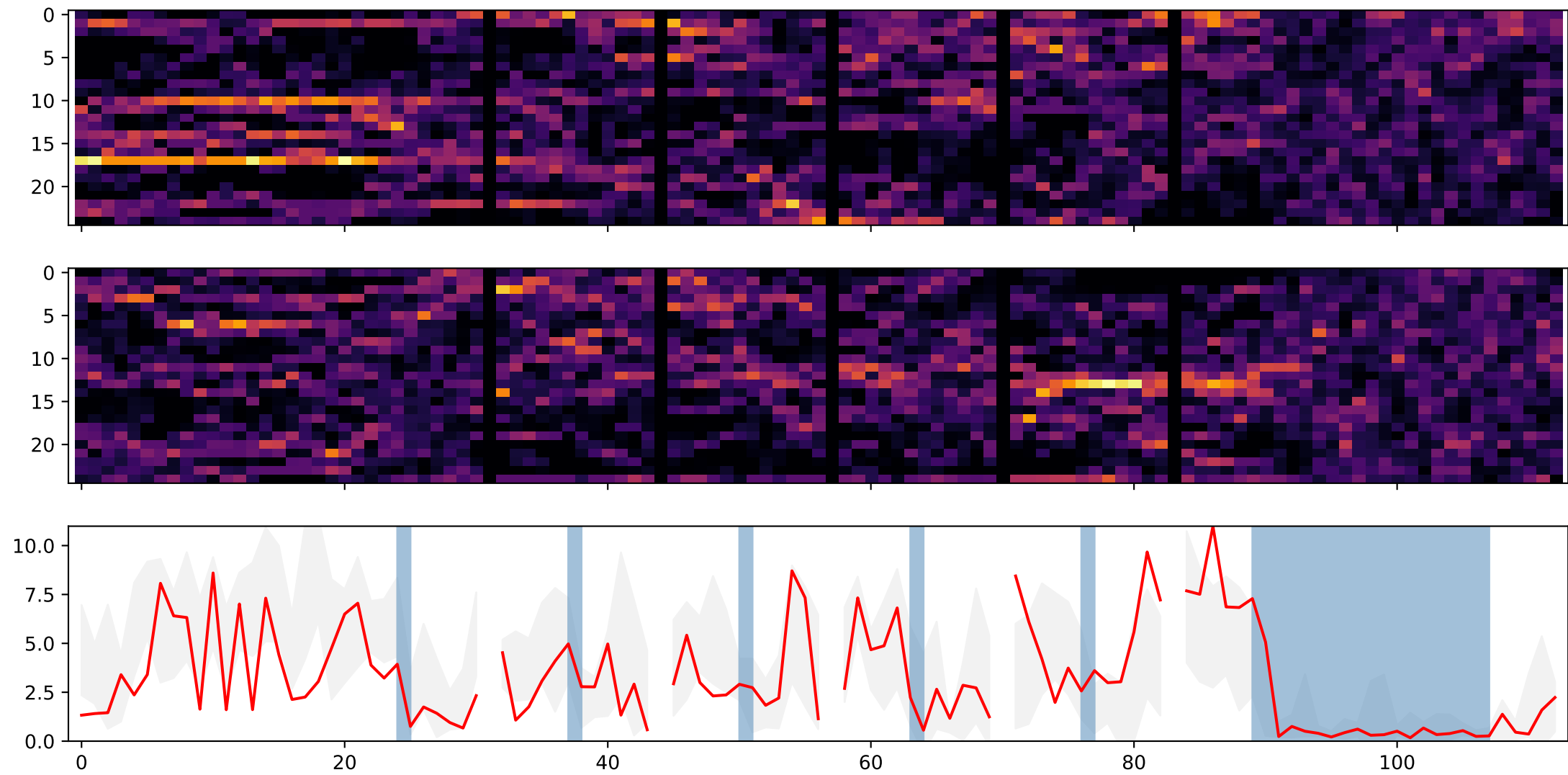
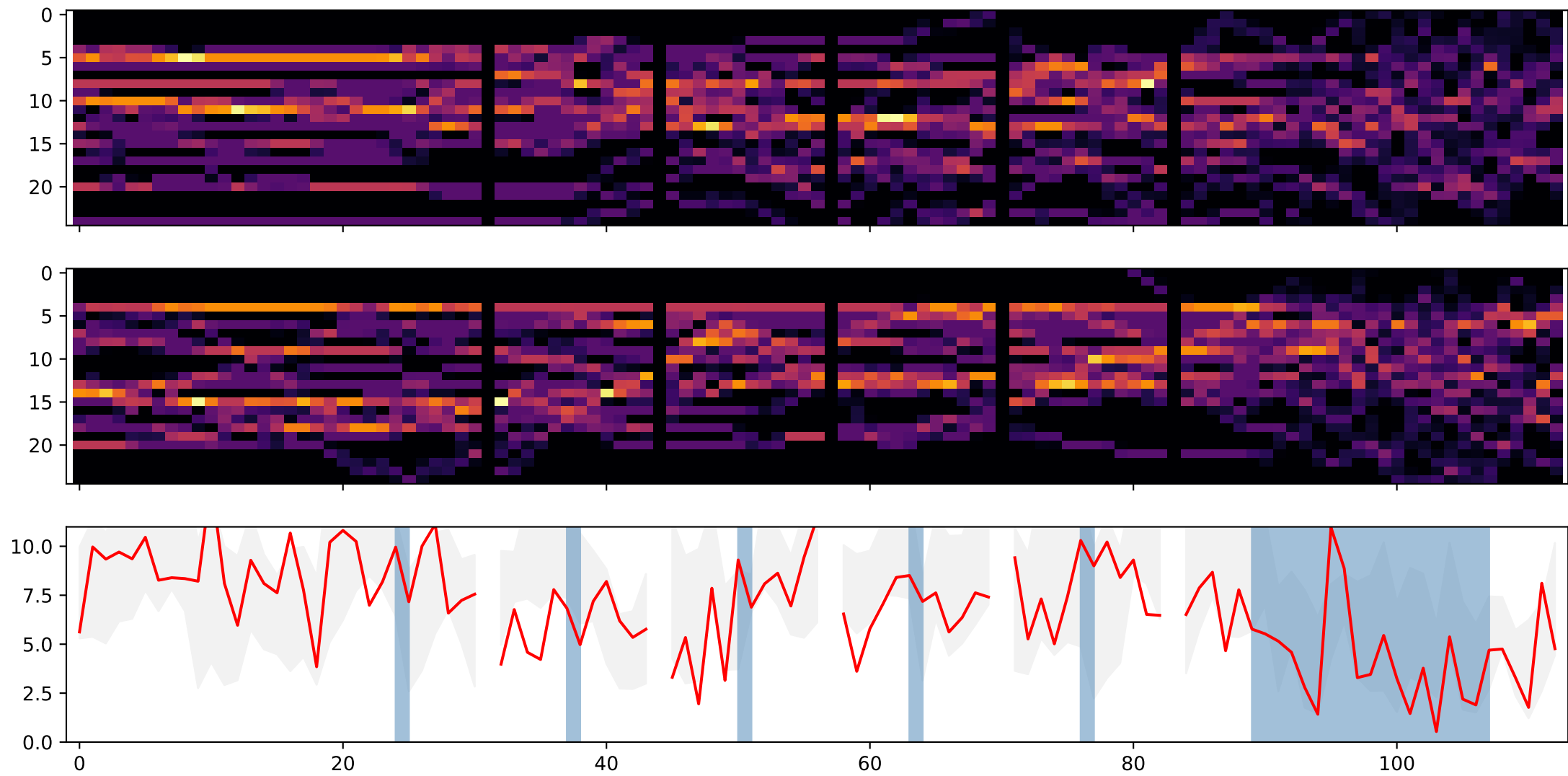


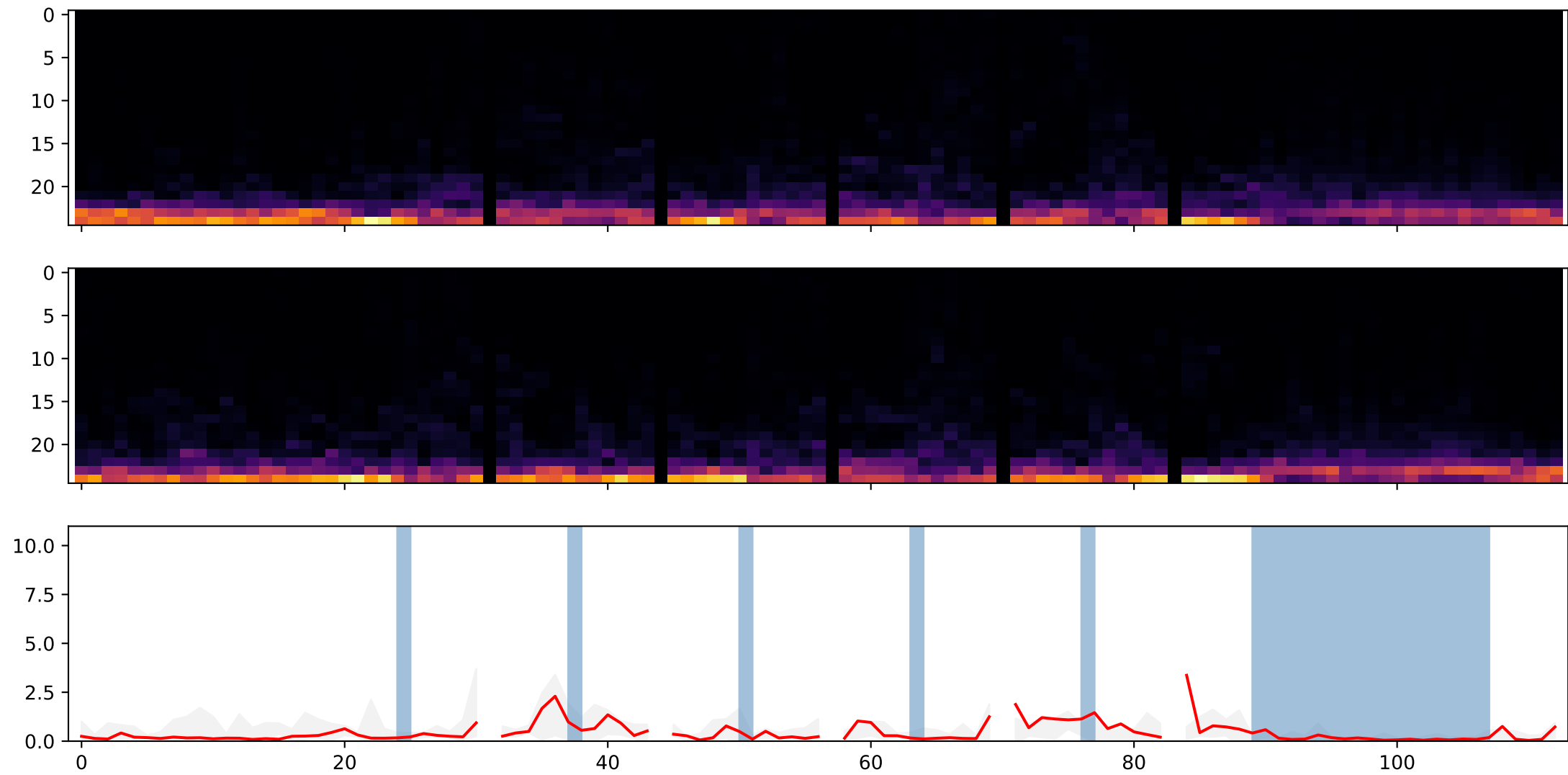
orientation_food_edge



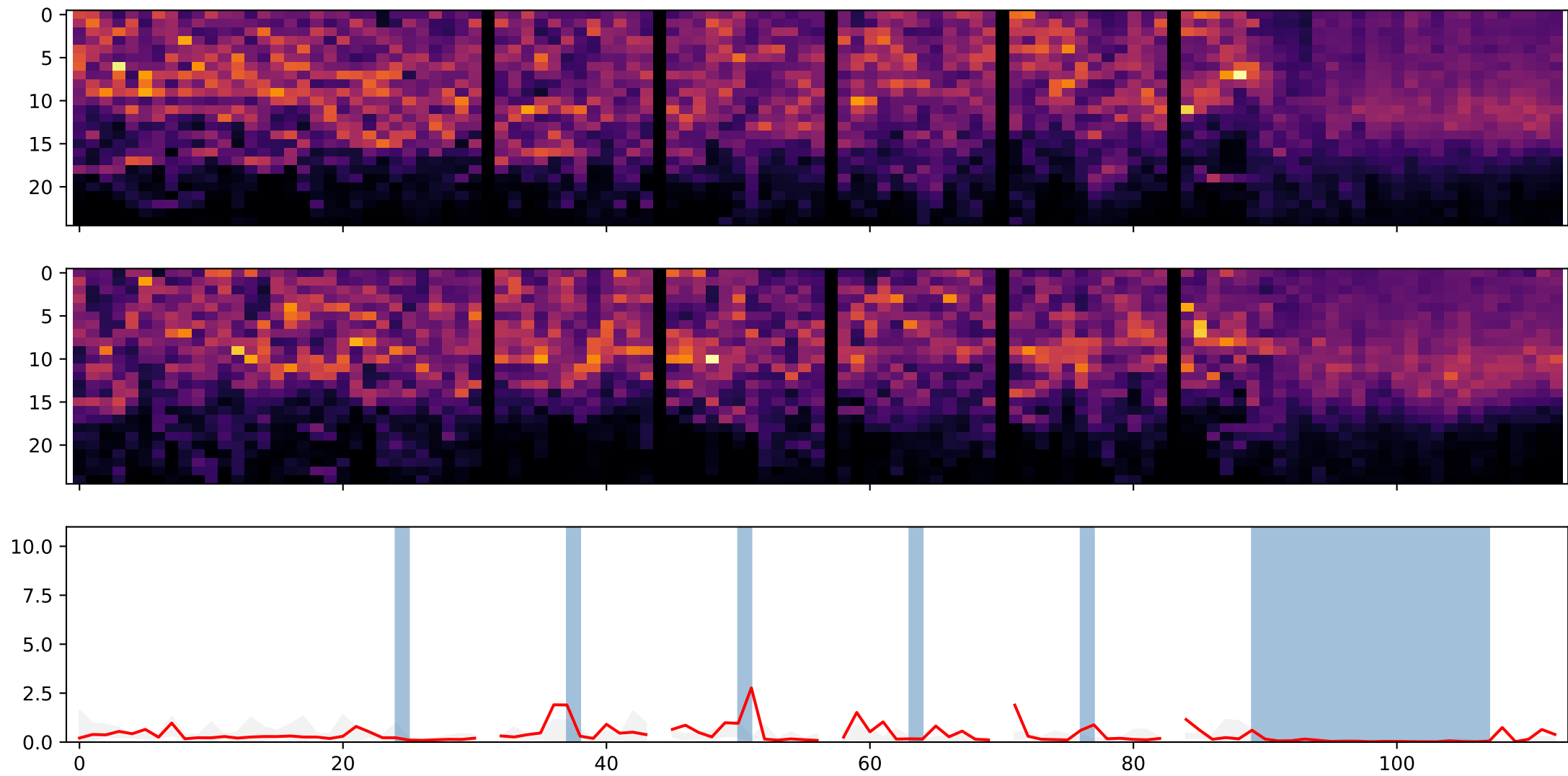
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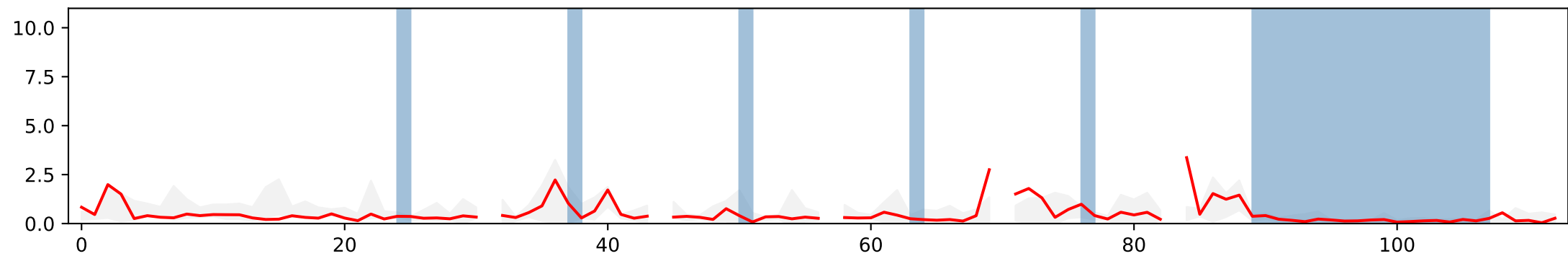
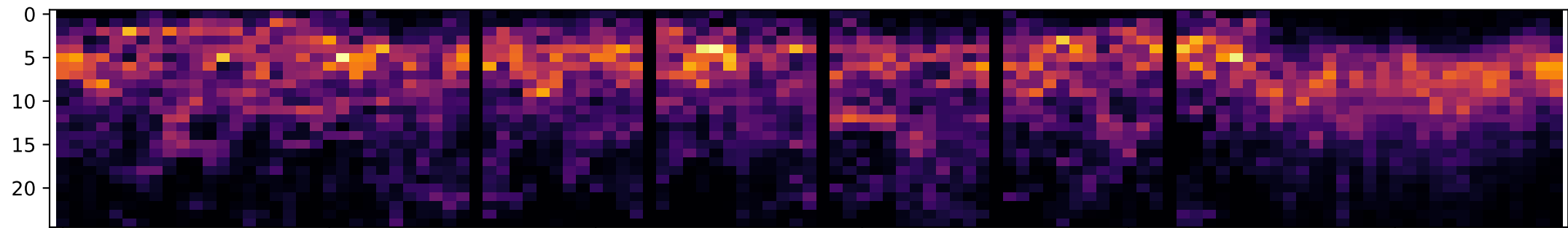
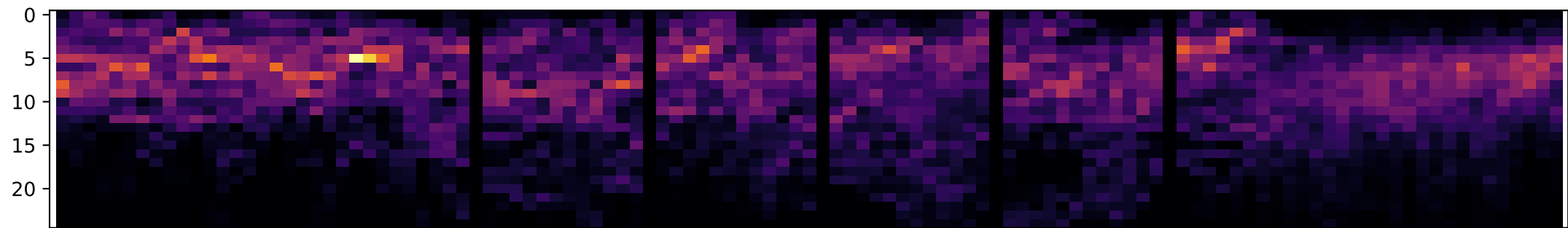
quirkiness



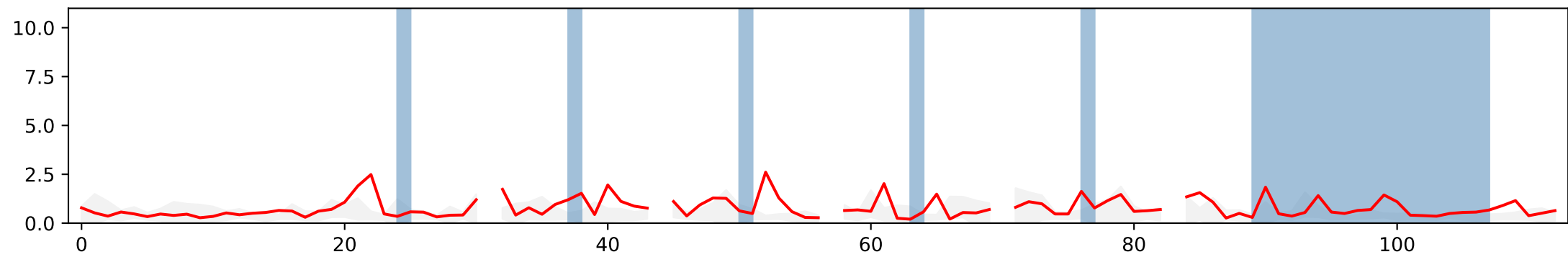
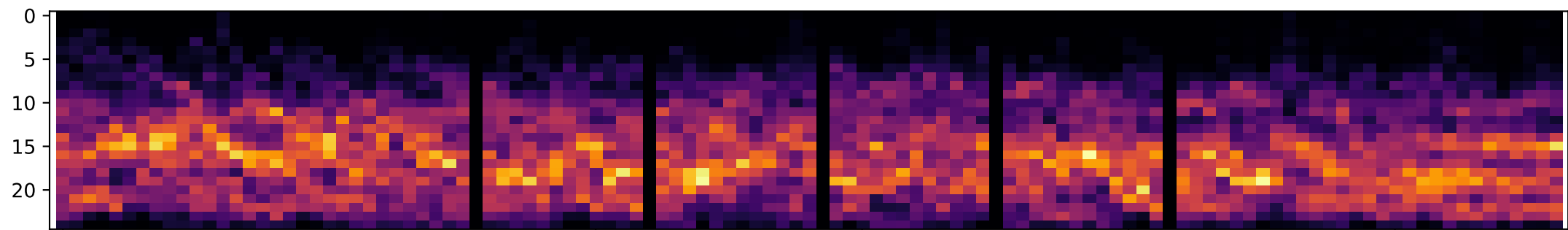
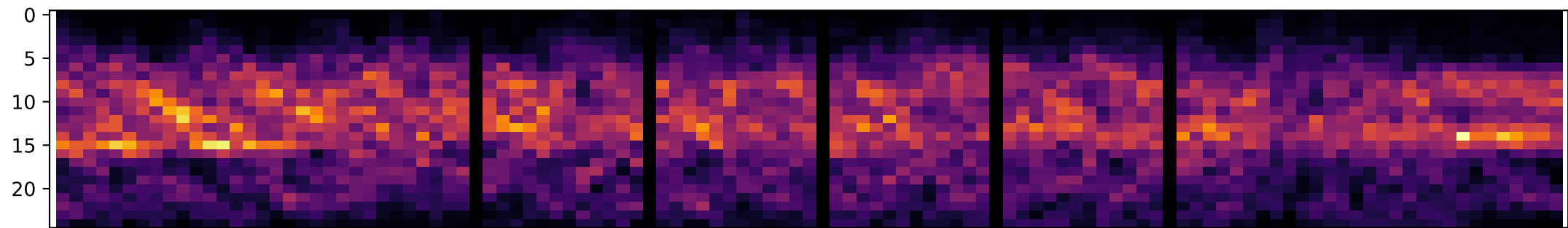
curvature_mean_hips



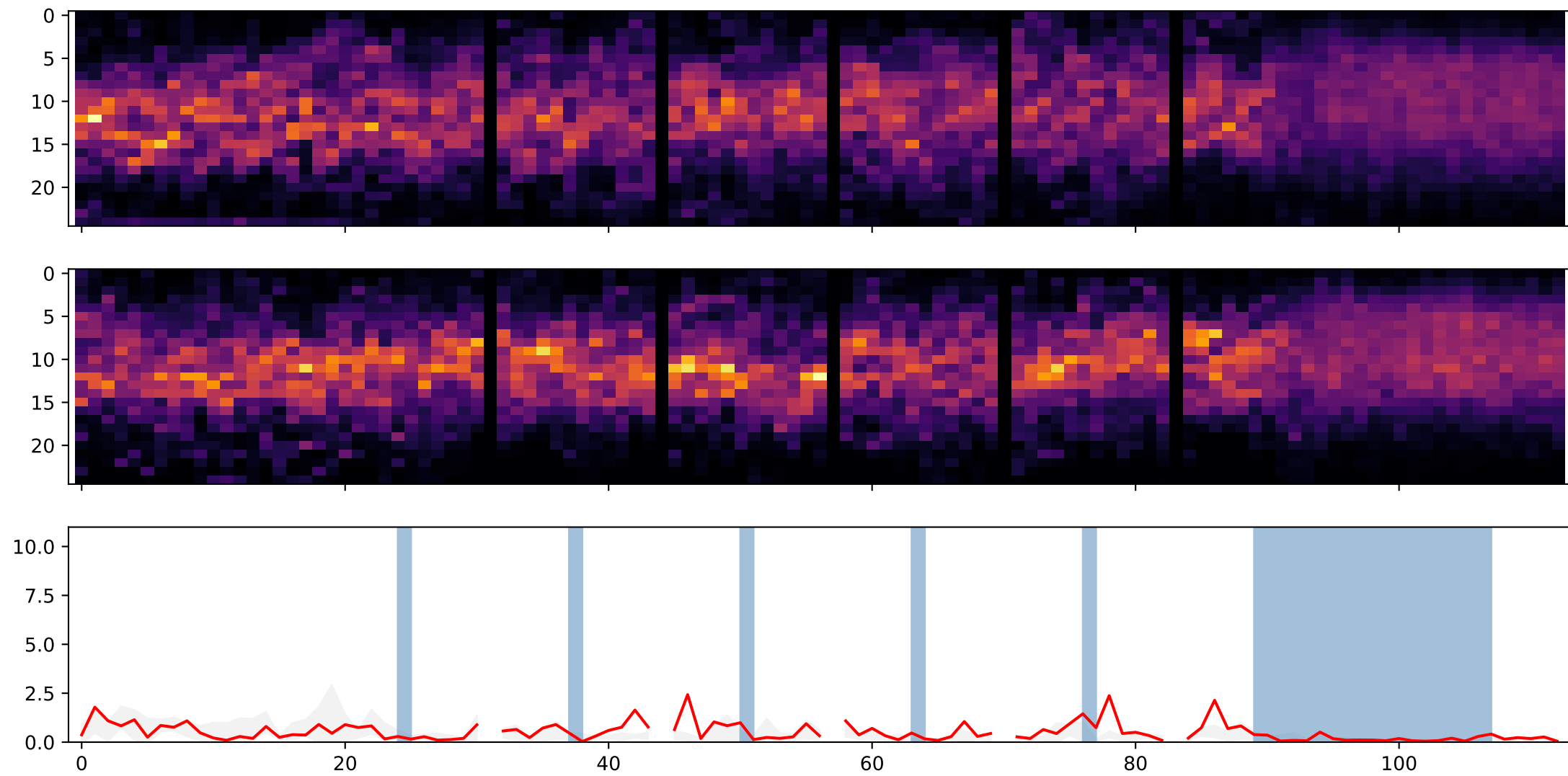
minor_axis



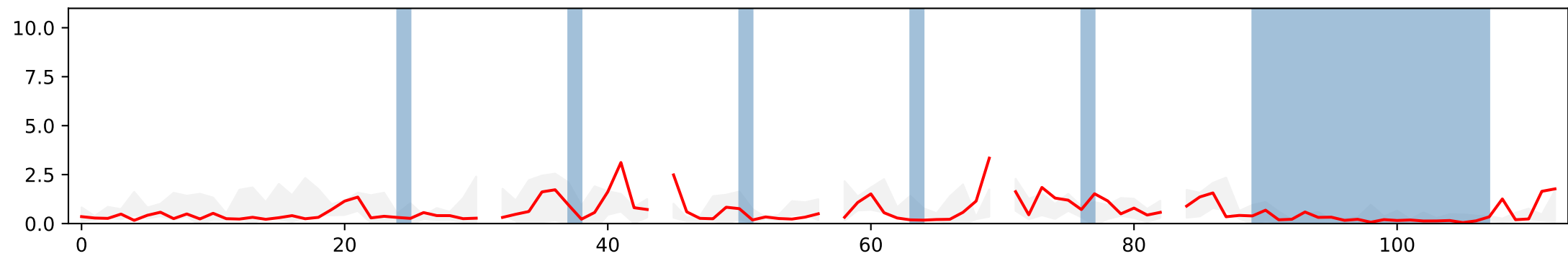
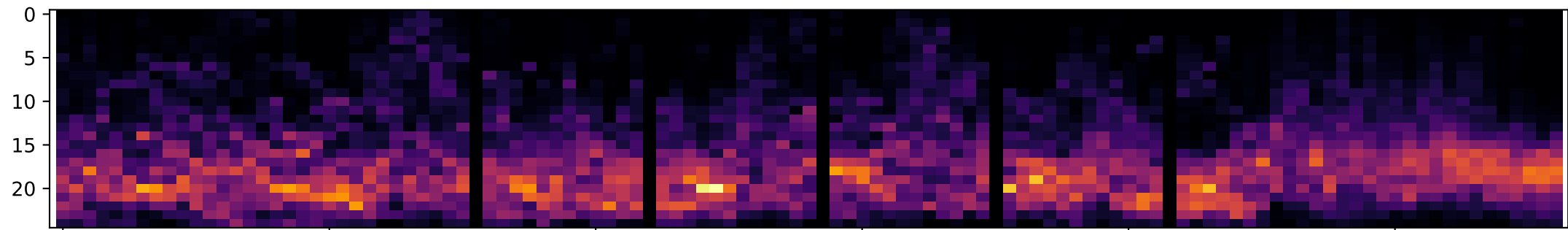
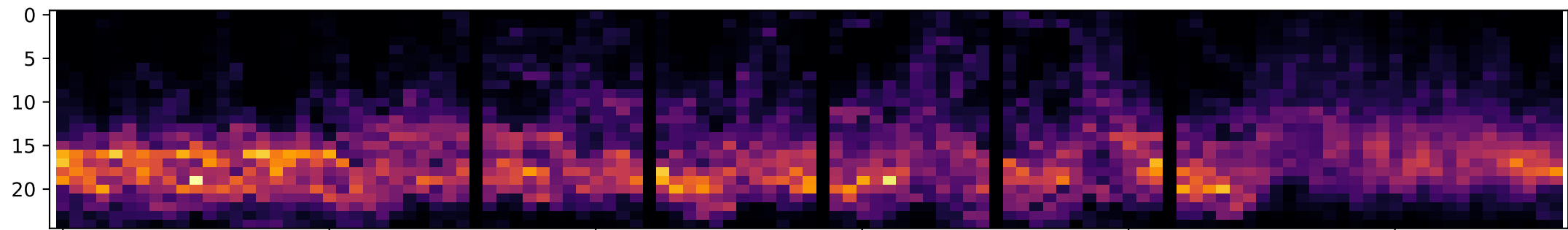
length



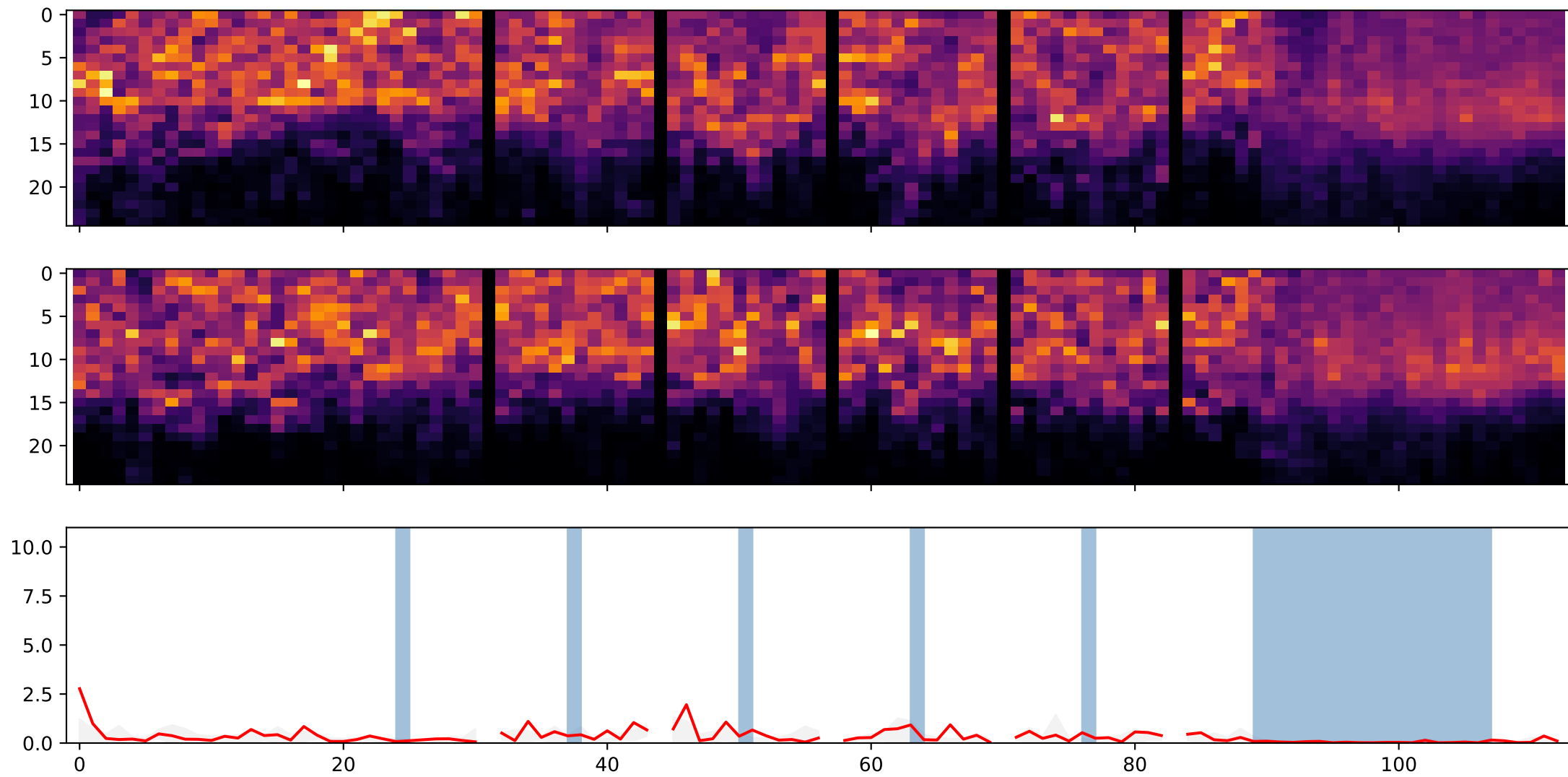
curvature_std_midbody



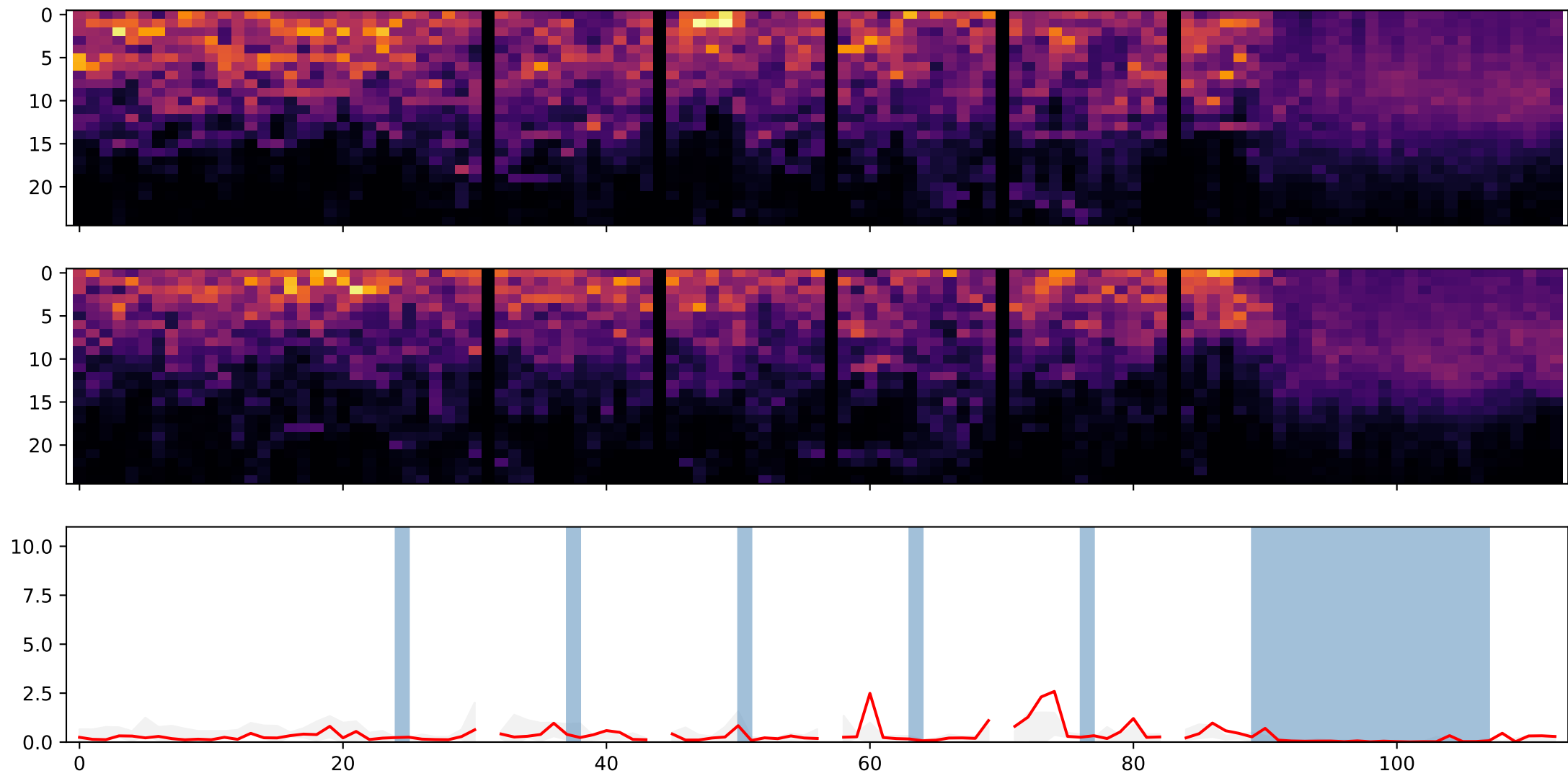
major_axis



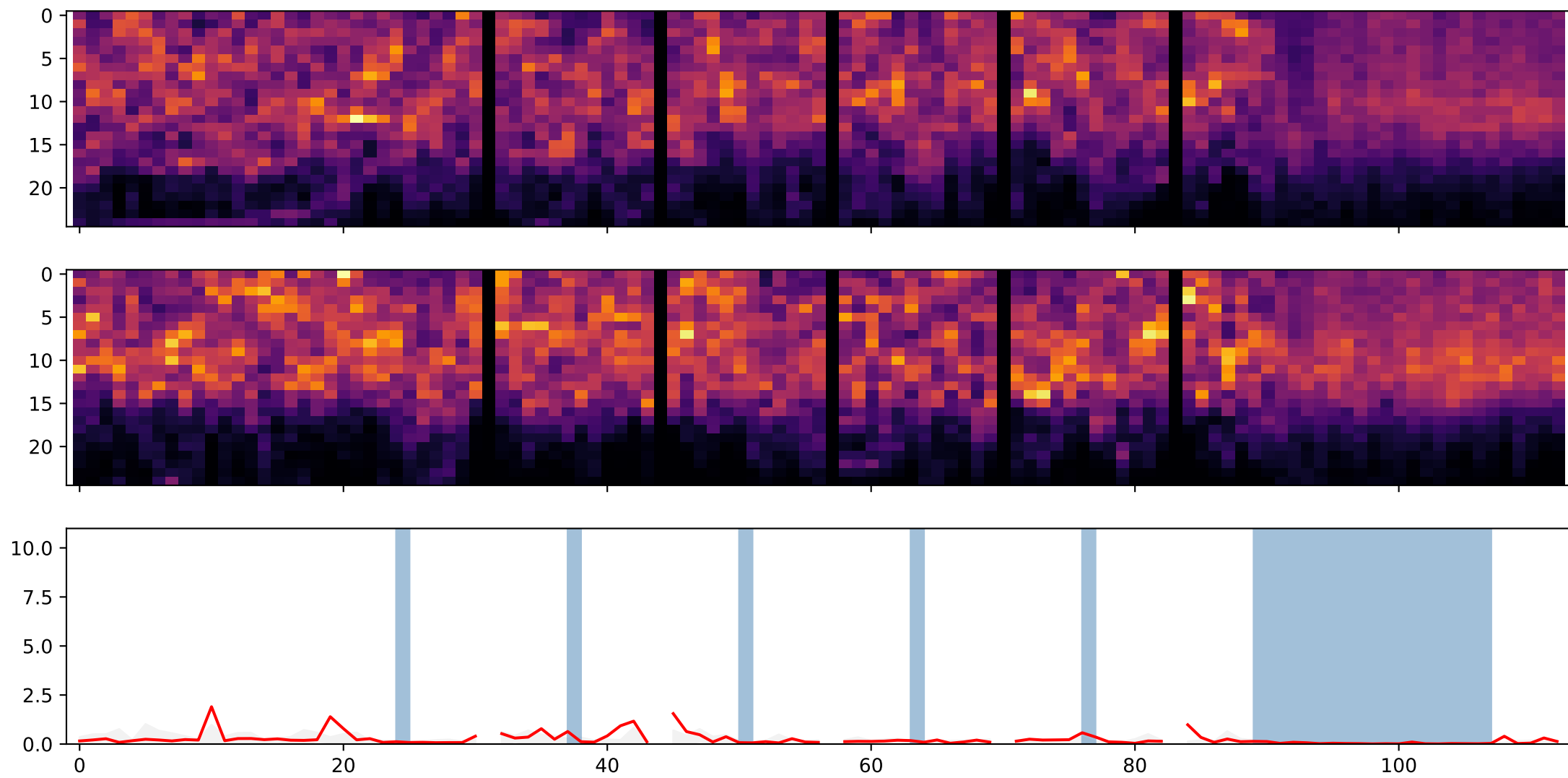
curvature_mean_tail



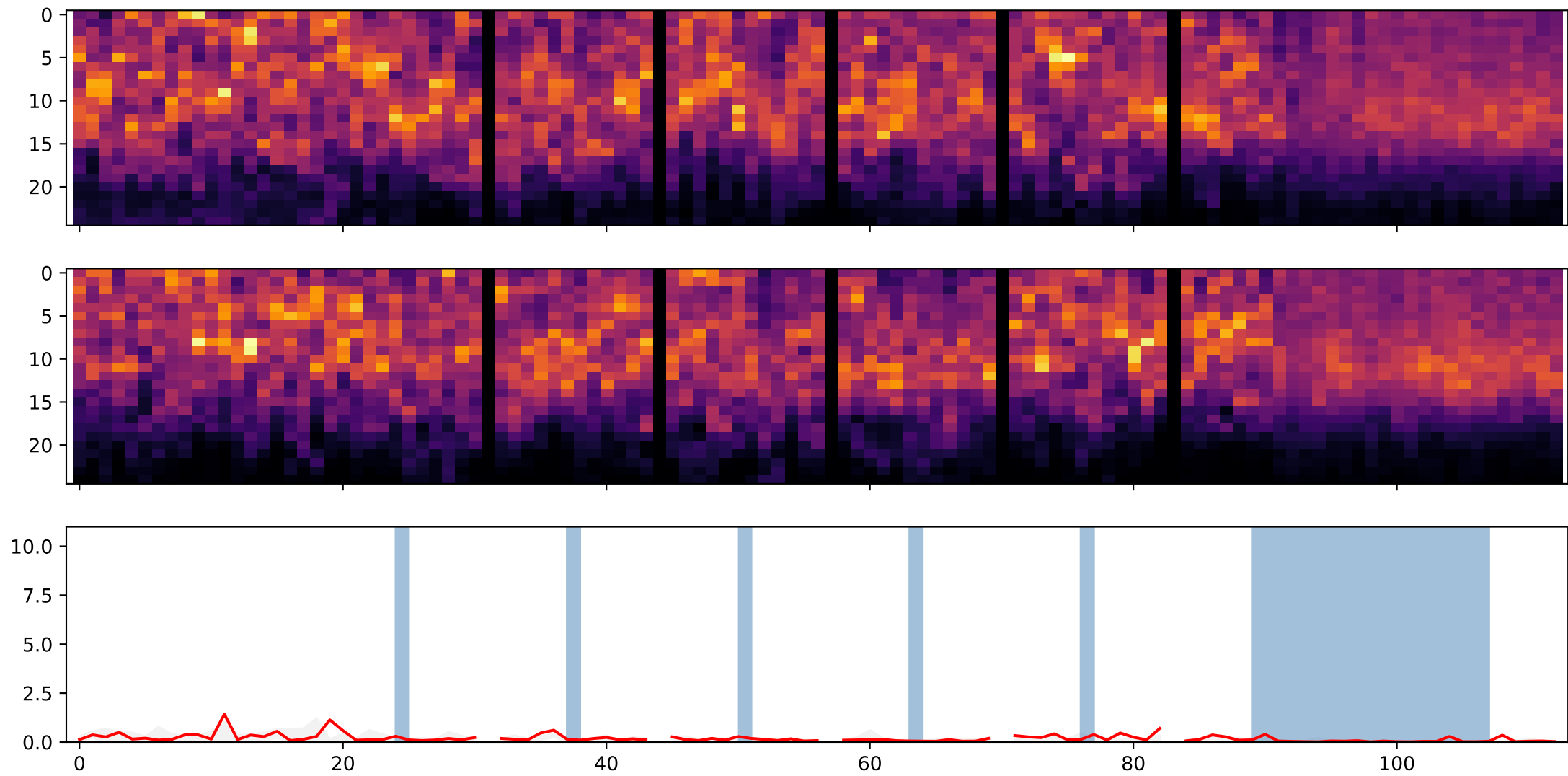
curvature_mean_midbody



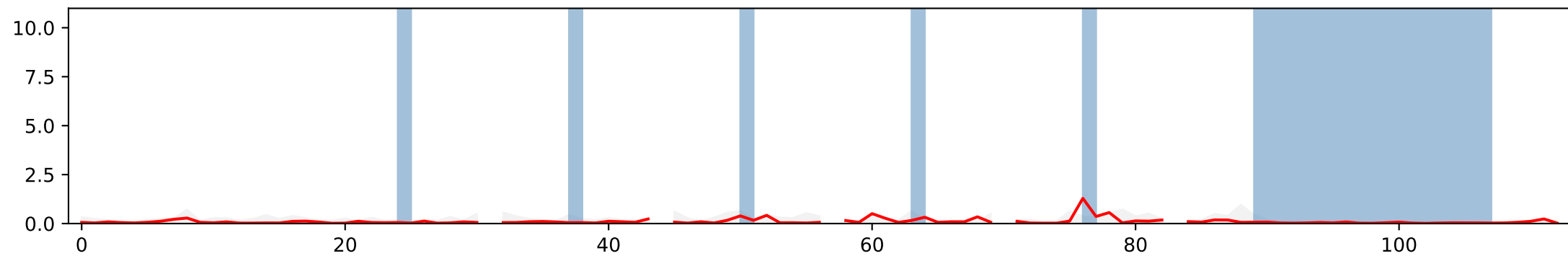
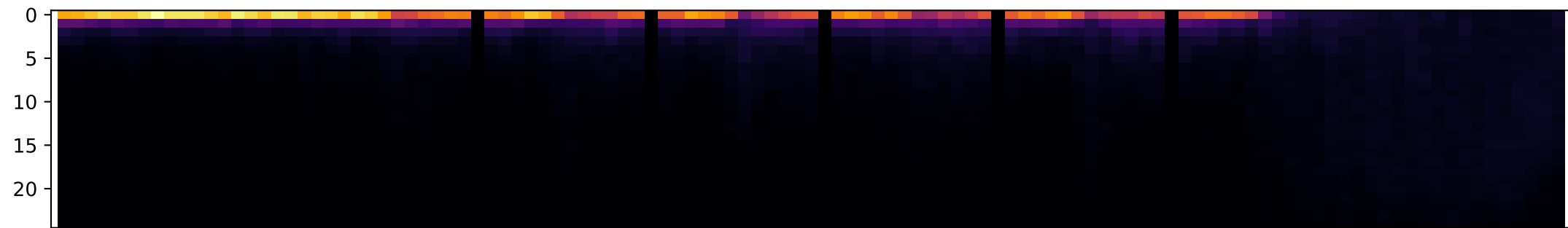
curvature_hips



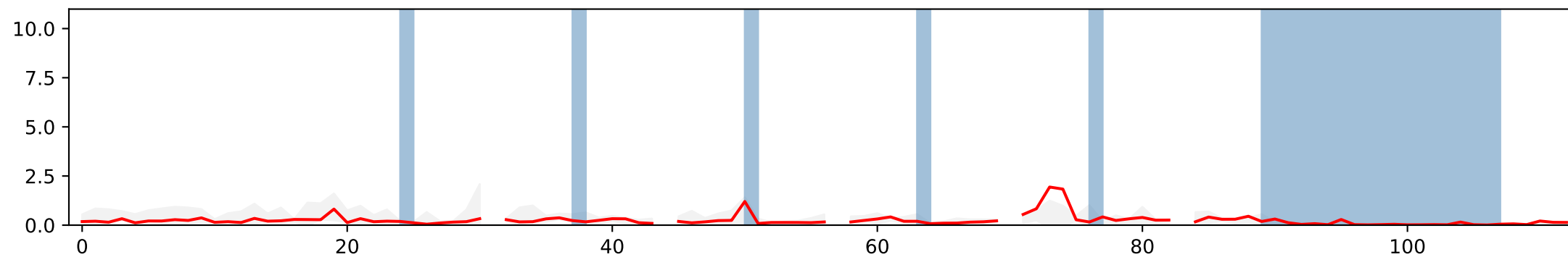
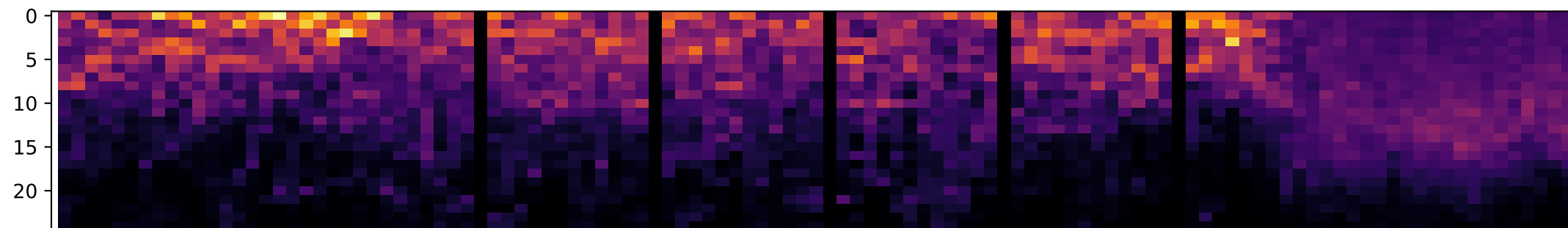
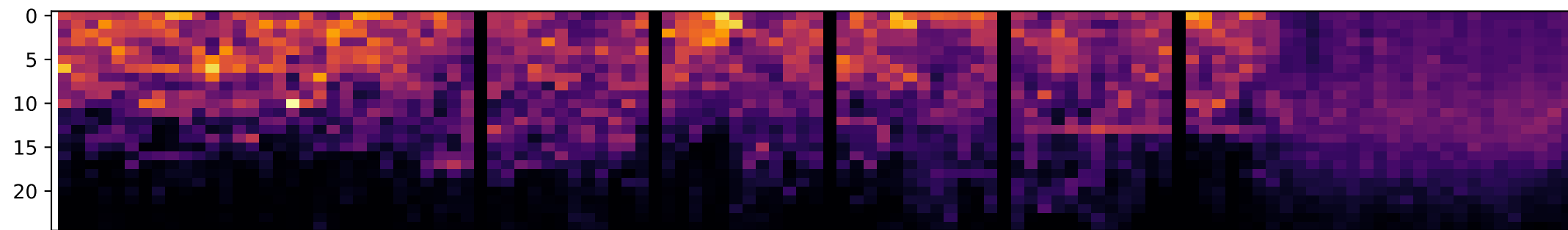
curvature_midbody



