CMOS 4000 And 7400 Series

Integrated Circuit Tester

Based on the work of Baweja Akshay and expanded by A.S.G

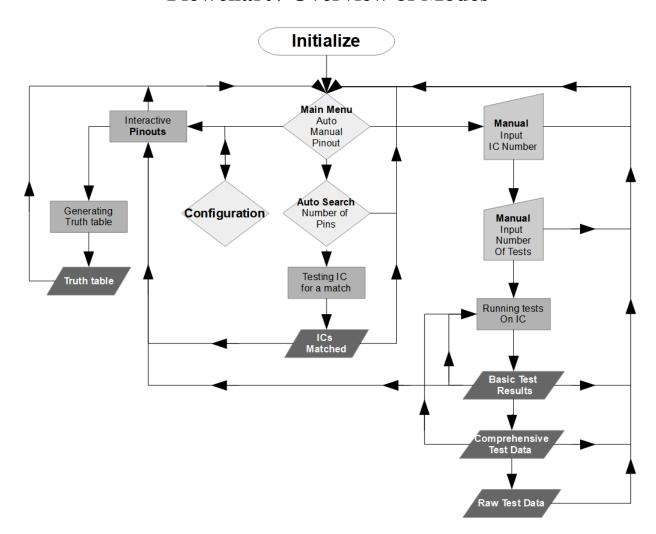
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Improvements and additional features

- No need to reboot the device after each test.
- Interactive graphical layout of Ics which lets the user check the functionality of Ics manually without additional circuitry.
- Truthtable/Timing diagram generation, both manually and automatically generated. Saves the truthtables as a CSV file.
- Loop testing available, the program keeps track of both passed and failed tests as well as which pins are the most like to be the culprits.
- Shortcut for Last test routine so the user can quickly test a sum of the same IC types.
- Configuration where the user can tailor the behaviour of the program to suit their testing needs.
- Added tests and pinouts for 20 & 24 Pin ICs

Flowchart / Overview of Modes



Setup and Install

Bill of Materials.

Arduino Mega 2560.

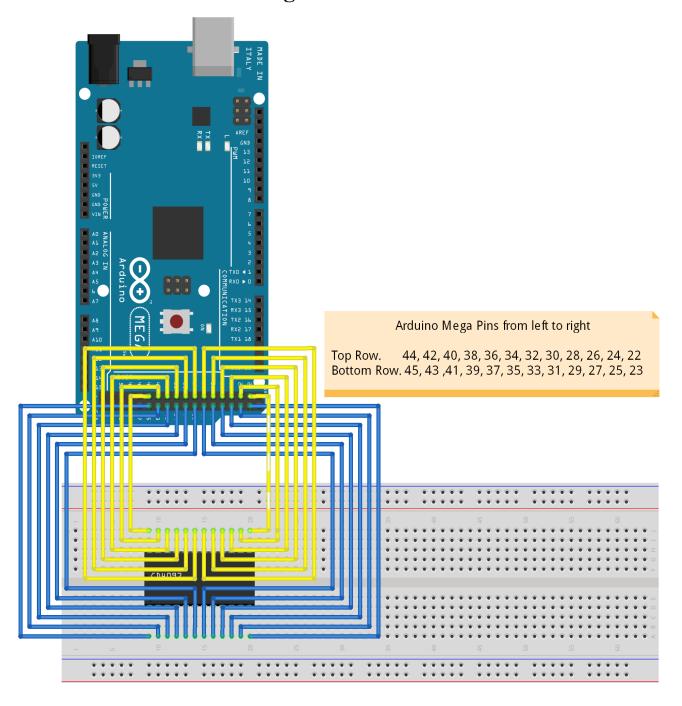
2,4" TFT Screen with an SD card slot(shield that you can plug directly on top of the arduino Mega see picture on the next page).

Breadboard(24 pin ZIF socket optional).

