

Chemical Property Prediction via Graph Knowledge Transfer

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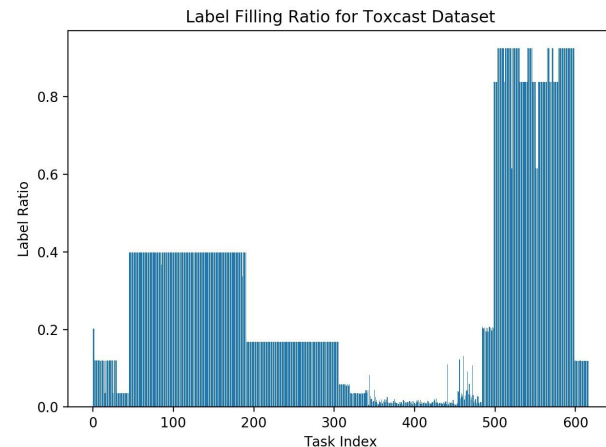
Introduction

Introduction

- Predicting molecular properties
 - A fundamental problem in Biomedicine and Chemistry
 - Expensive and time-consuming
- Use of deep learning (DL)
 - Speed-up the process
 - Better predict molecular properties

Introduction

- Practical effect of DL is limited
 - Require large amounts of labeled data
- Usually, in Biomedicine and Chemistry
 - Fully labeling a dataset is **unaffordable** ^[1]
 - Label ratio between properties is **imbalanced** ^[2]

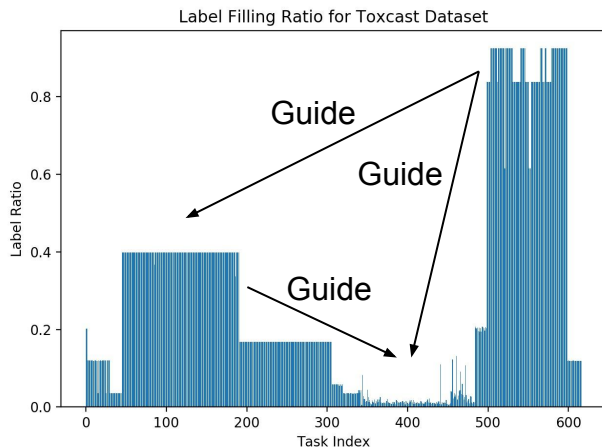


[1] H. Altae-Tran, B. Ramsundar, A. S. Pappu, V. Pande. Low Data Drug Discovery with One-Shot Learning. ACS Cent. Sci. 2017, 3 (4), 283–293.

[2] W. Lin, D. Xu, Imbalanced multi-label learning for identifying antimicrobial peptides and their functional types. Bioinformatics, Volume 32, Issue 24, 15 December 2016, Pages 3745.

Introduction

- Intuition: leverage task dependency
 - Knowledge extracted from fully labeled properties can enhance the prediction of properties with few labels



ToxCast dataset. x: no label.

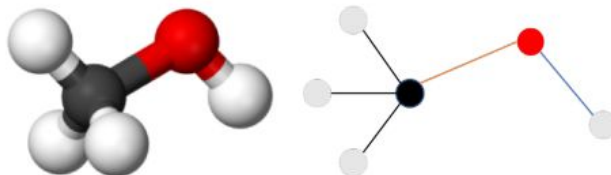
Property	ESRE	APR
	BLA	HepG2
Mol 1	1	x
Mol 2	0	0
Mol 3	0	x
Mol 4	1	1
Mol 5	1	x
...
Mol 8597	0	x
Mol 8598	1	x
Label Ratio	0.84	0.12

Guide

Related Work:
Graph-Level Classification / Regression

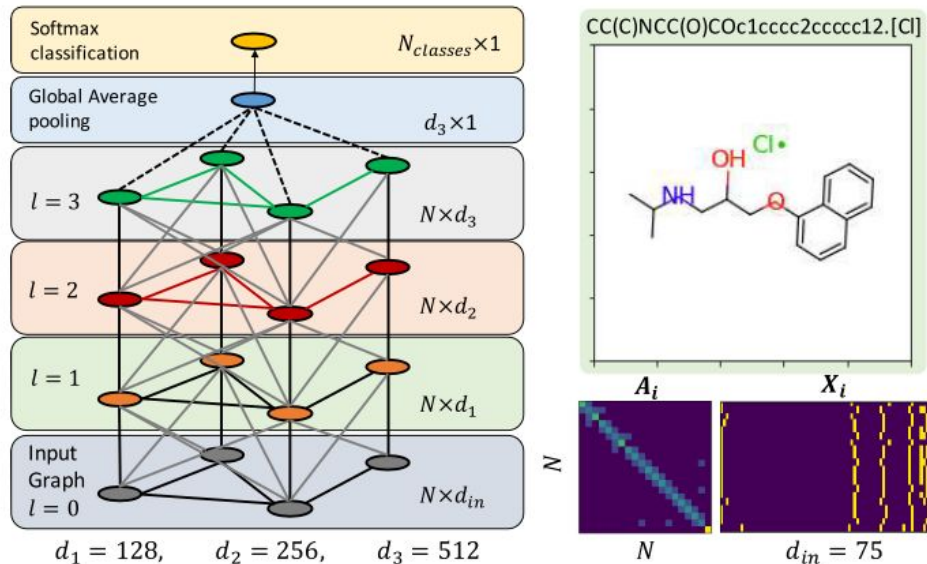
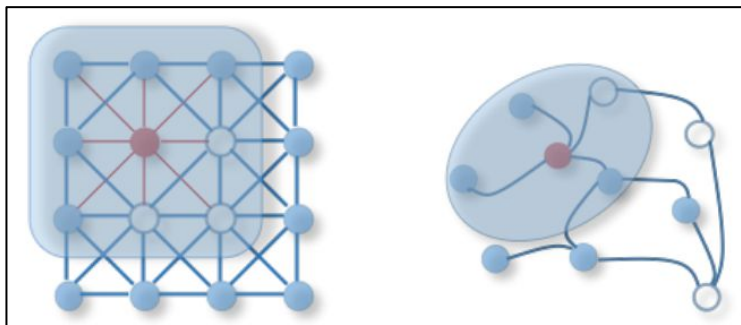
Graph-Level Classification / Regression

