

# rnn\_c

May 1, 2019

Reference: Tensorflow tutorials([https://www.tensorflow.org/tutorials/sequences/text\\_generation](https://www.tensorflow.org/tutorials/sequences/text_generation))

```
[1]: import tensorflow as tf
tf.enable_eager_execution()

import numpy as np
import os
import time
import matplotlib.pyplot as plt

[2]: # Read, then decode for py2 compat.
text = open('huge_c.txt', 'rb').read().decode(encoding='utf-8')
# length of text is the number of characters in it
print ('Length of text: {} characters'.format(len(text)))
```

Length of text: 26346 characters

```
[3]: # The unique characters in the file
vocab = sorted(set(text))
print ('{} unique characters'.format(len(vocab)))
```

85 unique characters

```
[4]: # Creating a mapping from unique characters to indices
char2idx = {u:i for i, u in enumerate(vocab)}
idx2char = np.array(vocab)

text_as_int = np.array([char2idx[c] for c in text])

[5]: # The maximum length sentence we want for a single input in characters
seq_length = 100
examples_per_epoch = len(text)//seq_length

# Create training examples / targets
char_dataset = tf.data.Dataset.from_tensor_slices(text_as_int)
sequences = char_dataset.batch(seq_length+1, drop_remainder = True)

for item in sequences.take(5):
```

```
print(repr(''.join(idx2char[item.numpy()])))
```

```
'// SPDX-License-Identifier: GPL-2.0\n#include "audit.h"\n#include  
<linux/fsnotify_backend.h>\n#include <  
'linux/namei.h>\n#include <linux/mount.h>\n#include <linux/kthread.h>\n#include  
<linux/refcount.h>\n#include  
'de <linux/slab.h>\n\nstruct audit_tree;\nstruct audit_chunk;\n\nstruct  
audit_tree {\n\trefcount_t count;\n\tin  
't goner;\n\tstruct audit_chunk *root;\n\tstruct list_head chunks;\n\tstruct  
list_head rules;\n\tstruct list_h  
'head list;\n\tstruct list_head same_root;\n\tstruct rcu_head head;\n\tchar  
pathname[];\n};\n\nstruct audit_chun'
```

```
[6]: def split_input_target(chunk):  
    input_text = chunk[:-1]  
    target_text = chunk[1:]  
    return input_text, target_text
```

```
dataset = sequences.map(split_input_target)
```

```
[7]: for input_example, target_example in dataset.take(1):  
    print('Input data: ', repr(''.join(idx2char[input_example.numpy()])))  
    print('Target data:', repr(''.join(idx2char[target_example.numpy()])))
```

```
Input data: '// SPDX-License-Identifier: GPL-2.0\n#include "audit.h"\n#include  
<linux/fsnotify_backend.h>\n#include '  
Target data: '/ SPDX-License-Identifier: GPL-2.0\n#include "audit.h"\n#include  
<linux/fsnotify_backend.h>\n#include <'
```

```
[8]: for i, (input_idx, target_idx) in enumerate(zip(input_example[:5],  
→target_example[:5])):  
    print("Step {:4d}".format(i))  
    print("  input: {} ({:s})".format(input_idx, repr(idx2char[input_idx])))  
    print(" expected output: {} ({:s})".format(target_idx,  
→repr(idx2char[target_idx])))
```

```
Step    0  
  input: 16 ('/')  
 expected output: 16 ('/')  
Step    1  
  input: 16 ('/')  
 expected output: 2 (' '  
Step    2  
  input: 2 (' '  
 expected output: 44 ('S')  
Step    3  
  input: 44 ('S')
```

```
    expected output: 42 ('P')
Step      4
    input: 42 ('P')
    expected output: 31 ('D')
```

```
[9]: # Batch size
BATCH_SIZE = 64
steps_per_epoch = examples_per_epoch//BATCH_SIZE

# Buffer size to shuffle the dataset
# (TF data is designed to work with possibly infinite sequences,
# so it doesn't attempt to shuffle the entire sequence in memory. Instead,
# it maintains a buffer in which it shuffles elements).
BUFFER_SIZE = 10000

dataset = dataset.shuffle(BUFFER_SIZE).batch(BATCH_SIZE, drop_remainder=True)

dataset
```

```
[9]: <BatchDataset shapes: ((64, 100), (64, 100)), types: (tf.int64, tf.int64)>
```

```
[10]: # Length of the vocabulary in chars
vocab_size = len(vocab)

# The embedding dimension
embedding_dim = 256

# Number of RNN units
rnn_units = 1024
```

```
[11]: model = tf.keras.Sequential()
model.add(tf.keras.layers.Embedding(len(vocab), embedding_dim,
                                     batch_input_shape=[BATCH_SIZE, None]))
model.add(tf.keras.layers.CuDNNGRU(rnn_units,
                                     return_sequences=True,
                                     recurrent_initializer='glorot_uniform',
                                     stateful=True))
model.add(tf.keras.layers.Dense(len(vocab)))

print(model.summary())
```

