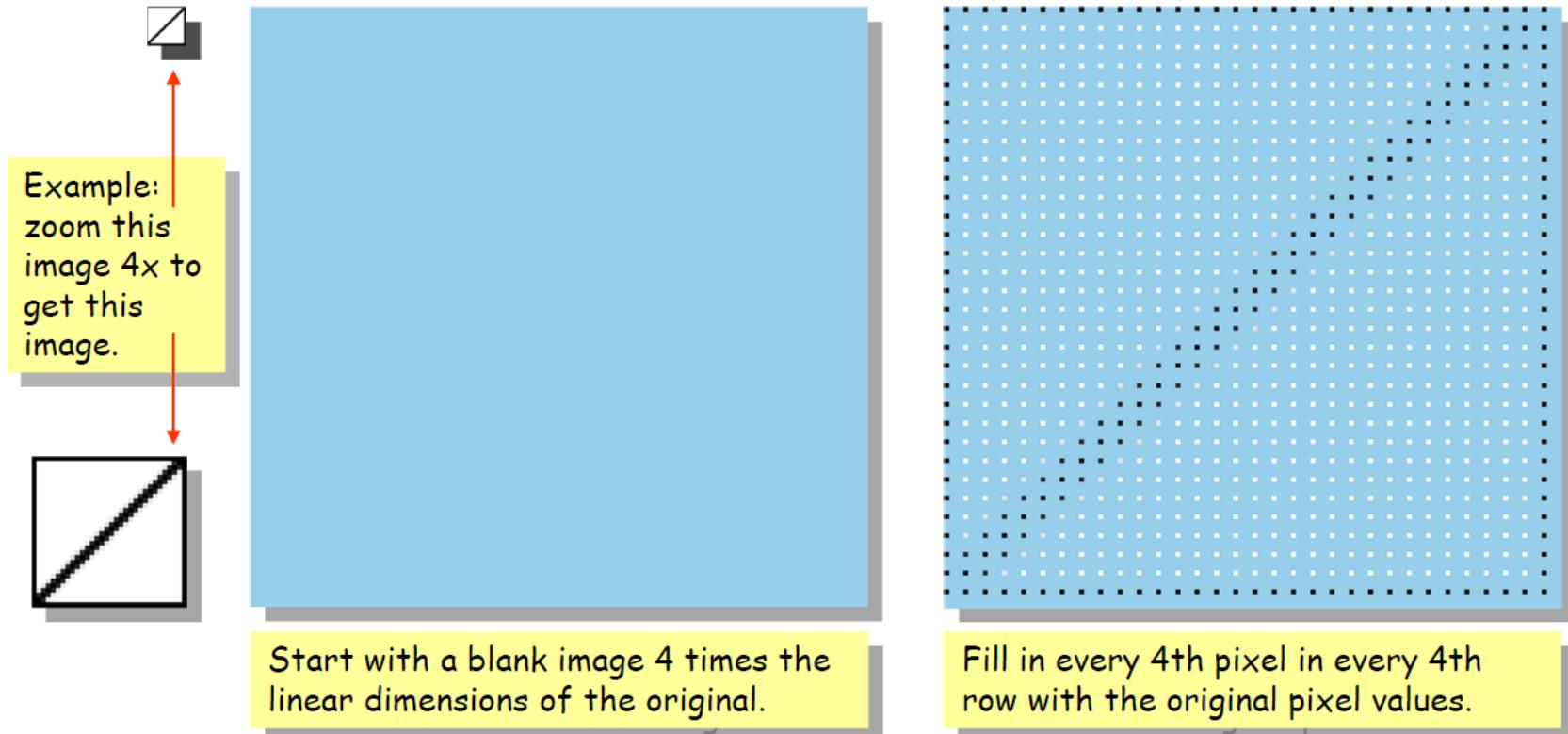


# Resizing image



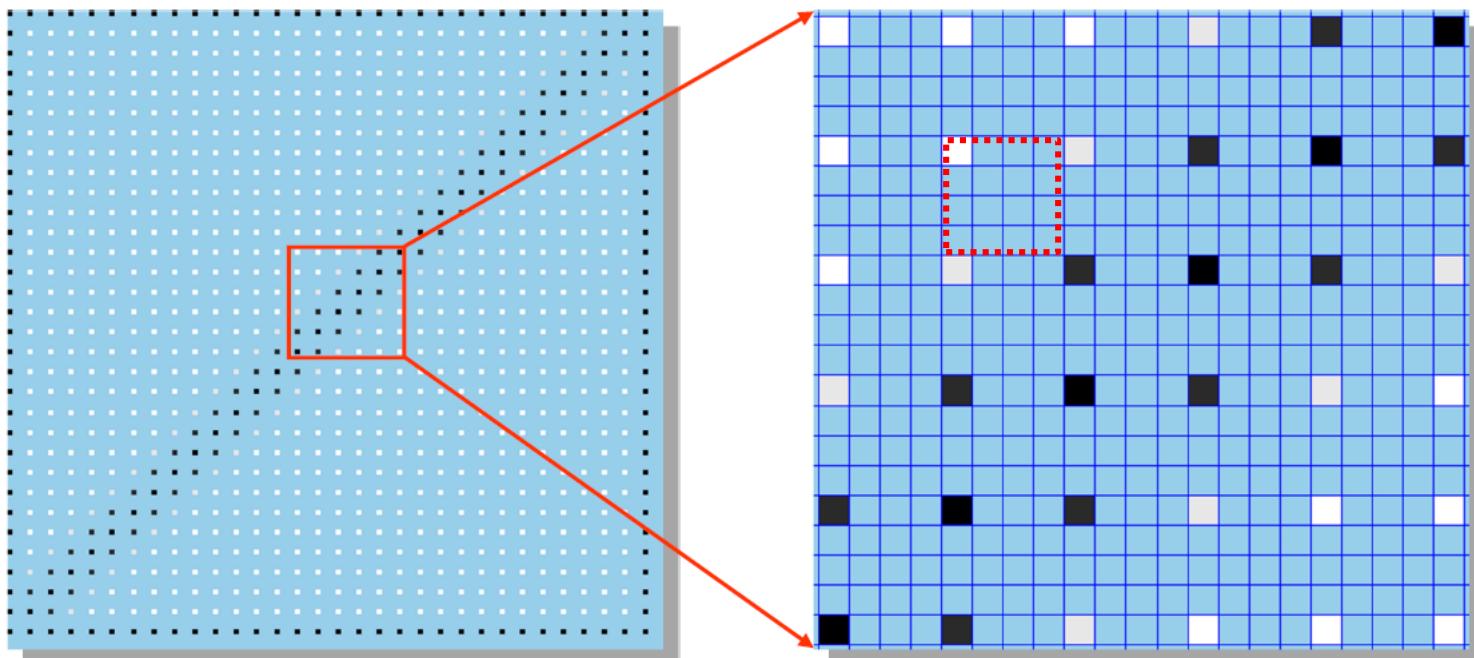
## Enlarging Images Through Pixel Replication



# Resizing image



## Enlarging Images Through Pixel Replication

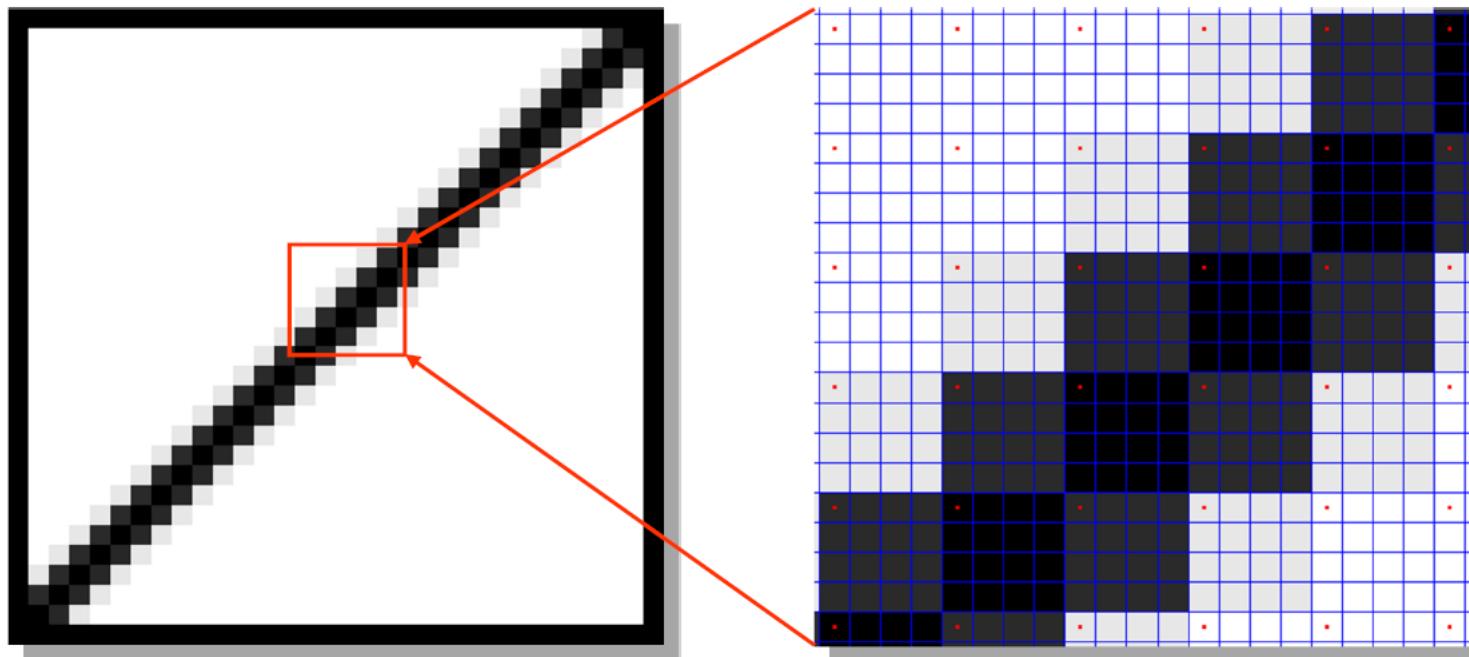


Detail showing every 4th pixel in every 4th row with the original pixel values.

# Resizing image



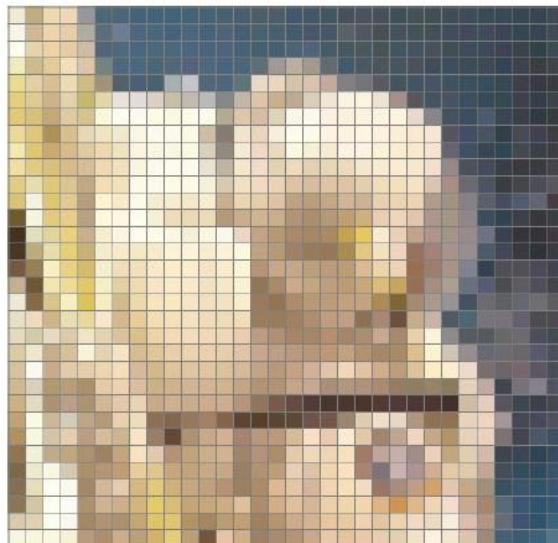
## Enlarging Images Through Pixel Replication



For each original value: replicate it 15 times to create a new, larger "pixel".



# Pixel Indexing in Matlab

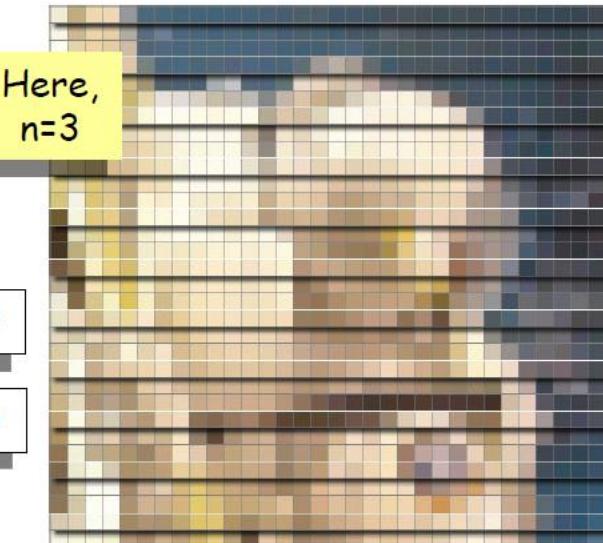


$r = 1:n:R;$

$I(r, :, :, :)$

$c = 1:n:C;$

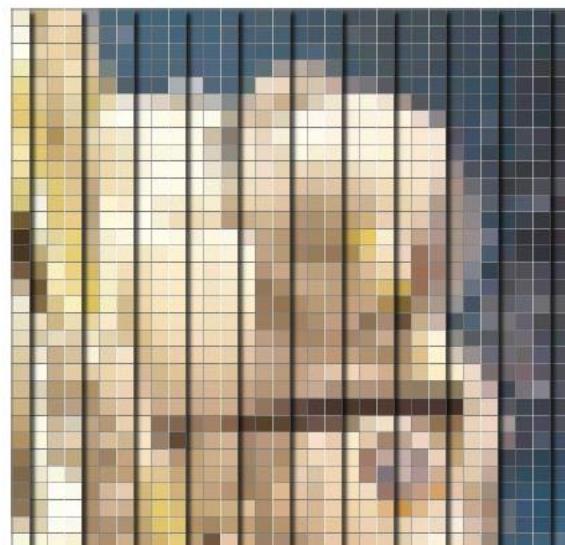
$I(:, c, :, :)$



$r = [1 4 7 10 13 16 19 22 25 28 31]$

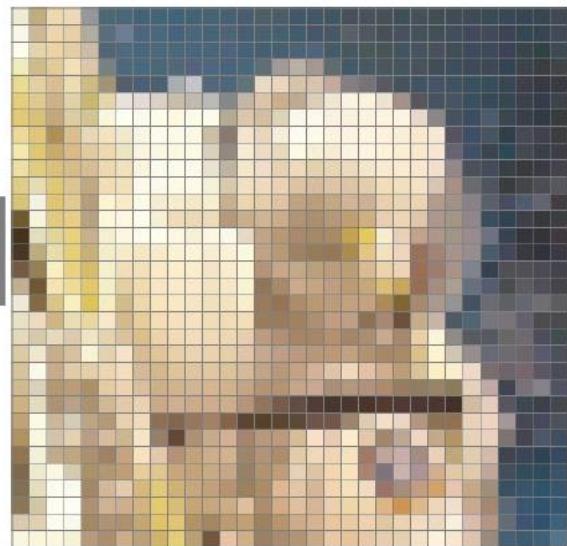
$c = [1 4 7 10 13 16 19 22 25 28 31]$

To decimate the above image by a factor of  $n$ , create a vector,  $r$ , that contains the index of every  $n$ th row, and a similar vector,  $c$ .



# Pixel Indexing in Matlab

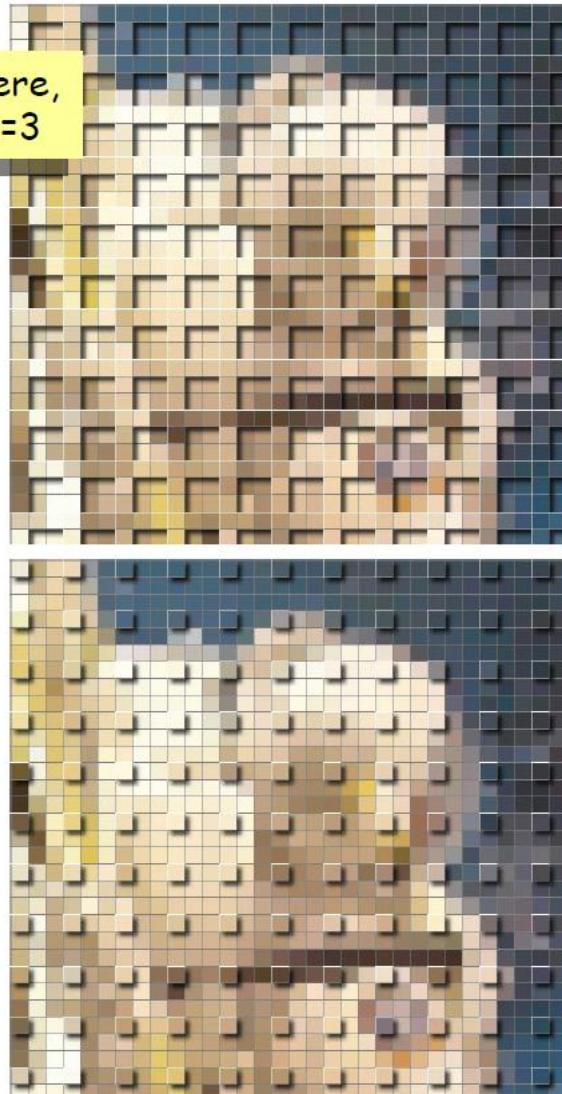
This is called,  
'vectorizing'.



Take the  
pixels  
indexed  
by both  
 $r$  and  $c$ .



$I(r, c)$

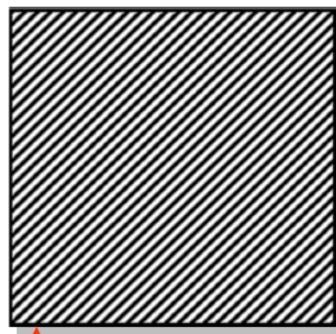


Then, vectors  $\mathbf{r}$  and  $\mathbf{c}$  used as index arguments for image  $I$  select every  $n$ th column in every  $n$ th row.

# Resizing image



## Reducing Images Through Pixel Decimation



Example:  
decimate  
this image  
4x to get  
this image.

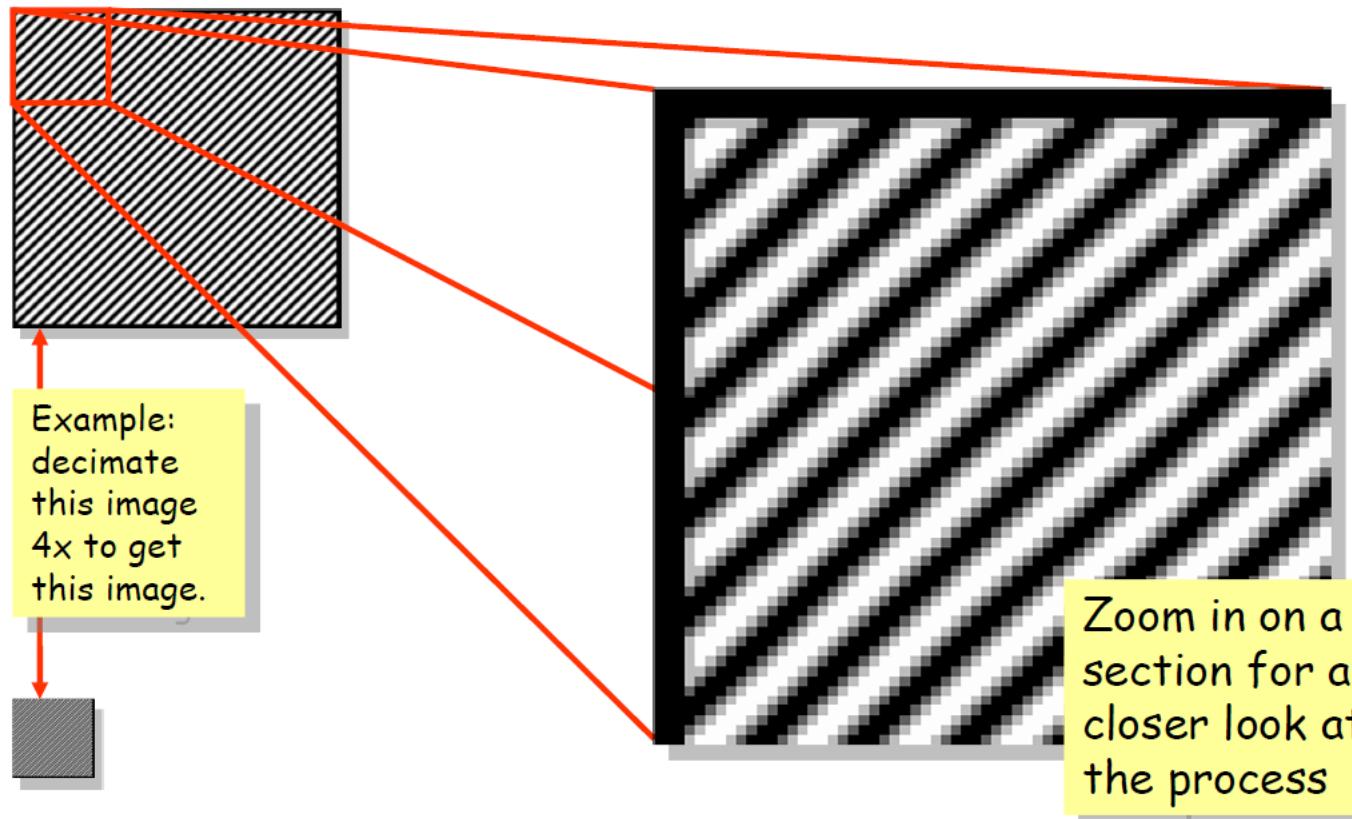


Decimation by  
a factor of  $n$ :  
take every  $n$ th  
pixel in every  
 $n$ th row

# Resizing image



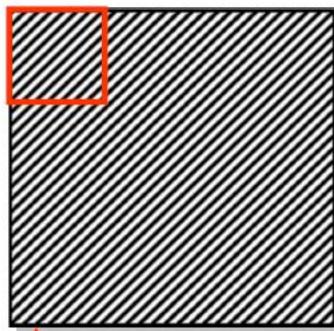
## Reducing Images Through Pixel Decimation



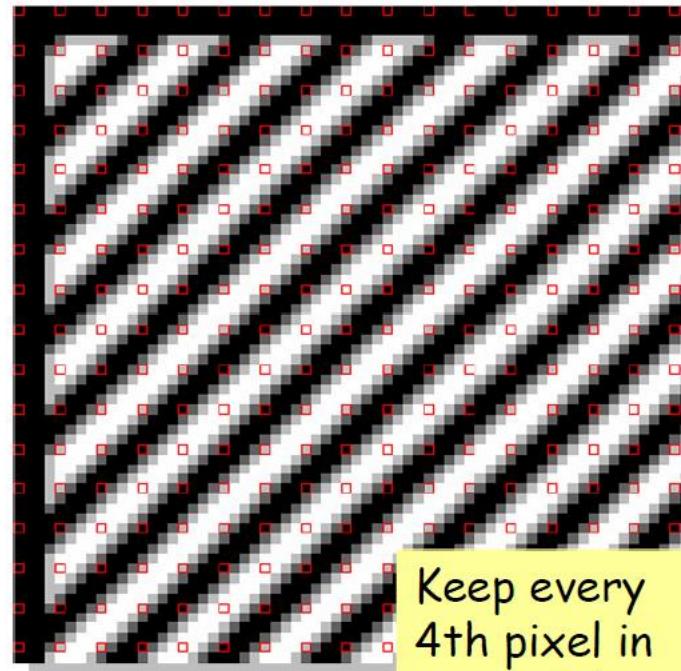
# Resizing image



## Reducing Images Through Pixel Decimation



Example:  
decimate  
this image  
4x to get  
this image.

