



# Arrays

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# Arrays: Abstract Data Type

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- Each instance of the data object array is a set of pairs of the form (index, value).
- No two pairs in this set have the same index.
- The functions performed on the array are as follows:
  - **Sets an Element** - Adds a pair of the form (index, value) to the set, and if a pair with the same index already exists, deletes the old pair.
  - **Gets an Element** – Retrieves the value of the pair that has a given index.

# Arrays: Abstract Data Type

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**AbstractDataType** *array*

{

**instances**

        set of (index, value) pairs, no two pairs have the same index

**operations**

*get(index)* : return the value of the pair with this index

*set(index, value)* : add this pair to set of pairs, overwrite existing pair (if any) with the same index

}



# Example

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- The high temperature (in degrees Fahrenheit) for each day of last week may be represented by the following array:

**High** = {(Sunday, 82), (Monday, 79), (Tuesday, 45), (Wednesday, 92), (Thursday, 88), (Friday, 89), (Saturday, 91)}

- We can change the high temperature recorded for Monday to 83 by performing the operation **set(Monday, 83)**.
- We can determine the high temperature of Friday by performing the operation **get(Friday)**.
- An alternative way to represent the daily high temperature is **High** = {(0, 82), (1, 79), (2, 45), (3, 92), (4, 88), (5, 89), (6, 91)}



# Indexing a C++ Array

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- The index of an array in C++ must be of the form  $[i_1][i_2][i_3] \dots [i_k]$ , where each  $i_j$  is a non-negative integer.
- A 3-dimensional array score, whose values are of type integer, can be created as `int score [u1] [u2] [u3]`, where  $u_i$ 's are positive constants or positive expressions derived from constants.
- Index  $i_j$  should be in the range  $0 \leq i_j \leq u_j$  and  $1 \leq j \leq k$ .
- The array can hold a maximum of  **$n = u_1 \cdot u_2 \cdot u_3$**  values
- The memory size of score is  **$n * \text{sizeof(int)}$  bytes**. This memory begins at byte **start** (say) and extends up to and including byte **start + sizeof(score)-1**.



# Row Major and Column Major Mappings

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- Let  $n$  be the number of elements in a  $k$ -dimensional array.
- The serialization of the array is done using a mapping function, which maps the array index  $[i_1][i_2][i_3]...[i_k]$  into a number  $\text{map}(i_1, i_2, i_3...i_k)$ , in the range  $[0, n-1]$  such that array element with index  $[i_1][i_2][i_3]...[i_k]$  is mapped to position  $\text{map}(i_1, i_2, i_3...i_k)$  in the serial order.
- When the number of dimensions is 1 (i.e.  $k=1$ ), the function

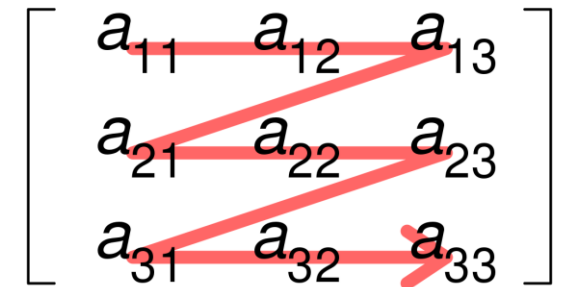
$$\text{map}(i_1) = i_1$$



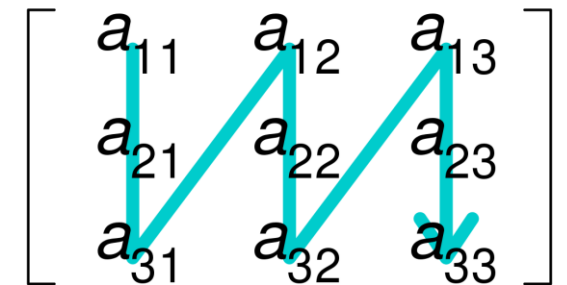
# Row Major and Column Major Mappings

- In a 2D array there are two possible ways to store the array:
- Row Major
- Column Major

