

Unsupervised Deep Learning for Fast Imaging: From DAE to Generative Model

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Unsupervised Deep Learning for Fast Imaging: From DAE to Generative Model

Outline:

1. Fast imaging: From CS to AI

2. A review of USL

2.1 Five representatives of USL

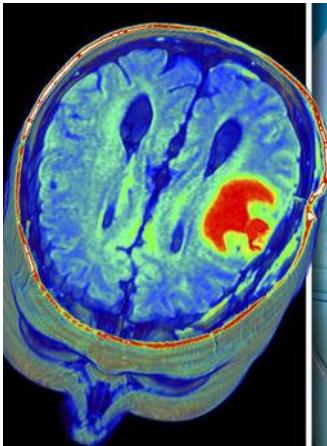
2.2 Underlying ideas for improvements

3. Our work of USL in fast imaging

3.1 Examples of USL from DAE to DSM

3.2 Examples of DSM from image domain to k-space domain

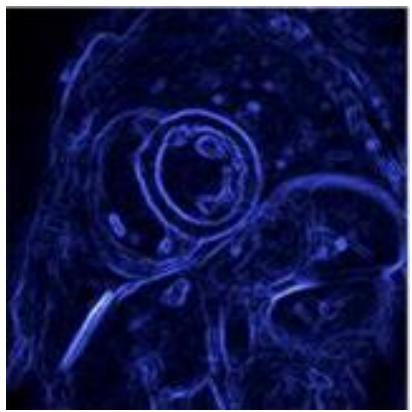
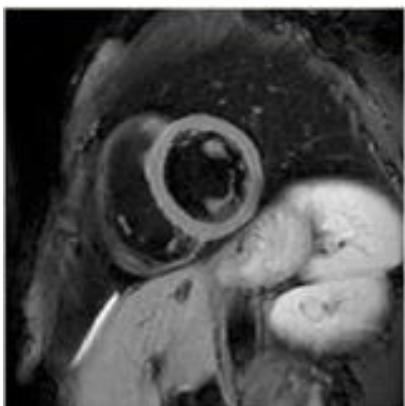
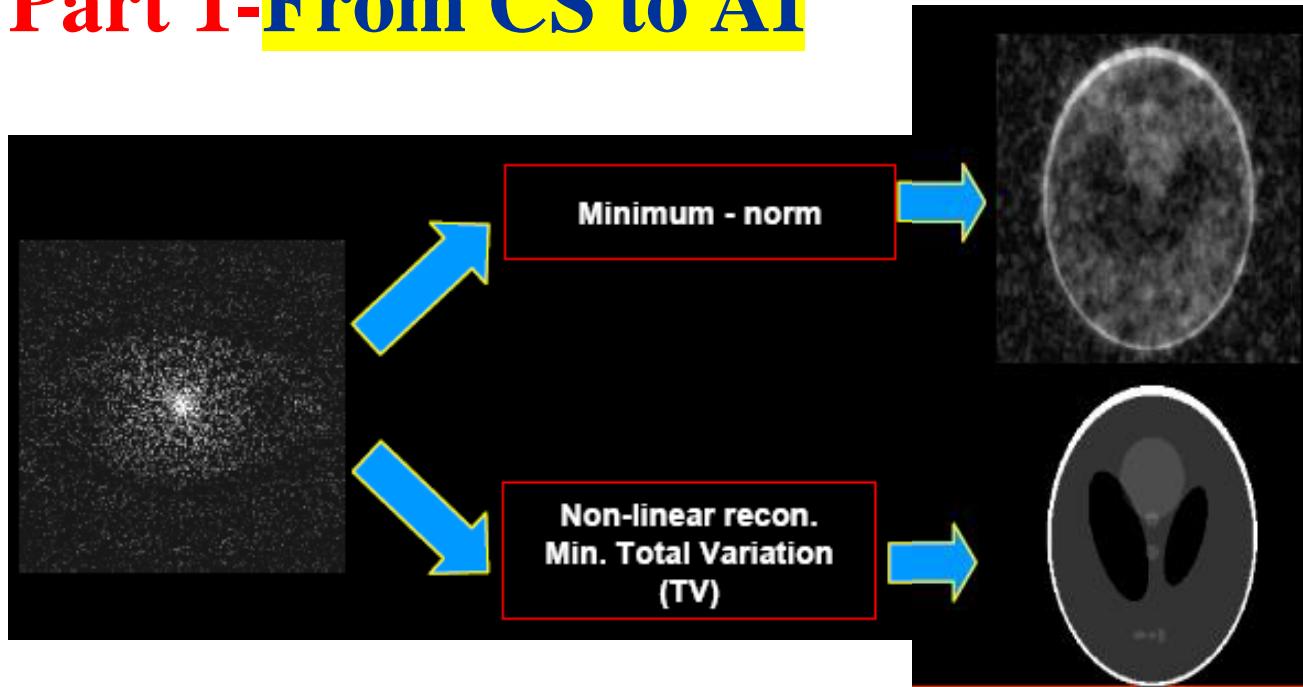
Part 1-From CS to AI



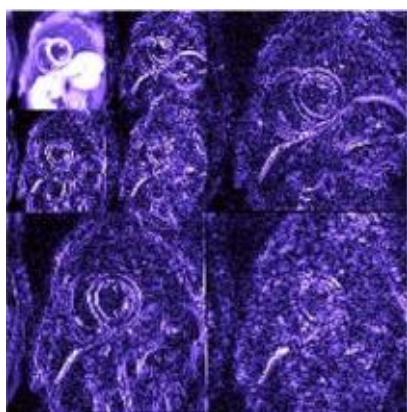
Fast MRI Techniques:

- ✓ **MR physics (1970's)**
 - Pulse sequence design
- ✓ **Hardware (2000's)**
 - Parallel imaging with phased array coils
- ✓ **Partial K-space reconstruction (past two decades)**
 - Modeling using priori knowledge, etc.

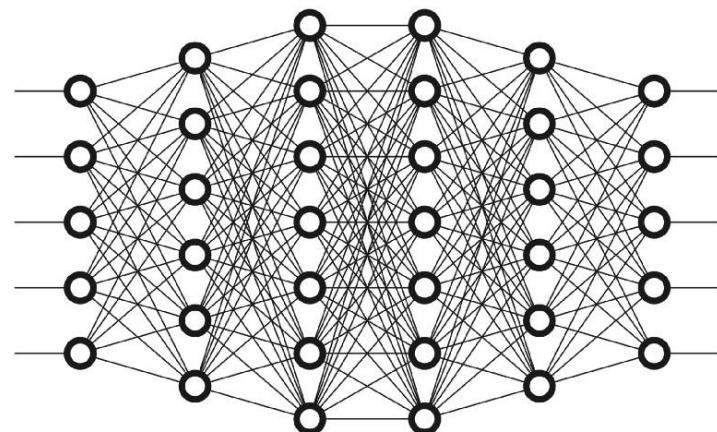
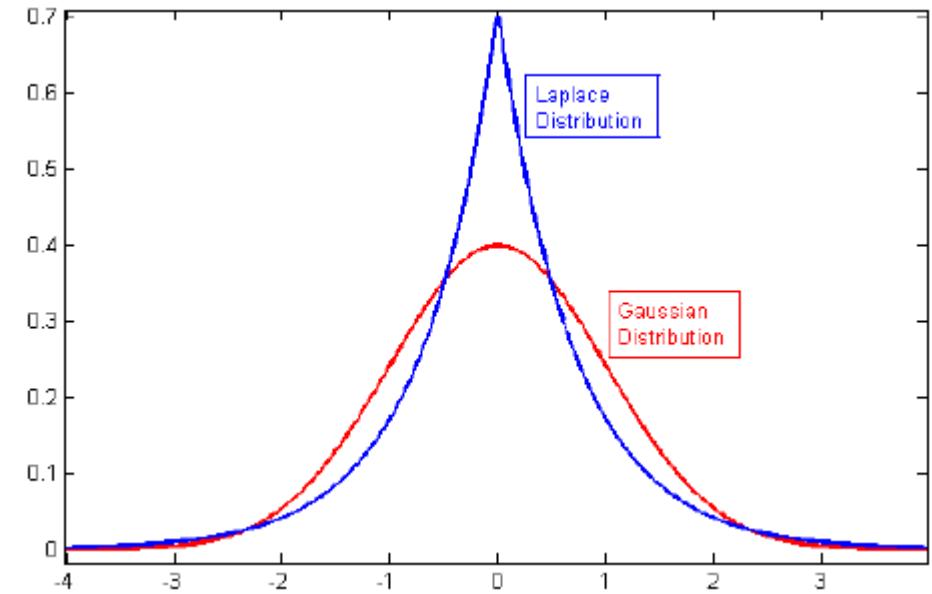
Part 1-From CS to AI



Sparse in Gradient



Sparse in Wavelet



From compressed sensing (**CS**) to Artificial intelligence (**AI**)

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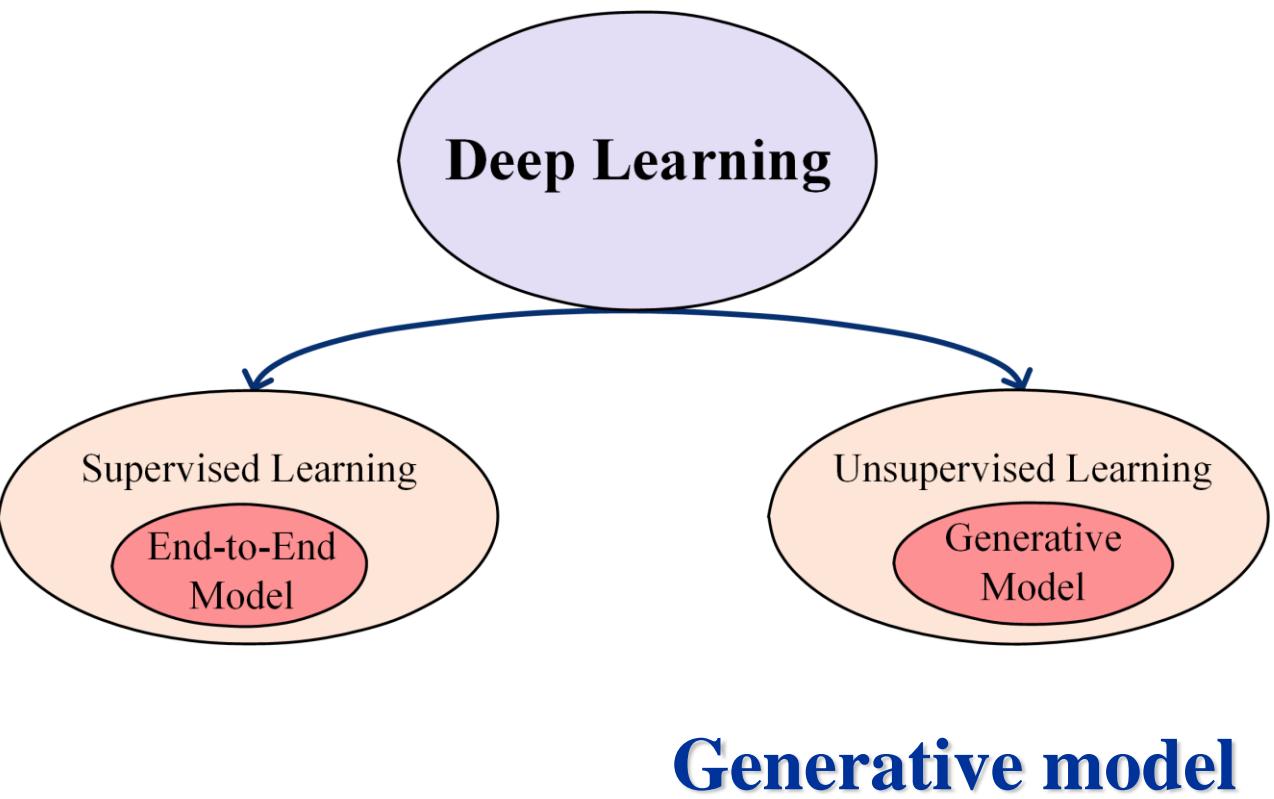
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Part 2.1-Five representatives of USL



- 01 Denoising autoencoding(DAE)
- 02 Variational Autoencoders (VAE)
- 03 Generative Adversarial Network (GAN)
- 04 PixelCNN
- 05 Generative Flow (Glow)