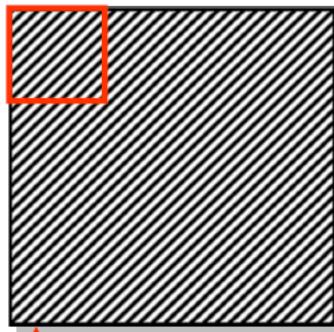


Keep every  
4th pixel in  
every 4th row

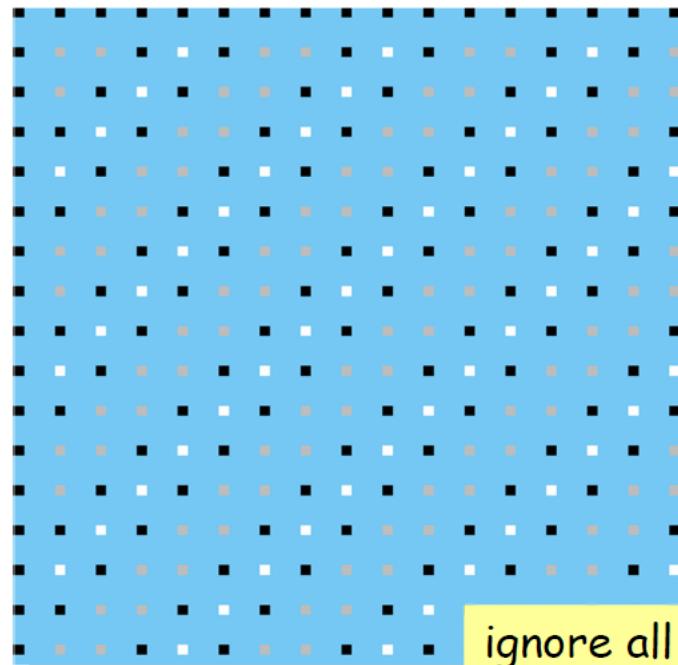
# Resizing image



## Reducing Images Through Pixel Decimation



Example:  
decimate  
this image  
4x to get  
this image.

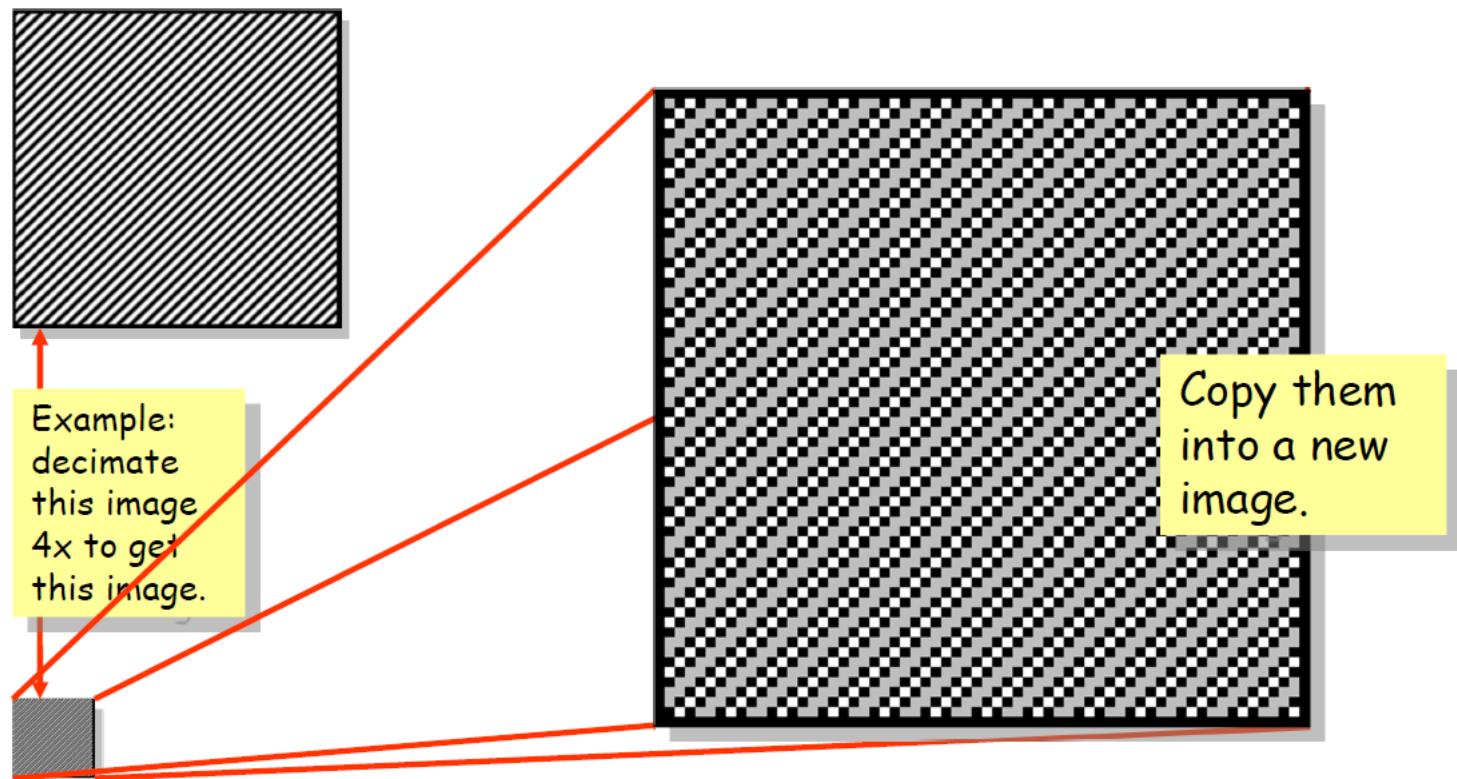


ignore all  
the others

# Resizing image



## Reducing Images Through Pixel Decimation



# Resizing image



## Nearest Neighbor Resampling

The “Nearest Neighbor” algorithm is a generalization of pixel replication and decimation.

It also includes fractional resizing, *i.e.* resizing an image so that it has  $p/q$  of the pixels per row and  $p/q$  of the rows in the original. ( $p$  and  $q$  are both integers.)



# Resizing image

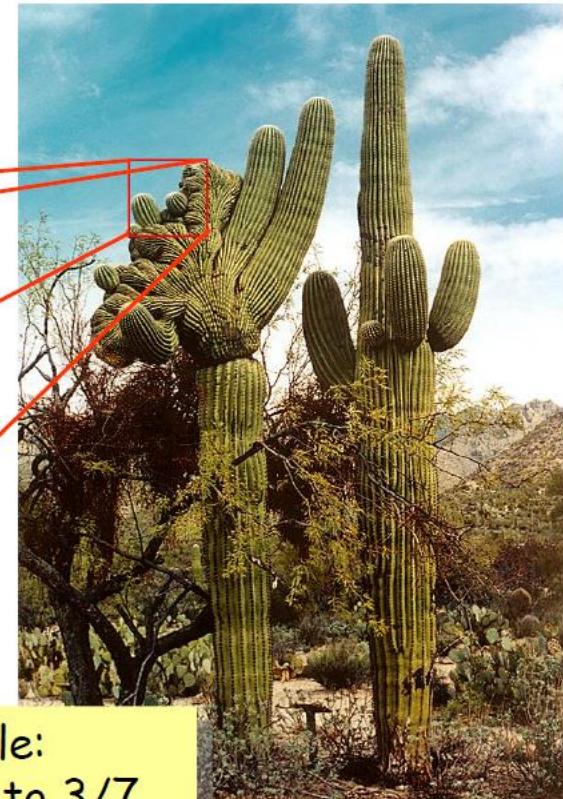


Nearest  
Neighbor  
Resampling

Zoom in on a  
section for a  
closer look at  
the process



Example:  
resize to 3/7  
of the original



# Resizing image



Nearest  
Neighbor  
Resampling

3/7 resize



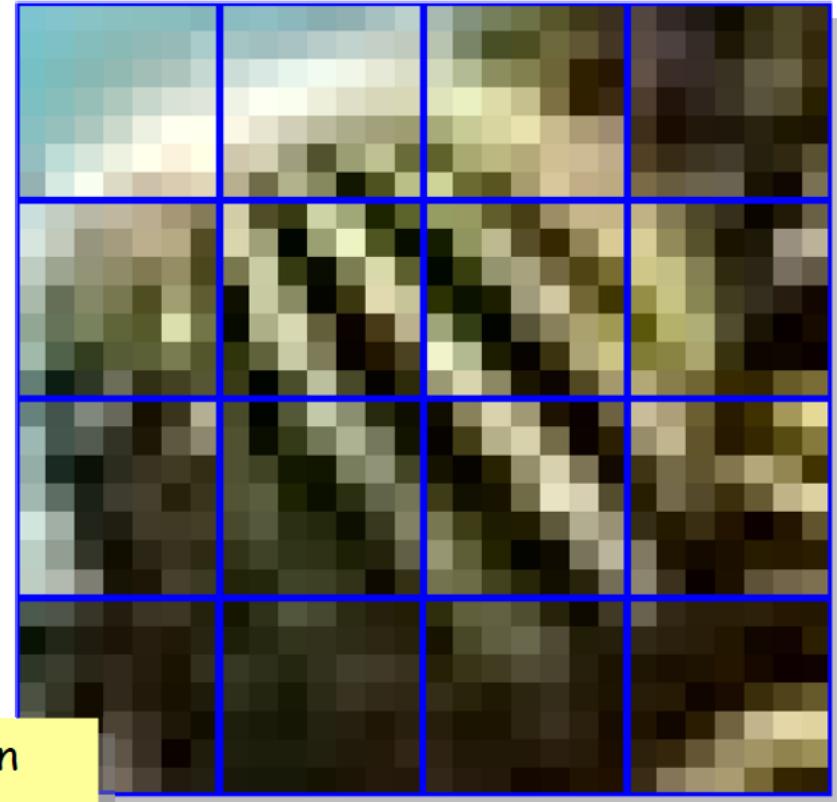
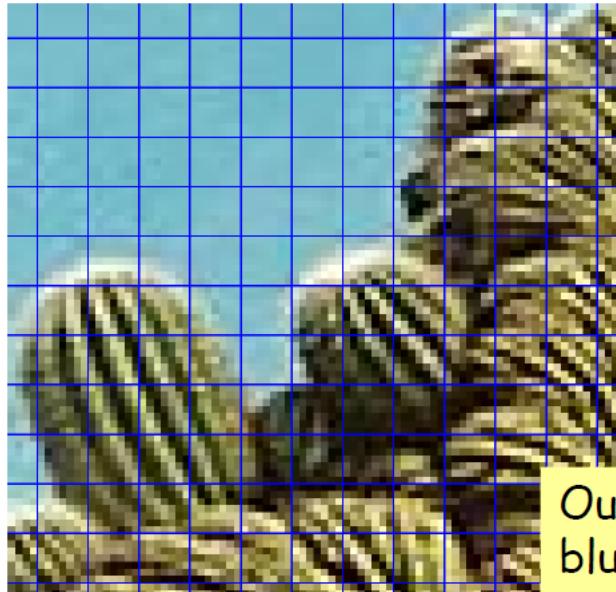
Zoom in for a  
better look

# Resizing image



Nearest  
Neighbor  
Resampling

3/7 resize



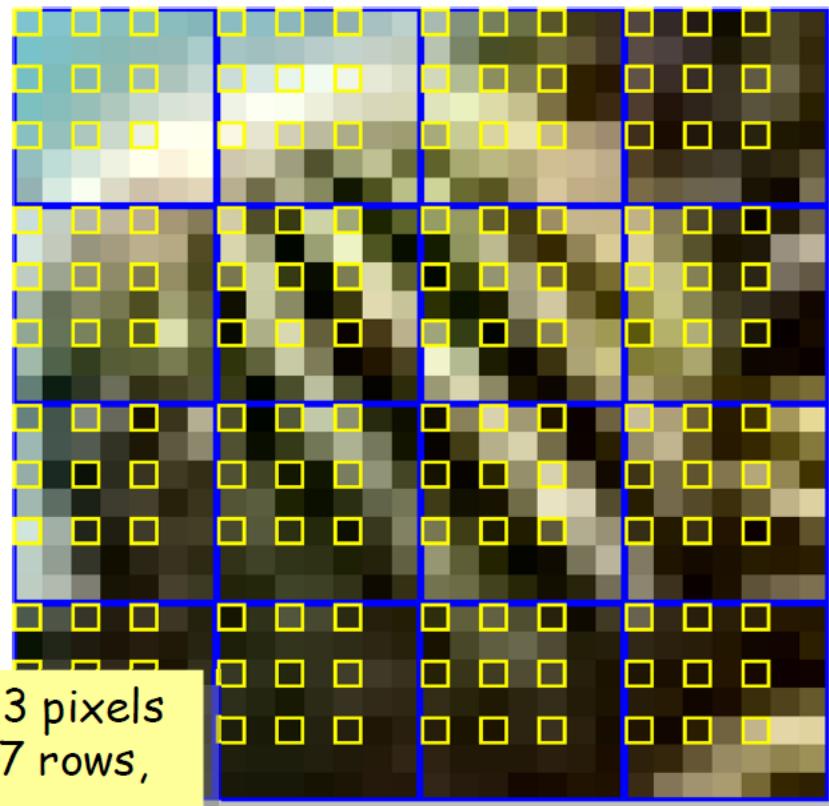
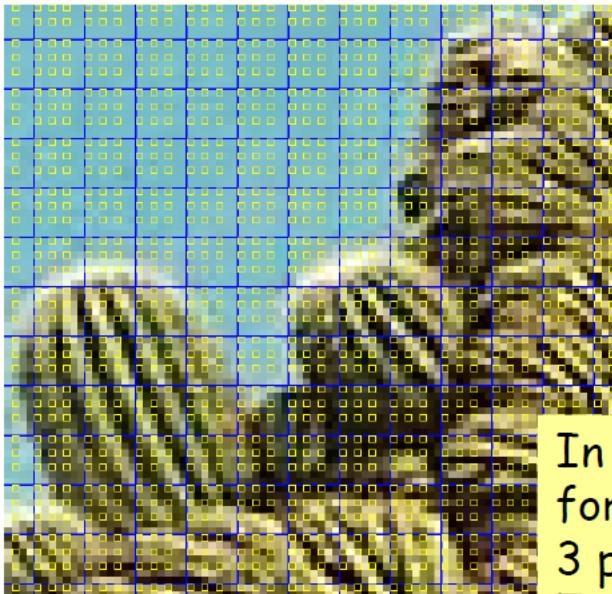
Outlined in  
blue: 7x7  
pixel squares

# Resizing image



Nearest  
Neighbor  
Resampling

3/7 resize



In yellow: 3 pixels  
for every 7 rows,  
3 pixels for every  
7 cols.

# Resizing image



Nearest  
Neighbor  
Resampling

3/7 resize



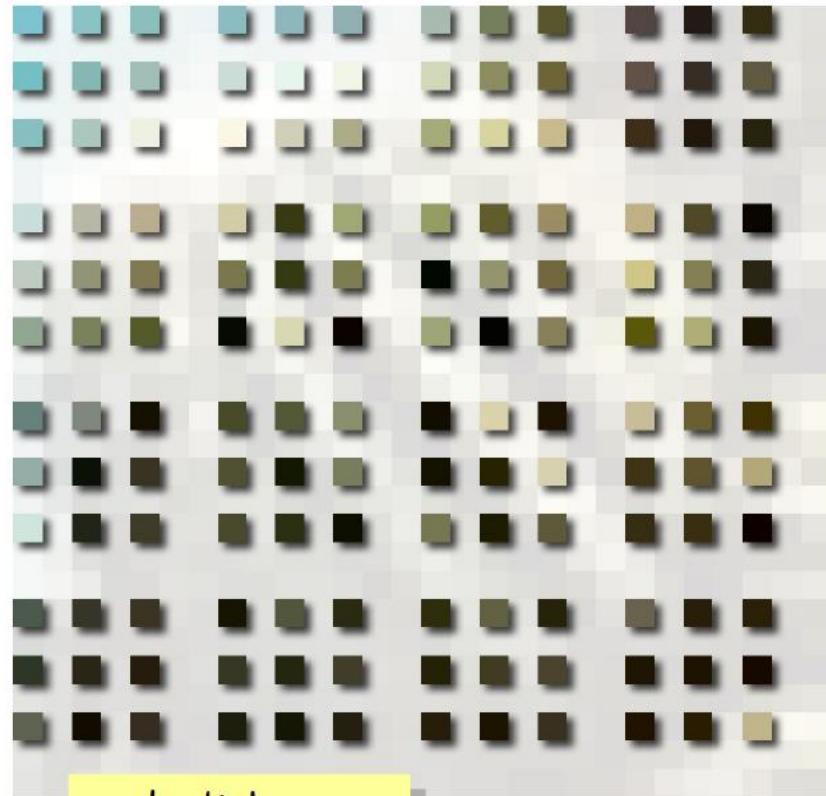
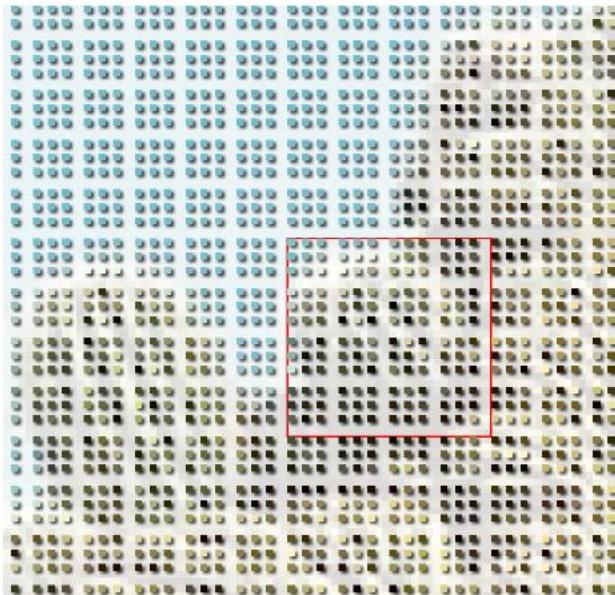
Keep the  
highlighted  
pixels...

# Resizing image



Nearest  
Neighbor  
Resampling

3/7 resize



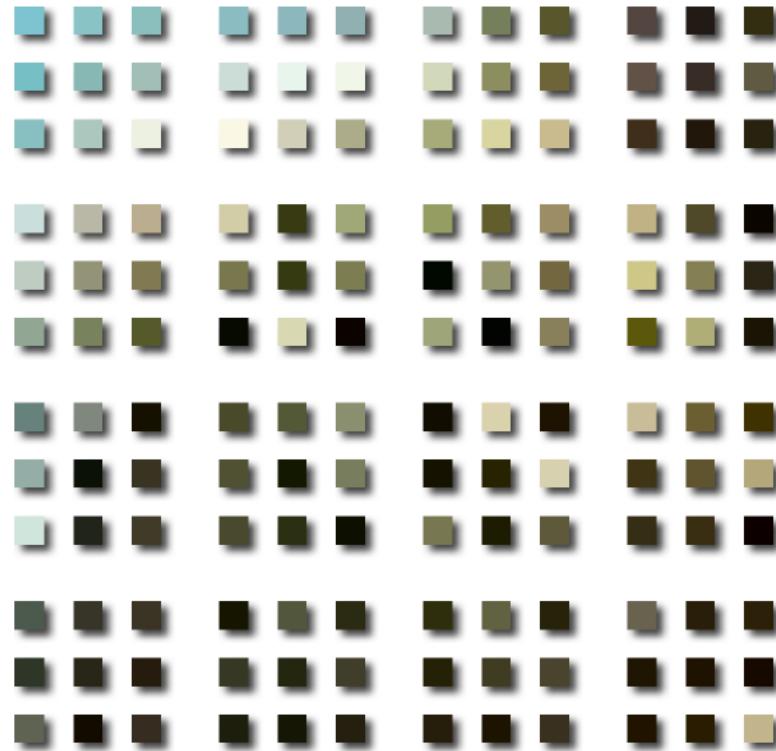
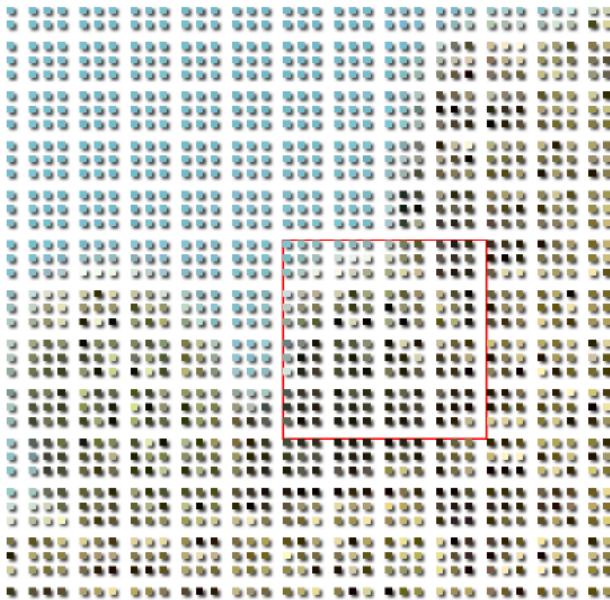
... don't keep  
the others.

# Resizing image



Nearest  
Neighbor  
Resampling

3/7 resize



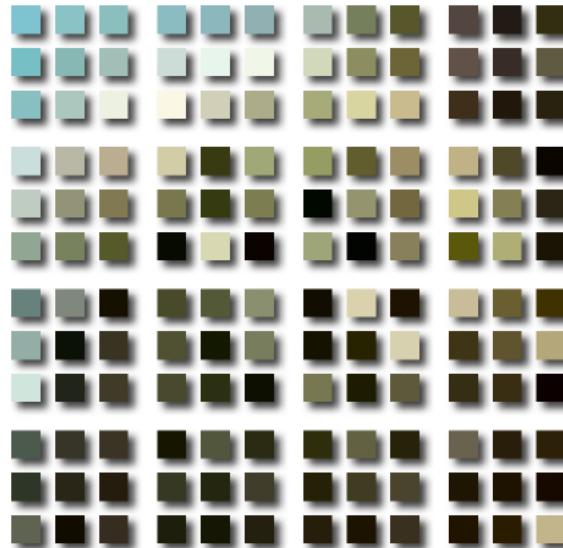
Copy them into  
a new image.

# Resizing image



Nearest  
Neighbor  
Resampling

3/7 resize



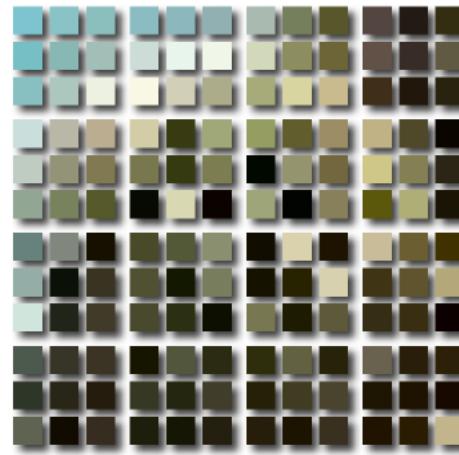
Copy them into  
a new image.

# Resizing image



Nearest  
Neighbor  
Resampling

3/7 resize



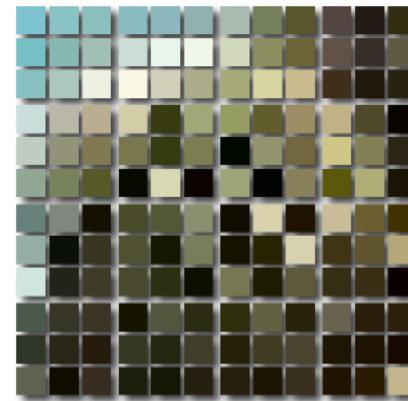
Copy them into  
a new image.

