

# Package ‘dynatop’

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**Title** An Implementation of Dynamic TOPMODEL Hydrological Model in R

**Version** 0.3.0.1000

**Description** An R implementation and enhancement of the Dynamic TOPMODEL semi-distributed hydrological model originally proposed by Beven and Freer (2001) <[doi:10.1002/hyp.252](https://doi.org/10.1002/hyp.252)>. The 'dynatop' package implements code for simulating models which can be created using the 'dynatopGIS' package.

**License** GPL-2

**Encoding** UTF-8

**LazyData** true

**ByteCompile** true

**Imports** R6, zoo, xts, Rcpp

**LinkingTo** Rcpp

**Depends** R (>= 4.0.0)

**BugReports** <https://github.com/waternumbers/dynatop/issues>

**URL** <https://waternumbers.github.io/dynatop/>,  
<https://github.com/waternumbers/dynatop>

**RoxygenNote** 7.2.3

**Suggests** terra, knitr, rmarkdown, bookdown, testthat (>= 3.0.0)

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**SystemRequirements** C++14

**Language** en-GB

**NeedsCompilation** yes

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dynatop-package	<i>dynatop</i>
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## Description

This package contains the core code for the R implementation of dynamic TOPMODEL

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dynatop	<i>R6 Class for Dynamic TOPMODEL</i>
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## Description

R6 Class for Dynamic TOPMODEL

R6 Class for Dynamic TOPMODEL

## Methods

### Public methods:

- `dynatop$new()`
- `dynatop$add_data()`
- `dynatop$clear_data()`
- `dynatop$initialise()`
- `dynatop$sim()`
- `dynatop$get_output()`
- `dynatop$plot_output()`
- `dynatop$get_obs_data()`
- `dynatop$get_model()`
- `dynatop$get_mass_errors()`
- `dynatop$get_states()`
- `dynatop$plot_state()`
- `dynatop$clone()`

**Method** `new()`: Creates a dynatop class object from the a list based model description as generated by dynatopGIS.

#### Usage:

```
dynatop$new(model, map = NULL, use_states = FALSE, delta = 1e-13)
```

#### Arguments:

`model` a dynamic TOPMODEL list object  
`map` file name of the map layers for the model  
`use_states` logical if states should be imported  
`delta` error term in checking redistribution sums  
`drop_map` logical if the map should be dropped

**Details:** This function makes some basic consistency checks on a list representing a dynamic TOPMODEL model. The checks performed are basic 'sanity' checks. They do not check for the logic of the parameter values nor the consistency of states and parameters. Sums of the redistribution matrices are checked to be in the range  $1 \pm \delta$ .

*Returns:* invisible(self) suitable for chaining

**Method** add\_data(): Adds observed data to a dynatop object

*Usage:*

```
dynatop$add_data(obs_data)
```

*Arguments:*

obs\_data an xts object of observed data

*Details:* This function makes some basic consistency checks on the observations to ensure they have uniform timestep and all required series are present.

*Returns:* invisible(self) suitable for chaining

**Method** clear\_data(): Clears all forcing and simulation data except current states

*Usage:*

```
dynatop$clear_data()
```

*Returns:* invisible(self) suitable for chaining

**Method** initialise(): Initialises a dynatop object in the simplest way possible.

*Usage:*

```
dynatop$initialise(
  vtol = sqrt(.Machine$double.eps),
  ftol = sqrt(.Machine$double.eps),
  max_it = 1000
)
```

*Arguments:*

vtol tolerance for the solution for the saturated zone storage (as volume)

ftol tolerance for the solution of the saturated zone storage (as difference of function from 0)

max\_it maximum number of iterations to use in the solution of the saturated zone

*Returns:* invisible(self) suitable for chaining

**Method** sim(): Simulate the hillslope and channel componets of a dynatop object

*Usage:*

```
dynatop$sim(
  output_defn,
  keep_states = NULL,
  sub_step = NULL,
  vtol = sqrt(.Machine$double.eps),
  ftol = sqrt(.Machine$double.eps),
  max_it = 1000
)
```

*Arguments:*

output\_defn a description of the output series

keep\_states a vector of POSIXct objects (e.g. from xts) giving the time stamp at which the states should be kept

sub\_step simulation timestep in seconds, default value of NULL results in data time step

vtol tolerance on width of bounds in the solution for the saturated zone (as volume)

ftol tolerance on the solution for the saturated zone (as difference of solution from 0)

max\_it maximum number of iterations to use in the solution of the saturated zone

*Details:* Saving the states at every timestep and keeping the mass balance can generate very large data sets!!

*Returns:* invisible(self) for chaining

**Method** `get_output()`: Return channel inflow as an xts series or list of xts series

*Usage:*

```
dynatop$get_output(name = colnames(private$time_series$output))
```

*Arguments:*

name one or more output series to return

**Method** `plot_output()`: Plot the channel inflow

*Usage:*

```
dynatop$plot_output(name = colnames(private$time_series$output))
```

*Arguments:*

name of series to plot

**Method** `get_obs_data()`: Get the observed data

*Usage:*

```
dynatop$get_obs_data()
```

**Method** `get_model()`: Return the model

*Usage:*

```
dynatop$get_model()
```

**Method** `get_mass_errors()`: Return the model

*Usage:*

```
dynatop$get_mass_errors()
```

**Method** `get_states()`: Return states

*Usage:*

```
dynatop$get_states(record = FALSE)
```

*Arguments:*

record logical TRUE if the record should be returned. Otherwise the current states returned

**Method** `plot_state()`: Plot a current state of the system

*Usage:*

```
dynatop$plot_state(state = c("s_sf", "s_rz", "s_uz", "s_sz"))
```

*Arguments:*

state the name of the state to be plotted

**Method** `clone()`: The objects of this class are cloneable with this method.

*Usage:*

```
dynatop$clone(deep = FALSE)
```

*Arguments:*

deep Whether to make a deep clone.

