HW5_Yi_Xiong

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Contents

1.(30 points) Following the developments in modules 4.3 and 4.4, derive the expressions f ACF for:	or	1
a.MA(1) and MA(2) models		1
b.AR(1) and AR(2) models		2
c.ARMA(1,1)		4

1.(30 points) Following the developments in modules 4.3 and 4.4, derive the expressions for ACF for:

a.MA(1) and MA(2) models

MA(1)

definition

$$y_t = \mu + \epsilon_t + \theta \epsilon_{t-1}$$

Autocovariance

$$\begin{split} \gamma_0 &= E[y_t - E(y_t)]^2 \\ &= E[y_t - \mu] \\ &= E[\epsilon_t + \theta \epsilon_{t-1}]^2 \\ &= E[\epsilon_t^2 + 2\theta \epsilon_t \epsilon_{t-1} + \theta^2 \epsilon_{t-1}^2] \\ &= \theta^2 + 0 + \theta^2 \sigma^2 \\ &= (1 + \theta^2) \sigma^2 \\ \\ \gamma_j &= E[(y_t - \mu)(y_{t-j} - \mu)] \\ &= E[(\epsilon_t + \theta \epsilon_{t-1})(\epsilon_{t-j} + \theta \epsilon_{t-j-1})] \\ &= \begin{cases} \theta E[\epsilon_{t-1}^2] = \sigma \theta^2 & \text{if } j = 1 \\ 0 & \text{otherwise} \end{cases} \end{split}$$

Autocorrelation

$$\rho_j = \frac{\gamma_j}{\gamma_0} = \frac{\theta \sigma^2}{(1 + \theta^2)\sigma^2} = \begin{cases} \frac{\theta}{(1 + \theta^2)} & \text{if } j = 1\\ 0 & \text{if } j \neq 1 \end{cases}$$

MA(2)

MA(q) definition

$$y_t = \mu + \sum_{j=0}^{q} \theta_j \epsilon_{t-j}, \ q \geqslant 1 \ and \ \theta_0 = 1$$

MA(2) definition

$$y_t = \mu + \epsilon_t + \theta_1 \epsilon_{t-1} + \theta_2 \epsilon_{t-2}$$

Autocovariance of MA(q)

$$\gamma_0 = E(y_t - \mu)^2$$
$$= \left[\sum_{j=0}^q \theta_j^2\right] \sigma^2$$

$$\gamma_j = E[(y_t - \mu)(y_{t-j} - \mu)]$$

$$\gamma_j = \begin{cases} (\theta_j + \theta_{j+1}\theta_1 + \theta_{j+2}\theta_2 + \dots + \theta_q\theta_{q-j})\sigma^2 & \text{for } 1 \leq j \leq q \\ 0 & \text{for } j > q \end{cases}$$

Autocovariance of MA(2)

$$\gamma_0 = (1 + \theta_1^2 + \theta_2^2)\sigma^2$$
$$\gamma_1 = (\theta_1 + \theta_2\theta_1)\sigma^2$$
$$\gamma_2 = \theta_2\sigma^2$$
$$\gamma_j = 0, \ j \geqslant 3$$

Autocorrelation of MA(2)

$$\rho_{1} = \frac{(\theta_{1} + \theta_{2}\theta_{1})\sigma^{2}}{(1 + \theta_{1}^{2} + \theta_{2}^{2})\sigma^{2}}$$

$$\rho_{2} = \frac{\theta_{2}\sigma^{2}}{(1 + \theta_{1}^{2} + \theta_{2}^{2})\sigma^{2}}$$

$$\rho_{j} = 0, \ j \geqslant 3$$

b.AR(1) and AR(2) models

AR(1)

definition

$$y_t = c + \phi y_{t-1} + \epsilon_t$$

Autocovariance

When $|\phi|$ < 1, y_t is weakly stationary and ergodic

$$y_t - \mu = \phi(y_{t-1} - \mu) + \epsilon_t$$

$$\gamma_0 = E[y_t - \mu]^2$$

$$= \sigma^2 [1 + \phi^2 + \phi^4 + \dots + \phi^{2k} + \dots]$$

$$= \frac{\sigma^2}{1 - \phi^2}$$

$$\gamma_{j} = E[(y_{t} - \mu)(y_{t-j} - \mu)]$$

$$= \sigma^{2}[\phi^{j} + \phi^{j+2} + \phi^{j+4} + \dots]$$

$$= \sigma^{2}\phi^{j}[1 + \phi^{2} + \phi^{4} + \dots]$$

$$= \sigma^{2}\frac{\phi^{j}}{1 - \phi^{2}}$$

Autocorrelation

$$\rho_j = \frac{\gamma_j}{\gamma_0} = \phi^j$$

AR(2)

definition

$$y_t = c + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \epsilon_t$$

For stationarity:

$$\lambda^{2} - \phi_{1}\lambda - \phi_{2} = 0$$
$$\lambda = \frac{\phi_{1} \pm \sqrt{\phi_{1}^{2} + 4\phi_{2}}}{2}$$
$$|\lambda| < 1$$

