

**EDUCATION****Texas A&M University**, College Station, Texas, Aug. 2010 – Present

Ph.D. student, Robotics &amp; Computer Vision, Computer Science &amp; Engineering, Overall GPA: 3.89/4.0

**Chinese University of Hong Kong**, Hong Kong, Aug. 2008 – Jun. 2010

M.Phil. in Mechanical &amp; Automation Engineering, Overall GPA: 3.67/4.0

**Xi'an Jiaotong University**, Xi'an, China, Aug. 2004 – Jun. 2008

B.S. in Electrical Engineering, Ranking: 1/380, Overall GPA: 3.73/4.0

**PROGRAMMING LANGUAGE**

C++, Matlab, Java, Python

**RESEARCH EXPERIENCE****Visual Navigation for Robots** Aug. 2010 – Present

- Designed a data structure consisting of heterogeneous features and geometric constraints for visual navigation.
- Applied the data structure to EKF-based and bundle adjustment-based visual odometry, respectively.
- Implemented in C++ (based on OpenCV).
- Published 3 conference papers.

**Robust Recognition of Mirrored Walls** Aug. 2010 – Aug. 2011

- Designed a two-view based vision algorithm for detecting and estimating mirrored walls.
- Implemented in Matlab.
- Published 1 conference paper.

**ECG Signal based Cardiac Condition Diagnosis** May 2009 – Jun. 2010

- Proposed novel approaches for Electrocardiogram (ECG) signal de-noising, feature extraction, and classification.
- Implemented in Matlab.
- Published 3 conference papers and 2 journal papers

**Robotic Artworks Drawing** Aug. 2008– Apr. 2009

- Developed an automatic method for a robotic manipulator to draw an artwork in pen-and-ink style based on an input digital image.
- Implemented in Matlab and C++.
- Published 1 conference paper.

**PUBLICATIONS**

- **Yan Lu**, Dezhen Song, and Jingang Yi. "High Level Landmark-Based Visual Navigation Using Unsupervised Geometric Constraints in Local Bundle Adjustment", IEEE International Conference on Robotics and Automation (ICRA), 2014
- **Yan Lu**, Dezhen Song, Yiliang Xu, A. G. Amitha Perera and Sang Min Oh. "Automatic Building Exterior Mapping Using Multilayer Feature Graphs", IEEE International Conference on Automation Science and Engineering (CASE), 2013
- **Yan Lu**, Dezhen Song, Haifeng Li and Jingtai Liu. "Automatic Recognition of Spurious Surface in Building Exterior Survey", IEEE International Conference on Automation Science and Engineering (CASE), 2013
- Haifeng Li, Dezhen Song, **Yan Lu**, and Jingtai Liu. "A Two-View based Multilayer Feature Graph for Robot Navigation", IEEE International Conference on Robotics and Automation (ICRA), 2012
- **Yan Lu**, Josh Lam, and Yeung Yam. "Preliminary Study on Vision-based Pen-and-Ink Drawing by a Robotic Manipulator", IEEE/ASME International Conference on Advanced Intelligent Mechatronics (AIM), 2009
- **Yan Lu**, Jingyu Yan, and Yeung Yam. "Model-based ECG Denoising Using Empirical Mode Decomposition", IEEE International Conference on Bioinformatics and Biomedicine (BIBM), 2009

**COURSEWORK**Computer Vision  
Pattern AnalysisAnalysis of Algorithm  
Data MiningApplied Random Process  
Linear Control SystemsMultivariate Analysis  
Convex Optimization