Part 2.1-Five representatives of USL

01

Denoising autoencoding(DAE)

02

Variational Autoencoders (VAE)

03

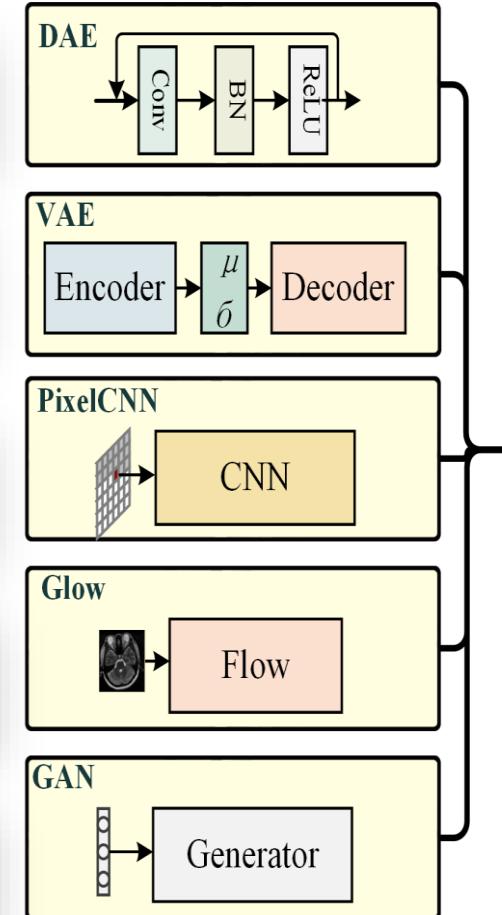
Generative Adversarial Network (GAN)

04

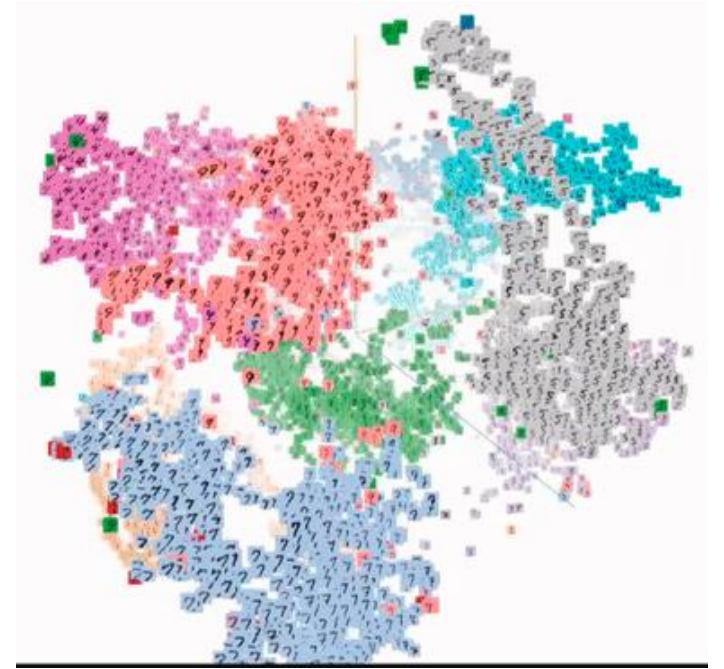
PixelCNN

05

Generative Flow (Glow)



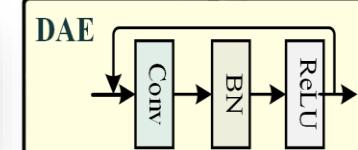
Data distribution $\log p(x)$



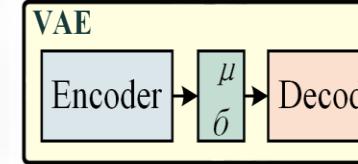
Part 2.1-Five representatives of USL

- 01
- 02
- 03
- 04
- 05

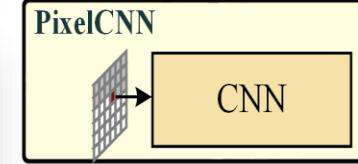
Denoising autoencoding(DAE)



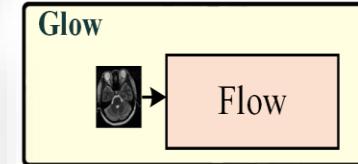
Variational Autoencoders (VAE)



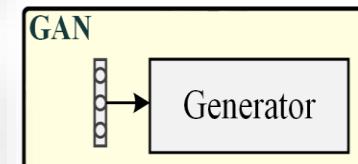
Generative Adversarial Network (GAN)



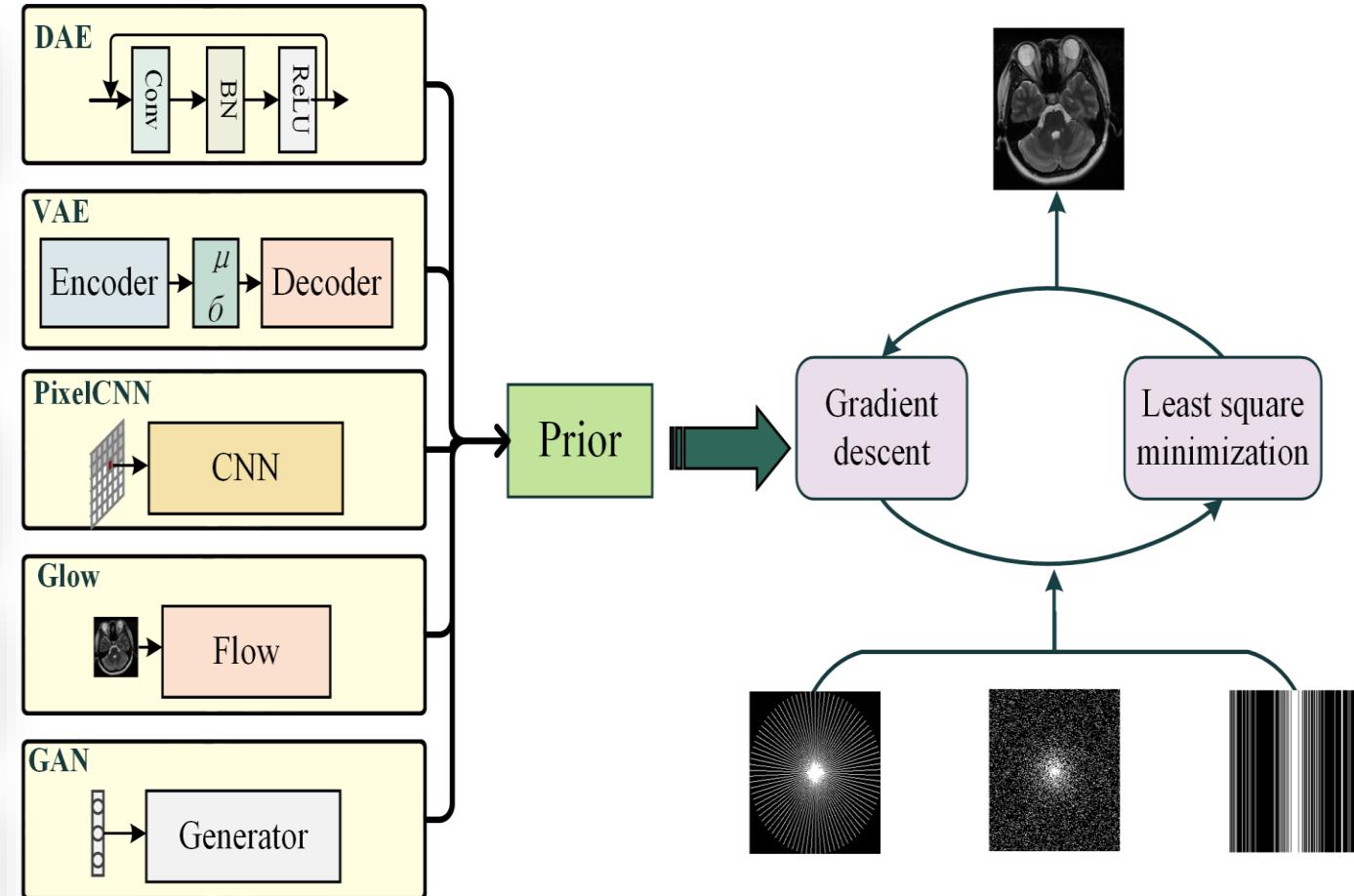
PixelCNN



Generative Flow (Glow)



POCS-like scheme for MRI Rec



Part 2.1-Five representatives of USL

01

Denoising autoencoding(DAE)

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Generative Flow (Glow)

POCS-like scheme for MRI Rec

$$\begin{cases} x^{k+1/2} = x^k - \alpha \nabla prior(x^k) & \text{Update on prior term} \\ x^{k+1} = \arg \min_x \|F_p x - y\|_2^2 + \lambda \|x - x^{k+1/2}\|_2^2 & \text{Update on data-consistency} \end{cases}$$

Algorithm 1: Unsupervised Learning for Reconstruction (USLearn)

Prior learning stage

Input: MR dataset: $x \in C^{n \times n}$

Output: Trained network model by learning $p(x)$

Iterative reconstruction stage

1: Initialization: $x^0 = F_p^H y$

2: For $k = 0, 1, 2, \dots, K$ do

3: Pre-process to get the corresponding network input $m^k = pre(x^k)$

4: Get gradient $\nabla_m prior(m)$ at m^k

5: Update $m^{k+1} = m^k + \alpha \nabla_m prior(m^k)$

6: Post-process $x^{k+1} = post(m^{k+1})$ for projection

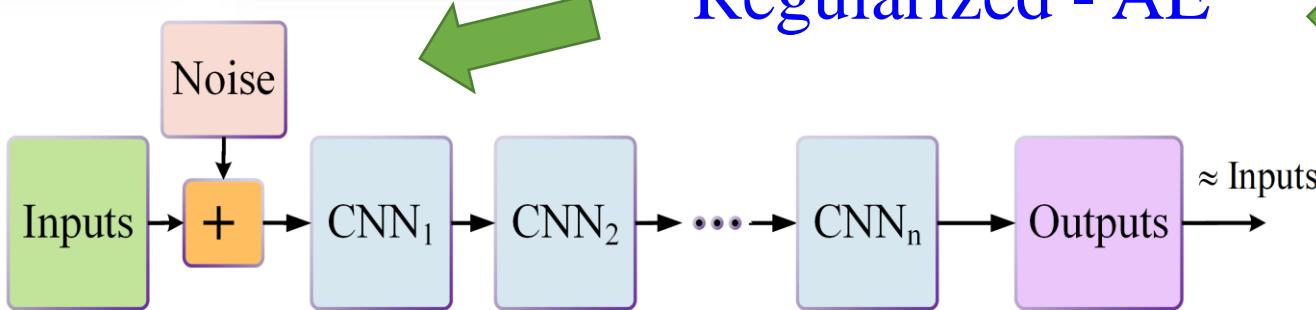
7: Projection x^{k+1} in Eq. (8)

8: Return x^k

Part 2.1-Five representatives of USL

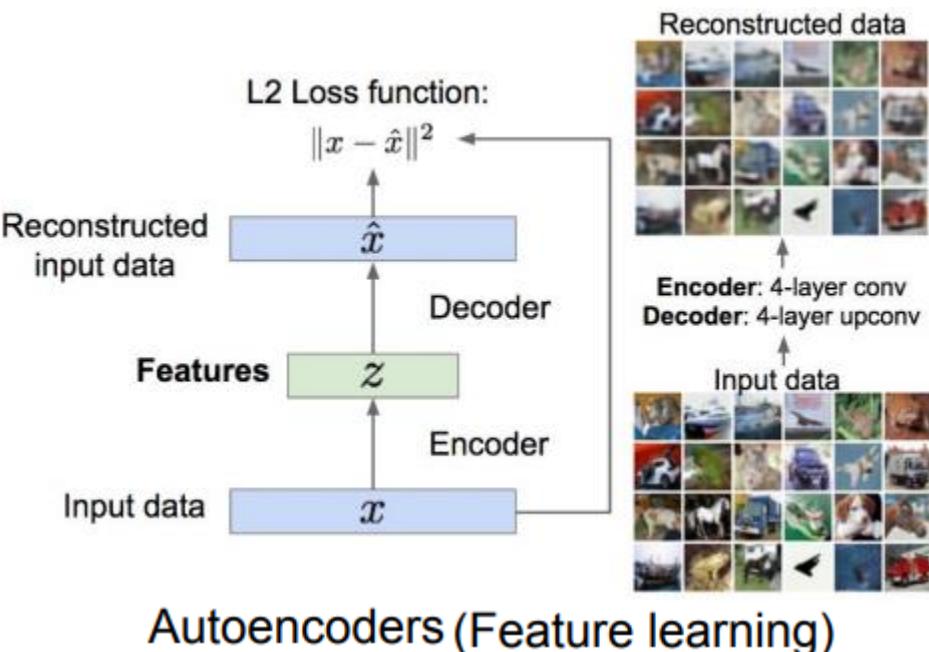
01

DAE



$$L_{DAE}(A) = E_{x, \mu} [\|A_\sigma(x + \mu) - x\|^2]$$

Regularized - AE



Autoencoders (Feature learning)

