

## Neurocomputing

Linear classification

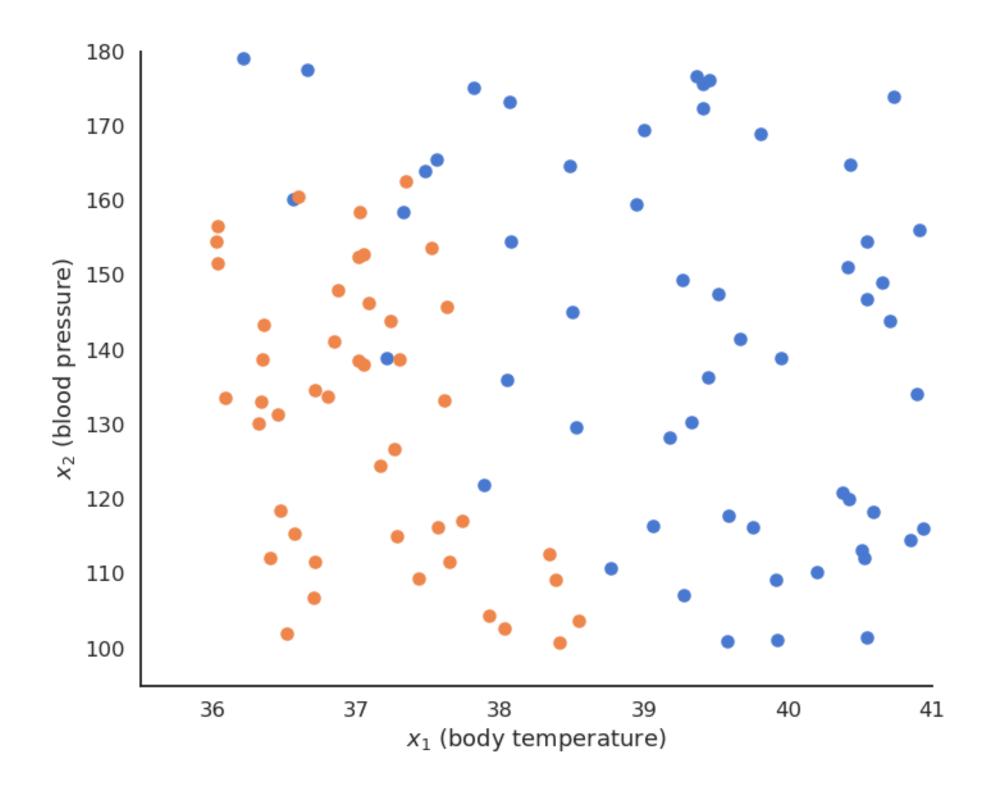
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1 - Hard linear classification

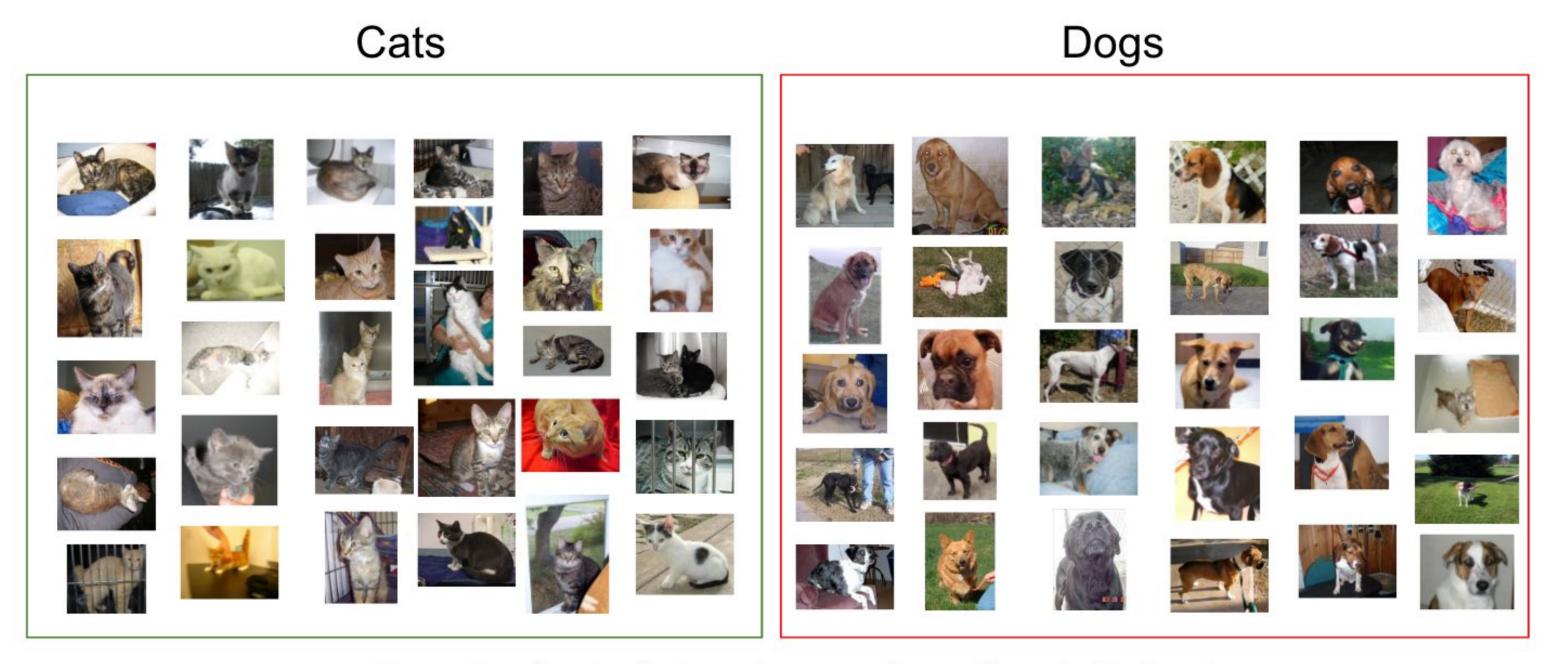
## **Binary classification**

- The training data  $\mathcal D$  is composed of N examples  $(\mathbf x_i,t_i)_{i=1..N}$  , with a d-dimensional input vector  $\mathbf x_i\in\Re^d$  and a binary output  $t_i\in\{-1,+1\}$
- The data points where  $t=\pm 1$  are called the **positive class**, the other the **negative class**.



### **Binary classification**

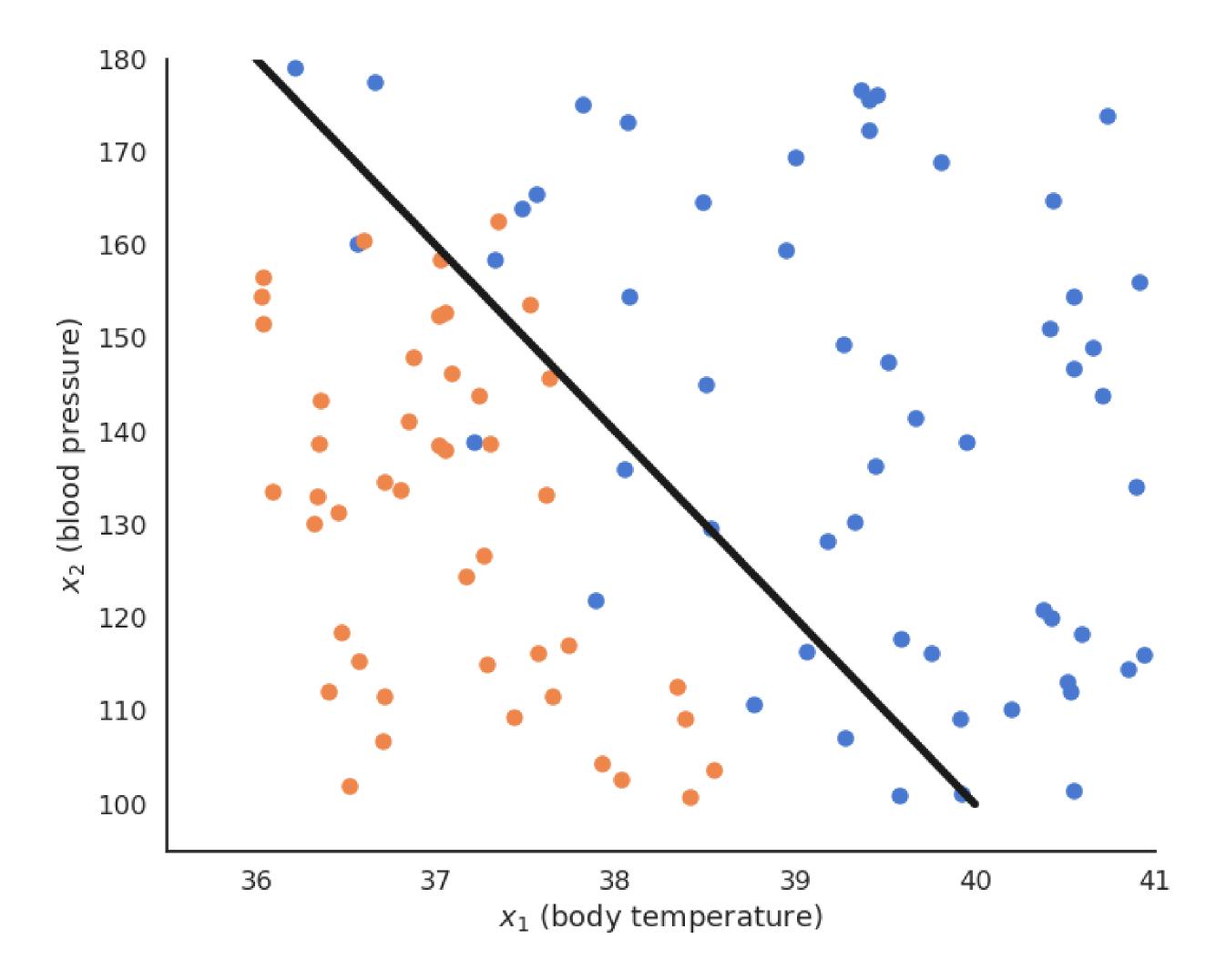
• For example, the inputs  $\mathbf{x}_i$  can be images (one dimension per pixel) and the positive class corresponds to cats  $(t_i=+1)$ , the negative class to dogs  $(t_i=-1)$ .



Sample of cats & dogs images from Kaggle Dataset

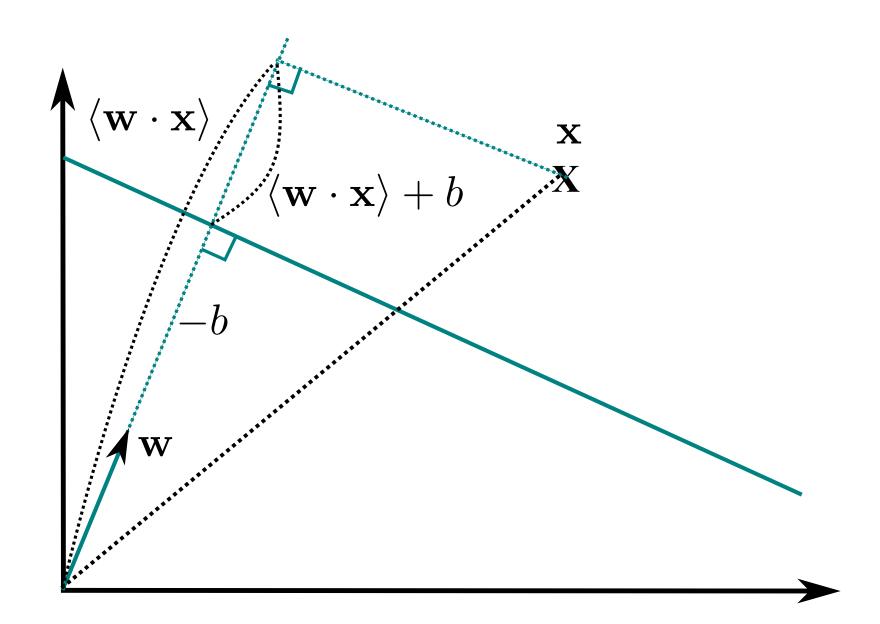
## **Binary linear classification**

ullet We want to find the hyperplane  $(\mathbf{w},b)$  of  $\Re^d$  that correctly separates the two classes.



### **Binary linear classification**

- For a point  $\mathbf{x} \in \mathcal{D}$ ,  $\langle \mathbf{w} \cdot \mathbf{x} \rangle + b$  is the projection of  $\mathbf{x}$  onto the hyperplane  $(\mathbf{w},b)$ .
  - If  $\langle \mathbf{w} \cdot \mathbf{x} \rangle + b > 0$ , the point is above the hyperplane.
  - If  $\langle \mathbf{w} \cdot \mathbf{x} \rangle + b < 0$ , the point is below the hyperplane.
  - If  $\langle \mathbf{w} \cdot \mathbf{x} \rangle + b = 0$ , the point is on the hyperplane.
- By looking at the **sign** of  $\langle {f w}\cdot {f x} \rangle + b$ , we can predict the class of the input:

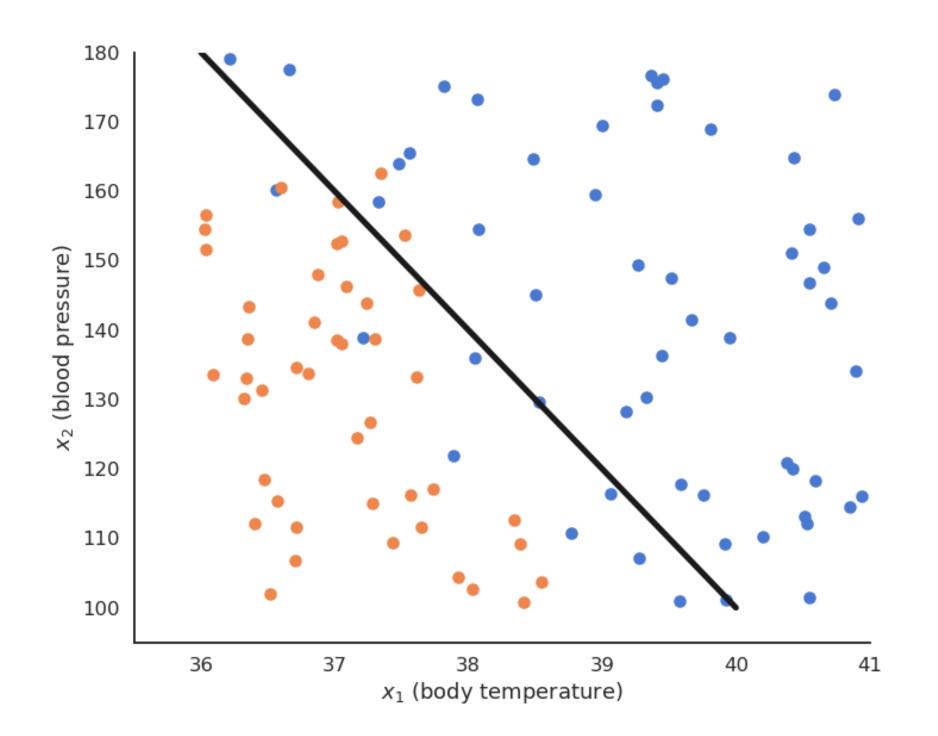


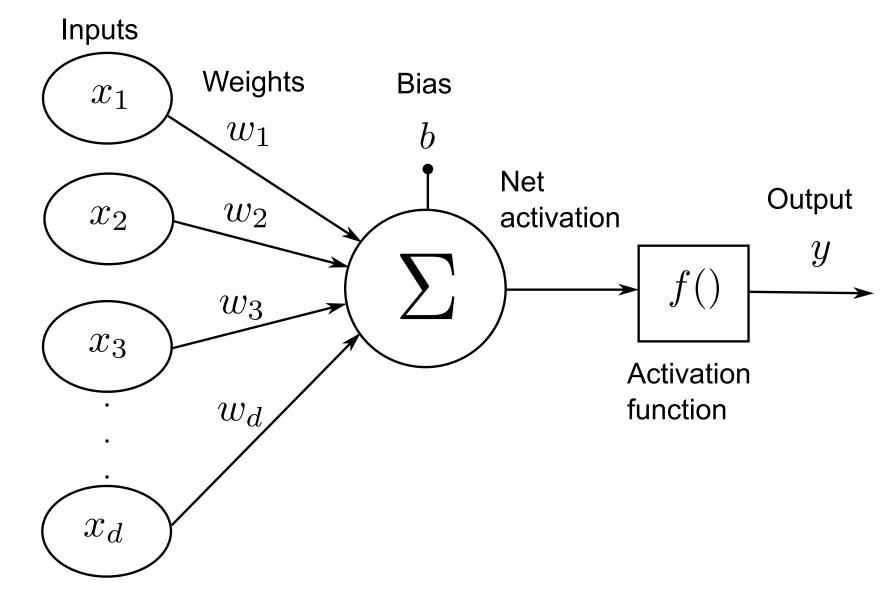
$$ext{sign}(\langle \mathbf{w} \cdot \mathbf{x} \rangle + b) = egin{cases} +1 & ext{if } \langle \mathbf{w} \cdot \mathbf{x} \rangle + b \geq 0 \ -1 & ext{if } \langle \mathbf{w} \cdot \mathbf{x} \rangle + b < 0 \end{cases}$$

