

# Design of Integrated Microrobotic Fish

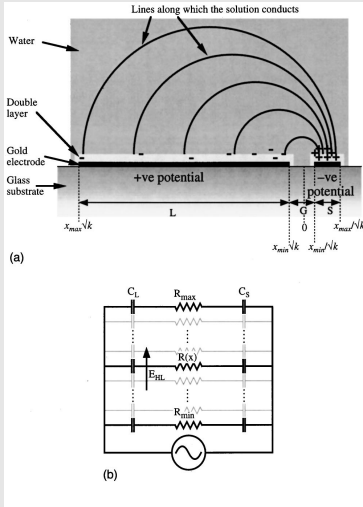
## Presentation 2 - Physical Model (Preliminary)

Yihua Liu

UM-SJTU Joint Institute

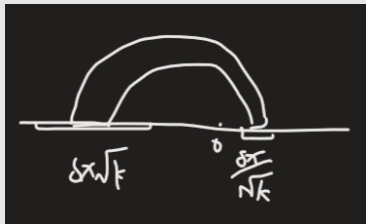
March 2, 2021

# Basic Frame



- The double layers at the electrode surfaces  $\rightarrow$  Capacitance  
The capacitance of the double layer at each end of the tube per unit length of the electrode  $C_{DL}$  and at the large electrode  $C_{DS}$
- The bulk water  $\rightarrow$  Resistance  
The resistance of the tube per unit length of electrode  $R(x)$

# Resistance



Different from common three-dimensional resistance given by  $R = \frac{\rho L}{S}$ , here the resistance is two-dimensional given by  $R = \frac{\rho L}{\sigma d} = \frac{L}{\sigma d}$ .

We can take infinitesimals of  $x$  ( $\delta x$ ) to calculate  $R(x)$ . Here we can assume the electric field lines are semicircles, so  $L = \pi r$  where the radius  $r = \frac{\sqrt{k} + \frac{1}{\sqrt{k}}}{2}$ .

Therefore, we have

$$R(x) = \frac{\pi x \left( \sqrt{k} + \frac{1}{\sqrt{k}} \right)}{2\sigma \delta x}.$$

# Capacitance

Different from common three-dimensional capacitance given by  $C = \frac{\epsilon S}{d}$ , here the resistance is two-dimensional given by  $R = \frac{\epsilon L}{d}$ . Then, we can derive that  $C_{DL} = \frac{\epsilon \delta x \sqrt{k}}{\lambda_D}$  and  $C_{DL} = \frac{\epsilon \delta x}{\sqrt{k} \lambda_D}$ .

# Electric Field

Now, there are three parts of impedance:  $C_{DL}$ ,  $C_{DS}$ , and  $R(x)$  in total, and the total difference of electric potential is  $\Psi = \Psi_0 \exp i\omega t$ . Based on two equations:

$$\Psi = I \cdot R_{total} = I \left( R + \frac{1}{i\omega C_{DL}} + \frac{1}{i\omega C_{DS}} \right)$$

$$\Psi_{DL}(x) = I \cdot \frac{1}{i\omega C_{DL}}$$

We have

$$\Psi_{DL}(x) = \Psi - IR - \frac{I}{i\omega C_{DS}} = \frac{\Psi}{1+k} \frac{1}{1 + \frac{i\omega \varepsilon \pi x}{2\lambda_D \sigma}}$$

# Electric Field

Then, by taking the derivative of  $\Psi_{DL}(x)$ , we have

$$E_{HL} = \frac{1}{\sqrt{k}} \frac{d\Psi_{DL}}{dx} = -\frac{\Psi}{\sqrt{k}(1+k)} \frac{\frac{i\omega\varepsilon\pi}{2\lambda_D\sigma}}{\left(1 + \frac{i\omega\varepsilon\pi x}{2\lambda_D\sigma}\right)^2}$$

# Velocity

Based on the principle of the fluid dynamics, we have the velocity of the ions and the fluid  $v_{DL}$  is

$$v_{DL} = \frac{\lambda_D \rho_{DL} E_{HL}}{\eta}$$

where

$$\rho_{DL} = \frac{\psi_{DL} C_{DL}}{\delta x \sqrt{k}} = \frac{\psi_{DL} \varepsilon}{\lambda_D}$$

