

# IEMS 304 Lecture 5: Non-linear and Non-parametric Regression

---

Yiping Lu

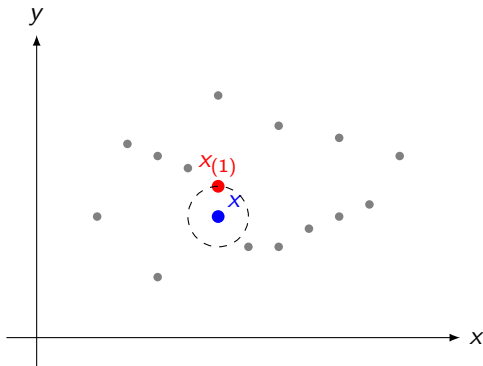
yiping.lu@northwestern.edu

*Industrial Engineering & Management Sciences  
Northwestern University*



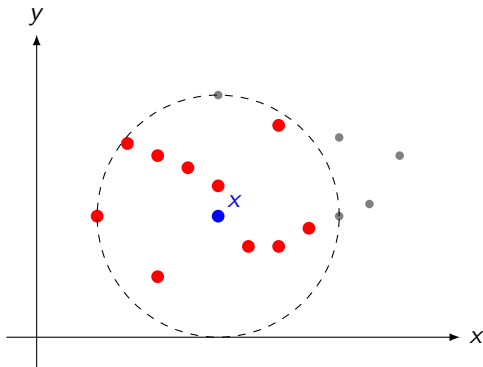
## k-NN Regression ( $k = 1$ )

$$\hat{f}(x) = y_{(1)}$$



## k-NN Regression ( $k = 10$ )

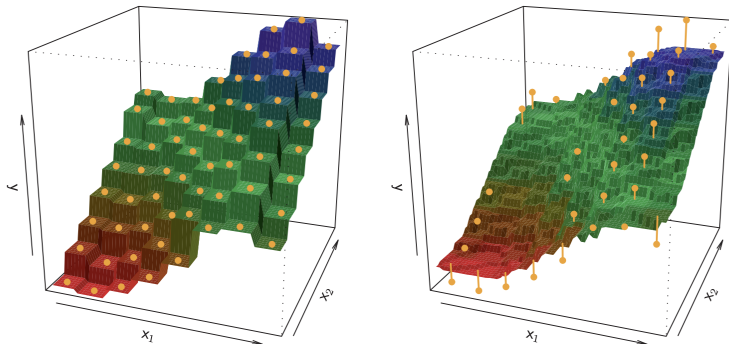
$$\hat{f}(x) = \frac{1}{10} \sum_{i=1}^{10} y_{(i)}$$



“A precise and universally acceptable definition of the term ‘nonparametric’ is not presently available. The viewpoint adopted in this handbook is that a statistical procedure is of a nonparametric type if it has properties which are satisfied to a reasonable approximation when some assumptions that are at least of a moderately general nature hold.”

– The Handbook of Nonparametric Statistics

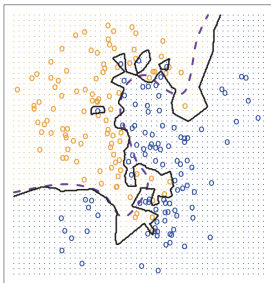
# Bias and Variance Trade-off



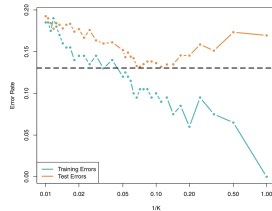
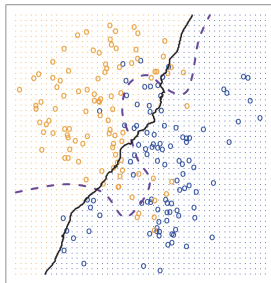
**FIGURE 3.16.** Plots of  $\hat{f}(X)$  using KNN regression on a two-dimensional data set with 64 observations (orange dots). Left:  $K = 1$  results in a rough step function fit. Right:  $K = 9$  produces a much smoother fit.