### **Binary linear classification**

• Binary linear classification can be made by a single artificial neuron using the sign transfer function.

$$y = f_{\mathbf{w},b}(\mathbf{x}) = ext{sign}(\langle \mathbf{w} \cdot \mathbf{x} 
angle + b) = ext{sign}(\sum_{j=1}^d w_j \, x_j + b)$$

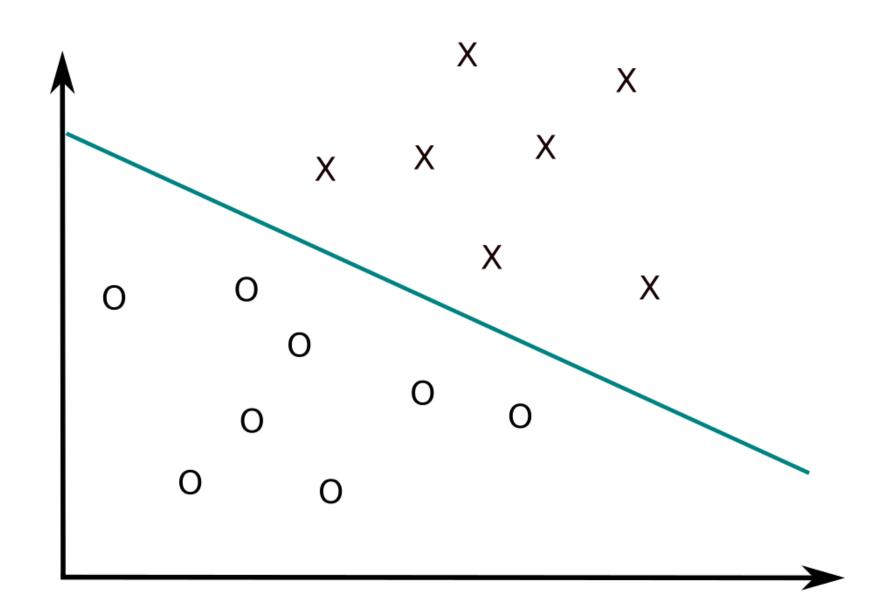




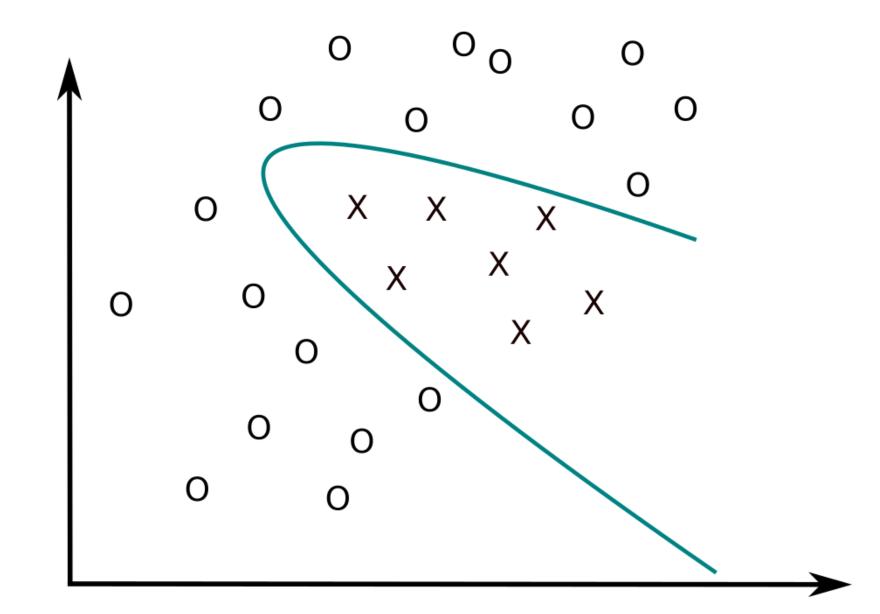
•  $\mathbf{w}$  is the weight vector and b is the bias.

#### **Linearly separable datasets**

#### **Linearly separable**



#### **Non-linearly separable**



- Linear classification is the process of finding an hyperplane  $(\mathbf{w},b)$  that correctly separates the two classes.
- If such an hyperplane can be found, the training set is said linearly separable.
- Otherwise, the problem is **non-linearly separable** and other methods have to be applied (MLP, SVM...).

#### Linear classification as an optimization problem

• The Perceptron algorithm tries to find the weights and biases minimizing the **mean square error** (*mse*) or **quadratic loss**:

$$\mathcal{L}(\mathbf{w},b) = \mathbb{E}_{\mathcal{D}}[(t_i-y_i)^2] pprox rac{1}{N} \sum_{i=1}^N (t_i-y_i)^2$$

- When the prediction  $y_i$  is the same as the data  $t_i$  for all examples in the training set (perfect classification), the mse is minimal and equal to 0.
- We can apply gradient descent to find this minimum.

$$egin{cases} \Delta \mathbf{w} = -\eta \, 
abla_{\mathbf{w}} \, \mathcal{L}(\mathbf{w}, b) \ \ \Delta b = -\eta \, 
abla_b \, \mathcal{L}(\mathbf{w}, b) \end{cases}$$

### Linear classification as an optimization problem

• Let's search for the partial derivative of the quadratic error function with respect to the weight vector:

$$abla_{\mathbf{w}} \, \mathcal{L}(\mathbf{w}, b) = 
abla_{\mathbf{w}} \, rac{1}{N} \, \sum_{i=1}^N (t_i - y_i)^2 = rac{1}{N} \, \sum_{i=1}^N 
abla_{\mathbf{w}} \, (t_i - y_i)^2 = rac{1}{N} \, \sum_{i=1}^N 
abla_{\mathbf{w}} \, l_i(\mathbf{w}, b)$$

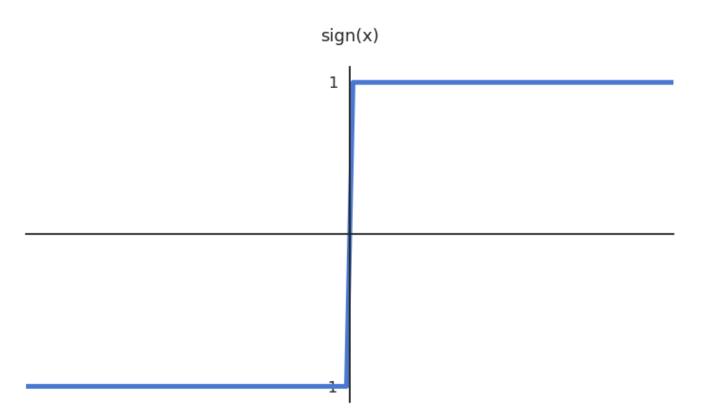
• Everything is similar to linear regression until we get:

$$abla_{\mathbf{w}} l_i(\mathbf{w}, b) = -2 \left( t_i - y_i \right) 
abla_{\mathbf{w}} \operatorname{sign}(\langle \mathbf{w} \cdot \mathbf{x}_i \rangle + b)$$

• In order to continue with the chain rule, we would need to differentiate  $\operatorname{sign}(x)$ .

$$abla_{\mathbf{w}} \ l_i(\mathbf{w}, b) = -2 \left( t_i - y_i 
ight) \mathrm{sign}'(\langle \mathbf{w} \cdot \mathbf{x}_i 
angle + b) \, \mathbf{x}_i$$

• But the sign function is **not** differentiable...



### Linear classification as an optimization problem

• We will simply pretend that the sign() function is linear, with a derivative of 1:

$$abla_{\mathbf{w}} \, l_i(\mathbf{w}, b) = -2 \left( t_i - y_i 
ight) \mathbf{x}_i$$

ullet The update rule for the weight vector  ${f w}$  and the bias b is therefore the same as in linear regression:

$$egin{cases} \Delta \mathbf{w} = \eta \, rac{1}{N} \, \sum_{i=1}^N (t_i - y_i) \, \mathbf{x}_i \ \Delta b = \eta \, rac{1}{N} \, \sum_{i=1}^N (t_i - y_i) \end{cases}$$

#### Batch version of linear classification

• By applying gradient descent on the quadratic error function, one obtains the following algorithm:

#### **Batch linear classification**

- ullet for M epochs:
  - $\mathbf{dw} = 0 \qquad db = 0$
  - for each sample  $(\mathbf{x}_i, t_i)$ :

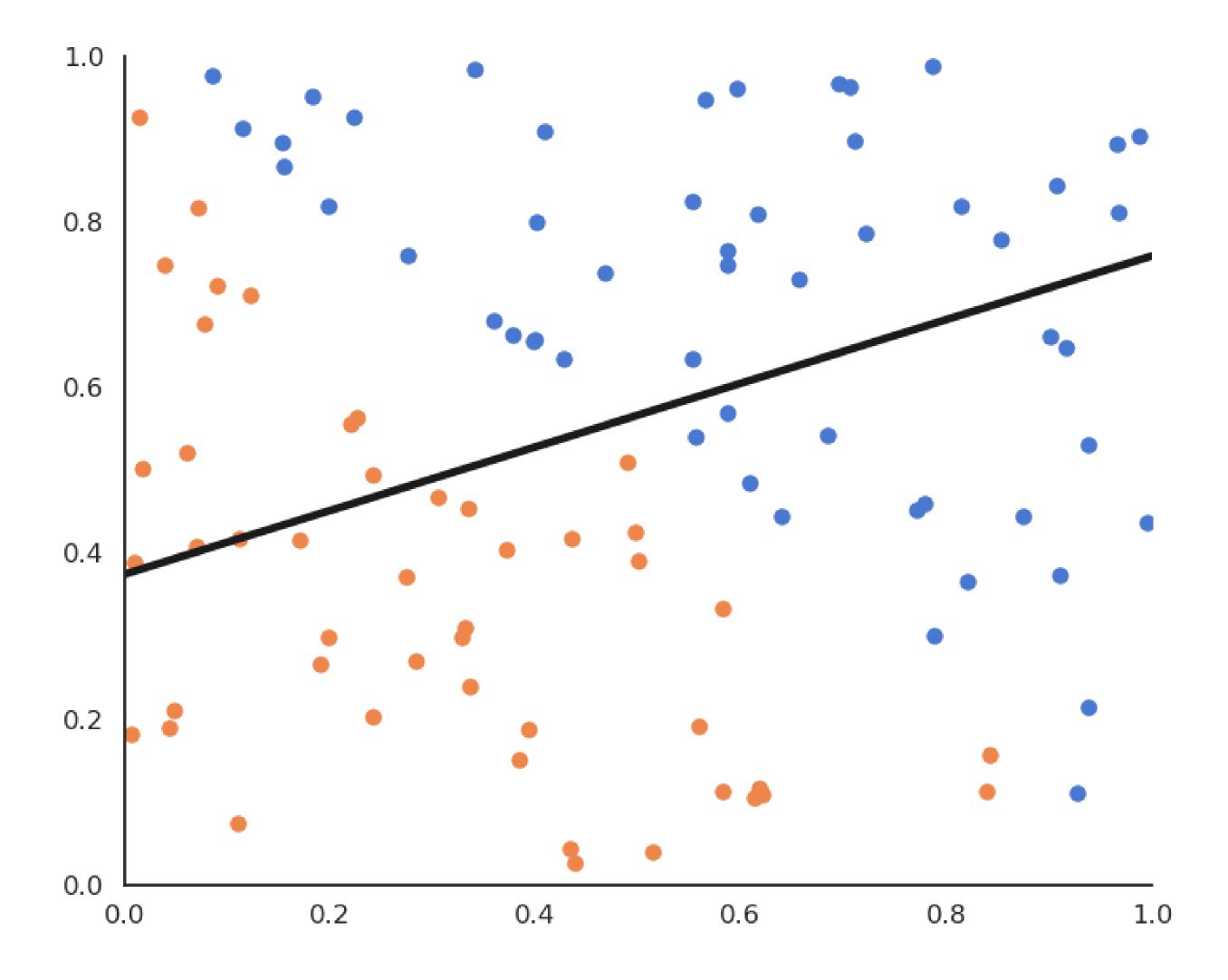
$$\circ \ y_i = \mathrm{sign}(\langle \mathbf{w} \cdot \mathbf{x}_i 
angle + b)$$

