# Programming Exercise 2 - Logistic Regression

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# 0.1 Programming Exercise 2 - Logistic Regression

```
• Logistic regression
```

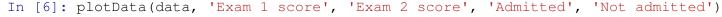
Regularized logistic regression

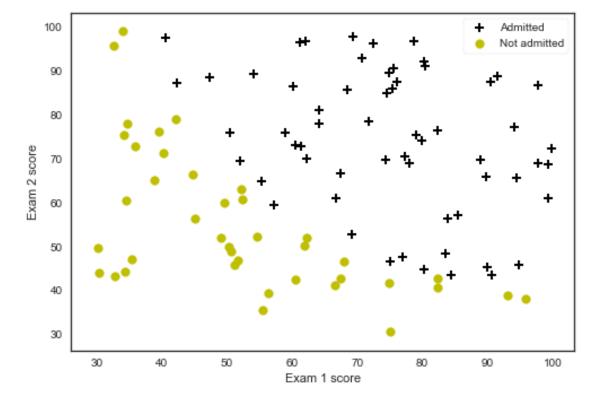
```
In [1]: # %load ../../standard_import.txt
        import pandas as pd
        import numpy as np
        import matplotlib as mpl
        import matplotlib.pyplot as plt
        from scipy.optimize import minimize
        from sklearn.preprocessing import PolynomialFeatures
        pd.set_option('display.notebook_repr_html', False)
        pd.set_option('display.max_columns', None)
        pd.set_option('display.max_rows', 150)
        pd.set_option('display.max_seq_items', None)
        #%config InlineBackend.figure_formats = {'pdf',}
        %matplotlib inline
        import seaborn as sns
        sns.set_context('notebook')
        sns.set_style('white')
In [2]: def loaddata(file, delimeter):
            data = np.loadtxt(file, delimiter=delimeter)
            print('Dimensions: ', data.shape)
            print (data[1:6,:])
            return (data)
In [3]: def plotData(data, label_x, label_y, label_pos, label_neg, axes=None):
            # Get indexes for class 0 and class 1
            neg = data[:,2] == 0
            pos = data[:,2] == 1
```

```
# If no specific axes object has been passed, get the current axes.
if axes == None:
    axes = plt.gca()
axes.scatter(data[pos][:,0], data[pos][:,1], marker='+', c='k', s=60, 1
axes.scatter(data[neg][:,0], data[neg][:,1], c='y', s=60, label=label_raxes.set_xlabel(label_x)
axes.set_ylabel(label_y)
axes.legend(frameon= True, fancybox = True);
```

# 0.1.1 Logistic regression

```
In [4]: data = loaddata('data/ex2data1.txt', ',')
Dimensions: (100, 3)
                              0.
[[ 30.28671077 43.89499752
                                         ]
[ 35.84740877 72.90219803
                              0.
                                         ]
 [ 60.18259939 86.3085521
                              1.
                                         ]
 [ 79.03273605 75.34437644
                              1.
                                         ]]
 [ 45.08327748 56.31637178
                              0.
```





# Logistic regression hypothesis

$$h_{\theta}(x) = g(\theta^T x)$$

$$g(z) = \frac{1}{1 + e^{-z}}$$

Scipy actually has a convenience function which does exactly the same: http://docs.scipy.org/doc/scipy/reference/generated/scipy.special.expit.html#scipy.special.expit

# **Cost Function**

$$J(\theta) = \frac{1}{m} \sum_{i=1}^{m} \left[ -y^{(i)} \log \left( h_{\theta} \left( x^{(i)} \right) \right) - (1 - y^{(i)}) \log \left( 1 - h_{\theta} \left( x^{(i)} \right) \right) \right]$$

