

# MDS and PCA

Lecture 1.

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# Geometric Embedding

- ◆ A Fundamental Problem in Data Representation
- ◆ Unstructured data -> Euclidean Space
- ◆ a.k.a. 'feature' learning (e.g. deep learning)
- ◆ speech, text, image, video...

# Multidimensional Scaling

- Given pairwise distances between data points, can we find a system of Euclidean coordinates for those points whose pairwise distances meet given constraints?

	1	2	3	4	5	6	7	8	9	
	BOST	NY	DC	MIAM	CHIC	SEAT	SF	LA	DENV	
1	BOSTON	0	206	429	1504	963	2976	3095	2979	1949
2	NY	206	0	233	1308	802	2815	2934	2786	1771
3	DC	429	233	0	1075	671	2684	2799	2631	1616
4	MIAMI	1504	1308	1075	0	1329	3273	3053	2687	2037
5	CHICAGO	963	802	671	1329	0	2013	2142	2054	996
6	SEATTLE	2976	2815	2684	3273	2013	0	808	1131	1307
7	SF	3095	2934	2799	3053	2142	808	0	379	1235
8	LA	2979	2786	2631	2687	2054	1131	379	0	1059
9	DENVER	1949	1771	1616	2037	996	1307	1235	1059	0

# Isometric Euclidean Embedding

Find an Euclidean embedding of  
low total metric distortion:

$$\min_{Y_i \in \mathbb{R}^k} \sum_{i,j} (\|Y_i - Y_j\|^2 - d_{ij}^2)^2$$

take the derivative w.r.t  $Y_i \in \mathbb{R}^k$ :

$$\sum_{i,j} (\|Y_i\|^2 + \|Y_j\|^2 - 2Y_i^T Y_j - d_{ij}^2)(Y_i - Y_j) = 0$$

which implies  $\sum_i Y_i = \sum_j Y_j$ . For simplicity set  $\sum_i Y_i = 0$ , i.e. putting the origin as data center.

Use a linear transformation to move the sample mean to be the origin of the coordinates, i.e. define a matrix  $B_{ij} = -\frac{1}{2}HDH$  where  $D = (d_{ij}^2)$ ,  $H = I - \frac{1}{n}\mathbf{1}\mathbf{1}^T$ , then, the minimization (1) is equivalent to find  $Y_i \in \mathbb{R}^k$ :

$$\min \|Y^T Y - B\|_F^2$$

then the row vectors of matrix  $Y$  are the eigenvectors corresponding to  $k$  largest eigenvalues of  $B = \tilde{X}^T \tilde{X}$ , or equivalently the top  $k$  right singular vectors of  $\tilde{X} = USV^T$ .

$B$  is Gram matrix or kernel matrix

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### Algorithm 1: Classical MDS Algorithm

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**Input:** A squared distance matrix  $D^{n \times n}$  with  $D_{ij} = d_{ij}^2$ .

**Output:** Euclidean  $k$ -dimensional coordinates  $\tilde{X}_k \in \mathbb{R}^{k \times n}$  of data.

- 1 Compute  $B = -\frac{1}{2}H \cdot D \cdot H^T$ , where  $H$  is a centering matrix.
- 2 Compute Eigenvalue decomposition  $B = U\Lambda U^T$  with  $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_n)$  where  $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n \geq 0$ ;
- 3 Choose top  $k$  nonzero eigenvalues and corresponding eigenvectors,  $\tilde{X}_k = U_k \Lambda_k^{\frac{1}{2}}$  where

$$U_k = [u_1, \dots, u_k], \quad u_k \in \mathbb{R}^n,$$

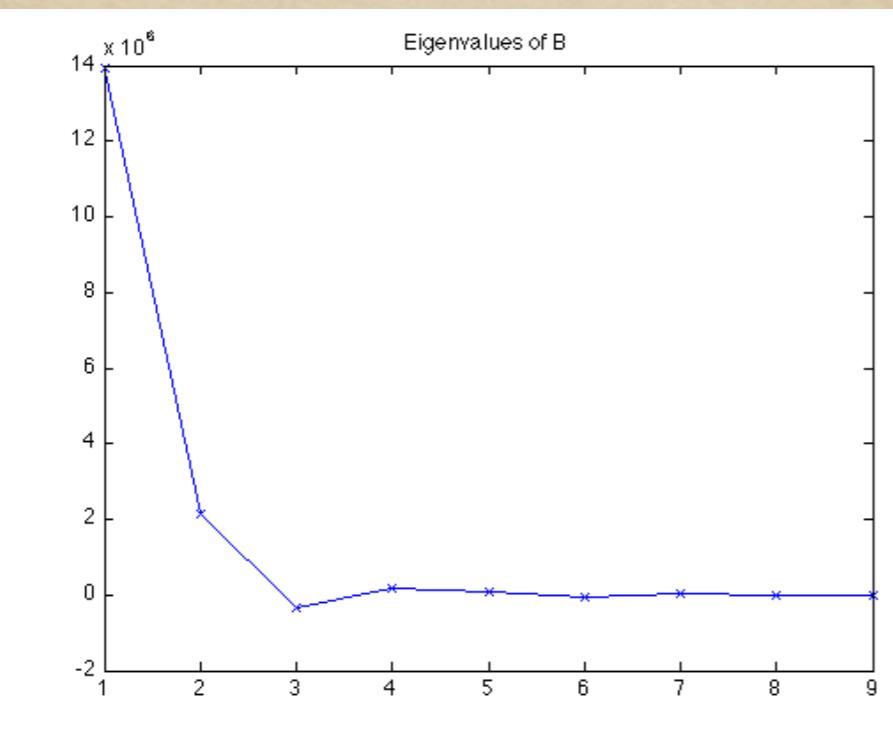
$$\Lambda_k = \text{diag}(\lambda_1, \dots, \lambda_k)$$

