

Vector Algebra

- The quantity which involves only one value, i.e. magnitude, is called a scalar quantity. For example: time, mass, distance, energy, etc.
- The quantity which has both magnitude and a direction is called a vector quantity. For example: force, momentum, acceleration, etc.
- A line with a direction is called a directed line. Let \overrightarrow{AB} be a directed line along direction B.



Here,

- The length of the line segment AB represents the magnitude of the above directed line. It is denoted by $|\overrightarrow{AB}|$ or $|\vec{a}|$ or a .
 - \overrightarrow{AB} represents the vector in the direction towards point B. Therefore, the vector represented in the above figure is \overrightarrow{AB} . It can also be denoted by \vec{a} .
 - The point A from where the vector \overrightarrow{AB} starts is called its initial point and the point B where the vector \overrightarrow{AB} ends is called its terminal point.
- The angles a , b , and g made by the vector $\vec{r} = a\hat{i} + b\hat{j} + c\hat{k}$ with the positive directions of the x-axis, y-axis, and z-axis respectively are called its direction angles. The cosines of the angle made by the vector $\vec{r} = a\hat{i} + b\hat{j} + c\hat{k}$ with the positive directions of x, y, and z axes are its direction cosines. These are usually denoted by $l = \cos a$, $m = \cos b$, and $n = \cos g$. Also, $l^2 + m^2 + n^2 = 1$

Example: Write the direction ratio's of the vector $\vec{r} = 2\hat{i} - \hat{j} - 2\hat{k}$ and hence calculate its direction cosines.

Solution: The direction ratio's a , b , c of a vector $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$ are the respective components x , y and z of the vector.

The direction ratio's of the given vector are $a = 2$, $b = -1$ and $c = -2$

If l , m and n are the direction cosines of the given vector, then

$$l = \frac{a}{|\vec{r}|}, m = \frac{b}{|\vec{r}|}, n = \frac{c}{|\vec{r}|}$$

$$|\vec{r}| = \sqrt{(2)^2 + (-1)^2 + (-2)^2} = \sqrt{9} = 3$$

$$\therefore l = \frac{2}{3}, m = \frac{-1}{3} \text{ and } n = \frac{-2}{3}$$

- The direction cosines (l, m, n) of a vector $a\hat{i} + b\hat{j} + c\hat{k}$ are

$$l = \frac{a}{r}, m = \frac{b}{r}, n = \frac{c}{r}, \text{ where } r = \text{magnitude of the vector } a\hat{i} + b\hat{j} + c\hat{k}$$

- The various types of vectors are given as follows:

- Zero vector: A vector whose initial and terminal points coincide is called a zero vector (or null vector). It is denoted as $\vec{0}$. The vectors \overrightarrow{AA} , \overrightarrow{BB} represent zero vectors.
- Unit vector: A vector whose magnitude is unity, i.e. 1 unit, is called a unit vector. The unit vector in the direction of any given vector \vec{a} is denoted by \hat{a} and it is calculated by

Note: that if l , m , and n are direction cosines of a vector, then $l\hat{i} + m\hat{j} + n\hat{k}$ is the unit vector in the direction of that vector.

Example: To find the unit vector along the direction of a vector $\vec{r} = 16\hat{i} - 15\hat{j} + 12\hat{k}$, we may proceed as follows:

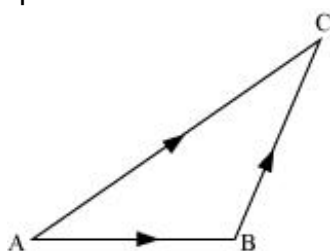
- The position vector of a point $P(x, y, z)$ with respect to the origin $(0, 0, 0)$ is given by $\overrightarrow{OP} = x\hat{i} + y\hat{j} + z\hat{k}$. This form of any vector is known as the component form.

Here,

- \hat{i} , \hat{j} , and \hat{k} are called the unit vectors along the x -axis, y -axis, and z -axis respectively.
- x , y , and z are the scalar components (or rectangular components) along x -axis, y -axis, and z -axis respectively.
- $x\hat{i} + y\hat{j} + z\hat{k}$ are called vector components of \overrightarrow{OP} along the respective axes.
- The magnitude of \overrightarrow{OP} is given by $|\overrightarrow{OP}| = \sqrt{x^2 + y^2 + z^2}$
- The scalar components of a vector are its direction ratios and represent its projections along the respective axes.

