# Mastering Alloy

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## Subset signatures

## Subset signatures

- An arbitrary subset of a signature can be declared with keyword instead of extends
- Subset signatures are not necessarily disjoint
- A signature can be declared as a subset of more than one signature
- Subset signatures cannot be extended
- Subset signatures can be used to simulate multiple-inheritance
- Atoms belonging to subset signatures are labelled in the visualiser

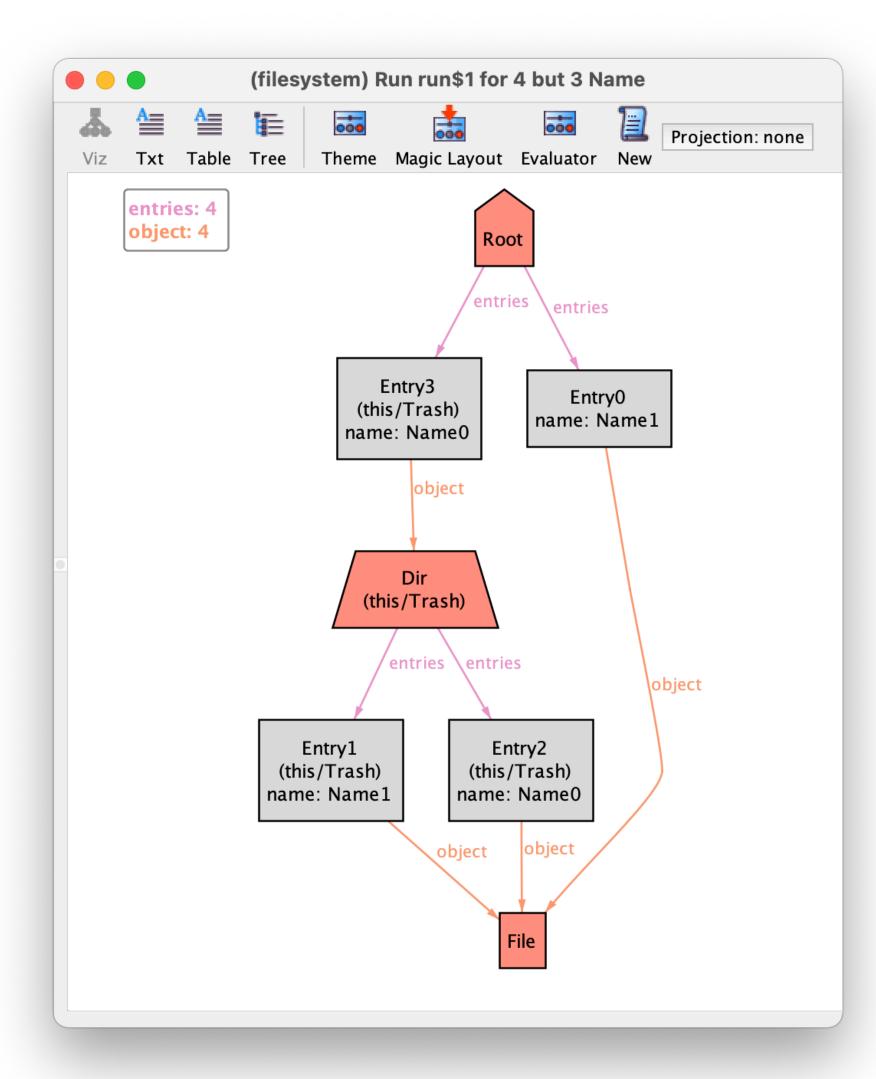
## File-system

```
abstract sig Object {}
sig Dir extends Object {
  entries : set Entry
sig File extends Object {}
one sig Root extends Dir {}
sig Entry {
  object: one Object,
  name : one Name
sig Name {}
```

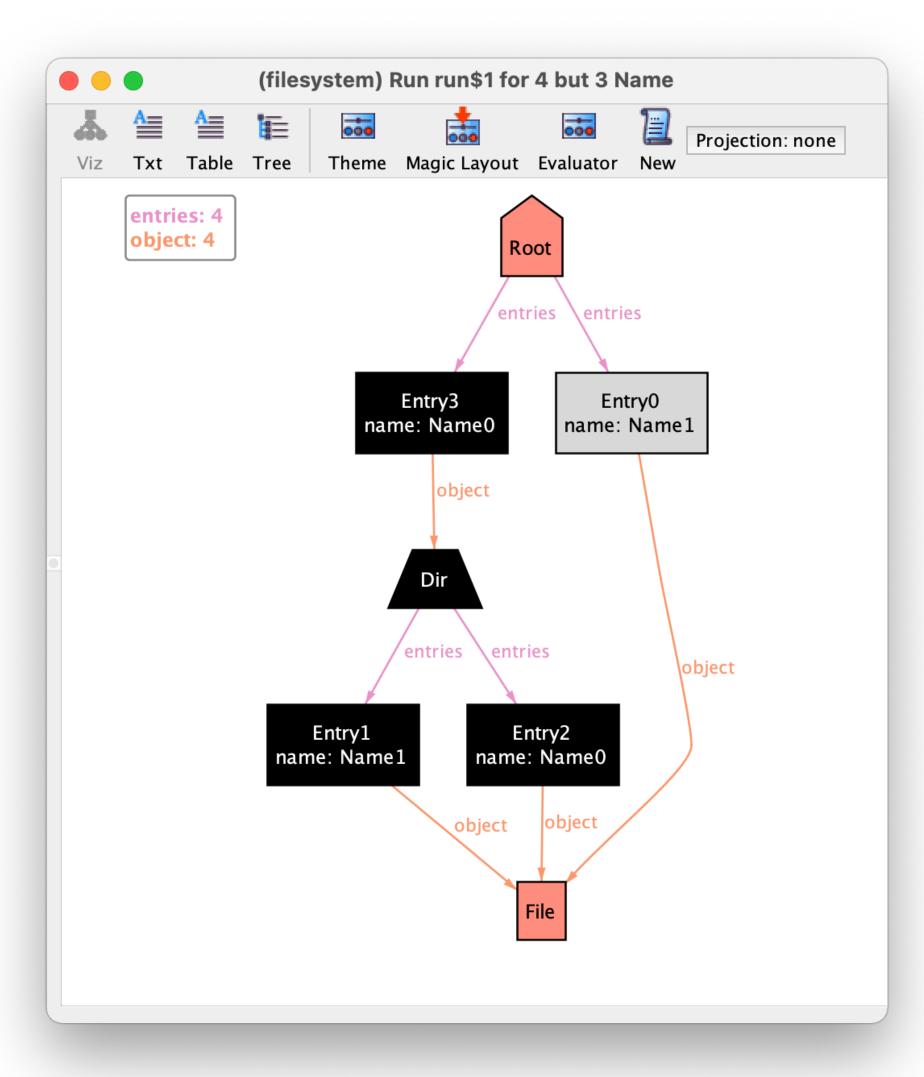
#### Subset example

```
sig Trash in Object+Entry {}
fact {
  // The root cannot be trashed
  Root not in Trash
  // All other objects are trashed iff all entries
  // that point to them are trashed
  all o: Object-Root | o in Trash iff object.o in Trash
  // If a directory is trashed all its entries are trashed
  all d: Dir & Trash | d.entries in Trash
```

# Visualising subsets



# Visualising subsets



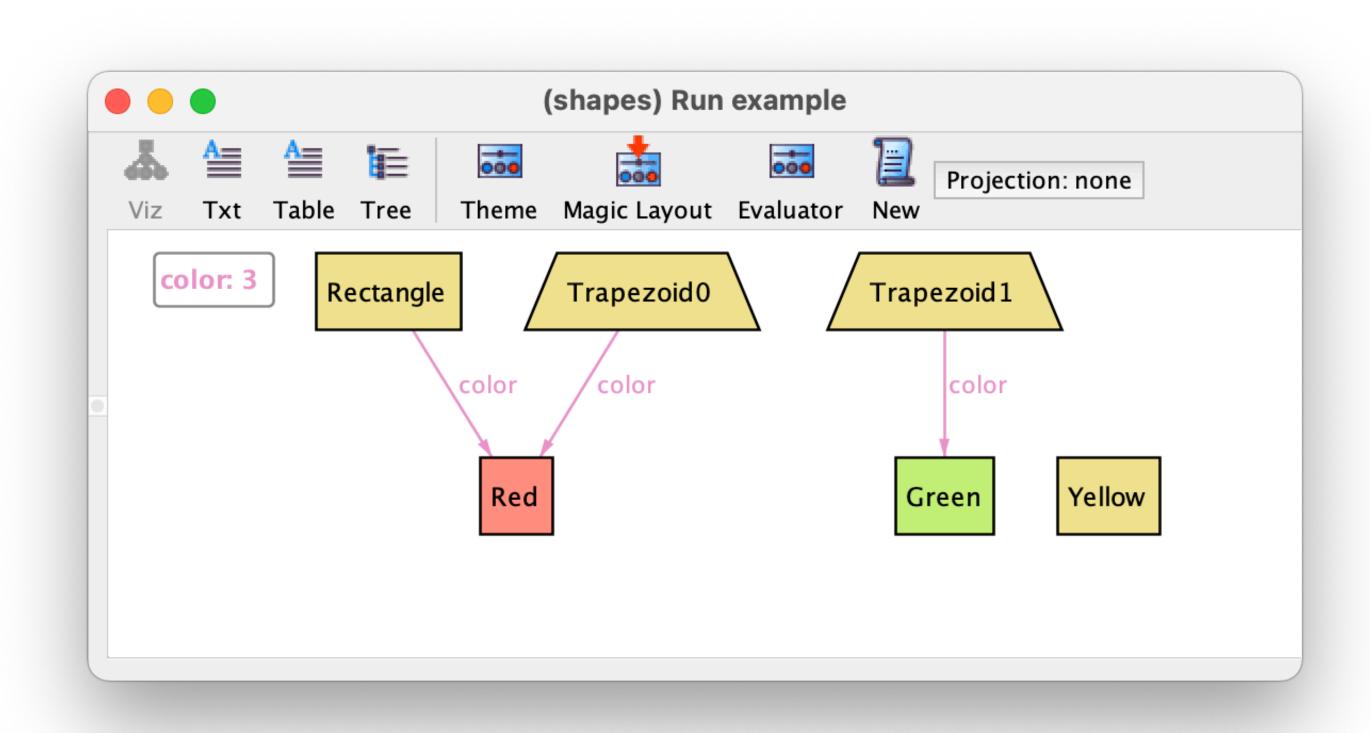
#### Subset example

```
abstract sig Shape {
   color : one Color
}
sig Rectangle, Trapezoid extends Shape {}
abstract sig Color {}
one sig Green, Red, Yellow extends Color {}
```

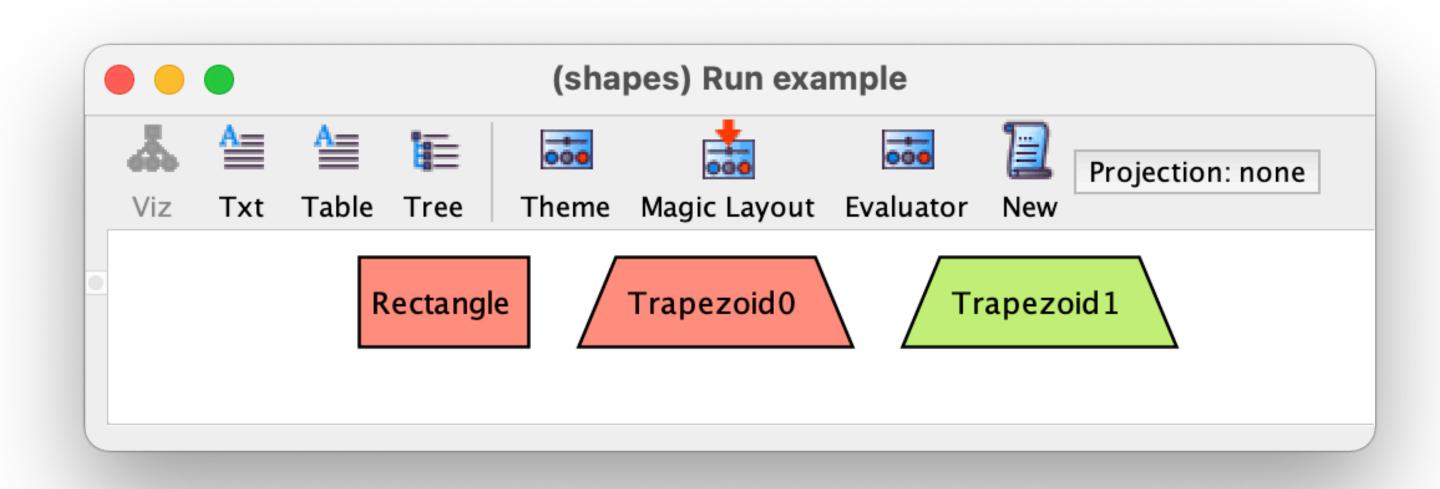
## Subset example

```
abstract sig Shape {}
sig Rectangle, Trapezoid extends Shape {}
sig Green, Red, Yellow in Shape {}
fact {
  Shape = Green+Red+Yellow
  no Green & Red
  no Red & Yellow
  no Green & Yellow
```