with  $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_k > 0$ .

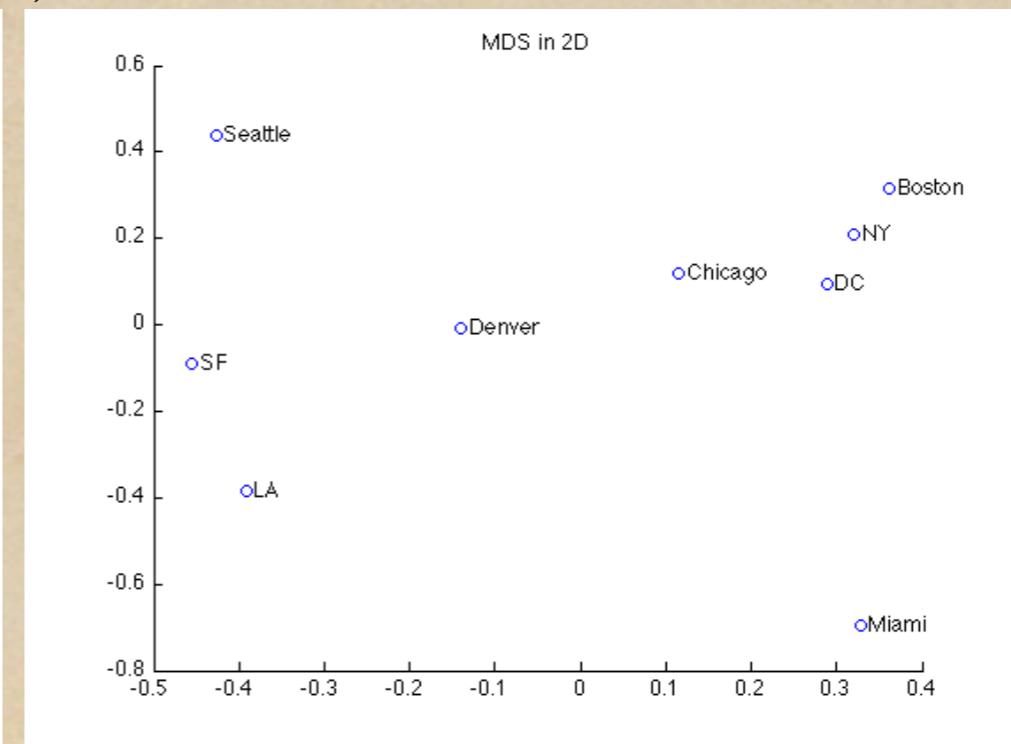
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(a)



(b)



(c)

# Inverse problem: when it is an Exact Isometry Embedding?

Consider a forward problem: given a set of points  $x_1, x_2, \dots, x_n \in \mathbb{R}^p$ , let

$$X = [x_1, x_2, \dots, x_n]^{p \times n}.$$

The distance between point  $x_i$  and  $x_j$  satisfies

$$d_{ij}^2 = \|x_i - x_j\|^2 = (x_i - x_j)^T (x_i - x_j) = x_i^T x_i + x_j^T x_j - 2x_i^T x_j.$$

# Inner Product (kernel) Matrix vs. Squared Distance Matrix

Let  $K$  be the inner product matrix

$$K = X^T X,$$

with  $k = \text{diag}(K_{ii}) \in \mathbb{R}^n$ . So

$$D = (d_{ij}^2) = k \cdot \mathbf{1}^T + \mathbf{1} \cdot k^T - 2K.$$

where  $\mathbf{1} = (1, 1, \dots, 1)^T \in \mathbb{R}^n$ .

