

Homework 3

Li Donghao 20653877

Problem 1

1.1

ln(μ,Σ)=logΠn_{i=1}1/e^{-1/2(X_i-μ)^TΣ^{-1}(X_i-μ)}\sqrt{(2\pi)^k|\Sigma|}

=-1/2∑_{i=1}^n(X_i-μ)^TΣ^{-1}(X_i-μ)-n/2logdet(Σ)+C

=-1/2∑_{i=1}^ntrace[(X_i-μ)^TΣ^{-1}(X_i-μ)]-n/2logdet(Σ)+C

=-1/2∑_{i=1}^ntrace[Σ^{-1}(X_i-μ)(X_i-μ)^T]-n/2logdet(Σ)+C

=-n/2trace(Σ^{-1}S_n)-n/2logdet(Σ)+C

1.2

f(X+Δ)=tr(A(X+Δ)^{-1})

=tr(AX^{-1}(I+ΔX^{-1})^{-1})

≈tr(AX^{-1}(I-ΔX^{-1}))

=tr(AX^{-1})-tr(AX^{-1}ΔX^{-1})

=f(X)-tr(X^{-1}AX^{-1}Δ)

1.3

g(X+Δ)=logdet(X+Δ)

=logdet(X^{1/2}X^{1/2}+X^{1/2}X^{-1/2}ΔX^{-1/2}X^{1/2})

=logdet(X^{1/2}(I+X^{-1/2}ΔX^{-1/2})X^{1/2})

=logdet(X^{1/2}Q(I+Λ)Q^{-1}X^{1/2})

=logdet(X)+logdet(I+Λ)

≈g(X)+tr(Λ)

=g(X)+tr(X^{-1/2}ΔX^{-1/2})

=g(X)+tr(X^{-1}Δ)

Where we define the eigenvalue decomposition of X^{-1/2}ΔX^{-1/2}=QΛQ^{-1}

1.4

We need to take partial derivative w.r.t. Σ and set it to 0. So, we have :

∂ln(μ,Σ)/∂Σ=n/2(Σ^{-1}S_nΣ^{-1}+Σ^{-1}ΣΣ^{-1})=0

That is :

Σ^{MLE}=S_n

2.1

Since we can split the objective function, we can just consider the i−th term and do minimizatn. Take partial derivative w.r.t μ_i and set it to zero, we can have:

μ_i^{ridge}=1/(1+λ)y_i

Then we can compute the risk:

R=E||μ-μ^{ridge}||^2=Σ_{i=1}^pE(μ_i-1/(1+λ)y_i)^2

=λ^2/(1+λ)^2||μ||_2^2+p/(1+λ)^2

2.2

We just consider one dimension.

min_{μ_i}1/2(y_i-μ_i)^2+λ|μ_i|=1/2μ_i^2-y_iμ_i+λ|μ_i|+C

Then consider the derivative df/dμ_i=μ_i-y_i+λ|μ_i|/μ_i. When y_i>λ and μ_i>0, we have μ_i^{soft}=y_i-λ.

When y_i<λ and μ_i<0,we have μ_i^{soft}=y_i+λ.

Otherwise, we have μ_i^{soft}=0. That finish the proof.

E(μ_i^{soft}-μ_i)^2=∫_{-inf}^{-λ}(x+λ-μ)^2f(x)dx+∫_{-λ}^λ(μ)^2f(x)dx+∫_λ^{inf}(x-λ-μ)^2f(x)dx

And I don't know how to do next.

2.3

We just consider one dimension:

min_{μ_i}(y_i-μ_i)^2+λ^21(μ_i≠0)

So the minimal value should be either λ^2 or y_i^2. That means when λ>y_i,μ_i=0,when λ<y_i,μ_i=y_i.

g(x)=1 when y_i<λ, g(x)=0 when y_i>λ. Then g is weakly differentiable.

2.4

Using SURE with g(Y)=-p-2/||Y^2||Y Then we have :

U(Y)=p+2∇^Tg(Y)+||g(Y)||^2

R(μ,μ^{JS})=EU(Y)=p-E(p-2)^2/||Y||^2

Comparing with MLE, when p>2, the risk is smaller.

2.5

All the conditions are shrinkage rules.

3

In this problem, I use conter-examples to show we can improve the risk.

r(μ_C,μ)=σ^2tr(C^TC)+||(I-C)μ||^2

(a): Let A=I-(I-C)^T(I-C) which is a symmetric matrix.

||(1-A)μ||^2=μ^T(1-C)^T(1-C)μ=||(1-A)μ||^2

trace(A^TA)=n-2trace(I-A)+trace(1-A)^T(1-A)

By last equation, we have:

trace(A^TA)=n-2trace((I-C)^T(I-C)(1/2))+trace(1-C)^T(1-C)

≤n-2trace((I-C)^T(I-C))+trace((1-C)^T(1-C))=trace(C^TC)

So the risk could be improved, so it is not admissible.

(b): Assume that the eigenvalues of C can be more than 1, C=UΛU^T. Then we define B=UΛ_{new}U^T where Λ_{new_{ii}}=max(0,min(1,Λ_{ii})) Then

r(μ,μ)=σ^2tr(C^TC)+||(1-C)μ||^2

=∑_{i=1}^p(σ^2ρ_i^2+(1-ρ_i)^2μ_i^2)

>∑_{i=1}^p(σ^2Λ_{new_{ii}}^2+(1-Λ_{new_{ii}})^2μ_i^2)

=r(μ_{new},μ)

(c): If there are d≥3 eigenvalues are one, we can design a JS estimator to these dimensions. Since JS estimator has smaller risk than MLE when d≥3, the new risk can be smaller.

In []:

In []:

In []: