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04ThreeViewTwoView_Versiglioni
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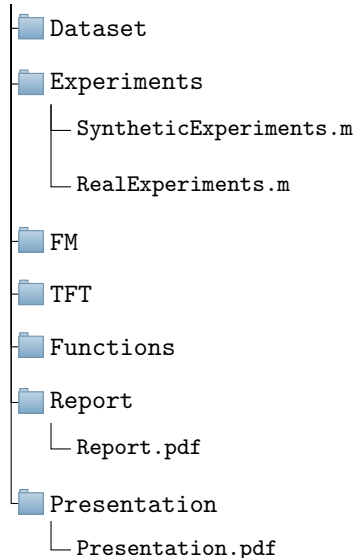
- **Dataset** contains EPFL dataset (images, cameras, ...)

- **Experiments** contains MATLAB scripts to reproduce both the synthetic and the real experiments, and the obtained results

- **FM** contains MATLAB scripts that implement LinearFM estimation and OptimizedFM estimation, exploited in the corresponding pose estimation algorithms (LinearFMPoseEst and OptimizedFMPoseEst)

- **TFT** contains MATLAB scripts that implement LinearTFT estimation and the optimized TFT estimations w.r.t. the considered parametrizations, exploited in the corresponding pose estimation algorithms

- **Functions** contains MATLAB functions utilized