## Invariance Proof of Algorithm Euclid

THEOREM PartialCorrectness is an invariant of algorithm Euclid.

1.  $Init \Rightarrow Inv$ 

PROOF: By the definitions of Init and Inv, since Init implies  $x=M,\,y=N,$  and  $pc\neq$  "Done".

- 2.  $Inv \wedge Next \Rightarrow Inv'$ 
  - 2.1. Case: x = y

PROOF: In this case, Next implies x = x' and y = y', which imply x' = y'. We then deduce x' = GCD(M, N) from Inv and GCD1, proving Inv'.

2.2. Case: x < y

PROOF: In this case, Next implies x' = x, and y' = y - x, which by the case assumption imply GCD(x', y') = GCD(x, y - x). This, Inv, and GCD3 imply GCD(x', y') = GCD(x, y), and Next implies  $pc' = \text{``Lbl\_1''}$ , so  $pc' \neq \text{``Done''}$ . Hence, Inv' is true.

2.3. Case: x > y

PROOF: This proof is similar to the proof of step 2.2, except that both GCD2 and GCD3 are needed to prove GCD(x', y') = GCD(x, y).

2.4. Q.E.D.

PROOF: By 2.1, 2.2, and 2.3, since the three cases cover all possibilities.

3.  $Inv \Rightarrow PartialCorrectness$ 

PROOF: It suffices to assume Inv and pc = "Done" and prove x = y and x = GCD(M, N). The proof of x = y is trivial, and x = GCD(M, N) follows from x = y, the first conjunct of Inv, and GCD1.

4. Q.E.D.

PROOF: By 1, 2, and 3 (which are conditions I1, I2, and I3).