

8.41

$$t < 0 \quad V_0 = 100V \quad I_0 = 5A$$

$$\alpha = \frac{1}{2RC} = \frac{1}{2(50)(25 \times 10^{-6})} = \underline{400 \text{ rad/s}}$$

$$\omega_0 = \sqrt{\frac{1}{LC}} = \sqrt{\frac{1}{(160 \times 10^{-3})(25 \times 10^{-6})}} = \underline{500}$$

$$\alpha^2 < \omega_0^2 \Rightarrow \omega_d = \sqrt{500^2 - 400^2} = \boxed{300}$$

8.22

$$\omega_0 = \sqrt{\frac{1}{LC}} = \sqrt{\frac{1}{(25 \times 10^{-3})(62.5 \times 10^{-6})}} = 800 \text{ rad/s}$$

$$\alpha = \frac{1}{2RC} = \frac{1}{25(62.5 \times 10^{-6})} = 640 \text{ rad/s}$$

$$\omega_d = \sqrt{800^2 - 640^2} = 480$$

$$I_F = 2 \text{ A}$$

$$i_L = 2 + B_1' e^{-640t} \cos 480t + B_2' e^{-640t} \sin 480t$$

$$i_L(0) = 2 + B_1' \Rightarrow \omega_d B_2' + \dots (-\alpha B_1') = \frac{d i_L}{dt}(0) = \frac{V_0}{L}$$

$$\boxed{B_1' = -1} \quad \boxed{B_2' = 2.83}$$

$$640 + 480 B_2' = 50/25 \times 10^{-3}$$

$$i_L(t) = 2 - e^{-640t} \cos 480t + 2.83 e^{-640t} \sin 480t \text{ A} \quad t \geq 0$$

$$8.35) t < 0$$

$$U_0 = U_0(0^-) = U_0(0^+) = \frac{3000}{4000} 100 = 75 \text{ V}$$

$$I_0 = i_L(0^-) = i_L(0^+) = 100 \text{ mA}$$

$$t > 0$$

$$\alpha = \frac{1}{2R_L} = \frac{1}{80(25 \times 10^{-6})} = 500 \text{ rad/s}$$

$$\omega_0 = \sqrt{(25 \times 10^{-2})(25 \times 10^{-6})} = 400$$

$$s_{1,2} = -500 \pm \underbrace{\sqrt{500^2 - 400^2}}_{300} = -200, -800$$

same eq. twice

$$[a] \quad i_L = I_F + A_1 e^{-200t} + A_2 e^{-800t} \Rightarrow I_F = 100 \text{ mA}$$

$$i_L(0) = 0,1 + \underbrace{A_1 + A_2}_{0} = 0,1$$

$$\frac{d i_L}{dt}(0) = -200 A_1 - 800 A_2 = \frac{U_0}{L} = \frac{75}{0,25} = 300$$

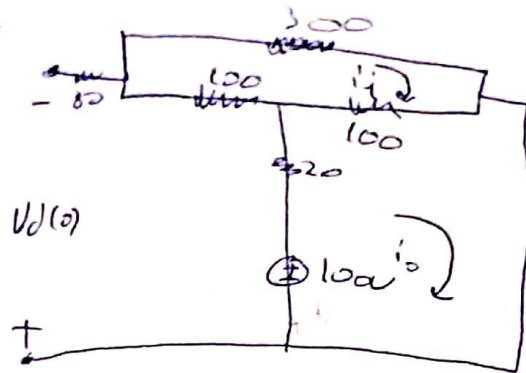
$$\underline{A_1 = 0,5} \quad \underline{A_2 = -0,5}$$

$$i_L(t) = 0,1 + 0,5 e^{-200t} - 0,5 e^{-800t} \text{ A}$$

$$[b] \quad v_L(t) = V_L(t) = L \frac{d i_L}{dt} = (0,25)(-100 e^{-200t} + 400 e^{-800t})$$