## Visualising subsets

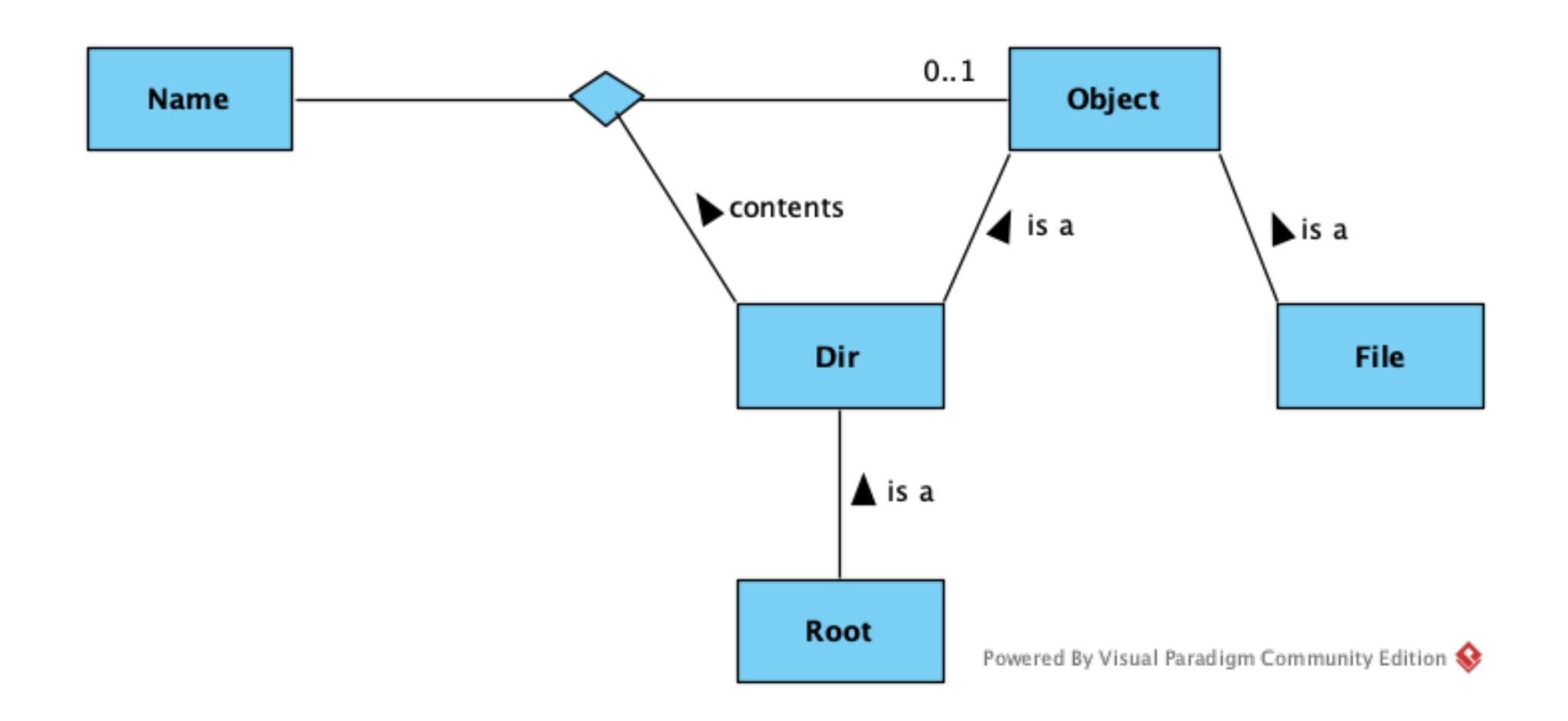


# Visualising subsets



# N-ary relations

#### N-ary relationships a la UML



## Ternary relation example

```
abstract sig Object {}
sig Dir extends Object {
  contents : Name -> lone Object
}
sig File extends Object {}
one sig Root extends Dir {}
sig Name {}
```

Root

Root

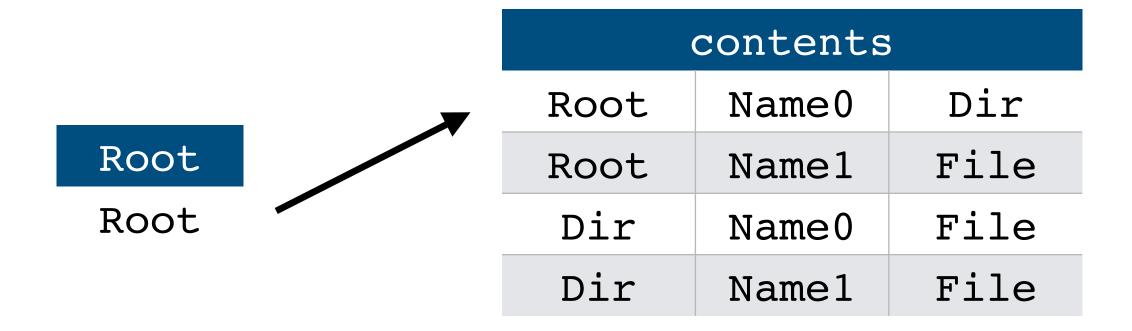
contents		
Root	Name0	Dir
Root	Name1	File
Dir	Name0	File
Dir	Name1	File

Root

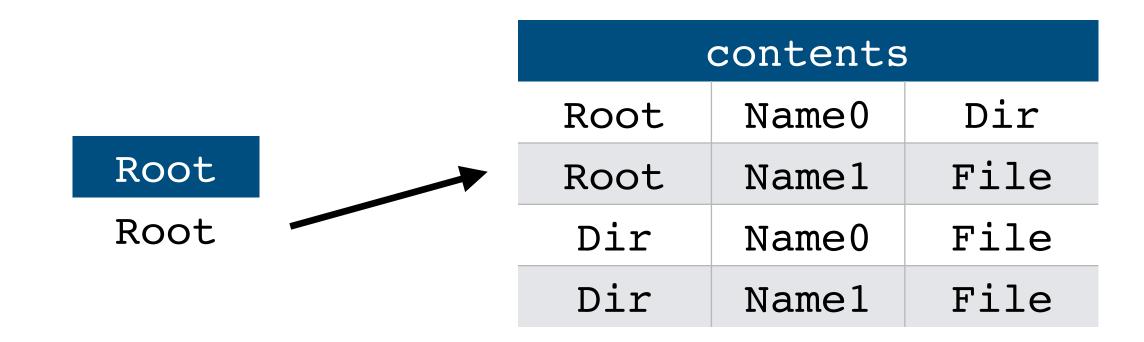
Root

contents		
Root	Name0	Dir
Root	Name1	File
Dir	Name0	File
Dir	Name1	File

Root . contents



Root .	contents
Name0	Dir



Root .	contents
Name0	Dir
Name1	File

Root

Root

contents		
Root	Name0	Dir
Root	Name1	File
Dir	Name0	File
Dir	Name1	File

Root .	contents
Name0	Dir
Name1	File

## Ternary relation example

```
fact {
   // All objects except the root are contained in at least one directory
  all o: Object - Root | some contents.o
  no contents.Root
   // All directories are contained in at most one directory
  all d : Dir | lone contents.d
  // A directory cannot be contained in itself
  all d : Dir | d not in d.^(???)
```

#### Comprehension

$$\{ x_1: A_1, \dots, x_n: A_n \mid \phi \}$$

$$\{ x_1: A_1, \dots, x_n: A_n \mid \phi \} (y_1, \dots, y_n)$$

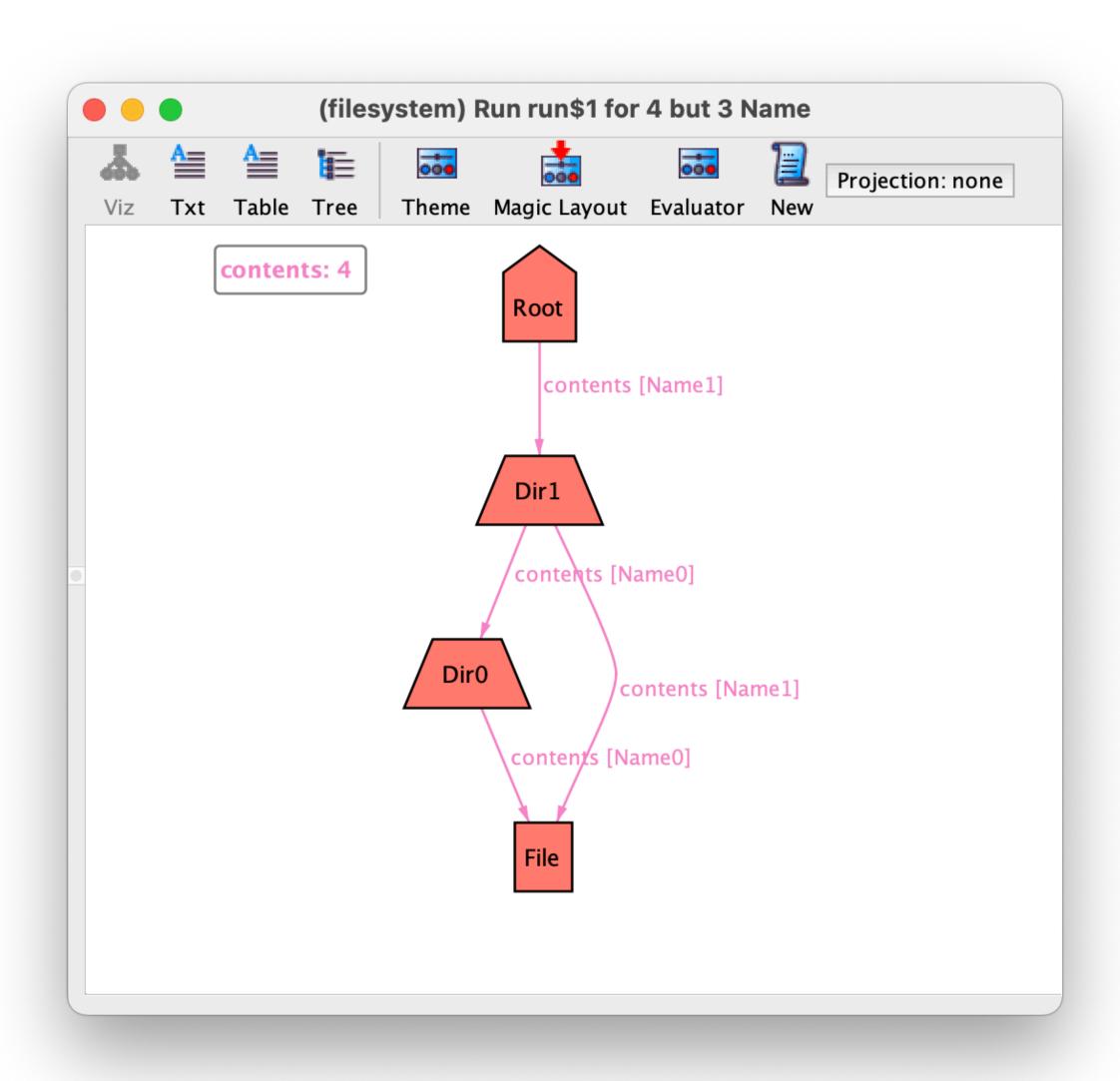
$$\leftrightarrow$$

$$A_1(y_1) \wedge \dots \wedge A_n(y_n) \wedge \phi[x_1 \leftarrow y_1, \dots, x_n \leftarrow y_n]$$

## Ternary relation example

```
fact {
  // All objects except the root are contained in at least one directory
  all o: Object - Root | some contents.o
  no contents.Root
   // All directories are contained in at most one directory
  all d : Dir | lone contents.d
  // A directory cannot be contained in itself
  all d: Dir | d not in d.^({d: Dir, o: Object | some d.contents.o})
```

## Visualising N-ary relations



# Overloading

## Overloading

- Fields in disjoint signatures can be overloaded (have the same name)
- Ambiguity errors may occur

## Overloading example

```
abstract sig Object {}
sig Dir extends Object {
  contents : set Entry
sig File extends Object {}
one sig Root extends Dir {}
sig Entry {
  contents : one Object,
  name : one Name
sig Name {}
```

## Overloading example

```
fact {
  // All objects except the root are contained in at least one entry
  all o: Object - Root | some contents.o
  no contents.Root
  // All directories are contained in at most one entry
  all d: Dir | lone contents.d
  // Different entries in a directory must have different names
  all d: Dir, n: Name | lone (d.contents & name.n)
  // A directory cannot be contained in itself
  all d: Dir | d not in d.^(contents.contents)
```

## Ambiguity errors

```
run { some contents }
```

```
A type error has occurred:
This name is ambiguous due to multiple matches:
field this/Dir <: contents
field this/Entry <: contents
```

## Resolving ambiguities

```
run { some d : Dir | some d.contents }
run { some contents & Dir->Entry }
run { some Dir <: contents }</pre>
```

#### Predicates and functions

#### Predicates

- Predicates are parametrised reusable constraints
  - Can also be derived propositions (without arguments)
  - Parameters can be arbitrary relations
- Only hold when invoked in a fact, command, or other predicates
- Recursive definitions are not allowed
- Run commands can directly ask for an instance satisfying a predicate
  - Atoms instantiating the parameters are shown in the visualiser

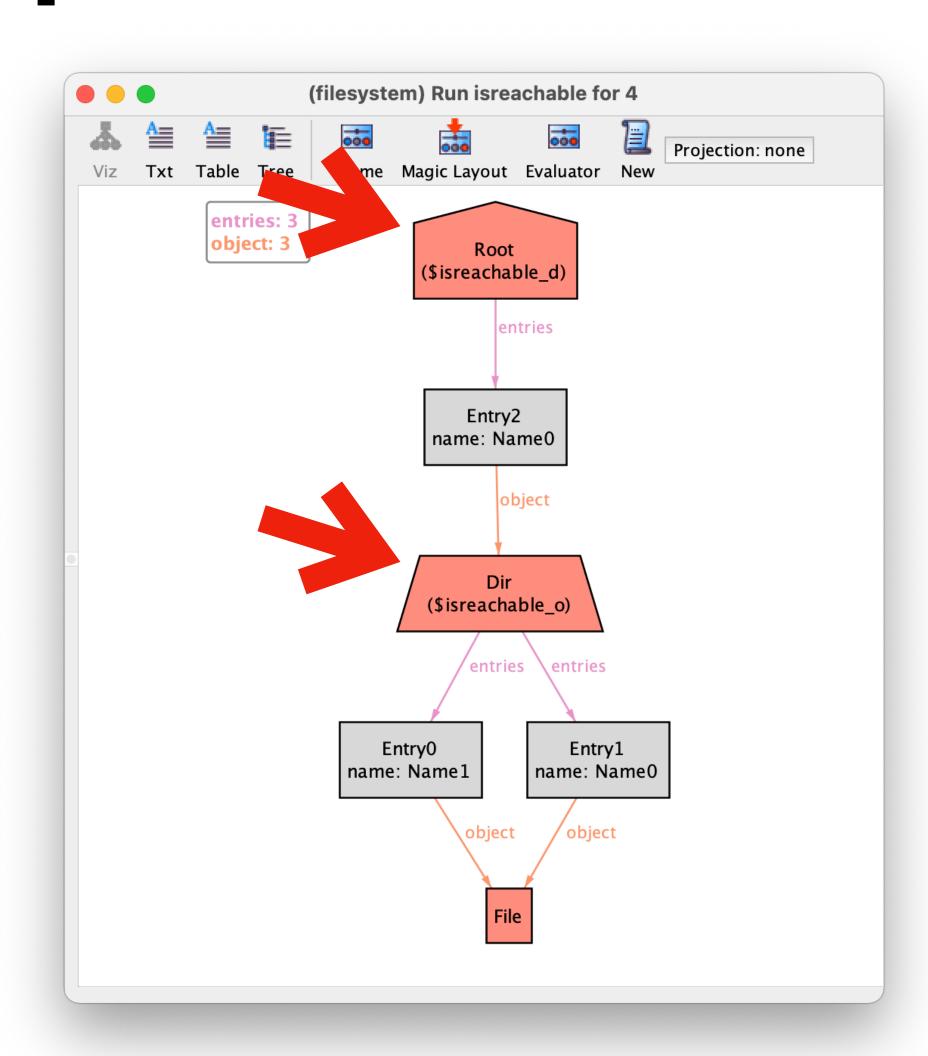
#### Predicate example

```
pred isreachable [d : Dir, o : Object] {
   o in d.^(entries.object)
}

fact {
   // A directory cannot be contained in itself
   all d : Dir | not isreachable[d,d]
}
```

