

# Optimization Models

EECS 127 / EECS 227AT

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# LECTURE 18

## Weak Duality

*Just as we have two eyes and two feet, duality is part of life.*

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Carlos Santana

# Outline

## 1 Weak duality

- Lagrangian
- Minimax inequality
- Weak duality
- Geometry

## 2 Examples

- Projection on the probability simplex
- Sum of  $k$  largest elements
- Dual of an LP

## 3 Take-aways

# Constrained optimization problem

Consider an optimization problem in standard form

$$\begin{aligned} p^* = \min_{x \in \mathbb{R}^n} \quad & f_0(x) \\ \text{subject to:} \quad & f_i(x) \leq 0, \quad i = 1, \dots, m, \\ & h_i(x) = 0, \quad i = 1, \dots, q, \end{aligned} \tag{1}$$

and let  $\mathcal{D}$  denote the domain of this problem, assumed to be nonempty.

We refer to the above problem as the *primal* problem.

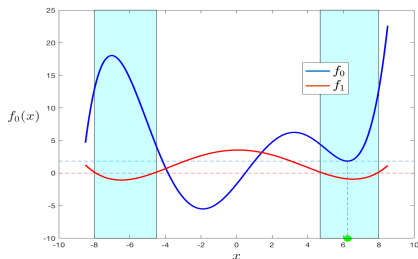
**Note:** we are *not* assuming convexity of  $f_0, f_1, \dots, f_m$  or of  $h_1, \dots, h_q$ , for the time being.

## A running example

To illustrate, we focus on a problem with a single inequality constraint, with  $f_0, f_1$  defined as

$$f_0(x) := \begin{cases} 0.0025x^5 - 0.00175x^4 - 0.212625x^3 \\ \quad + 0.3384375x^2 + 3.368x - 1.692 & -10 \leq x \leq 10, \\ +\infty & \text{otherwise,} \end{cases}$$

$$f_1(x) := 0.0025x^4 - 0.0005x^3 - 0.2129x^2 + 0.0320x + 3.5340.$$



A one-dimensional problem: minimize a fifth-order polynomial on the domain  $\mathcal{D} = [-10, 10]$ , with one quadratic inequality constraint that requires  $x$  to belong to the union of two intervals (indicated in light blue). The (unique) optimal point is shown in green on the  $x$ -axis.

# Lagrangian

Define a new function, called the *Lagrangian*, with values for  $x \in \mathbb{R}^n$ ,  $\lambda \in \mathbb{R}^m$  and  $\nu \in \mathbb{R}^q$ :

$$\mathcal{L}(x, \lambda, \nu) = f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{i=1}^q \nu_i h_i(x).$$

Vectors  $\lambda$  and  $\nu$  are referred to as *Lagrange multipliers*, or dual variables.

**Example:** for the previous problem, the Lagrangian is given by: for  $x \in \mathcal{D} = [-10, 10]$  and  $\lambda \in \mathbb{R}$ :

$$\mathcal{L}(x, \lambda) = f_0(x) + \lambda f_1(x) = \text{a polynomial of degree 5.}$$

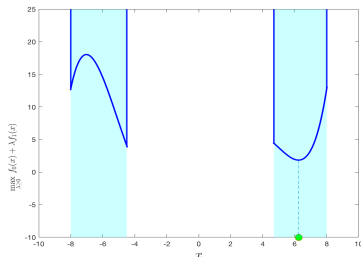
# Problem in min-max form

Thanks to the Lagrangian we may express the problem in “min-max” form:

$$p^* = \min_x \max_{\lambda \geq 0, \nu} \mathcal{L}(x, \lambda, \nu).$$

The above is due to the fact that, for any  $x$ ,

$$\max_{\lambda \geq 0, \nu} \mathcal{L}(x, \lambda, \nu) = \begin{cases} f_0(x) & \text{if } x \text{ is feasible,} \\ +\infty & \text{otherwise.} \end{cases}$$



We have encoded the problem as one without constraint, by re-defining the objective to be  $+\infty$  outside the feasible set. The minimizer of the function (green) is optimal for the original problem.