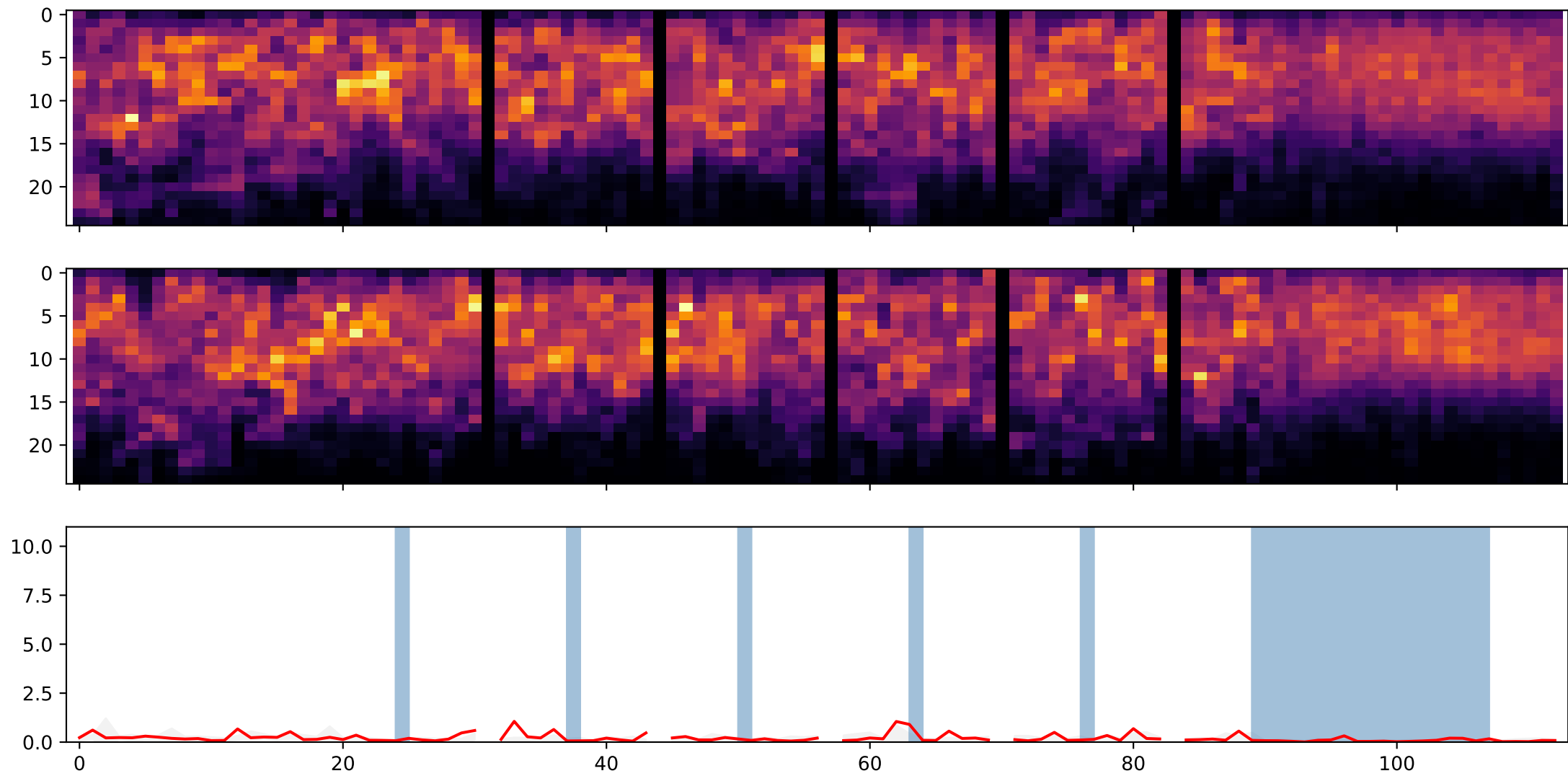
d_curvature_mean_midbody



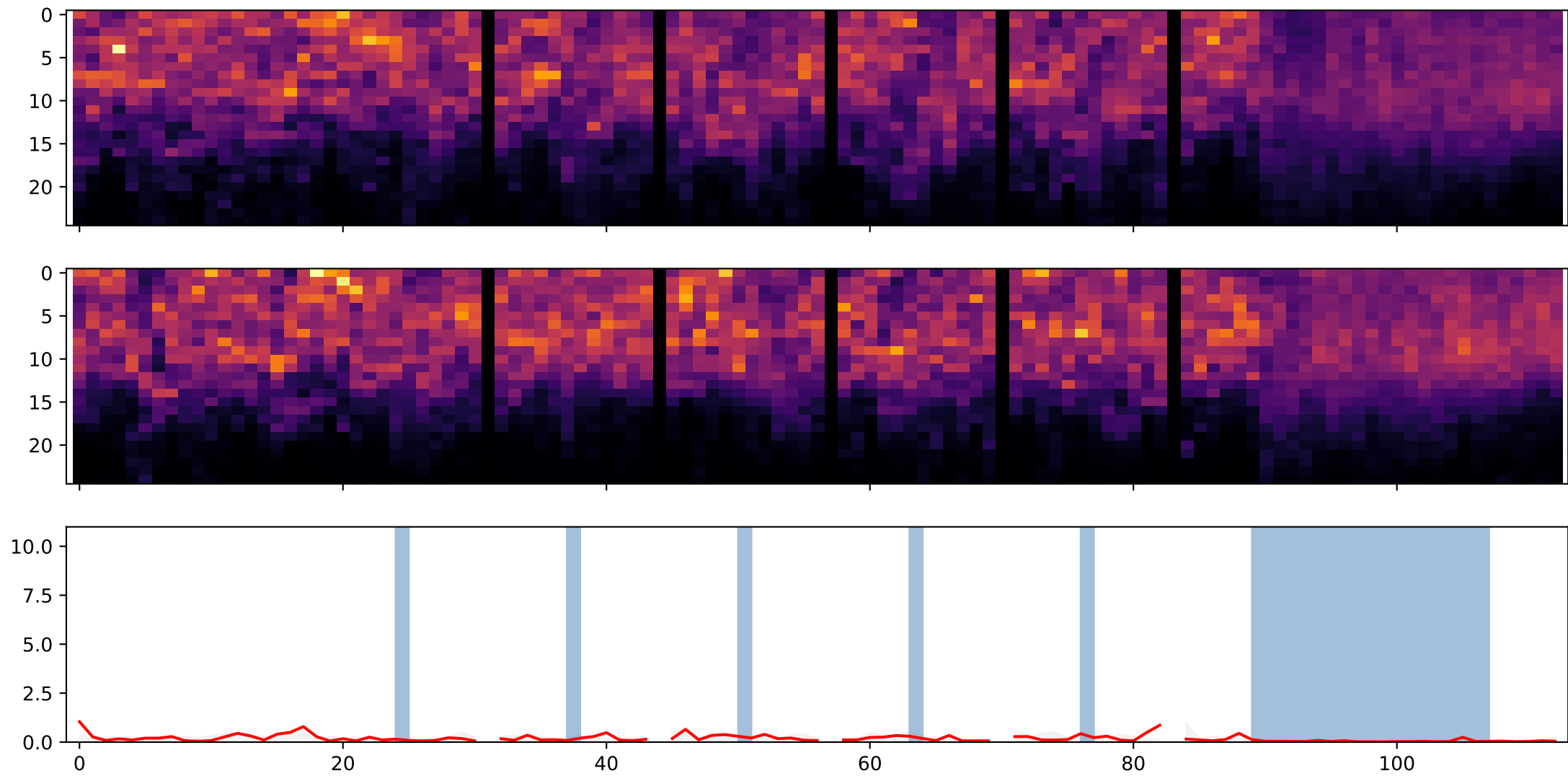
eigen_projection_3



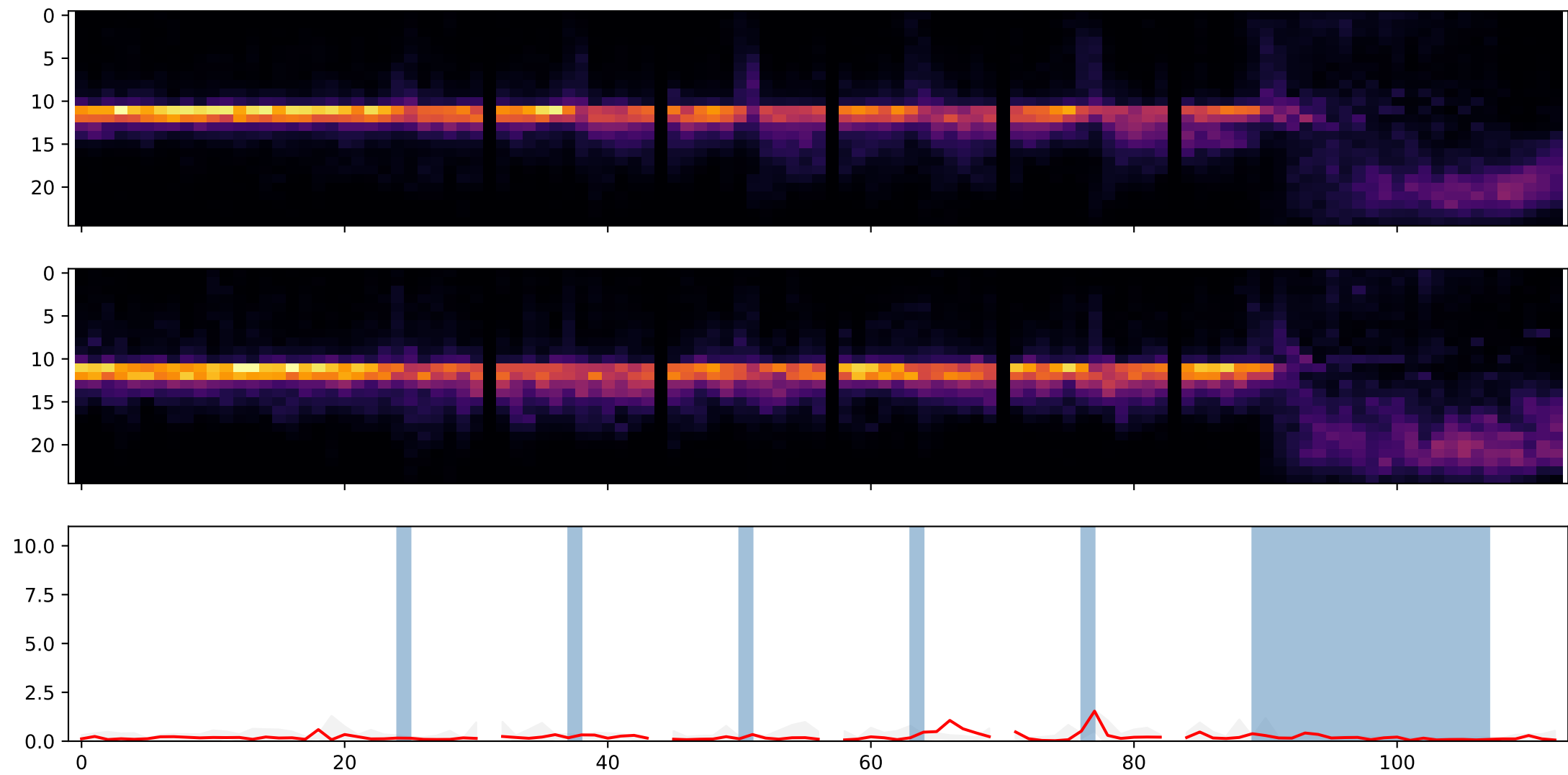
curvature_std_hips



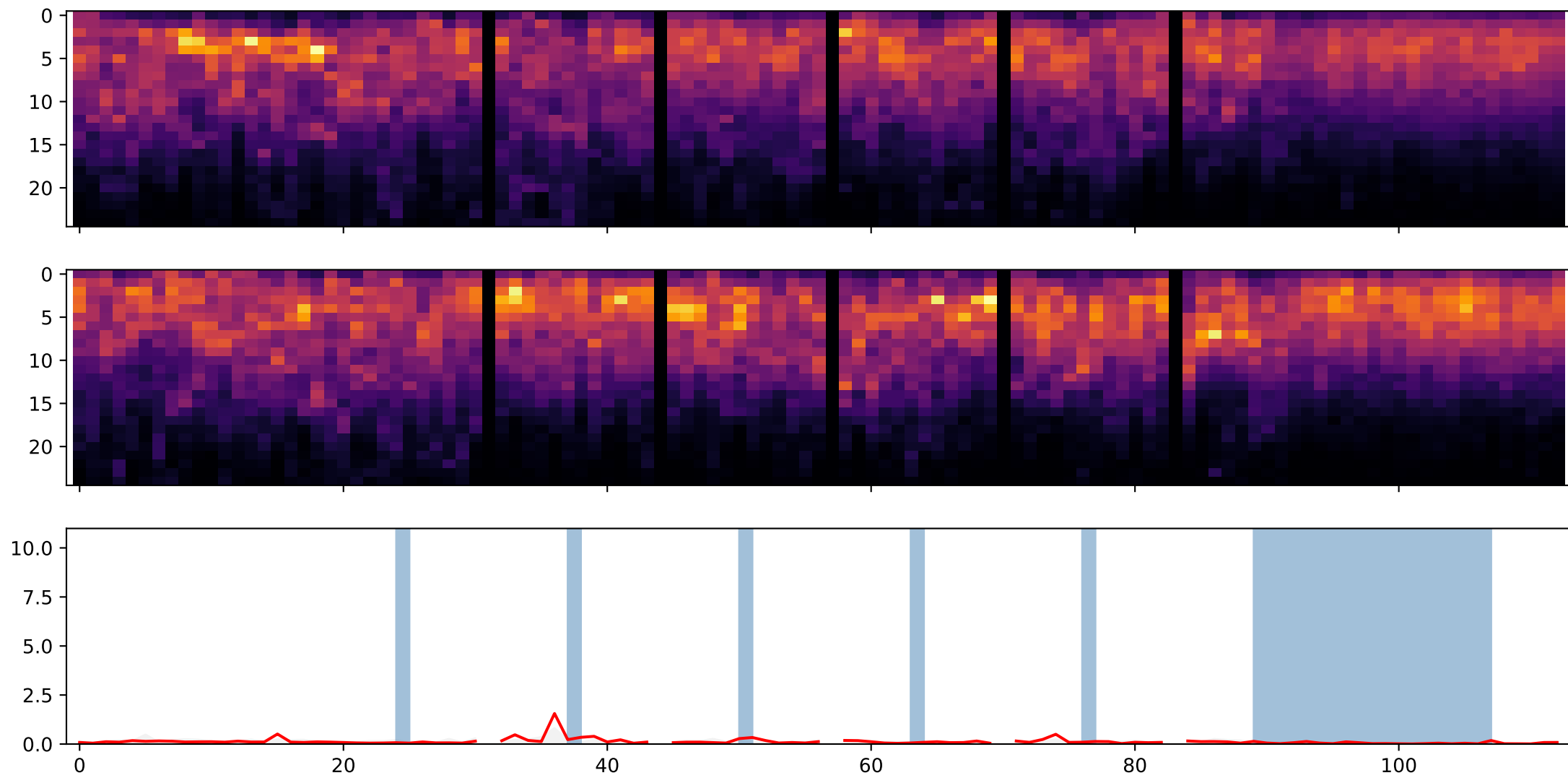
curvature_tail



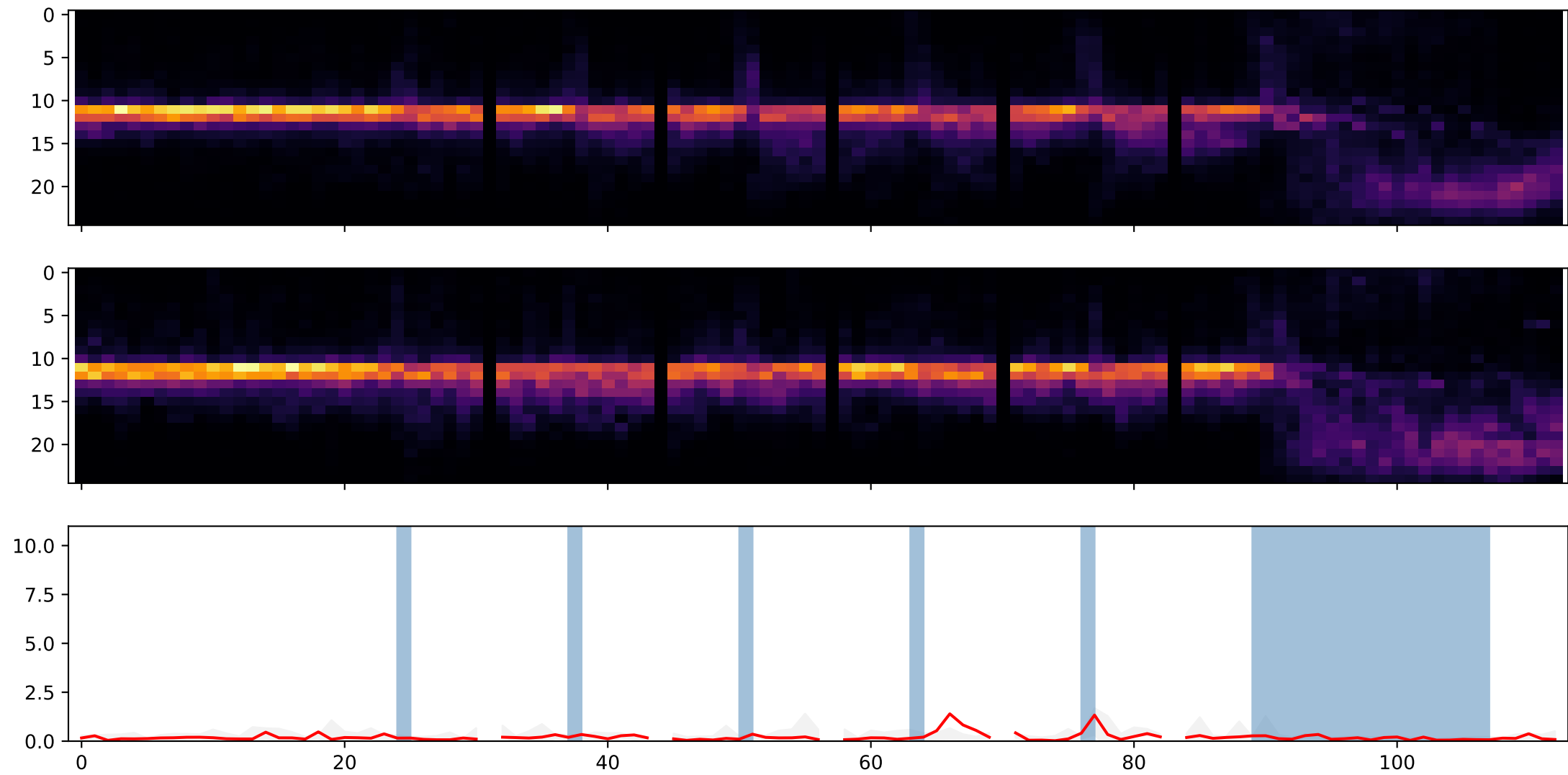
speed_midbody



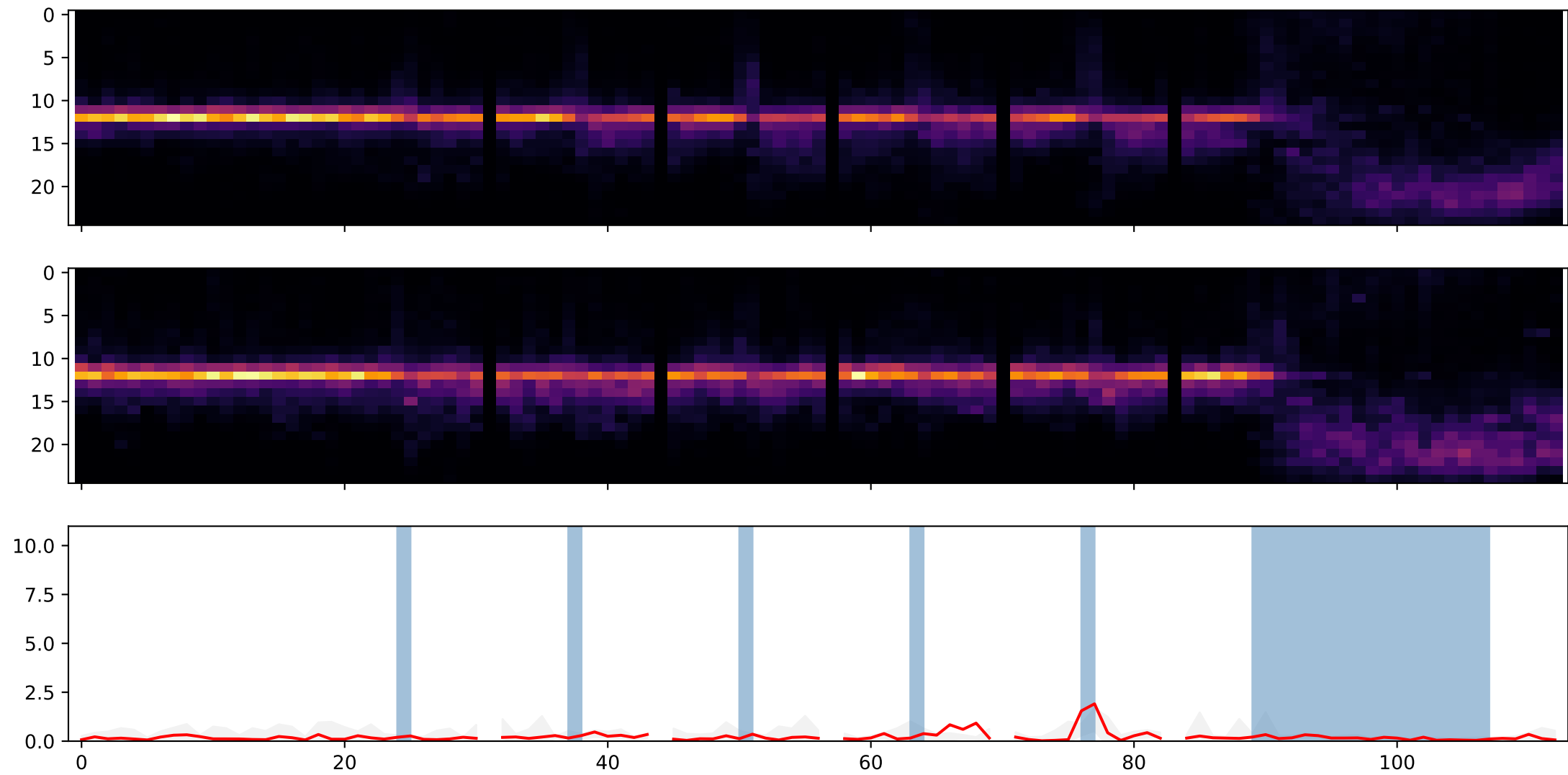
curvature_std_tail



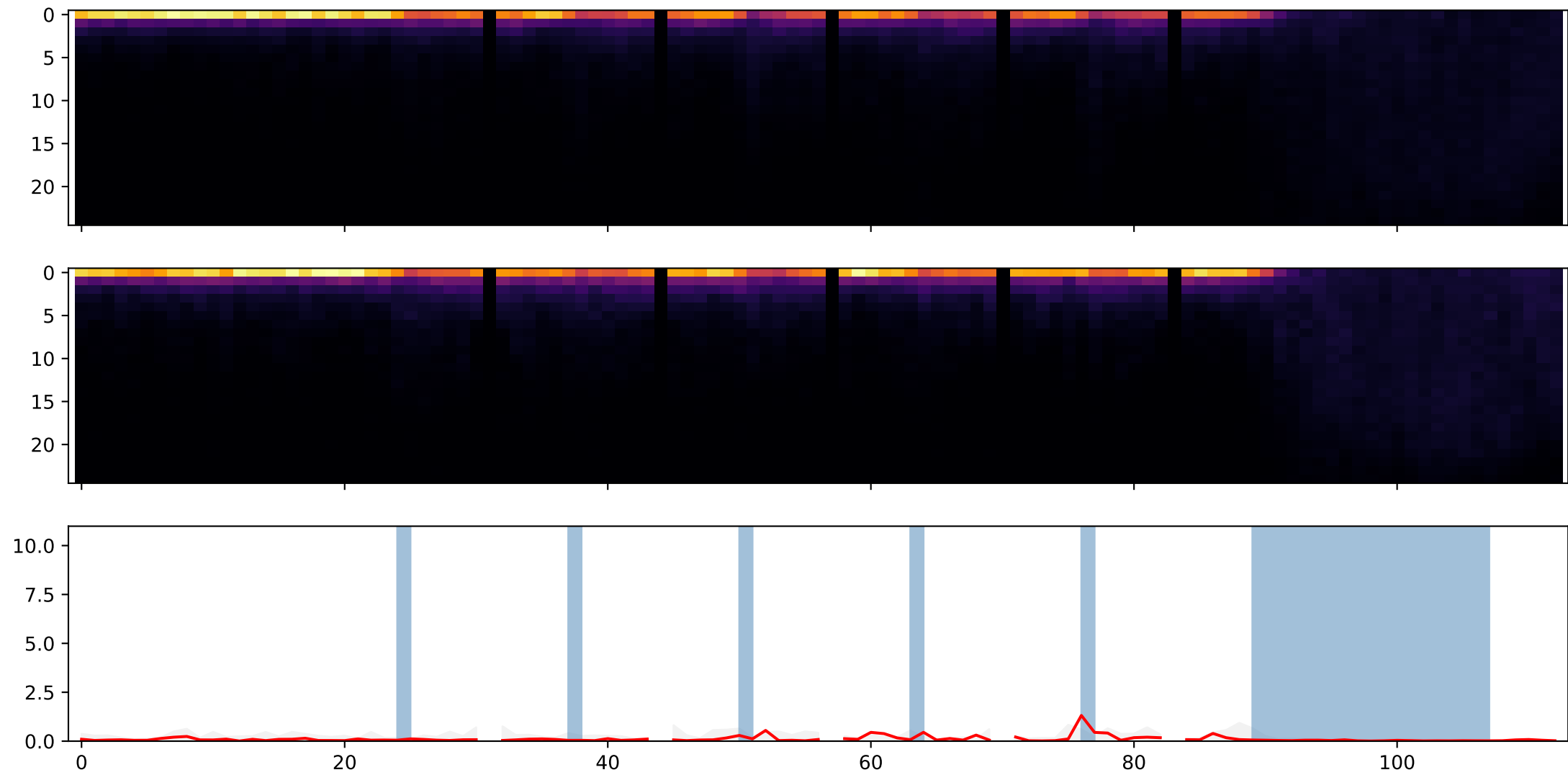
speed



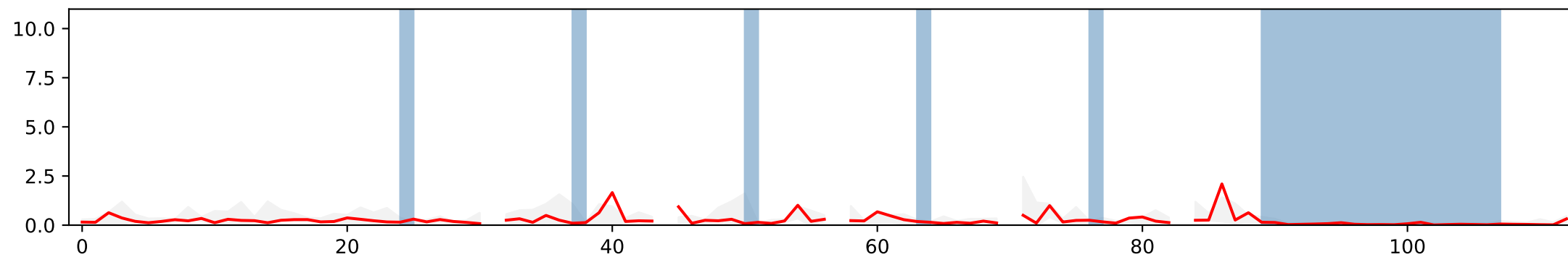
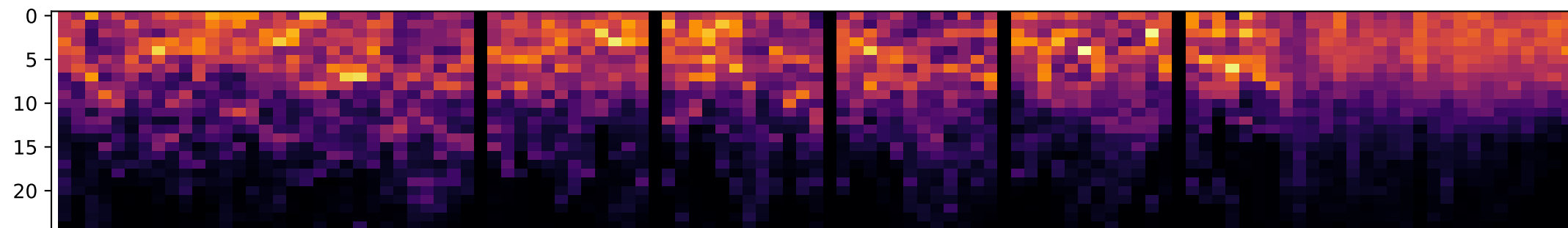
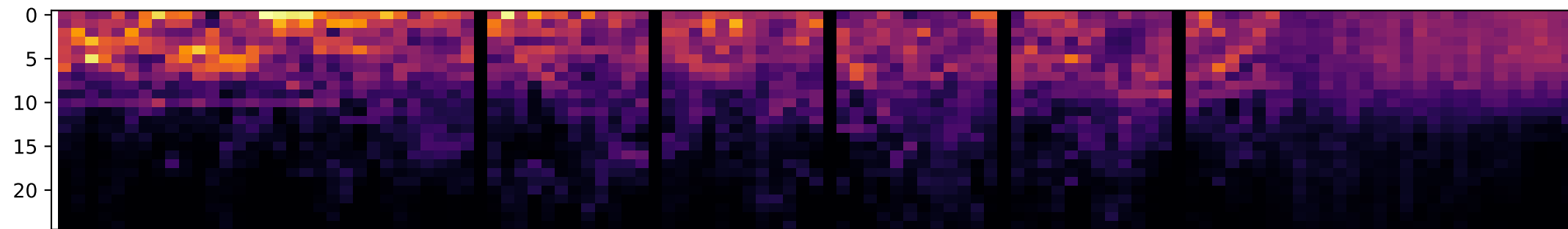
speed_tail_base



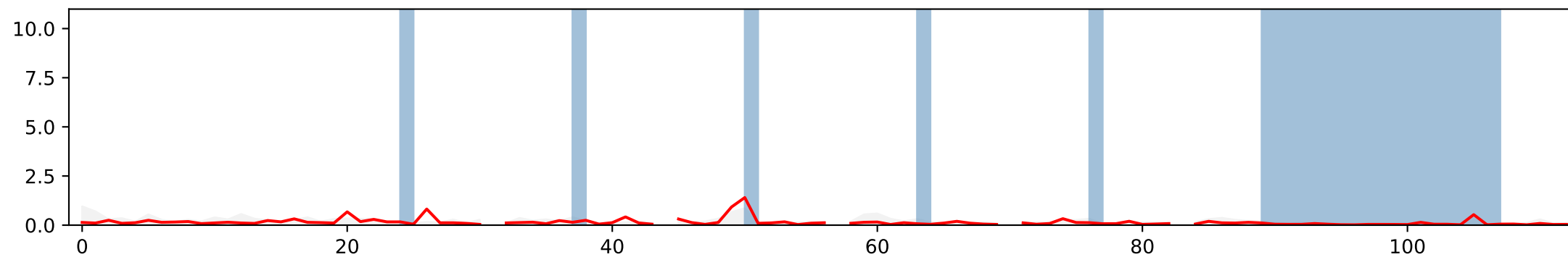
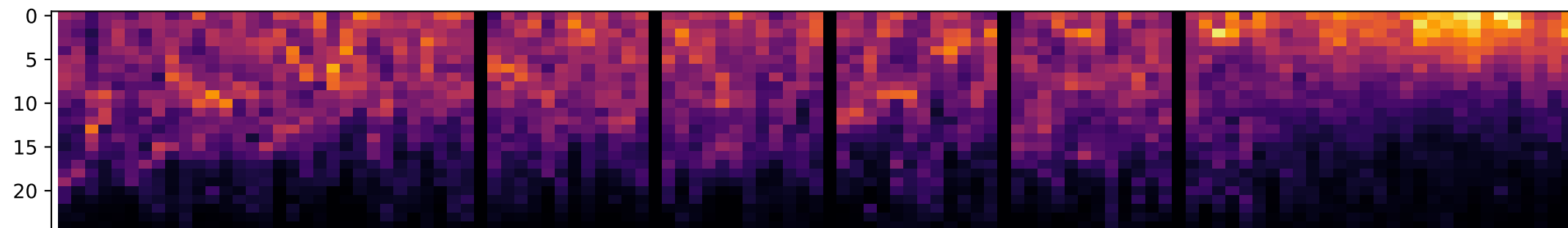
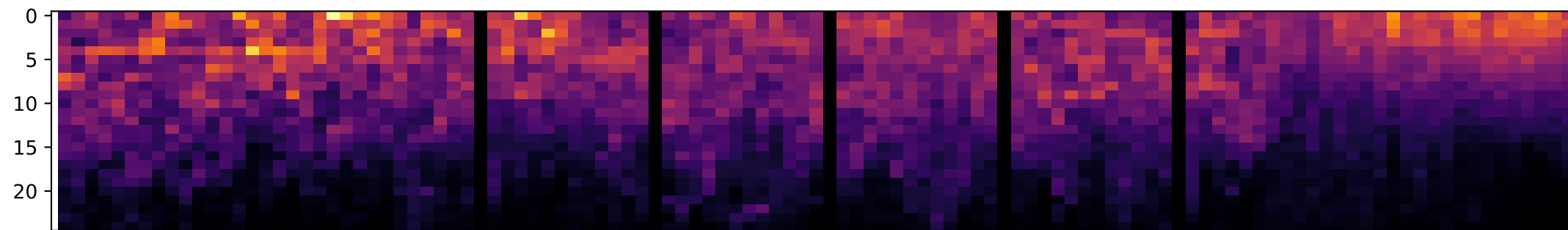
d_eigen_projection_3



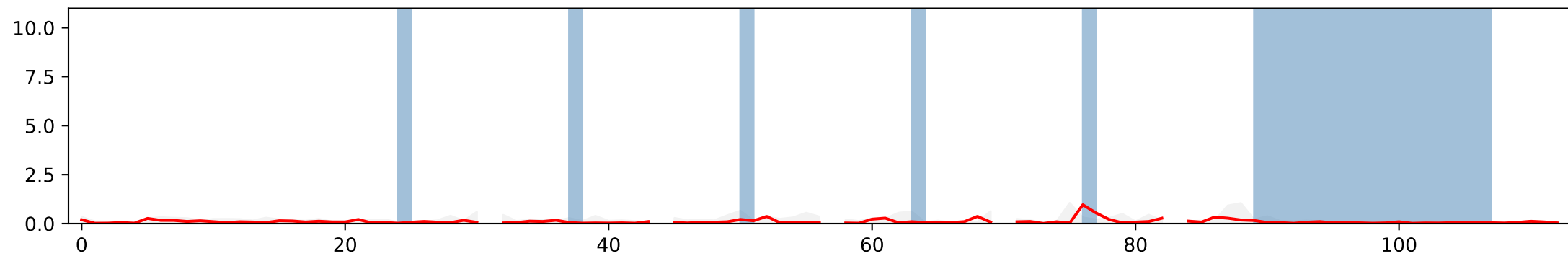
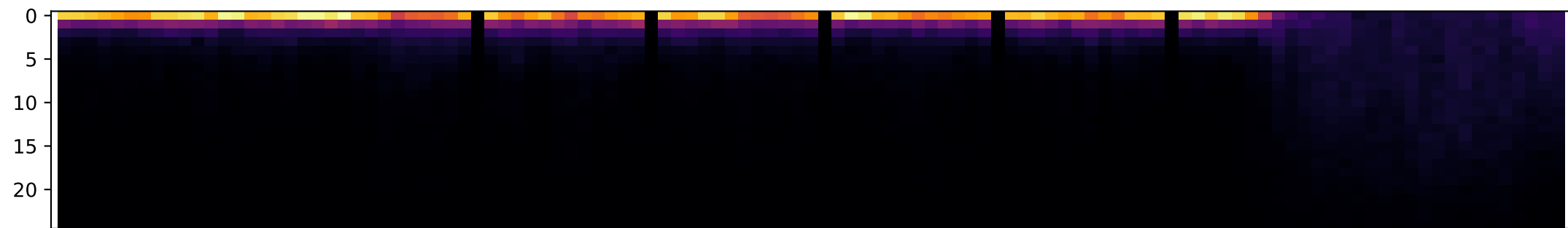
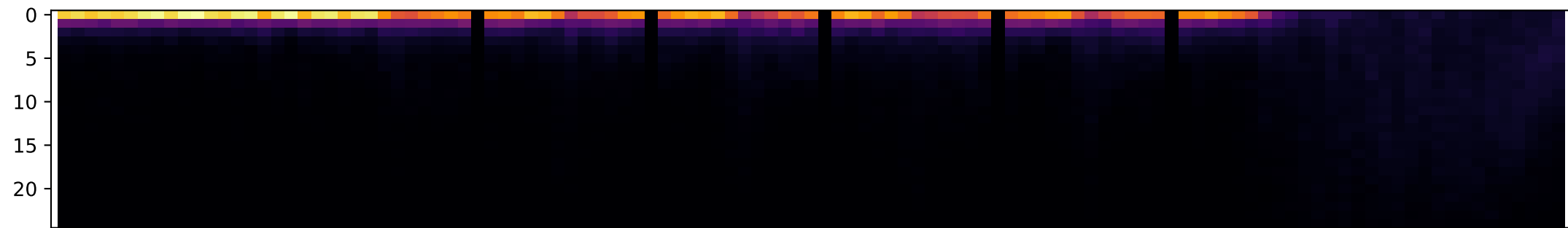
eigen_projection_1



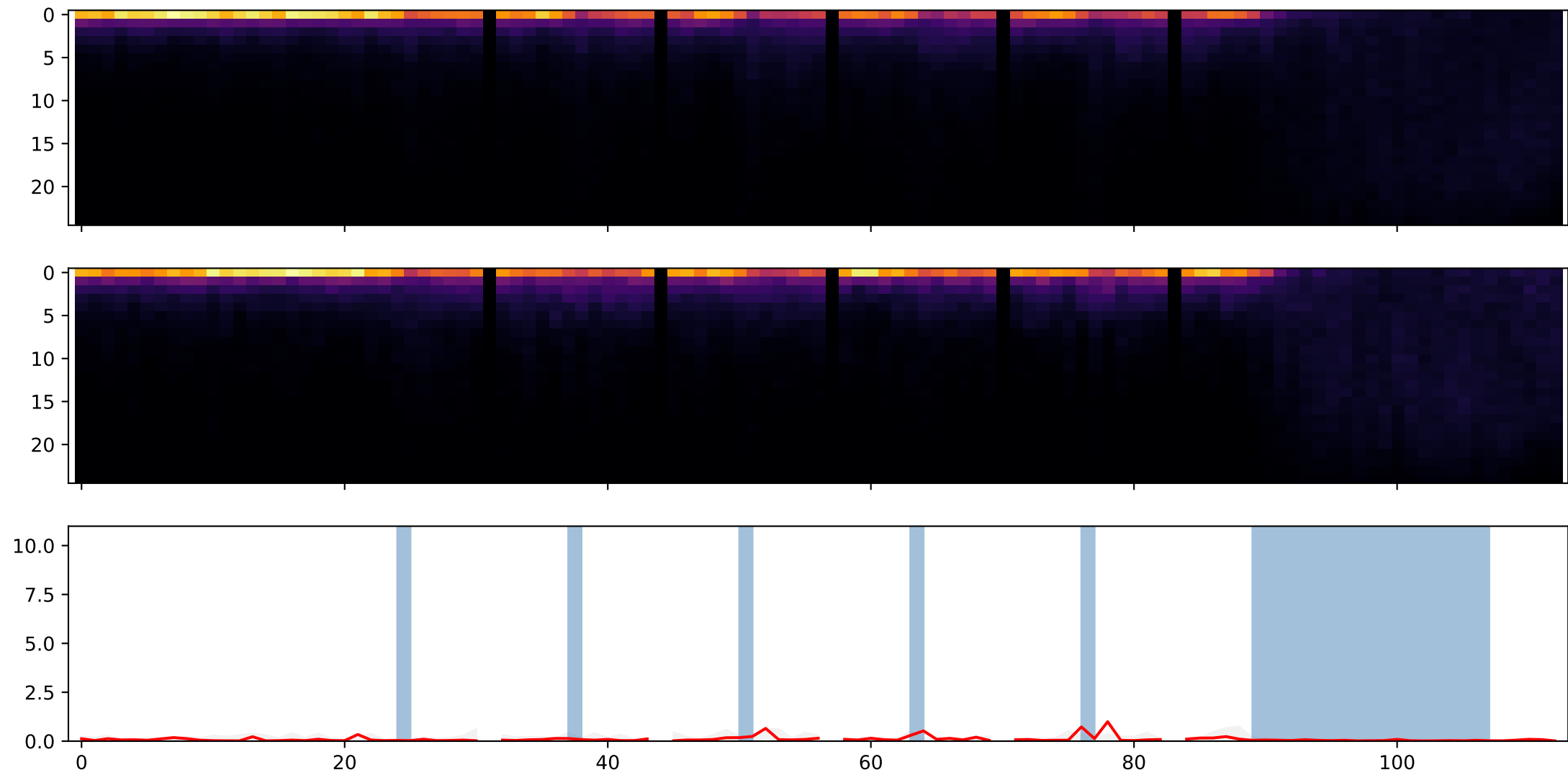
eigen_projection_4



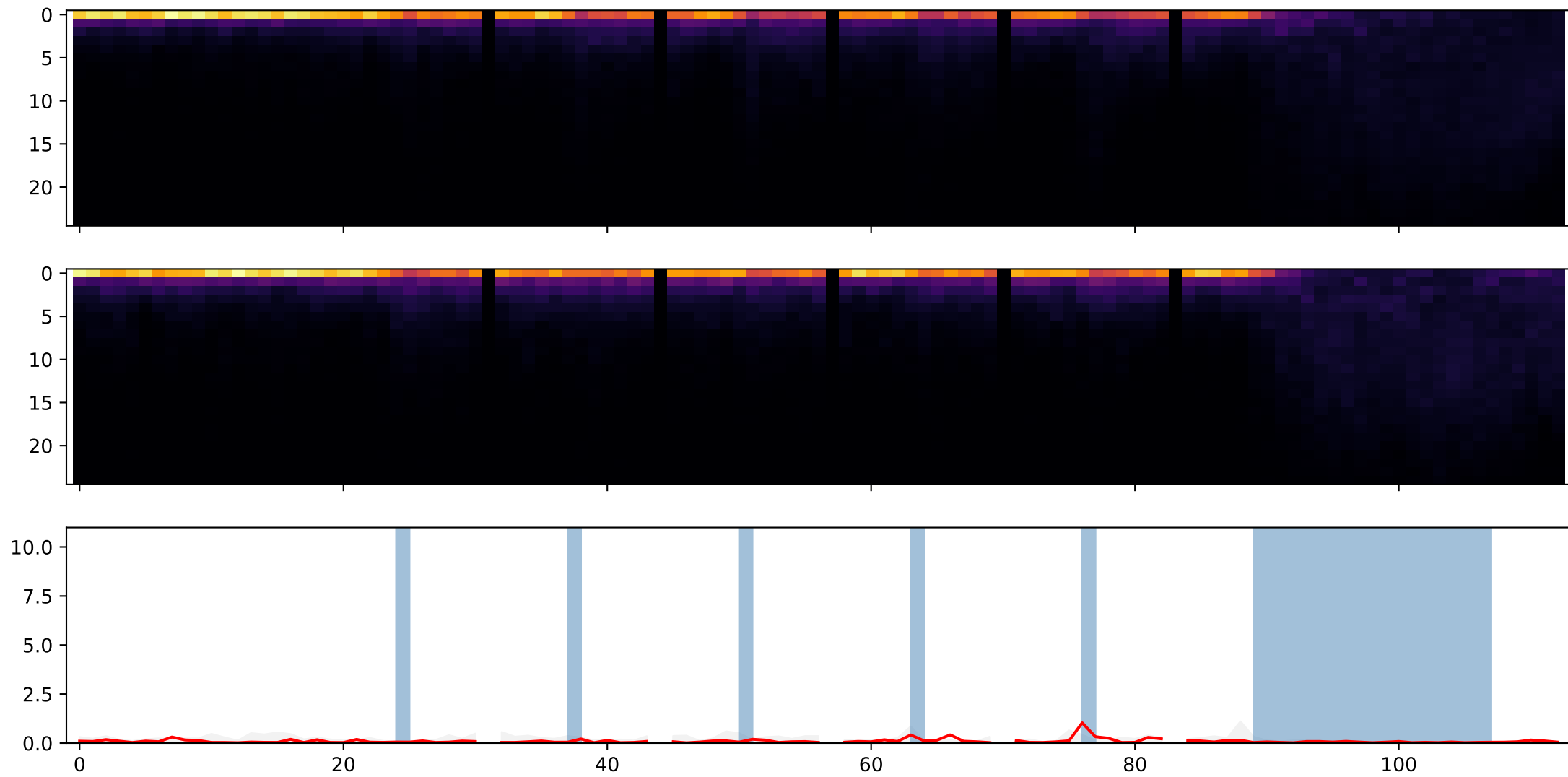
d_relative_to_body_angular_velocity_hips



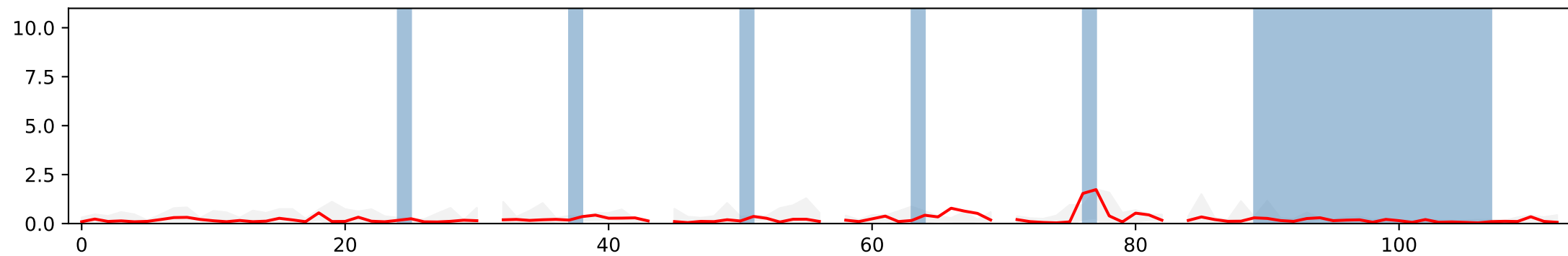
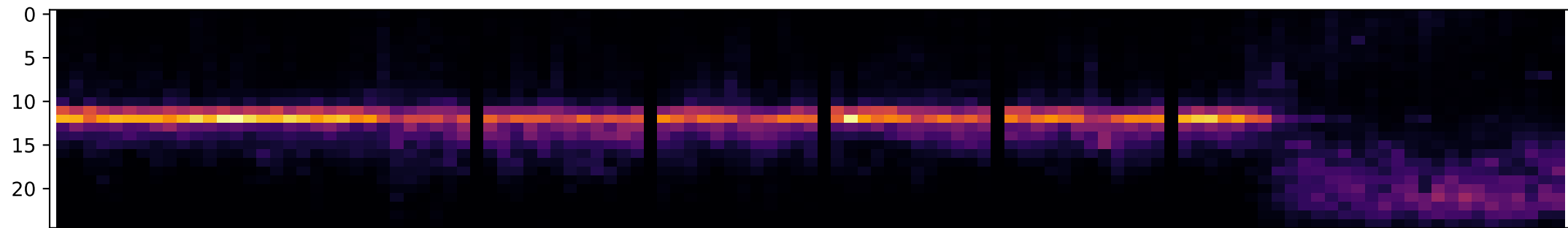
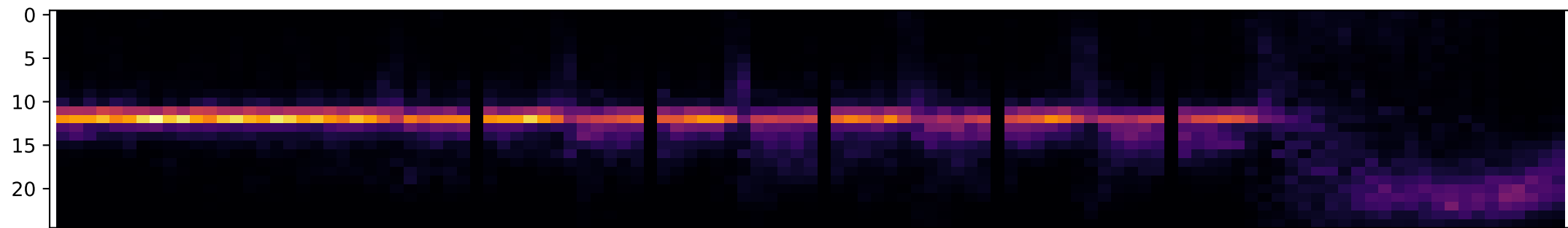
relative_to_hips_angular_velocity_tail_tip



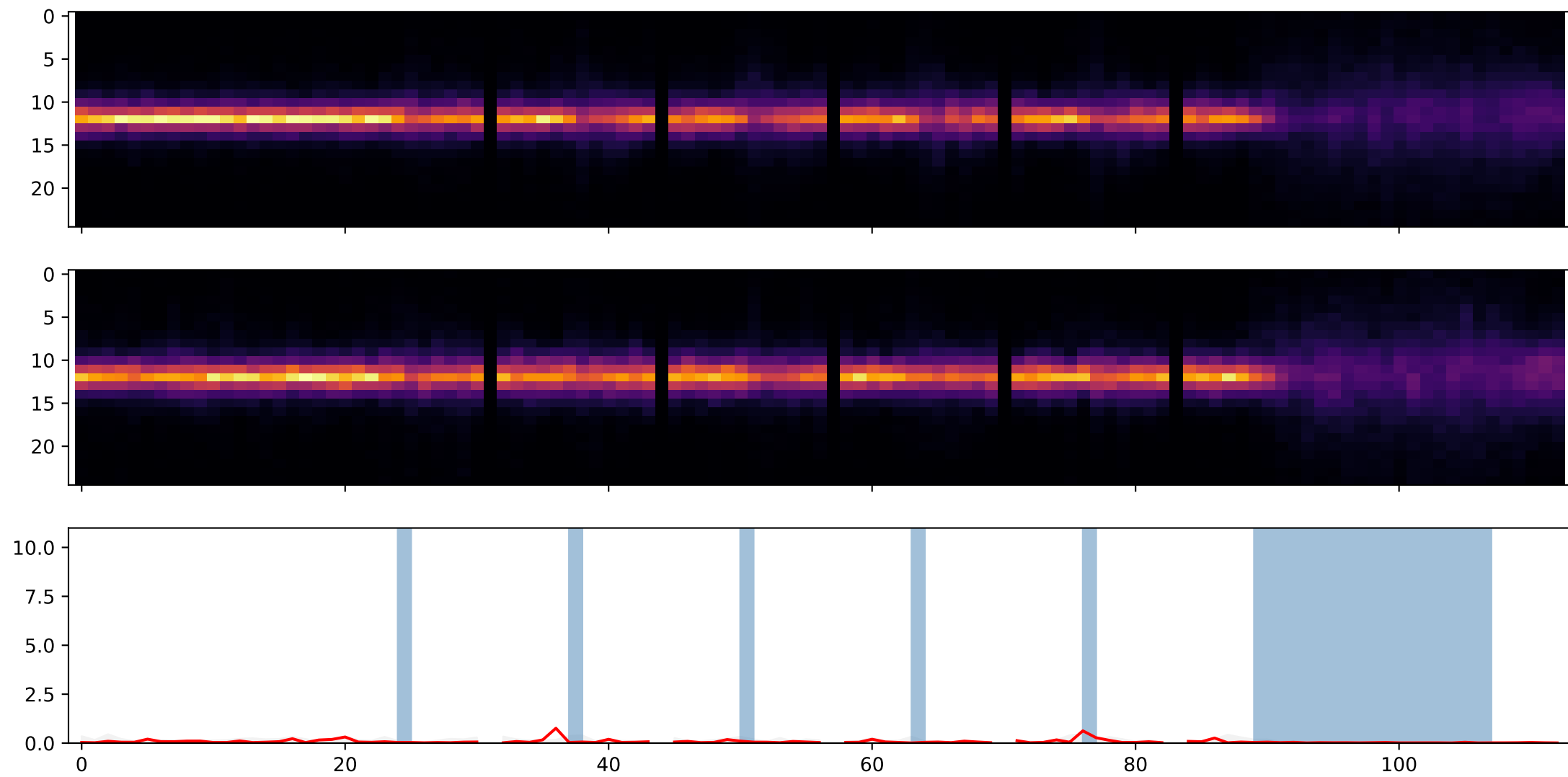
angular_velocity_hips



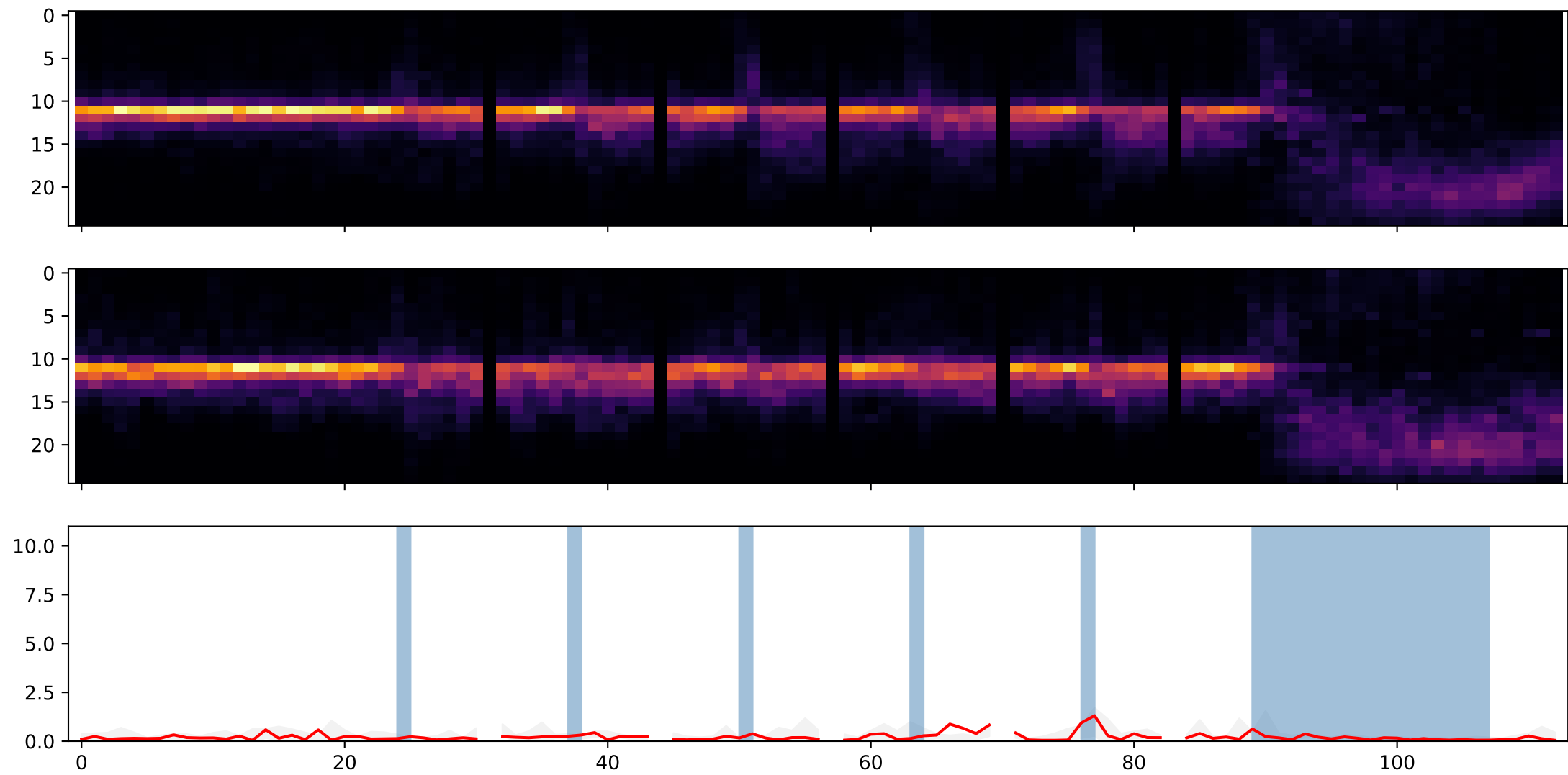
speed_hips



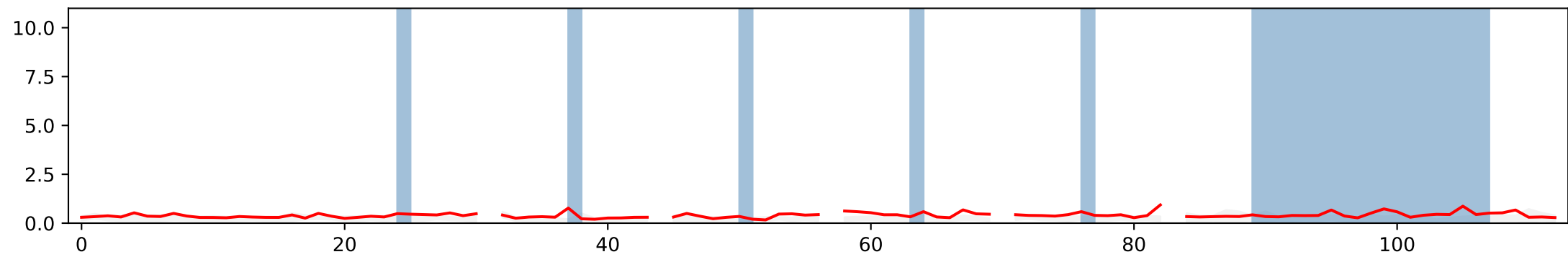
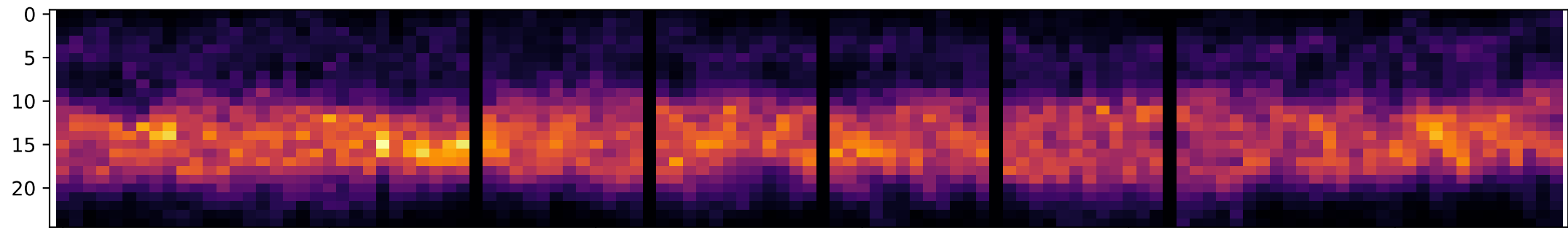
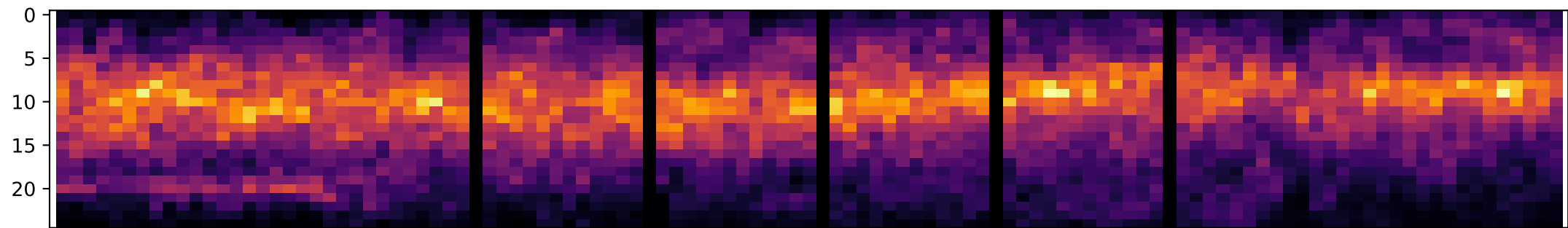
relative_to_body_radial_velocity_hips



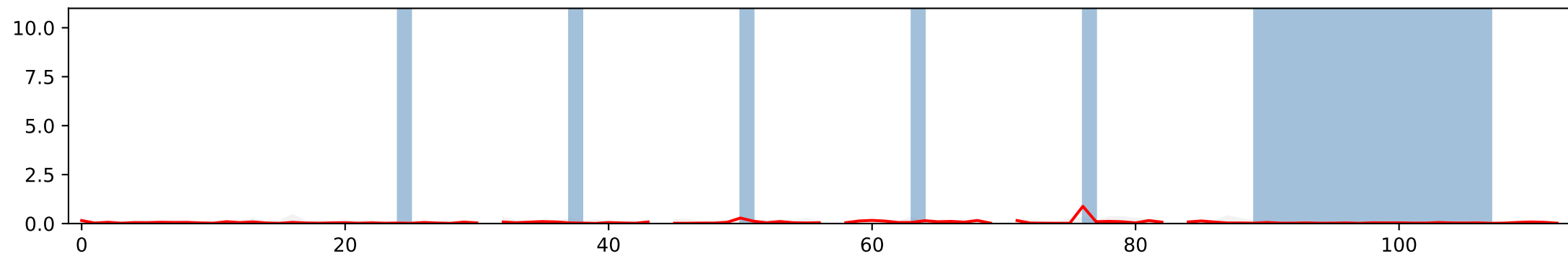
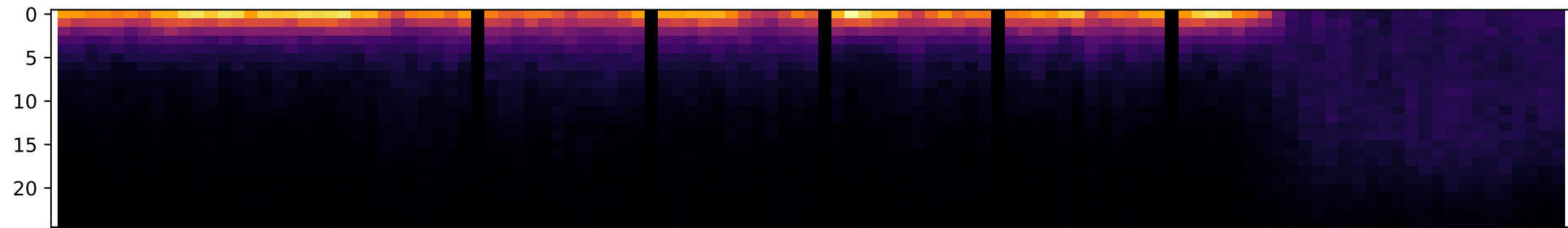
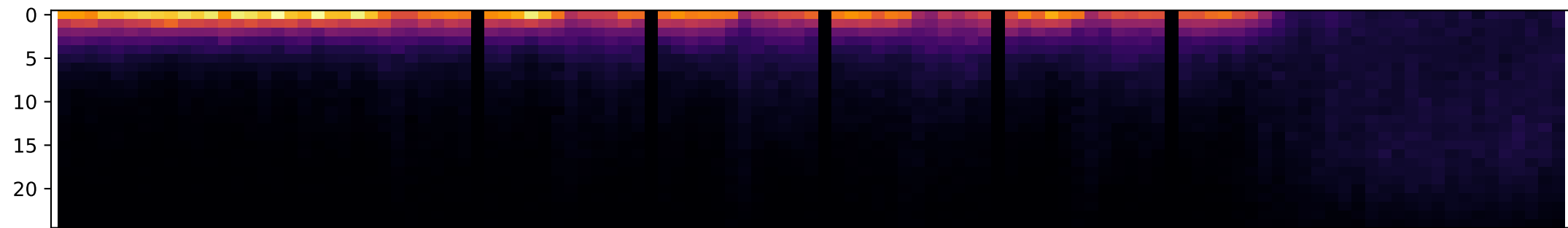
speed_neck