- Molecule graph
 - Atoms -> nodes
 - Chemical bonds -> edges



- Molecule -> Graph-Level Prediction
 - e.g. toxicity, solubility, side effect

Graph Classification / Regression Model

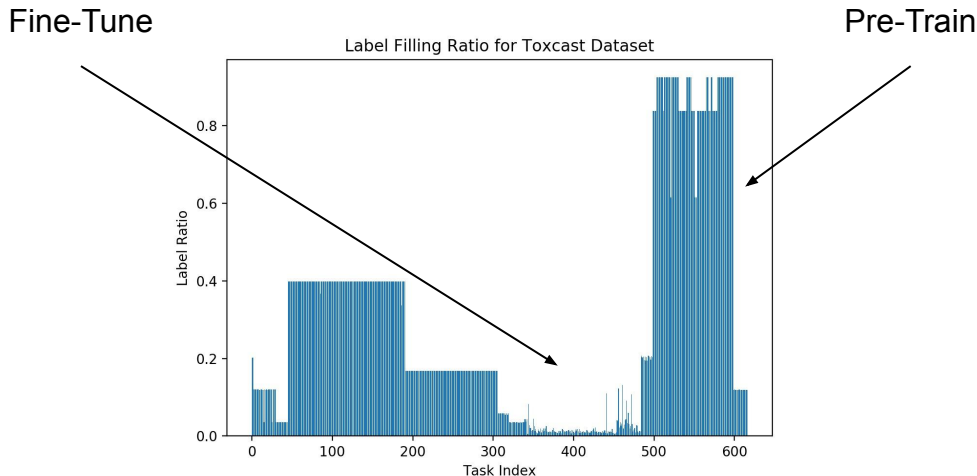


Suffer from the lack of labeled data

Related Work: Transfer Learning

Transfer Learning

- Pre-train the model on properties with abundant labels
- Fine-tune the model on properties with few labels

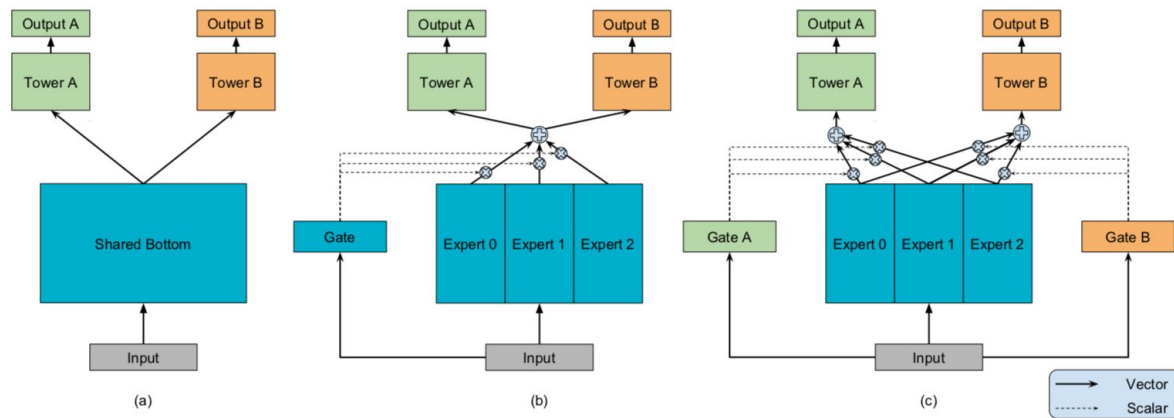


Not End-to-End
Not Time-Efficient

Related Work: Multi-Task Learning

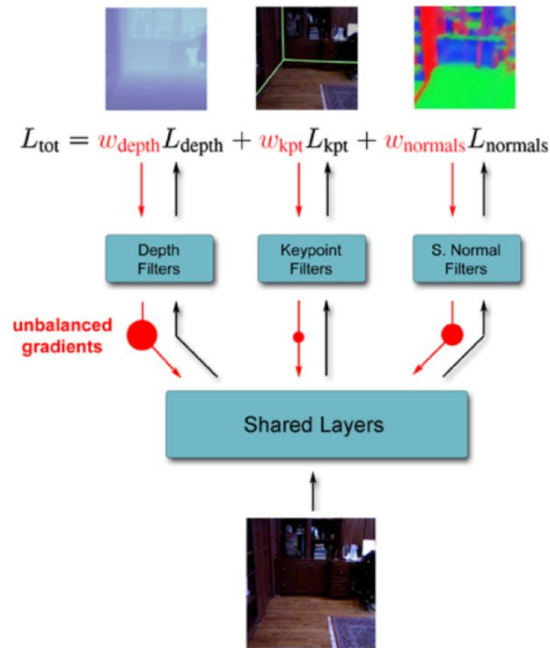
Multi-Task Learning

- Train multiple tasks together
 - Time efficient
 - Leverage knowledge among tasks