# Minimax inequality

For any sets  $X, Y$  and any function  $F : X \times Y \rightarrow \mathbb{R}$ :

$$\min_{x \in X} \max_{y \in Y} F(x, y) \geq \max_{y \in Y} \min_{x \in X} F(x, y).$$

**Proof:** for any  $(x_0, y_0) \in X \times Y$ :

$$h(y_0) \doteq \min_{x \in X} F(x, y_0) \leq F(x_0, y_0) \leq \max_{y \in Y} F(x_0, y) \doteq g(x_0).$$

Hence,  $h(y_0) \leq g(x_0)$ . Result follows from taking the max over  $y_0 \in Y$ , then the min over  $x_0 \in X$ .



## Interpretation as a game

Assume you play game against an opponent: given the payoff matrix below, you pick a row  $i \in \{1, \dots, 5\}$  and the opponent a column  $j \in \{1, \dots, 6\}$ . The payoff to you, the maximizing player, and cost to your opponent, the minimizing player, is  $M_{ij}$ , where  $M$  is the payoff matrix. Players play once, one after the other. The second player sees what the first does.

7	-8	-7	-8	3	5
9	-5	10	-2	-10	5
-8	1	10	9	7	-2
9	10	0	6	9	3
3	10	6	10	4	-7

Payoff matrix representing the payoff to the maximizing player. It is equal to the cost to the minimizing player. This is thus a “zero-sum” game.

**Question:** Do you prefer to play first, or second? What is your payoff in each case?

## Game interpretation (cont'd)

7	-8	-7	-8	3	5	-8
9	-5	10	-2	-10	5	-10
-8	1	10	9	7	-2	-8
<b>9</b>	<b>10</b>	<b>0</b>	<b>6</b>	<b>9</b>	<b>3</b>	<b>0</b>
3	10	6	10	4	-7	-7

If the maximizing player plays first, it will select a row (in **bold**) that maximizes the **worst-case (minimum) payoff** (in blue); the second player chooses the smallest element in that row. The payoff is

$$d^* = \max_i \min_j M_{ij} = 0.$$

7	-8	-7	-8	<b>5</b>	3
9	-5	10	-2	<b>5</b>	-10
-8	1	10	9	<b>-2</b>	7
9	10	0	6	<b>3</b>	9
3	10	6	10	<b>-7</b>	4
<b>9</b>	<b>10</b>	<b>10</b>	<b>9</b>	<b>5</b>	<b>3</b>

If the minimizing player plays first, it will select a column (in **bold**) that minimizes the **worst-case (maximum) cost** (in red); the second player accordingly chooses the largest element in that row. The payoff is

$$p^* = \min_j \max_i M_{ij} = 3.$$

It is always better to play **second** in this game, since the second player can adapt to the decision of the first; the first player must account for the worst-case.

# Weak duality

Applying the minimax inequality to the Lagrangian, we obtain:

$$p^* = \min_x \max_{\lambda \geq 0, \nu} \mathcal{L}(x, \lambda, \nu) \geq d^* \doteq \max_{\lambda \geq 0, \nu} \min_x \mathcal{L}(x, \lambda, \nu).$$

- The problem on the right is called the dual problem; it involves maximizing (over  $\lambda \geq 0, \nu$ ) the **dual function**:

$$g(\lambda, \nu) \doteq \min_x \mathcal{L}(x, \lambda, \nu).$$

- Since  $g$  is the pointwise minimum of affine (hence, concave) functions,  $g$  is concave.
- Hence the dual problem, a concave maximization problem over a convex set  $(\mathbb{R}_+^m \times \mathbb{R})$ , is convex!