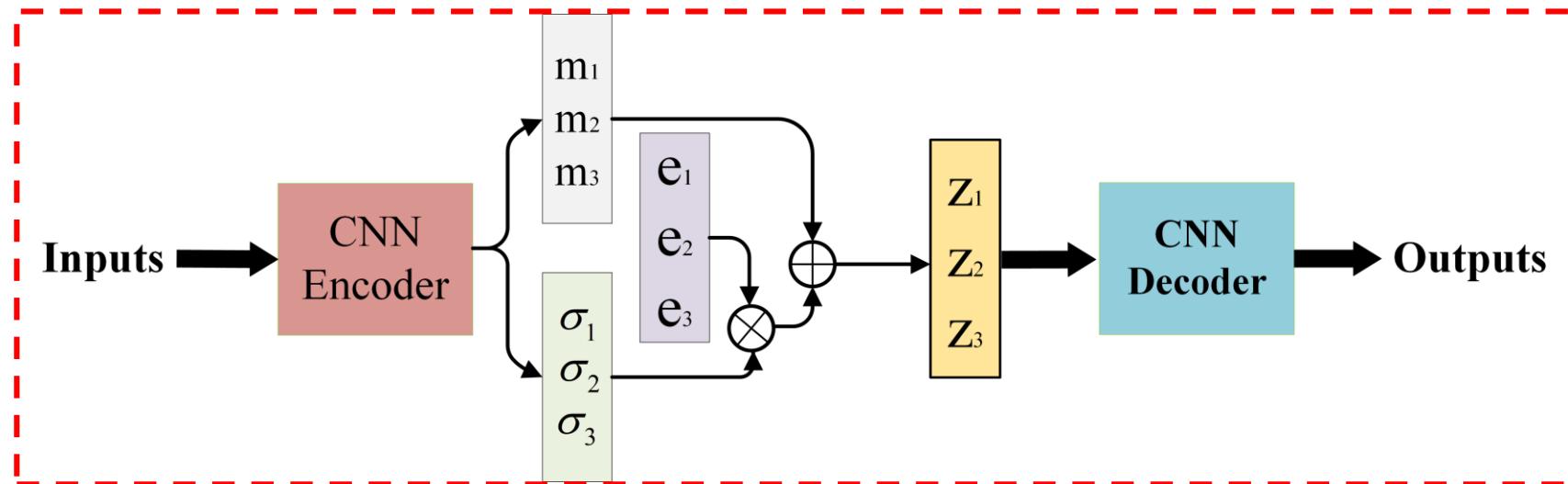
The relationship between DAE and generative model are not fully revealed by researchers in early period. DAE can be regarded as a generative model until Song et al. used denoising score matching and Langevin dynamics method to generate images

Part 2.1-Five representatives of USL

02

VAE

VAE realizes image generation by constraining the latent coding vectors to be Gaussian distribution.



$$p(x) = \int_Z p(x, z) dz = \int_Z p(x | z) p(z) dz$$

$$\log p(x) = E_{q(z|x)} \left[\log \frac{p(x, z)}{q(z|x)} \right] + D_{KL}[q(z|x) \| p(z|x)]$$

VAE is an approximate generative model, as it maximizes the lower bound of the data likelihood function.

Tezcan et al. used it to estimate the distribution of MR image patch as prior.

Part 2.1-Five representatives of USL

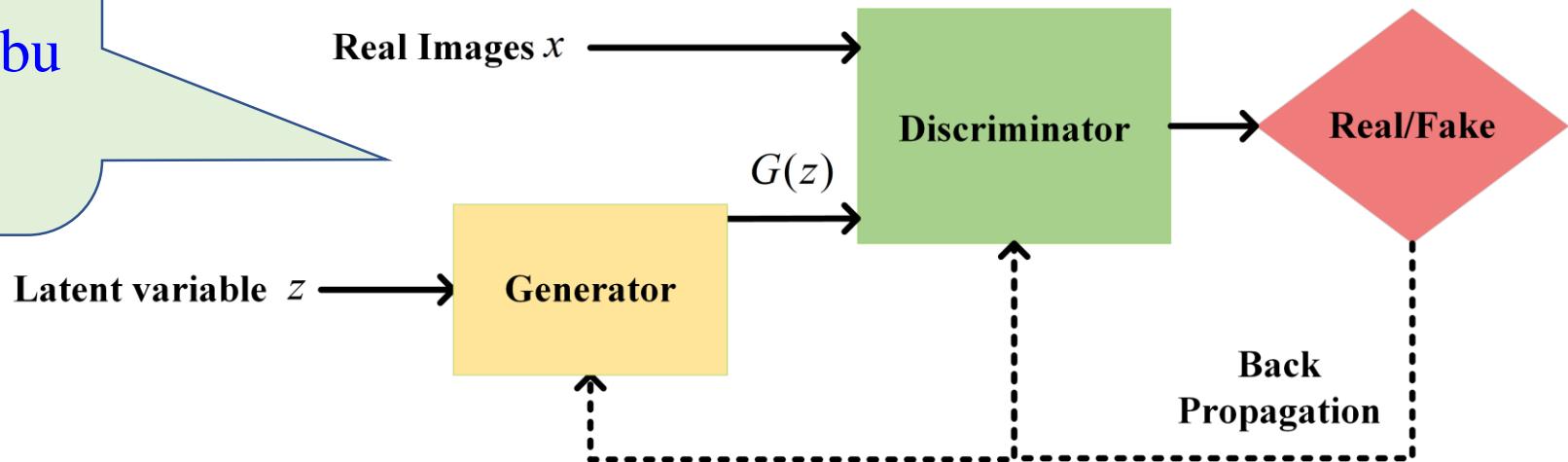
03

GAN

GAN gradually optimizes the generator and discriminator to generate image which has the same distribution as the real image

$$\min_G \max_D L(D, G) = E_{x \sim p_{data}} [\log D(x)] + E_{z \sim p_z(z)} [\log(1 - D(G(z)))]$$

$$y = Ax, \quad x = G(z)$$



A. Bora, A. Jalal, E. Price, A. Dimakis, Compressed sensing using generative models, *ICML* 2017.

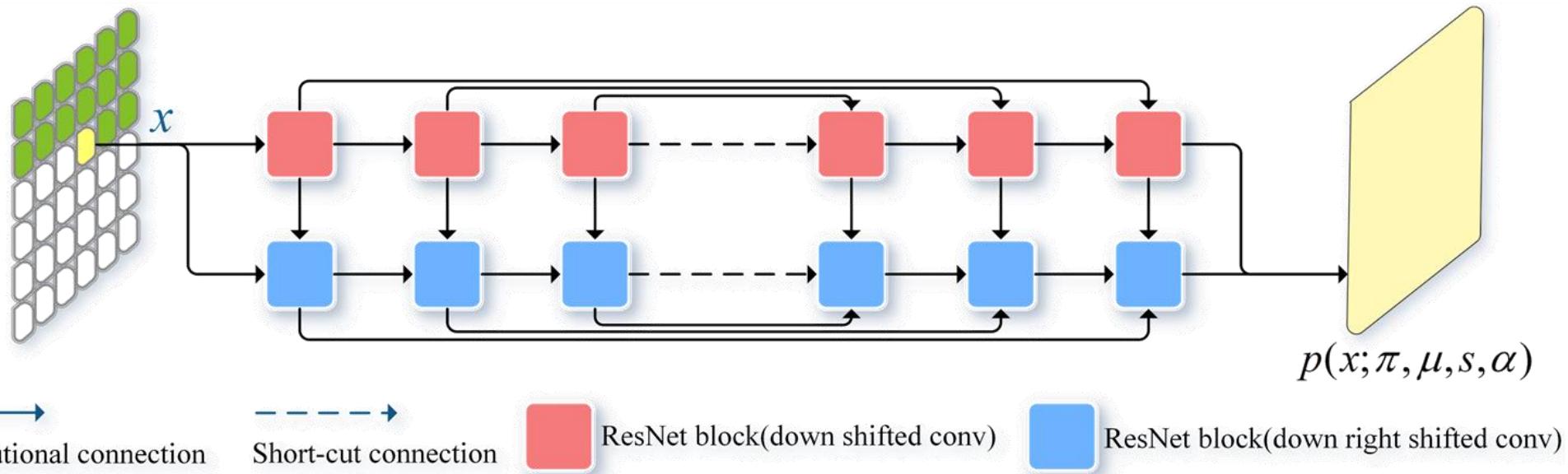
V. Shah, C. Hegde, Solving linear inverse problems using GAN priors: An algorithm with provable guarantees, 2018.

Part 2.1-Five representatives of USL

04

PixelCNN

The autoregressive model optimizes the explicit likelihood function through chain rule

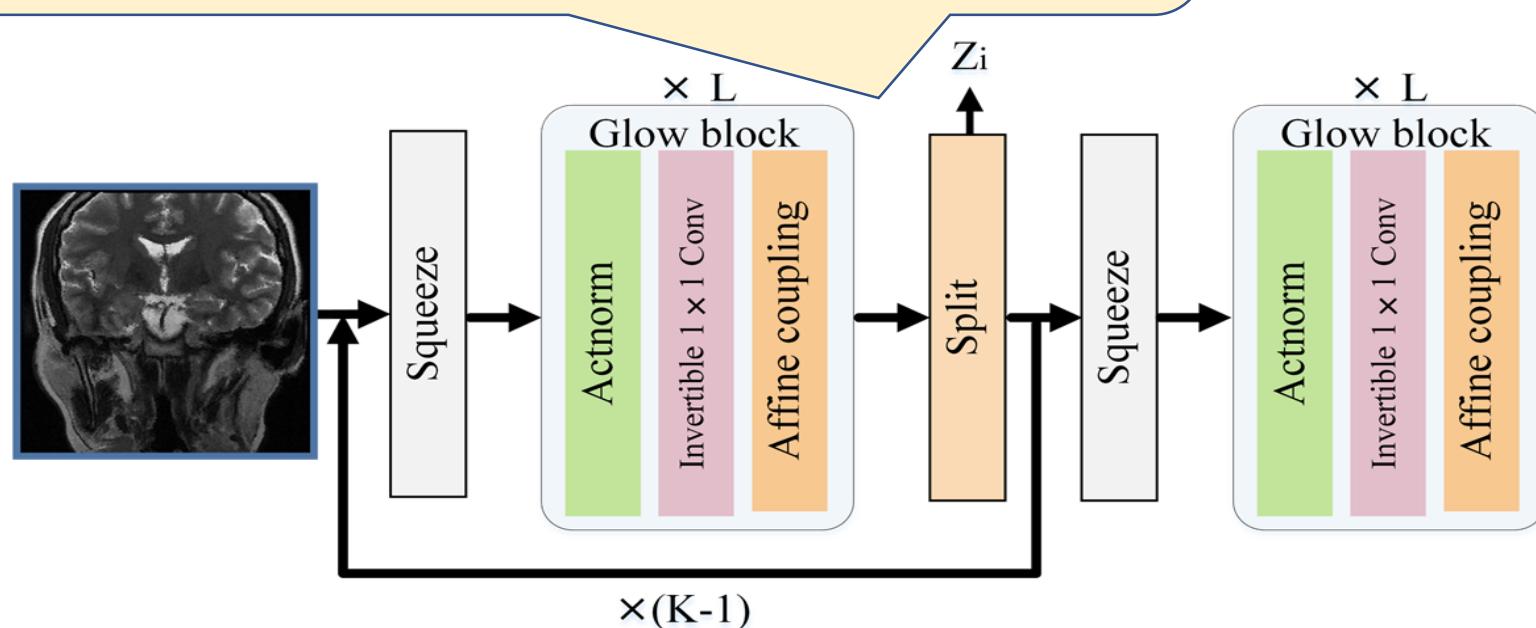


Part 2.1-Five representatives of USL

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Generative Flow (Glow)