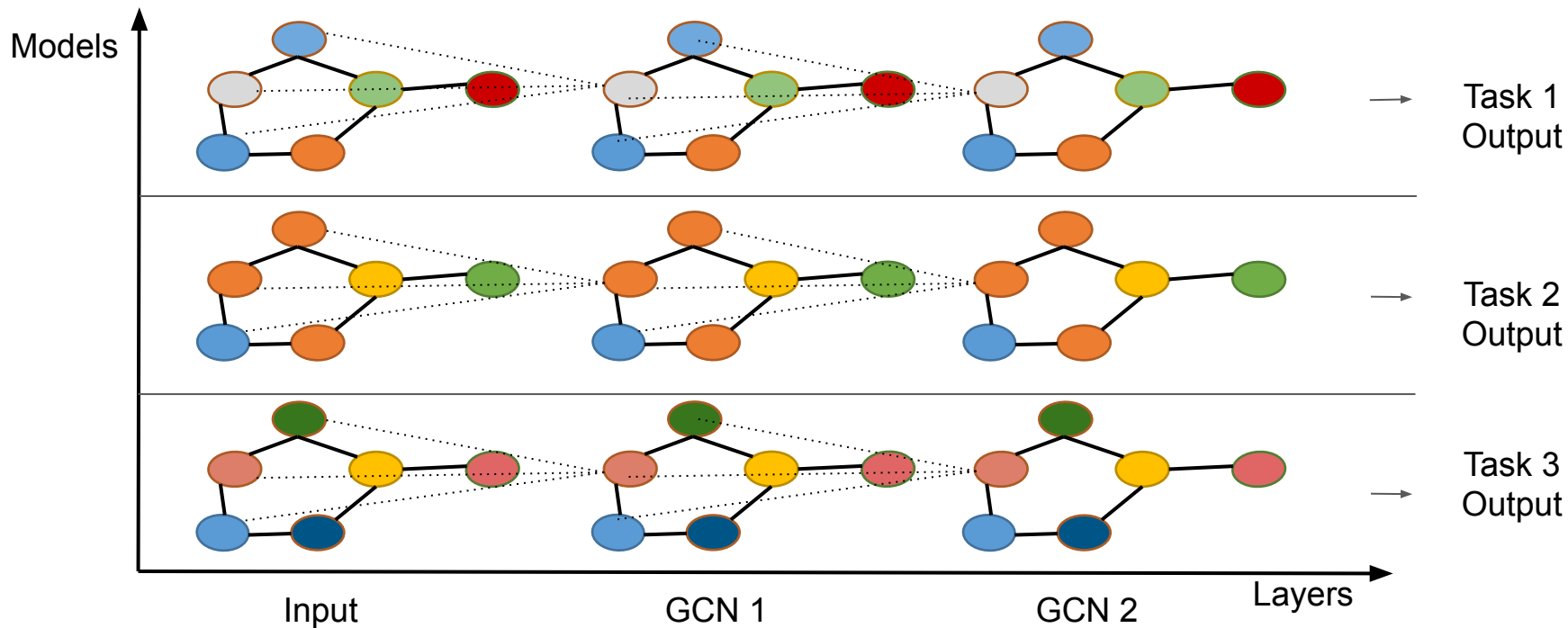
Multi-Task Learning

- Imbalanced label ratio
- Imbalanced gradients
 - Tasks with abundant labels / larger gradients will dominate the model
- Neglect interaction among different tasks