## Running a predicate

run isreachable for 4



## Higher-order predicate example

```
pred acyclic [r : univ -> univ] {
   no ^r & iden
}

fact {
   // A directory cannot be contained in itself
   acyclic[entries.object]
}
```

#### Functions

- Functions are parametrised reusable expressions
  - Parameters can be arbitrary relations
- Functions without parameters can be used to define derived relations
  - These show up in the visualiser
- Recursive definitions are not allowed

#### Function example

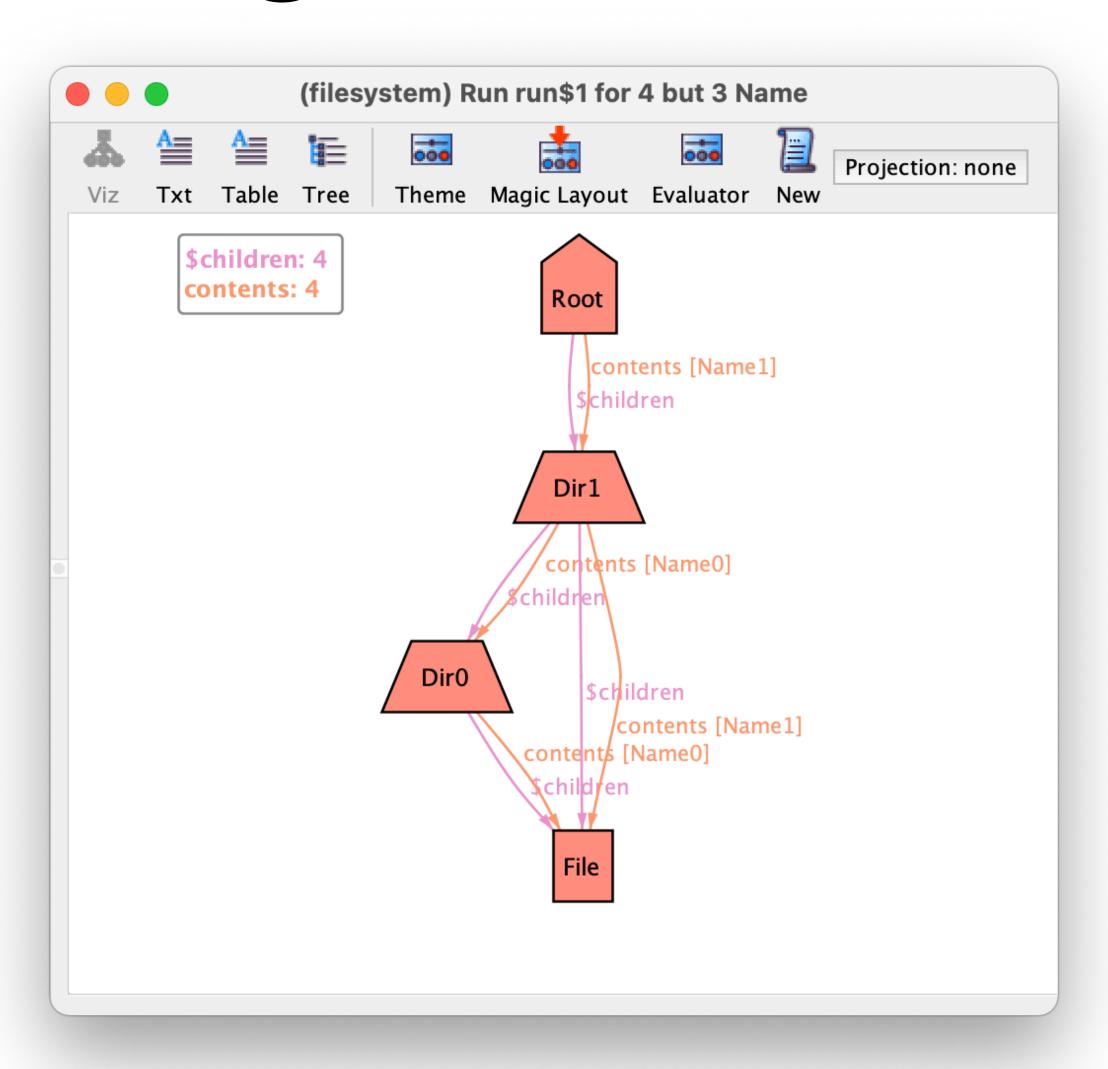
```
fun descendants [d : Dir] : set Object {
   d.^(entries.object)
}

fact {
   // A directory cannot be contained in itself
   all d : Dir | d not in descendants[d]
}
```

## Derived relation example

```
sig Dir extends Object {
  contents: Name -> lone Object
fun children : Dir -> Object {
  { d : Dir, o : Object | some d.contents.o }
fact {
  // A directory cannot be contained in itself
  all d: Dir | d not in d.^children
```

# Visualising derived relations



#### Modules

#### Modules

- A model can be split into modules
- A module name is declared in the first line with keyword module
- A module can be imported with an open statement
- A module name must match the path of the corresponding file
- To disambiguate a call to an entity, the module name can be prepended
- An alias to a module name can be given with the as keyword in an open statement
- A module can be parametrised by one or more signatures

#### Module example

```
module relation

pred acyclic [r : univ -> univ] {
   no ^r & iden
}
```

## Module example

```
open relation

fact {
    // A directory cannot be contained in itself
    acyclic[entries.object]
}
```

## Parametrised module example

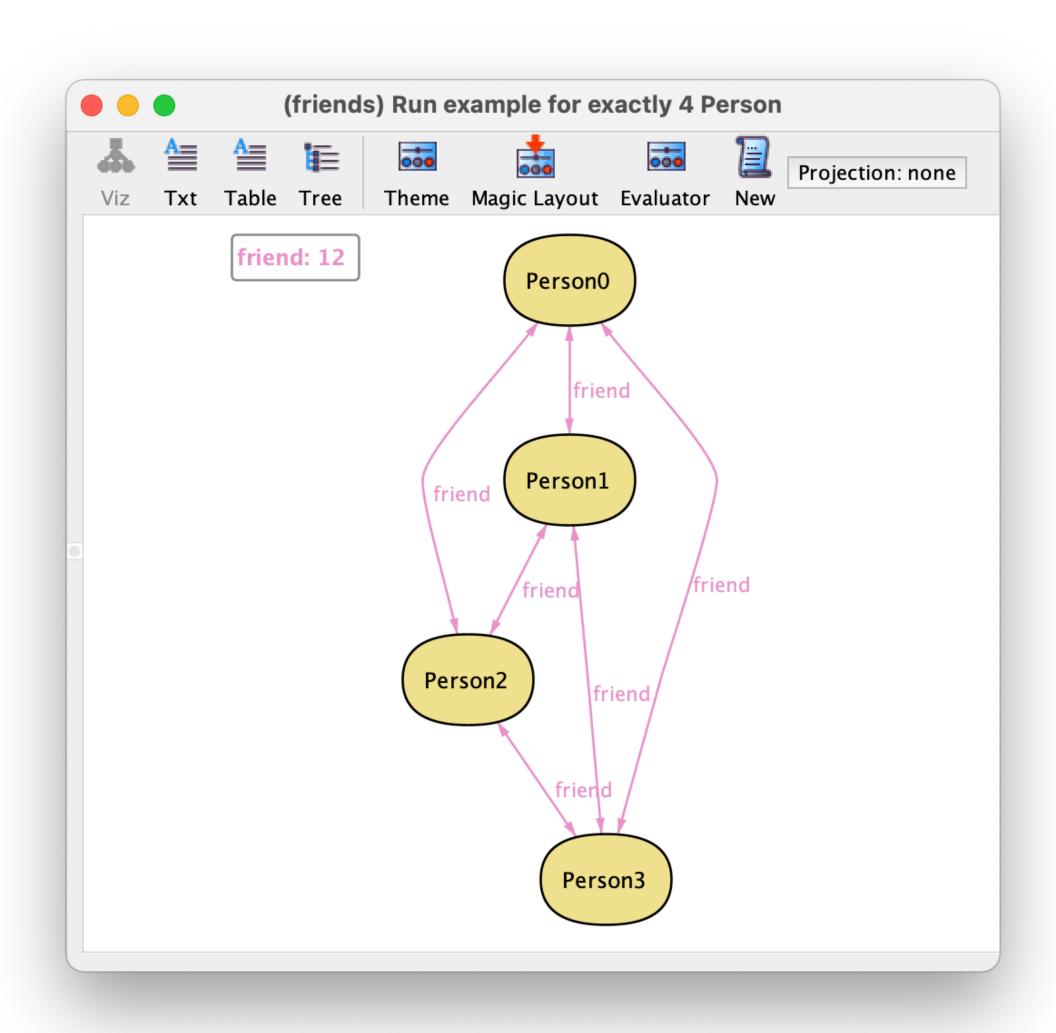
```
module graph[node]

pred complete[adj : node -> node] {
   all n : node | n.adj = node-n
}
```

## Parametrised module example

```
open graph[Person]
sig Person {
  friend : set Person
}
fact { complete[friend] }
```

#### We are all friends



#### Predefined modules

util/relations Useful functions and predicates for binary relations

util/ternary Useful functions and predicates for ternary relations

util/graph[A] Useful functions and predicates for graphs with nodes from signature A

util/natural Natural numbers, including some arithmetic operations

util/boolean Boolean type, including common logical connectives

util/ordering[A] Imposes a total order on signature A

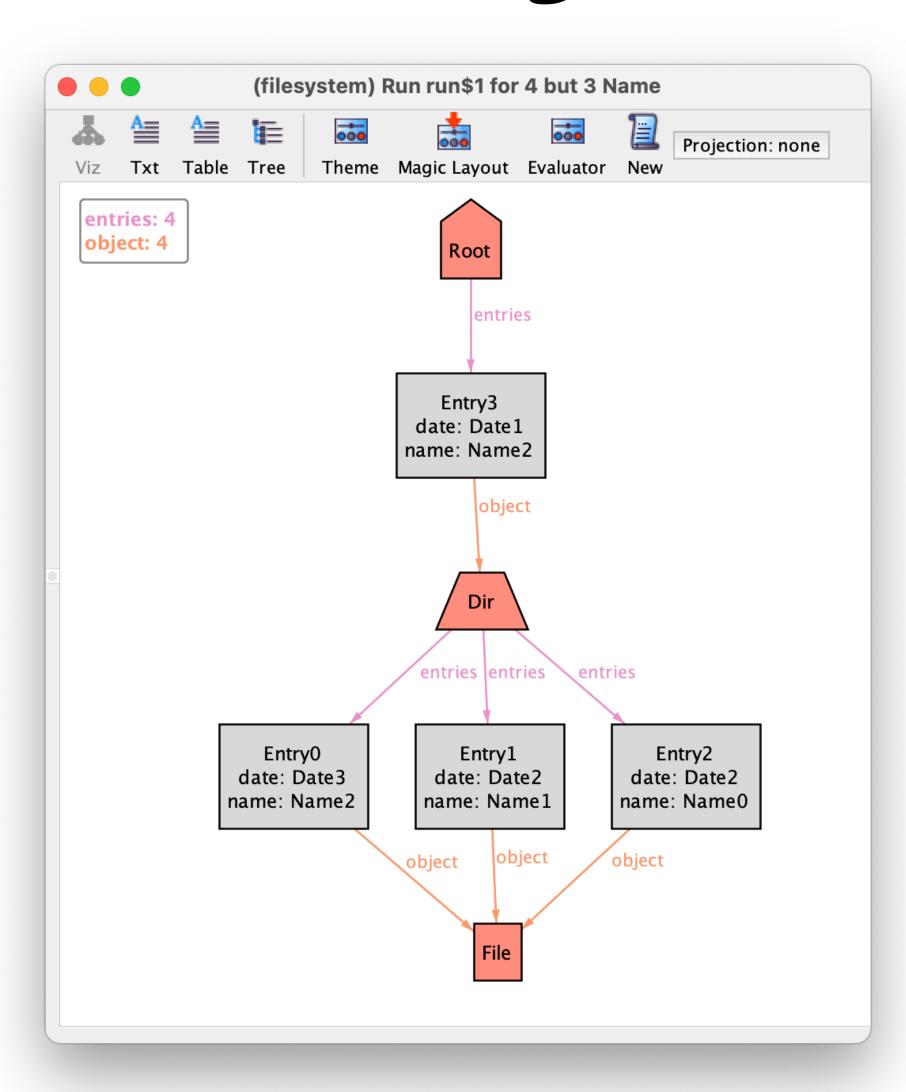
#### util/ordering

- Imposes a total order on the parameter signature
- For efficiency reasons the scope on that signature becomes exact
- Visualiser attempts to name atoms according to the order
- Many useful functions and relations, including
  - next and prev binary relations
  - first and last singleton sets
  - lt, lte, gt, and gte comparison predicates

## util/ordering example

```
open util/ordering[Date]
sig Date {}
sig Entry {
  object : one Object,
  name : one Name,
  date : one Date
fact {
  // Entries inside a directory must have been created later
  all e : object.Dir, c : e.object.entries | lt[e.date, c.date]
```

# util/ordering visualisation



# Type system

# File-system

```
abstract sig Object {}
sig Dir extends Object {
  contents: set Entry
sig File extends Object {}
one sig Root extends Dir {}
sig Entry {
  contents : one Object,
  name : one Name
sig Name {}
```