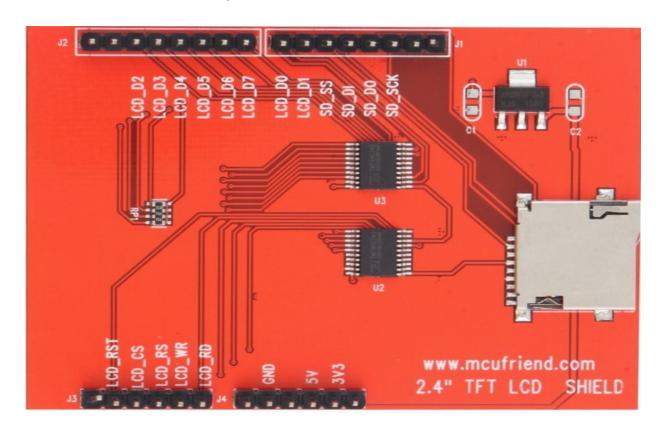
24 wires.

ICs to test.

Wiring on breadboard



2,4" TFT Shield Pinout



Shield placement on Arduino Mega2560



Intergrated Development Enviroment

Arduino IDE or other compatible IDE (It was developed on Arduino IDE 2)

Libraries for arduino

All the libraries that the tester uses are in the library folder in my GitHub.

Adafruit GFX or SPFD5408

(depends on the controller for your screen, most of the \$10-\$20 ones are of the SPFD variant)

Put it into **Documents/Arduino/Libraries**

Kicksort

Sorting library needs to be copied to **Documents/Arduino/Libraries**

SD library

This library needs to be referenced to directly or you need to override the one that comes with the arduino IDE. Placing it into you library folder in documents **isn't enough!!!**

for Arduino IDE 2 on Windows 10 it can be found here C:\Users\UserName\AppData\Local\Arduino15\libraries

SD Card Files

Copy **Pinouts.txt** & **Database.txt** which can be found in the main folder of the program onto a SD card and insert it into the TFT shield.

TFT screen troubleshooting

Unfortunately there are plenty of different screens and controllers being sold as the same thing. Same controller and the same pinouts yet they need to be addressed a bit differently

I have only acquired and tested the SPFD5408 variants and even they don't work exactly the same...: [

- If your screen only shows white after you have uploaded the sketch you probably need the other one. As in the adafruit type instead of the SPFD one or vice versa.
- If you have graphics on your screen after uploading but touch doesn't work. try uncommenting lines 63 to 68 in IC_Tester.ino and comment out the lines 54 to 57.
- If the touch is inverted you might need to switch the last values on lines 16 & 17 in Flow.ino depending on how it's inverted...

```
p.y = map(p.y, TS_MINX, TS_MAXX, tft.height(), 0);
p.x = map(p.x, TS_MINY, TS_MAXY, 0,tft.width());
```

If the touch is still inverted or more like at two places at once...:/ then you could try to uncomment out line 159 in SPFD5408 TouchScreen.cpp that can be found in the SPFD5408 folder

```
return TSPoint(x, y, z); //uncomment this line
```

■ If then the touch is only inverted then change the line to something of the sort

```
return TSPoint(1023-x, 1023-y, z);
```

■ Here are some helpful links:

https://www.instructables.com/How-to-use-24-inch-TFT-LCD-SPFD5408-with-Arduino-U/https://create.arduino.cc/projecthub/SurtrTech/interfacing-and-fixing-touch-problem-on-tft-lcd-2-4-shield-fd7738

If an IC fails a test. Don't panic!

There are few things that could be wrong other than the IC being faulty.

- Check the wiring connections if testing is done on a breadboard and traces/connectivity if done on a PCB
- Test a known good device if on hand and see if it passes the test.
- If the good device passes the test, check if the failed IC is from the same manufacturer as the one that passed the test. Sometimes the difference between them is active on rising edge versus falling edge which makes a test for one of them out of sync while the other one passes.(e.g HEF Versus TI) Better yet sometimes a pin is present on an IC from one manufacturer but not from another manufacturer e.g HEF4068(NAND) Vs CD4068(AND&NAND)
- There might be an error in the test for that type of IC. I was only able to test about 50% of the 4000 series and less than 10% of 7400 series since I don't own nearly all of them. My speculation is that Baweja Akshay was in a similar boat since I have already fixed few tests myself as added some from scratch as well. So check the datasheet, use Pinout Mode to verify the logic and see if the logic of the test is off. Often its as simple as getting the IC to an "initial state" before beginning the test.
- **Note** that some 4000 & 7400 series IC's can't be tested without external components e.g 4045 which needs a crystal oscillator to function.