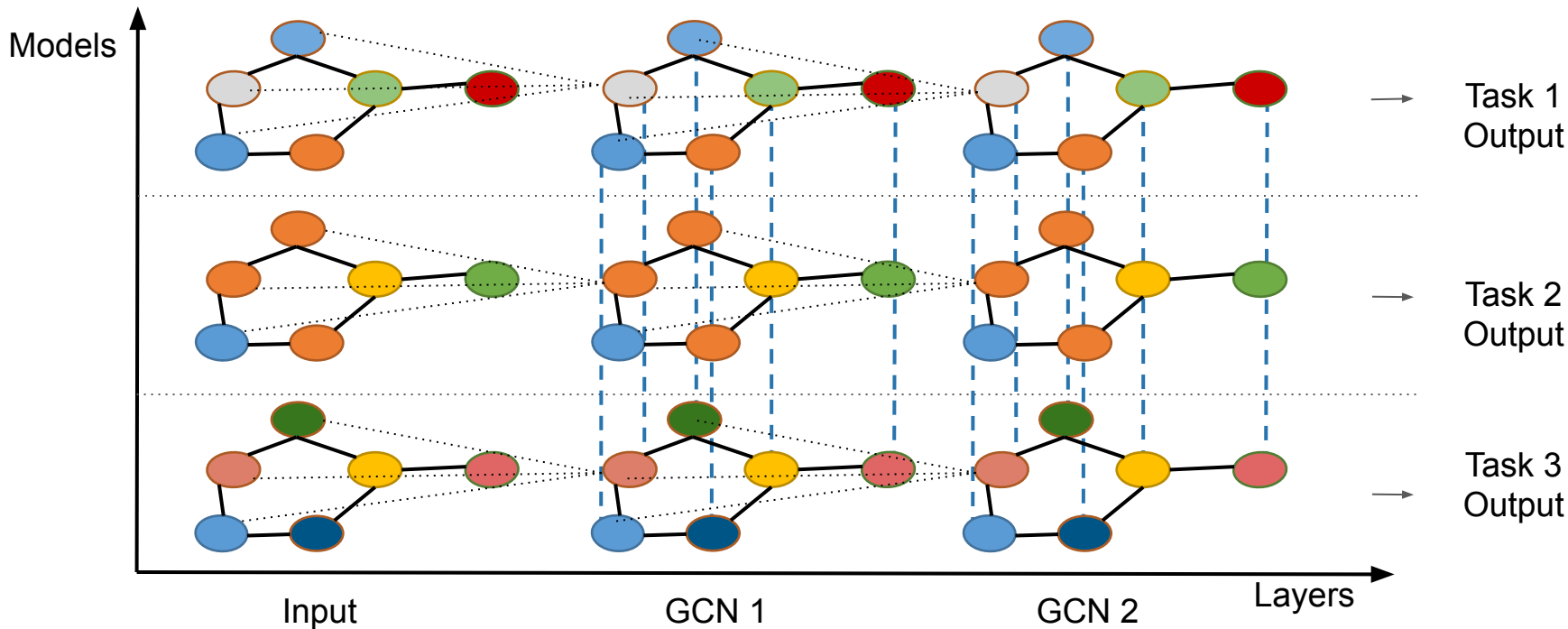


Method: Hypergraph Knowledge Transfer

Normal GCN



Hypergraph GCN



Data-Dependent Task Dependency Graph

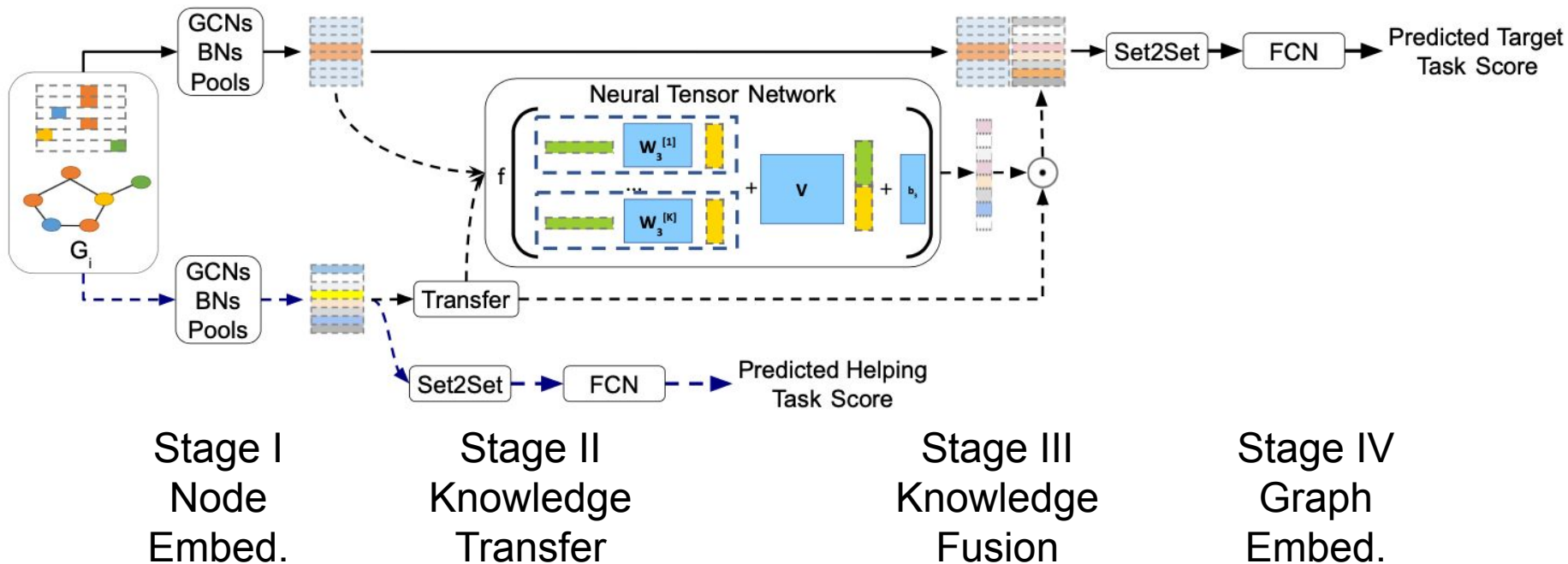
Hypergraph Knowledge Transfer

- Each task will have its own base model
- Calculate the data-dependent task dependency graph
- Aggregate representation from different task specific models



- Mutually enhance performance on all tasks
- Mining the task-level dependency

Base Model (Dual-Task)



Experiment

Experiment Setting

Dataset	Graph Meaning	#Graphs	#Tasks
TOX21	Qualitative Toxicity Measurements	7831	12
SIDER	Adverse Drug Reactions	1427	27

Target tasks (10% training):

- SR-ARE (TOX21)
- Investigations (SIDER)

Helping tasks: (90% training)

- SR-MMP (TOX21)
- Vascular Disorders (SIDER)