Layer (type)	Output Shape	Param #
embedding (Embedding)	(64, None, 256)	21760
cu_dnngru (CuDNNGRU)	(64, None, 1024)	3938304
dense (Dense)	(64, None, 85)	87125

```
=====
Total params: 4,047,189
Trainable params: 4,047,189
Non-trainable params: 0
-----
None
```

```
[12]: for input_example_batch, target_example_batch in dataset.take(1):
        example_batch_predictions = model(input_example_batch)
        print(example_batch_predictions.shape, "# (batch_size, sequence_length,
        →vocab_size)")
```

```
(64, 100, 85) # (batch_size, sequence_length, vocab_size)
```

```
[13]: def loss(labels, logits):
        return tf.nn.sparse_softmax_cross_entropy_with_logits(labels=labels,
        →logits=logits)

model.compile(
    optimizer = tf.train.AdamOptimizer(),
    loss = loss)
```

```
[14]: # Directory where the checkpoints will be saved
checkpoint_dir = './training_checkpoints'
# Name of the checkpoint files
checkpoint_prefix = os.path.join(checkpoint_dir, "ckpt_c_{epoch}")

checkpoint_callback=tf.keras.callbacks.ModelCheckpoint(
    filepath=checkpoint_prefix,
    save_weights_only=True)
```

```
[15]: EPOCHS=200

# history = model.fit(dataset.repeat(), epochs=EPOCHS,
→steps_per_epoch=steps_per_epoch, callbacks=[checkpoint_callback])

history = model.fit(dataset.repeat(), epochs=EPOCHS,
→steps_per_epoch=steps_per_epoch, callbacks=[checkpoint_callback])
```

```
Epoch 1/200
4/4 [=====] - 0s 82ms/step - loss: 4.3378
Epoch 2/200
4/4 [=====] - 0s 74ms/step - loss: 4.8581
Epoch 3/200
4/4 [=====] - 0s 77ms/step - loss: 4.1511
Epoch 4/200
4/4 [=====] - 0s 83ms/step - loss: 3.9667
Epoch 5/200
```

4/4 [=====] - 0s 81ms/step - loss: 3.7485  
 Epoch 6/200  
 4/4 [=====] - 0s 79ms/step - loss: 3.4750  
 Epoch 7/200  
 4/4 [=====] - 0s 78ms/step - loss: 3.2431  
 Epoch 8/200  
 4/4 [=====] - 0s 86ms/step - loss: 3.1185  
 Epoch 9/200  
 4/4 [=====] - 0s 79ms/step - loss: 2.9910  
 Epoch 10/200  
 4/4 [=====] - 0s 77ms/step - loss: 2.8767  
 Epoch 11/200  
 4/4 [=====] - 0s 76ms/step - loss: 2.7564  
 Epoch 12/200  
 4/4 [=====] - 0s 76ms/step - loss: 2.6457  
 Epoch 13/200  
 4/4 [=====] - 0s 76ms/step - loss: 2.5471  
 Epoch 14/200  
 4/4 [=====] - 0s 77ms/step - loss: 2.4573  
 Epoch 15/200  
 4/4 [=====] - 0s 82ms/step - loss: 2.3721  
 Epoch 16/200  
 4/4 [=====] - 0s 88ms/step - loss: 2.3039  
 Epoch 17/200  
 4/4 [=====] - 0s 96ms/step - loss: 2.2458  
 Epoch 18/200  
 4/4 [=====] - 0s 80ms/step - loss: 2.1756  
 Epoch 19/200  
 4/4 [=====] - 0s 79ms/step - loss: 2.1192  
 Epoch 20/200  
 4/4 [=====] - 0s 82ms/step - loss: 2.0716  
 Epoch 21/200  
 4/4 [=====] - 0s 76ms/step - loss: 2.0133  
 Epoch 22/200  
 4/4 [=====] - 0s 80ms/step - loss: 1.9690  
 Epoch 23/200  
 4/4 [=====] - 0s 78ms/step - loss: 1.9184  
 Epoch 24/200  
 4/4 [=====] - 0s 75ms/step - loss: 1.8763  
 Epoch 25/200  
 4/4 [=====] - 0s 73ms/step - loss: 1.8223  
 Epoch 26/200  
 4/4 [=====] - 0s 81ms/step - loss: 1.7843  
 Epoch 27/200  
 4/4 [=====] - 0s 81ms/step - loss: 1.7385  
 Epoch 28/200  
 4/4 [=====] - 0s 84ms/step - loss: 1.6874  
 Epoch 29/200