$$\mathbf{o} \ \mathbf{dw} = \mathbf{dw} + (t_i - y_i) \, \mathbf{x}_i$$

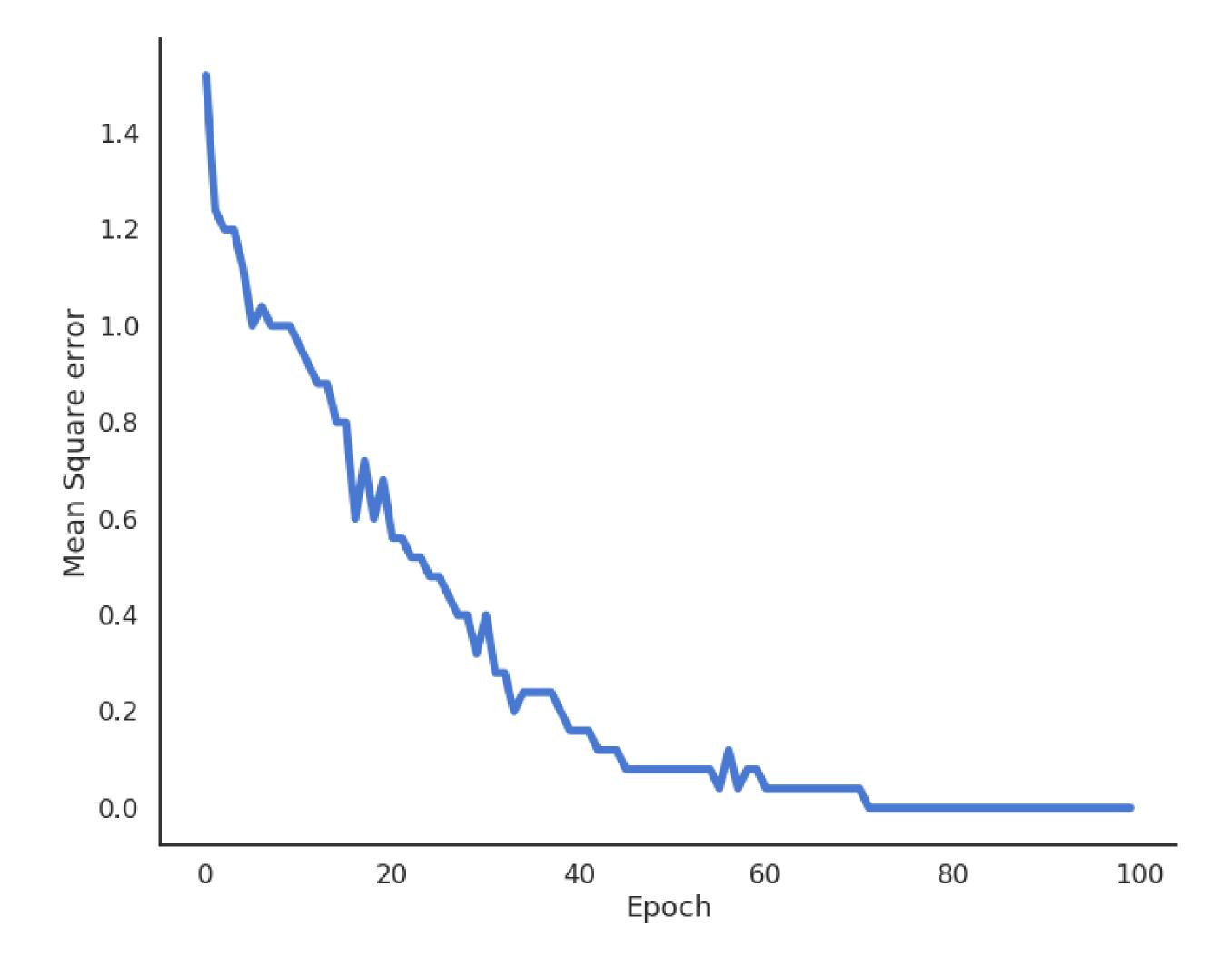
$$\circ \ db = db + (t_i - y_i)$$

- $ullet \Delta \mathbf{w} = \eta \, rac{1}{N} \, \mathbf{dw}$
- $lacksquare \Delta b = \eta \, rac{1}{N} \, db$
- This is called the **batch** version of the Perceptron algorithm.
- If the data is linearly separable and  $\eta$  is well chosen, it converges to the minimum of the mean square error.

## Linear classification: batch version



### Linear classification: batch version



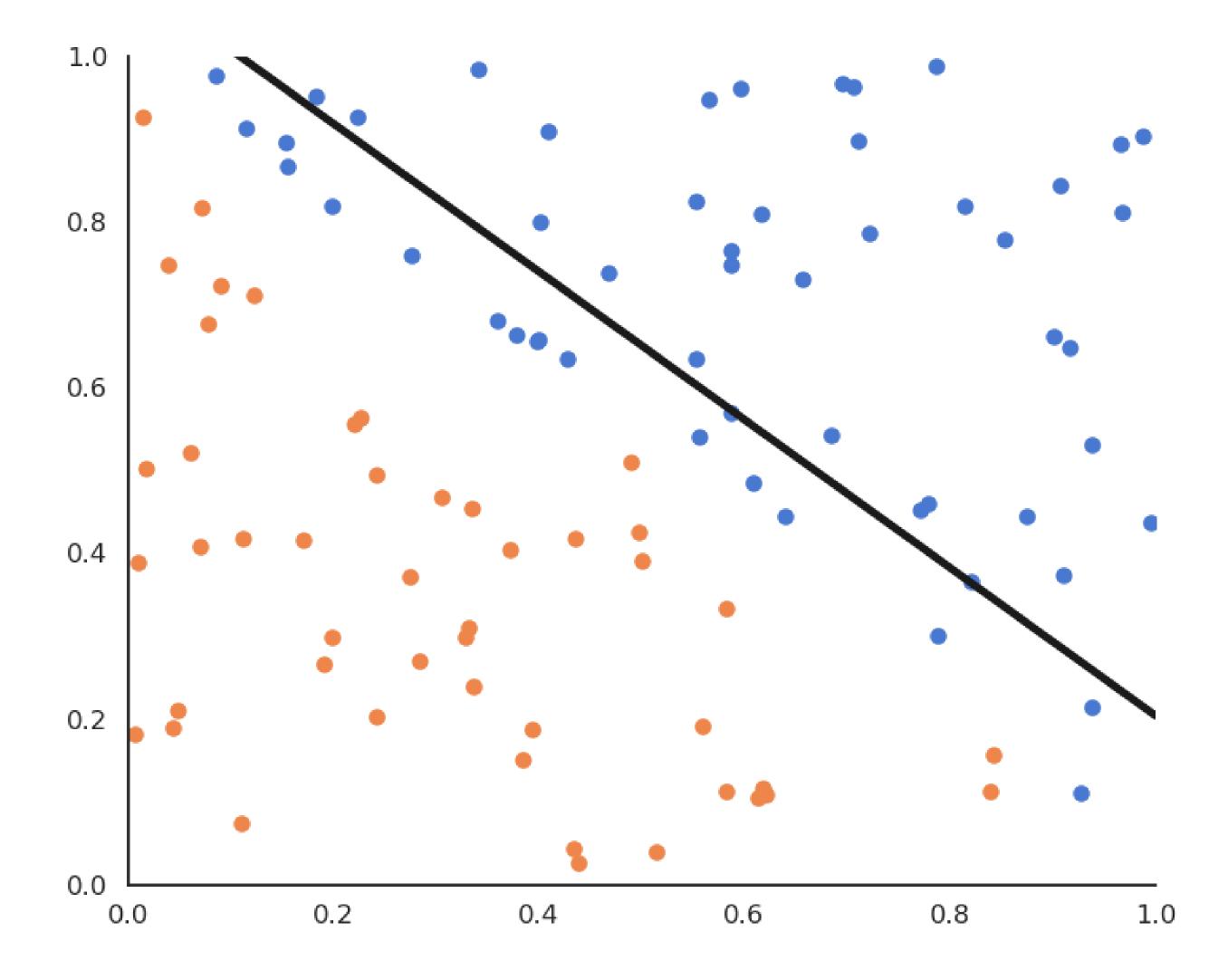
### Online version of linear classification: the Perceptron algorithm

• The **Perceptron algorithm** was invented by the psychologist Frank Rosenblatt in 1958. It was the first algorithmic neural network able to learn linear classification.

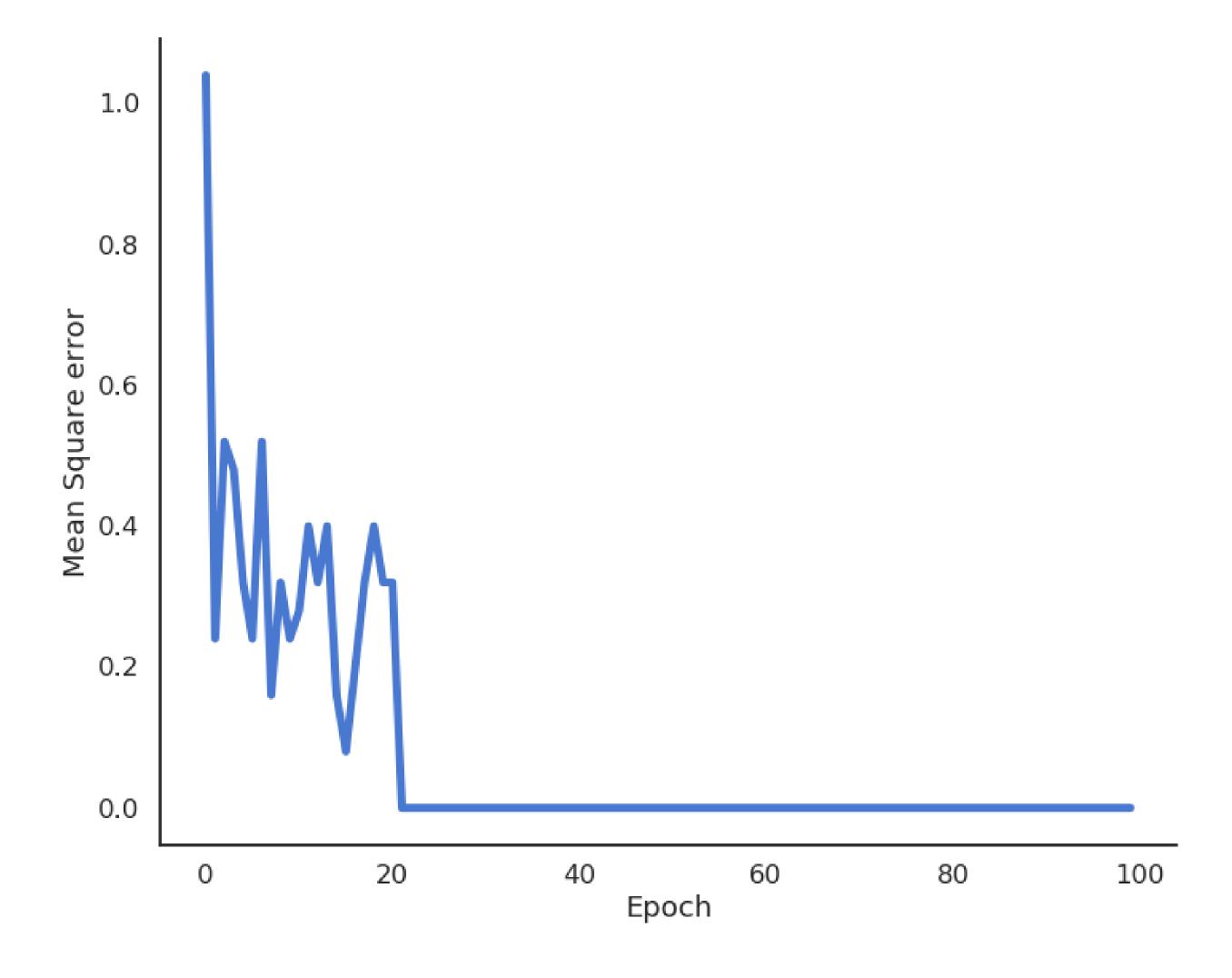
#### **Perceptron algorithm**

- $\bullet$  for M epochs:
  - for each sample  $(\mathbf{x}_i, t_i)$ :
    - $\circ \ y_i = \operatorname{sign}(\langle \mathbf{w} \cdot \mathbf{x}_i \rangle + b)$
    - $\circ \ \Delta \mathbf{w} = \eta \left( t_i y_i 
      ight) \mathbf{x}_i \, .$
    - $\circ \ \Delta b = \eta \left( t_i y_i 
      ight)$
- This algorithm iterates over all examples of the training set and applies the **delta learning rule** to each of them immediately, not at the end on the whole training set.
- One could check whether there are still classification errors on the training set at the end of each epoch and stop the algorithm.
- The delta learning rule depends on the learning rate  $\eta$ , the error made by the prediction  $(t_i y_i)$  and the input  $\mathbf{x}_i$ .

## Linear classification: online version



### Linear classification: online version



### Batch vs. Online learning

• The mean square error is defined as the **expectation** over the data:

$$\mathcal{L}(\mathbf{w},b) = \mathbb{E}_{\mathcal{D}}[(t_i-y_i)^2]$$

- **Batch learning** uses the whole training set as samples to estimate the mse:
- Online learning uses a single sample to estimate the mse:

$$\mathcal{L}(\mathbf{w},b)pprox rac{1}{N} \sum_{i=1}^{N} (t_i-y_i)^2$$

$$\Delta \mathbf{w} = \eta \, rac{1}{N} \sum_{i=1}^{N} (t_i - y_i) \, \mathbf{x_i}$$

 $\mathcal{L}(\mathbf{w},b)pprox (t_i-y_i)^2$ 

$$\Delta \mathbf{w} = \eta \left( t_i - y_i 
ight) \mathbf{x_i}$$

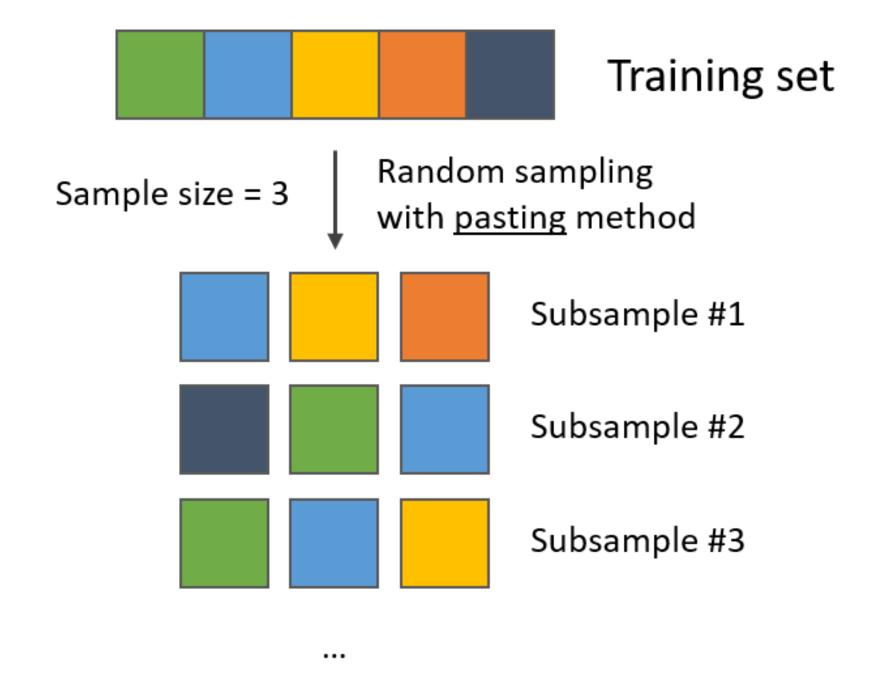
- Batch learning has less bias (central limit theorem) and is less sensible to noise in the data, but is very slow.
- Online learning converges faster, but can be instable and overfits (high variance).

#### **Stochastic Gradient Descent - SGD**

- In practice, we use a trade-off between batch and online learning called Stochastic Gradient Descent
  (SGD) or Minibatch Gradient Descent.
- The training set is randomly split at each epoch into small chunks of data (a **minibatch**, usually 32 or 64 examples) and the batch learning rule is applied on each chunk.

$$\Delta \mathbf{w} = \eta \, rac{1}{K} \sum_{i=1}^K (t_i - y_i) \, \mathbf{x_i}$$

- If the **batch size** is well chosen, SGD is as stable as batch learning and as fast as online learning.
- The minibatches are randomly selected at each epoch (i.i.d).

