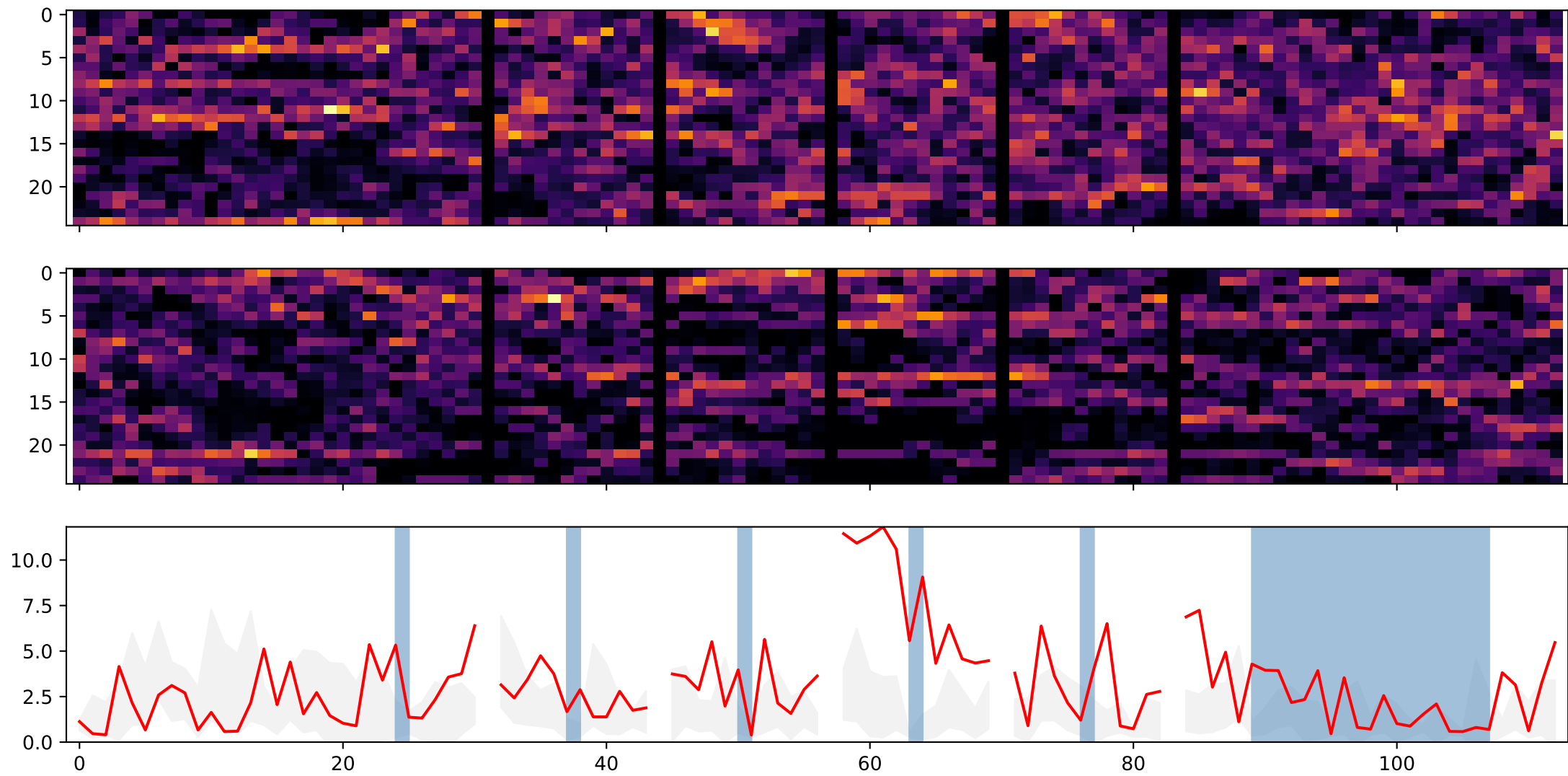
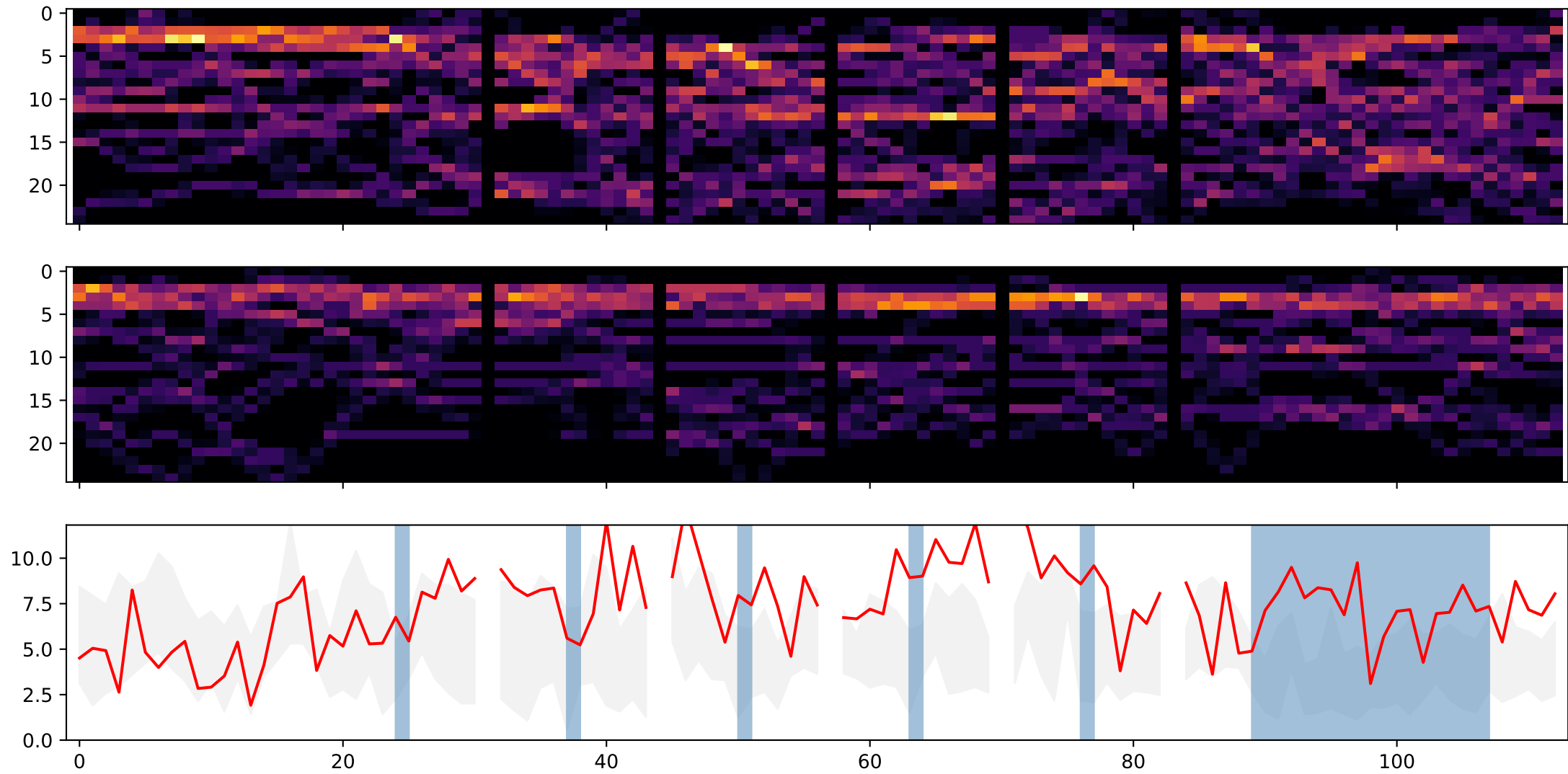


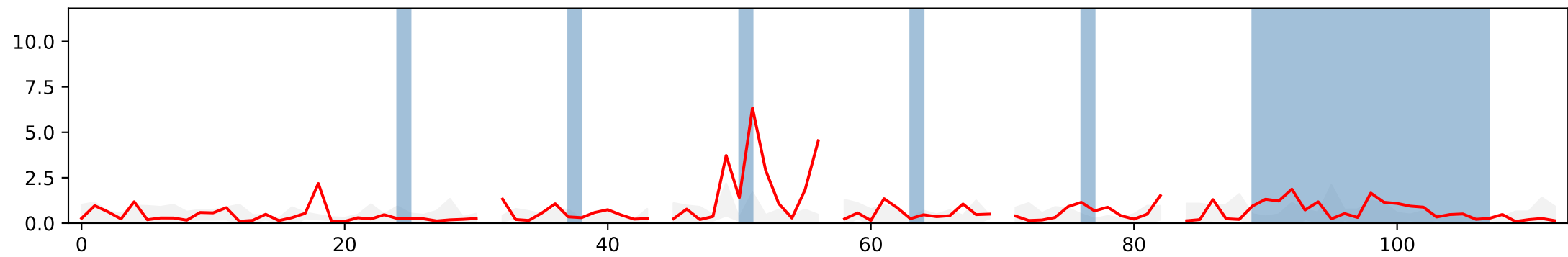
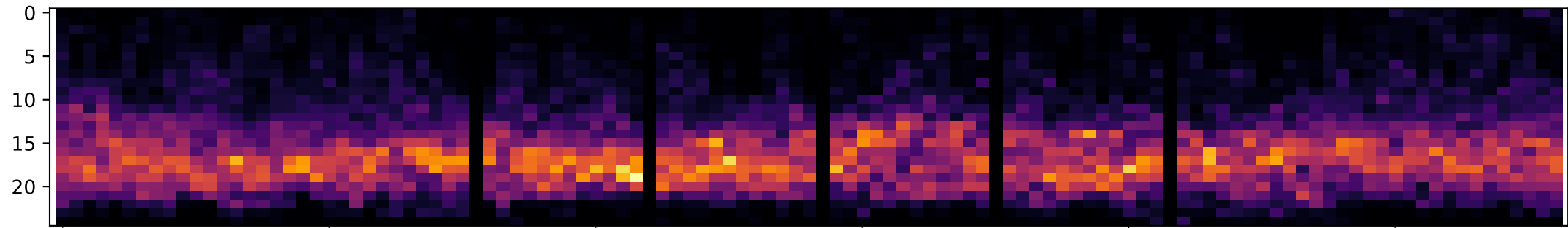
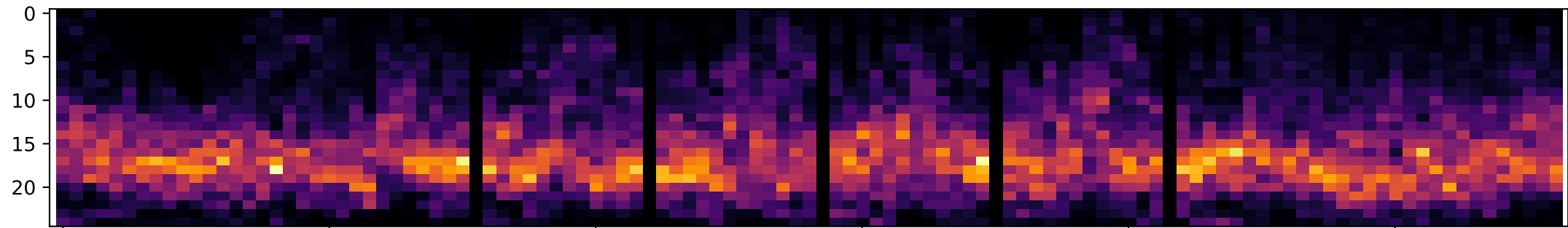
orientation_food_edge



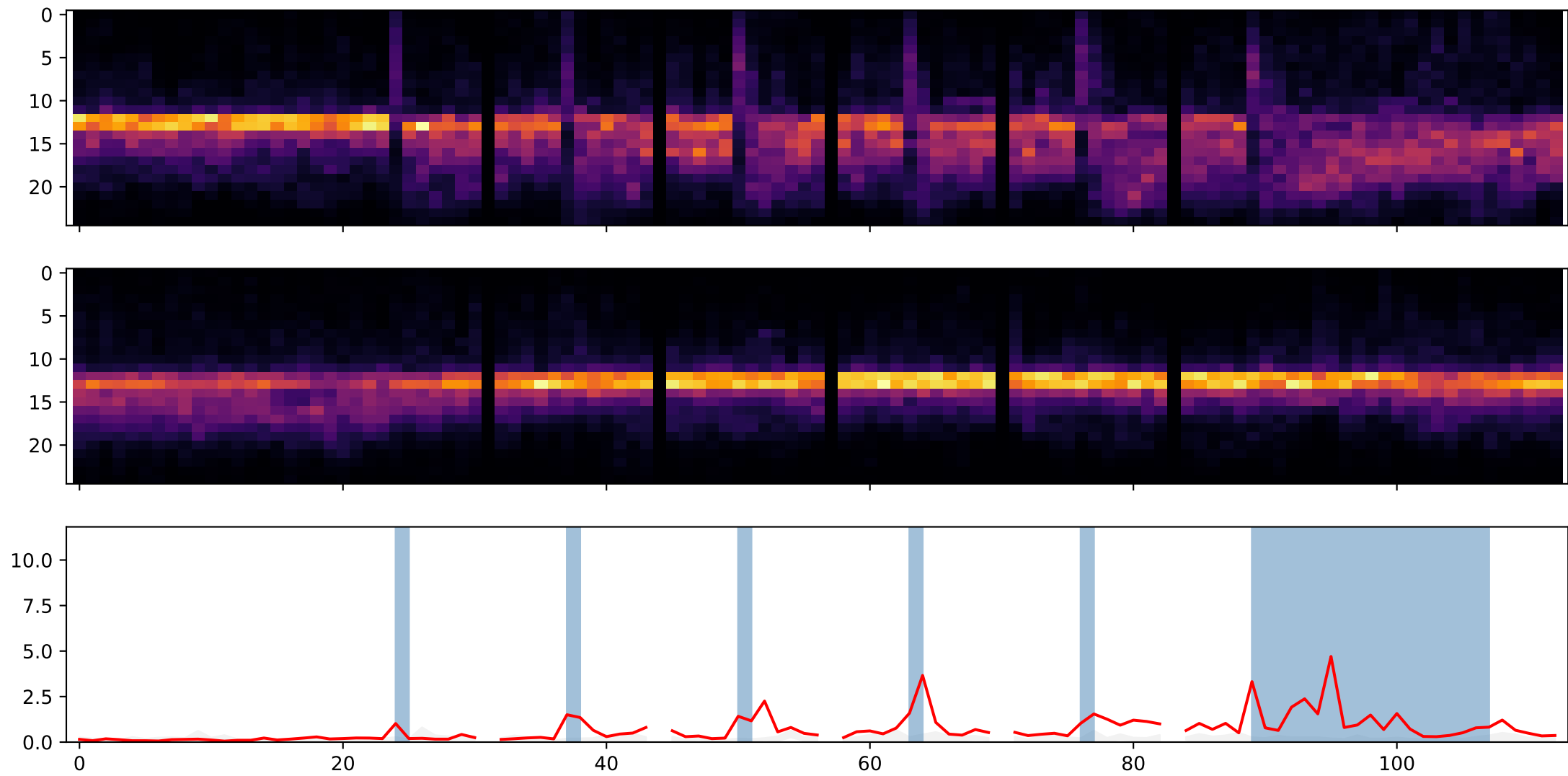
dist_from_food_edge



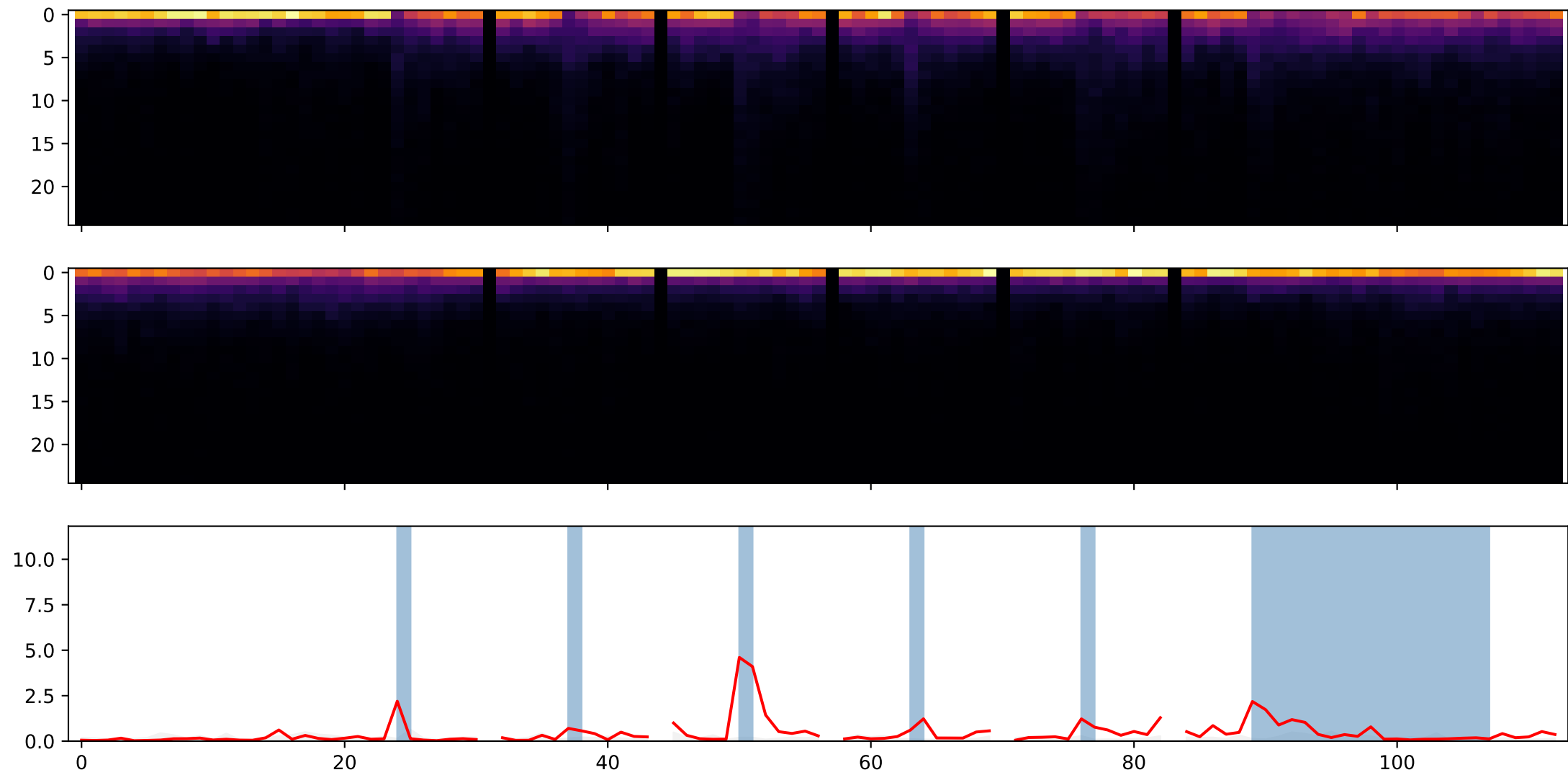
major_axis



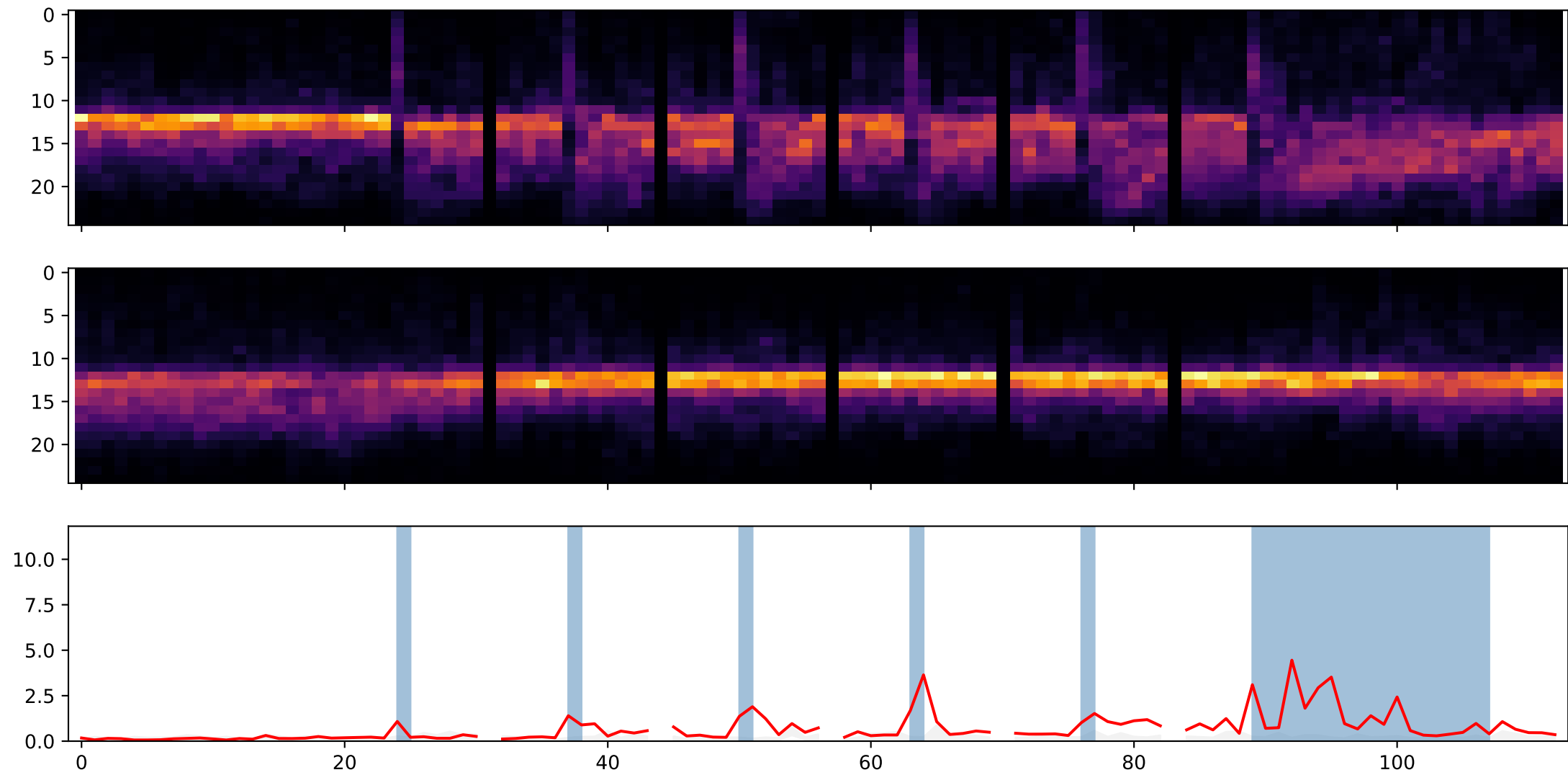
speed_midbody



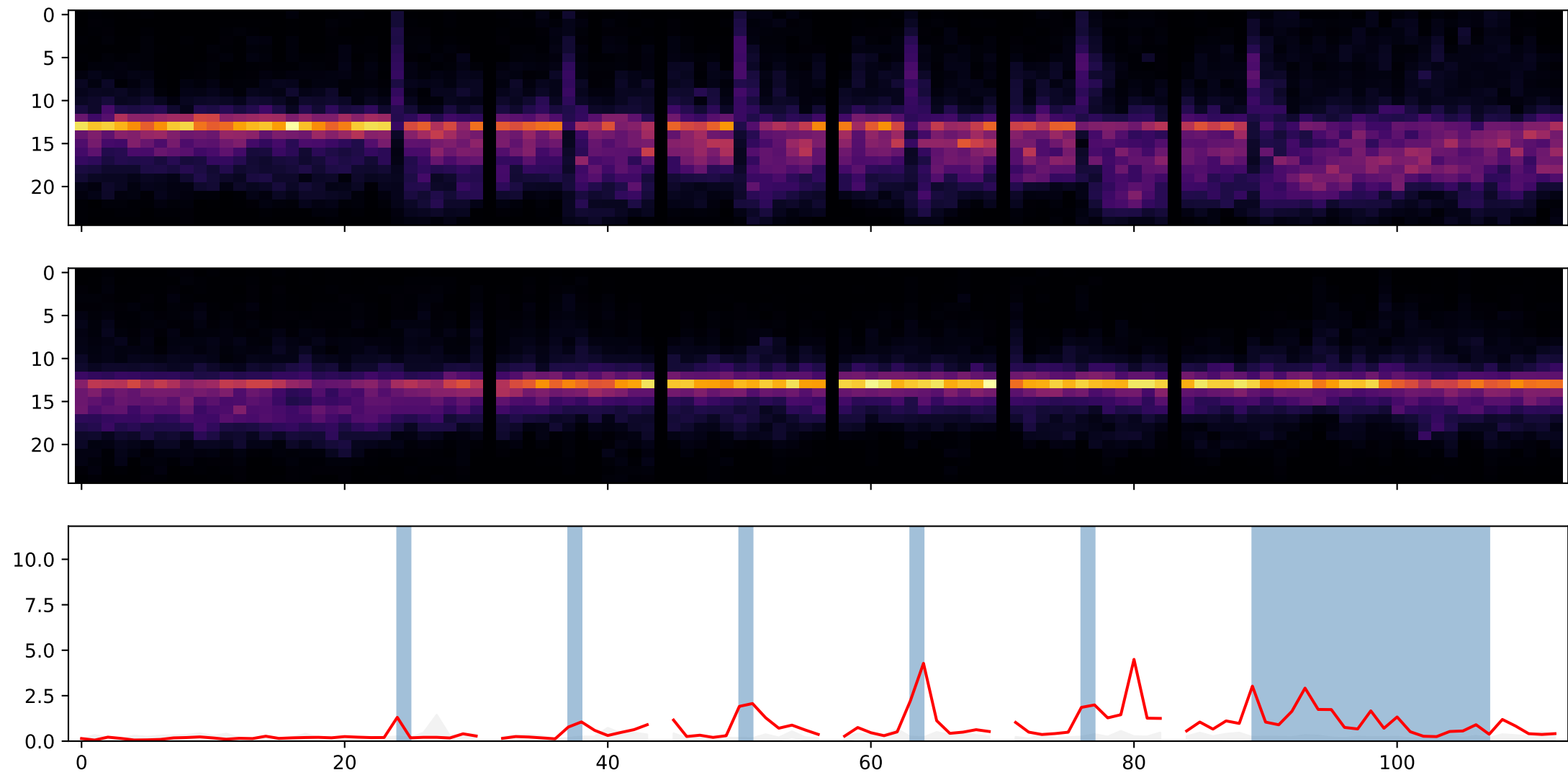
relative_to_body_angular_velocity_tail_tip



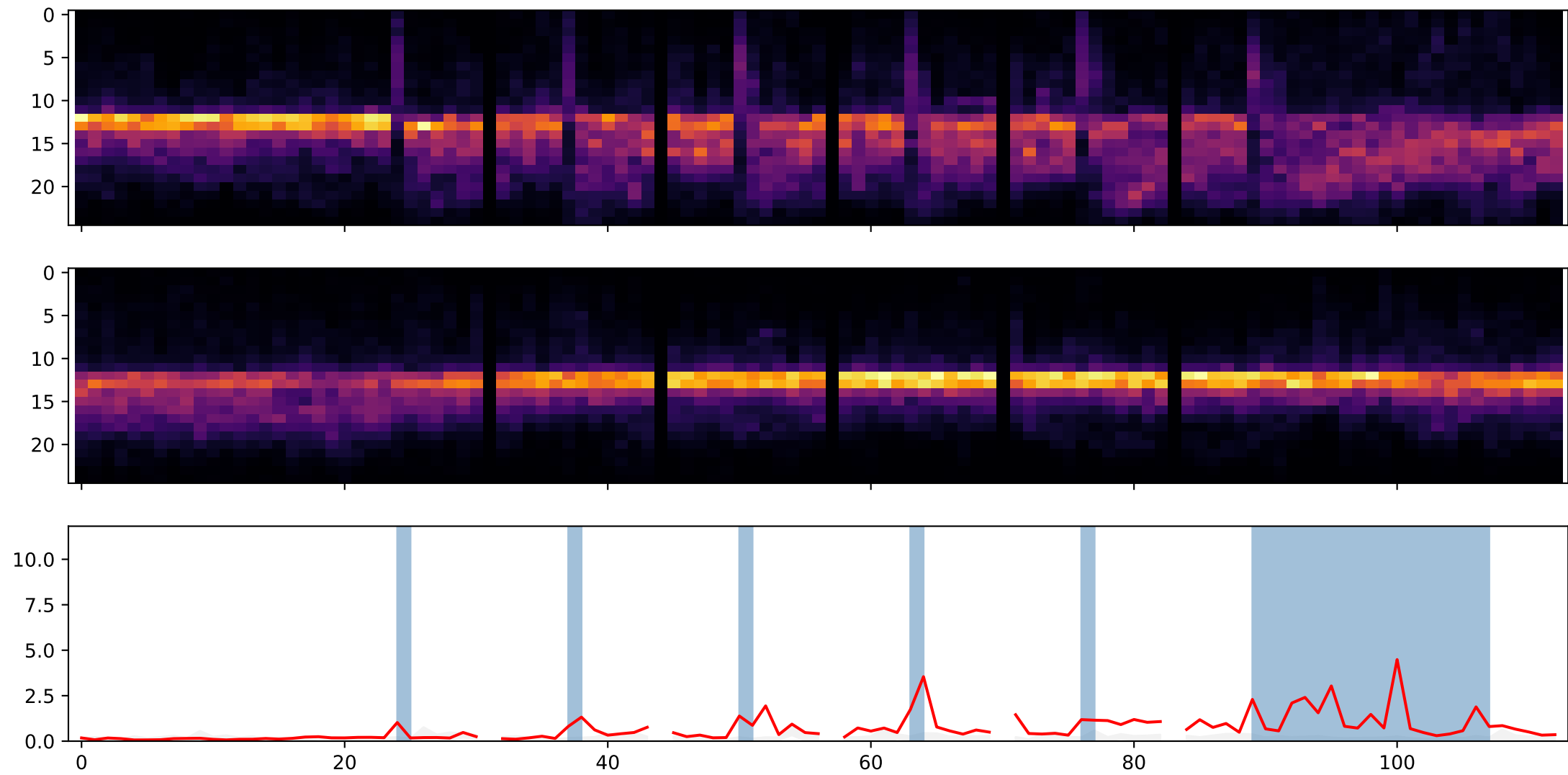
speed_neck



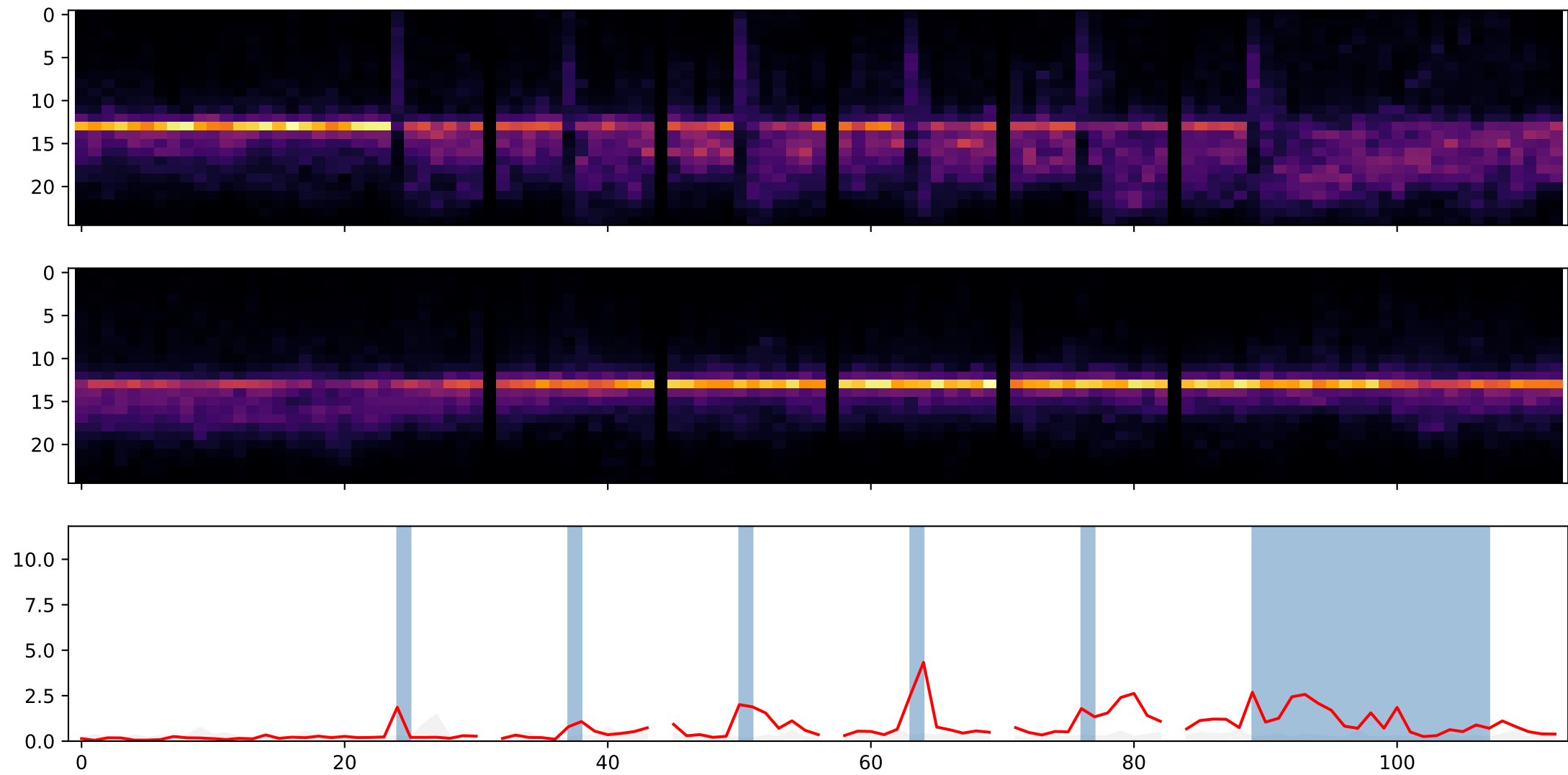
speed_tail_tip



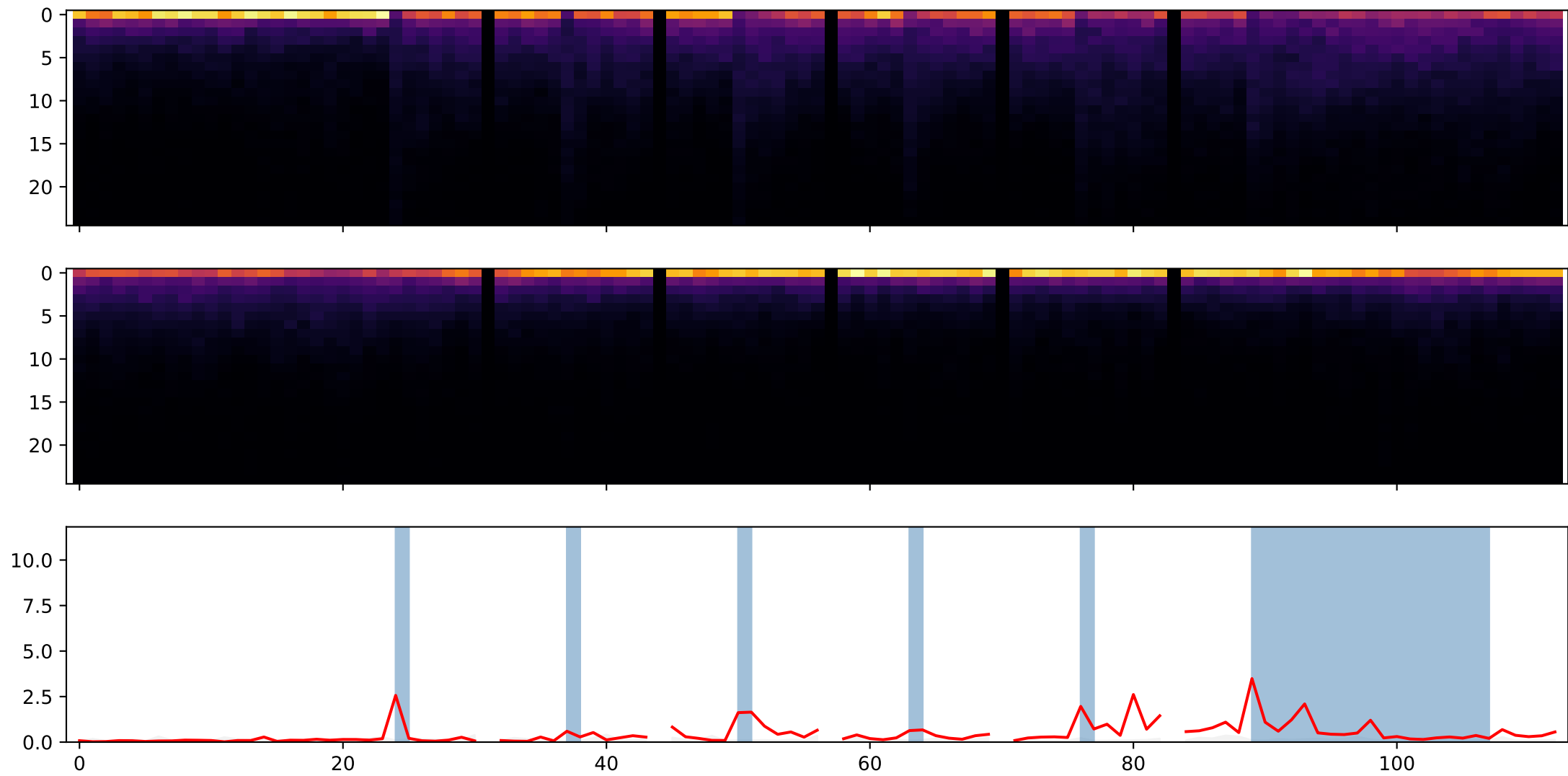
speed



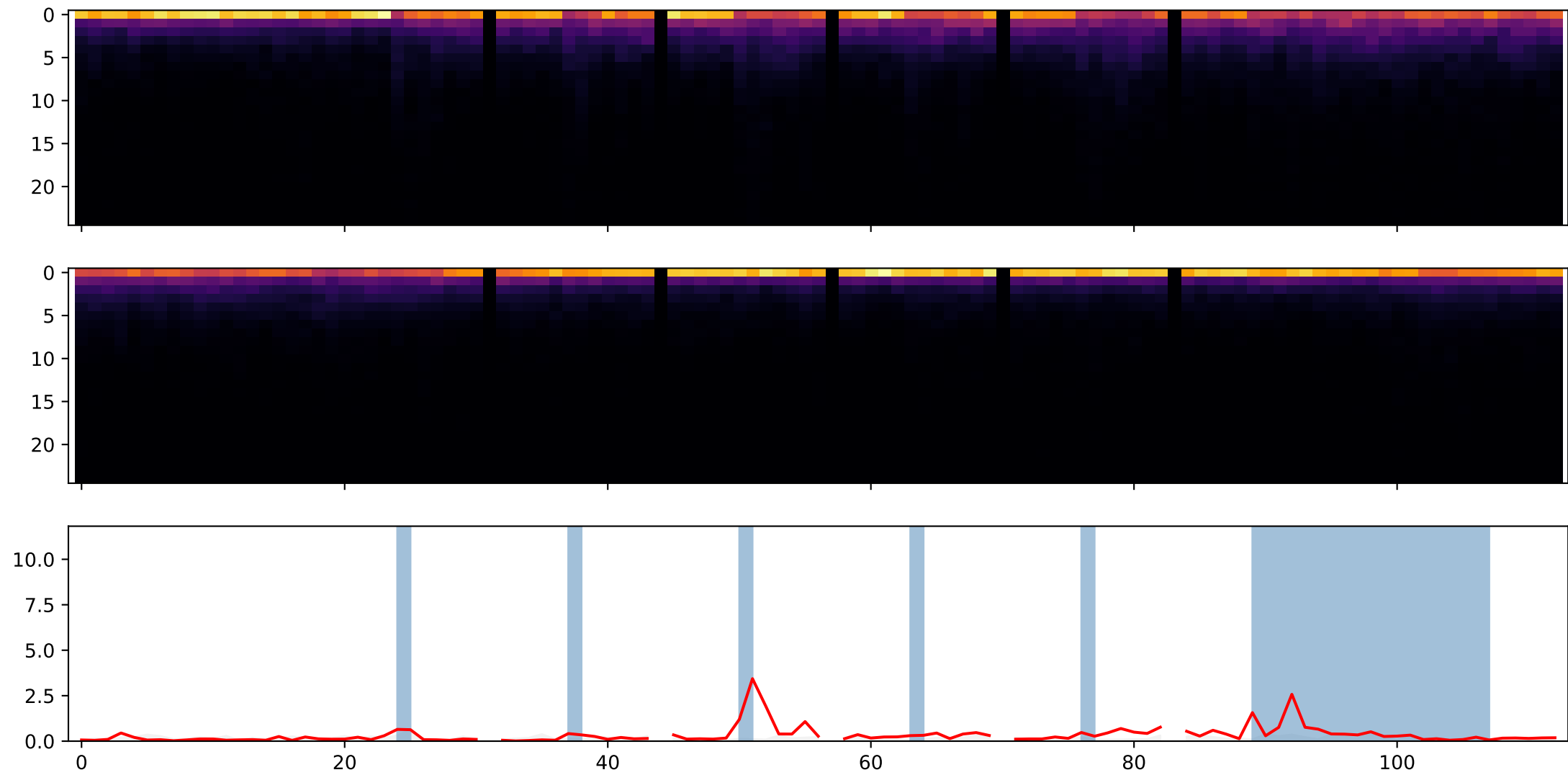
speed_tail_base



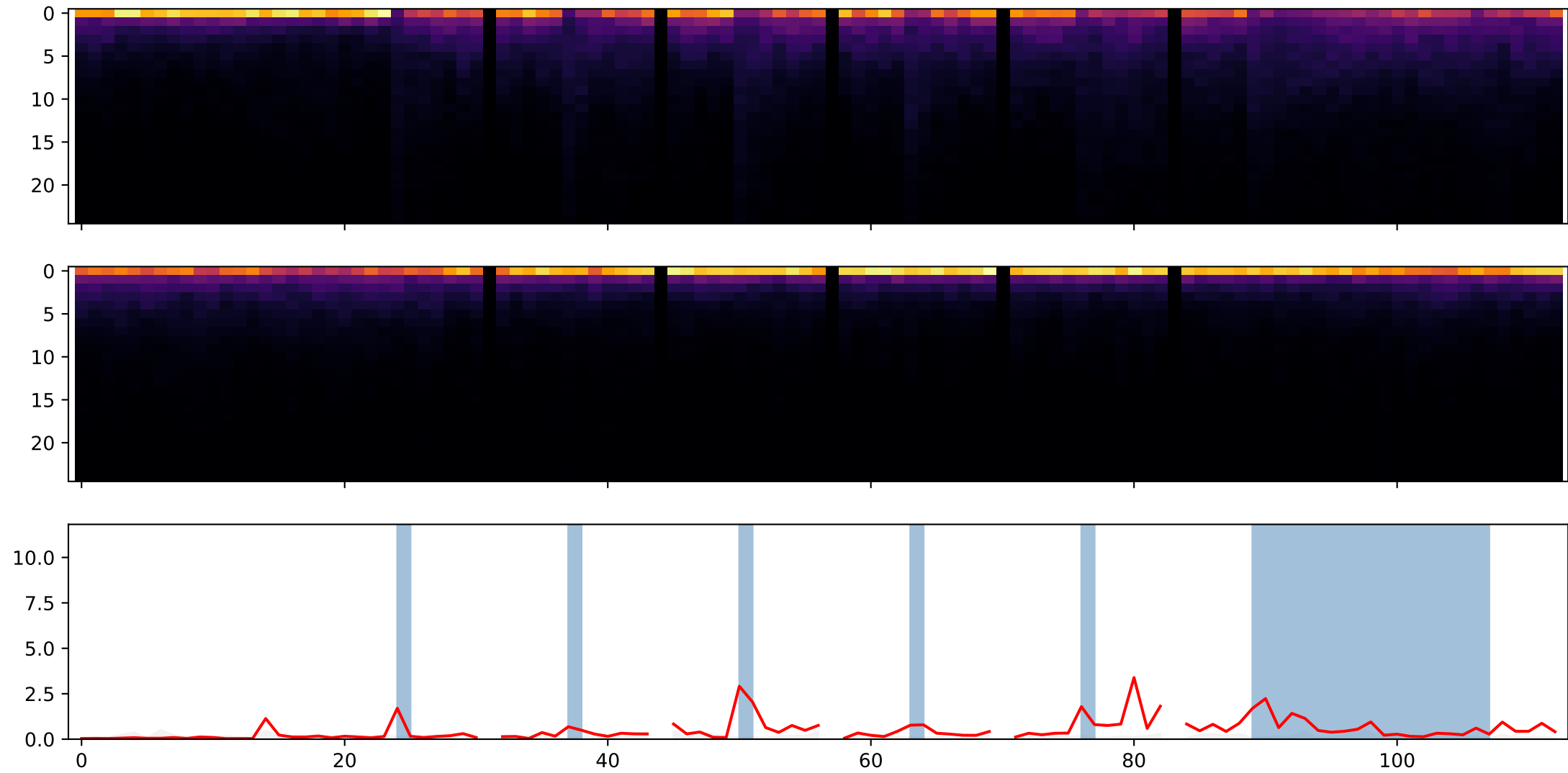
angular_velocity_hips



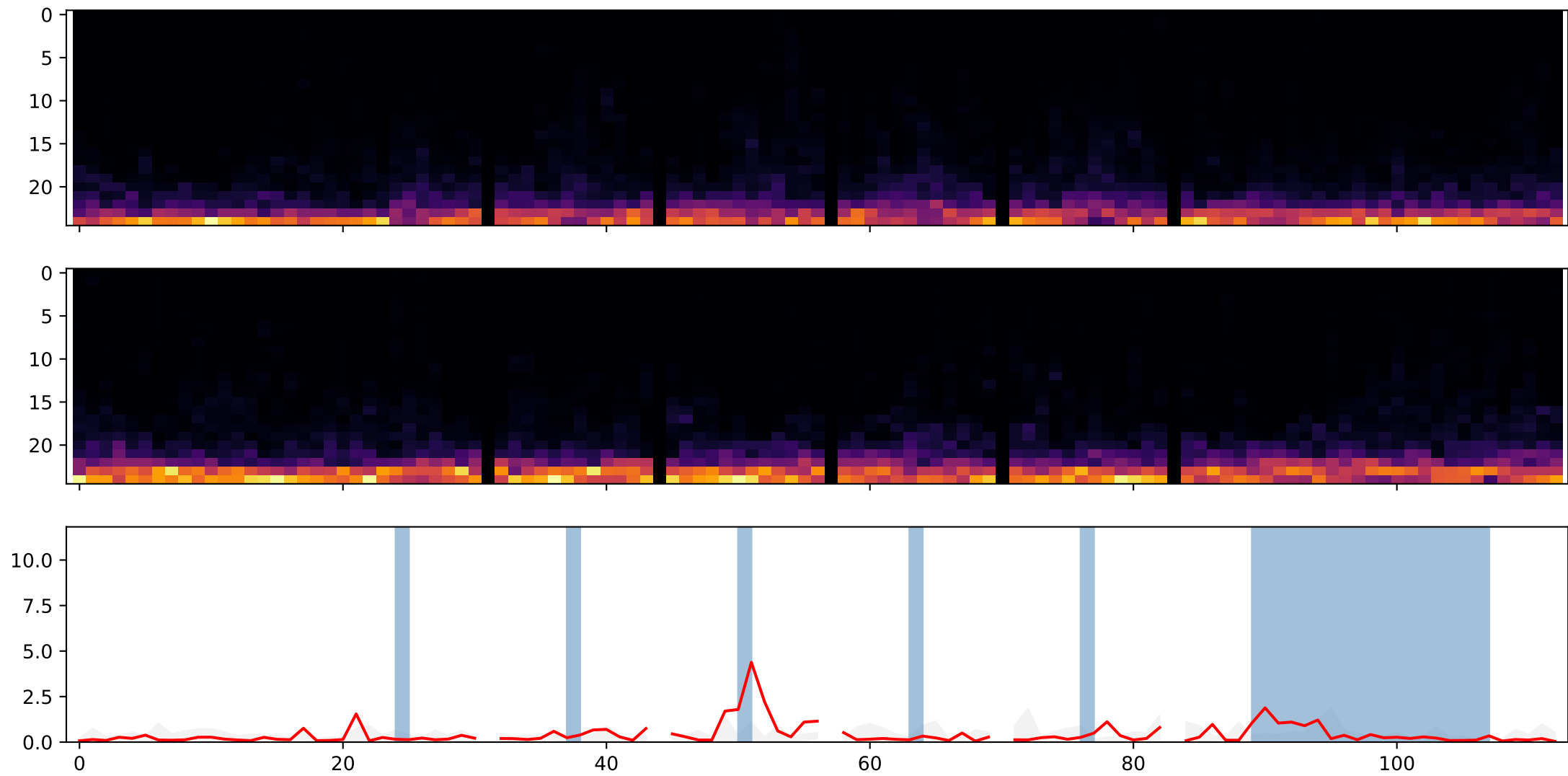
angular_velocity



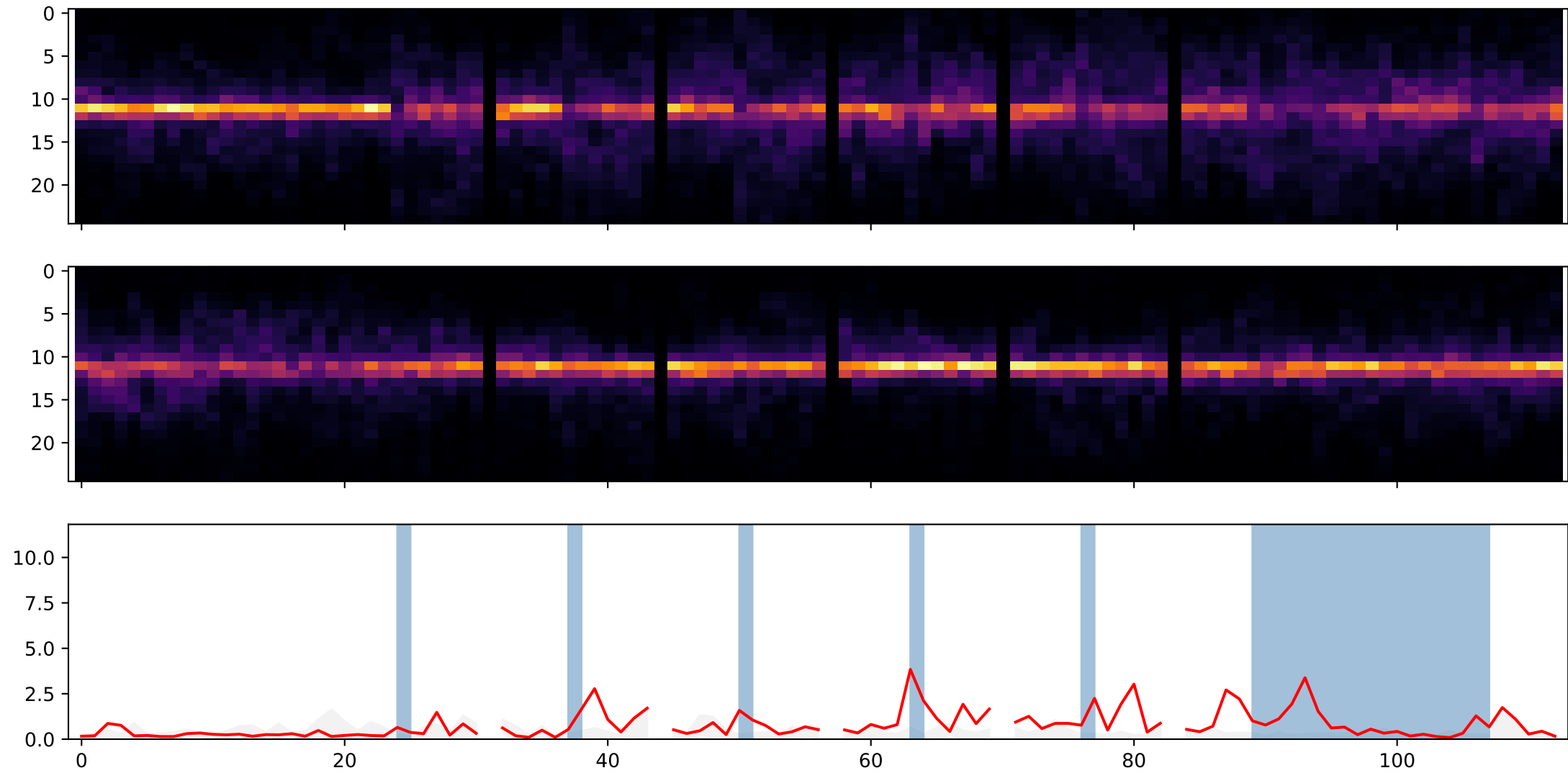
d_eigen_projection_2



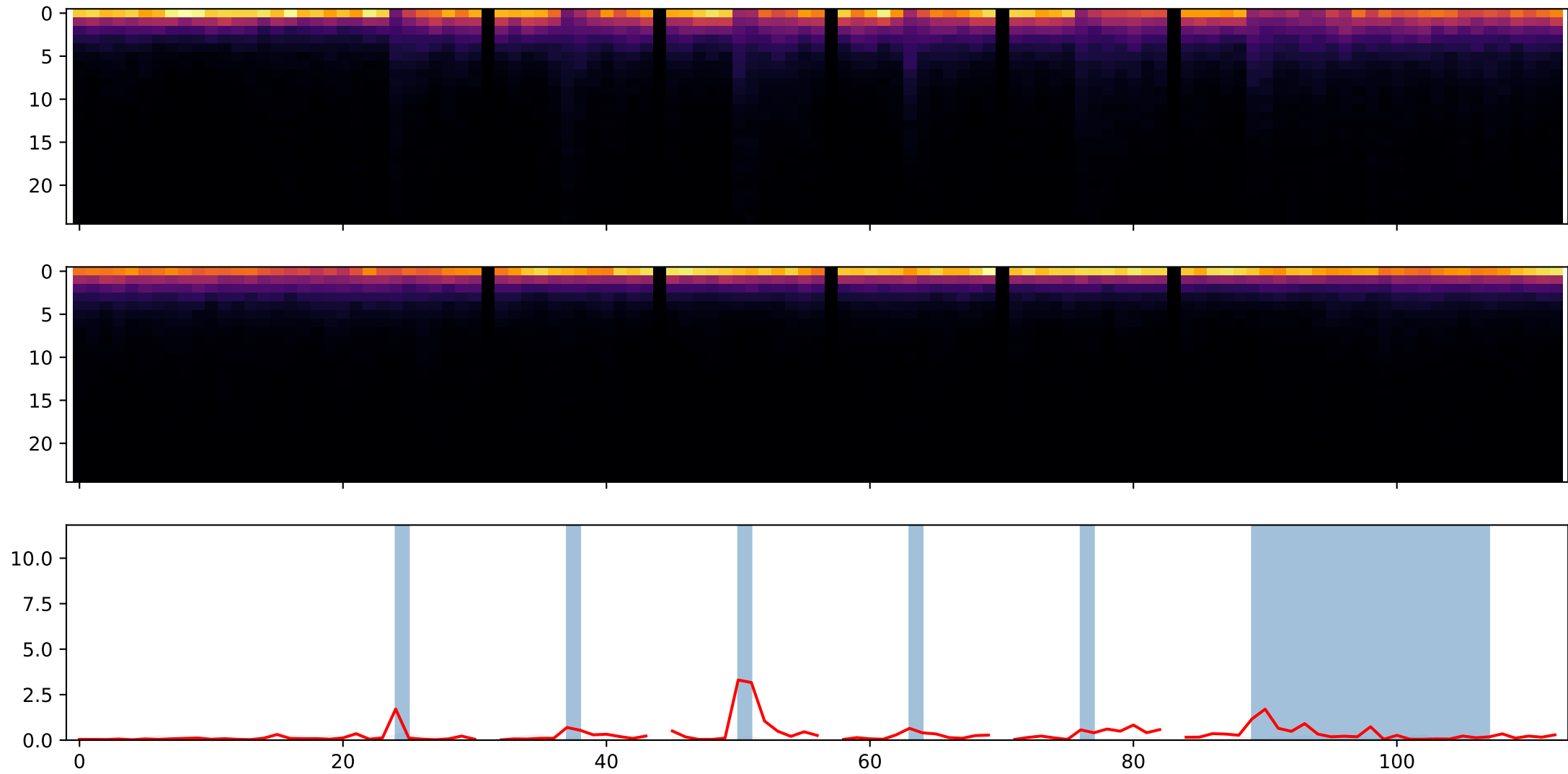
quirkiness



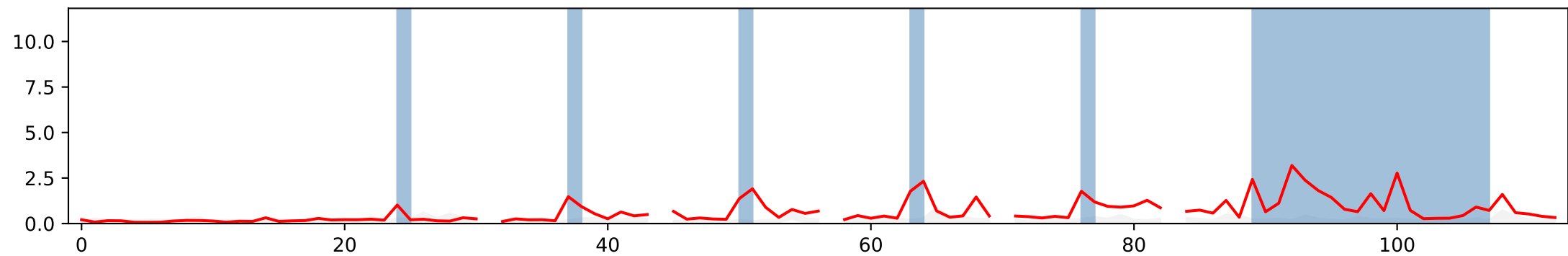
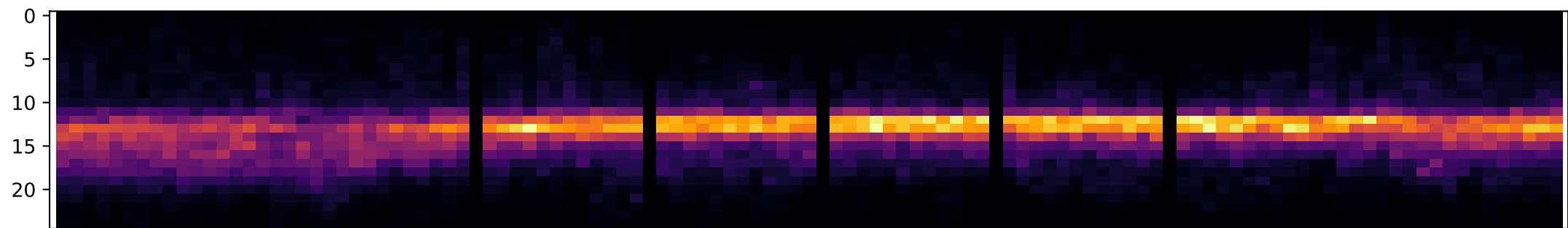
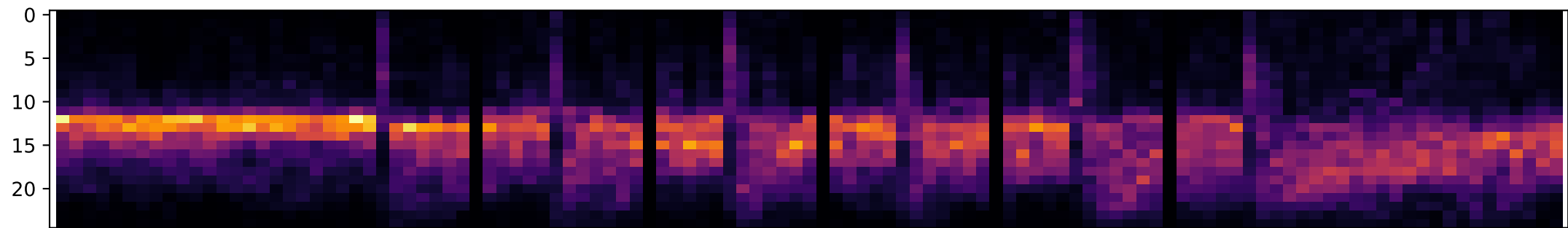
d_dist_from_food_edge



