

# Lecture 3 Linear Systems and Elimination

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Video 1 and 2 of Gilbert Strang's course:

https://ocw.mit.edu/courses/18-06-linear-algebra-spring-2010/video\_galleries/video-lectures/

## Strang Sections 2.1 – Vectors and Linear Equations and 2.2 – The Idea of Elimination

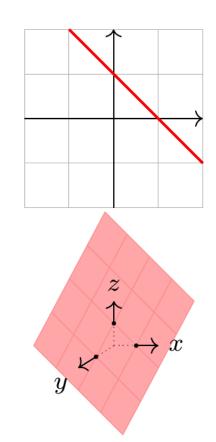
Course notes adapted from *Introduction to Linear Algebra* by Strang (5<sup>th</sup> ed), N. Hammoud's NYU lecture notes, and *Interactive Linear Algebra* by Margalit and Rabinoff, in addition to our text



What does the solution set of a linear equation look like?

► 
$$x + y = 1$$
  
 $x + y = 1$   
 $y = 1 - x$ 

$$x + y + z = 1$$
  
 $x + y + z = 1$   
 $x + y + z = 1$ 

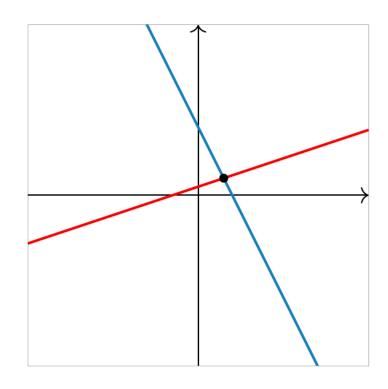


[not pictured here]

What does the solution set of a *system* of more than one linear equation look like?

$$x - 3y = -3$$
$$2x + y = 8$$

... is the *intersection* of two lines, which is a *point* in this case.

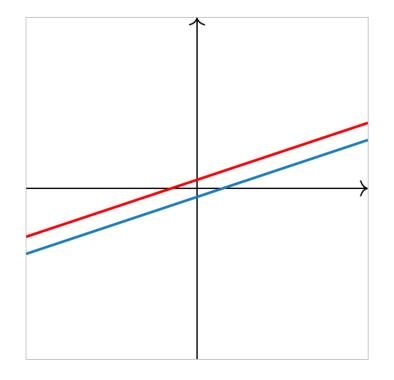


In general it's an intersection of lines, planes, etc.

In what other ways can two lines intersect?

$$x - 3y = -3$$
$$x - 3y = 3$$

has no solution: the lines are parallel.

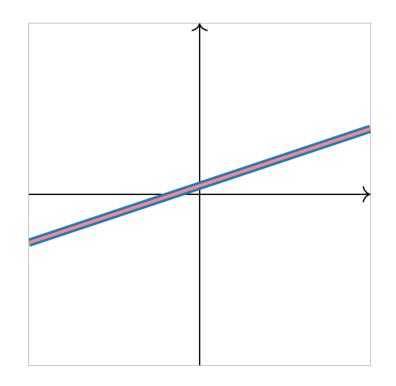


A system of equations with no solutions is called **inconsistent**.

In what other ways can two lines intersect?

$$x - 3y = -3$$
$$2x - 6y = -6$$

has infinitely many solutions: they are the *same line*.



Note that multiplying an equation by a nonzero number gives the *same* solution set. In other words, they are equivalent (systems of) equations.

#### Example

Solve the system of equations

$$x + 2y + 3z = 6$$
  
 $2x - 3y + 2z = 14$   
 $3x + y - z = -2$ 

This is the kind of problem we'll talk about for a good portion of the course.

- ▶ A **solution** is a list of numbers x, y, z, ... that make *all* of the equations true.
- ► The **solution set** is the collection of all solutions.
- ▶ **Solving** the system means finding the solution set.