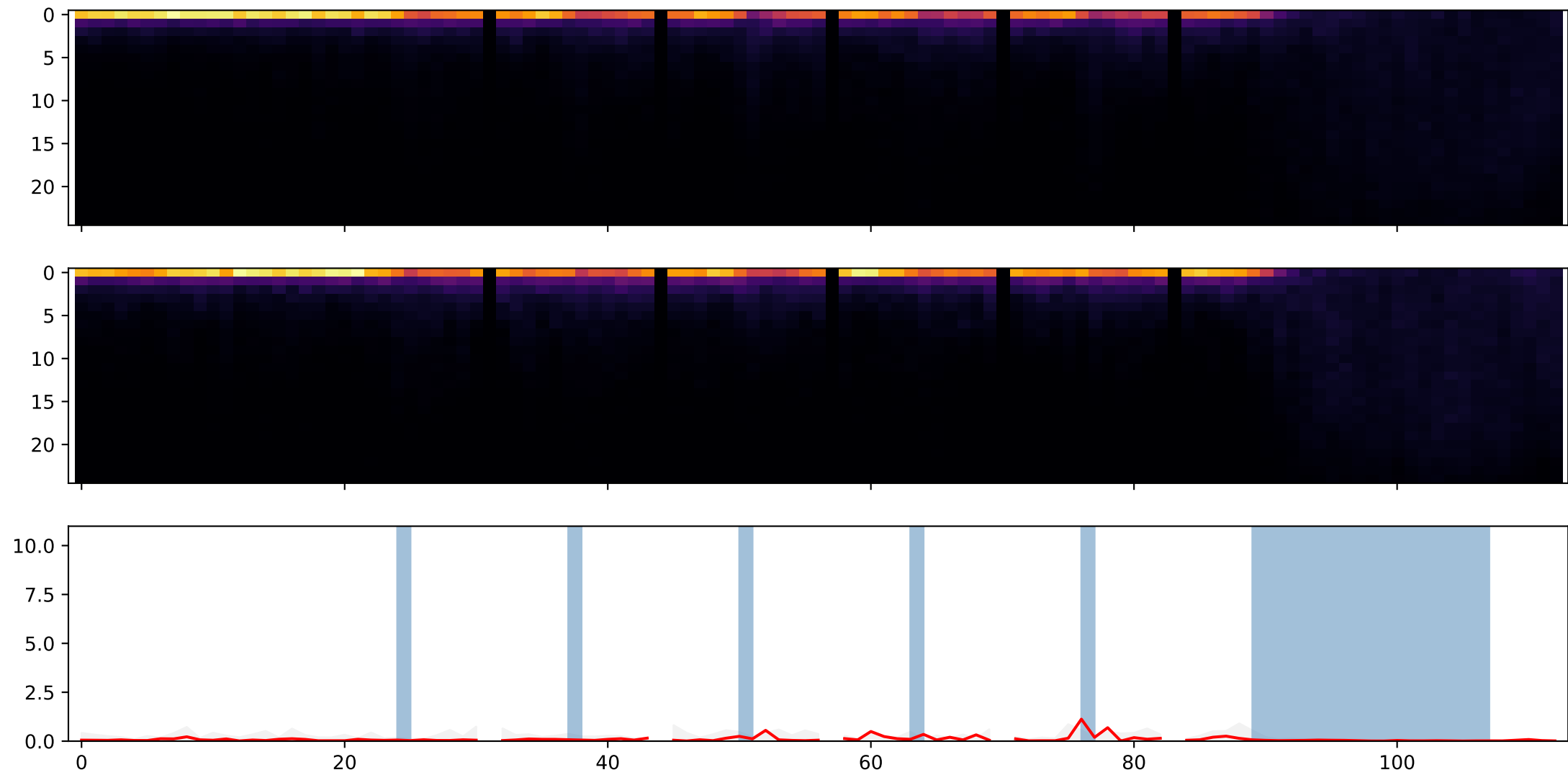
area



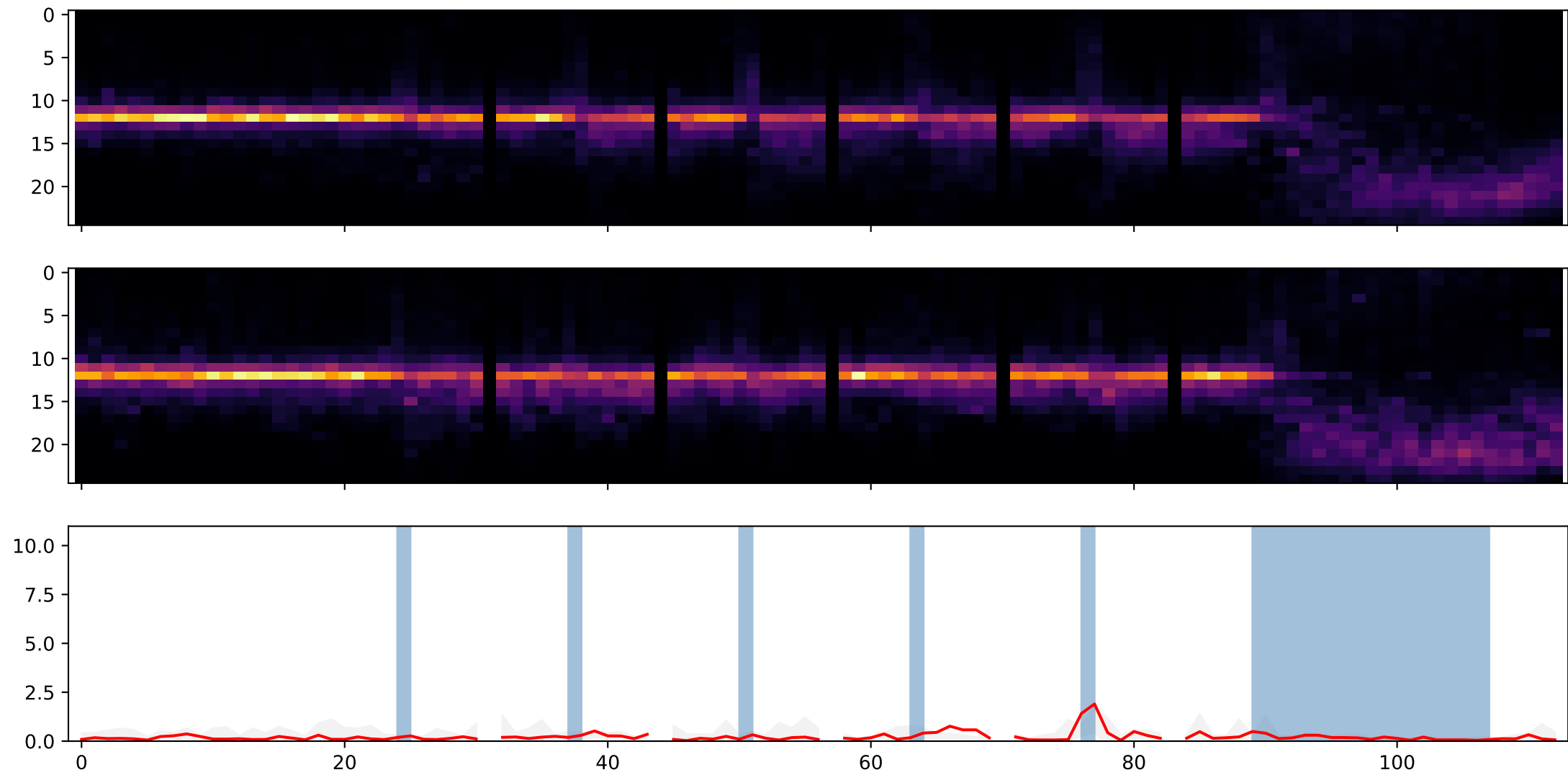
d_curvature_midbody



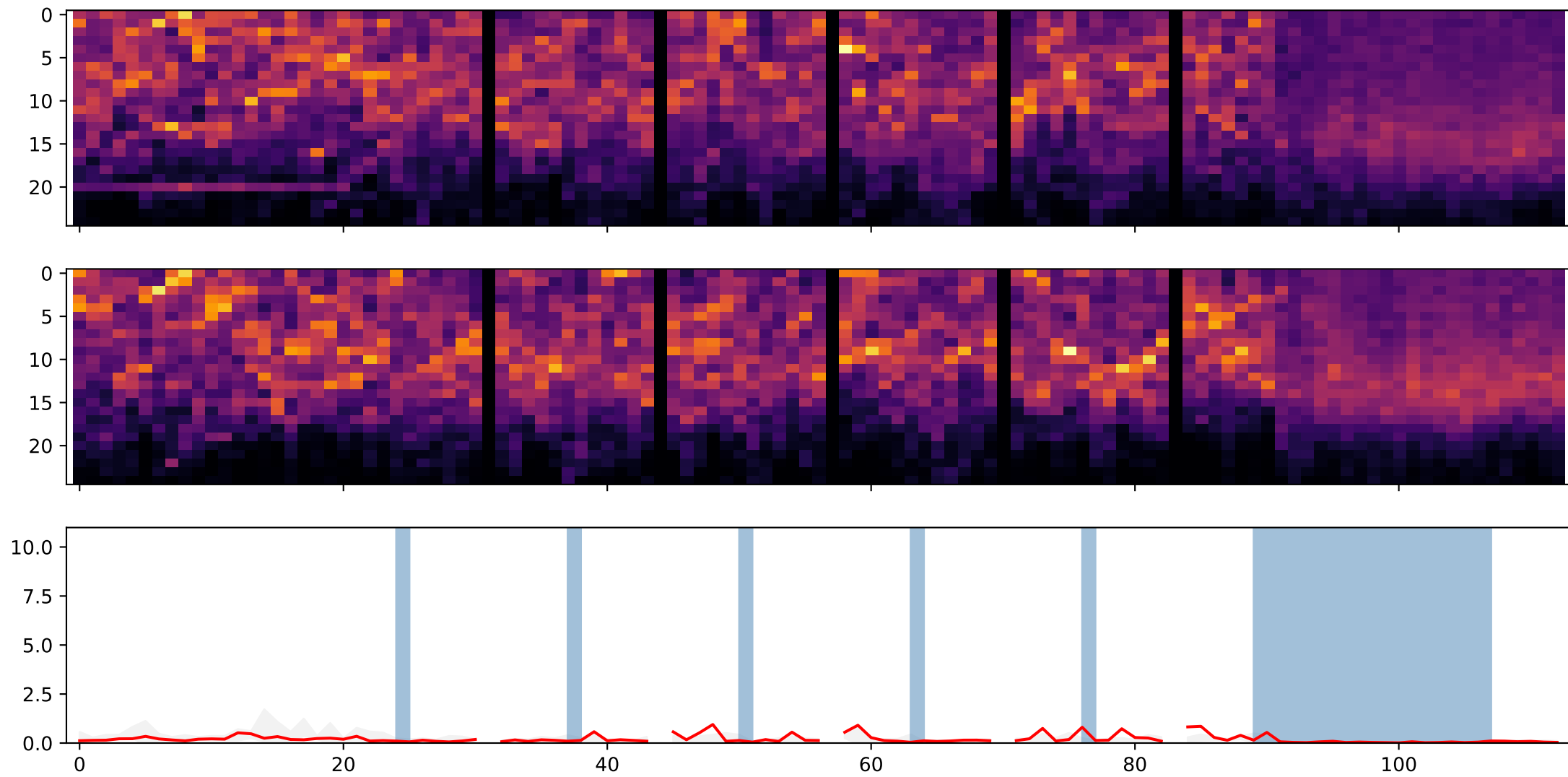
relative_to_body_speed_midbody



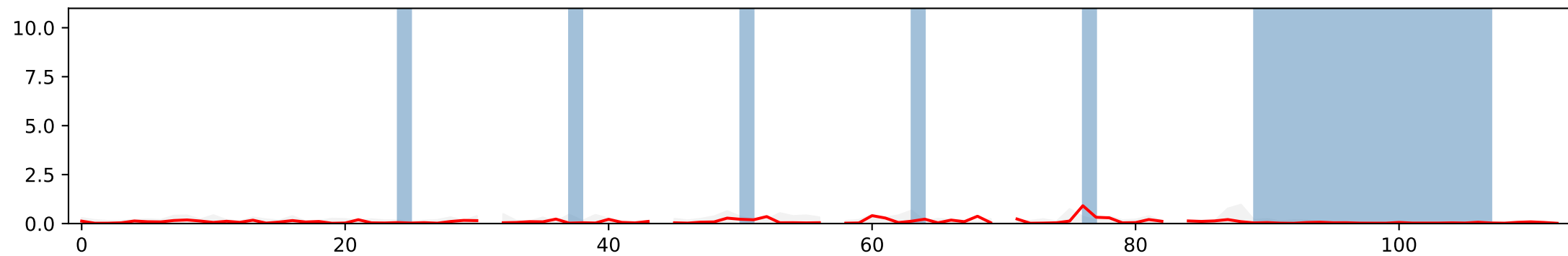
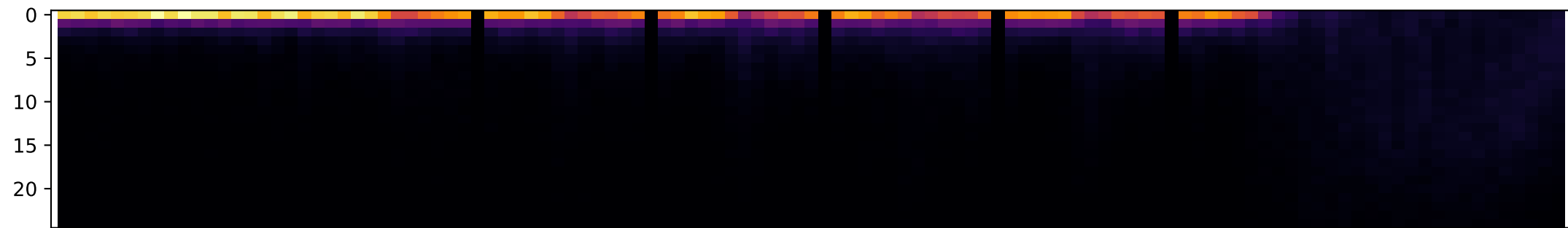
speed_tail_tip



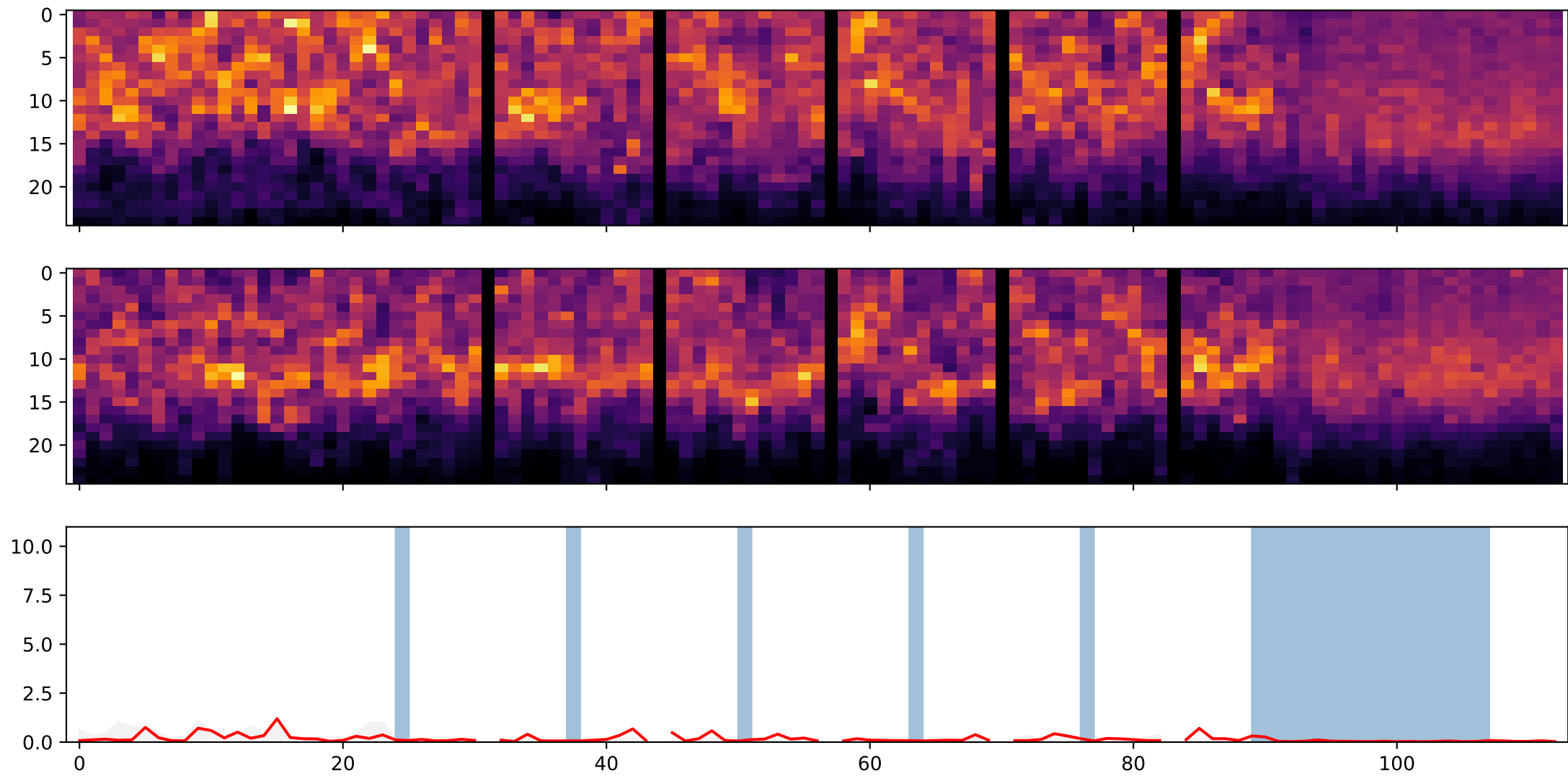
curvature_mean_neck



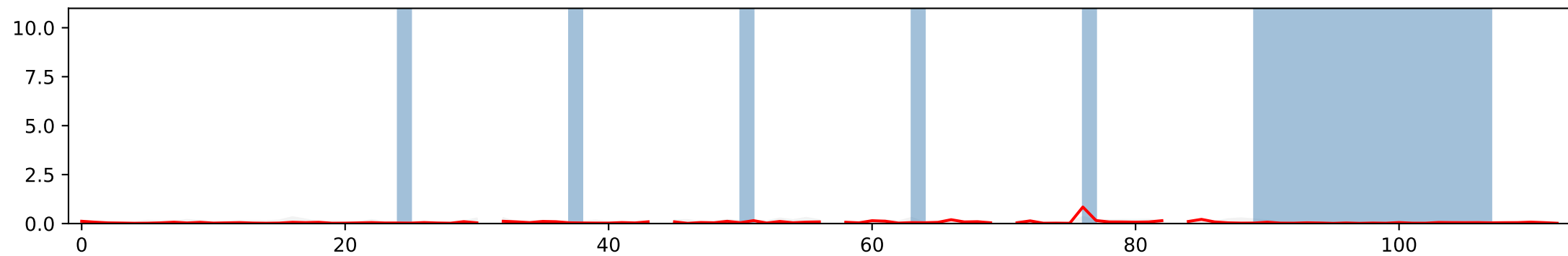
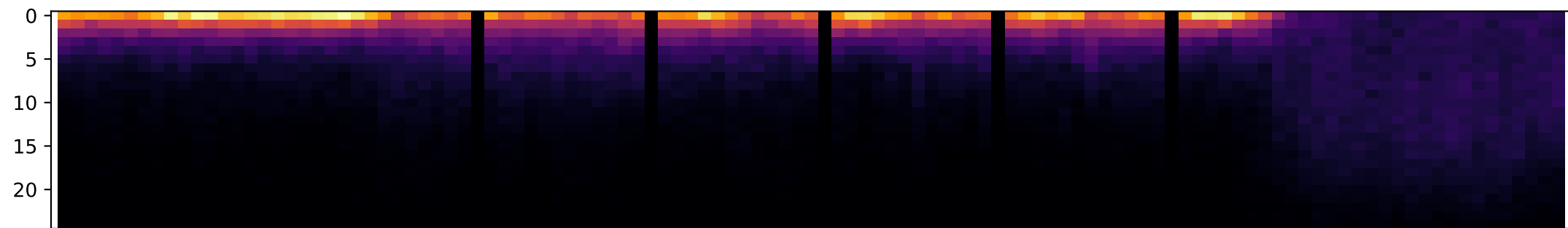
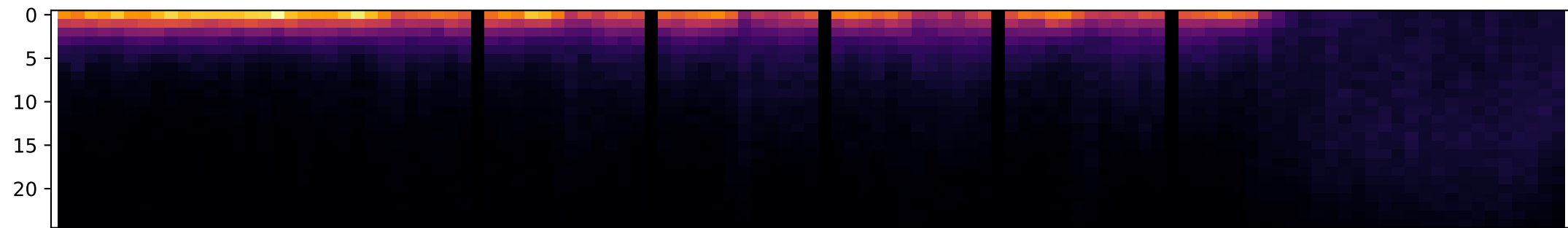
d_relative_to_body_speed_midbody



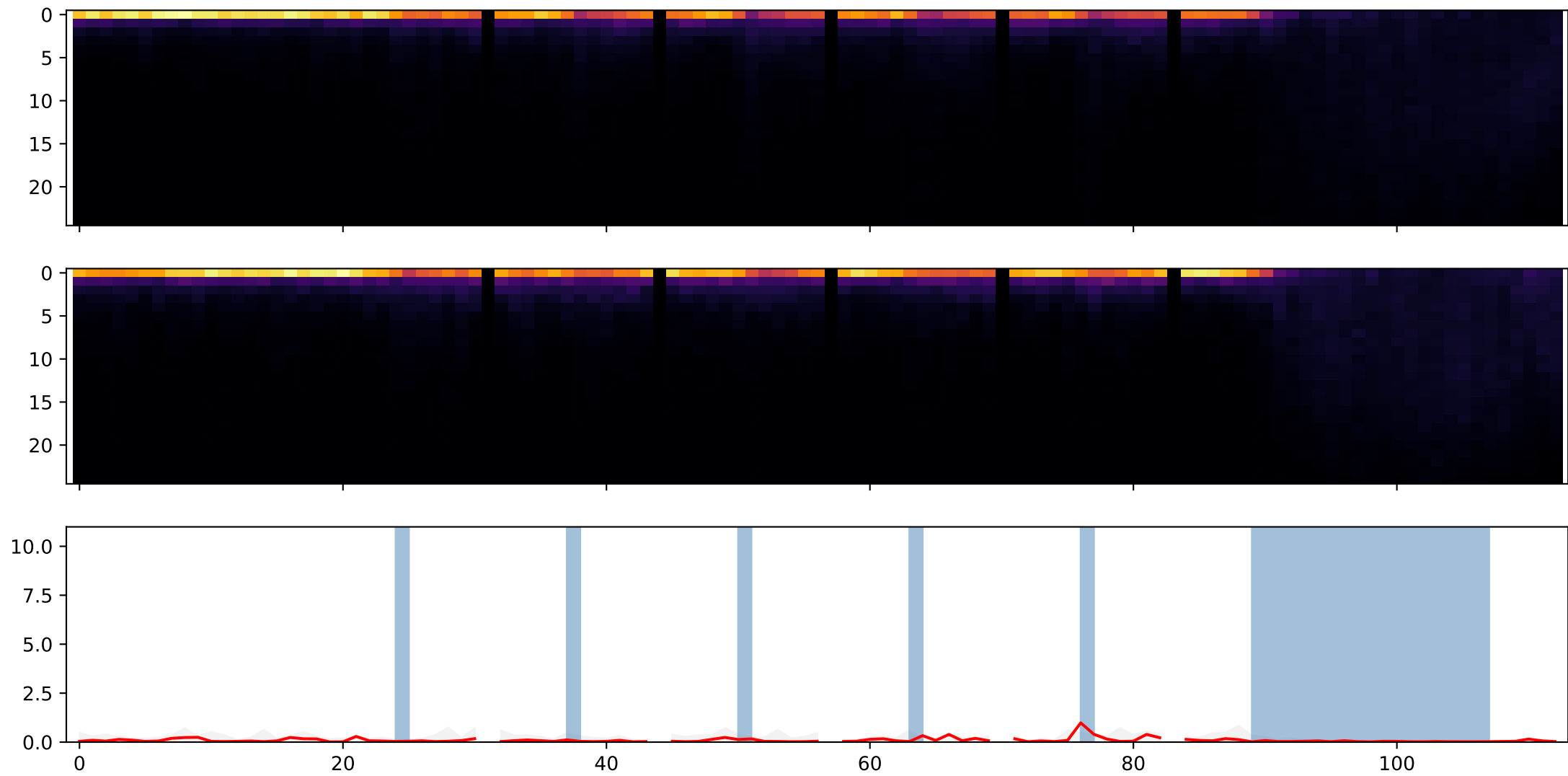
curvature_neck



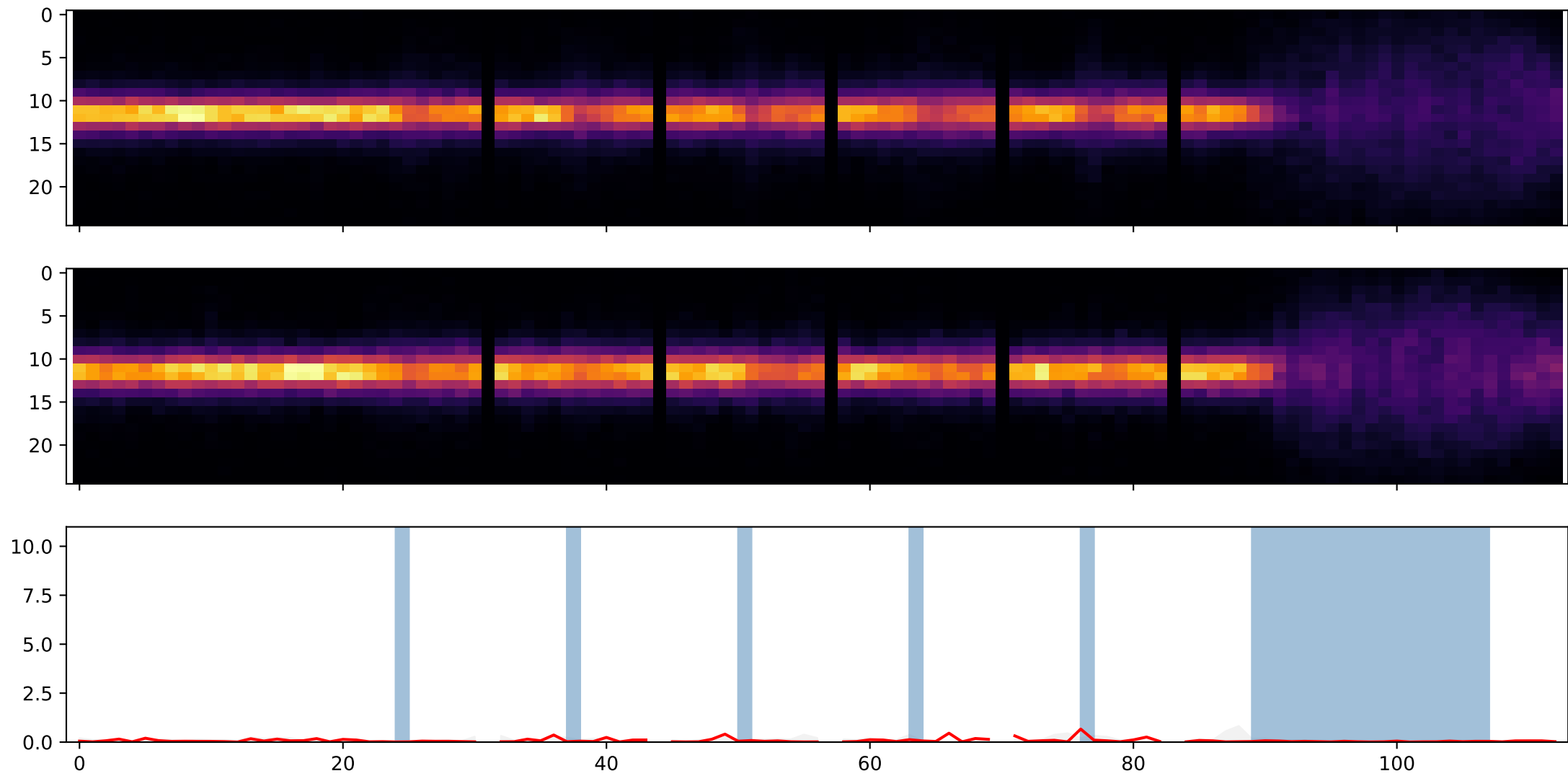
d_curvature_neck



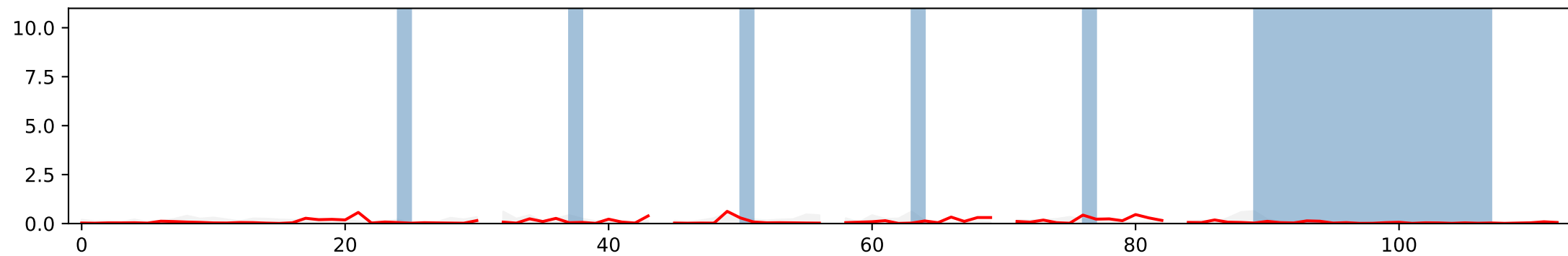
d_eigen_projection_2



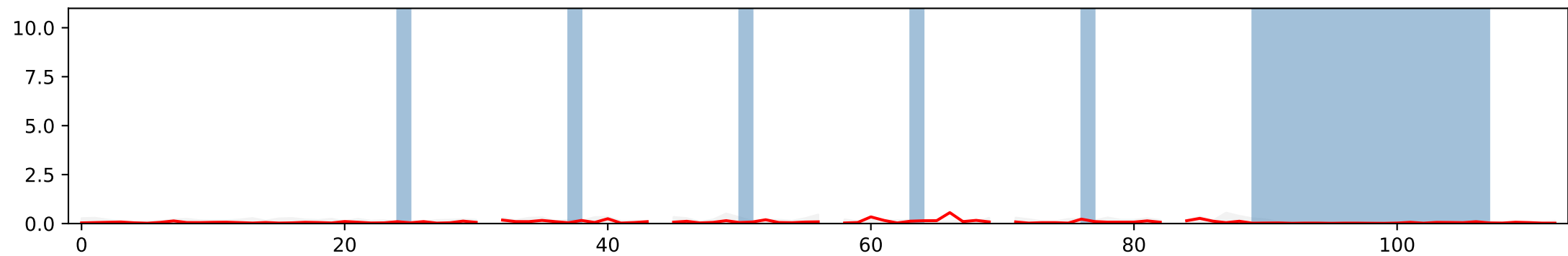
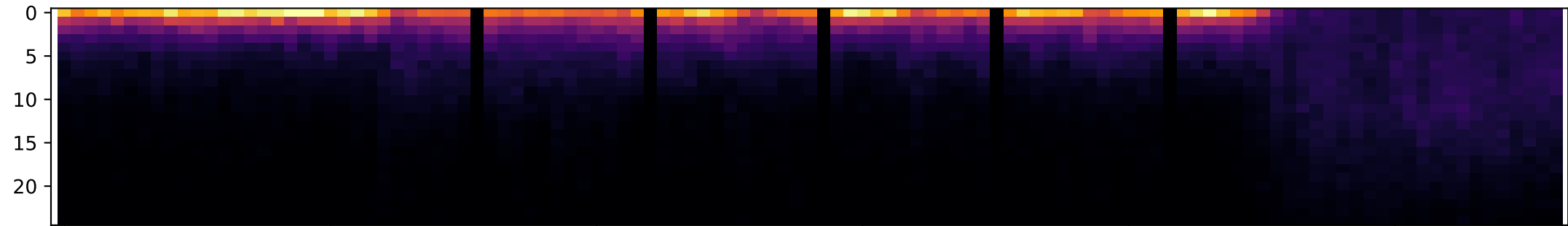
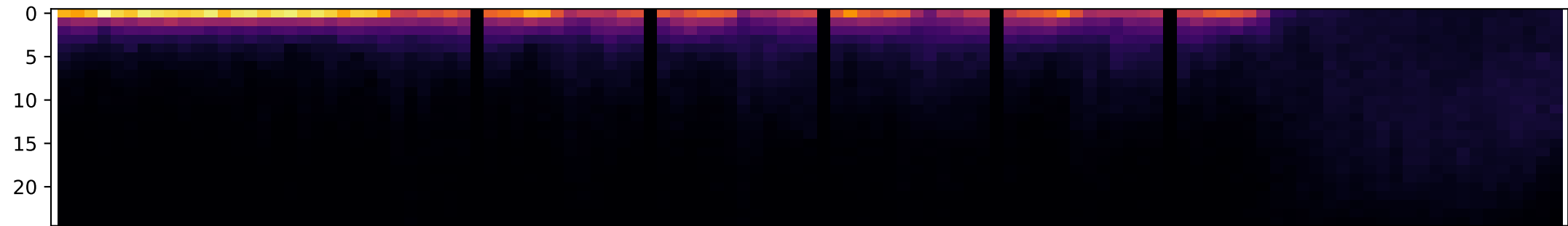
d_relative_to_hips_radial_velocity_tail_tip



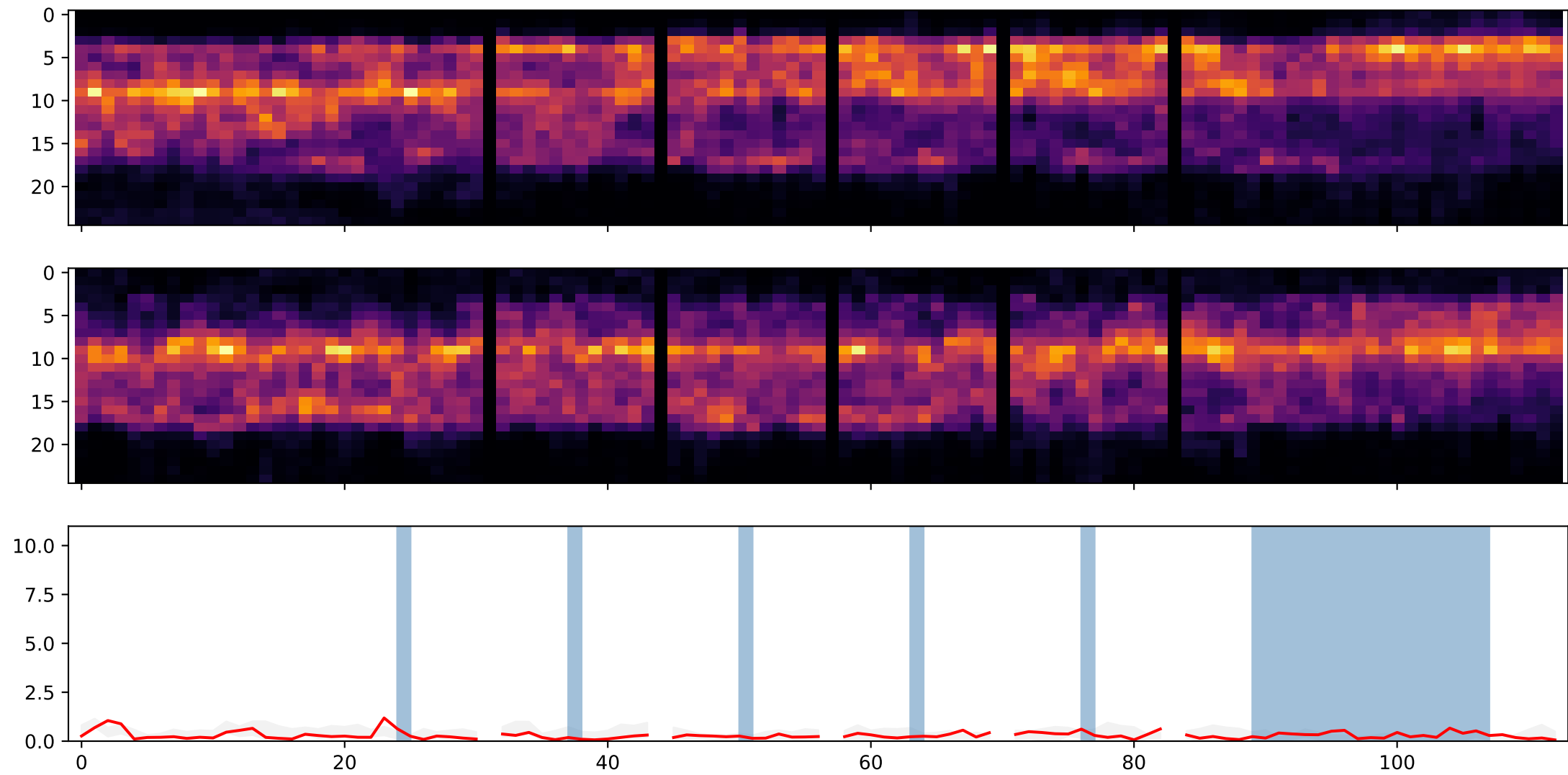
d_relative_to_body_angular_velocity_tail_tip



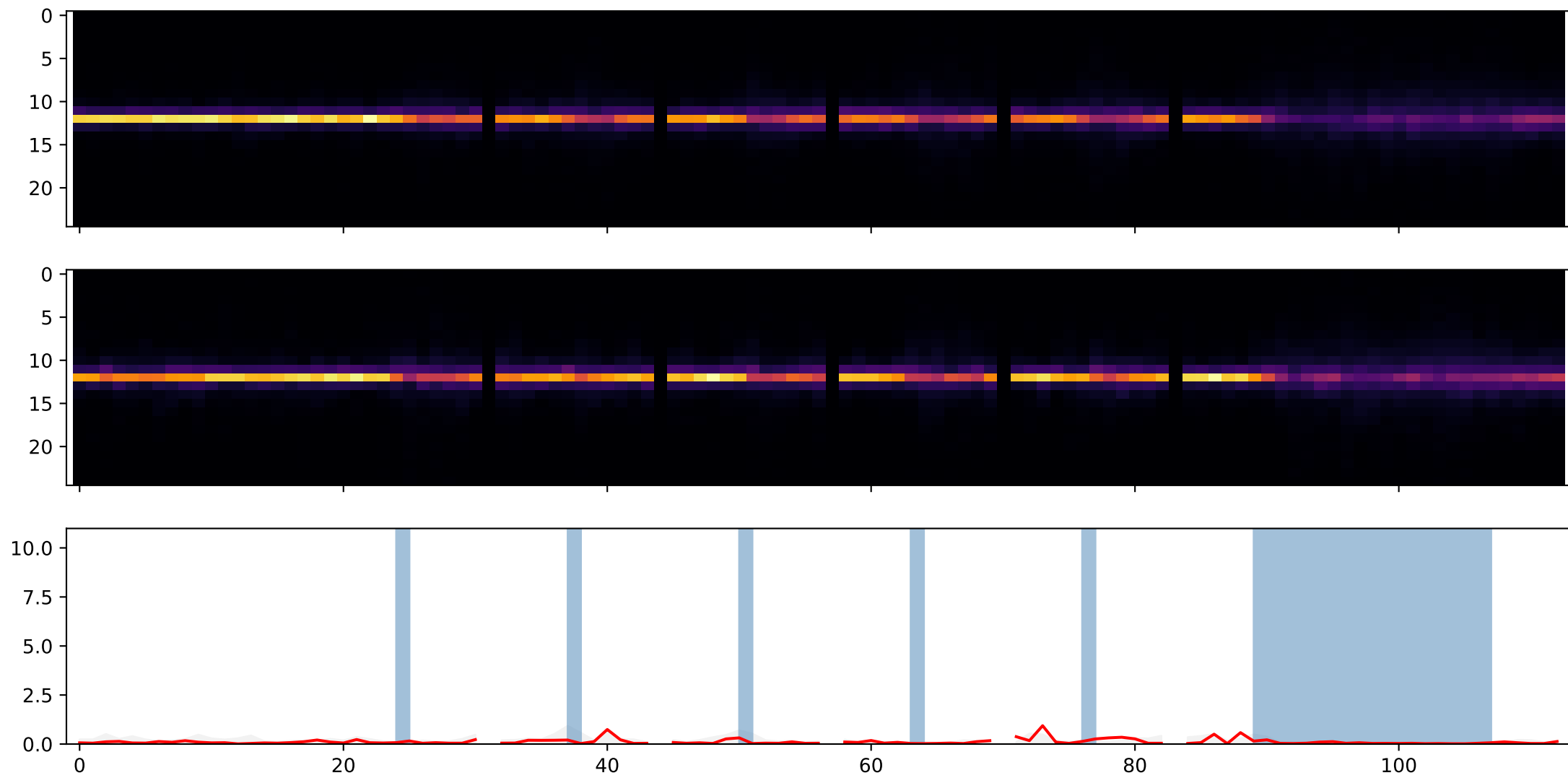
d_eigen_projection_1



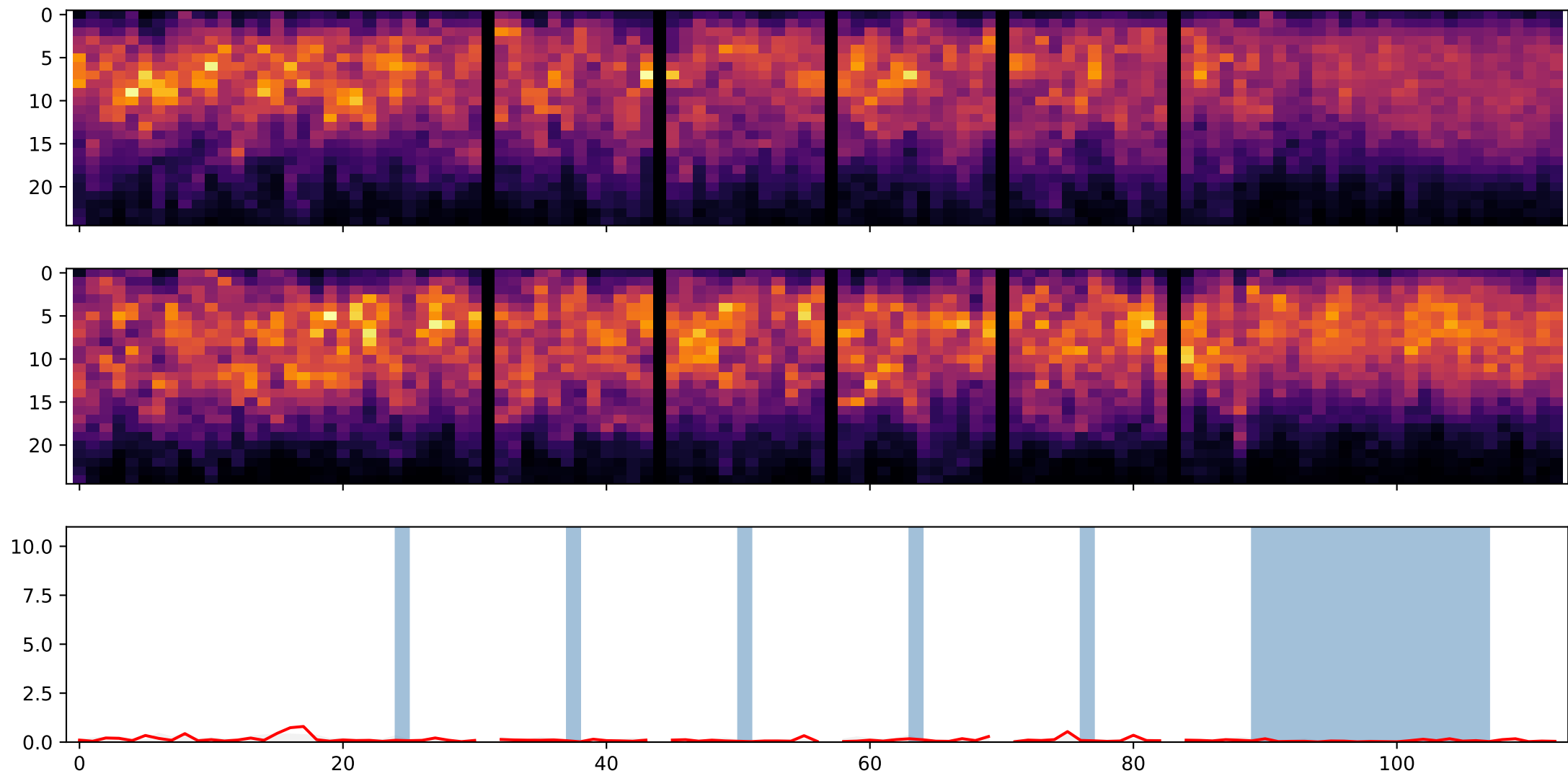
width_midbody



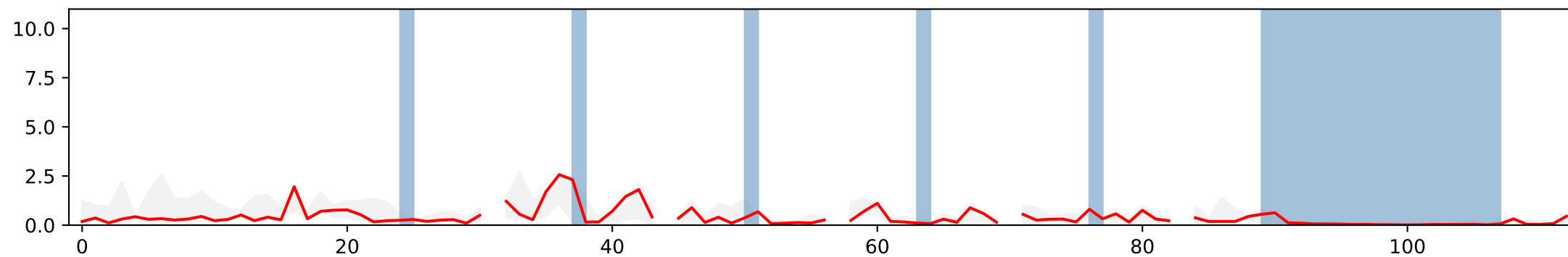
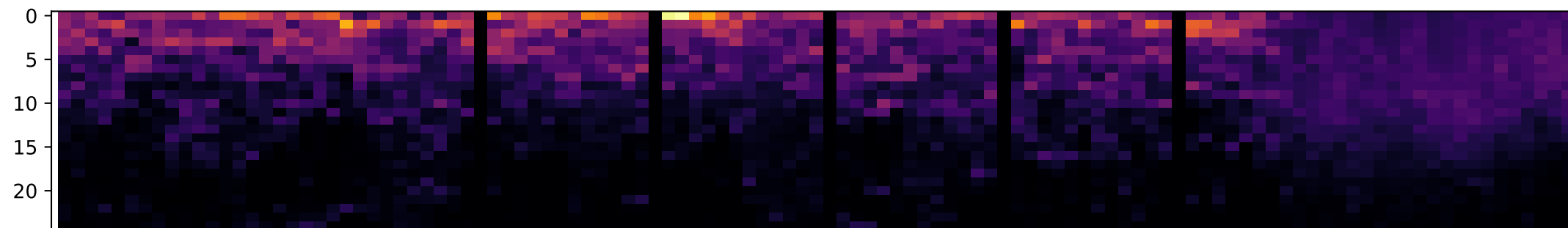
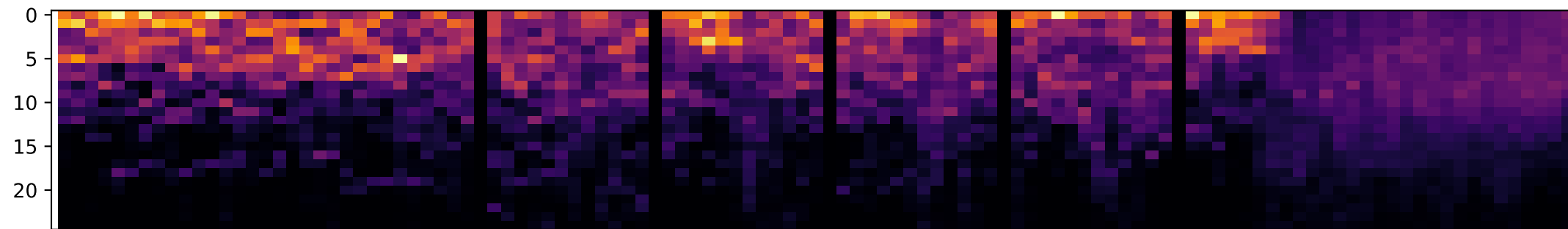
d_quirkiness



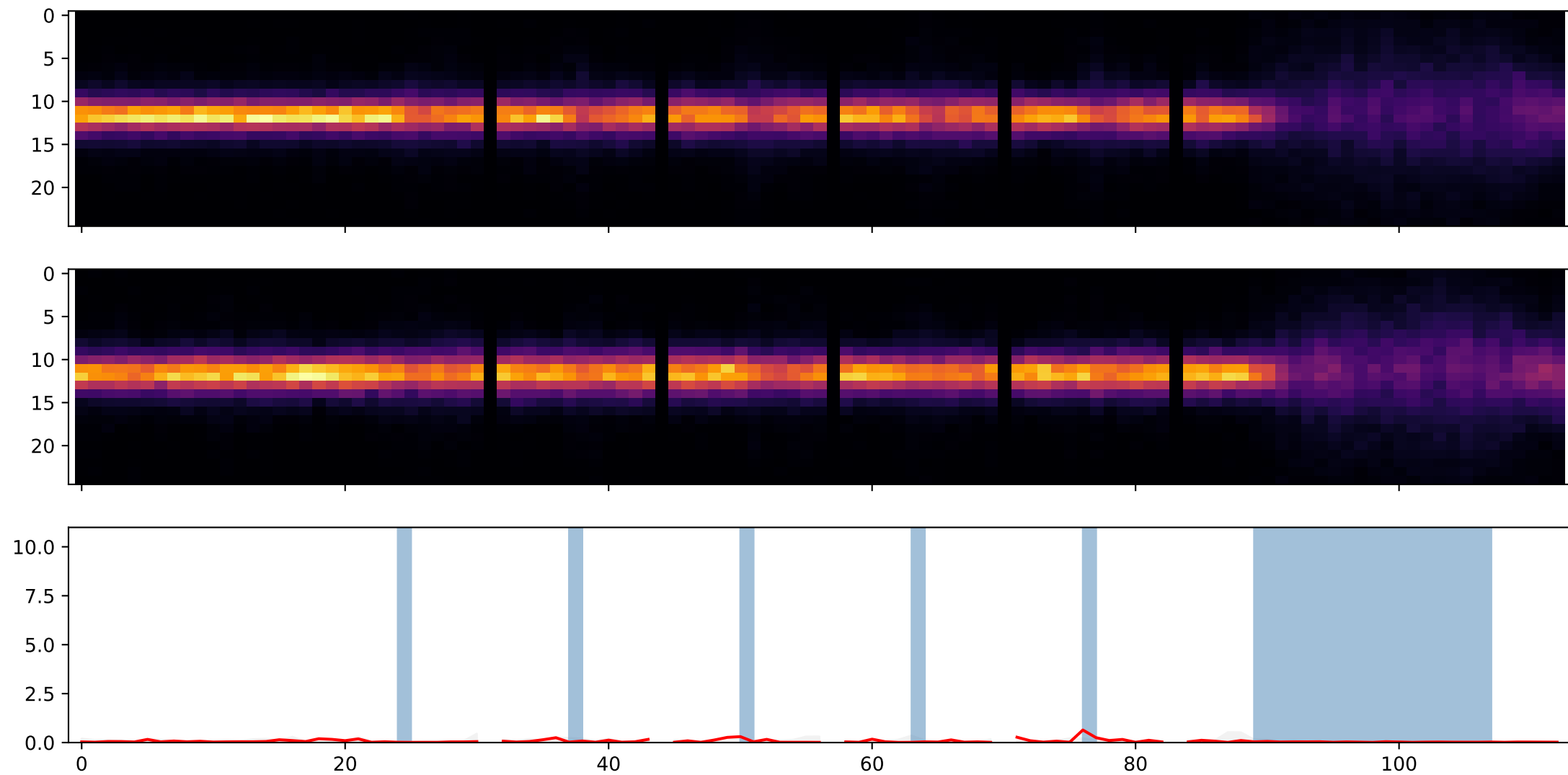
curvature_std_neck



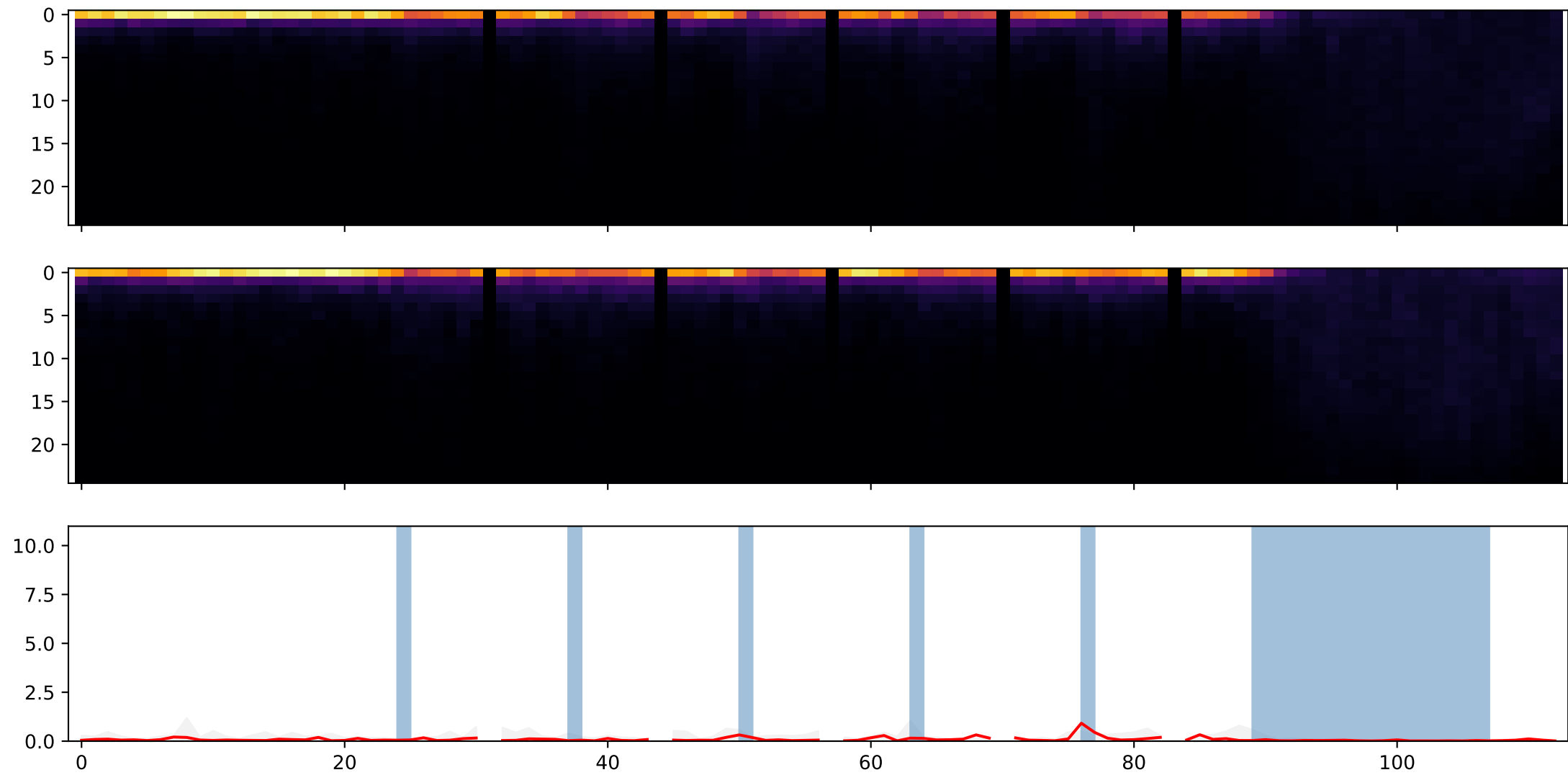
eigen_projection_2



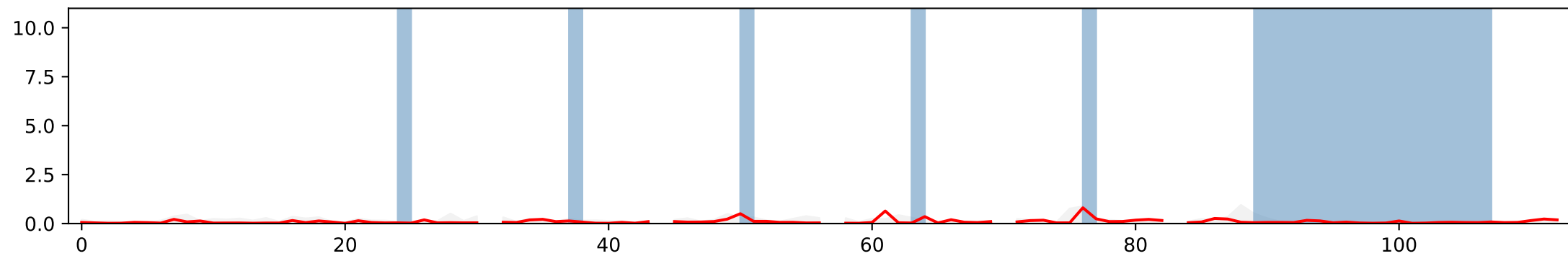
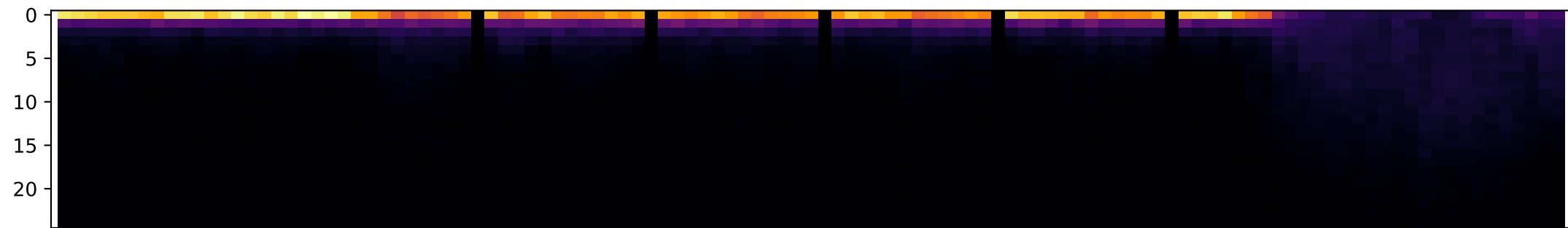
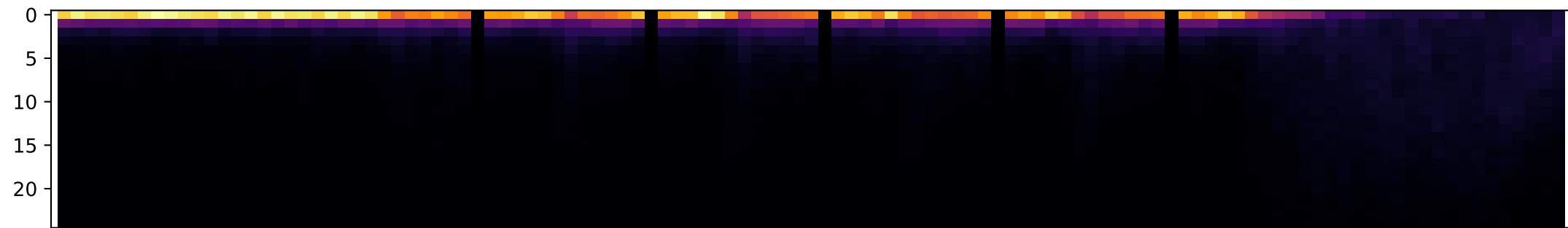
d_relative_to_body_radial_velocity_hips