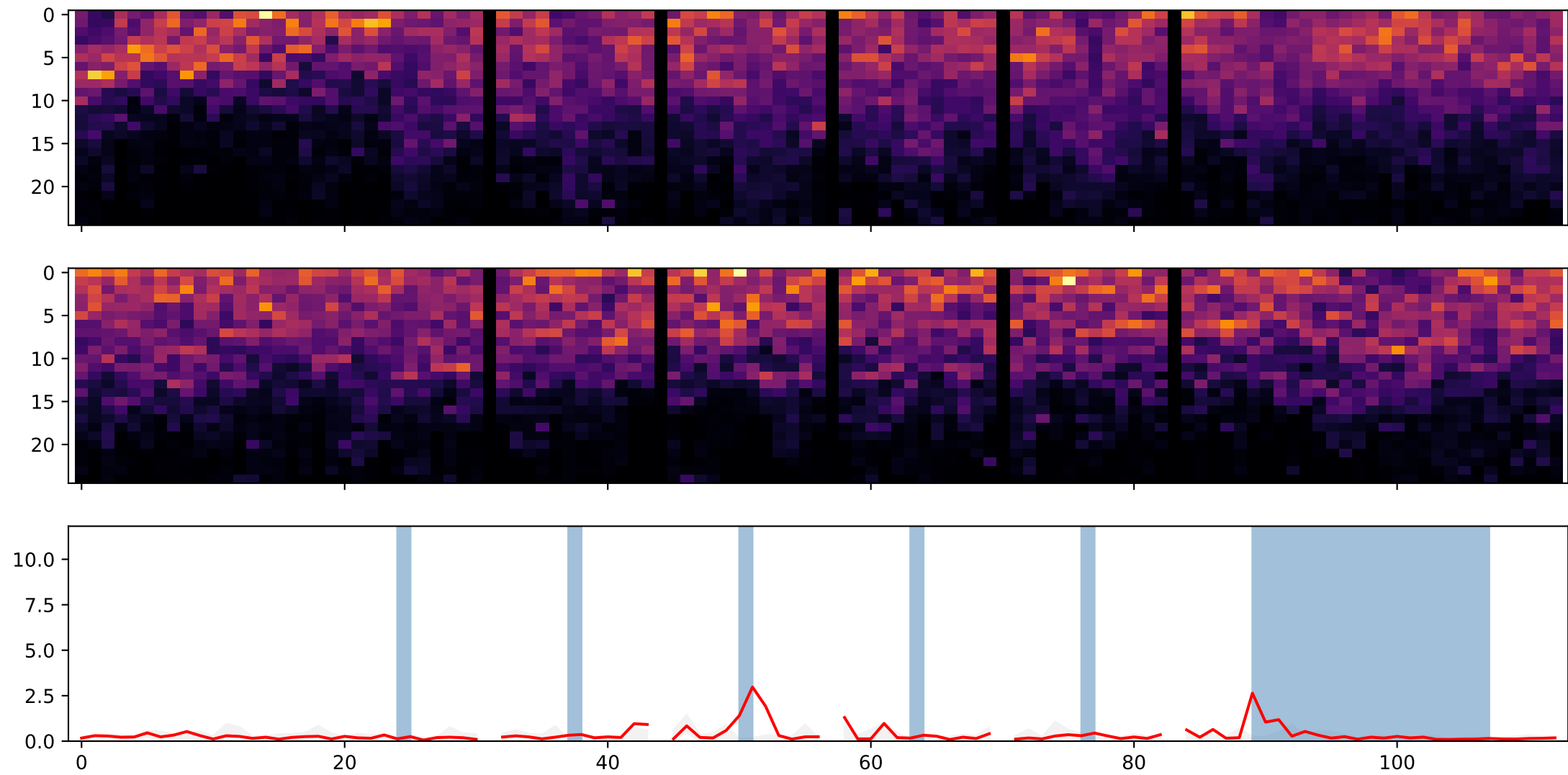
d_relative_to_body_angular_velocity_tail_tip



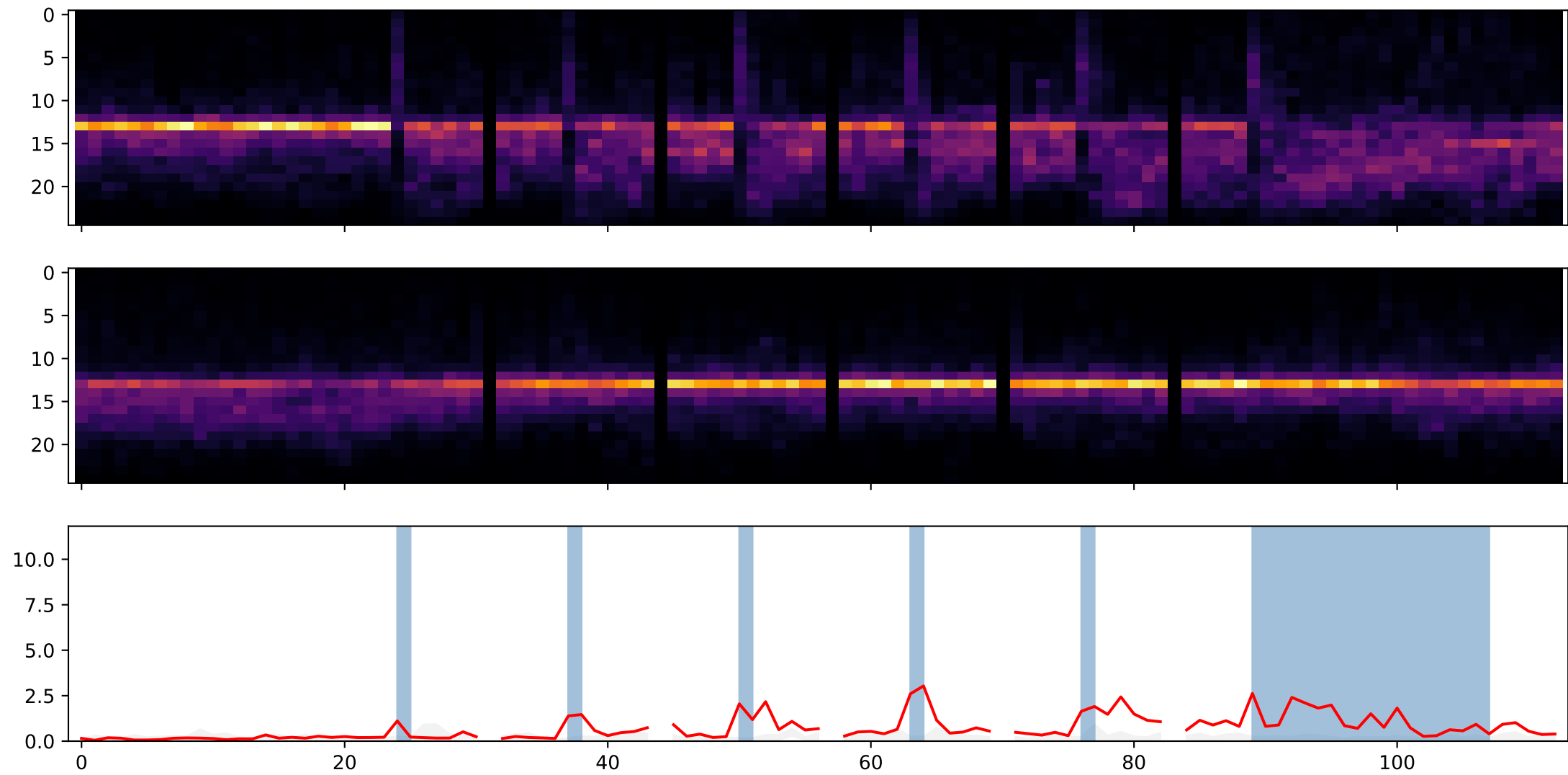
speed_head_base



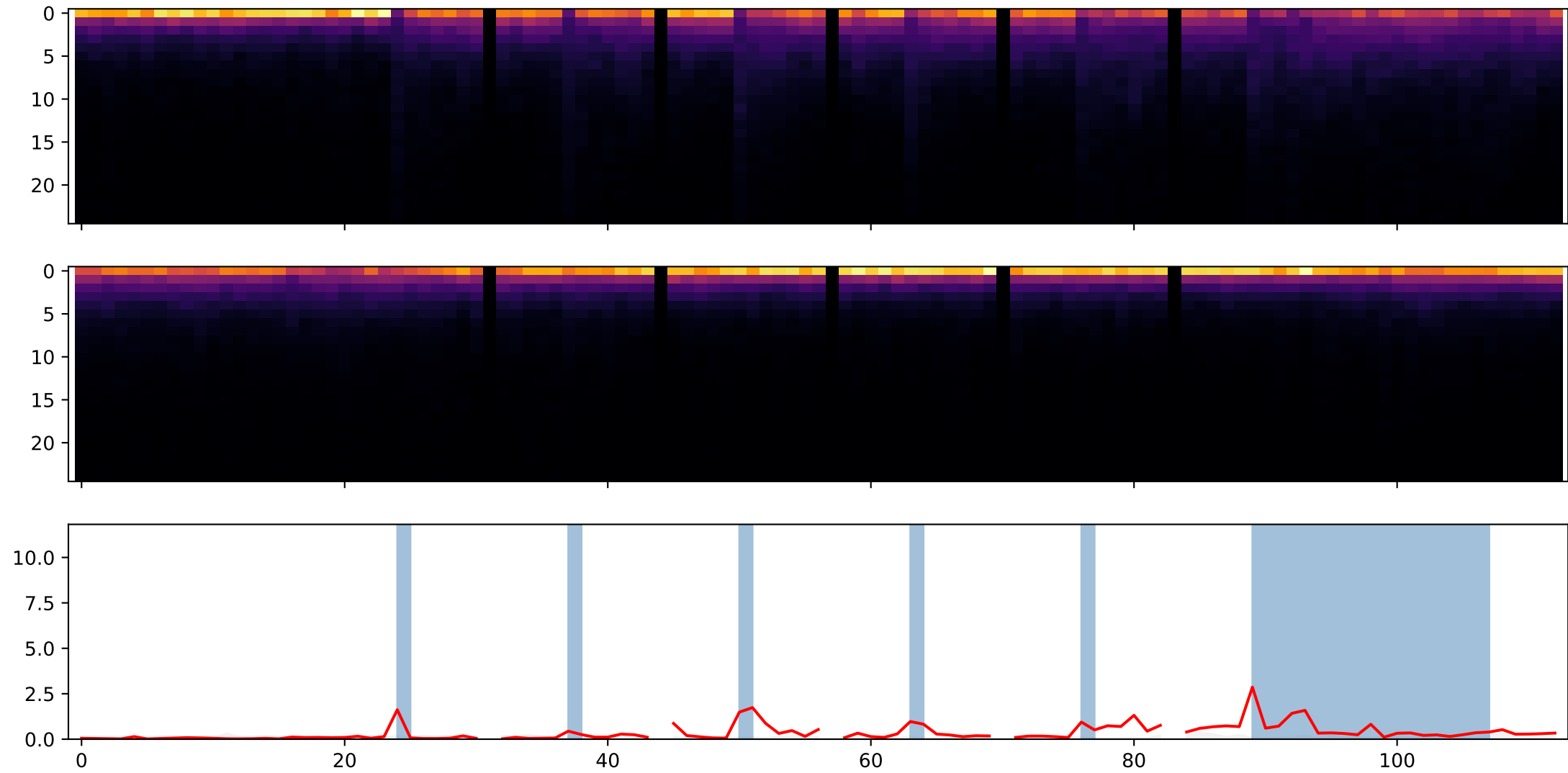
eigen_projection_2



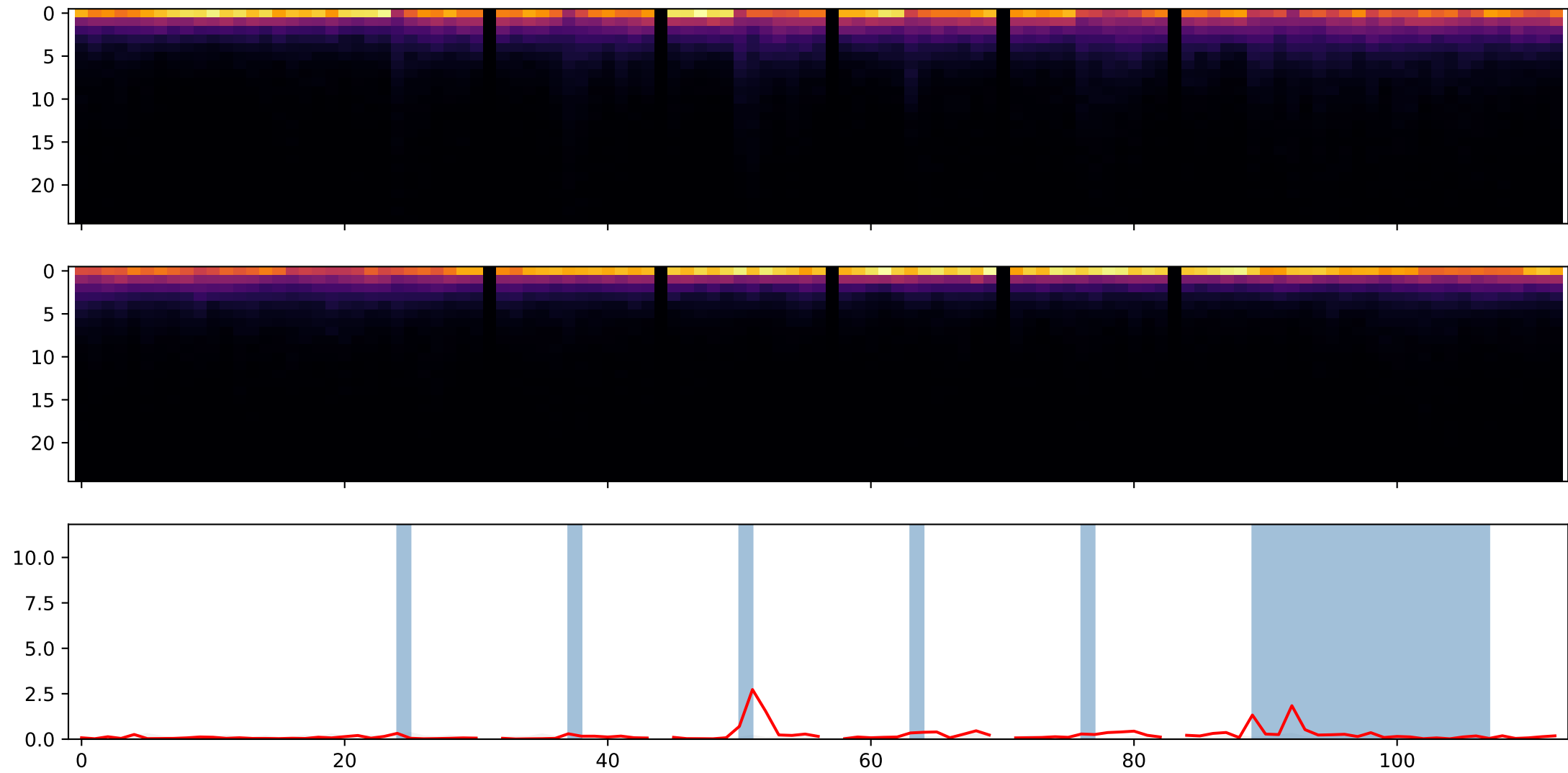
speed_hips



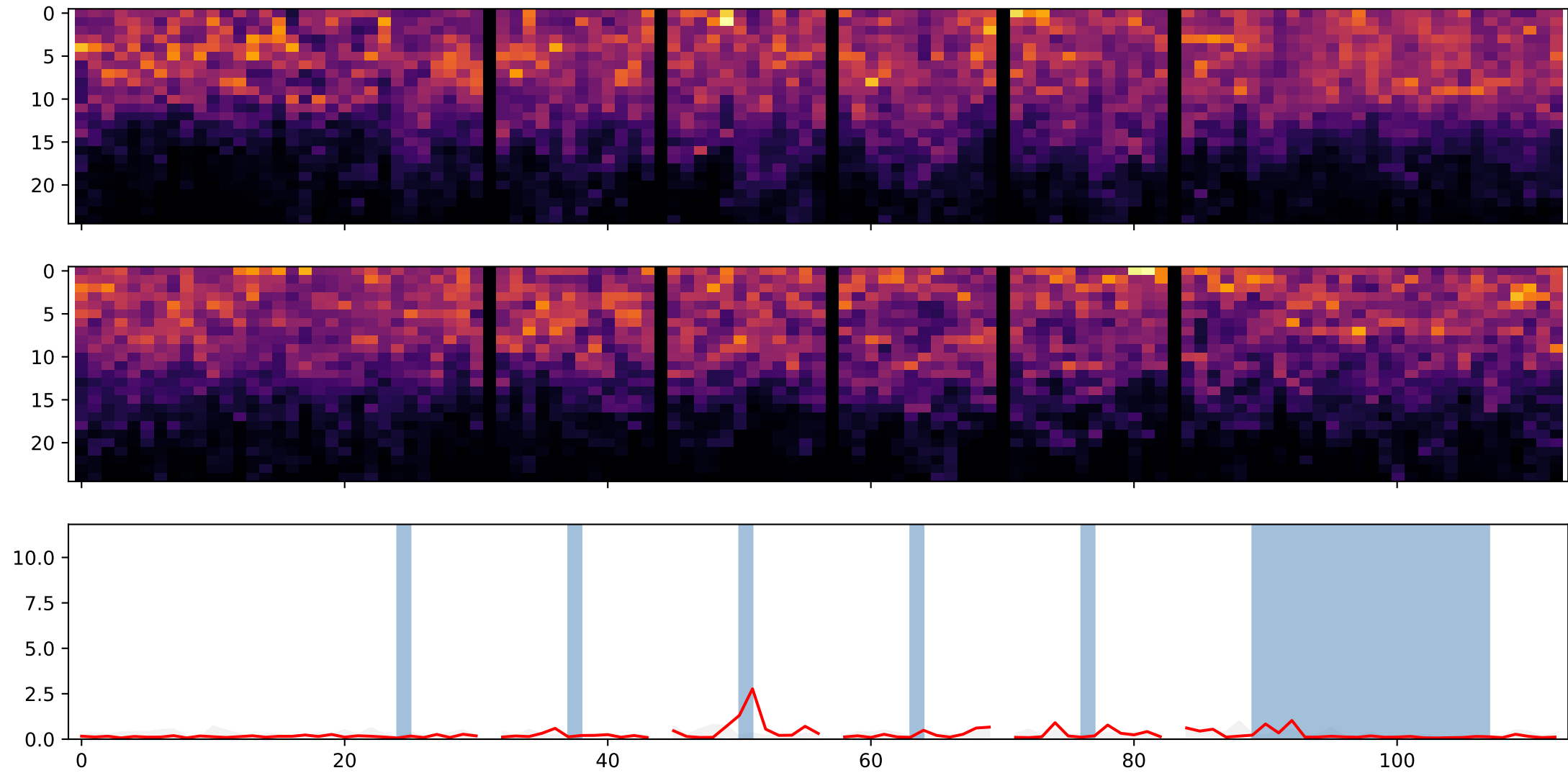
d_angular_velocity_hips



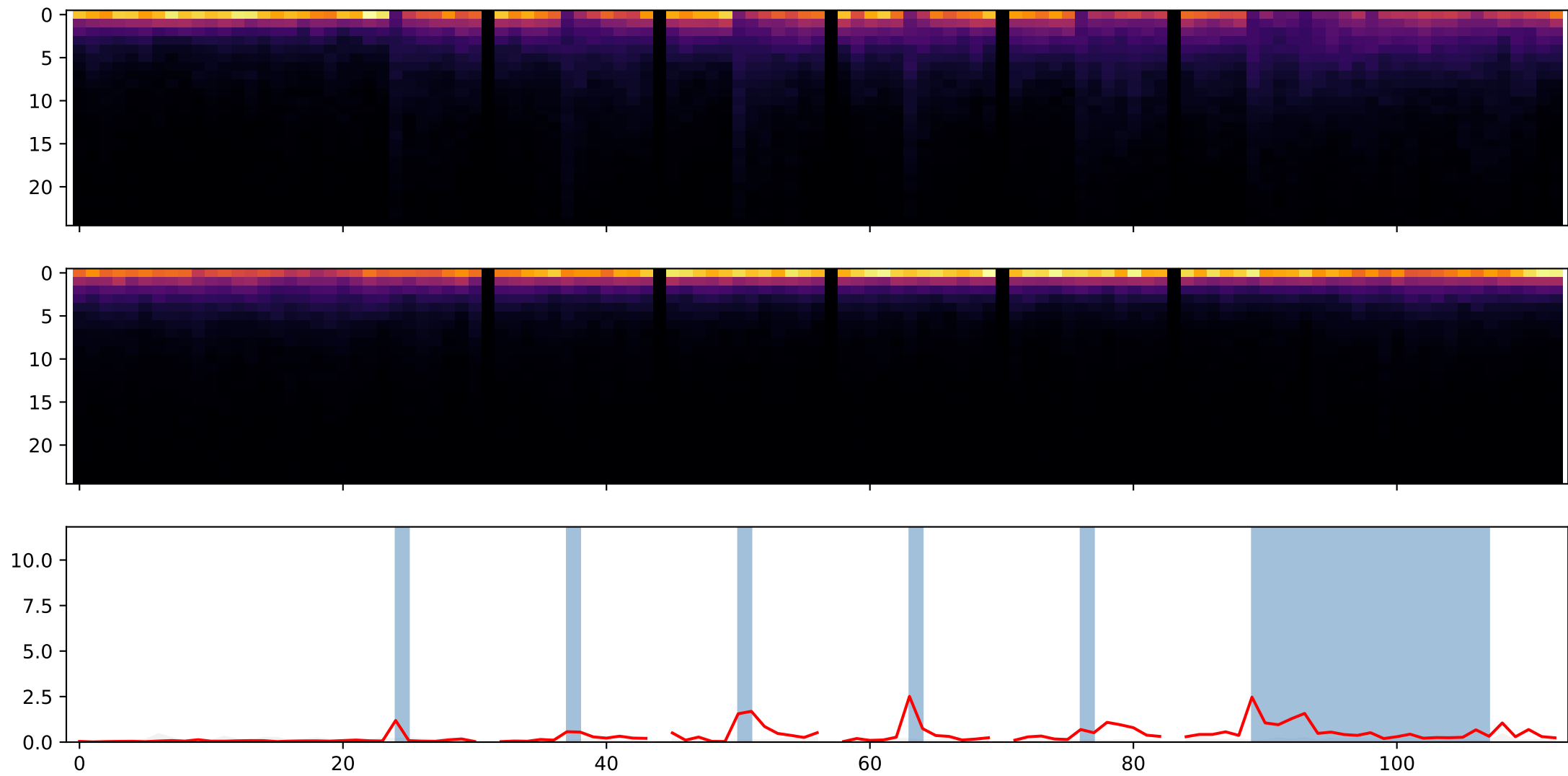
d_angular_velocity



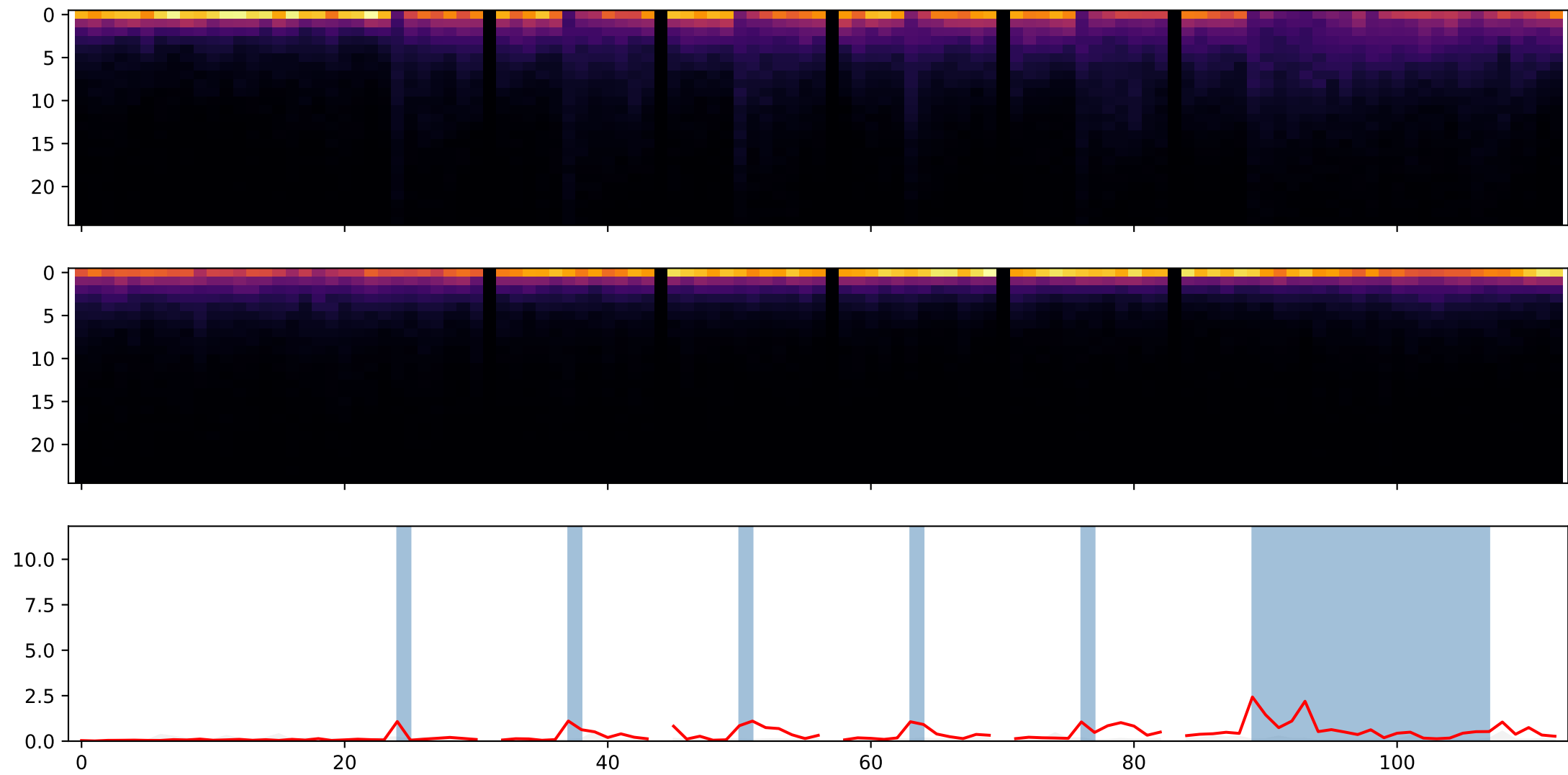
curvature_mean_midbody



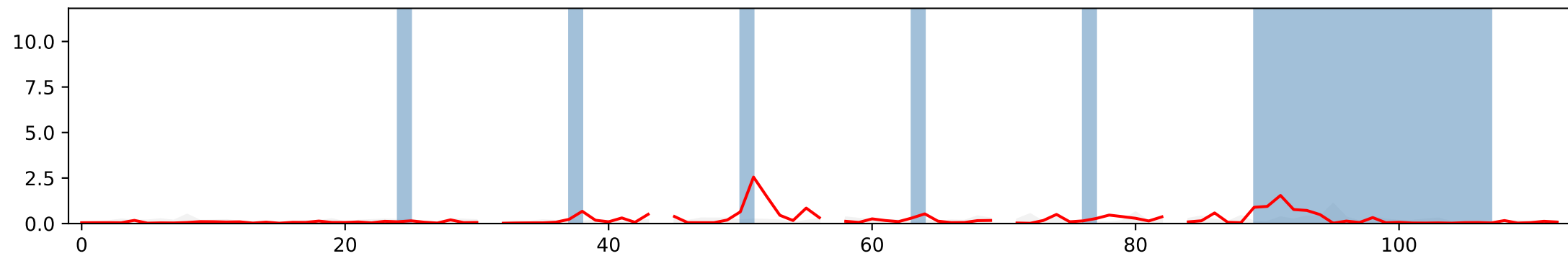
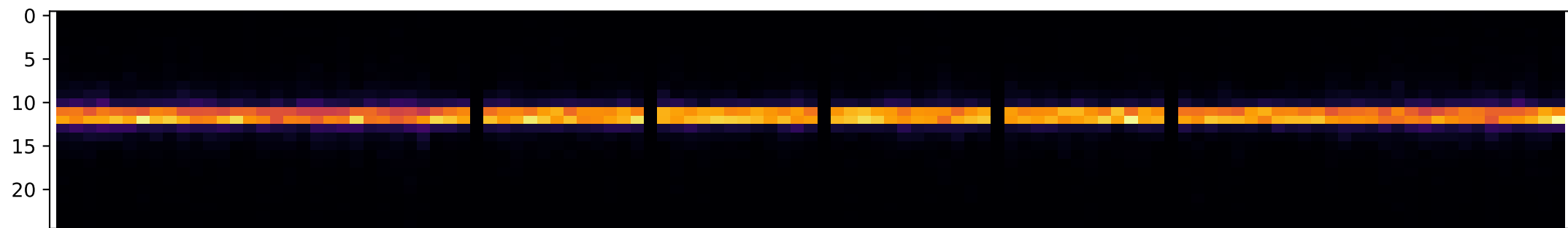
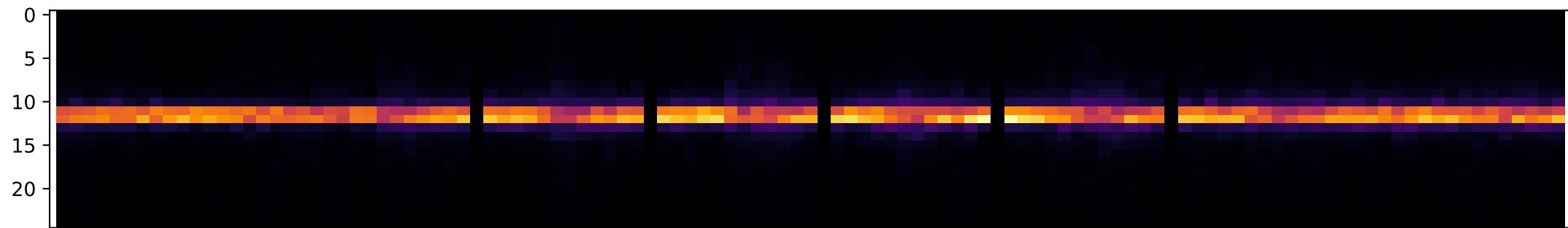
d_relative_to_body_angular_velocity_neck



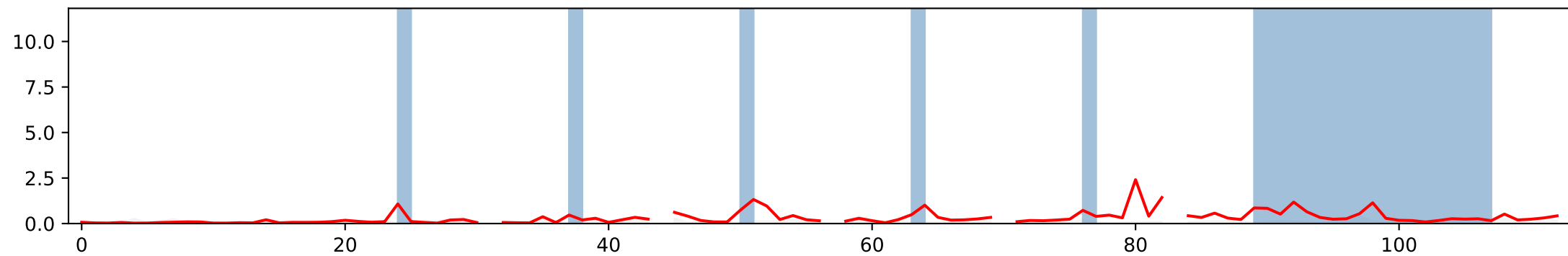
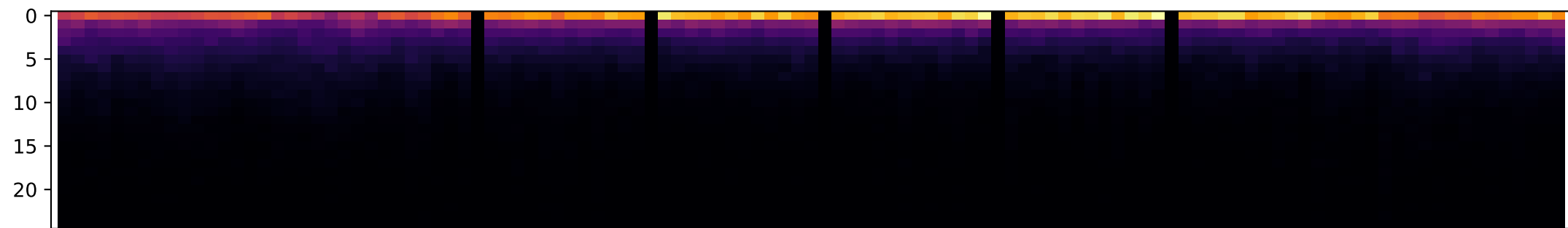
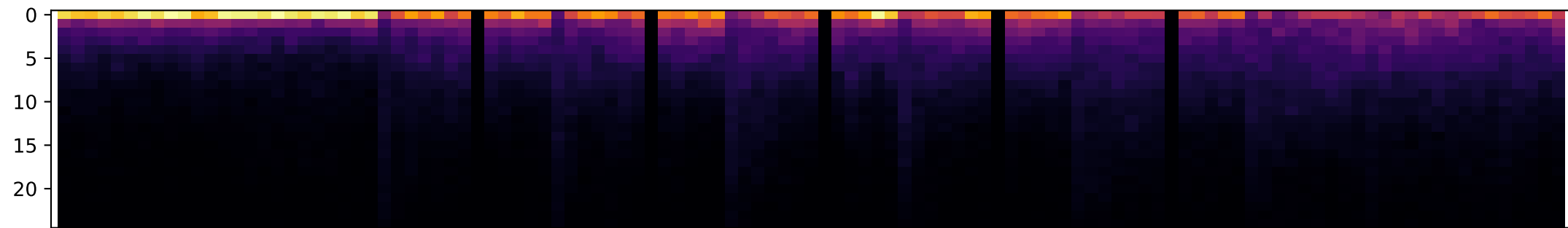
d_relative_to_body_speed_midbody



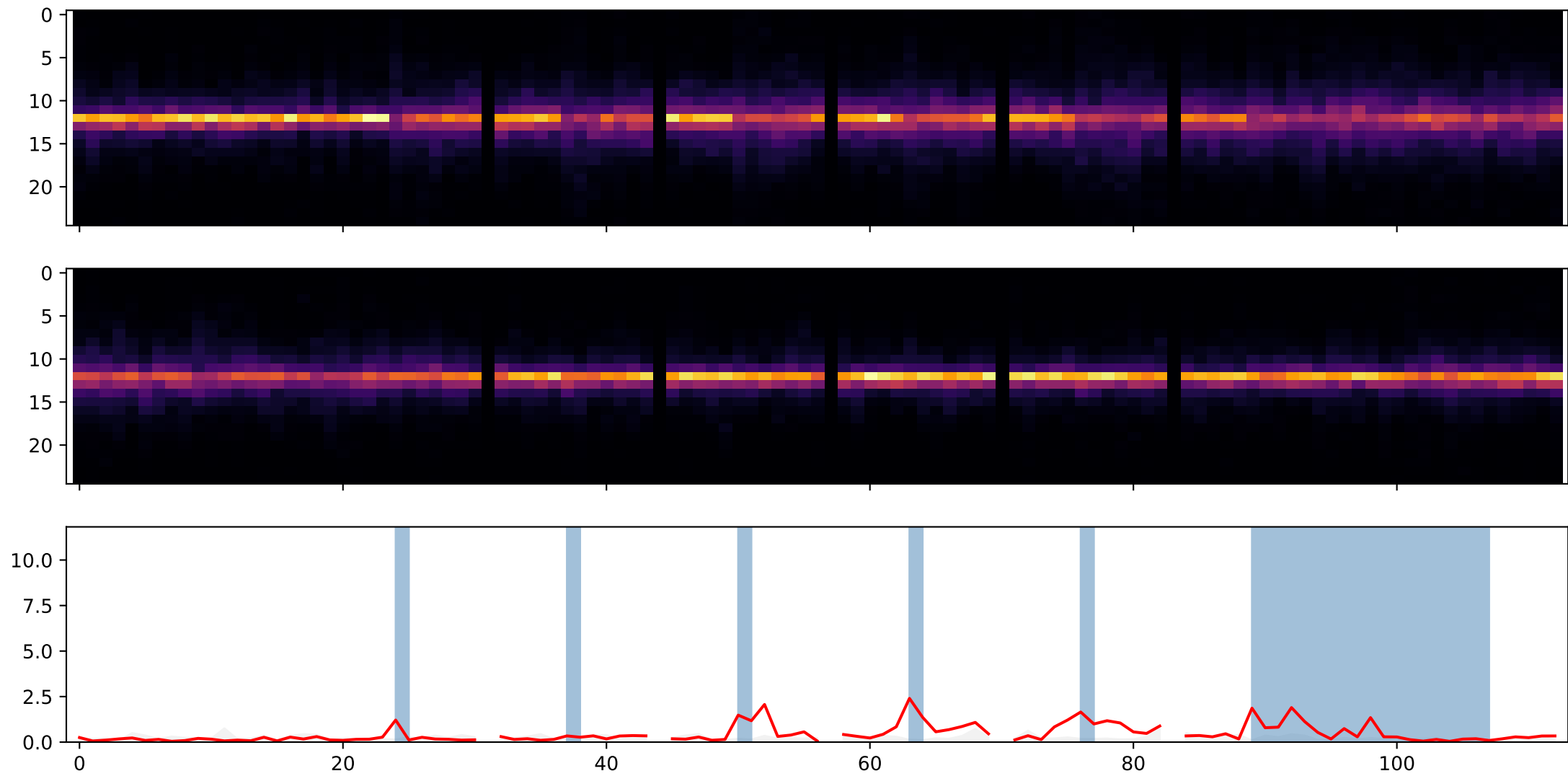
d_quirkiness



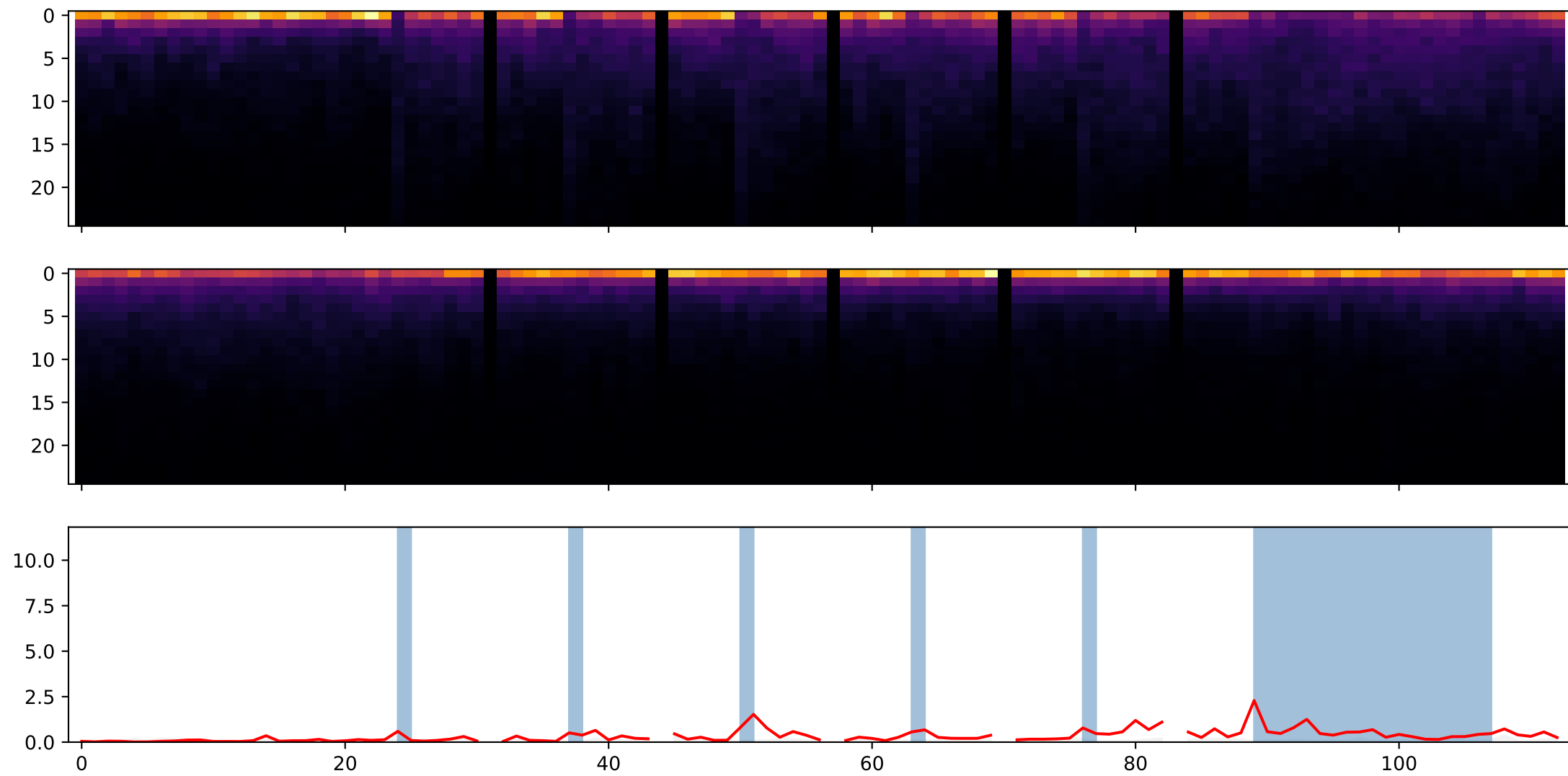
angular_velocity_tail_base



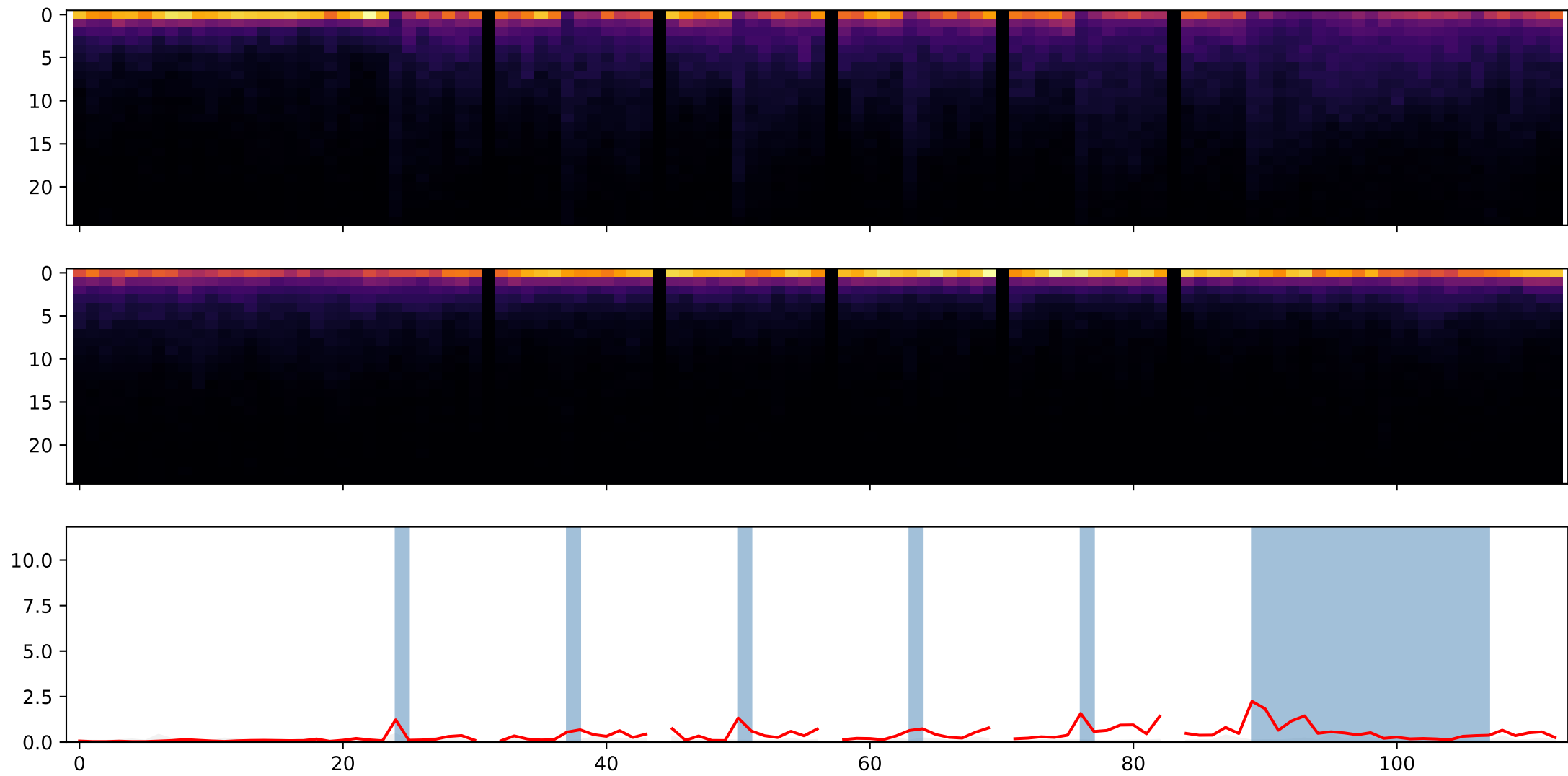
d_orientation_food_edge



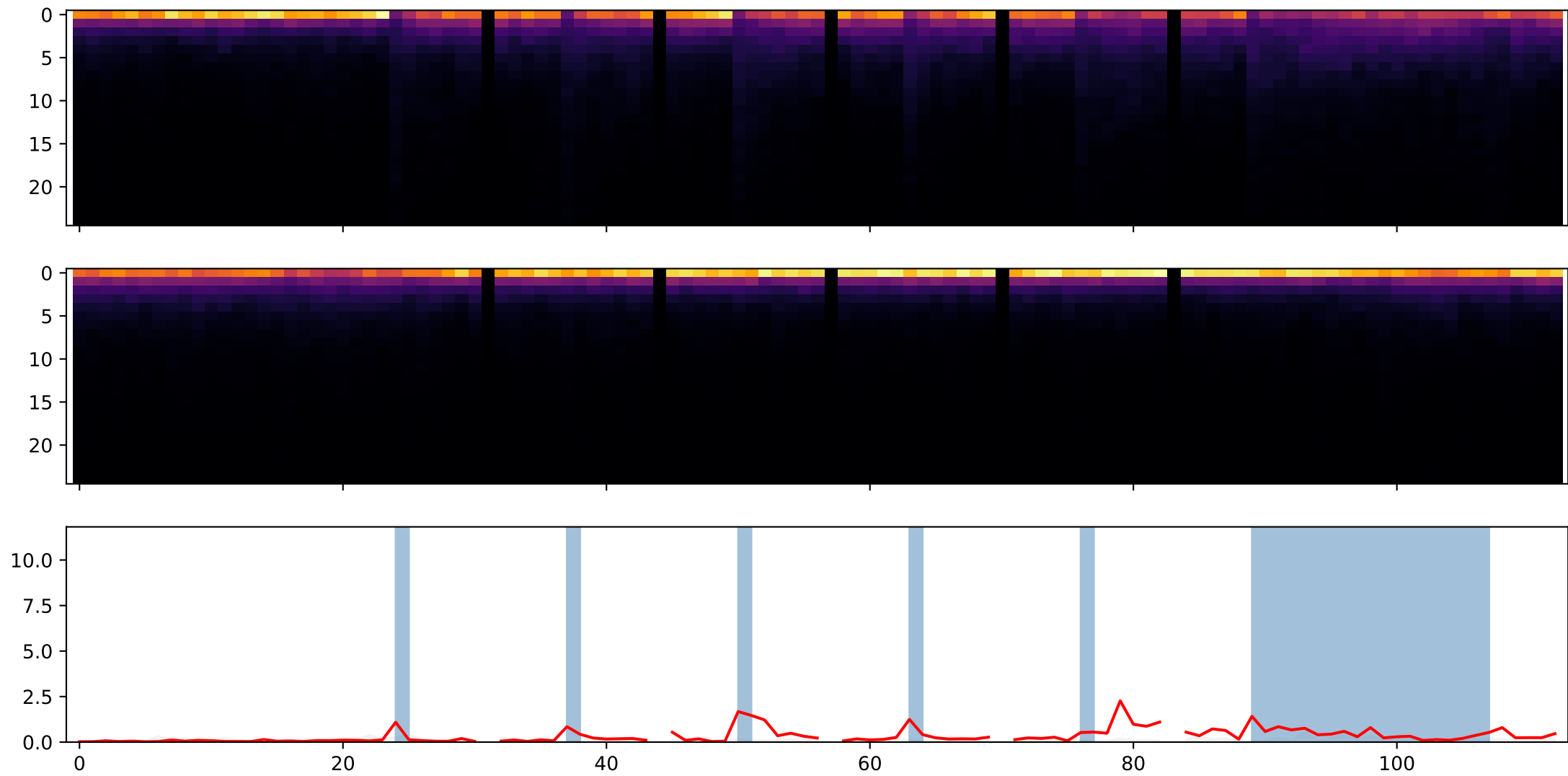
d_curvature_mean_hips



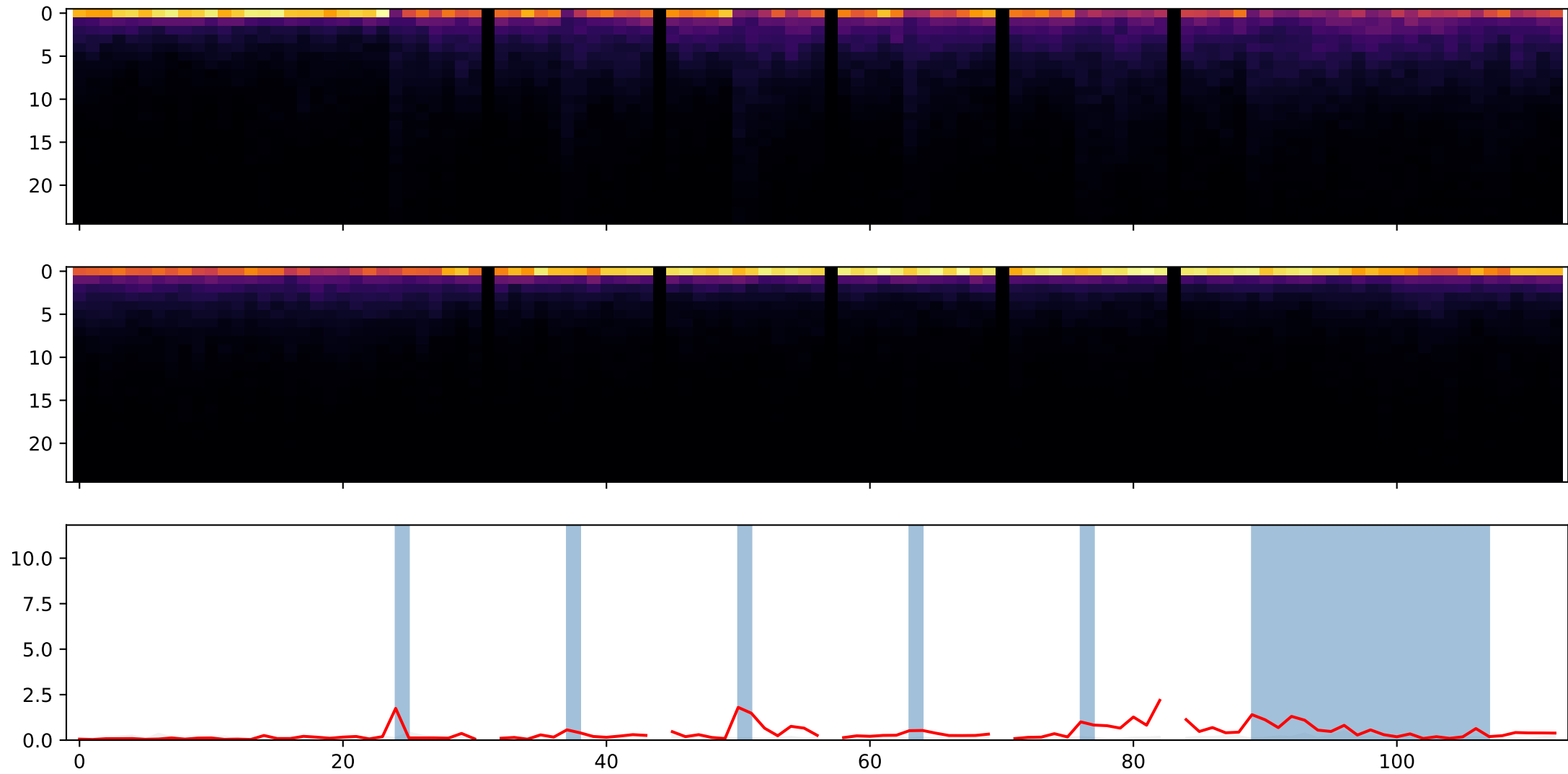
d_curvature_mean_midbody



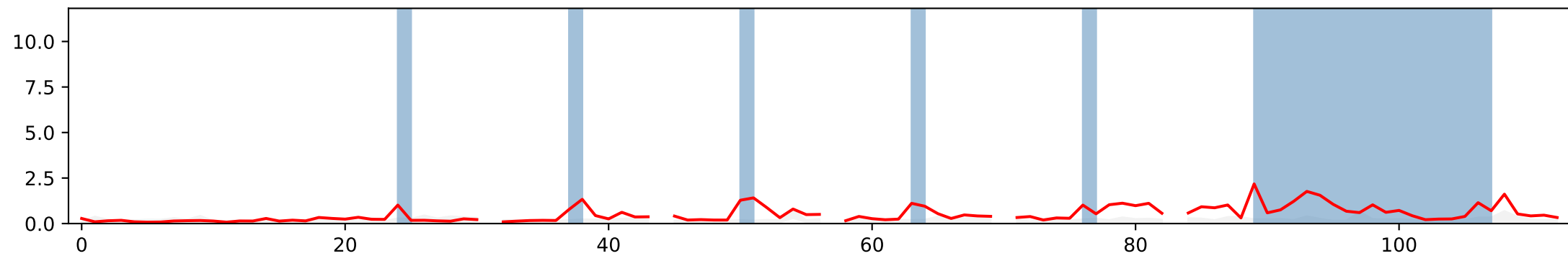
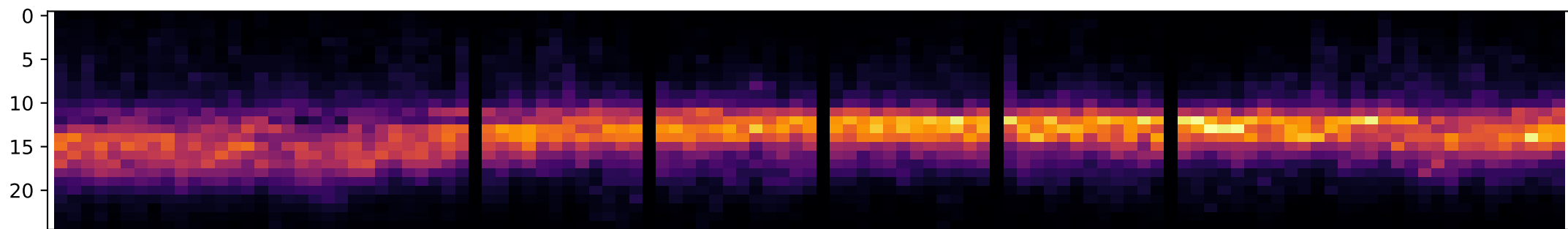
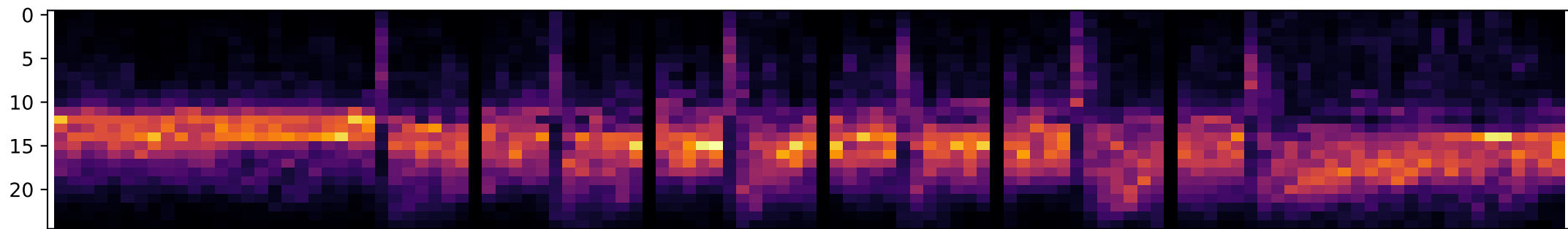
d_angular_velocity_midbody



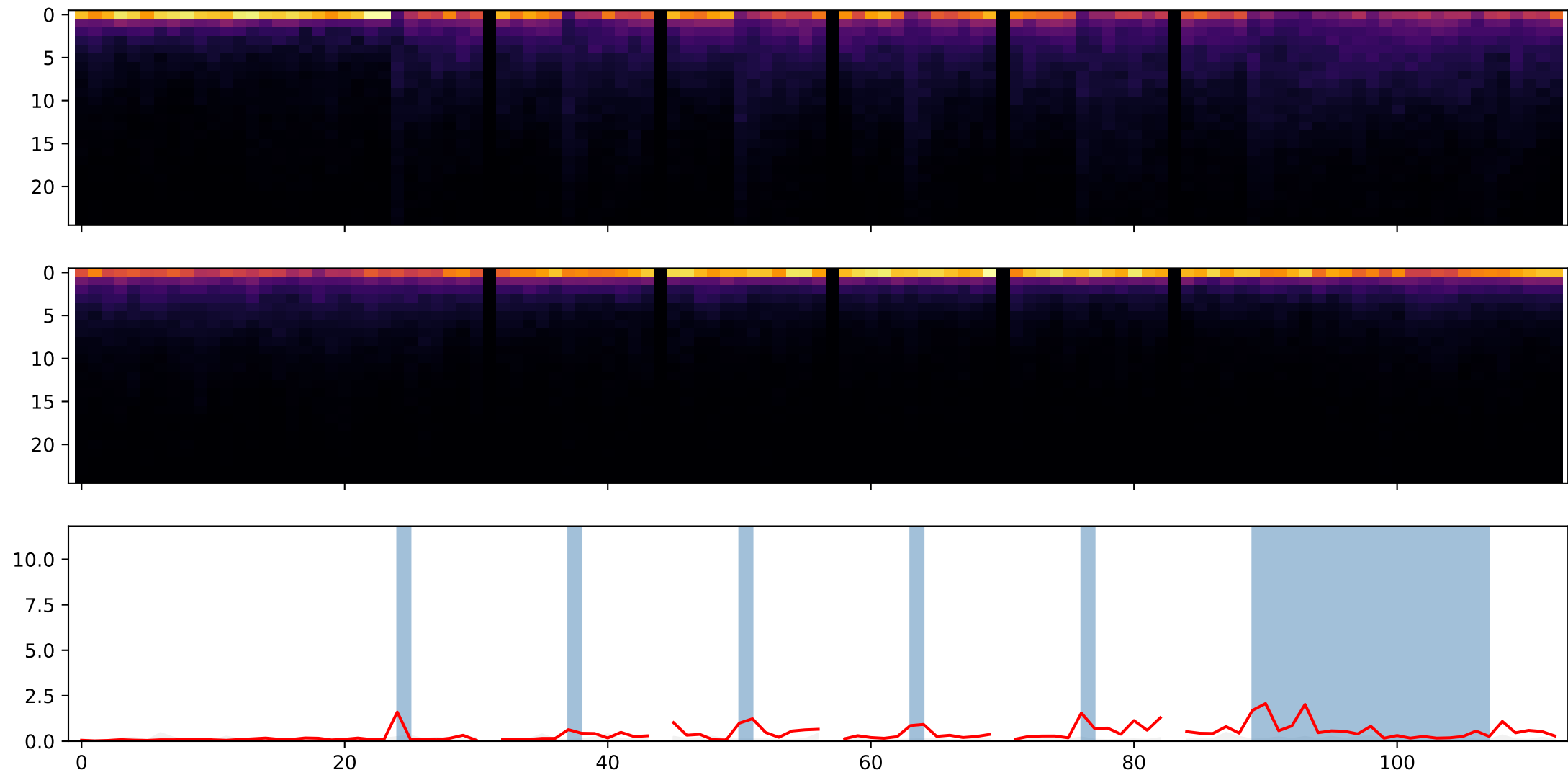
angular_velocity_midbody



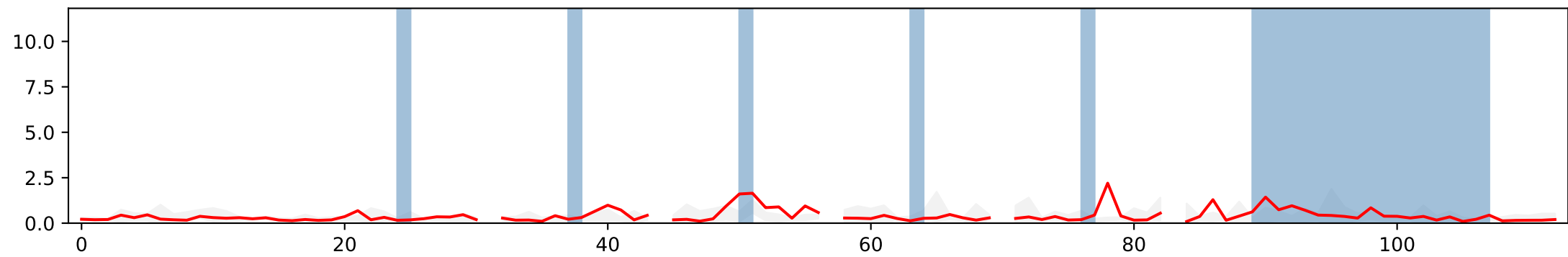
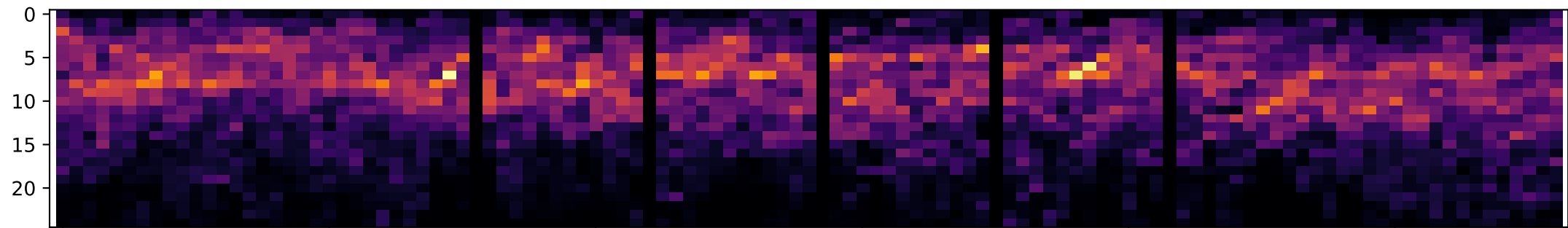
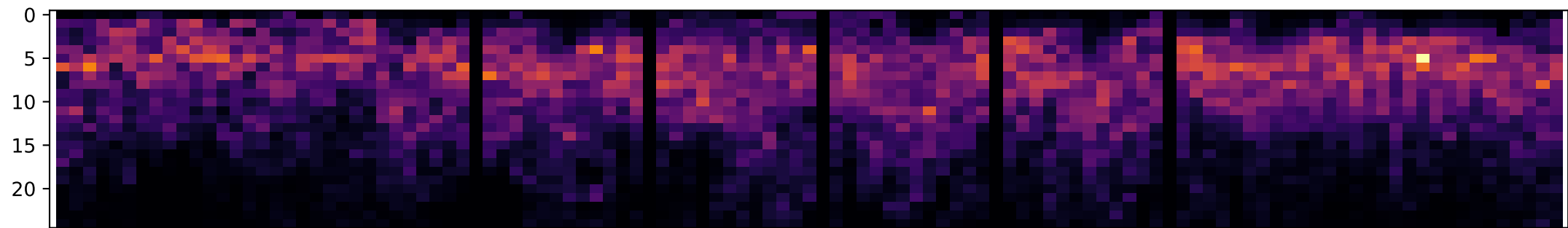
speed_head_tip