Tips and Tricks

- Always have a datasheet to reference to when testing unfamiliar Ics.
- If there isn't a test available for the type of IC you want to test and you want to roll your own. See if there is a version of it in Pinout Mode. Sometimes the datasheet doesn't remove all doubt about the sequence of events on the logic of the IC therefore with the aid of Pinout mode you can easily verify the logic of each pin which does help with creating a test for said IC.
- General handling of CMOS chips is touched upon further on the next page

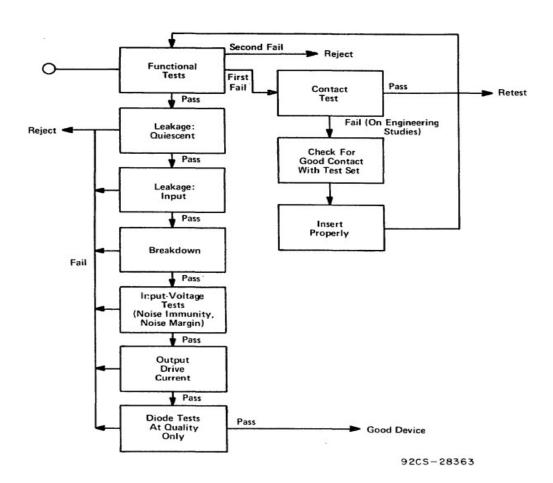
Fundamentals of Testing COS/MOS Integrated Circuits

From 1983 RCA CMOS Databook: page 740

ICAN-6532

"Users should follow the sequence below when testing COS/MOS devices:

- I. Insert the device into the test socket.
- 2. Apply VDD.
- 3. Apply the input signal.
- 4. Perform the test.
- 5. On completion of test, remove the input signal.
- 6. Turn off the power supply (VDD).
- 7. Remove the device from the test socket and insert it into a conductive carrier. COS/MOS, devices under test must not be exposed to electrostatic discharge or forward biasing of the intrinsic protective diodes"



Note*

This tester only tests the logical functions of an IC at a low speed and is therefore only a small indication of a health of an IC. Even if the IC under test passes all the tests on the tester there might be other issues with it that only analog tests could give a truthful image. See flowchart of a typical test sequence of an IC from RCA CMOS Databook above.

The Arduino Input pins are high impedense and so are the input pins of CMOS devices therefore if the IC under test is heating up there is probably something wrong with it. Very small current is present in this circuit when the IC works as intented. The Arduino Mega and the TFT screen generate some heat however so that is to be expected.

IC Tester Modes

Last Test:

Repeates the last IC test or Truth table/Timing diagram Cycle.

Fast Searching/Testing ON/OFF:

Disables the update of graphics in IC Search and IC Test which speeds up the process quite a bit.



IC Searching/Identifying:

Goes through a database of tests to determine which IC charachteristics the IC under test behaves as.

- 1. Select the number of pins on the IC (14, 16, 20, 24)
- 2. Runs tests. If fast mode is OFF then the Ics that are being tested against will be displayed on the screen.
- **3.** Displays the names of IC's that the IC passed the tests.

Note that often there are few Ics that are very similar in function usually the only differences are buffered versus unbuffered outputs and open collector versus open drain etc. So it's not uncommon for the tester to find more than one type of IC that functions like the one under test.(very common with gate type ICs they come in all sorts of flavors and hex inverters) e.g 40106 tests the same as 4069, 7404, 7405, 7406, 7414 and 7416 which are all hex inverters with the same pinout but different analog properties.