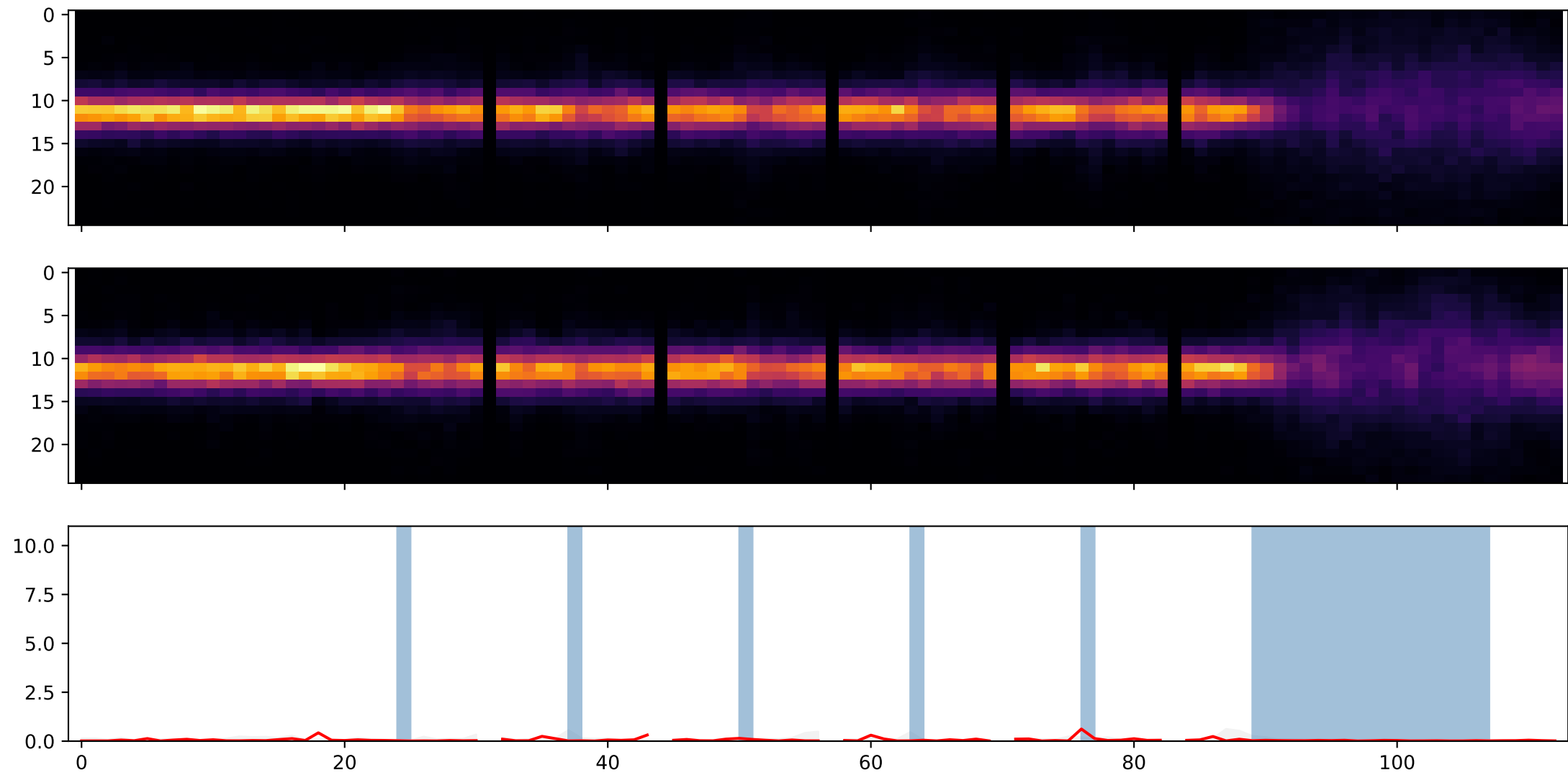
relative_to_body_angular_velocity_neck



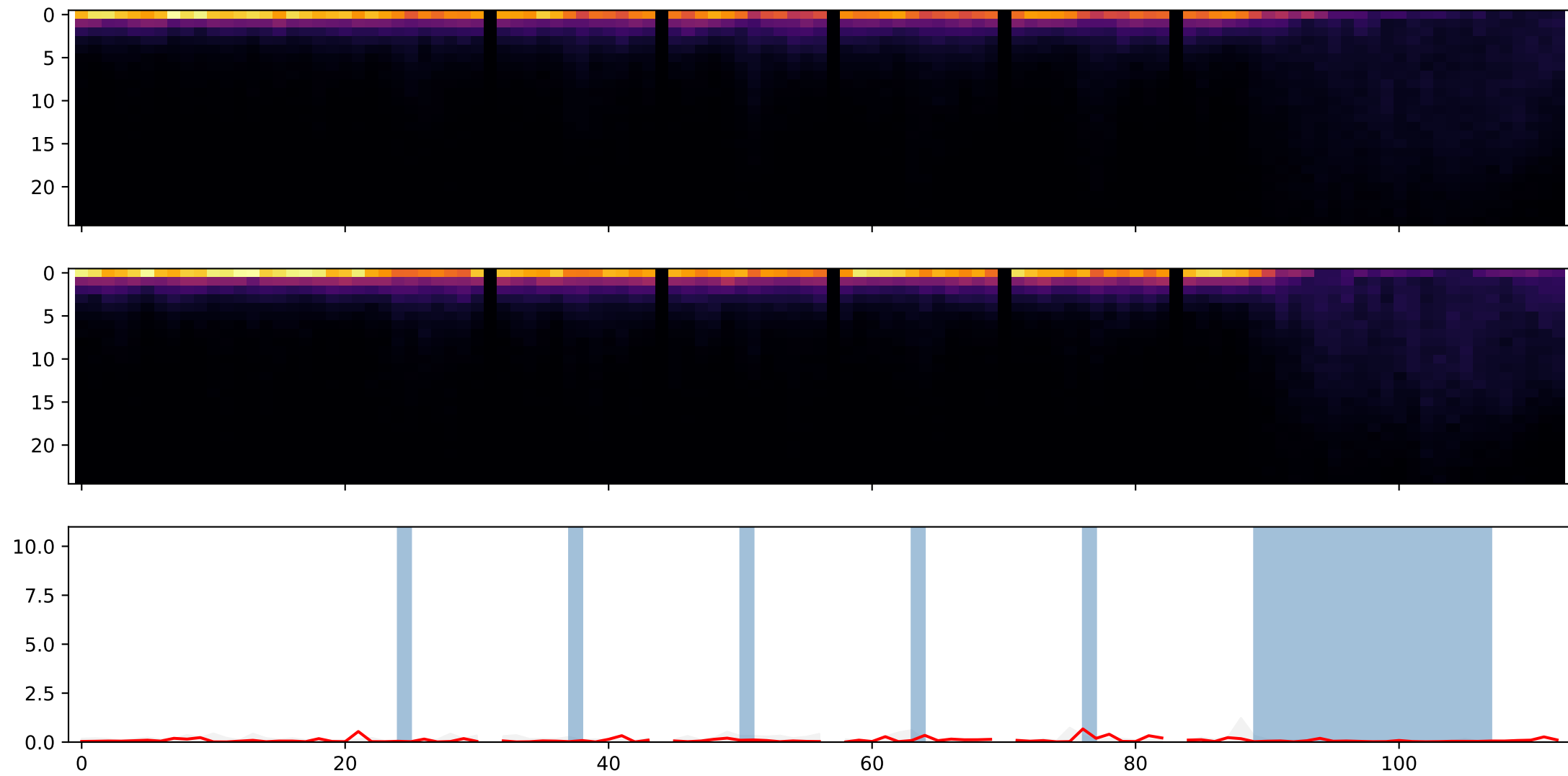
d_angular_velocity_midbody



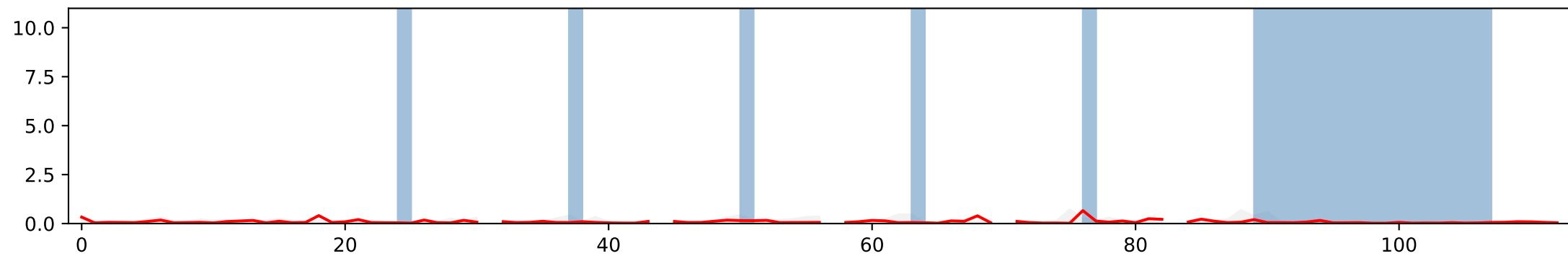
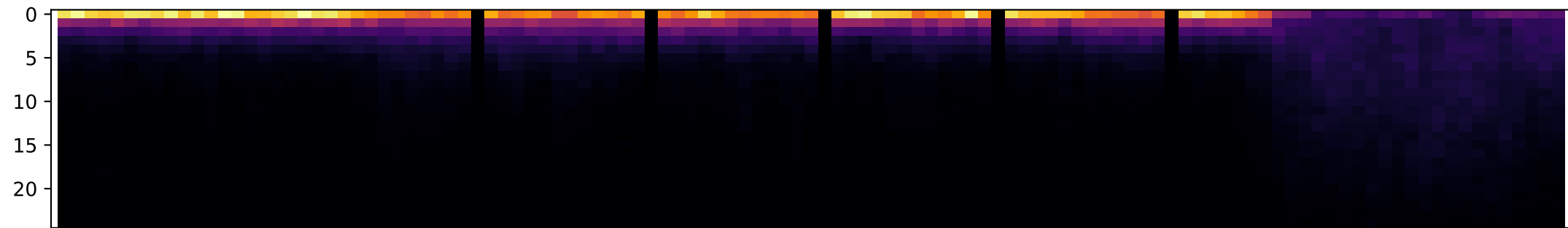
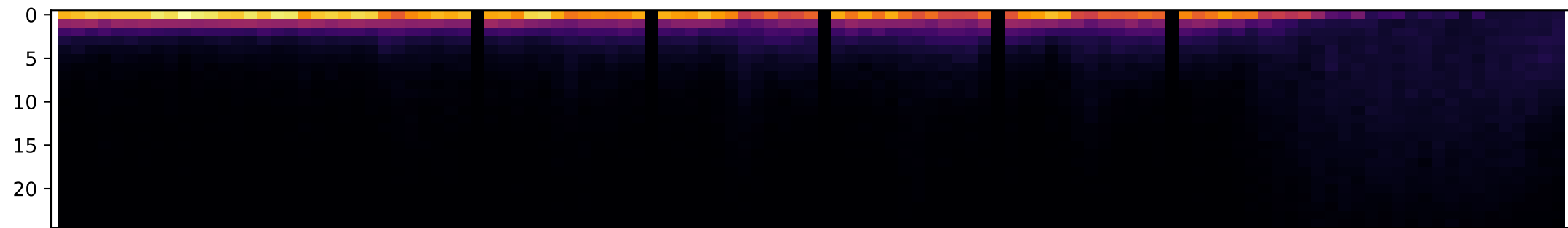
d_relative_to_body_radial_velocity_neck



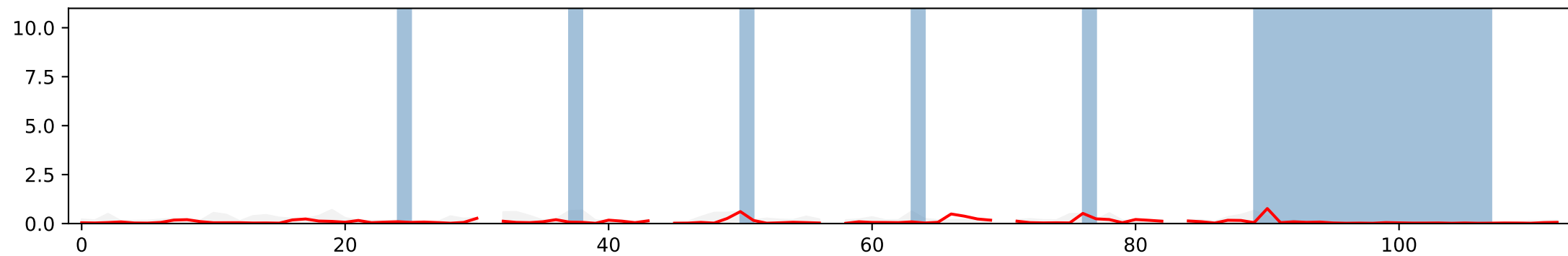
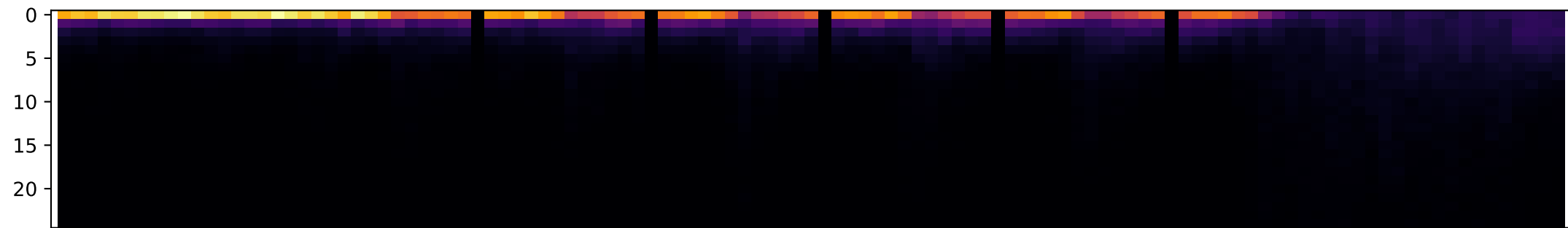
d_angular_velocity_hips



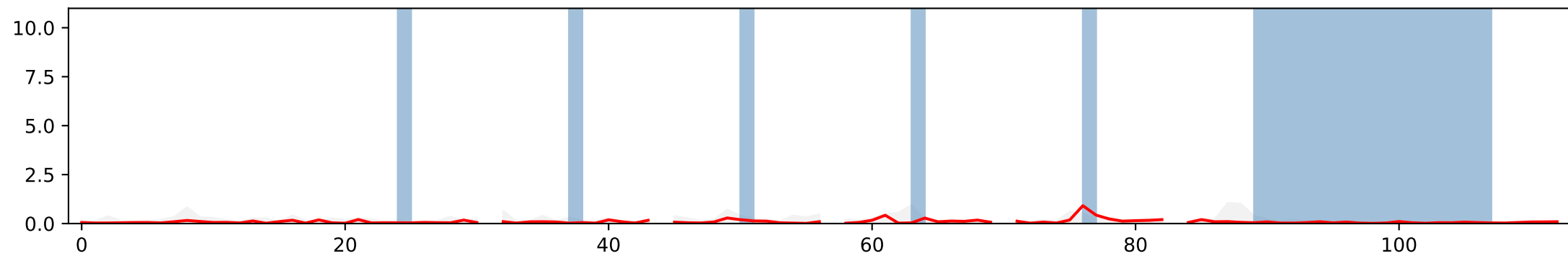
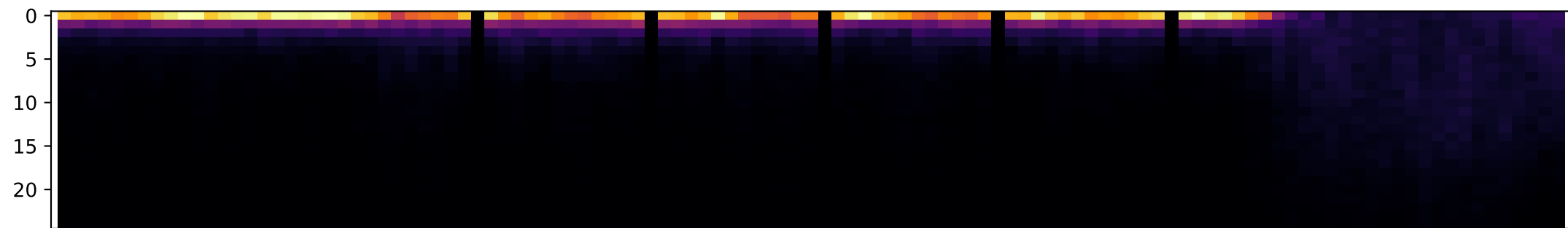
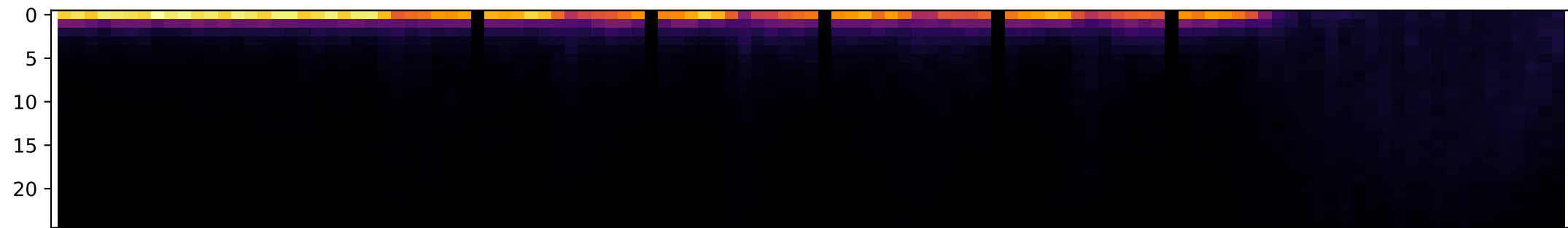
d_angular_velocity_neck



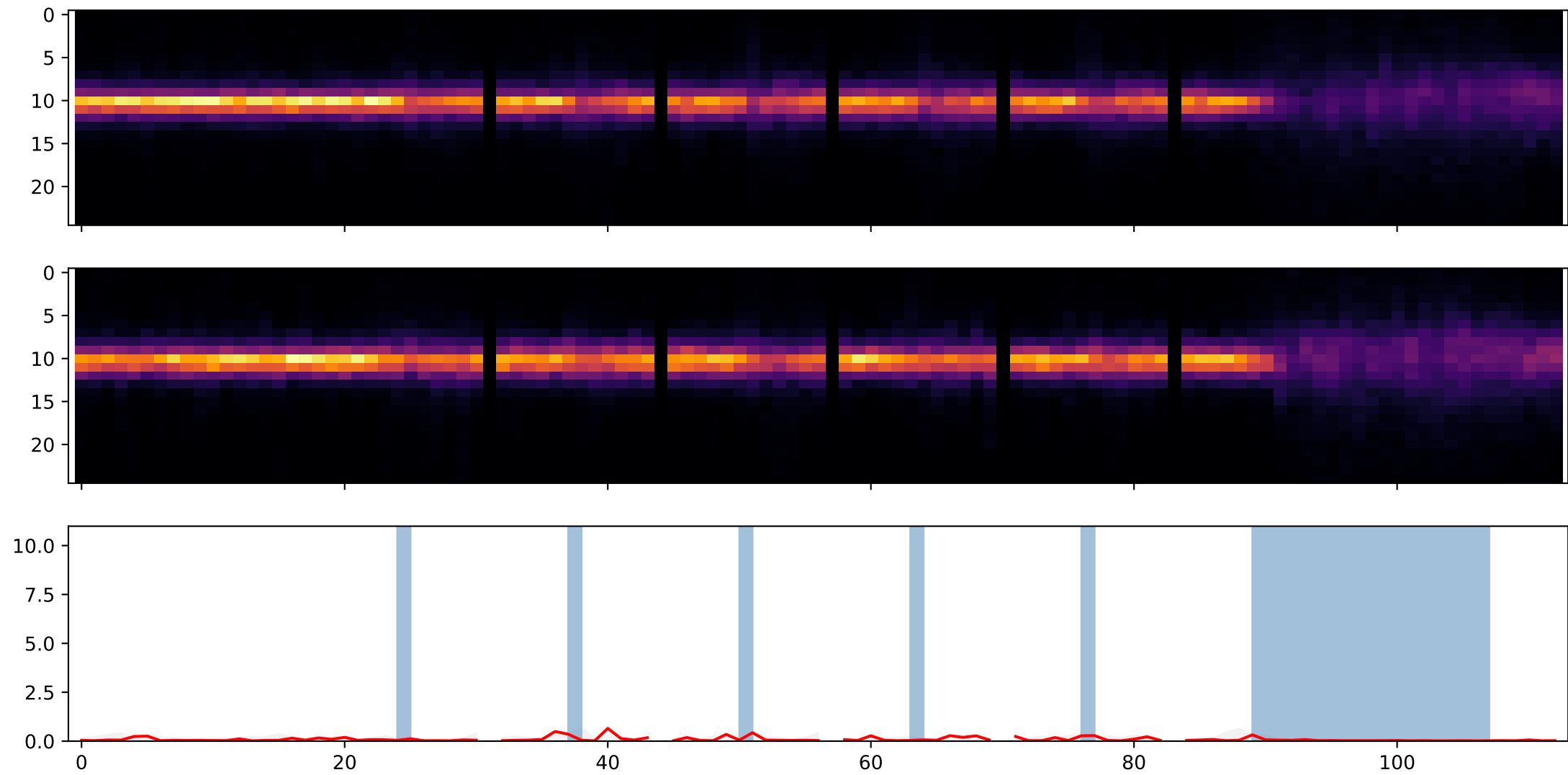
relative_to_body_angular_velocity_tail_tip



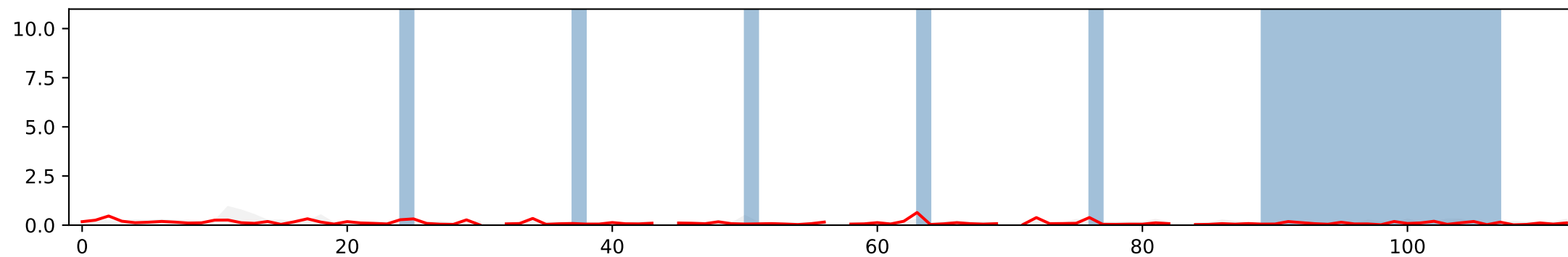
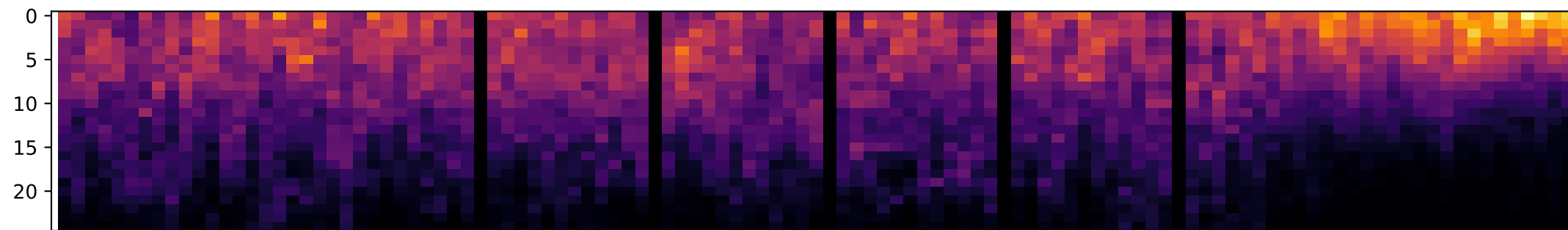
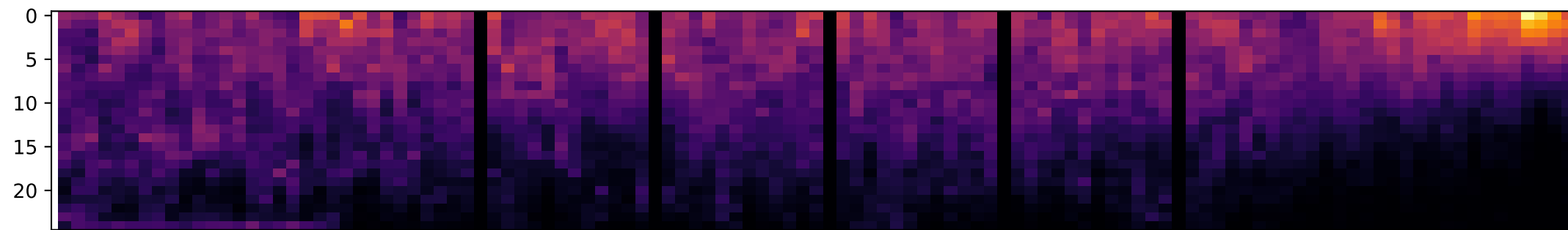
d_relative_to_body_angular_velocity_neck



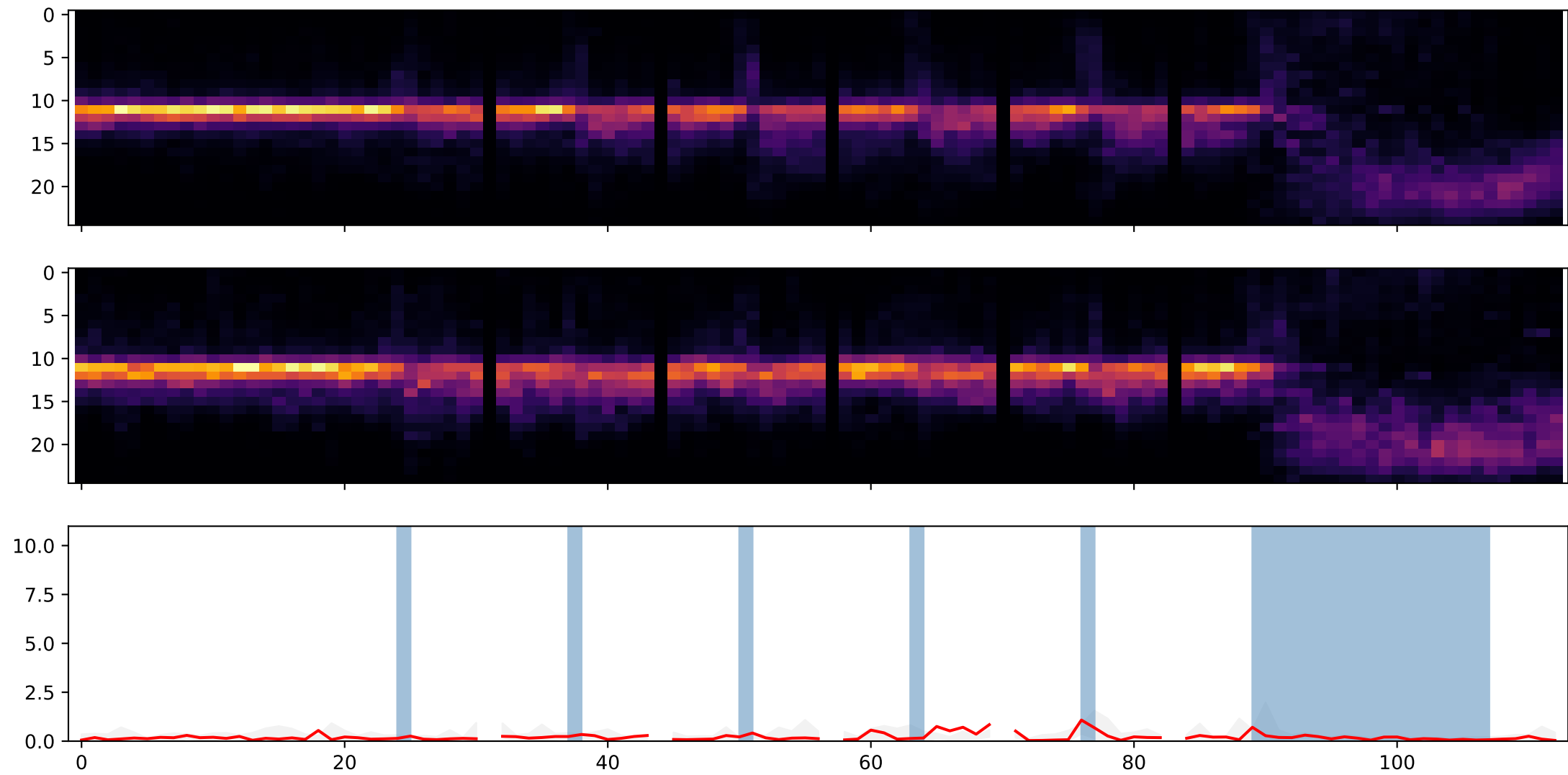
relative_to_body_radial_velocity_tail_tip



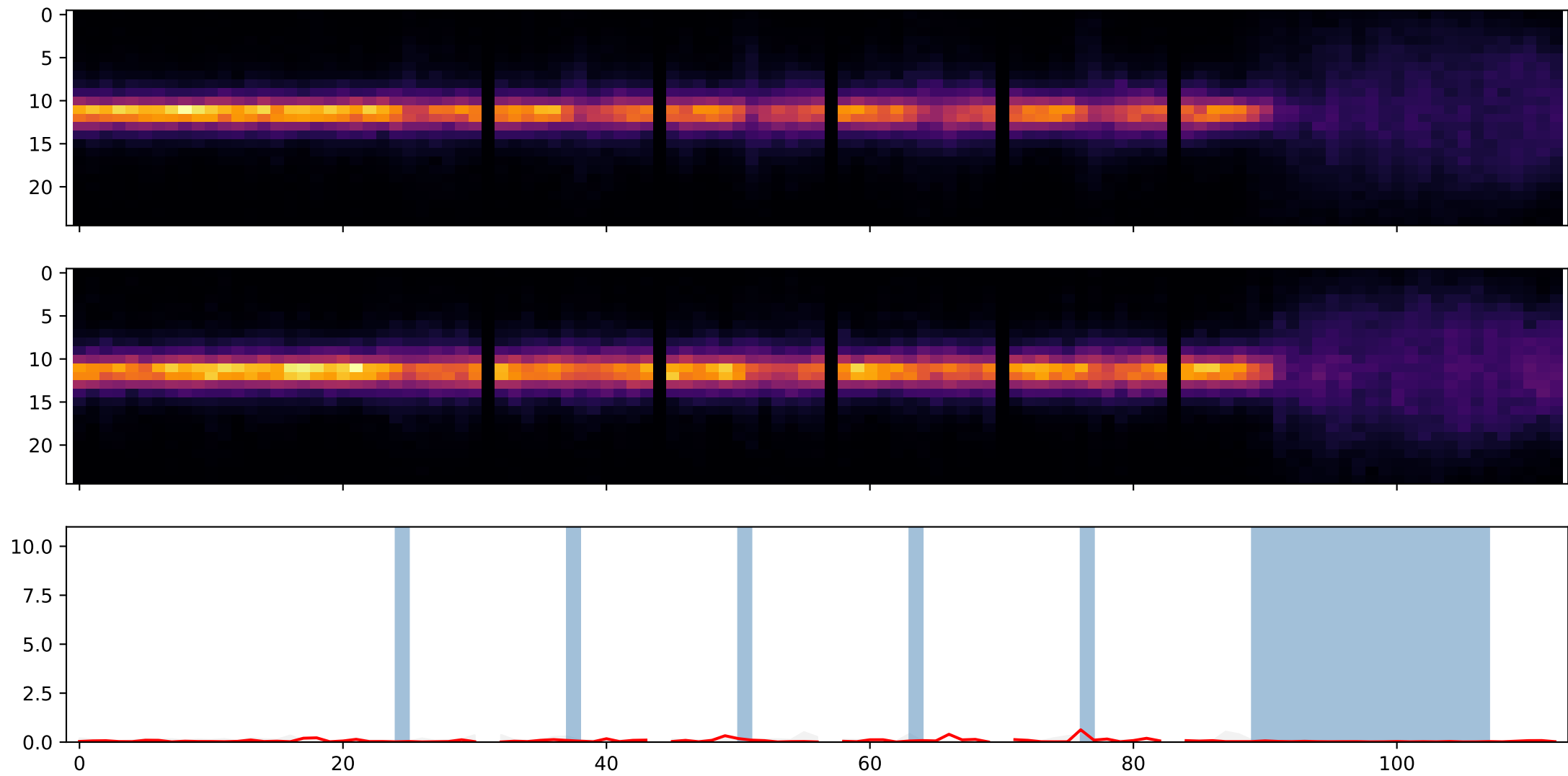
eigen_projection_5



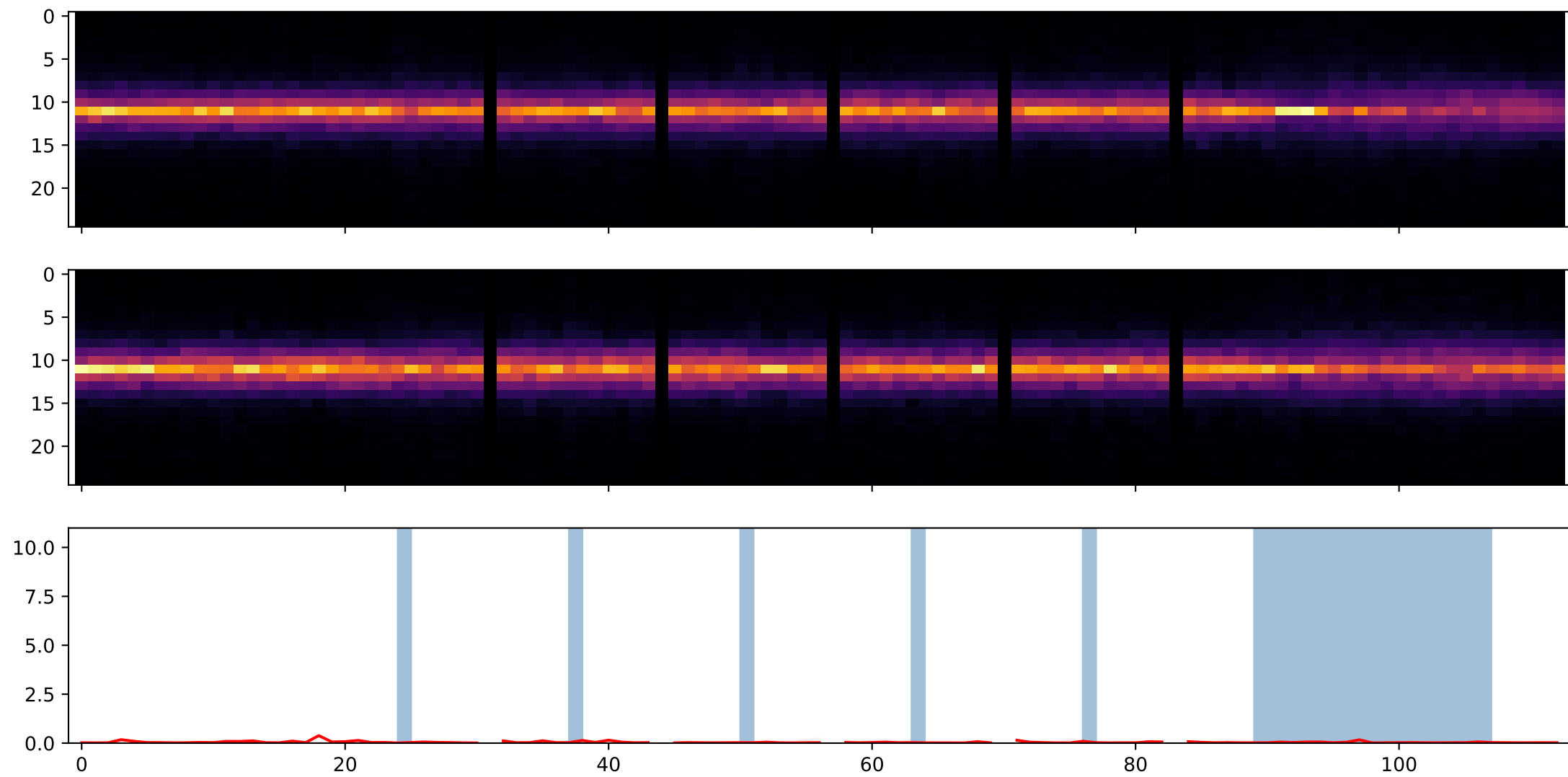
speed_head_base



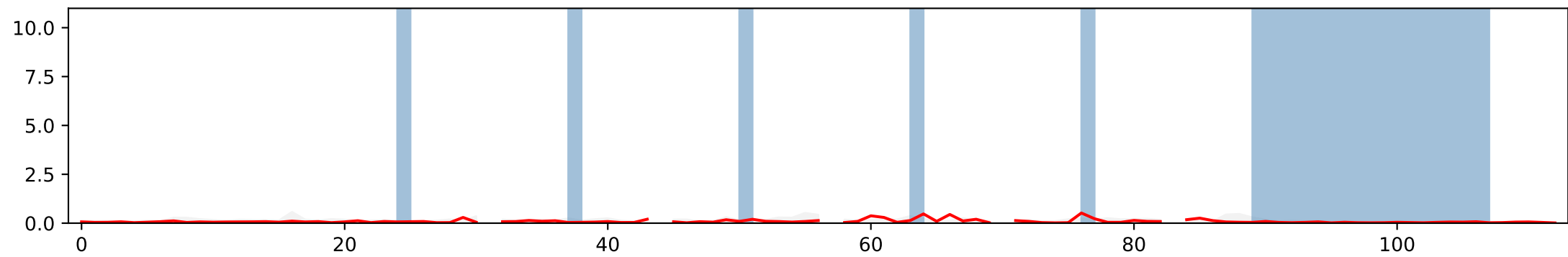
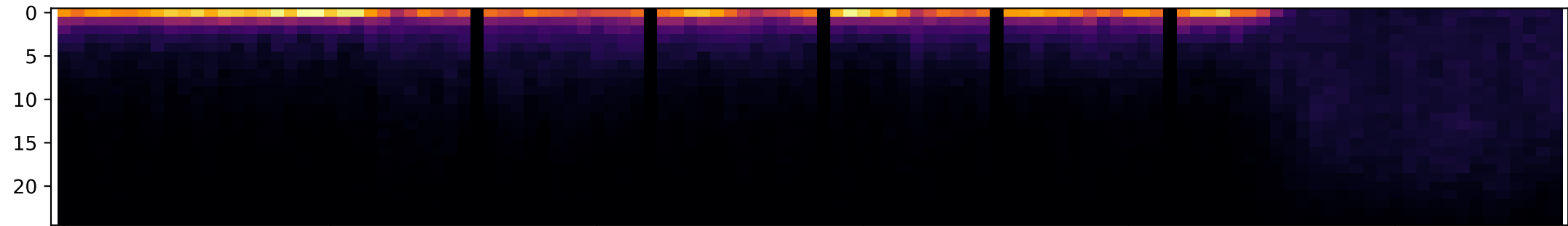
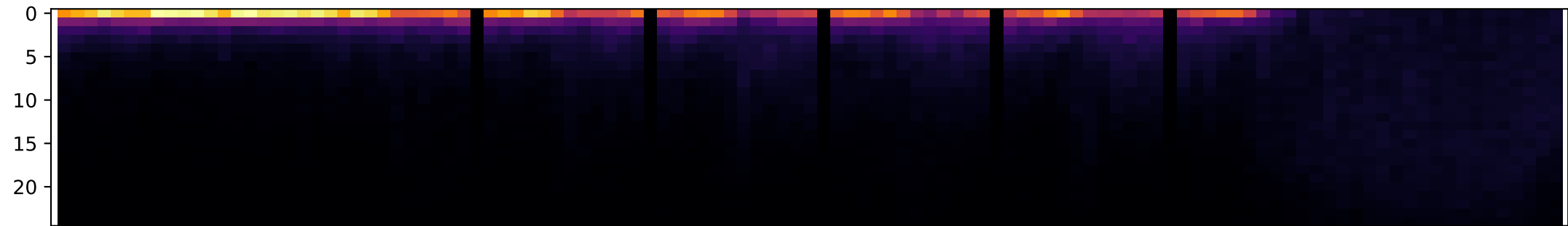
relative_to_hips_radial_velocity_tail_tip



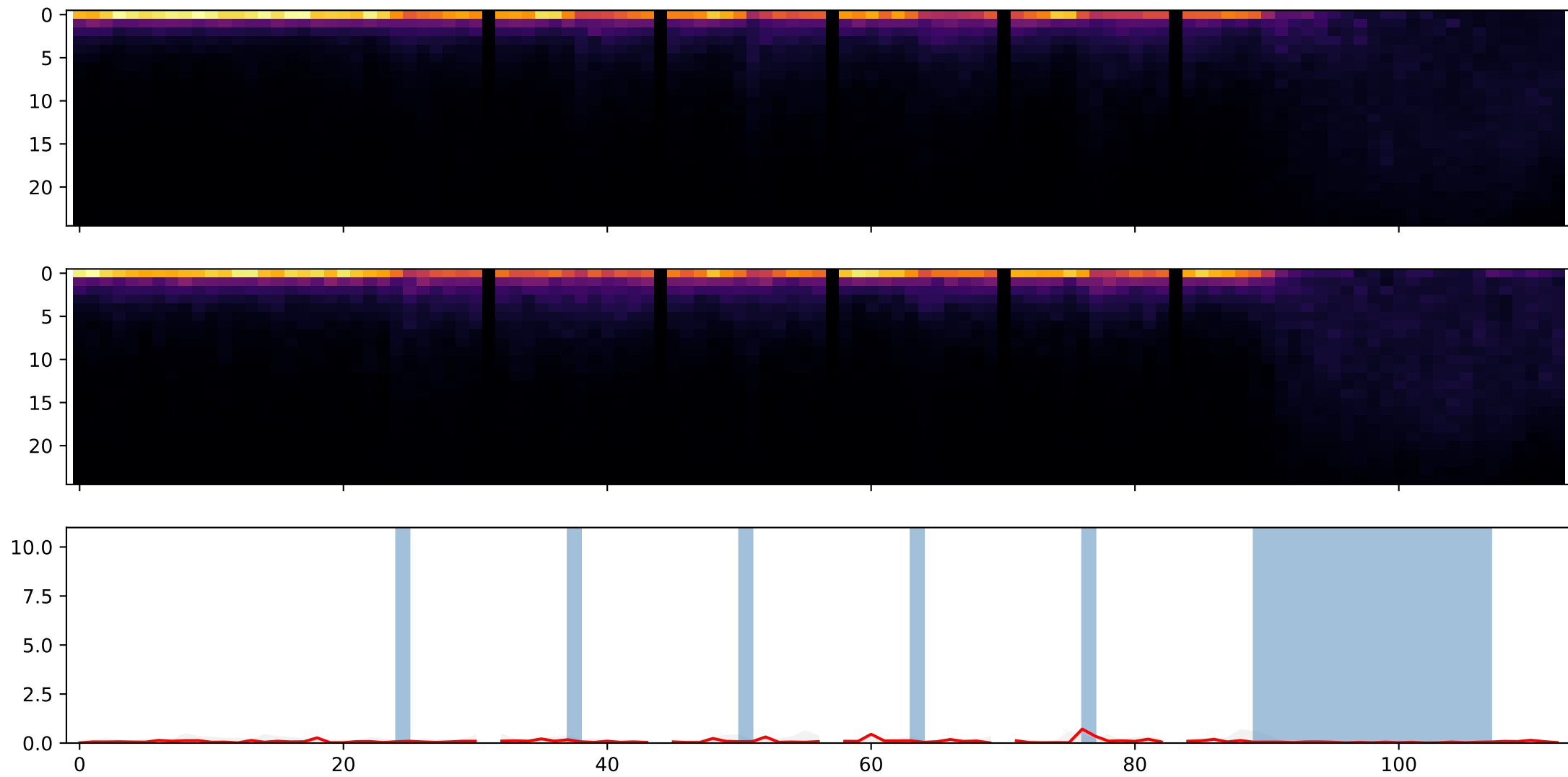
d_speed_head_tip



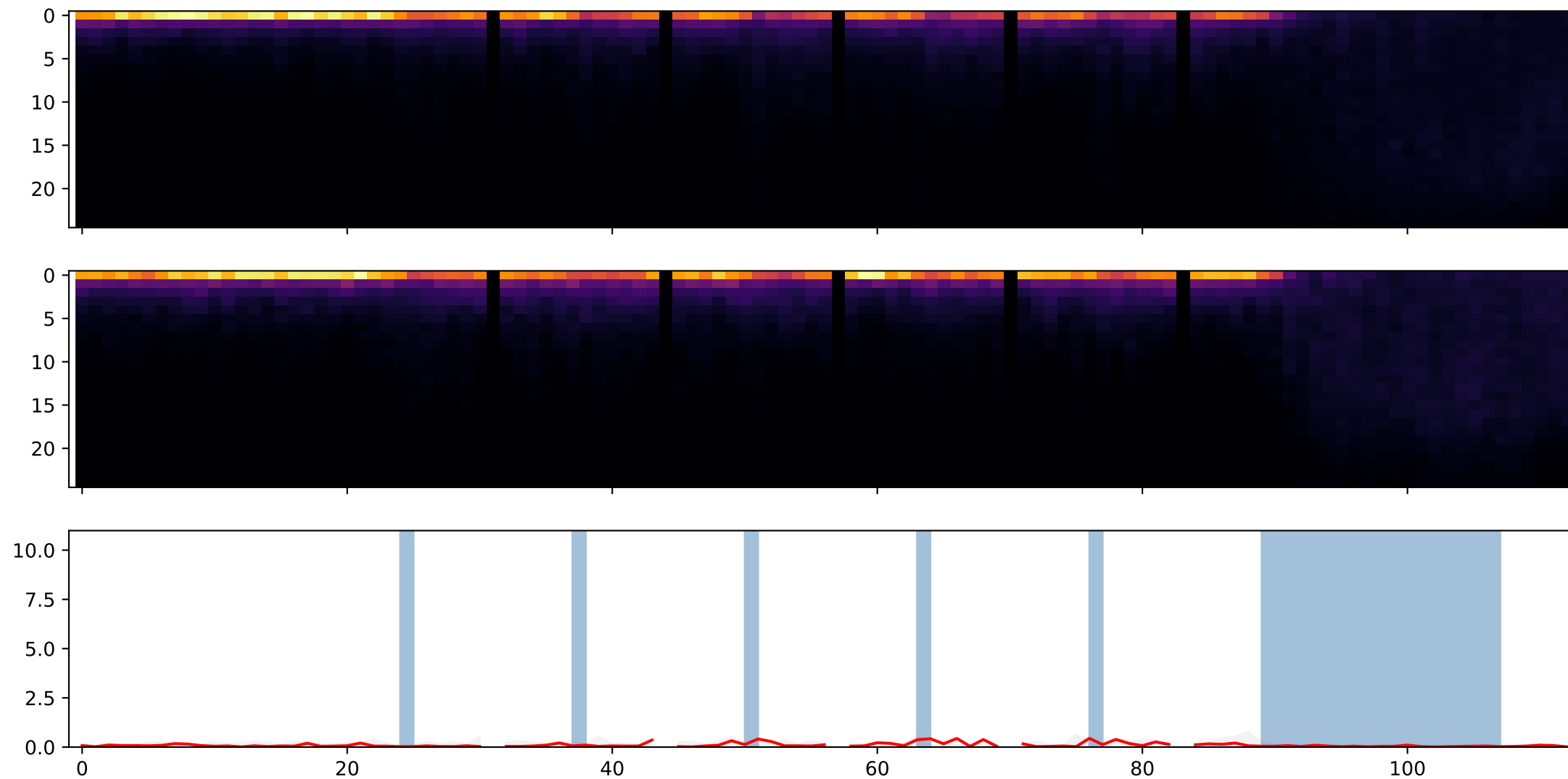
d_curvature_mean_neck



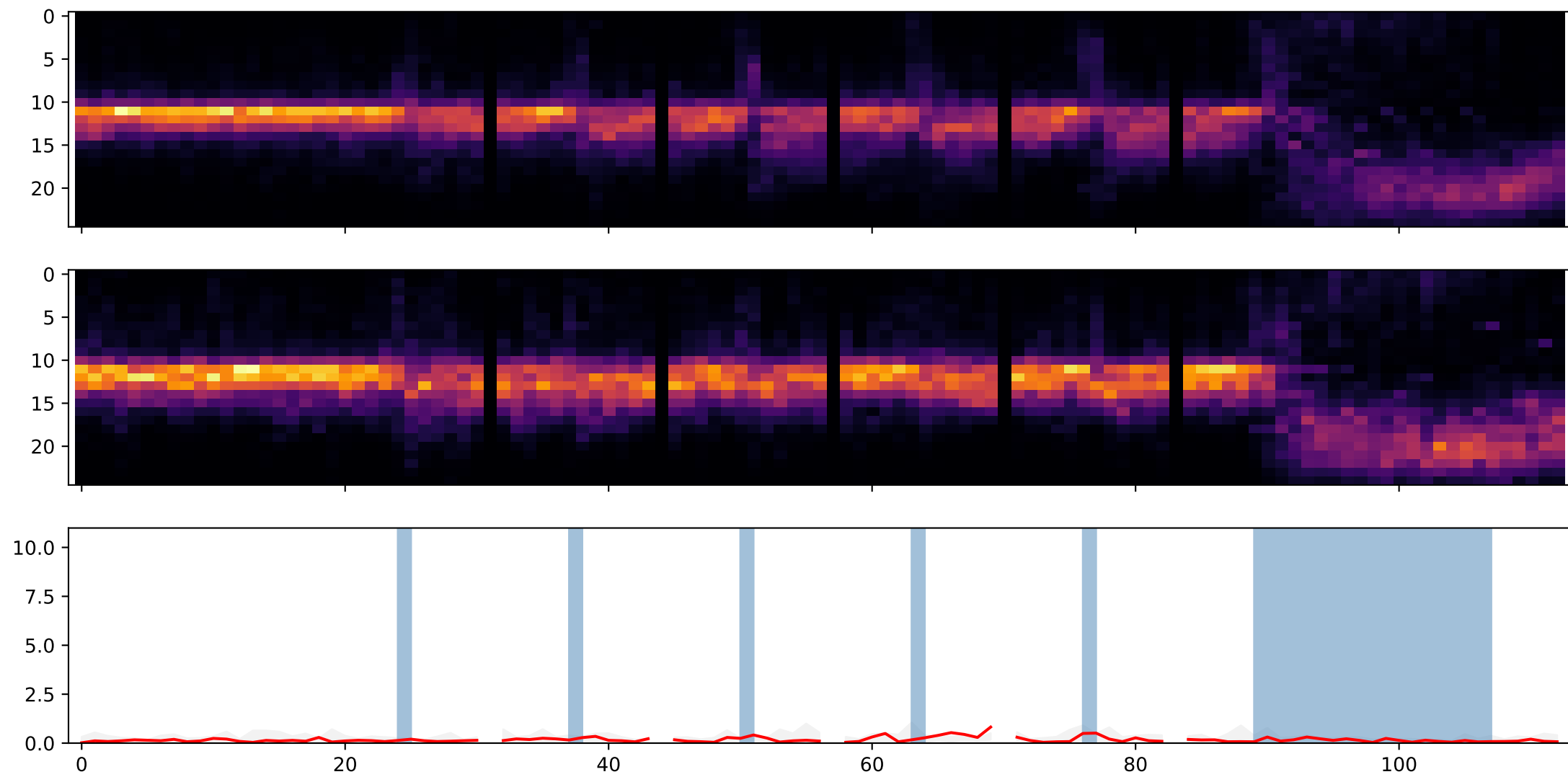
angular_velocity_neck



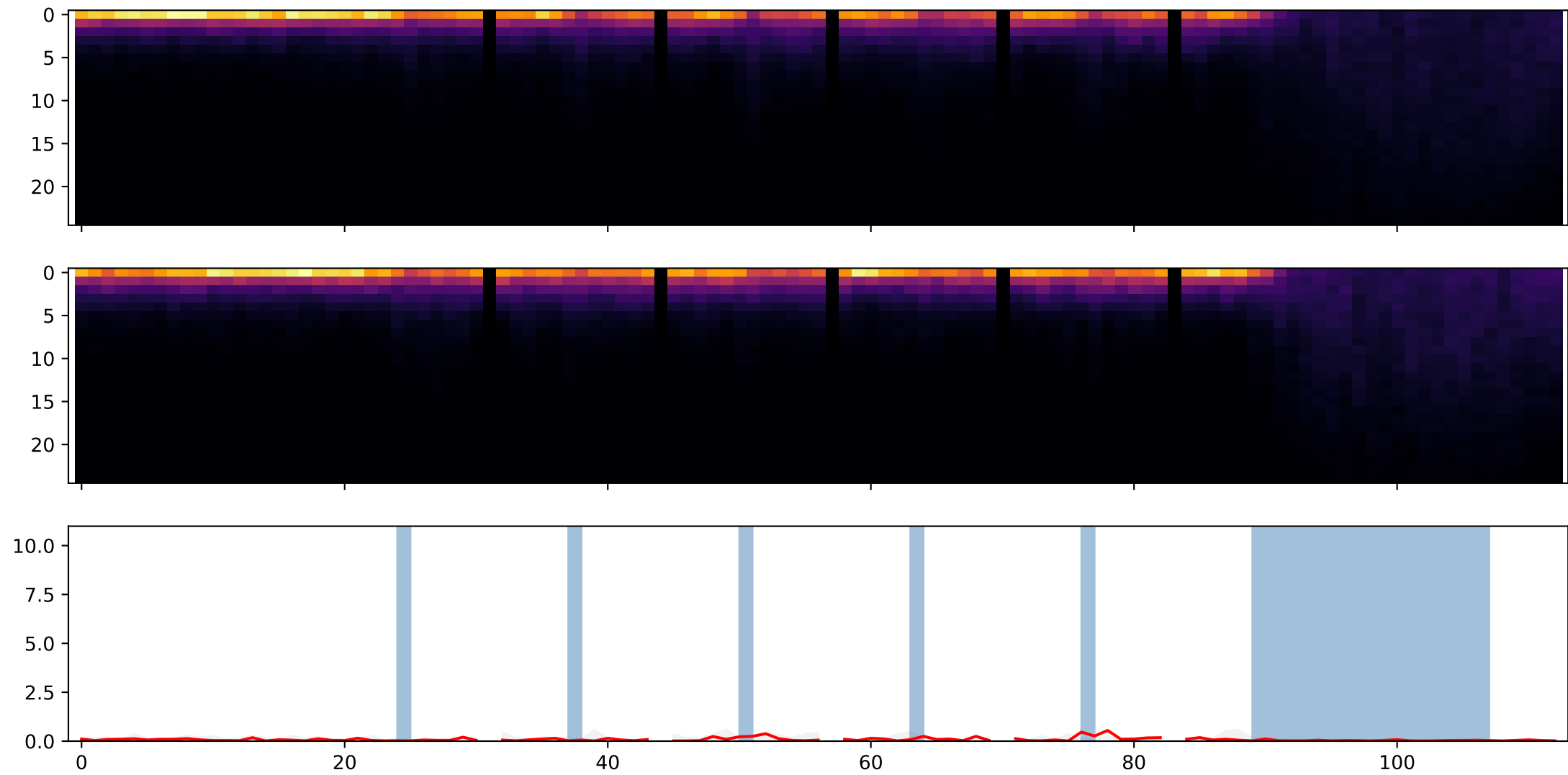
d_curvature_mean_hips



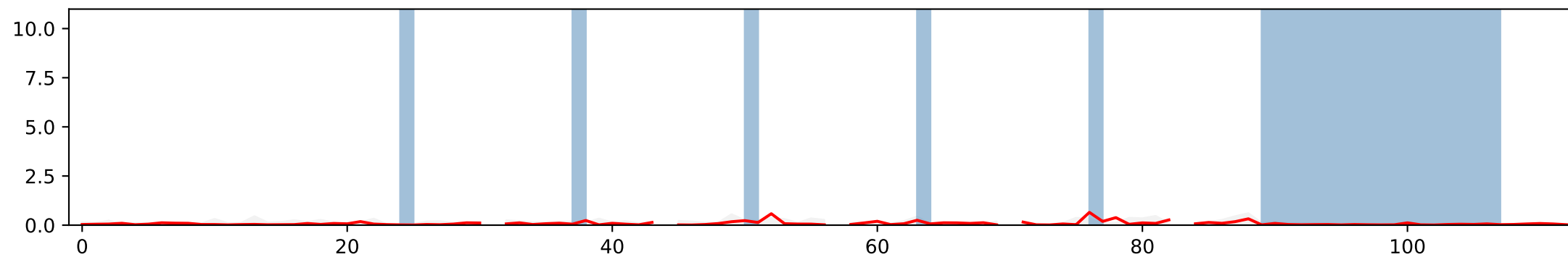
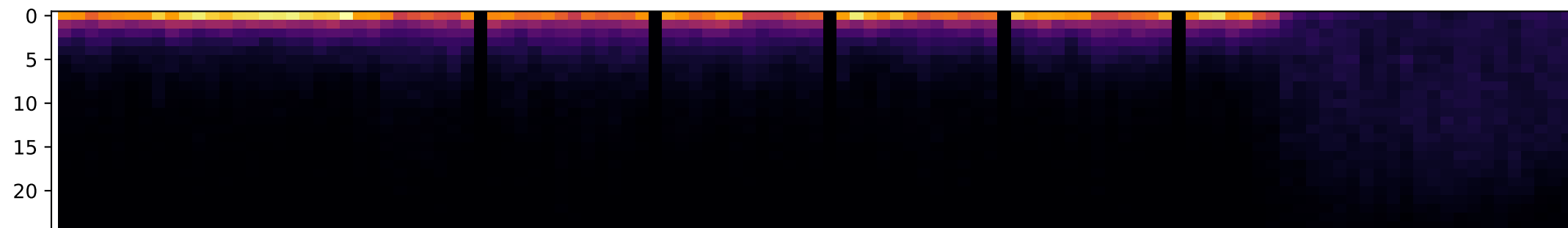
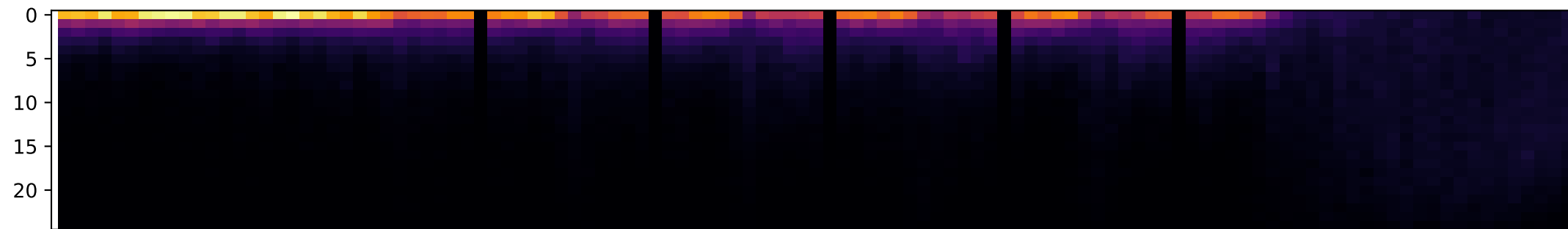
speed_head_tip



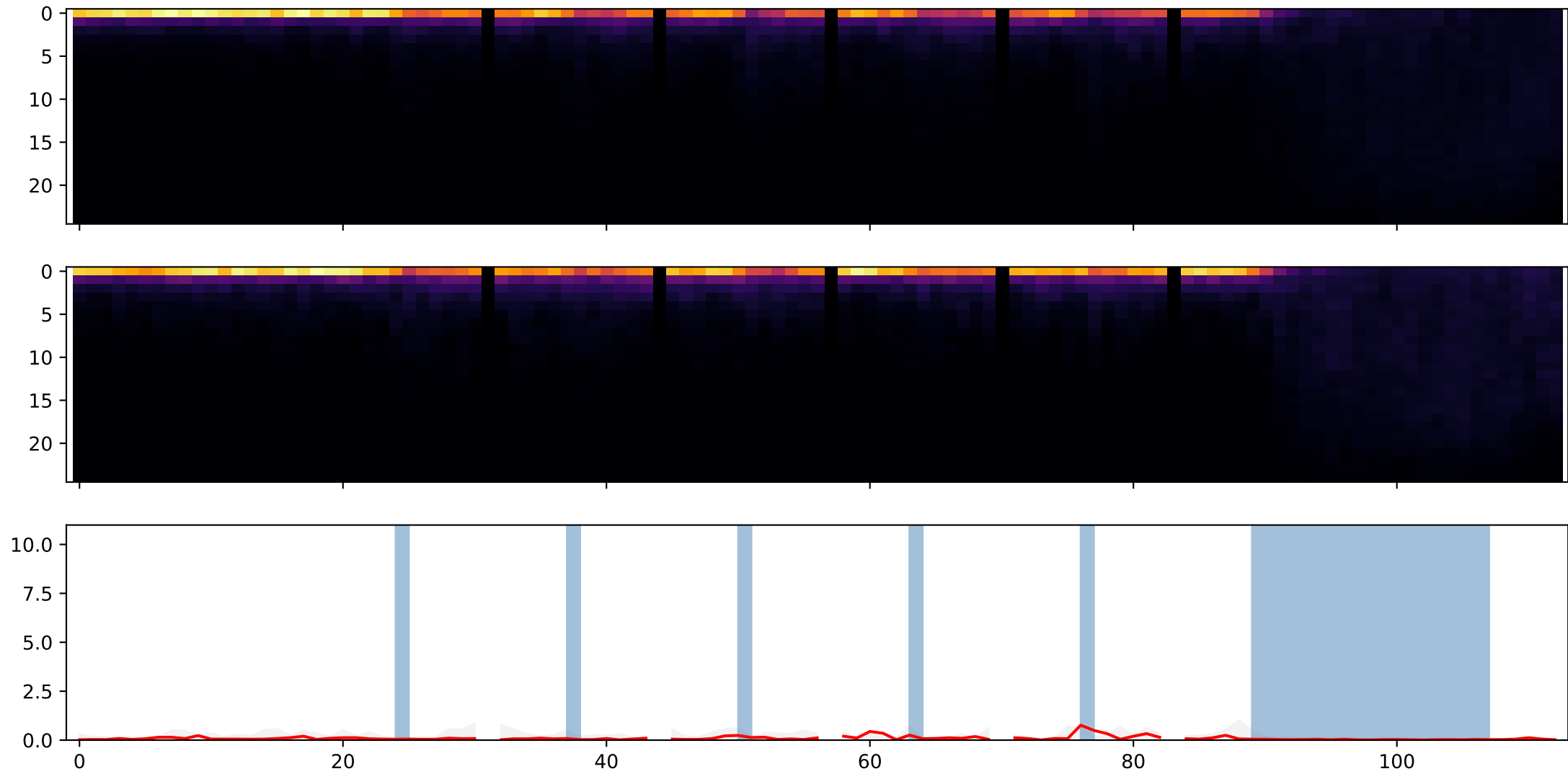
d_relative_to_hips_angular_velocity_tail_tip