# Resizing image



Nearest  
Neighbor  
Resampling

3/7 resize



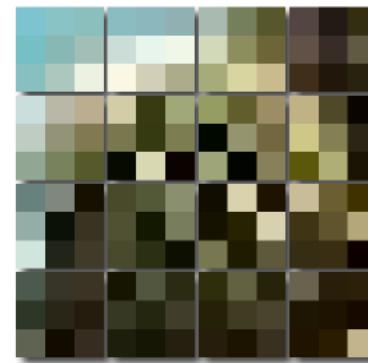
Copy them into  
a new image.

# Resizing image



Nearest  
Neighbor  
Resampling

3/7 resize



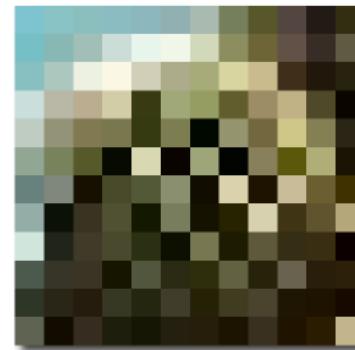
Copy them into  
a new image.

# Resizing image



Nearest  
Neighbor  
Resampling

3/7 resize

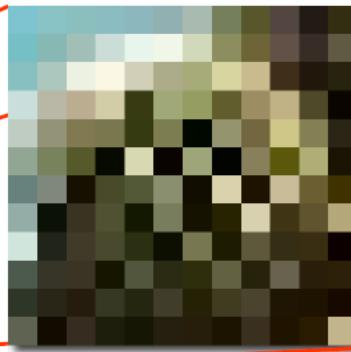
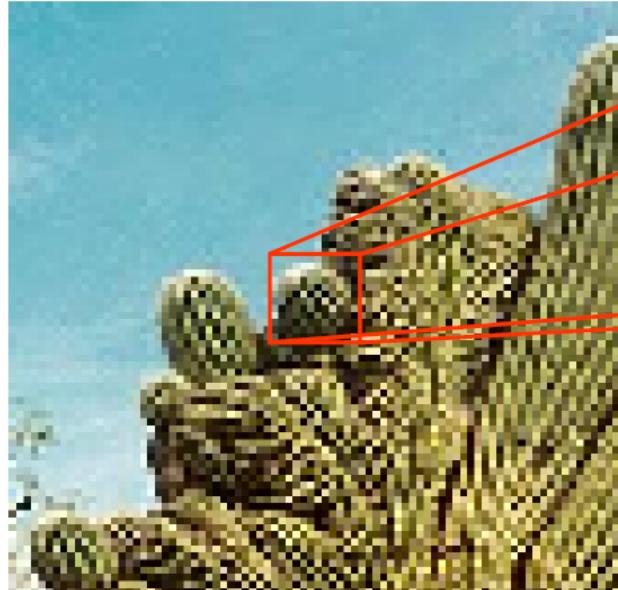


3/7 times the  
linear dimensions  
of the original

# Resizing image



Nearest  
Neighbor  
Resampling

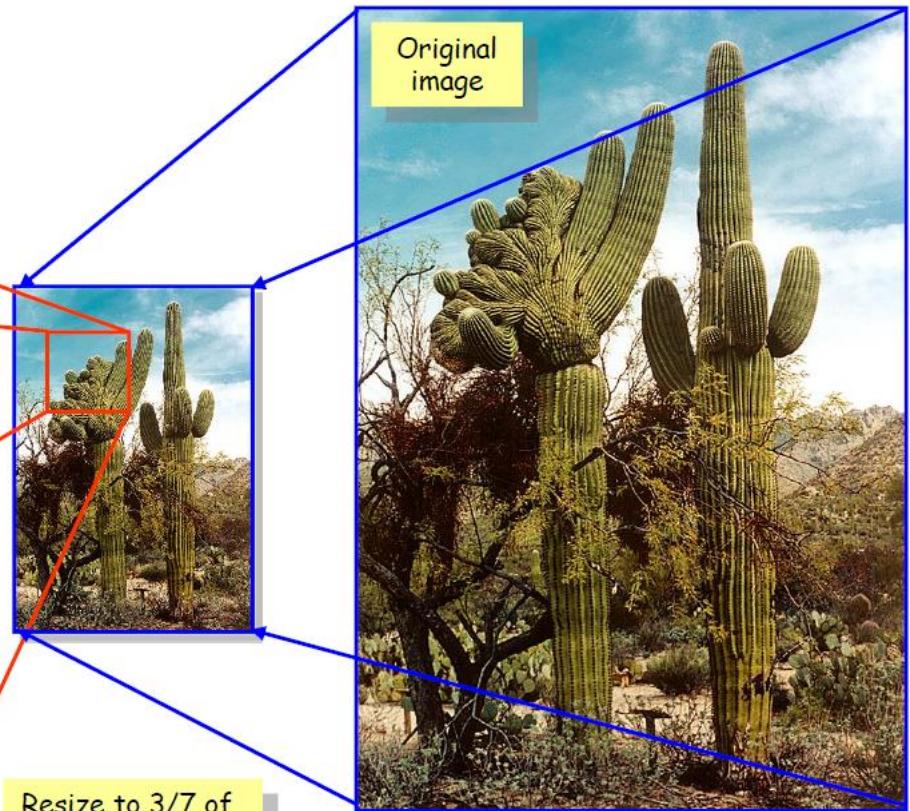
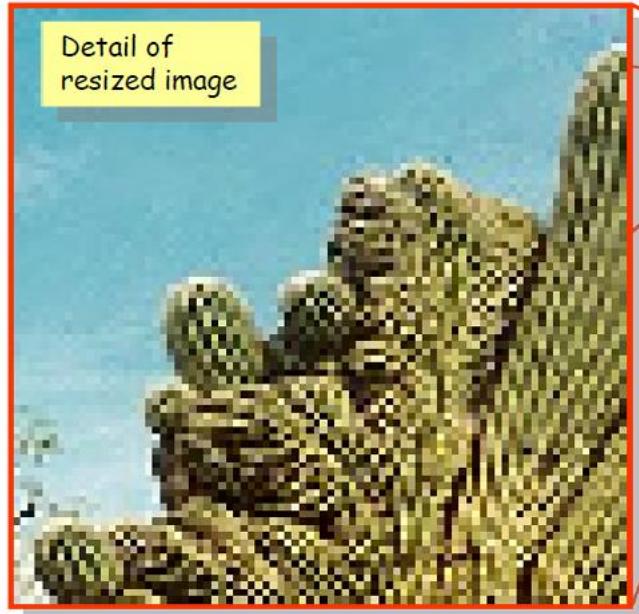


3/7 times the  
linear dimensions  
of the original

# Resizing image



## Nearest Neighbor Resampling



Detail of  
resized image

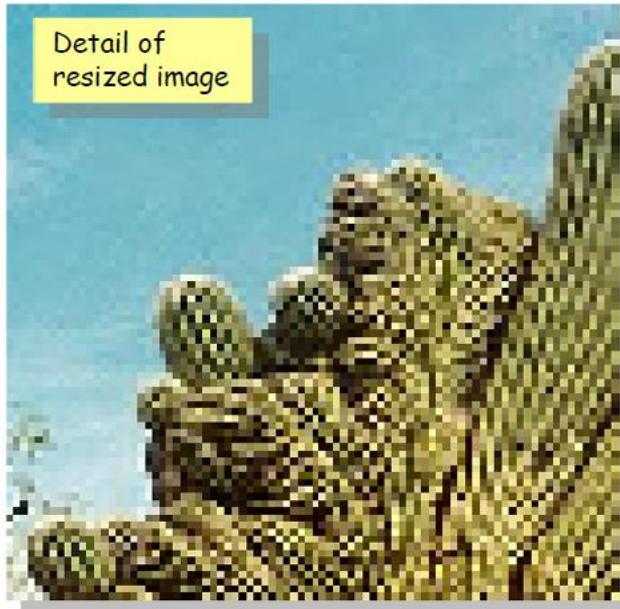
Original  
image

Resize to 3/7 of  
the original dims.

# Resizing image



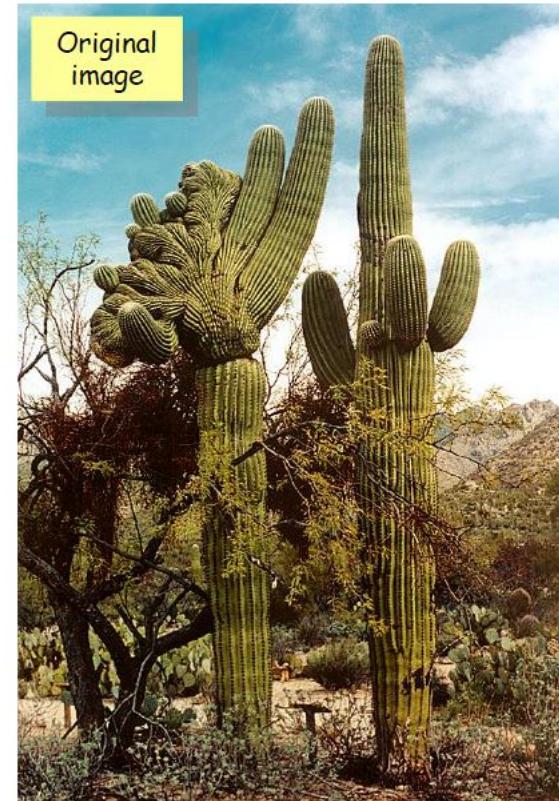
## Nearest Neighbor Resampling



Detail of  
resized image



Resize to 3/7 of  
the original dims.

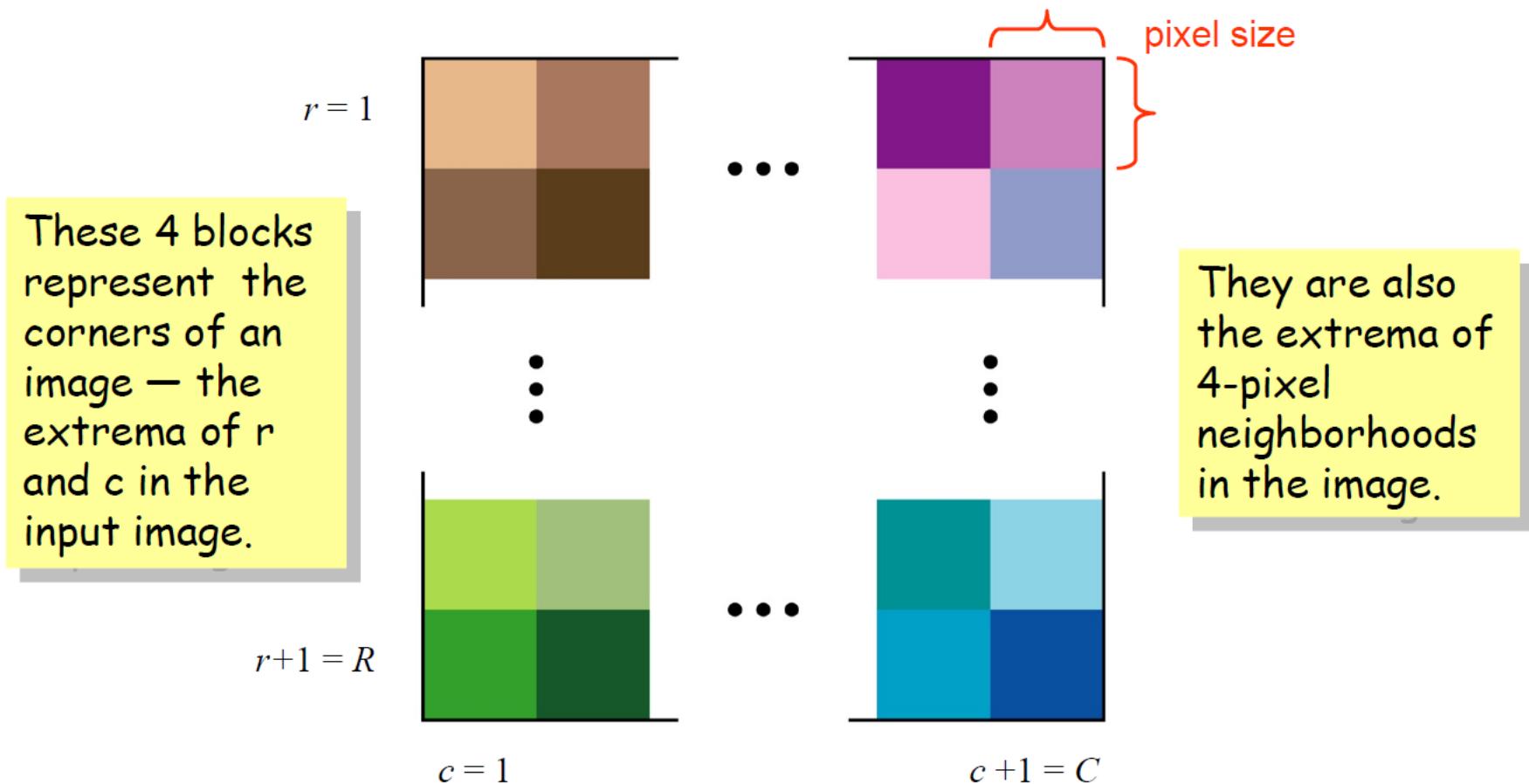


Original  
image

# Resizing image



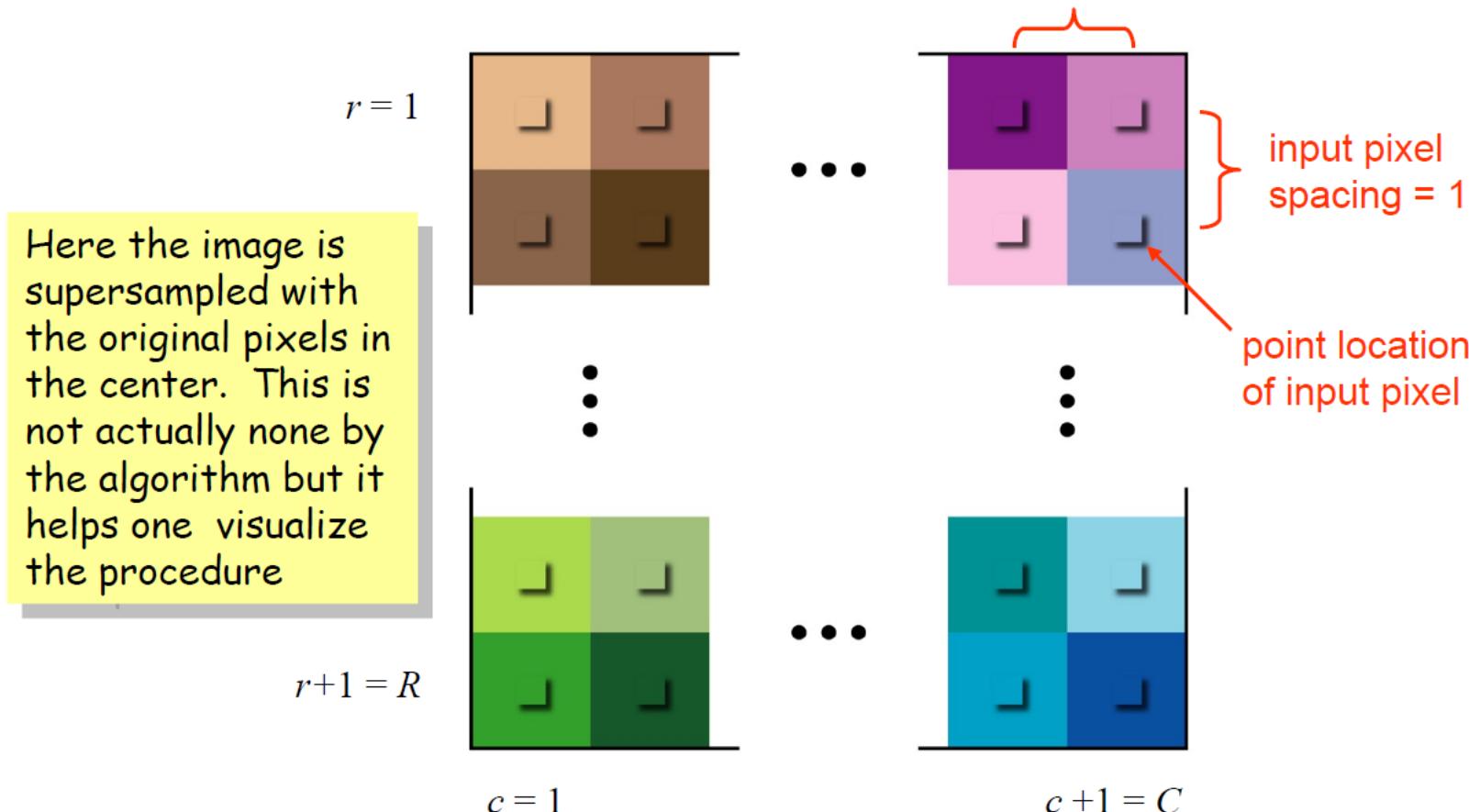
## Nearest Neighbor Resampling



# Resizing image



## Nearest Neighbor Resampling



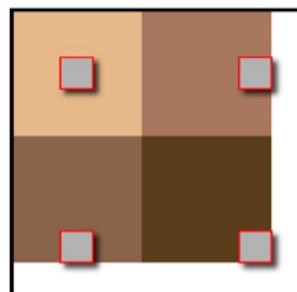
# Resizing image



## Nearest Neighbor Resampling

If the output image is smaller than the input image, then  $R' < R, C' < C$ .

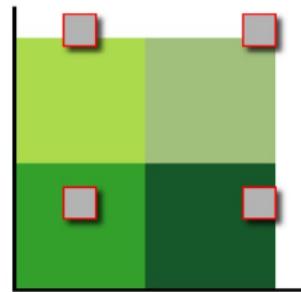
$r = 1$



...

⋮  
⋮

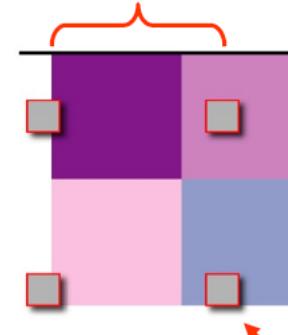
$r+1 = R$



$c = 1$

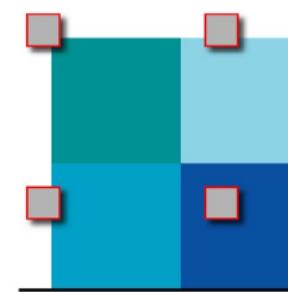
...

$c + 1 = C$



output pixel  
spacing  $> 1$

⋮  
⋮



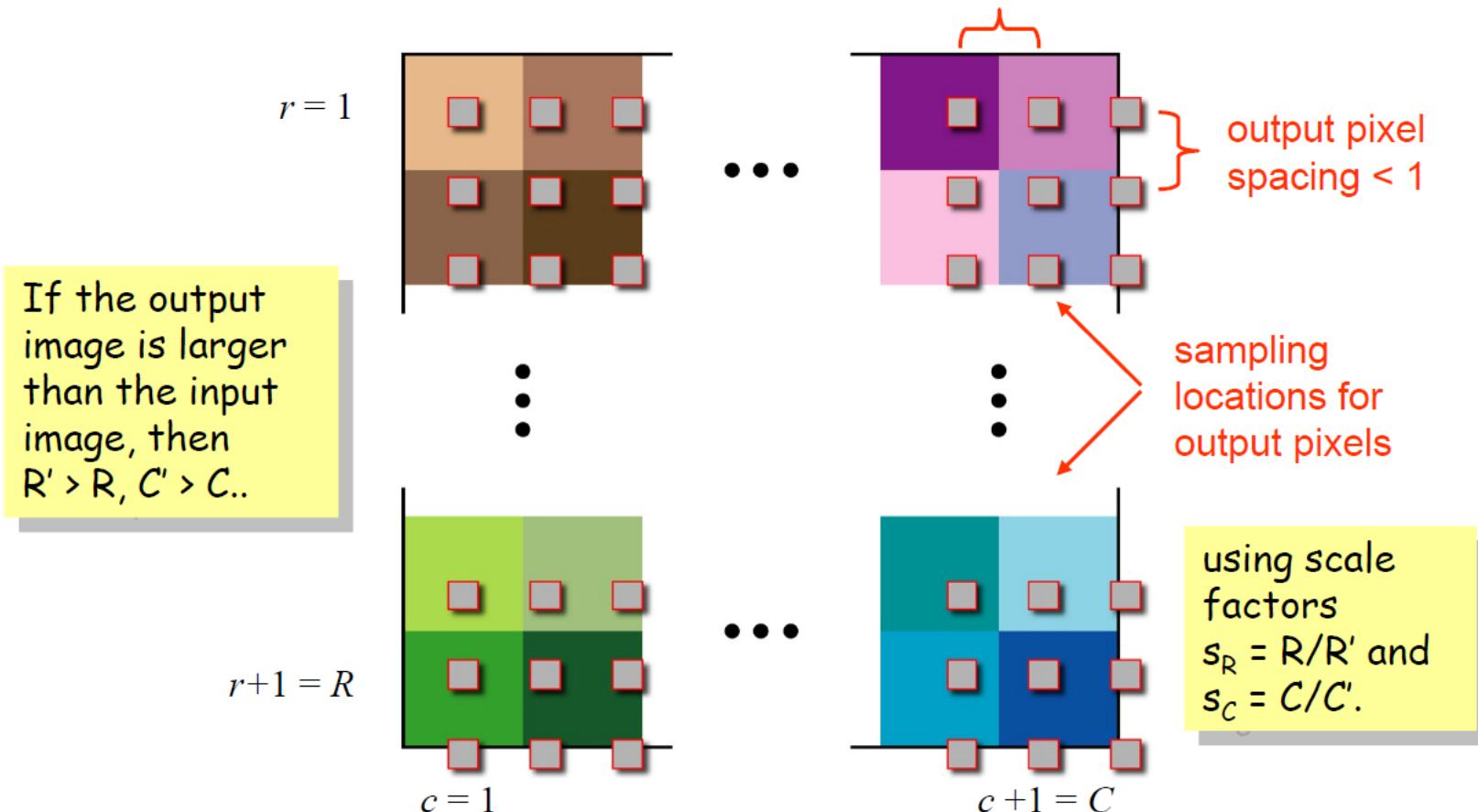
sampling  
locations for  
output pixels

using scale  
factors  
 $s_R = R/R'$  and  
 $s_C = C/C'$ .