# Bias and Variance Trade-off

KNN:  $K=1$

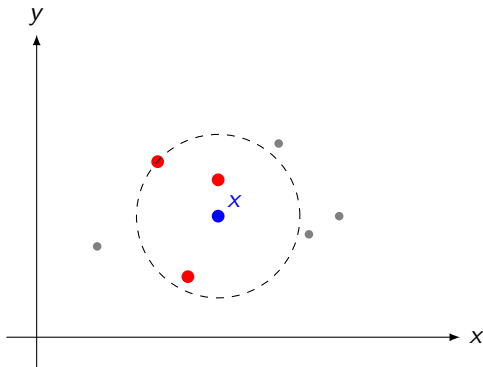


KNN:  $K=100$



## k-NN Regression with Limited Data (k=3)

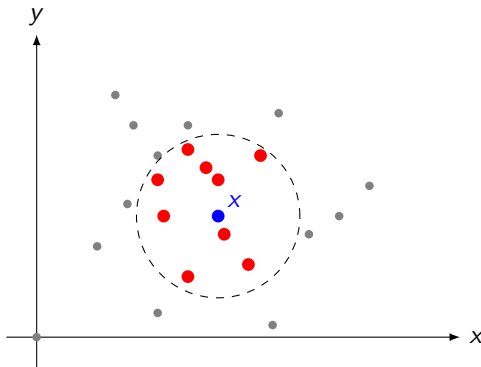
$$\hat{f}(x) = \frac{1}{3} \sum_{i=1}^3 y_{(i)}$$



## k-NN Regression with More Data

Use the same size of neighborhood, now we have 10 data in the circle

- ❑ How is bias changing? How is variance changing?
- ❑ How should we do bias-variance trade-off?

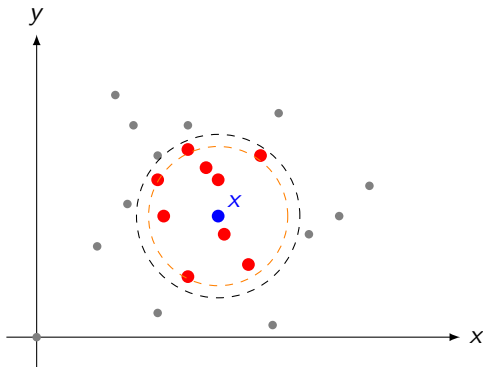




## k-NN Regression with More Data

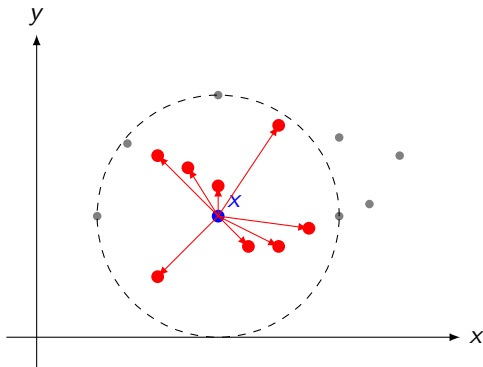
Use the same size of neighborhood, now we have 10 data in the circle

- ❑ How is bias changing? How is variance changing?
- ❑ How should we do bias-variance trade-off?

