

Kentaro Wada

5-14-24 Sendagi, Bunkyo-ku, Tokyo, 1130022, Japan
www.kentaro.wada@gmail.com • +81 (80) 6177-5221 • http://wkentaro.com

EDUCATION

The University of Tokyo, Bunkyo-ku, Tokyo, Japan

- Master of Computer Science (M.S.) in Creative Informatics of Information Science and Technology
Sep 2016 – Present
 - Thesis: Study of Robotic Manipulation with Learning for Object Segmentation
 - Supervisors: Prof. Masayuki Inaba and Associate Prof. Kei Okada
 - Focus: Machine Learning, 3D Vision, Robotic Manipulation
- Bachelor of Science (B.S.) in Mechano-Informatics, Engineering Department Apr 2012 – Mar 2016
 - Thesis: Learning for Picking through Experience of Verification-based Perception System
 - Supervisors: Prof. Masayuki Inaba and Associate Prof. Kei Okada
 - Focus: Machine Learning, 3D Vision, Robotic Manipulation
 - Studied in Science II Course in Apr 2012 – Sep 2014, before the decision of department in Oct 2014

RESEARCH EXPERIENCE

JSK Robotics Laboratory, The University of Tokyo

- Graduate Research Student, Computer Science Department Oct 2016 – Present
 - Project: Study of Robotic Manipulation with Learning for Object Segmentation (Master Thesis)
 - Supervisors: Prof. Masayuki Inaba and Associate Prof. Kei Okada
 - Focus: Deep Learning, 3D Vision, Robotic Manipulation
- Research Assistant Oct 2015 – Mar 2017
 - Project: Picking General Objects with Verification-based Vision System
 - Supervisors: Associate Prof. Kei Okada
 - Focus: Deep Learning, 3D Vision, Robotic Manipulation
- Undergraduate Research Student, Engineering Department Apr 2015 – Mar 2016
 - Project: Learning for Picking through Experience of Verification-based Perception System (Bachelor Thesis)
 - Supervisors: Prof. Masayuki Inaba and Associate Prof. Kei Okada
 - Focus: Deep Learning, 3D Vision, Robotic Manipulation

Tanaka Kenji Laboratory, The University of Tokyo

- Research Assistant May 2014 – Mar 2015
 - Project: Customer Clustering with Big Data Analysis of Purchase History
 - Supervisors: Associate Prof. Kenji Tanaka
 - Focus: Machine Learning, Data Mining

PUBLICATIONS

JOURNALS

- [7] K. Wada, I. Yanokura, M. Sugiura, Y. Inagaki, K. Okada, and M. Inaba, “Pick-and-Verify: Verification-based Highly Reliable Picking System for Various Target Objects in Clutter”, *Journal of Advanced Robotics*, Mar 2017.

INTERNATIONAL CONFERENCES

- [14] K. Wada, S. Hasegawa, S. Kitagawa, Y. Uchimi, N. Yamaguchi, K. Okada, and M. Inaba, “Few-shot Learning based on Context-aware Network Expansion with Artificial Training Data for Picking in Warehouse Automation”, in *Proceedings of the 2018 IEEE International Conference on Robotics and Automation (ICRA2018)*, (Under Review)
- [9] K. Wada, K. Okada, and M. Inaba, “Probabilistic 3D Multilabel Real-time Mapping for Multi-object Manipulation”, in *Proceedings of the 2017 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2017)*, Vancouver, Canada. Sep 2017.
- [8] S. Hasegawa, K. Wada, Y. Niitani, K. Okada, and M. Inaba, “A Three-Fingered Hand with a Suction Gripping System for Picking Various Objects in Cluttered Narrow Space”, in *Proceedings of the 2017 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2017)*, Vancouver, Canada. Sep 2017.
- [6] K. Wada, M. Murooka, K. Okada, and M. Inaba, “3D Object Segmentation for Shelf Bin Picking by Humanoid with Deep Learning and Occupancy Voxel Grid Map”, in *Proceedings of the 2016 IEEE-RAS International Conference on Humanoid Robotics (Humanoids 2016)*, Cancun, Mexico. Nov 2016.
- [5] Y. Furuta, K. Wada, M. Masaki, S. Nozawa, Y. Kakichi, K. Okada and M. Inaba, “Transformable Semantic Map Based Navigation using Autonomous Deep Learning Object Segmentation”, in *Proceedings of the 2016 IEEE-RAS International Conference on Humanoid Robotics (Humanoids 2016)*, Cancun, Mexico. Nov 2016.