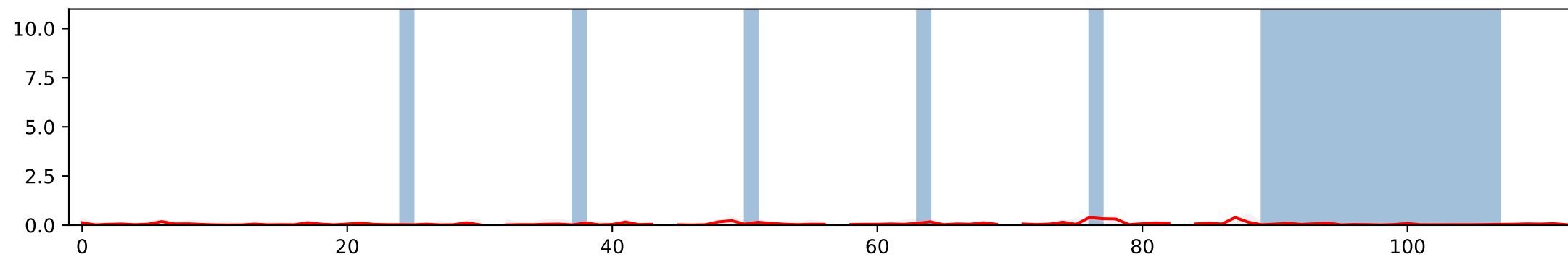
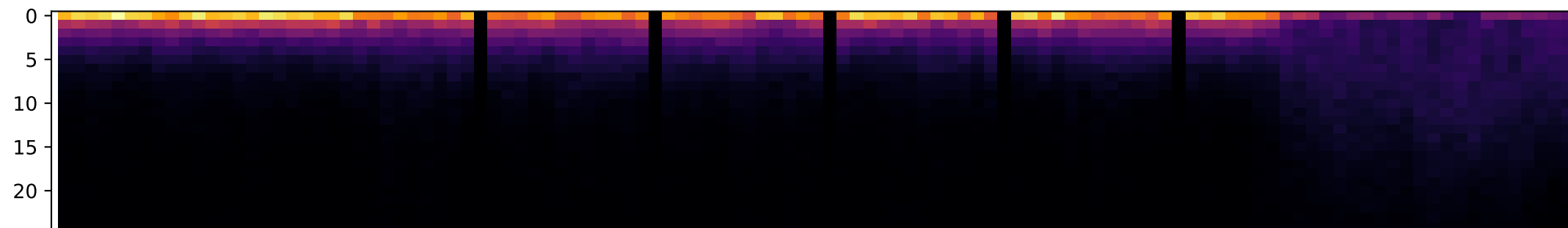
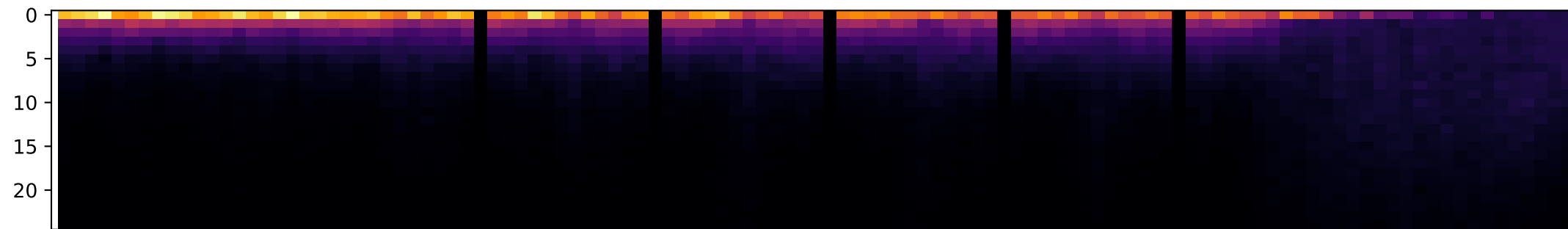
d_curvature_mean_tail



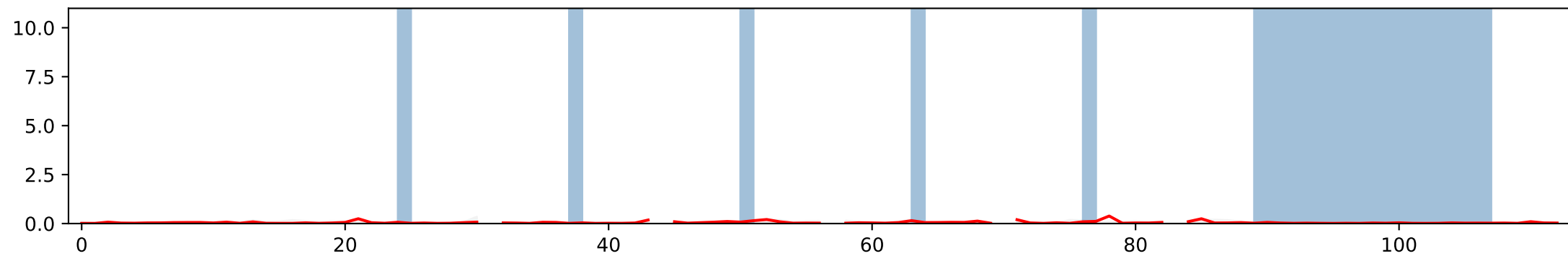
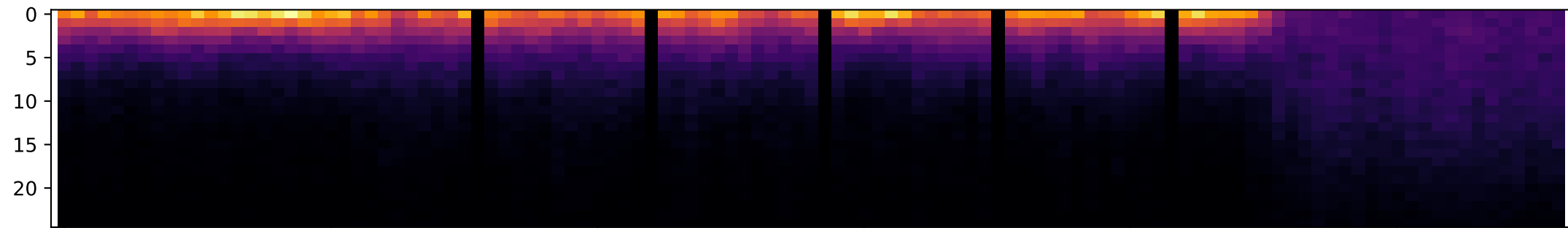
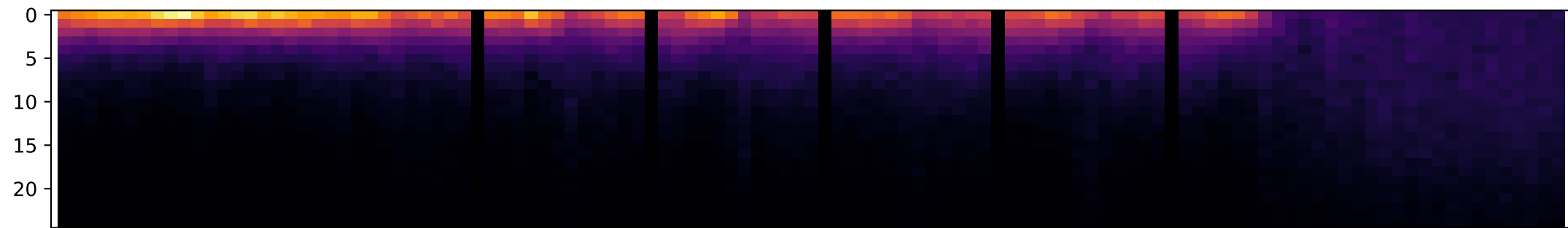
relative_to_body_angular_velocity_hips



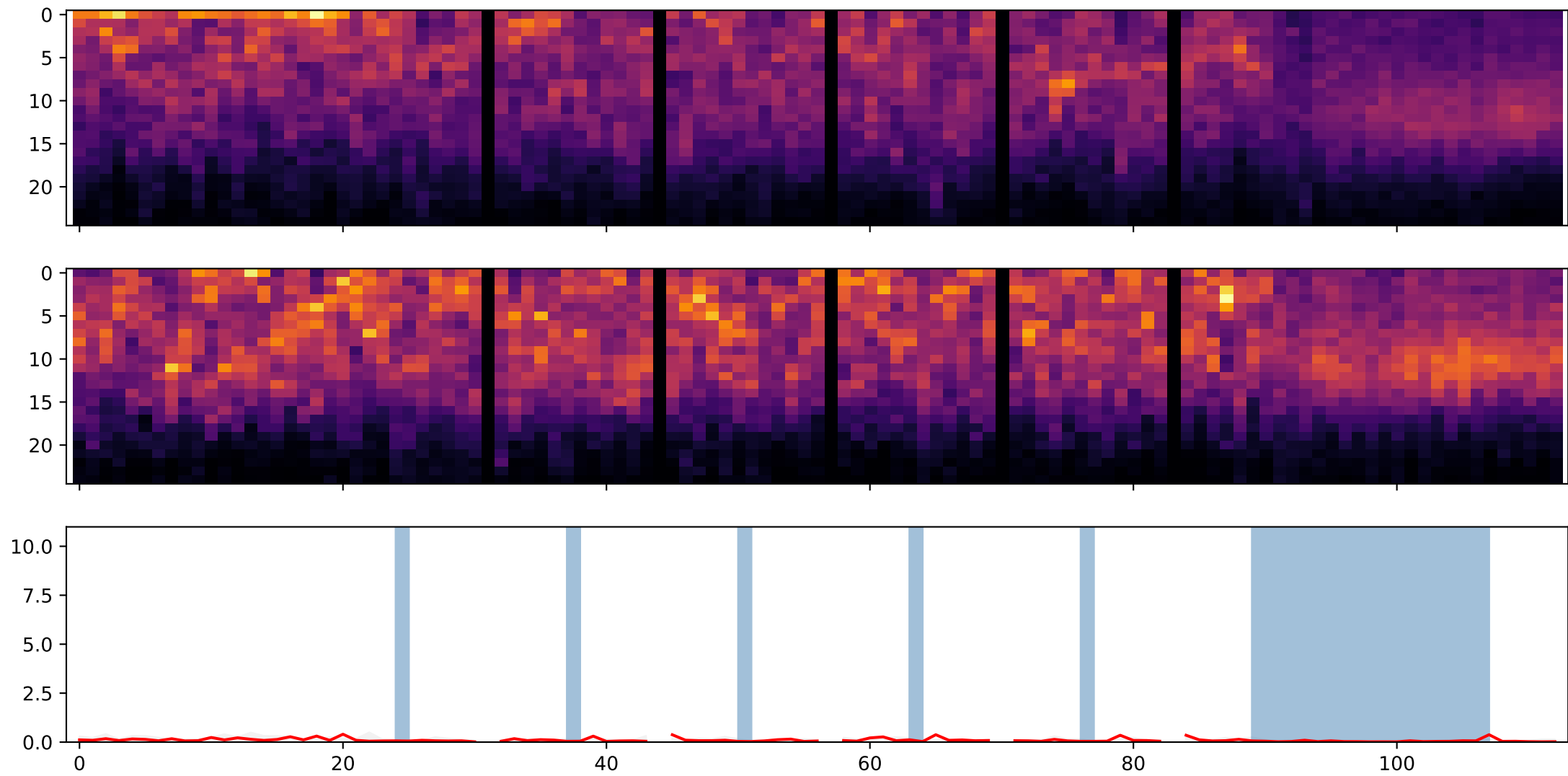
d_angular_velocity_tail_base



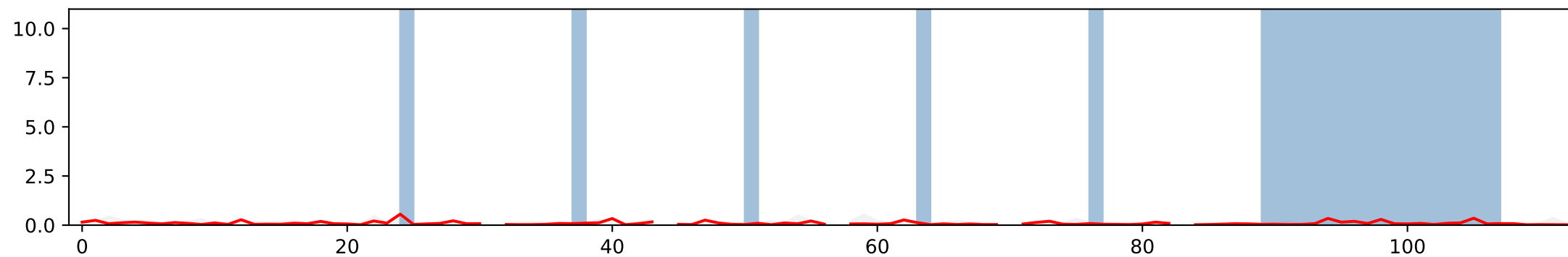
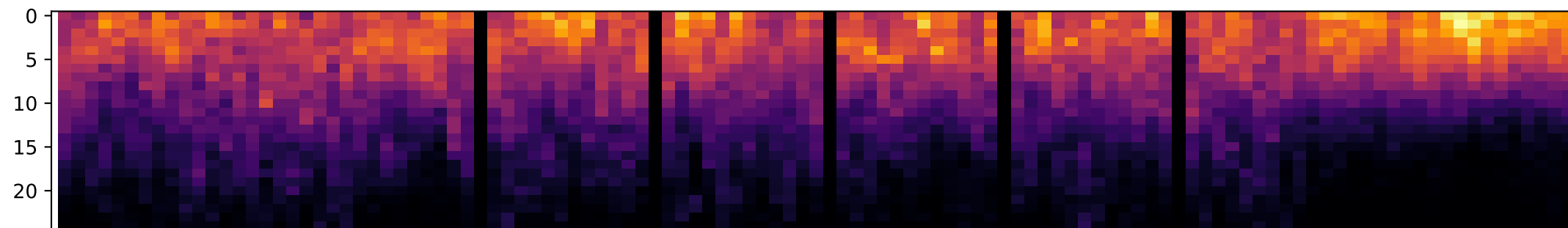
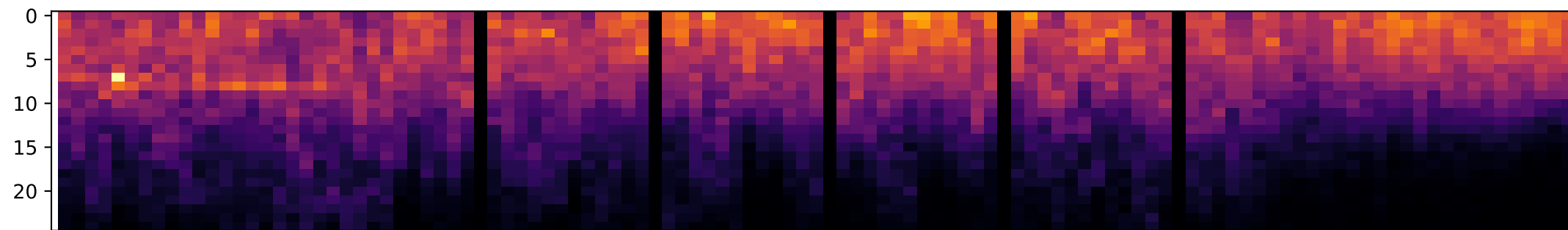
d_curvature_std_hips



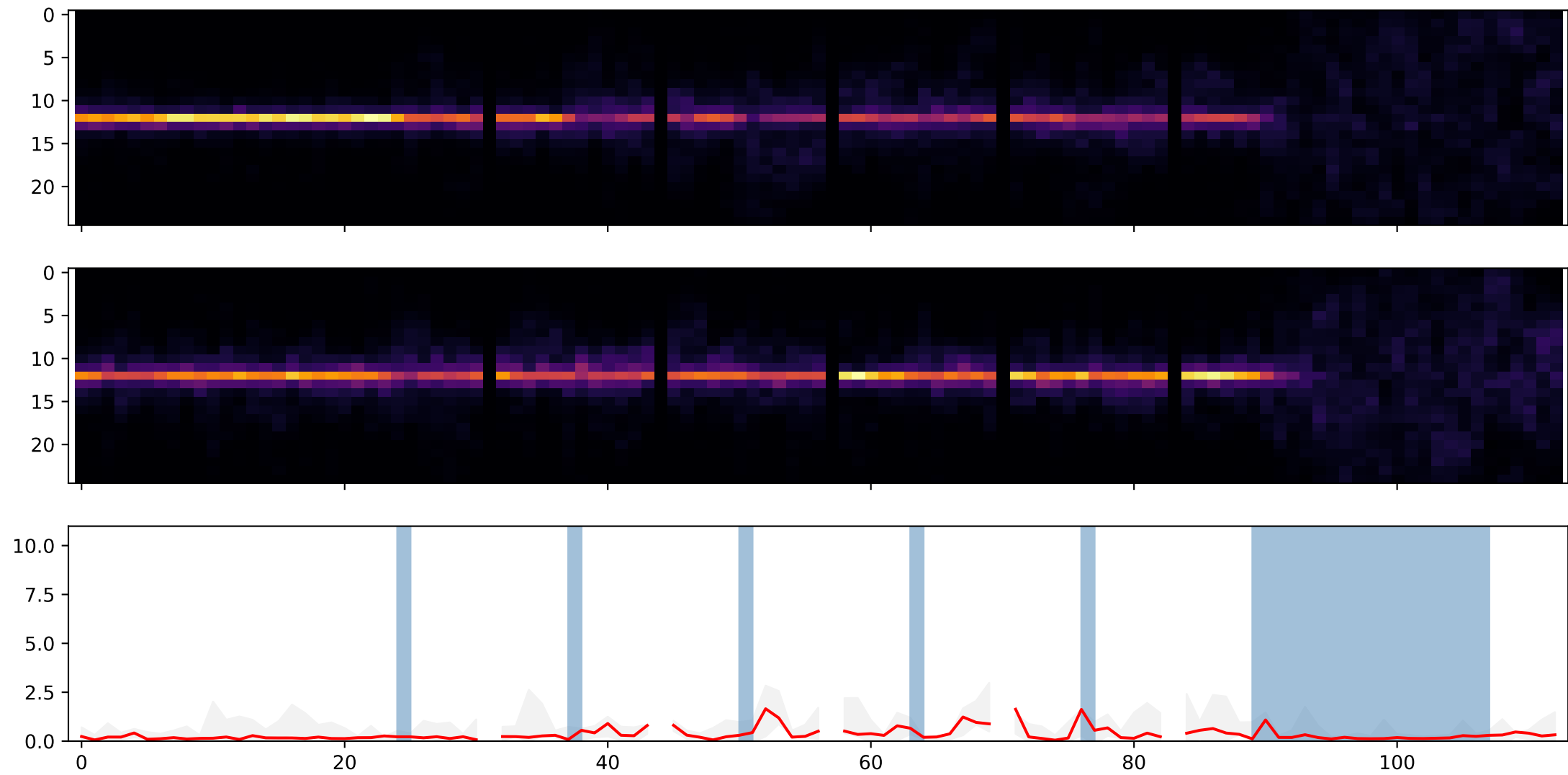
curvature_mean_head



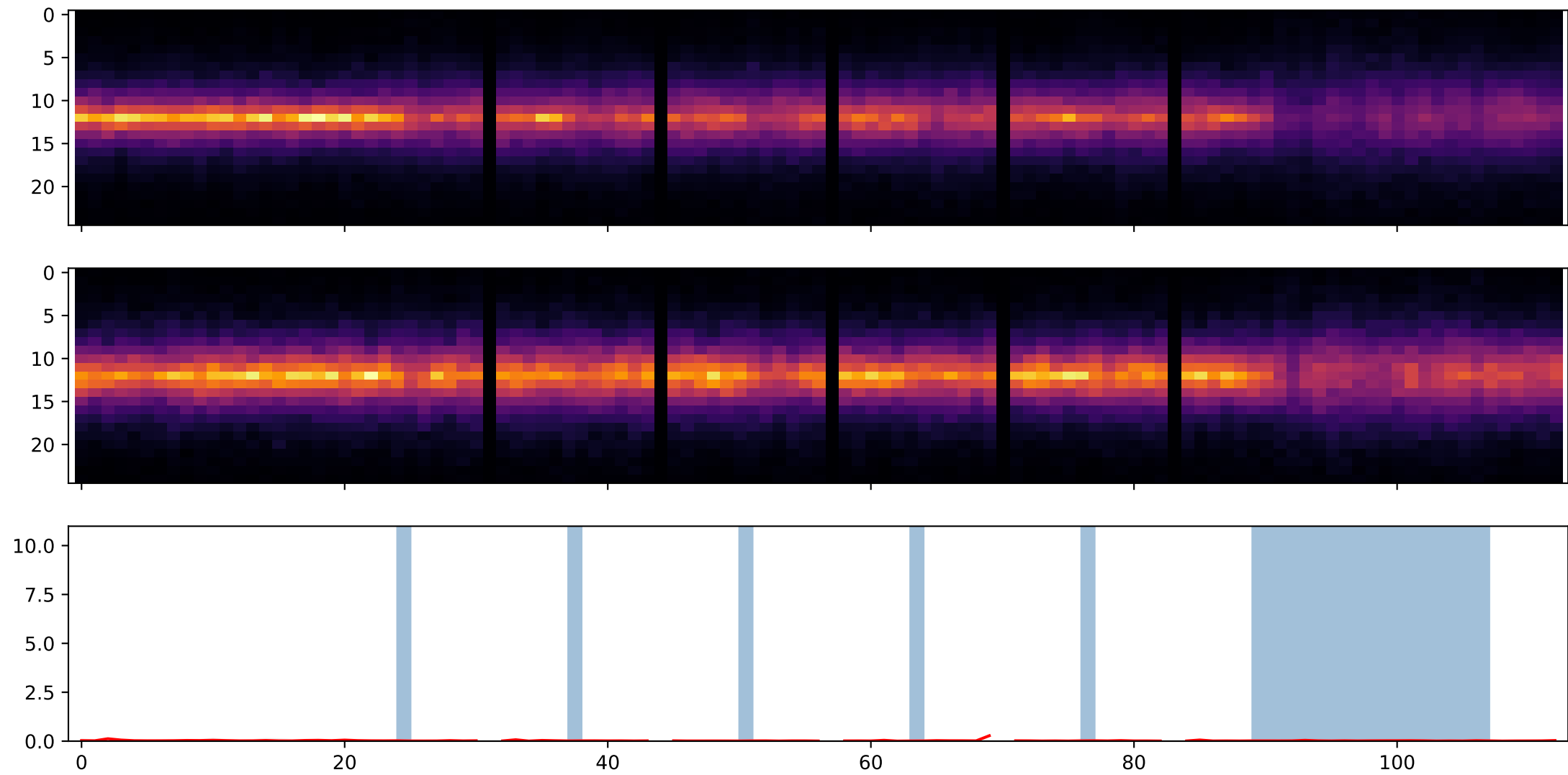
eigen_projection_6



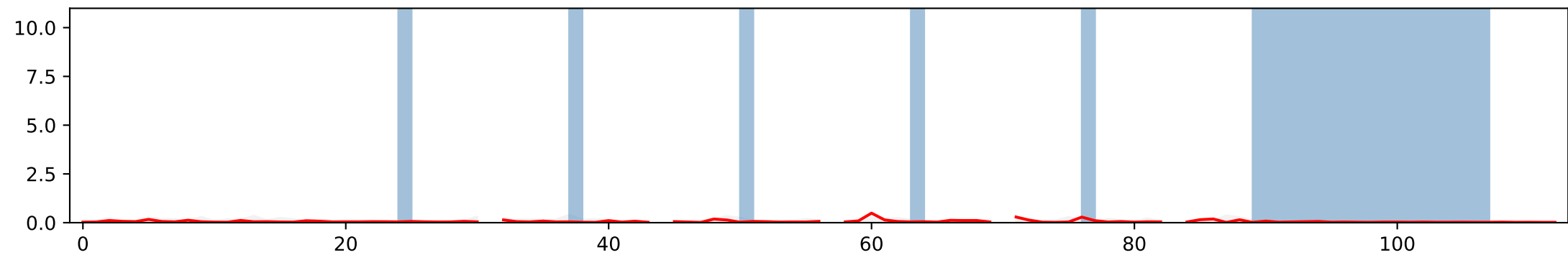
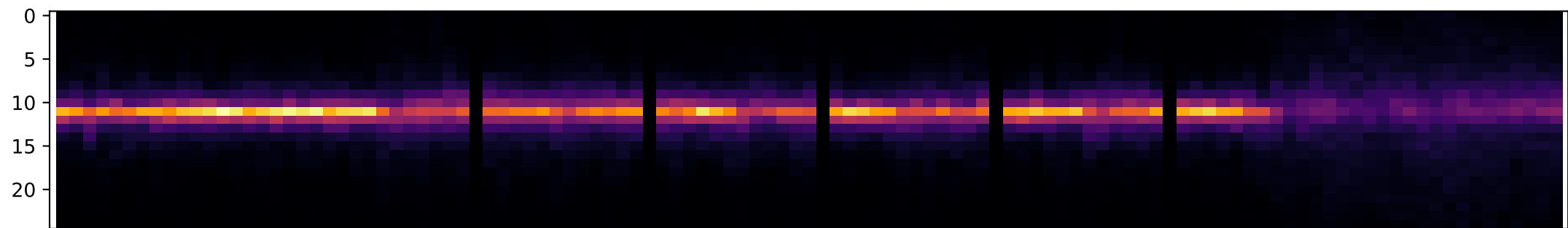
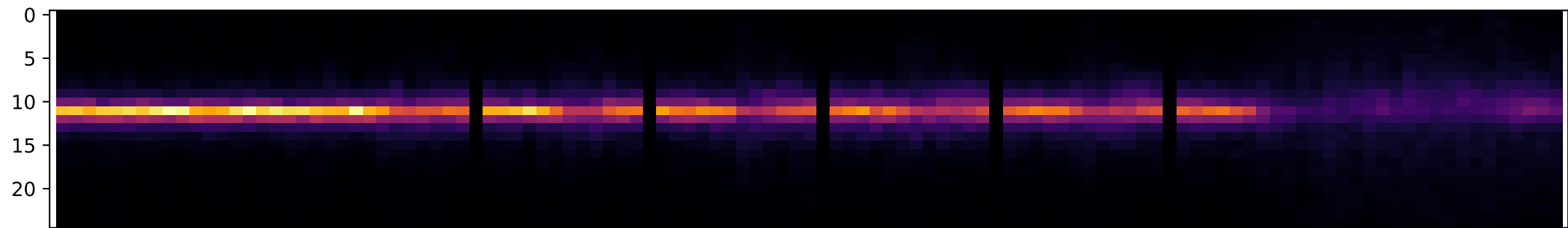
d_dist_from_food_edge



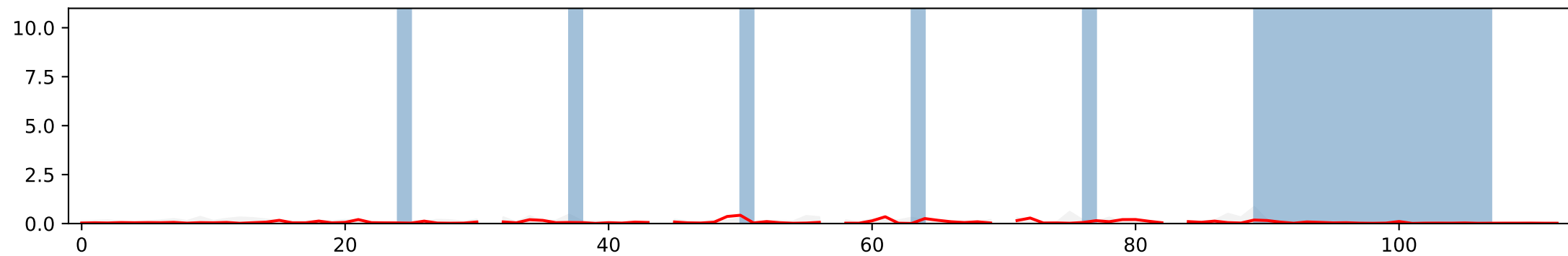
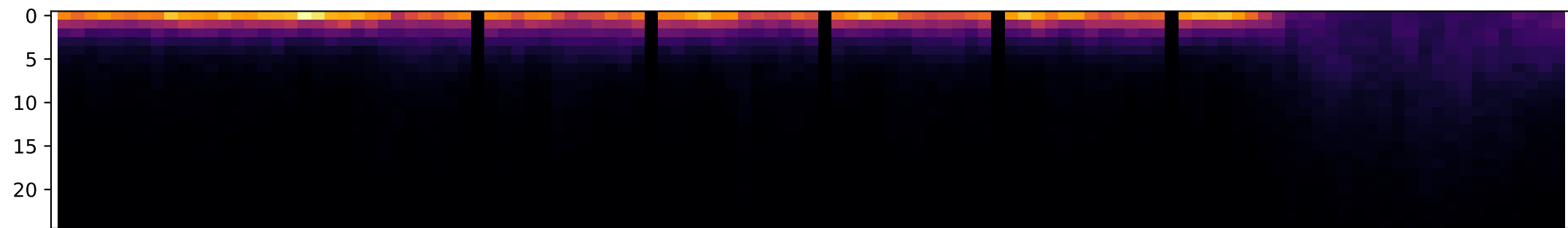
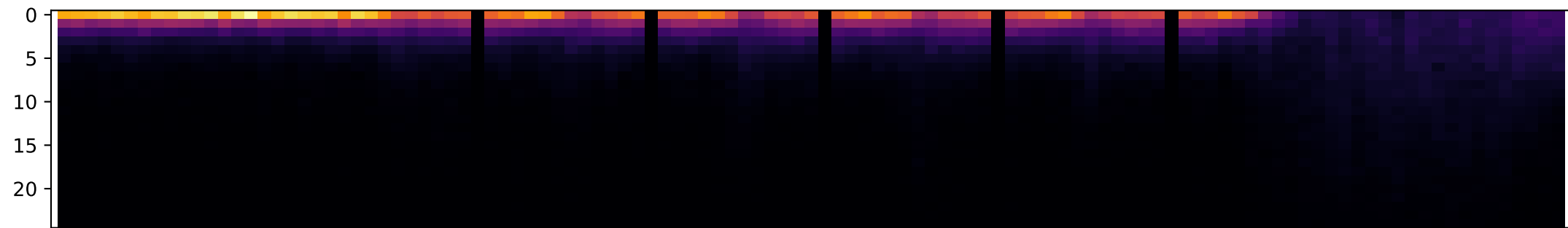
relative_to_head_base_radial_velocity_head_tip



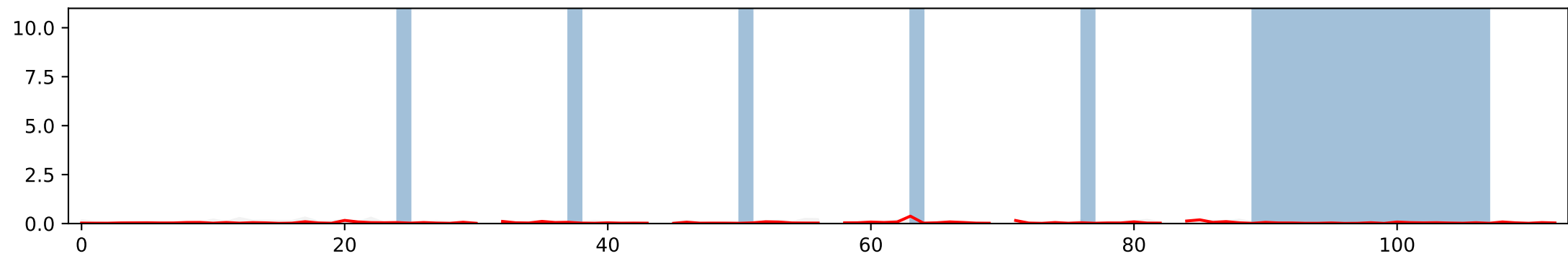
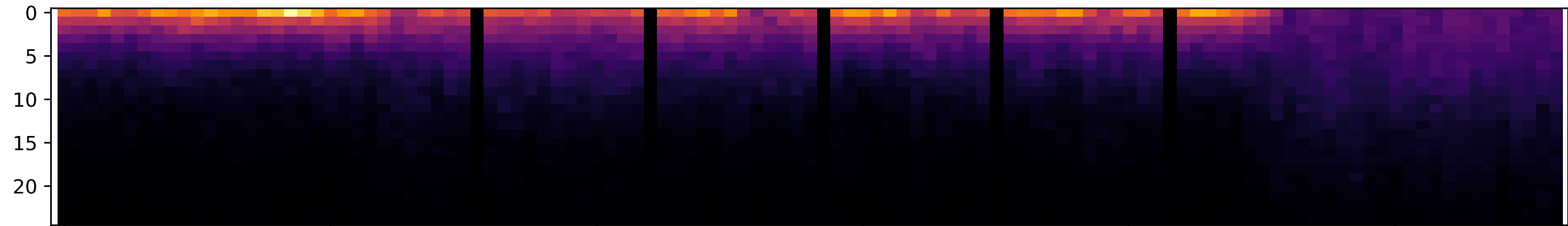
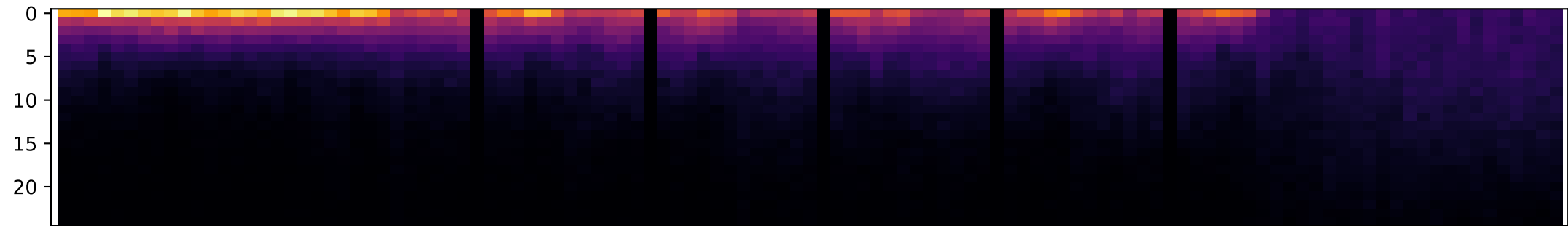
d_minor_axis



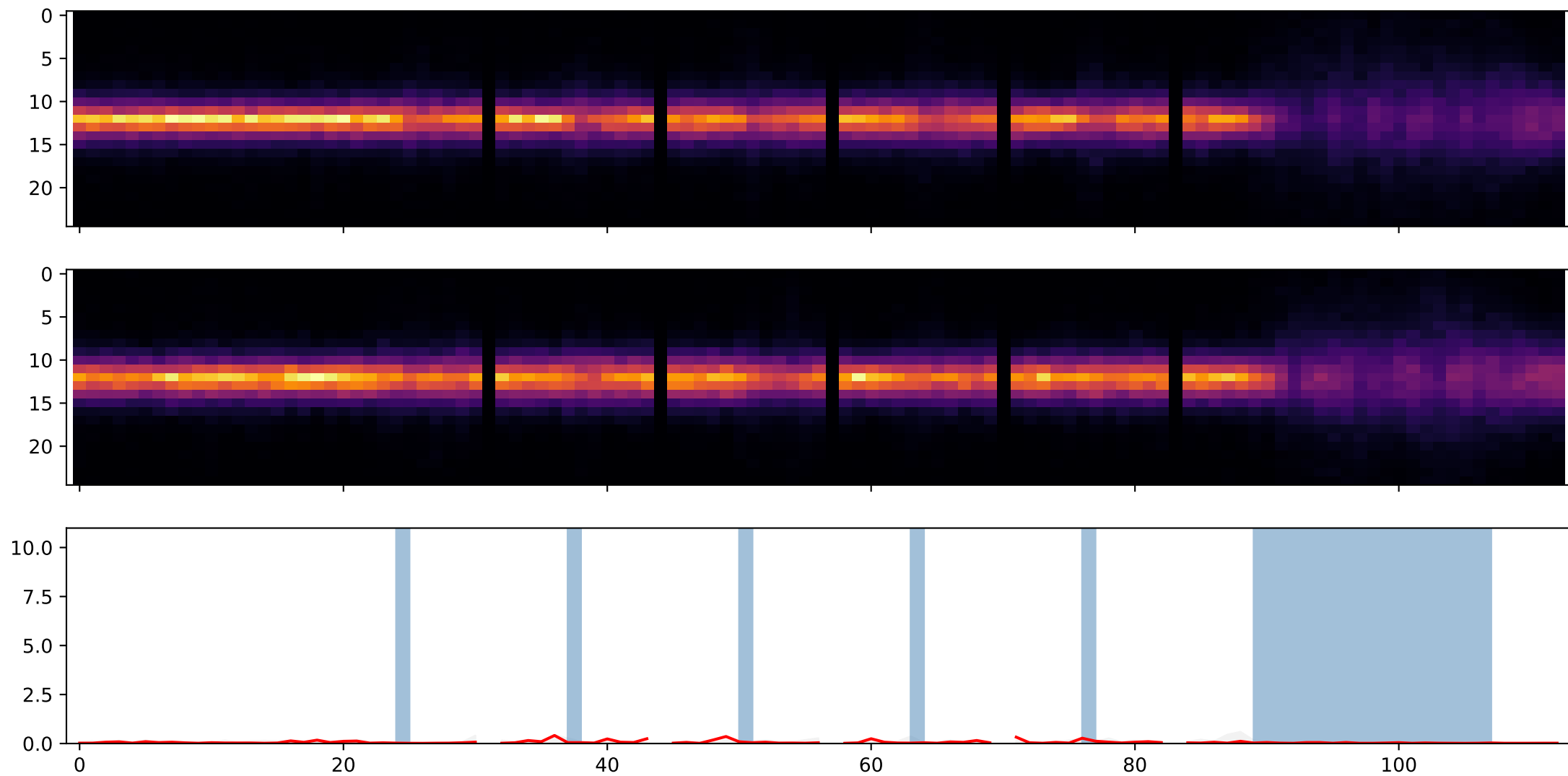
d_relative_to_body_angular_velocity_head_tip



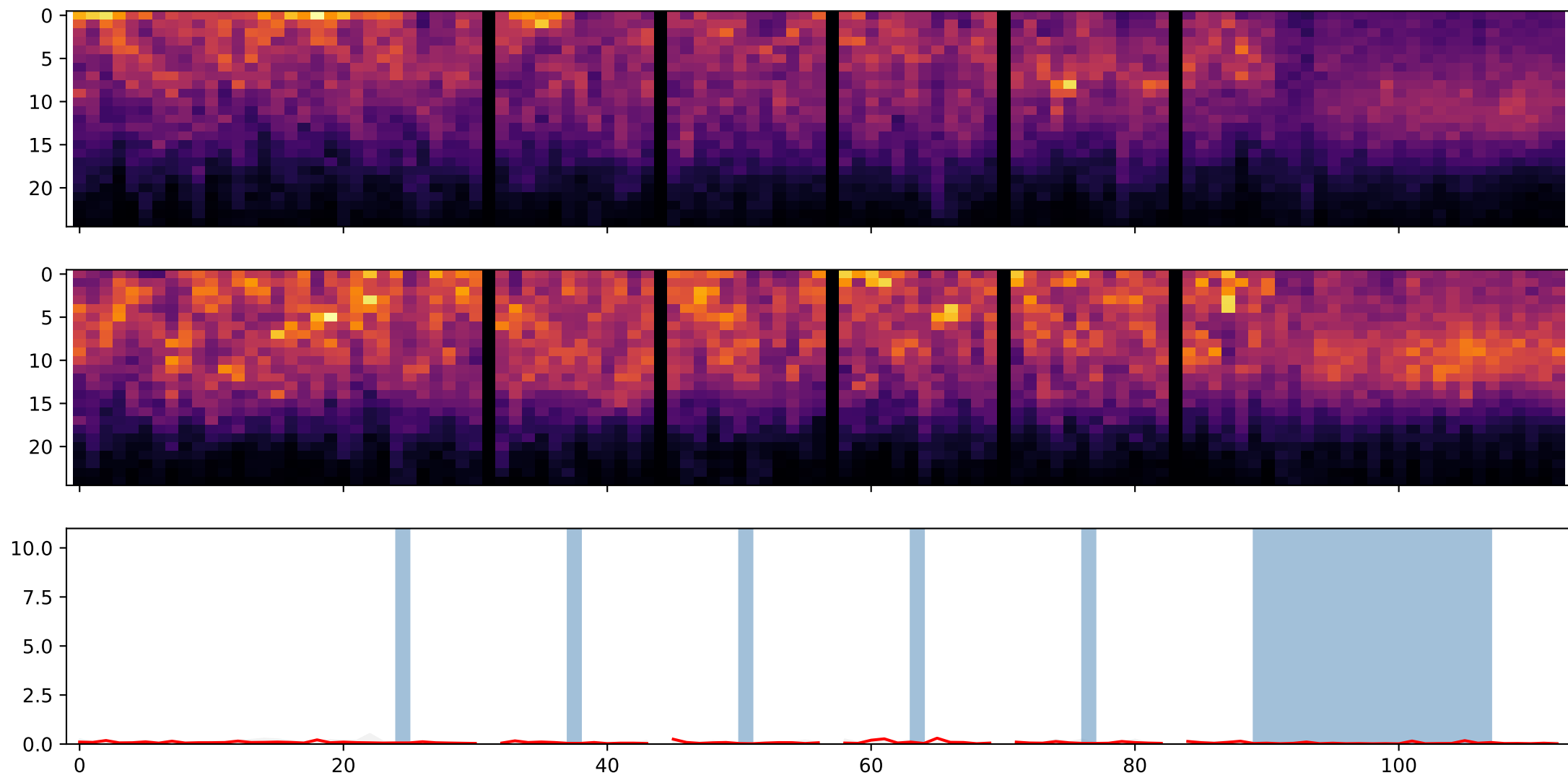
d_eigen_projection_4



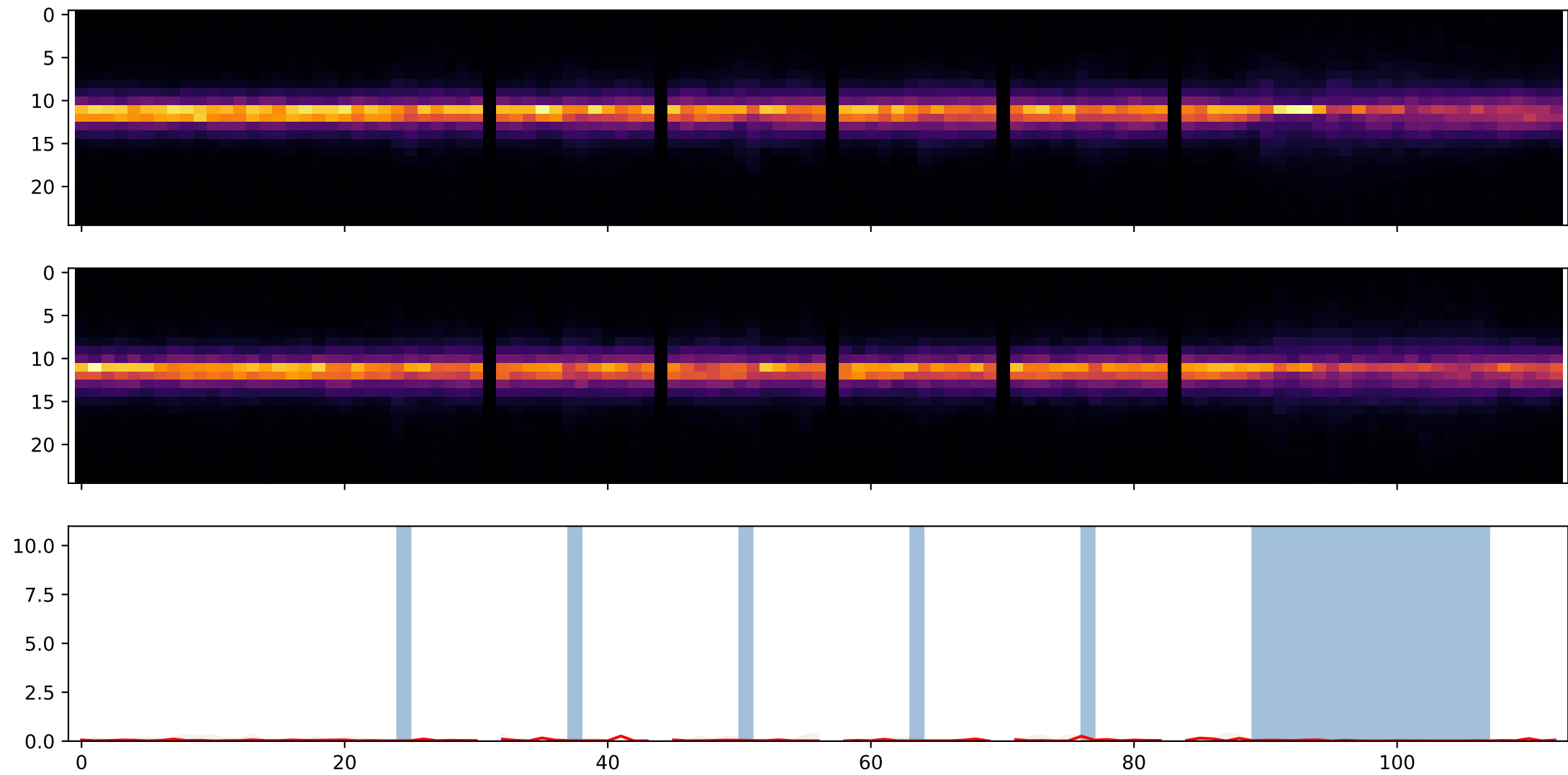
d_relative_to_body_radial_velocity_tail_tip



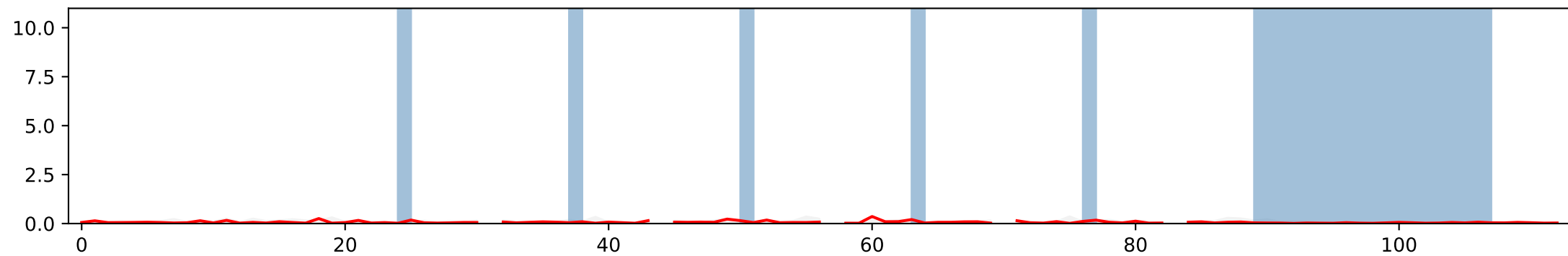
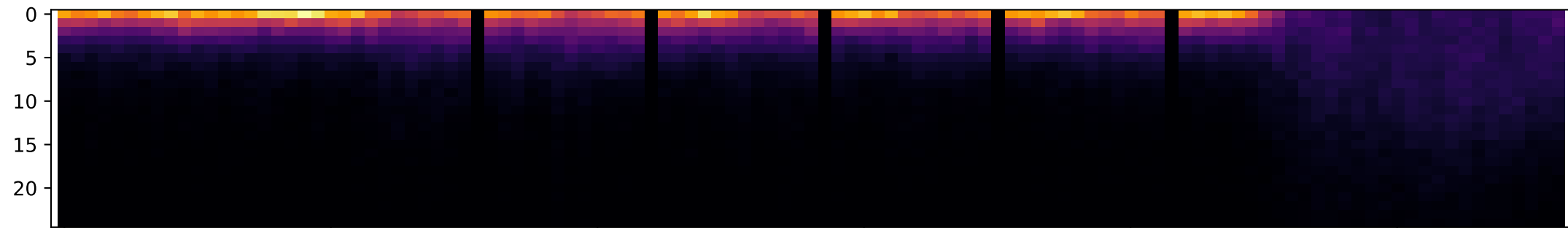
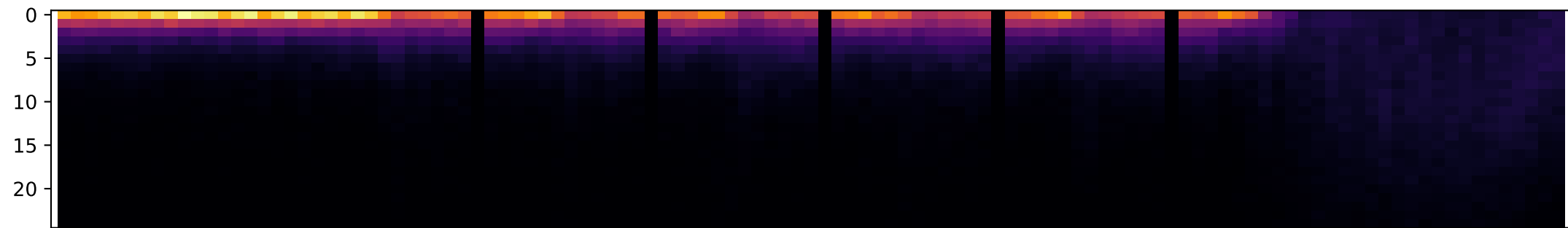
curvature_head



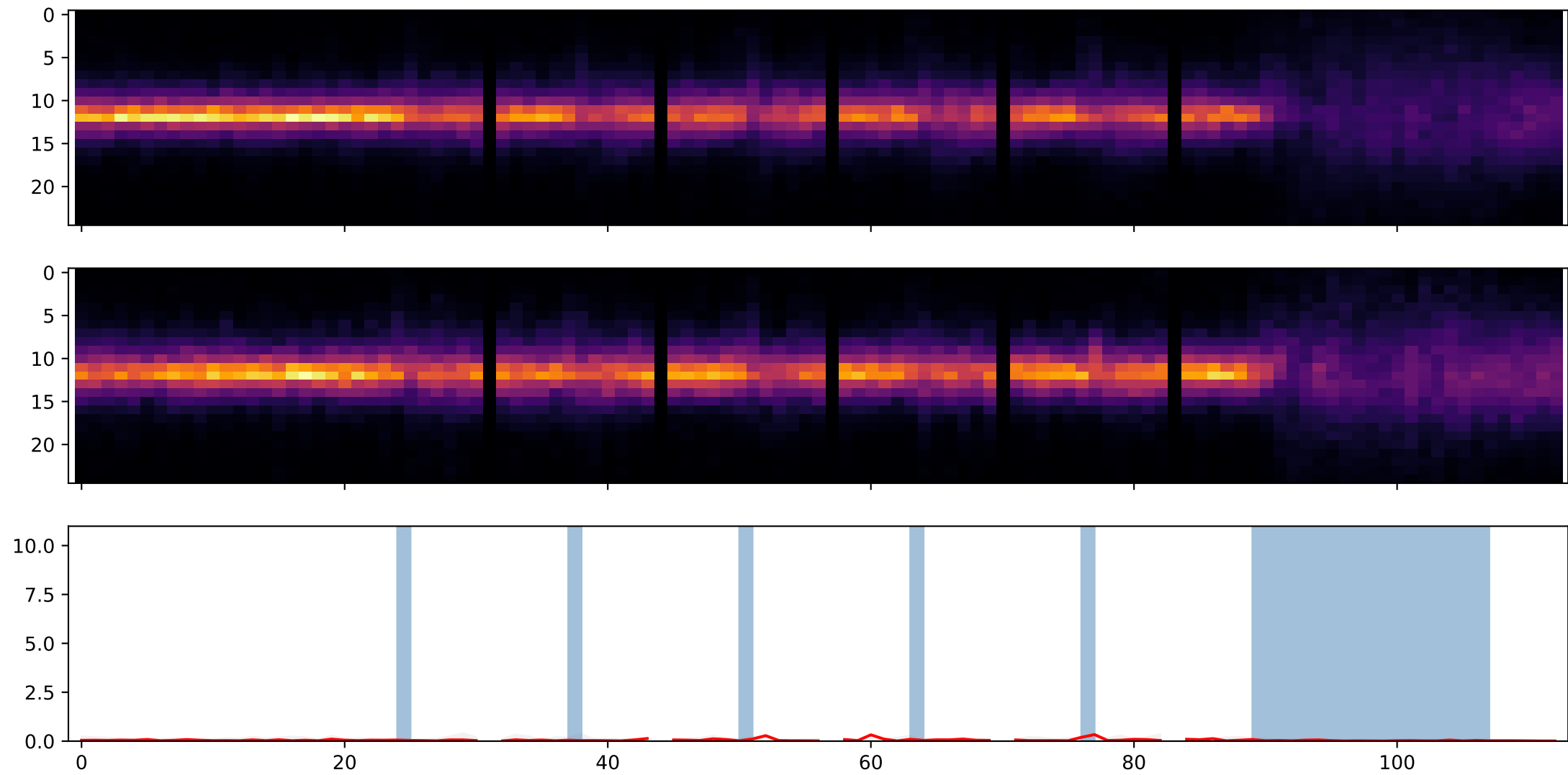
d_speed_tail_tip



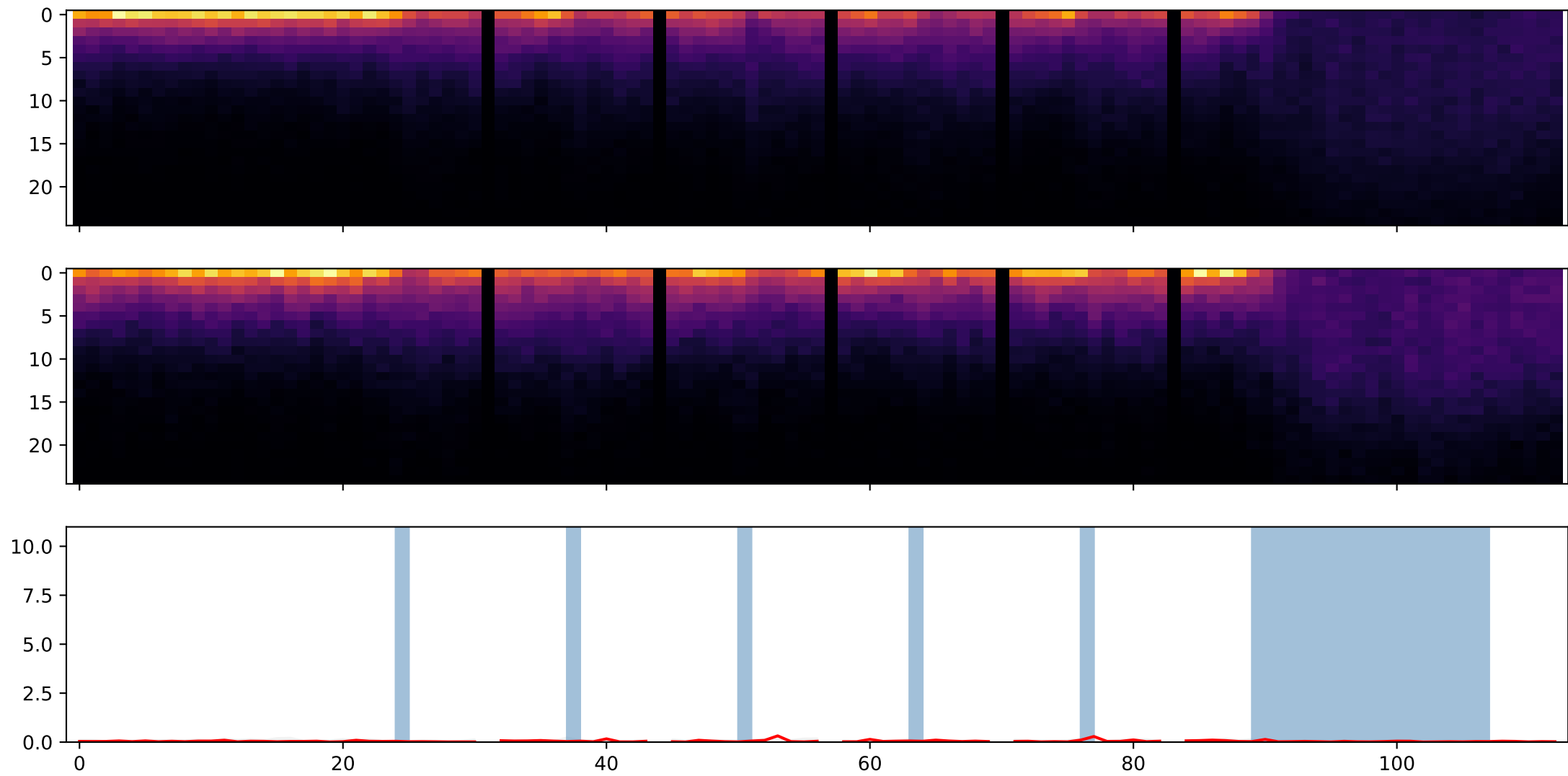
d_relative_to_neck_angular_velocity_head_tip