4/4 [=====] - 0s 81ms/step - loss: 1.6541  
Epoch 30/200  
4/4 [=====] - 0s 79ms/step - loss: 1.6110  
Epoch 31/200  
4/4 [=====] - 0s 81ms/step - loss: 1.5687  
Epoch 32/200  
4/4 [=====] - 0s 84ms/step - loss: 1.5273  
Epoch 33/200  
4/4 [=====] - 0s 81ms/step - loss: 1.4916  
Epoch 34/200  
4/4 [=====] - 0s 74ms/step - loss: 1.4454  
Epoch 35/200  
4/4 [=====] - 0s 74ms/step - loss: 1.4110  
Epoch 36/200  
4/4 [=====] - 0s 74ms/step - loss: 1.3637  
Epoch 37/200  
4/4 [=====] - 0s 76ms/step - loss: 1.3343  
Epoch 38/200  
4/4 [=====] - 0s 76ms/step - loss: 1.2990  
Epoch 39/200  
4/4 [=====] - 0s 74ms/step - loss: 1.2538  
Epoch 40/200  
4/4 [=====] - 0s 75ms/step - loss: 1.2152  
Epoch 41/200  
4/4 [=====] - 0s 76ms/step - loss: 1.1831  
Epoch 42/200  
4/4 [=====] - 1s 154ms/step - loss: 1.1496  
Epoch 43/200  
4/4 [=====] - 0s 78ms/step - loss: 1.1099  
Epoch 44/200  
4/4 [=====] - 0s 77ms/step - loss: 1.0789  
Epoch 45/200  
4/4 [=====] - 0s 80ms/step - loss: 1.0504  
Epoch 46/200  
4/4 [=====] - 0s 82ms/step - loss: 1.0235  
Epoch 47/200  
4/4 [=====] - 0s 73ms/step - loss: 0.9998  
Epoch 48/200  
4/4 [=====] - 0s 80ms/step - loss: 0.9671  
Epoch 49/200  
4/4 [=====] - 0s 76ms/step - loss: 0.9359  
Epoch 50/200  
4/4 [=====] - 0s 88ms/step - loss: 0.9012  
Epoch 51/200  
4/4 [=====] - 0s 76ms/step - loss: 0.8713  
Epoch 52/200  
4/4 [=====] - 0s 78ms/step - loss: 0.8433  
Epoch 53/200

