

6D Robot Motion Phantom

Assembly Name :

Assembly Number :


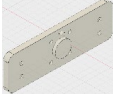
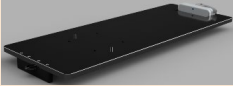
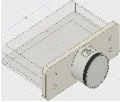
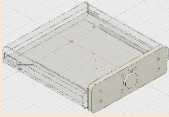
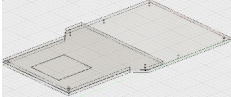
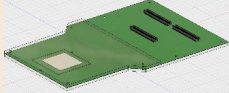
Assembly Revision :

Approval Date :

Part Count :7

Total Cost :



Part #	Part Name	Description	Qty	Units	Picture	Unit Cost	Cost
1	UR3 Robot	UR Robotic Arm	1				
2	Gripper attachment	PMMA attachment between the UR3 end effector phantom	1				
3	Base plate	Aluminium plate attaches to treatment couch and fixes UR3 robot on the surface of the plate	1			\$	-
4	Marker phantom (No detector insert)	PMMA block with three embedded gold markers (geometry configuration)	1			\$	-
5	Marker phantom (with detector insert)	PMMA block with three embedded gold markers and a detector insert for the Magic Plate system (dosimetry configuration)	1			\$	-
6	Magic Plate holder	PMMA case for Magic Plate radiation detector system (dosimetry configuration)	1			\$	-
7	Magic Plate 512	High spatial resolution radiation detector system (dosimetry configuration)	1				
Total			7				