Experiment Results

Model	TOX21		SIDER	
	Target Task (10% Training)	Helping Task (90% Training)	Target Task (10% Training)	Helping Task (90% Training)
Single-task Model				
GCN [3]	0.6776	0.8638	0.5938	0.6266
MoleculeNet [4]	0.7156	0.8315	0.6189	0.6294
Our	0.7385	0.9096	0.6266	0.8212
Multi-task Model				
MoleculeNet [4]	0.7298	0.8382	0.6315	0.6503
Our	0.7762	0.9233	0.6569	0.8037

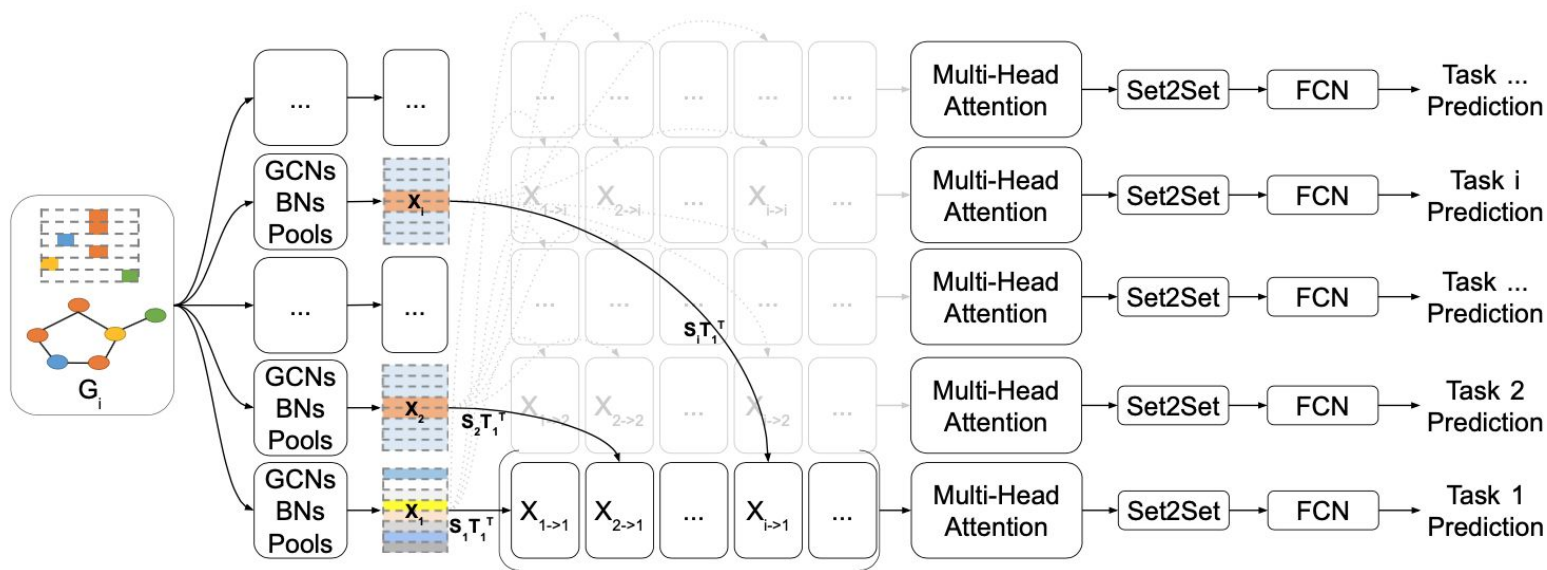
- Score will decrease if we lower the ratio of training data
- Score will increase if we leverage knowledge between tasks

Next Step

Backbone Model (Multi-Task)

- Problems of dual-task model
 - For every task pair (i, j), We need a transfer module $f_{i \rightarrow j}$
 - $O(k^2)$, k is #tasks -> not scalable
 - Ignore the tasks relation at a higher level
- Insight:
 - Decompose the transfer module $f_{i \rightarrow j} = S_i T_j'$
 - Each task i only need to store S_i and T_j
 - $O(k)$, k is #tasks
 - Explicitly model task-level and graph-level relations

Backbone Model (Multi-Task)