Row-major order



Column-major order





# Row Major Order: Locating element $A[i][j]$

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- **Location** of  $A[I][J]$  = Base Address (A) +  $W * [N(I - L_r) + (J - L_c)]$
- Where **Base Address** is the address of the first element in an array.
- **W**= Weight (size) of a data type.
- **N**= Total No of Columns.
- **I**= Row Number
- **J**= Column Number of an element whose address is to find out.
- **L<sub>r</sub>** = Lower limit of row/ if not given assume 0
- **L<sub>c</sub>** = Lower limit of column/ if not given assume 0





# Column Major Order: Locating element $A[i][j]$

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- **Location** of  $A[I][J]$  = Base Address (A) +  $W * [M (J-L_c) + (I-L_r)]$
- Where **Base Address** is the address of the first element in an array.
- **W**= Weight (size) of a data type.
- **M**= Total No of Rows.
- **I**= Row Number
- **J**= Column Number of an element whose address is to find out.
- $L_r$  = Lower limit of row/ if not given assume 0
- $L_c$  = Lower limit of column/ if not given assume 0
- **Number of Rows =  $(U_r - L_r) + 1$**
- **Number of Columns =  $(U_c - L_c) + 1$**

# Mapping Functions

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- When row major order is used, the mapping function is:

$$\text{map}(i_1, i_2) = i_1 u_2 + i_2$$

where  $u_2$  is the number of columns in the array.

- Note that by the time index  $[i_1][i_2]$  is numbered in the row major scheme,  $i_1 u_2$  elements from the rows 0, ...,  $i_1 - 1$  as well as  $i_2$  elements from row  $i_1$  have been numbered.

# Mapping Functions

- A sample array of 3 X 6 is shown in figure. Since the number of columns is 6,  $u_2$  becomes

$$\text{map}(i_1, i_2) = 6i_1 + i_2$$

So  $\text{map}(1,3) = 6 + 3 = 9$  and  $\text{map}(2,5) = 6 * 2 + 5 = 17$

0	1	2	3	4	5
6	7	8	9	10	11
12	13	14	15	16	17

(a) Row-major mapping

0	3	6	9	12	15
1	4	7	10	13	16
2	5	8	11	14	17

(b) Column-major mapping



# Mapping in a 3D Array

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- The discussed scheme can be extended to obtain mapping functions for arrays with more than 2 dimensions.
- In row major order, we first list all indexes with the first coordinate equal to 0, then those with this coordinate equal to 1 and so on.
- For instance, the indexes of score [3] [2] [4] in row major order are

[0][0][0]	[0][0][1]	[0][0][2]	[0][0][3]	[0][1][0]	[0][1][1]	[0][1][2]	[0][1][3]
[1][0][0]	[1][0][1]	[1][0][2]	[1][0][3]	[1][1][0]	[1][1][1]	[1][1][2]	[1][1][3]
[2][0][0]	[2][0][1]	[2][0][2]	[2][0][3]	[2][1][0]	[2][1][1]	[2][1][2]	[2][1][3]



# Mapping in a 3D Array

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- The mapping function for 3D array is