# Arity error

```
run { some name & File }
```

#### A type error has occurred:

```
& can be used only between 2 expressions of the same arity.

Left type = {this/Entry->this/Name}

Right type = {this/File}
```

# Ambiguity error

```
run { some contents }
```

#### A type error has occurred:

```
This name is ambiguous due to multiple matches: field this/Dir <: contents field this/Entry <: contents
```

# Irrelevance warning

```
run { some Dir.name }
```

```
Warning #1
The join operation here always yields an empty set.
Left type = {this/Dir}
Right type = {this/Entry->this/Name}
```

## Type system

- The main goal of Alloy's type system is to detect irrelevant expressions
- An expression is irrelevant if it can be replaced by none
- The same type system can be used to resolve overloading
  - An overloaded name is treated as the union of all respective relations
  - Only one of the overloaded relations must be relevant

## Types

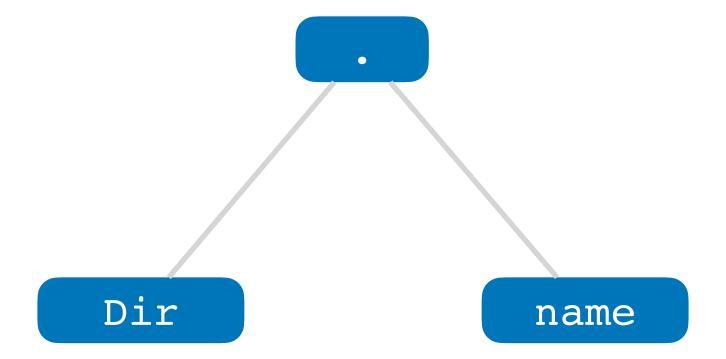
- The type of an expression is a set of tuples of atomic of atomic types
  - An atomic type is a signature that is not further extended
- For non abstract signatures we need a reminder type
  - The reminder contains all atoms not contained in one of the extensions
  - The reminder type of signature A is denoted as \$A
- The type of an expression is an upper-bound on its value
  - If the type of an expression is empty, the expression is irrelevant

#### Type inference

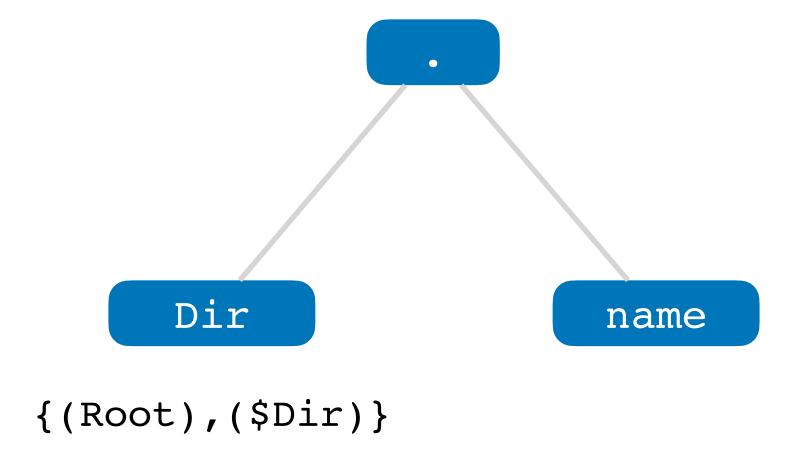
- Type inference is guided by the abstract syntax and works in two phases
  - A bottom-up phase computes the bounding types
  - A top-down phase refines these and computes the relevance types
- Unlike bounding types, relevance types depend on the context
  - The same expression in different formulas may have different types

- The bounding type of a signature or field is inferred from the respective declarations
- The bounding type of an expression is computed using the same relational operator applied to the bounding types of sub-expressions
  - This is possible because types are also relations