# Resizing image



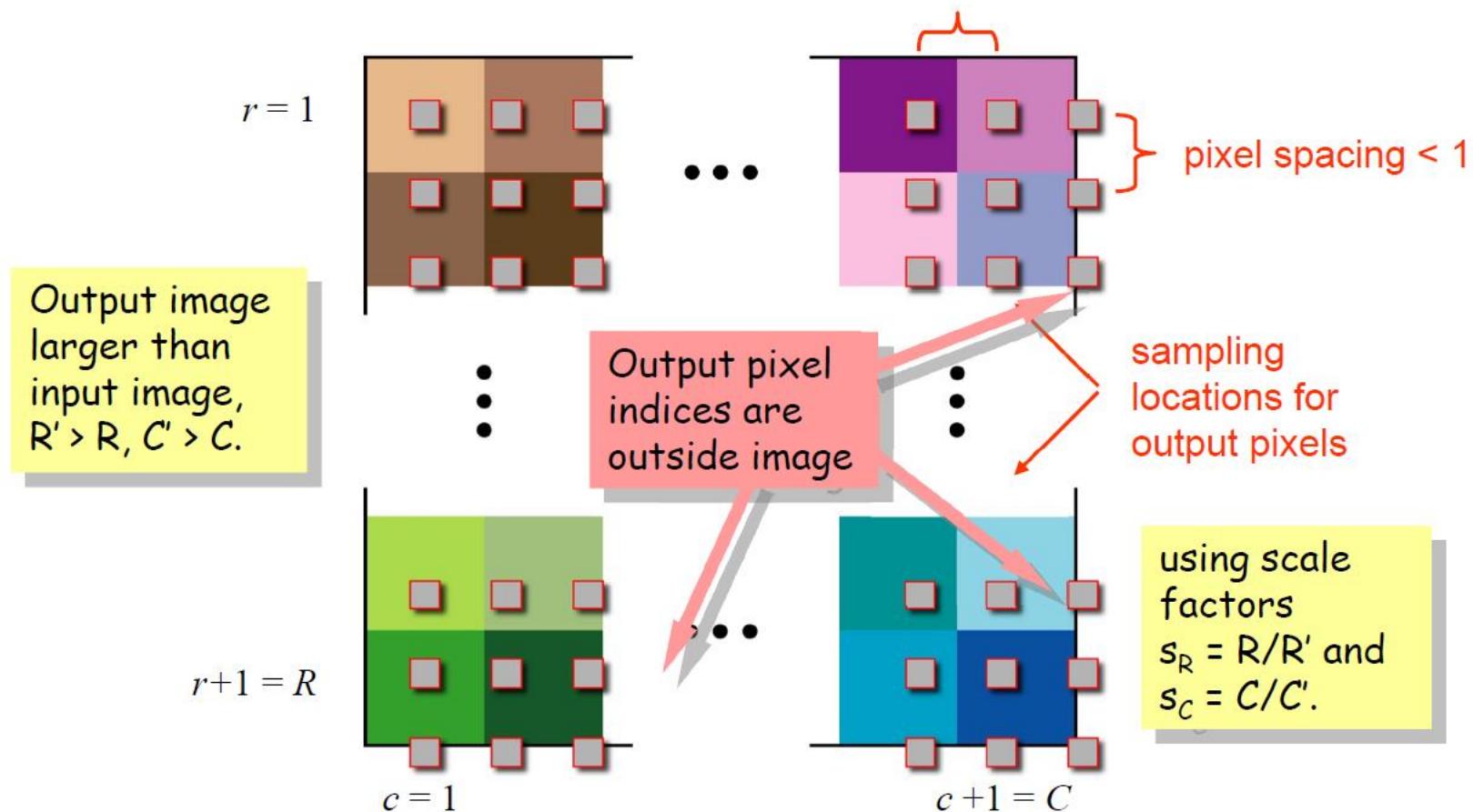
## Nearest Neighbor Resampling



# Resizing image



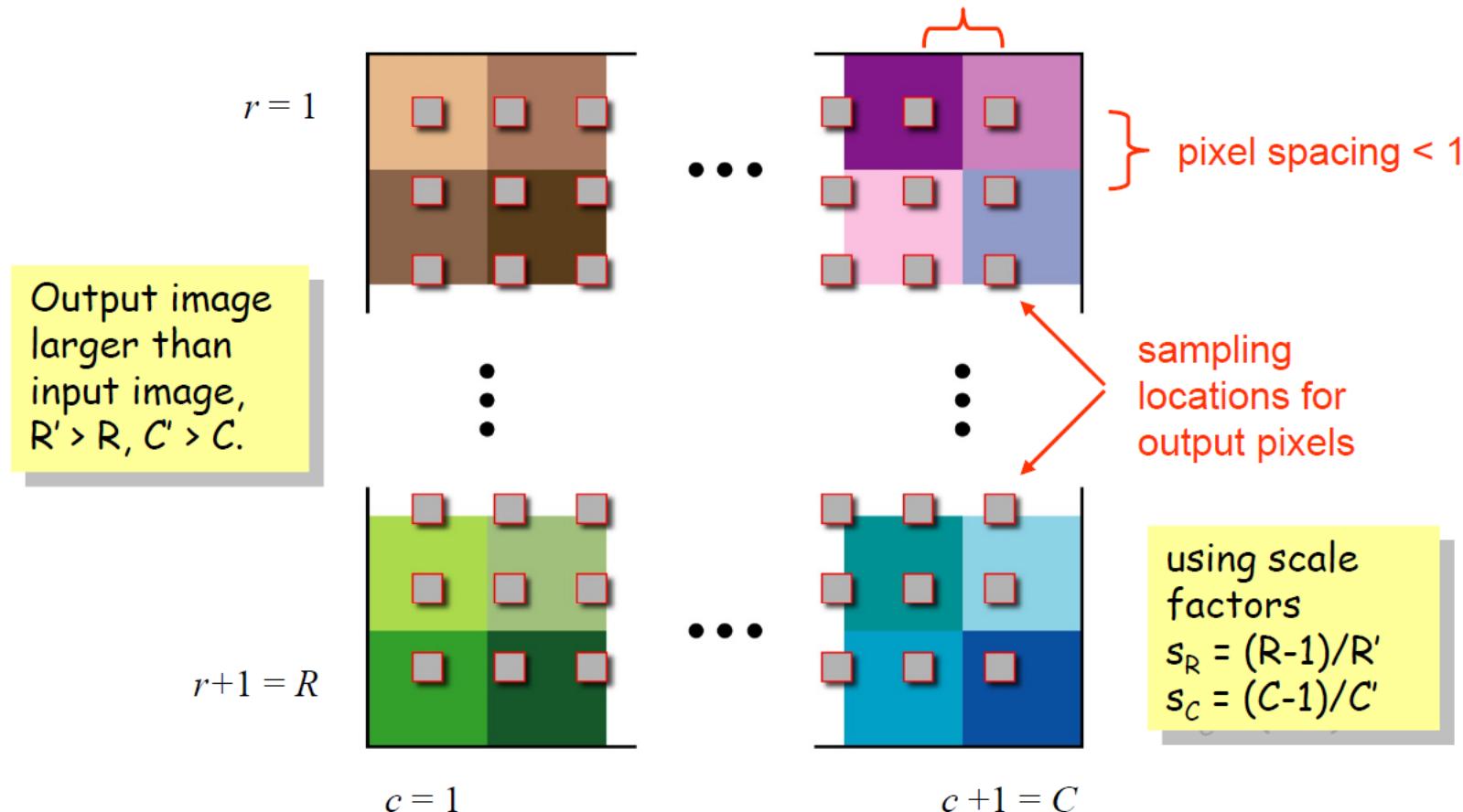
## Nearest Neighbor Resampling



# Resizing image



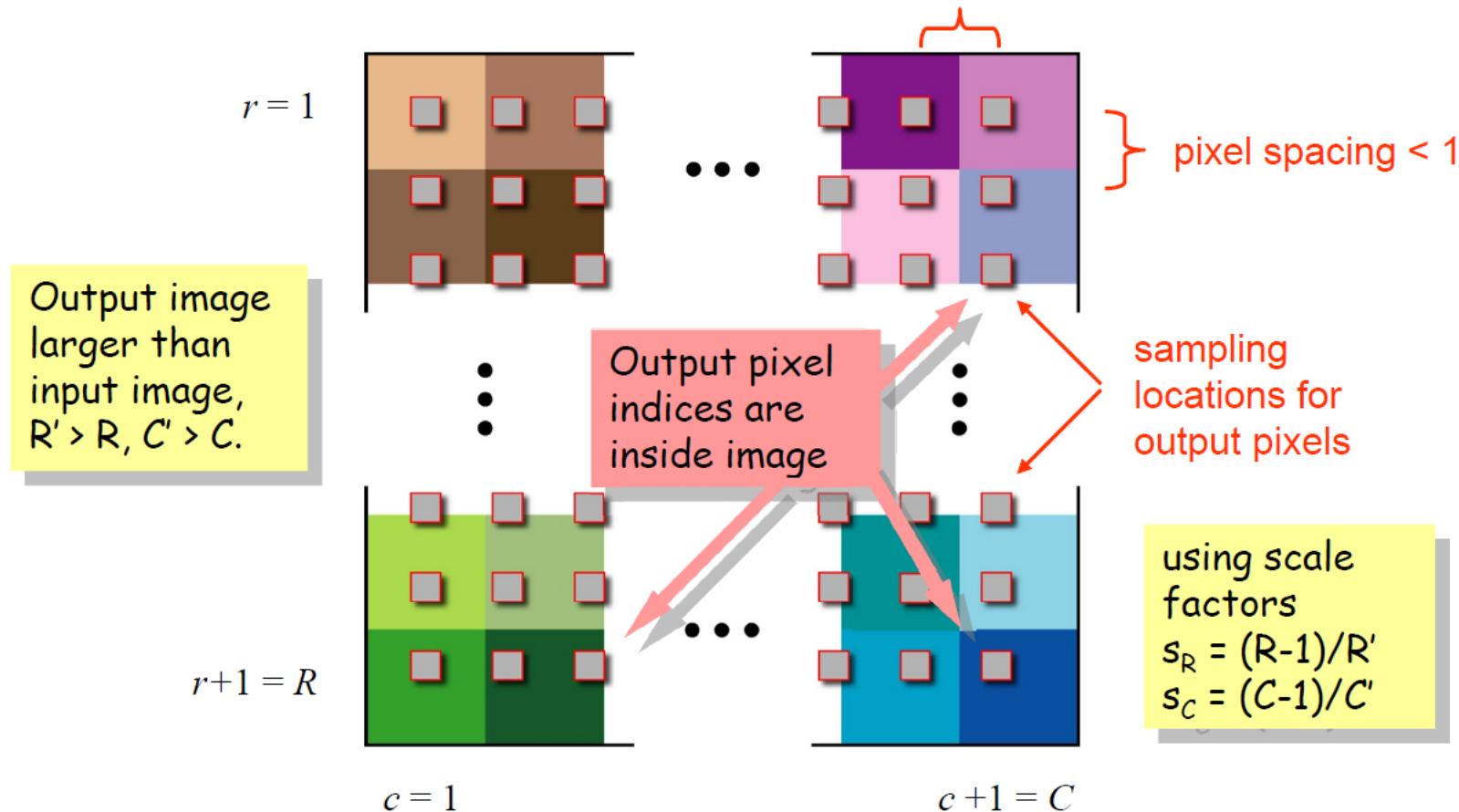
## Nearest Neighbor Resampling



# Resizing image



## Nearest Neighbor Resampling



# Resizing image



Resize this image to 3/5 of its original size

# Resizing image



**clear all**

**close all**

p=3;

q=5;

I=imread('Exp\_9\_1.jpg');

**ii=1;**

I\_new=zeros(size(I,1)\*p/q,size(I,2)\*p/q,3);

for i=1:q:size(I,1)-1

**jj=1;**

for j=1:q:size(I,2)-1

I\_new(ii:ii+p-1,jj:jj+p-1,:)=**double**(I(i:2:i+q-1,j:2:j+q-1,:));

jj=jj+p;

end

ii=ii+p;

end

figure

image(I)

truesize

figure

image(uint8(I\_new))

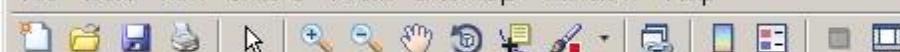
truesize

**Function imresize**

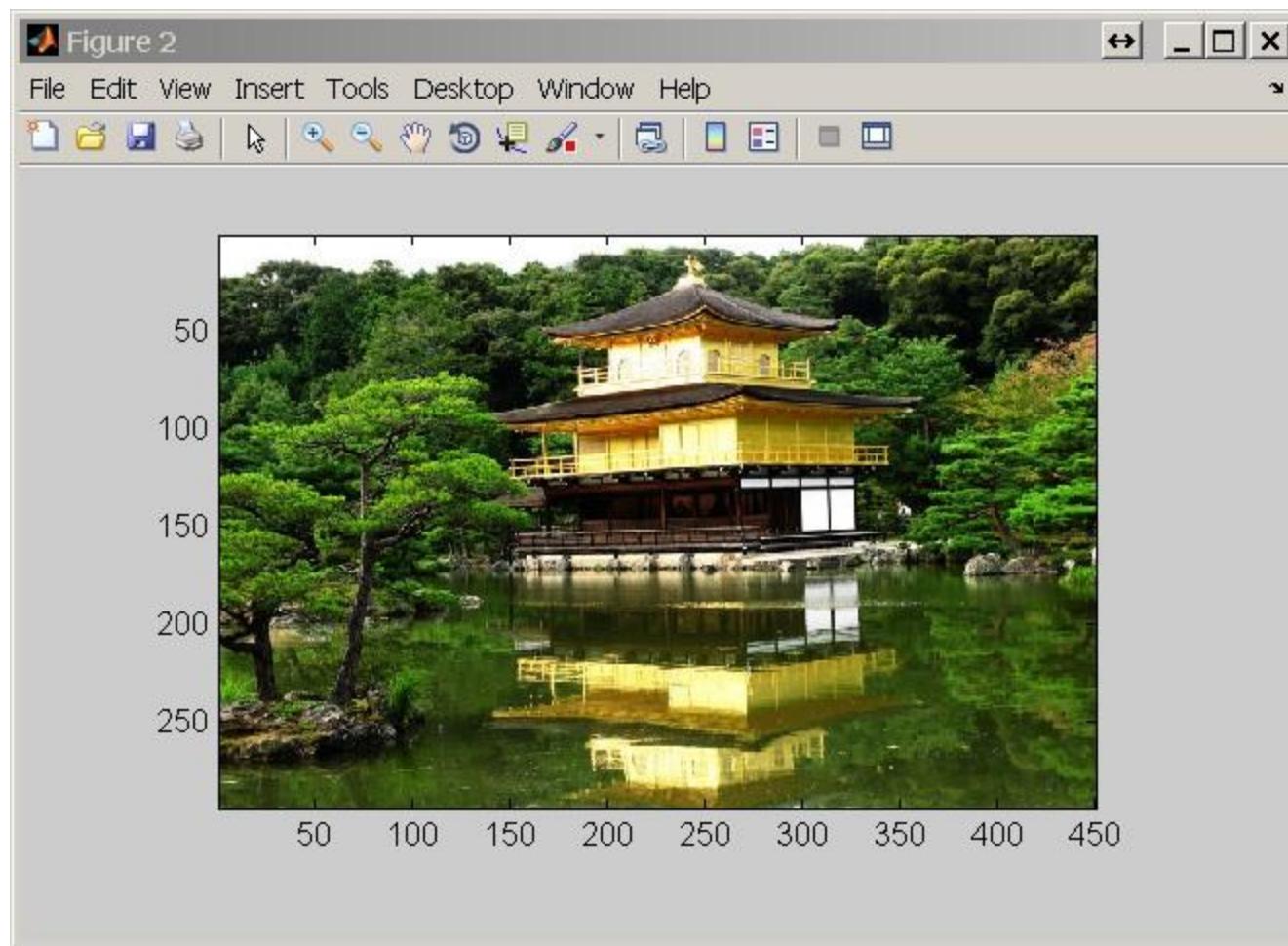
Figure 1



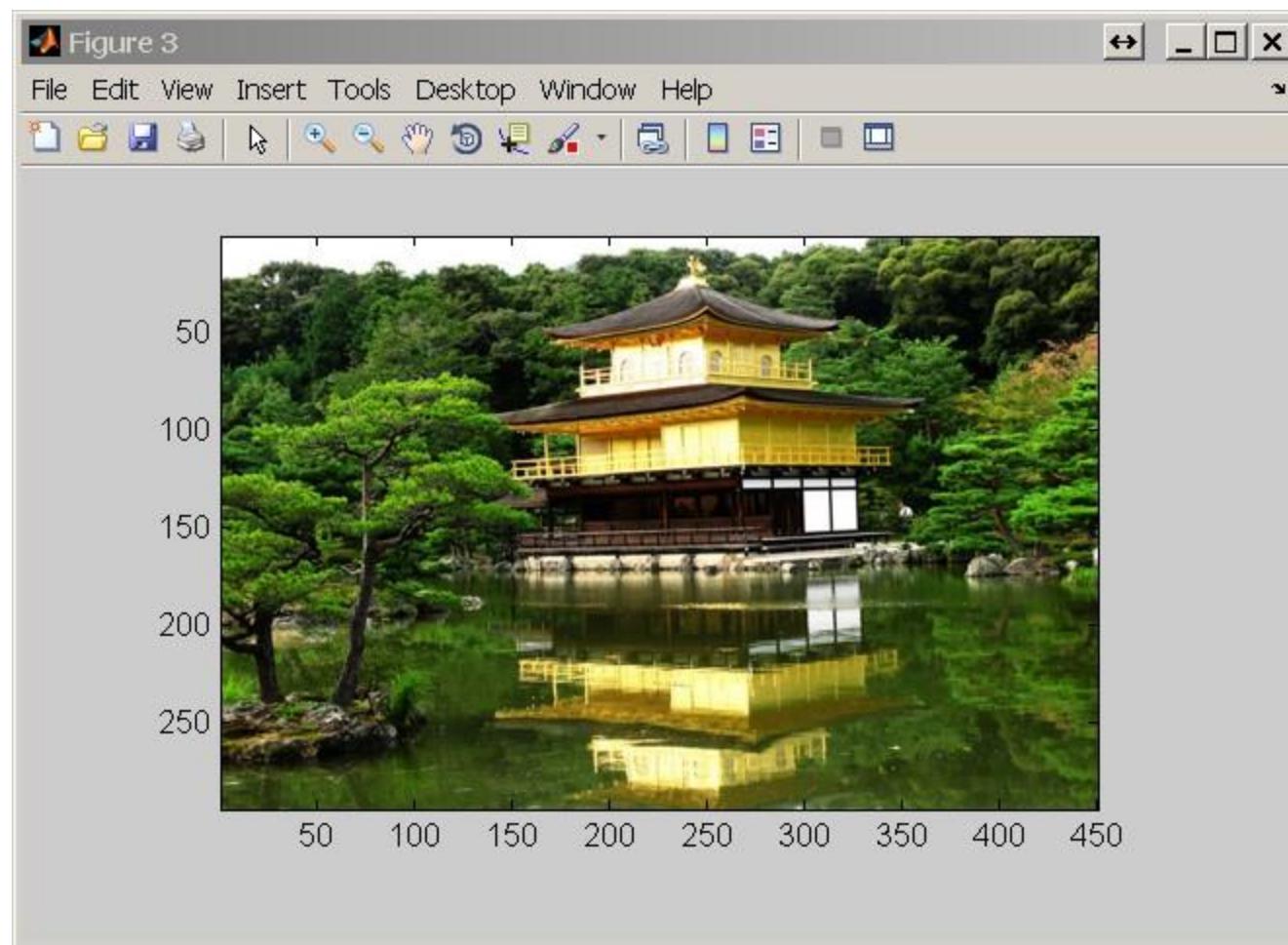
File Edit View Insert Tools Desktop Window Help



# Resizing image



# Resizing image

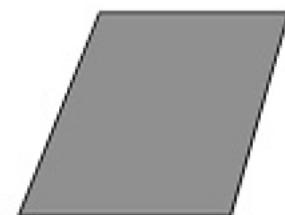


# Resizing image



## Resampling Through Bilinear Interpolation

want to  
upsample this  
image by a  
factor of  $3/2$



# Resizing image



## Resampling Through Bilinear Interpolation

new samples  
to be added  
at light gray  
locations.

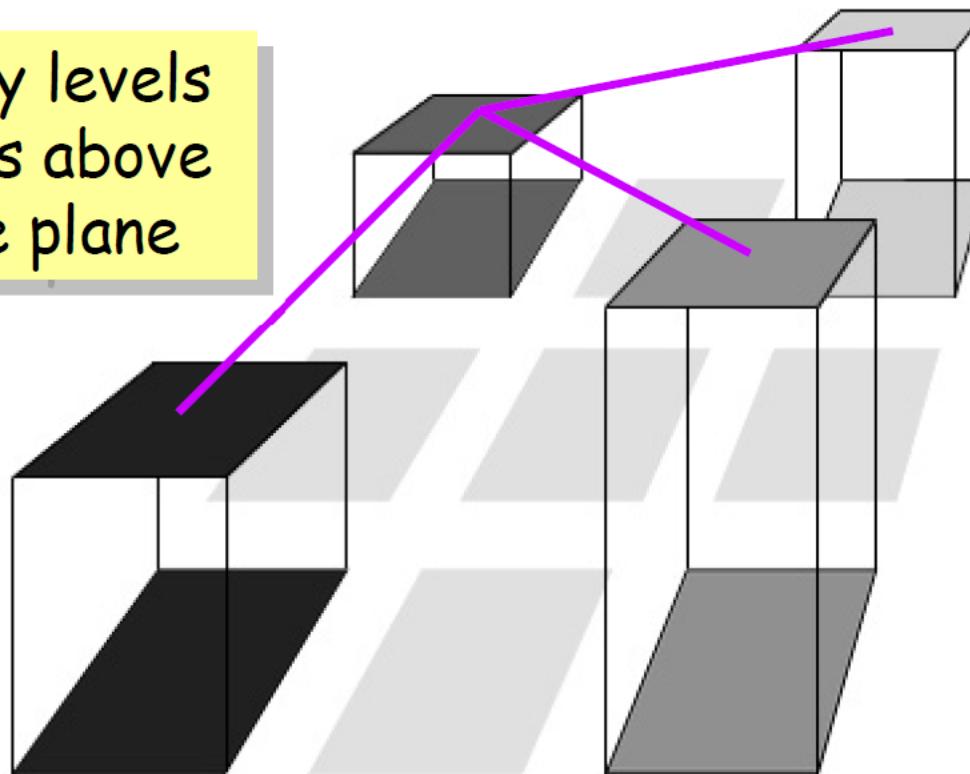


# Resizing image



## Resampling Through Bilinear Interpolation

treat gray levels  
as heights above  
the image plane



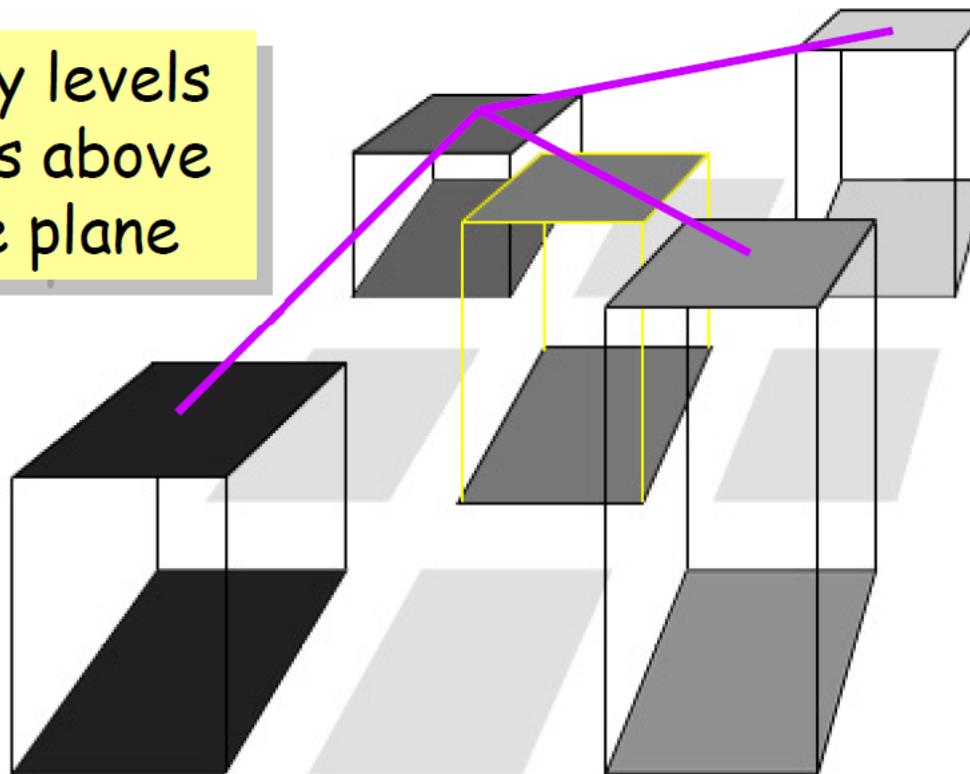
center =  
weighted  
average of  
four  
corners

