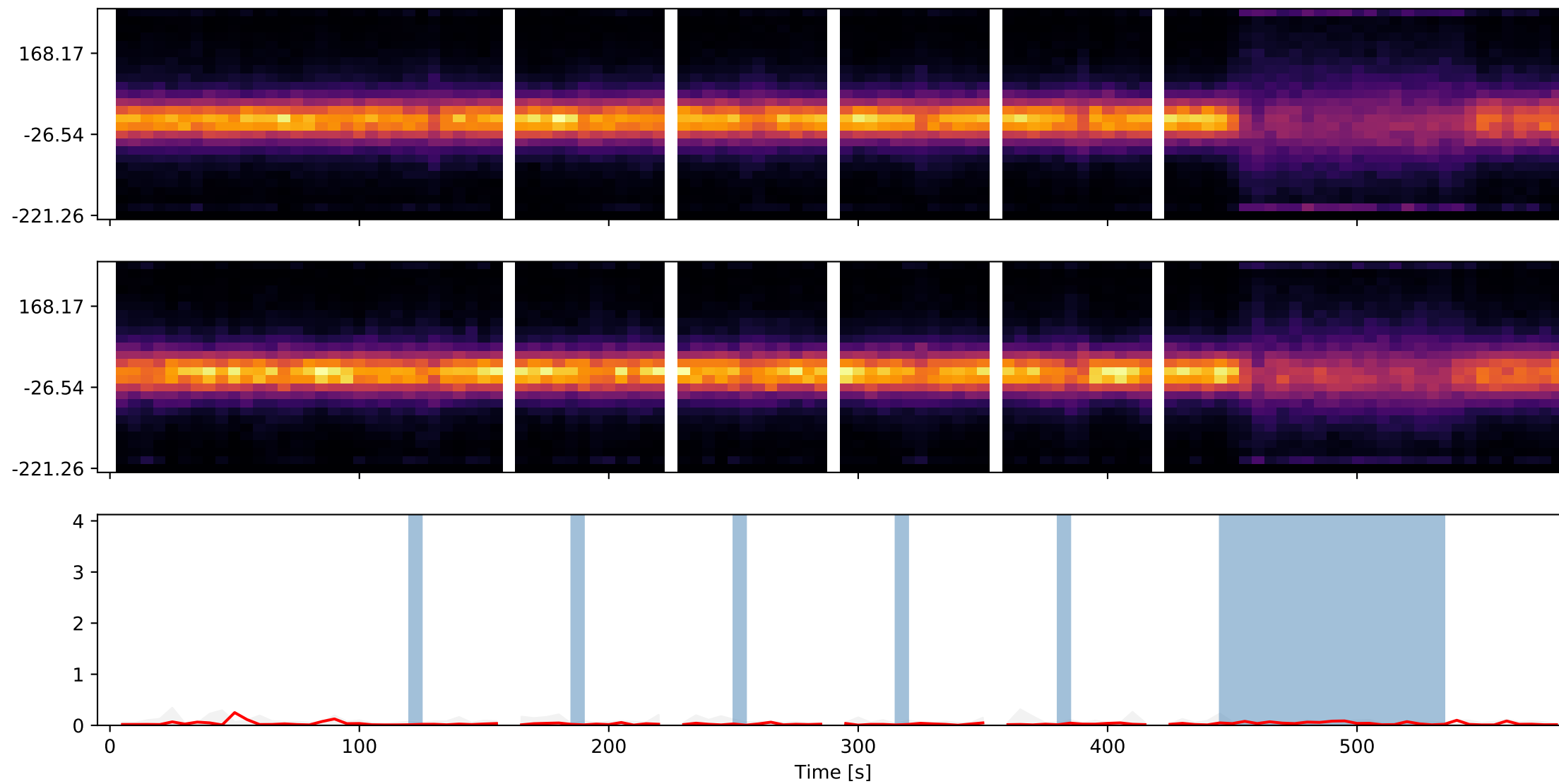
relative_to_body_angular_velocity_hips



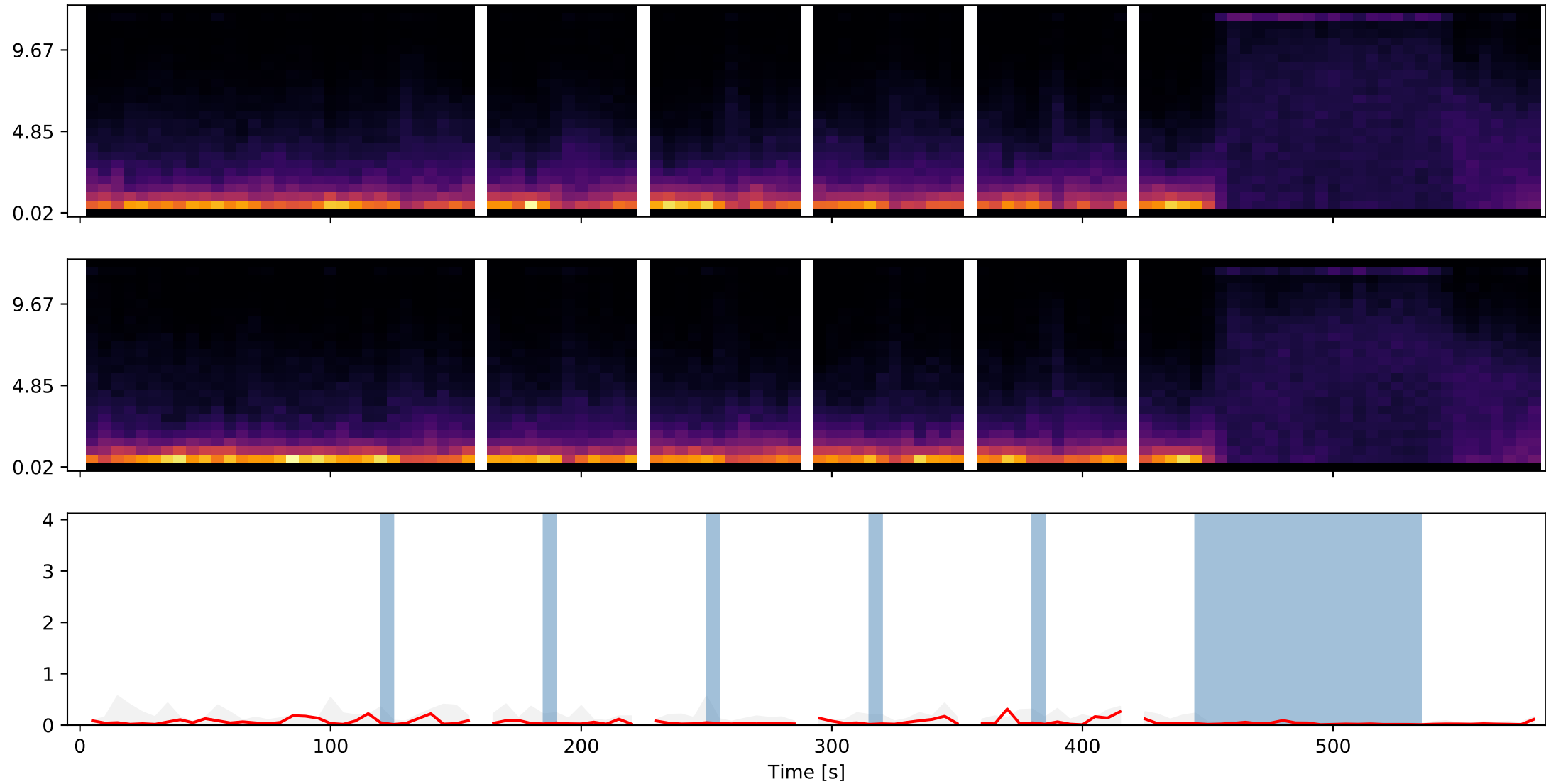
d_relative_to_body_speed_midbody



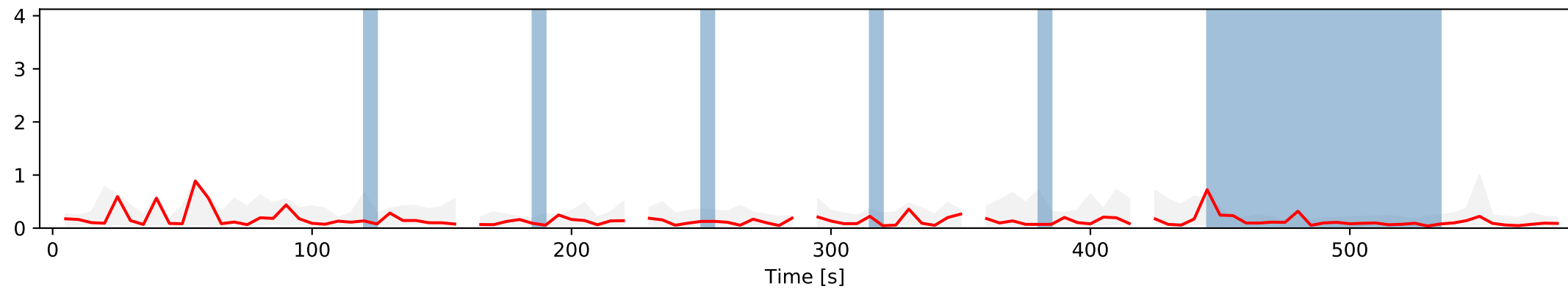
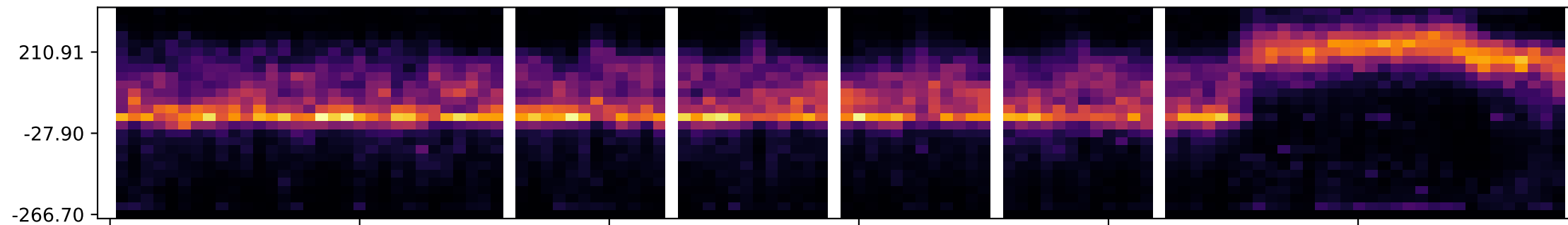
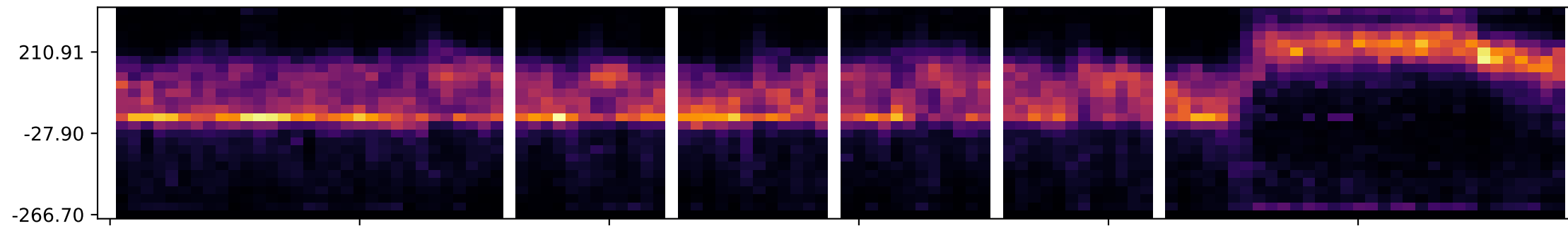
d_relative_to_body_radial_velocity_hips



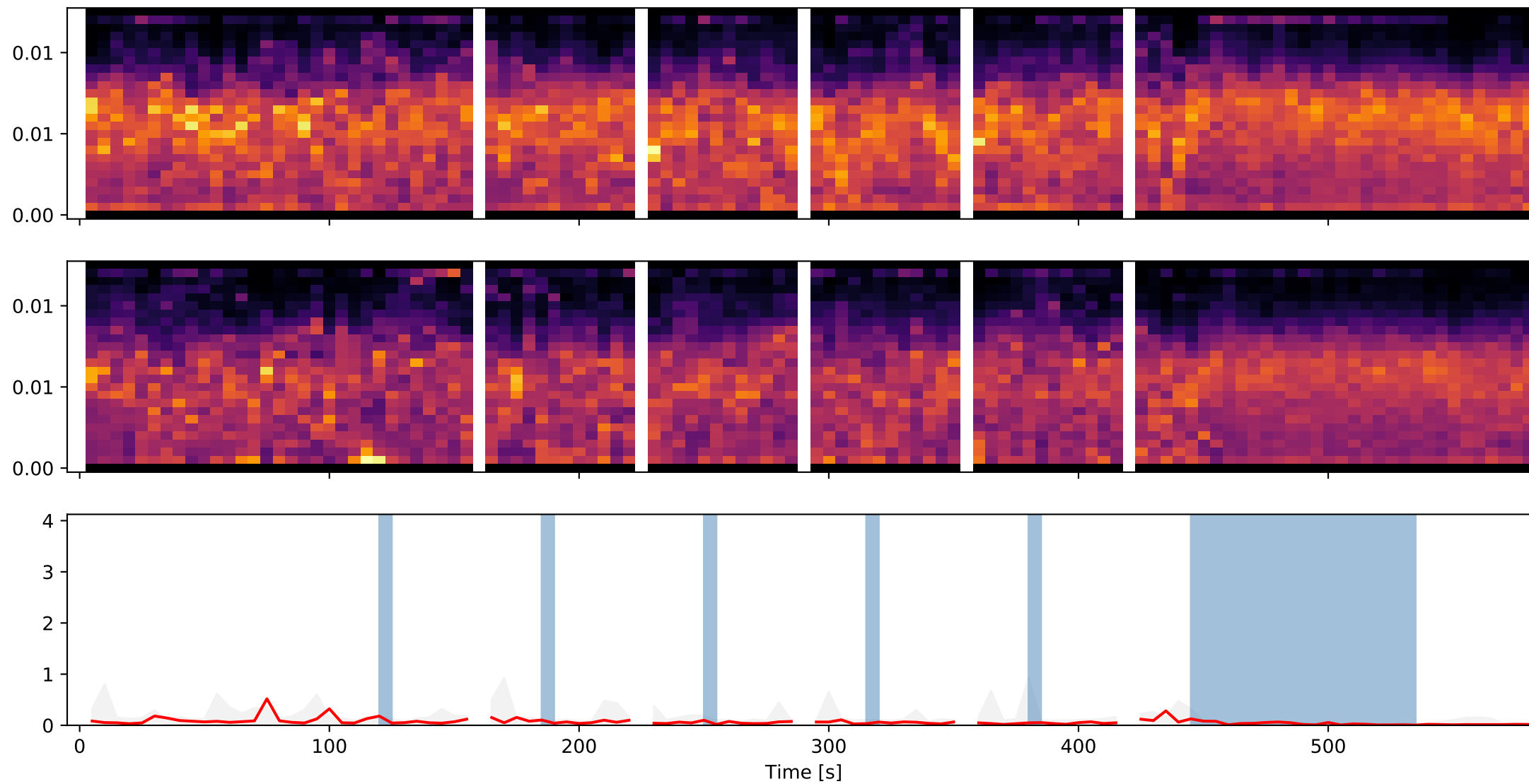
d_eigen_projection_3



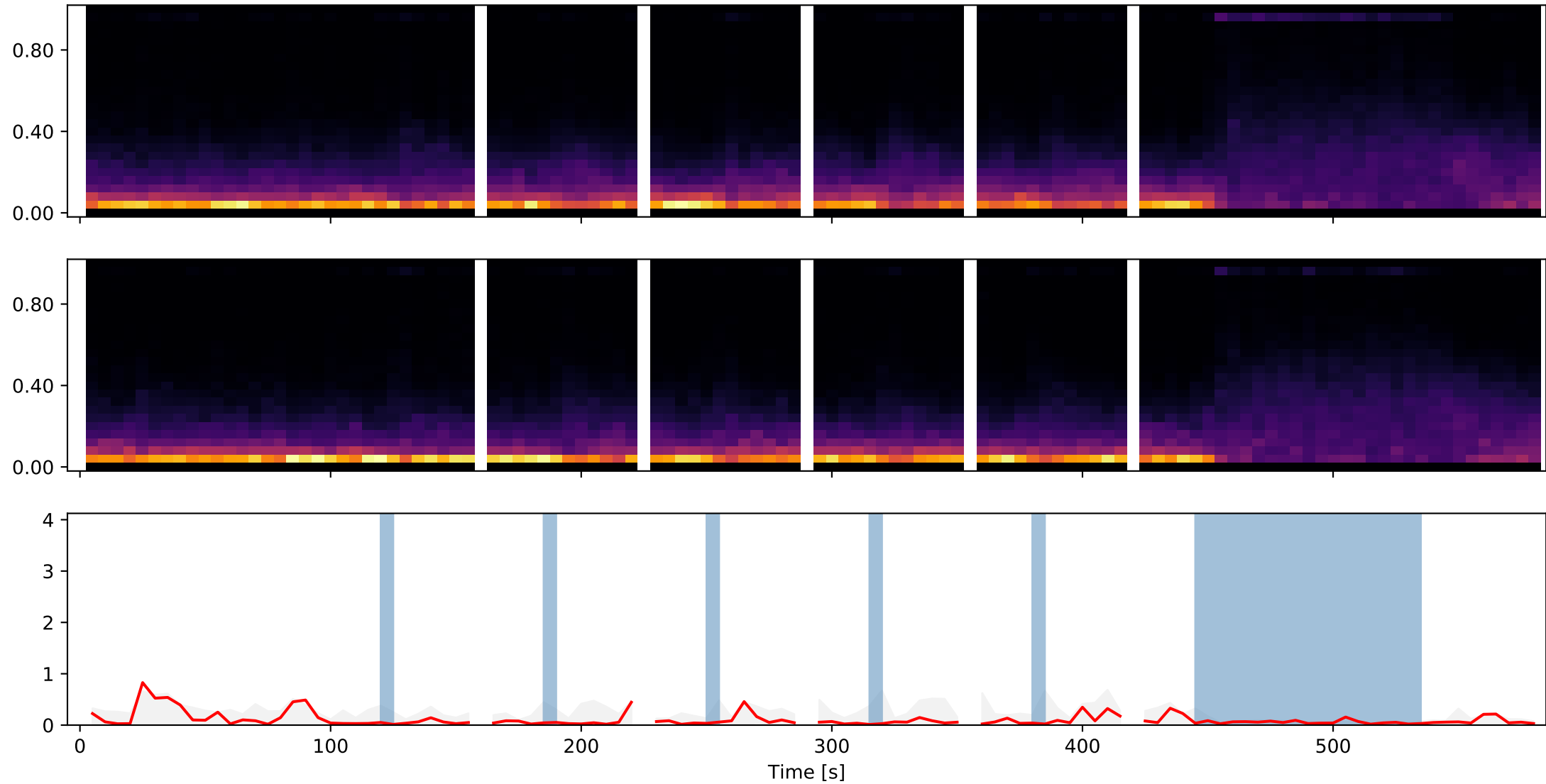
speed_hips



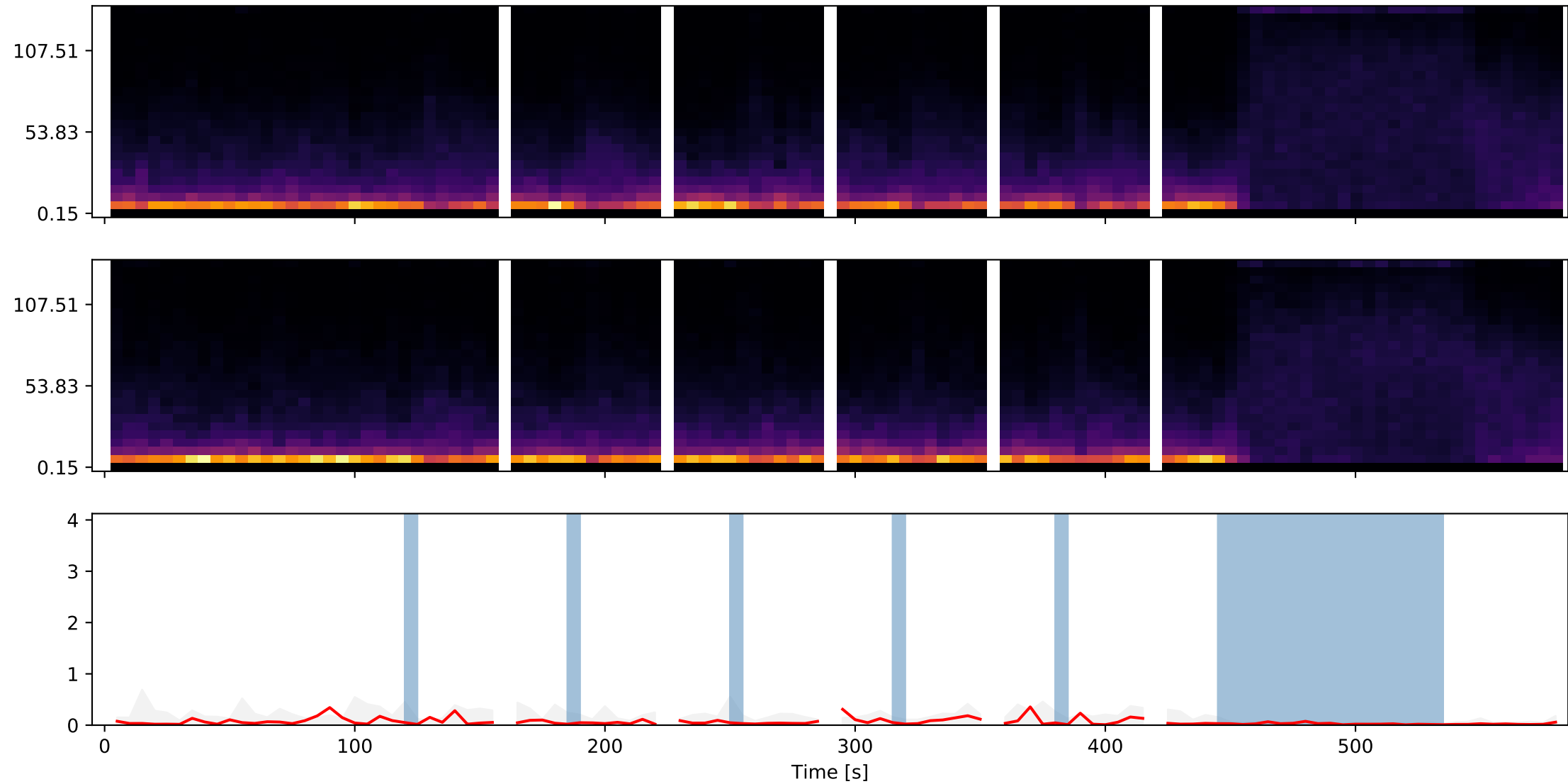
curvature_mean_tail



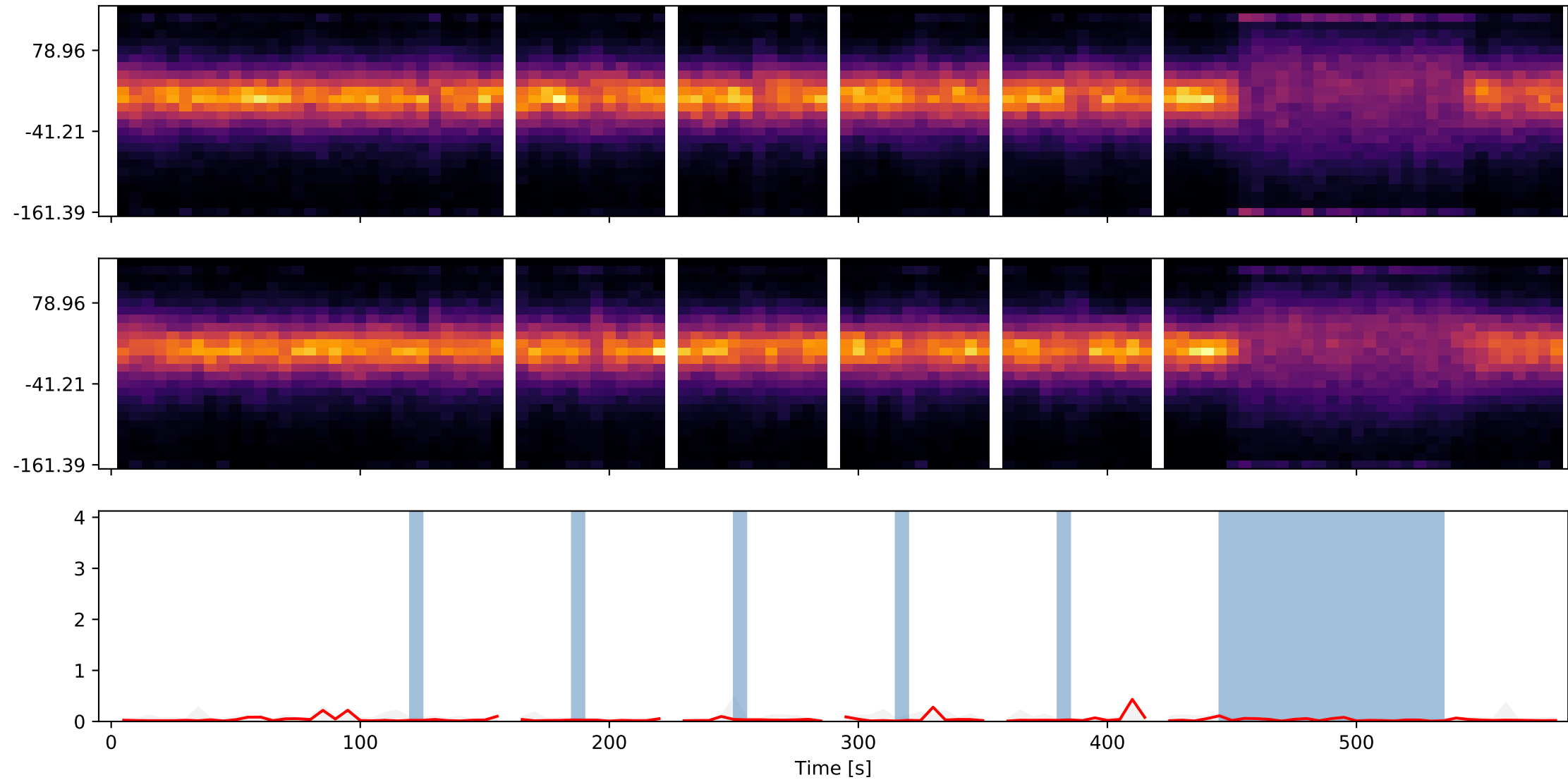
angular_velocity



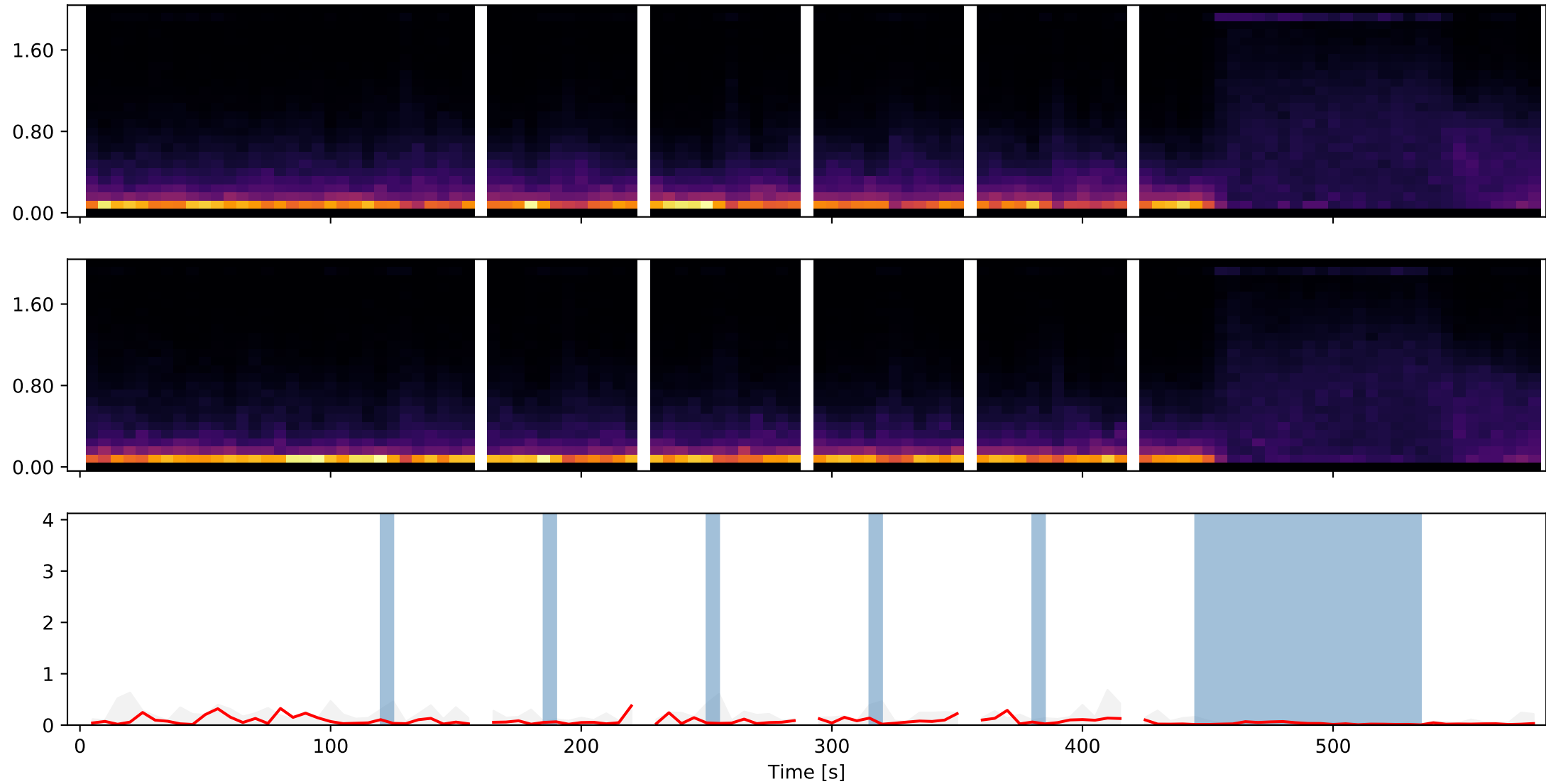
relative_to_body_speed_midbody



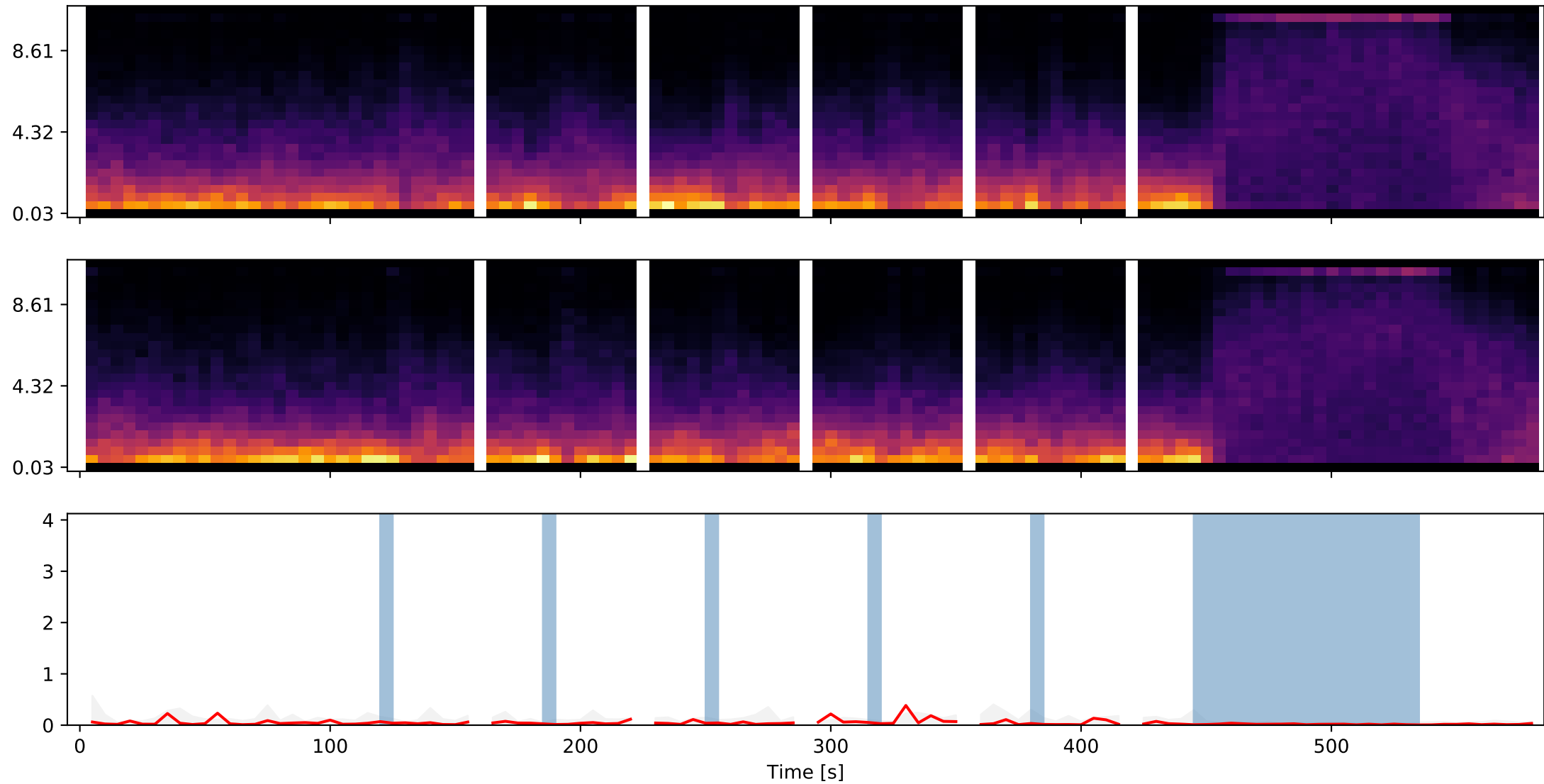
relative_to_body_radial_velocity_head_tip



