

## pyelmer Example: 3D Electrostatic Capacitance

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# 1 Problem Description

The 3D electrostatic capacitance including fringing between top metal and bottom metal (Fig. 1) shall be calculated with Elmer FEM [1], Gmsh [2] and Python [3] including the pyelmer [4] package. ParaView [5] is used to review the calculated FEM results, such as vector fields.

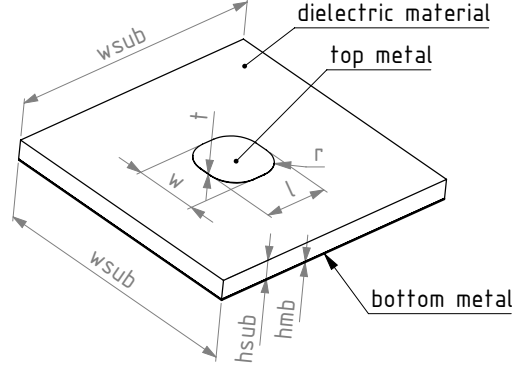


Figure 1: 3D electrostatics capacitance

The top metal has a width  $w$ , length  $l$  and metal layer thickness  $t$ . The corners of the top metal patch have a fillet  $r$ . The dielectric material layer has a relative permittivity  $\epsilon_r$ , thickness  $h_{sub}$ , width and length  $w_{sub}$ . The bottom metal layer has a layer thickness  $h_{mb}$ . The entire stack is surrounded by air.

## 2 Solution

### 2.1 Analytical Calculation

To verify the Elmer FEM computation of the capacitance, we can use a special geometrical case  $w = l$ ,  $r \rightarrow w/2 = l/2$  and  $t = h_{mb} \ll h_{sub}$ , which results in a circular microstrip disk, as shown in Fig. 2 and presented in the paper [6].

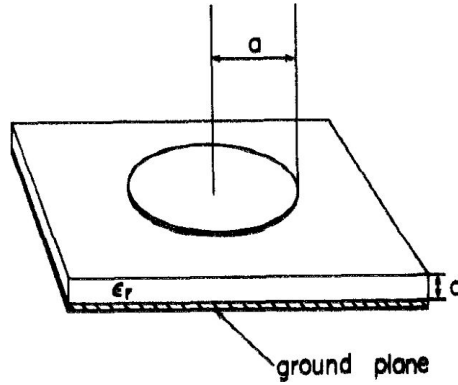


Figure 2: Effects of fringing fields on the capacitance of a circular microstrip disk [6]

The authors of the paper [6] present a quite accurate approximation formula for the capacitance within the parameter range of  $\epsilon_r = 1$  to 8.5 and  $d/a = 0.1$  to 0.5 as follows:

$$C \approx \frac{a^2 \pi \epsilon_r \epsilon_0}{d} \left\{ 1 + \frac{2d}{\pi \epsilon_r a} \left[ \ln \left( \frac{a}{2d} \right) + (1.41 \epsilon_r + 1.77) + \frac{d}{a} (0.268 \epsilon_r + 1.65) \right] \right\} \quad (1)$$

where the dielectric permittivity of vacuum  $\epsilon_0 = 8.854 \times 10^{-12} \text{ C V}^{-1} \text{ m}^{-1}$ .

## 2.2 Elmer FEM Calculation

Prerequisite is the installation of the following software packages<sup>1</sup>:

1. Elmer FEM solver [1]
2. Python  $\geq 3.7$  [3] including the pyelmer package [4]
3. ParaView [5] (optional)

The installation of the Elmer FEM solver and the Python/pyelmer package is mandatory. Gmsh is part of the Python pyelmer package. However, for debugging purposes the independent Gmsh software can be installed in parallel. ParaView is optional, but it is extremely helpful to review the Elmer FEM calculated results (\*.vtu), such as vector fields.

Copy the files `3d_electrostatic_capacitance.py`, `my_simulations.yml`, `my_solvers.yml` and `my_materials.yml` in a local folder and run `3d_electrostatic_capacitance.py`.

The entire geometry definition, mesh creation, Elmer FEM calculation and results evaluation process is executed by a single Python/pyelmer top level script `3d_electrostatic_capacitance.py`, which is listed in Sect. 4.1.

## 3 Test Case and Results

### 3.1 Test Case Parameter

The structure shown in Fig. 1 is simulated with the following parameters:

Parameter	Value	Unit	Description
$w$	6	mm	top metal patch width
$l$	6	mm	top metal patch length
$t$	0.035	mm	top metal layer thickness
$r$	2.95	mm	top metal patch corner radius (fillet)
$h_{sub}$	1.524	mm	dielectric material layer thickness
$w_{sub}$	24	mm	dielectric material layer width
$\epsilon_r$	3.55		dielectric material layer relative permittivity (Rogers RO4003C material [7])
$h_{mb}$	0.1	mm	bottom metal layer thickness

Table 1: Test case parameter

### 3.2 Capacitance Calculation Results

Analytical solution (Eqn. 1)	$C = 1.012 \text{ pF}$
Elmer FEM computation	$C = 1.062 \text{ pF}$

Table 2: Analytical solution and Elmer FEM computation result of the capacitance

The Elmer FEM computation result listing, CPU-time of the Elmer solver in [second], excluding meshing:

```
Errors: []
Warnings: []
Statistics: {'CPU-time': 86.6, 'real-time': 86.6}
Relative Change: 5.10E-12
#####
w: 6E-3
l: 6E-3
r: 2.95E-3
Capacitance: 1.062E-12
#####
```

<sup>1</sup>available for Windows, Linux, Mac. References shown mainly for Windows.

The agreement of the Elmer FEM computation result with the approximation formula Eqn. 1 is very good. However, it is very important to have small mesh size in the regions of high field gradients (Fig. 3). Otherwise the Elmer FEM computation result may be significant wrong despite fast FEM algorithm convergence.

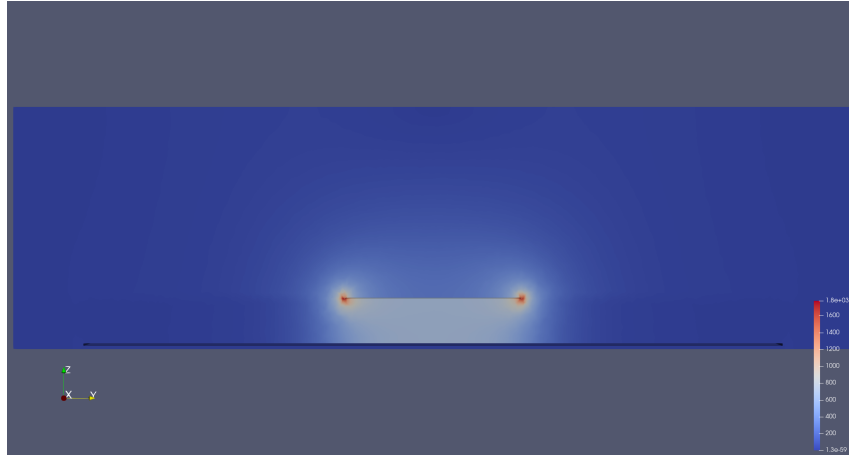


Figure 3: Calculated electric field magnitude (cross section of Fig. 4)

### 3.3 Discussion of the Elmer FEM Solution and Boundary Conditions

1. The surrounding air of the structure is modeled by a proper air box, as shown in Fig. 4. The size of the air box is calculated in line 123 and 124 (see Sect. 4.1). The top height of the air box is designed properly in order to cover the fringing field in the air.