The direction ratios of a vector $\vec{p} = a\hat{i} + b\hat{j} + c\hat{k}$ are a , b , and c .
Here, a , b , and c respectively represent projections of \vec{p} along x -axis, y -axis, and z -axis.

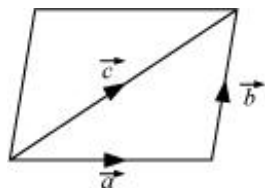
- The sum of two vectors $\vec{a} = a_1\hat{i} + a_2\hat{j} + a_3\hat{k}$ and $\vec{b} = b_1\hat{i} + b_2\hat{j} + b_3\hat{k}$ is given by,
 $\vec{a} + \vec{b} = (a_1 + b_1)\hat{i} + (a_2 + b_2)\hat{j} + (a_3 + b_3)\hat{k}$
- The difference of two vectors $\vec{a} = a_1\hat{i} + a_2\hat{j} + a_3\hat{k}$ and $\vec{b} = b_1\hat{i} + b_2\hat{j} + b_3\hat{k}$ is given by
 $\vec{a} - \vec{b} = (a_1 - b_1)\hat{i} + (a_2 - b_2)\hat{j} + (a_3 - b_3)\hat{k}$
- **Triangle law of vector addition:** If two vectors are represented by two sides of a triangle in order, then the third closing side of the triangle in the opposite direction of the order represents the sum of the two vectors.



$$\overrightarrow{AC} = \overrightarrow{AB} + \overrightarrow{BC}$$

Note: The vector sum of the three sides of a triangle taken in order is $\vec{0}$.

- **Parallelogram law of vector addition:** If two vectors are represented by two adjacent sides of a parallelogram in order, then the diagonal of the parallelogram in the opposite direction of the order represents the sum of two vectors.



$$\vec{c} = \vec{a} + \vec{b}$$

- The properties of vector addition are given as follows:
 - Commutative property: $\vec{a} + \vec{b} = \vec{b} + \vec{a}$
 - Associative property: $\vec{a} + (\vec{b} + \vec{c}) = (\vec{a} + \vec{b}) + \vec{c}$
 - Existence of additive identity: The vector $\vec{0}$ is additive identity of a vector \vec{a} , since $\vec{a} + \vec{0} = \vec{0} + \vec{a} = \vec{a}$
 - Existence of additive inverse: The vector $-\vec{a}$ is called additive inverse of \vec{a} , since $\vec{a} + (-\vec{a}) = (-\vec{a}) + \vec{a} = \vec{0}$

- The multiplication of vector $\vec{a} = a_1\hat{i} + a_2\hat{j} + a_3\hat{k}$ by any scalar λ is given by,

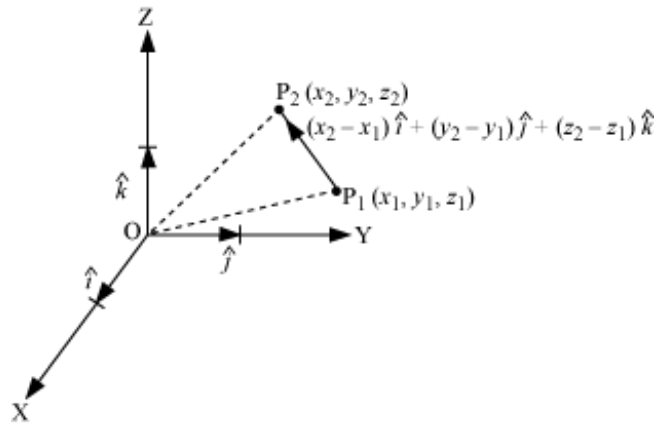
$$\lambda \vec{a} = (\lambda a_1)\hat{i} + (\lambda a_2)\hat{j} + (\lambda a_3)\hat{k}$$

