

# Econ720 - TA Session 9

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## Ramsey Model

### Social Planner Problem

$$\max \int_0^{\infty} e^{-(\rho-n)t} u(c_t) dt$$
$$\dot{k}_t = f(k_t) - (n + \delta)k_t - c_t$$

# Phase Diagram

Current Value Hamiltonian:

$$H = u(c_t) + \mu_t(f(k_t) - (n + \delta)k_t - c_t)$$

FOCs

$$[c_t]: u'(c_t) = \mu_t$$

$$[k_t]: \mu_t[f'(k_t) - (n + \delta)] = -\dot{\mu}_t + (\rho - n)\mu_t$$

Hence

$$\frac{u''(c_t)\dot{c}_t}{u'(c_t)} = (\delta + \rho) - f'(k_t)$$

# Phase Diagram

For simplicity, we use CRRA utility

$$u(c_t) = \frac{c_t^{1-\sigma}}{1-\sigma}$$

Hence,

$$\frac{u''(c_t)}{u'(c_t)} = -\frac{\sigma}{c_t}$$

Then the equation  $\frac{u''(c_t)\dot{c}_t}{u'(c_t)} = (\delta + \rho) - f'(k_t)$  becomes

$$\frac{\dot{c}_t}{c_t} = \frac{f'(k_t) - (\delta + \rho)}{\sigma}$$

# Phase Diagram

## How to draw phase diagram?

- 1 Find the dynamics for control and state  
Differential equation for control and for state
- 2 Think about the steady state
- 3 Plot the two steady state equations separately
- 4 Decide the movement of control and state **respectively**.

# Phase Diagram

**Step-1: Find differential equation for control and for state**

Control variable  $c_t$

$$\frac{\dot{c}_t}{c_t} = \frac{f'(k_t) - (\delta + \rho)}{\sigma}$$

State variable  $k_t$

$$\dot{k}_t = f(k_t) - (n + \delta)k_t - c_t$$

# Phase Diagram

**Step-2: How do these two equations look like in SS**

$$\frac{\dot{c}_t}{c_t} = 0 \Rightarrow f'(k^*) = \delta + \rho$$

Hence  $k^*$  is a constant

$$\dot{k}_t = 0 \Rightarrow c^* = f(k^*) - (n + \delta)k^*$$

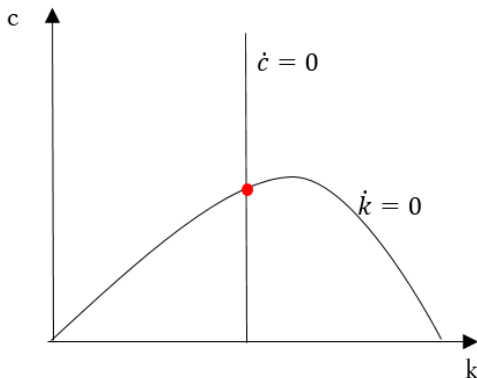
Hence  $c^*$  is a function of  $k^*$

# Phase Diagram

## Step-3: Plot the two SS equations

$$\dot{c} = 0: \quad f'(k^*) = \delta + \rho$$

$$\dot{k} = 0: \quad c^* = f(k^*) - (n + \delta)k^*$$





# Phase Diagram

## Step-4: Decide the movement of these two variables separately

- $c$  is the vertical axis  $\rightarrow c$  moves up and down
- $k$  is the horizontal axis  $\rightarrow k$  moves left and right

$$\frac{\dot{c}_t}{c_t} = \frac{f'(k_t) - (\delta + \rho)}{\sigma}$$
$$\dot{k}_t = f(k_t) - (n + \delta)k_t - c_t$$

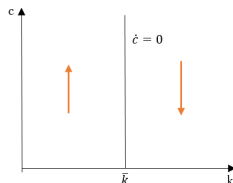
- 1 Use  $\dot{c}$  equation and change the value of  $k$  to study the movement of  $c$
- 2 Use  $\dot{k}$  equation and change the value of  $c$  to study the movement of  $k$
- 3 Put them together

# Phase Diagram

Use  $\dot{c}$  equation and change the value of  $k$  to study the movement of  $c$

$$\frac{\dot{c}}{c} = \frac{f'(k_t) - (\delta + \rho)}{\sigma}$$

- Take one  $k$  on  $\dot{c} = 0$  curve,  $k = \bar{k}$ ,  $\frac{\dot{c}}{c} = \frac{f'(\bar{k}) - (\delta + \rho)}{\sigma} = 0$
- For each  $k$  to the left of  $\bar{k}$ ,  $k < \bar{k}$ ,  
 $\frac{\dot{c}}{c} = \frac{f'(k) - (\delta + \rho)}{\sigma} > \frac{f'(\bar{k}) - (\delta + \rho)}{\sigma} = 0$   $c$  increases
- For each  $k$  to the right of  $\bar{k}$ ,  $k > \bar{k}$ ,  
 $\frac{\dot{c}}{c} = \frac{f'(k) - (\delta + \rho)}{\sigma} < \frac{f'(\bar{k}) - (\delta + \rho)}{\sigma} = 0$   $c$  decreases

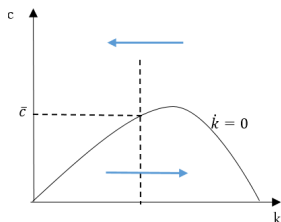


# Phase Diagram

Use  $\dot{k}$  equation and change the value of  $c$  to study the movement of  $k$

$$\dot{k}_t = f(k_t) - (n + \delta)k_t - c_t$$

- Take one  $c$  on  $\dot{k} = 0$  curve,  $c = \bar{c}$ ,  $\dot{k} = f(k) - (n + \delta)k - \bar{c} = 0$
- For each  $c$  above  $\bar{c}$ ,  $c > \bar{c}$ ,  
 $\dot{k} = f(k) - (n + \delta)k - c < f(k) - (n + \delta)k - \bar{c}$   $k$  decreases
- For each  $c$  under  $\bar{c}$ ,  $c < \bar{c}$ ,  
 $\dot{k} = f(k) - (n + \delta)k - c > f(k) - (n + \delta)k - \bar{c}$   $k$  increases



# Phase Diagram

Put them together

