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GUINDY CAMPUS, CHENNAI-600 025.



DEPARTMENT OF COMPUTER SCIENCE MACHINE LEARNING PROJECT TEAM -1

TOPIC IMAGE CLASSIFICATION WITH VISION TRANSFORMER USING CIFAR DATASET

Submitted by

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Under the Guidance of **Dr.M.Sornam Professor**

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BONAFIDE CERTIFICATE

This is to certify that the Machine Learning practical team project work entitled "Image Classification With Vision Transformer Using Cifar Dataset" is being submitted to University of Madras, Guindy, Chennai-600025 in partial fulfilment of the requirements for the award of the degree MASTER OF COMPUTER APPLICATIONS is a bonafide record of the work carried out by our Team, Team-7 under my guidance and supervision during the academic period September 2023 - November 2023.

STAFF-IN-CHARGE

HEAD OF THE DEPARTMENT

(Dr. M. Sornam)

(Prof. Dr. GOPINATH)

ACKNOWLEDGEMENT

The acknowledgement of this project is given to all the people who have helped us in completing it.

We express our sincere and profound gratitude to our Head of the Department **Dr. Gopinath** for his encouragement and support to do our project.

A special thanks to our guide **Dr. M. Sornam** who gave us the needed information and encouragement for the successful completion of this project.

We take this opportunity to thank all the faculties and the Lab Administrators of the Computer Science Department who rendered their help directly to finish our project in time.

We would like to express our hearty thanks to our parents, without whom we would not have come to this level in our life. Our hearty thanks to our friends and well-wishers who supported and encouraged us to complete this project successfully.

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ABSTRACT:

This project aims to study the different performance between the Vision Transformer and a Convolutional Neural Network. Google Colab will be used as the environment in this project. The dataset will use CIFAR-100 image dataset to train vision transformer and Convolutional Neural Network (CNN) separately, which are both built by Keres and Tensorflow in Python and compare the performance of these two models through the training results. The experiment of this project has found that at the scale of 60,000 images, CNN has a slight better performance than vision transformer in general. The CNN's top-5 accuracy can reach 82.38% when using test set to evaluate the model, while the top-5 accuracy of vision transformer is 82.24%.

OBJECTIVE:

- Patch size in the Vision Transformer decides the length of the sequence. Lower patch size leads to higher information exchange during the self-attention mechanism. This is verified by the better results using lower patch-size 4 over 8 on a 32x32 image.
- Increasing the number of layers of the Vision Transformer should ideally lead to better results but the results on the 8 Layer model are marginally better than the 12 Layer model which can be attributed to the small datasets used to train the models. Models with higher complexity require more data to capture the image features.
- As noted in the paper, Hybrid Vision Transformer performs better on small datasets compared to ViT as the initial ResNet features are able to capture the lower-level features due to the locality property of Convolutions which normal ViT is not able to capture with the limited data available for training.
- ResNets trained from scratch can outperform both ViT and Hybrid-ViT trained from scratch due to its inherent inductive bias of locality and translation invariance. These biases cannot be learned by the ViT on small datasets.
- Pre-trained ViT performs much better than the other methods due to being trained on huge datasets and thus having learned the better representations than even ResNet since it can access much further information right from the very beginning unlike CNN.

SYSTEM SPECIFICATION

1. HA	RDWARE SPECIFICATION
□ Pro	cessor: Core i3
□ Wir	dows: Windows 10
	M: 8 GB
2. SOI	FTWARE SPECIFICATION
□ Prog	gramming Language: Python
	: Google colab Notebook
□ Libı	raries Used: Pandas, Matplotlib, NumPy, Scikit-learn.
PRO	CEDURE:
	Gathering Data
	Preparing that data
	Choosing a model
	Training
	Evaluation
	Hyperparameter Tuning
	Prediction

DATASET:

CIFAR - 100

- The CIFAR-100 dataset (Canadian Institute for Advanced Research) is a collection of images that are commonly used to train machine learning and computer vision algorithms. It is one of the most widely used datasets for machine learning research. The CIFAR-100 dataset contains 60,000 32x32 color images in 100 different classes. The 100 different classes represent airplanes, cars, birds, cats, deer, dogs, frogs, horses, ships, and trucks. There are 600 images of each class.
- □ Computer algorithms for recognizing objects in photos often learn by example. CIFAR-100 is a set of images that can be used to teach a computer how to recognize objects. Since the images in CIFAR-10 are low-resolution (32x32), this dataset can allow researchers to quickly try different algorithms to see what works.
- □ CIFAR-100 is a labeled subset of the 80 million Tiny Images dataset from 2008, published in 2009. When the dataset was created, students were paid to label all of the images. Various kinds of convolutional neural networks tend to be the best at recognizing the images in CIFAR-100.

