

# **Deadlocks**

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#### Slides Credits for all PPTs of this course



- The slides/diagrams in this course are an adaptation,
   combination, and enhancement of material from the following resources and persons:
- Slides of Operating System Concepts, Abraham Silberschatz, Peter Baer Galvin, Greg Gagne - 9<sup>th</sup> edition 2013 and some slides from 10<sup>th</sup> edition 2018
- 2. Some conceptual text and diagram from Operating Systems Internals and Design Principles, William Stallings, 9<sup>th</sup> edition 2018
- 3. Some presentation transcripts from A. Frank P. Weisberg
- 4. Some conceptual text from Operating Systems: Three Easy Pieces, Remzi Arpaci-Dusseau, Andrea Arpaci Dusseau



**Principles of Deadlocks, Deadlock Characterization** 

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#### Introduction

- Multiprogramming environment: several processes compete to limited number of resources
- ☐ A Process is holding a resource(R1) and is waiting for the resources(R2).
- ☐ The resource R2 is held by another process...
- Waiting state of processes will not change, as the requested resource is held by the waiting process.
- □ This situation is called deadlock



## **System Model**

- System consists of finite number of resources
- $\square$  Resource types  $R_1, R_2, \ldots, R_m$ 
  - □ Physical resources: CPU cycles, memory space, I/O devices, printer, tape drives.
  - □ Logical resources: semaphores, mutex locks, files.
- $\square$  Each resource type  $R_i$  has  $W_i$  instances.
- ☐ Ex: if the system has 2 CPU's then CPU has 2 instances
- Each process utilizes a resource as follows:
  - Request: Process makes request to the resource. Eg. system call like request(), open(), wait(), allocate() etc
  - Use: operates on these resources
  - □ **Release:** process releases the resources. Eg. Using a system call like release(), close(), signal(), free etc.
- ☐ Request and release of semaphore, acquire and release of lock on mutex



## **Deadlock with physical resources**

## **Example 1**

- Consider a system with 3 CD RW drives.
- Suppose 3 processes(p0,p1,p2) are holding one drive each.
- What happens,
  - If a process p0 makes a request for one more drive

## Example 2

- Consider a system with one printer one DVD drive.
- Process Pi is holding printer and process Pj is holding DVD drive.
- What happens if
  - Process Pi request DVD and Pj requests printer

Does dead lock occur in example 1 and 2?



## **Deadlock with Semaphores**

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- Data:
  - A semaphore **\$1** initialized to 1
  - A semaphore **S2** initialized to 1
- Two processes P1 and P2
- **P1:**

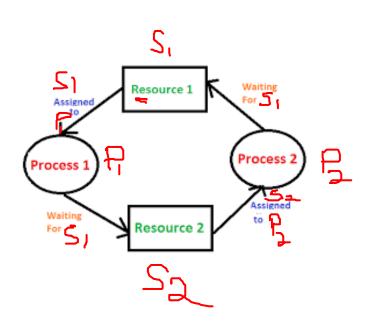
wait(s1)

wait(s2)

**P2:** 

wait(s2)

wait(s1)



### **Bridge crossing Example**





- Traffic only in one direction
- Each section of a bridge can be viewed as a resource
- If a deadlock occurs, it can be resolved if one car backs up (preempt resources and rollback)
- Several cars may have to be backed up if a deadlock occurs
- Starvation is possible.
- Note Most OSes do not prevent or deal with deadlocks

#### **Deadlock Characterization**



- Mutual exclusion: only one process at a time can use a resource (sharable resources like Read-only files do not require mutually exclusive access and thus cannot be involved in a deadlock.
- □ Hold and wait: a process holding at least one resource is waiting to acquire additional resources held by other processes
- No preemption: a resource can be released only voluntarily by the process holding it, after that process has completed its task
- Circular wait: there exists a set  $\{P_0, P_1, ..., P_n\}$  of waiting processes such that  $P_0$  is waiting for a resource that is held by  $P_1, P_1$  is waiting for a resource that is held by  $P_2, ..., P_{n-1}$  is waiting for a resource that is held by  $P_n$ , and  $P_n$  is waiting for a resource that is held by  $P_0$ .



## **Resource-Allocation Graph**



 Deadlocks are described precisely with directed graphs called system resource-allocation graph

A graph consists of set of vertices V and a set of edges E.

- V is partitioned into two types:
  - $P = \{P_1, P_2, ..., P_n\}$ , the set consisting of all the processes in the system
  - $\square$   $R = \{R_1, R_2, ..., R_m\}$ , the set consisting of all resource types in the system
- $\square$  request edge directed edge  $P_i \rightarrow R_i$
- $\square$  assignment edge directed edge  $R_i \rightarrow P_i$

## **Resource-Allocation Graph (Cont.)**

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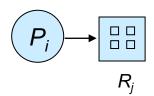
A set of vertices V and a set of edges E.

Process

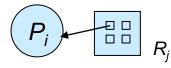


□ Resource Type with 4 instances

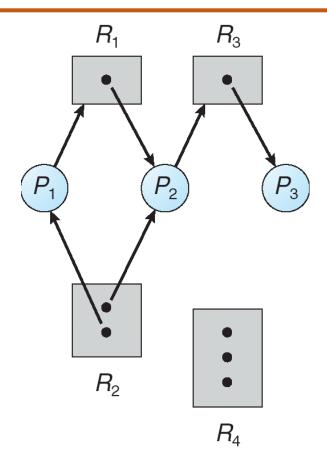
 $\square$   $P_i$  requests instance of  $R_j$ 



 $\square$   $P_i$  is holding an instance of  $R_j$ 



## **Example of a Resource-Allocation Graph**

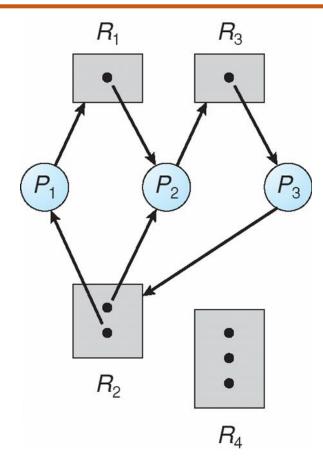


Set of process: P1,P2,P3

Set of Resources: R1,R2,R3



## **Resource-Allocation Graph With A Deadlock**

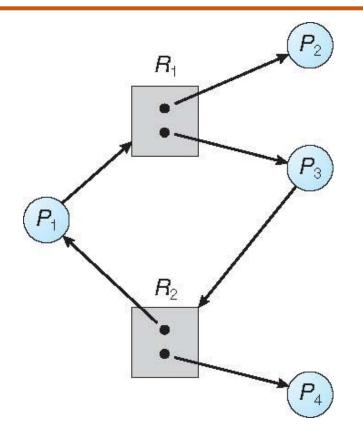


$$P1 \rightarrow R1 \rightarrow P2 \rightarrow R3 \rightarrow P3 \rightarrow R2 \rightarrow P1$$

 $P2 \rightarrow R3 \rightarrow P3 \rightarrow R2 \rightarrow P2$ 



## **Resource-Allocation Graph With A Cycle but No Deadlock**







#### **Basic Facts**

- $\square$  If graph contains no cycles  $\Rightarrow$  no deadlock
- ☐ If graph contains a cycle ⇒
  - ☐ if only one instance per resource type, then deadlock
  - ☐ if several instances per resource type, the system may or may not be in a deadlocked state





## **THANK YOU**

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