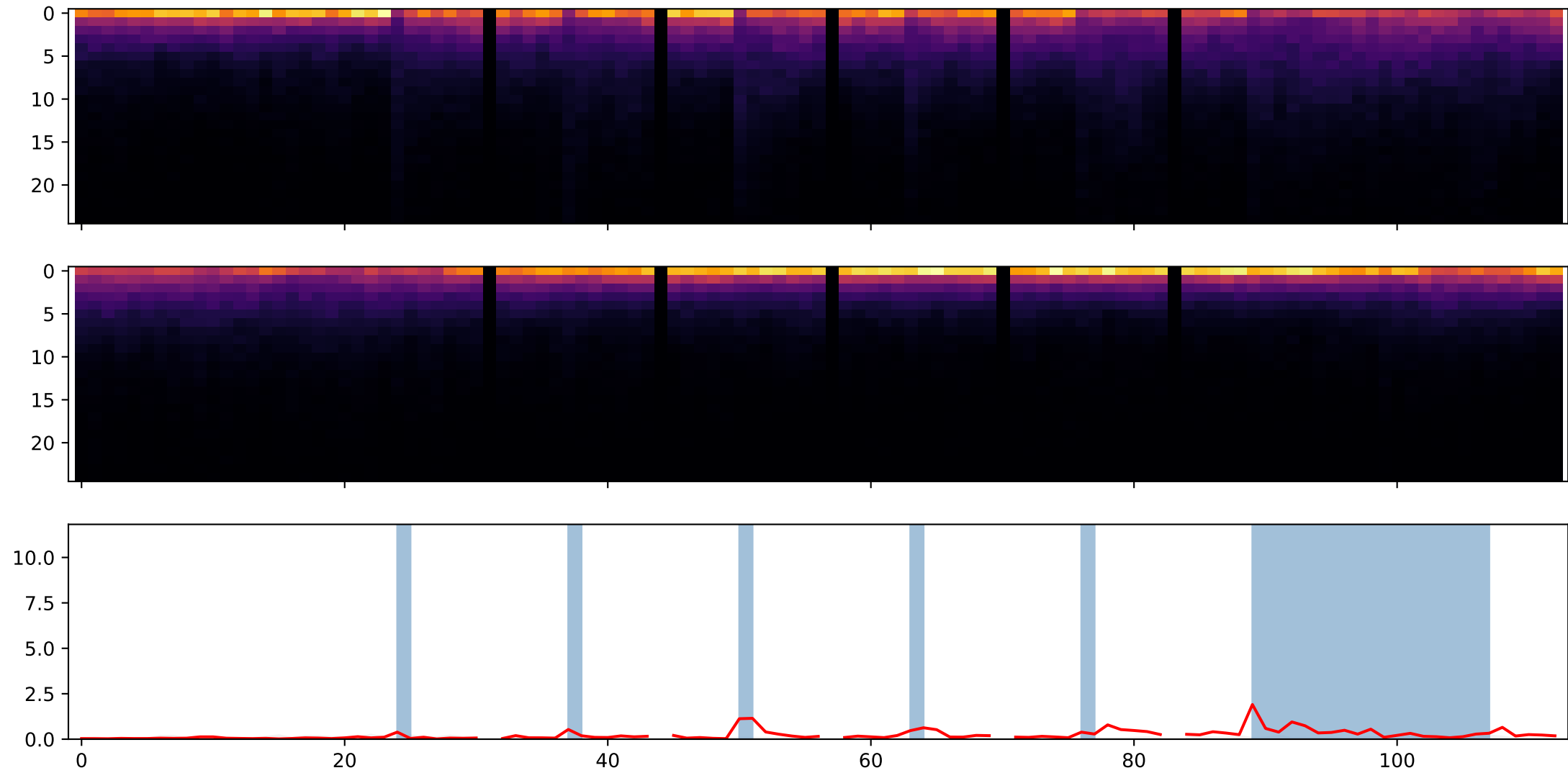
relative_to_body_angular_velocity_neck



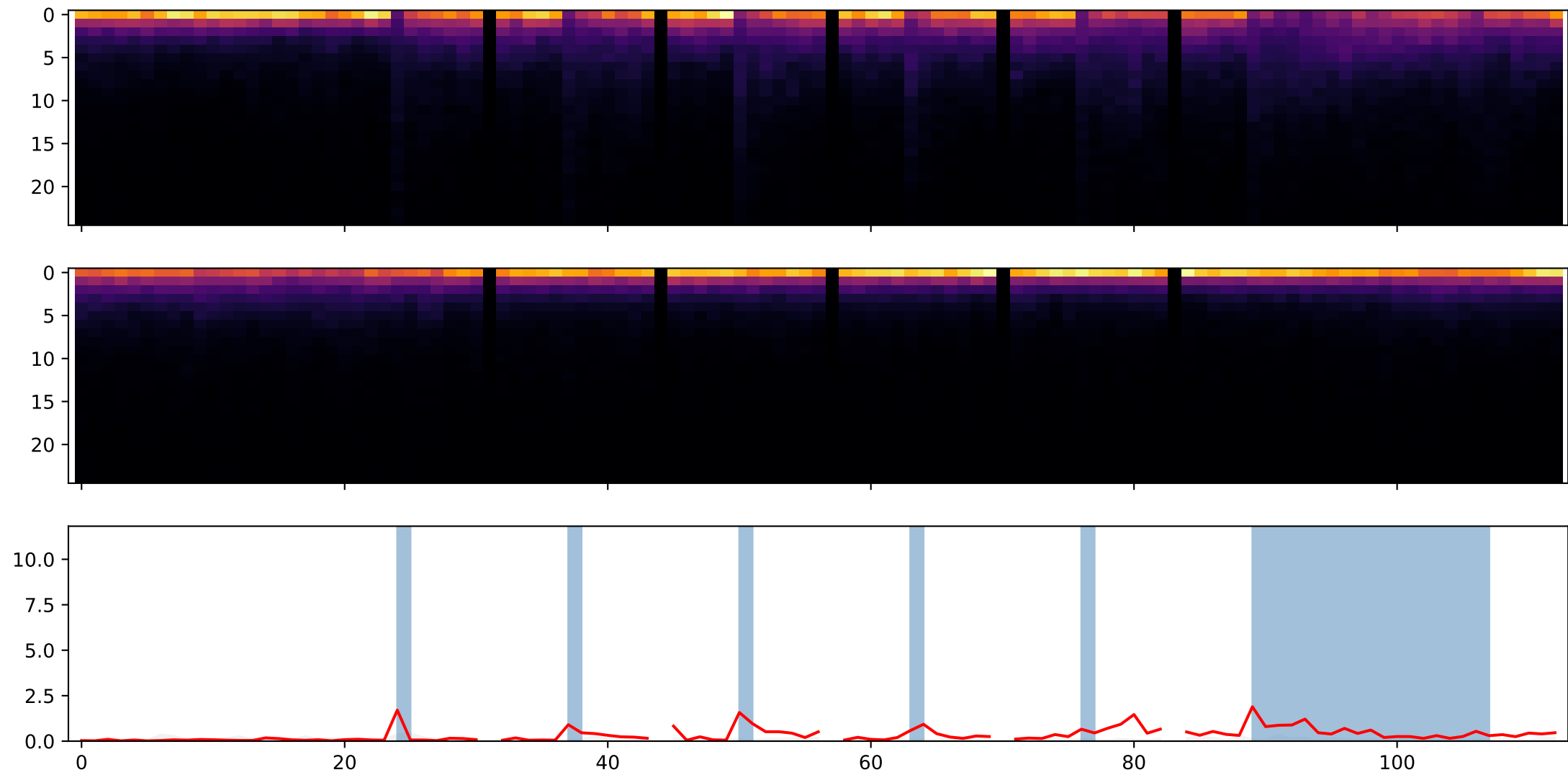
minor_axis



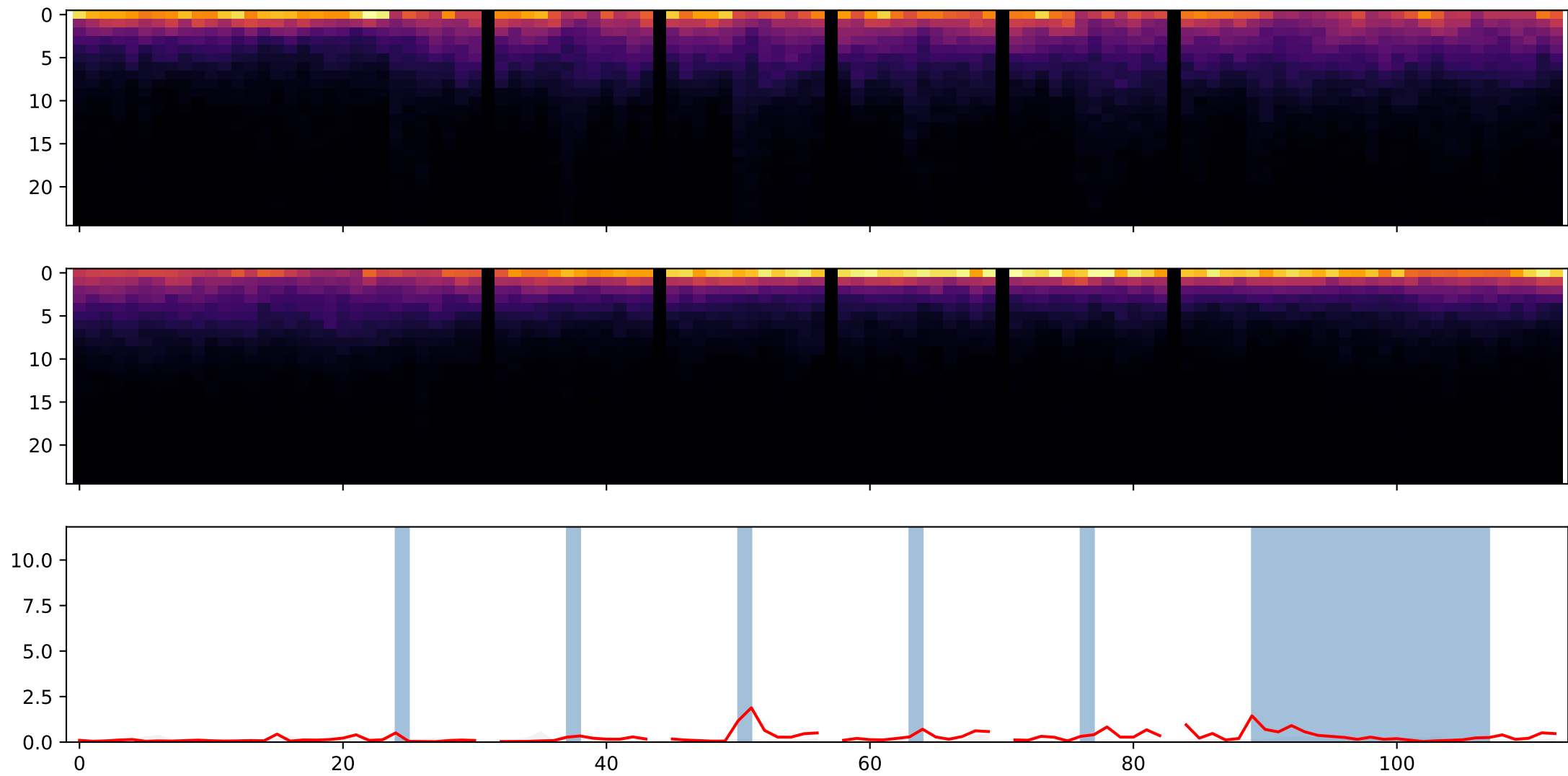
d_angular_velocity_neck



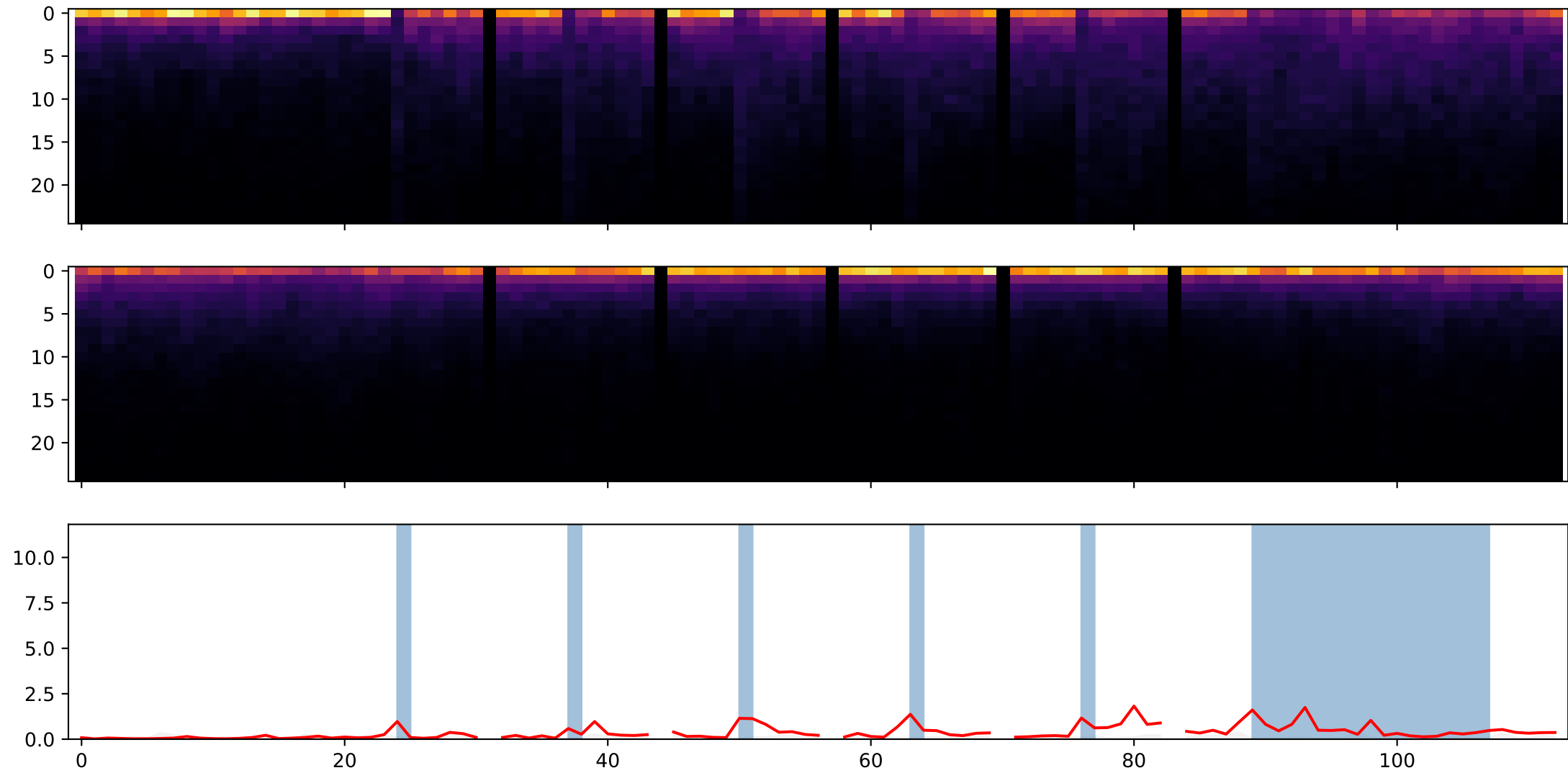
d_relative_to_body_angular_velocity_hips



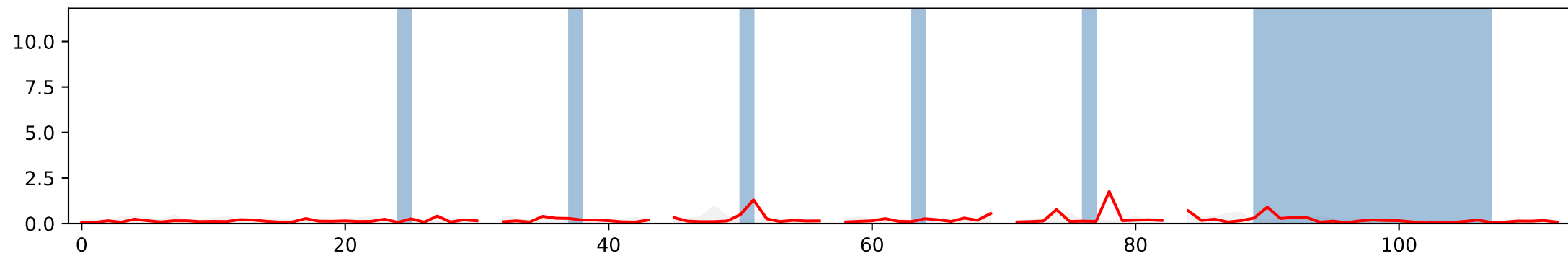
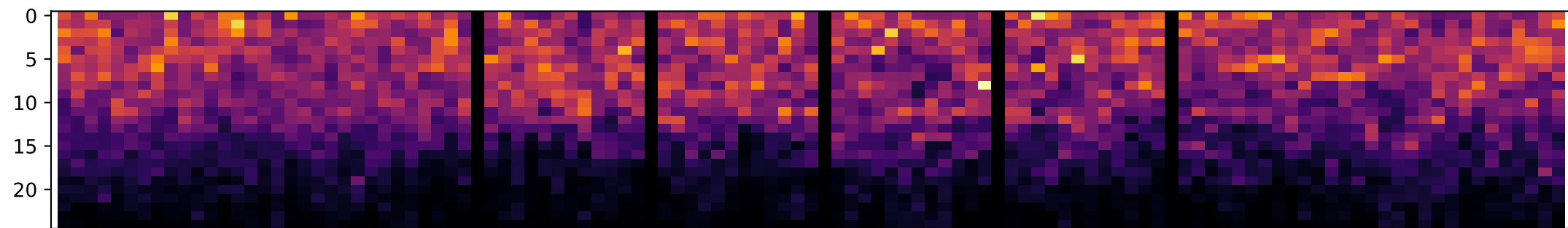
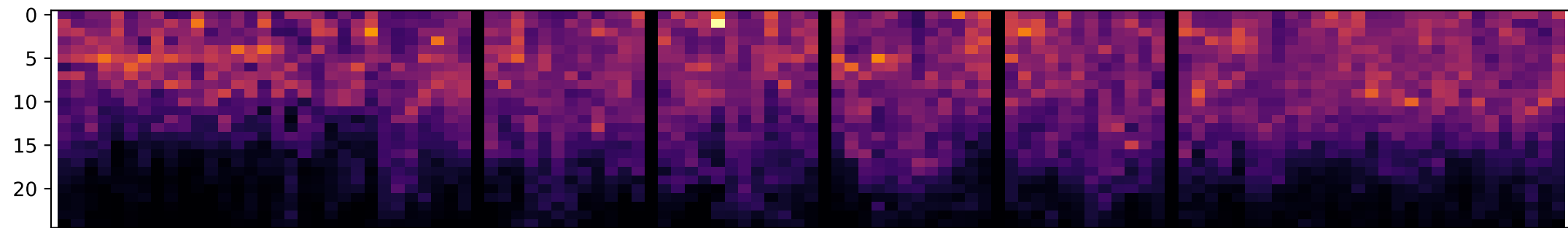
relative_to_body_angular_velocity_head_tip



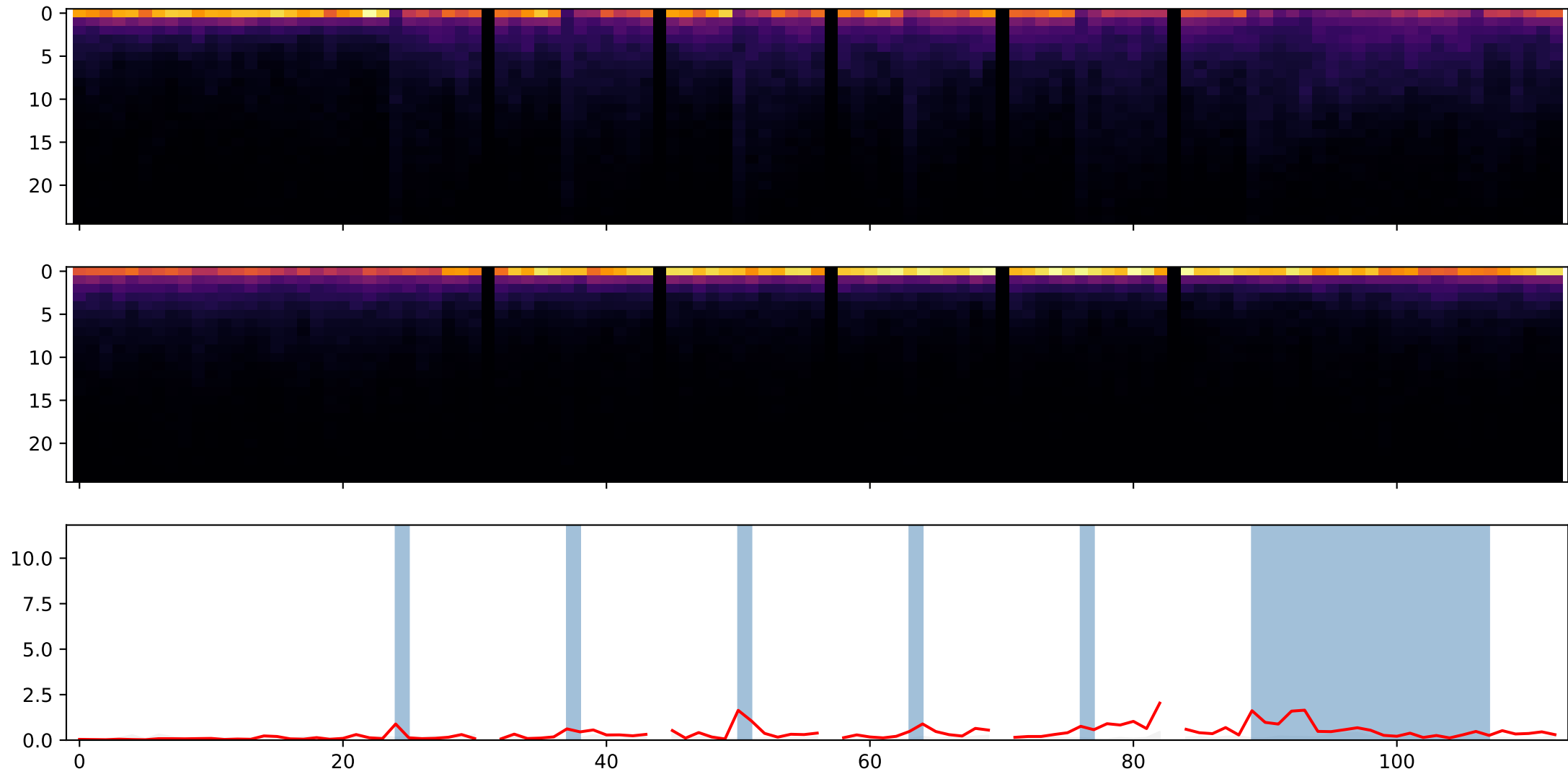
relative_to_hips_angular_velocity_tail_tip



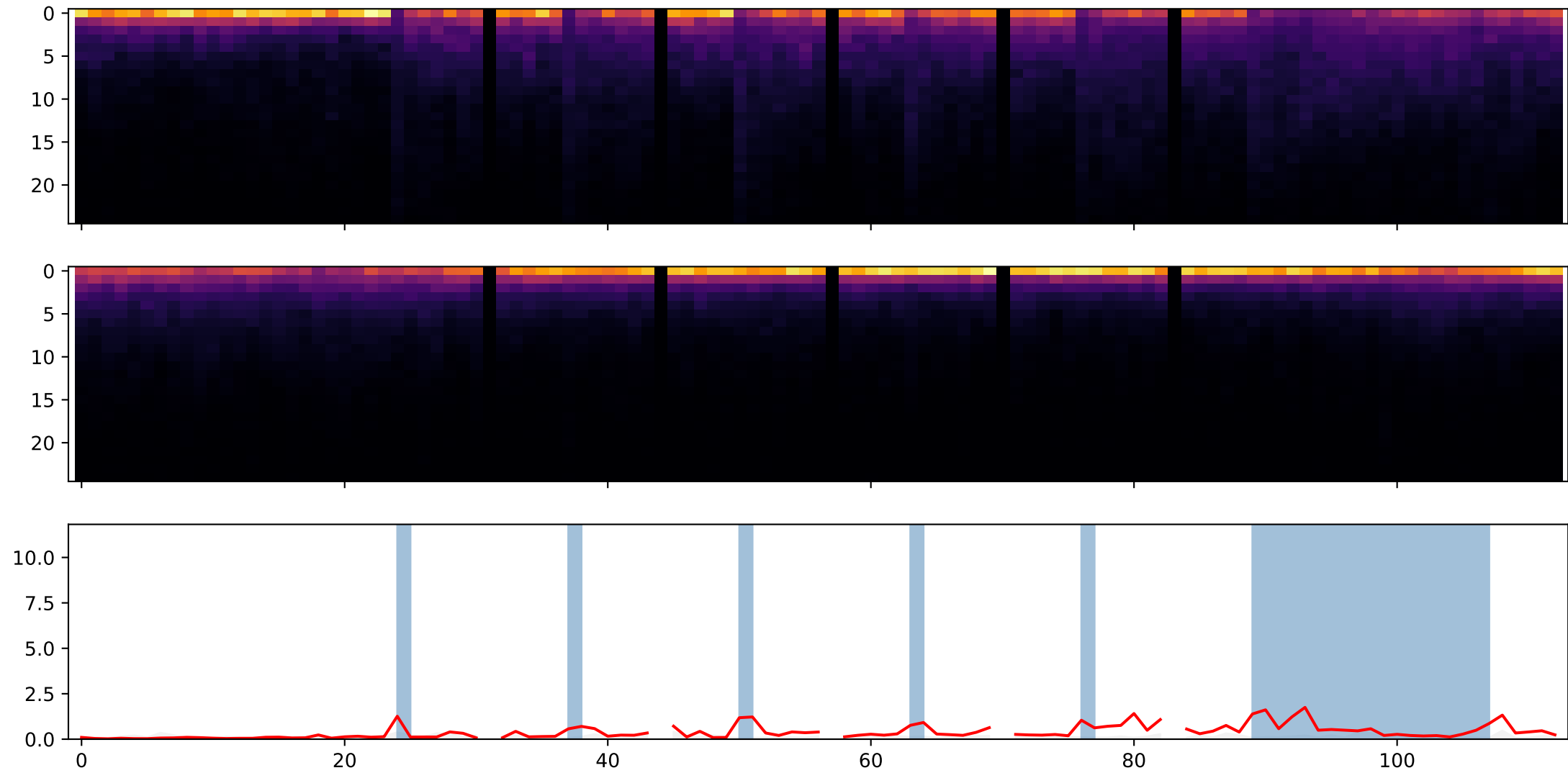
eigen_projection_3



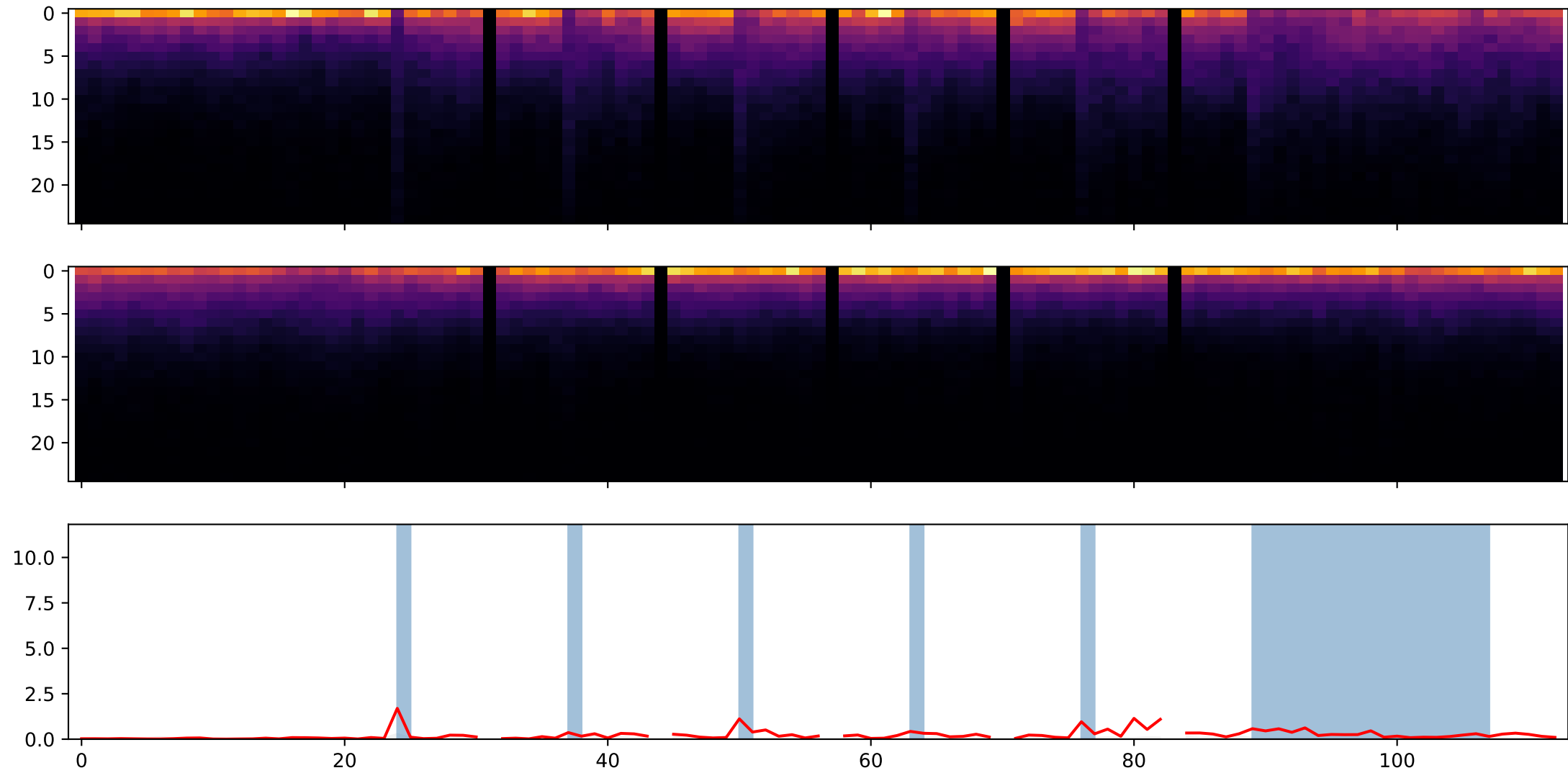
relative_to_body_angular_velocity_hips



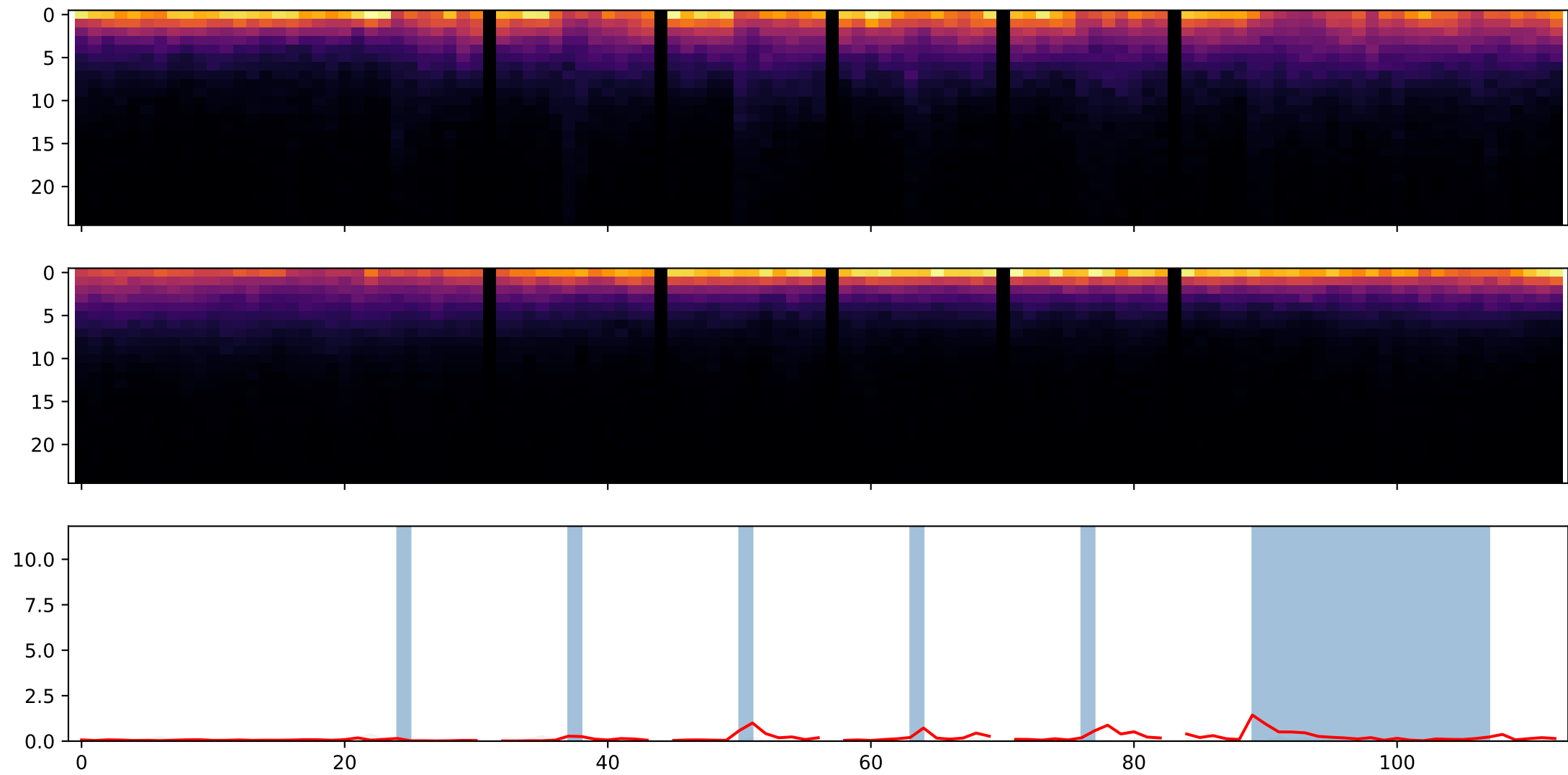
d_eigen_projection_3



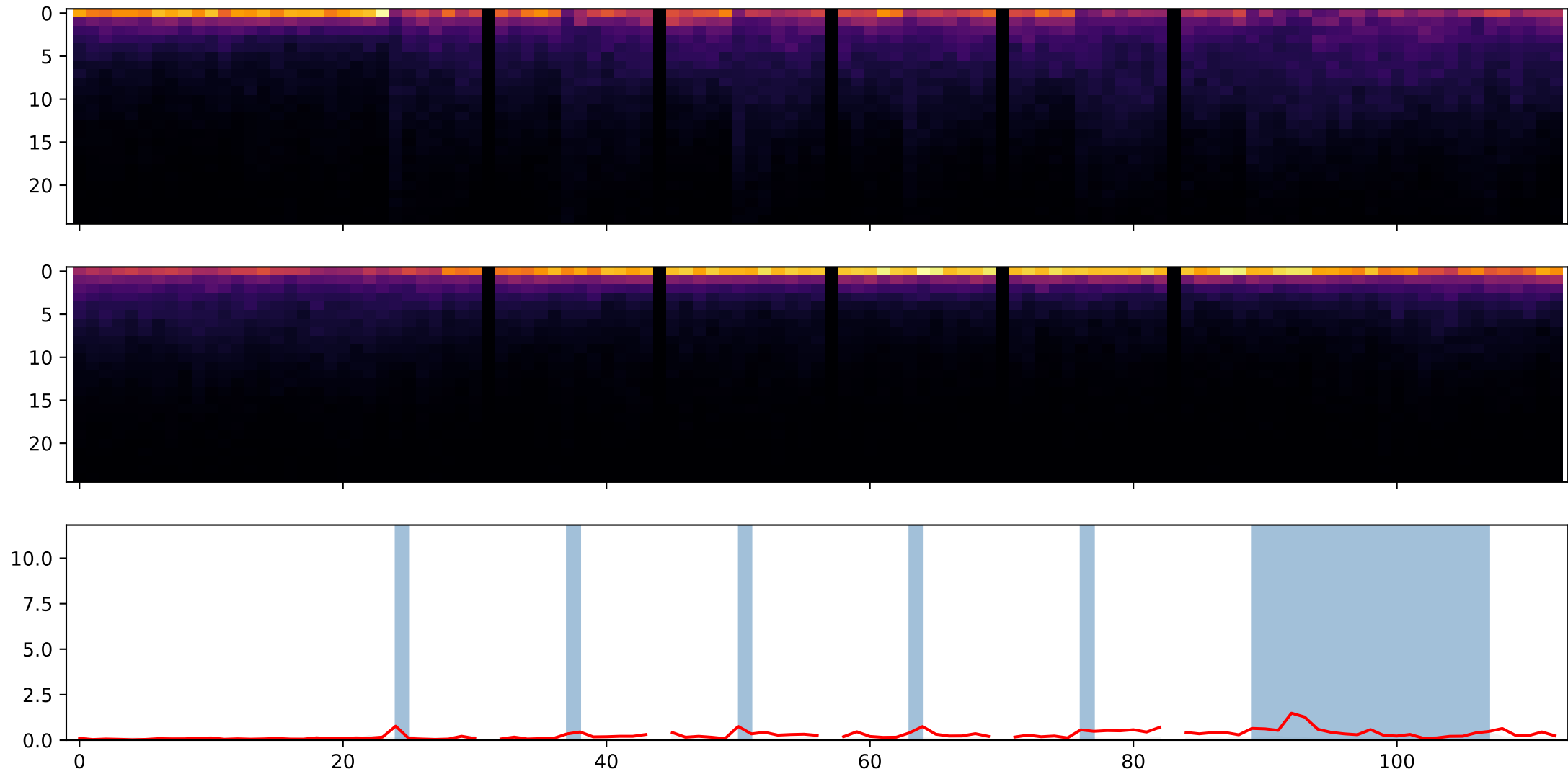
d_curvature_tail



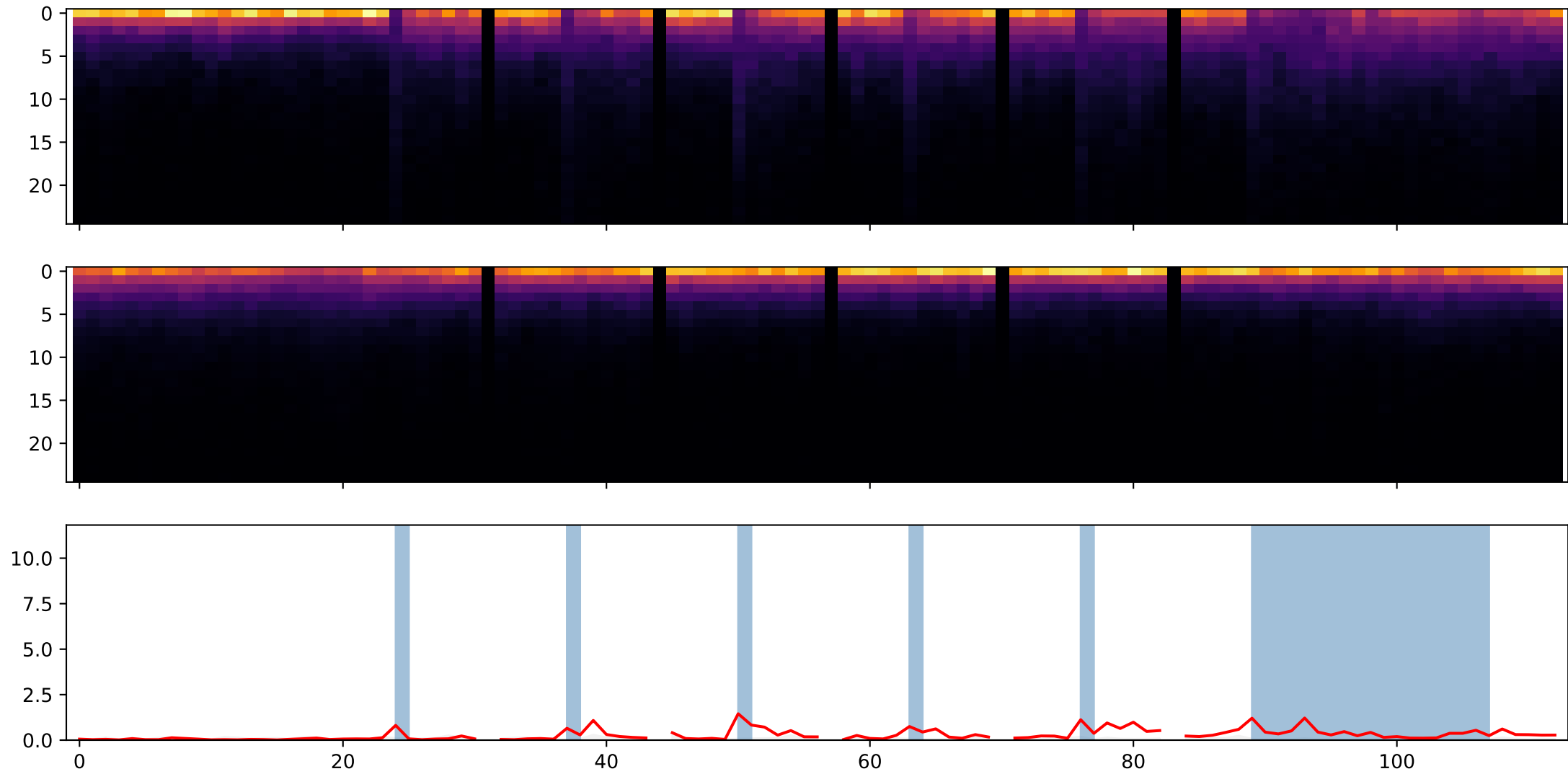
d_relative_to_body_angular_velocity_head_tip



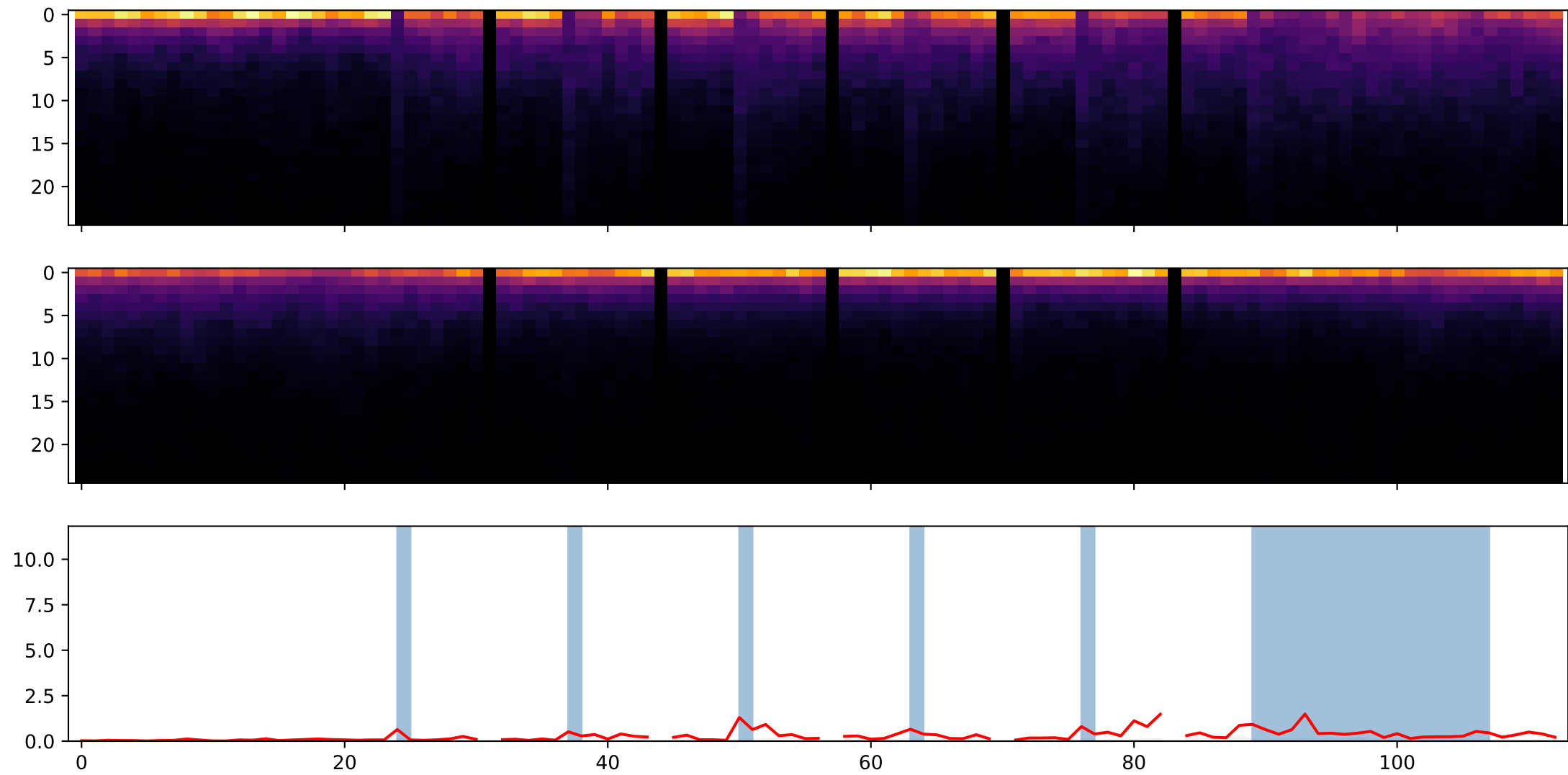
angular_velocity_neck



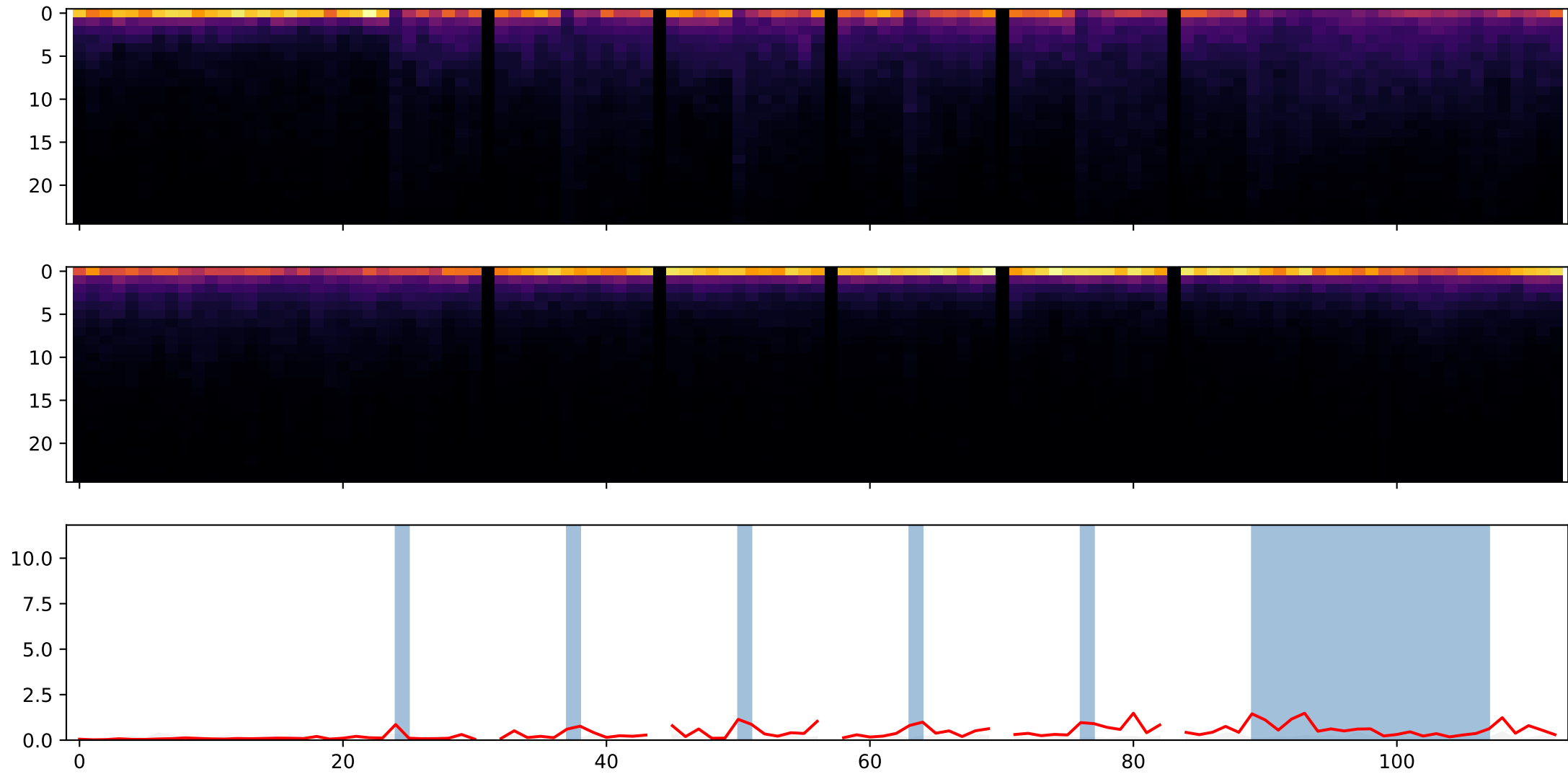
d_relative_to_hips_angular_velocity_tail_tip



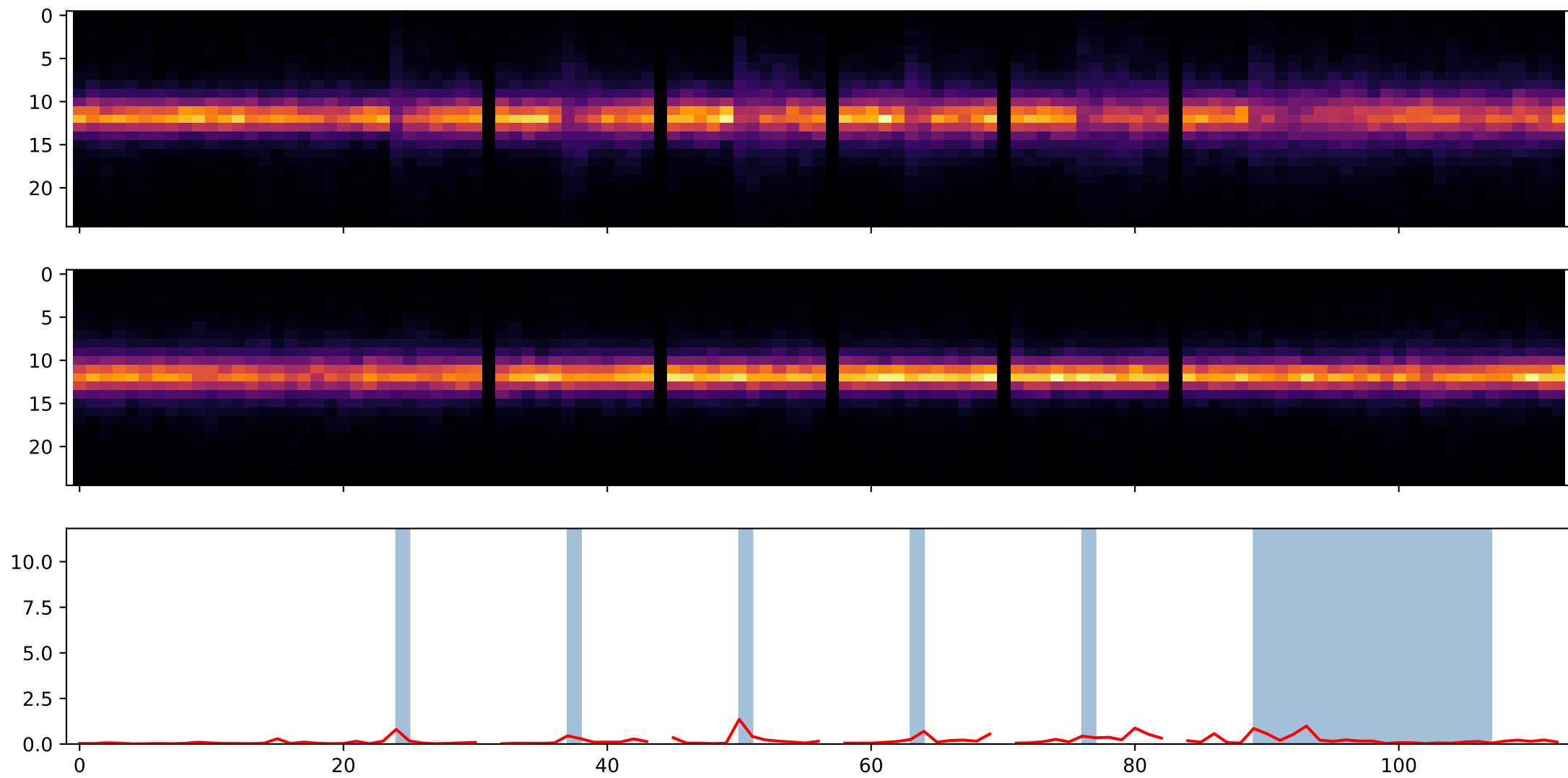
d_curvature_mean_tail



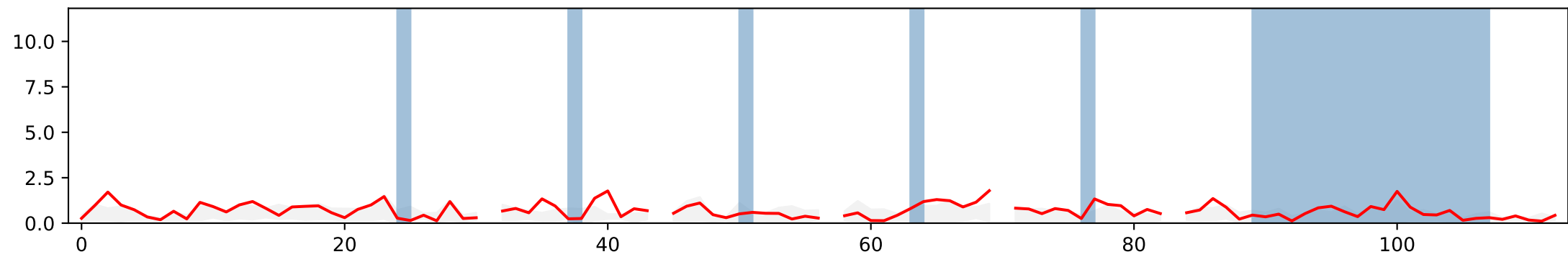
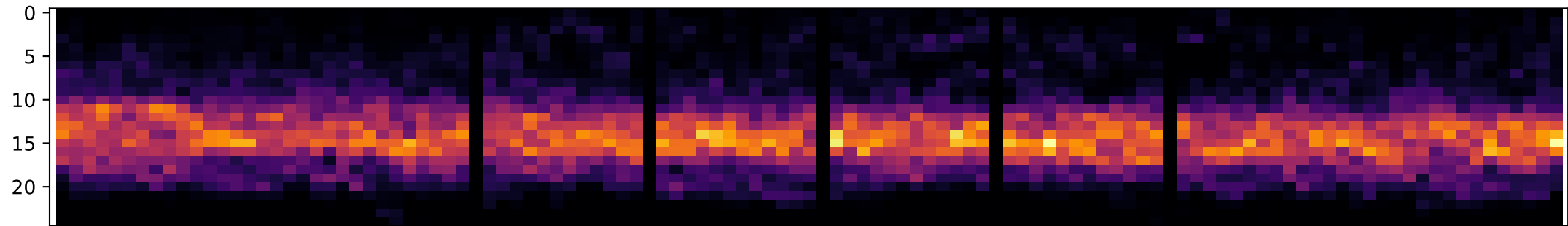
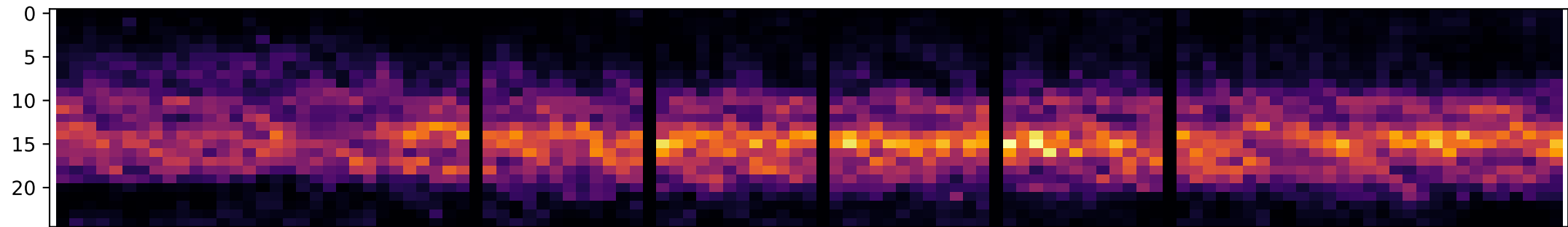
relative_to_body_speed_midbody



