- 1. I have the 8-digit ID number 21703381 which leads to following values for frequency, amplitude, and phase of the three signals which chosen according to the project description and within principal interval.
  - Frequency:  $\omega_0 = 33 \text{ rad/s}$
  - Amplitudes:  $A_1 = 3, A_2 = 8, A_3 = 1$
  - Phase values (degrees):  $\phi_1=33^\circ, \phi_2=-22^\circ, \phi_3=21^\circ$
  - Phase values (radians):  $\phi_1 = 0.576 \text{ rad}$ ,  $\phi_2 = -0.384 \text{ rad}$ ,  $\phi_3 = 0.367 \text{ rad}$
- 2. In order to allow user to type the values I used the input () command. Following is the MATLAB section to take user input for Part (i).

```
% Part (i)

% read user input

omega_0 = input('Enter the omega_0 value: ');

A1 = input('Enter the A1 value: ');

A2 = input('Enter the A2 value: ');

A3 = input('Enter the A3 value: ');

phi_1 = input('Enter the phi_1 value (deg): ');

phi_2 = input('Enter the phi_2 value (deg): ');

phi_3 = input('Enter the phi_3 value (deg): ');
```

3. Following is the MATLAB section to perform calculations for finding the amplitude A and phase  $\phi$  of the phasor addition. Steps well documented in the code section. First the polar representation obtained from the Amplitude and phase the user provides, then the polar representation converted back to the Cartesian representation to easily add up the real and imaginary parts. Final step was converting back to the polar representation which yield the signal with Amplitude: 10.9134, phase: -5.2815 for my university id.

```
%% Part (ii)
1
2
    % (a) represent signals as phasors
3
    X_1p = A1 * exp(1i*degree_to_radian(phi_1));
4
    X_2p = A2 * exp(1i*degree_to_radian(phi_2));
5
    X_3p = A3 * exp(1i*degree_to_radian(phi_3));
6
    % (b) convert back to the rectangular form
8
    X_1r = to_cartesian(A1, phi_1);
9
    X_2r = to_cartesian(A2, phi_2);
10
    X_3r = to_cartesian(A3, phi_3);
11
12
    % (c) add the real and imaginary parts
13
    X = X_1r + X_2r + X_3r;
14
15
    % (d) convert back to the polar
16
    X_polar = to_polar(X);
17
```

4. Resulting sinusoidal:  $x(t) = 10.91\cos(33.00t - 0.09)$ 

```
% Part (iii)

% resulting sinusoidal
fprintf('Resulting sinusoidal: ');
print_signal(X_polar(1,1), omega_0, degree_to_radian(X_polar(1,2)));
```

5. Following is the code section where I represent the phasor addition geometrically. It plots phasors of the three sinusoidal signals together with the resulting phasor on the complex z plane with real horizontal and imaginary vertical axes.

```
%% Part (iv)
1
2
    % define vectors
3
    res_phasor = (X_res);
4
    phasors = [X_1p; X_2p; X_3p];
5
    % Plot
7
    figure;
    plot(real(phasors), imag(phasors), '->','LineWidth',1)
    hold on
10
    plot(real(res_phasor), imag(res_phasor), '->','LineWidth',3.5)
11
    hold off
12
    xlim([-30 \ 30]);
13
    ylim([-30 \ 30]);
14
    title('Part (iv): phasor addition plot');
15
16
    xlabel('Real part');
    ylabel('Imaginary part');
17
    grid on;
```

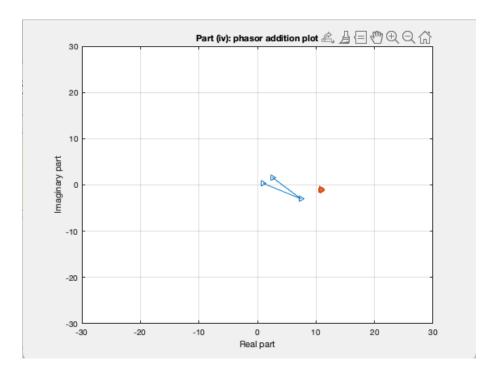


Figure 1: Geometric representation of the phasor addition

6. Following is the code section where I represent the phasor addition geometrically by adding up phasors end to end. To achieve adding vectors end to end I used the step-wise vectorsum via using the MATLAB command. cumsum().

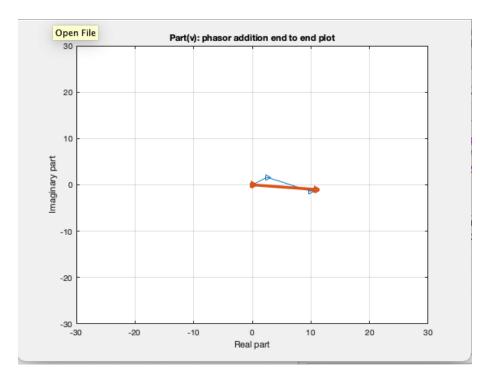


Figure 2: Adding three phasors end to end to demonstrate phasor addition

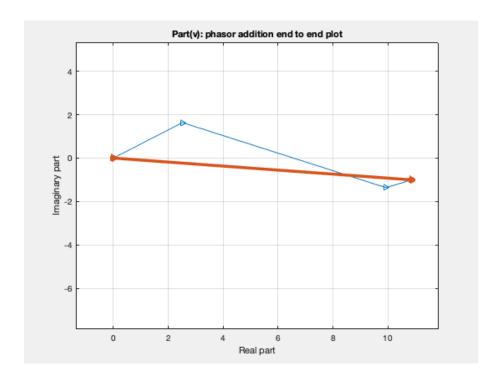


Figure 3: Figure 2 scaled.