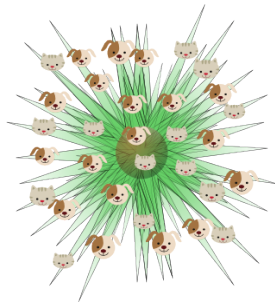
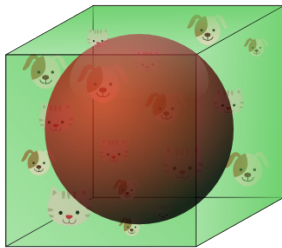
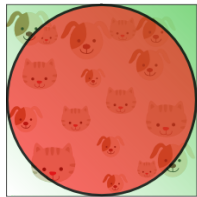


# Local Kernel Smoothing: Nadaraya-Watson Estimator

$$\hat{f}(x) = \frac{\sum_{i=1}^n K_h(x - x_i) y_i}{\sum_{i=1}^n K_h(x - x_i)}$$



# Curse of Dimensionality



# Nonlinear Regression Models

---

# Nonlinear Regression Model

A general form of nonlinear regression model is  $Y_i = g(x_i; \beta) + \epsilon_i$ , where

- $Y_i$ : response for observation  $i$ ;
- $x_i$ : vector of predictors for observation  $i$ ;
- $\beta$ : vector of model parameters;
- $g(x_i; \beta)$ : some parametric nonlinear function;
- $\epsilon_i$ : zero-mean random error for observation  $i$ .

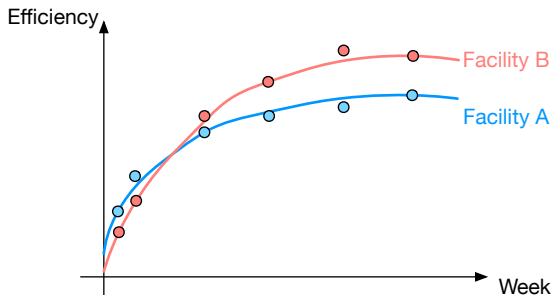
---

We will see shortly that if the random errors are **Gaussian** and independent of  $x$ , the MLE of  $\beta$  is just nonlinear least squares.

# Example of Manufacturing Learning Curve

- Two facilities operate with (different) efficiency as a function of time.
- We denote  $Y$  as the relative efficiency of operation. The predictor variables are

- $x_1 = \begin{cases} 1, & \text{facility B (modern)} \\ 0, & \text{facility A (old)} \end{cases};$
- $x_2 = \text{number of weeks.}$



# Questions and Discussions

- For facility A, and the data looked like in the previous slide, how would you model it?
- Facilities A and B have different asymptotic efficiencies, how would you modify the model?
- If facilities A and B have different learning rates, how would you modify the model?
- If the objective was to determine if the two facilities have different asymptotic efficiencies, how could you do this?

*Hint:* Play with the model  $Y = \beta_0 + \beta_3 \exp(\beta_2 x_2) + \epsilon$ .

# MLE for General Nonlinear Regression Model

Nonlinear model  $Y_i = \underbrace{g(x_i; \beta)}_{:=\mu_i} + \epsilon_i$  with  $\epsilon_i \sim N(0, \sigma^2)$ .

Now we view  $x_i$  as deterministic, not random.

- Accordingly, the nonlinear model becomes  $Y_i = \mu_i + \epsilon_i$ .
- Marginal pdf of  $Y_i$  is  $f(y_i; \beta, \sigma) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{1}{2\sigma^2}(y_i - \mu_i)^2\right)$ .

What is the Max-likelihood Estimator?



# Maximizing Likelihood Function

Joint pdf (a.k.a. the likelihood function) of  $Y_1, \dots, Y_n$  is

$$f(y; \beta, \sigma) = \frac{1}{(2\pi)^{n/2} \sigma^n} \exp\left(-\frac{1}{2\sigma^2} \sum_{i=1}^n (y_i - \mu_i)^2\right).$$

We want to  $\max_{\beta, \sigma} f(y; \beta, \sigma) = \max_{\beta, \sigma} \frac{1}{\sigma^n} \exp\left(-\frac{1}{2\sigma^2} \sum_{i=1}^n (y_i - \mu_i)^2\right)$ .