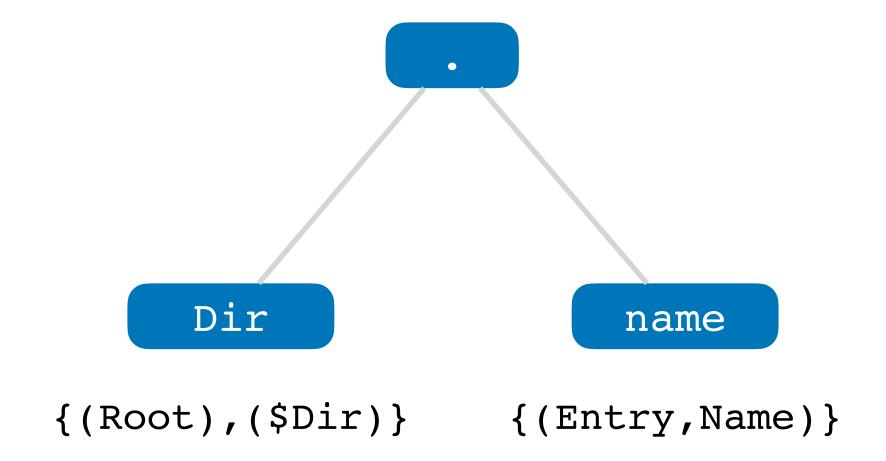
Dir.name



Dir.name

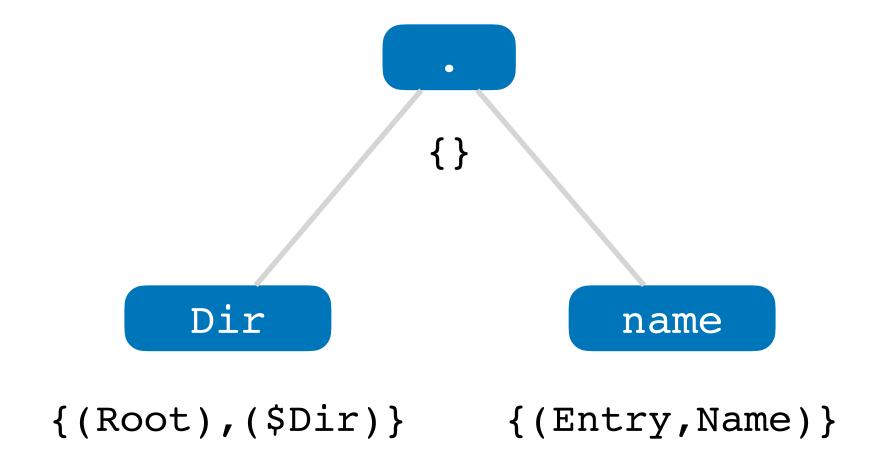


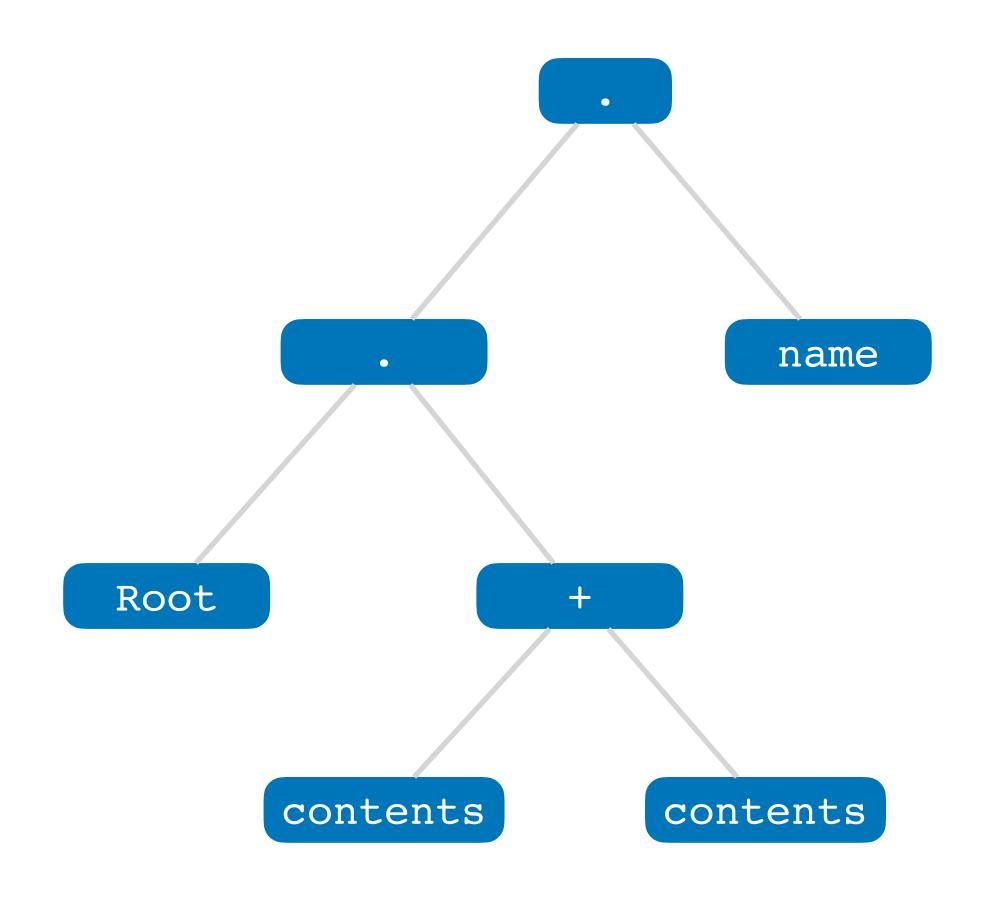
Dir.name

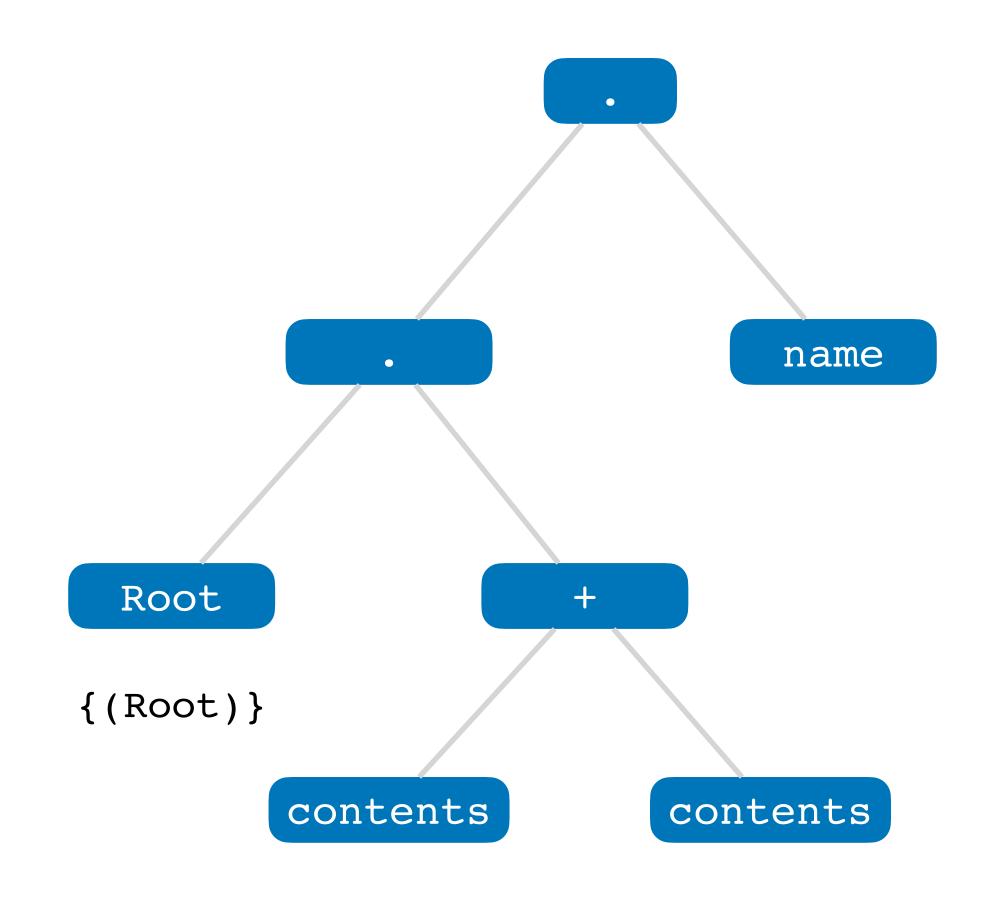


Dir.name

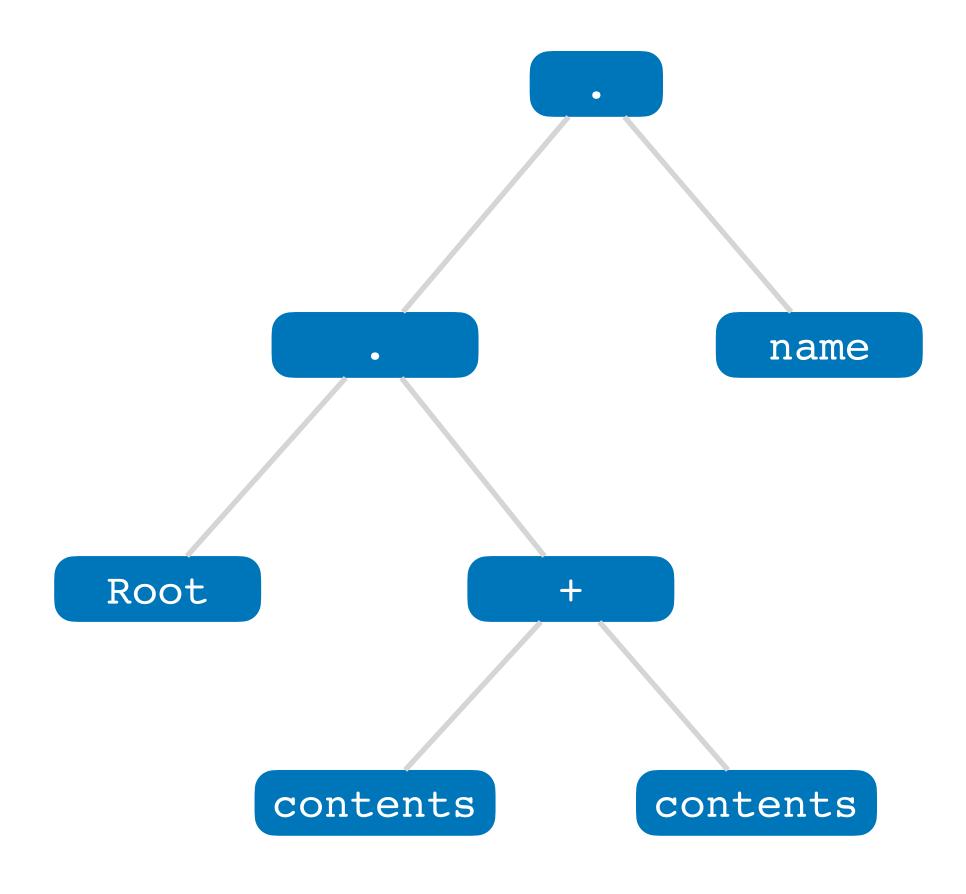
Dir.name



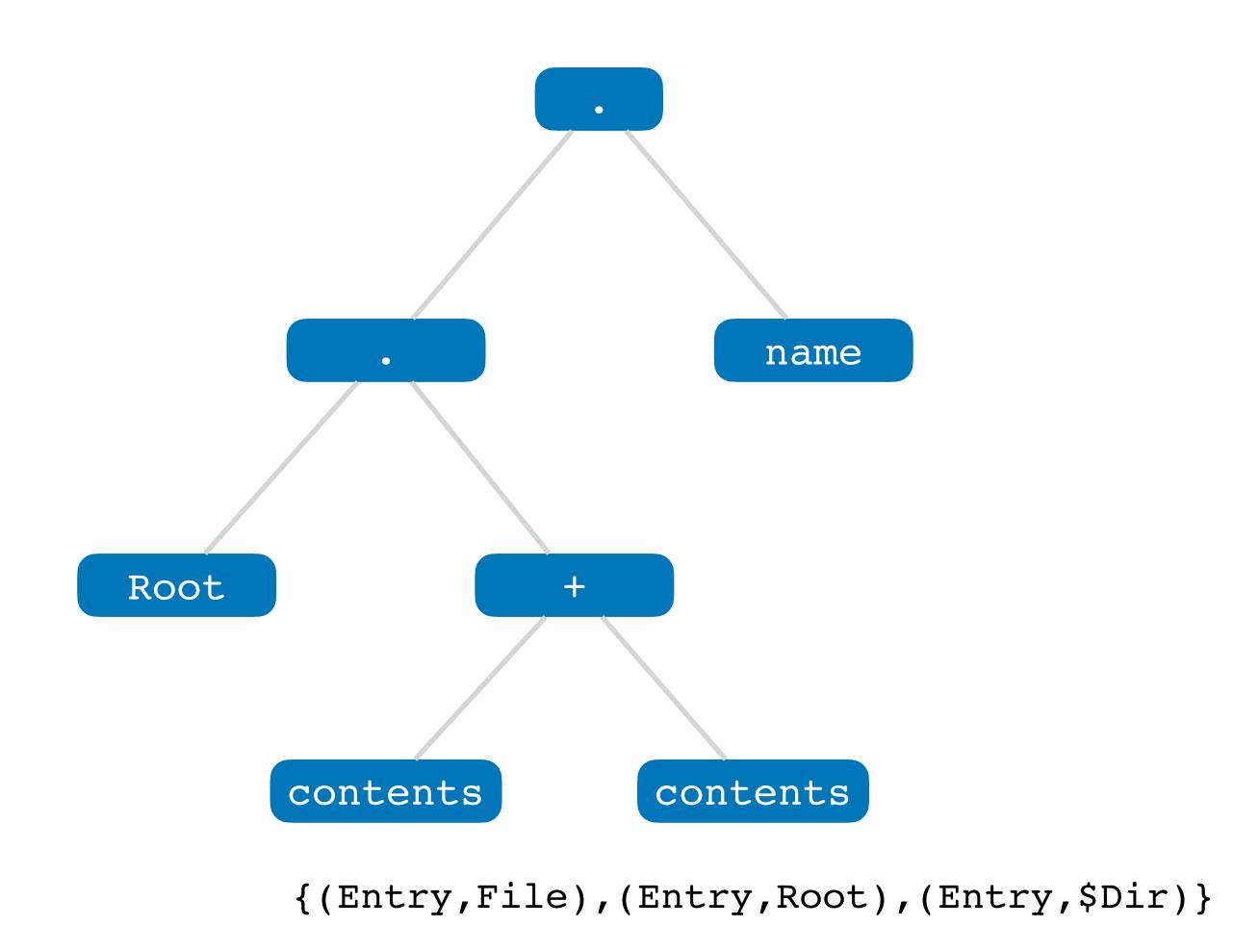


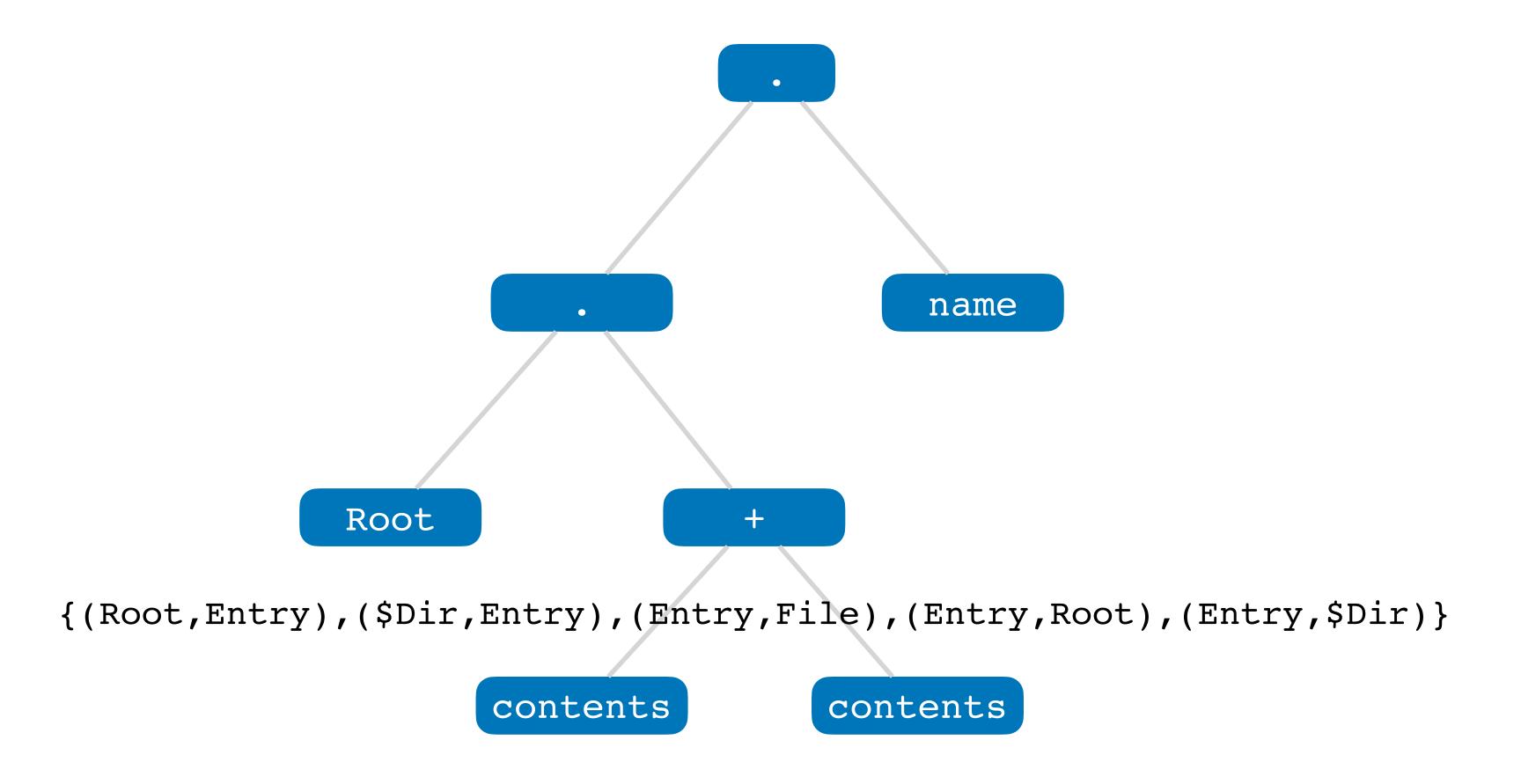