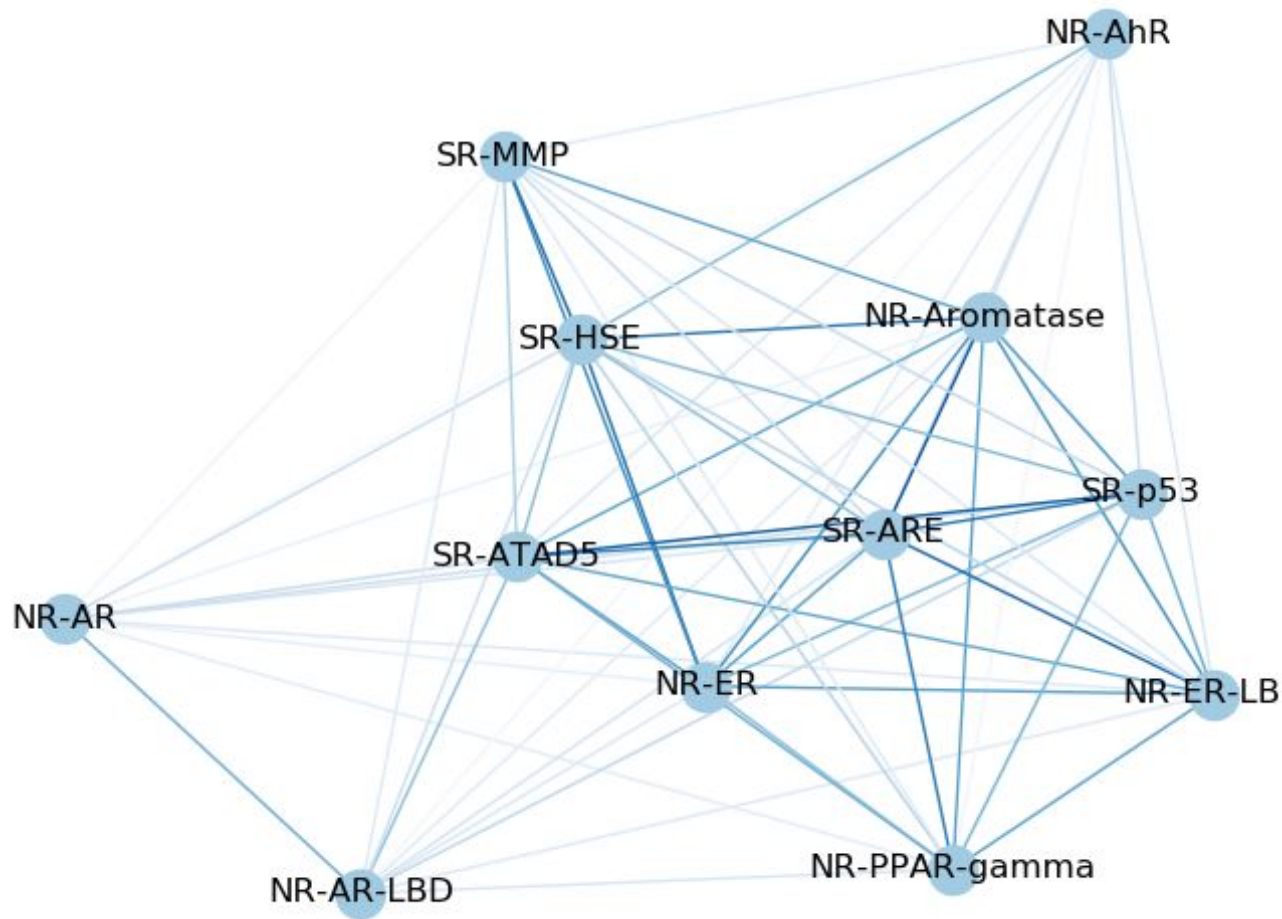


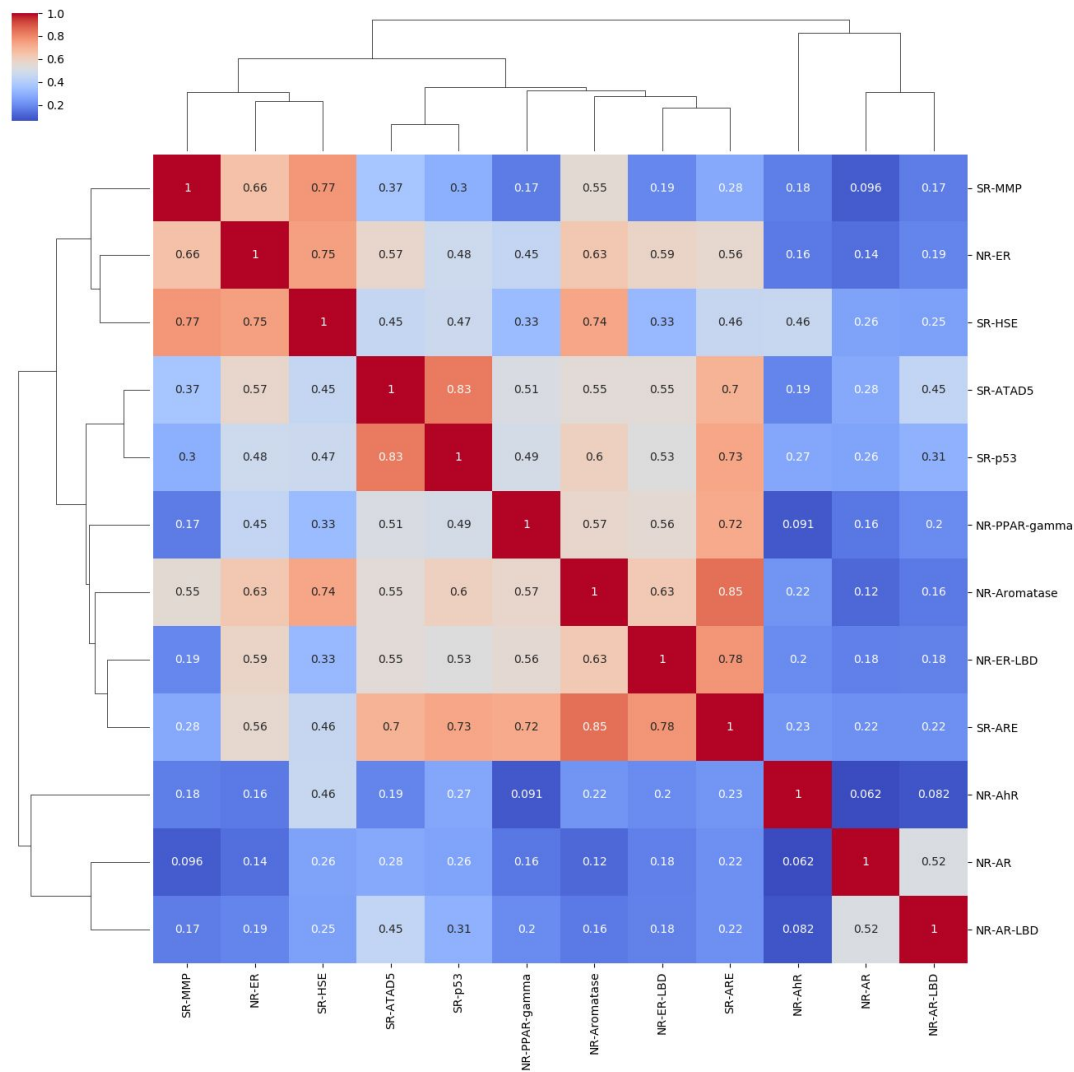
$$\hat{X}_j = \sum_{i=1}^k [\text{Softmax}(D_{i \rightarrow j} \mathbf{A}_{i \rightarrow j}) \cdot \mathbf{X}_{i \rightarrow j}]$$