Some inspection suggests that for  $\beta$ , it suffices to

$$\min_{\beta} \sum_{i=1}^n (y_i - \mu_i)^2 = \min_{\beta} \sum_{i=1}^n (y_i - \mu_i)^2. \quad \text{log-likelihood}$$

That is, the MLE of  $\beta$  for the general nonlinear regression model with i.i.d. Gaussian errors (that are independent of  $x$ ) is “nonlinear least squares”.

How to compute  $\beta$ ? Optimization!

# Summary of Steps in General MLE

- ❑ Write out the form of the statistical model that you are using to represent the data.
- ❑ Find the marginal distribution of each individual observation  $Y_i$  (for regression problems the  $x_i$ 's are not treated as random, so you only need to find the marginal distribution of the  $Y_i$ 's given the  $x_i$ 's).
- ❑ From the marginal distributions in step (2), find the joint distribution  $f(Y; \theta)$  of the entire set of data  $Y$ . Here  $\theta$  denotes all the parameters.

---

If tractable, find an analytical expression for the  $\theta$  that maximizes the likelihood  $f(Y; \theta)$ . Otherwise, use numerical optimization software to minimize  $-\log f(Y; \theta)$ .

- R has several built-in commands for nonlinear regression such as `nlm` and `nls` (a little buggier than `nlm`).
- For the manufacturing learning curve example, we read data in `MLC.csv`.
- The following code snippet is for nonlinear regression on `MLC.csv`.

```
MLC<-read.table("MLC.csv",sep=";",header=TRUE)
x1<-MLC$Location;x2<-MLC$Week;y<-MLC$Efficiency
fn <- function(p) {yhat<-p[1]+p[2]*x1+p[4]*exp(p[3]*x2); sum((y-yhat)^2)}
out<-nlm(fn,p=c(1,0,-.5,-.1),hessian=TRUE)
theta<-out$estimate #parameter estimates
```

## Example: Gaussian Distribution with Learned Variance

The likelihood function of a Gaussian distribution is given by:

$$P(y_i | \mu(x_i), \sigma(x_i)^2) = \frac{1}{\sqrt{2\pi \sigma(x_i)^2}} \exp\left(-\frac{(y_i - \mu(x_i))^2}{2 \sigma(x_i)^2}\right)$$

$$\begin{aligned}\ell(\mu, \sigma^2) &= \sum_{i=1}^n \log P(y_i | \mu(x_i), \sigma(x_i)^2) \\ &= \sum_{i=1}^n \left( -\frac{1}{2} \log(2\pi) - \frac{1}{2} \log(\sigma(x_i)^2) - \frac{(y_i - \mu(x_i))^2}{2\sigma(x_i)^2} \right) \\ &= -\frac{n}{2} \ln(2\pi(x_i)) - \underbrace{\frac{n}{2} \ln(\sigma(x_i)^2)}_{\text{sparse regularization}} - \underbrace{\sum_{i=1}^n \frac{(y_i - \mu(x_i))^2}{2\sigma(x_i)^2}}_{\text{weighted } \ell_2 \text{ loss}}\end{aligned}$$

## Another Example: Weibull Distribution

The likelihood function of a Weibull distribution is given by:

$$p_k(x|\lambda) = \frac{k}{\lambda} \left(\frac{x}{\lambda}\right)^{k-1} e^{-(x/\lambda)^k}$$

, where  $1 > k > 0$  is the shape parameter and  $\lambda > 0$  is the scale parameter.