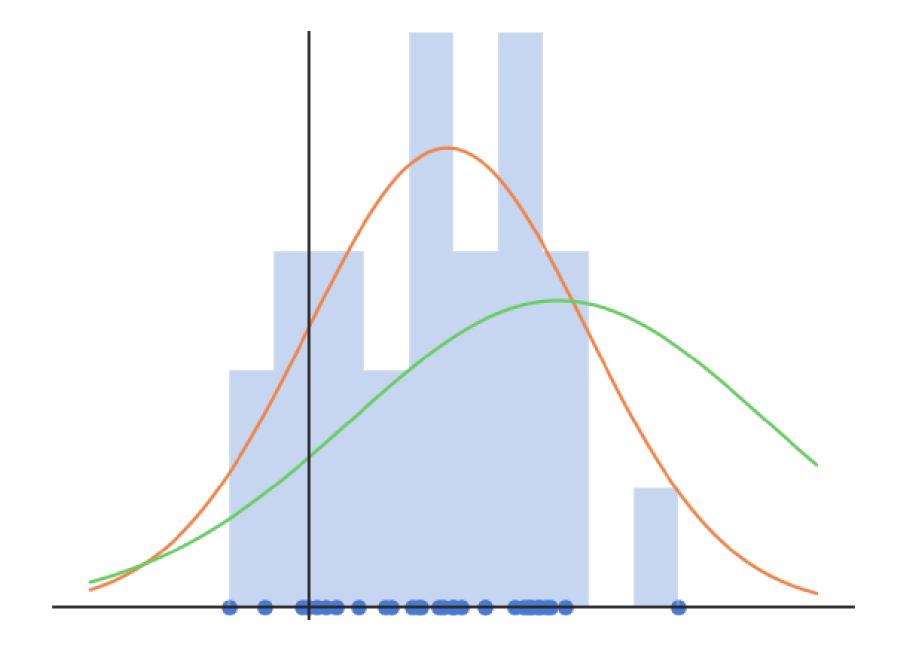


• Online learning is a stochastic gradient descent with a batch size of 1.

- Let's consider N samples  $\{x_i\}_{i=1}^N$  independently taken from a normal distribution X.
- The probability density function (pdf) of a normal distribution is:

$$f(x;\mu,\sigma) = rac{1}{\sqrt{2\pi\sigma^2}} \, \exp{-rac{(x-\mu)^2}{2\sigma^2}}$$

where  $\mu$  is the mean of the distribution and  $\sigma$  its standard deviation.

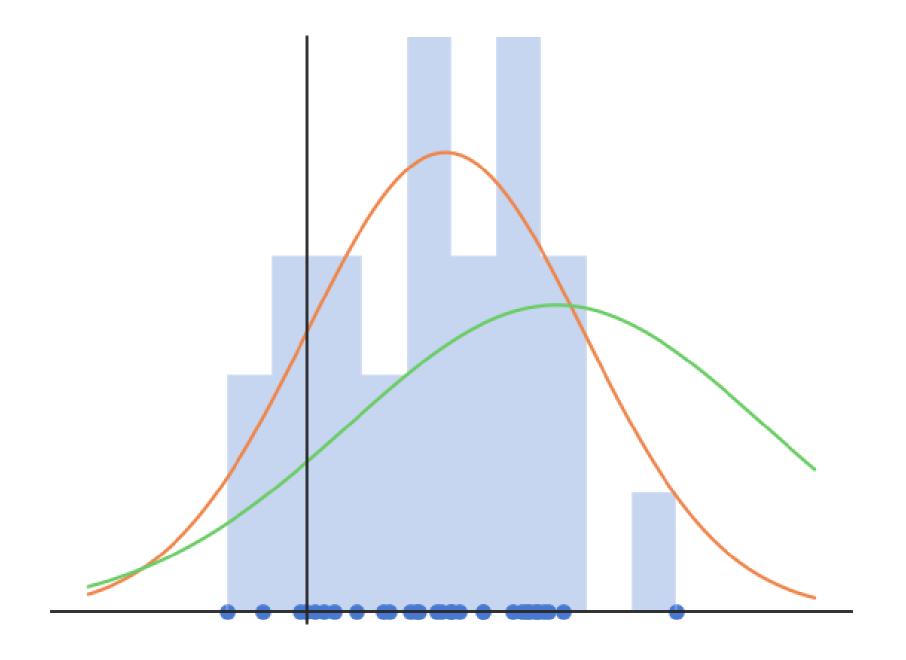


ullet The problem is to find the values of  $\mu$  and  $\sigma$  which explain best the observations  $\{x_i\}_{i=1}^N$ .

• The idea of MLE is to maximize the joint density function for all observations. This function is expressed by the **likelihood function**:

$$L(\mu,\sigma) = P(\mathbf{x};\mu,\sigma) = \prod_{i=1}^N f(x_i;\mu,\sigma)$$

 When the pdf takes high values for all samples, it is quite likely that the samples come from this particular distribution.



- ullet The likelihood function reflects how well the parameters  $\mu$  and  $\sigma$  explain the observations  $\{x_i\}_{i=1}^N$  .
- Note: the samples must be i.i.d. so that the likelihood is a product.

ullet We therefore search for the values  $\mu$  and  $\sigma$  which **maximize** the likelihood function.

$$\max_{\mu,\sigma} \ \ L(\mu,\sigma) = \prod_{i=1}^N f(x_i;\mu,\sigma)$$

For the normal distribution, the likelihood function is:

$$egin{aligned} L(\mu,\sigma) &= \prod_{i=1}^N f(x_i;\mu,\sigma) \ &= \prod_{i=1}^N rac{1}{\sqrt{2\pi\sigma^2}} \, \exp{-rac{(x_i-\mu)^2}{2\sigma^2}} \ &= (rac{1}{\sqrt{2\pi\sigma^2}})^N \, \prod_{i=1}^N \exp{-rac{(x_i-\mu)^2}{2\sigma^2}} \ &= (rac{1}{\sqrt{2\pi\sigma^2}})^N \, \exp{-rac{\sum_{i=1}^N (x_i-\mu)^2}{2\sigma^2}} \end{aligned}$$

ullet To find the maximum of  $L(\mu,\sigma)$ , we need to search where the gradient is equal to zero:

$$egin{cases} rac{\partial L(\mu,\sigma)}{\partial \mu} = 0 \ rac{\partial L(\mu,\sigma)}{\partial \sigma} = 0 \end{cases}$$

• The likelihood function is complex to differentiate, so we consider its logarithm  $l(\mu,\sigma)=\log(L(\mu,\sigma))$  which has a maximum for the same value of  $(\mu,\sigma)$  as the log function is monotonic.

$$egin{align} l(\mu,\sigma) &= \log(L(\mu,\sigma)) \ &= \log\left((rac{1}{\sqrt{2\pi\sigma^2}})^N\,\exp{-rac{\sum_{i=1}^N(x_i-\mu)^2}{2\sigma^2}}
ight) \ &= -rac{N}{2}\log(2\pi\sigma^2) - rac{\sum_{i=1}^N(x_i-\mu)^2}{2\sigma^2} \ \end{gathered}$$

•  $l(\mu,\sigma)$  is called the **log-likelihood** function.

$$l(\mu,\sigma) = -rac{N}{2}\log(2\pi\sigma^2) - rac{\sum_{i=1}^N(x_i-\mu)^2}{2\sigma^2}$$

The maximum of the log-likelihood function respects:

$$egin{align} rac{\partial l(\mu,\sigma)}{\partial \mu} &= rac{\sum_{i=1}^{N}(x_i-\mu)}{\sigma^2} = 0 \ rac{\partial l(\mu,\sigma)}{\partial \sigma} &= -rac{N}{2}rac{4\pi\sigma}{2\pi\sigma^2} + rac{\sum_{i=1}^{N}(x_i-\mu)^2}{\sigma^3} \ &= -rac{N}{\sigma} + rac{\sum_{i=1}^{N}(x_i-\mu)^2}{\sigma^3} = 0 \ \end{aligned}$$

We obtain:

$$\mu = rac{1}{N} \sum_{i=1}^N x_i \qquad \qquad \sigma^2 = rac{1}{N} \sum_{i=1}^N (x_i - \mu)^2$$

 Unsurprisingly, the mean and variance of the normal distribution which best explains the data are the mean and variance of the data...

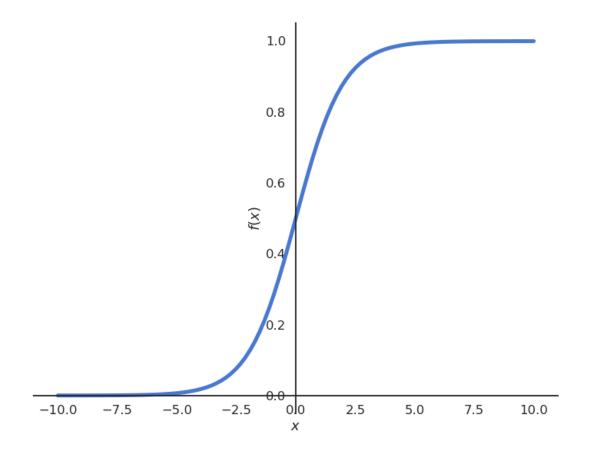
$$\mu = rac{1}{N} \sum_{i=1}^{N} x_i \qquad \qquad \sigma^2 = rac{1}{N} \sum_{i=1}^{N} (x_i - \mu)^2$$

- The same principle can be applied to estimate the parameters of any distribution: normal, exponential, Bernouilli, Poisson, etc...
- When a machine learning method has an probabilistic interpretation (i.e. it outputs probabilities), MLE can be used to find its parameters.
- One can use global optimization like here, or gradient descent to estimate the parameters iteratively.

3 - Soft linear classification : Logistic regression

### Reminder: Logistic regression

ullet We want to perform a regression, but where the targets  $t_i$  are bounded betwen 0 and 1.



• We can use a logistic function instead of a linear function in order to transform the net activation into an output:

$$y = \sigma(w x + b) = \frac{1}{1 + \exp(-w x - b)}$$

### Use of logistic regression for soft classification

• Logistic regression can be used in binary classification if we consider  $y = \sigma(w \, x + b)$  as the probability that the example belongs to the positive class (t = 1).

$$P(t = 1|x; w, b) = y;$$
  $P(t = 0|x; w, b) = 1 - y$ 

• The output t therefore comes from a Bernouilli distribution  $\mathcal{B}$  of parameter  $p=y=f_{w,b}(x)$ . The probability mass function (pmf) is:

$$f(t|x;w,b) = y^t \, (1-y)^{1-t}$$

- ullet If we consider our training samples  $(x_i,t_i)$  as independently taken from this distribution, our task is:
  - to find the parameterized distribution that best explains the data, which means:
  - to find the parameters w and b maximizing the **likelihood** that the samples t come from a Bernouilli distribution when x, w and b are given.
- We only need to apply Maximum Likelihood Estimation (MLE) on this Bernouilli distribution!

#### MLE for logistic regression

The likelihood function for logistic regression is :

$$egin{aligned} L(w,b) &= P(t|x;w,b) = \prod_{i=1}^N f(t_i|x_i;w,b) \ &= \prod_{i=1}^N y_i^{t_i} \ (1-y_i)^{1-t_i} \end{aligned}$$

The likelihood function is quite hard to differentiate, so we take the log-likelihood function:

$$egin{aligned} l(w,b) &= \log L(w,b) \ &= \sum_{i=1}^N [t_i \, \log y_i + (1-t_i) \, \log (1-y_i)] \end{aligned}$$

• or even better: the negative log-likelihood which will be minimized using gradient descent:

$$\mathcal{L}(w,b) = -\sum_{i=1}^{N} [t_i \, \log y_i + (1-t_i) \, \log (1-y_i)]$$

### MLE for logistic regression

 We then search for the minimum of the negative log-likelihood function by computing its gradient (here for a single sample):

$$egin{aligned} rac{\partial l_i(w,b)}{\partial w} &= -rac{\partial}{\partial w}[t_i\,\log y_i + (1-t_i)\,\log(1-y_i)] \ &= -t_i\,rac{\partial}{\partial w}\log y_i - (1-t_i)\,rac{\partial}{\partial w}\log(1-y_i) \ &= -t_i\,rac{rac{\partial}{\partial w}y_i}{y_i} - (1-t_i)\,rac{rac{\partial}{\partial w}(1-y_i)}{1-y_i} \ &= -t_i\,rac{y_i\,(1-y_i)\,x_i}{y_i} + (1-t_i)\,rac{y_i\,(1-y_i)\,x_i}{1-y_i} \ &= -(t_i-y_i)\,x_i \end{aligned}$$

• Same gradient as the linear perceptron, but with a non-linear output function!

### Logistic regression for soft classification

• Logistic regression is a regression method used for classification. It uses a non-linear transfer function  $\sigma(x)=rac{1}{1+\exp(-x)}$  applied on the net activation:

$$y_i = \sigma(\langle \mathbf{w} \cdot \mathbf{x}_i 
angle + b)$$

ullet The continuous output y is interpreted as the probability of belonging to the positive class.

$$P(t_i=1|\mathbf{x}_i;\mathbf{w},b)=y_i; \qquad P(t_i=0|\mathbf{x}_i;\mathbf{w},b)=1-y_i$$

• We minimize the **negative log-likelihood** loss function using gradient descent:

$$\mathcal{L}(\mathbf{w},b) = -\sum_{i=1}^N [t_i \, \log y_i + (1-t_i) \, \log(1-y_i)]$$

• We obtain the delta learning rule, using the class as a target and the probability as a prediction:

$$egin{cases} \Delta \mathbf{w} = \eta \left( t_i - y_i 
ight) \mathbf{x}_i \ \Delta b = \eta \left( t_i - y_i 
ight) \end{cases}$$

### Logistic regression

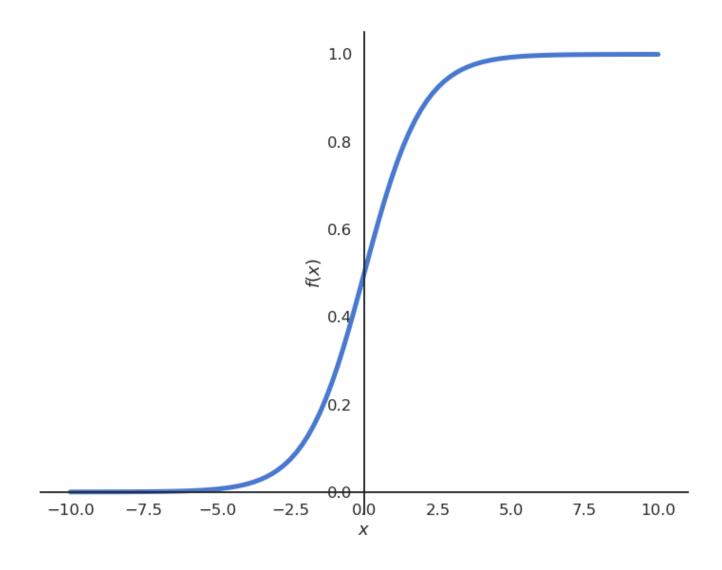
#### **Logistic regression**

- $\mathbf{w} = 0$  b = 0
- ullet for M epochs:
  - for each sample  $(\mathbf{x}_i, t_i)$ :

