IEMS 304 Lecture 8: Unsupervised Learning

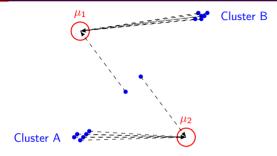
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k-means

Iteration 1: Initialization & Forced Assignment



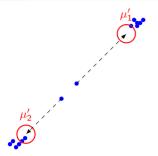
Assignment Summary (Iteration 1):

- $\mu_1 = (1, 4.5)$ gets: all Cluster B points (6 pts) + ambiguous point (2.5, 2.5) [total 7 pts].
- $\mu_2 = (4.5, 1)$ gets: all Cluster A points (6 pts) + ambiguous point (3,3) [total 7 pts].

Updated centroids (computed as the mean):

$$\begin{split} \mu_1' &= \left(\frac{30+2.5}{7}, \frac{30+2.5}{7}\right) \approx (4.643, \, 4.643) \\ \mu_2' &= \left(\frac{6.3+3}{7}, \frac{6.3+3}{7}\right) \approx (1.329, \, 1.329) \end{split}$$

Iteration 2: Reassignment



Reassignment (Iteration 2):

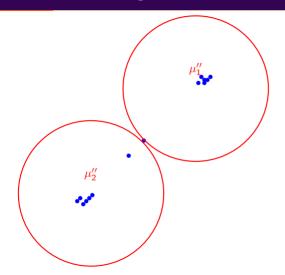
- (2.5, 2.5) switches from μ_1 to μ_2' (closer to (1.329, 1.329)).
- (3,3) switches from μ_2 to μ'_1 (closer to (4.643, 4.643)).

New centroids:

$$\mu_1'' = \left(\frac{30+3}{7}, \frac{30+3}{7}\right) = \left(\frac{33}{7}, \frac{33}{7}\right) \approx (4.714, 4.714)$$

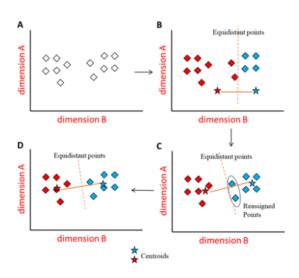
$$\mu_2'' = \left(\frac{6.3+2.5}{7}, \frac{6.3+2.5}{7}\right) = \left(\frac{8.8}{7}, \frac{8.8}{7}\right) \approx (1.257, 1.257)$$

Iteration 3: Convergence



Convergence: With centroids $\mu_1'' \approx (4.714, 4.714)$ and $\mu_2'' \approx (1.257, 1.257)$, all data points are now correctly grouped according to their true clusters.

k-means



k-means as Optimization

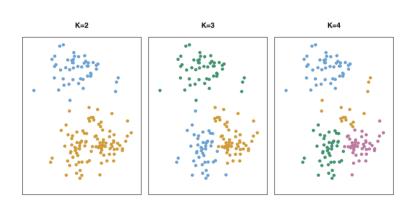
k-means aims to minimize the total within cluster (square) distance

$$\min_{\{C_j\},\{\mu_j\}} \sum_{j=1}^k \sum_{x \in C_j} \|x - \mu_j\|^2$$

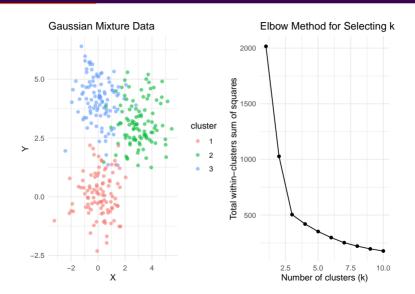
k-means as alternating direction optimization algorithm

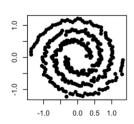
- **☐ Assignment:** Assign each x to its nearest μ_j (minimizes distance).
- **□ Update:** Recompute μ_j as the mean of C_j (minimizes variance).

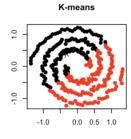
Wrong k can be Problematic

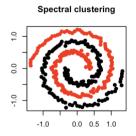


How to Select k: Elbow Effect







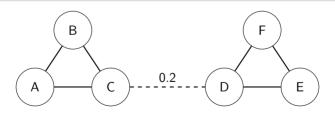


We first represent data as a weighted graph G(V, E) with weights w_{ij} .

Consider the Dirichlet form,

$$\frac{1}{2} \sum_{i,j} w_{ij} (f(i) - f(j))^2 = f^T L f, \quad \text{(Why?)}$$

where L is the graph Laplacian defined as L = D - W (where D is the degree matrix).