# **Vectorized Cost Function**

$$J(\theta) = \frac{1}{m} \left( (\log (g(X\theta))^T y + (\log (1 - g(X\theta))^T (1 - y)) \right)$$

```
In [8]: def costFunction(theta, X, y):
    m = y.size
    h = sigmoid(X.dot(theta))

J = -1*(1/m)*(np.log(h).T.dot(y)+np.log(1-h).T.dot(1-y))

if np.isnan(J[0]):
    return(np.inf)
return(J[0])
```

# Partial derivative

$$\frac{\delta J(\theta)}{\delta \theta_j} = \frac{1}{m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)}) x_j^{(i)}$$

#### Vectorized

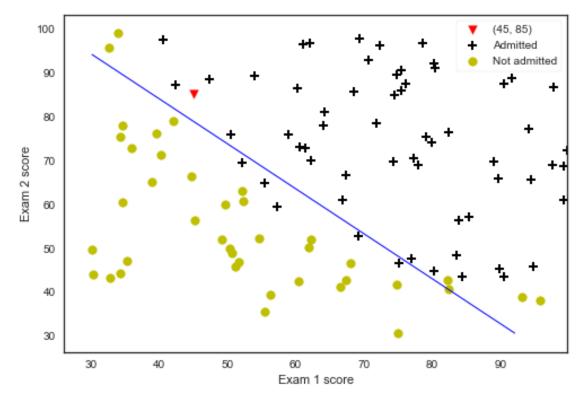
```
\frac{\delta J(\theta)}{\delta \theta_i} = \frac{1}{m} X^T (g(X\theta) - y)
In [9]: def gradient(theta, X, y):
             m = y.size
             h = sigmoid(X.dot(theta.reshape(-1,1)))
             grad = (1/m) *X.T.dot(h-y)
             return(grad.flatten())
In [10]: initial_theta = np.zeros(X.shape[1])
          cost = costFunction(initial_theta, X, y)
          grad = gradient(initial_theta, X, y)
          print('Cost: \n', cost)
          print('Grad: \n', grad)
Cost:
 0.69314718056
Grad:
 [-0.1]
         -12.00921659 -11.26284221]
```

# **Optimize** cost function

```
In [11]: res = minimize(costFunction, initial_theta, args=(X,y), method=None, jac=
C:\Users\Lenovo\Anaconda3\lib\site-packages\ipykernel\__main__.py:5: RuntimeWarning
C:\Users\Lenovo\Anaconda3\lib\site-packages\ipykernel\__main__.py:5: RuntimeWarning
Out [11]:
              fun: 0.20349770158950992
         hess_inv: array([[ 2.85339493e+03, -2.32908823e+01, -2.27416470e+01],
                [-2.32908823e+01, 2.04489131e-01, 1.72969525e-01],
                [ -2.27416470e+01, 1.72969525e-01, 1.96170322e-01]])
              jac: array([ -2.68557621e-09, 4.36433486e-07, -1.39671757e-06])
          message: 'Optimization terminated successfully.'
             nfev: 34
              nit: 25
             njev: 30
           status: 0
          success: True
                x: array([-25.16131634, 0.2062316, 0.20147143])
```

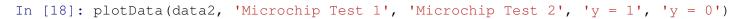
#### **Predict**

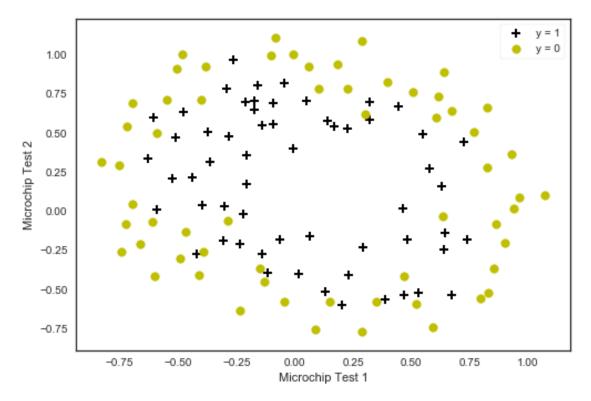
# **Decision boundary**



# 0.1.2 Regularized logistic regression

```
In [16]: data2 = loaddata('data/ex2data2.txt', ',')
Dimensions:
              (118, 3)
[[-0.092742]
              0.68494
                         1.
 [-0.21371
              0.69225
                         1.
 [-0.375]
              0.50219
                         1.
 [-0.51325]
              0.46564
                         1.
                                  1
 [-0.52477]
              0.2098
                         1.
                                  ]]
```