# Geometry

## Making the problem 2D

Consider the problem, with variable  $x \in \mathbb{R}^n$ :

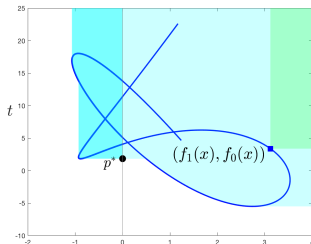
$$p^* = \min_x f_0(x) : f_1(x) \leq 0.$$

Define the 2D set of “achievable” values:

$$\mathcal{A} = \{(u, t) \in \mathbb{R}^2 : \exists x \in \mathbb{R}^n, u \geq f_1(x), t \geq f_0(x)\}.$$

We can visualize the problem as a 2D problem:

$$p^* = \min_{u,t} t : (u, t) \in \mathcal{A}, u \leq 0.$$



For our example: set  $\mathcal{A}$ , generated by plotting the set  $\{(f_1(x), f_0(x)) : x \in \mathbb{R}^n\}$ , including the NE quadrant (green) at each point. Feasible points correspond to where the curve intersects the set of pairs  $(u, t)$ , with  $u \leq 0$  (dark blue).

# Geometry

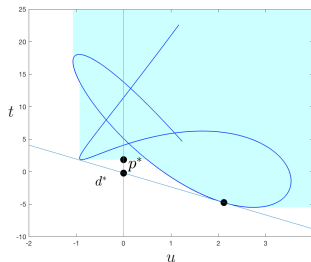
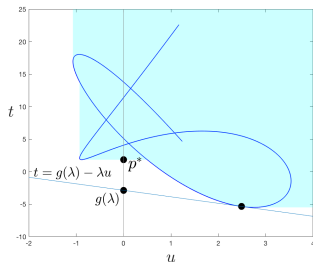
We have

$$p^* = \min_{(u,t) \in \mathcal{A}} \max_{\lambda \geq 0} t + \lambda u \geq d^* = \max_{\lambda \geq 0} g(\lambda),$$

where

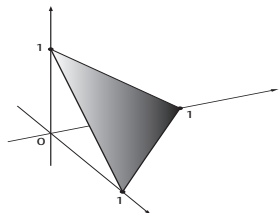
$$g(\lambda) = \min_x f_0(x) + \lambda f_1(x) = \min_{(u,t) \in \mathcal{A}} t + \lambda u.$$

For a given  $\lambda$ , the function  $g(\lambda)$  is a lower bound on  $p^*$ . The dual problem consists in finding the best such lower bound.



# Example

## Projection on the probability simplex



The probability simplex in  $\mathbb{R}^n$  is the set of discrete probabilities

$$\Delta^n \doteq \left\{ x \in \mathbb{R}^n : x \geq 0, \sum_{i=1}^n x_i = 1 \right\}.$$

The problem of projecting a given vector  $z \in \mathbb{R}^n$  onto the simplex arises in many contexts. The projection problem writes

$$\min_x \frac{1}{2} \|x - z\|_2^2 : x \geq 0, \sum_{i=1}^n x_i = 1.$$

# Projection on the probability simplex

Dual problem

Lagrangian:

$$\mathcal{L}(x, \nu) = \frac{1}{2} \|x - z\|_2^2 + \nu(1 - \mathbf{1}^\top x) \quad : \quad x \geq 0.$$

Dual function:

$$g(\nu) = \min_{x \geq 0} \mathcal{L}(x, \nu) = \frac{1}{2} z^\top z + \nu - \frac{1}{2} \sum_{i=1}^n \max(0, z_i + \nu)^2, \quad (2)$$

where we use the fact that, for a given  $\beta \in \mathbb{R}$ :

$$\min_{\xi \geq 0} \frac{1}{2} \xi^2 - \beta \xi = -\frac{1}{2} \max(0, \beta)^2.$$

The function  $g$  can be optimized by brute-force line search, or (faster) bisection methods.

By dualizing the equality constraint, we made the problem (2) easy (decoupled)!