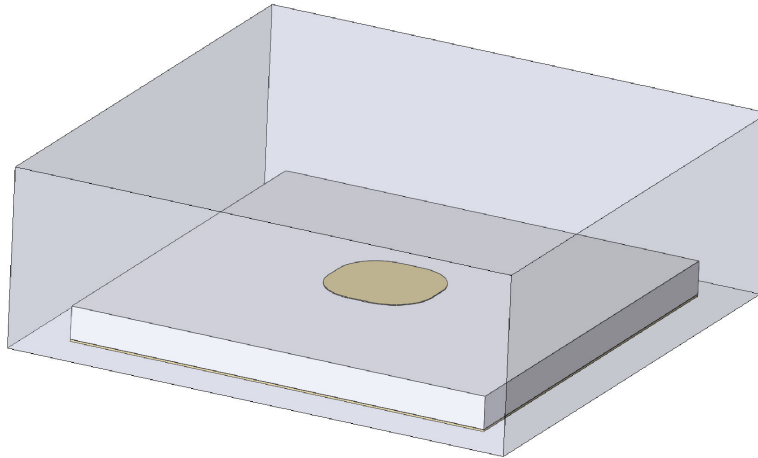


Figure 4: 3D model including air box

2. The top metal and bottom metal layer are considered as perfect conductor. Therefore, these two bodies are not meshed in order to keep the required FEM meshing time and FEM computation time as low as possible. As a consequence, the structure consists of only two bodies (see line 128) which are required to be meshed:
  - (a) dielectric material layer
  - (b) air box

3. To calculate the electrostatic capacitance between bottom metal and top metal, all surfaces need to be assigned to a potential value. All bottom metal body surfaces (there are 6 surfaces) are assigned to a potential of 0 V. All top metal body surfaces (there are 10, because of the corner radius) are assigned to a potential of 1 V. Further, it is very important to assign the correct value of the potential difference (line 269). Otherwise a wrong capacitance value will be calculated.

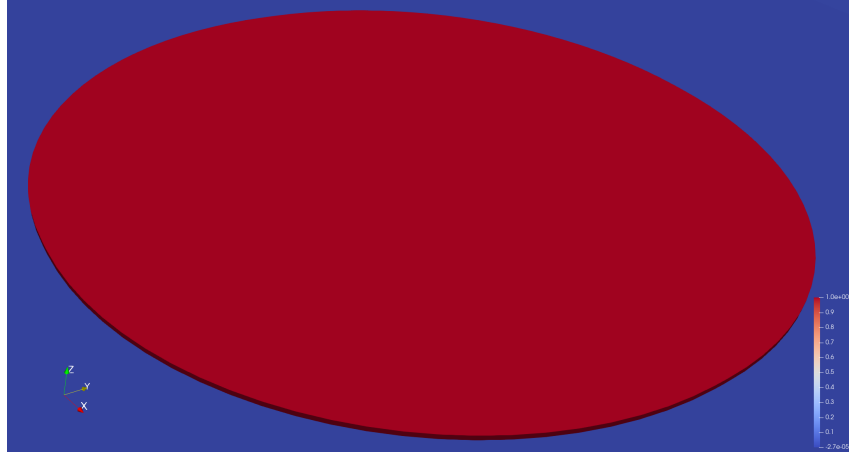


Figure 5: Potential distribution (top metal zoom view)

4. The correct assignment of physical bodies and boundary conditions are essential. The assignment of physical groups is semi-automated in this example, e.g. line 193, 194. The entity numbers of surfaces and physical group assignment is done automatically (e.g. line 205, 206). The general step approach of 3D modeling using pyelmer and Gmsh can be summarized as follows:
  - (a) 3D modeling of the structure using Gmsh API functions
  - (b) Assign (only one time!) physical groups of required bodies
  - (c) Assign boundaries using the style `id_for_elmer = add_physical_group(...)`. This can be done with automatic extraction using functions such as `getMyEntitiesInBoundingBox` or by manual assignment, e.g. `ph_sub`, `ph_ab` at line 193, 194.
  - (d) Meshing using Gmsh API functions
  - (e) Use Gmsh GUI to check if the assignment (step 2 above) is correct: press Ctrl+V, afterwards click through the physical groups
  - (f) For the definition of bodies use the `id_for_elmer` from step 2 above
5. Meshing notes: The set up of the mesh including optimization is done using the Gmsh application programming interface (API) [8]. The geometric meshing parameters could be further optimized. However, it works well at this point of time, but the FEM computation time and meshing time could be further reduced by an optimized mesh.