$$\circ \ y_i = \sigma(\langle \mathbf{w} \cdot \mathbf{x}_i 
angle + b)$$

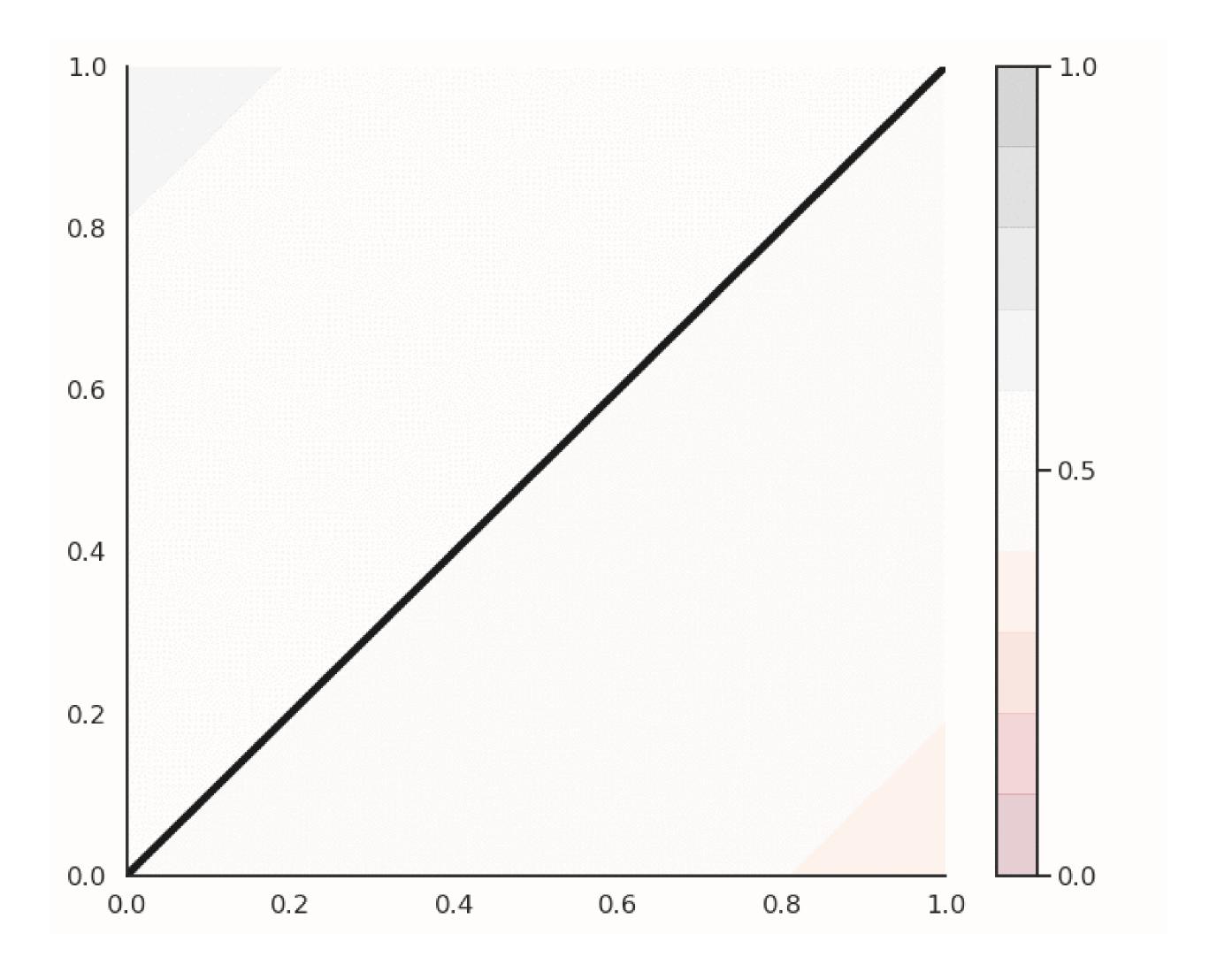
$$\circ \ \Delta \mathbf{w} = \eta \left( t_i - y_i 
ight) \mathbf{x}_i$$

$$\circ \; \Delta b = \eta \left( t_i - y_i 
ight)$$

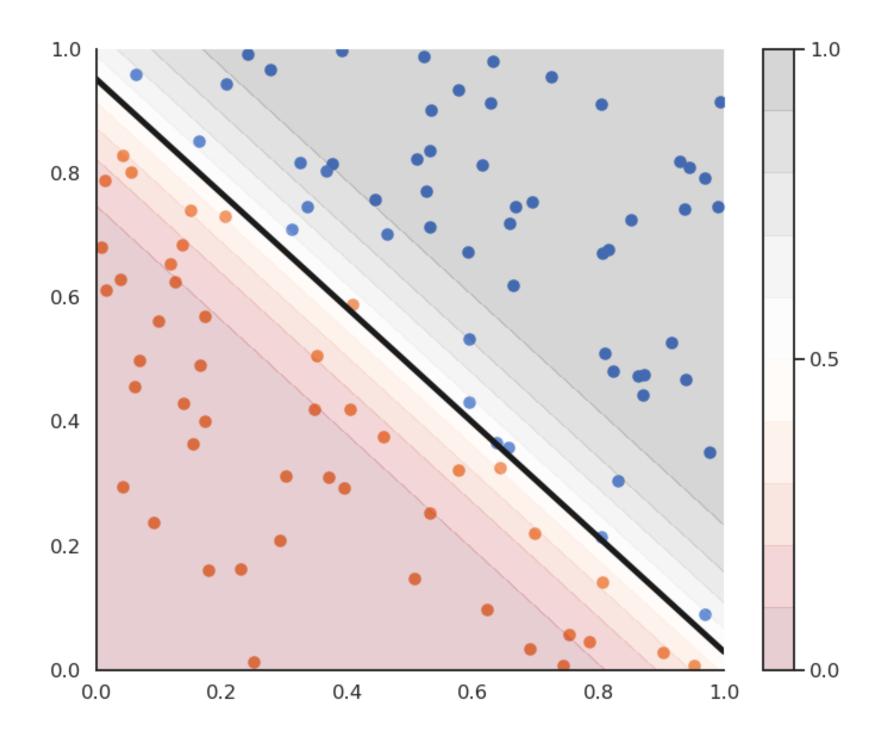


- Logistic regression works just like linear classification, except in the way the prediction is done.
- To know to which class  $\mathbf{x}_i$  belongs, simply draw a random number between 0 and 1:
  - if it is smaller than  $y_i$  (probability  $y_i$ ), it belongs to the positive class.
  - if it is bigger than  $y_i$  (probability  $1-y_i$ ), it belongs to the negative class.
- Alternatively, you can put a **hard limit** at 0.5:
  - if  $y_i > 0.5$  then the class is positive.
  - ullet if  $y_i < 0.5$  then the class is negative.

# Logistic regression



### Logistic regression and confidence score

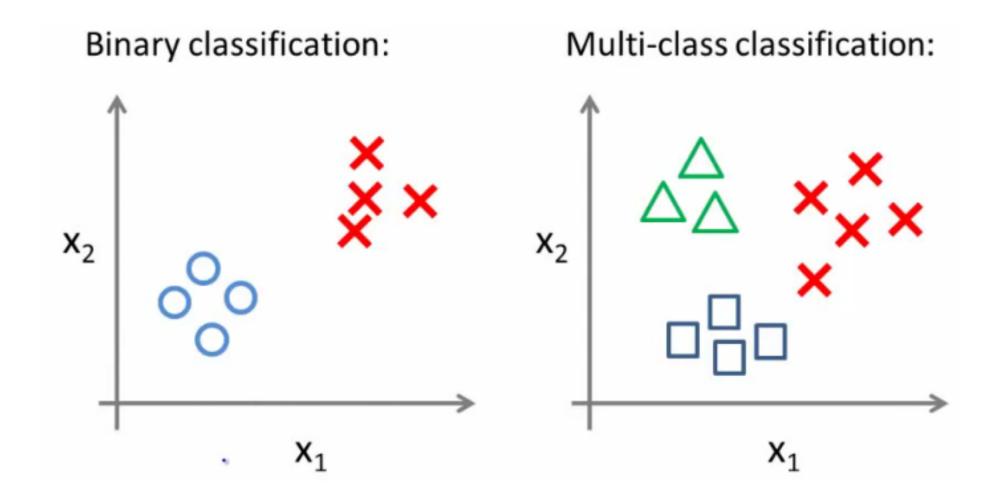


- Logistic regression also provides a confidence score:
  - the closer y is from 0 or 1, the more confident we can be that the classification is correct.
- This is particularly important in **safety critical** applications:
  - If you detect the positive class but with a confidence of 0.51, you should perhaps not trust the prediction.
  - If the confidence score is 0.99, you can probably trust the prediction.

4 - Multi-class classification

### Multi-class classification

ullet Can we perform multi-class classification using the previous methods when  $t\in\{A,B,C\}$  instead of t=+1 or -1?



#### Multi-class classification

Two main solutions:

- One-vs-All (or One-vs-the-rest): one trains simultaneously a binary (linear) classifier for each class. The examples belonging to this class form the positive class, all others are the negative class:
  - A vs. B and C
  - B vs. A and C
  - C vs. A and B

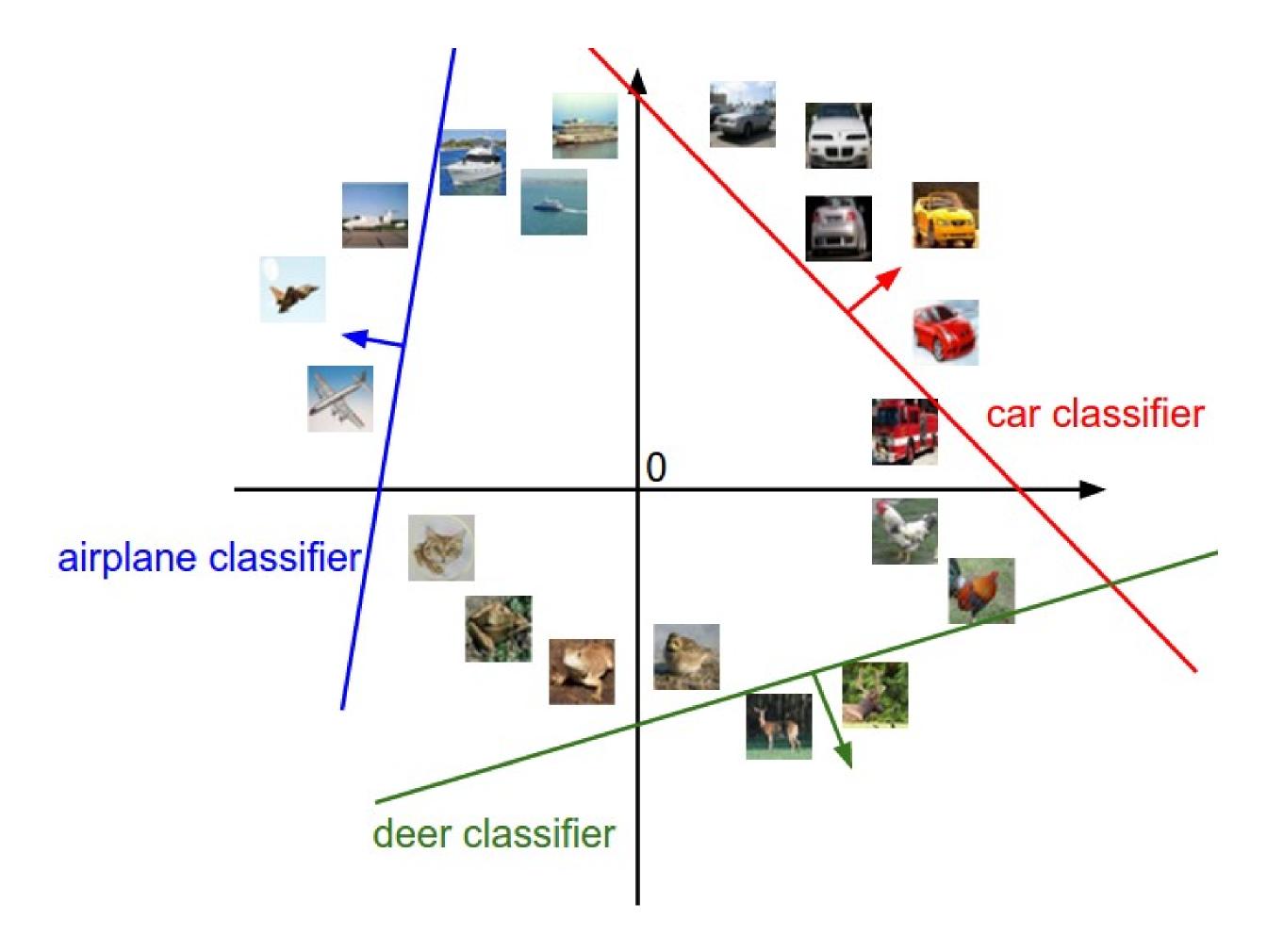
If multiple classes are predicted for a single example, ones needs a confidence level for each classifier saying how sure it is of its prediction.

- One-vs-One: one trains a classifier for each pair of class:
  - A vs. B
  - B vs. C
  - C vs. A

A majority vote is then performed to find the correct class.

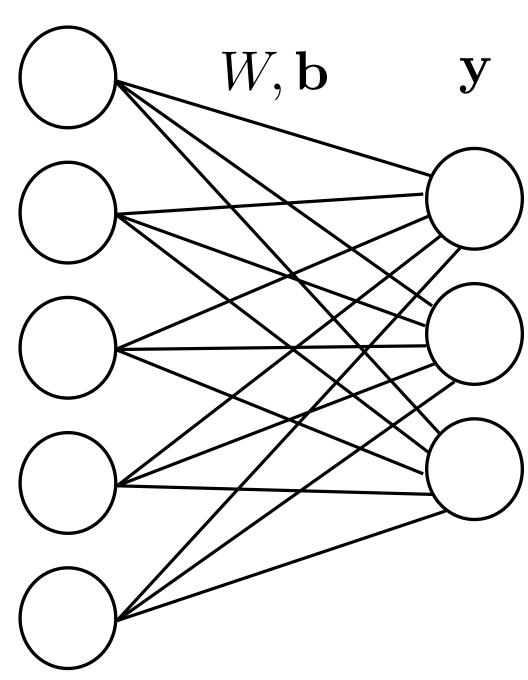
### **Multi-class classification**

• Example of One-vs-All classification: one binary classifier per class.



#### Softmax linear classifier





- ullet Suppose we have C classes (dog vs. cat vs. ship vs...).
- The One-vs-All scheme involves C binary classifiers  $(\mathbf{w}_i, b_i)$ , each with a weight vector and a bias, working on the same input  $\mathbf{x}$ .

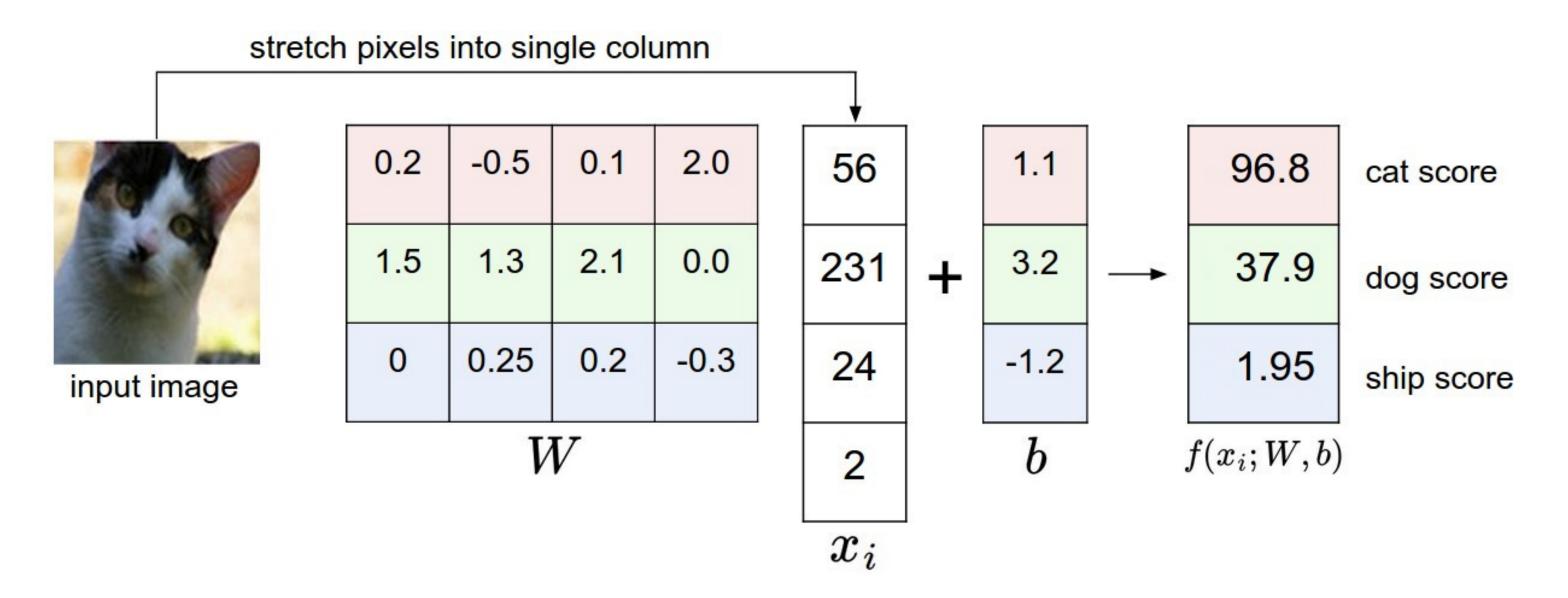
$$y_i = f(\langle \mathbf{w}_i \cdot \mathbf{x} 
angle + b_i)$$

• Putting all neurons together, we obtain a **linear perceptron** similar to multiple linear regression:

$$\mathbf{y} = f(W \times \mathbf{x} + \mathbf{b})$$

• The C weight vectors form a  $C \times d$  weight matrix W, the biases form a vector  ${\bf b}$ .