- The magnitude of the vector $\lambda \vec{a}$ is given by $|\lambda \vec{a}| = |\lambda| |\vec{a}|$
- The vectors $\vec{a} = a_1\hat{i} + a_2\hat{j} + a_3\hat{k}$ and $\vec{b} = b_1\hat{i} + b_2\hat{j} + b_3\hat{k}$ are equal, if and only if $a_1 = b_1$, $a_2 = b_2$, and $a_3 = b_3$
- Let \vec{a}_1 and \vec{a}_2 be two vectors, and k_1 and k_2 be any scalars, then the following are the distributive laws of addition and multiplication of a vector by a scalar:
 - $k_1\vec{a}_1 + k_2\vec{a}_1 = (k_1 + k_2)\vec{a}_1$
 - $k_1(k_2\vec{a}_1) = (k_1k_2)\vec{a}_1$
 - $k_1(\vec{a}_1 + \vec{a}_2) = k_1a_1 + k_1a_2$
- Collinear vectors:
 - Two vectors \vec{a} and \vec{b} are collinear, if and only if there exists a non-zero scalar λ such that
 - Two vectors $\vec{a} = a_1\hat{i} + a_2\hat{j} + a_3\hat{k}$ and $\vec{b} = b_1\hat{i} + b_2\hat{j} + b_3\hat{k}$ are collinear, if and only if

Vector Joining Two Points

The vector joining two points $P_1(x_1, y_1, z_1)$ and $P_2(x_2, y_2, z_2)$, represented as $\overrightarrow{P_1P_2}$, is calculated as

$$\overrightarrow{P_1P_2} = (x_2 - x_1)\hat{i} + (y_2 - y_1)\hat{j} + (z_2 - z_1)\hat{k}$$



The magnitude of $\overrightarrow{P_1P_2}$ is given by $|\overrightarrow{P_1P_2}| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$

Section Formula

If point R (position vector \vec{r}) lies on the vector \overrightarrow{PQ} joining two points P (position vector \vec{a})

and Q (position vector \vec{b}) such that R divides \overrightarrow{PQ} in the ratio $m:n$ [i.e. $\frac{\overrightarrow{PR}}{\overrightarrow{RQ}} = \frac{m}{n}$]

Internally, then $\vec{r} = \frac{m\vec{b} + n\vec{a}}{m+n}$

Externally, then $\vec{r} = \frac{m\vec{b} - n\vec{a}}{m-n}$

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- The scalar product of two non-zero vectors \vec{a} and \vec{b} is denoted by $\vec{a} \cdot \vec{b}$ and it is given by the formula $\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos \theta$, where θ is the angle between \vec{a} and \vec{b} such that $0 \leq \theta \leq \pi$

If either $\vec{a} = 0$ or $\vec{b} = 0$, then in this case, θ is not defined and $\vec{a} \cdot \vec{b} = 0$

- The following are the observations related to the scalar product of two vectors:
 - $\vec{a} \cdot \vec{b}$ is a real number.
 - The angle θ between vectors \vec{a} and \vec{b} is given by,

$$\cos \theta = \frac{\vec{a} \cdot \vec{b}}{|\vec{a}| |\vec{b}|} \Rightarrow \theta = \cos^{-1} \left(\frac{\vec{a} \cdot \vec{b}}{|\vec{a}| |\vec{b}|} \right)$$

- Let \vec{a} and \vec{b} be any two non-zero vectors, then $\vec{a} \cdot \vec{b} = 0$, if and only if $\vec{a} \perp \vec{b}$
- If $q = 0$, then $\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}|$
- If $q = \pi$, then $\vec{a} \cdot \vec{b} = -|\vec{a}| |\vec{b}|$
- $\hat{i} \cdot \hat{i} = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} = 1, \hat{i} \cdot \hat{j} = \hat{j} \cdot \hat{k} = \hat{k} \cdot \hat{i} = 0$
- If $\vec{a} = a_1\hat{i} + a_2\hat{j} + a_3\hat{k}$ and $\vec{b} = b_1\hat{i} + b_2\hat{j} + b_3\hat{k}$, then $\vec{a} \cdot \vec{b} = a_1b_1 + a_2b_2 + a_3b_3$
- The properties of scalar product are as follows:
 - Commutative property: $\hat{a} \cdot \hat{b} = \hat{b} \cdot \hat{a}$
 - Distributivity of scalar product over addition: $\hat{a} \cdot (\hat{b} + \hat{c}) = \hat{a} \cdot \hat{b} + \hat{a} \cdot \hat{c}$

Example: Find the angle between the vectors $8\hat{i} - 4\hat{j} - \hat{k}$ and $3\hat{i} - 6\hat{j} + 2\hat{k}$.

