

JavaScript Debugger
Using Data Structure Visualization
JavaScript のデータ構造可視化
を用いたデバッガ

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Abstract

Debugger is used to test and debug target programs by stepping through the program and examining the current program state by evaluating the values of expressions or checking the stack trace. However, the character-based expressions evaluation provides limited insight into the current program state. This paper examines how a debugger can provide a higher-level, more informative visualization based on data structure. Except static view, the debugger also allows generating animation while target object is modified. However, high-level visualization typically relies on user augmented source code. This paper enables the debugger to understand the data structure of target object by externally supplied semantic information which is written in a declarative language called visualjs.

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Chapter 1

Introduction

1.1 Motivation

Program visualization systems translate program into visual shapes. It is often used in algorithm animation systems where algorithm behavior is visualized by producing the abstraction of the data and the operations of the algorithm. Such visualization also can be used in a debugger, as it allows for better understanding on the behavior of the program and help perceive which parts of the program does not function correctly.

A debugger is used to test and debug target programs. It offers many sophisticated functions such as running a program step by step, pausing the program at some event or specified instruction by means of a breakpoint, and examining the current state by evaluating the values of expressions or checking the stack trace. However, the character-based expressions evaluation provides limited insight into the current program state. Modern IDEs intend to solve this problem by offering a dedicated view to watch expressions. As a typical example of object-oriented programming language, when the variable being watched is of reference type, its fields is listed in a tree-view table. The root of this list represents the value itself. If a field is also of reference type, it can be further expanded in the same manner. Fields of primitive type can not be further expanded.

However, such visualization still has deficiencies. Firstly, all of the objects are visualized in a tree-view table, and hence lack of important semantic information. Secondly, The whole view will be refreshed while stepping through the program. It is nearly impossible to check the modification parts and find the relevance between two succeeding states.

This paper examines how a debugger can visualize data structure and generate smooth animation automatically while according object is modified via

externally supplied semantic information. Instead of displaying object in a general way, we wish to produce more helpful and informative visualization.

1.2 Main Contribution

1.3 Outline of the Thesis

Chapter 2

Related Research

Price et al. [6] have defined software visualization as the use of the crafts of typography, graphic design, animation, and cinematography with modern human computer interaction technology to facilitate both the human understanding and effective use of computer software. This is a very abstract definition.

2.1 Debugger

2.2 Visual Debugger

Chapter 3

System Proposal

To solve the problems mentioned in last chapter, our system used traversal-based method [5] to traverse the object. A new declarative language called `visualjs` is created so that this approach can be oriented to JavaScript. On top of this, we proposed a mapping mechanism from an object to visual shapes. Making use of the mapping relationship, our system is able to visualize the object in kinds of shapes and animate these visual shapes automatically while stepping through program. Note that instead of providing rich kinds of data structure visualizations, our research intends to help users visualize and animate the objects that they are interested in.

3.1 The Design of VisualJS

The traversal-based approach takes a root object and traverse the objects by following any other objects referenced by the root. A set of predicates aligned in a pattern will be applied to the object and decide which action to execute. Each action describes its rules about how to generate visual nodes and which objects to traverse as follows.

The declarative language is written in text file. Each file describes only one data structure, which means you have to write code for objects with different structures in respective files. Each file is made up of one pattern and several actions.

The guiding principles that were considered when we designed this system are as follows:

1. **Expression Power:** The topology relationship of visual shapes should be specified clearly, naturally, intuitively, and concisely.

2. **Flexibility:** Flexibility provides the design with root to extend. More data structures and sophisticated visual attributes would be supported in the future. All these requirement changes should be considered in initial design.

3.1.1 Data Model

Although this system is constructed based on JavaScript, it theoretically suits all object-oriented programming languages like C++ and Java and any other programming language in which an object is constructed in a recursive way, which means an object is composed of other primitive type values or objects. Hence the object can be traversed and matching actions can be executed to generate the topology of visual nodes.