#### Softmax linear classifier



The net activations form a vector z:

$$\mathbf{z} = f_{W,\mathbf{b}}(\mathbf{x}) = W imes \mathbf{x} + \mathbf{b}$$

- Each element  $z_j$  of the vector  $\mathbf{z}$  is called the **logit score** of the class:
  - the higher the score, the more likely the input belongs to this class.
- The logit scores are not probabilities, as they can be negative and do not sum to 1.

## One-hot encoding

- ullet How do we represent the ground truth  $oldsymbol{t}$  for each neuron?
- ullet The target vector  ${f t}$  is represented using **one-hot encoding**.



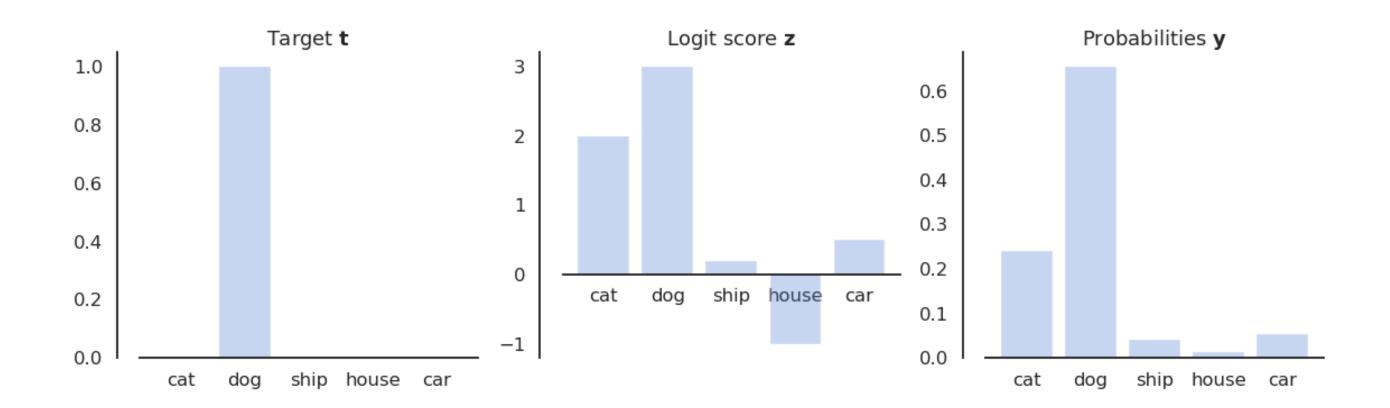
- The binary vector has one element per class: only one element is 1, the others are 0.
- Example:

$$\mathbf{t} = [\mathrm{cat}, \mathrm{dog}, \mathrm{ship}, \mathrm{house}, \mathrm{car}] = [0, 1, 0, 0, 0]$$

## One-hot encoding

- The labels can be seen as a **probability distribution** over the training set, in this case a **multinomial** distribution (a dice with C sides).
- f t: For a given image f x (e.g. a picture of a dog), the conditional pmf is defined by the one-hot encoded vector f t:

$$P(\mathbf{t}|\mathbf{x}) = [P(\text{cat}|\mathbf{x}), P(\text{dog}|\mathbf{x}), P(\text{ship}|\mathbf{x}), P(\text{house}|\mathbf{x}), P(\text{car}|\mathbf{x})] = [0, 1, 0, 0, 0]$$



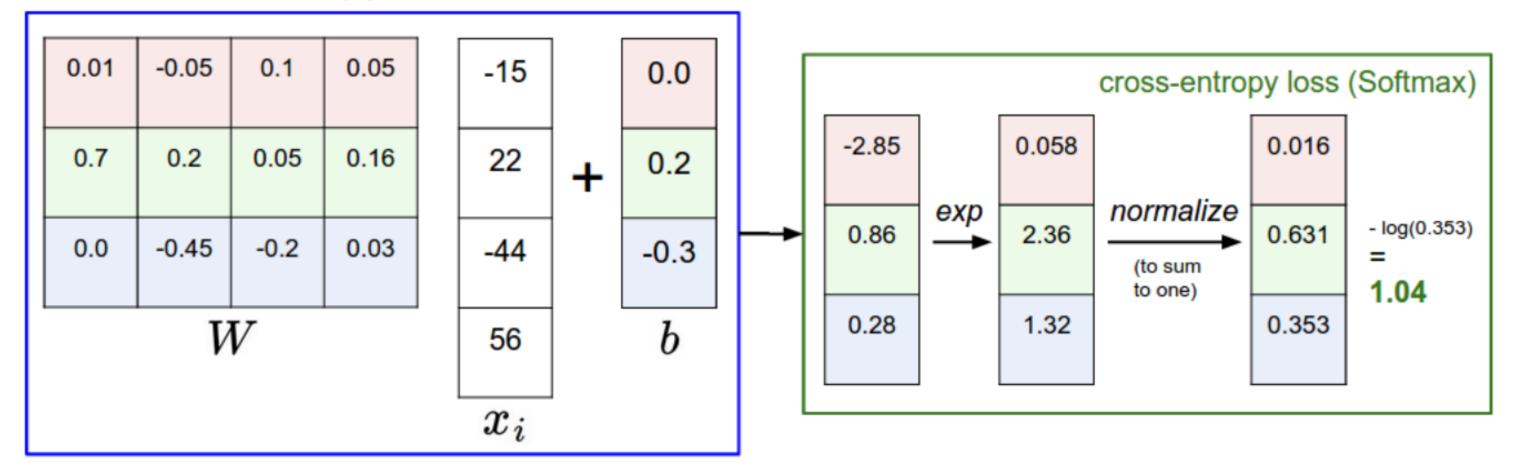
• We need to transform the logit score  $\mathbf{z}$  into a **probability distribution**  $P(\mathbf{y}|\mathbf{x})$  that should be as close as possible from  $P(\mathbf{t}|\mathbf{x})$ .

#### Softmax linear classifier

ullet The **softmax** operator makes sure that the sum of the outputs  $\mathbf{y}=\{y_i\}$  over all classes is 1.

$$y_j = P( ext{class} = ext{j}| extbf{x}) = \mathcal{S}(z_j) = rac{\exp(z_j)}{\sum_k \exp(z_k)}$$

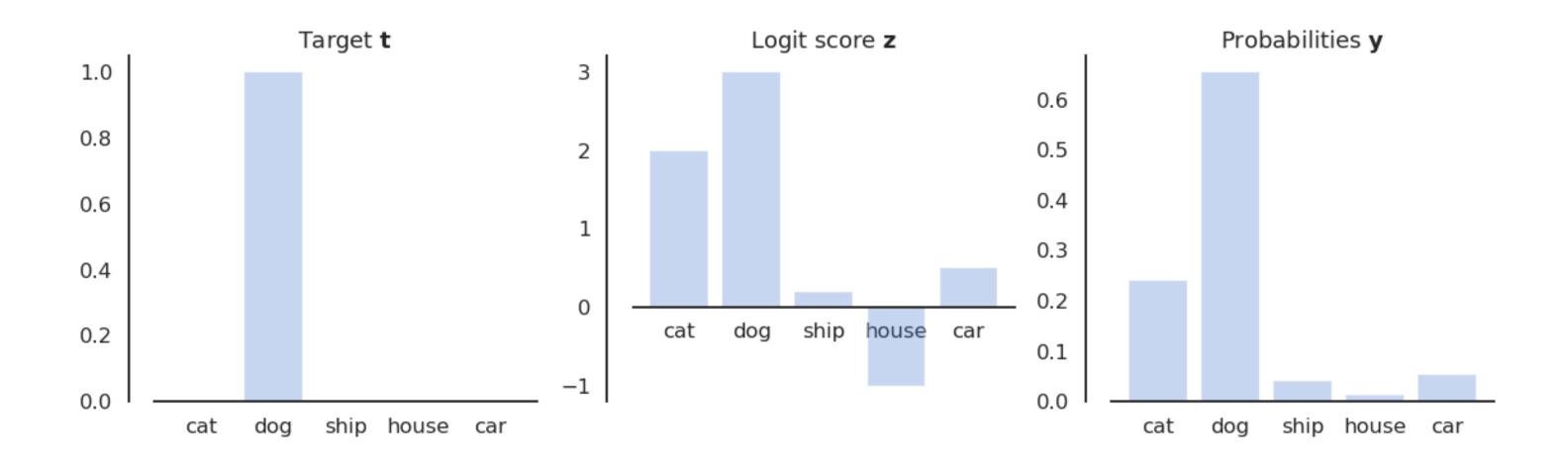
#### matrix multiply + bias offset



- ullet The higher  $z_j$ , the higher the probability that the example belongs to class j.
- This is very similar to logistic regression for soft classification, except that we have multiple classes.

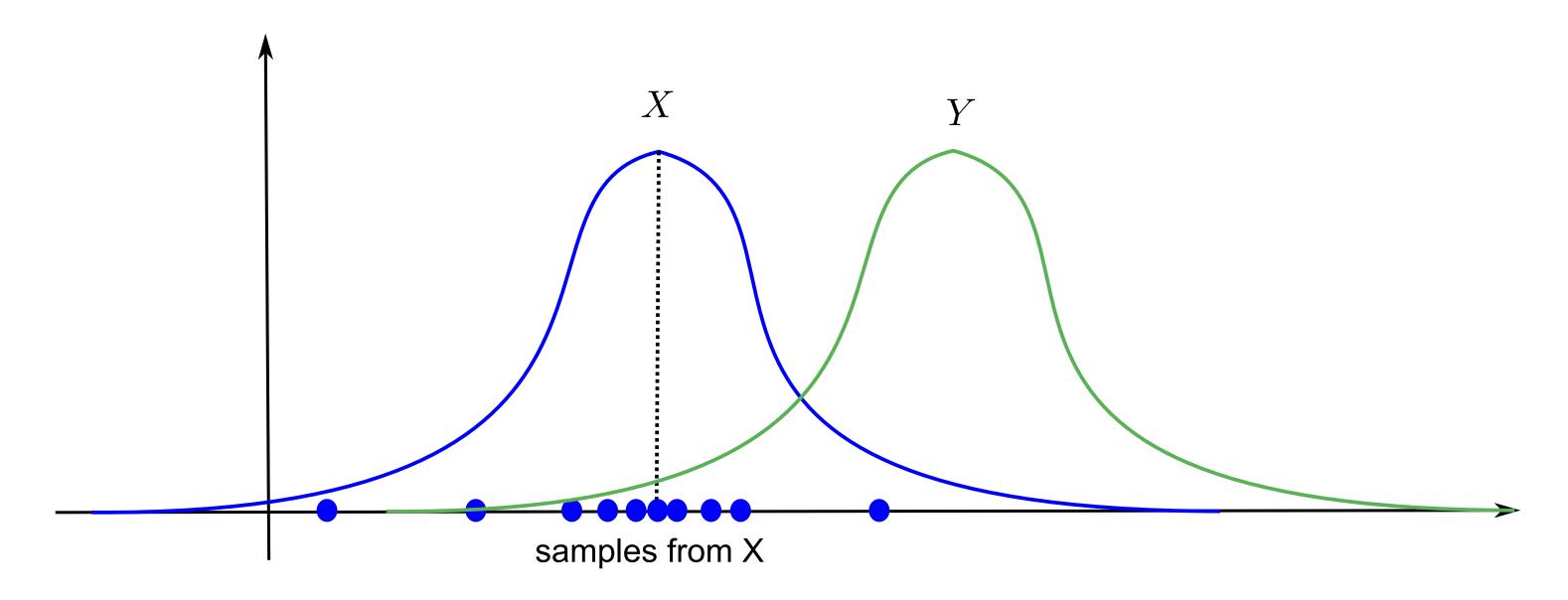
• We cannot use the mse as a loss function, as the softmax function would be hard to differentiate:

$$\mathrm{mse}(W,\mathbf{b}) = \sum_j (t_j - rac{\exp(z_j)}{\sum_k \exp(z_k)})^2$$



- We actually want to minimize the statistical distance netween two distributions:
  - lacksquare The model outputs a multinomial probability distribution f y for an input f x: P(f y|f x;W,b).
  - ullet The one-hot encoded classes also come from a multinomial probability distribution  $P(\mathbf{t}|\mathbf{x})$ .
- We search which parameters  $(W, \mathbf{b})$  make the two distributions  $P(\mathbf{y}|\mathbf{x}; W, \mathbf{b})$  and  $P(\mathbf{t}|\mathbf{x})$  close.