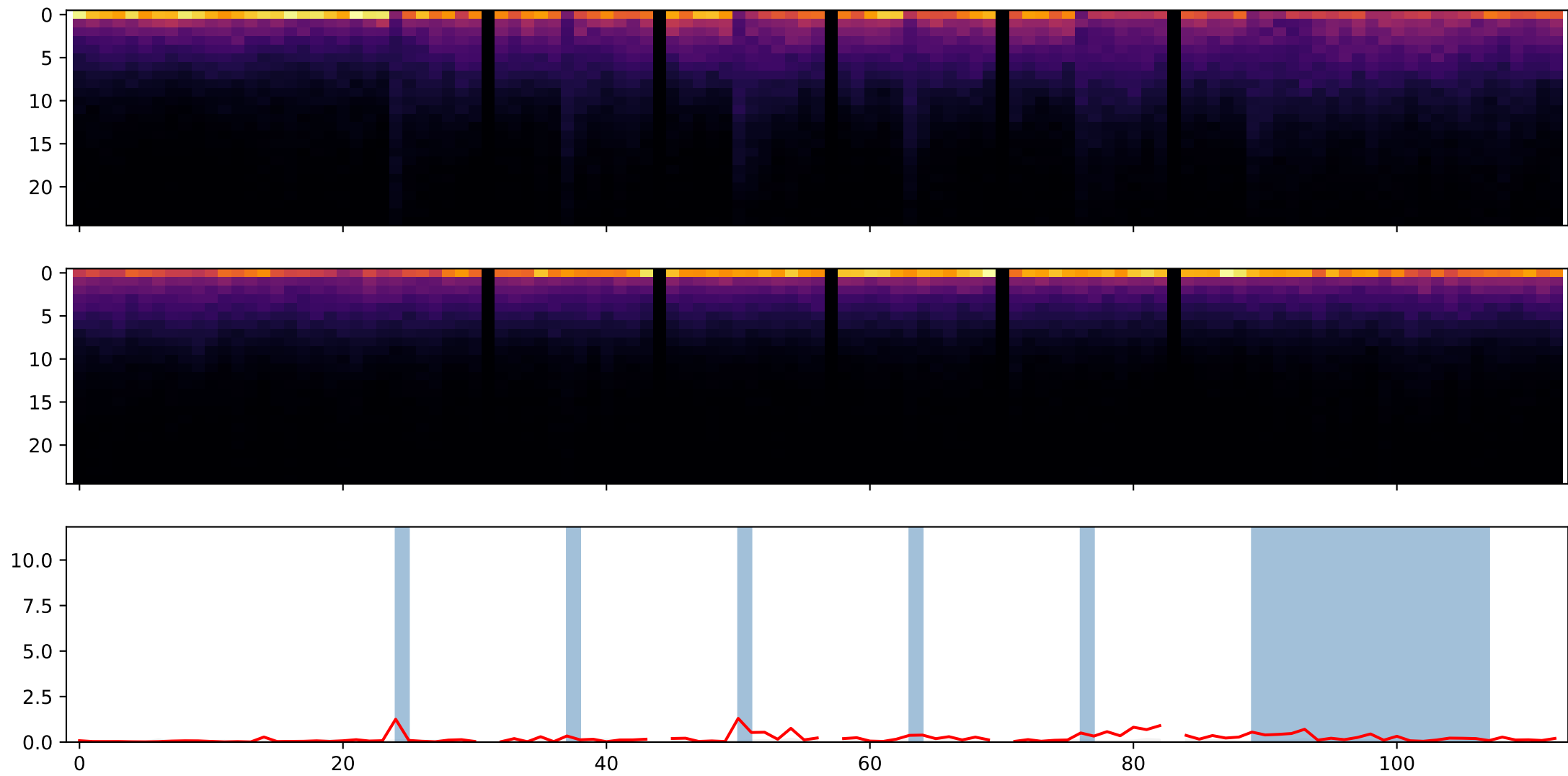
relative_to_body_radial_velocity_hips



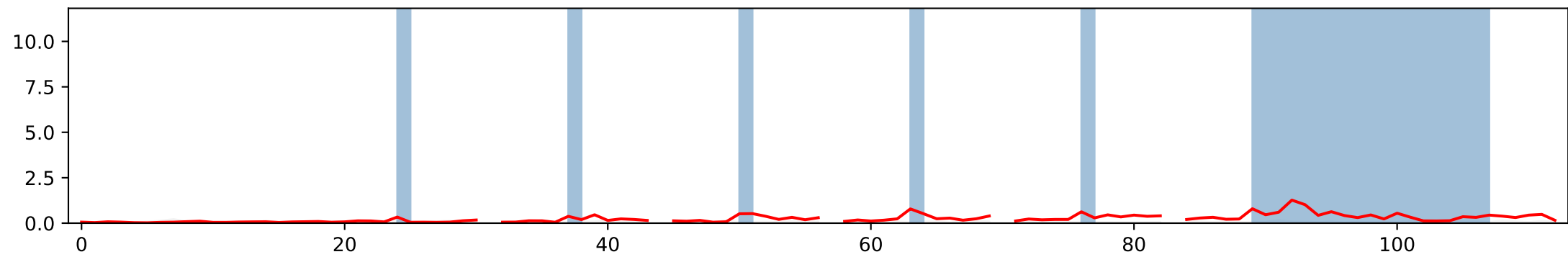
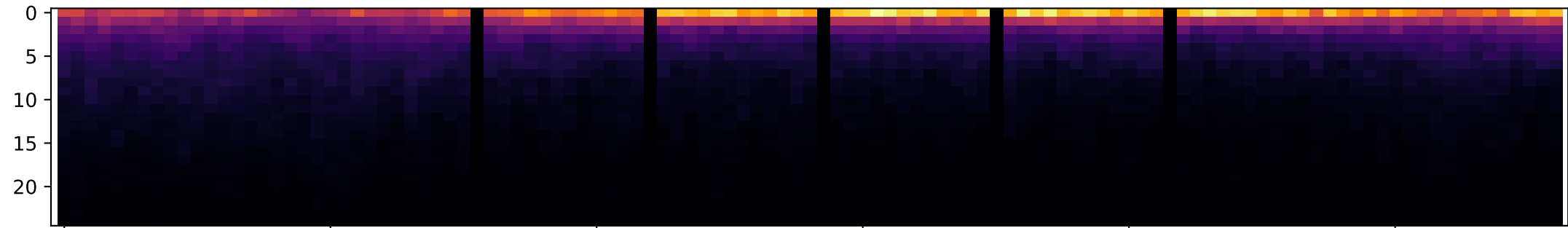
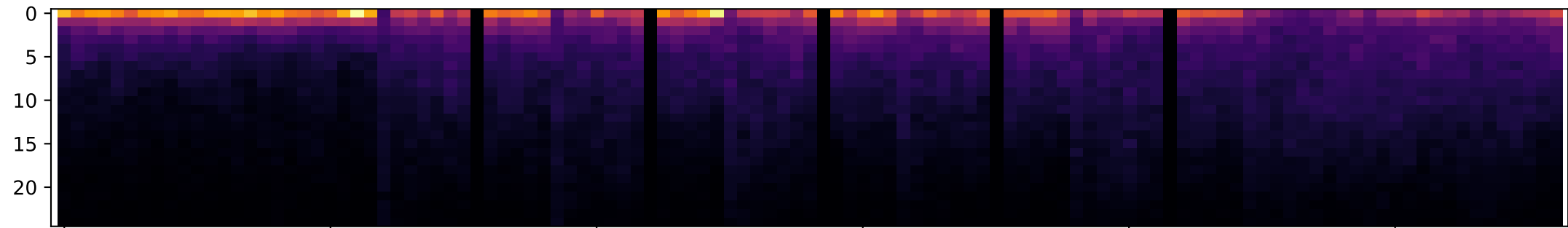
length



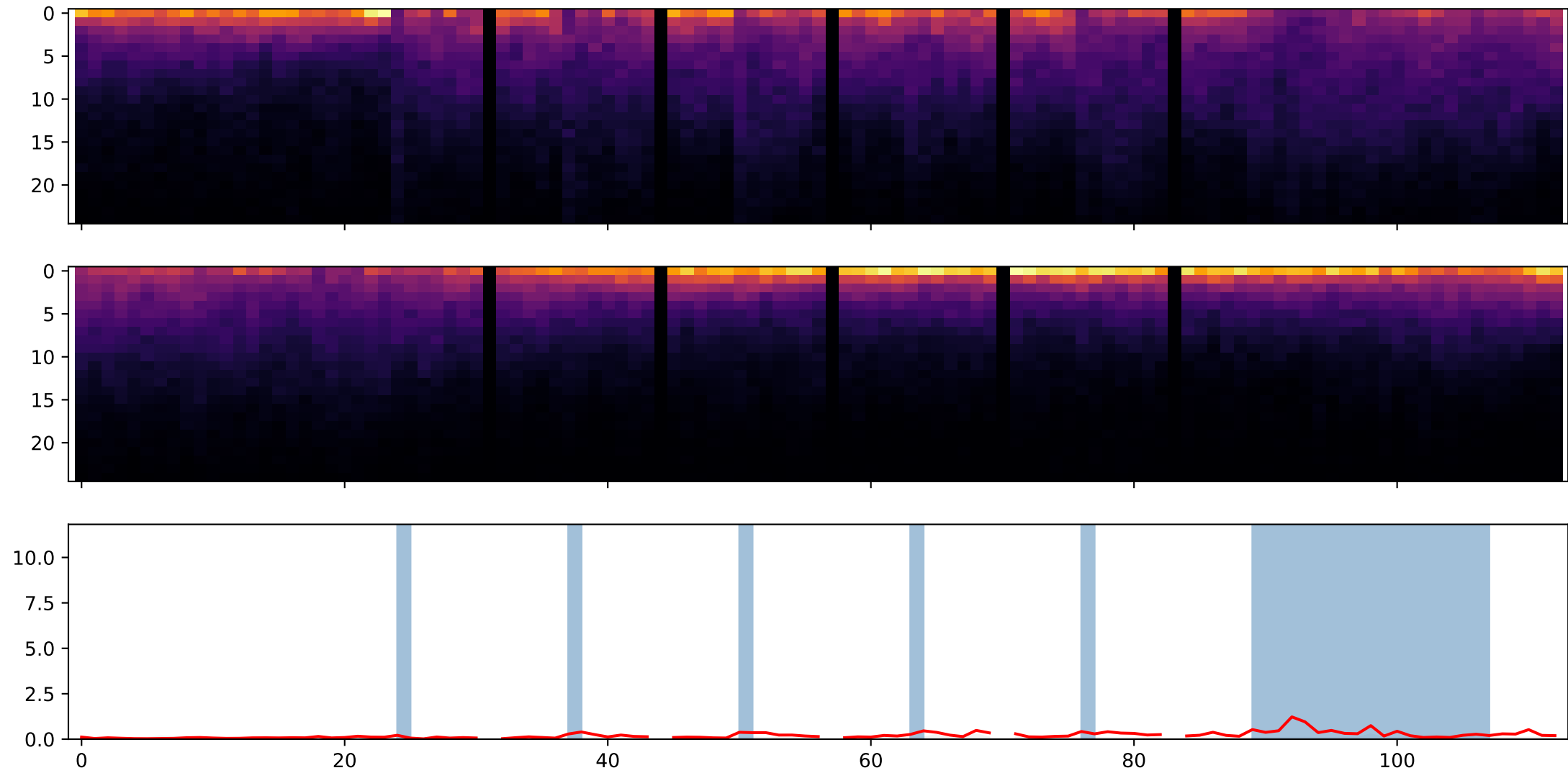
angular_velocity_tail_tip



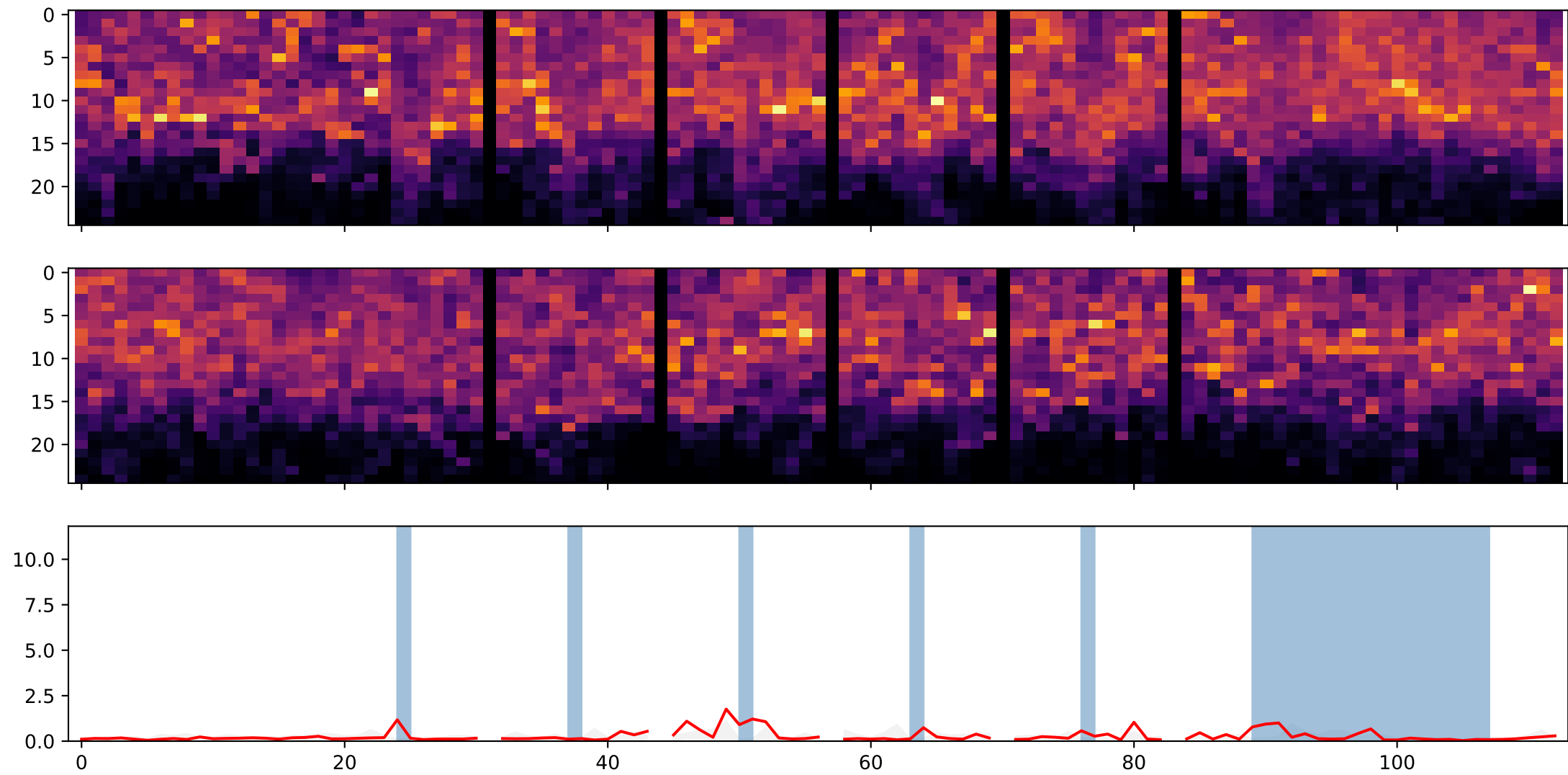
d_curvature_mean_neck



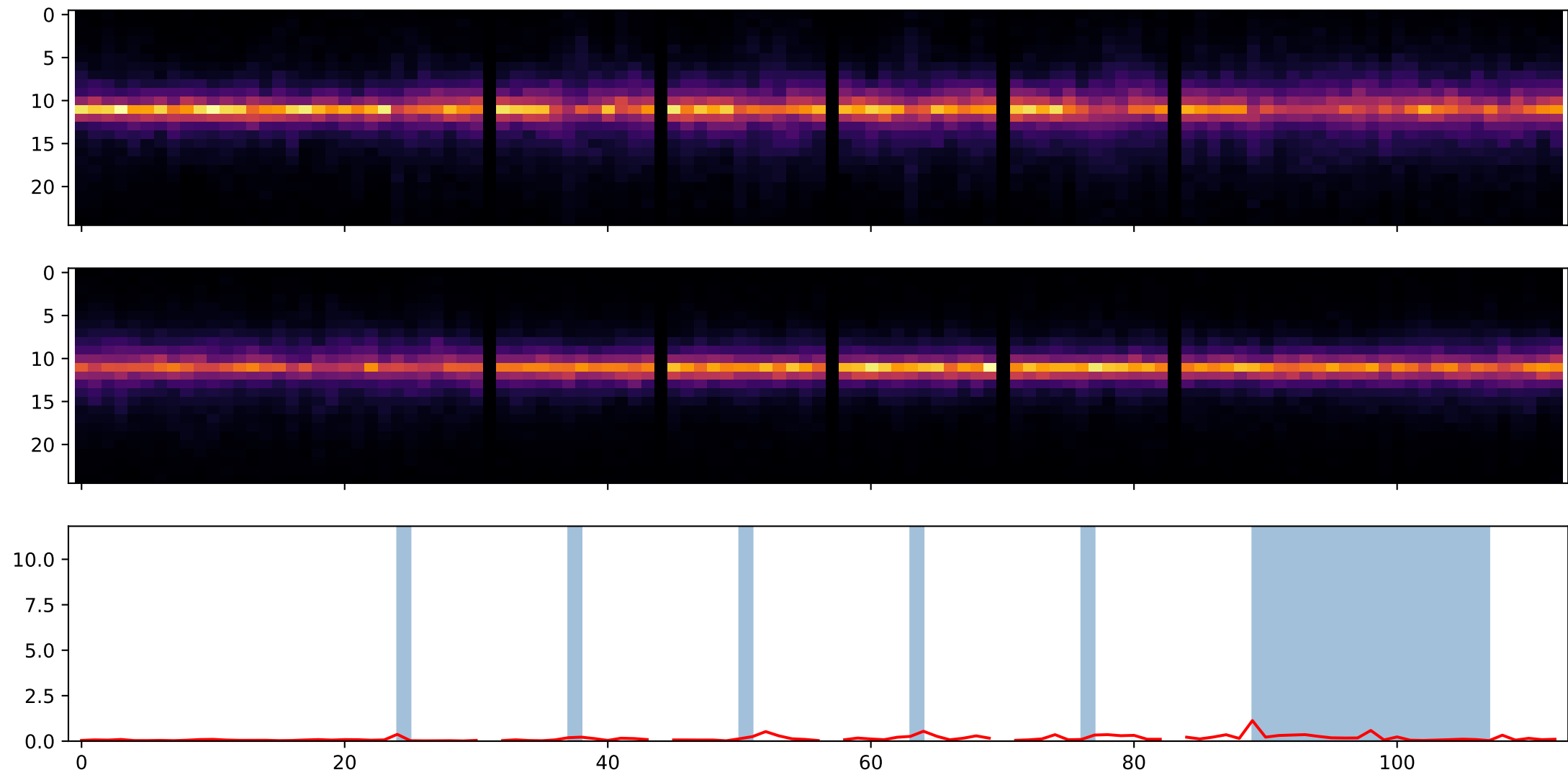
relative_to_neck_angular_velocity_head_tip



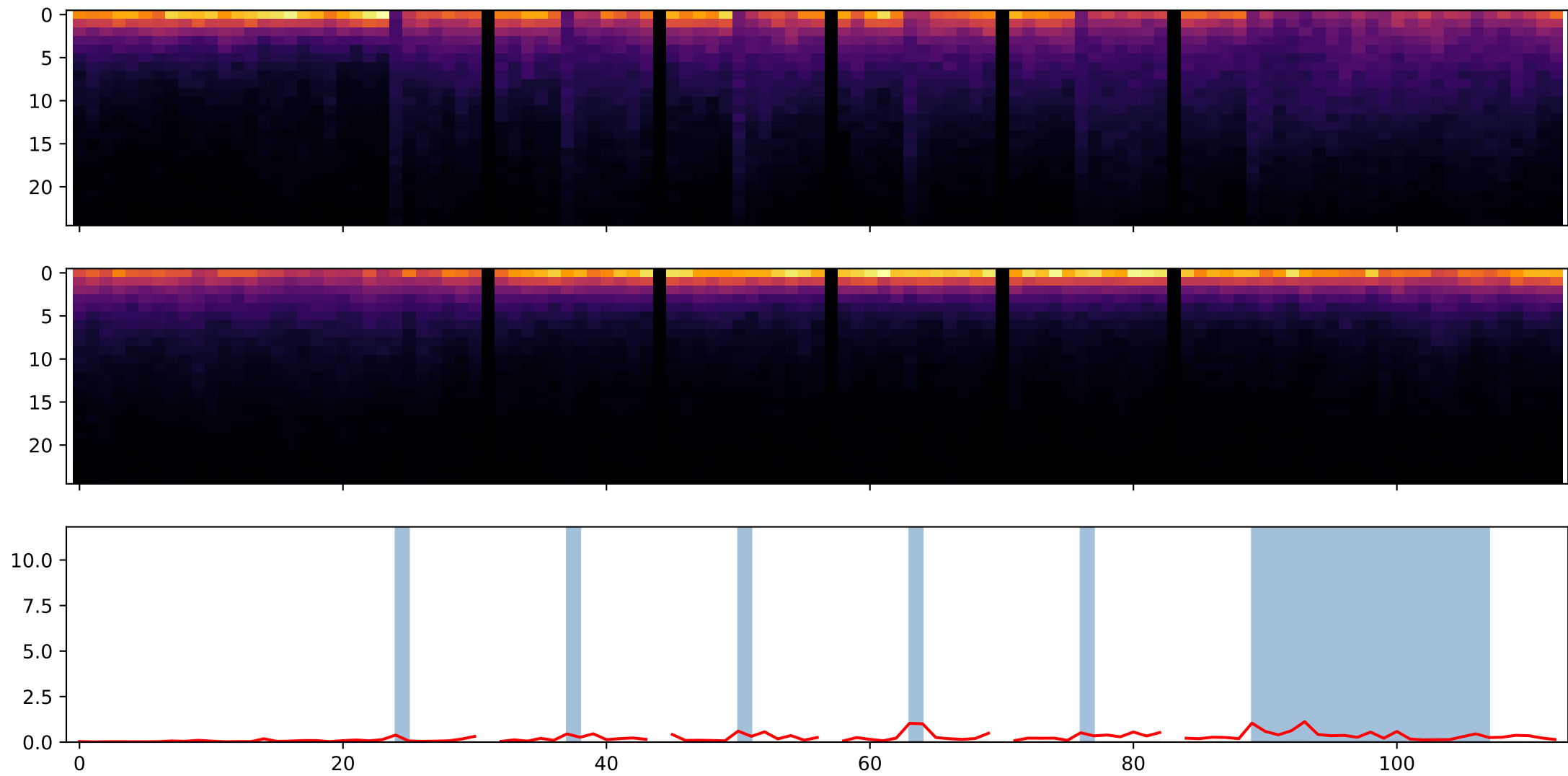
curvature_mean_hips



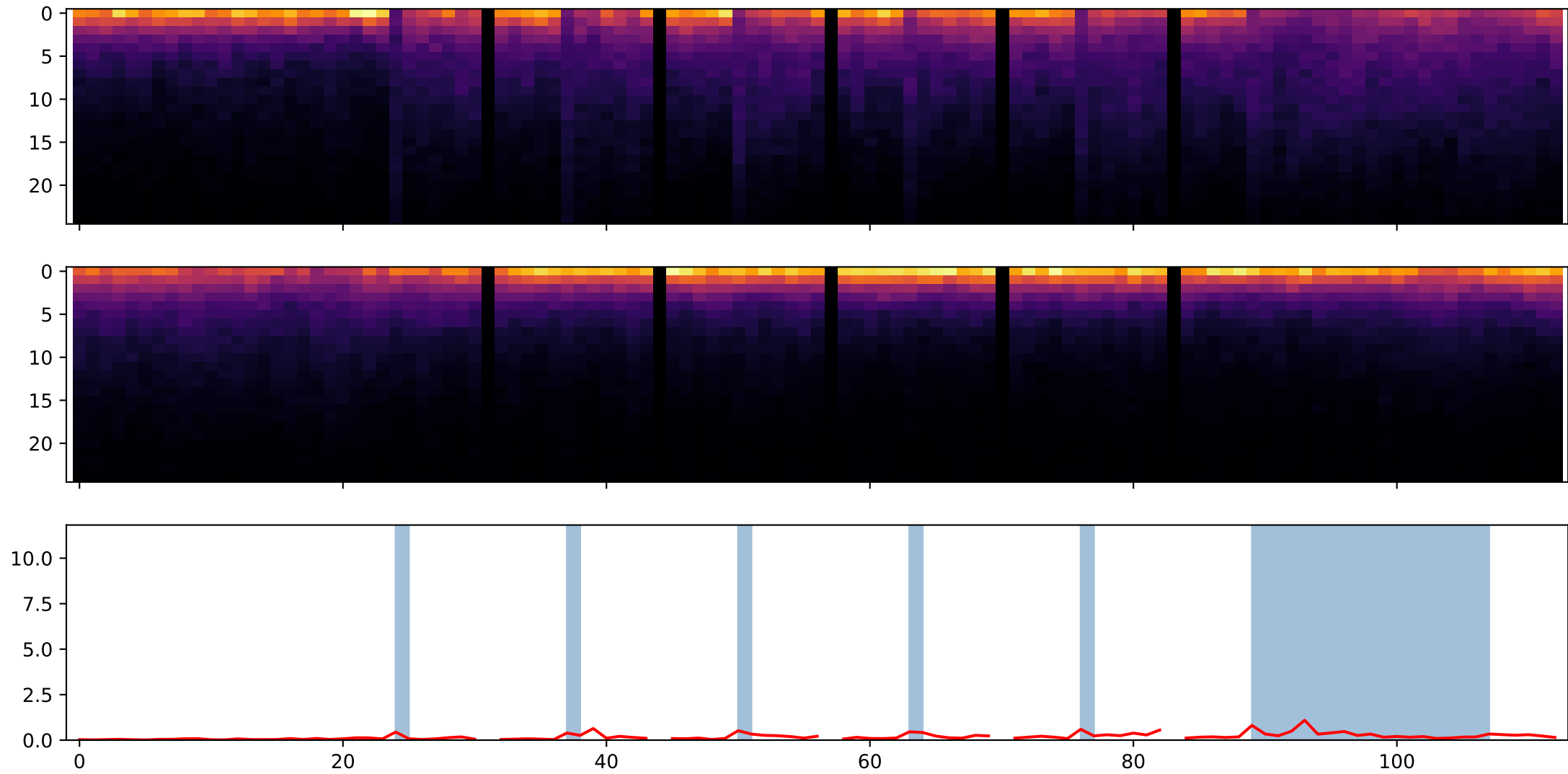
d_minor_axis



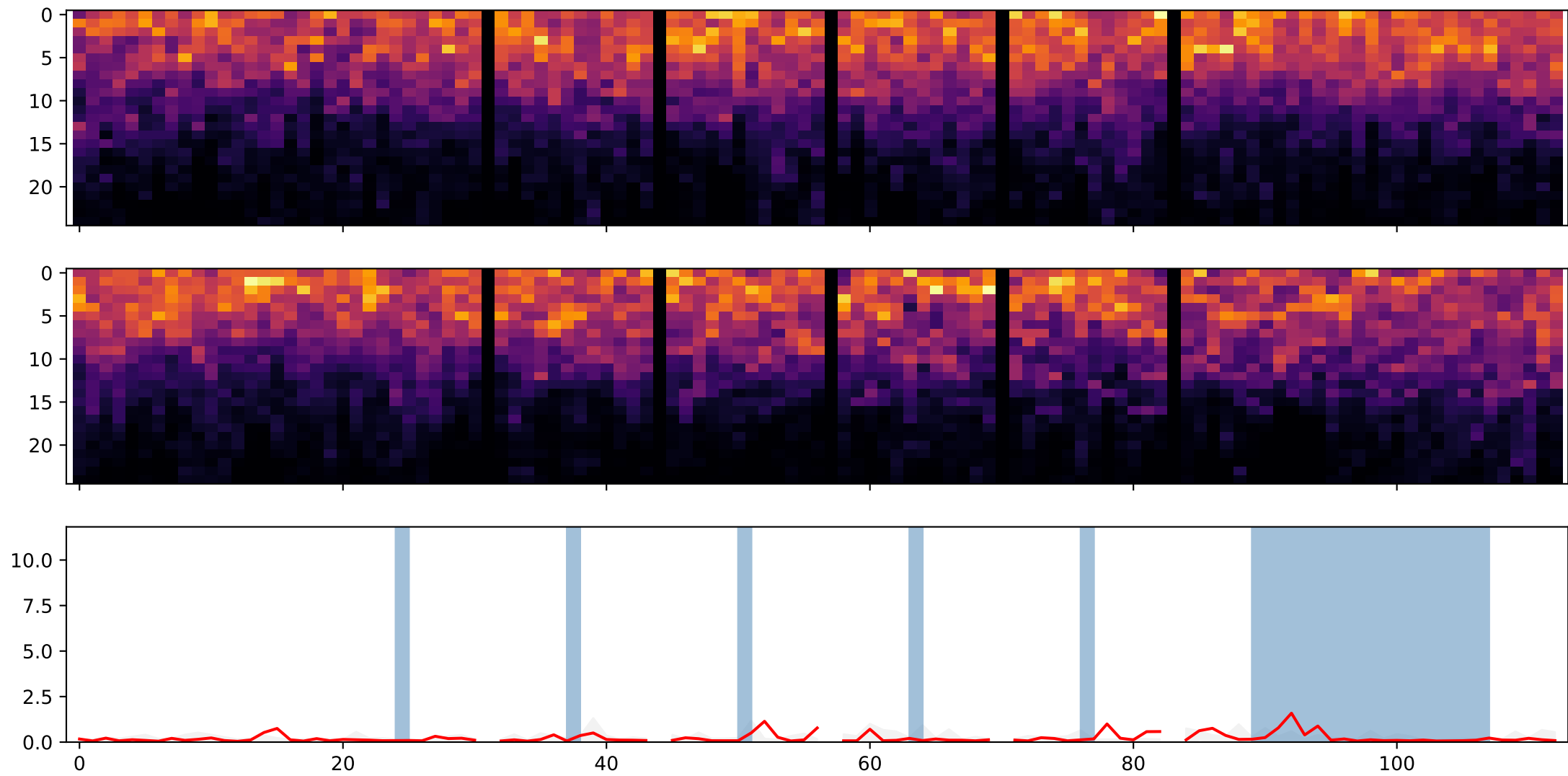
d_curvature_std_midbody



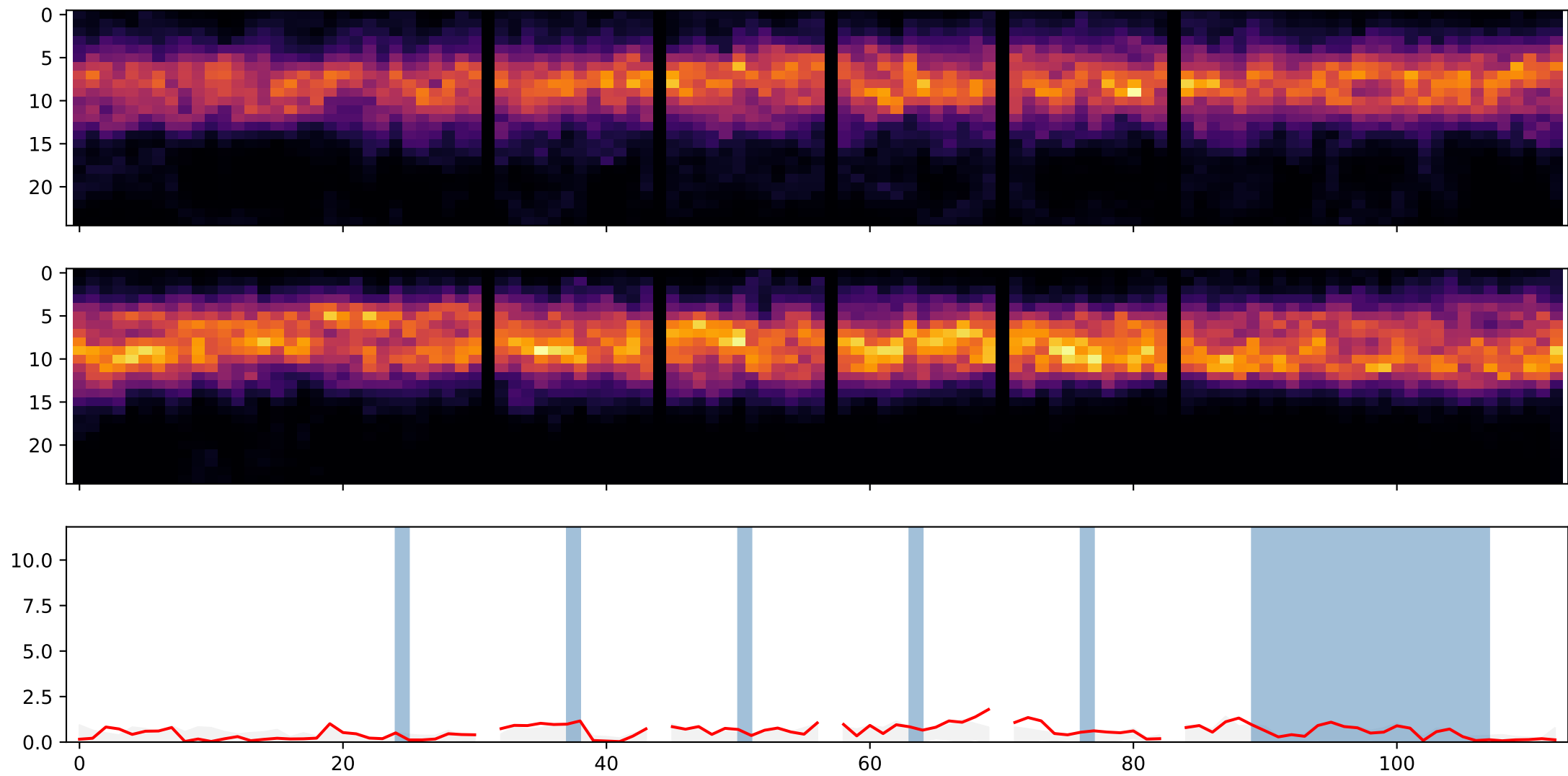
d_curvature_midbody



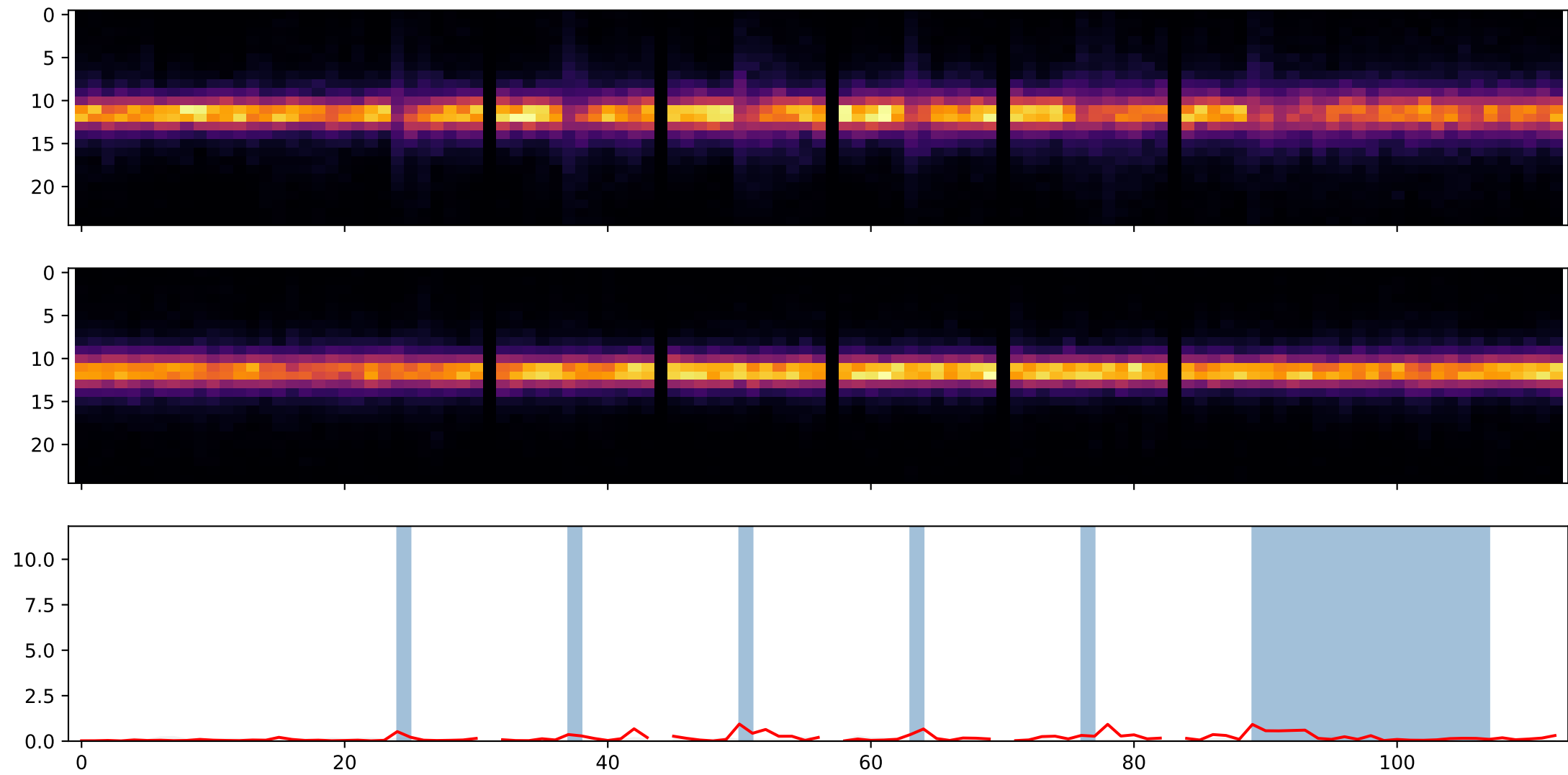
eigen_projection_1



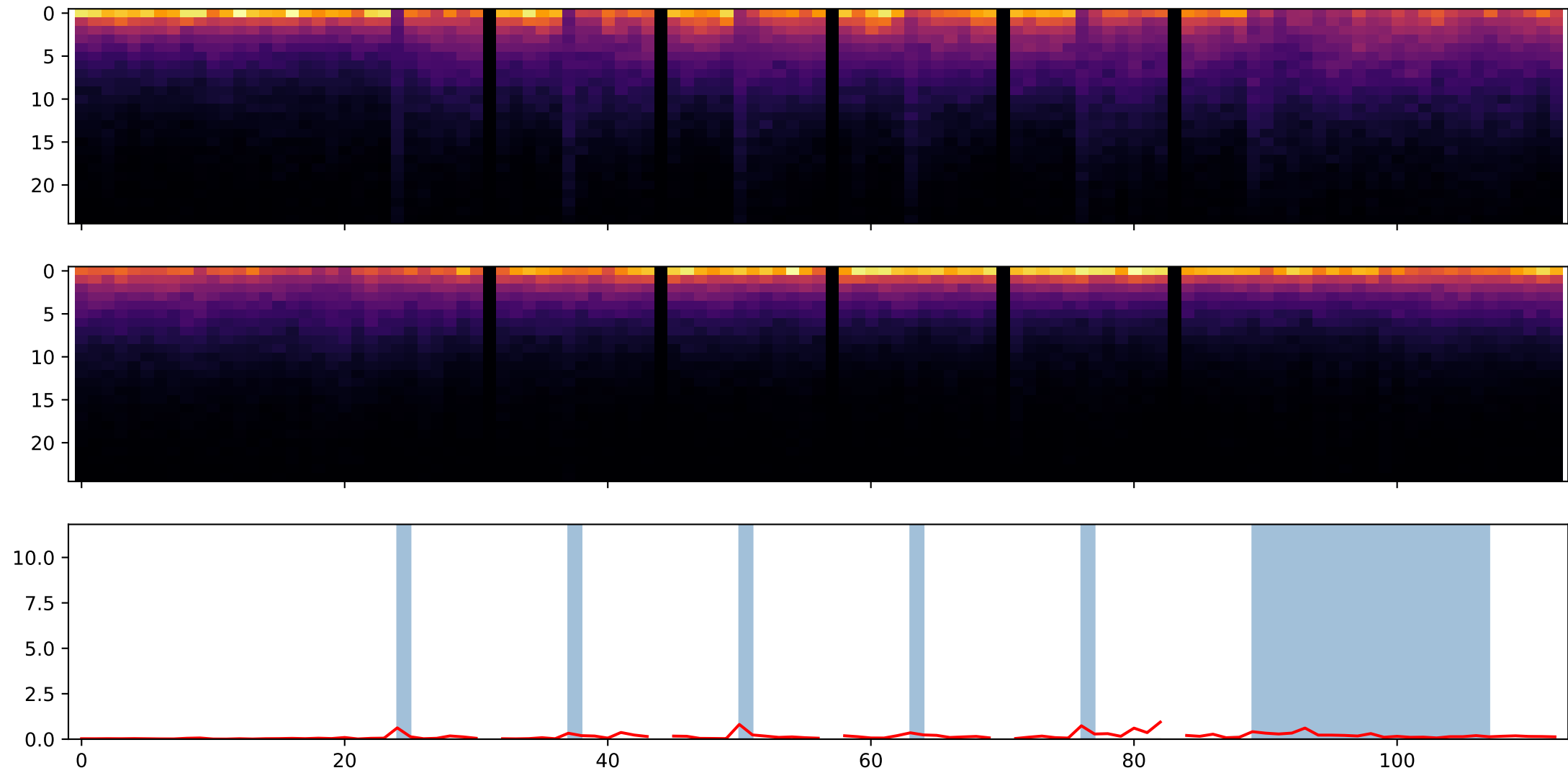
area



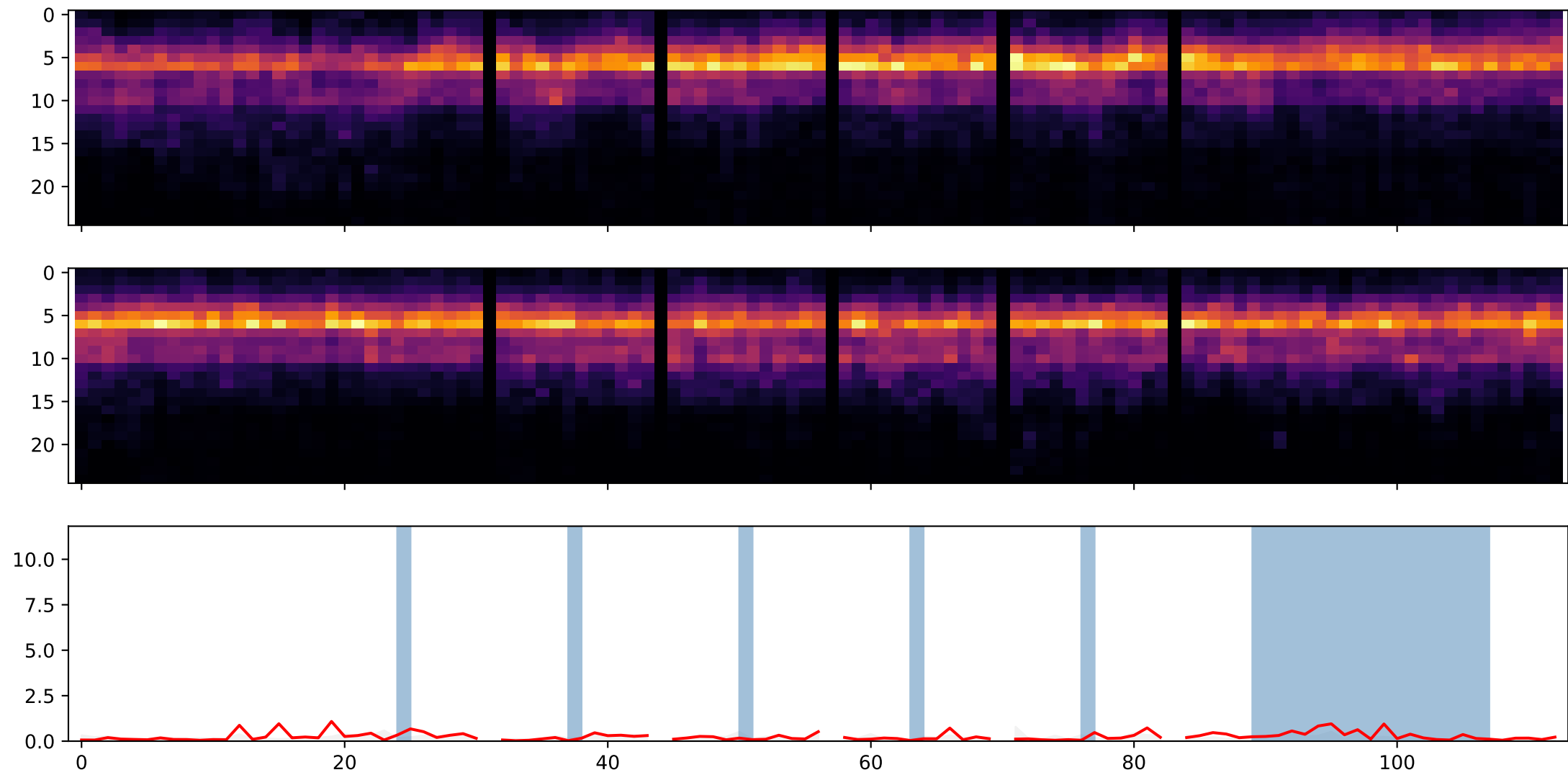
relative_to_body_radial_velocity_tail_tip



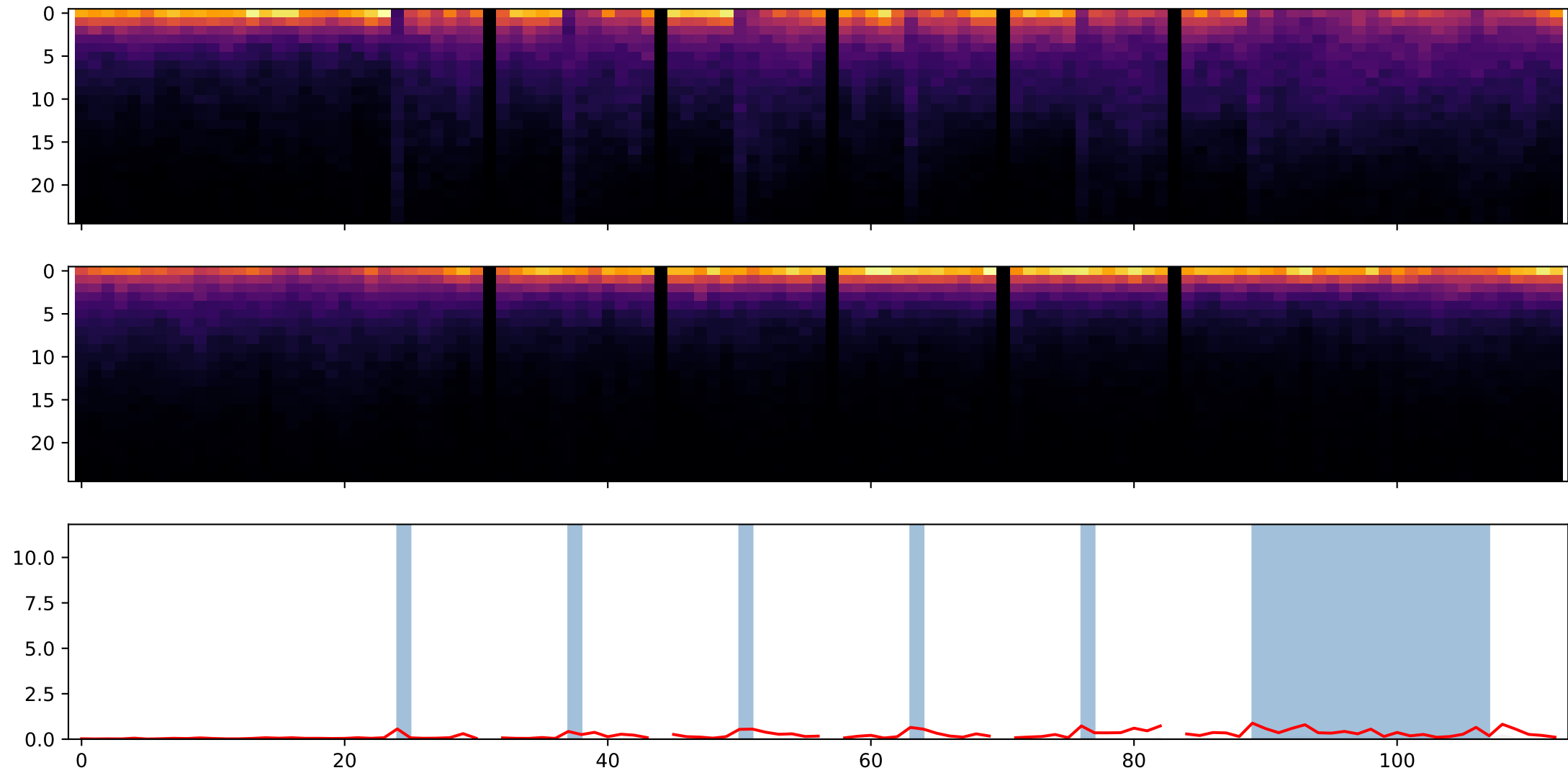
relative_to_tail_base_angular_velocity_tail_tip



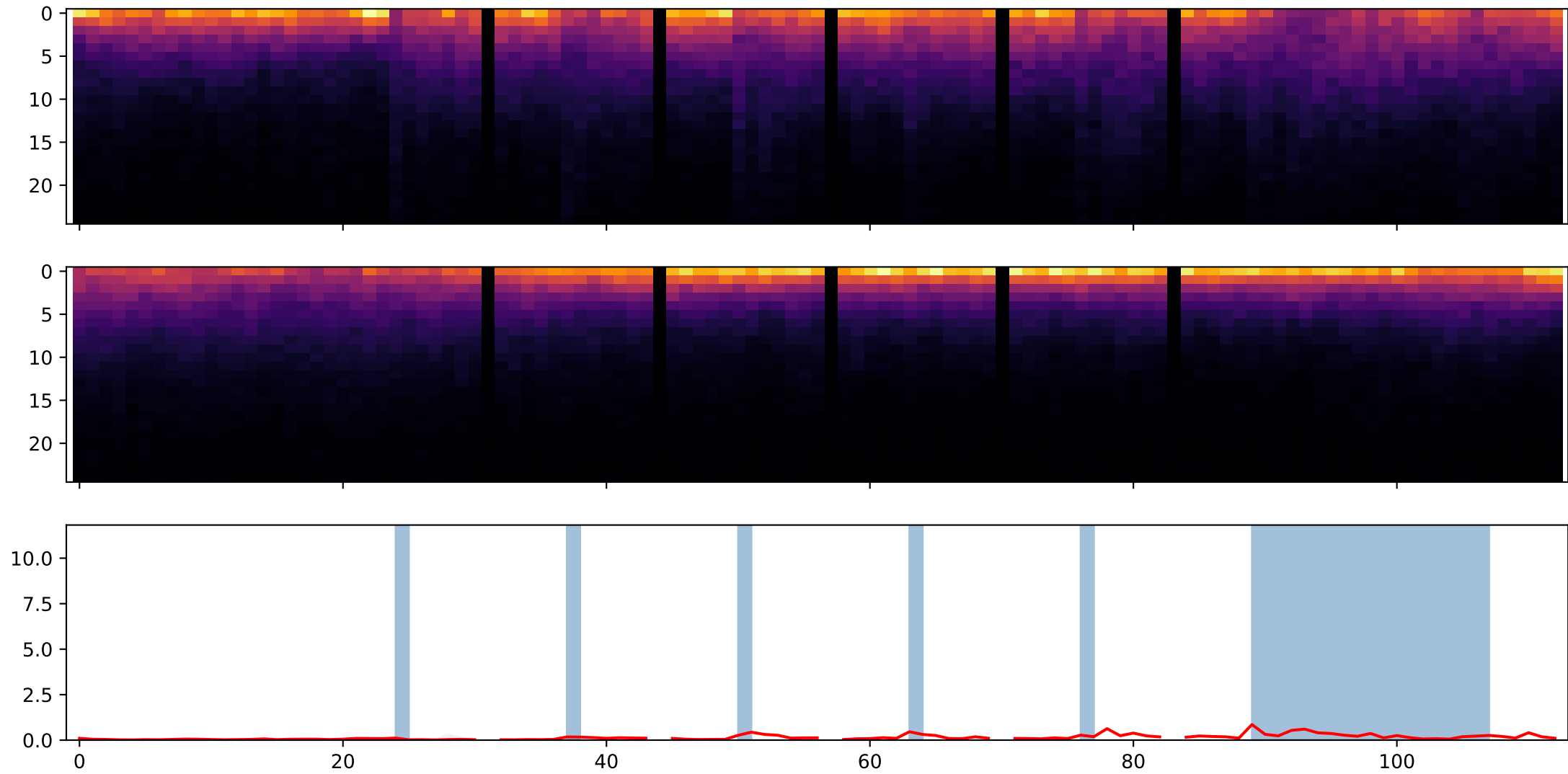
width_head_base



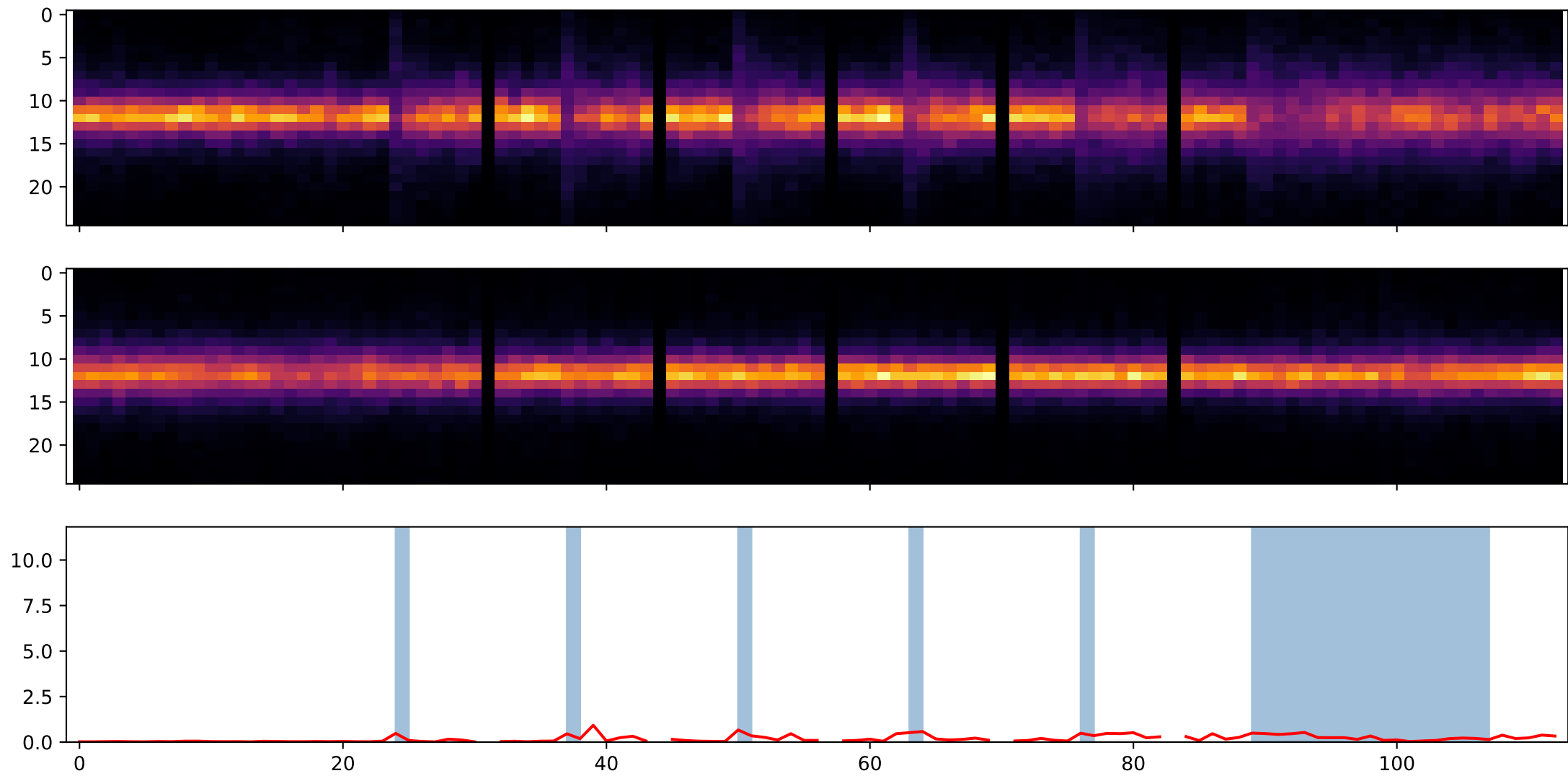
d_curvature_hips



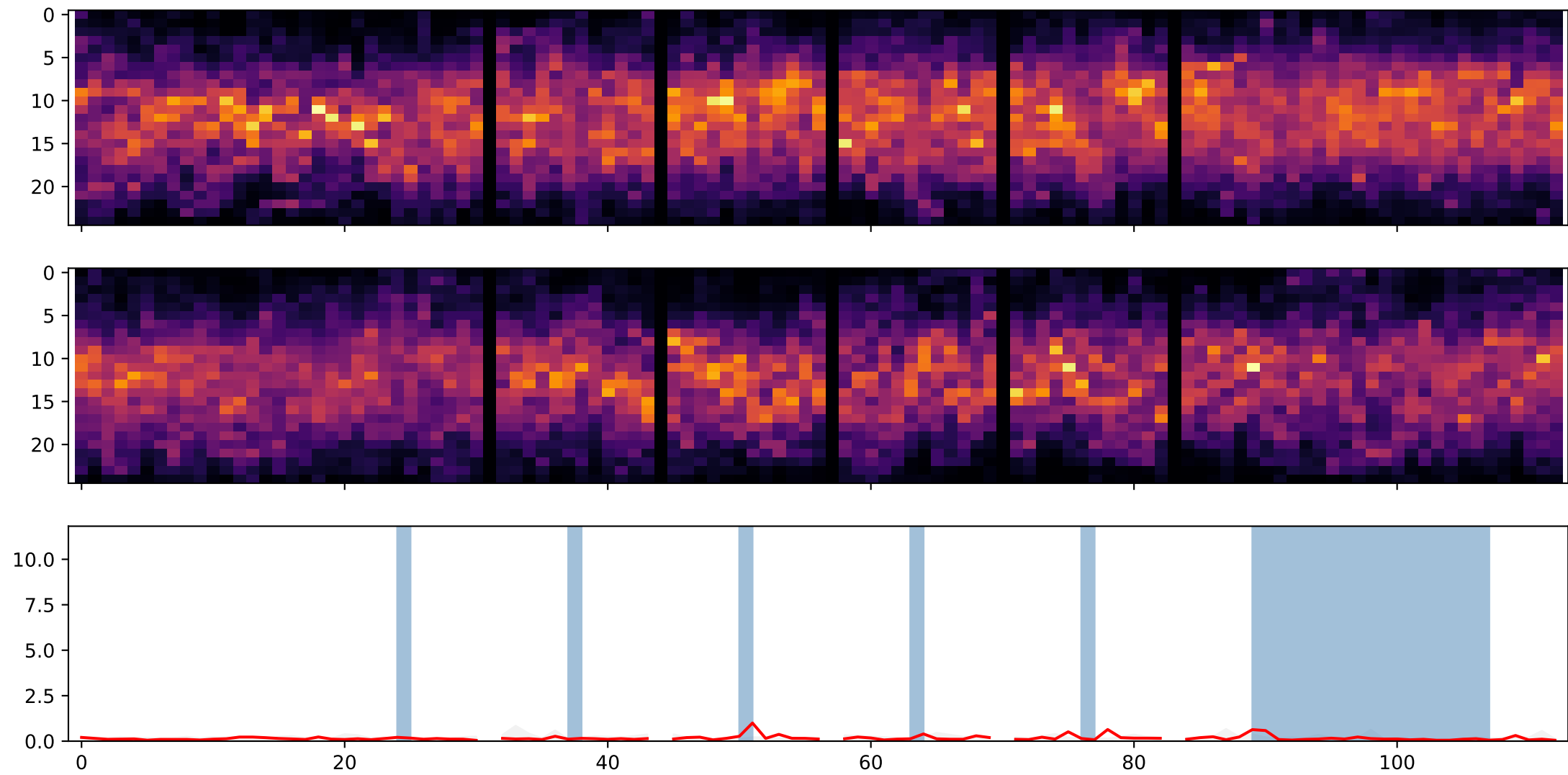
d_relative_to_neck_angular_velocity_head_tip



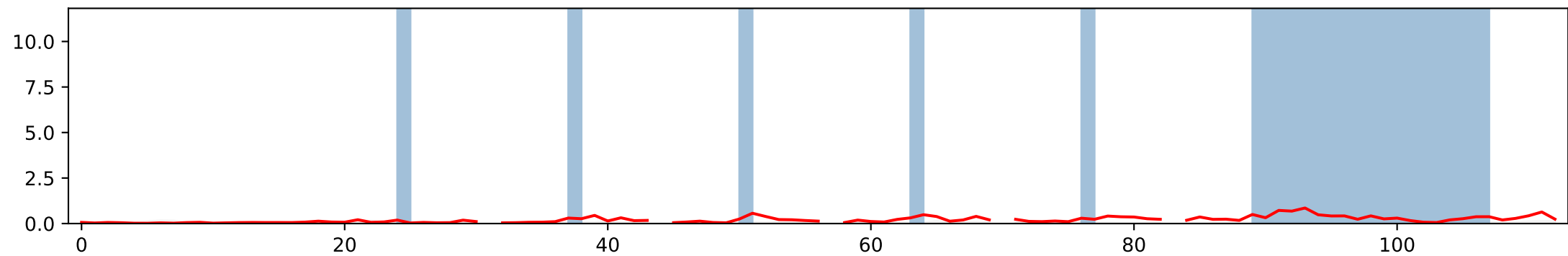
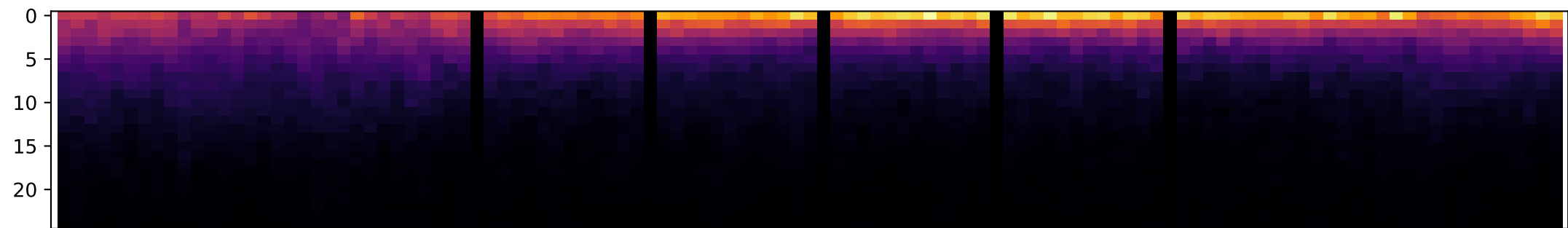
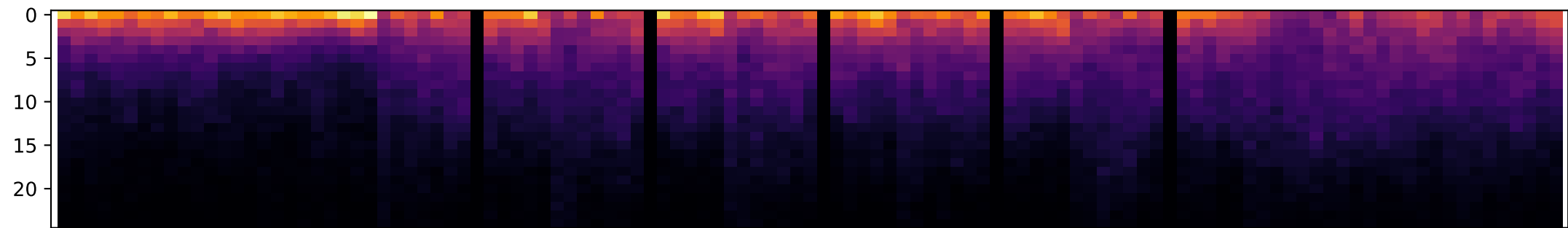
relative_to_hips_radial_velocity_tail_tip