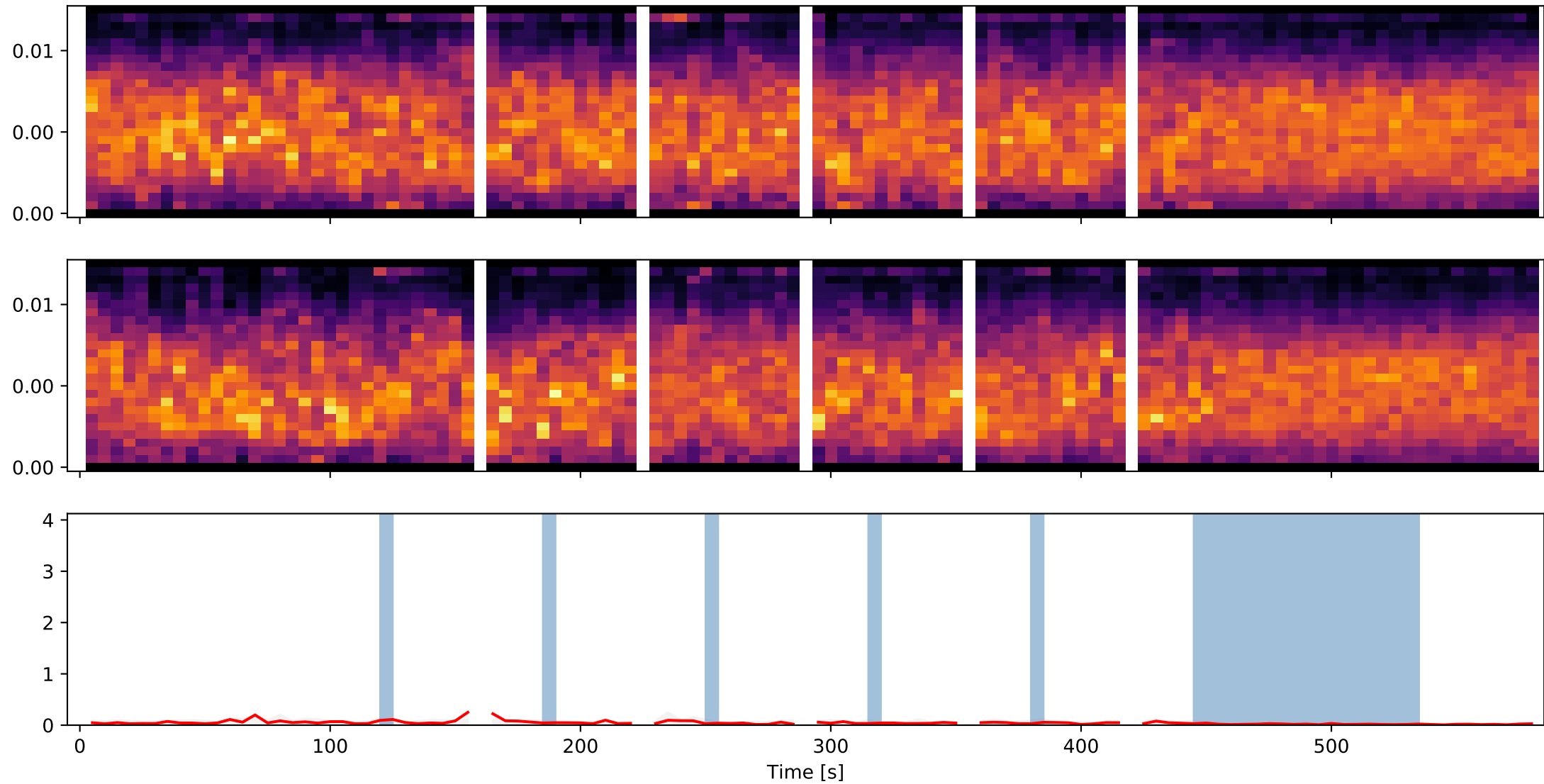
angular_velocity_midbody



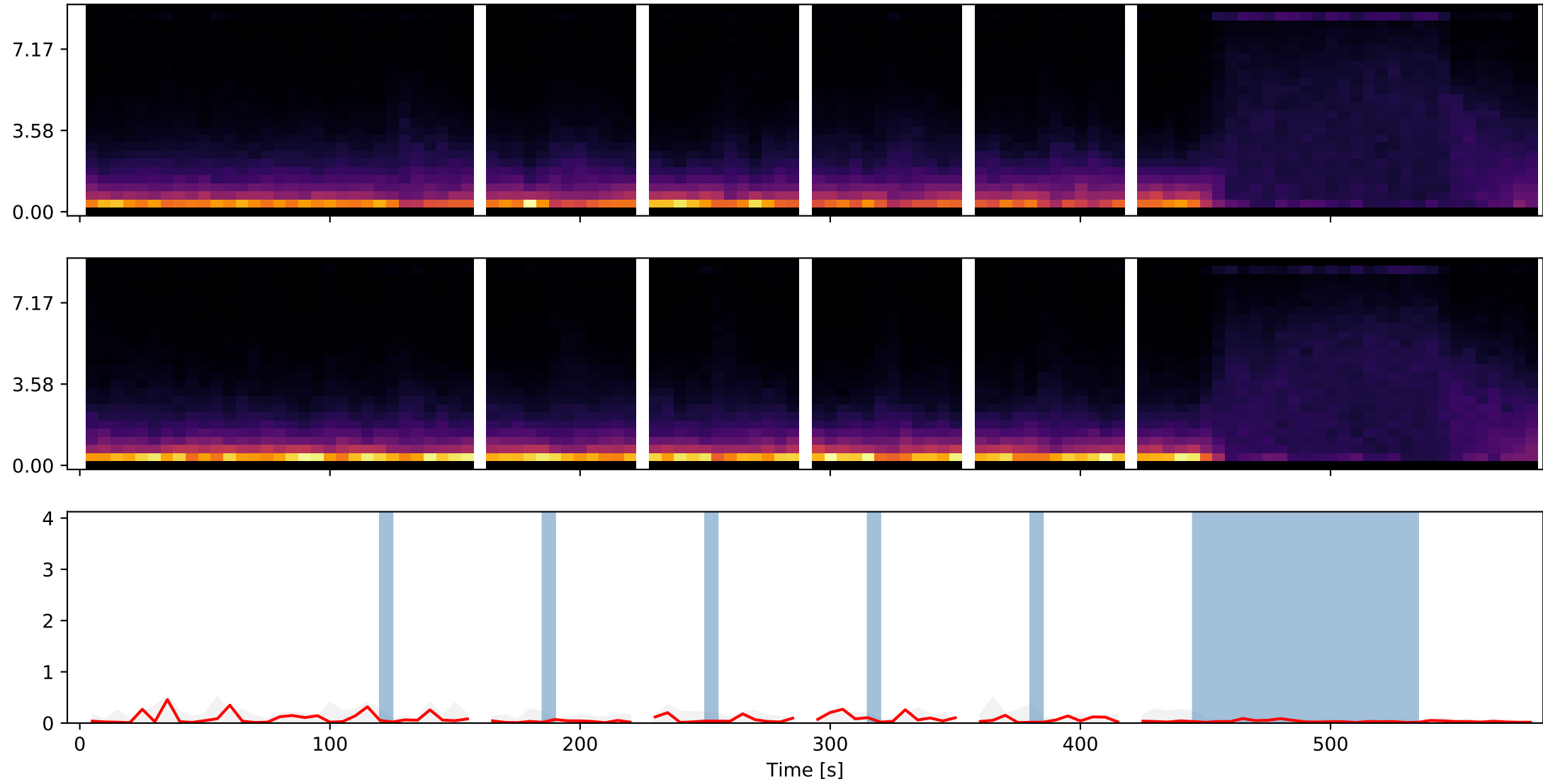
d_eigen_projection_1



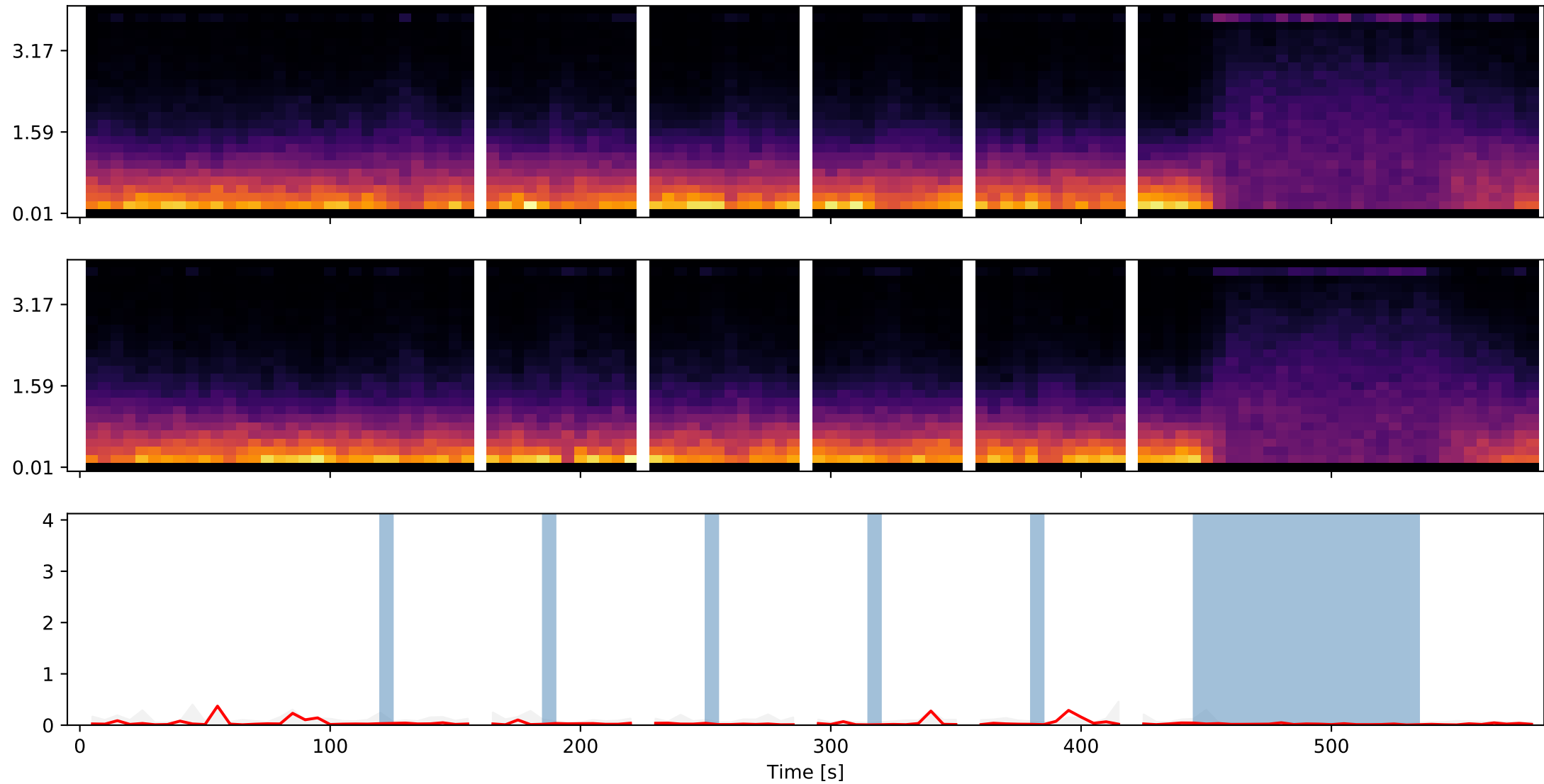
curvature_std_hips



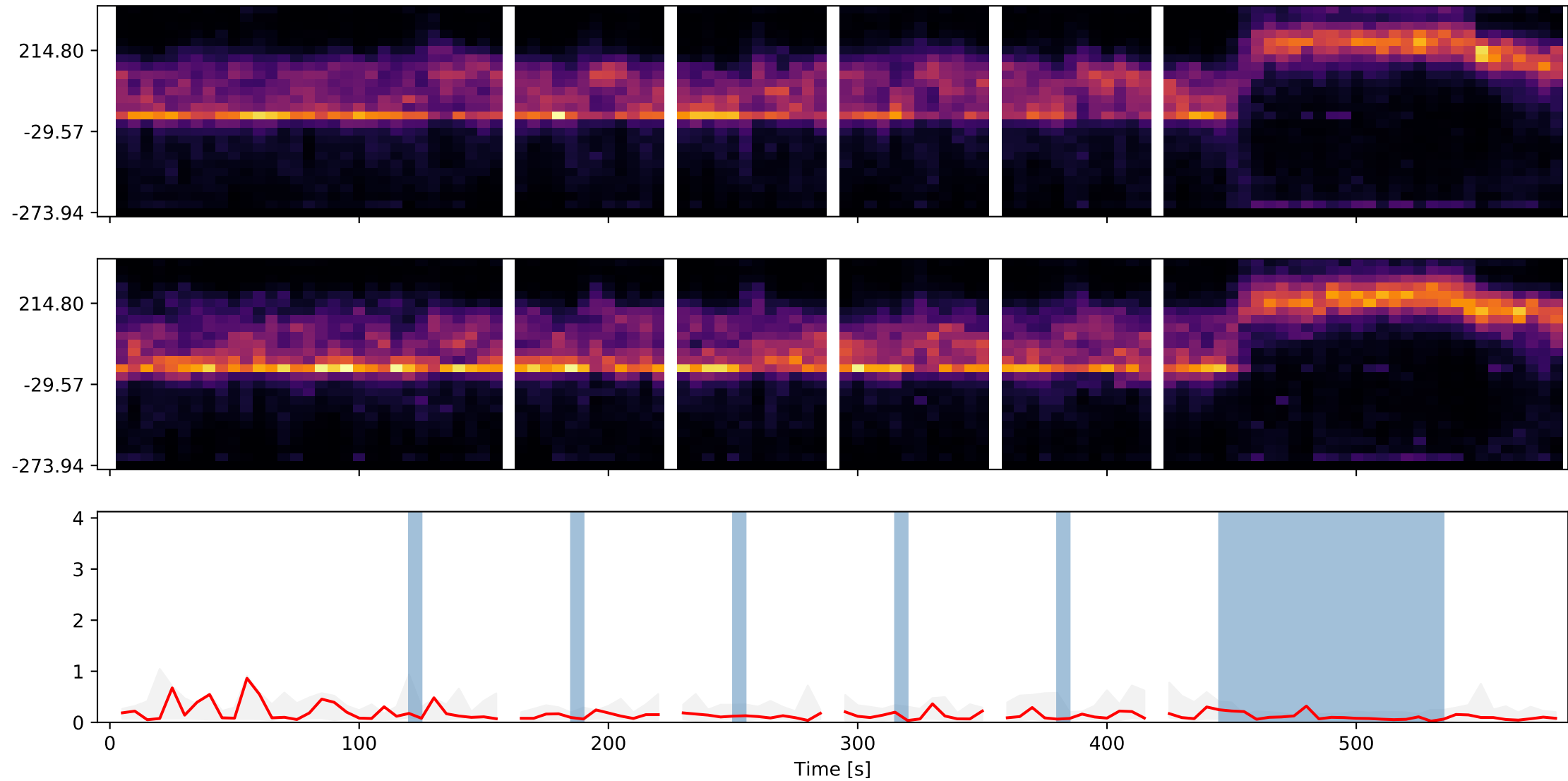
d_angular_velocity_hips



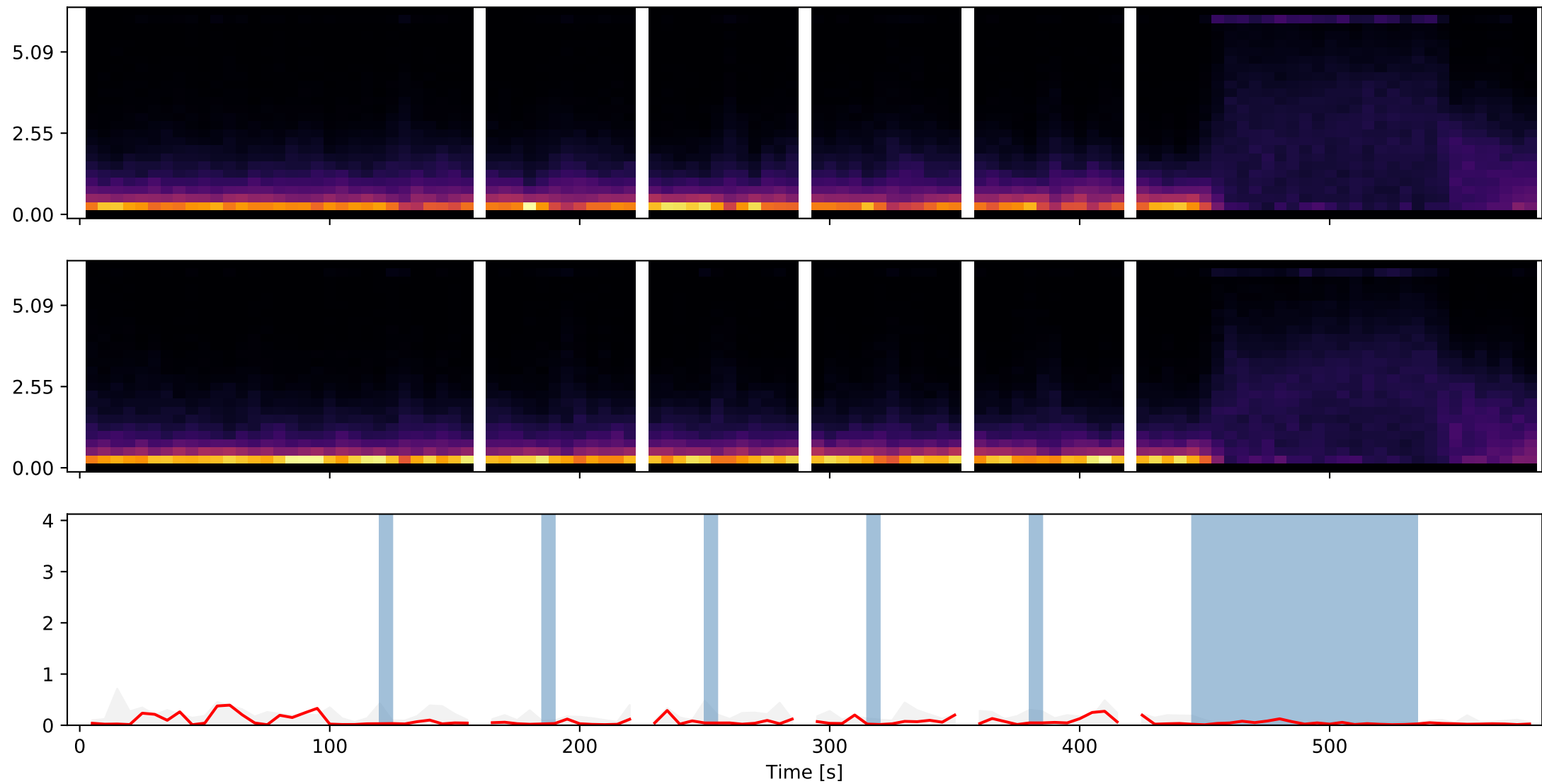
d_relative_to_body_angular_velocity_head_tip



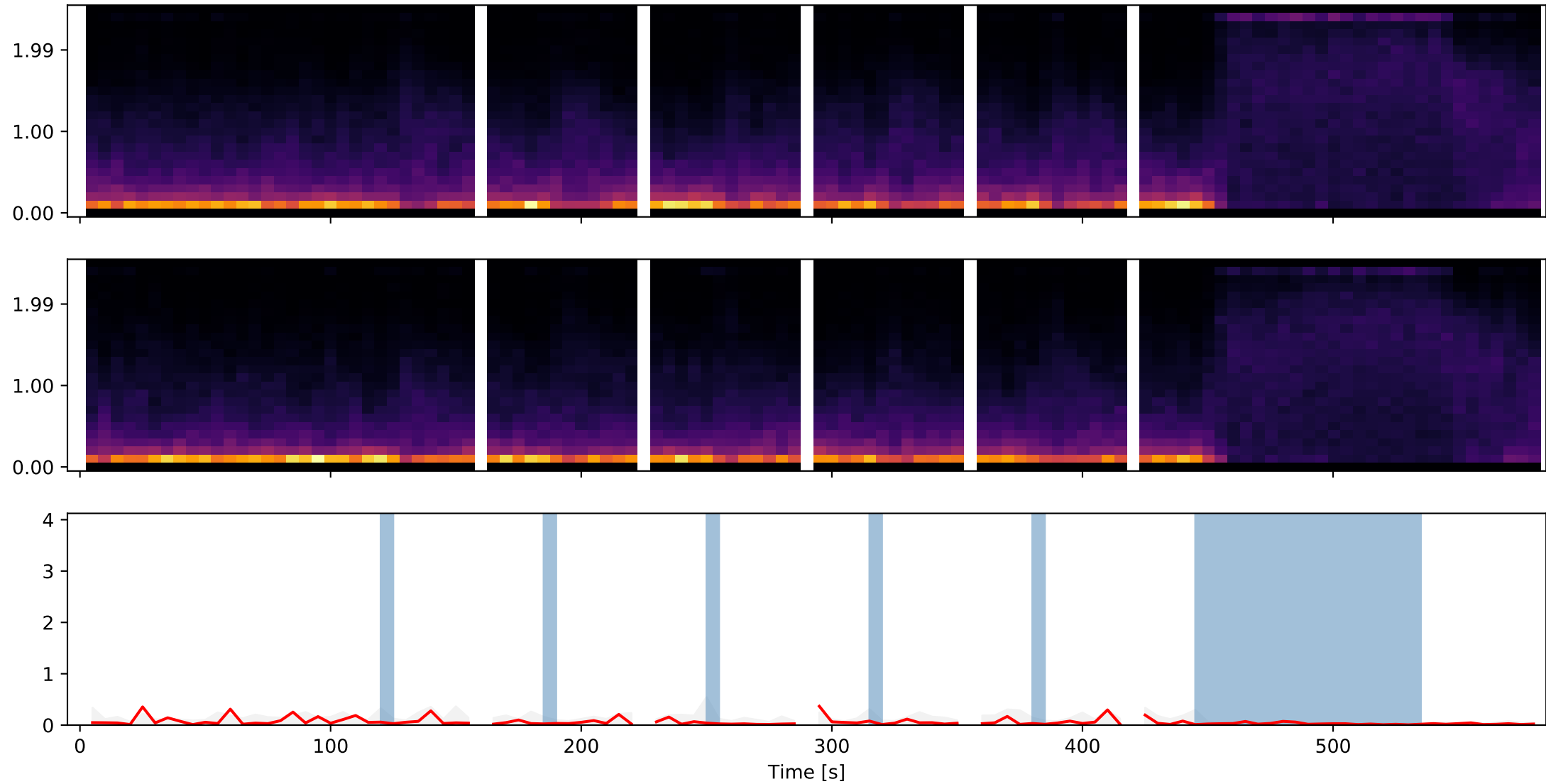
speed_tail_base



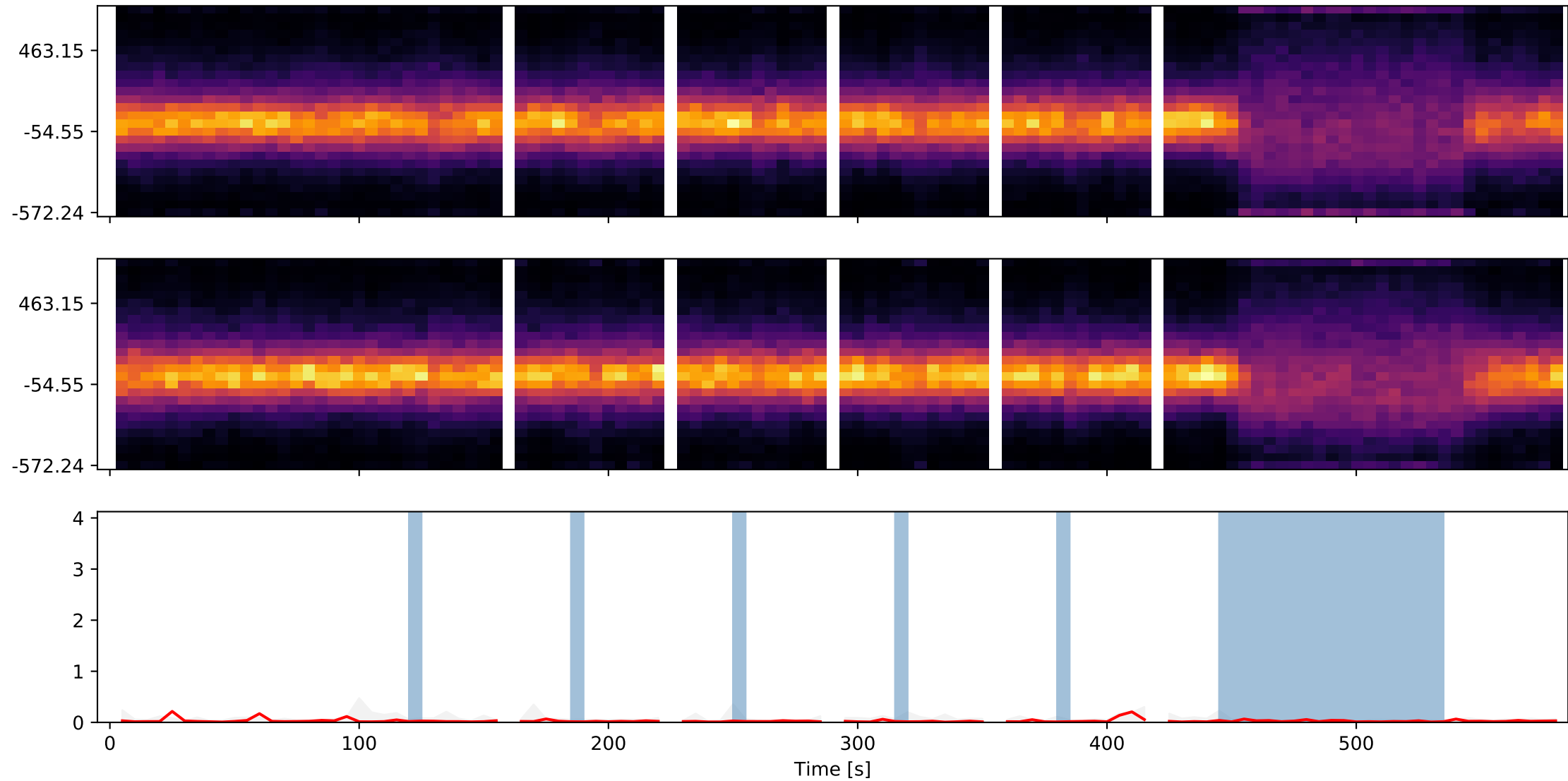
d_angular_velocity_midbody



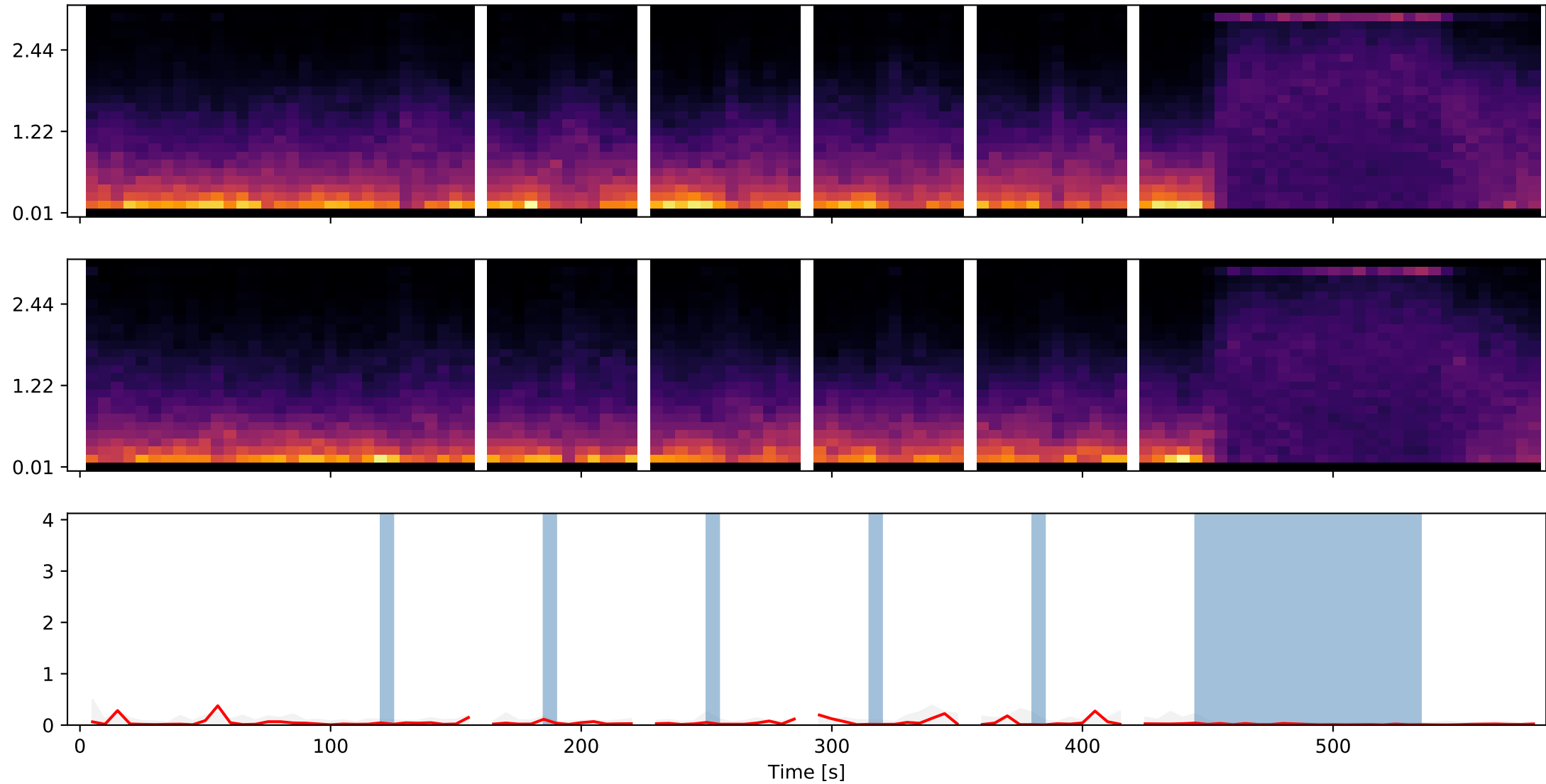
relative_to_hips_angular_velocity_tail_tip



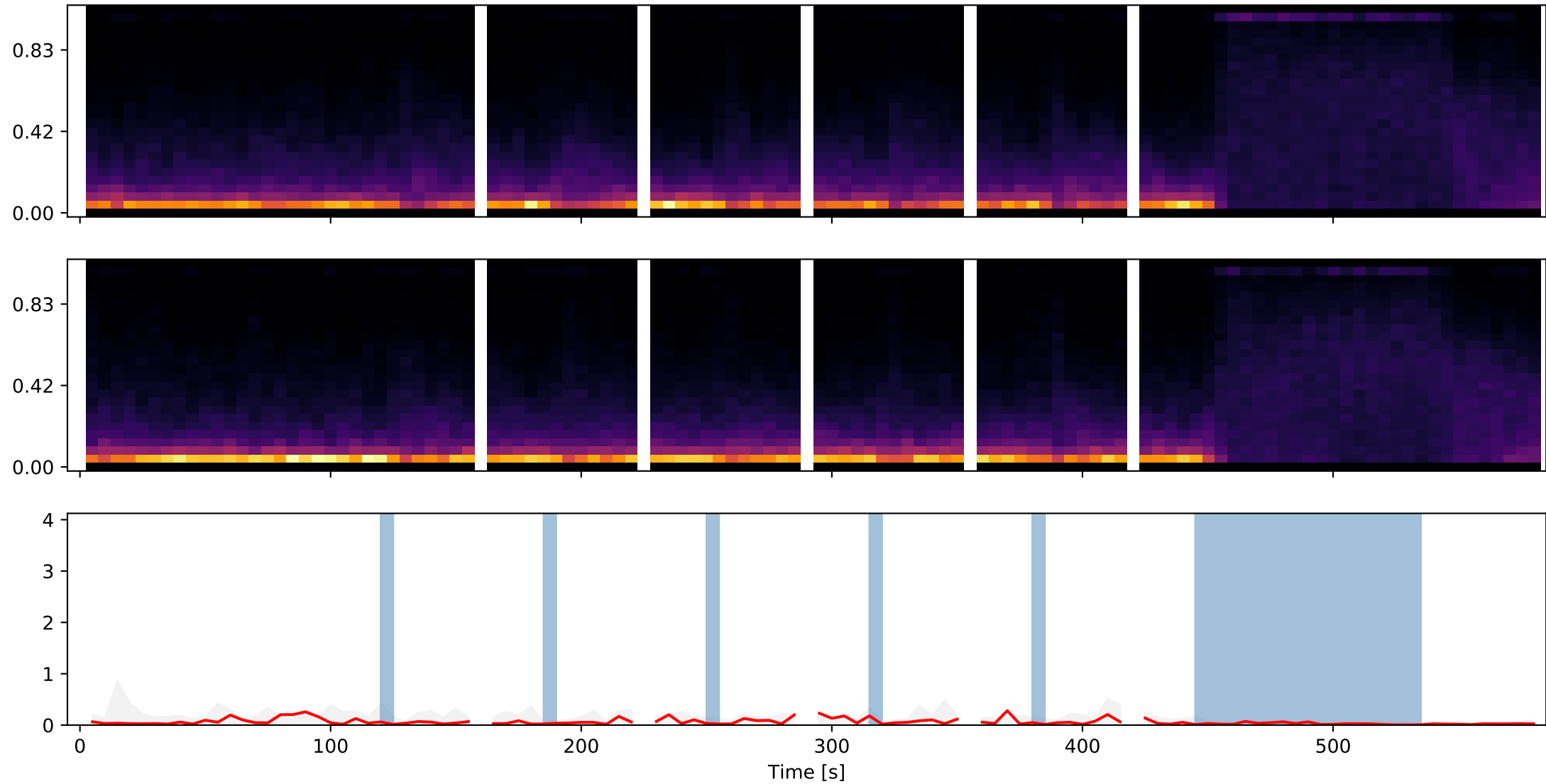
d_relative_to_body_radial_velocity_head_tip



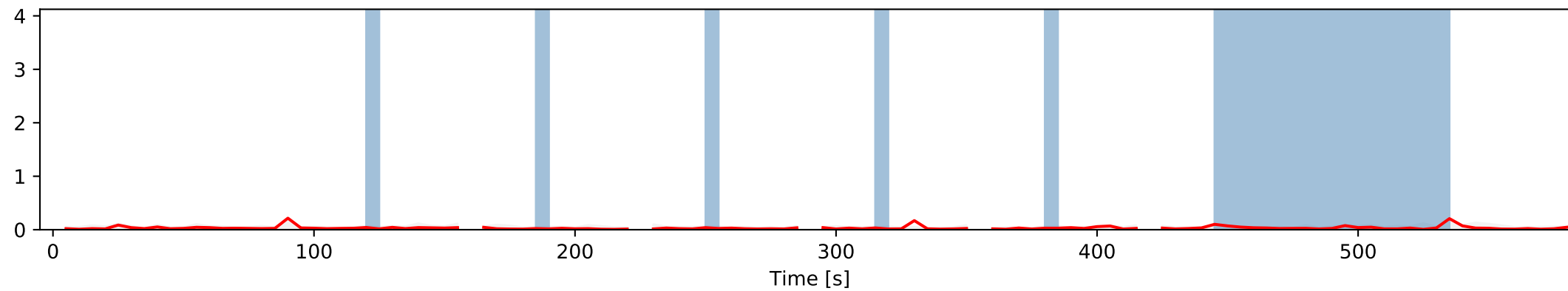
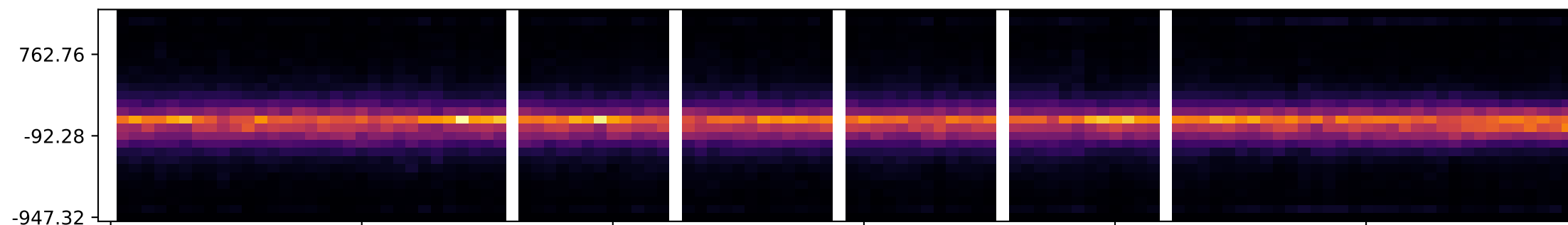
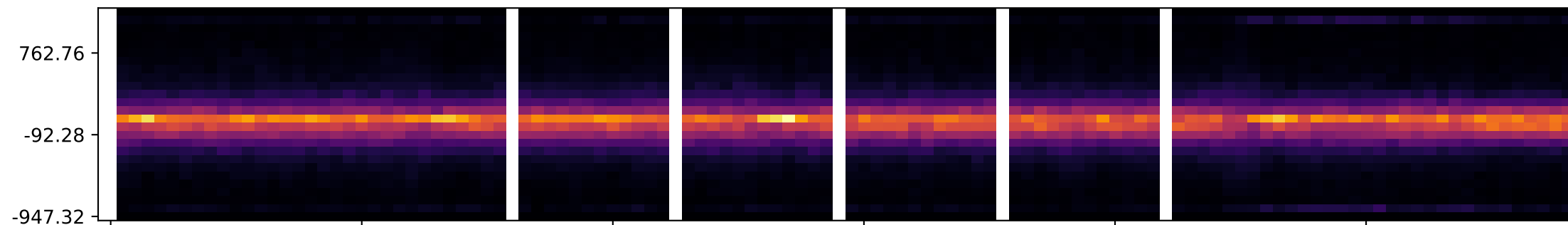
relative_to_neck_angular_velocity_head_tip