Consider the following system of two equations in two unknowns

$$x_1 - 2x_2 = 1$$
$$3x_1 + 2x_2 = 11$$

This system could be expressed in matrix notation as:

$$\left[\begin{array}{cc} 1 & -2 \\ 3 & 2 \end{array}\right] \left[\begin{array}{c} x_1 \\ x_2 \end{array}\right] = \left[\begin{array}{c} 1 \\ 11 \end{array}\right]$$

## Systems of Equations – 2D – Row vs. Column Picture

$$\left[ egin{array}{cc} 1 & -2 \ 3 & 2 \end{array} 
ight] \left[ egin{array}{c} x_1 \ x_2 \end{array} 
ight] = \left[ egin{array}{c} 1 \ 11 \end{array} 
ight]$$

Row picture: 
$$(1,-2) \cdot (x_1,x_2) = 1 \implies x_1 - 2x_2 = 1$$
  
 $(3,2) \cdot (x_1,x_2) = 11 \implies 3x_1 + 2x_2 = 11$ 

## Systems of Equations – 2D – Row vs. Column Picture

$$\left[ egin{array}{cc} 1 & -2 \ 3 & 2 \end{array} 
ight] \left[ egin{array}{c} x_1 \ x_2 \end{array} 
ight] = \left[ egin{array}{c} 1 \ 11 \end{array} 
ight]$$

Column picture: 
$$x_1 \begin{bmatrix} 1 \\ 3 \end{bmatrix} + x_2 \begin{bmatrix} -2 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 11 \end{bmatrix}$$

## Systems of Equations – 3D – Row vs. Column Picture

If we have three equations with three unknowns, it is still possible to draw a picture of what a solution looks like. Each of the three equations represents a plane in 3D, and their intersection gives the solution of the system. As soon as you go above 3D, visualization becomes impossible.

Consider the following system of three equations in three unknowns

## Systems of Equations – 3D – Row vs. Column Picture

$$\left[egin{array}{cccc} 1 & 2 & 3 \ 2 & 5 & 2 \ 6 & -3 & 1 \end{array}
ight] \left[egin{array}{c} x_1 \ x_2 \ x_3 \end{array}
ight] = \left[egin{array}{c} 6 \ 4 \ 2 \end{array}
ight]$$

**Row picture**: 
$$(1,2,3) \cdot (x_1, x_2, x_3) = 6 \implies x_1 + 2x_2 + 3x_3 = 6$$
  
 $(2,5,2) \cdot (x_1, x_2, x_3) = 4 \implies 2x_1 + 5x_2 + 2x_3 = 4$   
 $(6,-3,1) \cdot (x_1, x_2, x_3) = 2 \implies 6x_1 - 3x_2 + x_3 = 2$ 

## Systems of Equations – 3D – Row vs. Column Picture

$$\left[egin{array}{cccc} 1 & 2 & 3 \ 2 & 5 & 2 \ 6 & -3 & 1 \end{array}
ight] \left[egin{array}{c} x_1 \ x_2 \ x_3 \end{array}
ight] = \left[egin{array}{c} 6 \ 4 \ 2 \end{array}
ight]$$

Column picture: 
$$x_1 \begin{bmatrix} 1 \\ 2 \\ 6 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 5 \\ -3 \end{bmatrix} + x_3 \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 4 \\ 2 \end{bmatrix}$$



$$x_1 + 2x_2 + 3x_3 = 6$$
$$2x_1 + 5x_2 + 2x_3 = 4$$
$$6x_1 - 3x_2 + x_3 = 2$$

What strategies do you know?

#### **General Case**

Suppose we are given a system of m equations in n unknowns:

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$
 $a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$ 
 $\vdots$ 
 $a_{j1}x_1 + a_{j2}x_2 + \dots + a_{jn}x_n = b_j$ 
 $\vdots$ 
 $a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$ 

our goal is to find  $x_1, \ldots, x_n$ .

