

| <i>Quadrant : <math>Q_I</math></i> |                |                |                |
|------------------------------------|----------------|----------------|----------------|
| $0^\circ > \theta < 90^\circ$      |                | $\cos(\theta)$ | $\sin(\theta)$ |
| $Z_{01}$                           | <b>00.00°</b>  | 1.000          | 0.000          |
| $Z_{02}$                           | <b>12.86°</b>  | 0.975          | 0.223          |
| $Z_{03}$                           | <b>25.71°</b>  | 0.901          | 0.434          |
| $Z_{04}$                           | <b>38.57°</b>  | 0.782          | 0.623          |
| $Z_{05}$                           | <b>51.43°</b>  | 0.623          | 0.782          |
| $Z_{06}$                           | <b>64.29°</b>  | 0.434          | 0.901          |
| $Z_{07}$                           | <b>77.14°</b>  | 0.223          | 0.975          |
| <i><math>Q_{III}</math></i>        |                |                |                |
| $180^\circ > \theta < 270^\circ$   |                | $\cos(\theta)$ | $\sin(\theta)$ |
| $Z_{15}$                           | <b>180.00°</b> | -1.000         | -0.000         |
| $Z_{16}$                           | <b>192.86°</b> | -0.975         | -0.223         |
| $Z_{17}$                           | <b>205.71°</b> | -0.901         | -0.434         |
| $Z_{18}$                           | <b>218.57°</b> | -0.782         | -0.623         |
| $Z_{19}$                           | <b>231.43°</b> | -0.623         | -0.782         |
| $Z_{20}$                           | <b>244.29°</b> | -0.434         | -0.901         |
| $Z_{21}$                           | <b>257.14°</b> | -0.223         | -0.975         |

| <i><math>Q_{II}</math></i>       |                |                |                |
|----------------------------------|----------------|----------------|----------------|
| $90^\circ > \theta < 180^\circ$  |                | $\cos(\theta)$ | $\sin(\theta)$ |
| $Z_{08}$                         | <b>90.00°</b>  | -0.000         | 1.000          |
| $Z_{09}$                         | <b>102.86°</b> | -0.223         | 0.975          |
| $Z_{10}$                         | <b>115.71°</b> | -0.434         | 0.901          |
| $Z_{11}$                         | <b>128.57°</b> | -0.623         | 0.782          |
| $Z_{12}$                         | <b>141.43°</b> | -0.782         | 0.623          |
| $Z_{13}$                         | <b>154.29°</b> | -0.901         | 0.434          |
| $Z_{14}$                         | <b>167.14°</b> | -0.975         | 0.223          |
| <i><math>Q_{IV}</math></i>       |                |                |                |
| $270^\circ > \theta < 360^\circ$ |                | $\cos(\theta)$ | $\sin(\theta)$ |
| $Z_{22}$                         | <b>270.00°</b> | 0.000          | -1.000         |
| $Z_{23}$                         | <b>282.86°</b> | 0.223          | -0.975         |
| $Z_{24}$                         | <b>295.71°</b> | 0.434          | -0.901         |
| $Z_{25}$                         | <b>308.57°</b> | 0.623          | -0.782         |
| $Z_{26}$                         | <b>321.43°</b> | 0.782          | -0.623         |
| $Z_{27}$                         | <b>334.29°</b> | 0.901          | -0.434         |
| $Z_{28}$                         | <b>347.14°</b> | 0.975          | -0.223         |