# Velocity

$$\begin{aligned}
 \text{In}[*] = & \left( *V_{L0} = \frac{e}{2\eta \sqrt{k} (1+k)^2} ; * \right) \\
 & \left( * \omega_0 = \frac{2\lambda_0 c}{c + p_1} ; * \right) \\
 V_{DL} = & - \frac{V_{L0}}{X} * \omega_0^2 * \frac{\left( \frac{u+x}{\omega_0} \right)^2}{\left( 1 + \left( \frac{u+x}{\omega_0} \right)^2 \right)^2} \\
 \text{Out}[*] = & - \frac{X \omega^2 V_{L0} \omega_0^2}{\left( 1 + \frac{x^2 \omega^2}{\omega_0^2} \right)^2 \omega_0^2} \\
 \text{In}[*] = & V_{ave} = \frac{\int_{x_{min}}^{x_{max}} V_{DL} dx}{X_{max} - X_{min}} \\
 \text{Out}[*] = & \frac{\omega^2 \omega_0^2 \omega_0^2 \left( -\frac{1}{2 \omega^4 x_{max}^2 + 2 \omega^2 \omega_0^2} + \frac{1}{2 \omega^4 x_{min}^2 + 2 \omega^2 \omega_0^2} \right)}{2 \sqrt{k} (1+k)^2 \eta (X_{max} - X_{min})} \quad \text{if } \text{condition} * \\
 \text{In}[*] = & V_{ave} = \frac{\int_{x_{min}}^{x_{max}} V_{DL} dx}{X_{max} - X_{min}} \\
 \text{Out}[*] = & - \frac{\omega^2 V_{L0} \omega_0^2 \left( -\frac{1}{2 \omega^4 x_{max}^2 + 2 \omega^2 \omega_0^2} + \frac{1}{2 \omega^4 x_{min}^2 + 2 \omega^2 \omega_0^2} \right)}{X_{max} - X_{min}} \quad \text{if } \text{condition} *
 \end{aligned}$$

Inspired by the method we calculate the average power  $P = UI^*$ , we can take the time average of the velocity by

$$\langle v_{DL} \rangle = \frac{1}{2} \text{Re} \left\{ \frac{\lambda_D \rho_{DL} E_{HL}^*}{\eta} \right\}$$



# Velocity

```

In[ ]:= Refine[ $V_{ave} = \frac{\int_{x_{min}}^{x_{max}} v_{Dl} dx}{x_{max} - x_{min}}$ ,
  [精化]

  {Element[ $\omega_0$ , Reals], Element[ $\omega$ , Reals], Element[ $x_{max}$ , Reals],
    [属于] [实数域] [属于] [实数域] [属于] [实数域]

    Element[ $x_{min}$ , Reals],  $x_{max} > x_{min}$ , Element[ $x$ , Reals],  $\omega_0 > 0$ ,  $\omega > 0$ }
    [属于] [实数域] [属于] [实数域]

    
$$Out[ ]:= - \frac{\omega^2 v_{L0} \omega_0^2 \omega_0^2 \left( -\frac{1}{2 \omega^4 x_{max}^2 + 2 \omega^2 \omega_0^2} + \frac{1}{2 \omega^4 x_{min}^2 + 2 \omega^2 \omega_0^2} \right)}{x_{max} - x_{min}}$$


  In[ ]:=  $\lambda_0 = 30 * 10^{-9}$ ;
   $\sigma = 0.00123$ ;
   $k = 6.12$ ;
   $v_{L0} = 2.82 * 10^{-9}$ ;
   $\omega_0 = 0.03318$ ;
   $x_{min} = 1.6 * 10^{-6}$ ;
   $x_{max} = 12 * 10^{-6}$ ;
   $\omega_0 = 0.8$ ;
  
$$\omega = \frac{\omega_0}{\sqrt{x_{min} * x_{max}}}$$

   $V_{ave}$ 

  Out[ ]:= 7572.26

  Out[ ]:= -0.0000663529