# Resizing image



## Resampling Through Bilinear Interpolation

treat gray levels  
as heights above  
the image plane



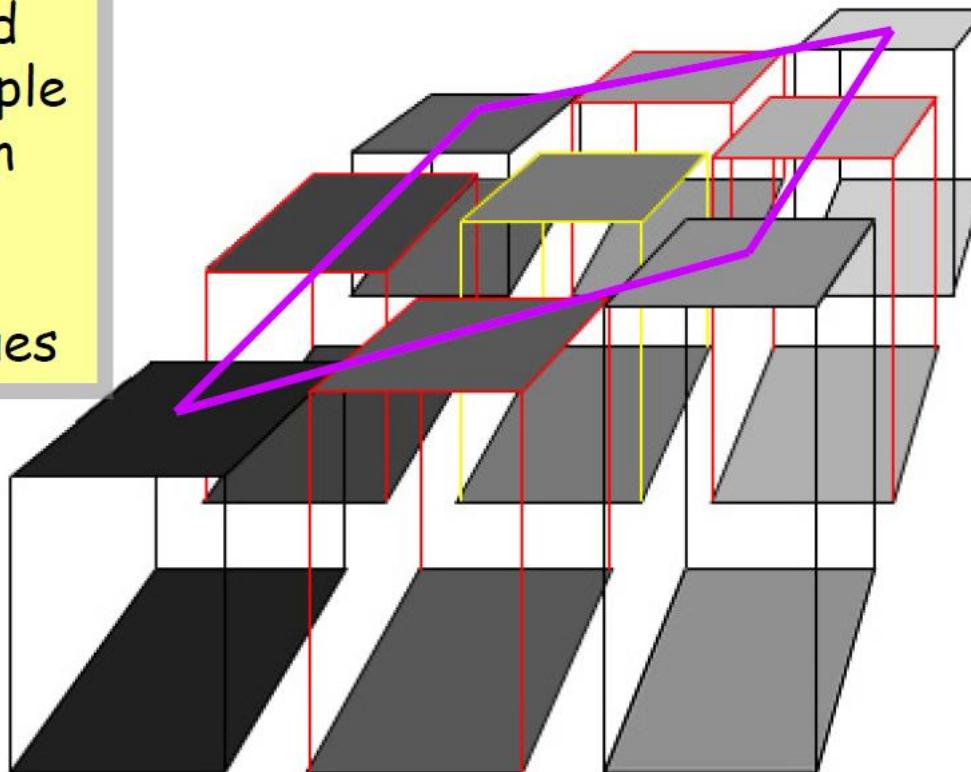
center =  
weighted  
average of  
four  
corners

# Resizing image



## Resampling Through Bilinear Interpolation

new row and column sample values lie on the lines connecting the old values

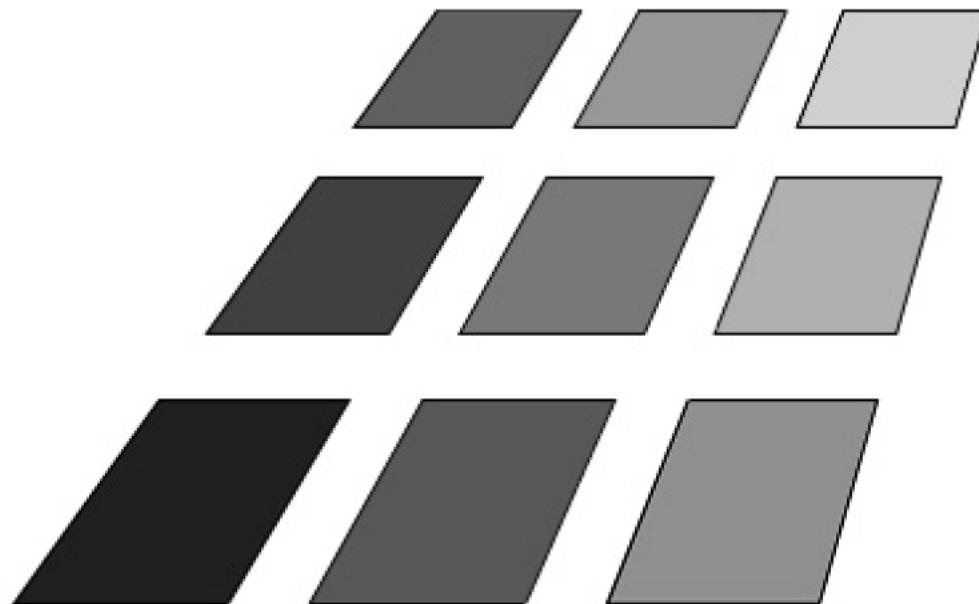


# Resizing image



## Resampling Through Bilinear Interpolation

the results



# Resizing image



## Bilinear Interpolation Example



We'll enlarge this image  
by a factor of 4 ...

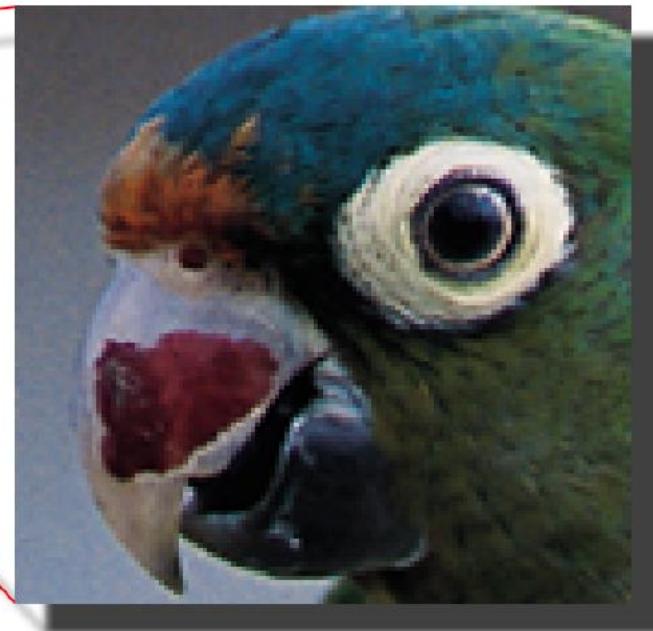
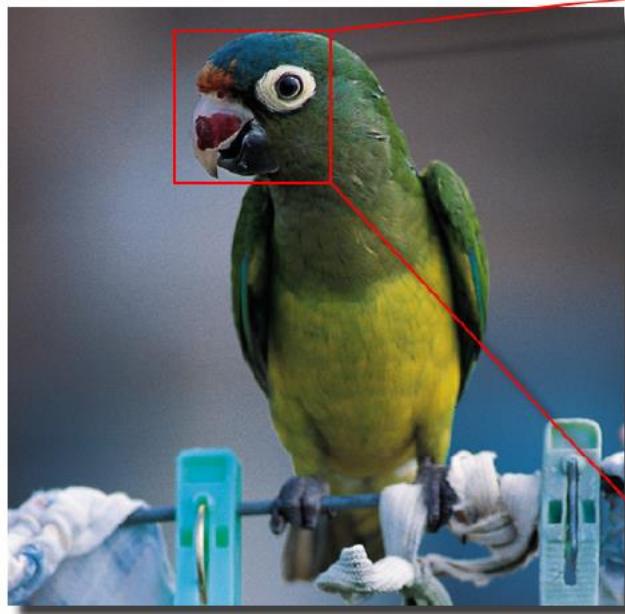
... via bilinear interpolation  
and compare it to a nearest  
neighbor enlargement.

# Resizing image



Example: Bilinear Interpolation –  $4 \times$  Zoom

Original  
Image

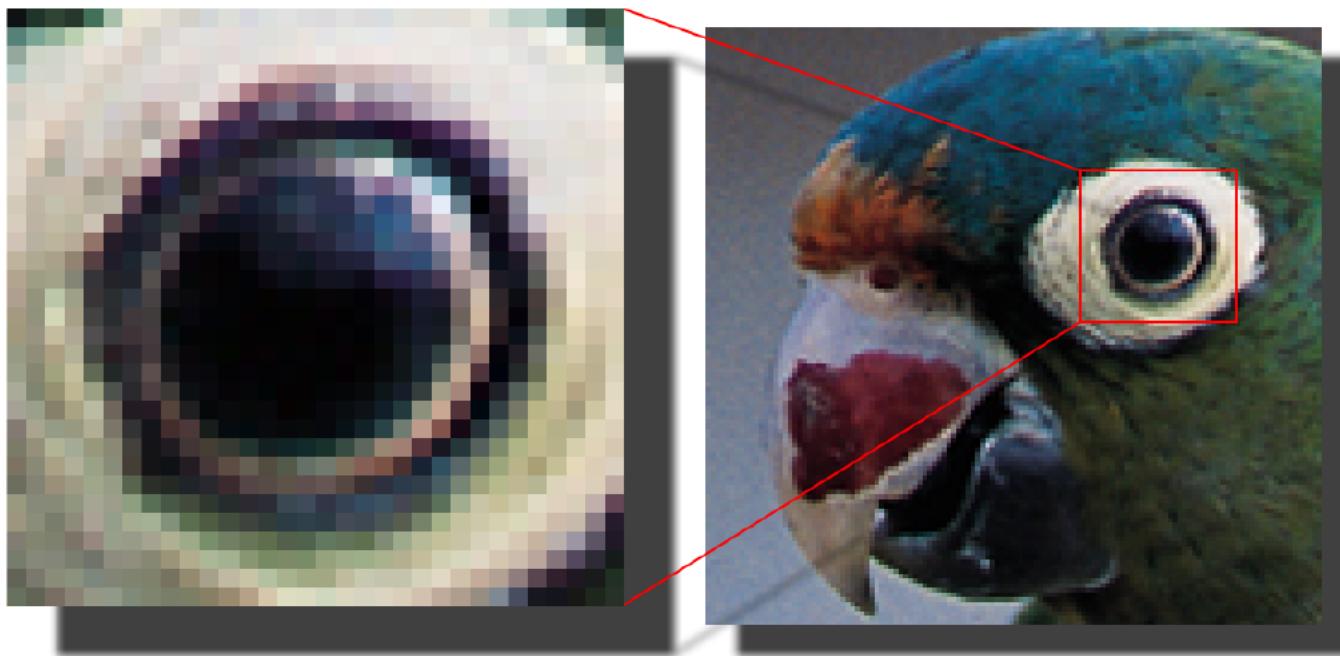


To better see what happens, we'll look at the parrot's eye.

# Resizing image



Example: Bilinear Interpolation –  $4\times$  Zoom



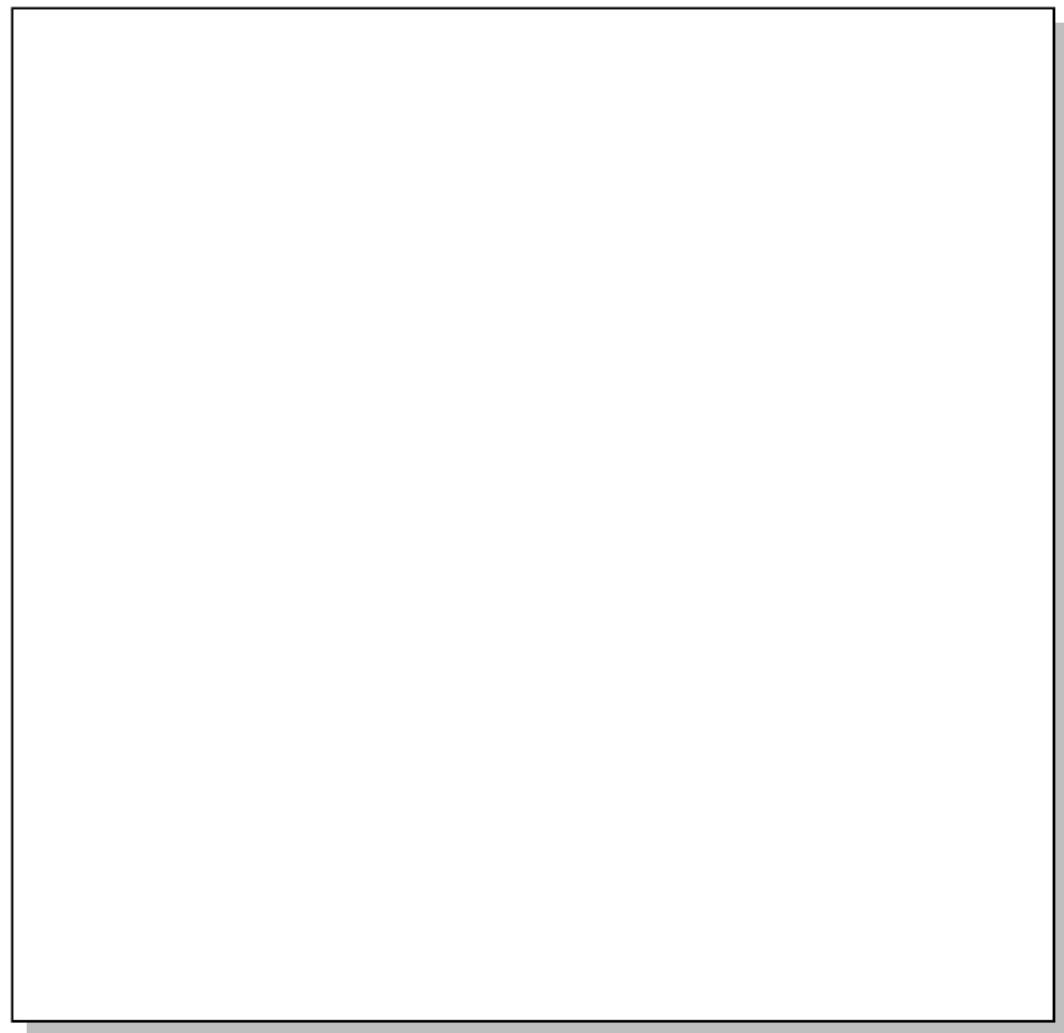
To better see what happens, we'll look at the parrot's eye.

# Resizing image



## Bilinear Interpolation

For a 4x zoom, create a blank image, four times the size of the original.

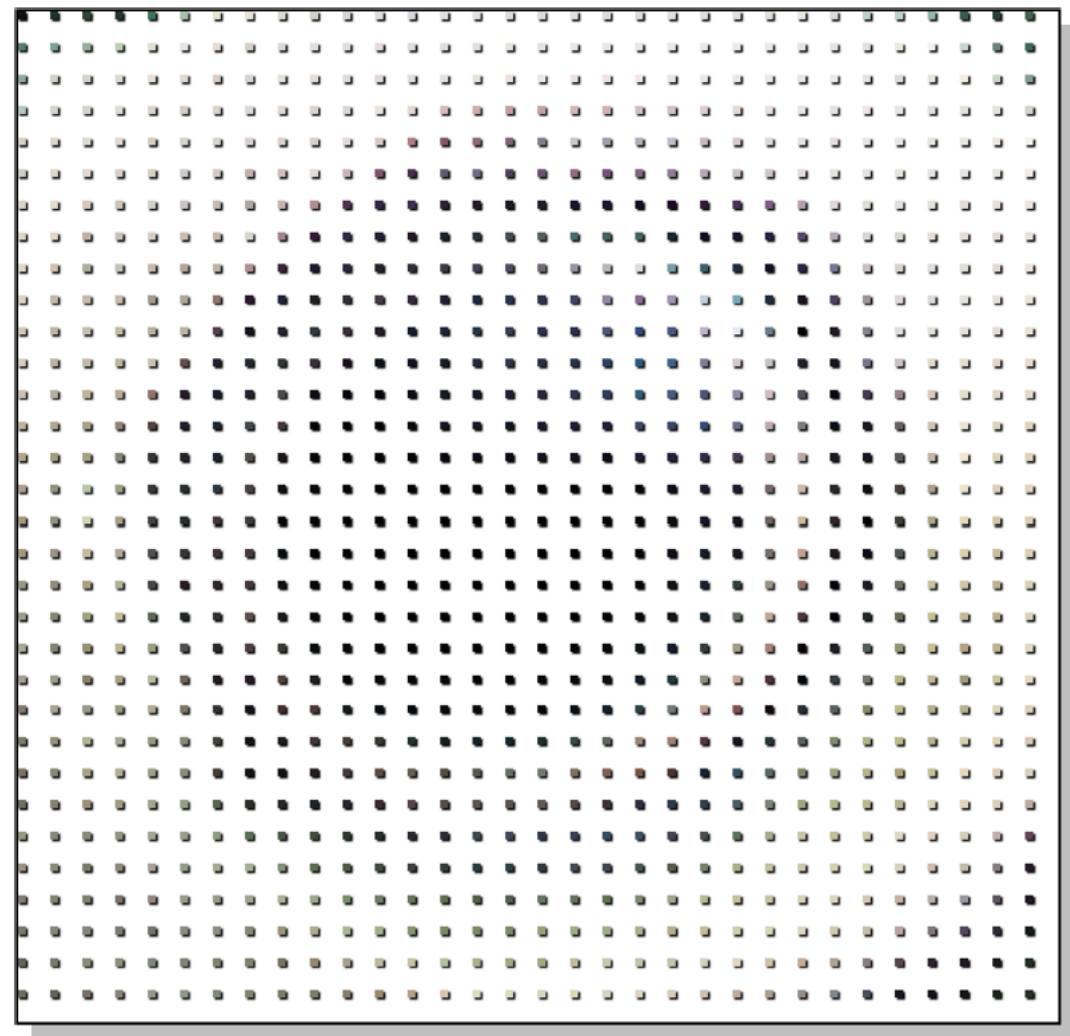


# Resizing image



## Bilinear Interpolation

Then fill in every 4th pixel in every 4th row with the original values.



# Resizing image

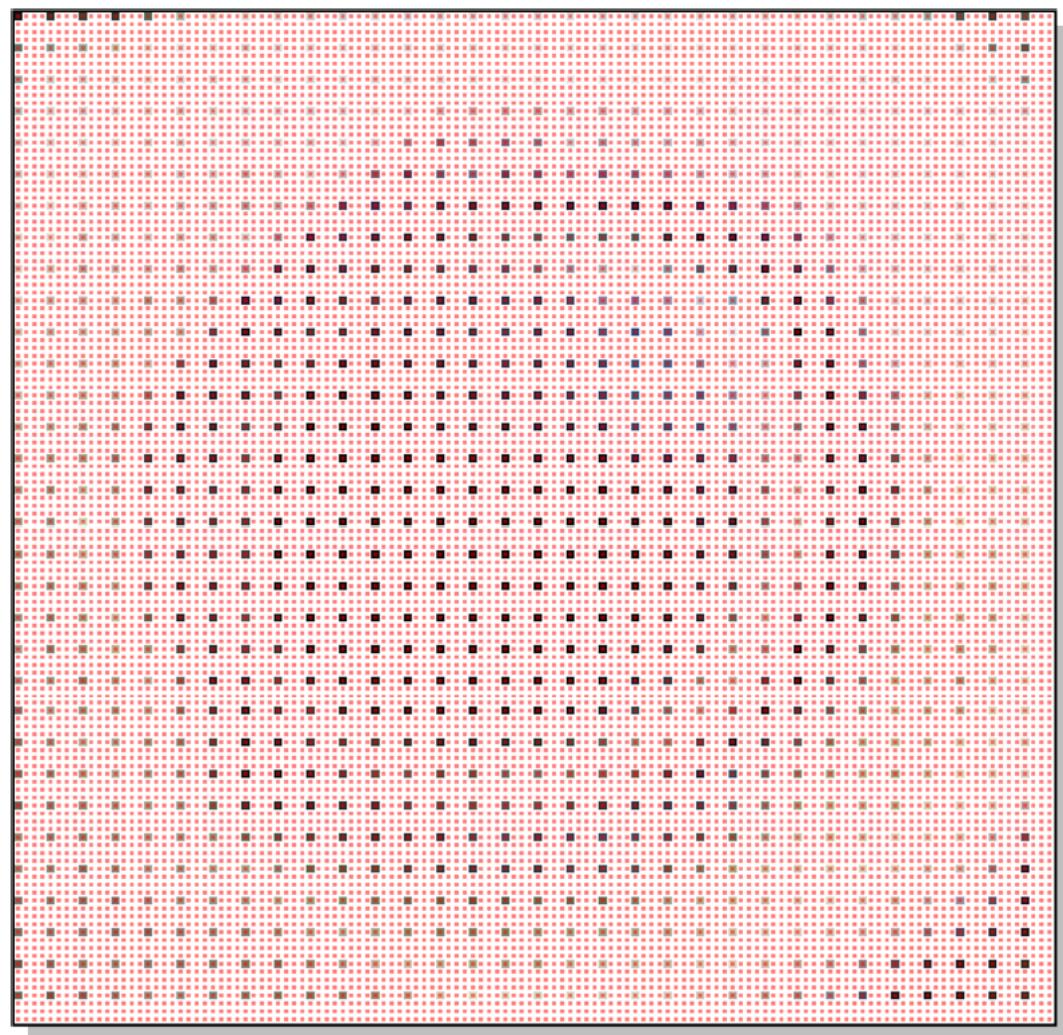


## Bilinear Interpolation

Next you want to fill in the other 15 pixels in each block with the intermediate values.



Each pink dot is a pixel location.



# Resizing image

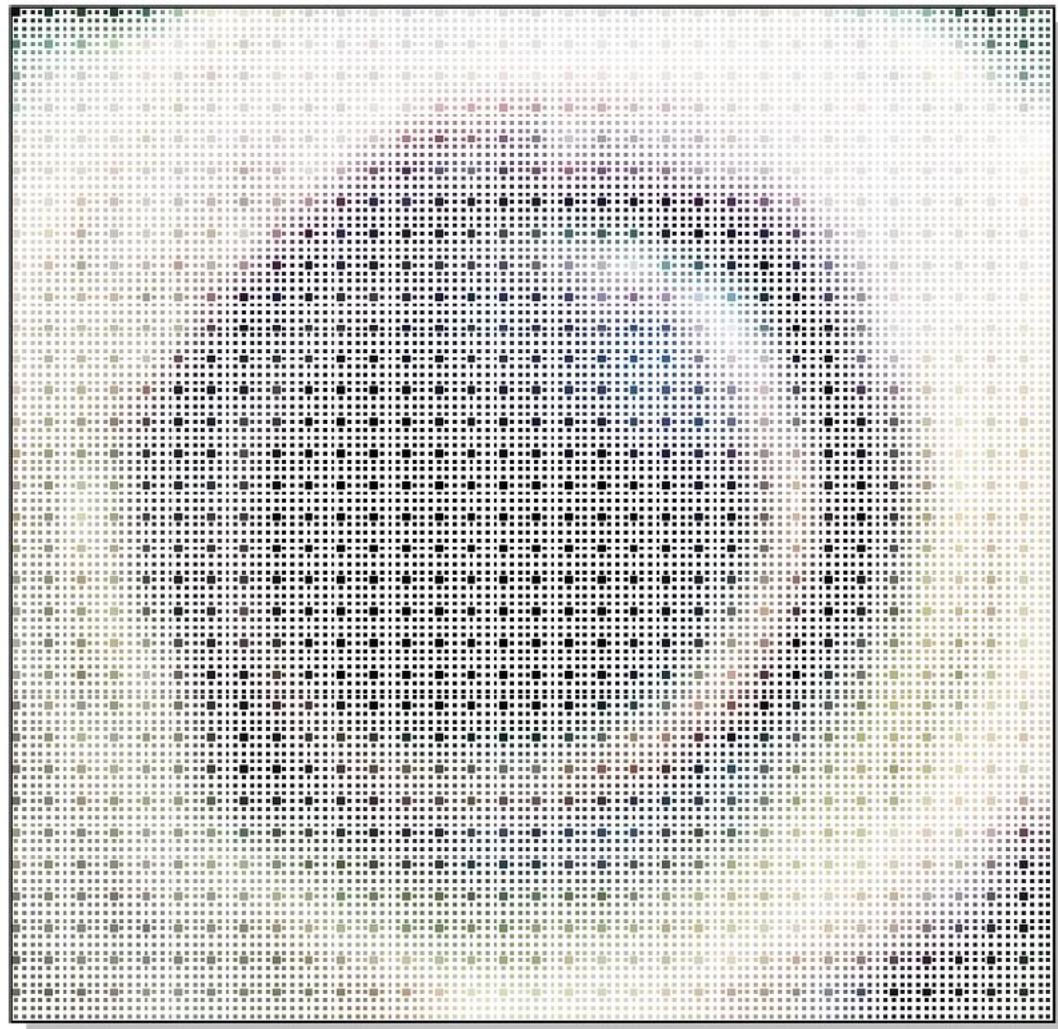


## Bilinear Interpolation

Next you want to fill in the other 15 pixels in each block with the intermediate values.