## 4 Source File Listings

### 4.1 Python (pyelmer) Script

The following Python script is based on pyelmer [4] and is used to set up and run the Elmer FEM simulation from Python including model geometric parameter definition, meshing, definition of boundary conditions, Elmer FEM simulation and extraction of results.

Listing 1: pyelmer code «3d\_electrostatic\_capacitance.py»

```

1 import os
2 import gmsh
3 from pyelmer import elmer, post
4 from pyelmer import execute
5 from pyelmer.gmsh import add_physical_group
6 from math import floor, log10
7
8
9 #####
10 ## Settings
11 #####
12
13 # The following switches defined are for debugging purposes
14 # run Elmer solver. Default: True
15 run_solver = True
16 # run Gmsh and create mesh. Default: True
17 run_mesher = True
18 # run Gmsh GUI in order to view and verify the mesh manually before Elmer simulation.
   Default: False
19 run_gmsh_gui = False
20
21 # Parameter Definition
22 w = 6e-3 # pad width
23 l = 6e-3 # pad length
24 r = 2.95e-3 # pad fillet radius
25 t = 0.035e-3 # metal thickness
26 tol = 1e-6 # search tol
27 hsub = 1.524e-3 # R04003C substrate height
28 hmb = 0.1e-3 # bottom metal height
29 wsub = 4 * max([w, l]) # substrate width
30 h_ab = 5 * (hsub + hmb + t) # air box height
31 w_ab = 1.2 * wsub # air box width
32
33 # set up working subdirectory
34 sim_dir = "/simdata/"
35
36 if not os.path.exists(sim_dir):
37     os.mkdir(sim_dir)
38
39 #####
40 ## Some useful functions
41 #####
42
43
44 def getMyEntitiesInBoundingBox(xmin, ymin, zmin, xmax, ymax, zmax, dim):
45     entities = gmsh.model.getEntitiesInBoundingBox(
46         xmin, ymin, zmin, xmax, ymax, zmax, dim
47     )
48     all_entities = []
49     for item in entities:
50         all_entities.append(item[1])
51     return all_entities
52
53
54 # scan err, war, stats and results
55 def extract_results_logfile(sim_dir):
56     """Scan log file for errors and warnings.
57
58     Args:
59         sim_dir (str): Simulation directory
60
61     Returns:
62         list[str], list[str], dict: error messages, warnings, statistics
63     """
64     with open(sim_dir + "/elmersolver.log", "r") as f:
65         log = f.readlines()
66         for i in range(len(log)):
67             log[i] = log[i][:-1]
68         for line in log:

```

```

69         if "StatElecSolve: Capacitance" in line: # extract capacitance from log file
70             s = " ".join(line.split()).split(" ")
71             capacitance = float(s[3])
72         if (
73             "StatElecSolve: Relative Change" in line
74         ): # extract relative change from log file
75             s = " ".join(line.split()).split(" ")
76             rel_change = float(s[4])
77     return capacitance, rel_change
78
79
80 # engineering format
81 def powerise10(x):
82     """Returns x as a*10**b with 0 <= a < 10"""
83     if x == 0:
84         return 0, 0
85     Neg = x < 0
86     if Neg:
87         x = -x
88     a = 1.0 * x / 10 ** (floor(log10(x)))
89     b = int(floor(log10(x)))
90     if Neg:
91         a = -a
92     return a, b
93
94
95 def eng(x):
96     """Return a string representing x in an engineer friendly notation"""
97     a, b = powerise10(x)
98     if -3 < b < 3:
99         return "%.4g" % x
100     a = a * 10 ** (b % 3)
101     b = b - b % 3
102     return "%.4gE%s" % (a, b)
103
104
105 #####
106 ## Geometry modeling using gmsh
107 #####
108
109 gmsh.initialize()
110
111 gmsh.model.add("3d_electrostatic_capacitance")
112 geom = gmsh.model.occ
113
114 # top metal
115 m1 = geom.addBox(-w / 2, -1 / 2, 0, w, 1, t)
116 geom.fillet([m1], [1, 3, 5, 7], [r], True)
117
118 # substrate
119 sub = geom.addBox(-wsub / 2, -wsub / 2, -hsub, wsub, wsub, hsub)
120
121 # bottom metal
122 m2 = geom.addBox(-wsub / 2, -wsub / 2, -(hsub + hmb), wsub, wsub, hmb)
123
124 # airbox: we mesh only air and substrate, but not metal
125 # design proper height of air box to cover fringing fields
126 ab = geom.addBox(-wab / 2, -wab / 2, -(hsub + 2 * hmb), wab, wab, hab)
127
128 # remove metal volumes
129 geom.cut([(3, ab)], [(3, m1), (3, m2)], removeObject=True, removeTool=True)
130
131 geom.synchronize()
132 geom.fragment([(3, sub)], [(3, ab)])
133
134 #####
135 # structured meshing would be advantageous but needs further optimization
136
137 # ## M1
138 # NN = 4