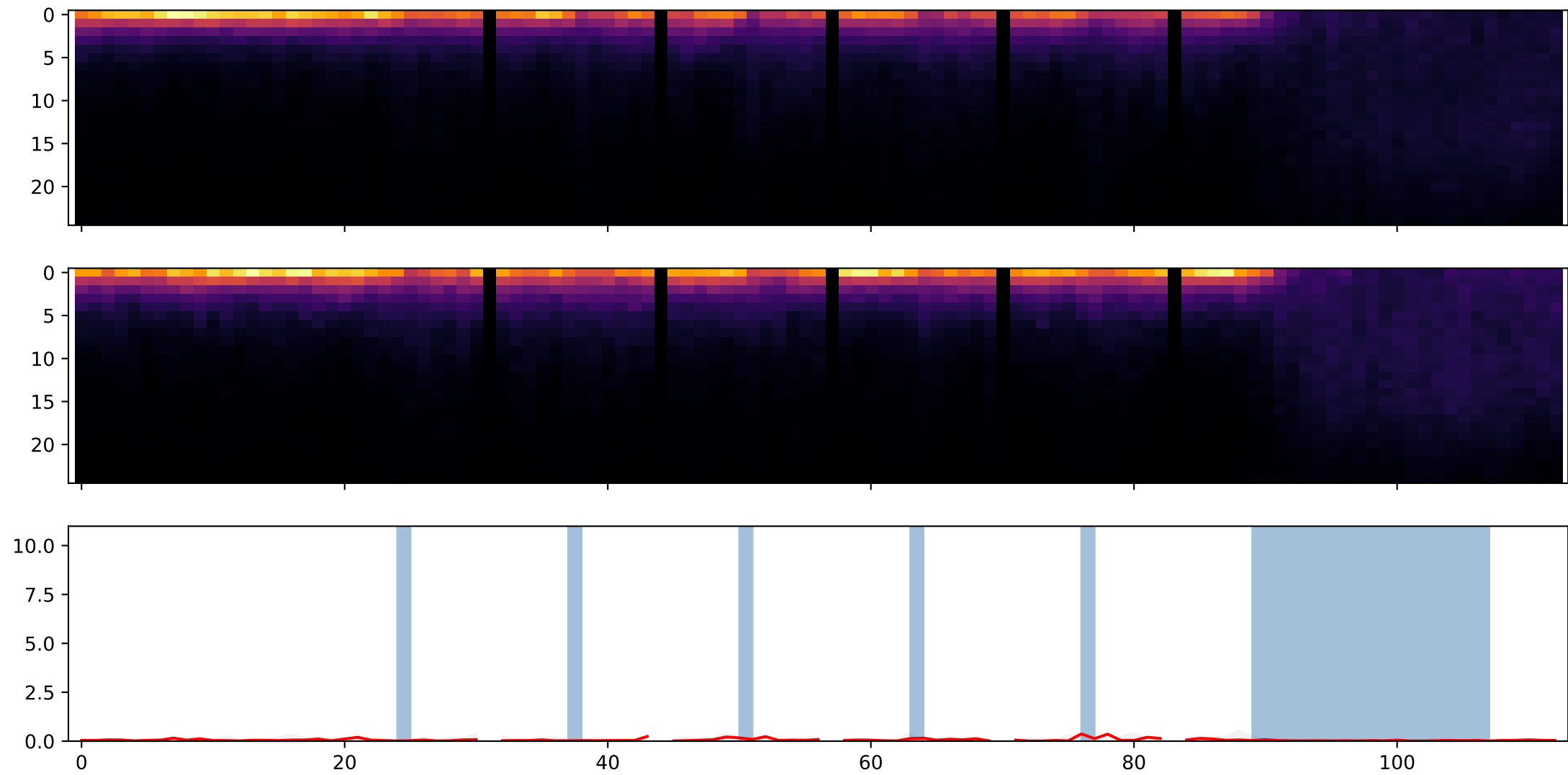
d_major_axis



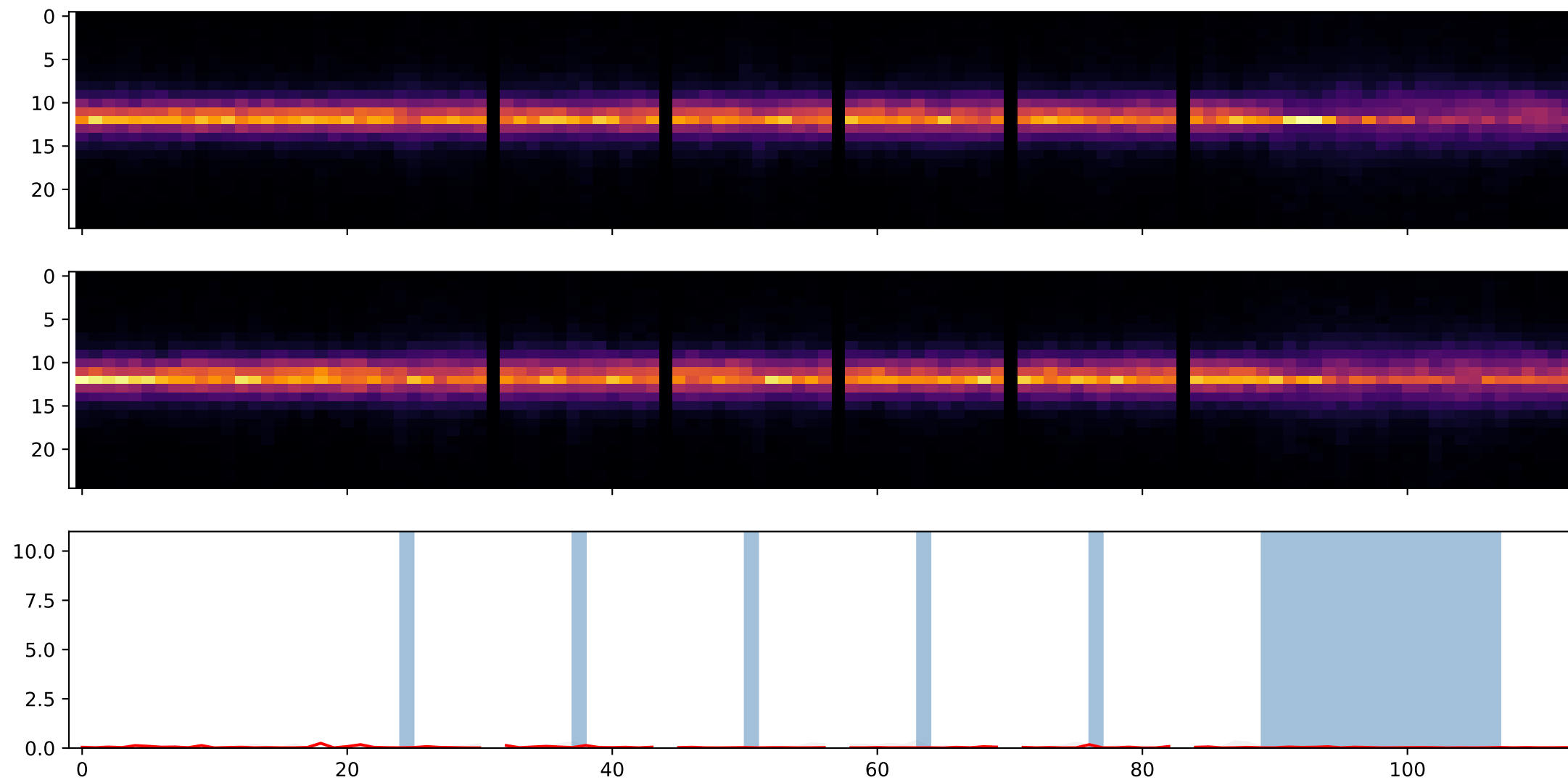
d_curvature_head



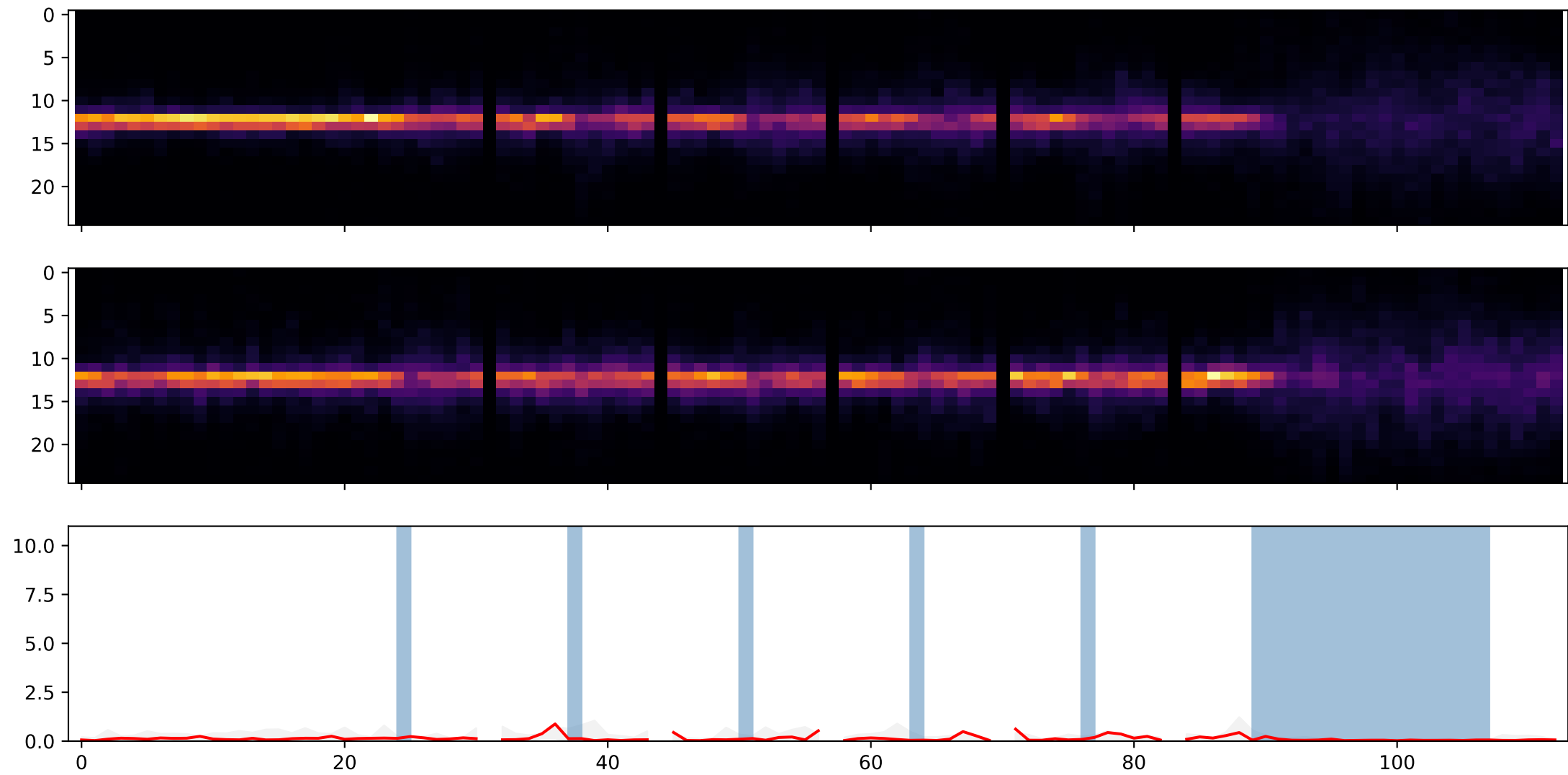
d_curvature_hips



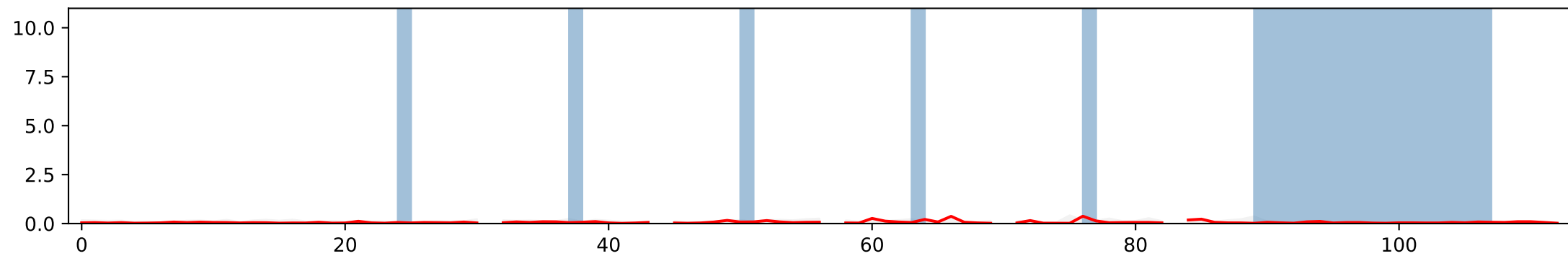
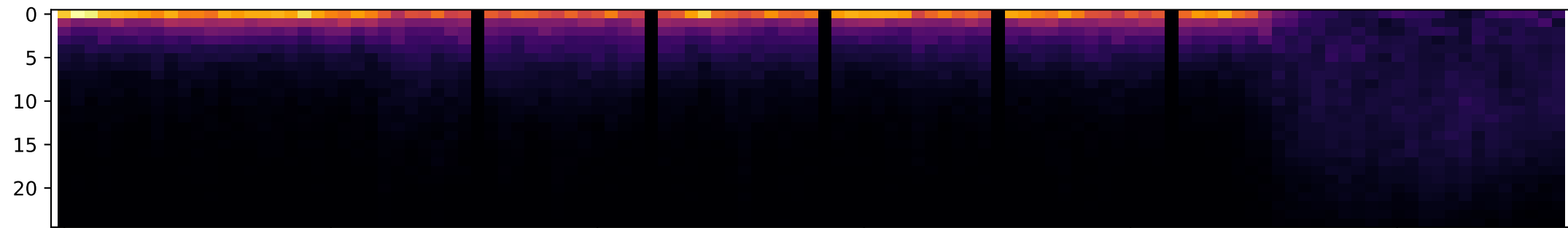
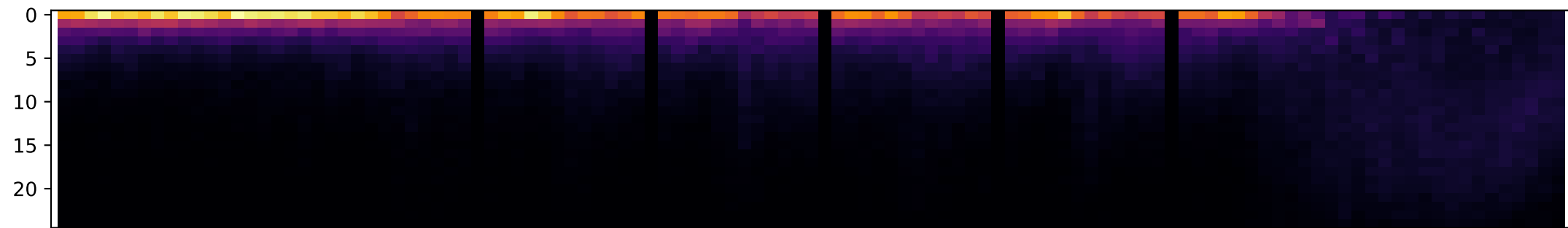
d_speed_head_base



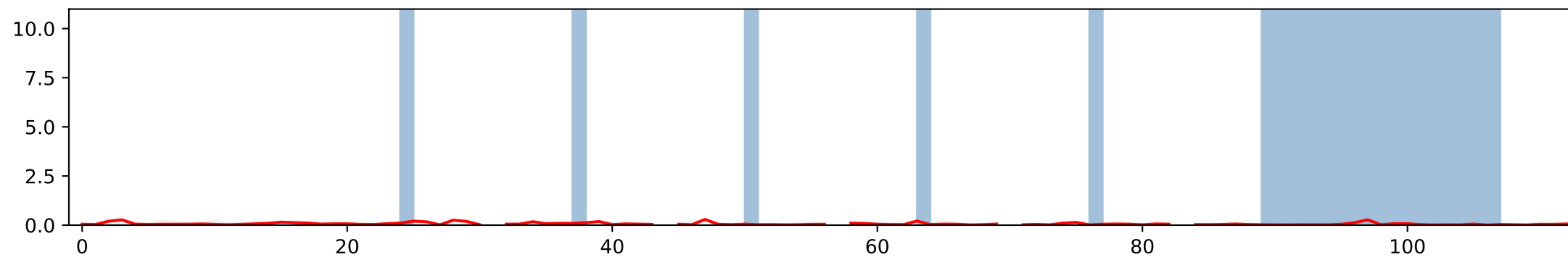
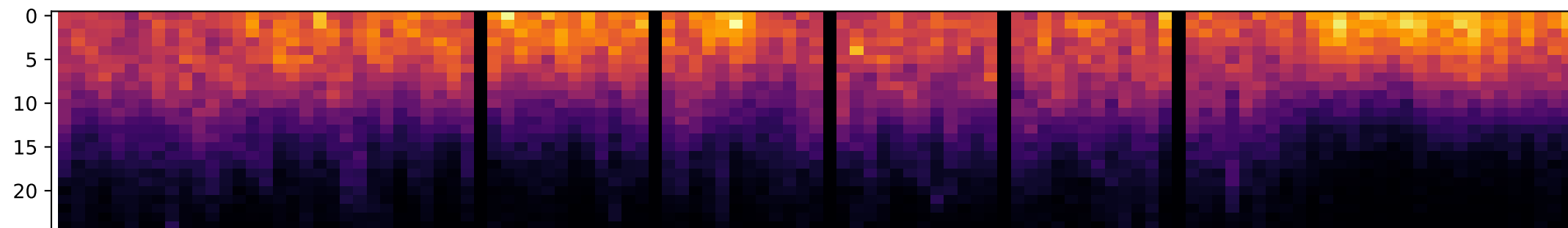
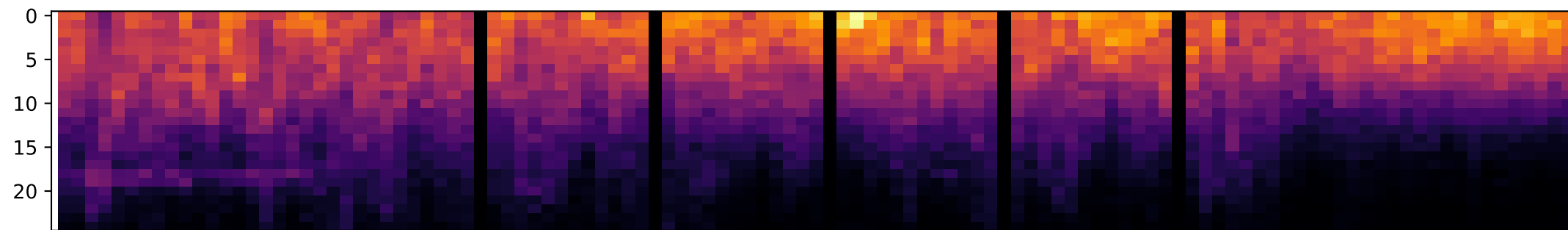
d_orientation_food_edge



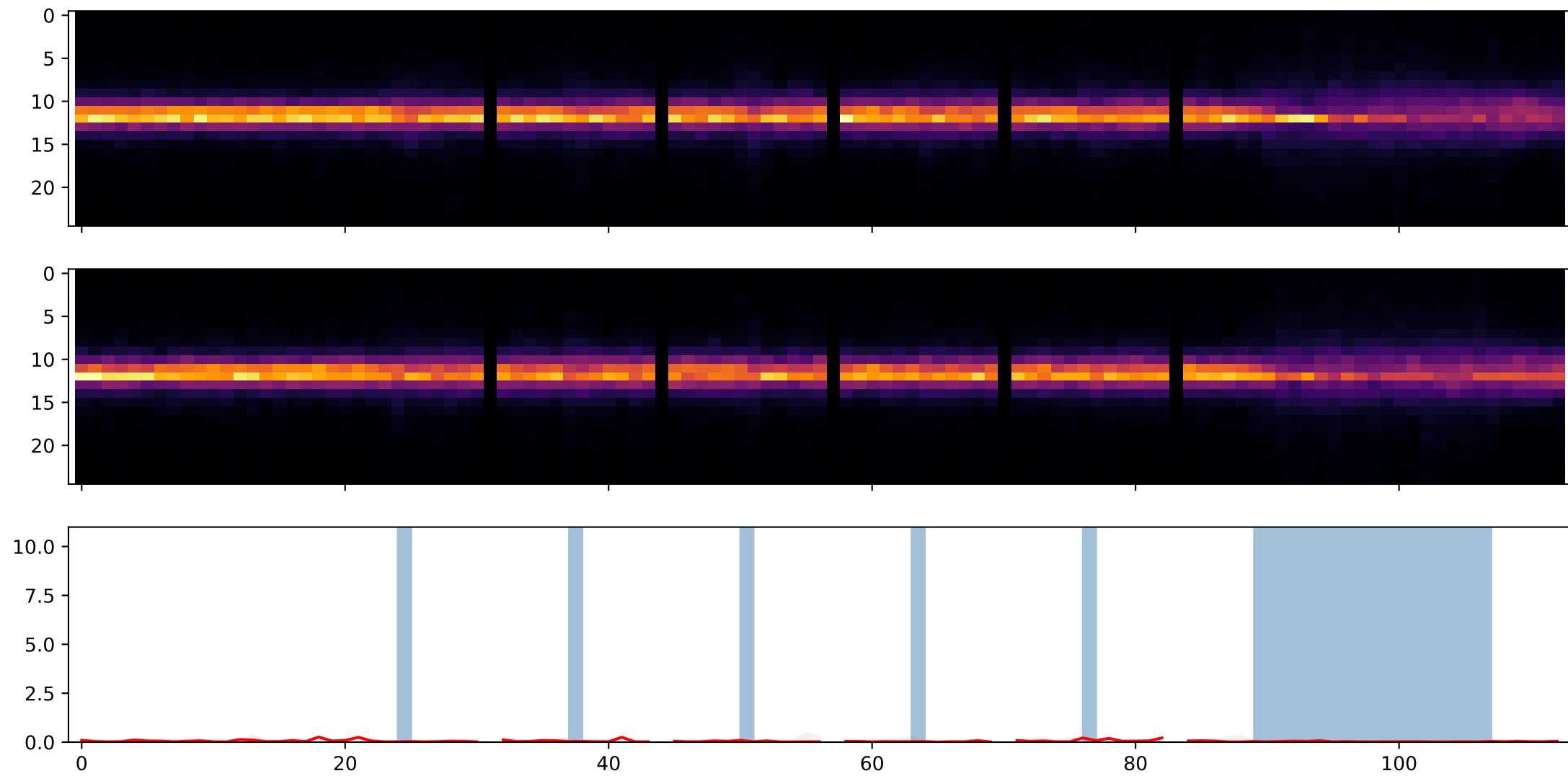
angular_velocity_head_base



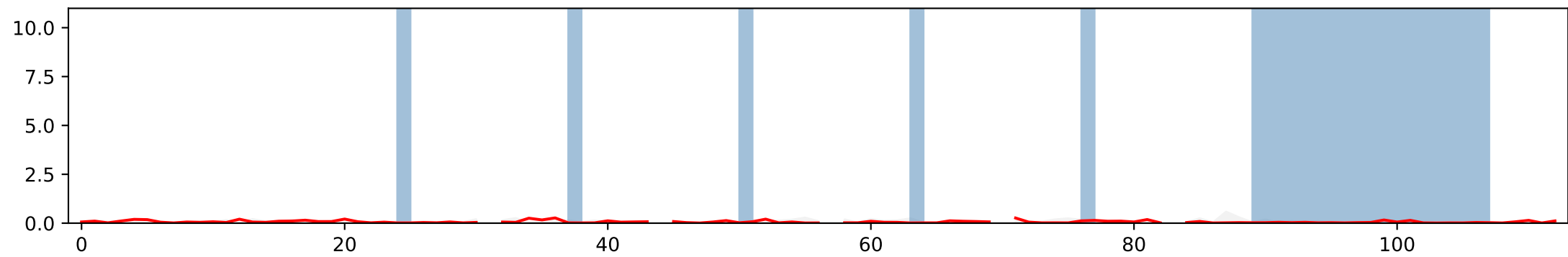
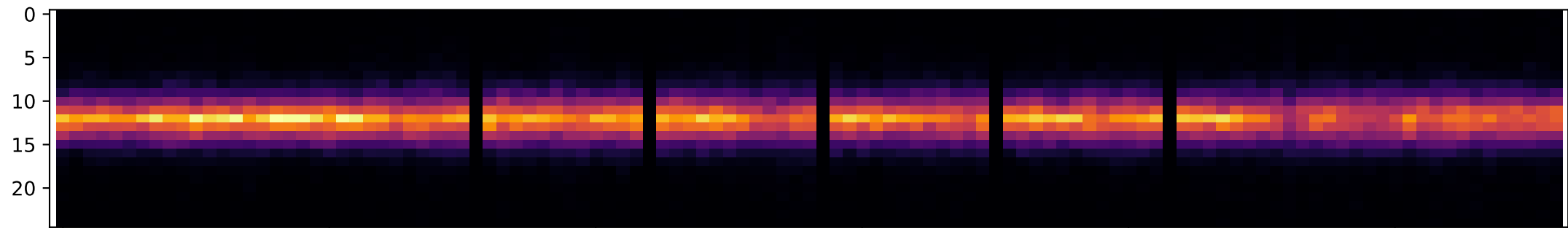
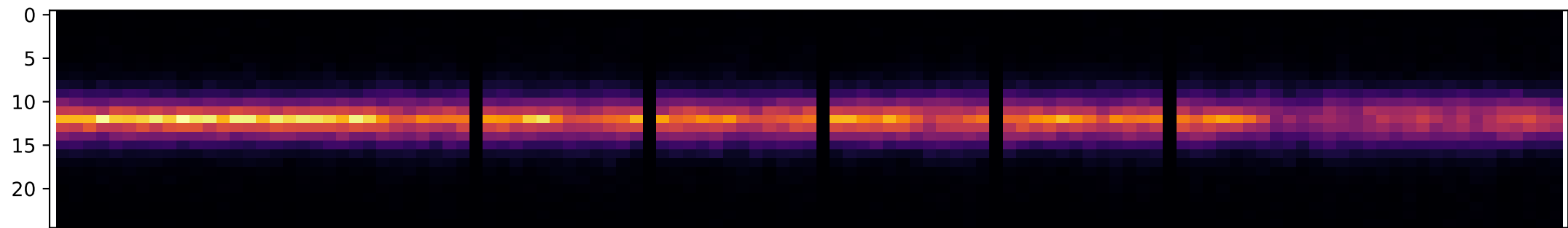
eigen_projection_7



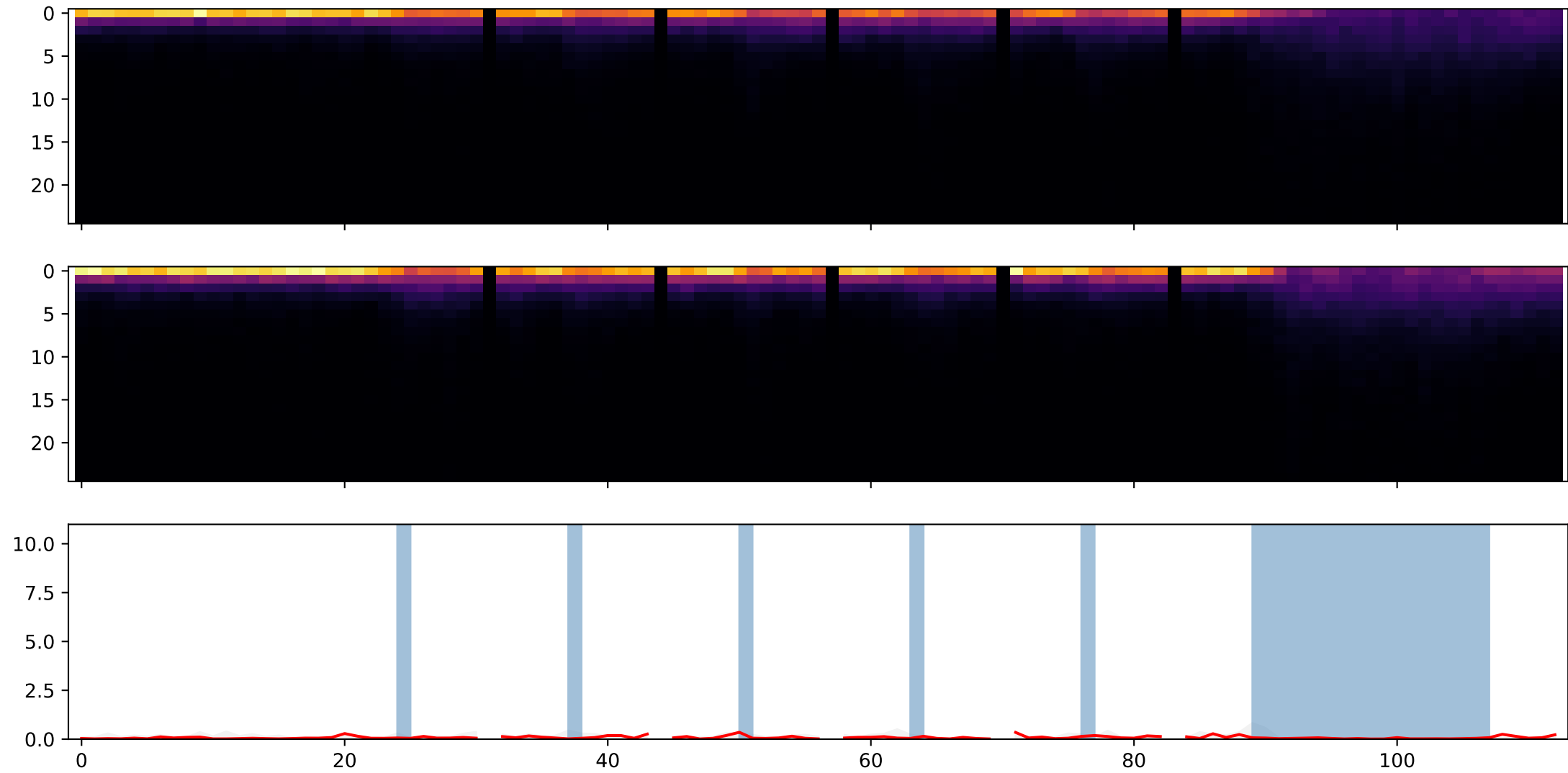
d_speed_midbody



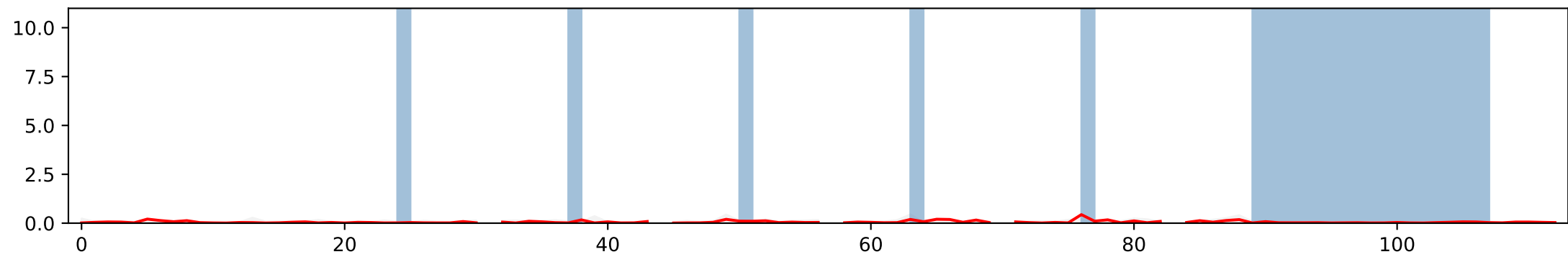
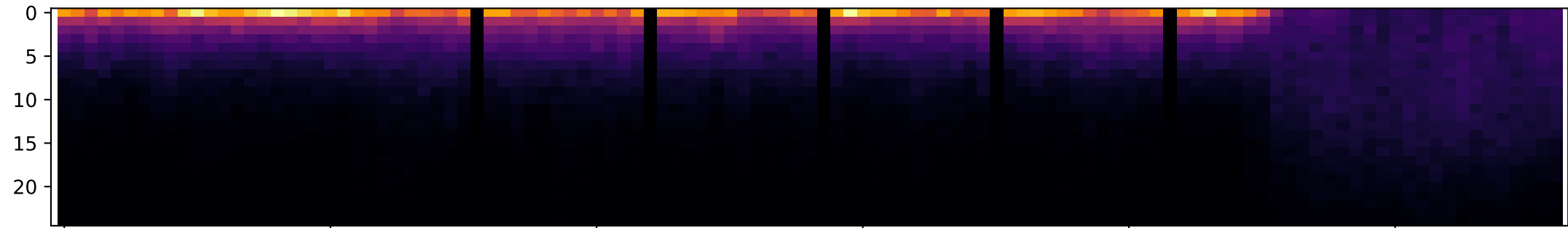
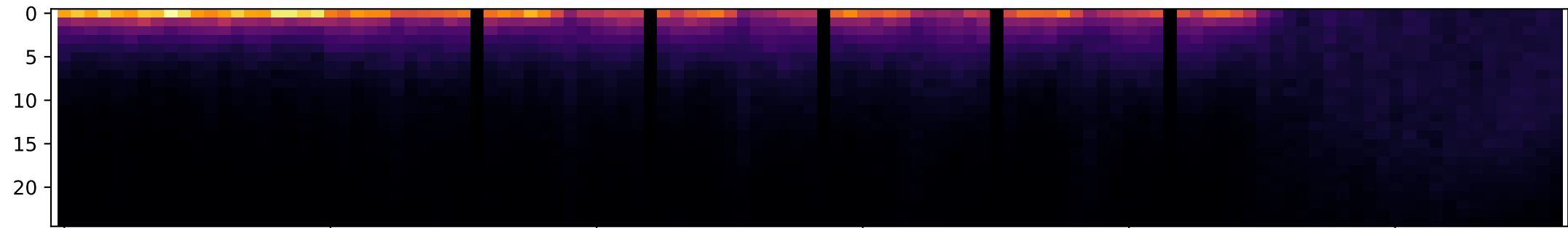
d_length



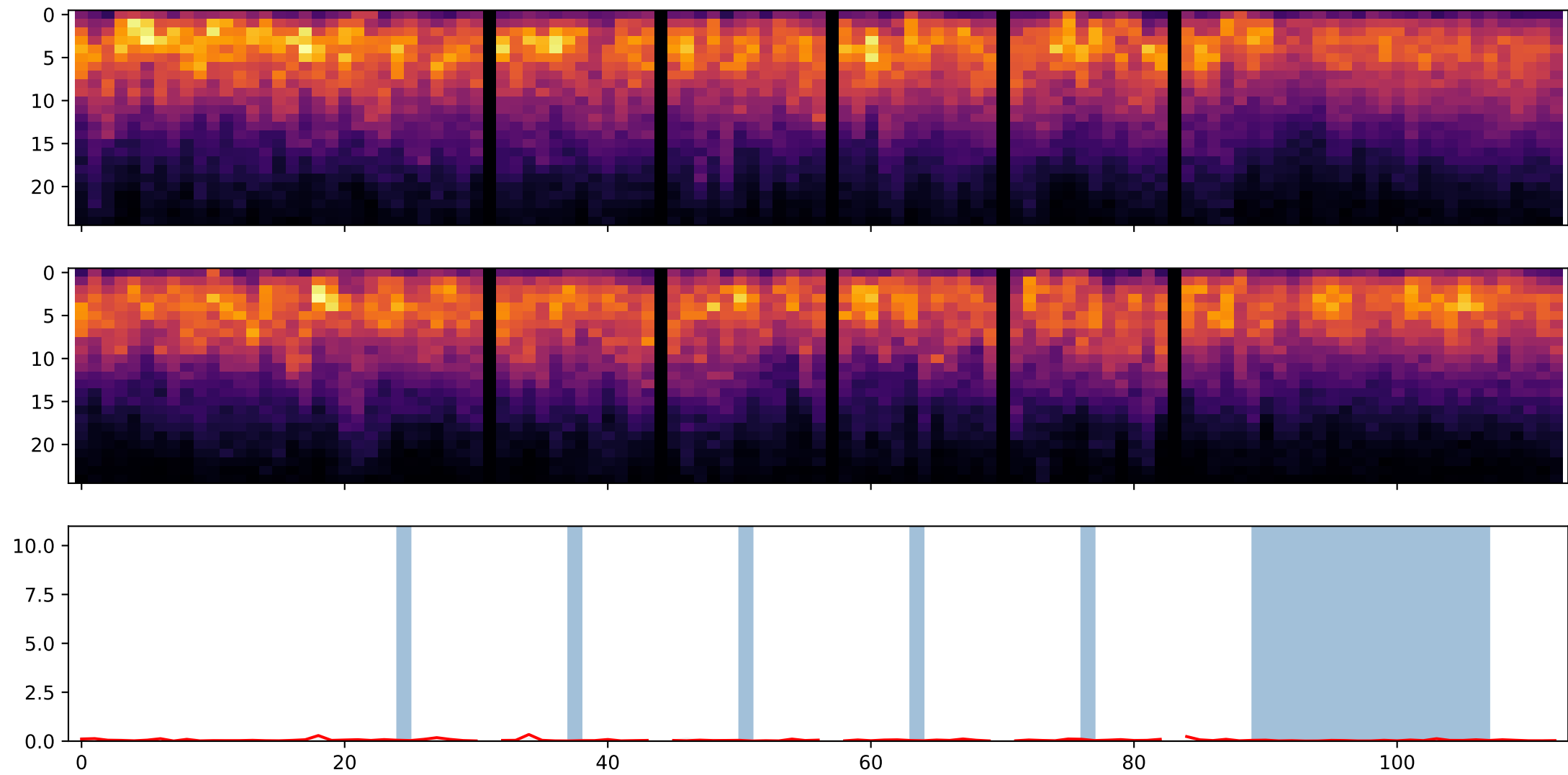
d_angular_velocity



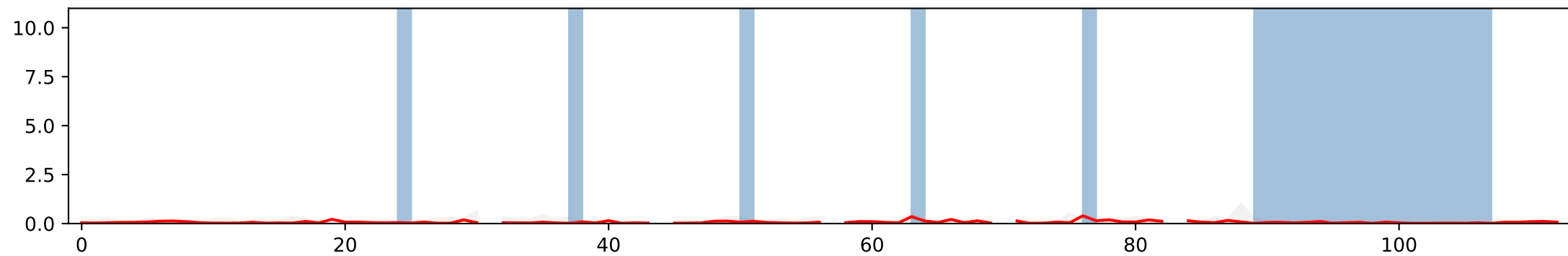
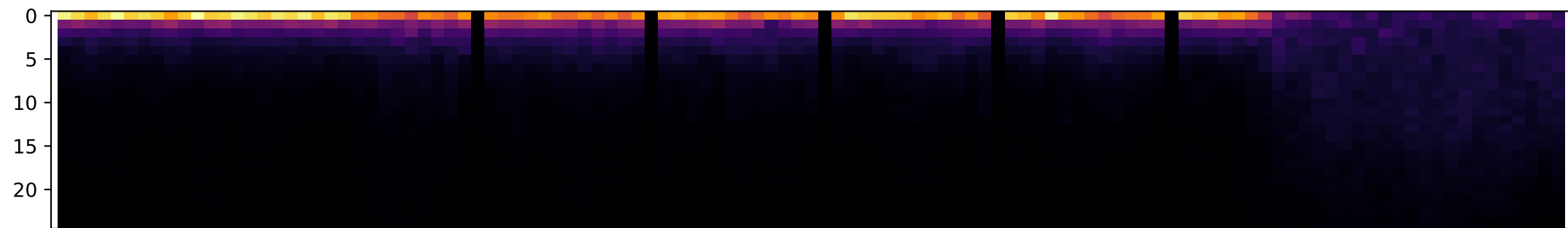
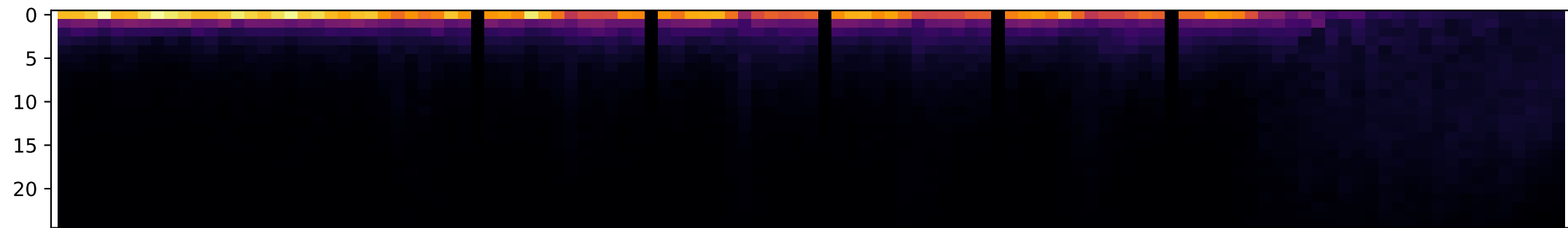
d_curvature_tail



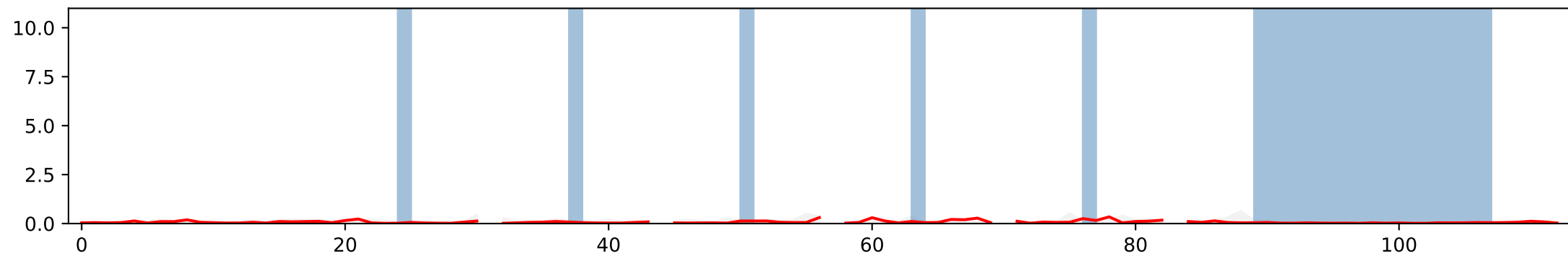
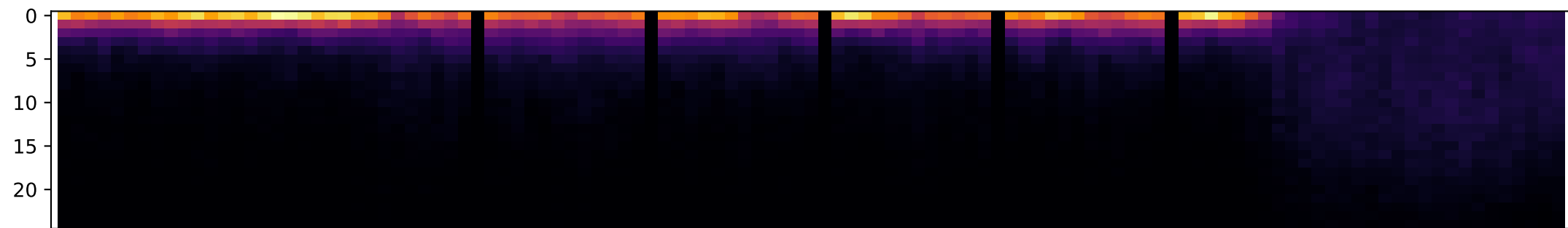
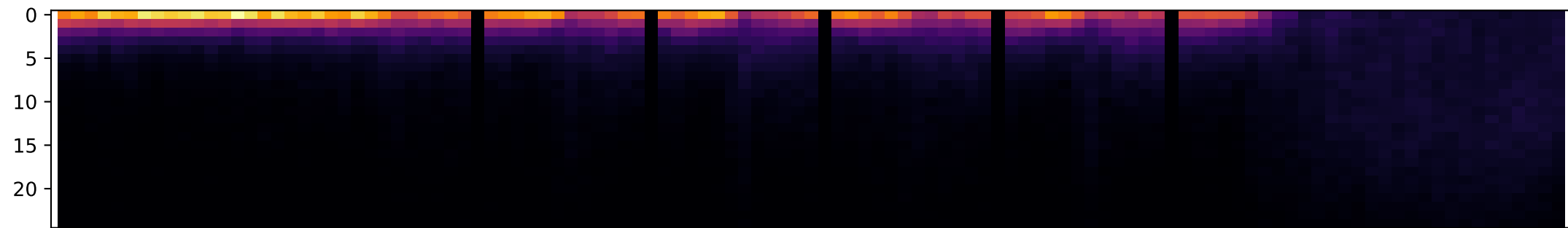
curvature_std_head