4/4 [=====] - 0s 77ms/step - loss: 0.8219  
Epoch 54/200  
4/4 [=====] - 0s 84ms/step - loss: 0.7875  
Epoch 55/200  
4/4 [=====] - 0s 74ms/step - loss: 0.7647  
Epoch 56/200  
4/4 [=====] - 0s 74ms/step - loss: 0.7443  
Epoch 57/200  
4/4 [=====] - 0s 89ms/step - loss: 0.7218  
Epoch 58/200  
4/4 [=====] - 0s 80ms/step - loss: 0.6971  
Epoch 59/200  
4/4 [=====] - 0s 94ms/step - loss: 0.6648  
Epoch 60/200  
4/4 [=====] - 0s 73ms/step - loss: 0.6509  
Epoch 61/200  
4/4 [=====] - 0s 85ms/step - loss: 0.6324  
Epoch 62/200  
4/4 [=====] - 0s 112ms/step - loss: 0.6025  
Epoch 63/200  
4/4 [=====] - 0s 74ms/step - loss: 0.5859  
Epoch 64/200  
4/4 [=====] - 0s 82ms/step - loss: 0.5635  
Epoch 65/200  
4/4 [=====] - 0s 82ms/step - loss: 0.5442  
Epoch 66/200  
4/4 [=====] - 0s 82ms/step - loss: 0.5253  
Epoch 67/200  
4/4 [=====] - 0s 96ms/step - loss: 0.5089  
Epoch 68/200  
4/4 [=====] - 0s 76ms/step - loss: 0.4913  
Epoch 69/200  
4/4 [=====] - 0s 73ms/step - loss: 0.4726  
Epoch 70/200  
4/4 [=====] - 0s 79ms/step - loss: 0.4592  
Epoch 71/200  
4/4 [=====] - 0s 80ms/step - loss: 0.4384  
Epoch 72/200  
4/4 [=====] - 0s 78ms/step - loss: 0.4293  
Epoch 73/200  
4/4 [=====] - 0s 86ms/step - loss: 0.4130  
Epoch 74/200  
4/4 [=====] - 0s 75ms/step - loss: 0.3982  
Epoch 75/200  
4/4 [=====] - 0s 84ms/step - loss: 0.3871  
Epoch 76/200  
4/4 [=====] - 0s 81ms/step - loss: 0.3687  
Epoch 77/200

4/4 [=====] - 0s 77ms/step - loss: 0.3594  
Epoch 78/200  
4/4 [=====] - 0s 118ms/step - loss: 0.3493  
Epoch 79/200  
4/4 [=====] - 0s 92ms/step - loss: 0.3354  
Epoch 80/200  
4/4 [=====] - 0s 86ms/step - loss: 0.3205  
Epoch 81/200  
4/4 [=====] - 0s 114ms/step - loss: 0.3112  
Epoch 82/200  
4/4 [=====] - 0s 79ms/step - loss: 0.3031  
Epoch 83/200  
4/4 [=====] - 0s 97ms/step - loss: 0.2934  
Epoch 84/200  
4/4 [=====] - 0s 77ms/step - loss: 0.2834  
Epoch 85/200  
4/4 [=====] - 0s 74ms/step - loss: 0.2800  
Epoch 86/200  
4/4 [=====] - 0s 84ms/step - loss: 0.2692  
Epoch 87/200  
4/4 [=====] - 0s 78ms/step - loss: 0.2660  
Epoch 88/200  
4/4 [=====] - 0s 99ms/step - loss: 0.2587  
Epoch 89/200  
4/4 [=====] - 0s 77ms/step - loss: 0.2529  
Epoch 90/200  
4/4 [=====] - 0s 75ms/step - loss: 0.2494  
Epoch 91/200  
4/4 [=====] - 0s 79ms/step - loss: 0.2412  
Epoch 92/200  
4/4 [=====] - 0s 76ms/step - loss: 0.2349  
Epoch 93/200  
4/4 [=====] - 0s 77ms/step - loss: 0.2277  
Epoch 94/200  
4/4 [=====] - 0s 115ms/step - loss: 0.2214  
Epoch 95/200  
4/4 [=====] - 0s 76ms/step - loss: 0.2210  
Epoch 96/200  
4/4 [=====] - 0s 104ms/step - loss: 0.2151  
Epoch 97/200  
4/4 [=====] - 0s 71ms/step - loss: 0.2070  
Epoch 98/200  
4/4 [=====] - 0s 78ms/step - loss: 0.2010  
Epoch 99/200  
4/4 [=====] - 0s 95ms/step - loss: 0.2003  
Epoch 100/200  
4/4 [=====] - 0s 74ms/step - loss: 0.1922  
Epoch 101/200



