Processes, Threads

CS 5007: Systems

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 - http://www.cs.cmu.edu/afs/cs/academic/class/ 15213-f15/www/lectures/14-ecf-procs.pdf
 - http://www.cs.cmu.edu/afs/cs/academic/class/ 15213-f15/www/lectures/23-concprog.pdf
- Justin Hsia
 - https:

```
//courses.cs.washington.edu/courses/cse333/18sp/
lectures/27/CSE333-L27-processes_18sp-ink.pdf
```

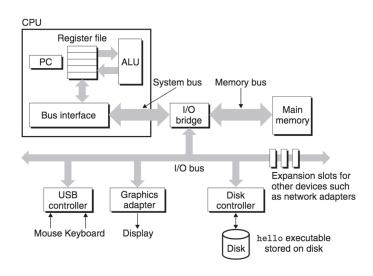
Section 1

Processes

The Big Picture: What is a System?

C application C Standard Library OS/app interface (system calls) **Operating System** HW/SW interface Hardware

Hardware Organization



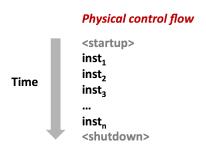
Outline

- Control flow
- Exceptions
- Processes
- Process Control
- Threads

Flow of control

Processors only do one thing:

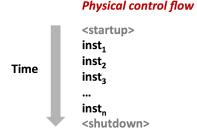
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Flow of control

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- A processor simply reads a sequence of instructions from the start to the finish.
- It's called the control flow



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Exceptional control flow

Processes

Definition: A process is an instance of a running program.

- One of the most profound ideas in computer science
- Not the same as "program" or "processor"

Process provides each program with two key abstractions:

Logical control flow

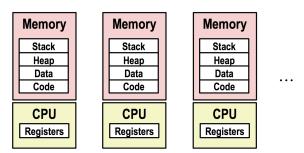
- Each program seems to have exclusive use of the CPU
- Provided by kernel mechanism called context switching

Private address space

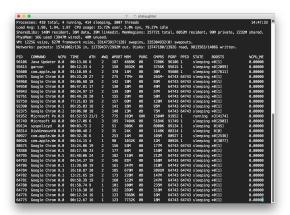
- Each program seems to have exclusive use of main memory.
- Provided by kernel mechanism called virtual memory



The Illusion of Multiprocessing



- Computer runs many processes simultaneously
 - Applications for one or more users
 - Web browsers, email clients, editors, ...
 - Background tasks
 - Monitoring network and I/O devices



- Running program "top" on Mac
 - System has 418 processes, 4 of which are active
 - Identified by Process ID (PID)



htop

■ Similar to top, but with some extra features



■ Used to find open files and which processes are using them.



The Reality: Traditionally

- Single processor executes multiple processes concurrently
 - Process executions interleaved (multitasking)
 - Address spaces managed by virtual memory system (later in course)
 - Register values for nonexecuting processes saved in memory

The Reality: In Modern systems

Multicore processors

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- Multiple CPUs on single chip
- Share main memory (and some of the caches)
- Each can execute a separate process
 - Scheduling of processors onto cores done by kernel

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Concurrent Processes

- Each process is a logical control flow.
- Two processes run concurrently (are concurrent) if their flows overlap in time
 - Otherwise, they are sequential
 - Examples (running on single core):
 - Concurrent: A & B, A & C
 - Sequential: B & C

- Control flows for concurrent processes are physically disjoint in time
- However, we can think of concurrent processes as running in parallel with each other

Context Switching

- Processes are managed by a shared chunk of memory resident OS code called the kernel
 - Important: the kernel is not a separate process, but rather runs as part of some existing process.
- Control flow passes from one process to another via a context switch

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An Aside: Errors when using System Calls

- On error, Linux system-level functions typically return -1 and set global variable errno to indicate cause.
 - Hard and fast rule:
 - You must check the return status of every system-level function
 - Only exception is for the few functions that return void
 - Example:

```
if ((pid = fork()) < 0) {
Ifprintf(stderr, "fork error: %s\n", strerror(errno));
Iexit(0);
}</pre>
```

Error Handling

■ Can simplify somewhat using an error-reporting function:

```
void unix_error(char *msg) /* Unix-style error */
2 {
3 Ifprintf(stderr, "%s: %s\n", msg, strerror(errno));
4 Iexit(0);
5 }
```

```
1 if ((pid = fork()) < 0)
2 Iunix_error("fork error");</pre>
```

Error Handling

■ Can simplify more by wrapping system calls with an error-handling function:

```
1 pid_t Fork(void)
2 {
3     pid_t pid;
4     if ((pid = fork()) < 0)
5     unix_error("Fork error");
6     return pid;
7 }</pre>
```

```
1 pid = Fork();
```

Things we want to do with processes

Get process IDs

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- Create and terminate processes

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- Create and terminate processes
- Reap child processes
- Kill the Zombies
- Synchronizing with child processes

Getting Process IDs

- pid_t getpid(void)
 - Returns PID of current process
- pid_t getppid(void)
 - Returns PID of parent process

Process States

From a programmer's perspective, we can think of a process as being in one of three states:

Running

■ Process is either executing, or waiting to be executed and will eventually be scheduled (i.e., chosen to execute) by the kernel

Stopped

■ Process execu; on is suspended and will not be scheduled until further notice (next lecture when we study signals)

Terminated

Process is stopped permanently

■ Process becomes terminated for one of three reasons:

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- exit is called once but never returns.