To do that, we choose one equation which has a nonzero coefficient multiplying  $x_1$  and use that to eliminate  $x_1$  from all the remaining equations. This equation is referred to as the *first pivot*, and it could be any of the m equations in our system, e.g, the  $j^{th}$  equation  $a_{i1}x_1 + a_{i2}x_2 + \cdots + a_{in}x_n = b_i$ .

this or any other equation with nonzero coefficient in front of ! %

can also be chosen as first pivot

$$a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2$$

$$\vdots$$

$$a_{j1}x_1 + a_{j2}x_2 + \cdots + a_{jn}x_n = b_j$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_m$$

To do that, we choose one equation which has a nonzero coefficient multiplying  $x_1$  and use that to eliminate  $x_1$  from all the remaining equations. This equation is referred to as the *first pivot*, and it could be any of the m equations in our system, e.g, the  $j^{th}$  equation  $a_{j1}x_1 + a_{j2}x_2 + \cdots + a_{jn}x_n = b_j$ .

$$a_{11}X_1 + a_{12}X_2 + \cdots + a_{1n}X_n = b_1$$

$$a_{21}X_1 + a_{22}X_2 + \cdots + a_{2n}X_n = b_2$$

$$\vdots$$

$$a_{j1}X_1 + a_{j2}X_2 + \cdots + a_{jn}X_n = b_j$$
this or any other equation with nonzero coefficient in front of ! % can also be chosen as **first pivot**

$$\vdots$$

$$a_{m1}X_1 + a_{m2}X_2 + \cdots + a_{mn}X_n = b_m$$

To do that, we choose one equation which has a nonzero coefficient multiplying  $x_1$  and use that to eliminate  $x_1$  from all the remaining equations. This equation is referred to as the *first pivot*, and it could be any of the m equations in our system, e.g, the  $j^{th}$  equation  $a_{j1}x_1 + a_{j2}x_2 + \cdots + a_{jn}x_n = b_j$ .

$$a_{j 1} x_1 + a_{j 2} x_2 + \cdots + a_{j n} x_n = b_j$$

$$\cdot x_2 + \cdots + \cdot x_n = \longleftarrow$$

$$\vdots$$

$$\cdot x_2 + \cdots + \cdot x_n = \bigcirc$$

the system after choosing the !'( equation as first pivot and using it to eliminate \$% from the remaining equations

$$a_{j 1} x_1 + a_{j 2} x_2 + \cdots + a_{j n} x_n = b_j$$

$$x_2 + \cdots + x_n = \longleftarrow$$

$$\vdots$$

$$x_2 + \cdots + x_n = \bigcirc$$

choose **second pivot** with nonzero!) coefficient, and use it to eliminate!) from all remaining equations except the first pivot

Once we have eliminated  $x_1$  from all equations except the first pivot, we move the pivot to the top, and leave it unaltered, then we choose another pivot from the remaining m-1 equations, which has a nonzero coefficient multiplying  $x_2$ . We use this second pivot to eliminate  $x_2$  from the m-2 equations, i.e., all equations except the pivot equations (first and second).

Once that is done, we move the second pivot and place it right under the first, and we leave it unaltered. We proceed by selecting a third pivot, which we use to eliminate  $x_3$  from the remaining m-3 equations.

## Systems in Upper Triangular Form

We continue with this procedure, until the system is upper triangular. Once that is achieved, we can use the last equation to solve for  $x_n$  and then back-solve for all the remaining unknowns.

## Example

$$x_1 + 2x_2 + 3x_3 = 6$$

$$2x_1 + 5x_2 + 2x_3 = 4$$

$$6x_1 - 3x_2 + x_3 = 2$$

## Example

$$x_1 + 2x_2 + 3x_3 = 6$$

$$2x_1 + 5x_2 + 2x_3 = 4$$

$$6x_1 - 3x_2 + x_3 = 2$$



This process is known as the Gauss-Jordan elimination method. We can go even further to make the work more practical.

## Gauss-Jordan

#### Example

Solve the system of equations

$$x + 2y + 3z = 6$$
  
 $2x - 3y + 2z = 14$   
 $3x + y - z = -2$ 

Elimination method: in what ways can you manipulate the equations?

