



Linear Machines and SVM

– Part 1: Linear Machines Basics

Objective



Objective

Define general linear
classifiers

Revisiting Logistic Regression

| **In Logistic Regression:** given a training set of n labelled samples $\langle \mathbf{x}^{(i)}, y^{(i)} \rangle$, we learn $P(y|\mathbf{x})$ by assuming a logistic sigmoid function.

→ We end up with a *linear classifier*.

→ $g(\mathbf{x}) = \mathbf{w}^t \mathbf{x}$ is called the *discriminant function*.

Linear Discriminant Functions



| In general, taking a discriminative approach, we can *assume* some form for the discriminant function that defines the classifier.

➔ The learning task is to use the training samples to estimate the parameters of the classifier.

Linear Decision Boundaries

| Linear discriminant functions give
arise to linear decision boundaries

→ *linear classifiers* or *linear machines*

| We will use both notations:

$$g(\mathbf{x}) = \mathbf{w}^t \mathbf{x} \quad \text{or} \quad g(\mathbf{x}) = \mathbf{w}^t \mathbf{x} + w_0$$

Linear Machine for $C > 2$ Classes



| We can define C linear discriminant functions:

$$g_i(\mathbf{x}) = \mathbf{w}_i^t \mathbf{x}, \quad i = 1, 2, \dots, C$$

| What is the decision rule for the classifier?

The Learning Task

| Finding $\mathbf{w}_i, i = 1, 2, \dots, C$

| Let's use the 2-class case as an example

- For n samples $\mathbf{x}_1, \dots, \mathbf{x}_n$, of 2 classes ω_1 and ω_2 , if there exists a vector \mathbf{w} such that $g(\mathbf{x}) = \mathbf{w}^t \mathbf{x}$ classifies them all correctly \rightarrow Finding \mathbf{w}

i.e., finding \mathbf{w} such that

$$\begin{aligned} \mathbf{w}^t \mathbf{x}_i &\geq 0 \text{ for samples of } \omega_1 \quad \text{and} \\ \mathbf{w}^t \mathbf{x}_i &< 0 \text{ for samples of } \omega_2, \end{aligned}$$

Linear Separability



| If we can find at least one vector \mathbf{w} such that $g(\mathbf{x}) = \mathbf{w}^t \mathbf{x}$ classifies all samples

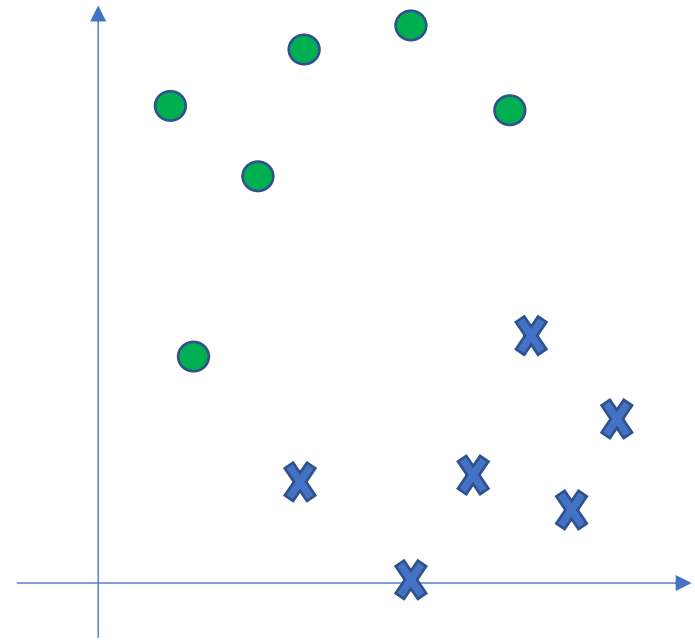
→ We say the samples are linearly separable.

| An example of not linearly separable in 2-D:

The Solution Region

| There may be many different weight vectors that can all be valid solutions for a given training set

→ The solution regions



| If the solution vector is not unique,
Which one is the best?

Solving for the Weight Vector



| Consider the following approach: finding a solution vector which optimizes some objective function.

→ We may introduce additional constraints for a “good” solution”

→ **Solving a constrained optimization problem.**

| Theoretical: Lagrange or Karush-Kuhn-Tucker.

| In practice: e.g., gradient-descent-based search

Gradient Descent Procedure

| Basic idea:

- Define a cost function $J(\mathbf{w})$
- Starting from an initial weight vector $\mathbf{w}(0)$
- Update \mathbf{w} by

$$\mathbf{w}(k + 1) = \mathbf{w}(k) - \eta(k) \nabla J(\mathbf{w}(k)),$$

| $\eta > 0$ is the *learning rate*.