$$\mathbf{X}_{i \rightarrow j} = \mathbf{X}_i \mathbf{S}_i \mathbf{T}_j^T, \text{ where } \mathbf{S}_i, \mathbf{T}_j \in R^{d \times d'}, \mathbf{X}_{i \rightarrow j} \in R^{n \times d}$$

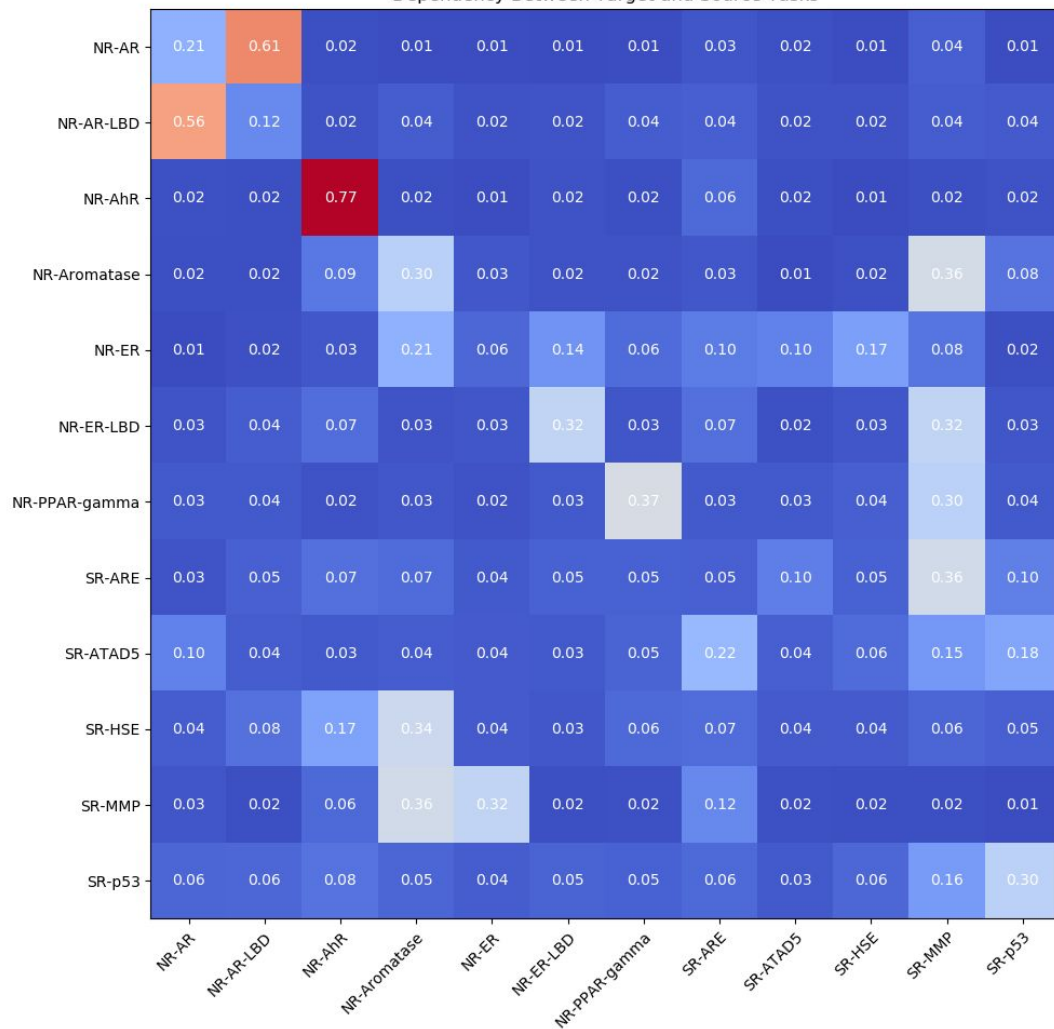
$$\mathbf{A}_{i \rightarrow j} = \mathbf{X}_{i \rightarrow j} \mathbf{Q}_i (\mathbf{X}_j \mathbf{K}_j)^T, \text{ where } \mathbf{Q}_i, \mathbf{K}_j \in R^{d \times d'}, \mathbf{A}_{i \rightarrow j} \in R^{n \times n}$$