3.1.2 Pattern

A pattern aligns a series of predicates to be matched when object comes. Each predicate has its pair action. The first action whose predicate is matched will be executed. We will elaborate pattern by showing its grammar in EBNF as follows:

$$\begin{aligned} \langle pattern \rangle &::= \text{pattern-name} : \text{pattern} \{ \langle pattern-body \rangle \} \\ \langle pattern-body \rangle &::= \langle exec-clause \rangle \{, \langle exec-clause \rangle\} \\ \langle exec-clause \rangle &::= \text{exec} \text{ action-name} [\langle when-clause \rangle] \\ \langle when-clause \rangle &::= \text{when} (\text{expression}) \end{aligned}$$

Each pattern starts with a name and a pattern keyword split by a colon, where the keyword is used to differentiate from action in that there is no decided order. After the pattern keyword, a pattern-body surrounded by a pair of braces aligns several exec-clauses. Each exec-clause describes a predicate statement to evaluate and which action will be executed when the predicate passed.

3.1.3 Actions

$$\begin{aligned}
\langle action \rangle &::= \text{action-name} : \mathbf{action} \{ \langle action-body \rangle \} \\
\langle action-body \rangle &::= \langle action-clause \rangle \{, \langle action-clause \rangle \} \\
\langle action-clause \rangle &::= \langle create-clause \rangle \mid \langle next-clause \rangle \\
\langle create-clause \rangle &::= \mathbf{create} [\text{environment-var} =] \text{node-name} \\
&\quad (\langle attribute-clause \rangle \{, \langle attribute-clause \rangle \}) \\
\langle attribute-clause \rangle &::= \text{attribute} = \text{expression} \\
\langle next-clause \rangle &::= \langle object-clause \rangle \mid \langle foreach-clause \rangle \\
\langle object-clause \rangle &::= \mathbf{next} \text{ expression } (\langle environment-clause \rangle \\
&\quad \{, \langle environment-clause \rangle \}) \\
\langle foreach-clause \rangle &::= \mathbf{foreach_next} (\langle environment-clause \rangle \\
&\quad \{, \langle environment-clause \rangle \}) \\
\langle environment-clause \rangle &::= \text{environment-var} = \text{expression}
\end{aligned}$$

3.2 From An Object to Visual Shapes

To generate valid data structure visualization and animation, we must at first prove the consistency between the program and visualization. A program is composed of a series of instructions which are executed orderly. Under the control of debugger, program is being paused until step requests come. Every time the program pauses, it represents a new program state.

What need to be proved is that the initial program state is being correctly visualized and every time the new program state is generated, the animation will respond to it correctly. However, program state contains too much information. A computer program stores data in variables, which represent storage locations in the computer's memory. Program state contains all contents of these memory locations. In contrast, users always have limited interest and perception at a time. We intend to help users understand the program from any angel he is interested in. Instead of visualizing the whole program state like Heapviz [1], this system always focuses on visualizing one object but allows switching targets at any time.

3.2.1 Variables versus Objects

In JavaScript, a variable is a storage location and an associated symbolic name which contains a value. JavaScript: The Definitive Guide [3] introduces about data types in JavaScript. JavaScript allows you to work with

three primitive data types: numbers, strings of text, and boolean truth values. JavaScript also defines two trivial data types, null and undefined, each of which defines only a single value.

In addition to these primitive types, JavaScript also supports a composite data type known as object. Just like other object-oriented programming languages, an object in JavaScript is composed of a collection of values with either primitive values or objects. An object can represent an unordered collection of named values or an ordered collection of numbered values. The latter case is called an array. Although array is also an object, it behaves quite differently and have to be considered specially throughout the paper.

JavaScript also defines a few other specialized kinds of objects. **Function** is a subprogram that can be called externally or internally in case of recursion. **Date** creates a object that represents a single moment in time. **RegExp** creates a object that represents a regular expression for matching text with a pattern. **Error** creates a object that represent syntax or runtime errors that can occur in a JavaScript program. Because this research focuses on user-customized data structures, these four types of objects have their own specific data structures hence will not be considered any specially.

We selected object as the target to visualize. This seems trivially different from previous research like the famous data structure visualization system, jGRASP [2], who uses variable as the target of visualization. Although there is no problem using variable in jGRASP because it is static visualization without any animation. Our research introduces animation hence the problem has tremendously changed. The fundamental difference is whether there exists substantive relationship between two consecutive states. Animation is visualizing the changes between two consecutive states, so it have to proceed on the former state. That is why variable can not be used here as the target of visualization in that even the variables with the same name may refer to different objects or go out of scope after stepping through the program. Both situations may lead to meaningless animation because original mapping relationship can not be adapted for new object with different structure.