4. User can choose to go to interactive pinout by using the 74xx/4xxx buttons or main menu. **Note** that the further down the pinout.txt file a IC information is stored the longer it takes for the program to load it.

IC Testing:

Runs the IC through series of tests and keeps track of which test the IC failed and/or passed

- 1. Enter the number of the IC under test
- 2. Enter the number of tests that the program should execute (entering 0 makes the program loop until the user stops the test)
- 3. While the program tests the IC the user can see how many tests the IC has passed or failed **IF Fast mode is disabled.** *the user can stop the test at anytime by touching the screen for a second*

The variables that keep track of number of passed, failed tests etc, are 16-bit positive integers(word variable) so they cap out at 65536 in which the program rolls them over to 0. This can be easily modified if the user choses so by making them into 32-bit **unsigned long** variables which will roll over after 4,294,967,295(this will however make the number to big for the screen and will wrap around to the other side.

The variables that keeps track of number of passed & failed tests can be found in the IC Test.ino

- 4. When testing has finished the number of passed and failed tests is displayed and the user can navigate to the Error screen which has more detailed information about the results.
 - a) Error section: Displays the pin functions, pin names, arduino IO's and which pins were most likely the ones that failed the test(if any).

Note. Since the program has no way of testing(reading) the input pins of the IC with any level of certainty the user must read a bit further into the results to make sure that an **Input** pint isn't creating a false error reading of an **Output** pin. The Pinout section is a great way to manually check the functions of each pins on the IC.

b) **Data section:** Here the user can see which lines and which pin the IC under test had fail. Not only useful to see which pins don't work as expected but also very handy when creating your own tests to be able to spot errors in them and where those errors are.

Pinout: → **Truth table/Diagram**

Interactive graphical representation of the chosen IC. From here the user can go to the Truthtable/ Timing diagram section of the program.

- In the graphical display of the user chosen IC the user can touch the inputs and see the readings of the outputs.
- If the IC has a clock pin a Clock menu button will be displayed and when activated will similated a clock pulse on that pin.e.g 4040, 4024 amd 4017
- If the IC is a Mux/Demux or any IC with bi-directional input/outputs an In/Out button will be displayed and when pushed will switch inputs with outputs and vice versa.eg. 4053,4067 and 4097
- The naming convention for inputs/outputs etc, on both the 4000 and 7400 series can be a bit inconsistent and even differ between books and datasheets so some of that inconsistancies have transferred into the IC tester. To make things even more confusing I had to make the designing choice of only having '8' characters per pin name which left me with shortening many names making it harder to read.

Truth table/Timing Diagram

Here the user can create a truth table / timing diagram.

- <u>Truth table/Timing diagram button</u> switches between the two.
- **Trig button** switches between rising edge / rising and falling edge for the input logic. The user can manually control the input logic(High or low) using the Input buttons.
- <u>Cycle button</u> lets the user select how many clock cycles to generate the truth table. If there is a Clock pin on the IC the user must push the Clock menubutton for the generation to start but if the IC has no Clock pin the program will automatically pulse each Input pin with a High to Low signal for as many clock cycle as the user has chosen. If you wish to stop the cycle press anywhere for a second.
- P-Button Will print out on the serial monitor the truth table that has been saved to the SD card in CSV format. See Converting CSV into a Timing Diagram section.
- C-Button Erases the truth table file.
- **B-Button** Goes back to Pinout section.
- M-Button Goes back to main menu

Configuration:

Here the user can set some parameters which makes life easier.

- Last IC displayed on keypad. Helpfull if the user is repeatedly testing the same kind of an IC.
- Enable Input with Clock. Helpfull if the IC under test in truth table generation has a Clock pin and also an Enable/Clear pin that needs logic High signal for the outputs to be active e.g the 74273 IC
- Clear CSV after each run. Sometimes you would want to record all of your truth table generated other times it would be unnessecery clutter.
- Auto set to diagram Helpfull if the user is repeatedly using the diagram over the truth table
- Free Memory Here you can see how much of the memory is left on the stack. Testing many different Ics in a session slowly starts eating up the memory and if the tester is acting irrationally then a reboot might be in order.
- **Speed of Clock 1-10.** 1 = slowest, 10 = fastest.
- **Screensaver 1-2.** Set the screensaver On/Off and the time 1 = 30 seconds, 2 = 60 seconds.