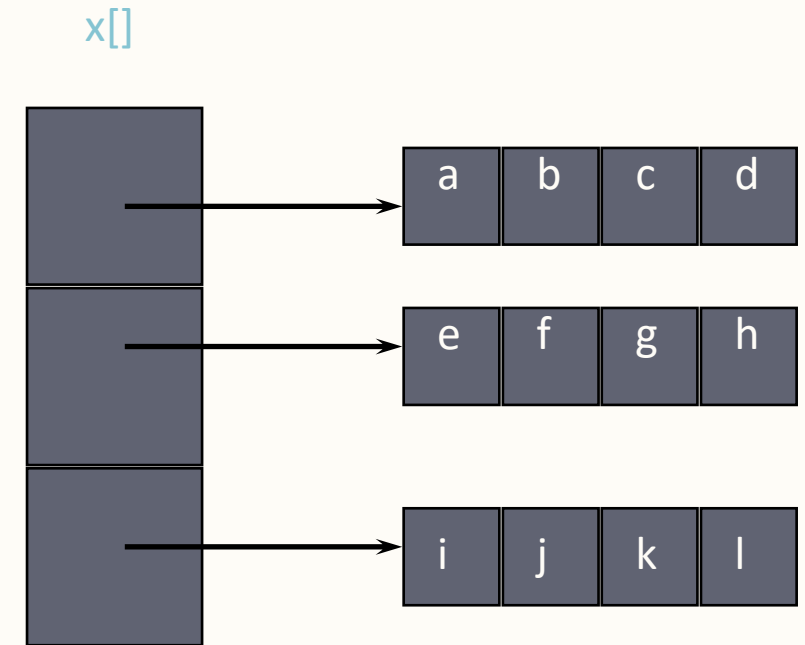
$$\text{map}(i_1, i_2, i_3) = i_1 u_2 u_3 + i_2 u_3 + i_3$$

- Note that the elements with the first coordinate  $i_1$  are preceded by all the elements whose first coordinate is less than  $i_1$ . There are  $u_2 u_3$  elements that have the same first coordinate. So there are  $i_1 u_2 u_3$  elements with the first coordinate less than  $i_1$ .
- The number of elements with the first coordinate equal to  $i_1$  and the second coordinate less than  $i_2$  is  $i_2 u_3$ , and the number with the first coordinate equal to  $i_1$ , the second equal to  $i_2$ , and the third less than  $i_3$  is  $i_3$ .

# Array of Arrays Representation

C++ uses array of arrays representation to represent a multidimensional array.

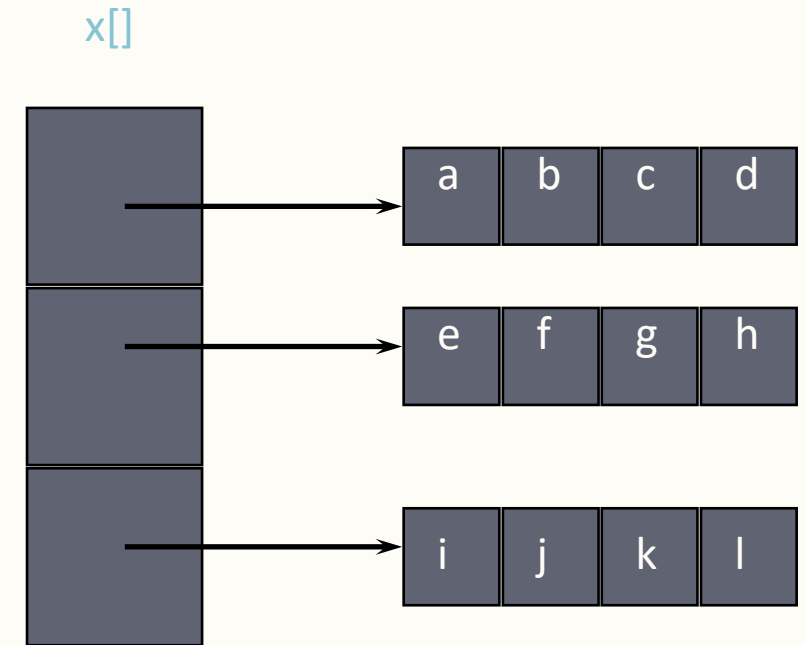
In this representation, a two-dimensional array is represented as a one-dimensional array in which each element is, itself, a one-dimensional array.