# Centered the data

Define the mean and the centered data

$$\hat{\mu}_n = \frac{1}{n} \sum_{i=1}^n x_i = \frac{1}{n} \cdot X \cdot \mathbf{1},$$

$$\tilde{x}_i = x_i - \hat{\mu}_n = x_i - \frac{1}{n} \cdot X \cdot \mathbf{1},$$

$$\tilde{X} = X - \frac{1}{n} X \cdot \mathbf{1} \cdot \mathbf{1}^T.$$

$$\begin{aligned}\tilde{K} &\triangleq \tilde{X}^T \tilde{X} \\&= \left( X - \frac{1}{n} X \cdot \mathbf{1} \cdot \mathbf{1}^T \right)^T \left( X - \frac{1}{n} X \cdot \mathbf{1} \cdot \mathbf{1}^T \right) \\&= K - \frac{1}{n} K \cdot \mathbf{1} \cdot \mathbf{1}^T - \frac{1}{n} \mathbf{1} \cdot \mathbf{1}^T \cdot K + \frac{1}{n^2} \cdot \mathbf{1} \cdot \mathbf{1}^T \cdot K \cdot \mathbf{1} \cdot \mathbf{1}^T\end{aligned}$$

Let

$$B = -\frac{1}{2}H \cdot D \cdot H^T$$

where  $H = I - \underbrace{\frac{1}{n} \cdot \mathbf{1} \cdot \mathbf{1}^T}_{\sim}$ . H is called as a *centering matrix*.

$$B = -\frac{1}{2}H \cdot (k \cdot \mathbf{1}^T + \mathbf{1} \cdot k^T - 2K) \cdot H^T$$

Since  $k \cdot \mathbf{1}^T \cdot H^T = k \cdot \mathbf{1}(I - \frac{1}{n} \cdot \mathbf{1} \cdot \mathbf{1}^T) = k \cdot \mathbf{1} - k(\frac{\mathbf{1}^T \cdot \mathbf{1}}{n}) \cdot \mathbf{1} = 0$ , we have  
 $H \cdot k \cdot \mathbf{1} \cdot H^T = H \cdot \mathbf{1} \cdot k^T \cdot H^T = 0$ .

Therefore,

$$\begin{aligned} B &= H \cdot K \cdot H^T = (I - \frac{1}{n} \cdot \mathbf{1} \cdot \mathbf{1}^T) \cdot K \cdot (I - \frac{1}{n} \cdot \mathbf{1} \cdot \mathbf{1}^T) \\ &= K - \frac{1}{n} \cdot \mathbf{1} \cdot \mathbf{1} \cdot K - \frac{1}{n} \cdot K \cdot \mathbf{1} \cdot \mathbf{1}^T + \frac{1}{n^2} \cdot \mathbf{1}(\mathbf{1}^T \cdot K \mathbf{1}) \cdot \mathbf{1}^T \\ &= \tilde{K}. \end{aligned}$$

# Gram/Kernel matrix

$$B = -\frac{1}{2}H \cdot D \cdot H^T = \tilde{X}^T \tilde{X}.$$

Note that often we define the covariance matrix

$$\hat{\Sigma}_n \triangleq \frac{1}{n-1} \sum_{i=1}^n (x_i - \hat{\mu}_n)(x_i - \hat{\mu}_n)^T = \frac{1}{n-1} \tilde{X} \tilde{X}^T.$$

# P.S.D. as inner product

**Definition** (Positive Semi-definite). Suppose  $A^{n \times n}$  is a real symmetric matrix, then:  
 $A$  is p.s.d. (positive semi-definite) ( $A \succeq 0$ )  $\iff \forall v \in \mathbb{R}^n, v^T A v \geq 0 \iff A = Y^T Y$

**Property.** Suppose  $A^{n \times n}, B^{n \times n}$  are real symmetric matrices,  $A \succeq 0, B \succeq 0$ . Then we have:

- (1)  $A + B \succeq 0$ ;
- (2)  $A \circ B \succeq 0$ ;

where  $A \circ B$  is called Hadamard product and  $(A \circ B)_{i,j} := A_{i,j} \times B_{i,j}$ .

# C.N.D.

**Definition** (Conditionally Negative Definite). Suppose  $A^{n \times n}$  is a real symmetric matrix, then:

$A$  is c.n.d. (conditionally negative definite)  $\iff \forall v \in \mathbb{R}^n, \mathbf{1}v^T = \sum_{i=1}^n v_i = 0$ , we have  $v^T A v \leq 0$

**Lemma 2.1** (Young/Householder-Schoenberg '1938). For any signed probability measure  $\alpha$  ( $\alpha \in \mathbb{R}^n, \sum_{i=1}^n \alpha_i = 1$ ),

$$B_\alpha = -\frac{1}{2} H_\alpha C H_\alpha^T \succeq 0 \iff C \text{ is c.n.d.}$$

where  $H_\alpha$  is Householder centering matrix:  $H_\alpha = \mathbf{I} - \mathbf{1} \cdot \alpha^T$ .