Constructing your own tests

It's fairly easy to make your own tests if your IC is not already in the database as well can you override the one already in place if you find it to be incomplete.

- 1. Get a hold of a datasheet for the IC. Make sure it's from the same manufacturer and if the suffixes match the one's you have on hand.
- 2. Check if there is already a pinout of said chip in the program. If not, go through the trouble of creating one (see pinouts.txt section above) since it will make it many times easier to make a test if you can verify the sequence of events manually.
- 3. Reference below on how the tests are constructed.

Database.txt

Tests parameters supported:

0 = Logic Low(0V) applied on Input

1 = Logic High(+5V) applied on Input

L = Logic Low(0V) read on Output

 $\mathbf{H} = \text{Logic High}(+5\text{V}) \text{ read on Output}$

X = Don't Care read on Output

C = Clock pulse for Ics with Clock inputs see 4017 example.

G = 0V for VSS Pin

V = +5V for VDD or VCC Pin

Basic Example Code

\$4000 //\$Name of IC

Dual 3-input NOR gate and inverter //Description of IC(Only one line)

14 //Number of pins on IC

00000HG1LH000V //First line of test. Applying +5V on Pin 8 and reading High on Pins 10 & 6, Low on Pin 9

00000HG0HH000V 00001LG0HL100V 00010LG0HL010V 00011LG0HL110V 00100LG0HL001V 00101LG0HL101V

00110LG0HL011V

 $\textbf{00111LG0HL111V} \hspace{0.5cm} /\!/ Last \ line \ of \ test. \ Applying +5V \ on \ Pins \ 3,4,5,11,12 \ \& \ 13 \ Reading \ High \ on \ Pin \ 9 \ and \ Low \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 3,4,5,11,12 \ \& \ 13 \ Reading \ High \ on \ Pin \ 9 \ and \ Low \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 6 \ and \ 10 \ Applying +5V \ on \ Pins \ 9 \ and \ Pins \$

Example with a Clock Pin

\$4017

Decade counter (5-stage Johnson counter) with 10-output decoder

16

LLHLLLGLLLH0C1V //First line of test. Applying +5V on Pin 15(Reset) to clear the counter to zero count, Pin 13(Inhibit) is set to Low

//Applied a clock pulse to Clock pin to make sure that the IC resets to zero. All outputs are read Low except Q0 and //Carry Out. Note that in this case and many other the IC needs to be set to an "initial state" first before actual testing //can can begin. Often X(don't care) is adviced on Outputs while/before the IC reaches its "initial state" since the

//Outputs could be in a random state when the IC is powered on (very common with shift registers)

LHLLLLGLLLH0C0V //Second line of test and the second Clock pulse. Now Output on Pin 2 is High(Q1) and Reset Pin has been pulled

//Low

LLLHLLLGLLLH0C0V //Third line of test and Clock pulse. Pin 4(Q2) and Pin 12(Carry Out) are High LLLLLHGLLLH0C0V //Fourth line of test and Clock pulse. Pin 7(Q3) and Pin 12(Carry Out) are High //Fifth line of test and Clock pulse. Pin 10(Q4) and Pin 12(Carry Out) are High LLLLLLGLHLH0C0V //Sixth line of test and Clock pulse. Pin 1(Q5) is High and Pin 12(Carry Out) is Low HLLLLLLGLLLL0C0V LLLLHLLGLLLL0C0V //Seventh line of test and Clock pulse. Pin 5(Q6) is High and Pin 12(Carry Out) is Low LLLLHLGLLLL0C0V //Eight line of test and Clock pulse. Pin 6Q7) is High and Pin 12(Carry Out) is Low LLLLLLGHLLL0C0V //9th line of test and Clock pulse. Pin 9(Q8) is High and Pin 12(Carry Out) is Low LLLLLLGLLHL0C0V //10th line of test and Clock pulse. Pin 11(Q9) is High and Pin 12(Carry Out) is Low LLHLLLLGLLLH0C0V //11th line of test and Clock pulse. Pin 2(Q0) and Pin 12(Carry Out) are High LLHLLLLGLLLH1C0V //12th line of test and Clock pulse. Pin 2 (Q0) and Pin 12(Carry Out) are High