## Examples

```
## the vignettes contains further details of the method calls.

data("Swindale") ## example data
mdl <- Swindale$model
mdl$map <- system.file("extdata", "Swindale.tif", package="dynatop", mustWork=TRUE)
ctch_mdl <- dynatop$new(mdl$hru, map=mdl$map) ## create with model
ctch_mdl$add_data(Swindale$sobs) ## add observations
ctch_mdl$initialise() ## initialise model
ctch_mdl$sim(Swindale$model$output_flux) ## simulate model
```

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evap\_est

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*Create sinusoidal time series of potential evapotranspiration input*


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## Description

Generate series of potential evapotranspiration

## Usage

```
evap_est(ts, eMin = 0, eMax = 0)
```

## Arguments

ts	as vector of POSIXct data/times
eMin	Minimum daily PE total (m or mm)
eMax	Maximum daily PE total (m or mm)

## Details

Dynamic TOPMODEL requires a time series of potential evapotranspiration in order to calculate and remove actual evapotranspiration from the root zone during a run. Many sophisticated physical models have been developed for estimating potential and actual evapotranspiration, including the Priestly-Taylor (Priestley and Taylor, 1972) and Penman-Monteith (Monteith, 1965) methods. These, however, require detailed meteorological data such as radiation input and relative humidities that are, in general, difficult to obtain. Calder (1983) demonstrated that a simple approximation using a sinusoidal variation in potential evapotranspiration to be a good approximation to more complex schemes.

If the insolation is also taken to vary sinusoidally through the daylight hours then, ignoring diurnal meteorological variations, the potential evapotranspiration during daylight hours for each year day number can be calculated (for the catchment's latitude). Integration over the daylight hours allows the daily maximum to be calculated and thus a sub-daily series generated.

## Value

Time series (xts) of potential evapotranspiration totals for the time steps given in same units as eMin and eMax

## References

Beven, K. J. (2012). Rainfall-runoff modelling : the primer. Chichester, UK, Wiley-Blackwell.  
 Calder, I. R. (1986). A stochastic model of rainfall interception. Journal of Hydrology, 89(1), 65-71.

## Examples

```
## Generating daily PET data for 1970
## the values of eMin and eMax may not be realistic
st <- as.POSIXct("1970-01-02 00:00:00",tz='GMT')
fn <- as.POSIXct("1971-01-01 00:00:00",tz='GMT')
daily_ts <- seq(st,fn,by=24*60*60)
dpet <- evap_est(daily_ts,0,1)

## create hourly data for the same period
st <- as.POSIXct("1970-01-01 01:00:00",tz='GMT')
fn <- as.POSIXct("1971-01-01 00:00:00",tz='GMT')
hour_ts <- seq(st,fn,by=1*60*60)
hpet <- evap_est(hour_ts,0,1)

## the totals should be the same...
stopifnot(all.equal(sum(hpet), sum(dpet)))
```

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resample\_xts

*Functions to resample an xts time series*


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## Description

Takes an xts time series object and resamples then to a new time step.

## Usage

```
resample_xts(obs, dt, is.rate = FALSE)
```

## Arguments

obs	A times series (xts) object with a POSIXct index.
dt	New time interval in seconds
is.rate	If TRUE then these are rates i.e m/h. Otherwise they are absolute values accumulated within the preceding time interval. Values are scaled before returning so resampling is conservative.

## Details

Time series of observation data are often of different temporal resolutions, however the input to most hydrological models, as is the case with the Dynamic TOPMODEL, requires those data at the same interval. This provides a method to resample a collection of such data to a single interval.

Because of the methods used the results:

- are not accurate when the input data does not have a constant timestep. The code issues a warning and proceeds assuming the data are equally spaced with the modal timestep.
- do not guarantee the requested time step but returns a series with the timestep computed from an integer rounding the ratio of the current and requested time step.

## Value

An xts object with the new timestep

**Examples**

```
# Resample Swindale Rainfall to hourly intervals
require(dynatop)
data("Swindale")
obs <- Swindale$obs
cobs <- resample_xts(obs, dt=60*60) # hourly data
dobs <- resample_xts(cobs,dt=15*60) # back to 15 minute data
cdobs <- resample_xts(dobs,dt=60*60) # back to hourly data - checks time stamp conversion
obs <- obs[zoo::index(obs)<=max(zoo::index(cobs)),]

# check totals
stopifnot( all.equal(sum(obs),sum(cobs)) )
stopifnot( all.equal(sum(obs),sum(dobs)) )
stopifnot( all.equal(cobs,cdobs) )
```

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Swindale*Example dynamic TOPMODEL setup*

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**Description**

This data set contains a processed model and observation data for Swindale.

**Usage**

```
data(Swindale)
```

**Format**

An object of class list of length 2.

**See Also**

[dynatop](#)

**Examples**

```
require(dynatop)
data(Swindale)

# Show it
# plot(obs)
```

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