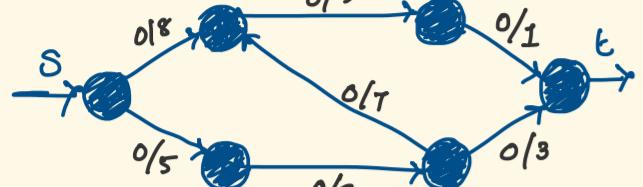


Network flow

Tuesday, October 31, 2023 6:15 AM

- A flow graph is a network of nodes each having a specific capacity
- It consists of a sink node & a source node
- ↑ sender
↑ receiver



Max flow w/o exceeding the capacity.
Applications

- roads with cars (traffic flow)
- water pipes
- electric wires

max flow is the bottleneck value of the amount of traffic your n/w can handle

Ford Fulkerson method

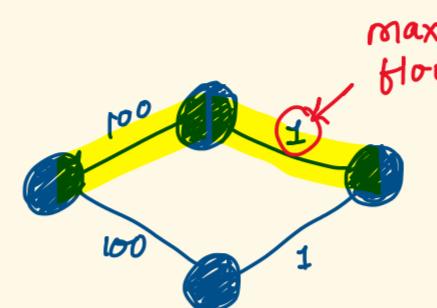
- To find the max flow (& min-cut) the ford fulkerson method repeatedly finds augmenting paths through the residual graph & augments the flow until no more augmenting paths can be found.

Augmenting paths: path in a residual graph with unused capacity > 0 from s to t.

- Every augmenting path has a bottleneck value which is the smallest edge along the path.
- When augmenting a path we update the flow value of the edges along the augmenting path.
- For forward edges we increase the flow val, & decrease for backward (residual edges) by the bottleneck value.
- Undo an bad choices taken while augmenting.

* flow can be -ve.

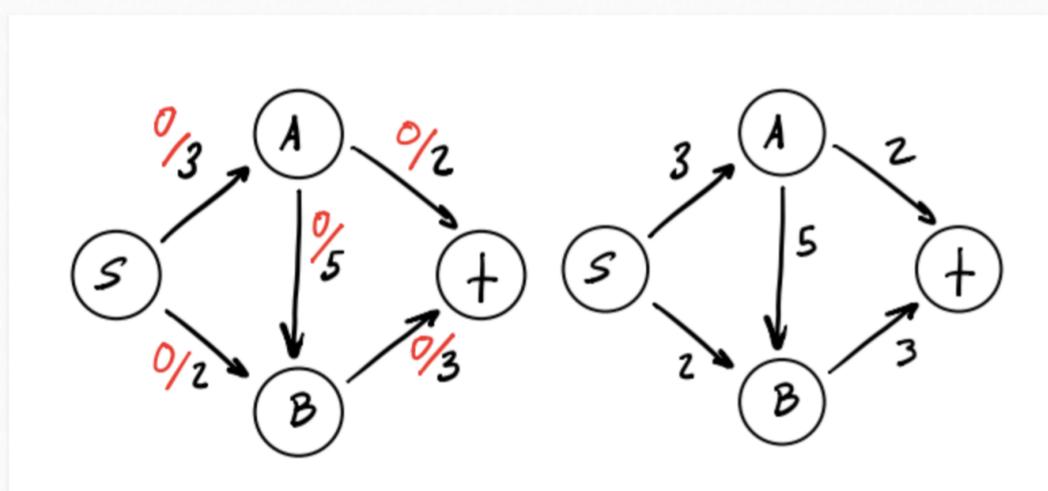
* capacity is always +ve.



<https://downey.io/blog/max-flow-ford-fulkerson-algorithm-explanation/> ← see

This algorithm will look pretty similar to the one we laid out earlier, with one key difference. We will be constructing a residual graph for the flow network and searching for $s-t$ paths across it instead!

1. Initially set the flow along every edge to 0.
2. Construct a residual graph for this network. It should look the same as the input flow network.



1. Use a pathfinding algorithm like depth-first search (DFS) or breadth-first search (BFS) to find a path P from s to t that has available capacity in the residual graph.
2. Let $cap(P)$ indicate the maximum amount of stuff that can flow along this path. To find the capacity of this path, we need to look at all edges e on the path and subtract their current flow, f_e , from their capacity c_e . We'll set $cap(P)$ to be equal to the smallest value of $c_e - f_e$ since this will bottleneck the path.
3. We then **augment the flow** across the forward edges in the path P by adding $cap(P)$ value. For flow across the back edges in the residual graph, we subtract our $cap(P)$ value.
4. Update the residual graph with these flow adjustments.
5. Repeat the process from step 2 until there are no paths left from s to t in the **residual graph** that have available capacity.

```
FordFulkerson(Graph G, Node s, Node t):
    Initialize flow of all edges e to 0.
    while(there is augmenting path(P) from s to t
    in the residual graph):
        Find augmenting path between s and t.
        Update the residual graph.
        Increase the flow.
    return
```

```
1 def search_path(s, t, parent):
2     visited = [0] * n
3     queue = deque()
4     queue.append(s)
5     visited[s] = True
6     while queue:
7         u = queue.popleft()
8         for ind, val in enumerate(matrix[u]):
9             if not visited[ind] and val > 0: # non-zero
10                capacity_edge = val
11                queue.append(ind)
12                visited[ind] = True
13                parent[ind] = u
14
15    return True if visited[t] else False
16
17 def ford_fulkerson(source, sink):
18     parent = [-1] * n
19     max_flow = 0
20
21     while search_path(source, sink, parent):
22         flow = inf
23         s = sink
24         while s != source:
25             flow = min(flow, matrix[parent[s]][s])
26             s = parent[s]
27
28         max_flow += flow
29
30         v = sink
31         while v != source:
32             u = parent[v]
33             matrix[u][v] -= flow
34             matrix[v][u] += flow
35             v = parent[v]
36
37         return max_flow
```

finding Bottleneck

↑ updating forward edges

```
1 def search_path(source, sink, parent, visited):
2     if source == sink: return True
3     visited.add(source)
4     for ind, val in matrix[source]:
5         if ind not in visited and val > 0:
6             parent[ind] = source
7             if search_path(ind, sink, parent, visited): return True # found path
8     return False
9
10
11 def ford_fulkerson(source, sink):
12     parent = [-1] * n
13     max_flow = 0
14
15     while search_path(source, sink, parent, set()):
16         flow = inf
17         s = sink
18
19         while s != source:
20             flow = min(flow, matrix[parent[s]][s])
21             s = parent[s]
22
23         max_flow += flow
24
25         v = sink
26         while v != source:
27             u = parent[v]
28             matrix[u][v] -= flow
29             matrix[v][u] += flow
30             v = parent[v]
31
32     return max_flow
```

$O(\frac{f}{E})$
max flow

Problems

- DFS randomly chooses nodes.
- Can return long paths.
- Inger the path, smaller the bottleneck val higher the runtime.

Edmonds Karp algorithm

- Uses BFS instead of DFS.
- Runs in $O(VE^2)$ time.
- Does not depend on the flow value
- It is a strongly polynomial.
- BFS gives us the shortest path.
- ↳ All the edges hv weights we don't distinguish between them.

