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Q1. $L: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ by $L(\alpha_1, \alpha_2, \alpha_3) = (\alpha_3 - \alpha_1, \alpha_1 + \alpha_2)$

(i) Representing in matrix form

$$\begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix} = \begin{bmatrix} \alpha_3 - \alpha_1 \\ \alpha_1 + \alpha_2 \end{bmatrix} = \alpha_1 \begin{bmatrix} -1 \\ 1 \end{bmatrix} + \alpha_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix} + \alpha_3 \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\therefore L(e_1) = (-1, 1)$$

$$L(e_2) = (0, 1)$$

$$L(e_3) = (1, 0)$$

(ii) Take any (α_1, y_1, z_1) and $(\alpha_2, y_2, z_2) \in \mathbb{R}^3$

$$\begin{aligned} T((\alpha_1, y_1, z_1) + (\alpha_2, y_2, z_2)) &= T(\underbrace{\alpha_1 + \alpha_2}_{\alpha_1}, \underbrace{y_1 + y_2}_{\alpha_2}, \underbrace{z_1 + z_2}_{\alpha_3}) \\ &= T((z_1 + z_2) - (\alpha_1 + \alpha_2), (\alpha_1 + \alpha_2) + (y_1 + y_2)) \\ &= T(z_1 + z_2 - \alpha_1 - \alpha_2, \alpha_1 + \alpha_2 + y_1 + y_2) \\ &= T((z_1 - \alpha_1) + (z_2 - \alpha_2), (\alpha_1 + y_1) + (\alpha_2 + y_2)) \\ &= (z_1 - \alpha_1, \alpha_1 + y_1) + (z_2 - \alpha_2, \alpha_2 + y_2) \\ &= T(\alpha_1, y_1, z_1) + T(\alpha_2, y_2, z_2) \end{aligned}$$

$$\text{Also } T(0, 0, 0) = \cancel{\mathbb{R}}(0, 0) = 0$$

$$\text{Q1) } L(e_1) = L(1, 0, 0) = (-1, 1)$$

$$L(e_2) = L(0, 1, 0) = (0, 1)$$

$$L(e_3) = L(0, 0, 1) = (1, 0)$$

$$\text{Q2 } L(1, 0, 1) = (-1, 1, 0, 2) \quad L(0, 1, 1) = (0, 6, -2, 0) \quad L(-1, 1, 1) = (4, -2, 1, 0)$$

Using the property of $L(\alpha_1, \alpha_2, \alpha_3) = \alpha_1 L(e_1) + \alpha_2 L(e_2) + \alpha_3 L(e_3)$

$$L(1, 0, 1) = L(e_1) + L(e_3) = (-1, 1, 0, 2)$$

$$L(0, 1, 1) = L(e_2) + L(e_3) = (0, 6, -2, 0)$$

$$L(-1, 1, 1) = -L(e_1) + L(e_2) + L(e_3) = (4, -2, 1, 0)$$

Representing in matrix form

$$\begin{bmatrix} -1 & 1 & 1 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} L(e_1) \\ L(e_2) \\ L(e_3) \end{bmatrix} = \begin{bmatrix} 4 & -2 & 1 & 0 \\ 0 & 6 & -2 & 0 \\ -1 & 1 & 0 & 2 \end{bmatrix}$$

Gaussian elimination:

$$\begin{bmatrix} -1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix}$$

$$\begin{bmatrix} 4 & -2 & 1 & 0 \\ 0 & 6 & -2 & 0 \\ 3 & -1 & 1 & 2 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 4 & -2 & 1 & 0 \\ 0 & 6 & -2 & 0 \\ 3 & -7 & 3 & 2 \end{bmatrix}$$

$$\therefore L(e_3) = (3, -7, 3, 2)$$

$$L(e_2) + L(e_3) = (3, -7, 3, 2) + L(e_2) = (0, 6, -2, 0)$$

$$\therefore L(e_2) = (-3, 13, -5, -2)$$

$$-L(e_1) + L(e_2) + L(e_3) = -L(e_1) + (0, 6, -2, 0) = (4, -2, 1, 0)$$

$$\therefore L(e_1) = -(4, -8, 3, 0)$$

$$\therefore L(e_1) = (-4, 8, -3, 0)$$

$$L(1, 2, -1) = L(e_1) + 2L(e_2) - L(e_3)$$

$$= (-4, 8, -3, 0) + (-6, 26, -10, -4) + (-3, 7, -3, -2)$$

$$= (-13, 41, -16, -6)$$

Q3. We multiply B with each vector in the standard basis of F.
The four corresponding matrices are columns in the matrix L.