---

$$\log p_k(y|\lambda(x)) = -(y/\lambda(x))^k - k \log \lambda(x) + \underbrace{\log(ky^{k-1})}_{\text{not dependent on the prediction } \lambda(x)}$$

**Fact.**  $f(y, \lambda)$  attains its minimum at  $\lambda = y$ .

# Non-parametric Statistical Inference

---

# Statistical Uncertainty in Supervised Learning

- With nonlinear regression models, the formulae for assessing statistical uncertainty in linear regression (e.g.,  $F$ -tests and  $t$ -tests for significance of predictors, SEs and CIs for parameters, PIs and CIs for new observations, etc.) do not apply directly.
  - Question: Why might we want to calculate SEs, CIs/PIs, do hypothesis tests, etc?
- For some nonlinear models, we can use approximate **asymptotic analytical results** valid for sufficiently large sample size  $n$  to assess statistical uncertainty.
- Fortunately, we have alternative **computational approaches** that apply to any nonlinear model:
  - **Cross-validation** for deciding which models are the best.
  - **Bootstrap resampling** (or **bootstrapping** for short) for SEs and CIs on the parameters and CIs and PIs on new observations.

# Overview of Bootstrapping

**Objective:** Estimate the sampling distribution of  $\hat{\theta}$  and quantities like  $SE(\hat{\theta})$  that are derived from it.

- ❑ You are given a sample of data of size  $n$  observations.
- ❑ You have estimated some parameter(s)  $\theta$  (call it  $\hat{\theta}$ ).

---

**Problem:** Hypothetically, if we knew the form of the population distribution, we could consider using simulation to draw many random samples (each of size  $n$ ) from the population and calculate a different  $\hat{\theta}$  for each sample. We could construct a histogram of all the  $\hat{\theta}$ 's and take their sample standard deviation to be an estimate of  $SE(\hat{\theta})$ . But what if we do not know the form of the population distribution?



# Illustration of Sampling from Known Distribution

**AIM.** estimate the mean of a Gaussian distribution and want to know the SE of the estimate.

- ❑ Generate say 10,000 samples, each of size  $n = 20$ , from an  $N(5.3, 0.4^2)$  distribution.
- ❑ Calculate the averages  $\{\bar{y}_{\text{sim}}^{(j)} : j = 1, \dots, 10000\}$  for the 10000 replicates.
- ❑ Take

$$\text{SE}(\bar{y}) \approx \sqrt{\frac{1}{10000 - 1} \sum_{j=1}^{10000} (\bar{y}_{\text{sim}}^{(j)} - \bar{y}_{\text{sim}})^2},$$

where  $\bar{y}_{\text{sim}}$  is the average of  $\bar{y}_{\text{sim}}^{(j)}$ .

## Idea: Bootstrap Sampling

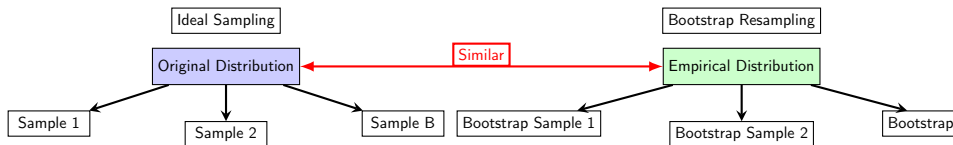
However, Step:

Generate say 10,000 samples, each of size  $n = 20$ , from  $\underbrace{N(5.3, 0.4^2)}_{\text{population}}$  is

impossible!

---

Idea. Bootstrap Sampling



## Bootstrapping Overview Cont'd

- ❑ The **bootstrap sampling approach**: Draw a “bootstrap” sample as a random sample of the same size  $n$  from the original sample of  $n$  observations (with replacement), and calculate a  $\hat{\theta}$  for the bootstrap sample.
- ❑ Repeat a large number of times, each time drawing another bootstrap sample (of size  $n$ ) and calculating another  $\hat{\theta}$  for that sample.
- ❑ Then construct a histogram of all the  $\hat{\theta}$ 's, take their sample standard deviation to be an estimate of  $SE(\hat{\theta})$ , etc.

**Why this works:** Consider making a pretend population that consists of your original sample of  $n$  observations, copied over and over, an infinite number of times. Each bootstrap sample is equivalent to drawing a random sample of size  $n$  from this infinite pretend population.

