

Chemical Property Prediction via Graph Knowledge Transfer

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MOTIVATION

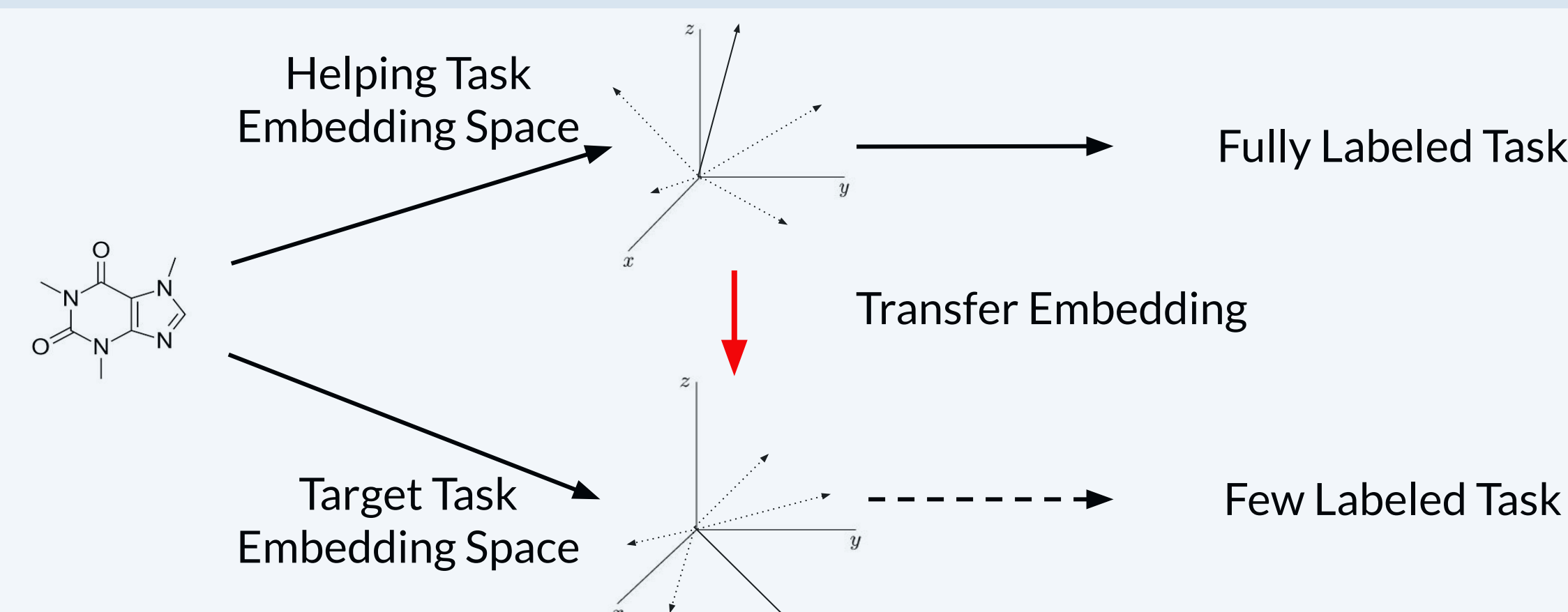
- Current deep learning frameworks require large amounts of data.
- In chemical and biomedical domain, the cost of fully labeling a dataset is usually unaffordable [1].
- Because measurements of some properties are more expensive than the others, label ratio between properties is usually imbalanced [2].

Insight: Leveraging chemical graph structure, knowledge extracted from fully labeled properties can be efficiently transferred to enhance the representation learning of properties with few labels.

ToxCast dataset. x: no label.