# Array of Arrays Representation

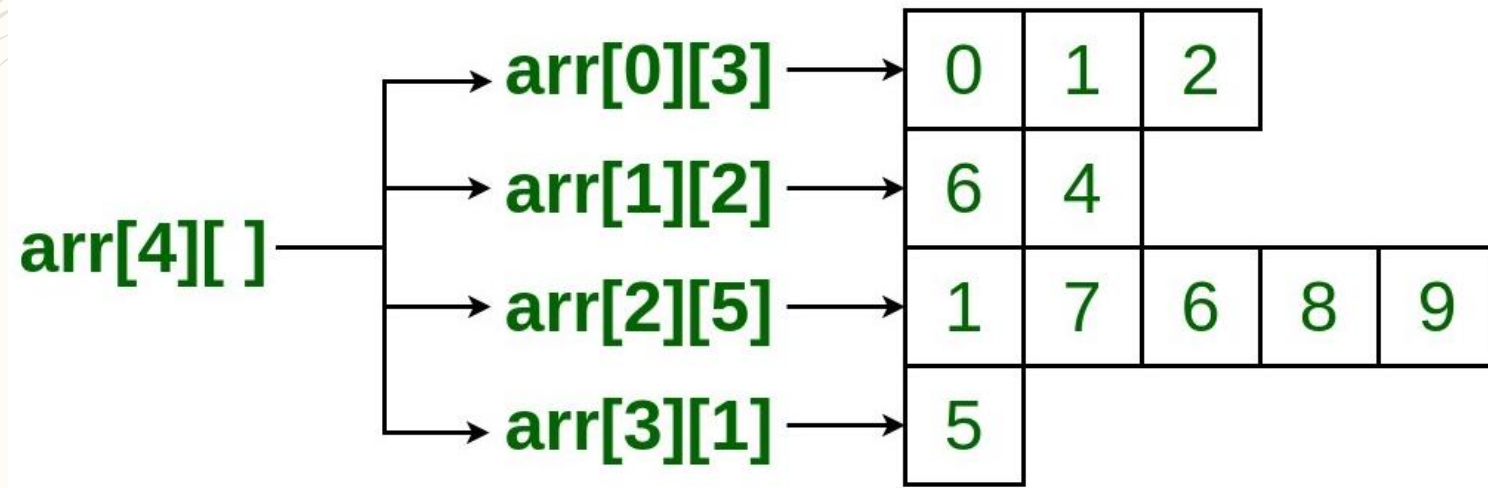
- This representation is called the array-of-arrays representation.
- Requires contiguous memory of size 3, 4, 4, and 4 for the 4 1D arrays.
- 1 memory block of size **number of rows** and **number of rows blocks** of size **number of columns**.



# Irregular Two Dimensional Array

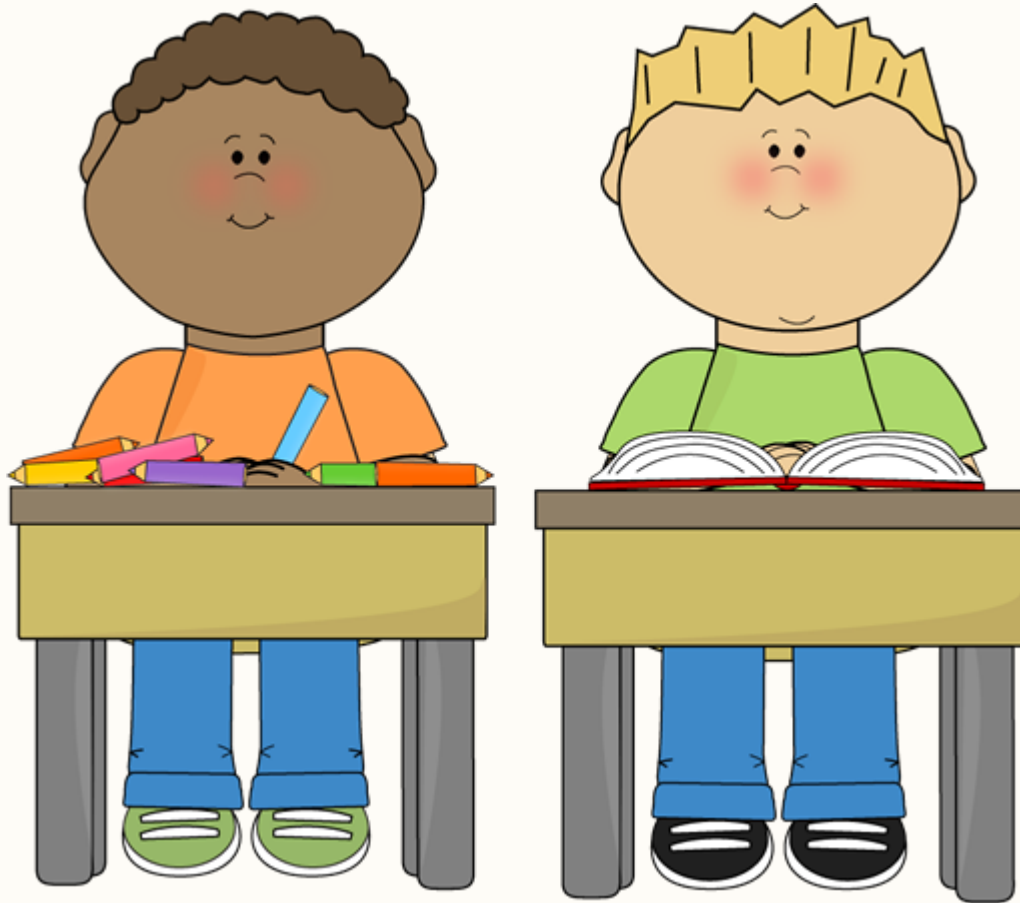
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- When two or more rows have different number of columns.



