

# World Class

<b>Reverse Engineering</b>									
Basket in Base									
Your model is in Base and is identical									
								Yes	No
								Yes	No
<b>Opening Doors</b>									
Door opened by pushing handle down									
								Yes	No
<b>Project-Based Learning</b>									
Loops on scale									
		0	1	2	3	4	5	6	7 8
<b>Apprenticeship</b>									
Model presented to Referee									
Touching circle, not in Base, people Bound									
								Yes	No
								Yes	No
<b>Search Engine</b>									
Only Slider caused wheel to spin 1+ times									
Only correct loop removed									
								Yes	No
								Yes	No
<b>Sports</b>									
Ball shot from east/north of "Shot Lines" toward Net									
Ball touching mat in Net at end of match									
								Yes	No
								Yes	No
<b>Robotics Competition</b>									
Only Robotics Insert installed									
Loop no longer touching model									
								Yes	No
								Yes	No
<b>Using the Right Senses</b>									
Loop no longer touching model									
								Yes	No
<b>Remote Communication / Learning</b>									
Referee saw robot pull slider west									
								Yes	No
<b>Thinking Outside the Box</b>									
Idea model not touching Box, Box never in Base, Bulb faces UP									
Idea model not touching Box, Box never in Base, Bulb faces DOWN									
								Yes	No
								Yes	No
<b>Community Learning</b>									
Loop no longer touching model									
								Yes	No
<b>Cloud Access</b>									
SD card is UP due to inserted "key"									
								Yes	No
<b>Engagement</b>									
Yellow section moved south									
Dial major marker color									
N/A		Red 10%	Orange 16%	Green 22%	Blue 28%	Red 34%	Blue 40%	Green	
						46%	Orange 52%	Red 58%	
Ticks past major marker		N/A	0	1	2	3	4	5	
<b>Adapting to changing conditions</b>									
Model rotated 90-ish degrees CCW									
								Yes	No
<b>Penalties</b>									
Robot, Sprawl, Junk penalties									
		0	1	2	3	4	5	6	7 8