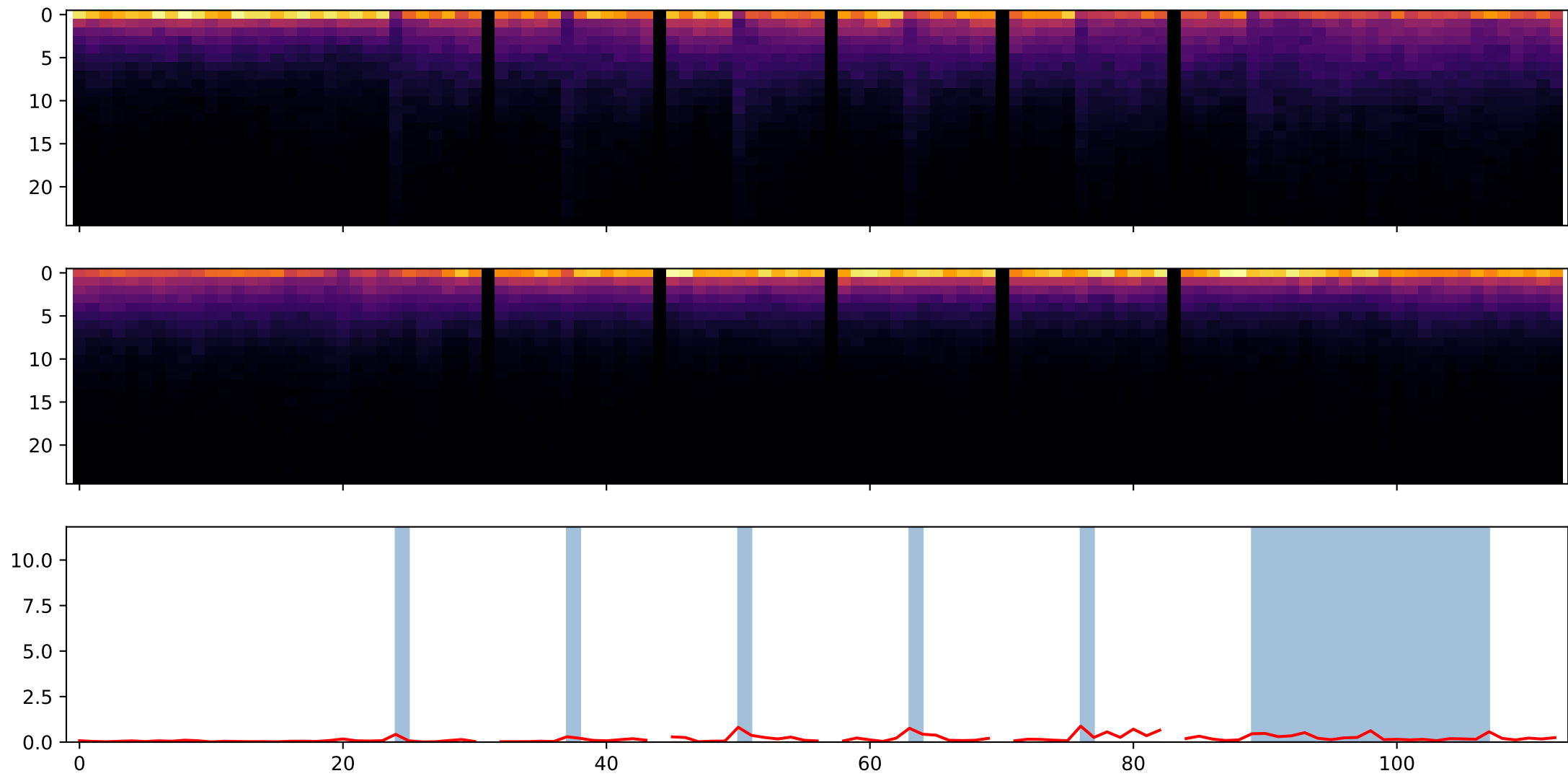
curvature_std_midbody



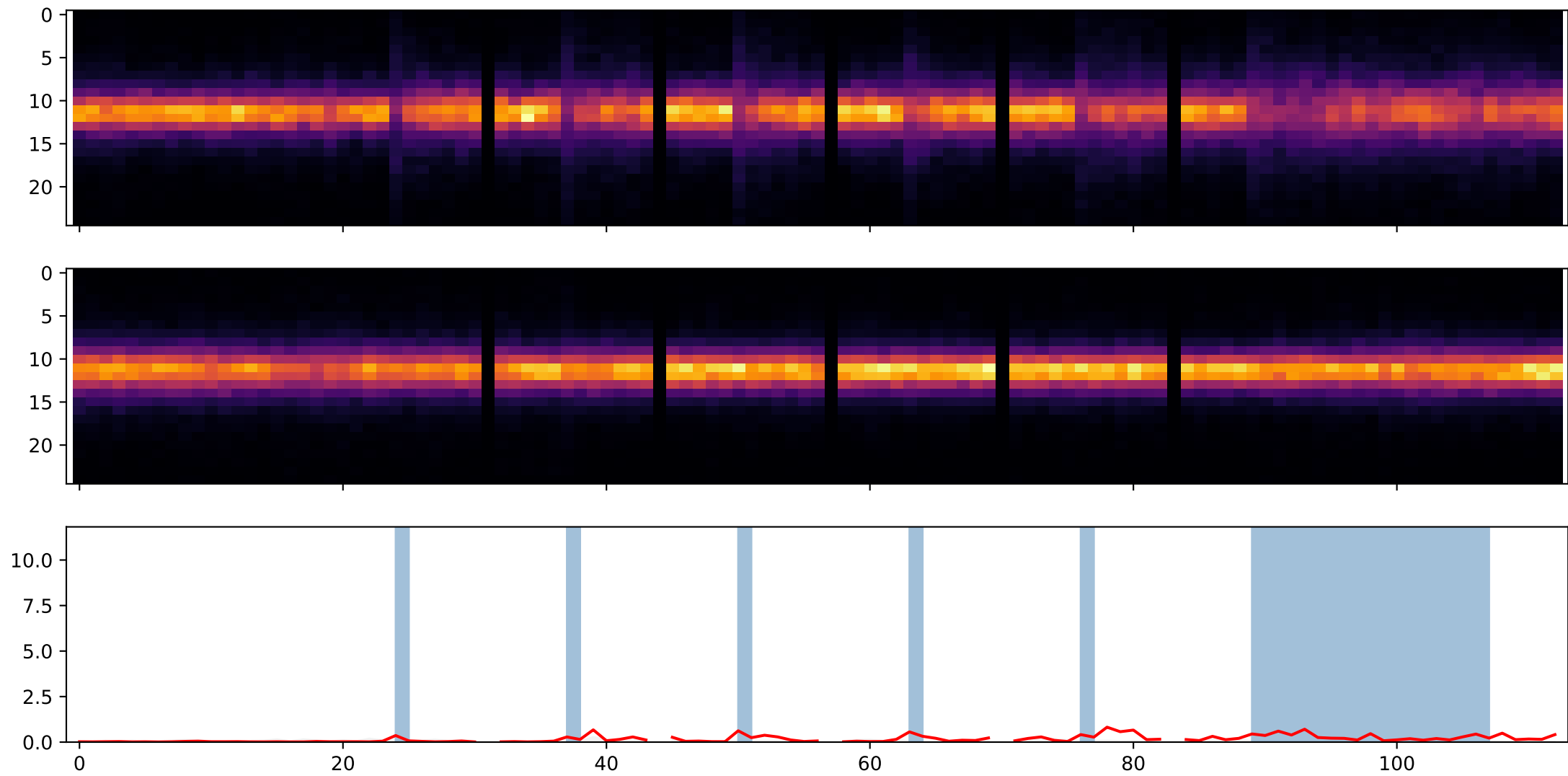
d_eigen_projection_1



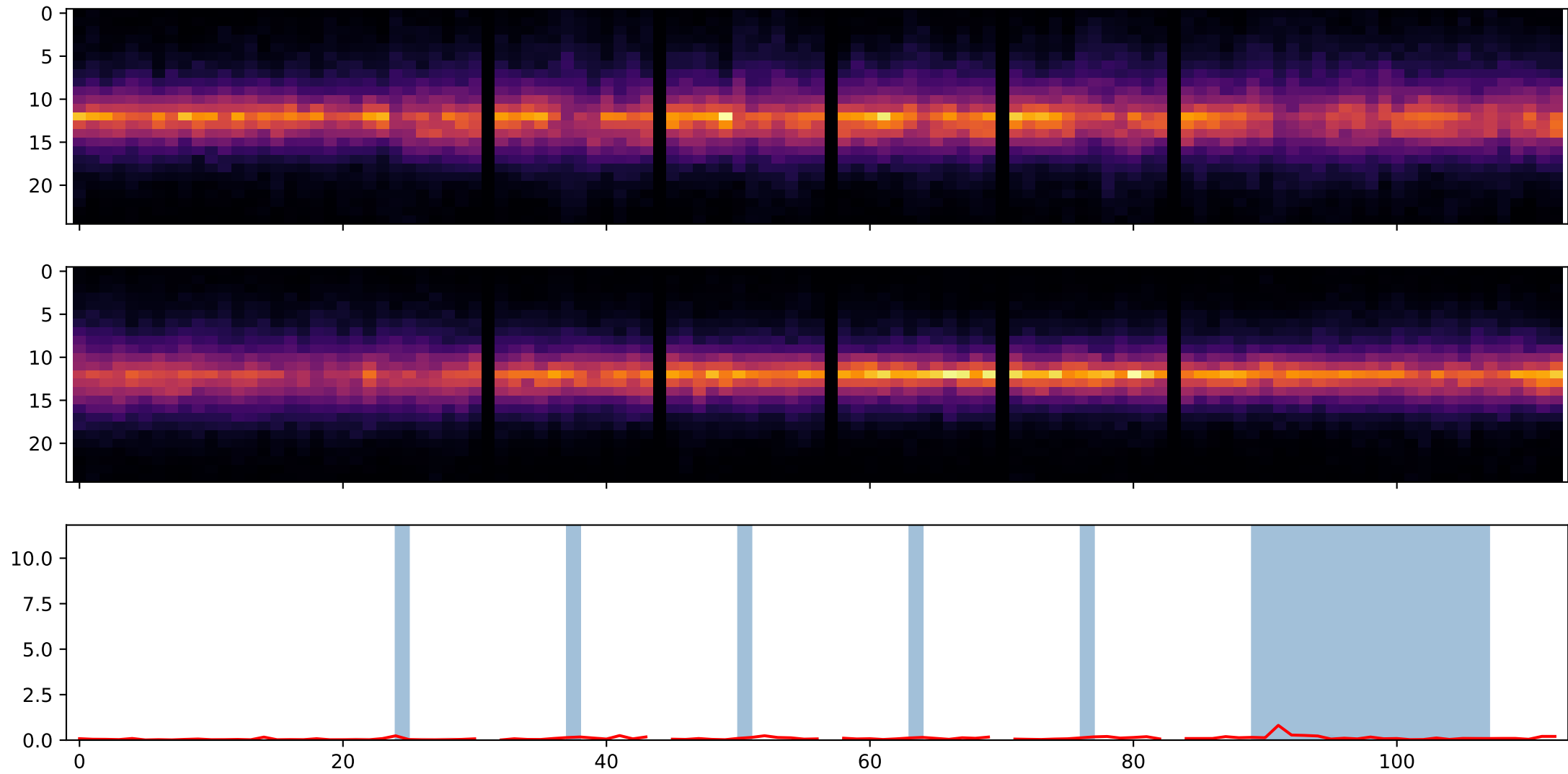
d_angular_velocity_tail_base



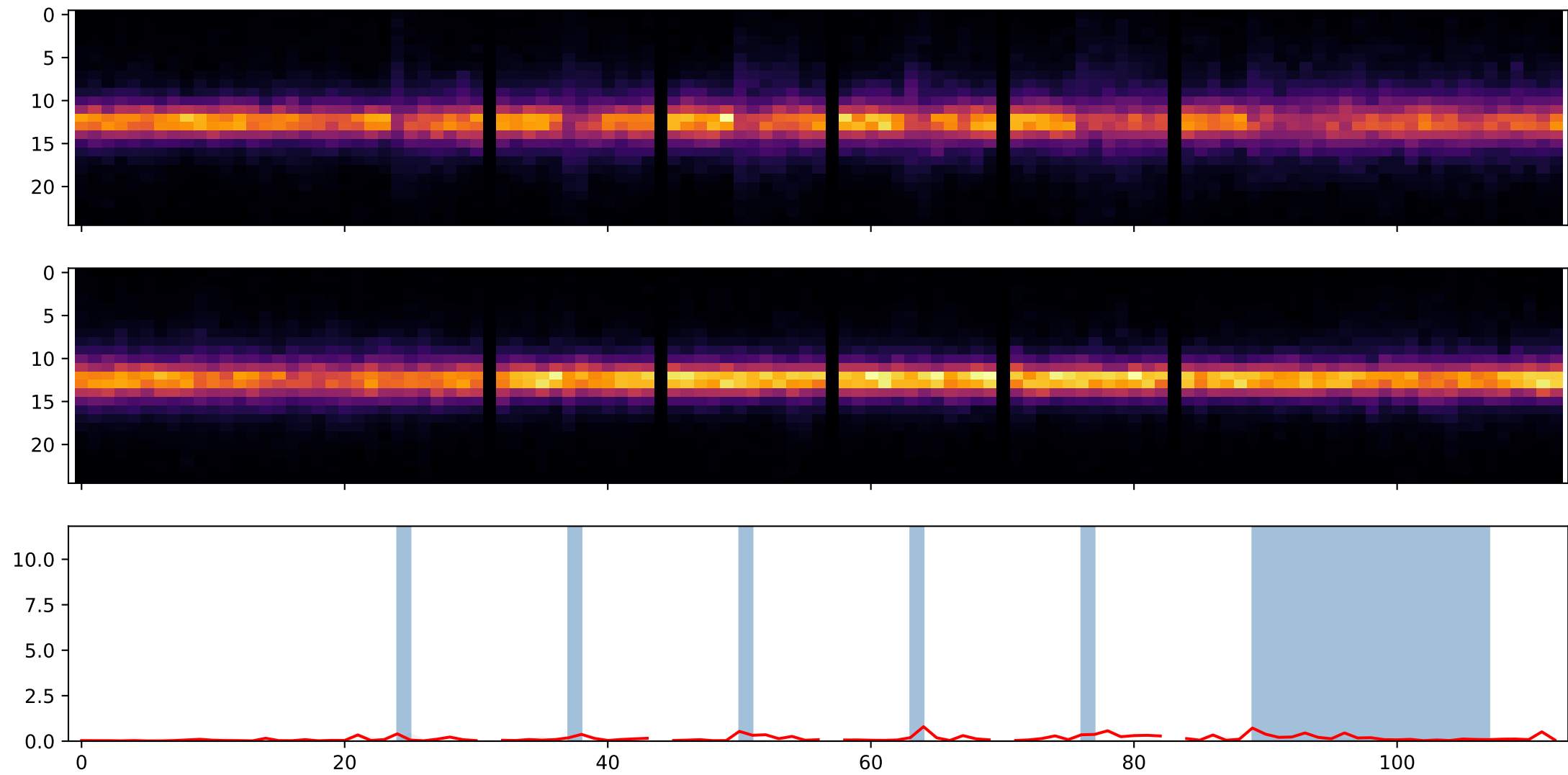
d_relative_to_hips_radial_velocity_tail_tip



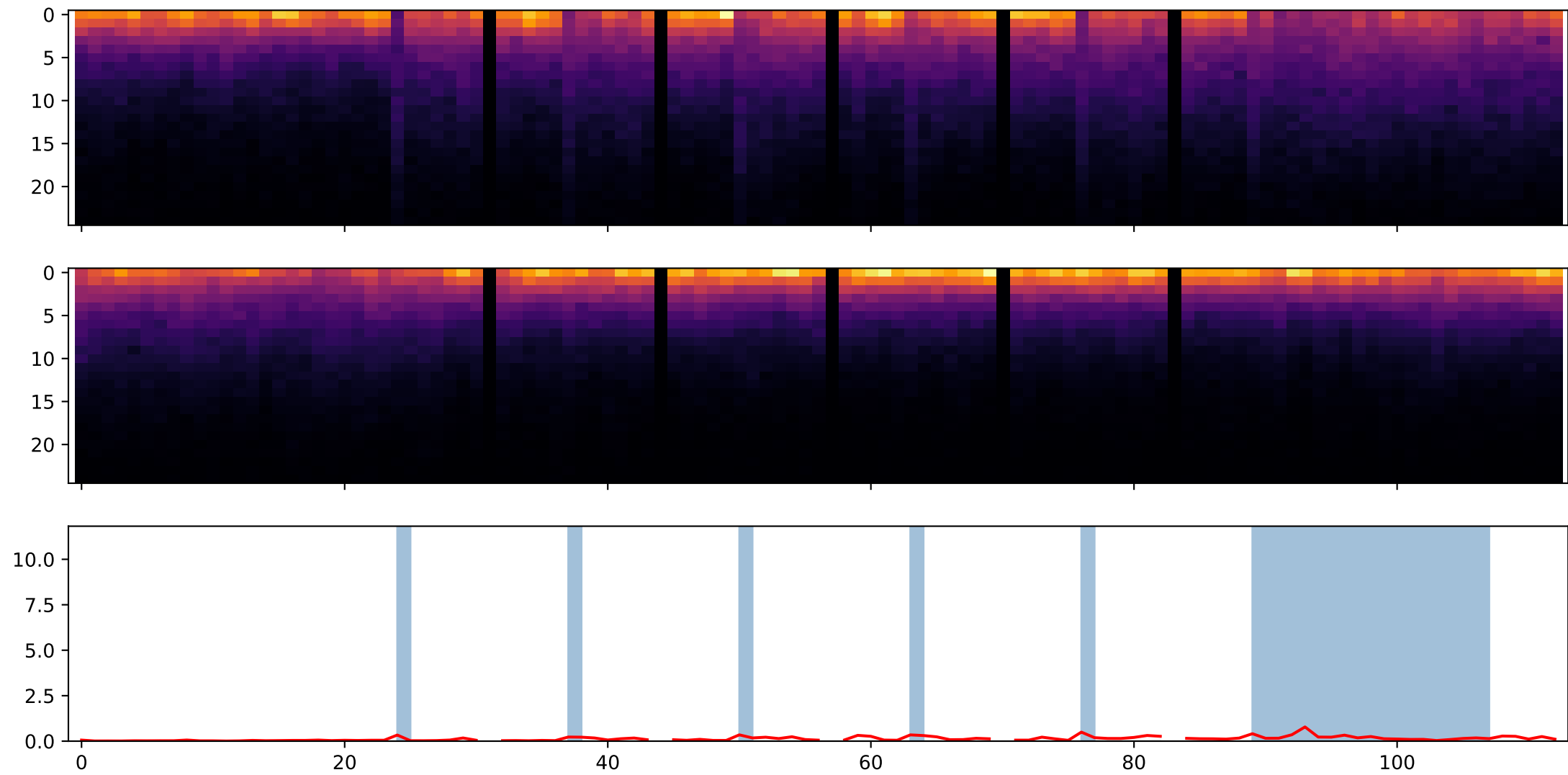
d_major_axis



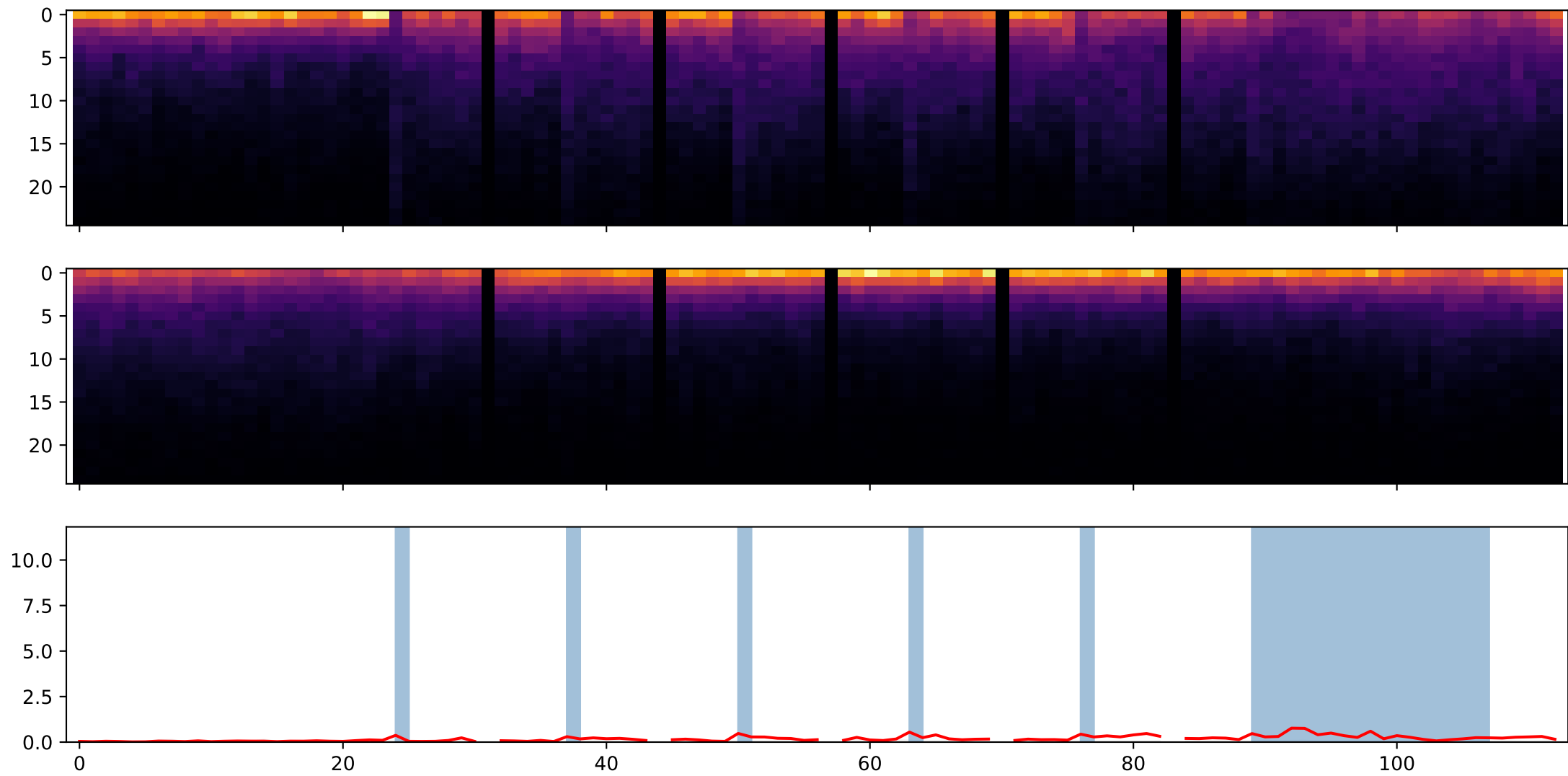
relative_to_body_radial_velocity_neck



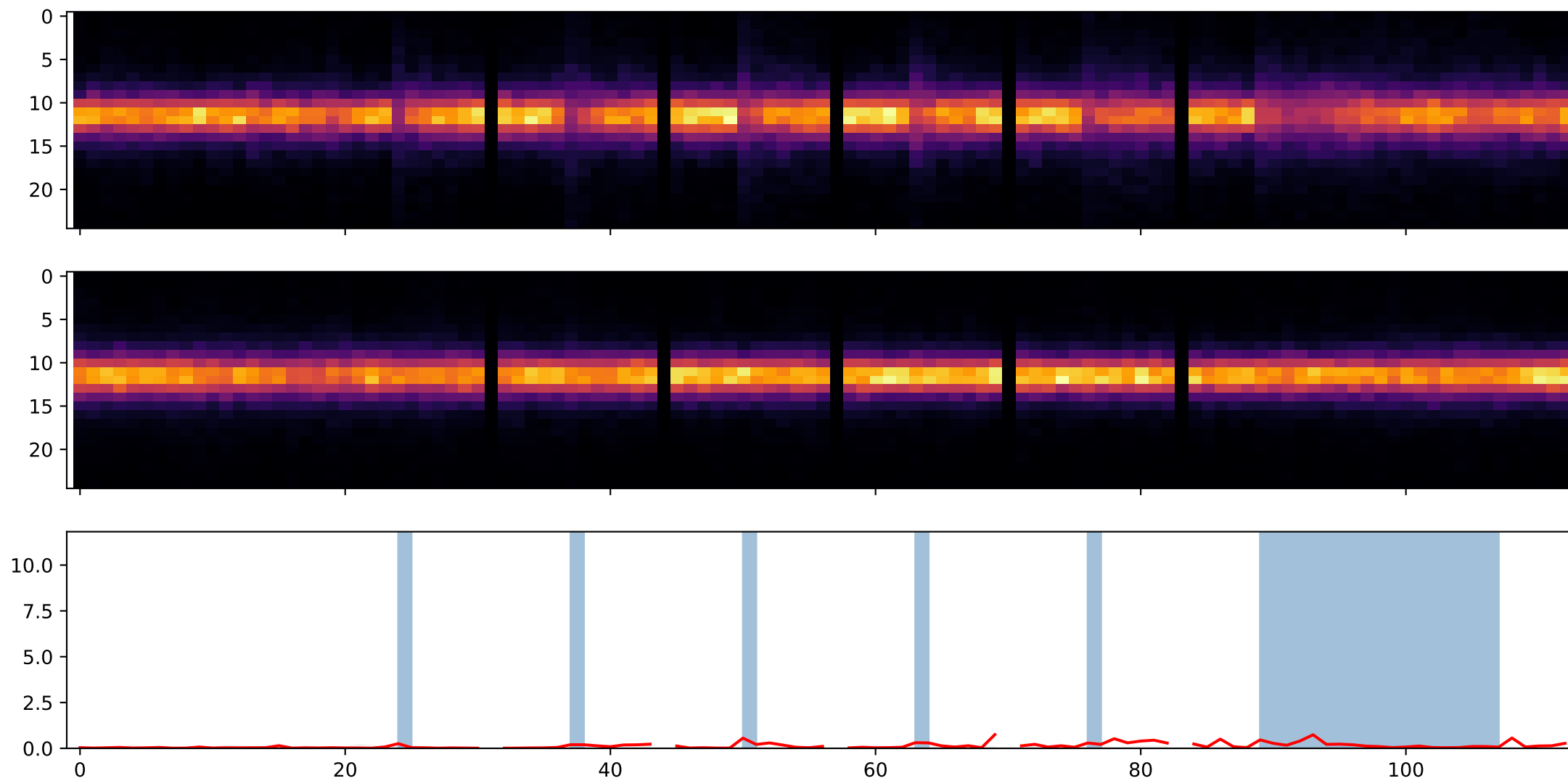
d_curvature_std_hips



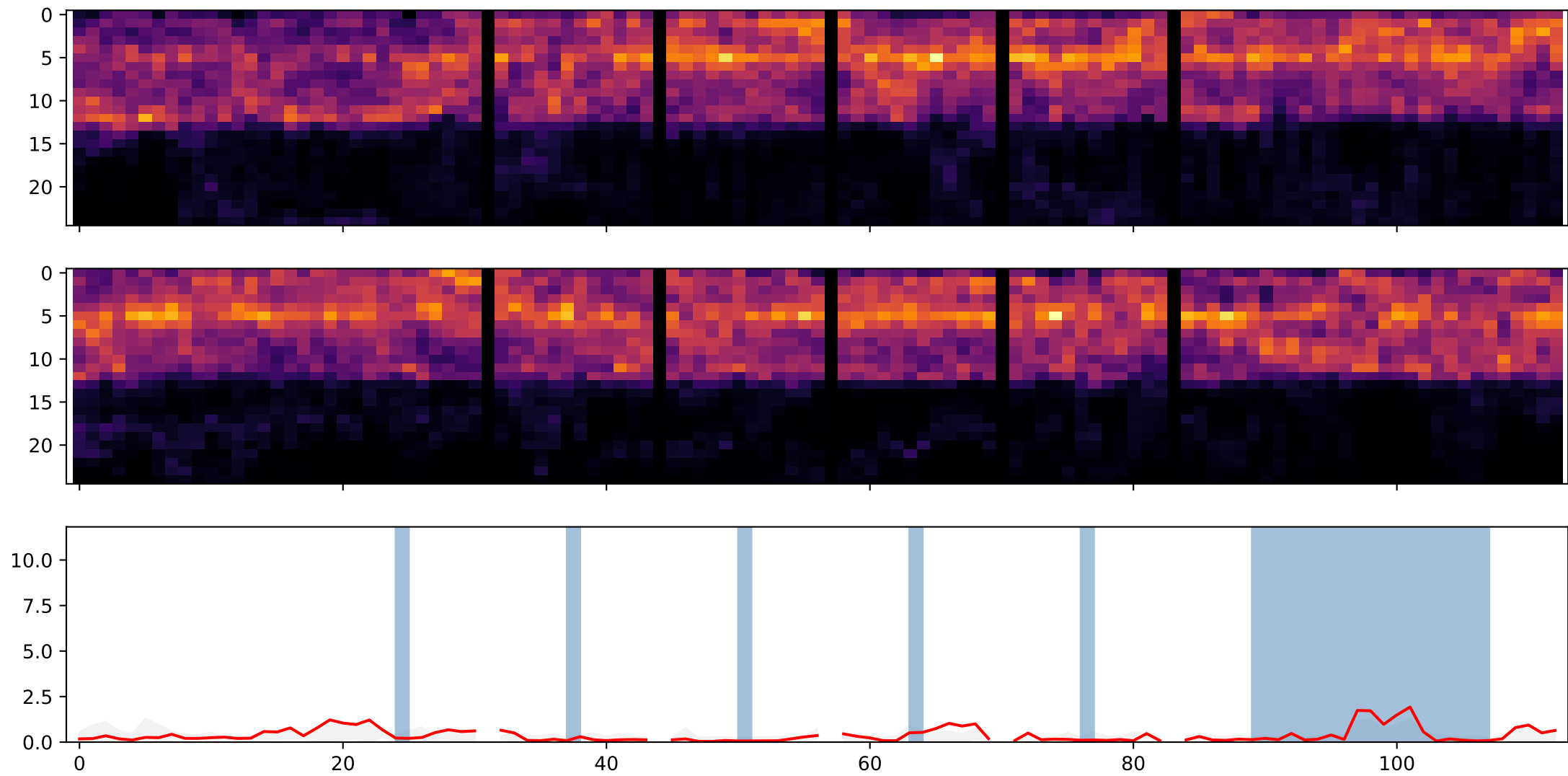
d_curvature_neck



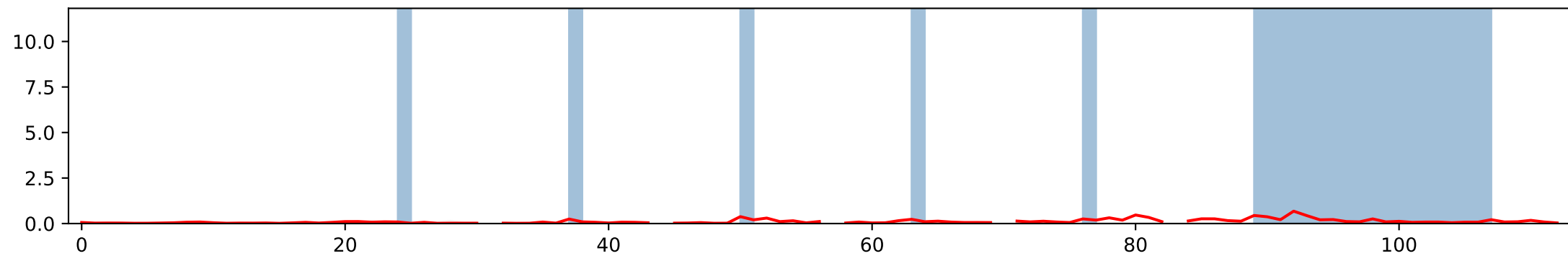
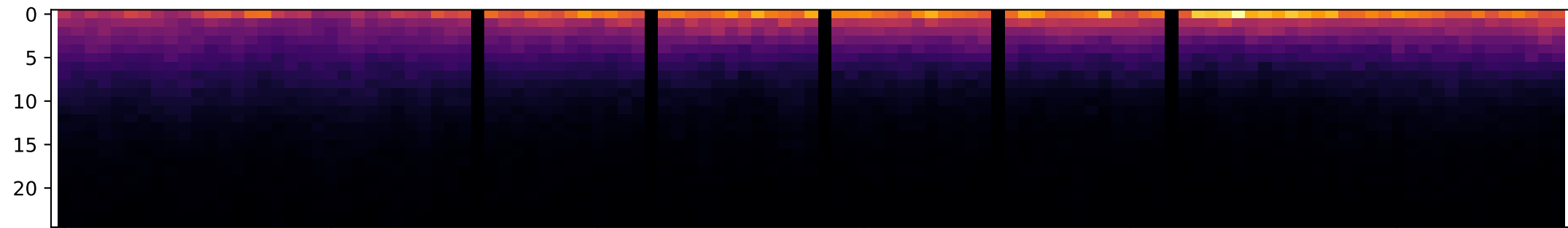
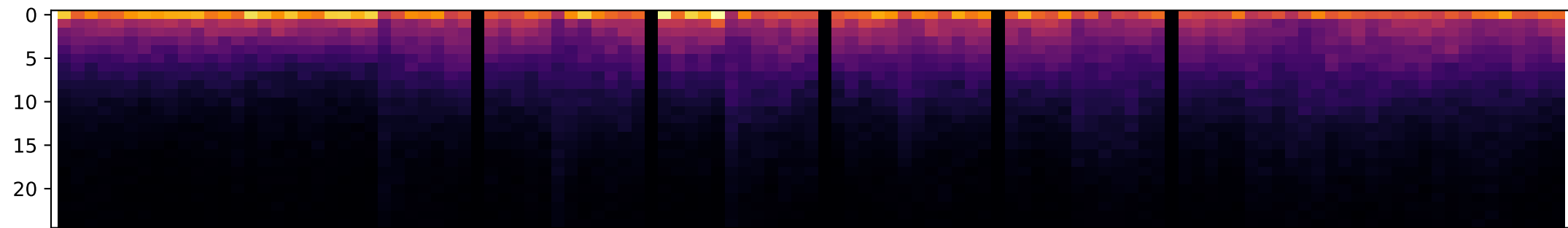
d_relative_to_body_radial_velocity_hips



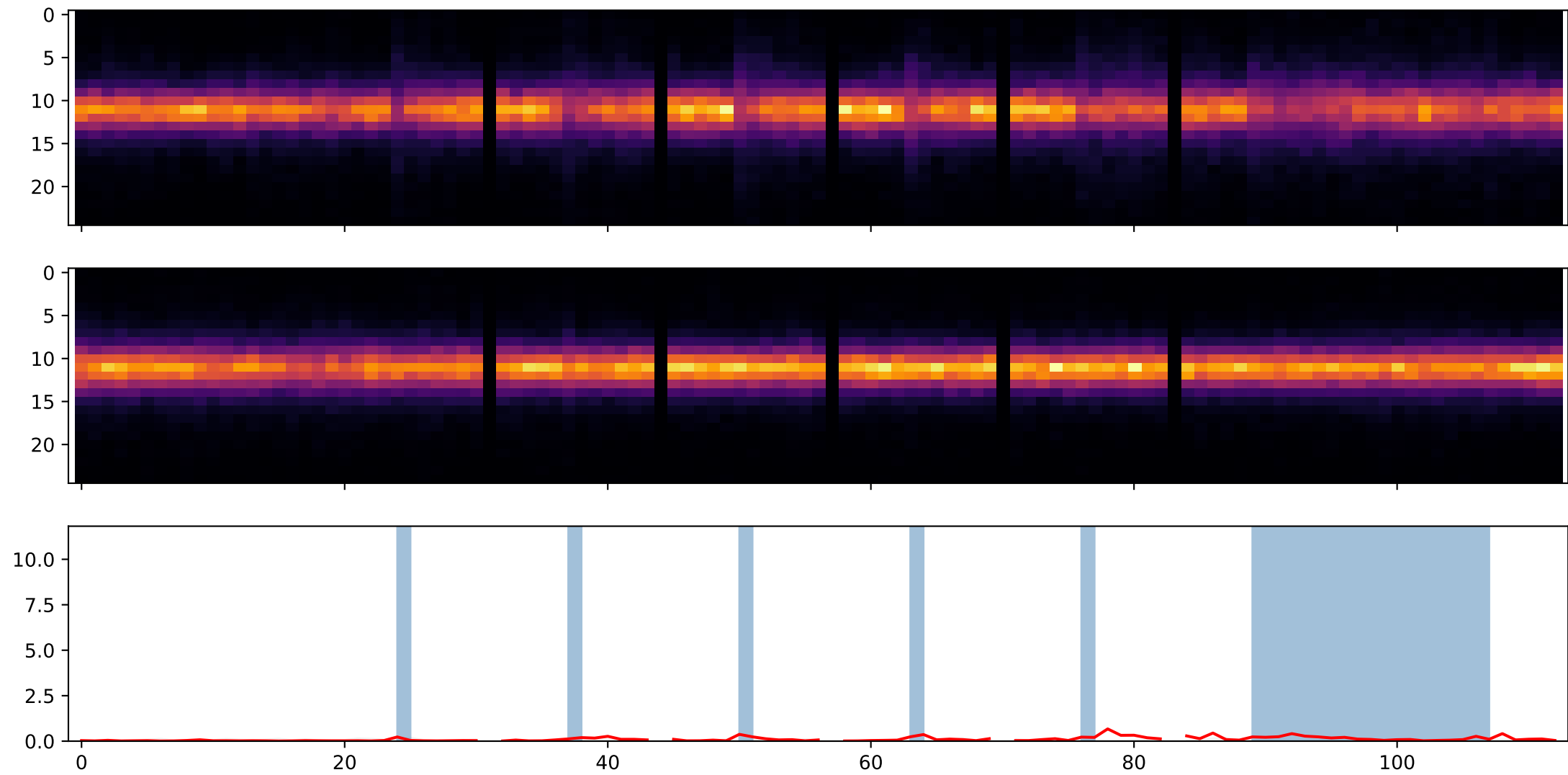
width_midbody



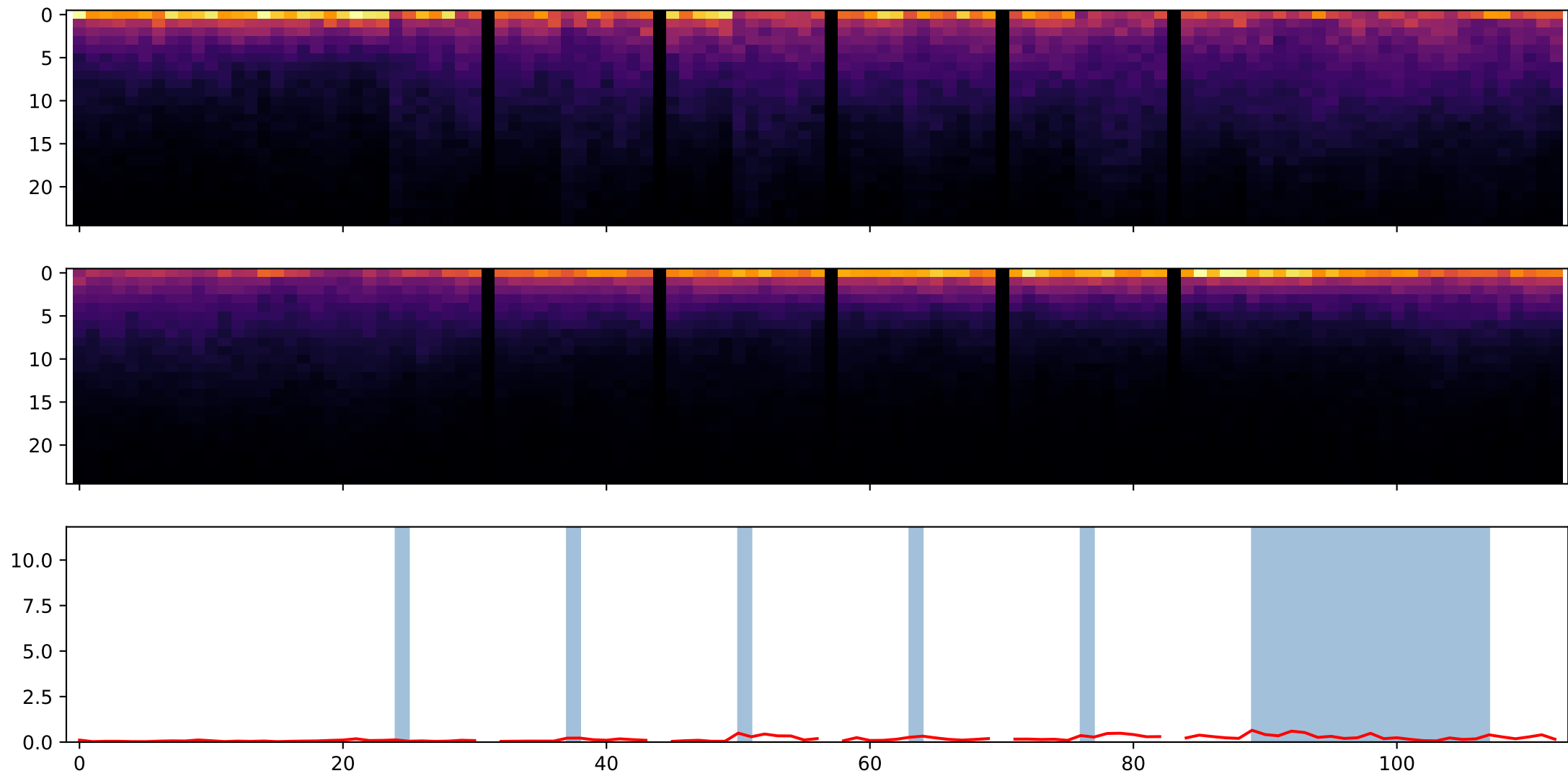
d_angular_velocity_head_base



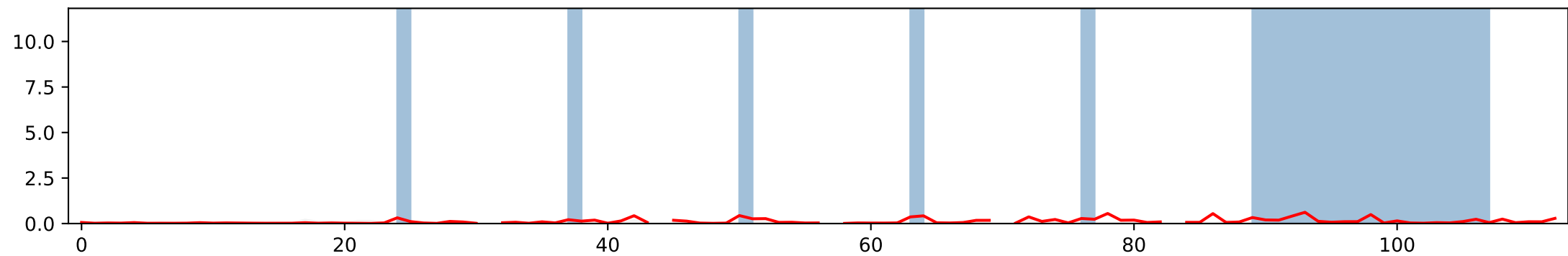
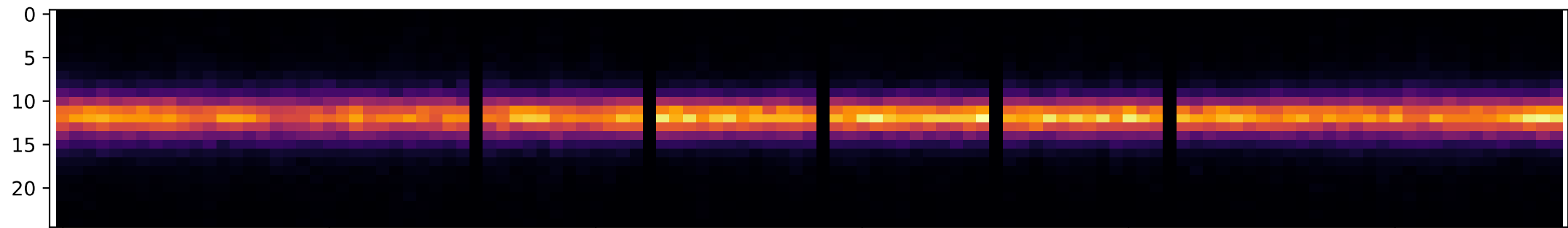
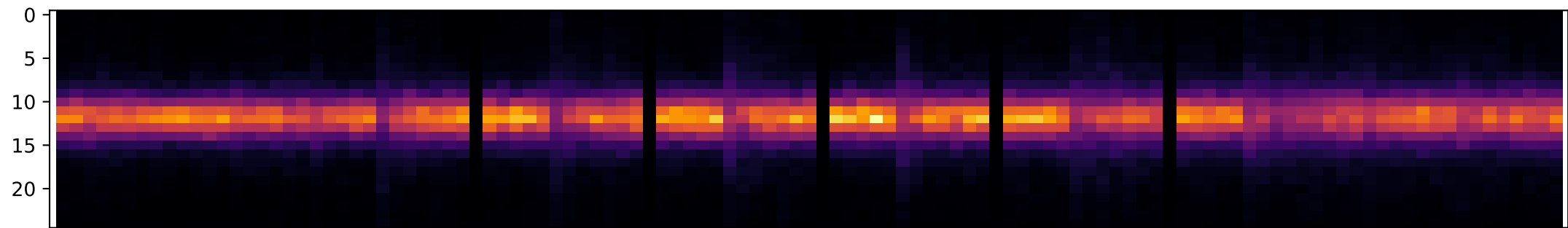
d_relative_to_body_radial_velocity_neck



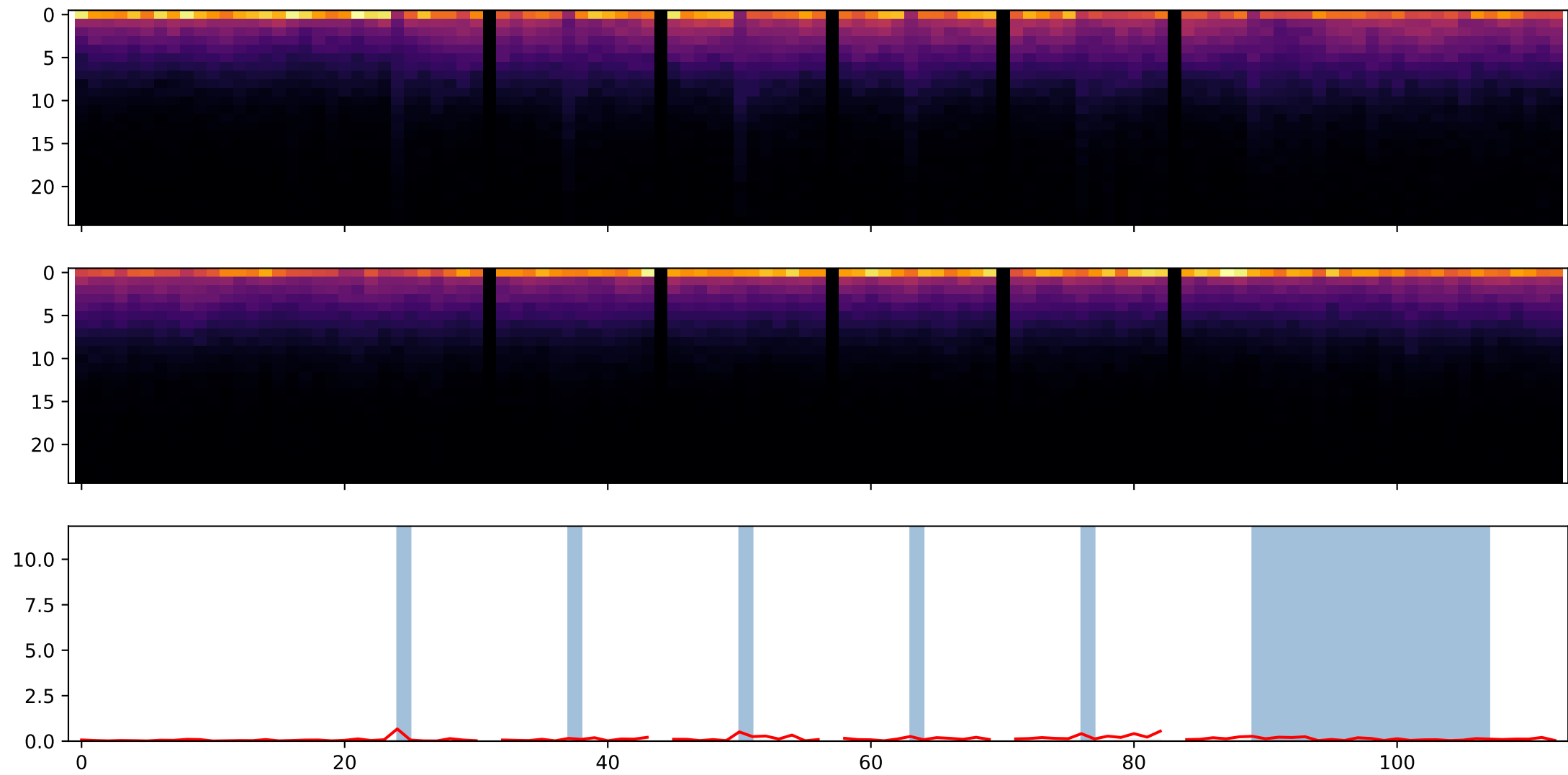
angular_velocity_head_base



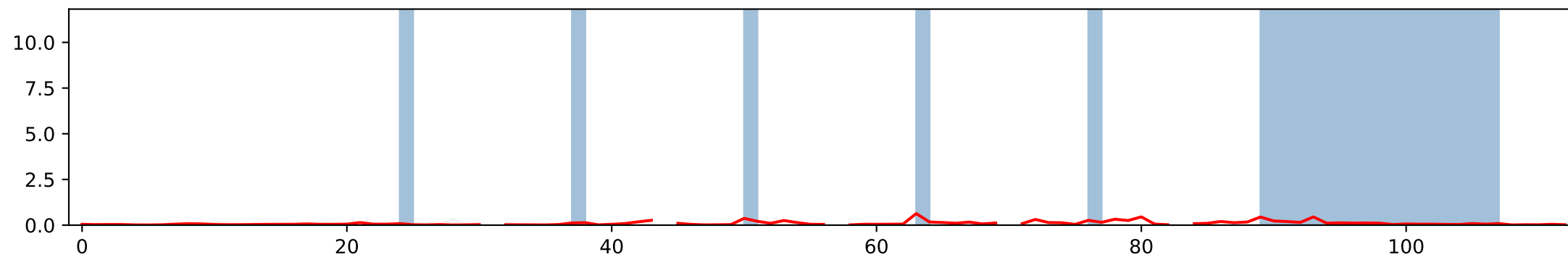
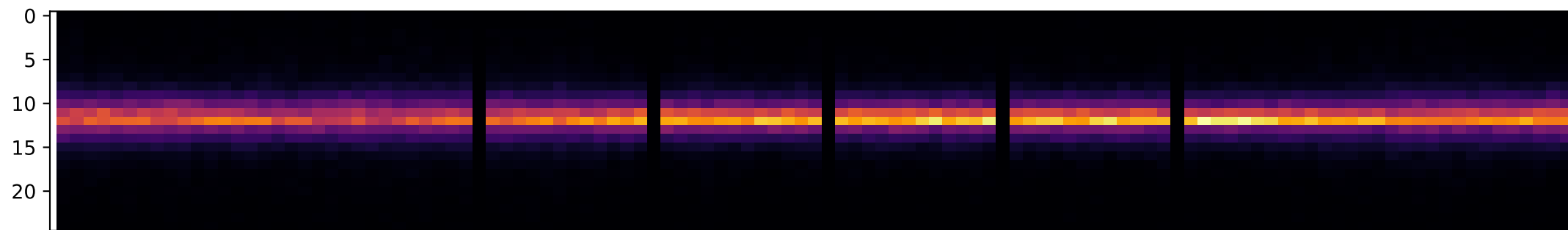
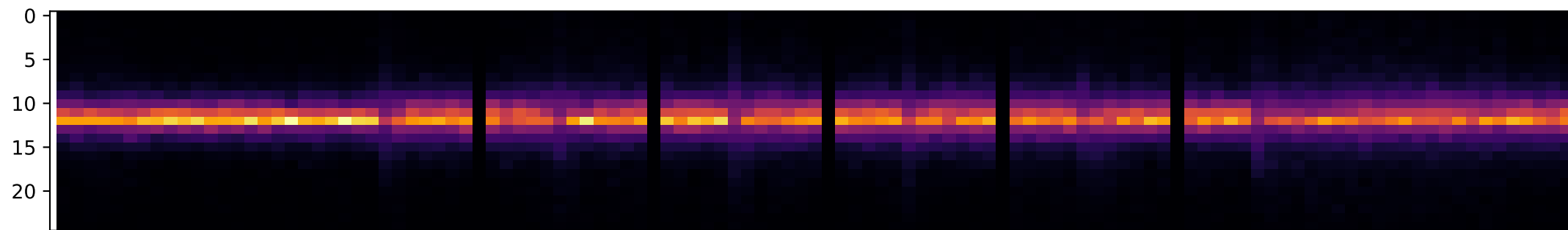
d_relative_to_body_radial_velocity_tail_tip



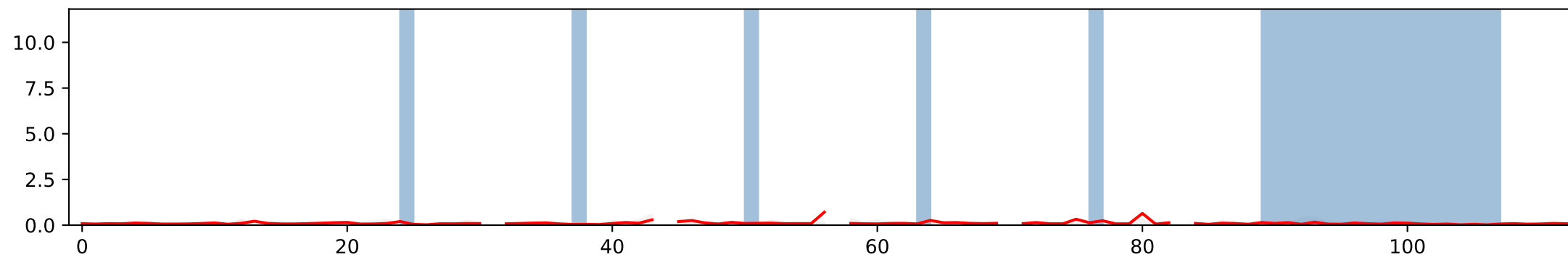
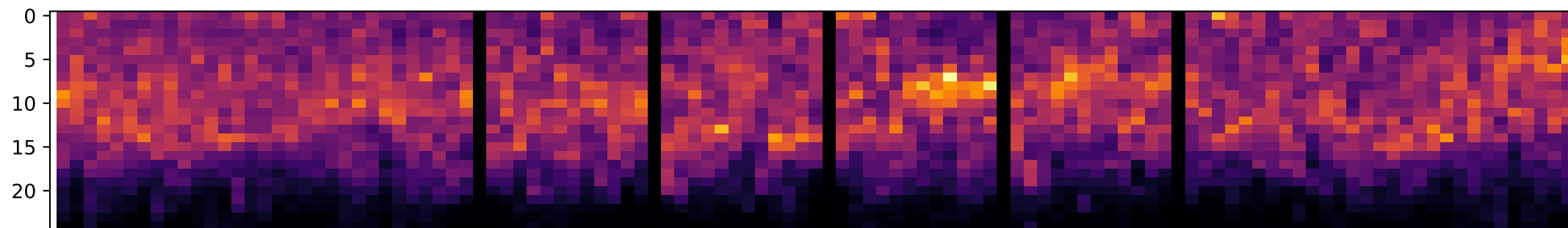
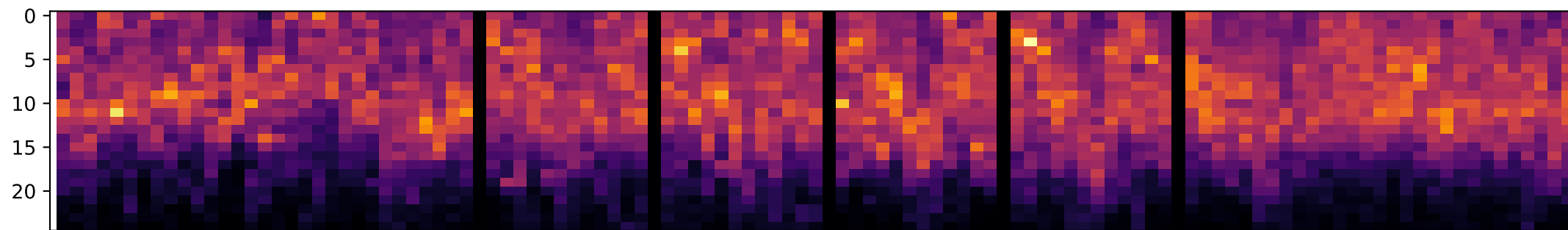
d_angular_velocity_tail_tip