$$= -25 e^{-200t} + 100 e^{-800t} \text{ V} \quad t \geq 0$$

847 | $t < 0$



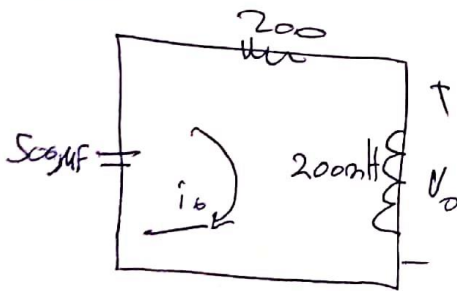
$$500i_1 - 100i_0 = 0 \quad -100i_1 + 120i_0 = 100$$

$$i_1 = 0.2 \text{ A}$$

$$i_0 = 1 \text{ A}$$

$$V_0 = -100 + 20i_0 + 100i_1 = 60 \text{ V}$$

$t > 0$



$$\alpha = \frac{R}{2L} = \frac{200}{2(0.5)} = 500$$

$$\omega_0 = \sqrt{\frac{1}{(0.5)(36.25 \times 10^{-6})}} = 1000$$

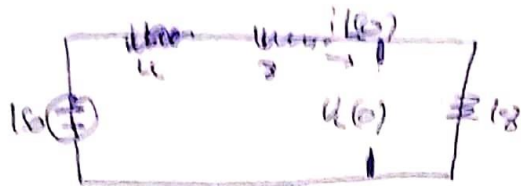
$$s_{1,2} = -100 \pm \sqrt{500^2 - 1000^2}$$

$$= -200 \pm 800 \text{ rad/s}$$

$$i_0 = A_1 e^{-200t} + A_2 e^{-800t}$$

$$i_0(0) = A_1 + A_2 = 1$$

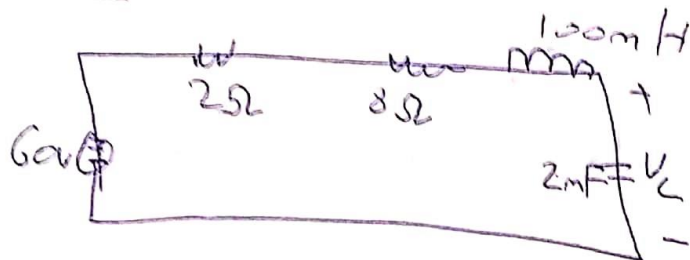
8.54 | 100



$$i(t) = \frac{-150}{30} = -5A$$

$$V_L(t) = 18i(t) = -90V$$

+ > 0



$$\omega = \frac{R}{2L} = \frac{10}{0.2} = 50 \text{ rad/s}$$

$$\omega_0^2 = \frac{1}{0.1(2 \times 10^{-3})} = 5000$$

$$s_{1,2} = -50 \pm \sqrt{50^2 - 5000} = -50 \pm j50$$

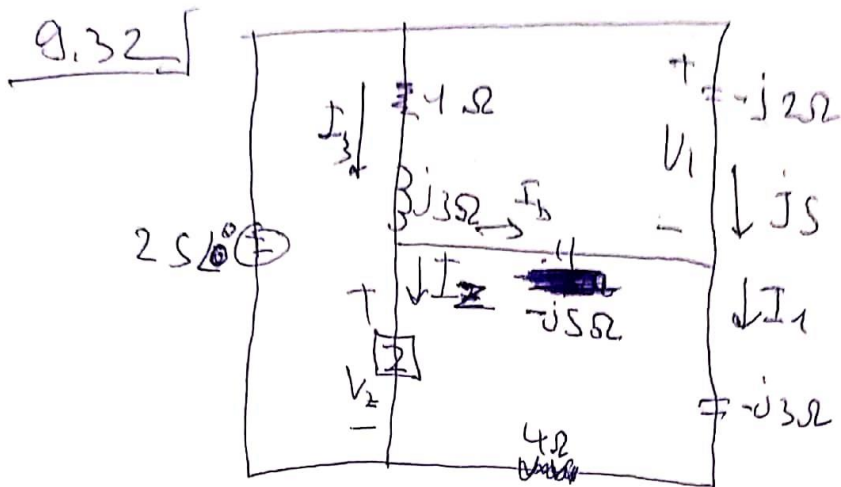
$$V_L = 60 + B_1 e^{-50t} \cos 50t + B_2 e^{-50t} \sin 50t$$