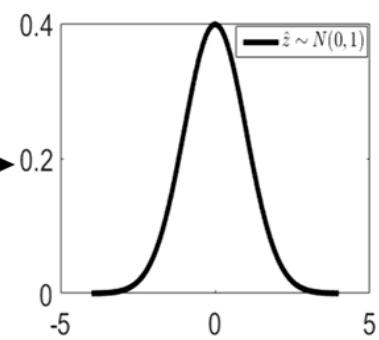
By designing a chain of invertible transformations with Jacobian determinants, flow-based generative models map points from the simple distribution to a complex one.



$$p_{\theta}(x) = p_z(z) |\partial z / \partial x|$$

$$\log p_{\theta}(x) = \log p_z(z) + \sum_{i=1}^L \log |\partial h_i / \partial h_{i-1}|$$

$$x \xleftrightarrow{F_1} h_1 \xleftrightarrow{F_2} h_2 \xleftrightarrow{F_3} \cdots \xleftrightarrow{F_L} z$$



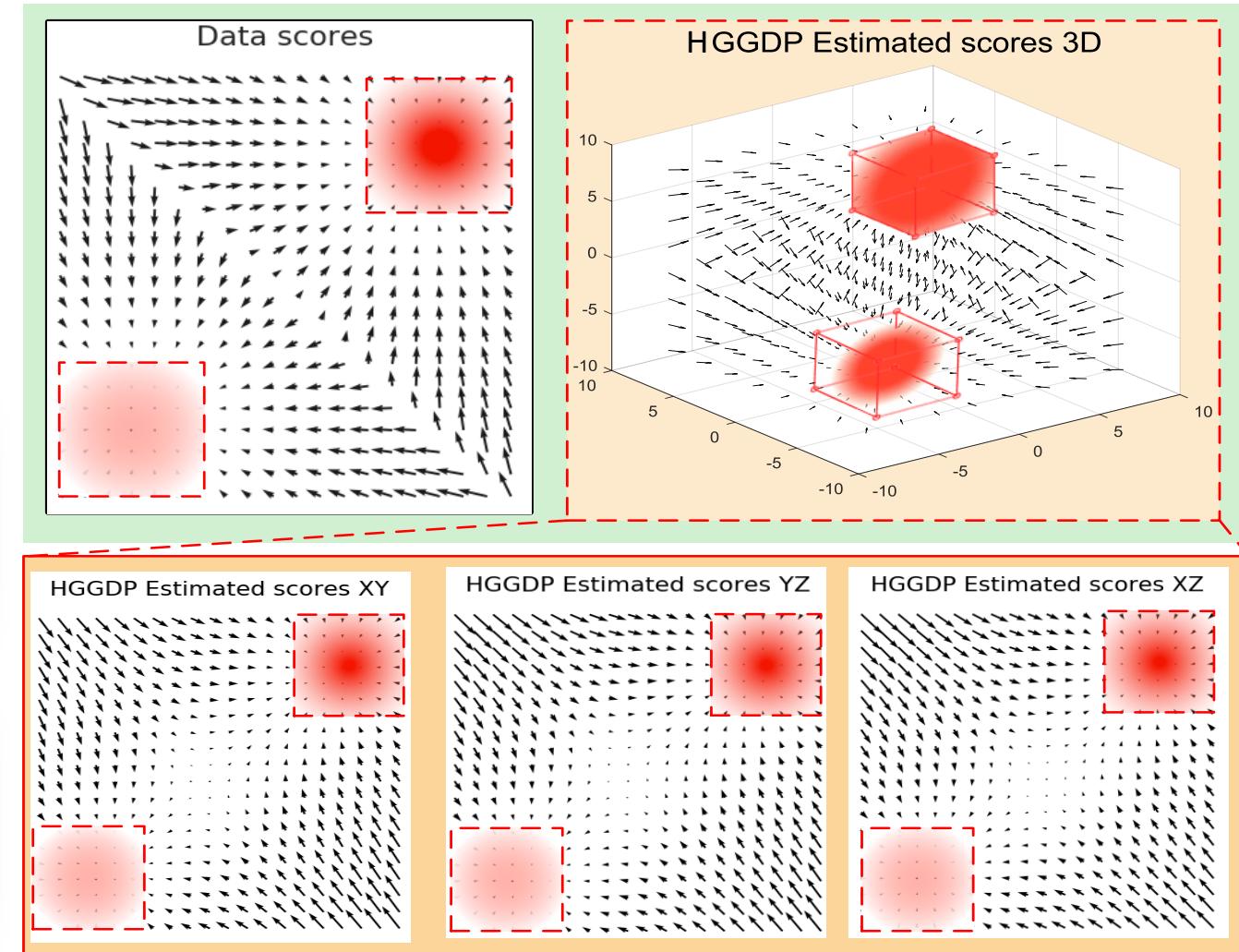
Part 2.2-Underlying ideas for improvements

01

How to estimate $\nabla_x \log p_{data}(x)$?

Learning prior density in higher-dimensional space

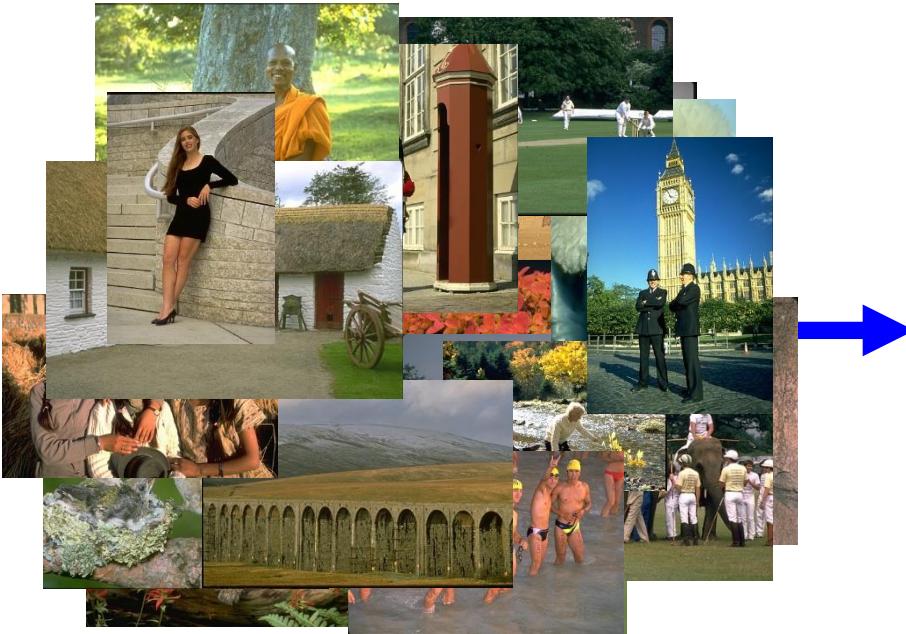
With variable X , not with x itself



Part 2.2-Underlying ideas for improvements

02

Prior knowledge across modality?

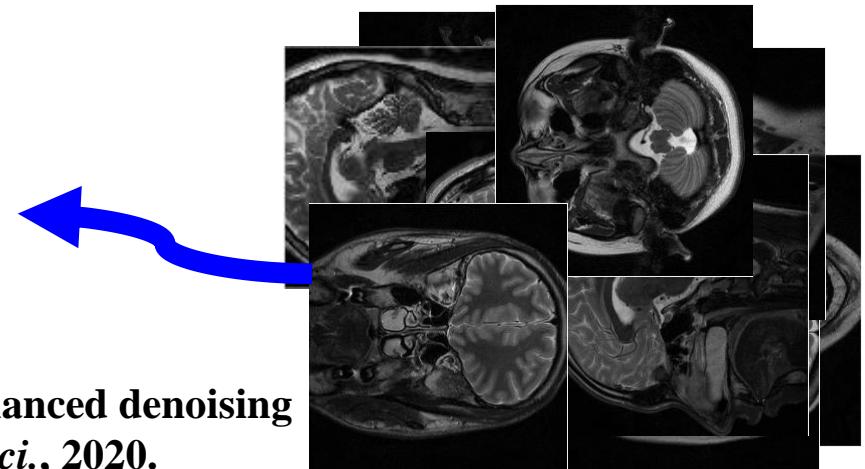
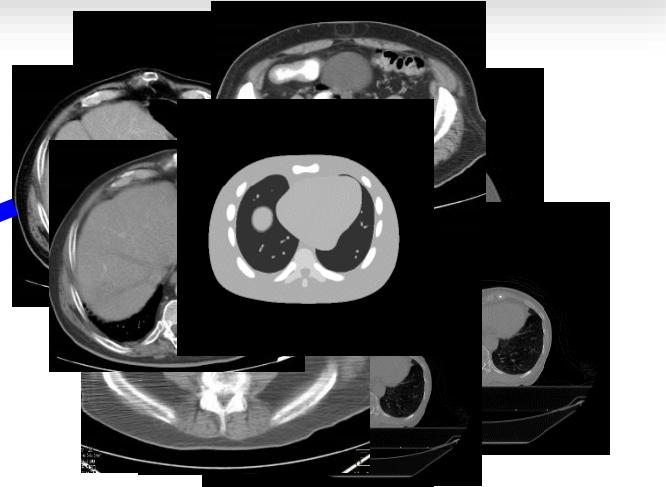


Prior learned from different modalities for CT recon

CT dataset	$p = 0.8$	47.47/0.9909
DIV2K dataset	$p = 1$	47.44/0.9908
	$p = 1.5$	47.18/0.9902
	$p = 2$	46.69/0.9888
MRI dataset	$p = 0.8$	47.54/0.9908
	$p = 1$	47.52/0.9907
	$p = 1.5$	47.24/0.9901
	$p = 2$	46.71/0.9887
	$p = 0.8$	46.69/0.9890
	$p = 1$	46.65/0.9889
	$p = 1.5$	46.41/0.9882
	$p = 2$	45.82/0.9863

Learning prior density in different modality

With variable z , not with x itself



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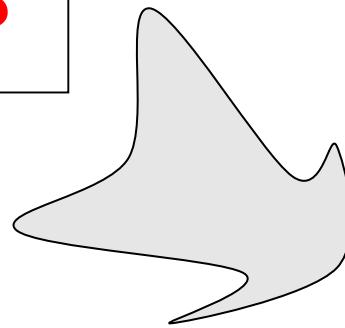
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Part 3.1-USL from DAE to DSM

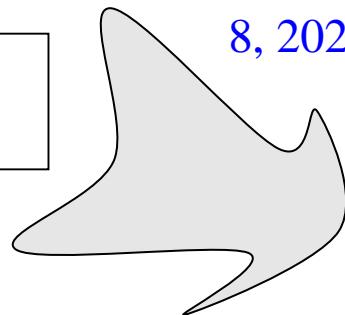
Q. Liu, Q. Yang, H. Cheng, S. Wang, M. Zhang, D. Liang, Highly undersampled magnetic resonance imaging reconstruction using autoencoding priors, *Magn. Reson. Med.*, vol. 83, no. 1, pp. 322-336, 2020.

DAEP



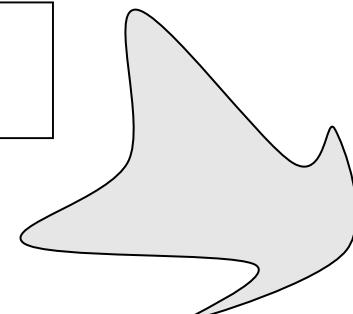
DAE

DMSP



S. Wang, J. Lv, Z. He, D. Liang, Y. Chen, M. Zhang, Q. Liu, Denoising auto-encoding priors in undecimated wavelet domain for MR image reconstruction, *Neurocomputing*, vol.437, pp.325-338, 2021.

DSM



M. Zhang, M. Li, J. Zhou, Y. Zhu, S. Wang, D. Liang, Y. Chen, Q. Liu. High-dimensional embedding network derived prior for compressive sensing MRI reconstruction, *Med. Image Anal.*, vol. 64, 101717, 2020.

