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Singular Value Decomposition, A \in all \ matrix \ IR^{m \times n}
                     Idea. ATA and AAT are always square and symmetric
           SVD: A = U I VT nxn
orthogonal diag matrix
         -A^{T}A = (U \Sigma V^{T})^{T} U \Sigma V^{T} = V \Sigma^{T} U^{T} U \Sigma V^{T} = V \Sigma^{T} \Sigma V^{T}
                                                                            eigenvalus
                                                                                                                                                                                                  V is eigenvectors of ATA
      - AA^{T} = U I I U^{T}

AT A and E^{T} Z are similar, AA^{T} and IZ^{T}
                                                                                                                                                                                                                                                                                                       are also...
                                                                U is the eigenvectors of AAT.

\Gamma = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \end{bmatrix} \Rightarrow \Gamma \Gamma = \begin{bmatrix} \lambda_1^2 & 0 \\ 0 & \lambda_2^2 \end{bmatrix} \text{ eigen: } \lambda_1^2, \lambda_2^2

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                                                                                                                                                                                                                                   There I are the same
     => 1) ATA 3x3 moth x hi. hi. 0
                                   AAT 2x2 matrix xt hit
 \frac{Thm}{N_{N}} = N_{N} (AA^{T}) = N_{N} (A^{T})
                                  if AA^{Tx} = 0 (=) A^{Tx} = 0 (equalities)
   0 = easier A^Tx = 0 \Rightarrow AA^Tx = A(A^Tx) = A \cdot 0 = 0
= XTA (= 0=11xTA)) (=
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- rank (AA^T) = tank (A^TA) = rank (A) = tank (A^T)
                                                   = number of non-zeros in the diag of I.
Four Fundamental Subspace. (orthogonal basis) via SVD.
       A = U \leq V^{T} = \begin{bmatrix} \vec{u}_{1} & \vec{u}_{2} & \cdots & \vec{u}_{m} \end{bmatrix} \begin{bmatrix} \lambda_{1} & \lambda_{2} & \cdots & \lambda_{n} \\ \vec{v}_{1} & \vec{v}_{2} & \cdots & \vec{v}_{n} \end{bmatrix}
Continuous continuous basis of IRM
 - {vi, ... vr} is the orthonormal basis of Column (A) ) Glumn (A) I loft Not
 - further um is the athonormal basis of left Nul space (A)
  - [Vi.... Vin] is the orthonormal basis of null space (A) [ now (A) L Null (A) - [ Vin] ... Vin] is the orthonormal basis of null space (A)
       - A = \lambda_1 \vec{u}_1 \vec{v}_1^T + \lambda_2 \vec{u}_2 \vec{v}_2^T + \cdots + \lambda_r \vec{u}_r \vec{v}_r^T
    VI W VI W Vn W
                    A = \lambda_1 \vec{u}_1 \vec{v}_1^T + \lambda_2 \vec{u}_2 \vec{v}_2^T \Rightarrow \begin{cases} \text{tow space = span } \vec{v}_1 \vec{v}_2 \end{cases}
space of A

\begin{bmatrix}
u_{11} \vec{v_1}^T \\
u_{12} \vec{v_1}^T
\end{bmatrix} + \begin{bmatrix}
u_{21} \vec{v_2}^T \\
u_{22} \vec{v_2}^T
\end{bmatrix} = \begin{bmatrix}
u_{11} \vec{v_1}^T + u_{21} \vec{v_2}^T
\end{bmatrix} = \begin{bmatrix}
u_{12} \vec{v_1}^T + u_{22} \vec{v_2}^T
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\end{bmatrix} = \begin{bmatrix}
u_{12} \vec{v_1}^T + u_{22} \vec{v_2}^T
\end{bmatrix} = \begin{bmatrix}
u_{13} \vec{v_1}^T + u_{22} \vec{v_2}^T
\end{bmatrix} = \begin{bmatrix}
u_{14} \vec{v_1}^T + u_{22} \vec{v_2}^T
\end{bmatrix} = \begin{bmatrix}
u_{15} \vec{v_1} + u_{22} \vec{v_2}^T
\end{bmatrix} = \begin{bmatrix}
u_{15} \vec{v_1} + u_{22} \vec{v_2} + u_{22} \vec{v_2}^T
\end{bmatrix} = \begin{bmatrix}
u_{15} \vec{v_1} + u_{22} \vec{v_2} + u_{22} \vec{v_2}
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- Nul $(AA^T) = Nul (A^T)$

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$$A A^{T} = U I I^{T} U^{T}$$

eigen voctor

$$U_{1} = \text{eigenvale } \lambda_{1}^{1} \Rightarrow A A^{T} U_{1} = \lambda_{1}^{N} U_{1}^{1}$$

$$U_{2} = \text{eigenvale } \lambda_{2}^{1} \Rightarrow A A^{T} U_{1} = \lambda_{1}^{N} U_{2}^{1}$$