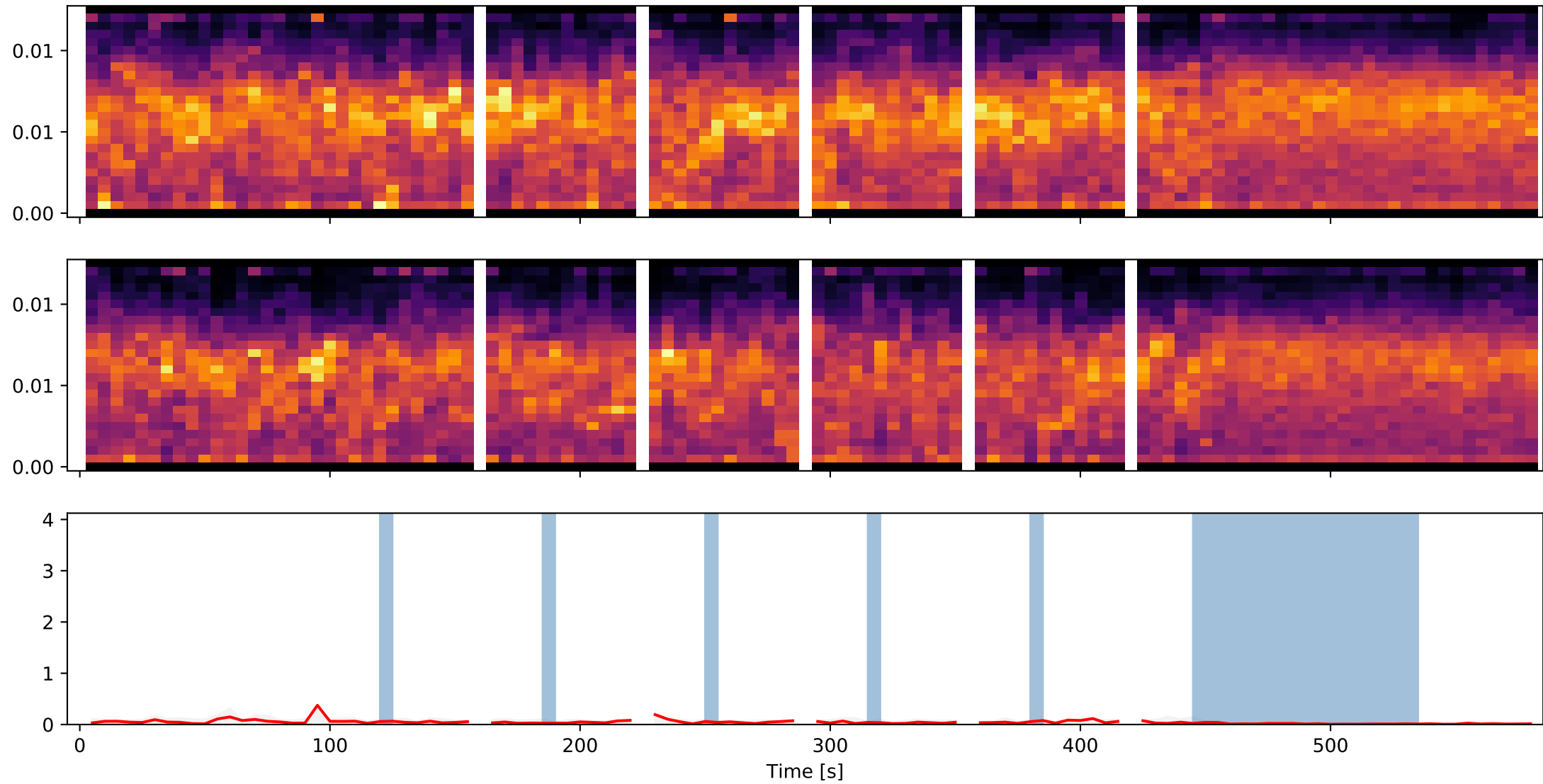
relative_to_body_angular_velocity_neck



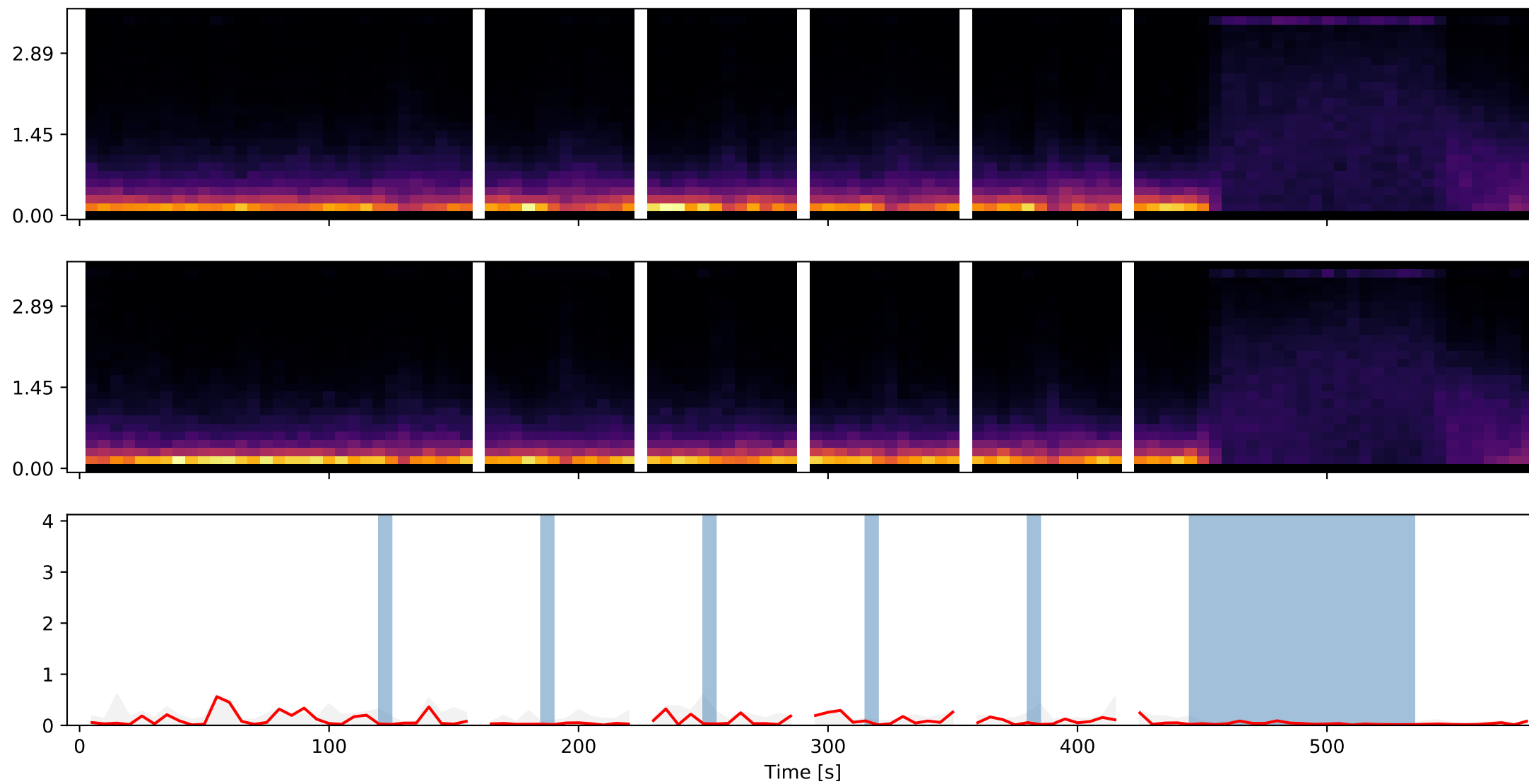
d_speed_head_tip



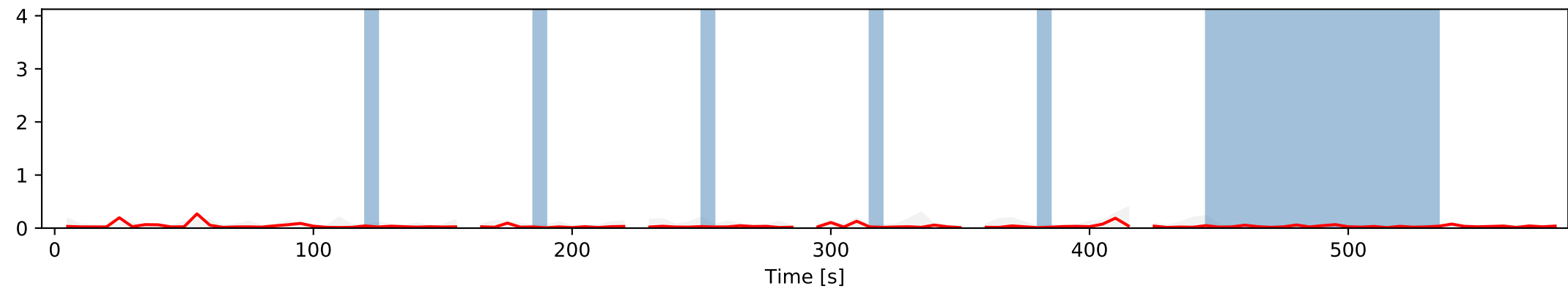
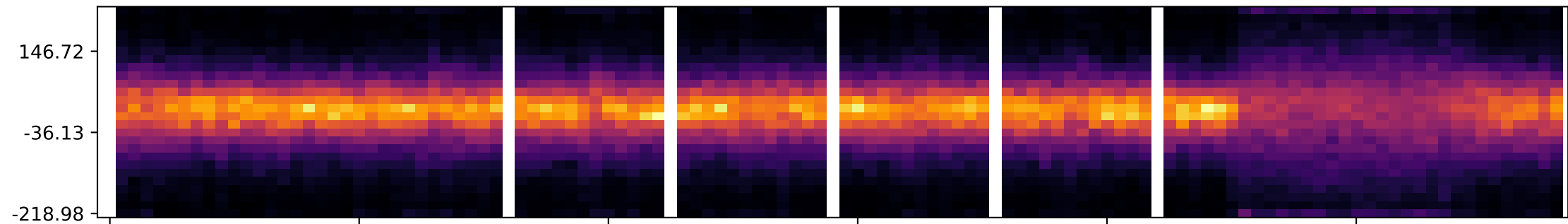
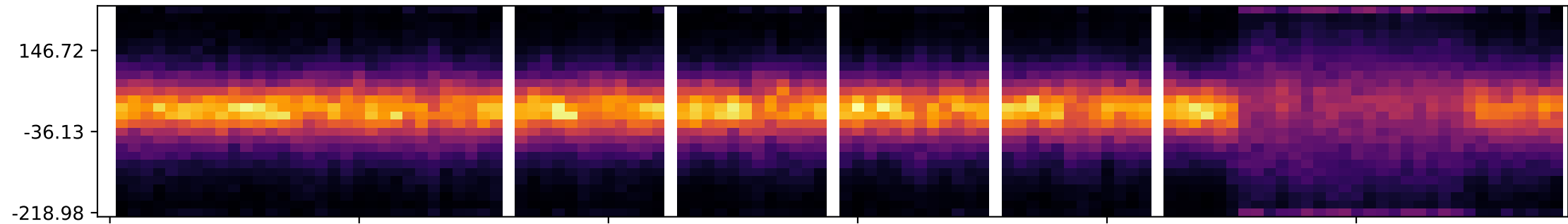
curvature_midbody



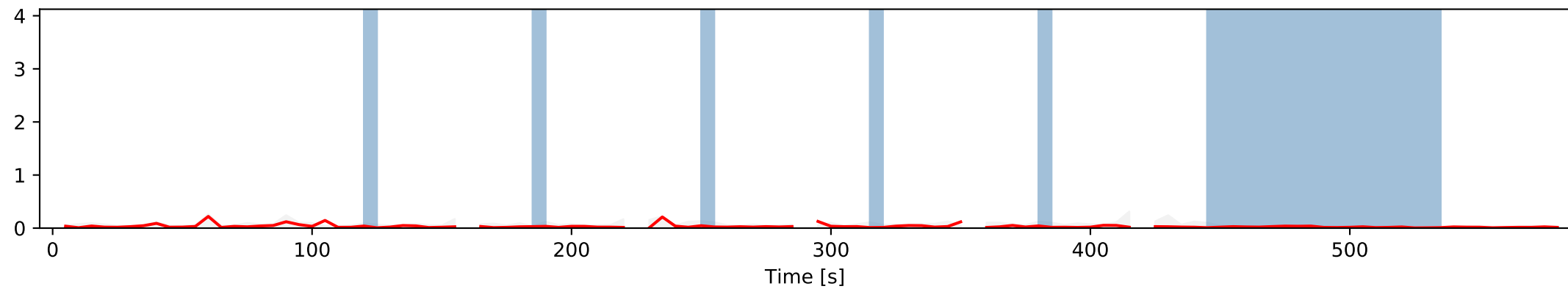
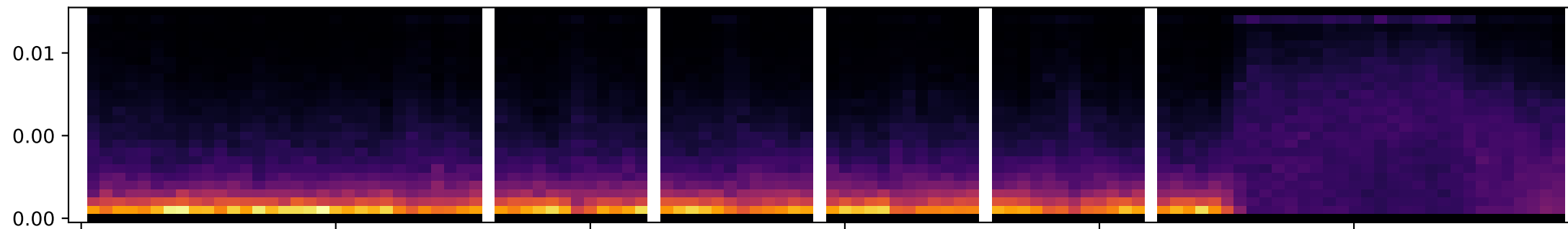
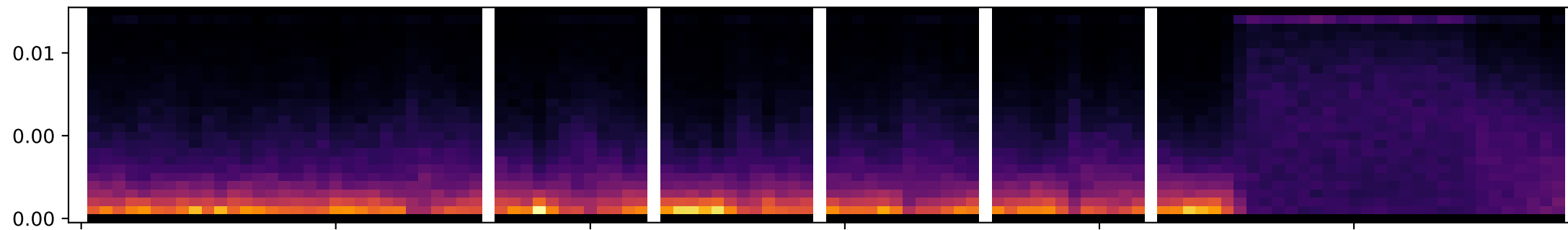
d_relative_to_body_angular_velocity_neck



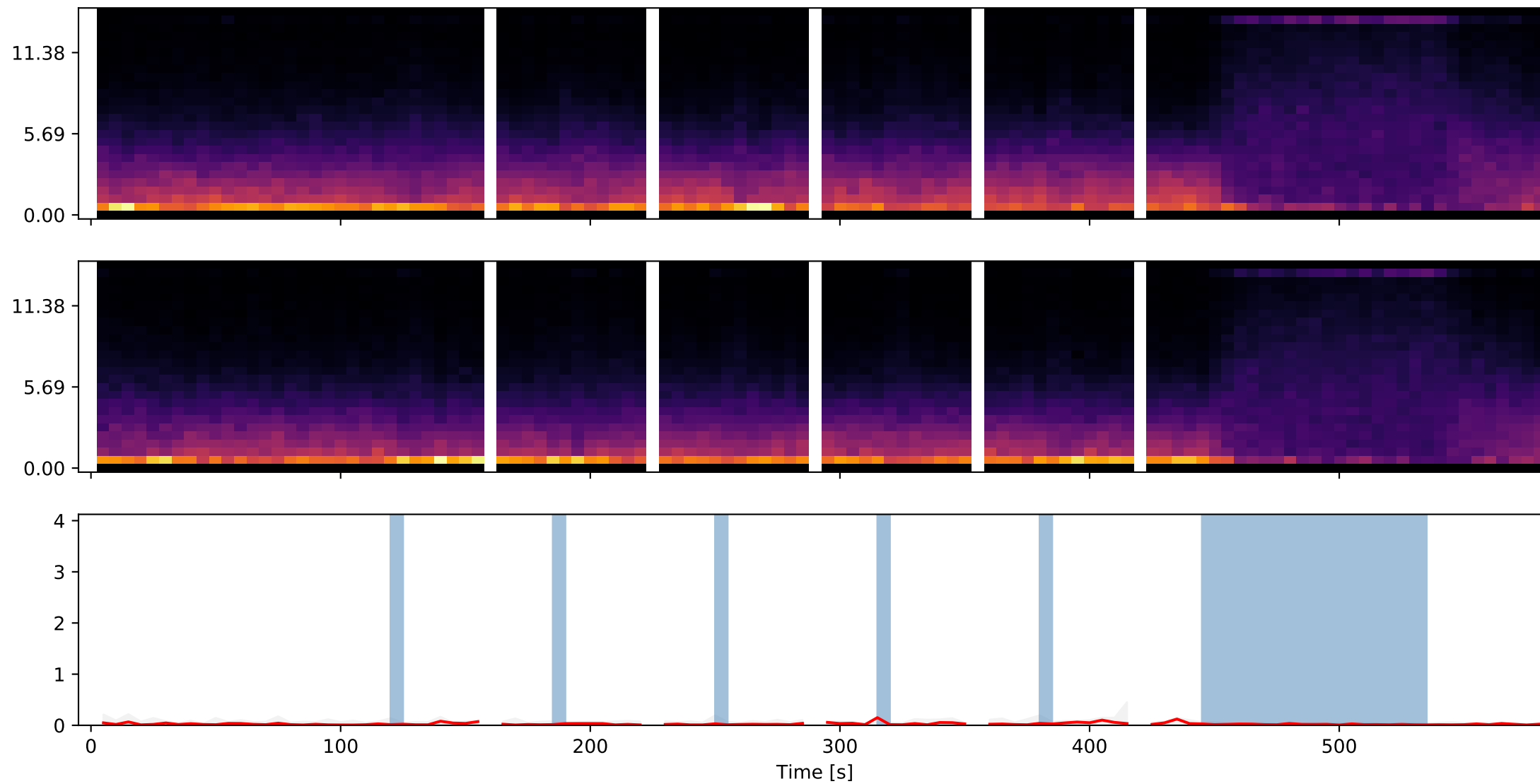
d_major_axis



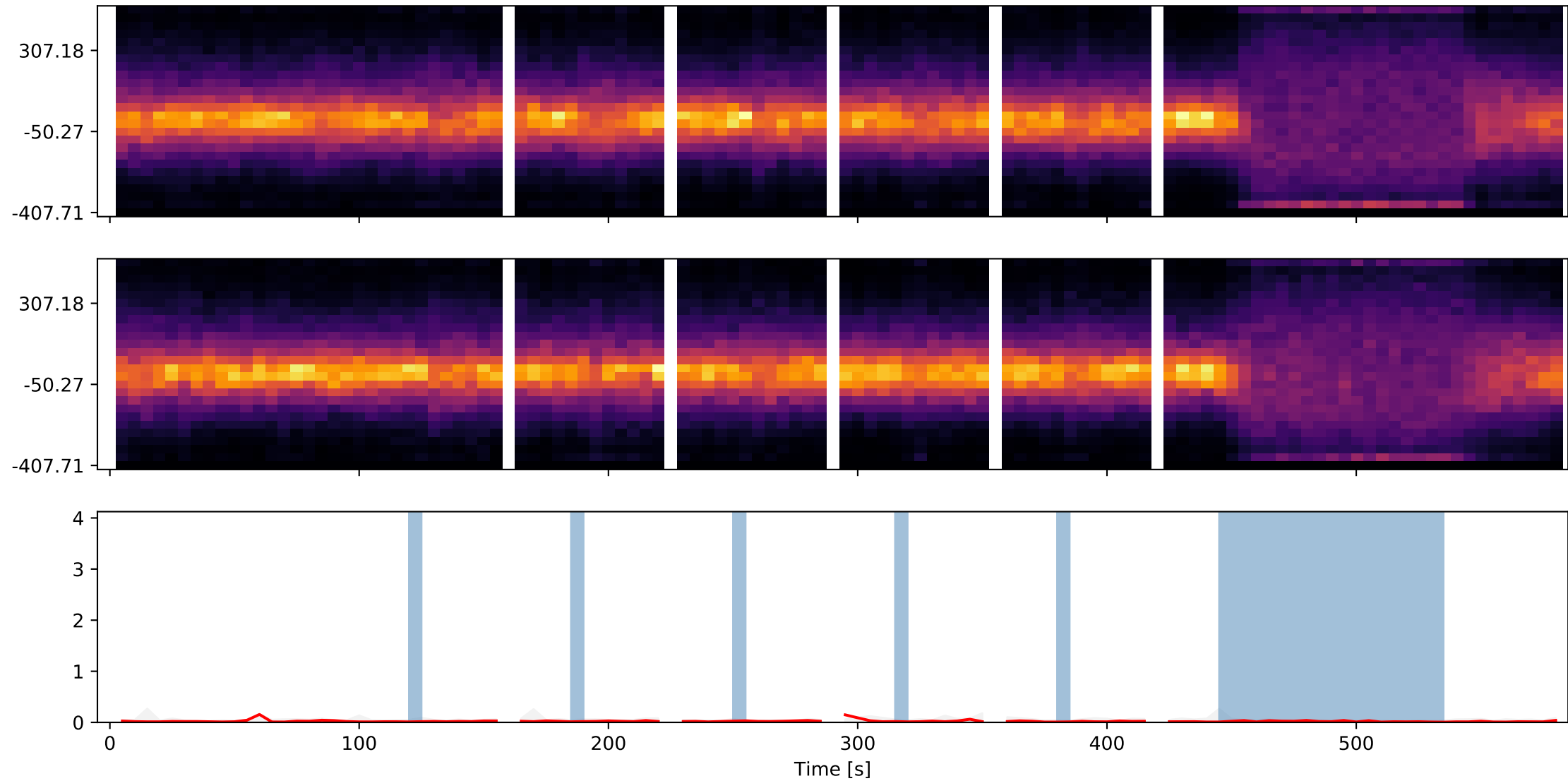
d_curvature_std_midbody



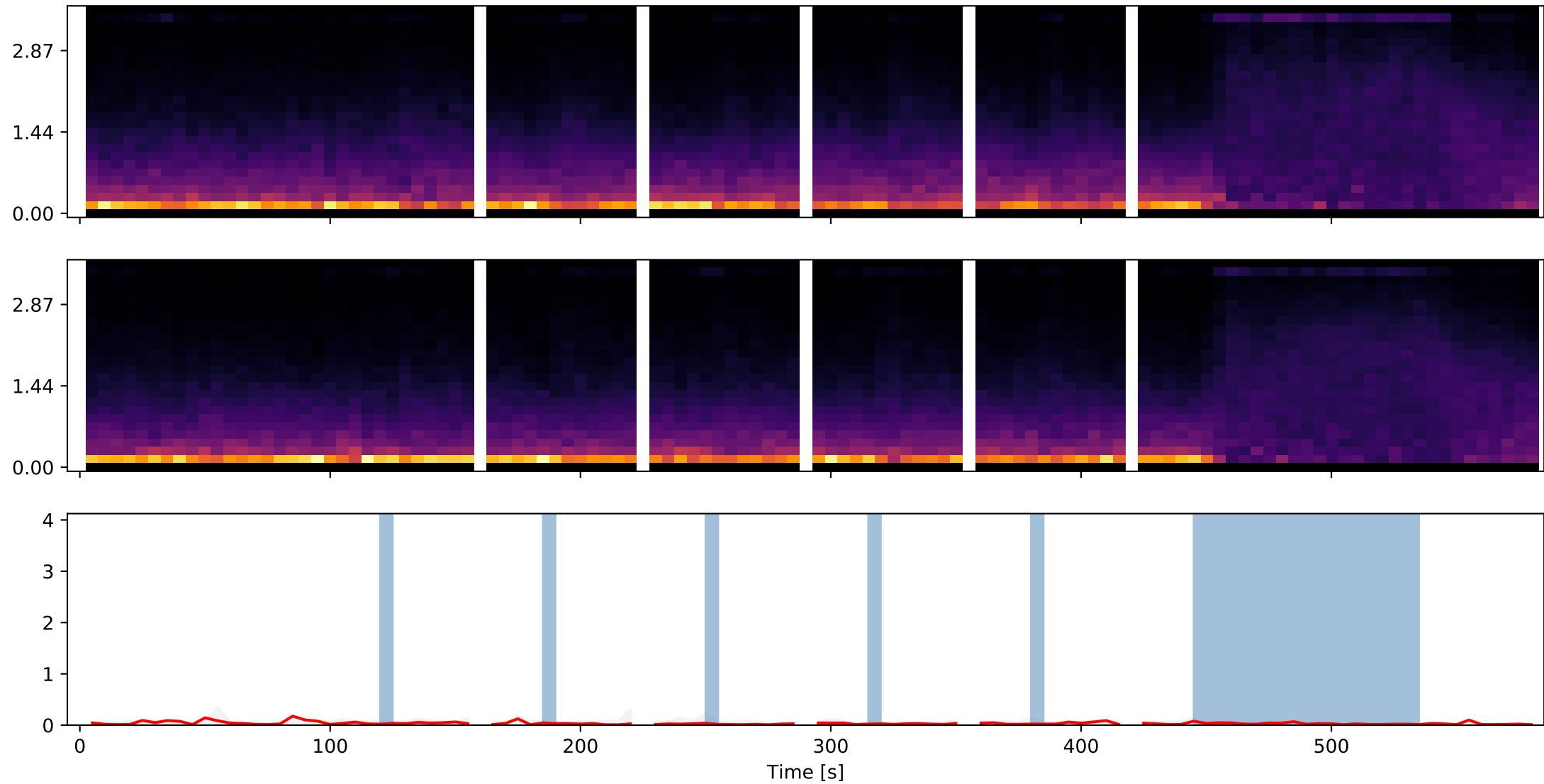
d_angular_velocity_head_base



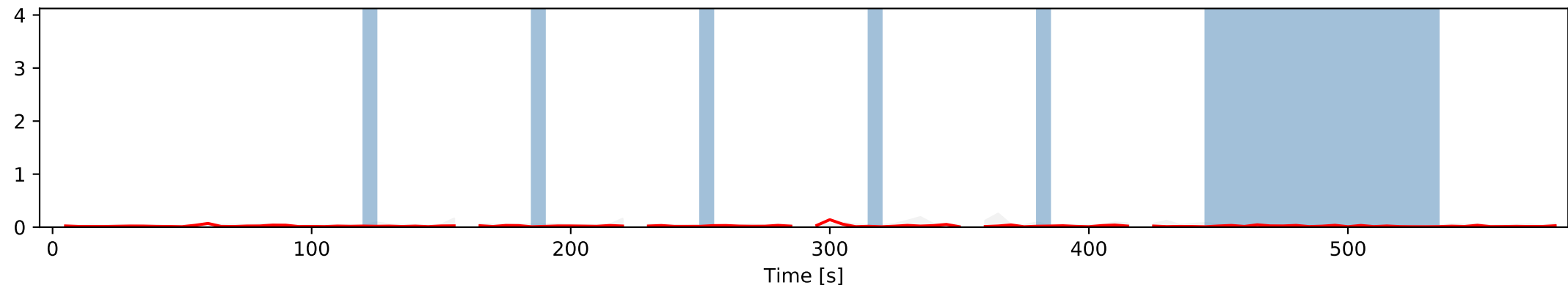
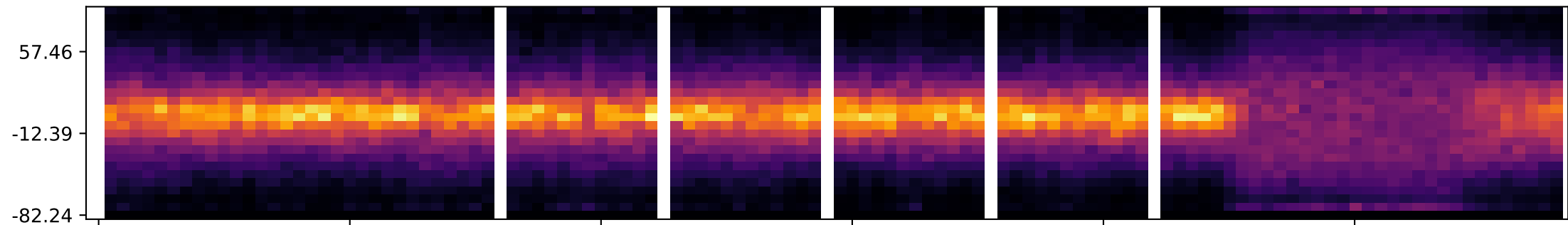
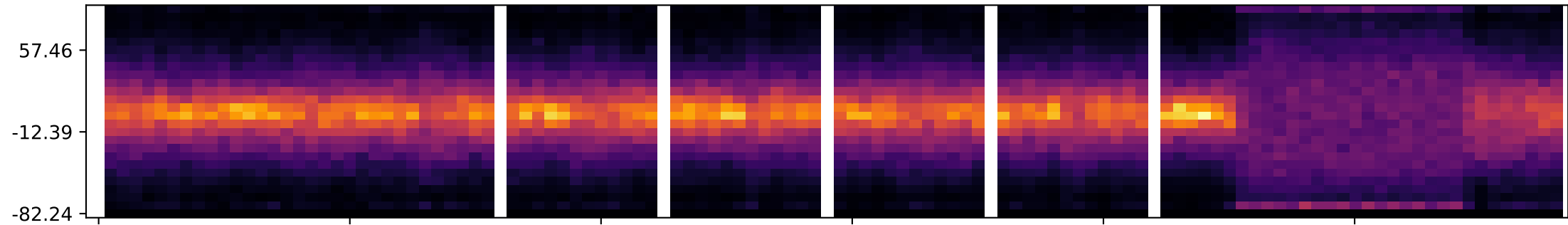
d_relative_to_neck_radial_velocity_head_tip



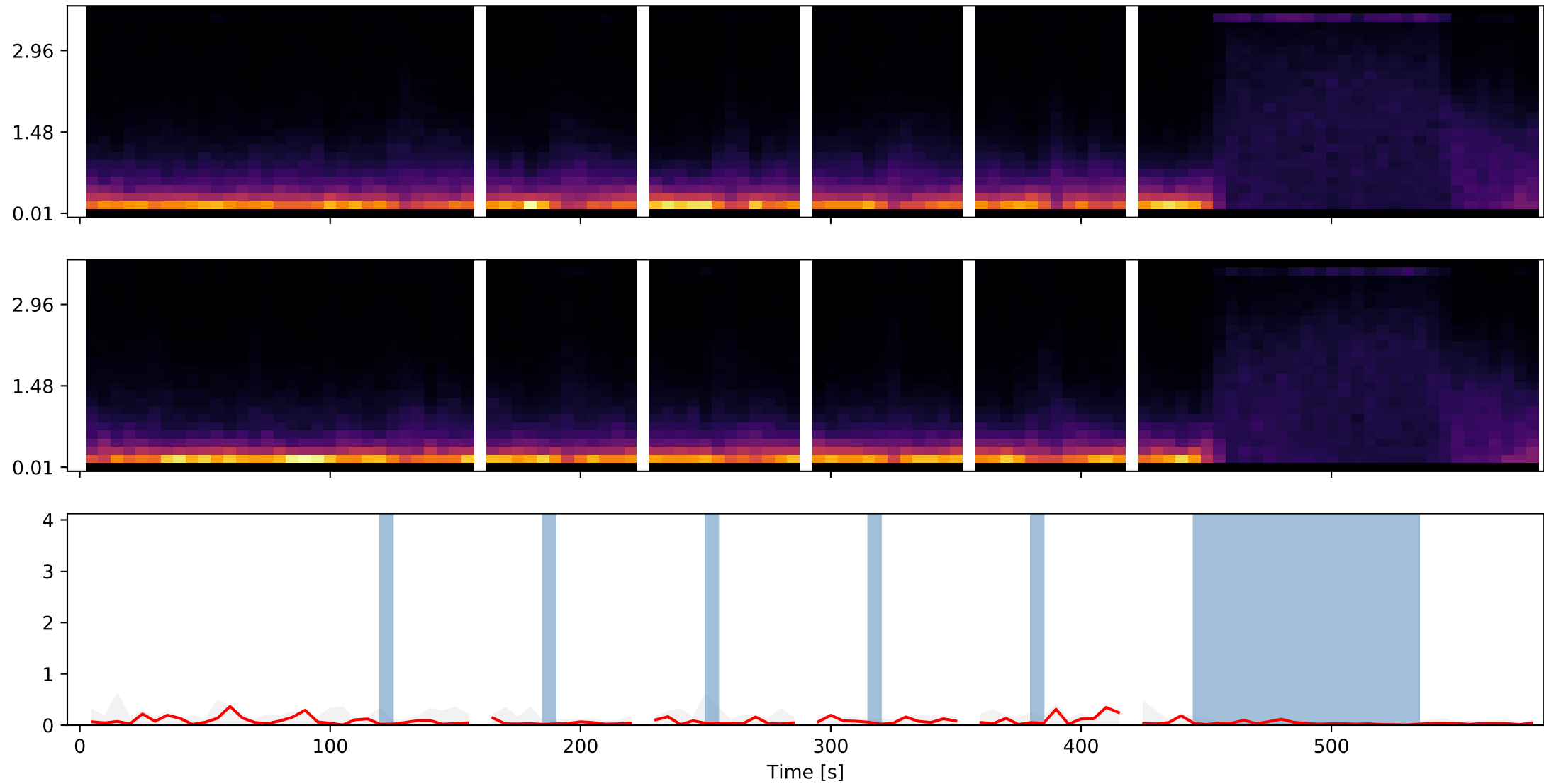
angular_velocity_tail_tip



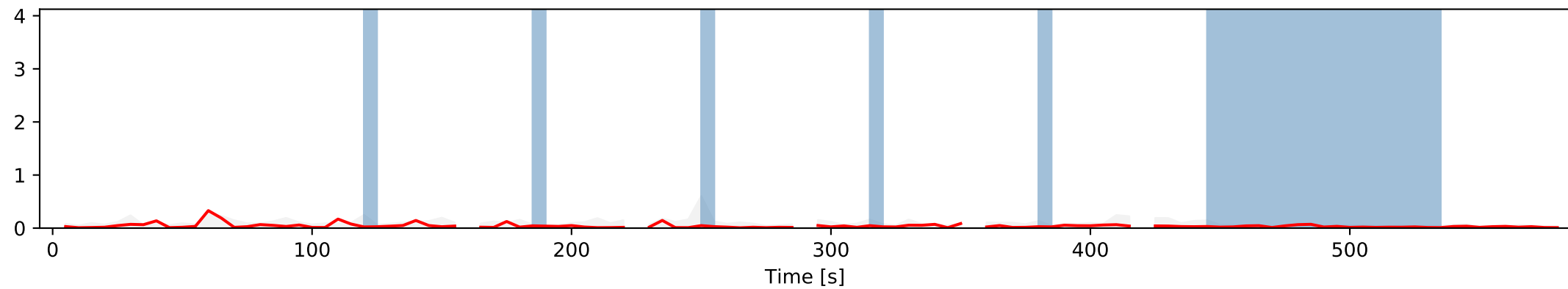
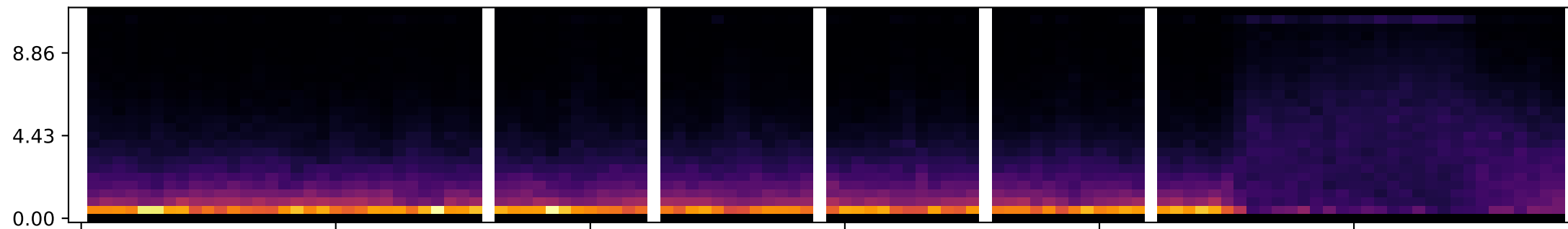
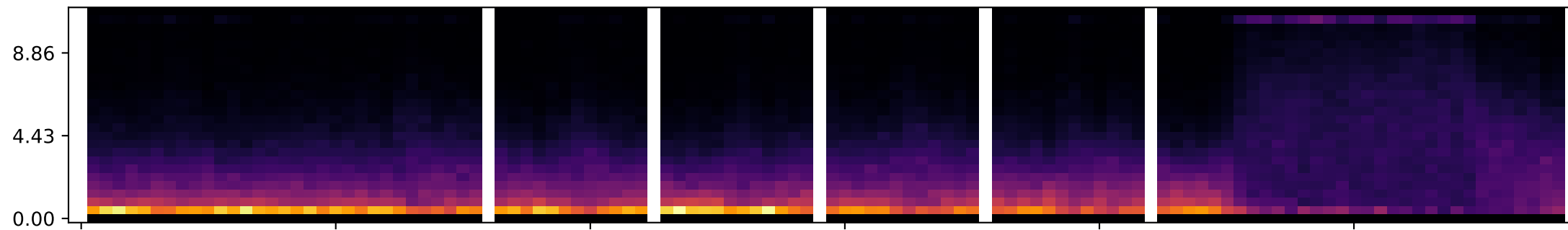
relative_to_neck_radial_velocity_head_tip