- ▶ Multiply an equation by a nonzero number.
- ▶ Add a multiple of one equation to another.
- ► Swap two equations.

(scale)

(replacement)

(swap)

#### Example

$$x + 2y + 3z = 6$$
  
 $2x - 3y + 2z = 14$   
 $3x + y - z = -2$ 

It sure is a pain to have to write x, y, z, and = over and over again.

Matrix notation: write just the numbers, in a box, instead!

This is called an **(augmented) matrix**. Our equation manipulations become **elementary row operations**:

- ► Multiply all entries in a row by a nonzero number. (scale)
- Add a multiple of each entry of one row to the corresponding entry in another.

  (row replacement)
- ► Swap two rows. (swap)

#### **General Case**

Suppose we are given a system of m equations in n unknowns:

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$
 $a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$ 
 $\vdots$ 
 $a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$ 

This system can be written in matrix form as:

$$\left[egin{array}{cccc} a_{11} & a_{12} & \dots & a_{1n} \ a_{21} & a_{22} & \dots & a_{2n} \ dots & & & & \ \vdots & & & & \ a_{m1} & a_{m2} & \dots & a_{mn} \end{array}
ight] \left[egin{array}{c} x_1 \ x_2 \ dots \ x_n \end{array}
ight] = \left[egin{array}{c} b_1 \ b_2 \ dots \ b_m \end{array}
ight]$$

#### Example

Solve the system of equations

$$x + 2y + 3z = 6$$
  
 $2x - 3y + 2z = 14$   
 $3x + y - z = -2$ 

Start:

$$\begin{pmatrix} 1 & 2 & 3 & 6 \\ 2 & -3 & 2 & 14 \\ 3 & 1 & -1 & -2 \end{pmatrix}$$

Goal: we want our elimination method to eventually produce a system of equations like

$$x = A$$
  
 $y = B$  or in matrix form,  $\begin{pmatrix} 1 & 0 & 0 & A \\ 0 & 1 & 0 & B \\ 0 & 0 & 1 & C \end{pmatrix}$ 

So we need to do row operations that make the start matrix look like the end one.

Strategy: fiddle with it so we only have ones and zeros.

#### Example

$$x + 2y + 3z = 6$$
  
 $2x - 3y + 2z = 14$   
 $3x + y - z = -2$ 

#### Example

$$x + 2y + 3z = 6$$
  
 $2x - 3y + 2z = 14$   
 $3x + y - z = -2$ 

#### Example

$$x + 2y + 3z = 6$$
  
 $2x - 3y + 2z = 14$   
 $3x + y - z = -2$ 

## Elimination – Summary of the previous example

$$\begin{pmatrix} 1 & 2 & 3 & 6 \\ 2 & -3 & 2 & 14 \\ 3 & 1 & -1 & -2 \end{pmatrix}$$

$$R_2 = R_2 - 2R_1$$

$$R_3 = R_3 - 3R_1$$

So we subtract multiples of the first row.

$$\begin{pmatrix}
1 & 2 & 3 & 6 \\
2 & -3 & 2 & 14 \\
3 & 1 & -1 & -2
\end{pmatrix}$$

$$R_2 = R_2 - 2R_1$$

$$\begin{pmatrix}
1 & 2 & 3 & 6 \\
0 & -7 & -4 & 2 \\
3 & 1 & -1 & -2
\end{pmatrix}$$
We want these to be zero.

$$R_3 = R_3 - 3R_1$$
where the first row 
$$\begin{pmatrix}
1 & 2 & 3 & 6 \\
0 & -7 & -4 & 2 \\
0 & -5 & -10 & -20
\end{pmatrix}$$

$$\left( egin{array}{cc|c} 0 & -7 & -4 & 2 \ 0 & -5 & -10 & -20 \end{array} \right)$$

## Elimination – Summary of the previous example

We want these to be zero. So we subtract multiples of the first row.

$$\begin{pmatrix}
1 & 2 & 3 & 6 \\
0 & -7 & -4 & 2 \\
0 & -5 & -10 & -20
\end{pmatrix}$$

$$R_2 \longleftrightarrow R_3$$

$$\begin{pmatrix}
1 & 2 & 3 & 6 \\
0 & -5 & -10 & -20 \\
0 & -7 & -4 & 2
\end{pmatrix}$$

$$R_2 = R_2 \div -5$$
We want these to be zero.
$$\begin{pmatrix}
1 & 2 & 3 & 6 \\
0 & -7 & -4 & 2
\end{pmatrix}$$

It would be nice if this were a 1. We could divide by -7, but that would produce ugly fractions.