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$$U_{2} = \lambda_{1}^{N} U_{2}^{1} = \lambda_{2}^{N} U_{2}^{1}$$

$$U_{3} = \lambda_{1}^{N} U_{4}^{1} = \lambda_{2}^{N} U_{4}^{1}$$

$$U_{4} = \lambda_{1}^{$$

Nul (AT)

Find SVD of
$$A = \begin{bmatrix} 4 & 4 \\ -3 & 3 \end{bmatrix}$$

$$A^{T}A = \begin{bmatrix} 25 & 7 \\ 7 & 25 \end{bmatrix}$$

$$P(\lambda) = \det \begin{bmatrix} 25 - \lambda & 7 \\ 7 & 25 - \lambda \end{bmatrix} = (25 - \lambda)^{2} - 7 \times 7 \Rightarrow 25 - \lambda = 132$$

$$I = \begin{bmatrix} 132 \\ 116 \end{bmatrix} \quad V = \begin{bmatrix} 115 \\ 15 \\ 115 \end{bmatrix} \quad \text{temember to normalize}$$

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How to compute
$$\vec{u}_1 = \frac{1}{\lambda_1} A \vec{v}_1$$

$$A = \lambda_1 \vec{u}_1 \vec{v}_1^T + \lambda_2 \vec{u}_2 \vec{v}_1^T \vec{v}_1 + \lambda_3 \vec{v}_3 \vec{v}_1^T \vec{v}_1 = \lambda_1 \vec{v}_1 \vec{v}_1 \vec{v}_1 + \lambda_4 \vec{v}_2 \vec{v}_1^T \vec{v}_1 = \lambda_1 \vec{v}_1 \vec{v}_1 \vec{v}_1 + \lambda_5 \vec{v}_2 \vec{v}_1 \vec{v}_1 + \lambda_5 \vec{v}_2 \vec{v}_1 \vec{v}_1 + \lambda_5 \vec{v}_2 \vec{v}_1 \vec{v}_1 + \lambda_5 \vec{v}_1 \vec{v}_1 \vec{v}_1 \vec{v}_2 \vec{v}_1 \vec{v}_1 \vec{v}_1 \vec{v}_1 \vec{v}_1 \vec{v}_1 \vec{v}_1 \vec{v}_1 \vec{v}_2 \vec{v}_1 \vec{v}_1 \vec{v}_2 \vec{v}_1 \vec{v}_1 \vec{v}_2 \vec{v}_1 \vec{v}_1 \vec{v}_1 \vec{v}_1 \vec{v}_1 \vec{v}_2 \vec{v}_1 \vec{v}_1 \vec{v}_1 \vec{v}_1 \vec{v}_1 \vec{v}_1 \vec{v}_1 \vec{v}_1 \vec{v}_2 \vec{v}_1 \vec{v$$

= | =0 | vi. vi) is an orthonomal basis

$$\vec{\mathcal{U}} = \frac{1}{\lambda_1} A \vec{\mathcal{V}}_1 = \frac{1}{\delta \tau_1} \begin{bmatrix} 4 & 4 \\ -3 & 3 \end{bmatrix} \begin{bmatrix} 1/\tau_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \in \text{fix the Sign}$$

$$\vec{\mathcal{U}}_1 = \frac{1}{\lambda_1} A \vec{\mathcal{V}}_2 = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

$$\Rightarrow A = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} \overline{132} & \overline{112} \\ \overline{118} & \overline{112} \end{bmatrix} \begin{bmatrix} \overline{112} & \overline{112} \\ \overline{112} & \overline{112} \end{bmatrix}$$

If you compute A^TA to get V, you sholdn't get U from AAT If you compute AAT to get U, you sholdn't get U from A^TA

may
$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \overline{152} \\ -\overline{118} \end{bmatrix}$$
 You can't determine $\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -\overline{152} \\ -\overline{114} \end{bmatrix}$ the sign.

You can compute AAT 2x2 ATA 4x4

$$AA^{T} \Rightarrow U = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$$

$$V_{1} = \frac{1}{\lambda_{1}} A \Omega_{1} = \begin{bmatrix} \sqrt{12}/2 \\ \sqrt{12}/2 \end{bmatrix}$$

$$v_1 = \frac{1}{\lambda_1} \Delta u_1 = \begin{bmatrix} \overline{12}/2 \\ 0 \\ \overline{12}/2 \end{bmatrix}$$
 How to compute $\overrightarrow{V_3}$, $\overrightarrow{V_4}$ (?) span $(\overrightarrow{V_1}, \overrightarrow{V_1})$

$$V_2 = \frac{1}{\lambda_2} A u_2 = \begin{bmatrix} 0 \\ \overline{u} \end{bmatrix}$$

$$V_3 \quad V_4 \text{ is the orthogonal besing of Null } V_1^T$$

$$V_{1} = \frac{1}{\lambda_2} A u_2 = \begin{bmatrix} 0 \\ \overline{u} \end{bmatrix}$$

$$AA^{T} \Rightarrow U = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad T = \begin{bmatrix} \overline{12} & 0 & 0 & 0 \\ 0 & \overline{12} & 0 & 0 \end{bmatrix}$$

- then use G-S to orthogonlite the basis
- hormalize to unit vector