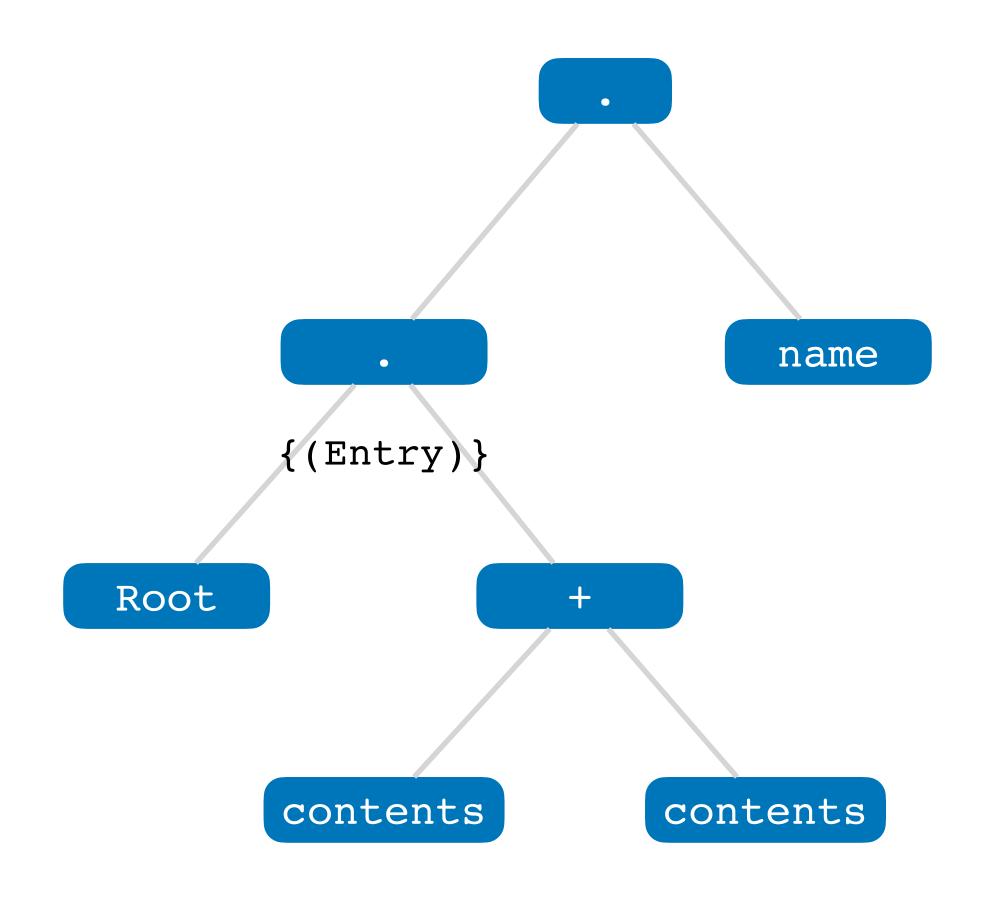
(Root.content).name

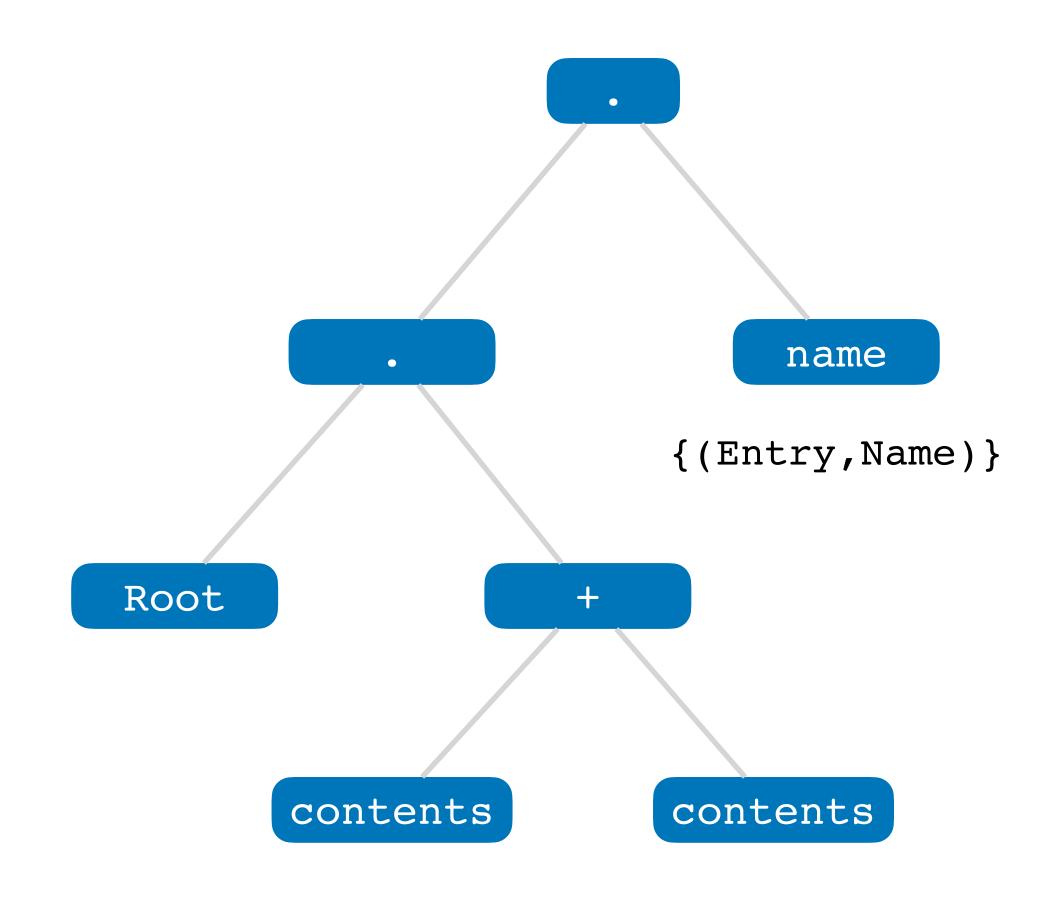


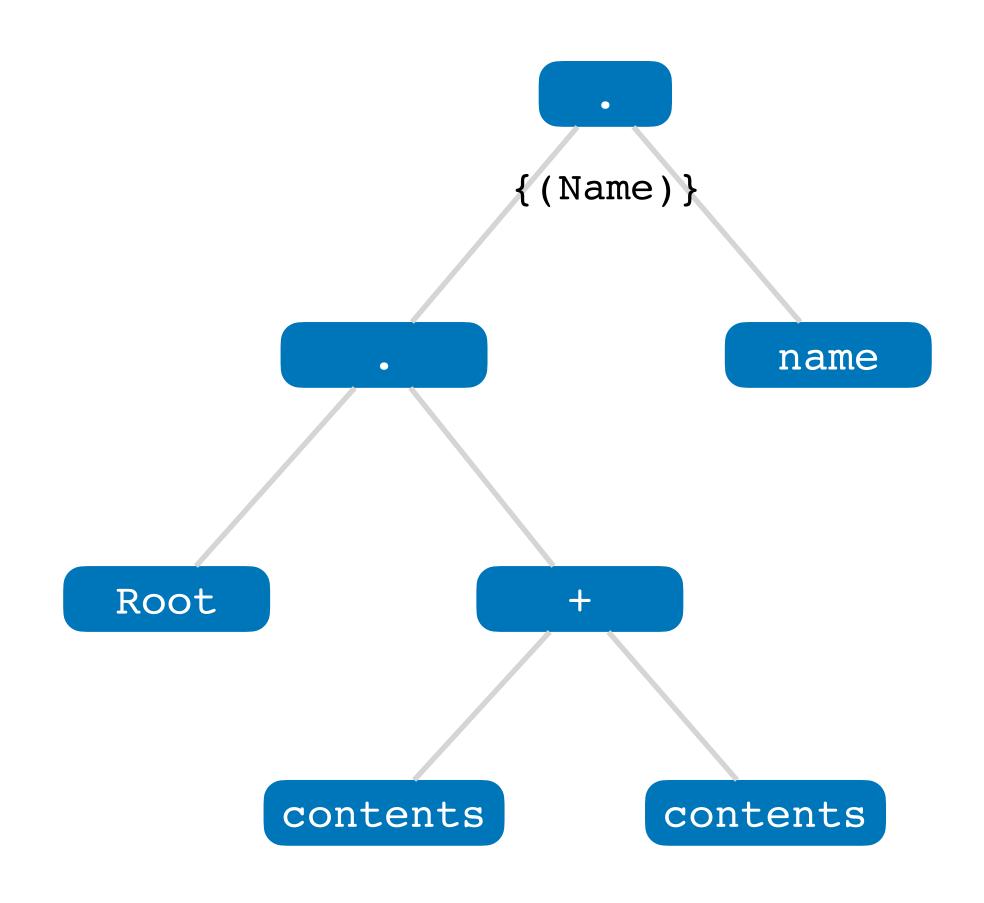
{(Root, Entry), (\$Dir, Entry)}





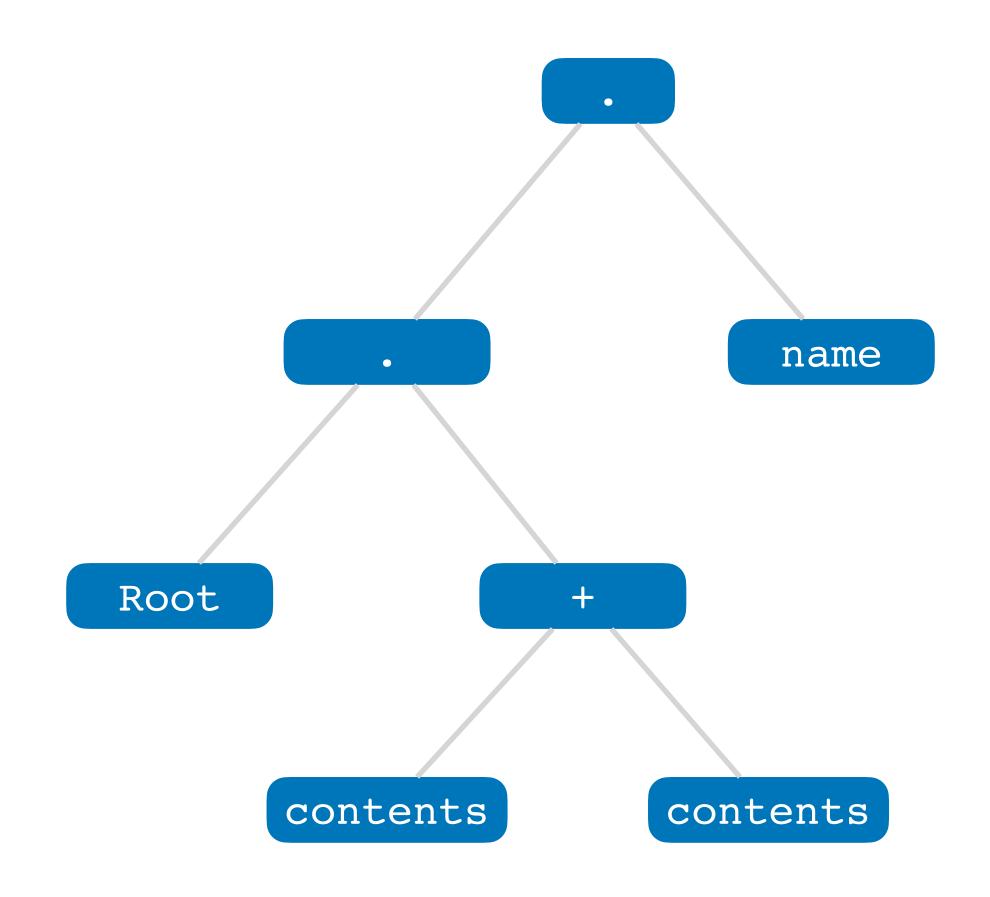


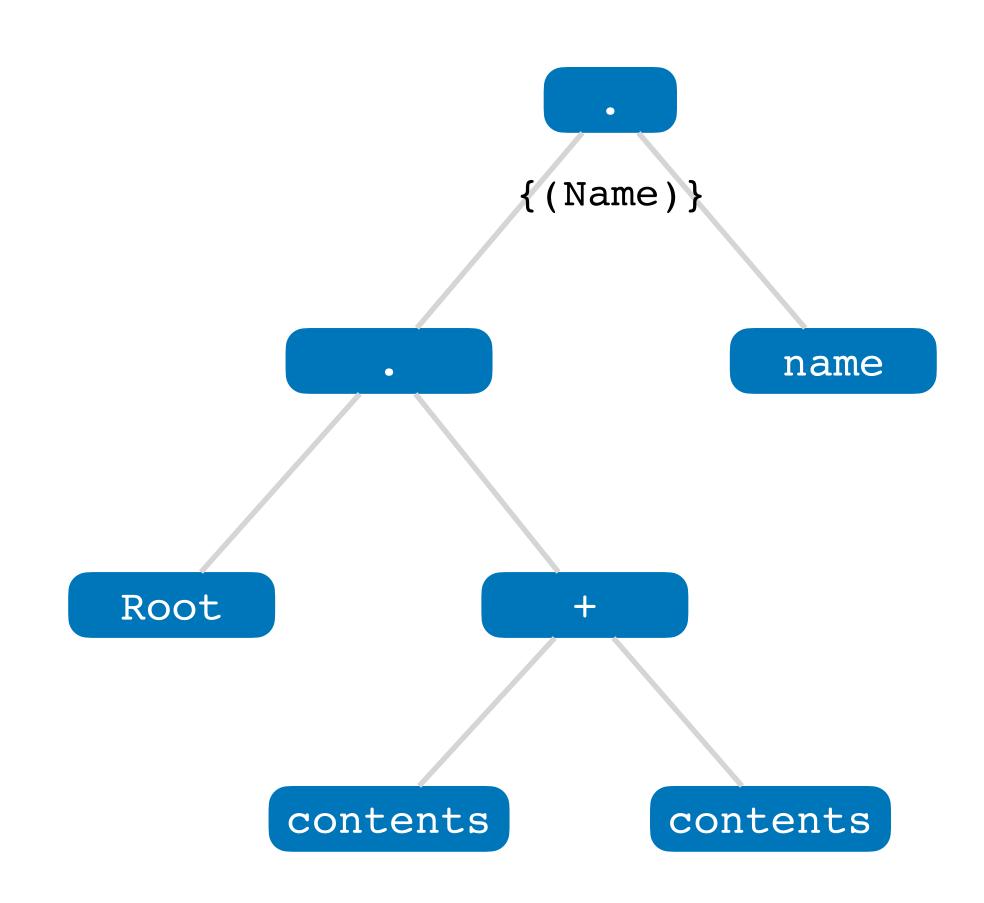


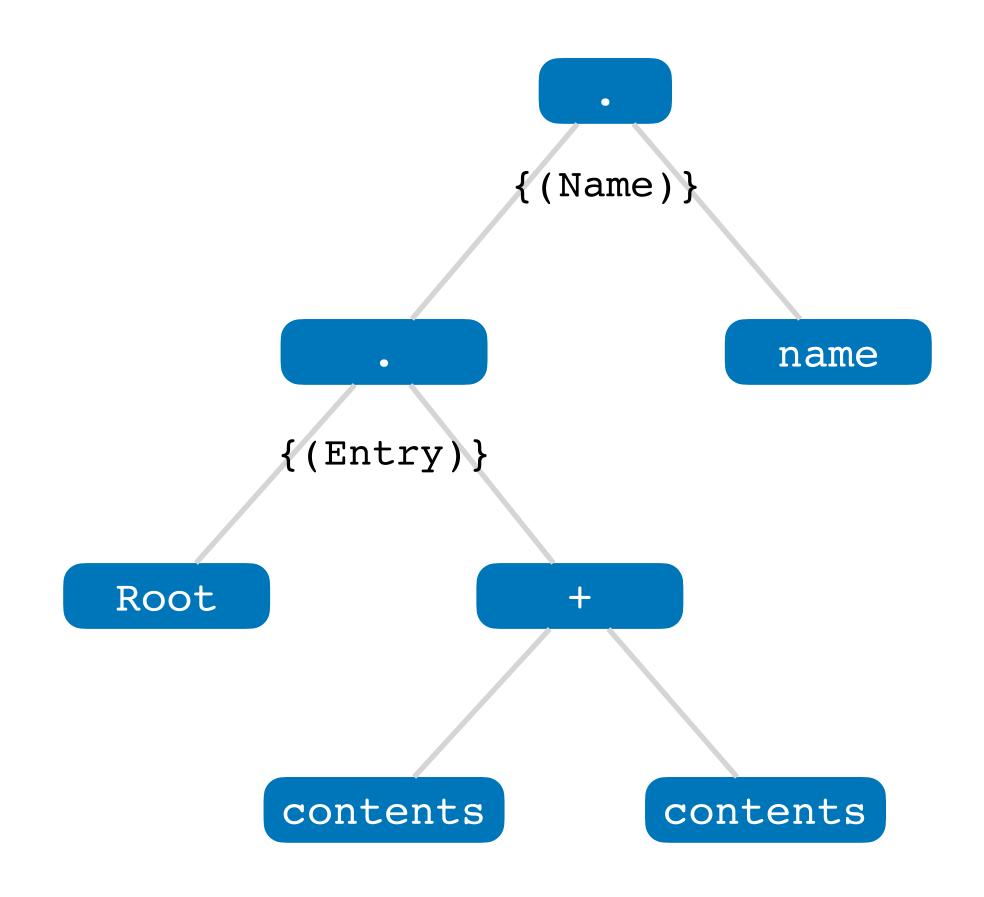