```

# Unresolved Problem

According to previous calculation of total impedance,

$$Z = \frac{\pi \left( \sqrt{k} + \frac{1}{\sqrt{k}} \right)}{2\sigma \ln \frac{x_{max}}{x_{min}}} + \frac{\varepsilon (x_{max} - x_{min})}{\lambda_D \left( \sqrt{k} + \frac{1}{\sqrt{k}} \right)}$$

However, the article gives a different result that

$$Z = \frac{\pi \left( \sqrt{k} + \frac{1}{\sqrt{k}} \right)}{2l\sigma} \frac{\ln A - i\theta}{(\ln A)^2 + \theta^2}$$

where

$$A = \frac{\sqrt{\left[ (2\lambda_D\sigma)^2 + (\omega\varepsilon\pi)^2 + x_{min}x_{max} \right]^2 + [2\lambda_D\sigma\omega\varepsilon\pi (x_{max} - x_{min})]^2}}{(2\lambda_D\sigma)^2 + (\omega\varepsilon\pi x_{min})^2}$$

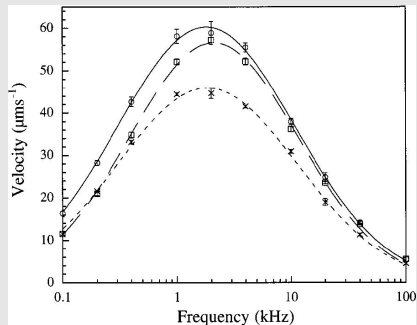
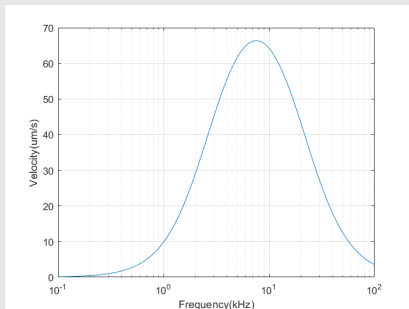
# Velocity

```

velocity.m
1  psi = 0.8; %potential between two electrodes
2  vL0 = 2.82 * 10-9; %velocity of the large electrode
3  w0 = 0.03318; %  $\omega_0$ 
4  xmin = 1.6 * 10-6;
5  xmax = 12 * 10-6;
6  w = 0.1:1000:1:100*1000; % x
7  a = sqrt(xmin.*xmax)/w0;
8  c = xmax/xmin;
9  d = xmin/xmax;
10 Vave = ((psi.^2 .* vL0) ./ (2.*(xmax-xmin))).*(((w.*a).^2.*(c-d))./(((w.*a).^2 + d).*((w.*a).^2 + c))); %y
11 semilogx(w./1000, Vave ./ (10-6));
12
13 grid on;
14 xlabel('Frequency (kHz)');
15 ylabel('Velocity (um/s)');
16

```

# Velocity



# Unresolved Problem

and

$$\theta = \arctan \frac{2\lambda_D \sigma \omega \varepsilon \pi (x_{max} - x_{min})}{(2\lambda_D \sigma)^2 + (\omega \varepsilon \pi)^2 x_{min} x_{max}}$$

# Unresolved Problem

$ln[*]= \lambda_D = 4.56 \times 10^{-9};$

$\sigma = 0.018;$

$k = 6.12;$

$V_{Le} = 2.82 \times 10^{-9};$

$X_{min} = 1.6 \times 10^{-6};$

$X_{max} = 12 \times 10^{-6};$

$\Phi_0 = 0.1;$

$\omega = 2 \text{ Pi} \times 1000;$

⌈圓周率

$l = 0.235;$

$\epsilon = 80;$

$Z$

$\theta$

$A$

$Z_0$

$Out[*]= 63519.5$

$Out[*]= 5.63092 \times 10^{-11}$

$Out[*]= 3.90625 \times 10^{11}$

$Out[*]= 40.0423 - 8.4476 \times 10^{-11} i$

However, this does not match its figures.

