# **Kentaro Wada**

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#### **EDUCATION**

#### The University of Tokyo, Bunkyo-ku, Tokyo, Japan

- Master of Computer Science (M.S.) in Creative Informatics of Information Science and Technology
  Sep 2016 Present
  - Thesis: Study of Robotic Manipulation with Learning for Object Segmentation
  - Supervisors: Prof. Masayuki Inaba and Assistant Prof. Kei Okada
  - Focus: Machine Learning, 3D Vision, Robotic Manipulation
- Bachelor of Science (B.S.) in Mechano-Informatics, Engineering Department Apr 2012 Mar 2016
  - Thesis: Learning for Picking through Experience of Verification-based Perception System
  - Supervisors: Prof. Masayuki Inaba and Assistant Prof. Kei Okada
  - Focus: Machine Learning, 3D Vision, Robotic Manipulation
  - Studied in Science II Cource in Apr 2012 Sep 2014, before the decision of department in Oct 2014

### RESEARCH EXPERIENCE

## **JSK Robotics Laboratory**, The University of Tokyo

• Graduate Research Student, Computer Science Department

- Oct 2016 Present
- Project: Study of Robotic Manipulation with Learning for Object Segmentation (Master Thesis)
- Supervisors: Prof. Masayuki Inaba and Assistant Prof. Kei Okada
- Focus: Deep Learning, 3D Vision, Robotic Manipulation
- Research Assistant

Oct 2015 – Sep 2016

- Project: Picking General Objects with Verification-based Vision System
- Supervisors: Assistant Prof. Kei Okada
- Focus: Deep Learning, 3D Vision, Robotic Manipulation
- Undergraduate Research Student, Engineering Department

Apr 2015 – Mar 2016

- Project: Learning for Picking through Experience of Verification-based Perception System (Bachelor Thesis)
- $\bullet\,$  Supervisors: Prof. Masayuki Inaba and Assistant Prof. Kei Okada
- Focus: Deep Learning, 3D Vision, Robotic Manipulation

#### Tanaka Kenji Laboratory, The University of Tokyo

■ Research Assistant

May 2014 - Mar 2015

- Project: Customer Clustering with Big Data Analysis of Purchase History
- Supervisors: Associate Prof. Kenji Tanaka
- Focus: Machine Learning, Data Mining

## **PUBLICATIONS**

## **JOURNALS**

[7] <u>K. Wada</u>, I. Yanokura, M. Sugiura, Y. Inagaki, K. Okada, and M. Inaba, "Pick-and-Verify: Verification-based Highly Reliable Picking System for Various Target Objects in Clutter", *Journal of Advanced Robotics*, (To appear)

#### INTERNATIONAL CONFERENCES

- [8] <u>K. Wada</u>, K. Okada, and M. Inaba, "LabelOctoMap: Probabilistic 3D Mapping for Object Segmentation", in *Proceedings of the 2017 IEEE-RAS International Conference on Robotics and Automation (ICRA2017*), (Under review).
- [6] K. Wada, M. Murooka, K. Okada, and M. Inaba, "3D Object Segmentation for Shelf Bin Picking by Humanoid with Deep Learning and Occupancy Voxel Grid Map", in *Proceedings of the 2016 IEEE-RAS International Conference on Humanoid Robotics (Humanoids 2016)*, Cancun, Mexico. Nov 2016.
- [5] Y. Furuta, K. Wada, M. Masaki, S. Nozawa, Y. Kakichi, K. Okada and M. Inaba, "Transformable Semantic Map Based Navigation using Autonomous Deep Learning Object Segmentation", in *Proceedings of the 2016 IEEE-RAS International Conference on Humanoid Robotics (Humanoids 2016)*, Cancun, Mexico. Nov 2016.

#### DOMESTIC CONFERENCES

- [4] Y. Niitani, K. Wada, S. Hasegawa, S. Kitagawa, M. Bando, K Okada, and M Inaba, "Semantic Image Segmentation and 3D Object Outline Extraction with Deep Learning for Picking Objects from Shelf-bin", in *Annual Conference of The Robotics Society of Japan*, Yamagata, Japan. Sep 2016.
- [3] <u>K. Wada</u>, K. Okada and M. Inaba, "Advanced Multi-layered Perception for Picking in Clutter with Parameter Reinforcement Learning via Experiment in Task" (in Japanese), in *The Robotics and Mechatronics Conference 2016*, Yokohama, Japan. Jun 2016.
- [2] <u>K. Wada</u>, I. Yanokura, M. Sugiura, Y. Inagaki, K. Okada and M. Inaba, "Daily Object Picking System with Visual Verification and Vacuum Gripper on Dual-arm Robot" (in Japanese), in *Annual Conference of Robotics Society Japan 2015*, Tokyo, Japan. Mar 2015.
- [1] <u>K. Wada</u>, K. Kawakami, Y. Honda, K. Tanaka, "Customer Clustering with Big Data Analysis of Purchase History" (in Japanese), in *Japanese Artificial Intellicence Conference*, *SIG-KST 23th*, Tokyo, Japan. Nov 2014.

## PROFESSIONAL AFFILIATIONS & ACTIVITIES

## Amazon Picking Challenge 2016, Leipzig, Germany

- K. Wada, S. Hasegawa, S. Kitagawa, Y. Niitani, M. Bando, K. Okada and M. Inaba
- 5th/8th place in 16 teams for pick/stow tasks.
- A core member of the team composed of 5 students and 2 professors.
- Especially worked for object recognition.

Apr 2016 - Jul 2016

### Google Summer of Code 2016, Tokyo, Japan

- K. Wada, F. Proctor, S. Edwards
- Student, Passed the Final Evaluation

May 2016 - Aug 2016

## Amazon Picking Challenge 2015, Seattle, USA

- K. Wada, I. Yanokura, M. Sugiura, Y. Inagaki, K. Okada and M. Inaba
- 8th place in 28 teams.
- A core member of the team composed of 4 students and 2 professors.
- Worked for object recognition and robotic manipulation.

Oct 2014 – May 2015

# OTHER WORK EXPERIENCE

## Donuts Co. Ltd., Tokyo, Japan

■ Internship as a system integrator

Sep 2013 – Jan 2014

- Frontend of e-commerce site with HTML, CSS and Javascript.
- Posting system construction with PHP.

#### Honda Research Institute, Tokyo, Japan

· Road scene recognition with deep learning

• Internship as a researcher

Aug 2014 – Sep 2014

# LANGUAGES

- Japanese: Native language.
- English: Fluent (listening, speaking, reading, writing).
- Chinese: Basic (listening, speaking, reading, writing).

# **SKILLS**

- Programming Languages: Python, C++, C, Bash, Zsh, HTML, CSS, Javascript, PHP, Lisp
- Frameworks: Chainer, Caffe, scikit-learn, ROS, PCL, OpenCV, scikit-image, flask

#### **INTERESTS**

Basketball, western art, piano.

## REFERENCES

#### Professor Masayuki Inaba

Professor of Mechano-Informatics Department

The University of Tokyo

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# ■ Associate Professor Kei Okada

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