```



```

139 # tf_lines = [2,13,21,23,24,22,15,3]
140 # for k in tf_lines:
141 #     gmsh.model.mesh.setTransfiniteCurve(k, NN)
142
143 # ## Sub
144 # NN = int((w-2*r)*10*1e3)
145 # tf_lines = [7,16,8,17]
146 # for k in tf_lines:
147 #     gmsh.model.mesh.setTransfiniteCurve(k, NN)
148
149 # ## MB
150 # NN = int((l-2*r)*10*1e3)
151 # tf_lines = [1,4,11,20]
152 # for k in tf_lines:
153 #     gmsh.model.mesh.setTransfiniteCurve(k, NN)
154
155 # NN = 5
156 # tf_lines = [42,45,47,41,50,53,55,49]
157 # for k in tf_lines:
158 #     gmsh.model.mesh.setTransfiniteCurve(k, NN)
159
160 # NN = int(wsub*50*1e3)
161 # tf_lines = [38,44,52,37,43,51,39,46,54,40,48,56]
162 # for k in tf_lines:
163 #     gmsh.model.mesh.setTransfiniteCurve(k, NN)
164 #####
165 #####
166 ##### Physical Groups and Boundary Conditions #####
167 #####
168 geom.synchronize()
169
170
171 # these two were identified manually in Gmsh GUI
172 # volumes = gmsh.model.getEntities(dim=3) # check volume numbers after fragment
173 ph_sub = add_physical_group(3, [2], "substrate")
174 ph_ab = add_physical_group(3, [3], "airbox")
175
176 # the others are identified using own function 'getMyEntitiesInBoundingBox'
177 m1_sfs = getMyEntitiesInBoundingBox(
178     -w / 2 - tol, -l / 2 - tol, 0 - tol, w / 2 + tol, l / 2 + tol, t + tol, 2
179 )
180 ph_m1_sfs = add_physical_group(2, m1_sfs, "metal1")
181
182 m2_sfs = getMyEntitiesInBoundingBox(
183     -wsub / 2 - tol,
184     -wsub / 2 - tol,
185     -(hsub + hmb) - tol,
186     wsub / 2 + tol,
187     wsub / 2 + tol,
188     -hsub + tol,
189     2,
190 )
191 ph_m2_sfs = add_physical_group(2, m2_sfs, "metal2")
192
193 sub_sfs = getMyEntitiesInBoundingBox(
194     -wsub / 2 - tol,
195     -wsub / 2 - tol,
196     -hsub - tol,
197     wsub / 2 + tol,
198     wsub / 2 + tol,
199     tol,
200     2,
201 )
202
203 temp_sfs = getMyEntitiesInBoundingBox(
204     -w_ab / 2 - tol,
205     -w_ab / 2 - tol,
206     -h_ab / 2 - tol,
207     w_ab / 2 + tol,
208     w_ab / 2 + tol,