What would happen if we minimizing this form?

Quadratic Function as a Quadratic Form

$$v^T A v = \begin{pmatrix} x & y \end{pmatrix} \begin{pmatrix} 3 & 2 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 3x^2 + 2xy + 2xy + 2y^2 = 3x^2 + 4xy + 2y^2.$$

Why is the Dirichlet Form Equal to $f^T L f$?

Consider the Dirichlet form:

$$\frac{1}{2}\sum_{i,j}w_{ij}\big(f(i)-f(j)\big)^2=\frac{1}{2}\sum_{i,j}w_{ij}\Big[f(i)^2-2f(i)f(j)+f(j)^2\Big].$$

 \square terms involving $f(i)^2$:

$$\frac{1}{2} \left(\sum_{i,j} w_{ij} f(i)^2 + \sum_{i,j} w_{ij} f(j)^2 \right)$$

$$= \sum_{i} f(i)^2 \sum_{i} w_{ij} = \sum_{i} d_i f(i)^2.$$

☐ The cross term simplifies to: $-\sum_{i:i} w_{ij} f(i) f(j).$

$$\frac{1}{2} \sum_{i,i} w_{ij} (f(i) - f(j))^2 = \sum_{i} d_i f(i)^2 - \sum_{i,i} w_{ij} f(i) f(j).$$

At the same time,

$$f^T L f = \sum_i d_i f(i)^2 - \sum_{i,j} w_{ij} f(i) f(j)$$
, where $L = D - W$,

Understanding the Dirichlet Form

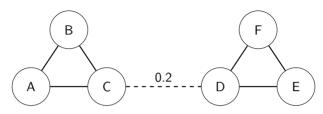
Definition

The Dirichlet form on a graph is defined as:

$$\frac{1}{2} \sum_{i,j} w_{ij} (f(i) - f(j))^2 = f^T L f.$$

- It sums the squared differences of the function values f(i) over every edge, weighted by w_{ii} .
- A small value of $f^T L f$ indicates that neighboring nodes (with high similarity w_{ij}) have similar function values.
- Minimizing the Dirichlet form under constraints leads to smooth functions on the graph, thus revealing inherent cluster structure.

Computing the Graph Laplacian



Step 1: Define the Matrices

- Weighted Adjacency Matrix W: For each edge (i,j), w(i,j) = 1except for the edge between C and D where w(C,D) = 0.2.
- **Degree Matrix** *D*: Diagonal with $d_A = 2$, $d_B = 2$, $d_C = 2.2$, $d_D = 2.2$, $d_F = 2$, $d_F = 2$

Step 2: Compute the Graph Laplacian

$$= \begin{pmatrix} L = D - W \\ \frac{2}{-1} & \frac{-1}{2} & 0 & 0 & 0 \\ -1 & 2 & -1 & 0 & 0 & 0 \\ -1 & -1 & 2.2 & -0.2 & 0 & 0 \\ 0 & 0 & -0.2 & 2.2 & -1 & -1 \\ 0 & 0 & 0 & -1 & 2 & -1 \\ 0 & 0 & 0 & -1 & -1 & 2 \end{pmatrix}.$$

Computing the Graph Laplacian

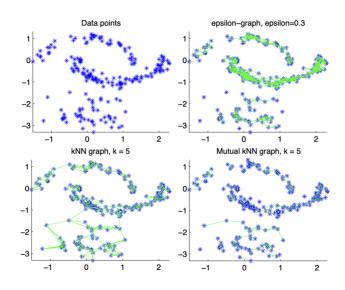


What is the smallest eigenvalue/eigenvectors of the graph laplacian? What would happen if we have *I*-connected component

$$\max f^{\top} L f$$
 s.t. $f^{\top} 1 = 0, ||f||_2 = 1$

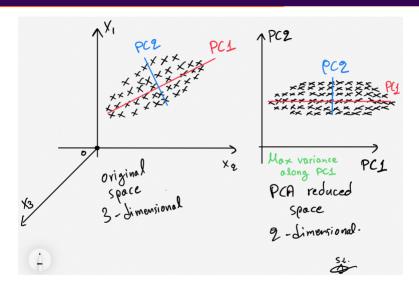
Then run a k-means on the spectral clustering representation f. (homework)

Graph

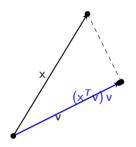


Dimension Reduction

Principal Component Analysis (PCA)