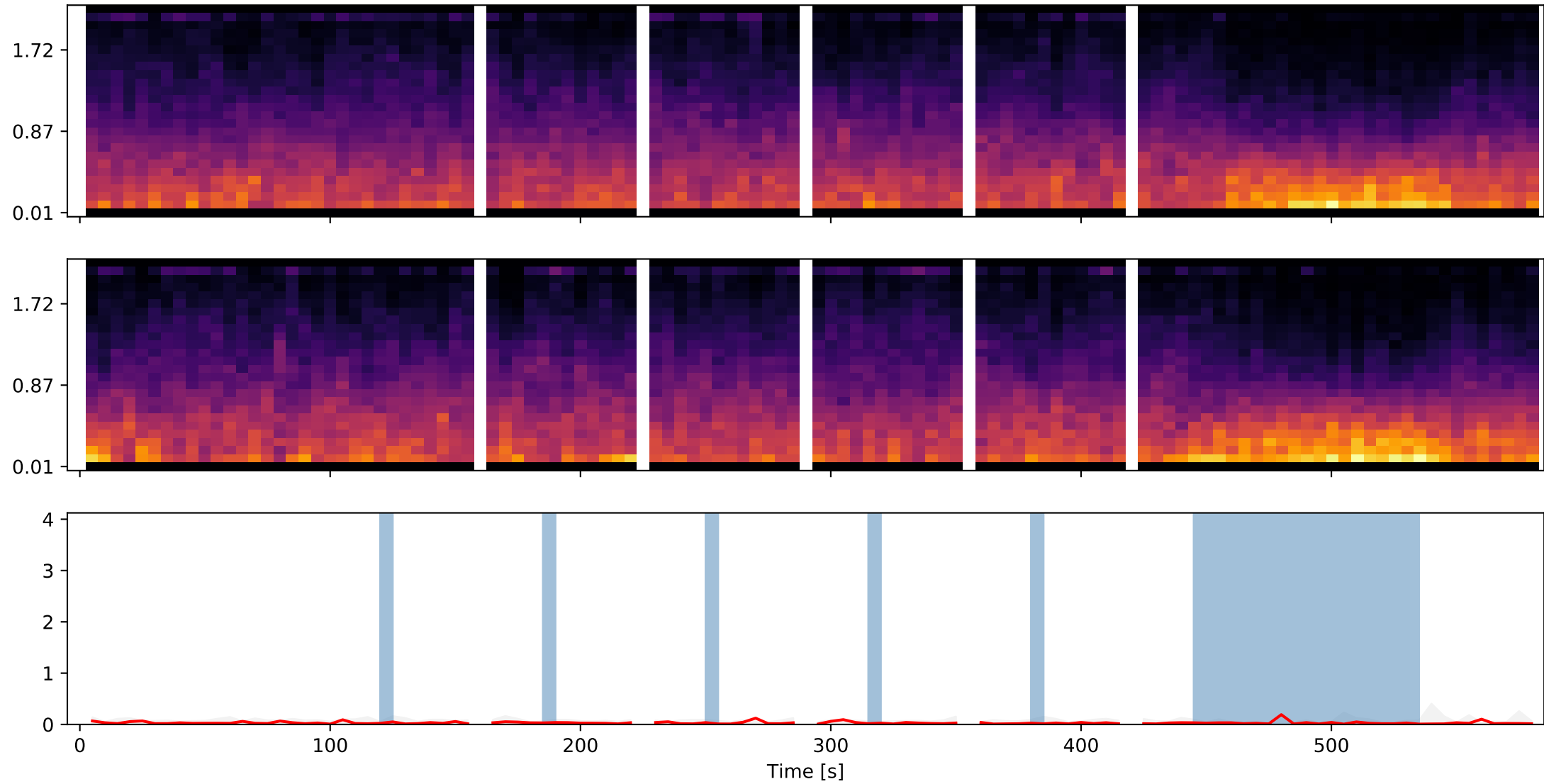
d_relative_to_body_angular_velocity_hips



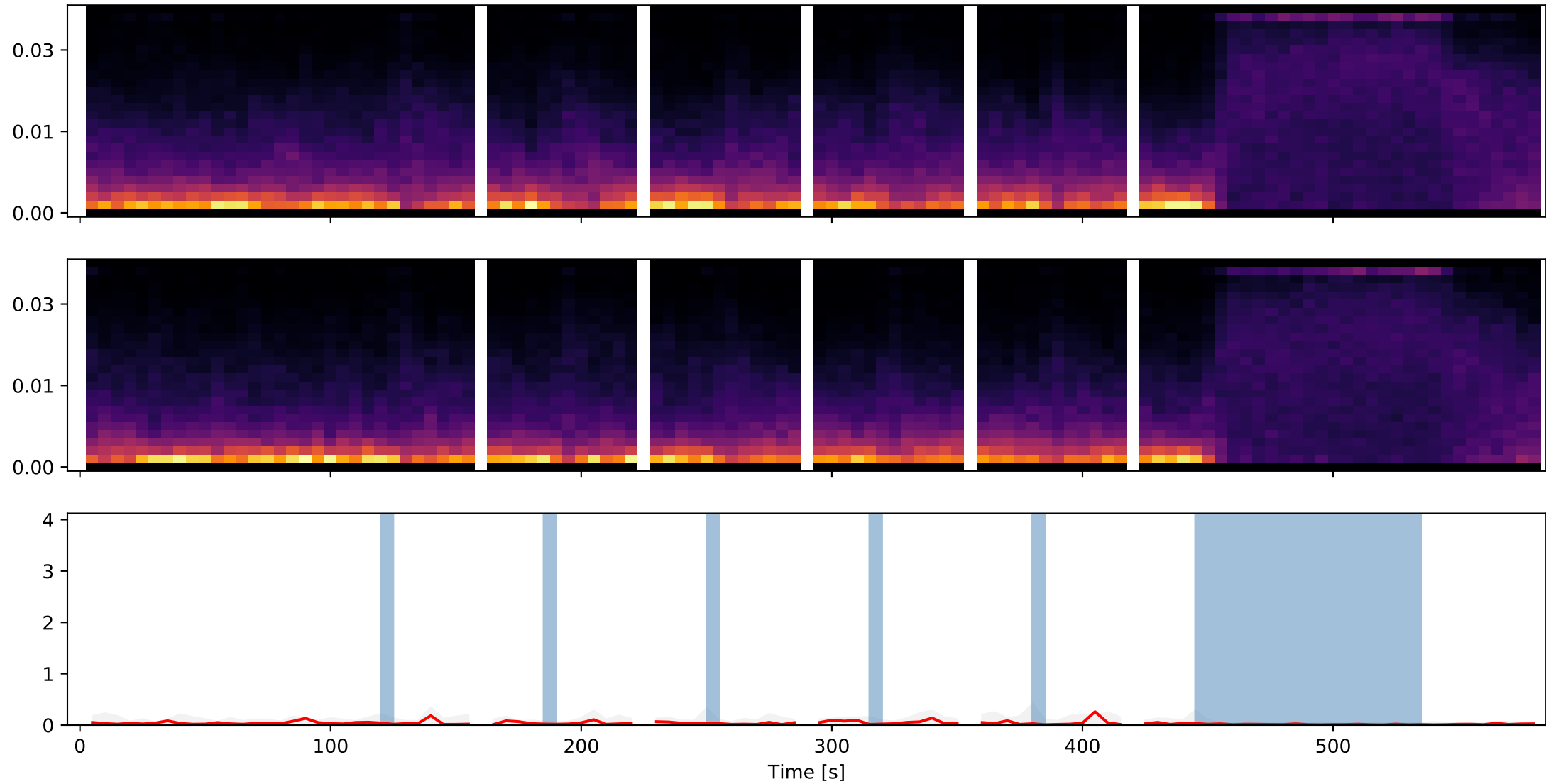
d_angular_velocity_tail_base



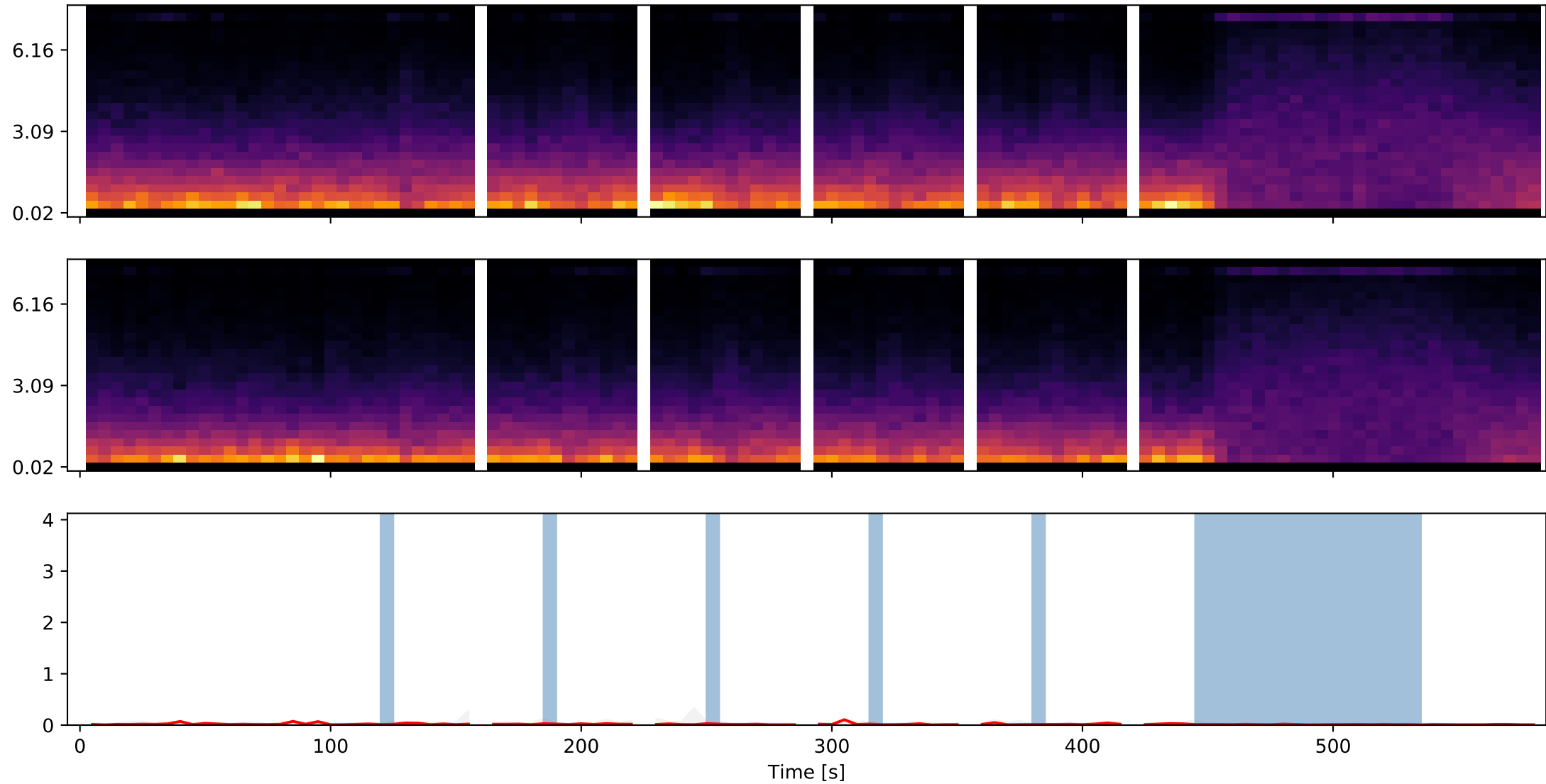
eigen_projection_5



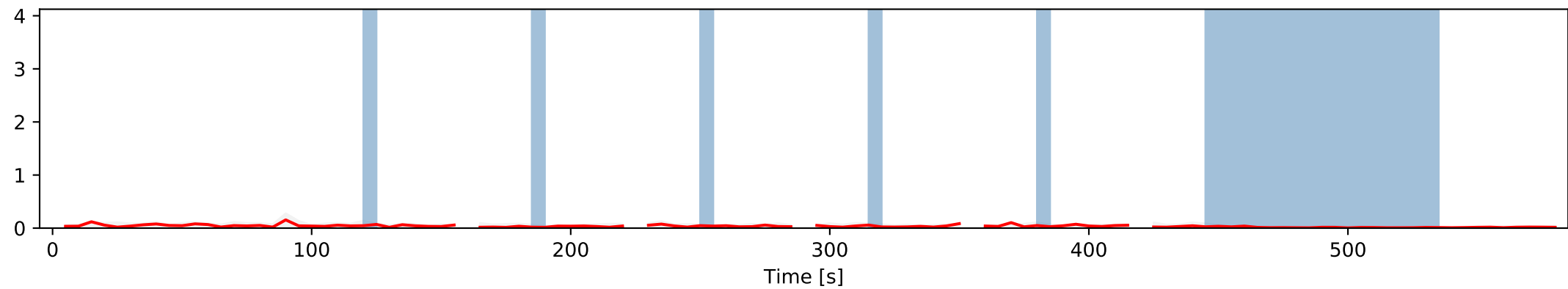
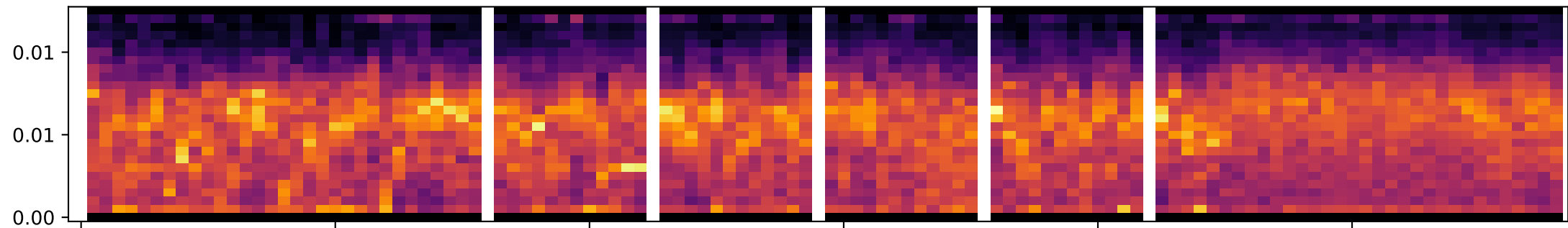
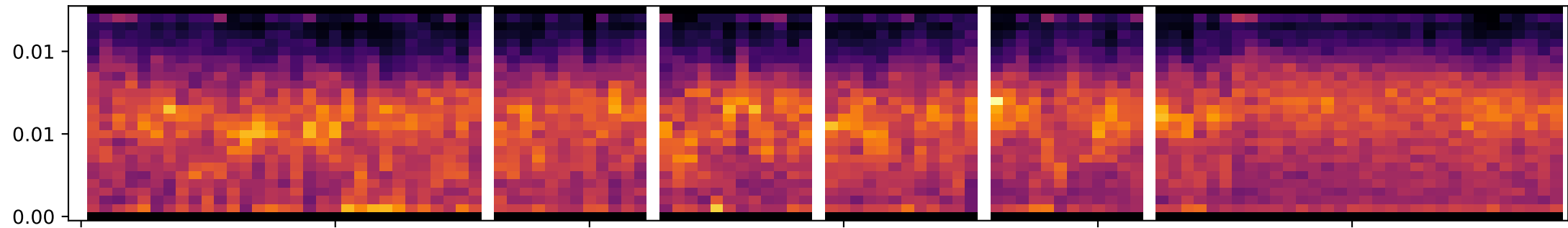
d_curvature_mean_neck



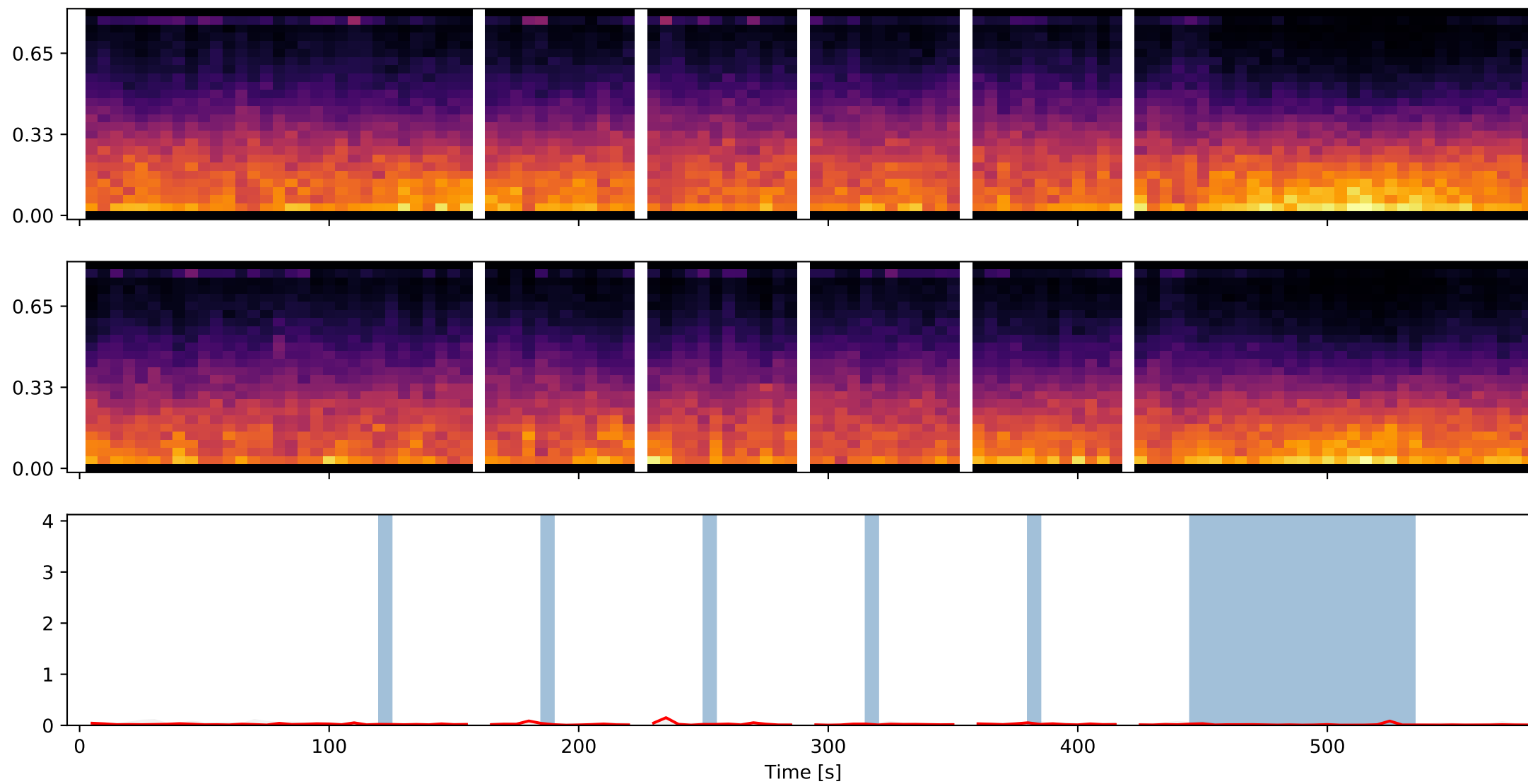
d_relative_to_tail_base_angular_velocity_tail_tip



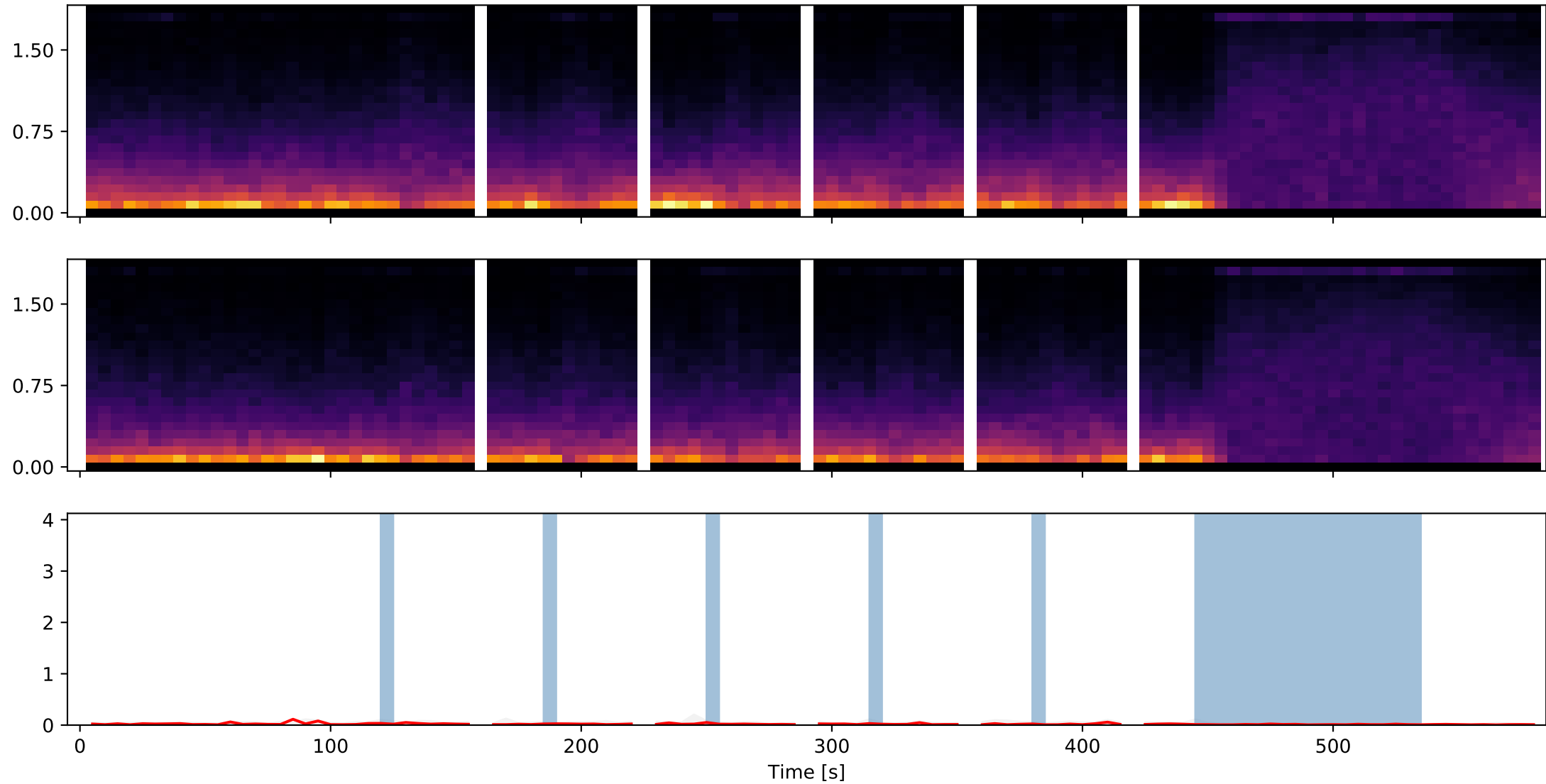
curvature_neck



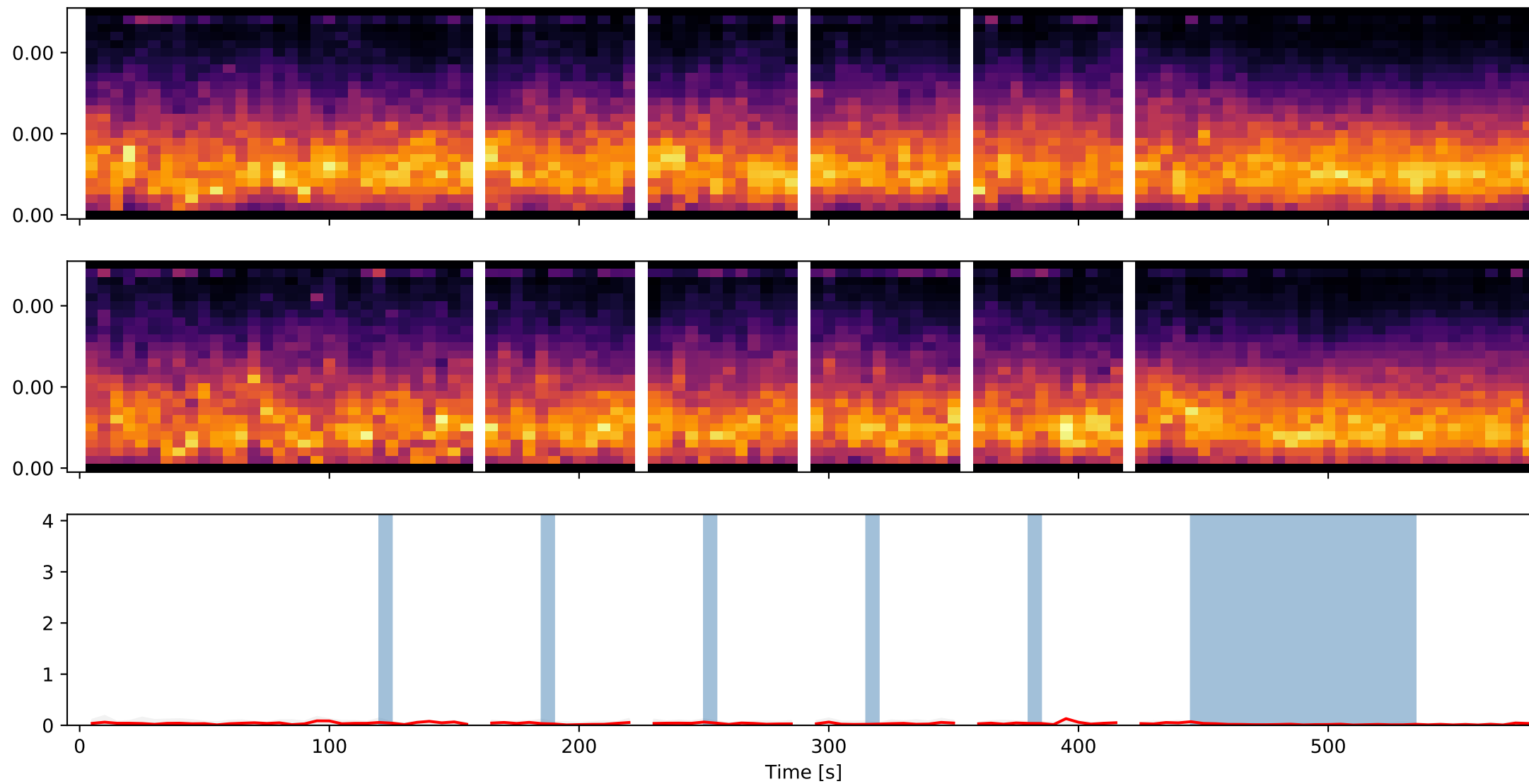
eigen_projection_7



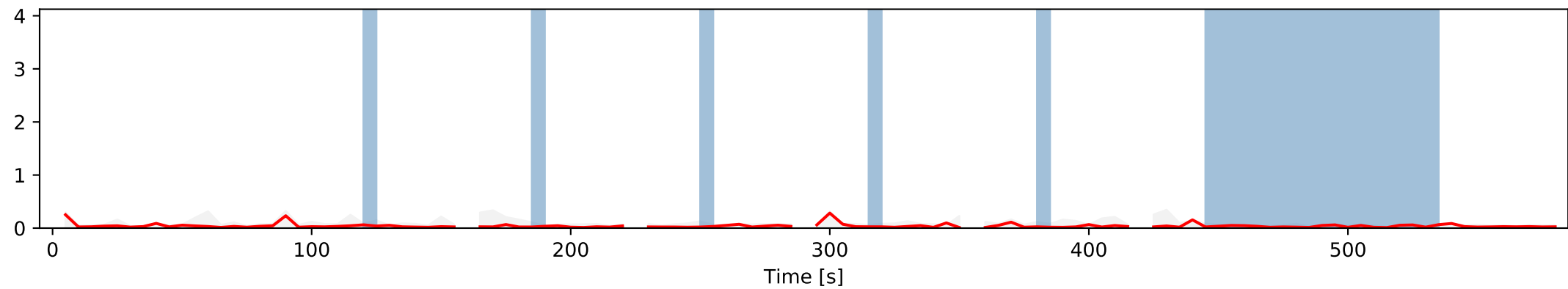
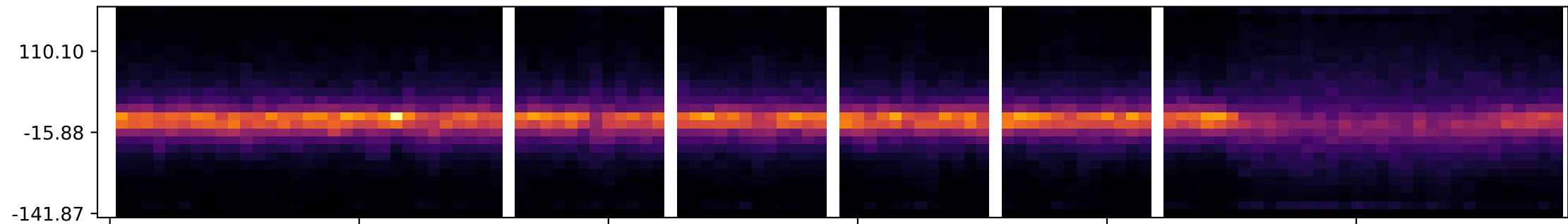
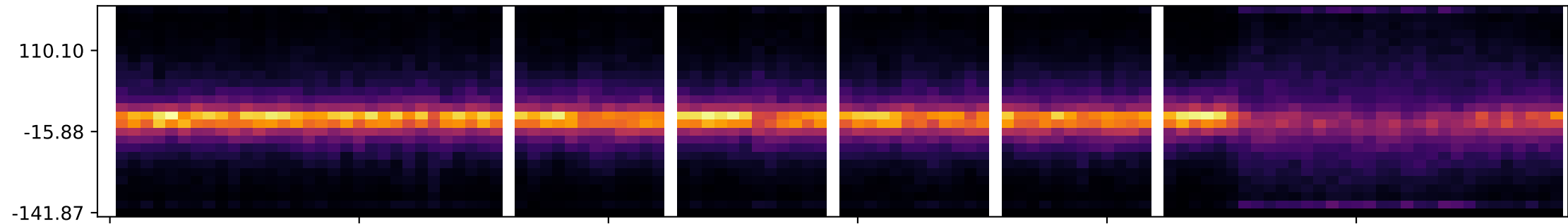
relative_to_tail_base_angular_velocity_tail_tip



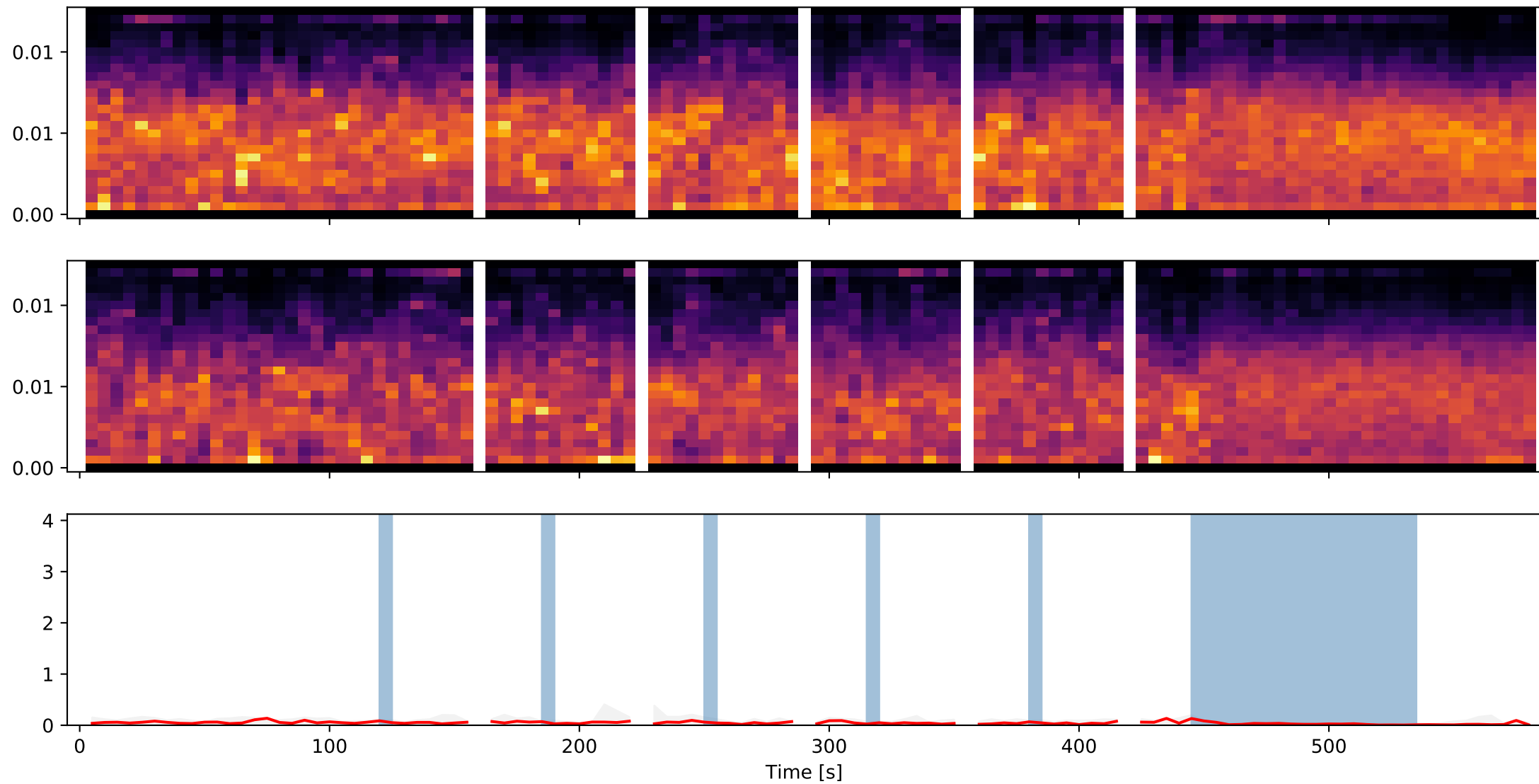
curvature_std_tail



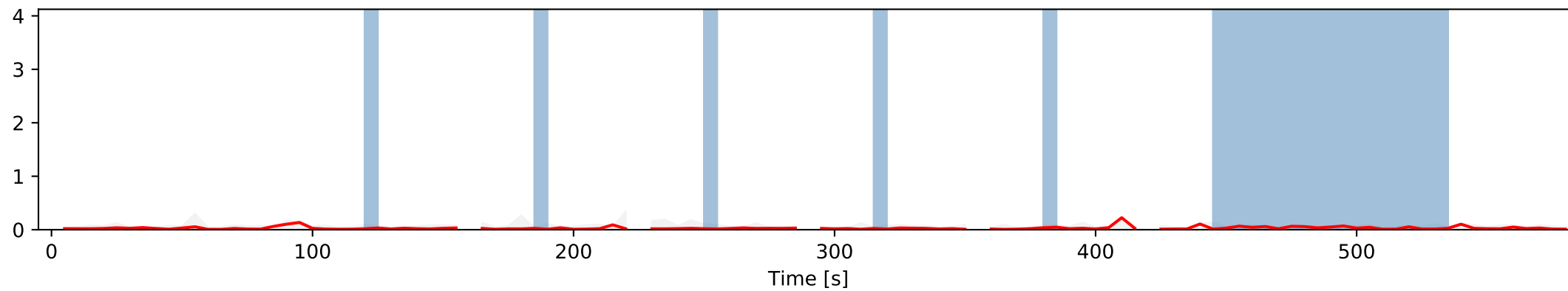
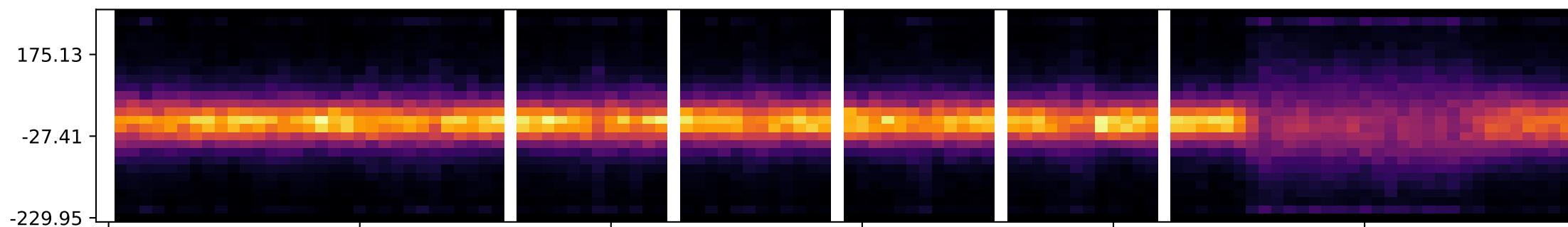
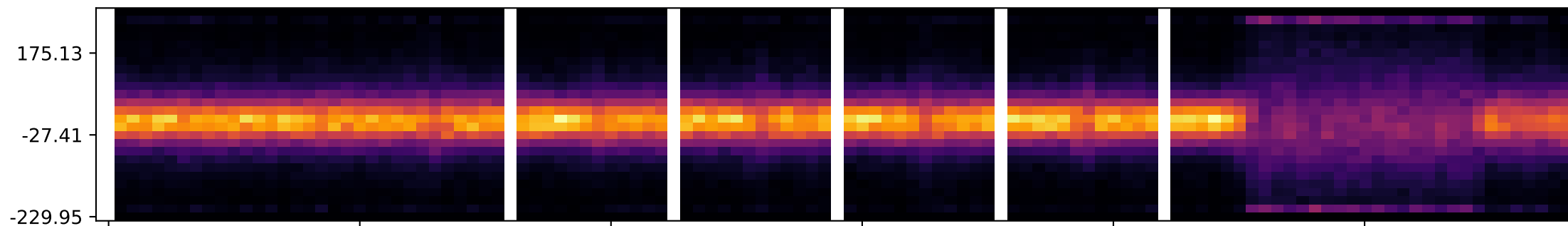
d_minor_axis