Let's swap the last two rows first.

$$R_3 = R_3 + 7R_2$$

 $R_1 = R_1 - 2R_2$ 

$$\begin{pmatrix} 1 & 2 & 3 & | & 6 \\ 0 & -7 & -4 & | & 2 \\ 3 & 1 & -1 & | & -2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & 3 & | & 6 \\ 0 & -7 & -4 & | & 2 \\ 0 & -5 & -10 & | & -20 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & 3 & | & 6 \\ 0 & -5 & -10 & | & -20 \\ 0 & -7 & -4 & | & 2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & 3 & | & 6 \\ 0 & 1 & 2 & | & 4 \\ 0 & -7 & -4 & | & 2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & -1 & | & -2 \\ 0 & 1 & 2 & | & 4 \\ 0 & -7 & -4 & | & 2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & -1 & | & -2 \\ 0 & 1 & 2 & | & 4 \\ 0 & -7 & -4 & | & 2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & -1 & | & -2 \\ 0 & 1 & 2 & | & 4 \\ 0 & -7 & -4 & | & 2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & -1 & -2 \\ 0 & 1 & 2 & 4 \\ 0 & 0 & 10 & 30 \end{pmatrix}$$

We want these to be zero.

Let's make this a 1 first.

$$R_3 = R_3 \div 10$$

$$R_1 = R_1 + R_3$$

$$R_2 = R_2 - 2R_3$$

$$\begin{pmatrix}
1 & 0 & -1 & | & -2 \\
0 & 1 & 2 & | & 4 \\
0 & 0 & 1 & | & 3
\end{pmatrix}$$

$$\begin{pmatrix}
1 & 0 & 0 & | & 1 \\
0 & 1 & 2 & | & 4 \\
0 & 0 & 1 & | & 3
\end{pmatrix}$$

$$\begin{pmatrix}
1 & 0 & 0 & | & 1 \\
0 & 1 & 0 & | & -2
\end{pmatrix}$$

$$\begin{array}{ccc}
x & = & 1 \\
y & = & -2 \\
z & = & 3
\end{array}$$

Success!

Check:

$$x + 2y + 3z = 6$$

$$2x - 3y + 2z = 14$$

$$3x + y - z = -2$$
subst

$$1 + 2 \cdot (-2) + 3 \cdot 3 = 6$$

$$2 \cdot 1 - 3 \cdot (-2) + 2 \cdot 3 = 14$$

$$3 \cdot 1 + (-2) - 3 = -2$$

## Another Example

#### Example

$$x + y = 2$$
$$3x + 4y = 5$$
$$4x + 5y = 9$$

## Another Example

#### Example

$$x + y = 2$$
$$3x + 4y = 5$$
$$4x + 5y = 9$$

#### Note

#### Important

The process of doing row operations to a matrix does not change the solution set of the corresponding linear equations!

#### Definition

Two matrices are called **row equivalent** if one can be obtained from the other by doing some number of elementary row operations.

The linear equations of row-equivalent matrices have the *same solution set*.

In other words, the original equations

$$x + y = 2$$
  $x + y = 2$   
 $3x + 4y = 5$  have the same solutions as  $y = -1$   
 $4x + 5y = 9$   $0 = 2$ 

But the latter system obviously has no solutions (there is no way to make them all true), so our original system has no solutions either.

#### Definition

A system of equations is called **inconsistent** if it has no solution. It is **consistent** otherwise.