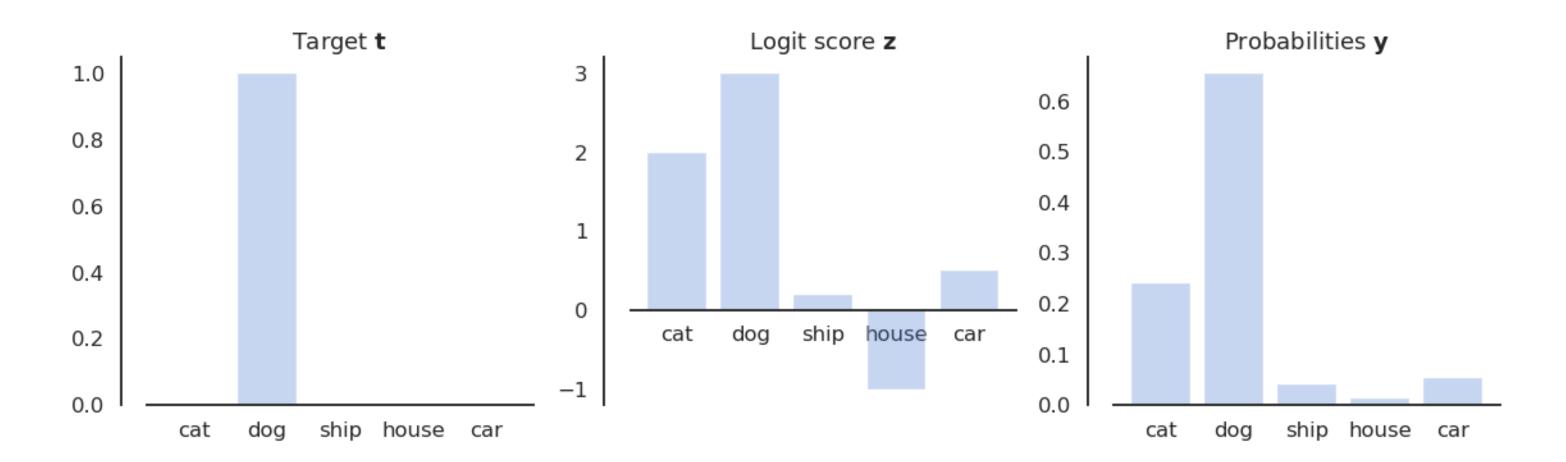
- The training data  $\{\mathbf{x}_i, \mathbf{t}_i\}$  represents samples from  $P(\mathbf{t}|\mathbf{x})$ .
- P(y|x;W,b) is a good model of the data when the two distributions are close, i.e. when the **negative** log-likelihood of each sample under the model is small.



ullet For an input  ${f x}$ , we minimize the **cross-entropy** between the target distribution and the predicted outputs:

$$l(W, \mathbf{b}) = \mathcal{H}(\mathbf{t}|\mathbf{x}, \mathbf{y}|\mathbf{x}) = \mathbb{E}_{t \sim P(\mathbf{t}|\mathbf{x})}[-\log P(\mathbf{y} = t|\mathbf{x})]$$

## Cross-entropy and negative log-likelihood



• The cross-entropy samples from  $\mathbf{t}|\mathbf{x}$ :

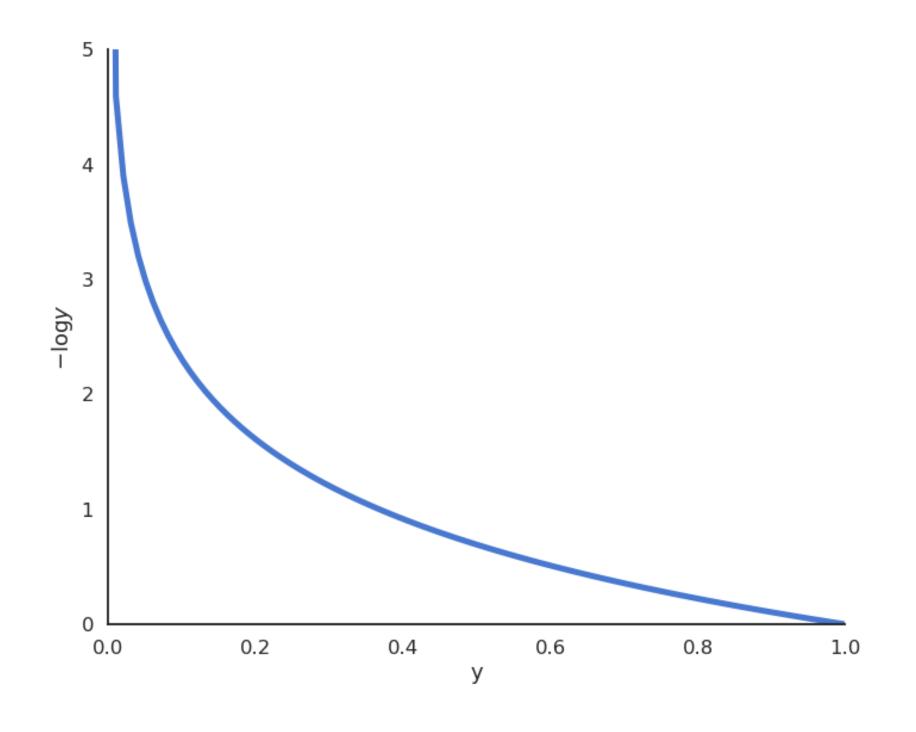
$$l(W, \mathbf{b}) = \mathcal{H}(\mathbf{t}|\mathbf{x}, \mathbf{y}|\mathbf{x}) = \mathbb{E}_{t \sim P(\mathbf{t}|\mathbf{x})}[-\log P(\mathbf{y} = t|\mathbf{x})] = -\sum_{j=1}^{C} P(t_j|\mathbf{x})\,\log P(y_j = t_j|\mathbf{x})$$

• For a given input  ${\bf x}$ ,  ${\bf t}$  is non-zero only for the correct class  $t^*$ , as  ${\bf t}$  is a one-hot encoded vector [0,1,0,0,0]:

$$l(W, \mathbf{b}) = -\log P(\mathbf{y} = t^* | \mathbf{x})$$

=

## Cross-entropy and negative log-likelihood



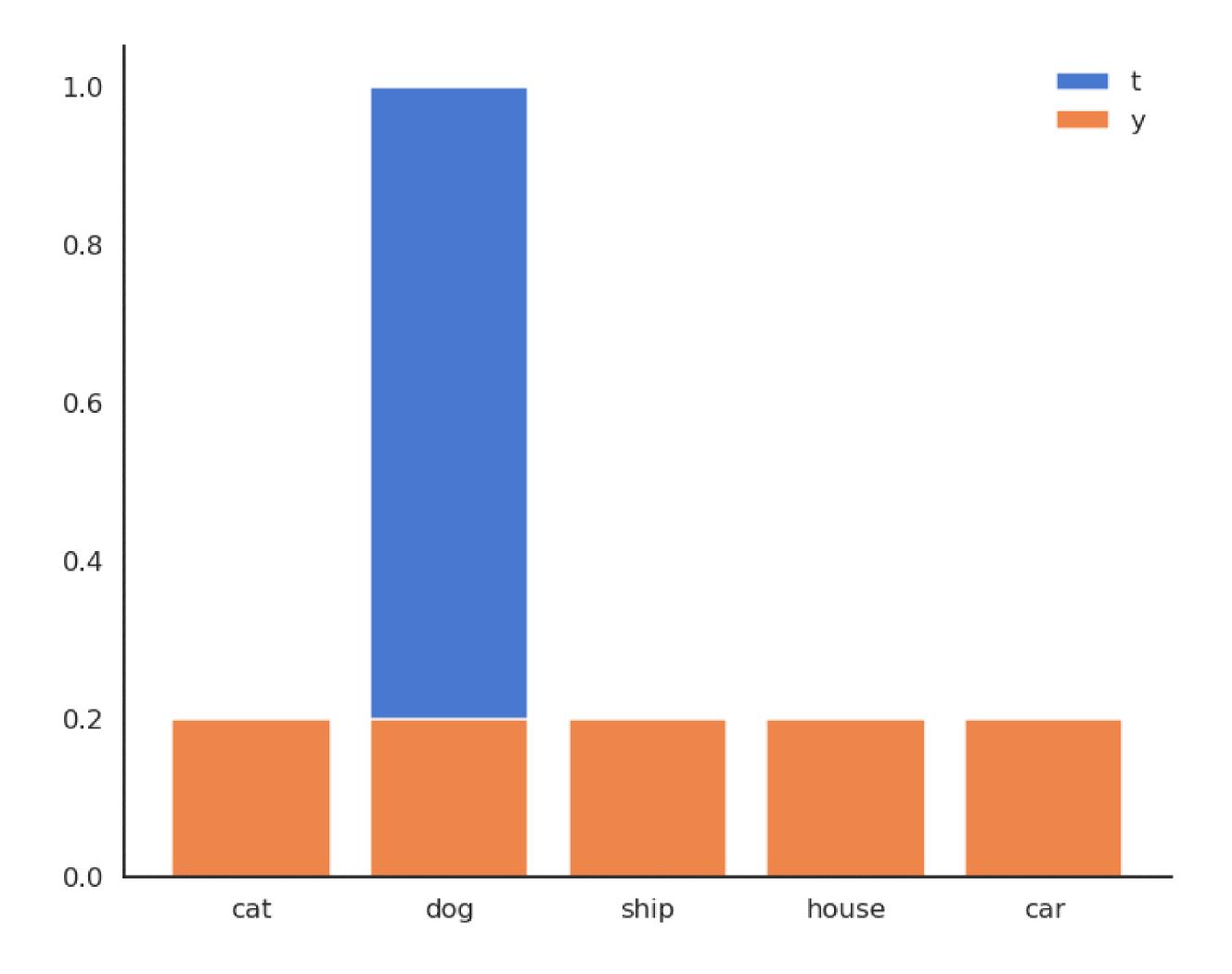
 As only one element of t is non-zero, the crossentropy is the same as the negative log-likelihood of the prediction for the true label:

$$l(W,\mathbf{b}) = -\log y_{j^*}$$

- The minimum of  $-\log y$  is obtained when y=1:
  - We want to classifier to output a probability 1 for the true label.
- Because of the softmax activation function, the probability for the other classes should become closer from 0.

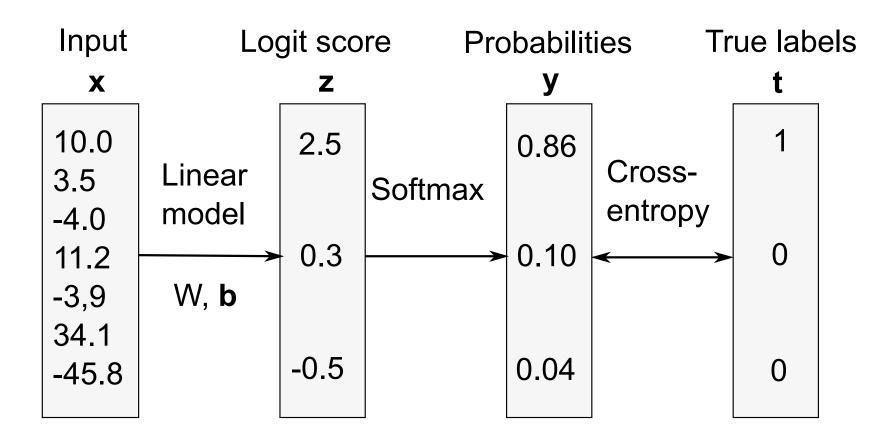
$$y_j = P( ext{class} = ext{j}) = rac{\exp(z_j)}{\sum_k \exp(z_k)}$$

• Minimizing the cross-entropy / negative log-likelihood pushes the output distribution  $\mathbf{y}|\mathbf{x}$  to be as close as possible to the target distribution  $\mathbf{t}|\mathbf{x}$ .



• As  $\bf t$  is a binary vector [0,1,0,0,0], the cross-entropy / negative log-likelihood can also be noted as the dot product between  $\bf t$  and  $\log \bf y$ :

$$l(W, \mathbf{b}) = - \langle \mathbf{t} \cdot \log \mathbf{y} 
angle = - \sum_{j=1}^C t_j \, \log y_j = - \log y_{j^*}$$



• The **cross-entropy loss function** is then the expectation over the training set of the individual cross-entropies:

$$\mathcal{L}(W, \mathbf{b}) = \mathbb{E}_{\mathbf{x}, \mathbf{t} \sim \mathcal{D}}[-\langle \mathbf{t} \cdot \log \mathbf{y} 
angle] pprox rac{1}{N} \sum_{i=1}^{N} -\langle \mathbf{t}_i \cdot \log \mathbf{y}_i 
angle$$

• The nice thing with the **cross-entropy** loss function, when used on a softmax activation function, is that the partial derivative w.r.t the logit score **z** is simple:

$$egin{aligned} rac{\partial l(W,\mathbf{b})}{\partial z_i} &= -\sum_j rac{\partial}{\partial z_i} t_j \log(y_j) = -\sum_j t_j rac{\partial \log(y_j)}{\partial z_i} = -\sum_j t_j rac{1}{y_j} rac{\partial y_j}{\partial z_i} \ &= -rac{t_i}{y_i} rac{\partial y_i}{\partial z_i} - \sum_{j 
eq i}^C rac{t_j}{y_j} rac{\partial y_j}{\partial z_i} = -rac{t_i}{y_i} y_i (1 - y_i) - \sum_{j 
eq i}^C rac{t_j}{y_i} (-y_j y_i) \ &= -t_i + t_i y_i + \sum_{j 
eq i}^C t_j y_i = -t_i + \sum_{j 
eq i}^C t_j y_i = -t_i + y_i \sum_{j 
eq i}^C t_j \ &= -(t_i - y_i) \end{aligned}$$

i.e. the same as with the mse in linear regression!

Vector notation:

$$rac{\partial l(W,\mathbf{b})}{\partial \mathbf{z}} = -(\mathbf{t}-\mathbf{y})$$

• As:

$$z = W \times x + b$$

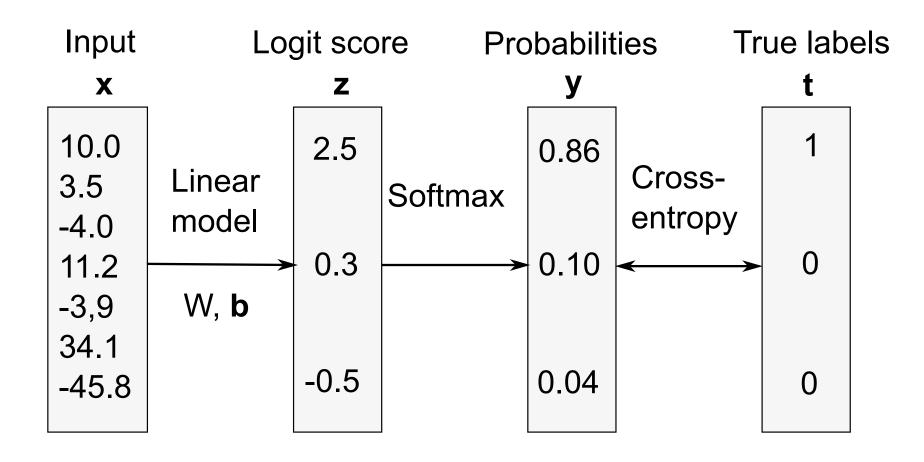
we can obtain the partial derivatives:

$$egin{aligned} rac{\partial l(W, \mathbf{b})}{\partial W} &= rac{\partial l(W, \mathbf{b})}{\partial \mathbf{z}} imes rac{\partial \mathbf{z}}{\partial W} = -(\mathbf{t} - \mathbf{y}) imes \mathbf{x}^T \ rac{\partial l(W, \mathbf{b})}{\partial \mathbf{b}} &= rac{\partial l(W, \mathbf{b})}{\partial \mathbf{z}} imes rac{\partial \mathbf{z}}{\partial \mathbf{b}} = -(\mathbf{t} - \mathbf{y}) \end{aligned}$$

• So gradient descent leads to the **delta learning rule**:

$$egin{cases} \Delta W = \eta \left( \mathbf{t} - \mathbf{y} 
ight) imes \mathbf{x}^T \ \Delta \mathbf{b} = \eta \left( \mathbf{t} - \mathbf{y} 
ight) \end{cases}$$

#### Softmax linear classifier



• We first compute the **logit scores z** using a linear layer:

$$z = W \times x + b$$

 We turn them into probabilities y using the softmax activation function:

$$y_j = rac{\exp(z_j)}{\sum_k \exp(z_k)}$$

• We minimize the cross-entropy / negative log-likelihood on the training set:

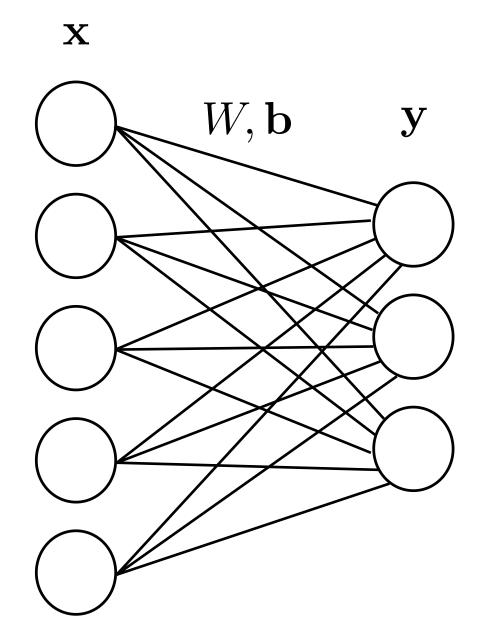
$$\mathcal{L}(W, \mathbf{b}) = \mathbb{E}_{\mathbf{x}, \mathbf{t} \sim \mathcal{D}}[-\langle \mathbf{t} \cdot \log \mathbf{y} 
angle]$$

which simplifies into the **delta learning rule**:

$$egin{cases} \Delta W = \eta \left( \mathbf{t} - \mathbf{y} 
ight) imes \mathbf{x}^T \ \Delta \mathbf{b} = \eta \left( \mathbf{t} - \mathbf{y} 
ight) \end{cases}$$

## Comparison of linear classification and regression

• Classification and regression differ in the nature of their outputs: in classification they are discrete, in regression they are continuous values.