Some Results





Dependency Between Target and Source Tasks



Conclusion

Conclusion

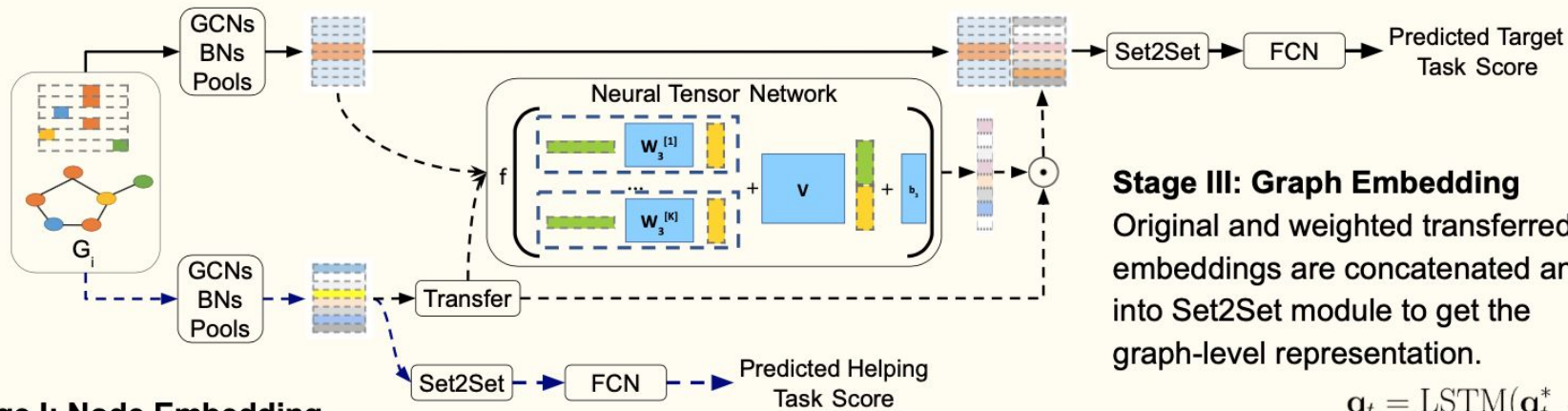
- Lack of labeled data and imbalanced label ratio limits the effect of DL in Chemistry and Biomedicine
- Contribution of our work: transfer + fusion
 - Introduce hypergraph to transfer knowledge between properties
 - Introduce novel attention mechanism to fuse transferred knowledge
 - Explore the hidden dependency structure between tasks
 - Improve dual-task's AUC-ROC score by 6.9%

Q&A

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MODEL DETAIL



Stage I: Node Embedding

$$\text{Conv}(A, X) = \hat{D}^{-1/2} \hat{A} \hat{D}^{-1/2} X \Theta$$

$$\text{BN}(X) = \frac{X - \mathbb{E}[X]}{\sqrt{\text{Var}[X] + \epsilon}} * \gamma + \beta$$

$$\text{Pool}(v) = \max\{\max_{(u,v) \in E} \{u, v\}\}$$

Stage II: Knowledge Transfer

Two linear layers with ReLU activation transfer the node embeddings from helping task to target task. Neural Tensor Network models the node-level interaction and decides the transfer weights.

Stage III: Graph Embedding

Original and weighted transferred embeddings are concatenated and fed into Set2Set module to get the graph-level representation.

$$\mathbf{q}_t = \text{LSTM}(\mathbf{q}_{t-1}^*)$$

$$\alpha_{i,t} = \text{softmax}(\mathbf{x}_i \cdot \mathbf{q}_t)$$

$$\mathbf{r}_t = \sum_{i=1}^N \alpha_{i,t} \mathbf{x}_i$$

$$\mathbf{q}_t^* = \mathbf{q}_t \parallel \mathbf{r}_t$$

Assume T_j is the target task.

Transfer the embeddings from T_i to T_j ($i \neq j$):

$$X_{i \rightarrow j} = X_i W_{Si} W_{Tj}^T, \text{ where } W_{Si}, W_{Tj} \in R^{d \times d'}, X_{i \rightarrow j} \in R^{n \times d}.$$

Calculate the node-level attention:

$$\text{ATT}_{i \rightarrow j} = X_{i \rightarrow j} W_{Qi} (X_j W_{Kj})^T, \text{ where } W_{Qi}, W_{Kj} \in R^{d \times d'}, \text{ATT}_{i \rightarrow j} \in R^{n \times n}.$$

$$\widetilde{\text{ATT}}_{i \rightarrow j} = \text{Softmax}(\text{ATT}_{i \rightarrow j}, \text{dim} = -1) \in R^{n \times n}.$$

Combine embeddings from all tasks w.r.t. node-level attention

$$\hat{X}_{i \rightarrow j} = \widetilde{\text{ATT}}_{i \rightarrow j} \cdot X_{i \rightarrow j} \text{ where } \hat{X}_{i \rightarrow j} \in R^{n \times d}.$$

$$X_j^{\text{comb}} = \text{cat}([X_j, \hat{X}_{: \rightarrow j}]) \in R^{k \times n \times d}.$$

$$\widetilde{X_j^{\text{comb}}} = \text{Norm}(X_j^{\text{comb}}) \in R^{k \times n \times d}.$$

Merge the embeddings w.r.t. task dependency:

$$\hat{X}_j = W_{Dj} \widetilde{X_j^{\text{comb}}}, \text{ where } W_{Dj} \in R^{1 \times k}, \hat{X}_j \in R^{n \times d}.$$

Finally, calculate graph-level embedding:

$$G_j = \text{Readout}(\hat{X}_j) \in R^{1 \times d}.$$

Tox21 Data Challenge