Autocovariance

$$y_t - \mu = \phi_1(y_{t-1} - \mu) + \phi_2(y_{t-2} - \mu) + \epsilon_t$$

$$\gamma_0 = E[(y_t - \mu)(y_t - \mu)]$$

$$= E[\phi_1(y_t - \mu)(y_{t-1} - \mu)]$$

$$+ E[\phi_2(y_t - \mu)(y_{t-2} - \mu)]$$

$$+ E[(y_t - \mu)\epsilon_t]$$

$$= \phi_1\gamma_1 + \phi_2\gamma_2 + \sigma^2$$

for
$$j \geqslant 1$$

$$\gamma_{j} = E[(y_{t} - \mu)(y_{t-j} - \mu)]$$

$$= E[\phi_{1}(y_{t-1} - \mu)(y_{t-j} - \mu)]$$

$$+ E[\phi_{2}(y_{t-2} - \mu)(y_{t-j} - \mu)]$$

$$+ E[(y_{t-j} - \mu)\epsilon_{t}]$$

$$= \phi_{1}\gamma_{1} + \phi_{2}\gamma_{2}$$

Autocorrelation

for
$$j \geqslant 1$$

$$\rho_{j} = \frac{\gamma_{j}}{\gamma_{0}}$$

$$= \theta_{1} \frac{\gamma_{j-1}}{\gamma_{0}} + \theta_{2} \frac{\gamma_{j-2}}{\gamma_{0}}$$

$$= \phi_{1} \rho_{j-1} + \phi_{2} \rho_{j-2}$$

$$\rho_{1} = \phi_{1} \rho_{0} + \phi_{2} \rho_{-1}$$

$$\rho_{1} = \frac{\phi_{1}}{1 - \phi_{2}}$$

$$\rho_{2} = \phi_{1} \rho_{1} + \phi_{2} \rho_{0}$$

$$= \phi_{1} \rho_{1} + \phi_{2}$$

$$\gamma_{0} = \frac{(1 - \phi_{2})\sigma^{2}}{(1 + \phi_{2})[(1 - \phi_{2})^{2} - \phi_{1}^{2}]}$$

Summary

$$\rho_1 = \frac{\phi_1}{1 - \phi_2}
\rho_2 = \phi_1 \rho_1 + \phi_2
\rho_j = \phi_1 \rho_{j-1} + \phi_2 \rho_{j-2} \text{ for } j \geqslant 3$$

c.ARMA(1,1)

definition

$$y_t = c + \phi_1 t_{t-1} + \epsilon_t + \theta_1 \epsilon_{t-1}$$

Autocovariance

$$y_t - \mu = \phi_1(y_{t-1} - \mu) + \epsilon_t + \theta_1 \epsilon_{t-1}$$

$$\gamma_0 = E[y_t - \mu]^2$$

$$= E[\phi_1(y_{t-1} - \mu) + \epsilon_t + \phi_1 \epsilon_{t-1}]^2$$

$$= \phi_1^2 \gamma_0 + \sigma^2 + \theta_1^2 \sigma^2 + 2\phi_1 \theta_1 \sigma^2$$

$$\gamma_0 = \frac{\sigma^2 [1 + 2\phi_1 \theta_1 + \theta_1^2]}{1 - \theta_1^2}$$

$$\begin{aligned} \gamma_1 &= E[(y_t - \mu)(y_{t-1} - \mu)] \\ &= E\{ [\phi_1(y_{t-1} - \mu) + \epsilon_t + \phi_1 \epsilon_{t-1}][y_{t-1} - \mu] \} \\ &= \phi_1 \gamma_0 + \theta_1 \sigma^2 \end{aligned}$$

for
$$j \geqslant 2$$

$$\begin{split} \gamma_j &= E[(y_t - \mu)(y_{t-j} - \mu)] \\ &= E\{[\phi_1(y_{t-1} - \mu) + \epsilon_t + \phi_1 \epsilon_{t-1}][y_{t-j} - \mu]\} \\ &= \phi_1 E[(y_{t-1} - \mu)(y_{t-j} - \mu)] \\ &= \phi_1 \gamma_{j-1} \end{split}$$

Autocorrelation

$$\gamma_0 = \frac{\sigma^2 [1 + 2\phi_1 \theta_1 + \theta_1^2]}{1 - \phi_1^2}$$
$$\gamma_1 = \phi_1 \gamma_0 + \theta_1 \sigma^2$$
$$\gamma_j = \phi_1 \gamma_{j-1} \text{ for } j \geqslant 2$$
$$\rho_1 = \frac{\gamma_1}{\gamma_0}$$
$$\rho_j = \frac{\gamma_j}{\gamma_0}$$