Intermediate values filled in.  
Spaces left so individual pixels can be seen.



# Resizing image



## Bilinear Interpolation

Next you want to fill in the other 15 pixels in each block with the intermediate values.



Intermediate values filled in.  
Red dots mark individual pixels.



# Resizing image



## Bilinear Interpolation

The result:



Compare to the next slide  
which contains a 4x pixel  
zoom via pixel replication.



# Resizing image



## Pixel Replication

The result:



Compare to the prev. slide  
which contains a 4x pixel  
zoom via bilinear interp.



# Resizing image

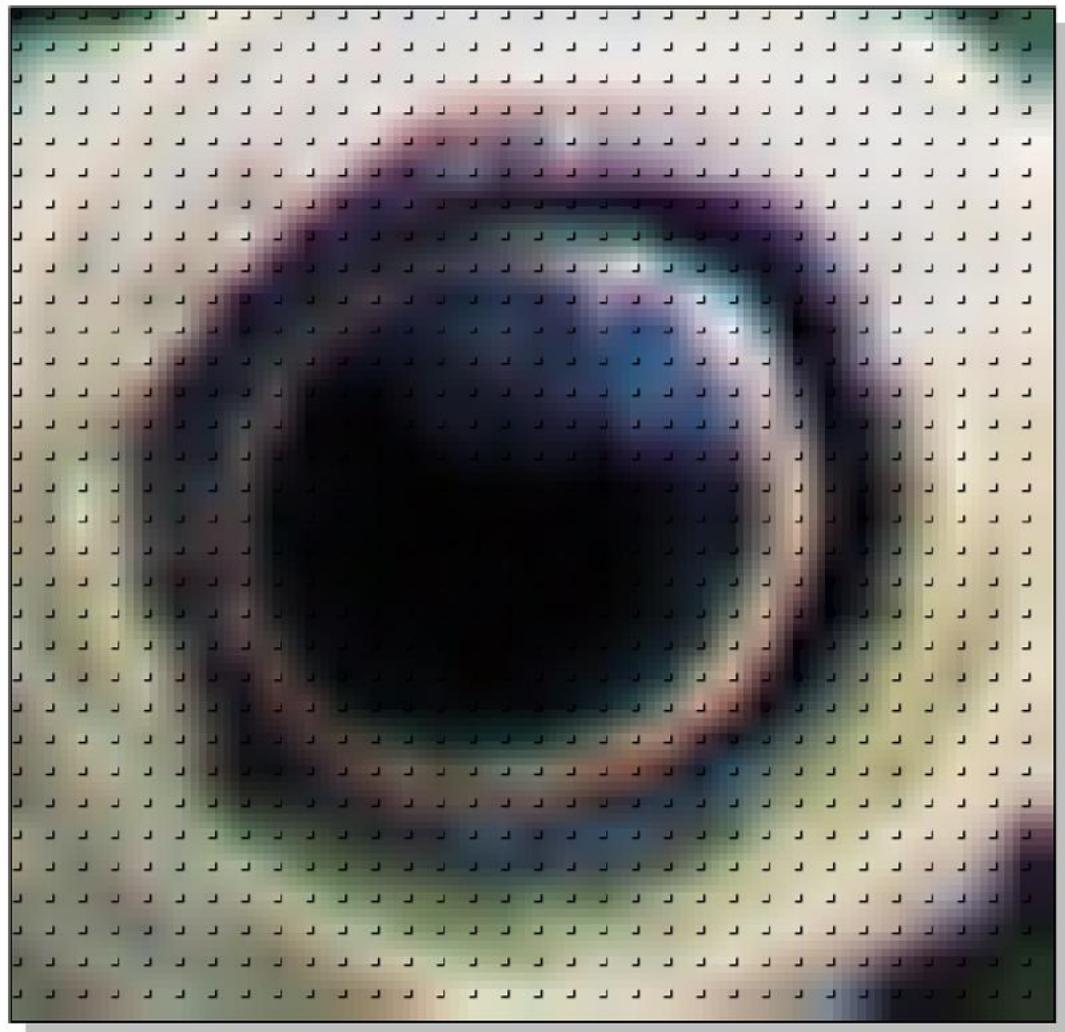


## Bilinear Interpolation

Result with original  
pixels marked:



Compare to the next slide  
which contains a 4x pixel  
zoom via pixel replication.



# Resizing image

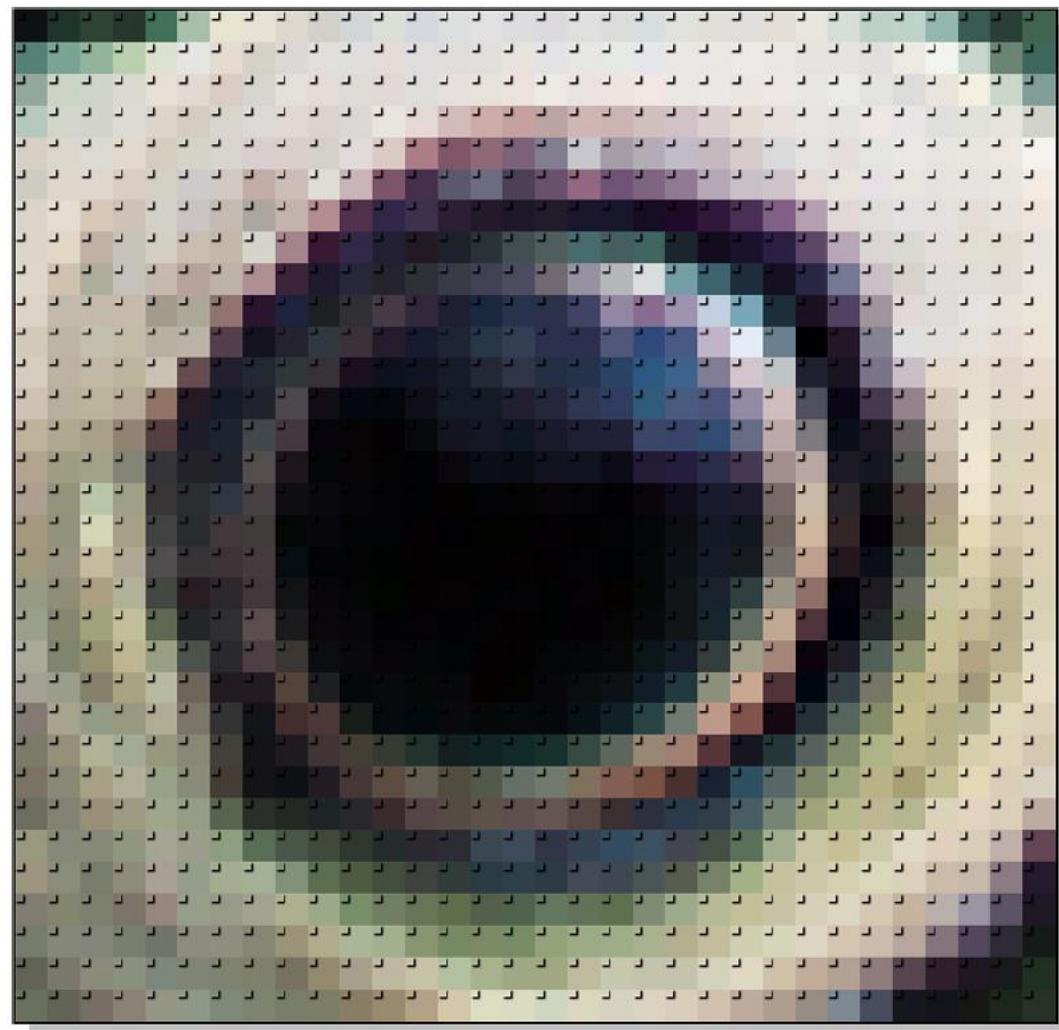


## Pixel Replication

Result with original  
pixels marked:



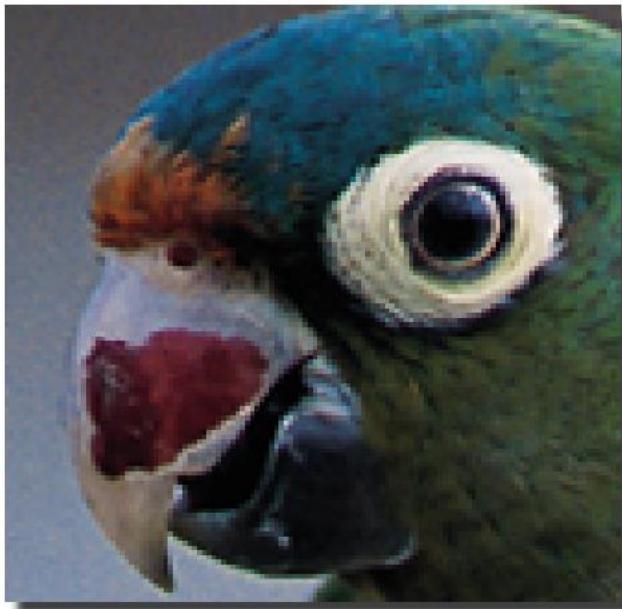
Compare to the prev. slide  
which contains a 4x pixel  
zoom via bilinear interp.



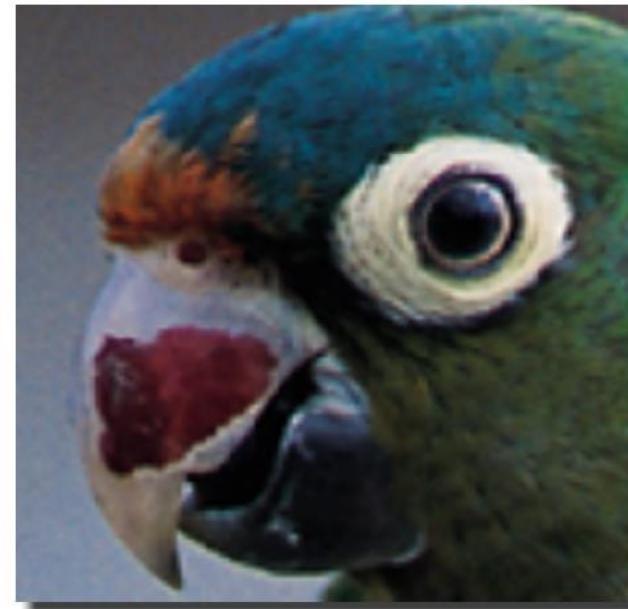
# Resizing image



## Pixel Replication vs. Bilinear Interpolation



Pixel replication

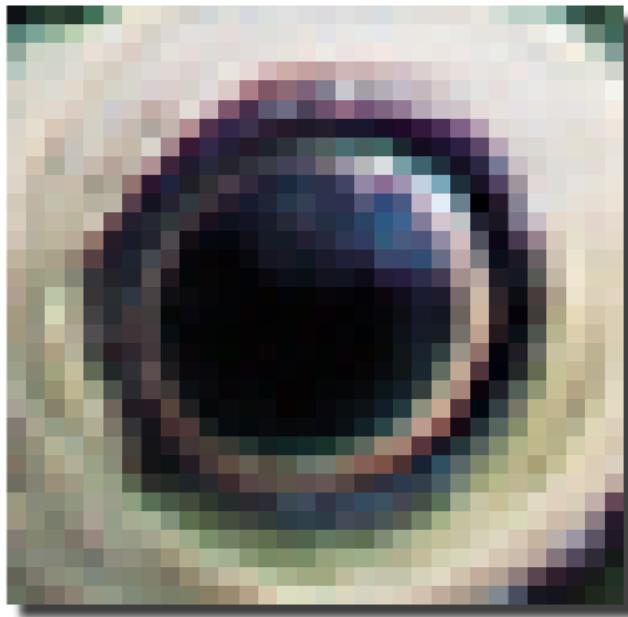


Bilinear interpolation

# Resizing image



## Pixel Replication vs. Bilinear Interpolation



Pixel replication



Bilinear interpolation

# Resizing image



## Resampling Through Bilinear Interpolation



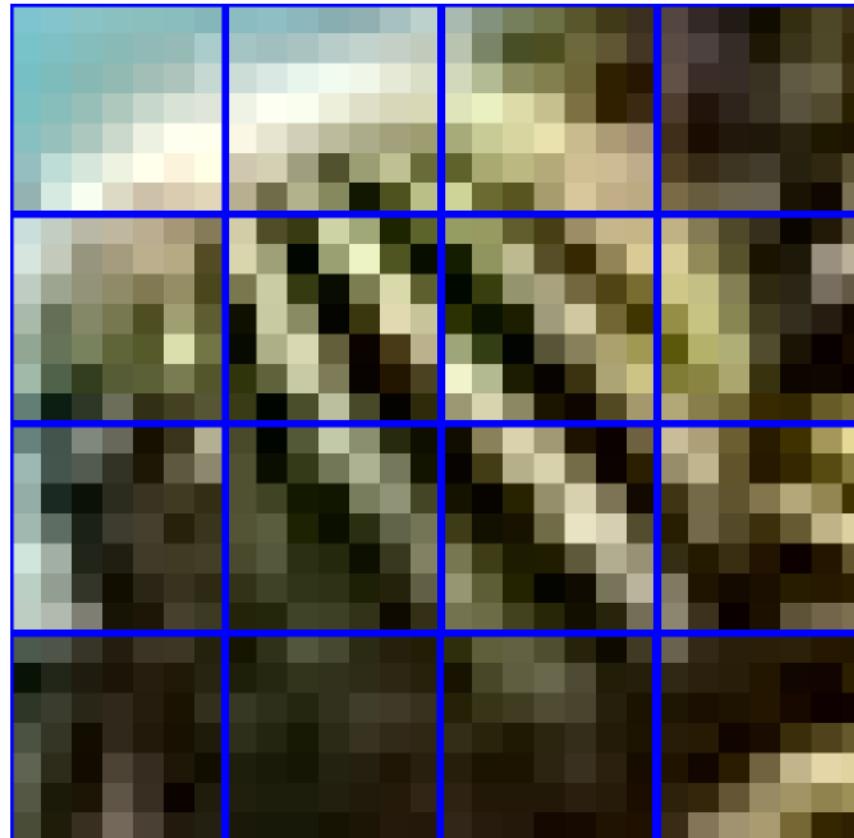
Example: reduce  
the cactus image  
to 3/7 its  
original size  
using bilinear  
interpolation

# Resizing image



## Resampling Through Bilinear Interpolation

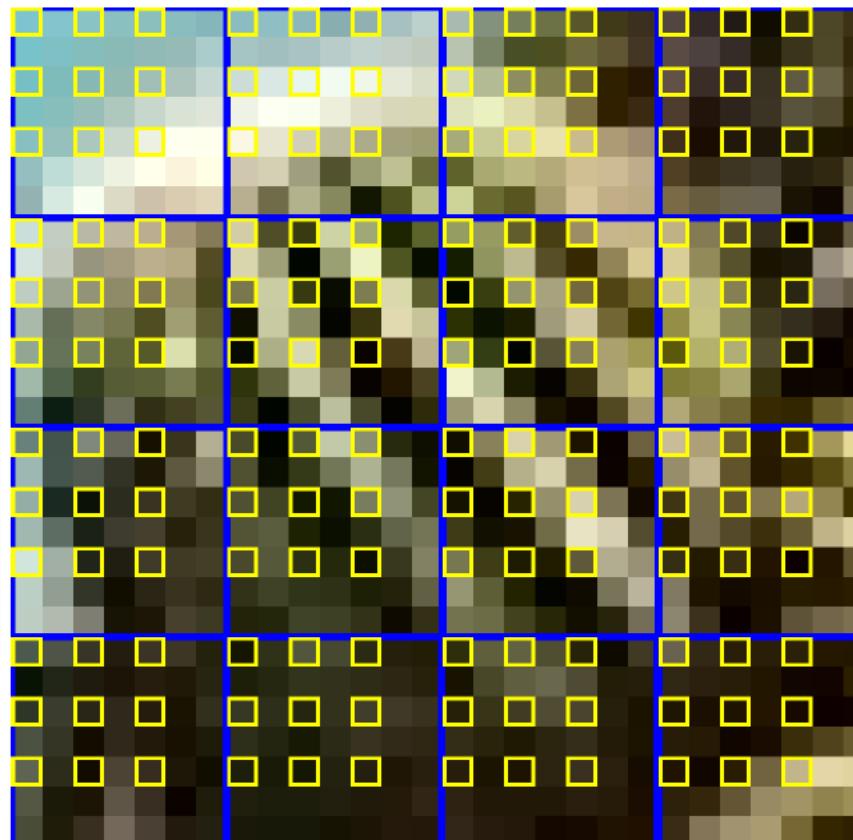
For each  $7 \times 7$  block of pixels  
select  $3 \times 3 = 9$   
pixel locations.



# Resizing image



## Resampling Through Bilinear Interpolation



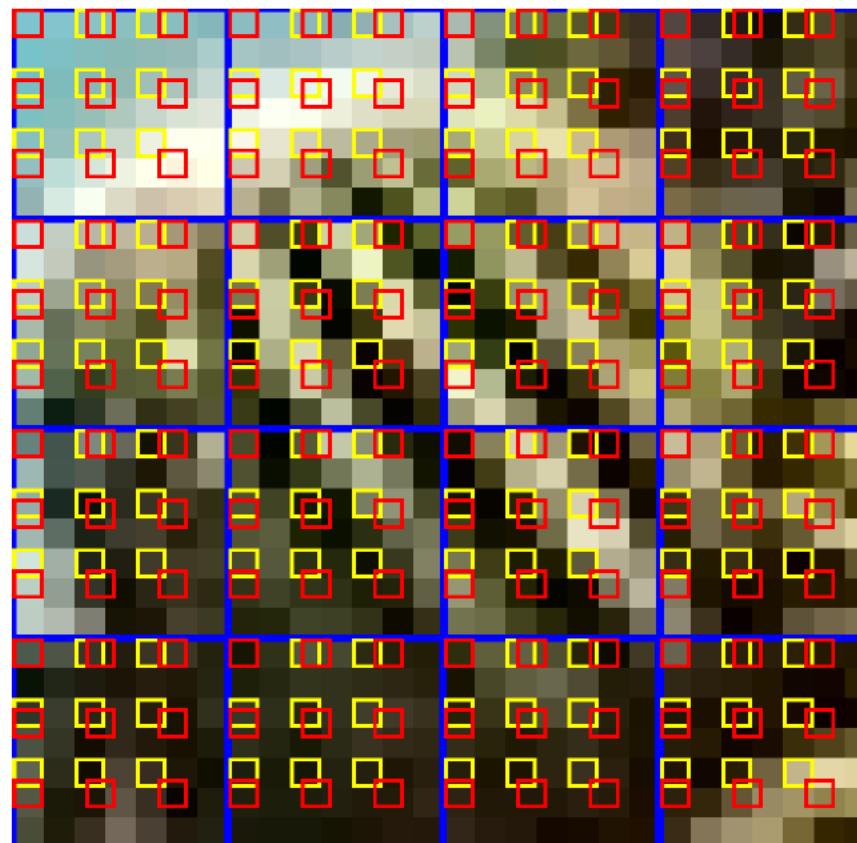
For nearest neighbor sampling the 9 pixel locations correspond to pixel locations in the original image.

Nearest neighbor selected pixels outlined in yellow.

# Resizing image



## Resampling Through Bilinear Interpolation



In bilinear interpolation the 9 pixel locations are distributed evenly.

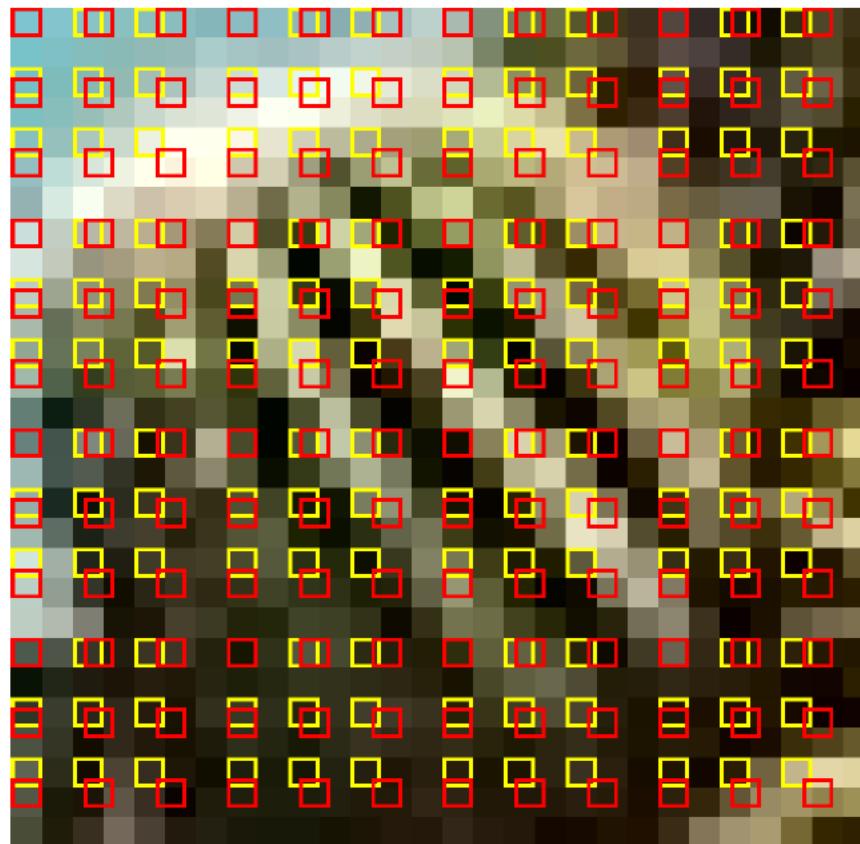
Nearest neighbor selected pixels outlined in yellow.

Bilinear interp. pixels locations outlined in red.

# Resizing image



## Resampling Through Bilinear Interpolation



In bilinear interpolation the 9 pixel locations are distributed evenly.