Pinouts.txt

Pin Functions supported:

Input: General Input
Output: General Output

Clock: Clock pin, this pin can be clocked by the program In/Out: Bi-directional pin(mux/demux etc.) by default an Input Out/In: Bi-directional pin(mux/demux etc.) by default an Output

NC: Not connected(non functional pin on an IC)
VCC: Positive voltage Pin(in our case+5V)

GND: 0V Pin

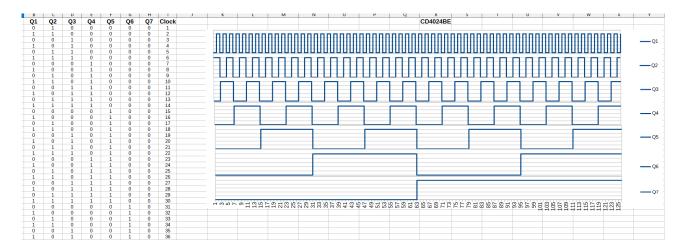
Basic Example Code

\$4000		//\$Name of IC (\$ should always be in front of the IC name for seperation purposes)
Dual 3-input NOR gate and inverter		//Description of IC(One line only!)
14		//Number of Pins on IC
NC % NC	Pin 1	//Left side = Pin Function % Right side = Pin Name
NC % NC	Pin 2	//8 characters % 8 characters
Input % 1A	Pin 3	//The pins on the left on the IC must end on the 8th
Input % 1B	Pin 4	//character for formating purposes. In this example
Input % 1C	Pin 5	//it's the first 7 pins.
Output % Out 1	Pin 6	
GND % 0V	Pin 7	
Input %2A	Pin 8	// The next 7 pins are the right side of the IC and their
Output %Out 2	Pin 9	// pin names should <u>not exceed 8 characters.</u>
Output %Out 3	Pin 10	//Watch out for whitespaces after the pin names they will cause formatting issues
Input %3A	Pin 11	
Input %3B	Pin 12	
Input %3C	Pin 13	
VCC %+V	Pin 14	

Example Code with both Bi-directional Input/Outputs and a Clock pin

```
// Name of IC
                                                                               // IC description
8-stage bidirectional parallel/serial input/output register
                                                                               // Number of pins on IC
24
                                                                       Pin 1 // Bi-directional port set as Input by default
In/Out %
               DB8
                                                                       Pin 2 // The ports can be switched in Pinout Mode
In/Out %
               DB7
                                                                       Pin 3
In/Out %
               DB6
                                                                       Pin 4
In/Out %
               DB5
                                                                       Pin 5
In/Out %
                                                                       Pin 6
In/Out %
               DB3
                                                                       Pin 7
In/Out %
               DB<sub>2</sub>
                                                                       Pin 8
In/Out %
               DB1
                                                                       Pin 9 // General Input
Input %Enable A
                                                                       Pin 10
Input %SerialIn
                                                                       Pin 11
Input %
               A/B
                                                                       Pin 12 // Ground Pin(0V)
GND
        %
                0V
                                                                       Pin 13
Input %P/S
                                                                       Pin 14
Input %A/S
                                                                       Pin 15 // Can be clocked in Pinout and Truth table Mode
Clock %Clock
                                                                       Pin 16 // Bi-directional port set as Output by default
Out/In %DA1
                                                                       Pin 17 // The ports can be switched in Pinout Mode
Out/In %DA2
                                                                       Pin 18
Out/In %DA3
                                                                       Pin 19
Out/In %DA4
                                                                       Pin 20
Out/In %DA5
Out/In %DA6
                                                                       Pin 21
                                                                       Pin 22
Out/In %DA7
                                                                       Pin 23
Out/In %DA8
VCC
       %+V
                                                                       Pin 24 // VCC (+5V)
```