$$\begin{bmatrix} -2 & 1 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} -2 & 0 \\ 3 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -2 & 1 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & -2 \\ 0 & 3 \end{bmatrix}$$

$$\begin{bmatrix} -2 & 1 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 4 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -2 & 1 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 0 & 4 \end{bmatrix}$$

$$\therefore L = \begin{bmatrix} -2 & 0 & 1 & 0 \\ 0 & -2 & 0 & 1 \\ 3 & 0 & 4 & 0 \\ 0 & 3 & 0 & 4 \end{bmatrix}$$

Q4. Since they are orthogonal, it means they are independent.

$$v = (7, 1, 9)$$

$$v_1 = (1, 2, 1)$$

$$v_2 = (2, 1, -4)$$

$$v_3 = (3, -2, 1)$$

$$v = c_1 v_1 + c_2 v_2 + c_3 v_3$$

We get the following equations

$$c_1 + 2c_2 + 3c_3 = 7$$

$$2c_1 + c_2 - 2c_3 = 1$$

$$c_1 - 4c_2 + c_3 = 9$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 2 & 1 & -2 \\ 1 & -4 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 7 \\ 1 \\ 9 \end{bmatrix}$$

Performing Gaussian elimination

$$R_2 \rightarrow R_2 - 2R_1$$

$$R_3 \rightarrow R_3 - R_1$$

$$\begin{bmatrix} 1 & 2 & 3 & 7 \\ 0 & -3 & -8 & -13 \\ 0 & -6 & -2 & 2 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - 2R_2$$

$$\begin{bmatrix} 1 & 2 & 3 & 7 \\ 0 & -3 & -8 & -13 \\ 0 & 0 & 14 & 28 \end{bmatrix}$$

$$\therefore c_3 = 2$$

$$\therefore c_2 = -1$$

$$\therefore c_1 = 3$$

$$\therefore v = (7, 1, 9) = 3v_1 - v_2 + 2v_3$$

q5. We know, $p = A(A^T A)^{-1} A^T$

$$A = \begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 1 & 0 \end{bmatrix}$$

$$A^T = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 0 \end{bmatrix}$$

$$A^T A = \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix}$$

$$(A^T A)^{-1} = \frac{1}{6} \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}$$

$$(A^T A)^{-1} A^T = \frac{1}{6} \begin{bmatrix} 2 & 2 & 2 \\ 3 & -3 & 0 \end{bmatrix}$$

$$A(A^T A)^{-1} A^T = \frac{1}{6} \begin{bmatrix} 5 & -1 & 2 \\ -1 & 5 & 2 \\ 2 & 2 & 2 \end{bmatrix} = \begin{bmatrix} 5/6 & -1/6 & 1/3 \\ -1/6 & 5/6 & 1/3 \\ 1/3 & 1/3 & 1/3 \end{bmatrix}$$

Q6. We need to find $\hat{\alpha}$.

$$\hat{\alpha} = (A^T A)^{-1} A^T y$$

$$A = \begin{bmatrix} 1 & 1 \\ 2 & 1 \\ -1 & 1 \\ 0 & 1 \end{bmatrix}$$

$$y = \begin{bmatrix} 2 \\ 3 \\ 1 \\ 1 \end{bmatrix}$$

$$A^T = \begin{bmatrix} 1 & 2 & -1 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix}$$

$$A^T A = \begin{bmatrix} 1 & 2 & -1 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 2 & 1 \\ -1 & 1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 6 & 2 \\ 2 & 4 \end{bmatrix}$$

$$(A^T A)^{-1} = \frac{1}{20} \begin{bmatrix} 4 & -2 \\ -2 & 6 \end{bmatrix} = \frac{1}{10} \begin{bmatrix} 2 & -1 \\ -1 & 3 \end{bmatrix}$$

$$(A^T A)^{-1} A^T = \frac{1}{10} \begin{bmatrix} 2 & -1 \\ -1 & 3 \end{bmatrix} \begin{bmatrix} 1 & 2 & -1 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix} = \frac{1}{10} \begin{bmatrix} 1 & 3 & -3 & -1 \\ 2 & 1 & 4 & 3 \end{bmatrix}$$

$$(A^T A)^{-1} A^T y = \frac{1}{10} \begin{bmatrix} 1 & 3 & -3 & -1 \\ 2 & 1 & 4 & 3 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \\ 1 \\ 1 \end{bmatrix} = \frac{1}{10} \begin{bmatrix} 7 \\ 14 \end{bmatrix}$$

$$\therefore \alpha = \begin{bmatrix} 7/10 \\ 7/5 \end{bmatrix}$$

Q7. Converting the equations in matrix form:

$$Ax = b$$

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 2 \\ 1 & 1 \end{bmatrix}$$

$$b = \begin{bmatrix} 3 \\ 5 \\ 2.09 \end{bmatrix}$$

$$x = \begin{bmatrix} x \\ y \end{bmatrix}$$

To find x , we find $\hat{x} = (A^T A)^{-1} A^T b$

$$A^T A = \begin{bmatrix} 1 & 3 & 1 \\ 2 & 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 2 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 11 & 9 \\ 9 & 9 \end{bmatrix}$$

$$(A^T A)^{-1} = \frac{1}{18} \begin{bmatrix} 9 & -9 \\ -9 & 11 \end{bmatrix}$$

$$(A^T A)^{-1} A^T = \frac{1}{18} \begin{bmatrix} 9 & -9 \\ -9 & 11 \end{bmatrix} \begin{bmatrix} 1 & 3 & 1 \\ 2 & 2 & 1 \end{bmatrix} = \frac{1}{18} \begin{bmatrix} -9 & 9 & 0 \\ 13 & -5 & 2 \end{bmatrix}$$

$$(A^T A)^{-1} A^T b = \frac{1}{18} \begin{bmatrix} -9 & 9 & 0 \\ 13 & -5 & 2 \end{bmatrix} \begin{bmatrix} 3 \\ 5 \\ 2.09 \end{bmatrix} = \frac{1}{18} \begin{bmatrix} 18 \\ 18.18 \end{bmatrix}$$

$$\therefore \hat{x} = \begin{bmatrix} 1 \\ 1.01 \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\therefore x = 1 \quad y = 1.01$$

Q8. $T(x, y, z) = (5x - 3y + z, 2z + 4y, 5x + 3y)$

To find the standard matrix, we use vectors from the identity matrix

$$T(1, 0, 0) = (5, 0, 5)$$

$$T(0, 1, 0) = (-3, 4, 3)$$

$$T(0, 0, 1) = (1, 2, 0)$$

88 These are now columns in the final matrix.

$$\therefore A = \begin{bmatrix} 5 & -3 & 1 \\ 0 & 4 & 2 \\ 5 & 3 & 0 \end{bmatrix}$$

89. $T(x, y, z) = (2x + 3y, 3y - z)$

$$T(1, 0, 0) = (2, 0)$$

$$T(0, 1, 0) = (3, 3)$$

$$T(0, 0, 1) = (0, -1)$$

$$\therefore A = \begin{bmatrix} 2 & 3 & 0 \\ 0 & 3 & -1 \end{bmatrix}$$

We need to find $T(0, 1, -1)$

So $Ax = b$ where $x = (0, 1, -1)$

$$\begin{bmatrix} 2 & 3 & 0 \\ 0 & 3 & -1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

~~verify~~ Verifying with $T(0, 1, -1) = (3(1), 3(1) - (-1))$
 $= (3, 4)$

$$\therefore T(0, 1, -1) = (3, 4)$$

10. Given,

T is a reflection of the line $y=x$ in \mathbb{R}^2 .

$$\text{so, } T(x, y) = (y, x)$$

$$T \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \quad T \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\text{Standard matrix of } T = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$T \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$$

$$T \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$$

11. Given,

$$\vec{x} = \begin{bmatrix} 6 \\ 5 \\ 4 \end{bmatrix}, \quad \vec{a} = \begin{bmatrix} 1 \\ -1 \\ 3 \end{bmatrix}$$

Let, projection be $\hat{x} \cdot a$

$$p = \hat{x} \cdot a = \left[\frac{a^T x}{a^T a} \right] \cdot a$$

$$= \left(\frac{[1 \ -1 \ 3] \begin{bmatrix} 6 \\ 5 \\ 4 \end{bmatrix}}{\| \begin{bmatrix} 1 \\ -1 \\ 3 \end{bmatrix} \|} \right) \begin{bmatrix} 1 \\ -1 \\ 3 \end{bmatrix}$$

$$p = \hat{x} \cdot a = \begin{bmatrix} \frac{13}{11} \\ -13/11 \\ +39/11 \end{bmatrix}$$

13. Given, $(1, 0, 1, 0, 2)$, $(0, 1, 1, 1, 0)$ & $(1, 1, 1, 1, 1)$

$$\text{Let, } S = \begin{bmatrix} 1 & 0 & 1 & 0 & 2 \\ 0 & 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 & 1 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - R_1$$

$$\sim \begin{bmatrix} 1 & 0 & 1 & 0 & 2 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 & -1 \end{bmatrix} = U = R$$