However, variable is still used as the entry to start watching certain object. Modern debugger offers many sophisticated features such as stepping through the program, stopping at some event by means of breakpoint and examining the current state such as tracking the values of variables and stack trace. We can find that typical debugging prefer examining variable values to exploring snapshot of the heap. Therefore, we choose variable as the entry and the object referred by the variable will drive the following animation.

Figure 3.1 shows the system interface. The left half is the visualization view.

CHAPTER 3. SYSTEM PROPOSAL

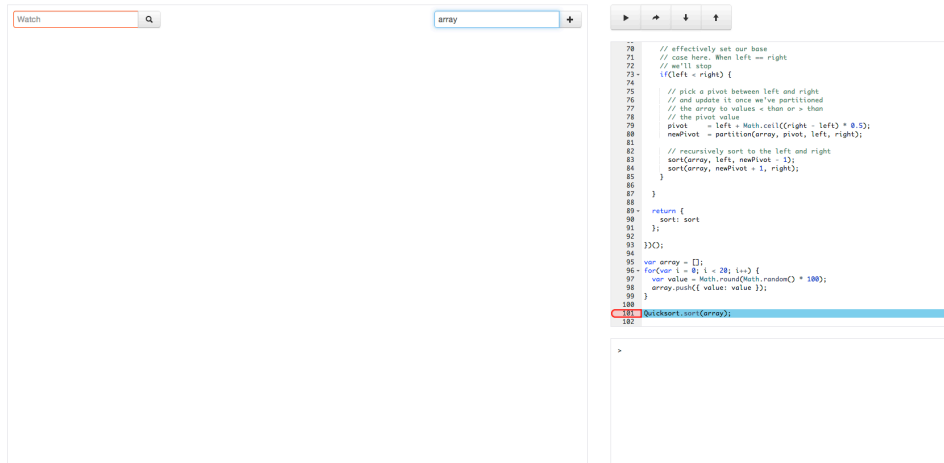


Figure 3.1: Select variable named array to visualize

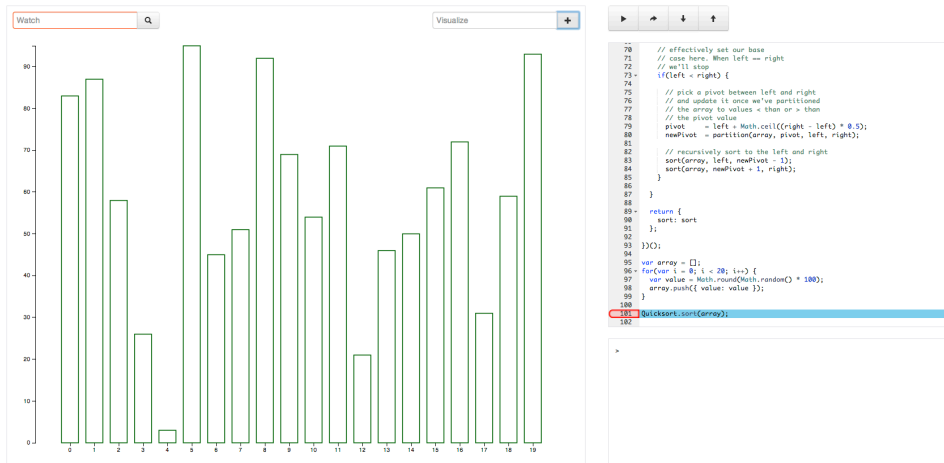


Figure 3.2: Variable named array has been visualized

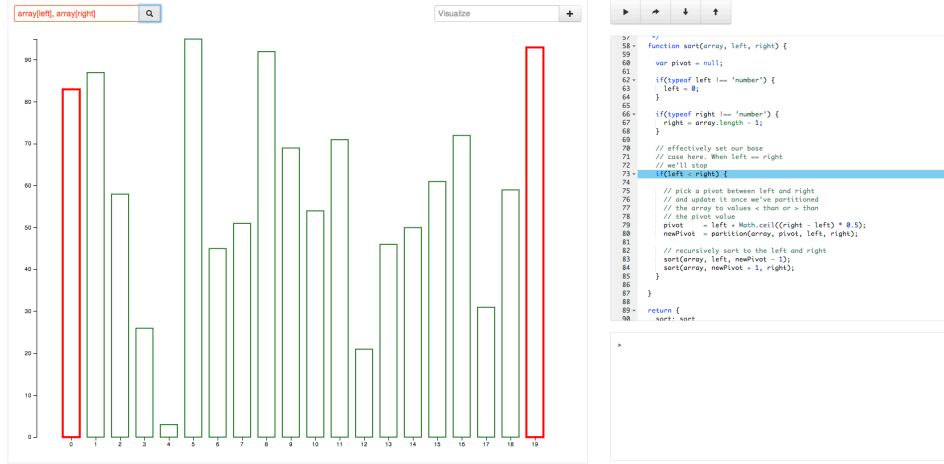


Figure 3.3: Context Visualization

Users can select some object to visualize by means of inputting its variable name and click the button with add icon on the top right corner and then you can see that object has been visualized as a bar chart in Figure 3.2.

3.2.2 User Interest

As Niklaus Wirth said in his book [7], Algorithms + Data Structures = Programs, which means that we have to understand algorithms and data structures before understanding programs. Although our research is based on data structure visualization, we also intend to help users understand algorithms as far as possible. Although the attention has to be focused on one object, we still can help users understand algorithms from two aspects:

1. **Animation** displays how algorithms contribute to the object modification
2. **Highlighted shapes** represent the objects that users are interested in

In Figure 3.3, we can see that two bars are highlighted with red border against Figure 3.2. Users can input arbitrary number of variables split by commas in the top left corner of the visualization view. Any object referred by any inputted variable and possessing the same handle with any visual object will be highlighted with red border. Unlike that the target object being visualized is locked, these variables will be evaluated each step because they stand for how current environment relates with the target object.