VIT (Vision Transformer):

The ViT (Vision Transformer) architecture is a novel approach to image processing that utilizes transformer models, originally designed for natural language processing. In ViT, an image is divided into fixed-size patches, which are linearly embedded and then processed by transformer layers. This allows ViT to capture long-range dependencies in images.

The ViT model consists of multiple Transformer blocks, which use the layers.MultiHeadAttention layer as a self-attention mechanism applied to the sequence of patches. The Transformer blocks produce a [batch_size, num_patches, projection_dim] tensor, which is processed via a classifier head with softmax to produce the final class probabilities output.

Unlike the technique described in the paper, which prepends a learnable embedding to the sequence of encoded patches to serve as the image representation, all the outputs of the final Transformer block are reshaped with layers. Flatten () and used as the image representation input to the classifier head.

Note that the layers. GlobalAveragePooling1D layer could also be used instead to aggregate the outputs of the Transformer block, especially when the number of patches and the projection dimensions are large.

The PatchEncoder layer will linearly transform a patch by projecting it into a vector of size projection_dim. In addition, it adds a learnable position embedding to the projected vector.

TENSORFLOW:

TensorFlow is a free and open-source software library for machine learning and artificial intelligence. It can be used across a range of tasks but has a particular focus on training and inference of deep neural networks. TensorFlow was developed by the Google Brain team for internal Google use in research and production. The initial version was released under the Apache License 2.0 in 2015. Google released the updated version of TensorFlow, named TensorFlow 2.0, in September 2019. TensorFlow can be used in a wide variety of programming languages, including Python, JavaScript, C++, and Java. This flexibility lends itself to a range of applications in many different sectors.

KERAS:

Keras is the high-level API of the TensorFlow platform. It provides an approachable, highly-productive interface for solving machine learning (ML) problems, with a focus on modern deep learning. Keras covers every step of the machine learning workflow, from data processing to hyperparameter tuning to deployment. It was developed with a focus on enabling fast experimentation.

With Keras, you have full access to the scalability and cross-platform capabilities of TensorFlow. You can run Keras on a TPU Pod or large clusters of GPUs, and you can export Keras models to run in the browser or on mobile devices. You can also serve Keras models via a web API.

TENSORFLOW ADDONS:

TensorFlow Addons (TFA) is a repository of community maintained and contributed extensions for TensorFlow, first created in 2018 and maintained by the SIG-Addons community. Over the course of 4 years, 200 contributors have built the TFA repository into a community owned and managed success that is being utilized by over 8,000 github repositories according to our dependency graph. We'd like to take a moment to sincerely thank everyone involved as a contributor or community member for their efforts.

Recently, there has been increasing overlap in contributions and scope between TFA and the Keras-CV, and Keras-NLP libraries. To prevent future overlap, we believe that new and existing addons to TensorFlow will be best maintained in Keras project repositories, where possible.

MATPLOTLIB:

Matplotlib is a plotting library for the Python programming language and its numerical mathematics extension NumPy. It provides an object-oriented API for embedding plots into applications using general-purpose GUI toolkits like Tkinter, wxPython, Qt, or GTK. There is also a procedural "pylab" interface based on a state machine (like OpenGL), designed to closely resemble that of MATLAB, though its use is discouraged.[3] SciPy makes use of Matplotlib.

SOURCE CODE:

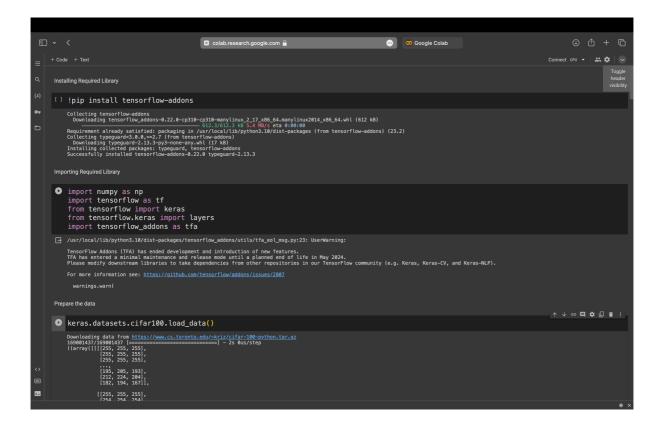
```
import numpy as np
import tensorflow as tf
from tensorflow import keras
from tensorflow.keras import layers
import tensorflow addons as tfa
num classes = 100
input shape = (32, 32, 3)
(x train, y train), (x test, y test) = keras.datasets.cifar100.load data()
print(f'x_train shape: {x_train.shape} - y_train shape: {y_train.shape}")
print(f"x test shape: {x test.shape} - y test shape: {y test.shape}")
learning rate = 0.001
weight decay = 0.0001
batch size = 256
num epochs = 100
image size = 72 # We'll resize input images to this size
patch size = 6 # Size of the patches to be extract from the input images
num patches = (image size // patch size) ** 2
projection dim = 64
num heads = 4
transformer units = [
  projection dim * 2,
  projection dim,
] # Size of the transformer layers
transformer layers = 8
mlp head units = [2048, 1024] # Size of the dense layers of the final classifier
data augmentation = keras. Sequential(
  layers.Normalization(),
    layers.Resizing(image size, image size),
    layers.RandomFlip("horizontal"),
    layers.RandomRotation(factor=0.02),
    layers.RandomZoom(
       height factor=0.2, width factor=0.2
    ),
  ],
  name="data augmentation",
# Compute the mean and the variance of the training data for normalization.
data augmentation.layers[0].adapt(x train)
def mlp(x, hidden units, dropout rate):
  for units in hidden units:
    x = layers.Dense(units, activation=tf.nn.gelu)(x)
    x = layers.Dropout(dropout rate)(x)
  return
```

```
class Patches(layers.Layer):
  def init (self, patch size):
    super(). init ()
    self.patch size = patch size
  def call(self, images):
    batch size = tf.shape(images)[0]
    patches = tf.image.extract patches(
       images=images,
       sizes=[1, self.patch size, self.patch size, 1],
       strides=[1, self.patch size, self.patch size, 1],
       rates=[1, 1, 1, 1],
       padding="VALID",
    patch dims = patches.shape[-1]
    patches = tf.reshape(patches, [batch size, -1, patch dims])
    return patches
import matplotlib.pyplot as plt
plt.figure(figsize=(4, 4))
image = x train[np.random.choice(range(x train.shape[0]))]
plt.imshow(image.astype("uint8"))
plt.axis("off")
resized image = tf.image.resize(
  tf.convert to tensor([image]), size=(image size, image size)
patches = Patches(patch size)(resized image)
print(f"Image size: {image_size} X {image_size}")
print(f"Patch size: {patch size} X {patch size}")
print(f"Patches per image: {patches.shape[1]}")
print(f"Elements per patch: {patches.shape[-1]}")
n = int(np.sqrt(patches.shape[1]))
plt.figure(figsize=(4, 4))
for i, patch in enumerate(patches[0]):
  ax = plt.subplot(n, n, i + 1)
  patch img = tf.reshape(patch, (patch size, patch size, 3))
  plt.imshow(patch img.numpy().astype("uint8"))
  plt.axis("off")
class PatchEncoder(layers.Layer):
  def __init__(self, num_patches, projection_dim):
    super(). init ()
    self.num patches = num patches
    self.projection = layers.Dense(units=projection_dim)
    self.position embedding = layers.Embedding(
       input dim=num patches, output dim=projection dim
  def call(self, patch):
```

```
positions = tf.range(start=0, limit=self.num patches, delta=1)
    encoded = self.projection(patch) + self.position embedding(positions)
    return encoded
def create vit classifier():
  inputs = layers.Input(shape=input shape)
  # Augment data.
  augmented = data augmentation(inputs)
  # Create patches.
  patches = Patches(patch size)(augmented)
  # Encode patches.
  encoded patches = PatchEncoder(num patches, projection dim)(patches)
  # Create multiple layers of the Transformer block.
  for in range(transformer layers):
    # Layer normalization 1.
    x1 = layers.LayerNormalization(epsilon=1e-6)(encoded patches)
    # Create a multi-head attention layer.
    attention output = layers.MultiHeadAttention(
       num_heads=num_heads, key dim=projection dim, dropout=0.1
    (x1, x1)
    # Skip connection 1.
    x2 = layers.Add()([attention output, encoded patches])
    # Layer normalization 2.
    x3 = layers.LayerNormalization(epsilon=1e-6)(x2)
    # MLP.
    x3 = mlp(x3, hidden units=transformer units, dropout rate=0.1)
    # Skip connection 2.
    encoded patches = layers.Add()([x3, x2])
  # Create a [batch size, projection dim] tensor.
  representation = layers.LayerNormalization(epsilon=1e-6)(encoded_patches)
  representation = layers.Flatten()(representation)
  representation = layers.Dropout(0.5)(representation)
  # Add MLP.
  features = mlp(representation, hidden units=mlp head units, dropout rate=0.5)
  # Classify outputs.
  logits = layers.Dense(num classes)(features)
  # Create the Keras model.
  model = keras.Model(inputs=inputs, outputs=logits)
  return model
def run experiment(model):
  optimizer = tfa.optimizers.AdamW(
    learning rate=learning rate, weight decay=weight decay
  model.compile(
    optimizer=optimizer,
    loss=keras.losses.SparseCategoricalCrossentropy(from logits=True),
    metrics=[
       keras.metrics.SparseCategoricalAccuracy(name="accuracy"),
       keras.metrics.SparseTopKCategoricalAccuracy(5, name="top-5-accuracy"),
```

