

Matrices

• A **matrix** is an ordered rectangular array of numbers or functions. The numbers or functions are called the **elements** or the **entries** of the matrix.

For example, $\begin{bmatrix} -10 & \sin x & \log x \\ e^x & 2 & -9 \end{bmatrix}$ is a matrix having 6 elements. In this matrix, number of rows = 2 and number of columns = 3

• A matrix having m rows and n columns is called a matrix of order $m \times n$. In such a matrix, there are mn numbers of elements.

For example, the order of the matrix $\begin{bmatrix} \sin x & \cos x \\ -1 & 1 + \sin x \\ 0 & \cos x \end{bmatrix}$ is 3×2 as the numbers of rows and columns of this matrix are 3 and 2 respectively.

• A matrix A is said to be a **row matrix**, if it has only one row. In general, $A = [a_{ij}]_{1 \ge n}$ is a row matrix of order $1 \times n$.

For example, $\begin{bmatrix} -9 & 6 & 5 & e & \sin x \end{bmatrix}$ is a row matrix of order 1 × 5.

• A matrix *B* is said to be a **column matrix**, if it has only one column. In general, $B = [b_{ij}]_{m \times 1}$ is a column matrix of order $m \times 1$.

 $B = \begin{bmatrix} -6\\19\\13 \end{bmatrix}$ is a column matrix of order 3 × 1.

• A matrix C is said to be a **square matrix**, if the number of rows and columns of the matrix are equal. In general, $C = [b_{ij}]_{m \gg n}$ is a square matrix, if m = n

For example, $C = \begin{bmatrix} -1 & 9 \\ 5 & 1 \end{bmatrix}$ is a square matrix.

- A square matrix A is said to be a **diagonal matrix**, if all its non-diagonal elements are zero. In general, $A = [a_{ij}]_{m \times n}$ is a diagonal matrix, if $a_{ij} = 0$ for $i \neq j$
- A matrix is said to be a rectangular matrix, if the number of rows is not equal to the number of columns.

For example: $\begin{bmatrix} 8 & 3 & 9 \\ 1 & 6 & 7 \end{bmatrix}$ is a rectangular matrix.

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• Two matrices $A = [a_{ij}]$ and $B = [b_{ij}]$ can be added, if they are of the same order.

The sum of two matrices A and B of same order $m \times n$ is defined as matrix $C = [c_{ij}]_{m \times n}$, where $c_{ij} = a_{ij} + b_{ij}$ for all possible values of i and j.

- The difference of two matrices A and B is defined, if and only if they are of same order. The difference of the matrices A and B is defined as A B = A + (-1)B
- If A, B, and C are three matrices of same order, then they follow the following properties related to addition:
 - Commutative law: A + B = B + A

- Associative law: A + (B + C) = (A + B) + C
- Existence of additive identity: For every matrix A, there exists a matrix O such that A + O = O + A = A. In this case, O is called the additive identity for matrix addition.
- Existence of additive inverse: For every matrix A, there exists a matrix (-A) such that A + (-A) = (-A) + A = O. In this case, (-A) is called the additive inverse or the negative of A.

Example: Find the value of x and y, if:

$$\begin{bmatrix} 2x + 3y & 9 \\ -2 & 4x - 7y \end{bmatrix} + 2 \begin{bmatrix} 3x + \frac{5}{2}y & -11 \\ -13 & 3x - \frac{3}{2}y \end{bmatrix} = \begin{bmatrix} 56 & -13 \\ -28 & 30 \end{bmatrix}$$

Solution:

$$\begin{bmatrix} 2x + 3y & 9 \\ -2 & 4x - 7y \end{bmatrix} + 2 \begin{bmatrix} 3x + \frac{5}{2}y & -11 \\ -13 & 3x - \frac{3}{2}y \end{bmatrix} = \begin{bmatrix} 56 & -13 \\ -28 & 30 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 2x + 3y & 9 \\ -2 & 4x - 7y \end{bmatrix} + \begin{bmatrix} 6x + 5y & -22 \\ -26 & 6x - 3y \end{bmatrix} = \begin{bmatrix} 56 & -13 \\ -28 & 30 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 8(x + y) & -13 \\ -28 & 10(x - y) \end{bmatrix} = \begin{bmatrix} 56 & -13 \\ -28 & 30 \end{bmatrix}$$

Therefore, we have

8
$$(x + y) = 56$$
 and 10 $(x - y) = 30$
 $\Rightarrow x + y = 7$... (1)
And
 $x - y = 3$... (2)