4/4 [=====] - 0s 83ms/step - loss: 0.1923  
Epoch 102/200  
4/4 [=====] - 0s 81ms/step - loss: 0.1872  
Epoch 103/200  
4/4 [=====] - 0s 75ms/step - loss: 0.1887  
Epoch 104/200  
4/4 [=====] - 0s 87ms/step - loss: 0.1793  
Epoch 105/200  
4/4 [=====] - 0s 76ms/step - loss: 0.1827  
Epoch 106/200  
4/4 [=====] - 0s 75ms/step - loss: 0.1805  
Epoch 107/200  
4/4 [=====] - 0s 74ms/step - loss: 0.1704  
Epoch 108/200  
4/4 [=====] - 0s 75ms/step - loss: 0.1700  
Epoch 109/200  
4/4 [=====] - 0s 75ms/step - loss: 0.1684  
Epoch 110/200  
4/4 [=====] - 1s 129ms/step - loss: 0.1676  
Epoch 111/200  
4/4 [=====] - 0s 72ms/step - loss: 0.1638  
Epoch 112/200  
4/4 [=====] - 0s 74ms/step - loss: 0.1627  
Epoch 113/200  
4/4 [=====] - 0s 93ms/step - loss: 0.1583  
Epoch 114/200  
4/4 [=====] - 0s 82ms/step - loss: 0.1559  
Epoch 115/200  
4/4 [=====] - 0s 75ms/step - loss: 0.1561  
Epoch 116/200  
4/4 [=====] - 0s 75ms/step - loss: 0.1520  
Epoch 117/200  
4/4 [=====] - 0s 94ms/step - loss: 0.1448  
Epoch 118/200  
4/4 [=====] - 0s 75ms/step - loss: 0.1478  
Epoch 119/200  
4/4 [=====] - 0s 82ms/step - loss: 0.1476  
Epoch 120/200  
4/4 [=====] - 0s 87ms/step - loss: 0.1414  
Epoch 121/200  
4/4 [=====] - 0s 84ms/step - loss: 0.1400  
Epoch 122/200  
4/4 [=====] - 0s 87ms/step - loss: 0.1429  
Epoch 123/200  
4/4 [=====] - 0s 85ms/step - loss: 0.1394  
Epoch 124/200  
4/4 [=====] - 0s 68ms/step - loss: 0.1408  
Epoch 125/200