DMSP

C. Quan, J. Zhou, Y. Zhu, Y. Chen, S. Wang, D. Liang, Q. Liu, Homotopic gradients of generative density priors for MR image reconstruction, *IEEE Trans. Med. Imag.*, 2021.

DSM

Generative model

DAE Prior

DAE is trained by minimizing the following objective function:

$$L_{DAE}(A) = E_{x, \mu} [\|A_\sigma(x + \mu) - x\|^2]$$

The autoencoder error is proportional to the gradient of the log-likelihood of the smoothed density

$$A_\sigma(x) = x + \sigma^2 \nabla \log[g_\sigma * p](x)$$

where $p(x)$ denotes the data density. $*$ represents the convolutional operator.

$$R(x) = \|A_\sigma(x) - x\|^2 = \|\sigma^2 \nabla \log[g_\sigma * p](x)\|^2$$

Regularization term

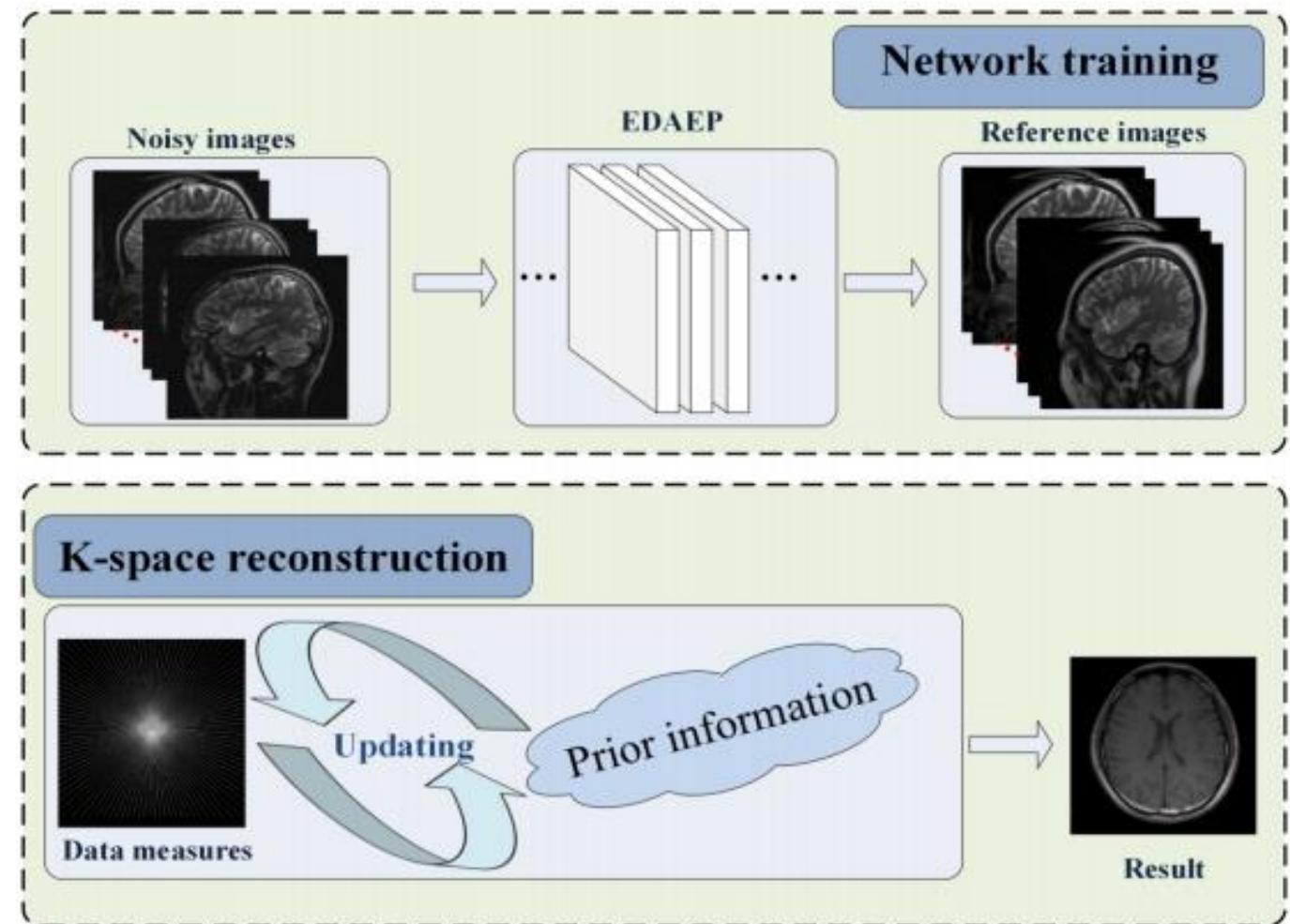
Algorithm overview

- Multi-channel learning scheme (self-copy)

EDAEPreC

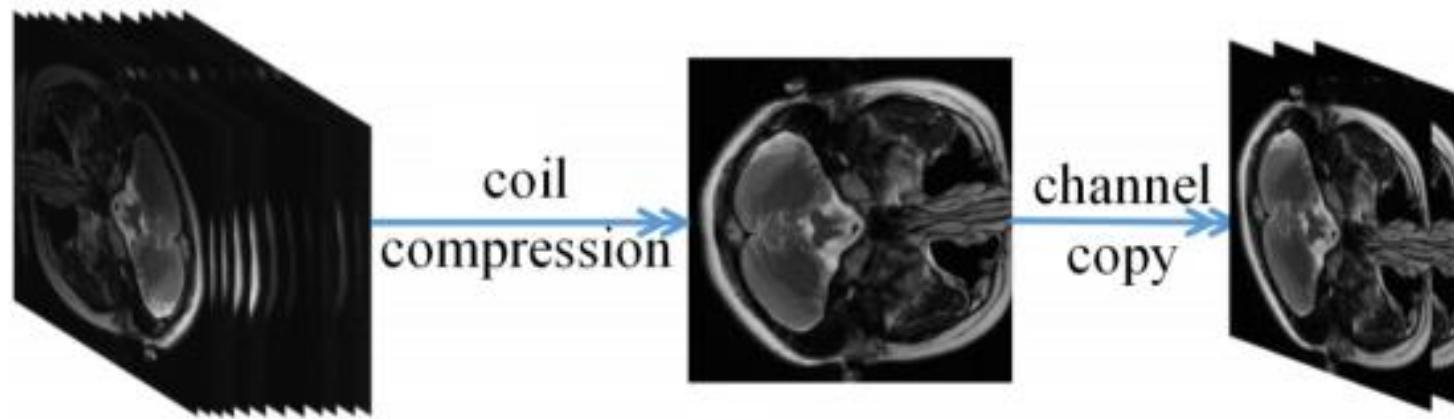
Training stage:
 $\{X = [x, x, x]\}$

Testing stage:
 $X^k = [x^k, x^k, x^k]$



Algorithm overview

- Multi-channel learning scheme (self-copy)



Schematic illustration of generating the three-channel training data.

Mathematical model for MRI Recon is:

EDAEPR
e

$$\underset{x}{\text{Min}} \frac{1}{2} \|X - A_{\sigma_{\eta_1}}(X)\|^2 + \frac{1}{2} \|X - A_{\sigma_{\eta_2}}(X)\|^2 + \nu \|F_p x - f\|^2$$

We convert the input of EDAEP from $C^{m \times n \times 3}$ space into $R^{m \times n \times 6}$ space.

From DAEP to Score-based generative model

Deep mean-shift prior (DMSP):

$$\begin{aligned}\nabla \text{prior}(x) &= \nabla \log \int g_\sigma(\eta) p(x + \eta) d\eta \\ &= [(A_\sigma(x) - x)] / \sigma^2\end{aligned}$$

Denoising score matching (DSM):

$$S(x) \rightarrow \nabla \log p_\sigma(x)$$

Theorem 1. The DAE loss

$$L_{DAE}(A) = E_{x \sim p, \eta \sim g_\sigma} [\|A(x + \eta) - x\|^2]$$

and the DSM loss

$$L_{DSM}(S) = E_{p_\sigma} [\|S(x) - \nabla \log p_\sigma(x)\|^2]$$

with $S(x) = \frac{A(x) - x}{\sigma^2}$

are equivalent up to a term that does not depend on A or S .

Score-based generative model

Prior learning stage:

$$p_\sigma(\tilde{x} | x) = N(\tilde{x} | x, \sigma^2 I)$$

$$\nabla_{\tilde{x}} \log p_\sigma(\tilde{x} | x) = -(\tilde{x} - x) / \sigma^2$$

$$\begin{aligned}\ell(\theta; \sigma) &\triangleq \frac{1}{2} E_{p_\sigma(x)} [\|S_\theta(x, \sigma) - \nabla_x \log p_\sigma(x)\|_2^2] \\ &= \frac{1}{2} E_{p_\sigma(\tilde{x}, x)} [\|S_\theta(\tilde{x}, \sigma) - \nabla_{\tilde{x}} \log p_\sigma(\tilde{x} | x)\|_2^2] + C \\ &= \frac{1}{2} E_{p_\sigma(\tilde{x}, x)} [\|S_\theta(\tilde{x}, \sigma) + (\tilde{x} - x) / \sigma^2\|_2^2] + C\end{aligned}$$

$$L(\theta; \{\sigma_i\}_{i=1}^I) \stackrel{\Delta}{=} \frac{1}{I} \sum_{i=1}^I \lambda(\sigma_i) \ell(\theta; \sigma_i)$$

Training DSM network S_θ for all $\{\sigma_i\}_{i=1}^I$

Beside of the statistical derivation to Eq. (8) [33], [34], we provide a new intuitive derivation for it. In fact, as stated in **Theorem 1**, we get $S_\theta(x, \sigma) = [A(x + \eta) - (x + \eta)] / \sigma^2$. On the other hand, as described in Fig. 3, if we denote $D_\theta(x, \sigma) = (x + \eta) - A(x + \eta)$ and $A(x + \eta) \rightarrow x$, then we get $S_\theta(x, \sigma) = -D_\theta(x, \sigma) / \sigma^2 \rightarrow -\eta / \sigma^2 = -(\tilde{x} - x) / \sigma^2$.

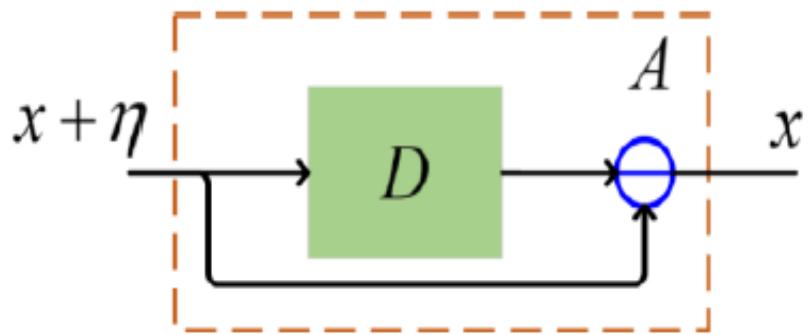


Fig. 3. Visual exhibition of the network A and D .