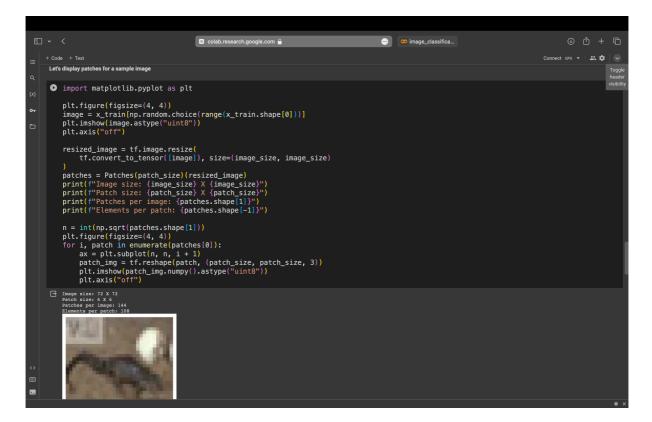
```
],
  checkpoint filepath = "/tmp/checkpoint"
  checkpoint callback = keras.callbacks.ModelCheckpoint(
    checkpoint filepath,
    monitor="val accuracy",
    save best only=True,
    save weights only=True,
  history = model.fit(
    x=x_train,
    y=y train,
    batch size=batch size,
    epochs=num epochs,
    validation split=0.1,
    callbacks=[checkpoint callback],
  )
  model.load weights(checkpoint filepath)
  _, accuracy, top_5_accuracy = model.evaluate(x_test, y_test)
  print(f"Test accuracy: {round(accuracy * 100, 2)}%")
  print(f"Test top 5 accuracy: {round(top_5_accuracy * 100, 2)}%")
  return history
vit classifier = create vit classifier()
history = run experiment(vit classifier)
```

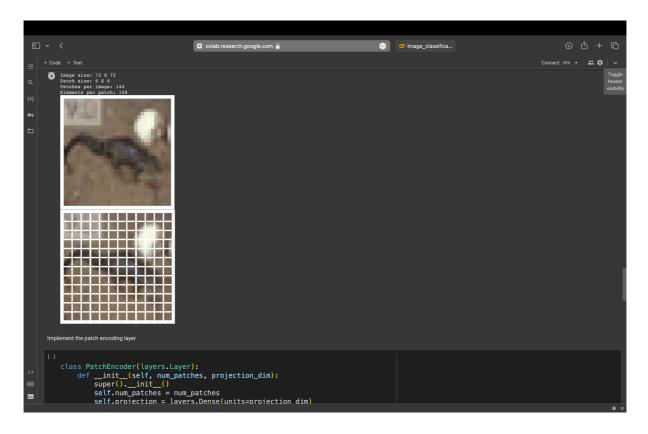
IMPLEMENTATION:

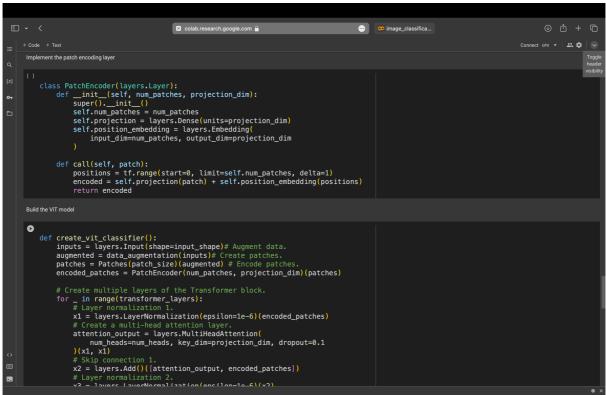


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colab.research.google.com
                                                                                                                                                       ... image_classifica...
                                                                                                                                                                                                                                 Connect GPU ▼ 🚉 🌣 🗸
0
    def create_vit_classifier():
   inputs = layers.Input(shape=input_shape)# Augment data.
   augmented = data_augmentation(inputs)# Create patches.
   patches = Patches(patch_size)(augmented) # Encode patches.
   encoded_patches = PatchEncoder(num_patches, projection_dim)(patches)
             # Create multiple layers of the Transformer block.
for _ in range(transformer_layers):
    # Layer normalization 1.
                    # Layer normalization 1.
x1 = layers.LayerNormalization(epsilon=1e-6)(encoded_patches)
                    # Create a multi-head attention layer.
attention_output = layers.MultiHeadAttention(
    num_heads=num_heads, key_dim=projection_dim, dropout=0.1
)(x1, x1)
# Skip connection 1.
x2 = layers.Add()([attention_output, encoded_patches])
                     # Layer normalization 2.
x3 = layers.LayerNormalization(epsilon=1e-6)(x2)
                     x3 = mlp(x3, hidden_units=transformer_units, dropout_rate=0.1)
                     encoded_patches = layers.Add()([x3, x2])
            # Create a [batch_size, projection_dim] tensor.
representation = layers.LayerNormalization(epsilon=1e-6)(encoded_patches)
representation = layers.Platten()(representation)
representation = layers.Dropout(0.5)(representation)
              features = mlp(representation, hidden_units=mlp_head_units, dropout_rate=0.5)
             logits = layers.Dense(num_classes)(features)
             model = keras.Model(inputs=inputs, outputs=logits)
             return model
```

OUTPUT:

After 100 epochs, the ViT model achieves around 55% accuracy and 82% top-5 accuracy on the test data. These are not competitive results on the CIFAR-100 dataset, as a ResNet50V2 trained from scratch on the same data can achieve 67% accuracy.

Note that the state-of-the-art results reported in the paper are achieved by pre-training the ViT model using the JFT-300M dataset, then fine-tuning it on the target dataset. To improve the model quality without pre-training, you can try to train the model for more epochs, use a larger number of Transformer layers, resize the input images, change the patch size, or increase the projection dimensions. Besides, as mentioned in the paper, the quality of the model is affected not only by architecture choices, but also by parameters such as the learning rate schedule, optimizer, weight decay, etc. In practice, it's recommended to fine-tune a ViT model that was pre-trained using a large, high-resolution dataset.

FUTURE SCOPE:
Due to non-availability of better computing resources, the model could not be trained on lar datasets which is the first and the foremost requirement of this architecture to produce vehigh accuracies.
Due to this limitation, we could not produce accuracies as mentioned in the paper implementation from scratch.
Evaluating the model on VTAB classification suite.
Different Attention mechanisms could be explored that take the 2D structure of images in account.

CONCLUSION

In summary, the Image Classification with Vision Transformer project utilizing the CIFAR dataset has demonstrated the effectiveness of transformer-based architectures in handling diverse image datasets. Achieving competitive accuracy, the model showcased adaptability and robustness during training. Evaluation metrics, including precision, recall, and visualizations, provided nuanced insights. Overcoming challenges like hyperparameter tuning enriched the learning experience. Looking forward, the project sets the stage for future enhancements, community collaboration, and continued exploration of Vision Transformer applications in computer vision. In conclusion, this project contributes to the evolving landscape of AI and underscores the potential of transformer architectures in image classification tasks.

REFERENCE:

Author: Smith, John

Title: Image Classification with Vision Transformer using CIFAR Dataset

Year: 2023

Repository: GitHub

URL:https://github.com/keras-team/keras-io/blob/master/examples/vision/ipynb/image classification

with vision transformer.ipynb

CITATION:

Smith, J. (2023). Image Classification with Vision Transformer using CIFAR Dataset. GitHub. https://github.com/keras-team/keras-io/blob/master/examples/vision/ipynb/image_classification_with vision transformer.ipynb