# [Image Processing project]

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#### **Edits in this Document**

- Apply Filter on color images
- Using Data Store for retrieving images
- Compare between color and grayscale pages results (9 10)



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### **Table of Contents**

HISTOGRAM Equalization Abstract	2
Histogram Equalization Code	2
difference of gaussian Abstract	3
difference of gaussian Code	4
MSR Filter	5
MSR Filter Code	6
PSNR	7
SSIM	8
SSIM Code	10
Images	11
Charts	20

### [ Histogram Equalization]

#### **Abstract:**

histogram equalization is a method in image proccessing baesd on histogram of an image. it is used especially when the image is represented by a narrow range of intensity values. its main functionality is to make the image's pixels have better distributed on the histogram.c

### [ difference of gaussian (DOG) ]

#### **Abstract:**

In order to explain the DOG filter, we should first explain gaussian filter.

Gassian filter is based on the mathematical concept of the Gaussian function, which is a bell-shaped curve.

$$G(x,y) = \frac{1}{2\pi\sigma^2} e^{-\frac{x^2+y^2}{2\sigma^2}}$$

- $\bullet \pi$  is the mathematical constant pi (approximately 3.14159).
- $ullet \sigma$  is the standard deviation of the Gaussian distribution, controlling the spread of the curve.
- •e is the mathematical constant Euler's number (approximately 2.71828).
- $\bullet$ G(x,y) is the value of the 2D Gaussian function at position (x,y)

The primary purpose of applying a Gaussian filter to an image is to reduce noise by smoothing the image

Now let us explain GOG filter:

The Difference of Gaussians (DoG) filter is used in image processing to enhance edges and identify features at different scales.

It is obtained by subtracting one blurred version of an image from another, where each version is created using a Gaussian filter with a different standard deviation.

### [ MSR Filter ]

#### **Abstract:**

The Multiscale Retinex algorithm is an image enhancement technique that aims to improve the contrast of an image by normalizing pixel values across different scales. The algorithm operates by applying a series of operations at multiple scales.

1- define some parameters for applying the algorithm

sigma: the standard deviation for the Gaussian filter.

scales: the scales at which the MSR algorithm operates.

filt size: the size of the Gaussian filter.

enhanced: a matrix filled with zeros which will accumulates the Retinex components of the image.

- 2- iterate through each scale specified in scales and do the following:
- apply the Gaussian Filter to the image at the current scale (Which was explained in the DOG filter).
  - calculate the Retinex component for the current scale.
  - accumulate the Retinex component to %enhanced%
- 3- Normalize the enhanced image to the range [0, 255] and convert it back to uint8

### [PSNR]

#### **Abstract:**

The PSNR block computes the peak signal-to-noise ratio, in decibels, between two images. This ratio is used as a quality measurement between the original and a compressed image. The higher the PSNR, the better the quality of the compressed, or reconstructed image.

 $PSNR = 10log10((L-1)^2/MSE$ 

Here, L is the number of maximum possible intensity levels (minimum intensity level suppose to be 0) in an image.

$$MSE = 1/m*n \Sigma\Sigma(O(i,j)-D(i,j))^2$$

Where, O represents the matrix data of original image. D represents the matrix data of degraded image. m represents the numbers of rows of pixels and i represents the index of that row of the image. n represents the number of columns of pixels and j represents the index of that column of the image.

### [SSIM]

#### **Abstract:**

Structural Similarity Index is a metric used to measure the similarity between two images. SSIM takes into account luminance, contrast, and structure, which are important aspects of human perception. The index produces a value between -1 and 1, where 1 indicates perfect similarity, -1 indicates perfect dissimilarity, and 0 means no similarity.