# Illustration of Bootstrapping

**AIM.** estimate the mean of an unknown distribution and want to know the SE of the estimate.

- ❑ Generate say 10,000 samples, each of size  $n = 20$ , from the given **observed data** (with replacement).
- ❑ Calculate the averages  $\{\bar{y}^{(b)} : b = 1, \dots, 10000\}$  for the 10000 replicates. (We think of  $\bar{y}^{(b)}$  just as the estimator  $\hat{\theta}$ .)
- ❑ Take

$$\text{SE}(\bar{y}) \approx \sqrt{\frac{1}{10000 - 1} \sum_{j=1}^{10000} (\bar{y}^{(b)} - \bar{y})^2},$$

where  $\bar{y}$  is the average of  $\bar{y}^{(b)}$ .

# Bootstrapping in Nonlinear Regression

- ❑ We have a sample of  $n$  observations  $\{(y_i, \mathbf{x}_i)\}_{i=1}^n$  of a response variable and a set of predictor variables.
- ❑ We fit a nonlinear regression model to the data to estimate a set of parameters  $\boldsymbol{\theta}$ .
- ❑ Let  $\theta$  denote one of the parameters of interest and  $\hat{\theta}$  its estimate.

**Objective:** Estimate the sampling distribution of  $\hat{\theta}$ , its standard error, a confidence interval for  $\theta$ , etc.

# Steps of the Bootstrap Procedure

- Generate a “bootstrap” sample (with replacement) of  $n$  observations from  $\{(y_i, x_i)\}_{i=1}^n$ . Denote the bootstrap sample by

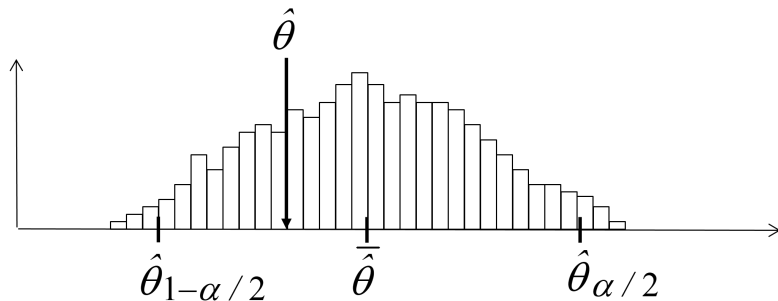
$$\{(y_i^{(b)}, x_i^{(b)})\}_{i=1}^n.$$

- Fit the same type of regression model (with the same set of parameters  $\theta$  and parameter  $\theta$  of special interest) to the bootstrapped sample. Denote the estimates for the bootstrapped sample by  $\hat{\theta}^{(b)}$  and  $\hat{\theta}^{(b)}$ .
- Pick a large number  $B$  (e.g.,  $B = 10,000$ ), and repeat Steps (1) and (2) a total of  $B$  times, which produces

$$\{\hat{\theta}^{(b)}\}_{b=1}^B.$$

## Steps of the Bootstrap Procedure Cont'd

- Construct a histogram of  $\{\hat{\theta}^{(b)}\}_{b=1}^B$  and calculate
- $\bar{\hat{\theta}} = \frac{1}{B} \sum_{b=1}^B \hat{\theta}^{(b)}$ : average of all bootstrapped estimates.
  - $SE(\hat{\theta}) = \sqrt{\frac{1}{B-1} \sum_{b=1}^B (\hat{\theta}^{(b)} - \bar{\hat{\theta}})^2}$ : standard error of  $\hat{\theta}$ .
  - $\hat{\theta}_{\alpha/2}$ : upper  $\alpha/2$  quantile.
  - $\hat{\theta}_{1-\alpha/2}$ : lower  $\alpha/2$  quantile.