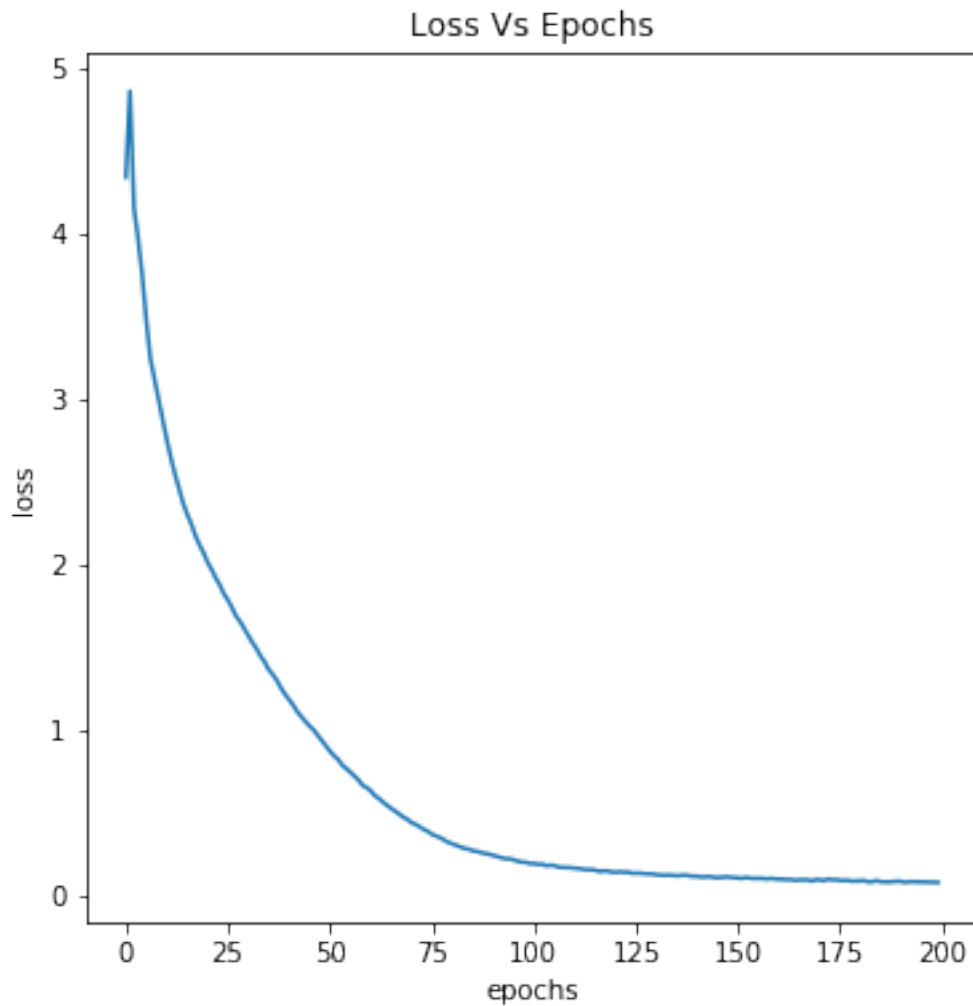
4/4 [=====] - 0s 100ms/step - loss: 0.1347  
 Epoch 126/200  
 4/4 [=====] - 0s 84ms/step - loss: 0.1337  
 Epoch 127/200  
 4/4 [=====] - 0s 73ms/step - loss: 0.1356  
 Epoch 128/200  
 4/4 [=====] - 1s 133ms/step - loss: 0.1310  
 Epoch 129/200  
 4/4 [=====] - 0s 82ms/step - loss: 0.1308  
 Epoch 130/200  
 4/4 [=====] - 0s 76ms/step - loss: 0.1294  
 Epoch 131/200  
 4/4 [=====] - 0s 82ms/step - loss: 0.1249  
 Epoch 132/200  
 4/4 [=====] - 0s 74ms/step - loss: 0.1231  
 Epoch 133/200  
 4/4 [=====] - 0s 93ms/step - loss: 0.1212  
 Epoch 134/200  
 4/4 [=====] - 0s 71ms/step - loss: 0.1234  
 Epoch 135/200  
 4/4 [=====] - 0s 74ms/step - loss: 0.1214  
 Epoch 136/200  
 4/4 [=====] - 1s 141ms/step - loss: 0.1188  
 Epoch 137/200  
 4/4 [=====] - 0s 82ms/step - loss: 0.1201  
 Epoch 138/200  
 4/4 [=====] - 0s 73ms/step - loss: 0.1228  
 Epoch 139/200  
 4/4 [=====] - 0s 86ms/step - loss: 0.1193  
 Epoch 140/200  
 4/4 [=====] - 0s 77ms/step - loss: 0.1152  
 Epoch 141/200  
 4/4 [=====] - 0s 81ms/step - loss: 0.1159  
 Epoch 142/200  
 4/4 [=====] - 0s 73ms/step - loss: 0.1115  
 Epoch 143/200  
 4/4 [=====] - 0s 83ms/step - loss: 0.1116  
 Epoch 144/200  
 4/4 [=====] - 0s 104ms/step - loss: 0.1145  
 Epoch 145/200  
 4/4 [=====] - 0s 84ms/step - loss: 0.1091  
 Epoch 146/200  
 4/4 [=====] - 0s 116ms/step - loss: 0.1077  
 Epoch 147/200  
 4/4 [=====] - 0s 76ms/step - loss: 0.1086  
 Epoch 148/200  
 4/4 [=====] - 0s 73ms/step - loss: 0.1121  
 Epoch 149/200