Solving equation (1) and (2), we obtain x = 5 and y = 2

• The multiplication of a matrix A of order $m \times n$ by a scalar k is defined as

$$kA = kA = k[a_{ij}]_{m \times n} = [k(a_{ij})]_{m \times n}$$

- If A and B are matrices of same order and k and I are scalars, then
 - \circ k(A + B) = kA + kB
 - $\circ (k+l) A = kA + lA$
- The negative of a matrix B is denoted by -B and is defined as (-1)B.
- The product of two matrices A and B is defined, if the number of columns of A is equal to the number of rows of B.
- If $A = [a_{ij}]_{m \times n}$ and $B = [b_{jk}]_{n \times p}$ are two matrices, then their product is defined as $AB = C = [c_{ik}]_{m \times p}$, where $c_{ik} = \sum_{j=1}^{n} a_{ij}b_{jk}$

For example, if
$$A = \begin{bmatrix} 2 & -3 & 7 \\ 0 & 1 & -9 \end{bmatrix}$$
 and $B = \begin{bmatrix} -5 & 9 \\ 7 & 2 \\ 0 & 1 \end{bmatrix}$, then

$$AB = \begin{bmatrix} 2 & -3 & 7 \\ 0 & 1 & -9 \end{bmatrix} \times \begin{bmatrix} -5 & 9 \\ 7 & 2 \\ 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 2 \times (-5) + (-3) \times 7 + 7 \times 0 & 2 \times 9 + (-3) \times 2 + 7 \times 1 \\ 0 \times (-5) + 1 \times 7 + (-9) \times 0 & 0 \times 9 + 1 \times 2 + (-9) \times 1 \end{bmatrix}$$

$$= \begin{bmatrix} -31 & 19 \\ 7 & -7 \end{bmatrix}$$

- If A, B, and C are any three matrices, then they follow the following properties related to multiplication:
 - Associative law: (AB) C = A (BC)
 - Distribution law: A(B + C) = AB + AC and (A + B)C = AC + BC, if both sides of equality are defined.
 - Existence of multiplicative identity: For every square matrix A, there exists an identity matrix I of same order such that IA = AI = A. In this case, I is called the multiplicative identity.
- Multiplication of two matrices is not commutative. There are many cases where the product *AB* of two matrices *A* and *B* is defined, but the product *BA* need not be defined.

For example, if $A = \begin{bmatrix} -1 & 5 \end{bmatrix}_{1 \times 2}$ and $B = \begin{bmatrix} 0 & 1 & -4 \\ 3 & 2 & -1 \end{bmatrix}_{2 \times 3}$, then AB is defined where as BA is not defined.

• If A is a matrix of order $m \times n$, then the matrix obtained by interchanging the rows and columns of A is called the transpose of matrix A. The transpose of A is denoted by A' or A^T . In other words, if $A = [a_{ij}]_{m \times n}$, then $A' = [a_{ij}]_{n \times m}$

For example, the transpose of the matrix $\begin{bmatrix} 2 & 8 & -3 \\ 1 & 11 & 9 \end{bmatrix}$ is $\begin{bmatrix} 2 & 1 \\ 8 & 11 \\ -3 & 9 \end{bmatrix}$.

- For any matrices A and B of suitable orders, the properties of transpose of matrices are given as:
 - o (A')' = A
 - o (kA)' = kA', where k is a constant
 - (A + B)' = A' + B'
 - \circ (AB)' = B'A'
- If A is square matrix such that A' = A, then A is called a symmetric matrix. I.e., square matrix $A = [a_{ij}]$ is symmetric if $[a_{ij}] = [a_{ji}]$ for all possible values of i and i.

$$A = \begin{bmatrix} 1 & 5 & -8 \\ 5 & -2 & 6 \\ -8 & 6 & 4 \end{bmatrix}. \text{ Now, } A' = \begin{bmatrix} 1 & 5 & -8 \\ 5 & -2 & 6 \\ -8 & 6 & 4 \end{bmatrix} = A.$$

Thus, A is a symmetric matrix.

If A is a square matrix such that A' = -A, then A is called a skew symmetric matrix. I.e., A square matrix $A = [a_{ij}]$ is skew symmetric if $a_{ij} = -a_{ji}$ for all possible values of *i* and *j*.

For i = j, $a_{ii} = -a_{ii}$ i.e. $a_{ii} = 0$. This means, all the diagonal elements of a skew symmetric matrix are 0.

For example, let
$$A = \begin{bmatrix} 0 & -5 & -8 \\ 5 & 0 & -6 \\ 8 & 6 & 0 \end{bmatrix}.$$

$$A' = \begin{bmatrix} 0 & 5 & 8 \\ -5 & 0 & 6 \\ -8 & -6 & 0 \end{bmatrix} = -\begin{bmatrix} 0 & -5 & -8 \\ 5 & 0 & -6 \\ 8 & 6 & 0 \end{bmatrix} = -A$$
Now.

Thus, A is a skew symmetric matrix

- For any square matrix A with entries as real numbers, A + A' is a symmetric matrix and A - A' is a skew symmetric matrix.
- Every square matrix can be expressed as the sum of a symmetric matrix and a skew symmetric matrix. In other words, if A is any square matrix, then A can be expressed as P + Q. where $P = \frac{1}{2}(A + A')$ and $Q = \frac{1}{2}(A - A')$. Here, P is symmetric matrix and Q is a skew symmetric matrix.