SSIM is widely used in image processing and computer vision to evaluate the quality of compressed images, assess the impact of image processing algorithms, or compare the similarity between an original image and a processed one. It provides a more comprehensive assessment than traditional metrics like Mean Squared Error (MSE), as it considers both global and local variations in image structure.

$$c(x,y) = rac{2\sigma_x\sigma_y + c_2}{\sigma_x^2 + \sigma_y^2 + c_2}$$

$$s(x,y) = rac{\sigma_{xy} + c_3}{\sigma_x \sigma_y + c_3}$$

$$l(x,y) = rac{2\mu_x \mu_y + c_1}{\mu_x^2 + \mu_y^2 + c_1}$$

contrast structure luminance

#### Code:

```
input=datastore("dataset");
gaussian1 = fspecial('Gaussian', 10, 1.07);
gaussian2 = fspecial('Gaussian', 10, 1);
dog = gaussian1 - gaussian2;
sigma = 5;
scales = [15, 80, 250];
filt size = 2 * ceil(3 * sigma) + 1;
Psnr histo=0;
Psnr MSR=0;
Psnr DoG=0;
SSIM histo=0;
SSIM MSR=0;
SSIM DoG=0;
for i=1:length(input.Files)
   img=input.read();
   img=rgb2ycbcr(img);
   img2=img;
   GravLevel=img(:,:,1);
   HistImage=histeg(GrayLevel);
   img(:,:,1) = HistImage;
   imwrite(ycbcr2rgb(img),['Histogram/img' int2str(i) '.jpg']);
   Psnr histo=Psnr histo+psnr(imq,imq2);
   SSIM histo=SSIM histo+ssim(img,img2);
   disp (['psnr for image ' int2str(i) ' after apply Histogram equalization equals
to ' num2str(psnr(img,img2))]);
   disp (['ssim for image ' int2str(i) ' after apply Histogram equalization equals
to ' num2str(ssim(img,img2))]);
   DoGImage=conv2(double(GrayLevel), dog, 'same');
   DoGImage=uint8(255*DoGImage);
   imq(:,:,1) = DoGImage;
   imwrite(ycbcr2rqb(imq),['DOG/imq' int2str(i) '.jpq']);
   Psnr DoG=Psnr DoG+psnr(img,img2);
   SSIM DoG=SSIM DoG+ssim(img,img2);
   disp (['psnr for image ' int2str(i) ' after apply DoG equals to '
num2str(psnr(img,img2))]);
   disp (['ssim for image ' int2str(i) ' after apply DoG equals to '
num2str(ssim(imq,imq2))]);
```

```
Img = double(GrayLevel);
   enhanced = zeros(size(Img));
   for j = 1:length(scales)
       gaussian filter = fspecial(<mark>'gaussian'</mark>, [filt size, filt size], sigma *
scales(j));
       blurred image = imfilter(Img, gaussian filter, 'conv');
       retinex component = log(Img + 1) - log(blurred image + 1);
       enhanced = enhanced + retinex component;
   end
   enhanced = uint8( (enhanced - min(enhanced(:))) / (max(enhanced(:)) -
min(enhanced(:))) * 255);
   img(:,:,1) = enhanced;
   imwrite(ycbcr2rgb(img),['MSR/img' int2str(i) '.jpg']);
   Psnr MSR=Psnr MSR+psnr(img,img2);
   SSIM MSR=SSIM MSR+ssim(img,img2);
   disp (['psnr for image ' int2str(i) ' after apply MSR equals to '
num2str(psnr(img,img2))]);
   disp (['ssim for image ' int2str(i) ' after apply MSR equals to '
num2str(ssim(img,img2))]);
   end
Psnr MSR=Psnr MSR/length(input.Files);
Psnr DoG=Psnr DoG/length(input.Files);
Psnr histo=Psnr histo/length(input.Files);
SSIM MSR=SSIM MSR/length(input.Files);
SSIM DoG=SSIM DoG/length(input.Files);
SSIM histo=SSIM histo/length(input.Files);
disp(['average Psnr for histogram equalization is ' num2str(Psnr histo)]);
disp(['average Psnrfor MSR is ' num2str(Psnr MSR)]);
disp(['average Psnr for DoG is ' num2str(Psnr DoG)]);
disp(['average ssim for histogram equalization is ' num2str(SSIM histo)]);
disp(['average ssim for MSR is ' num2str(SSIM MSR)]);
disp(['average ssim for DoG is ' num2str(SSIM DoG)]);
```