$$V_L(0) = -90 = 60 + B_1 \Rightarrow B_1 = -150$$

$$C \frac{dV_L}{dt}(0) = -5 \quad \frac{dV_L}{dt}(0) = \frac{-5}{2 \times 10^{-3}} = -2500$$

$$-50B_1 + 50B_2 = -2500 \Rightarrow B_2 = -200$$

$$V_L = 60 - 150 e^{-50t} \cos 50t - 200 e^{-50t} \sin 50t \text{ V} \quad + > 0$$



$$V_1 = j5(-j2) = 10V$$

$$-2S \angle 0^\circ + (4 - j3)I_1 = 0 \Rightarrow I_1 = \frac{1S}{4 - j3} = 2.4 + j1.8 A$$

$$I_b = I_1 - j5 = (2.4 + j1.8) - j5 = 2.4 - j3.2 A$$

$$V_2 = -j5I_2 + (4 - j3)I_1 = -j5(2.4 - j3.2) + (4 - j3)(2.4 + j1.8) \\ = -1 - j12V - 2S + (1 + j3)I_3 + (-1 - j12) = 0 \Rightarrow I_3 = 6.2 - j6.6 A$$

$$I_2 = I_3 - I_1 = 3.8 - j3.4 A$$

$$Z = \frac{V_2}{I_2} = 1.42 - j1.88 \Omega$$

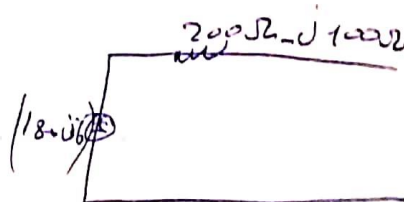
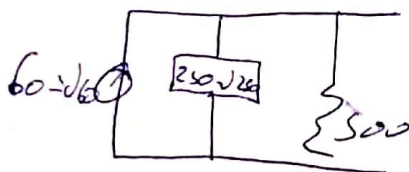
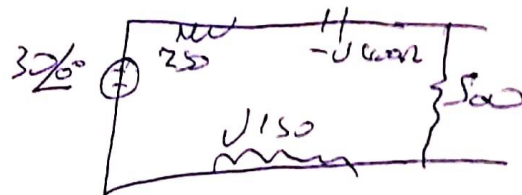
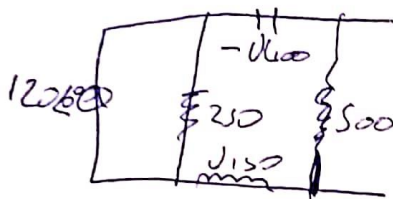
9.45

$$(912/0^\circ) 250 = \underline{300^\circ V}$$

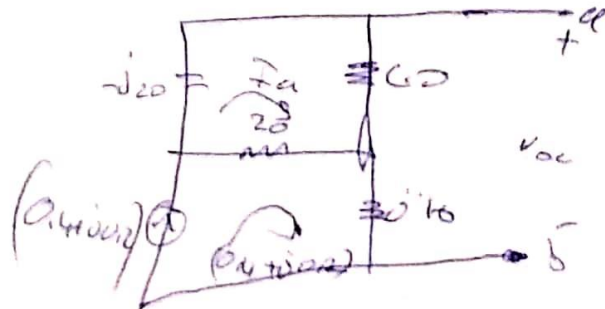
$$250 - j600 + j150 = 250 - j250 \Omega \quad \frac{30/0^\circ}{250 - j250} = \underline{60 - j60 \text{ mA}}$$

$$(250 - j250) \parallel 500 = 200 - j100 \Omega$$

$$(200 - j100)(0.06 + j0.06) = \underline{18 - j6 V}$$



9.46 | OPEN CIRCUIT !