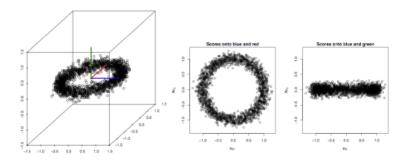
Projection



- $\square x^T v \in \mathbb{R} : score$
- \square $(x^T v) v \in \mathbb{R}^p$: projection

Not All Projection are the Same

Example: $X \in \mathbb{R}^{2000 \times 3}$, and $v_1, v_2, v_3 \in \mathbb{R}^3$ are the unit vectors parallel to the coordinate axes



Not all linear projections are equal! What makes a good one?

PCA: Preserve Most Information

We have n d-dimensional data points $x_1, x_2, \ldots, x_n \in \mathbb{R}^d$ and a parameter $k \in \{1, 2, \ldots, d\}$. We assume that the data is centered, meaning that $\sum_{i=1}^n x_i = 0$. (How to do that?)

<u>AIM.</u> Find directions that maximize the information preserved The output of the method is defined as k orthonormal vectors v_1, v_2, \ldots, v_k — the "top k principal components" — that maximize the objective function :

$$\frac{1}{n}\sum_{i=1}^n\sum_{j=1}^k (x_i\cdot v_j)^2.$$

Question: Why we want the principal components orthonormal?

Review: Projection Under Orthonormal Basis

Let $A = [v_1, \dots, v_k]$ where v_1, \dots, v_k are orthonormal. Remind. Least square solution: $A\beta \approx b$, then $\beta = (A^{\top}A)^{-1}A^{\top}b$ Then $A\beta = A(A^{\top}A)^{-1}A^{\top}b$

Review. Orthonormal means $A^{T}A = I$

Check. Project b to span $\{v_1, \dots, v_k\}$ means

$$\langle v_1, b \rangle v_1 + \langle v_2, b \rangle v_2 + \cdots + \langle v_k, b \rangle v_k$$

Matrix Formulation

Matrix Formulation: Define $V \in \mathbb{R}^{d \times k}$ with columns v_1, \dots, v_k , representing the k principal components.

The total variance captured when projecting the data onto the subspace spanned by \boldsymbol{V} is

$$\frac{1}{n}||XV||_F^2 = \operatorname{tr}\left(V^T\left(\frac{1}{n}X^TX\right)V\right) = \operatorname{tr}(V^TSV),$$

where $S = \frac{1}{n}X^TX$ is the covariance matrix.

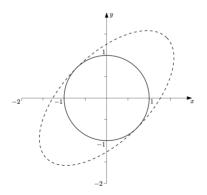
Note that
$$||A||_F^2 = \operatorname{tr}(A^T A)$$
 For $A = XV$, we have:
$$||XV||_F^2 = \operatorname{tr}((XV)^T (XV)) = \operatorname{tr}(V^T X^T XV). \qquad \text{(for } \operatorname{tr}(AB) = \operatorname{tr}(BA))$$

$$\max_{V \in \mathbb{R}^{d \times k}} \operatorname{tr}(V^T S V)$$
 subject to $V^T V = I_k$.

Matrix Formulation

Covariance Matrix: Rotation on Principal Component

$$\begin{pmatrix} \frac{3}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{3}{2} \end{pmatrix} \; = \; \underbrace{\begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix}}_{\text{rotate back } 45^\circ} \; \cdot \; \underbrace{\begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}}_{\text{stretch}} \; \cdot \; \underbrace{\begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix}}_{\text{rotate clockwise } 45^\circ}$$



PCA as Top Eigenvectors

PCA boils down to computing the k eigenvectors of the covariance matrix $X^{T}X$ that have the largest eigenvalues.

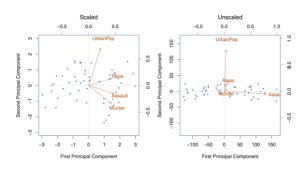
Eigen-Face





The components ("eigenfaces") are ordered by their importance from top-left to bottom-right. We see that the first few components seem to primarily take care of lighting conditions; the remaining components pull out certain identifying features: the nose, eyes, eyebrows, etc.

Normalize Your Data



Murder, Rape, and Assault are reported as the number of occurrences per 100, 000 people, and UrbanPop is the percentage of the state's population that lives in an urban area. These four variables have variance 18.97, 87.73, 6945.16, and 209.5