- ❑ A crude  $1 - \alpha$  confidence interval for  $\theta$  is

$$\hat{\theta} - z_{\alpha/2} \cdot \text{SE}(\hat{\theta}) \leq \theta \leq \hat{\theta} + z_{\alpha/2} \cdot \text{SE}(\hat{\theta}).$$

- ❑ A better  $1 - \alpha$  confidence interval for  $\theta$  is

$$\hat{\theta} - (\hat{\theta}_{\alpha/2} - \hat{\theta}) \leq \theta \leq \hat{\theta} + (\hat{\theta} - \hat{\theta}_{1-\alpha/2}).$$



# Conformal Prediction

---

## AIM.

- ❑ Finite-sample coverage guarantees without distributional assumptions
- ❑ Converting a point prediction algorithm into a prediction set
  - ▮ **Input:** i.i.d. data pairs  $(X_i, Y_i)$  for  $i = 1, \dots, n$
  - ▮ **Objective:** Construct a prediction band  $\hat{C}_n(x)$  such that

$$P(Y_{n+1} \in \hat{C}_n(X_{n+1})) \geq 1 - \alpha$$

---

**Note:** Trivial solutions (Why?) exist, but the goal is to develop nontrivial, adaptive methods

# Key Idea: Using Ranks and Quantiles

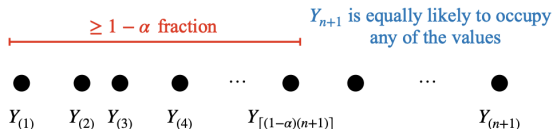
**Observation.** the rank of  $Y_{n+1}$  is uniformly distributed over the values  $1, 2, \dots, n+1$ . This means that

$$P\left(Y_{n+1} \text{ is among the } [(1-\alpha)(n+1)] \text{ smallest of } Y_1, \dots, Y_n\right) = 1-\alpha,$$

which is in turn equivalent to<sup>1</sup>

$$P\left(Y_{n+1} \text{ is among the } (1-\alpha)(n+1) \text{ smallest of } Y_1, \dots, Y_n\right) \geq 1-\alpha.$$

Accordingly, by defining  $q_n =$  the  $[(1-\alpha)(n+1)]$ -th smallest of  $Y_1, \dots, Y_n$ , we have precisely achieved the desired property. via  $Y_{n+1} \leq$  the  $[(1-\alpha)(n+1)]$ -th order statistic of  $Y_1, \dots, Y_n$ .



# Full Conformal Prediction

We have i.i.d. pairs  $\{(X_t, Y_t)\}_{t=1}^n$ , where  $X_t \in \mathcal{X}$  and  $Y_t \in \mathcal{Y}$ . We want to construct a prediction set for  $Y_{n+1}$  given  $X_{n+1}$ . Let  $\hat{f}_n$  be any regression predictor trained on

$$(X_1, Y_1), (X_2, Y_2), \dots, (X_n, Y_n).$$

Our goal is to achieve  $(1 - \alpha)$  coverage, i.e.,

$$P(Y_{n+1} \in C_n(X_{n+1})) \geq 1 - \alpha.$$

---

## Why the Naive procedure **Fails**?

- ❑ Compute the *training residuals*  $\hat{g}_i = Y_i - \hat{f}_n(X_i)$ ,  $i = 1, 2, \dots, n$ .
- ❑ Let  $\hat{q}_n$  be an estimate of a suitable quantile of the absolute residuals, for example the  $(1 - \alpha)$  empirical quantile of

$$\{|\hat{g}_1|, |\hat{g}_2|, \dots, |\hat{g}_n|\}.$$

- ❑ Define the prediction set for a new point  $x$  as

$$C_n(x) = \left[ \hat{f}_n(x) - \hat{q}_n, \hat{f}_n(x) + \hat{q}_n \right].$$

# Full Conformal Prediction

We have i.i.d. pairs  $\{(X_t, Y_t)\}_{t=1}^n$ , where  $X_t \in \mathcal{X}$  and  $Y_t \in \mathcal{Y}$ . We want to construct a prediction set for  $Y_{n+1}$  given  $X_{n+1}$ . Let  $\hat{f}_n$  be any regression predictor trained on