Example: Express the matrix
$$A = \begin{bmatrix} 1 & 2 & -3 \\ -5 & -2 & 4 \\ -9 & 6 & -7 \end{bmatrix}$$
 as the sum of a symmetric and a skew

symmetric matrix.

Solution:

We have
$$A = \begin{bmatrix} 1 & 2 & -3 \\ -5 & -2 & 4 \\ -9 & 6 & -7 \end{bmatrix}$$

$$\therefore A' = \begin{bmatrix} 1 & -5 & -9 \\ 2 & -2 & 6 \\ -3 & 4 & -7 \end{bmatrix}$$

$$P = \frac{1}{2}(A + A') = \frac{1}{2} \begin{bmatrix} 1 & 2 & -3 \\ -5 & -2 & 4 \\ -9 & 6 & -7 \end{bmatrix} + \begin{bmatrix} 1 & -5 & -9 \\ 2 & -2 & 6 \\ -3 & 4 & -7 \end{bmatrix} = \begin{bmatrix} 1 & -\frac{3}{2} & -6 \\ -\frac{3}{2} & -2 & 5 \\ -6 & 5 & -7 \end{bmatrix}$$
Now,
$$\therefore P' = \begin{bmatrix} 1 & -\frac{3}{2} & -6 \\ -\frac{3}{2} & -2 & 5 \\ -6 & 5 & -7 \end{bmatrix} = P$$

Thus, *P* is a symmetric matrix. Now,

- The various elementary operations or transformations on a matrix are as follows:
 - \circ R_i \leftrightarrow R_i or C_i \leftrightarrow C_i
 - ∘ $R_i \leftrightarrow kR_i$ or $C_i \leftrightarrow kC_i$, where k is a non-zero constant
 - ∘ $R_i \leftrightarrow R_i + kR_i$ or $C_i \leftrightarrow C_i + kC_j$, where k is a constant.

For example, by applying R₁
$$\rightarrow$$
 R₁ $-$ 7R₃ to the matrix $\begin{bmatrix} -9 & 5 & 8 \\ 5 & 6 & 11 \\ 2 & -1 & 0 \end{bmatrix}$, we obtain $\begin{bmatrix} -23 & 12 & 8 \\ 5 & 6 & 11 \\ 2 & -1 & 0 \end{bmatrix}$.

- If A and B are the square matrices of same order such that AB = BA = I, then B is called the inverse of A and A is called the inverse of B. i.e., $A^{-1} = B$ and $B^{-1} = A$
- If A and B are invertible matrices of the same order, then $(AB)^{-1} = B^{-1} A^{-1}$
- If the inverse of a square matrix exists, then it is unique.
- If the inverse of a matrix exists, then it can be calculated either by using elementary row operations or by using elementary column operations.

Example: Find the inverse of the matrix:
$$A = \begin{bmatrix} \sin \theta & \cos \theta \\ -\cos \theta & \sin \theta \end{bmatrix}$$

Solution:

We know that A = IA. Therefore, we have

$$\begin{bmatrix} \sin \theta & \cos \theta \\ -\cos \theta & \sin \theta \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} A$$

Applying $R_1 \rightarrow \sin \theta R_1$ and $R_2 \rightarrow \cos \theta R_2$, we have

$$\begin{bmatrix} \sin^2 \theta & \sin \theta \cos \theta \\ -\cos^2 \theta & \sin \theta \cos \theta \end{bmatrix} = \begin{bmatrix} \sin \theta & 0 \\ 0 & \cos \theta \end{bmatrix} A$$

Applying $R_1 \rightarrow R_1 - R_2$, we have

$$\begin{bmatrix} \sin^{2}\theta + \cos^{2}\theta & 0 \\ -\cos^{2}\theta & \sin\theta & \cos\theta \end{bmatrix} = \begin{bmatrix} \sin\theta & -\cos\theta \\ 0 & \cos\theta \end{bmatrix} A$$

$$\Rightarrow \begin{bmatrix} 1 & 0 \\ -\cos^{2}\theta & \sin\theta & \cos\theta \end{bmatrix} = \begin{bmatrix} \sin\theta & -\cos\theta \\ 0 & \cos\theta \end{bmatrix} A$$

Applying
$$R_2 \to R_2 + \cos^2\theta R_1$$
, we have
$$\Rightarrow \begin{bmatrix} 1 & 0 \\ 0 & \sin\theta\cos\theta \end{bmatrix} = \begin{bmatrix} \sin\theta & -\cos\theta \\ \sin\theta\cos^2\theta & \cos\theta(1-\cos^2\theta) \end{bmatrix} A$$