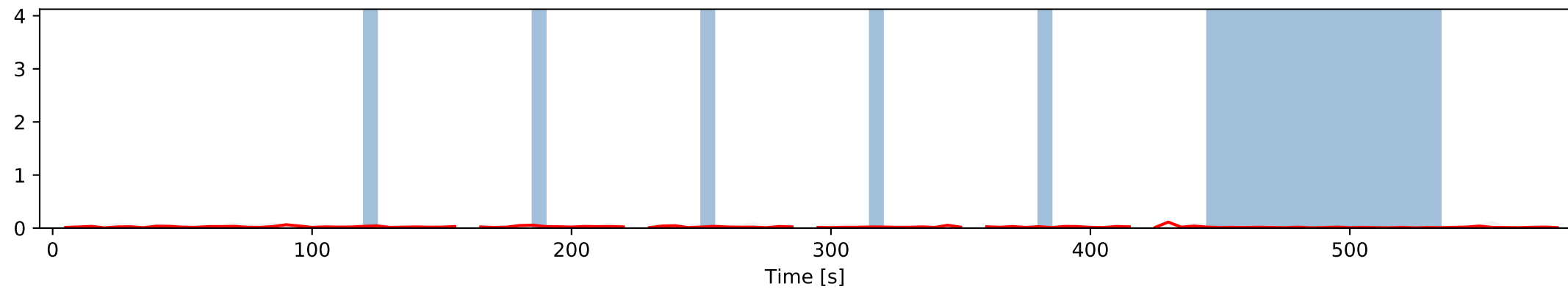
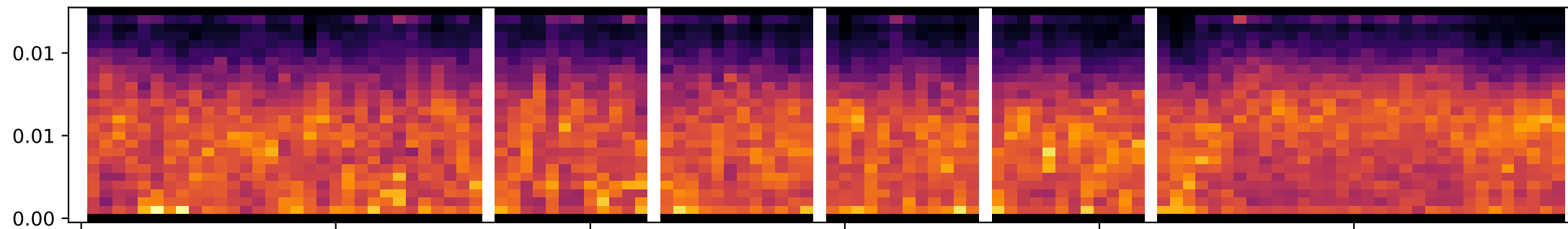
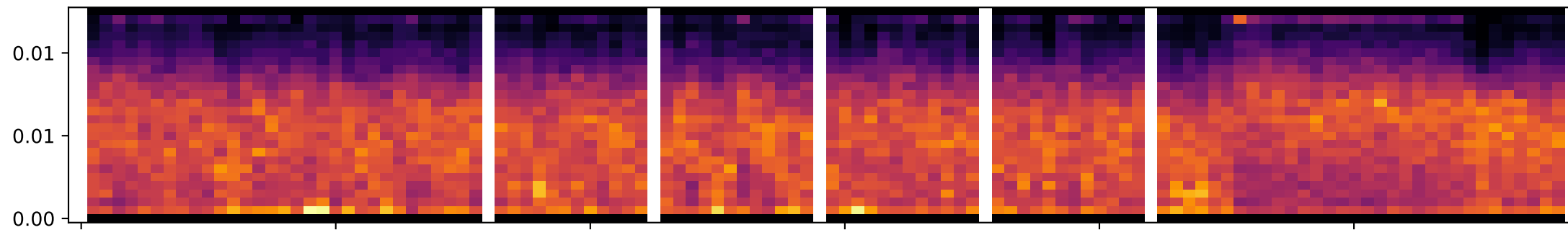
curvature_tail



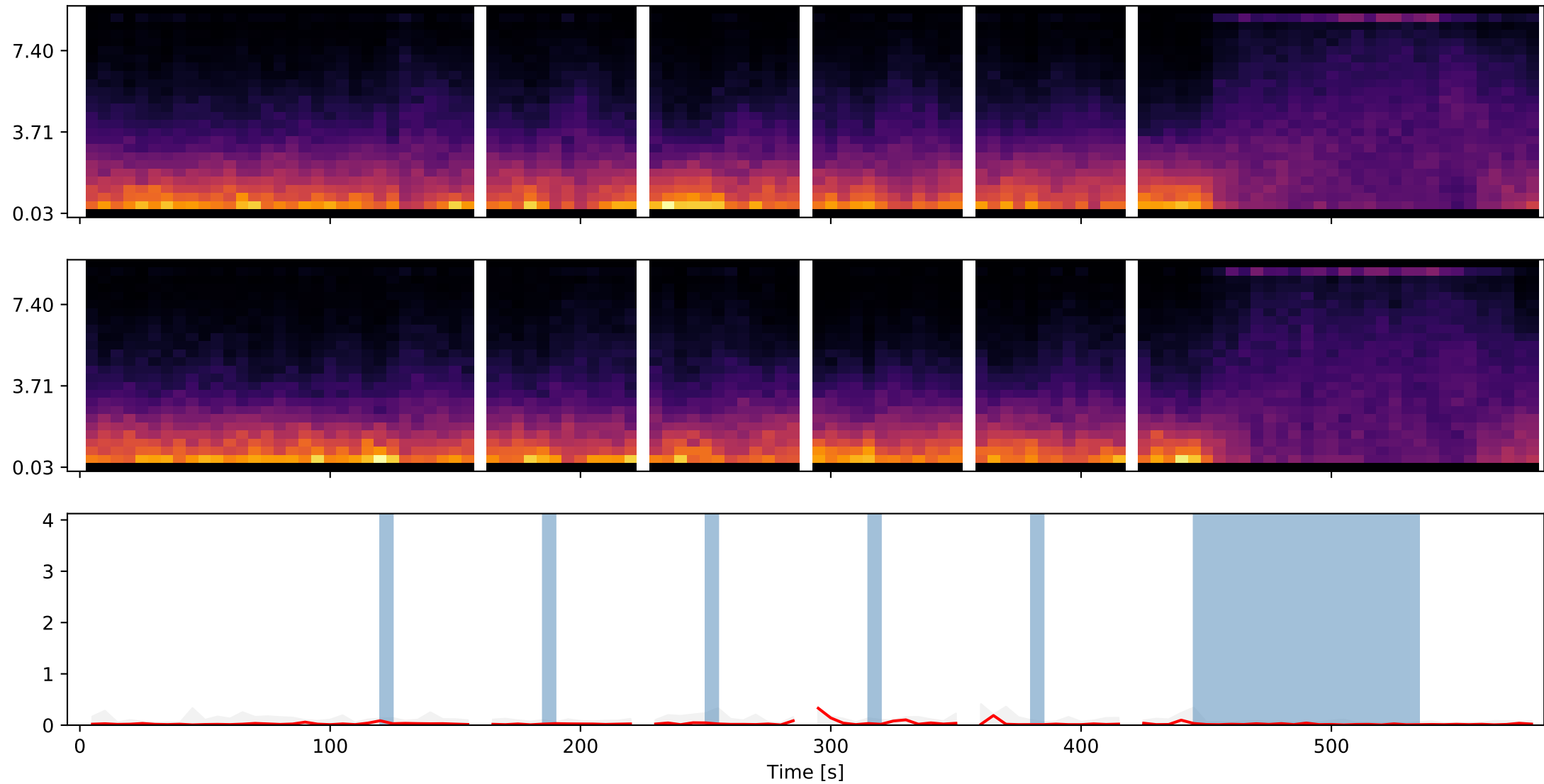
d_relative_to_body_radial_velocity_neck



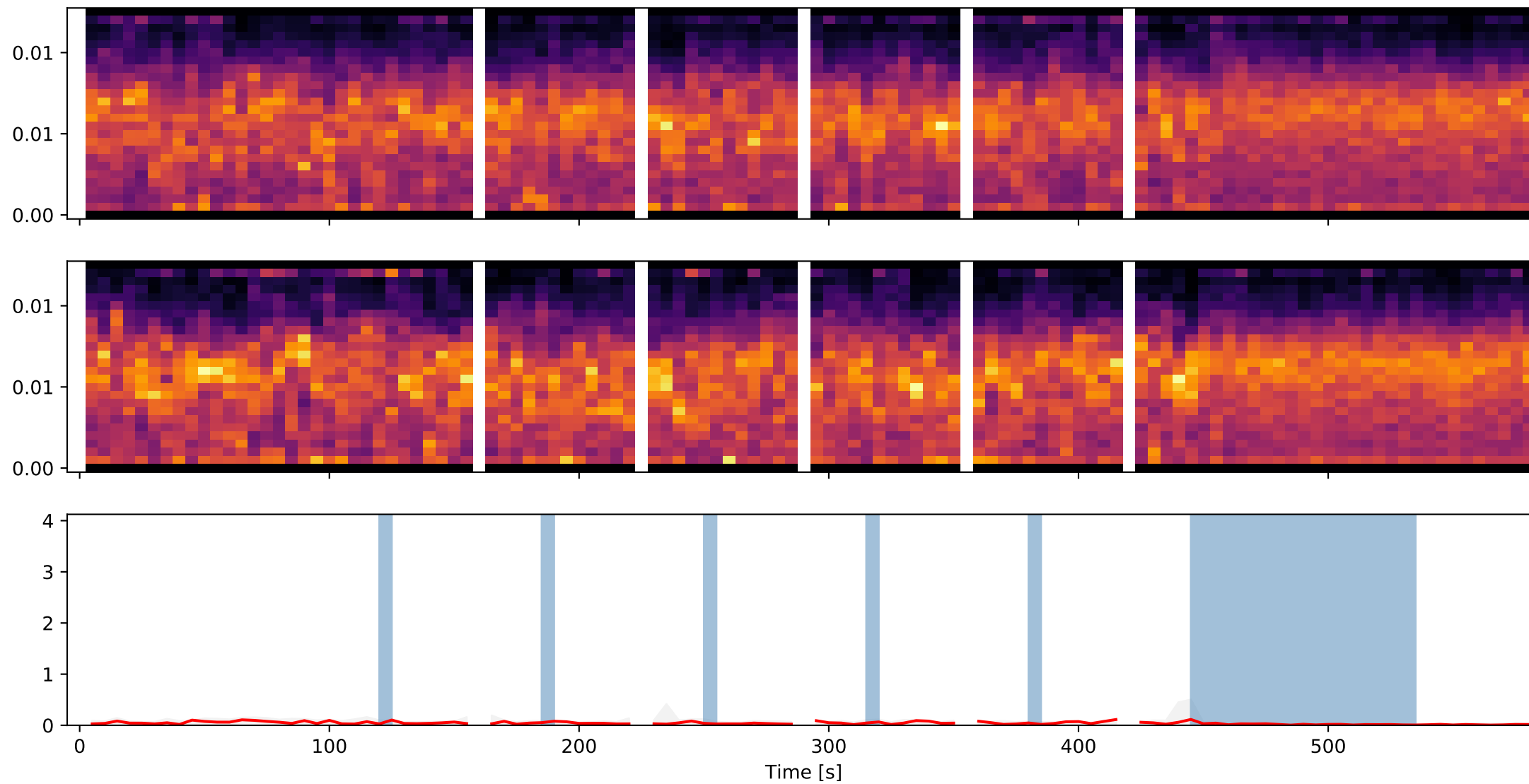
curvature_mean_head



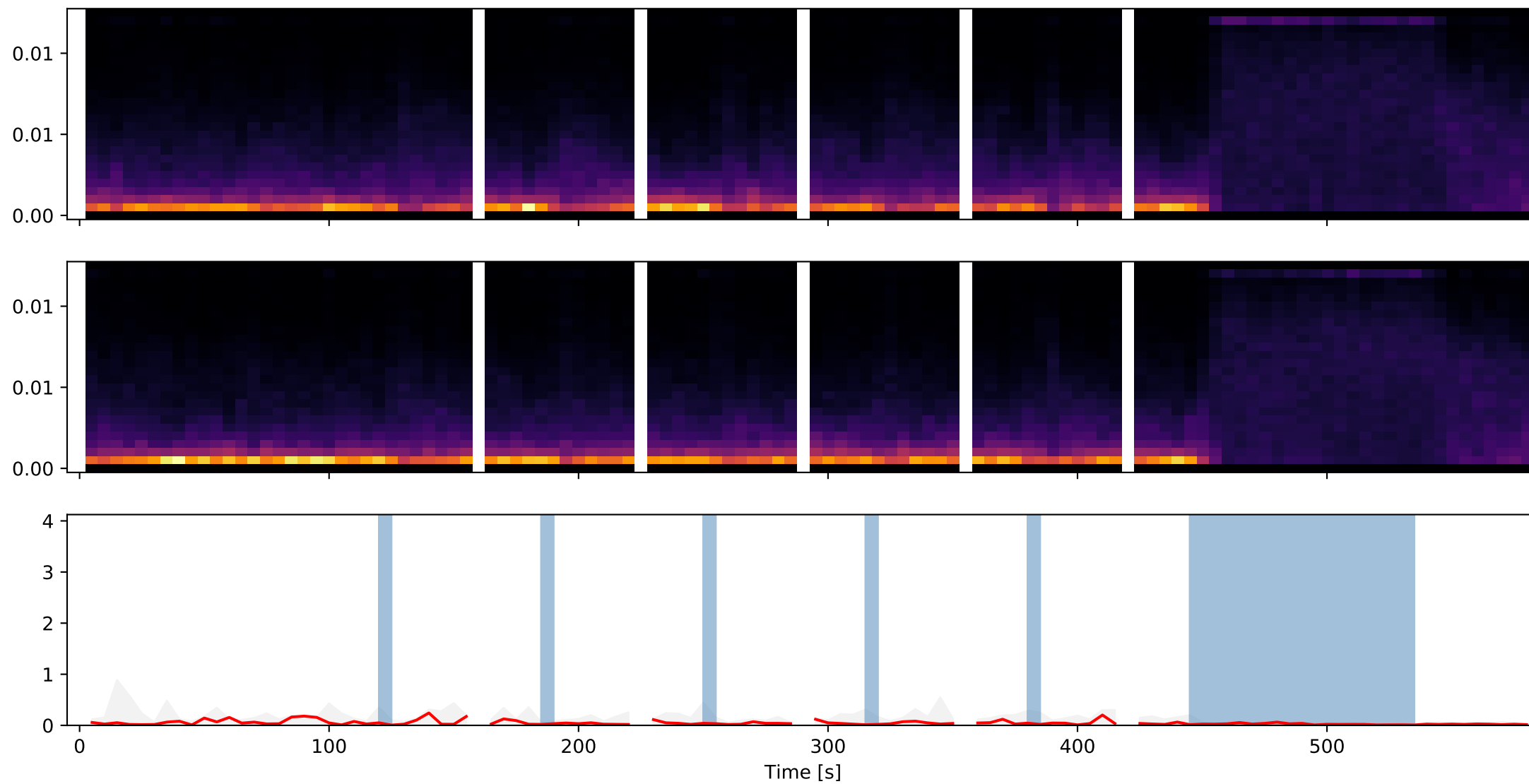
d_eigen_projection_4



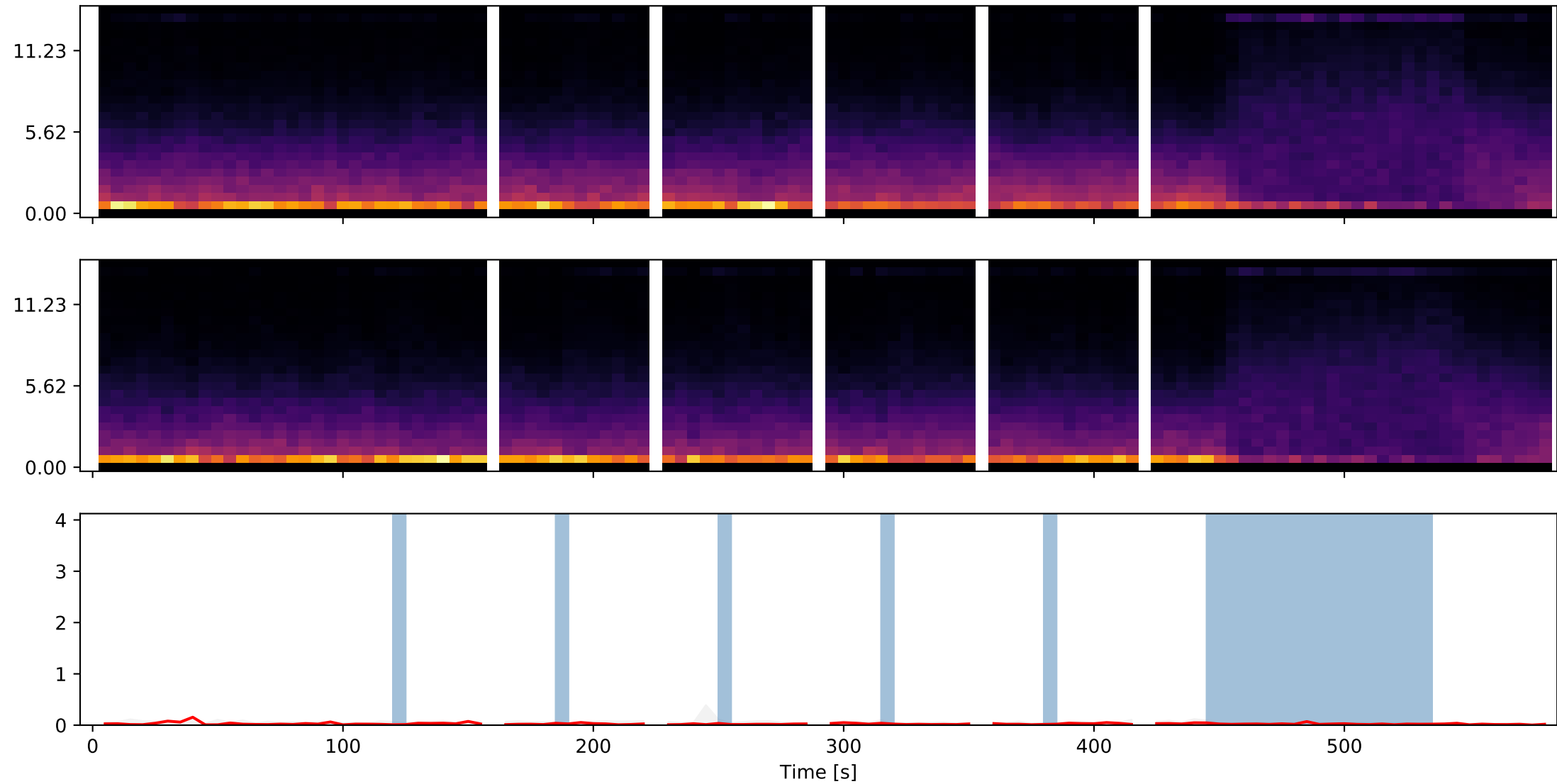
curvature_hips



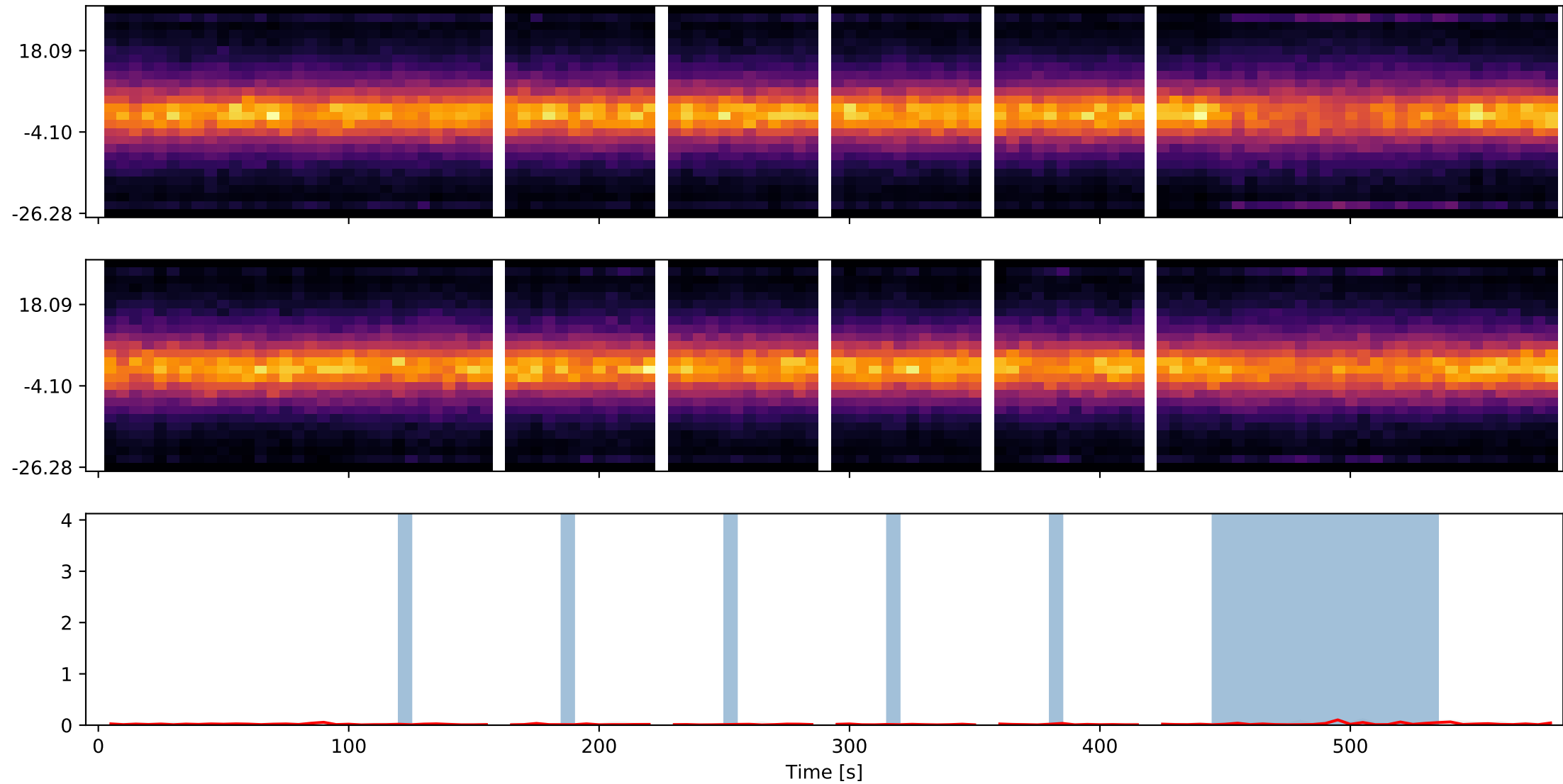
d_curvature_mean_midbody



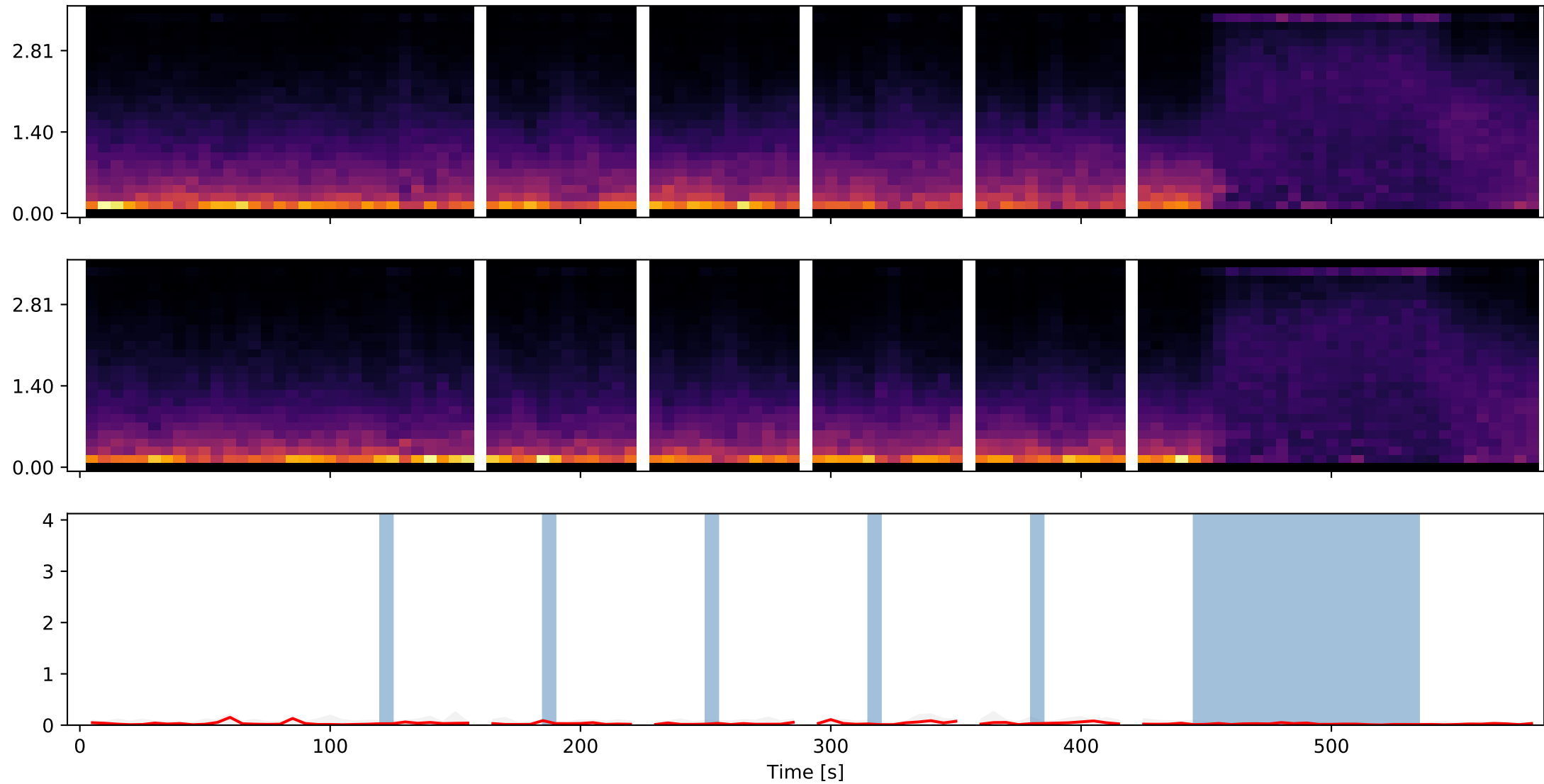
d_angular_velocity_tail_tip



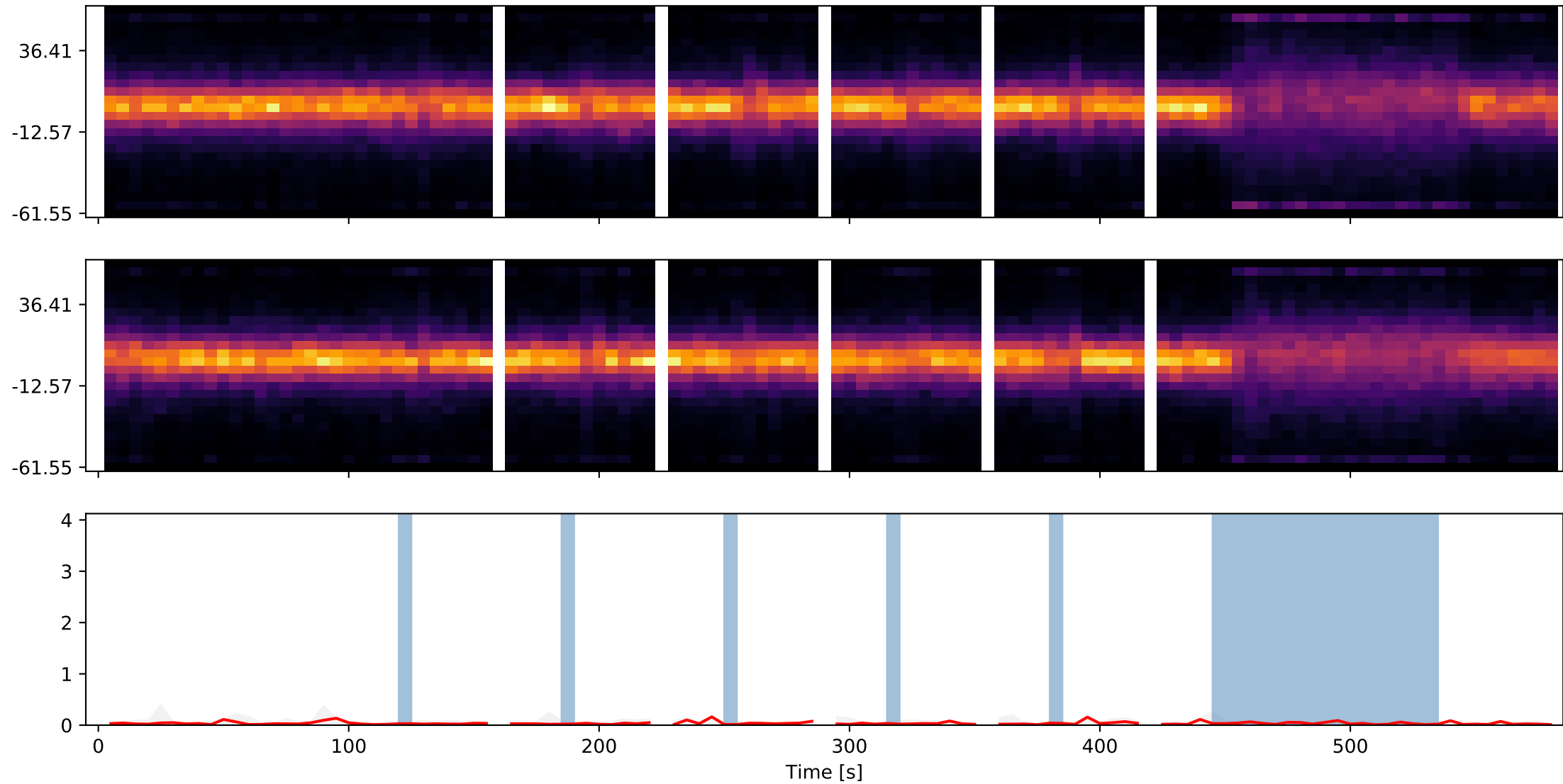
relative_to_head_base_radial_velocity_head_tip