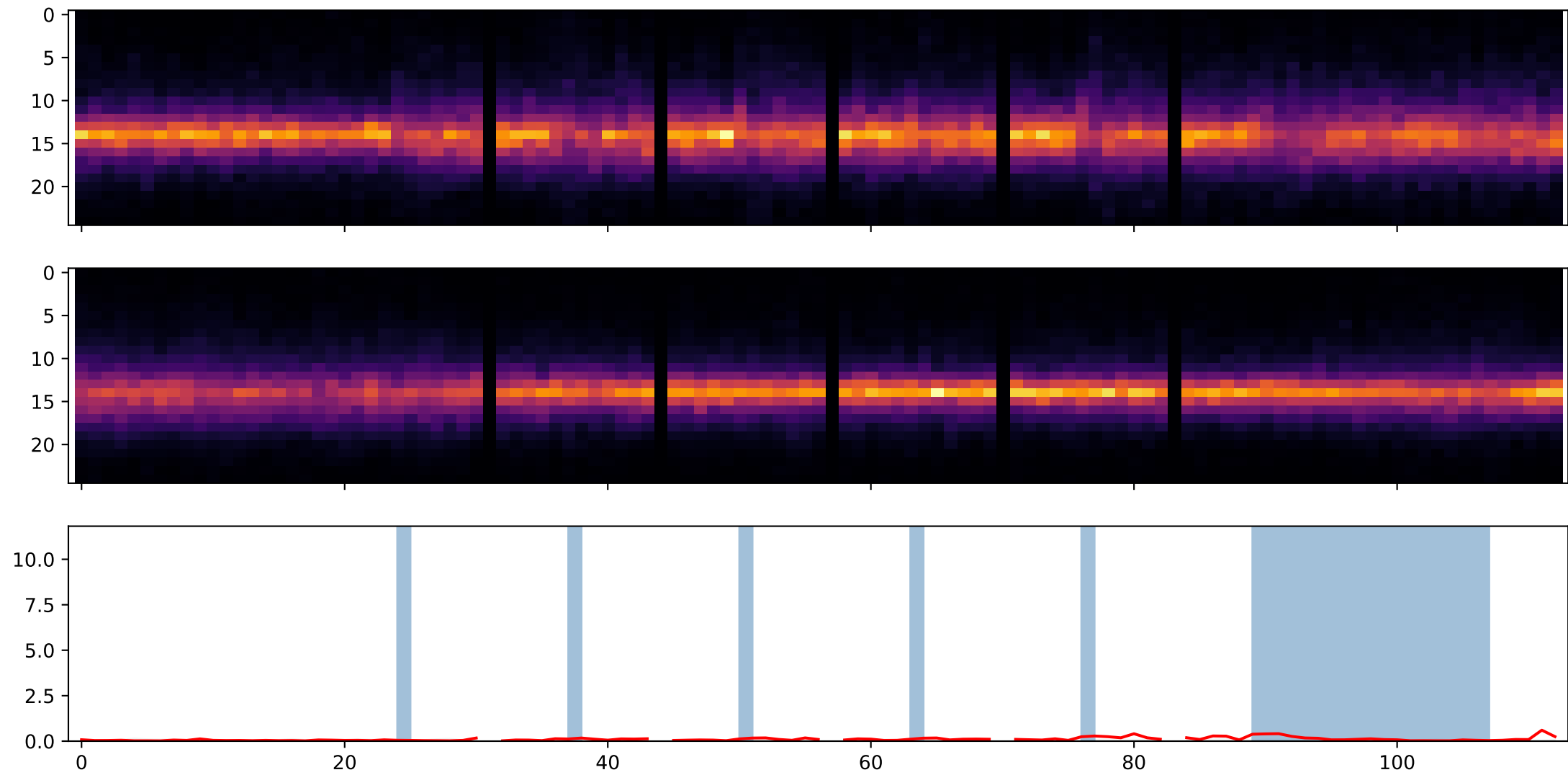
d_speed_tail_base



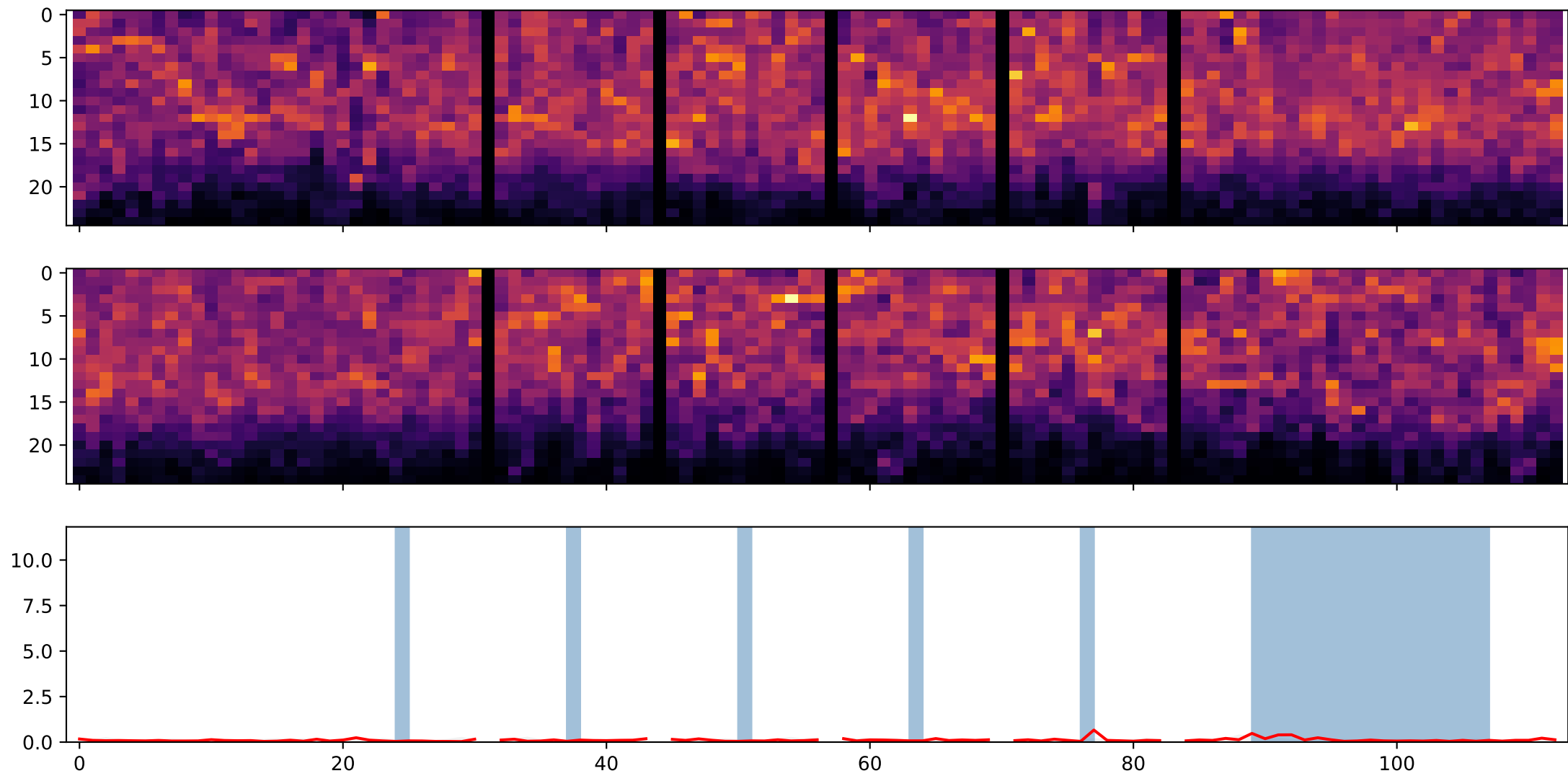
curvature_hips



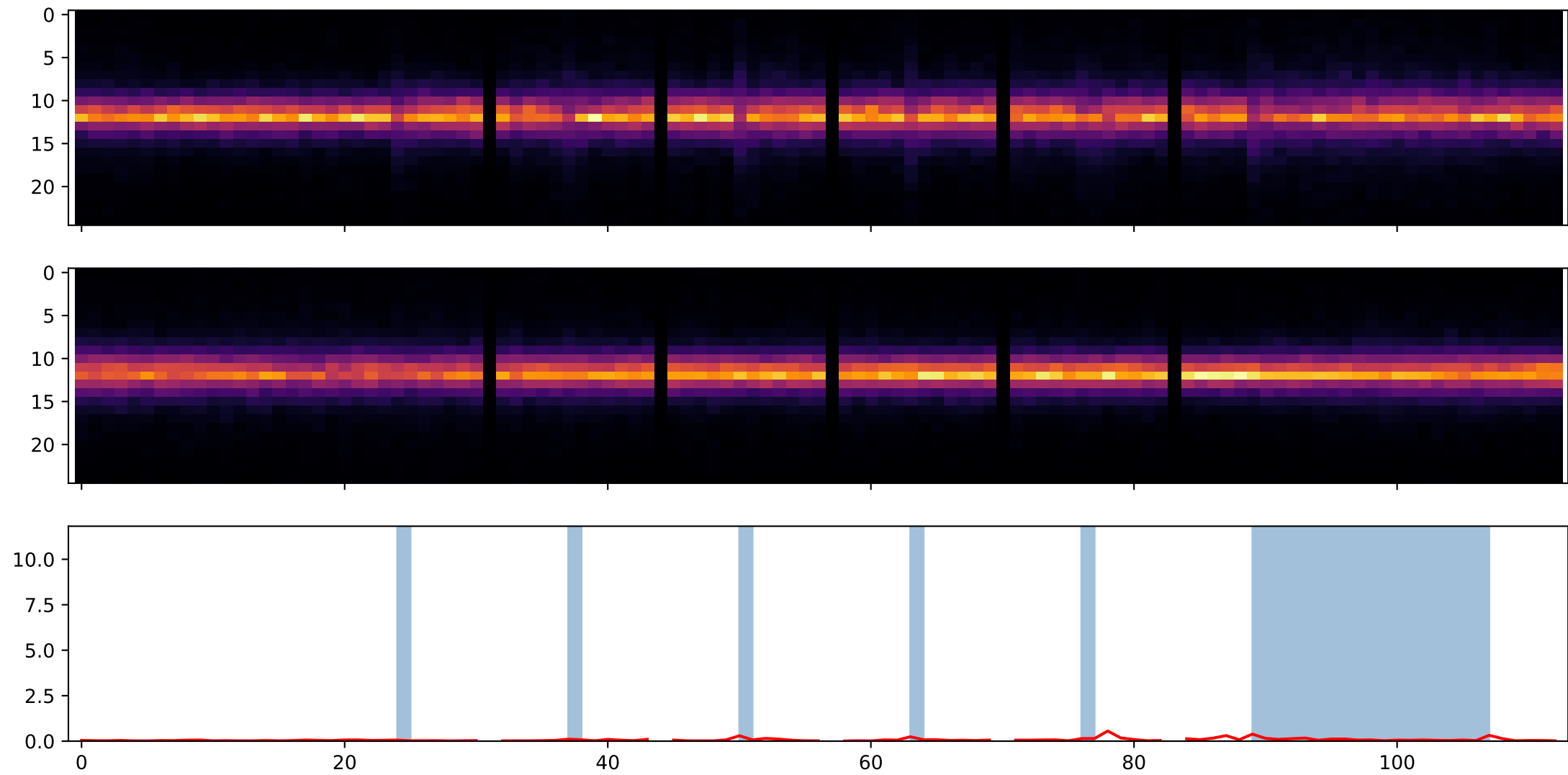
relative_to_body_radial_velocity_head_tip



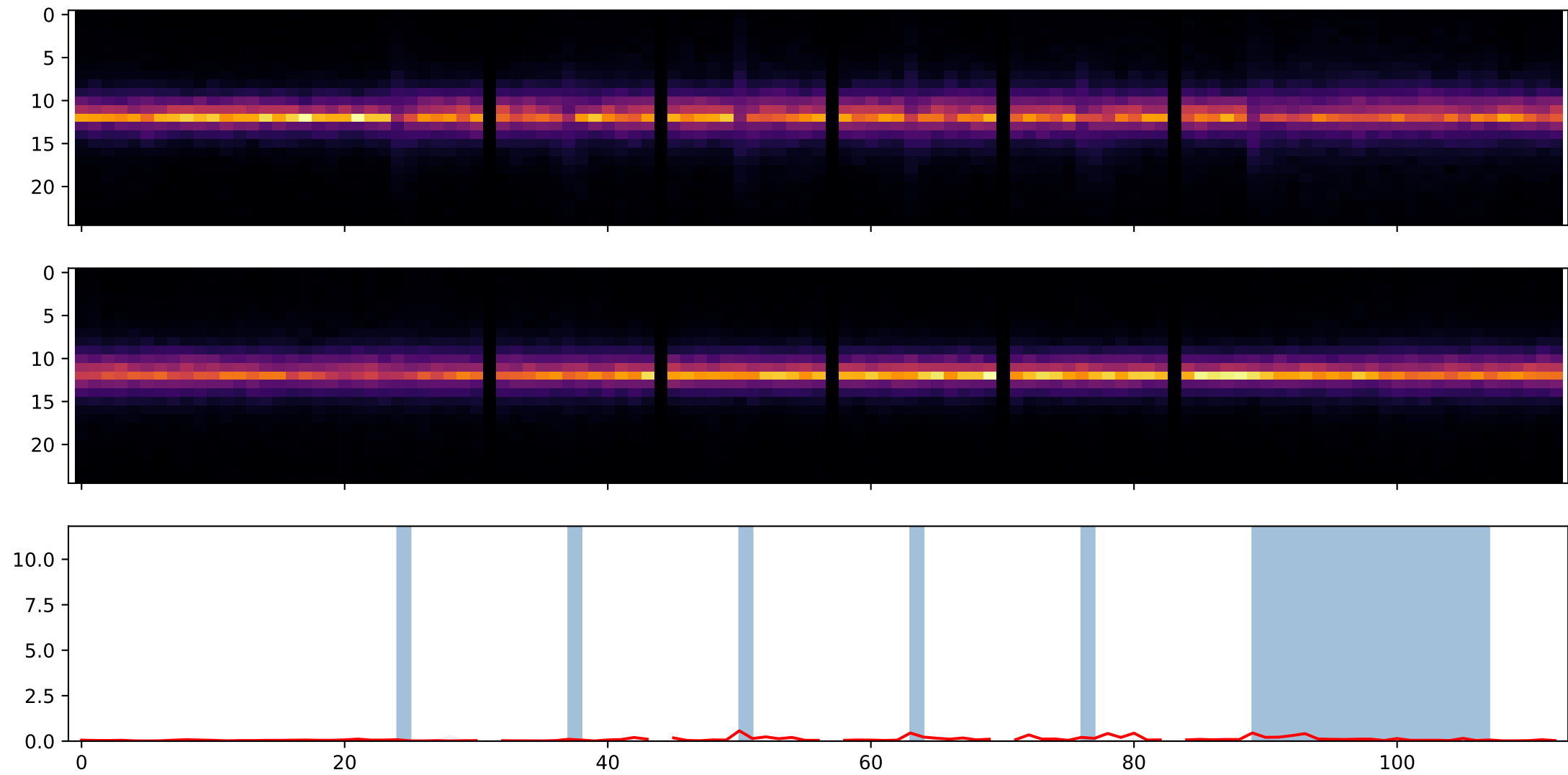
curvature_mean_neck



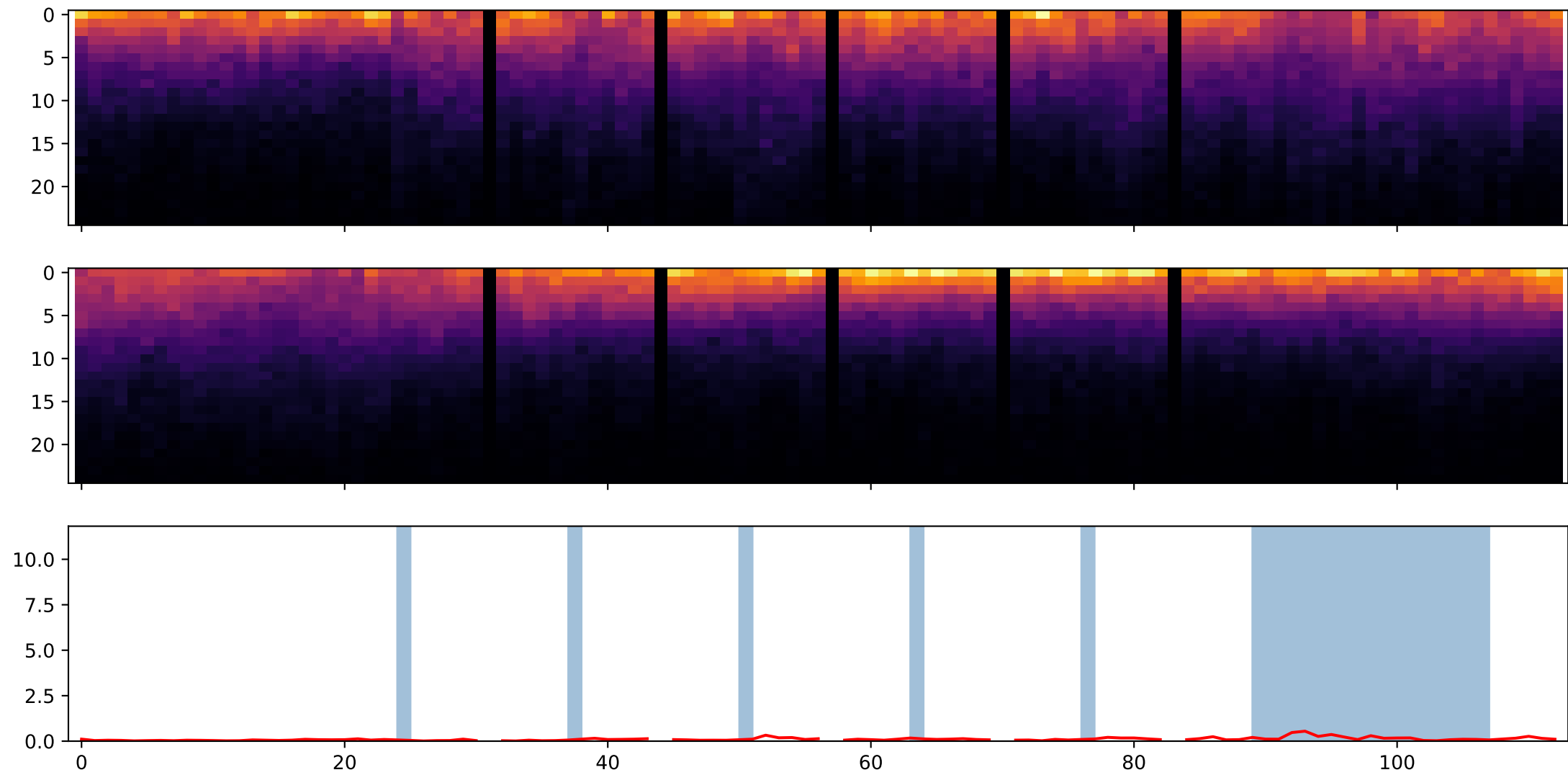
d_speed_neck



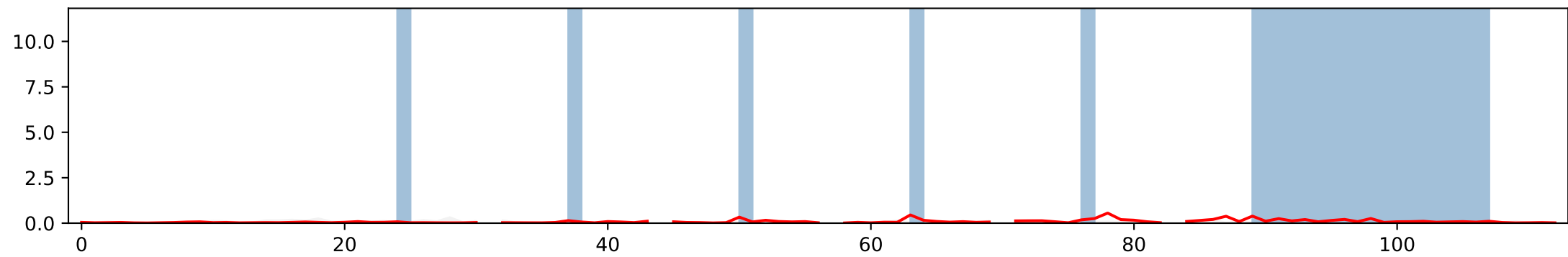
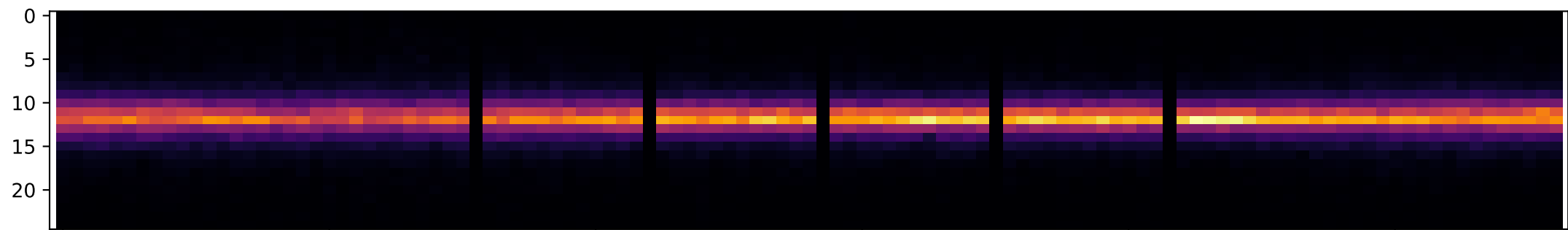
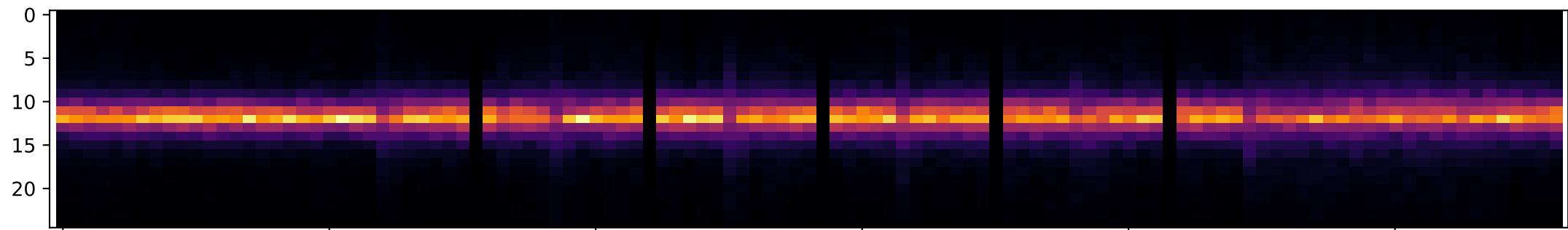
d_speed_tail_tip



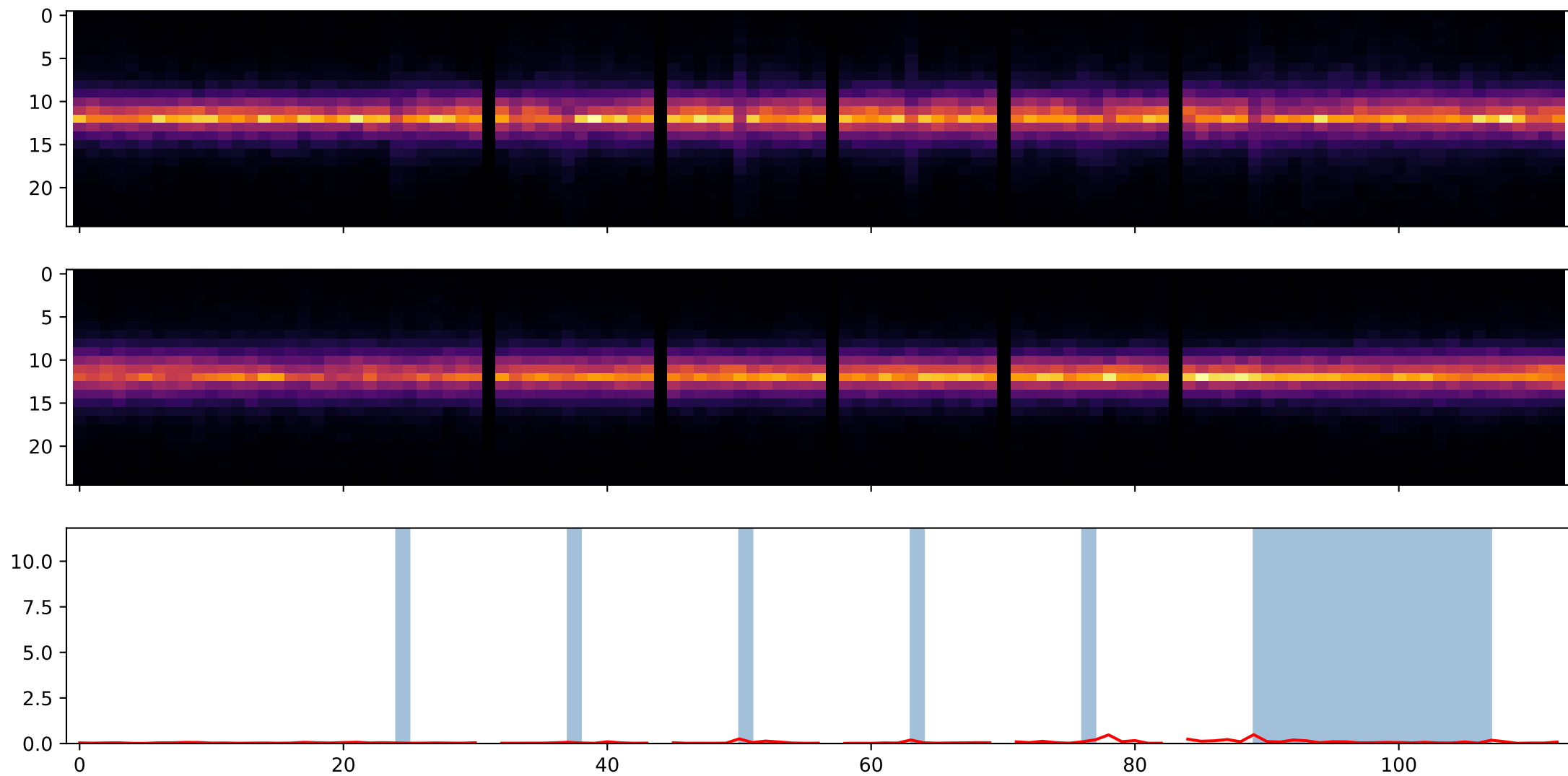
d_eigen_projection_4



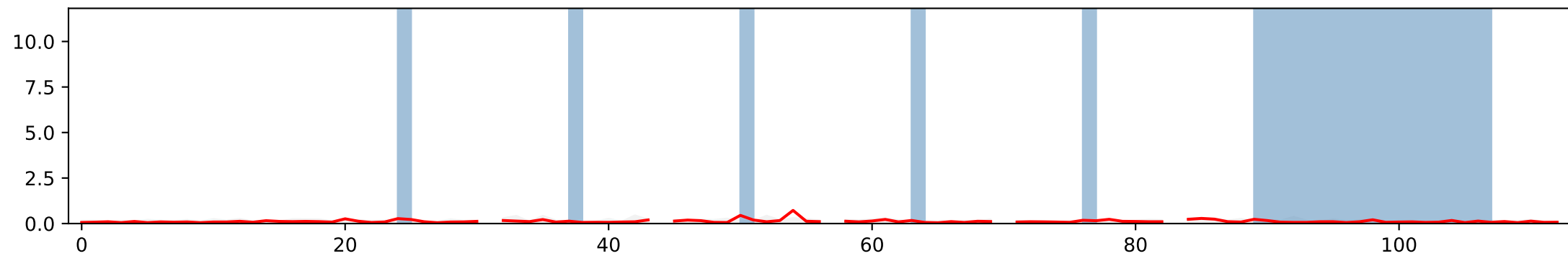
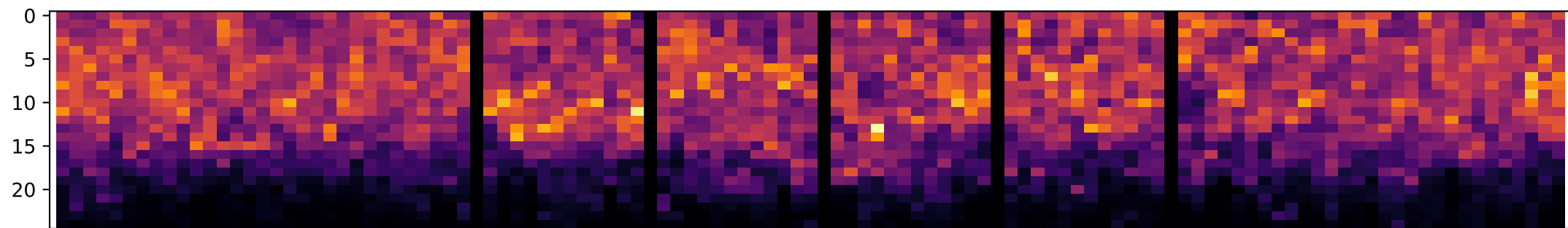
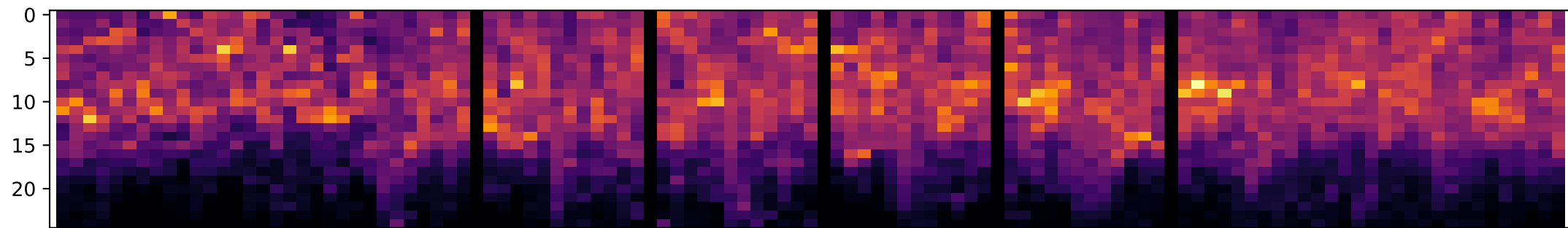
d_speed



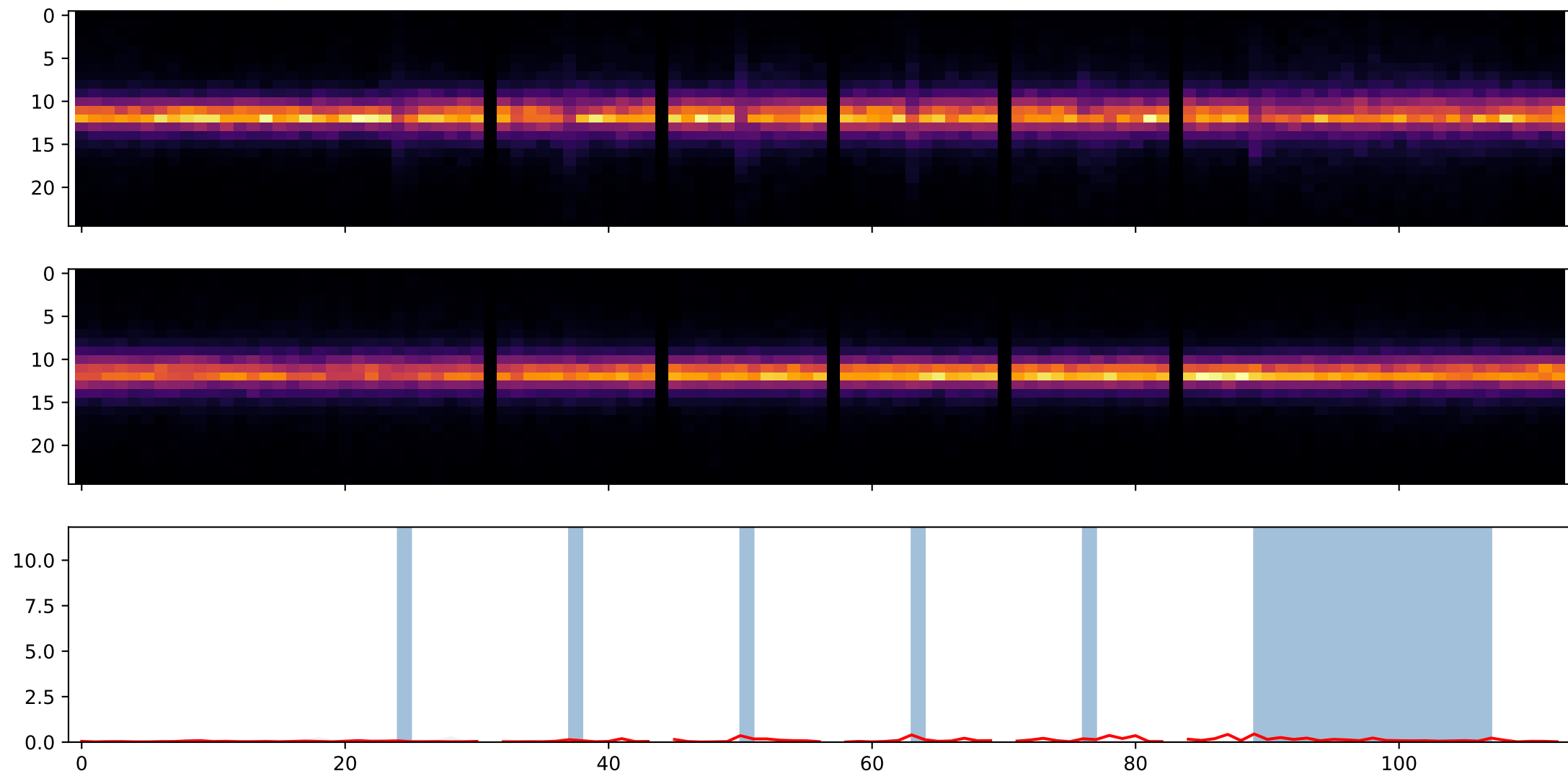
d_speed_head_base



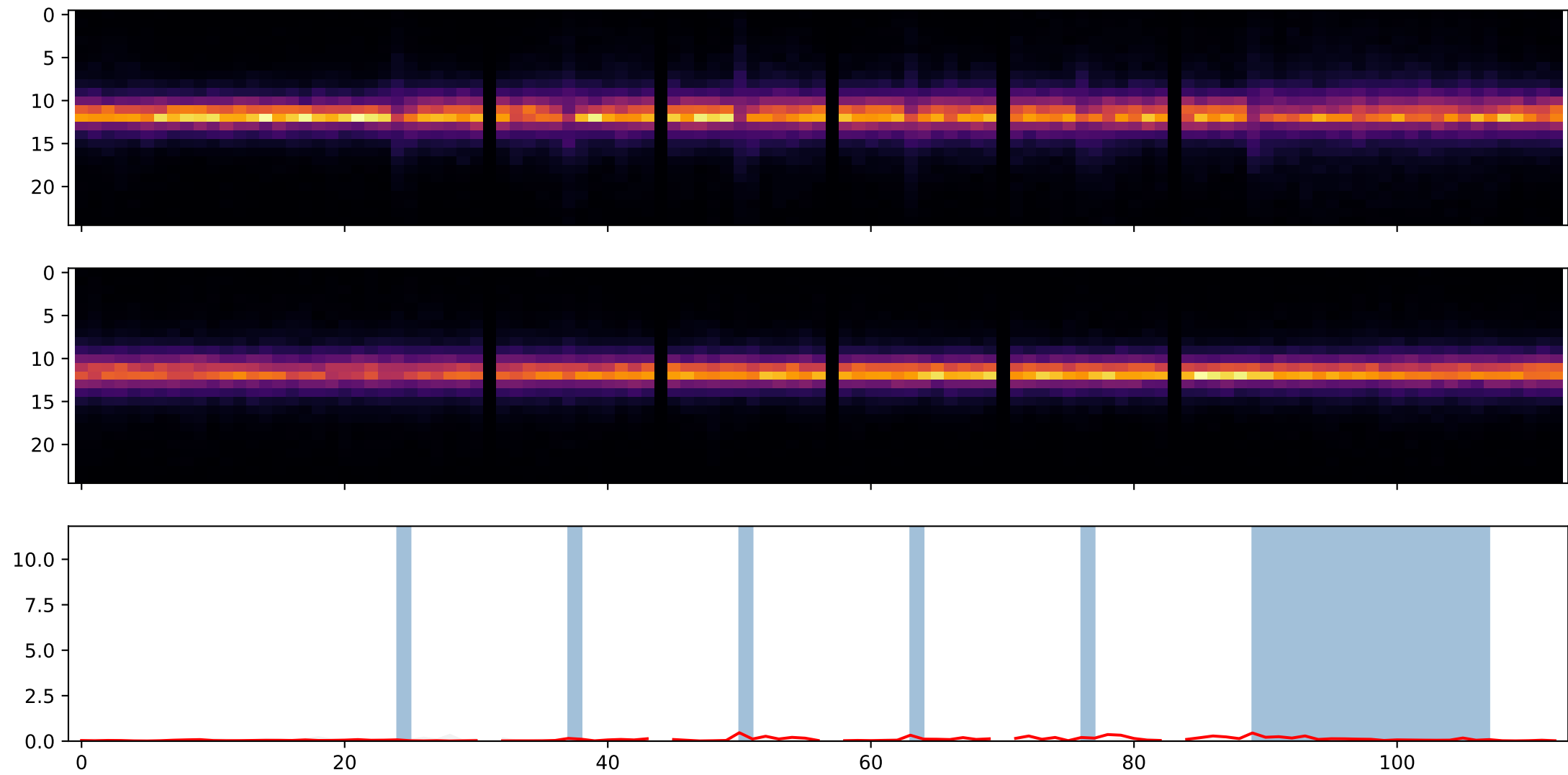
curvature_mean_tail



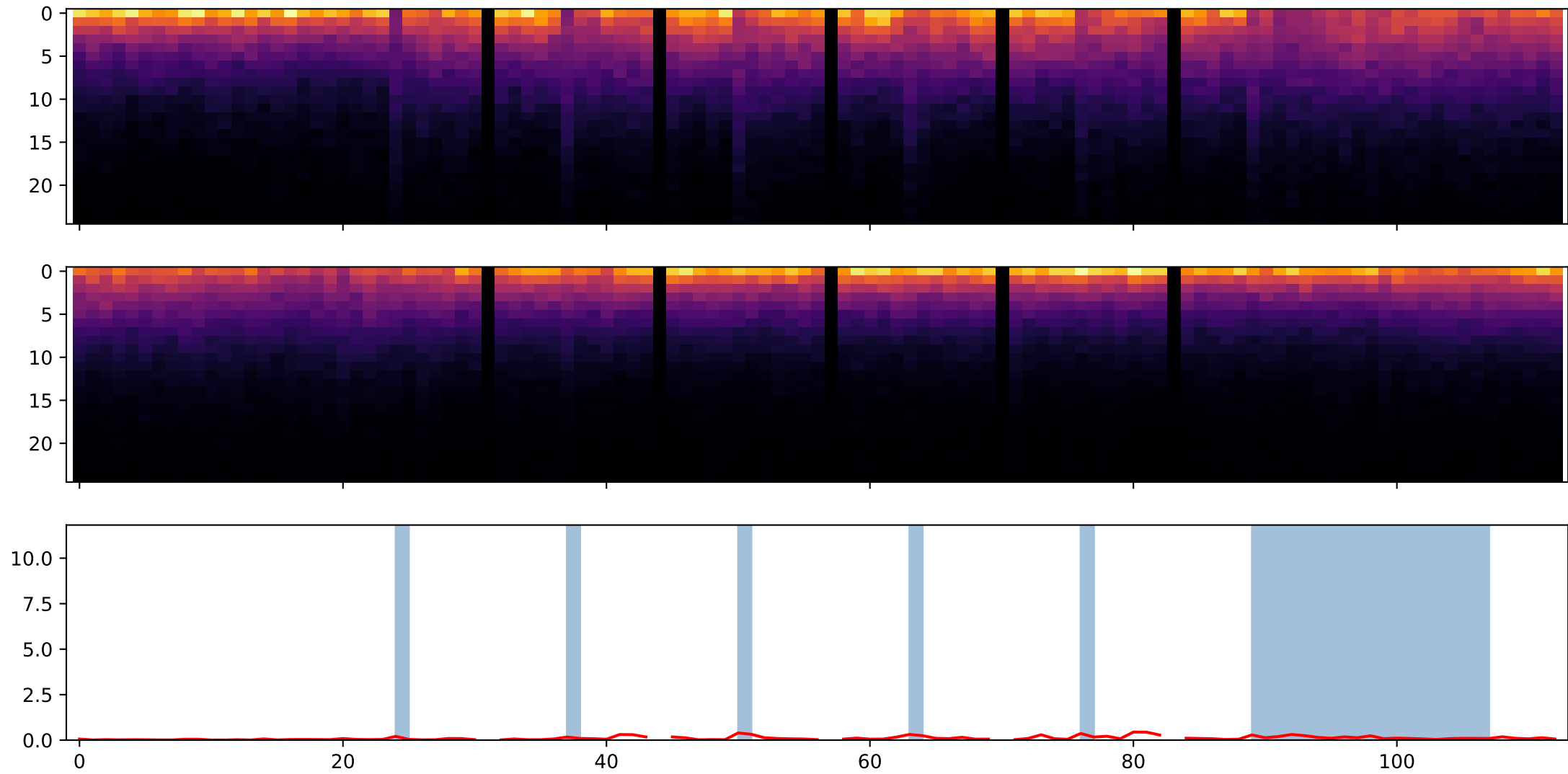
d_speed_midbody



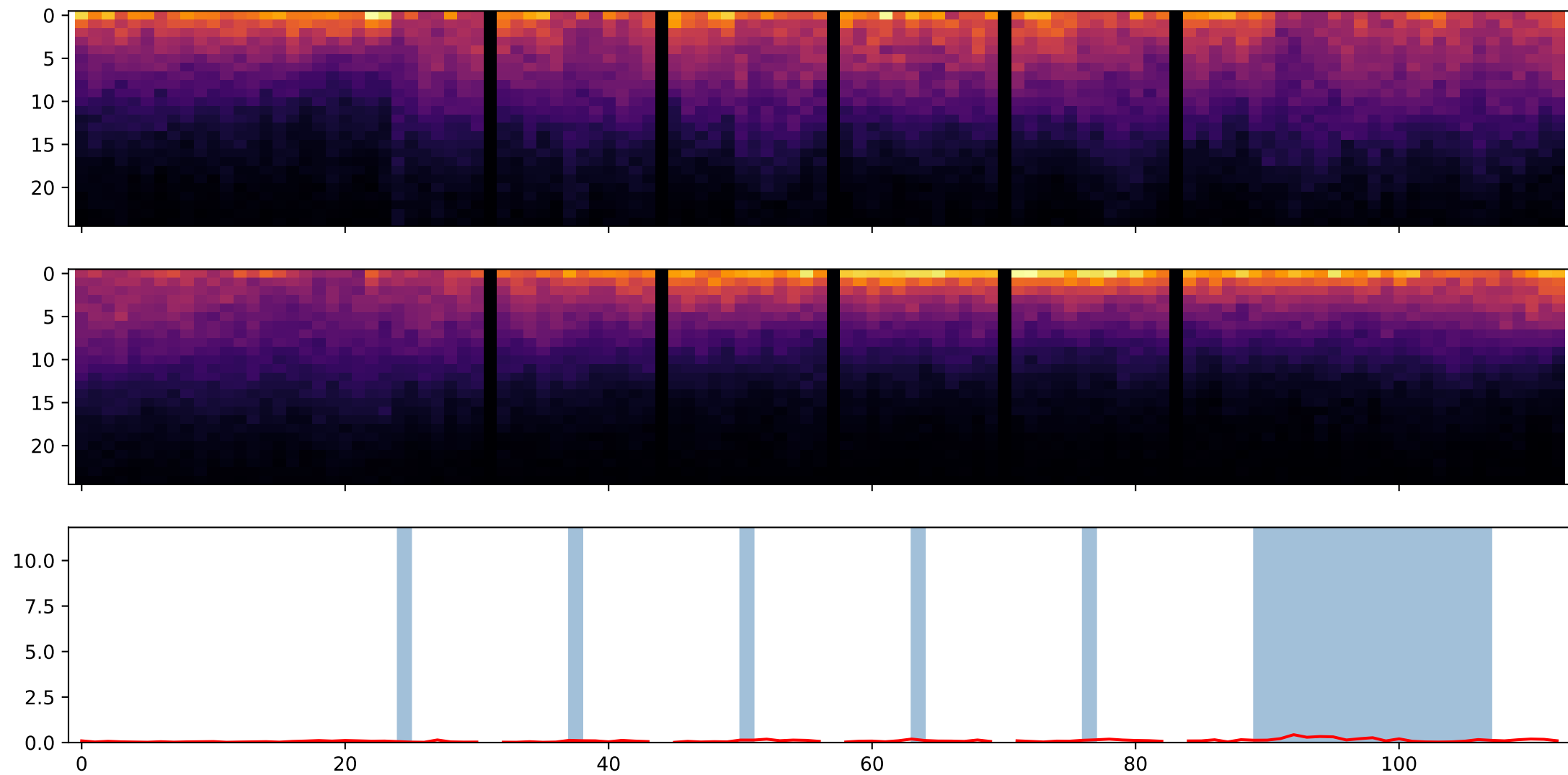
d_speed_hips



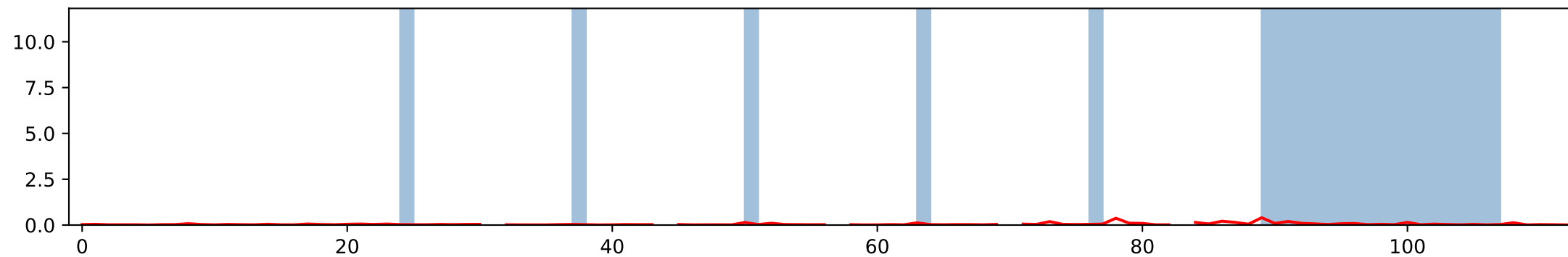
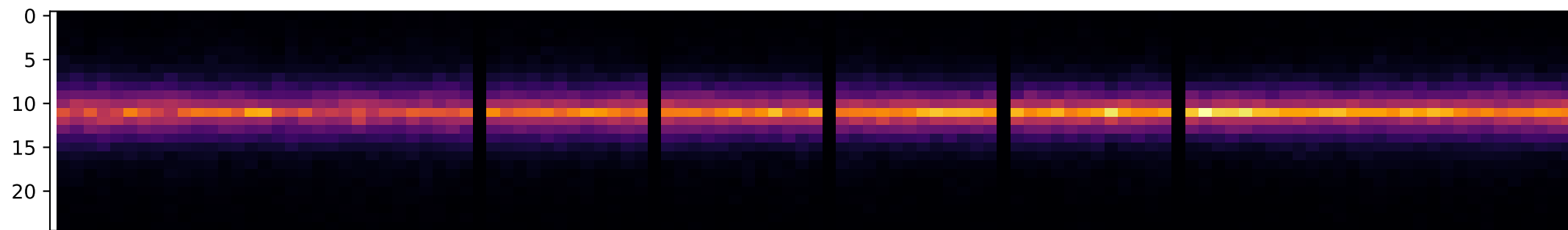
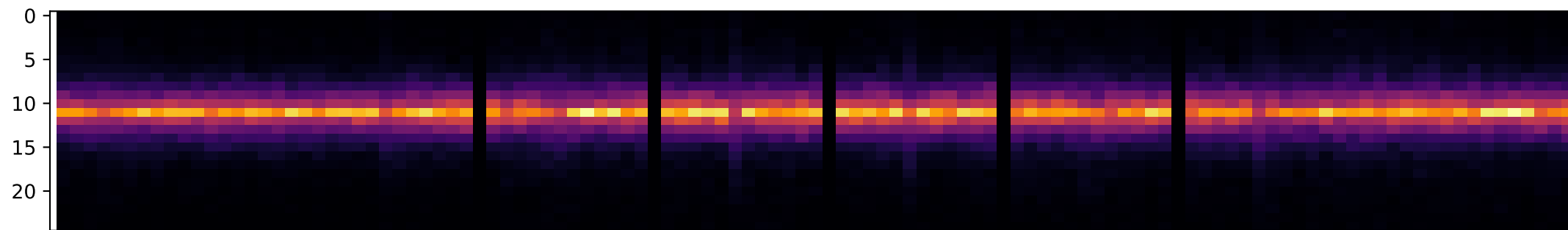
d_relative_to_tail_base_angular_velocity_tail_tip



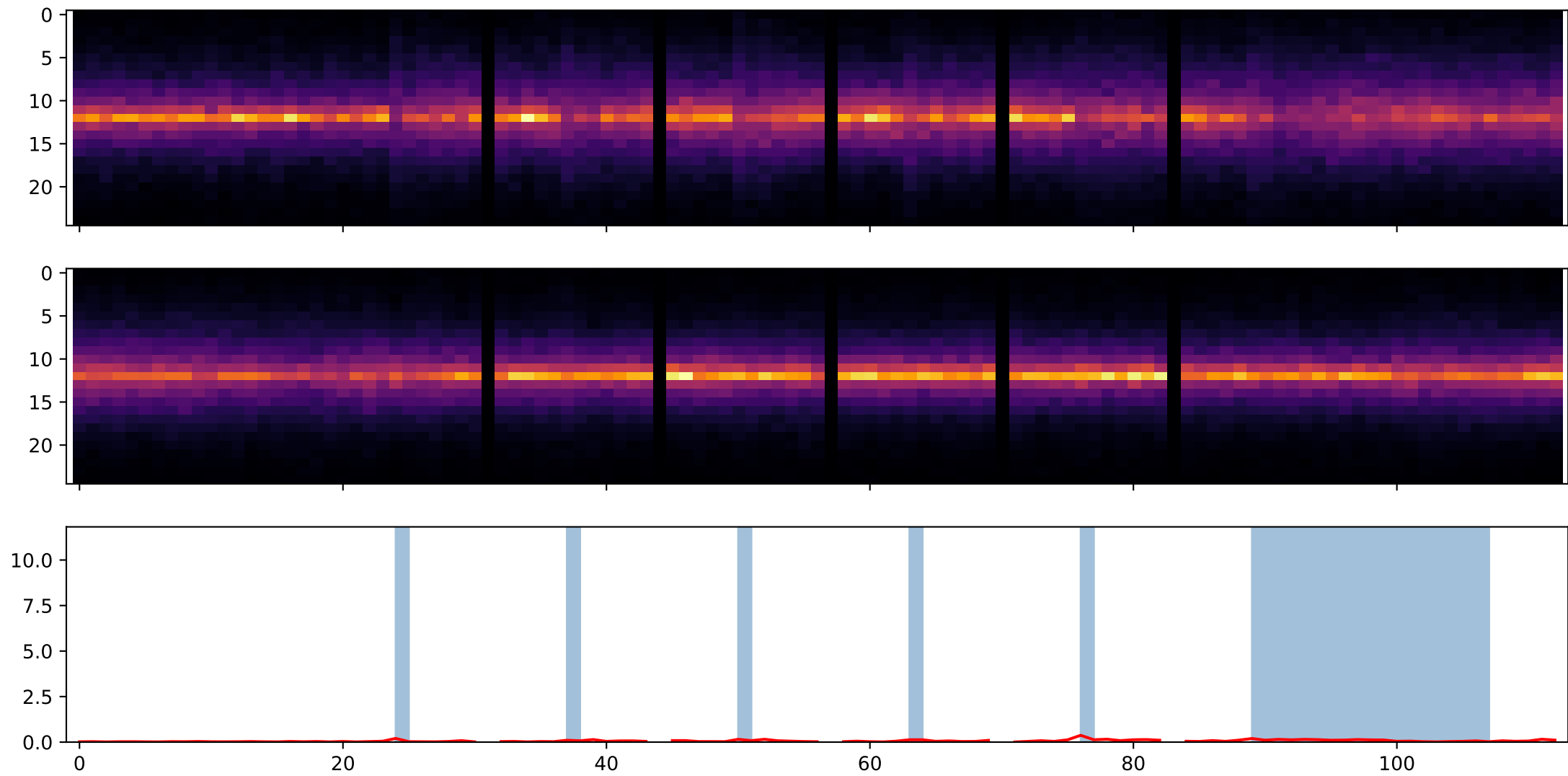
d_curvature_mean_head



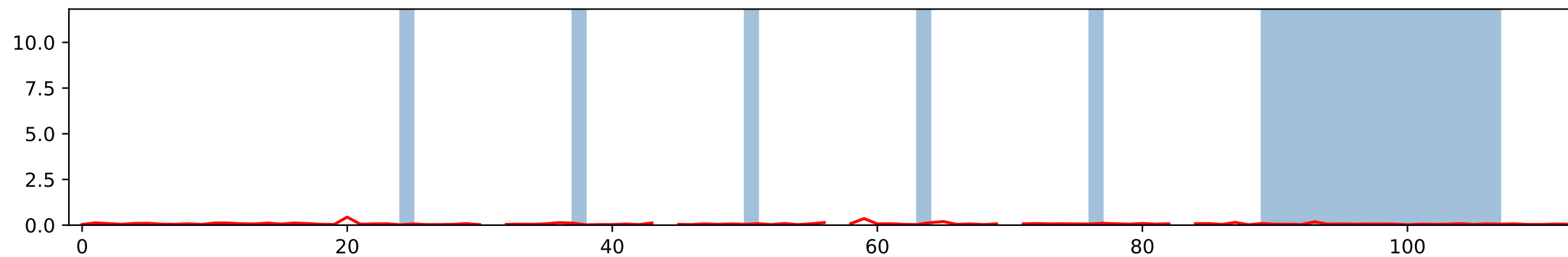
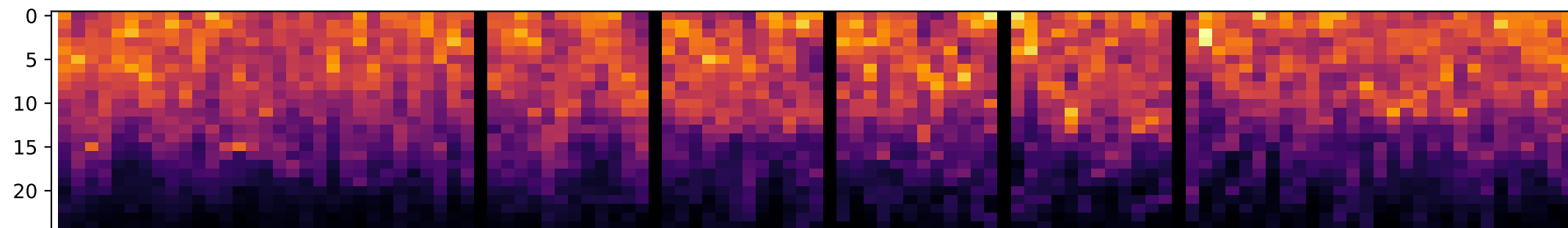
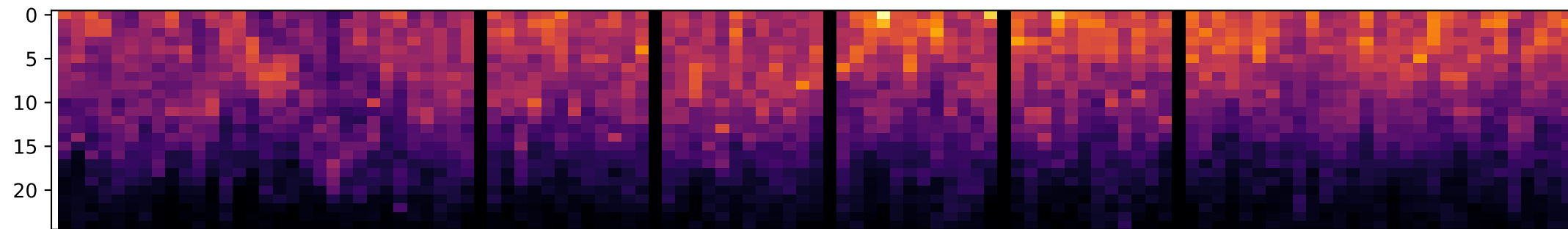
d_speed_head_tip