Score-based generative model

Iterative reconstruction stage: Annealed Langevin dynamics

Langevin dynamics

$$\begin{aligned}\tilde{x}_t &= \tilde{x}_{t-1} + \frac{\alpha_i}{2} \nabla_x \log p_{\sigma_i}(\tilde{x}_{t-1}) + \sqrt{\alpha_i} z_t \\ &= \tilde{x}_{t-1} + \frac{\alpha_i}{2} S_\theta(\tilde{x}_{t-1}, \sigma_i) + \sqrt{\alpha_i} z_t\end{aligned}$$

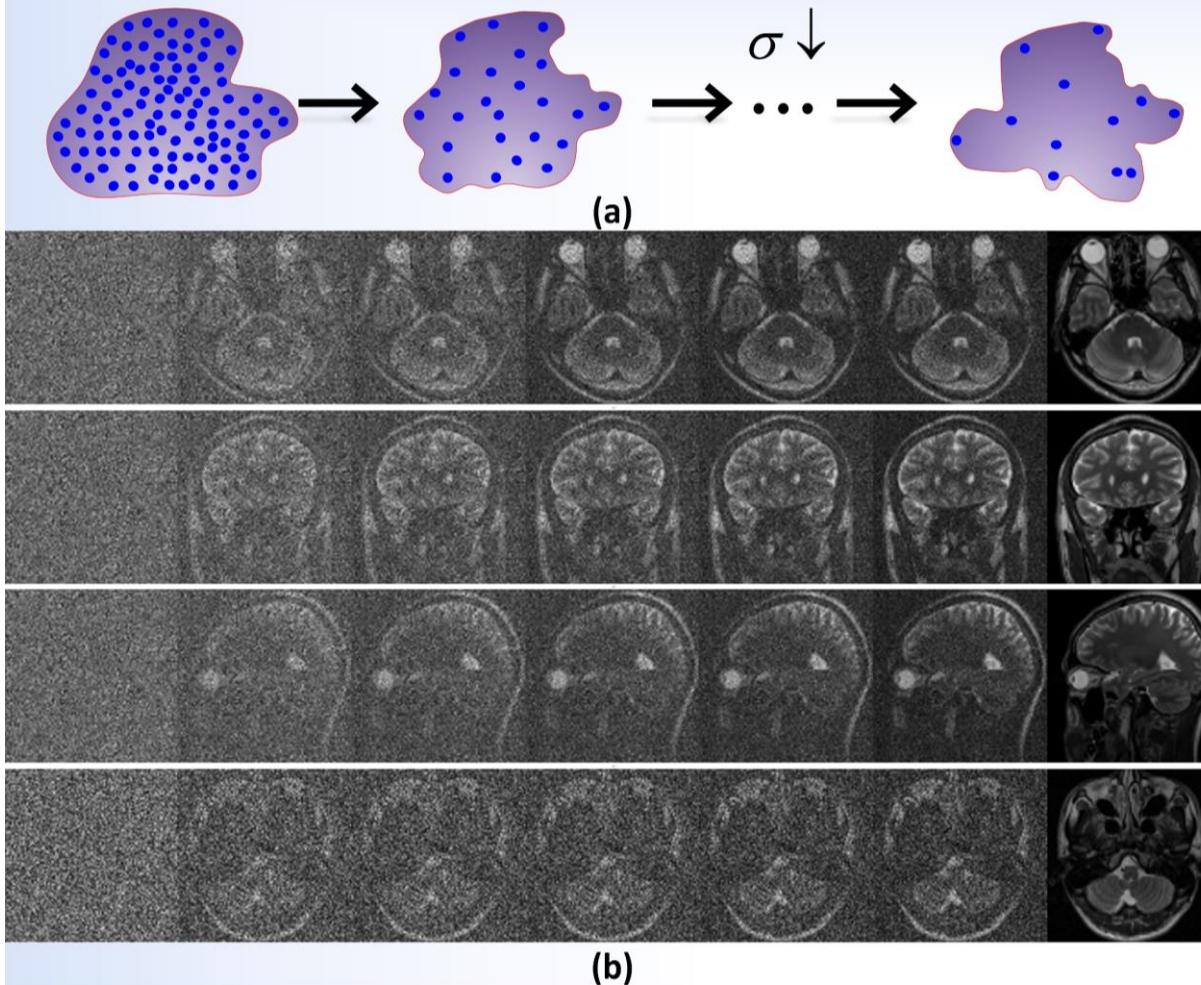
Algorithm 1 Annealed Langevin dynamics.

Require: $\{\sigma_i\}_{i=1}^L, \epsilon, T$.

```
1: Initialize  $\tilde{x}_0$ 
2: for  $i \leftarrow 1$  to  $L$  do
3:    $\alpha_i \leftarrow \epsilon \cdot \sigma_i^2 / \sigma_L^2$        $\triangleright \alpha_i$  is the step size.
4:   for  $t \leftarrow 1$  to  $T$  do
5:     Draw  $z_t \sim \mathcal{N}(0, I)$ 
6:      $\tilde{x}_t \leftarrow \tilde{x}_{t-1} + \frac{\alpha_i}{2} s_\theta(\tilde{x}_{t-1}, \sigma_i) + \sqrt{\alpha_i} z_t$ 
7:   end for
8:    $\tilde{x}_0 \leftarrow \tilde{x}_T$ 
9: end for
return  $\tilde{x}_T$ 
```

Iterative image generation

Annealed Langevin Dynamics



- (a) Conceptual diagram of the sampling on high-dimensional noisy data distribution with multi-view noise.
(b) Intermediate samples of annealed Langevin dynamics.

HGGDPRec

Iterative reconstruction stage

Algorithm 1 HGGDPRec

Training stage

Dataset: Multi- channel dataset: $X = \{X_1, X_2, X_3, \dots, X_N\}$

Outputs: Trained HGGDP $S_\theta(X, \sigma)$

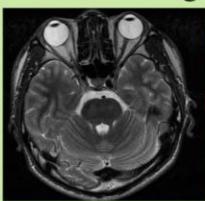
Reconstruction stage

Setting: $\sigma \in \{\sigma_i\}_{i=1}^I, \in, T$, and x^0

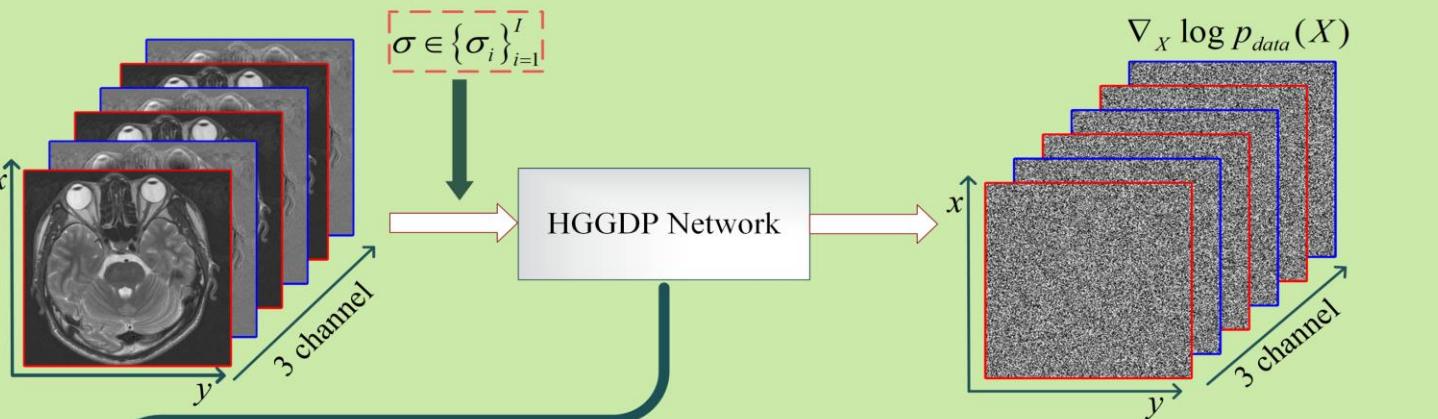
```
1: for  $i \leftarrow 1$  to  $I$  do (Outer loop)
2:    $\alpha_i = \epsilon \cdot \sigma_i^2 / \sigma_I^2$ 
3:   for  $t \leftarrow 1$  to  $T$  do (Inner loop)
4:     Draw  $z_t \sim N(0, 1)$  and  $X^{t-1} = \{x^{t-1}, x^{t-1}, \dots, x^{t-1}\}$ 
5:      $X^t = X^{t-1} + \frac{\alpha_i}{2} S_\theta(X^{t-1}, \sigma_i) + \sqrt{\alpha_i} z_t$ 
6:     Update  $x^t = \text{Mean}(X^t)$  and Eq. (17)
7:   end for
8:    $x^0 \leftarrow x^T$ 
9: end for
Return  $x^T$ 
```