Converting CSV into a Timing Diagram



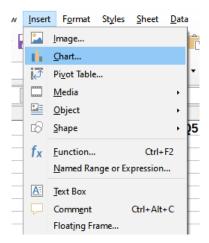
The example above was created using Libre Office. It's probably possible to create similar diagrams with other spreadsheet programs as well.

- 1. Copy the CSV file from the SD card or even easier method is by printing the data out on serial monitor. Paste it into a text file, save that file as CSV file.
- 2. Open it in a program of choice (in this example I'll be using Libre Office)

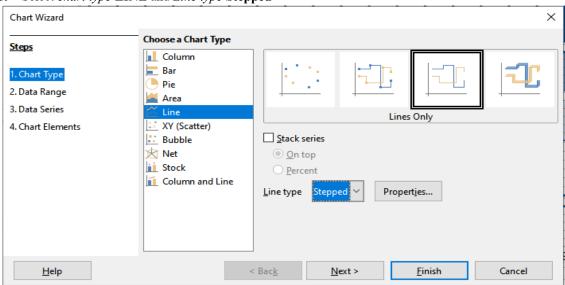
3. Example Data. Select the row and colums for the first diagram.

В	C	D
Q1	Q2	Q3
0	Q2 0	0
1	0	0
0	0	0
1	0	0
0	1	0
1	1	0
0	1	0
1	1	0
0	0	1
1	0	1
0	0	1
1	0	1
0	1	1
1	1	1
0	1	1
1	1	1

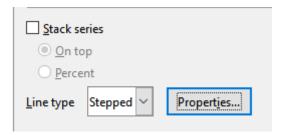
4. Insert Chart.



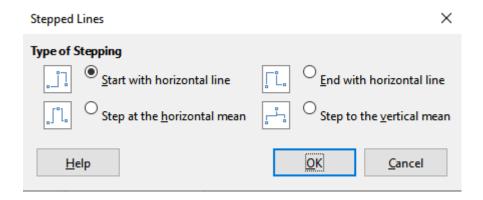
5. Select chart type LINE and Line type Stepped



6. Select properties



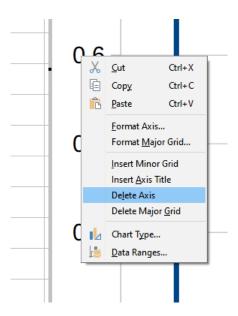
7. Select Start with horizontal line



8. Click on Finish

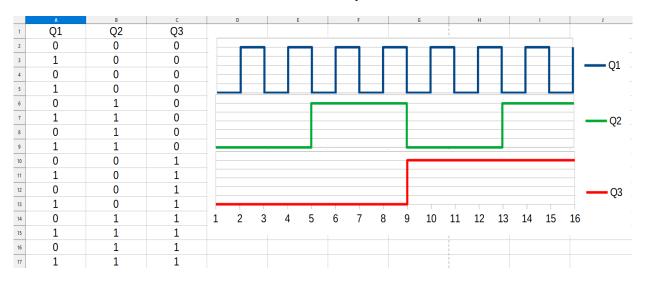


9. Right click on the left side Axis and select **Delete Axis** since we don't really need it.



10. Adjust the size of the diagram and position it as you see fit and repeat the process for the other Outputs. You can also copy the first diagram and change the **Data Ranges** on the new diagrams to make the process a lot quicker.

