Quiz 1

NAME: SID:

The quiz lasts 1h30. Notes are *not* allowed, except for a one-page, two sided cheat sheet.

- 1. (a) Consider the trace function on a square matrix $X \in \mathbb{R}^{n,n}$, defined as the sum of the elements on the diagonal of X: trace $(X) = \sum_{i=1}^{n} X_{ii}$. Prove that:
 - i. $\operatorname{trace}(A) = \operatorname{trace}(A^{\top})$, for any square matrix A;
 - ii. trace(AB) = trace(BA), for any square matrices A, B;
 - iii. Prove that if a square matrix A is diagonalizable, then the trace of A equals the sum of all the eigenvalues of A (this fact actually holds for general A, but you are here asked to prove it only for the diagonalizable case).
 - (b) Consider the space $\mathbb{R}^{m,n}$ of $m \times n$ matrices as a vector space, endowed with the inner product $\langle A, B \rangle \doteq \operatorname{trace}(A^{\top}B)$, for any $A, B \in \mathbb{R}^{m,n}$. Prove that $\langle A, B \rangle \doteq \operatorname{trace}(A^{\top}B)$ is indeed an inner product on $\mathbb{R}^{m,n}$, that is, it satisfies the following three properties:
 - i. $\langle A, A \rangle \geq 0$ for all $A \in \mathbb{R}^{m,n}$, and $\langle A, A \rangle = 0$ if and only if A = 0;
 - ii. $\langle A, B + C \rangle = \langle A, B \rangle + \langle A, C \rangle;$
 - iii. $\langle \alpha A, B \rangle = \alpha \langle A, B \rangle;$
 - iv. $\langle A, B \rangle = \langle B, A \rangle$.

SOLUTION

- (a) (i) The diagonal elements of a matrix and its transpose are the same. Since the trace is the sum of the diagonal elements, A and A^{\top} have the same trace.
 - (ii) The *i*-th diagonal element of AB is $[AB]_{ii} = \sum_j a_{ij}b_{ji}$ and the *j*-th diagonal element of BA is $[BA]_{jj} = \sum_i b_{ji}a_{ij} = \sum_i a_{ij}b_{ji}$. Since the trace is the sum of the diagonal elements, we have that

$$\operatorname{trace}(AB) = \sum_{i} [AB]_{ii} = \sum_{i} \sum_{j} a_{ij} b_{ji} = \sum_{j} \sum_{i} a_{ij} b_{ji} = \operatorname{trace}(BA).$$

(iii) If A is diagonalizable, it can be factored as $A=P\Lambda P^{-1}$, where Λ is diagonal. From (ii) it follows that

$$\operatorname{trace}(A) = \operatorname{trace}(P\Lambda P^{-1}) = \operatorname{trace}(\Lambda P^{-1}P) = \operatorname{trace}(\Lambda) = \sum_{i} \lambda_{i}.$$

- (b) (i) Since the diagonal element of $A^{\top}A$ are the squared norms of the columns, they are nonnegative, whence $\langle A,A\rangle=\operatorname{trace}(A^{\top}A)=\sum_i\|a_i\|_2^2\geq 0$, and this quantity can be zero if and only if the norms of all columns of A are zero, which happens if and only if A is zero.
 - (ii) Follows from linearity of the trace.
 - (iii) Follows from linearity of the trace.
 - (iv) Follows from point (i) in part a).

2. We are given two sets of points in \mathbb{R}^n : $\mathcal{A} = \{a_1, \ldots, a_m\}$ and $\mathcal{B} = \{b_1, \ldots, b_m\}$, with $a_i, b_i \in \mathbb{R}^n$, $i = 1, \ldots, m$. Let $A \doteq [a_1 \cdots a_m] \in \mathbb{R}^{n,m}$ and $B \doteq [b_1 \cdots b_m] \in \mathbb{R}^{n,m}$. We know that the points in \mathcal{B} are related to the points in \mathcal{A} via an orthogonal map, plus noise, that is

$$b_i = Qa_i + \epsilon_i, \quad i = 1, \dots, m,$$

where ϵ_i are unknown noise terms, and $Q \in \mathbb{R}^{n,n}$ is an unknown orthogonal matrix.