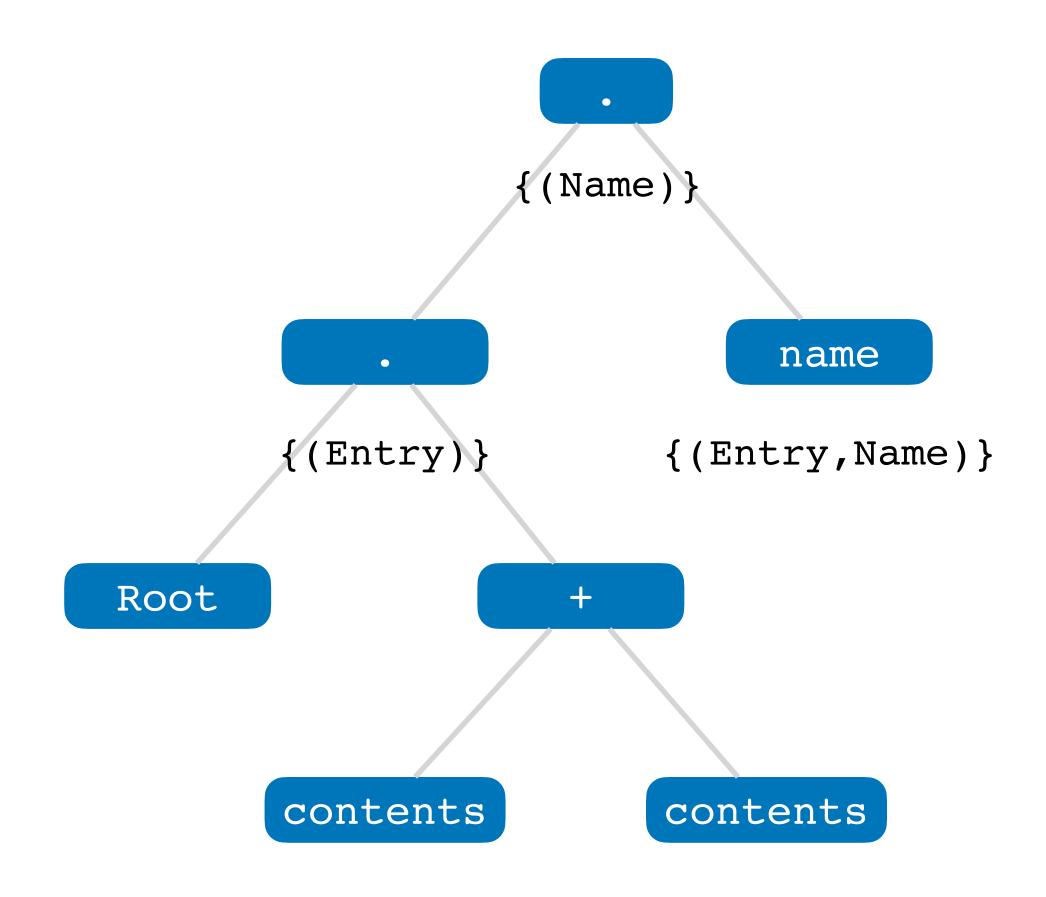
#### Relevance type inference

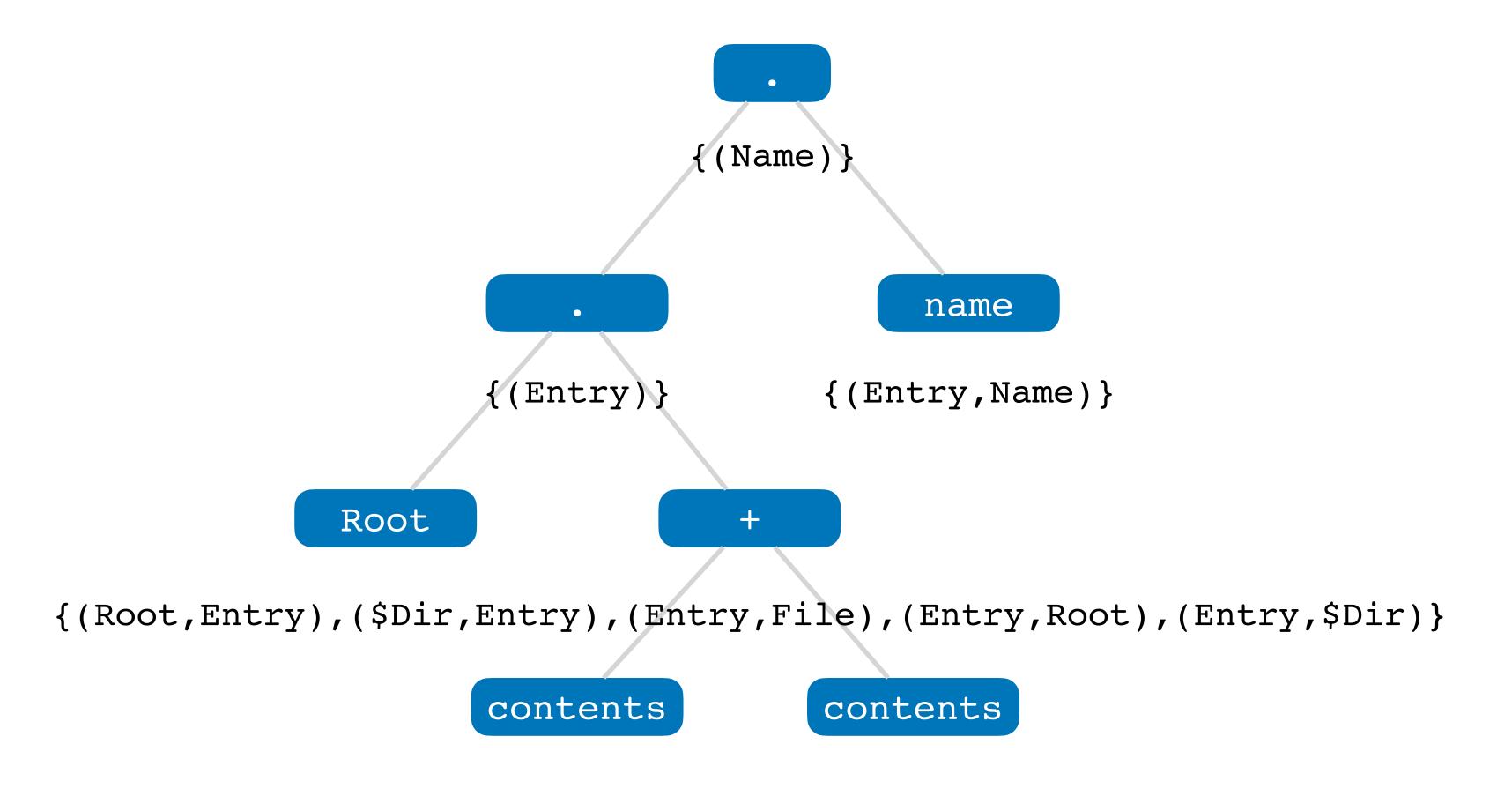
- The relevance type of the top expression is equal to its bounding type
- The relevance type of a sub-expression is computed by determining which tuples effectively contributed to the parent expression type