# **Polynomials**

```
Out[19]: (118, 28)
```

# **Regularized Cost Function**

$$J(\theta) = \frac{1}{m} \sum_{i=1}^{m} \left[ -y^{(i)} \log \left( h_{\theta}(x^{(i)}) \right) - (1 - y^{(i)}) \log \left( 1 - h_{\theta}(x^{(i)}) \right) \right] + \frac{\lambda}{2m} \sum_{j=1}^{n} \theta_{j}^{2}$$

# **Vectorized Cost Function**

$$J(\theta) = \frac{1}{m} \left( (\log (g(X\theta))^T y + (\log (1 - g(X\theta))^T (1 - y)) + \frac{\lambda}{2m} \sum_{j=1}^n \theta_j^2 \right)$$

```
In [20]: def costFunctionReg(theta, reg, *args):
    m = y.size
    h = sigmoid(XX.dot(theta))

J = -1*(1/m)*(np.log(h).T.dot(y)+np.log(1-h).T.dot(1-y)) + (reg/(2*m))

if np.isnan(J[0]):
    return(np.inf)
return(J[0])
```

# Partial derivative

$$\frac{\delta J(\theta)}{\delta \theta_j} = \frac{1}{m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)}) x_j^{(i)} + \frac{\lambda}{m} \theta_j$$

# Vectorized

$$\frac{\delta J(\theta)}{\delta \theta_j} = \frac{1}{m} X^T (g(X\theta) - y) + \frac{\lambda}{m} \theta_j$$

# Note: intercept parameter $\theta_0$ is not to be regularized

```
In [21]: def gradientReg(theta, reg, *args):
             m = y.size
             h = sigmoid(XX.dot(theta.reshape(-1,1)))
             grad = (1/m) *XX.T.dot(h-y) + (reg/m) *np.r_[[[0]], theta[1:].reshape(-1, -1, -1)]
             return(grad.flatten())
In [22]: initial_theta = np.zeros(XX.shape[1])
         costFunctionReg(initial_theta, 1, XX, y)
Out [22]: 0.6931471805599454
In [23]: fig, axes = plt.subplots(1,3, sharey = True, figsize=(17,5))
         # Decision boundaries
         # Lambda = 0 : No regularization --> too flexible, overfitting the training
         # Lambda = 1 : Looks about right
         # Lambda = 100 : Too much regularization --> high bias
         for i, C in enumerate([0, 1, 100]):
             # Optimize costFunctionReg
             res2 = minimize(costFunctionReg, initial_theta, args=(C, XX, y), method
             # Accuracy
             accuracy = 100*sum(predict(res2.x, XX) == y.ravel())/y.size
             # Scatter plot of X, y
             plotData(data2, 'Microchip Test 1', 'Microchip Test 2', 'y = 1', 'y =
             # Plot decisionboundary
             x1_{min}, x1_{max} = X[:,0].min(), X[:,0].max(),
             x2_{min}, x2_{max} = X[:,1].min(), X[:,1].max(),
             xx1, xx2 = np.meshgrid(np.linspace(x1_min, x1_max), np.linspace(x2_min
             h = sigmoid(poly.fit_transform(np.c_[xx1.ravel(), xx2.ravel()]).dot(re
             h = h.reshape(xx1.shape)
             axes.flatten()[i].contour(xx1, xx2, h, [0.5], linewidths=1, colors='g
             axes.flatten()[i].set_title('Train accuracy {}% with Lambda = {}'.form
```