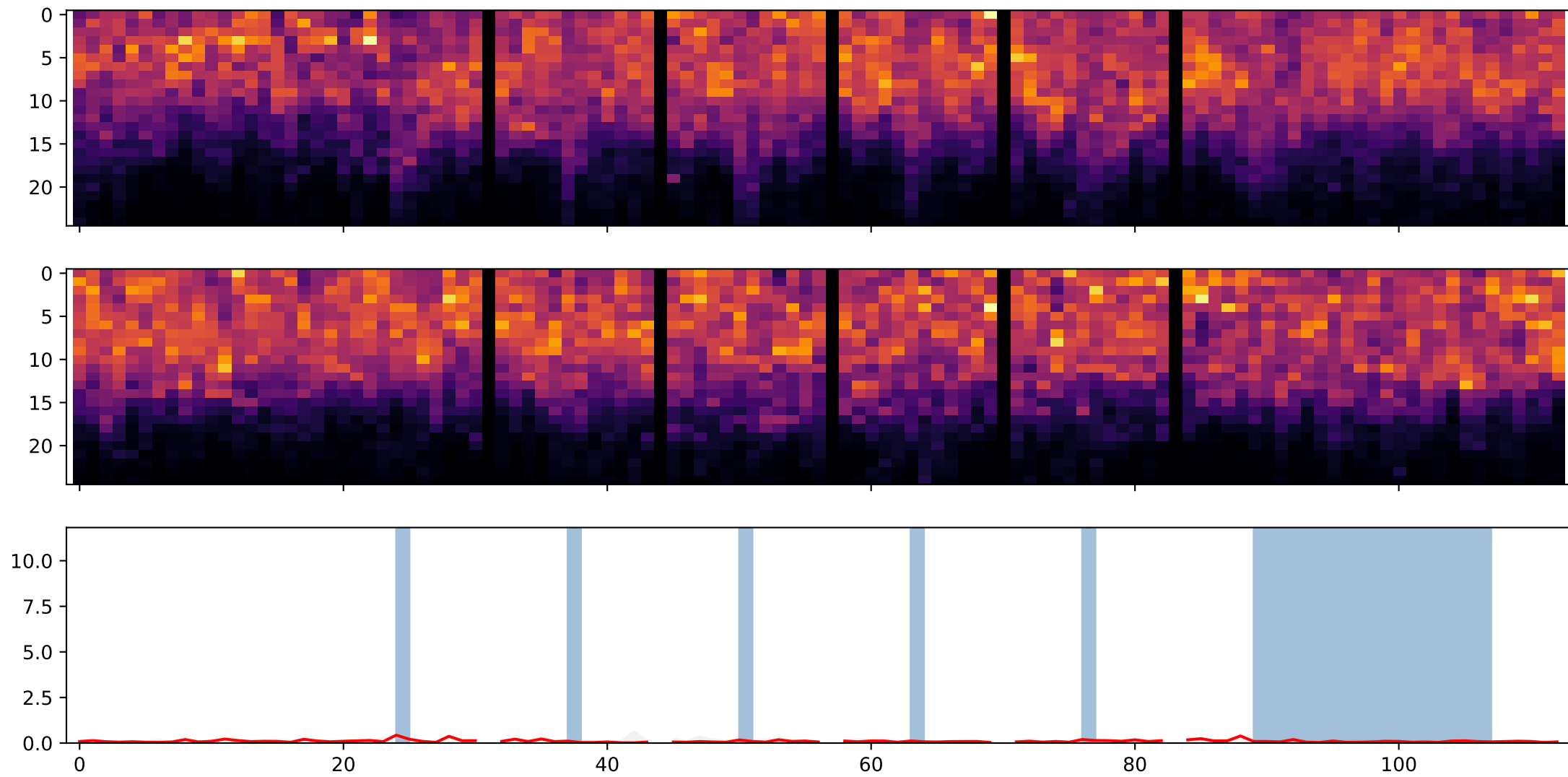
d_width_tail_base



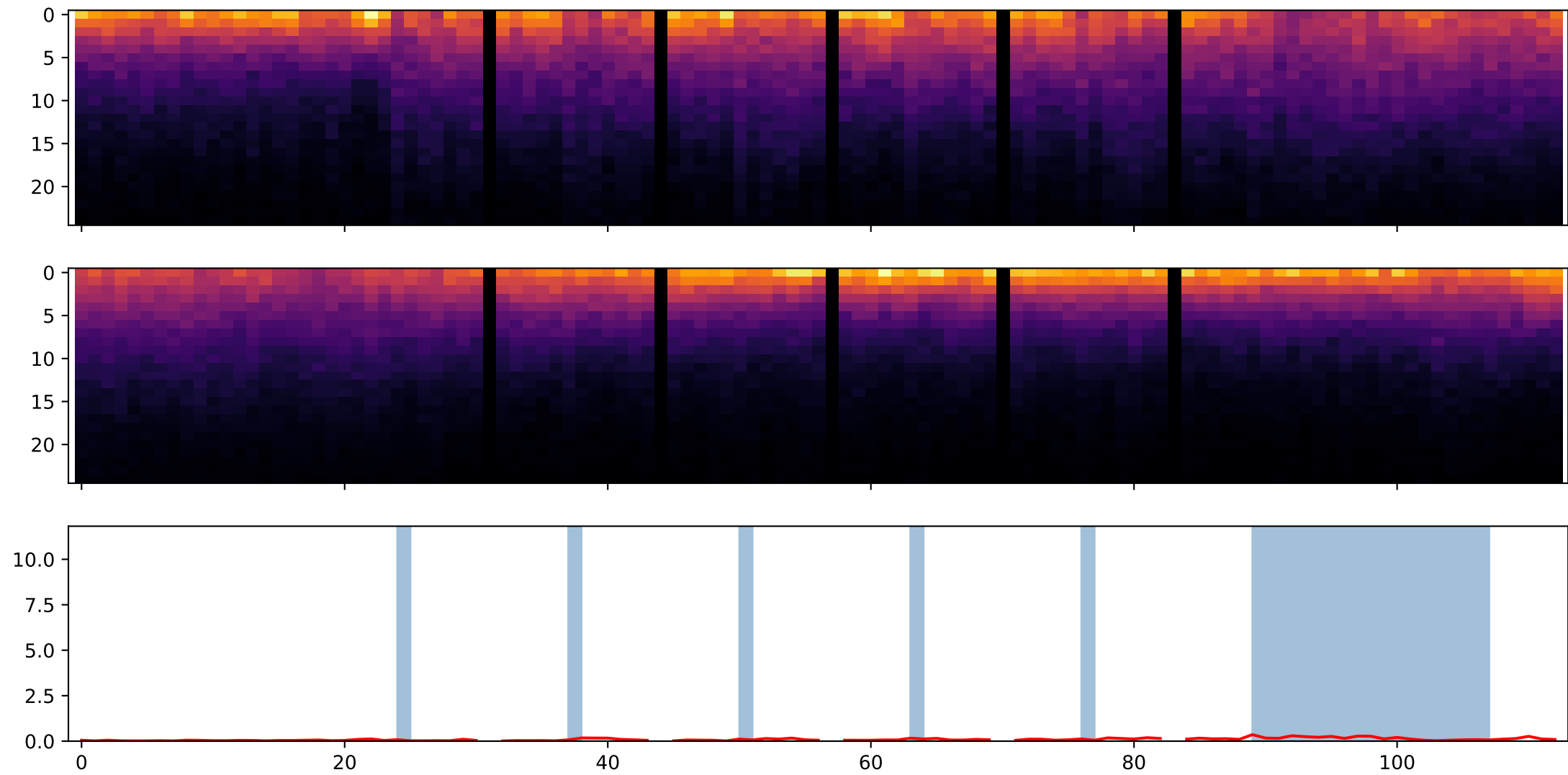
eigen_projection_4



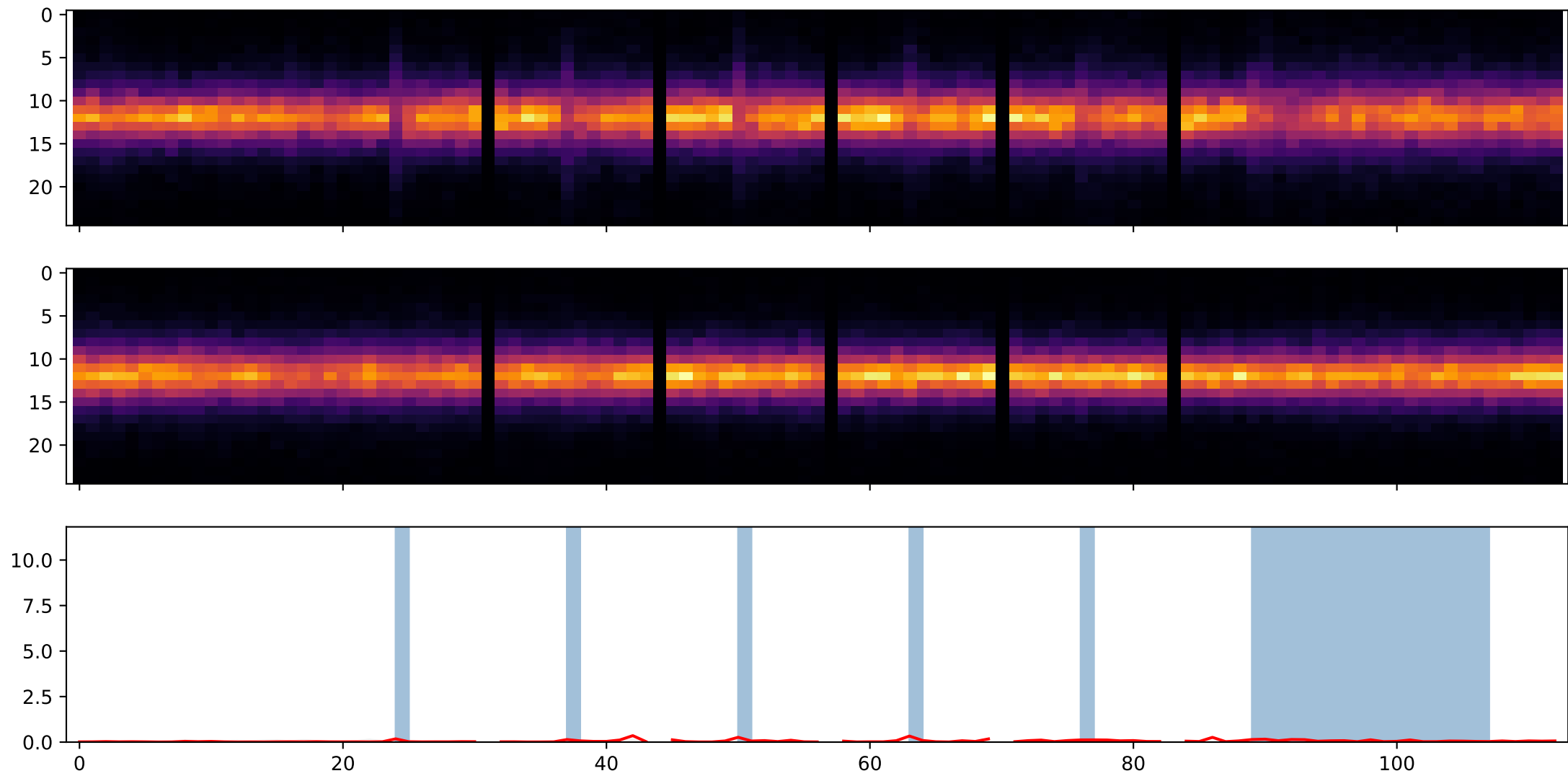
curvature_tail



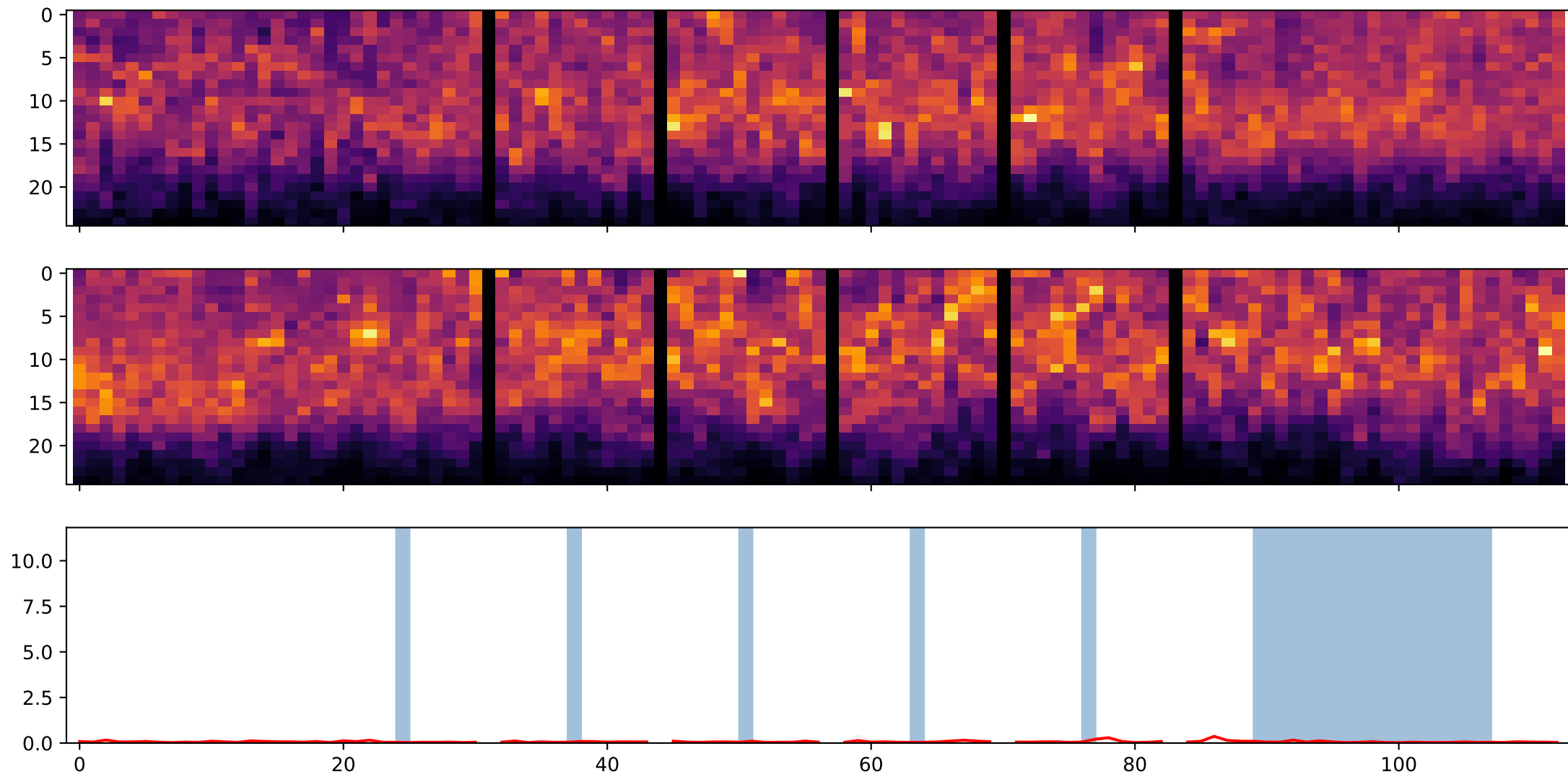
d_curvature_std_neck



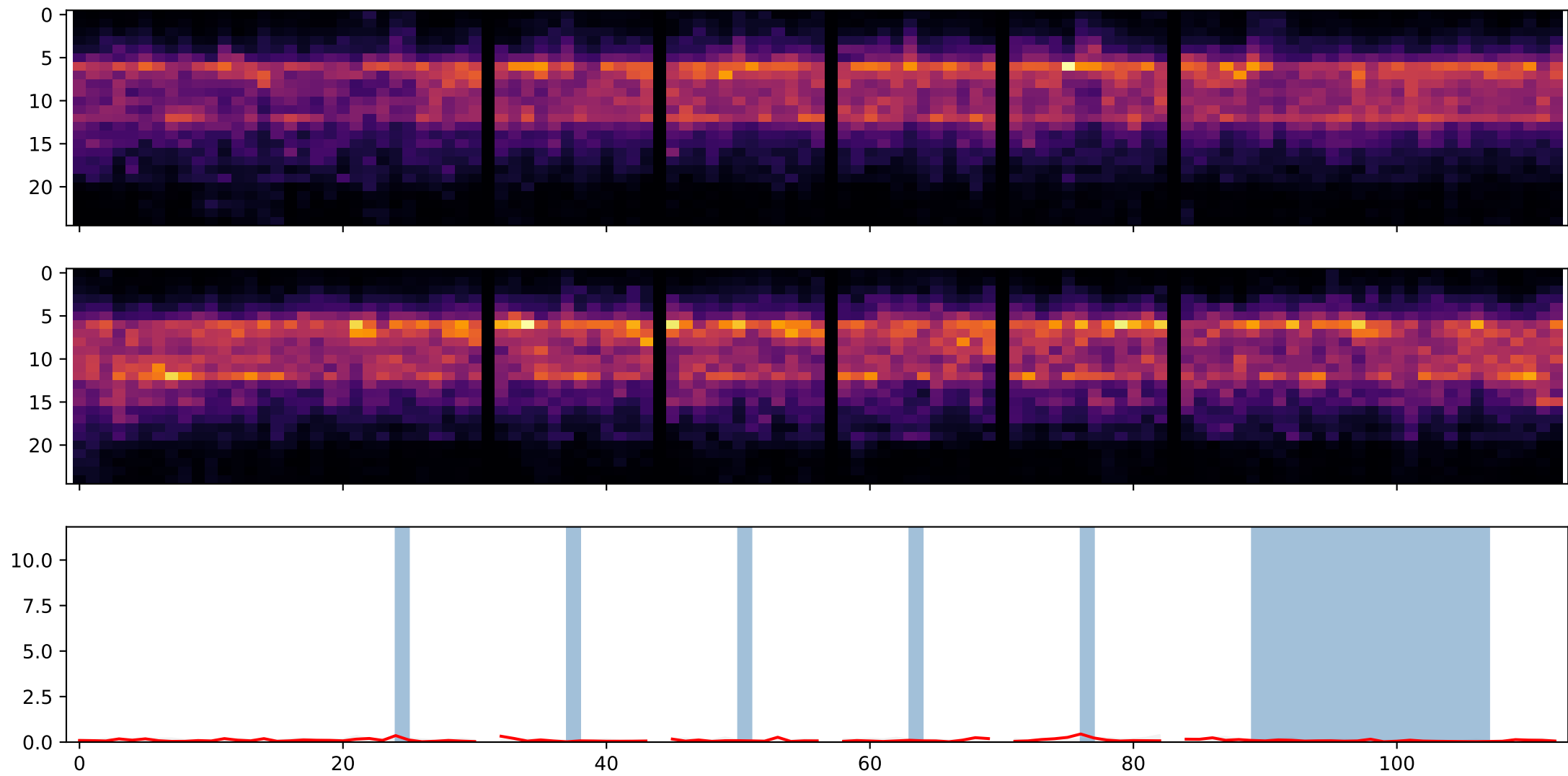
relative_to_tail_base_radial_velocity_tail_tip



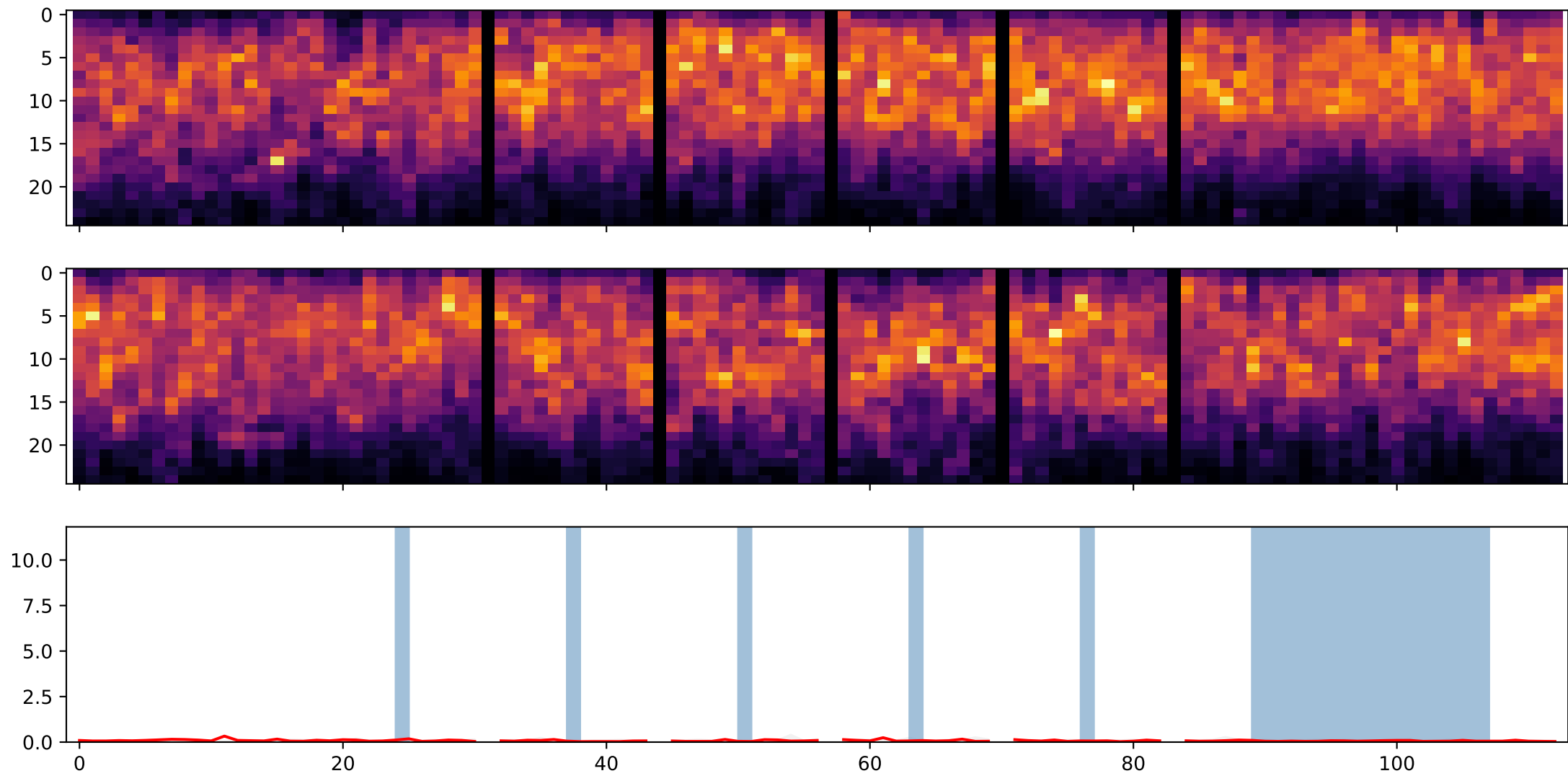
curvature_neck



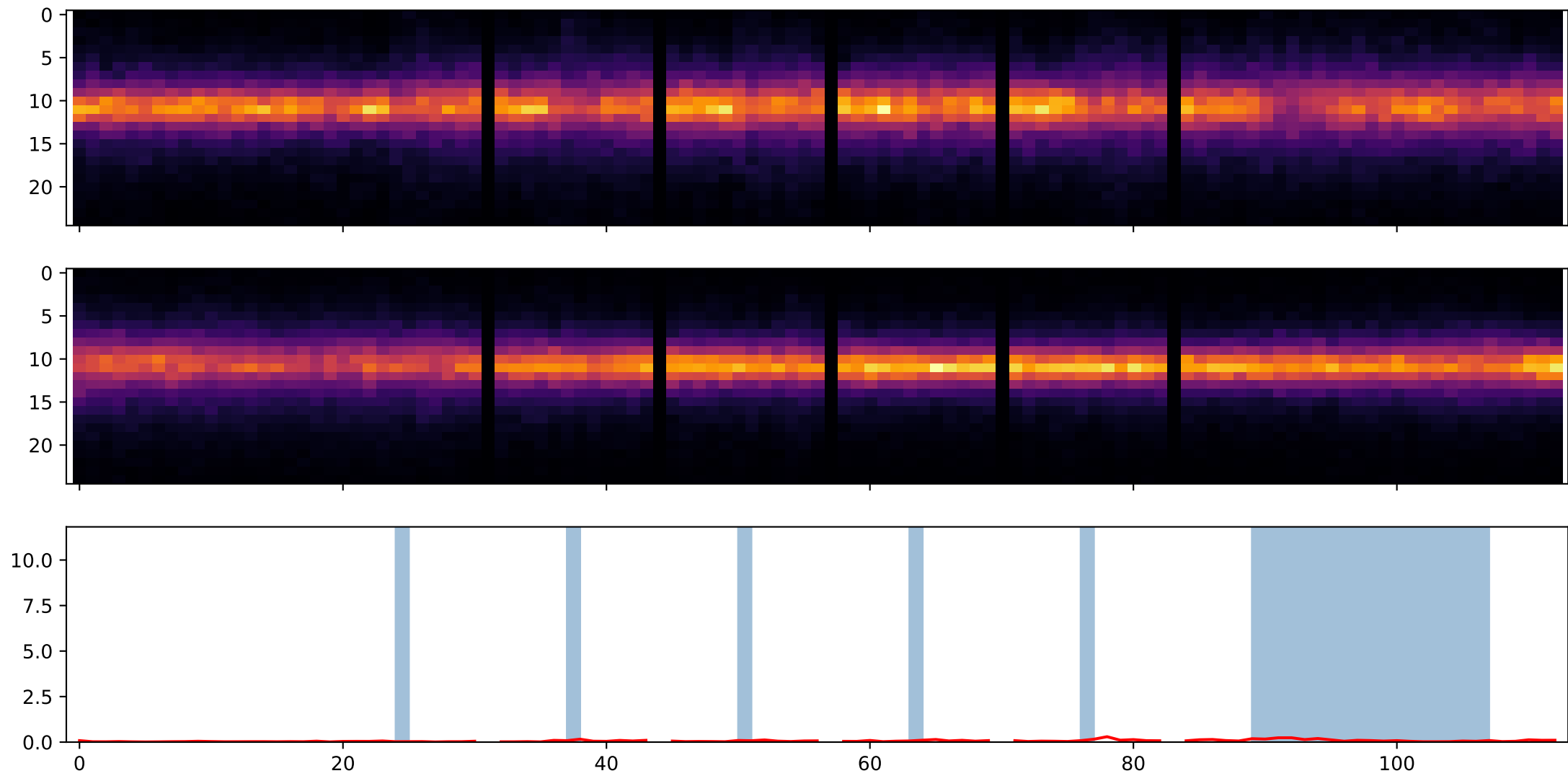
width_tail_base



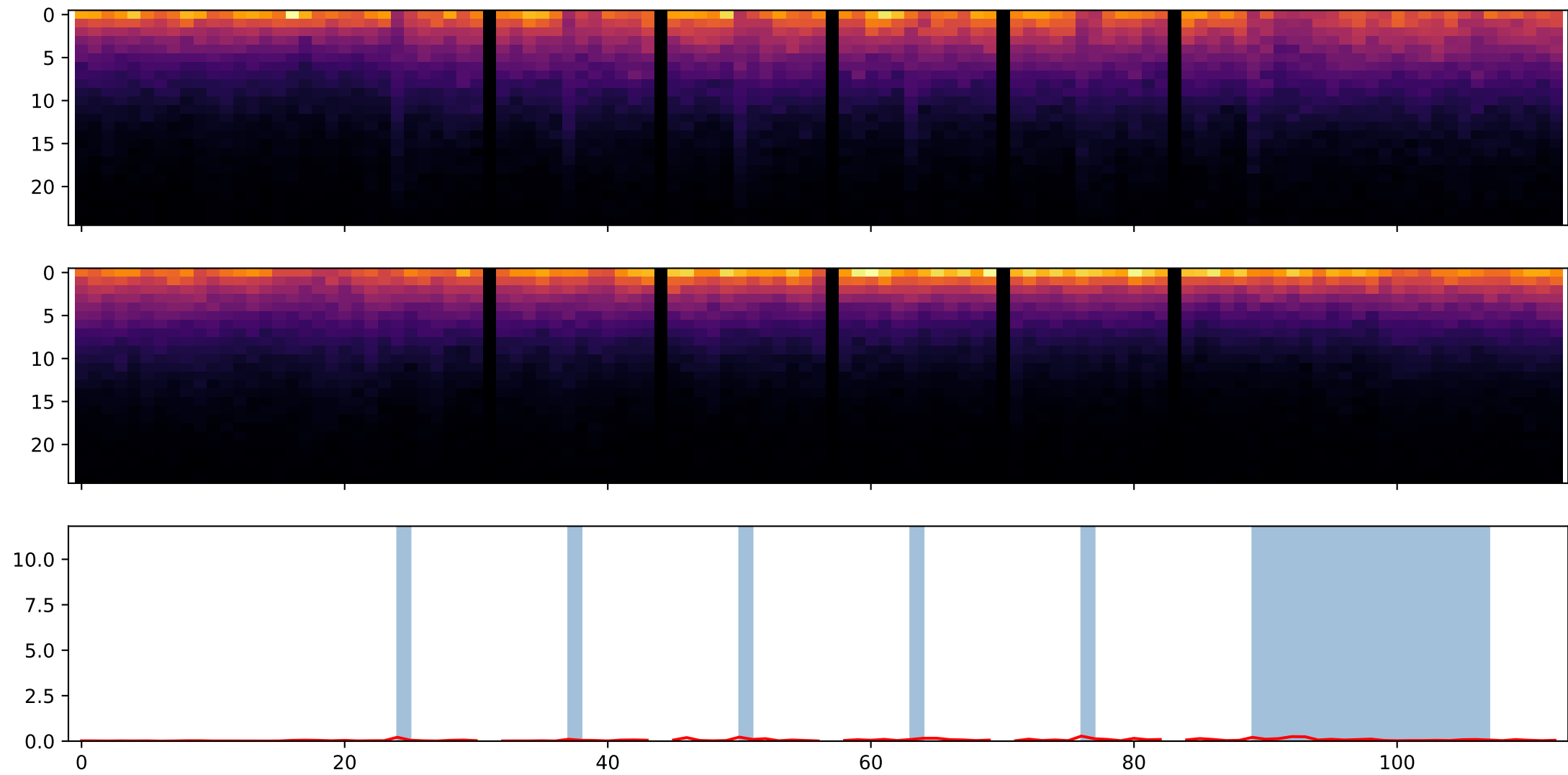
curvature_std_hips



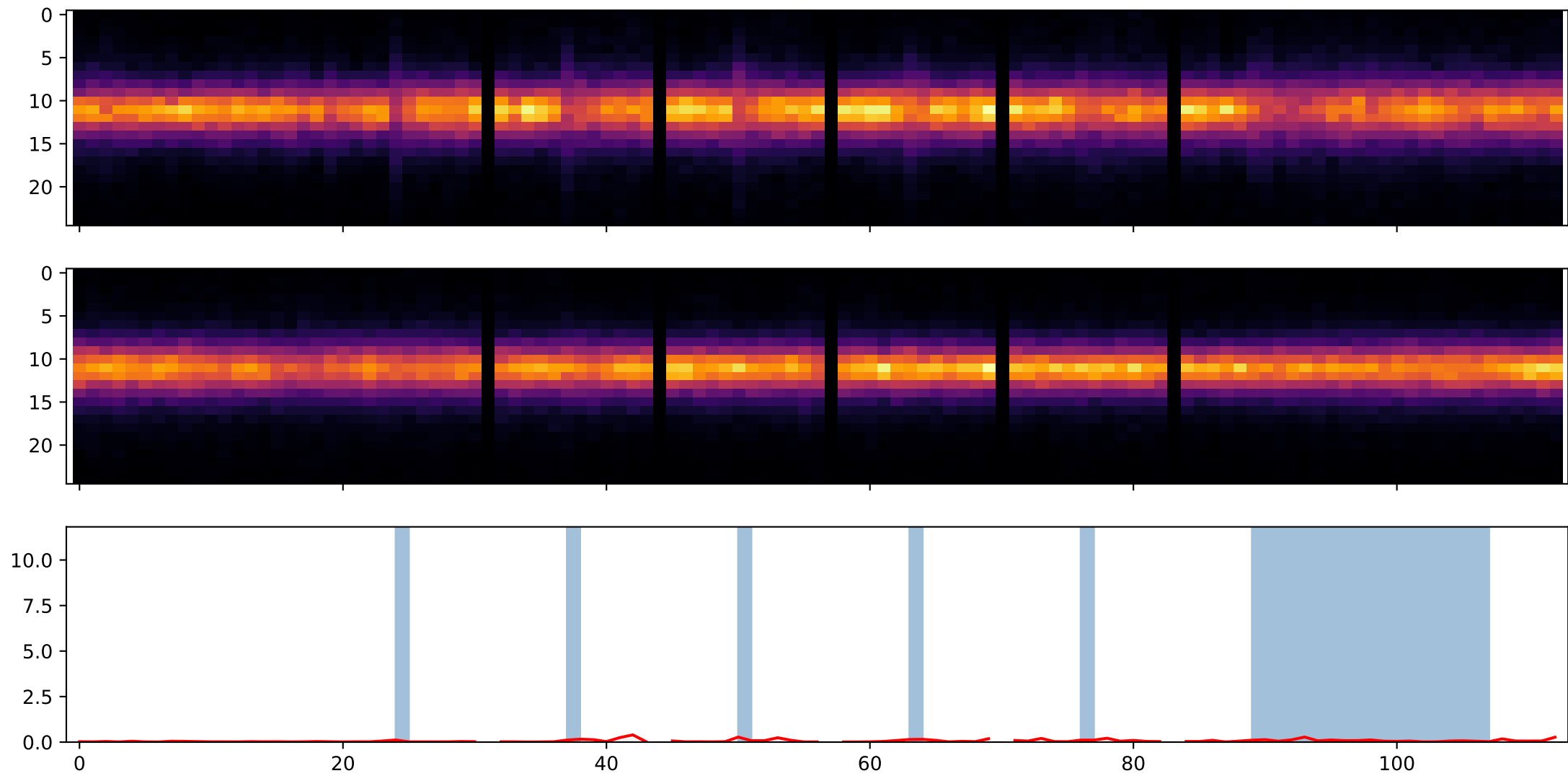
d_relative_to_body_radial_velocity_head_tip



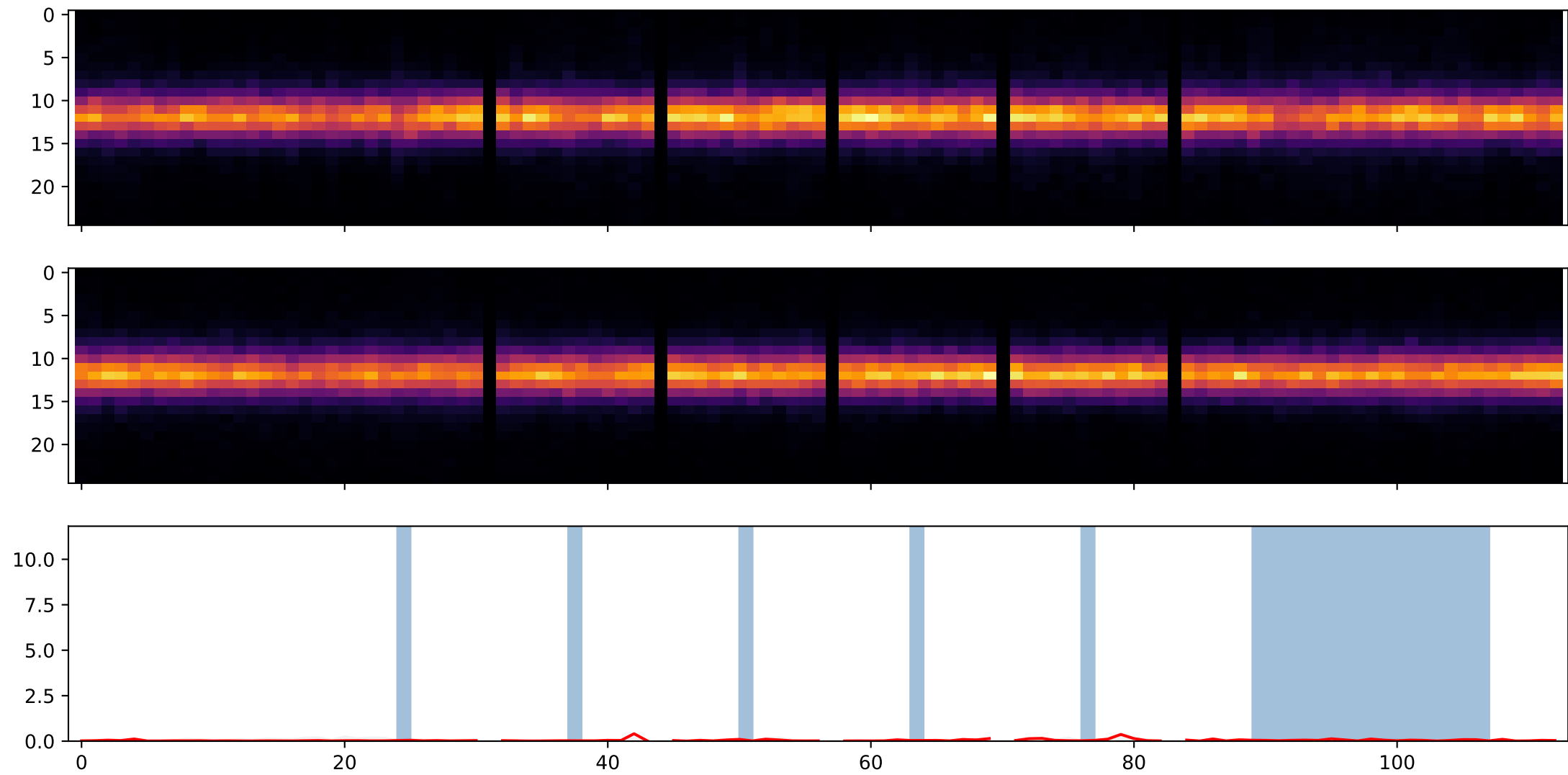
d_curvature_std_tail



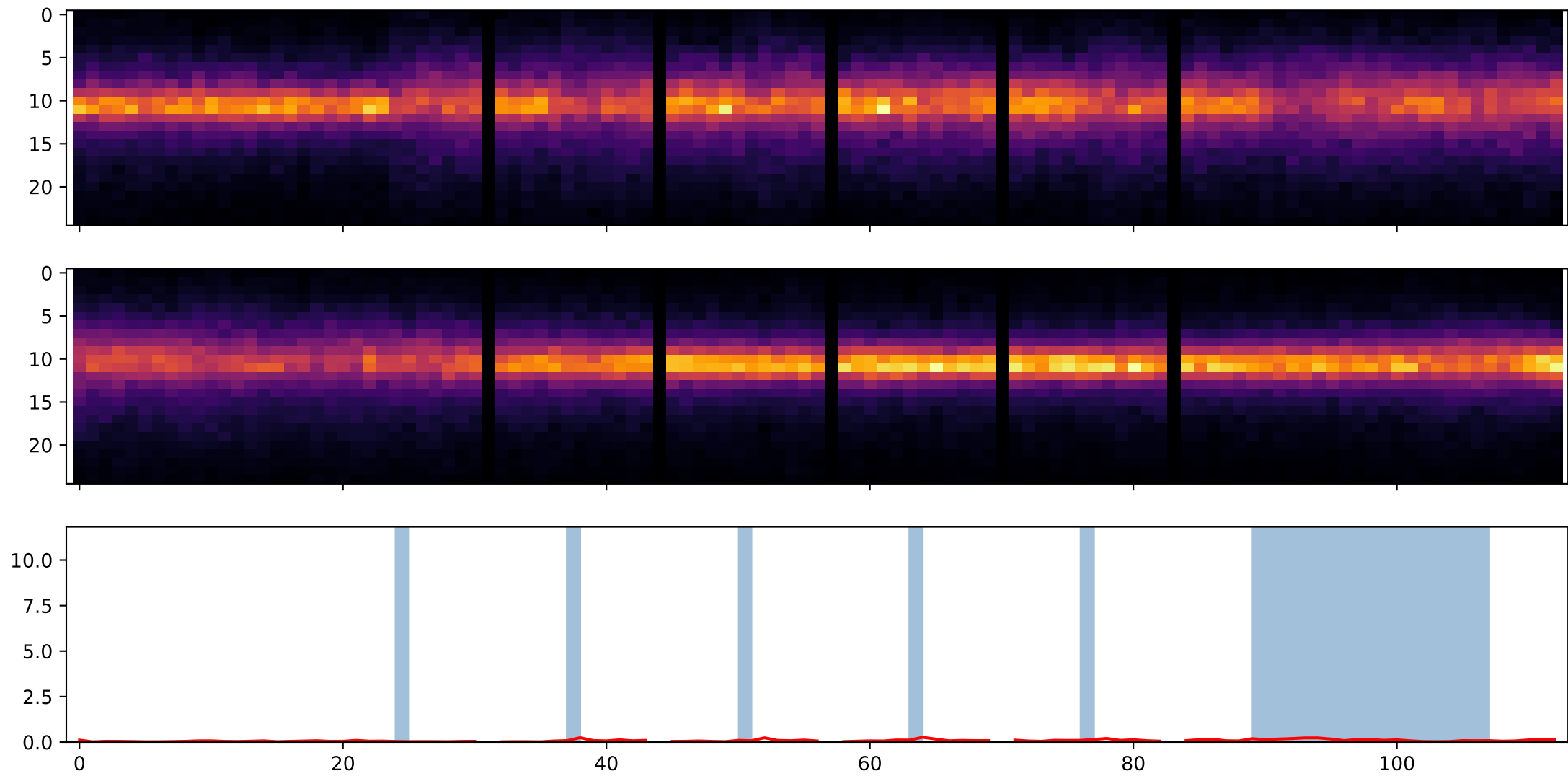
d_relative_to_tail_base_radial_velocity_tail_tip



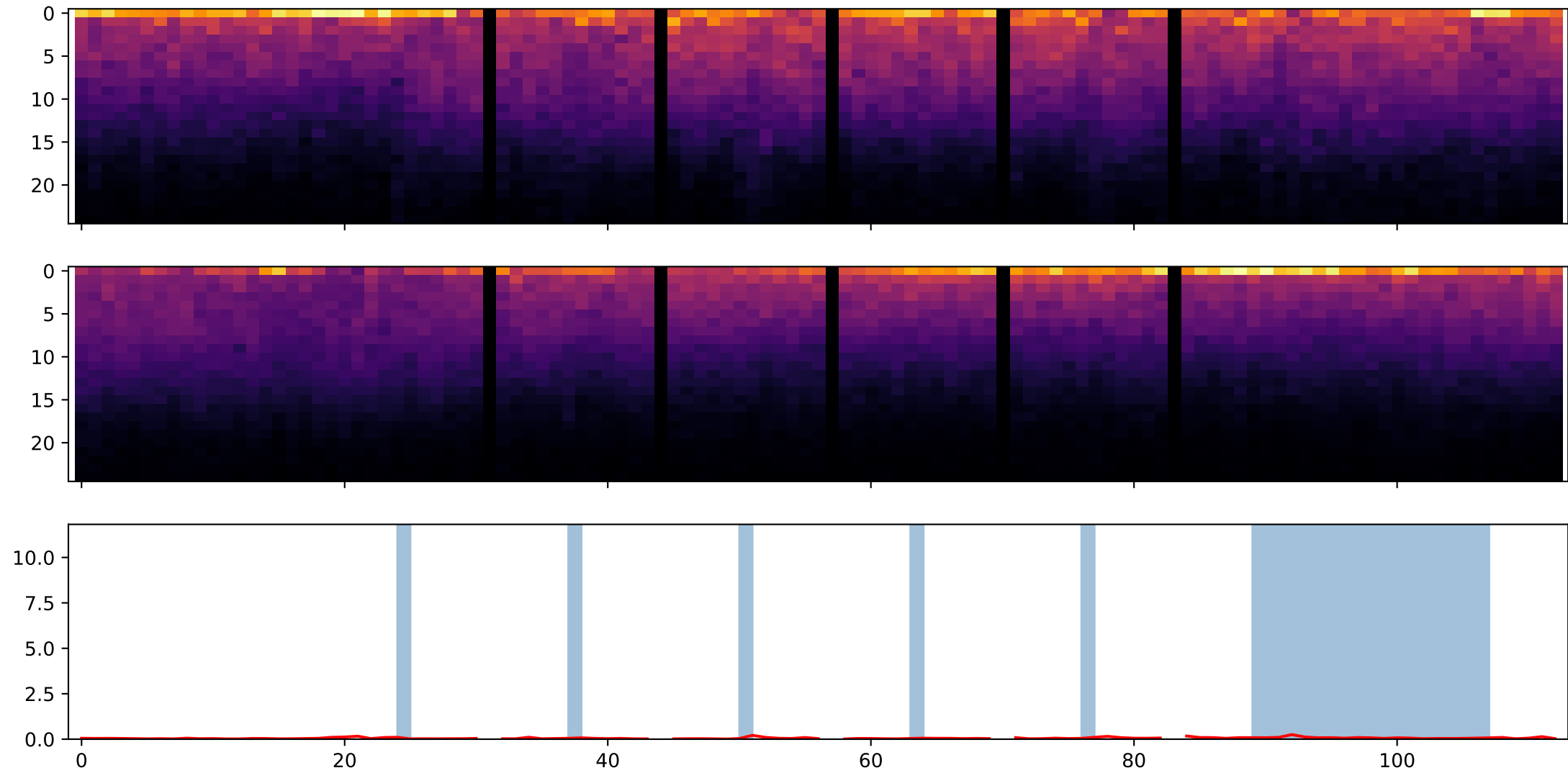
d_length



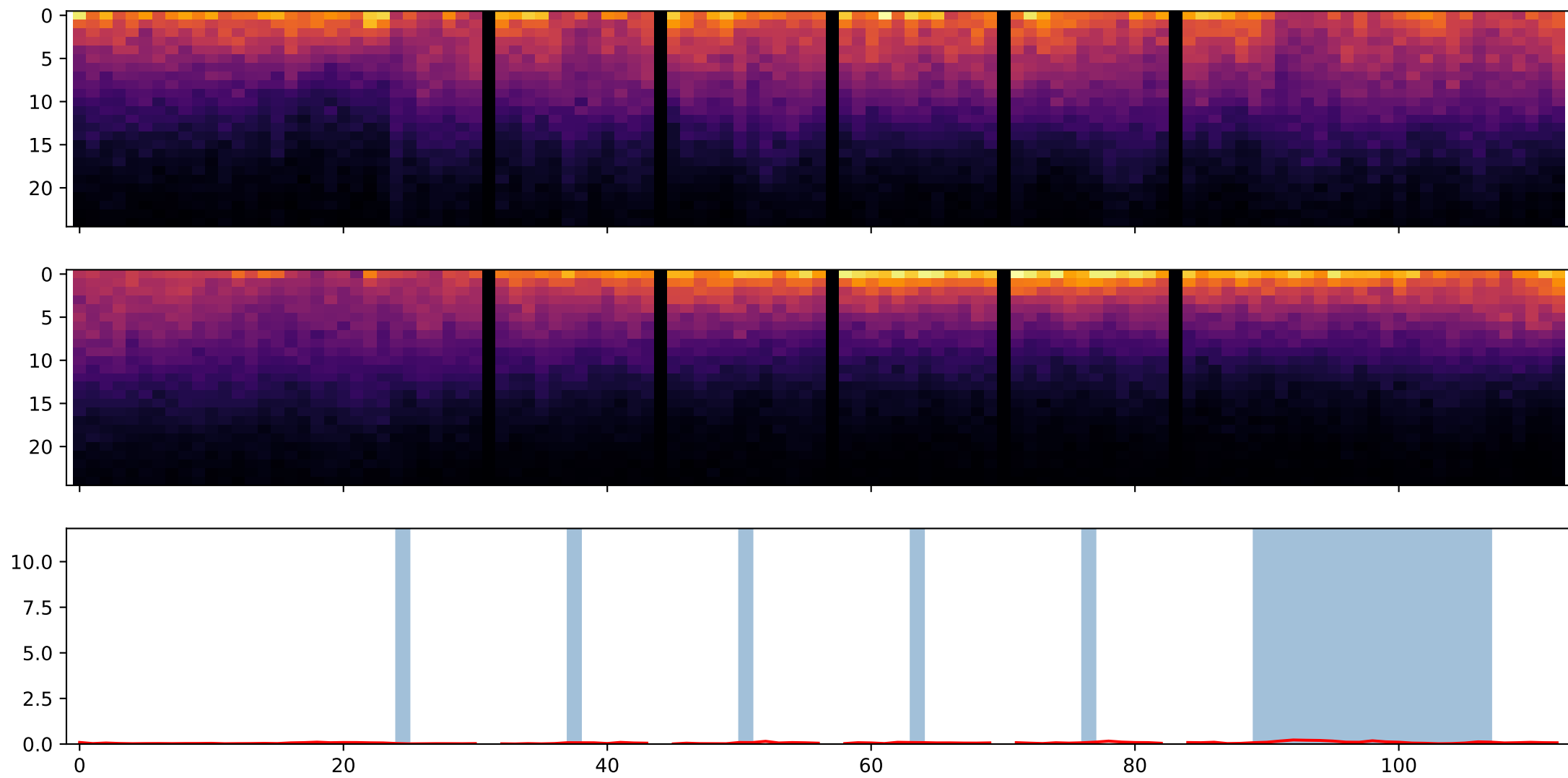
d_relative_to_neck_radial_velocity_head_tip



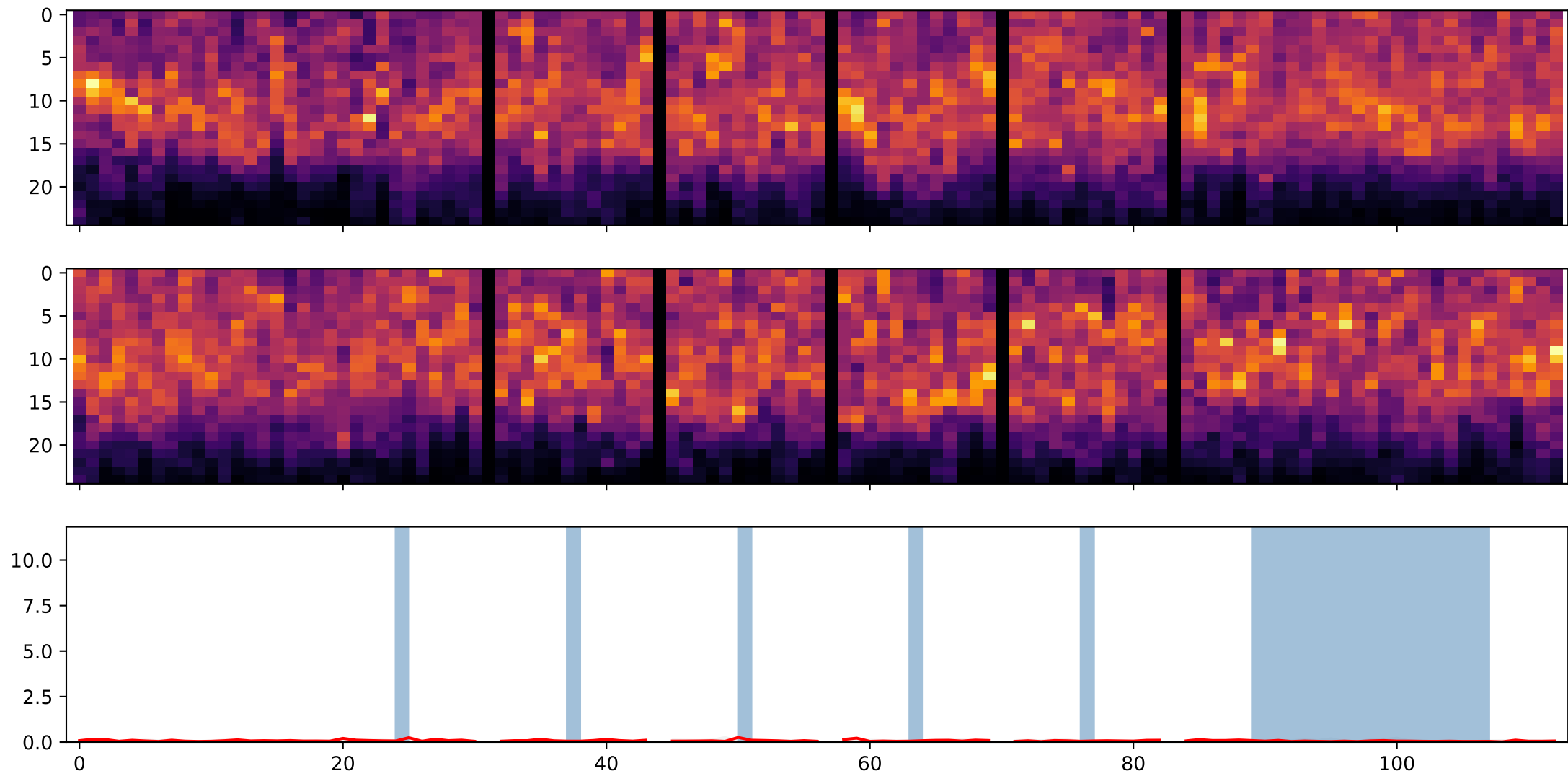
angular_velocity_head_tip



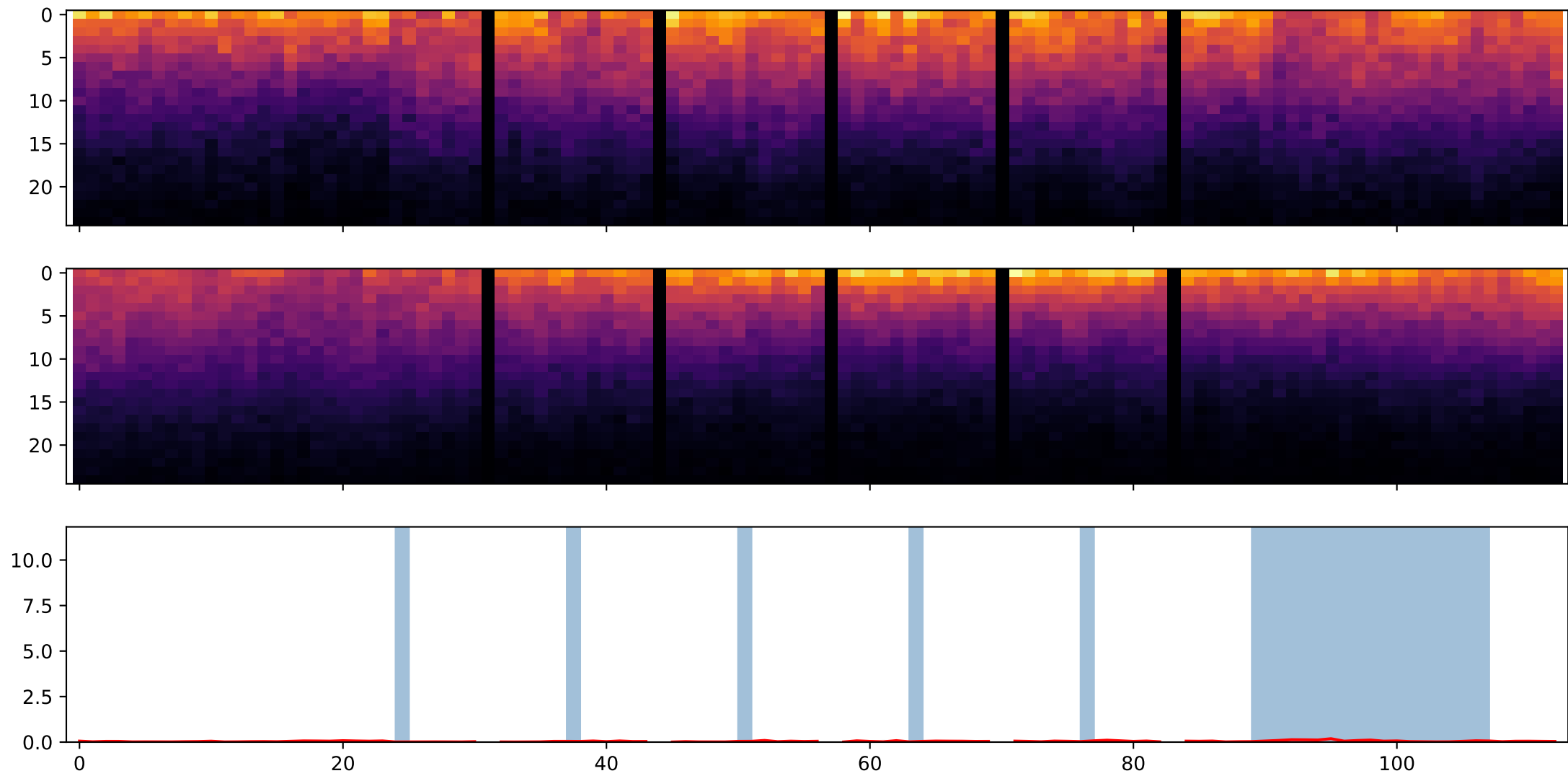
d_curvature_head



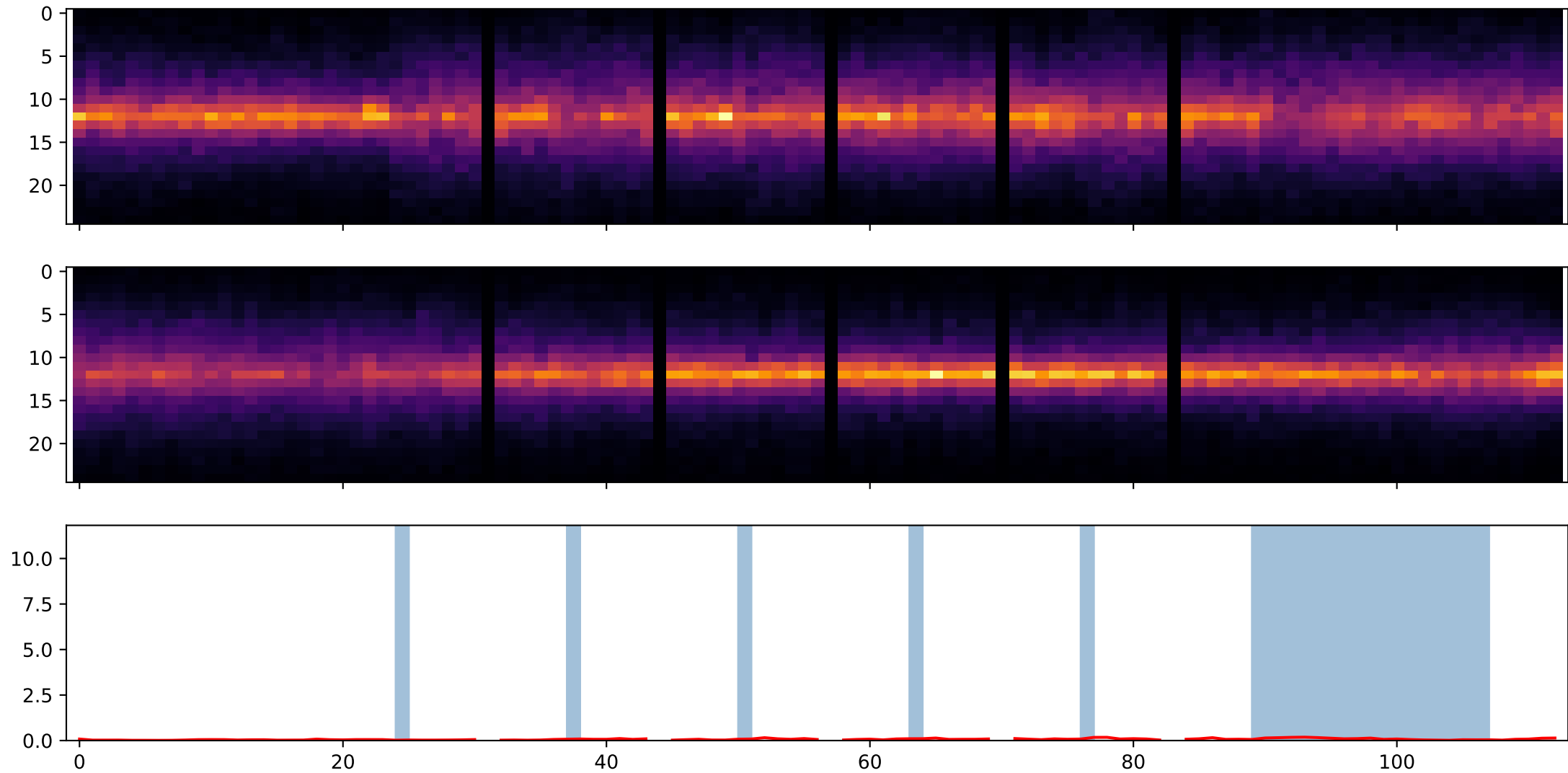
curvature_midbody



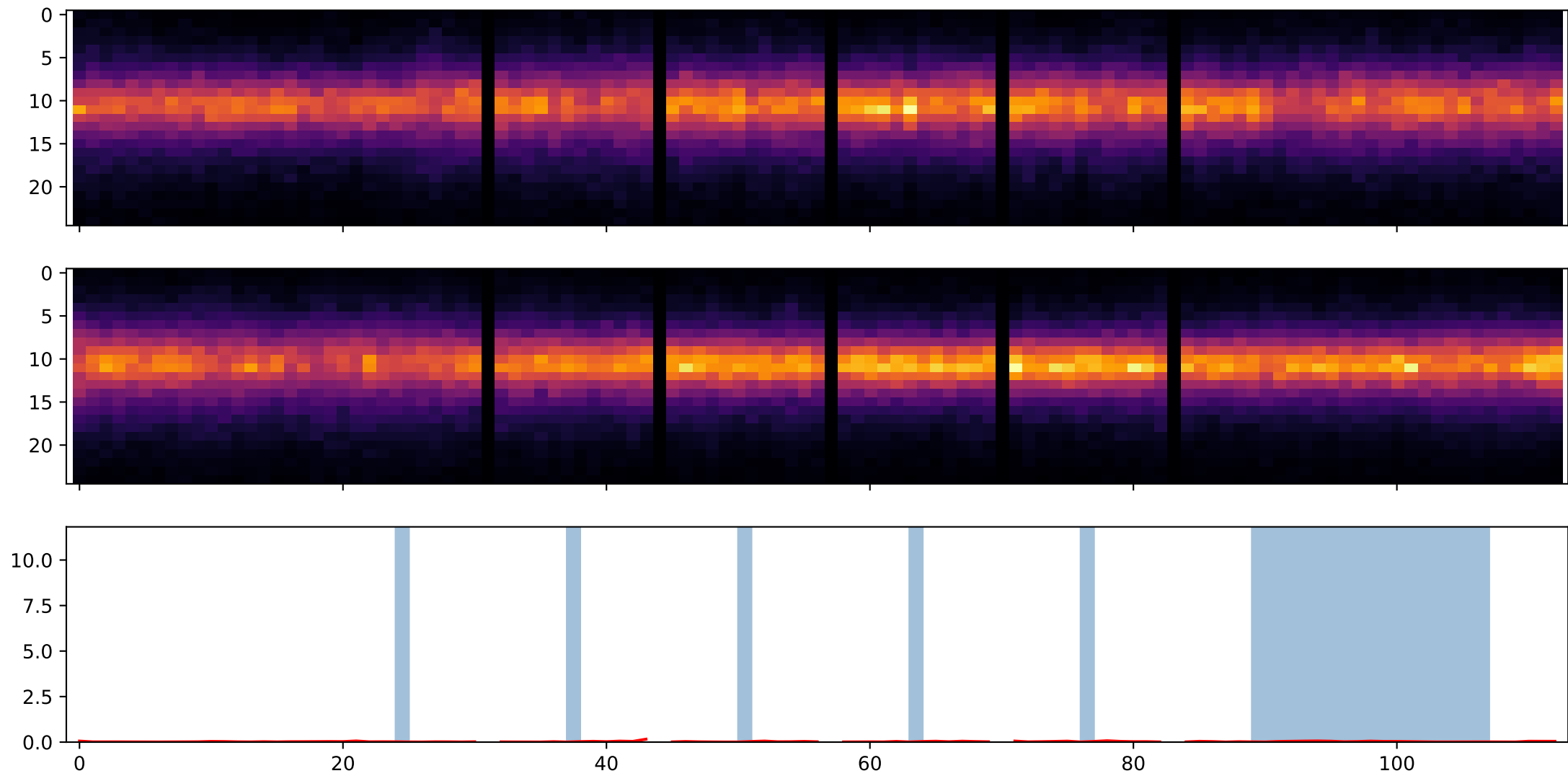
relative_to_head_base_angular_velocity_head_tip



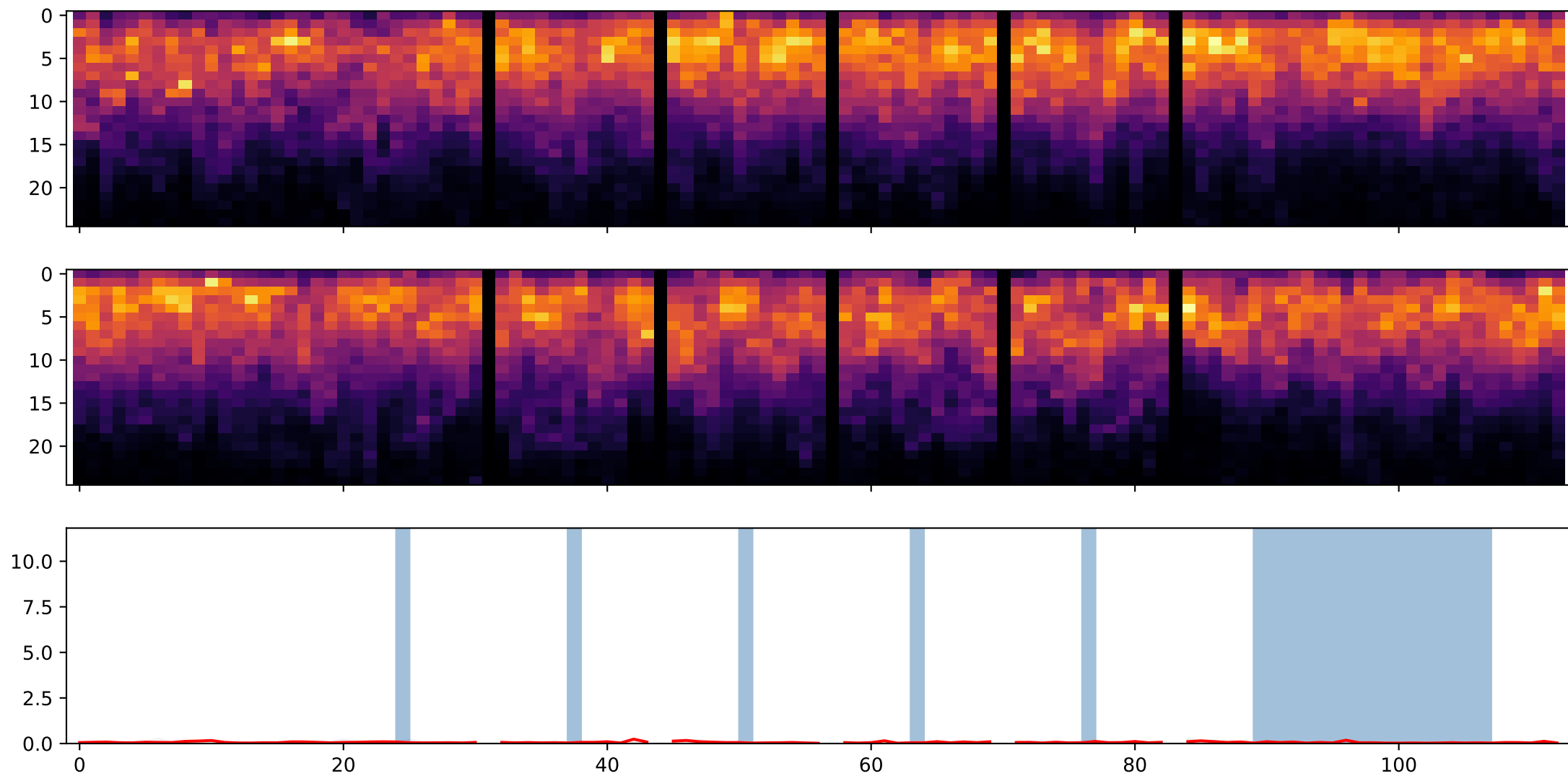
relative_to_neck_radial_velocity_head_tip