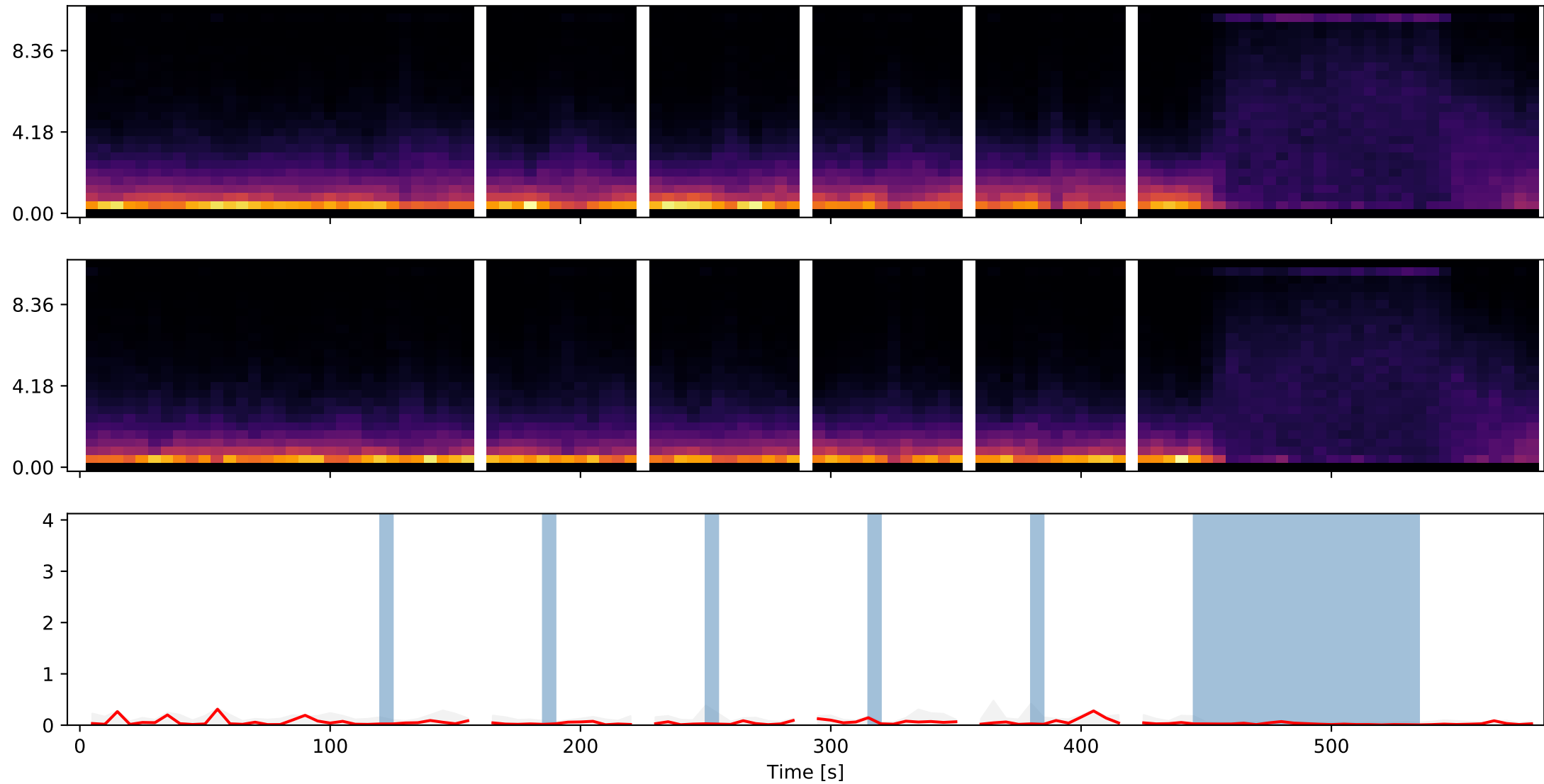
angular_velocity_head_base



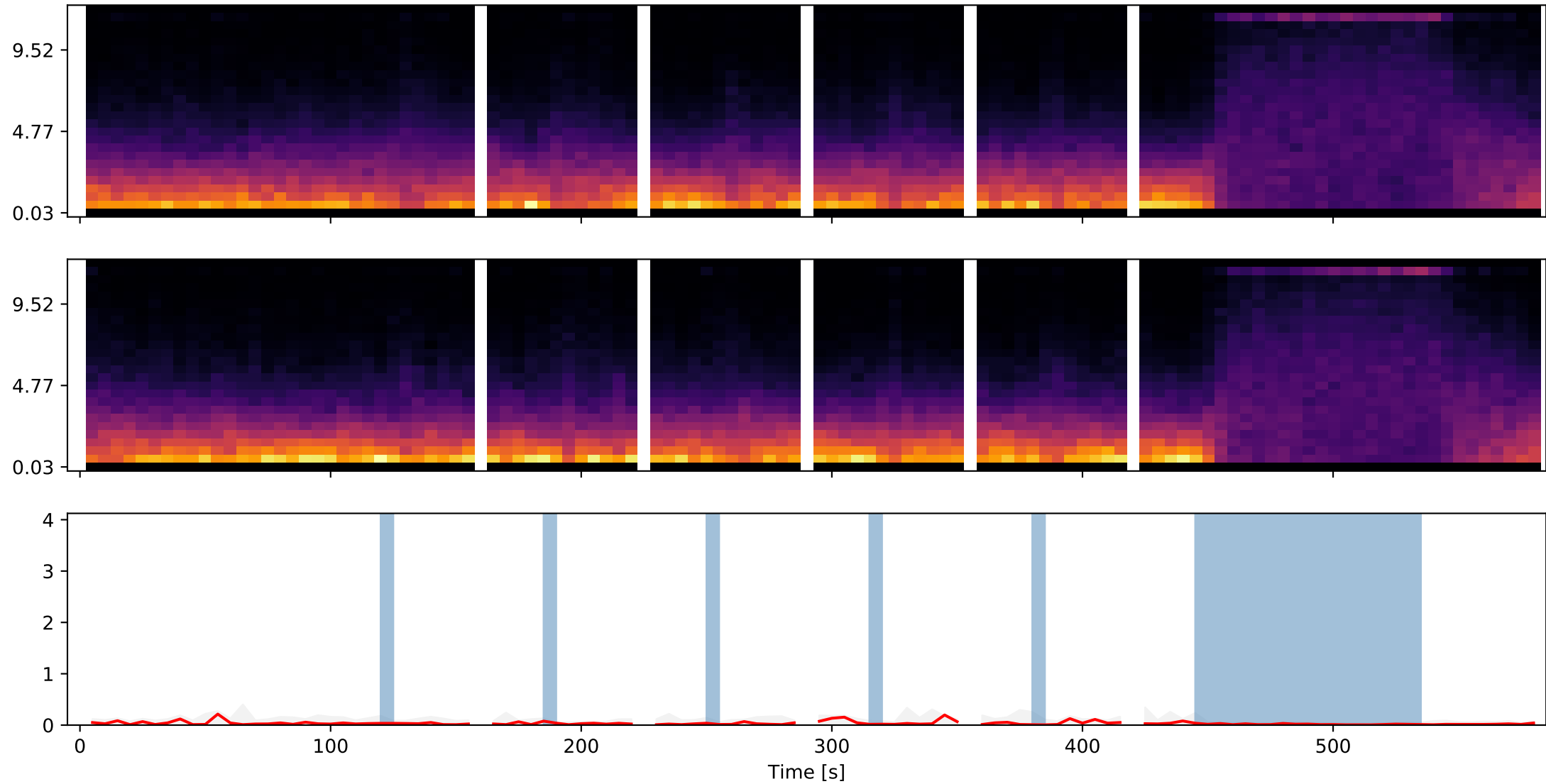
relative_to_body_radial_velocity_neck



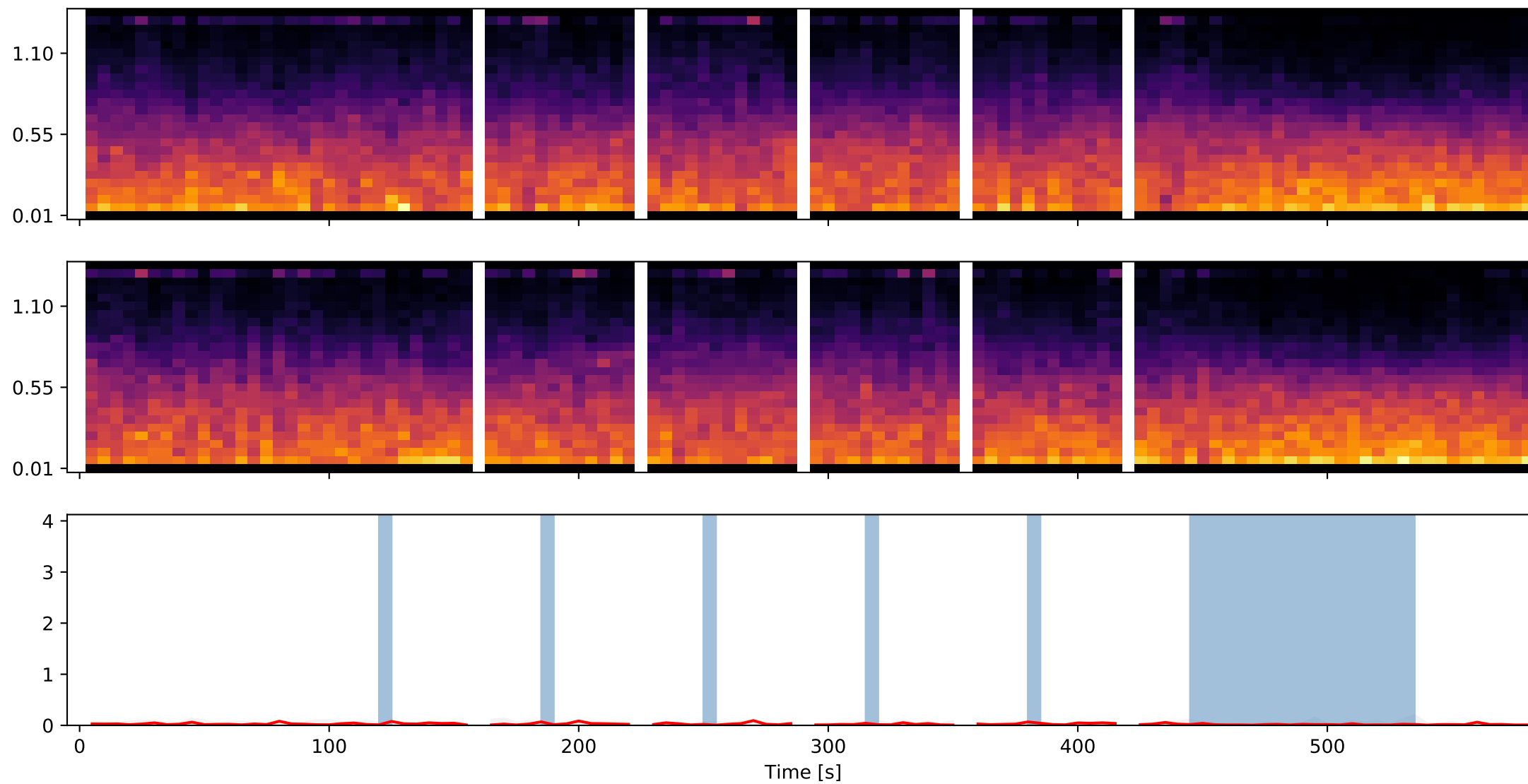
d_angular_velocity_neck



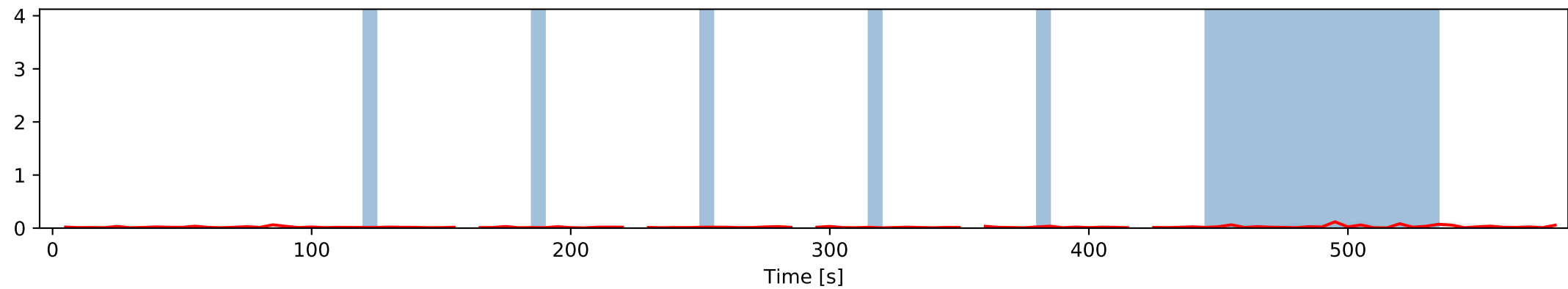
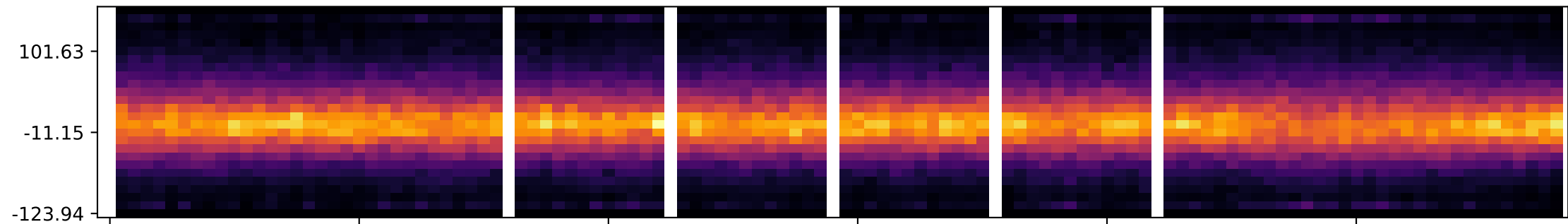
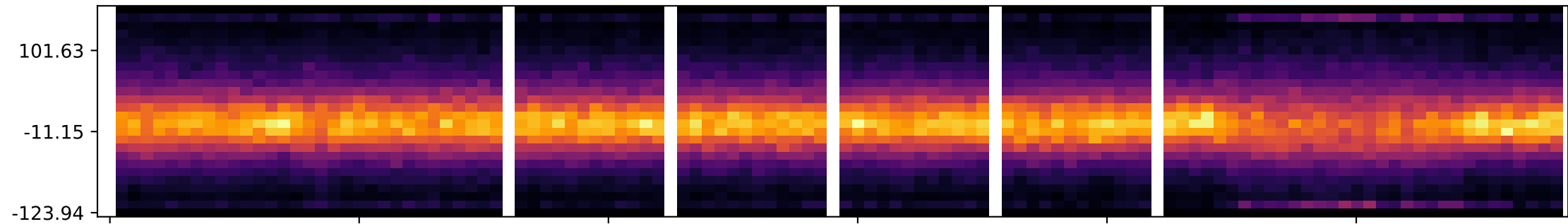
d_relative_to_neck_angular_velocity_head_tip



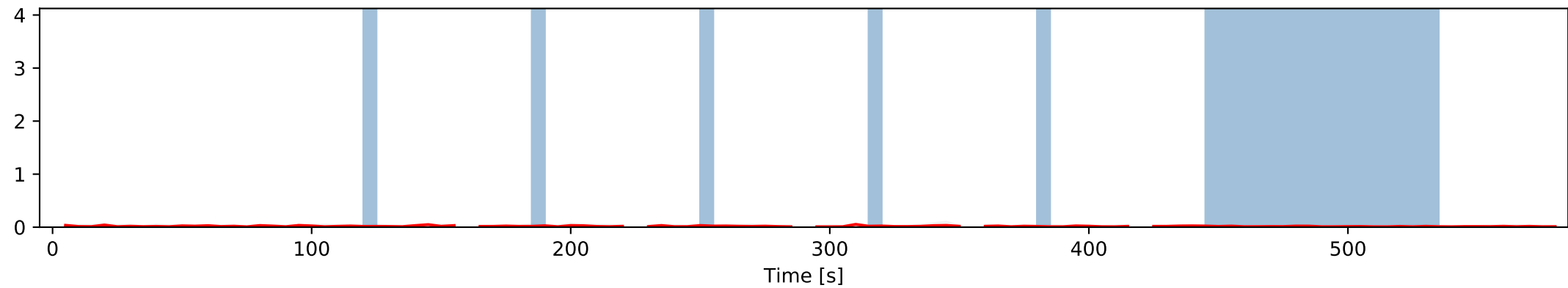
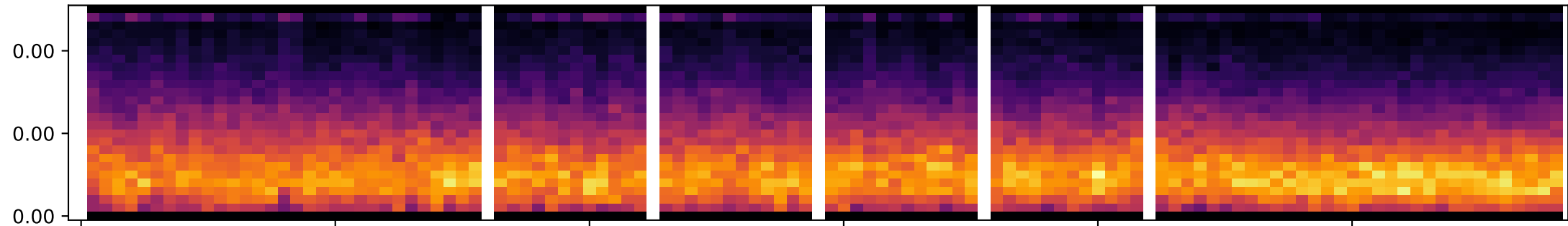
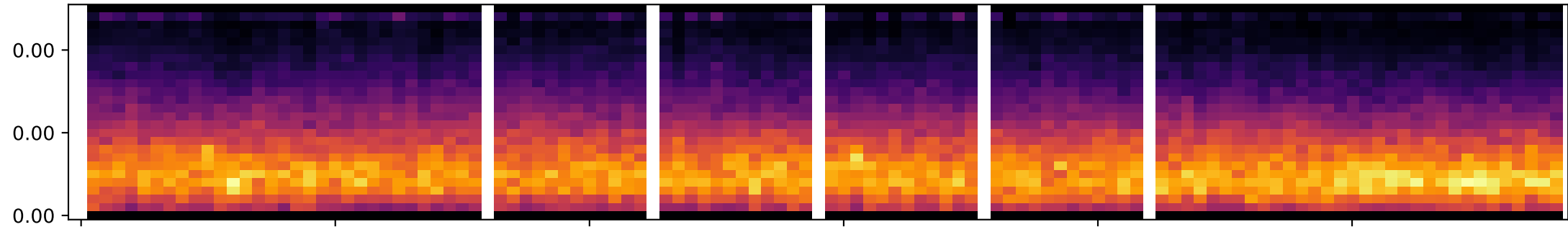
eigen_projection_6



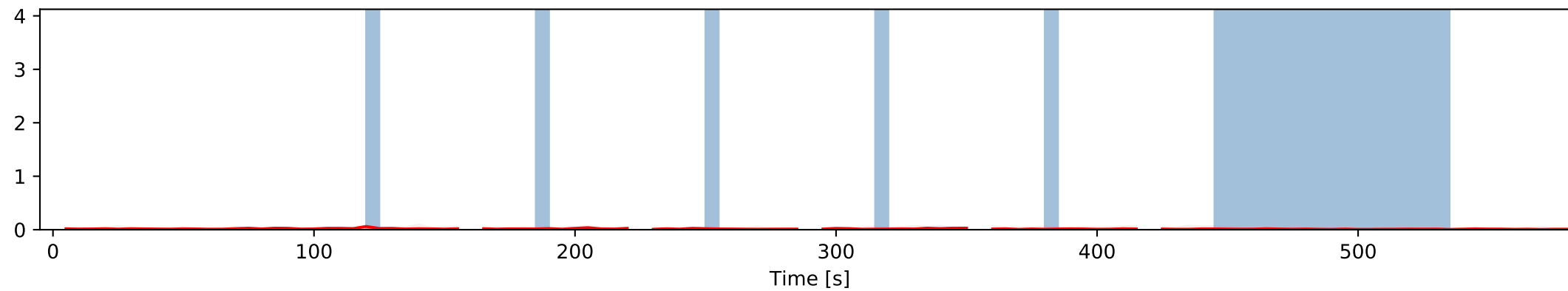
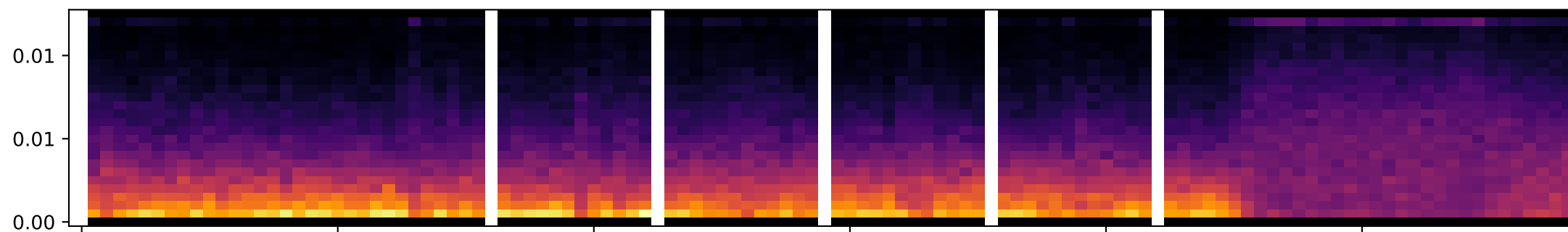
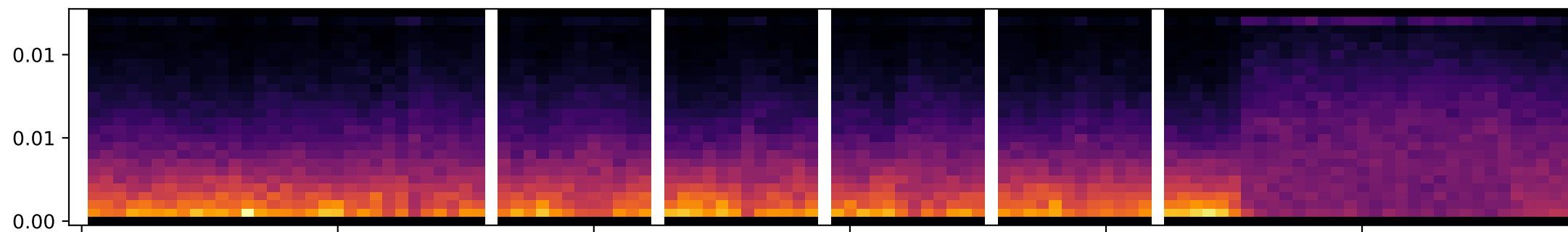
d_relative_to_head_base_radial_velocity_head_tip



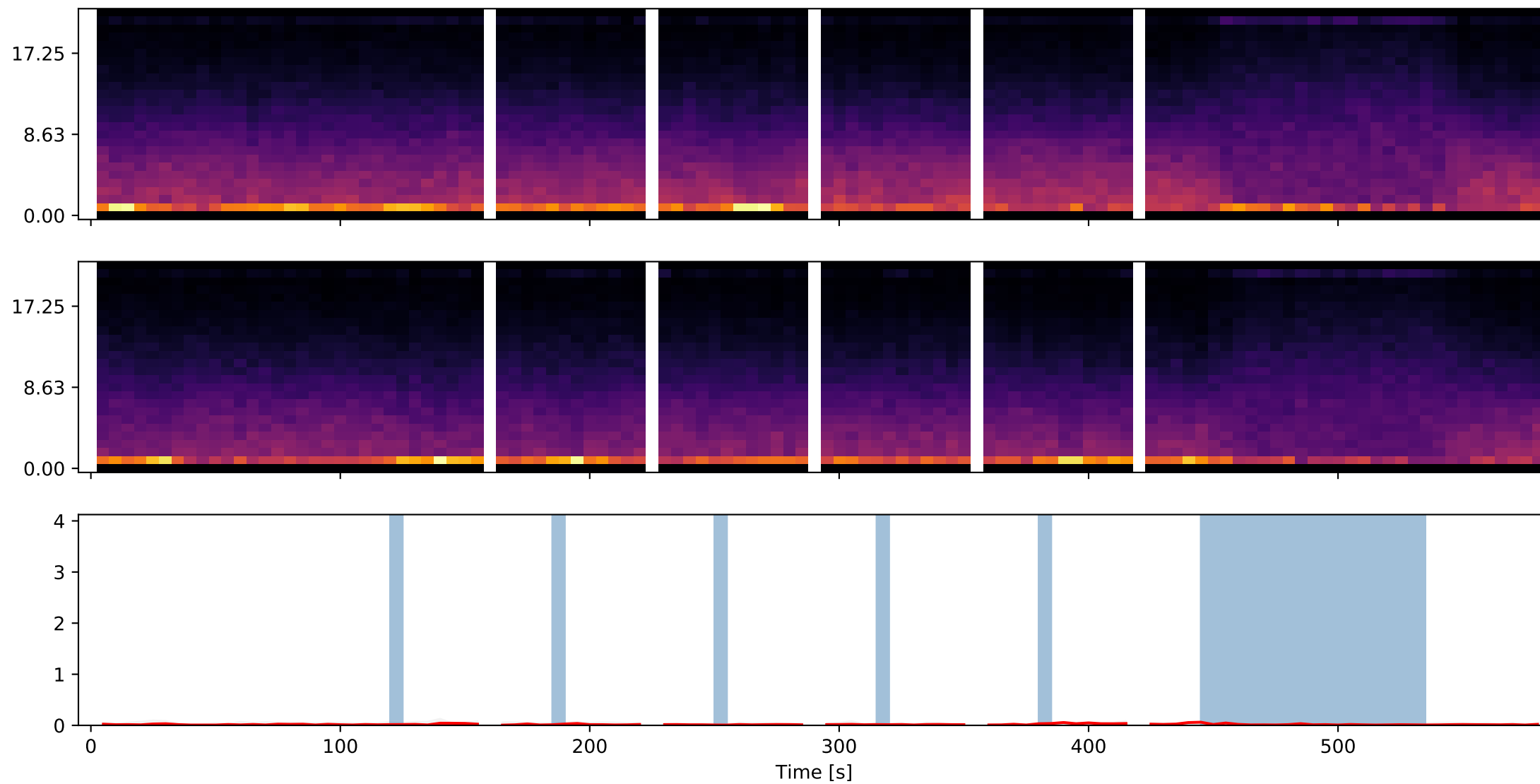
curvature_std_head



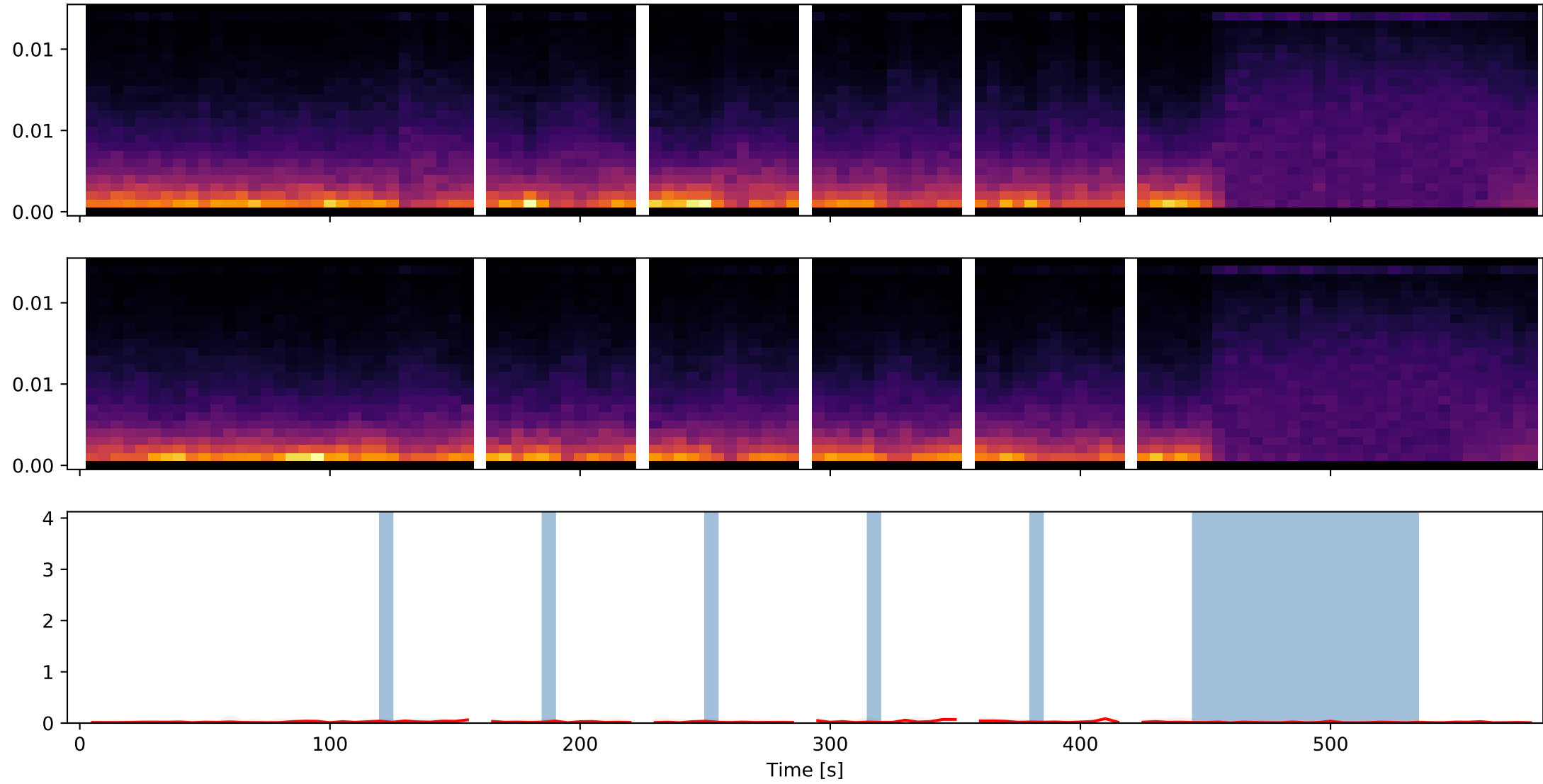
d_curvature_std_neck



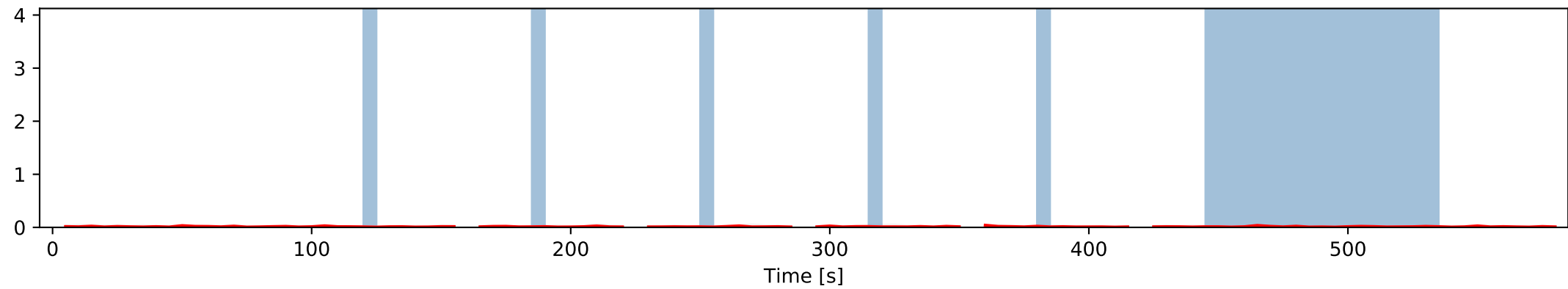
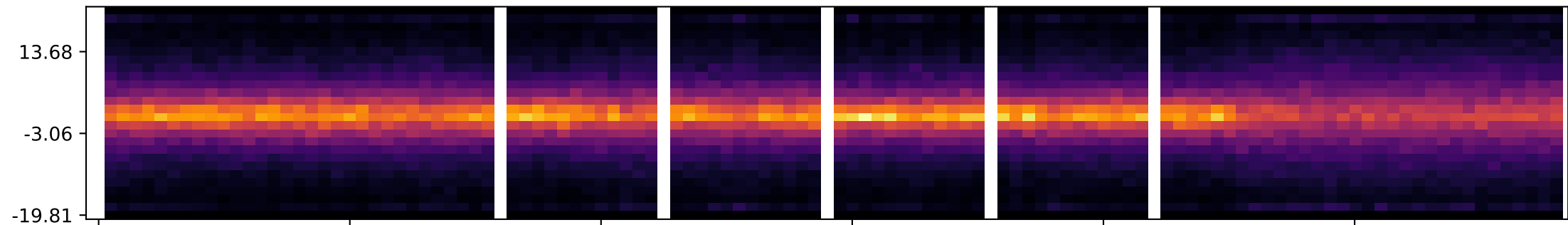
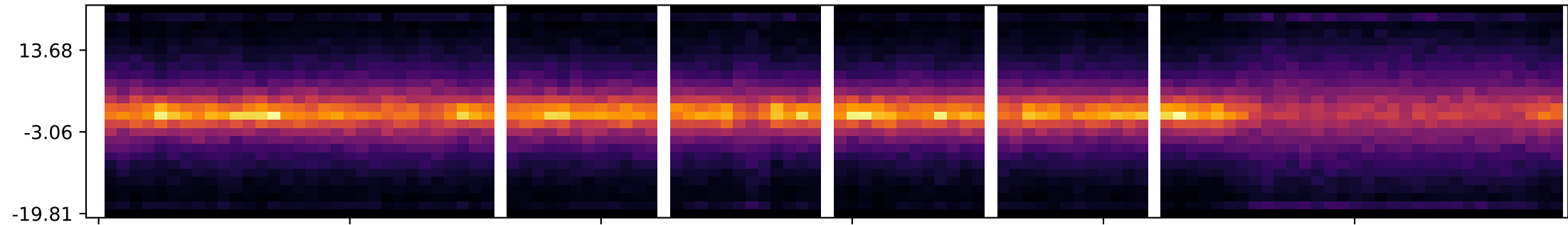
d_angular_velocity_head_tip



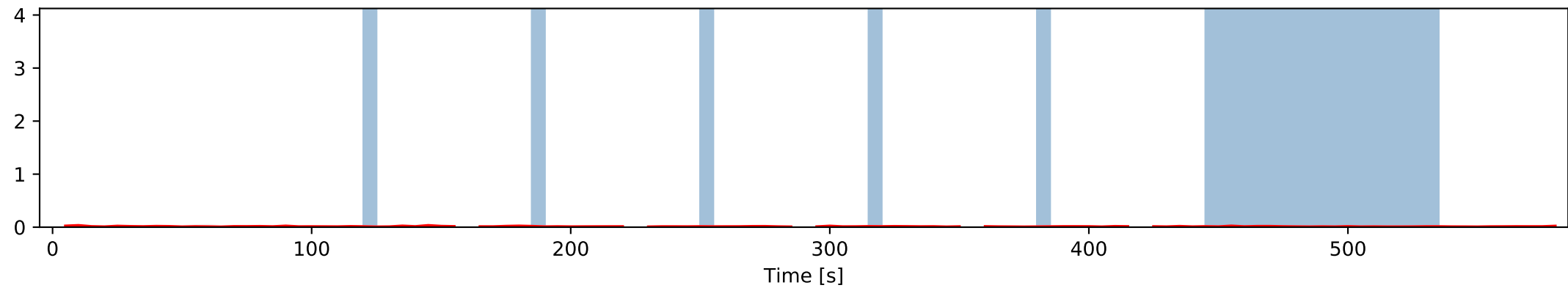
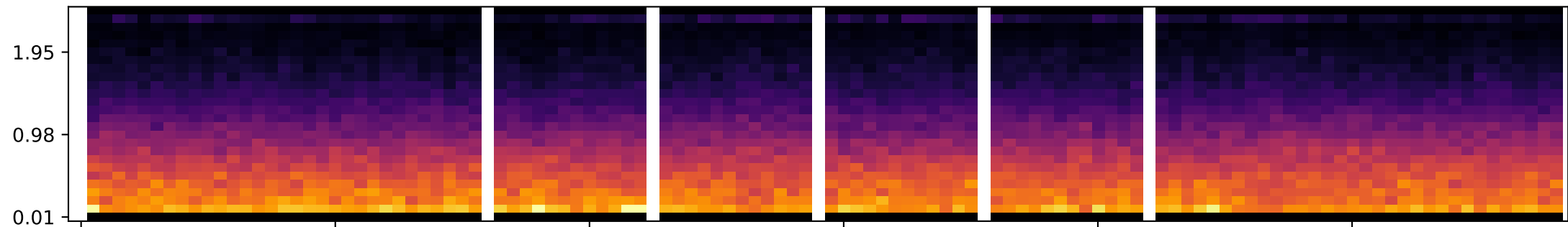
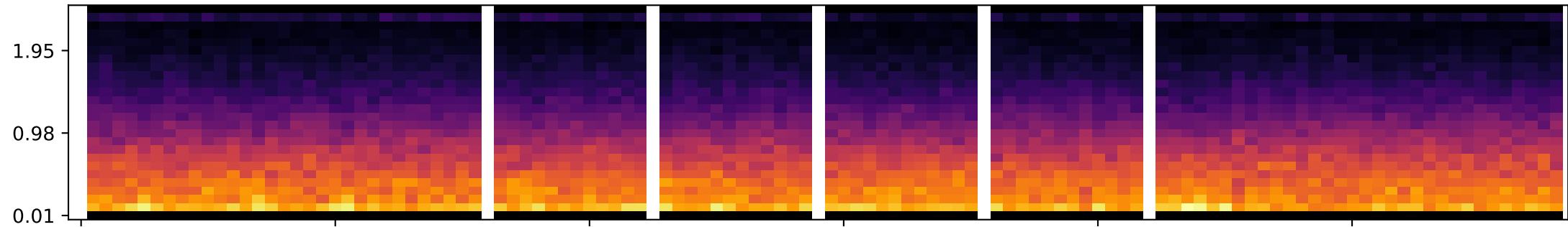
d_curvature_std_hips



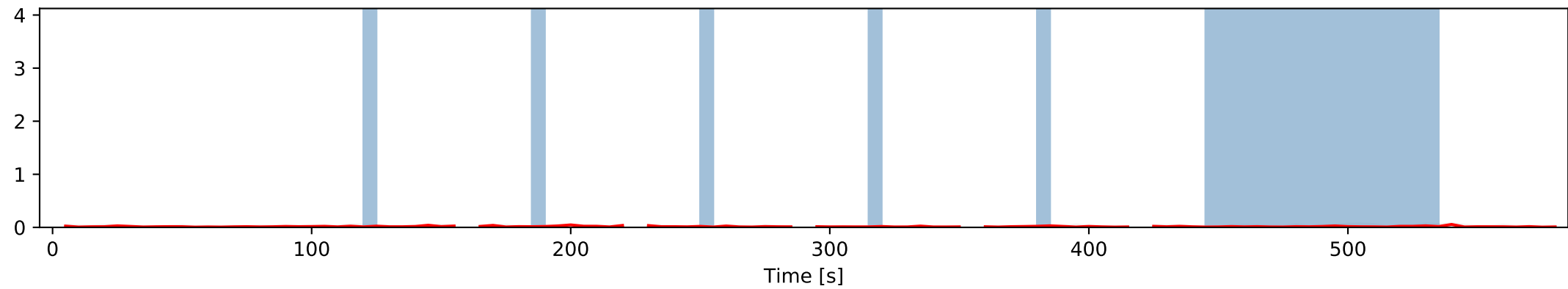
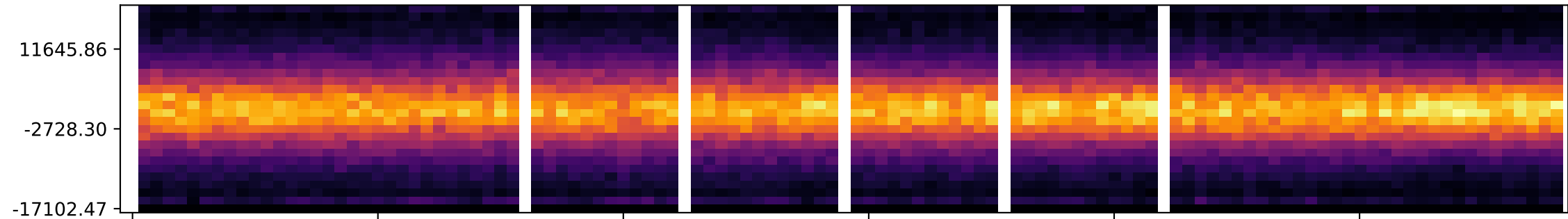
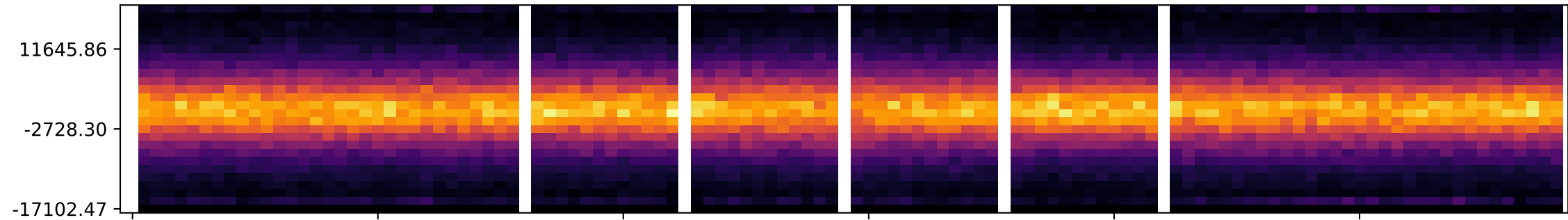
d_width_midbody



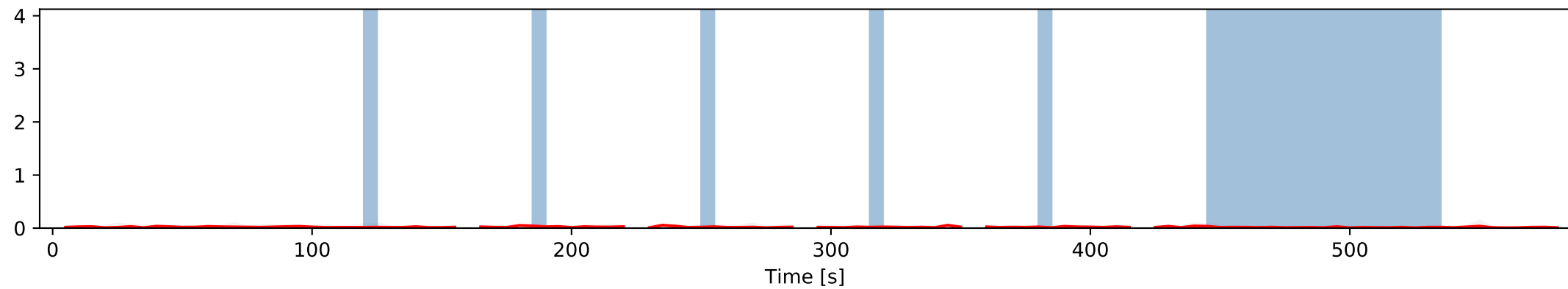
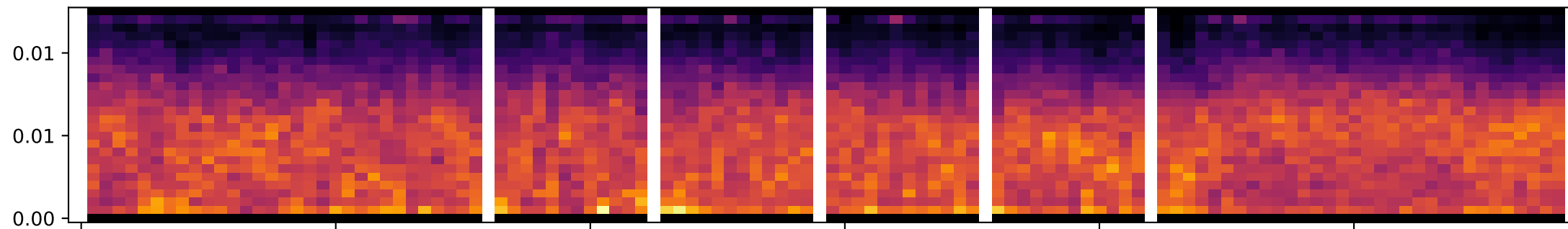
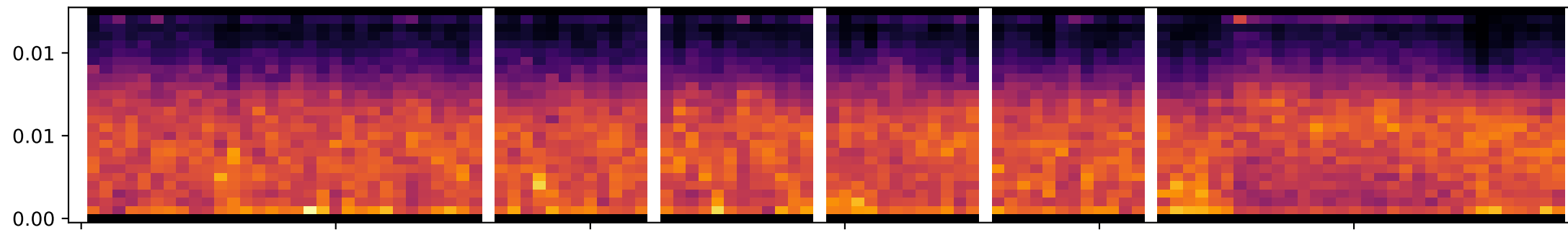
d_eigen_projection_7