4/4 [=====] - 0s 85ms/step - loss: 0.1100  
Epoch 150/200  
4/4 [=====] - 0s 75ms/step - loss: 0.1073  
Epoch 151/200  
4/4 [=====] - 0s 74ms/step - loss: 0.1073  
Epoch 152/200  
4/4 [=====] - 0s 79ms/step - loss: 0.1032  
Epoch 153/200  
4/4 [=====] - 0s 86ms/step - loss: 0.1084  
Epoch 154/200  
4/4 [=====] - 0s 86ms/step - loss: 0.1042  
Epoch 155/200  
4/4 [=====] - 0s 87ms/step - loss: 0.1023  
Epoch 156/200  
4/4 [=====] - 0s 87ms/step - loss: 0.1033  
Epoch 157/200  
4/4 [=====] - 0s 86ms/step - loss: 0.1025  
Epoch 158/200  
4/4 [=====] - 0s 83ms/step - loss: 0.0998  
Epoch 159/200  
4/4 [=====] - 0s 83ms/step - loss: 0.1020  
Epoch 160/200  
4/4 [=====] - 0s 101ms/step - loss: 0.0996  
Epoch 161/200  
4/4 [=====] - 0s 75ms/step - loss: 0.0977  
Epoch 162/200  
4/4 [=====] - 0s 101ms/step - loss: 0.0980  
Epoch 163/200  
4/4 [=====] - 0s 74ms/step - loss: 0.0944  
Epoch 164/200  
4/4 [=====] - 0s 74ms/step - loss: 0.0959  
Epoch 165/200  
4/4 [=====] - 0s 94ms/step - loss: 0.0912  
Epoch 166/200  
4/4 [=====] - 0s 84ms/step - loss: 0.0938  
Epoch 167/200  
4/4 [=====] - 0s 83ms/step - loss: 0.0942  
Epoch 168/200  
4/4 [=====] - 0s 77ms/step - loss: 0.0944  
Epoch 169/200  
4/4 [=====] - 1s 148ms/step - loss: 0.0870  
Epoch 170/200  
4/4 [=====] - 0s 116ms/step - loss: 0.0945  
Epoch 171/200  
4/4 [=====] - 0s 70ms/step - loss: 0.0950  
Epoch 172/200  
4/4 [=====] - 0s 75ms/step - loss: 0.0887  
Epoch 173/200