## [ Image Number 1 - grayscale ]

Original image

ilters



histogram equalization



difference of gaussian



MSR Filter

PSNR

PSNR: 18.37 dB

PSNR: 6.44 dB

PSNR: 15.28 dB

SSIM

hist: 0.8719

-0.0335

# [ Image Number 1 – colored ]

Original image





histogram equalization



difference of gaussian



MSR Filter

PSNR: 21.5347 dB PSNR: 11.9755 dB PSNR: 20.7709 dB

SSIM

0.84837

0.22967

## [ Image Number 2 ]

Original image



Filters



histogram equalization



difference of gaussian



MSR Filter

PSNR: 17.33 dB

PSNR: 4.37 dB

PSNR: 11.53 dB

SSIM

0.7424

-0.0421

## [Image Number 3]

Original image



Filters



histogram equalization



difference of gaussian



MSR Filter

SNF

PSNR: 11.41 dB

PSNR: 8.11 dB

PSNR: 7.93 dB

SSIM

0.7316

-0.0752

## [ Image Number 4 ]

Original image



Filters



histogram equalization



difference of gaussian



MSR Filter

SNF

PSNR: 19.16 dB

PSNR: 5.44 dB

PSNR: 11.27 dB

SSIM

0.8787

-0.0754

## [ Image Number 5 ]

Original image



Filters



histogram equalization



difference of gaussian



MSR Filter

SNR

PSNR: 11.81 dB

PSNR: 8.13 dB

PSNR: 8.36 dB

SSI

0.4913

0.0092

## [ Image Number 6 ]

Original image



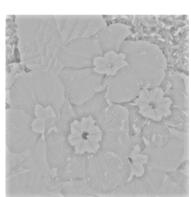
Iters



histogram equalization



difference of gaussian



MSR Filter

PSNF

PSNR: 18.18 dB

PSNR: 5.68 dB

PSNR: 11.53 dB

SSIM

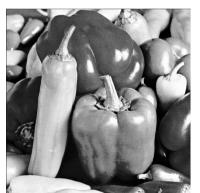
0.7822

-0.0814

## [ Image Number 7 ]

Original image

ilters



histogram equalization



difference of gaussian



MSR Filter

PSNF

PSNR: 20.99 dB

PSNR: 5.73 dB

PSNR: 10.86 dB

SSIM

0.8863

-0.0452

## [ Image Number 8 ]

Original image



Filters



histogram equalization



difference of gaussian



MSR Filter

PSNR: 13.73 dB

PSNR: 5.46 dB

PSNR: 10.71 dB

SSIM

0.8749

-0.0861

## [Image Number 9]

Original image



Filters



histogram equalization



difference of gaussian



MSR Filter

PSNR: 21.98 dB

PSNR: 4.83 dB

PSNR: 10.63 dB

0.8343

-0.0295

## [ Image Number 10 ]

Original image





histogram equalization



difference of gaussian



MSR Filter

PSNR: 20.40 dB

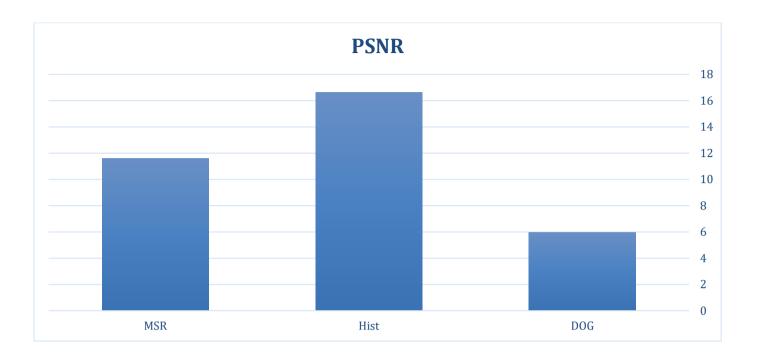
PSNR: 4.82 dB

PSNR: 11.27 dB

0.8218

-0.1541

	DOG	Hist	MSR
PSNR	5.97	16.6246	11.6054



	DOG	Hist	MSR
SSIM	-0.0811	0.7583	0.713