Solution:

Let $\vec{a} = 8\hat{i} - 4\hat{j} - \hat{k}$

$\vec{b} = 3\hat{i} - 6\hat{j} + 2\hat{k}$

Angle between \vec{a} and \vec{b} is given by,

$$\theta = \cos^{-1} \left(\frac{\vec{a} \cdot \vec{b}}{|\vec{a}| |\vec{b}|} \right)$$

However, $\vec{a} \cdot \vec{b} = 8 \times 3 + (-4) \times (-6) + (-1) \times 2 = 46$

$$|\vec{a}| = \sqrt{(8)^2 + (-4)^2 + (-1)^2} = 9$$

$$|\vec{b}| = \sqrt{(3)^2 + (-6)^2 + (2)^2} = 7$$

$$\therefore \theta = \cos^{-1} \left(\frac{46}{9 \times 7} \right) = \cos^{-1} \left(\frac{46}{63} \right)$$

- Projection of a vector:
 - If \hat{p} is the unit vector along a line l , then the projection of a vector \vec{a} on the line l is given by $\vec{a} \cdot \hat{p}$.
 - Projection of a vector \vec{a} on other vector \vec{b} is given by $\vec{a} \cdot \hat{b}$ or $\frac{\vec{a} \cdot \vec{b}}{|\vec{b}|}$.

Example: Find the projection of the vector $3\hat{i} - 8\hat{j} + 6\hat{k}$ on the vector $2\hat{i} - 3\hat{j} - 6\hat{k}$.

Solution:

Let $\vec{a} = 3\hat{i} - 8\hat{j} + 6\hat{k}$ and $\vec{b} = 2\hat{i} - 3\hat{j} - 6\hat{k}$

Then, the projection of \vec{a} on \vec{b} is given by,

$$\frac{\vec{a} \cdot \vec{b}}{|\vec{b}|} = \frac{(3\hat{i} - 8\hat{j} + 6\hat{k}) \cdot (2\hat{i} - 3\hat{j} - 6\hat{k})}{\sqrt{(2)^2 + (-3)^2 + (-6)^2}}$$

$$= \frac{6 + 24 - 36}{7}$$

$$= -\frac{6}{7}$$

- The vector product (or cross product) of two non-zero vectors \vec{a} and \vec{b} is denoted by $\vec{a} \times \vec{b}$ and is defined by $\vec{a} \times \vec{b} = |\vec{a}| |\vec{b}| \sin \theta \hat{n}$, where θ is the angle between \vec{a} and \vec{b} , $0 \leq \theta \leq \pi$, and \hat{n} is a unit vector perpendicular to both \vec{a} and \vec{b} .
- If $\vec{a} = a_1\hat{i} - a_2\hat{j} + a_3\hat{k}$ and $\vec{b} = b_1\hat{i} - b_2\hat{j} + b_3\hat{k}$ are two vectors, then their cross product

$$\vec{a} \times \vec{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

$\vec{a} \times \vec{b}$, is defined by

- The following are the observations made by the vector product of two vectors:

- $\vec{a} \times \vec{b} = \vec{0}$, if and only if $\vec{a} \parallel \vec{b}$
- $\hat{i} \times \hat{i} = \hat{j} \times \hat{j} = \hat{k} \times \hat{k} = 0$

$$\hat{i} \times \hat{j} = \hat{k}, \hat{j} \times \hat{k} = \hat{i}, \hat{k} \times \hat{i} = \hat{j}$$

$$\hat{j} \times \hat{i} = -\hat{k}, \hat{k} \times \hat{j} = -\hat{i}, \hat{i} \times \hat{k} = -\hat{j}$$

- In terms of vector product, the angle θ between two vectors \vec{a} and \vec{b} is given by

$$\sin \theta = \frac{|\vec{a} \times \vec{b}|}{|\vec{a}| |\vec{b}|} \text{ or}$$

- If \vec{a} and \vec{b} represent the adjacent sides of a triangle, then its area is given as $\frac{1}{2} |\vec{a} \times \vec{b}|$.