We are interested in approximately "recovering" the unknown Q matrix from the data in A and B. More precisely, we seek an orthogonal matrix \hat{Q} that minimizes $||B-QA||_F^2$ over all orthogonal matrices Q, i.e., in solving

$$\hat{Q} = \arg\min_{\{Q: \ QQ^{\top} = I\}} \|B - QA\|_F^2.$$

- (a) Prove that $||YAX||_F^2 = ||A||_F^2 = \text{for any matrix } A \text{ and orthogonal matrices } X, Y.$
- (b) Show that the optimal solution \hat{Q} can be expressed in terms of the Singular Value Decomposition (SVD) of the matrix $M = BA^{\top}$. Find this solution explicitly in terms of the SVD factors of $BA^{\top} = U\Sigma V^{\top}$.

SOLUTION

(a) Since X, Y are orthogonal, we have that $Y^{\top}Y = I$ and $XX^{\top} = I$, and by the commutativity property of the trace we obtain that

$$||YAX||_F^2 = \operatorname{trace}(X^\top A^\top Y^\top Y A X) = \operatorname{trace}(X^\top A^\top A X) = \operatorname{trace}(A^\top A X X^\top)$$
$$= \operatorname{trace}(A^\top A) = ||A||_F^2.$$

(b) Let $M \doteq BA^{\top} = U\Sigma V^{\top}$, with U, V orthogonal, and Σ such that $\Sigma\Sigma^{\top}$ is diagonal. Then,

$$\begin{split} \|B - QA\|_F^2 &= \operatorname{trace}(B - QA)^\top (B - QA) \\ &= \operatorname{trace} \left(B^\top B - B^\top QA - A^\top Q^\top B + A^\top Q^\top QA \right) \\ &= \|B\|_F^2 + \|A\|_F^2 - 2 \operatorname{trace} A^\top Q^\top B \\ &= \|B\|_F^2 + \|A\|_F^2 - 2 \operatorname{trace} Q^\top BA^\top = \|B\|_F^2 + \|A\|_F^2 - 2 \operatorname{trace} Q^\top M \\ &= \|B\|_F^2 + \|A\|_F^2 - 2 \operatorname{trace} Q^\top U \Sigma V^\top \\ &= \|B\|_F^2 + \|A\|_F^2 - 2 \operatorname{trace} V^\top Q^\top U \Sigma. \end{split}$$

Now, $\tilde{Q} \doteq V^{\top}Q^{\top}U$ is an orthogonal matrix, and $\tilde{Q}\Sigma$ is a matrix formed by the columns of \tilde{Q} multiplied by the diagonal elements in Σ (which are nonnegative). The trace of $\tilde{Q}\Sigma$ is thus maximized if we choose $\tilde{Q}=I$, whence

$$V^{\top}Q^{\top}U = I \quad \Rightarrow \quad Q = UV^{\top}.$$

3. Given the following three points in \mathbb{R}^5

$$x_{1} = \begin{bmatrix} 1 \\ 2 \\ 0 \\ 3 \\ 1 \end{bmatrix}, \ x_{2} = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}, \ x_{3} = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \\ 0 \end{bmatrix},$$

compute:

(a) the projections $\hat{x}_1, \hat{x}_2, \hat{x}_3$ of x_1, x_2, x_3 onto the line $\mathcal{L} \doteq \{x = \bar{x} + \gamma v, \gamma \in \mathbb{R}\},$ where

$$\bar{x} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \quad v = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix};$$

(b) the distances d_1, d_2, d_3 of the points x_1, x_2, x_3 from the hyperplane

$$\mathcal{H} \doteq \{x : \sum_{i=1}^{5} x_i = 0\}.$$

SOLUTION

(a) Let $u = v/\|v\|_2 = v/\sqrt(5)$. Using the formula on page 40 of the book, we obtain $\hat{x}_i = \bar{x} + u^\top (x_i - \bar{x})u, \quad i = 1, 2, 3.$

(b) Let **1** denote the vector of all ones. The hyperplane is defined by $\mathbf{1}^{\top}x = 0$, hence from eq. (2.6) in the book, we have

$$d_i = \frac{|\mathbf{1}^{\top} x_i|}{\|\mathbf{1}\|_2} = \frac{1}{\sqrt{5}} |\mathbf{1}^{\top} x_i|.$$

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