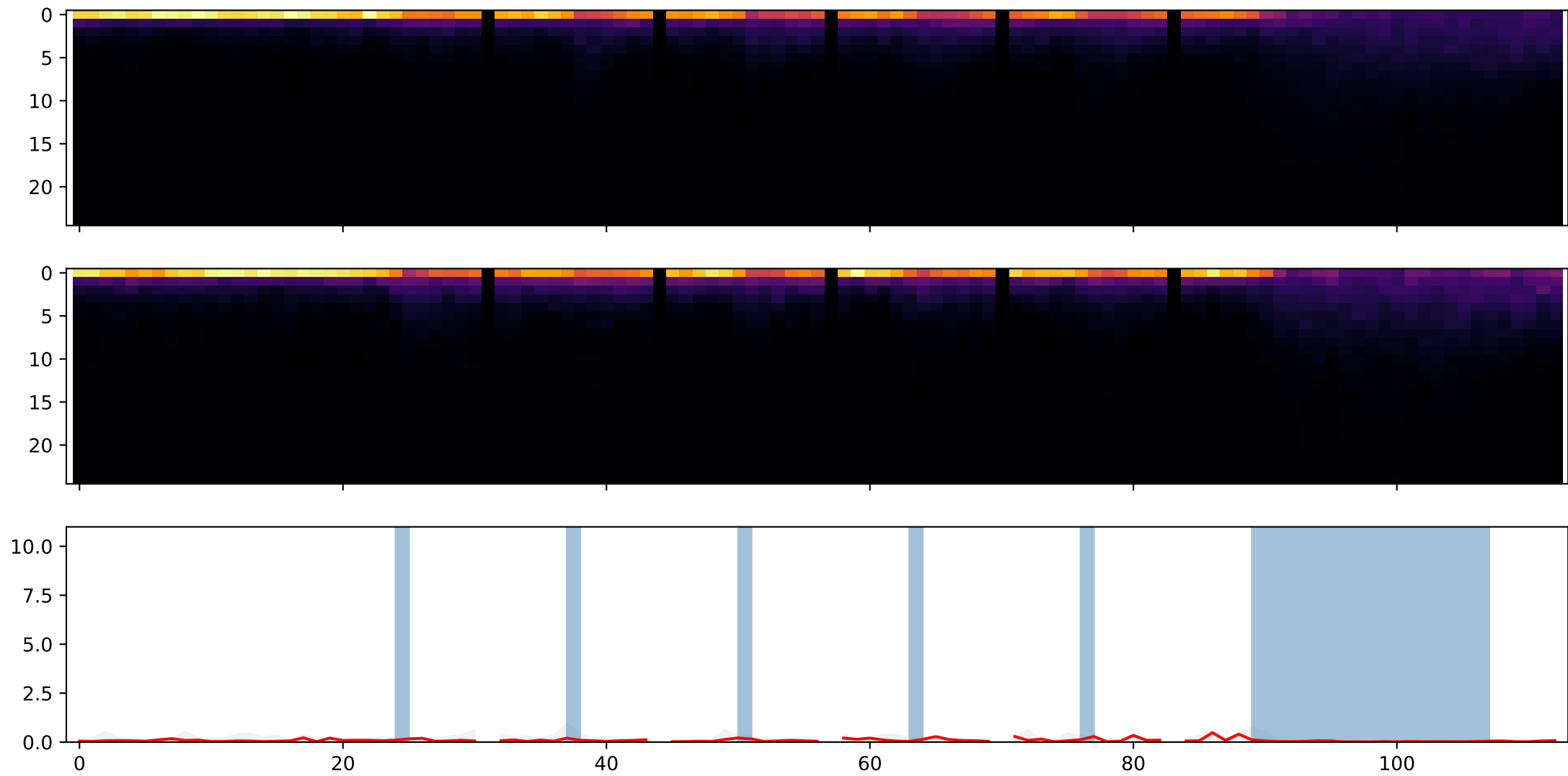
angular_velocity_tail_base



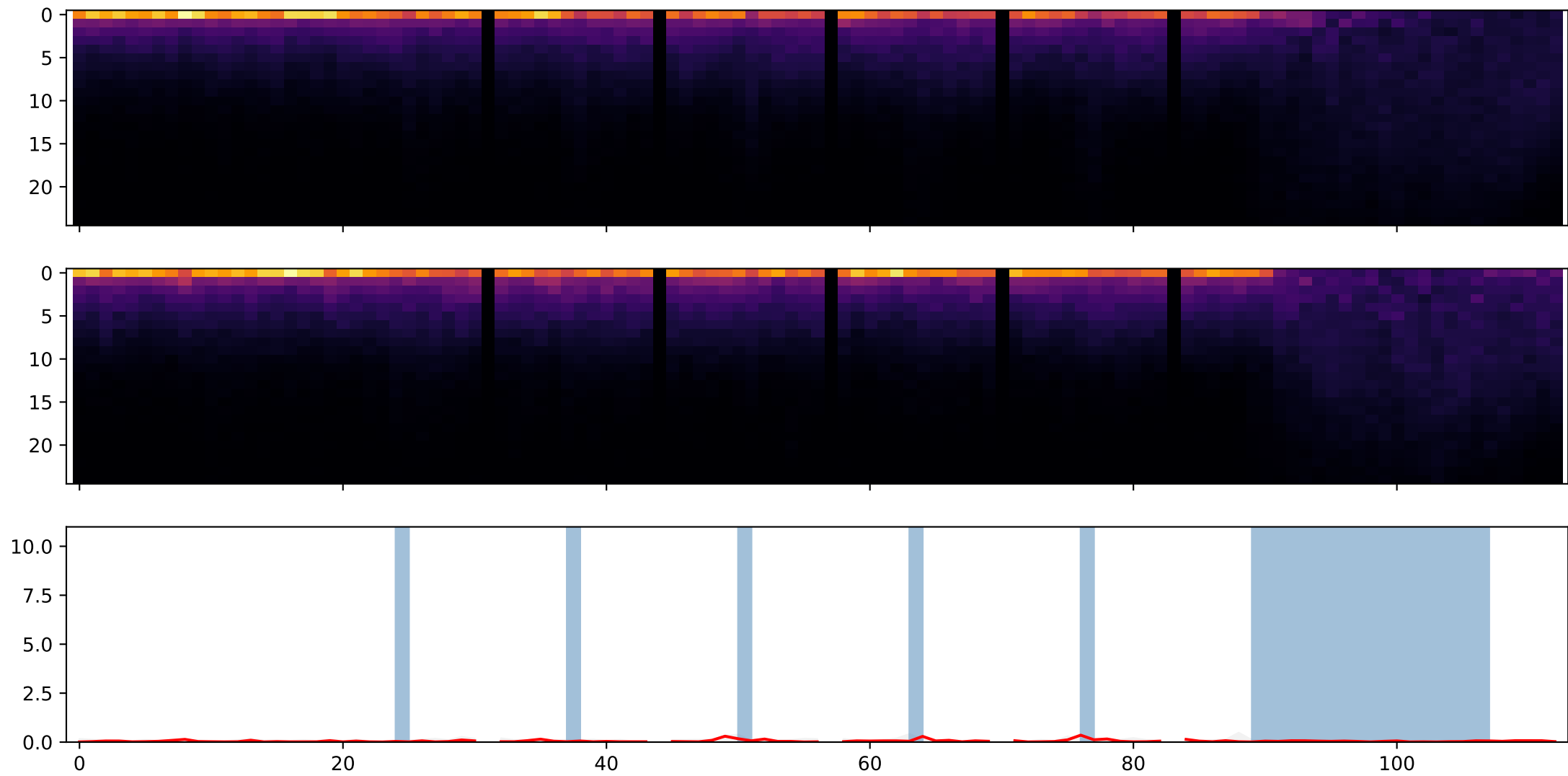
d_curvature_std_midbody



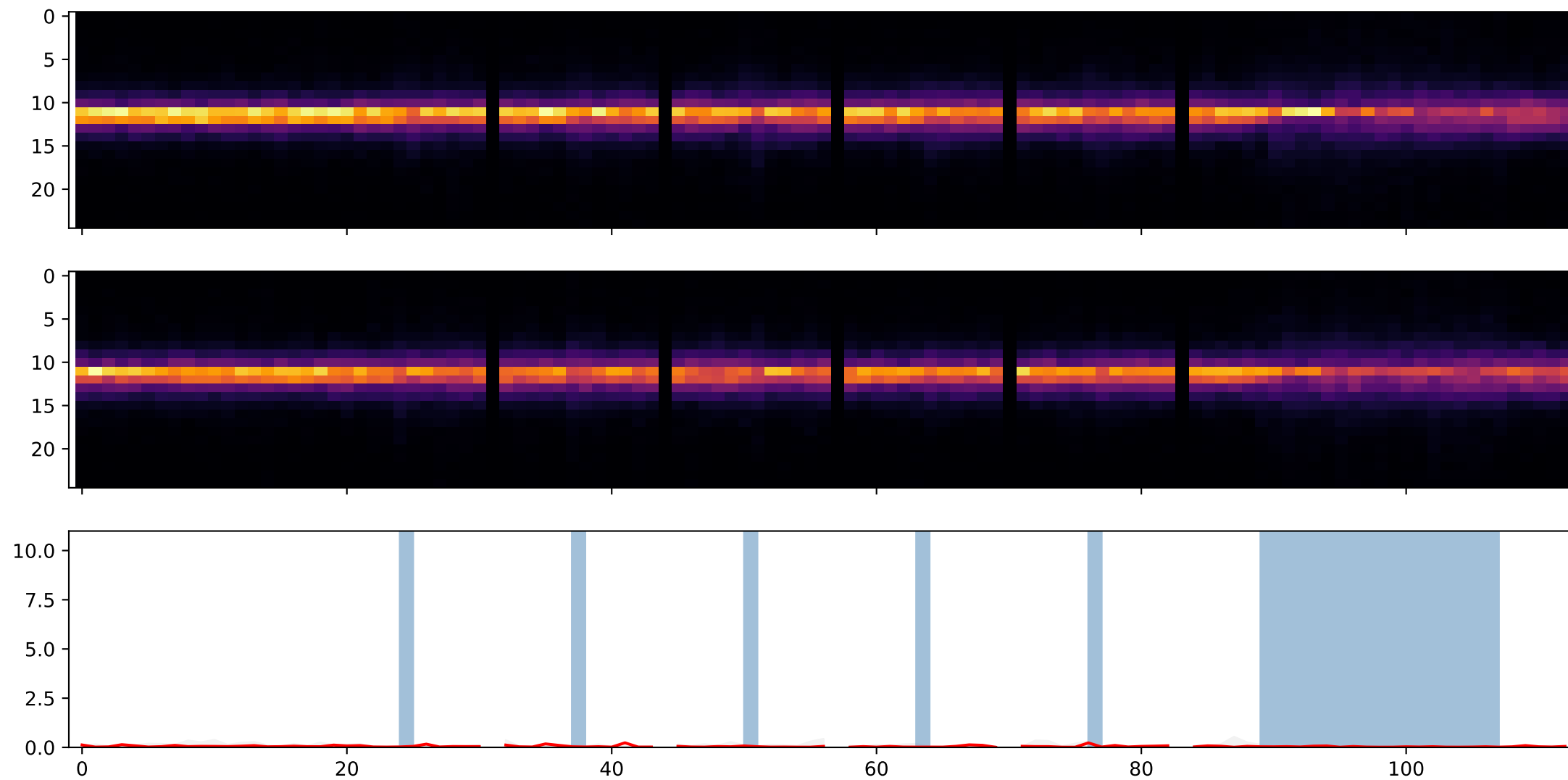
angular_velocity



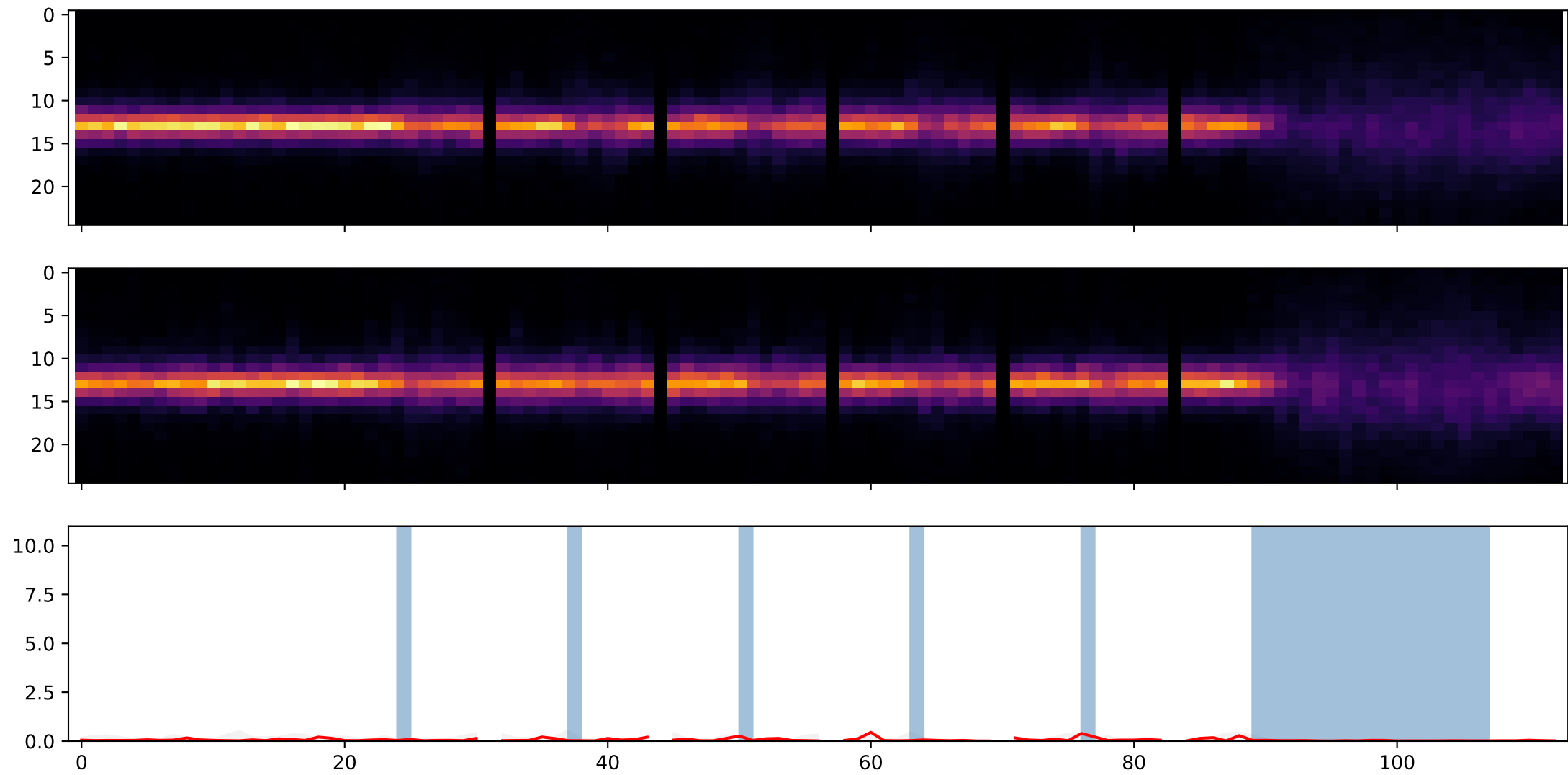
angular_velocity_tail_tip



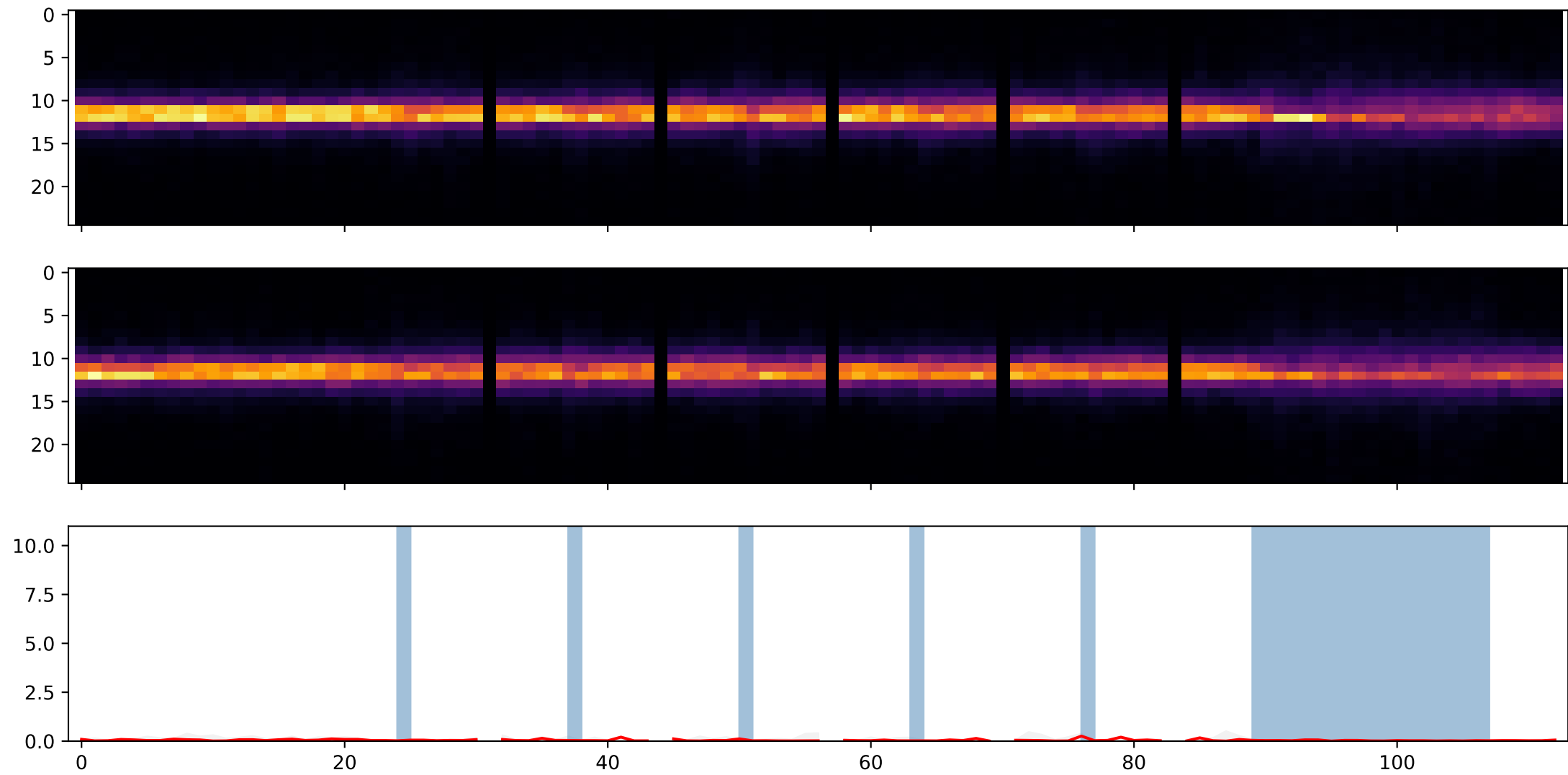
d_speed_tail_base



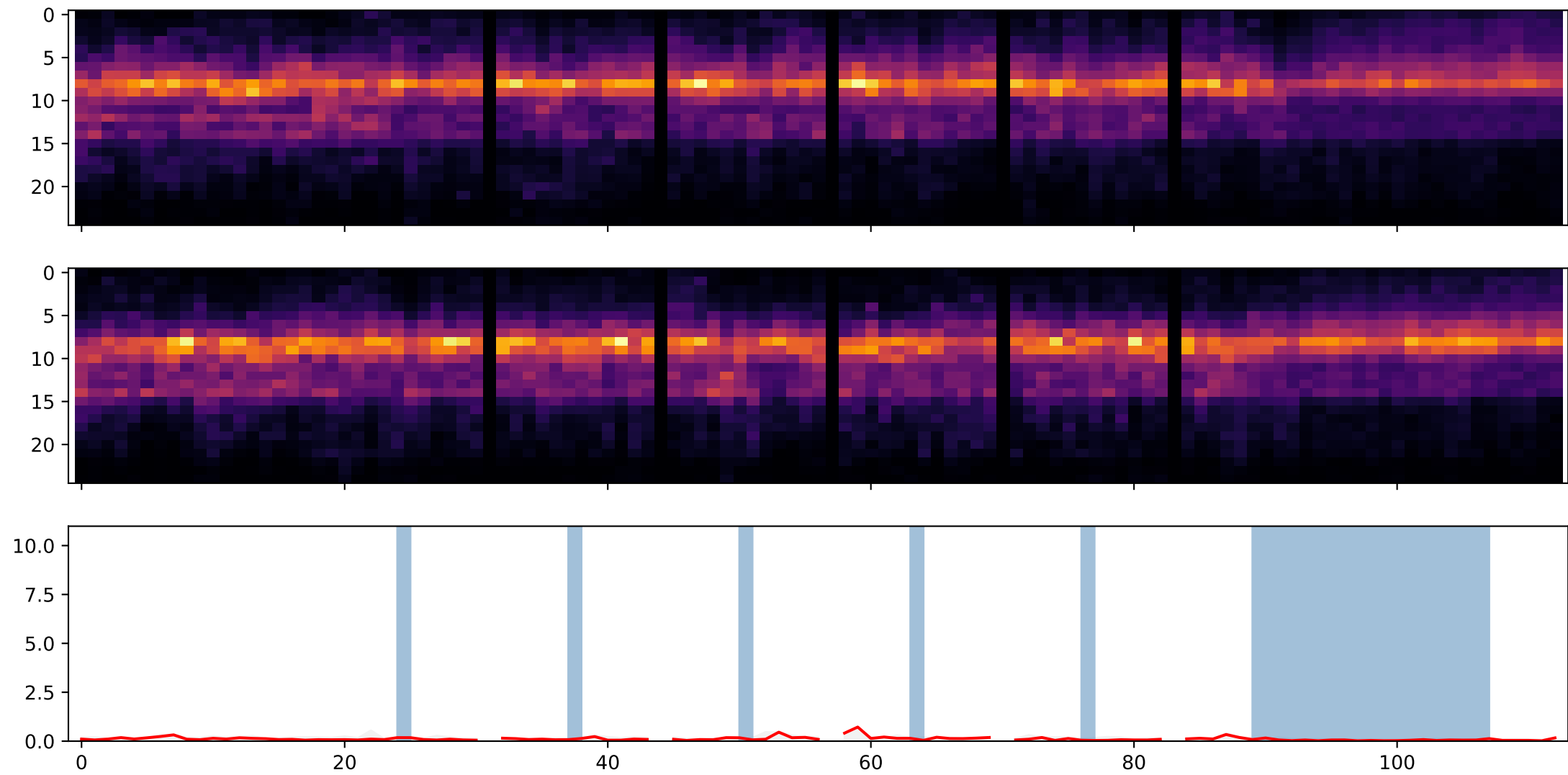
relative_to_body_radial_velocity_neck



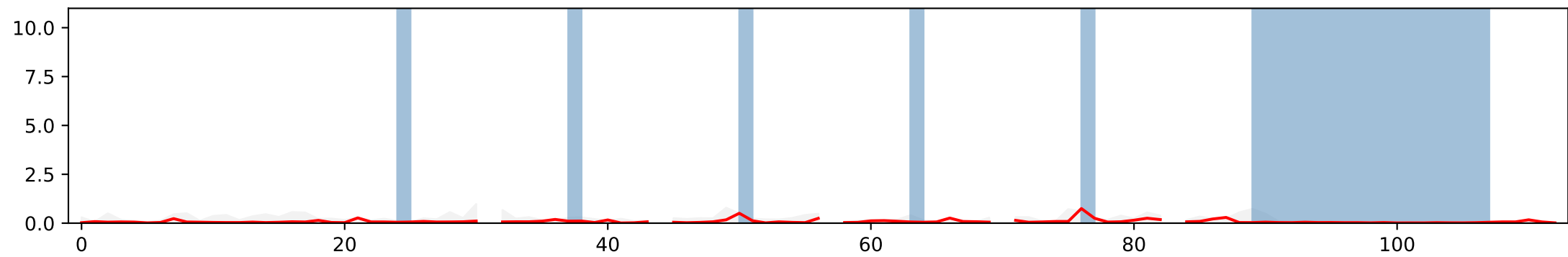
d_speed_hips



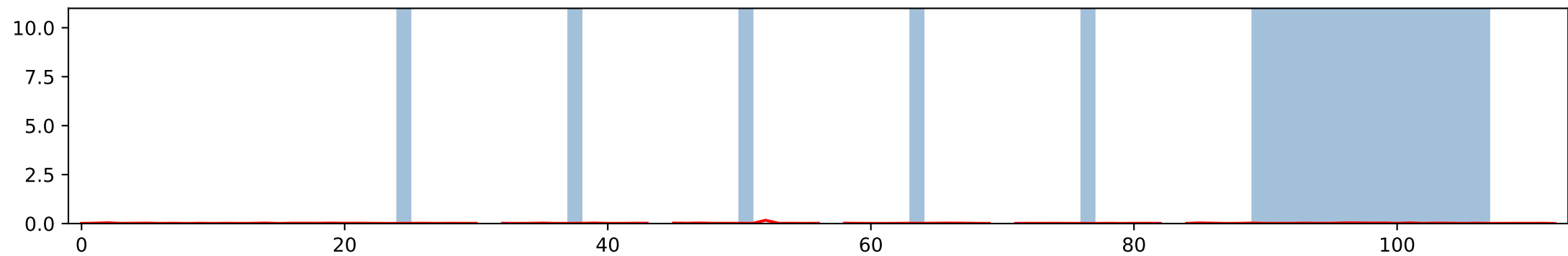
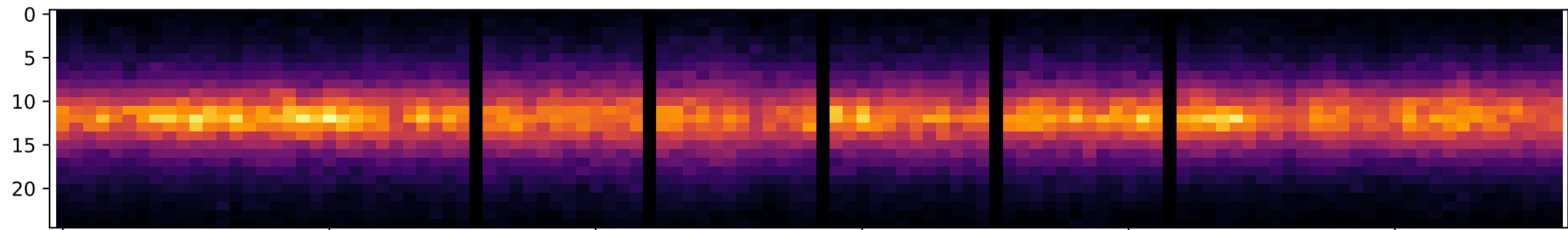
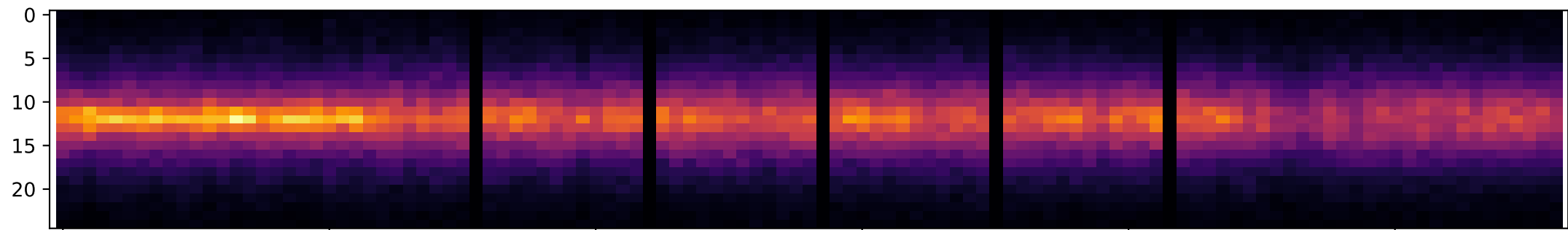
width_head_base



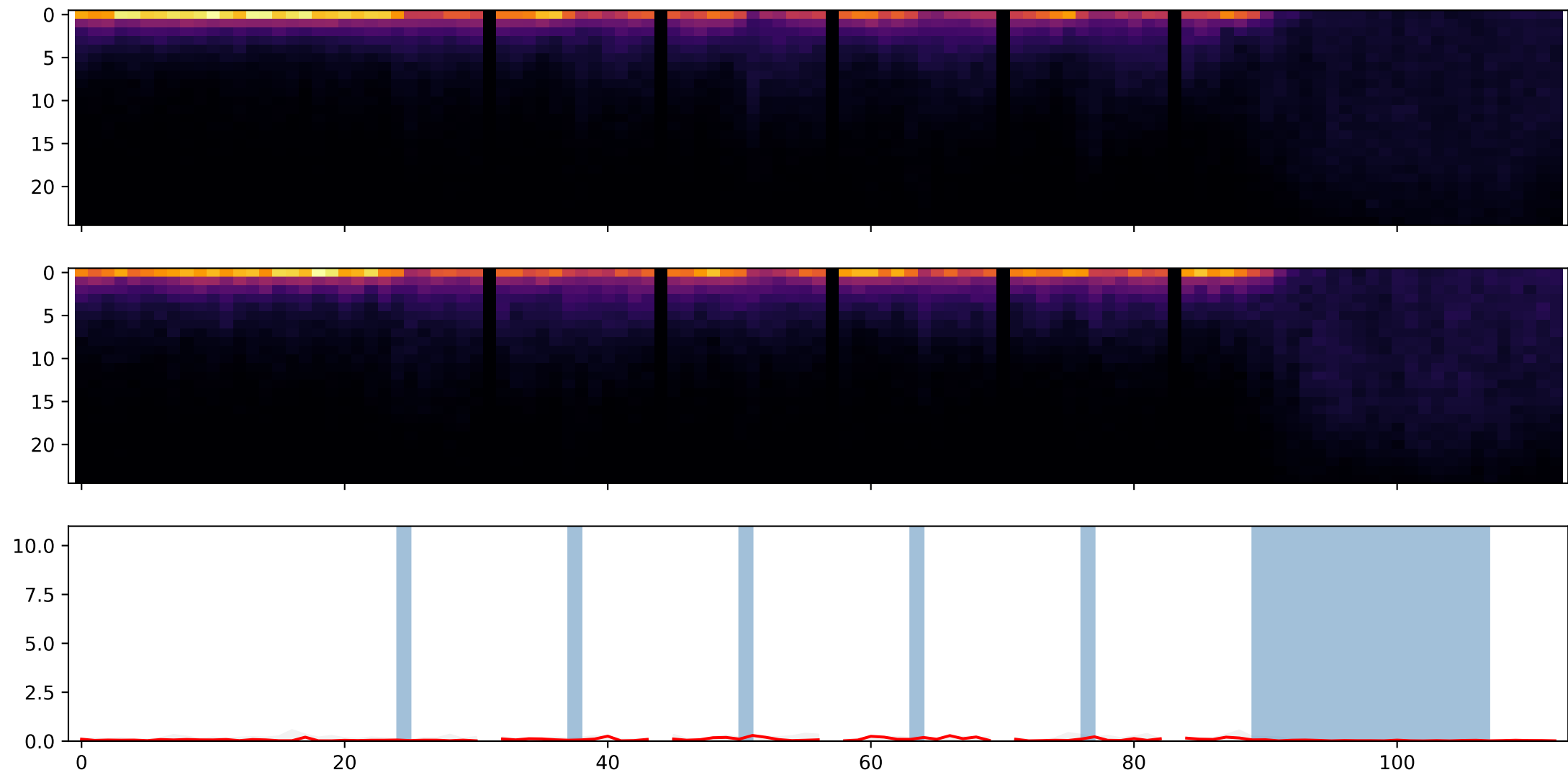
angular_velocity_midbody



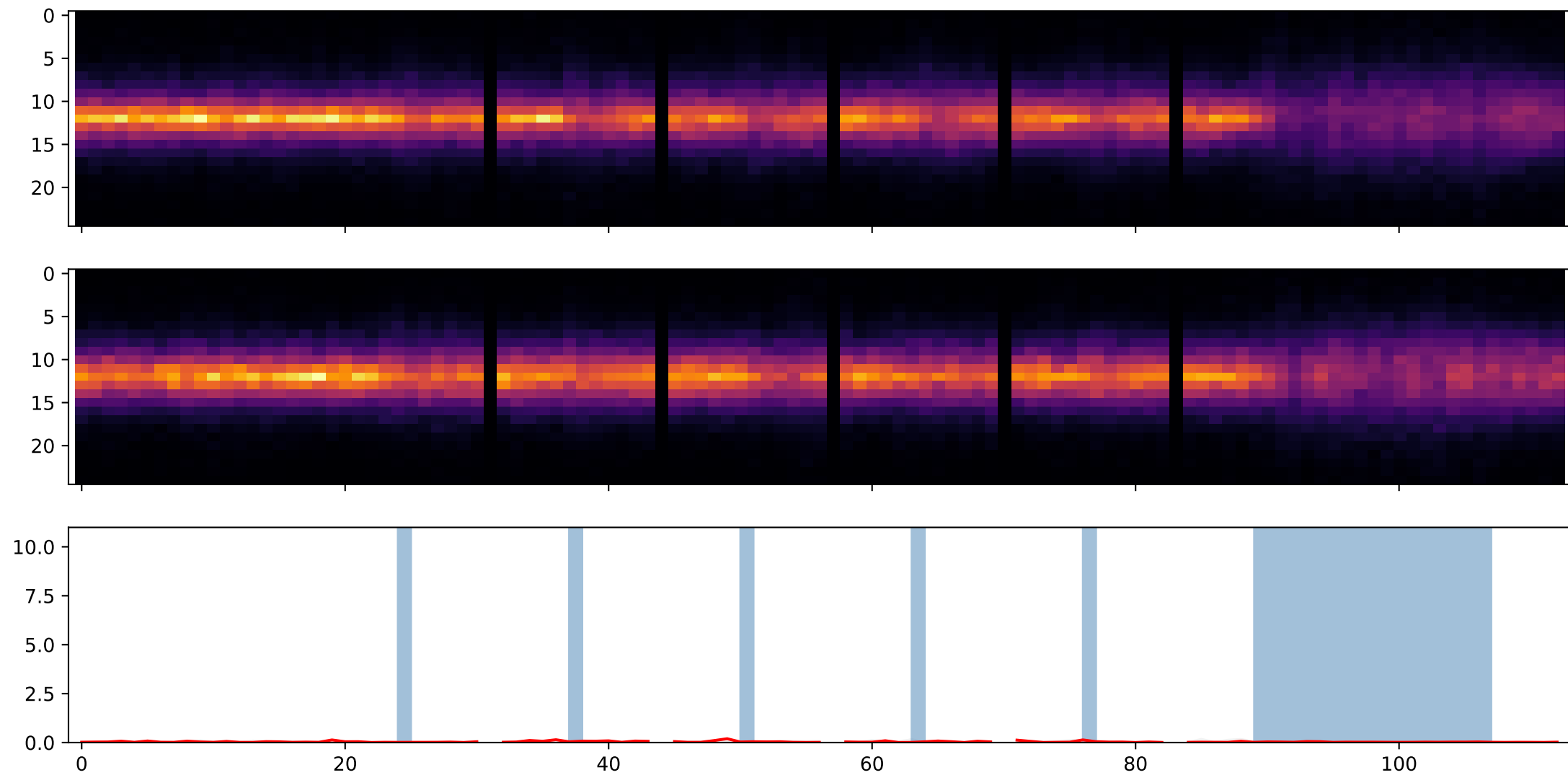
d_area



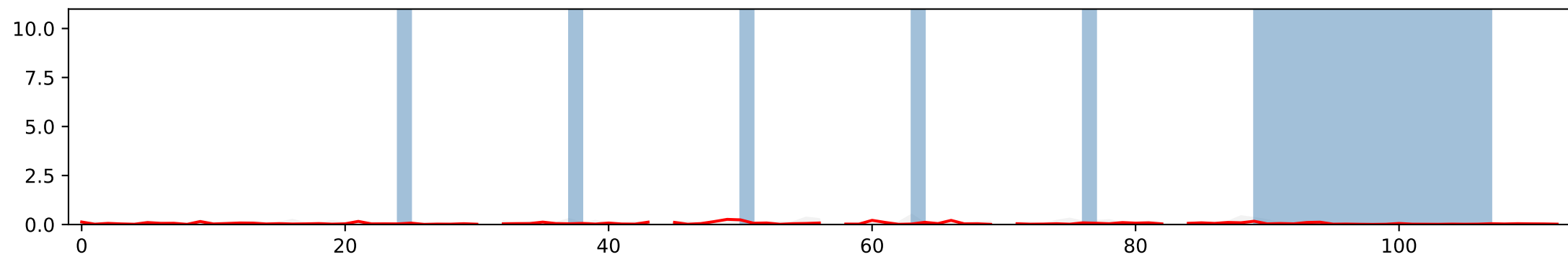
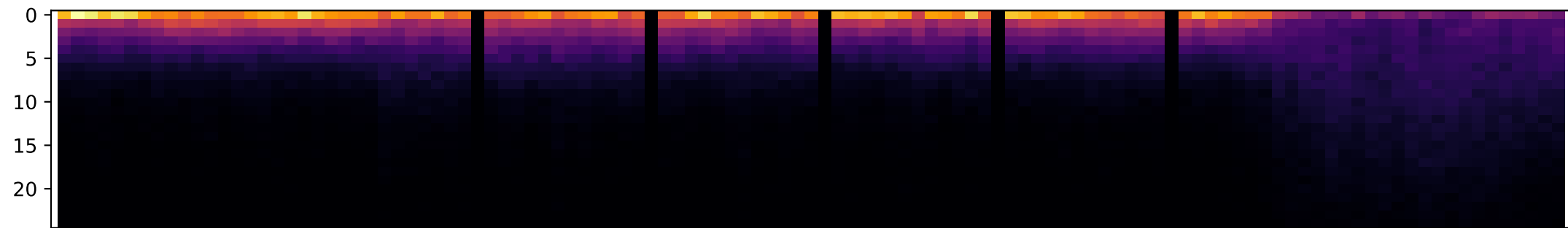
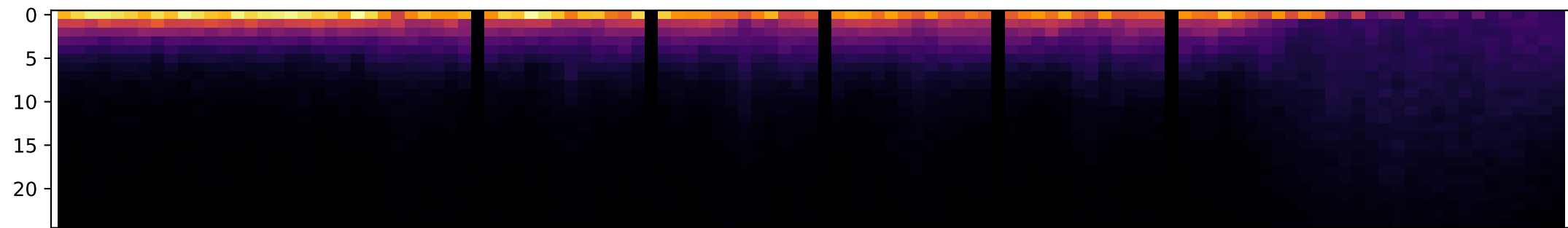
relative_to_neck_angular_velocity_head_tip



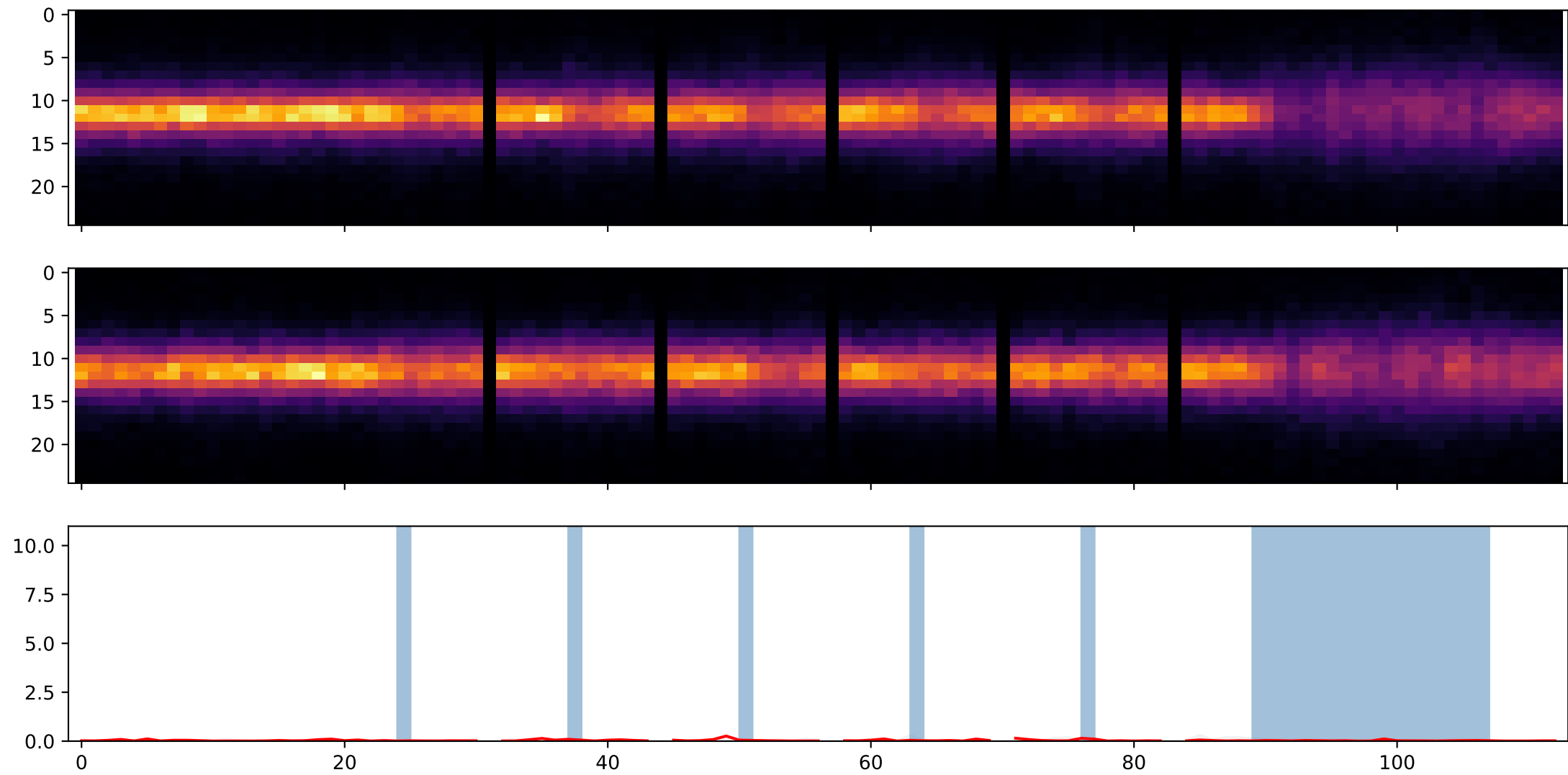
relative_to_tail_base_radial_velocity_tail_tip



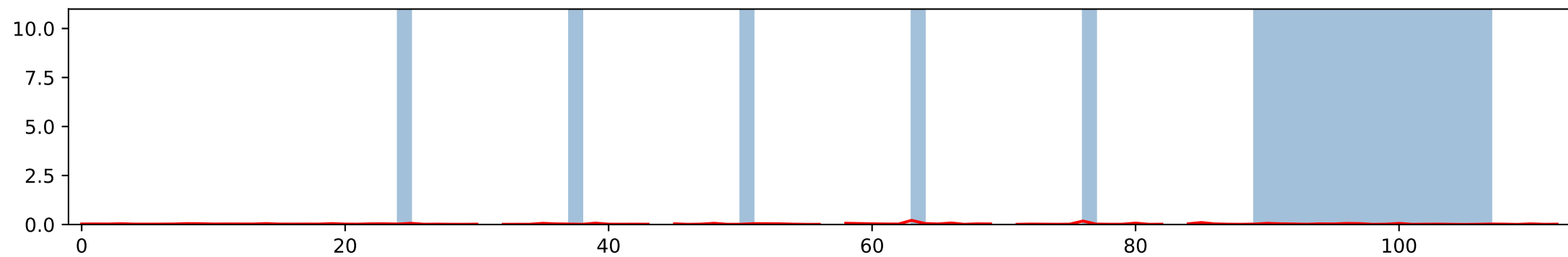
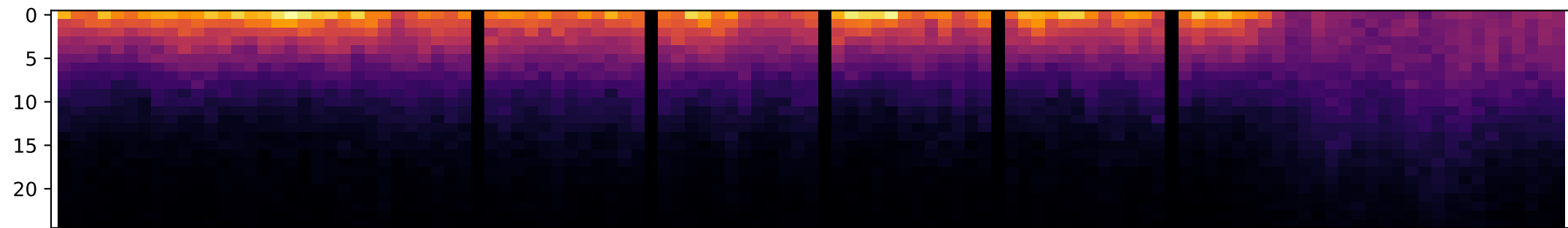
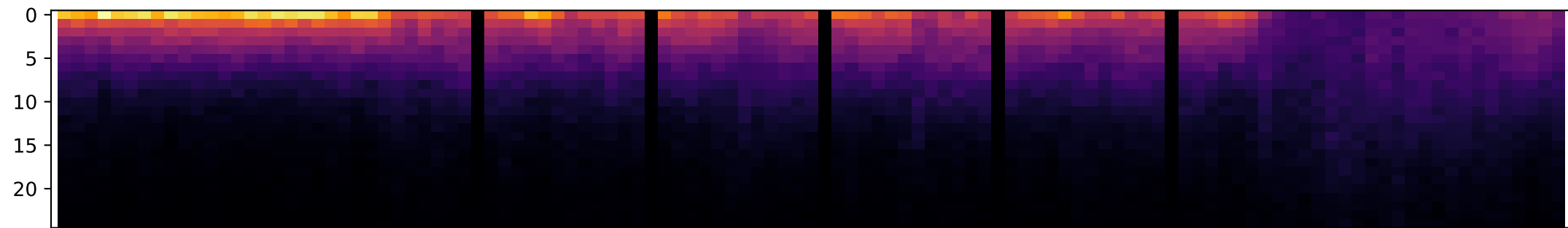
d_angular_velocity_head_base



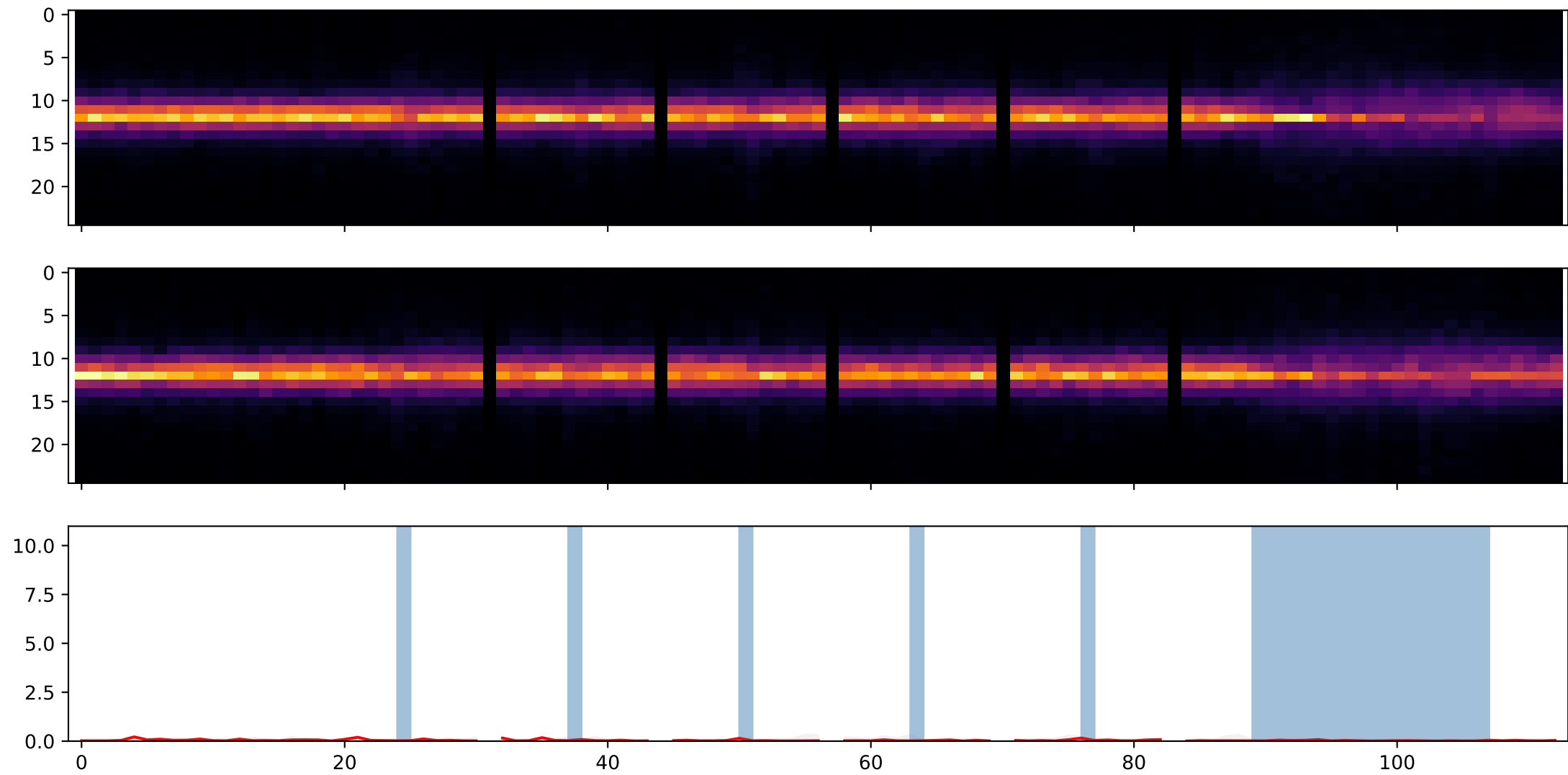
d_relative_to_tail_base_radial_velocity_tail_tip



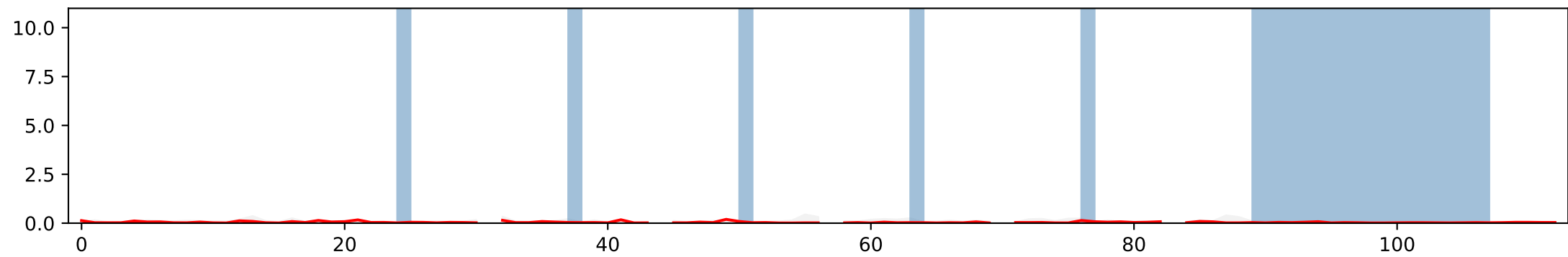
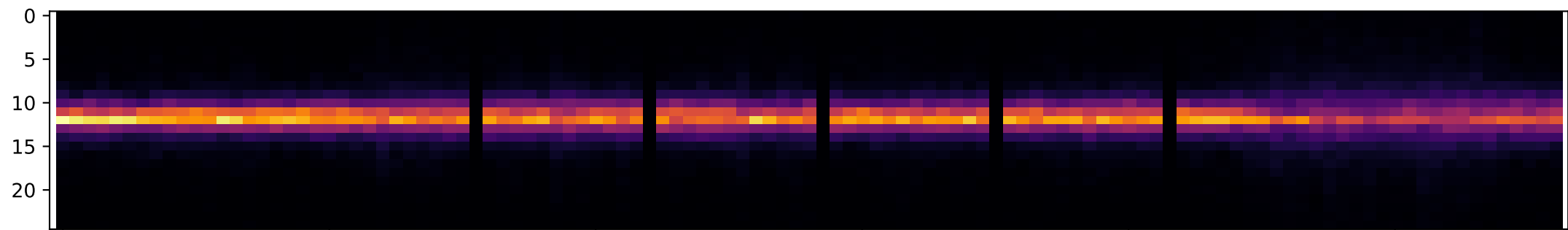
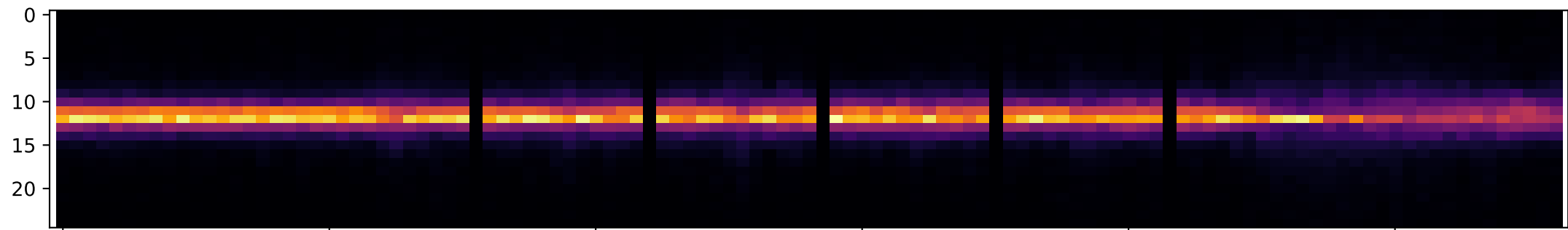
d_eigen_projection_5



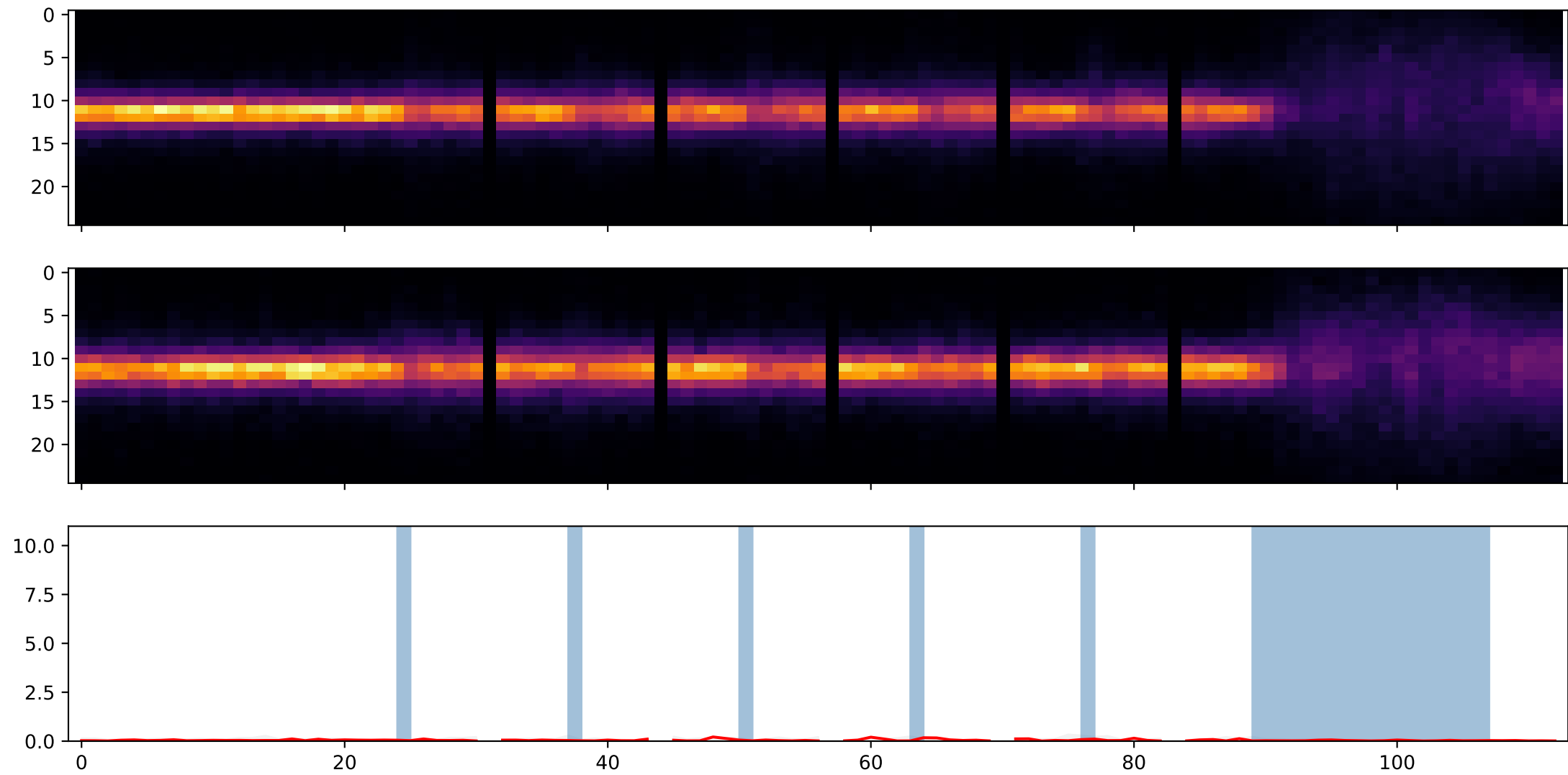
d_speed_neck



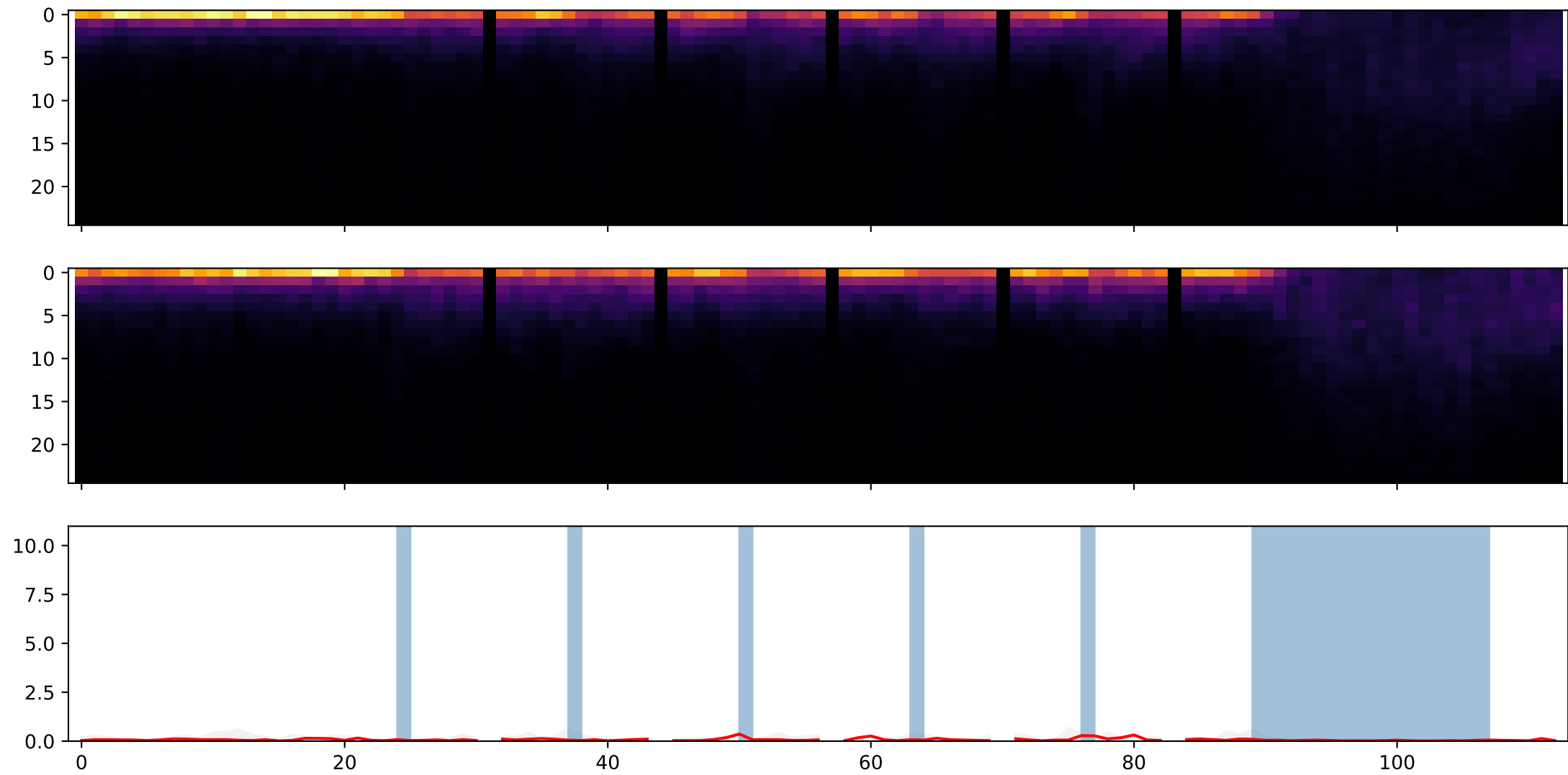
d_speed



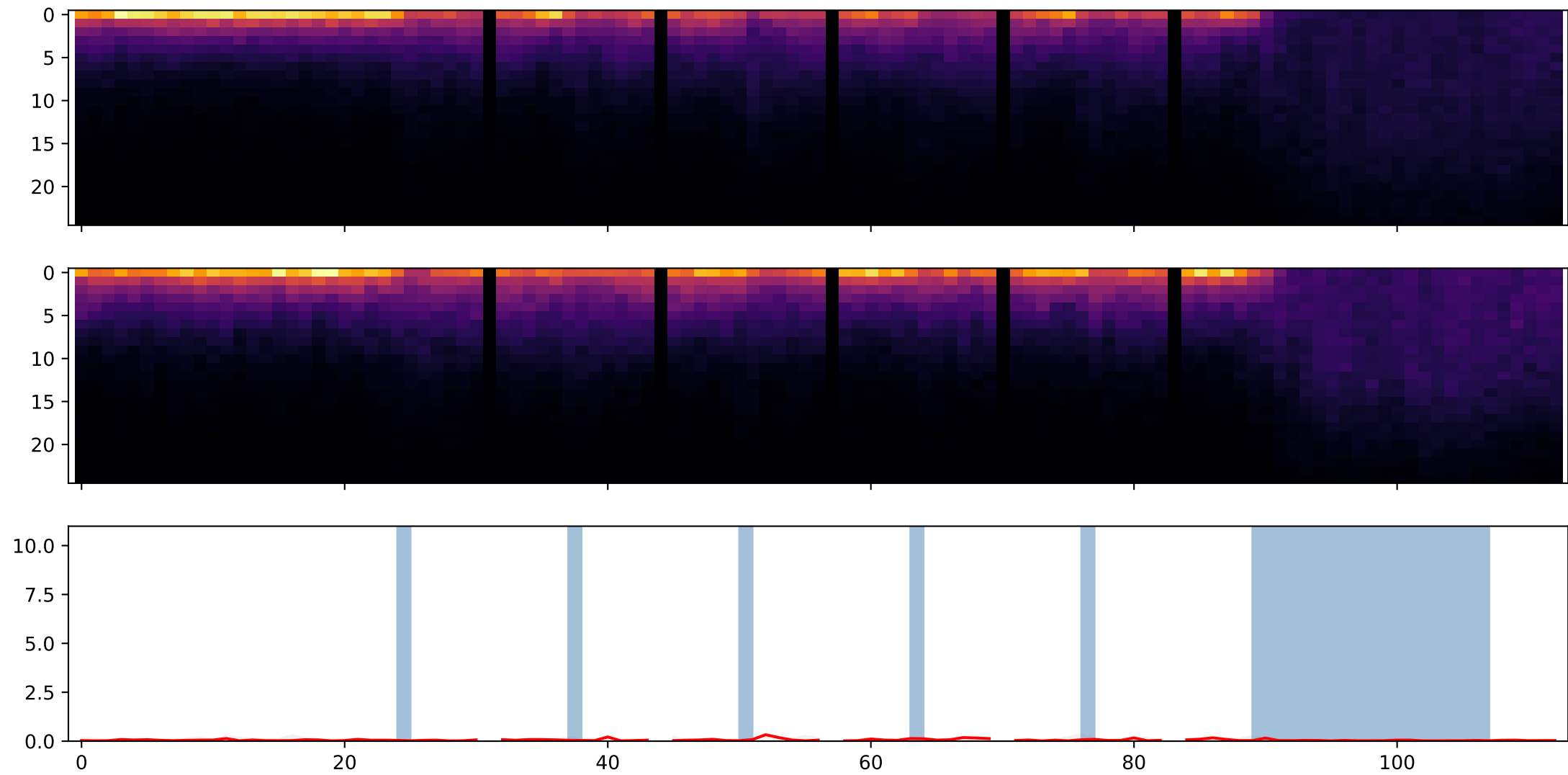
d_relative_to_body_radial_velocity_head_tip



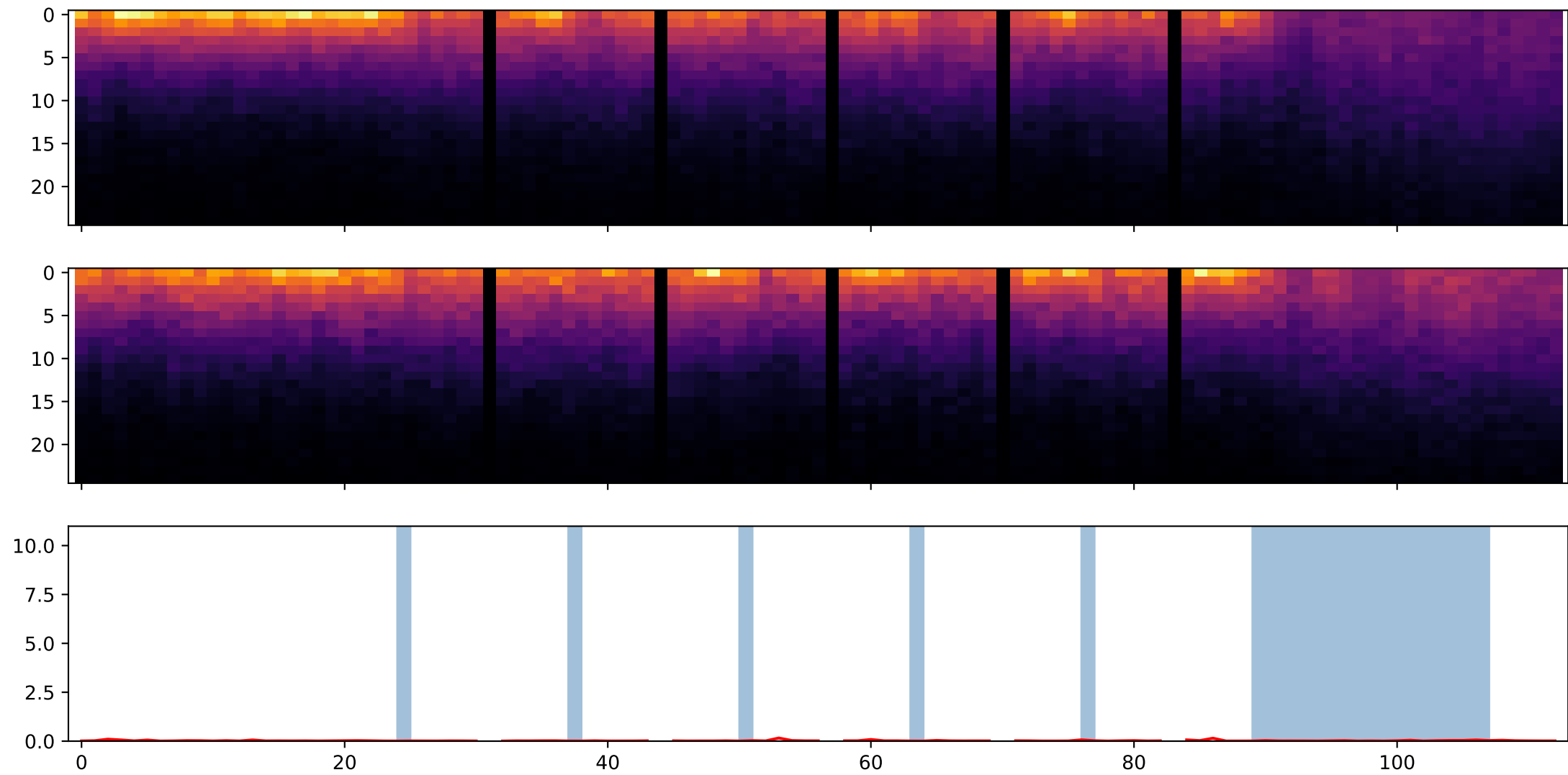
relative_to_body_angular_velocity_head_tip



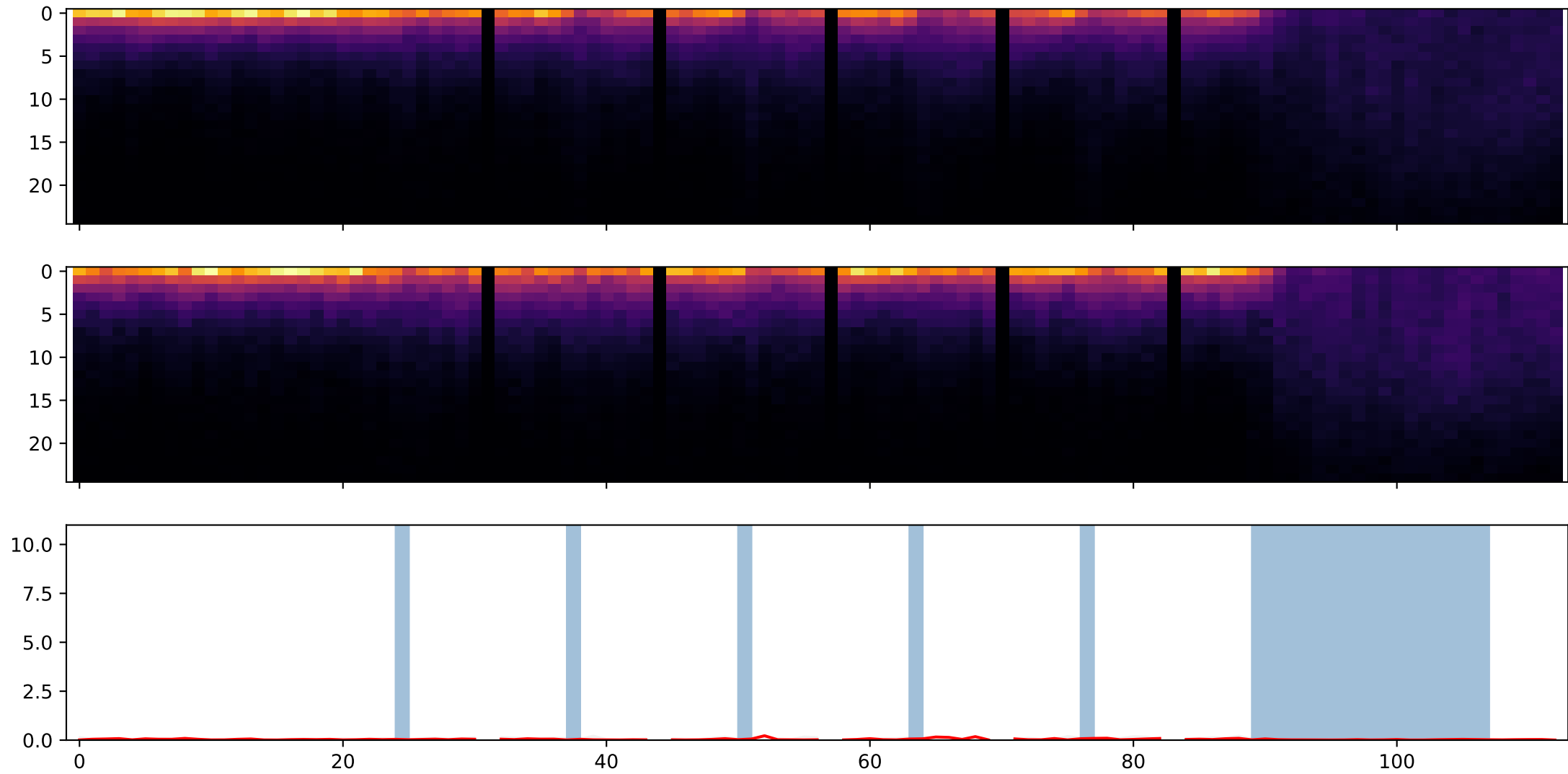
d_curvature_mean_head



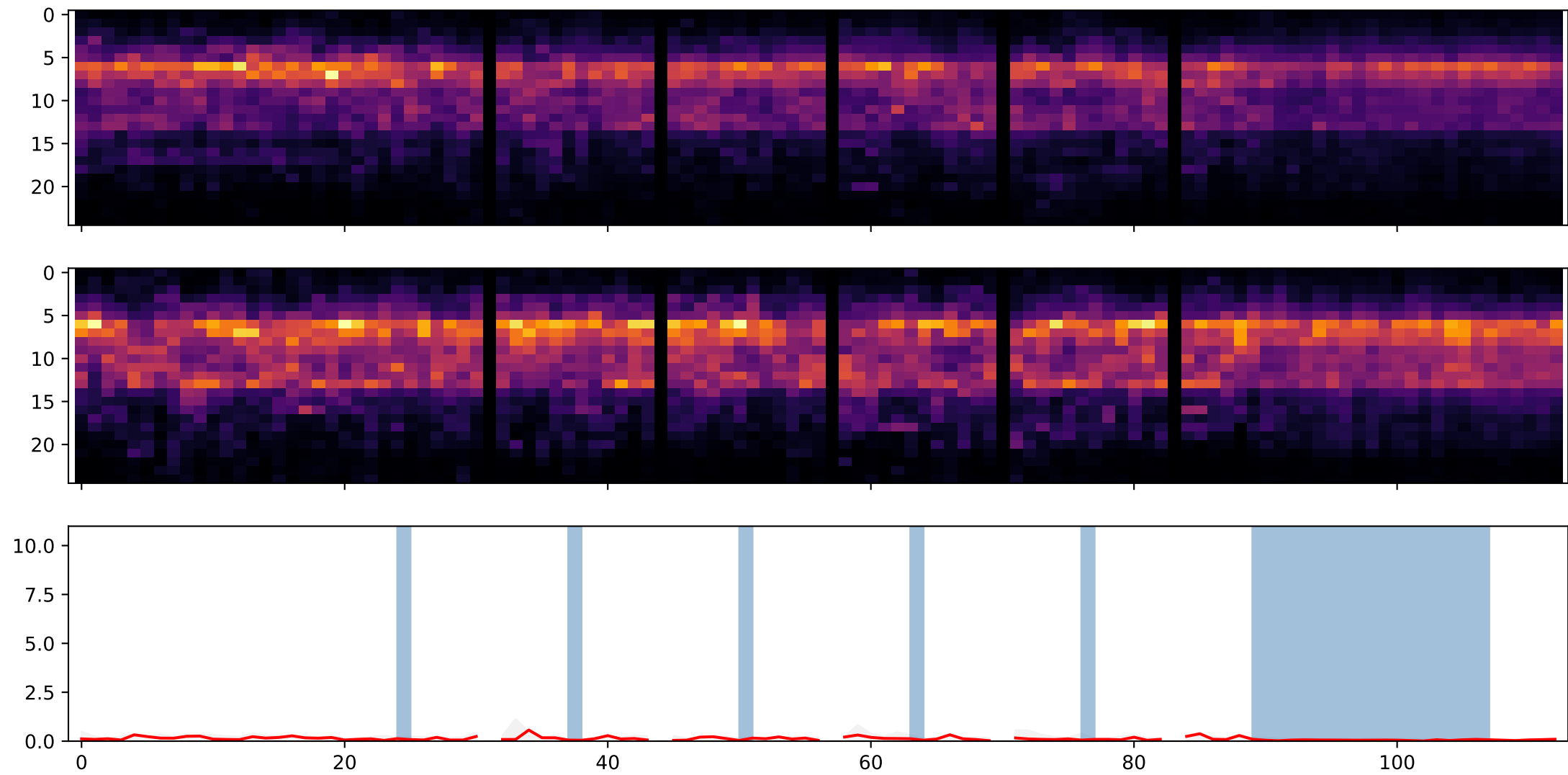
d_curvature_std_head



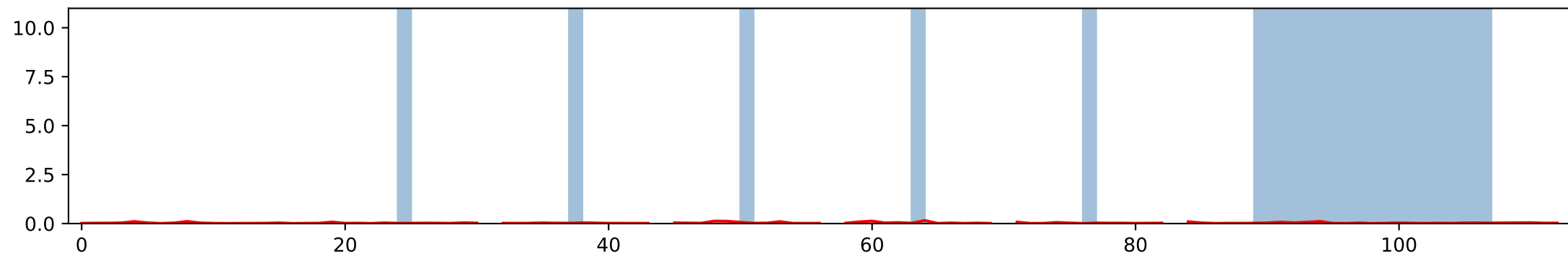
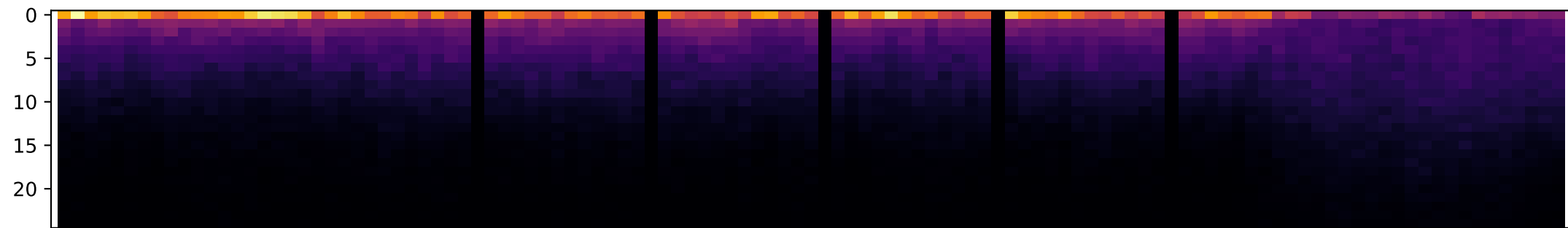
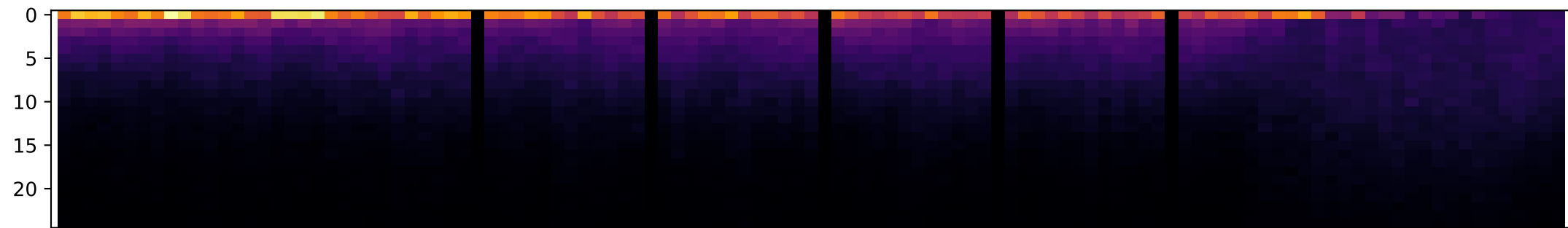
relative_to_tail_base_angular_velocity_tail_tip