DOMESTIC CONFERENCES

- [10] K. Wada, K. Okada and M. Inaba, “Fully Convolutional Object Depth Prediction for 3D Segmentation from 2.5D Input”, in *Annual Conference of the Japanese Society for Artificial Intelligence 2017*, Aichi, Japan. May 2017.
- [11] M. Murooka, Y. Niitani, K. Wada, S. Nozawa, Y. Kakiuchi, K. Okada and M. Inaba, “Motion Prediction of Object in Image by Deep Learning for Robot Manipulation”, in *Annual Conference of the Japanese Society for Artificial Intelligence 2017*, Aichi, Japan. May 2017.
- [12] S. Kitagawa, K. Wada, K. Okada and M. Inaba, “Learning-based Task Failure Prediction and Selective Execution of Dual-arm Support Motion for Stowing Task”, in *Annual Conference of the Japanese Society for Artificial Intelligence 2017*, Aichi, Japan. May 2017.
- [13] S. Hasegawa, K. Wada, K. Okada and M. Inaba, “Development of Suction Pinching Hand for Picking Task in Narrow Space”, in *2017 JSME Conference on Robotics and Mechatronics*, Fukushima, Japan. May 2017.
- [4] Y. Niitani, K. Wada, S. Hasegawa, S. Kitagawa, M. Bando, K. Okada, and M. Inaba, “Semantic Image Segmentation and 3D Object Outline Extraction with Deep Learning for Picking Objects from Shelf-bin”, in *Annual Conference of The Robotics Society of Japan*, Yamagata, Japan. Sep 2016.
- [3] K. Wada, K. Okada and M. Inaba, “Advanced Multi-layered Perception for Picking in Clutter with Parameter Reinforcement Learning via Experiment in Task” (in Japanese), in *The Robotics and Mechatronics Conference 2016*, Kanagawa, Japan. Jun 2016.
- [2] K. Wada, I. Yanokura, M. Sugiura, Y. Inagaki, K. Okada and M. Inaba, “Daily Object Picking System with Visual Verification and Vacuum Gripper on Dual-arm Robot” (in Japanese), in *Annual Conference of Robotics Society Japan 2015*, Tokyo, Japan. Mar 2015.
- [1] K. Wada, K. Kawakami, Y. Honda, K. Tanaka, “Customer Clustering with Big Data Analysis of Purchase History” (in Japanese), in *Japanese Artificial Intelligence Conference, SIG-KST 23th*, Tokyo, Japan. Nov 2014.

PROFESSIONAL AFFILIATIONS & ACTIVITIES	Amazon Robotics Challenge 2017 , Nagoya, Japan	
	<ul style="list-style-type: none"> ▪ <u>K. Wada</u>, S. Hasegawa, S. Kitagawa, Y. Uchimi, N. Yamaguchi, K. Okada and M. Inaba ▪ 12th/13th place in 16 teams for pick/stow tasks. ▪ A core member the team composed of 5 students and 2 professors. ▪ Especially worked for object recognition. 	Apr 2017 – Jul 2017
	Amazon Picking Challenge 2016 , Leipzig, Germany	
	<ul style="list-style-type: none"> ▪ <u>K. Wada</u>, S. Hasegawa, S. Kitagawa, Y. Niitani, M. Bando, K. Okada and M. Inaba ▪ 5th/8th place in 16 teams for pick/stow tasks. ▪ A core member of the team composed of 5 students and 2 professors. ▪ Especially worked for object recognition. 	Apr 2016 – Jul 2016
	Google Summer of Code 2016 , Tokyo, Japan	
	<ul style="list-style-type: none"> ▪ <u>K. Wada</u>, F. Proctor, S. Edwards ▪ Student, Passed the Final Evaluation 	May 2016 – Aug 2016
	Amazon Picking Challenge 2015 , Seattle, USA	
	<ul style="list-style-type: none"> ▪ <u>K. Wada</u>, I. Yanokura, M. Sugiura, Y. Inagaki, K. Okada and M. Inaba ▪ 8th place in 28 teams. ▪ A core member of the team composed of 4 students and 2 professors. ▪ Worked for object recognition and robotic manipulation. 	Oct 2014 – May 2015
OTHER WORK EXPERIENCE	Donuts Co. Ltd. , Tokyo, Japan	
	<ul style="list-style-type: none"> ▪ Internship as a system integrator <ul style="list-style-type: none"> • Frontend of e-commerce site with HTML, CSS and Javascript. • Posting system construction with PHP. 	Sep 2013 – Jan 2014
	Honda Research Institute , Tokyo, Japan	
	<ul style="list-style-type: none"> ▪ Internship as a researcher <ul style="list-style-type: none"> • Road scene recognition with deep learning 	Aug 2014 – Sep 2014
LANGUAGES	<ul style="list-style-type: none"> ▪ Japanese: Native language. ▪ English: Fluent (listening, speaking, reading, writing). ▪ Chinese: Basic (listening, speaking, reading, writing). 	
SKILLS	<ul style="list-style-type: none"> ▪ Programming Languages: Python, C++, C, Bash, Zsh, HTML, CSS, Javascript, PHP, Lisp ▪ Frameworks: Chainer, Caffe, scikit-learn, ROS, PCL, OpenCV, scikit-image, flask 	
INTERESTS	Basketball, western art, piano.	
REFERENCES	<ul style="list-style-type: none"> ▪ Professor Masayuki Inaba Professor of Mechano-Informatics Department The University of Tokyo 73A1, Engineering Building NO. 2, 7-3-1, Hongo, Bunkyo-ku, Tokyo, 1138656, Japan inaba@jsk.imi.i.u-tokyo.ac.jp • +81 (3) 5841-7416 	
	<ul style="list-style-type: none"> ▪ Associate Professor Kei Okada Associate Professor of Mechano-Informatics Department The University of Tokyo 73A2, Engineering Building NO. 2, 7-3-1, Hongo, Bunkyo-ku, Tokyo, 1138656, Japan k-okada@jsk.imi.i.u-tokyo.ac.jp • +81 (3) 5841-7416 	

[CV compiled on 2017-09-20]