Training

Reference image

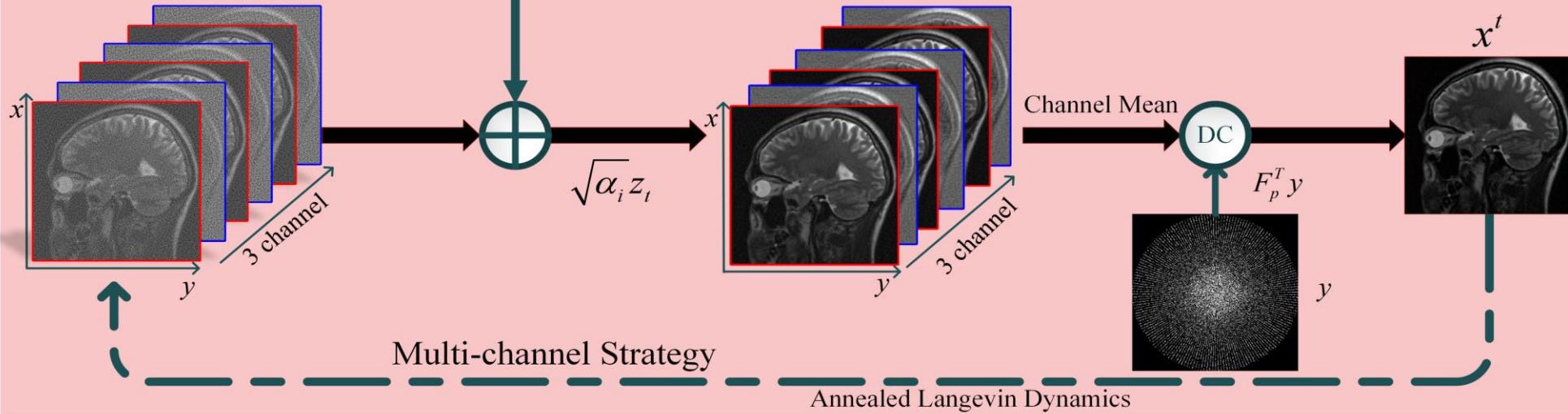


Multi-channel
Strategy



Reconstruction

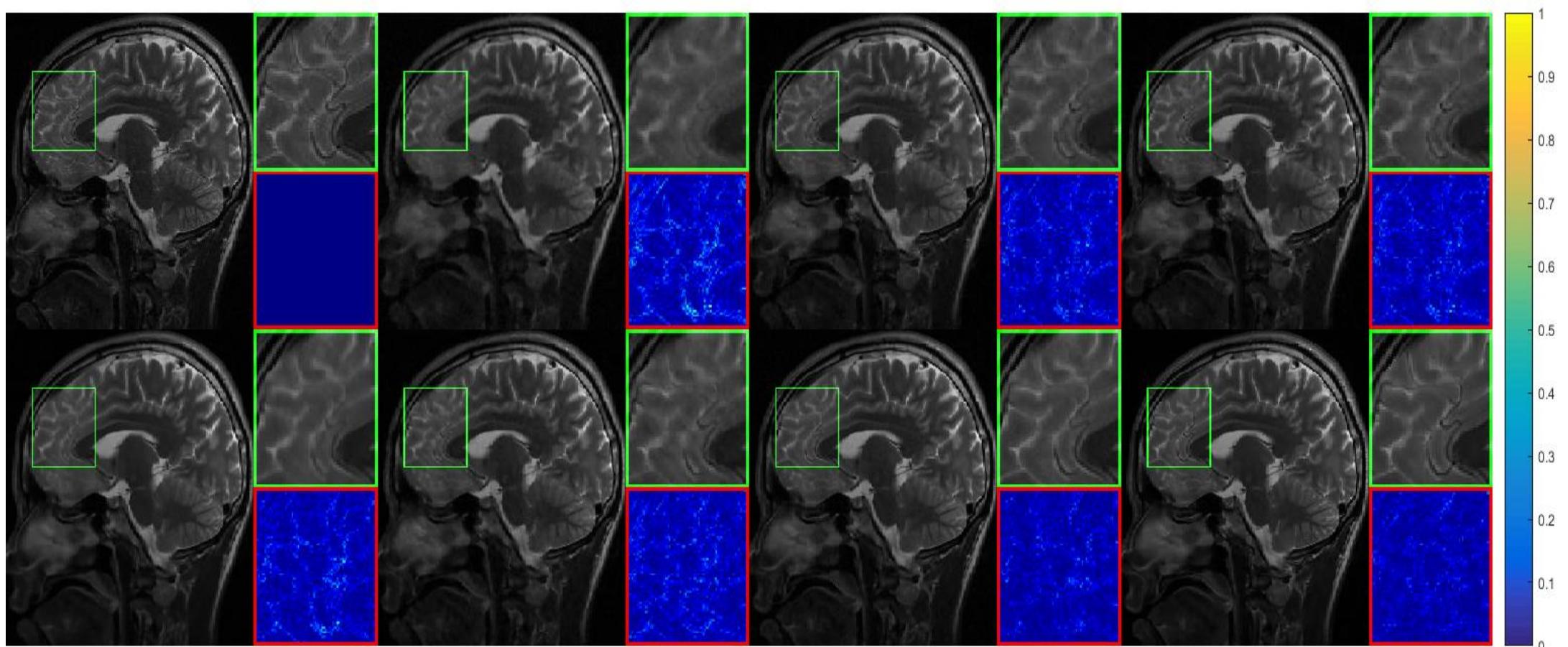
Initial Result x^{t-1}



HGGDPRec

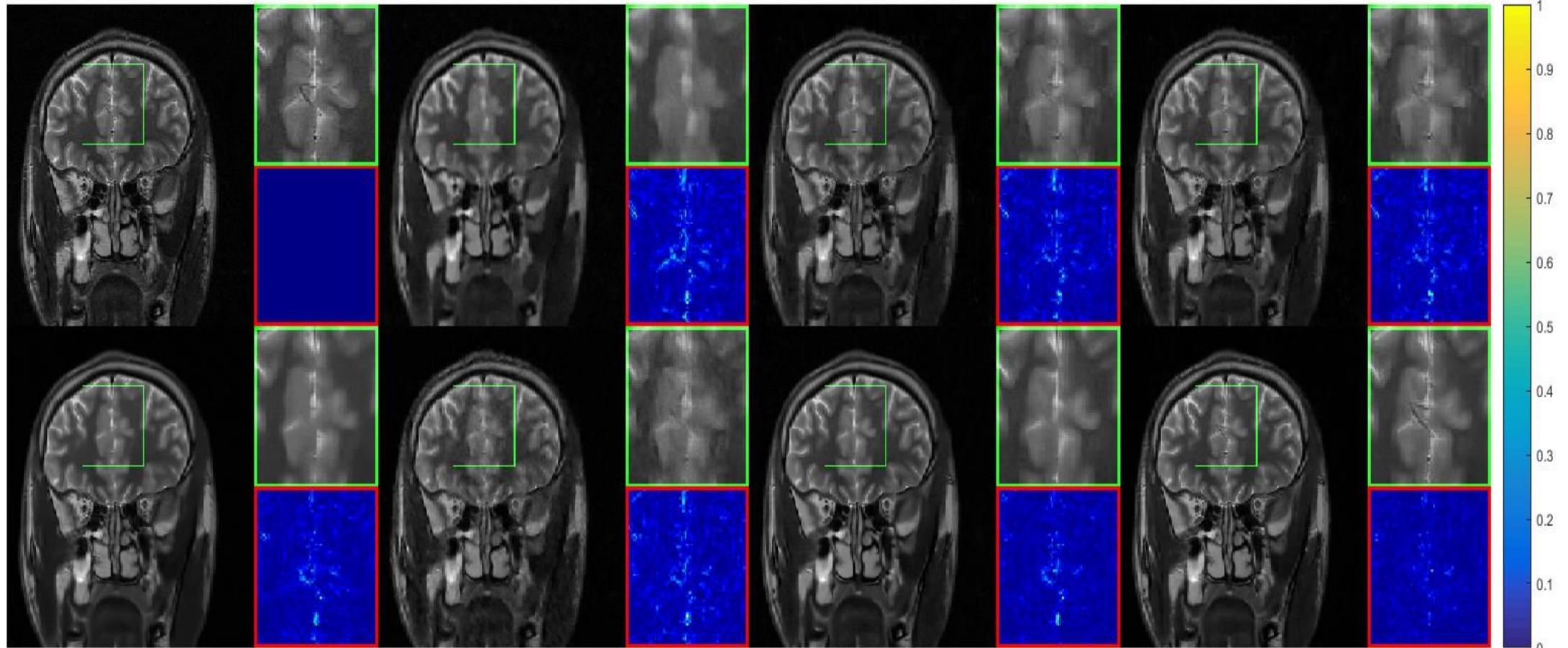
Pipeline of HGGDP training process for prior learning and HGGDPRec procedure for MRI reconstruction.

Experimental results



Reconstruction comparison on pseudo radial sampling at acceleration factor $R=6.7$. Top: Reference, reconstruction by DLMRI, PANO, FDLCP; Bottom: Reconstruction by NLR-CS, DC-CNN, EDAEPRRec, HGGDPRRec. Green and red boxes illustrate the zoom in results and error maps, respectively.

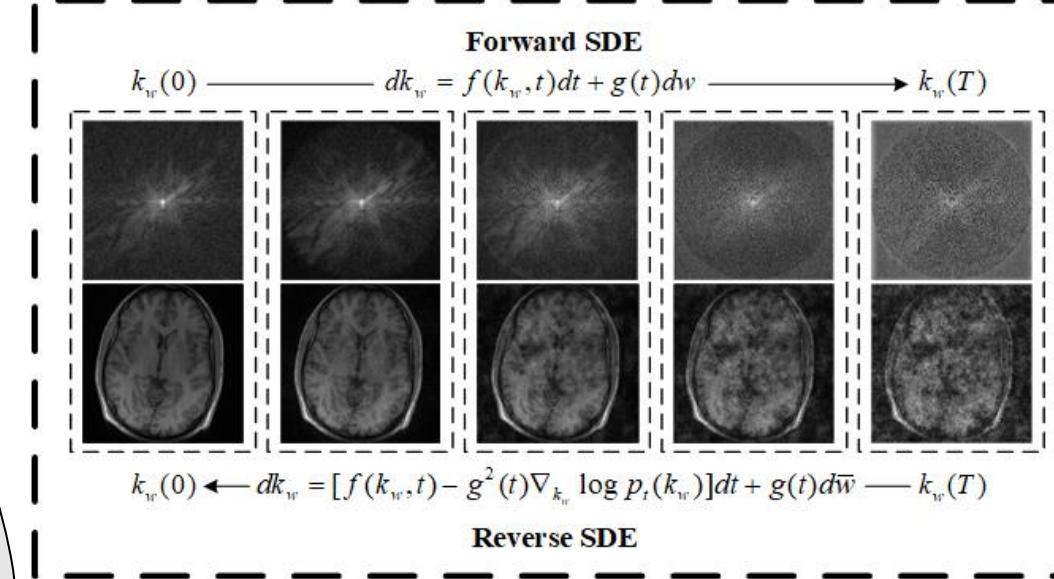
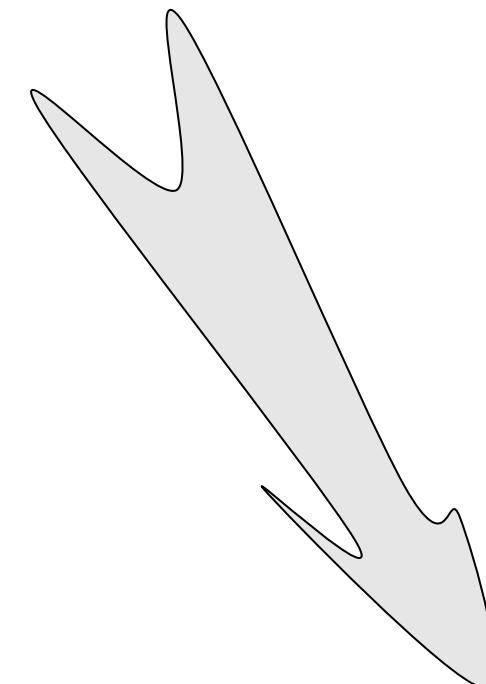
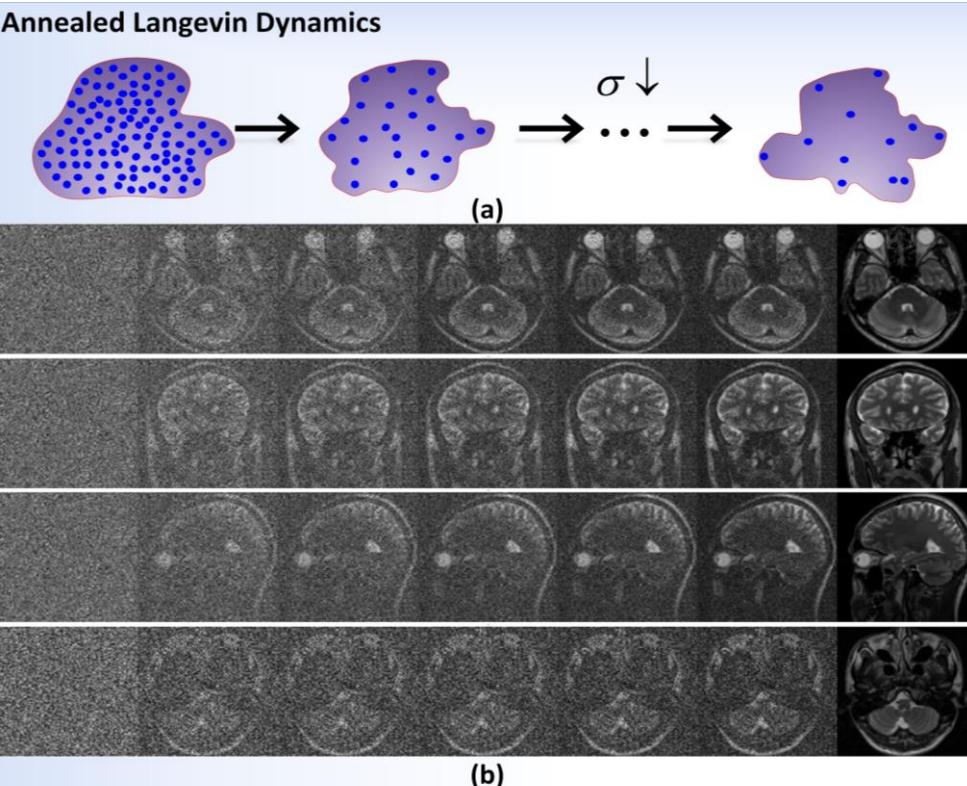
Experimental results



Reconstruction comparison on 2D Random sampling at acceleration factor $R=6.7$. Top: Reference, reconstruction by DLMRI, PANO, FDLCP; Bottom: Reconstruction by NLR-CS, DC-CNN, EDAEPRRec, HGGDPRRec. Green and red boxes illustrate the zoom in results and error maps, respectively.

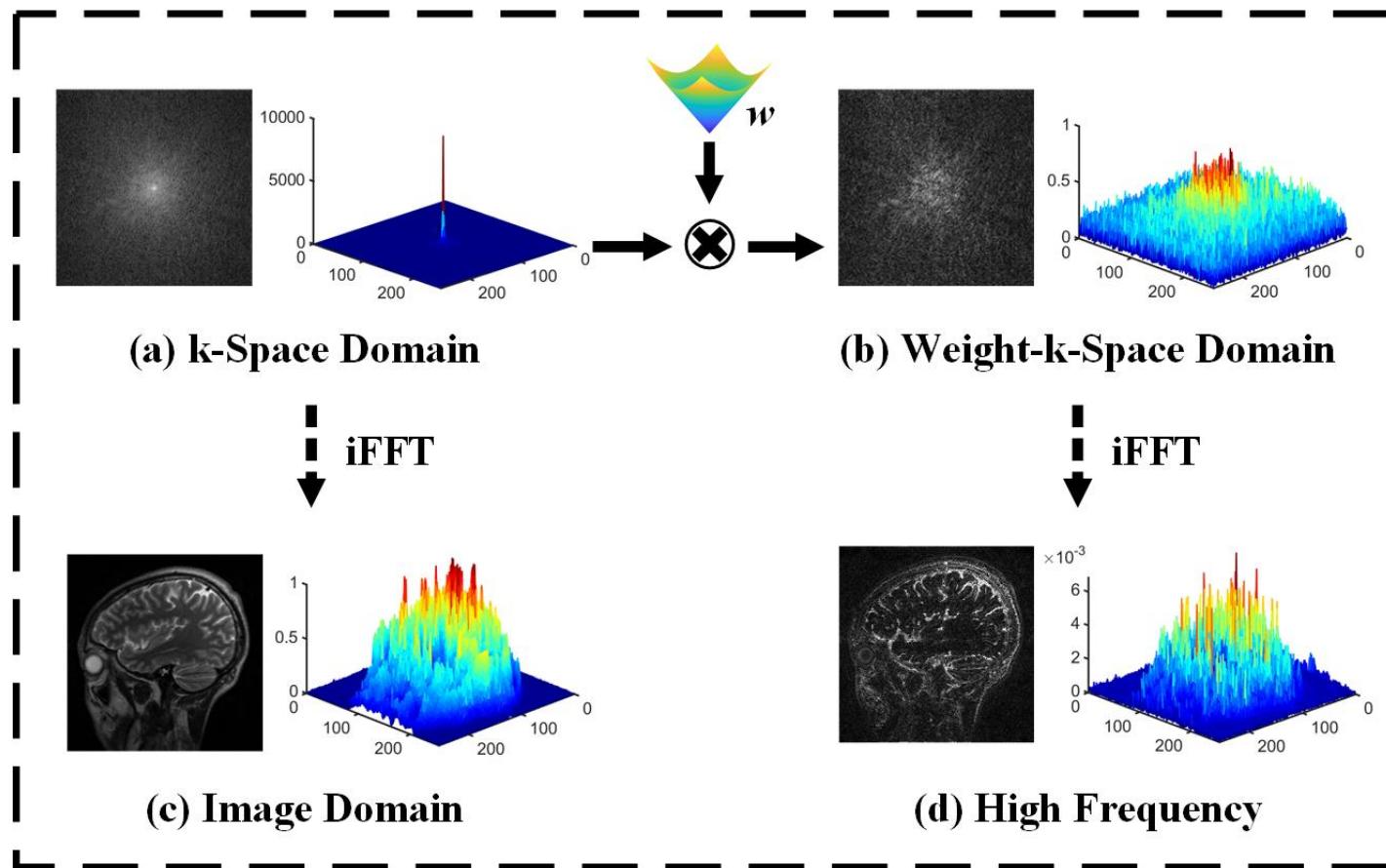
Part 3.2-DSM from image domain to k-space domain