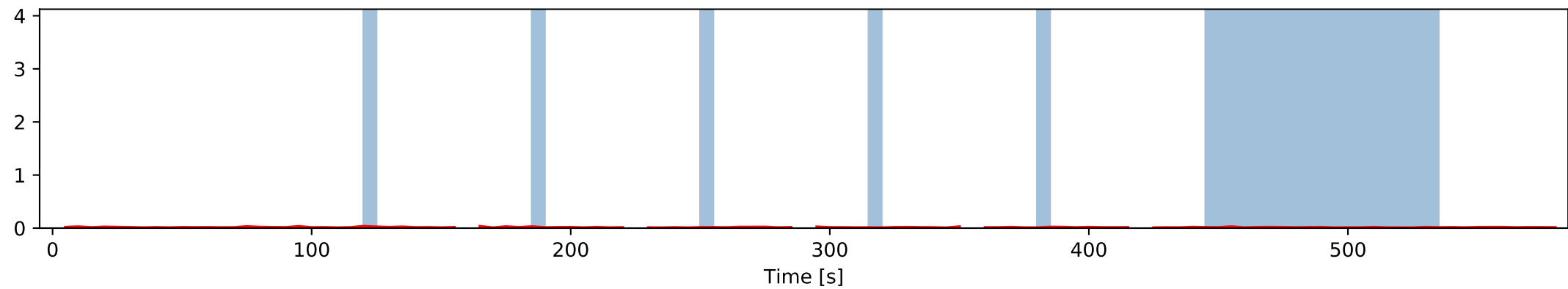
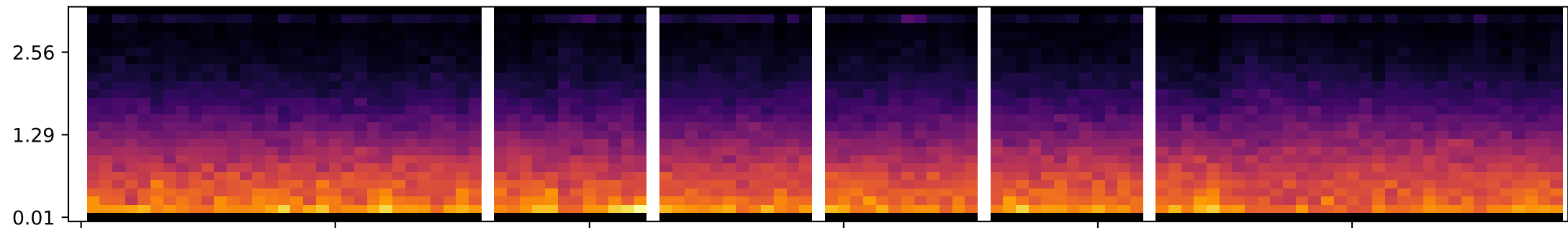
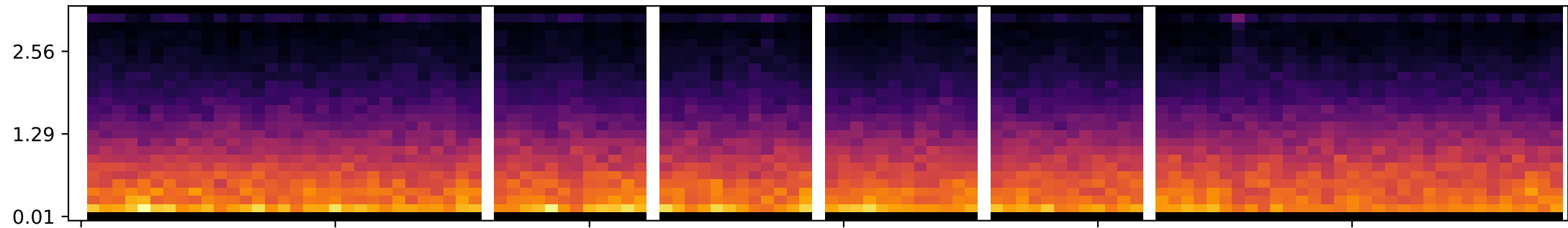
d_area



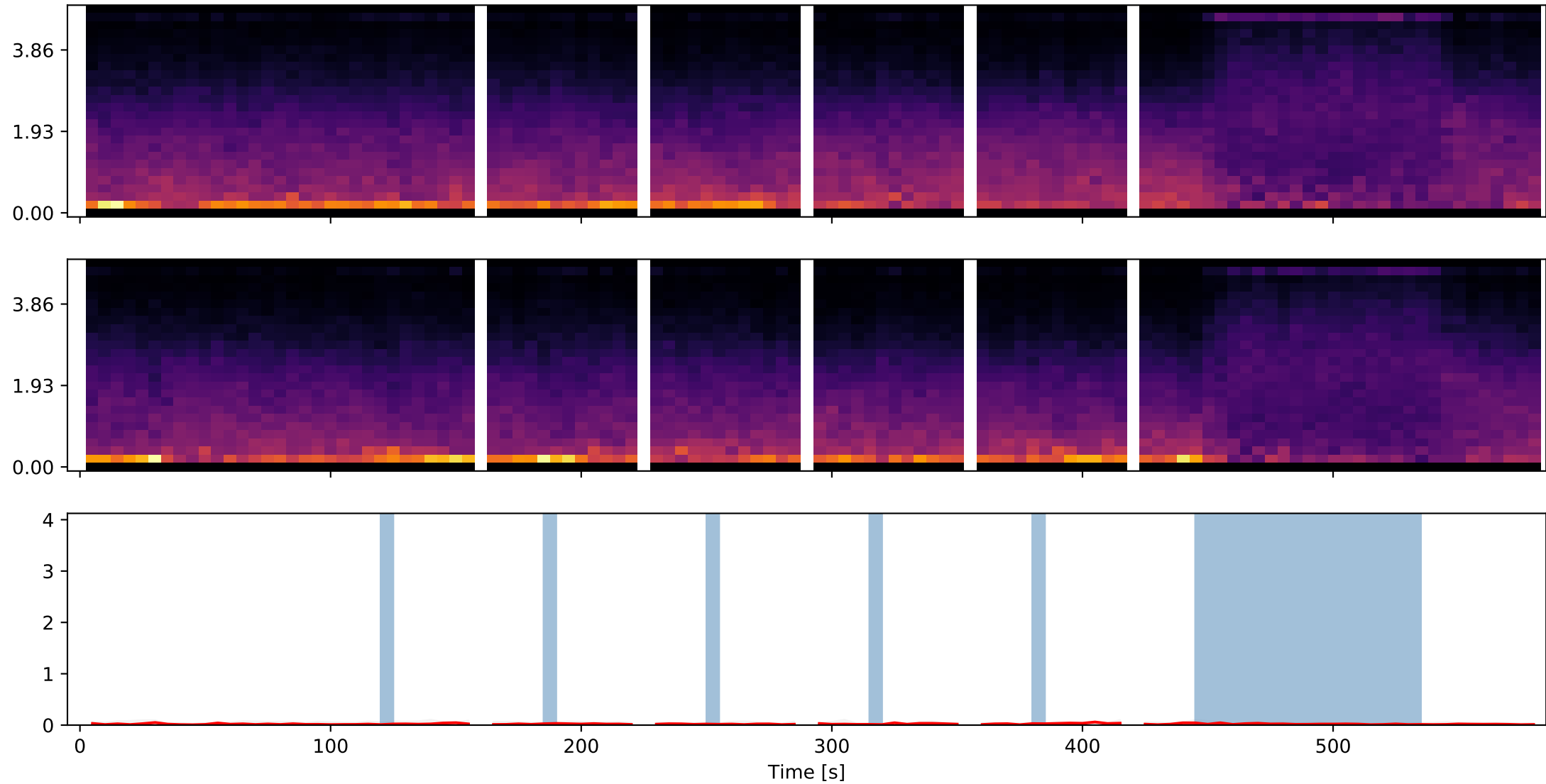
curvature_head



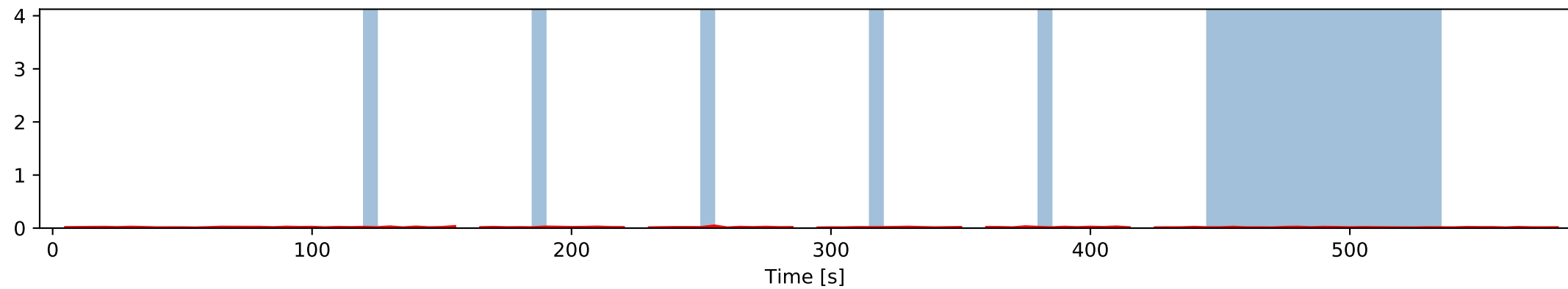
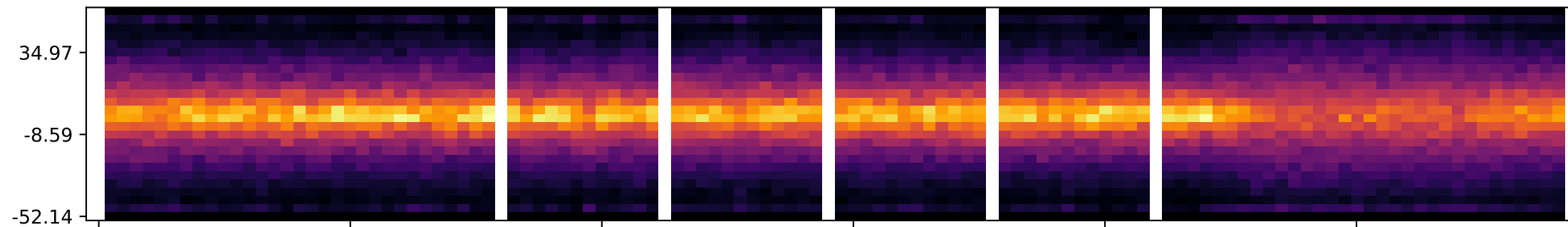
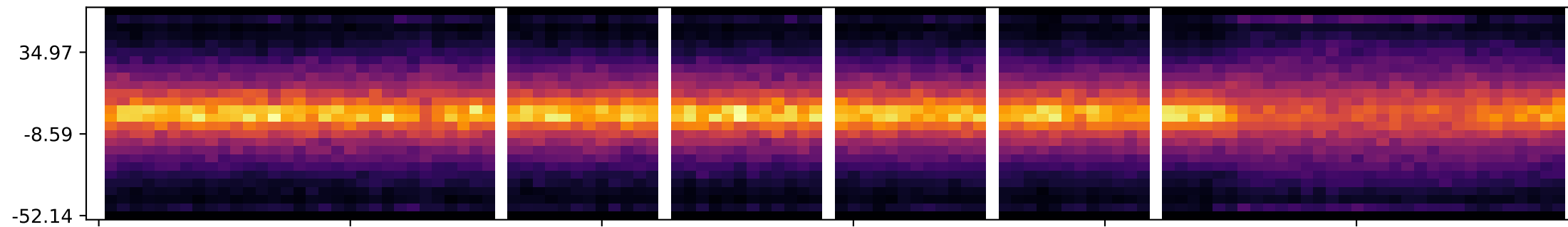
d_eigen_projection_6



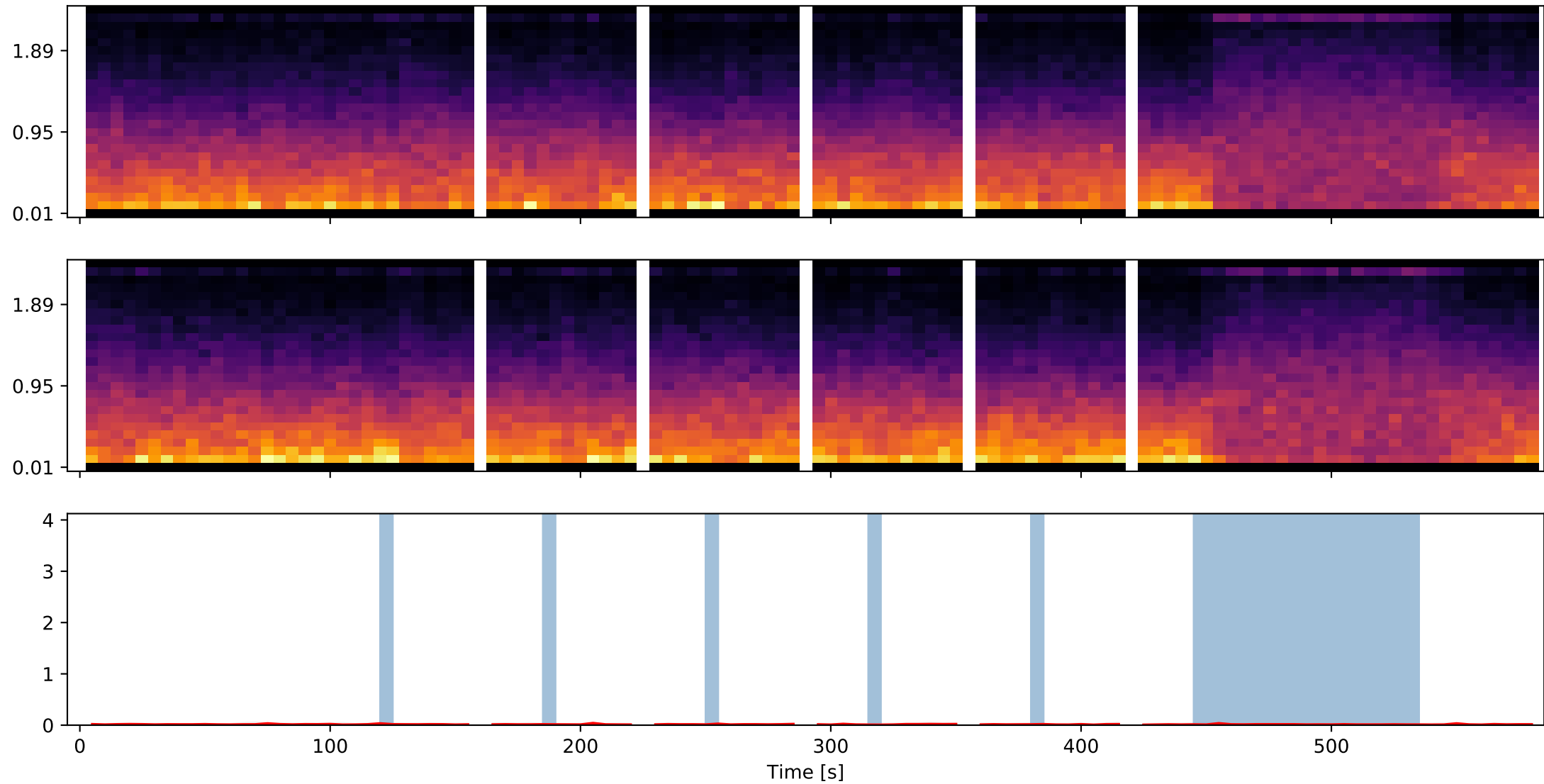
angular_velocity_head_tip



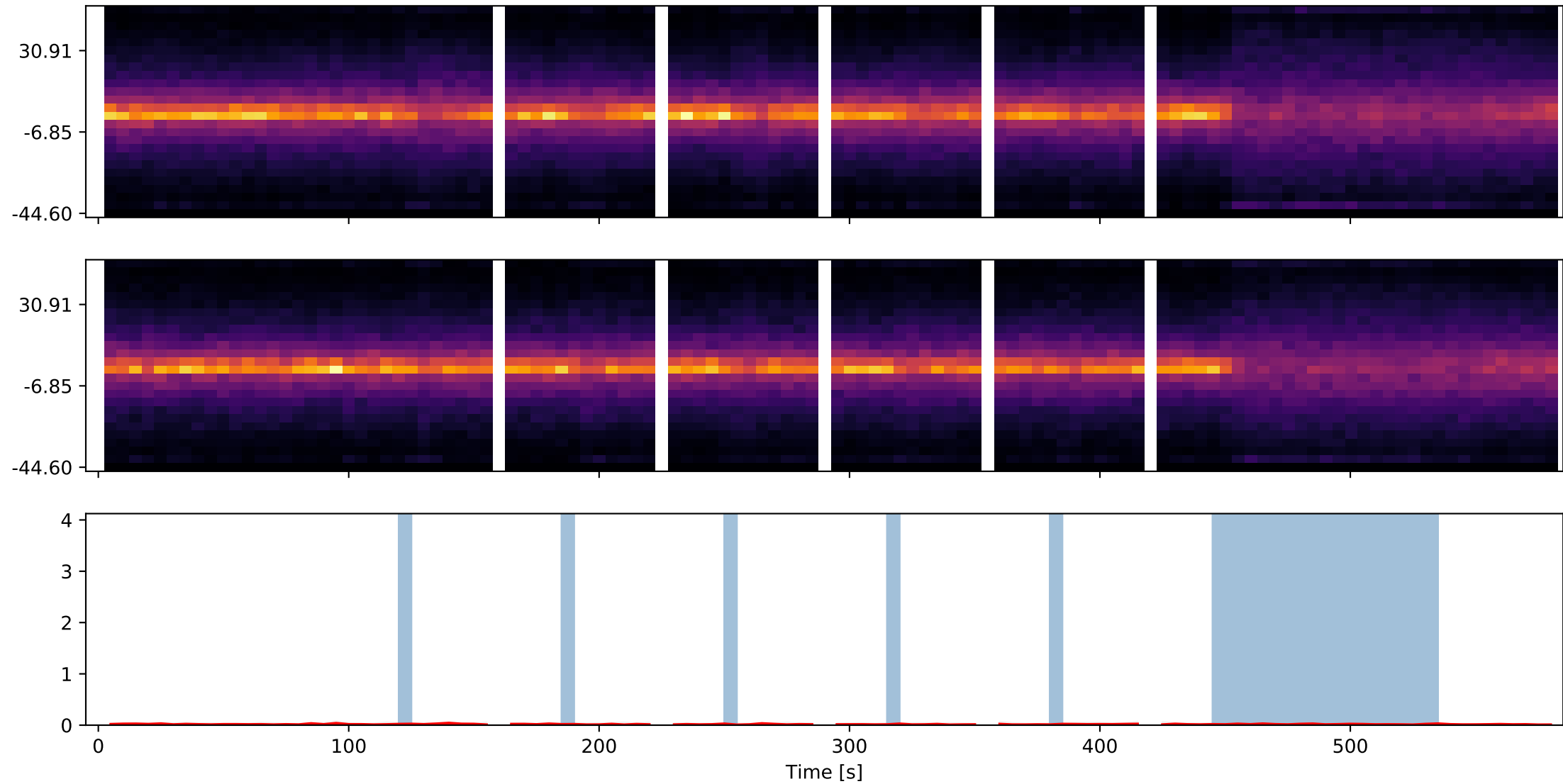
d_width_head_base



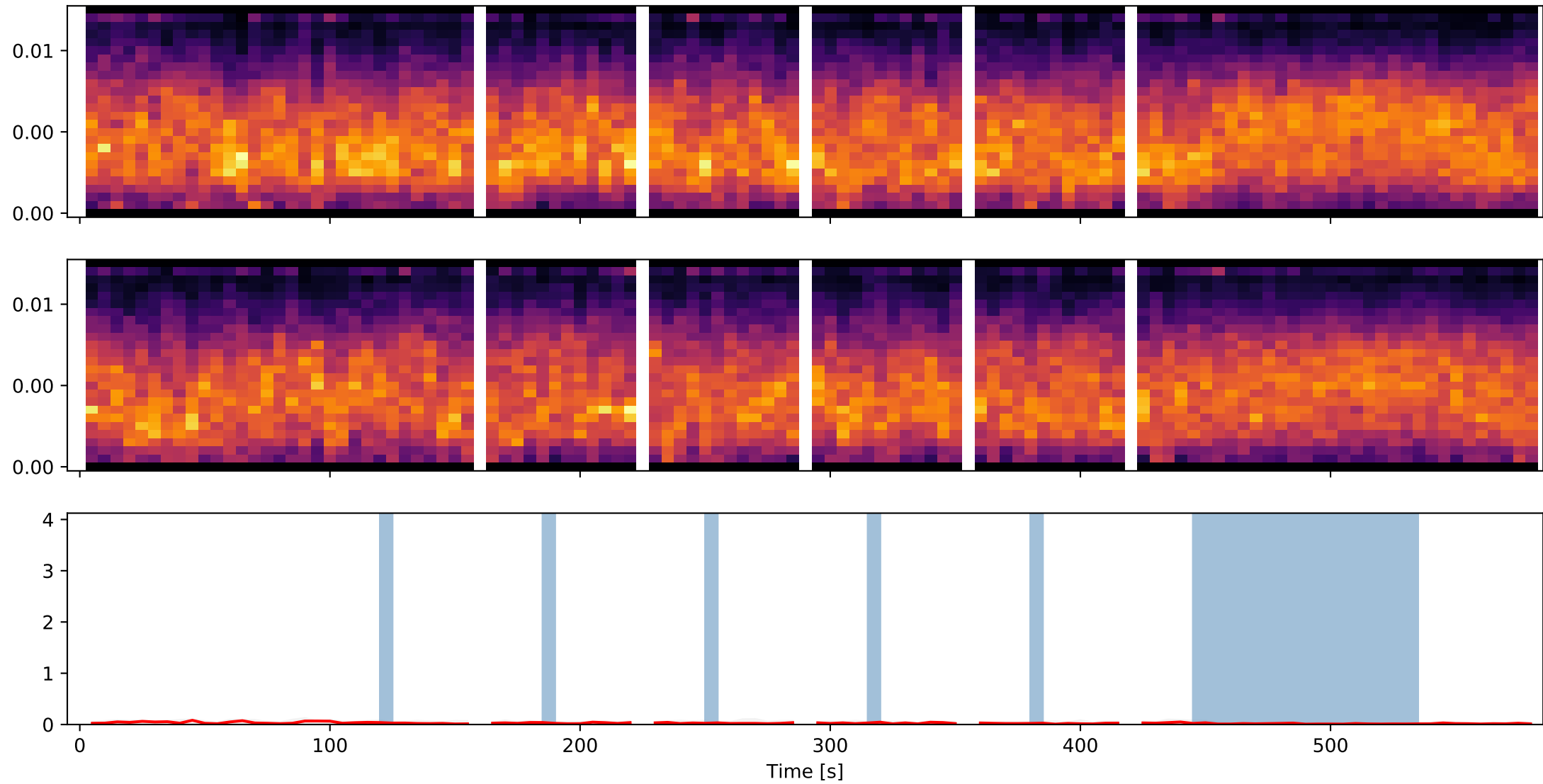
relative_to_head_base_angular_velocity_head_tip



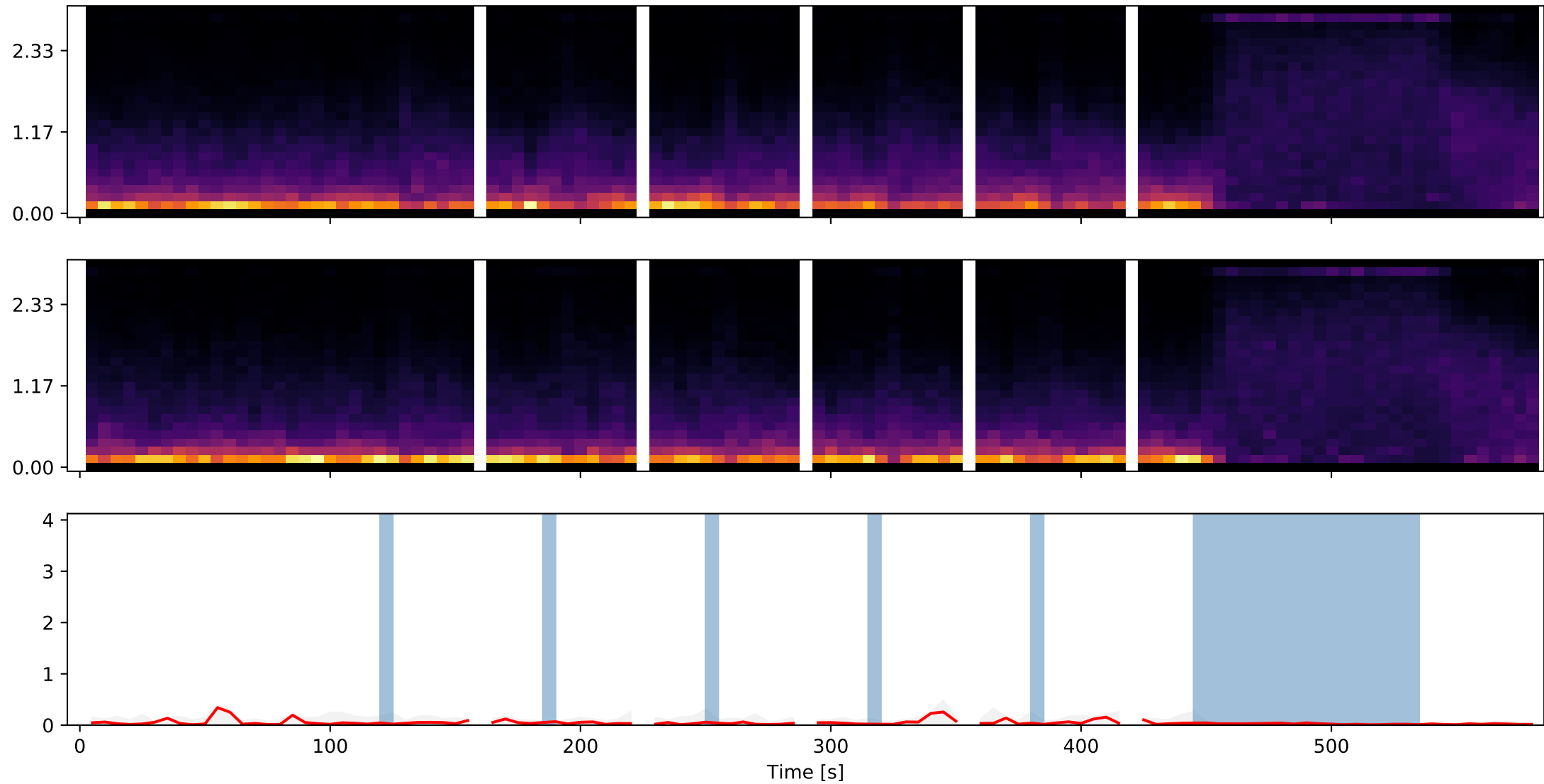
d_width_tail_base



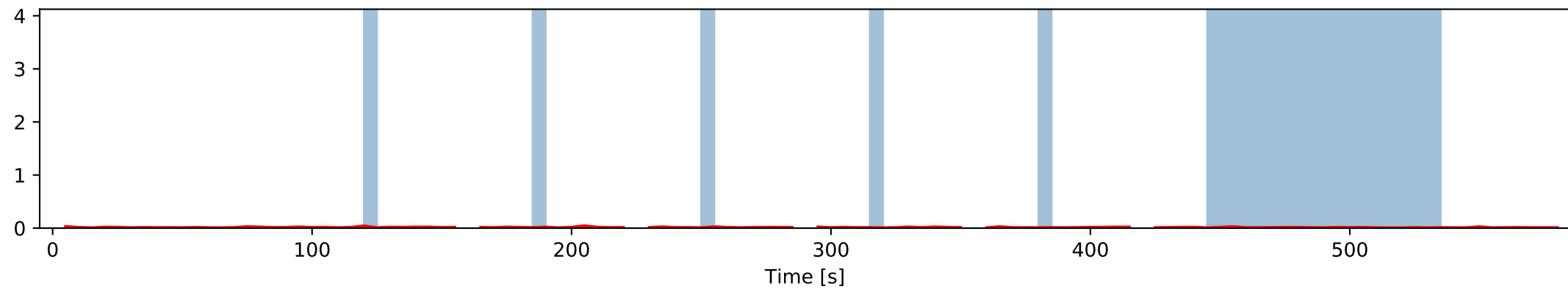
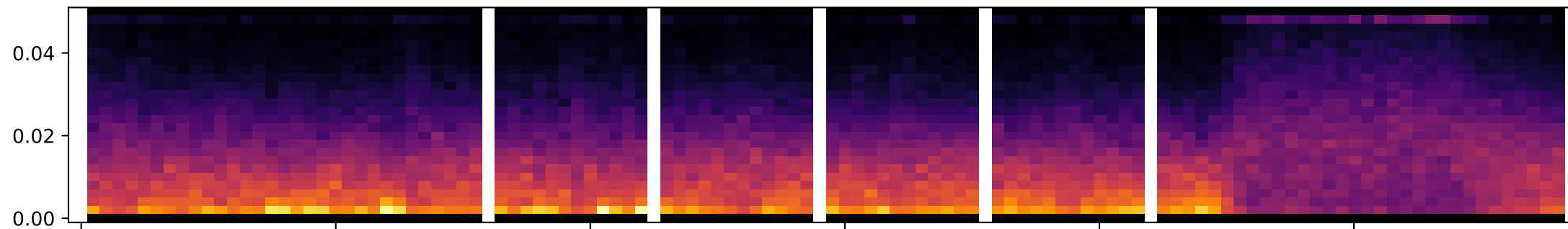
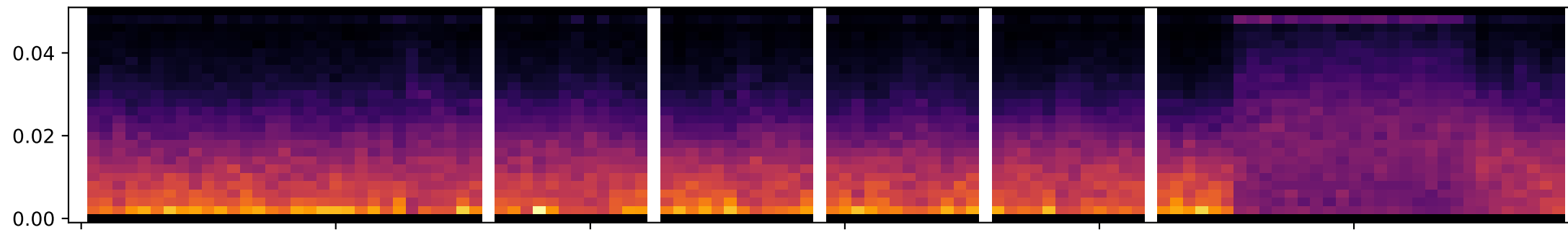
curvature_std_neck



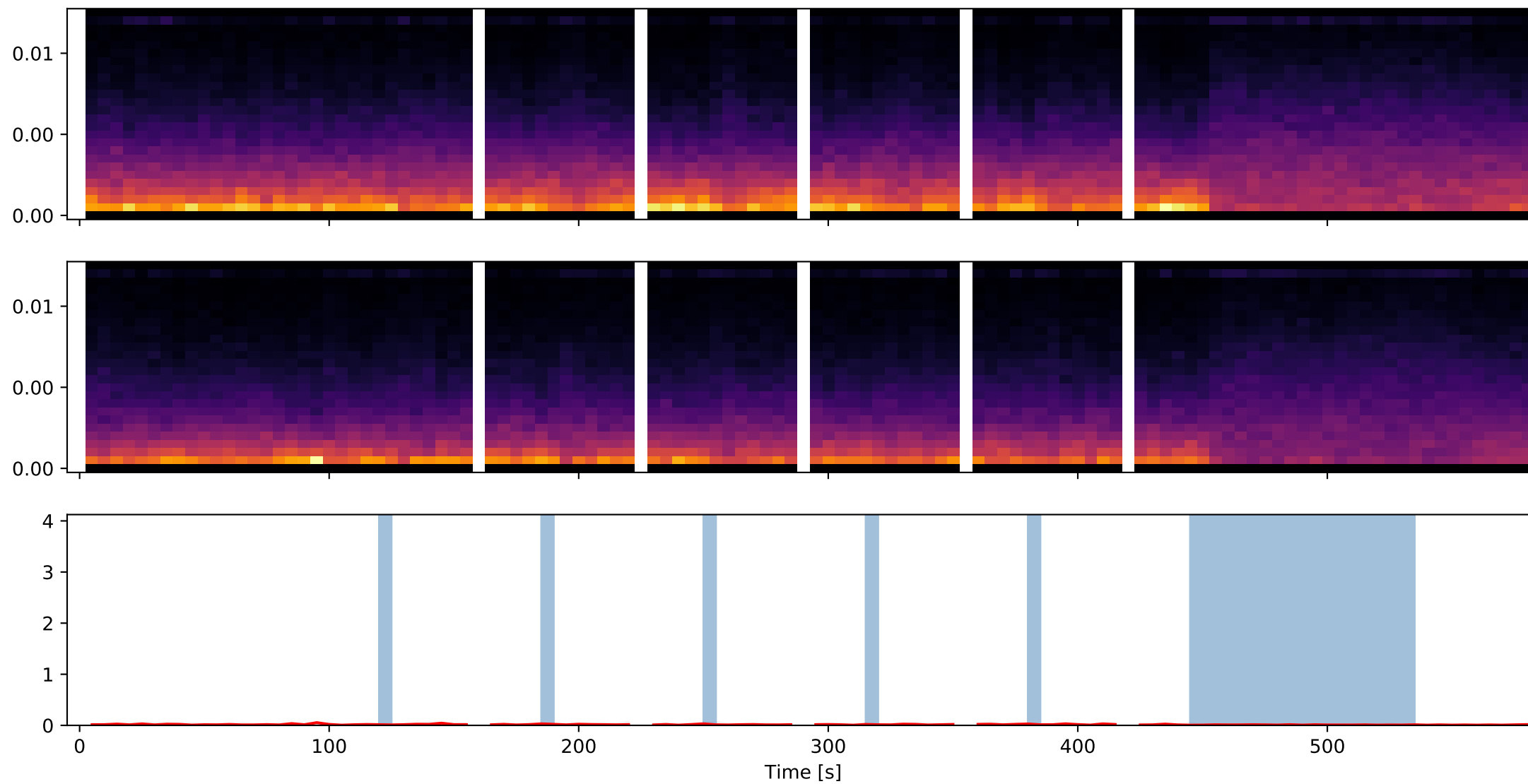
angular_velocity_neck



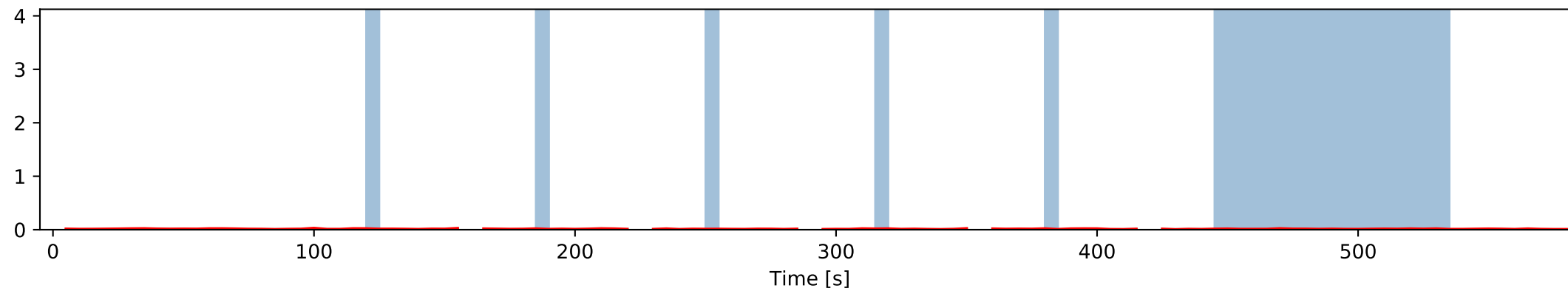
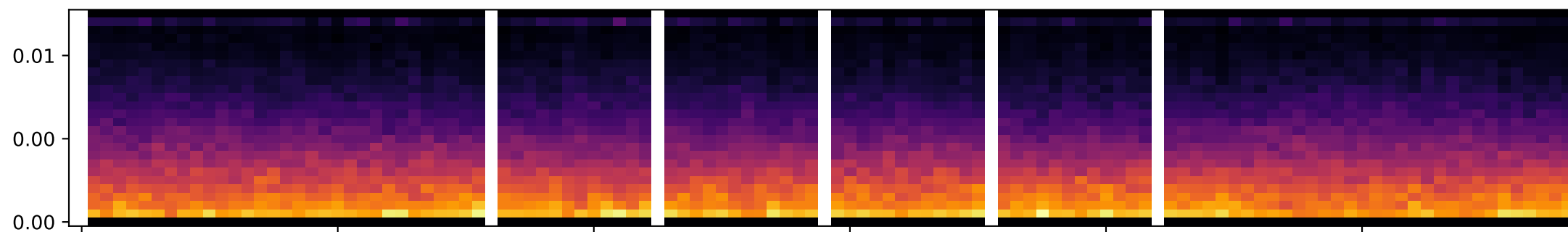
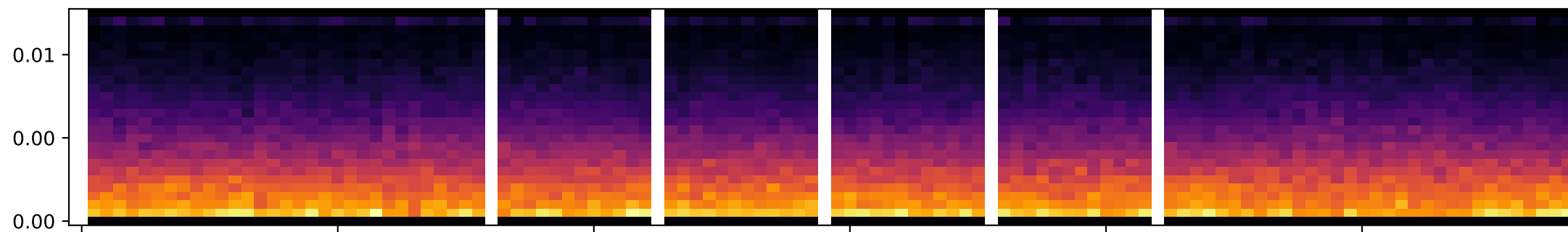
d_curvature_head



