Kentaro Wada

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EDUCATION

The University of Tokyo, Bunkyo-ku, Tokyo, Japan

- Master of Computer Science (M.S.) in Creative Informatics of Information Science and Technology Sep 2016 – Present
 - Thesis: Study of Robotic Manipulation with Learning for Object Segmentation
 - Supervisors: Prof. Masayuki Inaba and Assistant Prof. Kei Okada
 - Focus: Machine Learning, 3D Vision, Robotic Manipulation
- Bachelor of Science (B.S.) in Mechano-Informatics, Engineering Department Apr 2012 Mar 2016
 - Thesis: Learning for Picking through Experience of Verification-based Perception System
 - Supervisors: Prof. Masayuki Inaba and Assistant Prof. Kei Okada
 - Focus: Machine Learning, 3D Vision, Robotic Manipulation
 - Studied in Science II Cource in Apr 2012 Sep 2014, before the decision of department in Oct 2014

RESEARCH EXPERIENCE

JSK Robotics Laboratory, The University of Tokyo

• Graduate Research Student, Computer Science Department

- Oct 2016 Present
- Project: Study of Robotic Manipulation with Learning for Object Segmentation (Master Thesis)
- Supervisors: Prof. Masayuki Inaba and Assistant Prof. Kei Okada
- Focus: Deep Learning, 3D Vision, Robotic Manipulation
- Research Assistant

Oct 2015 – Sep 2016

- Project: Picking General Objects with Verification-based Vision System
- Supervisors: Assistant Prof. Kei Okada
- Focus: Deep Learning, 3D Vision, Robotic Manipulation
- Undergraduate Research Student, Engineering Department

Apr 2015 – Mar 2016

- Project: Learning for Picking through Experience of Verification-based Perception System (Bachelor Thesis)
- $\bullet\,$ Supervisors: Prof. Masayuki Inaba and Assistant Prof. Kei Okada
- Focus: Deep Learning, 3D Vision, Robotic Manipulation

Tanaka Kenji Laboratory, The University of Tokyo

■ Research Assistant

May 2014 - Mar 2015

- Project: Customer Clustering with Big Data Analysis of Purchase History
- Supervisors: Associate Prof. Kenji Tanaka
- Focus: Machine Learning, Data Mining

PUBLICATIONS

JOURNALS

[1] <u>K. Wada</u>, I. Yanokura, M. Sugiura, Y. Inagaki, K. Okada, and M. Inaba, "Pick-and-Verify: Verification-based Highly Reliable Picking System for Various Target Objects in Clutter", *Journal of Advanced Robotics*, (To appear)

INTERNATIONAL CONFERENCES

- [2] K. Wada, M. Murooka, K. Okada, and M. Inaba, "3D Object Segmentation for Shelf Bin Picking by Humanoid with Deep Learning and Occupancy Voxel Grid Map", in *Proceedings of the 2016 IEEE-RAS International Conference on Humanoid Robotics (Humanoids 2016)*, Cancun, Mexico. Nov 2016.
- [3] Y. Furuta, <u>K. Wada</u>, M. Masaki, S. Nozawa, Y. Kakichi, K. Okada and M. Inaba, "Transformable Semantic Map Based Navigation using Autonomous Deep Learning Object Segmentation", in *Proceedings of the 2016 IEEE-RAS International Conference on Humanoid Robotics (Humanoids 2016)*, Cancun, Mexico. Nov 2016.

DOMESTIC CONFERENCES

PROFESSIONAL AFFILIATIONS & ACTIVITIES

Society of Professional Earth Scientists, New York, USA

■ Member 2009 – Present

OTHER WORK EXPERIENCE

Alpha Engineering Firm, Oakland, Ohio, USA

- Project Officer, Research & Development Division
 - Nullam venenatis egestas nisl eget elementum.
 - Nulla finibus justo vel turpis efficitur, non lacinia orci maximus. Proin rhoncus, felis vel hendrerit lacinia, enim ipsum ultricies massa, sit amet interdum nisi massa sit amet justo.
 - Etiam vitae eros mollis, consectetur quam quis, molestie massa.

LANGUAGES

- Japanese: Native language.
- English: Fluent (listening, speaking, reading, writing).
- Chinese: Basic (listening, speaking, reading, writing).

SKILLS

- Programming Languages: Python, C++, C, Bash, Zsh, HTML, CSS, Javascript, PHP, Lisp
- Frameworks: ROS, PCL, OpenCV, scikit-image, Chainer, Caffe, scikit-learn, django

INTERESTS

Basketball, western art, piano.

REFERENCES

■ Professor Masayuki Inaba

Professor of Mechano-Informatics Department

The University of Tokyo

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Assistant Professor Kei Okada

Assistant Professor of Mechano-Informatics Department

The University of Tokyo

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 $[CV\ compiled\ on\ 2016\text{-}12\text{-}12]$

Oct 2007 - Jan 2008