# Section 7.2.2 – The Class Matrix

## Self Study






# Special Matrices

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- A square matrix has the same number of rows and columns. Some special forms of square matrices are:
  - **Diagonal**:  $M$  is diagonal iff  $M(i,j) = 0$  for  $i \neq j$
  - **Tridiagonal**:  $M(i, j) = 0$  for  $|i-j| > 1$
  - **Lower Triangular**:  $M(i,j) = 0$  for  $i < j$
  - **Upper Triangular**:  $M(i,j) = 0$  for  $i > j$
  - **Symmetric**:  $M(i,j) = M(j,i)$  for all  $i$  and  $j$

# Special Matrices

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$$\begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 0 & 0 & 6 \end{bmatrix}$$

(a) Diagonal

$$\begin{bmatrix} 2 & 1 & 0 & 0 \\ 3 & 1 & 3 & 0 \\ 0 & 5 & 2 & 7 \\ 0 & 0 & 9 & 0 \end{bmatrix}$$

(b) Tridiagonal

$$\begin{bmatrix} 2 & 0 & 0 & 0 \\ 5 & 1 & 0 & 0 \\ 0 & 3 & 1 & 0 \\ 4 & 2 & 7 & 0 \end{bmatrix}$$

(c) Lower triangular

$$\begin{bmatrix} 2 & 1 & 3 & 0 \\ 0 & 1 & 3 & 8 \\ 0 & 0 & 1 & 6 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

(d) Upper triangular

$$\begin{bmatrix} 2 & 4 & 6 & 0 \\ 4 & 1 & 9 & 5 \\ 6 & 9 & 4 & 7 \\ 0 & 5 & 7 & 0 \end{bmatrix}$$

(e) Symmetric

# Diagonal Matrices

```
template<class T>
class diagonalMatrix
{
public:
    diagonalMatrix(int theN = 10);
    ~diagonalMatrix() {delete [] element;}
    T get(int, int) const;
    void set(int, int, const T&);
private:
    int n;          // matrix dimension
    T *element;     // 1D array for diagonal elements
};
```

```
template<class T>
diagonalMatrix<T>::diagonalMatrix(int theN)
{// Constructor.
    // validate theN
    if (theN < 1)
        throw illegalParameterValue("Matrix size must be > 0");

    n = theN;
    element = new T [n];
}
```

Add input() and display()




# Diagonal Matrices get Method

```
template <class T>
T diagonalMatrix<T>::get(int i, int j) const
{
    // Return (i,j)th element of matrix.
    // validate i and j
    if (i < 1 || j < 1 || i > n || j > n)
        throw matrixIndexOutOfBounds();

    if (i == j)
        return element[i-1];    // diagonal element
    else
        return 0;               // nondiagonal element
}
```