```

```

209     h_ab / 2 + tol,
210     2,
211 )
212 ab_sfs = [x for x in temp_sfs if x not in (m1_sfs + sub_sfs + m2_sfs)]
213 ph_ab_sfs = add_physical_group(2, ab_sfs, "ab_sfs")
214
215 #####
216 ## Meshing
217 #####
218
219 # We can activate the calculation of mesh element sizes based on curvature
220 # (here with a target of 90 elements per 2*Pi radians):
221 gmsh.option.setNumber("Mesh.MeshSizeFromCurvature", 90)
222
223 # Finally we apply an elliptic smoother to the grid to have a more regular
224 # mesh:
225 gmsh.option.setNumber("Mesh.Smoothering", 10)
226 gmsh.option.setNumber("Mesh.Algorithm3D", 10) # faster
227 # gmsh.option.setNumber('General.NumThreads', 8)
228 # gmsh.option.setNumber("Mesh.MeshSizeMin", 0.1)
229 gmsh.option.setNumber("Mesh.MeshSizeMax", 0.2e-3)
230
231 if run_mesher:
232     geom.synchronize()
233     gmsh.model.mesh.generate(dim=3)
234     gmsh.write(sim_dir + "/3d_electrostatic_capacitance.msh")
235     # Preview mesh.
236 if run_gmsh_gui:
237     gmsh.fltk.run()
238
239 # Clear mesh and close gmsh API.
240 gmsh.clear()
241 gmsh.finalize()
242
243 #####
244 ## Elmer Setup
245 #####
246
247 sim = elmer.load_simulation("3D_steady", "my_simulations.yml")
248 # adding constants is very important, otherwise the solver calculates wrong results!
249 sim.constants.update({"Permittivity of Vacuum": "8.8542e-12"})
250 sim.constants.update({"Gravity(4)": "0 -1 0 9.82"})
251 sim.constants.update({"Boltzmann Constant": "1.3807e-23"})
252 sim.constants.update({"Unit Charge": "1.602e-19"})
253
254 # materials
255 air = elmer.load_material("air", sim, "my_materials.yml")
256 ro4003c = elmer.load_material("ro4003c", sim, "my_materials.yml")
257
258 # solver
259 solver_electrostatic = elmer.load_solver("Electrostatics", sim, r"my_solvers.yml")
260 # very important, the value must match the boundary condition abs(potential difference)
261 !!!
262 # otherwise the capacitance will be calculated wrong !
263 solver_electrostatic.data.update({"Potential Difference": "1.0"})
264
265 # equation
266 eqn = elmer.Equation(sim, "main", [solver_electrostatic])
267
268 # bodies
269 bdy_sub = elmer.Body(sim, "substrate", [ph_sub])
270 bdy_sub.material = ro4003c
271 bdy_sub.equation = eqn
272
273 bdy_ab = elmer.Body(sim, "airbox", [ph_ab])
274 bdy_ab.material = air
275 bdy_ab.equation = eqn
276
277 # boundaries
278 bndry_m1 = elmer.Boundary(sim, "top metal", [ph_m1_sfs])

```

```

278 bndry_m1.data.update({"Potential": "1.0"})
279
280 bndry_m2 = elmer.Boundary(sim, "bottom metal", [ph_m2_sfs])
281 bndry_m2.data.update({"Potential": "0.0"})
282
283 bndry_airbox = elmer.Boundary(sim, "FarField", [ph_ab_sfs])
284 bndry_airbox.data.update({"Electric Infinity BC": "True"})
285
286 # export
287 sim.write_startinfo(sim_dir)
288 sim.write_sif(sim_dir)
289
290 if run_mesher:
291     execute.run_elmer_grid(sim_dir, "3d_electrostatic_capacitance.msh")
292
293 #####
294 # execute ElmerGrid & ElmerSolver
295 if run_solver:
296     execute.run_elmer_solver(sim_dir)
297     #####
298     # scan log for errors and warnings
299     err, warn, stats = post.scan_logfile(sim_dir)
300     capacitance, rel_change = extract_results_logfile(sim_dir)
301     print("## RESULTS BEGIN #####")
302     print("Errors:", err)
303     print("Warnings:", warn)
304     print("Statistics:", stats)
305     print("Relative Change:", f"{rel_change:.2E}")
306     print("#####")
307     print("w:", eng(w))
308     print("l:", eng(l))
309     print("r:", eng(r))
310     print("Capacitance:", eng(capacitance))
311     print("#####")

```

## 4.2 Elmer FEM Solver Input File (SIF)

This Elmer FEM solver input file (SIF) is created automatically and listed here just for review purpose:

Listing 2: Elmer FEM solver input file (SIF)

```
1 Header
2   CHECK KEYWORDS "Warn"
3   Mesh DB "." "."
4 End
5
6 Simulation
7   Max Output Level = 5
8   Coordinate System = Cartesian
9   Coordinate Mapping(3) = 1 2 3
10  Simulation Type = Steady state
11  Steady State Max Iterations = 1
12  Output Intervals = 1
13  Timestepping Method = BDF
14  BDF Order = 1
15  Solver Input File = case.sif
16  Post File = case.vtu
17  Output File = case.result
18 End
19
20 Constants
21   Stefan Boltzmann = 5.6704e-08
22   Permittivity of Vacuum = 8.8542e-12
23   Gravity(4) = 0 -1 0 9.82
24   Boltzmann Constant = 1.3807e-23
25   Unit Charge = 1.602e-19
26 End
27
28 ! main
29 Equation 1
30   Active Solvers(1) = 1    ! Electrostatics,
31 End
32
33
34 ! Electrostatics
35 Solver 1
36   Equation = Electrostatics
37   Calculate Electric Field = True
38   Procedure = "StatElecSolve" "StatElecSolver"
39   Variable = Potential
40   Calculate Electric Energy = True
41   Exec Solver = Always
42   Stabilize = True
43   Bubbles = False
44   Lumped Mass Matrix = False
45   Optimize Bandwidth = True
46   Steady State Convergence Tolerance = 1e-05
47   Nonlinear System Convergence Tolerance = 1e-07
48   Nonlinear System Max Iterations = 20
49   Nonlinear System Newton After Iterations = 3
50   Nonlinear System Newton After Tolerance = 0.001
51   Nonlinear System Relaxation Factor = 1
52   Linear System Solver = Iterative
53   Linear System Iterative Method = BiCGStab
54   Linear System Max Iterations = 500
55   Linear System Convergence Tolerance = 1e-10
56   BiCGStabl polynomial degree = 2
57   Linear System Preconditioning = ILU0
58   Linear System ILUT Tolerance = 0.001
59   Linear System Abort Not Converged = False
60   Linear System Residual Output = 10
61   Linear System Precondition Recompute = 1
62   Potential Difference = 1.0
63 End
64
65
```

```

66 ! air
67 Material 1
68   Density = 1.1885
69   Electric Conductivity = 0.0
70   Heat Capacity = 1006.4
71   Heat Conductivity = 0.025873
72   Relative Permeability = 1
73   Relative Permittivity = 1
74 End
75
76 ! ro4003c
77 Material 2
78   Density = 1790
79   Relative Permeability = 1
80   Relative Permittivity = 3.55
81 End
82
83
84 ! substrate
85 Body 1
86   Target Bodies(1) = 1
87   Equation = 1 ! main
88   Material = 2 ! ro4003c
89 End
90
91 ! airbox
92 Body 2
93   Target Bodies(1) = 2
94   Equation = 1 ! main
95   Material = 1 ! air
96 End
97
98
99 ! top metal
100 Boundary Condition 1
101   Target Boundaries(1) = 3
102   Potential = 1.0
103 End
104
105 ! bottom metal
106 Boundary Condition 2
107   Target Boundaries(1) = 4
108   Potential = 0.0
109 End
110
111 ! FarField
112 Boundary Condition 3
113   Target Boundaries(1) = 5
114   Electric Infinity BC = True
115 End

```

## 5 Conclusions

This example may help the reader to set up a Elmer FEM computation of a 3D electrostatic capacitance problem using pyelmer. The Elmer FEM computation result agrees very well with published data in the literature. However, the calculated result depend on the mesh structure and mesh element size. Mesh generation is by far not perfect and not solved yet in this example. Gmsh API functions can be used to ensure small mesh size at regions of high field gradients (edges, corners) and to optimize the mesh for lower FEM computation time. The authors welcome any comments for further improvements.

## References

- [1] “Elmer FEM open source multiphysical simulation software.” (2021), [Online]. Available: <http://www.elmerfem.org/blog/>.
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