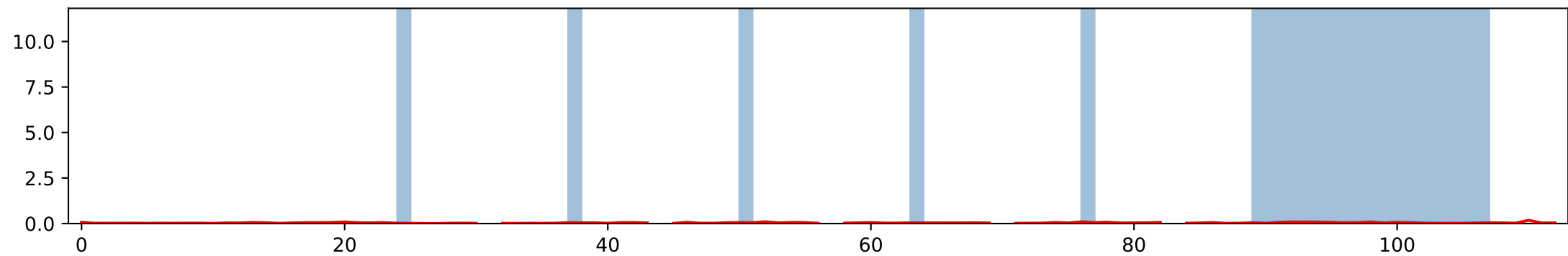
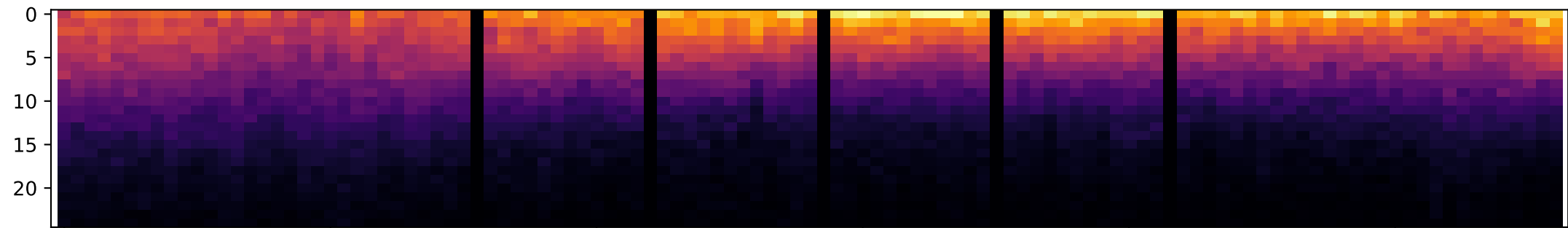
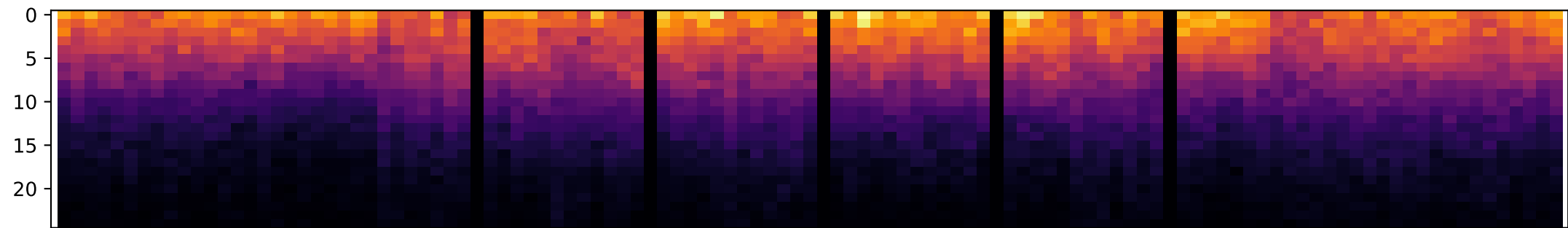
d_relative_to_head_base_radial_velocity_head_tip



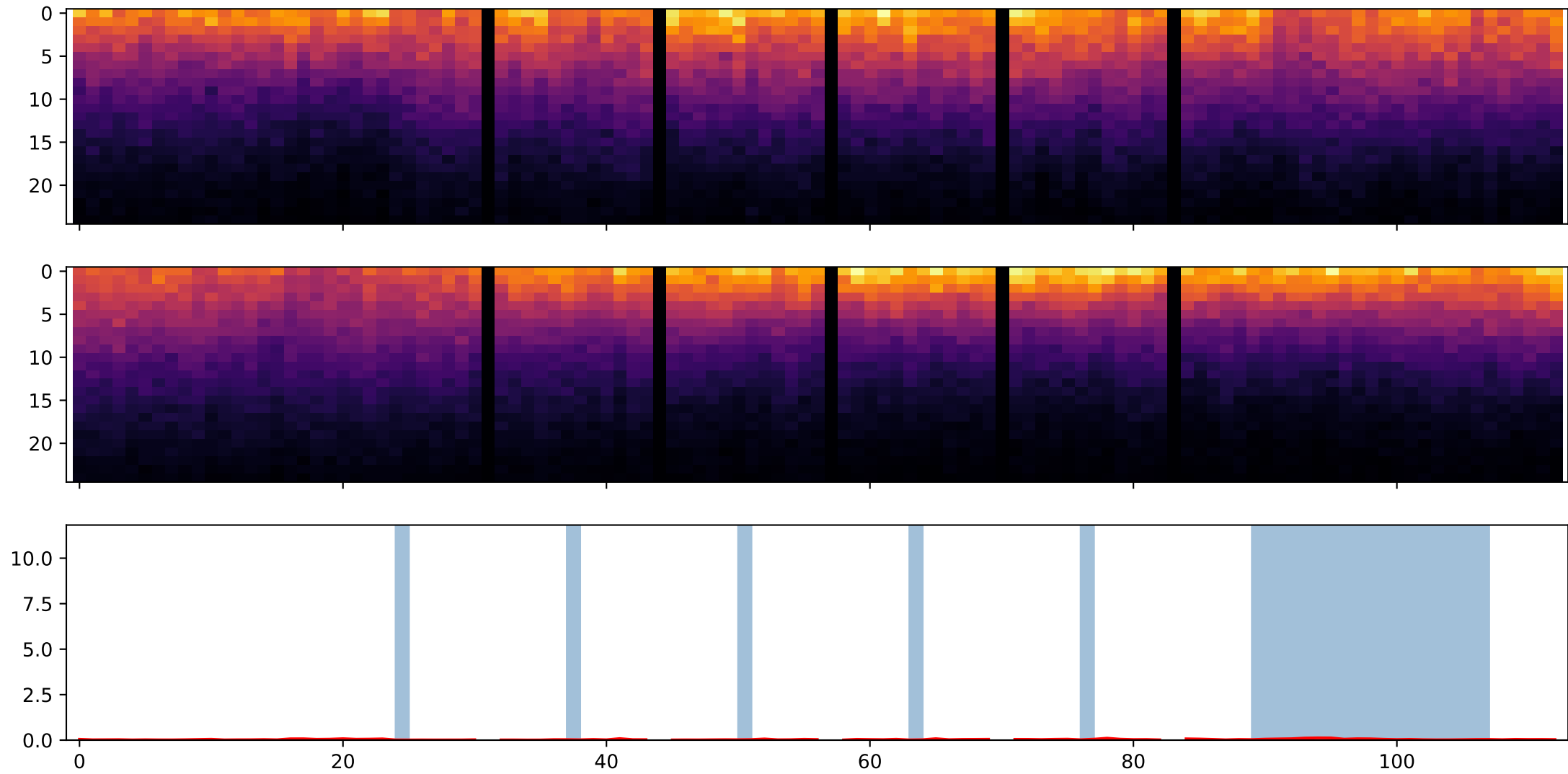
curvature_std_tail



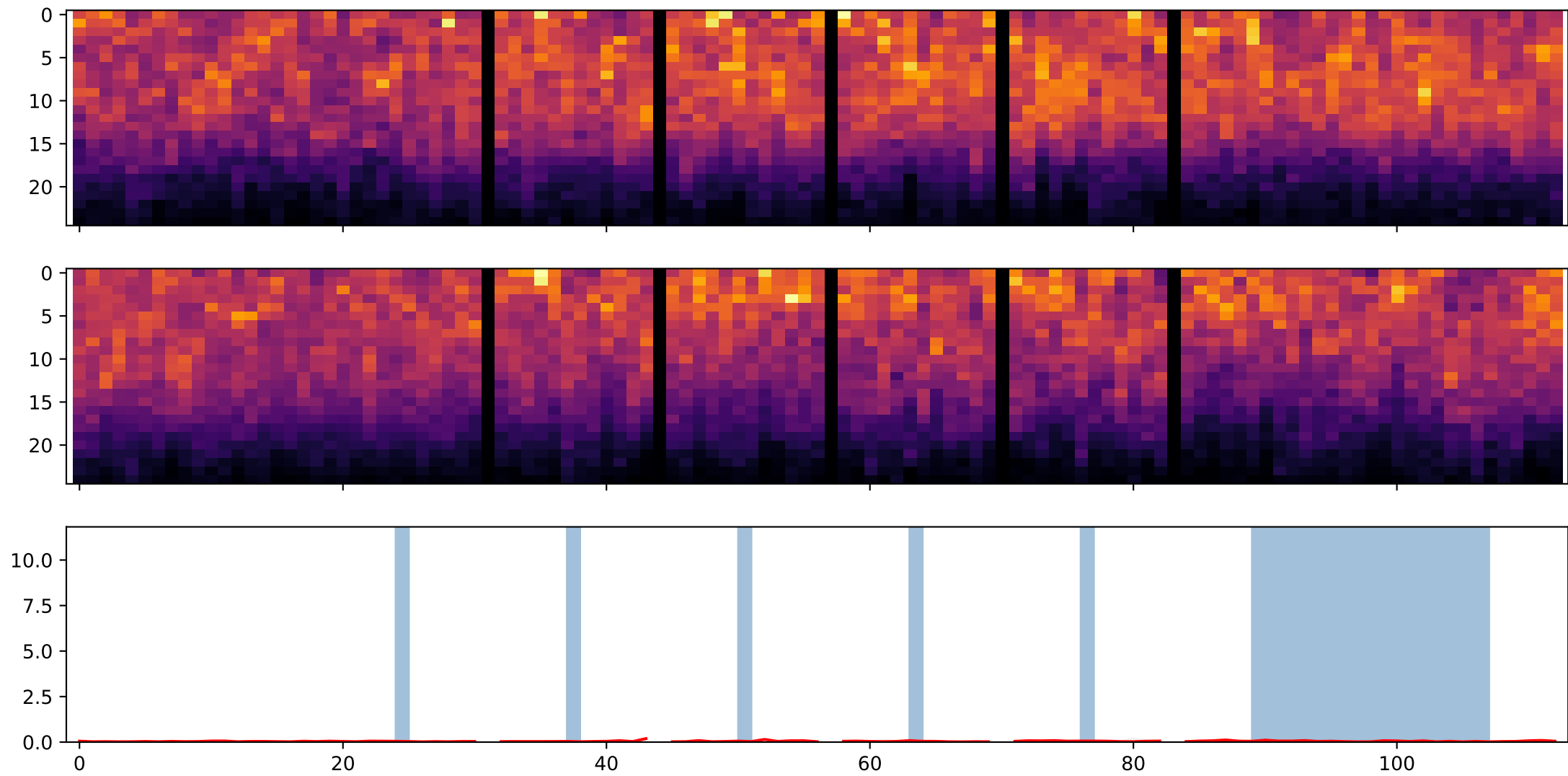
d_eigen_projection_5



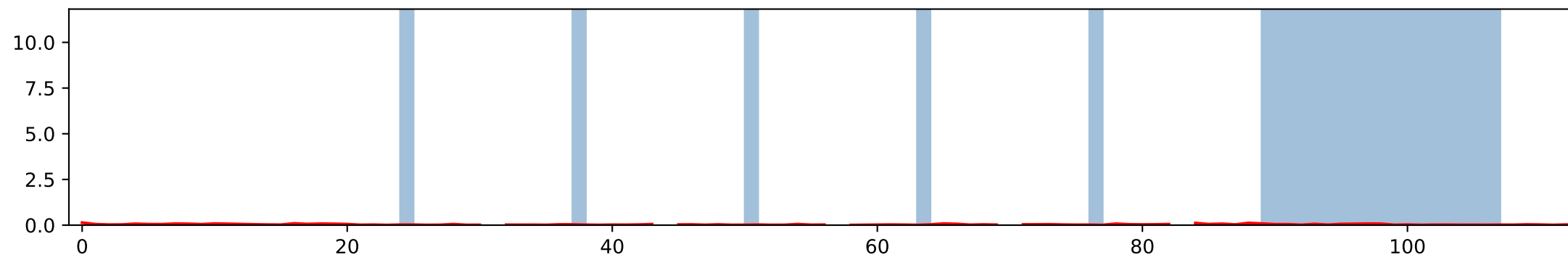
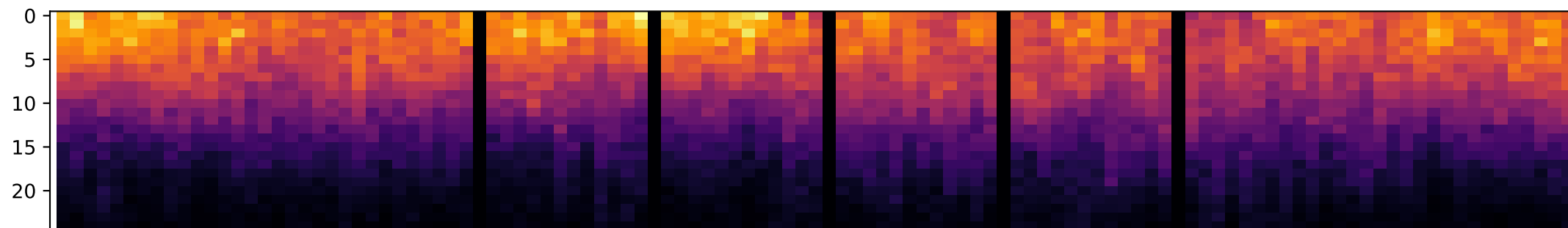
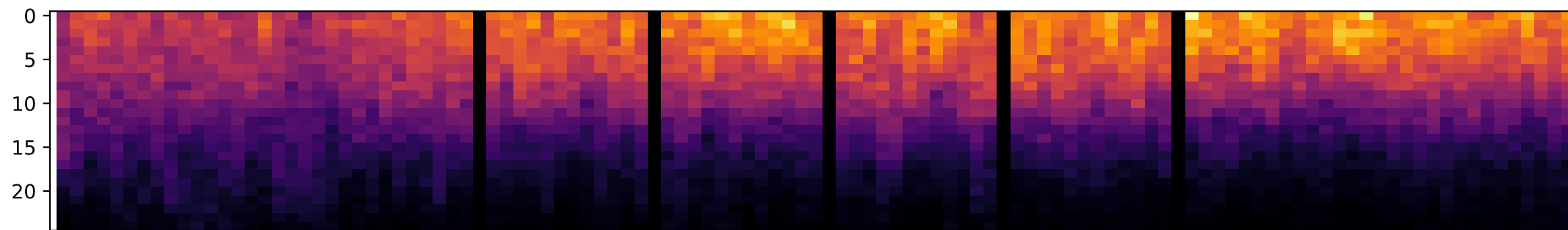
d_relative_to_head_base_angular_velocity_head_tip



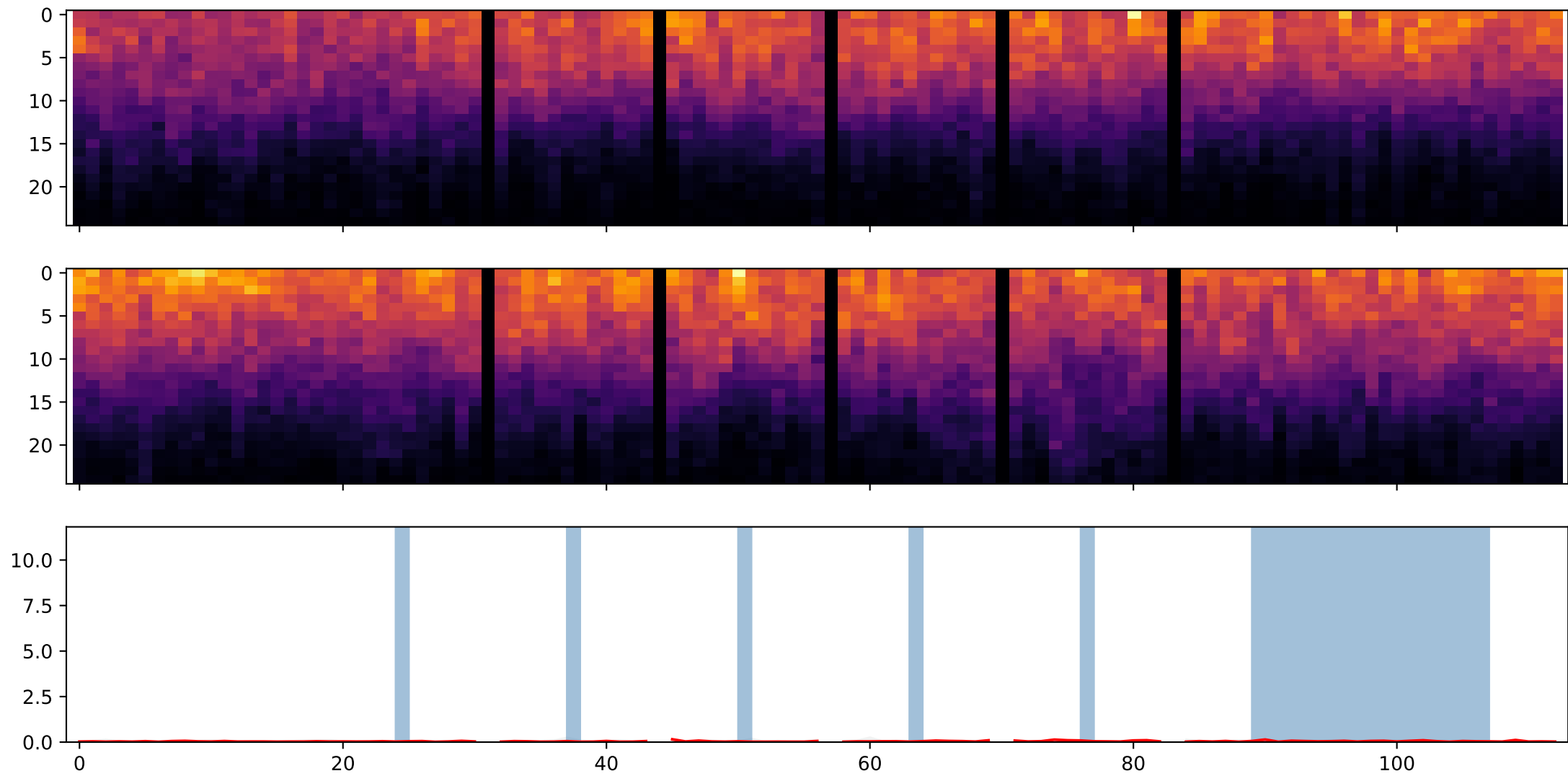
curvature_mean_head



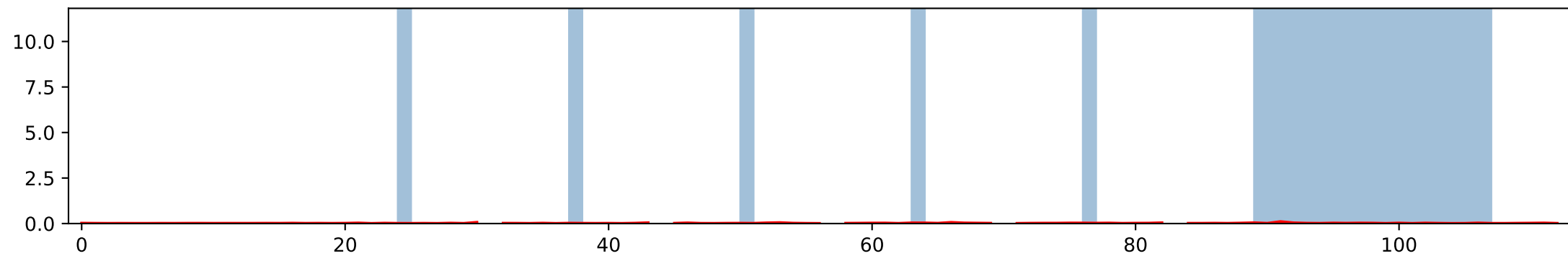
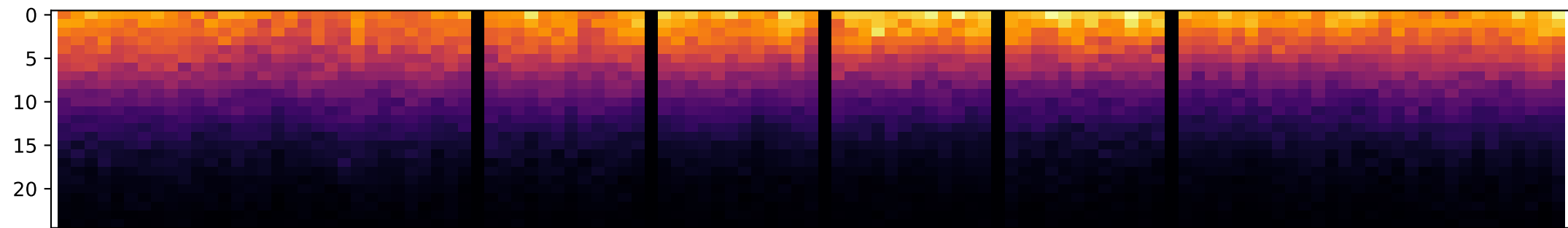
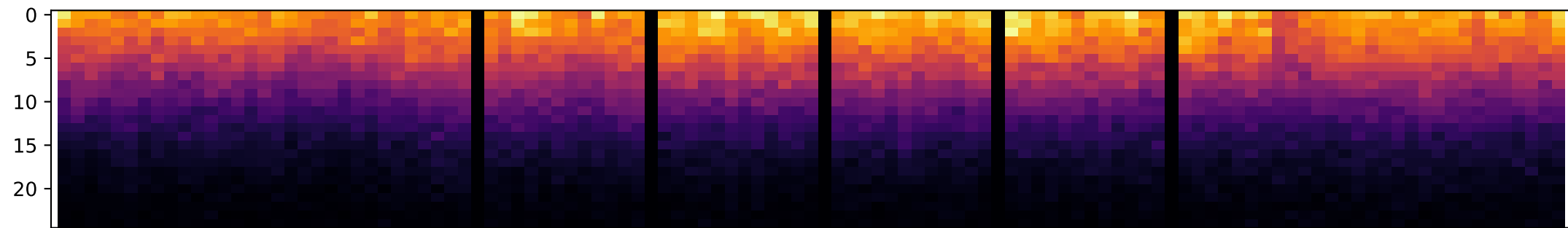
eigen_projection_7



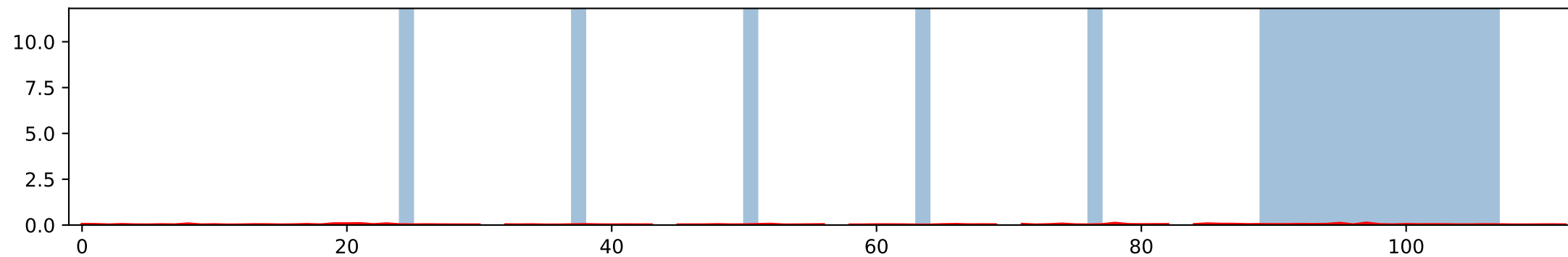
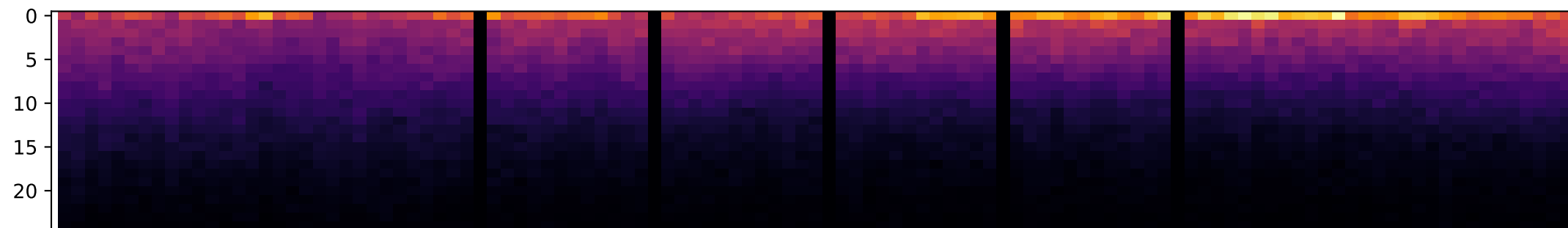
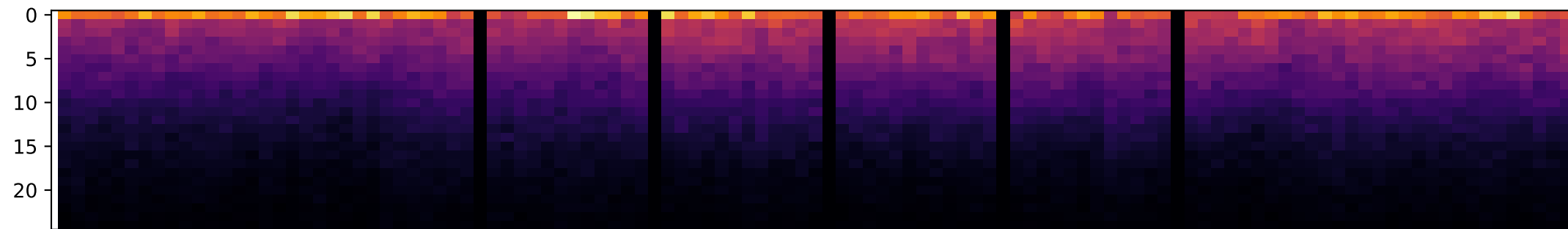
eigen_projection_6



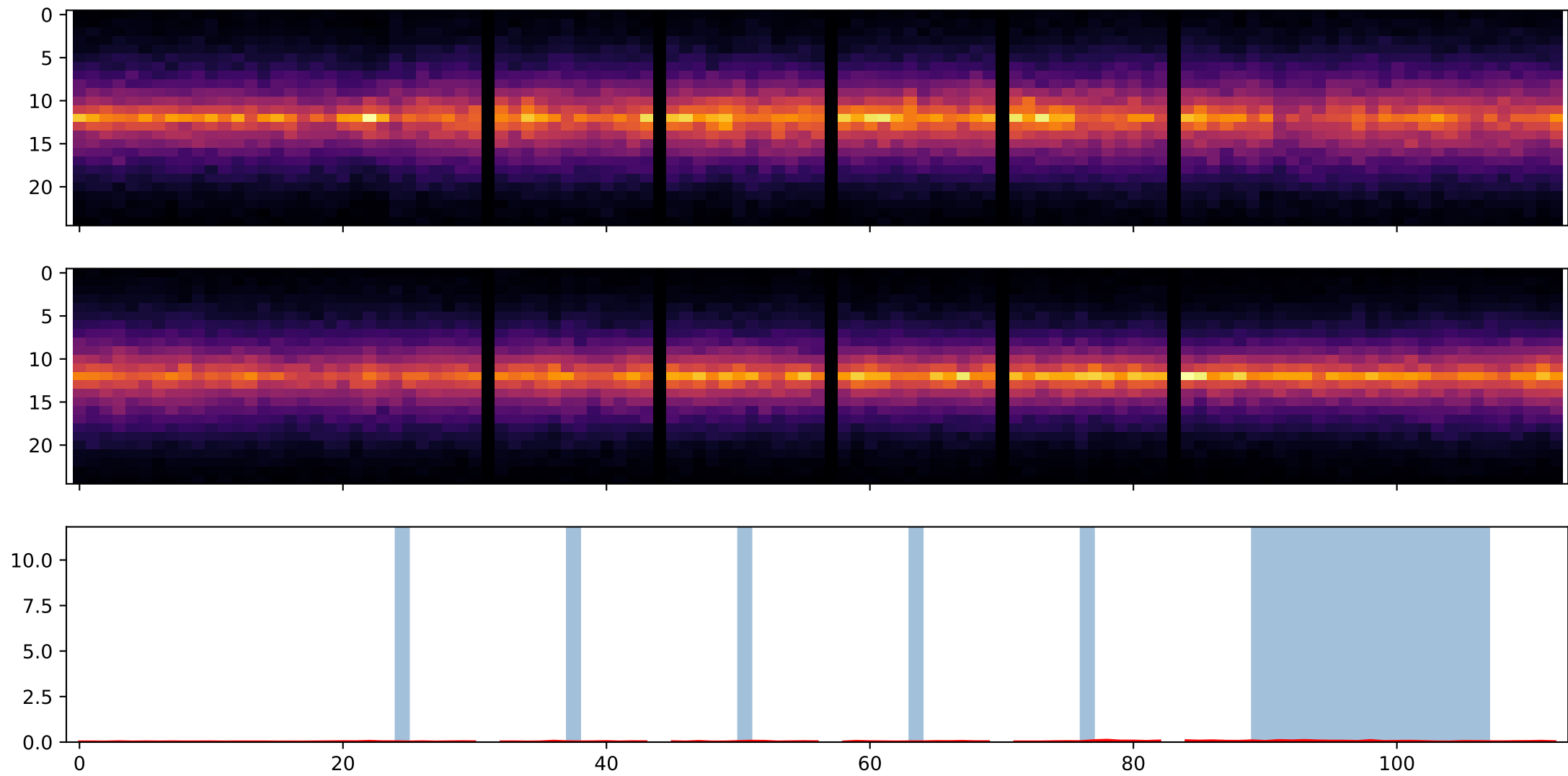
d_eigen_projection_7



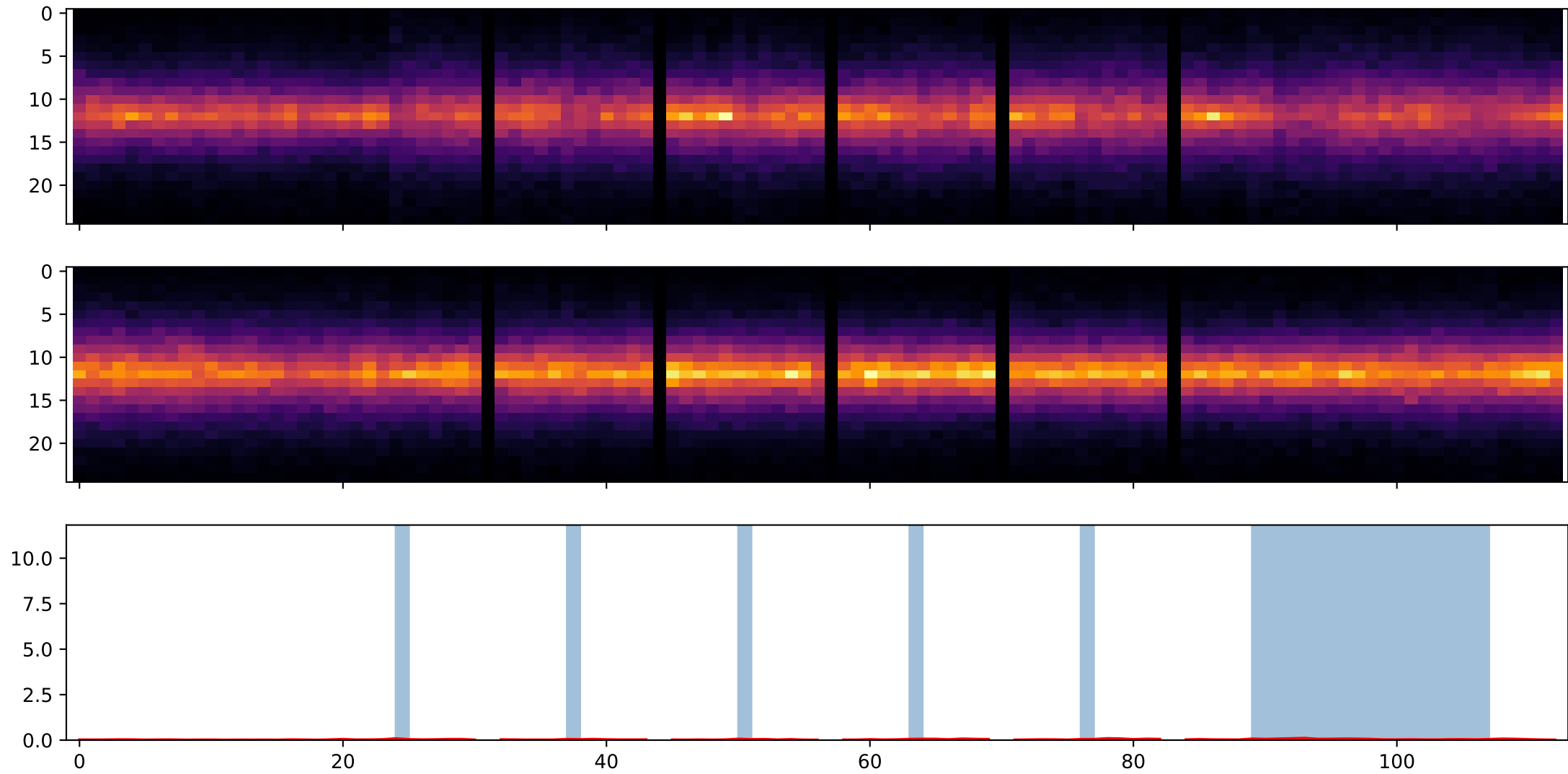
d_angular_velocity_head_tip



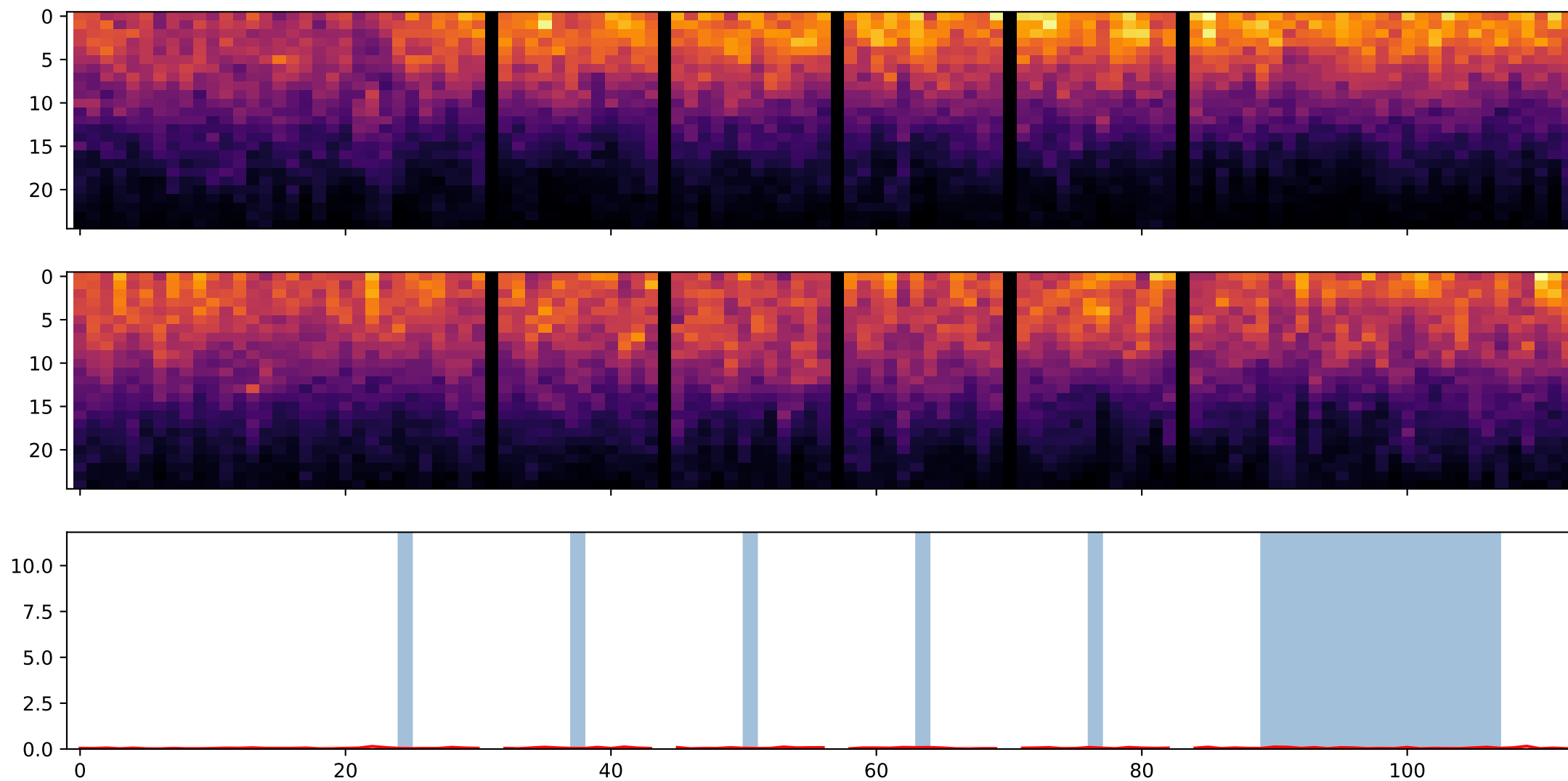
d_width_head_base



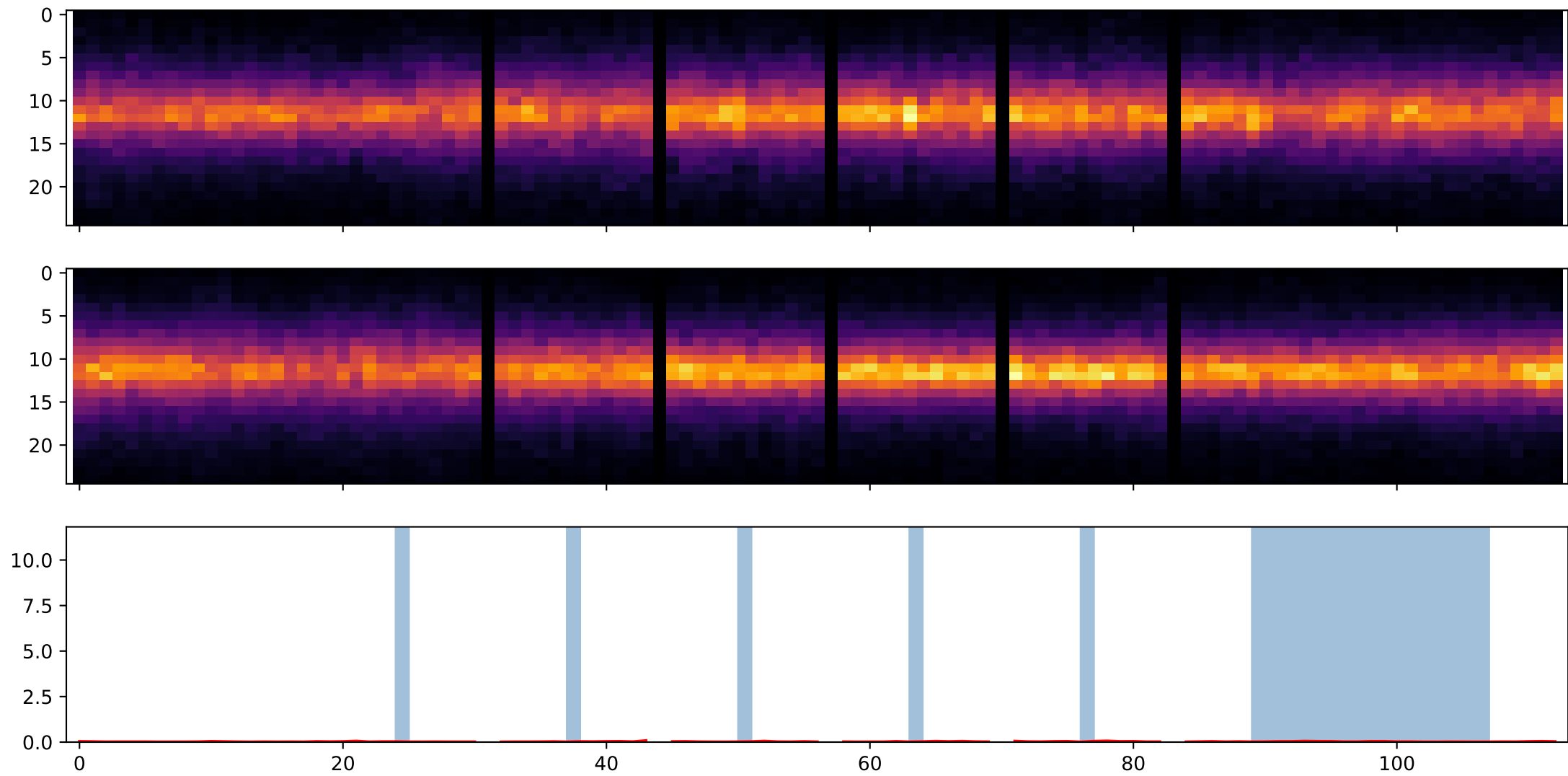
d_width_midbody



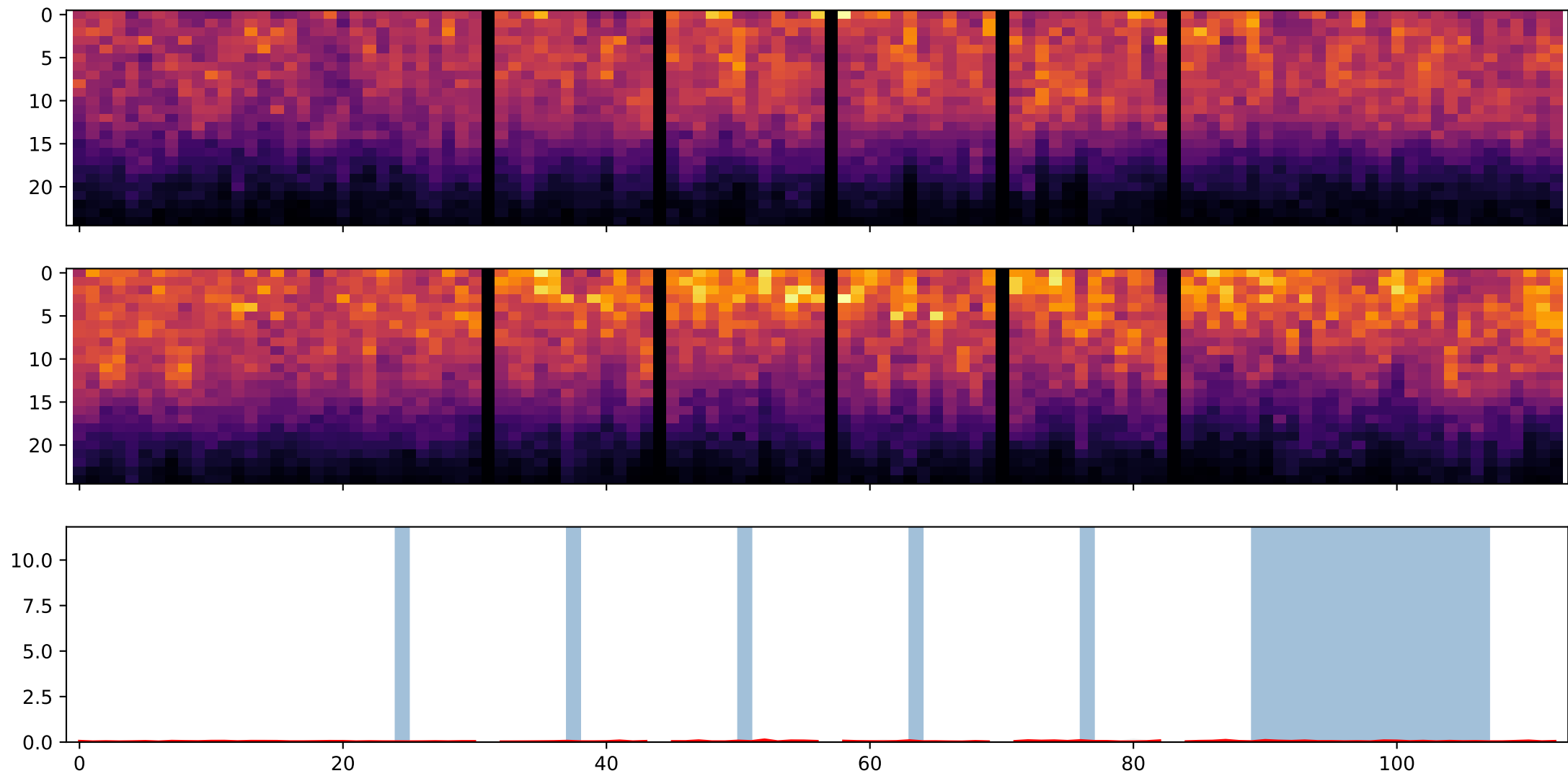
eigen_projection_5



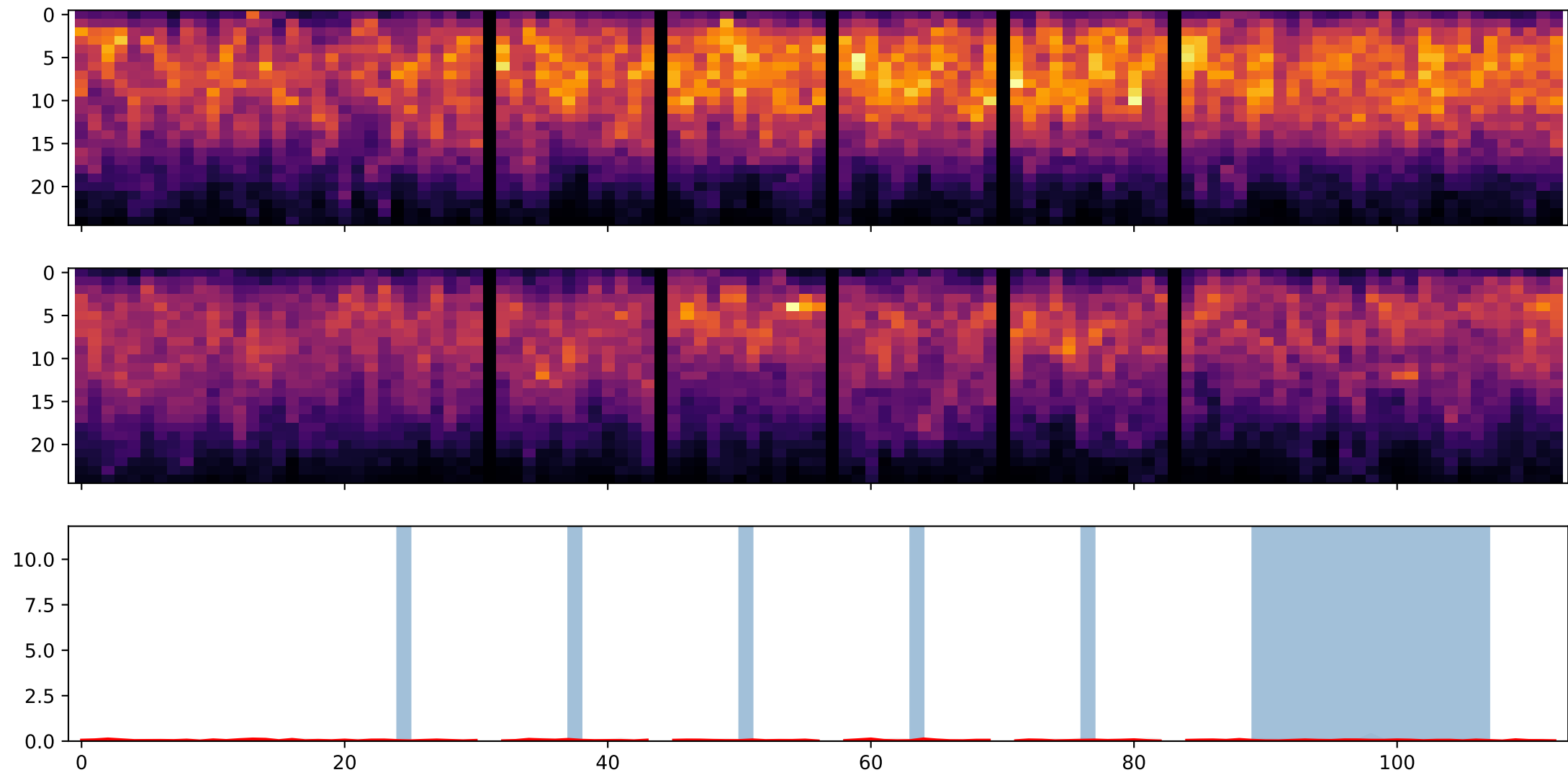
relative_to_head_base_radial_velocity_head_tip



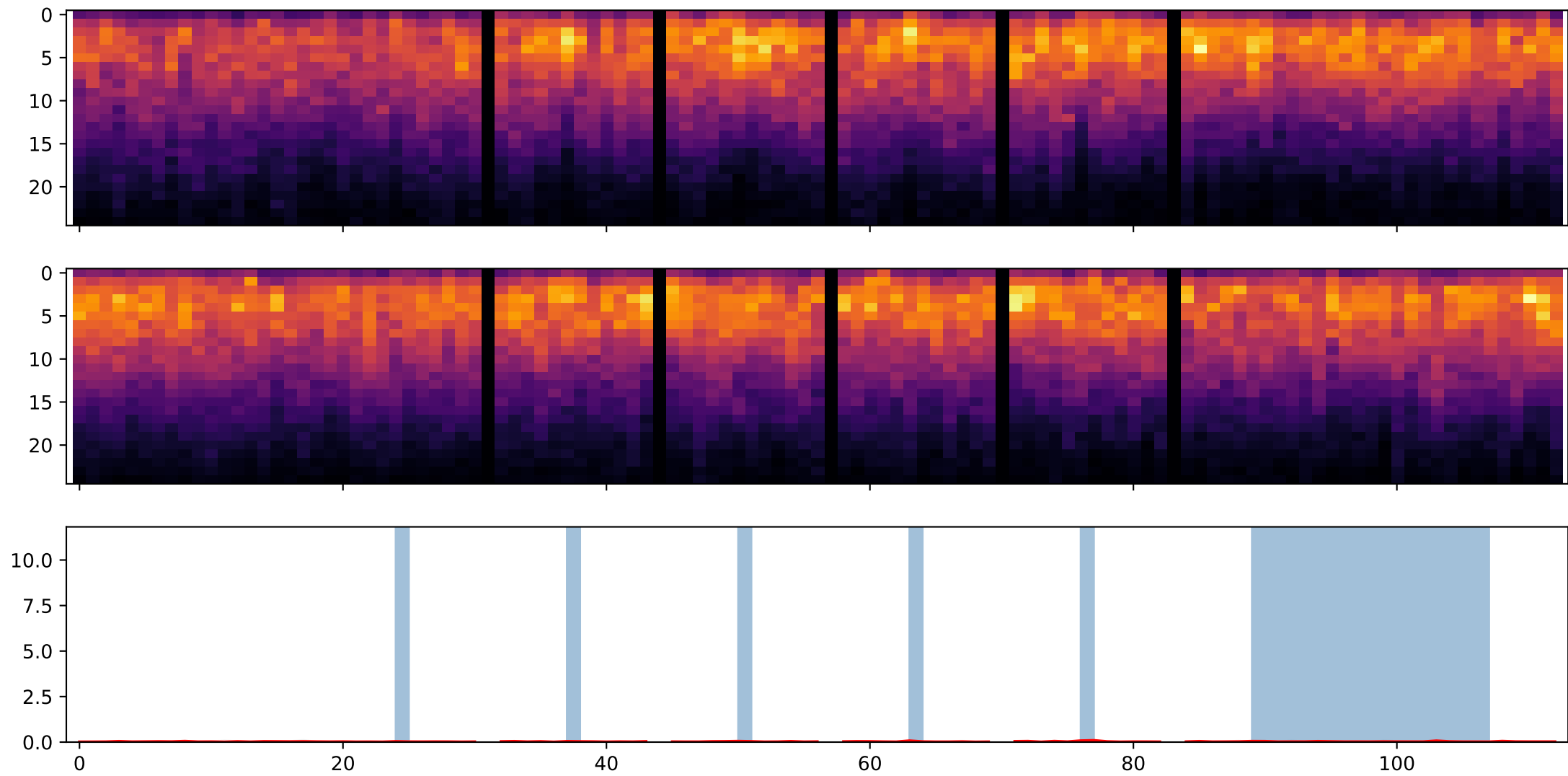
curvature_head



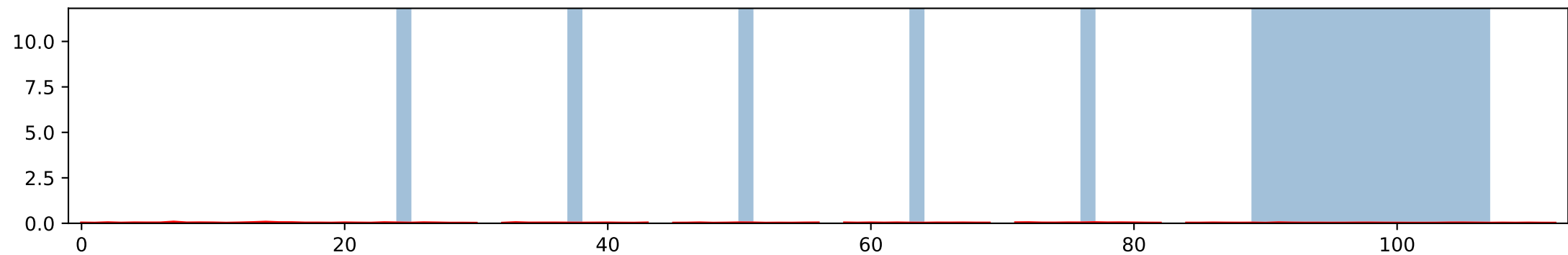
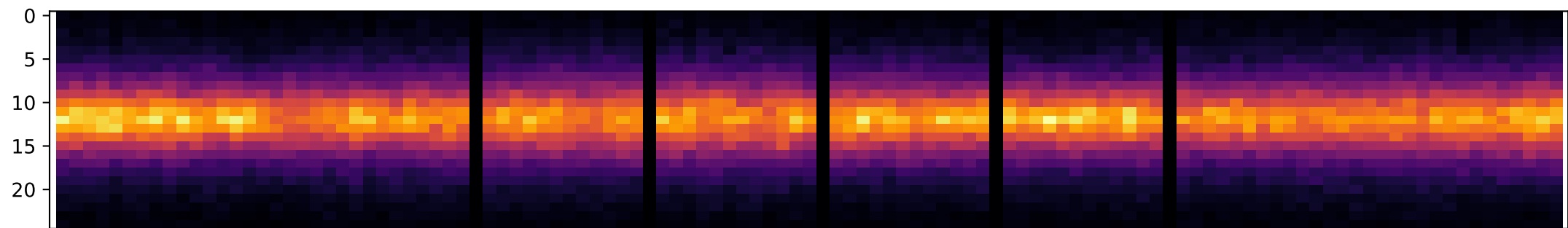
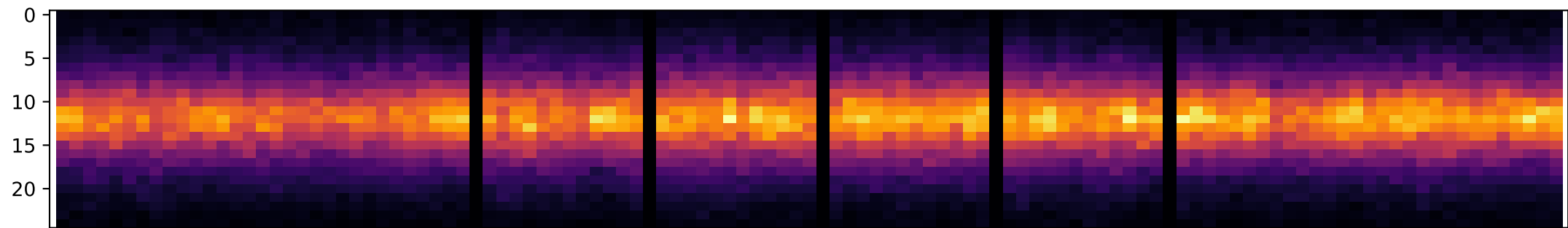
curvature_std_neck



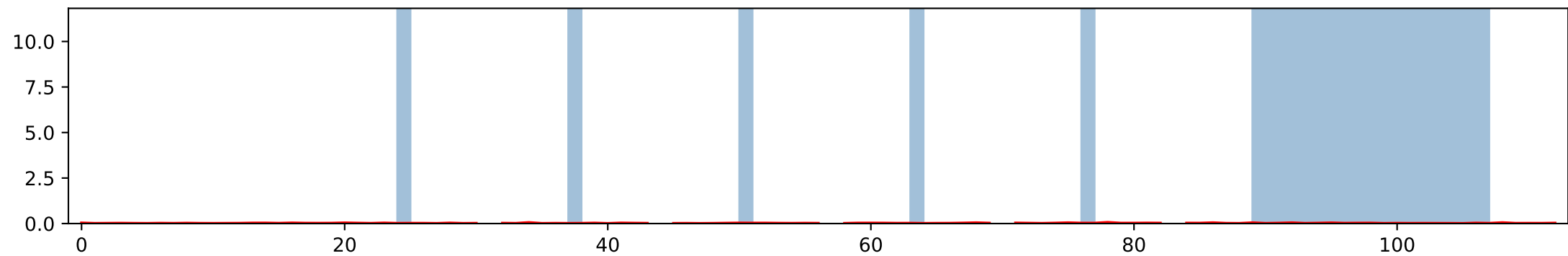
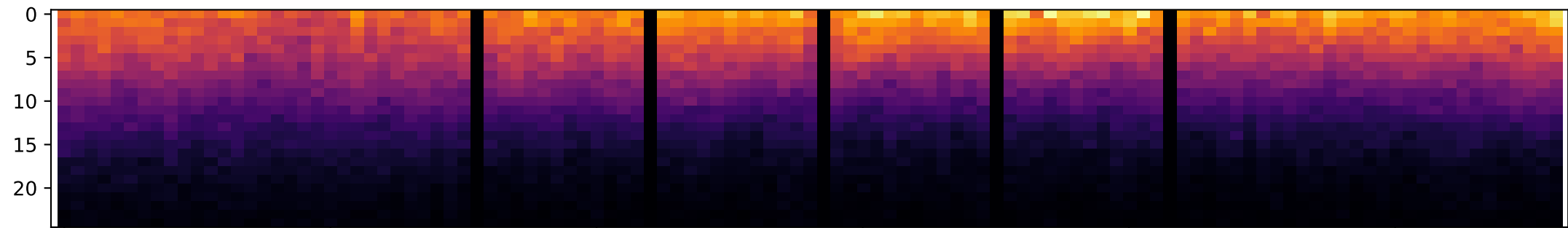
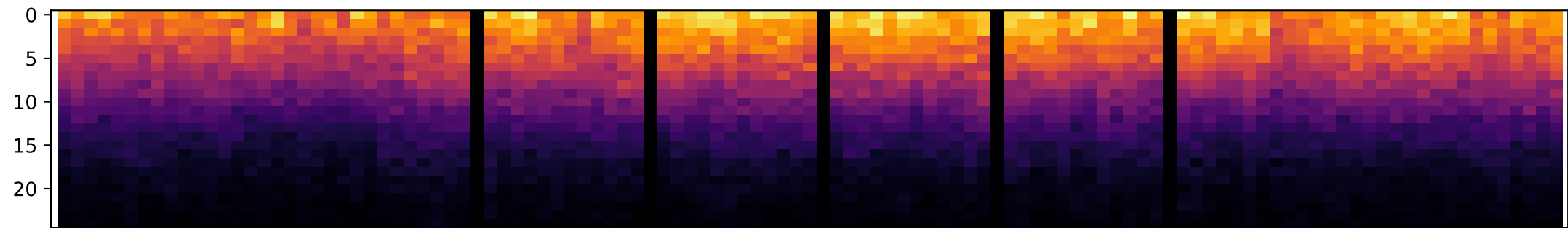
curvature_std_head



d_area



d_eigen_projection_6



d_curvature_std_head

