

Vibhor Aggarwal

Master's Student, Automotive Engineering RWTH Aachen

24 February, 1996 (24 Years)

Bayernalle 7, Aachen, Germany

(+49)17659896222
vibhoraggarwal.github.io

vibhor.aggarwal@rwth-aachen.de

Matlab, Simulink

CAD(Solidworks, Autodesk Inventor)

5

ROS, YARP

FEA(Ansys, Abaqus)

y 0, 7 1.5 4 4 4 5

Gazebo

3

Languages* ————

6

Hindi

6

German

3.5

Italian

2

*Scale 1:Beginner to 6:Proficient

Projects' Photos & Videos -



Summary

Automotive engineer with experience in cutting edge research on robot and vehicle dynamics. Interested to work in the field of Advanced Driver Assistance Systems, Automated Driving, and Electromobility

Education

M.Sc, Automotive Engineering RWTH Aachen, Germany

B.Tech, Major: Mechanical Engineering

Minor: Applied Mathematics

Indian Institute of Technology Kanpur(IIT), India

Achievement and Awards

Best Under-Graduate project in Mechanical Engineering: IIT Kanpur 2017 Ranjan Kumar Memorial Award for best socially relevant project: IIT Kanpur 2017 Ranked 3rd in state and 914th nationally among 1.4 million students in JEE 2013 Gold Medal in National Mathematics Olympiad: AISMTA 2013

Experience

- Creating a C++ framework using inter-process-communication via UDP
- · Data acquisition and time synchronisation among IMU and GNSS sensors

Research Fellow, C++ Gazebo Simulink YARP ♥ Italy Nov 2017-Aug 2018 Guide: Dr. Daniele Pucci, DIC lab Research center for Human-Robot Collaboration Italian Institute of Technology, Genova, Italy

- Implemented low level torque control framework for Humanoid robot, iCub
- Identified transfer function between Voltage and iCub's joints' torque

Graduate Engineer Trainee MS Excel TPM Hero Motocorp Ltd, Haridwar, India

Sep 2018-Present

July 2013-June 2017

- Managed TPM for machine quality, process inspection and resource planning
- Produced machined parts by programming and setting up the CNC machine

- Designed suspension system of a material handling Automated Guided Vehicle
- Optimized assembly using Design for Manufacturing and Assembly techniques

Projects

Object perception for Automated Driving Nov 2019-Present Institute for Automotive Engineering, RWTH Aachen, Germany Mini-thesis

• Designing evaluation criteria for penalizing occlusions at urban intersections

Robotic Exoskeleton Arm CAD FEA Matlab

Guide: Dr. Sumit Basu, IIT Kanpur, India

Best Under graduate project at IIT Kanpur

Developed Pnematic Air Muscles (Proportional pressure pneumatics)

Off-road Vehicles CAD FEA Matlab Dec 2013-Jan 2016
Guide: Dr. Avinash Kumar Agarwal, IIT Kanpur For Event similar to FSAE & Baja SAE

Created/optimised mathematical models for multi link suspension systems

Additional Information

- Led the Motorsports team at IIT Kanpur, with more than 25 members.
- · Interested in Abstract expressionism, Philosophy, Psychology, Hiking