The basis for $S^\perp = (-1, -1, 1, 0, 0), (0, -1, 0, 1, 0), (-2, 0, 0, 0, 1)$

14. P_1 = Projection of b onto A

$$= \frac{a^T b \cdot a}{a^T \cdot a}$$

$$= \frac{19}{38} (3, 2, 5)$$

$$= (3/2, 1, 5/2)$$

P_2 = Projection of b onto c

$$= \frac{c^T b}{c^T c} \cdot c$$

$$= (0, 0, 0)$$

15. Reflection matrix $H = \begin{bmatrix} 2c^2 - 1 & 2cs \\ 2cs & 2s^2 - 1 \end{bmatrix}$

1st reflection about y-axis $\theta = 90^\circ$, Let T be the matrix

$$T = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$

2nd reflection about x-axis $\theta = 0^\circ$, Let S be the matrix

$$S = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$ST = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$

16. Given,

$(1, -1), (4, 11), (-1, -9) \& (-2, -13)$

Let, $b = c + Dt$ be the best fitting line,

Now, $c + D(1) = -1$

$$c + D(4) = 11$$

$$c + D(-1) = -9$$

$$c + D(-2) = -13$$

i.e., $Ax = b$

$$\begin{bmatrix} 1 & 1 \\ 1 & 4 \\ 1 & -1 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} c \\ D \end{bmatrix} = \begin{bmatrix} -1 \\ 11 \\ -9 \\ -13 \end{bmatrix}$$

consider,

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 4 & -1 & -2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 4 \\ 1 & -1 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} c \\ D \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 4 & -1 & -2 \end{bmatrix} \begin{bmatrix} -1 \\ 11 \\ -9 \\ -13 \end{bmatrix}$$

$$\begin{bmatrix} 4 & 2 \\ 2 & 22 \end{bmatrix} \begin{bmatrix} c \\ D \end{bmatrix} = \begin{bmatrix} -12 \\ 78 \end{bmatrix}$$

$$R_2 \rightarrow R_2 - \left(\frac{1}{2}\right) R_1$$

$$\begin{bmatrix} 4 & 2 \\ 0 & 21 \end{bmatrix} \begin{bmatrix} c \\ D \end{bmatrix} = \begin{bmatrix} -12 \\ 84 \end{bmatrix}$$

$c = -5, D = 4$ the best fitting line is $b = 4t - 5$

17. Given,

x	0	1	2	3
$f(x)$	1	0	1	2

Let, $f(x) = c + Dx$ be the best fitting line,

$$c + D(0) = 1, \quad c + D(1) = 0, \quad c + D(2) = 1, \quad c + D(3) = 2$$

$$c = 1, \quad c + D = 0, \quad c + 2D = 1, \quad c + 3D = 2$$

i.e., $Ax = b$

$$\begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 2 \end{bmatrix}$$

Consider, $A^T A \hat{x} = A^T b$

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 4 & 6 \\ 6 & 14 \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} 4 \\ 8 \end{bmatrix}$$

$$R_2 \rightarrow R_2 - \left(\frac{3}{2}\right) R_1$$

$$\begin{bmatrix} 4 & 6 \\ 0 & 5 \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} 4 \\ 8 \end{bmatrix}$$

$$4C + 6D = 4, \quad 5D = 8$$

$$4C + 6\left(\frac{8}{5}\right) = 4 \quad D = \frac{8}{5}$$

$$C + 6\left(\frac{2}{5}\right) = 1$$

$$C = 1 - \frac{12}{5}$$

$$C = -\frac{7}{5}$$

The best fitting line is $-\frac{7}{5} + \frac{8}{5}x = b$
 $-7 + 8x = 5b$

g12

W^1 is a line through the point $(1,1,1)$

Find the matrix P that projects onto this line

$$P = A(A^T A)^{-1} A^T$$

where $A = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

$$A^T A = [1 \ 1 \ 1] \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = 3$$

$$(A^T A)^{-1} = \frac{1}{3}$$

$$A(A^T A)^{-1} A^T = \frac{1}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} [1 \ 1 \ 1]$$

$$= \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

The matrix, that projects onto W is $(I - P)$.

$$\text{proj}_W = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - \begin{bmatrix} 1/3 & 1/3 & 1/3 \\ 1/3 & 1/3 & 1/3 \\ 1/3 & 1/3 & 1/3 \end{bmatrix} = \begin{bmatrix} 2/3 & -1/3 & -1/3 \\ -1/3 & 2/3 & -1/3 \\ -1/3 & -1/3 & 2/3 \end{bmatrix}$$

$$\therefore \text{proj}_W(y) = \frac{1}{3} \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$$

g18.

if $v \in V$

then $v = c(1,1)$

if $w \in W$

then $w = c(1,2)$

$$\therefore c_1(1,1) + c_2(1,2) = (2,-1)$$

we get the equations:

$$c_1 + c_2 = 2$$

$$c_1 + 2c_2 = -1$$

We get, $c_1 = 5$ and $c_2 = -3$.

$$\therefore v = 5(1,1) = (5,5)$$

$$w = -3(1,2) = (-3,-6)$$