## 7. Appendix

## The MATLAB codes

```
%% ASSIGNMENT 1
    % Author: Zeynep CANKARA
2
    % Course: EEE391 Signals and Systems
    %% Helpers
5
    % degree to radian
    degree_to_radian = @(deg) (deg * pi / 180);
    % radian to degree
    radian_to_degree = @(rad) (rad * 180 / pi);
    % to cartesian
    to_cartesian = @(len, deg) len .* exp(1i * degree_to_radian(deg));
11
    % to polar
12
    to_polar = @(num) [abs(num) radian_to_degree(angle(num))];
13
14
15
    %% Part (i)
16
17
    % read user input
18
    omega_0 = input('Enter the omegao value: ');
19
    A1 = input('Enter the A1 value: ');
20
    A2 = input('Enter the A2 value: ');
21
     A3 = input('Enter the A3 value: ');
```

```
phi_1 = input('Enter the phi1 value (deg): ');
    phi_2 = input('Enter the phi2 value (deg): ');
    phi_3 = input('Enter the phi3 value (deg): ');
^{25}
    %% Part (ii)
27
    % (a) represent signals as phasors
    X_1p = A1 * exp(1i*degree_to_radian(phi_1));
    X_2p = A2 * exp(1i*degree_to_radian(phi_2));
    X_3p = A3 * exp(1i*degree_to_radian(phi_3));
    % (b) convert back to the rectangular form
    X_1r = to_cartesian(A1, phi_1);
35
    X_2r = to_cartesian(A2, phi_2);
37
    X_3r = to_cartesian(A3, phi_3);
38
    % (c) add the real and imaginary parts
39
    X = X_1r + X_2r + X_3r;
40
41
    % (d) convert back to the polar
42
    X_polar = to_polar(X);
43
44
    X_res = X_polar(1,1) * exp(1i*degree_to_radian(X_polar(1,2)));
45
46
47
     % Report A and phi values
48
    fprintf('A: %.4f, phi: %.4f \n', X_polar(1,1), X_polar(1,2));
49
50
    %% Part (iii)
51
52
    % resulting sinusoidal
53
    fprintf('Resulting sinusoidal: ');
54
    print_signal(X_polar(1,1), omega_0, degree_to_radian(X_polar(1,2)));
55
56
     %% Part (iv)
57
58
    % define vectors
59
    res_phasor = (X_res);
60
    phasors = [X_1p; X_2p; X_3p];
61
62
    % Plot
63
    figure;
64
    plot(real(phasors), imag(phasors), '->','LineWidth',1)
65
66
    plot(real(res_phasor), imag(res_phasor), '->','LineWidth',3.5)
67
    hold off
68
    xlim([-30 \ 30]);
69
    ylim([-30 \ 30]);
70
```

```
title('Part (iv): phasor addition plot');
     xlabel('Real part');
72
     ylabel('Imaginary part');
73
     grid on;
74
     %% Part (v)
76
77
     % define vectors
     phasors = cumsum([X_1p; X_2p; X_3p]);
     res_phasor = [0; res_phasor];
     phasors = [0; phasors]; % concat with origin as starting point
     % Plot
 83
     figure;
     plot(real(phasors), imag(phasors), '->','LineWidth',1)
     hold on
     plot(real(res_phasor), imag(res_phasor), '->','LineWidth',3.5)
 87
     hold off
 88
     xlim([-30 \ 30]);
 89
     ylim([-30 \ 30]);
90
     title('Part(v): phasor addition end to end plot');
91
     xlabel('Real part');
92
     ylabel('Imaginary part');
93
     grid on;
94
95
96
      %% Function declerations
97
     function print_signal(A, omega_0, phi)
98
          if phi < 0</pre>
99
              fprintf('x(t) = \%.2f cos(\%.2ft - \%.2f)\n', A, omega_0, abs(phi));
100
          else
101
              fprintf('x(t) = \%.2f cos(\%.2ft + \%.2f)\n', A, omega_0, phi);
102
103
          end
104
      end
```

The output dumps, contains screen shot of the workspace and command window

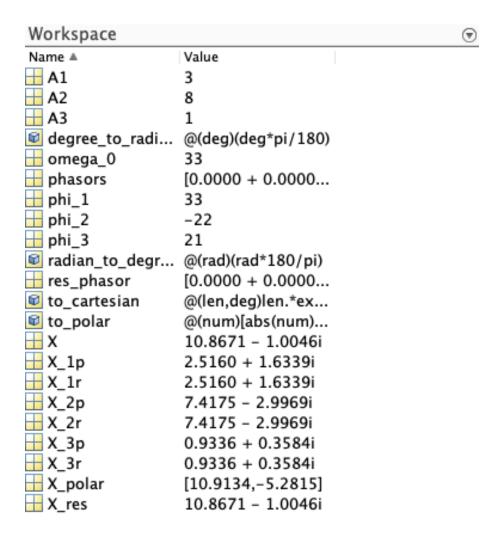


Figure 4: Workspace

```
Command Window

>> eee391_hw1
Enter the ωo value: 33
Enter the A1 value: 3
Enter the A2 value: 8
Enter the A3 value: 1
Enter the φ1 value (deg): 33
Enter the φ2 value (deg): -22
Enter the φ3 value (deg): 21
A: 10.9134, φ: -5.2815
Resulting sinusoidal: x(t) = 10.91 cos(33.00t - 0.09)

fx
>>
```

Figure 5: Command Window