$$(X_1, Y_1), (X_2, Y_2), \dots, (X_n, Y_n).$$

Our goal is to achieve  $(1 - \alpha)$  coverage, i.e.,

$$P(Y_{n+1} \in C_n(X_{n+1})) \geq 1 - \alpha.$$

---

## Full Conformal Prediction

- ❑ Compute the *training residuals*  $\hat{g}_i = Y_i - \hat{f}_n^{-i}(X_i)$ ,  $i = 1, 2, \dots, n$ .  
( $-i$  means delete  $i$ -th data while training)
- ❑ Let  $\hat{q}_n$  be an estimate of a suitable quantile of the absolute residuals, for example the  $(1 - \alpha)$  empirical quantile of  $\{|\hat{g}_1|, |\hat{g}_2|, \dots, |\hat{g}_n|\}$ .
- ❑ Define the prediction set for a new point  $x$  as

$$C_n(x) = \left[ \hat{f}_n(x) - \hat{q}_n, \hat{f}_n(x) + \hat{q}_n \right].$$

# Split Conformal Prediction

Full Conformal Prediction is computationally intractable! (why?)

## Key Idea. Data Split

- ❑ **Proper Training Set ( $D_1$ ):** Fit the point predictor  $\hat{f}_{n_1}(x)$
- ❑ **Calibration Set ( $D_2$ ):** Compute residuals

$$R_i = |Y_i - \hat{f}_{n_1}(X_i)|, \quad i \in D_2$$

- 
- Define quantile from calibration residuals:

$$q_{n_2} = \lceil (1 - \alpha)(n_2 + 1) \rceil\text{-th smallest residual}$$

- Prediction set:

$$\hat{C}_n(x) = [\hat{f}_{n_1}(x) - q_{n_2}, \hat{f}_{n_1}(x) + q_{n_2}]$$

- Guarantee: Ensures marginal coverage of at least  $1 - \alpha$

# Mathematical Formulation: Regression Case

## Nonconformity Score

For a predictive model  $\hat{f}$  and calibration data  $\{(x_i, y_i)\}_{i=1}^{n_{\text{cal}}}$ , define the nonconformity score as:

$$\alpha_i = |y_i - \hat{f}(x_i)|$$

## Prediction Interval

Let  $\hat{q}_{1-\alpha}$  be the  $(1 - \alpha)$ -quantile of  $\{\alpha_i\}_{i=1}^{n_{\text{cal}}}$ . For a new input  $x_{n+1}$ , the prediction interval is given by:

$$\{y \in \mathbb{R} : |y - \hat{f}(x_{n+1})| \leq \hat{q}_{1-\alpha}\}$$

This interval guarantees that the true  $y$  falls inside with probability at least  $1 - \alpha$ .

## Nonconformity Score

For a classification model, a common choice is:

$$\alpha_i = 1 - p(y_i | x_i)$$

where  $p(y_i | x_i)$  is the predicted probability for the true class.

## Prediction Set

For a new example  $x_{n+1}$ , the prediction set is defined as:

$$\Gamma(x_{n+1}) = \left\{ y \in \mathcal{Y} : \frac{\#\{i : \alpha_i \geq \alpha(y)\} + 1}{n_{\text{cal}} + 1} > \alpha \right\}$$

where  $\alpha(y)$  is the nonconformity score computed if  $y$  were the true label.



# Advantages and Limitations

## Advantages

- **Finite-Sample Guarantees:** Ensures valid coverage without asymptotic approximations.
  - **Model-Agnostic:** Can be applied on top of any predictive model.
- 

## Limitations

- **Computational Cost:** Some methods can be computationally intensive, especially in the transductive setting.
- **Loose Confidence Interval**
- **Assumptions:** Relies on the exchangeability assumption which might not hold in all cases.