Example:

Find the area of a triangle having the points A (1, 2, 3), B (1, -1, -3) and C (-1, 1, 2) as its vertices

Solution:

$$\overrightarrow{AB} = (1-1)\hat{i} + (-1-2)\hat{j} + (-3-3)\hat{k} = -3\hat{j} - 6\hat{k}$$

$$\overrightarrow{AC} = (-1-1)\hat{i} + (1-2)\hat{j} + (2-3)\hat{k} = -2\hat{i} - \hat{j} - \hat{k}$$

$$\text{The area of the given triangle is } \frac{1}{2} |\overrightarrow{AB} \times \overrightarrow{AC}|$$

$$\begin{aligned}\overrightarrow{AB} \times \overrightarrow{AC} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 0 & -3 & -6 \\ -2 & -1 & -1 \end{vmatrix} \\ &= \hat{i}(3 - 6) - \hat{j}(0 - 12) + \hat{k}(0 - 6)\end{aligned}$$

$$= -3\hat{i} + 12\hat{j} - 6\hat{k}$$

$$\therefore \left| \overrightarrow{AB} \times \overrightarrow{AC} \right| = \sqrt{(-3)^2 + (12)^2 + (-6)^2} = \sqrt{9 + 144 + 36} = \sqrt{189}$$

Thus, the required area is $\frac{1}{2}\sqrt{189}$.

- If \vec{a} and \vec{b} represent the adjacent sides of a parallelogram, then its area is given as $\left| \vec{a} \times \vec{b} \right|$.

- The properties of vector product are as follows:

- Not commutative: $\vec{a} \times \vec{b} \neq \vec{b} \times \vec{a}$

However, $\vec{a} \times \vec{b} = -\vec{b} \times \vec{a}$

- Distributivity of vector product over addition:

$$\begin{aligned}\blacksquare \quad \vec{a} \times (\vec{b} + \vec{c}) &= \vec{a} \times \vec{b} + \vec{a} \times \vec{c} \\ \blacksquare \quad \lambda (\vec{a} \times \vec{b}) &= (\lambda \vec{a}) \times \vec{b} = \vec{a} \times (\lambda \vec{b})\end{aligned}$$

Example: If the position vectors of vertices P, Q, R, and S of quadrilateral PQRS are $-\hat{i} + 2\hat{j} + \hat{k}$, $\hat{i} - 2\hat{j} + 5\hat{k}$, $4\hat{i} - 7\hat{j} + 8\hat{k}$, and $2\hat{i} - 3\hat{j} + 4\hat{k}$ respectively, then find the area of quadrilateral PQRS.

Solution:

$$\overrightarrow{PQ} = (1+1)\hat{i} + (-2-2)\hat{j} + (5-1)\hat{k} = 2\hat{i} - 4\hat{j} + 4\hat{k}$$

$$\overrightarrow{QR} = (4-1)\hat{i} + (-7+2)\hat{j} + (8-5)\hat{k} = 3\hat{i} - 5\hat{j} + 3\hat{k}$$

$$\begin{aligned}\overrightarrow{RS} &= (2-4)\hat{i} + (-3+7)\hat{j} + (4-8)\hat{k} = -2\hat{i} + 4\hat{j} + 4\hat{k} \\ &= -(2\hat{i} - 4\hat{j} + 4\hat{k}) \\ &= -\overrightarrow{PQ}\end{aligned}$$

$$\begin{aligned}\overrightarrow{SP} &= (-1-2)\hat{i} + (2+3)\hat{j} + (1-4)\hat{k} = -3\hat{i} + 5\hat{j} - 3\hat{k} \\ &= -(3\hat{i} - 5\hat{j} + 3\hat{k}) \\ &= -\overrightarrow{QR}\end{aligned}$$

Clearly, $\overrightarrow{PQ} \parallel \overrightarrow{RS}$ and $\overrightarrow{QR} \parallel \overrightarrow{SP}$. Hence, PQRS is a parallelogram.

$$\text{Therefore, area (PQRS)} = \left| \overrightarrow{PQ} \times \overrightarrow{QR} \right|$$

Now,

$$\begin{aligned}\overrightarrow{PQ} \times \overrightarrow{QR} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2 & -4 & 4 \\ 3 & -5 & 3 \end{vmatrix} \\ &= (-12+20)\hat{i} - (6-12)\hat{j} + (-10+12)\hat{k} \\ &= 8\hat{i} + 6\hat{j} + 2\hat{k}\end{aligned}$$

$$\therefore \left| \overrightarrow{PQ} \times \overrightarrow{QR} \right| = \sqrt{(8)^2 + (6)^2 + (2)^2} = 2\sqrt{26}$$

Hence, area of the quadrilateral PQRS is $2\sqrt{26}$ square units.