Generative model in image domain



Generative model in k-space domain

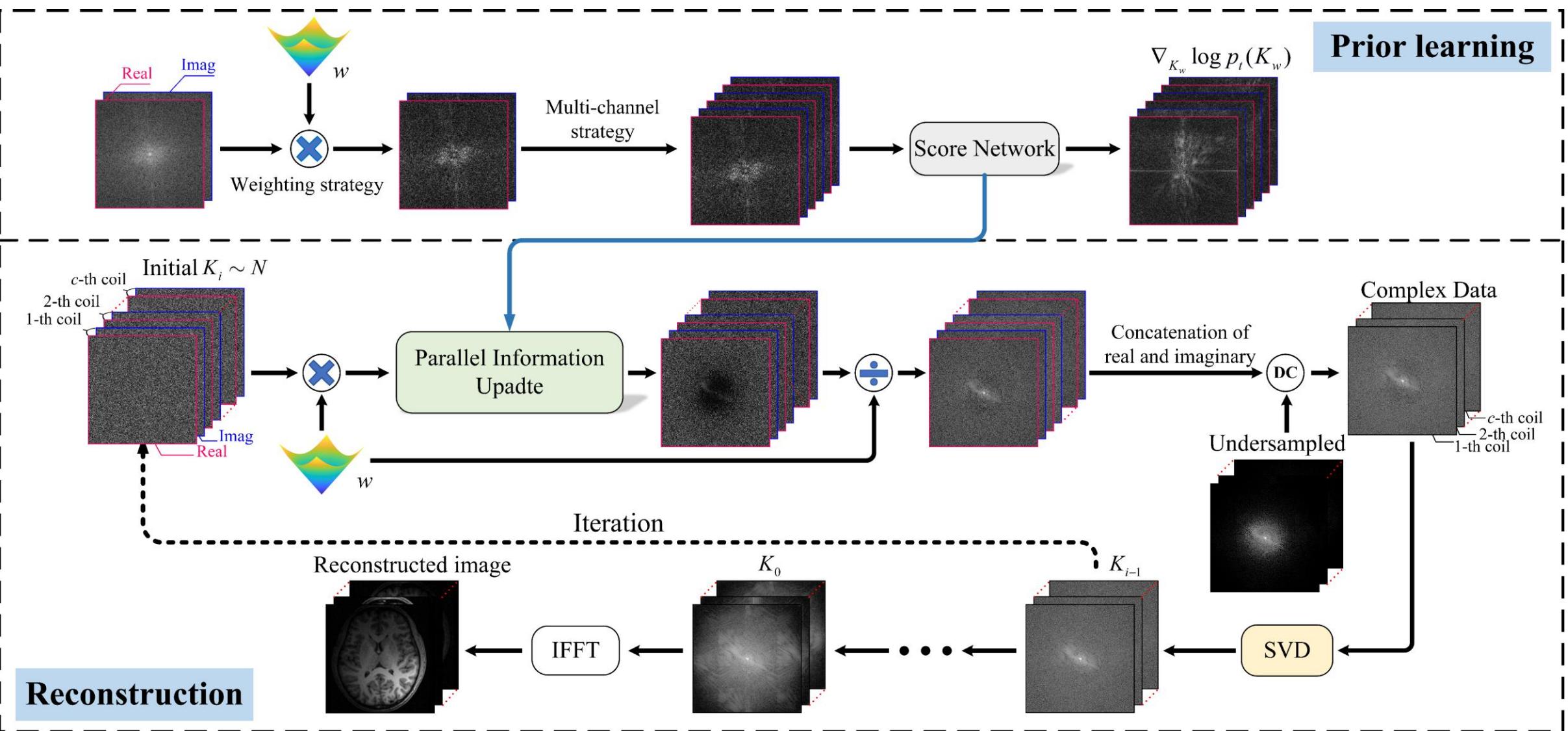
Algorithm overview



Visual comparison of the amplitude values in k-space domain and weight-k-space domain.

Prior learning in weighted k-space domain is more efficient !

Algorithm overview



Algorithm overview

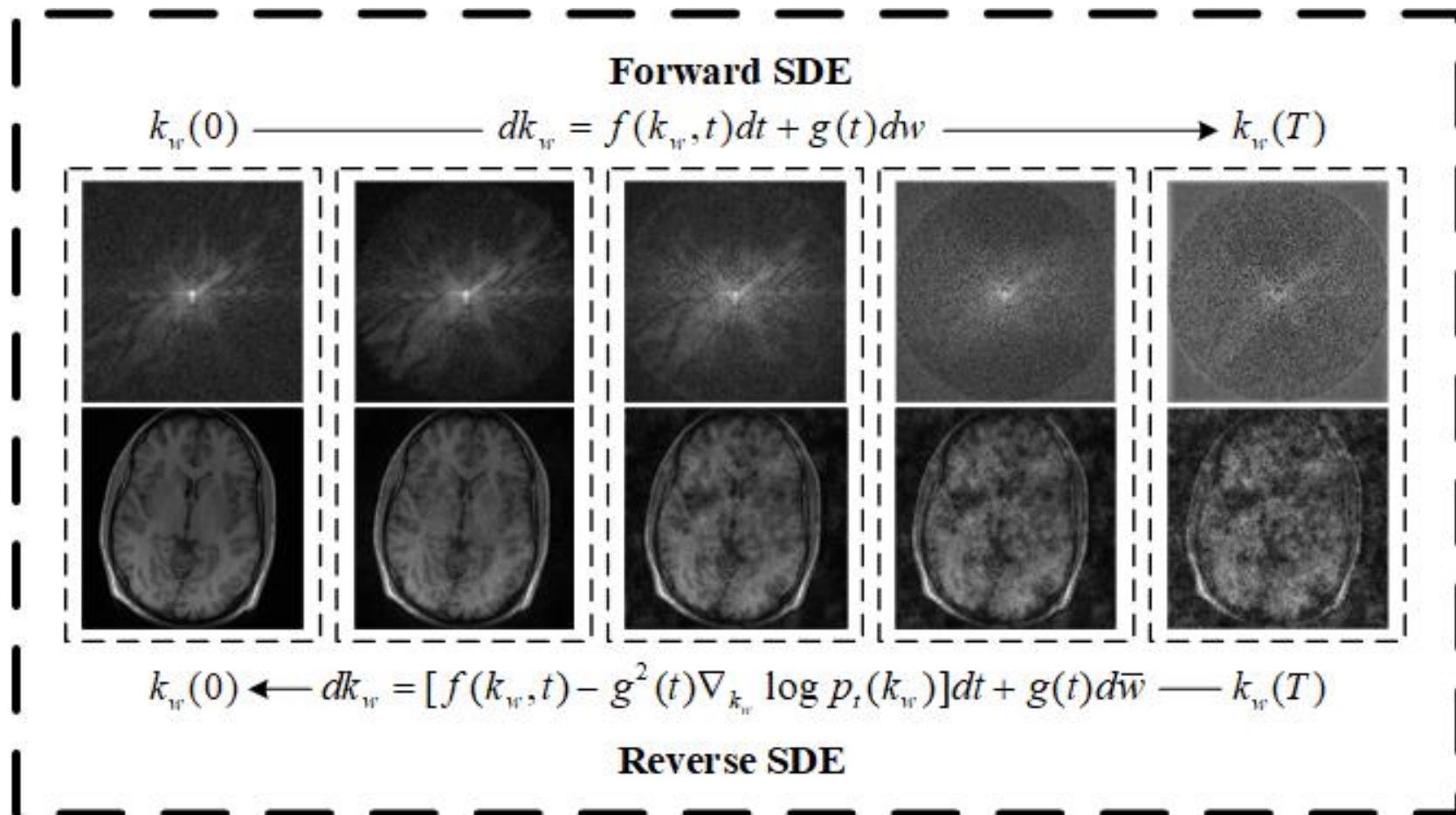
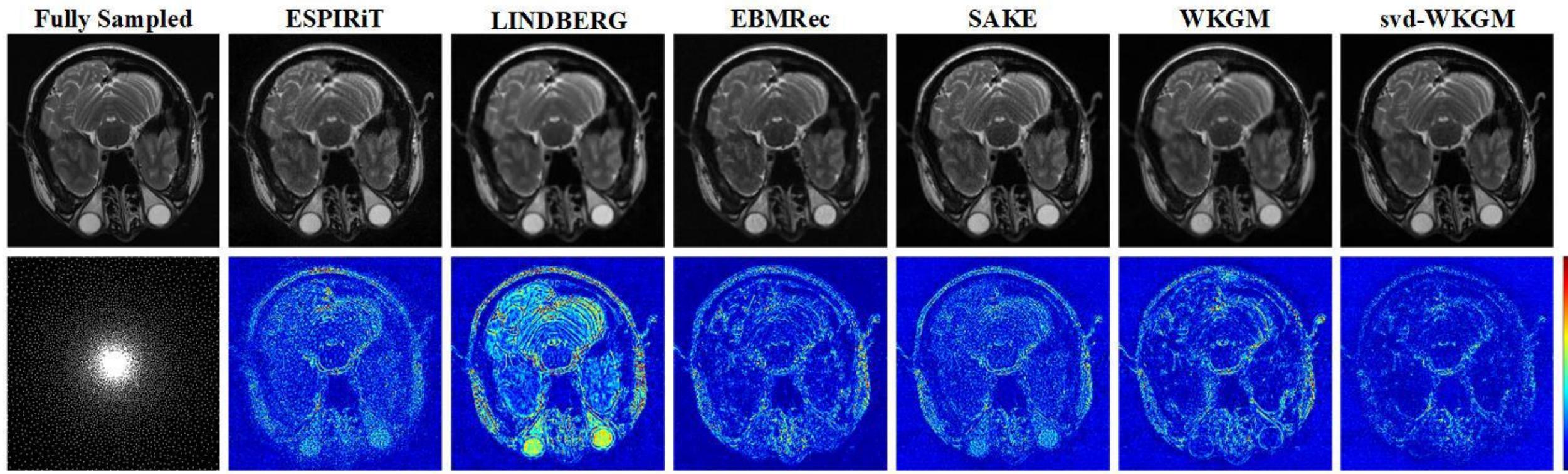


Illustration of the forward and reverse processes of k-space data and corresponding image. The forward process can be accomplished with a continuous-time SDE.

Experimental results



Parallel imaging reconstruction results by ESPIRiT, LINDBERG, EBMRec, SAKE, WKGM and svd-WKGM in T_2 Transversal Brain at $R=10$ 2D Poisson disk under-sampling mask. The intensity of residual maps is five times magnify.

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