

# COL774 Assignment 4

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## Non competitive part

Here all times denote the training times in seconds, and all f-1 scores denote the macro f-1 score multiplied by 100

### a) **Vanilla neural network**

Learning rate: 0.1  
Batch size: 100  
SGD optimizer  
epsilon 1e-4  
max 100 epochs

Experimentation with hidden layer activation:

#### **Relu**

Time: 34.64810252189636  
Train f-1: 98.14087685598051  
Test f-1: 37.72851051012835

#### **Leaky relu**

Time: 34.34696388244629  
Train f-1: 94.35404968309084  
Test f-1: 36.583156746893685

#### **Sigmoid**

Time: 34.409926414489746  
Train f-1: 97.19654384940632  
Test f-1: 34.338805408298775

#### **Tanh**

Time: 34.564528942108154

Train f-1: 98.56884967633265

Test f-1: 33.695052358400076

Thus the relative performance of the model varies as  $Relu > Leaky\ relu > Sigmoid > Tanh$

b) **Feature engineering**

Learning rate: 0.1

Batch size: 100

SGD optimizer

epsilon 1e-4

max 100 epochs

ReLU activation in hidden layer

**Gabor**

Time: 35.21726655960083

Train f-1: 98.81549927093614

Test f-1: 35.35701516651953

**HOG**

Time: 34.72723412513733

Train f-1: 66.02495393559022

Test f-1: 42.40706955644302

HOG improves the performance on test set, while Gabor degrades the performance.

c) **CNN**

Learning rate: 0.1

Batch size: 100

SGD optimizer

epsilon 1e-4

max 100 epochs

Time: 42.0122652053833

Train f-1: 98.93396900293293

Test f-1: 38.20937725900574

CNN, being a bigger model, takes some more time to train and predict compared to the vanilla neural network, but also gives slightly better performance.

## Competitive part

We tried various models, including various variations of resnet, eigenfaces+svm, etc. Details of our best performing model are as follows:

- We used *resnext101\_32x8d* (imported from *torchvision.models*) as it gave the best performance relative to others. *pretrained* was set to True. The final FC layer was modified to accomodate 7 perceptrons in the output layer.
- We used SGD optimizer with learning rate 0.01. Batch size for training was set to 100
- We used data augmentation to increase training examples. For each example, we added a horizontally-flipped example to the train set. We also included the public test set for training in the final model.
- We also added rotation of images by 10 degrees to augment our dataset further.