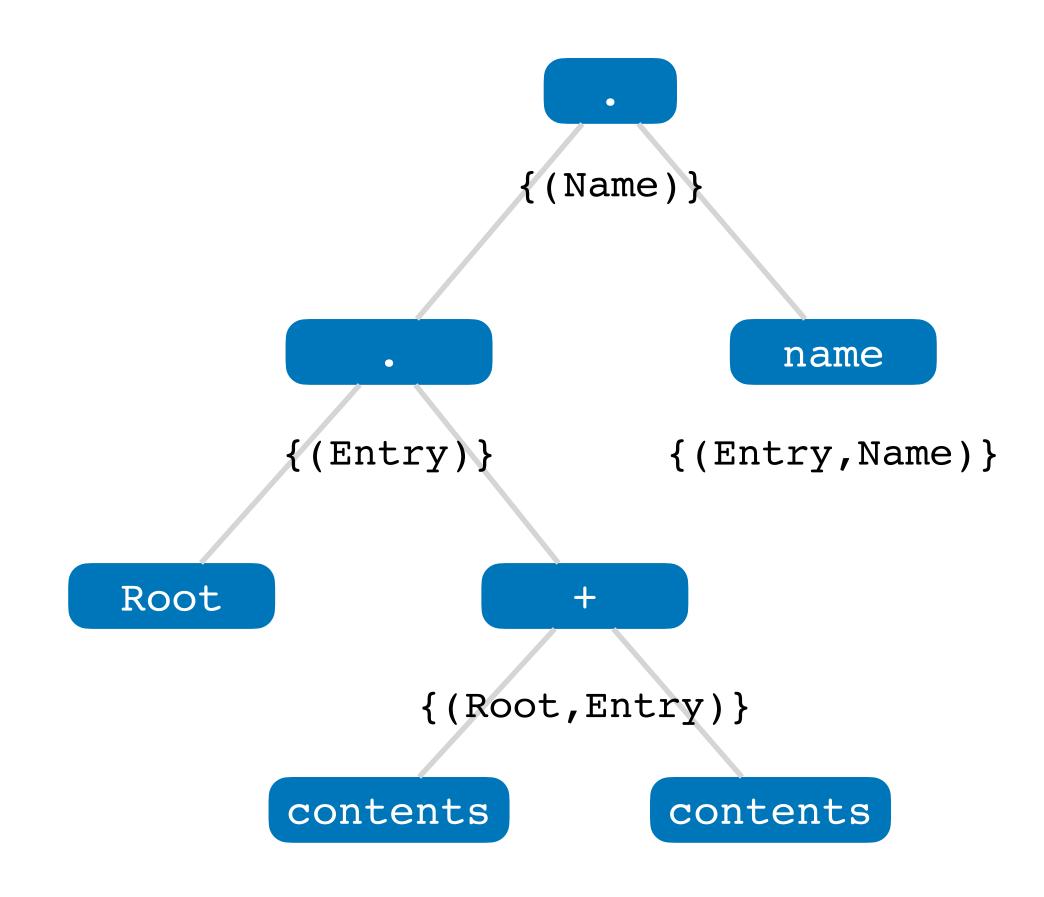


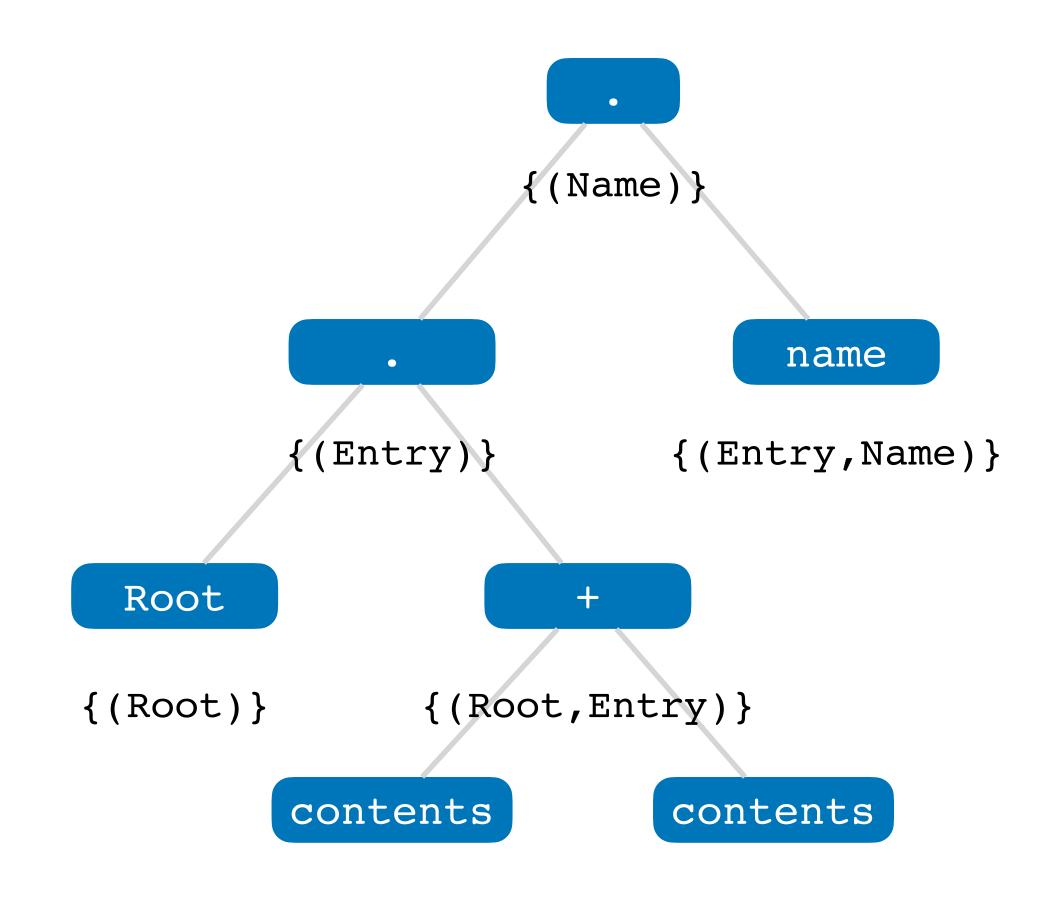


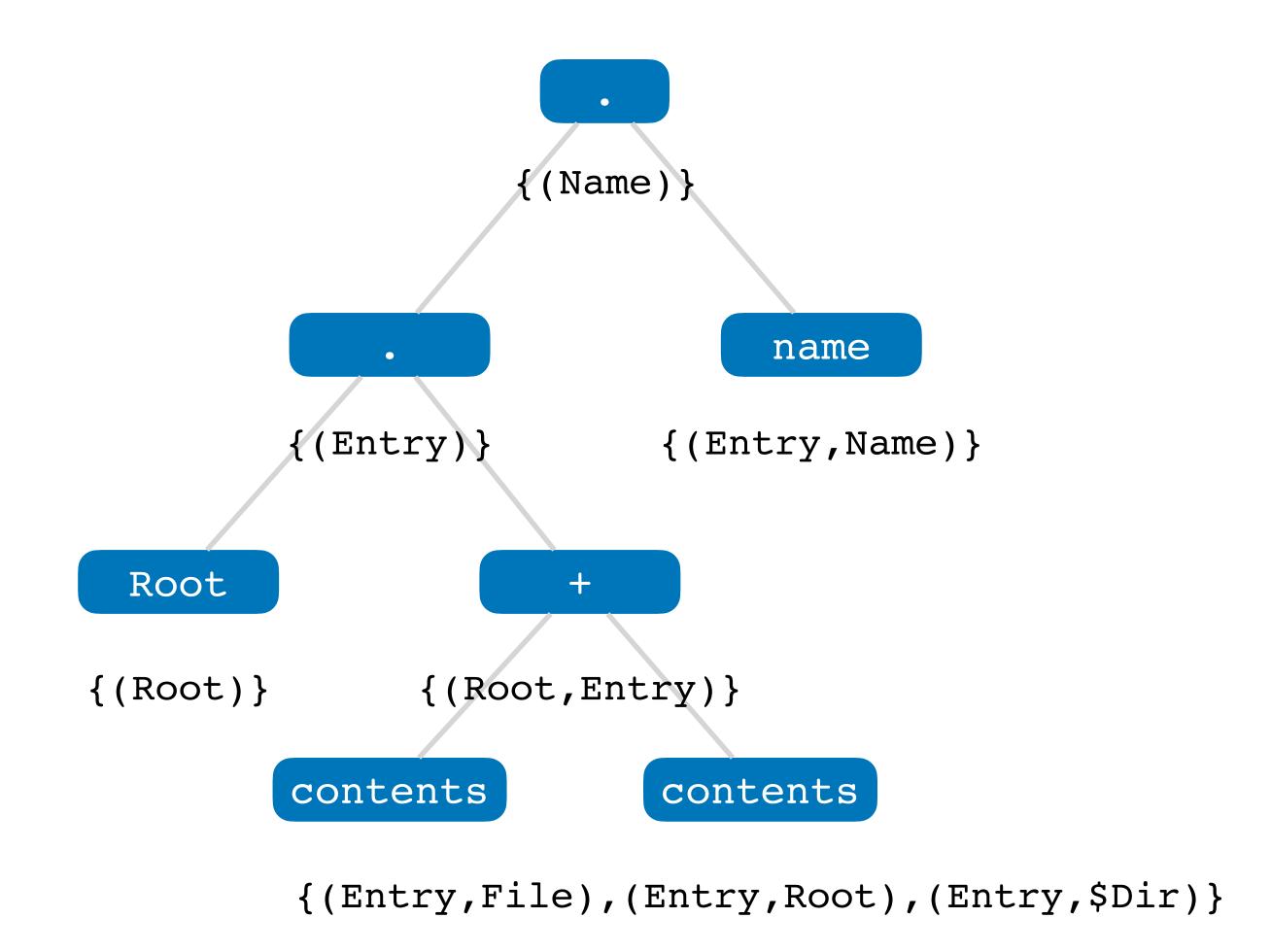


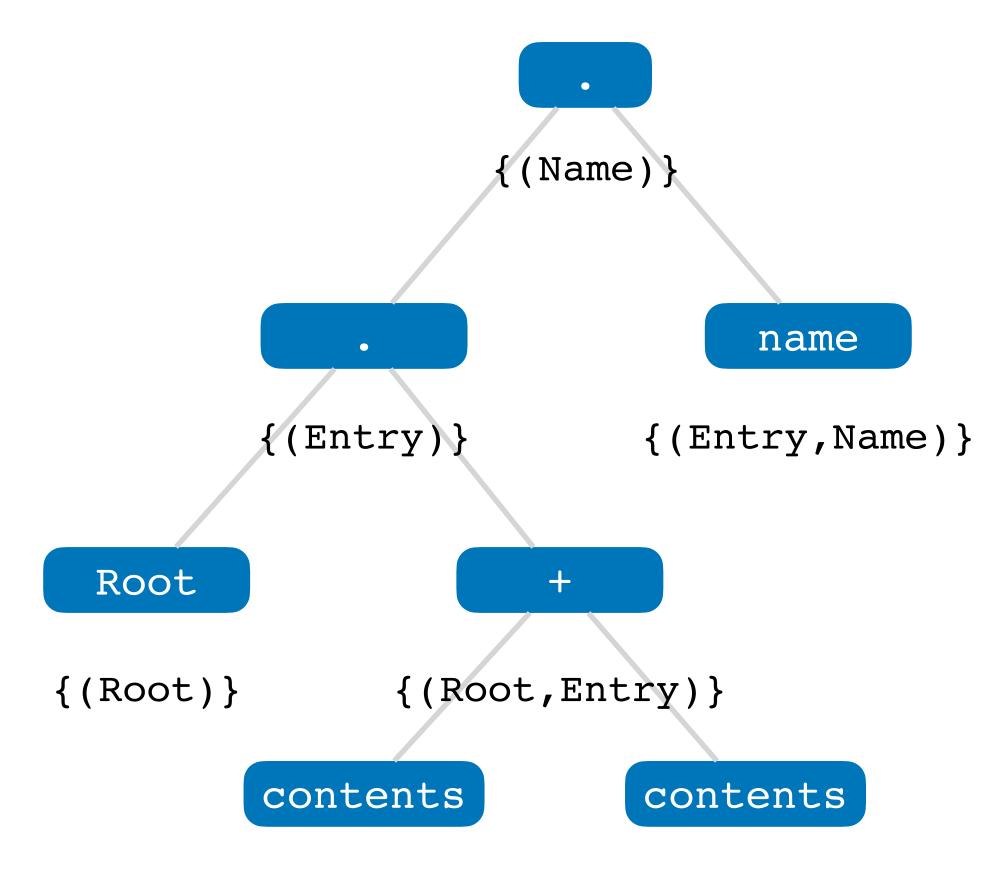


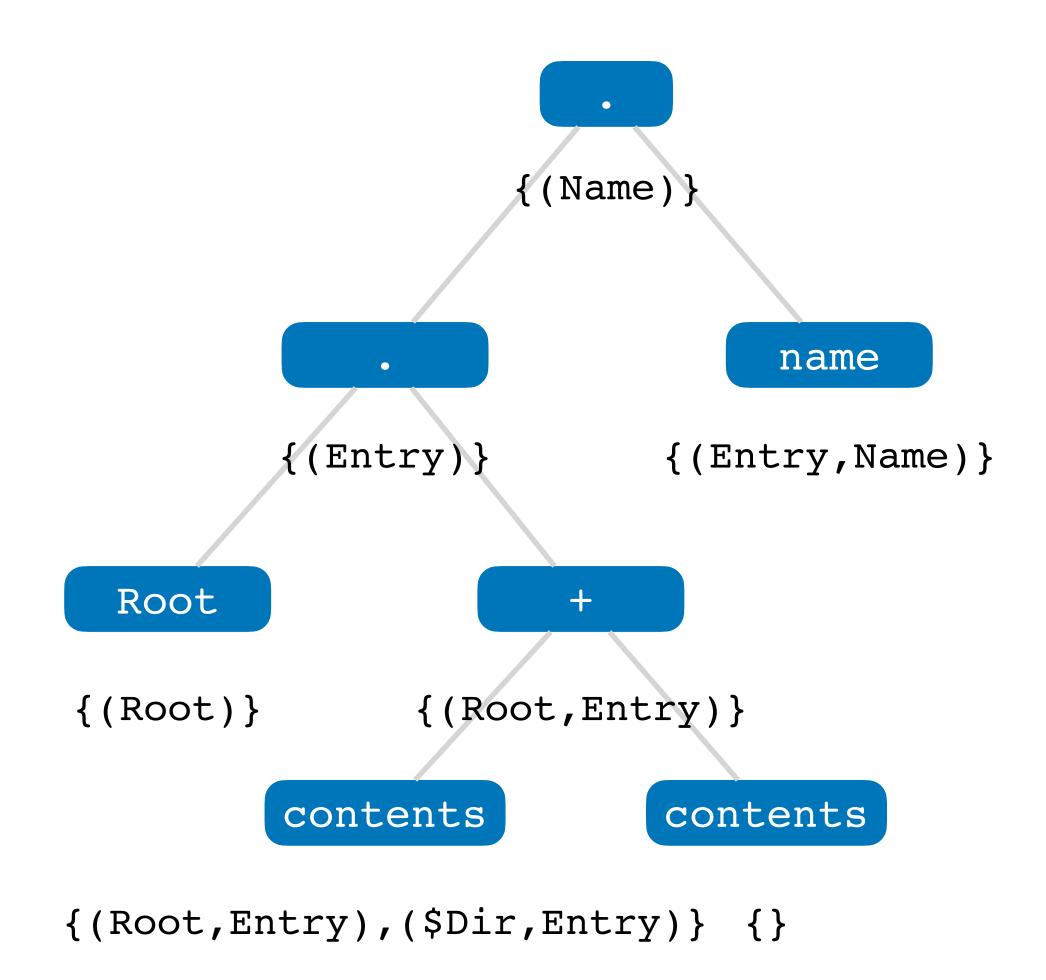


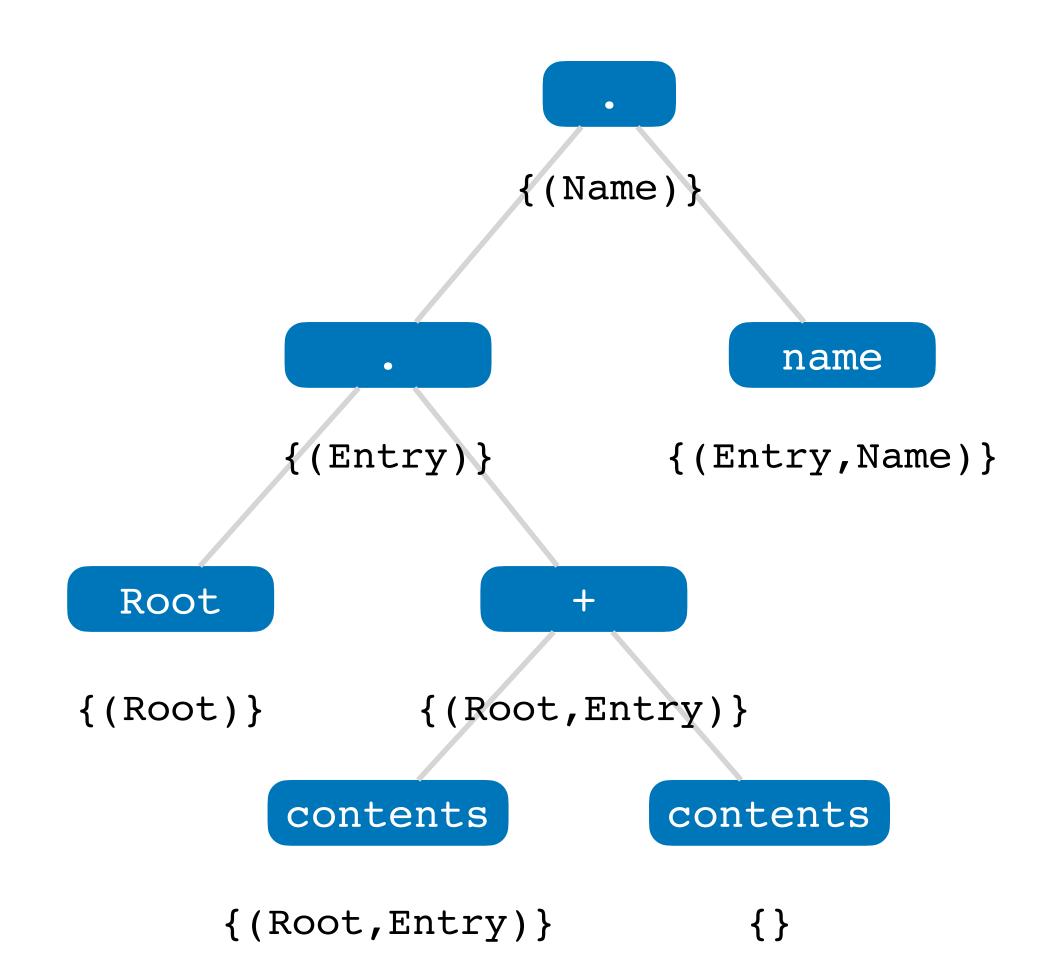












# Relational model finding

### Architecture



### Kodkod

- A Kodkod problem consists of
  - A universe of atoms  $\mathscr{U}$
  - A set of relation declarations of shape  $r:_a r_L r_U$ 
    - a is the arity of r
    - $r_L$  is the *lower-bound* of r, tuples that MUST be present in r
    - $r_U$  is the *upper-bound* of r, tuples that MAY be present in r
  - A relational logic formula  $\phi$

### Kodkod

- Kodkod is a relational model finder
- It finds a valuation (a model) for the relations such that
  - $\phi$  is true in that model
  - the valuation of each relation r complies with the partial-knowledge declared in the bounds

# Alloy \Rightarrow Kodkod

- Alloy assertions to be checked are negated and conjoined with the facts in the Kodkod formula
  - An assertion is valid if its negation is unsatisfiable
- Alloy fields and atomic signatures are declared in the Kodkod problem
  - Non-atomic signatures are aliased to a disjunction of atomic ones
- Appropriate bounds are inferred from scopes
  - Upper-bounds can be shared between related atomic signatures
    - Further constraints must be added to ensure a sound structural semantics
  - Kodod atom names are meaningless
    - When building an Alloy instance from a Kodkod instance atoms are renamed

# Alloy example

```
abstract sig Object {}
sig Dir extends Object {
  entries: set Entry
sig File extends Object {}
one sig Root extends Dir {}
sig Entry {}
run { some entries.Entry } for 3 but 2 Entry
```

### Kodkod translation

```
{A,B,C,D,E}
Dir :_{1} { (A), (B) }
File :<sub>1</sub> {} {(A),(B)}
Root : \{(C)\}
Entry : \{ \} \{ (D), (E) \}
entries:<sub>2</sub> {} {(A,D),(A,E),(B,D),(B,E),(C,D),(C,E)}
no File & $Dir
all x : $Dir+Root | x.entries in Entry
entries.univ in $Dir+Root
some entries. Entry
```

• A relation r of arity a can be represented by a matrix of boolean variables of size  $\|\mathcal{U}\|^a$ 

$$r[i_1,...,i_a] = \begin{cases} \top & \text{if } (\mathcal{U}_{i_1},...,\mathcal{U}_{i_a}) \in r_L \\ r_{i_1,...,i_a} & \text{if } (\mathcal{U}_{i_1},...,\mathcal{U}_{i_a}) \in r_U \backslash r_L \\ \bot & \text{otherwise} \end{cases}$$

$$\mathtt{\$Dir} = \begin{bmatrix} d_A \\ d_B \\ \bot \\ \bot \\ \bot \end{bmatrix} \quad \mathtt{File} = \begin{bmatrix} f_A \\ f_B \\ \bot \\ \bot \\ \bot \end{bmatrix} \quad \mathtt{Root} = \begin{bmatrix} \bot \\ \bot \\ \bot \\ \bot \\ \bot \end{bmatrix} \quad \mathtt{Entry} = \begin{bmatrix} \bot \\ \bot \\ e_D \\ e_E \end{bmatrix}$$

 Relational operators are implemented by matrix operations (in the boolean semiring)

•	Multiplication
+	Addition
&	Hadamard product
•••	

• Atomic formulas originate propositional formulas

in	Conjunction of point-wise implication
some	Disjunction

•••

$$\begin{bmatrix} (r_{A,D} \wedge e_D) \vee (r_{A,E} \wedge e_E) \\ (r_{B,D} \wedge e_D) \vee (r_{B,E} \wedge e_E) \\ (r_{C,D} \wedge e_D) \vee (r_{C,E} \wedge e_E) \\ \bot \\ \bot \end{bmatrix}$$

$$\begin{bmatrix} (r_{A,D} \wedge e_D) \vee (r_{A,E} \wedge e_E) \\ (r_{B,D} \wedge e_D) \vee (r_{B,E} \wedge e_E) \\ (r_{C,D} \wedge e_D) \vee (r_{C,E} \wedge e_E) \\ \bot \\ \bot \end{bmatrix}$$

$$(r_{A,D} \wedge e_D) \vee (r_{A,E} \wedge e_E) \vee (r_{B,D} \wedge e_D) \vee (r_{B,E} \wedge e_E) \vee (r_{C,D} \wedge e_D) \vee (r_{C,E} \wedge e_E)$$

### Quantifiers

Since the universe is finite quantifiers can be handled by expansion

```
all x : Entry | some entries.x

\[
\exists \text{some entries.}\{(D)\}\] and some entries.\{(E)\}\]
```

Unfortunately this yields no witnesses to existential quantifiers

```
some x : Entry | some entries.x

\[
\begin{align*}
\text{some entries.} \{(D)\} \text{ or some entries.} \{(E)\}
\end{align*}
\]
```

### Skolemization

- Skolemization replaces existentially quantified variables by free variables
  - Free variables are implicitly existentially quantified
  - Generates smaller but equisatisfiable formulas
  - Skolemized variables are witnesses that can be shown in the visualiser

```
some x : Entry | some entries.x

\[ \xi :_1 \{\} \{(D),(E)\} \]
one \xi and some entries.\x
```

# Symmetry breaking

- Kodkod performs several optimisations to decrease SAT complexity
- The most significant is symmetry breaking
  - Since atoms are uninterpreted isomorphic instances are equivalent
  - To avoid returning isomorphic instances a symmetry breaking formula is conjoined to the problem formula
  - For efficiency reasons the technique is not complete
- Besides increasing efficiency symmetry breaking is also useful for validation
  - Otherwise the user would be overwhelmed with isomorphic instances