Finished Example



ICs Pinouts supported:

	\sim	•
4xxx	10	MIDE
7222	L)E	<i>l</i> len

4000	4001	4002	4006	4007	4008	4009	4010	40101	40102	40103	40104	40105	40106
40107	40108	40109	4011	4012	4013	4014	4015	4016	4017	4018	4019	4020	4021
4022	4023	4024	4025	4026	4027	4028	4029	4030	4031	4032	4033	4034	4035
4037	4038	4040	4041	4042	4043	4044	4045	4046	4047	4048	4049	4050	4051
4052	4053	4054	4055	4056	4057	4059	4060	4062	4063	4066	4067	4068	4069
4070	4071	4072	4073	4075	4076	4077	4078	4081	4082	4085	4086	4089	4093
4094	4095	4096	4097	4098	4099	4502	4503	4504	4508	4510	4511	4512	4514
4516	4517	4518	4520	4527	4532	4536	4538	4541	4543	4555	4556	4585	4724
							~ .						
74xx Series													
7400	7401	7402	7403	7404	7405	7406	7407	7408	7409	7410	74107	74109	7411
74112	74121	74122	74123	74124	74133	74136	74137	74138	74139	7414	74140	74145	74147
74148	74150	74151	74153	74154	74155	74156	74159	7416	74161	74163	74164	74165	74166
74169	7417	74170	74173	74174	74175	74181	74182	7419	74190	74191	74193	74194	74195
7420	7421	74221	74240	74241	74243	74244	74245	74247	7425	74250	74251	74253	74257
74258	74259	7426	74260	74265	74266	7427	74273	74276	74279	74280	74283	74286	74292
74293	74294	74297	74298	74299	7430	7431	7432	74321	74323	7433	7434	74348	7435
74354	74356	74365	74366	74367	74368	7437	74373	74374	74375	74377	74378	7438	74386
74390	74393	74395	74399	7442	74423	7445	74465	7447	7451	74518	74520	74521	74533
74534	74540	74541	74543	74561	74563	74564	74569	74573	74574	74575	74576	74577	74580
74590	74592	74593	74594	74595	74596	74597	74598	74624	74628	7464	74640	74641	74642
74645	74646	74647	74648	74651	74652	74653	74654	74657	74666	74667	74669	74670	74673
74674	74679	74682	74684	74686	74688	74697	74699	7473	7474	7475	74756	74756	74760
74804	74805	74808	74821	74823	74825	74827	74828	74832	74841	74843	7485	74857	7486
74867	74869	74870	74873	74874	74876	74885	7490	74990	7492	74992	7493	74994	7497

ICs Testing supported:

4xxx Series

4000 40174 4029 4066 4086 4532	4001 40175 4030 4067 4093 4543	4002 4018 4031 4068 4094 4572	4009 4019 4040 4069 4097	4010 40192 4041 4070 4098	40106 40193 4042 4071 4503	4011 4020 4043 4072 4504	4012 4021 4044 4073 4510	4013 4022 4048 4075 4511	4015 4023 4049 4076 4512	4016 4024 4050 4077 4518	40161 4025 4051 4078 4519	40162 4027 4053 4081 4520	4017 4028 4063 4082 4529
74xx S	eries												
7400 74112 74140 74164 74195 74259 7432 7446 7472	7401 74113 74145 74165 7420 7426 74365 7447	7402 7412 74147 74166 7421 74260 74366 7450	7403 74123 74148 7417 7422 74266 74367 7451	7404 74125 7415 74173 74237 7427 74368 7455 7486	7405 74126 74151 74174 74242 74273 7437 7458	7406 7413 74153 74175 74243 7428 74373 74589	7407 74132 74157 7418 74244 74280 74375 74595	7408 74133 74158 74182 74245 74283 7438 74597	7409 74136 7416 74190 7425 74292 74386 7460	7410 74137 74160 74191 74251 74293 74390 7461	74107 74138 74161 74192 74253 74294 74393 7462	74109 74139 74162 74193 74257 74298 7440 7465	7411 7414 74163 74194 74258 7430 7442 74682

References and other sources

7400 Series Texas Instruments Digital Logic Pocket Data Book (REV.B)

CMOS 4000 Series RCA CMOS Databook 1983

GitHub page for the original IC tester IC tester GitHub