# Diagonal Matrices set Method



```
template<class T>
void diagonalMatrix<T>::set(int i, int j, const T& newValue)
{
    // Store newValue as (i,j)th element.
    // validate i and j
    if (i < 1 || j < 1 || i > n || j > n)
        throw matrixIndexOutOfBounds();

    if (i == j)
        // save the diagonal value
        element[i-1] = newValue;
    else
        // nondiagonal value, newValue must be zero
        if (newValue != 0)
            throw illegalParameterValue
                ("nondiagonal elements must be zero");
}
```

# Diagonal Matrices input Method



```
template<class T>
void DiagonalMatrix<T>::input()
{
    T val;
    cout<<"Enter the elements of the Diagonal metric array:\n";
    for(int i=1;i<=n;i++)
    {
        for(int j=1;j<=n; j++)
        {
            cin>>val;
            set(i,j, val);
        }
    }
}
```

# Diagonal Matrices display Method

```
template<class T>
void DiagonalMatrix<T>::display()
{
    cout<<"\nElements of the Diagonal metric array are:\n";
    for(int i=1;i<=n;i++)
    {
        for(int j=1;j<=n; j++)
        {
            T val=get(i,j);
            cout<<val<<"\t";
        }
        cout<<"\n";
    }
}
```



# TriDiagonal Matrices

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- In an  $n \times n$  tridiagonal matrix  $T$ , the nonzero elements lie on one of the 3 diagonals
- **Main Diagonal**  $\rightarrow i = j$
- **Diagonal below main diagonal**  $\rightarrow i = j + 1$
- **Diagonal above main diagonal**  $\rightarrow i = j - 1$
- The total number of elements on these 3 diagonals is  **$3n-2$** .
- Only the elements on the 3 diagonals are explicitly stored in one-dimensional array with  $3n-2$  positions.



# TriDiagonal Matrices

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- Elements can be mapped into one dimensional array
  - **By rows** = [2, 1, 3, 1, 3, 5, 2, 7, 9, 0]
  - **By columns** = [2, 3, 1, 1, 5, 3, 2, 9, 7, 0]
  - **By Diagonals** = [3, 5, 9, 2, 1, 2, 0, 1, 3, 7]

2	1	0	0
3	1	3	0
0	5	2	7
0	0	9	0



# TriDiagonal Matrices get()

```
template <class T>
T tridiagonalMatrix<T>::get(int i, int j) const
{
    // Return (i,j)th element of matrix.

    // validate i and j
    if ( i < 1 || j < 1 || i > n || j > n)
        throw matrixIndexOutOfBounds();

    // determine element to return
    switch (i - j)
    {
        case 1: // lower diagonal
            return element[i - 2];
        case 0: // main diagonal
            return element[n + i - 2];
        case -1: // upper diagonal
            return element[2 * n + i - 2];
        default: return 0;
    }
}
```

# Triangular Matrices

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- In an n-row lower triangular matrix, the nonzero region has one element in row 1, two in row 2, ..., and n in row n.
- In an n-row upper triangular matrix, the nonzero region has n elements in row 1, n-1 in row 2, ... and one in row n.
- In both the cases the total number of elements in the nonzero region is

$$\sum_{i=1}^n i = n(n+1)/2$$

- Both kind of triangular matrices can be stored in an array of size  **$n(n+1)/2$** .

# Triangular Matrices

- Consider element  $L(i,j)$  of a lower-triangular matrix.
- If  $i < j$ , the element is in the zero region.
- If  $i \geq j$ , the element is in the non-zero region.
- In row mapping, the element  $L(i,j)$ ,  $i \geq j$  is preceded by  $\sum_{k=1}^{i-1} k$  nonzero region elements that are in rows 1 through  $i-1$  and  $j-1$  such elements from row  $i$ .
- The total number of nonzero region elements that precede  $L(i,j)$  in a row mapping is  $i(i-1)/2 + j-1$ . This expression also gives the position  $L(i,j)$  in element.