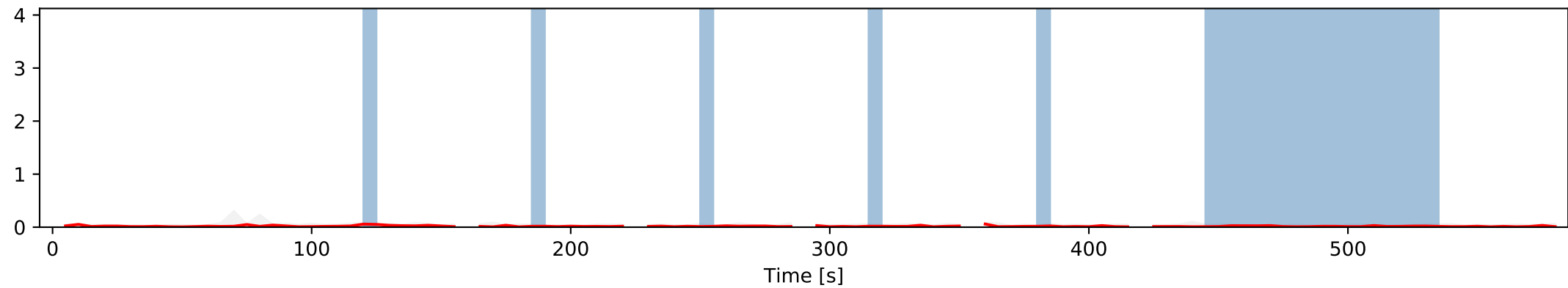
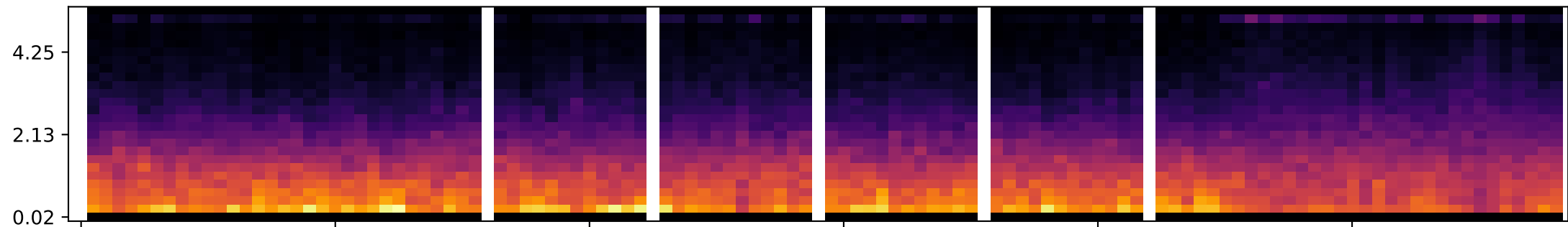
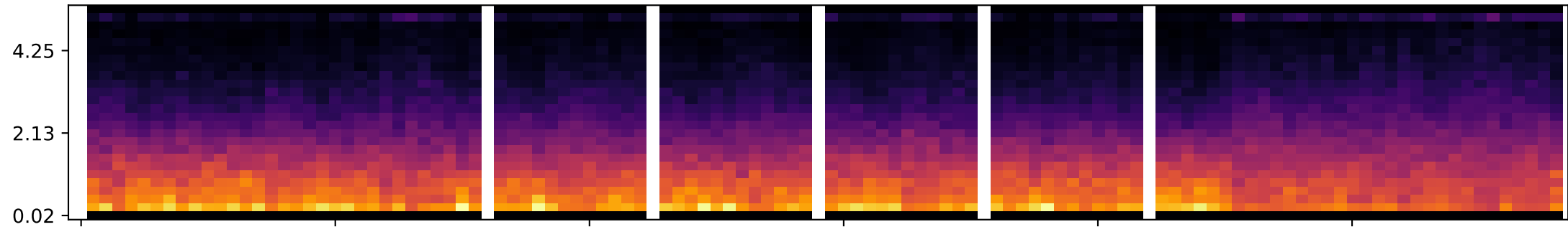
d_curvature_std_tail



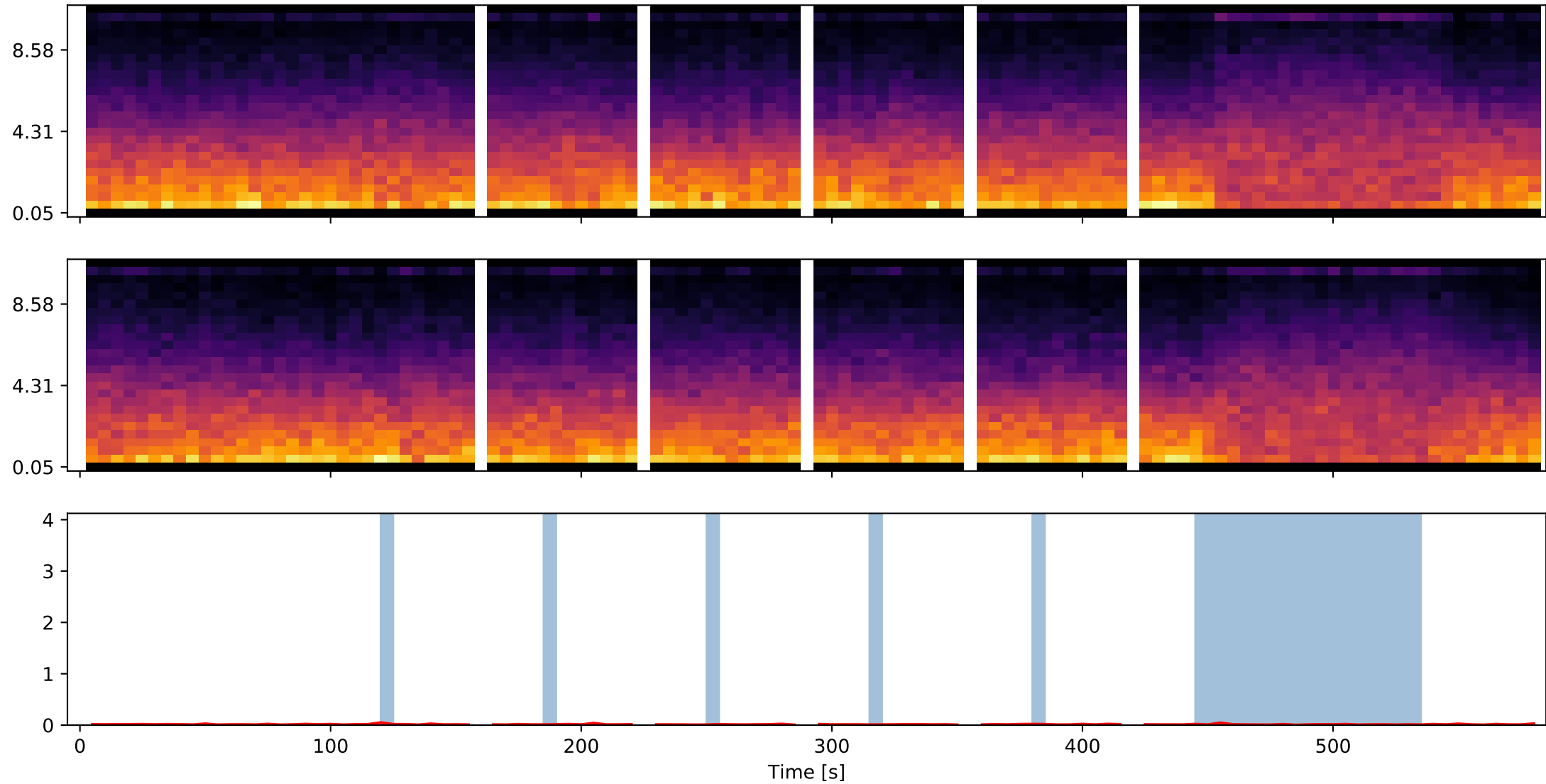
d_curvature_std_head



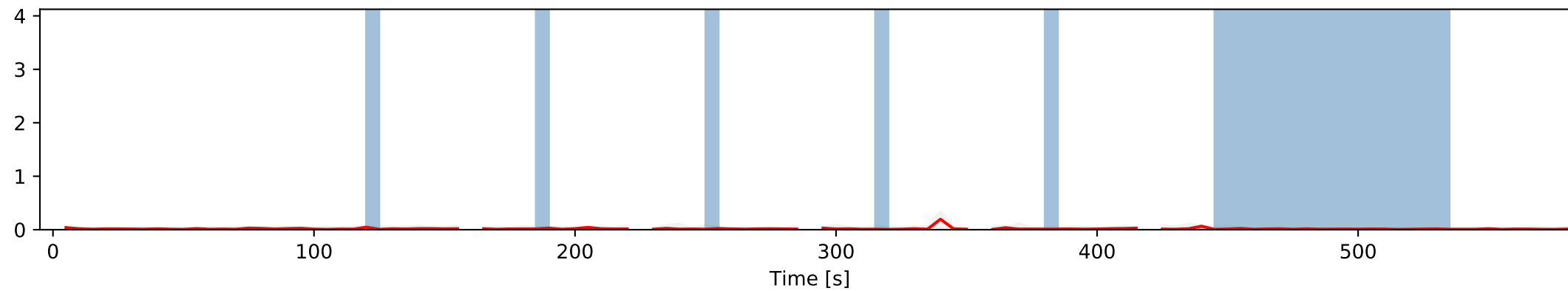
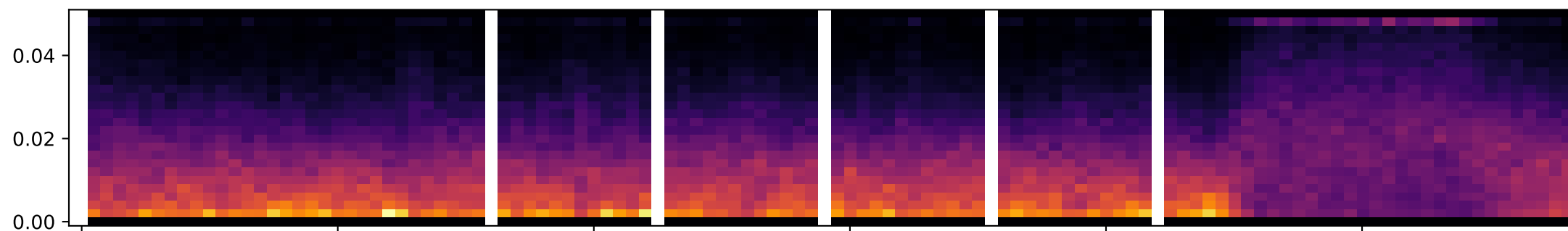
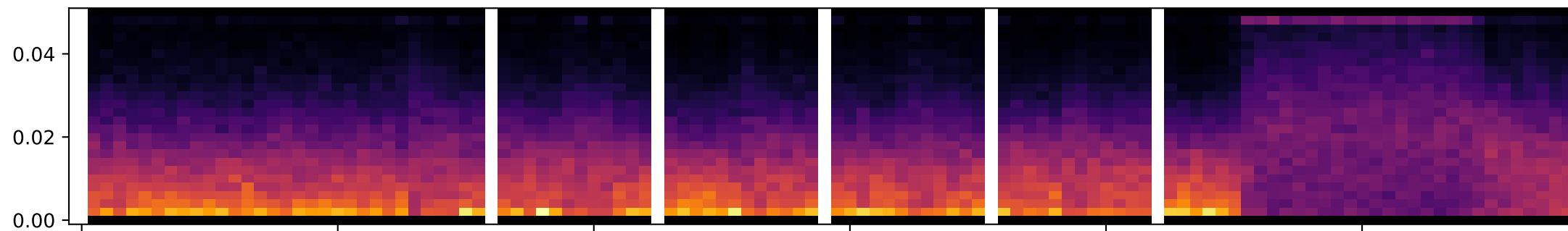
d_eigen_projection_5



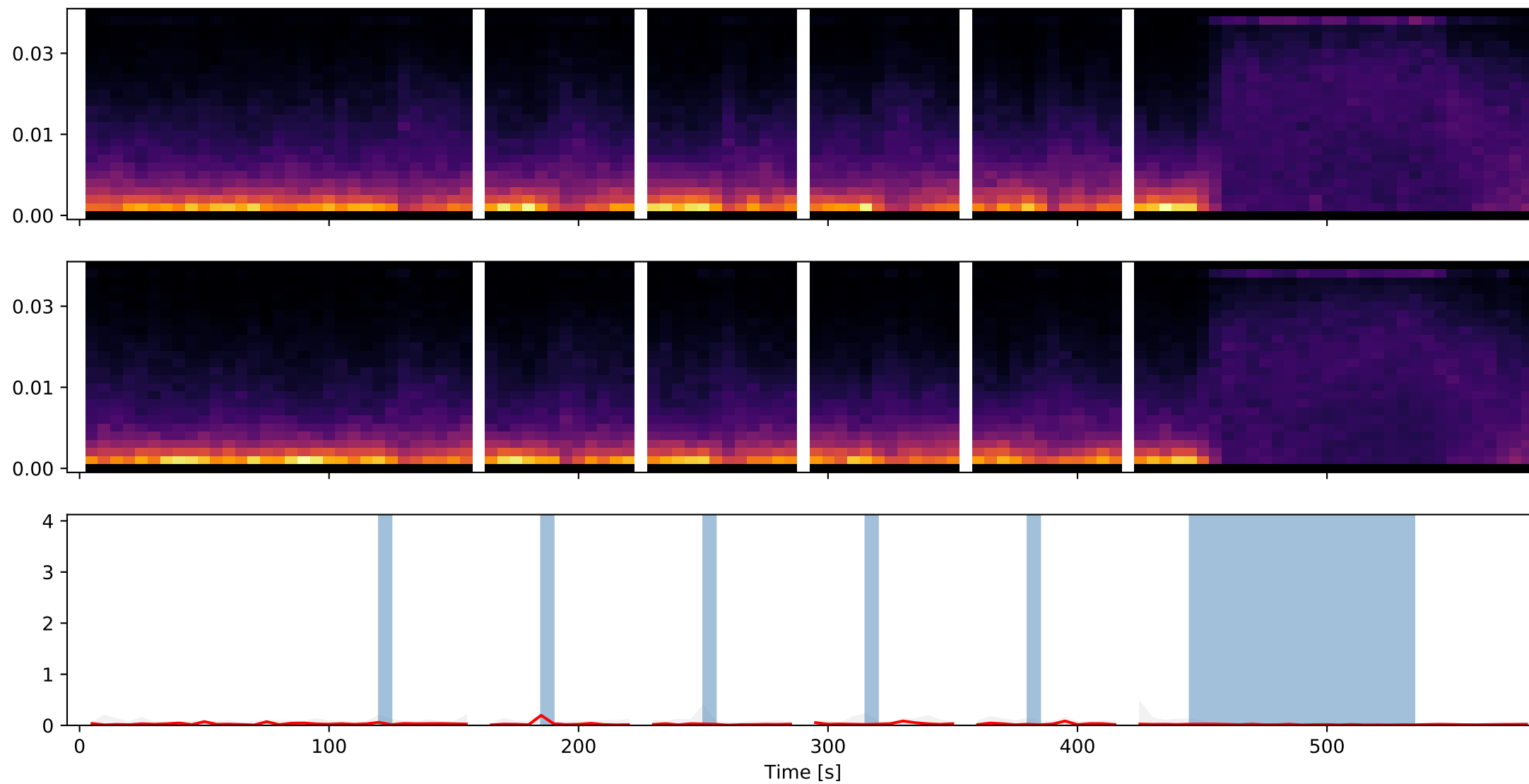
d_relative_to_head_base_angular_velocity_head_tip



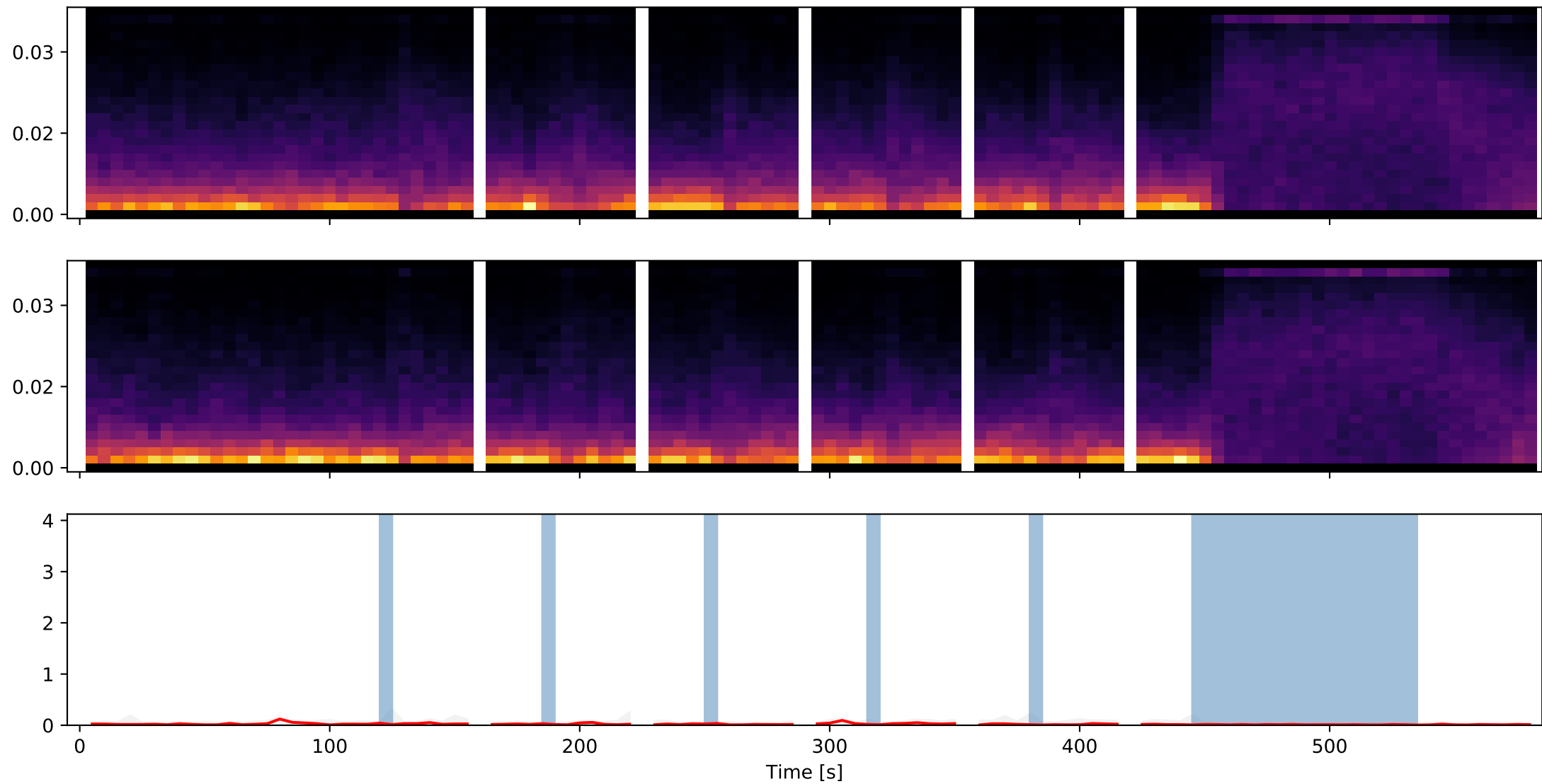
d_curvature_mean_head



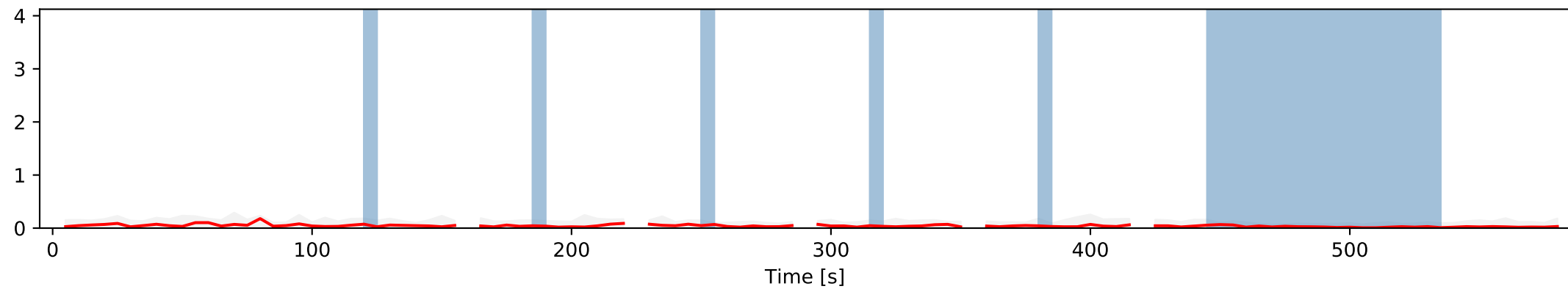
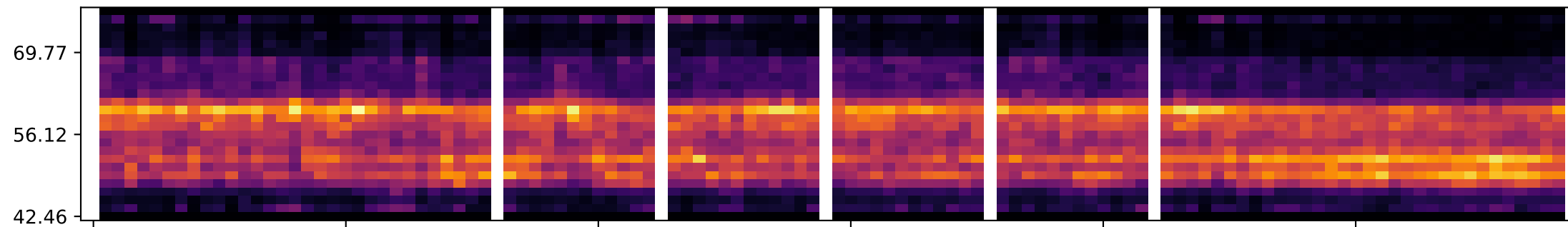
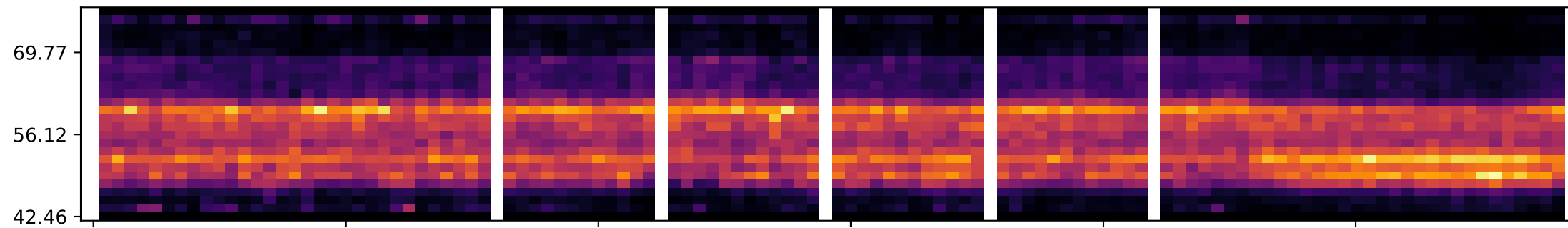
d_curvature_midbody



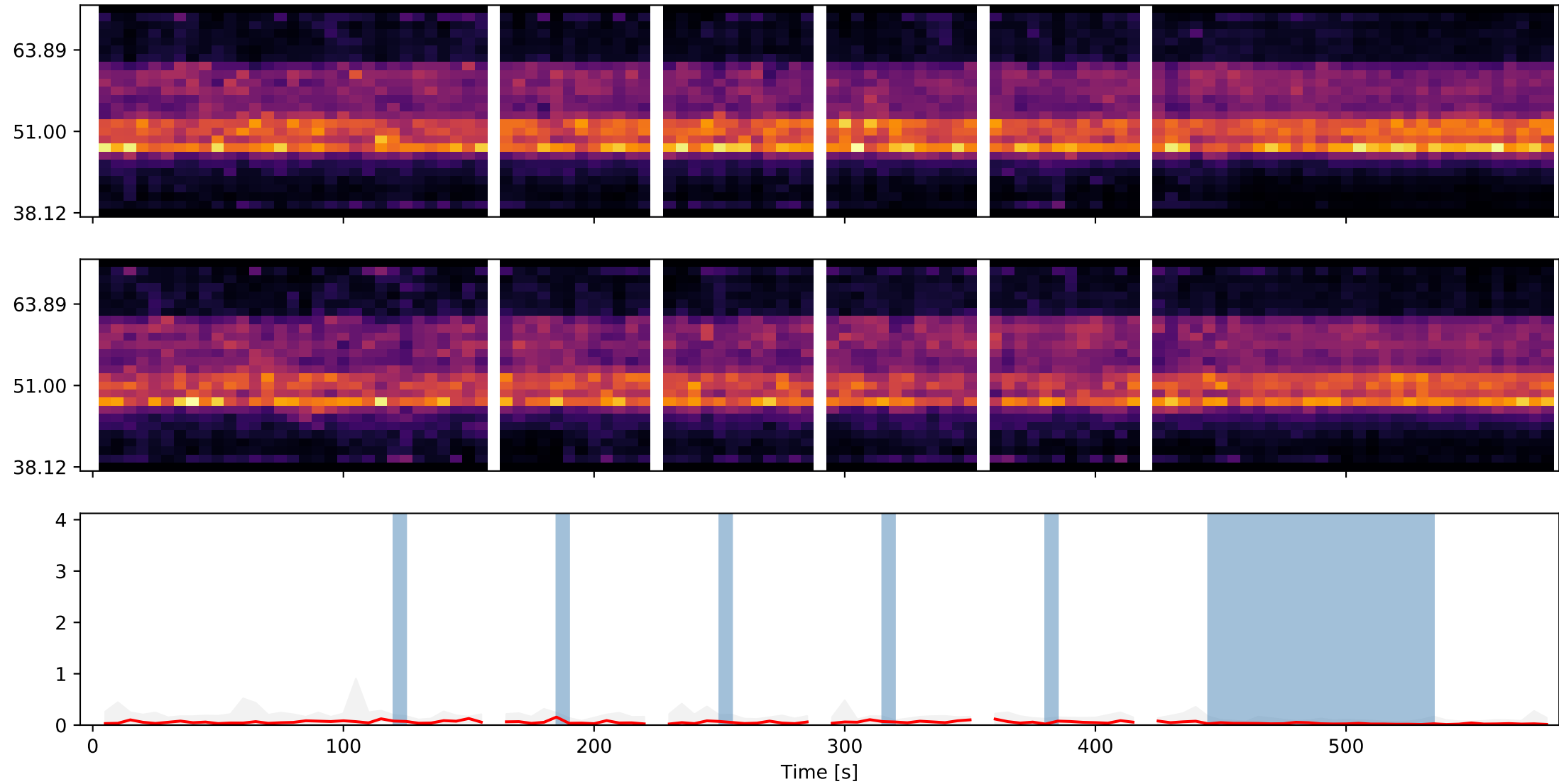
d_curvature_neck



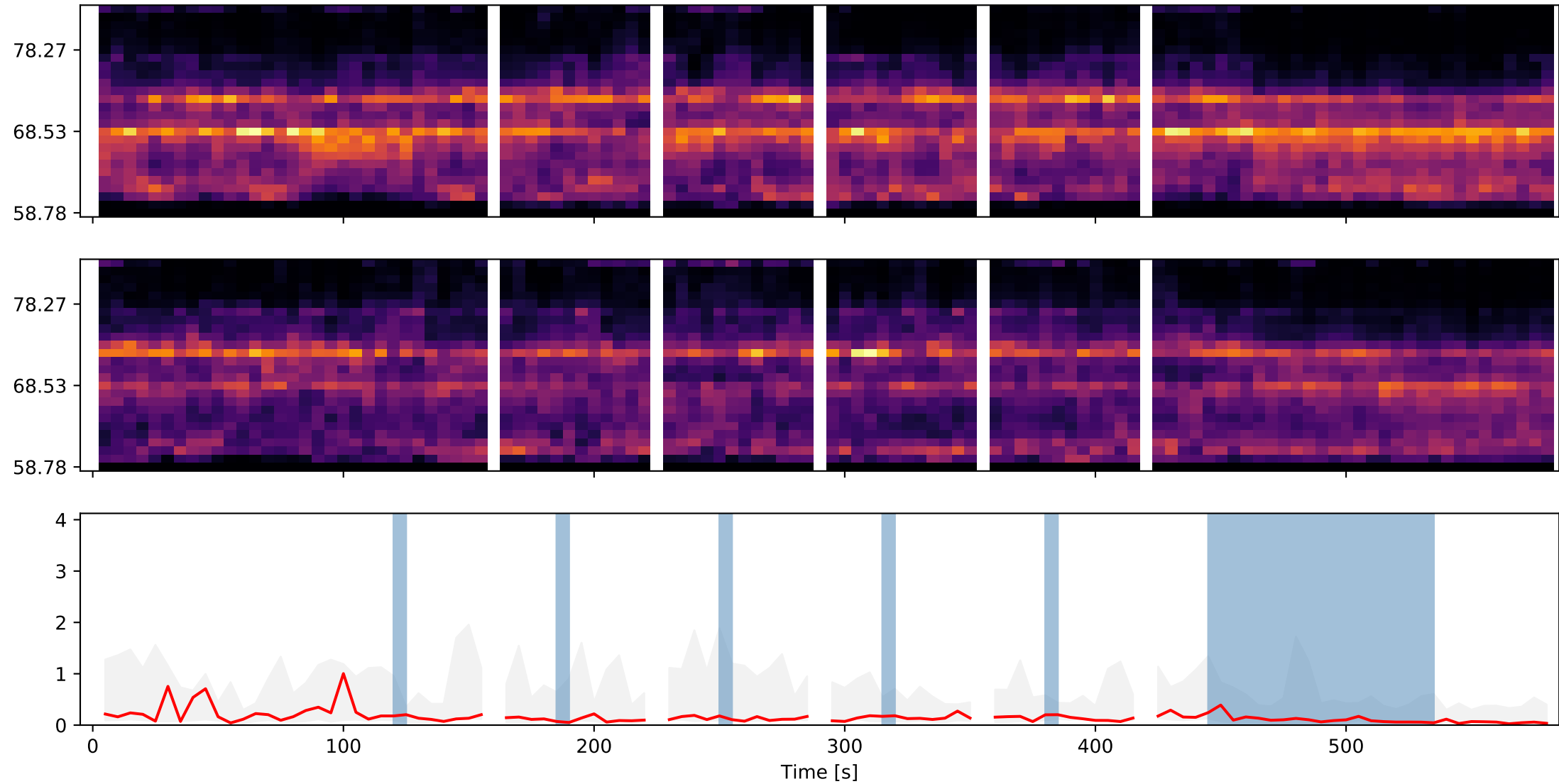
width_head_base



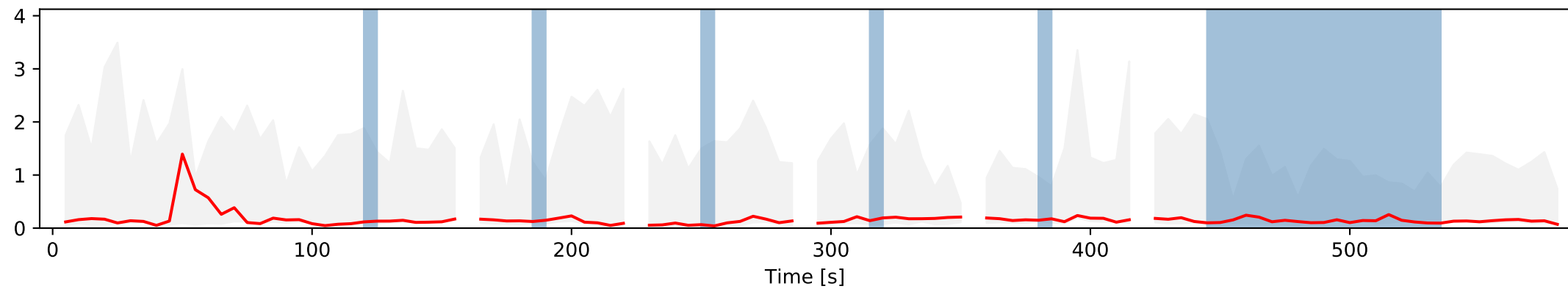
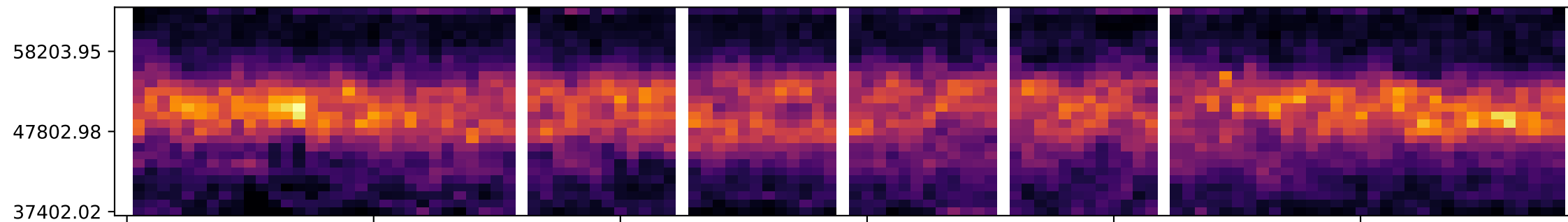
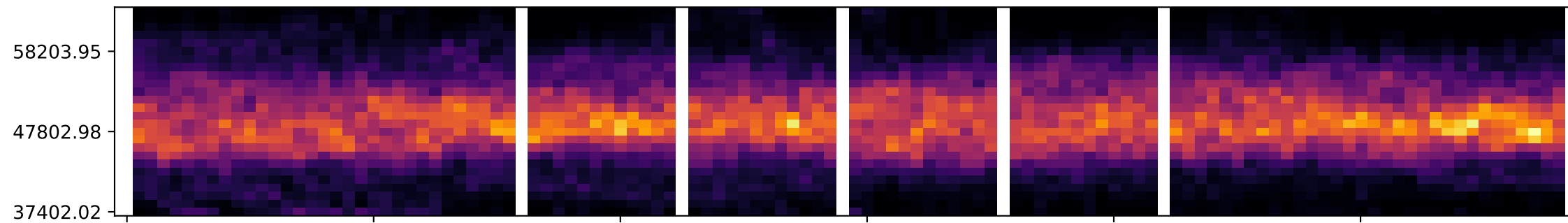
width_tail_base



width_midbody



area



length