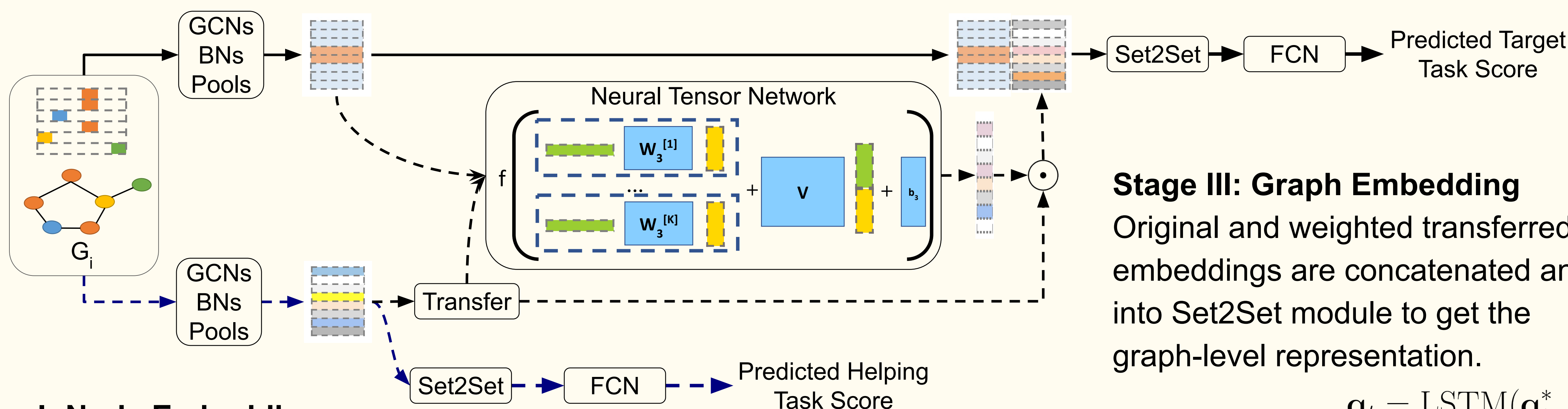
Property	ESRE	APR
	BLA	HepG2
Mol 1	1	x
Mol 2	0	0
Mol 3	0	x
Mol 4	1	1
Mol 5	1	x
...
Mol 8597	0	x
Mol 8598	1	x
Label Ratio	0.84	0.12

METHOD



Our model **transfers** and **fuses** the knowledge between tasks to enhance the performance on target task. Chemical graph will first be mapped to task-specific embedding space separately. Then, node embeddings of helping task will be transferred by a powerful transfer layer (red arrow) to the target task embedding space.

MODEL DETAIL



Stage I: Node Embedding

$$\text{Conv}(A, X) = \hat{D}^{-1/2} \hat{A} \hat{D}^{-1/2} X \Theta$$

$$\text{BN}(X) = \frac{X - E[X]}{\sqrt{\text{Var}[X] + \epsilon}} * \gamma + \beta$$

$$\text{Pool}(v) = \max\{\max_{(u,v) \in E} \{u, v\}\}$$

Stage II: Knowledge Transfer

Two linear layers with ReLU activation transfer the node embeddings from helping task to target task. Neural Tensor Network models the node-level interaction and decides the transfer weights.

Stage III: Graph Embedding

Original and weighted transferred embeddings are concatenated and fed into Set2Set module to get the graph-level representation.

$$\mathbf{q}_t = \text{LSTM}(\mathbf{q}_{t-1}^*)$$

$$\alpha_{i,t} = \text{softmax}(\mathbf{x}_i \cdot \mathbf{q}_t)$$

$$\mathbf{r}_t = \sum_{i=1}^N \alpha_{i,t} \mathbf{x}_i$$

$$\mathbf{q}_t^* = \mathbf{q}_t \parallel \mathbf{r}_t$$

RESULTS

Model	TOX21		SIDER	
	Target Task (10% Training)	Helping Task (90% Training)	Target Task (10% Training)	Helping Task (90% Training)
Single-task Model				
GCN [3]	0.6776	0.8638	0.5938	0.6266
MoleculeNet [4]	0.7156	0.8315	0.6189	0.6294
Our	0.7385	0.9096	0.6266	0.8212
Multi-task Model				
MoleculeNet [4]	0.7298	0.8382	0.6315	0.6503
Our	0.7762	0.9233	0.6569	0.8037

We select SR-ARE (TOX21) and Investigations (SIDER) as target tasks; SR-MMP (TOX21) and Vascular Disorders (SIDER) as helping tasks.

ACKNOWLEDGEMENTS

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CONCLUSION

In this work, we make the following contributions:

- Identify imbalanced labeling issues on chemical and biomedical tasks.
- Introduce novel graph neural network to extract, transfer and fuse knowledge between tasks.
- Improve AUC-ROC score by 6.9% without fine tuning.

REFERENCE

- [1] H. Altae-Tran, B. Ramsundar, A. S. Pappu, V. Pande. Low Data Drug Discovery with One-Shot Learning. ACS Cent. Sci. 2017, 3 (4), 283–293.
- [2] W. Lin, D. Xu, Imbalanced multi-label learning for identifying antimicrobial peptides and their functional types. Bioinformatics, Volume 32, Issue 24, 15 December 2016, Pages 3745.
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- [4] Z. Wu, B. Ramsundar, E. N. Feinberg, J. Gomes, C. Geniesse, A. S. Pappu, K. Leswing, V. Pande. MoleculeNet: A Benchmark for Molecular Machine Learning, 2017. <https://arxiv.org/abs/1703.00564>.