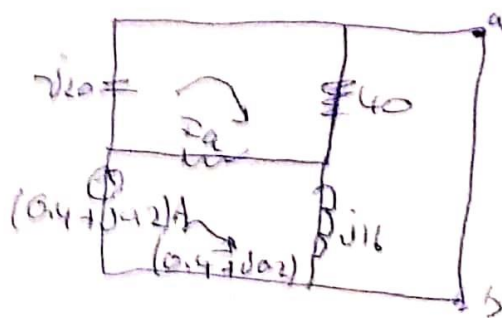


$$-j20I_g + 40I_a + 20(I_a - 0.4 - j0.2) = 0$$

$$I_a = \frac{20(0.4 + j0.2)}{60 - j20} = 0.1 + j0.1 \text{ A}$$

$$V_{OC} = 40I_a + j16(0.4 + j0.2) = 0.8 + j10.4 \text{ V}$$

Short circuit



$$-jI_a + 40(I_a - I_{SC}) + 20(I_a - 0.4 - j0.2) = 0$$

$$40(I_{SC} - I_a) + j16(I_{SC} - 0.4 - j0.2) = 0$$

$$I_{SC} = 0.3 + j0.5 \text{ A}$$

$$\boxed{16 + j8 \Omega}$$

$$Z_{Th} = \frac{V_{Th}}{I_{SC}} = \frac{0.8 + j10.4}{0.3 + j0.5} = \boxed{16 + j8 \Omega}$$

$$\text{Q.55} \quad U_1 \Rightarrow -5\angle 60^\circ + \frac{U_1 - U_2}{-j8} + \frac{U_1 - 20\angle 45^\circ}{-j4} = 0$$

$$U_2 \Rightarrow \frac{U_2 - U_1}{-j8} + \frac{U_2}{j4} + \frac{U_2 - 20\angle 45^\circ}{12} = 0$$

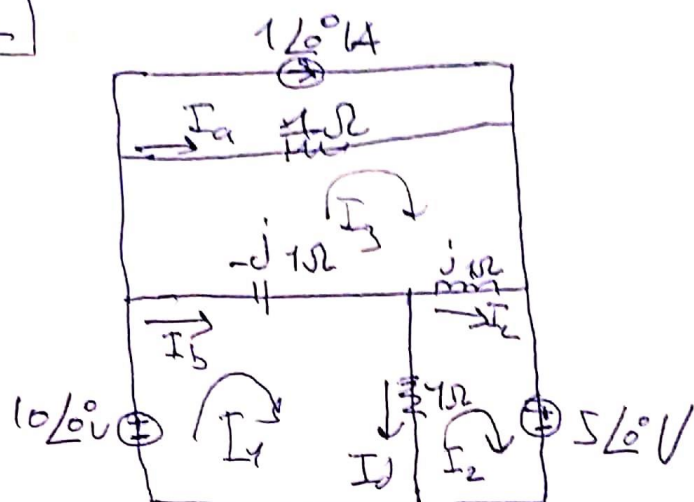
$$U_1 \left(\frac{1}{-j8} + \frac{1}{-j4} \right) + U_2 \left(\frac{-1}{-j8} \right) = 5\angle 60^\circ + \frac{20\angle 45^\circ}{-j4}$$

$$U_1 \left(\frac{1}{+j8} \right) + U_2 \left(\frac{1}{-j8} + \frac{1}{j4} + \frac{1}{12} \right) = \frac{-20\angle 45^\circ}{12}$$

$$U_1 = \frac{-8}{3} + j\frac{4}{3} \quad U_2 = -8 + j4$$

$$V_g = U_1 - 20\angle 45^\circ = -\frac{8}{3} - j\frac{56}{3} \text{ V}$$

9.62



$$10\angle 0^\circ = (1-j1)I_1 - I_2 + jI_3$$

$$\rightarrow 10\angle 0^\circ = I_1 + (1+j1)I_2 - jI_3$$

$$1 = jI_1 - jI_2 + I_3$$

$$\underline{I_1 = 11+j10A}, \underline{I_2 = 11+j5A}, \underline{I_3 = 6A}$$

$$\underline{I_a = I_3 - 5A = 1A}$$

$$\underline{I_b = I_1 - I_3 = 5+j10A}$$

$$\underline{I_c = I_2 - I_3 = 5+j5A}$$

$$\underline{I_d = I_1 - I_2 = j5A}$$