• However, when trying to minimize the mismatch between a model y and the real data t, we have found the same **delta learning rule**:

$$egin{cases} \Delta W = \eta \left( \mathbf{t} - \mathbf{y} 
ight) imes \mathbf{x}^T \ \Delta \mathbf{b} = \eta \left( \mathbf{t} - \mathbf{y} 
ight) \end{cases}$$

- Regression and classification are in the end the same problem for us. The only things that needs to be adapted is the activation function of the output and the loss function.
- For regression, we use linear activation functions and the **mean square error** (mse):

$$\mathcal{L}(W, \mathbf{b}) = \mathbb{E}_{\mathbf{x}, \mathbf{t} \sim \mathcal{D}}[||\mathbf{t} - \mathbf{y}||^2]$$

 For classification, we use the softmax activation function and the cross-entropy (negative loglikelihood) loss function.

$$\mathcal{L}(W, \mathbf{b}) = \mathbb{E}_{\mathbf{x}, \mathbf{t} \sim \mathcal{D}}[-\langle \mathbf{t} \cdot \log \mathbf{y} 
angle]$$

5 - Multi-label classification

#### Multi-label classification

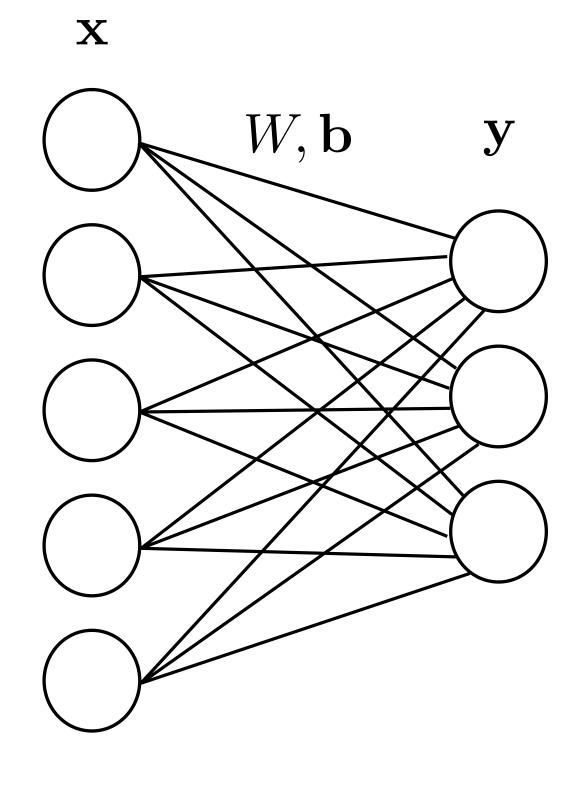
- What if there is more than one label on the image?
- The target vector **t** does not represent a probability distribution anymore:

$$\mathbf{t} = [\mathrm{cat}, \mathrm{dog}, \mathrm{ship}, \mathrm{house}, \mathrm{car}] = [1, 1, 0, 0, 0]$$

• Normalizing the vector does not help: it is not a dog or a cat, it is a dog and a cat.

$$\mathbf{t} = [\text{cat}, \text{dog}, \text{ship}, \text{house}, \text{car}] = [0.5, 0.5, 0, 0, 0]$$

#### Multi-label classification



• For multi-label classification, we can simply use the **logistic** activation function for the output neurons:

$$\mathbf{y} = \sigma(W \times \mathbf{x} + \mathbf{b})$$

 The outputs are between 0 and 1, but they do not sum to one. Each output neuron performs logistic regression for soft classification on their class:

$$y_j = P( ext{class} = j | \mathbf{x})$$

• Each output neuron  $y_j$  has a binary target  $t_j$  (one-vs-the-rest) and has to minimize the negative log-likelihood:

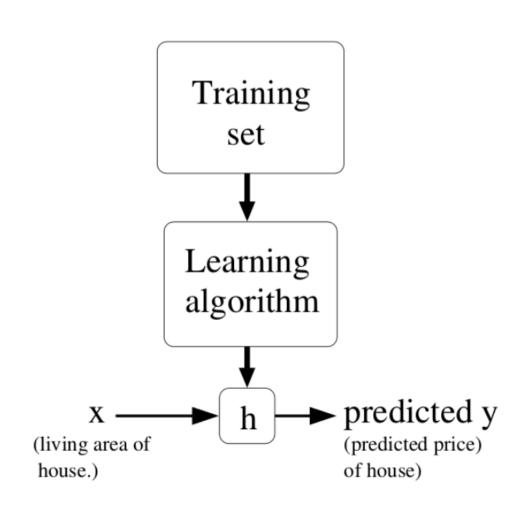
$$l_i(W, \mathbf{b}) = -t_i \log y_i + (1 - t_i) \log(1 - y_i)$$

• The binary cross-entropy loss is the sum of the negative log-likelihood for each class:

$$\mathcal{L}(W, \mathbf{b}) = \mathbb{E}_{\mathcal{D}}[-\sum_{j=1}^C t_j \, \log y_j + (1-t_j) \, \log(1-y_j)]$$

## 6 - Metrics

## Training vs. Generalization error



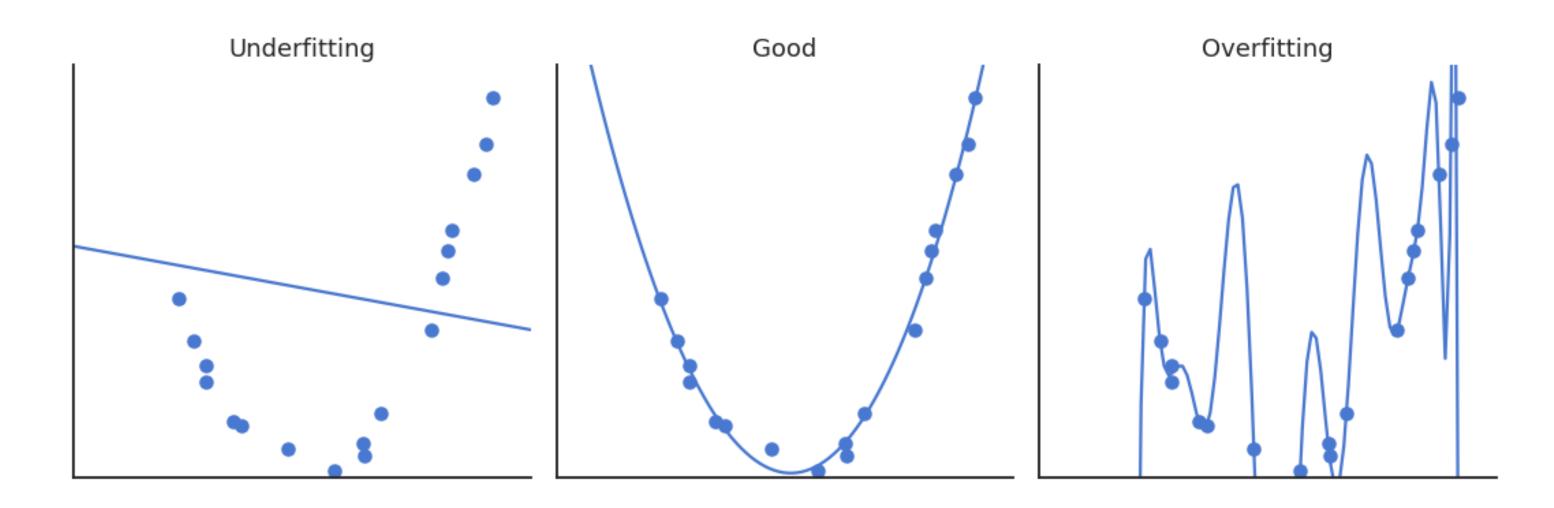
- The **training error** is the error made on the training set.
  - Easy to measure for classification: number of misclassified examples divided by the total number.

$$\epsilon_{\mathcal{D}} = \frac{\text{number of misclassifications}}{\text{number of examples}}$$

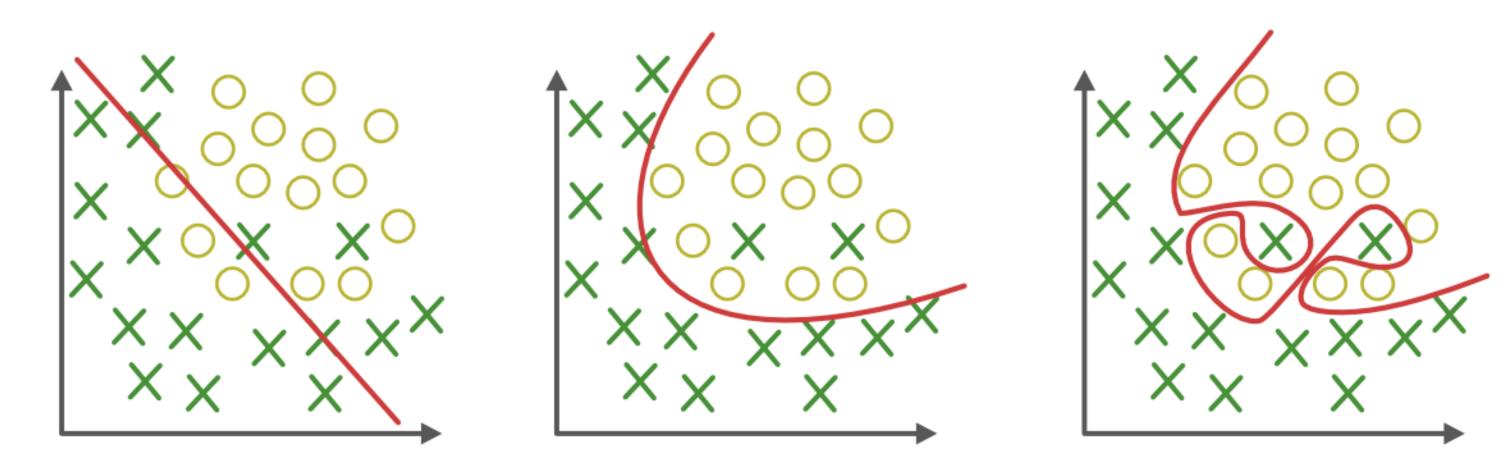
 Totally irrelevant on usage: reading the training set has a training error of 0%.

- What matters is the **generalization error**, which is the error that will be made on new examples (not used during learning).
  - Much harder to measure (potentially infinite number of new examples, what is the correct answer?).
  - Often approximated by the empirical error on the test set: one keeps a number of training examples
    out of the learning phase and one tests the performance on them.
  - Need for cross-validation to detect overfitting.

#### **Overfitting in regression**

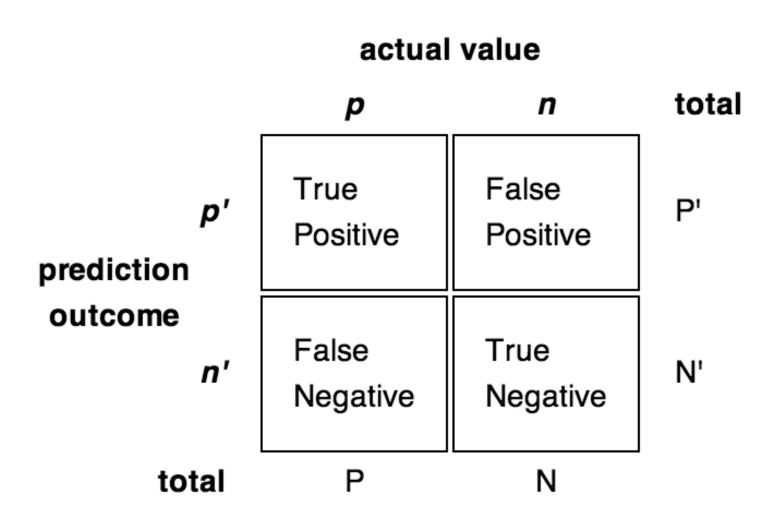


#### **Overfitting in classification**



#### **Classification errors**

#### **Confusion matrix**

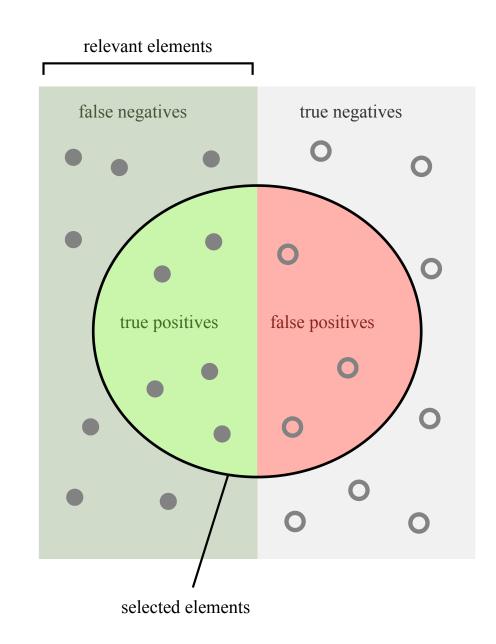


- Classification errors can also depend on the class:
  - False Positive errors (FP, false alarm, type I) is when the classifier predicts a positive class for a negative example.
  - False Negative errors (FN, miss, type II) is when the classifier predicts a negative class for a positive example.
- True Positive (TP) and True Negative (TN) are correctly classified examples.
- Is it better to fail to detect a cancer (FN) or to incorrectly predict one (FP)?

#### Source:

https://alliance.seas.upenn.edu/~cis520/dynamic/2017/wiki/index.php? n=Lectures.PrecisionRecall

#### **Classification errors**



How many selected items are relevant?

How many relevant items are selected?

Recall =

Error

$$\epsilon = rac{ ext{FP} + ext{FN}}{ ext{TP} + ext{FP} + ext{TN} + ext{FN}}$$

• Accuracy (1 - error)

$$acc = \frac{TP + TN}{TP + FP + TN + FN}$$

• Recall (hit rate, sensitivity) and Precision (specificity)

$$R = rac{ ext{TP}}{ ext{TP} + ext{FN}} \ \ P = rac{ ext{TP}}{ ext{TP} + ext{FP}}$$

• F1 score = harmonic mean of precision and recall

https://upload.wikimedia.org/wikipedia/commons/2/26/Precisionrecall.svg

$$\mathrm{F1} = rac{2\,P\,R}{P+R}$$

### **Confusion matrix**

- For multiclass classification problems, the confusion matrix tells how many examples are correctly classified and where confusion happens.
- One axis is the predicted class, the other is the target class.
- Each element of the matrix tells how many examples are classified or misclassified.
- The matrix should be as diagonal as possible.

• Using scikit-learn:

```
from sklearn.metrics import confusion_matrix
m = confusion_matrix(t, y)
```