3.2.3 Mapping Mechanism

Object graph details the relationships between objects. The object graph of the root object is defined as $G = (V, E)$. Here, the vertex set V represents all objects referred by the root object either directly or indirectly, and the edge set E represents the reference relationships between those objects. Figure 3.4 shows an example of JavaScript object graph.

Traversing the object graph according to the next actions, we will get a subgraph of it, $G_s = (V_s, E_s)$. The whole object graph probably contains much information that users are not interested in, hence we extract a subgraph from the whole object graph. All of the objects in the subgraph serve the visualization work, so we call them visual objects here.

After, each visual object is responsible to create its own visual shapes. We called them visual nodes here. Each data structure defines its own visual nodes. In this paper, we have implemented two data structures, bar chart and tree.

Bar chart only has one type of visual node. All visual nodes are connected into one list. The bars will be displayed in the same order of the list elements. The data structure of the visual node is defined as follows:

```
{
  "value": <number>,
  "id"    : <string>
}
```

Property value is displayed via the bar height. Property id is a GUID representing the identification of visual node. If the visual nodes are created by objects, their id is set as the object handle. As for the visual nodes created by primitive type values, their id is set as their index in the list.

Tree has two types of visual nodes, node and edge. Their data structure are defined as follows:

```
{
  "label": <string>,
  "id"    : <string>,
  "type"  : "node"
}
```

Node type visual node is displayed as a rectangle and property label can be seen inside. Like the visual node defined above, property id is also a GUID representing the identification of the visual node. For the visual nodes created by objects, their id is set as the object handles. For the visual nodes created by primitive type values, they must be leaf nodes in that there is no objects to traverse further. Their id is made up of three parts: the id of the adjacent node, the value of property label, and their index in the