4/4 [=====] - 0s 80ms/step - loss: 0.0985  
Epoch 174/200  
4/4 [=====] - 0s 70ms/step - loss: 0.0939  
Epoch 175/200  
4/4 [=====] - 0s 73ms/step - loss: 0.0947  
Epoch 176/200  
4/4 [=====] - 0s 75ms/step - loss: 0.0907  
Epoch 177/200  
4/4 [=====] - 0s 76ms/step - loss: 0.0899  
Epoch 178/200  
4/4 [=====] - 0s 74ms/step - loss: 0.0904  
Epoch 179/200  
4/4 [=====] - 0s 74ms/step - loss: 0.0863  
Epoch 180/200  
4/4 [=====] - 0s 73ms/step - loss: 0.0871  
Epoch 181/200  
4/4 [=====] - 0s 74ms/step - loss: 0.0892  
Epoch 182/200  
4/4 [=====] - 1s 131ms/step - loss: 0.0893  
Epoch 183/200  
4/4 [=====] - 0s 73ms/step - loss: 0.0816  
Epoch 184/200  
4/4 [=====] - 0s 82ms/step - loss: 0.0840  
Epoch 185/200  
4/4 [=====] - 0s 78ms/step - loss: 0.0895  
Epoch 186/200  
4/4 [=====] - 0s 77ms/step - loss: 0.0825  
Epoch 187/200  
4/4 [=====] - 0s 76ms/step - loss: 0.0812  
Epoch 188/200  
4/4 [=====] - 0s 81ms/step - loss: 0.0820  
Epoch 189/200  
4/4 [=====] - 0s 81ms/step - loss: 0.0829  
Epoch 190/200  
4/4 [=====] - 0s 83ms/step - loss: 0.0865  
Epoch 191/200  
4/4 [=====] - 0s 80ms/step - loss: 0.0846  
Epoch 192/200  
4/4 [=====] - 0s 100ms/step - loss: 0.0784  
Epoch 193/200  
4/4 [=====] - 0s 80ms/step - loss: 0.0834  
Epoch 194/200  
4/4 [=====] - 0s 124ms/step - loss: 0.0825  
Epoch 195/200  
4/4 [=====] - 0s 81ms/step - loss: 0.0820  
Epoch 196/200  
4/4 [=====] - 0s 79ms/step - loss: 0.0820  
Epoch 197/200

```
4/4 [=====] - 0s 78ms/step - loss: 0.0789
Epoch 198/200
4/4 [=====] - 0s 78ms/step - loss: 0.0789
Epoch 199/200
4/4 [=====] - 0s 82ms/step - loss: 0.0798
Epoch 200/200
4/4 [=====] - 0s 84ms/step - loss: 0.0787
```

```
[16]: plt.figure(figsize = (6,6))
      plt.plot(history.history['loss'])
      plt.title('Loss Vs Epochs')
      plt.xlabel('epochs')
      plt.ylabel('loss')
      plt.show()
```



```
[20]: checkpoint_dir = './training_checkpoints/ckpt_c_200'
# tf.train.latest_checkpoint(checkpoint_dir)

model = tf.keras.Sequential()
model.add(tf.keras.layers.Embedding(len(vocab), embedding_dim,
                                     batch_input_shape=[1, None]))
model.add(tf.keras.layers.CuDNNGRU(rnn_units,
                                     return_sequences=True,
                                     recurrent_initializer='glorot_uniform',
                                     stateful=True))
model.add(tf.keras.layers.Dense(len(vocab)))

model.load_weights(checkpoint_dir)

model.build(tf.TensorShape([1, None]))

print(model.summary())
```

```
-----
Layer (type)                 Output Shape              Param #
=====
embedding_2 (Embedding)      (1, None, 256)           21760
-----
cu_dnngru_2 (CuDNNGRU)       (1, None, 1024)          3938304
-----
dense_2 (Dense)              (1, None, 85)            87125
=====
Total params: 4,047,189
Trainable params: 4,047,189
Non-trainable params: 0
-----
None
```

```
[21]: def generate_text(model, start_string):
# Evaluation step (generating text using the learned model)

# Number of characters to generate
num_generate = 1000

# Converting our start string to numbers (vectorizing)
input_eval = [char2idx[s] for s in start_string]
input_eval = tf.expand_dims(input_eval, 0)

# Empty string to store our results
text_generated = []

# Low temperatures results in more predictable text.
```

```

# Higher temperatures results in more surprising text.
# Experiment to find the best setting.
temperature = 1.0

# Here batch size == 1
model.reset_states()
for i in range(num_generate):
    predictions = model(input_eval)
    # remove the batch dimension
    predictions = tf.squeeze(predictions, 0)

    # using a multinomial distribution to predict the word returned by the
    →model
    predictions = predictions / temperature
    predicted_id = tf.multinomial(predictions, num_samples=1)[-1,0].numpy()

    # We pass the predicted word as the next input to the model
    # along with the previous hidden state
    input_eval = tf.expand_dims([predicted_id], 0)

    text_generated.append(idx2char[predicted_id])

return (start_string + ''.join(text_generated))

```

```

[22]: print(generate_text(model, start_string=u"struct"))

```

```

struct audit_tree *tree)
{
    put_tree *tree)
{
    return tree->pathname, 0, &path);
    if (IS_ERR(mark))
        return;
    out_mutex:
    mutex_unlock(&audit_tree_group->mark_mutex);
    return -ENOMEM;
}

mark = ale;
    fsnotify_free_mark(mark);
    fsnotify_put_mark(mark);
    kfree(chunk);
    return 0;
}
replace_mark_chunk(old->mark, new);
/*
    /      struct audit_chunk *chunk)
{

```

```

struct audit_chunk *old;

assert_spin_locked->chunks, list) {
    list_move(&owner->list, &prune_list);
    need_prune = 1;
} else {
    struct path path1, path2;
struct vfsmount *tagged;
int err;

err = kern_path(new, 0, &path2);
    if (!err) {
        good_one = canlic inline struct audit_tree_mark
*audit_mark(struct fsnotify_mark *mark,
                err)
        goto skip_it;

        root_mnt = collect_mounts(&path);
        path_put(&path);
        if (IS_ERR(rootagner) /* reorder */
for (p = tree->chunks.next; p != &tree->chunks; p = q) {
            struct node *node = list_entry(prune_list.next,
                struct audit_chunk *chunk =
from_chunk(mark) != chunk)
                goto o

```