2	0	0	0
5	1	0	0
0	3	1	0
4	2	7	0



# Lower Triangular Matrix set method

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```
template<class T>
void lowerTriangularMatrix<T>::set(int i, int j, const T& newValue)
{
    // Store newValue as (i,j)th element.
    // validate i and j
    if ( i < 1 || j < 1 || i > n || j > n)
        throw matrixIndexOutOfBounds();

    // (i,j) in lower triangle iff i >= j
    if (i >= j)
        element[i * (i - 1) / 2 + j - 1] = newValue;
    else
        if (newValue != 0)
            throw illegalParameterValue
                ("elements not in lower triangle must be zero");
}
```

# Upper Triangular Matrix

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- Similar to Lower Triangular Matrix, the mapping of Upper triangular matrix elements can be obtained. However, in this case, we use column major mapping.
- $L(i, j)$  in a column mapping is  $j(j-1)/2 + i - 1$

2	1	3	0
0	1	3	8
0	0	1	6
0	0	0	0



# Symmetric Matrices

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- An  $n \times n$  symmetric matrix can be represented using a one-dimensional array of size  $n(n+1)/2$  by storing either the lower or upper triangle matrix using one of the schemes for a triangular matrix.
- The elements that are not explicitly stored may be computed from those that are.

2	4	6	0
4	1	9	5
6	9	4	7
0	5	7	0





# Sparse Matrices

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- An  $m \times n$  matrix is said to be sparse if many of its elements are zero.
- A matrix that is not sparse is dense.
- The boundary between a dense and a sparse matrix is not defined.
- Assumption: Sparse matrices with number of nonzero terms less than  $n^2/3$  and in some cases less than  $n^2/5$ .
- Example: A supermarket study, with 1000 customers and 10,000 items. The Purchase  $(i,j)$  matrix stores the quantity of item  $i$  purchased by customer  $j$ . If an average customer buys 20 different items, only about 20,000 of the 10,000,000 matrix entries are nonzero. It may be noted that the distribution of these non-zero entries do not fall into any well defined structure.



# Representation using Linked List

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- The nonzero entries of an irregular sparse matrix may be mapped into a linear list in row major order.
- To reconstruct the matrix structure, we need to record the originating row and column of each nonzero entry.
- So each element of the array into which the sparse matrix is mapped needs to have 3 fields:
  - Row (the row of the matrix entry)
  - Col (the column of the matrix entry)
  - Value (the value of the matrix entry)



# Representation using Linked List

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- For this purpose, we define the struct `matrixTerm` that has three data members. The data type of `row` and `col` is `int` and that of `value` is `T`.
- In addition to storing the nonzero entries of the matrix, we need to store the number of rows and columns in the matrix.

0	0	0	2	0	0	1	0
0	6	0	0	7	0	0	3
0	0	0	9	0	8	0	0
0	4	5	0	0	0	0	0

(a) A  $4 \times 8$  matrix

terms	0	1	2	3	4	5	6	7	8
row	1	1	2	2	2	3	3	4	4
col	4	7	2	5	8	4	6	2	3
value	2	1	6	7	3	9	8	4	5

(b) Its linear list representation



# Space Complexity

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- For the example discussed, we need
  - 8 bytes for storing the number of rows and columns ( 2 ints)
  - $9 * 12$  bytes for storing each nonzero element as term
  - 4 bytes (for a reference to the array terms.elements)
  - Total: 128 bytes
- Conventionally, the array purchase would have required  $10,000,000 * 4 = 40,000,000$  bytes



# Time Complexity

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- The get operation takes
  - $O(\log [\text{number of nonzero entries}])$  time when an array linear list and binary search are used.
- The set operation takes
  - $O(\text{number of nonzero entries})$  time because we may need to move this many entries to make room for the new term.
- Each of these operations take  $\theta(1)$  time using the standard two-dimensional array representation.