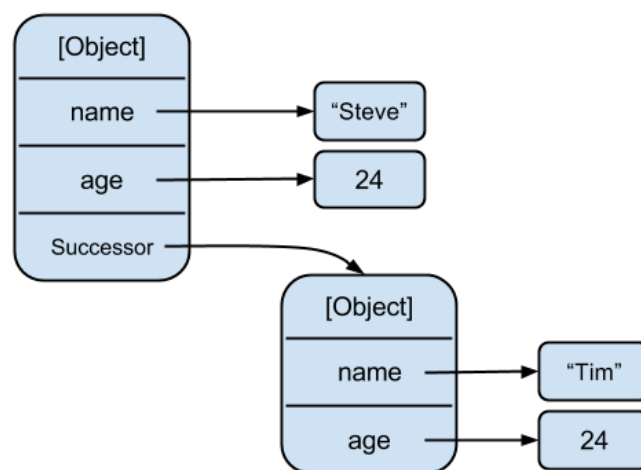


Figure 3.4: JavaScript Object Graph

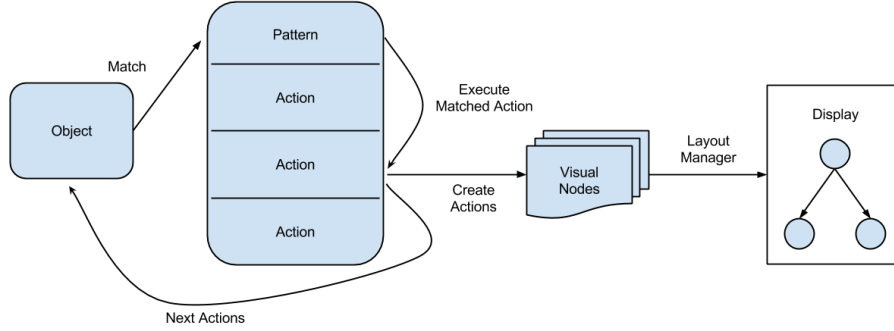


Figure 3.5: Mapping Process

children node list. When the sibling nodes are also created by primitive type values, the latter two parts can be used to distinguish the visual nodes from their sibling nodes.

```
{
  "from": <node type visual node>,
  "to"   : <node type visual node>,
  "id"   : <string>,
  "type": "edge"
}
```

Edge type visual node is displayed as an undirected line linking two node type visual nodes, namely property from and property to. Property id has just the same meaning defined before. It is set as the id of the visual node expressed by property to in that the child node is always unique in a tree.

The visual nodes of the tree data structure can be defined as a graph, $G' = (V', E')$. The vertex set represents all visual nodes of tree node. V_s can be mapped to V' by a bijective function $f : V_s \rightarrow V'$. The edge set represents all visual nodes of tree edge. E_s also can be mapped to E' by a bijective function $f : E_s \rightarrow E'$.

Figure 3.5 shows the whole mapping process starting from the root object.

3.2.4 Animate Data Structures

After establishing the mapping relationship, we will be able to generate the animation. Animation is driven by data modifications, which is contributed

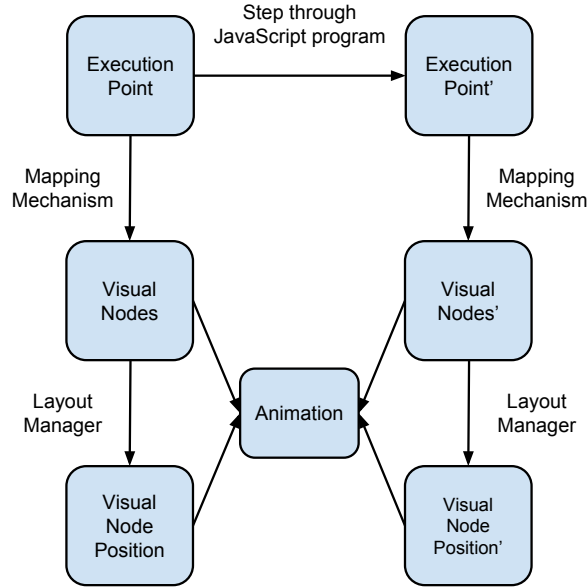


Figure 3.6: Animation Generation Process

by JavaScript program execution. Therefore, what we need to prove is the consistency between data modifications and animation.

The first step is to enumerate all of the situations of data modifications and animation, and then data modifications can be translated to animation.

Figure 3.6 shows the whole process of animation generation.

Chapter 4

System Implementation

4.1 V8 Debugger Protocol

V8 is able to debug the JavaScript code running in it. The debugger related API can be used in two ways, a function based API using JavaScript objects and a message based API using JSON based protocol. The function based API is for in-process usage, while the message based API is for out-process usage. This system is implemented with message based API. The protocol packet is defined in JSON format and can to be converted to string.

