World Class

Reverse Engineering
Basket in Base — **Yes** **No**
Your model is in Base and is identical — **Yes** **No**

Opening Doors
Door opened by pushing handle down — **Yes** **No**

Project-Based Learning
Loops on scale — **0 1 2 3 4 5 6 7 8**

Apprenticeship
Model presented to Referee — **Yes** **No**
Touching circle, not in Base, people Bound — **Yes** **No**

Search Engine
Only Slider caused wheel to spin 1+ times — **Yes** **No**
Only correct loop removed — **Yes** **No**

Sports
Ball shot from east/north of "Shot Lines" toward Net — **Yes** **No**
Ball touching mat in Net at end of match — **Yes** **No**

Robotics Competition
Only Robotics Insert installed — **Yes** **No**
Loop no longer touching model — **Yes** **No**

Using the Right Senses
Loop no longer touching model — **Yes** **No**

Remote Communication / Learning
Referee saw robot pull slider west — **Yes** **No**

Thinking Outside the Box
Idea model not touching Box, Box never in Base, Bulb faces UP — **Yes** **No**
Idea model not touching Box, Box never in Base, Bulb faces DOWN — **Yes** **No**

Community Learning
Loop no longer touching model — **Yes** **No**

Cloud Access
SD card is UP due to inserted "key" — **Yes** **No**

Engagement
Yellow section moved south — **Yes** **No**

Dial major marker color

N/A	Red 10%	Orange 16%	Green 22%	Blue 28%	Red 34%	Blue 40%	Green 46%	Orange 52%	Red 58%

Ticks past major marker — **N/A 0 1 2 3 4 5**

Adapting to changing conditions
Model rotated 90-ish degrees CCW — **Yes** **No**

Penalties
Robot, Sprawl, Junk penalties — **0 1 2 3 4 5 6 7 8**