# Projection on the probability simplex

## Strong duality

For every  $\nu \in \mathbb{R}$ , the solution to the problem

$$\min_{x \geq 0} \mathcal{L}(x, \nu)$$

is unique, and characterized by the zero-gradient condition  $\nabla_x \mathcal{L}(x, \nu) = 0$ , leading to

$$x_i^*(\nu) = \max(0, z_i + \nu), \quad i = 1, \dots, m.$$

In addition, the dual function  $g$  is smooth, and at its maximum its gradient is zero:

$$0 = \nabla_\nu g(\nu^*) = 1 - \sum_{i=1}^n \max(0, z_i + \nu^*) = 1 - \sum_{i=1}^n x_i^*(\nu^*),$$

which proves that the point  $x^*(\nu^*)$  is feasible for the primal problem.



# Projection on the probability simplex

## Strong duality

Further, after some algebra, exploiting  $\mathbf{1}^\top x^*(\nu^*) = 1$ , it can be shown that

$$\frac{1}{2} \|x^*(\nu^*) - z\|_2^2 = g(\nu^*) = d^*,$$

which proves that  $x^*(\nu^*)$  attains the dual lower bound, hence it is optimal, and “strong duality” holds, that is:

$$p^* = d^*.$$

This is an example where we are able to recover a primal feasible point from the dual and prove that strong duality holds, so that solving the dual solves the original problem. We will see later how to generalize this approach.

# Example

## Sum of $k$ largest elements

For given  $w \in \mathbb{R}^n$ , and  $k \in \{1, \dots, n-1\}$ , we define

$$s_k(w) = \sum_{i=1}^k w_{[i]},$$

where  $w_{[i]}$  is the  $i$ -th largest element in  $w$ .

The function  $s_k$  is convex, due to the pointwise maximum rule:

$$\begin{aligned} s_k(w) &= \max_{\mathcal{I}} \sum_{i \in \mathcal{I}} w_i : \mathcal{I} \subseteq \{1, \dots, n\}, \text{ Card } \mathcal{I} \leq k \\ &= \max_{u \in \{0,1\}^n} u^\top w : \mathbf{1}^\top u = k. \end{aligned}$$

# Weak and strong duality

By weak duality (third line):

$$\begin{aligned}s_k(w) &= \max_{u \in \{0,1\}^n} u^\top w : \mathbf{1}^\top u = k \\&= \max_{u \in \{0,1\}^n} \min_{\nu} u^\top w + \nu(k - \mathbf{1}^\top u) \\&\leq \min_{\nu} \max_{u \in \{0,1\}^n} u^\top w + \nu(k - \mathbf{1}^\top u) \\&= \min_{\nu} k\nu + \sum_{i=1}^n \max(0, w_i - \nu),\end{aligned}$$

exploiting in the last line that for any vector  $z$

$$\max_{u \in \{0,1\}^n} u^\top z = \sum_{i=1}^n \max(0, z_i).$$

We observe that if  $\nu$  is set to the  $(k+1)$ -th largest element in  $w$ , then we recover  $s_k(w)$ . Hence equality (strong duality) holds on the second line, and we obtained the dual form:

$$s_k(w) = \min_{\nu} k\nu + \sum_{i=1}^n \max(0, w_i - \nu).$$

# Application

## Diversification in resource allocation

Consider an asset allocation problem where  $w \geq 0$  is a vector containing the amount invested in the different assets:

$$\max_{w \in \mathcal{W}} r^\top w : w \geq 0, \quad s_k(w) \leq \theta \sum_{i=1}^n w_i,$$

where  $\theta \in [0, 1]$ , and

- $r \in \mathbb{R}^n$  contains the expected return on investment for each asset;
- The polytope  $\mathcal{W}$  encodes other constraints on  $w$  (such as, upper bound on its elements);
- The constraint on  $s_k(w)$  means that no more than a fraction  $\theta$  of the total budget  $\mathbf{1}^\top w$  is ascribed to the  $k$  largest investments.