4.1.1 Protocol Packet Format

All packets have two basic elements called seq and type. The seq field holds the consecutive assigned sequence number of the packet. And type field is a string value representing the packet is request, response or event. Each request will receive a response with the same request seq number as long as the connection still works. And additional events will be generated on account of particular requests or system errors. Each packet has the following structure.

```
{
  "seq" : <number>,
  "type": <type>,
  ...
}
```

A request packet has the following structure.

```
{
  "seq"      : <number>,
  "type"     : "request",
  "command"  : <command>,
}
```

```
"arguments": { ... }  
}
```

A response packet has the following structure. If command fails, the success field will be set as false and message field will contain an error message.

```
{  
  "seq"           : <number>,  
  "type"          : "response",  
  "request_seq"   : <number>,  
  "command"       : <command>,  
  "body"          : { ... },  
  "running"       : <is the VM running after sending the message>,  
  "success"       : <boolean indicating success>,  
  "message"       : <error message>  
}
```

An event packet has the following structure.

```
{  
  "seq"   : <number>,  
  "type"  : "event",  
  "event" : <event name>,  
  "body"  : ...  
}
```

4.1.2 V8 Debugger Protocol Features

V8 debugger has various commands and events providing detailed runtime information. However, this research focus on the data structure visualization. Only following features are used in order to implement basic debugger features.

- **Request** continue
- **Request** evaluate
- **Request** lookup
- **Request** source
- **Request** setbreakpoint
- **Request** clearbreakpoint
- **Event** break
- **Event** exception

Request "continue" makes V8 start running or stepping forward, including stepping in, stepping over, and stepping out. Although step count can be indicated in the arguments, we always set it as 1.

Request "evaluate" is used to evaluate a expression. However, if the result is object type that contains other fields, all fields will be represented as their object handle. Hence we have to use request "lookup" to lookup objects based on their handle. As a result, we can get the deep copy of any object by recursively using request "lookup".

Request "source" is used to retrieve source code for a frame. Frame and code range have to be indicated in the arguments. Note here that each script file running on node.js is wrapped within a wrapper function. Hence we have to remove the header and tail before showing it to users.

Request "setbreakpoint" is used to add breakpoint. Target file/function and line number are essential here. Request "clearbreakpoint" is used to remove breakpoint set by request "setbreakpoint". Breakpoint number which can be received from request "setbreakpoint" has to be indicated in the arguments. There also exists other kinds of requests like request "backtrace" which is used to require stacktrace information, request "frame" which is used to require frame information and so on.

4.1.3 Response Object Serialization

As discussed in 4.1.2, request "evaluate" and "lookup" may contain objects as part of the body. All objects are assigned with an ID called handle. Object identity[4] is that property of an object which distinguishes each object from all others. Although the handle can be used to identify objects here, it has a certain lifetime after which it will no longer refer to the same object. The lifetime of handles are recycled for each debug event.

For objects serialized they all contains two basic elements, handle and type. Each object has following the structure.

```
{
  "handle": <number>,
  "type"   : <"undefined", "null", "boolean", "number",
              "string", "object", "function">,
  ...
}
```

For primitive JavaScript types, the value is part of the result.

- 0 →


```
{
        "handle": <number>,
        "type"   : "number",
        "value"  : 0
      }
```

- "hello" →

```
{
  "handle": <number>,
  "type"   : "string",
  "value"  : "hello"
}
```

- true →

```
{
  "handle": <number>,
  "type"   : "boolean",
  "value"  : true
}
```

- null →

```
{
  "handle": <number>,
  "type"   : "null",
}
```

- undefined →

```
{
  "handle": <number>,
  "type"   : "undefined",
}
```

An object is encoded with additional information.