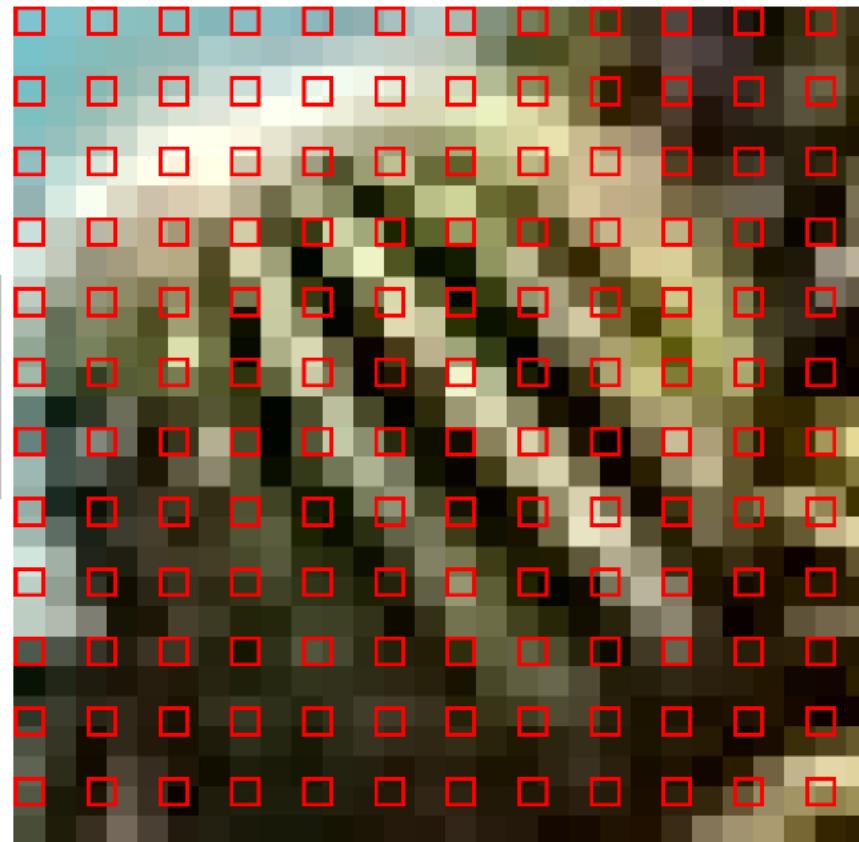
Nearest neighbor selected pixels outlined in yellow.

Bilinear interp. pixels locations outlined in red.

# Resizing image



## Resampling Through Bilinear Interpolation



In bilinear interpolation the 9 pixel locations are distributed evenly.

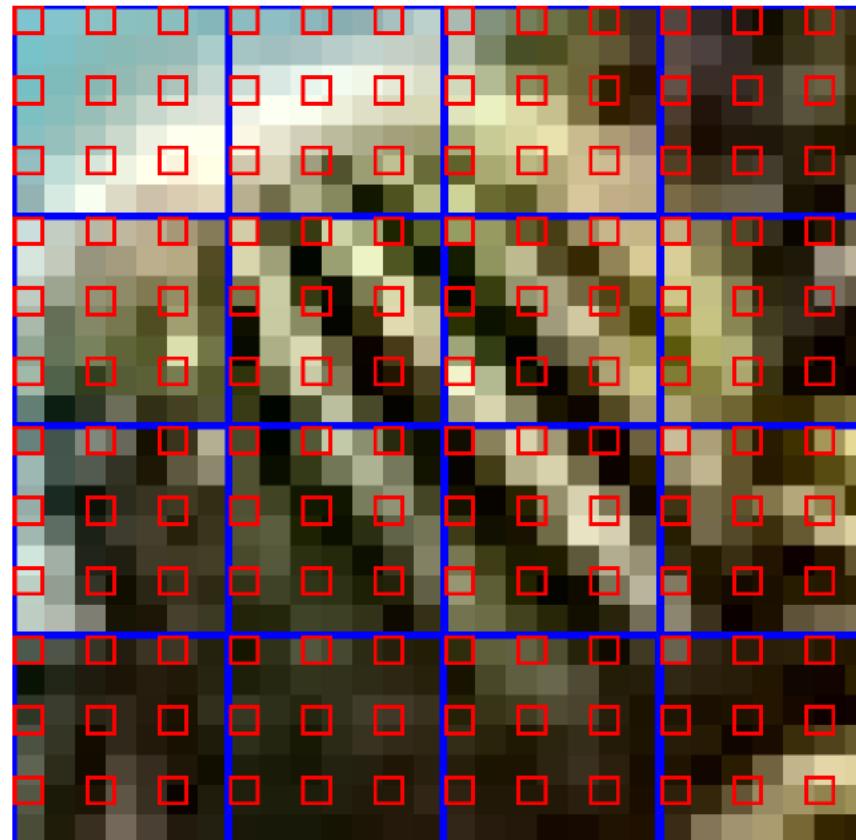
Notice that the locations overlap pixels in the original image.

# Resizing image



## Resampling Through Bilinear Interpolation

For each  $7 \times 7$  block of pixels  
select  $3 \times 3 = 9$  pixel locations.

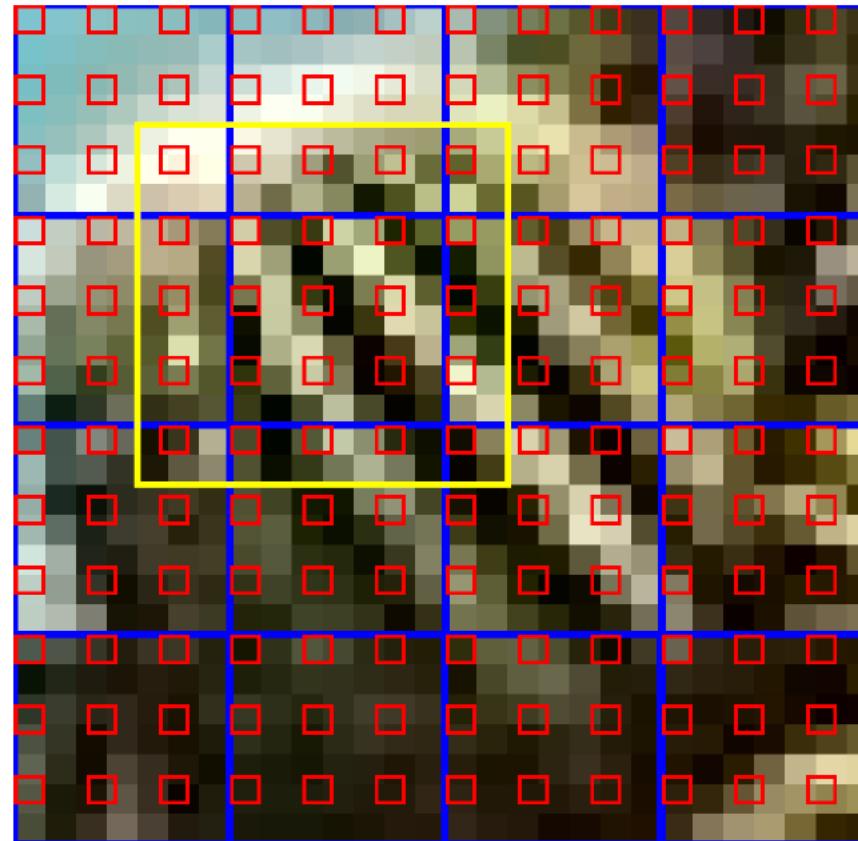


# Resizing image



## Resampling Through Bilinear Interpolation

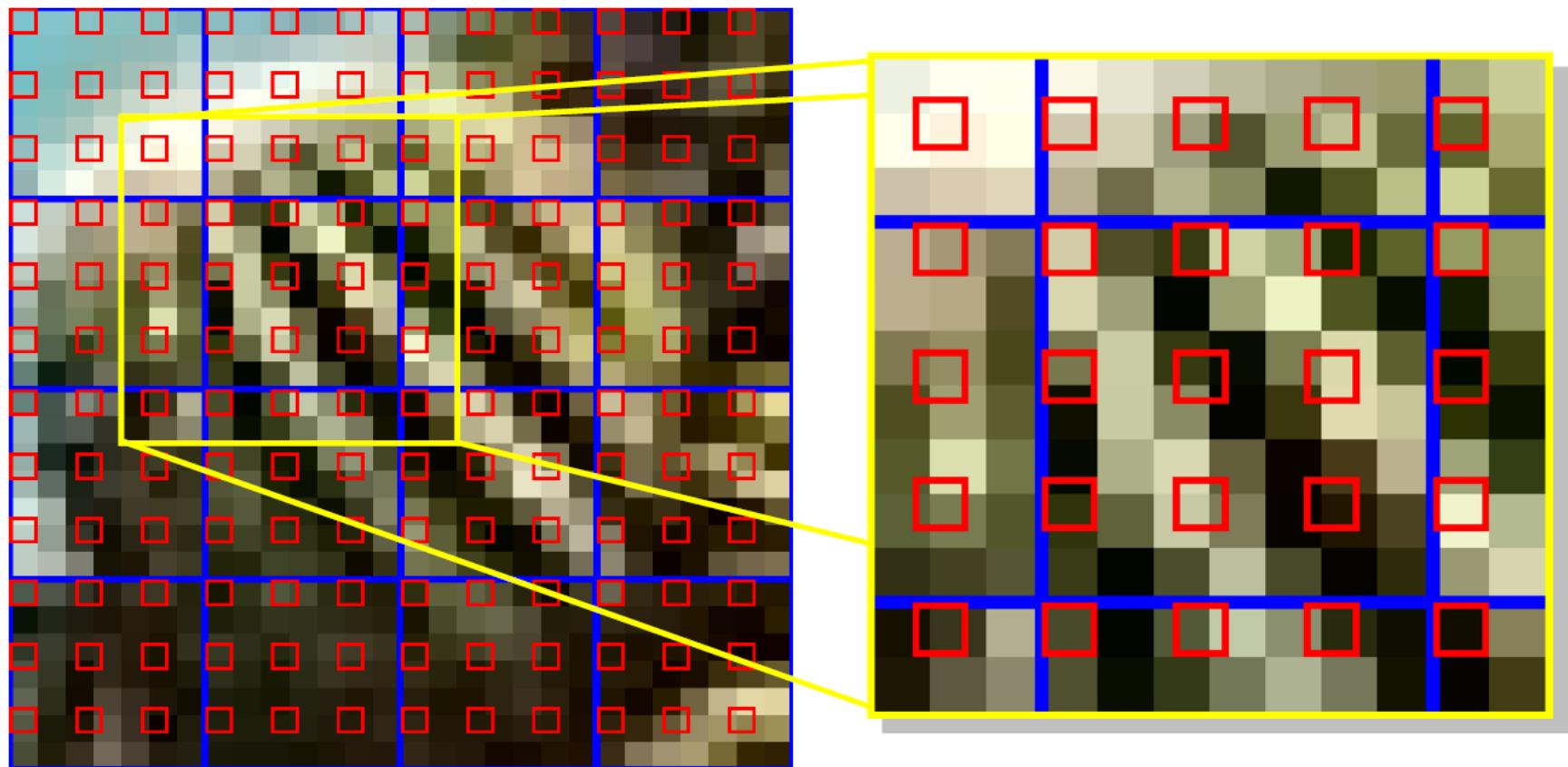
Examine one section in detail.



# Resizing image



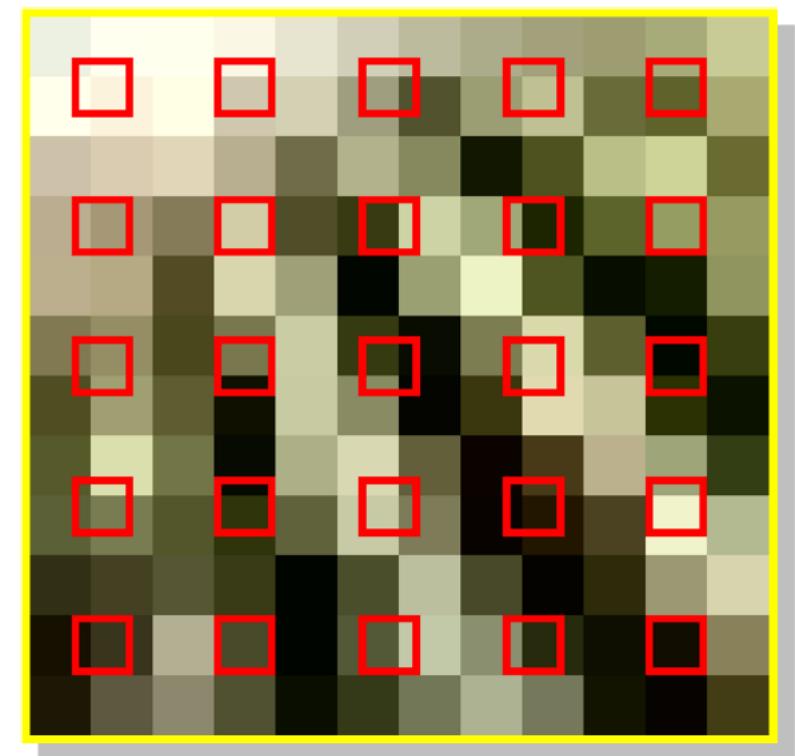
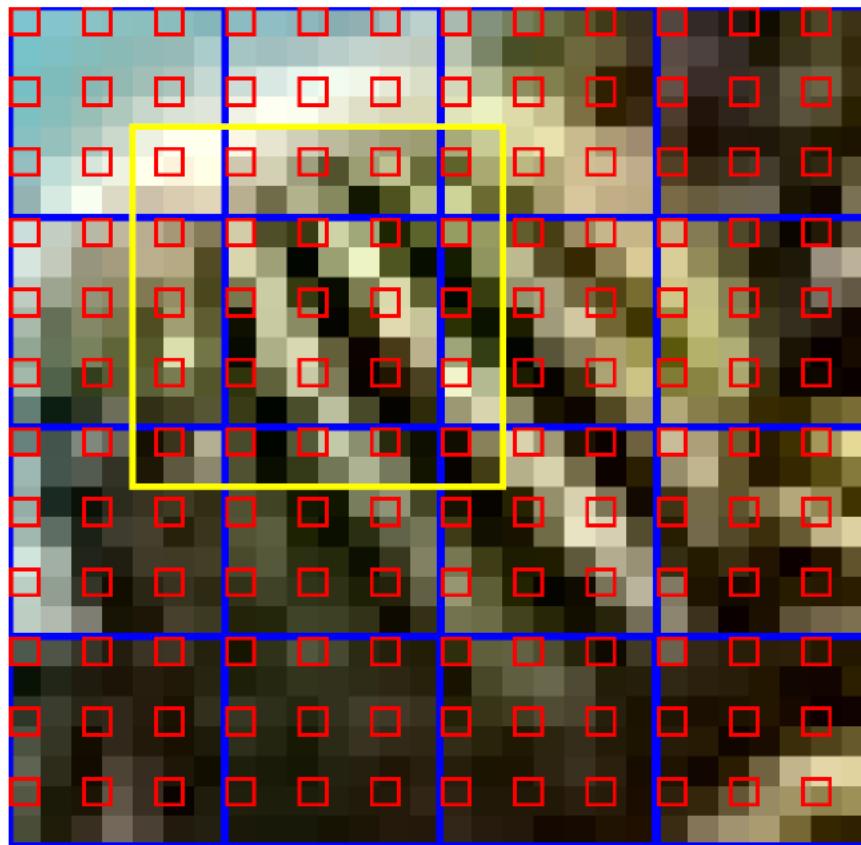
Resampling Through Bilinear Interpolation



# Resizing image



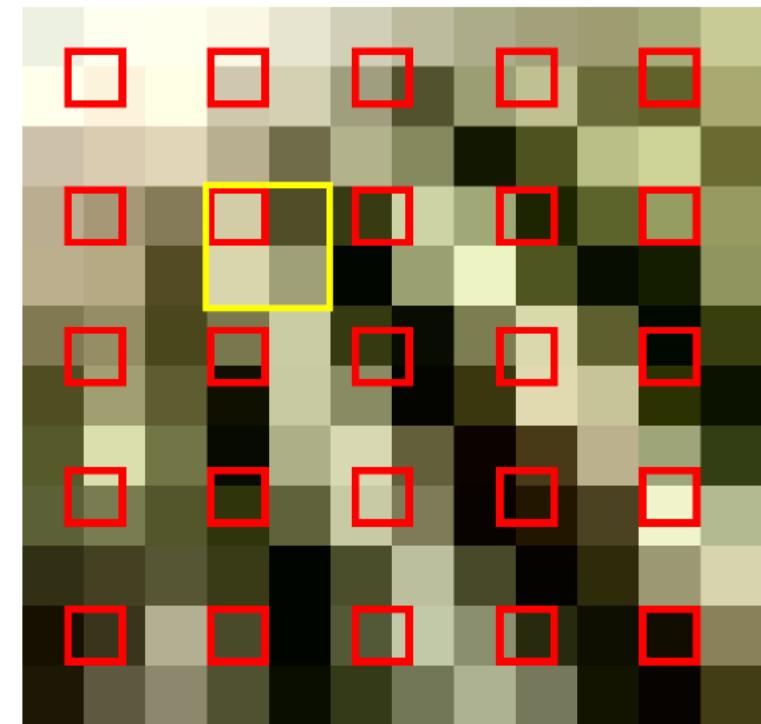
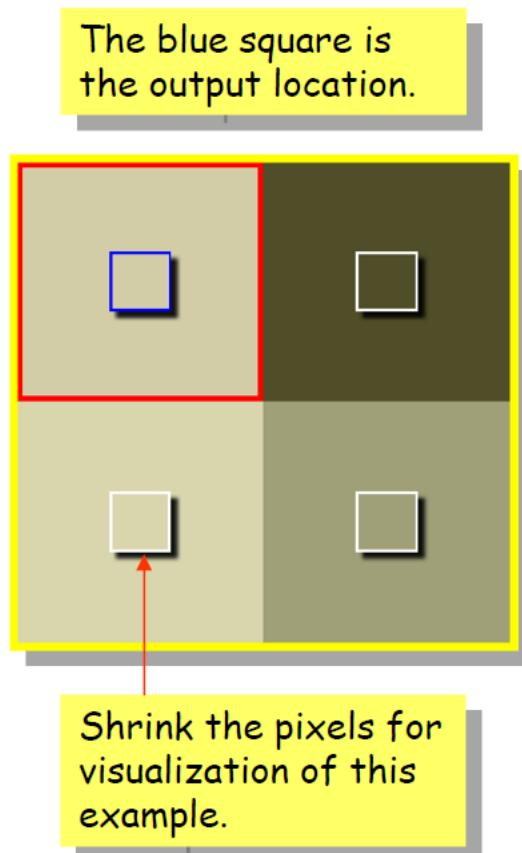
Resampling Through Bilinear Interpolation



# Resizing image



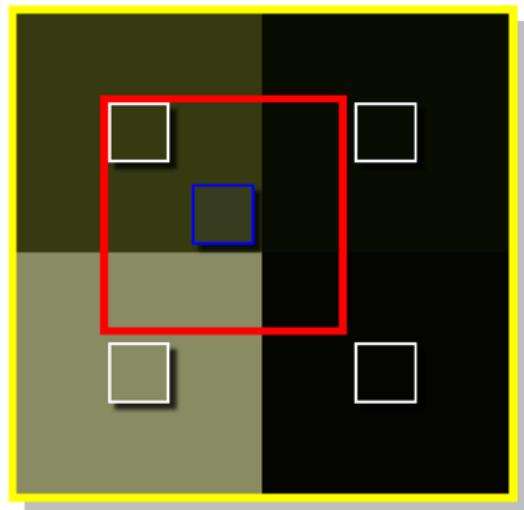
## Resampling Through Bilinear Interpolation



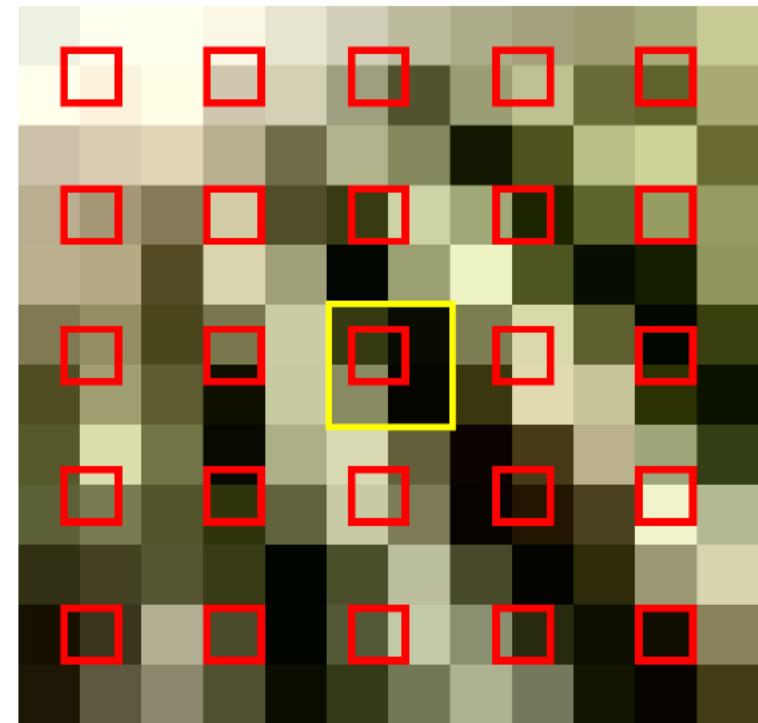
# Resizing image



## Resampling Through Bilinear Interpolation



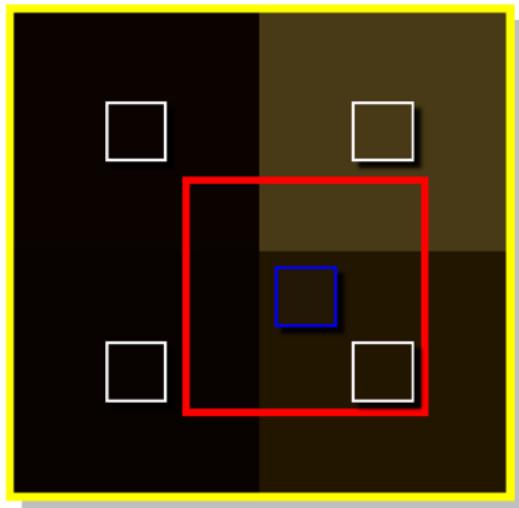
The blue square is  
the output location.