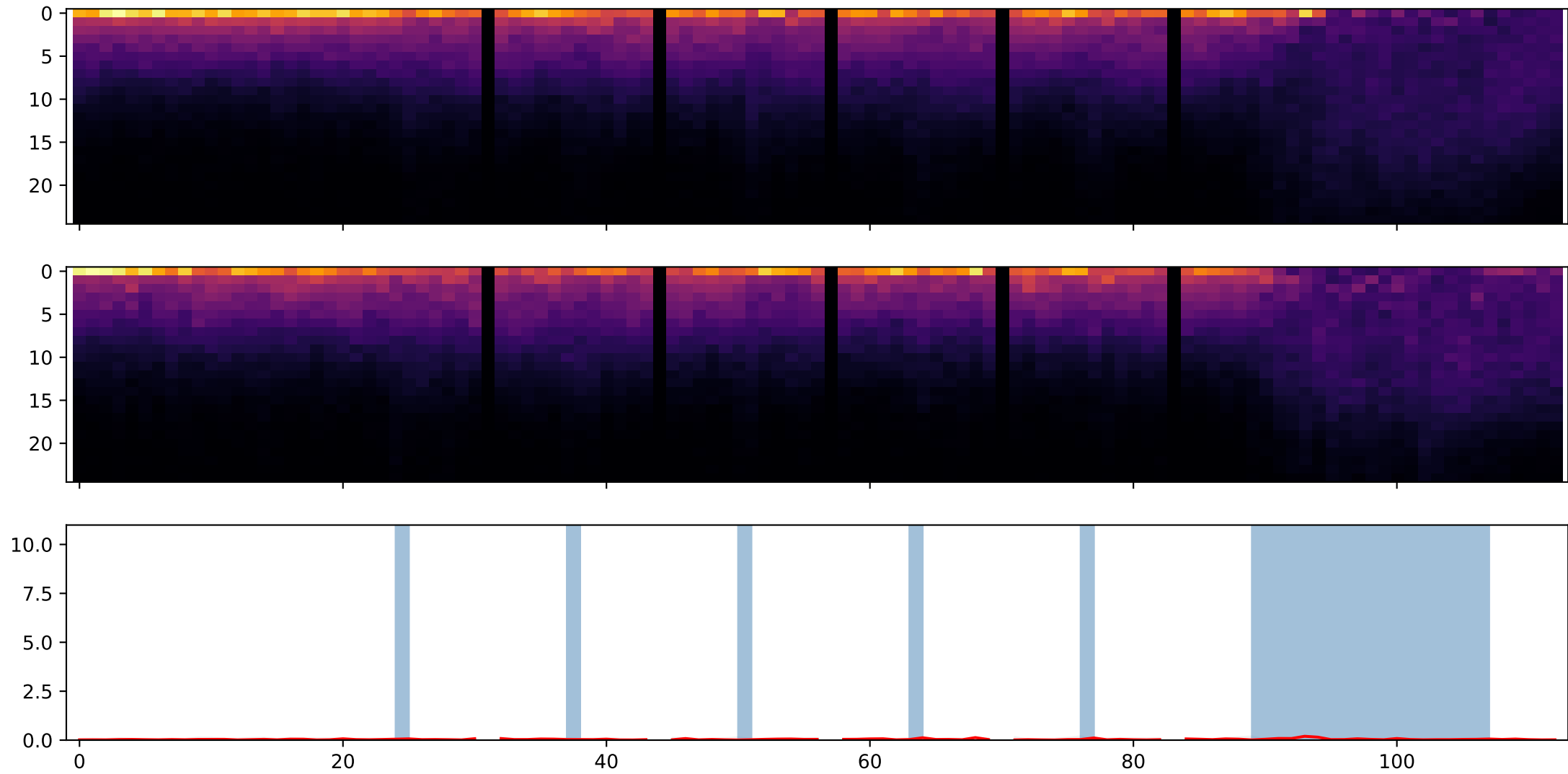
width_tail_base



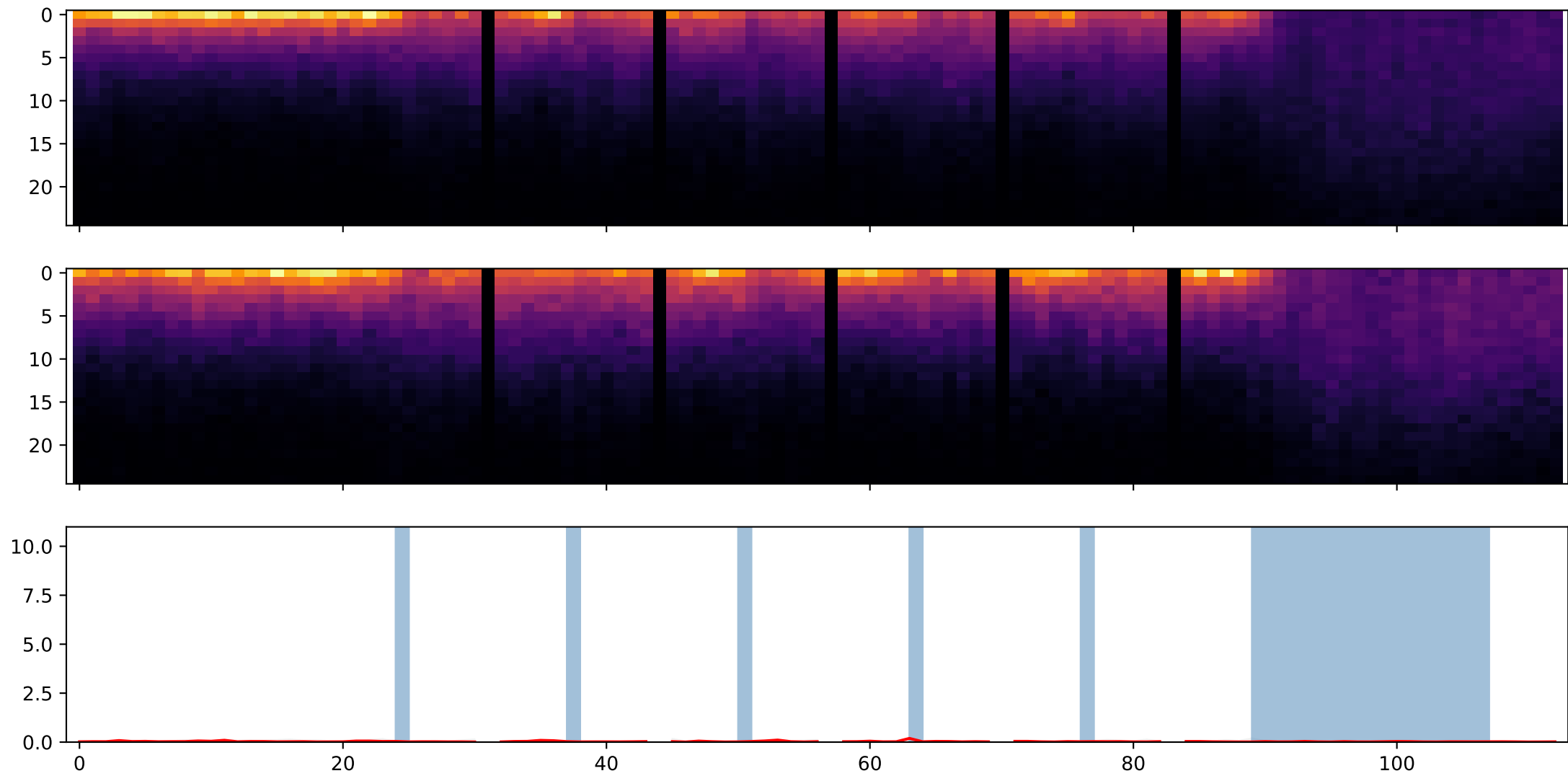
d_angular_velocity_tail_tip



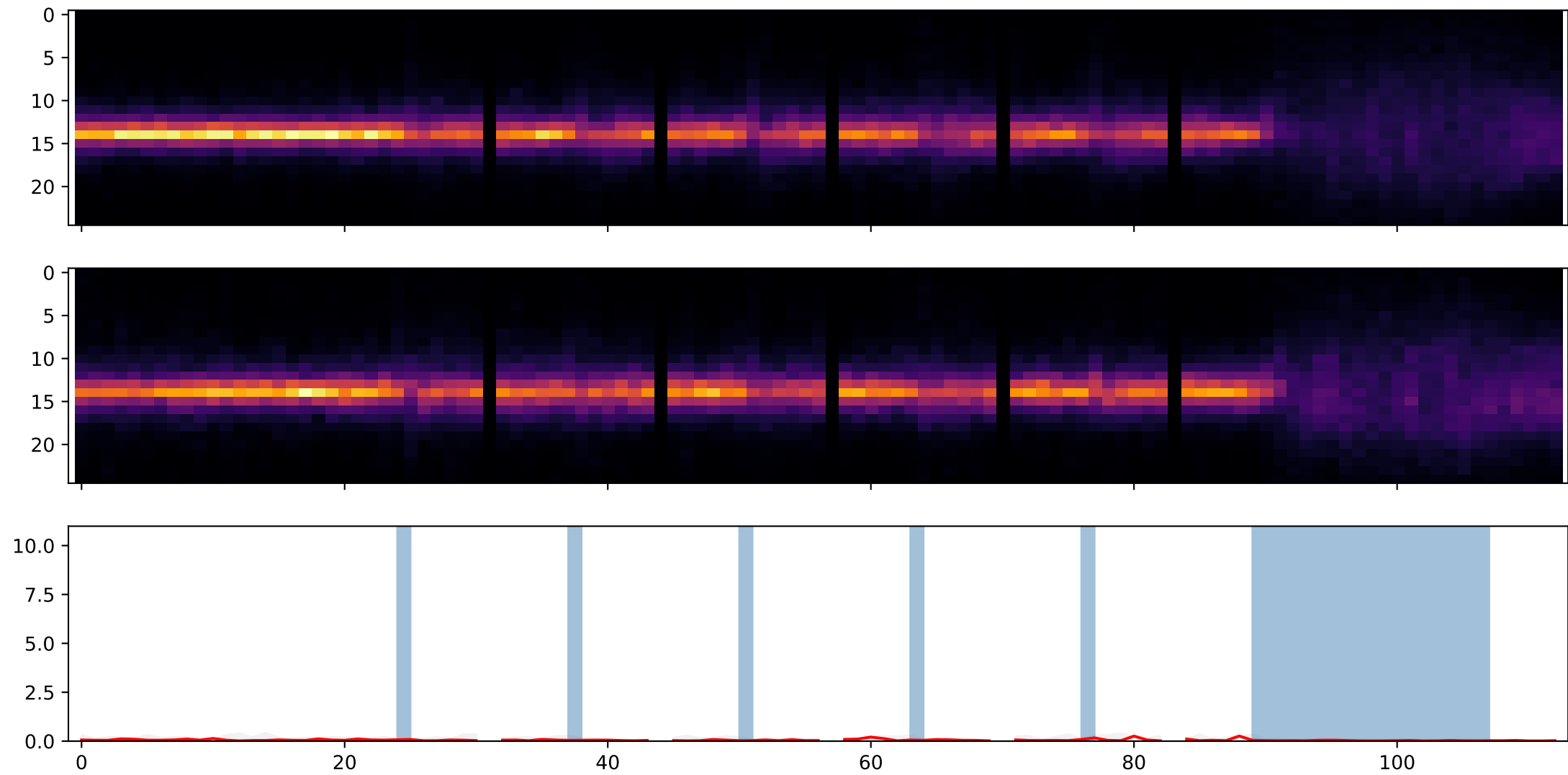
angular_velocity_head_tip



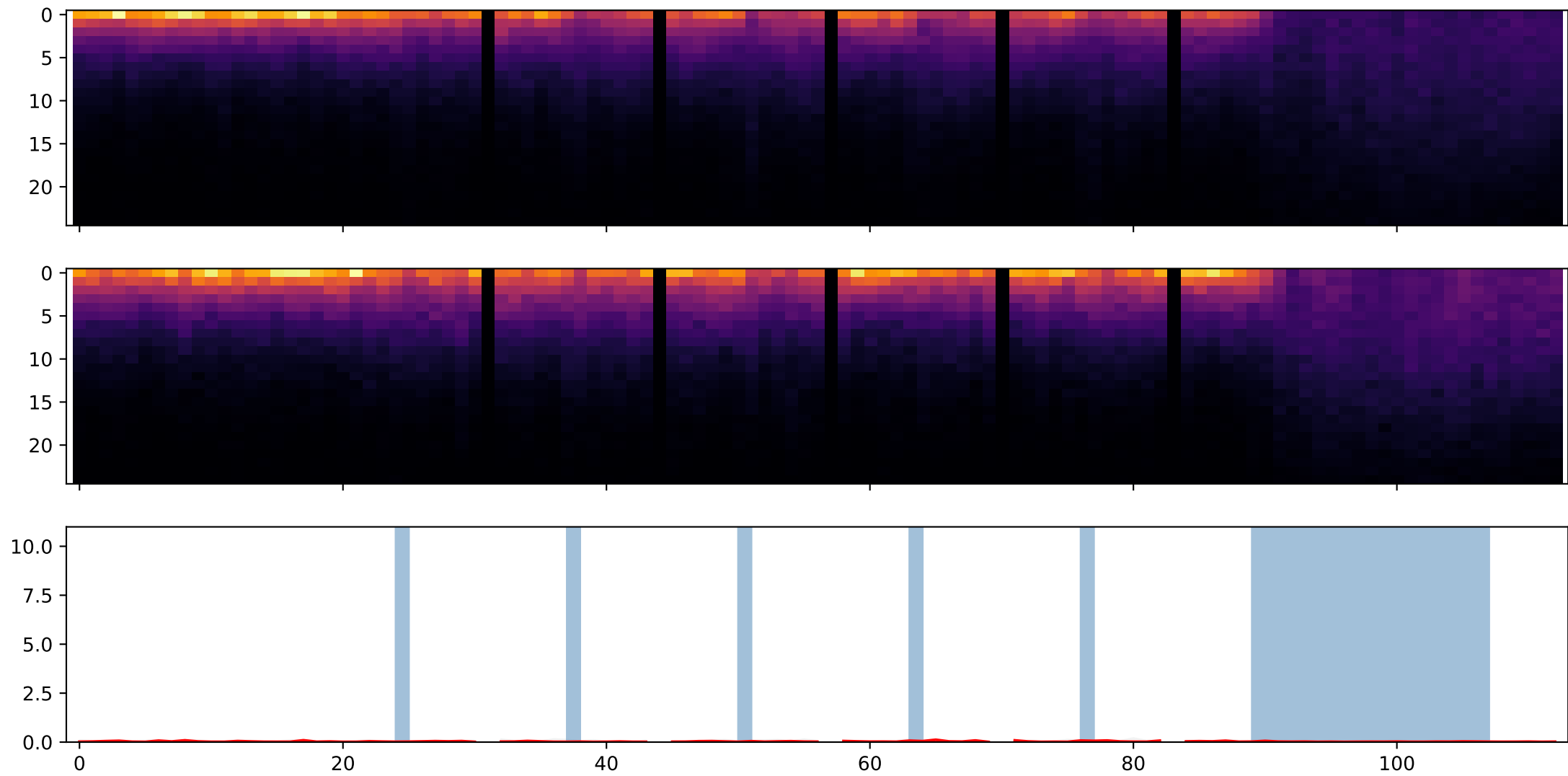
relative_to_head_base_angular_velocity_head_tip



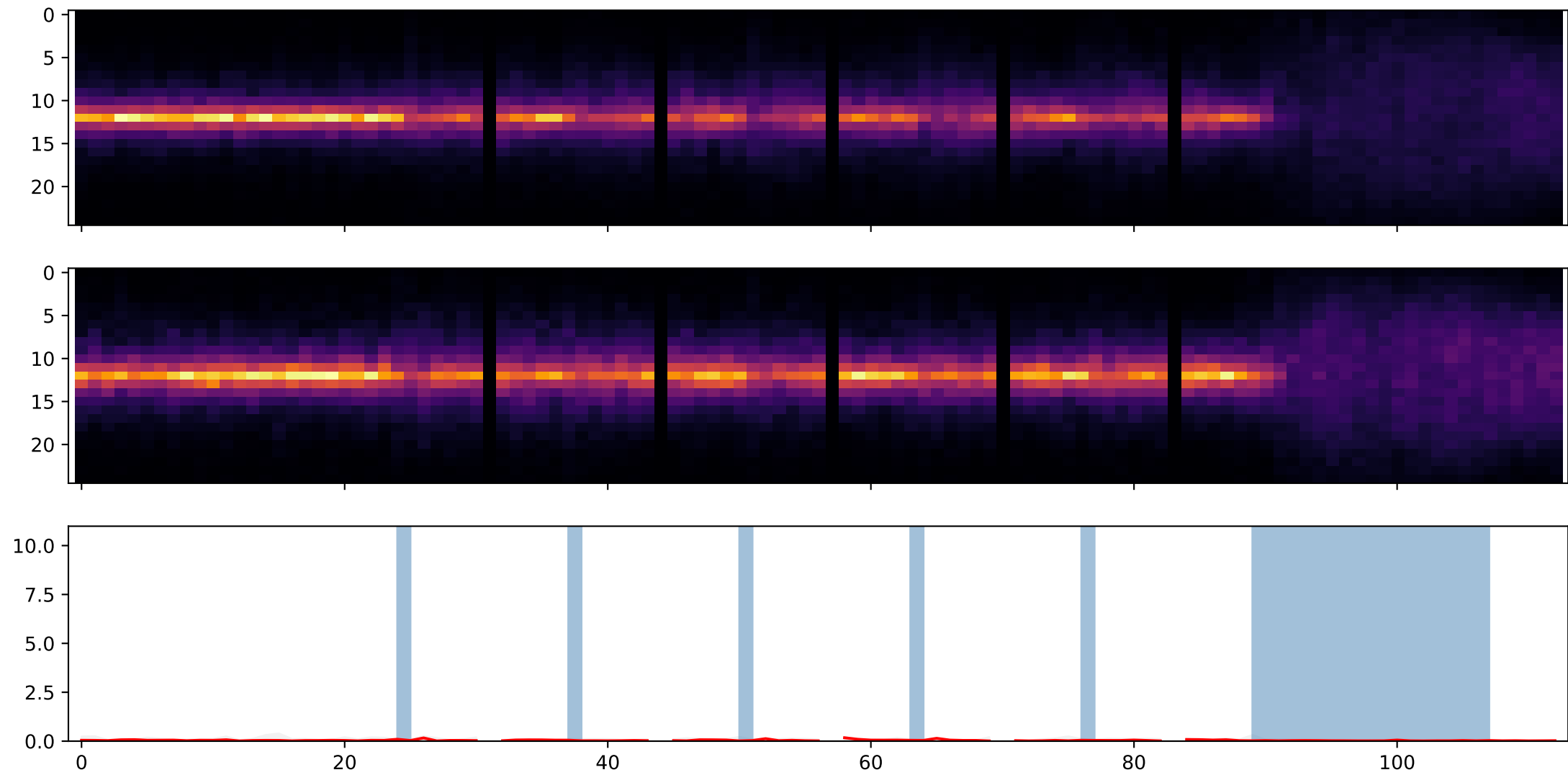
relative_to_body_radial_velocity_head_tip



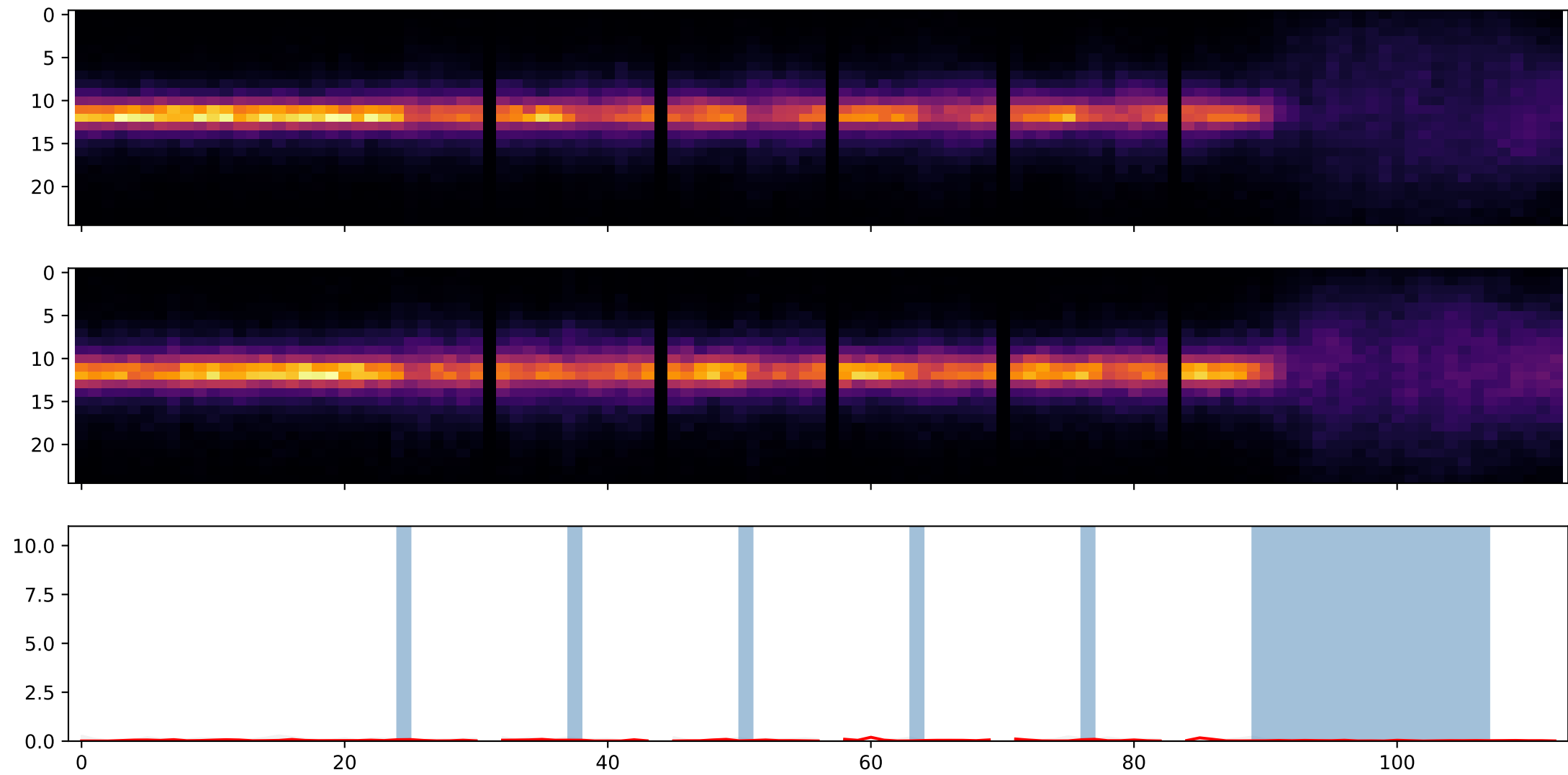
d_relative_to_tail_base_angular_velocity_tail_tip



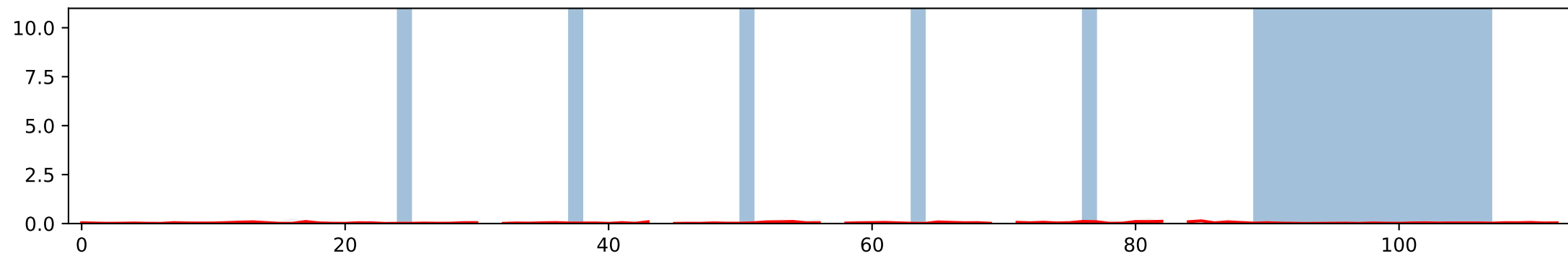
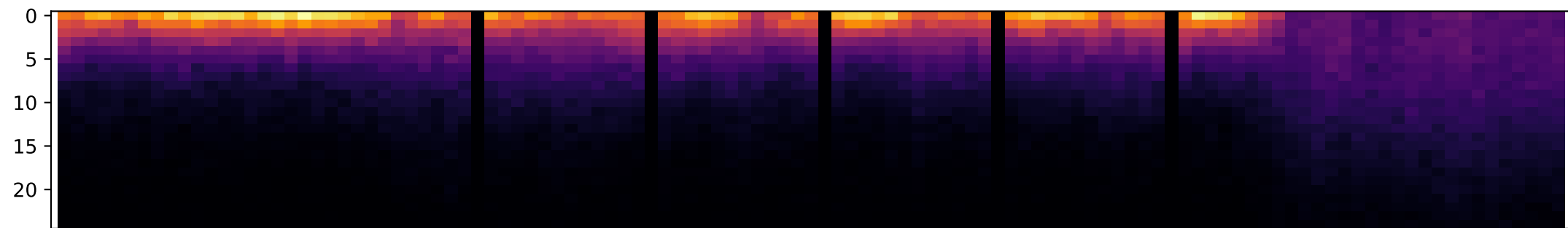
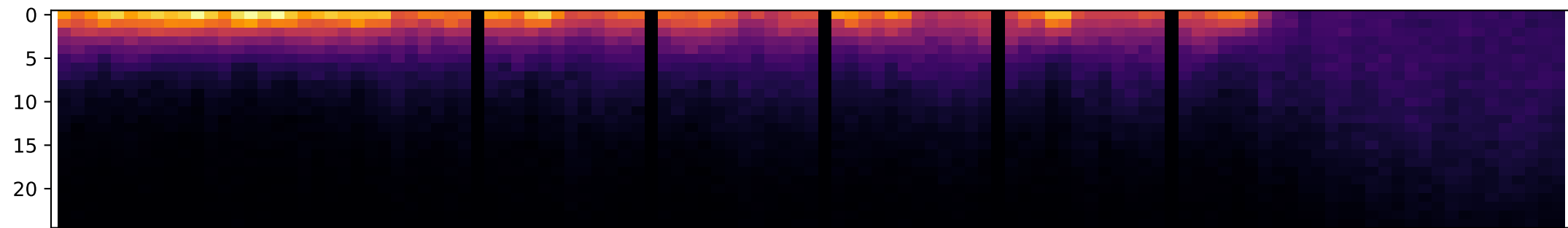
relative_to_neck_radial_velocity_head_tip



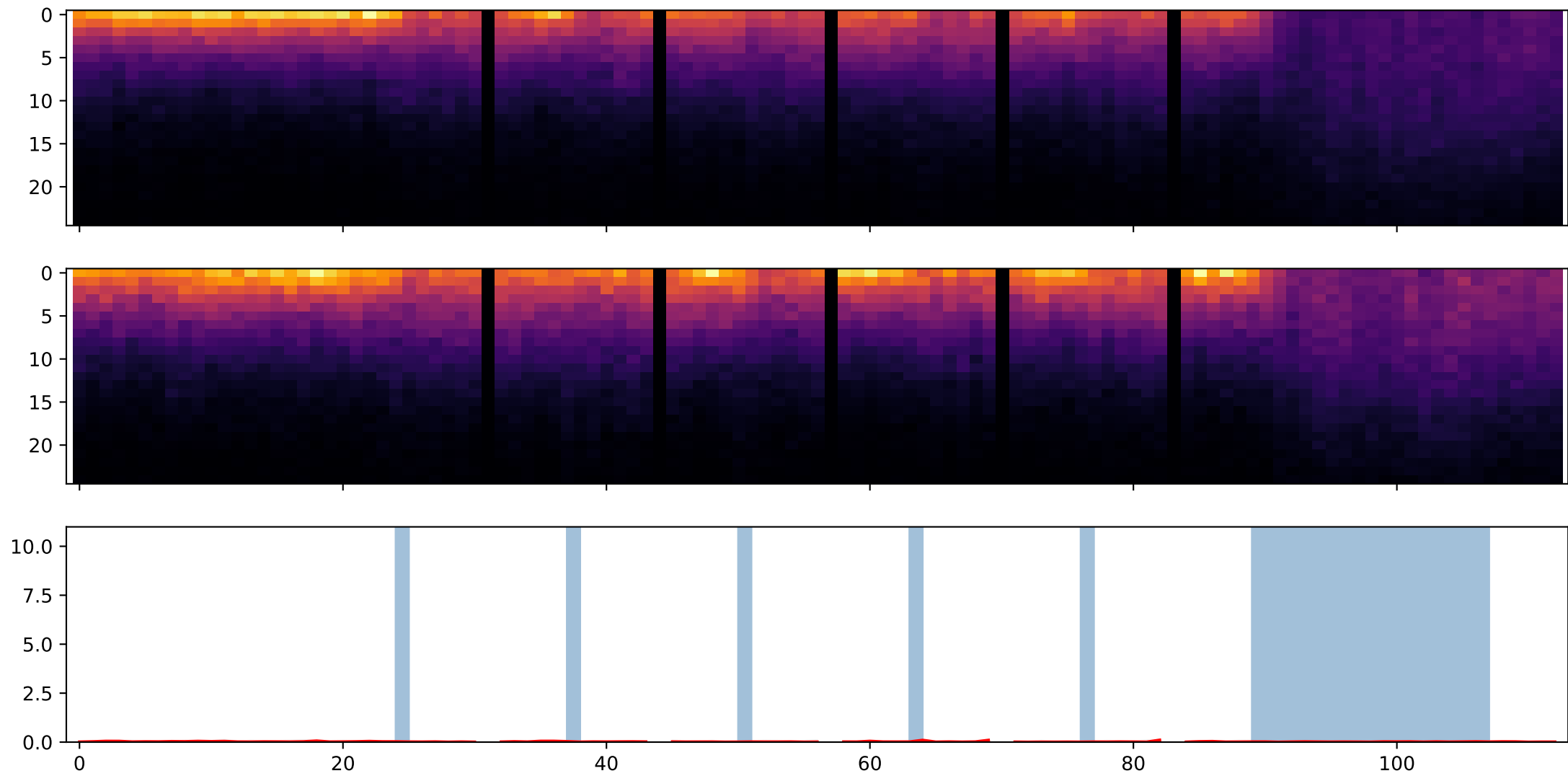
d_relative_to_neck_radial_velocity_head_tip



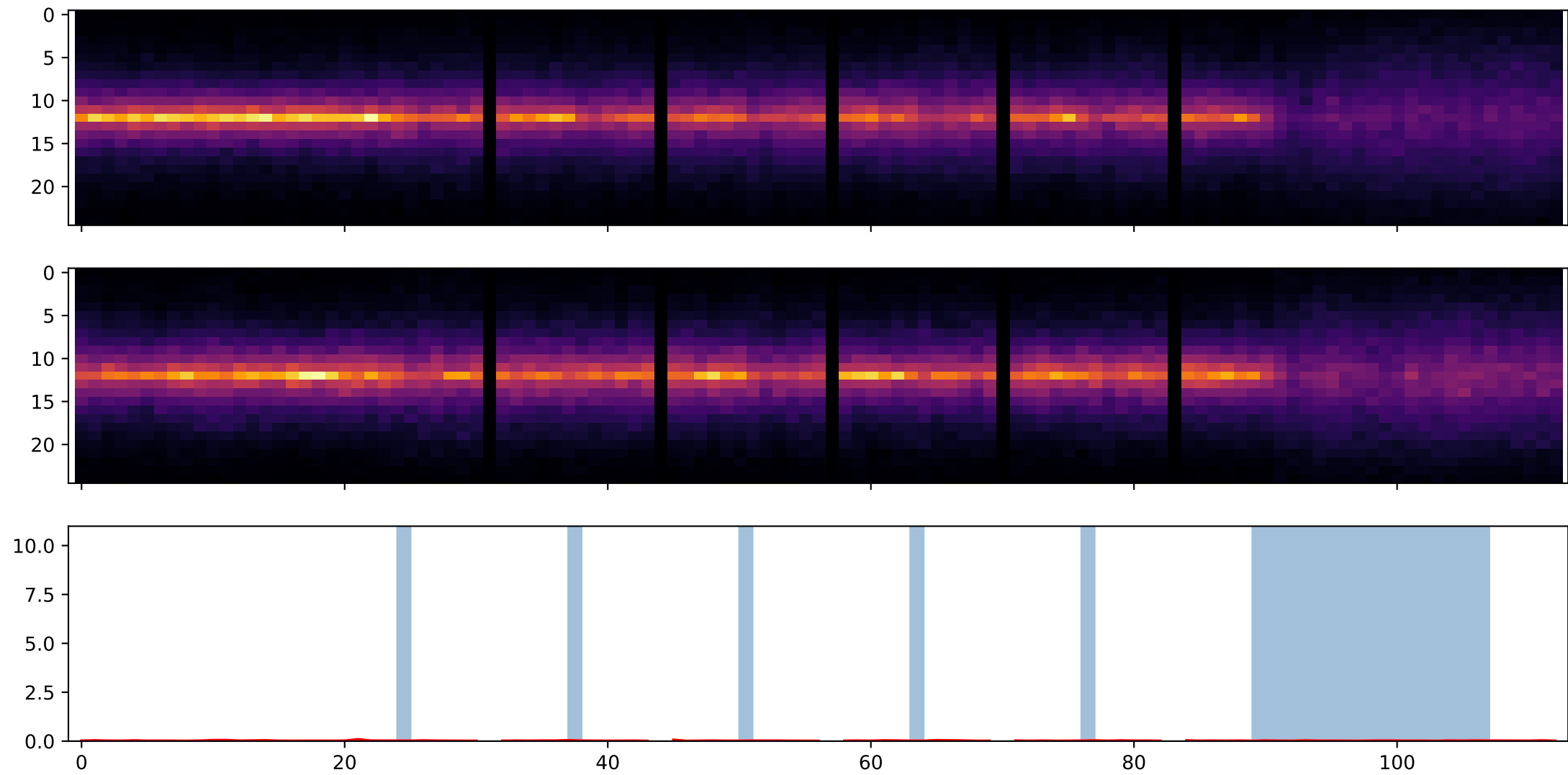
d_curvature_std_neck



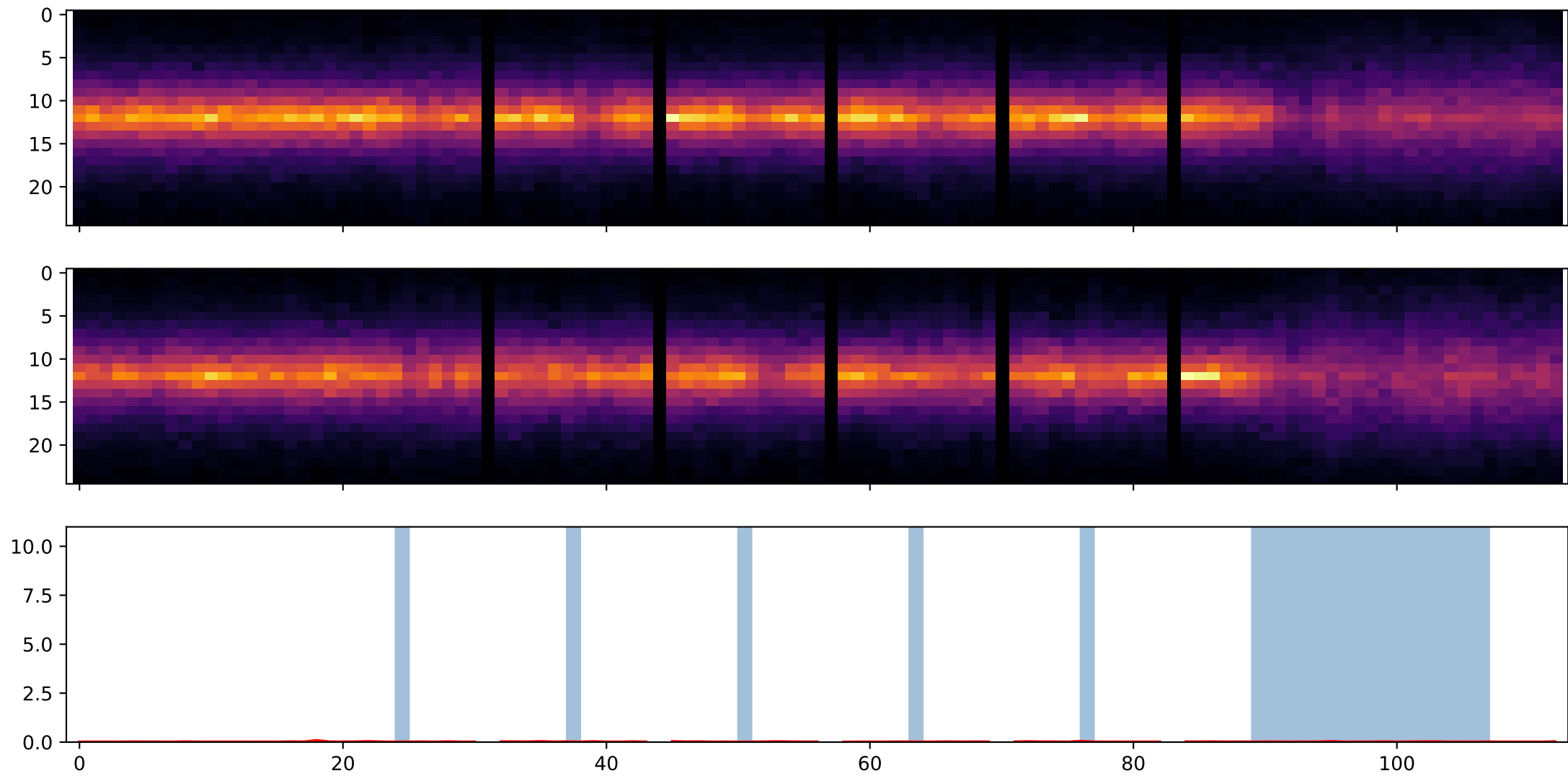
d_relative_to_head_base_angular_velocity_head_tip



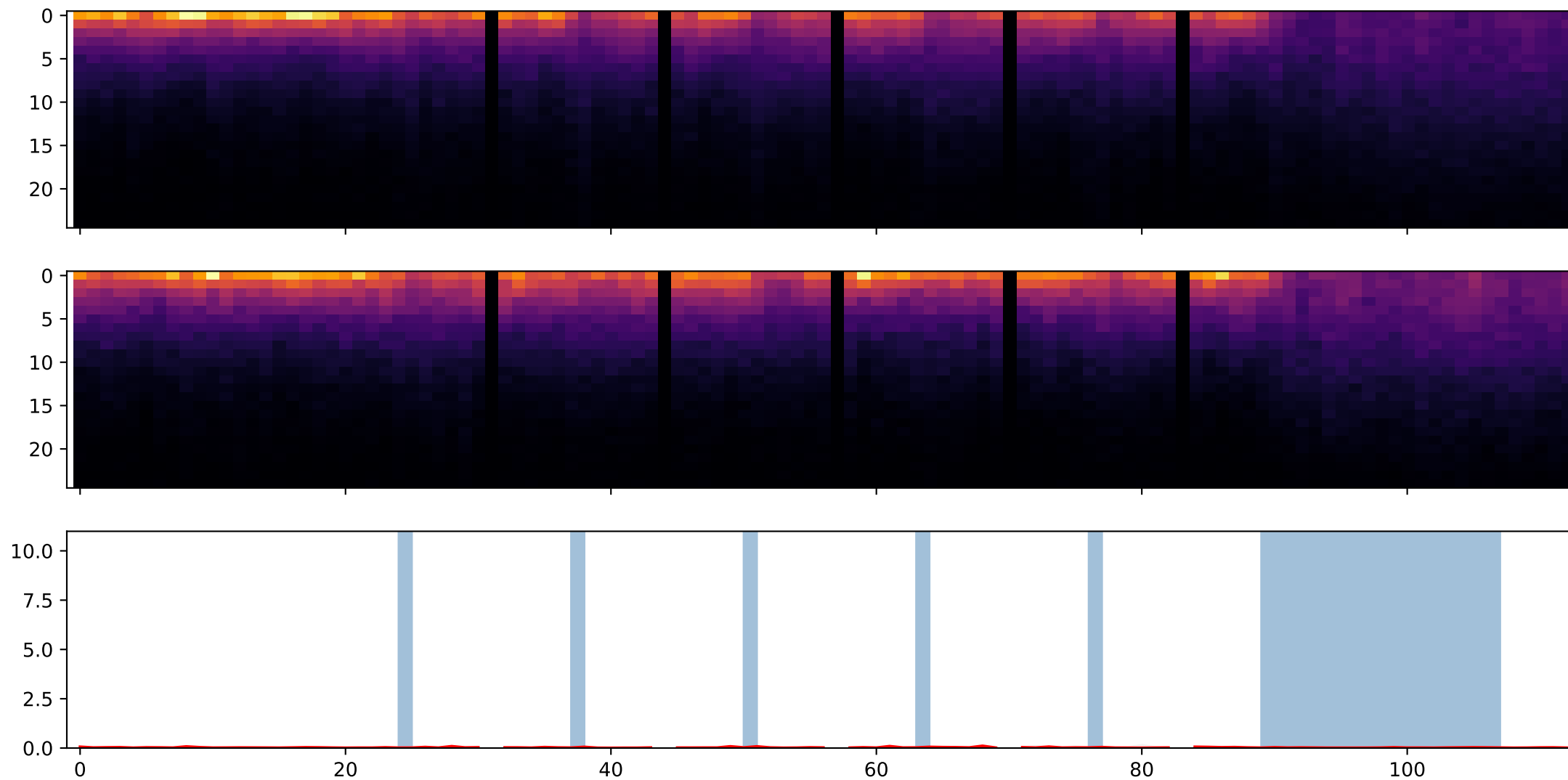
d_width_head_base



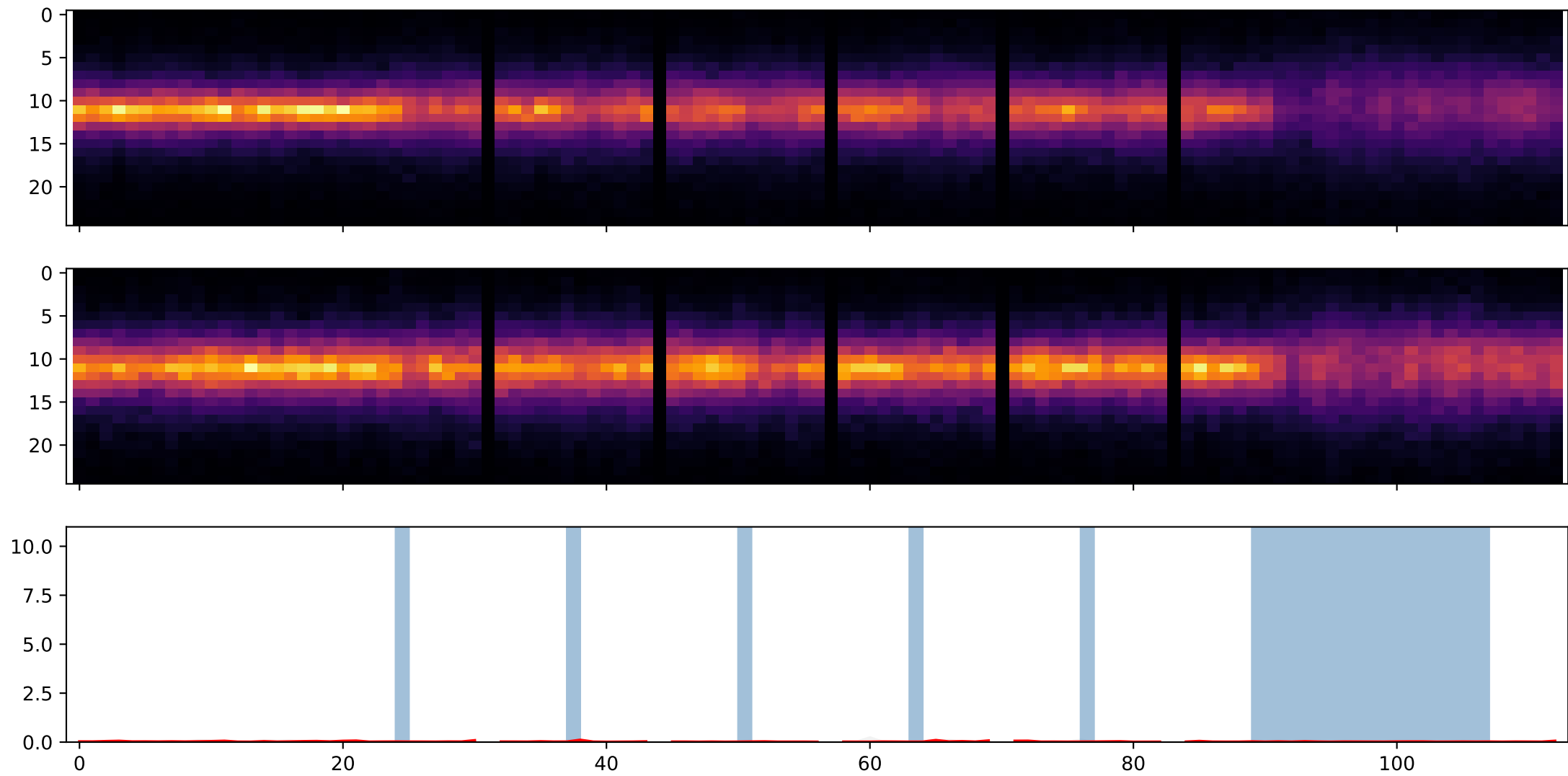
d_width_midbody



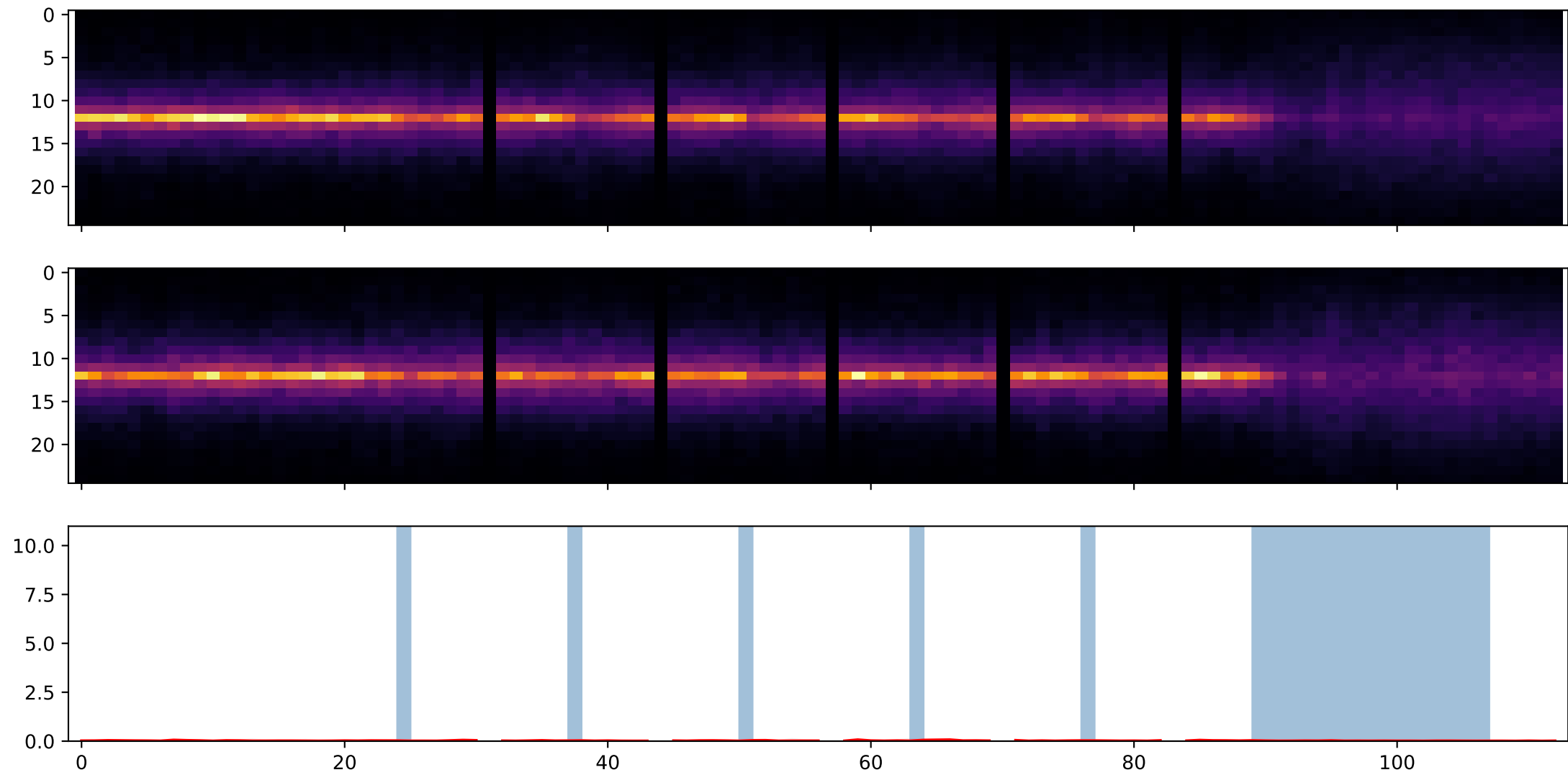
d_curvature_std_tail



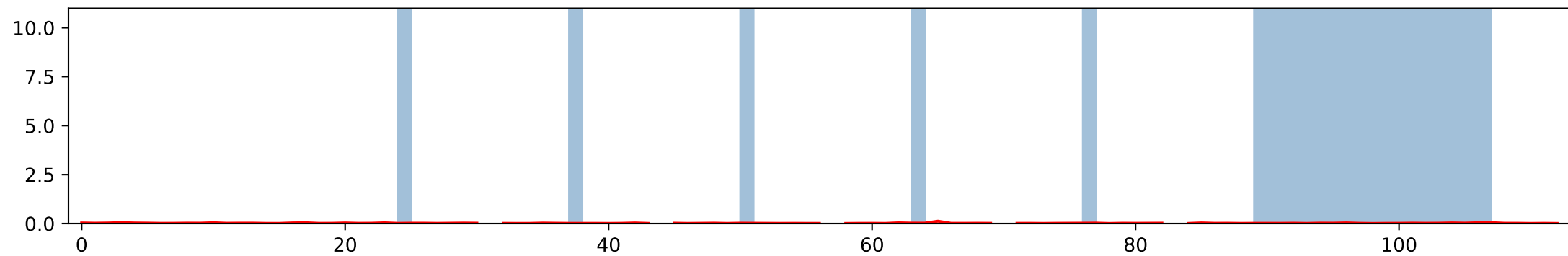
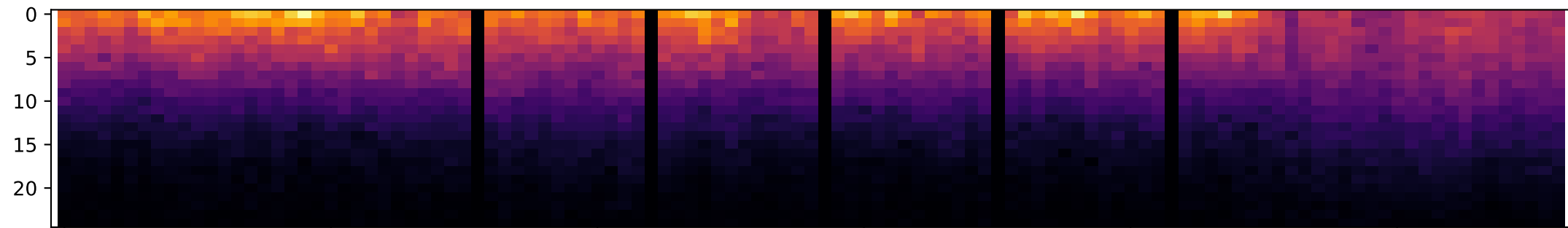
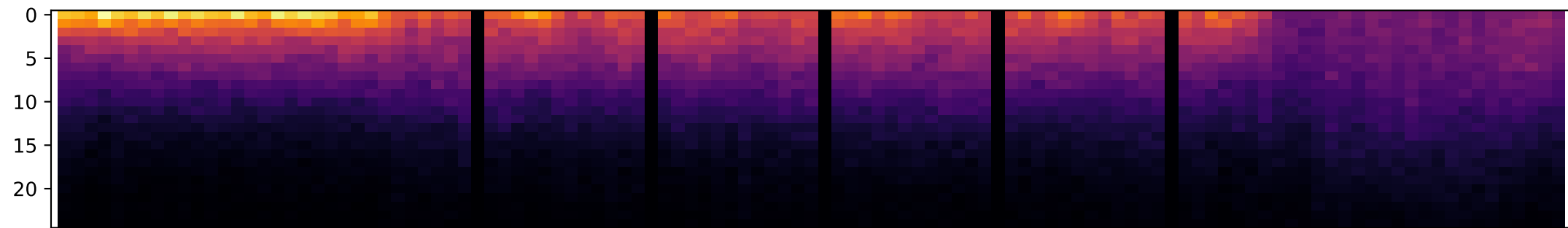
d_relative_to_head_base_radial_velocity_head_tip



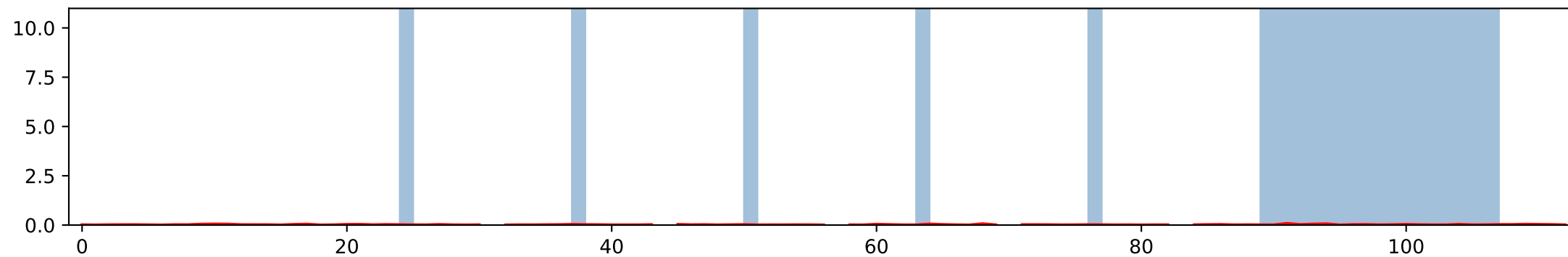
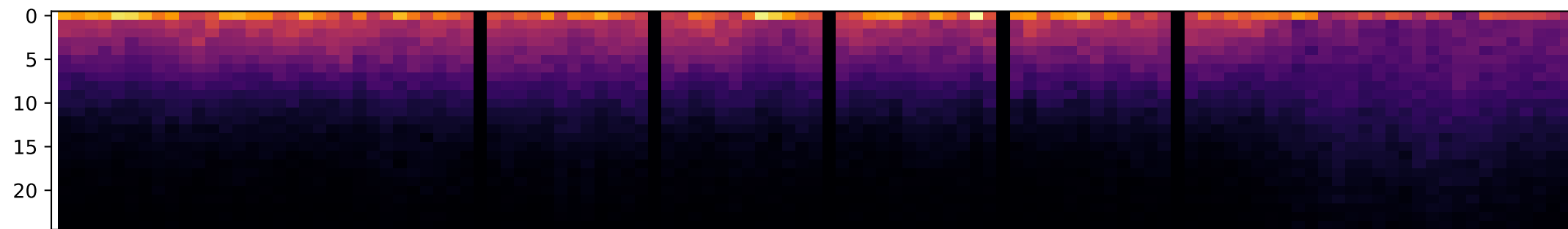
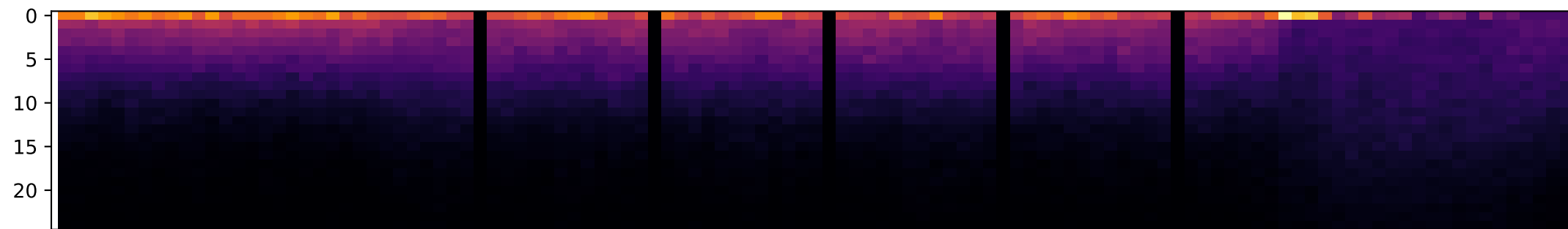
d_width_tail_base



d_eigen_projection_6



d_angular_velocity_head_tip



d_eigen_projection_7