{a:1,b:2} →

```
{
  "className"           : "Object"
  "constructorFunction": { "ref": <number> },
  "handle"              : <number>,
  "properties"          : [{ "ref": <number> }, ...],
  "protoObject"         : { "ref": <number> },
  "prototypeObject"     : { "ref": <number> },
  "text"                : "#<Object>",
  "type"                : "object"
}
```

An function is encoded as an object with additional information in the properties name, inferredName, source and script.

function(){} →

```
{
  "handle"              : <number>,
  "type"                : "function",
  "className"           : "Function",
  "constructorFunction": { "ref": <number> },
}
```

```
"protoObject"      : { "ref": <number> },
"prototypeObject"  : { "ref": <number> },
"name"             : "",
"inferredName"     : "",
"source"           : "function(){}",
"scriptId"         : { "ref": <number> },
"scriptId"         : <number>,
"position"         : <number>,
"line"             : <number>,
"column"           : <number>,
"properties"       : [{
    "name": <string>,
    "ref" : <number>
  }, ...]
}
```

4.2 System Architecture

This is a full-stack JavaScript system which consists of three components.

1. The debuggee node.js program is running on V8.
2. Server is also running on node.js.
3. Client is running on browser.

Server side is responsible for starting running debuggee program along with V8 debugger and communicate with it using V8 debugger protocol. It responds to the client and require according information from V8 debugger. When response arrives, this component is also responsible for informing client to update along with required information. Because the communication with V8 debugger is an asynchronized process whereas the system logic is basically synchronized, this component must be able to handle it carefully. Client side provides IDE-like debugging experience with an embedded editor to show the source code of the debuggee program, breakpoint management and series of stepping buttons. It also be responsible for visualization work. Figure ?? shows the system architecture.

4.2.1 Implementation Technique

Protocol.js ensures data integrity in that some responses may be separated into several chunks. Client.js is provides basic features by encapsulating the communication with V8 debugger. Animator module generates and updates graph for target object with the given script. It is feasible to build different interfaces, like command interface or GUI interface.

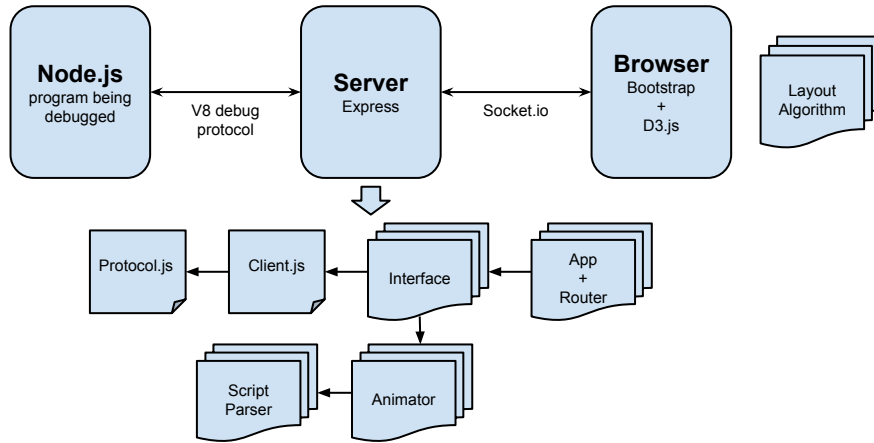


Figure 4.1: System architecture

On the client side, we used bootstrap for faster and easier web GUI development. Visualization related work is finished by D3.js which is an open-source project about visualizing. D3.js is a JavaScript library for manipulating documents based on data. D3 helps you bring data to life using HTML, SVG and CSS. D3 's emphasizes on combining powerful visualization components with a data-driven approach to DOM manipulation.

We also used other open-source libraries and tools like underscore, async.js, jquery, require.js, buckets, grunt, jasmine to help the development work on both sides.

4.2.2 Asynchronized Communication Mechanism

Another mentionable implementation technique used here is the asynchronized communication mechanism. Most I/O-related API containing TCP/IP communication provided by node.js is in asynchronized way. On the other hand, all requests sent from client via websocket is also in asynchronized way. As a result, it is very complicated to keep program running correctly because the overall control flow across three components is based on synchronization logic. Firstly, blocking message queue is used to handle the requests

from client. All requests are stored in the queue and will be handled one by one. On the server side, Async.js is used to help manage asynchronized code. Although node.js is famous for its speed and single-thread model, its coding style is difficult to maintain on account of endless nested callback. Async.js is a tool to help alleviate this problem.

4.3 Declarative Language Parser

4.4 Visualization Generation and Updating

Chapter 5

Examples

5.1 Quick Sort

5.2 Math Expression Tree

5.3 AVL Tree

Chapter 6

Summary

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