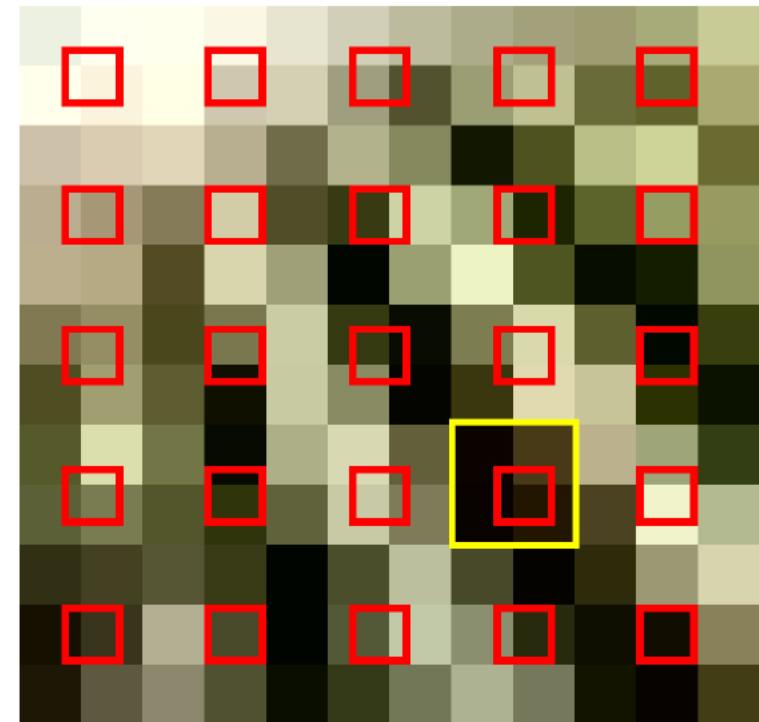
# Resizing image



## Resampling Through Bilinear Interpolation



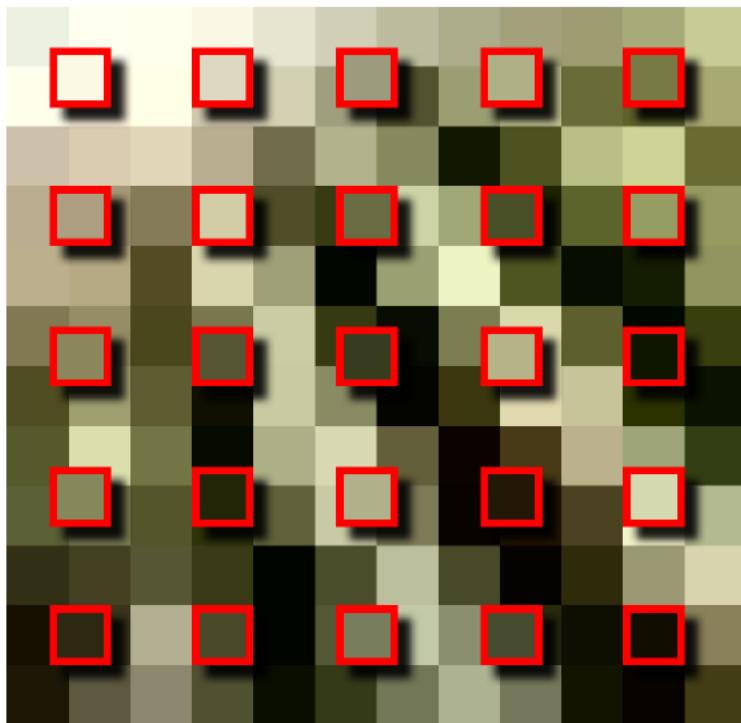
The blue square is  
the output location.



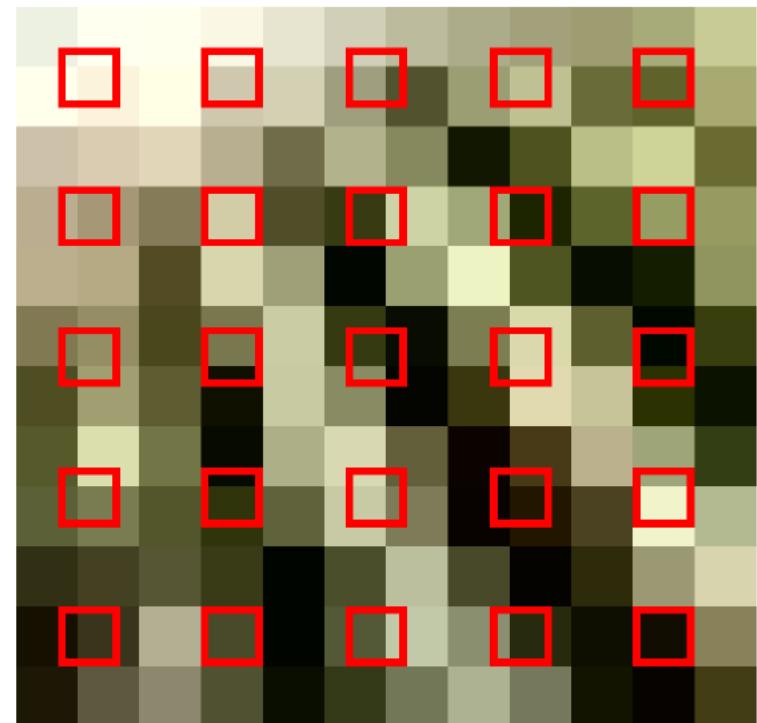
# Resizing image



## Resampling Through Bilinear Interpolation



locs & colors of new pixels

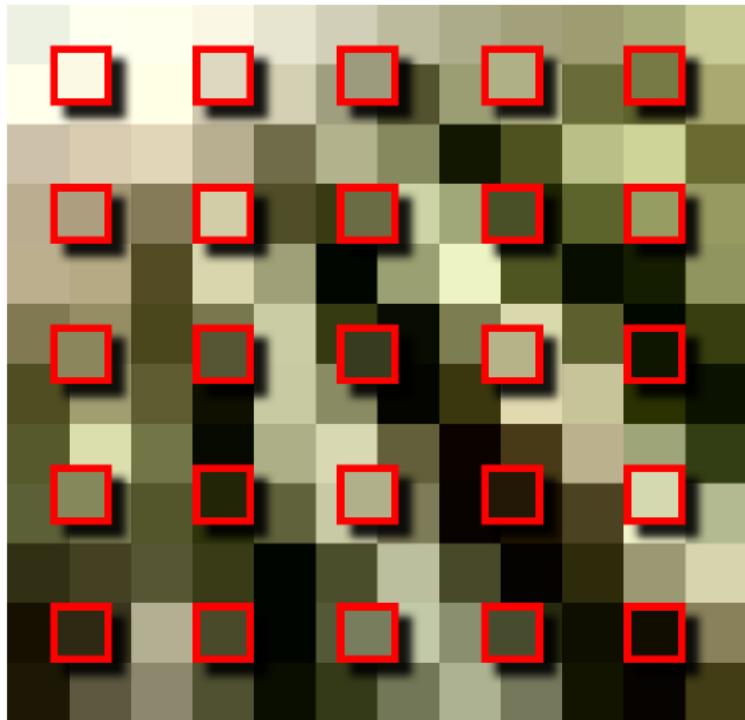


locations of new pixels

# Resizing image



Resampling Through Bilinear Interpolation



locs & colors of new pixels

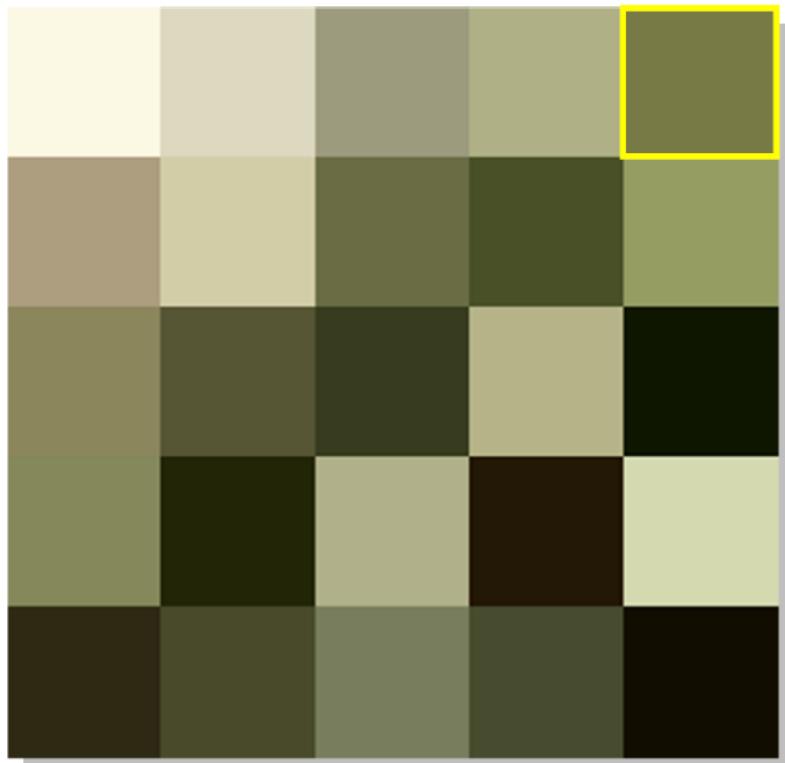


locs & colors of new pixels

# Resizing image



Resampling Through Bilinear Interpolation

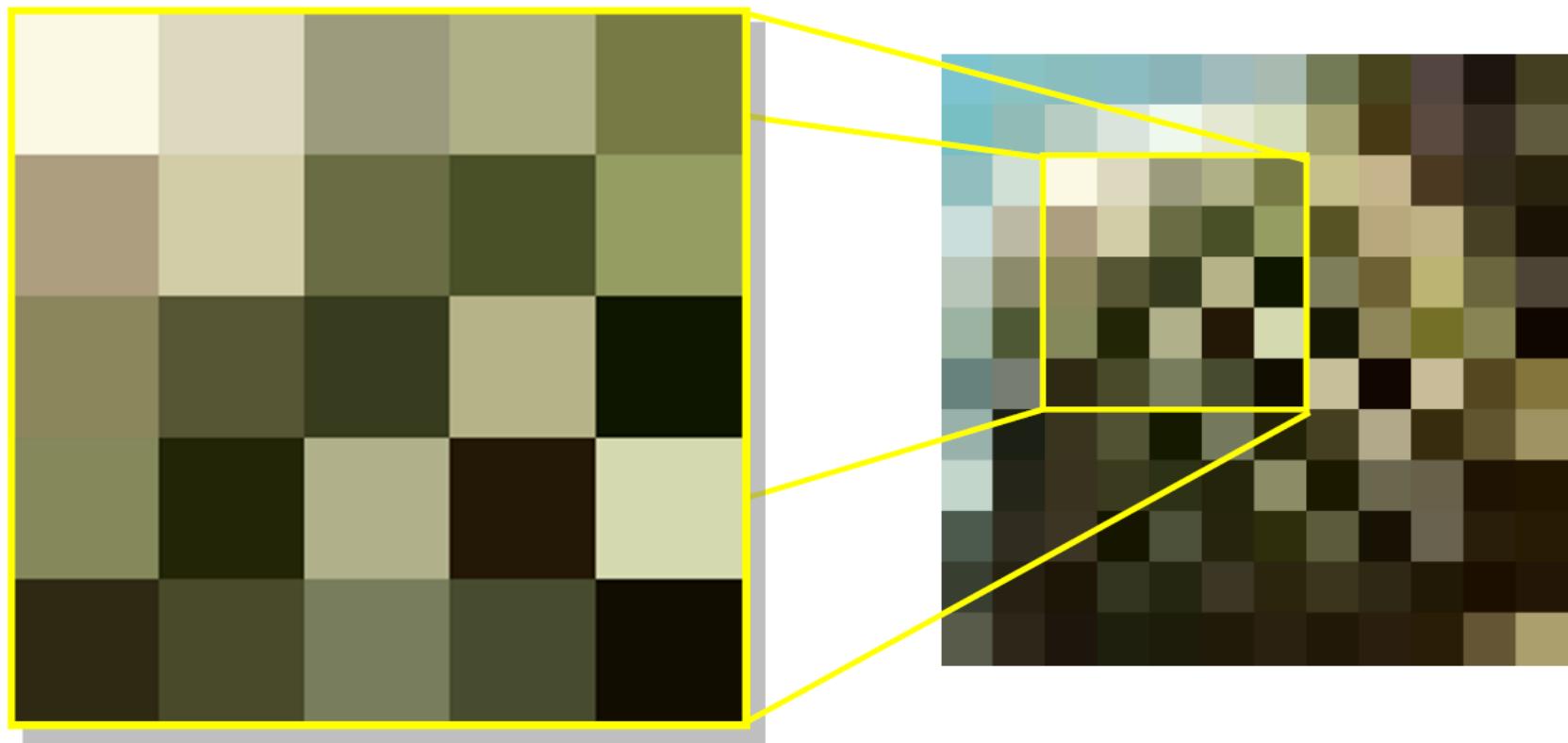


New image from new pixels

# Resizing image



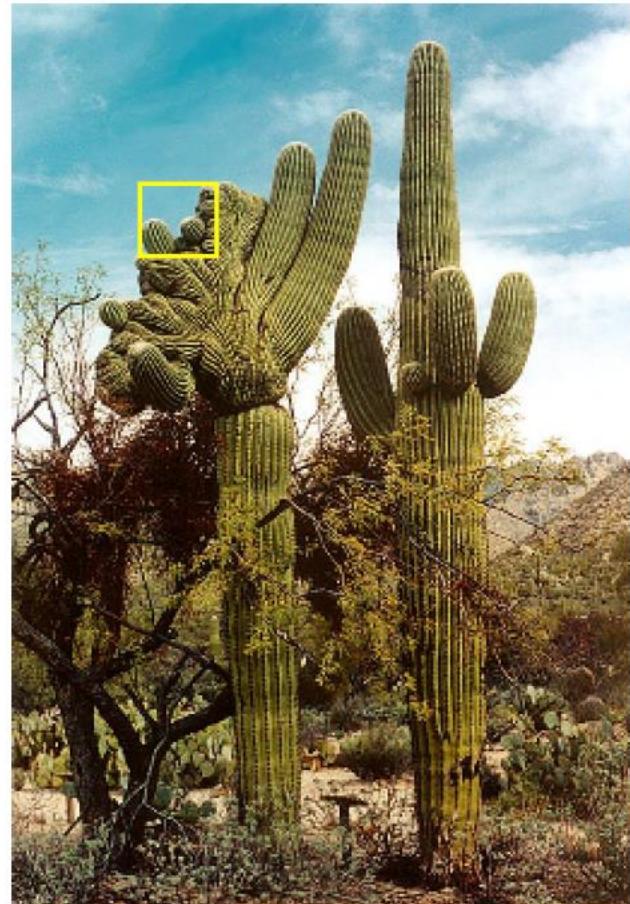
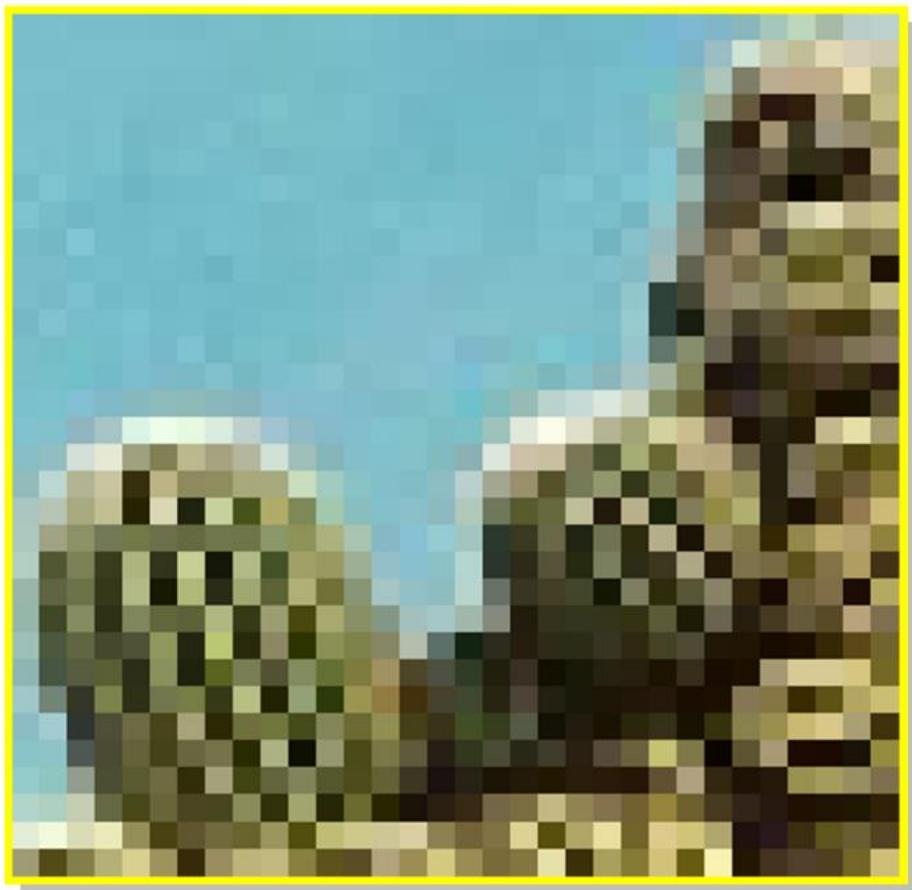
Resampling Through Bilinear Interpolation



# Resizing image



## Resampling Through Bilinear Interpolation



# Resizing image



## Resampling Through Bilinear Interpolation

Let  $\mathbf{I}$  be an  $R \times C$  image.

We want to resize  $\mathbf{I}$  to  $R' \times C'$ .

Call the new image  $\mathbf{J}$ .

Let  $s_R = R / R'$  and  $s_C = C / C'$ .

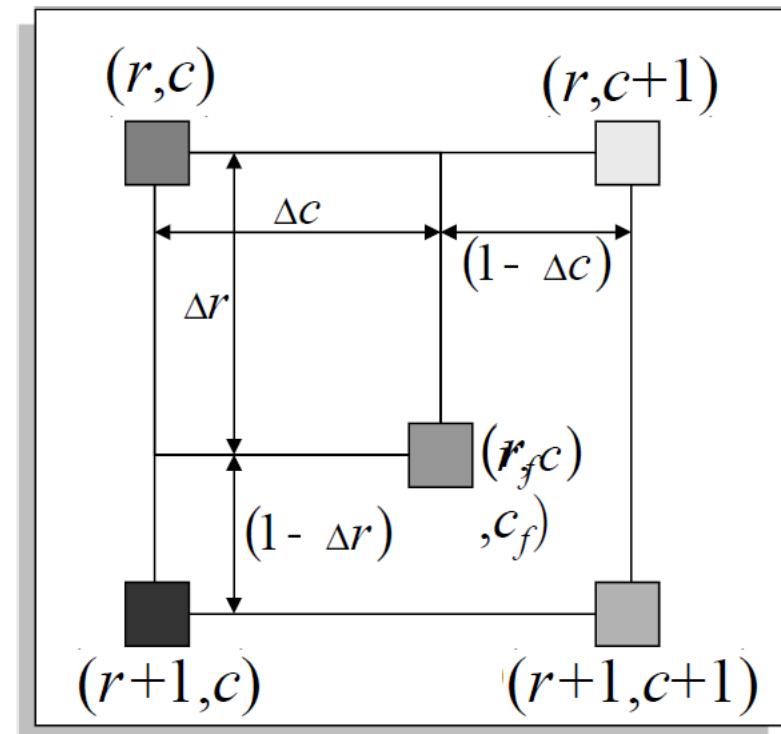
Let  $r_f = r' \cdot s_R$  for  $r' = 1, \dots, R'$

and  $c_f = c' \cdot s_C$  for  $c' = 1, \dots, C'$ .

Let  $r = \lfloor r_f \rfloor$  and  $c = \lfloor c_f \rfloor$ .

Let  $\Delta r = r_f - r$  and  $\Delta c = c_f - c$ .

Then  $\mathbf{J}(r', c') = \mathbf{I}(r, c) \cdot (1 - \Delta r) \cdot (1 - \Delta c)$   
 $+ \mathbf{I}(r+1, c) \cdot \Delta r \cdot (1 - \Delta c)$   
 $+ \mathbf{I}(r, c+1) \cdot (1 - \Delta r) \cdot \Delta c$   
 $+ \mathbf{I}(r+1, c+1) \cdot \Delta r \cdot \Delta c$ .



# Resizing image



## Resampling Through Bilinear Interpolation

Size of original image:  $R \times C$

Size of scaled image:  $R' \times C'$

Row scale factor:

$$S_r = \begin{cases} R / R', & \text{if } R > R', \\ (R - 1) / R', & \text{if } R < R'. \end{cases}$$

Column scale factor:

$$S_c = \begin{cases} C / C', & \text{if } C > C', \\ (C - 1) / C', & \text{if } C < C'. \end{cases}$$

$(r_f, c_f)$  is the fractional location in the input image from which to sample the output pixel  $(r, c)$ .

$$r_f = [(1, \dots, R') \cdot S_r], \quad c_f = [(1, \dots, C') \cdot S_c]$$

$(r, c)$  are the row and column indices of the pixels in the input image to use in the algorithm.

$$(r, c) = (\lfloor r_f \rfloor, \lfloor c_f \rfloor)$$

$(\Delta r, \Delta c)$  are the fractional parts of the row and column locations,  $(r_f, c_f)$ .

$$(\Delta r, \Delta c) = (r_f - r, c_f - c)$$

Then the value of each output pixel is given by

$$\begin{aligned} \mathbf{J}(r', c') = & \mathbf{I}(r, c) \cdot (1 - \Delta r) \cdot (1 - \Delta c) \\ & + \mathbf{I}(r + 1, c) \cdot \Delta r \cdot (1 - \Delta c) \\ & + \mathbf{I}(r, c + 1) \cdot (1 - \Delta r) \cdot \Delta c \\ & + \mathbf{I}(r + 1, c + 1) \cdot \Delta r \cdot \Delta c. \end{aligned}$$

# Resizing image



Size Reduction 3/7



original



nearest neighbor



bilinear



bicubic

# Resizing image



Size Reduction 3/7

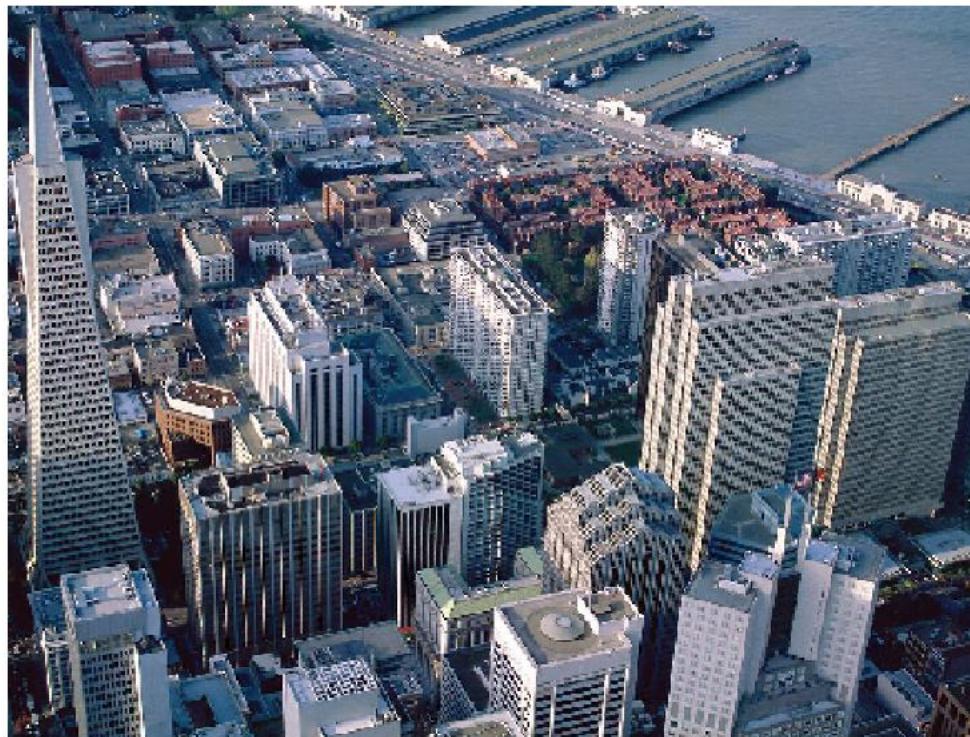


original

# Resizing image



Size Reduction 3/7 (zoomed)



nearest neighbor

# Resizing image



Size Reduction 3/7 (zoomed)



bilinear

# Resizing image



Size Reduction 3/7 (zoomed)



bicubic

# Noise Reduction



blurred image



color noise



color-only blur

# Shot Noise or Salt & Pepper Noise



+ shot noise



s&p noise



- shot noise

# Nonlinear Filters: the Median



original



s&p noise



median filter

# Nonlinear Filters: Min and Maxmin



+ shot noise



min filter



maxmin filter

# Nonlinear Filters: Max and Minmax



- shot noise



max filter



minmax