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- fork is interesting (and often confusing) because it is called once but returns twice

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 - stdout is the same in both parent and child

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 - Total ordering of vertices where all edges point from left to right

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Process Graph Example

```
1 int main() {
2 Tpid_t pid;
3 Iint x = 1;
4 Tpid = Fork();
5 Iif (pid == 0) {
6 II/* Child */
7 IIprintf("child : x=%d\n", ++x);
8 ITexit(0);
9 I)
1/* Parent */
11 Iprintf("parent: x=%d\n", --x);
12 Iexit(0);
13 }
14 I
```

Interpreting Process Graphs

Original Graph:

Interpreting Process Graphs

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Nested forks



Idea:

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 - So, only need explicit reaping in long-running processes
 - e.g., shells and servers



Zombie Example

- ps shows child process as "defunct" (i.e., a zombie)
 - Killing parent allows child to be reaped by init

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Non-Terminating Child Example

- shows child process as "defunct" (i.e., a zombie)
 - Killing parent allows child to be reaped by init

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wait: Synchronizing with Children

- Parent reaps a child by calling the wait function
- int wait(int *child_status)
 - Suspends current process until one of its children terminates
 - Return value is the pid of the child process that terminated
 - If child_status != NULL, then the integer it points to will be set to a value that indicates reason the child terminated and the exit status:
 - Checked using macros defined in wait.h
 - WIFEXITED, WEXITSTATUS, WIFSIGNALED, WTERMSIG, WIFSTOPPED, WSTOPSIG, WIFCONTINUED
 - Details...look them up if you're interested :)

Synchronizing with children

```
void fork9() {
Int child_status;
Int (fork) == 0) {
Ilprintf("HC: hello from child\n");
Ilexit(0);
Ilexit(0);
Ilprintf("HP: hello from parent\n");
Ilprintf("HP: hello from parent\n");
Ilprintf("CT: child has terminated\n");
Ilprintf("Eye\n");
Ilprintf("Bye\n");
Ilprintf("Bye\n");
Ilprintf("Bye\n");
```

Feasible Output:

- HC
- HP
- CT
- Bye

Infeasible Output:

- HP
- CT
 - Bye
- HC

Another wait example

```
void fork10() {
Ipid_t pid[N];
Int i, child_status;
Ifor (i = 0; i < N; i++)
IIif ((pid[i] = fork()) == 0) {
ITexit(100+i); /* Child */
II}
If (i = 0; i < N; i++) { /* Parent */
II}
If (i = 0; i < N; i++) { /* Parent */
IIII wpid = wait(&child_status);
IIIII IIII (WIFEXITED(child_status));
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IIII (WIFEXITED(child_status));
III (WIFEXITED(child_status));
IIII
```

- If multiple children completed, will take in arbitrary order
- Can use macros WIFEXITED and WEXITSTATUS to get information about exit status

waitpid: Waiting for a specific process id

- pid_t waitpid(pid_t pid, int &status, int options)
 - Suspends current process until specific process terminates

```
void forkl1() {
2 pid_t pid[N];
3 lint i;
4 lint child_status;
5 lfor (i = 0; i < N; i++)
6 llif ((pid[i] = fork()) == 0)
7 lllexit(100+i); /* child */
8 llfor (i = N-1; i >= 0; i--) {
9 llipid_t wpid = waitpid(pid[i], &child_status, 0);
10 llif (MIFEXIED(child_status))
11 lllIprintf("Child %d terminated with exit status %d\n",
12 lllIllwpid, WEXITSTATUS(child_status));
13 lllelse
14 lllIprintf("Child %d terminate abnormally\n", wpid);
15 ll}
16 l
```

Processes: Summary

- Exceptions
- Processes
 - At any given time, a system has multiple processes running
 - Only one can run at a time on a single processor
 - Each process appears to have complete control over the processor, memory, etc.
- Spawning processes
 - Call fork
 - Call once, returns twice
- Process completion
 - Call exit
 - Call once, returns 0 times
- Reaping and waiting for processes
 - Call wait or waitpid

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- Both are considered **independent sequences of execution**
- Threads run in a shared memory space
- All processes start out with a single thread, and can start a new thread

1



¹https://randu.org/tutorials/threads/

Why have threads?

- When the process has a lot to do, threads can run simultaneously, potentially speeding up computation
- Threads start faster than processes
- It's easier & more efficient for threads to communicate and share memory