PANIS Modelling:

```
570 K-E model
E- equation:
```

$$\frac{\partial}{\partial t}(\alpha P E) + \frac{\partial}{\partial n_i}(\alpha P U_i E)$$

$$= C_1 \propto f G \frac{\mathcal{E}}{k}$$

$$= \left(\frac{2}{3}C_{1}-C_{3}\right) \mathcal{L} \left(\frac{2}{3}C_{1}\right) \mathcal{L} \left(\frac{2}{3}C_{$$

$$-\left(C_{2} \propto f \frac{\varepsilon}{k}\right) \varepsilon$$

```
tmp<fvScalarMatrix> epsEqn
   (
        fvm::ddt(alpha, rho, epsilon_)
        + fvm::div(alphaRhoPhi, epsilon_)
        - fvm::laplacian(alpha*rho*DepsilonEff(), epsilon_)
        ==
        C1_*alpha()*rho()*G*epsilon_()/k_()
        - fvm::SuSp(((2.0/3.0)*C1_ - C3_)*alpha()*rho()*divU, epsilon_)
        - fvm::Sp(C2_*alpha()*rho()*epsilon_()/k_(), epsilon_)
        + epsilonSource()
        + fvOptions(alpha, rho, epsilon_)
);
```

```
DEMI TE + D
```

## KEpsilon . M

```
C1, C2 -> Model Constant

C=1 -> Sigle Phase

P=) Constant.
```

R- Equation

$$\frac{\partial (\alpha f k)}{\partial t} + \frac{\partial}{\partial n_i} (\alpha f u_i k) - \frac{\partial}{\partial n_k} (\alpha f D_{kll} \frac{\partial k}{\partial n_k})$$

$$= \alpha f G - \frac{\partial}{\partial \alpha} \alpha f \frac{\partial u_i}{\partial n_i} K$$

$$= \alpha f E + S_k + S_{pvok}$$

REpsilon. C

tmp<fvScalarMatrix> kEqn

(
fvm::ddt(alpha, rho, k\_)
+ fvm::div(alphaRhoPhi, k\_)
- fvm::laplacian(alpha\*rho\*DkEff(), k\_)

==
alpha()\*rho()\*G
- fvm::SuSp((2.0/3.0)\*alpha()\*rho()\*divU, k\_)
- fvm::Sp(alpha()\*rho()\*epsilon\_()/k\_(), k\_)
+ kSource()
+ fvOptions(alpha, rho, k\_)
);

tmp<volScalarField> DkEff() const
{
 return tmp<volScalarField>
 (
 new volScalarField
 (
 "DkEff",
 (this->nut\_/sigmak\_ + this->nu())
 )
 );
}

REpsilon.

G= production =

G= pro

KEPSILON.C

tmp<volTensorField> tgradU = fvc::grad(U);
 volScalarField::Internal G
 (
 this->GName(),
 nut.v()\*(dev(twoSymm(tgradU().v())) && tgradU().v())
);

$$-\langle v_{i}^{\dagger}v_{k}^{\dagger}\rangle = \Im t \left(\frac{\partial \overline{v}_{i}}{\partial n_{k}} + \frac{\partial \overline{v}_{k}}{\partial n_{i}}\right) - \frac{2}{3} k S_{ij} \frac{Boossines 2}{approximation}$$

$$G = \Im_{t} * \left[dev\left(\frac{\partial \overline{v}_{i}}{\partial n_{k}} + \frac{\partial \overline{v}_{k}}{\partial n_{i}}\right) \cdot \left(\frac{\partial \overline{v}_{i}}{\partial n_{k}}\right)\right]$$

$$dev(t) = t - \frac{1}{3} trace(t) * I$$