The above problem is an LP, provided we are willing to express the constraint on  $s_k(w)$  as an **exponential** list of ordinary affine inequalities in  $w$ :

$$\forall \mathcal{I} \subseteq \{1, \dots, n\}, \quad \text{Card } \mathcal{I} \leq k : \sum_{i \in \mathcal{I}} w_i \leq \theta \sum_{i=1}^n w_i.$$

## Using the dual form

The previous naïve approach is not practical, as there are  $n$ -choose- $k$  constraints.

The constraint  $s_k(w) \leq \theta(\mathbf{1}^\top w)$  holds if and only if there exist  $\nu$  such that

$$k\nu + \sum_{i=1}^n \max(0, w_i - \nu) \leq \theta \sum_{i=1}^n w_i.$$

The above is a convex, perfectly manageable constraint. It can even be represented in linear inequality form, by introducing  $n$  slack variables

$$k\nu + \sum_{i=1}^n s_i \leq \theta \sum_{i=1}^n w_i, \quad s \geq 0, \quad s \geq w - \nu \mathbf{1}.$$

Thus, at the price of augmenting the number of variables, we avoided dealing with an exponential number of constraints.

**Geometrically:** the set corresponding to the constraint on  $s_k(w)$  is a polytope in  $\mathbb{R}^n$ , with  $2^n$  facets; it is the projection of another polytope in  $\mathbb{R}^{2n+1}$  that has  $2n+1$  facets only.

# Dual of a linear program

- Consider the following optimization problem with linear objective and linear inequality constraints (a so-called linear program in standard inequality form)

$$\begin{aligned} p^* = \min_x \quad & c^\top x \\ \text{s.t.:} \quad & Ax \leq b, \end{aligned} \tag{3}$$

where  $A \in \mathbb{R}^{m,n}$  is a matrix of coefficients, and the inequality  $Ax \leq b$  is to be intended elementwise.

- The Lagrangian for this problem is

$$\mathcal{L}(x, \lambda) = c^\top x + \lambda^\top (Ax - b) = (c + A^\top \lambda)^\top x - \lambda^\top b.$$

- In order to determine the dual function  $g(\lambda)$  we next need to minimize  $\mathcal{L}(x, \lambda)$  w.r.t.  $x$ . But  $\mathcal{L}(x, \lambda)$  is affine in  $x$ , hence this function is unbounded below, unless the vector coefficient of  $x$  is zero (i.e.,  $c + A^\top \lambda = 0$ ), and it is equal to  $-\lambda^\top b$  otherwise. That is,

$$g(\lambda) = \begin{cases} -\infty & \text{if } c + A^\top \lambda \neq 0 \\ -\lambda^\top b & \text{if } c + A^\top \lambda = 0. \end{cases}$$

# Dual of a linear program

- The dual problem then amounts to maximizing  $g(\lambda)$  over  $\lambda \geq 0$ :

$$\begin{aligned} d^* &= \max_{\lambda} && -\lambda^\top b \\ \text{s.t.:} &&& c + A^\top \lambda = 0, \\ &&& \lambda \geq 0. \end{aligned} \tag{4}$$

- From weak duality, we have that  $d^* \leq p^*$ .
- We may also rewrite the dual problem into an equivalent minimization form, by changing the sign of the objective, which results in

$$\begin{aligned} -d^* &= \min_{\lambda} && b^\top \lambda \\ \text{s.t.:} &&& A^\top \lambda + c = 0, \\ &&& \lambda \geq 0, \end{aligned}$$

and this is again an LP, in standard conic form.

# Take-aways

## Weak duality:

- We consider a non-convex minimization problem, and refer to it as the “primal” problem.
- Weak duality is a process by which we find a lower bound on the optimal value of the primal.
- It is based on expressing the primal problem in a min-max form, and applying the minimax inequality.
- The lower bound is the value of an optimization problem, referred to as the dual.
- The dual problem is a convex problem, even if the primal is not.

## Coming up next:

- can we make duality strong?
- How can we recover a primal point from the dual problem?
- What are applications of duality?